

Overidentification in Regular Models

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Overidentification

- Original Question: Is this model overidentified or just identified?
- Broader Question:
 - What do we actually mean by “overidentified”?
 - How do we characterize “overidentification”?

First Definition?

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Comments

- **First definition:** Discussed in context of **potential refutability**.
- But authors warn, **not sufficient for testability** (Romano, 2004).
- **Second definition:** Related to **estimation and Hausman test**.
- But “**overidentifying**” stronger than “**observationally restrictive**”.

Is “overidentification” a useful concept?

Yes

- Word “overidentification” often associated with **testability** of the model.
Examples: Chesher (2003), Matzkin (2003), Florens et. al. (2007).
- Word “overidentification” also associated with **efficient estimation**.
Plug in Estimators: Newey (1994), Powell (1994).
Two Stage: Newey & Powell (1999), Akerberg et. al. (2014).

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But

- What do we do in nonparametric IV model?
 - ⇒ Need precise definition of “overidentification” for general models.
 - ⇒ Should be intrinsically linked to **testing and efficiency**.

Overidentification in GMM

Let $\Theta \subseteq \mathbf{R}^{d_\beta}$, $X_i \in \mathbf{R}^{d_x}$, $\rho : \mathbf{R}^{d_x} \times \mathbf{R}^{d_\beta} \rightarrow \mathbf{R}^{d_\rho}$ with $d_\beta \leq d_\rho$ and suppose

$$\int \rho(X_i, \beta(P)) dP = 0 .$$

Overidentification

- When is an overidentification test available? When $d_\rho > d_\beta$.
- When are efficiency considerations relevant? When $d_\rho > d_\beta$.
- Overidentification $\iff d_\rho > d_\beta$.

Counting

- Counting intuition a widely used notion of overidentification.
- Stronger than “observationally restrictive”.
- Not helpful in nonparametric instrumental variables.

Aim of Paper

The Literature

- The term overidentification is used in different ways in the literature.
- What is the precise definition that captures these ideas?

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Our Answer

- Introduce a simple condition we call **local overidentification**.
- Show it is **equivalent** to existence of more **efficient estimators**.
- Show it is **equivalent** to **local testability** of the model.

Implications

- Establish intrinsic **link between efficiency and testability**.
- Apply to conditional moment restrictions models.
- Apply to two stage and plug-in estimators.

1 Local Overidentification

2 Specification Testing

3 Estimation

4 Conditional Moment Models

Setup

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Definition: A model \mathbf{P} is a subset of the set of distributions on \mathbf{R}^{d_x} .

Definition: A “path” $t \mapsto P_{t,g}$ with $P_{t,g}$ a probability measure on \mathbf{R}^{d_x} and

$$\lim_{t \rightarrow 0} \int \left[\frac{1}{t} (dP_{t,g}^{1/2} - dP^{1/2}) - \frac{1}{2} g dP^{1/2} \right]^2 = 0.$$

The function $g : \mathbf{R}^{d_x} \rightarrow \mathbf{R}$ is referred to as the “score” of the path $t \mapsto P_{t,g}$.

Comments

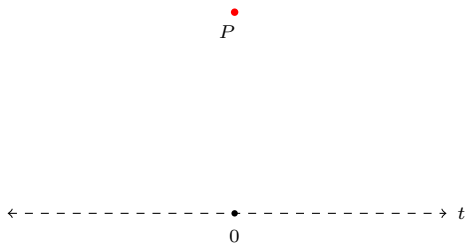
- $t \mapsto P_{t,g}$ is a smooth correctly specified likelihood ($P_{0,g} = P$).
- As usual, score g has mean zero and finite second moment.
- Only feature will matter to us is the score g .

Space of Distributions

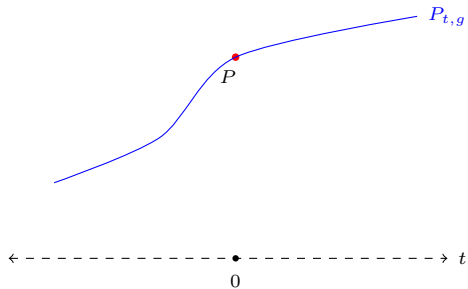


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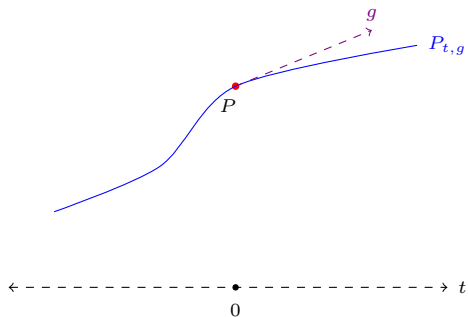
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Tangent Space

$$L_0^2 \equiv \{g : \int g dP = 0 \text{ and } \int g^2 dP < \infty\}$$

Possible to show for any $g \in L_0^2$ we can find a path $t \mapsto P_{t,g}$ with score g .

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- The tangent space is the set of scores that “agree” with the model \mathbf{P}

$$\bar{T}(P) \equiv \text{cl}\{g \in L_0^2 : g \text{ is score of some } t \mapsto P_{t,g} \in \mathbf{P}\}$$

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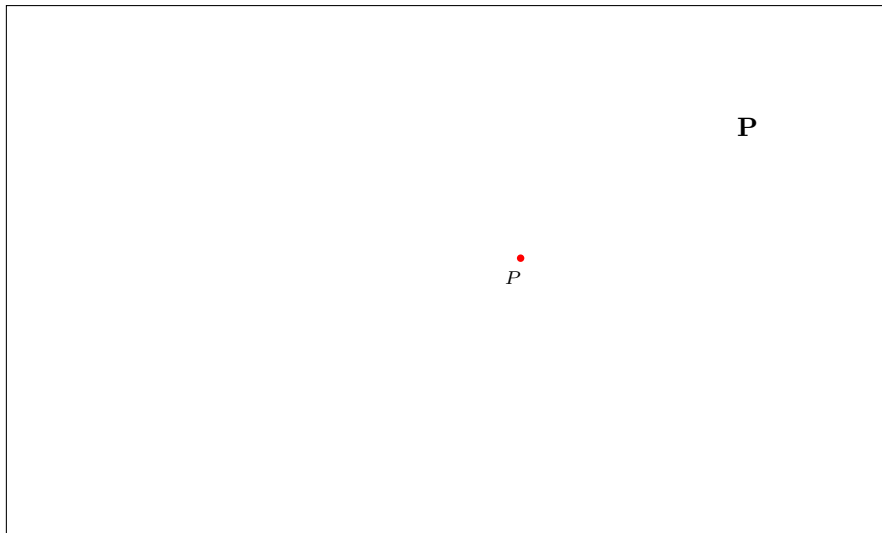
$$\bar{T}(P) \equiv \text{cl}\{g \in L_0^2 : g \text{ is score of some } t \mapsto P_{t,g} \in \mathbf{P}\}$$

- The orthocomplement of $\bar{T}(P)$ are scores that “disagree” with \mathbf{P}

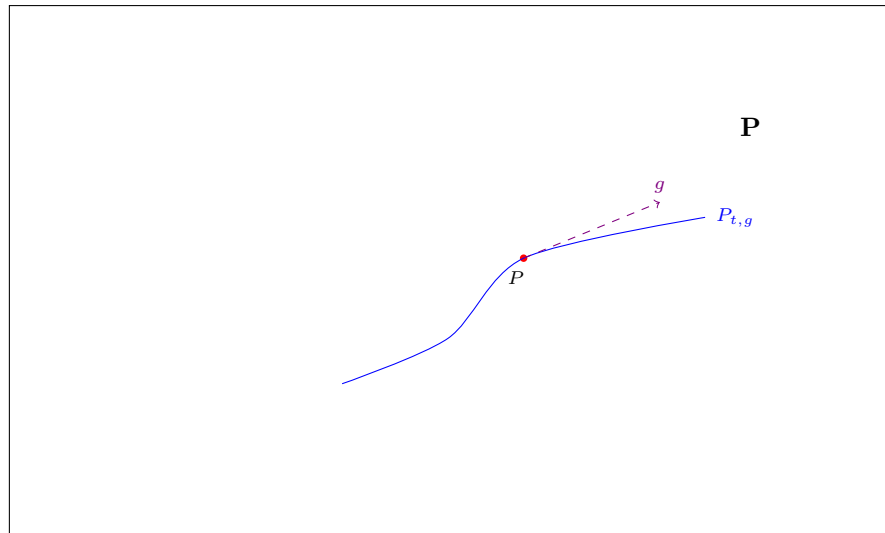
$$\bar{T}(P)^\perp \equiv \{g \in L_0^2 : \int g f dP = 0 \text{ for all } f \in \bar{T}(P)\}$$

Note: $\bar{T}(P)$ and $\bar{T}(P)^\perp$ decompose the set of all possible scores.

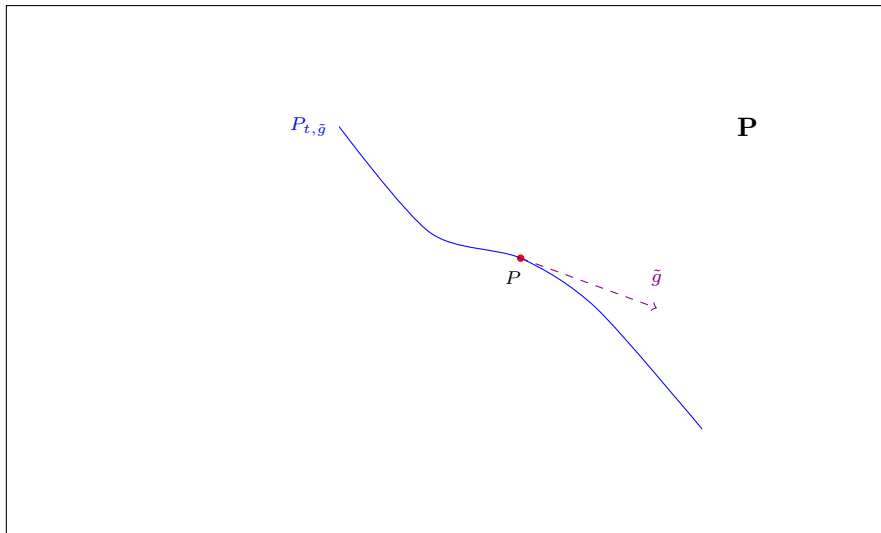
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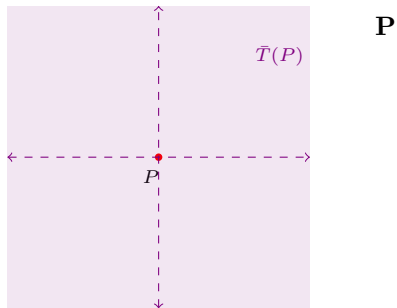
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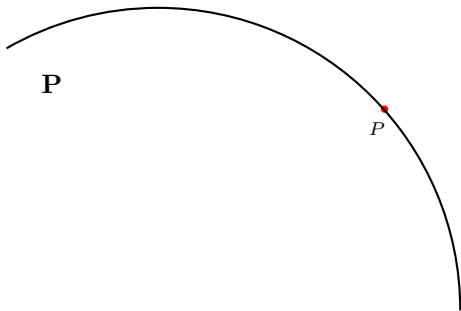


Informative P

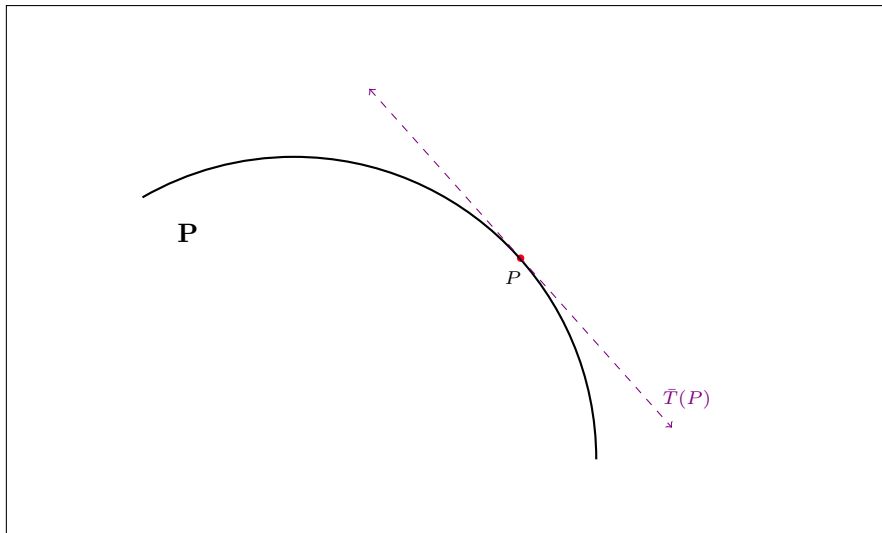


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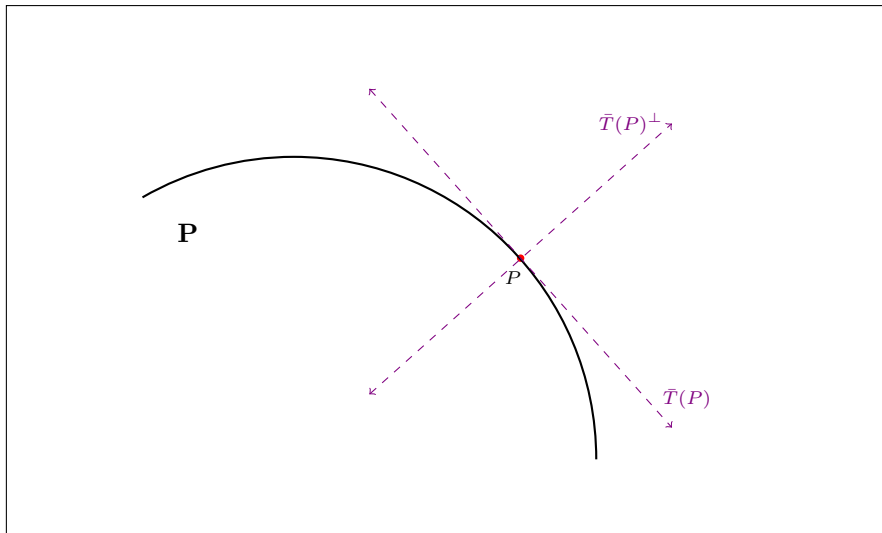
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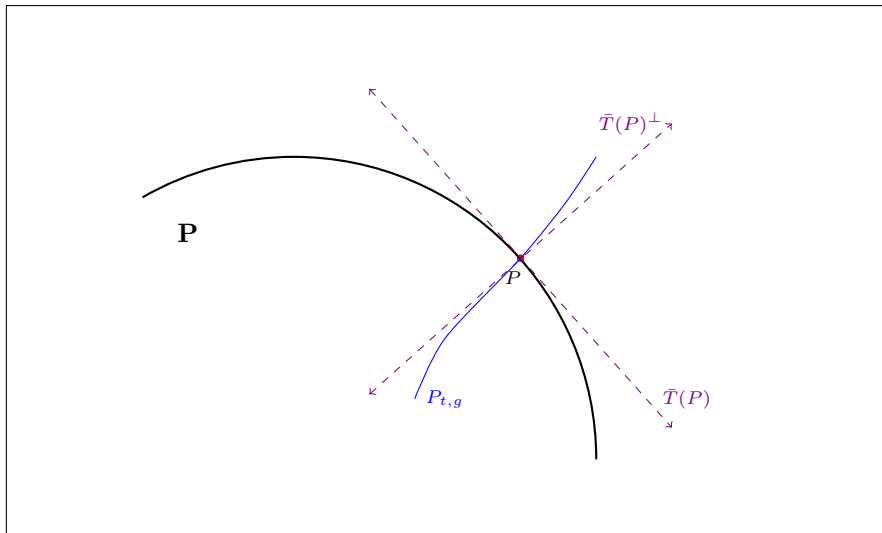
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Local Overidentification

Assumption (R)

- $\{X_i\}_{i=1}^n$ is i.i.d. with $X_i \sim P_{1/\sqrt{n},g}$ for some path $P_{t,g}$ with $P_{0,g} = P \in \mathbf{P}$.
- $\bar{T}(P)$ is linear – i.e. if $g, f \in \bar{T}(P)$, $a, b \in \mathbf{R}$, then $ag + bf \in \bar{T}(P)$.

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Main Definition

- If $\bar{T}(P) = L_0^2$ then we say P is locally just identified by \mathbf{P} .
- If $\bar{T}(P) \subsetneq L_0^2$ then we say P is locally overidentified by \mathbf{P} .

Intuition

- P is just identified $\Leftrightarrow \mathbf{P}$ locally consistent with any parametric model.
- P is overidentified $\Leftrightarrow \mathbf{P}$ restricts possible parametric specifications.

Note: Reduces to traditional definition in GMM context.

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Setup

$$H_0 : P \in \mathbf{P}$$

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We consider tests $\phi_n : \{X_i\}_{i=1}^n \rightarrow [0, 1]$ with well defined limiting local power

$$\lim_{n \rightarrow \infty} \int \phi_n dP_{1/\sqrt{n},g}^n \equiv \pi(g)$$

for $X_i \sim P_{1/\sqrt{n},g}$ and with $P_{1/\sqrt{n},g}^n \equiv \bigotimes_{i=1}^n P_{1/\sqrt{n},g}$ the product measure.

Comments

- Note limiting power depends only on g – this is not an assumption.
- Mild conditions guarantee π exists when $\phi_n = 1\{T_n > c_{1-\alpha}\}$.

(Re)interpreting Test

Local size control demands that for any submodel $t \mapsto P_{t,g} \in \mathbf{P}$ we have

$$\pi(g) = \lim_{n \rightarrow \infty} \int \phi_n dP_{1/\sqrt{n},g}^n \leq \alpha$$

Equivalently, $\pi(g) \leq \alpha$ for any $g \in \bar{T}(P)$ – i.e. g “looks like” from submodel.

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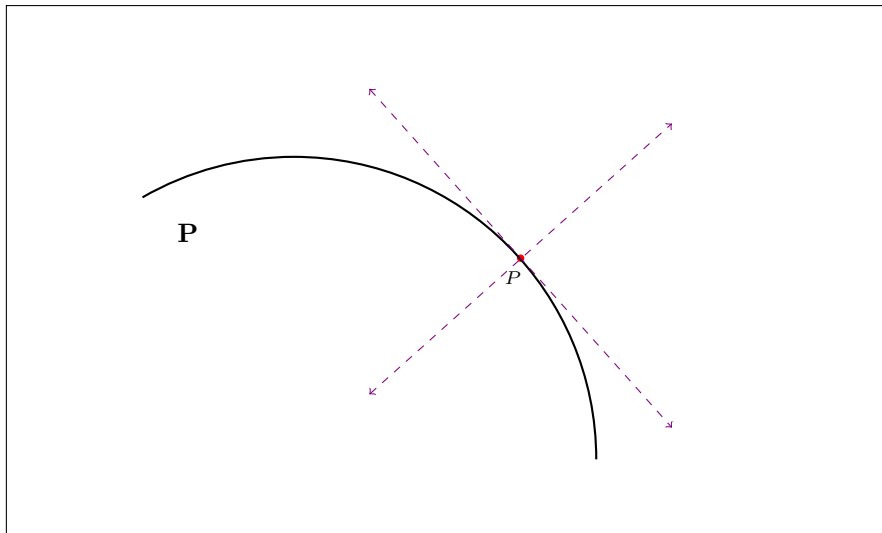
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Notation

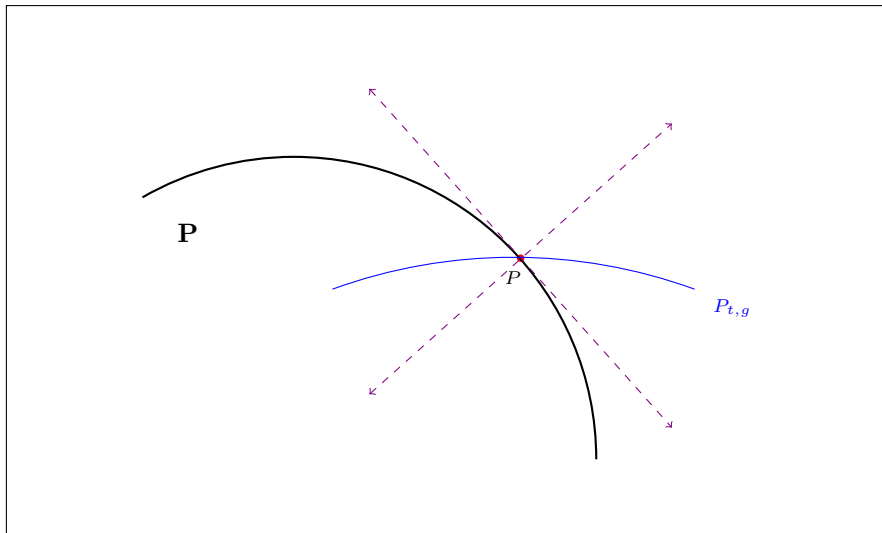
- Let $\Pi_T(g)$ denote projection of g into $\bar{T}(P)$ (in L_0^2).
- Let $\Pi_{T^\perp}(g)$ denote projection of g into $\bar{T}(P)^\perp$ (in L_0^2).

Note: For any $g \in L_0^2$ we have $g = \Pi_T(g) + \Pi_{T^\perp}(g)$.

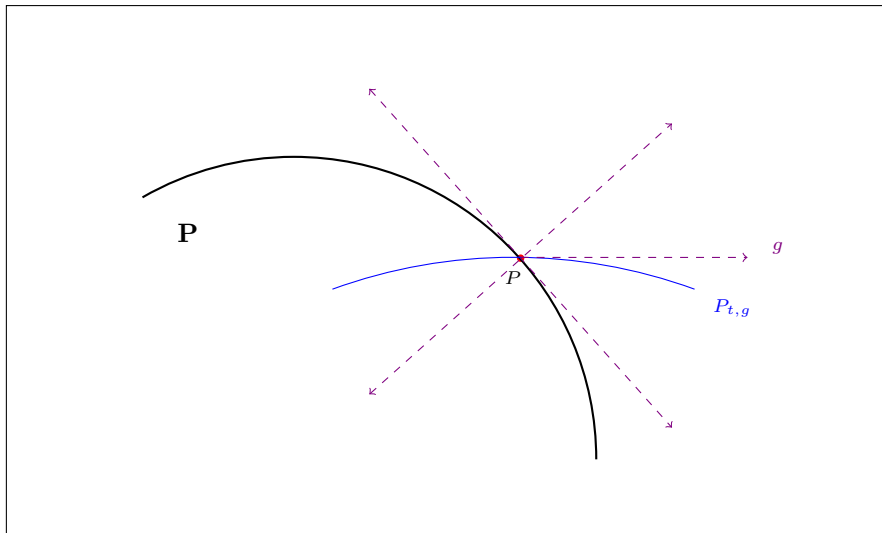
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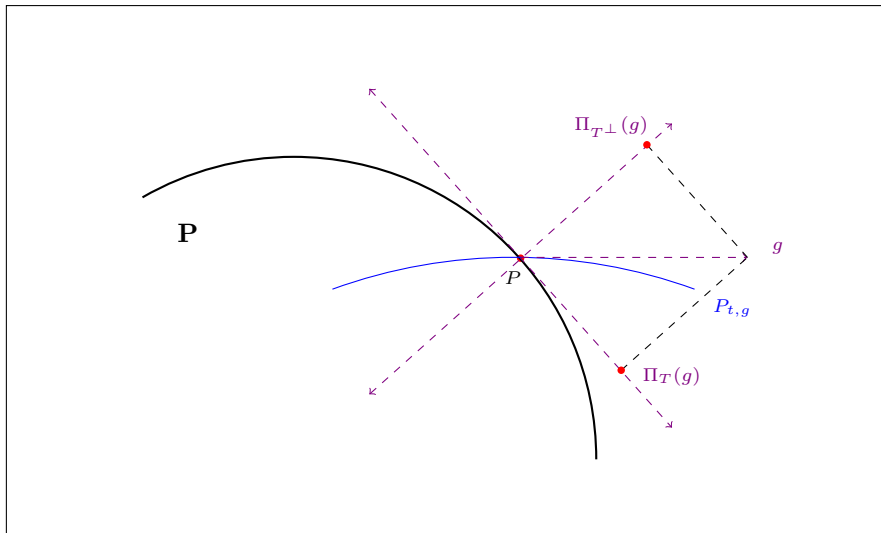
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Formally

- Let $\{\psi_k^T\}_{k=1}^{d_T}$ be orthonormal basis for $\bar{T}(P)$.
- Let $\{\psi_k^\perp\}_{k=1}^{d_{T^\perp}}$ be orthonormal basis for $\bar{T}(P)^\perp$.
- Let Q_g be distribution of $(Y, Z) \equiv (\{Y_k\}_{k=1}^{d_T}, \{Z_k\}_{k=1}^{d_{T^\perp}})$ on $\mathbf{R}^{d_T} \times \mathbf{R}^{d_{T^\perp}}$

$$Y_k \sim N\left(\int g\psi_k^T dP, 1\right) \text{ for } 1 \leq k \leq d_T$$

$$Z_k \sim N\left(\int g\psi_k^\perp dP, 1\right) \text{ for } 1 \leq k \leq d_{T^\perp}$$

Intuition: (Y, Z) is a “noisy” signal of the unknown score g .

(Re)interpreting Test

Theorem Let Assumption R hold, and ϕ_n satisfy for any $t \mapsto P_{t,g} \in \mathbf{P}$

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based on a single observation (Y, Z) such that for any path $t \mapsto P_{t,g}$

$$\pi(g) \equiv \lim_{n \rightarrow \infty} \int \phi_n dP_{1/\sqrt{n},g}^n = \int \phi dQ_g$$

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Comments

- Specification tests examine if g agrees with \mathbf{P} based on signal (Y, Z) .
- J -test corresponds to a Wald test on “signals” Z from $\bar{T}(P)^\perp$.

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Assumption (B)

- There is a known subset $\mathcal{F} = \{f_k\}_{k=1}^{d_F} \subseteq \bar{T}(P)^\perp \subseteq L_0^2$.
- The set \mathcal{F} satisfies $\sum_{k=1}^{d_F} f_k^2 dP < \infty$.

Note: Common tests implicitly estimate \mathcal{F}

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$$\mathbb{G}_n \equiv \underbrace{\left(\frac{1}{\sqrt{n}} \sum_{i=1}^n f_1(X_i), \dots, \frac{1}{\sqrt{n}} \sum_{i=1}^n f_{d_F}(X_i) \right)'}_{\approx Z \text{ "signal" from } \bar{T}(P)^\perp}$$

Overidentification and Testing

Theorem (i) If Assumptions R and B hold, then for any path $t \mapsto P_{t,g} \in \mathbf{P}$

$$\lim_{n \rightarrow \infty} P_{1/\sqrt{n},g}^n (\|\mathbb{G}_n\| > c_{1-\alpha}) = \alpha$$

where $c_{1-\alpha}$ is $1 - \alpha$ quantile of $\|\mathbb{G}_0\|$.

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and in addition \mathcal{F} is such that $\text{cl}\{\text{lin}\{\mathcal{F}\}\} = \bar{T}(P)^\perp$, then it also follows that

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In Words: If P is locally overidentified by \mathbf{P} , then \mathbf{P} is locally testable.

$\Rightarrow \mathbf{P}$ is locally testable if and only if P is locally overidentified.

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Preview

Question: What are implications for estimation of local overidentification?

GMM Intuition: Weighting matrix not important under just identification.

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In General

- Regular estimators asymptotically equivalent under just identification.
- Asymptotically distinct estimators exist under over identification.

Comments

- Finite dimensional case follows from role of $\bar{T}(P)$ (Newey, 1990).
- We require generalization to infinite dimensional for Hausman test.
- Will show “abstract” test can implemented through Hausman test.

Multiple Estimators

Assumption (E)

- $\theta : \mathcal{P} \rightarrow \mathcal{B}$ is a known map with \mathcal{B} a Banach space.
- There exists an asymptotically linear regular estimator $\hat{\theta}_n$ of $\theta(P)$.

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Theorem Let Assumptions R and E hold.

- (i) If P is **locally just identified** and $\tilde{\theta}_n$ is regular and asymptotically linear

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- (ii) If P is **locally overidentified**, there is regular asymptotically linear $\tilde{\theta}_n$

$$\sqrt{n}\{\hat{\theta}_n - \tilde{\theta}_n\} \xrightarrow{L} \Delta \neq 0 \quad (\text{in } \mathbf{B})$$

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Implications

- GMM link between efficiency and testing not coincidental.
- Efficiency literature can be exploited to determine when \mathbf{P} is testable.
- \Rightarrow Semiparametric models are locally testable (Ai & Chen, 2003).

1 Local Overidentification

2 Specification Testing

3 Estimation

4 Conditional Moment Models

Setup

Question: So is the nonparametric IV model locally overidentified?

Goal: Use results from efficiency literature to answer (Ai & Chen, 2012).

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For $X = (Y, Z, W)$ with $Y \in \mathbf{R}^{d_y}$, $Z \in \mathbf{R}^{d_z}$, $W \in \mathbf{R}^{d_w}$, and $\rho : \mathbf{R}^{d_y+1} \rightarrow \mathbf{R}$

$$E[\rho(Y, h_P(Z))|W] = 0$$

for some unknown function $h_P : \mathbf{R}^{d_z} \rightarrow \mathbf{R}$ satisfying $\int h_P^2 dP < \infty$.

Examples

- (NPIV) $E[Y - h_P(Z)|W] = 0$ maps to $\rho(Y, h(Z)) = Y - h(Z)$.
- (NPQIV) $P(Y \leq h_P(Z)|W) = \tau$ maps to $\rho(Y, h(Z)) = 1\{Y \leq h(Z)\} - \tau$.

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Think of $m(W, \cdot)$ as map $m : L_Z^2 \rightarrow L_W^2$ and assume differentiability in that

$$\nabla m(W, h_P)[s] \equiv \left. \frac{\partial}{\partial \tau} m(W, h_P + \tau s) \right|_{\tau=0}$$

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Consider derivative as a map $\nabla m(W, h_P) : L_Z^2 \rightarrow L_W^2$ and denote its range

$$\mathcal{R} \equiv \{f \in L_W^2 : f = \nabla m(W, h_P)[s] \text{ for some } s \in L_Z^2\}$$

Setup

NPIV Example

- Here, $m(W, h) = E[Y - h(Z)|W]$.
- Which implies $\nabla m(W, h_P)[s] = -E[s(Z)|W]$, and therefore

$$\mathcal{R} = \{f \in L_W^2 : f(W) = E[s(Z)|W] \text{ for some } s \in L_Z^2\}$$

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- Here, $m(W, h) = P(Y \leq h(Z)|W) - \tau$.
- Which implies $\nabla m(W, h_P)[s] = E[f_{Y|Z,W}(h_P(Z)|Z, W)s(Z)|W]$, and

$$\mathcal{R} = \{f \in L_W^2 : f(W) = E[f_{Y|Z,W}(h_P(Z)|Z, W)s(Z)|W] \text{ for some } s \in L_Z^2\}$$

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Theorem Under regularity conditions, P is locally just identified if and only if

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Map is “onto” ($\bar{\mathcal{R}} = L_W^2$)

Over ID:

Not onto ($d_{\beta} < d_{\rho}$)

Not onto ($\bar{\mathcal{R}} \subsetneq L_W^2$)

Local Overidentification

Alternative Characterization

$$\bar{\mathcal{R}} = L_W^2 \text{ if and only if } \{0\} = \{s \in L_W^2 : \nabla m(W, h_P)^*[s] = 0\}$$

where $\nabla m(W, h_P) : L_W^2 \rightarrow L_Z^2$ is the adjoint of $\nabla m(W, h_P) : L_Z^2 \rightarrow L_W^2$.

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NPQIV Example

- Similarly, in NPQIV P is locally **just identified** by \mathbf{P} if and only if

$$E[f_{Y|Z,W}(h_P(Z)|Z, W)s(W)|Z] = 0 \text{ implies } s(W) = 0 \text{ for all } s \in L_W^2$$

Discussion

Exogenous Models

- Suppose $W = (Z, V)$ and that $\rho(W, h(Z))$ is differentiable in h .
- Then, it follows that P is locally **just identified** if and only if

$$P(E[V] = V) = 1 \text{ and } P(E[\nabla_h \rho(Y, h_P(Z)) | Z] \neq 0) = 1$$

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Efficiency Implications

- Parameters θ such as average derivatives, consumer surplus, etc.
 - \Rightarrow Plug-in typically **efficient** under “exogeneity” (Newey, 1994).
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 - ⇒ Plug-in **need not be efficient** under “endogeneity” (Ai & Chen, 2012).
- Two stage estimation problems $\theta(P) = \arg \max_{\theta} E[q(X, \theta, h_P(Z))]$.
 - ⇒ Two stage **efficient** under “exogeneity” (Ackerberg et al. 2014).
 - ⇒ Two stage estimation **need not be efficient** under “endogeneity”.

Conclusion

Local Overidentification

- Is model locally consistent with any parametric model?
- Abstracts from counting “parameters” and “restrictions”.
- Partial generalization to nonregular models.

Refutability and Efficiency

- Intrinsic link between refutability and efficiency.
- Generalizes connection present in GMM to regular models.

Conditional Moment Models

- Simple characterization by exploiting efficiency literature.
- Implications for plug-in and two stage estimation.