

THIS DOCUMENT IS BEST QUALITY AVAILABLE. THE COPY FURNISHED TO DTIC CONTAINED A SIGNIFICANT NUMBER OF PAGES WHICH DO NOT REPRODUCE LEGIBLY.

ATLAS Fording Study

ATLAS Fording Study Table of Contents

Executive Summary

1.0 Vehicle System

1.1 Baseline Description

1.2 Alternative Design

1.3 Performance

1.4 Human Factors Engineering/Safety Requirements

1.5 Reliability

1.6 Producibility

1.7 Cost Growth

1.8 Integrated Logistic Support

2.0 Engine Arrangement

- 2.1 Baseline Description
- 2.2 Alternative Design
- 2.3 Performance
- 2.4 Human Factors Engineering/Safety Requirements
- 2.5 Reliability

(ħ

- 2.6 Producibility
- 2.7 Cost Growth
- 2.8 Integrated Logistic Support

3.0 Operator Compartment

- 3.1 Baseline Description
- 3.2 Alternative Design
- 3.3 Performance
- 3.4 Human Factors Engineering/Safety Requirements
- 3.5 Reliability
- 3.6 Producibility
- 3.7 Cost Growth
- 3.8 Integrated Logistic Support

4.0 Electrical/Instrumentation

- 4.1 Baseline Description
- 4.2 Alternative Design
- 4.3 Performance
- 4.4 Human Factors Engineering/Safety Requirements
- 4.5 Reliability
- 4.6 Producibility
- 4.7 Cost Growth
- 4.8 Integrated Logistic Support

Approved for public release

Distribution Unlimited

Acce	sion Fo	r		
DTIC Unan	CRA& TAB nounced		A D	
By	ication	271	à	
Distribution / Availability Codes				
Dist	Avail			\neg
A-1				

DITO QUALITY INSPECTED 1





() 0 6

8 29

93

4.1 Base

1.4

		- 1
5.0 Suspension and Steering		
5.1 Baseline Description		
5.2 Alternative Design		
5.3 Performance		
5.4 Human Factors Engineering/Safety Requirements		
5.5 Reliability		
5.6 Producibility		
5.7 Cost Growth		
5.8 Integrated Logistic Support		
6.0 Powertrain		
5.1 Baseline Description		1
2 Alternative Design		
6.3 Performance		
6.4 Human Factors Engineering/Safety Requirements		
• • • •	•	
6.5 Reliability		
6.6 Producibility		
6.7 Cost Growth		
6.8 Integrated Logistic Support		
7.0 Hydraulic System		
7.1 Baseline Description		1
7.2 Alternative Design		
7.3 Performance		
7.4 Human Factors Engineering/Safety Requirements		Í
7.5 Reliability		
7.6 Producibility		
7.7 Cost Growth		
7.8 Integrated Logistic Support	· ·	{
8.0 Chassis Group		1
		i
8.1 Baseline Description	· · ·	l i
8.2 Alternative Design		ł
8.3 Performance		. .
8.4 Human Factors Engineering/Safety Requirements		1
8.5 Reliability		1
8.6 Producibility		1
8.7 Cost Growth		
8.8 Integrated Logistic Support		
9.0 Boom and End Effectors		
9.1 Baseline Description	1	ĺ
9.2 Alternative Design		
9.3 Performance		
9.4 Human Factors Engineering/Safety Requirements		
9.5 Reliability		
9.6 Producibility		4
9.7 Cost Growth		
9.8 Integrated Logistic Support		

ATLAS Fording Study



10.0 Tires

- **10.1** Baseline Description
- **10.2** Alternative Design
- **10.3 Performance**
- 10.4 Human Factors Engineering/Safety Requirements
- 10.5 Reliability
- **10.6** Producibility
- 10.7 Cost Growth
- **10.8 Integrated Logistic Support**

11.0 Microclimate Control

- **11.1** Baseline Description
- **11.2** Alternative Design
- **11.3** Performance
- 11.4 Human Factors Engineering/Safety Requirements
- 11.5 Reliability
- 11.6 Producibility
- 11.7 Cost Growth
- **11.8 Integrated Logistic Support**

12.0 Stabilizers

- **12.1 Baseline Description**
- **12.2** Alternative Design
- 12.3 Performance
- 12.4 Human Factors Engineering/Safety Requirements
- 12.5 Reliability
- 12.6 Producibility
- 12.7 Cost Growth
- **12.8 Integrated Logistic Support**

13.0 CCTV

13.1 Baseline Description

- **13.2** Alternative Design
- 13.3 Performance
- 13.4 Human Factors Engineering/Safety Requirements

13.5 Reliability

- 13.6 Producibility
- 13.7 Cost Growth
- **13.8 Integrated Logistic Support**

Attachment 1 - Corrosion Resistant Coating Technology

Attachment 2 - Surf Zone Stability

Attachment 3 - C130 Transportability Study

Attachment 4 - NBC Contamination Of Hydraulic System

Attachment 5 - Failure Modes

Attachment 6 - Operation & Maintenance Manual

Attachment 7 - Parts Manual

Executive Summary

The All-Terrain, Articulated Lift System (ATLAS) is the next generation of rough-terrain, shooting boom, fork-lift trucks. ATLAS operational requirements call for a dash speed of 50 mph, 60 inches of seawater fording capability for Logistics-Over-the-Shore (LOTS) operations, 10,000 lbs lift capacity at 4 feet and 4,000 lbs lift capacity at 21.5 feet and enhanced operator controls.

For ATLAS to reach the procurement phase, production and operating costs must be managed wisely. Machine requirements beyond those available on commercial roughterrain fork-lifts must be weighed against their incremental costs. The ATLAS's 60" fording requirement is substantially beyond commercial vehicle capability and was thought to be a major cost driver. To address this issue, BRDEC awarded Caterpillar a contract to study the impact of adding the 60" fording capability to a commercial machine conceptually altered to fulfill the operational requirements of ATLAS (Figure 1).

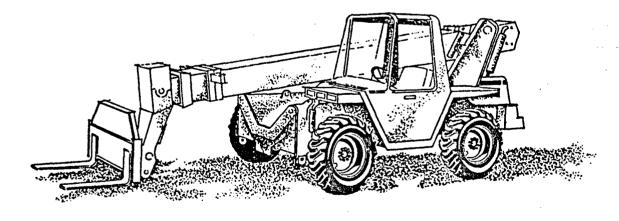


Figure 1 All-Terrain, Articulated Lift System (ATLAS) vehicle

A-TLAS Fording Study

Under the technical direction of Mr. David Krawchuk, Material Handling and Equipment Team (MHE), Fort Belvoir, VA, Caterpillar Inc. performed the ATLAS 60" Fording Study. The information generated during that effort is reported in this report. As a result of this study, the total technical and costs risks were substantially reduced without compromising ATLAS operational requirements.

The RFP and the work plan submitted in the Caterpillar proposal was heavily focused on the impact of saltwater corrosion. The concern was that protecting the vehicle from saltwater corrosion would require extreme measures (like the use of stainless steel materials, etc). That would drive procurement and operating costs, and adversely impact maintainability, reliability, and overall machine life. The impact of the 60" fording requirement on ATLAS operational performance was also investigated.

An intense Failure Modes, Effects and Criticality Analysis (FMECA) was proposed to assess the impact of seawater corrosion on all major vehicle systems and system components. However, early contract effort identified a cost-effective coating (primer) that substantially eliminates the corrosion problem. This information eliminated the need for the intense FMECA effort and more effort was shifted to other fording issues. This shift in effort allowed a more complete definition of an affordable ATLAS vehicle.

This study predicts that the procurement cost drivers (Figure 2) for an ATLAS vehicle are as follows:

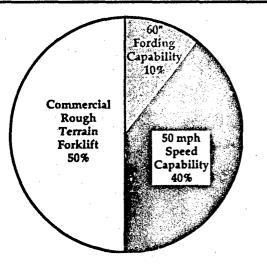
- 50% will be the cost of commercial machine
- 40% will be the cost of increasing speed from 20 to 50 mph
- 10% will be the cost of 60" of fording.

<u>^</u>

The 10% cost growth associated with the 60" fording requirement is based on the use of a very corrosion resistant primer coating identifed during this contract.

The commercial machine provides a fording capability of 16" and nominal corrosion resistance. A fording requirement of 30" would drive 80% of the cost required to provide a fording depth of 60".

ATLAS Fording Study



11

Figure 2 Procurement Cost Drivers

Technical issues required to safely and reliably operate ATLAS in 60 inches of salt water for extended periods of time fall into 2 categories: 1) waterproofing and 2) corrosion. These issues were further complicated by the fact that 60% of the vehicle could be under water during fording operations.

First, the ATLAS must be designed to be waterproof to the required fording depth. Classical waterproofing techniques, waterproof components, sealing, venting breather lines, etc., will satisfy that requirement.

Second, the LOTS operation requires that ATLAS be designed with sufficient corrosion protection to operate safely and reliably in a saltwater environment a number of times during its life cycle. The extensive and repetitive exposure of ATLAS to this environment necessitates that the corrosion issues be resolved in a thorough yet cost effective manner. As a result, corrosion and corrosion control was the prime focus of the trade study to assure that ATLAS would be as capable and reliable in completing its final mission as its initial mission.

The All Terrain Lifter, Articulated System (ATLAS) 60" Fording Study identified:

- 1) A cost-effective coating that substantially mitigates the life cycle costs associated with corrosion, and
- 2) The technical viability of ATLAS to safely and reliably operate in 60 inches of salt water for LOTS operations.

Besides addressing the primary concerns of fording and corrosion, the study also identified and resolved the following concerns:

- 1) C130 Transportability
- 2) NBC Contamination of Hydraulic System
- 3) Surf Zone Stability
- 4) Concept Design of Waterproof Operator Cab
- 5) Viability of FMTV Engine.

Corrosion Resistance Coating

The coating technology presented in Attachment 1 identifies an extra-ordinary, zinc-rich primer that is corrosion resistant and compatible with the CARC topcoat. Other primers that provide the required corrosion resistance were not compatible with CARC. CARC primers currently in use by the Army do not exhibit the desired corrosion resistance required by LOTS operations. This extra-ordinary, zinc-rich coating will provide the desired corrosion resistance without compromising the desired NBC protection associated with CARC. It eliminates the need for exotic designs, materials, and processes and allows the use of cost effective, off-the-shelf technology. This primer technology minimizes procurement, and owning and operating costs' impact of providing ATLAS the desired seawater corrosion resistance.

As a result of identifying this coating technology, the technical direction of this study shifted part of its emphasis from corrosion to the aforementioned engineering issues. Results of these investigations are presented in the following paragraphs.

C130 Transportability Study

The C130 Transportability Study (Attachment 3) identified one approach for .ransporting that does not compromise ATLAS operational, speed, lift, and mobility requirements. It requires that the wheels be reversed with the rim-offset inboard to meet the C130 requirement of 102 inches width.

This approach permits a wider stance and the use of large, 20.5R25, tires to fulfill its mission yet be readily converted to a C130 transport configuration. Caterpillar identified an axle, tire, and offset-rim design that meets those requirements. Alternate designs may be considered with maturation of ATLAS.

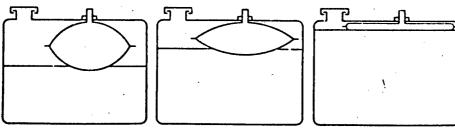
NBC Contamination of the Hydraulic System

The NBC Contamination of the Hydraulic System investigation (Attachment 4) identified cost effective technology to eliminate contamination of the hydraulic reservoir, lines, valves, and cylinders.

Hydraulic systems require an open breather or vent to the atmosphere to provide make-up air for the hydraulic tank. This repetitious inhaling and exhausting of air concentrates contaminates in the hydraulic oil during operations. The contaminated oil then contaminates the hydraulic lines, valves, cylinders, etc. of the system.

By substituting a simple bladder in lieu of a breather on the hydraulic tank, a closed system can be used (Figure 3).

The concept eliminates contamination of the hydraulic oil and subsequent disposal of a hazardous waste.



MINIMUM OIL VOLUME IN TANK NORMAL OIL VOLUME IN TANK

MAXIMUM OIL VOLUME IN TANK

Figure 3 Hydraulic tank with bladder

Surf Zone Stability Assessment

The Surf Zone Stability Assessment (Attachment 2) defines the stability of ATLAS when operating in a surf zone.

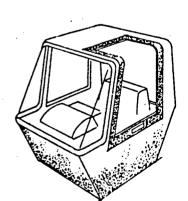
Operating within a surf zone introduces a wave loading not typically considered in classical stability assessments. This wave load on the rear of the vehicle is of greatest concern when ATLAS carries a 10,000 lb. load above the 60" waterline.

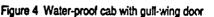
The Surf Zone Stability Assessment established that the ATLAS could safely and reliably operate in and exit from a surf zone while carrying the load above the waterline without tipping. This analysis identifies parameters that may be monitored as the ATLAS matures, assuring that this stability is not compromised. A more rigorous surf zone stability assessment, considering buoyancy effects, is suggested during full scale development.

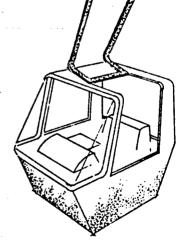
Water-Proof Cab

The water-proof cab (Paragraph 3.0) provides the operator a safe, functional environment for LOTS operations in a variety of water/air temperature extremes (Figure 4).

The concept incorporates a watertight structure below the waterline by locating the operator access entirely above the waterline. Operator access would be via a "gull-wing" door. The operator would be able to enter or leave the vehicle without entering the water or swamping the cab.







ATLAS Fording Study

This concept precluded further consideration of an alternative design that raised the cab above the waterline. That alternative design would have required removing the cab for C130 transport. The water-proof cab ensures the survivability of the operator during LOTS operations in a NBC contaminated environment. (Water degrades the level of protection provided by the NBC suits.)

FMTV Engine

The Family of Medium Tactical Vehicles (FMTV) Engine (Paragraph 2.0) was considered for ATLAS because it is a modern engine being used by the Army (Figure 5). Its use would substantially reduces life-cycle costs as well as reduce program technical risk. The FMTV engine and engine accessories have demonstrated fording capability as well as having fulfilled the RAM-D requirements for the FMTV Program.

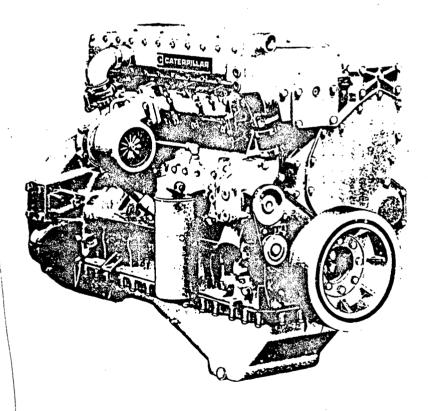


Figure 5 Caterpillar 3116 Family of Medium Tactical Vehicles (FMTV) Engine

Fage 7

ATLAS Fording Study

ATLAS Subsystems

The impact of fording and corrosion was also considered on the following ATLAS subsystems:

Electrical Arrangement	Paragraph	4.0
Instrument Group	Paragraph	4.0
Transmission	Paragraph	6.0
Axles	Paragraph	6.0
Suspension	Paragraph	5.0
Chassis	Paragraph	8.0
Boom	Paragraph	9 .0
Micro-Climate Control	Paragraph	11.0
Closed Circuit Television	Paragraph	13.0

For each subsystem, technology was identified that permitted ATLAS to be operated and maintained in a safe and effective manner. The study addressed *performance*, *human factors, safety, reliability, producibility, cost growth, and integrated logistic support issues.*

Each of these issues are addressed within each ATLAS subsystem paragraph. The following summary identifies the principal subsystems that are impacted by each issue.

Performance requirements for capacity, weight (total and distribution), fuel consumption, speed, vehicle height, and ground clearance are achievable by implementing the engine, powertrain, suspension, transportability, and cab concepts that are presented later. ATLAS performance will be most influenced by the C130 transportability issue, in particular tire size and vehicle gage.

HFE/Safety requirements for operator effectiveness and operator/spectator safety and noise are achievable. Suspension, cab, micro-climate control, and closed-circuit television (CCTV) concepts have the greatest impact.

ATLAS Fording Study

Reliability requirements of 89.9% for an 8 hour mission, and Mean-Time-Between-Mission-Failures are achievable by incorporating commercial water-proof components and the corrosion resistant coating. Establishing the acceptability of the FMTV engine and engine accessories substantially reduced ATLAS reliability risks.

Producibility requirements are addressed within each section. Implementation of the coating technology, permits application of commercially available water-proof components including the FMTV engine and engine accessories. The water-proof cab/ structures including the implementation of bulkhead (electrical, hydraulic, etc.) connectors provides a manufacturable structure and assembly with minimum cost growth. Engineering changes that would influence producibility are required to minimize crevice volume and facilitate decontamination are equally applicable to minimizing the incidence of crevice corrosion.

Procurement *Cost* Estimate, as represented by Figure 6, establishes that roughly 50% of the ATLAS cost is incurred to obtain a commercial rough terrain forklift capability.

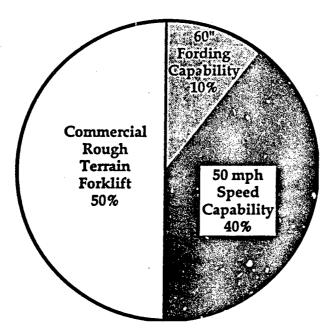


Figure 6 Procurement Cost Estimate

1

ATLAS Fording Study

ATLAS cost growth, above and beyond a continencial rough-terrain, shooting boom forklift truck, would be largely the result of the speed requirement. The speed requirement over 35 mph necessitates a new engine, powertrain, axles, tires, and most notably an elastic suspension. Forty percent of the procurement cost is incurred to provide for the high speed operation. Implementation of the coating technology minimizes the cost growth associated with the selection and processing of corrosion resistant materials. In combination with commercially available water-proof components, the cost growth to provide the fording capability is projected at 10% of the procurement costs. Most notably, only 10% of the cost is incurred to fulfill the 60 inch fording requirement. Of the fording costs almost 80% of that cost is incurred to obtain a 30" seawater fording depth capability. The remaining twenty percent of the cost is driven by increasing the fording depth to 60".

ILS requirements for 95% Achieved Availability and Maintainability including repair/ echelon, Direct Productive Annual Maintenance Hours (DPAMMHRS), support equipment, and preventative maintenance have been assessed within each section. Daily, fresh-water washdowns and proper maintenance of the corrosion-resistant coating provides sufficient corrosion control during LOTS operations. Only components that are subject to erosion corrosion must be inspected and replaced as required. DPAMMHRS increased as expected with the level of complexity of the ATLAS vehicle subsystems and operation in a corrosive environment. Systems that contribute to this increase include suspension, micro-cooling, and CCTV.

ATLAS Fording Study

Paragraph 1.0 Vehicle System

۶

1.1 Baseline Description

1.1.1 Commercial Applications of Rough Terrain Fork Lift Trucks (RTFL). The use of variable-reach rough terrain lift trucks has grown rapidly over the past decade. Telescoping material handlers (TMH), "Shooting booms" or "reach trucks" now represent between 40-50% of total rough terrain lift truck sales in North America. The remainder are of the "vertical mast" configuration.

One of the biggest advantages of a shooting boom machine over a vertical mast lift truck is its ability to reach forward and place the load. A straight mast truck must drive right up to the scaffolding or building to place the load; a telescopic machine can reach over obstacles to get the job done. Since lift height decreases as reach increases, the combination of required placing height and reach must be taken into account when specifying a RTFLs for a particular job.

The frame leveling feature of RTFLs (Rough Terrain Fork Lifts) improves their productivity and stability over straight mast lift trucks. The operator can level the chassis on uneven terrain for greater lateral stability and safety during high lifts. With frame leveling, RTFLs machines retain more capacity during high lifts than comparable-capacity high reach trucks.

RTFLs all-wheel three-mode steering provides excellent maneuverability for greater productivity on crowded job sites. For example, the circle steering mode gives Caterpillar's RT100 a very tight 13.6 ft (4.1 m) outside turning radius.

18

*

ATLAS Fording Study

Compact dimensions allow RTFLs to operate in low overhead and confined areas, further enhancing their productivity. For example, Cat's RT100 is only 104 in (2640 mm) tall and 96 in (2440 mm) wide.

Users buy four-wheel drive machines when they expect extremely poor underfoot conditions or need exceptional gradeability. RTFLs allow contractors to start building earlier in the spring and continue working in the worst underfoot conditions. Attachment flexibility makes these machines much more than just a "forklift". An attachment coupler makes it easy to drop off the fork carriage and install a truss boom, loose material bucket or other attachment for added versatility on the job site. This versatility increases machine utilization and can help justify premium rental rates.

1.1.1.1 Features of the Reference (Caterpillar RT100) Vehicle.

- Strong frame resists distortion and cracking in tough applications.
- Durable CAT 3114 engine.
- Proven CAT powershift transmission with elcetronic controls, full-clutch modulation, precision-ground high contact ratio spur gears, anti-friction bearings, large capacity lube system and excellent cooling capacity for long transmission life.
- Outboard planetary axle design reduces stresses on differential, drive shafts and axle shaft U-joints.
- Enclosed oil disc brakes on both axles are protected from contamination and oil cooled for long brake life.
- Parking brake interlock prevents driving through parking brake to protect brake discs.
- Electro-hydraulic control system eliminates mechanical linkages and hydraulic lines for increased reliability.
- Electronic control box is designed to high CAT standards for trouble-free operation and long life. Heavy-duty box is located in iso-mounted cab to reduce vibration and to protect it from the elements for increased reliability.

ATLAS Fording Study

- Premium wiring harness is waterproof and protected from abrasion for long, reliable service.
- Solenoid-actuated main control valve spools are enclosed within control valve body to seal out dirt and eliminate leaks.
- O-ring face seal fittings throughout hydraulic system reduce leaks.
- Lock valves are connected to cylinders with welded tubes to eliminate leaky fittings and hose failures.
- Overhead guard is certified to provide FOPS and ROPS protection. Standard 3 in (75 mm) wide seat belts pass the SAE J386 seat belt pull test.
- Gauges for engine coolant temperature, engine oil pressure and transmission oil temperature allow operator to monitor this critical information to help prevent damage to engine or transmission.
- Superior capacity retention at reach allows customers to place more material in less time. Optional outriggers increase capacity at reach for increased productivity.
- Planetary drive axles with full-time 4-WD, a front axle differential lock, equal size tires, balanced weight distribution and excellent ground clearance give these machines outstanding traction in difficult underfoot conditions to help keep jobs on schedule.
- All-wheel steering with three steering modes provides a very tight turning radius and excellent maneuverability.
- 12 degree of frame tilt allows operator to level chassis on uneven terrain to enhance lateral stability during high lifts.
- Attachment coupler on the boom allows attachments to be changed quickly and easily for versatility on the job. A wide range of attachments is available to meet customer's needs.

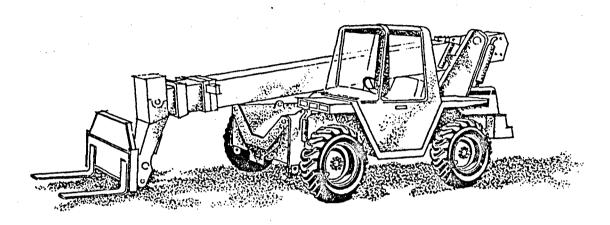
1.1.1.2 Operation and Maintenance/Parts Manuals. Commercial manuals are attached to clarify base vehicle configuration and operation/maintenance considerations.

Operation and Maintenance Manuals Parts Manuals Attachment 6 Attachment 7

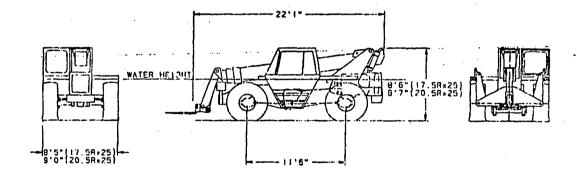
ATLAS Fording Study

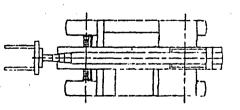
1.2 Alternative Design Vehicle Configuration.

The ATLAS vehicle concept generated by this study (Figure 1.2-1 and 1.2-2) uses the Caterpillar RT100 as the base vehicle. The modifications are driven by either vehicle performance or the 60[°] fording requirements. A description of the concept follows.











1.2.1 Concept Development. The ATLAS concept was strongly influenced by four major developments:

- a) Identification of a superior corrosion resistant coating,
- b) A Waterproof cab concept,
- c) Acceptability of Family of Medium Tactical Vehicles (FMTV) Engine for ATLAS, and
- d) C130 Transport Mode Concept.

Technical uncertainties were identified and addressed as follows:

Corrosion Resistant Coating Technology	Attachment 1
Surf Zone Stability	Attachment 2
C130 Transportability Study	Attachment 3
NBC Contamination of Hydraulic System	Attachment 4

These studies provided the direction for generating the ATLAS vehicle concept. The concept vehicle will fulfill the operational requirements for:

- a) Self Deployable at convoy speeds up to 50 mph,
- b) Variable Reach,
- c) Operational/fording capability to 60" (sea water) during Logistics Over the Shore (LOTS),
- d) 10,000 lb capacity @ 4 feet and 4000 lbs @ 21.5 feet,
- e) Micro-climate cooling system for operator in an enclosed cab,
- f) Operator enhancements that provide for coordinated boom movements (single lever true horizontal and true vertical control),
- g) Stability Monitoring and control,
- h) Closed circuit television (CCTV) for viewing forks and right rear of the vehicle, and
- i) C130 drive-on/drive-off capability with minimal disassembly and without removal of vehicle cab.

ATLAS Fording Study

Definition of the following vehicle subsystems (arrangements) are strongly influenced by the previously defined ATLAS requirements:

a) Engine Arrangement,

b) Operator Compartment,

c) Micro-climate Control,

d) Electrical/CCTV/Instrumentation System,

e) Brake Arrangement,

f) Steering Arrangement,

g) Hydraulic Arrangement,

h) Transmission/Drive Shafts,

i) Drive Axles,

j) Frame Leveling,

k) Frame,

l) Boom,

m) Attachments, and

n) Tires.



1.2.2 Operational Considerations. Operational considerations required to provide a valid trade study include but are not limited to:

- a) System Hour
- b) % Operating Time in saltwater
- c) Operating hour/year
- d) Operational life
- e) Reliability

a) System Hour. For purposes of this trade study, a system hour is defined as 80% operating time and 20% travel and transportation time. During the 48 minutes of operating time, the operator will complete 40 loading and transport cycles. The definition of the system hour defines the number of cycles/hour that the vehicle will be subjected to salt water.

b) % Operating Time in Saltwater. The vehicle will be subjected to 6 LOTS operations per year, each 24 hours in duration. During that time the vehicle will be operating in and out of the saltwater 80% of the time (19.2 hours).

ATLAS Fording Study

The % Operating Time in Saltwater establishes the number of times that a vehicle will be subjected to a salt water environment per year.

c) Operating Hours. The vehicle will be subjected to a total of 24 operations per year each 24 hours in duration for a total of 576 hours per year.

1.2.3 100 Hour Operation. A histogram for 100 hours of operation was developed to establish a baseline for sizing the automotive elements of ATLAS. The operational modes are defined as follows:

	<u>% Operation</u>	
Accordian Effect	5%	
Convoy	25 %	
Work Cycle	60%	
Idle	10%	

<u>1.2.3.1 Accordion Effect</u>. The accordian effect is defined as the lengthening and compression of a convoy. Some vehicles will not maintain convoy speed and lengthen the convoy. Those vehicles must have sufficient dash speed to overtake the convoy within a prescribed period of time or progress of the convoy is reduced.

The aforementioned ATLAS Histogram projects that the 50 mph dash speed will be used 5% of the time (5% out of 100 hrs of operation). This ATLAS concept provides for a maximum speed of 50 mph on level, improved surface roads with an empty machine.

<u>1.2.3.2 Convoy Speed.</u> ATLAS will be deployed in convoys with 2.5 and 5 ton trucks. ATLAS must maintain a minimum speed over a variety of grades without compromising convoy progress. Typically, convoys speeds are less than the dash speed. When convoying, the ATLAS will be unladened or empty. The convoy speed drives ATLAS powertrain requirements beyond commercial RTFLs which are matched to a maximum speed requirement of 35 mph.

Convoying will be 25% of ATLAS's mission. Here is the predicted convoy histogram:

ATLAS Fording Study

<u>1.2.3.3 Work Cycle.</u> The ATLAS work cycle is typical for RTFLs, i.e. low speed operation over undulating, unimproved surfaces, and severe grades. Typically, the RTFL is carrying a load more than 50% of the time because of the lower operating speed during the loaded part of the work cycle. However, for purposes of this study, loaded and unloaded time was assumed to be equal during the work cycle

The work cycle portion of ATLAS's mission is 60%. The histogram for the work cycles is predicted to be:

60% <	1/2 hr	≥2 mi/hr	45% Grade			1/2 Empty	
						1/2 Loaded	
	1 hr -	≥2 mi/hr —	30% Grade			1/2 Empty	
						1/2 Loaded	
			150 0		Γ	1/2 Empty	
		$3-1/2 hr \ge 2$	≥2 mi/hr —	15% Grade			1/2 Loaded
		55 hr ≥ 2 mi/hr -		0% Grade		Γ	1/2 Empty
			22 mi/hr —				1/?. Loaded

<u>1.2.3.4 (dle.</u> A RTFL will idle a substantial portion of its duty cycle waiting for work. For ATLAS, idle time is predicted to be 10% or 10 hrs out of 100 hr mission.

10% 10 hr — idle

<u>1.2.3.5. Operational Life.</u> The vehicle will have a projected 20 year service life.

1.2.4 Criticality Analysis. The ATLAS configuration defined in this study identified and mitigated a number of concerns with respect to fording and corrosion.

Operational safety hazards and mission critical failures were addressed by a concept including a water-proof cab, the proven FMTV engine (with fording capability), and implementation of classical, commercial practices for waterproofing construction equipment.

ATLAS Fording Study

Maintenance safety hazards and basic failures were addressed primarily by the identification of a corrosion resistant coating, preventive maintenance recommendations, and a hydraulic system concept that prevents NBC contamination. Only the concept development of the C130 Transport modification introduces the potential for a maintenance safety hazard, i.e. reversal of the wheel/rim, if appropriate resources are not allocated to this task.

<u>1.2.4.1 Definitions.</u> The criticality analysis implemented the definitions and establishes an order of precedence for the study. For purposes of this trade study, mission hours
 (t) = 8 hours anticipated for a LOTS operation.

a) Operational Safety Hazard	< t, mission hours
b) Mission Critical Failure	< t, mission hours
c) Maintenance Safety Hazard	> t, mission hours
d) Basic Failure	> t, mission hours

<u>1.2.4.1.1 Operational Safety Hazard</u>. An operational safety hazard is defined as any combination of failure modes and effects that may result in a Category I or Category II hazard during any single LOTS operation, i.e. less than 8 hours of operation.

Category I hazards are defined at catastrophic, i.e. a failure which would cause death of a human being or complete system loss.

Category II hazards are defined as critical, i.e. a failure which may cause severe personal injury or major system damage resulting in the loss of the mission.

<u>1.2.4.1.2 Mission Critical Failure</u>. A mission critical failure is defined as any combination of failure modes and effects that may result in a component, subsystem, or system failure that would reduce the effectiveness of that vehicle during a LOTS operation by 20%. Preventative maintenance during that specific operation is not applicable.

<u>1.2.4.1.3 Maintenance Safety Hazard</u>. A maintenance safety hazard is defined as a combination of failure modes and effects that may result in a Category I or Category II hazard over a number of LOTS operations.

Ĩ

<u>1.2.4.1.4 Basic Failure</u>. A basic failure is defined as any combination of failure modes and effects that would reduce the Mean-Time-Between-Failure of a component or subsystem.

<u>1.2.4.1.5 Preventative Maintenance</u>. Establishing a preventive maintenance base line improves program efficiency and effectiveness. Increased preventive maintenance is required to maintain any vehicle subjected to a salt water environment. Preventive maintenance procedures included (but not limited to this category) are post operational wash and dry, increased inspection, maintaining protective coating, etc. General preventive maintenance procedures applicable to a variety of common part categories will be defined. For example, this initial effort may preclude serious consideration of a stainless steel vehicle.

<u>1.2.4.1.5.1 Clean Water Washdown Recommendation</u>. ATLAS will undergo a daily clean, fresh water washdown to preclude the unnecessary build up of salt on the vehicle.

The clean water washdown substantially reduced the corrosion of a track width mine plow developed for the USMC Assault Amphibious Vehicle (AAV). After a year of virtually constant exposure to a salt water and spray environment, no single component was replaced due to degradation as a result of corrosion.

The AAV Mine Plow (AAVMP) was subjected to extensive hours of operation in salt water and a salt spray environment. During the mine clearing demonstration, the AAV would make several excursions into the surf zone per day to remove sand from the plow and wait for the next mine clearing exercise. The AAVMP had only the protection afforded by a red-lead primer and commercial topcoat.

<u>1.2.4.1.5.2</u> Maintenance of Corrosion Resistant Coating. The corrosion resistant primer and CARC top coat must be maintained consistent with the standard maintenance procedures of the U.S. Army.

<u>1.2.4.1.5.3 Inspection and Replacement</u>, Supplemental inspection and replacement (as required) of leaf springs will be required. Leaf springs will be installed on the rear axle in particular and may be installed on the front axle (similar to the ATLAS prototype vehicle).

1.3 Performance.

ATLAS performance both during LOTS operation and more conventional land operations is crucial to a mirilion success. ATLAS performance will not be compromised as a result of inclusion of a 60 inch fording requirement. Secondly, ATLAS performance will not improve as a result of reducing the fording requirement.

Specific performance attributes were considered throughout the study including:

Capacity Weight (Total and Distribution) Fuel Consumption Speed Vehicle Height Ground Clearance

1.3.1 Capacity. ATLAS will have a variable reach capacity of 10,000 lb @ 4 feet and 4000 lbs @ 21.5 feet. No factors have been identified as a result of this stud; that would compromise the current nor matured lift and reach capacity of ATLAS.

1.3.2 Weight (Total and Distribution). The ATLAS weight and weight distribution must be considered in two modes, operational and C130 transport. The requirements of the two modes are somewhat conflicting. The operational mode requires a rear axle weight to be greater than front axle to facilitate lifting a maximum of 4000 lbs @ 21.5 feet, whereas the transport mode necessitates that the weight be balanced (to maximize the GVW) within axle weight limitations.

<u>1.3.2.1 Operational Mode.</u> The projected ATLAS configuration with GVW of 32,500 lbs. introduces no identifiable operational concerns but the GVW introduces a number of transport concerns that are addressed in the C130 Transportation Study.

<u>1.3.2.2 C130 Transportation Study.</u> An ATLAS transport configuration identified within Attachment 3 provides a temporary 3rd axle, removal and stowage of the counterweight on forks, and reversal of the rim/wheels to meet the weight distribution and envelop limitations of C130 transport.

ATLAS Fording Study

1.3.3 Fuel Consumption. ATLAS fuel consumption for RTFL (low speed, low load factor) operations and convoy (high speed, high load factor) is strongly influenced by GVW, speed, grade, etc. Fuel tank size will be sufficient to allow completion of a 10 hour mission.

1.3.4 Speed. ATLAS shall be self-deployable at convoy speeds with a dash speed of 50 mph on level, improved surfaces. This speed requirement represents the most substantial departure from a commercial RTFL, establishes the requirements for the engine, transmission, axles, and tires, and requires a suspension group and a mechanically augmented front axle. Each element of the configuration is addressed within subsequent paragraphs.

1.3.5 Vehicle Height. The required ATLAS height of 101 inches facilitates C130 driveon/drive-off capability without removal of vehicle cab. The cab concept, identified as a result of this study, eliminates or negates the concept of raising the cab above the waterline 60 inch fording requirement. The cab transport height will be maintained at 98-100 inches.

Given the stringent requirement for C130 transport, ATLAS height must be monitored and addressed throughout maturation of the design.

1.3.6 Ground Clearance. ATLAS requirements are defined as follows. ATLAS with and without load will be capable of negotiating a 25 degree ramp of length greater than the truck's wheelbase with level surfaces at both the top and bottom of the ramp. Nothing other than the tires shall come in contact with the ramp when ATLAS travels over the ramp in either direction. Hydraulic fittings, hoses, tubing, and linkages shall not be the lowest portion of the truck and shall be protected by structural members from striking obstacles.

ATLAS ground clearance is projected to be 18 inches with the 20.5Rx25 tires on the concept vehicle. The 20.5Rx25 provide an additional 2.0 inches of ground clearance over the 17.5Rx25 tires. Given the acceptability of the projected ground clearance, no concerns have been identified that would compromise the ground clearance of the ATLAS.

1.4 Human Factors Engineering/Safety Requirements.

A number of issues have been identified that impact the safe and reliable operation of ATLAS that are resolvable with the maturation of the ATLAS design.

Specific HFE/Safety elements considered are as follows:

Operator Effectiveness Operator/Spectator Safety Noise Operator/Spectator

1.4.1 Requirements. HFE and Safety requirements are derived from MIL-T-53038.

<u>1.4.1.1 Human Factors Engineering</u>. ATLAS characteristics with the waterproof wab will provide for operation and maintenance by personnel ranging from the small person clothed, through the large person arctic clothed, in accordance with SAE J833, S \E J925, and Mil-STD-1474.

<u>1.4.1.2 Safety</u>. ATLAS will meet the safety requirements specified in SAE J 98 and ANSI B56.6. All rotating and reciprocating parts and parts subject to high temperature shall be guarded when such parts are exposed to contact by the operator and maintenance personnel performing daily maintenance functions. Nonfunctional edges shall be rounded, projecting points shall be blunted or rounded and excessive length of fasteners shall be avoided. Steps and platforms for entering the forklift shall have anti-skid, ice resistant surfaces. Oil level indicators for engine, transmission, and other components will be within easy reach and safe access of the operator and maintenance personnel.

1.4.2 Operator Effectiveness. Operator effectiveness will be enhanced by a number of engineering concept developments including:

- a) Suspension,
- b) Micro-cooling, and
- c) Closed Circuit Television (CCTV).

ATLAS Fording Study

<u>1.4.2.1</u> Suspension. ATLAS convoy and dash speed requirements establish the need for an elastic suspension. The effectiveness of the ATLAS suspension will be established with ride quality evaluations defined in Paragraph 5.0.

Maturation of the ATLAS design may require a suspended seat at vehicle speeds above 20 mph on improved surfaces.

<u>1.4.2.2 Microcooling</u>. The microcooling concept provides a subsystem that enhances the safety and performance of the ATLAS operator in harsh and life threatening environments. The objective of microcooling is to minimize water loss by the operator that would otherwise impair his judgment and reduce operational effectiveness jeopardizing operator and spectator safety. Thermo-electric cooling/heating devices will maintain operator effectiveness up to an ambient, temperature of 120 degrees Fahrenheit. Augmenting the thermo-electic system with an ice filled cooler enables ambient temperatures up to 160 degrees Fahrenheit.

<u>1.4.2.3 CCTV</u>. The CCTV concept designs provide for a two carnera (monaural) subsystem that permits the operator, with his view obstructed, to effectively engage or place a load up to the full extension of the boom. The second camera provides a rearview from the vehicle to assist the operator in negotiate the vehicle in reverse in any of the three steering modes; two wheel, crab, and counter steer. Other government studies have established that a 2-dimensional system fulfills the requirements for the supplemental vision. The CCTV is projected to have a 3% duty cycle for ATLAS material handling operations.

1.4.5 Operator/Spectator Safety. As a result of this evaluation, no issue was identified that compromised the safety of the operator or spectator.

1.4.6 Noise Operator/Spectator. Operator and spectator noise limitations have been derived from MIL-T-53038 for:

- a) Noise Limits- Operator,
- b) Noise Limits-Spectator, and
- c) Noise Hazard Precaution/Warning.

As a result of this evaluation, only noise emitted by the FMTV engine has been identified as a concern to be resolved during maturation of the ATLAS design.

ATLAS Fording Study

<u>1.4.6.1 Noise Limits - Operator</u>. The noise produced by the ATLAS shall not exceed 85 db (A) at the operators station during lifting, load lowering, and high speed operation. The evaluation will be conducted under the following conditions: engine operated at 2/3 maximum no-load, governed speed, 2/3 the rated load, and all windows fully opened.

<u>1.4.6.2 Noise Limits - Spectator</u>. The noise level of the of the forklift (excluding horns) shall not exceed 88 db (A) when tested in accordance with SAE J88.

<u>1.4.6.3 Noise Hazard</u>. The precaution of MIL-STD-1474 and noise hazard warning signs will be provided if the noise level is 85 db (A) or greater.

<u>1.4.6.4 Noise Engine-FMTV.</u> The FIATV engine is relatively quiet for a 290 HP engine emitting 96.4 db (A) untreated and 94.3 db (A) treated.

1.4.7 ATLAS HFE/Safety Baseline. The baseline RT100 vehicle incorporates a number of commercial features that address operator safety, performance, and comfort as well as spectator safety. These features are listed below.

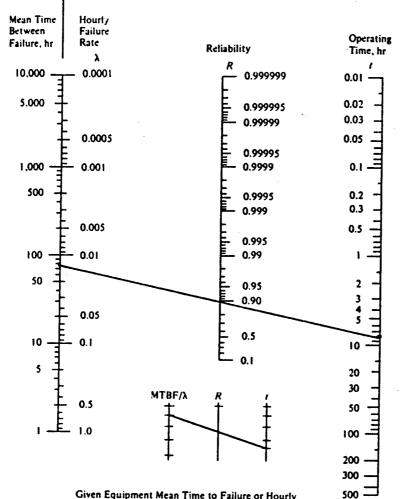
- Spacious operator compartment with plenty of head, leg, and elbow room comfortably accommodates most operators.
- Standard vinyl seat with thick cushions for comfort. Optional full-suspension seat for even greater operator comfort.
- Tilt steering column adjusts to fit the operator. Low effort power steering reduces operator fatigue.
- Low effort controls conveniently located to reduce reaching and operator fatigue.
- Electric joystick with low "Lever" effort gives the operator precise control of the boom.
- Twist-grip transmission control allows the operator to easily change gears or direction with the same control.

ATLAS Fording Study

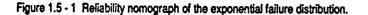
- Power brake system reduces brake pedal effort while maintaining good brake pedal "feel".
- A large convex mirror gives the operator good visibility to the right rear corner of the machine. The optional mirror group provides two additional mirrors to further enhance rearward visibility.
- Redesigned over-head grate offers improved upward visibility, and redesigned fuel/hydraulic tank module provides better visibility over right side of machine.
- Enclosed cab option with heater/defroster keeps operator warm in the winter, and good natural cross-ventilation keeps cab cool in the summer.
- Low noise levels and a radio/cassette option enhance operator comfort.
- Optional hydraulically-operated attachment coupler lets operator change attachments without leaving the cab.

1.5 Reliability.

Figure 1.5-1 provides a reliability nomograph that correlates reliability, MTBF, and mission duration (operating time on nomograph). This study incorporates "waterproof" not "water resistant" components to achieve the reliability requirements of ATLAS.



Given Equipment Mean Time to Failure or Hourly Failure Rate and Operating Time, Solve for Reliability. Connect "MTBF" and t Values with Straight Line. Read R, Probability of Survival in % is $R \times 100$.



ATLAS Fording Study

Reliability of the ATLAS vehicle was established based upon guidance provided in MIL-STD-785B Reliability Program for Systems and Equipment Development and Production. Specific reliability attributes (base line values) were established for the ATLAS vehicle as follows:

The reliability of 89.9% is a calculated term based upon a mission duration of 8 hours, a MTBF of 76 hour, and assuming an exponential failure rate implemented by the following equation:

% Reliability = e exp-(lambda summation)(mission duration) 89.9% = e exp-(0.0132)(8) or 89.9% = e exp-(1/76)(8)

1.5.1 Reliability Modeling and Allocations. Consistent with the guidance provided in MIL-STD-785 Tasks 201 and 202, the ATLAS vehicle is modeled as a series of subsystems with a specific reliability allocation for each subsystem. Typically automotive systems do not provide subsystem redundancy in order to minimize weight and maximize vehicle performance.

At the system level the ATLAS will exhibit a MTBF of 76 hours or a lambda summation of 0.0132 (= MTBF¹ or 76⁻¹). The summation of the lambda for each subsystem cannot exceed 0.0132 and meet the reliability objectives. In summary, the reliability allocation for each subsystem the ATLAS vehicles is projected as follows:

Subsystem	MTBF	lambda
Engine Arrangement	500	0.0020
Operator Compartment	1 000	0.0010
Electrical/CCTV/Instrumen	tation 1000	0.0010
Suspension/Steering	10 000	0.0001
Powertrain	1 000	0.0010
Hydraulic System	1 000	0.0010
Chassis	10 000	0.0001
Boom/End Effectors	10 000	0.0001
Tires	2 000	0.0005
Microclimate Control	4 000	0.0003
Subtotal		0.0063
Reserve		0.0069
· · · ·	Total	0.0132

ATLAS Fording Study

The reliability allocation provides substantial reserve (0.0069) that may be allocated to as yet undefined additional systems or added to currently defined systems. The reliability allocation is predicated upon the following assumptions:

- a) The ATLAS vehicle is an extension of proven commercial RTFL tailored to the requirements of the US Army.
- b) The ATLAS vehicle design reflects acceptable waterproofing technology, and
- c) Preventative Maintenance procedures are implemented with respect to the protective coating and the engine and automotive elements.

1.5.2 Failure Modes. Operating a vehicle in a salt water environment introduces a number of potential failure modes or damage mechanisms that must be assessed. Resolution of this problem is required for safe and reliable operation. As noted previously, failure modes are very sensitive to the definition of the operational requirements and definition of the mission.

Each of the following failure modes have been assessed with respect to the appropriate design elements) in the following order of precedence including:

Electrical Short Fluid Contamination Air Restriction/Constriction Galvanic Corrosion Stress Corrosion Crevice Pitting Erosion Corrosion Uniform Corrosion Intergranular Selective Leaching

ei Sa

ATLAS Fording Study

The first three failure modes, electrical short, fluid contamination, and air restriction/ constriction, can be eliminated with the use of off-the-shelf technology. This available technology will provide low-cost solutions for fording depth to 60".

The balance of the failure modes are related to vehicle operation in salt water for extended times over a period of years. Attachment 5 provides a brief, text book description of these corrosion mechanisms. Implementation of the corrosion resistant primer substantially mitigates the balance of the corrosion mechanisms.

Crevice corrosion must be addressed during the design maturation. Minimizing the number and size of crevice will adequately resolve this issue.

Erosion corrosion must be addressed by inspection and replacement as required of two elements of the ATLAS, leaf springs and drive shafts. These two elements are exposed to high, relative surface velocities in an abrasive, corrosive environment, i.e. sand/ saltwater. The abrasiveness of the environment precludes further consideration of surface treatments, exotic materials (stainless steel), etc.

1.5.2.1 Material Deterioration Prevention and Control. Caterpillar referenced the guidance provided in DARCOM-R 702-24 Army Corrosion Prevention and Control Program for this trade study.

1.6 Producibility.

As a result of this study, a corrosion resistant primer has been identified that substantially mitigates the long term degradation of ATLAS due to operating in a salt water (corrosive) environment. This primer is compatible with the MIL-P-26168 CARC paints. Reference Attachment 1.

Commercial manufacturing practices for RTFL would generally reflect the scope and depth of producibility considerations provided in MIL-HDBK-727 Design Guidance for Producibility. A number of special design considerations that impact producibility are required to accommodate the salt water fording requirements of the ATLAS vehicle. The design considerations fall within two broad categories of Watertight Integrity and Combating Corrosion.

ATLAS Fording Study

1.6.1 Watertight Integrity. The watertight integrity of the ATLAS vehicle can be provided by the design of watertight compartments and the utilization of waterproof bulkhead connectors for electrical, hydraulic, and mechanical penetration points to the watertight compartments.

Commercial high density electrical connectors, as well as MIL-C-5015 connectors, are available to provide adequate resistance to electrical shorts.

1.6.2 Combating Corrosion. Several generic methods are available for combating corrosion. One method is simply the replacement of inexpensive parts. Another would be to include one or more of the following design features:

- 1) choosing one metal for a system or electrically insulating dissimilar metals,
- 2) using a large anode surface area of compared with the cathode surface area,
- 3) eliminating or reducing to a minimum crevices, lap joints, nuts and bolts, rivets, small recessed areas, grooves and scratches, etc.,
- 4) providing for easy maintenance to prevent buildup of dirt, scale, rust, etc.,
- 5) allowing for uniform and moderate flow rates of fluids,
- 6) using the proper material for the given environment,
- 7) reducing the stress in parts that may stress crack, and
- 8) using corrosion inhibitors, corrosion-preventing films, or coatings where necessary.

<u>1.6.2.1 Alloying</u>. Alloying frequently provides the prime path to obtaining desired corrosion performance of engineering materials, i.e. ferrous, cast irons, and aluminum.

Identification of the corrosion resistant coating effectively precluded further consideration of material changes, i.e. steel to stainless steel to provide the desired corrosion resistance.

<u>1.6.2.2 Ferrous Materials</u>. Stainless steels feature chromium, a particularly useful alloying metal for ferrous materials, (steel). When present in concentrations greater than 12%, a passive oxide film is formed that is very corrosion resistant.

Stainless steels are particularly sensitive to erosion, crevice corrosion, and chloride pitting.

ATLAS Fording Study

<u>1.6.2.3 Cast Irons</u>. Cast irons, gray, malleable, and ductile, typically are alloyed with silicon in sufficient concentrations to provide a complex silicon-oxide film that imparts good corrosion resistance to cast iron.

<u>1.6.2.4</u> <u>Aluminum</u>. Service experience with 1000, 3000, 5000, and 6000 series wrought aluminum alloys in marine applications under the condition of partial exposure to salt water environments demonstrates good corrosion resistance and long life.

1.6.3 Protective Coating. Protective coatings cover a tremendous range. Choice of coating is determined by the degree of corrosion resistance required and the relative cost of obtaining the desired corrosion resistance. Some of the common coating techniques are defined as follows:

- Chemical conversion building up a relatively thick oxide film by anodizing (anodic oxidation, usually of aluminum) or immersing in a chromate or phosphate solution.
- Cladding hot rolling a sandwich of two metals to obtain metallurgical bonding between them.
- Diffusion high-temperature treatment in which one or more metals are dif fused into the substrate metal to form an alloy diffusion coating.
- Electroplating Electroplating or electrodeposition of a metal such as chromium, nickel, copper, tin, zinc, cadmium*, gold silver or platinum provides a thin layer on a metal substrate. Typically restricted to chromium in RTFL applications, these coating are more noble (more corrosion resistant than steel in salt water). The coating must be free of pits, scratches, or imperfections that would otherwise expose the steel substrate to the corrosive environment. Exposure of the steel substrate to salt water forms a galvanic cell, introduces a pitting corrosion, and rapidly degrades the durability of that component.

Hydraulic cylinder rods are typically electroplated to provide and maintain a smooth surface to maintain the integrity of the hydraulic seals. A minimum thickness of 0.016 inches is required to provide the necessary level of protection for ATLAS.

ATLAS Fording Study

- Enameling Enameling provides a fused glassy composition on the surface of steel or fuses a polymeric composition on a metal substrate to provide a non-corrosive film. Enameling is not typically used in off-highway applications.
- Flame spraying (or metallizing) Metallizing provides an alternate manufacturing method to electrodeposition. Metallizing is achieved by blowing metal in finely divided form through a melting flame onto a metal substrate. Typically, the film would be more noble than the steel substrate and subject to similar considerations.
- Hot dipping Hot dipping provides a protective film by immersing the metal substrates in liquid metals to coat them with zinc (as in galvanizing), tin, lead or aluminum. The coating may be more nobel (tin, lead, or aluminum) or less nobel (zinc) than the substrate.
- Painting Painting provides a pigmented organic carrier that reacts with air or dries by evaporation.
- * The use of cadmium has been restricted in the U.S. and EEC. Beginning in January, 1993 products that include cadmium will no longer be permissible or available.

1.6.4 Corrosion Design. Degradation due to corrosion can be minimized by implementing the following design strategies.

<u>1.6.4.1</u> Bolts. Chrome plated bolts may be replaced by oil-and-phosphate coated bolts. Chrome plated bolts are sensitive to damage of the chrome plating, whereas the oil-and-phosphate bolts are less sensitive to corrosion of the substrate.

<u>1.6.4.2 Sealing</u>. Any component sensitive to water damage or corrosion, in particular, should be sealed to prevent the intrusion of water.

Structural box elements should be watertight. Provide plugs to enable draining any accumulated water.

ATLAS Fording Study

<u>1.6.4.3 Crevice Corrosion Resistance</u>. The design of the vehicle should minimize or eliminate features that accumulate or retain water, dirt, oil, etc.

Drain holes should be provided in any cup-like features.

Intermittent welds should be eliminated and replaced by continuous welds.

Single sided welds should be replaced by double sided welds.

Perforated (skid) plate should be replaced by adhesive backed, skid-resistant overlays.

1.7 Cost Growth.

The ATLAS vehicle will reflect cost growth over a commercial vehicle.

The cost growth is associated with the performance requirements of the ATLAS, specifically the speed. The speed requires a suspension arrangement to control ride and shock when convoying. Alternately the suspension group must retain the stable platform and performance of a RTFL.

Given that the ATLAS vehicle fording requirements are driven by the LOTS operation, the cost growth associated with marinizing the vehicle are relatively independent of fording depth for this mission. Waterproofing the automotive elements and engine accessories eliminates salt spray from degrading critical elements. These elements are readily available largely due to historical US Army and USMC requirements for fording 60 inches of water.

Additional costs associated with the fording requirement are sealed cab and the corrosion resistance coating.

The fording, in combination with the NBC requirement drives the development of the unitized sealed cab. Given the extent to which water/moisture degrades the protection provided by the MOPP IV gear, elimination of the fording requirement may not preclude the desirability for a unitized sealed cab. The unitized cab would prevent salt water from readily entering the cab and coming into contact with the operator.

The corrosion resistant coating with the extra high density of zind dust increases the material cost of the primer by a factor of two over standard MIL-P-22709 (which is a non-CARC primer). The necessity of the coating is driven by salt spray and not necessarily by fording depth.

1.8 Integrated Logistic Support.

For this study, the alternative design (as required for the baseline vehicle to meet ATLAS requirements) was analyzed for Integrated Logistic Support (ILS) requirements. RAM-D related concerns were surfaced along with any provisioning issues. The maintainability requirements, listed in MIL-T-53038, served as a baseline to measure against maintainability.

1.8.1 The major ILS related concerns are trade-offs required to provide proper corrosion resistance, modifications necessary to meet ATLAS road speed and changes required to meet the 60" fording requirement. At the start of this study, it was felt that corrosion resistance was a major concern. Corrosion concerns were greatly reduced when a suitable corrosion inhibitive primer was found. The area which currently has the greatest ILS impact is the road speed requirement. Modifications for increased speed have large potential effects on reliability and maintainability. The 60" fording requirement, which has its largest impact on cap design, has some reliability and maintainability concerns, but these are relatively small in relation to the road speed requirement.

1.8.2 Specific Integrated Logistic considerations (definitions included) are:

Reliability

Availability

Maintainability

Repuir Echelon/Skill Required MTTR (Direct Productive Annual Maintenance Manhours) Support Equipment Preventative Maintenance

"*Reliability*" is defined as the probability that a system will perform satisfactorily for a given period of time, when used under specific operating conditions.

"Maintainability" will analyze requirements for both preventative and corrective maintenance.

ATLAS Fording Study

"Repair echelon" will use organizational/intermediate/depot levels in analysis of the net effect of a FMECA failure on operational availability. The analysis will look at the net increase in maintenance manhours (DPAMMHRS) resulting from modifying the system.

The "MTTR" is the mean time spent to repair a failure, regardless of level of maintenance.

"Support equipment", as a factor, is the logistic burden of systems necessary to maintain the modified equipment in a functional condition.

"Preventative maintenance" will analyze the increased requirements to maintain the modified vehicle in good working order. This procedure will include, but is not limited to, post operational wash and dry, increased inspection and maintenance of protective coating.

"Availability" is defined as Achieved Availability (Ai) of 95%. The system factors which impact on the ability to reach this goal are the limiting areas for availability.

ATLAS Fording Study

Paragraph 2.0 Engine Arrangement

2.1 Baseline Description-Engine.

The engine in the reference vehicle (RT100) is a state of the art turbocharged diesel engine. It is the 4-cylinder version of Caterpillar's 1.1 liters/cylinder engine series.

In October, 1991, the 6-cylinder version of this engine was selected by the Army for its new generation of Medium Tactical Trucks. The key features of this 1.1 Series are common through the series.

Details of the reference vehicle's 4-cylinder version, known as Caterpillar's 3114 engine (Table 2.1-1), are provided to establish the level of technology available with the 1.1 Series and more specifically in commercial RTFLs.

Key benefits of Caterpillar's 1.1 Series engine are exceptional performance, proven reliability and durability, low fuel consumption and quiet operation.

	<u>CA</u> 1	3114
Configuration	In-Line, F	our Cylinder
Bore	4.12 in	(105 mm)
Stroke	5.00 in	(127 mm)
Displacement	268 cu in	(4.4 L)
Horsepower @ 2200 rpm	103 hp	(77 kW)
Peak Torque @ 1400 rpm	284 lb-ft	(385 N•m)
Governed speed (no load)	2420 rpm	

Table 2.1-1 CAT 3114 Specifications

ATLAS Fording Study

2.1.1 Reliability. One of the main reasons for the 3114's outstanding reliability and durability is that the engine in the RT100 operates at a conservative speed and low load factor, well below its maximum 150 hp (112 kW) @ 2600 rpm capability.

2.1.2 Lube and Cooling Systems. The large capacity lubrication and cooling systems also enhance engine durability. The 11.6 qt (11.0 L) lube system has a large plate-type oil cooler integrally mounted in the engine block to reduce oil deterioration and varnishing of precision parts in severe operating conditions. The gear-type oil pump is mounted low, in the oil pan, for quick priming to reduce engine wear during start-up. A feature especially important in RTFL applications, since the engine is started frequently. A bypass valve in the oil filter mounting base ensures engine lubrication during cold starts and in case the filter plugs.

The 32.0 qt (30.0 L) capacity cooling system has a large five row radiator, and a 21 in (533 mm) diameter, six-blade fan for excellent cooling. The fan draws cool air from the rear of the vehicle for improved cooling efficiency. Flat fins in the radiator core reduce clogging and ease radiator cleaning. Wing nuts on the rear grill provide easy access for cleaning the radiator. The water pump is mounted separate from the fan and fan drive which reduces load and vibration for longer bearing and seal life. It is driven from the crank pulley by a separate belt to isolate it from an accessory belt failure.

2.1.3 Intake and Exhaust Systems. A large capacity, dual element air cleaner with pre-cleaner and service indicator is standard. The pre-cleaner and service indicator extend filter element life. The secondary element protects the engine in case of primary element failure for increased engine durability.

The turbocharger, driven by the engine's exhaust, acts as a compressor to boost the intake system pressure and force more air into the cylinders. This increases power while improving fuel economy and reducing emissions. The exhaust manifold has short straight runners to conserve exhaust energy for the turbo thus improving engine efficiency. The modern split turbocharger housing is designed for maximum performance. The turbo's size is carefully matched to the engine's power rating for optimum fuel economy and performance. The turbocharger allows the 3114 to produce rated horsepower and torque up to 7200 ft (2200 m) altitude. A large muffler and a cover over the engine oil pan contribute to lower noise levels.

ATLAS Fording Study

2.1.4 Fuel System. The 3114's excellent fuel economy is the result of precise fuel metering, high pressure direct injection and an advanced combustion chamber design. During endurance and quality tests, average RT100 fuel consumption was between 1.0 and 2.0 gallons per hour (3.6-7.6 L/h). Actual fuel consumption will depend on the vehicle application and other load factors.

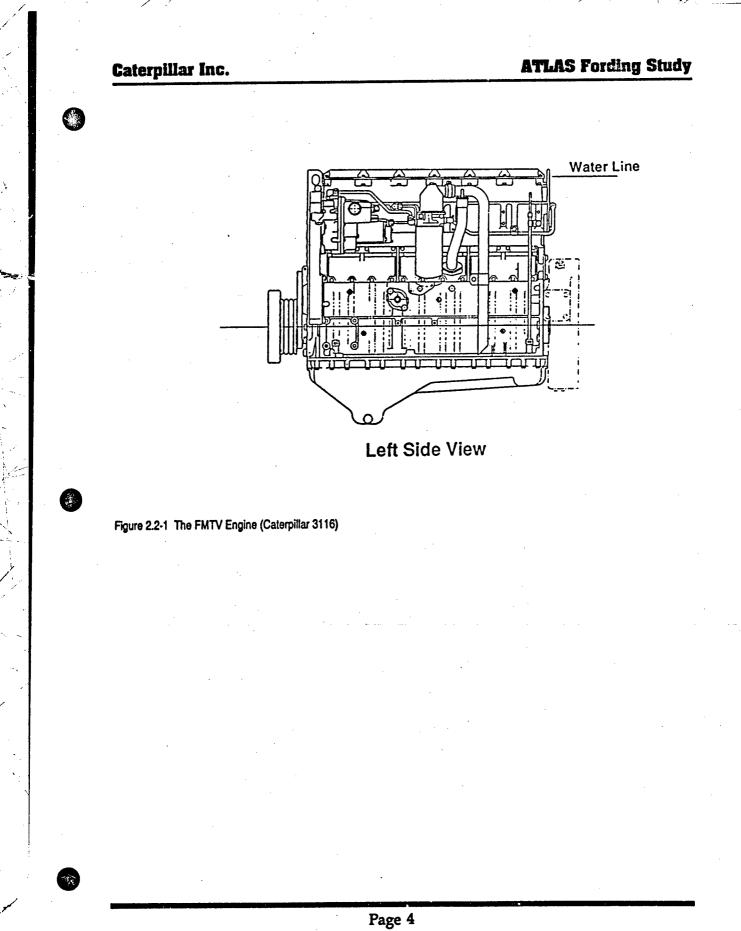
Cat's 1.1 Series uses a unit injector fuel system. This eliminates external high pressure fuel lines for increased reliability. The mechanical unit fuel injectors combine the injector nozzle and high pressure pump into one assembly for each cylinder. This rugged system provides very high injection pressures and short injection times for fast response, low fuel consumption and excellent emissions control. An electric solenoid on the flyweight-type, full range governor shuts down the engine when the engine run control is turned off.

Spin-on primary and secondary fuel filters keep contamination out of the fuel system for top performance. The primary fuel filter screens out large particles and also acts as a water separator. It can be cleaned and reused. The secondary filter has a medium to filter out fine particles, so it must be replaced periodically. A primer pump makes it easy to prime the fuel system.

2.2 Alternative Design.

ATLAS power requirements were calculated based on operational requirements. Dash speed and convoying scenarios identified the minimum power requirement as 270 hp. The Army's newest truck engine, the Cat 3116 engine rated at 290 hp, is presented as one logical choice for ATLAS. The FMTV Engine (Caterpillar 3116) fulfills the engineering, performance, and supportability considerations defined within this study. The 3116TA Engine (Turbocharged, Aftercooled) is a logical extension of the 3114T Engine provided on the RT100. Both engines are members of the 1.1 Liter Engine Family (liters/cylinder).

As reflected in Figure 2.2-1, the FMTV engine has been tested and evaluated with respect to fording; tests were conducted on two of the three run-off FMTV vehicle configurations. Figures 2.2-2 summarizes the characteristics of this engine arrangement.



.

ATLAS Fording Study

	3116 ATAAC DIESEL TRUCK	ENGINE	
	- 290 HP @ 2600 RPM - 25% Torque		
	- 230 IF @ 2000 RFM - 23% TOIQUE	SI Metric	English
General Engine	Power Daties and Second		
Data	Power Rating and Speed	216 kW 2600 r/min	290 HP @ 2600 rpm
Uala	Rating Type No. of Cylinders and Arrangement	Medium Duty 6 in-line	Medium Duty
	Bore and Stroke	105 x 127mm x mm	6 in line
	Displacement	6.6 L	4,13 x 5in x in
	Combustion System	Direct Injection (DI)	403 cu in Direct biostics (DI)
	Aspiration Type	ATAAC	Direct Injection (DI) ATAAC
	Compression Ratio	16.0 10 1	16.0 to 1
	Piston Speed	11.0 m/s	2167 ft/min
	Cycle	4	4
	Rotation Facing Flywheel End	CCW	ĊĊŴ
	Firing Order	1.5.3.6.2.4	1.5.3-6-2-4
	Dry Unit Weight (with Flywheel)	555.1 kg	1224 b
	Static Bending Moment @Rear Face Flywheel Housing (max.)	814.1 N-m	7200 tb-in
Air Intolia Custom			
Air Intake System	System Restriction Limits:		
	Maximum Allowable with Clean Dry Element	3.7 kPa	15 in H2O
	Maximum Allowable with Dirty Element	6.2 kPa	25 in H2O
Air-to-Air System	Intake Manifold Temperature (Maximum Allowable)	43.3°C	110° F
(Conditions of	Charge Air Flow @ Rated	23.6 kg/min	52.0 lb/min
77" F Ambient and	Charge Air Flow @ Peak Torque	13.7 kg/min	30.2 lb/min
30 mph Ram Air)	Turbo Air Outlet Pressure @ Rated	280.5 kPa (Abs)	83.0 in/HG (Abs)
	Turbo Air Outlet Pressure @ Peak Torque	248.4 kPa (Abs)	73.5 in/HG (Abs)
	Maximum Turbo Inlet Temperature	36.1°C	97" F
	Turbo Air Outlet Temperature @ Rated	189° C	372' F
	Turbo Air Outlet Temperature @ Peak Torque Allowable Pressure Drop Turbo Outlet to Manifold Inlet	164 ° C 13.5 kPa	327" F
• •	Nomable Fressbie blop - robb Oblet to Markov inter	1J.J KEG	4 in Hg
Cooling System	Engine Coolant Capacity	13.2 L	14 qt
	Top Tank Temperature (Maximum Allowable)	110° C	230' F
	Top Tank Temperature (Minimum Recommended)	71.1°C	160° F
	System Capability (Min. Ambient Temp) Rated/Peak Torque		
	+100 rpm	48.9/43.3° C	:20/110" F
	System Pressure Cap (Minimum Pressure Recommended)	68.9 kPa	10 psi
	Coolant System Regulators		
	Start to Open Temperature	82.2°C	180° F
	Fully Open Temperature Coolant Pump Flow @ 1.5m (5 II) H20	93.0° C	199° F
	Resistance:		
	Flow Rate @ Raied Speed	272 L/min	72 000
	Flow Rate @ Pezk Torque Speed	148 L/min	72 gpm 39 gpm
	System Fill Rate (Capable of Interrupted Fill)	18.9 L/min	5 gpm
	Coolant Low Level Sensitivity:		a Abuu
	Minimum Percent of Total System	9	9
	Maximum Percent of Pump Pressure Rise Loss	10	10
	Pump Cavitation Temperature (Minimum Allowable)	93.3° C	200' F
	Pump Pressure Rise Loss (Maximum Allowable)	20%	20%
	Air Venting Capability @ 35% Pump Pressure Rise Loss	0.33 L/min	0.7 pt/min
Exhaust System	System Back Pressure (Maximum Allowable)	10.0 kPa	40 in H20

15 AUG 90

Figure 2.2-2 Caterpillar 3116 Engine Specifications Part 1

Ξġ.

ATLAS Fording Study

CATERPILLAR INC	. 3116 ATAAC - 290 HP (continued	uj .	an a
		St Metric	English
Fuel and Governor	Fiel System Type	Cat MUI	Cat MUI
r der and Governor	Fuel Supply Line Restriction (Maximum Allowable)	13.8 kPa	4.1 in Hg
	Fuel Return Line Restriction (Maximum Allowable)	67.5 kPa	20.0 in Hg
	Normal Fuel Pressure	365 kPa	53 psi
		JOJ KFa	as hai
	System Shutolis Offered:	Yes	Yes
	Energized to Run Standard Energized to Shut Off Optional	Yes	Yes
	Energized to Shot Off Ophonal	162	105
Lube Oil System	Refill Volume with Filter Change	17 L	18 qt
	Sump Capacity:		
	Low Mark Level	13.2 L	14 qt
	High Mark Level	15.2 L	16 qt
,	Maximum Allowable Oil Temperature	121.1°C	250° F
	Oil Pressure with SAE 10w30 Oil @ 99" C (210" F)		
	Normal	350.0 kPa	51 psi
	Min. @ Low Idle	103.4 kPa	15 psi
	Oil Type Recommended	API CE, CE/SG	API CE, CE/SG
Starting System (Engine with SAE 10w30 Oil)	Recommended Battery Capacity for 90-Sec Cranking (Min. CCA @-18°C (0°F)) Electric Slart - 12 V Mcºor: Ambient Temperature 0° C (32° F) and Above	1050 CCA	1050 CCA
	Ambient Temperature -18° C (0° F) to 0° C (32° F)	1100 CCA	1100 CCA
	Ambient Temperature Below -18° C (0° F)	1200 CCA	1200 CCA
	Electric Start - 24 V Motor:	505 000	525 CCA
	Ambient Temperature 0° C (32° F) and Above	525 CCA 550 CCA	525 CCA 550 CCA
	Ambient Temperature -18° C (0° F) to 0° C (32° F) Ambient Temperature Below -18° C (0° F)	600 CCA	600 CCA
Performance	Low kile Speed	750 r/min	750 rpm
Data	High Idle Speed	2870 r/min	2870 rpm
@ Rated	Altitude Capability	1525 m	5000 tt
Conditions	Starting Torque	445.7 N•m	328.7 lb-ft
	Heat Rejection to Coolant (Total @ Rated Load)	99.4 kW	5655 Btu/min
Unless Noted)	Specific Heat Rejection @ Rated Load	0.46 kW/kW	19.5 Blu/hp-min
	Heat Rejection to Coolant (Total @ Peak Torque)	76.1 kW	4340 Btu/min
	Specific Heat Rejection @ Peak Torque	0.47 kW/kW	20.0 Btu/hp-min
		108.6 U/h	28.7 gph
	Fuel Flow to Return Line (From Engine)	50.8 U/h	13.4 gph
	Specific Heat Rejection @ Peak Torque Fuel Flow to Transfer Pump (To Engine) Fuel Flow to Return Line (From Engine)		•

Figure 2.2-2 Caterpillar 3116 Engine Specifications Part 2

ATLAS Fording Study

2.2.1 Basic Engine Arrangement. The FMTV engine may be provided as a commercial, basic engine arrangement in accordance with MIL-STD-1410 Methods for Selection of Industrial Engines for End Item Applications.

2.2.1.1 Engine Location. Rear mount engines are typical for RTFL applications.

<u>2.2.1.2 Noise Engine-FMTV.</u> The 3116 engine is quiet for a 290 HP engine operating at 2600 rpm emitting 96.4 db(A) untreated and 94.3 db(A) treated. The ATLAS engine, at 270 HP and 2400 rpm, would emit less noise than the FMTV engine.

<u>2.2.1.3 Corrosion Resistance</u>. The engine shall be painted with corrosion resistant primer with a topcoat of MIL-P-26168.

Various engine components experience temperatures that "burn" and effectively remove the primer and topcoat from those surfaces. Those components, i.e. turbocharger, exhaust manifold, etc, are alloyed to provide oxidation recistance. The same alloys, (chromium, nickel, etc) that provide oxidation resistance in air provide corrosion resistance in salt water.

<u>2.2.1.4 Waterproofing</u>. The FMTV engine has been evaluated by the US Army with respect to fording capability. The ATLAS engine arrangement of the 3116 engine could maintain _ll those features.

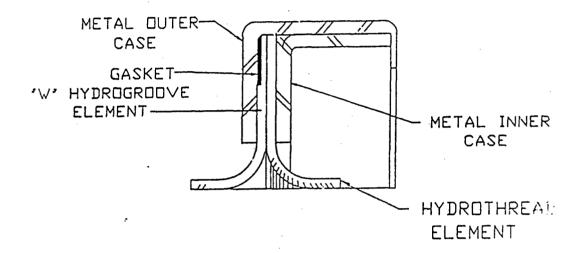
2.2.2 Fan Disconnect. The engine fan must be disconnected before the fan is exposed to water. During a LOTS operation the fan must be disconnected with each excursion into the surf zone and reactivated upon exiting the surf zone, hence a manual fan disengagement was not considered.

The ATLAS engine arrangement provides an automatic fan disconnect to disengage the fan when a predetermined water level is encountered; alternately, the fan reengages upon exiting the surf zone.

The addition of a fan disconnect can also reduce fuel consumption. By automatically monitoring the water temperature at the radiator, the fan will be engaged only when required to provide necessary engine cooling. Fan horsepower requirements are eliminated and fuel consumption decreases.

2.2.3 Seals Crankshaft. The FMTV engine arrangement provides water fording seals on the crankshaft. Two seals are used in series to prevent contamination of the oil during fording operations.

The outboard crankshaft seal provides the double-seal needed for fording, see Figure 2.2.3-1.



CATERPILLAR 4R8831

Figure 2.2.3-1 Outboard Crankshaft Seal

Pumping action provided by a hydrodynamic thread in combination with the rotation of the crankshaft excludes the water.

A second seal in-board of the engine precludes the loss of oil from the engine. As with the outboard seal, the pumping action of the hydrodynamic thread in combination with the rotation of the crankshaft stops oil loss.

2.2.4 Flywheel Housing. The flywheel housing, located below the waterline, incorporates sealed access covers and plugs.

2.2.5 Breather Group-Line. The ATLAS Breather Group-Line will be routed from the crankcase breather to a location above the splash zone. The design of the ATLAS may provide for a common breather group for submersed engine, transmission, axles, etc.

2.2.6 Heat Rejection. The 3116's low heat rejection, 20 btu/hp/minute, minimizes radiator size. Low heat rejection and small packaging results in more uniform heat distribution. "Hot" spots on the surface of the block are minimized and any thermal fatigue introduced by excursions into the surf zone are minimized.

2.3 Performance.

2.3.1 100 Hour Operation. A histogram for 100 hours of operation was developed to establish a baseline for sizing the automotive elements of ATLAS. The operational modes were defined as follows:

	<u>% Operation</u>
Accordion Effect (Dash Speed)	5%
Convoy	25 %
Work Cycle	60%
Idle	10%

<u>2.3.1.1 Accordion Effect.</u> The accordion effect is defined as the lengthening and compression of a convoy. Some vehicles over a period of time will not maintain convoy speed and lengthen the convoy. Vehicles that do not maintain convoy speed must have sufficient dash speed capability to overtake the convoy within a prescribed period of time or convoy speed would be reduced.

ATLAS Fording Study

<u>2.3.1.1.1 Dash Speed.</u> Operationally ATLAS is required to have a 50 mph dash speed on level (0% slope), improved surfaces. This dash speed provides ATLAS the capability to make up lost time and distance when convoying with other vehicles, 2.5 and 5 ton trucks. An unloaded ATLAS, at 270 hp, will have dash capabilites as follows:

•	2% Grade	-	40 mph
•	1 1/2% Grade	-	43 mph
•	1% Grade	-	47 mph

• 1/2% Grade - 50 mph (Max Speed)

Figure 2.3.1.1.1-1 shows this information. Combinations of these conditions make up 5% of ATLAS's operations. This was used for calculating RAM and in sizing other powertrain components.

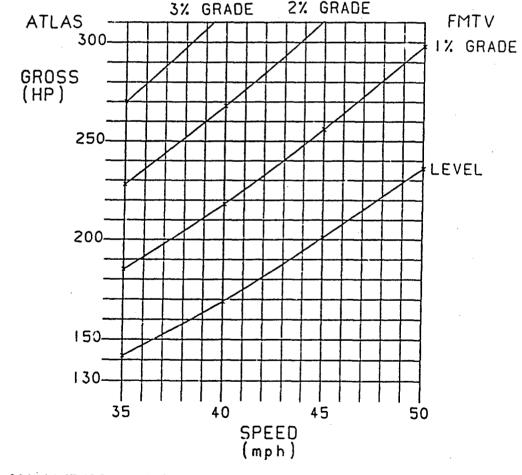


Figure 2.3.1.1.1-1 ATLAS Concept with Cat 3116 Engine

ATLAS Fording Study

Figure 2.3.1.1.1-1 was developed based upon the following factors:

Rolling Resistance=2.0% (on road)Frontal Area=75 ft 2Vehicle Weight=32,250 lbs.

The effort required to overcome the rolling resistance is:

Rolling Effort

- Vehicle Weigh. x Rolling Resistance
 32,250 x 2%
- = 645 lbs.

The effort required to overcome the air resistance is:

 Air Effort
 = 0.0025 x mph² x Frontal Area

 = 0.0025 x mph² x 75

 = 0.1875 x mph² (lbs)

The effort required to negotiate the gradient is:

Gradient Effort	-	Vehicle Weight x Gradient (%)
	-	32,250 x Gradient (%) (lbs)

The horsepower required at the wheels is:

HP_{Wheels} = <u>(Rolling + Air + Gradient Effort) x MPH</u> 375

The net engine power is a function of the efficiency of the power train:

HP_{Net}

<u>HP Wheels</u> 0.70

The gross engine horsepower is the summation of the HP_{Net} and the parasitic losses*:

HP_{Gross}

HP_{Net} + Parasitic Losses
HP_{Net} + 25

* Parasitic losses are defined as horsepower requirements of engine fan and other engine accessories.

ATLAS Fording Study

<u>2.3.1.2 Convoy Speed</u>. ATLAS will be deployed in convoys with 2.5 and 5 ton trucks and similar tactical vehicles. Typical convoys will operate at speed somewhat less than the dash speed, but for extended periods of time. When convoying the ATLAS will be unladened or empty. The folowing convoy conditions were identified as typical for ATLAS and here have been used for selecting other powertrain components and calculating RAM.

8%@	 35 mi/hr	- 2%	Grade	 Empty
12%@	 35 mi/hr	- 1%	Grade	 Empty
80% @	 35 mi/hr	0%	Grade	 Einpty

Figure 2.3.1.1.1-1 shows that ATLAS at 270 hp easily meets power requirements. Convoying is 25% of ATLAS's operating mission.

<u>2.3.1.3 Work Cycle.</u> The ATLAS work cycle is typical for RTFLs, i.e. low speed operation over undulating, unimproved surfaces, and severe grades. For purposes of this evaluation, loaded and unloaded times are equal. 60% of ATLAS's mission will be in the work cycle. The following conditions were identified as typical for ATLAS and have been used in selecting other powertrain components and RAM calculations.

$$60\% < \begin{bmatrix} 1\% @ - \ge 2 \text{ mi/hr} & -45\% \text{ Grade} & - \\ 1/2 \text{ Empty} \\ 1/2 \text{ Loaded} \\ 1/2 \text{ Empty} \\ 1/2 \text{ Loaded} \\ 1/2 \text{ Loaded} \\ 5\% @ - \ge 2 \text{ mi/hr} & -15\% \text{ Grade} & - \\ 1/2 \text{ Loaded} \\ 1/2 \text{ Loade$$

<u>2.3.1.4 Idle</u>, ATLAS will idle 10% of its duty cycle.

<u>2.3.1.5 Hours to Rebuild</u>. ATLAS engine hours before overhaul/rebuild, would be estimated at 3000 hours.

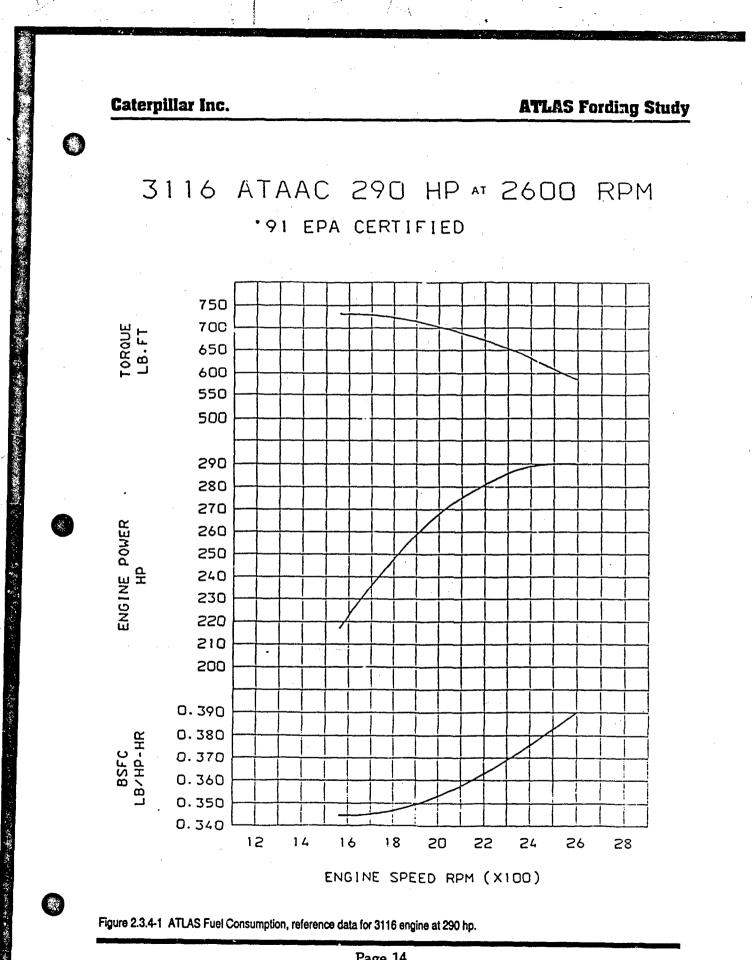
2.3.2 Capacity. Application of the 3116 Engine Arrangement does not influence the capacity of ATLAS.

2.3.3 Weight (Total and Distribution). Replacement of the 3114 engine with the 3116 engine results in an increase of 205 lbs from 1019 to 1224 lbs. The frame of the ATLAS would need to be extended to accommodate the longer engine, increasing the weight supported by the rear axle. Maturation of the design will establish the extent to which the increase in weight can be applied in lieu of additional counterweight.

2.3.4 Fuel Consumption. The AT^T_AS fuel consumption is strongly influenced by the gross vehicle weight, payload/load factor, duty cycle, slope, speed, efficiency of the powerplant, etc.

These data can then be reduced within a family of curves plotting torque (ft-lbs), engine power, and Brake Specific Fuel Consumption (BSFC) vs engine speed (Figure 2.3.4-1 and 2 for the FMTV Engine Arrangement). The BSFC provides a variable to compare fuel consumption of various engine sizes and duty cycles. The minimum power rating for ATLAS is 270 HP at 2400 rpm. A dual power setting of the engine may be considered to limit the maximum torque at low gears (work operations), yet provide the horsepower and rpm necessary for high speed, convoy operations.

During maturation of the ATLAS design and further consideration of operational requirements charts specific to the ATLAS engine would be developed for accurate predictions of fuel consumption and fuel tank sizing.





ATLAS Fording Study

ζ.,

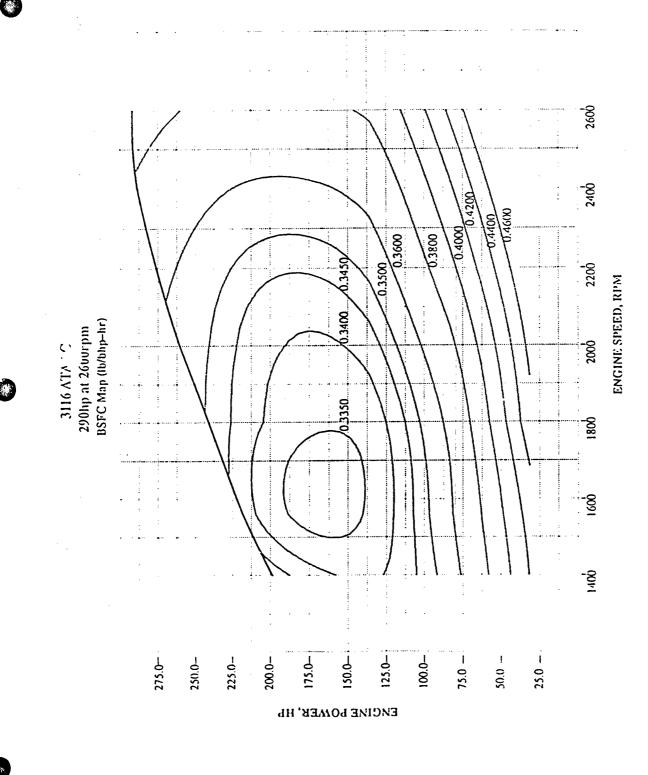


Figure 2.3.4-2 ATLAS Fuel Consumption, reference data for 3116 engine at 290 hp.

ATLAS Fording Study

2.3.5 Vehicle Height. Vehicle height will not be influenced by the use of the 3116 engine.

2.3.6 Ground Clearance. Ground Clearance will not be affected by the use of the 3116 engine.

2.4 HFE/Safety.

Application of the 3116 engine arrangement introduces no identifiable concerns though emissions are considered with respect to safety.

2.4.1 Engine Emissions. The FMTV 3116 engine meets the 1991 EPA on-highway emissions standards.

Emissions are also a function of the ability of the engine to breath, i.e. to bring in air at low temperature and to exhaust completely leaving no gas in the combustion chamber. Close attention to these issues will assure engine performance and efficiency during excursions into the surf zone and fording during LOTS operations.

2.4.2 ATLAS Engine Configuration. The ATLAS requires a rear mount engine as opposed to a front mount engine of the FMTV. This could impact engine performance if not properly addressed during the final vehicle design phase.

2.5 Reliability.

Implementation of the modified FMTV 3116 Engine arrangement and commercially available waterproof accessories will provide a MTBF that equals or exceeds the 500 hours allocated. Upon maturation of the ATLAS design the reliability model can be refined as required.

The long term reliability (durability) of the 3116 engine has been established as a result of the FMTV evaluation at a power rating of 290 HP at 2600 rpm. The projected power requirement for ATLAS is 270 HP at 2400 rpm. This decrease in power rating translates directly to an improvement in reliability and durability.

ATLAS Fording Study

Caterpillar Inc.

2.6 Producibility.

Implementation of the modified FMTV 3116 engine has no detrimental effect on producibility.

Implementation of commercially available waterproof engine accessories have no detrimental effect on producibility.

2.7 Cost Impact.

ATLAS engine cost will be typical of a commercial diesel engine at the 270 hp rating. Since ATLAS performance requirements are higher than commercial RTFLs in this load capacity, engine costs will increase roughly equal to the percentage increase in engine power. The important fact is that commercial engines are available to meet ATLAS's requirements. The engine cost would increase by approximately 50%.

Implementation of commercially available engine accessories will minimize cost growth though a water-resistant accessories are typically 50% more than standard accessories whereas waterproof accessories are typically 100% more expensive than standard accessories.

Cost savings due to FMTV provisioning of the 3116TA engine, will be realized. Items changed to meet ATLAS will be the only items requiring separate provisioning. With the excellent reliability and fuel economy exhibited by the 3116 engine, substantial life cycle cost (LCC) savings will be realized. Additionally, LCC savings due to the inherent maintainability and simple, reliable design of the 3116 should be realized.

ATLAS Fording Study

2.8 Integrated Logistic Support.

Implementation of the basic arrangement of the FMTV 3116 engine will reduce ILS impact on the ATLAS program. Provisioning costs will be minimized by FMTV provisioning of a similar engine. The excellent inherent maintainability of the 3116 has been proven by commercial application and successful maintenance by Army personnel during FMTV endurance testing and teardown for logistic demonstration. The reliability and availability of the engine are excellent as shown by commercial application and FMTV endurance testing. The engine is designed to optimize reliability, with design features as listed above.

The 3116A engine has inherently high durability due to the simplicity and sizing of engine components. The durability of the FMTV engine will be even higher in the ATLAS vehicle, due to reduced RPM and horsepower. The sizing of the engine block, to minimize hot spots, is particularly important (to minimize danger of block damage by asynchronous cooling) when operating in the surf zone.

The Army parts system, with a base minimum of 16,000 FMTV engines, will be well prepared to handle the addition of ATLAS engines. Additionally, the worldwide Caterpillar support network will be available to assist with emergency maintenance/ parts requirements as proven recently during Operation Desert Shield and Desert Storm.

Paragraph 3.0 Operator Compartment

3.1 Baseline Description.

The RT100 incorporates a standard cab arrangement with a step up, side access.

3.2 Alternative Design.

The cab will be a new design to fulfill the fording and NBC requirements of ATLAS.

3.2.1 Requirements.

<u>3.2.1.2 NBC Warfare</u>. ATLAS is expected to operate in a Nuclear Biological and Chemical environment.

<u>3.2.1.3 Transport.</u> ATLAS shall have a C130 drive on/off capability without removal of the vehicle cab.

<u>3.2.1.4 Considerations.</u> The fording requirement may be addressed via three approaches with the accept/reject rationale;

- a) Do Nothing. Assume the cab leaks and take appropriate action inside the cab to waterproof instruments, electronics, etc. The do nothing approach was rejected as the presence of water would degrade the protection provided by the MOP IV gear in NBC environments. The water level would be above the waist of the operator.
- b) Seal Standard Cab. Prevent the ingress of water 100% into the (standard) cab by sealing electrical/mechanical penetration points, windows, doors, etc. Add a bilge pump to minimize standing water. Sealing standard cab was rejected based upon the extreme difficulty in maintaining the door seals (below the waterline) over the life of ATLAS.

ATLAS Fording Study

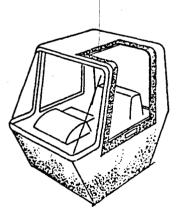
c) Water-Proof Cab. Develop a water-proof cab (new design). A submersible structure (bathtub) below the waterline would eliminate leaking/weepage of water through the bulkhead.

ATLAS requirements to operate in a Nuclear Biological and Chemical and environment in conjunction with the fording requirements and a transportation requirement for C130 drive on/off capability without removal of the vehicle cab necessitated the concepting of a waterproof cab.

3.2.2 Water-Proof Cab. The water-proof cab concept (Figure 3.2.2-1) necessitated that a number of concepts evolve to fulfill ATLAS requirements including:

- a) Submersible Structure,
- b) Superstructure/Operator Access,
- c) Penetration Points, and
- d) Cofferdam/Bilge Pump.

A waterproof cab precludes raising the cab from further consideration.



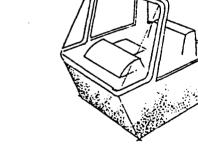


Figure 3.2.2-1 Water-proof cab with gull-wing door



ATLAS Fording Study

The waterproof cab would be sensitive to fording requirements between the depths of 15 and 60 inches. A fording depth of 15 inches would not required a submersible structure, waterproofing of penetration points, nor consideration for a bilge pump. Fording requirements greater than 15 inches requires sealing of the penetration points and an increasing portion of the cab to be a submersible structure with a bilge pump. The height of the operator access decreases, see Figure 3.2.2.2.1-1, with an increasing fording requirement.

<u>3.2.2.1 Submersible Structure.</u> The submersible structure provides a welded "bathtub" structure that will be submersed below the waterline.

<u>3.2.2.2 Superstructure/Operator Access.</u> The superstructure above the waterline will consist of operator access, a FOPS (falling object protection structure), and the glass enclosure (including provisions for the emergency exit).

<u>3.2.2.2.1 Operator Access.</u> The operator will access the vehicle via a "gull-wing" door. The door will be located completely above the waterline (Figure 3.2.2.1-1). It provides accessibility to the operator's station by allowing the operator to step down into the operating compartment. The gull-wing door is comprised of access height, depth, and width.

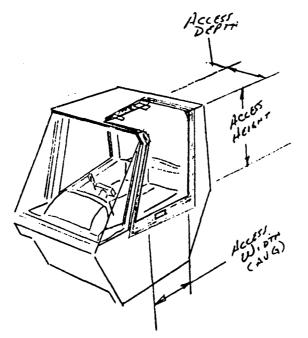


Figure 3.2.2.2.1-1 Operator Cab with gull-wing door

ATLAS Fording Study

The door concept is a trade-off between maintaining the watertight seal of a door that would extend below the waterline and accessibility by the operator (human factors engineering/safety issues that may be addressed with maturation of the ATLAS design). Reduction of the fording requirement would, in general, improve accessibility by the operator as door height increased.

<u>3.2.2.2.2 FOPS.</u> The falling object protection (FOPS) will be an extension of commercial cab technology. Inclusion of the "gull wing" operator access will require an engineering assessment of the FOPS structure.

To fulfill FOPS requirements with a gull wing door the cab would require a number of structural changes. The horizontal component of the gull-wing door would require sufficient structural integrity to assume and distribute the load. This may be accomplished with a single steel plate or shroud.

The cut-out from the cab overhead would be designed to accommodate the loading from either the horizontal plate of the gull wing door or balance of the overhead structure.

<u>3.2.2.3 Penetration Points.</u> The submersible structure provides for waterproof penetration points below the waterline. Waterproof bulkhead connectors are available for the electrical (including coaxial for CCTV), hydraulic, pneumatic, and microclimate systems.

Mechanical penetration points would be eliminated via the application of springapplied, hydraulic release mechanisms for the parking brake and engine acceleration.

<u>3.2.2.4 Cofferdam/Bilge Pump.</u> The bilge pump provides a level of redundancy that in combination with a cofferdam below the floor of the cab would exhaust any water that circumvented the submersible structure and sealed penetration points. The cofferdam would provide a drain plug that would also serve as an inspection point. The presence of water in the cofferdam would trigger a maintenance action.

3.2.3 Ventilation. Typical RTFL operations may be conducted with an open rear window and supplemental fans.

ATLAS Fording Study

3.2.4 Glass. The development of a sealed cab with limited ventilation necessitates consideration of tinted/treated glass to minimize heat build-up in the cab (greenhouse effect) and micro-cooling power requirements.

Potential maturation of a requirement for specialized laminated glass permits consideration of bullet-proof glass providing a low-level of ballistic protection.

3.3 Performance.

Implementation of the waterproof cab will degrade ATLAS performance only to the extent that minimal weight (<200 lbs) is added to the vehicle.

3.4 HFE/Safety.

The water proof cab substantially mitigates a number of operator survivability risks associated with conducting a LOTS operation in a NBC environment. The waterproof cab provides for operator access and emergency egress above the .vaterline permitting the operator (in MOPP IV gear) to safely exit the vehicle during a LOTS operation. Immersion of the MOPP IV gear in water compromises the level of protection provided by that gear.

A number of HFE and safety issues must be addressed with the maturation of the ATLAS waterproof cab design and the fording depth/operational requirements.

The primary issues is safe and easy operator access and egress for other than LOTS operations. The minimum access height expected for the gull-wing door is 40 inches with an access depth approximately equal to the half the width of the cab. The access width of the door may be proportioned accordingly to facilitate operator access and egress.

The cab would provide a combination of steps, toe holds, and grab handles to permit the operator to safely and effectively enter/egress the cab.

The step would be a single rung with supporting wire rope. A toe hold would be provided as a second step to support the operator. An exterior grab handle would be provided. A second grab handle and step would be provided within the cab to support the operator as he sits down within the cab. Once seated the operator would secure the gull wing door in the retracted or closed position.

ATLAS Fording Study

Caterpillar Inc.

3.5 Reliability.

The waterproof cab minimizes the unreliability associated with operating a vehicle with stringent fording and NBC requirements.

3.6 Producibility.

The waterproof cab will be a new design. The primary producibility trade-off is the design of the door. Sealing a standard door would require stringent dimensional conformance to fulfill the watertight integrity requirements.

Conceptually, the gull-wing door and frame would be manufactured as a serviceable, module with minimal assembly required at the vehicle assembly operation.

3.7 Cost Impact.

The cost of the gull-wing waterproof door would be a factor of two greater than a conventional waterproof door or a factor of four greater than a standard RTFL door. The water-proof cab structure would be comparative in cost with a standard cab. The cost growth associated with a water-proof cab is defined in other sections of this study, notably 4.0 Electrical/Instrumentation and 5.0 Suspension and Steering.

3.8 Integrated Logistic Support.

Implementation of the water proof cab with a serviceable water-proof door facilitates repair-by-replacement of the module. Locating the door seals above the waterline minimizes the criticality of maintaining those seals.

Paragraph 4.0 Electrical/Instrumentation

4.1 Baseline Description.

The baseline description establishes the electrical instrument arrangement of the RT100 from which the alternative ATLAS designs evolve.

4.1.1 Electrical System and Cold Start. The 12-volt negative ground electrical system has a 100 amp-hr maintenance-free battery, a 60 amp alternator and an enclosed, positive engagement starter An anti-restart ignition key switch prevents engaging the starter when the engine is already running. A 60 amp circuit breaker protects the alternator and fuses protect the other electrical circuits. The fuses are located under the hinged dash in the operator compartment.

The standard starting system is capable of starting the engine down to 32° F (0° C). An optional Cold Start Package provides an ether starting aid and dual CAT 100 ...mp-hr batteries for extra cranking capacity to start the engine below 32°F (0° C).

4.1.2 Electric-over-Hydraulic Controls. Electro-hydraulic control system eliminates mechanical linkages and hydraulic lines for increased reliability.

4.1.3 Electric Transmission Control. Electric transmission controls eliminate mechanical linkages, and internal oil passages eliminate external oil lines for increased transmission reliability.

ATLAS Fording Study

4.1.4 Boom Controls. The RT100 implements:

- a) Single Lever Control,
- a) the Kruger System Mark III,

 $\langle \cdot \rangle$

- b) Auto-Height Control and
- c) Auto-Reach Control

<u>4.1.4.1 Single Level Control</u>. Control of the boom is achieved through one 3-axis joystick. This joystick inputs a signal into the Electrical Control Unit (ECU). Upon receiving this signal, the ECU outputs a signal, the magnitude of which is relative to joystick position, to the valve for that particular function. This proportional control feature provides very precise control of the boom motions.

A thermistor is built into the main hydraulic valve-bank. It permits the system to automatically compensate for any change in solenoid resistance, due to temperature change, and provides constant response charactistics over the entire operating temperature range.

<u>4.1.4.2 Kruger System Mark III.</u> The Kruger System Mark III load moment device monitors the load for comparison to the load chart. At such time that the operator exceeds the safe operating limits, the system will "advise" the operator via an audible/ visual alarm and/or a shut-off device to preclude the operator from increasing the load-moment. The system is environmentally sealed.

<u>4.1.4.3 Auto Height Control</u>. The operator has the ability to automatically maintain a constant height of the forks to horizon when telescoping out or in. The boom is positioned manually to the desired height. This distance is automatically set when Auto mode is selected by a switch on the dash. The ECU then begins computing boom length, boom angle and chassis angle from information supplied by three syncronized sensors.

Auto Height operates by simply selecting a telescope function as illustrated by the following example. As the boom moves out, the ECU is constantly updated with information from the three external sensors and drives the telescope out, and boom raise or lower valves automatically maintain the selected height.

ATLAS Fording Study

The chassis inclinometer allows the ECU to compare actual chassis angle to the horizon. This means that even if the truck is working in rough terrain, the height of the forks remain true to horizon, not to chassis angle.

<u>4.1.4.4 Auto Reach Control.</u> The operator has the ability to maintain a constant distance between the center of the front axle and the front of the forks with respect to horizon when boom lowering or raising. The boom is positioned manually to the desired reach. This distance is automatically set when Auto mode is selected by a switch on the dash. The ECU then begins computing boom length, boom angle and chassis angle from information supplied by the three sensors.

The selection of boom raise or lower results in the ECU driving the chosen valve and the telescope in or out valves automatically to maintain the set distance between the front of the fork and the center of the front axle.

4.1.5 Harness-Wiring. Premium wiring harnesses are waterproof and protected from abrasion for long, reliable service.

4.2 Alternative Design.

The electrical system of the RT100 provides many of the features required by ATLAS though a number of alterations are required.

4.2.1 Requirement. Electrical requirements are derived from MIL-T-53038(ME). Maturation of the ATLAS Program will include many of these requirements.

<u>4.2.1.1 Electrical system.</u> The forklift electrical system would be for heavy duty, 12 volt or 24 volt service, and in accordance with SAE J539. All electric wiring would be routed so as to provide ease of maintenance and maximum protection.

and the second second

a start a start and a start a

ATLAS Fording Study

<u>4.2.1.2 Batteries</u>. Batteries would be furnished and shall be in accordance with MS35000 Battery, Storage, Lead Acid, Waterproof, type 6TN and would be readily accessible for service. The batteries would be negative grounded in accordance with SAE J538. The battery terminals would be accessible for removal without requiring disassembly of other components.

<u>4.2.1.3 Battery mounting</u>. Batteries would be located so they can be cleaned, serviced, and removed without removing any component except the quick-release battery box cover if a battery box is furnished. Battery supports, holddowns, and areas around the installation which could possibly be affected by dripping or seepage of acids would be protected with a coating conforming to TT-C-494, type II. The battery would be mounted in such a manner as not to interfere with access to engine components (accessories). Battery mounting would provide for complete support over the entire base of the battery and would be in such a position that the level of the electrolyte is directly visible without removing the battery from its mounting bracket or requiring the use of tools. Battery restraining claps would be provided to hold the battery in a fixed position. The battery compartment (if furnished) would have provision for drainage and provision for gas venting at or near the top of the compartment. Cover and positioning would be protected against short circuiting. Ungrounded cable would be protected by rubber grommets or insulated passages at entry to the battery box.

<u>4.2.1.4 Battery cable</u>. Battery cables would be furnished which meet the requirements of SAE J1127. The voltage at the storage battery terminals and the starting motor terminals including connections would not differ more than those shown in table I of SAE J541. Positive and negative cable terminals would be identified and corrosion-resistant SAE bolts and nuts provided.

<u>4.2.1.5 Slaving components.</u> The truck would be equipped with a 24-volt slave receptacle conforming to MS52131 Connector, Plug, Electrical Inter-vehicular Power, Cable. The slave receptacle would permit charging of the truck batteries and slave starting of the engine from an external power source and shall also provide a power

ATLAS Fording Study

source for charging and slaving other equipment. The slave receptacle would be installed on the exterior of the truck near the battery enciesure and would be accessible to personnel standing on the ground. A plate would be furnished adjacent to the slave receptacle which reads "24 Volts".

<u>4.2.1.6 Circuit breaker</u>. Each electrical circuit would be protected with a circuit breaker in accordance with SAE J553 and would have labels which describe the function served by the circuit breaker. Fuses are not acceptable.

<u>4.2.1.7 Lights.</u> The forklift would be provided with not less than two headlamps for forward illumination, not less than two floodlamps mounted so as to illuminate the forks and MLRS, and two floodlamps for rearward illumination. The lights would be shock mounted in elastomer ring housings and would conform to SAE J598. Headlamps would conform to SAE J1029. Front floodlamps would be adjustable a minimum of 45 degrees above and below the horizontal plane and laterally a minimum of 15 degrees right and 15 degrees left and would be capable of being adjusted by the operator from inside the operator's cab. Lights positioned in such a way as to be subject to damage would be protected by guards.

<u>4.2.1.8 Blackout lighting</u>. A separate wiring harness may be provided for the blackout lights. One blackout headlight conforming to MS51318 Headlight: Blackout, 24 volt, Waterproof would be mounted on the extreme left within the plan outline of the forklift at the front, positioned to provide illumination when the forks are in retracted carry position. The blackout headlight would be adjustable in accordance with SAE J598. Two blackout stoplight-taillights conforming to MS51330 Stoplight - Taillight, Vehicular - 24 Volt Blackout Tail, Blackout Stop or MS52125 Composite Light - Tail, Stop, Turn, and Marker would be mounted adjacent to the rear taillights, and would be mounted in 6-inch diameter holes or would be provided with guards. Each light would be recessed not less than 1/2-inch behind the hole or face of the guard. Two blackout marker lights conforming to MS52126 Composite Light - Front, Turn, Park and Marker would be mounted as far apart as practicable.

ATLAS Fording Study

<u>4.2.1.9 Taillights.</u> Two taillight-stoplight assemblies in accordance with SAE J585 and SAE J586 would be installed, one on the left rear and one on the right rear of the forklift, with the lens face recessed not less than 1/2-inch back of a protecting member.

<u>4.2.1.10 Interior lighting</u>. The truck would be equipped with gauge lighting or indicators which are readily visible to the full range of user personnel. The gauges and instruments shall be adequately lighted for night operation and would have blue-green blackout lens with spectral emission in the 400 to 625 nanometer wavelength range.

<u>4.2.1.11 Horn.</u> The forklift shall be equipped with an electric, air, or air-over-electric horn. The horn button assembly and electrical wiring for the horn shall be constructed to be moisture and weather resistant to prevent entry of moisture when operated or stored outdoors under all weather conditions. The horn button may be mounted on the steering wheel or instrument panel.

<u>4.2.1.12 Diagnostic Connector Assembly (DCA) Measurement Capability.</u> The forklift would incorporate an easily accessible DCA in the operator's cab for interface with the simplified test equipment/internal combustion engine (STE/ICE) test equipment as specified in MIL-T-62314, Appendix B. The DCA would be in accordance with TACOM drawing No. 12258941. All requirements for DCA would be in accordance with the STE/ICE design guide for vehicle diagnostic connector assemblies, report No. CR-82-588-003. As a minimum, the DCA shall have the capabilities for measuring:

Engine RPM (average), Engine power (RPM/SEC), Compression unbalance, Battery voltage, Starter negative cable voltage drop.

ATLAS Fording Study

A fuel shut-off method would be provided for running compression unbalance checks. Determination of test mode (either DCA or transducer kit (TK) shall be made by the contractor for the following test parameters:

Fuel Supply Pressure,	Starter Motor Voltage,
Fuel Return Pressure,	Starter Current First Peak,
Fuel Filter Pressure Drop,	Internal Battery Resistance,
Fuel Solenoid Voltage,	Battery Resistance Change,
Engine Oil Pressure,	Alt/Gen Output Voltage,
Engine Oil Filter Pressure Drop,	Alt/Gen Field Voltage,
Engine Coolant Temperature,	Alt/Gen Neg Cable Voltage Drop,
Starter Solenoid Voltage,	Starter Circuit Resistance,
Starter Current (Average),	Transmission Oil Pressure.

Test points which are inaccessible for measurement in the TK mode would be made in the DCA mode. A separate wiring harness would be provided for the DCA assembly and include all wiring and necessary hardware to perform required capabilities. The contractor would also provide vehicle test cards in the format identified on TACOM drawing No. 122258955 addressing both DCA and TK measurements and would incorporate the test cards into forklift technical manuals. Adaptors required for interface with the STE/ICE when measuring in the TK mode would be permanently installed on the forklift.

<u>4.2.1.13 EMI/EMP</u>. EMI requirements are considered to be readily obtained with current off-the shelf technology. The EMI requirements are per MIL-STD-461A, Notice 4 Methods RE05 & CE07.

<u>4.2.1.13.1 CE07</u>. The requirement is applicable for Air Force and Navy procurements for the following types of leads: AC and DC leads which obtain power from or provide power to other equipment or subsystems.

Conducted switching spikes of less than 50 microseconds in duration would not exceed the following, as applicable:

a) AC Leads: +/- 50% of nominal rms roltage b) DC Leads: +50%, -150% of nomin (line voltage

ATLAS Fording Study

Conducted switching spikes equal to or greater than 50 microseconds in duration shall meet the transient requirements of MIL-STD-704. Spike duration is the time interval between the 50% amplitude point on the transient trailing edge and the 50% point of the transient trailing edge; high frequency ringing superimposed on the pulse leading edge or trailing edges should be ignored.

<u>4.2.1.13.1</u> HEMP requirements necessitated that the vehicle be fully operational after 15 minutes and referenced Fig A10, A11, and Table A3 of QSTAG-244.

Normal operation occurs when the system is operating as intended in the absence of any fault or malfunction which degrades the performance beyond established requirements. It includes all system function required for the aircraft operation except during the electric starting of the propulsion engines and the battery start of the auxiliary power unit. Normal operation includes switching the utilization equipment, prime mover speed changes, synchronizing and paralleling of the power sources and operation from external power sources. Although transfer operation as defined herein is a normal function, it is treated separately in the standard because of the power interruption which may be produced. Conducted switching spikes, which are excursions of the instantaneous voltage not exceeding 50 microseconds, would be considered normal operation characteristics.

Transient. A transient is changing value of the characteristic that usually occurs as a result of normal disturbances such as electric load change and engine speed change. A transient may also occur as a result of a momentary power interruption or an abnormal disturbance such as a fault clearing.

Transients that do not exceed the steady state limits are defined as lesser transients. Transients that exceed the steady state limits but remain within the specified normal transient limits are defined as normal transients.

Transients that exceed normal transient limits as a result of abnormal disturbance and eventually return to a steady state limits are defined as abnormal transients.

Table II and Figures 10 and 11 should clarify the limitations.

ATLAS Fording Study

4.2.2 Alternative Design - Electrical. The electrical system of the RT100 must be altered to meet the operational requirements of ATLAS. The RT100 implements a 12 volt water-resistant system that would be replaced with a 24 volt water-proof system. In addition the RT100 must fulfill additional requirements for close circuit television (CCTV), micro-cooling, and DCA/ICE.

4.2.2.1 Battery. The batteries of the RT100 may be located in a sealed structure or above the splash height permitting the use of water-resistant units. Alternately, waterproof batteries (MS3500) shall be required.

The 3116 ATAAC engine requires 600CCA @ 24V to start at -20°F.

Enclosed is a drawing (Figure 4.2.2.1-1) of projected battery position.

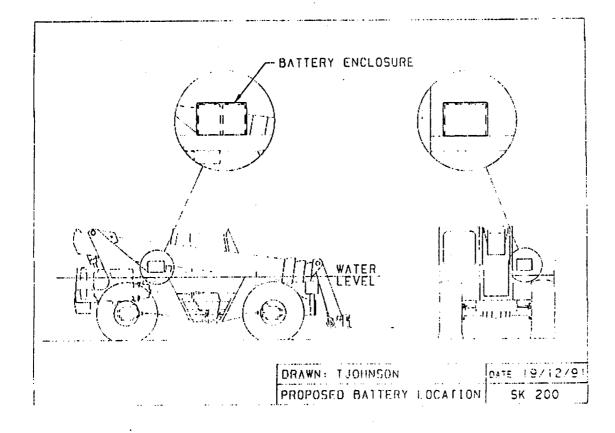


Figure 4.2.2.1-1 Battery Location



4.2.2.2 Harness Wiring. Waterproofing of the chassis wiring harnesses is central to the reliability of ATLAS.

<u>4.2.2.2.1 Cable.</u> SAE J1128 (special purpose, cross-linked, polyethylene cable, (SXL)) may be used on the chassis to provide a desirable abrasion resistance and meet fording requirements. Type SXL is a thermosetting material.

SAE J1128 (general purpose, thermoplastic, insulated cable (Type GPT)) may be used within watertight compartments. Type GPT cable is more flexible and workable than Type SXL for routing in tight quarters.

<u>4.2.2.2.2 Covering</u>. Chassis harnesses, exposed to the sea-water, will incorporate nylon braid covering providing supplemental abrasion resistance.

<u>4.2.2.2.3 Connectors.</u> A variety of connectors is commercially available to meet the ATLAS waterproofing requirements, including MIL-C-5015 (Caterpillar Environmental Connector (EC)), Canon Sure-Seal, Crouse-Hinds Water-Proof Connectors, and Glenair Series 22 Geo-Marine Connectors. The RT100 utilizes both the MIL-C-5015 and Canon Sure-Seal connectors.

<u>4.2.2.2.3.1 Engineering Considerations.</u> Space claims for bulkhead connectors may limit the applicability of Canon Sure-Seal and Crouse-Hinds Water-Proof connectors as these connectors are limited to 10 terminations. This limitation will lead to a high connector concentration between the chassis and watertight structures, particularly the cab.

MIL-C-5015 connectors, available from a number of suppliers including Canon and Deutsch, and the Glenair Series 22 Geo-Marine Connectors provide for increased number of terminations/connector to reduce connector concentrations (minimizing space claims). MIL-C-5015 connectors are considered the prime path for purposes of the fording evaluation; the Glenair and Crouse-Hinds provide viable commerciallyavailable alternate designs to fulfill the fording requirements.

For example considering the applicability of the Deutsch HD-30 and DT connectors a number of advantages are realized including:

- a) The maximum number of terminations of an HD-30 is 31, allowing a substantial reduction of connectors in critical areas.
- b) The HD-30 is a bulkhead connector.
- c) Both HD-30 and DT connectors are self-locking and require no external clips (required by the Canon Sure Seal and Crouse-Hinds Water-Proof connectors).
- d) Both HD-30 and DT connectors are environmentally sealed and meet MIL-STD-1344 (salt spray test method 1001).

<u>4.2.2.2.3.2 HD-30 Application</u>. This connector offers a sealed bulkhead mounting applicable for use in the critical cab to chassis interface and within the cab.

The HD series of connectors is constructed of heavy duty non-magnetic metal shell and is environmentally sealed with a current rating for No. 12 and No. 16 contacts of 35 amps and 16 amps maximum, applicable within a temperature range of -55 degree C to 125 degree C.

a) The HD-30 connector may be used at the cab to chassis interface. Using the RT100 as a basis, the number of bulkhead HD-30s would be 4.

x 14 way (No. 16 contacts) for signal wires;
 x 31 way (No. 16 contacts) for signal wires;
 x 8 way (No. 12 contacts) for power wires.

Alternately the RT100 uses 15 Sure-Seal connectors to accommodate 70 signal wires and 4 power wires.

b) The HD-30 connector can be employed is the fusepanel, dashpanel, and cab junction. Using the RT100 as a basis, the number of bulkhead HD-30s would be 4.

Cab to fusepanel: 1 x 21 way (4 No. 12 contacts, 17 No. 16 contacts) Cab to dashpanel: 1 x 14 way (No. 16 contacts) 1 x 23 way (No. 16 contacts)

Dashpanel to fusepanel: 1 x 21 way (4 No. 12 contacts, 17 No. 16 contacts).

Alternately, the RT100 uses 15 sure-seals to connect 57 signal wires and 5 power wires.

<u>4.2.2.2.3.3 DT Series Application.</u> The DT series connector would be most applicable in connecting the wiring harness to individual components (eg: headlights, joystick, etc.). With a size choice of 2, 3, 4, 6, 8, and 12 this connector is as versatile as the family of Sure-Seal connectors.

The DT series of connectors is constructed of a general purpose thermoplastic housings and environmentally sealed with a current rating of 13 amps for all contacts applicable within a temperature range of -55° C to 125° C.

<u>4.2.2.2.3.4 Sure-Seal Application</u>. Application of Sure-Seal connector may be limited by the applicability of the MIL-C-5015 connector. Alternately, expansion of the line of Sure-Seal connectors is a viable option.

<u>4.2.2.2.3.5 Crouse-Hinds Water-Proof Application</u>. Application of Crouse-Hinds Water-Proof connector may be limited by the applicability of the MIL-C-5015 connector. Alternately, expansion of the line of Crouse-Hinds Water-Proof connectors is not established.

ATLAS Fording Study

<u>4.2.2.2.3.6 Glenair Connectors.</u> Application of Glenair Series 22 Geo-marine Connector may be limited by the applicability of the MIL-C-5015 connectors. The Glenair connectors are available with a broad range of insert arrangements (diameter and terminations) up to 24-128.

4.2.3 Alternator. The alternator (24 volt) will provide an amperage that will be determined with maturation of ATLAS. Suppression may be required to meet the EMI requirements.

The water-resistant alternator if employed must be located above the splash zone, where as a waterproof alternator may be located without regard to the water level.

FMTV utilizes a CE Neihoff (Model S-216) alternator with an output of 100 amps that may be suitable for ATLAS. The fording capability of this unit has been demonstrated.

Alternately, Prestolite Electric and Leece-Neville offer waterproof alternators that fulfill the requirements of MIL-G-46795.

4.2.4 Starter. The starter must be waterproofed.

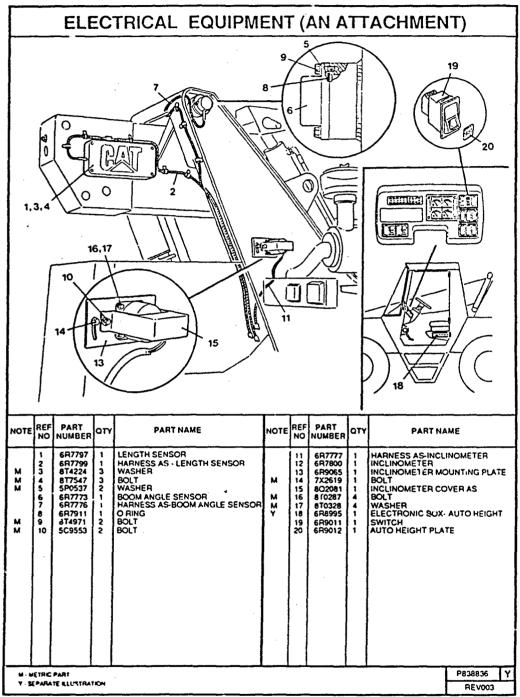
FMTV utilizes a waterproof Prestolite EO29404A electric starter suitable for ATLAS. The fording capability of this unit has been established.

4.2.5 Boom Control. ATLAS requires auto-height and auto-reach requiring minor modification to the electronic system currently used on the RT100 required to control the boom. The electrical system is comprised of:

Electronic Control Unit (ECU) Joystick Hydraulic Valve Manifold/Thermistor Boom Length Sensor Boom Angle Sensor Load Indicator Chassis Inclinometer/Tilt

ATLAS Fording Study

All external sensors (Figure 4.2.5-1) are mounted above the 60 inch water line and the sensors are environmentally sealed.



878836 AUTO HEIGHT/REACH GROUP

Figure 4.2.5-1 Sensor Locations

ATLAS Fording Study

<u>4.2.5.1 Electronic Control Unit.</u> The ECU will require a number of modifications to accommodate the ATLAS requirements as a result of or including:

- a) System Voltage. The change from a 12 volt system to a 24 volt system necessitates a modification to the power supply section of the ECU's printed circuit board.
- b) Machine Geometry. The envelope dimensions, weight, center-of-gravity, etc as well as load requirements will necessitate modification of the firmware.
- c) Boom Head Position. The articulated boom head would require sensors to monitor the position of the head. The head typically operates either fully up or fully down. If the head was in any intermediate position, auto height or auto reach would be disabled.

The ECU is located within the watertight cab beneath the seat of the operator. The ECU is environmentally sealed, providing redundant protection.

<u>4.2.5.2 Joystick.</u> The joystick is located within the watertight cab adjacent to and controlled by the right hand of the operator. The joystick is environmentally sealed, providing an additional level of redundant protection.

<u>4.2.5.3 Hydraulic Manifold/Thermistors.</u> The hydraulic manifold, solenoid valves, and thermistors will either be located in a watertight structure, relocated to a position above the waterline, or waterproof components will be identified.

<u>4.2.5.4 Sensors Boom Length</u>. The boom length sensors would be commercially available inductive proximity types. The units are environmentally sealed. The sensors would be mounted on the outer most section which would mean a cable reeling drum would be employed to interface between this section and the first section of the boom. The cable reeling drum would be located above the 5 foot water line and be environmentally sealed.

<u>4.2.5.5 Sensors Boom Angle.</u> The boom angle sensors would be commercially available inductive proximity types, and the units are again environmentally sealed. The sensors would, of course, be mounted on the fourth section which would mean a cable reeling drum would be employed to interface between this section and the first section of the boom. This unit would be fitted above the 5-foot water line and would be environmentally sealed.

ATLAS Fording Study

4.2.6 Instrumentation. Instrumentation will be environmentally sealed and located within a watertight cab. Current instrumentation is implemented with a open cab arrangement of the RT100. Minimum changes to the RT100 instrument package is required to meet ATLAS requirements.

Primary machine functions are implemented via rocker switches directly in front of the operator.

The RT100's instrumentation is compatible with a 24 volt electrical system and provides for monitoring of:

a) Engine coolant temperature

b) Engine oil pressure

c) Transmission oil temperature

d) Fuel level

and an indication of:

e) Alternator no charge f) Engine oil pressure low

g) Headlamp "High" beam

h) Crab steer engaged

i) Four wheel steer engaged

j) Turn signal left

k) Turn signal right

l) Manual mode (voom)m) Auto mode (voom)

n) Malfunction (ECU)

To fulfill the requirement of ATLAS a number of additional features including but not restricted to:

o) Speedometer

p) Blackout Switch

r) Rear Steering Pinned (Warning Lamp)

s) Closed Circuit Television and Operating Panel

t) Fording Switch (to activate water level sensor)

4.3 Performance.

The electrical system has minimum impact of ATLAS performance with respect to vehicle capacity, weight (total and distribution), fuel consumption, speed, vehicle height, and ground clearance.

4.3.1 Weight. Replacing the 12 volt electrical system with a 24 volt system has distinct weight advantages, i.e. a reasonable sized alternator, batteries, lighter gauge wire, etc., that will not otherwise compromise vehicle performance.

4.4 HFE/Safety.

Implementation of the electrical system is central to the safe and effective operation of the ATLAS vehicle under all operational scenarios in particular with respect to the feedback provided the operator.

Electrical connectors would be keyed to provide only a one-way interface between male and female connectors.

4.5 Reliability.

The reliability of the electrical system is the single facet of ATLAS that introduces substantial, though manageable, risk. A trivial amount of water can introduce an electrical short that will disable a circuit(s) of the system. Waterproofing of the electrical system is central to the reliability of ATLAS.

In general, electronic devices will be enclosed in a wate.proof structure. Electronic/ electrical devises that cannot be enclosed within a waterproof structure must be, at a minimum, water resistance and, preferably waterproof. Penetration of the waterproof structure will be via bulkhead connectors; hence, primarily wiring harnesses will be exposed to the salt water environment. These wiring harnesses shall be waterproof. The interface between the wiring bundle and the connector must be sealed to preclude the intrusion of water (weepage over time). Dummy plugs must be provided for each electrical connector that is used intermittently.

ATLAS Fording Study

4.5.1 Connectors. A variety of connectors are commercially available to meet the ATLAS waterproofing requirements, including MIL-C-5015, Canon Sure-Seal, Crouse-Hinds Water-Proof Connectors, and Glenair Series 22 Geo-marine Connectors. The RT100 utilizes both the MIL-C-5015 and Canon Sure-Seal connectors.

<u>4.5.1.1 MIL-C-5015 Connectors.</u> MIL-C-5015 connectors (Figure 4 5.1.1-1) are waterproof up to 1 bar (35 feet of water). For full environmental sealing, each connector is sealed completely with a sealing grommet. A specific sealing grommet is required for each shell design. In addition, wire hole fillers are recommended but not required. Alternately the wiring bundle may be potted for environmental sealing.

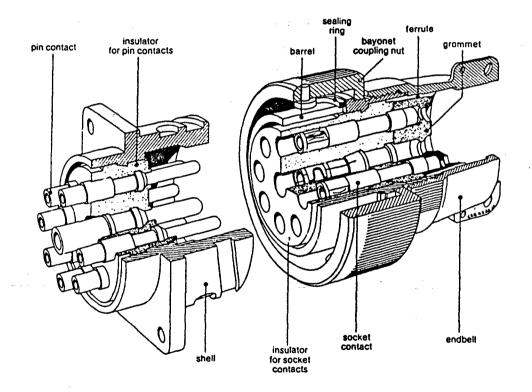


Figure 4.5.1.1-1 MIL-C-5015 Military Connector

Previous experience with MIL-C-5015 connectors has resulted in isolated problems with electrical shorts associated with weepage. The problem was resolved by removal of the sealing grommet and potting of the wiring bundle within the shell. Other connectors in the same environment performed satisfactorily.

<u>4.5.1.2 Canon Sure-Seal Connectors.</u> Canon Sure-Seal (Figure 4.5.1.3-1) connectors have replaced MIL-C-5015 connectors in military applications with fording requirements. Canon Sure-Seal connectors have been evaluated to depth of 3 feet immersed in a 5% salt solution to meet the minimum requirements of the FMTV program (Reference TACOM Part Number 12258940). Sure-Seal connectors provide a one-piece molded body with multiple moisture seals.

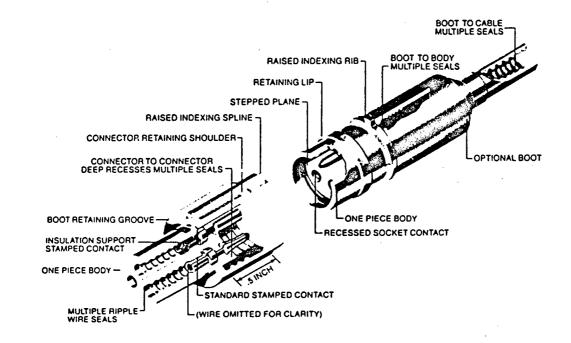
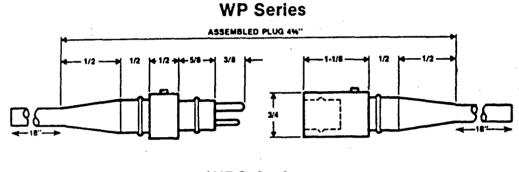


Figure 4.5.1.2-1 Canon Sure Seal Connector

Though evaluations have not been conducted at depths greater than 3 feet, no engineering limitations have been identified that would preclude consideration of these connectors for ATLAS. Though Sure-Seal connectors can withstand submersion, these connectors are not designed to be used as an underwater connector. The Crouse-Hinds Electro Water-Proof Connectors are designed for underwater applications.

ATLAS Fording Study

<u>4.5.1.3 Crouse-Hinds Electro Water-Proof Connectors.</u> Crouse-Hinds Electro Water-Proof Connectors (Figure 4.5.1.3-1) are designed to be a waterproof connector to a depth of 20,000 psi. The connectors are transfer molded from a specially compounded neoprene formula. The connectors are vulcanized directly to the cable to provide a positive seal at all pressures up to 20,000 psi. The connectors are available with underwater connect/disconnect capability. Locking sleeves are required.



WPS Series

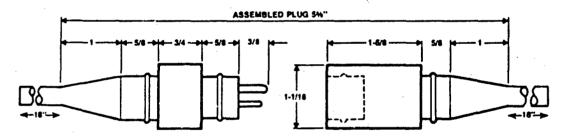


Figure 4.5.1.3-1 Crouse-Hinds Elector Water-Proof Connectors to provide positive retention.

ATLAS Fording Study

<u>4.5.1.4 Glenair Connectors.</u> The Glenair Series 22 Geo-Marine Connectors (Figure 4.5.1.4) are designed as waterproof connectors to a depth of 11,500 feet (5000 psi hydrostatic sealing capability). The Glenair connectors provide the watertight integrity of the Crouse-Hinds connector with the versatility of the MII-C-5015 Connectors.

Design Features

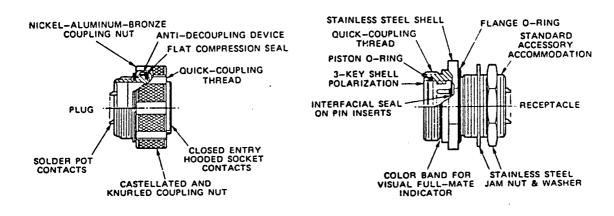


Figure 4.5.1.4 Glenair Series 20 Geo-Marine Connector

The connectors are available in a stainless steel (QQ-S-763, AISI 316L passivated per QQ-P-35) incorporating a flat compression seal and a piston O-ring (MIL-G-21569, Class 1) provides a watertight seal in conjunction with an interfacial seal for each pin contact insert. Pin and socket contacts are gold plated (per MIL-G-45204, Type II, Class 1) for maximum corrosion resistance. Molded cable-to-terminations with jackets of neoprene, polyurethane, or viton are available.

4.5.2 Electric Controls. Implementation of electric-over-hydraulic controls and electric control of the transmission are required to fulfill ATLAS reliability requirements in a salt water environment. The electric over hydraulic controls eliminate the mechanical linkages (with associated bearing surfaces and crevices) that would otherwise compromise the reliability of ATLAS.

ATLAS Fording Study

4.6 Producibility.

The primary producibility issue is associated with the growth in the number of part numbers, procurement, and assembly costs required to meet any ATLAS waterfording requirement.

4.6.1 Harness-Wiring. Typically a wiring harness penetrates a bulkhead (structure) via a cut/drilled hole with a rubber grommet installed. Waterproofing this harness arrangement necessitates that:

1) The grommet be replace by a bulkhead connector and

2) That the single wiring harness be redesigned as two wiring harnesses (in-board/out-board).

A water-resistant, inboard wiring harness will be adequate within the waterproof structure (Note that a waterproof harness would provide an additional level of redundant protection). Two connectors would typically be required for each harness though the bulkhead connector may be hard wired.

A water-proof, outboard harness shall be required for harnesses exposed to the salt water environment. Two connectors would again be required.

4.6.2 MIL-C-5015 Connectors. To be considered waterproof up to 1 bar, each connector incorporates a sealing grommet to provide the desired full environmental sealing. A specific sealing grommet is required for each shell design. In addition, wire hole filler are recommended.

Alternately the wiring bundle may be potted for environmental sealing. Wires entering the potting cup shall be grouped, centered, and retained with a double wrap of vinyl adhesive tape before potting. The shell shall then be assembled and tightened such that the assembly cannot be loosened by hand. The shell assembly shall be filled with epoxy leaving no voids for conductive paths. A rigid epoxy potting compound such as Armstrong Products Company C-4/D, Locktite Megabond, or 3M Company Scotchweld DP-100 must be used to secure wires in the connector. Coupling nuts must be free to rotate and lock wire holes must be free of any potting materials.



4.7 Cost Impact.

The various connectors, suggested as alternatives, increase in cost as the water tight integrity of the connector increases. The estimated increase in cost per vehicle for electrical/instrument sealing is \$1500. The specific time, frequency and depth of submersion will drive the connector requirements to achieve a seal with acceptable reliability.

4.7.1 Harness-Wiring. Redesign of single wiring harness as two wiring harnesses would increase the cost by a factor of two as the cost of a wiring harness is generally independent of harness length. The assembly costs may be unchanged if routing a comparatively long harness required substantial time.

The primary cost driver is associated with replacing an inexpensive grommet with a bulkhead connector. Assembly of the bulkhead connector will require more time than the grommet.

4.8 Integrated Logistic Support.

The potted MIL-C-5015 connector is more expensive to replace, but provides the positive seal necessary to insure high reliability in LOTS operations. Shorting of an electrical contact, depending on the device connected, could either reduce capability or render the system inoperable. The increase in maintainability costs, which are relatively minor, may be more than off-set by the overall increase in reliability of the electrical system.

The use of bulkhead connectors, to insure proper sealing of the cab, also would improve the maintainability of any wiring harness requiring replacement.

4.8.1 Serviceable Connectors. Only the MIL-C-5015 and Canon Sure-Seal connectors would be serviceable. The potted MIL-C-5015, Crouse-Hinds, and Glenair connector would be considered repair-by-replacement.

ATLAS Fording Study

Caterpillar Inc.

Paragraph 5.0 Suspension And Steering

5.1 Baseline Description.

The RT100 provides 3 steering modes and hydraulic steering. The vehicle suspension is provided by a combination of tires and a center pivot axle (walking beam). RTFLs normally travel on road up to 20 mph and have no additional elastic suspension.

5.1.1 Frame Leveling. The front axle is trunnion mounted to the frame and controlled by a single hydraulic cylinder to provide 12 degrees of frame tilt to either side (24 degrees total). This allows the chassis to be leveled on uneven terrain for greater lateral stability during high lifts. The frame should always be leveled before the boom is raised, but the frame should not be tilted once the boom has been raised.

The rear axle is also trunnion mounted to the frame, but it is free to oscillate 12 degrees to either side (24 degrees total). This improves traction and stability by helping to keep all four tires in contact with the ground on uneven terrain.

5.1.2 Steering. Both axles are steerable to provide three steering modes; 4-wheel counter steer, 4-wheel crab steer and 2-wheel front steer. These steering modes give the RTFL excellent maneuverability.

A three-position switch on the dash allows the operator to easily select the desired steering mode. The machine should be brought to a complete stop and the wheels aligned parallel to the chassis before changing steering modes. Indicator lights on the dash show when the circle or crab steer modes have been selected. If neither indicator light is illuminated, it means the machine is in the two-wheel steer mode.

ATLAS Fording Study

<u>5.1.2.1 Counter Steer.</u> In the counter steer or circle steering mode, the front and rear tires steer in opposite directions. Circle steering is used most frequently because it provides the tightest turning radius. Circle steer also enhances traction because the rear tires track in the ruts of the front tires.

<u>5.1.2.2 Crab Steer</u>. In the crab steering mode, all of the tires steer in the same direction. This causes the machine to move sideways as it goes forward or backwards, while still pointing straight ahead. Crab steering is useful for "sideshifting" the machine or when working close to a wall.

<u>5.1.2.3 Two-wheel Steer</u>. In the two-wheel steering mode or Ackerman steer, only the front tires steer, like an automobile. This mode is normally used only for driving the machine at higher speeds.

5.1.3 Power Steering. The power steering system is fully hydrostatic. Each axle has a single steer cylinder located above the axle for maximum protection. Double-acting cylinders provide synchronized movement, with equal effort and steering in both directions. Double-acting cylinders also allow a simplified linkage with just an adjustable tie rod on each end connecting the cylinder rods to the spindles.

Hydraulics for the power steering are supplied from the main hydraulic system through a priority valve that supplies flow based on demand. The steering gear has a hydraulic control valve and a metering section that permit manual steering in the event of an engine shutdown or a hydraulic system malfunction.

ATLAS Fording Study

Caterpillar Inc.

5.2 Alternative Design.

ATLAS on-road speed requirements necessitate the most substantial alterations to a commercial RTFL, specifically;

- a) Elastic suspension to accommodate 50 mph,
- b) Provide a means of locking out the suspension mode when the vehicle is used for boom motions, and
- c) Maintain a level frame capability.

Table 5.2 provide a synopsis of suspension elements with respect to various characteristics. A hydro-pneumatic suspension system with hydraulic cylinders and nitrogen over oil accumulators exhibits characteristics necessary to meet ATLAS speed requirements.

		COIL SPRING	TORSION BAR	LEAF SPRING	ELASTOMER SPRING	AIR SPRINGS	GASIOIL ACCUMULATOR	GAS/OIL STRUT
(1)	SQE	barge 5	large xmarcanx	međum	medum	međum	međum	
	WEIGHT	heavy	medum	heavy	light	i çhi	međum	നൽഗ്ന
	STROKE	good	good	međum	poor xxxxxxxxx	xxxxxxxxx	good	good
	SPRING RATE	good	boog	good	stfl srxxxxxxx	good	good	good
(2)	BUILT IN DAMPING			iow a	midum		good	good
(2)	BUILT IN LEVELING		NO NO		e minima		yes	yes
(7)	ACTIVE CONTROL			NO XIIIIIIIIIII	AD NO	NO XXXXXXXXXXXX	унс	yes
(4)	SUPPORT SYSTEMS	8	no	no	10	TITITITI	no	no
ନ	ADAPTIVE RATES		THE STATE	yes	yes	yes	yes	yes
(6)	ABLE TO BE TUNED						yes	yes
	NITIAL Cost	s high	high	high A	medium	međum	medum	
	COMPLEXITY	iow .	łow	łow	low	łow	nedun TETTTTT	high
	MAINTENANCE	low	iow	low	tow	low	medum	medum

NOTES:

1. Undesireable teatures are indicated by xxxxxxxxx 2. Any "built in" capability that is not present requires an additional mechanisim (e.g. shock absorbers)

- Active control indicates ability to be used with a power source and controller to actively reduce the chassis
 motion induced when manipulating the load.
- Support system indicates any system required in addition to typical variable reach fork lift systems.
- Adaptive rate indicates the inherent ability to maintain a constant natural frequency, regardless of
- upported weight.
- Ability to be tuned indicates easily varied spring and damping rates to best match machine configuration and operating conditions.

Table 5.2 Suspension Elements Evaluation

5.2.1 Requirements.

<u>5.2.1.1 Periodic Motion</u>. The elastic suspension is required to dampen the periodic motion yet provide compliance for roading. Periodicity is related to static deflection by:

t=2 (3.1416) (d/g) ^{1/2}

where: t = time to complete one oscillation in seconds d = static deflection in feet g = 32 ft/sec²

cr rewritten $p = (35230/d)^{1/2}$

The front axle is estimated to have a periodicity of 100 cycles/min with a deflection of 3.4 inches whereas the rear axle is estimated to have a periodicity of 80 cycles/min with a deflection of 2.18 inches.

<u>5.2.1.2 Curb-Clearance Circle.</u> The curb clearance circle as defined in SAF J695 shall be 34.5 feet, maximum.

5.2.2 Suspension-Travel. An elastic suspension on the front and rear axles is required to accommodate the on-road travel speed of 50 mph. Unsuspended RTFLs would experience severe pitch and bounce at speeds above 25 mph, and may cause the operator to lose control of the vehicle. This bounce and pitch motion is a result of out-of-round/ unbalanced tires, road roughness, and low damping of the tires.

Hydro-pneumatic (hydraulic/accumulator) and leaf spring were defined as prime paths early because each minimized space claims with respect to vehicle height. Secondly, hydro-pneumatic springs could also function to level frame.

ATLAS Fording Study

Ì

The hydro-pneumatic suspension provides a hermetically-sealed quantity of gas that is compressed by hydraulic oil according to the applied load. This suspension element will assume the role of a shock absorber by throttling the valves in the oil chamber. The hydro-pneumatic suspension provides the design latitude to tailor the spring rate and dampening characteristics of the element. The primary factors that influence these characteristics include accumulator volume, displaced volume of cylinder (area x stroke), and pressure (precharge, nominal, and maximum).

Leaf springs provide one or more laminations and can assume axle and wheel control functions. Primary factors that influence spring characteristics (per SAE J788 Manual on Design and Application of Leaf Springs) include active length of the spring, number, width and thickness of leaves, deflection, stress, etc.

<u>5.2.2.1 Suspension-Front Axle.</u> Four links (tie rods) will pin and locate the axle with respect to the chassis frame (per Figure 5.2.2.1-1). Three of the four links act as torque reaction members whereas the remaining link locates the axle in the transverse direction.

FRONT SUSPENSION

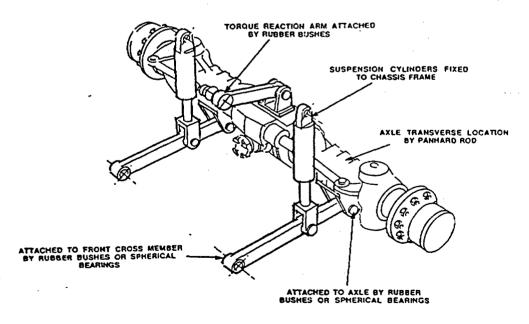


Figure 5.2.2.1-1 Front Axle Suspension

ATLAS Fording Study

Each link is fitted with rubber bushings or spherical bearings to accommodate required motion.

The chassis frame will be supported on the axle by two hydraulic cylinders (which also provide for frame leveling).

Referring to the hydraulic circuit Figure 5.2.2.1-2, the hydraulic cylinders are plumbed to nitrogen gas accumulators to provide an elastic spring. Each hydraulic suspension cylinder will be provided with an independent accumulator.

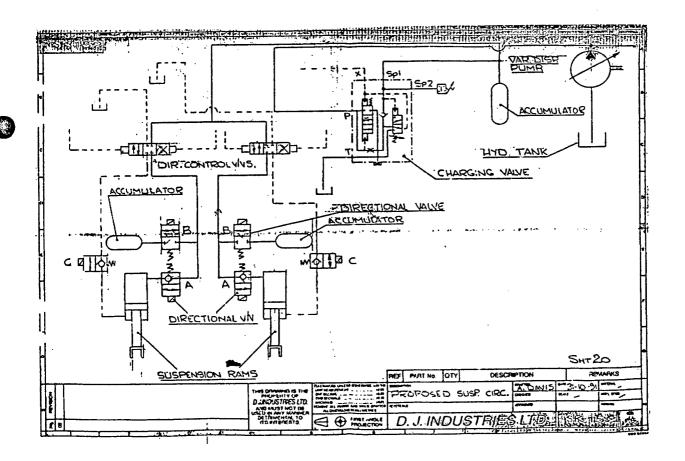


Figure 5.2.2.1-2 Hydraulic Circuit

To ensure a fast responding system, the hydraulic pump will supply a charge accumulator via a charging value.

The oil is then directed into independent control valves for each suspension cylinder.

These control valves could be either manual, pneumatic, electric or hydraulically pilot controlled to supply oil to the system.

1. With valve "A" energized as shown on diagram, the suspension mode is locked out.

2. With valve "A" and "B" energized, the suspension is in the highway mode.

3. Valve "C" provides roll stiffness by ensuring oil on the annular side of the suspension cylinder during highway mode.

4. To level frame, operate directional control valve to provide oil supply.

<u>5.2.2.1.1 Suspension-Front Axle (Alternate Design)</u>. Alternatively, a simpler mechanical front suspension per Figure 5.2.2.1.1-1 may be considered to replace the hydropneumatic suspension with leaf springs. Hydraulic cylinders are still required for frame level and locking out the leaf springs during RTFL operations.

The axle is mounted on leaf springs which are attached to a frame which can pivot relative to the chassis frame.

The springs are locked out in boom motion mode either mechanically or hydraulically. If dampers are required, these will dampen, bump stop, and lock out the springs.

One or two rams are attached to the pivoting frame and chassis frame to lock in high speed mode or frame level in boom motion mode.

Page 7

- 2

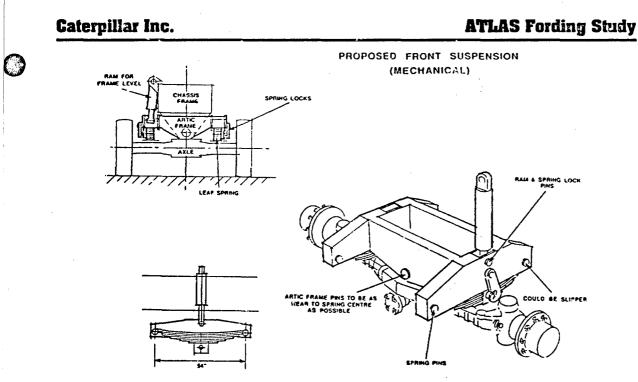
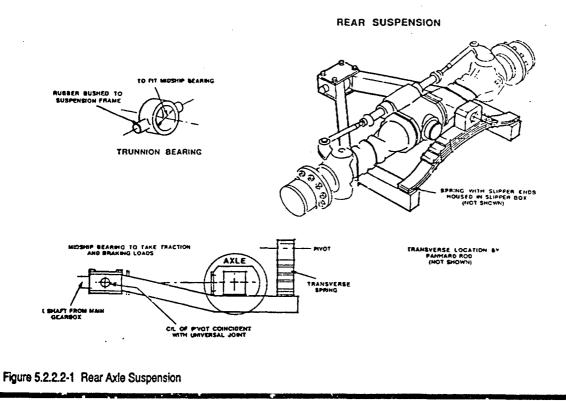


Figure 5.2.2.1.1-1 Alternate Design Front Axle Suspension

<u>5.2.2.2 Suspension-Rear Axle.</u> Figure 5.2.2.2-1 shows the rear axle suspension system. It is relatively simple because its worst case loading is during the travel mode.



Page 8

ATLAS Fording Study



The axle would be attached to the chassis by means of an A-frame which would take the traction and braking forces.

At the rear of the A-frame, a transverse spring is mounted which would be also mounted to a pivot under the chassis to provide 7.5 degree lateral movement.

<u>5.2.2.2.1 Suspension-Rear Axle Alternate Design</u>. The rear suspension could be either transverse spring or two rear springs similar to the front axle without the pivot frame.

5.2.3 Suspension-Working. As described in paragraph 5.2.2, in the working mode the elastic suspension of the front axle would be locked out to provide the stiff platform required for lifting operations.

5.2.4 Steering-Travel. ATLAS requirements for high-speed, on-road travel necessitates the addition of a mechanical, front wheel (Ackerman) steer and locking the rear wheels (rear steering) parallel to the centerline of the vehicle.

5.2.4.1 Mechanical Steering. The operator will steer the vehicle with the same steering wheel used for off-road steering. To transition from off-road to on-road travel (4x2 Mode) the operator would align the wheels parallel to the vehicle in any of the three steering modes. With the wheels straight the operator, would toggle a switch on the dash to lock out the rear (steering) wheels.

The mechanical system is comprised of a bevel box, steering box with an integral hydraulic cylinder (power assist), universal joint, and a steering rod pinned to the existing steering cylinder on the axle (Figure 5.2.4.1-1)



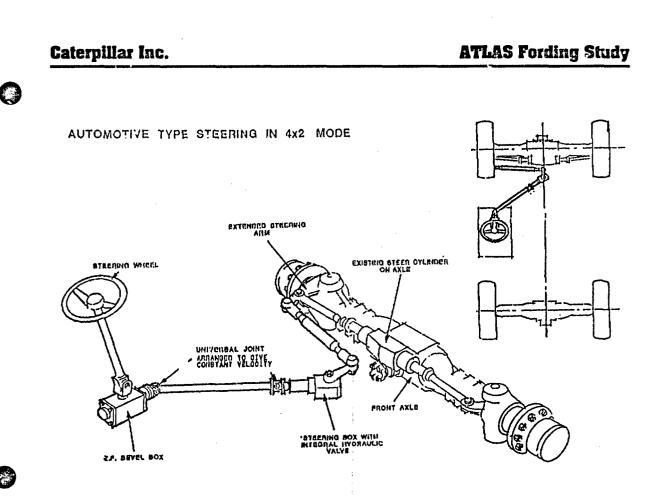


Figure 5.2.4.1-1 Mechanical Steering

<u>5.2.4.2 Rear Wheel Lockout</u>. Rear wheel lockout is necessary to operate ATLAS at the high speeds. The operator will toggle a switch to lock the rear steering. Alternately an automatic alignment feature may be considered (paragraph 5.2.4.1.1)

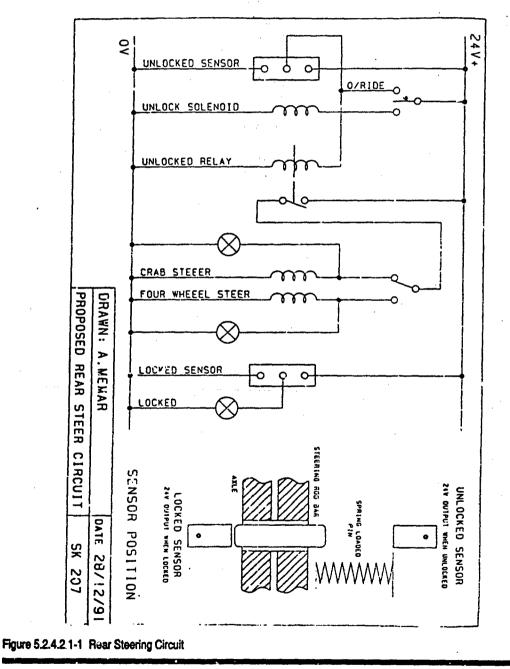
<u>5.2.4.2.1 Automatic Alignment</u>. An automatic rear steering alignment (Figure 5.2.4.2.1-1) could be incorporated by mechanically pinning a bar (which is linked by the steering rod) to the axle.

The toggle switch on the dash would be toggled to the LOCK position in any one of the three steering modes. The toggle switch would deactivate a spring applied, hydraulic-release solenoid valve and ride on top of a bar. Power would remain in the rear axle steering system until the pin re-extended. At that time the pin would lock the steering rod bar and axle (removing the rear steering) and switch the unlock sensor off.



Automatic alignment would provide a number of advantages including;

- a) Visual indication of both the locked and unlocked conditions,
- b) Rear steering would be disabled unless unlocked, and
- c) Override capability to release a jammed pin by momentarily applying power to the rear steering to "joggle" the pin free.



ATLAS Fording Study

5.2.5 Steering-Working. Three-steering modes, Ackerman, circle, and crab steer will be available on ATLAS and controlled from the operator dash via a switch by the operator.

<u>5.2.5.1 Ackerman Steer.</u> The curb-to-curb turning radius for the Ackerman steer is sensitive to tire size and lock angles per:

	Reduced						
Tire Sizc	Turning Circle	Lock Angle	Figure				
20.5Rx25	<i>52′</i> 0"	No	5.2.5.1-1				
20.5 Rx25	63'0"	Yes	5.2.5.1-2				
17.5 <i>R</i> x 25	35′6"	No	5.2.5.1-3				
17.5Rx25	51′6"	Yes	5.2.5.1-4				

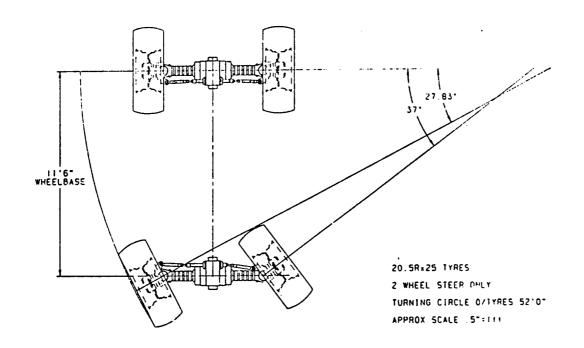
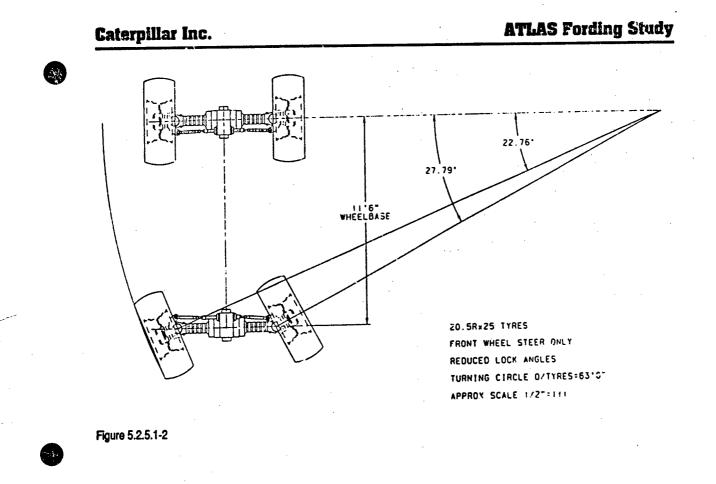


Figure 5.2.5.1-1

Page 12



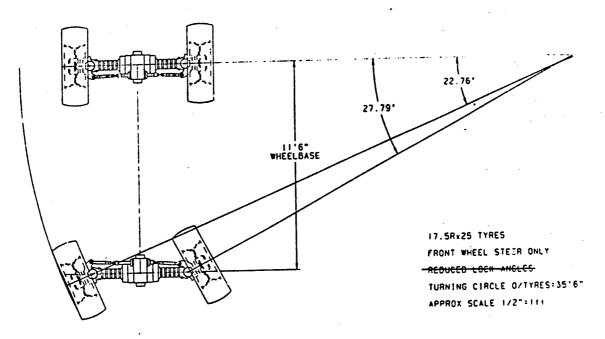




Figure 5.2.5.1-3

 \bigcirc

ATLAS Fording Study

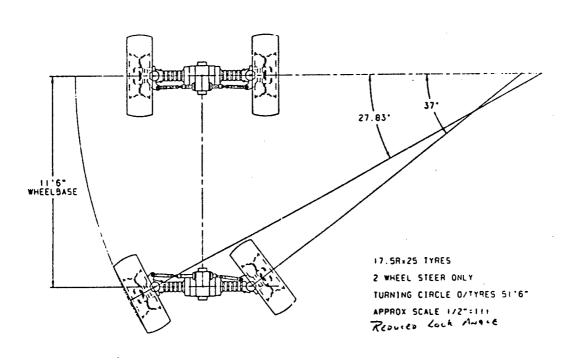
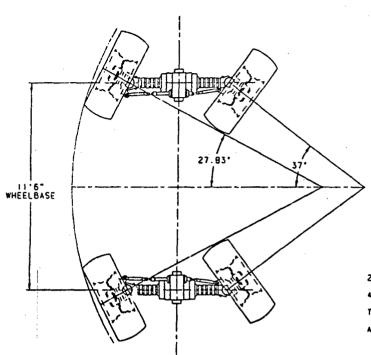


Figure 5.2.5.1-4

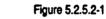
<u>5.2.5.2 Counter Steer.</u> The curb-to-curb turning radius for the counter steer is sensitive to tire size and lock angles per:

	Reduced						
Tire Size ·	Turning Circie	Lock Angle	Figure				
20.5Rx25	31′0"	No	5.2.5.2-1				
20.5Rx25	36'0"	Yes	5.2.5.2-2				
17.5Rx25	30′6"	No	5.2.5.2-3				
17.5Rx25	35′6"	Yes	5.2.5.3-4				

ATLAS Fording Study



20.58+25 TYRES 4 WHEEL STEER TURNING CIRCLE O/TYRES 31'0" APPROX SCALE .5"=111



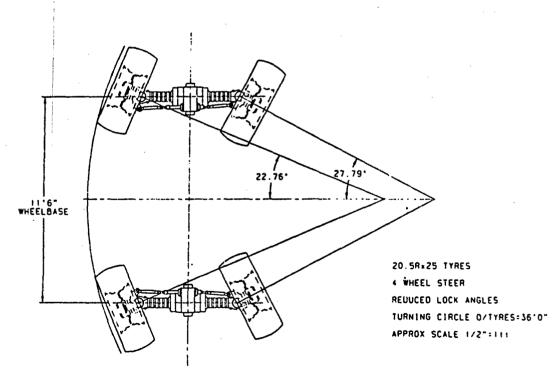


Figure 5.2.5.2-2

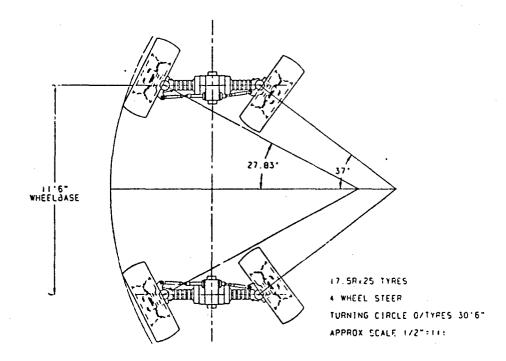
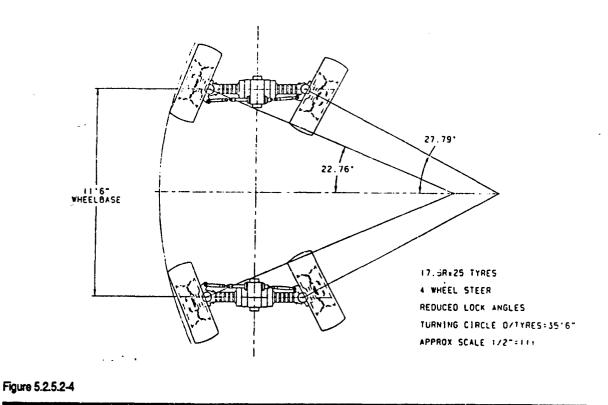


Figure 5.2.5.2-5





ATLAS Fording Study

5.2.6 Frame Level. The operator will be able to level the chassis frame in the lateral plane to approximately \geq 7.5 degrees from the cab. Leveling of the frame may be accomplished with the travel suspension locked.

5.2.7 Considerations-Corrosion. The structural elements of the suspension group and cylinders will be coated with the zinc-rich primer to provide the desired corrosion resistance.

Corrosion protection for the cylinder rods will be provided by chrome plate. The chrome must be of sufficient thickness (0.016 in. minimum after polishing) and uniformity to provide the desired level of protection. Adequate substrate hardness must be provided to minimize spalling of the chrome plate.

5.3 Performance.

An elastic suspension is required to meet ATLAS requirements for speed.

5.3.1 Capacity. Implementation of the hydro-pneumatic/leaf spring suspension does not compromise the capacity of the vehicle.

5.3.2 Weight (Total and Distribution). The elastic suspension adds substantial weight, approximately 2500 lbs., to the Gross Vehicle Weight (GVW). The weight is added low on the vehicle, lowering the Center of Gravity (CG).

5.3.3 Fuel Consumption. The elastic suspension increases fuel consumption only to the extent that it adds to the GVW.

5.3.4 Speed. The weight added by the elastic suspension is within the projected weight of ATLAS to meet the 50 mph requirement.

5.3.5 Vehicle Height. The vehicle height is very sensitive to the configuration and vertical space claim of the elastic suspension, hence strong space efficient leaf springs on the rear axle and dual-purpose, hydro-pneumatic springs on the front axle are desirable.

5.3.6 Ground Clearance. The ground clearance is not compromised by the suspension system.

ATLAS Fording Study

Caterpillar Inc.

5.4 HFE/Safety.

Implementation of an elastic suspension and the redundant mechanical steering system is critical to the safe and reliable operation of ATLAS at highway speeds.

5.4.1 Suspension. ATLAS convoy and dash speed requirements establish the requirements for suspension. The effectiveness of the ATLAS suspension can be documented with absorbed power and acceleration measurements that will identify ride quality.

Maturation of the ATLAS design could establish a requirement for a suspended seat at vehicle speeds above 20 mph.

5.4.2 Absorbed Power. Absorbed power measured in terms of watts is the descriptive parameter that correlates human response (comfort/performance) to a mechanical vibration. Absorbed power characterizes vibrations monitored in three planes which is the energy flow to and dampened by the human body. The energy flow is the result of the complex dampened, elastic properties of the human body.

ISO Standard 2631 establishes three levels of vibration exposure to define the human response in order of increasing severity:

i) Reduced Comfort Boundary,
 ii) Fatigue Boundary, and
 iii) Exposure Limit.

- *i) Reduced Comfort Boundary.* The vibration frequency, acceleration, and exposure time at which the operator experiences a reduction in comfort.
- *ii) Fatigue Boundary*. The fatigue boundary establishes the level at which the operator proficiency decreases (ie the vibration frequency, acceleration, and exposure time) at which time that there is a significant risk of impaired working efficiency.
- *iii) Exposure Limit.* The vibration frequency, acceleration, and exposure time at which there is a significant risk to Lealth and safety.

ATLAS Fording Study

5.4.3 Evaluation. The instrumented ATLAS will traverse a number of courses from 0.5 to 3 inch rms. The vehicle velocity is typically presented at each roughness condition (rms) when the power is 6 watts.

5.4.4 Acceleration. Acceleration, measured in terms of gravity (gs), is the descriptive parameter that correlates human response (performance) to a single shock load introduced as the vehicle encounters a bump.

Evaluation. The instrumented ATLAS will traverse a number of bump courses at various speeds. The bump is defined as a quarter or half-round radius. The vehicles velocity will be presented at each encounter when the acceleration is +/- 5 gs and plotted. The speed data will be plotted with respect to the bump diameter.

5.5 Reliability.

The suspension and steering group must be reliable, hence a reliability allocation of 10,000 hours for a mission critical failure is provided. The complexity of the system necessitates that individual components be exceedingly reliable.

5.5.1 Cylinders-Hydraulic. Reliability of the hydraulic cylinders is typically the primary source of unreliability as a result of oil leaks. Other than mechanical damage to the cylinder rod that damages the seals, most damage to the rod seals occurs due a third particle intrusion.

The fording environment provides a number of sources for 3rd particles. Corrosion products, resulting in pitting of the rod, are generated as a result of inadequate plating thickness. The 3rd particles, sand and debris, are suspended in the surf zone. Hydraulic cylinders (Figure 5.5.1-1) suitable for sustained fording operations required a wiper seal to prevent the 3rd particles from coming into contact with the rod seals.

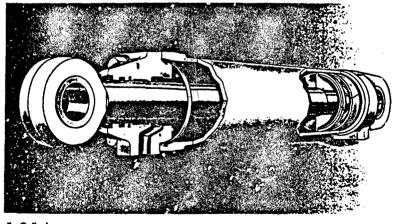


Figure 5.5.1-1 Hydraulic Cylinders

ATLAS Fording Study

Caterpillar Inc.

5.5.2 Springs-Leaf. To assure long term reliability, leaf springs must be inspected and lubricated on a regulation sis.

The relative motion of the leaf spring provides for a localized pumping action that will over a period of time result in erosion corrosion of the springs. The erosion rate will be aggravated by third particle wear.

The surf zone provides an unlimited source of abrasive third particles suspended in the water. The pumping action between the leaves of the spring provides the velocity for the localized erosion. Consideration may be given to replacement of the springs based upon number and duration of LOTS operation or based upon a specific (localized) reduction in leaf thickness.

The springs should be inspected for spalling of the CARC top coat and repaired as required.

5.5.3 Steering-Mechanical. The mechanical steering provides a redundant steering mechanism to the all-hydraulic system. This redundancy is central to achieving the desired mission reliability.

5.6 Producibility.

Other than the incremental costs associated with procurement and assembly of hydraulic cylinders, accumulators, carriage, and other elements of the hydraulic system, the suspension group is an assembly of off-the-shelf components tailored to the ATLAS requirements.

5.7 Cost Impact.

The cost increase associated with the more complicated suspension system required for the 50 mph road speed is approximately \$10,000. Two alternatives are offered for the front suspension (leaf spring or hydro- pneumatic) with the leaf spring representing a relatively high initial cost with low complexity and maintenance. The hydro-pneumatic suspension offers a lower initial cost, but higher complexity and maintenance costs. Three alternatives are offered for the rear suspension design (A-Frame, Transverse spring or rear springs). The A-Frame represents a higher cost, with correspondingly increased performance, from the alternative suspensions.

ATLAS Fording Study

5.8 Integrated Logistic Support.

All alternative suspensions offer proven designs with high reliability/availability. Leaf spring suspension may be more susceptible to reliability problems from third particle erosion when conducting LOTS operations. The hydro-pneumatic suspension, offering excellent performance, will generally be less reliable that simple leaf springs, but should be less susceptible to 3rd particle erosion. The slight increase in maintenance necessary should not have an appreciable effect on life cycle maintenance costs. All alternatives fit well within the maintainability and reliability requirements of MIL-T-53038 (ME).

ATLAS Fording Study

Paragraph 6.0 Powertrain

6.1 Baseline Description

The baseline description establishes the powertrain arrangement of the RT100 from which the alternative ATLAS designs evolve.

6.1.1 Transmission. The RT100 has a 4-speed full powershift transmission.

6.1.2 Transmission Controls. A single twist-grip control on the left side of the steering wheel allows the operator to change gears or direction easily. This electric control eliminates typical mechanical linkages for increased reliability and reduced maintenance. The control valve is externally mounted on top of the transmission for easy access and quick-disconnect pressure taps are provided to ease troubleshooting.

Full clutch modulation for all shifts increases durability and provides smooth gear shifts and directional changes. On-the-go power reversals can be made up to 5 mph (9 km/h) for increased productivity. Large diameter, high energy clutch packs provide excellent performance and long life.

A standard variable-output back-up alarm sounds whenever the transmission is shifted into reverse. Neutral start prevents starting the engine with the transmission in gear.

ATLAS Fording Study

6.1.3 Speed. Four speeds forward and reverse allow closer gear ratios for smoother shifts than competitive 3-speed transmissions. More speed ranges can also mean a faster top travel speed cr a lower first gear for better gradeability.

Gear	Direction	Ratio	Top Travel Speed
1st	Forward	4.00	4 mph (6 km/h)
2nd	Forward	2.17	7 mph (11 km/h)
3rd	Forward	1.20	12 mph (19 km/h)
4th	Forward	0.78	19 mph (31 km/h)
1st	Reverse	3.68	4 mph (6 km/h)
2nd	Reverse	2.00	7 mph (12 km/h)
3rd	Reverse	1.10	13 mph (21 km/h)
4th	Reverse	0.72	21 mph (33 km/h)

6.1.4 Transmission Lube and Cooling System. The large 30 qt (28 L) capacity lube system and a large plate-type oil cooler in the bottom of the radiator help keep oil temperatures low to increase transmission life. The oil is circulated by a gear pump which is externally mounted on the transmission for easier service access. The spin-on oil filter is shielded by a guard for protection from damage. A by-pass valve in the filter base ensures lubrication during cold starts or in case the filter gets plugged.

6.1.5 Transmission Interface. The transmission is remote-mounted from the engine in the middle of the chassis. A gear box provides the flywheel input for the transmission, a slight drop between the engine output and transmission input shafts and a centrally located hydraulic pump drive.

A torsional-damped drive shaft transfers power from the engine to the gear box. This shaft is connected to the engine and gear box with large rubber collars to isolate the transmission and gear box from the engine's torsional vibrations. Drive shafts with conventional universal joints connect the transmission to the drive axles.

Full-time 4-WD is standard. The identical front and rear axle ratios and equal size tires make a 4-WD disconnect unnecessary. However, tight turns on hard pavement should be minimized to extend tire tread life.

ATLAS Fording Study

6.1.6 Axles. The RT100 has planetary drive axles front and rear. The RT100 has a large axle to accommodate the vehicle weight and lift capacity. These double reduction axles have the initial gear reduction in the differential and the final reduction in the planetary hubs. The outboard planetary design reduces stress on the differential, axle shafts and axle shaft universal joints. In addition, it helps absorb shocks, and it reduces axle shaft wind-up and wheel chatter for continuous traction. It also provides a more compact differential housing which increases ground clearance.

Both axles have 4-pinion differentials. Distributing the torque through four gears instead of two reduces the gear loads for greater reliability and longer life.

The front axle differential lock increases traction by ensuring power is transferred to both front wheels. Normally, the differential allows the right and left wheels to turn at different speeds to reduce tire scrubbing when turning on hard surfaces. However, it also allows all the power to go to the tire with the least traction causing it to spin. The differential lock overrides normal differential operation and rigidly connects the two front wheels. The differential lock is actuated by a foot switch, and normal operation is restored when the switch is released.

6.1.7 Brakes. Both axles feature fully enclosed, inboard mounted, oil disc brakes. This design provides longer service life and reduced potential for contamination when compared to external disc brake or expanding shoe brake designs. Each axle has ten brake discs, with a total contact area of 338 sq in (2180 sq cm). With brakes on both axles, the brake system has a total of twenty brake discs with a total area of 676 sq in (4360 sq cm). Distributing the braking loads over such a large area helps reduce heat build-up and wear for longer brake life.

The RT100 provides full power brakes for excellent braking performance with low pedal effort. The hydraulic pump supplies pressurized oil to the brake system charge valve, which in turn stores oil in the accumulator at 2320 psi (160 bars). When the brake pedal is depressed, the power valve releases oil from the accumulator to actuate the brake discs in both axles. Pressure in the brake lines is proportional to brake pedal movement, so the further the brake pedal is depressed the harder the brakes are applied. The pressure in the brake lines is transmitted back to the brake pedal to give

Page 3

ATLAS Fording Study

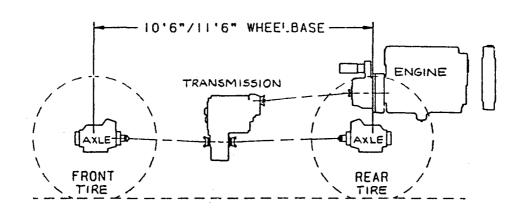
the operator "brake feel". The accumulator is normally recharged after each stop. If a system malfunction allows the pressure in the accumulator to fall to 1800 psi (124 bars), a warning buzzer alerts the operator. The accumulator can provide up to ten more stops after the buzzer sounds.

6.1.8 Brake-Parking. The hand-actuated parking brake mechanically actuates the service brake discs in the front axle. An interlock neutralized the transmission when the park brake is applied to prevent driving through the parking brake for longer brake life. There is an adjustment on the parking brake handle to compensate for cable stretch to make it easier to keep the parking brake adjusted properly.

6.2 Alternative Design.

ATLAS necessitates that the commercial powertrain be redesign to meet the speed requirements. Figure 6.2-1 provide approximate location of powertrain components and brief summary of requirements.

ATLAS Fording Study



MACHINE SPEC ALL TERRAIN VARIABLE REACH FORK LIFT TRUCK. MAX WIDTH 8'5" OR 9'0". WEIGHT 32250 Ib UNLADEN. WEIGHT 42250 Ib LADEN. ON ROAD SPEED (4x2) 50MPH UNLADEN. OFF ROAD PERFORMANCE (4×4) 2MPH UP 45% GRADE LADEN. OFF ROAD MAX SPEED 20/25MPH UNLADEN. ENGINE 6 CYL DIESEL TURBO-CHARGED. 247 HP AT 2400 RPM NET. POWER SHIFT TORQUE CONVERTOR WITH LOCK UP. TRANSMISSION 6 OR 8 SPEED. HYDRAULIC PUMP P.T.O. AXLES STEER/DRIVE-OIL IMMERSED BRAKES HUB REDUCTION, HYD/MECH STEERING. O/ALL RATIO ← 10 TO 1. MAX STATIC AXLE LOAD 44750 Ib: AT 50MPH 18000 16. IYRES 17.5x25 OR 20.5x25 PNEUMATICS. SINGLES. SUSPENSION ON ROAD- BOTH AXLES SPRUNG. OFF-ROAD- FRONT-RIGID, REAR-CENTRE PIVOT OR SPRUNG.

Figure 6.2-1 Powertrain Components Location & Summary of Requirements

Page 5

ATLAS Fording Study

6.2.1 Engine. ATLAS engine considerations are addressed in paragraph 2.0. To maintain universal joints speed below 3500 rpm, maximum engine speed is limited to 2610 rpm at (No Load) and 2400 rpm @ 270 HP.

6.2.2 Transmission. Various transmission arrangements have been reviewed with respect to ATLAS to meet the duty cycle with the 50 mph dash speed:

- a) Clark 3200 Series Transmission with CL320 Series Converter rated at 250 HP,
- b) Clark 3400 Series Transmission with 2-speed transfer case rated at 300 HP
- c) Allison MD 3070 World Transmission rated at 300 HP,
- d) Allison MD 3560 with 2-speed transfer case (w/retarder) rated at 300 HP,
- e) ZF Powershift Reversing Transmission rated at 300 HP.

Mounting of the transr. ission (remote or engine) will be determined with maturation of the ATLAS design.

<u>6.2.2.1 Clark Transmissions.</u> The Speed vs Tractive Force for each of the two transmissions (250 and 300 HP) arrangements are defined in Figure 6.2.2.1-1.

Clark provided a number of analyses of ATLAS powertrain that are submitted for review (Table 6.2.2.1 located at the back of this section).

-

ATLAS Fording Study

- - -

\·----

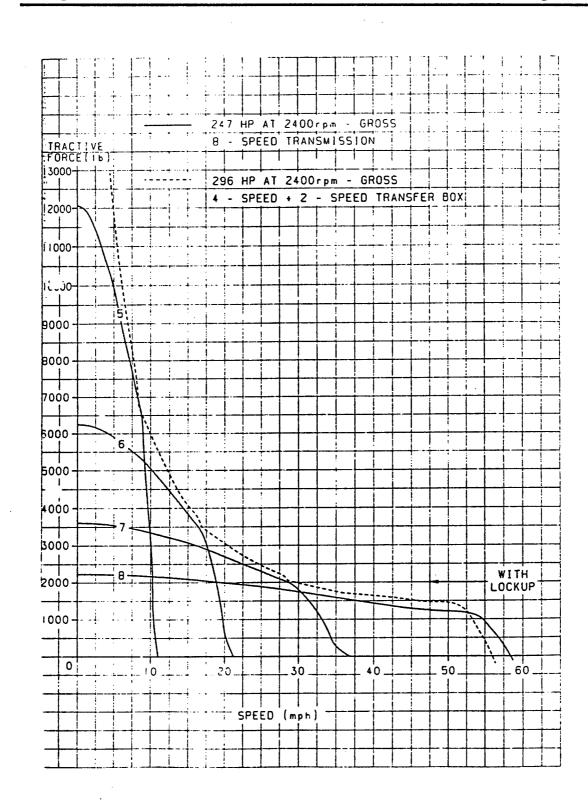


Figure 6.2.2.1-1 Clark Transmissions

Page 7

<u>6.2.2.2 Allison Transmissions.</u> The MD3070 WT Transmission used in the FMTV Program provides a 300 HP capability, but the range of gears 0.783 to 6.929 and the offset of the outputs are not suitable for RTFL applications. Alternately the MD3560 with as 2-speed transfer case may be suitable. This arrangement allows the use of a retarder to assist in braking from highway speeds.

Allison provided a number of analyses of the ATLAS powertrain. These are summarized in Figure 6.2.2.2-1 with Table 6.2.2.2-1 (located at the back of this section) providing supporting documentation.

, SCAAN REF	G.V.W. lbs	H.P.	DRIVELINE RATIO	TYRE SIZE	STALL GRADE	GRADE % @ 2 MPH 1st GEAR	GRADE % @ 2 MPH REVERSE
326077	42000	300	11.099	20.5 X 25	148	77	65
326078	42000	250	11.095	20.5 X 25	131	64	56
326079	42000	225	11.095	20.5 X 25	126	62	54
326080	42000	300	10.106	17.5 X 25	148	77	65
323447	42000	250	10.102	17.5 X 25	131	64	56
323449	42000	225	10.102	17.5 X 25	126	62	54

ATLAS 4 X 4

Figure 6.2.2.2-1 Allison Transmission Summary

<u>6.2.2.3 ZF Transmissions.</u> Insufficient data was submitted by ZF to establish the feasibility of this manufacturer's transmissions.

6.2.3 Axles. Any steerable axle selected for ATLAS requires modification to meet the steering and suspension requirements and are addressed within Section 5.0 of this report.

The maximum static and dynamic axle loads are projected to be 44,750 and 18,000 lbs respectively. Maximum dynamic loads are predicted to occur during 58 mph operations.

Page 8

ATLAS Fording Study

An overall powertrain ratio of 10:1 with 20.5Rx15 tires is required to provide the desired speed. Commercial axles will require modification to provide this powertrain ratio.

Final selection of the axle is required to consider vehicle width and transportability requirements. The Clark-Hurth 276 series axie provides the baseline axle arrangement for the C130 transportability study. Alternately Spicer has recommended the PS 1350 series axle. ZF and Rockwell have been solicited, but did not respond.

6.2.4 Braking. Viable brake options to meet the ATLAS operational requirements for fording were rapidly reduced to enclosed wet disc brakes.

Dry brakes, either caliper disc or drum brakes, are very sensitive to corrosion. In addition to corrosion, caliper disc brakes are totally exposed to a very abrasive environment that wears the pads and discs. Drum brakes typically implement a labyrinth seal to minimize ingestion of abrasive particles. Alternately, the same labyrinth seal would retain 3rd particles ingested during fording; again the drums and brake pads would abrade readily.

Enclosed brakes are offered on a variety of axle arrangements including Hurth (inboard disc) and Spicer (outboard disc). They are environmentally sealed hence braking performance is not compromised.

<u>6.2.4.1 Performance</u>. Braking performance is strongly influenced by the increased weight, speed, and braking efficiency of ATLAS over the commercial RTFLs. The heat dissipation properties of the brakes must be monitored with maturation of the ATLAS design.

Preliminary performance targets have been established for this study; Table 6.2.4.1-1 provide preliminary calculations. The service brakes should be able to decelerate the unladened vehicle at 14.5 ft/sec² from highway speeds with 45% efficiency requiring 15540 lbs brake torque per axle at the wheels.

Parking brakes should be able to hold a ladened and unladened vehicle on grades of 25% and 33% respectively. Figures 6.2.4.1-1 provide force requirements vs brake torque. Note that the brake torque required exceed capability of the commercial brakes with 12 discs and an applied force of 1300 lbs force.

The braking system at a minimum should provide for a dual circuit, hydraulically powered service brake and a spring-applied, hydraulically-released parking brake.

Page 9

FROM CLARK HARLOW

Table 6.2.2.1 H. 1100116.

CLARK Customer : BROWN DESIGN Approval no. BDE 3 Harlow Application : 5T BOOM LIFT TRUCK 29 NOV 91 sheet 1 of 4

pump drive ratio : 0.951 36.99 GPM @ 2000 rpm & 100.0 psi = 12.72 #' MAIN/STEER 21 GPH @ 2000 rpm & 250.0 psi = 12.00 #' charging pump Total non-std accessories : = 24.80 #'

P. 1

· .				(range	shift)	hgs
CAT	CL323.5 (1	TD) R28	825 ratios	: FWD	REV	
3116				9.94	9.94	
converter				5.16	5.16	
stall at				2.97	2.97	
477 #ft @2308	3			1.84	1.84	
				4.02	4.02	
				2.09	2.09	
				1.20	1.20	
				0.14	0.74	

Rotation : (pposite engine (transm. FWD-clutch engaged)

curb vehicle weight	3m.	32325 1bs	axle reduction : 9.250	1
gross vehicle weight	38	32325 1bs	rolling radius : 25.71 inch	
weight on drivers	*	32325 1bs 32325 1bs	tire slze: 20.5RX25	

Engine curve no. Net engine HP = gross HP less 10.0 % deduction for standard engine accessories Converter input torque = net engine torque less 24.80 \sharp' for non-std access. Engine overrun 10.0 % (1HP + .746 kW)

No load gov'd	engino	engine	engine	engine	converter
	RPM	Gross IIP	Net HP	Net Torçue	Input Torque
	2640	O	O	O	-24.8 4
Full load gov'd	2400 2200	247 341	222 217	485.6 #' 517.1 #'	460.8 #
	1800	213	192	559.4 #'	534.6 #'
	1500	181	163	571.9 #'	\$47.1 #'
Peak gross engine	torque =	635.4 #' at	: 1500 rpm		

SPEED=TURB.RPMx(25.71" ROL.RAD.)/(168xTR.RAT.x(9.250 A.R.)) TE=TURB.TQxTR.RAT.x(9.250 A.R.)x(80.0% EFF.)/(25.71" ROL.RAD.)

 * Max. speeds calculated assuming 20/1000 rolling resist., 10850.0 square in frontal area, air res. coeff: 0.000017 lbs per (MPH)squared per square in
 * Tractive effort and % grade are with converter at stall
 * § grade is calculated with gross train weight

ORÓS	S TRAIN WT	EMPTY VEHICLE	*	TRACTIVE	effort	S GRADE
Gear no $2 = 8$ Gear no $3 = 14$ Gear no $4 = 22$ Gear no $5 = 10$ Gear no $6 = 19$ Gear no $7 = 33$.40 mph .39 mph .27 mph .51 mph .67 mph .96 mph .48 mph .78 mph	4.40 mph 8.39 mph 14.27 mph 22.51 mph 10.67 mph 19.96 mph 33.48 mph 48.78 mph	******	29829 15466 8924 5519 12071 6257 3617 2232	lbs lbs lbs lbs lbs	209.9 51.6 26.5 15.2 37.8 17.6 9.2 4.9

Tractive effort required to slip wheels : (32325)x(0.60 coeff.) = 19395 lbs Converter efficiency at wheel slip in gear no 1 = 91.4 % (1.17 torque ratio) Stall tractive effort relationship to GVW : 29829/ 32325 = 0.923

THIS DOCUMENT IS FOR PERFORMANCE COMPARISON PURPOSE ONLY AND MUST NOT BE CONSIDERED AS APPROVAL OF COMPONENTS, ADAPTATION OR OPTIONS WHICH IS SUBJECT TO BRUGGE APPLICATION ENGINEERING REVIEW.

1999 - 1997 - 19**99 - 1**997 - 11.29.1991 29 NOV 91 sheet 2 of 4 ST BOOM LIFT TRUCK

1.201

. . . .

FROM CLARK HARLOW

Ϊ.

:

ł

13:45

Approval no. BDE 3 CLARK Components Europe

DRIVELINE DESCRIPTION

Engine		CAT	3116		247	НP	at	2400	rpm
		CL323.5	Thru	drive					
Transmission	1	R28825							

CALCULATED TOROUE CONVERTER PERFORMANCE Per curve no. PA13-18

Charging pump flow less an estimated flow of 3.5 GPM clutch pressure supply and converter lubrication equals the approximate oil flow to cooler

D +	Speed	Torque	Conv.	Con	verter	input	Conv	erter T	urbine	Conv.C	
Pt	ratio	ratio	eff.	RPM	TO #	НР	RPM	TQ 🦸	HP	GPM	HP 👻
no				2308	476.9	209.6	0	868.0	0.0	22.0	209.6
1	0.000	1.820	0.0			208.3	226	861.9	37.0	21.4	171.3
2	0.100	1.778	17.8	2257	484.7				71.5	21.0	135.7
3	0.200	1.725	34.5	2223	489.3	207.1	445	844.1			
ž	0.300	1.657	49.7	2201	492.2	206.2	660	815.5	102.5	20.8	103.7
Ē	0.400	1.575	63.0	2183	494.3	205.5	873	778.5	129.5	20.6	76.0
ž	0.458	1.529	70.0	2175	495.3	205.1	996	757.3	143.6	20.5	61.5
6				2171	495.8	204.5	1085	740.7	153.1	20.5	51.9
7	0.500	1.494	74.7			204.9	1302	690.5	171.1	20.5	33.8
8	0.600	1.392	83.5	2169	496.0			627.6	183.8	20.8	22.3
9	0.700	1.274	89.2	2197	492.6	206.1	1538			21.1	19.2
10	0.750	2.210	90.7	2232	488.2	207.4	1674	590.7	188.3		
11	0.800	1,144	91.5	2300	478.2	209.4	1840	547.0	191.7	21.9	17.8
12	0.850	<u>1.071</u>	91.0	2374	465.7	210.5	2018	498.8	191.6	22.7	18.9
	>0.867	1.046	90.6	2400	460.8	210.5	2080	481.9	190.9	23.0	19.7
		0.989	89.0	2444	427.4	198.8	2199	422.7	177.0	23.5	21.9
13	0.900				300.9	144.1	2389	259.7	118.1	24.3	26.0
14	0.950	0.863	82.0	2515			2495	125.5	59.6	24.9	21.5
15	0.970	0.758	73.5	2573	165.6	81.1					20.9
16	0.973	0.719	70.0	2582	141.7	69.7	2513	101.9	48.8	25.0	
17	1.020	0.000	0.0	2624	23.1	11.6	2677	0.0	0.0	25.5	11.6

*: Does not consider transmission mechanical efficiency

- Heat exchanger capacity required is minimum 30 % of maximum engine power or more when necessary to keep conv. outlet temp. between 80 and 120 deg C in all conditions (working, travelling, etc. in all ambient

temperatures). - It is not allowed to run the vehicle downhill faster than the maximum speeds indicated for each gear -see vehicle performance page(s).

FROM CLARK HARLOW

A

Approval no. BDE 3 <u>CLARK</u> Components Europe

29 NOV 91 theat 3 of 4 ST BOOH LIFT TRUCK

DRIVELINE DESCRIPTION

Transmission : R28825 Axle ratio : 9.250 Tire size : 20.5RX25	Rolling ra	dius :	25.71	in	(static,	loaded)

CALCULATED VEHICLE PERFORMANCE IN CONVERTER DRIVE

Grade based on GTW, assuming 20/1000 rolling resistance, 10850.0 square in frontal area, air res. coeff: 0.000017 lbs per (MPH)squared per square in

low range

	_					,						
		EAR NO			EAR NO			EAR NO				.4
	RAT	'IO = 9		RAT	10 = 5.		RATI	io = 2.		RAT	10 - 1.	840
Pt	SPEED		GRADE	SPEED	T.E.	GRADE	SPEED		GRADE	SPÉÉD	T.E.	GRADE
no	mph	lbs	\$	mph	lbs	•	mph	1bs	%	mph	ibs	•
1	0.0	29829		ð.o	15466	51.6	ð.o	8924	26.5	ð.o	5519	15.2
2	0.4	29617	202.0	0.7	15357	51.1	1.3	8861	26.3	2.0	5480	15.1
3	0.7	29006	182.8	1.4	15040	49.7	2.5	8678	25.6	4.0	5367	14.8
2 3 4	1.1	28025		2.1	14531	47.6	3.7	8384	24.6	3.9	5186	14.2
5	1.5	26754	137.0	2.8	13872	44.8	4.9	8004	23.4	7.9	4951	13.4
6	1.7	26025	126.8	3.2	13494	43.3	5.5	7786	22.6	9.0	4816	13.0
7	1.8	25455		3.5	13198	42.1	6.0	7615	22.1	9.8	4710	12.6
ŝ	2.2	23727	102.0	4.2	12303	38.6	7.2	7099	20.3	11.7	4390	11.6
5 6 7 8 9	2.6	21566		4.9	11182	34.5	8.6	6452	18.2	13.8	3991	10.3
10	2.8	20300	76.6	5.4	10526	32.1	9.3	6073	17.0	15,1	3756	9.5
11	3.1	18799	67.9	5.9	9747	29.3	10.2	5624	15.5	16.6	3478	8.6
12	3.4	17140	59.3	6.5	6887	26.3	11.2	5128	13.9	18,2	3172	7.6
ĞÖV>		16561	56.6	6.7	8587	25.3	11.6	4955	13.4	18.7	3064	7.3
13	3.7	14525	47.5	7.1	7531	21.8	12.2	4346	11.4	19.8	2688	6.1
14	4.0	8924	26.5	7.7	4627	12.4	13.3	2670	6.2	21.5	1651	2.8
15	4.2	4312	11.4	8.0	2236	4.9	13.9	1290	1.9	22.5	798	0.2
16	4.2	3503	8.9	8.1	1816	3.6	14.0	1048	- ī.i	22.6	648	ŏ.ō
17	4.5	ŏ	ŏ.ŏ	8.6	ō	0.0	14.9	0	ō.ō	24.1	0	0.0
	•••=	-		•••	•	••••		-	0.0		v	0.0
THEO	RETICA	L TRANS	SMISSIO	N SHIF	r point	S (TUR	BINE RP	M). EN	GINE A	T FULL	THROTT	LE
	1 > 3	2 1 23	270	2 > 3	3 1 22	30	3 > 4	1 22	10			
	2 < 2		170	3 < 2		90		1 13				
			•				_					
hir	nge											
	GI	EAR NO		GI	EAR NO	6	GE	AR NO	7	GE	AR NO	8
		[0 = 4.		RATI	10 = 2.	086	RATI	0 = 1.:	204		0 = 0.	
Pt	speed		GRACE	SPEED	T.E.		SPEED	T.E. (GRADE		T.E.	
	and and the	9 5	•	and the second s	4 4	•						

		mun ny			and the				1	62	AR NU	8
	RAT	$\mathbf{IO} = 4$.024	RATI	0 = 2.0	86	RATI	0 = 1.	204		0 = 0.	744
Pt	Speed	T.Z.	GRACE	SPEED	T.E. G		SPEED	T.E.		SPEED		GRADE
no	mph	- 1be	•	mph	155	•	mph 0.0	lbs		mph	lbs	
1	ð.o	12071	37.8	0.0		17.6	0.0	3612	9.2	5.0	2232	4.9
2	0.9	11985	37.5	1.8		17.5	3.1	3586	9.1	5.0	2216	4.8
23	1.8	11738	36.5	3.5	6085	17.1	6.1	3512	8.9	9.9	2170	4.7
4	2.7	11341	35.1	5.2	5879	16.4	9.1	3393	8.5	14.7	2097	4.4
5	3.6	10827	33.2	6.9		15.5	12.0	3239	8.0	19.4	2002	4.0
6	4.1	10532	32.1	7.9		15.0	13.7	3151	7.7	22.2	1947	3.7
7	4.5	10301	31.3	8.6			14.9	3082	7.4	24.2	1905	3.6
8	5.4	9602	28.8	10.3		13.5	17.9	2873	6.7	29.0	1775	3.0
89	6.3	8727	25.8	12.2			21.1	2611	5.8	34.2	1614	2.0
1Ō	6.9	8215	24.1	13.3		11.1	23.0	2458	5.3	37.2	1519	1.9
11	7.6	7607	22.0	14.6		10.1	25.3	2276	4.7	40.9	1406	
12	8.3	6936	19.8	16.0	3596	ð.ð	27.7	2075	4.0	44.9	1282	1.4
ĞÕV>	8.6	6702	19.0	16.5	3474	8.6	28.6	2005	3.7	46.3	1239	
13	9.0	5878	16.3	17.5	3047	7.3	30.2	1759	2.9	48.9	1233	0.6
14	9.8	3611	9.2	19.0	1872	3.6	32.9	1080			1087	0.0
15	10.3	1745	3.3	19.8	905	0.6	34.3	1000	0.7	53.2	668	0.0
16	10.3	1417	2.3	19.9	735	0.0	34.5	522	0.0	55.5	323	0.0
17	11.ó	Ő	ō.ō	21.2	0			424	0.0	55.9	262	0.0
	44.0	•	0.0	61.4	v	0.0	36.8	0	0.0	59.6	0	0.0
THEOD	TTON	. TOANC	NTOOTA	N GUTOT	POINTS	/ 110					Denne a ma n	_
11001	5 > 6	5 . 99	70	6 > 7	: 2230	(TOK)		N), ENC	INE A	T FULL	THROTT	LE
	6 < 9		20	7 < 6			7 > 8 8 < 7					
				0	* ***		0 < 7	1 136	30			

211、29、1991 13:47 P. 4

FROM CLAPK HARLOW

•

A

Approval no. BDE 3 CLARK Components Europe

29 NOV 91 abeat 4 of 4 ST BOOM LIFT TRUCK

DRIVELINE DESCRIPTION

Engine Converter		CAT CL323.5	3116 Thru drive		HP	at	2400	rpm	· .	
Transmission	:	R28825	Inte deive							
Axle ratio Tire size	-	9.250 20.5RX25	Rolling r	adius	3 :	2:	5.71 :	Ln	(Static,	loaded)

CALCULATED VEHICLE PERFORMANCE IN LOCKUP

S Grade based on GTW, assuming 20/1000 rolling resistance, 10850.0 square in frontal area, air res. coeff: 0.000017 lbs per (MPH)squared per square in

low range

	GEAP. NO 1 Ratio = 9.944			GEAR NO 2 RATIO = 5.156			GEAR NO 3 RATIO = 2.975			GEAR NO 4 RATIO = 1.840		
Turb	SPEED		GRADE				SPEED		GRADE	SPEED T.E. GRADE		
		1bs			lbs	8		lbs			lba	6
RPM	mph			mph			mph			mph 13.5		2 -
1500	2.5	18535	66.4	4.8	9611	28.8	8.3	5545	15.3	13.5	3430	8.5
1680	2.8	18306	65.2	5.4	9491	28.4	9.3	5477	15.1	15.1	3387	8.4
1860	3.1	17801	62.6	6.0	9230	27.5	10.3	5326	14.6	16.7	3294	8.1
2040	3.4	17090	59.1	6.5	8861	26.2	11.4	5113	13.9	18.4	3162	7.6
		16261	55.2	7.1	8432	24.8	12.4	4865	13.1	20.0	3009	7.1
2220	3.7											
2400	4.0	15172	50.3	7.7	7867	22.9	13.4	4539	12.0	21.5	2807	6.4
2448	4.1	13809	44.6	7.9	7160	20.5	13.6	4131	10.7	22.0	2555	5.6
2496	4.2	10944	33.6	8.0	5675	15.7	13.9	3274	8.0	22.5	2025	4.0
2544	4.2	7411	21.4	8.2	3843	9.9	14.2	2217	4.7	22.9	1371	1.9
2592	4.3	3210	7.9	ě.3	1665	3.1	14.4	960	0.8	23.3	594	0.0
2640	4.4	-1658	0.0	8.5	-860	ŏ.ō	14.7	-496	ŏ.ŏ	23.8	-307	0.0
2040	4.4	-1020	0.0	0.5	-200	0.0	4411	-470	0.0	***	-307	0.0
		OROSS	TRAIN	WT	EMPTY V	EHICLE			Max	speed	in	
Gear	no 1		16 mph		4.36	mph	*			-		
Gear			19 mpl		8.39		*					
	=	- 14 4	18 mph		14.48		*					
Gear							*					
Gear	no 4	a 23.2	24 mph		23.24	mpn	*					

hi re						·				
		R NO 5	GEAR NO			RNO 7		GEAR NO 8		
	RATIC	= 4.024	RATIO = 2.0	086	RATIO	= 1.204	RATIO = 0.744			
Turb	SPEED	T.E. GRADE	SPEED T.E.	GRADE	SPEED	T.E. GRADE	SPEED	T.E. G	RADE	
RPM	mph	lbs 🔪	mph lbs	8	mph	lbs %	mpn	lbs	*	
1500	6.2	7501 21.7	11.9 3888	10.0	20.6	2244 4.7	33.4	1387	1.6	
1680	6.9	7408 21.4	13.3 3840	9.8	23.1	2216 4.5	37.4	1370	1.4	
1860	7.7	7204 20.7	14.8 3734	9.5	25.6	2155 4.3	41.4	1332	1.i	
2040	8.4	6916 19.7	16.2 3585	9.0	28.0	2069 3.9	45.4	1279	ō.7	
2220	9.1	6580 18.6	17.6 3411	8.4	30.5	1969 3.5	49.4	1217	0.3	
2400	9.9	6139 17.2	19.0 3183	7.7	33.0	1837 3.0	53.4	1135	0.0	
2448	10.1	5588 15.4	19.4 2897	6.8	33.7	1672 2.5	54.5	1033	õ.õ	
2496	10.3	4429 11.7	19.8 2296	4.9	34.3	1325 1.4	85.S	819	ŏ.ŏ	
2544	10.5	2999 7.2	20.2 1555	2.6	35.0	897 0.1	56.6	555	0.0	
2592	10.7	1299 2.0	20.6 673	ō.o	35.6	389 0.0	\$7.7	240	0.0	
2640	10.9	-671 0.0	21.0 -348	0.0	36.3	-201 0.0	58.7	-124	0.0	
		GROSS TRAIN	WT EMPTY V	FUTCLE		Max	speed	1.2		
Gear	-		10.73			1100	abeed	411		
Gear				i mph	*					
Gear			20.55) mph	*					
		52.34 mph			*					
Gear	10 0 -	52.34 mph	52.34	ւ աթո	-					

Lock-up to be engaged and disengaged at 2013 turbine RPM when engine is at full throttle.

FRUN CLARK HARLOW

the second s

12. 2.1991 14:51

CLARK
HarlowCustomer : BROWN DEEIGN
Application : ST BOOH LIFT TRUCKApproval no. BDE 3
2 DEC 91 sheat 1 of 6pump drive ratio : 1.000
36.99 GPM @ 2000 rpm & 100.0 psi = 12.10 #' MAIN/STEER
31 GPM @ 2000 rpm & 250.0 psi = 16.96 #' charging pump
Total non-std accessories : = 29.06 #'

·/ NE PARA

15.5LHR34414 (full powershift) ratios : FWD REV CAT 5.32 3116 5.32 2.86 2.62 transferodae converter 1.51 1.51 stall at 0.86 0.86 648 #ft @1774

> ratios : 1.90 0.90

11.00

P. 1

Rotation : opposite engine (transm. FWD-clutch engaged)

curb vehicle weight gross vehicle weight	-	32325 lbs	axle reduction : 9.250 rolling radius : 25.71 inch	
weight on drivers	=	32325 1bs	tire elze: 20.5RX25	
gross train weight	-	32325 1bm		

Engine curve no. Net engine HP = gross HP less 10.0 % deduction for standard engine accessories Converter input torque = net engine torque less 29.06 #' for non-std access. Engine overrun 10.0 % (1HP \clubsuit .746 kW)

No load gov'd	engine RPM 2640	engine Grose HP O	engine Net HP O	engine Net Torque O	converter Input Torque
Full load gov'd	2400	296 285	266 257	582.8 #' 612.4 #'	553.7 #* 583.4 #*
	1800 1500	256 222	231 200	673.4 #* 699.3 #*	644.3 #* 670.2 #*
Peak gross engine	torque =	-777.0 #' at	: 1500 rpm		

Max. speeds calculated assuming 20/1000 rolling resist., 10850.0 square in frontal area, air res. coeff: 0.000017 lbs per (MPH)squared per square in
 Tractive effort and % grade are with converter at stall
 % grade is calculated with gross train weight

GROSS TRAIN WT	EMPTY VEHICLE	٠	TRACTIVE	EFFORT	• GRADE
Transfercase ratio : 1.900 Gear no 1 = 4.32 mph	4.32 mph		40300		INF.
Cear no 2 = 8.58 mph	8.58 mph		20146	1b s	75.6
Gear no $3 = 14.89$ mph	14.89 mph	*	11466	lbs	35.5
Gear no $4 = 25.54$ mph	25.54 mph	*	6516	lbs	18.5
Transforcase ratio : 0.900					
Gezr no $1 = 9.04$ mph	9.04 mph		19089	lbs	69.5
Gear no $2 = 17.78$ mph	17.78 mph		9543	lbs	28.6
Gear no $3 = 30.23$ mph	30.23 mph		5431		15.0 °
Gear no $4 = 49.41$ mph	49.41 mph	*		155	7.6

Tractive effort required to slip wheels : $(32325)\times(0.60 \text{ coeff.}) = 19395$ lbs Converter efficiency at wheel slip in gear no 1 = 85.4 % (0.92 torque ratio) Stall tractive effort relationship to GVW : 40300/ 32325 = 1.247

THIS DOCUMENT IS FOR PERFORMANCE COMPARISON PURPOSE ONLY AND MUST NOT BE CONSIDERED AS APPROVAL OF COMPONENTS, ADAPTATION OR OPTIONS WHICH IS SUBJECT TO BRUGGE APPLICATION ENGINEERING REVIEW.

1. S. C. S.

Approval no. BDE 3 CLARK Components Europe

2 DEC 91 sheet 2 of 6 ST BOOM LIFT TRUCK

DRIVELINE DESCRIPTION

•

Engine : CAT Transmission : 15.5LHR34414 3116

296 HP at 2400 rpm

CALCULATED TOROUZ CONVERTER PERFORMANCE Per curve no. PA15-6

Charging pump flow less an estimated flow of 5.5 GPM clutch pressure supply and converter lubrication equals the approximate oil flow to cooler

Pt	Speed	Torque	Conv.	Con	verter	input	Conv	verter 1	urbine	Conv.C	ooling
no	ratio	ratio	eff.	RPM	TQ #'	ĤΡ	RPH	TQ #"	HP	GPM	HP 👬
1	0.000	1.780	0.0	1774	647.5	218.7	0	1152.6	0.0	22.0	218.7
2	0.100	1.731	17.3	1752	650.1	216.8	175	1125.2	37.5	21.6	179.3
3	0.200	1.675	33.5	1732	652.2	215.0	346	1092.5	72.0	21.3	143.0
4	0.300	1.613	49.4	1711	654.4	213.2	513	1055.5	103.2	21.0	110.0
5	0.400	1.548	61.9	1691	656.4	211.3	676	1016.1	130.9	20.7	80.5
Ĝ	0.466	1.503	70.0	1679	657.6	210.2	782	988.5	147.1	20.5	63.1
7	0.500	1.476	73.8	1673	658.1	209.6	836	971.4	154.7	20.4	54.9
8	0.600	1.388	83.3	1656	659.6	208.0	994	915.5	173.2	20.2	34.8
ĝ	0.650	1.329	86.4	1670	658.3	209.4	1086	874.9	180.9	20.4	28.5
10	0.700	1.267	88.7	1700	655.5	212.2	1190	830.5	188.2	20.9	24.0
11	0.750	1.197	89.8	1736	651.8	215.4	1302	780.2	193.4	21.4	22.0
12	0.800	1.129	90.3	1785	646.2	219.6	1428	729.6	198.3	22.2	21.3
13	0.850	1.062	90.3	1843	638.8	224.1	1566	678.4	202.3	23.1	21.8
14	0.900	0.978	88.0	1970	620.0	232.5	1773	606.4	204.7	25.0	27.9
15	0.950	0.856	81.3	2368	558.4	251.7	2249	478.0	204.7	31.2	47.0
	>0.951	0.849	80.8	2400	\$53.7	253.0	2283	470.2	204.4	31.7	48.6
16	0.963	0.727	70.0	2531	321.1	154.8	2438	233.4	108.3	33.7	46.4
17	1.015	0.000	0.0	2620	44.0	22.0	2659	0.0	0.0	35.1	22.0

*: Does not consider transmission mechanical efficiency

- Heat exchanger capacity required is minimum 30 % of maximum engine power or more when necessary to keep conv. outlet temp. between 80 and 120 deg C in all conditions (working, travelling, etc. in all ambient temperatures).
 It is not allowed to run the vehicle downhill faster than the maximum speeds indicated for each gear -see vehicle performance page(s).

S.

Approval no. BDE 3 CLARK Components Europe

and series and the state of the

2 DEC 91 sheet 3 of 6 5T BOCH LIFT TRUCK

DRIVELINE DESCRIPTION

Ingine : C		296 HP at 2400 rpm	
Transmission : 1 Axle ratio : Tire size : 2	9.250	Transfercase ratios : 1.900 0.900 Colling radius : 25.71 in (Static, 1.	Obdeda

CALCULATED VEHICLE PERFORMANCE IN CONVERTER DRIVE

S Grade based on GTW, assuming 20/1000 rolling resistance, 10850.C square in frontal area, air res. coeff: 0.000017 lbs per (MPH) squared per square in

transfercase ratio : 1.900

у." Г. 1

				GEAR NO 2			G	EAR NO	3	GEAR NO 4		
	· RAT	10 = 5	.325	RAT	IO = 2.	662	RAT	10 = 1.	515		10 = 0.	861
Pt	SPEED	T.E.	GRADE	SPEED	T.E.	GRADE	SPEED		GRADE	SPEED		GRADE
no	mph	lbs	۲.	mph	lbs	•	mph	1b s		mph	lbs	8
1	ð. 0	40300	INF.	0.0	20146	75.6	δ.ο	11466	35.5	0.0	6516	18.5
23	0.3	39343	INF.	0.6	19668	72.8	1.0	11193	34.5	1.8	6361	18.0
3	0.6	38199	INF.	1.1	19096	69.5	2.0	10868	33.3	3.5	6176	17.4
Ă	0.8	36904	INF.	1.7	18449	66.0	3.0	10500	32.0	5.2	5967	16.7
ŝ	1.1	35527	INF.	2.2	17760	62.4	3.9	10108	30.6	6.8	5744	15.9
	1.3	34563	INF.	2.6	17278	60.0	4.Ś	9834	29.6	7.9	5589	15.4
6 7	1.4	33964	INF.	2.7	16979	58.5	4.8	9663	29.0	8.5	5492	
é	1.6	32009	400.3	3.3	16001	54.0	5.7	9107	27.1			15.1
89	1.8	30591	245.9				5.7			10.1	5175	14.1
10	1.9	29038	183.7	3.6	15292	50.8	6.2	8703	25.7	11.0	4946	13.3
10				3.9	14516	47.5	6.8	8262	24.2	12.0	4695	12.5
11	2.1	27278	145.3	4.3	13636	43.9	7.5	7761	22.5	13.2	4411	11.6
12	2.3		120.3	4.7	12752	40.4	8.2	7258	20.9	14.4	4125	10.7
13	2.6		101.9	5.1	11858	37.0	9.0	6749	19.2	15.8	3835	9.8
14	2.9	21201	82.4	5.8	10599	32.3	10.2	6032	16.8	17.9	3428	8.4
15	3.7	16712	57.3	7.4	8355	24.5	12.9	4755	12.7	22.8	2702	6.1
GOV>	3.7	16440	56.0	7.5	8219	24.1	13.1	4677	12.5	23.1	2658	5.9
16	4.0	8160	23.9	8.0	4079	10.6	14.0	2322	5.1	24.7	1319	1.7
17	4.4	0	0.0	8.7	0	0.0	15.3		0.0	26.9	ō	Ö.Ö
THEAT	SPUT Cat	TOANC	VICOTON		DOTNO	C / T(1))	DTNE Br				-	
AUDU	1 > 2		HISSION	antra	L FOINI	5 (108	DINC KE	TI, EN	GINE A	T FULL	THROTT	نتابا
				2 > 3	3 : 22		3 > 4					
	2 < 1	L T - 1 1	.50	3<2	2 r 13	00	4 < 3): 13	UQ			

Approval no. BDE 3 CLARK Components Europe

2 DEC 91 sheet 4 of 6 5T BOOH LIFT TRUCK

F. 4

DRIVELINE DESCRIPTION

LEAST MARLUM

.

1.10 - 21.1

Engine			296	HP (t 240	0 rpm		
Transmission Axle ratio		Transfer				1 000	0.900	
	20.5RX25	Rolling r					(Static,	(babsol

121 211981 114450

15

CALCULATED VEHICLE PERFORMANCE IN CONVERTER DRIVE

% Grade based on GTW, assuming 20/1000 rolling resistance, 10850.0 square in frontal area, air res. coeff: 0.000017 lbs per (MPH)squared per square in

transfercase ratio : 0.900

	GEAR NO 1				AR NO 2		EAR NO		GEAR NO 4		
	RAT	IO = 5.	. 325	RATI	0 = 2.662	RAT	'IO = J.	515	RAT	0 = 0 .	861
Pt	SPEED	T.E.	GRADE	SPEED	T.E. GRAD	SPEED	T.E.	GRADE	SPEED	T.E.	GRADE
no	mph	lbs	•	mph	lbs N	mph	lbs		mph	lbs	4
1	ð.o	19089	69.5	٥.٥	9543 28.	5 d.o	5431	15.0	δ.ο	3087	7.6
2	0.6	18636	67.0	1.2	9316 27.0	3 2.1	5302	14.6	3.7	3013	7.3
3	1.2	18094	64.1	2.4	9045 26.9		5148	14.1	7.4	2926	7.0
4	1.8	17481	61.0	3.5	8739 25.		4973	13.5	11.0	2827	6.7
5	2.3	16828	57.8	4.7	8413 24.		4788	12.9	14.4	2721	6.3
6	2.7	16372	55.7	5.4	8185 24.0		4658	12.5	16.7	2647	6.0
6 7	2.9	16088	54.4	5.8	8043 23.		4577	12.2	17.9	2601	5.9
Ŕ	3.4	15162	50.2	6.9	7580 21.		4314	11.3	21.2	2452	5.3
8 9	3.8	14490	47.4	7.5	7244 20.1		4123	10.7	23.2	2343	4.9
10	4.1	13755	44.4	8.2	6876 19.0		3913	10.0	25.4	2224	4.5
ĩĭ	4.5	12921	41.0	9.0	6459 18.		3676	9.3	27.8	2089	4.0
12	4.9	12084	37.8	9.9	6041 16.		3438	8.5	30.5	1954	3.5
12 13	5.4	11236	34.7	10.8	5617 15.		3197	7.7	33.5	1817	3.0
14	6,1	10043	30.4	12.2	5020 13.0		2857	6.6	37.9	1624	2.2
15	7.8	7916	23.0	15.5	3957 10.		2252	4.5	48.1	1280	0.6
GOV>	7.9	7788	22.6	15.8	3893 9.		2216	4.4	48.8	1259	0.5
16	8.4	3865	10.0	16.8	1932 3.0		1100	0.9	52.1	625	ŏ.ŏ
17	9.2	Ő	-0.0	18.4	õ 0.		ŤÖ	ŏ.ó	56.8	õ	ð.ö
~ '		Ŭ	010	2014	0 0.	/ /2	Ŭ	0.0	2010	v	•••
THEO	RETICAL	TRANS	MISSIO	N SHIFT	POINTS (T	IRATNE R	PMI EN	GINE A	T FULL	THROTT	LE
2	1 > 2		10	2 > 3			4 : 22				
	2 < 3		50	3 < 2		4 <					

FROM CLARK HARLOW

.

112. 2.1444 (14554)

Approval no. BDE 3 CLARK Components Europe

2 DEC 91 sheat 5 of 6 ST BOOM LIFT TRUCK

and the and the set of the this state and the set of the

F. 5

DRIVELINE DESCRIPTION

Transmission	:	CAT 15.5LHR34414	3116	296	HP	at	2400	rpm		
Axle ratio Tire size	1	9.250 20.5RX25	Transfer Rolling r	case adius	rat	108 25	.71	1.900 in	0.900 (Static,	losdedi

CALCULATED VEHICLE PERFORMANCE IN LOCKUP

Grade based on GTW, assuming 20/1000 rolling resistance, 10850.0 square in frontal area, air res. coeff: 0.000017 lbs per (MPH)squared per square in

transfercase ratio : 1.900

	GEAR NO 1 Ratio = 5.325			GEAR NO 2 RATIO = 2.662			GEA Ratio		3	GEAR NO 4		
Turb	SPEED		GRADE							RATIO = 0.861		
RPM	mph	lbe	9	mph	lbs	GRADE	SPEED mph	T.E. 1bs	GRADE	SPEED mph	T.E. 1bs	GRADE
1500	2.5	22933	95.2	4.9	11464	35.5	8.6	6525				
1680	2.7	22353	90.6	5.5					18.4	15.2	3708	9.4
1860	3.0	21475			11174	34.4	9.7	6360	17.9	17.0	3614	9.0
			84.2	6.1	10736	32.8	10.7	6110	17.1	18.8	3472	8.6
2040	3.3	20348	76.9	6.7	10172	30.8	11.7	5789	16.0	20.6		
2220	3.6	19183	70.0	7.3	9590	28.8	12.8				3290	8.0
2400	3.9	18067	64.0	7.9				5458	15.0	22.5	3102	7.3
2448					9032	26.8	13.8	5140	13.9	24.3	2921	6.7
	4.0	16385	\$5.7	8.0	8191	24.0	14.1	4662	12.4	24.8	2649	5.8
2496	4.1	12867	40.8	8.2	6432	18.2	14.4	3661	9.2			
2544	4.2	8533	25.1	8.3	4266	11.2				25.3	2081	4.1
2592	4.2	3384	8.5				14.6	2428	5.4	25.7	1380	1.9
2640				8.5	1692	3.2	14.9	963	0.8	26.2	547	0.0
2040	4.3	-2581	0.0	8.6	-1290	0.0	15.2	-734	0.0	26.7	-417	ŏ.ŏ
	,	CD000 m							- • •			
C		GROSS T	RETU I	WT 1	empty v				Max	speed	in	
Gear		■ 4.28	mph		4.28	ncam	*				~``	
Gear	no 2 •		mph		8.54	moh	*					
Gear	no 3.	14.05	mph		14 00	ing. I						

Gear no 3 = 14.95 mph 14.95 mph Gear no 4 = 26.10 mph 26.10 mph

Look-up to be engaged and disengaged at 1669 turbine RPM when engine is at full throttle.

FROM CLARK HAPLOW

ø

12. 2.1991 14:54

- _

Approval no. BDE 3 <u>CLARK</u> Components Europe

2 DEC 91 sheet 6 of 6 ST BOOM LIFT TRUCK

DRIVELINE DESCRIPTION

Engine	£	CAT	3116	296 F	HP a	t 2400) rpm		
Transmission							•		
Axle ratio			Transfe					0.900	
Tire size	1	20.5RX25	Rolling	radius	1	25.71	in	(Static,	loaded)

CALCULATED VEHICLE PERFORMANCE IN LOCKUP

8 Grade based on GTW, assuming 20/1000 rolling resistance, 10850.0 square in frontal area, air res. coeff: 0.000017 lbs per (MPH)squared per square in

transfercase ratio : 0.900

	QE	AR NO	1	GE	CAR NO	2	GEA	R NO	3	GEA	R NO	4
	RATIO			RATI	0 = 2.6	62	RATIO	# 1.5	15	RATIC	= 0.8	61
Turb	SPEED		GRADE	SPEED) T.E.	GRADE	SPEED	T.E.	GRADE	SPEED	T.E. (GRADE
RPM	mph	lbs		mph	lbs	8	mph	1bg	8	mph	lbs	8
1500	5.2	10863	33.3	10.4	5430	14.9	18.2	3091	7.4	32.0	1756	2.8
1680	5.8	10588	32.3	11.6	5293	14.4	20.4	3012	7.1	35.9	1712	2.5
1860	6.4	10173	30.8	12.9	5085	13.8	22.6	2894	6.7	39.7	1645	2.2
2040	7.0	9639	28.9	14.1	4818	12.9	24.8	2742	6.1	43.6	1558	1.7
2220	7.7	9087	27.0	15.3	4543	12.0	27.0	2585	5.6	17.4	1469	1.2
2400	8.3	8558	25.2	16.6	4278	11.1	29.1	2435	5.0	51.3	1384	0.7
2448	8.5	7761	22.5	16.9	3880	9.9	29.7	2208	4.3	52.3	1255	0.3
2496	8.6	6095	17.1	17.2	3047	7.3	30.3	1734	2.8	53.3	986	0.0
2544	8.8	4042	10.5	17.6	2021	4.1	30.9	1150	1.0	54.3	654	0.0
2592	9.0	1603	2.9	17.9	801	0.3	31.5	456	0.0	55.4	259	0.0
2640	9.1	-1223	0.0	18.2	-611	0.0	32.1	-348	0.0	56.4	-198	0.0
		GROSS	TRAIN	WT	EMPTY V	EHICLE			Мах	speed	fn	
Gear	no 1 •		1 mph			mph	*			-2		
Gear		17.9			17.93		*					
Gear	no 3 -				31.17	mph	*					
Gear	no 4 •	52.6	6 mph		52.66	mph	*					

Lock-up to be engaged and disengaged at 1669 turbine RPM when engine is at full throttle.



	SCAAN NO 323	447	Table 6.2.2.2.1				11.2
	.date::10/31/	91, 12:47pm CET		The second s			1195
	tm887768, Ey	ne.				:	1 1 1
		50	TRANSH ISSI AAN Summary	/			
1	Vahicia	HOBILE EQUIP- NOU	na source sources of basis Althe States of Altheory Table		Boli ki kata kata kata kata kata kata kata	C AMA	
	Engine	CAT 3116 ATAACM 2			542 (FREE 1996) 422 - 478 (FREE 199	12 474	
ء 1 جو د ر		(Clutch fan ENGAG					12
	Transmission	ALLISON MD3070PT					
	Converter	ALLISON TC-417 RE		i, 10-3-90			
÷				mendation	appli-		
				rating	cation		· .
		n anda minin artis tamar akad minin kana kana akan anar akar akan kana akan kana ka kuta kata kana kana kana a I anga pana tama tama angan minin tama tama aya mana kana akan kana tama tama tama tama tama tama kata kat			ין ביני ביני לא היה לא ליב אל היו אין		Ľ
	ENGINE:	TING/VOCATION COMP				·	
		TO ENGINE MEGRS. R					-
	SUBJECT	TO ENGLINE PEGNO. P	ac. V 4 6.49			· · · · · · · · · · · · · · · · · · ·	-
•	CONVERTER:						
		bine torque, 16.ft		50.maa	1235.	er iz	
		m, conv. stall		······		5.5 # 5 5 #	
					1 / 76 / /		
Ni-			•		1758.		
Ņ.	Converter	stall torque rati	0 1	·	2.160	η.K.	
N	Converter Eng peak	stall torque rati torque rpm vs min.	o (rpm 153)				
	Converter Eng peak	stall torque rati	o (rpm 153)	·	2.160 1754,		
	Converter Eng peak	stall torque rati torque rpm vs min. at 2600. gov rpm	o (rpm 153)		2.160 1754,		
	Converter Eng peak Conv. SR	stall torque rati torque rpm vs min. at 2600. gov rpm N:	о (грл 153 О.8		2.160 1754,	Ċ. k :	
	Converter Eng peak Conv. SR TRANSMISSIO Input hor	stall torque rati torque rpm vs min. at 2600. gov rpm N:	ь (rpm 153 0.8		2.160 1754, 0.937	0.K.	·
	Converter Eng peak Conv. SR TRANSMISSIO Input hor	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku	р) 7	50.max	2.160 1754, 0.937 225.	0.K. 0.K.	·
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input rpm	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku	p) 7 2000	50.max	2.160 1754, 0.937 225, 616,	0.K. 0.K.	·
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input rpm Transm ou	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.)	b (rpm 153) 0.8 p) 7 200 1.4.	50.max	2.160 1754, 0.937 225, 616,	0.K. 0.K.	- - -
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input rpm Transm ou at 2600:	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, 1b.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s	b (rpm 153) 0.8 p) 7 200 1.4.	50.max	$2.160 \\ 1754 \\ 0.937 \\ 225 \\ 616 \\ 2600 \\ . \end{cases}$	0.K. 0.K.	
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input rpm Transm ou at 2600: VEHICLE/DRI	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE:	b (rpm 153) 0.8 p) 7 200 1.4.	50.max	2.160 1754, 0.937 225, 616, 2600, 3321 ,	0.K. 0.K.	-
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Transm ou at 2600: VEHICLE/DRI Vehicle G	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs.	b (rpm 153 0.8 p) 7 200 1.u. peed (-) 50.max 50.max 00.max 0./2800.	2.160 1754, 0.937 225, 616, 2600, 3321, 42000,	0.K. 0.K. 0.K.	
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600: VEHICLE/DRI Vehicle G Ist conv	<pre>stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine govs VELINE: VW, lbs. stall tr.eff/veh.w</pre>	o (rpm 153 0.8 p) 7 200 1.u. peed (- t ratio 0.		2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170	С.К. О.К. О.К. О.К.	
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Transm ou at 2600: VEHICLE/DRI Vehicle G ist conv Driveline	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio	o (rpm 153 0.8 p) 7 200 1.u. peed (- t ratio 0. 7.		2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102	С.К. О.К. О.К. О.К.	-
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600: VEHICLE/DRI Vehicle G ist conv Driveline (reverse	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio e range, 70% conv.	o (rpm 153 0.8 p) 7 200 1.u. peed (- t ratio 0. 7. eff. at 0.) 50.max 50.max 00.max 0./2800.) 4000 min 958min 400 traction	2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102 n coeff.)	0.K. 0.K. 0.K. 0.K. 0.K.	
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600: VEHICLE/DRI Vehicle G ist conv Driveline (reverse ist gear	stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio e range, 70% conv.	o (rpm 153 0.8 2 p) 7 200 1.u. peed (- t ratio 0. (- t ratio 0. 7. eff. at 0. bility (-) 4000 min 4000 min 958 min 4000 min 958 min 400 traction)	2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102 n coeff.) 131,85%	0.K. 0.K. 0.K. 0.K.	i. i
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600. VEHICLE/DRI Vehicle G ist conv Driveline (reverse ist gear o ist conv.	<pre>stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio e range, 70% conv. conv. stall gradea 70% eff. gradeabi</pre>	o (rpm 153 0.8 2 p) 7 200 1.u. peed (- (- t ratio 0. (- t ratio 0. 5 eff. at 0. bility (- lity (-		2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102 n coeff.) 131,85% 69,93%	С.К. О.К. О.К. О.К. О.К.	in the second
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600. VEHICLE/DRI Vehicle G ist conv Driveline (reverse ist gear ist conv. ist conv.	<pre>stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio e range, 70% conv. conv. stall gradea 70% eff. gradeabi 80% eff. gradeabi</pre>	<pre></pre>		2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102 n coeff.) 131,85% 69,93% 57,57%	С.К. О.К. О.К. О.К.	
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600: VEHICLE/DRI Vehicle G ist conv Driveline (reverse ist gear ist conv. ist conv. ist conv.	<pre>stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio e range, 70% conv. conv. stall gradea 70% eff. gradeabi 80% eff. gradeabi 70% eff. transm B</pre>	<pre></pre>		2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102 n coeff.) 131,85% 69,93% 57,57% pm) 3117.	С.К. О.К. О.К. О.К.	
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600: VEHICLE/DRI Vehicle G ist conv Driveline (reverse ist gear ist conv. ist conv. ist conv. ist conv.	<pre>stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio e range, 70% conv. conv. stall gradea 70% eff. gradeabi 80% eff. transm B 80% eff. transm B</pre>	o (rpm 153 0.8 2 p) 7 200 1.u. peed (- t ratio 0. 7. eff. at 0. bility (- lity (- lity (- TU/min (at TU/min (at		2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102 n coeff.) 131,85% 69.93% 57.57% pm) 3117, pm) 2338.	С.К. О.К. О.К. О.К.	i.
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600: VEHICLE/DRI Vehicle G ist conv Driveline (reverse ist gear ist conv. ist conv. ist conv. ist conv.	<pre>stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio e range, 70% conv. conv. stall gradea 70% eff. gradeabi 80% eff. transm B 80% eff. transm B 80% eff. transm B</pre>	<pre>0</pre>		2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102 n coeff.) 131,85% 69,93% 57,57% pm) 3117.	С.К. О.К. О.К. О.К.	i. A
	Converter Eng peak Conv. SR TRANSMISSIO Input hor Input tor Input tor Input rpm Transm ou at 2600: VEHICLE/DRI Vehicle G ist conv Driveline (reverse ist gear ist conv. ist conv. ist conv. ist conv. feared mp max mph	<pre>stall torque rati torque rpm vs min. at 2600. gov rpm N: sepower que, lb.ft. (locku (gov.) tput rpm, range 7 rpm engine gov. s VELINE: VW, lbs. stall tr.eff/veh.w reduction ratio e range, 70% conv. conv. stall gradea 70% eff. gradeabi 80% eff. transm B 80% eff. transm B</pre>	0 (*pm) 153 0.8 0.8 p) 7 p) 200 1.u. (~ peed (~ t ratio 0. bility (~ lity (~ lity (~ TU/min (at 7 1.u. (~ lutch fan D		2.160 1754, 0.937 225, 616, 2600, 3321, 42000, 0.8170 10,102 n coeff.) 131,85% 69.93% 57.57% pm) 3117, pm) 2338.	С.К. О.К. О.К. О.К.	

		Card La	1004913			2	• .				
	SCAAN I	No:32	3447	47pm CE1				. <i>.</i>		an a	્રેલ્પ્સિંગ્સ સ્ આગળવા છે.
0	tm8877			i pin oc			÷	· :.			P
		A	LLISON 1	RANSHIS	SIGN DI	(V					
	V.	ehicl		hrottle		Na Let e 197				•	• • • •
·				v Fen Eng		n an an cathair					
	Veh av	naina	tr	drawbar	where ?	rust y	tenso ot			•	ing ing the second s Second second
	again a		effort				BTU/win				
•	•	•		, 22 25 25 25 25 15 15 15 15 15 15 15 15 15 15 15 15 15							
	Reverse	1	atio= -4	.032 -et	lant r	n na sucar i s	ar natura a	tion			
			29362			92.51		C.3.CM (
				20599							
			21330			55.87		70%	Conv.	Efficiency	
			18650							Efficiency	
				13400							
i,				10673							
N -	-6.00	2572	10038	9193	160.6	22.43	1723				
$\sim 10^{-1}$				9057	160.6	22.08	1704				
$\sim \sqrt{2}$	-6.91	2792	841	-4	15.5	-0.01	721		•		
. }	Forward	1. 5	atio= 6.	929 -100	v rance	e start.	conver	ter d	operat	ion	
				33465		131.85					
	1.76	1873	24910	24069	117.2	69.93	3117	70%	Conv.	Efficiency	
	2.00	1899	23628	22788	126.0	64.59	2752				
4				20956				80%	Conv.	Efficiency	
į				13738							
				12674			1927				•
	5.30	2600	11632	10788	164.3	26.58	1527		, ,	•	114
	Forward	2, r.	atio= 4.	185 -dri				ertei	r oper	ation	
Ş	0.00	1758	20871			54.26					
		1319	17216		91.8		4207				
		1873			117.6					Efficiency	
			13180					80%	Conv.	Efficiency	
		1947				30.15	2266				-
· · · ·		2124				21.54	1767				
• • •	7.12			7216 6652							
			6902			14.56	1776 1667				
	Forward							oper	ration		
•	8.77					13.05					
	10.00					11.65					
	11.15			4384	155.8	10.49	1723				
	auto 100 11.15			4704	166 0	10 40	100				
× .	12.00				155.8	10.49	606 451				
~	12.00					10.14 9.10	651 751				
1921	16.00					7.94	828			-	
		2600				6.98	869				
				-		,					
			•								
	Forward 17.51			691 -aut 2780			ito locki 716	.p st	nift		

7.

-

LILLING THE REPORT OF THE PARTY OF THE PARTY

			3447	e se concentra El societado					ि संजीत २ ४४-४) इ.स.स. २ १०२ १४		
	veh e	noine	tr c	teremente Irawbar	wheel	net %	tran ht	1 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	a state of the		<i>स्टिम् यस्ट्रम्य</i>
			effort				BTU/min				
-		•									
			3598			6.47					
	20.00	2245	3330 . 3045	2433	177.6	5.80	318				
	22.00	2470	3045	2136	178.6	5,09	379				
	23.16	2600	2868	1952	177.1	4.65	-704				
	• • • • •									• •	
							ito locku	p shift			
			2669								· .
			2618								•
			2485								
			2344								-
			2197			2.93					
	32.00	2549									
	32.64	2600	1985	994	172.8	2.37	1113				
:											
							ito locku	p shift			
N S			1878								
$\sim \lambda_{\rm eff}$			1825	821	165.5	1.95	1107				
			1748	72.	167.8	1.72	1183			·	
\sim			1669			1.49					1 A. A
.)			1589								
ÿ			1505								
	43.53	2600	1439	330	167.0	0.78	1394				
							ito locku	p shift			
			1386			0.66					· · ·
			1370				1673				
i			1301				1790				
1	48.00						··· 1911** ·		14	•	. 2
	50.00			-41	153.8	-0.10	2037				
į	50.02	2600	1152	-42	153.7	-0.10	2038				

Note:

* exceeds vehicle traction limit

::

· 15.5444755414

TL X S

зj.

T. A State St

n sy Rogai

÷

···· · · · · · ·

· . . .

date: 10/31/91, tm387768, Eyre

ALLIGOU TRANSMISSION DIV Engine Converter Match Clutch Fan Engaged

12:47pm CE1

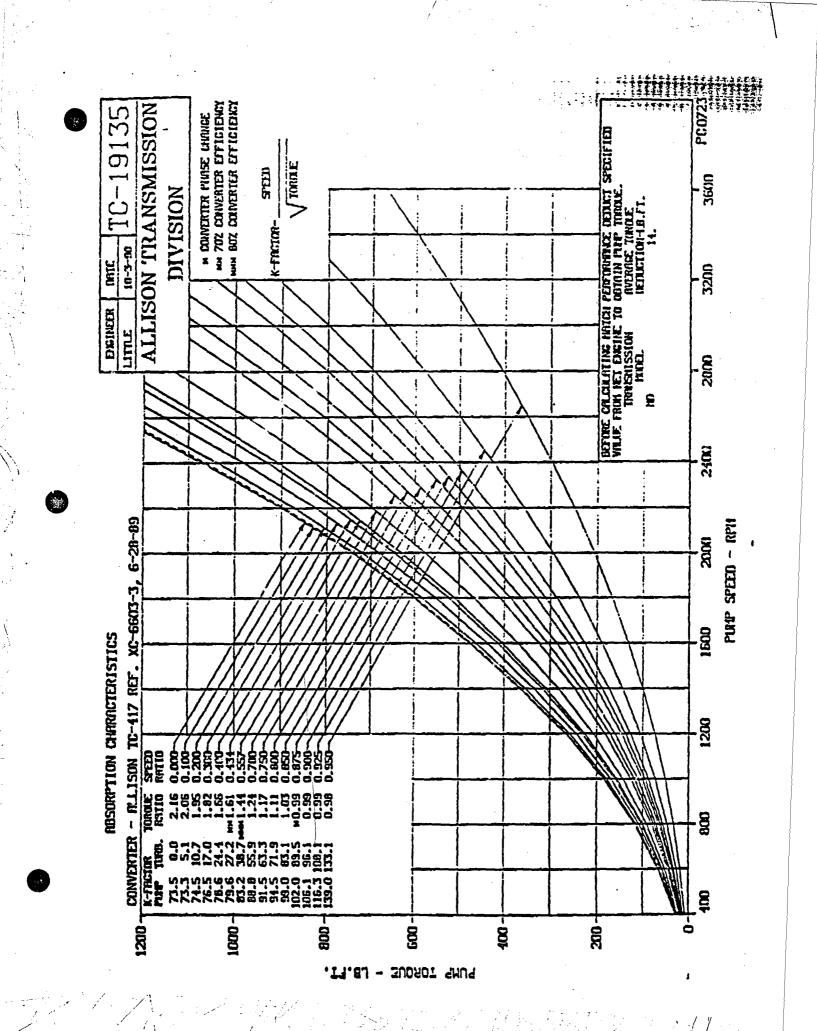
tan unite in construction and the second second

	speed	.eng	one	t	urbine	• . •	heat re	∋j ″
	ratio	+ pm	torque				GTU/mi	
	0.0000	1758		0,0		11155	8480	
	0.1000	1754	598	39.4	175	1.1 °Q	6799	
	0.2000	1776	595	75.0	355	$1 \neq 1 \leq 1$	5350	
	0.3000	1817	589	106.5	540	1.472.15	4133	
	0.4000	1857	584	131.2	743		3187	
	0.4333	1873	58j	138.5	812	1 - 2 - 2 - 2	2918	70 % eff
	0.5000	1907	576	152.0	954	037	2431	
	0.5568	1939	571	161.3	1080	705		80 % eff
	0.6000	1966	567	167.2	1179	~ 4 1	1912	
\mathbf{N}	0.7000	2043	554	177.9	1430	653	1601	
$\mathbf{N}^{(1)}$	0.7500	2088	547	182.4	1566	611	1488	
N:	0.8000	2140	538	184.8	1712	5437	1462	
N	0.8500	2213	525	183.6	1881	r. 1 4	1602	
1	0.8750	2250	517	183.9	1978	-1. S	1635	coupling
	0.9000	2325	505	188.9	2092	474		
	0.9250	2472	478	194.6	228ϵ	447	1279	
	0.9310	2536	465	195.0	2361	434	1243	
	0.9368	2600	452	195.1	2436	4124	1210	gov. rpm
	0.9434	2616	419	181.7	2468	387	1121	
	0.9500	2632	384	168.0	2500	353	1041	
1 ° 1	0.9750	2714	215	94.5	2646	180	730	
}	0.9900	2785	77	26.7	2758	51	607	

Lockup Üperation eng ...turb... speed torque hp

1.5

		1.15		
1500	590	168.5		
1560	590	175.3		
1655	584	184.1	conv-lockup	APROVED SHOP ON
1700	578	187.2		
1800	566	394.0		
2000	536	204.0		
2200	502	210.2		
2400	466	112.3		
2600	426	220.2	erts stra	
2600	426			
2665	289	146.5		
2730	158	82.2		
2795	33	17,8		



ļ

Service and a service of the service SCAAN No 326080 date: 11/28/91, 10:50am GMT tm992012, ATD UNITED KINGDOM ALLISON TRANSPUSSION DIV SCAAN Application Information VEHICLE: MOBILE EQUIP- ROUGH TERRAIN -D. J. IMOUSTRIES ATLAS 4X4 5600 vocation library file number 42000. 1bs. gross vehicle weight 42000. lbs. weight on drive wheels (100.0 percent) 25.575 in. radius, wheel-394.29 wheel rev/mile 10.106 total driveline reduction ratio (transm. output to wheels) req'd for 50.00 mph geared top speed driveline: propeller shaft, wheel planetary, all wheel drv off hwy 87.56 % driveline efficiency 0.700 traction limit coefficient 2.00 % rolling resistance 70.0 sq.ft. vehicle frontal area 0.8500 air resistance coefficient DIESEL ENGINE: CAT 3116 300 HP (engine data responsibility: ATDUK) NOTE: ENGINE RATING/VOCATION COMPATIBILITY SUBJECT TO ENGINE MFGRS. REVIEW. PERFORMANCE BASED ON PUBLISHED 'LUG-BACK' ENGINE DATA. ENGINE 'ACCEL' CHARACTERISTICS MAY INFLUENCE PERFORMANCE AS OUTLINED IN TD115. 403.0 in3 engine displacement 995674 engine library file number 299.5 gross horsepower at 2600. rpm deductions (hp. at 2600. rpm) 19.5 hp fan (clutch engaged) 0.0 hp/fan((clutch disengaged) 1.5 hp_alternator/generator 1.5 hplair compressor 3.0 hp.steer pump 6.0 hp implement drive 268.0 net horsepower 2600. rpm 1400. 1500. 1600. 1800. 2000. 2200. 2400. 2600. 2850. eng rpm entered hp 193 3 208.5 221.2 246.8 268.5 278.6 294.7 299.5 0.0. net hp 183.1 197.2 208.7 231.5 250.0 256.4 268.2 268.0 -38.7 net torque 686.7 690.4 684.9 675.5 656.5 612.0 586.9 541.4 -71.3 engine torque of 690.5 lb ft occurs at 1490. rpm) (max. net (max. gross engine torque of 730.0 lb ft occurs at 1306. rpm) 0.932 lb.ft.sec.2 engine inertia CONVERTER: ALLISON TC-419 REF. TC-19137, 10-3-90 TRANSMISSION: ALLISON MD3070PT (2-7) 8589. 15.ft. max transm output torque, 1st mange conv stall 7351. lb.ft. max transm output torque, rev range conv stall TRANSM. AFFLICATION- MD3070FT (2-7) GENERAL 16625 transm application library file number THIS SCAAN INFORMATION SUBJECT TO THE DISCLAIMER SET FORTH IN THE SCAAN USER'S MANUAL **Mannah** and 资料代码保持认为目标

SCAAN No 326080 date: 11/28/91, 10:50am GMT tm992012, ATD UNITED KINGDOM ALLISON TRANSMISSION DIV SCAAN Summary a al caracteria en la rem Vehicle MOBILE EQUIP- ROUGH TERRAIN -D. J. INDUSTRIES ATLAS 4%4 Engine CAT 3116 300 HP (Clutch fan ENGAGED) (engine data responsibility: ATDUK) ALLISON ND3070PT (2-7) Transmission Converter ALLISON TC-419 REF. TC-19137, 10-3-90 • • • recommendation | applior rating cation status ENGINE: -->ENGINE RATING/VOCATION COMPATIBILITY --> SUBJECT TO ENGINE MFGRS. REVIEW Same and the second second CONVERTER: Stall turbine torque, lb.ft. 1350.max 1283. **D**.K. Engine rpm, conv. stall (----) 1693. (----) Converter stall torque ratio 1.960 Eng peak torque rpm vs min. rpm 1490.+100.min 1693. 0.K. Conv. SR at 2600. gov rpm 0.800/1.000 0.K. 0.938 ·经产于考虑246、约集时来,1996年3月。 TRANSMISSION: ->Input horsepower 250.max 270. <-(XXX) Input torque; 1b.ft. (lockup) 700.max 690. O.K. Input rpm; (gov.) 2000./2800. 2600. **0.K.** Transm output rpm, range 7 1.u. : at 2600. rpm engine gov. speed 3321. . . . 5 × 1 VEHICLE/DRIVELINE: Vehicle: GVW, 1bs. (----) 42000. 0.4000 min 1st conv stall tr.eff/veh.wt ratio 0.8490 о.к. Driveline reduction ratio 7.291min 10.105 O.K. (reverse range, 70% conv. eff. at 0.400 traction coeff.) 1st gear conv. stall gradeability (----) 148.27% ist conv. 70% eff. gradeability (----) 90.63% 1st conv. 80% eff. gradeability (----)
1st conv. 70% eff. transm BTU/min (at 1876. eng rpm)
1st conv. 80% eff. transm BTU/min (at 1966. eng rpm) 67.31% 3553. 2703. Geared mph @ gov rpm, range 7 l.u. (----) 50.00 max mph on 0.25% grade (clutch fan DISENGAGED) at 2630. engine rpm, range 7 l.u. 20.00min 50.58 O.K. ALL TRANSMISSION APPLICATIONS require submittal to PRODUCT ENGINEERING DEPARTMENT NOTE: Symbols indicate: ->Not within TRANSMISSION RATINGS <-(XXX) 1111223112114

					د چې د د د د د د مد به به به د د .	e an star en de ser a constant	1-1- 1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-	· · · · · · · · · · · · · · · · · · ·		
										and a second
	SCAAN I	1			177 a Grand d' d'Arign 1	7月前日 1-3 足前なり	********	╺픚 <u>횿፦쥳</u> 쫕뼒低랔슻툳쒭		Care J. Mar.
	date: .	11/28/	91, 10:5							
T	tm9920.	12, AT	D UNITER	D KINGDI	314			•	· .	
		ÁL	LISON TE	RANSM) OS	an en	.,				
	Q_{i}		Full T	antic	Ferful					
į			Clutch		• •					
1	veh e mph	-	tr c effort				tran ht BTU/min			
, L	4		erior. Sessesses		•	-				
								•		
ķ			tio= -6. 7 523*			onverte 99.89	r opera 9304	tion'	:	
			: 73			47.07 65.58				
, N			2 10					70% Conv.	Efficiency	
Ś.			20790					80% Conv.	Efficiency	
			16706						• • •	
			13255				2217			
			12187 12017			27.59				
	-6.92		847			0.00	738			
	·	-						· •		
								ter operat	ion ***	
			- 35661* - 27200						Efficiency	
			26595				3343			
	2.48	1966	24290	23452	160.7	67.31	2703	80% Conv.	Efficiency	
6			17350					•		
			15552 14103	14709			2025 1716		ing the state of t	
	0.00		14100		1//12	00.27	2720	·	• • •	
								erter oper	ation	
1		1693				57.21	9304		an star	
			18722 16490		99.8	47.05 40.15	4876 3529	707 Copy	Efficiency	
			14886		158.8	35.48	2758	/0/. 00/14.	Childrency	
			14700	13857			2688	80% Conv.	Efficiency	
			11393			25.95	2031			
1			9292	8444		20.52	2123			
			9104 8406	8255 7555		18.29	1998 1841			
://								operation		
1.1		2022	7320 6718			15.59 14.10				
	11.80		5855			11.98				
	auto lo	ckup s	hift							
		1754	5855		184.3	11.58	667		٨	
			5843 5526			11.95 11.16	579 788			
9			5048			9.98			•	
		2600	4625		215.8		913			
	· 동네 - 14:5년 8:44	• 1 • •	.			:			1. : · · ·	
зK	Forward	4, ra	て10= 1.0 - 4て07	571 -aut 7474	to upsh 201 A	11T, AU 8.18	to lock 747	up shift	2 . Alter a	
				0724	201.0	0.10	/ 7 /			unter 🛃
题	1111		•.					100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100 - 100		***
	- A-A- # E 3563 -E 43	n # 2 AL L'T, SP '	•						n in an an suite ann an An An Stain, an Shain (Shain Shain) a' s	
،	· · ·						<u> </u>			
-								• •	the state	
	:					- /		,	14	

``

_! .

1

and the statement is

- With the state of the

「見ないの、気を読書に驚くない、たちない

217

1, ĊΞ 2.30%

veh e	ngine	, tr	drawbar	wheel'	net %	tran ht	
			pull			BTU/min	
			3365				
			3610				
			2792				
23.15	2600	3485	2569	219.2		944	
						ato lockuj	p shif
			2179				
			2141				
			2010				
			1807				1
			1693				1
32.00	2550	2493	1508	212.8	3.59	1116	
32.63	2600	2426	1435	211.1	3.42	1142	
Forward		tio = 0.	.900 -aut	In unsh	ift. au	ito lockuj	n shif
	•		1225	•	•	•	
			1168				
			1049				
38.00	2271	1983	937	200.9	2.23	1287	
40.00	2390	1934	866	206.3	2.06	1353	
42.00	2510	1850	866 759	207.2	1.81	1405	
, 43.51	2600	1767	658	205.0	1.57	1437	
a a shaka din tatu				2. X. 2. A		an an ing an	
Forward	7, ra	tio= 0.	783aut	o upsh	ift, au	to Tockup	o shif
			549				
44,00	2283	1645	529	193.0	1.26	1712	
. 46.00	2392	1601	461	196.4	1.10	1835	
48.00	2496	1530	461 362 242	195.8	0.86	1958	
50.00	2600	1437	242	147 1	0.58	2083	
• .		•					
Note:	. * .	exceeds	vehicle	tract:	ion lim	it	
• •	:		• •			•	
			•				

t a tans³nu

. .

•

.

SCAANTNATS2608011458-AND ST. L date: 11/28/91, 10:50am GMT tm992012, ATD UNITED KINGDOM

(A) 17

ALLISON TRANSMISSION DIV Engine-Convertor Match Clutch Fan Engaged

ŧ.

1.1.1

speed .engine..turbine.... heat rej ratio rpm torque hp rpm torque BTU/min 0.0000 1693 680 0.0 Ó 12839304 0.1000 1693 680 40.1 169 1244 7603 0.2000 1721 78.3 679 344 1196 6113 0.3000 1770 677 113.2 5311120 4873 0.4000 1837 673 144.1 735 1031 3865 0.4600 1876 669 160.8 979 863 3322 70 % eff 0.5000 1903 667 171.2 952 945 2987 0.5805 1966 660 189.9 1141 874 2430 80 % eff 0,6000 1983 659 194.0 1190 857 2317 0.6500 2026 652 1317 202.3 807 2091 0.7000 2079 642 209.8 1455 757 1880 0.7500 2126 632 214.6 1594 707 1741 1048000 - 2176 619 217.4 1741 656 1650 0.8500 2248 604 220.4 1911 606 1622 .0.8970 2346 592 225.1 1667 coupling 2104 562 (0.9250) 2479 571 235.7 2293 540: 1443 0-9315 2540 - 556 236.3. 2366 525 1389 019377 2600 541 236.5. 2438 509 1338 gov. rpm 0.9439 2613 508 223.5 2466 476 1237 0.9500 2625 474 210.1 2494 442 1144 0,9750 2708 264 118.0 2640 235 770 0.9900 2773 105 41.0 2746 78 620 Lockup Operation eng turb... ... speed torque hp ___________ 1400 661 176.2 1500 665 189.9 200.8 1600 659 :1754 652 217.7 conv-lockup intersection 1800 650 222.7 631 2000 240.2 2200 586 245.6 2400 561 256.5 255.3 gov. rpm 2600 516 2600 516 255.3 2663 352 178.4 2725 196 101.5

2788

46

24.5

. .

. . .

917 # 10 A 10 Western in erre

ATLAS Fording Study

6.3 Performance.

The power train, required to meet the speed and torque requirements of ATLAS, substantially contributes to the weight growth of the ATLAS. The weight growth is within the additional weight required to accommodate the lift requirements.

Pe formance is not otherwise compromised by the application of the components of the powertrain.

6.4 HFE/Safety.

Implementation of the powertrain components are not projected to introduce HFE or safety concerns once the braking issues are addressed.

6.5 Reliability.

The power train reliability allocation (MTBF) is 1000 hours. The allocation is low given the uncertainty of the ratings assigned to each of the components.

6.6 Producibility.

Modification of most if not all of the commercial power train components is required to meet performance requirements. Modifications to meet fording and corrosion considerations are limited to providing vents/breathers and sealing of filler tubes/dipsticks.

6.7 Cost Impact.

With the modifications of commercial products the economies of scale are sacrificed. The most significant modifications are to the axles. Modifications may increase the cost of each axle by \$1500. These modifications to the axle would involve increasing brake capacity and changing axle ratios to provide the required speed. Configuration changes to fulfill fording and corrosion requirements are trivial.

ATLAS Fording Study

6.8 Integrated Logistic Support.

Reliability of the powertrain may be affected by the performance requirements of the ATLAS vehicle. The potential impact on reliability will need to be offset against the cost/weight/size/transportability concerns with maturation of the design. Most RAM-D considerations are discussed above, so will not be repeated. The maintainability requirements will increase for any design alternative. The increase in components will have a minor impact on provisioning costs. This system should have the most potential impact on ILS concerns within the ATLAS vehicle.

Page 11

ATLAS Fording Study

Caterpillar Inc.

Paragraph 7.0 Hydraulic System

7.1 Baseline Description.

The baseline description establishes the hydraulic arrangement of the RT100 from which the alternative ATLAS designs evolve. The RT100 implements electric-over-hydraulic controls for boom movements, steering, raising/lowering outriggers, etc. This control eliminates mechanical linkages and hydraulic lines for increased reliability. The electro-hydraulic control system gives the operator smooth, precise control of the load to facilitate load engagement and placement. The electronic control box is environmentally sealed and design for off-road application. The heavy duty box is iso-mounted within the cab to reduce vibrational loading and provide redundant protection from the elements.

Solenoid-actuated main control valve spools are enclosed within the hydraulic control body to seal out dirt and moisture and eliminate leaks.

7.1.1 Pump-Hydraulic. Load sensing, variable displacement piston pump reduces engine loads and hydraulic oil temperature for increased reliability and durability. The pump varies its output to match constantly changing system requirements.

7.1.2 Cylinders-Hydraulic. Spherical bushing isolate hydraulic cylinders from offcenter loads that would otherwise reduce cylinder and seal life. Chrome plated cylinder rods resist both wear and corrosion. Wiper seals prevent intrusion of particles that wear seals.

ATLAS Fording Study

7.2 Alternative Design.

The hydraulic design of the ATLAS will be essentially unchanged from the commercial vehicle except that ATLAS may incorporate a hydro-pneumatic suspension (Paragraph 5.0), a sealed hydraulic tank, and bulkhead connectors through watertight compartment.

7.2.1 Connectors-Bulkhead. Each hydraulic hose that penetrates a compartment to be sealed will be replaced by two shorter hoses and a bulkhead connector. Bulkhead connectors will be used to penetrate a watertight structure.

7.2.2 Hydraulic Tank-Sealing. Alternative designs are identified in the Hydraulic System Contamination Study to eliminate the potential of NBC particles contaminating the hydraulic oil via the breather of the hydraulic tank.

7.3 Performance.

Implementation of a tailored hydraulic system will not compromise the performance of ATLAS.

7.4 HFE/Safety.

Implementation of a tailored hydraulic system will not compromise the HFE/Safety requirements of ATLAS.

7.5 Reliability.

Implementation of a tailored hydraulic system will not compromise the reliability of ATLAS.

ATLAS Fording Study

7.5.1 Connectors-Bulkhead. The incremental increase in number of bulkhead connectors and hoses increase system complexity but still remain within the reliability allocation (MTBF=1000 hours).

7.5.2 Cylinders-Hydraulic. Reliability of the hydraulic cylinders is typically the primary source of unreliability as a result of oil leaks. Other than mechanical damage to the cylinder rod that damages the seals, most damage to the rod seals occurs due to the presence of a 3rd particle intrusion. The fording environment provides a number of sources of 3rd particles. Corrosion products, resulting in pitting of the rod, are generated as a result of inadequate plating thickness. 3rd particles, sand and debris, are suspended in the surf zone. Hydraulic cylinders suitable for sustained fording operations required a wiper seal to prevent the 3rd particles from coming into contact with the rod seals.

The cylinder rod can be protected from pitting and corrosion damage with a 0.016" chrome plating.

7.5.3 Hydraulic Tank. Replacing the breather of the hydraulic tank with a bladder may serve to eliminate a source of contamination and increase the life of the hydraulic pump.

7.6 Producibility.

The increase in number of hoses, bulkhead connectors, and associated assemblies serve to decrease the producibility of ATLAS. Replacing the breather on the hydraulic tank with an internal bladder will add minimum material cost and assembly effort.

Page 3



7.7 Cost Impact.

The increase in number of hoses, bulkhead connectors, and associated assembly time will increase the cost of ATLAS by approximately \$2500..

7.8 Integrated Logistic Support.

The minor modifications suggested for ATLAS should have very minor effects on reliability and availability. A minor improvement in maintainability may be seen through the use of bulkhead connectors and separated hydraulic lines. This will have only minor effects on provisioning.

ATLAS Fording Study

Paragraph 8.0 Chassis

8.1 Baseline Description.

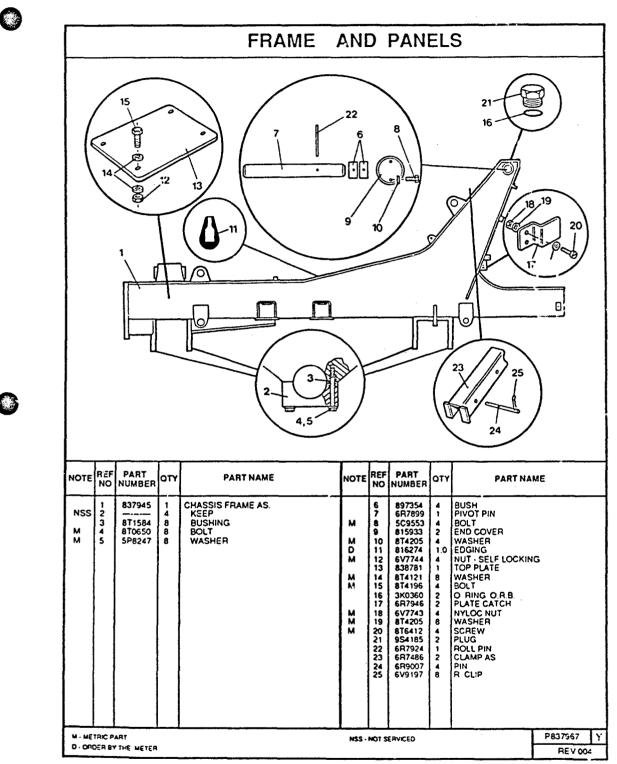
The baseline description establishes the chassis arrangement of the RT100 from which the alternative ATLAS designs evolve. The RT100 provides a strong stiff frame that resists distortion and fatigue cracking in tough applications. For purposes of this evaluation, the chassis group (Figure 8.1-1) includes the engine cowl and platform group (Figure 8.1-2) as well as the concept design for the carriage and A-frame required for the ATLAS suspension (Paragraph 5.0). The baseline vehicle implements a common one-piece, unitized main frame. The frame has box section side rails, which are joined by thick plate bulkheads for good torsional rigidity.

.....

· •

1.

ATLAS Fording Study



837967 CHASSIS FRAME GROUP

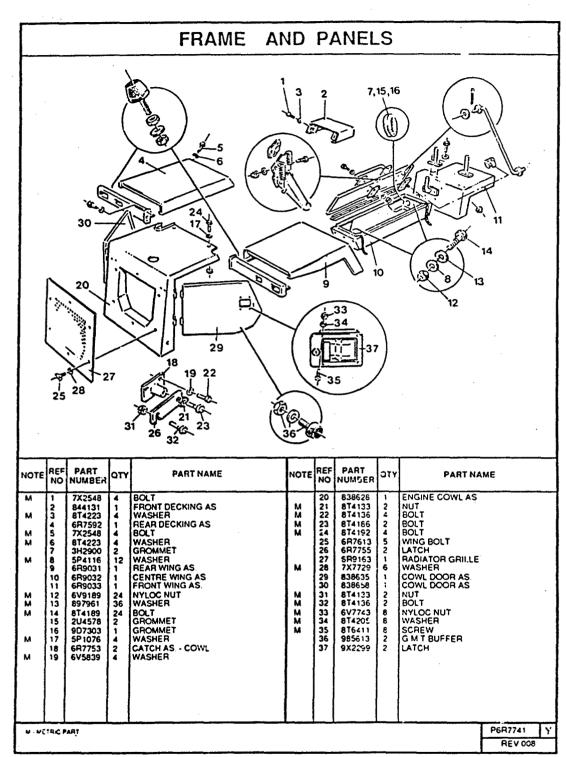
Figure 8.1-1 Chassis Frame Group

Page 2

£,

ATLAS Fording Study

1



11

.

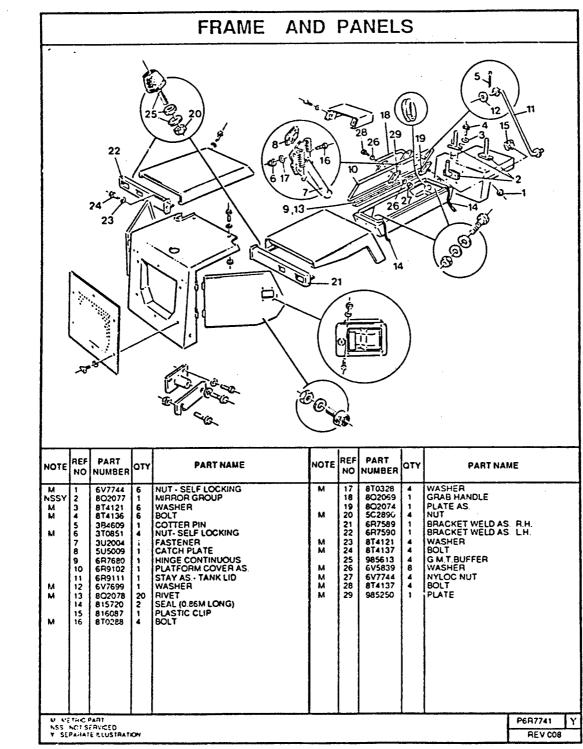
6R7741 ENGINE COWL AND PLATFORM GROUP (1 of 2)

Figure 8.1-2 Engine Cowl and Platform Group Part 1

;

ß

ATLAS Fording Study



6R7741 ENGINE COWL AND PLATFORM GROUP (2 of 2) 802077 - PAGE 237

Figure 8.1-2 Engine Cowl and Platform Group Part 2

Page 4

ATLAS Fording Study

8.2 Alternative Design.

The chassis will be a new design to accommodate the front and rear suspensions group and the new powertrain components.

8.2.1 Corrosion. The chassis design will incorporate features to minimize the incidence of crevice corrosion. Ceneral corrosion resistance of these mild steel structures will be provided by the corrosion resistant primer.

8.2.2 Sound Suppression. Reduction of operator and spectator noise will require shrouding of the engine compartment. Typical materials, foams and fiberglass, used for sound suppression within an engine compartment will tend to retain moisture adjacent to the crowl or engine enclosure. This moisture will facilitate corrosion of the substrate if the corrosion resistance is not maintained. Alternative sound suppression methods can be pursued as required in later stages of ATLAS development.

8.3 Performance.

Implementation of the chassis group will not compromise the performance of ATLAS. The weight growth projected for the chassis group is accounted for within the projected weight of 32,500 lbs.

8.4 HFE/Safety.

Implementation of the chassis group will not compromise the HFE/Safety of ATLAS. Engineering changes to the chassis group to provide the necessary corrosion resistance will facilitate decontamination of the vehicle.

8.5 Reliability.

Implementation of the chassis group will not compromise the reliability of ATLAS. The reliability allocation assigned the chassis group (MTBF=10,000 hours) may be conservative given that the cuty cycle of ATLAS is moderate when compared to commercial RTFLs.

8.6 Producibility.

Components of the chassis group will be redesigned to meet the fording and corrosion considerations. Box bean, exctions will be watertight. Intermittent welds will be replaced by continuous welds. Cup-like features that would other wise retain water, will include a provision for drainage. Holes will be plugged or other wise sealed.

8.7 Cost Impact.

Design changes to provide the desired corrosion resistance will have minimum impact on cost growth, i.e. less than \$500.

8.8 Integrated Logistic Support.

The reliability of the chassis group is excellent. Potential reliability problems created by ATLAS requirements can be addressed through vehicle chassis modifications. RAM-D considerations are minor for the corrosion resistive design planned for ATLAS. Design changes should have minor or no difference created for provisioning.

A STATE AND A STAT

ATLAS Fording Study

and consider the second states

Paragraph 9.0 Boom and End Effecters

9.1 Baseline Description.

9.1.1 Boom-3 Piece. The RT100 provides a 3 pc boom assembly (Figure 9.1.1-1).

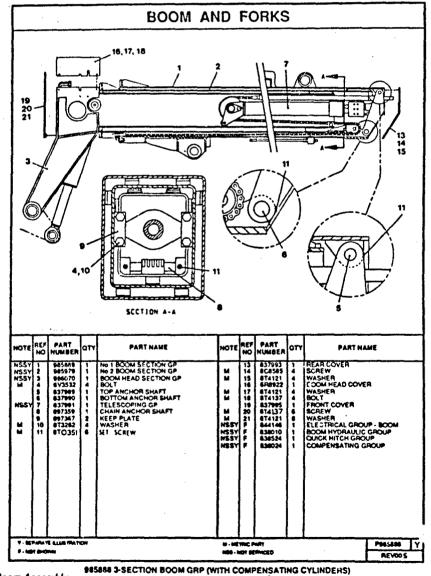


Figure 9.1.1-1 Boom Assembly

ATLAS Fording Study

The boom assembly consists of:

No 1. Boom Section Group No 2. Boom Section Group Boom Section Head Assembly Telescoping Group

/ .

Figure 9.1.1-2 Figure 9.1.1-3 Figure 9.1.1-4 Figure 9.1.1-5

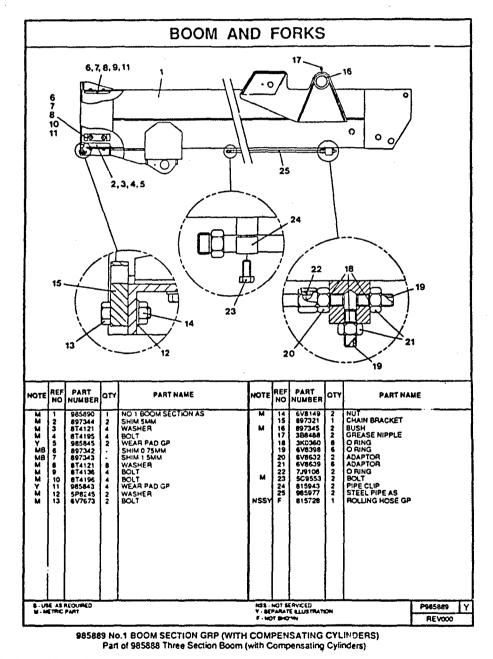
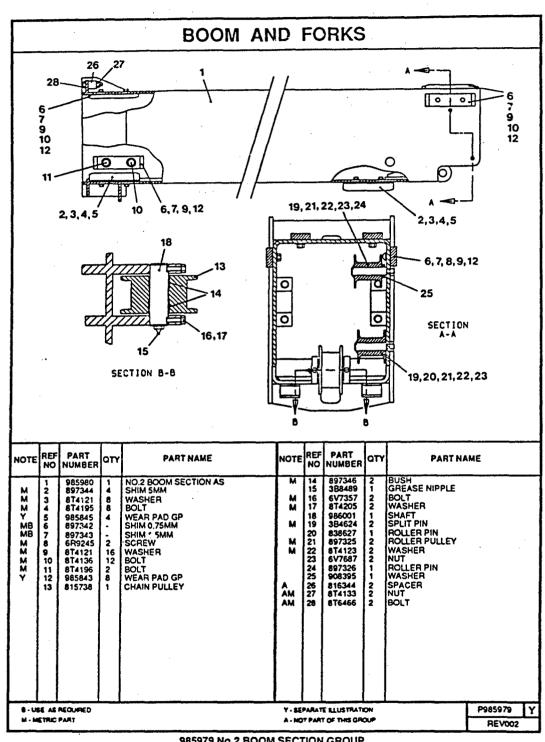


Figure 9.1.1-2 No. 1 Boom Section Group

ATLAS Fording Study

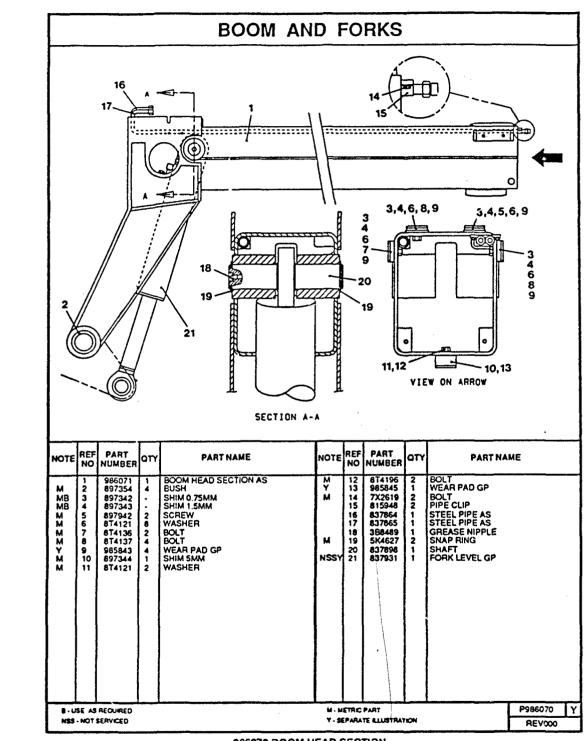
and the second of the second of a second second



985979 No.2 BOOM SECTION GROUP Part of 985888 Three Section Boom (with Compensating Cylinders)

Figure 9.1.1-3 No. 2 Boom Section Group

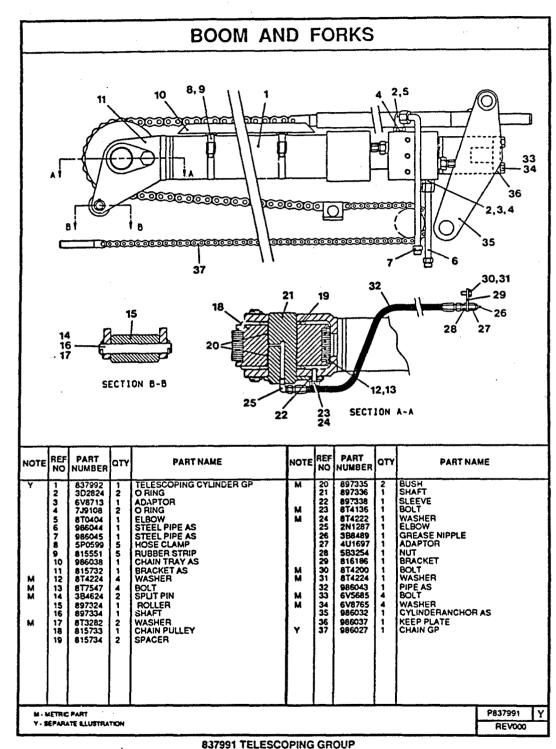
 \bigcirc



986070 BOOM HEAD SECTION Part of 985888 Three Section Boom (with Compensating Cylinders)

Figure 9.1.1-4 Boom Section Head Assembly

ATLAS Fording Study



1

Part of 985888 Three Section Boom Group (with Compensating Cylinders)

Figure 9.1.1-5 Telescoping Group

16.5

ATLAS Fording Study

9.1.2 Capacity Charts. The capacity of the RTFLs vary with lift height and forward reach, and depends on which attachment is installed and whether the machine is equipped with optional outriggers. (Note that commercial capacity charts do not provide for the 24" load center required by US Army). The RTFLs have two-dimensional "capacity charts" to show the capacities of the machine throughout the boom range. Capacity charts for the following are provided:

Ca	Figure 9.1.2-1				
Fixed (
M	"	Outriggers Up	9.1.2-2		
	"	Outriggers Down	9.1.2-3		
Tilt Ca	9.1.2-4				
N	"	Outriggers Up	9.1.2-5		
H	"	Outriggers Down	9.1.2-6		
Truss E	Boom, N	lo Outriggers and			
Outri	9.1.2-7				

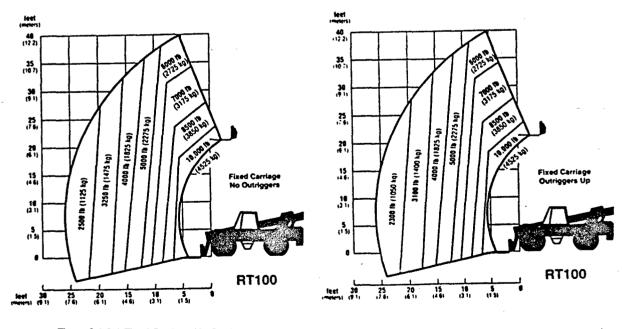
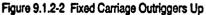
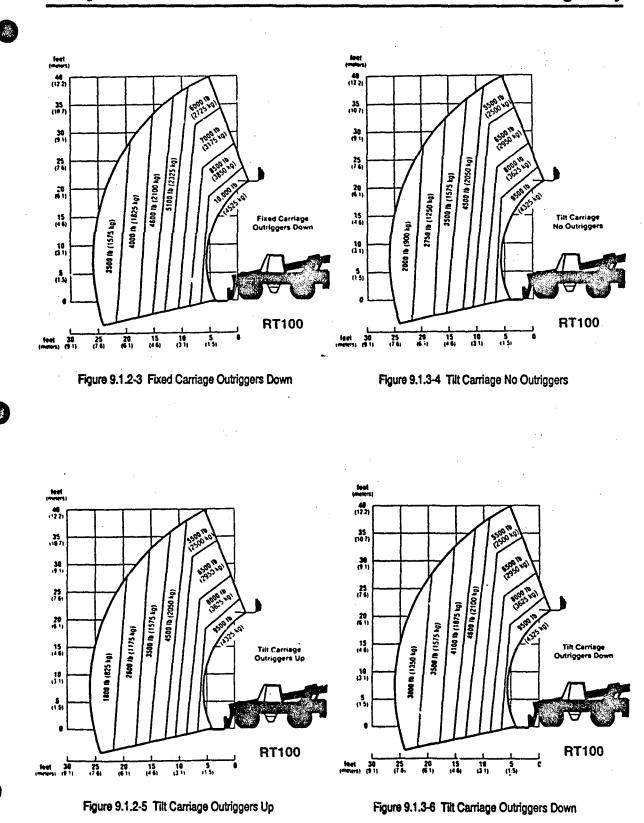


Figure 9.1.2-1 Fixed Carriage No Outriggers Figure



÷,

ATLAS Fording Study



ATLAS Fording Study

feel 55 (168) 50 (15 2) 45 (137) 40 (12 2) 35 30 25 1200 Ib (550 kg) 20 (6 1) Truss B No Outriggers and Outriggers Up or Dov 15 18 (3.1) - 3 (1.5) **RT100** feet 35 30 25 20 15 10 40

Caterpillar Inc.

Figure 9.1.2-7 Truss Boom, No Outriggers and Outriggers Up or Down

Capacity charts for the fixed carriages, side-tilt carriages and 12 ft (3.7 m) truss boom are standard. The framer's carriages use the same load charts as the narrower carriages. Both machines have the same capacity with a truss boom, since the maximum truss boom capacity is limited by the tilt linkage.

There are two sets of capacity charts: one set for machines without outriggers and a second set for machines with the optional outriggers. With the outriggers down, capacity at reach increases, up to 1,000 lb (450 kg) at full forward reach.

However, machines equipped with outriggers have slightly reduced capacities at reach when the outriggers are raised, compared to machines without the outrigger option. While setting the outriggers enhances lateral and longitudinal stability, they do not increase capacity at full height.

9.1.3 Blocks Slider. Low friction nylon slider blocks contribute to smooth boom operation.

9.1.4 Coupler. A hydraulically operated attachment coupler permits the operator to change attachment without leaving the cab.

9.2 Alternative Design.

The ATLAS boom design will be a modified version of the RT100 design. No significant changes are required to accommodate the capacity with 24 inch load centers.

9.2.1 MLRS (Multiple Launch Rocket System) Pods. Redesign of the boom head section is required to load/unload Multiple Launch Rocket System pods within the 18 inches of head clearance provided.

9.2.2 Boom Angle. The boom angle will be restricted to 45 degrees.

9.2.3 ISO Container. Maturation of the ATLAS requirements to stuff/unstuff a 40 ft. ISO container will require a new boom design.

9.2.4 Level Crowd. Level crowd is accomplished electronically instead of hydraulically extending/retracting a slider mounted boom and pedestal.

9.2.5 Corrosion Protection. The zinc rich coating will provide the desired corrosion resistance. Special attention must be provided to coating, draining, sealing, etc. of the interior of the Boom Head Section Assembly. This assembly will be subjected to periodic immersion into the salt water, were as the balance of the boom assembly will be subjected to splash and spray only.

Lubrication of the Chain Group of the Telescoping Group may provide the only corrosion protection necessary as this group will not be immersed.

Implements including forks must be coated and the corrosion coating maintained.



ATLAS Fording Study

9.3 Performance.

Implementation of the boom group will not compromise the performance of ATLAS. Maturation of the ATLAS requirements to stuff/unstuff a 40 ft. ISO container will require a new boom design.

9.4 HFE/Safety. Implementation of the 3-pc boom and end effecters will not compromise HFE/Safety.

9.5 Reliability.

Implementation of the 3-pc boom design will not compromise reliability. The reliability allocation (MTBF= 10,000 hours) may be conservative given the moderate duty cycle of ATLAS when compare to more severe commercial applications.

9.6 Producibility.

Implementation of the 3-pc boom design will not compromise producibility. Special consideration may be given to the Boom Head Section Assembly to assure that the interior of the rectangular section is primed with the corrosion resistant primer.

9.7 Cost Impact.

Implementation of the 3-pc boom design will not contribute substantially to cost growth. Some cost growth will occur, however, if the requirement to stuff/unstuff a 40 ft ISO container is added.

9.8 Integrated Logistic Support.

The simple boom design make reliability of little concern. The few internal systems (telescoping cylinder) are reliable, and durable, and designed for easy maintainance. Components inside the boom are designed for easy removal and installation. Even the telescoping cylinder can be removed without complete disassembly of the boom. Provisioning requirements are minimal for the boom.

9.8.1 Slider Blocks. Boom slider blocks have drilled and tapped holes in the ends to facilitate installation and maintenance.

9.8.2 Boom Props. Boom Props are provided to support the boom when maintenance personnel are required to work under the boom.



Paragraph 10.0 Tires

10.1 Baseline Description.

10.1.1 Tire Size. The RT100 uses 14.00 x 24 12-ply tires to match to its weight, capacity, and performance requirements. The tires are tubeless and have a polyester cord, bias-ply construction with a self-cleaning loader lug tread pattern.

10.1.2 Rim. The tires mount on 24 in (610 mm) diameter, one-piece, drop-center rims. The single-piece rims are more durable and easier to work on than split rims. Each wheel is secured to the axle hub with ten lug nuts for extra strength.

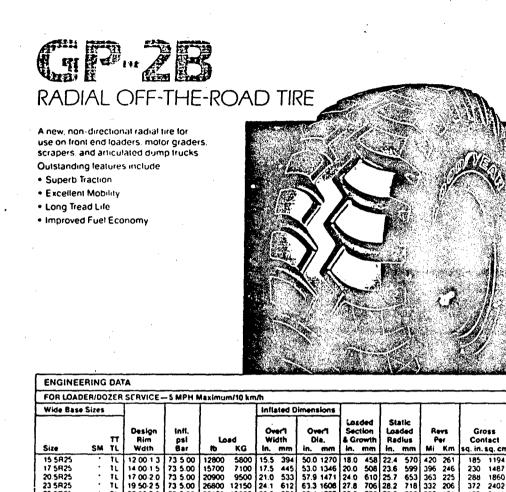
10.1.3 Hydrofill. Hydrofill is required in all tires. The hydrofill is a solution of calcium chloride (CaCl) and water that is used to add weight in the tires for additional capacity at reach and better lateral stability. The calcium chloride acts as anti-freeze to lower the freezing point of the solution. Since the hydrofill is required to achieve rated capacities, care must be taken to insure the proper amount of hydrofill is maintained in the tires.

10.2 Alternative Design.

10.2.1 Tires. The primary tire size considered for ATLAS is the 20.5Rx25 (525/80R25) to meet speed, mobility, and load requirements (Figure 10.2.1). As a result of the C130 Transportability Study, a transport vehicle configuration has been identified that will provide drive on/off within the 102" width restriction.

Page 1

ATLAS Fording Study



20.5R25	•	π.	17 00 2.0	73 5.00	20900	9500	21.0	533	57.9	1471	24.0	610	25.7	653	363	225	288	1860	
23 5R25	•	TL	19 50-2 5	73 5.00	26800	12150	24.1	612	63.3	1608	27.8	706	28.2	718	332	206	372	2402	
26.5R25	•	ŤL.	22 00-3 0	73 5.00	33100	15000	26.6	676	68.4	1737	30.3	770	29.9	759	307	191	485	3141	
40 5/75R39	••	11	32 00 4 5	73 5 00	83500	37500	41.2	1045	101.4	2576	47.8	1214	43.8	1113	201	125	1145	7387	
FOR GRADER SERVICE (G2) 25 MPH Maximum Speed																			
15.5R25	•	TL	12.00-1.3	45 3.75	5740	2900	15.5	394	50.0	1270	17.5	445	22.9	582	420	261	165	1065	٦
17 5R25	•	TL	14 00-1 5	45 3.75	6850	3450	17.5	445	53.0	1346	19.4	493	24.2	615	396	246	205	1341	1
20 5R25	•	۴L	17.00-2.0	45 3.75	9150	4625	21.0	533	57.9	1471	23.4	594	26.4	678	363	225	260	1677	- 1
23 5R25	•	1L	19 50-2.5	45 3 75	11700	6000	24.1	612	63.3	1608	27.1	688	28.9	735	332	206	337	2174	
FOR EARTHMOVER SERVICE 30 MPH Maximum/S0 km/h																			
15 5R25	•	TL	12 00-1 3	54 3 75	7850	3550	15.5	394	50.0	1270	17.5	445	22.9	582	420	261	165	1065	٦
15 5R25	••	TL.		76 5 25	9900	4550	15 5	394	50.0	1270	17.5	445	22.9	582	420	261	165	1065	- 1
17 5R25	•	TL	14 00-1 5	54 3.75	9100	4125	17.5	445	53.0	1346	19.4	493	24.2	615	396	246	205	1341	- 1
	••	TL		76 5 25	12000	5450	17.5	445	53.0	1346	19.4	493	24.2	615	396	246	205	1341	- 1
20 5R25	•	ΤL	17 00 2 0	54 3 75	12300	5600	210	533	57.9	1471	23.4	594	26.4	678	363	225	260	1677	
	••	11		76 5 25	16100	7300	210	533	57.9	1471	234	594	26.4	678	363	225	260	1677	i
23 5R25	•	11	19 50 2 5	54 3 75	15700	7100	24 1	612	63.3	1608	27.1	688	28.9	735	332	206	337	2174	1
	••	11		76 5 25	20400	9250	24 1	612	633	1608	27.1	688	28.9	735	332	206	337	2174	1
26 5825	•	11	22 00 3 0	54 3 75	19800	9000	26 6	676	68.4	1737	29.5	750	30.7	780	307	191	365	2355	i
	••	- TL		76 5 25	25400	11500	26 6	676	68 4	1737	29 5	750	30.7	780	307	191	365	2355	
40 5/75839	••	- 14 J	32 00 4 5	76 5 25	64000	29000	412	1045	101.4	2576	46 9	1191	44.0	1118	201	125	915	5899	

Static

Loaded Radius in. mm Revs Per Mi Km

Gross

Contact sq. in. sq. cm



Figure 10.2.1 The 20.5Rx25 is the tire size considered for ATLAS

ATLAS Fording Study

The 17.5Rx25 (445/80R25) tire is an optional choice. It would provide an easier solution to C130 transportability, but at the expense of reduced mobility and vehicle stability. Depending on final ATLAS requirements, this could be a viable option. Each of the tire configurations are bi-directional to provide equal mobility forward or reverse. English designations of tire sizes refer to Goodyear tires tailored to off-road service. Metric designations refer to mobile crane tires with the high speed capability required of ATLAS.

10.2.2 Rims. The ATLAS rims for the 20.5Rx25 tires would be a new design to provide the desired rim-offset. In the standard configuration, the rim offset would be outboard providing a vehicle width of 108". In the C130 transport configuration, the rims-offset would be inboard providing a vehicle width of 101".

10.2.3 Hydrofill. Hydrofill would not be required to provide the ATLAS lift capacity.

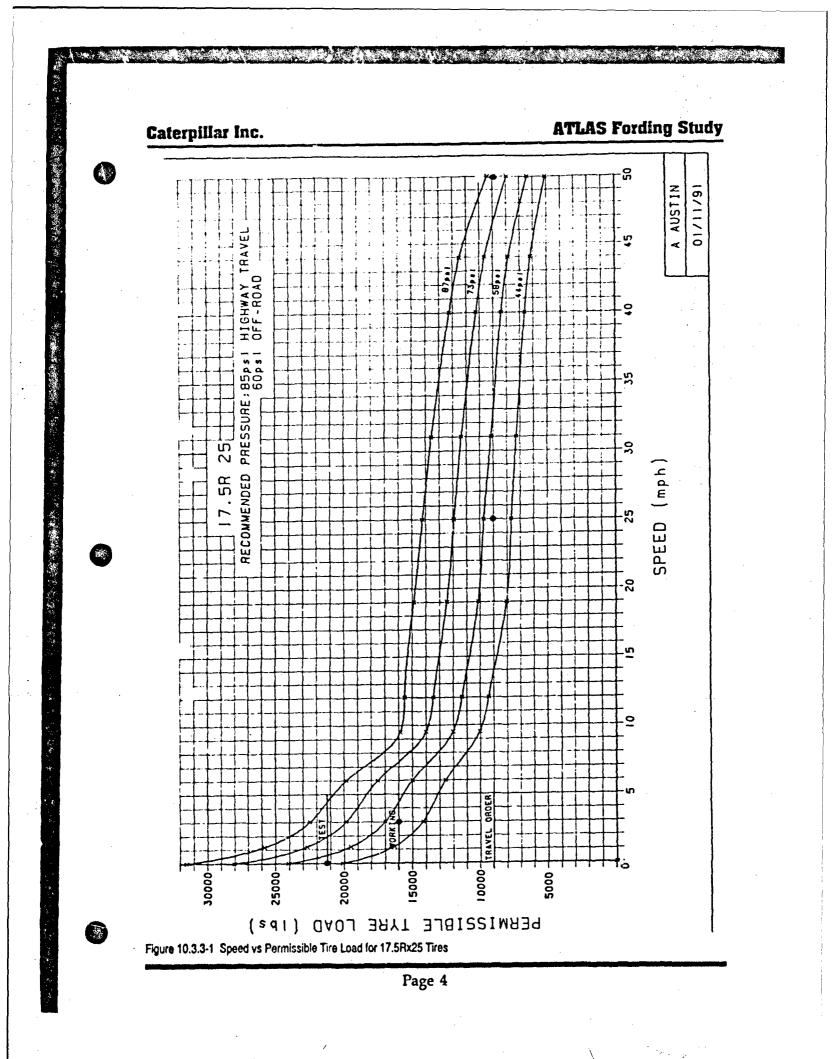
10.3 Performance.

The tire size, load rating, braking requirements and operating pressure significantly impacts each aspect of the vehicle design including speed, lift capability, mobility, etc.

10.3.1 Capacity. The 20.5Rx25 tires provides a larger footprint for working in the soft underfooting typical of LOTS operations. The 17.5Rx25 tires require higher pressure for equal lift capacity. Increasing tire pressure reduces the footprint which decreases mobility.

10.3.2 Weight. Weight growth associated with implementation of the larger tires is a result of performance requirements for capacity, speed and mobility.

10.3.3 Vehicle Speed. The rolling radius of the tire impacts vehicle speed. The ATLAS requires an Load Rating E for sustained highway performance without cooling stops. Figures 10.3.3-1 and 10.3.3-2 provide Speed vs Permissible Tire Load at various tire pressures for the 20.5Rx25 and 17.5Rx25 tires respectively.

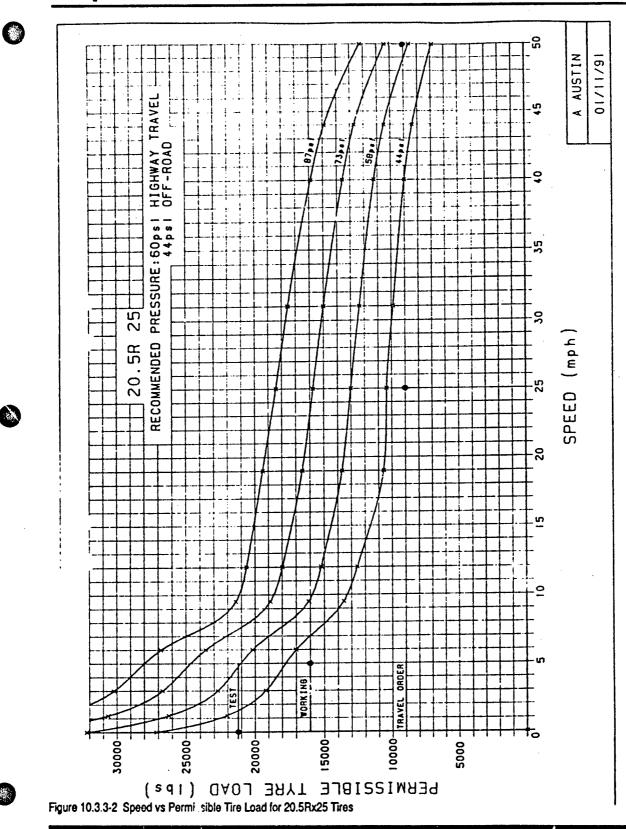


State States

2

ATLAS Fording Study

١.



ATLAS Fording Study

The 20.5Rx25 tires are favored over the 17.5Rx25 tires to obtain the desired speed with an powertrain ratio of approximately 10:1. Secondly, the 20.5Rx25 tire would operate at lower tire pressures for both on and off road operations.

10.3.4 Fuel Consumption. Fuel consumption is influenced by tire selection, but would be dominated by factors other than tire size.

10.3.5 Vehicle Height. Vehicle height would be sensitive to tire selection. The 20.5Rx15 would increase the height of the ATLAS by 2 inches over the 17.5Rx15 tire without other configuration changes to the vehicle to offset the increase.

10.3.5 Ground Clearance. The 20.5Rx15 would increase the ground clearance of the ATLAS by 2 inches over the 17.5Rx15 tire. This increase provides a direct improvement in mobility. Final ground clearance will be determined by selection of the transmission.

10.3.6 Space Claim. Each of the tires will have different space claim requirements to provide the same steering angle per Figures 10.3 6-1 and 10.3.6-2 for 0° steering angle and 37 and 27.79 degrees respectively.

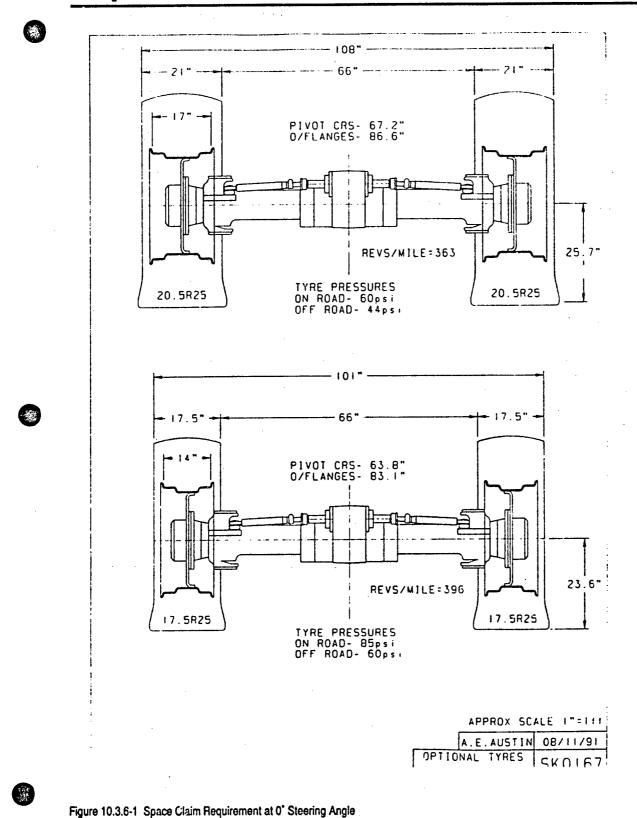
ł

ATLAS Fording Study

and the second second second second

· ...

• • • •



an and a transferrate of the second state of the second state of the

ATLAS Fording Study

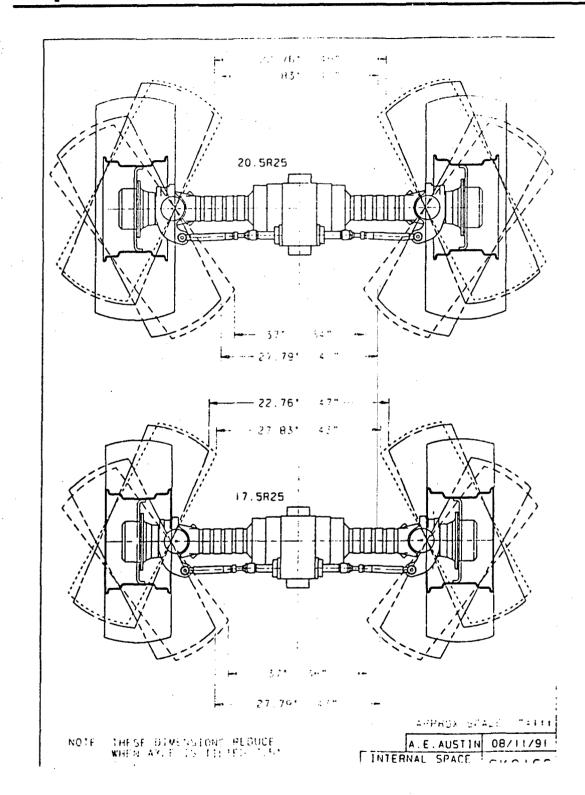


Figure 10.3.6-2 Space Claim Requirement at 37° and 27.79° Steering Angle Respectively

Page 8

. . . .

.....

10.4 HFE/Safety.

Implementation of either the 17.5Rx25 or the 20.5Rx25 tire has not projected impact of HFE/Safety.

Implementation of the 20.5Rx25 tire with a 108" vehicle width will improve side slope stability of ATLAS and reduce the probability that the operator can overturn the vehicle.

10.5 Reliability.

The 20.5Rx25 tire will be more durable (reliable) for ATLAS loading conditions. Either tire provides comparable side wall construction to the earth moving (off-highway) and maintaining the durability of the tire.

10.6 Producibility.

Implementation of either tire has no impact on producibility.

10.7 Cost Impact.

The increased procurement cost of the 20.5Rx25 tire, about \$750 per vehicle, will be offset by the lower owning and operating costs. Implementation of the 20.5Rx25 tire will reduce the life cycle costs of the axle.

10.8 Integrated Logistic Support. Reliability is enhanced with the alternative, 20.5Rx25 tires, with corresponding enhancement to the maintainability. Provisioning is not effected.

ATLAS Fording Study

Paragraph 11.0 Microclimate Control

11.1 Baseline Description.

The baseline cooling system would either be fans, or an air conditioning system. Neither baseline meets the requirements for under garment cooling necessitated by the wearing of chemical protective overgarments.

11.2 Alternative Designs.

Several alternative technologies appear to meet the ATLAS microclimate cooling requirements. These cooling systems are currently in production, though not in large quantities.

11.2.1 The Cooling System. The cooling technologies are of three basic configurations. Vapor compression (air conditioning), thermo-electric, and thermal exchange systems all provide the cooled medium, either liquid or air, which is pumped through tubing to a cooling undergarment worn by the operator. Each system is briefly discussed.

<u>11.2.1.1 Vapor Compression</u>. Vapor compression uses standard engine mounted compressor, freon based cooling. This system would either require extensive modification to a vehicle mounted air cooling system, or a separate specialized cooling system dedicated to the micro-climate cooling role.

<u>11.2.1.1.1 Advantages Of Vapor Compression</u>. Advantages of vapor compression cooling are that the system would be highly integrated to the ATLAS system, the system would use existing air conditioner technology and the system be maintained at the unit or direct support level of maintenance.

ATLAS Fording Study

<u>11.2.1.1.2 Disadvantages Of Vapor Compression</u>. The primary disadvantages are reduced reliability, and higher cost (both initial and life cycle) than other alternatives. The system is also directly integrated into the vehicle, eliminating any possibility for off vehicle use.

<u>11.2.1.2 Thermo-Electric Cooling</u>. Thermo-electric cooling uses the property of (Peltier Effect) electric current passed t⁺ rough two dissimilar metals creating a temperature differential between the metals, to generate a cooling effect. The power requirements of this system are not expected to require a larger alternator from the baseline configuration. A pump or fan is required to transport the medium (water or air) to the vest of the operator.

<u>11.2.1.2.1 Advantages Of Thermo-Electric System</u>. The primary advantage of this system is its high reliability. The pump or fan unit, which transports water or air from the cooling unit, through tubing, to the cooling vest worn by the operator, is the only element with moving parts. The thermo-electric cooling unit itself has very high reliability. The unit could be mounted, when needed, in the cab. This would require an electric source (outlet) located within the cab. The system also has the advantage of being portable, for a limited time, if external battery packs are available. Some portions of the thermo-electric unit may be damaged while the system still operates effectively. Thermo-electrics may also be used for heating without modification.

<u>11.2.1.2.2 Disadvantages Of Thermo-Electric System.</u> The primage disadvantage of the thermo-electric option is its inherent reduction in cooling effect as ambient temperature increases. Thermo-electrics create a temperature differential between dissimilar metals. Temperatures on both hot and cold metal increase as ambient temperature increases. So the cooling effect is reduced as ambient temperatures increase. The cooling effects of thermo-electrics are still excellent at 120 degrees F. Ambient temperatures above this level will rapidly reduce the cooling effect. So, the acceptability of this type of cooling system will depend on the requirements of ATLAS. The thermo-electric unit is not complex, but could not be repaired at the using unit.

ATLAS Fording Study

<u>11.2.1.3 Thermal Exchange.</u> The third cooling method, thermal exchange, uses an external source for cooling medium (usually ice, though more exotic mediums such as phase-transition crystals may be used). The system consists of the same vest and pump type units used in the ' wo preceding concepts. The difference is that cooling tubes, in an insulate d container, provide the cooled liquid for cooling effect. Several reports on this system, in use at the National Training Center, are provided. The reports indicate that the ice cooling units needed new ice only once every two days. Thermal exchange units have a much higher inherent capacity to cool in extreme climates. Thermal exchange exchange is also less costly.

<u>11.2.1.3.1 Advantages Of Thermal Exchange.</u> The major advantage of this system is its simplicity of design, creating an increase in reliability and reduction in cost. A major advantage of this system, over vapor compression and thermo-electrics, is the much higher cooling effect which may be created by the system. Vapor compression and thermo-electric's are limited by the size of their compressor and electric cooling units respectively. Though the pumps can easily transport more coolant, the systems have strict limitations on cooling rate. The ice based thermal exchange system easily responds to extreme temperature requirements with a simple increase in pump rate. Minimal vehicle power is needed to operate the system. This system is easily adaptable for off vehicle use, with minimum battery power necessary to transport the cooling liquid to the user.

<u>11.2.1.3.2 Disadvantages Of Thermal Exchange</u>. The major disadvantage of thermal exchange systems are their reliance on external sources of coolant and the periodic need to recharge the units' coolant. Requirements for ice could be infeasible in a war environment.

<u>11.2.1.4 Combination Coolir.g Unit.</u> A point to be noted is that a combination cooling unit could be developed if required. An example would be a thermo-electric unit for temperatures up to 120 degrees, with provisions to allow attaching an ice based cooler (the insulated container and lines) to the lines leading to the thermo-electric units pump. This provision could be included, if the requirement exists, with only minor cost impact on the base thermo-electric cooling unit. This could meet the rare requirement for use in extreme temperatures up to 160° F.

ATLAS Fording Study

11.2.2 The Cooling Medium. Cooled liquid or air are the two mediums used to actually cool the operator. Each has advantages and disadvantages. Both methods are in use and both appear to successfully cool the operator.

<u>11.2.2.1 Liquid Cooling</u>. Liquid cooling has the advantages of increased thermal efficiency and a liquid "clean" environment. Though not documented, liquid cooling is thought to reduce human. Liquid cooling systems, typically either thermo-electric or thermal exchange systems, would most likely have the entire unit within the cab. This location reduces the possibility of the system developing leaks.

The major disadvantage of liquid cooling is the inability to reduce humidity effects on the operator (this is a comfort factor). Other disadvantages are:

- a) A potential increase in maintenance requirements (over an air cooled system) if the system is use 1 infrequently.
- b) An increased risk of system failure should the cooling garment/tubing leak (leaking could compromise the effectiveness of the chemical protective overgarment).
- c) The space requirements of the cooling system, should the cooling unit be mounted within the cab. The space problem could be minimized through either cooling unit or cab design.

<u>11.2.2.2 Air Cooling</u>. Air cooling has the advantage of being able to reduce the humidity within the operator's environment.

The major disadvantage is the requirement to filter air prior to reaching the operator. Leaks in tubing could allow chemicals to directly violate the integrity of the chemical protective overgarment. A further disadvantage is the reduced thermal efficiency of air as a cooling medium. It requires a larger, costly cooling unit. A third disadvantage, is the potential dehydration of the operator due to the convective cooling of the air. A 3% water loss contributes to a decrease in operator performance.

ATLAS Fording Study

11.2.3 Cooling Vest. The cooling system transports cooled air/water to a location under the chemical protective overgarment. This usually consists of a vest worn under the overgarment. The vest can be augmented with either cooling pants and/or a cooling hat. Generally the vest is used for general cooling. Interestingly, the cooling hat seems to provide a similar level of cooling as the entire vest. This is due to the increase requirements for body cooling created by the insulating layer of body fat in the torso. The head cooling hat seems to provide the same amount of overall body cooling. A question has been raised about head cooling and possible head aches this system could create. Actual use of head coolers, with no body vest (this is currently done commercially for auto racing), has indicated no problems with headaches or other physiological problems. It is recommended that the Government consider using head and vest cooling as opposed to just vest cooling. This should provide an acceptable level of cooling, whereas the vest just alone provides what may be termed an acceptable level of cooling.

11.3 Performance.

The alternative designs all provide an acceptable level of cooling, up to the 120° F. Above 120°F, thermo-electrics degrade in performance. Vapor compression cooling can cool above this level but require a larger compressor and stronger tubing required throughout the system. This would have a negative effect on system reliability and cost. Thermal exchange has the highest potential level of cooling, limited only by the requirement for external sources of coolant. Vapor compression has some potential effect on engine performance. Thermo-electrics and thermal exchange should have no effect on engine performance. Air cooling requires a substantial increase in cooling unit size to compensate for air cooling inefficiencies.

11.4 HFE/Safety.

Human factor engineering issues are important to micro-climate cooling. Specifically, what constitutes "cool" is still open to wide interpretation. This basic issue and the current lack of standards, create a risk of the Government not receiving a capability level desired. The major objective is to erwure the operator's performance is not degraded while working in a high ambient temperature environment in chemical protective overgarments.

11.4.1 Cooling Capacity. A recommended baseline is to require 300 watts of cooling to the operator. This would put limits on the system's ability to perform when additional cooling is required, but would establish a performance specification for whatever system is chosen.

11.4.2 Cooling Medium. This determination would drive the choice of cooling methods. In particular, the question of dehydration effect on user performance should be analyzed (to determine its relevance) before making a decision on liquid vs. air cooling. Additionally, the small amount of sweating when liquid cooling should be analyzed to determine if this is relevant.

11.4.3 Cooling System Hardware. A human factor question relates to the tubing running from the cooling unit, under the overgarment, to the user. Questions of how to allow user movement, while not providing excessive tubing must be addressed.

11.4.4 Control Logic. The interface desired between the cooling unit and the user is another operating issue. A manual cooling adjust (thermostat) is simplest, but requires effort and thought to monitor. A method of automatically controlling the level of cooling/comfort may be difficult.

ATLAS Fording Study

11.4.5 Vest Durability. The durability of the cooling vest is a concern. Due to the complicated nature of the vest, its durability is limited. As long as extended use (months) is not anticipated, this is not a problem. The anticipated level of use should be determined by the Government to ensure that an acceptable level of durability is designed into the cooling vest.

11.4.6 Other Cooling Considerations. No requirement for operator cooling, other than micro-climate cooling, has been identified. A requirement for non-chemical environment cooling could require standard air conditioners or a duty cycle for the micro-climate cooler in a non-chemical environment.

11.4.7 Safety. The largest safety related question has to do with potential violations to the integrity of the protective overgarment. Though potential violations are unlikely, the risk to the individual is great.

<u>11.4.7.1 Safety-Liquid System</u>. The liquid system can reduce the effectiveness of the protective suit should it leak and saturate the overgarment with liquid. This may provide an avenue for chemicals to reach the user. If the system leaks freon gas injested through the engine generates phosgene gas (in small quantities).

<u>11.4.7.2 Safety-Air System</u>. The air system can leak, and with negative pressure effects, directly transport chemical agents to the user.



11.5 Reliability.

The reliability of all three cooling alternatives is high. Vapor compression would have the lowest inherent reliability, with thermo-electrics higher and thermal exchange having the highest reliability. The durability of the cooling vests is limited and may create reliability concerns, should the expected level of use be high. By its permanent installation on the ATLAS, the vapor compression system would be exposed to weather and compressor use throughout its life. The thermo-electric and thermal exchange systems could be stored off vehicle, but would require periodic preventative maintenance/inspection. None of the systems has seen extensive use, so long term reliability of the alternatives is uncertain. Reliability allocation is 4000 hours.

11.6 Producibility.

Producibility of all systems has been proven through commercial and military use. Several producers surged to support various militaries during Desert Storm.

11.7 Cost Impact.

The baseline vehicle does not contain a micro-climate cooling feature. Cost impact may be high, approximately \$10,000, depending to the alternative desired. Additionally, cost impact for vehicle interface will be a factor (this includes any required cab interface and mounting considerations). An additional cost will be a sociated with any decision to permanently mount the cooling system, or to store off vehicle. If external sources of coolant (ice) are available, the thermal exchange system is by far the least expensive. If no external source of ice is available, then thermal electrics becomes the least expensive, for environments up to 120 degrees F. Should extreme temperature cooling be required, then either thermal exchange or vapor compression will be necessary.

ATLAS Fording Study

11.8 Integrated Logistic Support.

Reliability of the micro-climate cooling systems is relatively high. Interestingly, the most expensive alternative, vapor compression, is the least reliable and the least expensive, thermal exchange, has the highest reliability. Other performance related factors will determine which system is appropriate. The relationship for reliability holds true for maintainability also. The vapor compression system would have the worst maintainability and highest life cycle cost, the thermal exchange system the best maintainability and lowest life cycle cost, with the thermo-electric system falling in between.

Durability of the cooling systems is high for all alternatives. But, a weak point in all systems is the cooling vest. The vest will not hold up well to extended use, due to the need for a thin layer of material between the cooling tubes/passages and the user. Additionally, all systems have limited puncture resistance.

New provisioning will be required for this system.

ATLAS Fording Study

Paragraph 12.0 Stabilizers

12.1 Baseline Description.

Hydraulic outriggers (also known as stabilizers) are available as an option. The advantage of outriggers is that they enhance lateral and longitudinal stability, and significantly increase lift capacity at maximum reach. Disadvantages include higher cost, slower cycle times, and slightly lower capacity at reach when the outriggers are raised compared to a standard machine.

The outriggers bolt to the main frame so once they are down the chassis cannot be leveled with the frame leveling control. On uneven terrain, the frame should be leveled first, then the outriggers should be lowered into place and adjusted to ensure the chassis remains level. Like frame leveling, the outriggers should not be operated after the boom is raised.

12.2 Alternative Design.

Outriggers, though precluded from consideration on the 6K RTFLs per MIL-T-5058, may have a role within ATLAS with respect to LOTS operations and are anticipated increase in lift/reach requirements. Historically, outriggers have been considered to increase cycle times and provide additional opportunities for operator error.

Stabilizers provide a lift capability at full boom extension that would not otherwise be possible with an RTFL of that GVW and boom reach. For example, the lift capacity of the RT100 increases by 67% at full boom extension.

Stabilizers would not be required for typical lift and carry operations. Stabilizers may be required when ATLAS lift at reach capabilities are increased.

1

Caterpillar Inc.

ATLAS Fording Study

12.2.1 LOTS Operations. LOTS operations, conducted in sand with soft underfootings, may required a stabilizer to lift loads at full reach. The stabilizers would share the front axle load to reduce front tire sinkage.

12.2.2 Stabilizer Design Consideration. ATLAS stabilizers could be commercial systems like the one shown in Figure 12.2.2-1 (optional commercial outrigger group) or they could be tailored to the requirements of ATLAS.

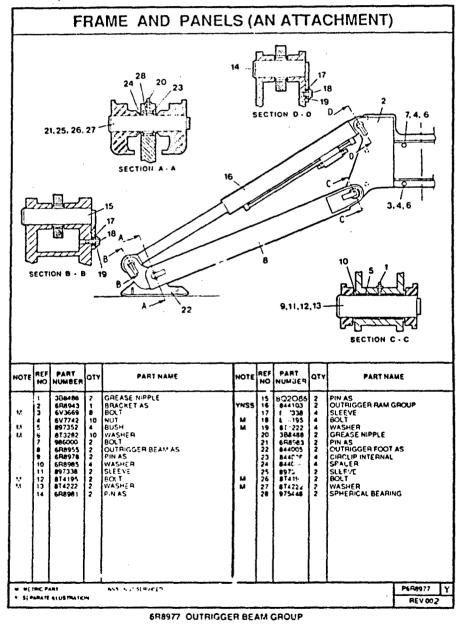


Figure 12.2.2-1 Optional Commercial Outrigger Group

Page 2

ATLAS Fording Study

12.3 Performance.

Outriggers would influence the performance of ATLAS.

12.3.1 Capacity. The ATLAS boom design would provide the desired lift capacity of 4000 lbs at 20.5 ft and 10,000 lbs at 4 ft. Lift capacity would be less at minimum extension when the stabilizers were not in use. Commercially the lift capacity of the RT100 is reduced by 200 lbs at minimum extension.

Paragraph 9.0, Boom and End Effectors provides the capacity charts, with and without stabilizers, for the RT100.

12.4 HFE/Safety.

10.00

Implementation of stabilizers introduce an additional operation that the operator would be required to perform (Figure 12.4-1). Adding to the operator typically increases the probability for operator error. Maturation of the ATLAS load sensing and boom controls in combination with a stabilizer sensor may provide the opportunity to address safe-fail limitations.

Use of Outriggers (if equipped)

Incorrect use of outriggers could cause an accident resulting in injury or death. Do not use

the outriggers except as described in the following instructions

Machines equipped with outriggers are capable of handling heavier loads at some boom angle and length combinations when the outriggers are lowered.

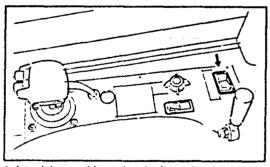
The stability of the machine at all boom angle and length combinations is increased when outriggers are used, but DO NOT rely on stability alone as a guide to maximum capacity. Maximum capacity is determined by factors other than stability at some boom angles and lengths.

The outriggers must always be used in conjunction with the correct load chart and the capacities shown should never be exceeded.

The boom must be fully retracted and lowered to the travel position before lowering the outriggers. Ensure the areas adjacent to the outriggers are clear and will provide uniform support for the weight of the machine and intended load.

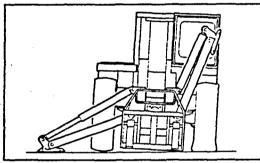
Use the following procedure for lowering the outriggers:

Figure 12.4-1 Part 1 Operator instruction for use of outriggers.



1. Level the machine using the frame level control and the level indicator. Do not use the frame level control after lowering the outriggers.

^{2.} Press the panel switch (1) to lower the right outrigger. Hold the switch until.....



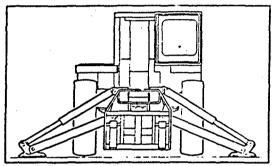
.....the outrigger lifts the right tire clear of the ground then release.

Observe the area where the outrigger is moving to ensure there are no obstructions.

Figure 12.4-1 Part 2 Operator instruction for use of outriggers.

ATLAS Fording Study

3. Press the panel switch (2) to lower the left outrigger. Hold the switch until.....



.....the outrigger lifts the left tire clear of the ground. Adjust the position of the left outrigger to level the machine then release the switch. The front wheels must remain just clear of the ground.

Observe the area where the outrigger is moving to ensure there are no obstructions.

Before raising the outriggers, fully retract and lower the boom to the travel position. Ensure that both outriggers are FULLY raised before travelling with the machine.

12.5 Reliability.

Stabilizers would add to the overall complexity of ATLAS and decrease to the reliability of the system. This reduced reliability may be accommodated within the reserve allocation.

12.6 Producibility. Producibility of stabilizer group would be comparable to the commercial outrigger group. Only vehicle assembly time would be moderately impacted by implementation of a stabilizer group.

and the set of the set

12.7 Cost Impact.

Implementation of a stabilizer group would contribute to procurement and life cycle costs. Application of commercial components, i.e., hydraulic cylinders, lines, volves, etc., would minimize the cost growth. New design would be limited to the structural components of the stabilizer group, though changes in the chassis design may be considered to meet ATLAS requirements.

12.8 Integrated Logistic Support.

Reliability would be reduced by addition of this system. Maintenance costs would also rise correspondingly. The degradations are offset by the increased performance potential of ATLAS. Provisioning costs would also increase slightly.

ATLAS Fording Study

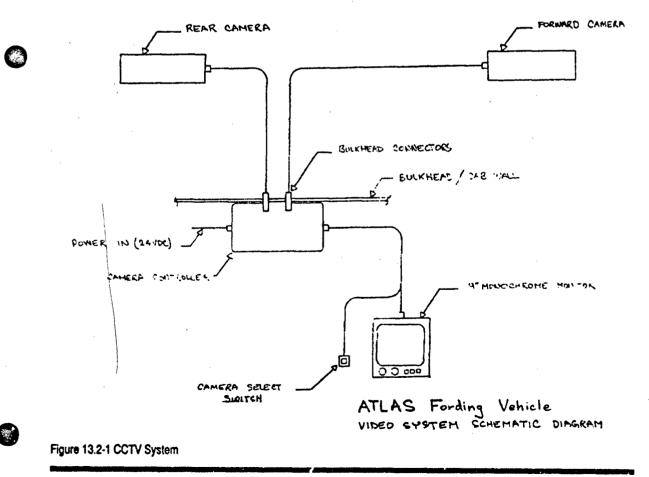
Paragraph 13.0 CCTV

13.1 Baseline Description.

The RT100 does not provide for a Closed Circuit Television (CCTV).

13.2 Alternative Design.

The CCTV system (Figure 13.2-1) considered provides supplemental vision to assist the operator in locating and engaging the load (within an ISO container for example), traveling, and finally placing the load in a safe and reliable manner.



ATLAS Ferding Study

Caterpillar Inc.

The CCTV consists of:

- 2 Series 200 cameras with pedestals
- 1 Series 200 camera control unit
- 1 9-inch high resolution video monitor
- 1 Camera select switch
- **1** Set of external cables and connectors
- **1** Set of bulkhead connectors
- **1** Set of internal cables and connectors
- **1** Set of mounting hardware
- 1 User manual

13.2.1 Camera-Forward. The forward looking camera is mounted on the upper most boom extension over looking the loading forks. This camera has approximately 70° field of view and is in focus throughout the full working distance of the vehicle. The auto iris camera lens and camera automatic glare control (AGC) system allows effective operation from full sunlight to head light lit night conditions.

13.2.2 Camera-Rearward. The rear camera is mounted such as to give a wide angle view of the center and right rear areas of the vehicle. Field of view of this camera may be adjusted by the appropriate selection of camera lenses.

13.2.3 Cabling. Cabling to both cameras is enclosed in a chemical resistant flexible plastic jacket. The stainless steel camera connectors and bulkhead fittings are secured to the cable jacket with hermetic seals. All cables, connectors, camera housings and fittings are waterproof to 100 m and can withstand repeated exposure to harsh chemical and corrosive environments.

Cable routing to the forward camera will be provided through the boom; alternately, a side mounted reel may be considered if insufficient space or technical problems are identified.

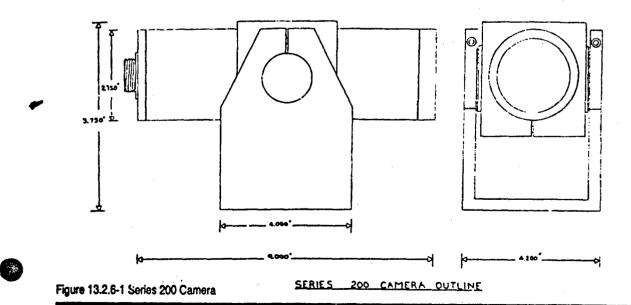
ATLAS Fording Study

13.2.4 Controller. The camera controller is mounted inside the vehicle cab and is also watertight with watertight connectors. This unit provides regulated power to the cameras in addition to providing the camera selection function. A switch on the vehicle instrument panel provides the camera select command to the camera controller.

13.2.5 Monitor. The 9-inch video monitor is mounted behind the vehicle instrument panel. Power and video signals are provided to this unit from the camera controller. A LEXAN faceplate protects the monitor CRT from damage and also provides a measure of glare reduction for outside light. Resilient shock mounts are fitted to limit the vibration to the monitor.

13.2.6 Series 200 Camera. The series 200 camera (Figure 13.2.6-1) is an environmentally secured, high resolution, monochrome, Closed Circuit Display unit. The external camera housing and mount is fabricated from 6061 grade aluminum with hard anodized finish. Stainless steel or mild steel is also available with a variety of finishes and paint options.

The 200 camera housing is totally environmentally sealed and is submersible to a depth of 100 m. Stainless steel and glass electrical bulkhead fittings are rated at 2000 psi operating pressure with gold on gold contact material for reliable low noise operation.



ATLAS Fording Study

Caterpillar Inc.

Series 200 Camera Specifications:

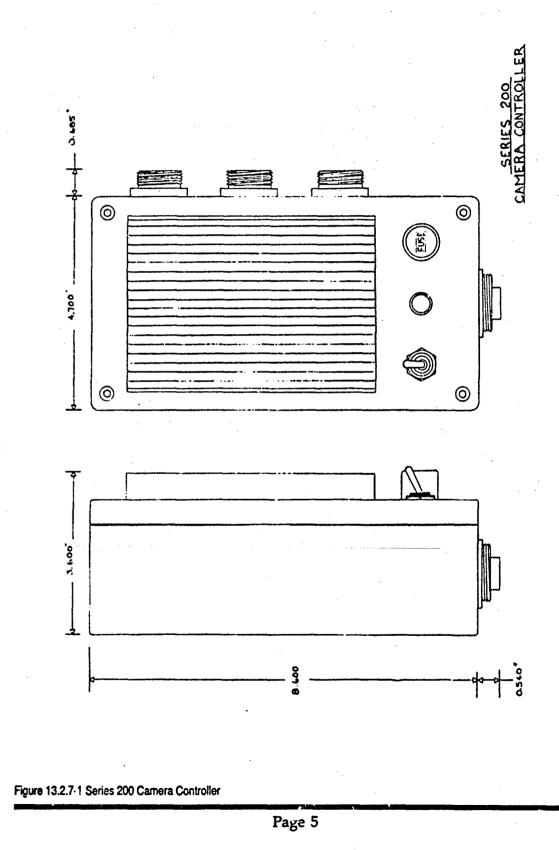
Physical Dimensions:	4.2" (w) x 5.75" (h)			
Weight:	8.9 lbs (aluminum)			
Vibration Resistance:	7G (11 Hz to 200 Hz)			
Shock Resistance:	70G (non-repetitive)			
Operating Temperature:	-20 to +50 degrees C			
Environmental:	waterproof to 100 m			
Power Consumption:	50 watts (with heater)			
Resolution:	570 (H), 485 (V) TV lines			
Sensitivity:	400 LUX			
S/N ratio:	50 dB or better			
Minimum Sensitivity:	0.5 LUX			
"C" mount lens:	auto iris			

13.2.7 Series 200 Camera Controller. The series 200 camera controller accepts input from two cameras. Regulated and filtered 12 volt power is supplied to the cameras from this unit. The camera controller is housed in an environmentally sealed, water-tight aluminum case and fitted with waterproof connectors. (Figures 13.2.7-1 and 2) Two configurations of this unit are available for in cab mounting. One configuration is designed to accept bulkhead connectors (Figures 13.2.7-3 and 4) mounted through the vehicle cab wall (Figure 13.2.7-5).

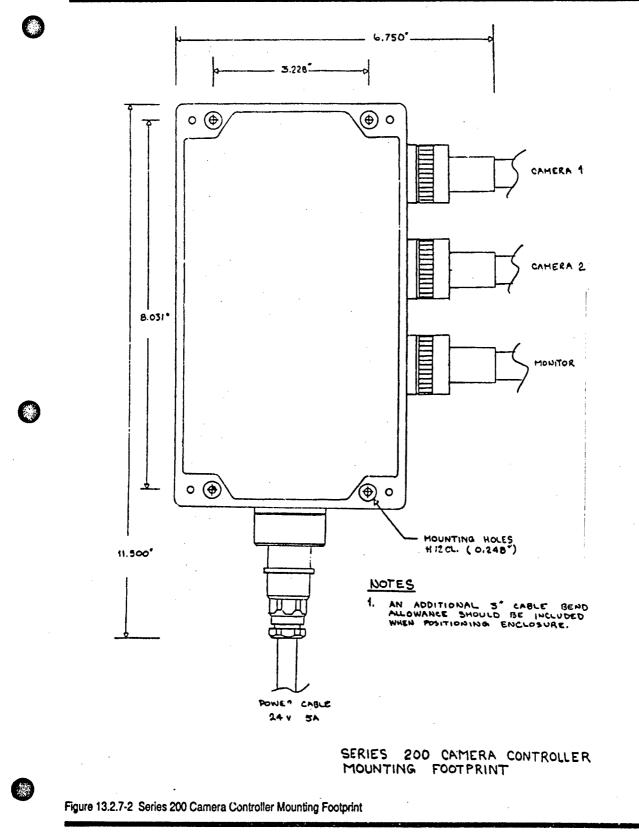
Series 200 Camera Controller Specifications

8.6" x 4.7" x 3.6"
5.6 lbs
7G (11 Hz to 200 Hz)
70G (non-repetitive)
-20 to +50 degrees C
watertight
150 watts (with heater)
24 volts 5.5 amps (max)

ATLAS Fording Study



1



Page 6

. .

٠,

ATLAS Fording Study

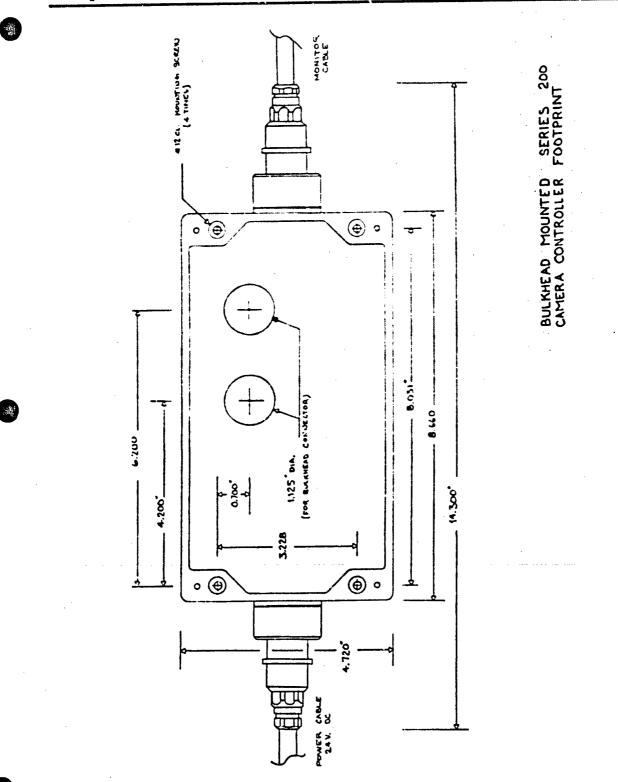


Figure 13.2.7-3 Bulkhead Mounted Series 200 Camera Controller Footprint

ATLAS Fording Study

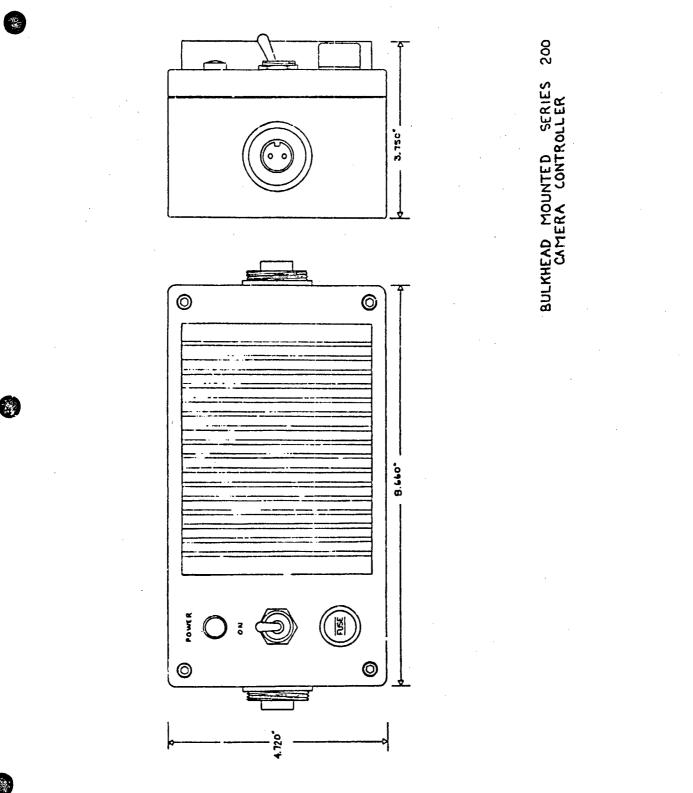
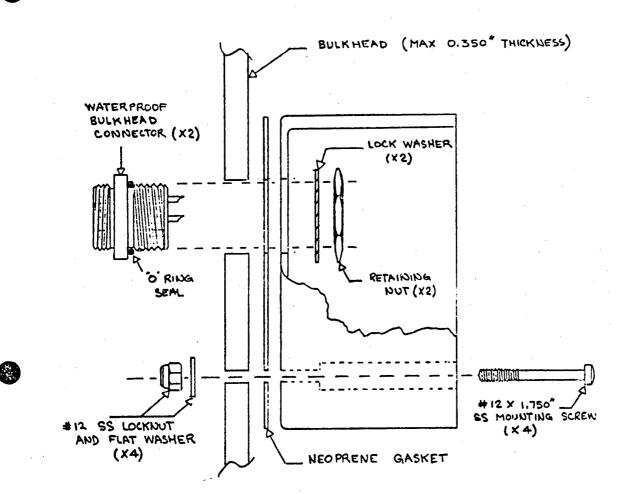


Figure 13.2.7-4 Bulkhead Mounted Series 200 Camera Controller

ATLAS Fording Study



INSTALLATION DETAIL

BULKHEAD MOUNTED SERIES 200 CAMERA CONTROLLER

Figure 13.2.7-5 Installation Detail For Bulkhead Mounted Series 200 Camera Controller

13.3 Performance.

Implementation of the CCTV system is not expected to impact ATLAS performance.

13.4 HFE/Safety.

Implementation of the CCTV system is central to the safe and reliable operation of ATLAS. Supplemental vision is required to assist the operator in locating and engaging a load in a darkened environment, i.e., an ISO container. Subsequently, the operator is required to negotiate the vehicle in reverse with the load until clear of the ISO container; the rear vision system will permit the operator to assure that the intended path is clear of personnel and materials.

The CCTV system is projected to have a duty cycle of 3-5%.

13.5 Reliability.

Subsystem reliability allocation for the CCTV system is MTBF=3000 hours.

13.6 Producibility.

Implementation of the CCTV system will not compromise the producibility of ATLAS.

13.7 Cost Impact.

Implementation of the ATLAS CCTV system has substantial impact on procurement costs. The estimated cost increase is \$10,000. Improvements in electronic technology are constantly reducing maintenance and support costs.

13.8 Integrated Logistic Support.

The CCTV system is modular in design. It is anticipated that repair by replacement of modules will by appropriate. It may be desirable to conduct a repair versus discard analysis when developing the maintenance philosophy for this system. The reliability and availability of the system is good. Most of the CCTV components will be externally mounted, aiding in maintainability. The proper protection of the cameras is a minor reliability concern to be addressed.

Attachment 1 Corrosion Resistant Coating Technology

1.0 Corrosion Resistant Coating.

A corrosion resistant coating has been identified with a corrosion resistance capability that substantially mitigates the corrosion associated with the extensive operation in the surf zone required by ATLAS.

Implementation of this coating technology precludes from further consideration the use of exotic materials (stainless steels) and processes (plating) and minimizes procurement and life cycle costs. The coating technology provides the desired corrosion protection at a fraction of the cost of alternate materials and processes. Implementation of the coating technology will avoid a 40% to 50% increase in procurement costs, 10% to 15% reduction in development costs, and a 15% to 30% reduction in owning and operating costs.

1.1 Discriminator. The primer incorporates an extraordinary, zinc-dust, rich primer similar to MIL-P-26195 with an epoxy polyamide base similar to MIL-P-53022 to provide corrosion resistance in excess of 1000 hours per ASTM B117. Limited testing has been conducted up to 1500 hours.

1.2 Compatibility - CARC Paint. This primer is compatible with a MIL-A-46168 top coat. Alternate primers, compatible with CARC topcoats, do not provide the desired level of protection. Alternate primers that provide the corrosion resistance are not compatible with CARC topcoates. CARC provides a top coat of a material with high molecular density that may be decontaminated after being subjected to chemical, biological, and nuclear warfare agents. The principal decontaminant is MIL-D-50030H Military Specification for Decontamination Agent, DS2.

1. A.S.

2.0 Application.

The CARC topcoat will eliminate contact between the salt water and the zinc-rich primer, hence the primer will not experience corrosion. At such time that the top-coat is violated, the zinc primer will begin to corrode (general corrosion) in the presence of salt water. After the primer is violated and the steel base metal is exposed to the salt water, a galvanic cell is established with the zinc primer corroding preferentially to the steel base metal.

The zinc-rich primer provides a sacrificial material that will corrode preferentially to steel (and other materials) in the presence of salt water. As a result of this preferential corrosion, the corrosion of the base material will be minimized.

The corrosion rate for the zinc rich coating will be greater than the corrosion rate for the steel substrate, hence the corrosion damage will be limited largely to the sacrificial coating. The corrosion by-products of the zinc may be readily identified visually. Corrosion of the steel substrate will occur only after the sacrificial coating has been depleted.

Upon identification by visual inspection, the corroded area may be cleaned and recoated with the zinc rich primer and topcoat thus preventing any substantial damage to the component.

2.1 Corrosion Resistance, Zinc. The corrosion resistance of zinc in salt water is influenced by the amounts of dissolved salts, principally chlorides and sulfates, in the water. The high chloride content of salt water (representative of the salt spray test) would normally accelerate the corrosion rate, but the presence of magnesium and calcium ions retards the corrosion rate.

ATLAS Fording Study

The effect of time of exposure on the corrosion rate in natural waters indicates that the corrosion rate in seawater exceeds that of freshwater, but after a period of two years the rate of corrosion in salt water decreases to approximately the rate of fresh water.

2.2 Corrosion Protection. The corrosion resistance of zinc compares very favorable with other coating materials when immersed in saltwater. Side-by-side evaluations conducted with aluminum-, cadmium-, lead-, tin-, and zinc-coated specimens resulted in failure of all coatings within 2 years except for the zinc coated specimens which were evaluated for an additional 4 years. After 6 years of immersion, the coatings were just ceasing to provide complete protection. The zinc coating was consumed at a rate of 0.5 ounces-year/ft².

Typically, zinc coating would not be employed alone to provide the necessary protection for marine structures, but would be employed in conjunction with other protective measures. With respect to ATLAS, the zinc rich primer is recommended in combination with a top coat of CARC paint that minimizes the exposure of the primer and base metal to the corrosive environment.

2.3 Noble Coating. Noble coatings are an option for general protection of the ATLAS structure. Noble coating such as chrome, cadmium, etc, exhibit a corrosion rate less than steel in salt water. At such time that the coating is violated and the steel substrate and coating are exposed to salt water, a galvanic cell is formed. At that time, the steel will corrode preferentially resulting in substantial pitting/corrosion damage to the substrate. The corrosion rate (damage rate) is accelerated by the relatively large cross section of the coated area as compared to the very small cross sectional area of the exposed substrate.

3.0 Processing.

b

The processing requirements are consistent with the processing of MIL-A-46168 coating including preparation of the base material, application of the primer, and application of the top coat though several considerations exist. The dry film coating thickness is limited to 20 mils to provide for field repair of the coating by US Army personnel.

3.1 Base Metal Preparation. The base (ferrous) material must be grit blasted to a white or near white condition as defined by the National Association of Corrosion Engineers (NACE). The base material may then be subjected to a conversion coating of either zinc or iron.

3.2 Primer Application. The primer requires a longer cure under all temperature and humidity conditions than comparable MIL-P-26195 and MIL-A-46168 coatings. Various combinations of lower temperatures and higher humidity will retard curing until more favorable atmospheric conditions exist or until the product is subjected to a forced cure. Curing will be completed between 24-72 hours under common atmospheric conditions.

3.3 Top Coat Application. The top coat should be applied within 2 weeks after the primer has cured in order to provide the desired intercoat adhesion. At such time that this span of time is exceeded, an intermediate (epoxy polyamid) primer of approximately 3.0 mils (Dry Film Thickness (DFT)) thickness) is required to wet the previously primed and cured primer surface of the part. The top coat may then be applied without loss of intercoat adhesion. The coating may be subjected to a scribe test after 72 hours to determine the acceptability of the adhesion of the coating to the base material.

ATLAS Fording Study

4.0 E-Deposition Coating.

Electrolytic deposition (E-coats or E-deposition) may be considered in lieu of the zinc rich primer. Technical direction was provided to consider E-coats to address crevice corrosion. E-depostion coatings will coat crevices inaccessible to normal spray paint processes. Unfortunately, E-coat primers are not compatible with CARC topcoats. E-coat primers also possess the following shortcomings:

- a) E-Deposition painting system typically costs in excess of \$1,000,000 for a new installation and is not generally available within the construction equipment industry.
- b) Base metal must be exceedingly clean to provide the desired coat incorporating a 7-stage process for mill scaled metal, metal with welding slag, cast/forged surfaces, etc. (near white blast, wash, rinse, conversion coat, rinse (de-ionized water), prime. (Residual oxides and contamination left on the surface of the part (in particular crevices) disrupts the flow of the electrical current causing imperfections within the paint.)
- c) Top coat should be applied within 30 days. After 30 days, the part will require a MIL-P-53022 primer to obtain the necessary intercoat adhesion. (Primers typically have very good wetting capabilities.)
- d) Primer degrades rapidly in sunlight (under-roof stowage only)
- e) Previously painted surfaces must be thoroughly cleaned (high-pressure, hot alkaline spray or steam clcan) pricr to CARC topcoat.



5.0 Material Considerations.

A number of supplemental material considerations identified in this paragraph must be addressed with maturation of ATLAS.

5.1 Environmental Considerations. Two considerations have been identified at this time that will significantly impact the cost of providing the desired corrosion resistance. The cost impact will be influenced by a number of factors such as current equipment, location of the manufacturing facility, EPA legislation, etc.

<u>5.1.1 Hazardous Material</u>, Zinc (as are most metals) is considered a hazardous material; hence, the waste water, filters, cleaning fluids, etc. shall be treated as hazardous waste. Dry-filter paint booths are recommended. Treatment of waste water may preclude consideration for water wash paint booths in particular if a number of paint booths share a common water reservoir.

<u>5.1.2 Volatile Organic Content (VOC)</u>. The primer has a volatile organic content of 3.64 lbs/gallon which exceed federal guidelines of 3.5 lbs/gallon. The VOC (the measure of a material to air pollution) may become a major processing consideration depending upon the local and regional air pollution board and, to a lesser extent, on state and/or federal clean air mandates. Reductions in the VOC content are being addressed by the paint manufacturer.

5.2 Usage. The rough terrain fork lift will require approximately 5 gallons of primer and topcoat. Each weighs approximately 18 lbs/gal.

5.3 Scribe Test. The scribe test provides a destructive, pass-fail in-process method for assessing the primer and intercoat adhesion.

ATLAS Fording Study

The scribe test should be run between 24 and 72 hours after the top coat has been applied by a trained, quality control technician. The scribe shall provide a very sharp knife edge. The technician will provide a simple cross-hatch pattern with an intersection of nominally 60 degrees with the scribe maintained perpendicular to the surface. The scribe mark introduces a defect through the thickness of the coating. Subsequently the technician will apply a scribe tape and upon removal of the tape determine the acceptability of the adherence of the coating.

Some government agencies required a cross-hatch pattern at an intersection of 90 degrees. In either situation, failure of the coating is defined as the loss of 2 or more squares.

5.4 Aluminum. Pretreatments, MIL-A-8625 (Anodizations) or MIL-C-5541 (Chemical Conversion), are recommended for aluminum alloys followed by a wash primer per DOD-P-15328 (typically TT-C-490 Type III) with a MIL-P-53022 primer and MIL-C-46168 top coat.

5.5 Plastic/Rubber. The compatibility of plastic or rubber with the coating must be established to minimize or preclude degradation of the mechanical properties of the base material. The primary consideration for determining the retention of the coating will be the movement of the plastic or rubber parts.

Though plastics and rubbers may be coated, those components that are subjected to large deflections, eg. boots, hydraulic hoses, engine/cab mounts, etc., will spall the coating with time. Simply the CARC coatings are stiffer and relatively brittle compared to the non-metallic plastic/rubber component. The difference in relative stiffness of the two materials introduces shear stresses at the interface that cause the spalling of the top coat.

Attachment 2 Surf Zone Stability

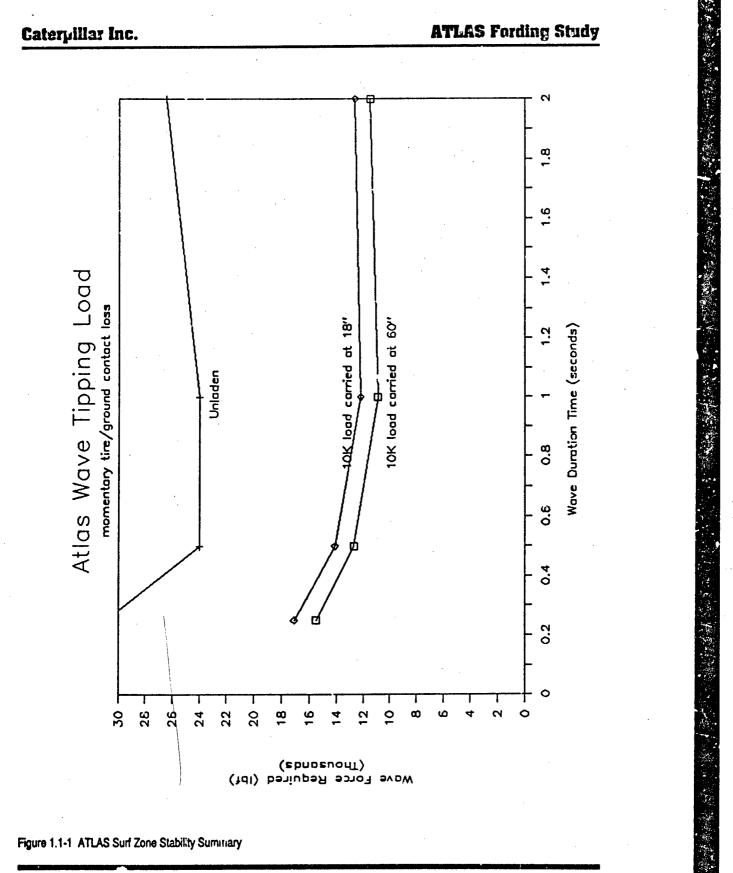
1.0 Introduction.

The ATLAS rough terrain fork lift is required to negotiate a surf zone during a LOTS operation. Exiting the surf zone ladened with a 10,000 lb. payload carried at heights of 18 and 60 inches exposes the rear of the vehicle to a wave which may tip the vehicle forward.

A simple (quick-look) 2-dimensional analysis was initiated to investigate this operational scenario. The tipping load for this analysis is defined as the wave loading required to cause momentary loss of contact between the tire and the ground. Three loading conditions have been investigated; the 10,000 lb load carried at 60 inches may be compared to each an unloaded condition with the forks at 60 inches and the same 10,000 lb load carried at 18 inches. Three loading conditions have been investigated:

- a) 10,000 load carried at 60 inches;
- b) Unloaded with the forks at 60 inches, and;
- c) 10,000 load carried at 18 inches.

1.1 Results. ATLAS stability is not compromised when operating in a surf zone. Figure **1.1-1** summarizes the results of this analysis. Substantial wave force (>10000 lbs) and duration (=1 second) is required to tip the ladened vehicle with the load at 60 inches.



1.2 Recommendation. The ATLAS is sufficiently stable under the conditions assessed hence no additional analysis is required at this time. With maturation of the program, the government should review the configuration of ATLAS and anticipated LOTS operational scenarics with respect to this analysis and determine the need for additional analysis.

1.3 Operational Considerations. For purposes of this evaluation, the vehicle was assumed to be operating in a V-shaped bay where a wave would build as it progressed into the bay and break over exposed beach. The vehicle with the suspension system locked out is assumed to be operating on level grade (as opposed to a more naturally occuring positive grade). More importantly, the vehicle is modeled out of the water yet impacted at by a wave at the rear of the vehicle. Positive or negative effects of buoyancy are offset with respect to each other.

2.0 Model Development.

The ATLAS vehicle model was assembled to address the concern of waves impacting the vehicle while in the surf. The simple 2D dynamic vehicle model consists of a rigid-body (vehicle with and without payload) with vertical and fore-aft springs (tires).

2.1 Wave Loading. The wave loading is applied in a horizontal direction to the rear of the vehicle over a period of time. This loading function is represented by the positive half of one cycle of a sine wave function. The duration of the loading function was varied from 0.25 to 2.0 seconds.

2.2 Tipping Load. The tipping load is defined to be the load required to cause momentary tire/ground contact loss.

ATLAS Fording Study

2.3 Assumptions. The simple analysis makes several assumptions which tend to give a more conservative result than a more complex analysis would provide. The major assumptions include;

- a) the vehicle is traveling on level ground,
- b) the wave impact force acts horizontaliy,
- c) the beneficial damping provided by water enveloping the vehicle is ignored (only tire damping is included),
- d) the vertical component (secondary loading) of the waveloading and vehicle reaction are assumed to offset each other.
- e) the damping of the beach sand is ignored.

2.4 Tire Stiffness. The ratio of fore-aft/vertical tire stiffness was decreased as the wave loading time increased, simulating the loading rate sensitivity of the tires. As the loading rate increases the tires will exhibit a less compliant or stiffer response, i.e. the loading rate is inversely related to loading time.

Dynamic Spring Rate and Dampening data was provided by the Goodyear Technical Center for this evaluation (Figures 2.4-1 and 2.4-2).

For purposes of this evaluation, tire stiffness of 4600 lbf/in. represented the application of the 17.5R25 and 20.5R25 tires at 50 and 40 psi tire pressure respectively. All four tires of the vehicle are the same and pressured equally.



ATLAS Fording Study

Caterpillar Inc.

DYNAMIC SPRING RATE AND DAMPING

			RADIAL TIRE:	17.5R25 RL-2F	L-2	
SPEED (MPH)	PRESSURE (PSI)	E LOAD (LB)	DAMPING FACTOR (%)	DAMPING COEFFICIENT (LB-SEC∕IN)	FREQUENCY (HZ)	SPRING RATE (LB/IN)
	50	13400	1.85	14.4	1.88	4600
10	50	13400	1.24	9.6	1.87	4560
20	50	13400	1.10	8.5	1.87	4560
5	75	15600	1.67	16.2	2.60	6110
10	75	15690	1.13	11.0	2.00	6110
20	75	15600	0.62	6.0	2.00	6110

rigure 2.4-1

DYNAMIC SPRING RATE AND DAMPING

			RADIAL TIRE:	20.5R25 RL-2F	L-2	
SPEED (MPH)	PRESSURE (PSI)	LOAD (LB)	DAMPING FACTOR (%)	DAMPING COEFFICIENT (LB-SEC/IN)	FREQUENCY (HZ)	SPRING RATE (LB/IN)
5	40	15700	1.93	16.3	1.73	4600
10	40	15700	1.26	10.6	1.71	4500
20	40	15700	1.22	10.2	1.71	4500
5	75	20900	1.80	22.1	1.86	7160
10	75	20900	1.15	14.1	1.86	7160
20	75	20900	1.19	14.6	1.86	7160

Figure 2.4-2

t,

2.5 Vehicle Speed. Vehicle speed was assumed to be 5 mph.

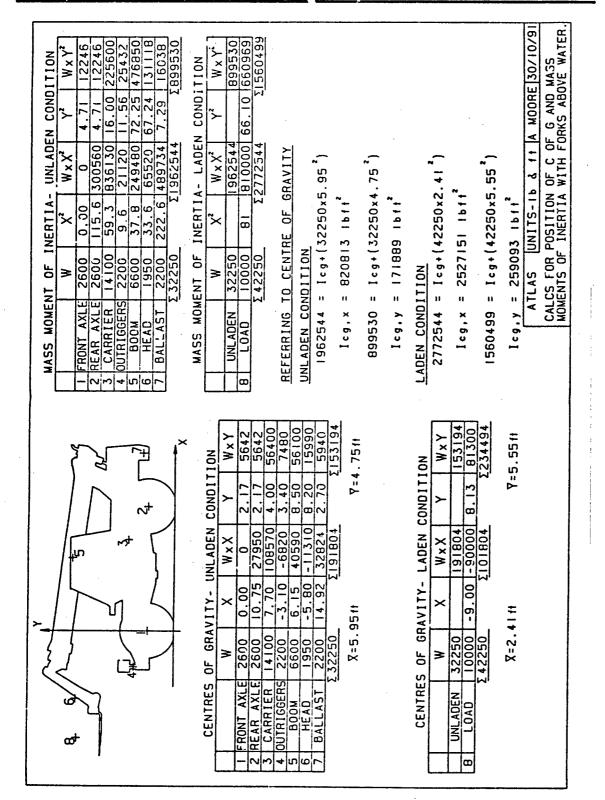
2.6 Vehicle Data. Coordinates are referenced with respect to the ground line at front axle. The positive X axis is pointing to the rear of the vehicle. Figure 2.6-1 provides Center of Gravity and Mass Moment of Inertia data used for this analysis and summarized in Table 1.

Vehicle Weight	Tii Cente r of		Wave Stiffness	Damping	Impact
(<i>lbf</i>)	X	Ŷ	lbf/in	lbf/(in/sec)	Height (ft)
Unladen 32,250	5.95	4 .75	4600	14.4	3.75
Laden(60) 42,250	2.41	5.55	4600	14.4	3.75
Laden(18) 42,250	2.41	4.72	4600	14.4	3.75

Table 1. Model Inputs



ATLAS Fording Study



2

Figure 2.6-1 Center of Gravity and Mass Moment of Inertia Data

ATLAS Fording Study

2.7 Analysis of Results. The tipping load for this analysis was defined to be the load required to cause momentary tire/ground contact loss. Due to the inherent stability of the vehicle, these loads are not substantial enough to completely overturn the vehicle. However, under these loading conditions, the operator may experience a momentary loss of steering of the vehicle as the tires lose contact with the ground. Wave loading required to tip the vehicle is marginally reduced when the load is carried at a height of 60 inches as opposed to 18 inches (Reference Figure 1.1-1).

The timeplots (Figures 2.7-1-12) included show the vehicle response has not settled out after 10 seconds inferring that the vehicle may be sensitive to a second wave load. Operationally, the vehicle would not be expected to operate in the surf zone exceeding the period defined by the frequency of the waves.

This continuing response is due to the low damping rates for the tires alone. If the damping effects of the water and sand on the vehicle were considered, this vibration would decay much more rapidly.

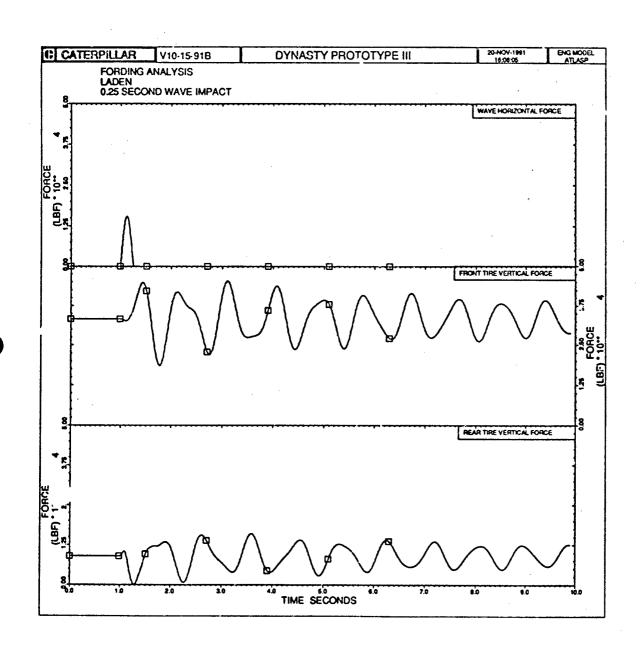
This simple analysis provides a conservative estimate of the horizontal wave force required to tip the vehicle. The overall minimum wave force required to cause any tire/ground contact loss was over 10,000 lbf.

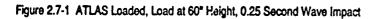
Wave Impact Time (sec)	Fore-Aft/Vertical Tire Stiffness	Tipping Loads (lbf) Unladen (60") Laden (60") Laden (18")			
0.25	1.0	31,000	15,500	17,500	
0.50	0.5	24,000	12,700	14,500	
1.00	0.25	24,000	10,900	12,500	
2.00	0.1	26,500	11,500	13,000	

Table 2. Analysis Runs and Results

ATLAS Fording Study

5





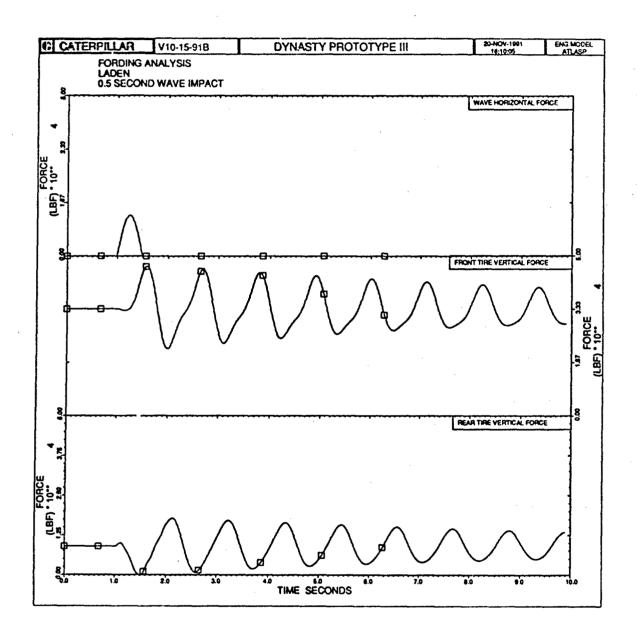


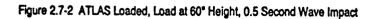
eret.

ġ,

13

ATLAS Fording Study





ATLAS Fording Study

CALCULAR DAY

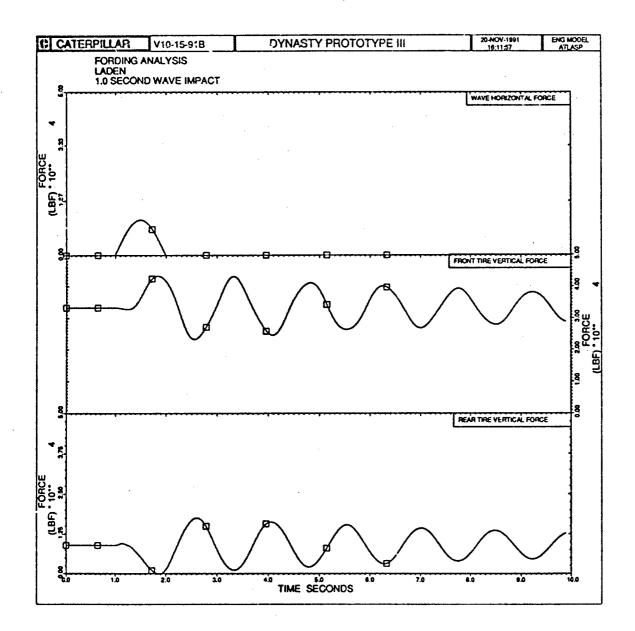


Figure 2.7-3 ATLAS Loaded, Load at 60" Height, 1.0 Second Wave Impact



ATLAS Fording Study

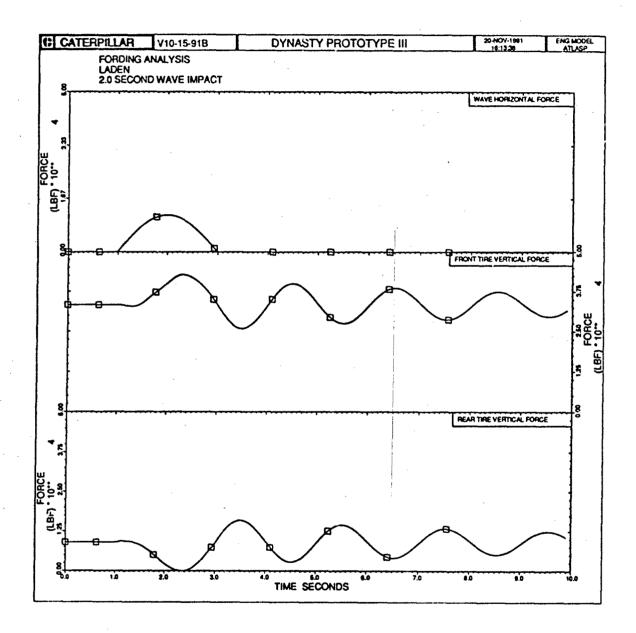


Figure 2.7-4 ATLAS Loaded, Load at 60" Height, 2.0 Second Wave Impact

ATLAS Fording Study

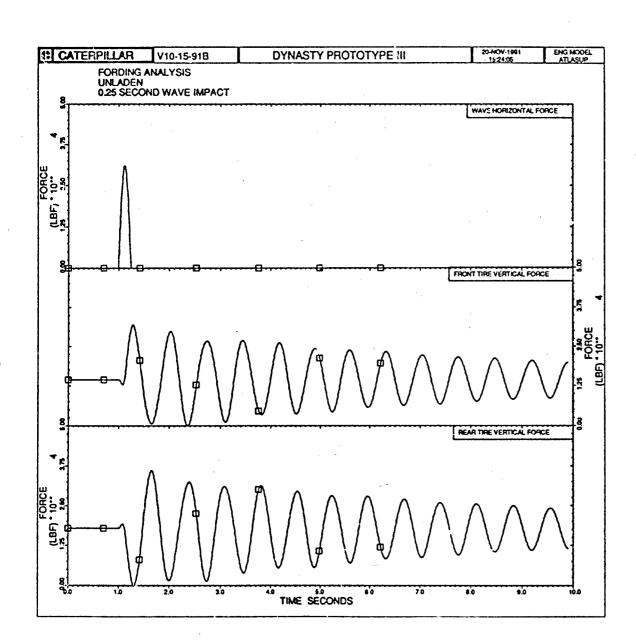


Figure 2.7-5 ATLAS Unloaded, 0.25 Second Wave Impact

3

ATLAS Fording Study

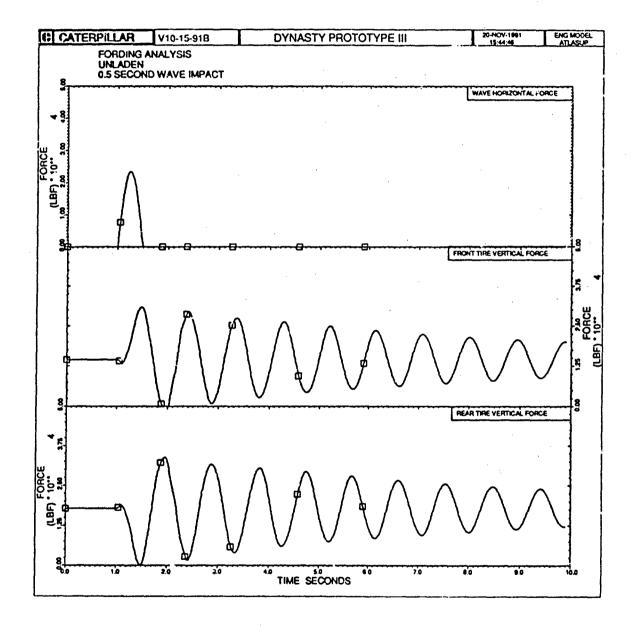


Figure 2.7-6 ATLAS Unloaded, 0.5 Second Wave Impact.

ATLAS Fording Study

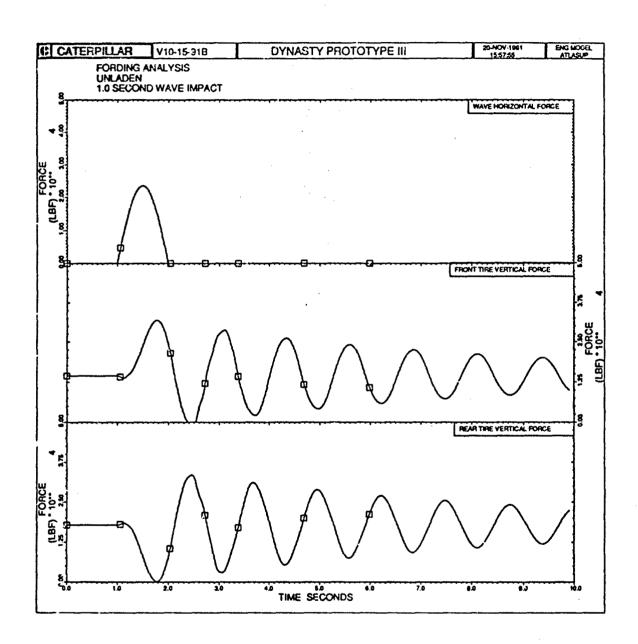


Figure 2.7-7 ATLAS Unloaded, 1.0 Second Wave Impact

Page 15

ATLAS Fording Study

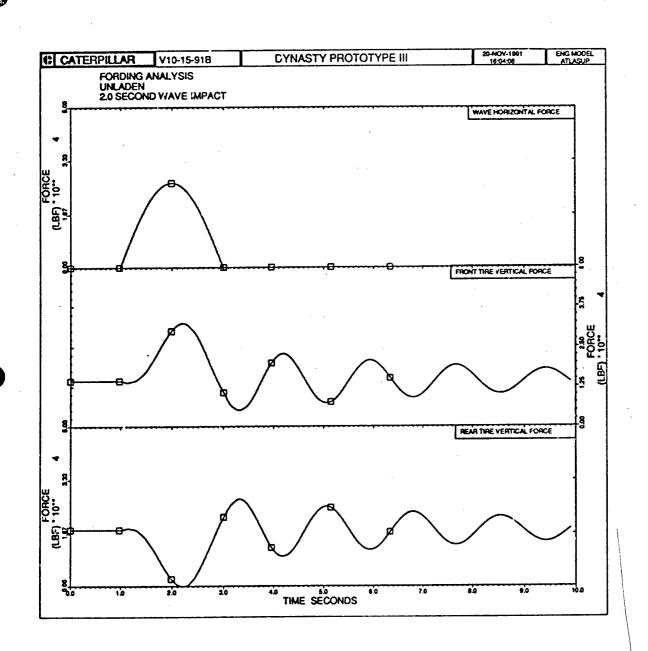


Figure 2.7-8 ATLAS Unloaded, 2.0 Second Wave Impact



ATLAS Fording Study

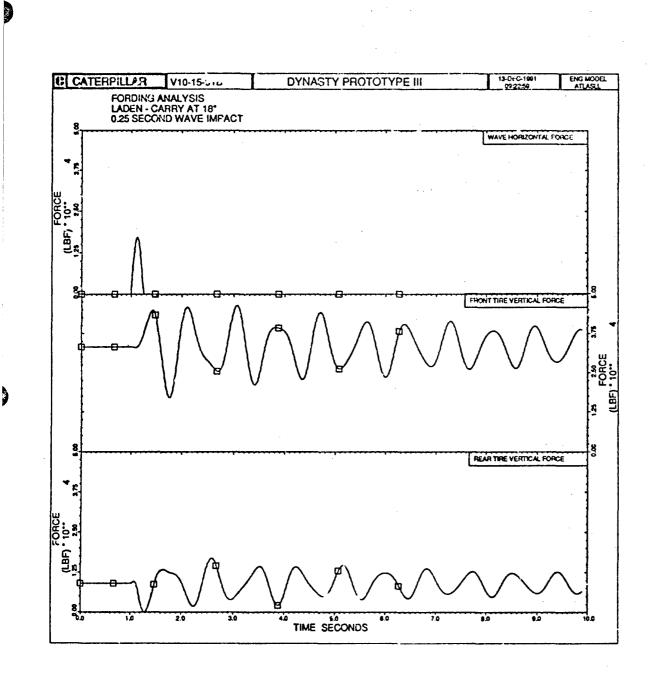


Figure 2.7-9 ATLAS Loaded, Load at 18" Height, 0.25 Second Wave Impact

Page 17

)

ATLAS Fording Study

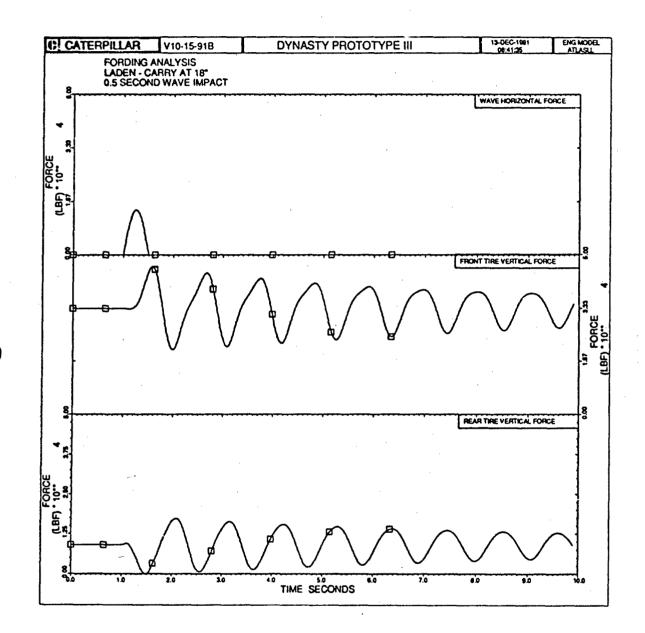


Figure 2.7-10 ATLAS Loaded, Load at 18" Height, 0.5 Second Wave Impact

Sec.

ATLAS Fording Study

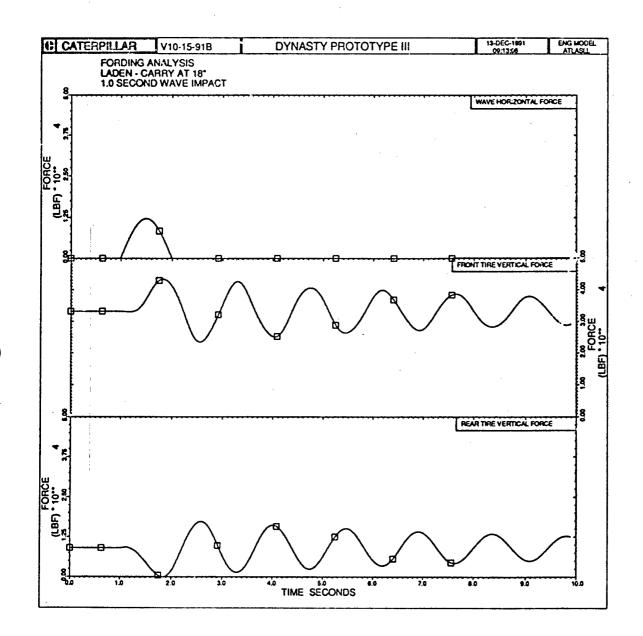


Figure 2.7-11 ATLAS Loaded, Load at 18" Height, 1.0 Second Wave Impact

ATLAS Fording Study

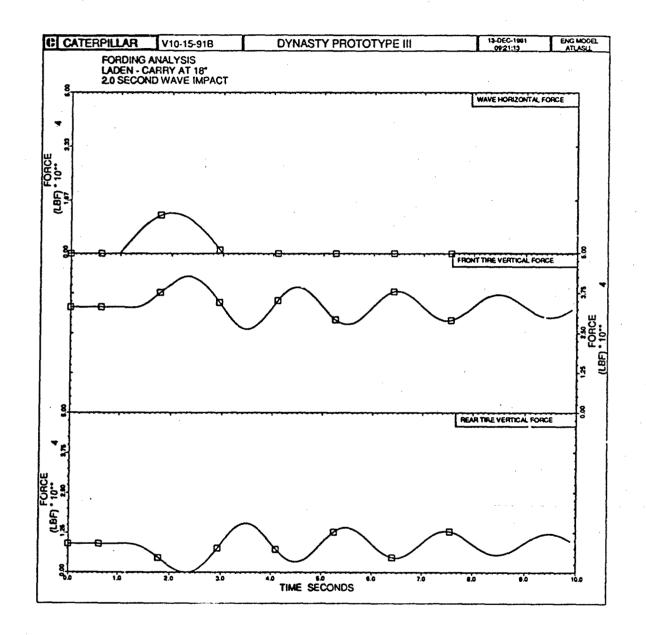


Figure 2.7-12 ATLAS Loaded, Load at 18" Height, 2.0 Second Wave Impact

Attachment 3 C130 Transportability Study

1.0 Transportability Background.

The ATLAS transportability requirements exceed the air transport requirements defined in MIL-T-53038 (ME) for the current 6K RTFL with the inclusion of C130 transport (Figure 1.0-1) requirement. Neither the C130 transport capability nor ATLAS performance shall be compromised per the technical guidance provided. Cab removal was not an option.

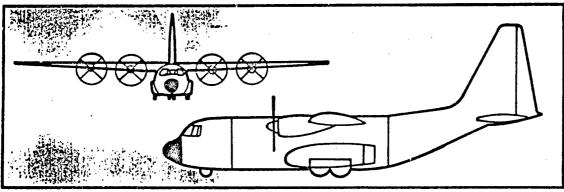


Figure 1.0-1 C130

The issue is multi-faceted centering primarily on weight distribution and envelope dimensions. The primary trade-off (to meet the 102" vehicle width defined) as a result of this study is vehicle performance versus additional preparation for C130 transport. Figure 1.0-2 provides the envelope (width and height) dimensions including the 5.5 inch rail that limits vehicle width including tire bulge to 102 inches.

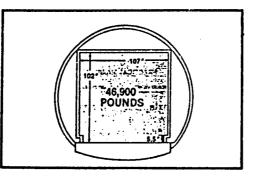


Figure 1.0-2 C130 Envelope Dimensions

1.1 Recommendations. A C130 transport configuration of ATLAS is achievable without compromising the operational configuration/performance with implementation of the following recommendations provided as a result of this study:

Provide the necessary resources to convert the ATLAS from operational configuration to a C130 air transport configuration.

Provide the necessary resources to return the ATLAS to operational configuration at the theatre of operations.

Provide consideration for an ATLAS C130 Transport Kit with maturation of the ATLAS Program.

The need for an ATLAS C130 Transport Kit will be alluded to but the need for such a kit has not been established under the auspices of this effort.

1.2 Rationale. Given that C130 transportability parameters cannot be violated and vehicle performance is central to the safe and reliable completion of the ATLAS mission, the minimum allocation of resources (labor and materials) to prepare the ATLAS for C130 transport and restore the vehicle to operational configuration is the most cost effective and lowest risk approach.

1.3 Technical Approach. The technical approach centers on four techniques to convert the ATLAS from operational configuration to C130 air transport configuration;

- a) Relocation of counterweight,
- b) Extension of boom,
- c) Addition of temporary 3rd axle, and
- d) Reversal of the rim/wheels. if the 20.5R25 tires are used.

These activities will result in the required to provide the required weight distribution and envelope dimensions. Figures 1.3-1 and 1.3-2 provide two examples of potential transport configurations.

ATLAS Fording Study

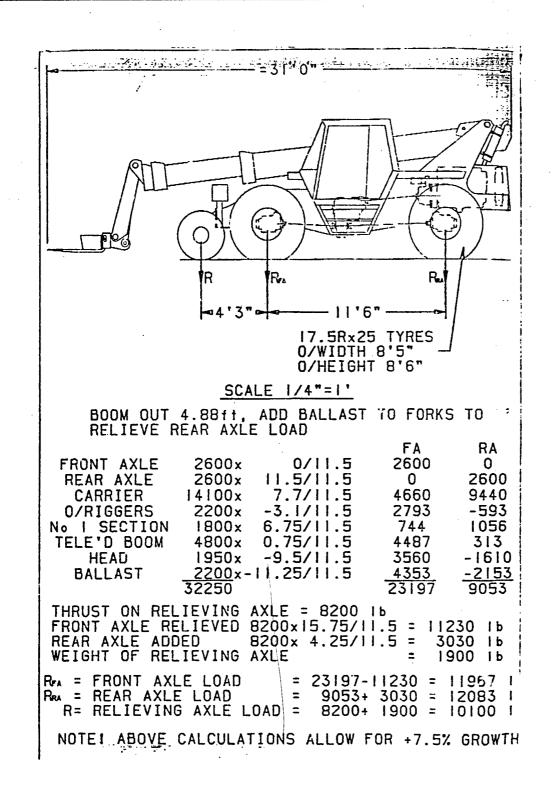


Figure 1.3-1 establishes a 31 foot vehicle length with the ballast/counterweight secured to the forks of the extended boom.



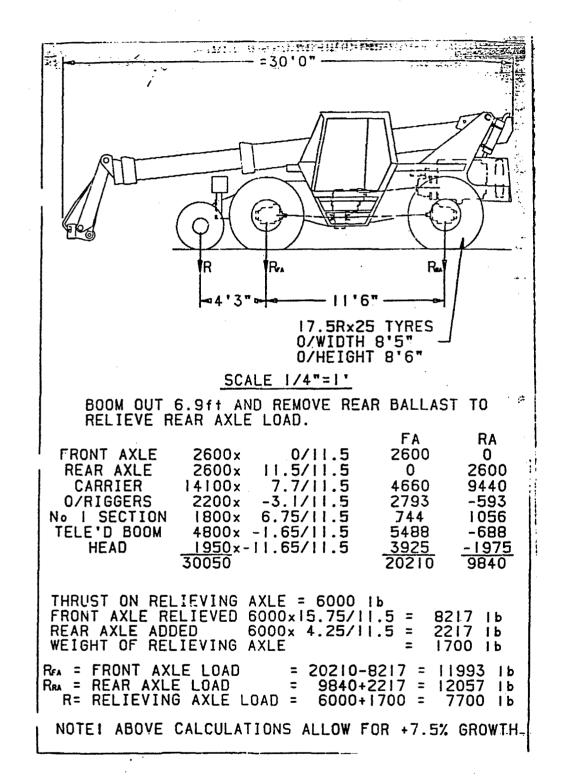


Figure 1.3-2 establishes a 30 foot vehicle length with the extended boom and the ballast/counterweight shipped separately.

ATLAS Fording Study

Vehicle height of 101 inches for C130 transport is readily achievable with tire deflation.

<u>1.3.1 Relocation of the Counterweight.</u> Relocation of the counterweight is required to provide the necessary weight distribution. The counterweight of approximately 2200 lbs will be removed from the rear of the vehicle and relocated on the forks of the boom (to provide a more desirable weight distribution during transport) or transported separately (to reduce transport weight).

Outriggers would also be removed and relocated. For purposes of this study, outriggers are removed and shipped independently of ATLAS. Maturation of the ATLAS design will establish the need for outriggers and provide for alternatives to accommodate outriggers for C130 transport.

<u>1.3.2</u> Extension of the Boom. Extension of the boom is necessary to shift the center of gravity of the vehicle forward by shifting weight from the rear axle to the front axle. With the counterweights stowed on the forks, extension of the boom may be minimized.

Total vehicle length including extension of the boom is limited to 480" (40 feet) on the C130.

<u>1.3.3 Addition of the Temporary 3rd Axle.</u> Application of a temporary 3rd axle is necessary to meet the axle weight limitations of (13,000/13,500 lbs) for the C130. Implementation of a 3rd axle is the classical alternative to removing weight from the vehicle. The projected gross vehicle weight of 32,500 lbs for ATLAS, though well within the 47,000 lbs maximum, would necessitate the removal of 6,000 lbs to be within the 26,500 permitted for a 2 axle vehicle.

ATLAS Fording Study

The temporary 3rd axle would be located at the front of the vehicle and provide the required minimum spacing of 43 inches between axles. The wheels would be located in the treadways of the C130. The axle may require suspension to assure that sufficient load is carried by the axle during loading, transport, and unloading the ATLAS vehicle. The axle weight carried by the 3rd axle would be limited to 13,000 lbs (if the wheels are located on treadways) and 5000 lbs (if wheels are located between the treadways). Figures 1.3-1 and 1.3-2 project axle loads of 10,100 and 7,700 lbs respectively.

Provisions may be made to stow the 3rd axle on the ATLAS vehicle when not in use or provide the axles with the ATLAS C130 Transport Kit as required.

<u>**1.3.4** Reversal of the Rim/Wheels</u>. Reversal of the wheels is required to provide the necessary vehicle width of 102 inches for C130 transport if 20.5R25 tires are used. The rim would be designed with an offset such that when the offset was outboard the vehicle would be configured for working. Alternatively when the offset was inboard, the vehicle would be configured for C130 transport.

<u>1.3.5 ATLAS C130 Transport Kit.</u> An ATLAS C130 Transport Kit may be determined to be a more cost effective approach than providing the 3rd axle and supplemental tools and materials to reconfigure ATLAS for C130 transport. The need for such a kit was not defined under this contract. The definition of this kit should not be precluded from further consideration with the maturation of the ATLAS design.

Integrating the design features to required for C130 transportability may add 5% to 10% to the cost of each vehicle. Implementation of a reusable kit could avoid a substantial portion of that cost. Unfortunately, a transport kit introduces the logistics problem of mating a kit with the vehicle when required.

2.0 Transportability Requirements.

Transportability criteria are established by MIL-STD-1366 and MIL-HDBK-157. The following paragraphs are taken from MIL 7-53038(ME); recommendations/comments are provided in sub-paragraphs. The RTFL shall be transportable worldwide without damage, by highway, air, marine, and rail transport modes.

2.1 Highway Transportability. The RTFL shall be capable of being towed with a dead engine without damage. The drivetrain shall be provided with a means to disengage the wheels from the transmission for towing. Disengagement and reengagement shall each be performed in not more than one hour by one person using only manual devices and common tools. The forklift, in its reduced configuration, shall be capable of highway movements worldwide when transported on US Army M871 semitrailer, and highway transportable in NATO countries. The RTFL shall not exceed the permit limits as defined in Table I of MIL-HDBK-157 for transport in CONUS, excluding Guam and Puerto Rico.

(No substantiative departure from the 6K RTFL to meet the ATLAS requirements is anticipated.)

2.2 Air Transportability. The forklift shall be transportable in USAF C130, C140, and C-5A aircraft. Transportability requirements shall be in accordance with MIL-A-8421, Air Force Design Handbook DH1-11, and as specified herein. The fully assembled forklift truck shall be capable of being driven on and off the aircraft. The air transport configuration shall be with a minimum of 1/2 to a maximum of 3/4 tank of fuel.

<u>2.2.1 C130 Air Lift Configuration Recommendation</u>. The fully assembled forklift truck should provide for an air lift configuration with sufficient time and resources to convert the ATLAS from the operational configuration to an air lift configuration.

ATLAS Fording Study

<u>2.2.2. Tools and Time Allocation Recommendation</u>, Conversion of ATLAS from the operational configuration to the C130 air lift configuration will require additional time and effort. The conversion may be accomplished with on-board tool incorporating features of the ATLAS vehicle or with consideration for an ATLAS C130 Transport Kit. Sufficient personnel must be provided for the conversion to be completed in a safe and reliable manner.

<u>2.2.3 Technical Order C130A-9.</u> Technical Order C130A-9 (Figure 2.2.3-1) provides for the on/off loading of heavy duty forklifts. Notably, the TO provides for "remove cab top, doors, counterweights, and rollerized tines and place on a separate pallet for shipment" and a reduction in fuel load if required. The extent to which this TO will be applicable to ATLAS has not been determined, i.e. ATLAS shall exceed the 26,500 lb limitation. The TO implies that resources and materials are allocated to prepare RTFLs for C130 transport.

	CONFIGURATION		DIMENSIONS		
NOMENCLATURE		LENGTH	WIDTH	HEIGHT	POUNDS
Heavy Duty Forklifts					26,500
•					
	ON/OF	F LOADING ME	THODS		
		NOTE			
	Due to the numerous mode	designations an	d manufacture	rs, the	
	models are not specified. H adverse and rough terrain	lowever, the proce forklifts, respectiv	dures below a vely.	pply to	
	-	•	•		
I. REMOVE CAD to	p, doors, counterweights, and rol	ierized lines and	place on separ	ate pallet for air sh	ipment.
		NOTE			
	Removal of counterweights				
	when the added weight does One axle may weigh 13,500 a	not exceed 13,500	-pound asie w	eight. 3 000	
	pounds. The gross weight wi	ll not exceed 26,50	0 pounda.		
2. If forklift is to	be shipped in the operational mo	xde, do not exceed	the limitation	a in the NOTE abo	ve Fuel load
may be reduced if	required to remain within limit	8.			
3. Sleepershorin	r in required.				
	•				

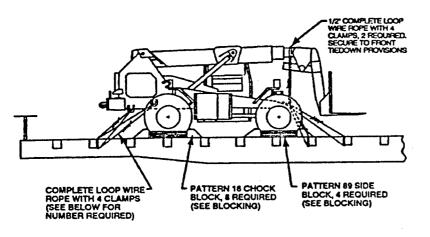
Figure 2.2.3-1 Technical Order C130A-9

ATLAS Fording Study

2.3 Rail Transportability. The forklift shall have unrestricted movement by railroad when loaded on a 50-foot flat car (see MIL-HDBK-157)/ The forklift shall withstand railroad bumping without permanent deformation or damage to any of its components when secured to the flatcar in accordance with the Association of American Railroad (AAR) Rules Governing the Loading of Department of Defense Material on Open Top Cars. The railroad bumping test shall be in accordance with the AAR General Rules Governing the Loading of Commodities on Open Top Cars (Section 1, Part 3).

No substantiative departure from the 6K RTFL to meet the ATLAS requirements are anticipated. MTMCTEA PAM 55-19 provides guidance for the securing of Variable Reach Forklift Truck, 6000 lb (Figure 2.3-1). Note that the table also provides for GVWs between 25,000 and 38,000 lbs that bracketed the 32,500 lbs projected for ATLAS.

Variable Reach Forklift Truck, 6,000 lb



	S X 19 IWRC IPS ROPE		
VEHICLE WEIGHT RANGES (LB)	CABLE SIZE (DIA, IN.)	NUMBER OF CABLES (COMPLETE LOOP)	
0-14,000	3/8	4	
14,000-25,000	1/2	4	
25.000-38.000	5/8	4	
38,000-50,000	1/2		
50,000-76,000	5/6	•	

NOTE: FROM GENERAL RULES, SECTION NO. 1.

Figure 2.3-1 MTMCTEA PAM 55-19 Provide Guidance For Securing Variable Reach Forklift Truck, 6,000 lb

Page 9

ATLAS Fording Study

2.4 Marine Transportability. The forklift shall be transportable by breakbulk cargo ships, roll-on/roll-off (RORO) ships, C-8 and larger, lighter aboard ship (LASH), barge carrying ships (SEABEE), LARC60 and larger amphibious vessels, and army barges and lighters in accordance with MIL-HDBK-157.

No substantiative departure from the 6K RTFL to meet the ATLAS requirements are anticipated.

<u>2.4.1 ISO Container Transport.</u> ATLAS may be transported via an ISO platform (flat rack) container.

Initially, marine transport by ISO Series 1 container was desirable. This desired feature was deleted from further consideration because the requirements of this transport mode were far more stringent than C130 transport requirements. Specifically, vehicle width and height would be limited to 91 inches, i.e. an 11 and 10 inch reduction in width and height, respectively, from what is allowed for C130 transport.

Alternate containers were investigated. A limited number of "tall" Series 1 containers providing for 101" height are available. The availability of "tall" Series 1 containers has not been established. Open top containers provide additional latitude in height but no additional latitude in width. Only the aforementioned, platform (flat rack) ISO container has been identified to meet a requirement for ISO containerization and transport. Subsequent establishment of a requirement and maturation of the ATLAS program and design may necessitate that this issue be addressed.

ATLAS Fording Study

Caterpillar Inc.

3.0 Vehicle Performance Considerations.

Off-road performance of the RTFL in an undulating terrain is strongly influenced by a number of factors including gage of the vehicle, i.e. the wider the gage the more stable the lifting and transport platform. RTLFs provide hydraulic cylinders to level the frame for lifting the load.

Notably the tire size and footprint strongly influences mobility of the vehicle particularly in soft underfootings typical for LOTS operations.

3.1 Vehicle Gage. The vehicle gage is defined at the center-to-center dimension between the tires. The vehicle gage is established by the flange-to-flange dimension of the axle, the offset of the rim, and the tire width. The vehicle width for C130 transport is limited to 102" by siderails to a height of 5 inches from the groundline.

Given that all other factors are held constant, the wider the vehicle gage the more stable the platform on side slopes.

<u>3.1.1 Tire Size</u>, Two tire sizes (17.5Rx25) and (20.5Rx25) are considered for the ATLAS. The 20.5Rx25 is necessary to meet the mobility requirement for speed, specifically the dash speed of 50 mph with an achievable axle ratio of 10.1

The 17.5Rx25 tire is under consideration only to meet the C130 vehicle width limitation of 102" with widest commercially available axle arrangement. Implementation of the 17.5Rx25 tire compromises dash speed and the vehicle's capability to negotiate soft soil conditions.

The capability of a vehicle to negotiate soft soil condition is a function of its footprint, i.e. wider tires provide increased cross-sectional area in contact with the ground, hence more flotation and increased mobility. The 20.5Rx25 tire provides 1.17 times the width of the 17 5Rx25 tire. The ability to negotiate soft soil conditions may be descri' ed by a number of empirical indices including Mobility Index (NATO Reference Mobility

ATLAS Fording Study

Model), Flotation Index (MIL-STD-53038) (ME), and Min-Max Pressure favored by British MOD. The Flotation Index recognizes that RTFLs, except under unique loading conditions, have an unequal weight distribution between axles.

<u>3.1.2 Rim Offset</u>. Rim offset provides the option for relocating the centerline of the tire and rim with respect to the axle hub. The wheel may be move? outboard or inboard. A single rim design may provide offsets on the order of 2 through 8 inches. A reversible rim would require that the geometry of the clearance holes provide for reversal of the rims.

<u>3.1.2.1 Engineering Considerations.</u> Changing the rim offset changes the loading on the roller bearings necessitating engineering review and possible redesign. Briefly, the axle hub includes the axle flange (to which the rim bolts) and distributes the loading through the axle bearings to the spindle. The bearings are sized to accommodate the expected loading.

<u>3.1.2.2 Steering Restriction</u>. Reversing the rims to facilitate C130 transport, i.e. offsetting the rim inboard would reduce the maximum steering angle by a limited, but measurable number of degrees. Maturation of the ATLAS design would determine the extent to which maneuverability is degraded in the C130 transport configuration.

The three modes of steering provided by RTFLs, Ackerman, crab, and countersteer provide sufficient maneuverability to the C130 configured ATLAS that it can accomplish the C130 drive on/ drive off maneuvers. Maturation of the ATLAS design will provide for the technology required to limit the steering angle in the C130 transport configuration. The electronic over hydraulic controls may be utilized to provide "soft" steering angle limitation. Alternately, the axle housing may be modified to provide a "hard" steering angle limitation. A bolt/pin-on stop could be provided with the ATLAS C130 Transport Kit or a stowage location provided on the ATLAS vehicie.

ATLAS Fording Study

<u>3.1.3 Axle Width</u>. Steerable axles as required for the 3 steering mode operation of the ATLAS RTFL are available with a limited variety of flange-to-flange dimensions. Substantiative alterations to this dimension are not trivial nor recommended at this time. Notably RTFLs provide for a steering angle of 37 degrees. Axles configurations with flange-to-flange dimensions of 73 and 85 inches have been considered.

<u>3.1.3.1 73" Axle.</u> The 73" axle is under consideration only to meet the C130 vehicle width limitation of 102" with the 20.5Rx25 tire. A rim offset of 4.25 would meet 102" required for air-transport but would limit the operational configuration to 102".

<u>3.1.3.2 85" Axle.</u> The 85" axle would provide a vehicle width of 108 inches with the 20.5Rx25 tire providing a more stable lift and working platform. An offset of 3 inches would be required to meet C130 transport requirement.

The 85 inch axle provides a 16% increase in the flange-to-flange dimension over the 73 inch axle.

3.3 Weight/Weight Distribution. Proper weight/weight distribution is central to the performance and transportation of 32,500 lb ATLAS. In the working mode (unloaded) the rear axle carries more weight (approx. 17,970 lbs) than the front axle (approx. 14,288 lbs). Note that each axle exceeds the maximum axle weight permitted by TO 1C130A-9 of 13,000/13,500 lbs.

<u>3.3.1 Engineering Consideration</u>. Substantial increases in gross vehicle weight are not a viable alternative to meeting the transportability requirements hence a temporary 3rd axle was considered in lieu of provisions to remove more weight. Provisions to remove more weight (6000+) for transport may have necessitated unacceptable weight growth compromising both dash'speed and soft soil mobility.

4.0 C130 Transport Configuration Considerations, Preparation For. Preparation for C130 transport is generally desired to be 1 hour. Alternatively preparation for C130 transport of ATLAS will require 3-4 hours without compromising the operational performance of the vehicle. Preparation for C130 transport will consist of the following:

<u>Activity</u>	Lapse Time Estimated	
	(mirutes)	
1) Removal of Counterweight,	15	
2) Addition of the 3rd axle, and	45	
3) Reversal of the Rims/Wheels.	120	
4) Extension of boom,	1	
5) Miscellaneous Activity	59	

4.1 Counterweight. Removal of the counterweight (2200 lbs) may be accomplished using the boom per Figure 4.1-1. The number 2 section of boom will be partially extended. A cable(s) will be routed from number 2 section, over a pulley, and secured to the counterweight. The number 2 section of boom will be extended relieving the weight off the pins that secure the counterweight to the frame. The counterweight will be unpinned and the boom retracted to lower the counterweight safely to the ground. The vehicle can then engage its counterweight with the forks secured.

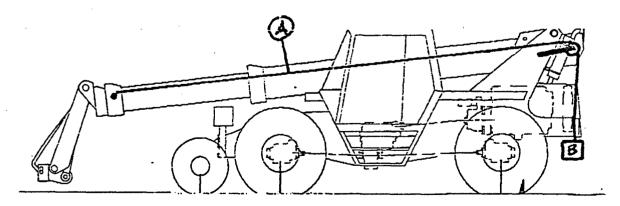


Figure 4.1-1 Removal Of The Counterweight May Be Accomplished By Using The Boom

ATLAS Fording Study

4.2 Addition of the 3rd Axle. Maturation of the ATLAS design may provide for addition of the 3rd axle. As a minimum the temporary 3rd axle will include a structure (cross axle and mounting features) and hydraulic cylinders.

4.3 Reversal of Rims/Wheels. Reversal of the wheels can be accomplished in a variety of ways. Basically, this operation requires that each wheel be lifted clear of the ground, the lug nuts/bolts loosened and removed, the wheel be safely rotated 180 degrees, the wheel reinstalled on the hub and secured.

The wheels on the front axle may be readily cleared from the ground by dropping the boom to the ground and hydraulically lifting the front of the vehicle until the wheels clear the ground. The rear axle may then be chocked to positively preclude accidental shifting of the vehicle.

The wheels of the rear axl^o can be raised using a similar technique except that a sufficient load must be engaged with an over-extended boom that will lift the rear axle off the ground. The axle may then be chocked wheels reversed. Another option is to use a jack to raise the rear axle off the ground. The jack may be obtained from maintenance or be provided as part of an ATLAS C130 Transport Kit.

<u>4.3.1 Safety Concern</u>, Handling/reversing the wheels introduces an Operator/ maintainer safety concern that may be mitigated by implementing standard military maintenance practices to remove and replace a tire on RTFLs. This approach may require allocation of maintenance resources not typically associated with C130 transport operations though Technical Order 1C130A-9 alludes to the allocation of maintenance/operator resources to remove cabtop, doors, counterweights, rollerized tines, etc.

4.4 Extension of the Boom. Extension of the boom is required to relieve the weight on the rear axle and transfer that weight to the temporary 3rd axle in particular. Extension of the boom may be decreased if the counterweights (and perhaps other miscellaneous elements) are secured and transported on the forks. The 3rd axle must accommodate between 7000 and 10000 lbs. Extension of the boom to the desired length (between 4.88 and 6.9 feet) will require less than a minute.

4.5 Miscellaneous Activity. This task provides for undefined miscellaneous activity necessary to prepare the vehicle for shipment including implementation of the sleeper shoring, securing the vehicle within the C130, removal of fuel, etc.

4.6 ATLAS C130 Transport Kit. Definition of an ATLAS C130 Transport Kit may be determined to be the most cost effective approach to providing the 3rd axle and supplemental tools and materials to reconfigure ATLAS for C130 transport. The trade-off is between configuring each ATLAS vehicle with materials necessary for air transport or providing and distributing those materials in a limited number of kits.

At a minimum the kit may include:

the temporary 3rd axle,
 jack,
 steering stops, and
 hardware.

The kit may be provided in a reusable container suitable for C130 transport with the ATLAS vehicle. The container may be used to transport materials that would otherwise be palletized. Upon arrival at the theatre of operations, the container would be readily matched with the associated vehicle for reconfiguration. The container would then be reused to stow the elements of the transport kit until required for return shipment. Perhaps the kit could be returned with the C130 for installation on the next ATLAS to be transported to the theatre of operations.

The need for such a kit has not been defined nor provided for under the auspices of this effort. The definition of this kit should not be precluded from further consideration with the maturation of the ATLAS design.

ATLAS Fording Study

Attachment 4 NBC Contamination Of Hydraulic System

1.0 Operation in Contaminated Environments.

The ATLAS vehicle will operate in a NBC contaminated environment to fulfill its mission. Once that operation is completed, all elements and subsystems of that vehicle must be decontaminated.

1.1 Definition of the Problem. The hydraulic system may be contaminated by particles breaching the system via the vent/breather of the hydraulic reservoir. The hydraulic reservoir is vented to and operates at atmospheric pressure. The vent of the hydraulic reservoir permits changes in the level of the hydraulic fluid to accommodate the hydraulic oil demands of the ATLAS vehicle. Without the vent the hydraulic tank would be subject to internal pressures greater than or less than atmospheric pressure depending on the fluid level.

As the hydraulic demand increases, i.e. the hydraulic fluid level decreases, the vent introduces outside (contaminated) air in the reservoir. The air is purged as the hydraulic level increases.

1.2 Recommendation. Define a requirement for a sealed hydraulic system for ATLAS to minimize the potential for contamination of the hydraulic system by NBC agents.

18

ATLAS Fording Study

2.0 Technical Approach.

Three alternatives have been identified to address the problem:

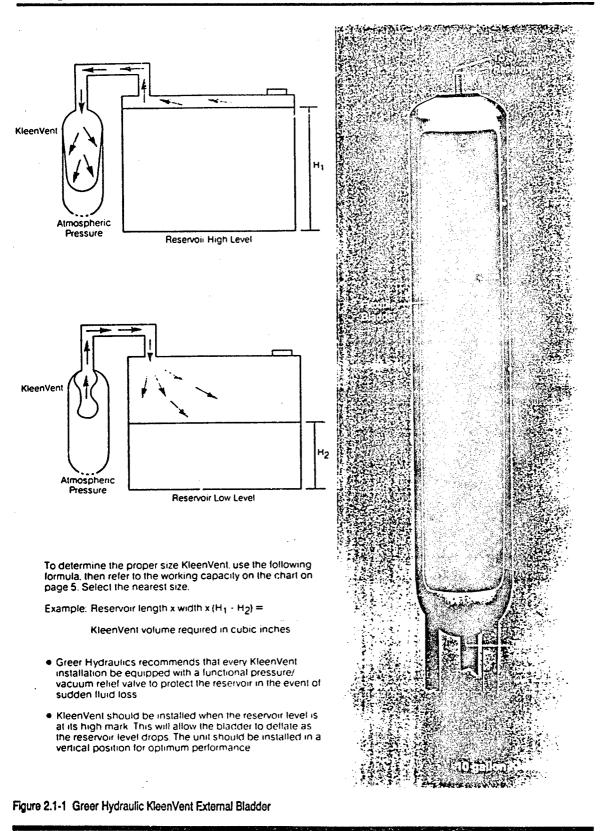
a) Seal hydraulic system,
i) External
ii) Internal
b) Add filter to the vent/breather, and
c) Do nothing.

The sealed hydraulic system provides a positive separation between the contaminated environment and the hydraulic fluid, whereas the addition of the filter would provide quasi-temporary separation. Finally, the do nothing approach would necessitate maintenance resources to fully decontaminate ATLAS.

2.1 Seal Hydraulic System-External. A sealed hydraulic system would require the addition of an external bladder in series with the hydraulic reservoir (Figure 2.1-1). Commercial off-the-shelf accumulator technology, such as the Greer Hydraulic KleenVent, exists to seal the hydraulic system from outside (contaminated) air.

Greer recommends a functional pressure/relief valve between the hydraulic tank and the external accumulator. The valve would ingest or purge outside air when the internal system pressure exceeds preset amounts.





ATLAS Fording Study

<u>2.1.1 Theory of Operation</u>. The bladder acts as a "lung" expanding and contracting to accommodate the changes in gas volume of the hydraulic reservoir. Instead of outside contaminated air being ingested and purged, the clean air within the sealed hydraulic system is "reused". The external surface of the bladder and the enclosure would be contaminated but may be readily decontaminated via standard decontamination procedures with DS2.

<u>2.1.2 Engineering Consideration</u>. The bladder must be sized to accommodate the differential volume of hydraulic oil at operating temperature in the reservoir. In simplistic terms, the required size in cubic inches may be defined as follows:

Reservoir	
Volume	= (Length x Width) x (H1 - H2)
Required	

where H1 = Low Level of the reservoir H2 = High Level of the reservoir

The bladder is typically enclosed in a steel or fiberglass cylinder permitting remote location. A line is then routed to the bladder from the hydraulic reservoir.

2.1.3 Engineering Concern. The bladder and enclosure may require a substantial space claim. Implementation of the pressure valve will be required to minimize space claims for the accumulator

<u>2.1.4 Operational Concern</u>. The pressure valve may ingest contaminants if activated during an operation in a contaminated environment.

2.2 Sealed Hydraulic System-Internal. The sealed hydraulic system may include an internal bladder within the hydraulic reservoir (Figure 2.2-2). The same theory of operation and engineering consideration would be applicable to the internal bladder as to the external bladder though several differences exist.

ATLAS Fording Study

Breather bags provide in-tank protection against air contamination

A breather bag is a synthetic rubber bag which provides a permanent llexible non-porous barrier between the atmosphere and the system fluid without affecting the operational functions of the system components.

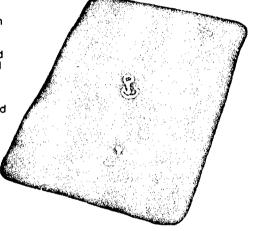
The bag is fully encloced, except for a metal stem which gives access to the bag interior. Provided the tank is properly sealed air flows only in and out of the breather bag as the fluid level rises and falls. Thus all air and contaminants are prevented from contacting the fluid.

The standard breather bag is made from neoprene/nylon coated fabric, allowing prolonged contact with hydraulic fluid while resisting ozone cracking from contact with the atmosphere.

KleenVent Breather Bags are available:

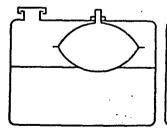
- square
- rectangular
- sizes to fit most applications

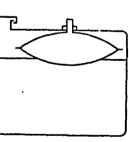
See page 6 for ordering information.

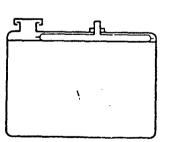


INTERNAL BREATHER SYSTEM.

In this system, a Fawcett Breather Bag is fitted to the underside of the top of the fluid supply tank. The fluid occupies the full volume of the tank with the exception of breather bag interior, which is open to the atmosphere. Air is free to flow in and out of the breather bag as the oil volume changes. The bag has to be of sufficient size to accommodate the volume change within the tank, equal to the full system displacement, plus an additional 25% giving an allowance for any leakage and volume change due to thermat expansion or contraction.







MINIMUM OIL VOLUME IN TANK NORMAL OIL VOLUME IN TANK MAXIMUM OIL VOLUME IN TANK

Figure 2.2-2 Hydraulic Reservoir Internal Bladder

ATLAS Fording Study

Primarily, the internal bladder mitigates the engineering concern with respect to the space claim demands of the external bladder. Notably the bladder would be located within the hydraulic reservoir with the outside skin exposed to the oil and the inside skin exposed to the contaminated environment.

Secondly, using an internal bladder eliminates the need for a pressure valve and it's potential for contaminating the oil.

The primary tradeoffs between the internal and external bladders would be application of the pressure valve, space claim, weight growth, and decontamination efficiency.

To decontaminate, the bladder may be removed from the tank via an access port incorporated within the design of the hydraulic tank. The access port would be located above the maximum fluid level.

<u>2.2.1 Producibility Concern</u>. Though the technology for internal bladders exists, the bladders are no longer commercially available off-the-shelf, hence a bladder to fulfill the requirements of ATLAS would be a new design.

2.3 Filter. Filtration of the contaminated air is the classical approach to minimize ingestion of particles, particularly dust and dirt, within the hydraulic system on off-highway vehicles. For example, typical Pall filters provide a glass fiber medium to filter particles to 2.5 microns.

To address chemical and biological agents, a second, hydroscopic filter in series with the particle filter would be required to impede the chemical/biological agents. The filter would require changing after exposure to chemical and biological agents. Unfortunately, these agents would permeate through the filter with time.

ATLAS Fording Study

2.4 Do Nothing. The do nothing approach would simply recognize that the hydraulic oil would be contaminated with each mission in a contaminated environment.

After each mission in which the oil became contaminated the hydraulic system would be drained, cleaned/flushed, and replenished with clean oil and filters at the intermediate maintenance level. Cleaning to decontaminate the components of the hydraulic system would either require complete disassembly to decontaminate or flushing the system. Flushing the system would require substantial volumes of oil to dilute the contaminants to "acceptable" levels. The volume of hazardous waste would increase. Maintenance personnel performing the decontamination procedure would in all probability be wearing protective clothing whose level of protection may be degraded upon contact with a petroleum product such a hydraulic oil.

The contaminated oil and filters would be classified as a hazardous waste necessitating proper disposal.

3.0 Recommendation Rationale.

The sealed hydraulic system with an internal bladder provides for the most cost effective solution. The external bladder and pressure valve space claim requirements compromise its desirability. Filtration provides only a "temporary" impediment to contamination of the system and would necessitates substantial logistic support. Doing nothing may result in unacceptable generation of hazardous waste and pose a safety problem during decontamination.

Though the internal bladder is not "commercially" available, the manufacturing technology is common and should be readily available from a variety of sources.

ATLAS Fording Study

Attachment 5 Failure Modes

a) Electrical Short.

The presence of moisture or water will provide an electrical short circuit that induces a failure of that electrical circuit.

b) Fluid Contamination.

Contamination of various automotive fluids (engine, brake, and hydraulic oil, battery acid, coolants, etc.) by saltwater will alter the properties of that fluid and introduce the potential for failure.

c) Air Restriction/Constriction.

Salt water may impede the flow of air and impair the performance of the vehicle.

d) Galvanic Corrosion.

When two metals are placed in electrical contact and exposed to a conductive or corrosive solution, one tends to go into solution while the other acts as a cathode and does not go into solution. Galvanic corrosion can usually be predicted by referring to a table of standard electrode potentials.

Galvanic corrosion is accelerated when two metals in electrical contact have large differences in their electrode potentials. Parts may fail due to the accelerated attack when only one metal would have lasted much longer because of a uniform, but slow, attack. For incance, a steel hot water pipe may fail when a copper pipe is attached to it. Accelerated corrosion due to galvanic effects is usually greatest near the junction of the two metals. In addition, if the anodic material has a relatively small surface area compared with the cathode (small anode-large cathode), corrosion accelerates.

ATLAS Fording Study

Galvanic corrosion may be prevented or minimized by:

1) avoiding electrical contact of two dissimilar metals by insulation

2) using metals having similar electrode potentials

3) avoiding large cathode/anode ratios of surface areas

4) designing for easy replacement, using thicker metal parts for anodic metals

Cathodic protection is making a metal part the cathode in a galvanic cell in order to prevent corrosion. This may be done by:

- 1) galvanizing steel
- 2) connecting magnesium to less active metals
- 3) impressing a current from an external power source

Underground pipes are frequently protected cathodically by 2) or 3). (Amphibious vehicles such as the USMC AAV7A1 are cathodically protected by 2.)

e) Stress Corrosion.

The presence of tensile stress and certain specific chemicals combine to cause stress corrosion, another insidious type of corrosion. Stress corrosion results in either transgranular (across grains) or intergranular cracking (along grain boundaries). Most of the surface of a stress-cracked metal is essentially unattacked. Stress cracking may occur at relatively low stress levels compared with stress needed for failure (tensile strength) and at relatively low concentrations of chemicals, such as C1 ions for austenitic stainless steels.

Stress corrosion of brass is frequently referred to as "season cracking". In the Tropics, brass cartridge cases cracked where the case was crimped to the bullet. Ammonia plus stress causes brass to stress crack. Carbon steel stress cracks in the presence of sodium hydroxide ("caustic embrittlement"), whereas austenitic stainless steels stress crack in chloride solutions.

ATLAS Fording Study

Important variables are solution composition, temperature, and stress for a given metal. Stresses may be of several types:

- 1) residual stresses acquired during forming (stamping, rolling, etc.)
- 2) applied stresses resulting from the use of a structural part
- 3) thermal stresses, e.g., quenching or welding stresses

Corrosion products themselves can create stresses when a metal corrodes. The final cracking results from mechanical failure.

Although the mechanism of stress corrosion is not completely known, it appears that stresses generated from the presence of corrosion products plus stresses already present result in mechanical failure. Of course, the tips of cracks in metals are fairly sharp, and this may lead to accelerated corrosion. Plastic deformation occurs just ahead of the crack when it stops momentarily. Cracks grow sporadically—they have been heard even with the unaided ear. Rupture of passive films may also occur during stress cracking. In intergranular stress cracking such as occurs in brass, grain boundaries may be anodic compared with the grain interiors, and the grain boundaries are the preferred paths for cracking. The present state of knowledge about the mechanism of stress cracking leaves much to be discovered in the future.

Stress cracking may be reduced or prevented by:

- 1) decreasing the stress level by annealing, design, etc.
- 2) avoiding the environment that leads to stress cracking
- 3) changing the metal if the environment cannot be changed
- 4) adding inhibitors or applying cathodic protection to reduce the rate of corrosion.

ATLAS Fording Study

Caterpillar Inc.

f) Crevice.

Crevice corrosion is due to small volumes of stagnant solution collecting in crevices under bolts, under surface deposits such as dirt, corrosion products or loose paint, and in holes or under gaskets. Intense localized corrosion occurs when the crevice is wide enough to permit liquid entry, but sufficiently narrow to create a stagnant solution. Although this type of corrosion occurs in openings of about 10 to 100 mm, it rarely occurs (0.1 cm or larger). Fibrous gaskets are notorious for creating stagnant pockets in wide grooves or slots solutions on flanges. A surprising example of crevice corrosion is the fact that 304 stainless steel may be cut in two by placing a stretched rubber band around the stainless and immersing it in a chloride solution such as seawater.

The mechanism of crevice corrosion involves several steps:

- 1) the depletion of oxygen in the stagnant solution due to corrosion of the metal [for example, O2 + 2Fe + 2H2O -> 2Fe(OH)x]
- 2) corrosion in the crevice continues through a reaction such as Fe 2e- -> Fe+2; the electrons migrate through the metal to the region where oxygen is available:
 O2 + 2H2O + 4e- -> 4OH-
- 3) both chloride and hydroxide ions migrate into the crevice because of attraction by the cations created through corrosion, but chloride ions migrate more rapidly
- 4) the higher concentration of chloride ions causes corrosion to accelerate; also Fe+2 hydrolyzes to form a weak acidic solution: Fe+2 + 2H2O -> Fe(OH)2 + 2H+. This weak acid in conjunction with chlorides is highly corrosive.

In crevice corrosion, there is often a long incubation period (as long as one year) before accelerated attack begins. Metals depending on passive oxide films are particularly susceptible to crevice corrosion because passivity may be broken by the presence of chlorides and acid of certain concentrations. Crevice corrosion may be minimized by avoiding crevices in design (e.g., using welded joints instead of bolts or rivets), by filling crevices with a sealant, by removing dirt and deposits regularly, and by using "solid" instead of fibrous gaskets.

ATLAS Fording Study

Filiform corrosion is a special type of crevice corrosion in which corrosion occurs along channels under enameled or lacquered steel surfaces. Other metals have also exhibited filiform corrosion. The result of filiform corrosion is a network of 0.2-cm-wide worm-like trails of corrosion products. Corrosion trails move in straight lines, but they do not cross inactive trails; the active "head" reflects from the inactive trail and continues on its way. Filiform corrosion involves osmosis: water diffuses into the active head and out of the inactive tail because the head contains a high concentration of ferrous ions and the tail contains mainly precipitated ferric hydroxide. Thus, the filiform corrosion acts as a self-propagating crevice.

g) Pitting.

Pitting is another form of severe localized attack, and it results in holes in a metal, usually of small diameter. Pits frequently go undetected until the metal has been severely corroded because pits may be covered with corrosion products or by a protective coating having only a pinhole opening. Pitting is difficult to predict by laboratory tests, so it remains a particularly insidious form of corrosion.

Austenitic stainless steel containing 18% Cr and 8% Ni (18-8 type such as 304) may be pitted in sulfuric acid containing ferric chloride in only a few days. Pits usually take much longer to form, and they tend to grow in the direction of gravity. Pitting usually requires an incubation period of several months, but pitting corrosion accelerates once the pit forms because pit formation is autocatalytic. It is also similar to crevice corrosion. Once a pit begins to form, probably due to nonuniform local attack, the concentrations of both metal ions and hydrogen ions increase. Corrosion accelerates, and the pit corrodes because it is an anode. This services to protect the rest of the metal, which is an inactive cathode. Many systems that suffer from crevice corrosion are not susceptible to pitting corrosion on free surfaces, but metals that pit usually suffer from crevice corrosion as well. Electroplated coatings are particularly susceptible to pitting, e.g., automobile bumpers.

ATLAS Fording Study

Pitting is frequently found in the presence of chloride ions and oxidizing agents such as Cu+2, Fe+3, or Hg+2. It is often inhibited by hydroxides, chromates, or silicates. Surprisingly, carbon steel is more resistant to pitting than are stainless steels. Because chlorides and diluted acid accelerate pitting, these should be avoided. Addition of molybdenum to stainless steels markedly increases their resistance to pitting.

h) Erosion Corrosion.

Erosion corrosion is accelerated corrosion due to the relative motion of the metal and the environment. Mechanical wear and abrasion are involved, in addition to corrosion. Metal may corrode, forming dissolved ions, which are swept away, or it may form solid corrosion products, which are mechanically removed.

Erosion corrosion appears as grooves, gullies, waves, or valleys and is usually directional in character. This type of corrosion may occur in a surprisingly short time, particularly when static corrosion tests are relied on. Obviously, metals that depend on the presence of passive oxide, or other surface films, are susceptible to erosion corrosion due to the continual destruction or damage of these protective films. Soft metals, such as lead and copper, are easily affected by erosion corrosion.

Moving fluids cause erosion corrosion in components of piping systems (bends, elbows, tees), valves, pumps, blowers, propellers, impellers, agitated vessels, tubing in heat exchangers, turbine blades and nozzles, ducts, cutters, grinders, and so on. Velocity of the moving fluid and its composition play important roles in erosion corrosion. Metals having good inherent corrosion resistance, rather than metals depending on passive surface films, exhibit good erosion corrosion resistance. Addition of another metal to an alloy usually improves erosion corrosion characteristics due to the formation of more resistant surface films.

ATLAS Fording Study

Erosion corrosion may be reduced or avoided by:

- 1) using materials with better inherent corrosion or erosion corrosion resistance
- 2) designing to avoid high-velocity flow of liquids or sharp changes in direction of liquid flow
- 3) changing the environment, such as by deaeration, addition of corrosion inhibitors, or removal of solids by filtration,
- 4) coatings such as hard facings or overlays
- 5) cathodic protection

Cavitation damage is the formation and collapse of vapor bubbles in a liquid adjacent to a metal surface. When vapor bubbles burst, shock waves form and cause damage to the metal, particularly by the destruction of passive surface films. Cavitation damage can be reduced by designing to minimize hydrodynamic pressure differences. Coating metals with resilient rubber or plastic can often minimize damage.

Fretting corrosion occurs at contact areas between metals subjected to vibration or slip. Pits or grooves appear in the metal and are surrounded by corrosion products. Fretting corrosion is sometimes referred to as friction oxidation, wear oxidation, or chafing. This type of corrosion occurs in the atmosphere rather than in aqueous solutions. Seizing and galling frequently occur, as well as fatigue fracture and loss of tolerances.

Examples of fretting corrosion include bolted tie plates on train rails and press-fitted ball-bearing races on shafts. In order for fretting corrosion to occur, the interface must be under stress, relative motion between two surfaces must occur such as in vibration motion, and the stress and motion must be great enough to deform the surfaces.

The mechanism for fretting corrosion may involve either:

- 1) cold welding occurring between the relatively few contact points between the two surfaces followed by rupture of the contact points and removal of debris, which immediately oxidize because they are so finely divided
- 2) rupture of protective oxide layers at contact points followed by reoxidation of the freshly exposed metal.

Fretting corrosion may be reduced or eliminated by:

- 1) lubrication with oil or grease
- 2) increasing the hardness and, therefore, the abrasion resistance of one or both metal surfaces
- 3) using gaskets to absorb vibration and exclude oxygen
- 4) increasing the relative motion of the two metal parts

i) Uniform Corrosion.

Uniform corrosion is the most common form of corrosion. Uniform attack occurs when an electrochemical reaction, or solution reaction, proceeds uniformly over the entire surface of a metal. A sheet of steel exposed to the environment exhibits uniform attack. Because the corrosion rate is easily predicted from corrosion test data, it is relatively easy to deal with uniform corrosion. In some instances, very slow attack may be tolerated. In other cases, it is even desirable, such as in steels made so that the corrosion product is both tightly adherent and decorative (for instance, Cor-Ten steel rusts to form a highly protective surface oxide, and this surface oxide is esthetically pleasing; hence, unpainted architectural panels, bridges, etc., are made from this steel).

Uniform corrosion may be controlled by using proper materials, inhibitors, or cathodic protection. Uniform corrosion is the least insidious type of corrosion because it is completely predictable.

Caterpillar Inc.

ATLAS Fording Study

j) Intergranular.

Grain boundaries have a higher energy than the interiors of crystals. However, the surface energy of a metal is still higher, so grain boundaries generally do not corrode as rapidly as the surface. However, in certain circumstances the grain boundaries are far less corrosion resistant than the grain interiors, and intergranular corrosion, in which grain boundaries corrode but grain interiors do not, results.

Intergranular corrosion is caused by impurities collected at grain boundaries or by enrichment or depletion of elements in and near the grain boundaries. Iron tends to segregate along grain boundaries in aluminum. Other examples of grain boundary enrichment include zinc in brass and iron in stainless steels.

Intergranular corrosion occurs in 18-8 stainless steels (e.g., type 304) when they have been sensitized by heating in the range 500 degree C to 800 degree C. Sensitization is the precipitation of chromium carbide, Cr23C6, in the grain boundaries. This results in depletion of chromium in a narrow zone parallel with the grain boundaries. The depleted zone then corrodes much more easily and rapidly than the bulk alloy. The time and temperature are critical for sensitization to occur. At temperatures greater than 800 degree C, sensitization does not occur because Cr23C6 will not precipitate. Below 500 degrees C, the diffusion rate of carbon is too low for Cr23C6 to form at grain boundaries. The time in the range 510 degree C to 790 degree C must be sufficient for carbon to diffuse to the grain boundaries to precipitate chromium carbide, but not long enough for chromium to diffuse in from the interior of the grain to replenish the depleted zone.

The complicated time-temperature dependence results in a zone of corrosion occurring parallel to welds of austenitic stainless steels. The band near the weld has experienced the proper time-temperature history to cause sensitization, which later results in corrosion. Intergranular corrosion that occurs as a result of welding stainless steels is called weld decay.

Page 9

Caterpillar Inc.

Intergranular corrosion in austenitic stainless steels may be avoided by:

- 1) heat treating at a temperature above 800 degree C and cooling rapidly to avoid sensitization; the high-temperature treatment dissolves any carbides that may be present, and rapid cooling prevents their subsequent formation at grain boundaries
- 2) lowering the carbon content of the stainless steel to below 0.03%; this decreases the quantity of chromium carbide precipitated so that only minor amounts of chromium are depleted from near grain boundaries
- 3) adding elements such as niobium or titanium to the stainless steel, because these metals preferentially react with carbon to form insoluble carbides throughout the steel; there is no carbon left for a subsequent reaction with chromium.

These latter steels are called titanium- or niobium-stabilized. Titanium-stabilized stainless steel is 321, while niobium-stabilized is type 347.

k) Selective Leaching.

Selective leaching is the preferential removal of one metal from a solid solution as a result of corrosion. The most common example is the dezincification of brass, in which zinc is preferentially removed from containing 30% or more Zn. The color of brass becomes redder and less yellow brasses during dezincification. Two types of dezincification are:

uniform or layer-type, in which the whole surface layer is depleted of zinc
 plug-type, in which dezincification is confined to pit-like regions, usually in brasses containing lower zinc contents.

The aftermath of dezincification is porous copper-rich alloy, which is weak and permeable.

Page 10

Caterpillar Inc.

The mechanism for dezincification appears to be solution of brass, followed by deposition of copper, leaving zinc in solution. Dezincification may be reduced or eliminated by:

1) reducing the oxidizing power of the environment

2) cathodic protection

3) using brass containing a lower level of zinc

Graphitization of gray cast iron is the corrosion of iron, which leaves a weak network of graphite and corrosion products. Dimensional changes do not occur, and failure can be dramatic. This is corrosion of a two-phase structure and is not really analogous to dezincification, which involves a single solid phase.

CATERPILLAR®

SEBN8601 October 1991

Parts Manual

RT80 RT100 Telescopic Material Mandler

1GJ1-Up (Vehicle) 2FG1-Up (Engine) 3WE1-Up (Transmission)

Powered by 3114 Diesel Engine

CATERPILLAR®

SEBN8601 October 1991

RT80 RT100 Telescopic Material Handler

1GJ1-Up (Vehicle) 2FG1-Up (Engine) 3WE1-Up (Transmission)

© 1991 Caterpillar ALL RIGHTS RESERVED TECHNICAL INFORMATION DIVISION MARKETING SUPPORT SERVICES

LIFT TRUCK IDENTIFICATION

Caterpillar lift trucks are identified with SERIAL NUMBERS and ARRANGEMENT NUMBERS. In some cases MODIFICATION NUMBERS are also used. These numbers are shown on the serial number plate mounted on the cowling.

Caterpillar dealers need all of these numbers to determine which components were included on the machine when it was assembled at the factory. This permits accurate identification of replacement part numbers.

ORDERING PARTS

Quality Caterpillar Replacement parts are available from Caterpillar dealers throughout the world. Their parts stocks are up to date and include all parts normally required to protect your investment in Caterpillar lift trucks. Some dealers may have exchange/remanufactured parts available as an option. When ordering parts, your order should specify the quantity, part number, part name and the serial number, arrangement number and modification number of the machine for which the parts are needed. If in doubt about the part number, please provide your dealer with a complete description of the needed item.

HOW TO USE THE PARTS BOOK

Caterpillar Parts Books include illustrations of the groups or assemblies which make up the machine. These illustrations show the standard components and attachments for each machine.

The alphabetical index located in the front part of the book should be used to determine the page number on which specific illustrations are shown. Reference to those pages will identify each of the individual serviceable parts.

Captions

The caption under each illustration identifies the part number and name of the group or assembly shown. If more than one illustration is included for any group, the caption identifies the specific serial numbers to which each illustration applies. In some cases it is not possible to determine the specific serial numbers to which different illustrations are applicable. In those cases the caption identifies the illustration as "First Type", "Second Type", etc. Reference to the actual group or assembly is necessary in those cases to determine which illustration should be used. Captions provide additional information such as page numbers where illustrations of sub assemblies are shown, information regarding quantities used and other information intended to assist the user in determining parts needs.

Indented Part Names

Within each illustration is a parts list identifying each serviceable part in the illustration. When a part name is indented in this list, it means that serviceable item is a part of the serviceable item under which it is indented.

Abbreviations

- O.D. Outside diameter
- I.D. Inside diameter
- A Not Part of This Group
- B Use as Required
- C Indicates Change
- D Order by the Meter
- E Order by the Centimeter
- F Not Shown
- G Order by the inch
- I See Hose Fabrication Guide
- K See Mast Arrangement
- M Metric Part
- R Remfg Part May Be Available
- X Major Component Exchange
- Y Separate Illustration
- Z iver Serviced Separately

REMANUFACTURED COMPONENTS

As an option when making repairs consider Caterpillar Remanufactured Components. Components that are available through the Caterpillar Remanufactured Program are identified three ways in the parts book:

- -with the letter R in the note field of the parts list
- -with an R* at the beginning of the first line of the caption
- -with an #R at the end of the first line of the caption

Check with your local Caterpillar Dealer for the availability of Remanufacturad Components.

NOTE:

Continuing improvement and advancement of product design may cause changes to your machine which may not be included in this publication.

Whenever a question arises regarding your Caterpillar product, or this publication, please consult your Caterpillar dealer for the latest available information.

ENTIFICATION DU CHARIOT ÉLÉVATEUR

s chariots élévateurs Caterpillar portent un NUMÉRO DE RIE et un NUMÉRO DE VERSION. Dans certains cas, S NUMÉROS DE MODIFICATION sont également utiis. Ces numéros figurent sur la plaque signalétique qui trouve sur le capotage.

5 concessionnaires Caterpillar doivent connaître tous 3 numéros pour savoir quels composants ont été emyés lors du montage en usine et trouver plus facilement numéro des pièces de rechange.

IMMANDE DE PIÈCES

s concessionnaires Caterpillar fournissent dans le nde entier des pièces de rechange de qualité Caterpillar. urs stocks de pièces sont constamment réapprovinnés et comptent toutes les pièces nécessaires pour surer la bonne marche de votre chariot élévateur terpillar. Certains concessionnaires proposent égalent des pièces en échange standard ou rénovées, au vix. Lors des commandes de pièces, mentionner la antité, le numéro et la désignation des pièces ainsi que le néro de série, le numéro de version et, le cas échéant, le néro de modification du chariot auquel les pièces sont stinées. En cas de doute sur le numéro de pièce, fournir concessionnaire une description complète de la pièce en visition.

ILISATION DU CATALOGUE DE PIÈCES

: Catalogues de pièces Caterpillar comportent des illusions des groupes ou ensembles qui composent la mane. Ces illustrations représentent les composants stand et nombre des accessoires disponibles.

début du catalogue figure un index alphabétique qui voie aux pages et illustrations correspondantes. Toutes pièces du moteur avec leur numéro figurent dans ces jes.

iendes

ique illustration comporte une légende comprenant le néro de pièce et la désignation du groupe ou celle de semble. Si à un groupe donné correspondent plusieurs trations, la légende indiquera le numéro de série de que machine spécifique. Parfois, il n'est pas possible de nir à quels numéros de série spécifiques de la machine apportent les différentes illustrations. Dans ce cas, les indes comportent la mention "Premier type", "Deuxième 3", etc. Pour déterminer quelles illustrations utiliser, il ira connaître la référence du groupe ou du l'ensemble respondant. Les légendes indiquent également les nuos de page des plans des sous-ensembles, les quan-

tités utilisées et autres renseignements destinés à aider l'utilisateur à déterminer quelles sont les pièces nécessaires.

Désignations de pièces en retrait

Chaque illustration comporte la liste des pièces qui la constituent et que l'on peut se procurer. Lorsqu'une désignation de pièce est en retrait, cela veut dire que l'article en regard fait partie de l'ensemble sous lequel il figure.

Abréviations et symboles

- O.D. Diamètre extérieur
- I.D. Diamètre intérieur
- Α Ne fait pas partie de ce groupe B
 - Utiliser selon besoin
- С Mudification
- D Commander par mètre
- Commander par centimètre
- E F Non représenté
- G Commander par pouce
- L Flexible XT
- к Voir version de mât
- Pièce métrique М
- R Pièce rénovée éventuellement disponible
- Echange standard
- X Y Illustration séparée
- Z Non fourni séparément

PIÈCES RÉNOVÉES

En cas de réparations, tenir également compte de la disponibilité de certains composants Caterpillar rénovés. Dans le présent catalogue, ces pièces rénovées sont identifiées de trois manières:

- -par la lettre R dans la colonne Nota de la liste de pièces
- -par la lettre R° au début de la première ligne de la légende
- -par la lettre *R à la fin de la première ligne de la légende

Pour savoir si une pièce rénovée est disponible, consulter le concessionnaire Caterpillar.

NOTA:

En raison du progrès technique et des améliorations continuelles apportées au matériel, votre machine comporte peut-être des modifications qui n'apparaissent pas dans la présente publication.

En cas de doute sur un détail de votre machine Caterpillar ou sur le texte de la présente publication, adressez-vous à votre concessionnaire Caterpillar.



MONTACARGAS

Los montacargas Caterpillar se identifican con NUMEROS DE SERIE y NUMEROS DE DISPOSICION. En algunos casos se usan también NUMEROS DE MODIFICACION. Estos números se muestran en la placa de número de serie que se encuentra en el cubretablero.

Los distribuidores Caterpillar necesitan estos números para determinar con qué componentes se armó la máquina en la fábrica. Esto permite una identificación exacta de los números de pieza de repuesto.

COMO PEDIR REPUESTOS

Piezas de repuesto Caterpillar de calidad están disponibles de los distribuidores Caterpillar en todo el mundo. Sus existencias actualizadas incluven todas las piezas normalmente requeridas para proteger su inversión en montacargas Caterpillar. Algunos distribuidores pueden tener piezas remanufacturadas de intercambio, disponibles como opción. Al pedir piezas de repuesto, especifique en su pedido la cantidad, el número de pieza, el nombre de la pieza, el número de serie, el número de disposición y el número de modificación de la máquina para la cual se necesitan las piezas. Si tiene duda del número de pieza, déle al distribuidor una descripción completa de la misma.

COMO USAR ESTE CATALOGO

Los Catálogos de Piezas Caterpillar tienen ilustraciones de los grupos o conjuntos que componen la máquina. Estas ilustraciones muestran los componentes estándar y muchos de los accesorios disponibles para la máquina.

Se debe utilizar el indice alfabético al frente de este catálogo para determinar el número de página donde se encuentran ilustraciones específicas. Dichas páginas identifican las piezas utilizables.

Titulos

El título debajo de cada ilustración identifica el número de pieza y el nombre del grupo o del conjunto indicado. Si se incluve más de una ilustración de cualquier grupo, el título identifica números de serie de las máquinas correspondientes a cada ilustración. En algunos casos no es posible determinar los números de serie de las máquinas correspondientes a las diferentes ilustraciones. En esos casos, el título identifica la ilustración como "Primer tipo", "Segundo tipo", etc. Es necesario referirse al grupo o conjunto en si para determinar cuál ilustración se debe utilizar. Los títulos proveen información adicional: los números de las páginas en que aparecen las ilustraciones de los subconjuntos, las cantidades utilizadas y demás información para ayudar al usuario a determinar las piezas necesarias.

Nombres de Pieza sangrados

En cada ilustración hay una lista de piezas que identifica las piezas utilizables en la ilustración. Cuando el nombre de una pieza está sangrado en esta lista, significa que esta pieza forma parte de la pieza utilizable inmediatamente arriba.

Abraviaturas y símbolos

- O.D. Dlámetro exterior
- I.D. Diámetro interior
- A No es pieza de este grupo в
 - Utilizado según la demanda
- Ĉ Indica cambio
- Ď Se pide por metro ĒF
- Se pide por centimetro
- No se muestra
- G Se pide por pulgada
- ł Manguera XT
- κ Ver el mástil
- Μ Pieza métrica
- R Puede estar disponible como pieza remanufacturada
- Х Puede ser posible el intercambio de Componentes Principales
- Y Ilustración separada
- Ζ No se suministra por separado

COMPONENTES REMANUFACTURADOS

Al hacer reparaciones tenga en cuenta la disponibilidad de componentes remanufacturados Caterpillar. Dichos componentes se identifican de tres maneras en este catálogo de piezas:

- -con la letra R en la columna de Nota de la lista de piezas
- -con la letra R* al comienzo de la primera línea de la levenda
- -con la letra *R al final de la primera línea de la levenda

Para saber si un componente remanufacturado está disponible, consulte a su distribuidor Caterpillar.

NOTA:

Las continuas mejoras y adelantos en diseño podrían originar cambios a su máquina que no se incluyan en esta publicación.

Cuando tenga alguna pregunta acerca de su producto Caterpillar o de esta publicación, consulte al distribuidor Caterpillar para obtener la información más reciente.

L'IDENTIFICAZIONE DEL CARRELLO ELEVATORE

L'identificazione dei carrelli elevatori Caterpillar avviene tramite il NUMERO DI SERIE ed il NUMERO DEL TIPO DI ALLESTIMENTO. In alcuni casi viene usato anche il NU-MERO DELLA MODIFICA. Questi numeri sono stampigliati sulla targa di identificazione applicata al cofano.

Tutti questi numeri sono necessari ai dealer Caterpillar per poter determinare quali componenti sono stati impiegati nell'assemblaggio in fabbrica della macchina. Ciò rende possibile l'esatta identificazione dei numeri delle parti di ricambio.

COME ORDINARE I RICAMBI

I ricambi originali Caterpillar sono disponbili presso la rete internazionale di dealer Caterpillar. I magazzini dei dealer sono sempre aggiornati e sono provvisti di tutti i ricambi di normale consumo, necessari per proteggere il vostro investimento in carrelli elevatori Caterpillar. Molti dealer offrono anche gruppi completi in Programma Scambio o componenti ricostruiti da Caterpillar, affinché il cliente possa segliere l'alternativa più conveniente. Nelle ordinazioni di ricambi è necessario indicare quantità, numero e nome del ricambio, nonché il numero di serie, del tipo di allestimento e della modifica della macchina per la quale tali ricambi sono richiesti. In caso di dubbio relativo al numero del ricambio è opportuno fornire al dealer una completa descrizione del comonente a cui ci si riferisce.

COME USARE IL CATALOGO RICAMBI

I cataloghi ricambi Caterpillar illustrano i gruppi completi ed i sottogruppi che formano la macchina, ne visualizzano sia i componenti standard, sia anche alcuni degli accessori disponibili per la macchina.

L'indice alfabetico riportato all'inizio del catalogo deve essere usato per la ricerca del numero di pagina nella quale si possono trovare le singole illustrazioni specifiche. La consultazione di queste pagine consente l'identificazione di ciascun componente separatamente disponibile.

Leggende

La leggenda al piede di ciascuna illustrazione identifica il numero del ricambio ed il nome del gruppo o sottogruppo illustrato. I numeri di ricambio per gruppi completi sono riportati a titolo indicativo. Per conoscere la disponibiliità di gruppi completi è opportuno sentire il vostro dealer CAT. Se per il medesimo gruppo esiste più di una illustrazione la leggenda identifica i numeri specifici di serie delle macchine a cui ciascuna illustrazione si riferisce. In alcuni casi non è possibile stabilire i numeri specifici di serie delle macchine alle quali le diverse illustrazioni possono essere attribuite. In questi casi la leggenda identifica l'illustrazione come "Tipo 1" – "Tipo 2", ecc. In queste condizioni è necessario confrontare le illustrazioni con il gruppo completo, o con il sottogruppo, da sostiituire. La leggenda fornisce anche altre informazioni, come i numeri delle pagine nelle quali appaiono le illustrazioni dei sottogruppi, le quantità utilizzate ed alter notizie utili per assistere il cliente nella selezione dei ricambi occorrenti.

Nomi di Ricambi Fuori Colonna

All'interno di ogni illustrazione c'è un elenco dei ricambi che fanno parte del gruppo. Quando, in questa lista, il nome di un ricambio è stampato fuori colonna ció indica che è un componente dell'assieme precedente soprastante.

Abbreviazioni

- O.D. Diametro esterno
- I.D. Diametro interno
- A No fa parte di questo gruppo
- B Da Impiegare secondo necessita
- C Indica un cambiamento
- D Si ordina a metraggio
- E Si ordina per centimetri
- F No illustrato
- G Si ordine per pollici

1

- Complessivo tubi flessibili CAT-XT
- K Vedere composizione montante
- M Particolare costruito con misure metriche
- R Possibile disponibilità componente ricostruito
- X Gruppo in Programma Scambio
- Y Illustrato separatamente
- Z No viene fornito separatamente

COMPONENTI RICOSTRUITI

Quando eseguite una riparazione prendete in considerazione l'uso di componenti ricostruiti da Caterpillar. Nel catalogo ricambi questi particolari sono così identificati:

- -Con la lettera "R" nella colonna "NOTE" dell'elenco ricambi
- --Con la lettera "R*" all'inizio della prima riga della leggenda
- -Con la lettera ""R" alla fine della prima riga della leggenda.

Sentite il vostro dealer Caterpillar in merito alla disponibilità di componenti ricostruiti.

AVERTENZA

Il costante perfeizionamento progettuale dei nostri prodotti può comportare modifiche già introdotte nella vostra macchina, ma non ancora incluse in questo catalogo ricambi.

Per qualisiasi domanda che riguardi il vostro prodotto Caterpillar o questo catalogo vi preghiamo di rivolgervi direttamente al vostro dealer Caterpillar che vi darà le informazioni più aggiornate.

GABELSTAPLERKENNZEICHNUNG

Cat-Gabelstapler sind mit SERIAL NUMBERS und AR-RANGEMENT NUMBERS (Serien-Nr. und Ausrüstungs-Nr.) gekennzeichnet. In einigen Fällen werden auch MODI-FICATION NUMBERS (Änderungsnummern) verwendet. Diese Nummern befinden sich auf dem Typenschild an der Motorhaube.

Die Cat-Händler benötigen alle genannten Nummern, um feststellen zu können, welche Baugruppen bei der Montage des Geräts im Werk eingebaut wurden. Nur mit Hilfe dieser Angaben lassen sich die Bestellnummern der benötigten Ersatzteile genau bestimmen.

BESTELLEN VON ERSATZTEILEN

Original-Cat-Ersatzteile können bei den Cat-Händlern überall auf der Welt bestellt werden. Ihre umfangreichen Lager enthalten normalerweise alle Teile, die Sie für Ihren Cat-Gabelstapler benötigen. Einige Händler bieten Reparatursätze, Austausch- oder werküberholte Teile an, so daß Sie die Auswahl unter verschiedenen Reparaturmöglichkeiten treffen können. Ihre Bestellung muß folgende Angaben enthalten: Anzahl der benötigten Teile, Bestellnummer, Bezeichnung des Teils; Serien-Nr., Ausrüstungs-Nr. und Änderungs-Nr. des Geräts, für das die Teile benötigt werden. Wenn Sie Zweifel hinsichtlich der richtigen Bestell-Nr. haben, geben Sie dem Händler eine möglichst genaue Beschreibung des benötigten Teils.

HINWEISE ZUR BENUTZUNG DES PARTS BOOKS

Die Cat-Parts Books enthalten Zeichnungen der Gruppen oder Teile des Geräts. Gezeigt werden die Standardteile sowie verschiedenes Zubehör für die Geräte.

Anhand des Index vorn im Buch können Sie die Nummer der Seite heraussuchen, auf der sich die von Ihnen gesuchte Abbildung befindet. Beim Aufschlagen der betreffenden Seite können dann alle gesuchten Teile identifiziert werden. Hinten im Buch befindet sich ein numerischer Index, mit allen Bestell-Nr. und dem Hinweis auf die Seite, auf der sich die entsprechenden Zeichnungen befinden.

Bildunterschriften

Die Zeilen unter jeder Abbildung enthalten die Bestell-Nr. der gezeigten Baugruppen. Die Nummer wird nur als Referenz aufgeführt. Ihr Cat-Händler kann Ihnen sagen, ob eine Gruppe komplett lieferbar ist. Wenn für eine Gruppe mehrere Zeichnungen vorhanden sind, enthalten die Zeilen unter den Zeichnungen die Seriennummern, genen jede Zeichnung entspricht. In einigen Fällen ist es nicht möglich, die Serien-Nr. anzugeben, auf die sich die Zeichnungen beziehen. In diesem Fall wird lediglich First Type (Typ 1), Second Type (Typ 2) usw. angegeben. Hier ist ein Hinweis auf die Baugruppe erforderlich, um anzuzeigen, welche Abbildung verwendet werden muß. Die Zeilen unter den

Abbildungen enthalten ferner Angaben über die Seiten, auf denen sich Zeichnungen von Unterbaugruppen und Anzahl der benötigten Teile sowie andere Angaben befinden, die es dem Benutzer des Buchs erleichtern, die gewünschten Teile zu identifizieren.

Eingerückte Bezeichnungen

In der zu jeder Abbildung gehörenden Ersatzteilliste sind manche Bezeichnungen eingerückt. Dadurch wird angezeigt, daß das entsprechende Teil zu dem gehört, unter dessen Bezeichnung es eingerückt ist.

Abkürzungen und Symbole

- O.D. Außendurchmesser
- Innendurchmesser I.D.
- Α kein Teil dieser Gruppe
- в nach Bedarf verwenden
- С Hinweis auf eine Änderung
- D in Meter-Länge bestellen
- Ε in Zentimeter-Länge bestellen
- F nicht gezeigt
- G in Zoll-Länge bestellen
- L
- XT-Schlauch
- siehe Mast-Ausrüstung К
- metrisches Teil Μ
- R werküberholtes Teil unter Umständen lieferbar Х Austauschteil
- Y separate Abbildung
- Z nicht einzeln erhältlich

WERKÜBERHOLTE BAUGRUPPEN

Beim Durchführen von Reparaturen sollte auch die Verwendung von werküberholten Baugruppen in Betracht gezogen werden. Derartige Teile sind im Parts Book auf drei verschiedene Arten gekennzeichnet:

- -durch den Buchstaben R in der Spalte "NOTE" der Ersatzteilliste:
- -durch "R*" zu Beginn der ersten Zeile der Bildunterschrift;
- -durch ""R" am Ende der ersten Zeile der Bildunterschrift.

Erkundigen Sie sich bei Ihrem Cat-Händler nach der Verfügbarkeit von werküberholten Teilen.

ANMERKUNG:

Ständig vorgenommene Verbesserungen und Weiterentwicklungen an Ihrem Gerät können Änderungen verursachen, die in der vorliegenden Ausgabe noch nicht berücksichtigt sind. Sie werden jedoch in später folgenden Ausgaben erscheinen.

Fragen zu Ihrem Cat-Gerät oder diesem Ersatzteilbuch beantwortet Ihr Cat-Händler.

MAINTENANCE PARTS

DESCRIPTION	PART NO.	PAGE NO.
BREATHER	9G5127	80
BREATHER AS	2W9162	33
ELEMENT AS (PRIMARY)	7W3920	42
ELEMENT AS-SECONDARY	7C1062	42
ELEMENT-FILTER	ST9054	92
FILTER AS-FUEL	1R0711	57
FILTER AS-OIL	1R0714	30
REGULATOR-TEMP	9Y3365	37
V-BELT	618384 9L1553	39 23

EBN8601

c.1

REMANUFACTURED COMPONENTS

As an option when making repairs consider Caterpillar Remanufactured Components. Components that are available through the Caterpillar Remanufactured Program are identified three ways in the parts book:

- with the letter R in the note field of the parts list
- with an R* at the beginning of the first line of the caption
- with an *R at the end of the first line of the caption

Typical components included in the Remanufacturing Program include:

ALTERNATORS CONNECTING RODS CRANKSHAFTS - UNDERSIZE CRANKSHAFTS - UPGRADE TO NEW CYLINDER HEADS ELECTRONIC CONTROL MODULES (ECM) **ELECTRONIC SENSORS** FUEL INJECTORS FUEL NOZZLES FUEL PUMPS GOVERNORS **OIL PUMPS** PISTONS SHORT BLOCKS **STARTERS TURBOCHARGERS - COMPLETE** TURBOCHARGER CARTRIDGES WATER PUMPS

Caterp!llar Remanufactured engines for many engine arrangements are also available.

MAJOR COMPONENT EXCHANGE

As an option when making repairs consider Caterpillar Major Component Exchange Program. Components included in this program are noted in the parts book with an *X at the end of the first line of the caption.

Typical components include:

ENGINES PISTON TYPE HYDRAULIC MOTORS PISTON TYPE HYDRAULIC PUMPS SHORT BLOCKS TRANSMISSIONS TORQUE CONVERTERS STEERING BRAKE AND CLUTCH

Check with your local Caterpillar Dealer for the availability of Remanufactured Components and Major Component Exchanges.

	IND	EX 1	
ENGIN	E ARRANGEMENT	FUEL	(ENGINE)
AGE No	TITLE	PAGE No	TITLE
2	ENGINE ARRANGEMENT	48	PUMP GROUP - FUEL INJECTION
		48	CONTROL GROUP - GOVERNOR
BASIC	ENGINE	49	GOVERNOR GROUP - UNIT INJECTOR
PAGE No	TITLE	50	GOVERNOR GROUP - UNIT INJECTOR
4	CYLINDER BLOCK GROUP	52	DRIVE GROUP - GOV. AND TRANSFER PUMP
5	CYLINDER BLOCK GROUP	54 55	CONTROL GROUP - FUEL INJECTION LINES GROUP - FUEL FILTER
6	COVER GP - CYLINDER BLOCK	55	LINES GROUP - GOVERNOR OIL
7	CRANKSHAFT GROUP	57	FILTER GROUP - FUEL
8 .	SEAL GROUP - CRANKSHAFT	58	FASTENER GROUP GOVERNOR
8 9		ELEC	TRICAL
10	FLYWHEEL GROUP PISTON AND ROD GROUP		
11	CAMSHAFT GROUP - SINGLE	ISYST	EM (ENGINE)
12	CYLINDER HEAD GROUP	PAGE No	TITLE
13	CYLINDER HEAD GROUP	60	INSTRUMENT GROUP
14	CYLINDER HEAD A.S.	61	ALTERNATOR GROUP
15	CYLINDER HEAD A.S.	62	ALTERNATOR GROUP - CHARGING -12 VOLT
16	MECHANISM GROUP - FUEL PUMP AND VALVE	63	STARTING MOTOR GROUP-ELECTRIC-12 VOLT
17 18	ROCKER ARM GROUP COVER GROUP - VALVE MECHANISM	64 65	STARTING MOTOR GROUP-ELECTRIC-12 VOLT SOLENOID GROUP - SHUT - OFF 12 VOLT
16	GEAR GROUP - FRONT		
20	HOUSING GROUP - FRONT	ENGI	NE RELATED PARTS
21	PULLEY GROUP - CRANKSHAFT	PAGE No	TITLE
22	DRIVE GROUP - FAN	66	POWER GROUP
23	PULLEY GROUP - FAN DRIVE	67	ENGINE GROUP
24	PAN GROUP - OIL	68	ENGINE MOUNTING GROUP
25	COVER GROUP - OIL PAN	69	FUEL LINE GROUP
25 26		70	
_	CARRIER GROUP - SEAL	71	AIR CLEANER GROUP RADIATOR GROUP
UBRIC	CATION SYSTEM	73	ENGINE DRIVE SHAFT GROUP
AGE No	TITLE	74	FLEXIBLE COUPLING
27	BALANCER GROUP	75	THROTTLE GROUP
28	PUMP GROUP - ENGINE OIL	76	ETHER START GROUP
29	PUMP GROUP - ENGINE OIL	TDAN	SMISSION AND
30	FILTER GROUP - ENGINE OIL	1	
30		DRIVE	TRAIN
31		PAGE No	TITLE
31 32	GAUGE GROUP - OIL LEVEL (DIPSTICK)	78	TRANSMISSION GROUP
32 32	FUMES DISPOSAL GROUP	79	TRANSMISSION A.R.
33	BREATHER GROUP	80	CASE AND PARTS GROUP
33	DRAIN GROUP - OIL PAN	62	CLUTCH GROUP
	NG (ENGINE)	84	CLUTCH GROUP
	· · · · · · · · · · · · · · · · · · ·	86	CLUTCH GROUP
	TITLE FAN GROUP - SUCTION	88	PUMP GROUP - CRESENT
34 35	PUMP GROUP - SUCTION PUMP GROUP - WATER	89	PUMP GROUP - CRESENT
35	PUMP GROUP - WATER - R	90	VALVE GROUP - FLOW CONTROL
37	LINES GROUP - WATER	91 92	LINES GROUP - POWER TRAIN OIL FILTER GROUP - TRANSMISSION
38	COOLER GROUP - ENGINE OIL	93	CONTROL GROUP - TRANSMISSION CONTROL GROUP - TRANSMISSION HYDRAULIC
39	DRIVE GROUP - WATER PUMP	94	VALVE GROUP
IR INI	ET AND EXHAUST	96	VALVE GROUP - CONTROL
		97	VALVE GROUP - SELECTOR AND PRESS .CONT.
YSTE	M (ENGINE)	99	DRIVE GROUP - FLEXIBLE COUPLING
AGE No	TITLE	100	DRIVE GROUP - TRANSFER
40	MANIFOLD GROUP - EXHAUST	101	CONTROL GROUP - TRANSMISSION
41	MANIFOLD GROUP - INLET	103	
42	COVER GROUP - INLET MANIFOLD	105 106	MOUNTING GROUP (TRANSMISSION)
42	AIR CLEANER GROUP	106	TRANSMISSION PIPING GROUP FILLER GROUP
44	TURBOCHARGER GROUP	108	UNIVERSAL JOINT GROUP (TRANSMISSION)
45	LINES GROUP - AIR	109	DRIVESHAFT GUARD GROUP
46	LINES GROUP - TURBOCHARGER OIL		

IN	DEX 2
ASSESS AND BRAKES PAGE NO TITLE 11 FRONT AXLE G.P (RT80) 12 FRONT AXLE G.P (RT100) 13 REAR AXLE GROUP (RT80) 14 REAR AXLE GROUP (RT80) 15 FRONT AXLE SUB. GROUP (RT80) 16 FRONT AXLE SUB. GROUP (RT80) 17 REAR AXLE SUB. GROUP (RT80) 18 REAR AXLE SUB. GROUP (RT80) 19 DIFFERENTIAL CASING GROUP - FRONT 10 DIFFERENTIAL GROUP - FRONT RT80 12 DIFFERENTIAL GROUP - FRONT RT80 12 DIFFERENTIAL GROUP - FRONT RT100 13 DIFFERENTIAL GROUP - REAR RT80 14 DIFFERENTIAL GROUP - REAR RT80 15 AXLE CASING GROUP - RT80 16 DISC BRAKE GROUP - RT80 17 AXLE CASING GROUP - RT80 18 DIFFERENTIAL GROUP - REAR RT80 19 DISC BRAKE GROUP - RT80 12 DISC BRAKE GROUP - RT80 13 DISC BRAKE GROUP - RT80 REAR 13 DISC BRAKE GROUP - RT80 REAR 13 DISC BRAKE GROUP - RT80 REAR 13 DISC BRAKE GROUP - RT80 REAR	DEX 2 PAGE No TITLE 149 HYDRAULIC PIPING G.P CHASSIS 151 HYD. AND FUEL TANK MTG. GROUP 152 HYDRAULIC AND FUEL TANK GROUP 153 FILTER GROUP 154 STACK PIPE GROUP 155 HYDRAULIC VALVE GROUP - 4 SPOOL 168 HYD. PIPING G.P DIFF LOCK 169 COMPENSATING VALVE GROUP 170 SINGLE OVERCENTRE VALVE GROUP 171 COUNTERBALANCE VALVE GROUP 172 OVERCENTRE LOCK VALVE GROUP 173 DUAL OVERCENTRE VALVE GROUP 174 HYDRAULIC PIPING OUTRIGGERS 177 DUAL OVERCENTRE VALVE 178 COMPENSATING MANIFOLD WITH BY - PASS
TEERING SYSTEM GE No TITLE 141 STEERING CONSOLE GROUP 142 HYD. PIPING GP - STEERING 144 SELECTOR VALVE GROUP 144 PUMP GROUP - METERING 145 STEERING COLUMN GROUP 146 STEERING COLUMN SWITCH GROUP 147 DIRECTIONAL CONTROL VALVE GROUP	FRAME AND PANELS PAGE No TITLE 179 CHASSIS FRAME GROUP 180 ENGINE COWL AND PLATFORM GROUP 182 SOUND SUPPRESSION GROUP - RT80 183 BALLAST WEIGHT GROUP - RT80 184 BALLAST WEIGHT GROUP - RT100 185 FRAME LEVEL GROUP 186 FRAME LEVEL RAM GROUP 187 FRAME LEVEL RAM GROUP 188 TOW HOOK GROUP 189 OUTRIGGER BEAM GROUP 190 OUTRIGGER RAM GROUP 191 OUTRIGGER RAM GROUP 194 YANDALISM GROUP

Ť

	INI	DEX 3			
BOOM AGE No 195 196 197 198 200 201 202 203 204 205 206 207 208 209 210 211 211 212 213 214 215 216 217 218 219 220 221 221 222 223 224 225 226 227 228	TITLE THREE SECTON BOOM GROUP No 1 BOOM SECTION GROUP No 2 BOOM SECTION GROUP BOOM HEAD SECTION GROUP TELESCOPING GROUP TELESCOPING CYLINDER GROUP TELESCOPING RAM GROUP CHAIN GROUP FORK LEVEL GROUP FORK LEVEL CYLINDER GROUP FORK LEVEL CYLINDER GROUP BOOM RAISE GROUP BOOM RAISE GROUP BOOM RAISE RAM GROUP BOOM RAISE RAM GROUP BOOM RAISE RAM GROUP BOOM RAISE RAM GROUP BOOM HYDRAULIC GROUP AUXILIARY 2 SERVICE GROUP WEAR PAD GROUPS ROLLING HOSE GROUP COMPENSATING GROUP COMPENSATING CYLINDER GROUP WEAR FAD GROUPS ROLLING HOSE GROUP COMPENSATING CYLINDER GROUP FRAMERS FORK CARRIAGE GROUP FRAMERS FORK CARRIAGE GROUP HYDRAULIC PIPING GP - ROTATE FORKS HYDRAULIC QUICK HITCH GROUP AUXILIARY HYDRAULIC AUCK HITCH GROUP AUXILIARY HYDRAULIC QUICK HITCH GROUP	ELEC PAGE No 255 257 253 259 261 262 263 264 265 266 267 268 269 270 271 272 273 274 275 276 276 276 277 277 277 278 279 280 281	THICAL EQUIPMENT TITLE ELECTRICAL G.P CHASSIS ELECTRICAL GROUP - DASHPANEL FUSE AND RELAY PANEL GROUP ELECTRICAL GROUP - CAB JOYSTICK GROUP ELECTRICAL G.P OWERBRAKE ELECTRONIC CONTROL BOX GROUP ELECTRONIC CONTROL BOX GROUP AUTO HEIGHT/REACH GROUP BOOM WORKLAMP GROUP COLD START GROUP ROAD LIGHTING BEACON GROUP LAMP GROUP - ROTATING WARNING ROAD LIGHTING GROUP (ALL WEATHER CAB) - RIGHT HAND DIP ROAD LIGHTING G.P. (STANDARD CAB) - L.H. DIP ROAD LIGHTING G.P. (STANDARD CAB) - L.H. DIP ROAD LIGHTING G.P. (STANDARD CAB) - R.H. DIP RAMP GROUP (L.H. DIP) L.H. FRONT LIGHT GROUP (L.H. DIP) L.H. FRONT LIGHT GROUP (RIGHT HAND DIP) R.H. FRONT LIG		
229	RADIUS / ANGLE INDICATOR GROUP				
			LS TITLE		
AB 233 234 235 236 237 238 239 240 240 241 243 245 246 247 248 249 249 249 250 251 252	TITLE OPEN CAB GROUP CAB GROUP - BASIC DE LUXE ALL WEATHER CAB GROUP ALL WEATHER CAB GROUP MIRROR GROUP WING MIRROR GROUP DASHPANEL GROUP DOCUMENT POUCH GROUP SEAT CLOSING PLATE GROUP SEAT CLOSING PLATE GROUP SEAT GROUPS OPERATORS CAB DOOR GROUP MAT GROUP - CAB INTERIOR CAB HEATER GROUP WINDSCREEN GRILL GROUP RADIO/CASSETTE GROUP WASHER GROUP - (FRONT SCREEN) WINDSCREEN WIPER GROUP RAD GROUP CAB GLAZING GROUP	283 284 285 286 287 288 289	ENGLISH DECALS CROUP FRENCH, SPANISH, ITALIAN AND GERMAN DECALS GROUPS DANISH (AEEK DUTCH AND PORTUC'JESE DECAL GROUPS FRENCH AND SPANISH (NACD) DECAL GROUPS CAPACITY CHART GROUPS RTB0 (COSA) CAPACITY CHART GROUP RTB0 (USA) CAPACITY CHART GROUP RT100 (USA)		

ENGINE ARRANGEMENT

 \bigcirc

0

497494 P

			PAGE
1	977235	ALTERNATOR GP	61
1	7E3686	BALANCER GP	27
1	1N3477	BREATHER GP	33
1	4W4865	CAMSHAFT GP-SINGLE	11
1	4W3462	CARRIER GP-SEAL	26
1	788600	CONTROL GP-FUEL INJECTION	54
1	705201	CONTROL GP-GOVERNOR	48
1	4₩4869	COOLER GP-ENGINE OIL	38
1	188897	COVER GP-CYLINDER BLOCK	6
1	7₩9847	COVER GP-FRONT	21
1	7C2290	COVER GP-INLET MANIFOLD	42
1	9Y8048	COVER GP-DIL PAN	25
1	7W7337	COVER GP-VALVE MECHANISM	18
1	483579	CRANKSHAFT GP	7
1	483724	CYLINDER BLOCK GP	4
1	7E4211	CYLINDER HEAD GP	12
1	7C4566	DRAIN GP-OIL PAN	33
1	7C4532	DRAIN GP-OIL PAN	32
1	700044	DRIVE GP-FAN	22
1	4₩5428	DRIVE GP-WATER PUMP	39
1	7W4812	FASTENER GP-GOVERNOR	58
1	788798	FILLER GP-OIL	31
1	700896	FILTER GP-ENGINE OIL	30
1	1N3476	FILTER GP-FUEL	57
1	9Y 1384	FLYWHEEL GP	9
1	7\8420	FUMES DISPOSAL GP	32
1	7w8796		31
1	7E3756	GEAR GP-FRONT	19
1	973833	GOVERNOR GP-UNIT INJECTOR	49
1		HOUSING GP-FLYWHEEL	
1	7L0002	HOUSING GP-FRONT	20

7C5477 ENGINE AR-PART 1 OF 2 S/N 2FG1-Up

ENGINE ARRANGEMENT

PAGE

1	7E9408	INSTRUMENT GP 60
1	4W2515	LIFTING GP 25
1	486609	LINES GP-AIR
1	7C0897	LINES GP-ENGINE DIL
1	7W9854	LINES GP-FUEL FILTER
1	7W8434	LINES GP-GOVERNOR OIL
1	486615	LINES GP-TURBOCHARGER OIL
1	9Y7743	LINES GP-WATER
1	188898	MANIFOLD GP-EXHAUST 40
1	4W5362	MANIFOLD GP-INLET 41
1	4₩4866	MECHANISM GP-FUEL PUMP & VALVE 16
1	1W7632	PAN GP-OIL 24
4	7E3429	PISTON & ROD GP 10
1	9Y4914	PULLEY GP-CRANKSHAFT 21
1	9Y7234	PULLEY GP-FAN DRIVE 23
1	7E2971	PUMP GP-ENGINE OIL 28
4	729711	PUMP GP-FUEL INJECTION
1	4W7589	PUMP GP-WATER
_		
1		SEAL GP-CRANKSHAFT 8
1	7C7695	
1	788759	STARTING MOTOR GP-ELECTRIC
1	7E5202	TURBOCHARGER GP 44

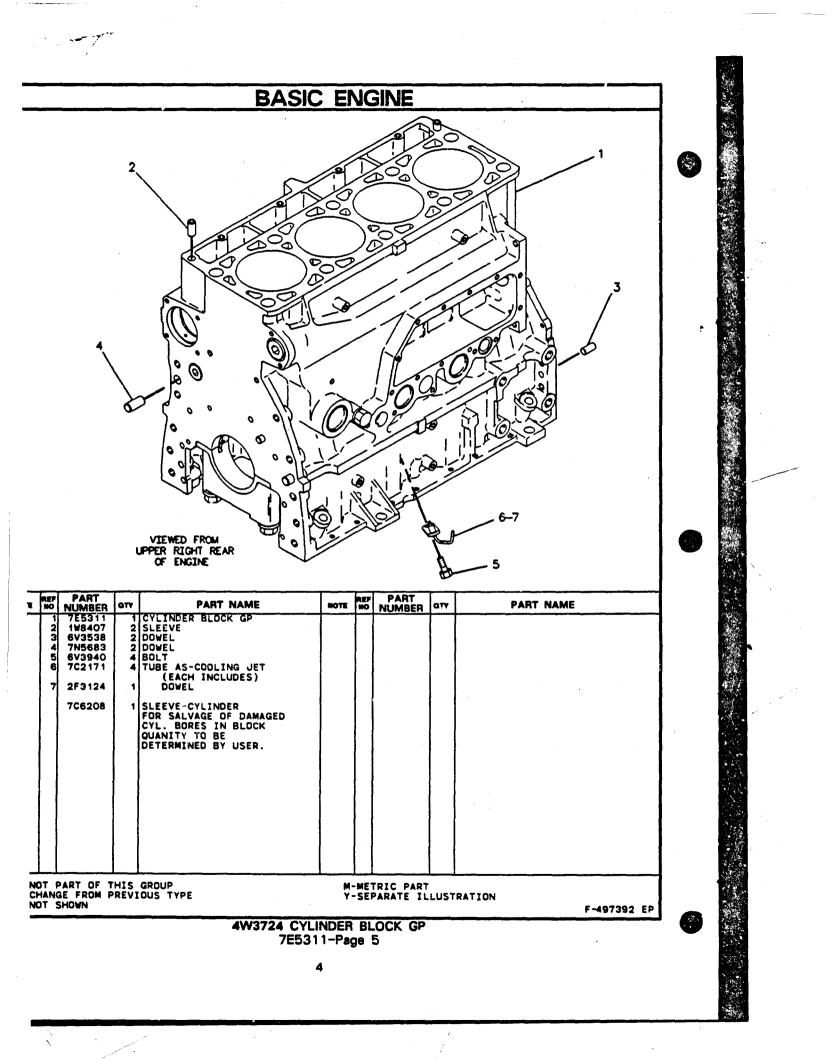
藏.

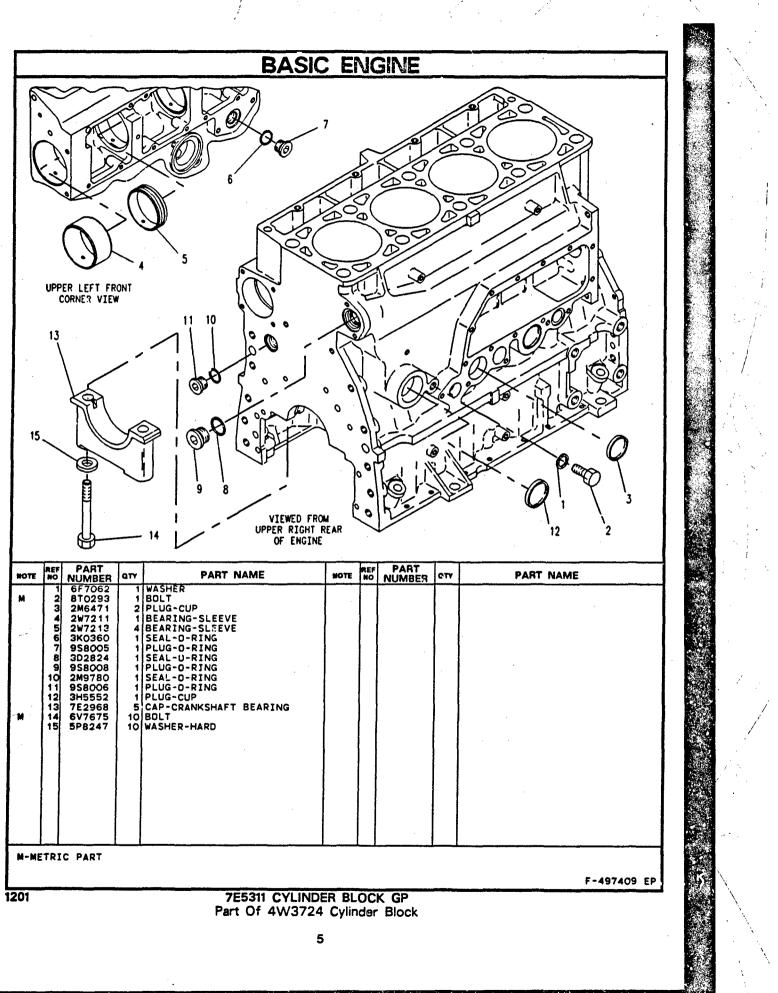
497494 P

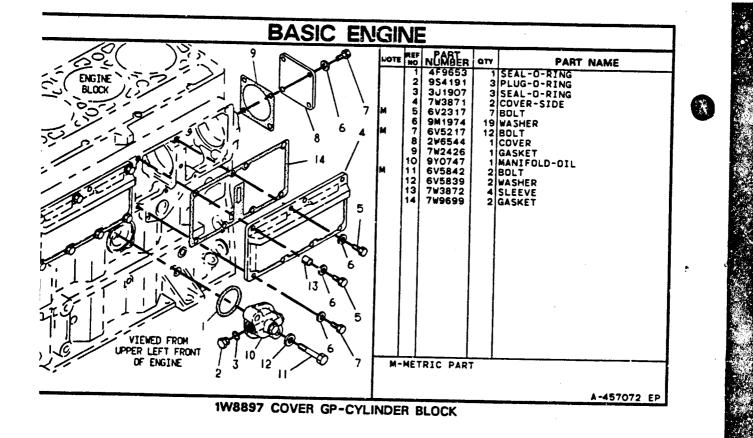
7C5477 ENGINE AR-PART 2 OF 2 S/N 2FG1-Up

3

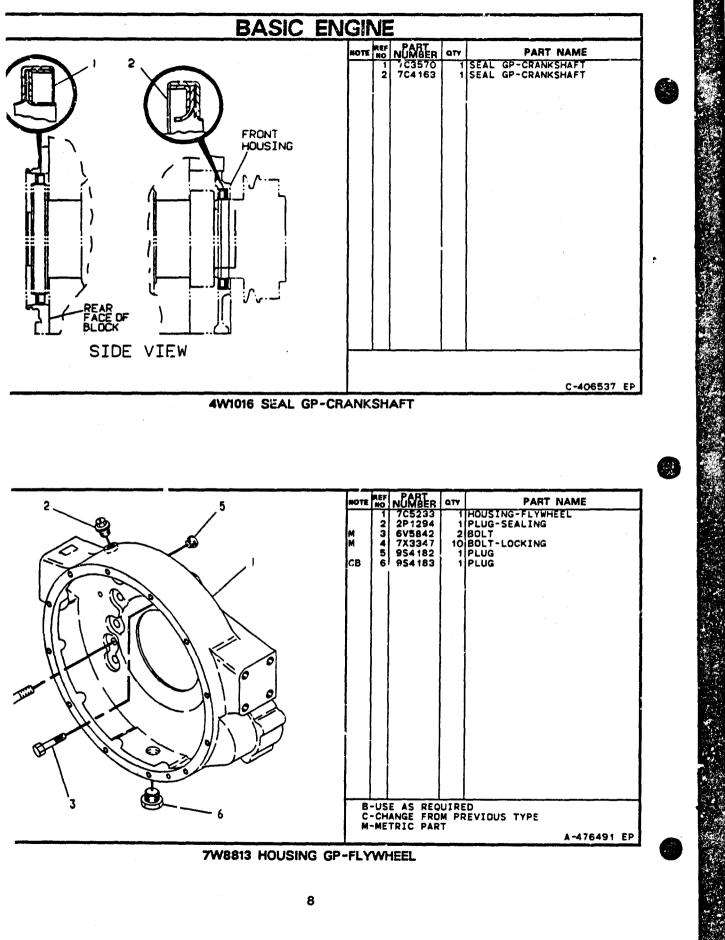
• ,



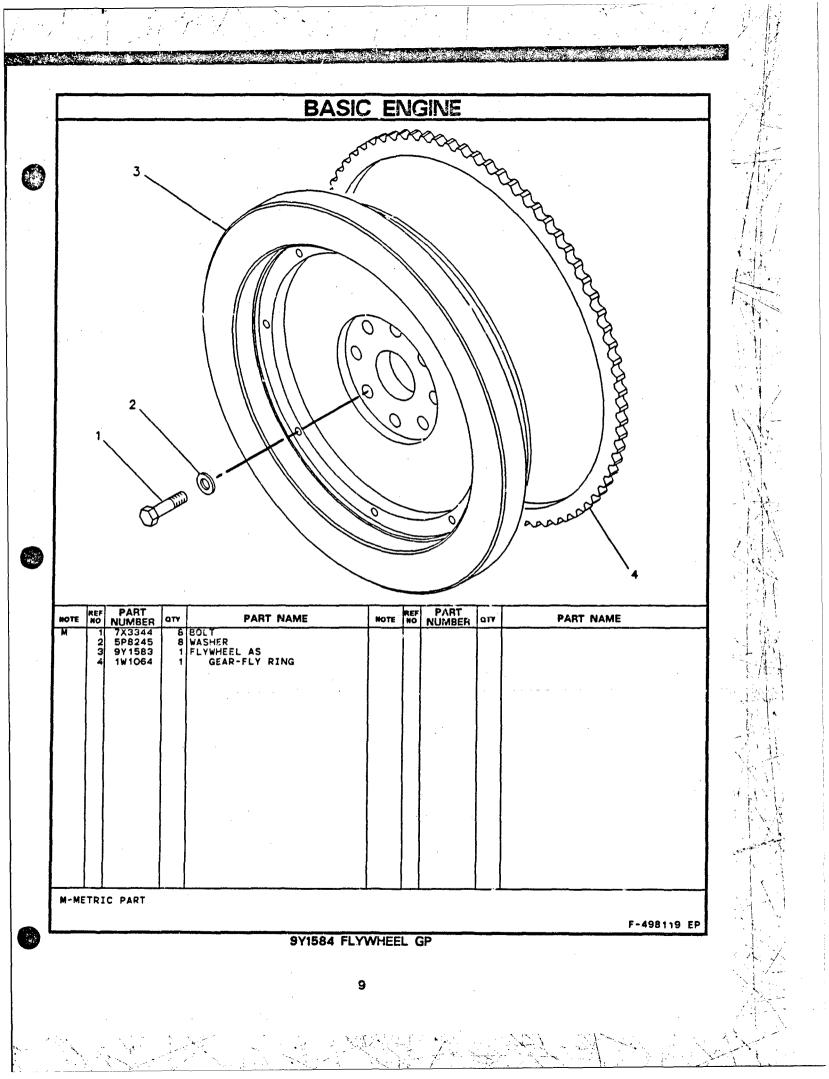




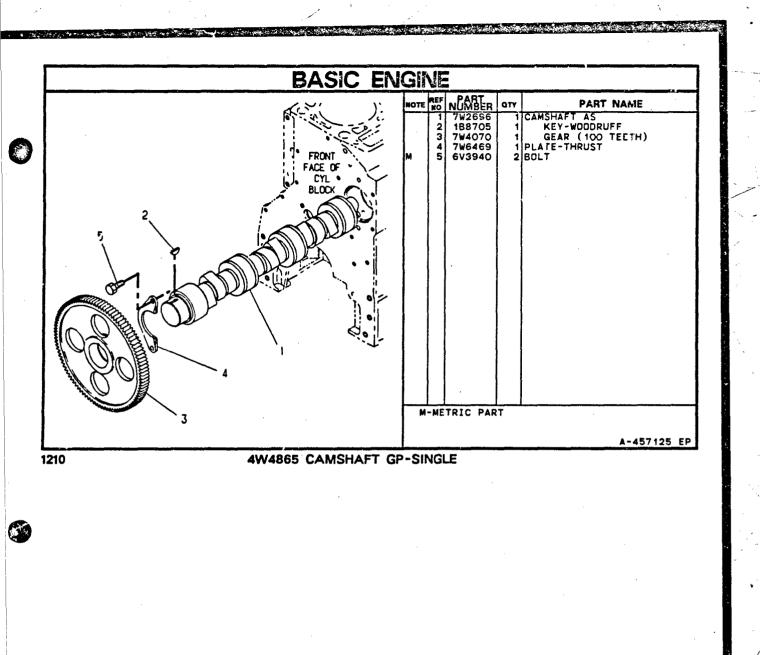
	ENGINE
REF PART NUMBER atv PART NAME 1 4W3989 1 CRANKSHAFT AS 2 188705 1 KEY-WODDRUFF 3 2W8147 1 GEAR (50 TEETH) 4 7W9416 1 BEARING-THRUST 7C6969 BEARING-THRUST 0.5MM OS 7C6970 BEARING-THRUST 0.5MM US 7C6966 BEARING-THRUST 0.5MM US 7C6967 BEARING-THRUST 0.5MM US 7C6974 BEARING-MAIN 0.5MM US 7C6975 BEARING-MAIN 0.5MM US 7C6976 BEARING-MAIN 0.5MM US 7C6971 BEARING-MAIN 0.5MM US 7C6972 BEARING-MAIN 0.5MM US 7C6973 BEARING-MAIN 0.5MM US 7C6974 BEARING-MAIN 0.5MM US 7C6975 BEARING-MAIN 0.5MM US 7C6974 BEARING-MAIN 0.5MM US 7C6975 BEARING-MAIN 0.5MM US 7C69761 BEARING-MAIN 0.5MM U	NOTE NOTE NUMBER OT PART NAME
NOT PART OF THIS GROUP NOT SHOWN 4W3579 CRANK	F-467199 EP



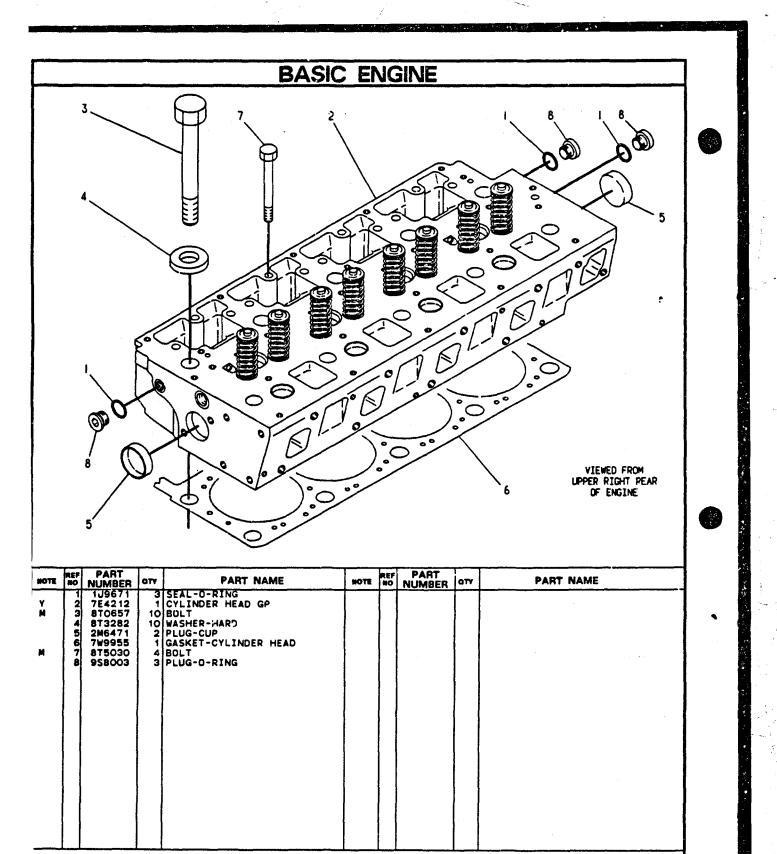
The and the filling



				BASIC) Ei	VC	SINE			
			5							
									11	
NOTE	REF	PART NUMBER 7E3428	077	PART NAME BODY AS-PISTON	HOTE	REF NO	PART NUMBER	aty	PART NAME	
A A R		7C0260 7E5786 7C5232 7C0111 7C0115 7V9415 7C6976 7C6977	1 1 2 1 1 1	RING-PISTON (TOP) RING-PISTON (INTERMEDIATE) RING-PISTON (OIL) RETAINER-PIN PIN-PISTON BEARING-CONVECTING ROD BEARING (.5MM US) BEARING (.5MM US) ROD AS-CONNECTING BEARING BOLT-CONNECTING ROD						



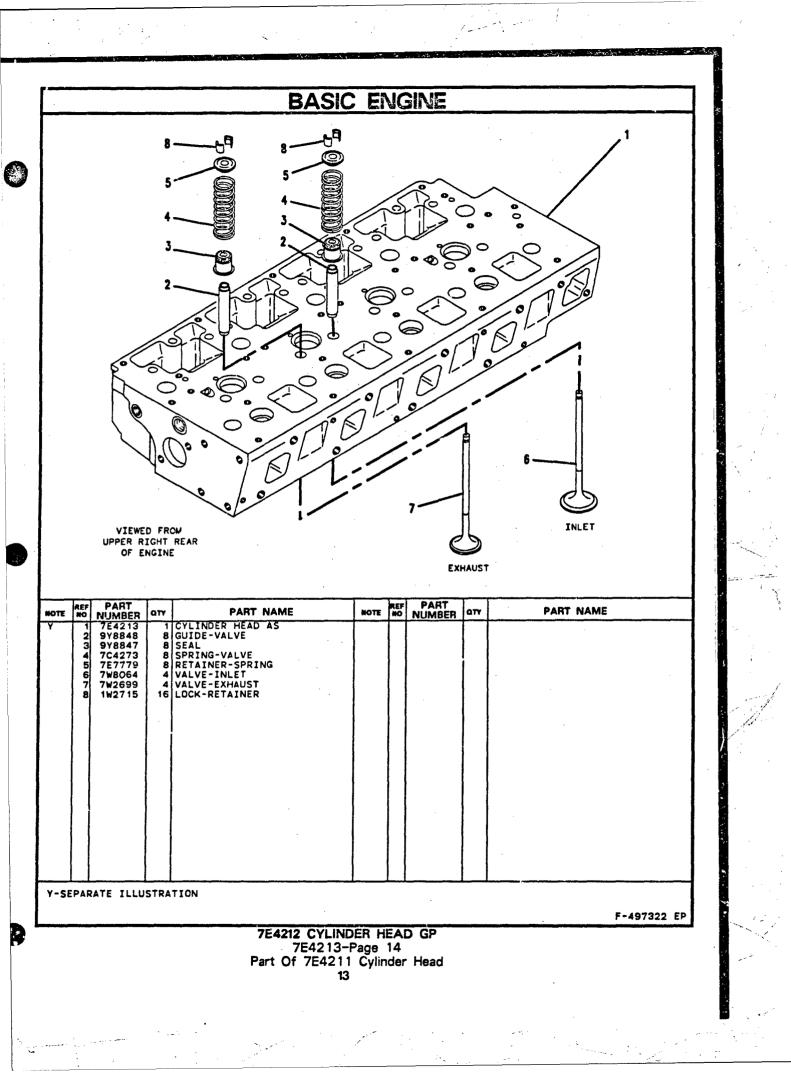
្លីភ្ន

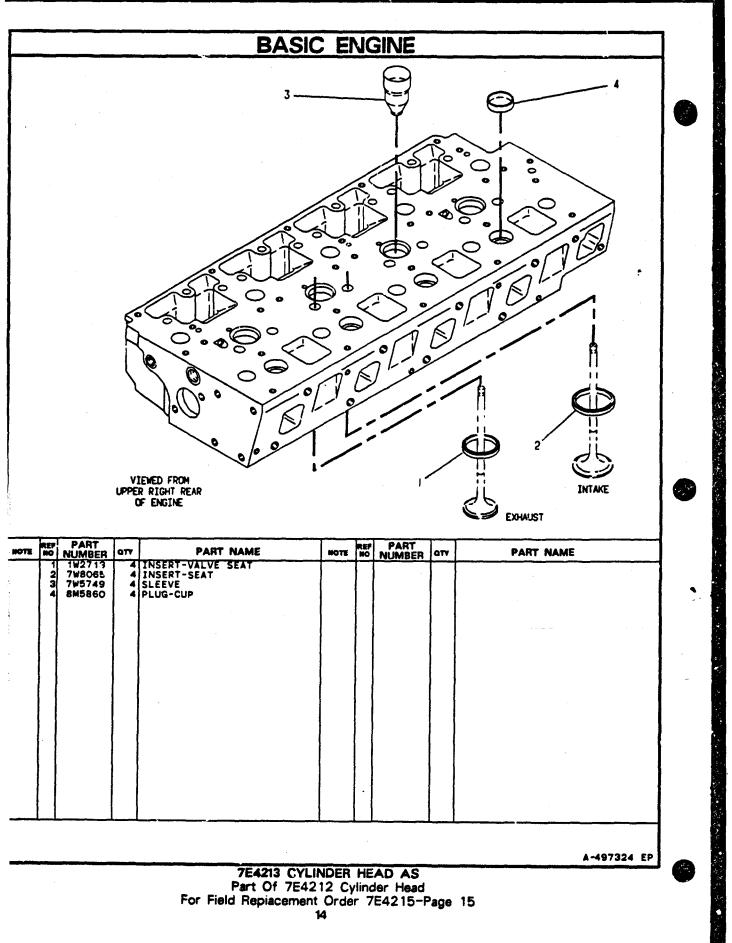


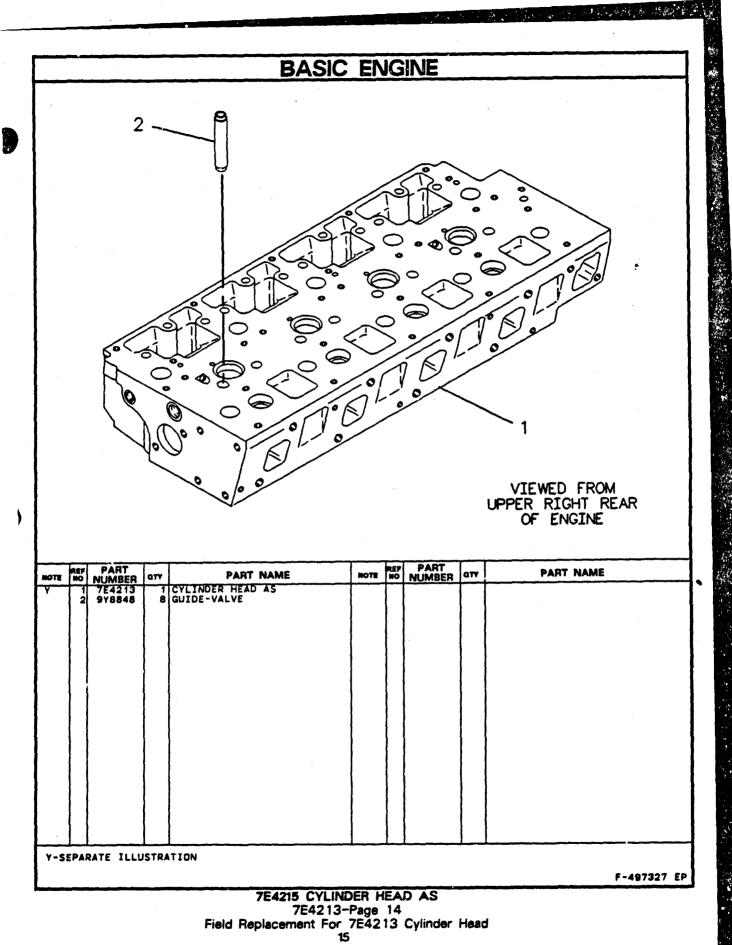
M-METRIC PART Y-SEPARATE ILLUSTRATION

A-497318 EP

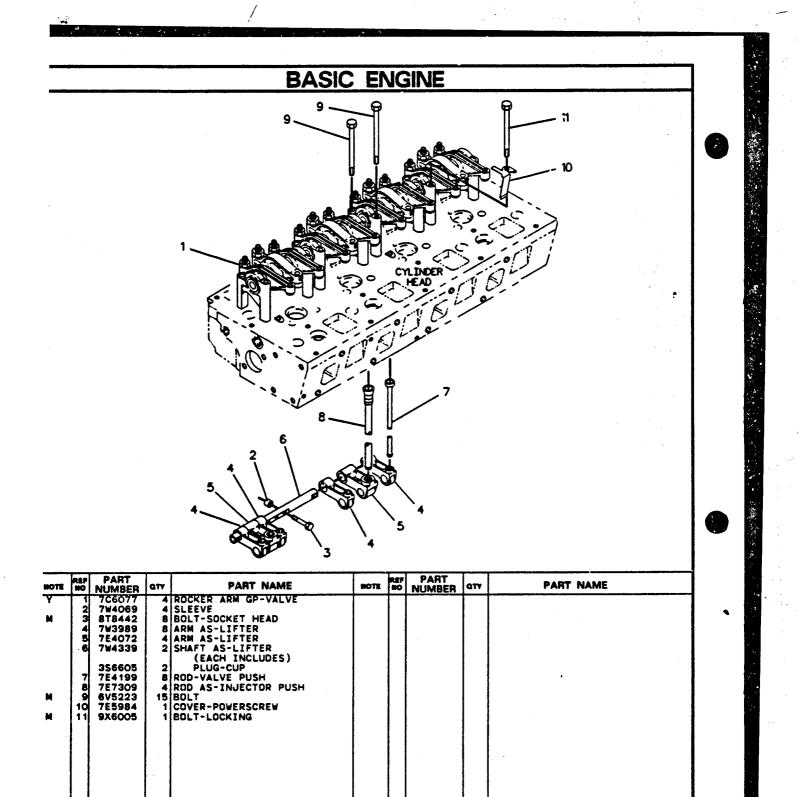
7E4211 CYLINDER HEAD GP 7E4212-Page 13







···- . ·

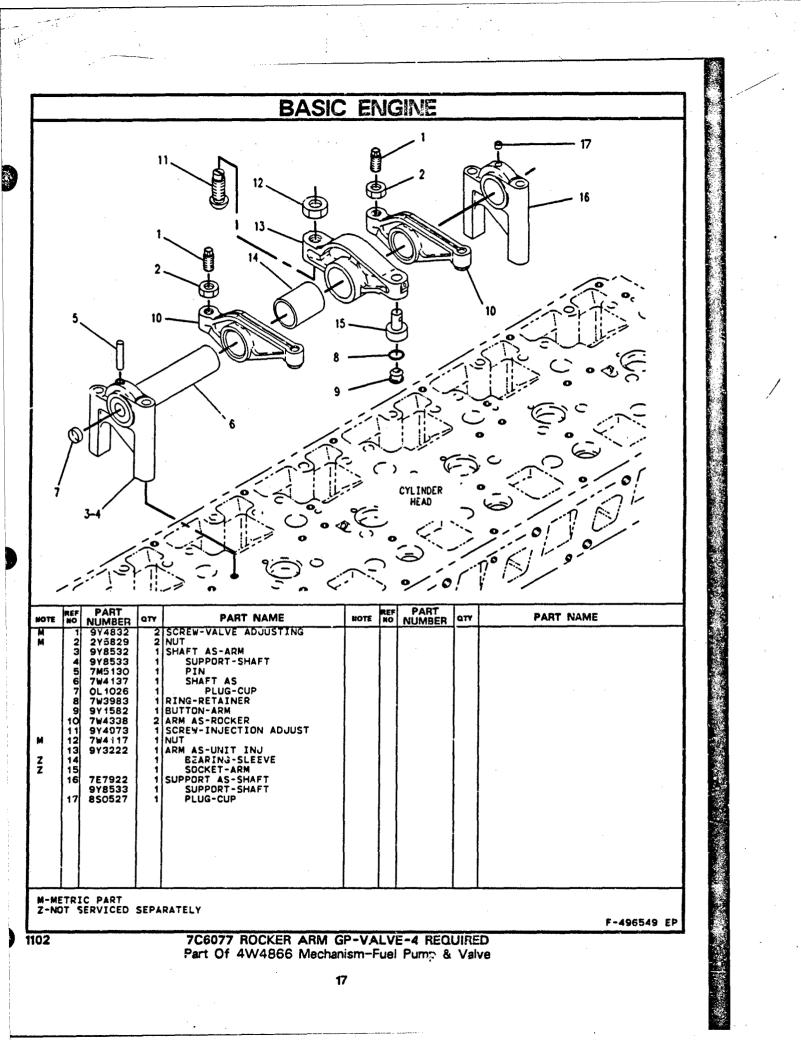


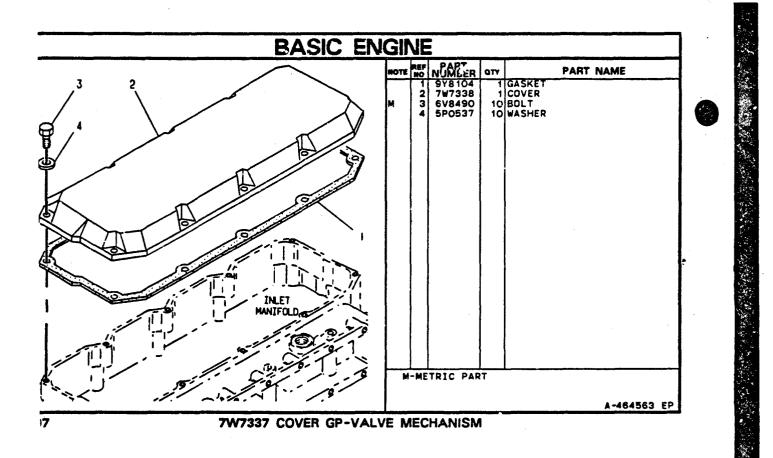
M-METRIC PART Y-SEPARATE ILLUSTRATION



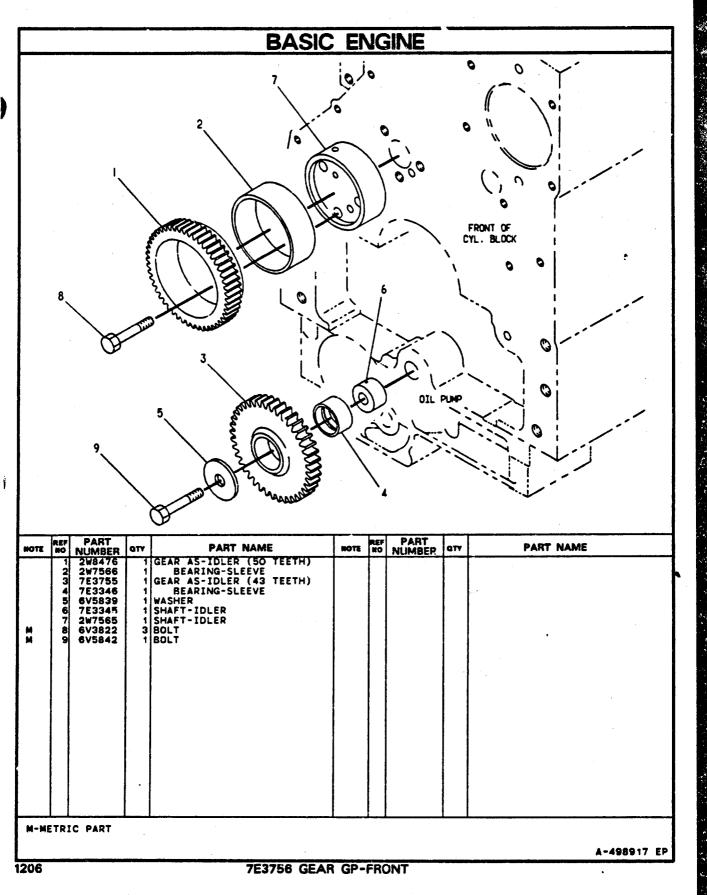
4W4866 MECHANISM GP-FUEL PUMP & VALVE 7C6077-Page 17

F-490035 EP

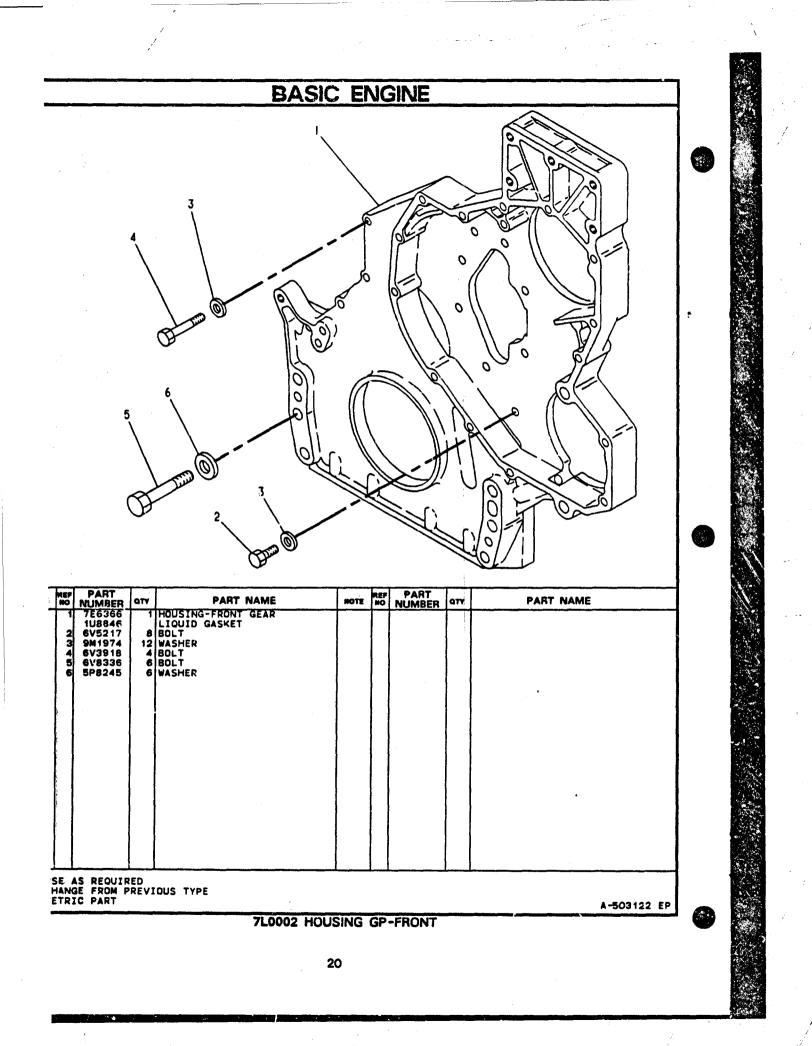


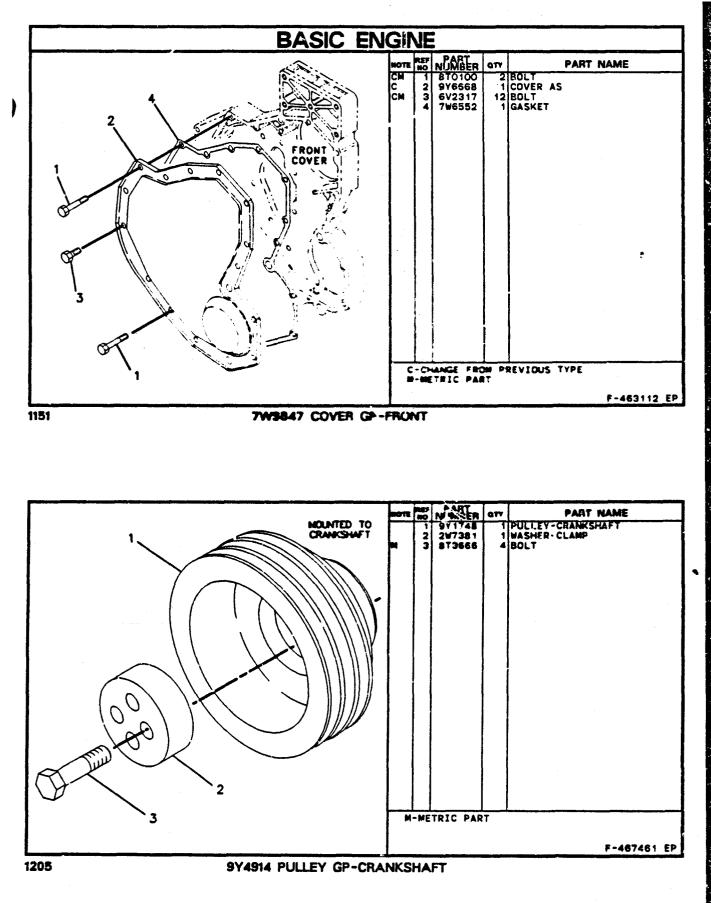


-



Ċ,



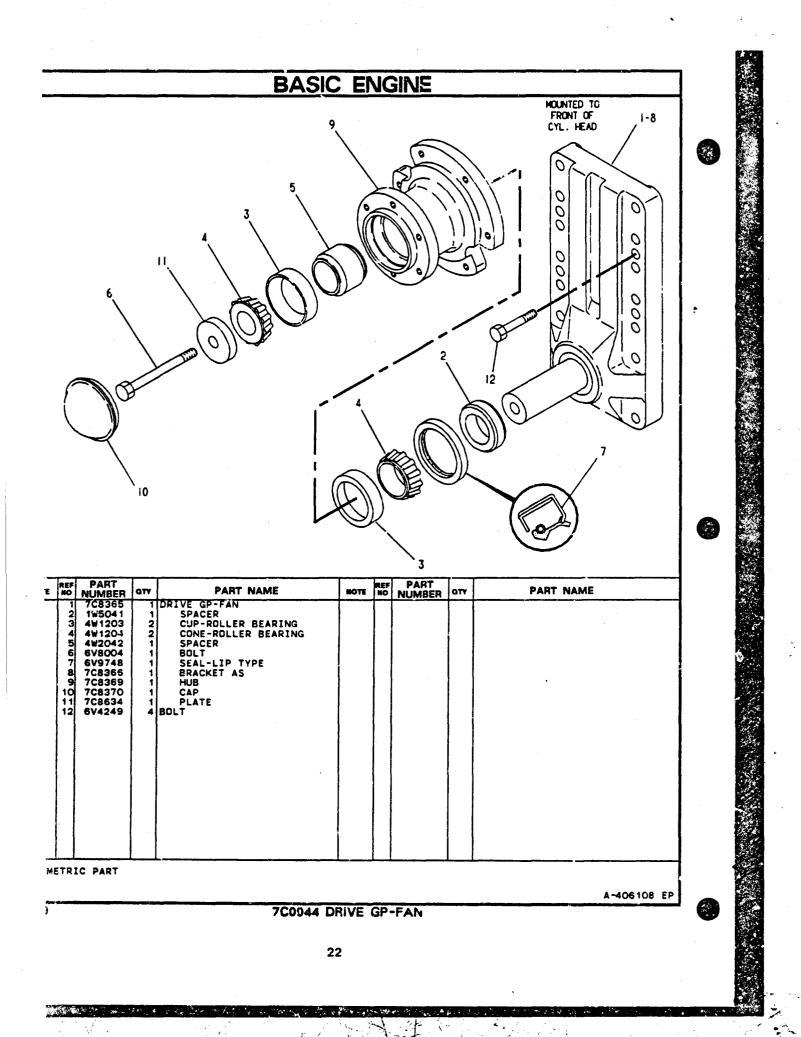


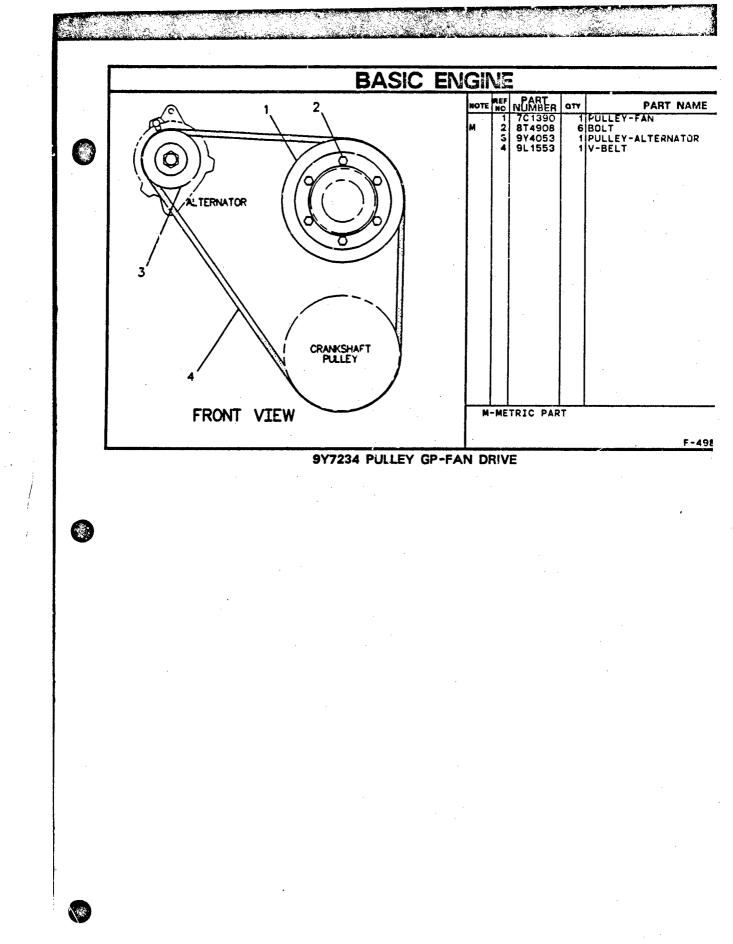
.....

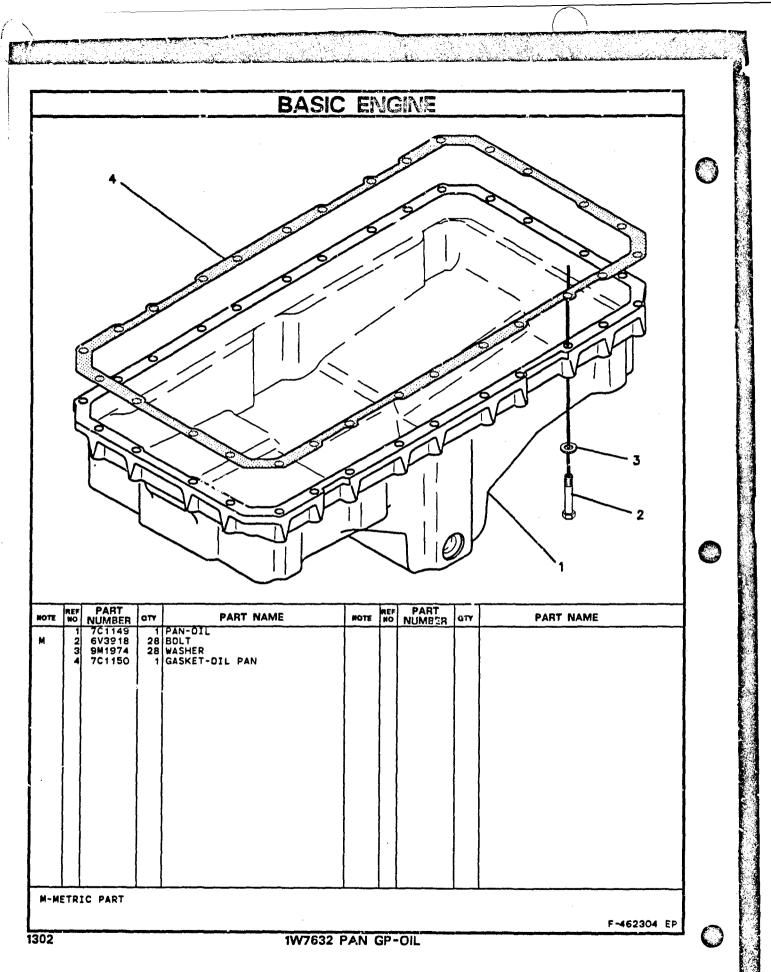
21

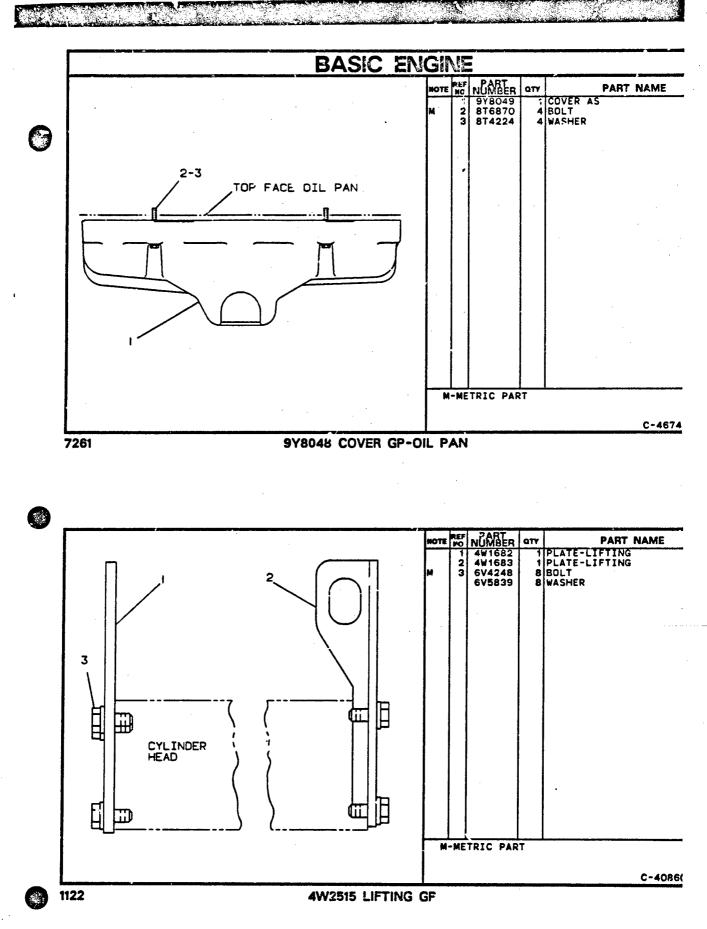
15

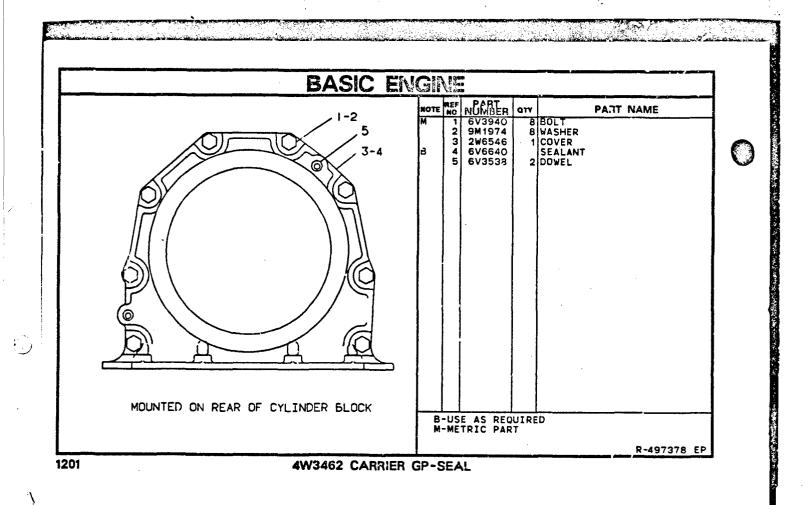
ه باره ک



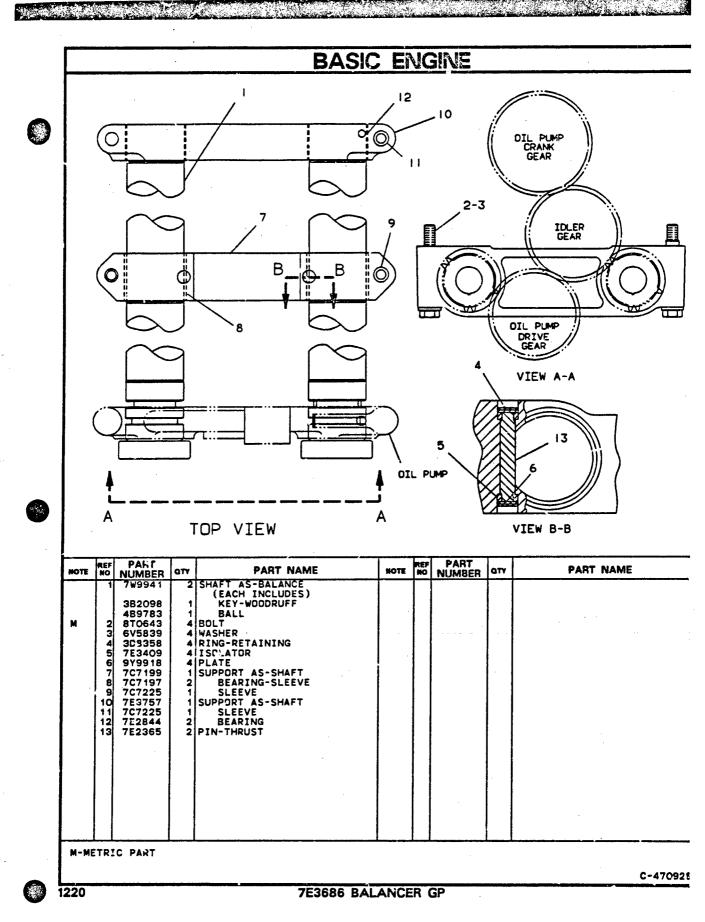


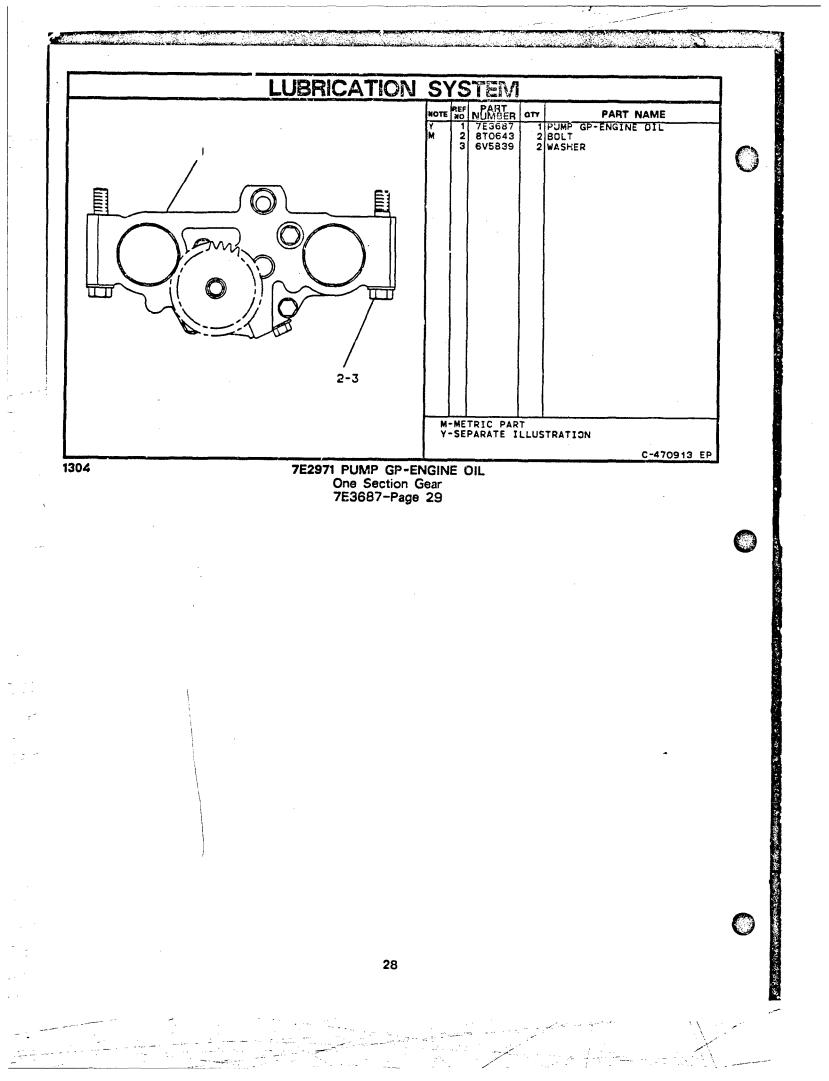


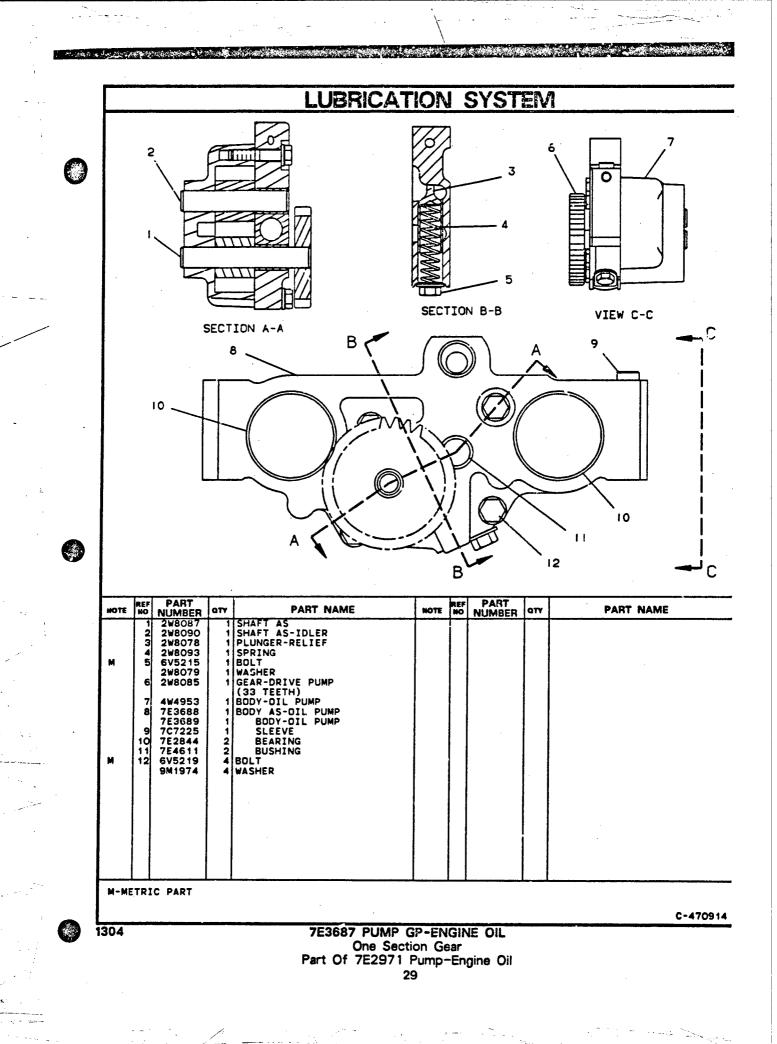




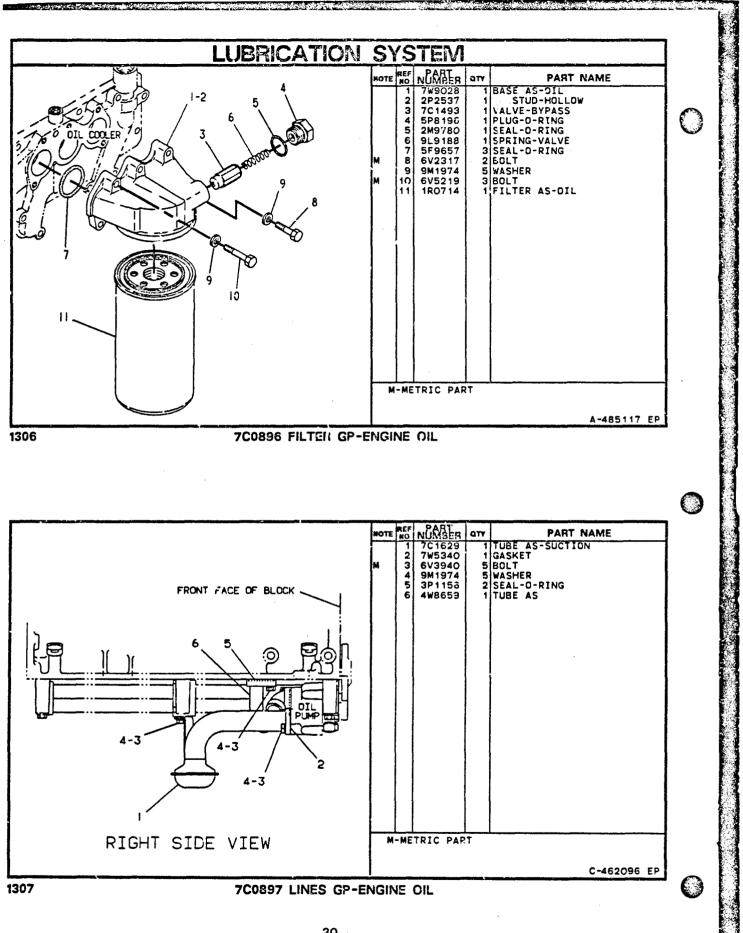
「「「「「「「」」」」



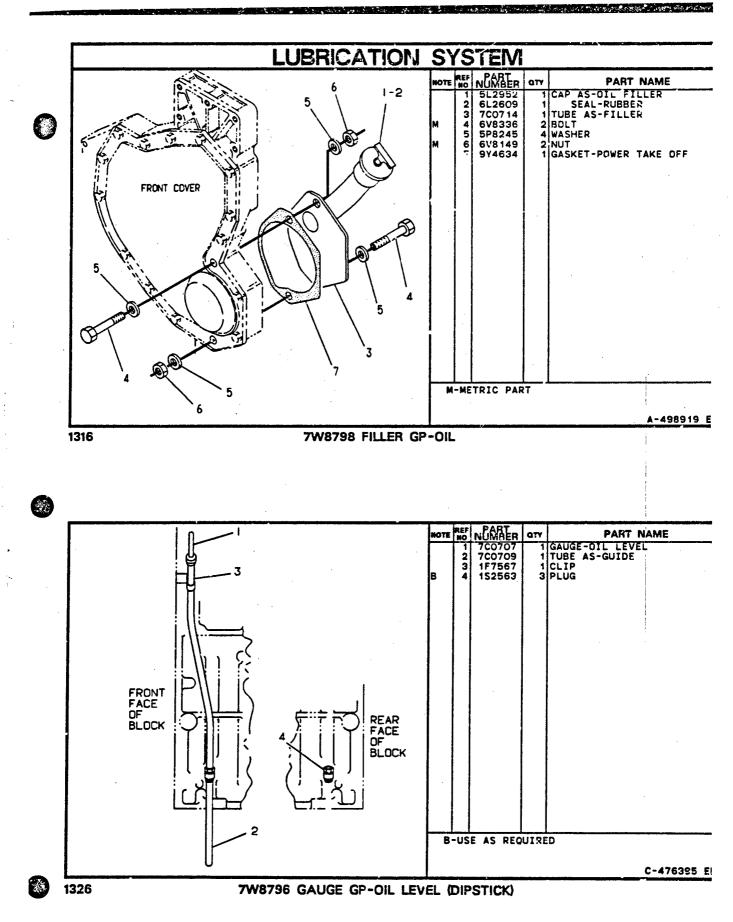


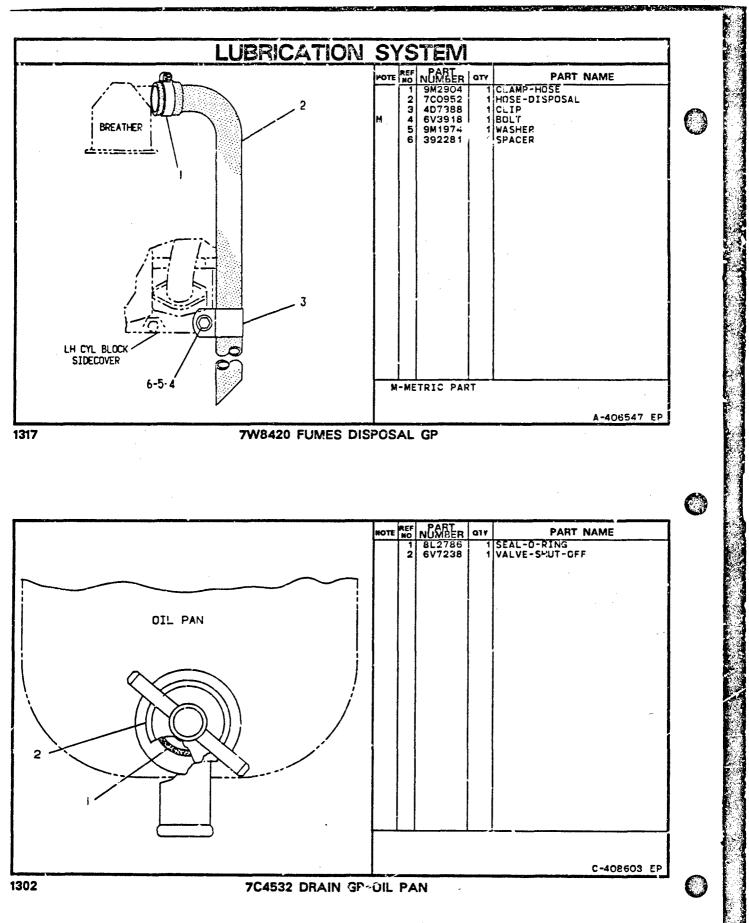


87 A 3

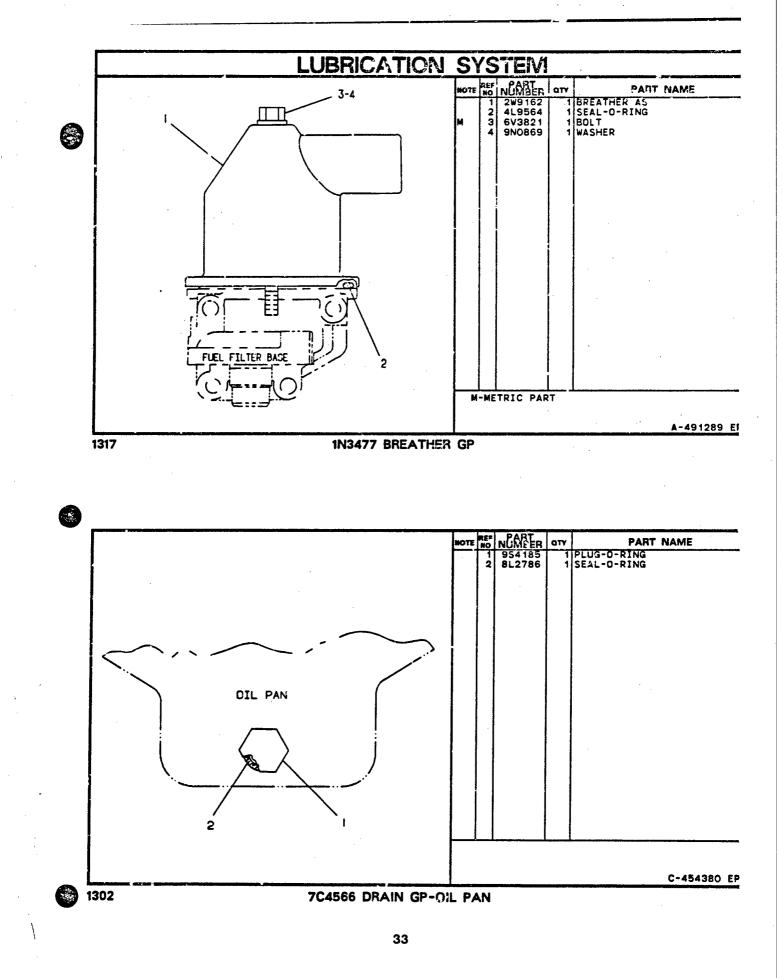


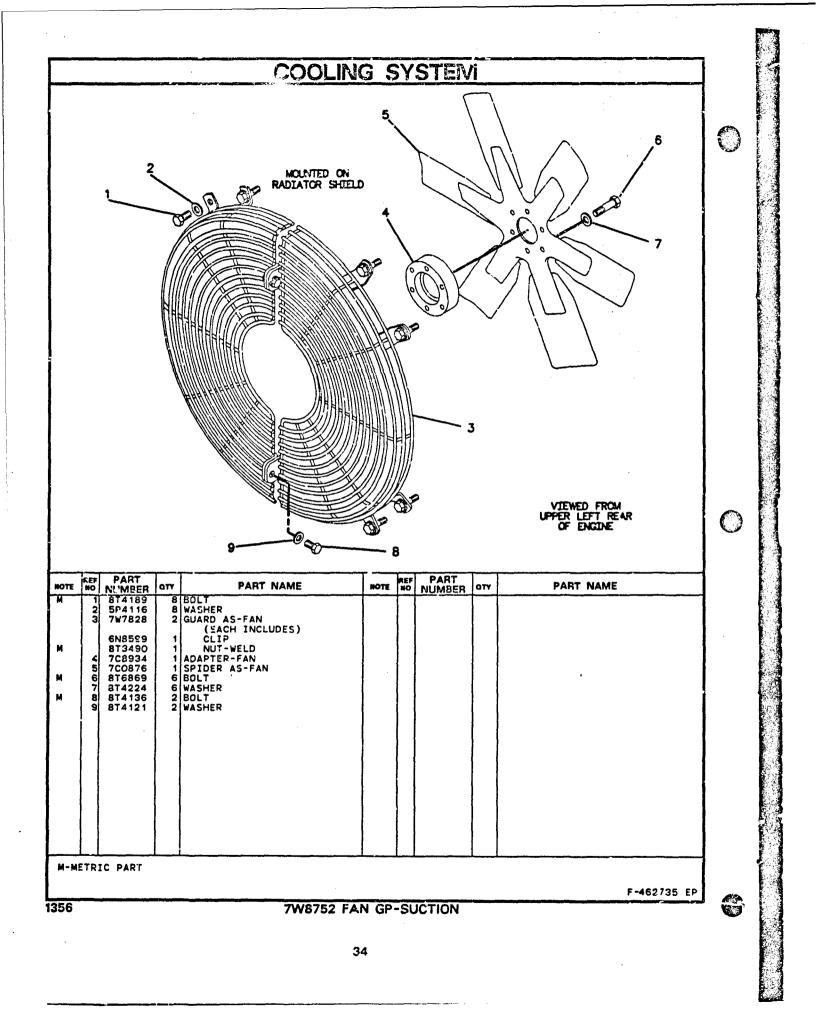
.

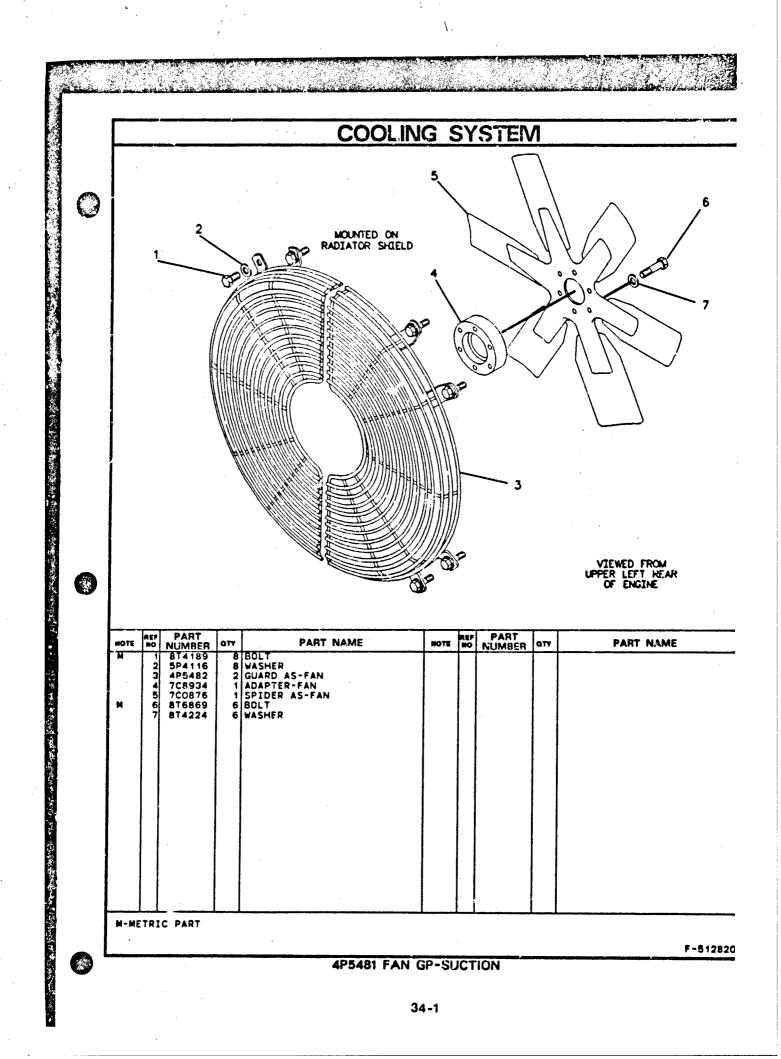


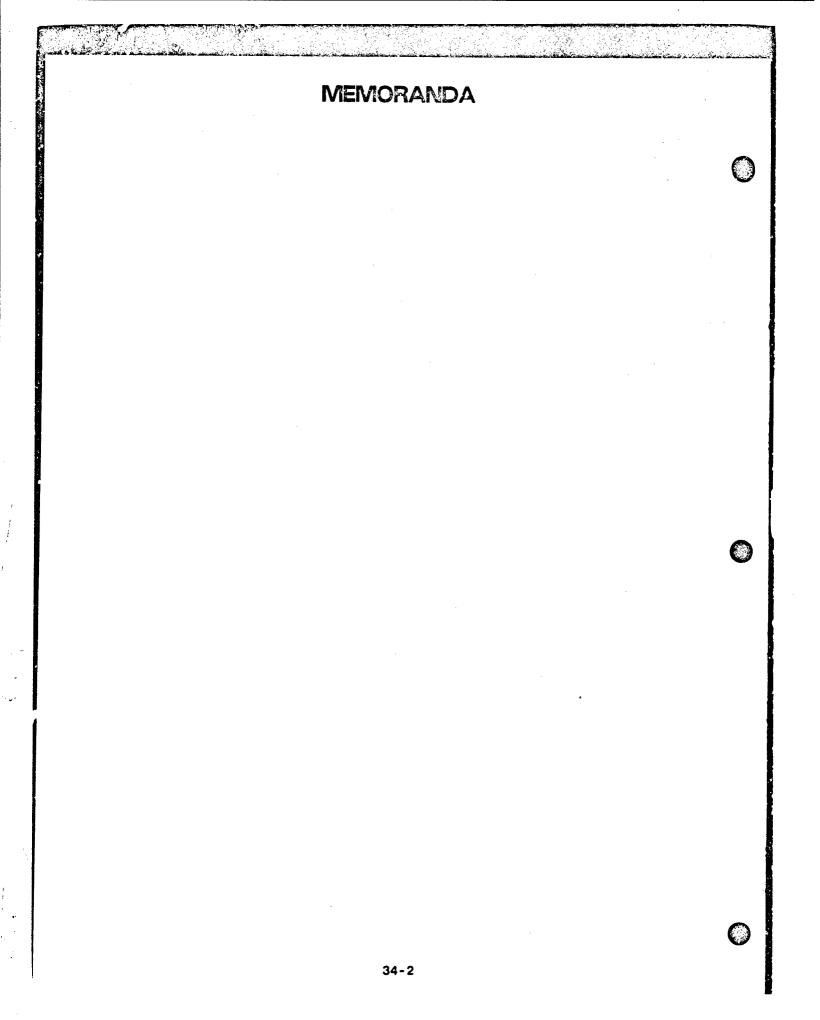


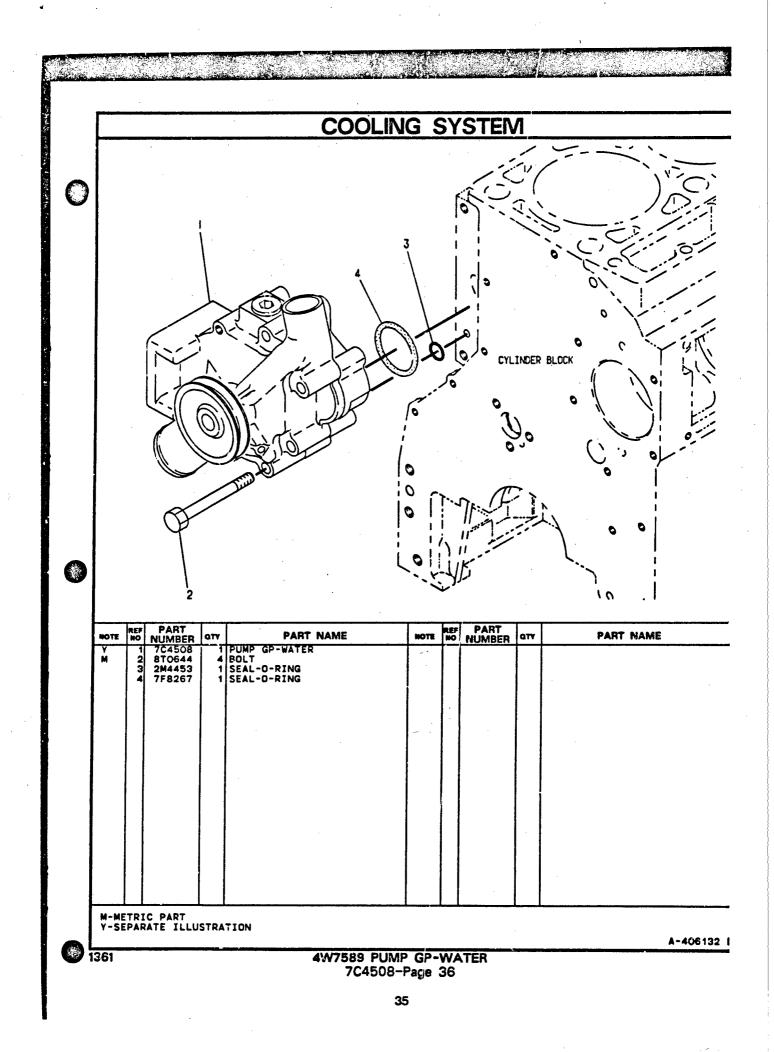
ς.

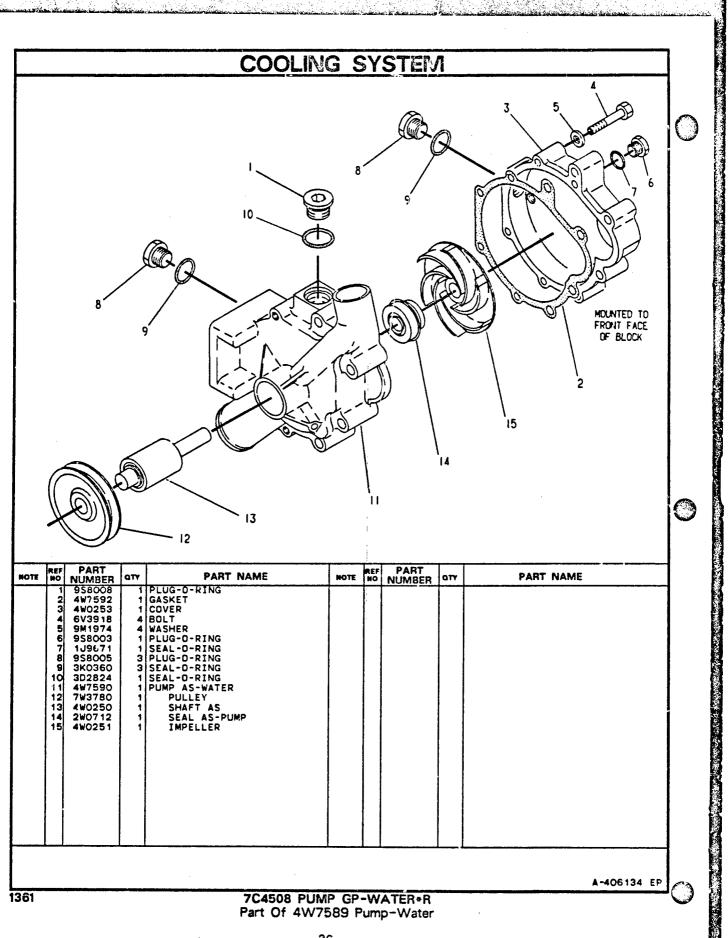


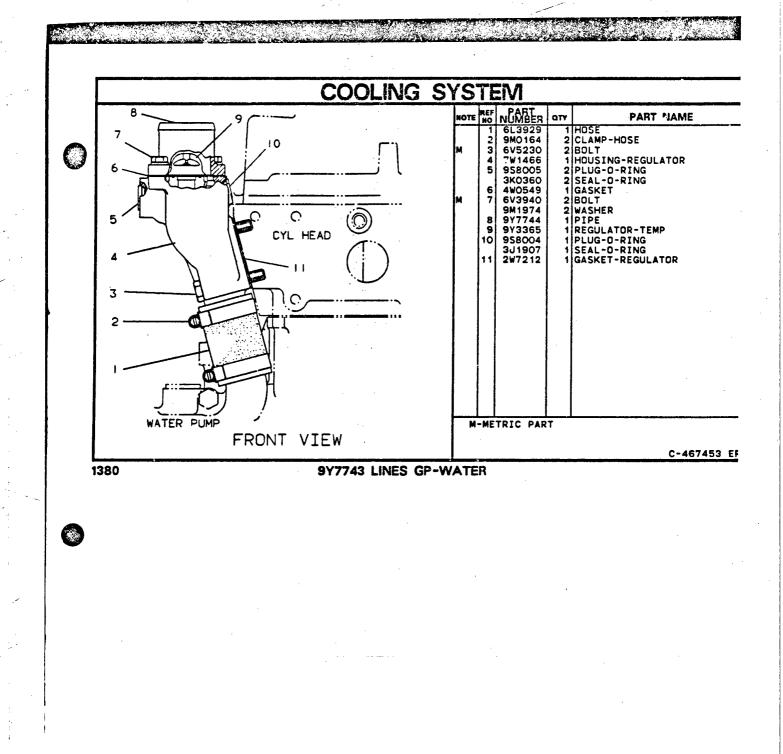


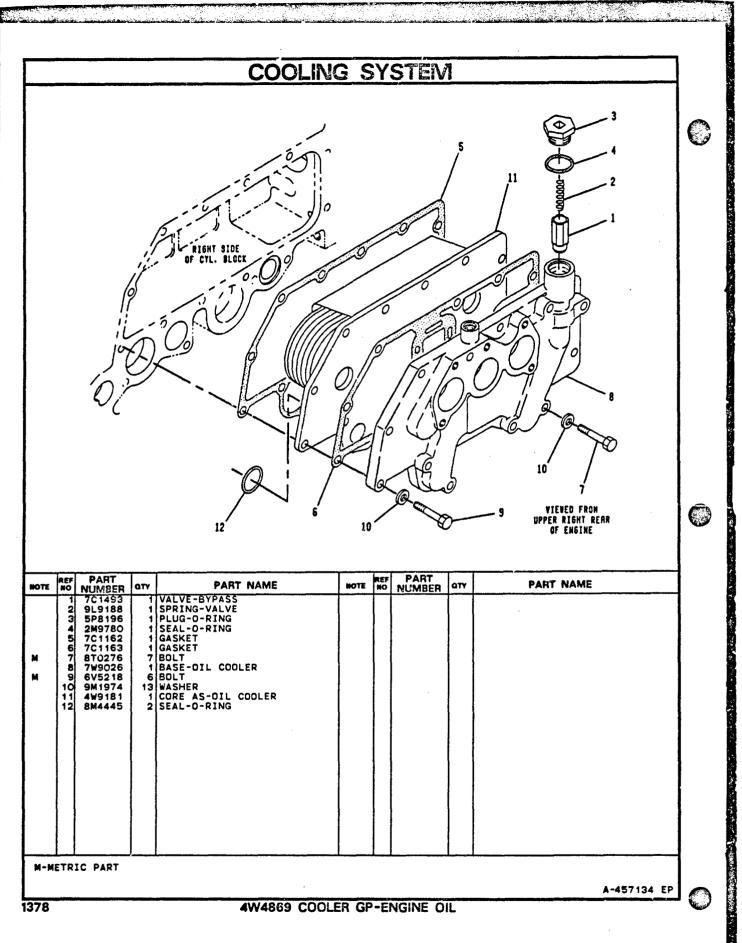




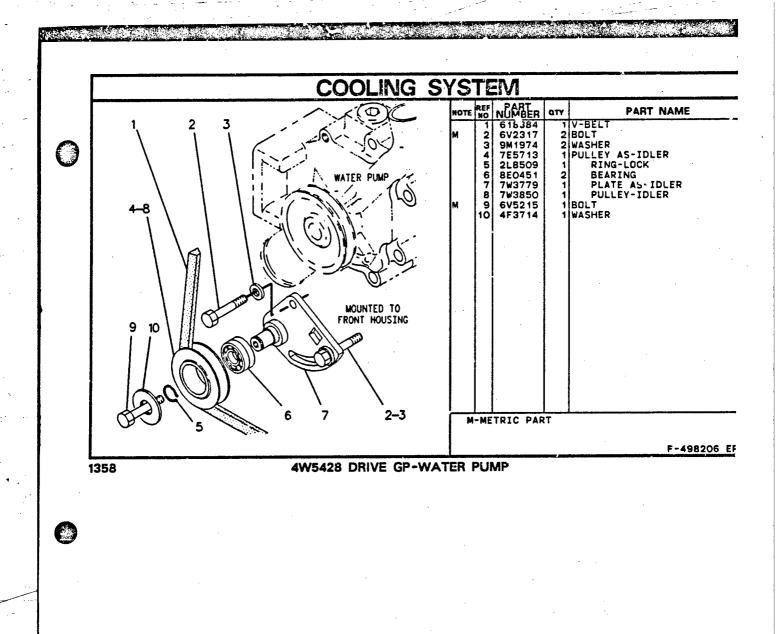


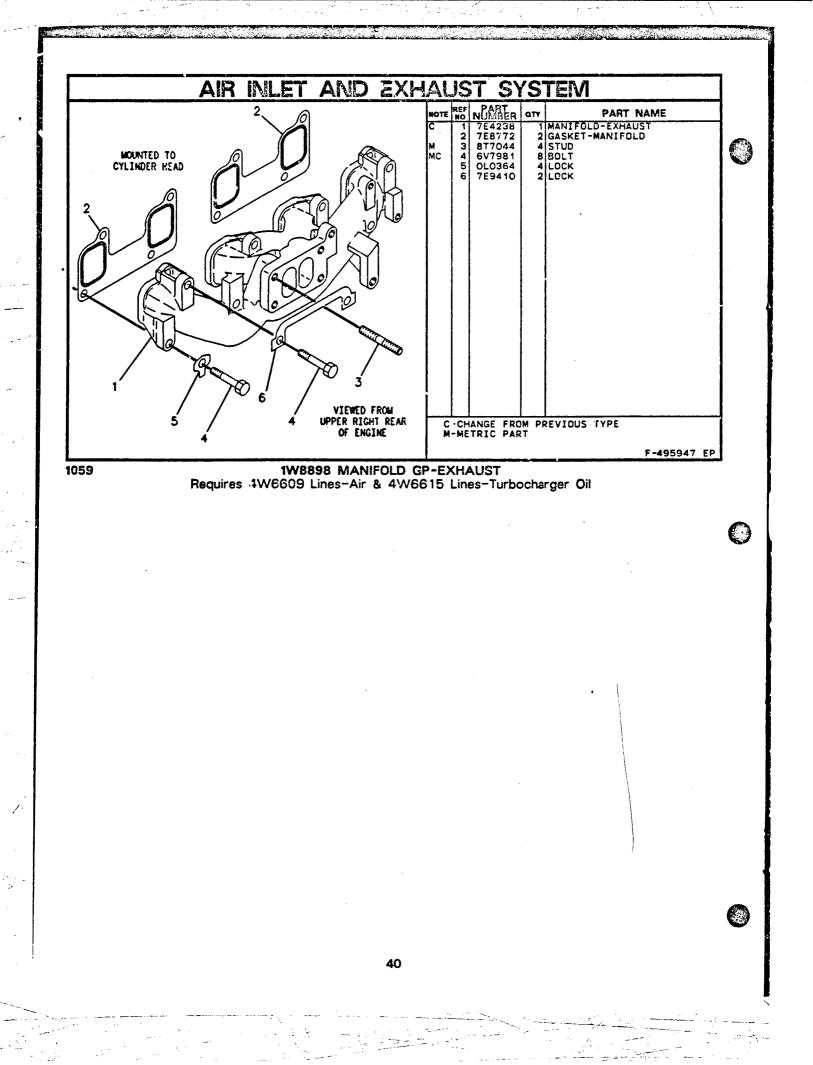


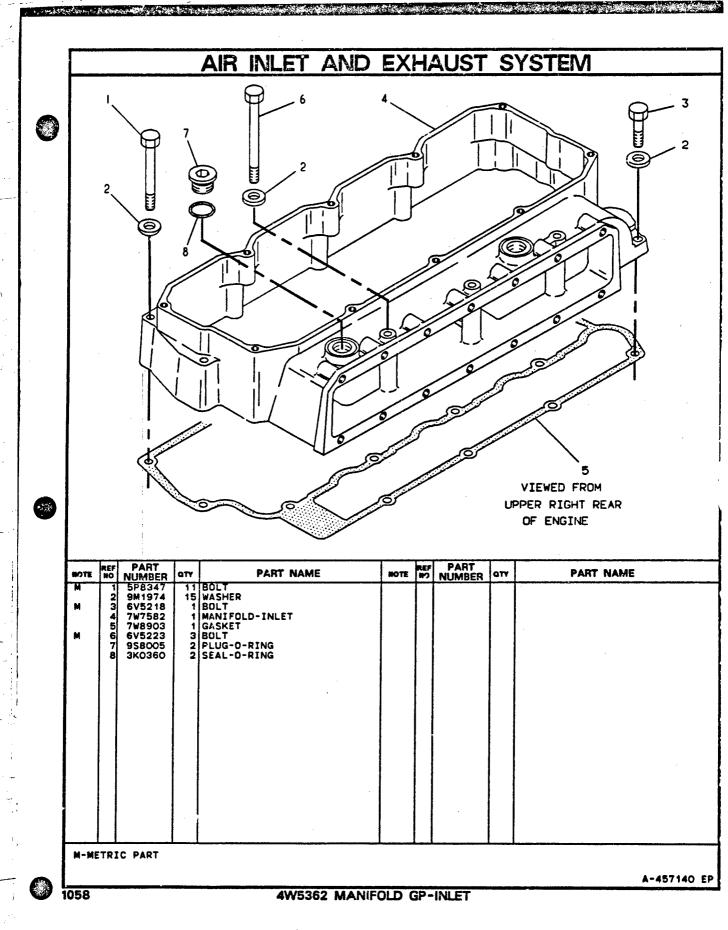




•



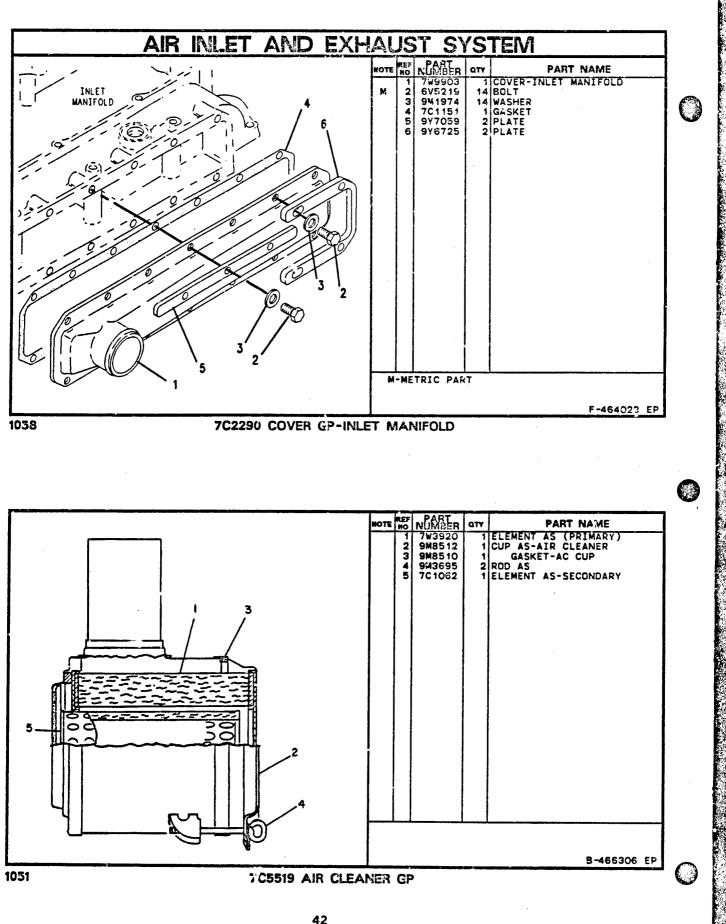




Ξ.

 z^{+}

:



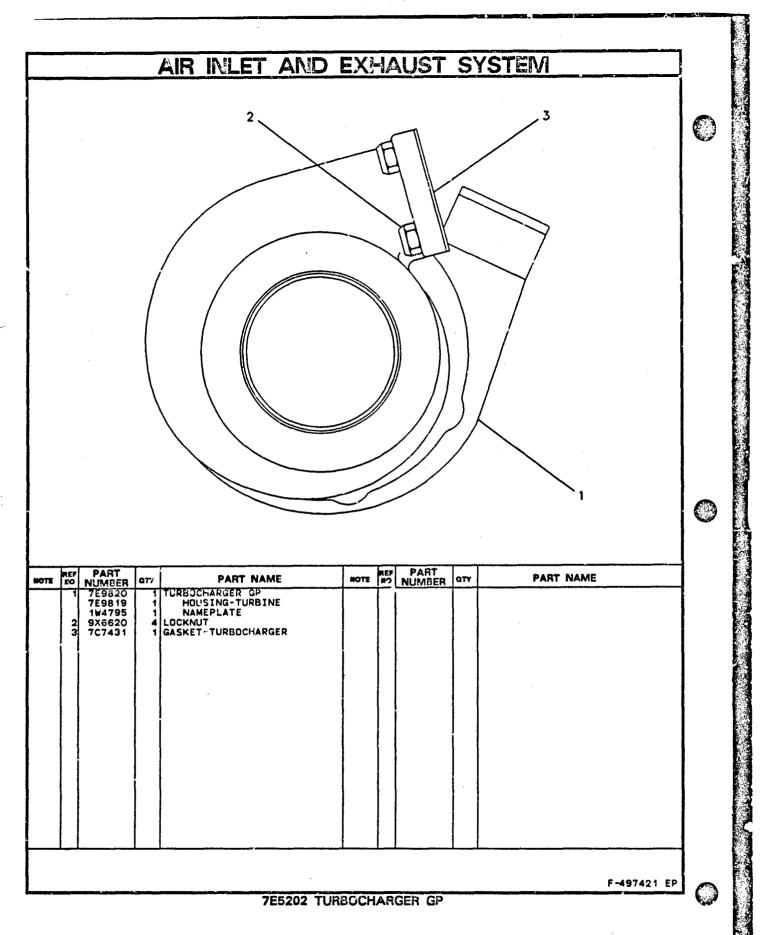
;

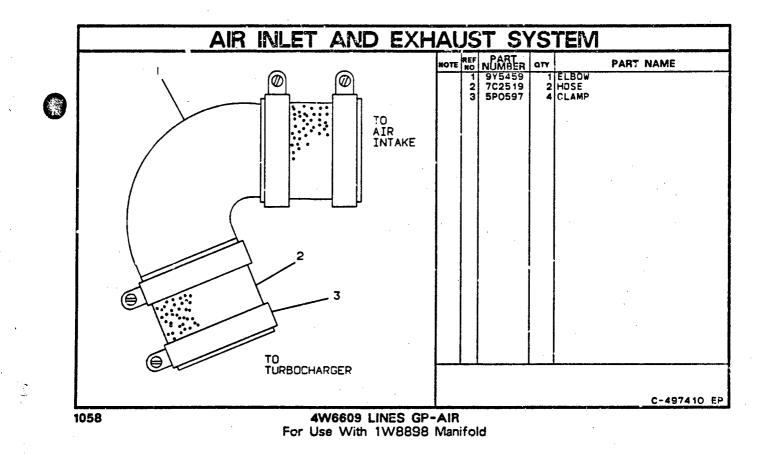
Second March 19

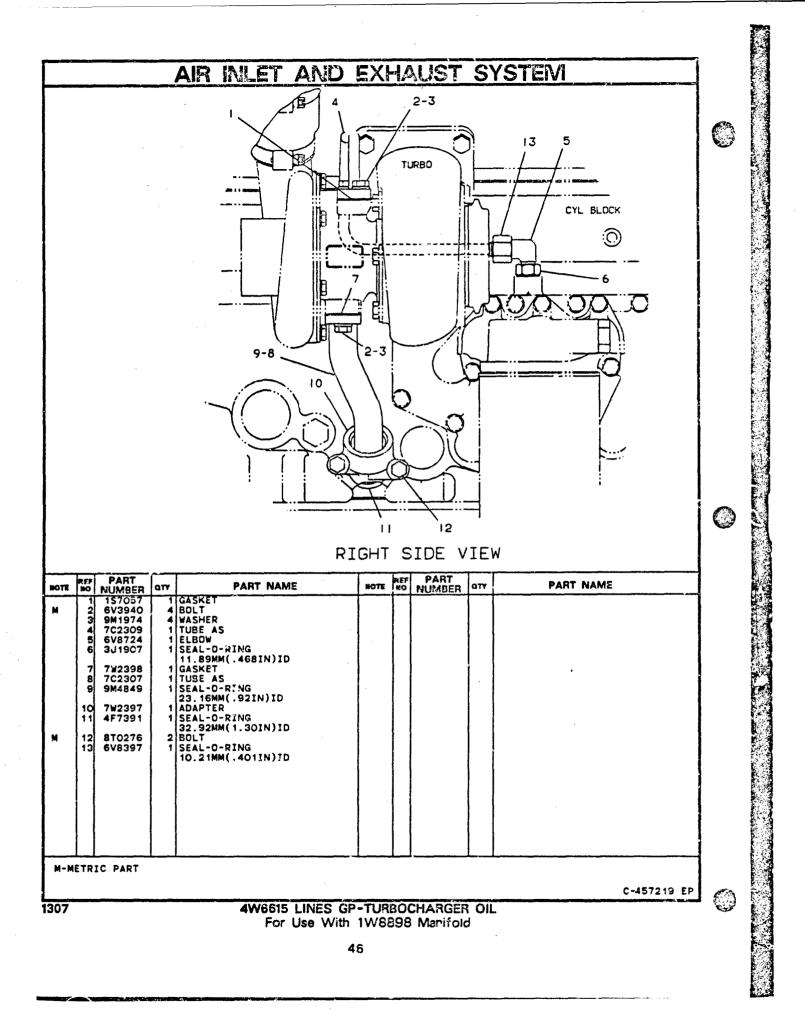
Γ

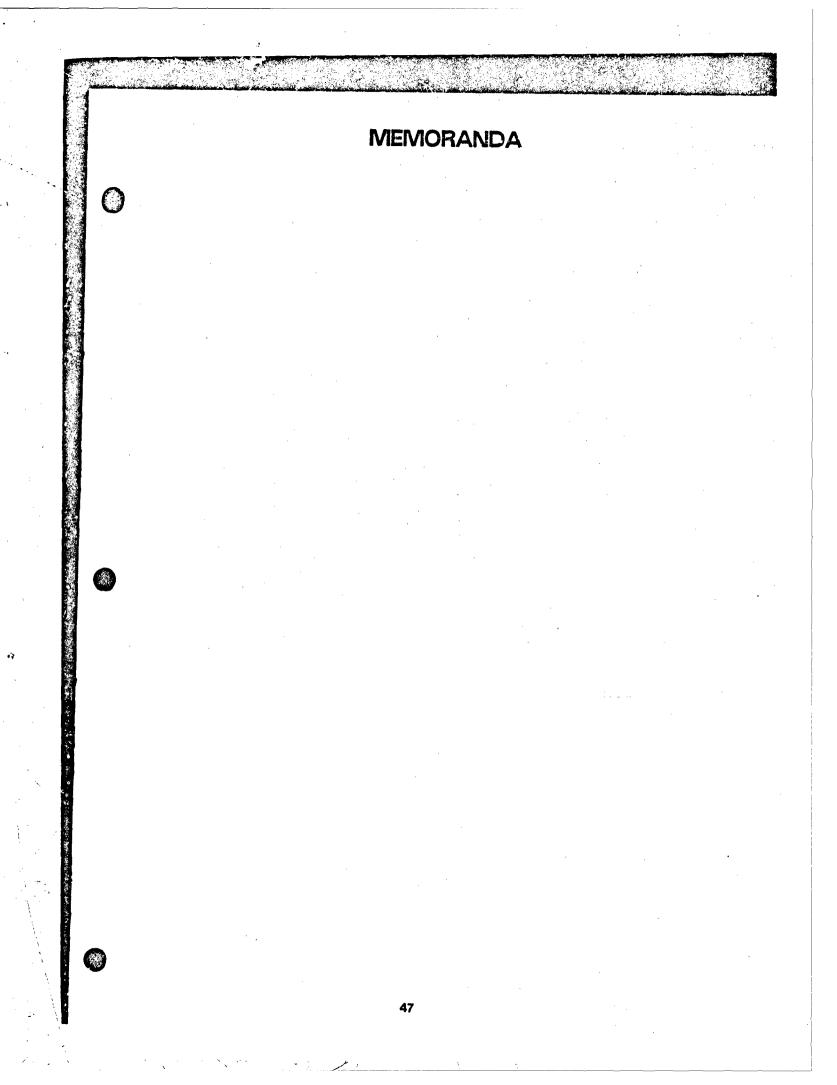
MEMORANDUM

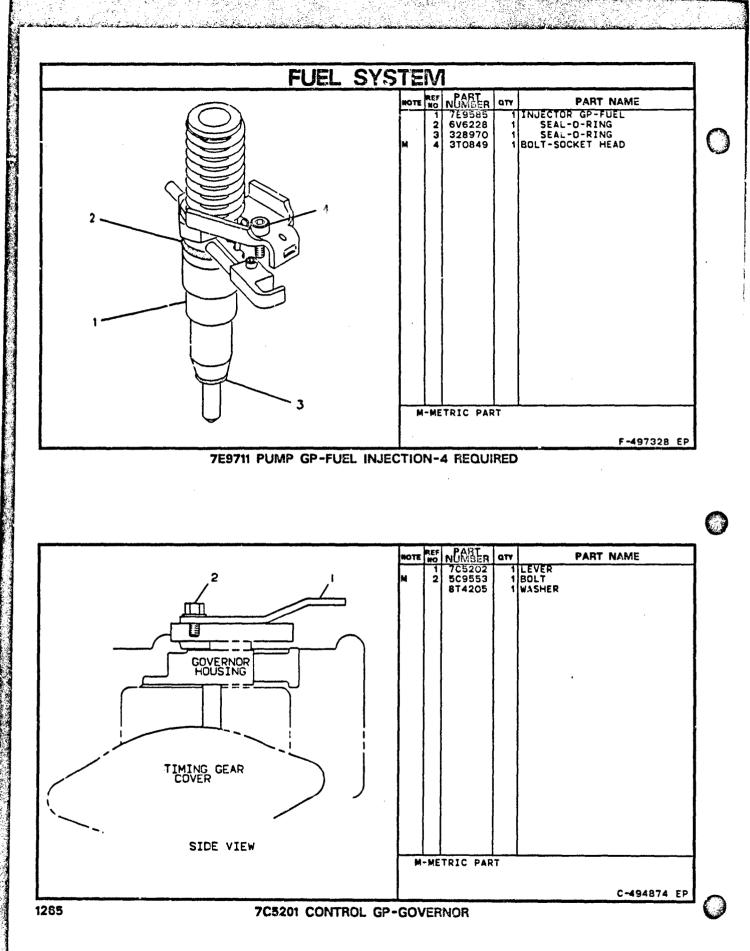
MEMORANDUM









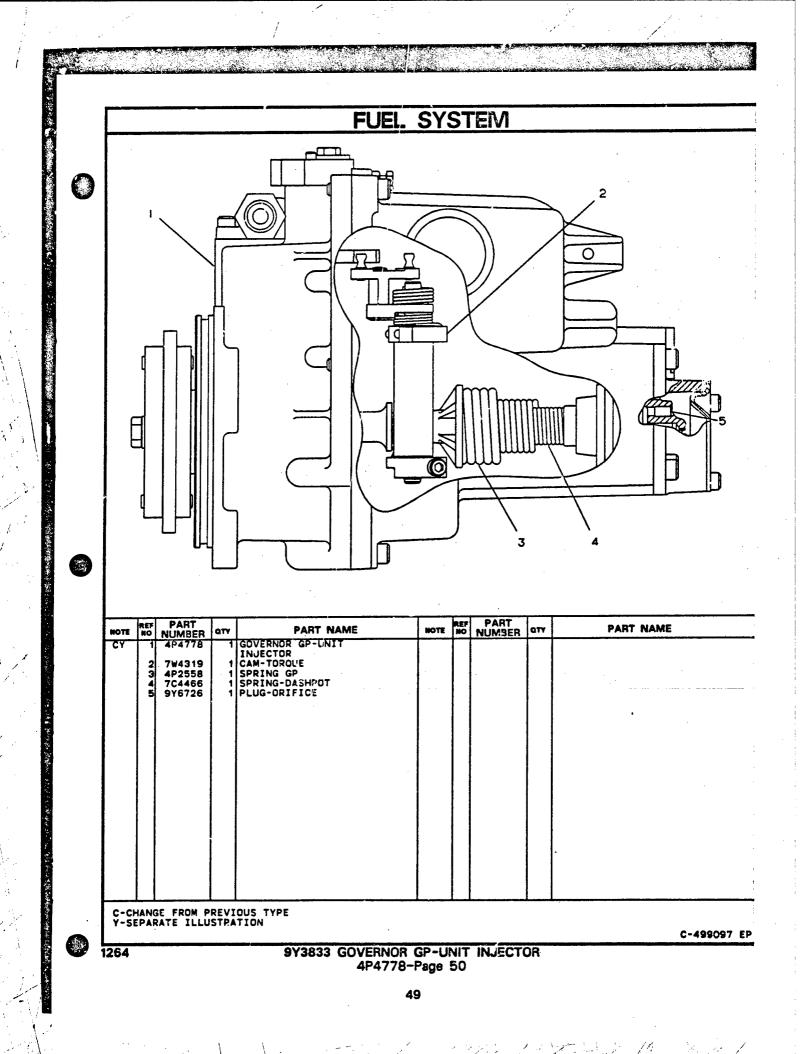


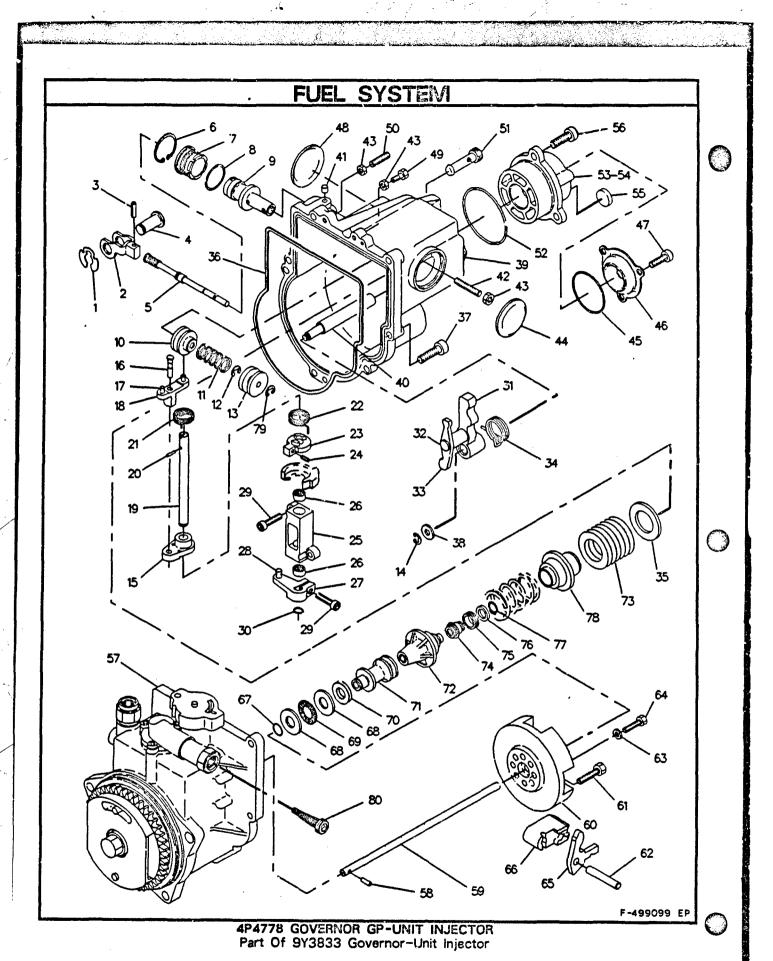
J

1

· · ·

i .

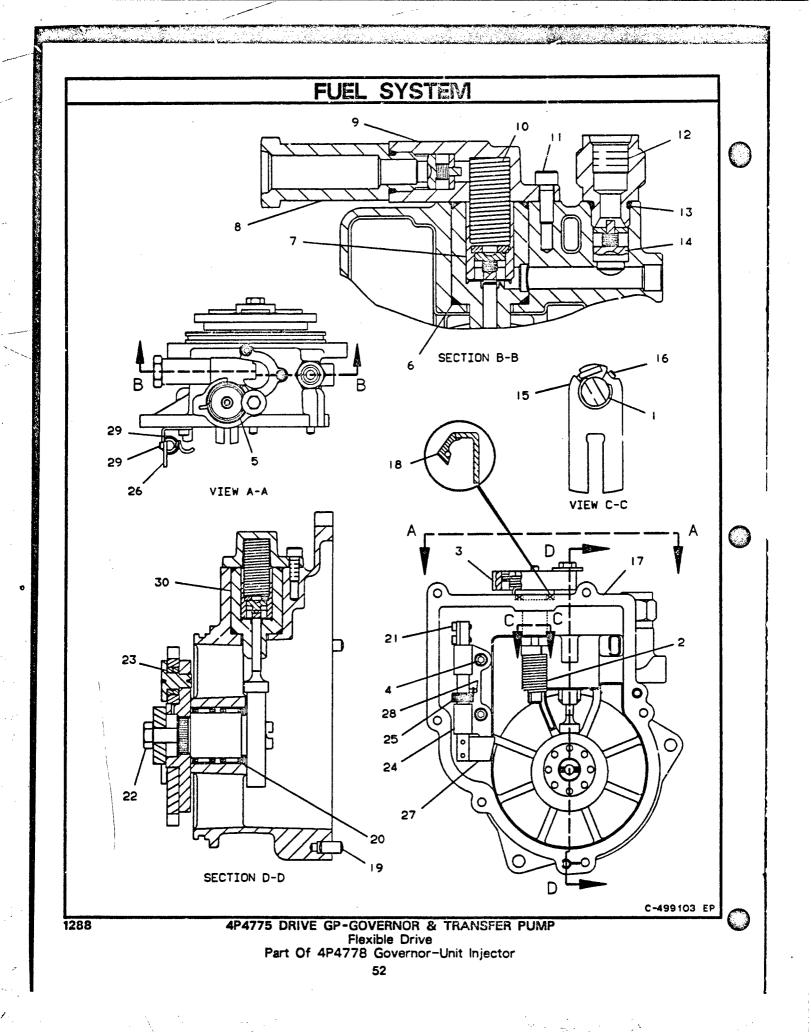


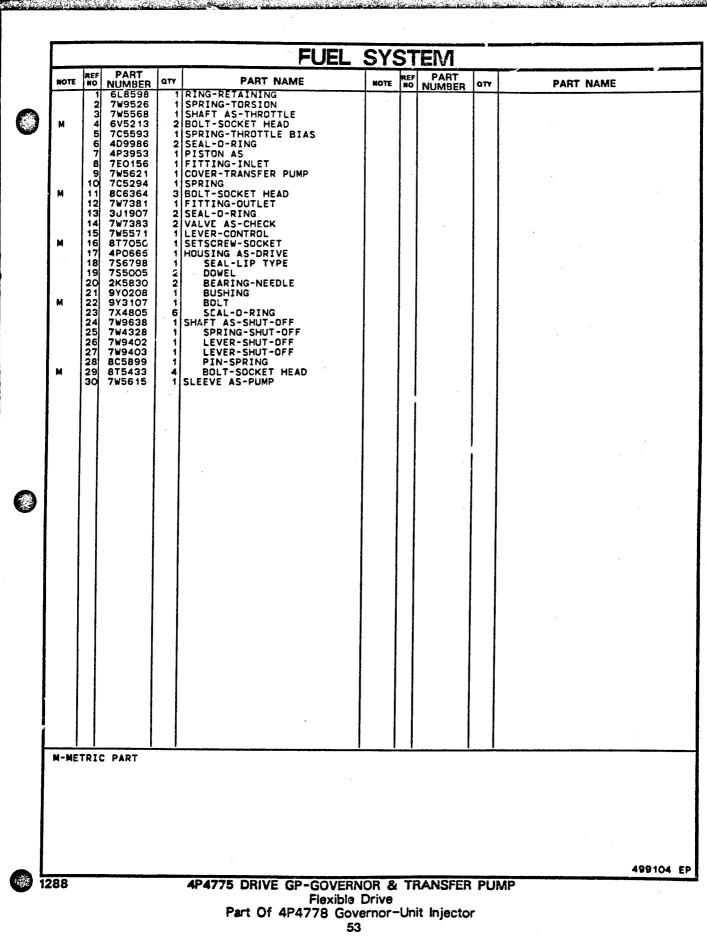


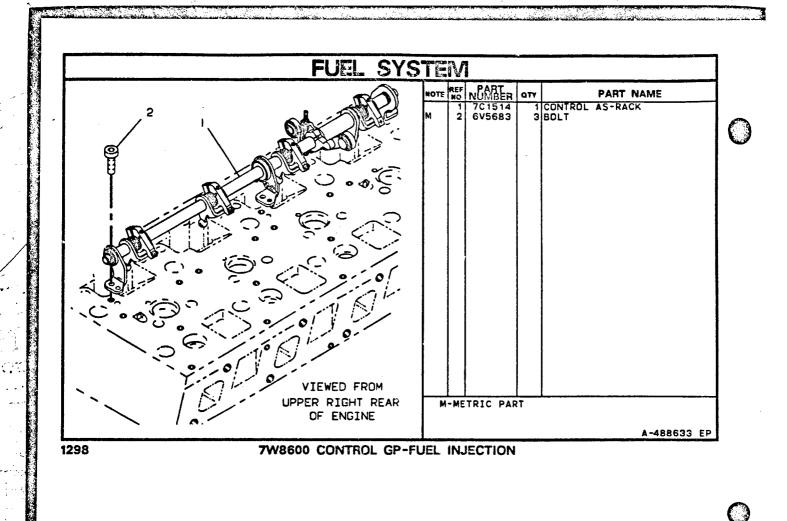


1 -

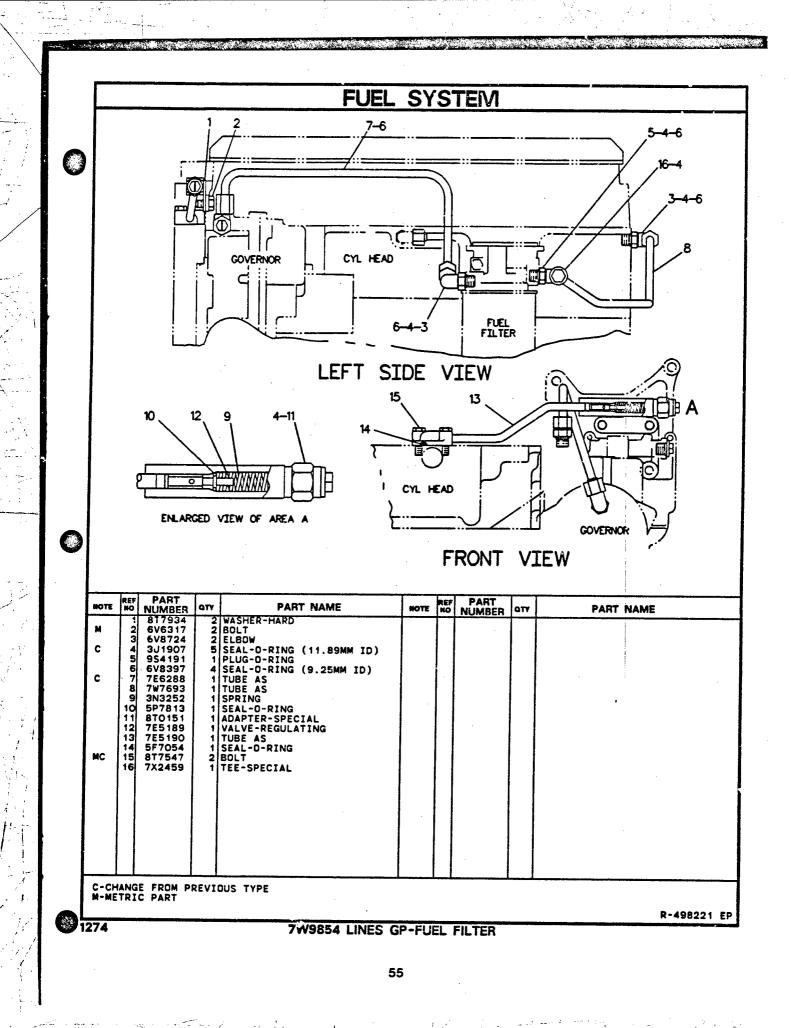
Υ.,

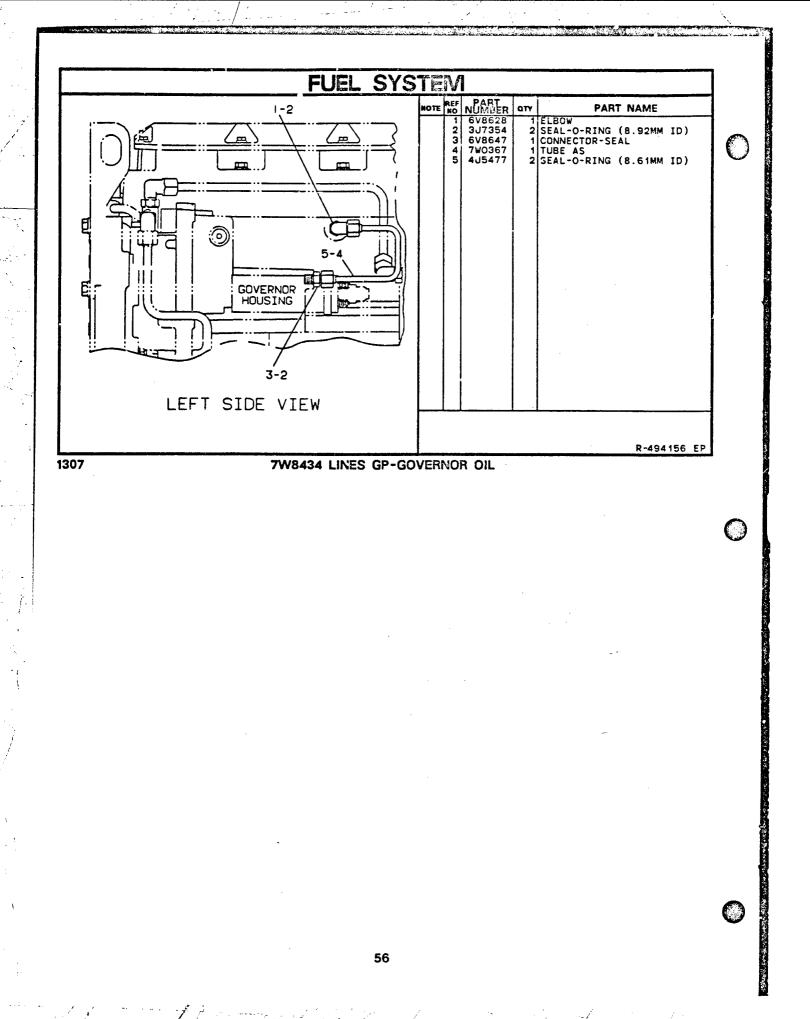


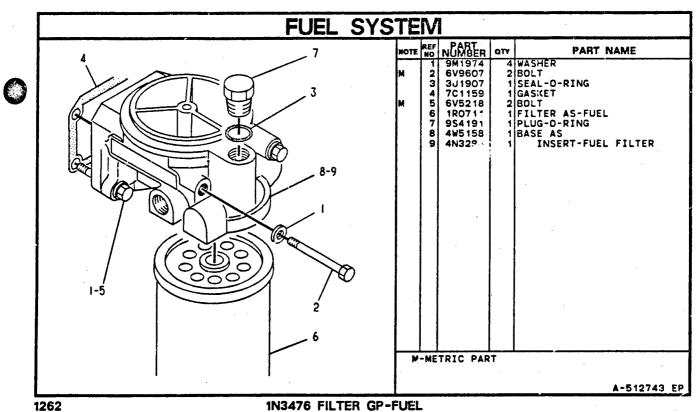


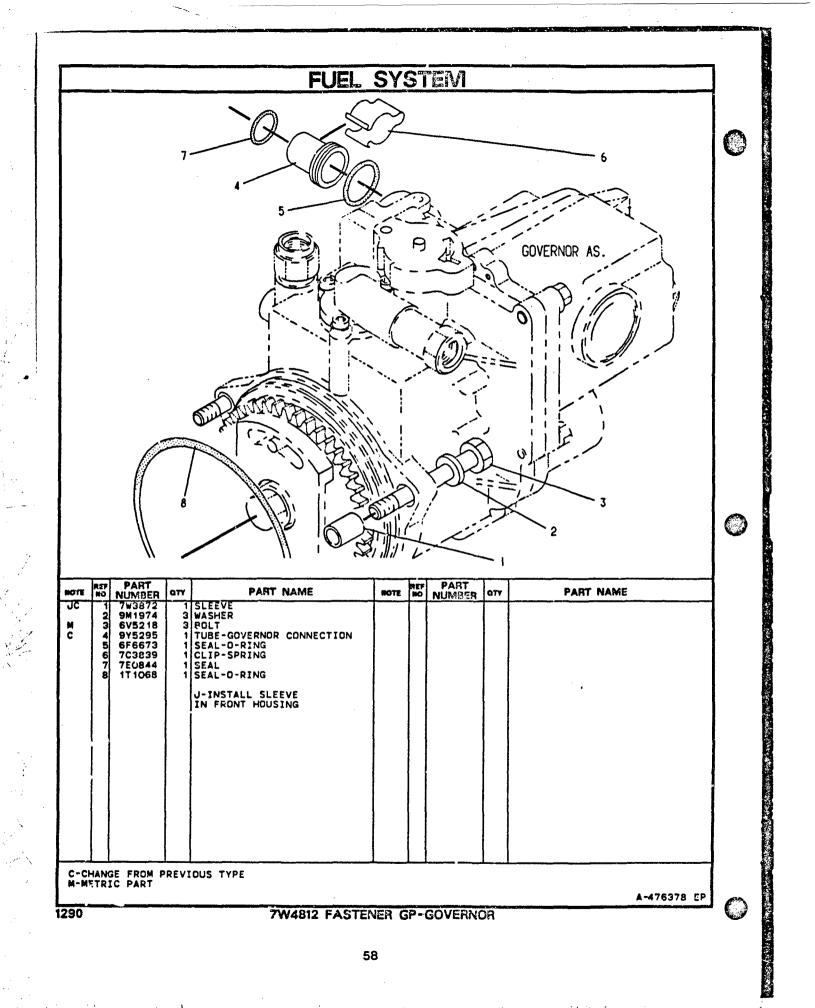


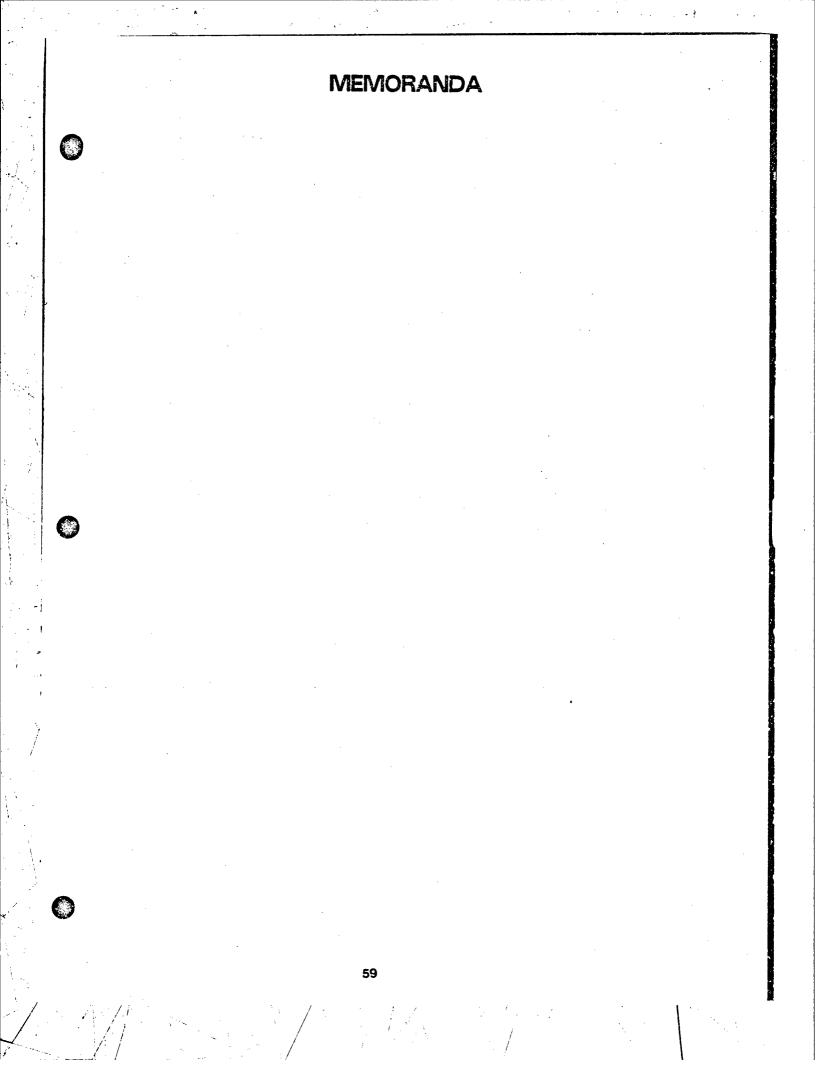
SEBN8601

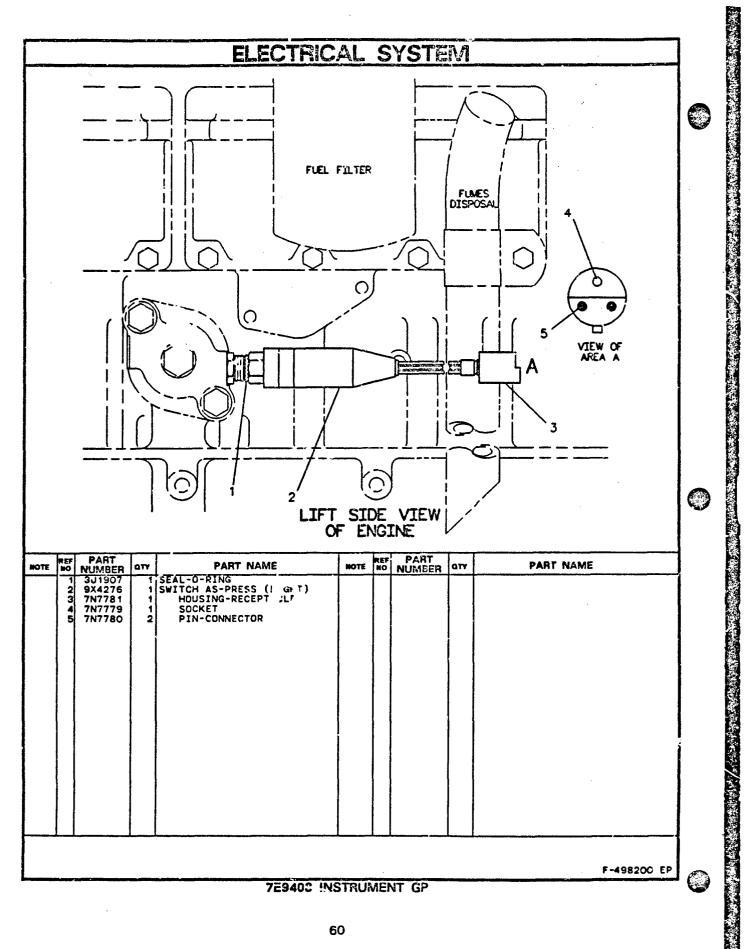




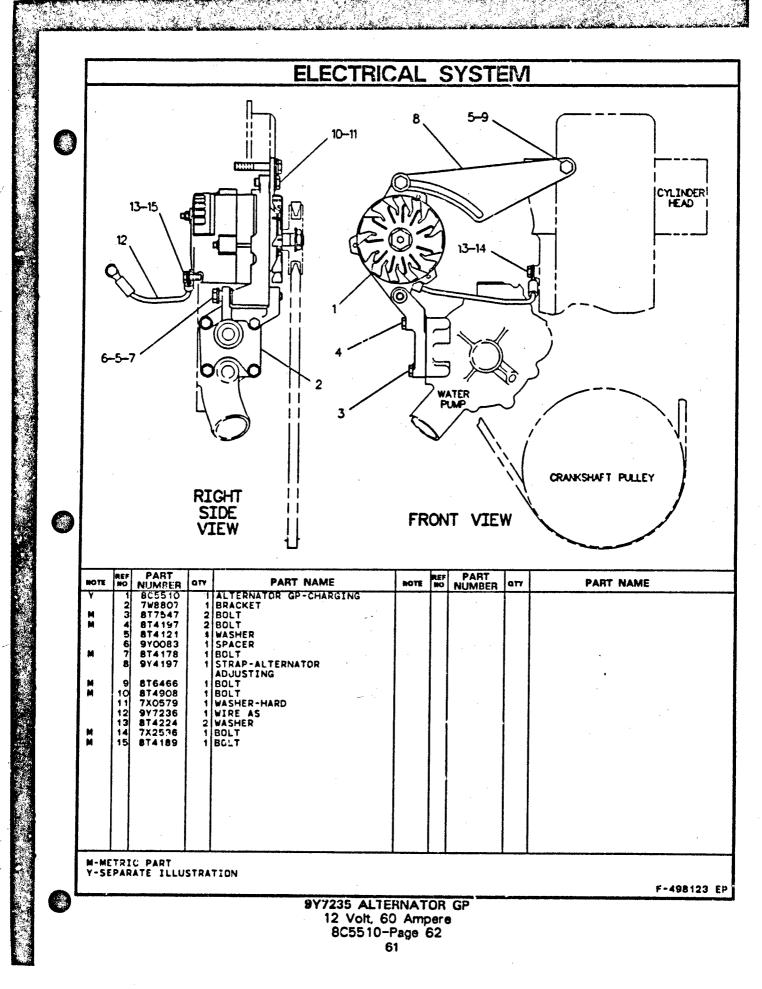




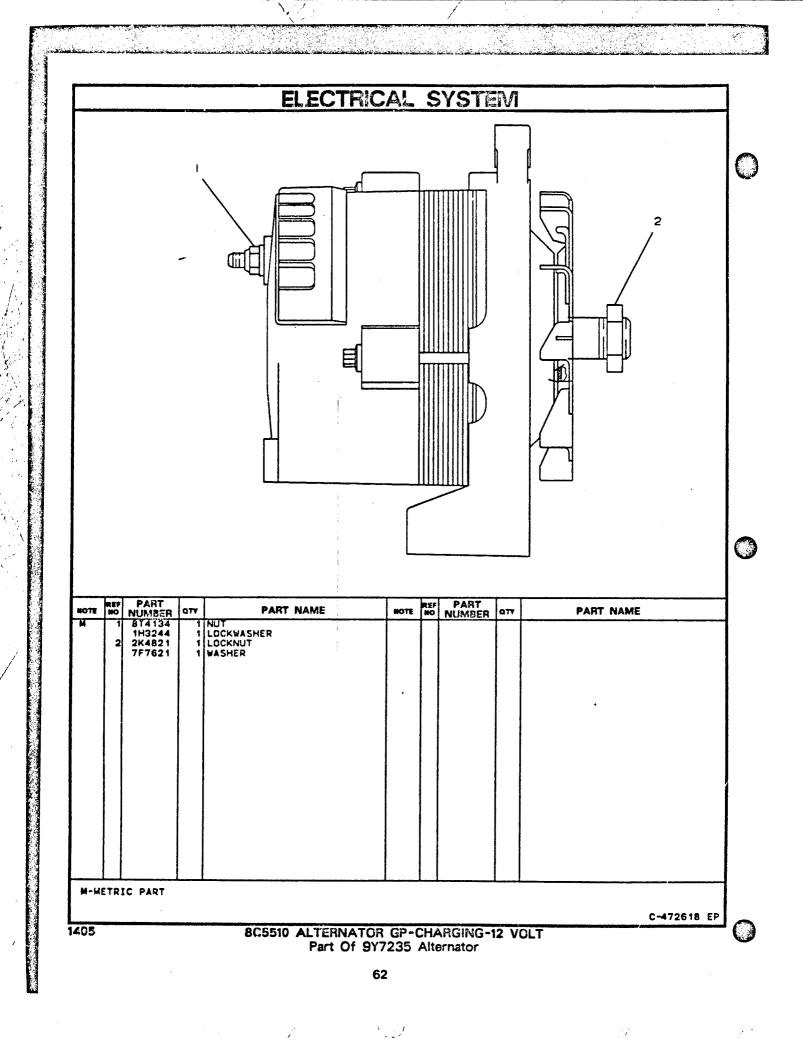


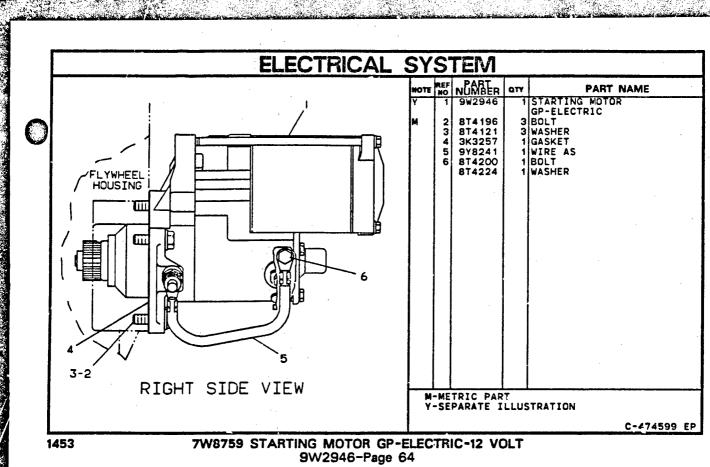


 \vec{r} .

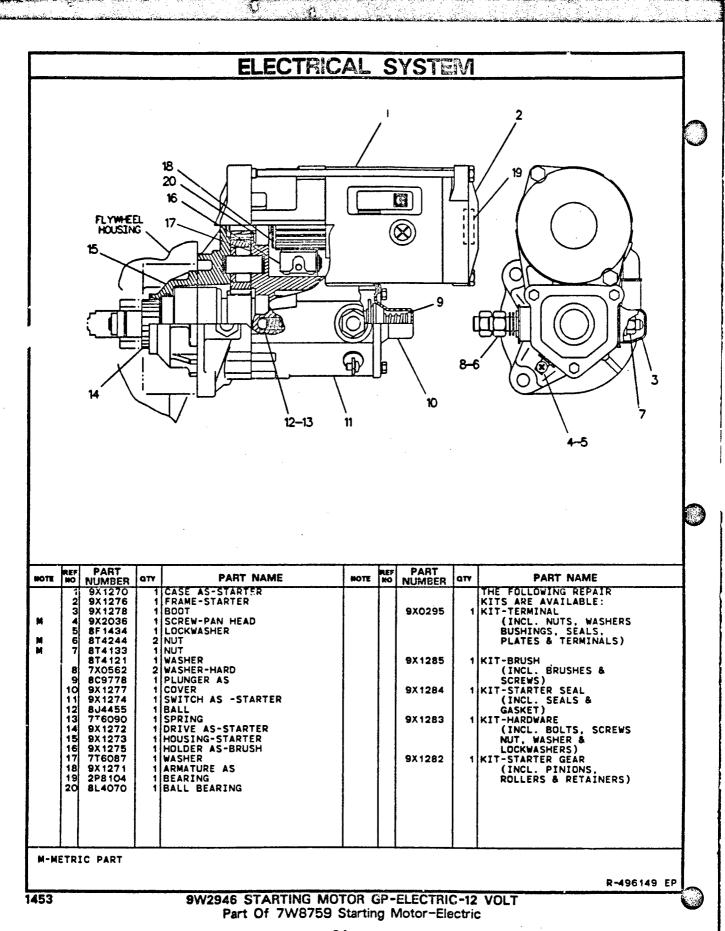


····· / ····· ,



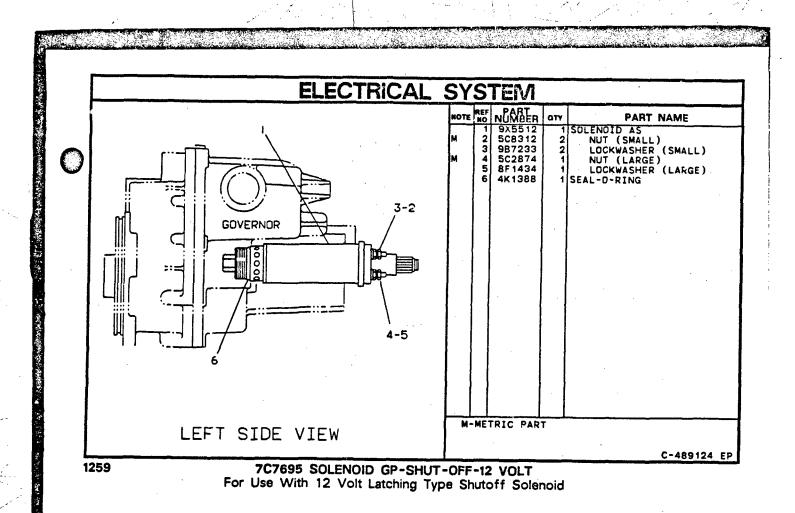


1.10





.



65

(:)

ENGINE RELATED PARTS

NOTE	PART NUMBER	ατγ	DESCRIPTION	F	AGE
NSS Y F	838073	1	ENGINE GROUP		67
NSS Y F	838087	1	ENGINE MOUNTING GROUP		68
NSS Y F	844141	1	ENGINE DRIVE SHAFT GROUP		73
NSS Y F	838111	1	RADIATOR GROUP		72
NSS Y F	815630	1	AIR CLEANER GROUP		71
NSS Y F	838870	1	EXHAUST GROUP		70
NSS Y F	838871	1	FUEL LINE GROUP		69
NSS Y F	4P5481	1	FAN SUCTION GROUP		34-1

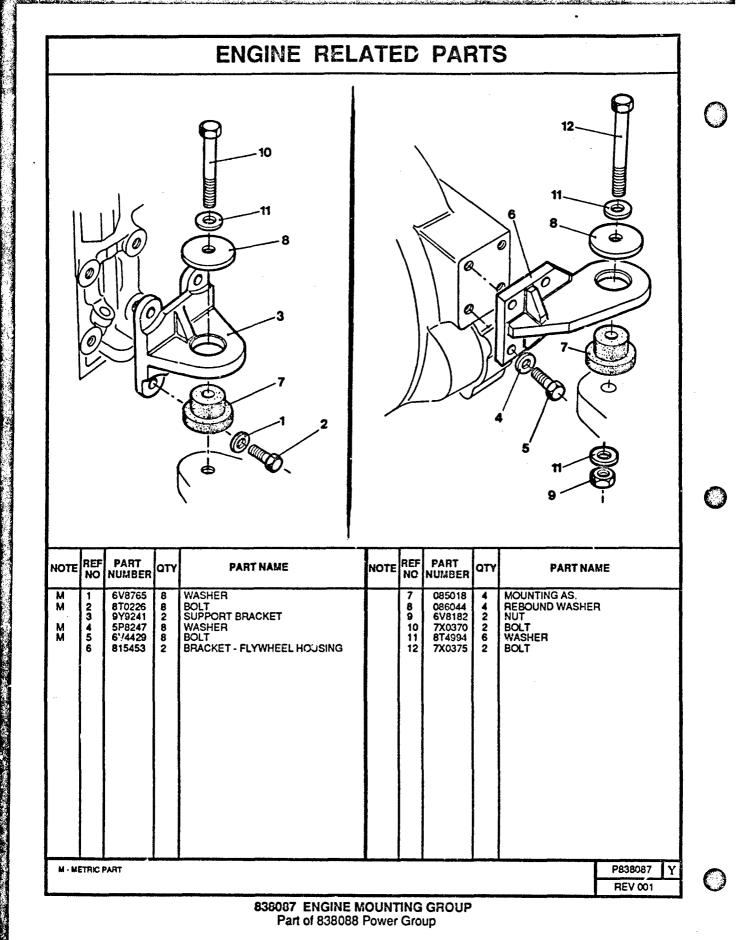
F - NOT SHOWN Y - SEPARATE ILLUSTRATION NSS - NOT SERVICED

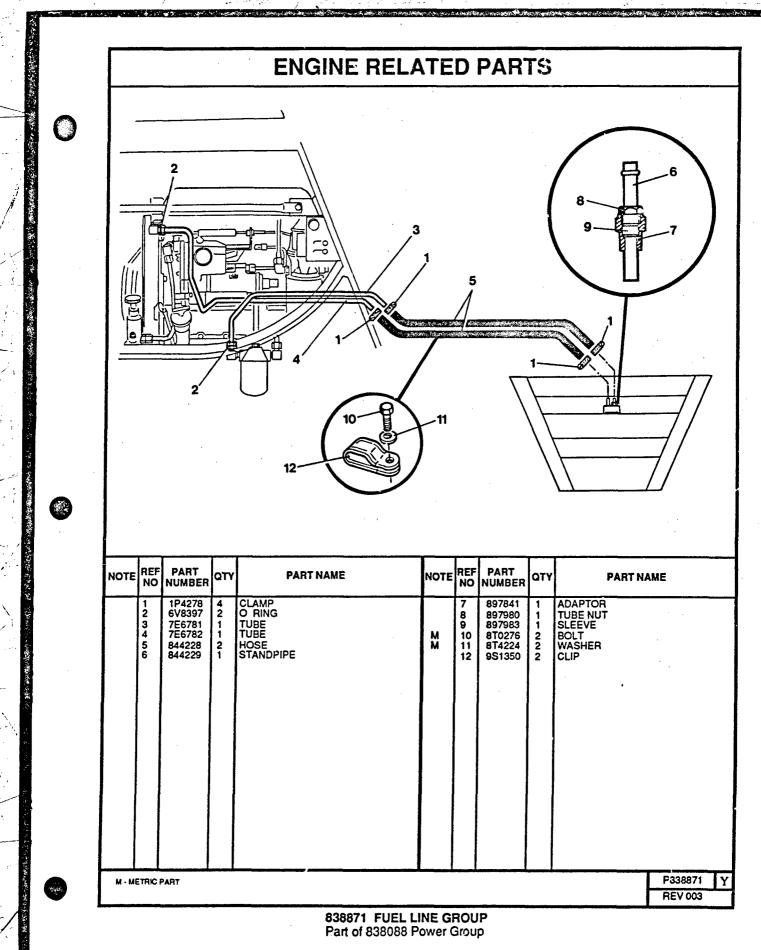
838088 POWER GROUP

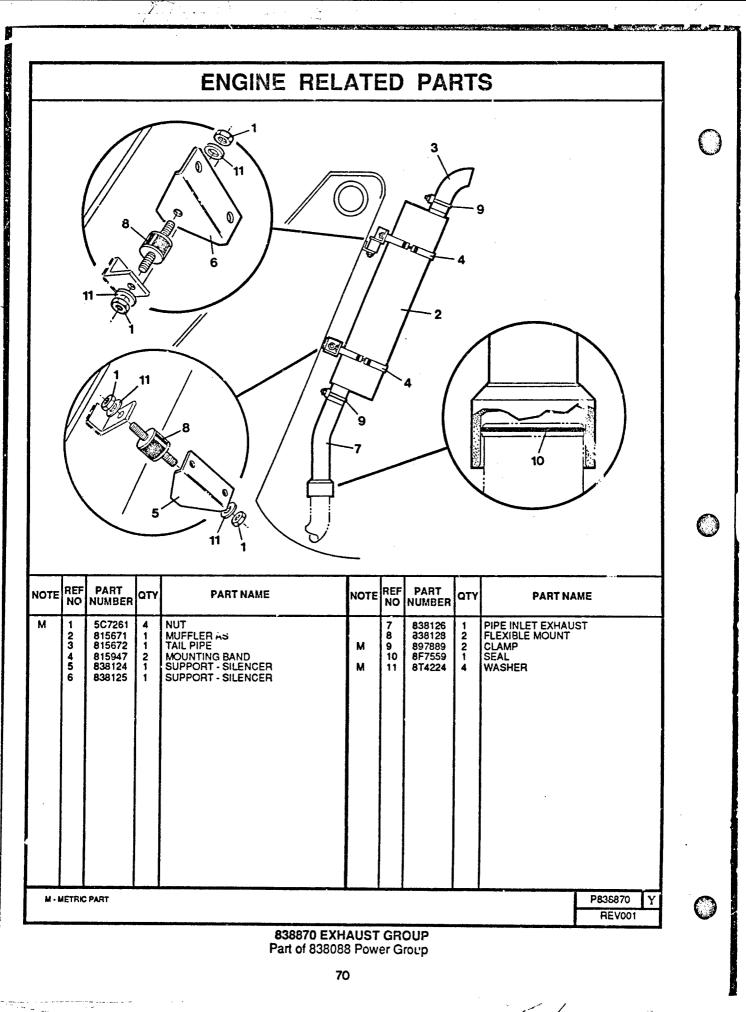
 \bigcirc

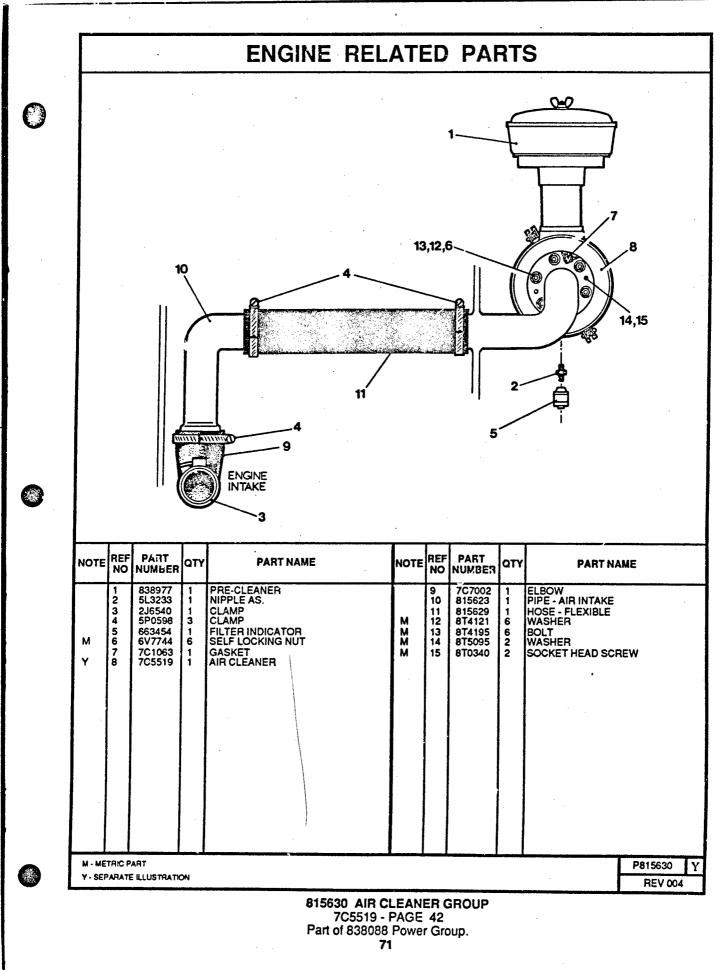
P838088 REV 001

	· · · · · · · · · · · · · · · · · · ·	ENGINE RELATE	D PARTS	
0		PART NOTE NUMBER QTY DESCRIPTION	PAGE	
		NSS Y F 7C5477 1 ENGINE GROUP	2 and 3	
			· · ·	
	F - NOT SHOWN Y - SEPARATE ILLUSTRATION NSS - NOT SERVICED	J		P838073 REV 000
1		838073 ENGINE GROU Part of 838088 Power Gro	Jb Jb	
V	: :			
	1			
i.				
				•
-				







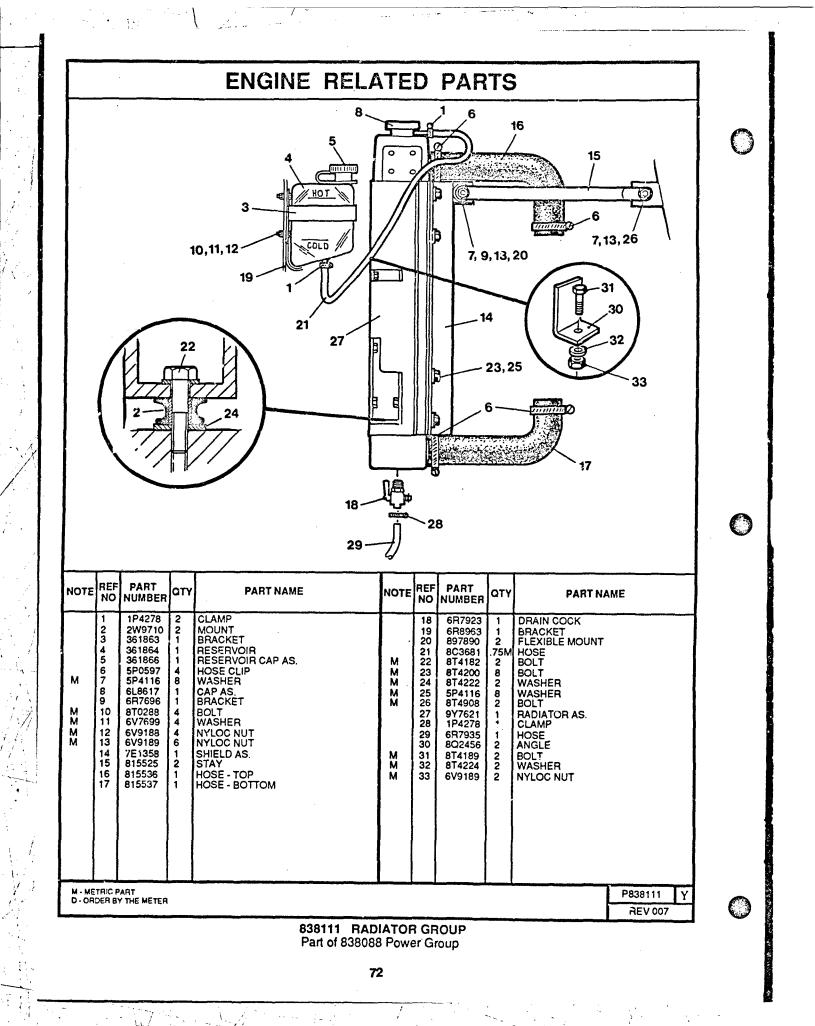


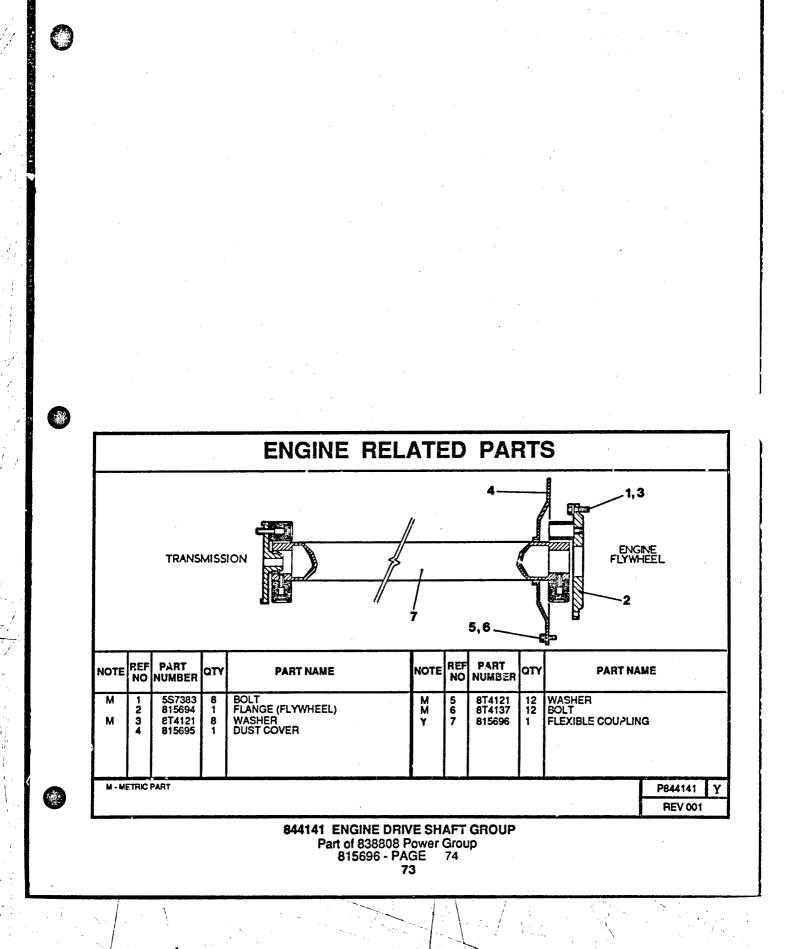
ļ

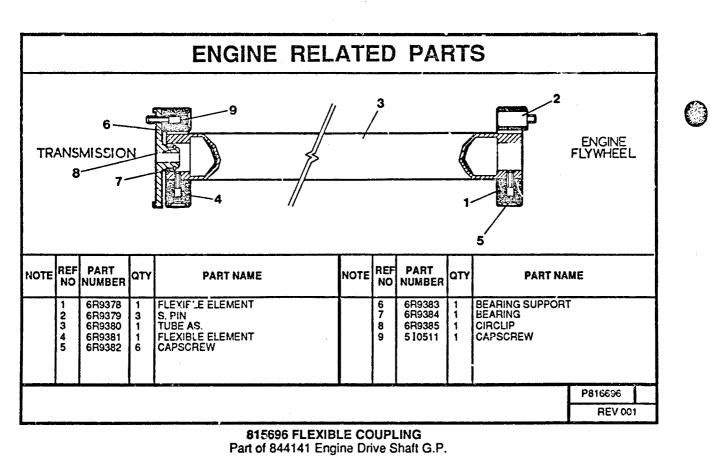
٤,

11.1

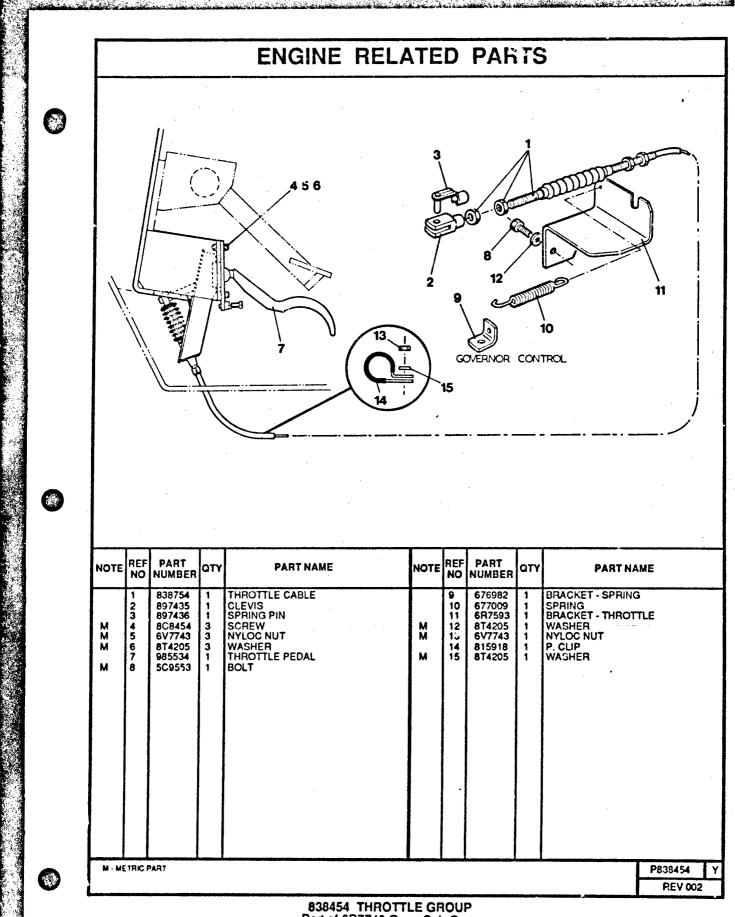
.





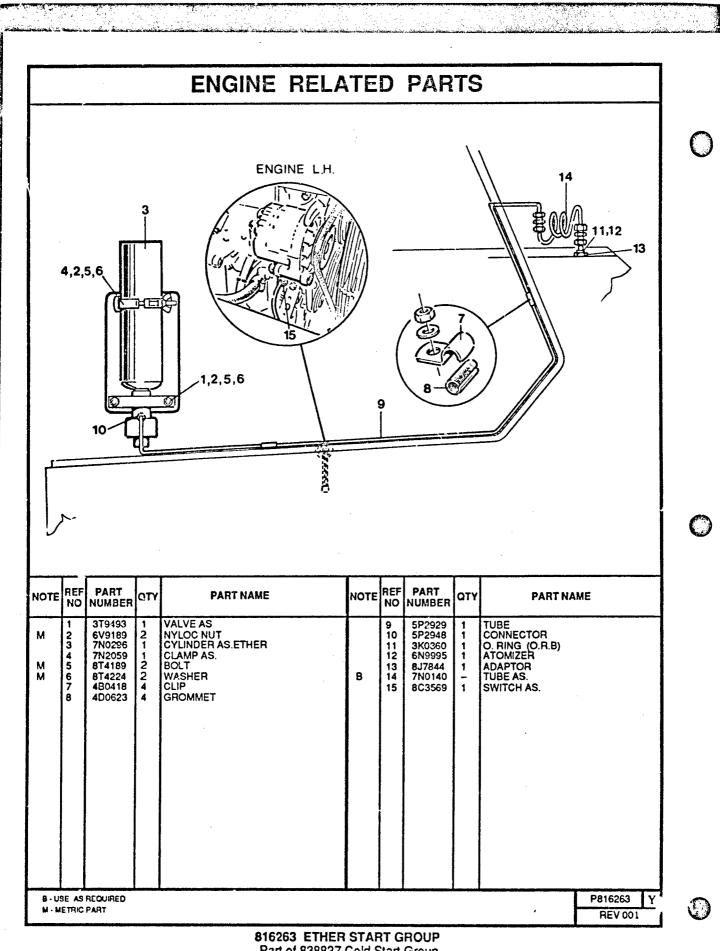


The state of the second of



.

Part of 6R7740 Open Cab Group



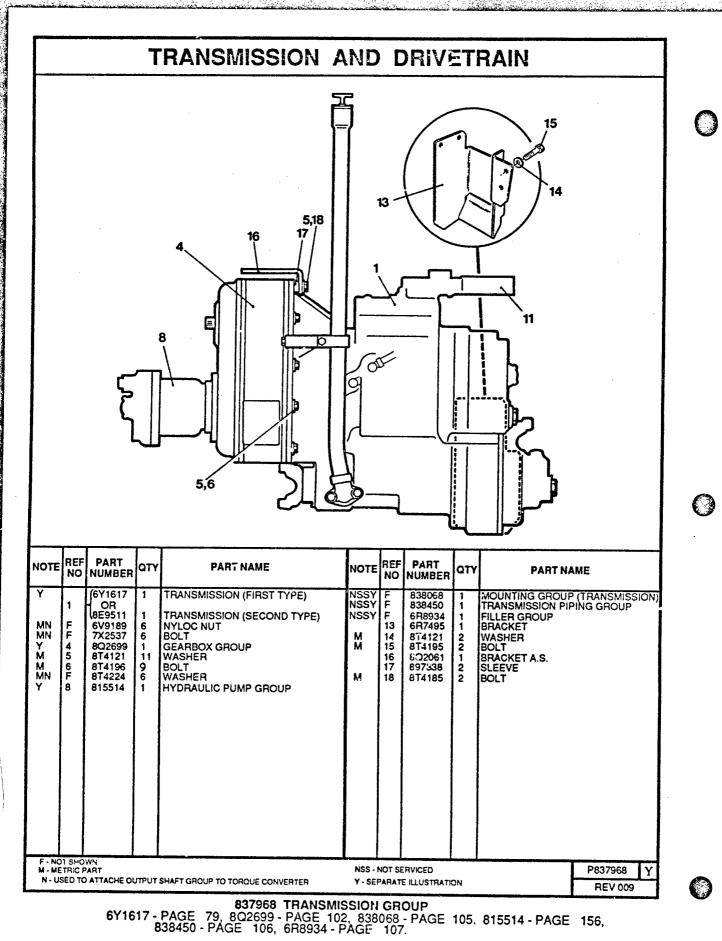
Part of 838837 Cold Start Group

	MEMORANDUM	
0		
0		
		•
0		MEMORANDUM

.

*

e



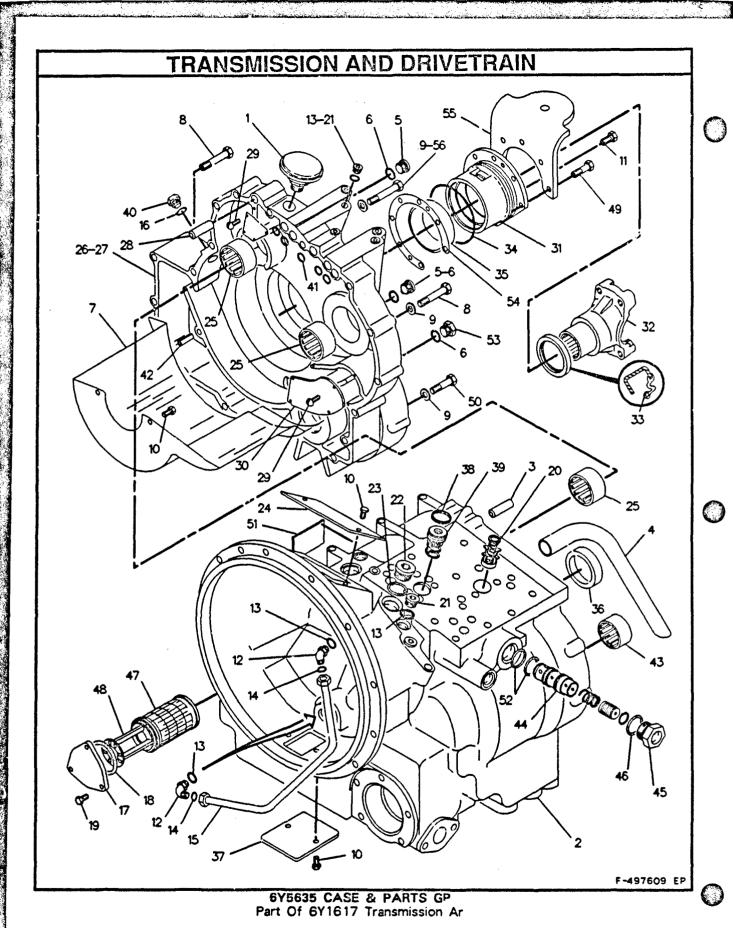
TRANSMISSION AND DRIVETRAIN

			PAGE
1	6Y5635	CASE & PARTS GP	80
1	779400	CLUTCH GP	82
1	779402	CLUTCH GP	84
1	779401	CLUTCH GP	86
1	6Y 1293	CONTROL GP-TRANSMISSION HYD	93
1	98214	DRIVE GP-FLEXIBLE COUPLING	99
1	6Y8151	DRIVE GP-TRANSFER	100
1	675641	LINES GP-POWER TRAIN OIL	91

1 BEB623 TORQUE CONVERTER AS (NO SERVICEABLE PARTS)

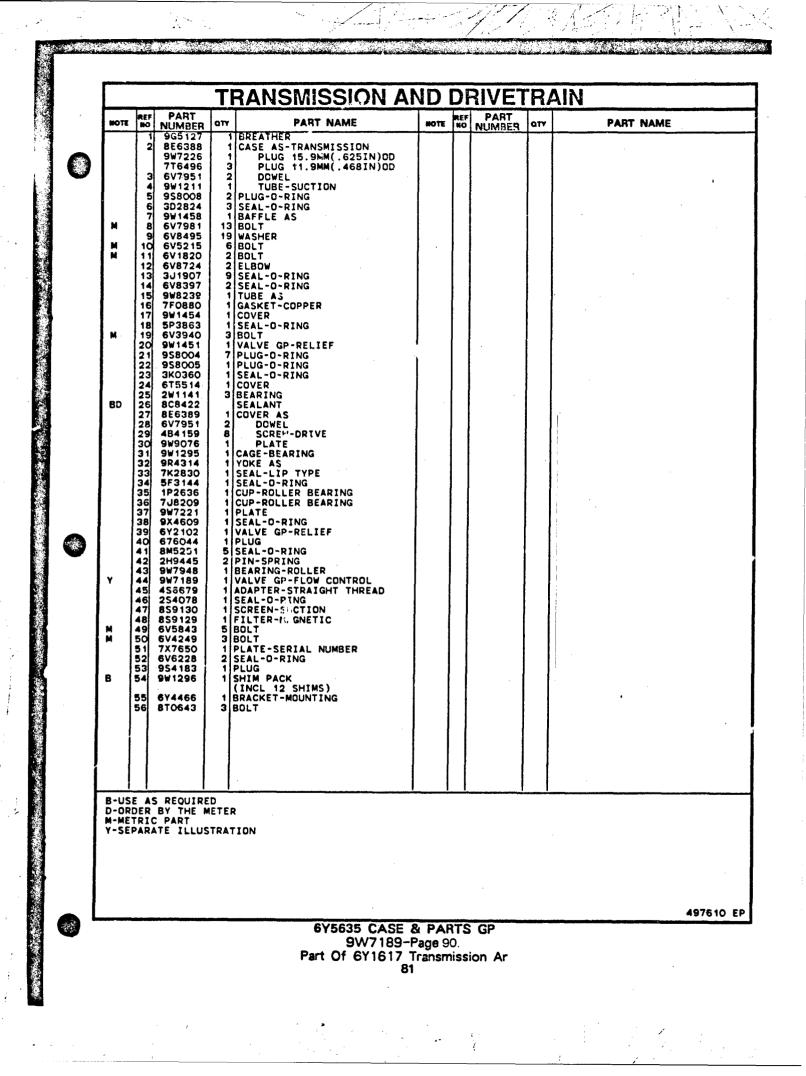
512741 P

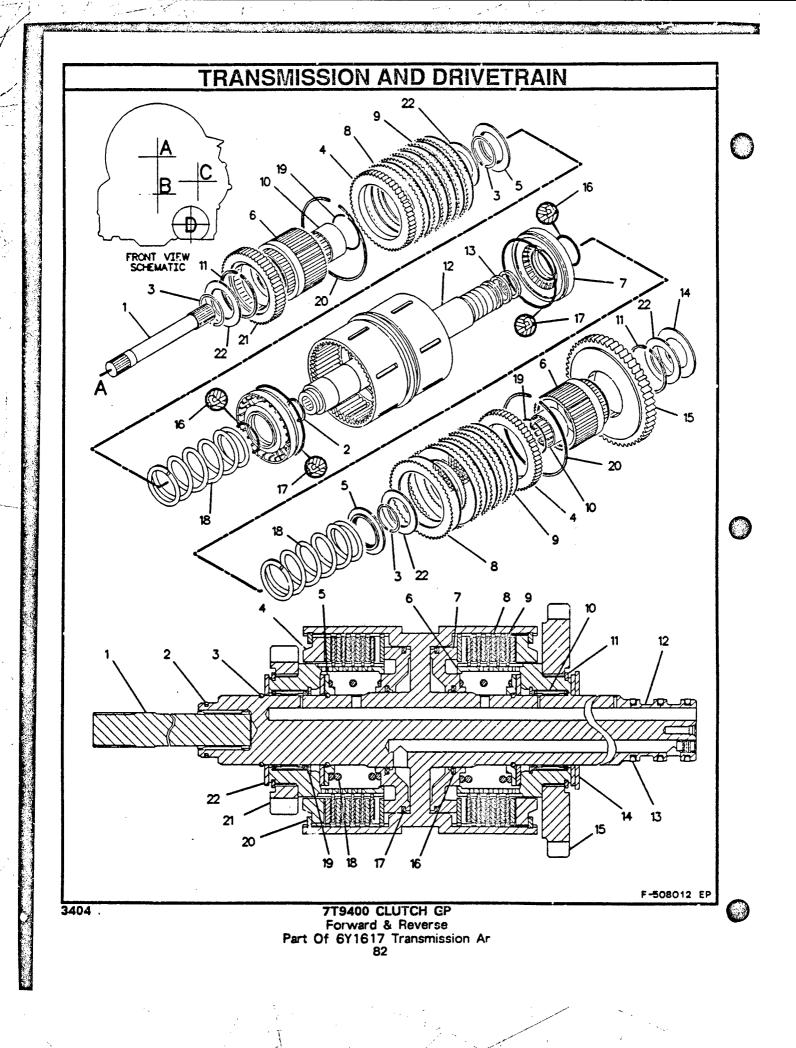
FY1617 TRANSMISSION AR

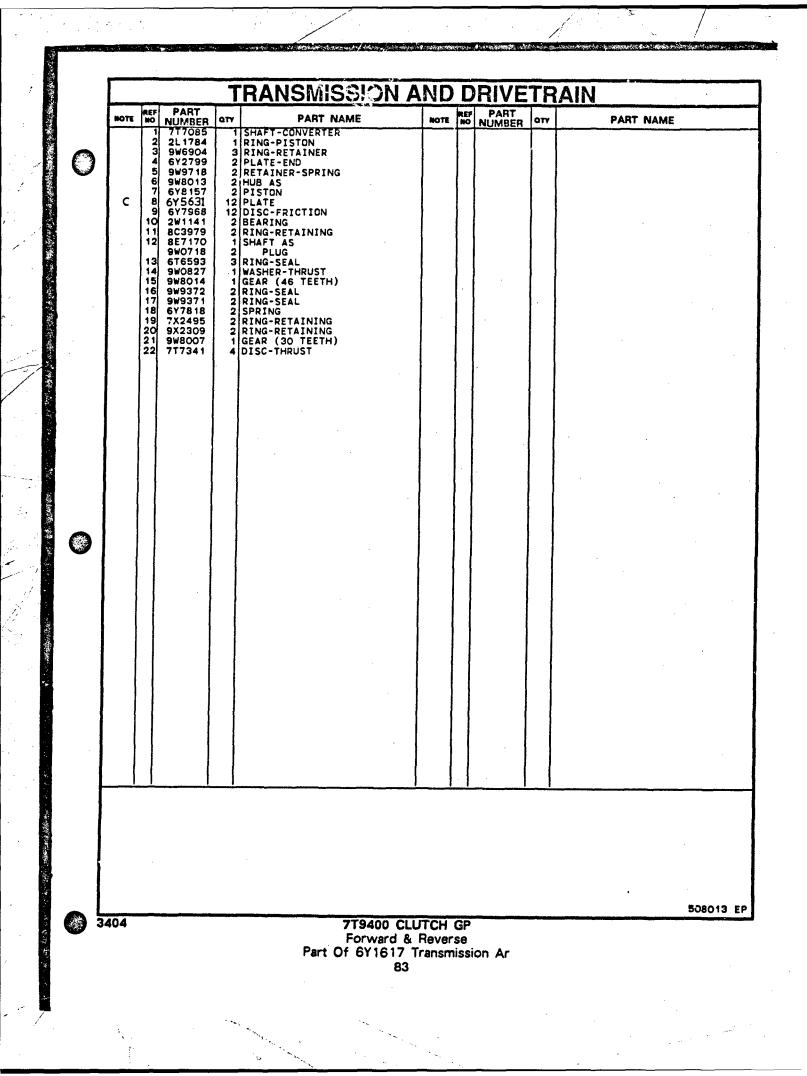


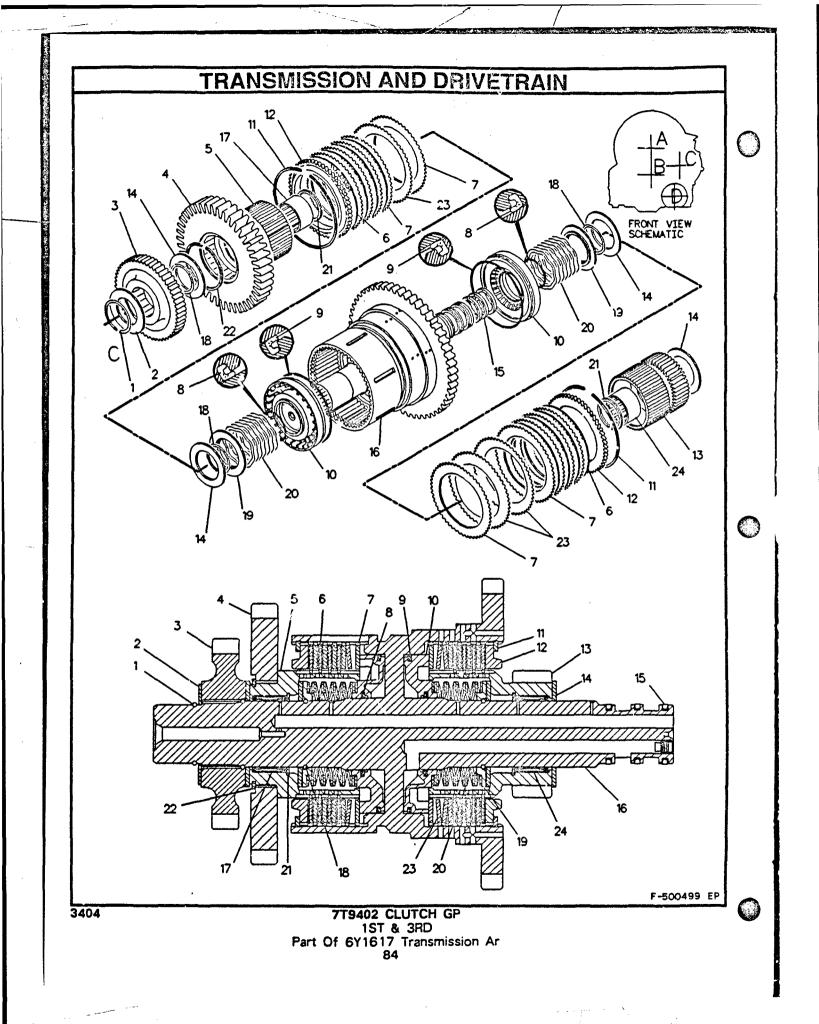
···-- /

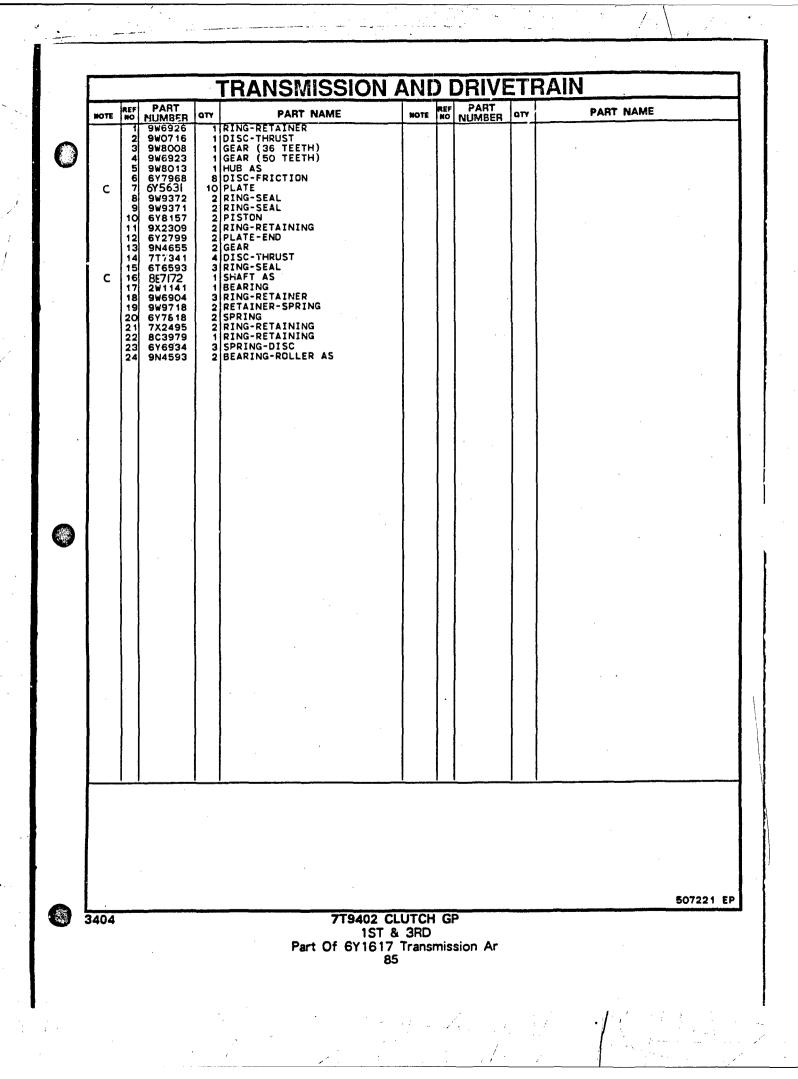


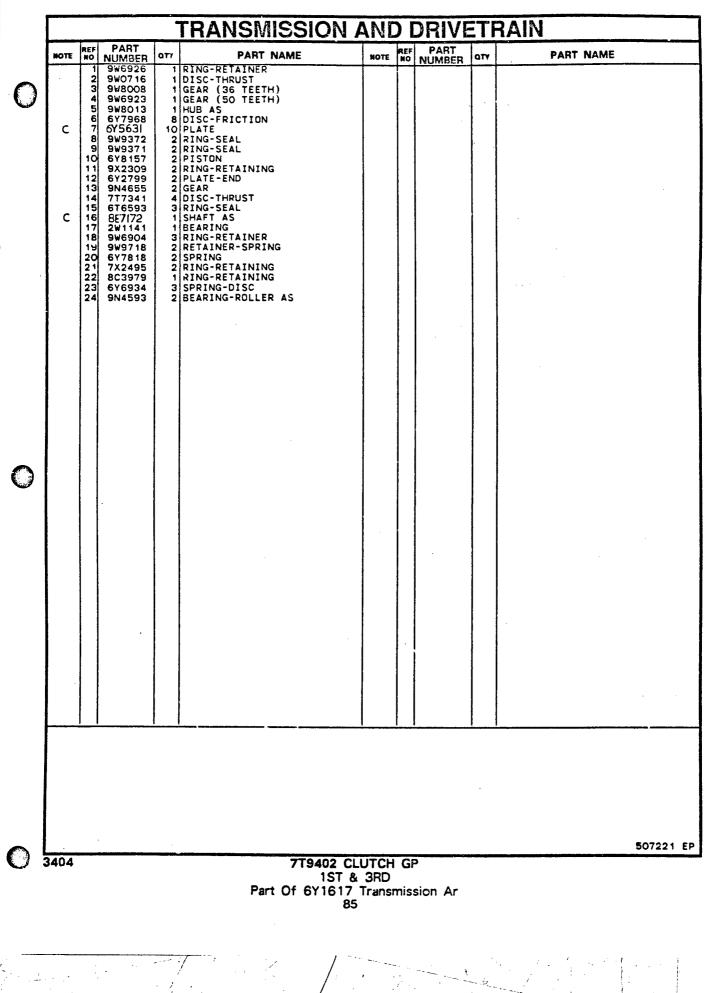






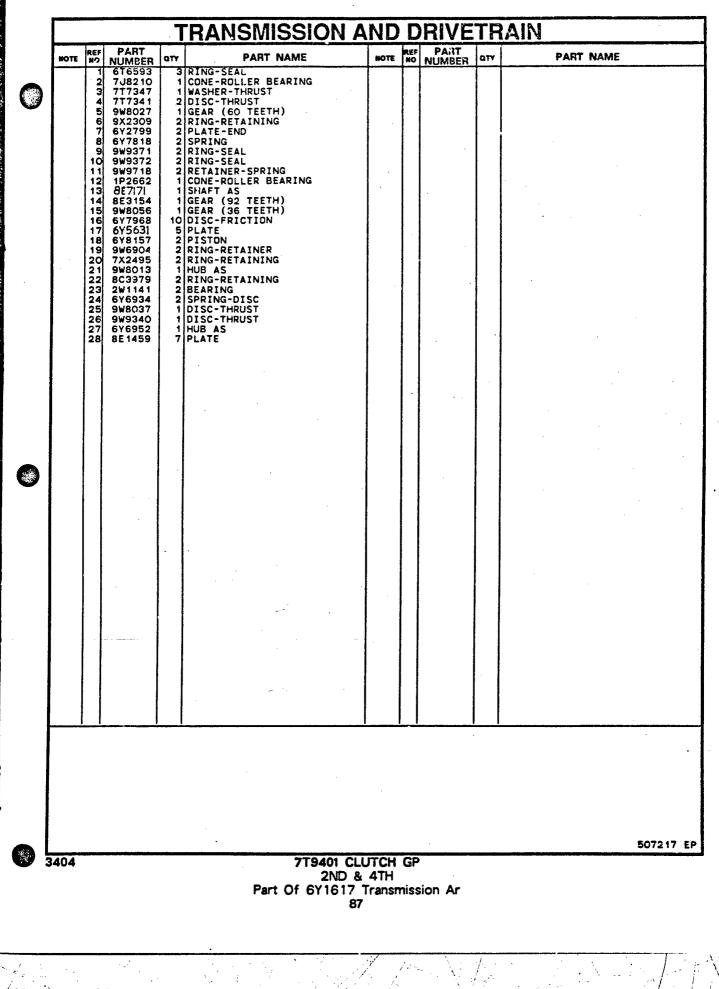




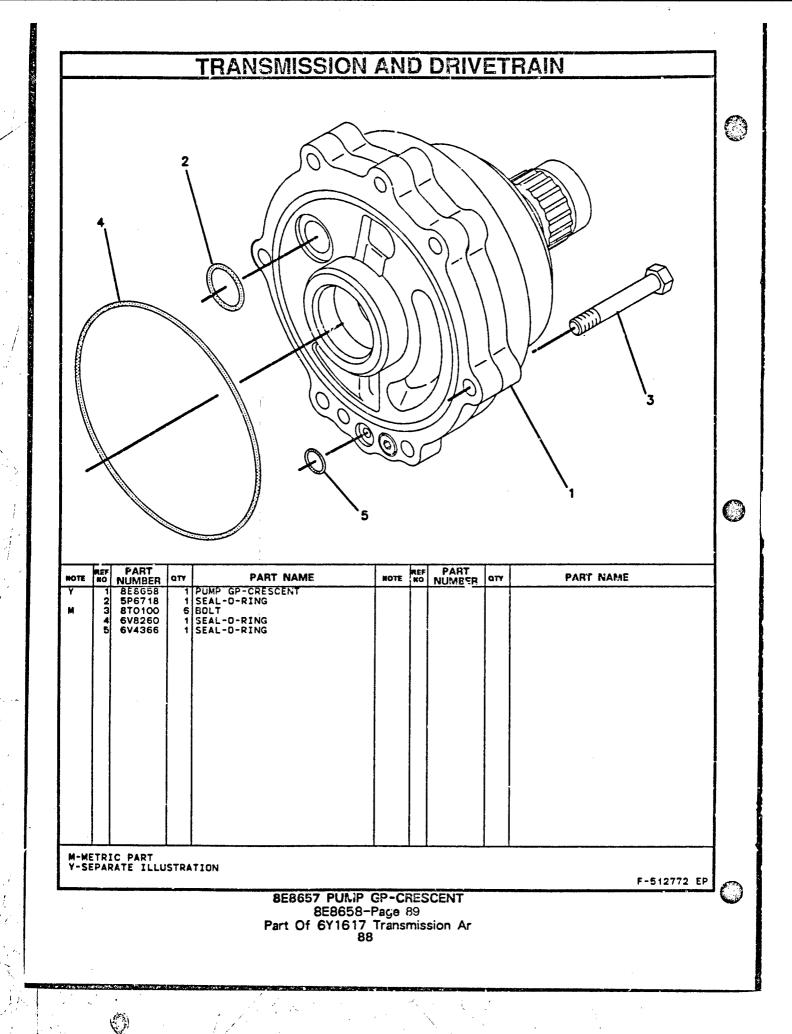


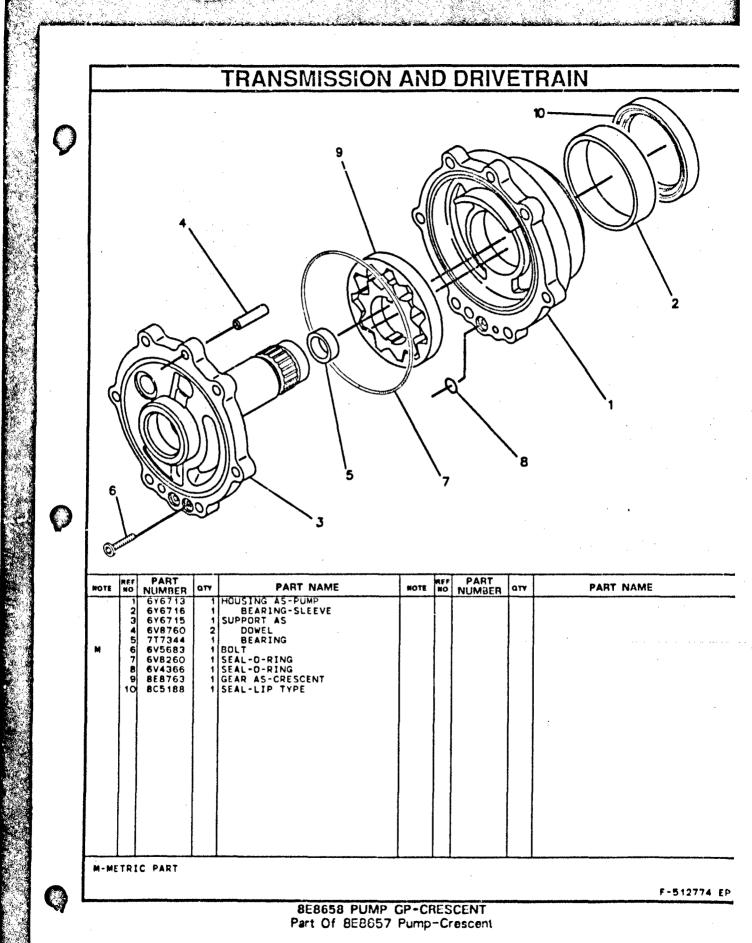
÷

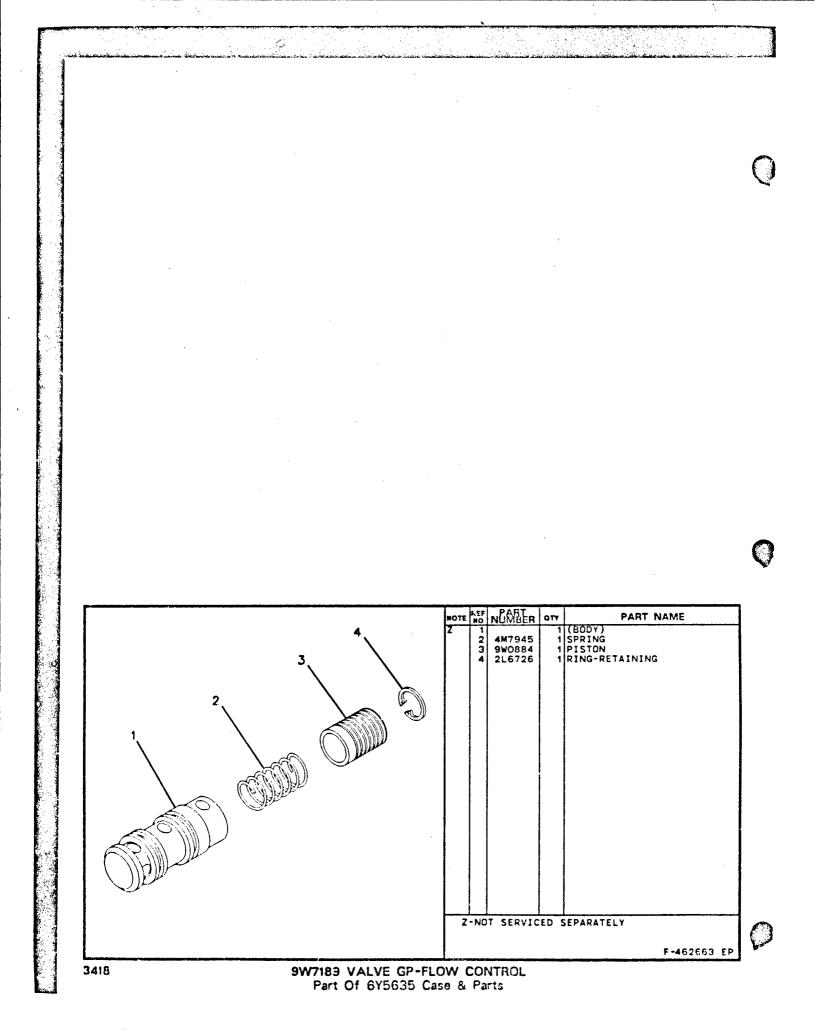
....

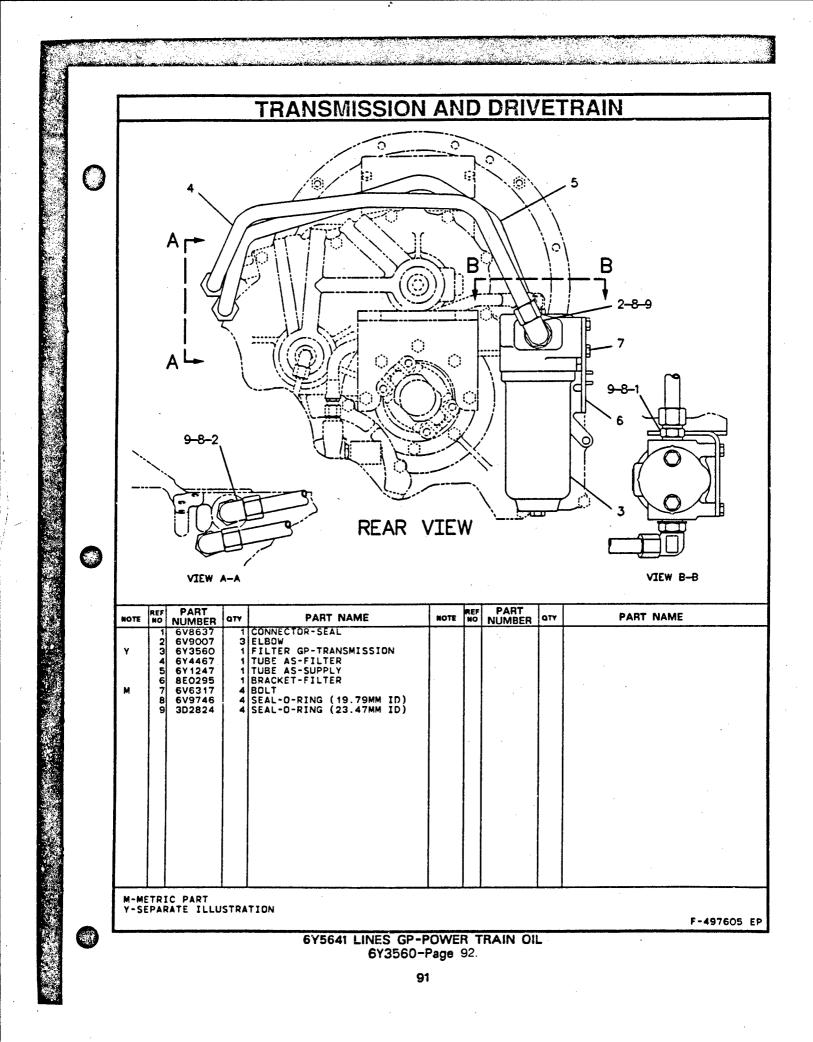


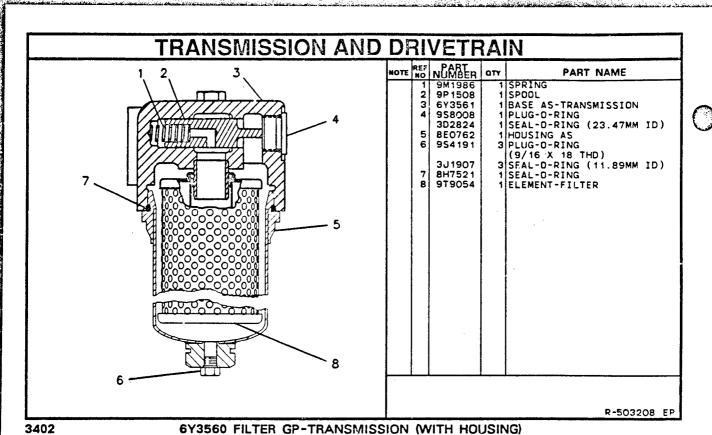
and the tar



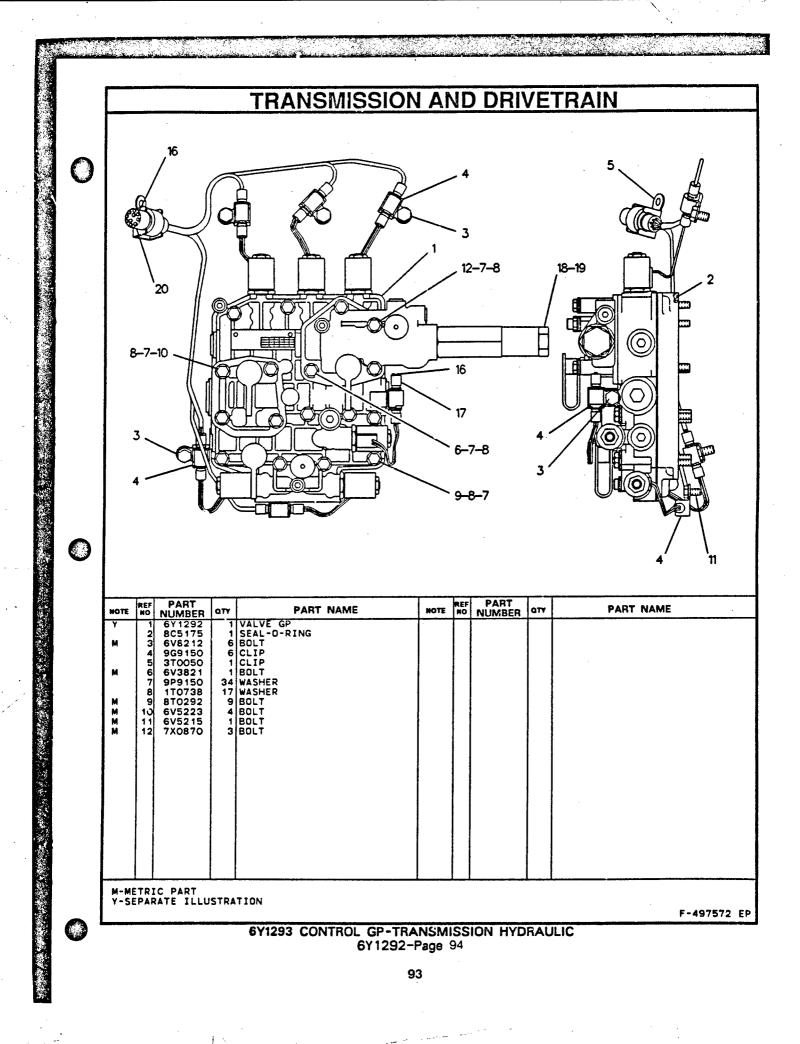


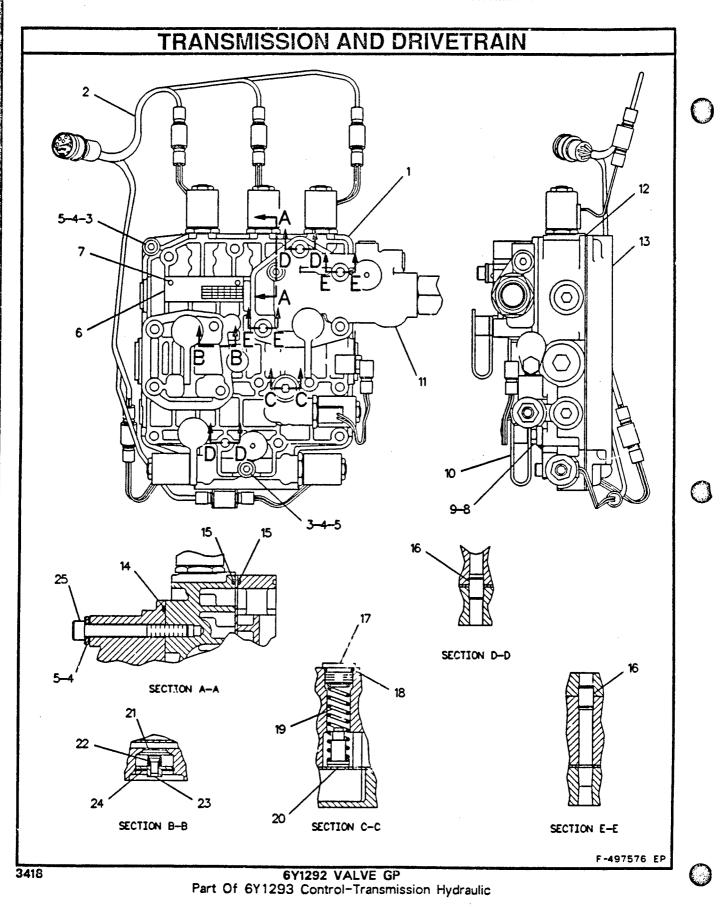


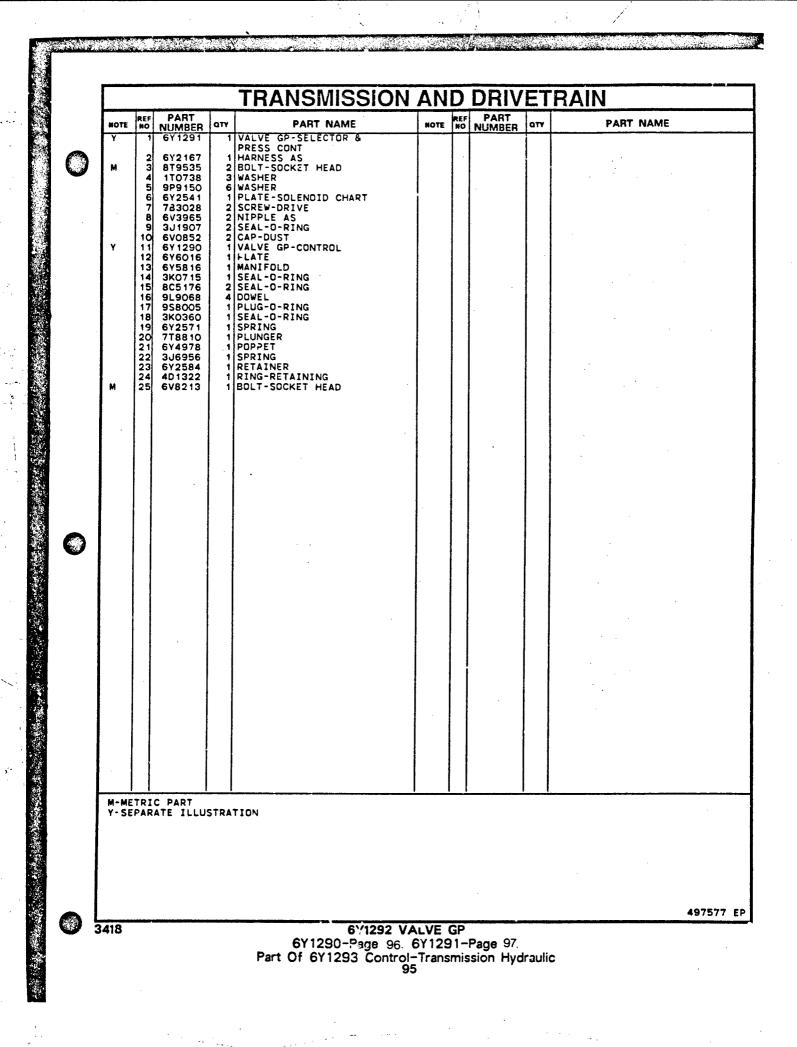


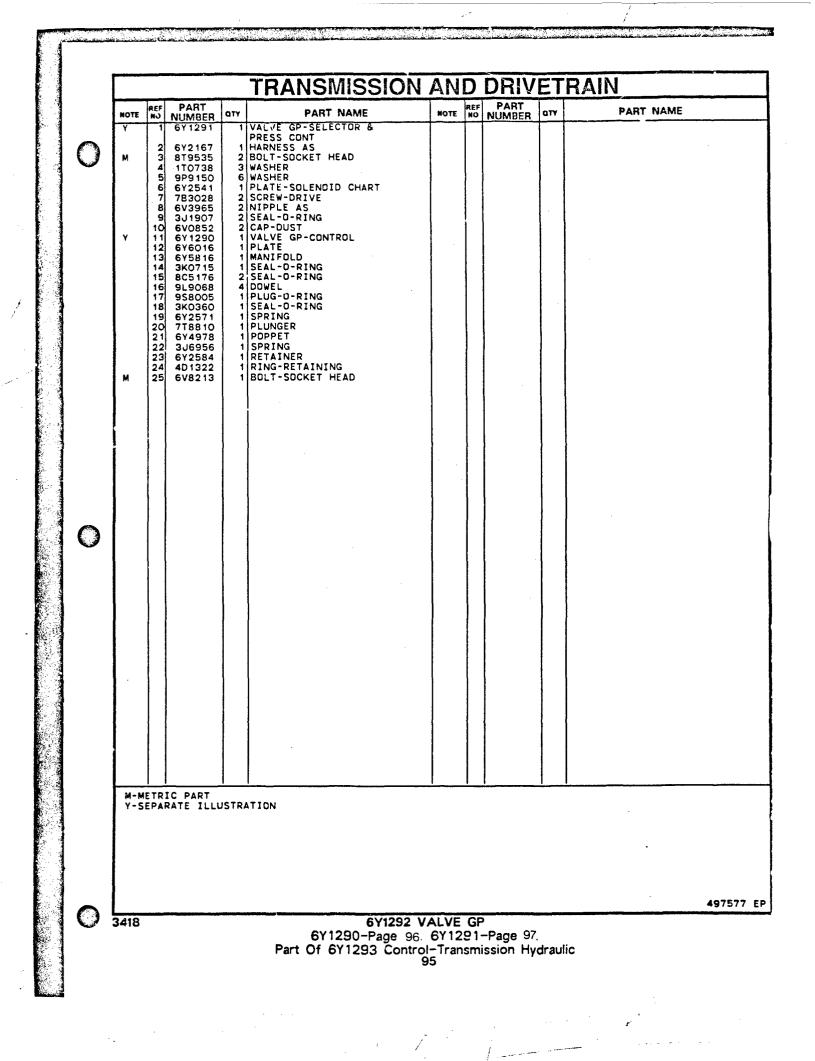


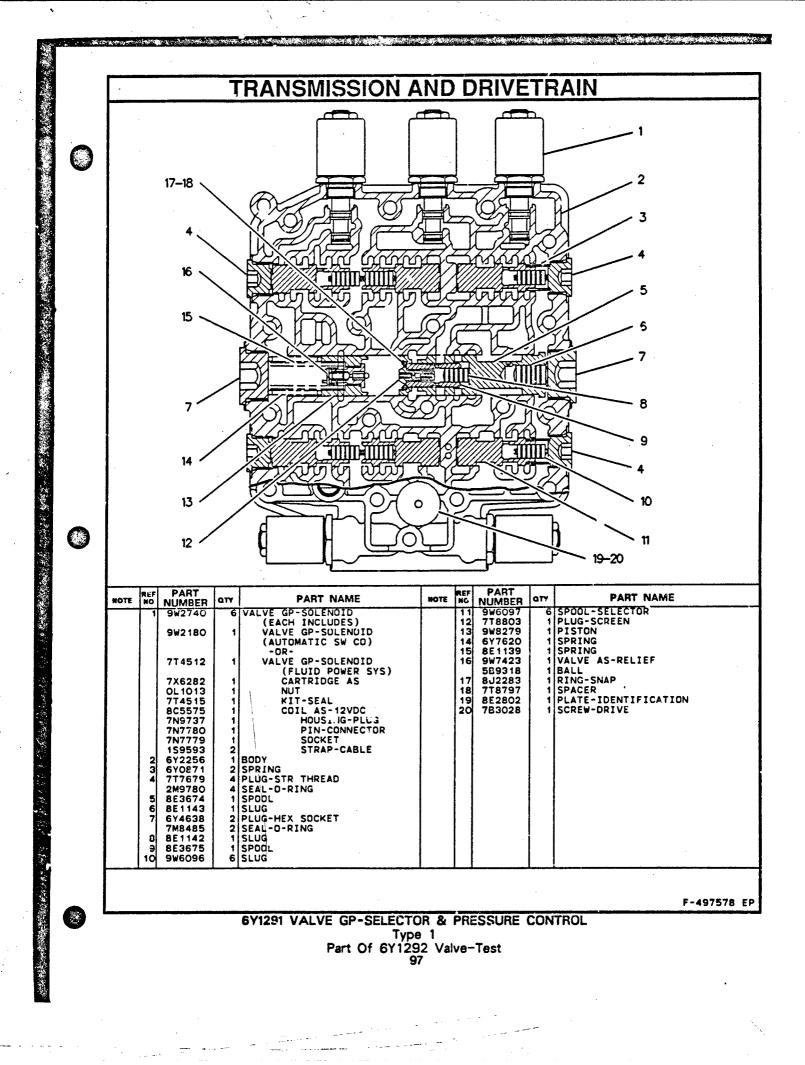
Part Of 6Y5641 Lines-Power Train Oil

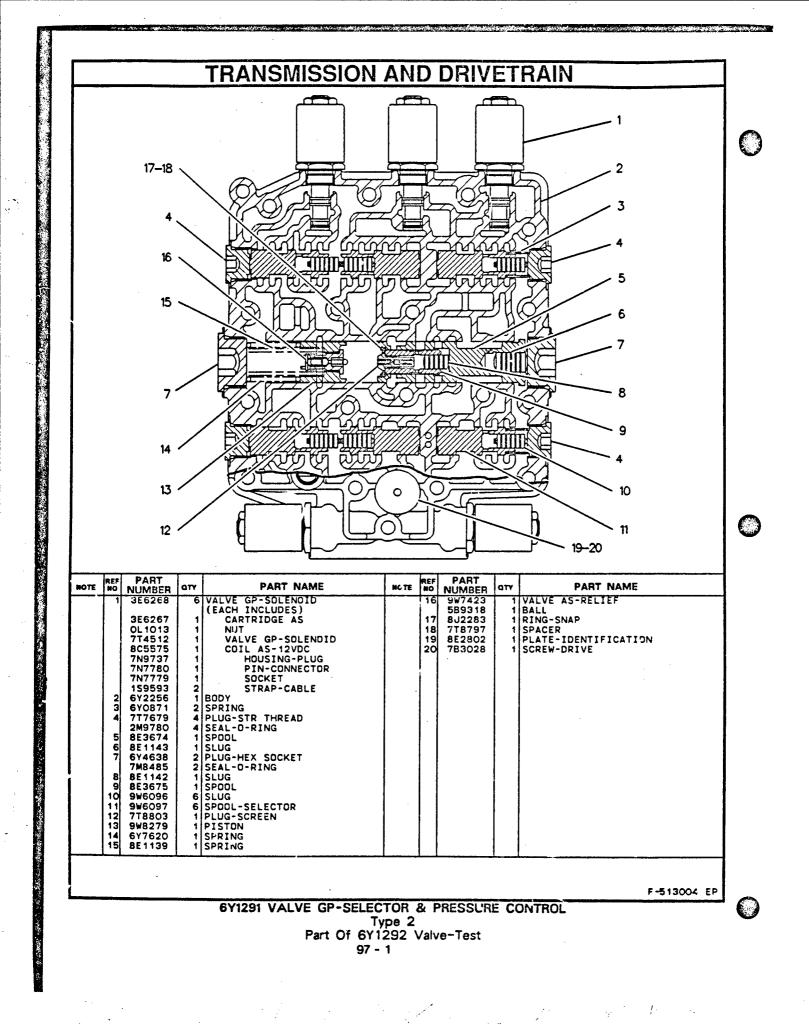


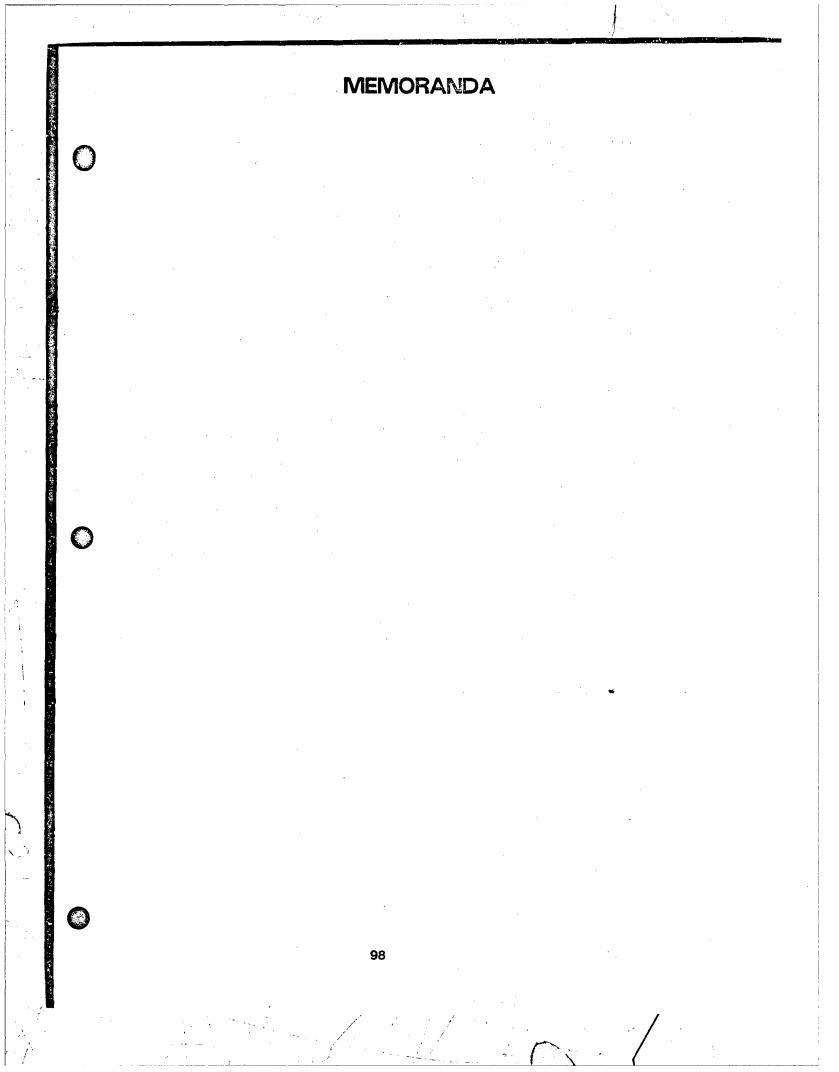


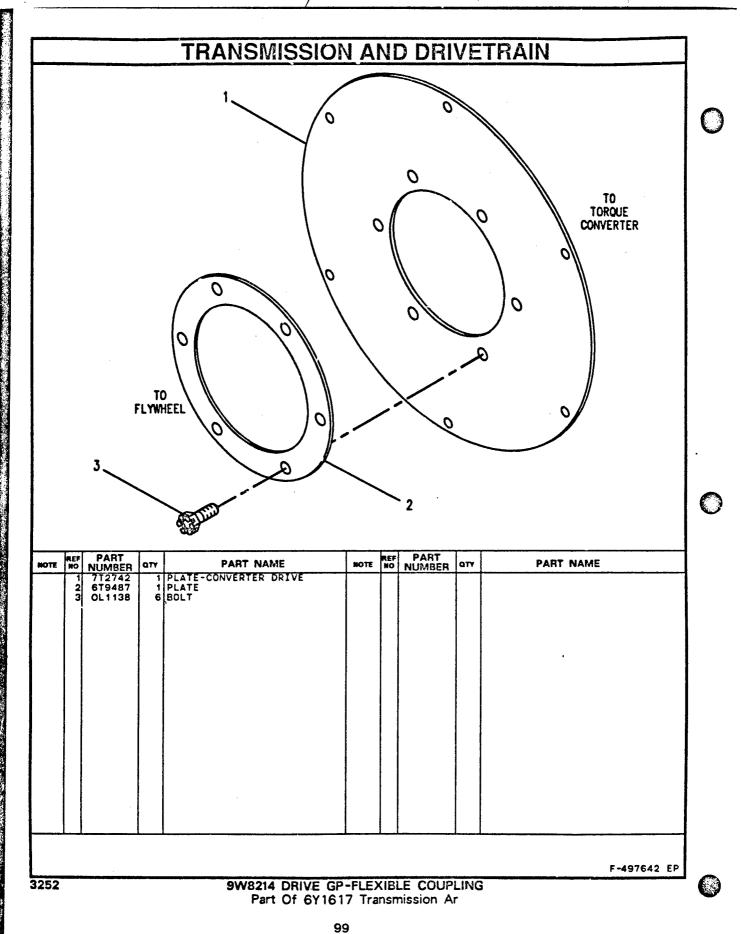






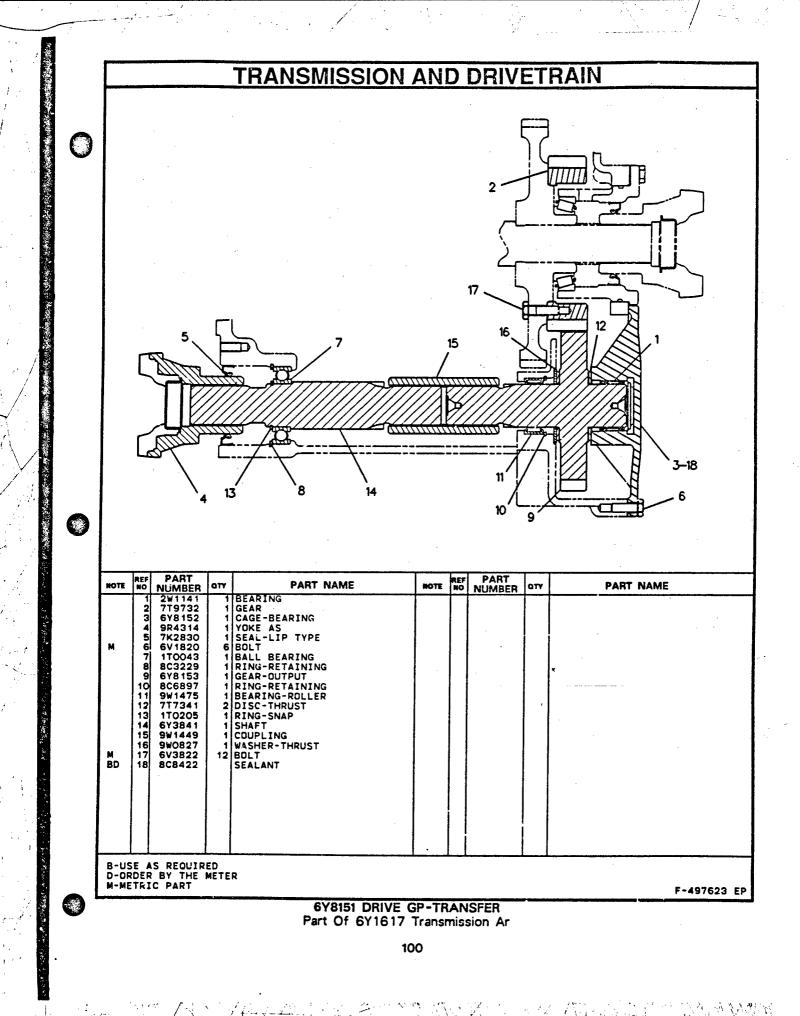


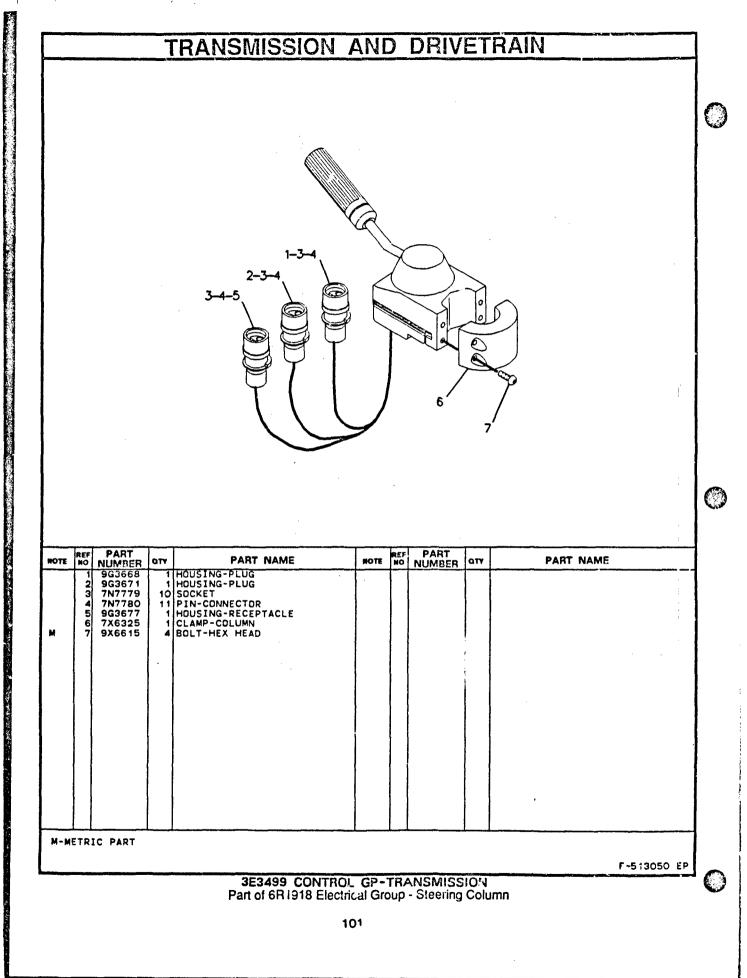




•••

.

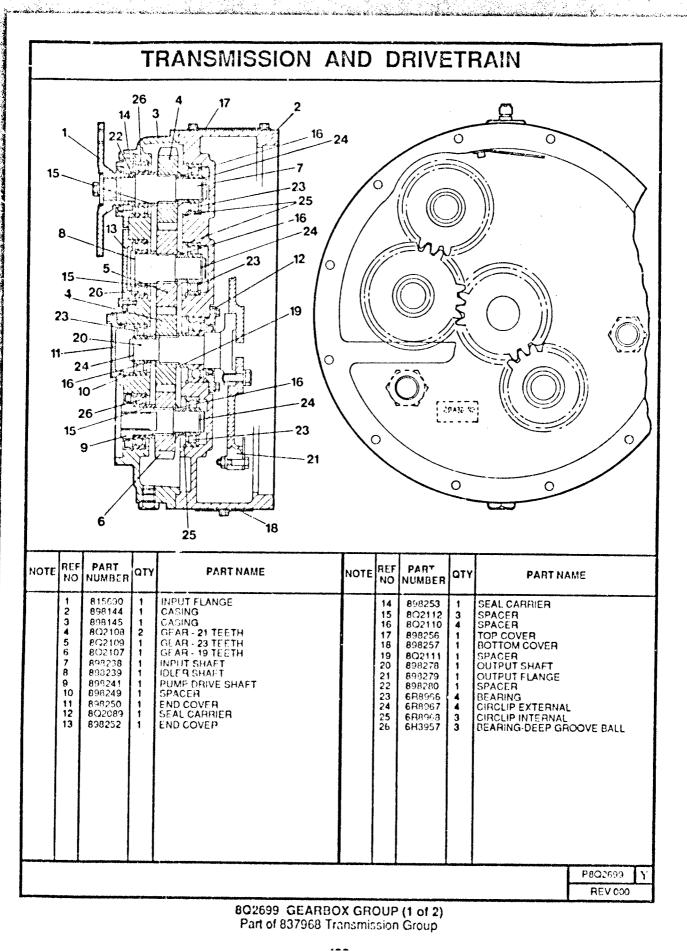




÷

MEMORANDA

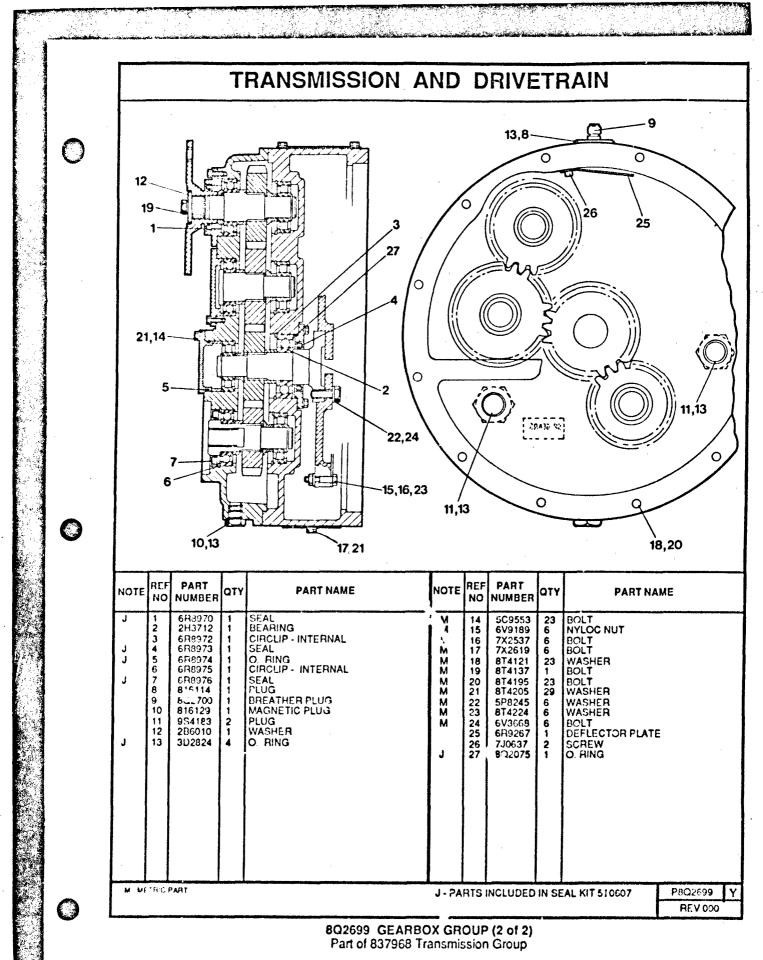
 \bigcirc



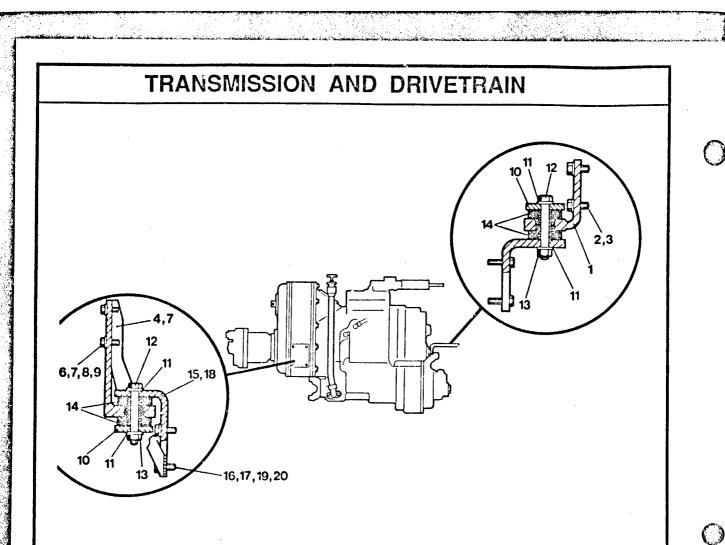
Q

0

(]



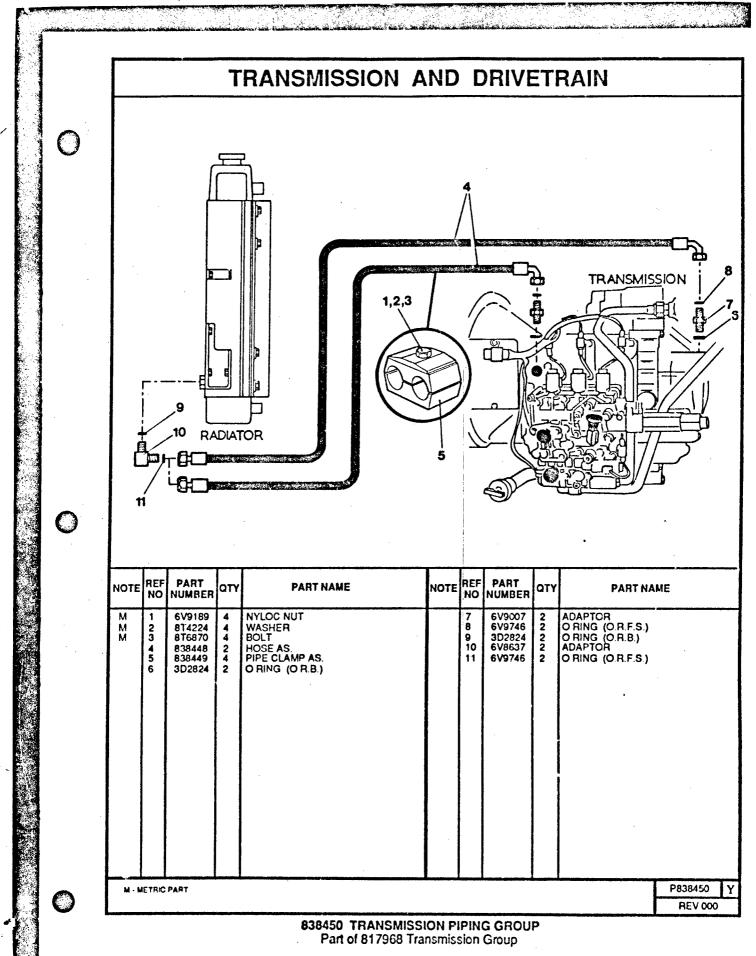
10.4

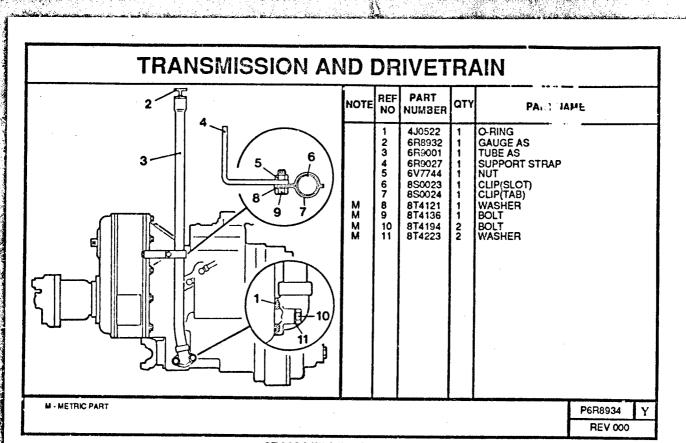


NOTE	REF NO	PART NUMBER	ατγ	PART NAME	NOTE	REF NO	PART NUMBER	ατγ	PARTNAME
м м м м м	1 2 3 4 5 6 7 8 9 10	815448 8T4139 8T4223 838052 8T4139 8T4223 838048 8T4223 874223 3T6742	4 1 4 1 4 4	BRCKET-TRANSMISSION MOUNTING BOLT WASHER BOLT WASHER BRACKET AS. R.H. BOLT WASHER RETAINER	M M M M M M M M M M M M M M M M M M M	11 12 13 14 15 16 17 17 18 19 20	4D3704 8T0262 8T1757 9R0390 815451 8T4139 8T4223 815452 8T4139 8T4223	6333144144	WASHER BOLT NUT MOUNTING AS. BRCKET ASTRANSMISSION R.H. BOLT WASHER BRCKET ASTRANSMISSION L H BOLT WASHER
M - METRIC PART									P836068 Y REV 000

838068 MOUNTING GROUP (TRANSMISSION) Part of 817968 Transmission Group

 \bigcirc



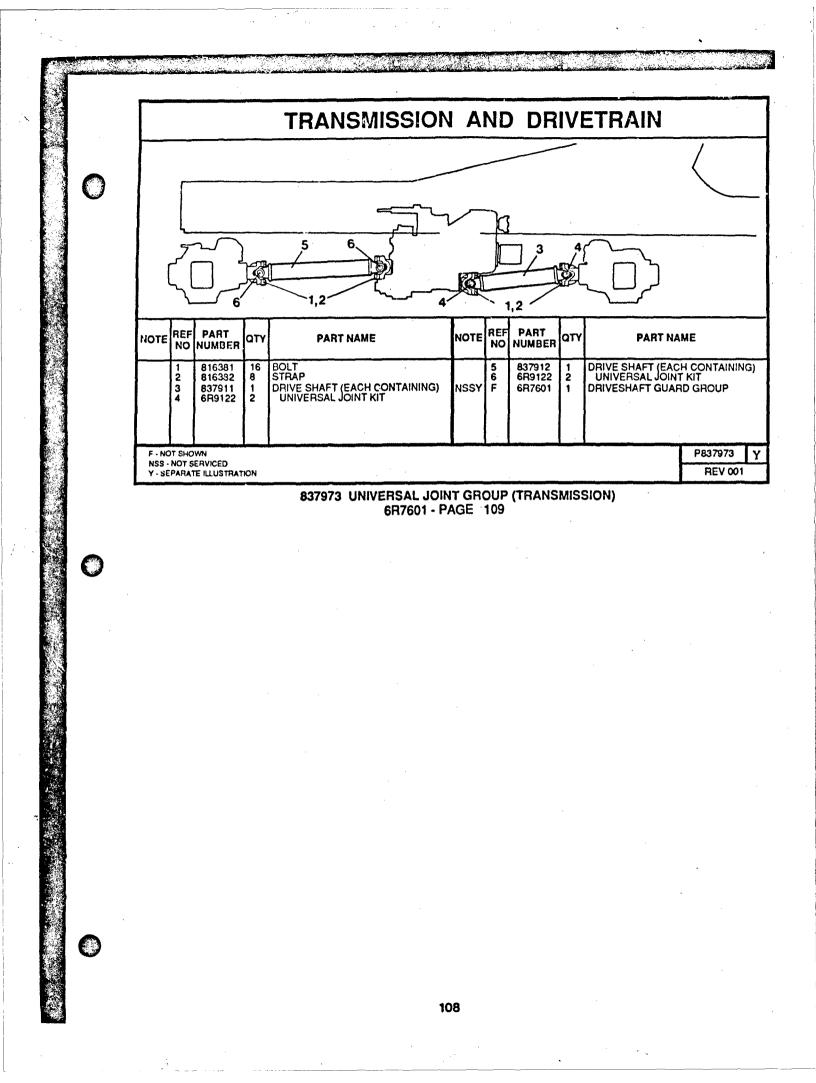


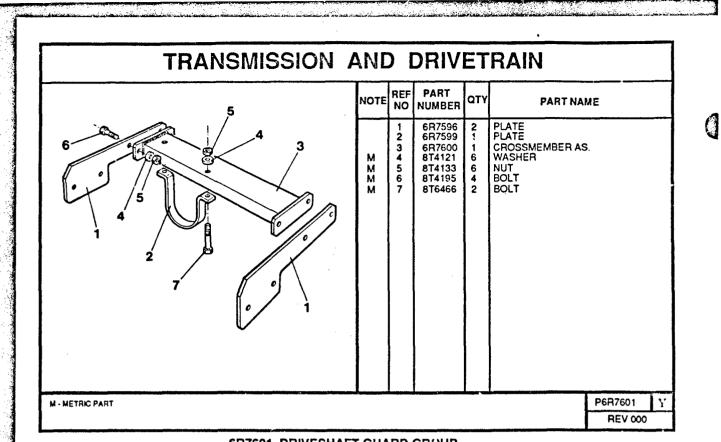
 \square

)

6R8934 FILLER GROUP Part of 837968 Transmission Group

•





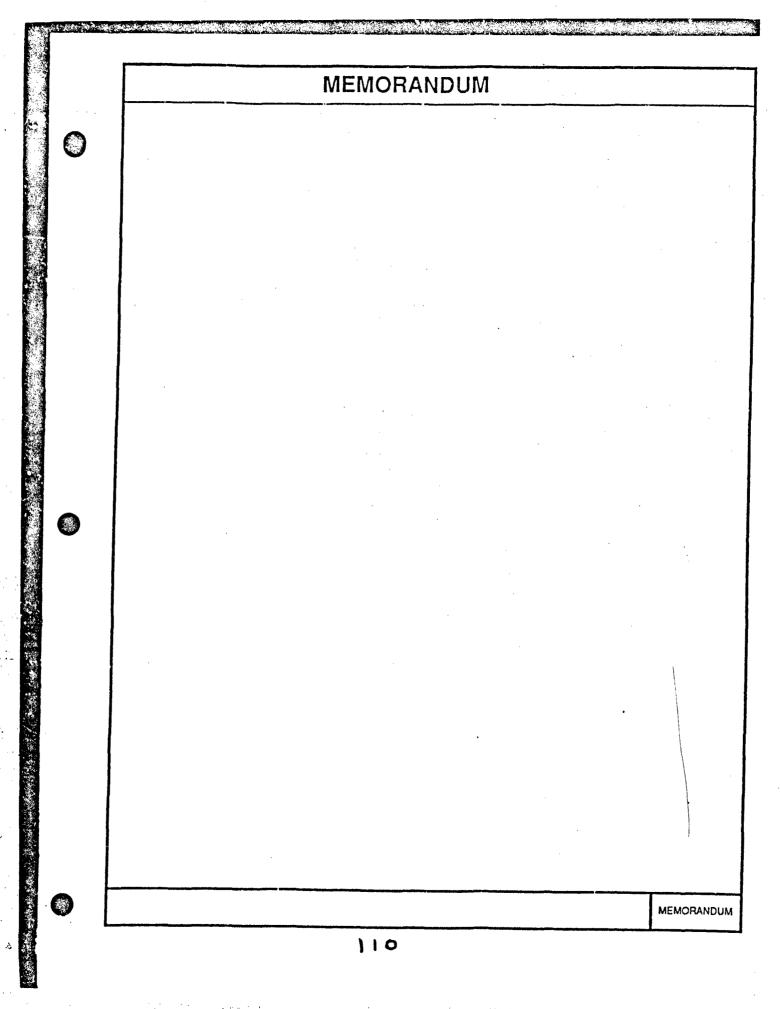


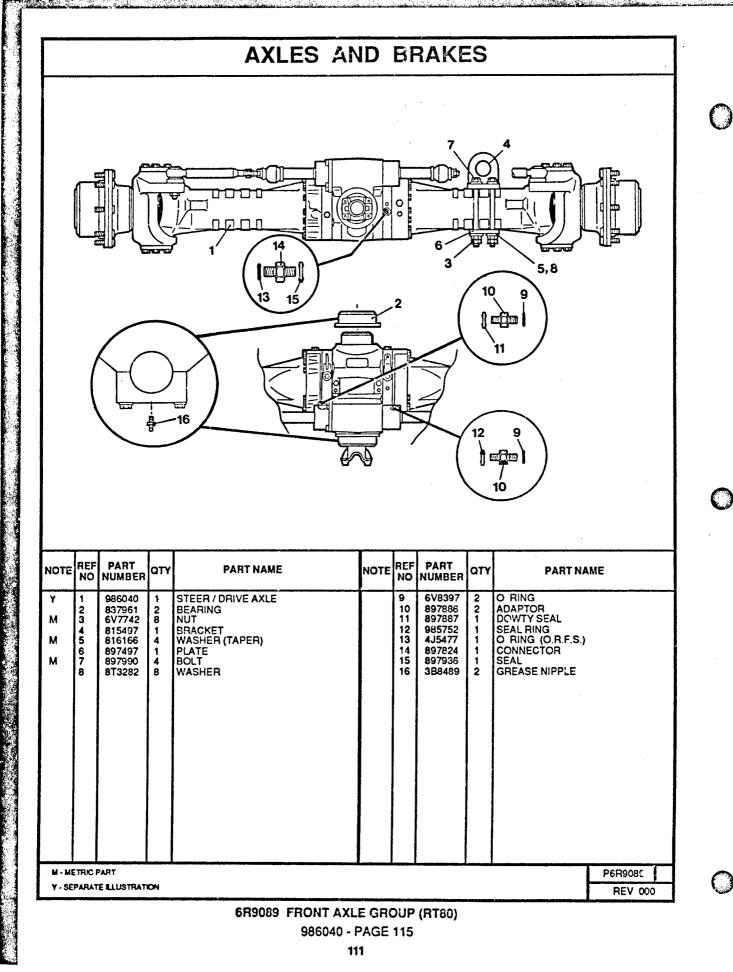


109

.

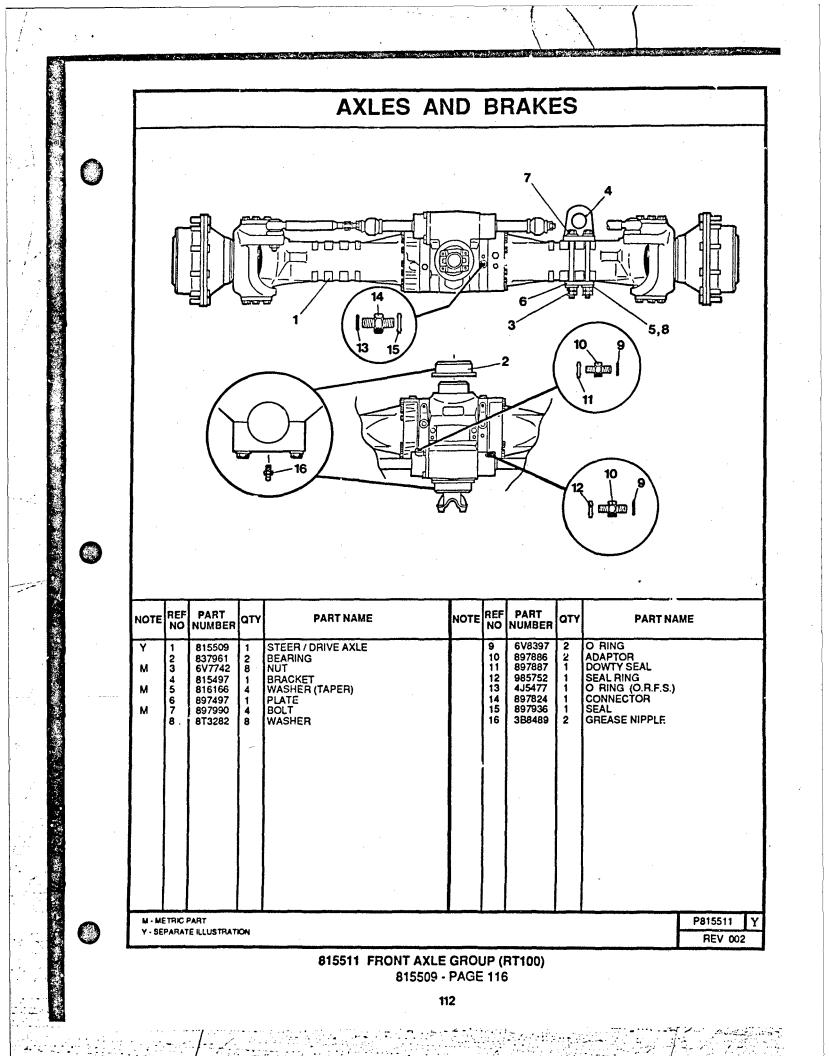
.

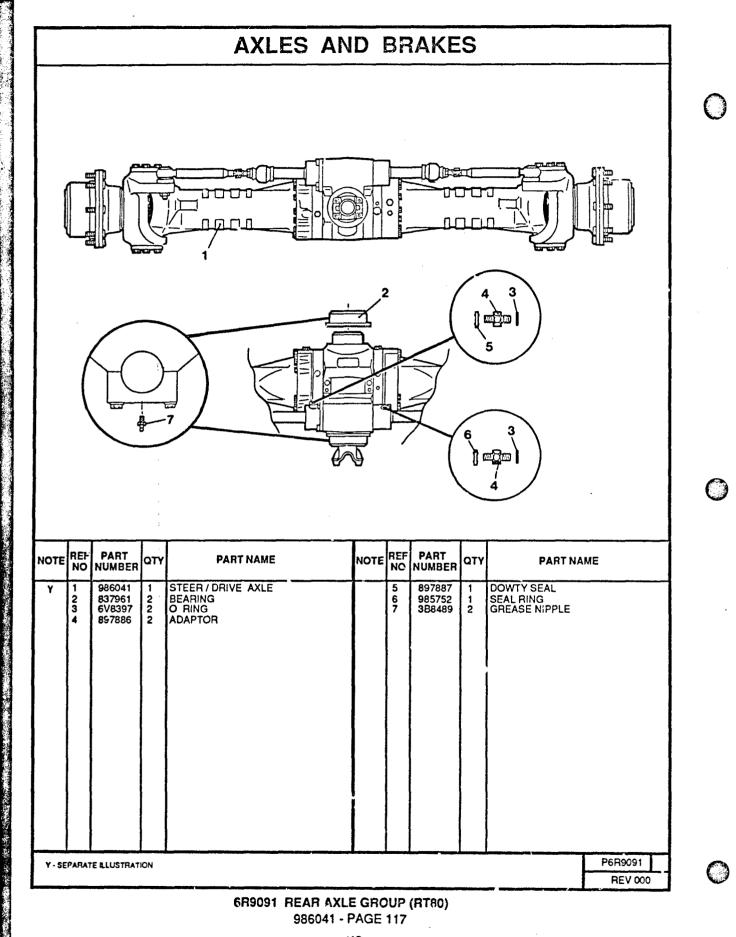




t = 1 + 1

. . .





. ...

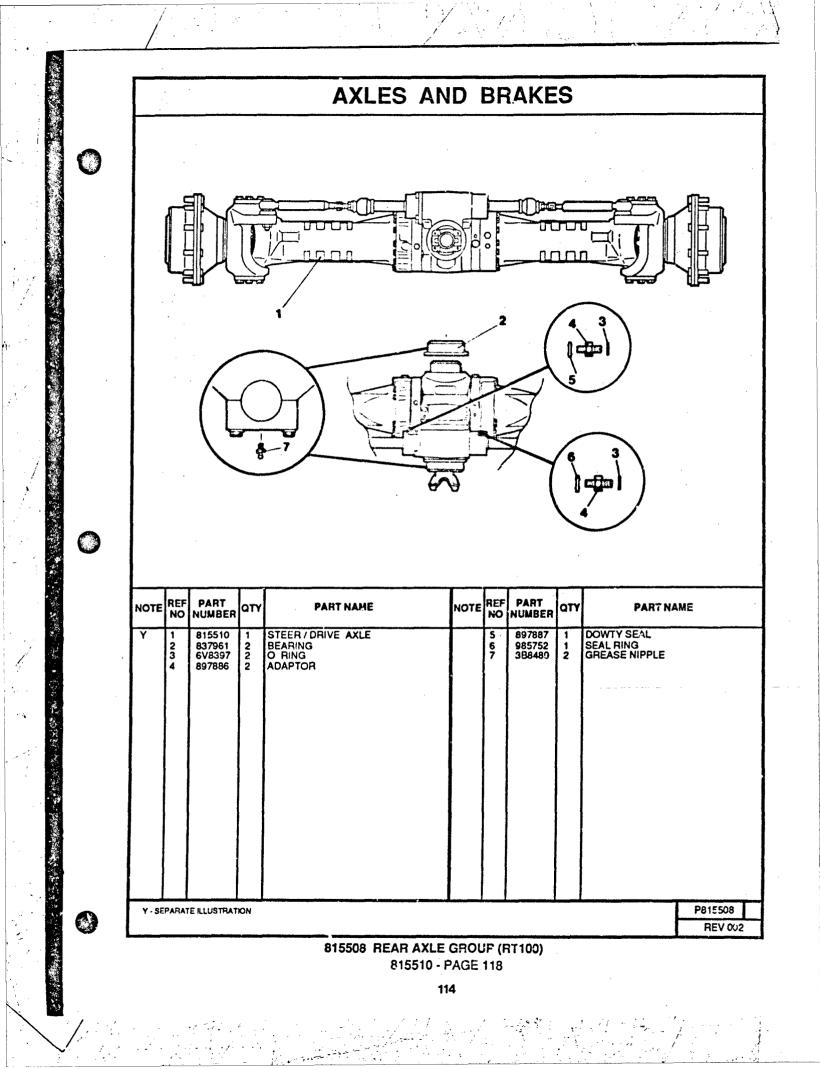
Section And the street

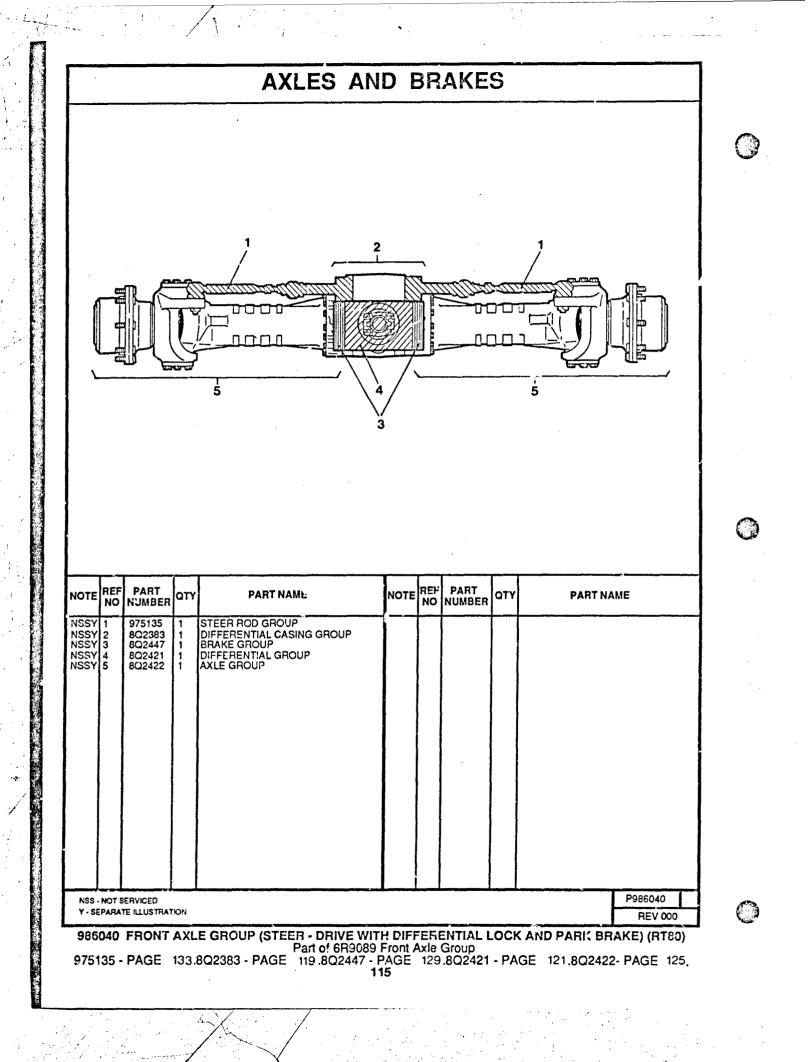
113

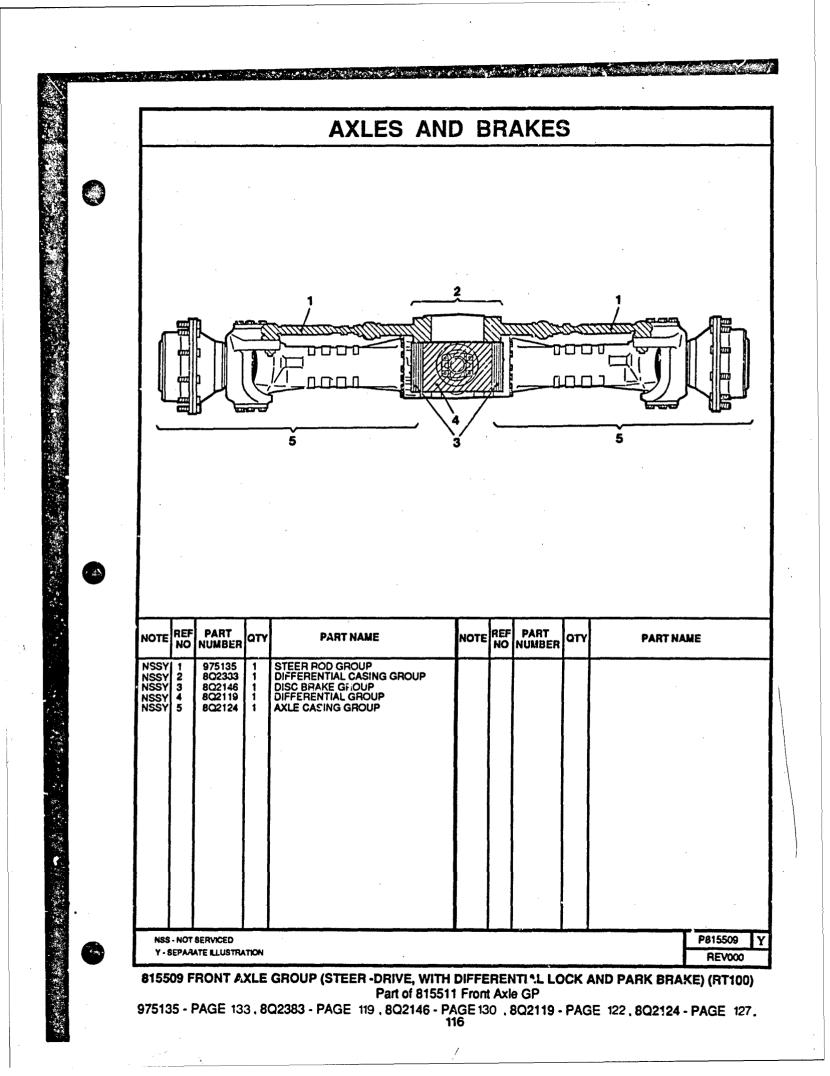
. . . .

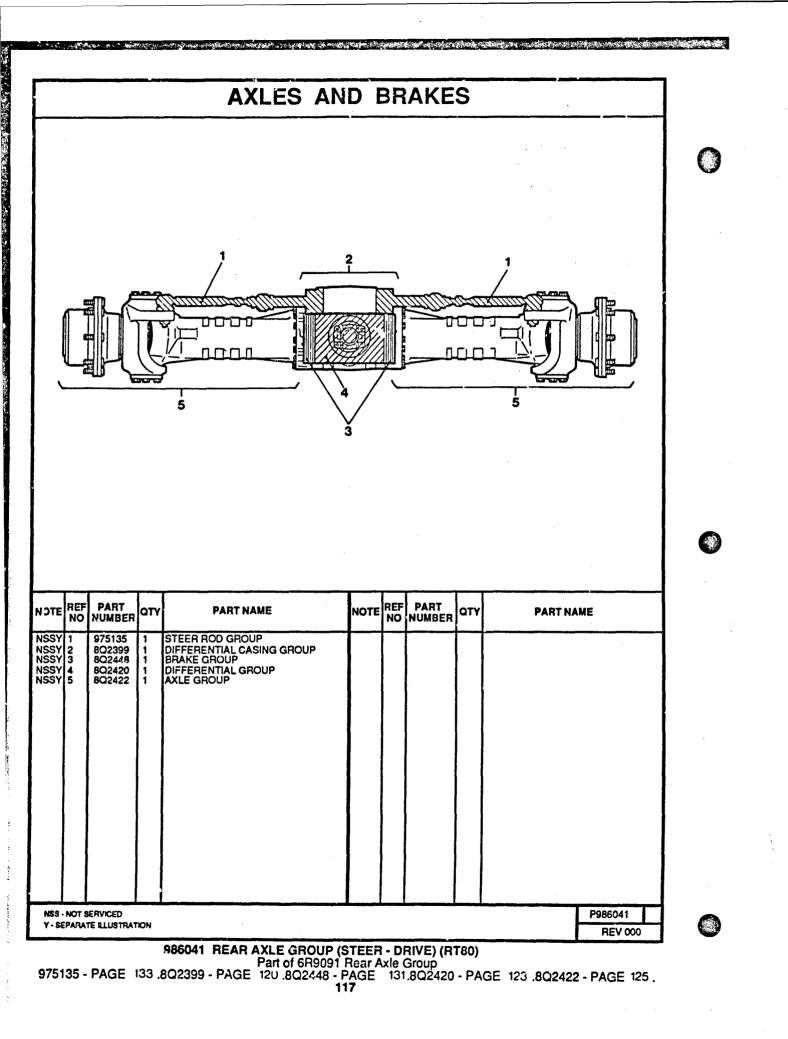
, ,

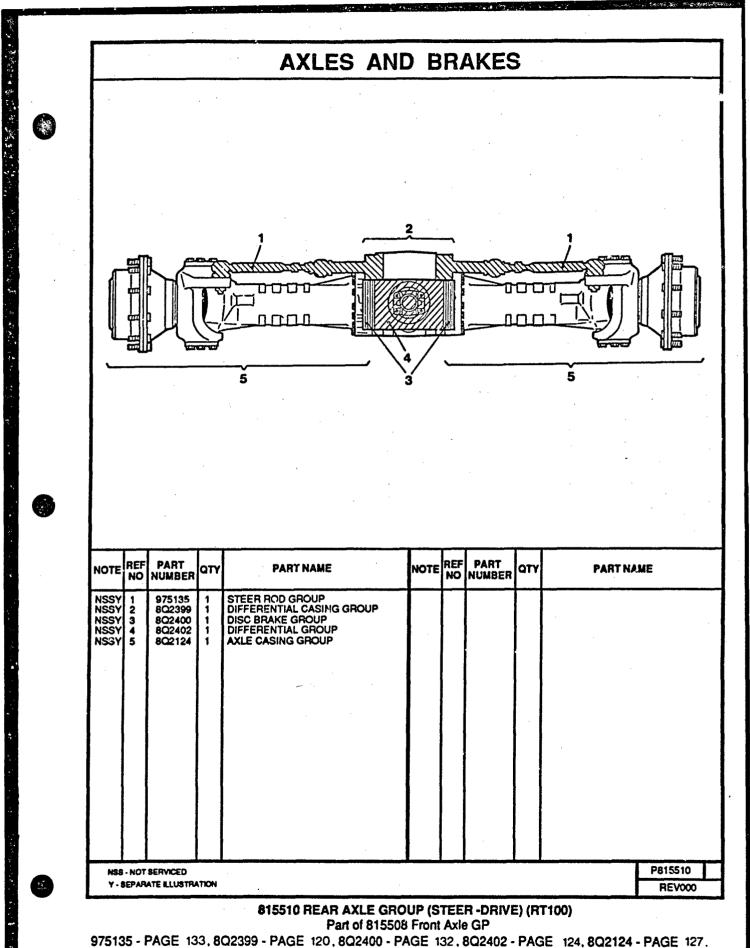
)

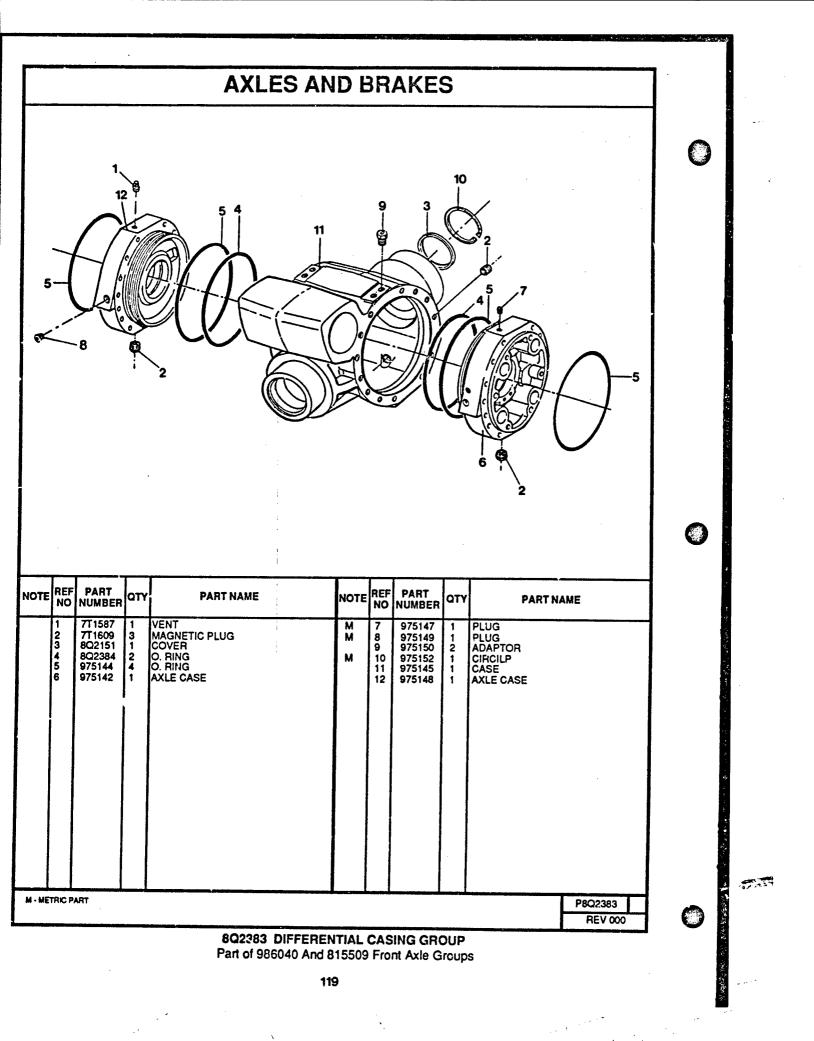


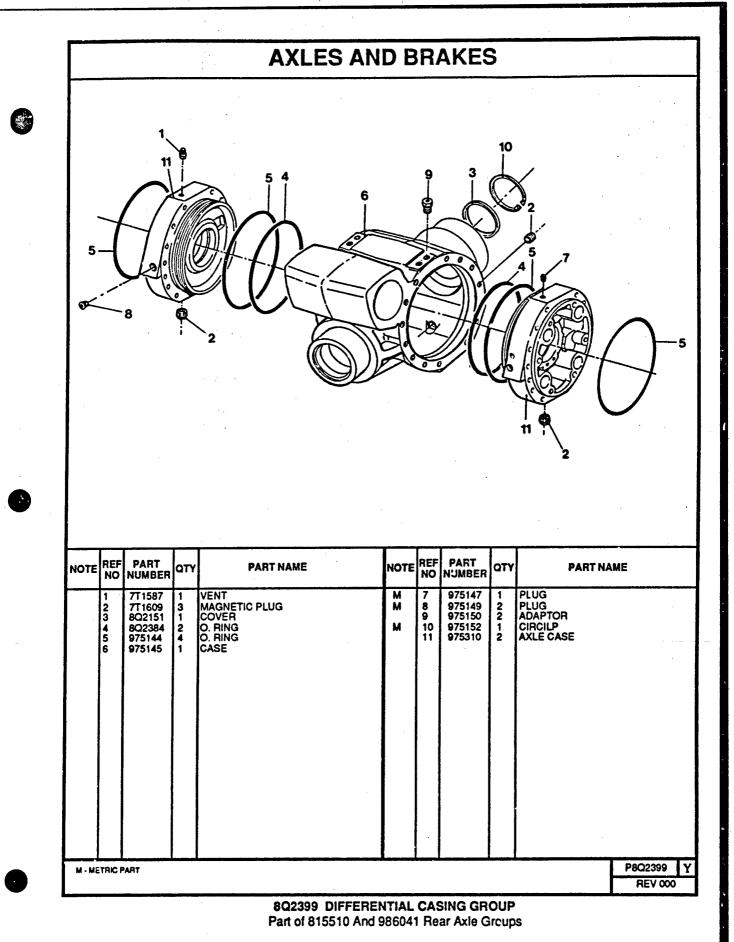


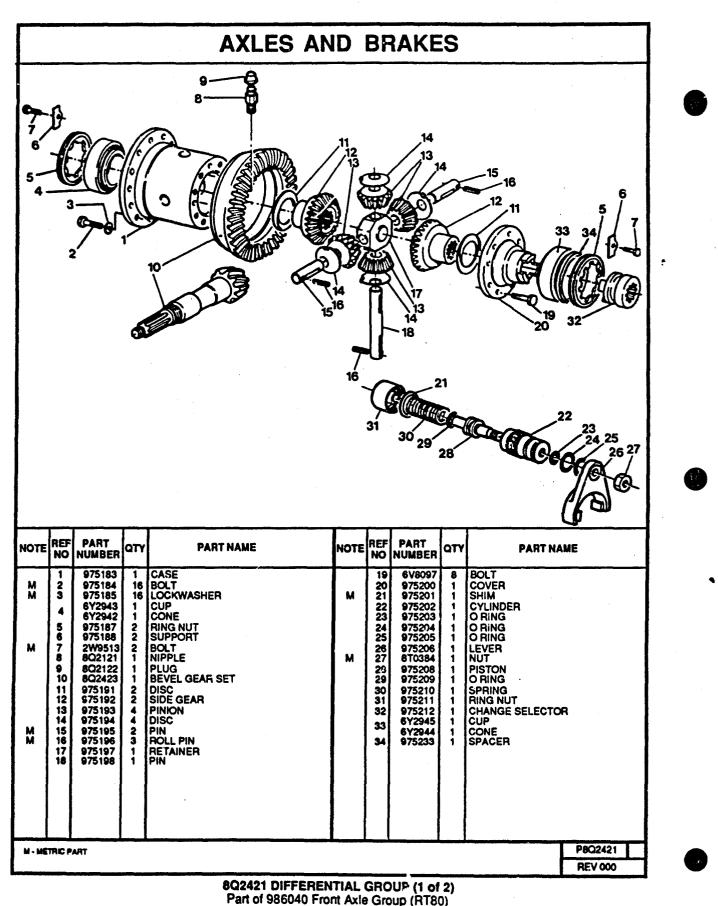






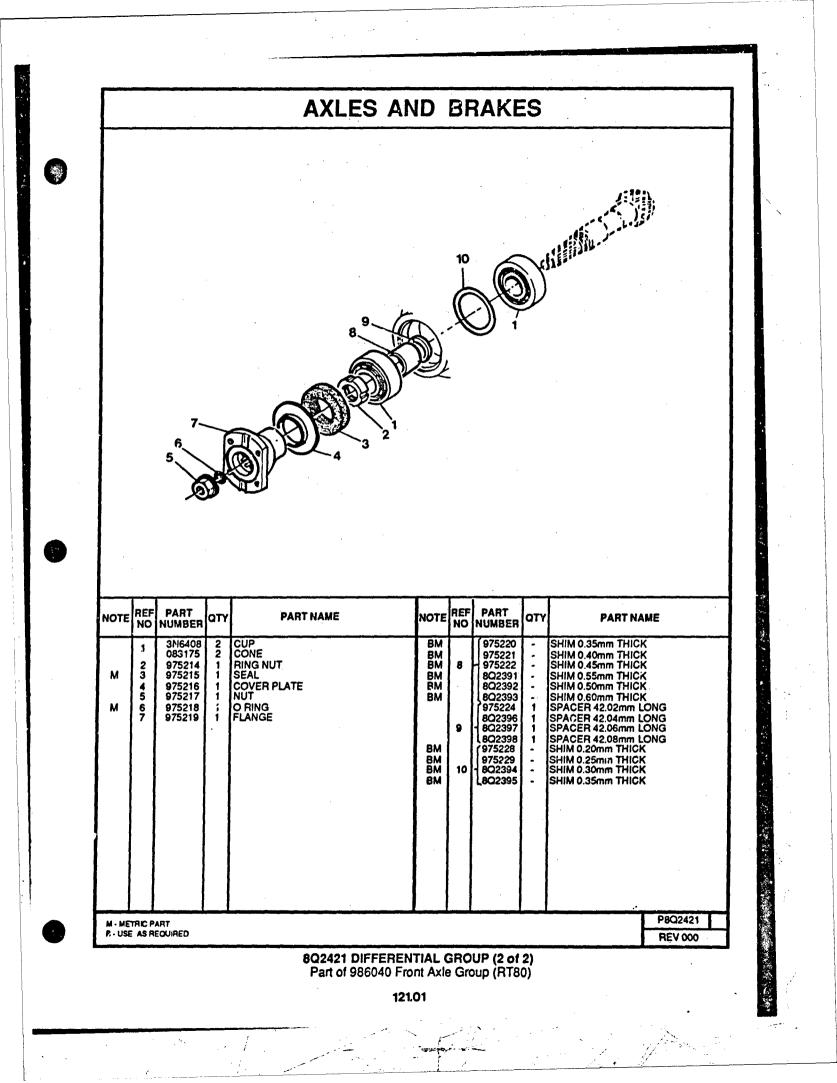


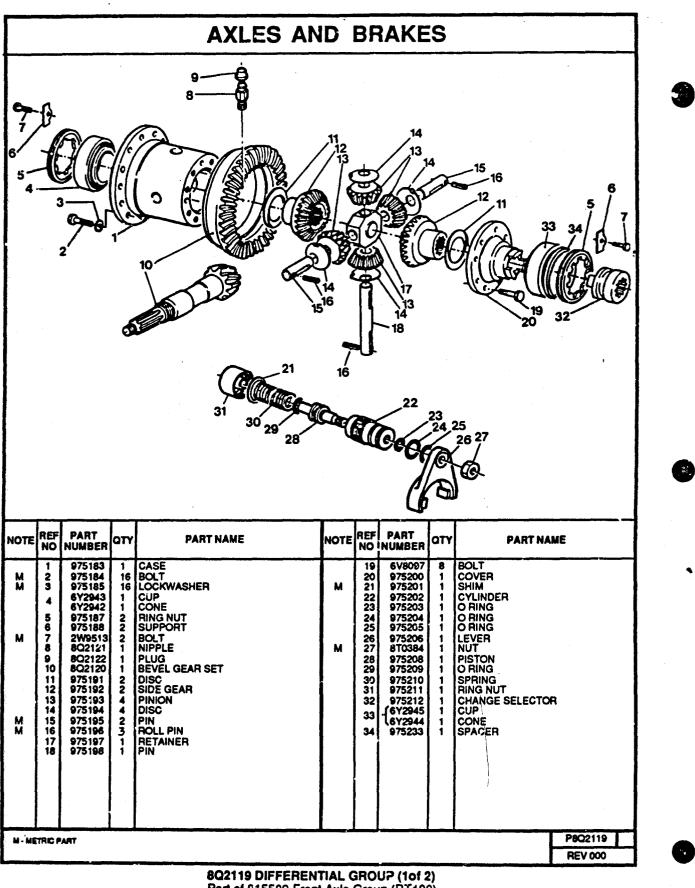




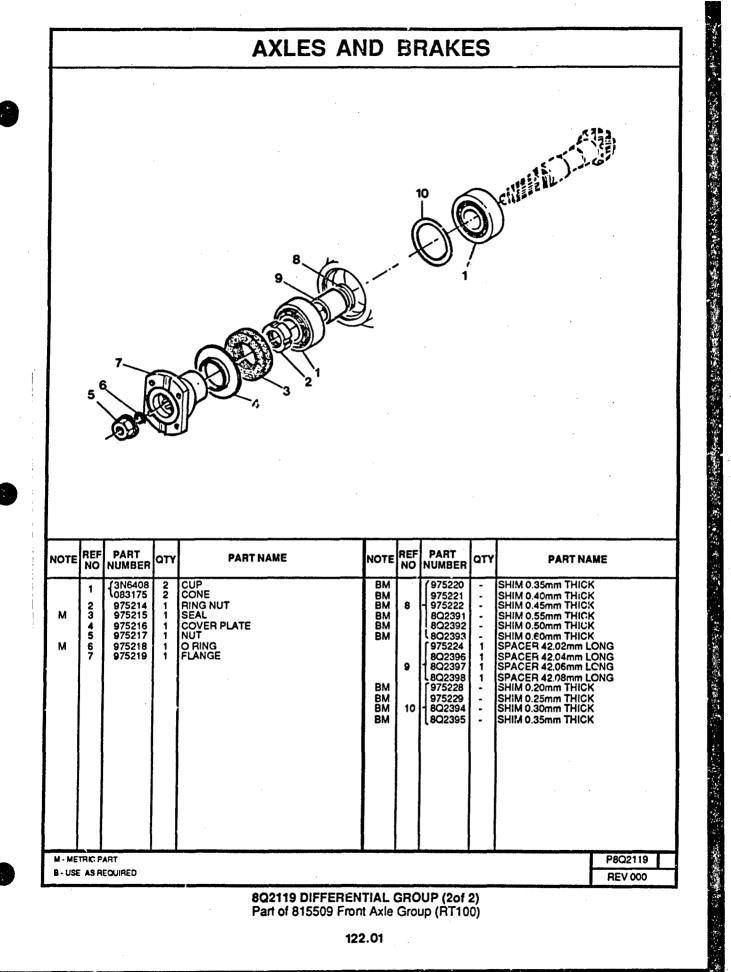


ماساندا المامكية بنها الالو



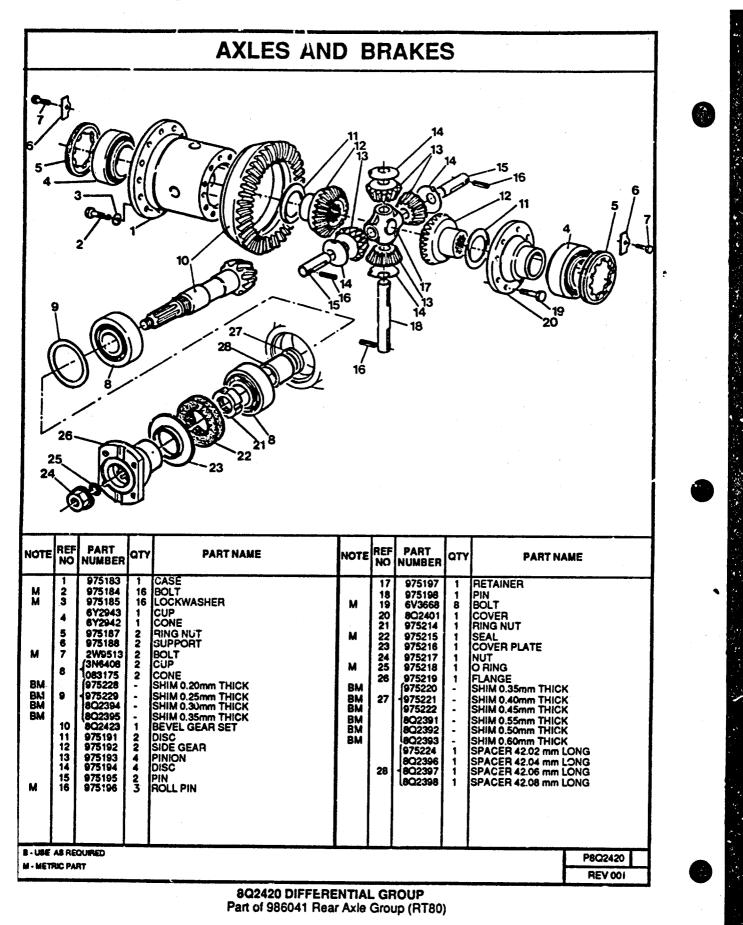


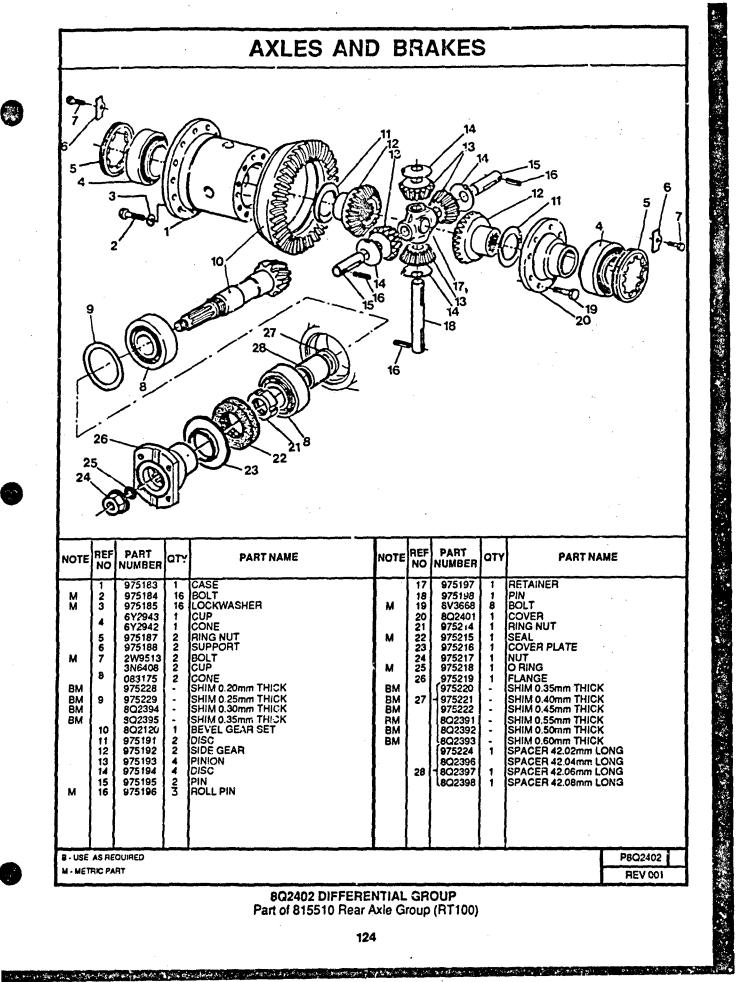
Part of 815509 Front Axle Group (RT100)



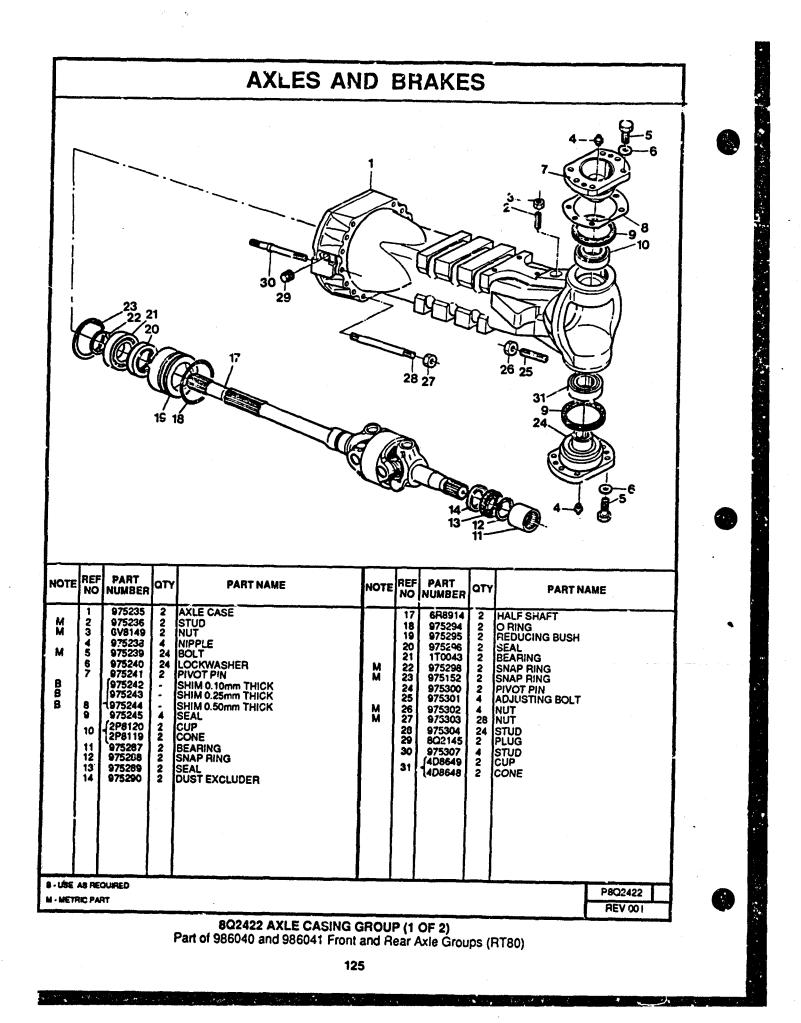
12.1

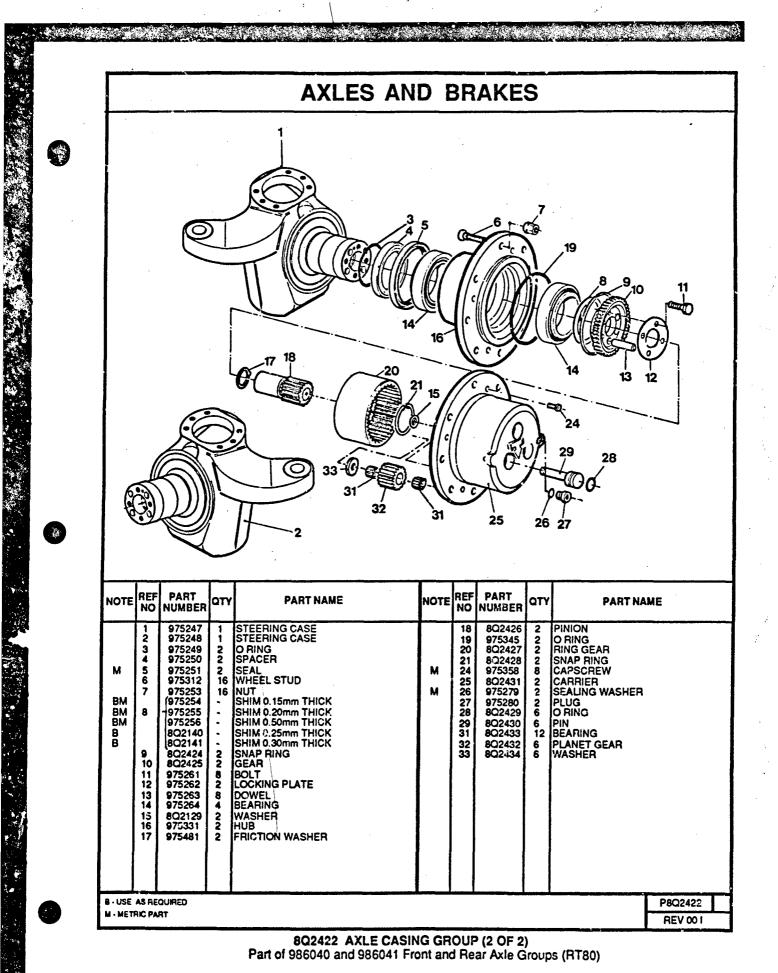
1.9

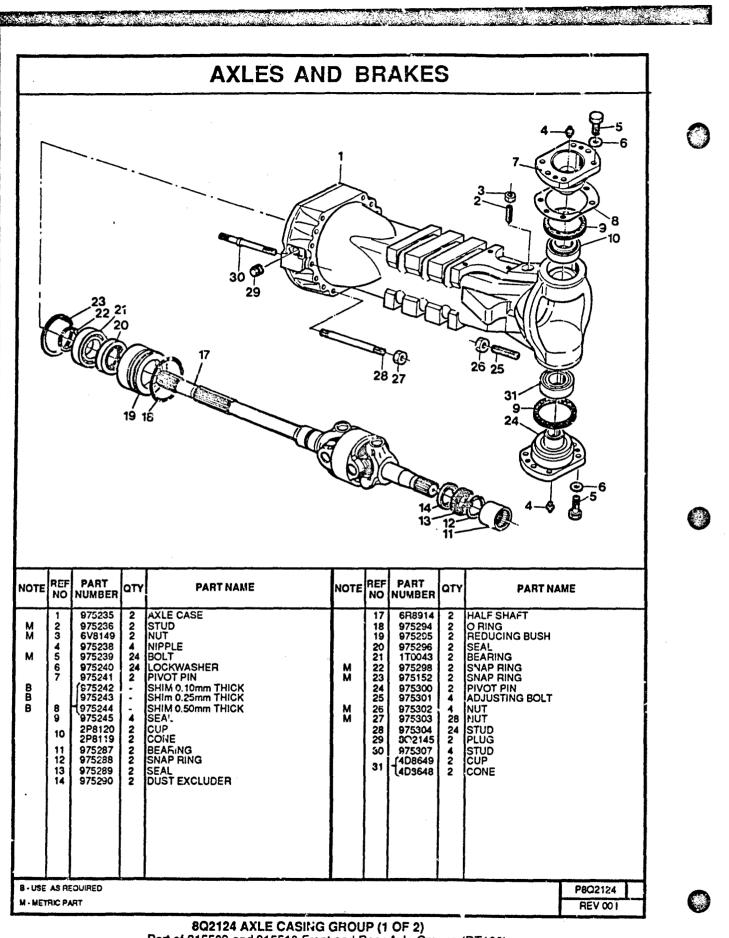




:

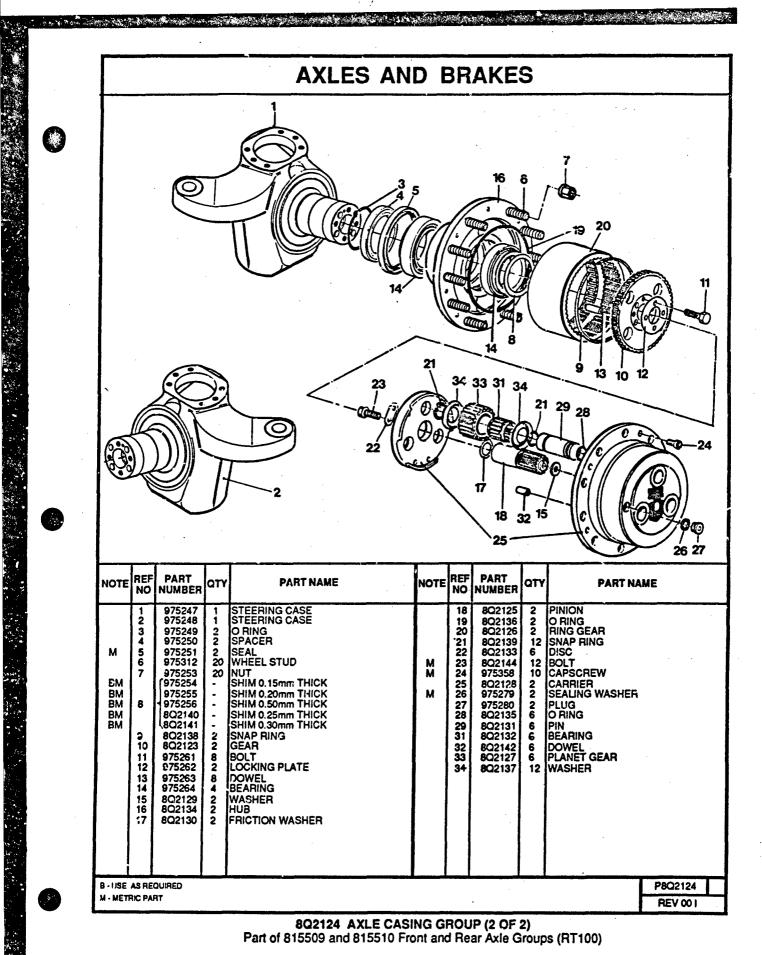


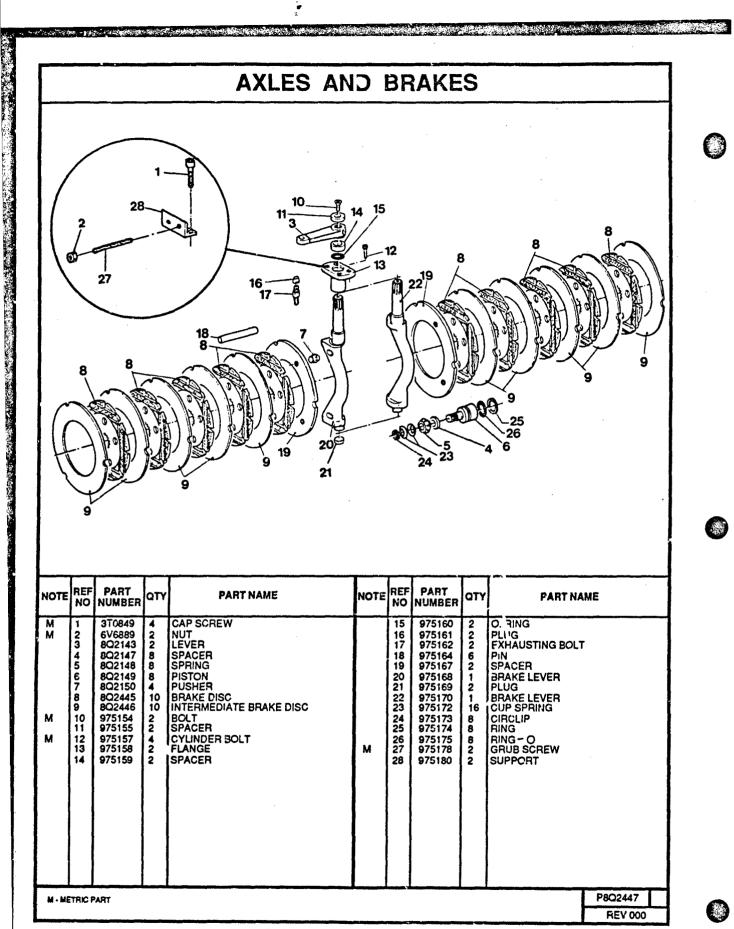




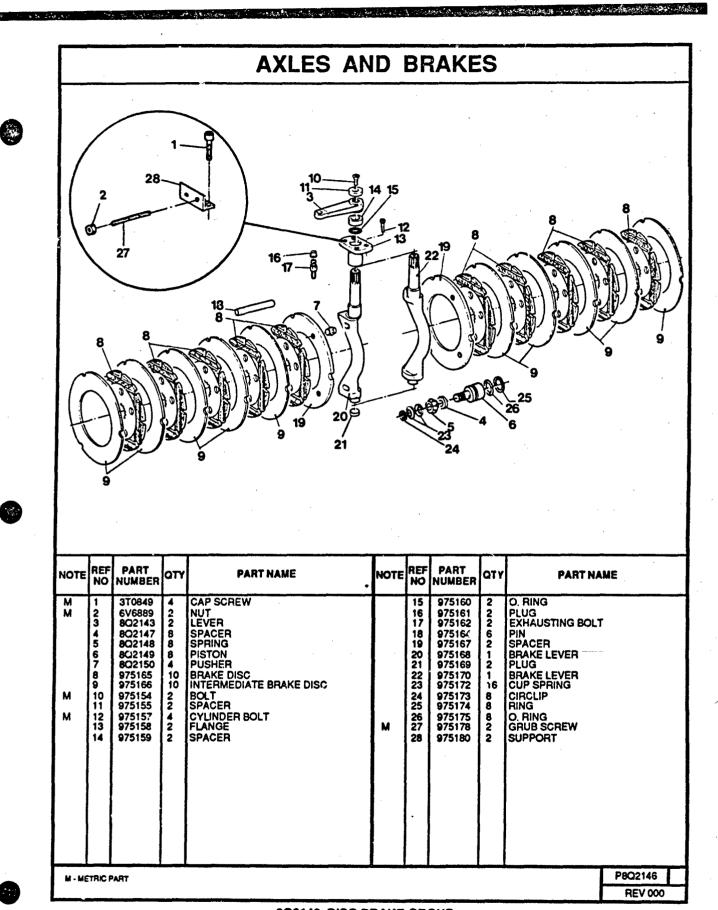
in the second

Part of 815509 and 815510 Front and Pear Axle Groups (RT100)





8Q2447 DISC BRAKE GROUP Part of 986040 Front Axle Group (RT80)

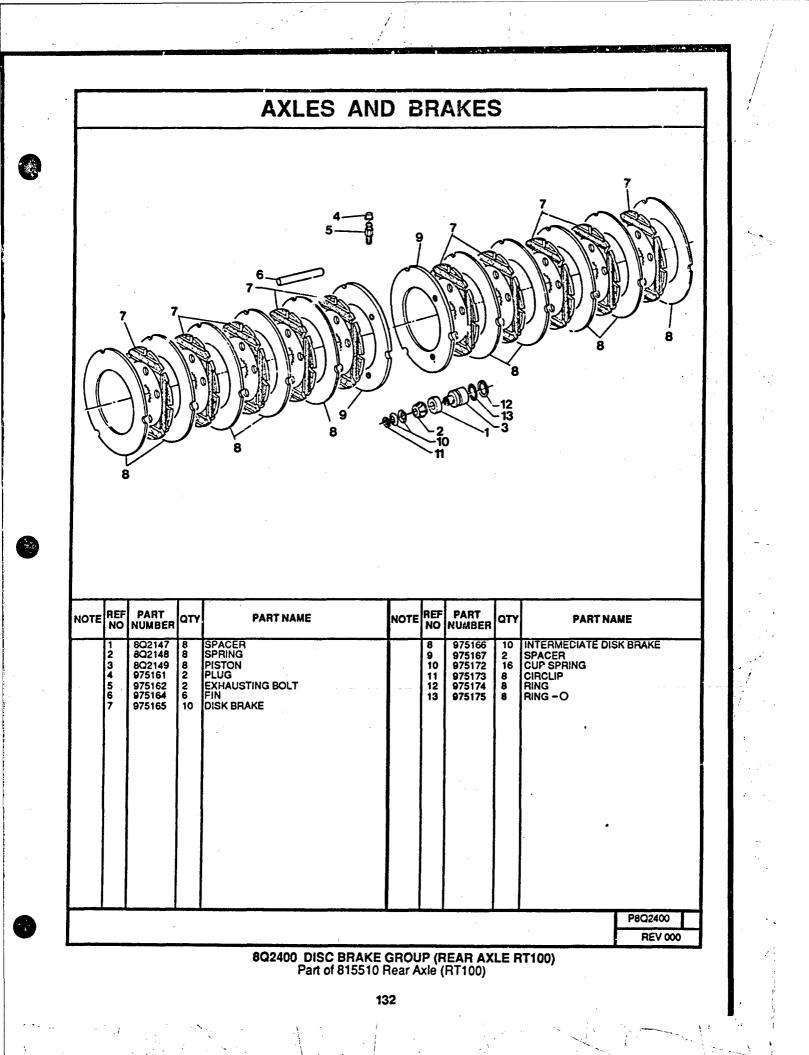


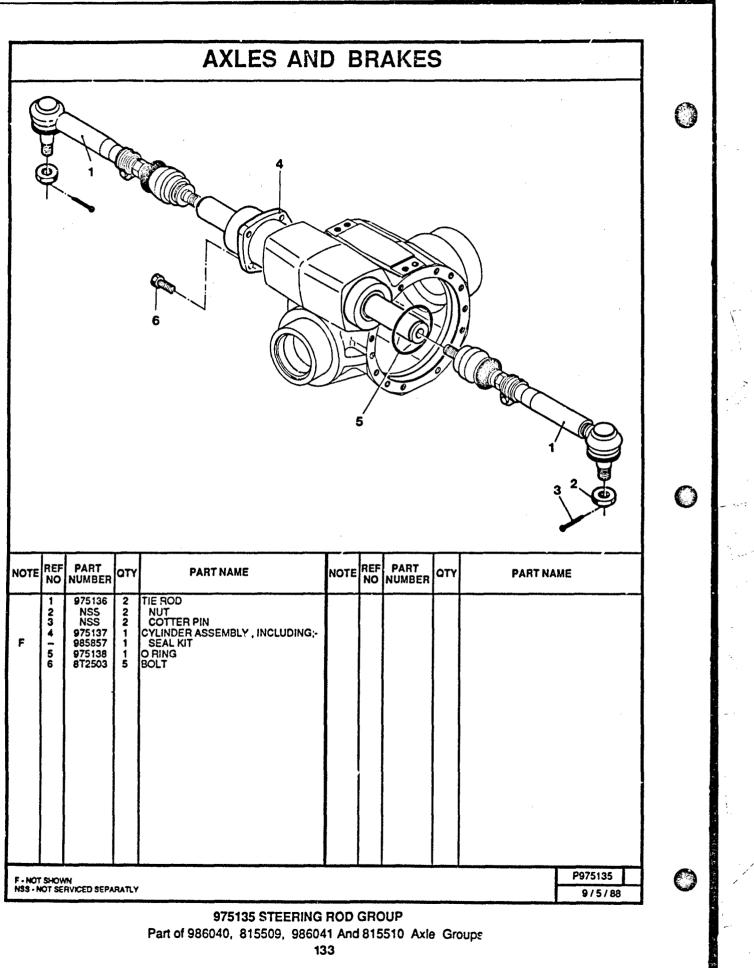


				AXLES /	AND	BR	AKE	5		
	7					9		All of the state	The second secon	
NOTE		PART		PART NAME	NOT		PART NUMBER	-13 -13	PART NAME	
	1 2 3 4 5 6 7	8Q2149 975161 975162 975164	8 2 2 6	SPACER SPRING PISTON PLUG EXHAUSTING BOLT PIN DISK BRAKE		8 9 10 11 12 13	8Q2446 975167 975172 975173 975174 975175	2 16 8 8	INTERMEDIATE DISK BRAKE SPACER CUP SPRING CIRCLIP RING RING - O	
									P8Q2448	

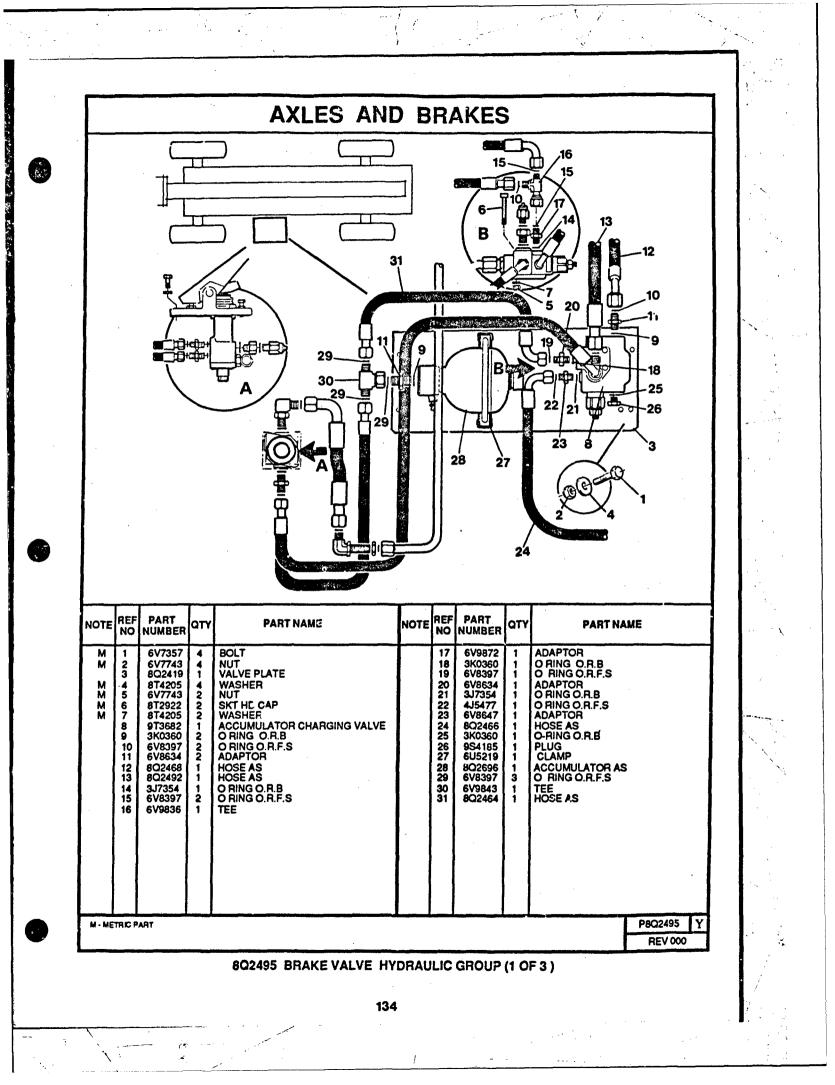


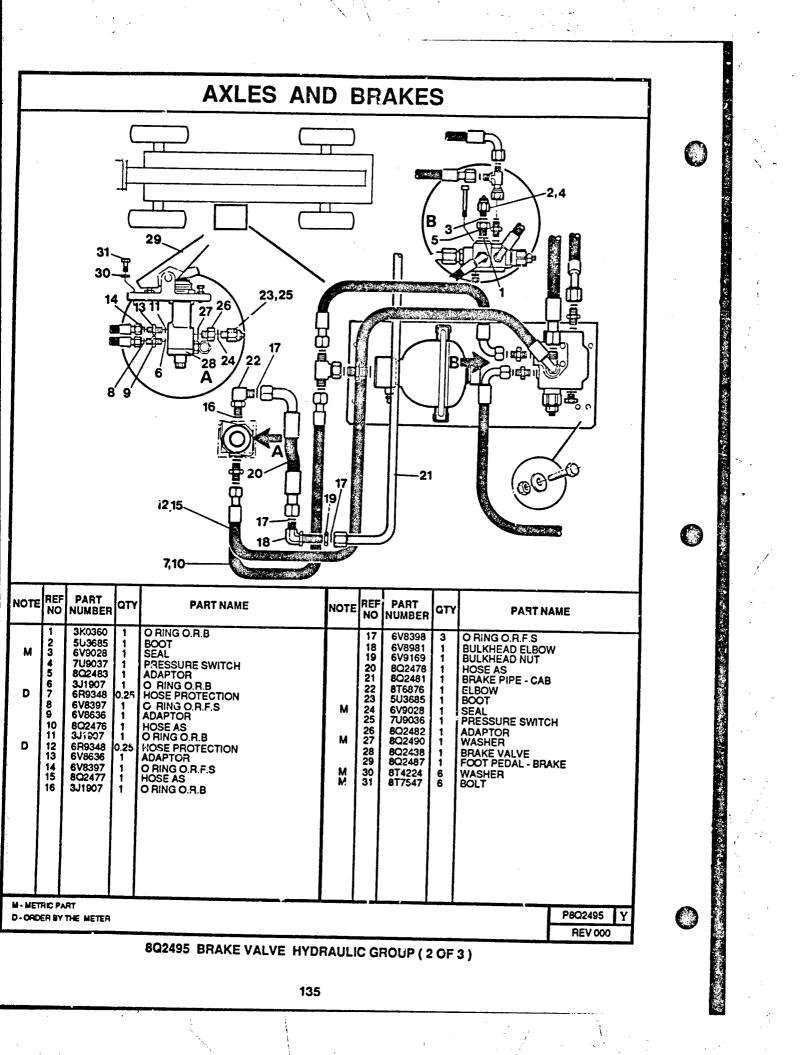
.

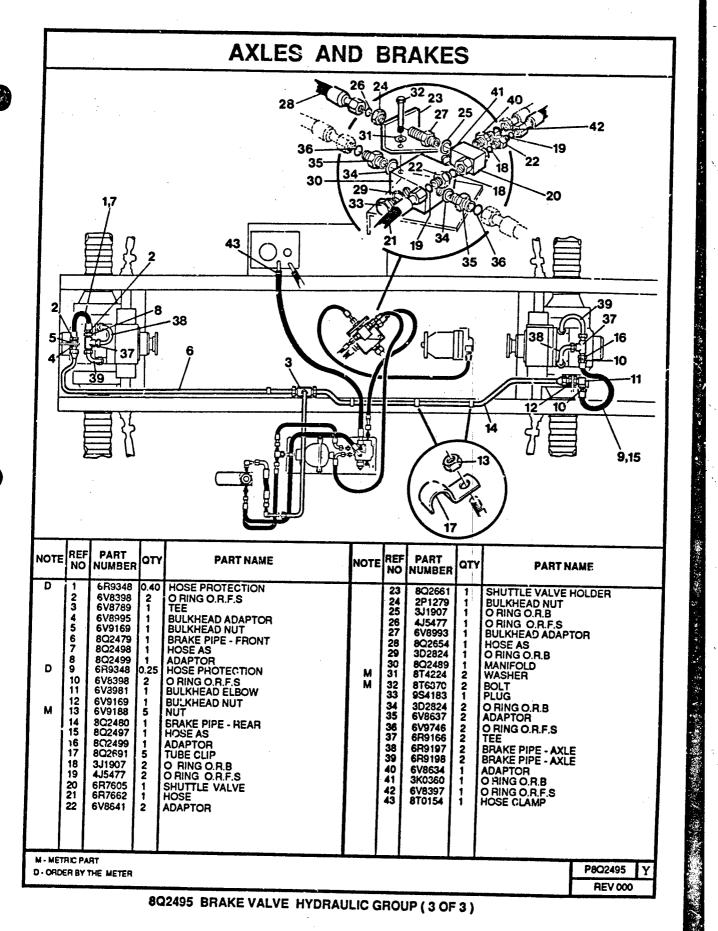




`:

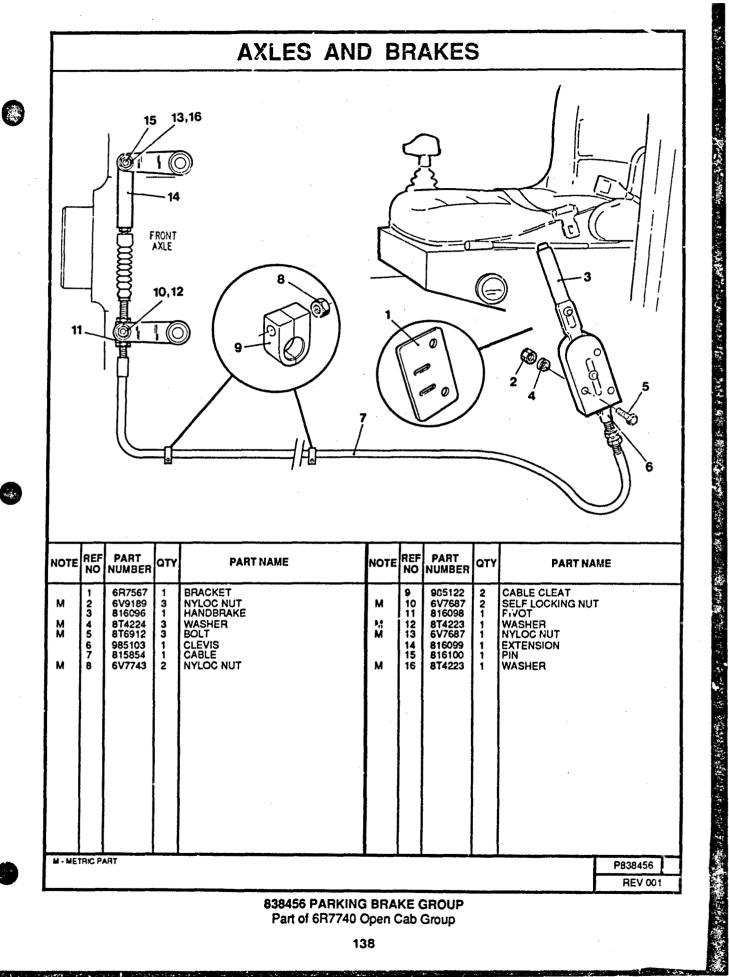


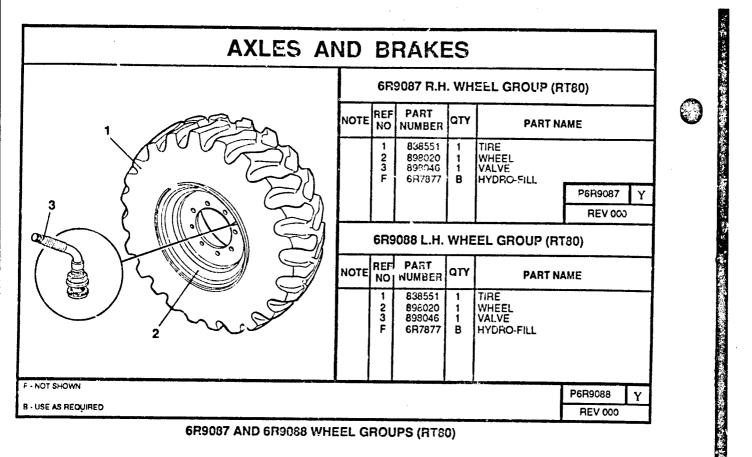




 MEMORANDUM	
	Ο
	1000 - 10000 - 10000 - 1000 - 1000 - 1000 - 1000 - 1000 - 1000 - 1000 -
 MEMORANDU 137	

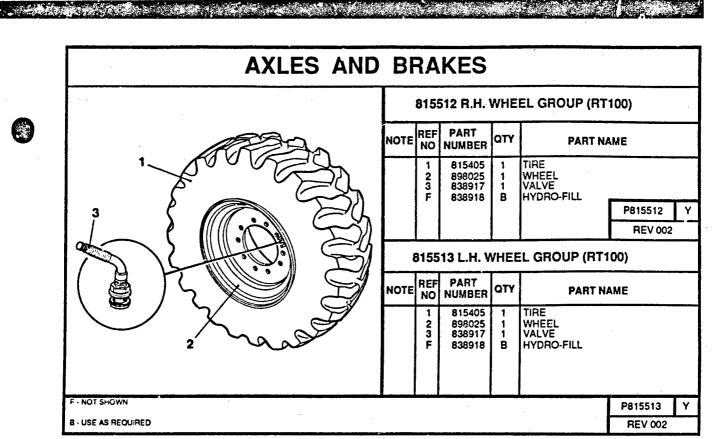
11 - 11



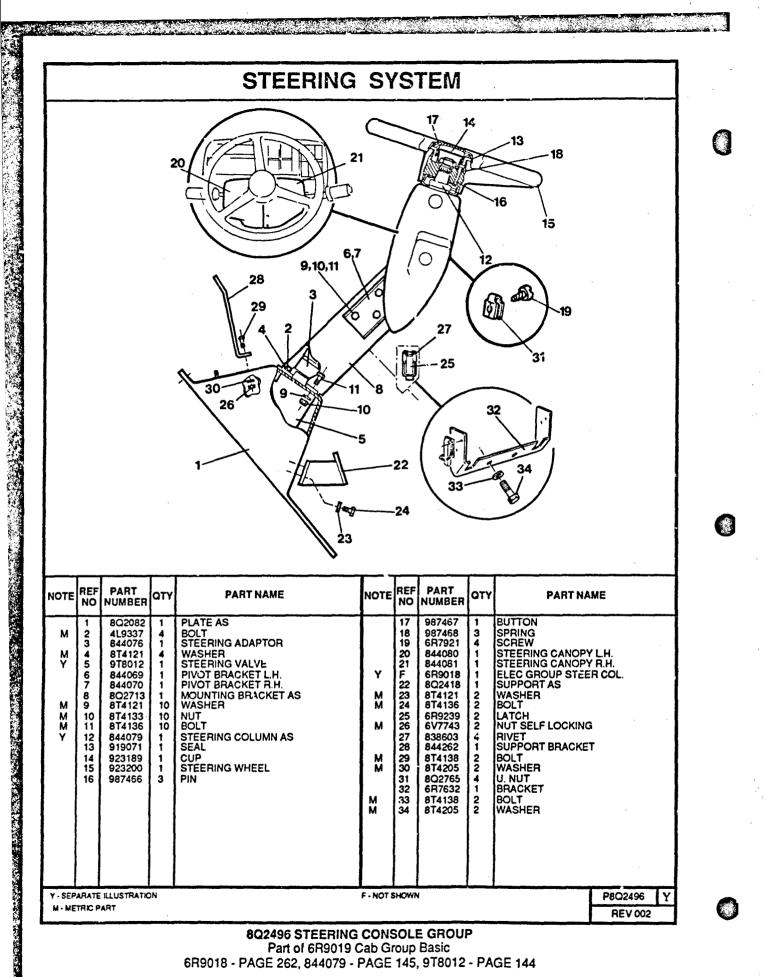


The state of the s

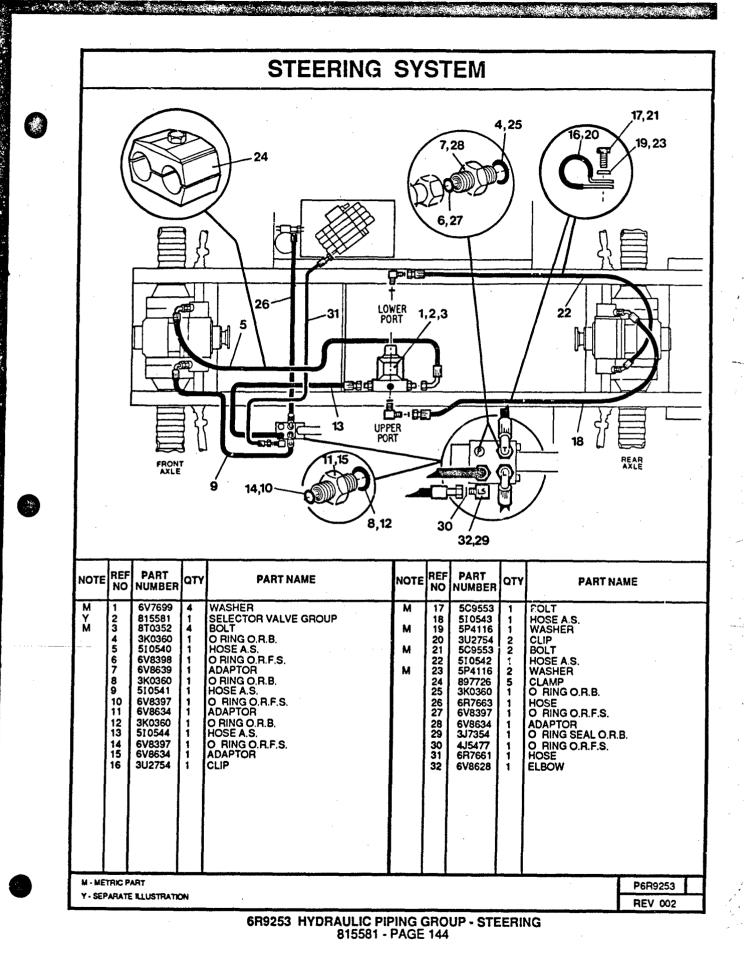
ないです。そうないで、



815512 AND 815513 WHEEL GROUPS (RT100)



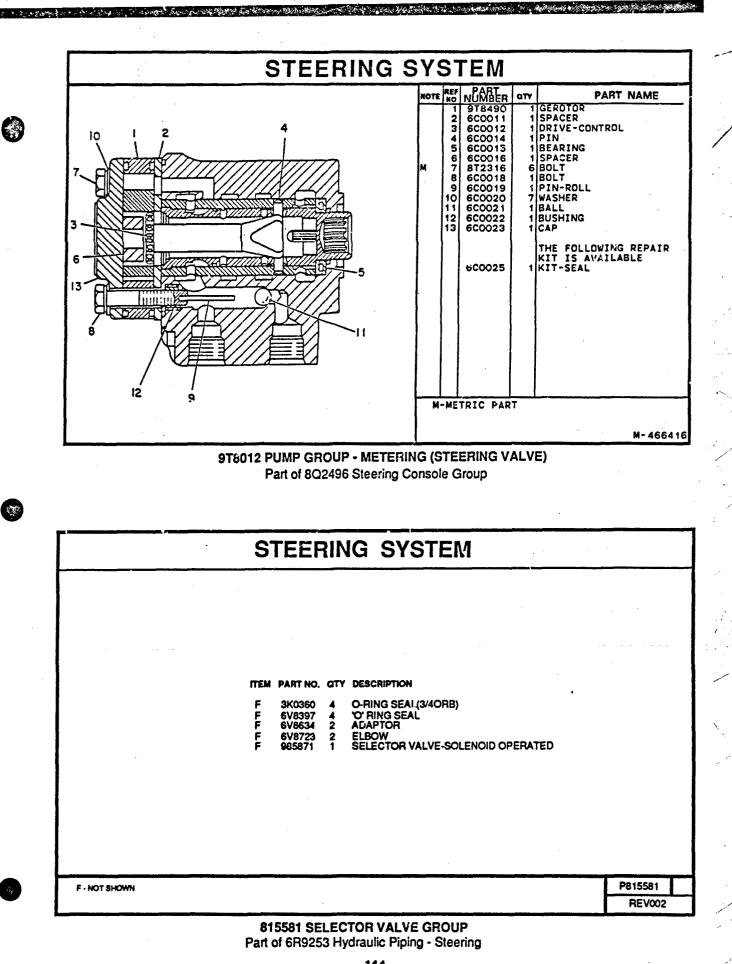
1-4



Ĩ

A CAN PROVIDE AND

<u></u>	MEN	IORANDUM		
- - -				
	ŕ			
				۲
			 MEMORANDUM	

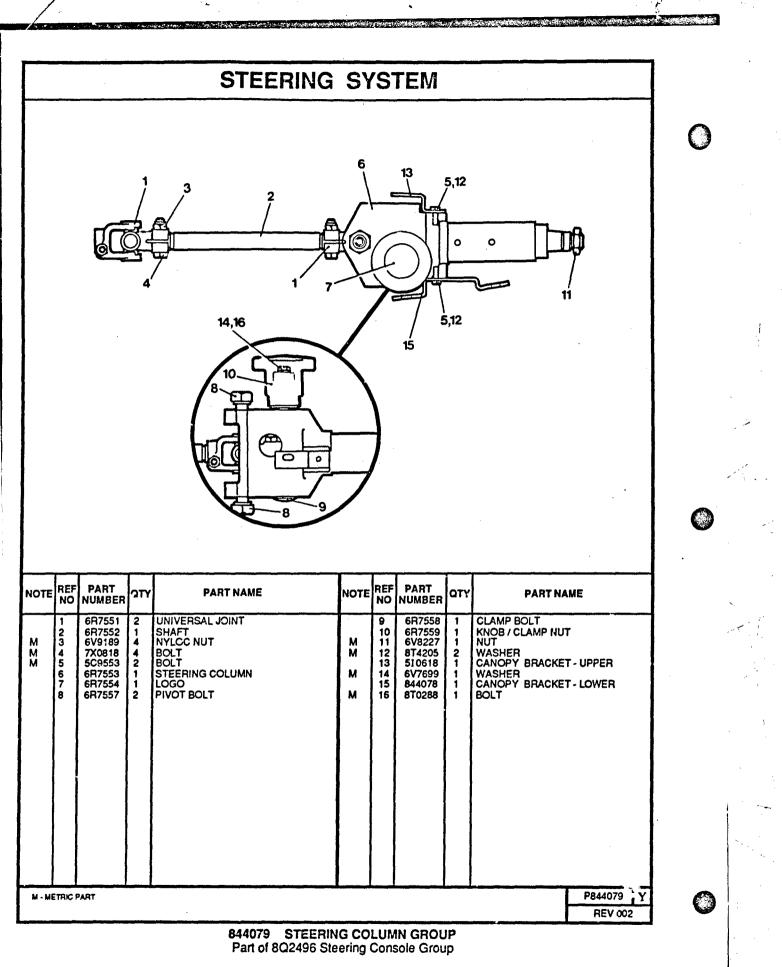


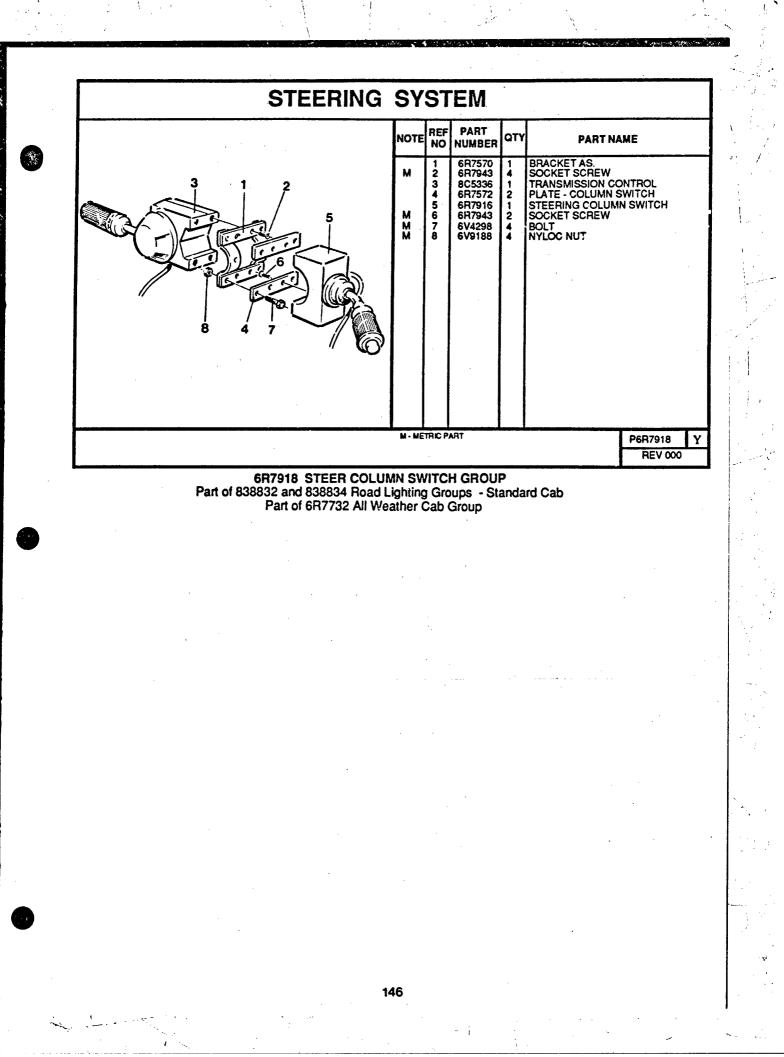
.

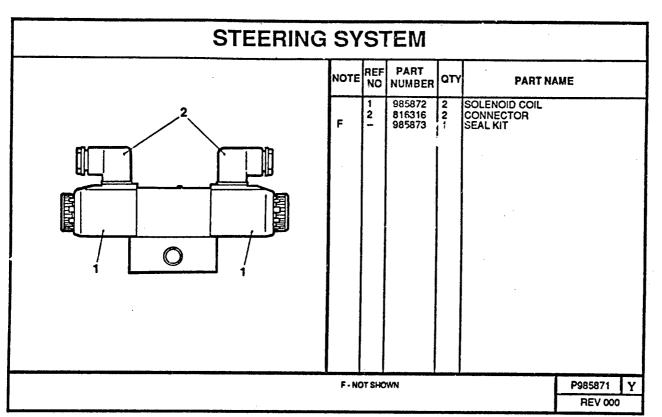
State State State

144

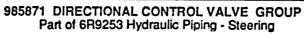
di la

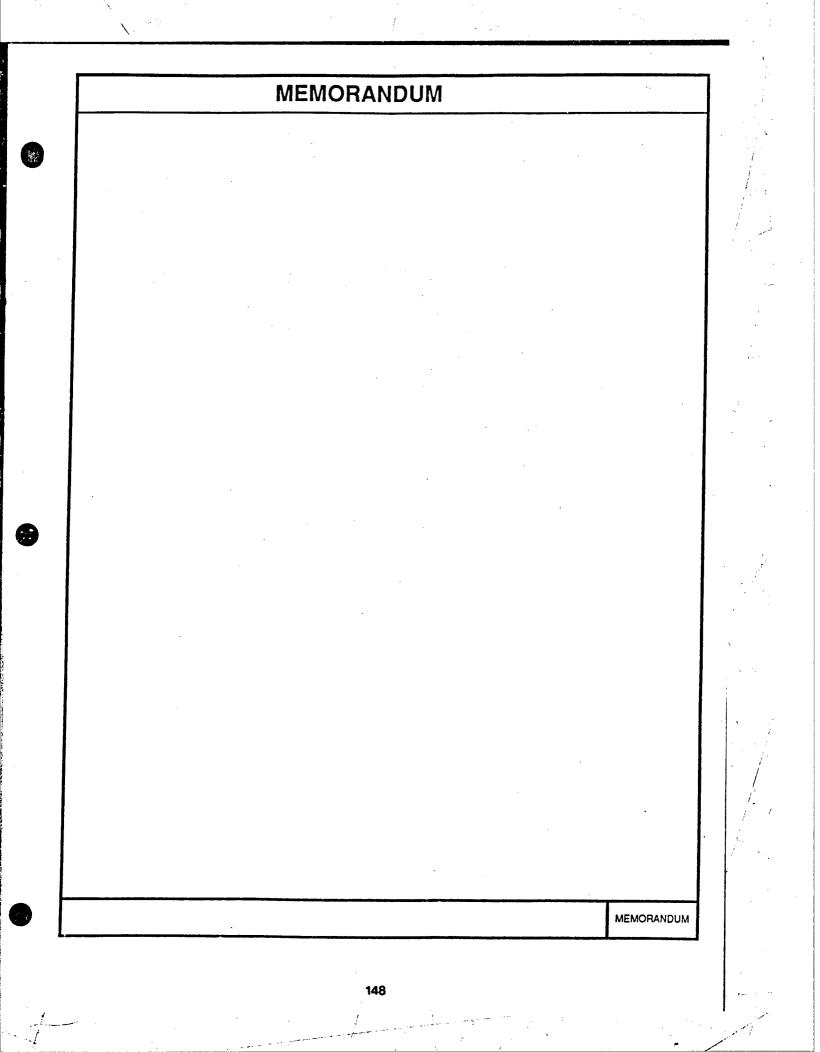


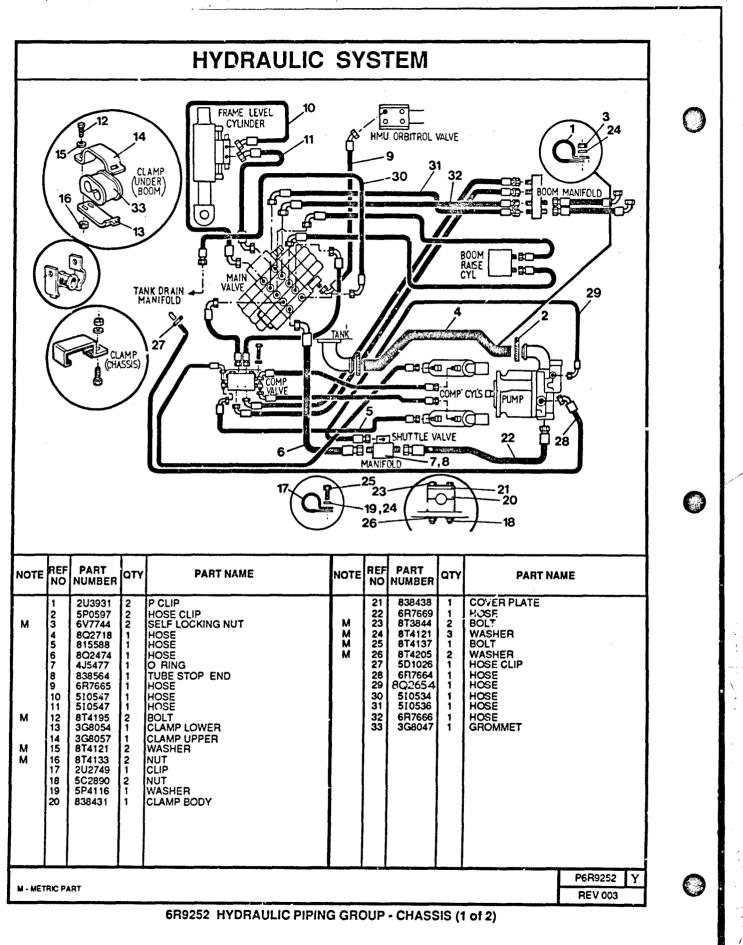


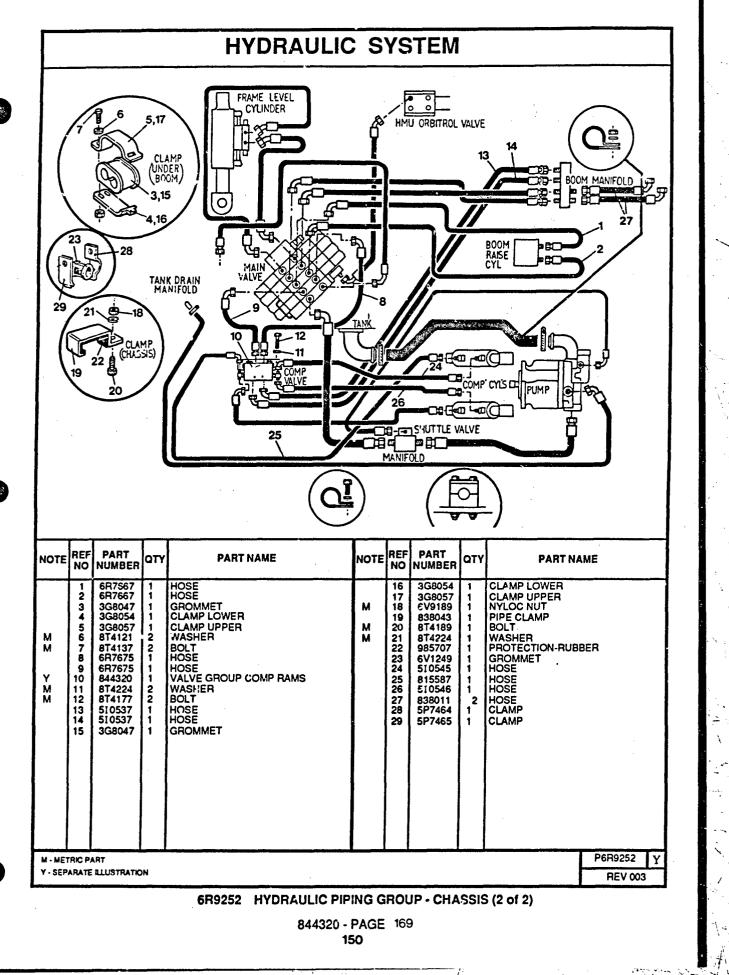


Martin C.





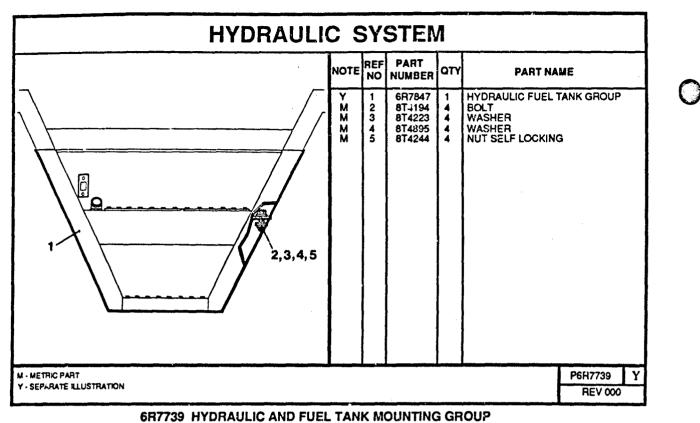




Ë

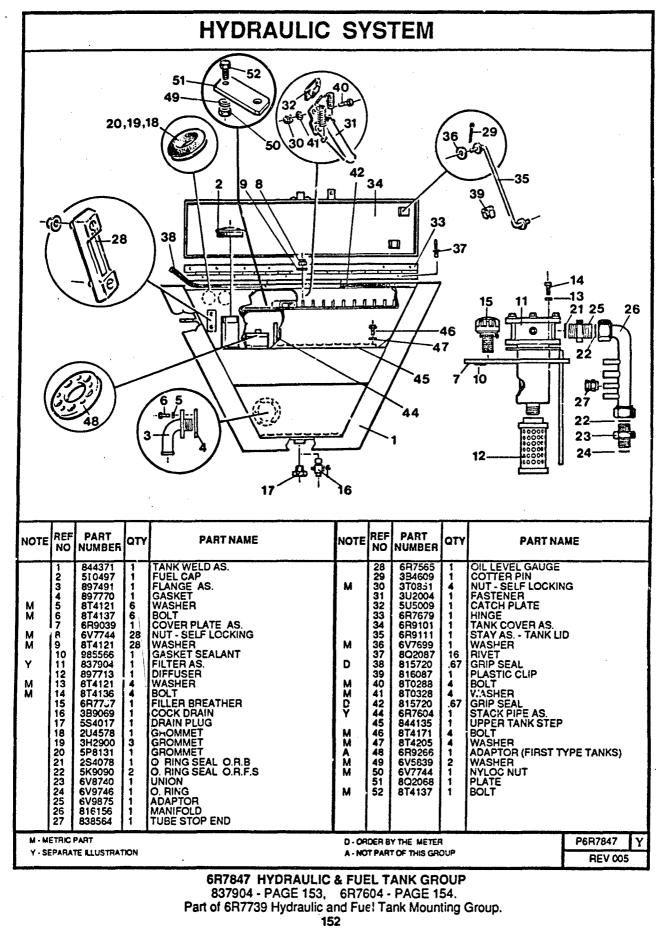
-

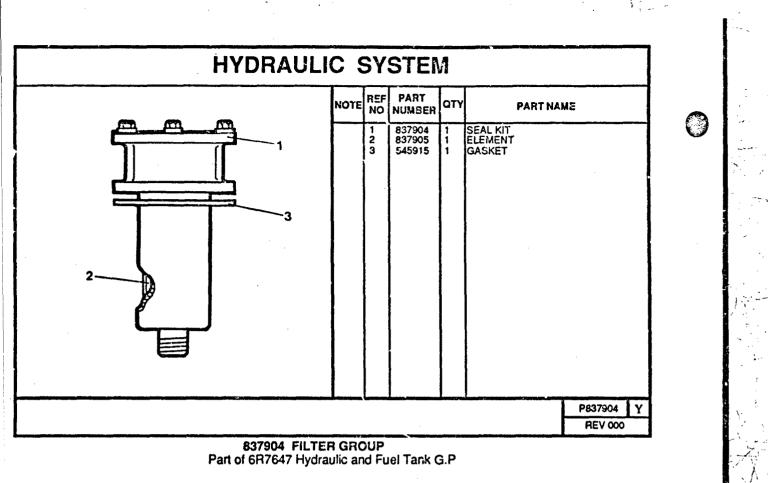
.



DRAULIC AND FUEL TANK MOUNTING 6R7847 - PAGE 152

> ala Nga



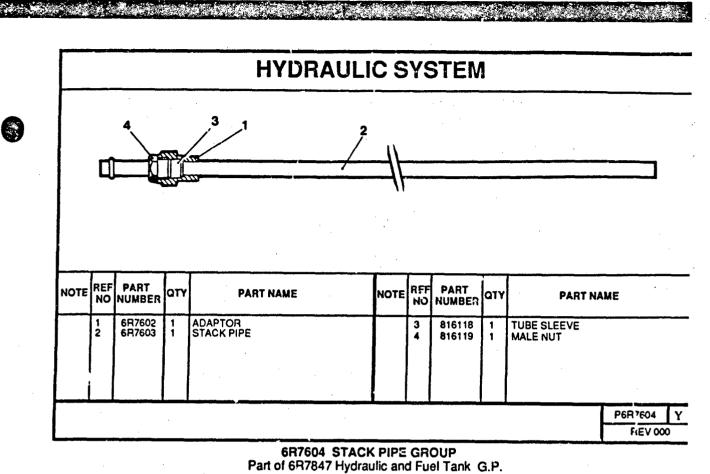


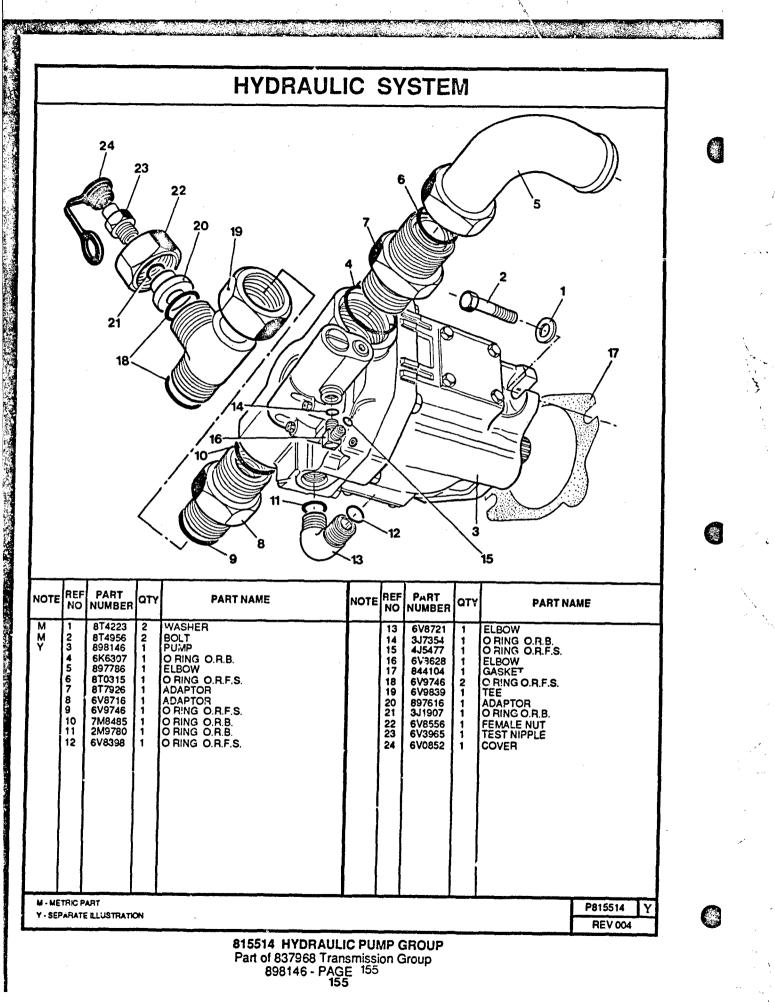
Y.

9

153 A STATE OF A STATE OF A

The second state of the second s

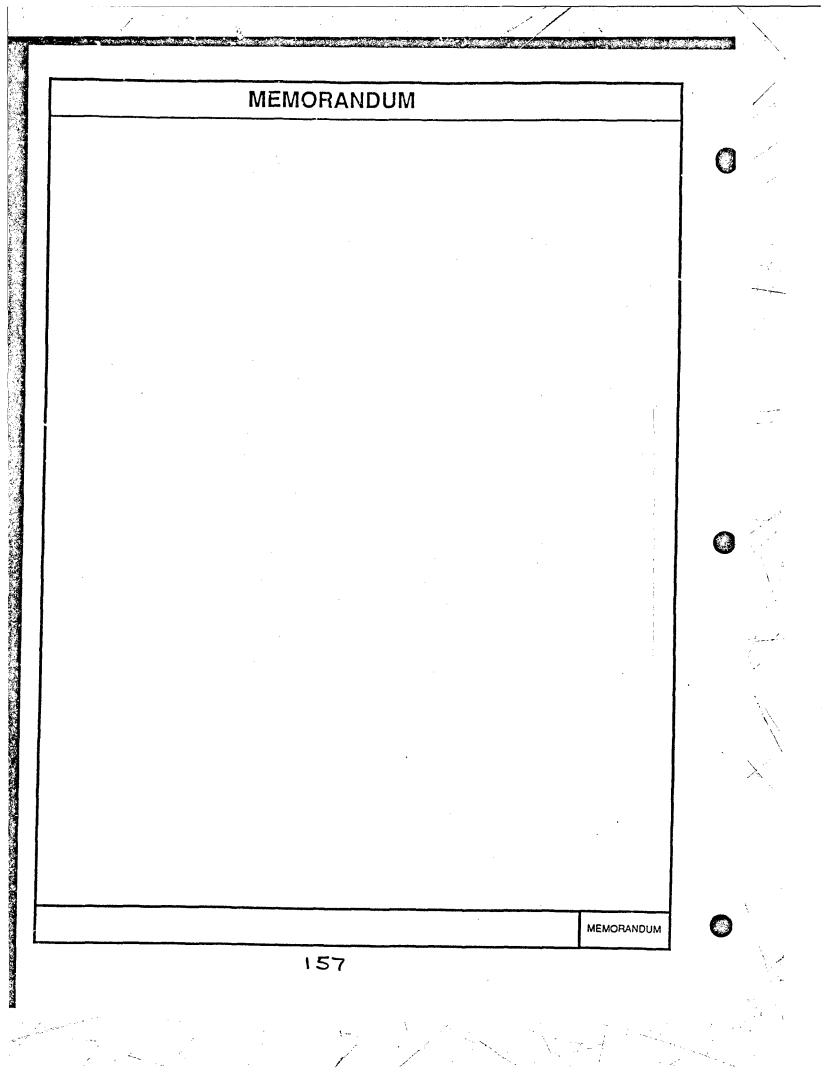


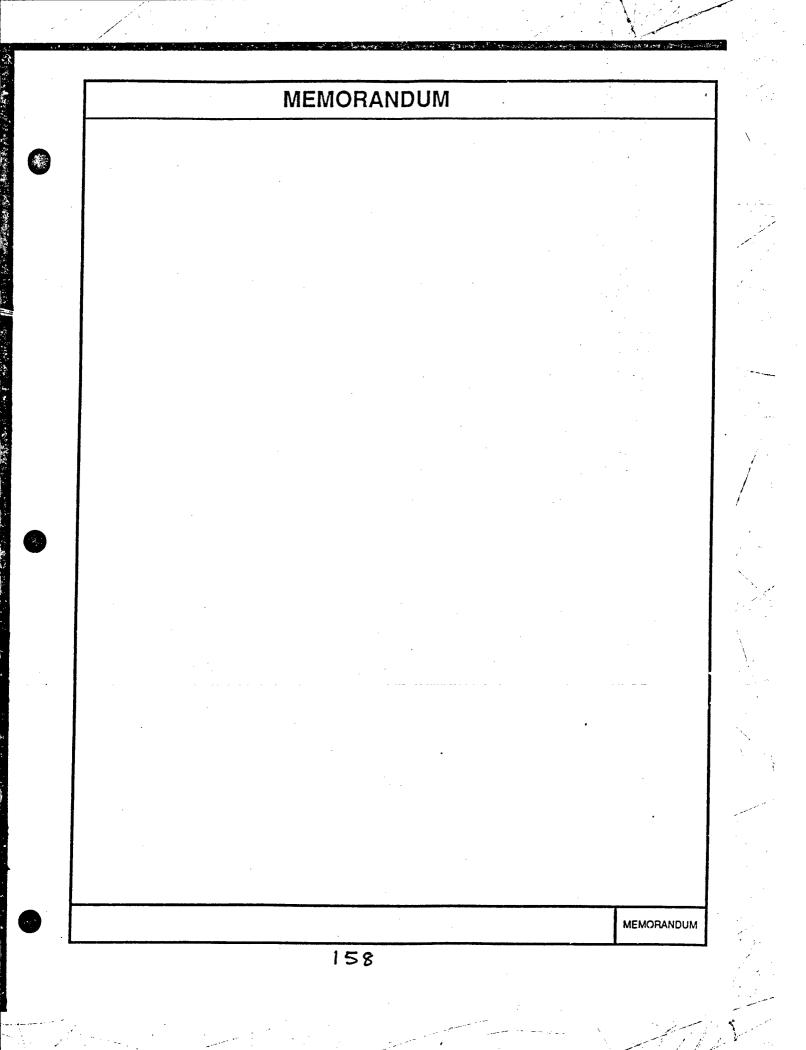


......

MEMORANDUM

MEMORANDUM

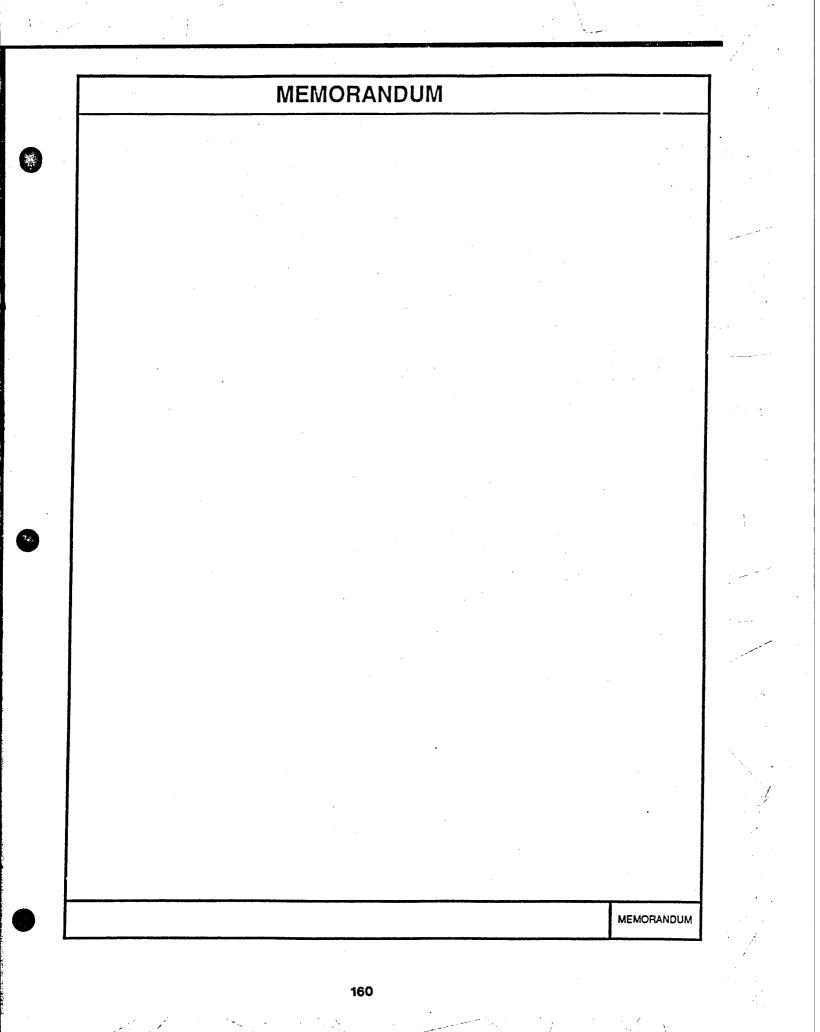




HYDRAULIC SYSTEM

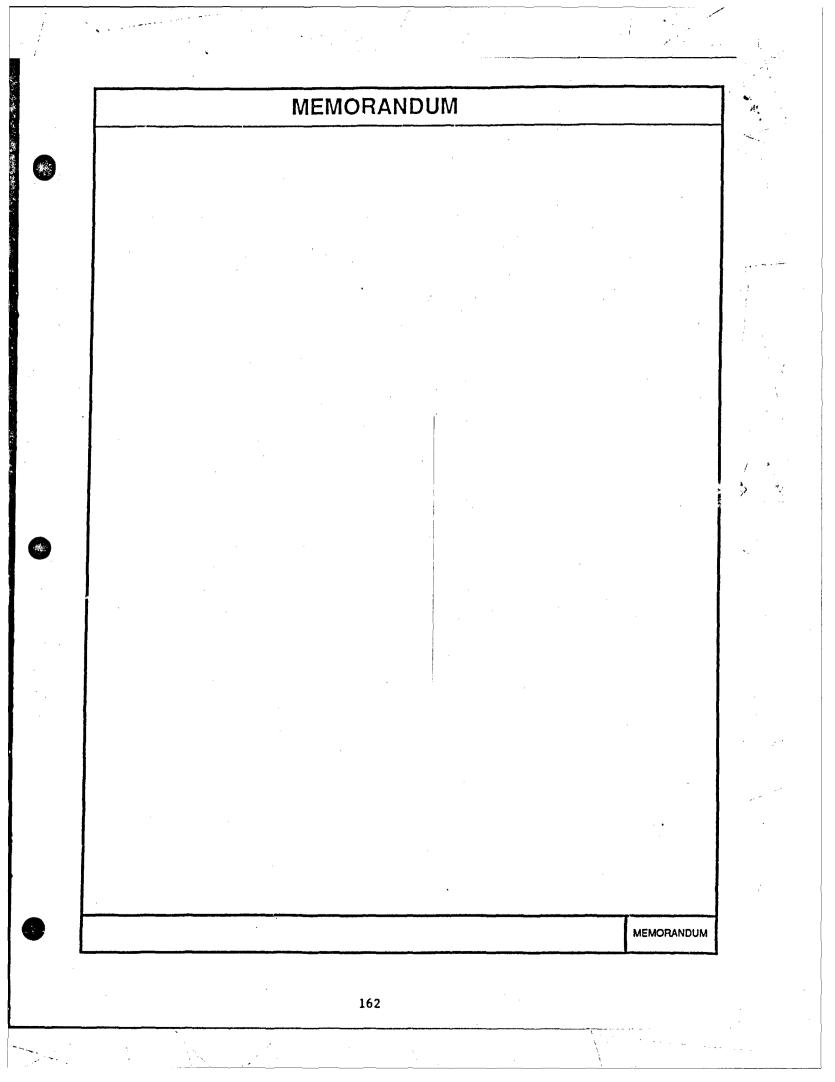
NOTE ITEM PART NO. GTY DESCRIPTION

F 54302 3 BOLT HX HD 38UNC 34LG GR S M F 64431 3 WASHER HD.MIO(ZINC PLATED) H BS633 HSACKET HSACKET M F 85033 VALVE MOUNTING M F 851473 BOLT HK HD 12X0 (B) ZP M F 851473 BOLT HK HD 12X0 (B) ZP M F 851473 BOLT HK HD 12X0 (B) ZP M F 8514734 D' RING F 649620 1 O' RING F 649630 1 O' RING F 649630 1 O' RING F 649633 ADAPTOR STA THD (LONG) F 649833 ADAPTOR F 649834 REDUCERTITHE ICORES) F 649833 ADAPTOR F 649834 ELBOW SEAL(SHORES) F 649843 ELBOW							*	
M - METRIC PART		м	***********************************	844313 874121 838544 898033 874179 874223 2M9780 6V8629 6V9746 2M9780 6V8629 6V9746 3K0360 6R9165 6V8398 6V8639 6V8639 6V8639 6V8639 6V8634 6V8394 4J5477 7J0204 815622 3J1907 6V8634 6V8394 935077 6V8631 6V8838 815645 3J1907 6V0852 6V3965 3J1907	131144111111636322222111112112112111112	HUSCO 4 SPOOL VALVE(ALL ELECTRIC) WASHER HD.M10(ZINC PLATED) BRACKET-VALVE MOUNTING VALVE MOUNTING BRACKET BOLT HX HD 12X20 (8.8) Z/P WASHER HD.M12(ZINC PLATED) 'O' RING ELBOW 'O' RING ELBOW 'O' RING SEAL(3/4ORB) ADAPTOR STR THD (LONG) O-RING SEAL(3/4ORB) ADAPTOR STR THD (LONG) O-RING SEAL(13/16ORFS) ADAPTOR O-RING SEAL(3/4ORB) O-RING SEAL(3/4ORB) O-RING SEAL(3/4ORB) O-RING SEAL(13/16ORFS) Y RING SEAL (9/16ORFS) 'O' RING SEAL (9/16ORFS) O-RING SEAL (9/16ORFS) O-RING SEAL (9/16ORFS) O-RING SEAL (9/16ORFS) O-RING SEAL (9/16ORFS) O-RING SEAL (9/16ORFS) O-RING SEAL (9/16ORFS) ADAPTOR ELBOW 9/16-18ORFSX9/16-18ORFS('O' RING SEAL COVER TEST POINT NIPPLE ASSY QUICK RELEASE O-RING SEAL COVER TEST POINT NIPPLE ASSY QUICK RELEASE 'O' RING SEAL COVER TEST POINT NIPPLE ASSY QUICK RELEASE 'O' RING SEAL		
REV000	F - NOT SHOWN						P6R9255	Г
	M - METRIC PART						REV000	
				CD00EF	יעט			



 MEMORANDUM		
		0
		·
·		
· · · · · · · · · · · · · · · · · · ·		•
 	MEMORANDUM	

ï,



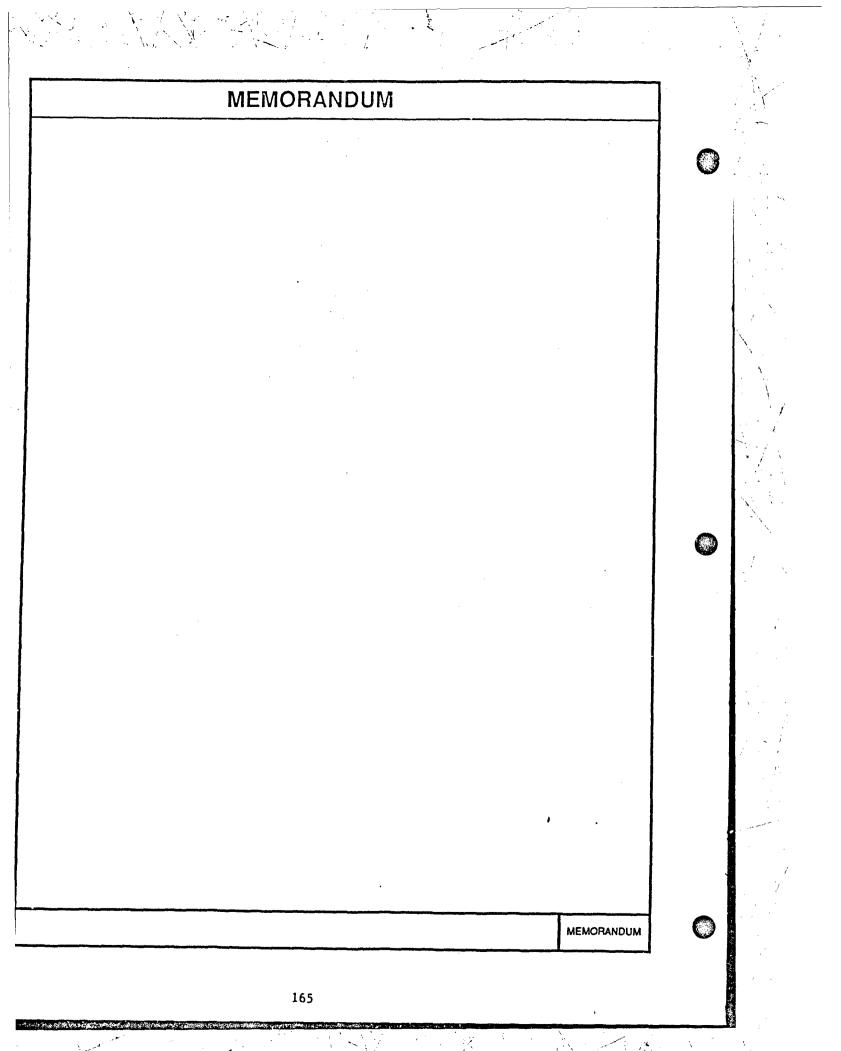
	MEMORANDUM
	- .
. · ·	
MEMORANDUM	

· .

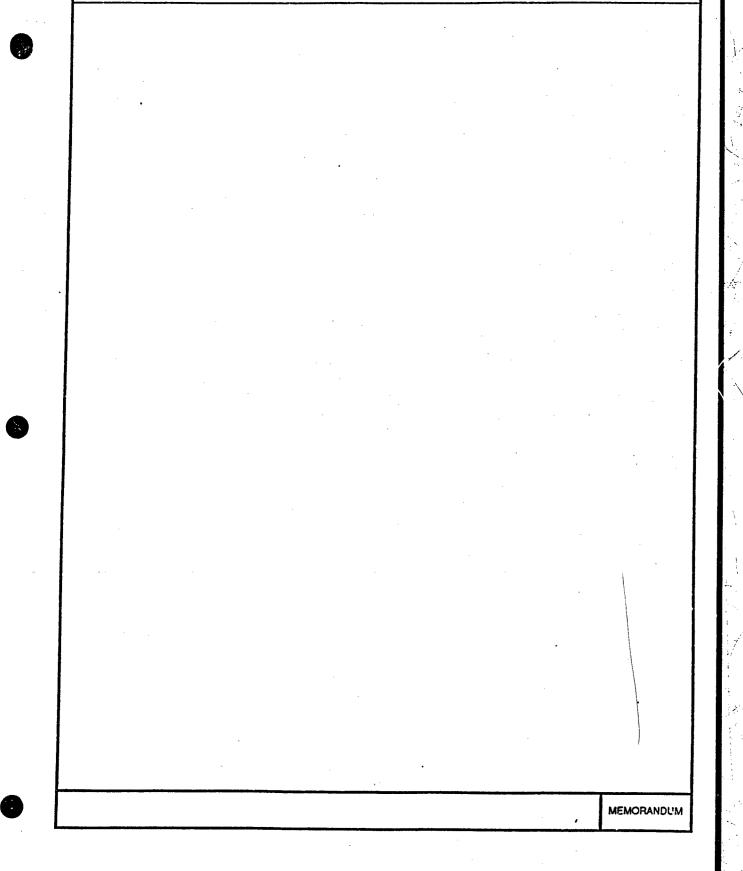
•

MEMORANDUM			
	Л		MEMORAN
			· · · ·
			·
MEMORANDUM	MEMORANDUM	MEMORANDUM	

ł,



MEMORANDUM



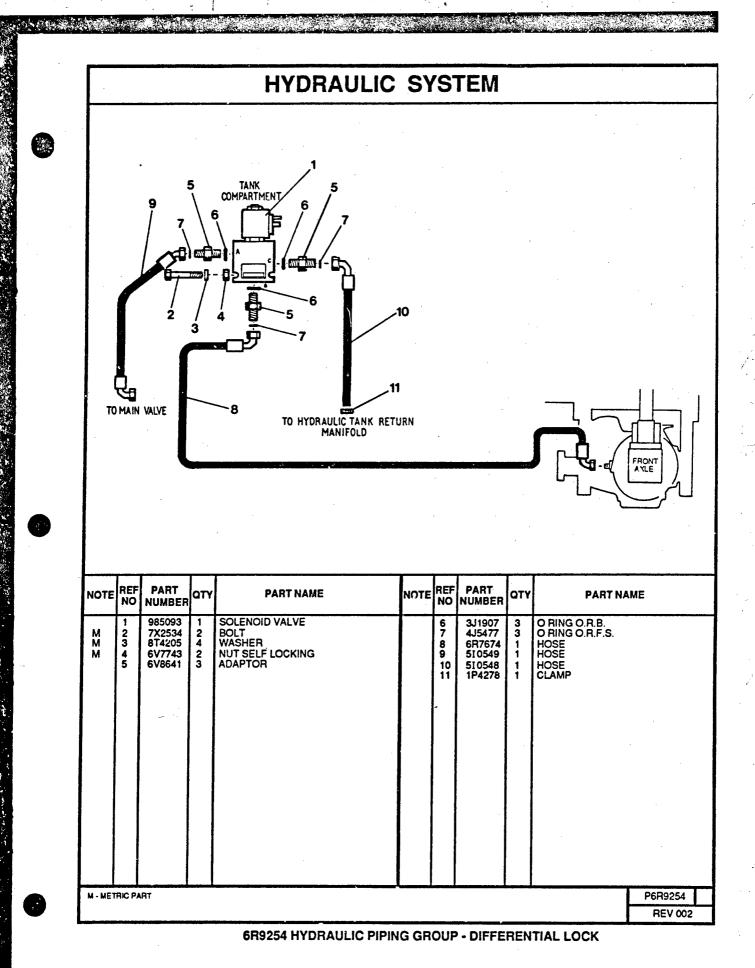
;56

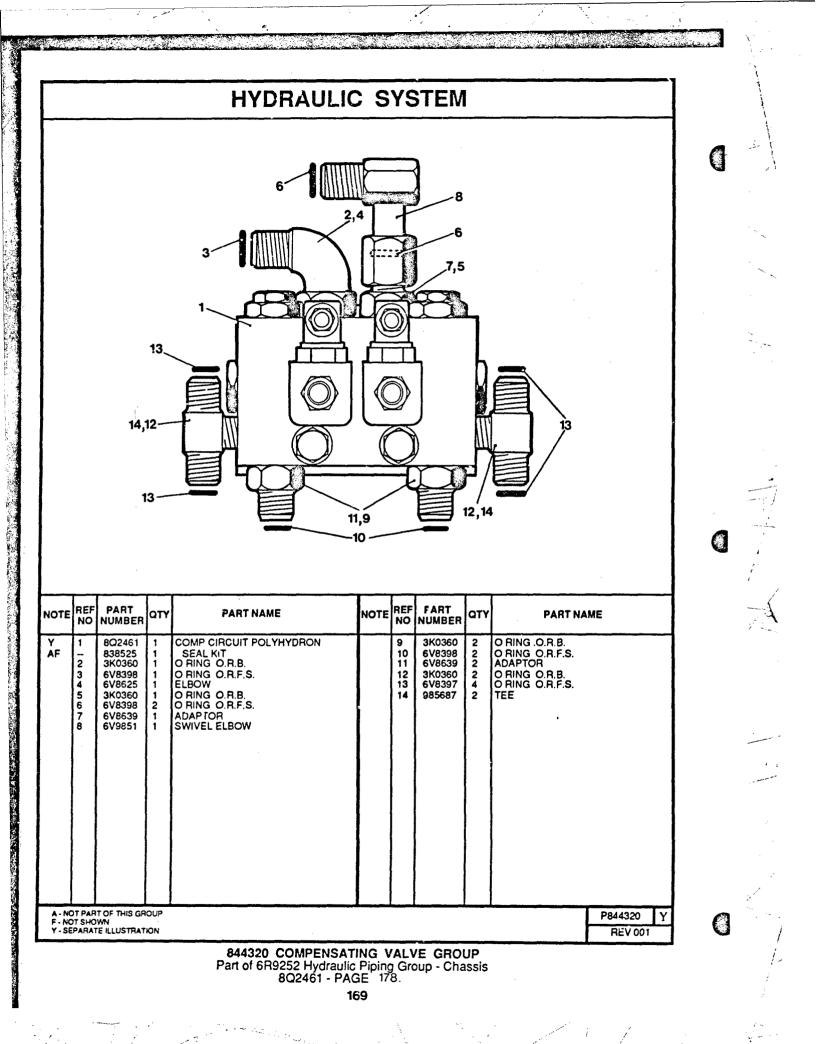
inge in the

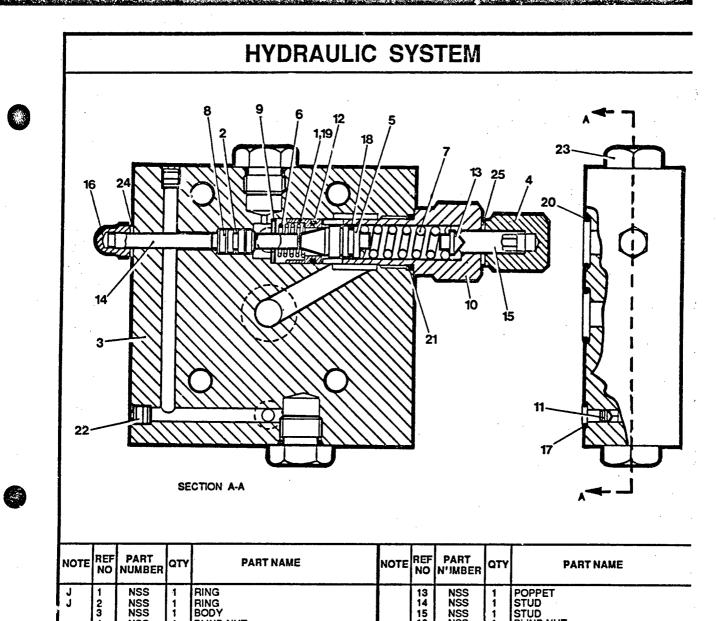
MEMORANDUM

· ·

MEMORANDUM

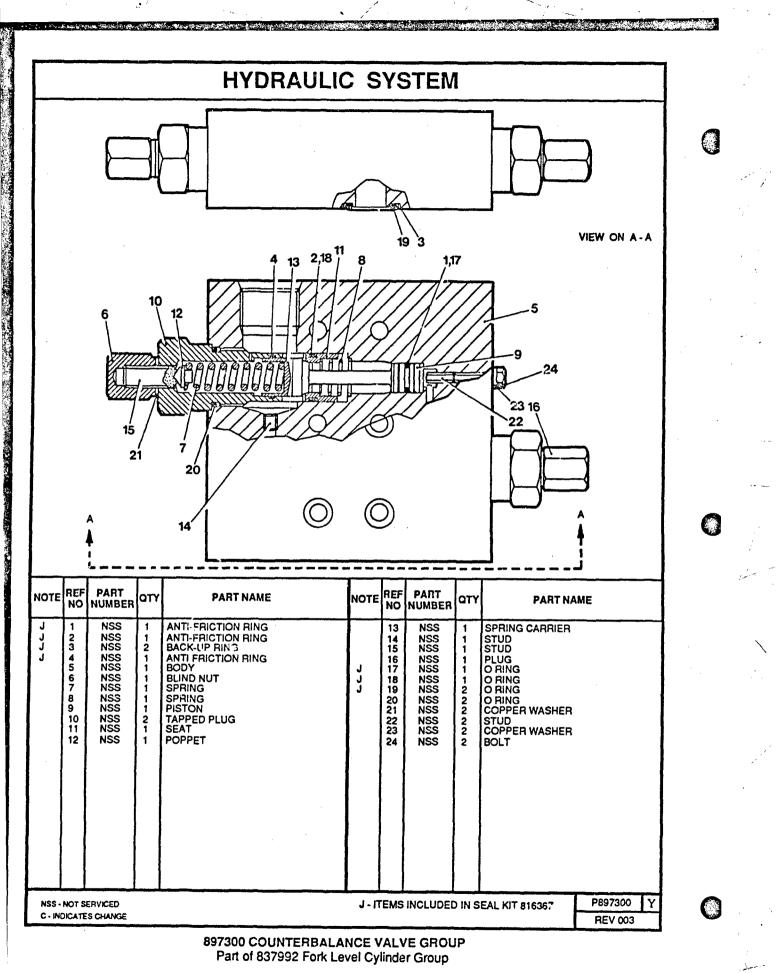


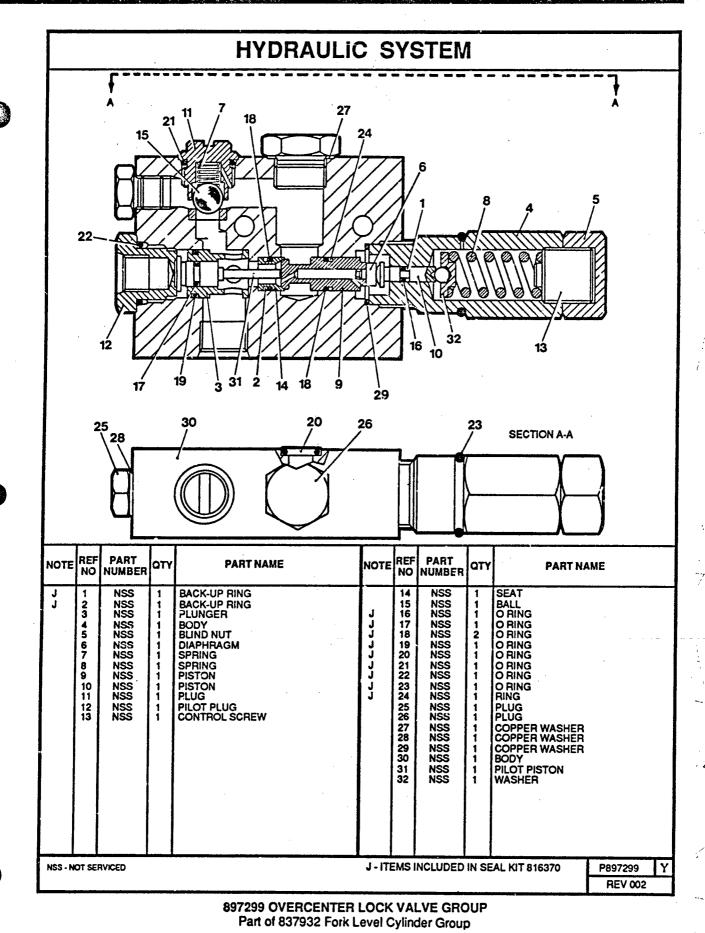




	NO	NUMBER	.			NO	N'IMBER		FADINA	WE	
ι. Γ	1 23 45 67 89 10 11 12	S S S S S S S S S S S S S S S S S S S	1 1 1 1 1 1 1 1 1 1 1 1	RING RING BUND NUT POPPET SPRING SEAT WASHER TAPPED BLOCK PLUG SEAT	111111111111111111111111111111111111111	13 14 15 16 17 18 20 21 22 32 4 25	NSS NSS NSS NSS NSS NSS NSS NSS NSS NSS	111111111111111111111111111111111111111	POPPET STUD STUD BLIND NUT O RING O RING O RING O RING PLUG PLUG COPPER WASHER COPPER WASHER		-
NSS - NC	T SER	VICED			J - IT	EMS	INCLUDED	IN SE	AL KIT 816368	P897301 REV 003	Y
				897301 SINGLE OVERCENT				~			-

897301 SINGLE OVERCENTER VALVE GROUP Part of 838021 Boom Raise Ram Group

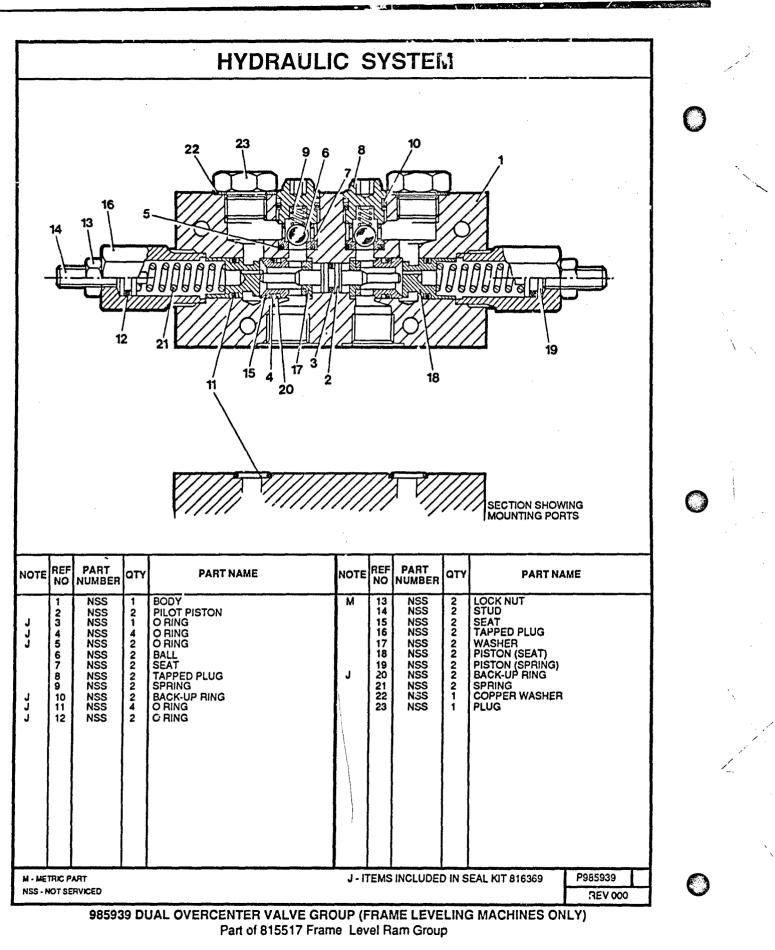


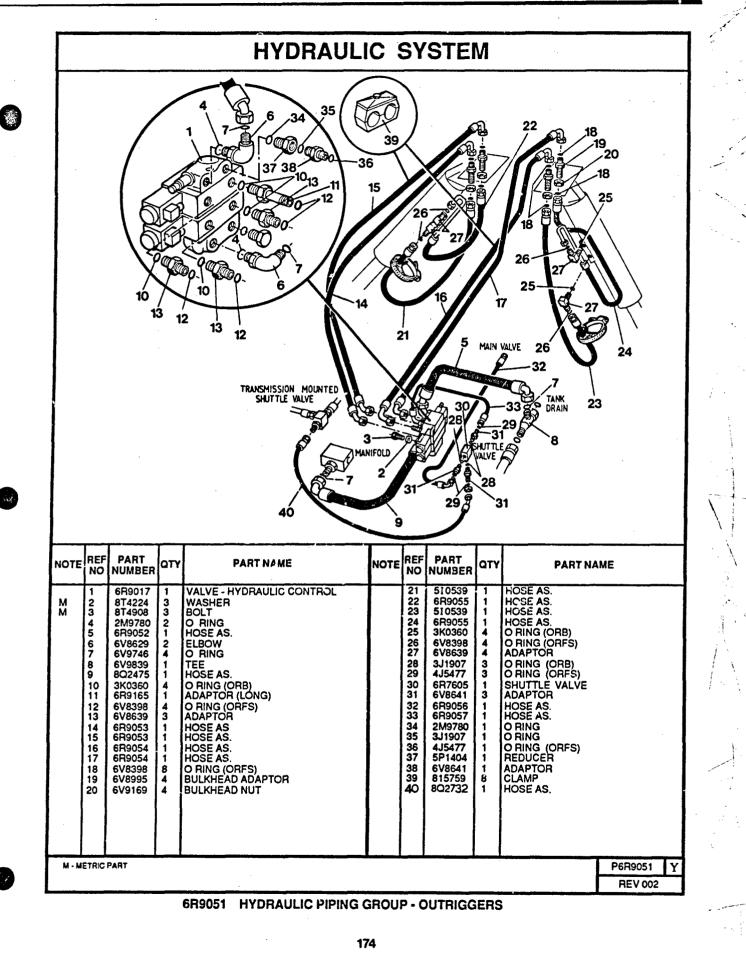


「日本のない」の

172

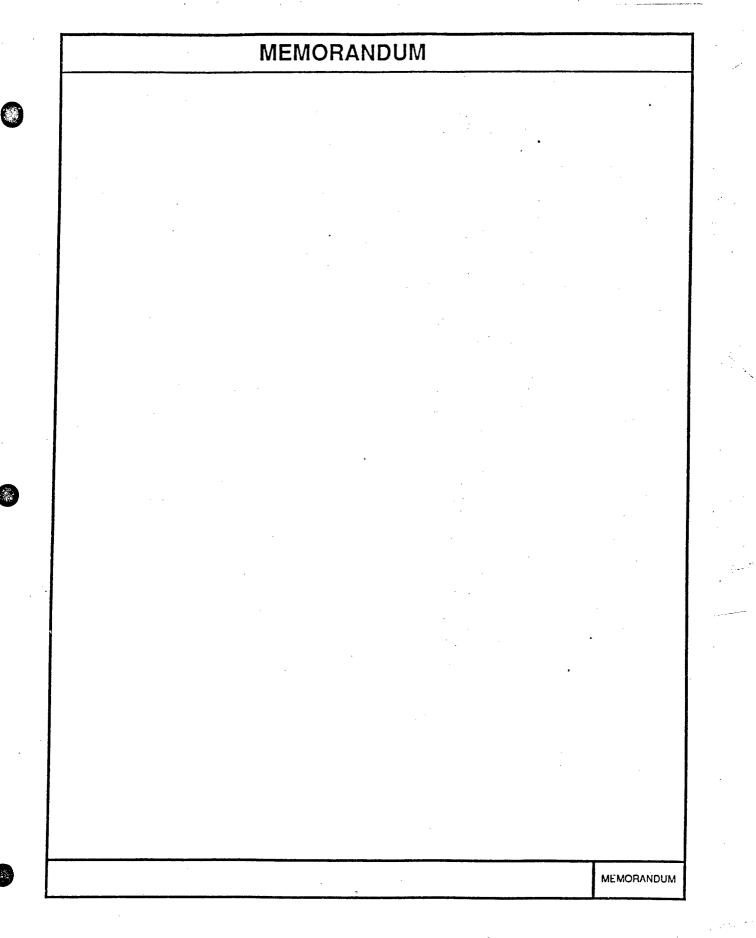
.

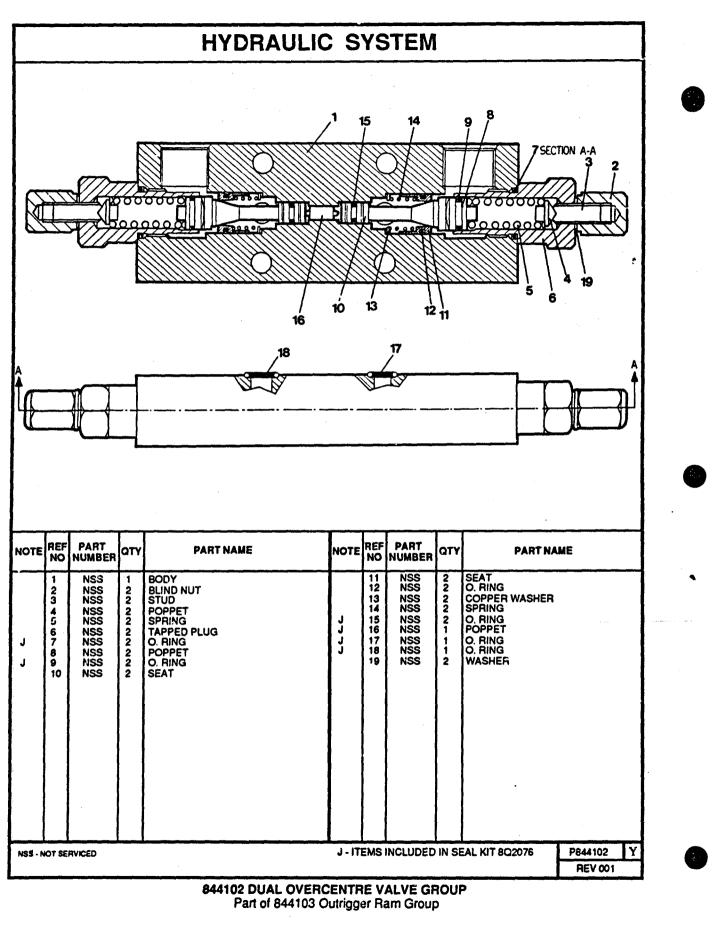




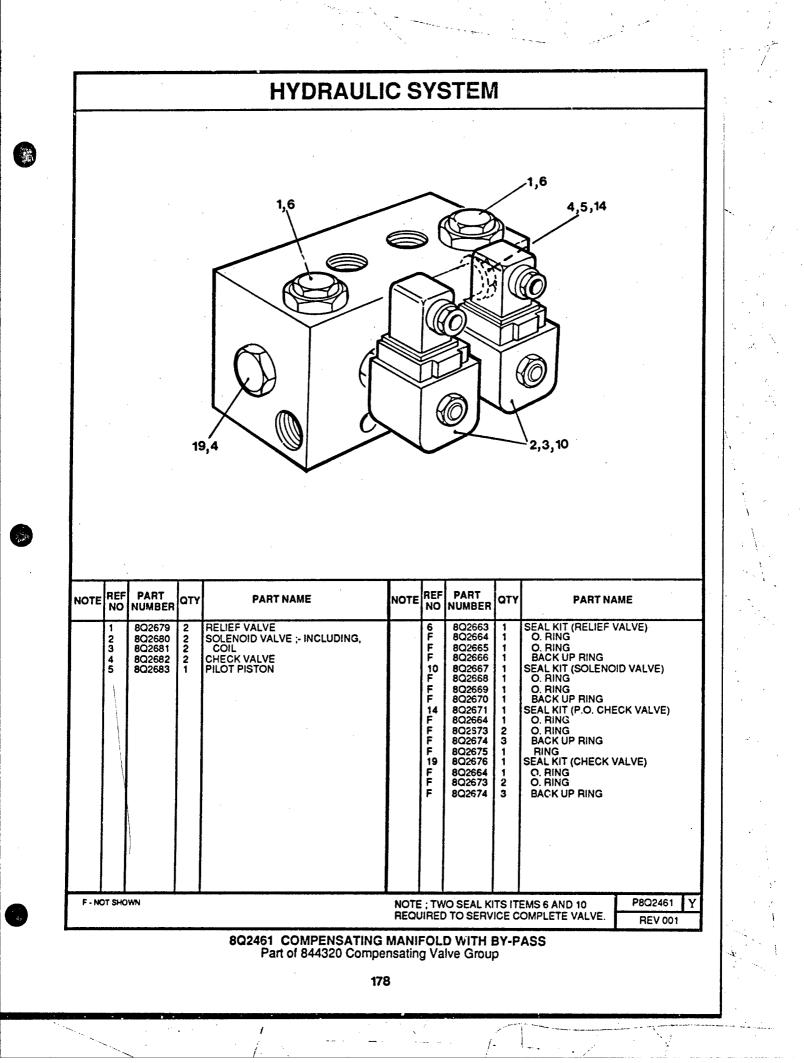
. .

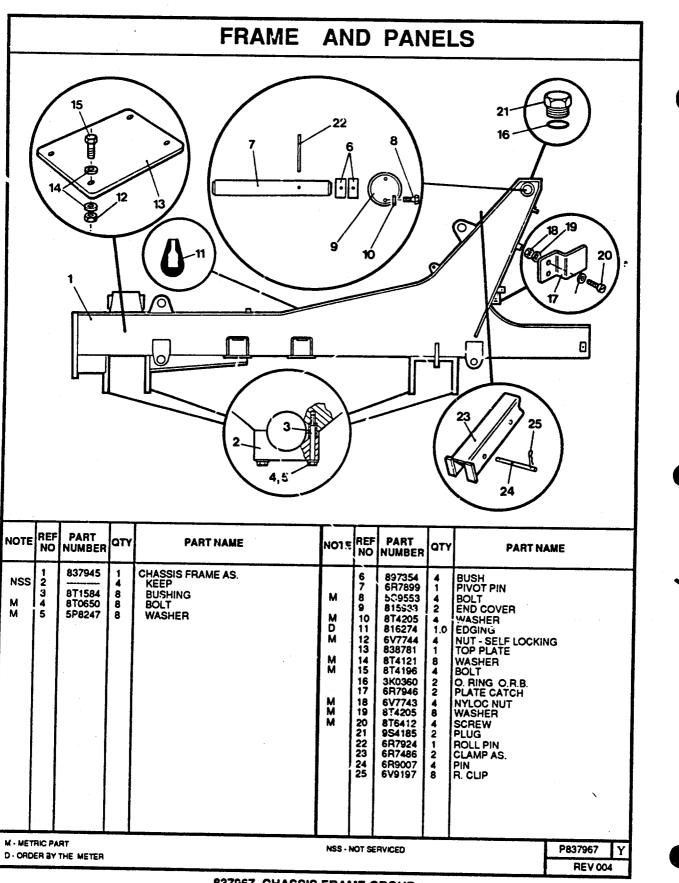
MEMORA	NDUM	
		 MEMORANDUM





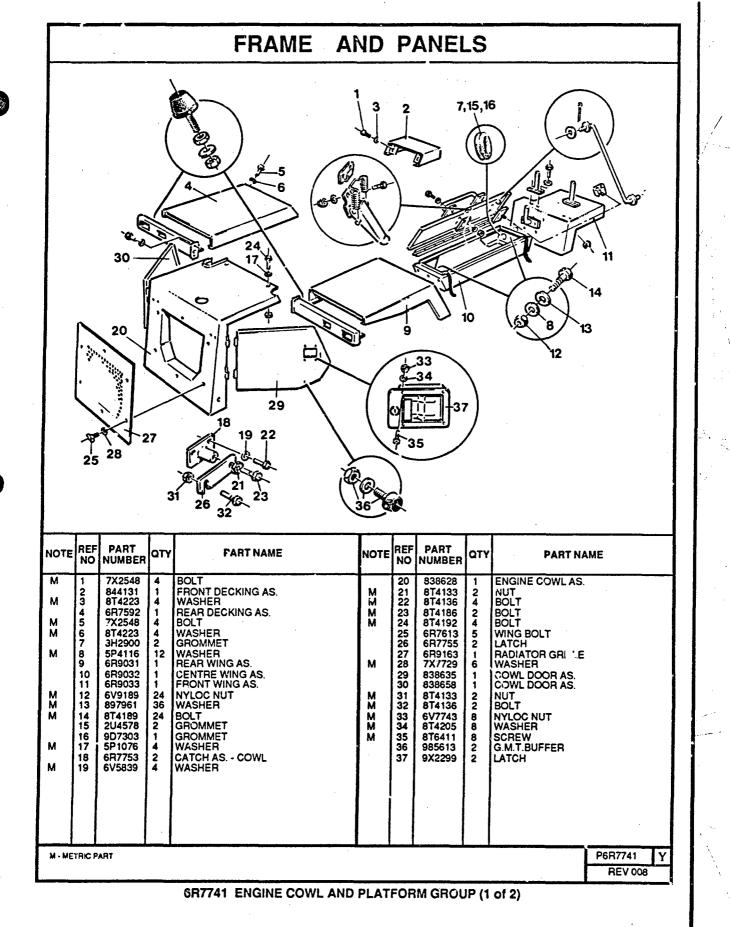
`>





·

837967 CHASSIS FRAME GROUP



×.

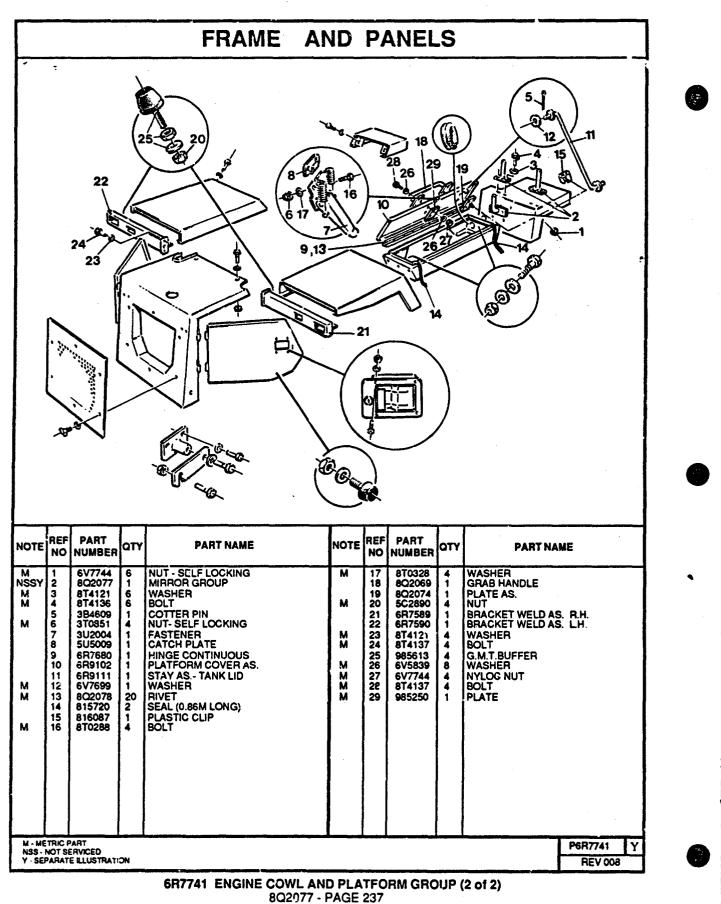
1

e history in which is the strain of

180

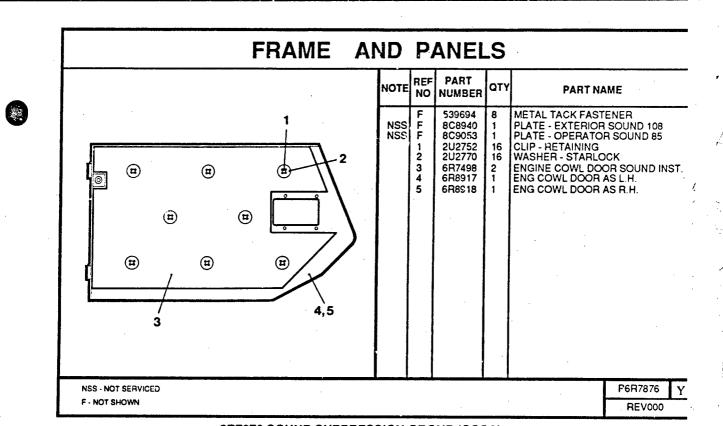
" with a state of the states

Sec. 2

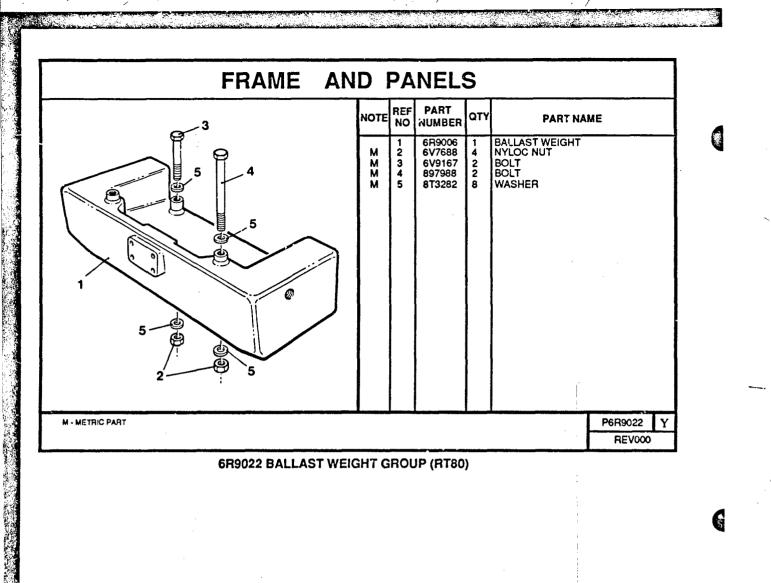


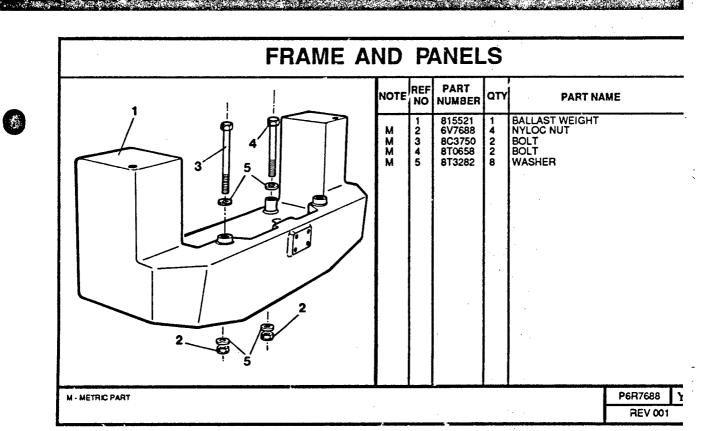
ĩ,

. .

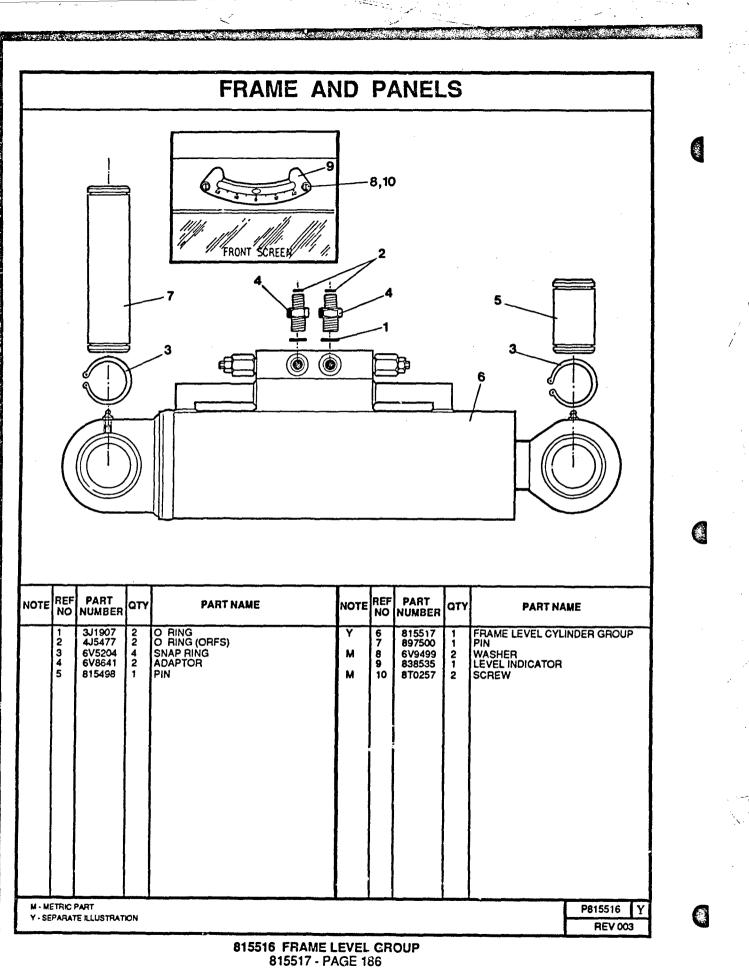


6R7876 SOUND SUPPRESSION GROUP (COSA)





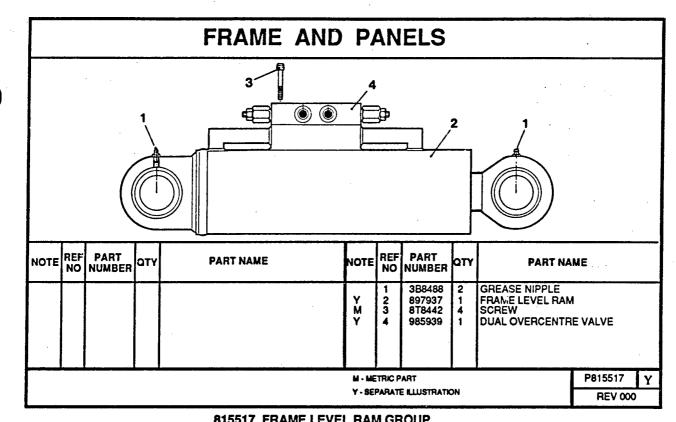
6R7688 BALLAST WEIGHT GROUP (RT100)



Same week.

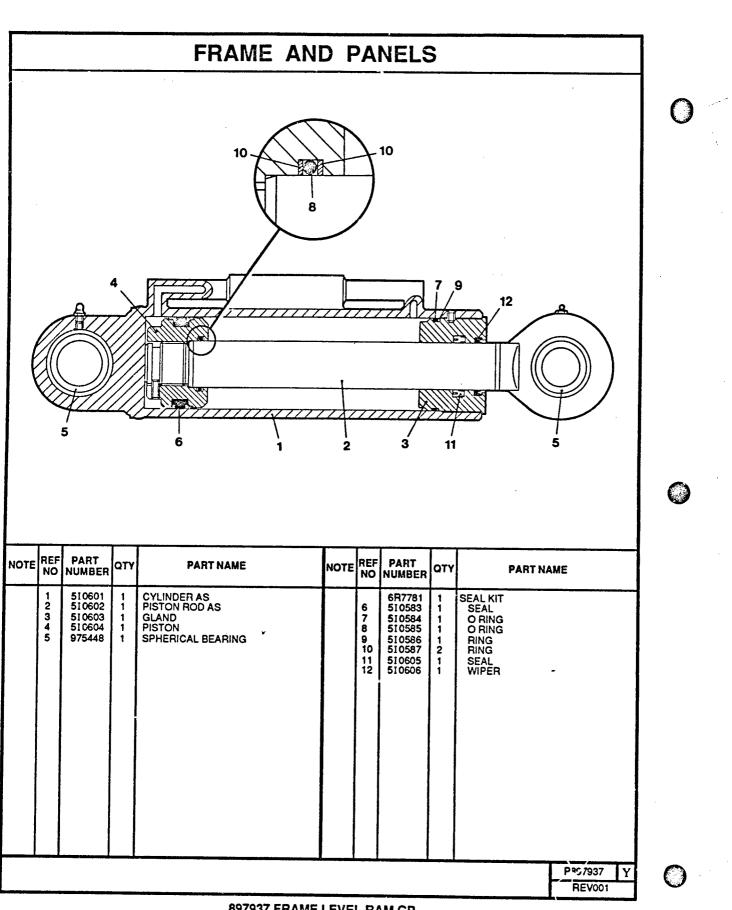
Contraction of the





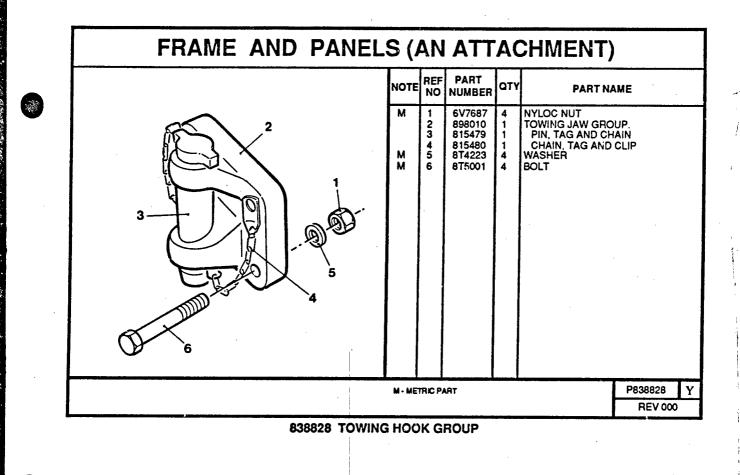
1

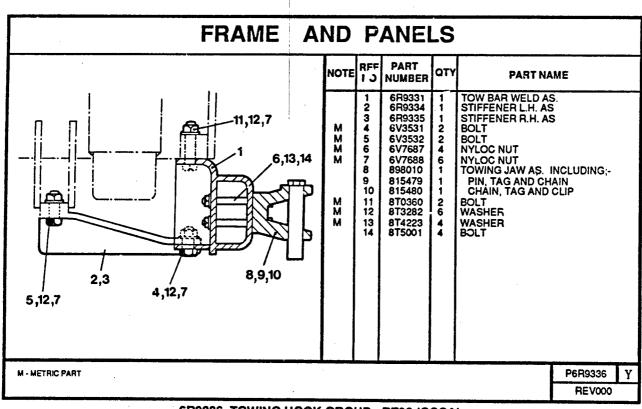
815517 FRAME LEVEL RAM GROUP 897937 - PAGE 187. 985939 - PAGE 173 .



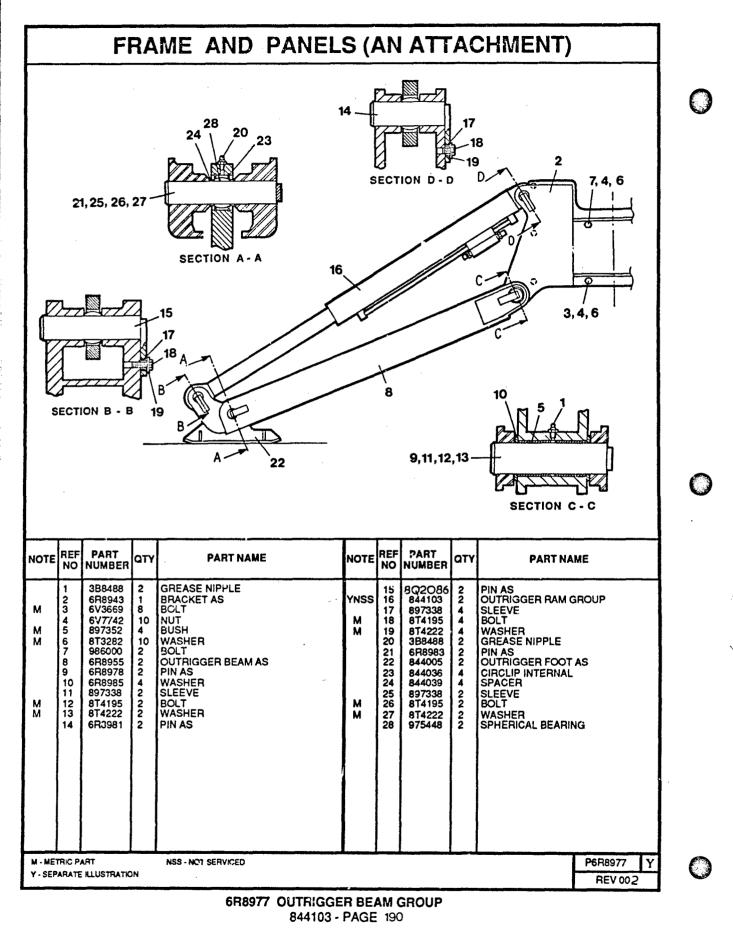
The far in the state of the far have a state of the state

897937 FRAME LEVEL RAM GP Part of 815517 Frame Level Ram GP

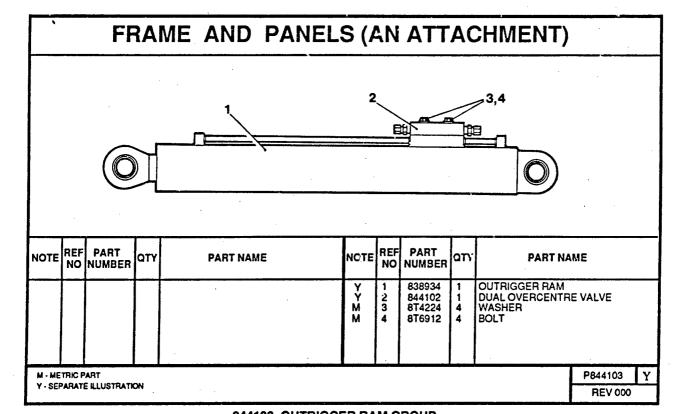




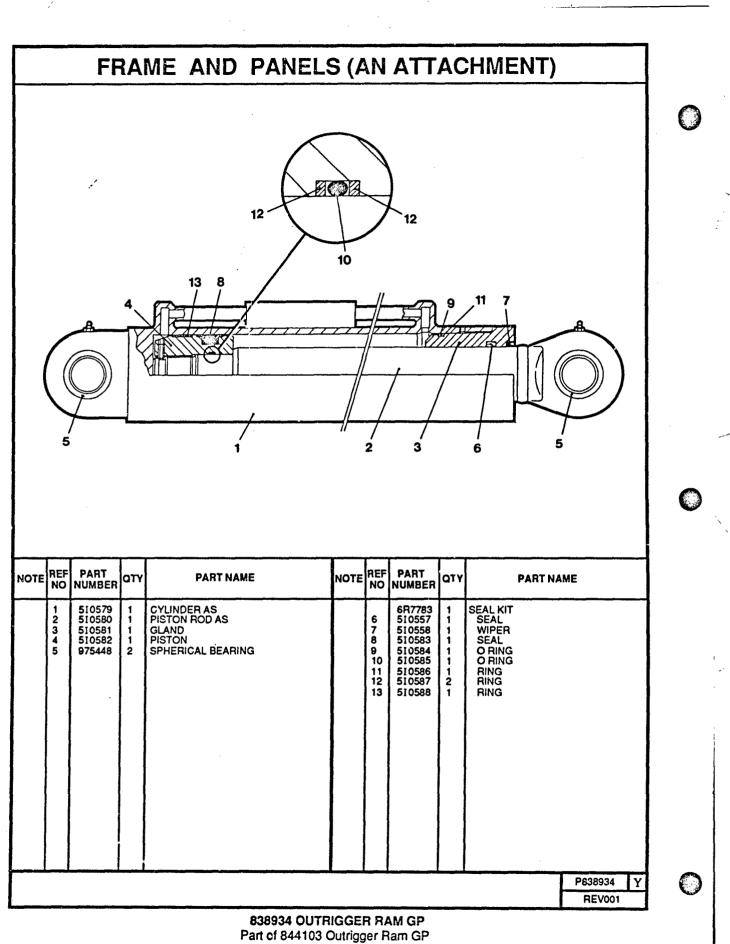
6R9336 TOWING HOOK GROUP - RT80 (COSA)



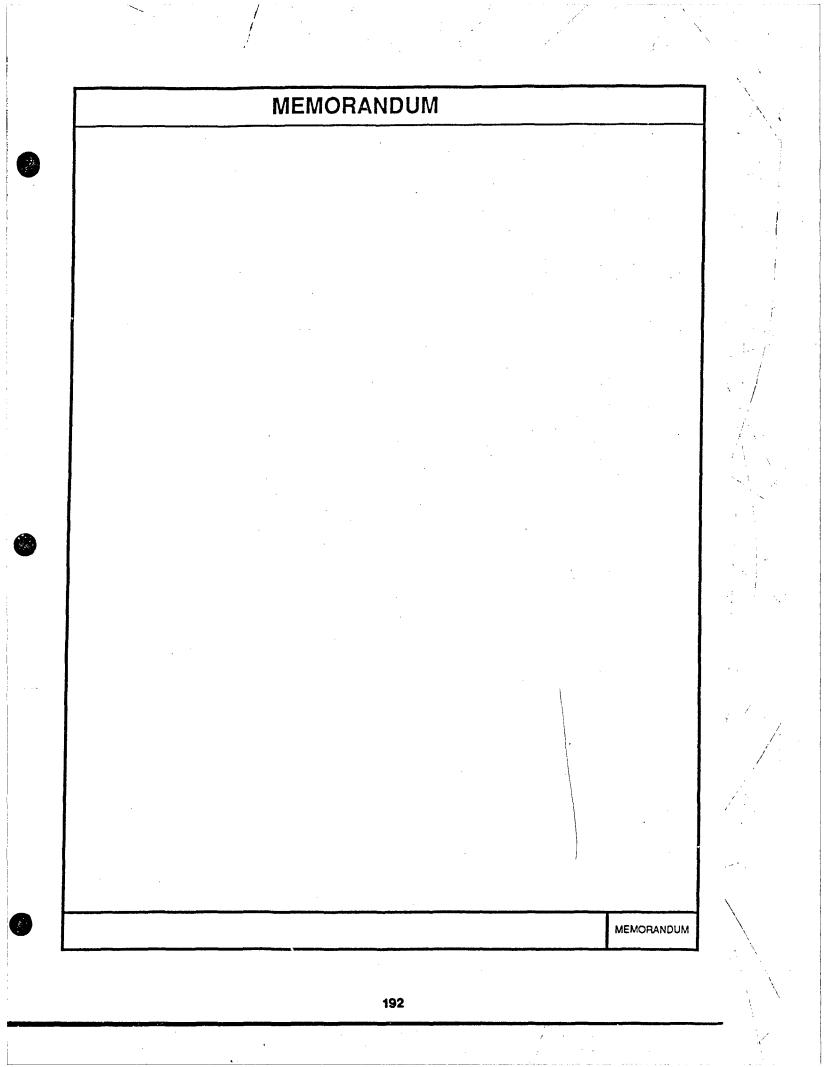




844103 OUTRIGGER RAM GROUP 844102 - PAGE 177. 838934 - PAGE 191





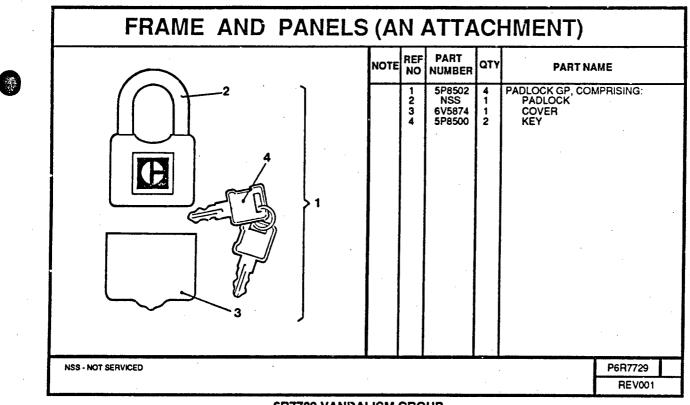


MEMORANDUM

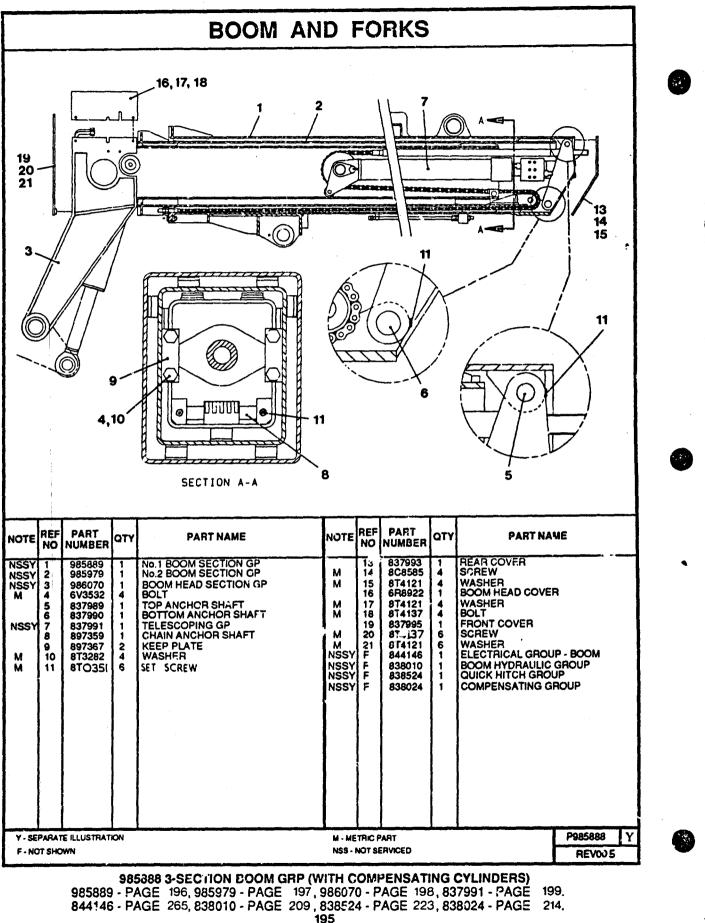
MEMORANDUM

0

0

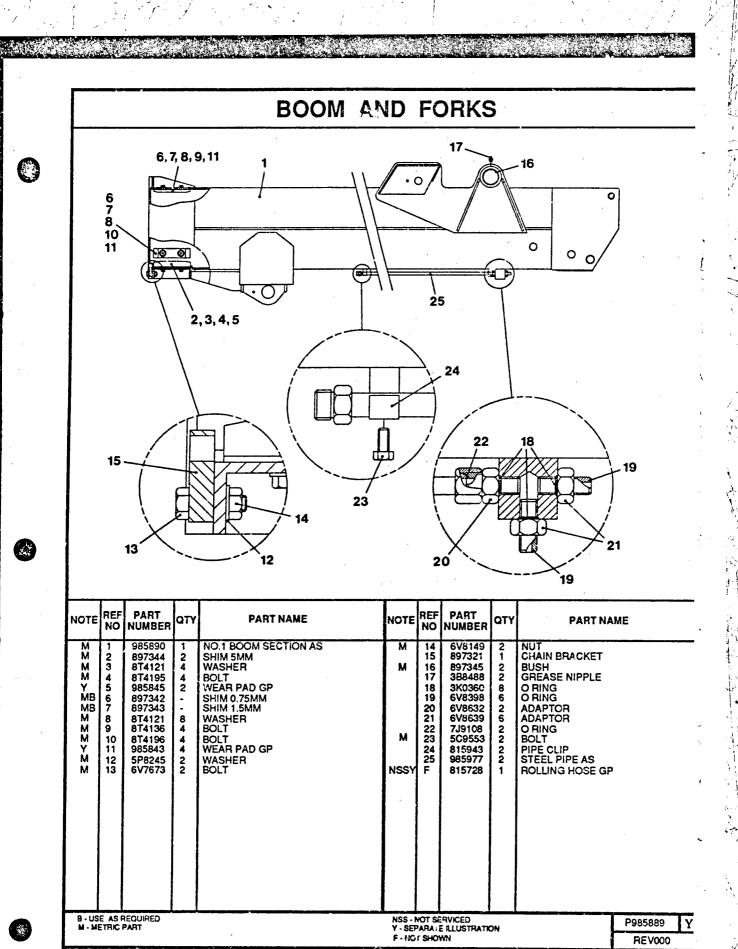


6R7729 VANDALISM GROUP



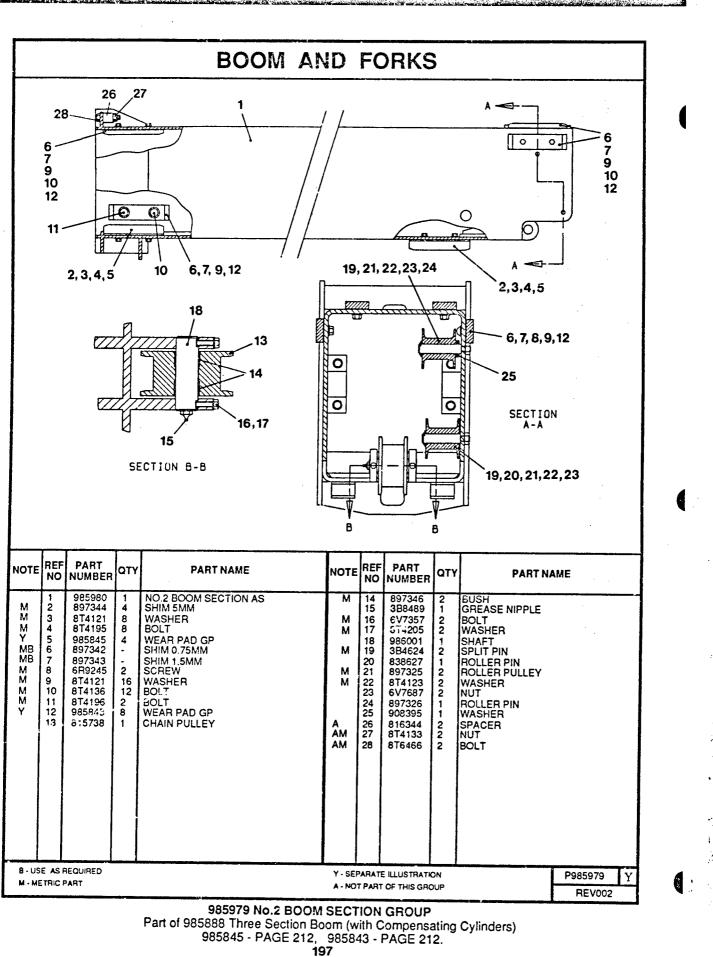
• •

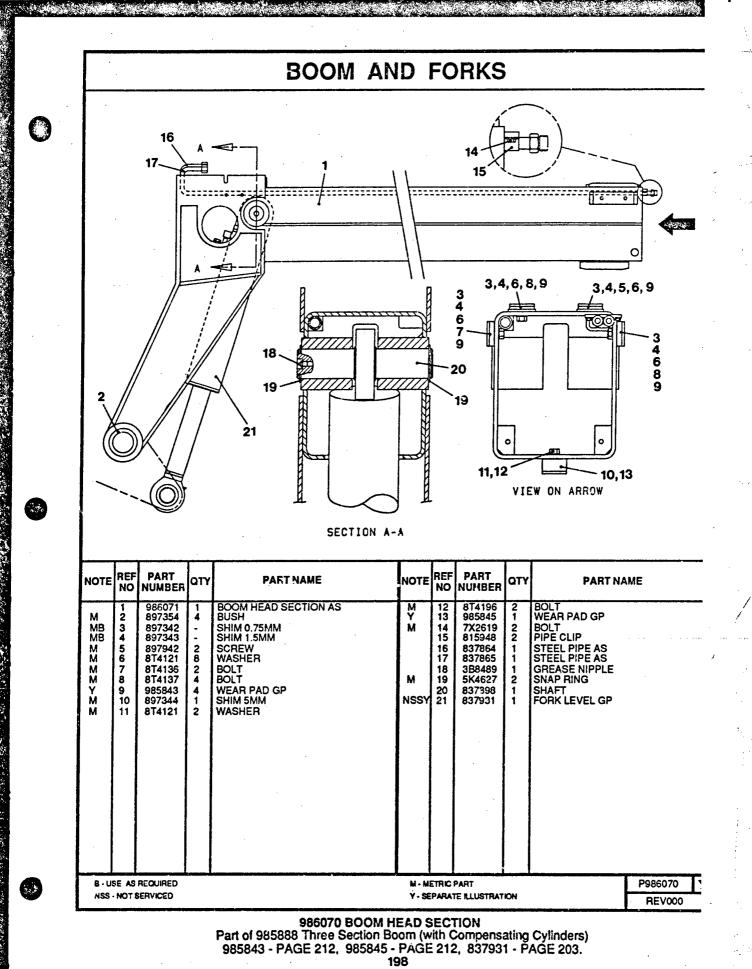
Caller Caller

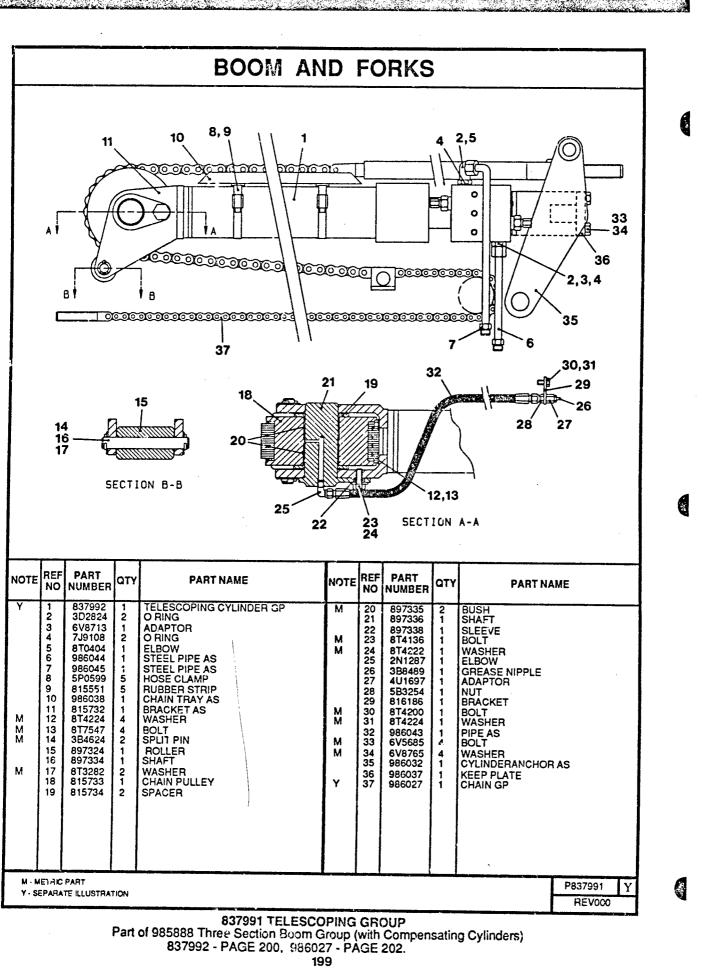


985889 No.1 BOOM SECTION GRP (WITH COMPENSATING CYLINDERS) Part of 985888 Three Section Boom (with Compensating Cylinders)

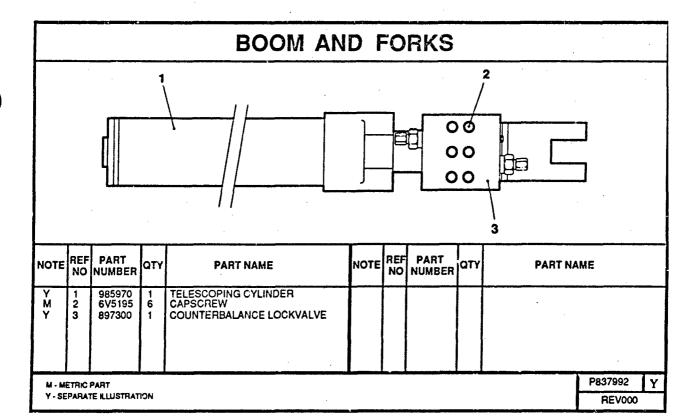
985845 - PAGE 212, 985843 - PAGE 212, 815728 - PAGE 213.





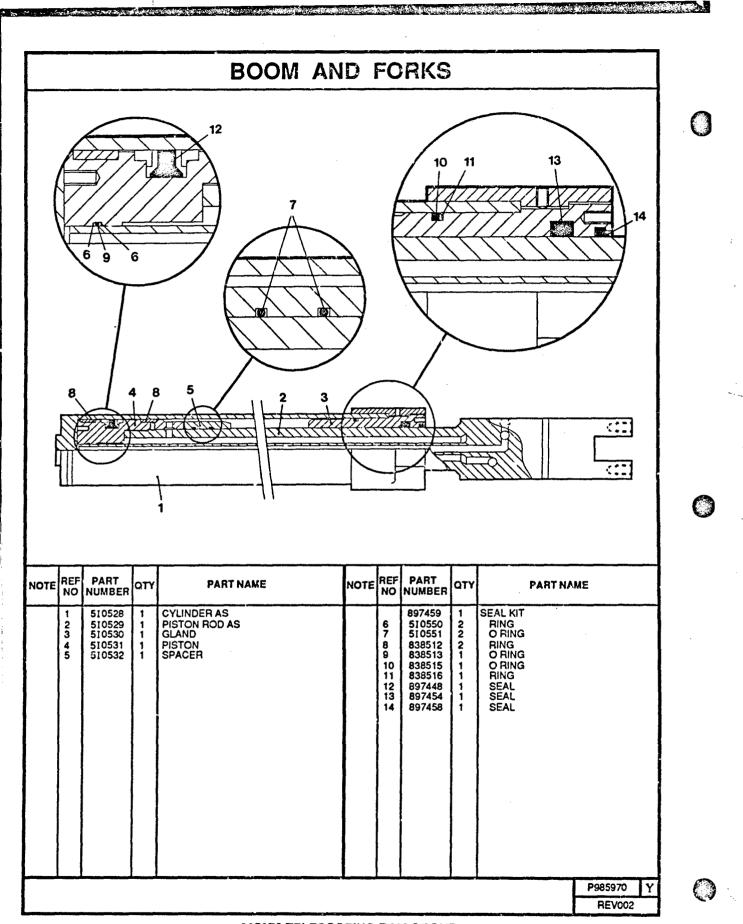


Contraction of the second



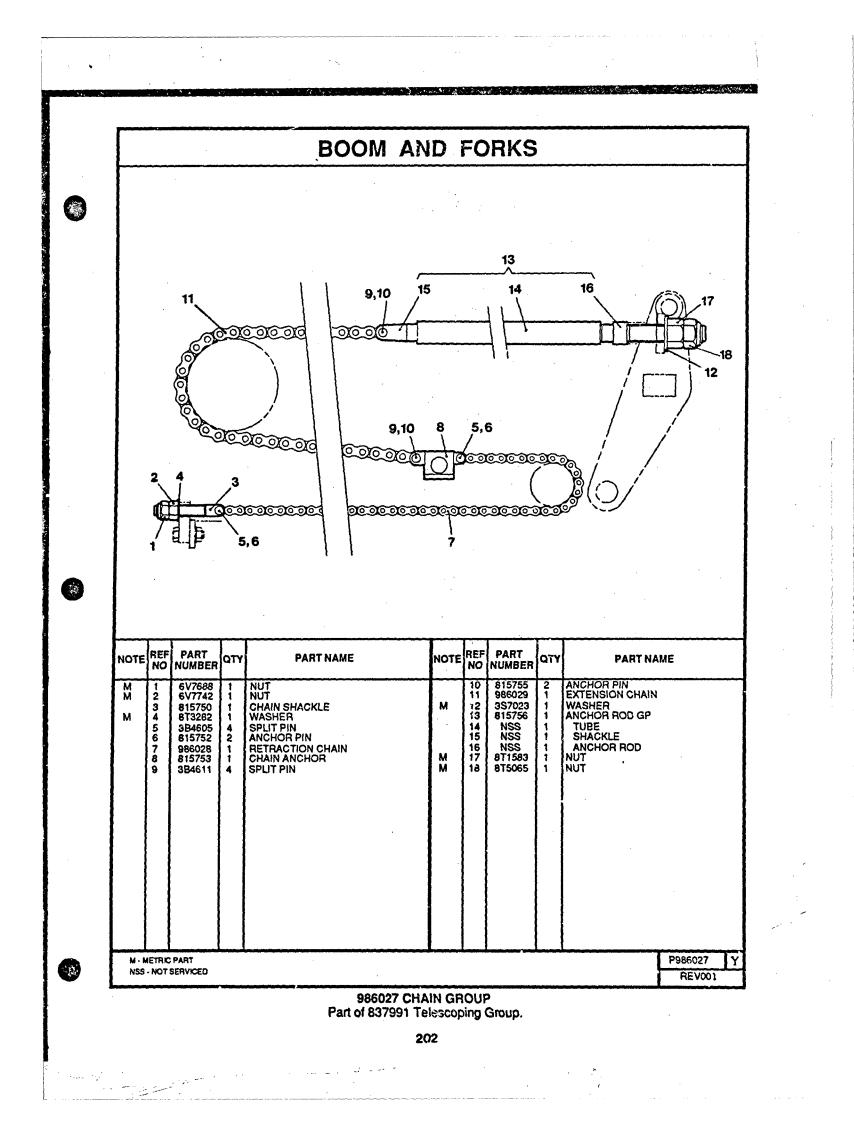
Ching in date billion.

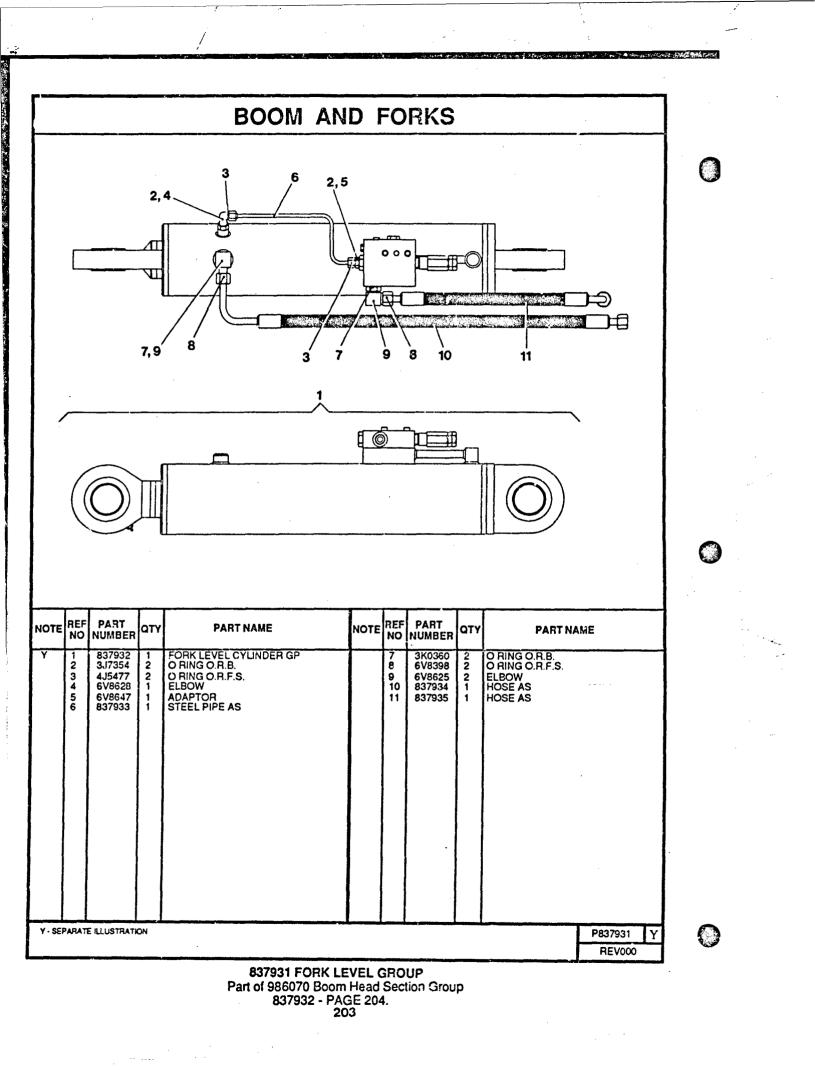
837992 TELESCOPING CYLINDER GROUP Part of 837991 Telescoping Group 985970 - PAGE 201. 897300 - PAGE 171.

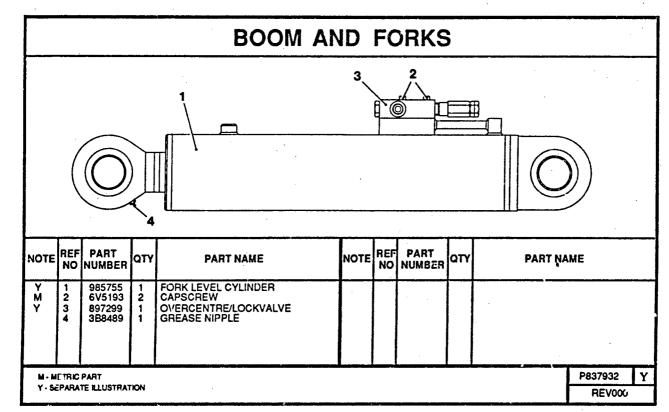


í.

985970 TELESCOPING RAM GROUP Part of 837992 Telescoping Cylinder GP.

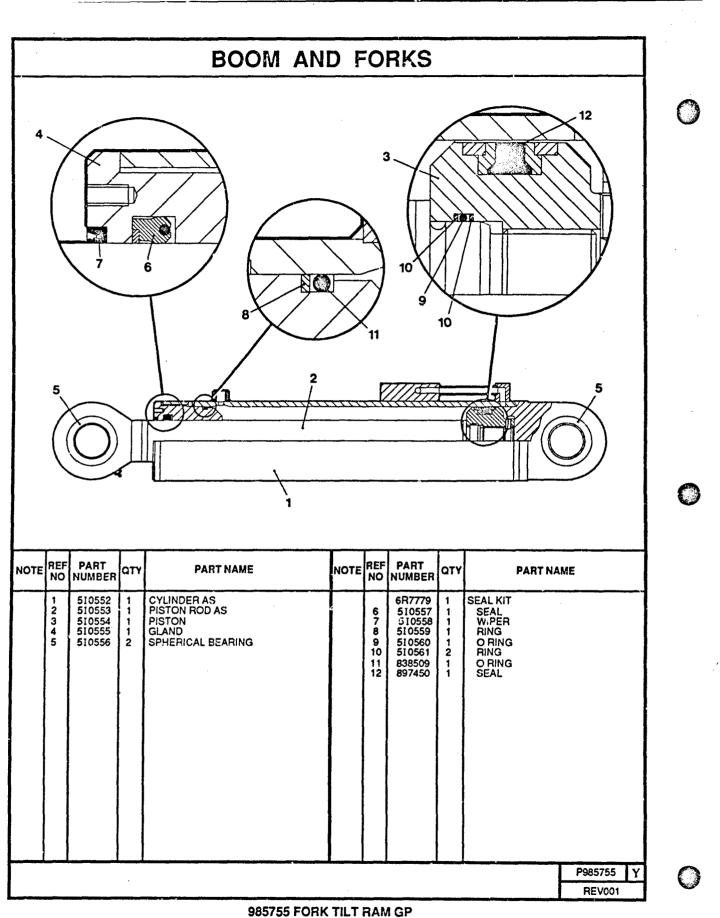






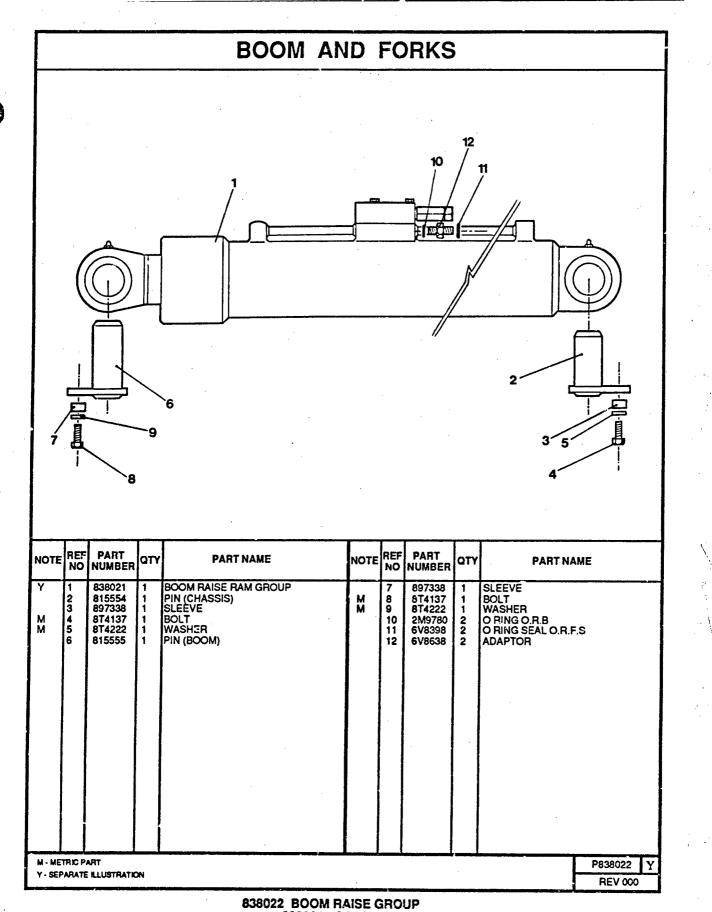
ų.

837932 FORK LEVEL CYLINDER GROUP Part of 837931 Fork Level Group 985755 - PAGE 205, 897299 - PAGE 172.



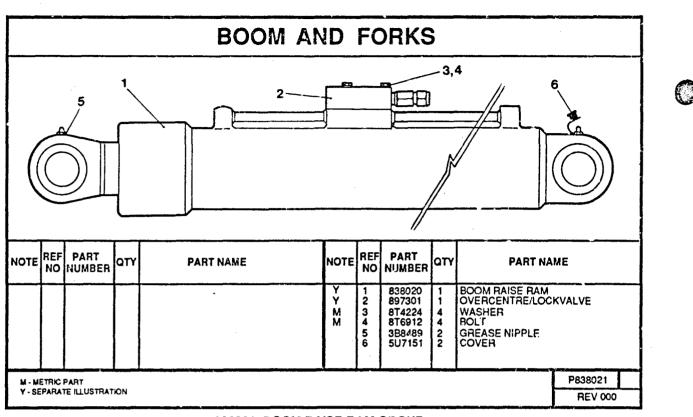
,

Part of 837932 Fork Level Cylinder GP



838021 - PAGE 207.

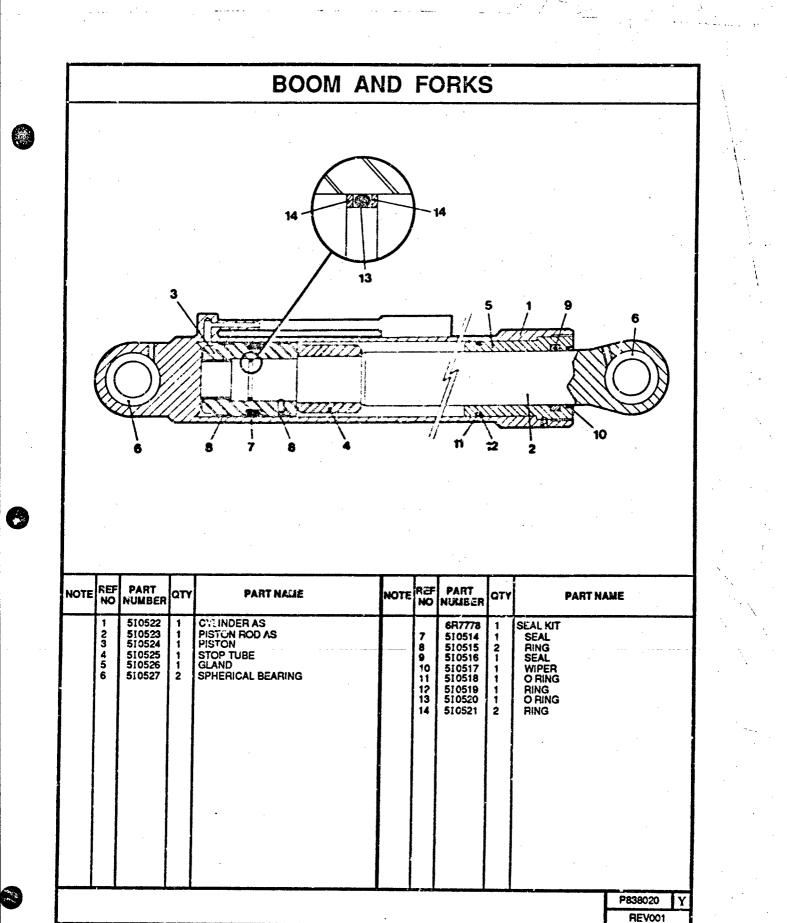
Ľ,



· · .

. .

838021 BOOM RAISE RAM GROUP Part of 838022 Boom Raise Group 838020 - PAGE 208, 897301 - PAGE 170.



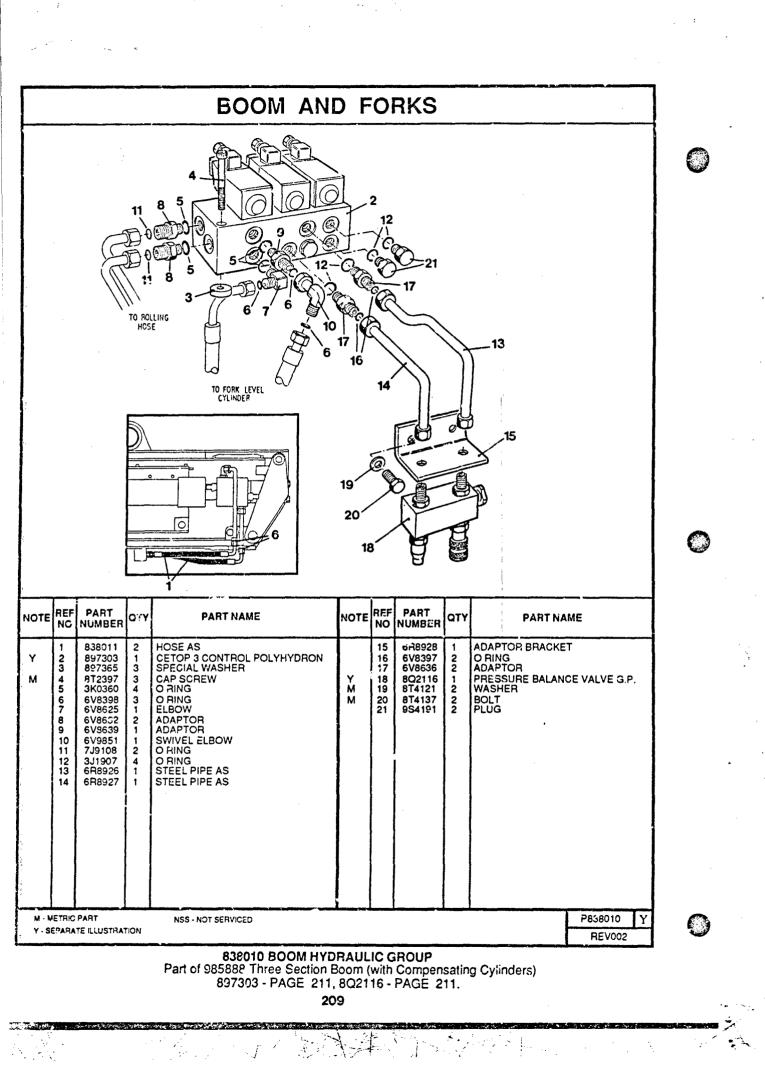
838020 BOOM RAISE RAM GROUP Part of 838021 Boom Raise Ram GP.

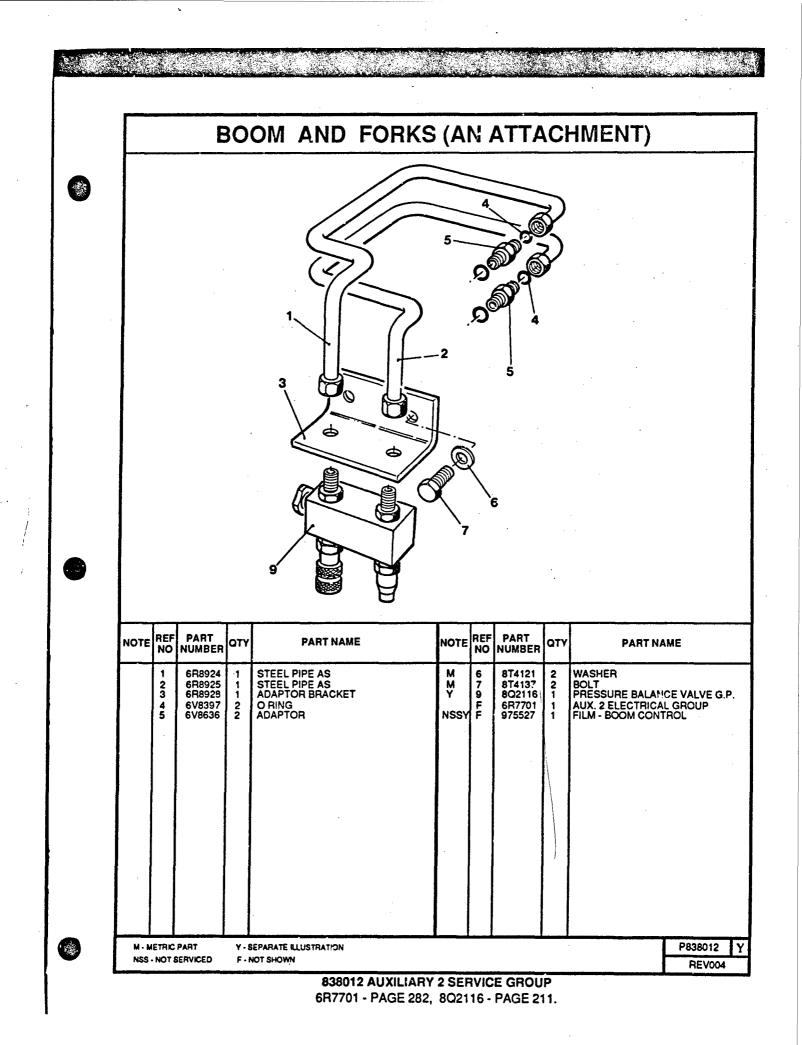
14

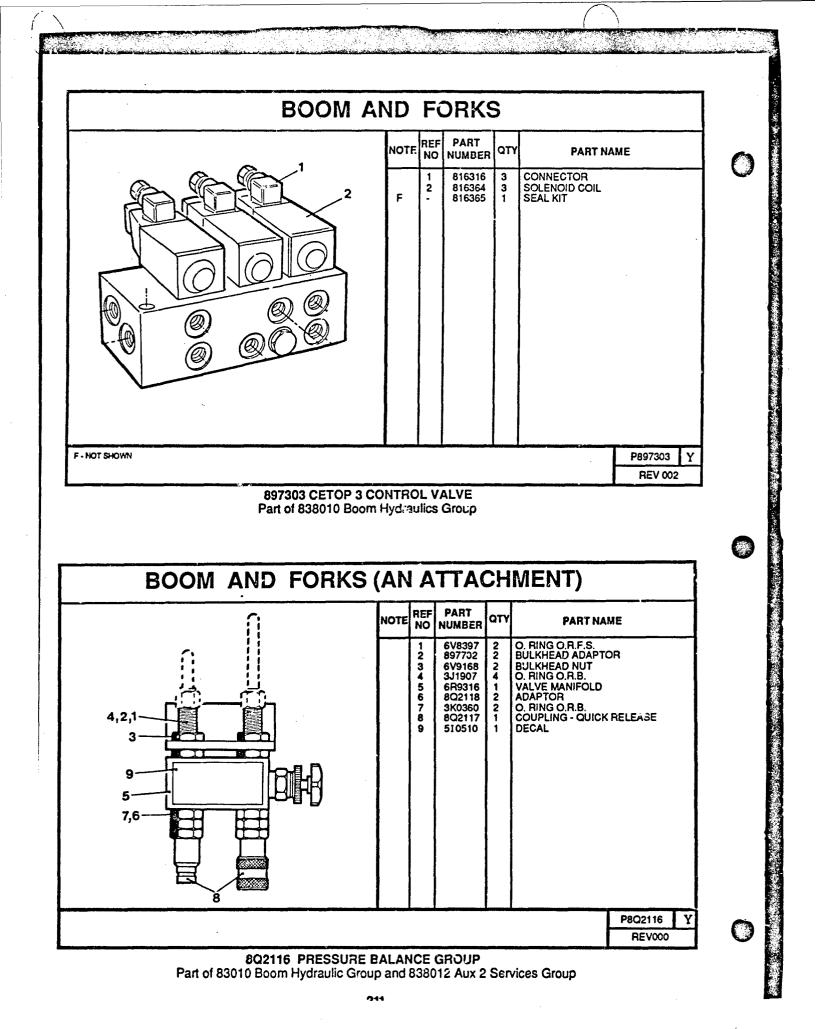
208

- 2

.

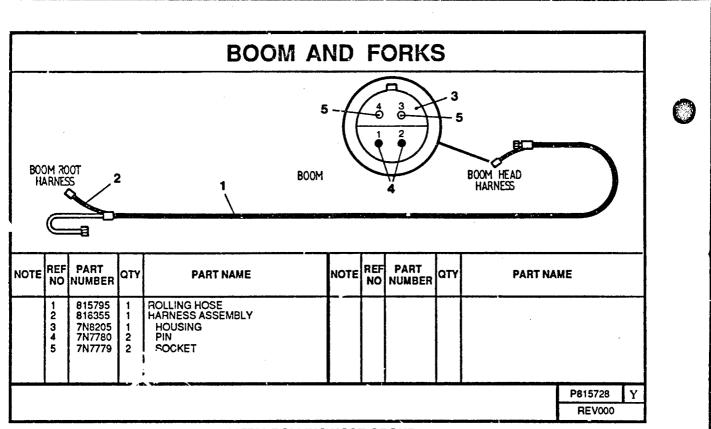






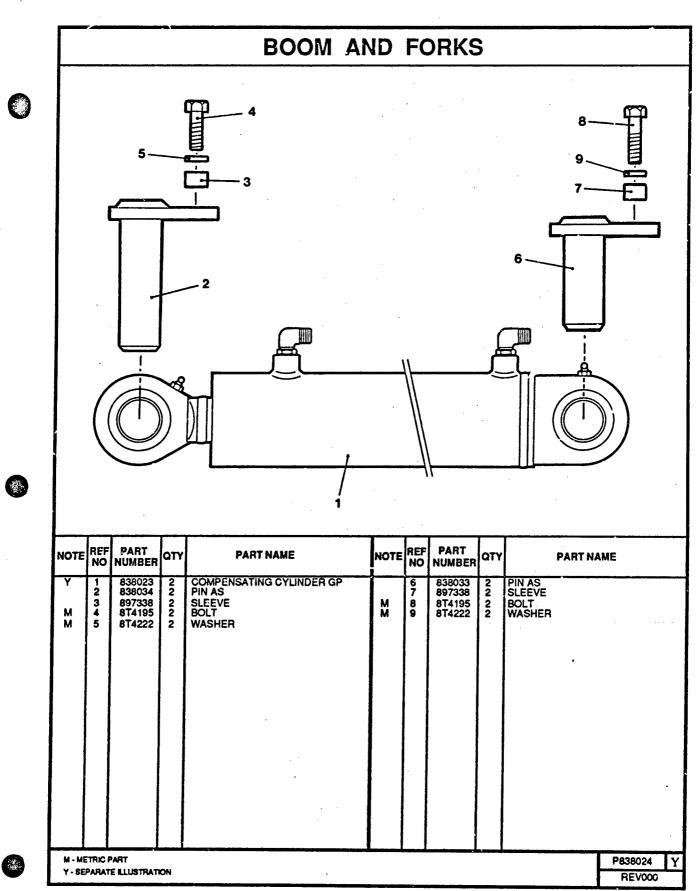
	BOOM AND FORKS												
			9	85843					_	985845			
NOTI		PART NUMBER	ατγ	PART NA	AME	NOTE	REF	PART NUMBER	ατγ	PART NA	ME		
	1 2	985844 985509	1 2	WEAR PAD INSERT			1 2	985846 985509	1 2	WEAR PAD			

985843 AND 985845 WEAR PAD GROUPS Part of 985889, 985979, 986070 Boom Services Groups.



1.0

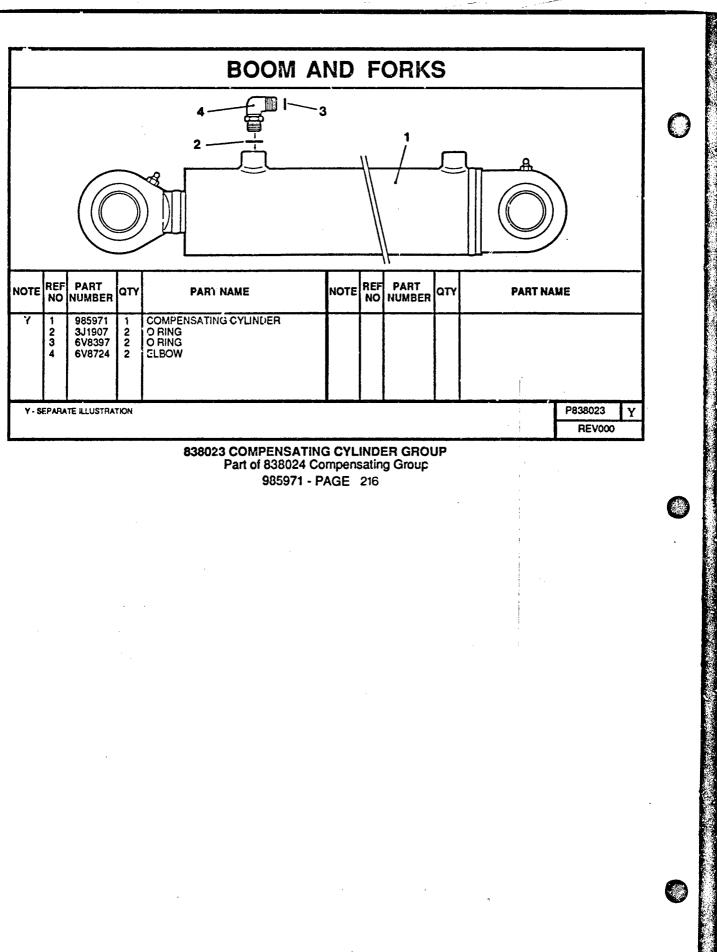
815728 ROLLING HOSE GROUP Part of 985889 No 1 Boom Section Group (with Compensating Cylinders)

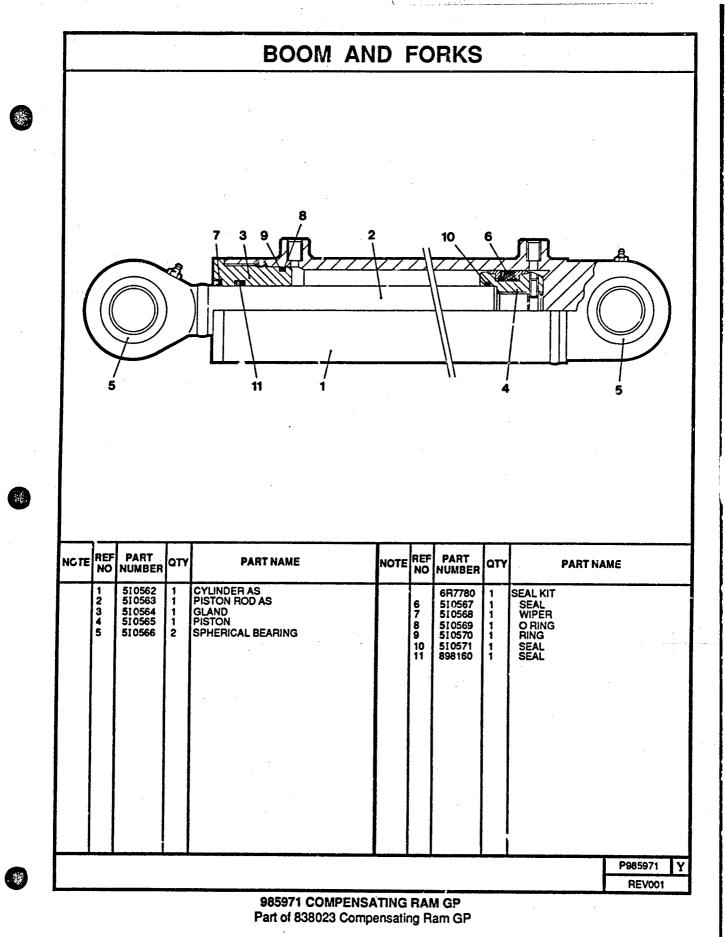


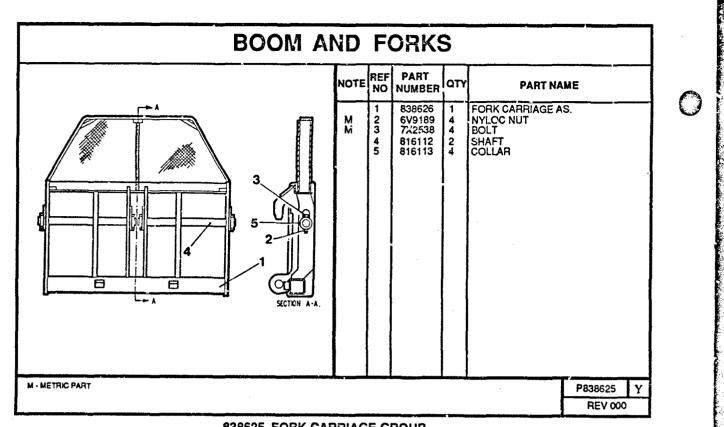
..... States - Strates

and the second second second second second

838024 COMPENSATING GROUP 838023 - PAGE 215.

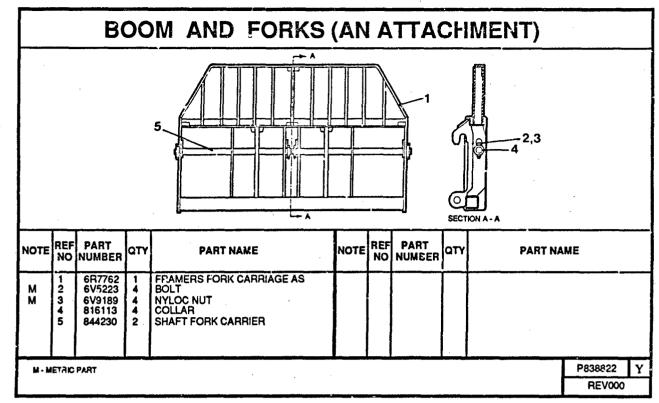




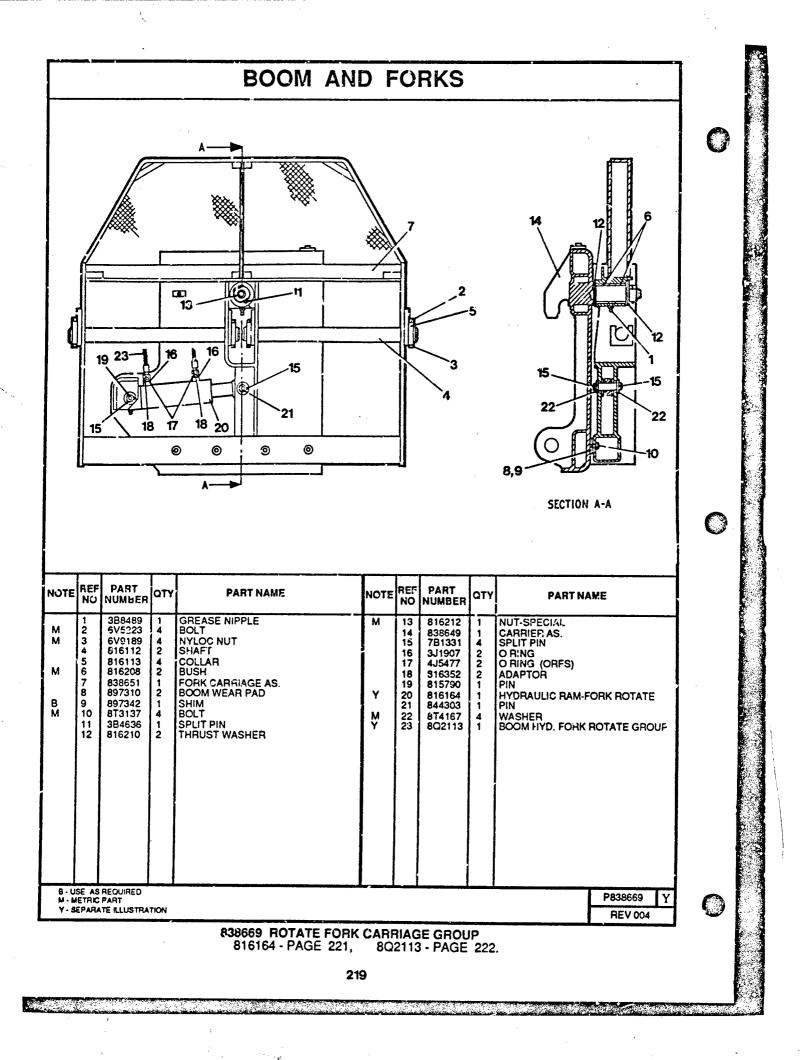


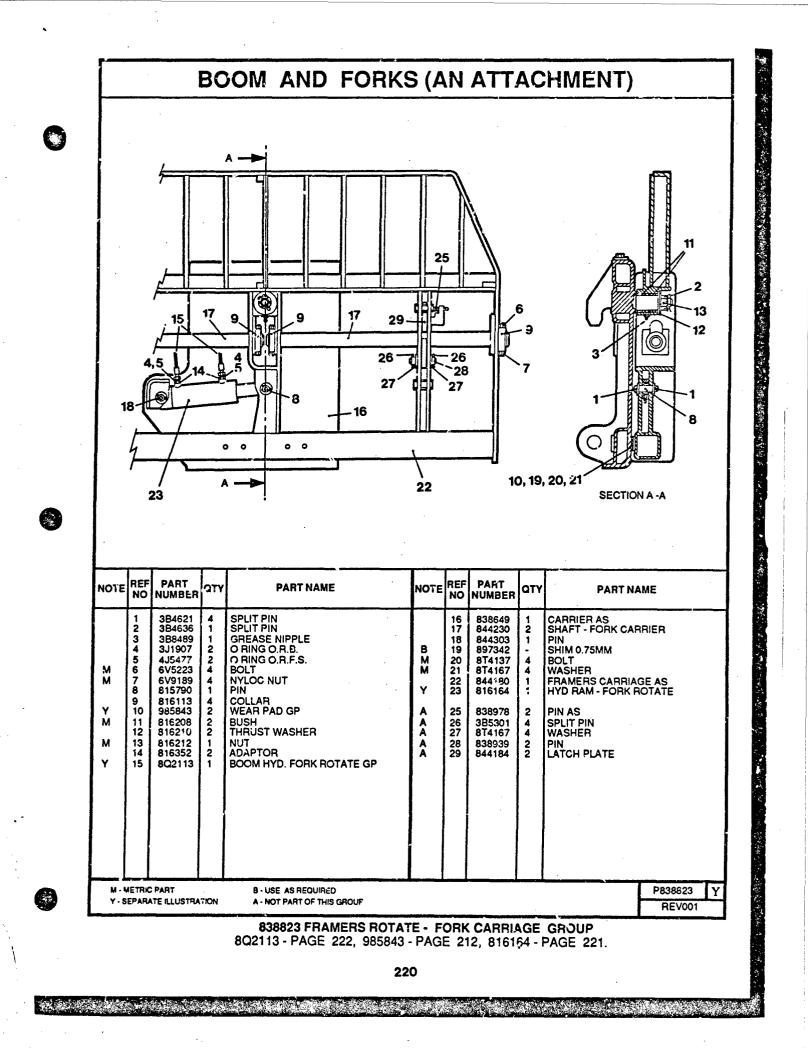
Ċ

838625 FORK CARRIAGE GROUP

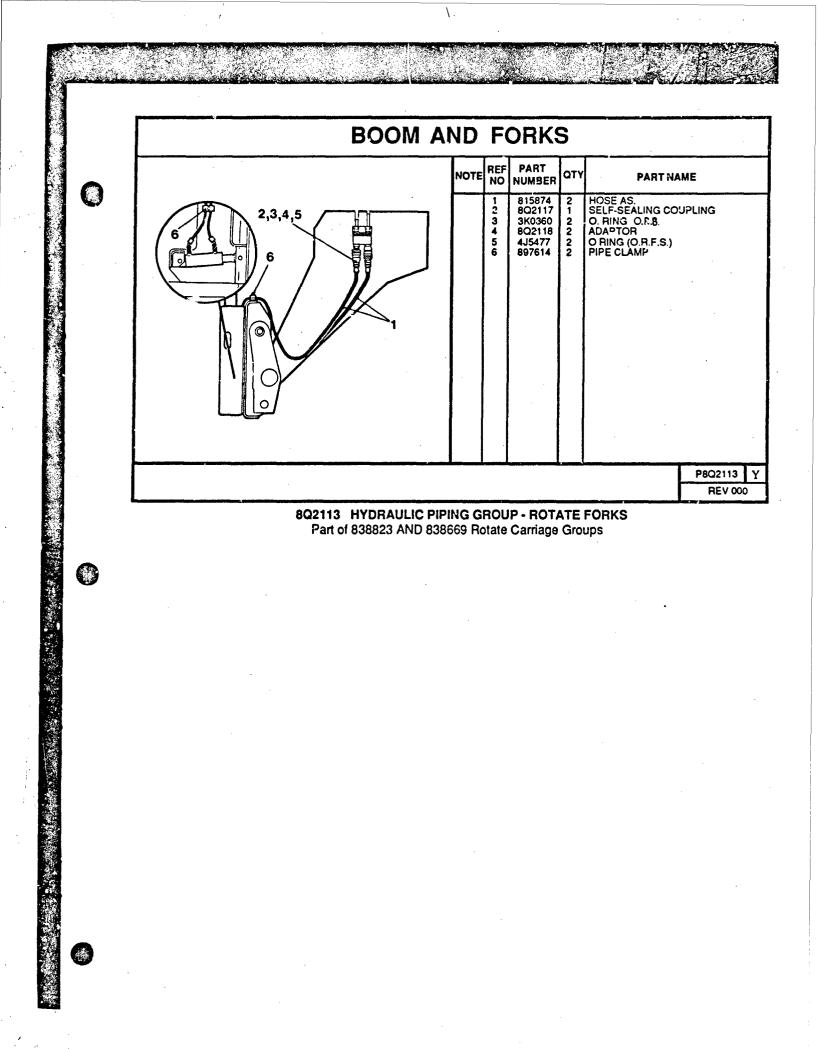


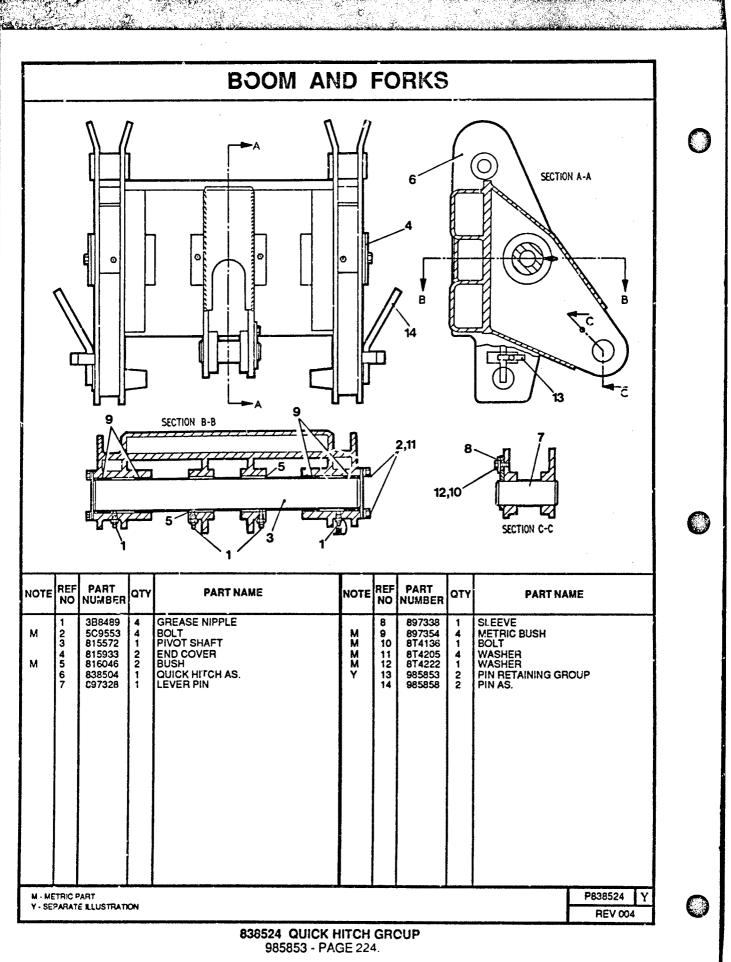
838822 FRAMERS FORK CARRIAGE GROUP





				11	2		11			
	5			1	7		3			
				r					T	
+	REF NO	PARY NUMBER 510572	Q ТҮ 1	CYLINDER AS	NOTE	REF	PART NUMBER			·
+		PARY NUMBER 510572 510573 510574 510575 975442	_		NOTE	REF NO 6 7 8 9 10 11 12	PART NUMBER 6R7782 510568 510569 510576 510576 510577 510578 898160	QTY 1 1 1 1 1 2 1	PART NAME SEAL KIT WIPER O RING RING SEAL O RING SEAL	
+	1 2 3 4	510572 510573 510574		CYLINDER AS PISTON ROD AS GLAND PISTON	NOTE	6 7 8 9 10 11	6R7782 510568 510569 510570 510576 510577 510578	1 1 1 1 1 2	SEAL KIT WIPER O RING RING SEAL O RING RING	
+	1 2 3 4	510572 510573 510574		CYLINDER AS PISTON ROD AS GLAND PISTON	NOTE	6 7 8 9 10 11	6R7782 510568 510569 510570 510576 510577 510578	1 1 1 1 1 2	SEAL KIT WIPER O RING RING SEAL O RING RING	Y O





うち こう うちののない

の法とないの

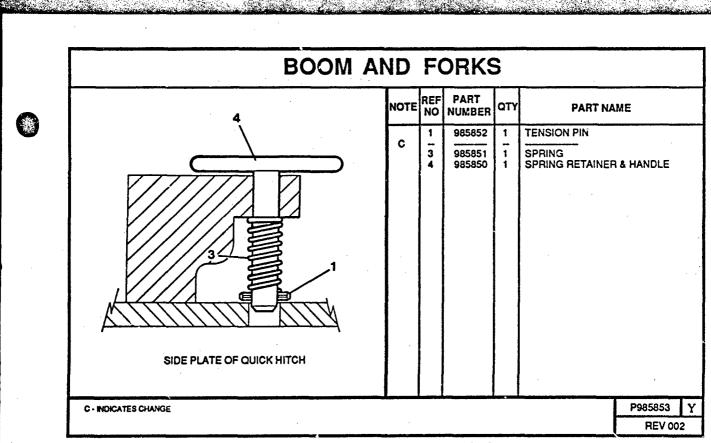
う いみずみ 第二部 第二部 ないやい

のないないない

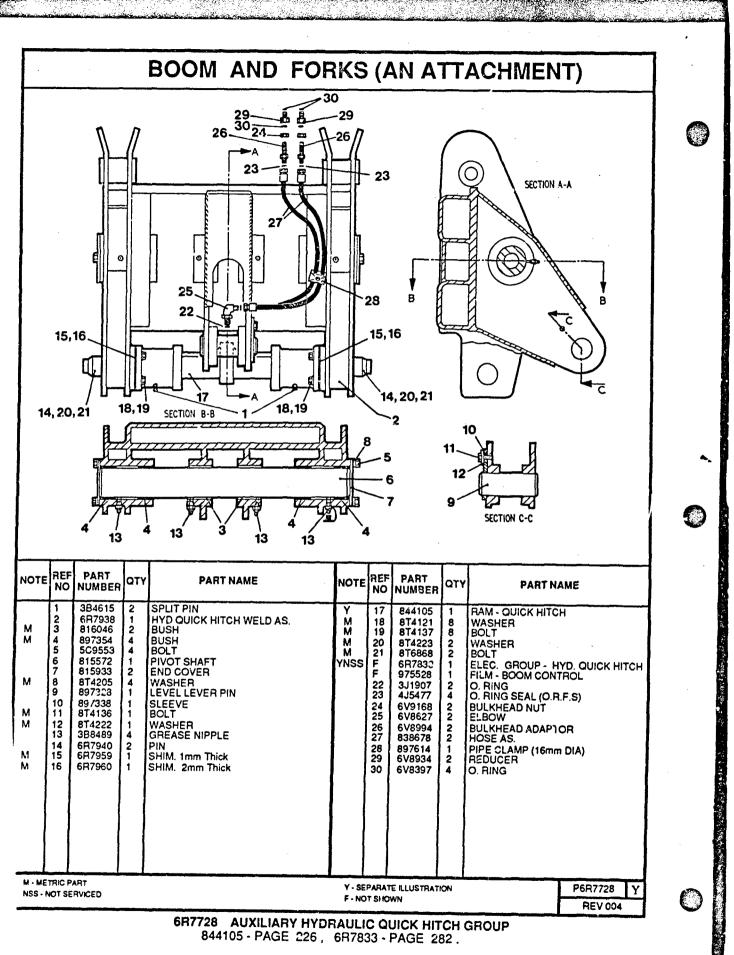
ł

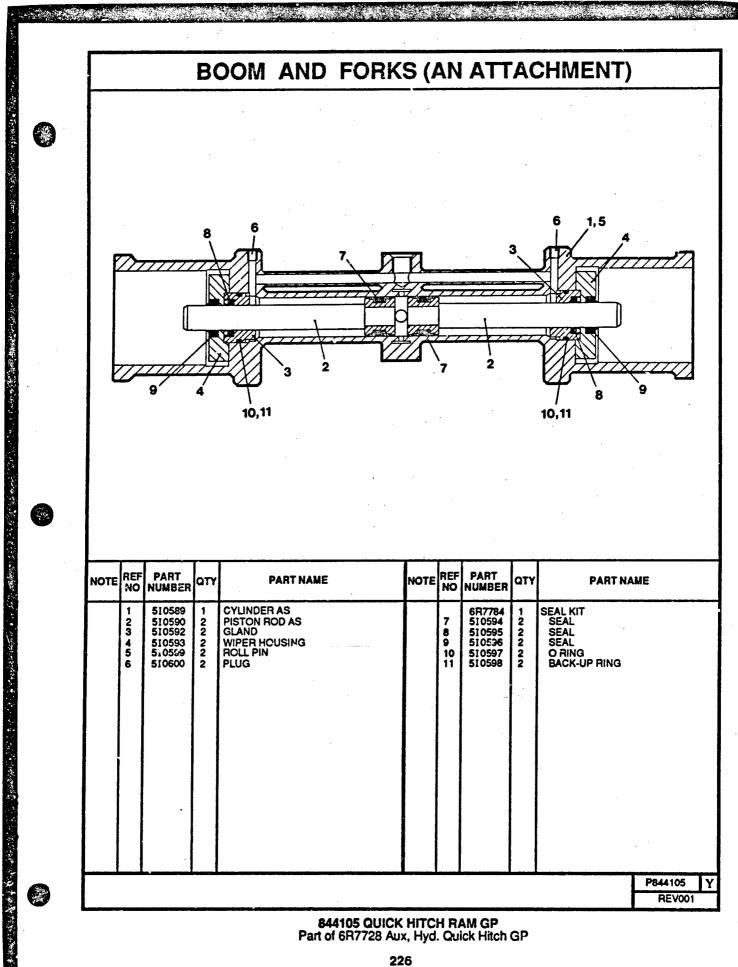
ので、「「「「「」」

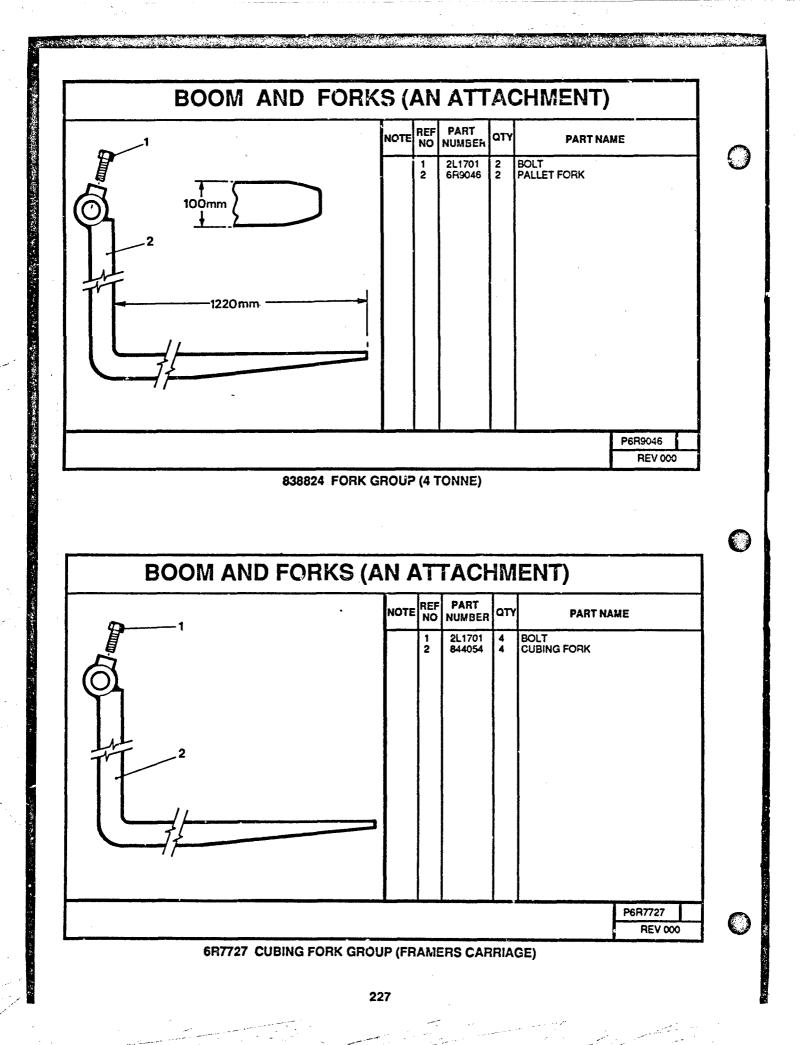
199

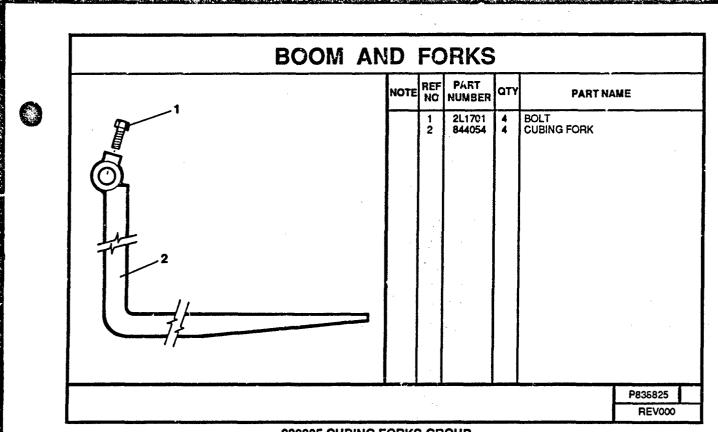




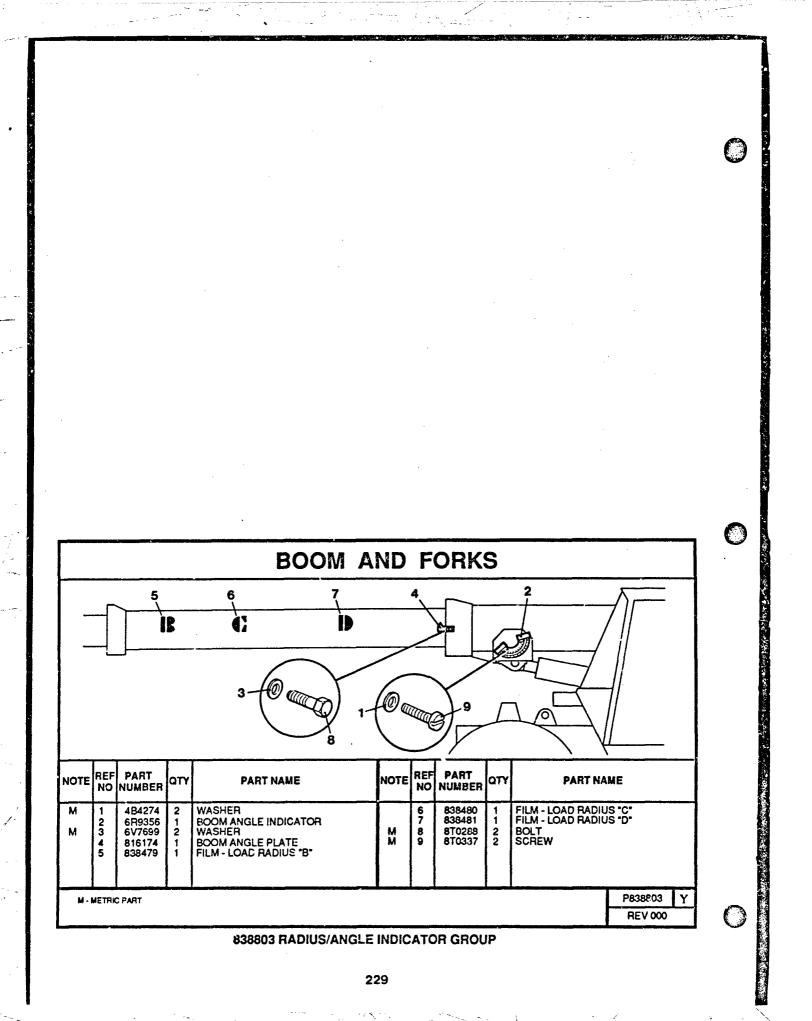


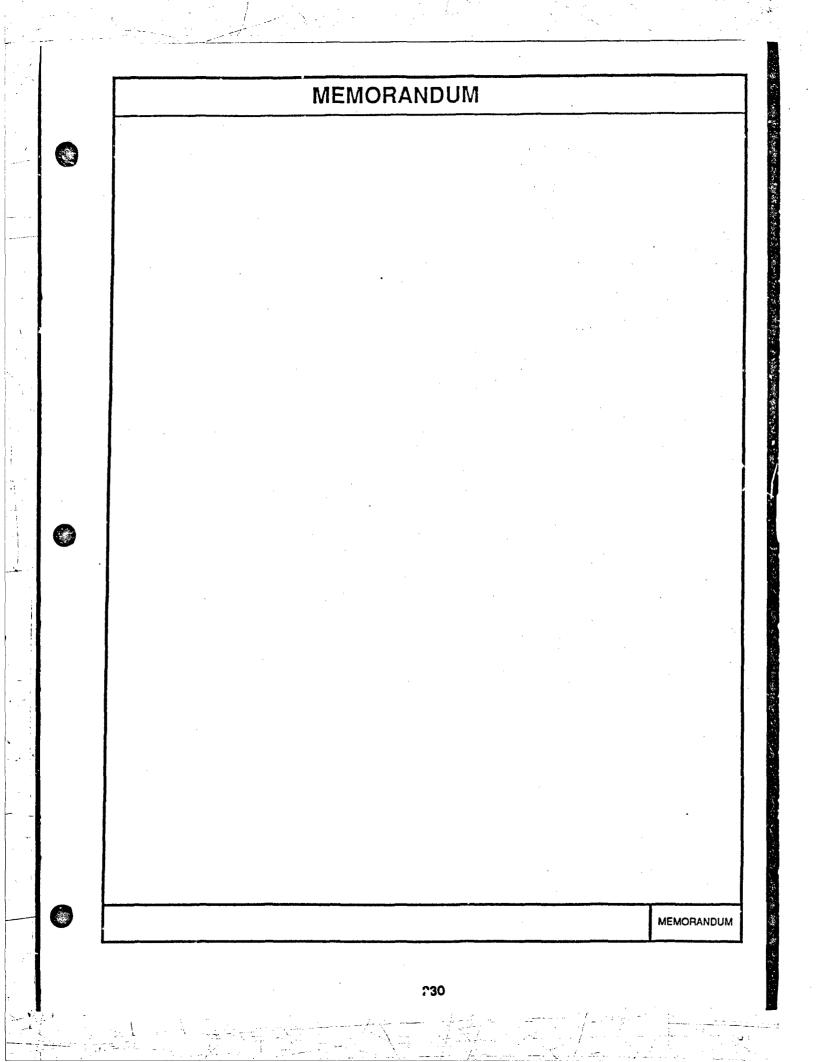


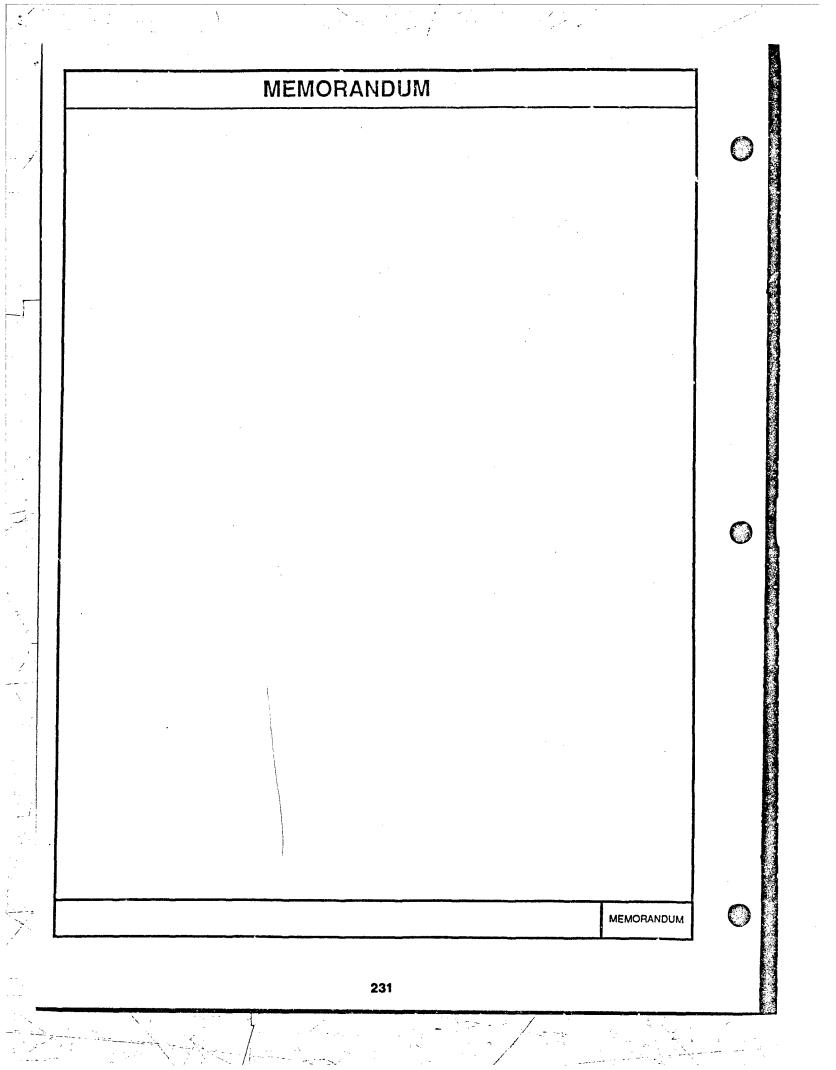




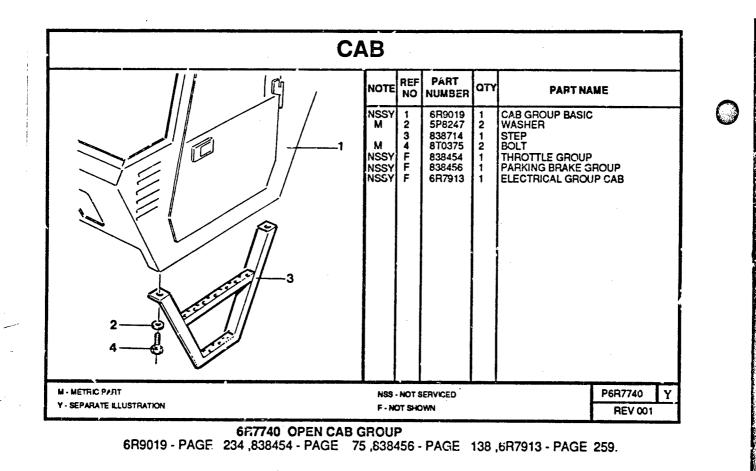
838825 CUBING FORKS GROUP





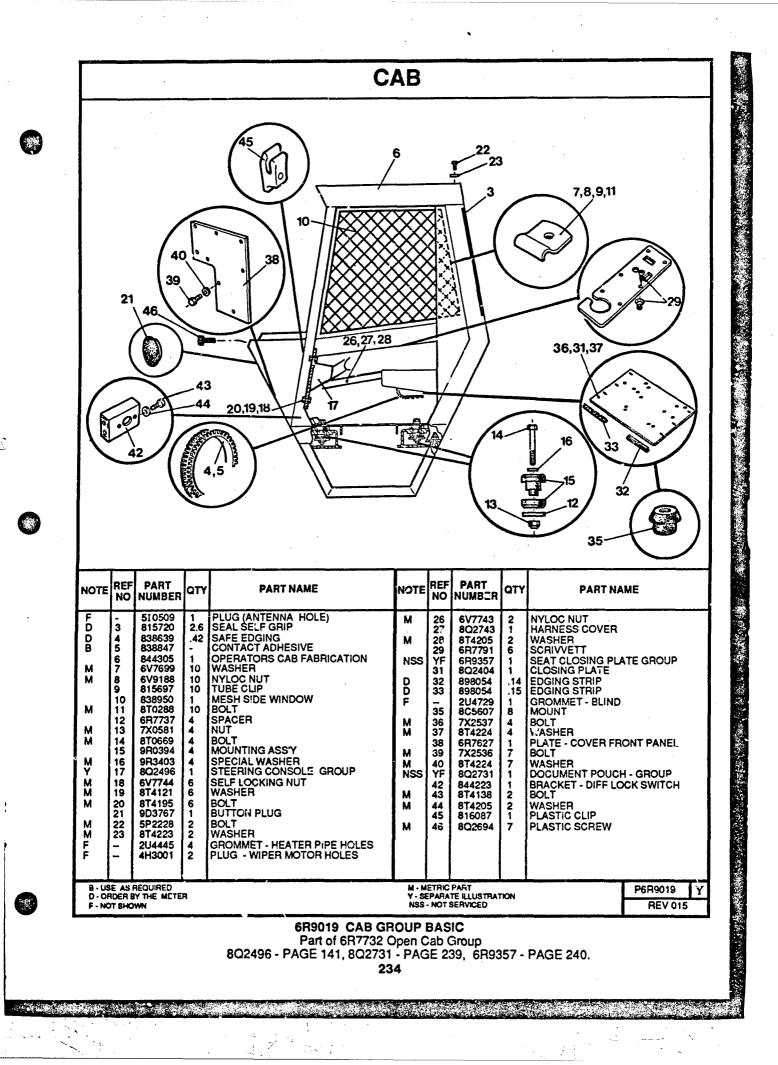


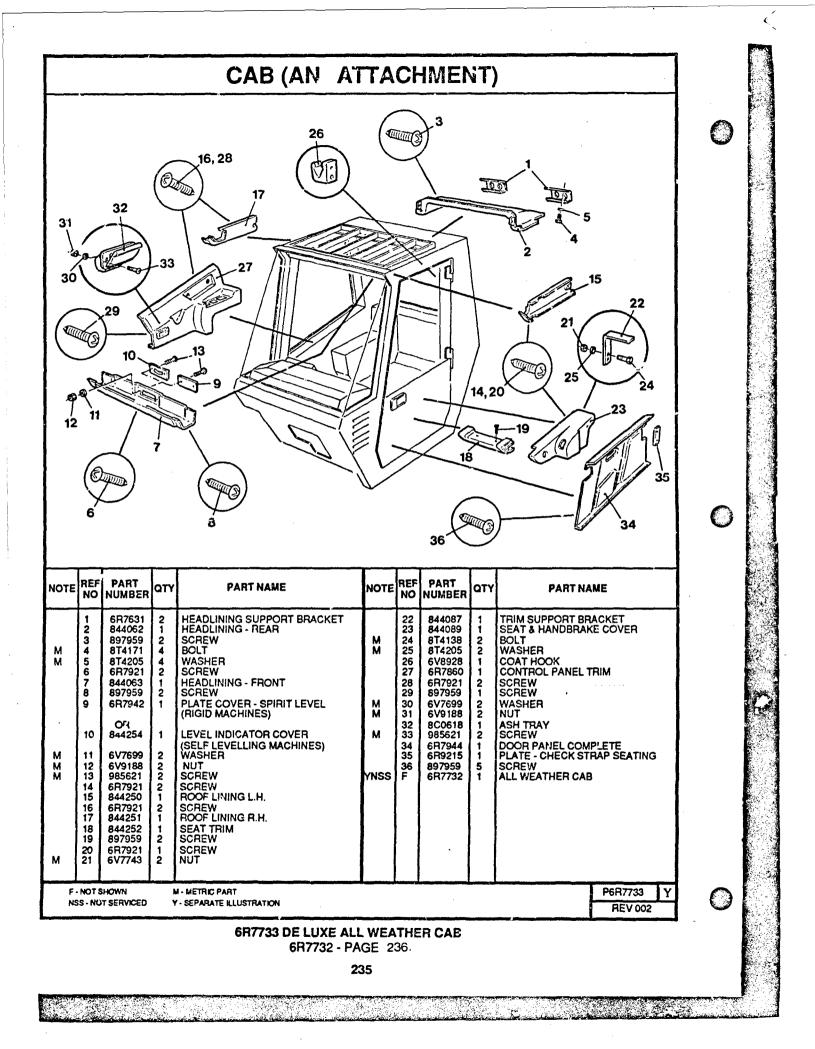
		·	· ·		
	• .	• •			
	· ,				
0				·	
					·
					MEMORANDUM
		232			

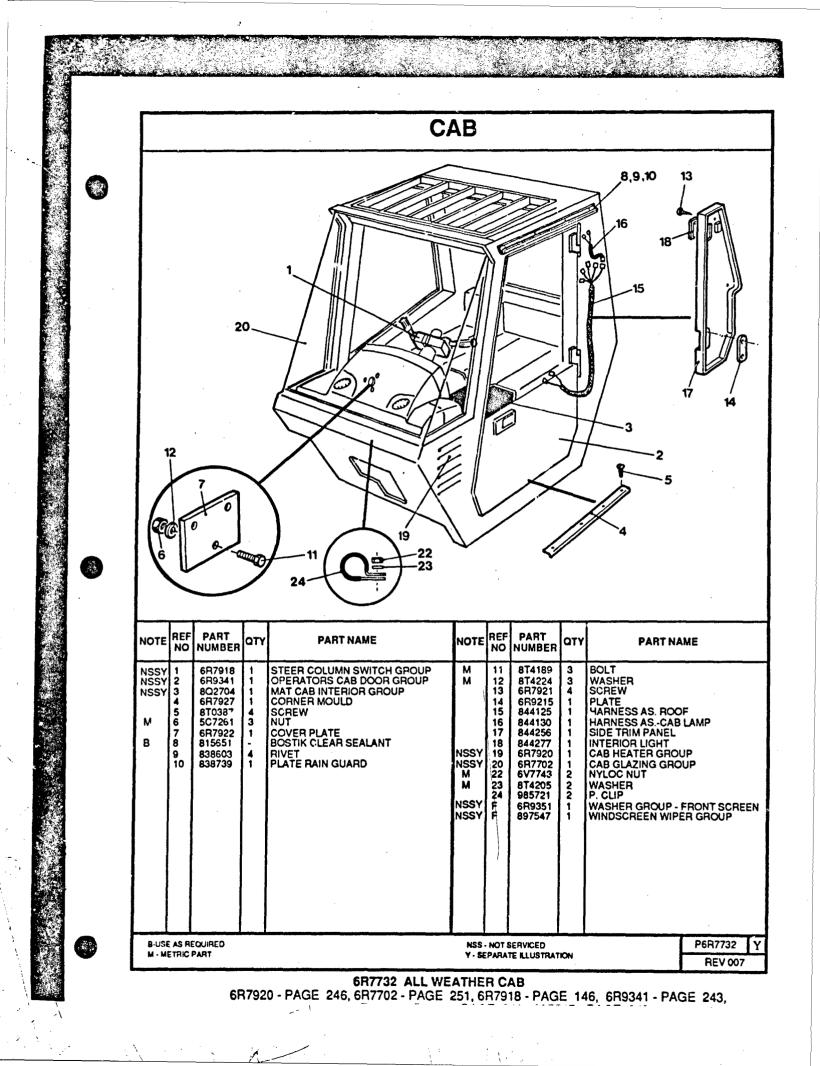


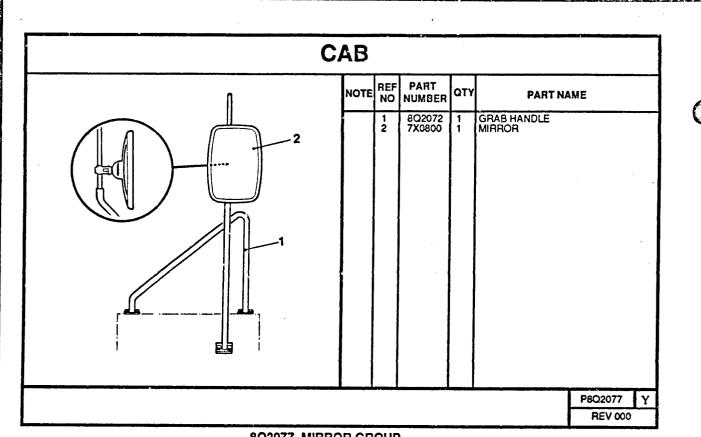
ţ

 \bigcirc







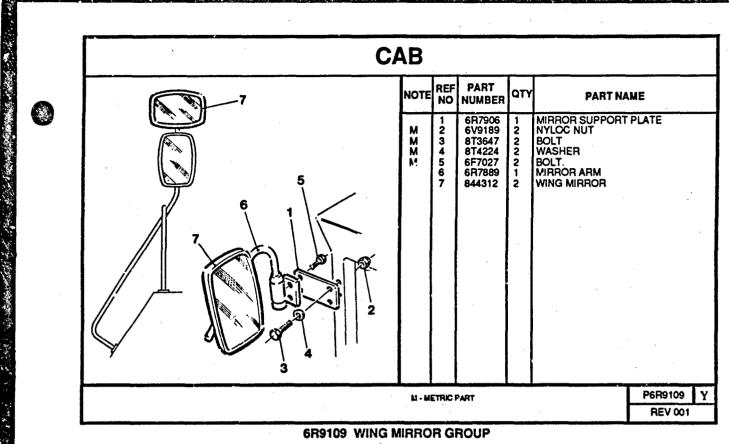


8Q2077 MIRROR GROUP

14

11 1

)



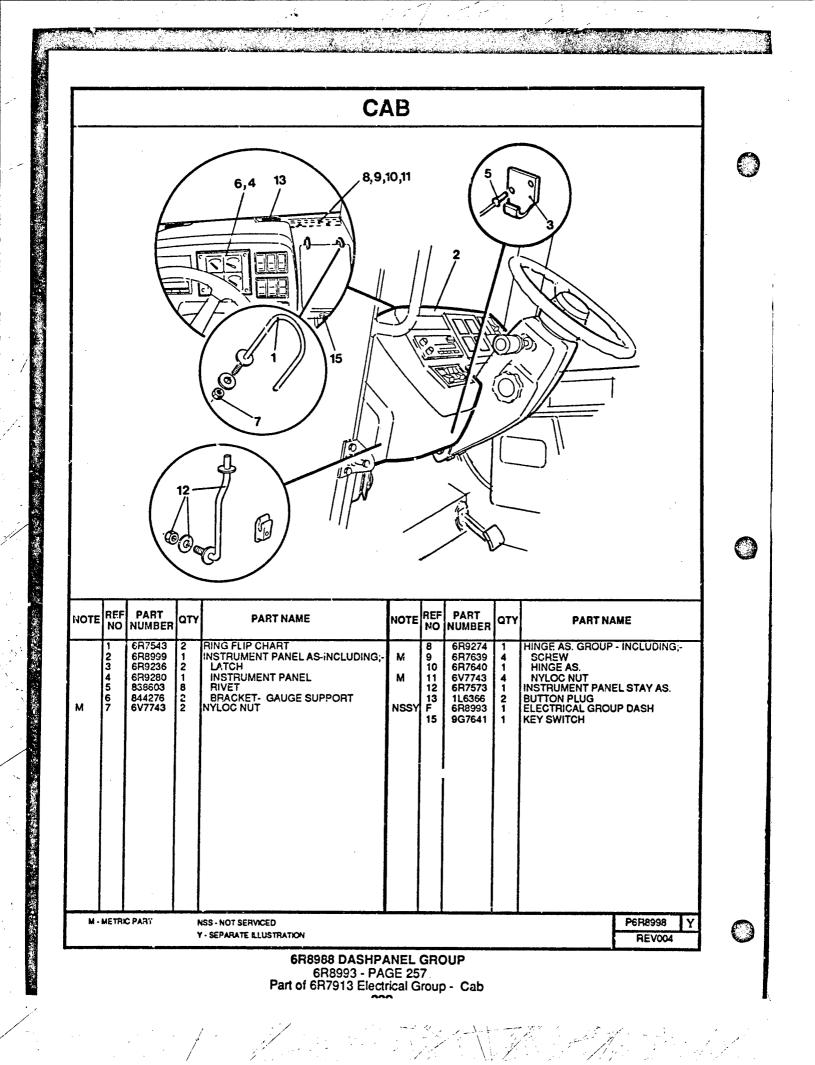
11-10

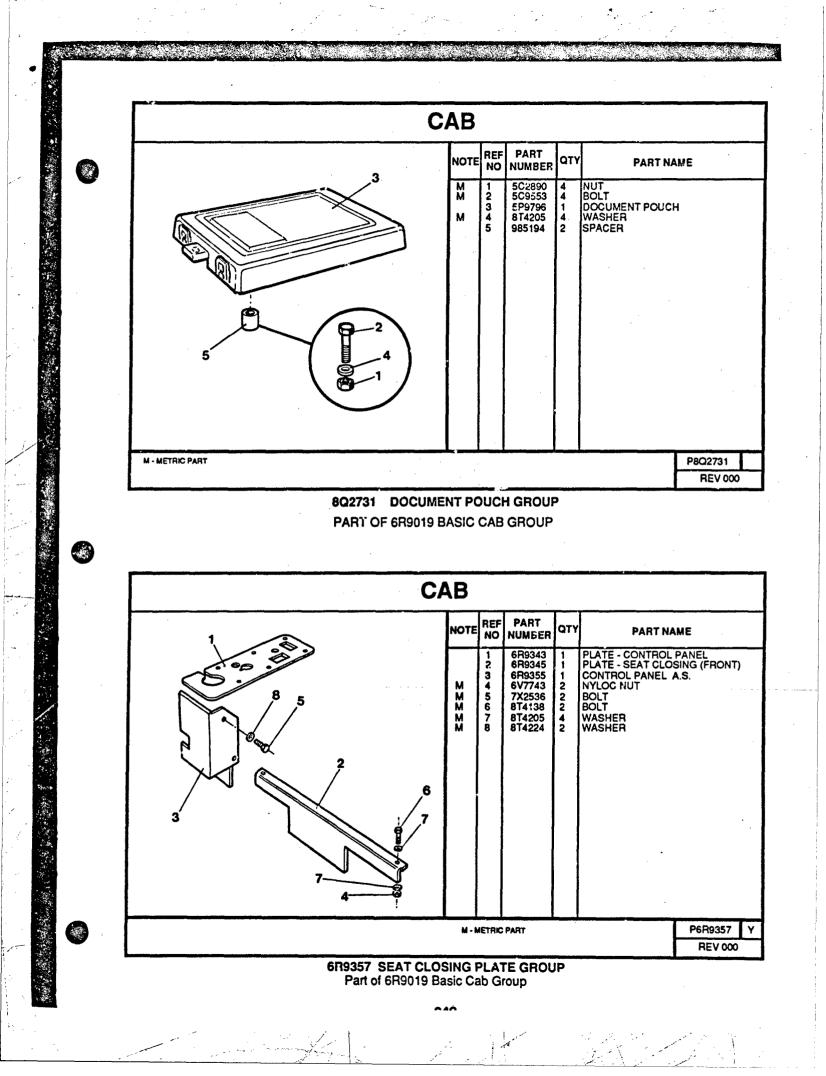
1.4

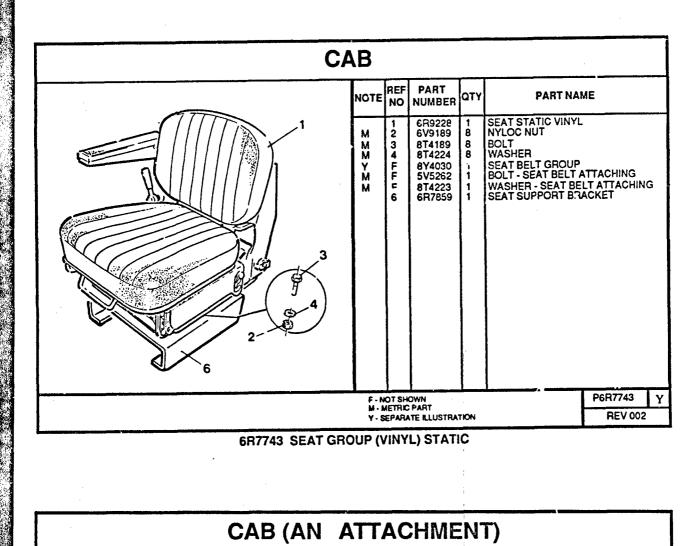
23 -

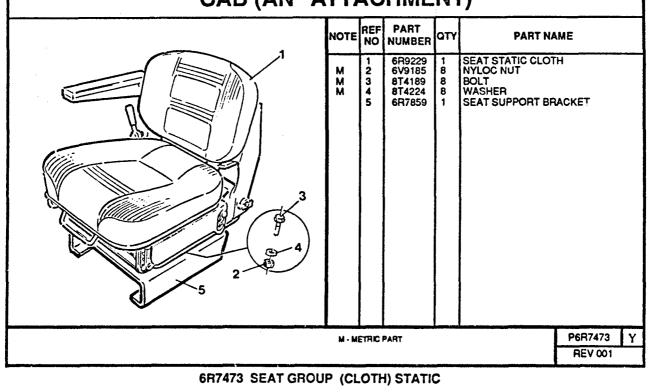
194

6R9109 WING MIRROR GROUP



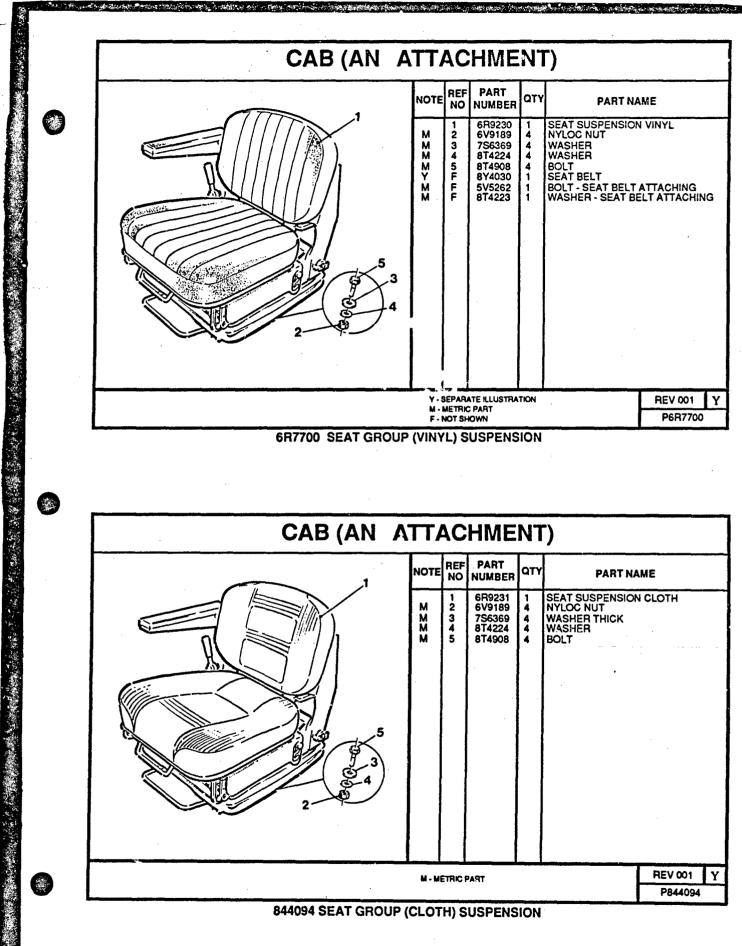


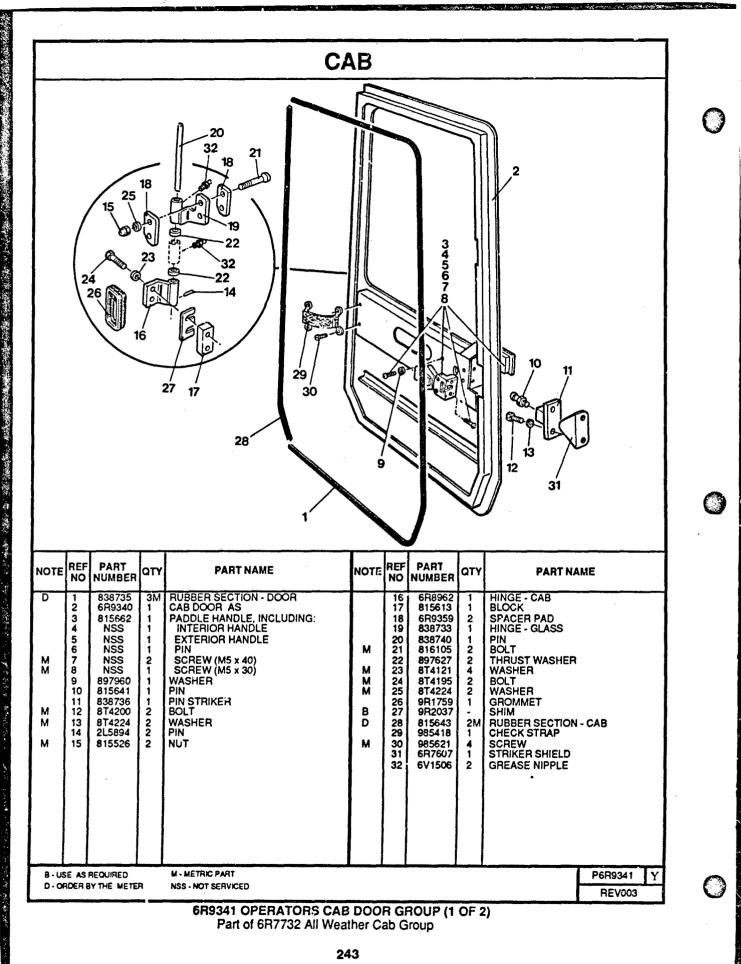




Ð

941





.....

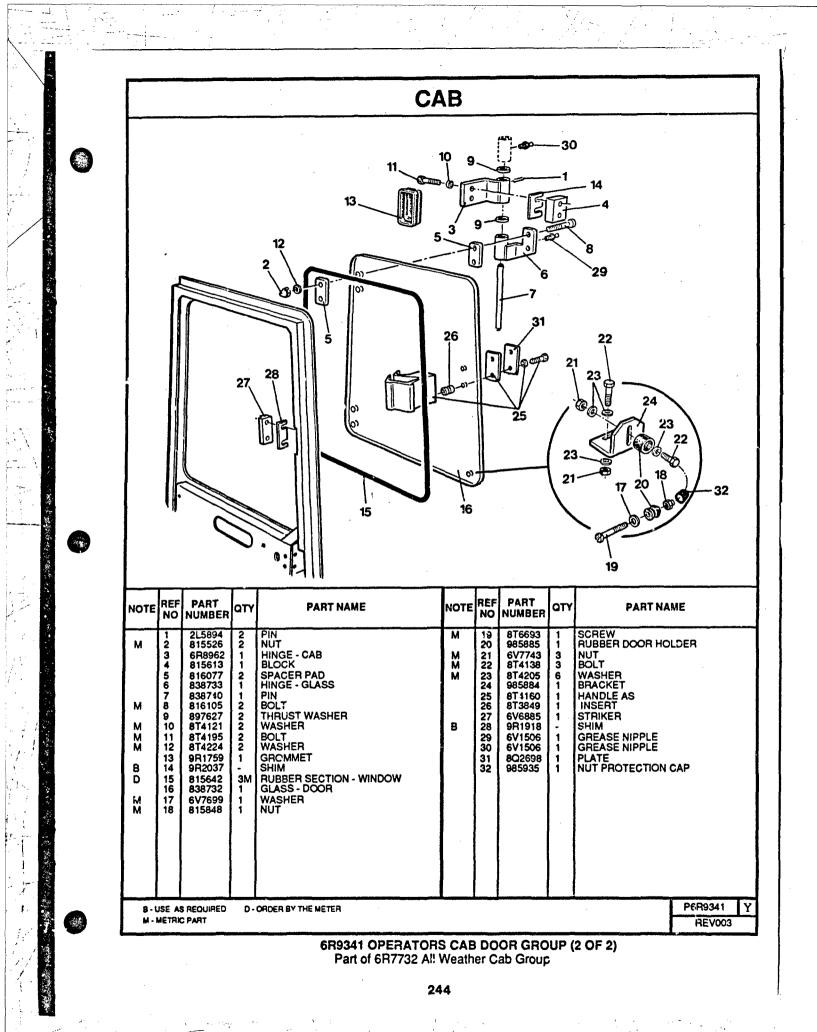
.... .

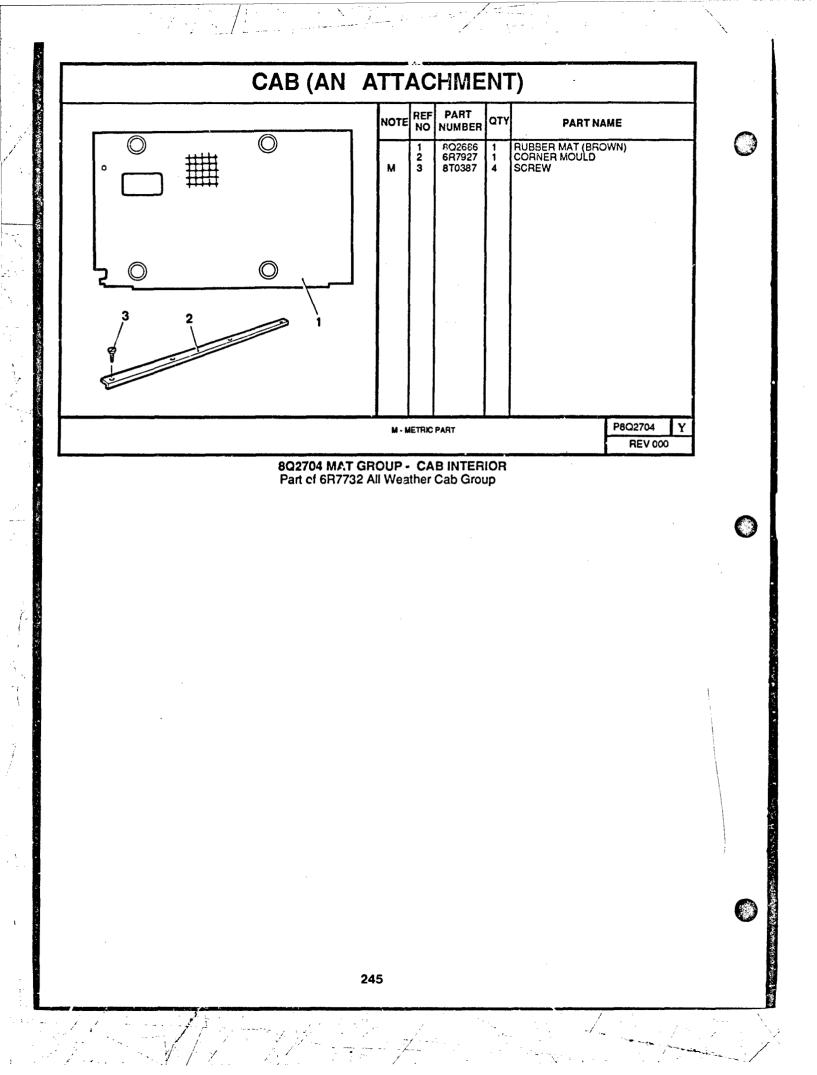
100

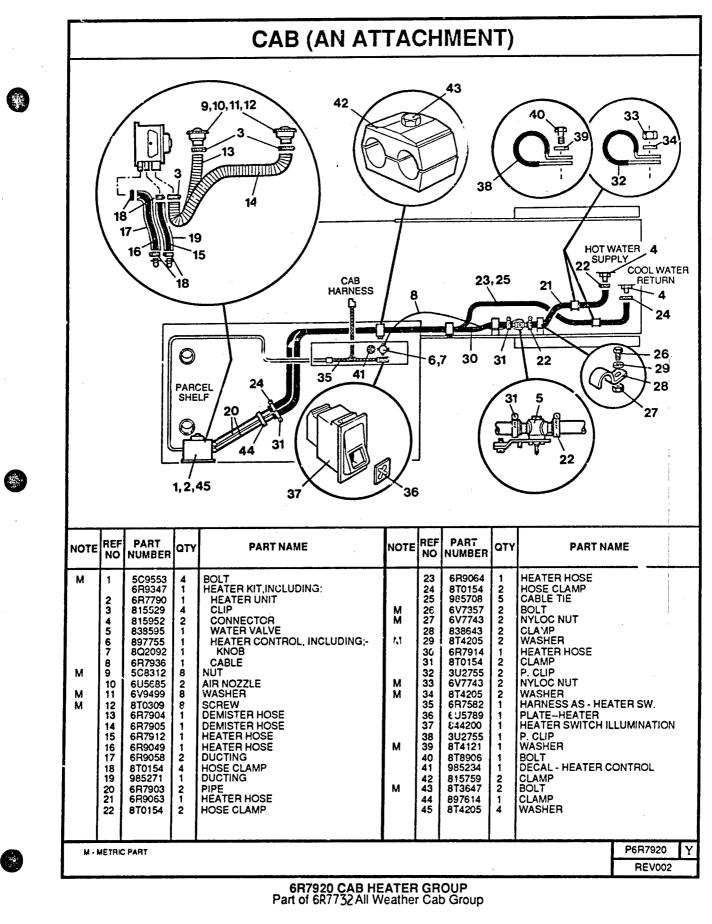
ないいたいと

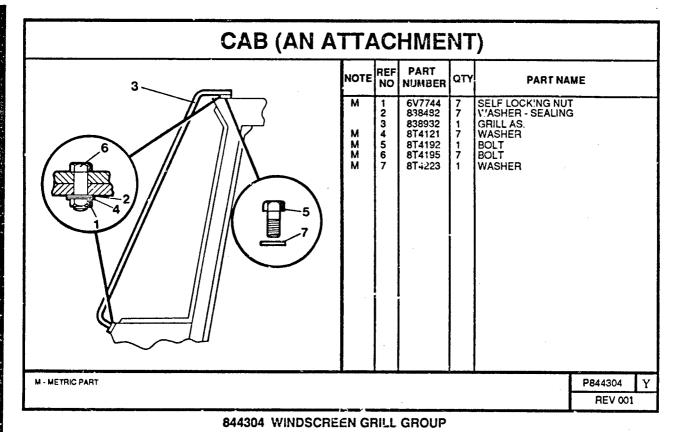
20

. Property.

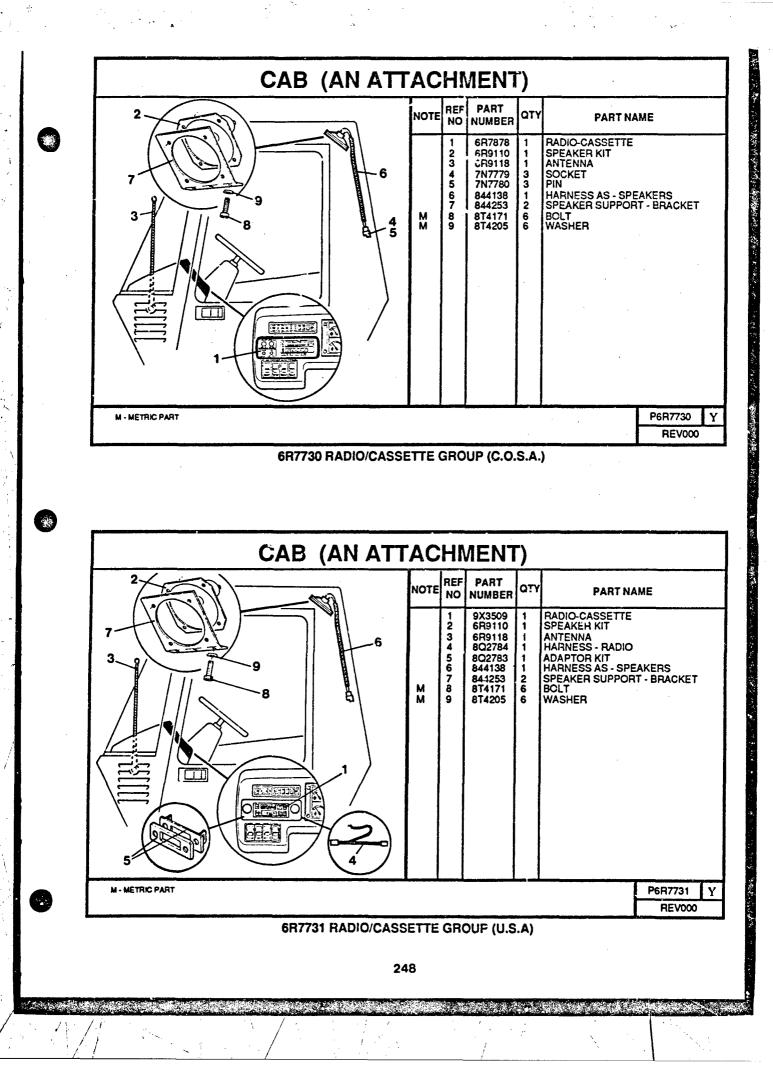


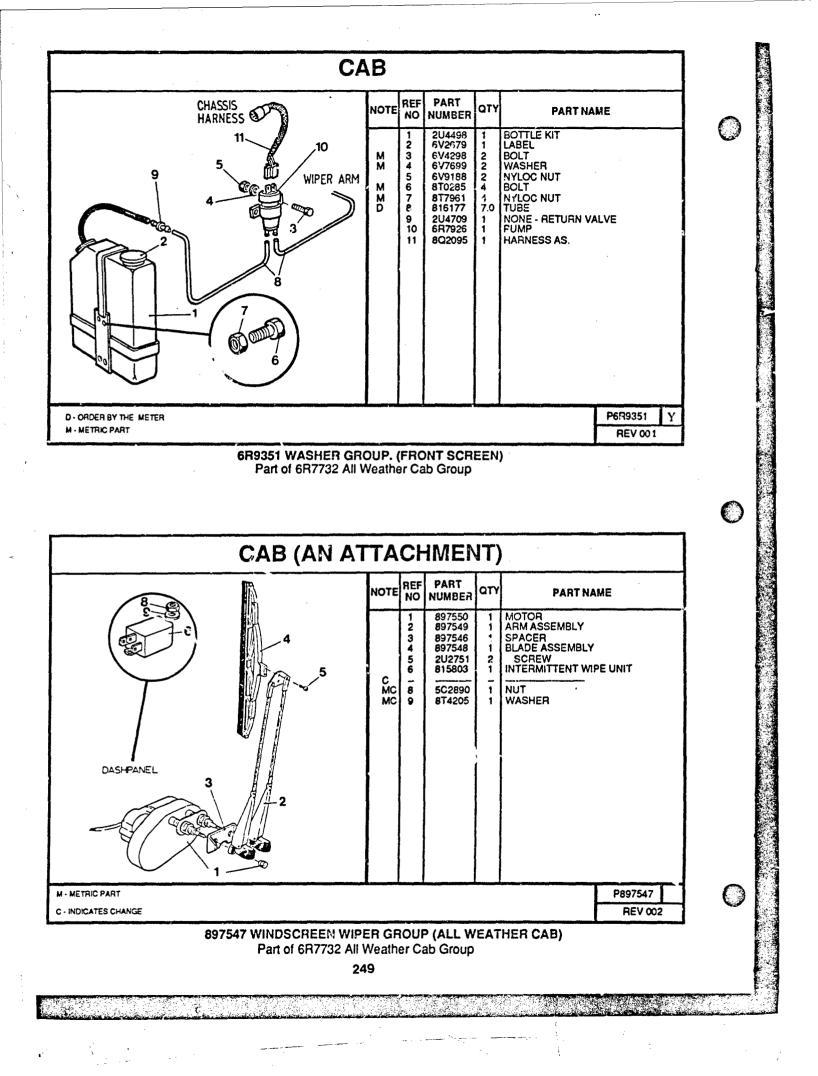


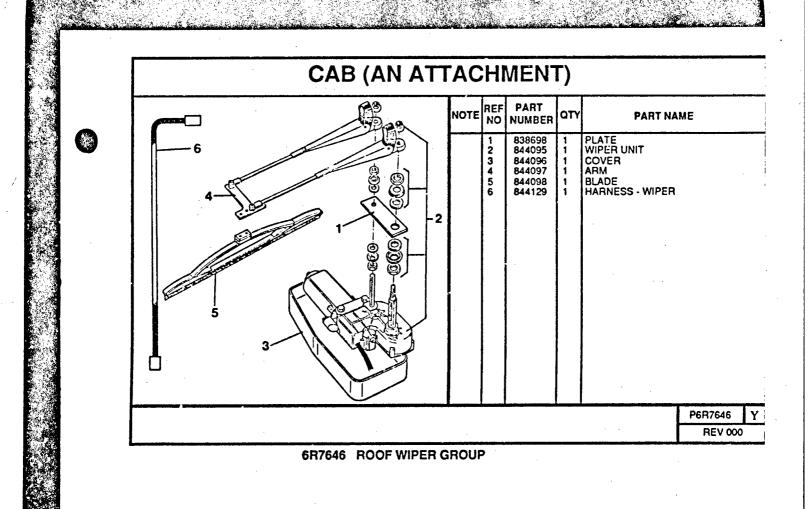


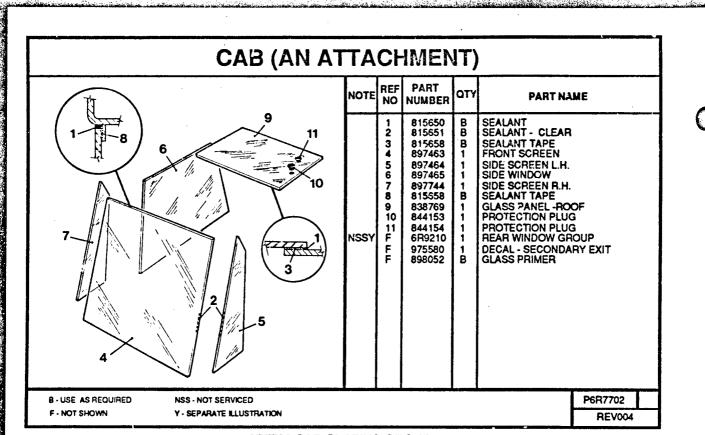


٠.



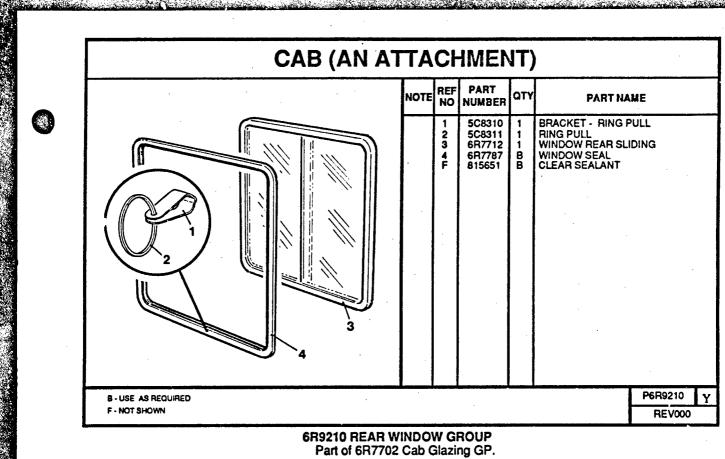






6R7702 CAB GLAZING GROUP Part of 6R7732 Cab Glazing Group 6R9210 - PAGE 252

1.27



MEM	ORANDU	IM			
		·			
			,		
			·		
				•	
				MEMOR	

7.

÷

į

Ì

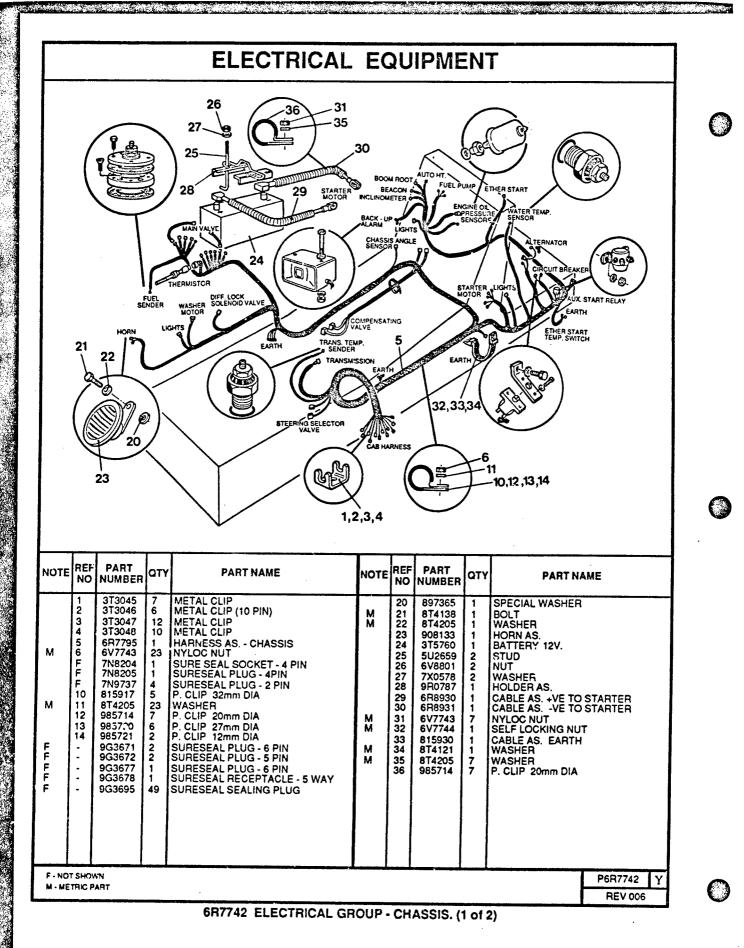
1

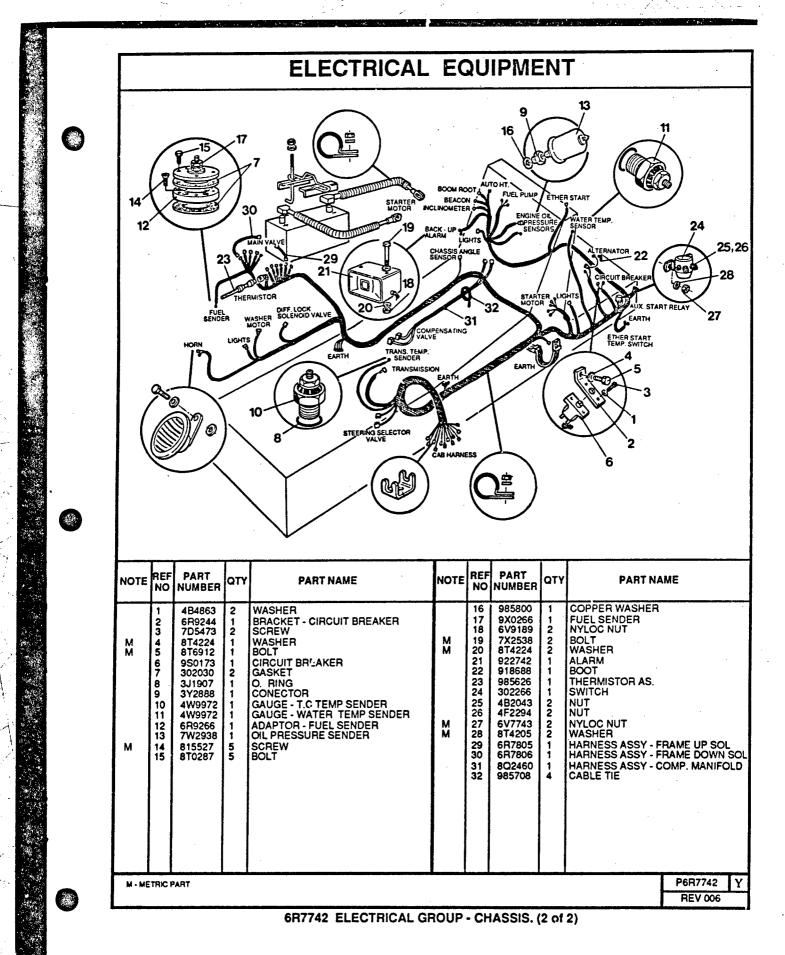
252

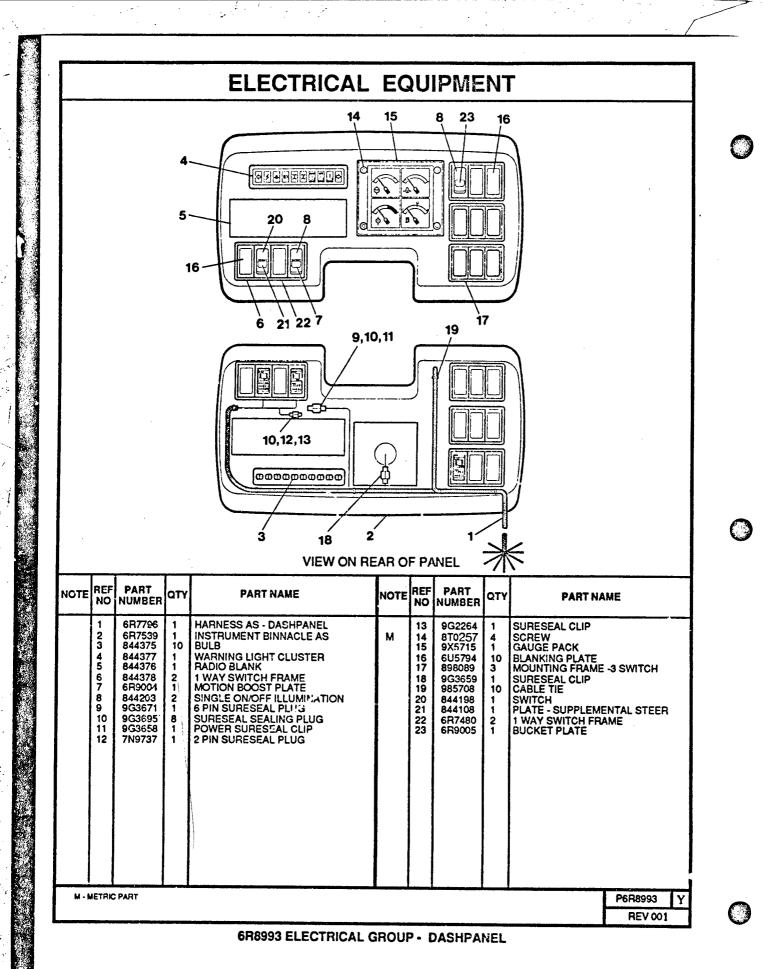
ĥ

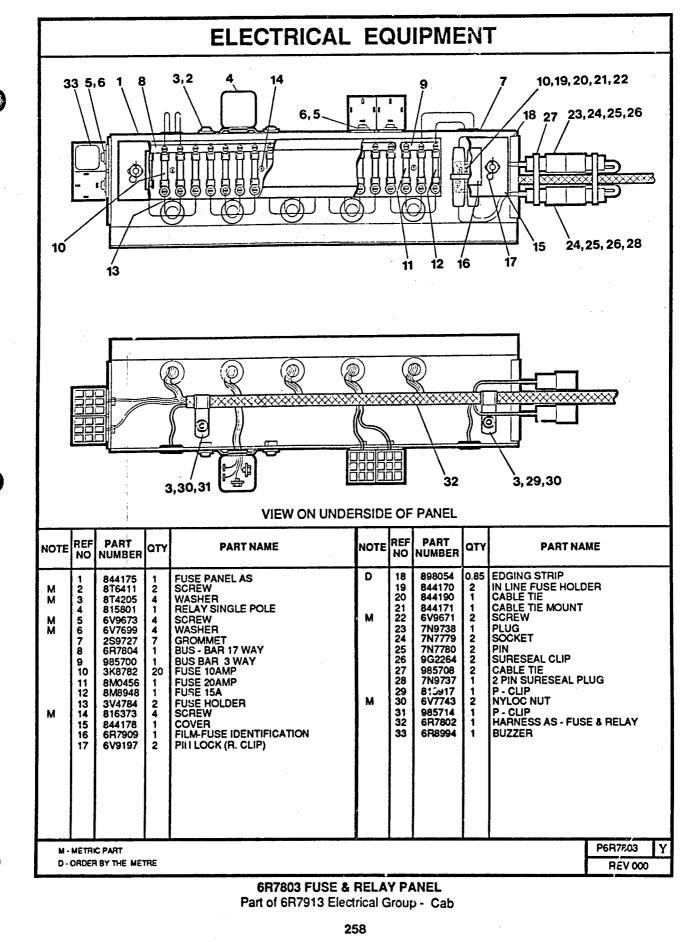
· · · · · · · · · · · · · · · · · · ·			
	MEMORANDU	M	
	· - · - · · · ·		
		•	
			MEMORAN

()









والمرجب

- _ -

ź

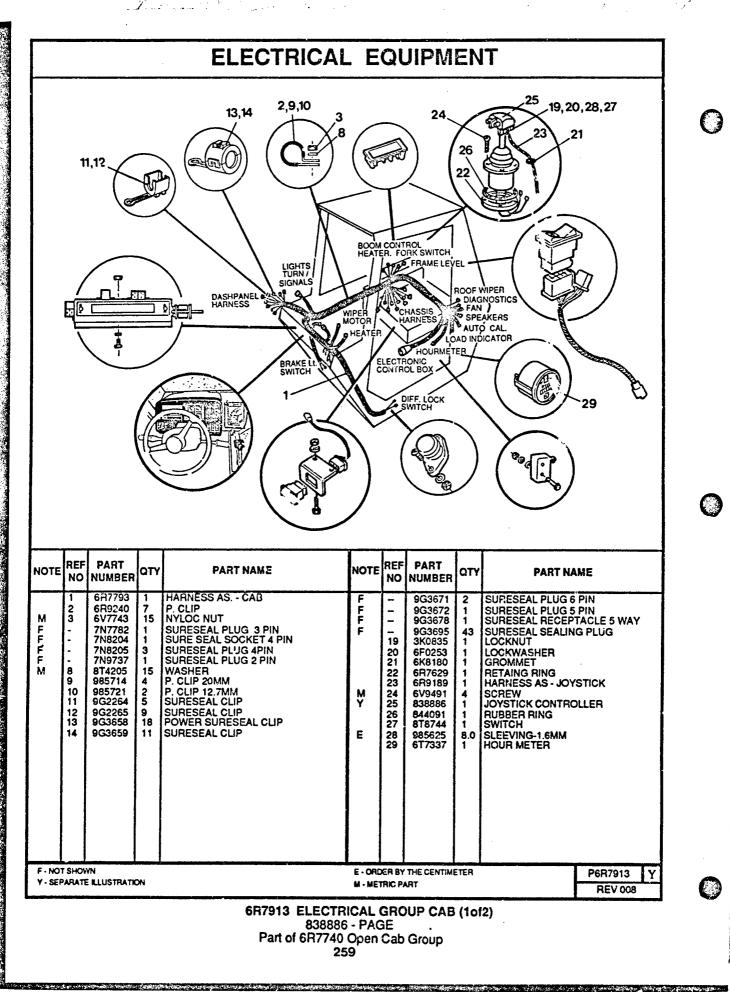
Solution and the second

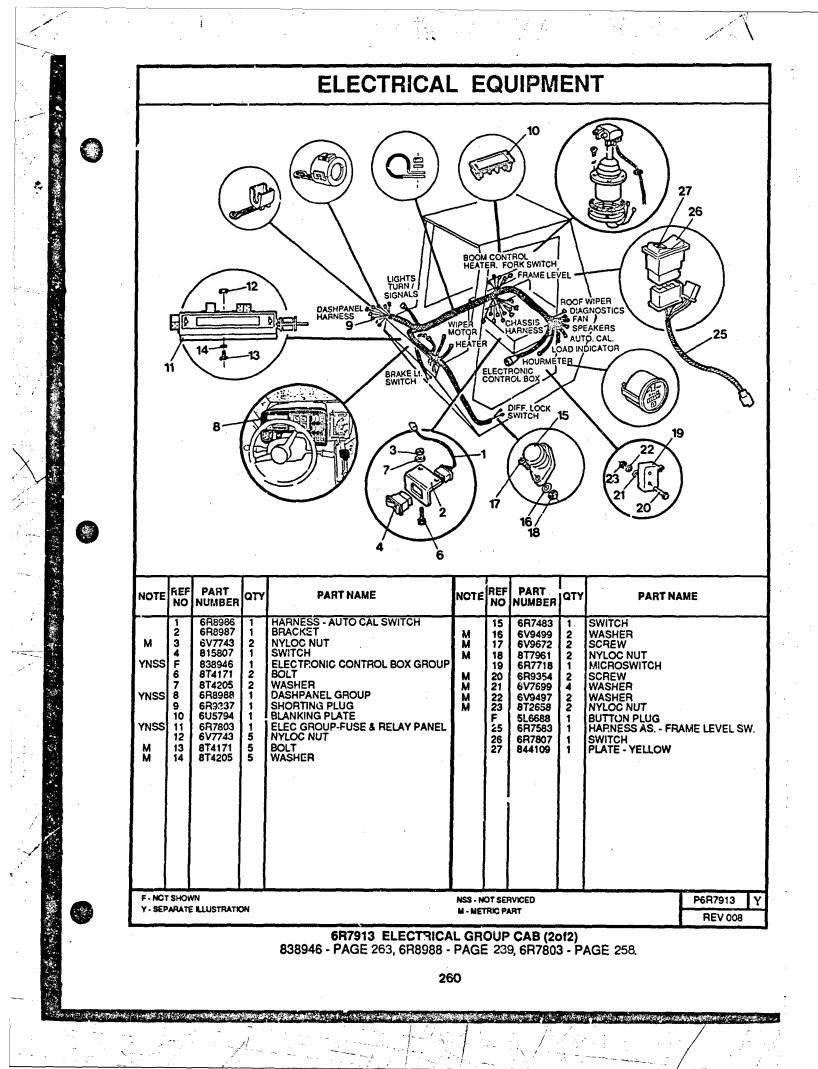
14

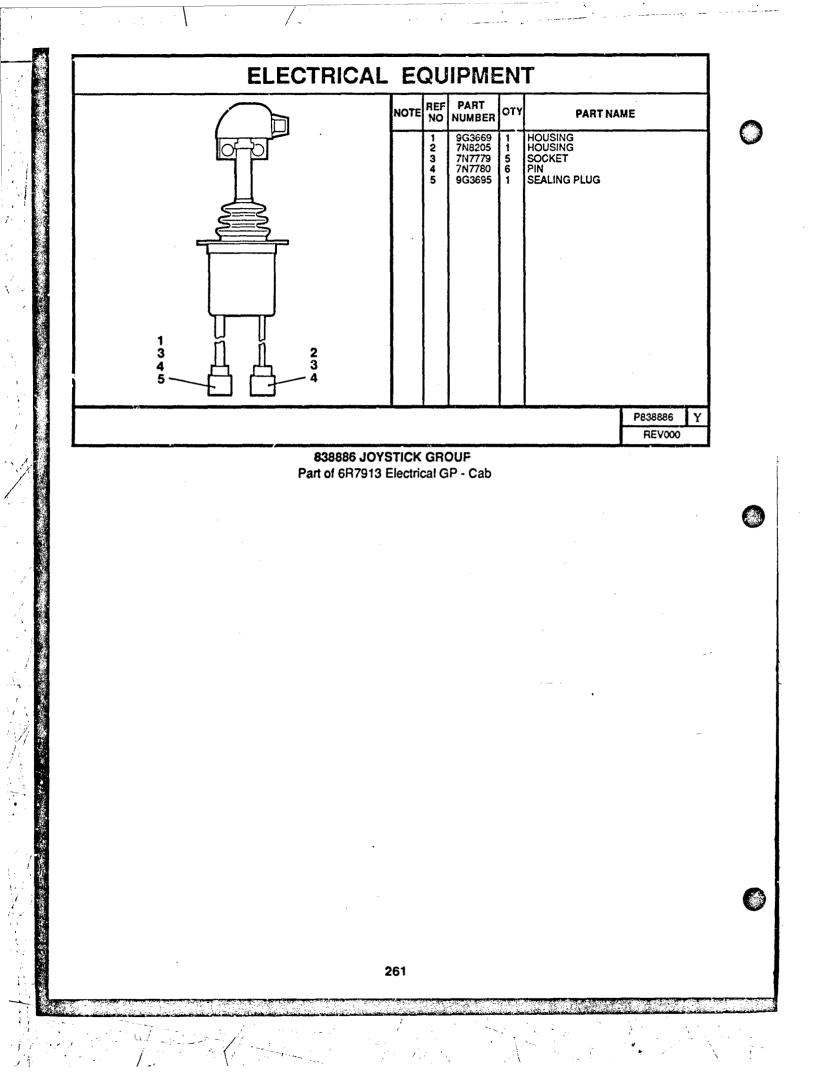
1

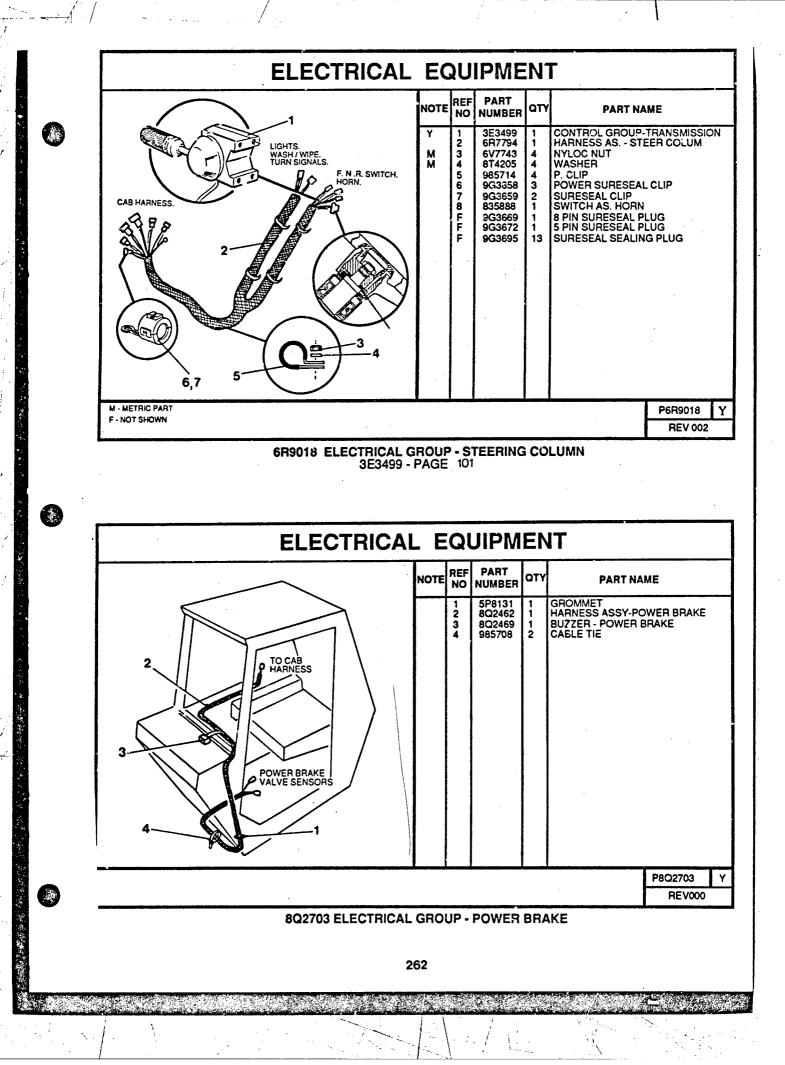
1.1

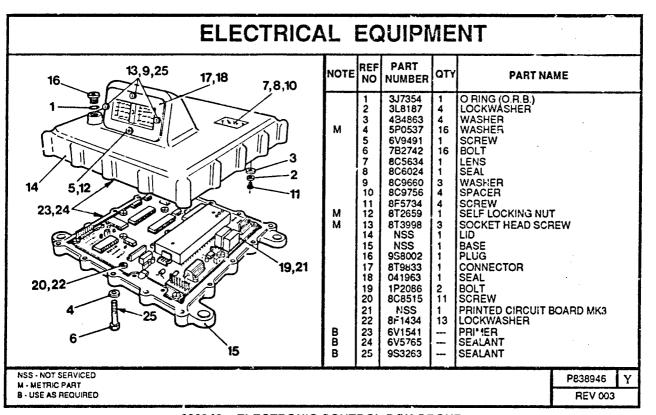
.





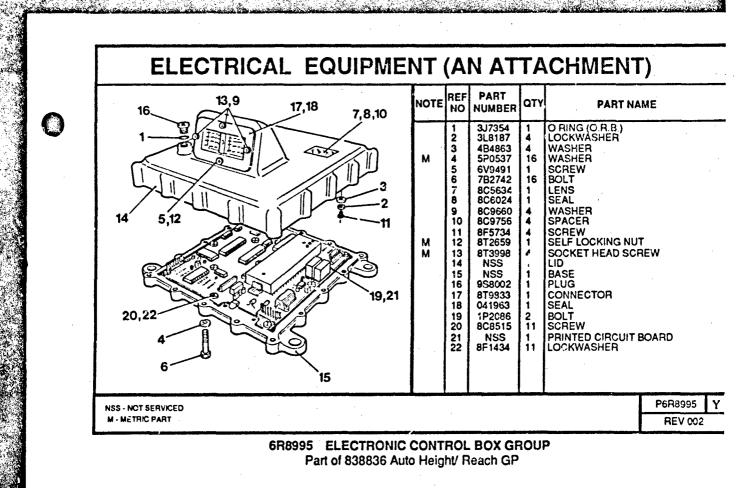


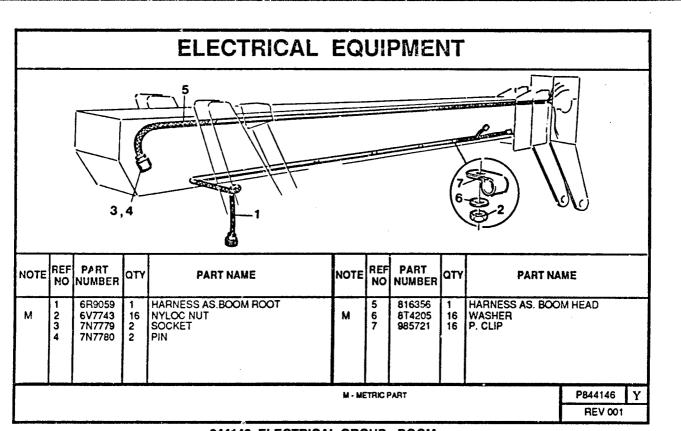




Promise with the factor

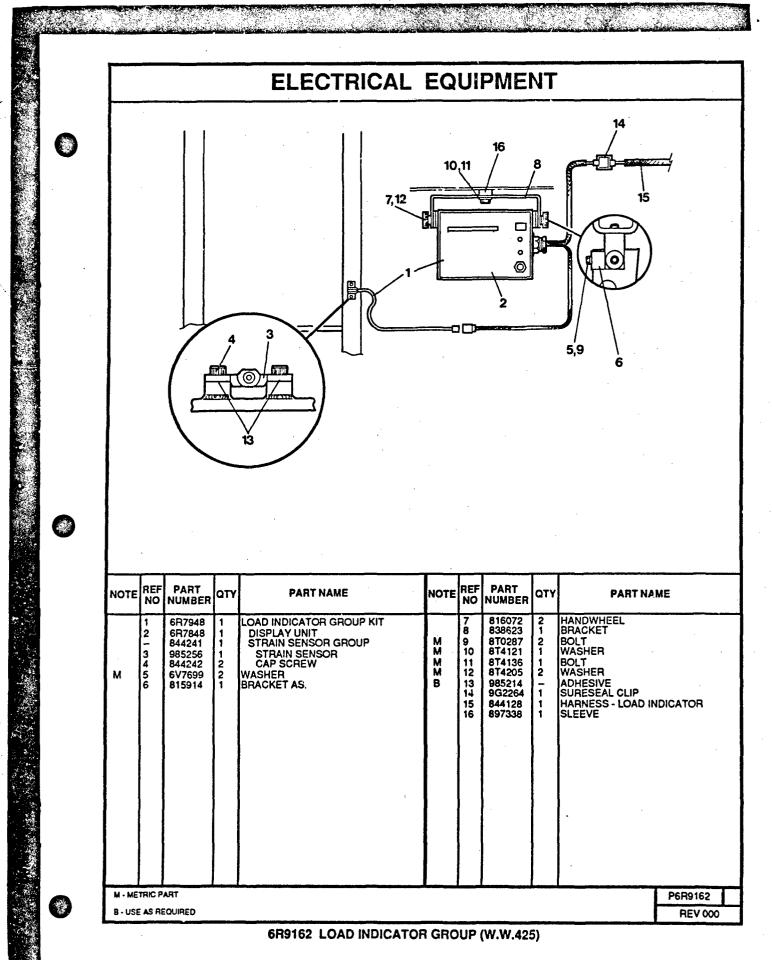
838946 ELECTRONIC CONTROL BOX GROUP Part of 6R7913 Electrical Group - Cab

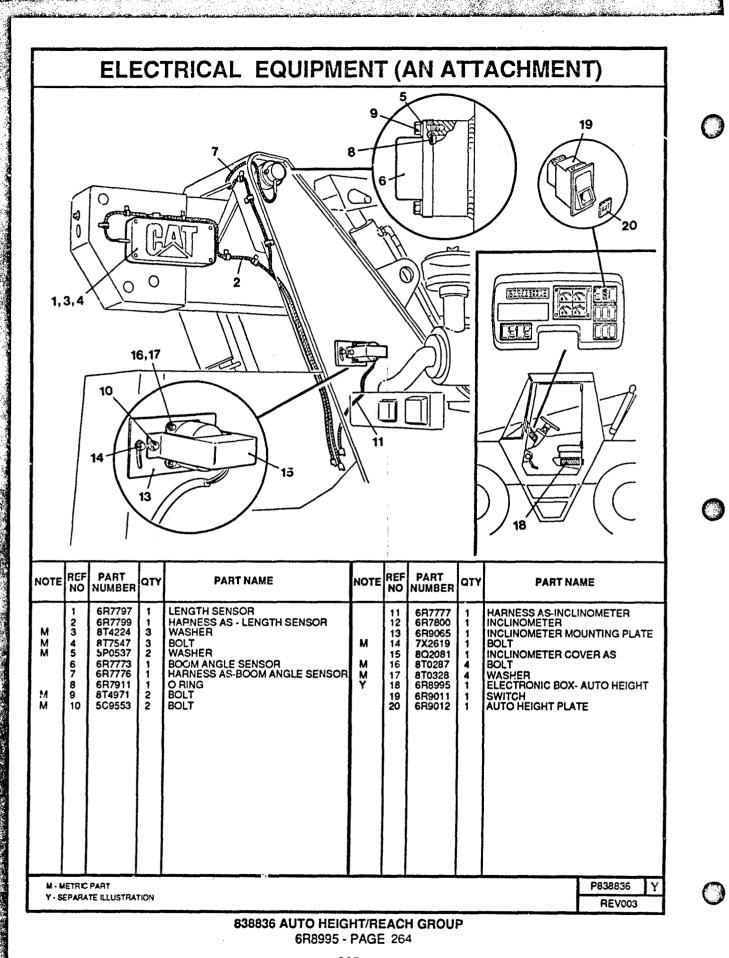




1.

844145 ELECTRICAL GROUP - BOOM Part of 985888 Three Section Boom Group (with Compensating Cylinders)

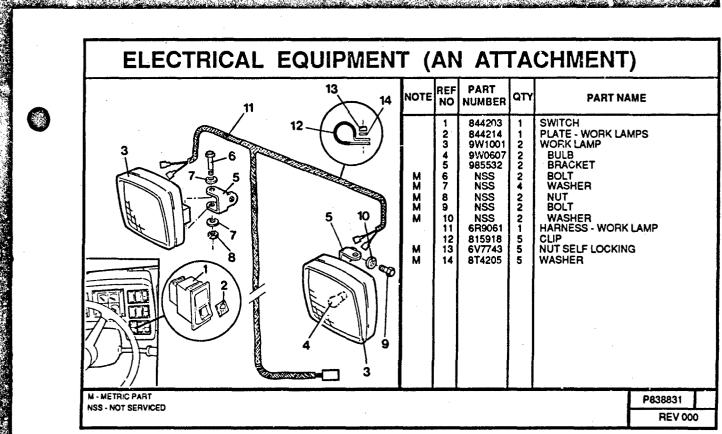




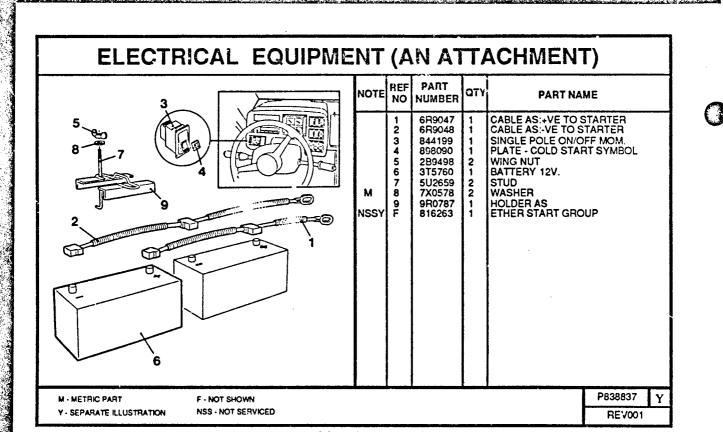
.

267

. *

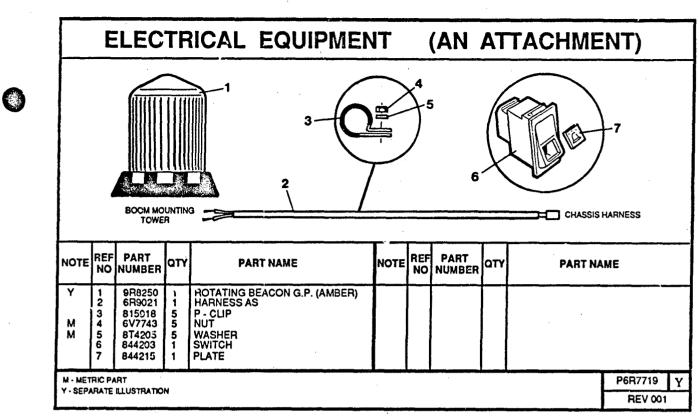


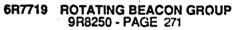
838831 BOOM WORK LAMP GROUP (WITH BOOM SERVICES)

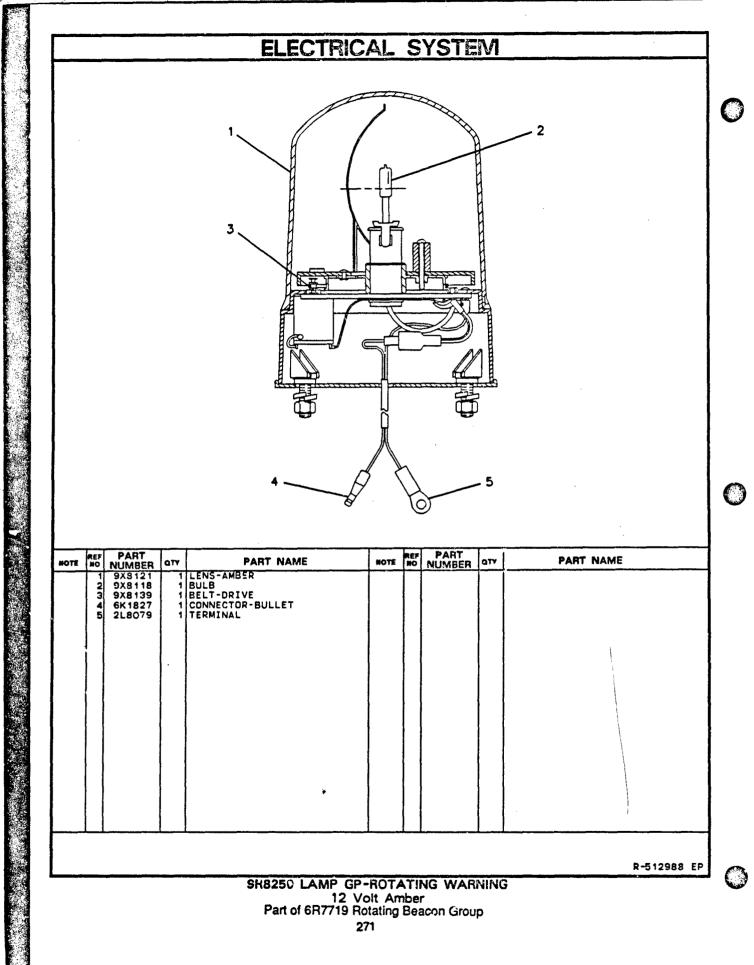


.

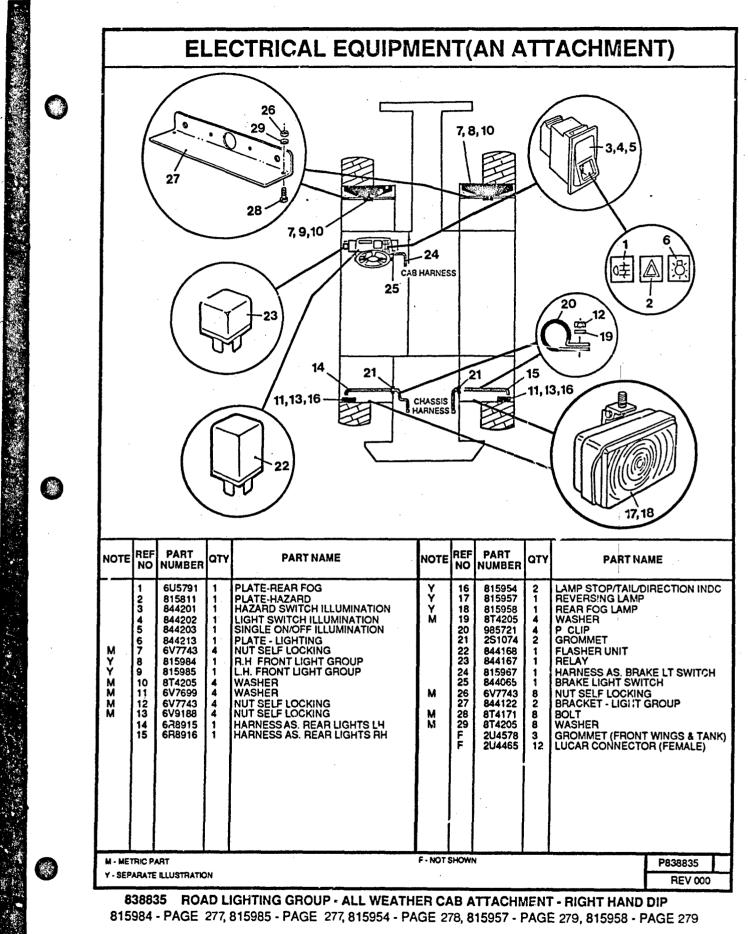
838837 COLD START GROUP 816263 - PAGE

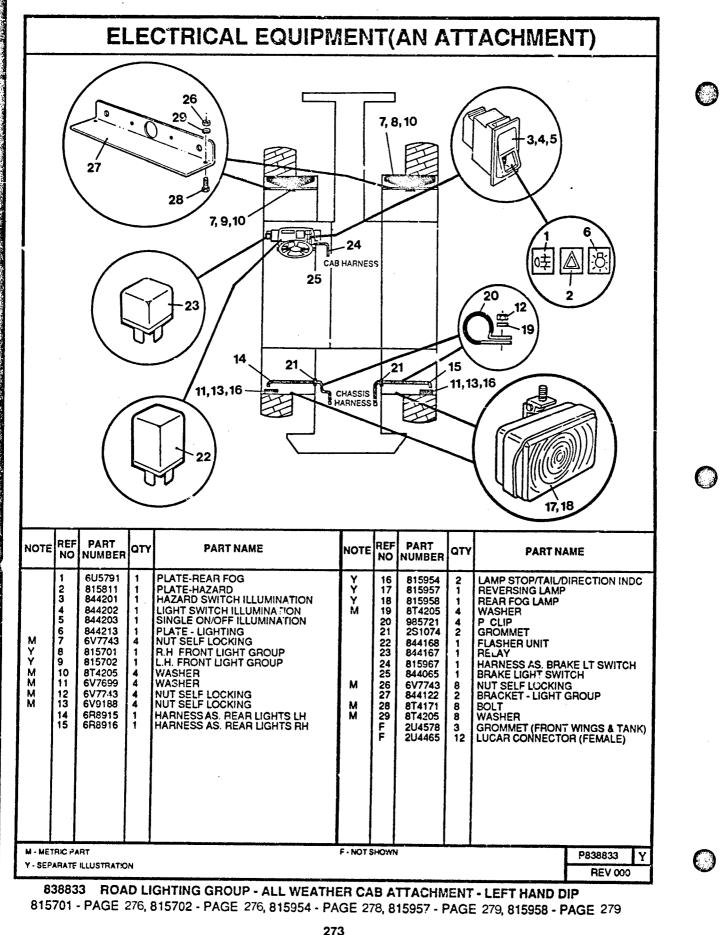






.

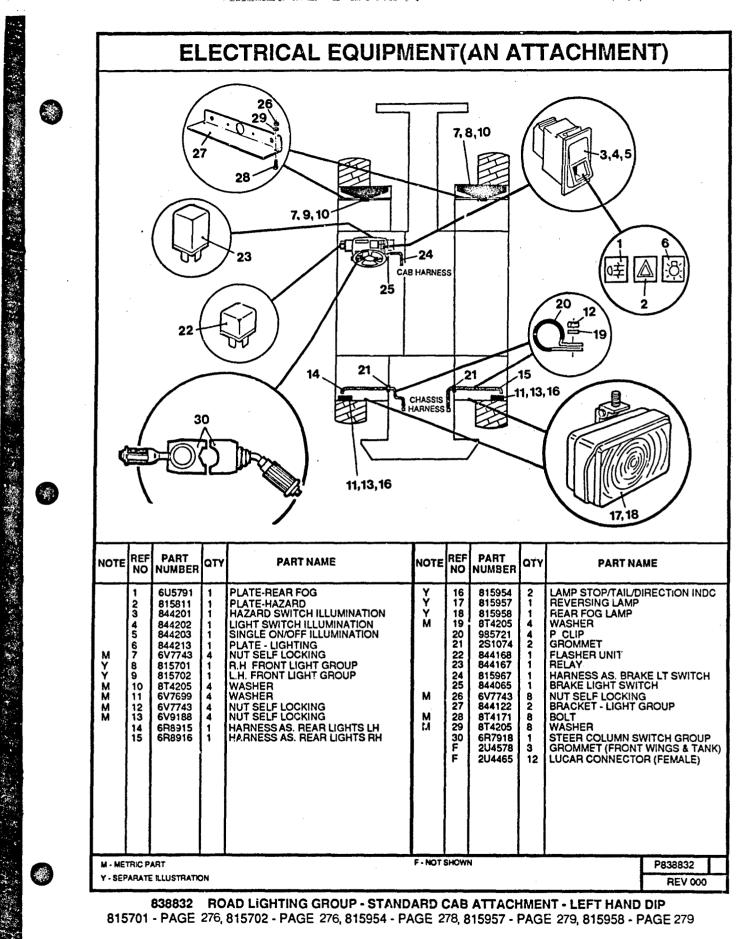




273

of the particular and the second of the second of the second of the second of the second back of the second back of the second of the

. . . .



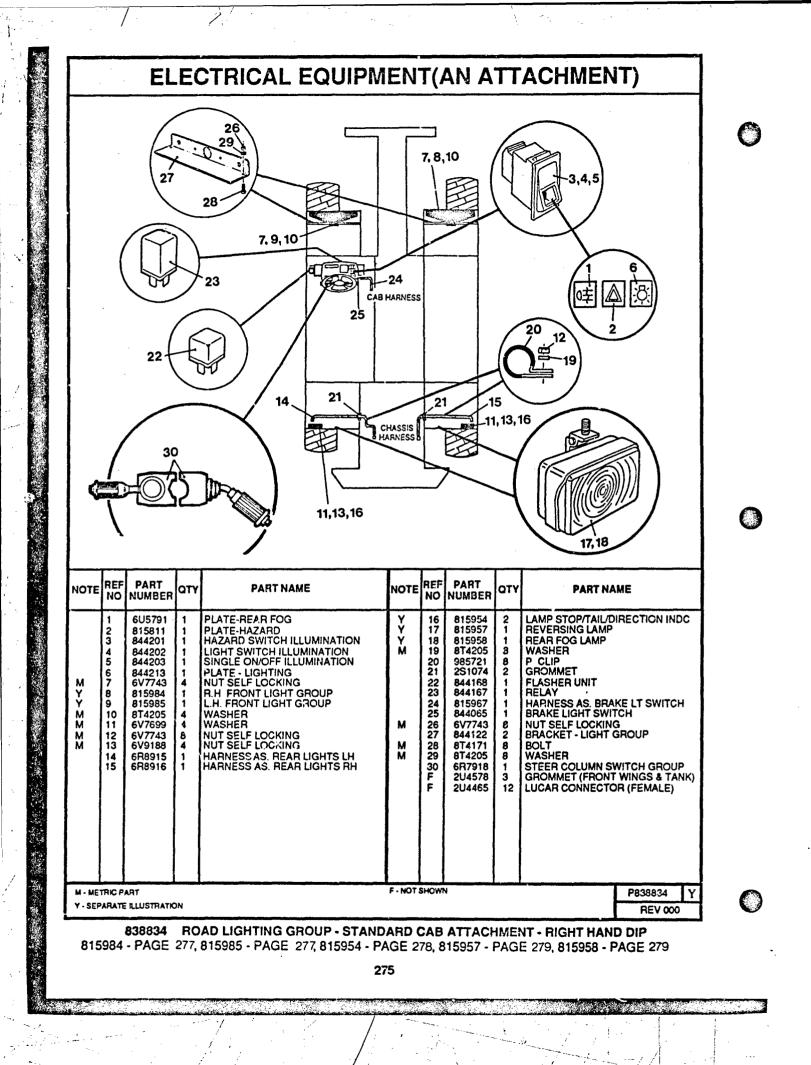
1 - - -

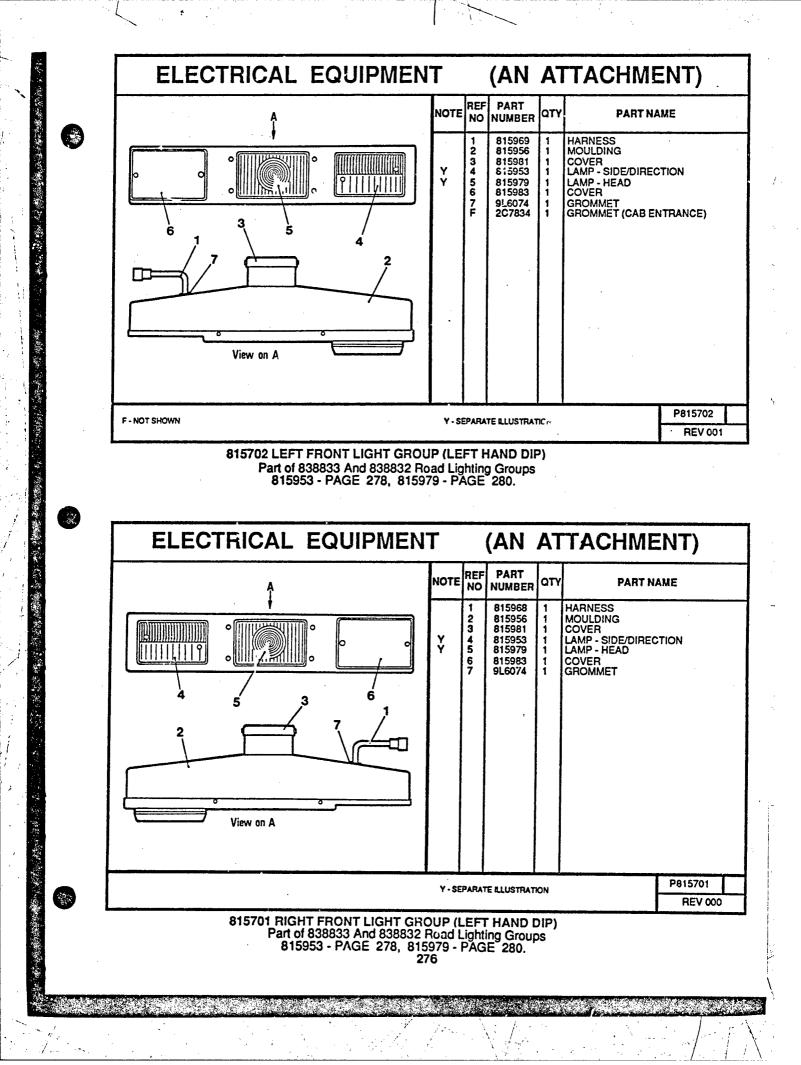
1.

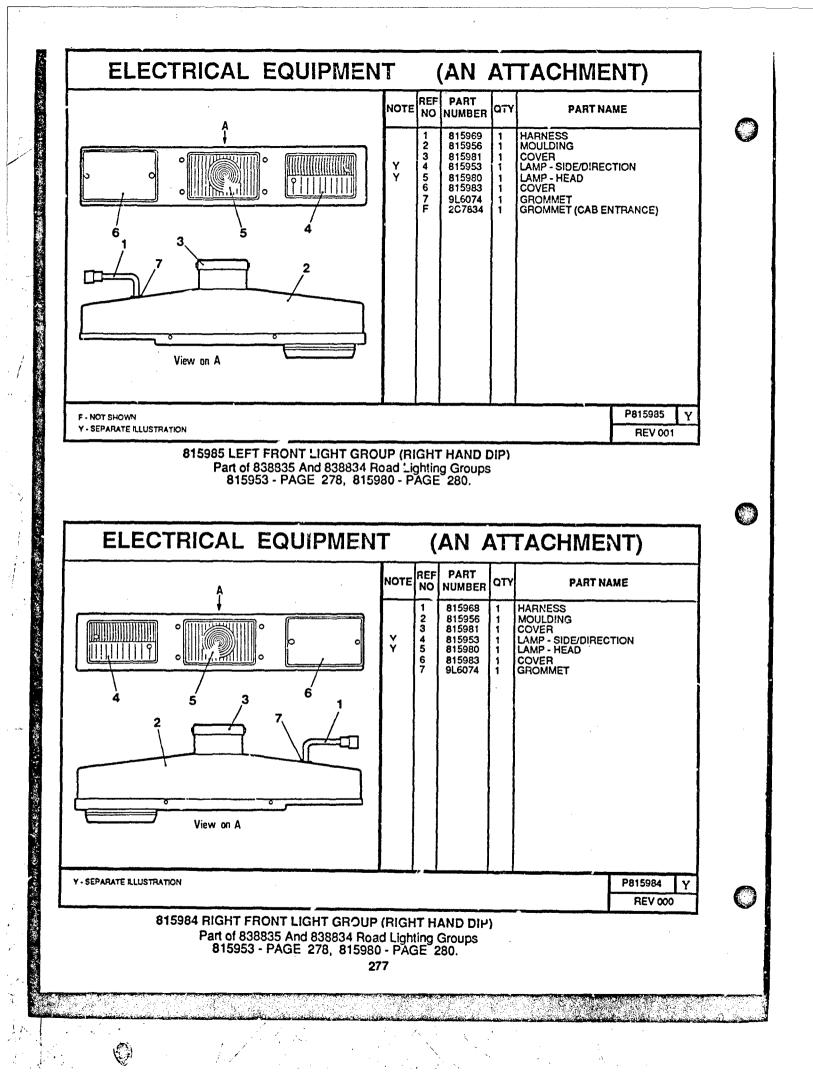
in the second second

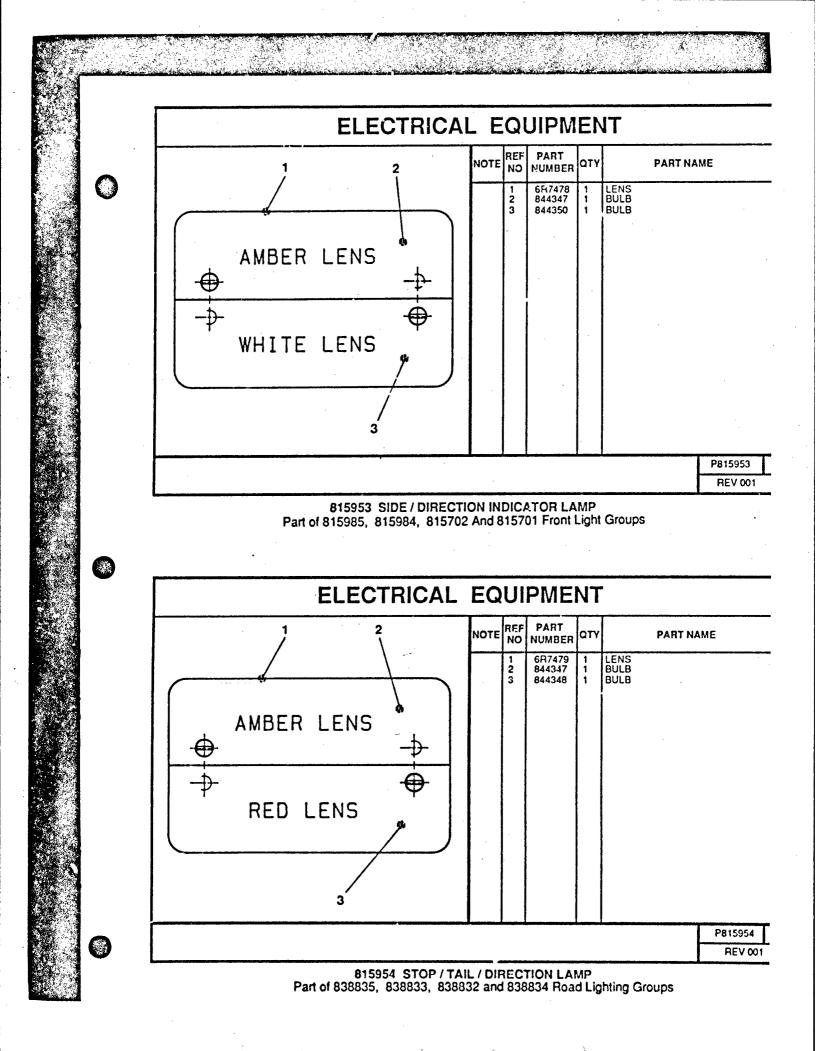
- - - ----

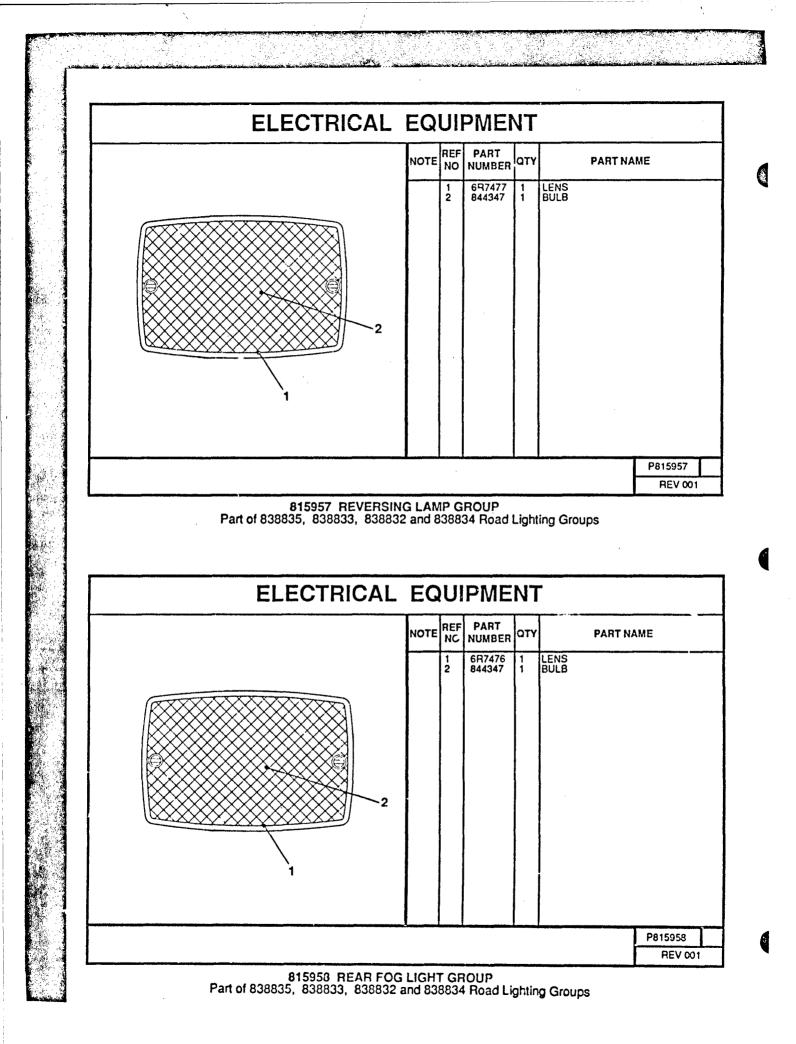
274





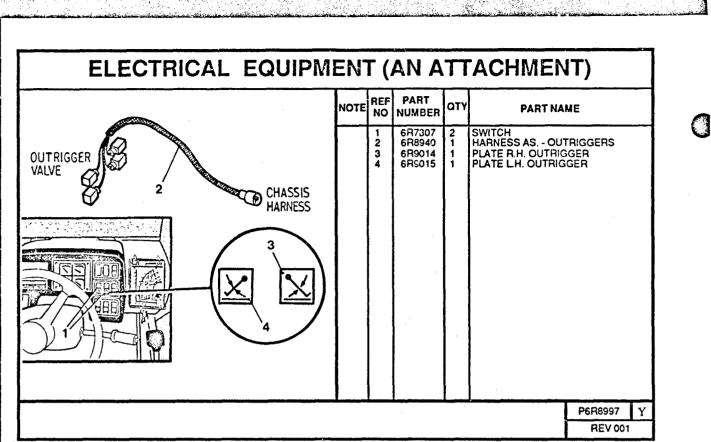






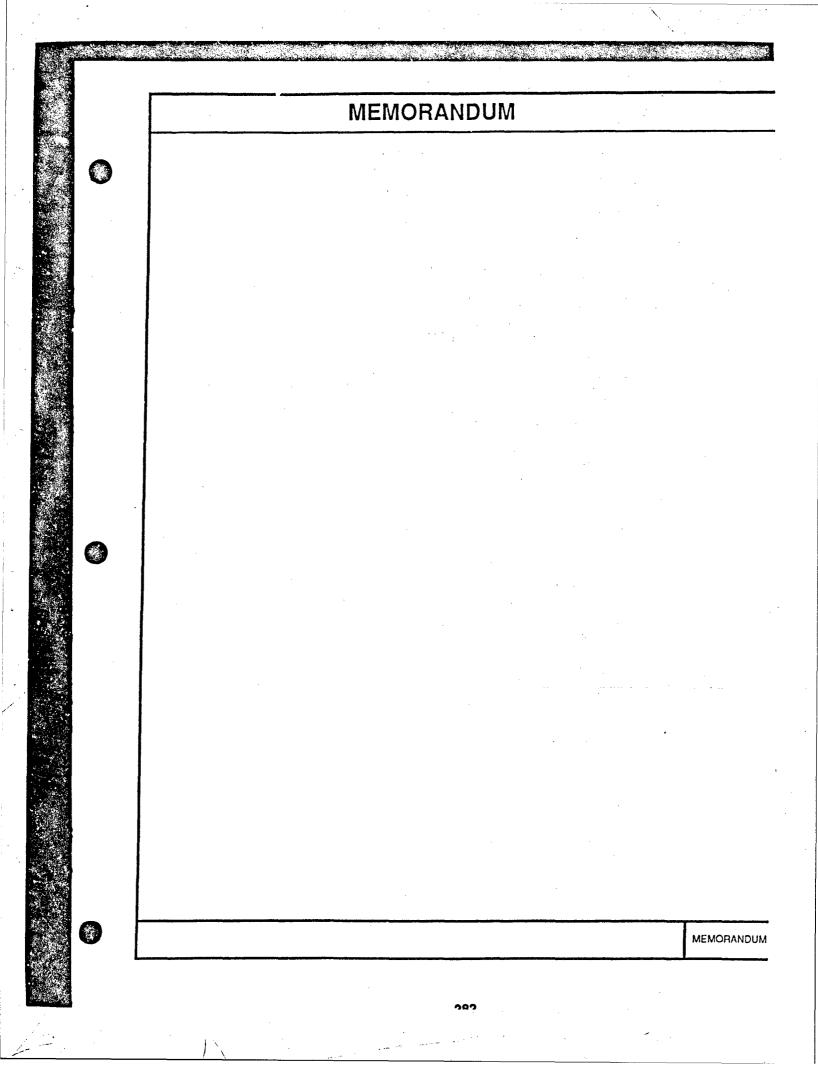
		······································		ELECTRIC	AL E	Q	JIPM	EN	IT		
	·	A	- (VIEW OF	NARROW A
	8	B15980 H	IEAD	LAMP R.H. DIP			815979	IEAI	DLAMP	L.H. DIP	
NOTE	REF NO	PART NUMBER	ατγ	PART NAME	NOTE	REF NO	PART NUMBER	ατγ		PART NA	ME
	1	844349	1	BULB		1	844349	1	BULB		

815979 AND 815980 HEADLAMP GROUPS Part of 815985, 815984, 815702 And 815701 Front Light Groups **REV 001**



6R8997 ELECTRICAL GROUP - OUTRIGGERS

巍

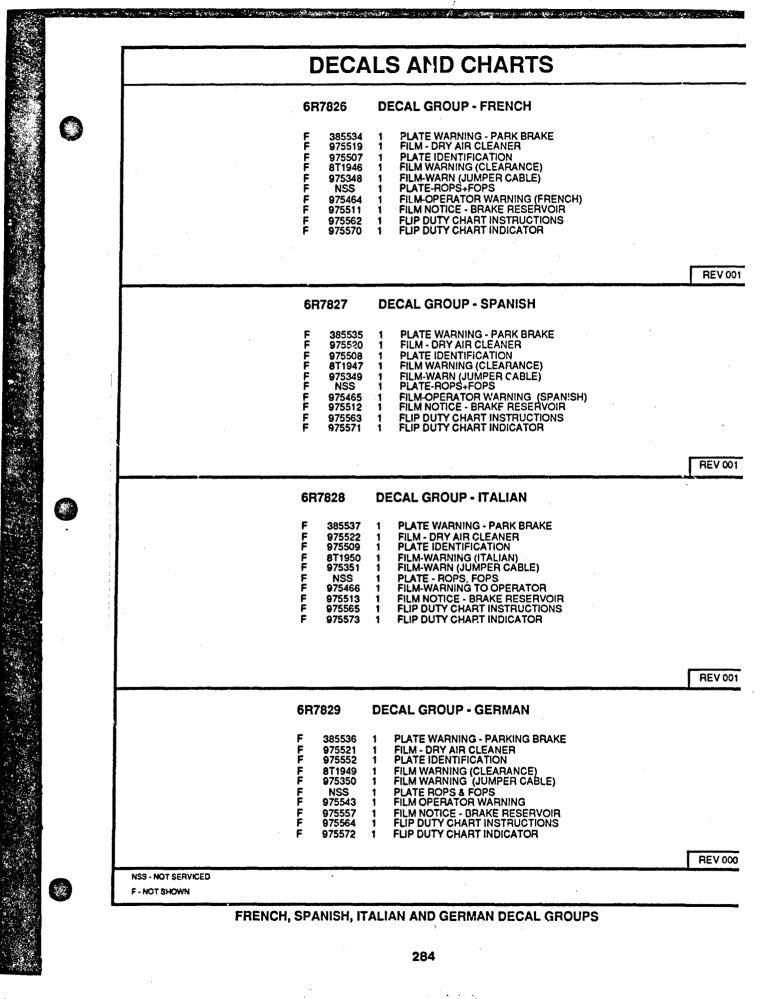


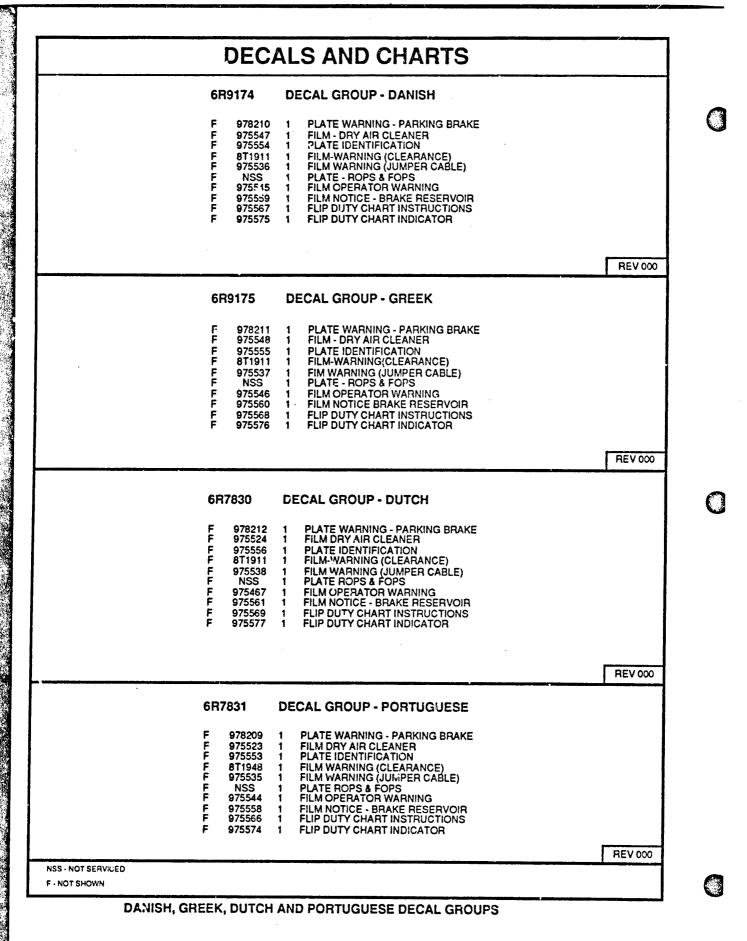
20035 20037 1 TAL. MITPREZE StERNIC WHEEL 368972 Sternic WHEEL TALK FILLER NECK TALK FILLER NECK 368972 Sternic WHEEL TALK FILLER NECK TALK FILLER NECK 372471 372471 Sternic WHEEL TALK FILLER NECK 372471 372471 Sternic WHEEL TALK FILLER NECK 372471 372471 Sternic WHEEL TALK FILLER NECK 373533 Sternic WHEEL TALK FILLER NECK ALL ELEVEL PLOGS / TALK FILLER 373533 Sternic WHEEL TALK FILLER ALL ELEVEL PLOGS / TALK FILLER 373533 Sternic WHEEL TALK FILLER ALL ELEVEL PLOGS / TALK FILLER 373533 Sternic WHEEL TALK FILLER ALL ELEVEL PLOGS / TALK FILLER 373533 Sternic WHEEL TALK FILLER ALL ELEVEN 373533 Sternic WHEEL TALK FILLER ALL ELEVEN 373533 Sternic WHEEL TALK FILLER TALK FILLER 373533 Sternic WHEEL TALK FILLER TALK FILLER 373533 Sternic WHEEL TALK FI		838805 RT80	838807 RT100	Γ	,, <u>,,,,</u> _,,,	
366871SeentFilmThe Public OldTank Filler3668753689721FilmTAANSMISSION FLUIDAXLE LEVEL PULGS / TRANS. FILLER3724713724712FilmFORMANNISAXLE LEVEL PULGS / TRANS. FILLER3724833724711FilmFORMANNISAXLE LEVEL PULGS / TRANS. FILLER385531FilmFORMANNISFARE385531FilmFORMANNISFARE537425517421FilmFORMANNIS	NOTE	PART No.	PART No.	an	DESCRIPTION	LOCATION
		369871 369872 369875 372471 374929 374930 385533 539694 551742 6R7530 6R9271 6R9272 6R9273 6R9352 836955 836971 844226 835955 836971 916850 975347 NSS 975462 NSS 975516 975518 975518 975518 975578 975578 975578 975578 975578 975578	369871 369872 369872 372471 374929 374930 385533 539694 551742 6R9271 6R9271 6R9272 6R9273 6R9352 836955 836972 844226 836972 844226 836972 844226 836972 844226 836972 875516 975518 975516 975518 975518 975578 975516 975578 975462 802741	113211104112441123321142211111411113221	FILM - HYDRAULIC OIL FILM - DIESEL FILM - TRANSMISSION FLUID FILM - TRANSMISSION FLUID FILM - DO NOT OPEN FILM - OPEN INSTRUCTIVE PLATE WARNING (PARKING BRAKE) METAL TACK FASTENER FILM - TIE DOWN LITERATURE GROUP SHIFT PATTERN DECAL TREAD - ANTI SKID TREAD - ANTI SKID TREAD - ANTI SKID FILM PARKING BRAKE FILM MFG BY D.J.I. FILM CATERPILLAR FILM - RT80 FILM - RT80 FILM - RT100 TREAD - ANTI SKID FILM - RT80 FILM - RT80 FILM - RT80 FILM - RT80 FILM - TIRE PRESSURE FILM - TIRE PRESSURE FILM - HAND WARNING FILM - NOTICE(SHIPPING) PLATE - ROPS/FOPS FILM - DERATOR WARNING FILM - DERATOR WARNING FILM - DENTIFICATION FILM - LIFT SYMBOL FILM - CATERPILLAR FILM - CATERPILLAR	TANK FILLER TANK FILLER NECK AXLE LEVEL PLUGS / TRANS. FILLER EACH SIDE OF BOOM HEAD RADIATOR CAP RADIATOR BURP BOTTLE PARK BRAKE PLATES TIE DOWN POINTS SEE FACTORY NOTIFICATION LIST STEERING COLUMN HYDRAULIC AND FUEL TANK LIDS L.H. REAR MUD WING R.H. REAR MUD WING NEXT TO LEVER R.H. SIDE CAB WALL EACH SIDE OF BOOM EACH SIDE OF BOOM TOWER / R.H. BOON EACH SIDE OF BOOM TOWER / R.H. BOON CAB LOWER R.H. CAB WALL CAB ROOF ABOVE TIRES ABOVE TIRES ABOVE TIRES ABOVE REAR TIRES HEAD PLATE No2 BOOM SECTION BATTERY COMPARTMENT LID CAB ROOF R.H. CAB WALL TANK SIDE R.H. SIDE CAB WALL REAR CHASSIS LIFTING LUGS AIR CLEANER BODY REAR R.H. CAB SHELF BOOM CONTROLLER RADIATOR COWL ENGINE COWL ENGINE COWL ABOVE FRONT TIRES
REV 001 P838605 AND 07						REV 001

Ø

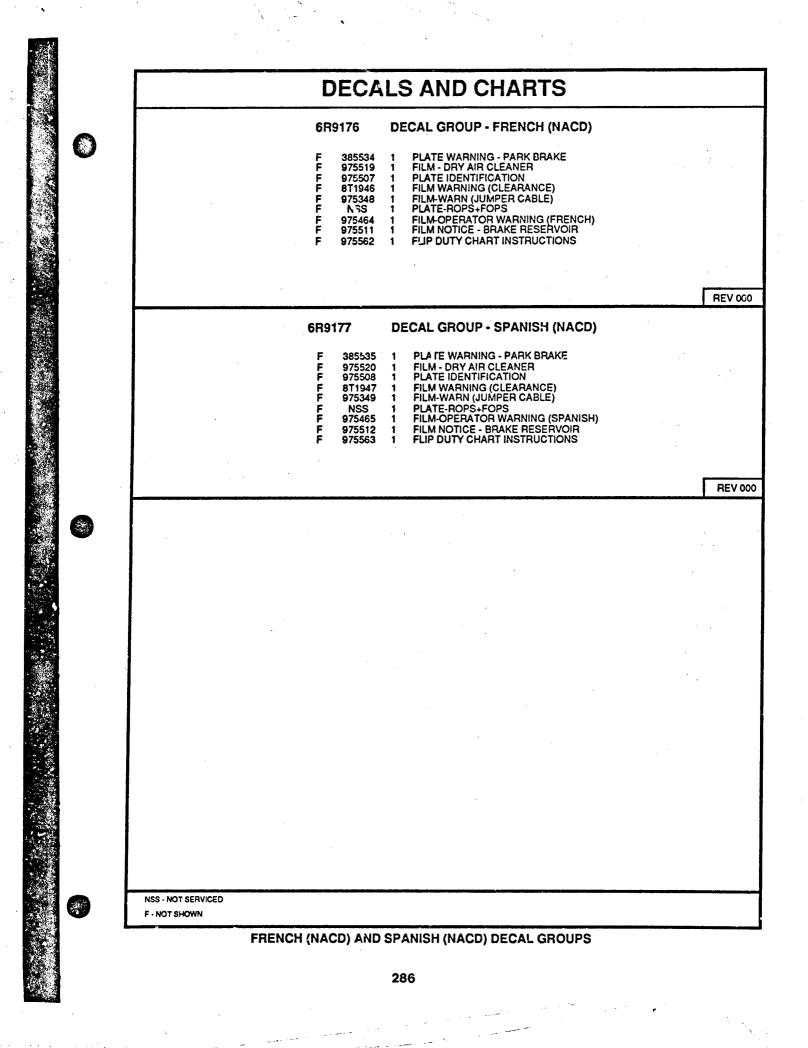
ž

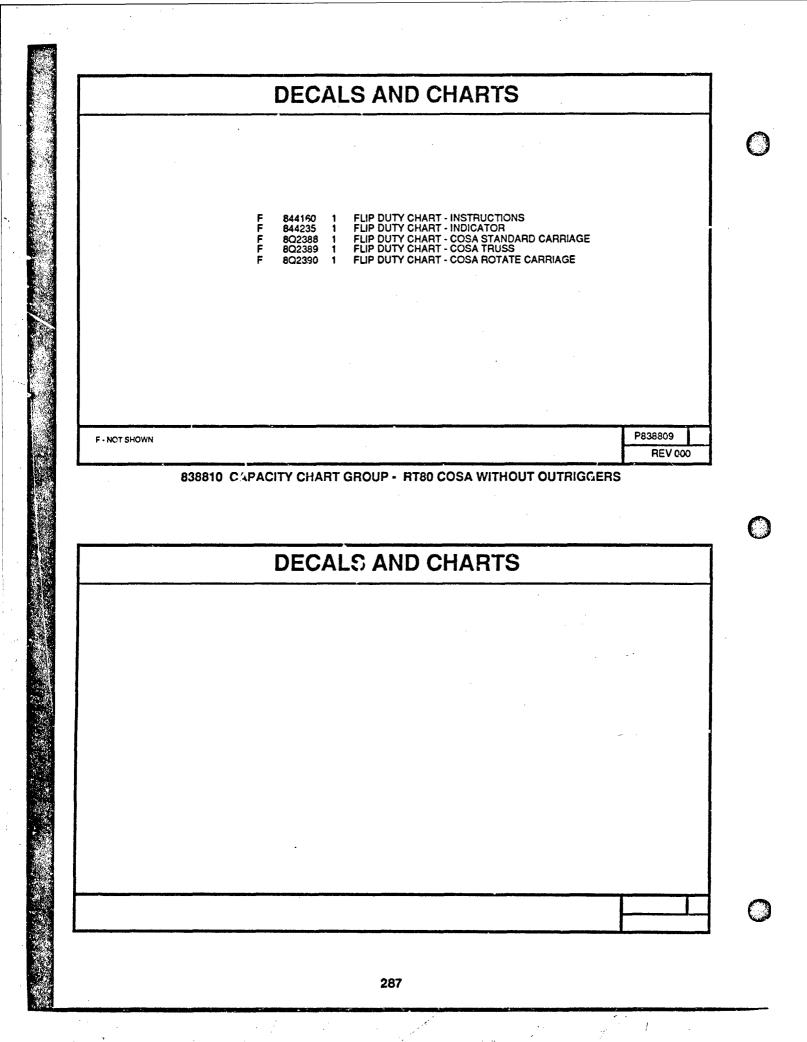
.

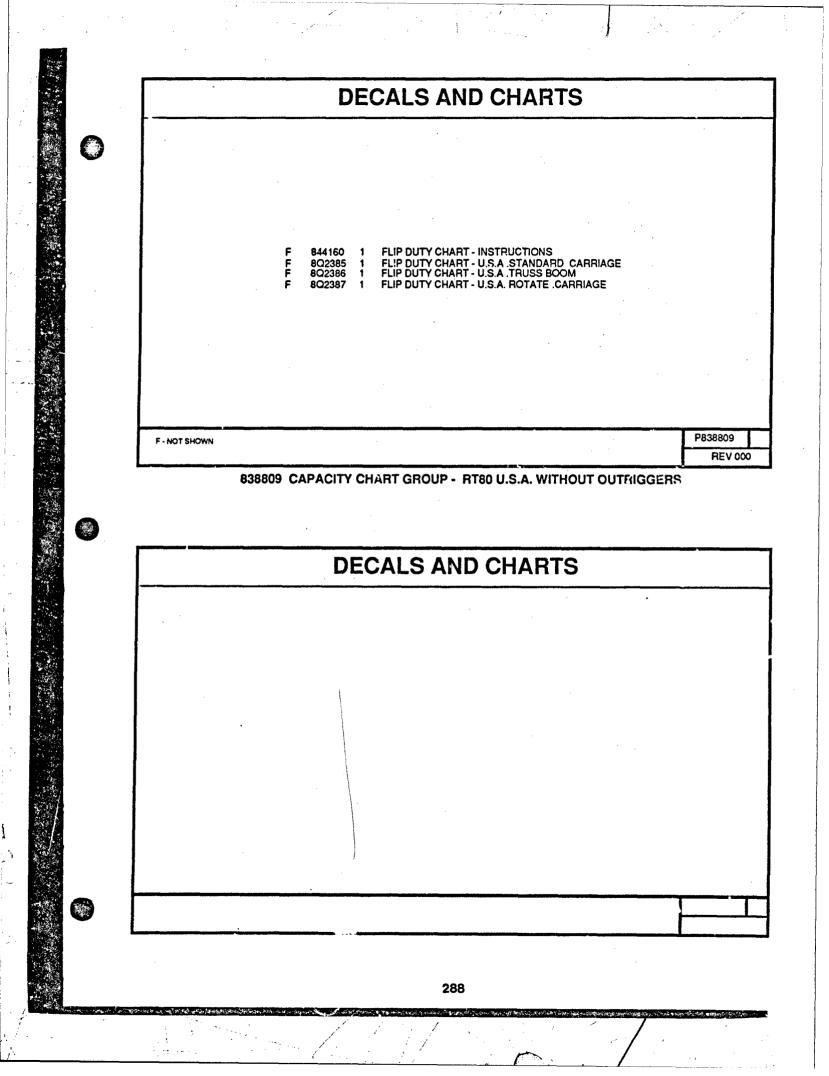


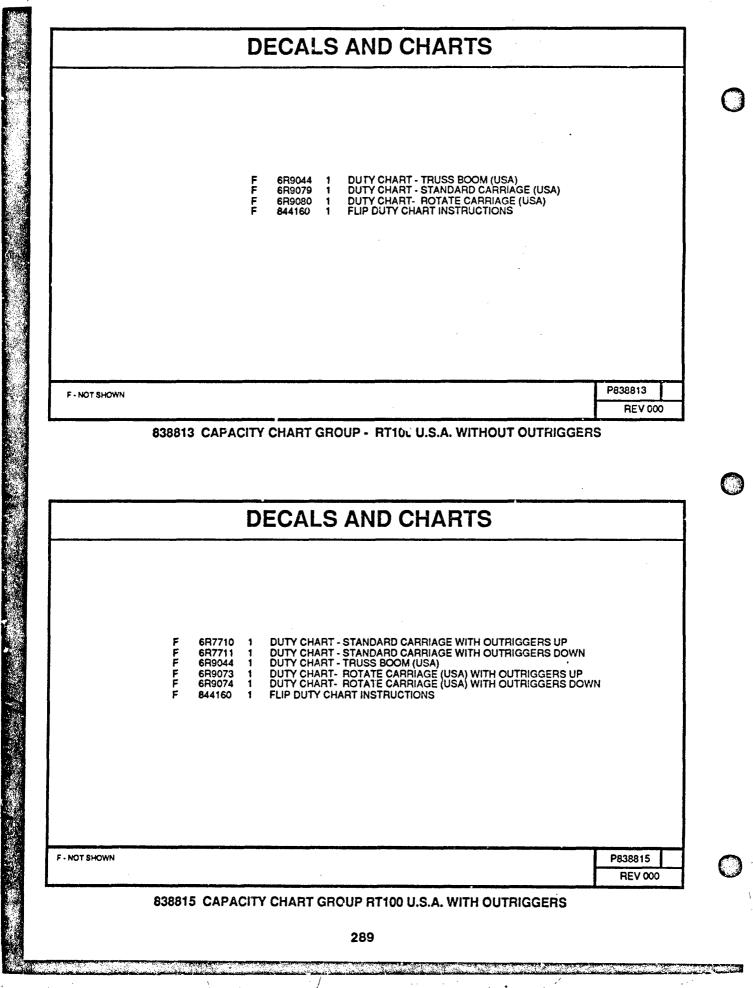


1.









END FILMED DATE: 4-93 DTIC