



Unmanned Combat Air Vehicles



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Outline

- Mission
- Current UCAVs
- Component / Configuration
- Human Systems Integration
- X-45A Analysis
- Overall Assessment



Purpose / Mission

- UCAV – Unmanned Combat Air Vehicle
- Military puposes
 - Suppression of Enemy Air Defense (SEAD)
 - Bombing runs
 - Surveillance
- Mission
 - Range = 1000 nm w/ 2 hrs loiter
 - Average payload = 4500 lb



Current UAV / UCAV's

“ Take the Pilot Out Of Harms Way”





Navy / Marines Pioneer

- Flew over 300 Missions over Persian Gulf
- Used for Surveillance and Bombing Missions
- The single most valuable intelligence collector *
- STOL Aircraft



* LtGen Boomer, USMC



Air Force Predator



- Long Endurance
- Medium Altitude
- Surveillance and Reconnaissance Missions
- Operational In Bosnia Since 1995
- Also been used to drop Missiles
- 450 lb Payload Capacity



Boeing X-45



- Stealth and low observability features
- Still Experimental
- Truck Based support Systems
- Highly Automated, One Operator can control up to four Air Vehicles



UCAV Milestones

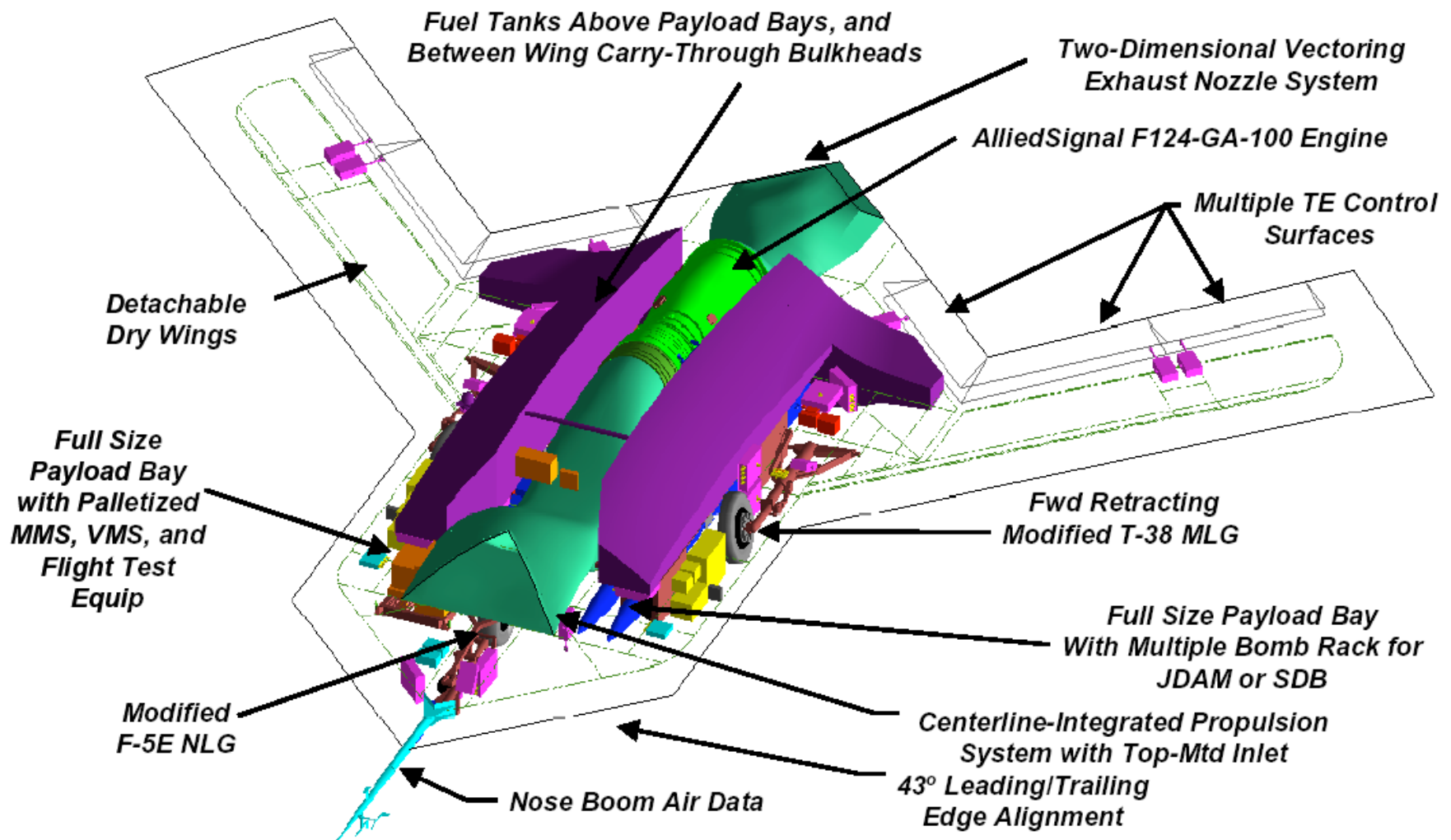


- X-45A
 - First Flight, May 22, 2002
 - Release of unguided bomb, March 20, 2004
 - Precision-guided release, expected soon
- X-47A Pegasus
 - First Flight, February 23, 2003





Component Integration

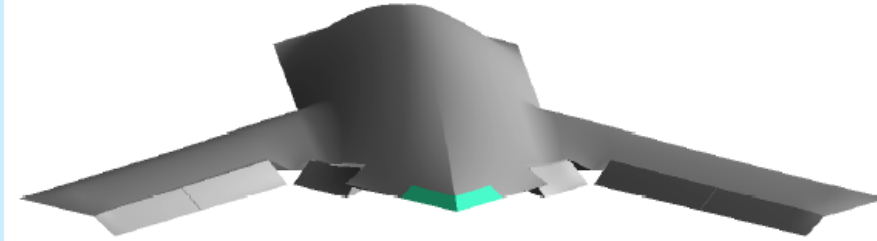


Source: Wise, Kevin, "First Flight of the X-45A Unmanned Combat Air Vehicle (UCAV)", AIAA 2003-5320

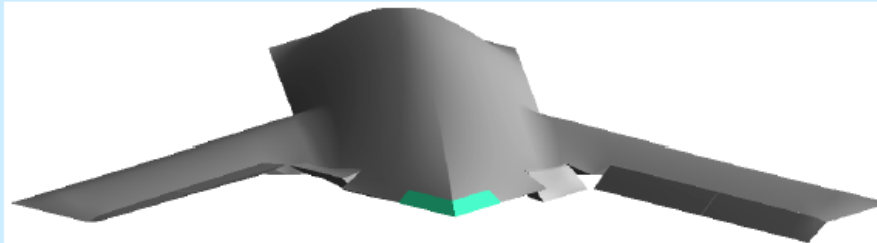


Controls

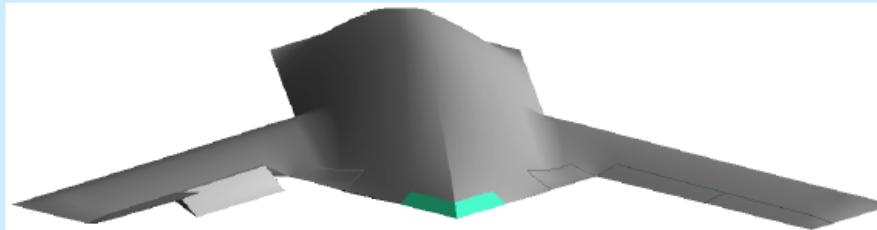
Pitch Control: Symmetric Deflection of Elevons



Roll Control: Differential Deflection of Elevons



**Yaw Control: Nozzle Vectoring + 'Crow-Mixing'
of Outbd/Mid Elevons**





Aerodynamic Configuration Drivers

- Removal of human factor constraints
- Cost effective
- Multi-disciplinary, multi-mission design challenges
- High maneuverability and agility
 - 2 design features
 - 1) Fuselage placement
 - 2) Planform



Human Factors

- What information does the operator need during flight?
- What is the best way to display this info?
- Are communication links fast enough?
- What controls should the operator have and what should be done autonomously?
- What feedback is necessary from the aircraft?

Operators must be included in the design process



Human Systems Integration Strengths

- Take the Pilot out of Harms Way
- Highly Automated
- Built to allow aircraft system and components to be interchangeable and easily replaced
- Designed for easy Maintenance

AIAA paper 98-1032



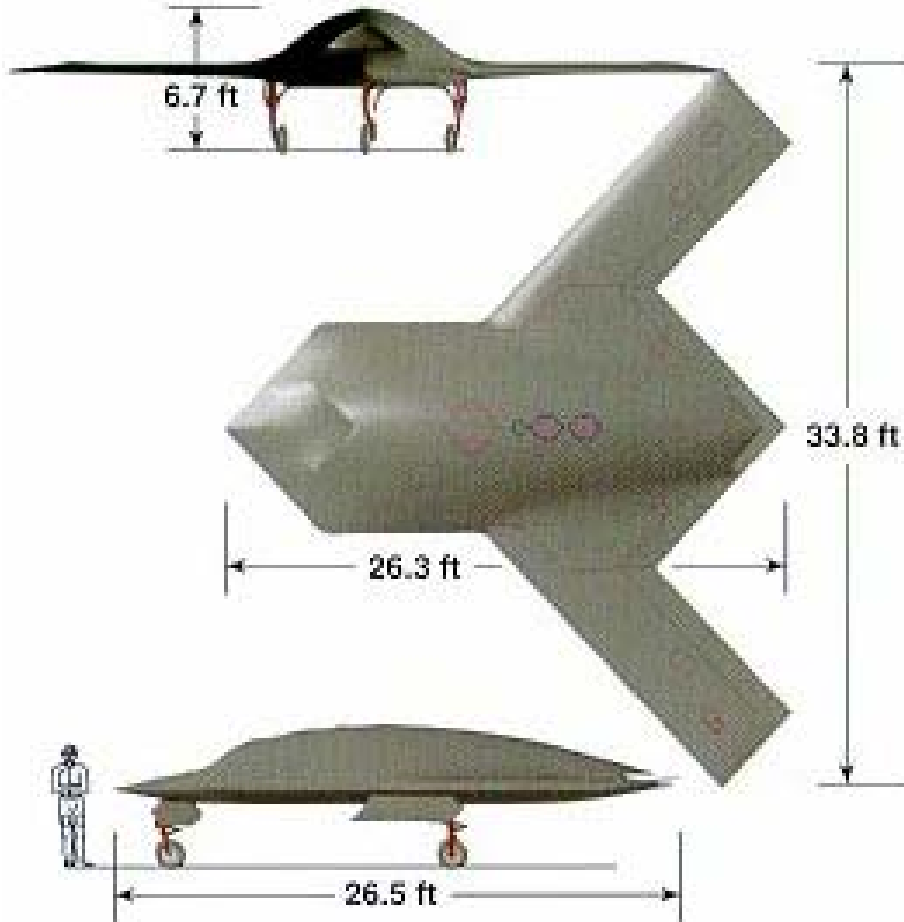
Human System Integration Shortfalls

- Displays are non-conventional
- Limited Field of View
- Potentially Ambiguous Information
- Relatively High Operational Costs
- Requires High Levels of Operator Skills

AIAA paper 98-1032



Specifications

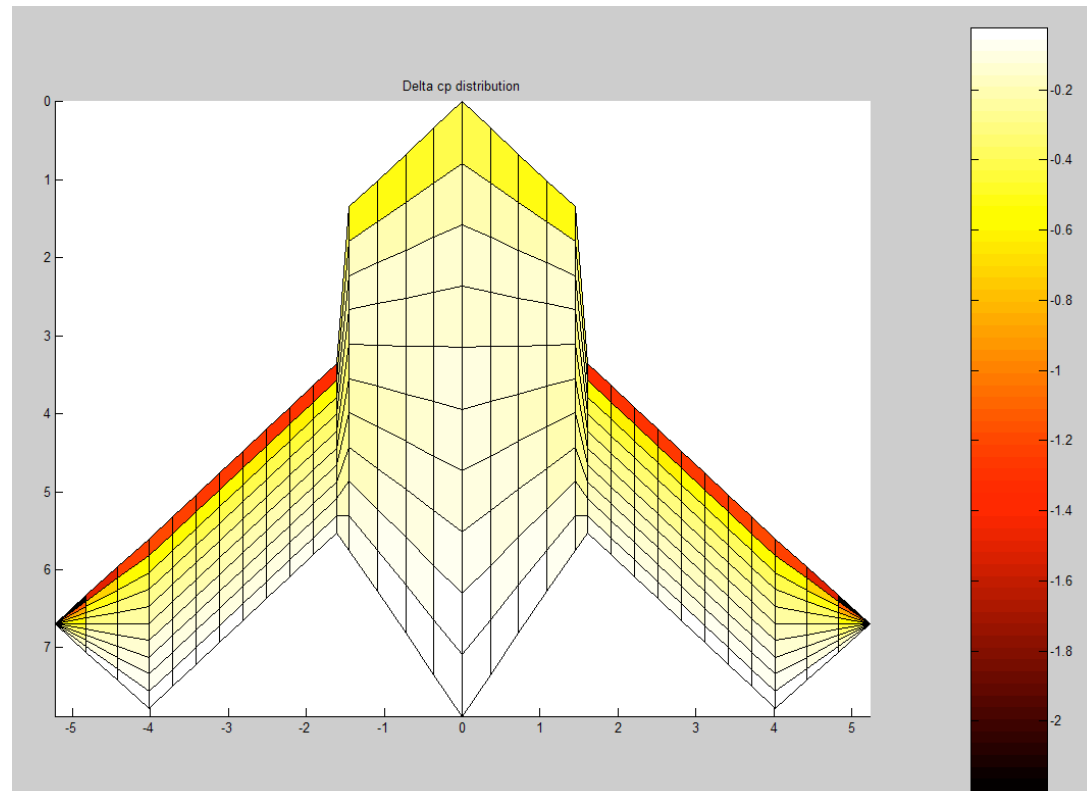


<http://www.invisible-defenders.org/programs/uavs/x-45-design-man.htm>

Empty Weight	8,000 lbs
Fuel Weight	2,690 lbs
Payload	1,500 lbs
Operating Altitude	35,000 ft
Cruise Mach No.	0.80



Vortex Lattice Methods

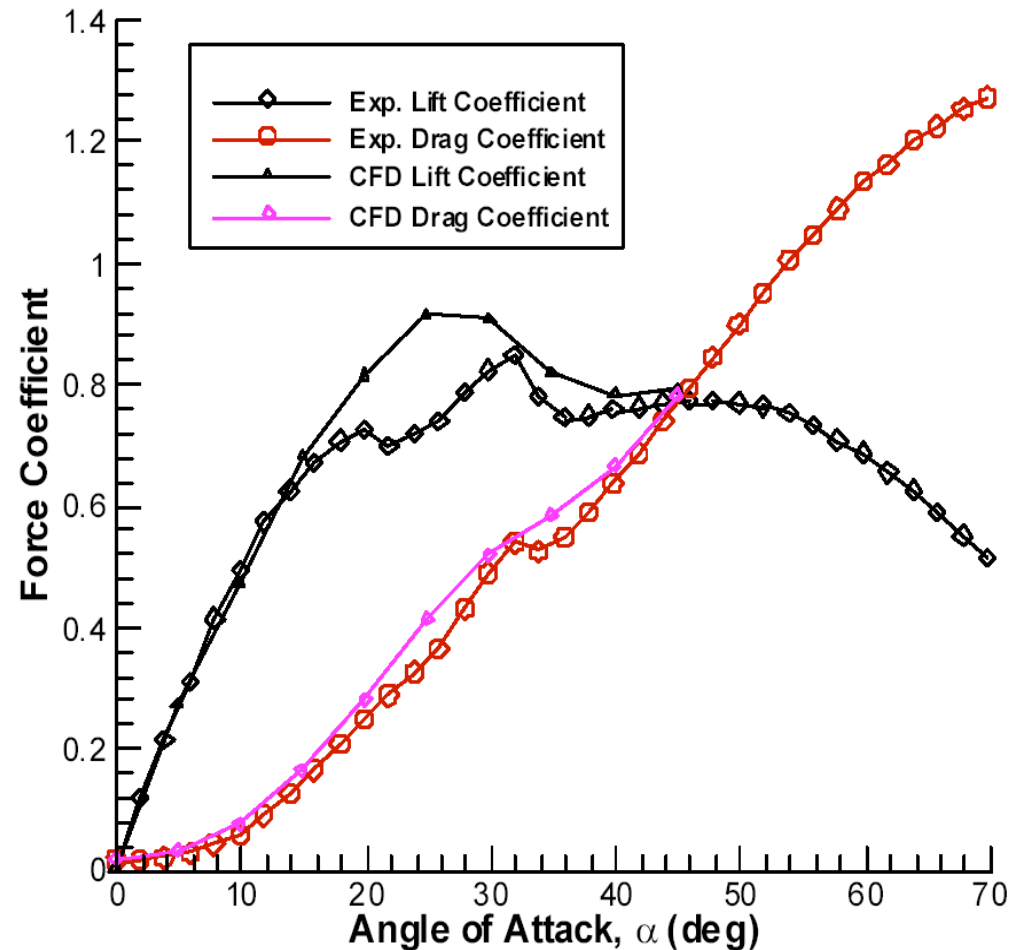
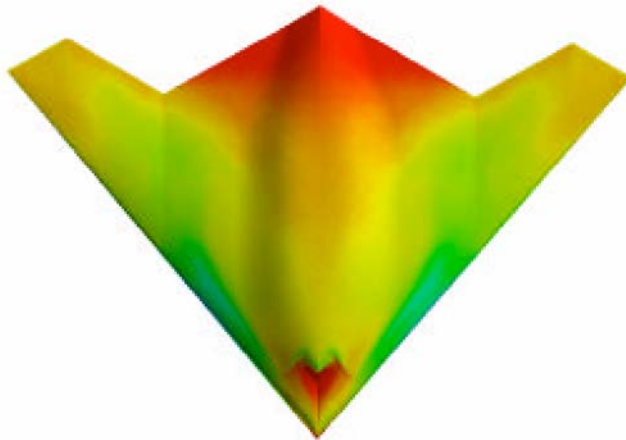


	VLMpc	Tornado©
$C_{L\alpha}$	0.053 /deg	0.048 /deg
$C_{m\alpha}$	0.00408 /deg	0.00252 /deg



Force Measurements

- 1:46.2 scale
- Boeing 1301 UCAV config
- $C_{L\alpha} = 0.049 / \text{deg}$
- $Re = 142,000$
(full scale $\Rightarrow Re \sim 30$ million)





Takeoff / Landing Performance

First Flight, X-45A




 NASA Dryden Flight Research Center Photo Collection
<http://www.dfc.nasa.gov/gallery/photo/index.html>
 NASA Photo: EC02-0106-07 Date: May 22, 2002 Photo by: Carla Thomas
 X-45A Unmanned Combat Air Vehicle, or UCAV, technology demonstration aircraft taking off during its first flight at Edwards Air Force Base, California.

<i>Takeoff Performance</i>	
T/O Speed	152 KEAS
T/O Distance	4500 ft
Climb Rate	1000 ft/min
<i>Landing Performance</i>	
Approach Speed	175 KEAS
T/D Sink Rate	2.7 ft/s
Landing Distance	3500 ft



Overall Assessment

- Pros

- Eliminate pilot casualties
- More maneuverable
- Reduce pilot fatigue
- Flexibility
- Possibility for future cost reduction

- Cons

- Limited control abilities
- Limited pilot reasoning
- Delayed response time
- Adaptability to mission modification

