

Flexible Production with Automated Guided Vehicles

SIMOVE | 01.06.2020 | Dave Suctlffe

Flexible Production with AGV's

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Siemens addresses the AGV market with the development and marketing of a system package

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SIMOVE – Standardized solution for AGV applications

Use of standard automation and drives components + tailored application software

Easy system extension via open Interfaces

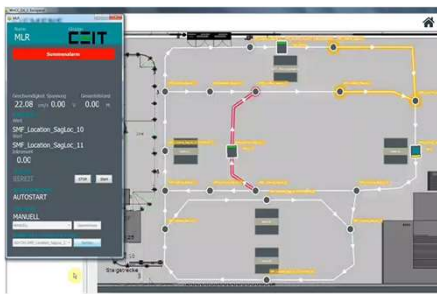
Competence team for application support



SIMOVE – The comprehensive system package for AGV automation

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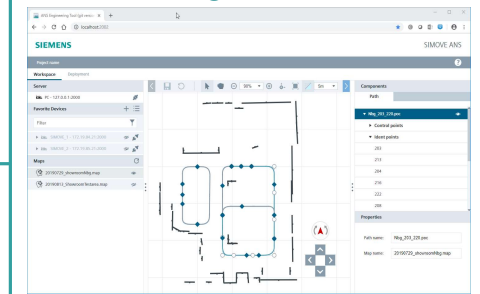
Master Control SW



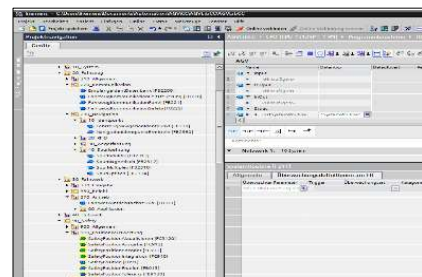
Enables machine builders and manufacturers
to automate...



Navigation SW

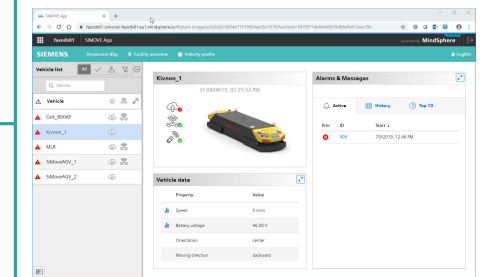


Carrier Control SW



... AGV applications
with Siemens components and technologies

Maintenance SW



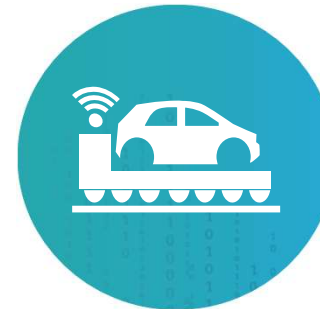
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Carrier
Control

Navi-
gation

Master
Control



SIMOVE – Scalable AGV Classification

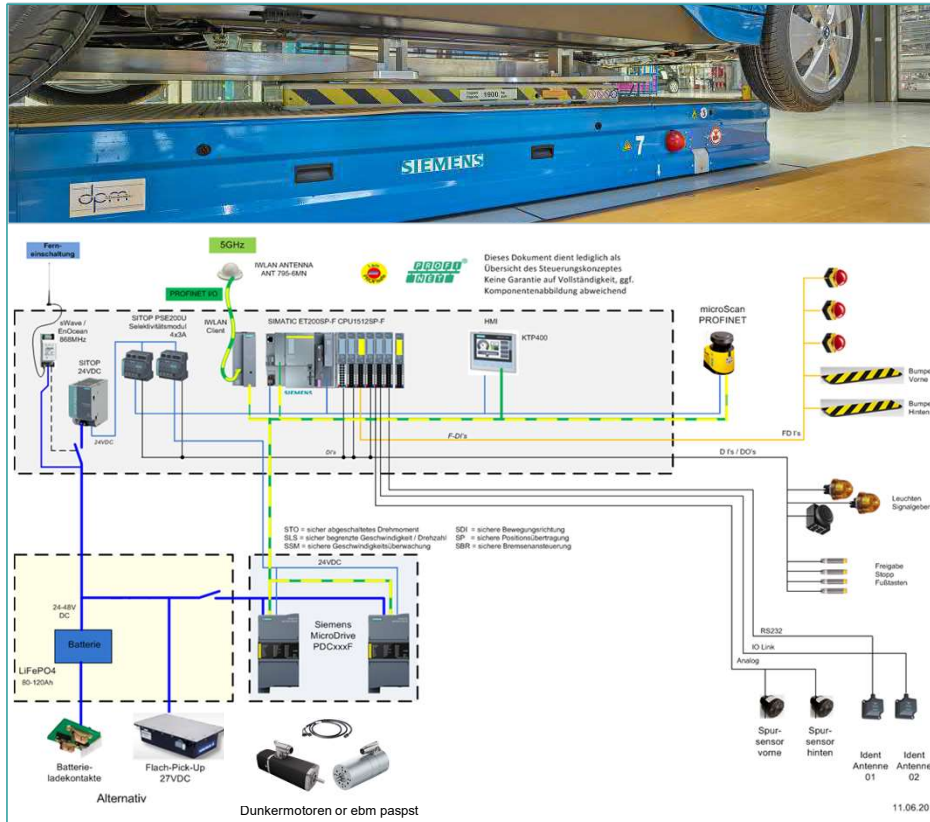
Basic	Advanced	Complex
 <ul style="list-style-type: none"> • Vehicles with single steer/drive wheel • Basic material flows • Light loads • Manual load handling 	 <ul style="list-style-type: none"> • Vehicles with single steer/drive wheel • Complex material flows • Light/medium loads • Automatic load handling 	 <ul style="list-style-type: none"> • Vehicles with multiple steer/drive wheels • Complex material flows • All load types, light to heavy • Automatic load handling
		

SIMOVE – Automate with standard automation and drives components

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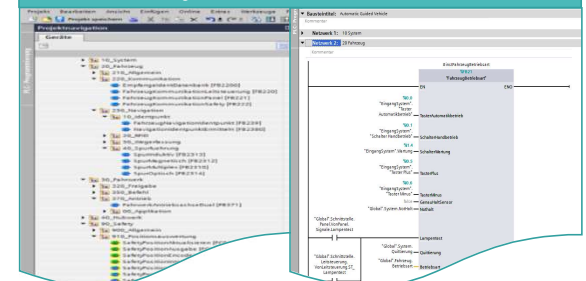
- Basic functions
- Communication
- Track management
- Drive train
- Energy supply
- Safety-functions
- Additional onboard functions e.g. lifting



Recommended component list tailored for different types of AGVs

Bez.	Herstell.	MLFB	Benennung	Menge/F
CPU	Siemens	6ES7512-1SK01-0AB0	SIMATIC DP, CPU 1512SP F-1 PN für ET 200SP, Zentralbaugruppe mit Arbeitsspeicher 300 KB für Programm und 1MByte für Daten	1
SD	Siemens	6ES7954-8LF02-0AA0	SIMATIC S7, Memory Card für S7-1x 00 CPU/SINAMICS, 3, 3V Flash, 24 Mbyte	1
BA 2xFC	Siemens	6ES7193-6AF00-0AA0	SIMATIC ET 200SP, Busadapter BA 2xFC, 2x Fast-Connect Anschluss für PROFINET	1
F-DI 8x24VDC HF	Siemens	6ES7136-6BA00-0CA0	SIMATIC DP, Elektronikmodul für ET 200SP, F-DI 8x 24VDC HF, 15mm Baubr.	2
F-DQ 4x24VDC/2A	Siemens	6ES7136-6DB00-0CA0	SIMATIC DP, Elektronikmodul für ET 200SP, F-DQ 4xDC 24V/2A, 15mm Baubr.	1
PM HF F-RQ 1xDC24V/AC24, 230V/5A	Siemens	6ES7136-6RA00-0BF0	SIMATIC DP, Elektronikmodul f. ET200SP, F-RQ 1x 24VDC/24, 230V/AC/5A ST, 20mm Baubr.	1
DI 16x24VDC	Siemens	6ES7131-6BH00-0BA0	SIMATIC ET 200SP, Elektronikmodul für ET 200SP, F-DI 16x 24VDC HF, 15mm Baubr.	1

Preconfigured "TIA AGV project" and library with function blocks



SIMOVE – Automate with standard automation and drives components

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IPC 127E – Simatic Ind. OS



S7-1500 ET 200SP PLC



iWLAN components



HMI's

S7-1500 Open Controller



Simatic Ident - RFID



Simatic MicroDrive



SIMOVE– Drivetrain provided by Simatic MicroDrive



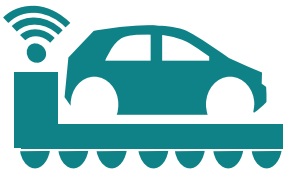
Drive Solution for Safety extra-low voltage

AGV Safety achieved with STO / SLS / SLT

Energy recovery using Brake Chopper

PDC Telegram integrated into SIMOVE library blocks

SIMOVE– Automate with standard automation and drives components



- Basic functions
- Communication
- Track management
- Drive train
- Energy supply
- Safety-functions
- Additional onboard functions e.g. lifting

The screenshot shows the Siemens TIA Portal interface for an AGV project. The left pane displays the 'Geräte' (Devices) tree with a hierarchy including '10_System', '20_Fahrzeug', '210_Allgemein', '220_Kommunikation', '230_Navigation', and '30_Fahrwerk'. The main workspace shows a table for 'AGV' with columns for Name, Datentyp, and Defaultwert. The table contains entries for Input, Output, InOut, and Static, with a specific entry for 'instSystemRoutine' of type '*SystemRoutine*'. Below the table, the 'SystemRoutine [FB11]' configuration is visible, showing a table for 'Überwachungsdefinitionen am FB' with columns for Überwacher, Parameter, Trigger, Überwachungsart, and Kategorie.

The screenshot displays the ladder logic for the 'Fahrzeugbetriebsart' function block. It shows a network with various inputs and outputs, including 'EingangSystem', 'SchalterHandbetrieb', 'EingangSystem', 'SchalterWertung', 'EingangSystem', 'SystemFlux', 'EingangSystem', 'SystemRuhes', 'EingangSystem', 'SystemRuhes', 'Global' Schrittmotor, 'Global' System, 'Global' Schrittmotor, 'Global' Fahrzeug, and 'Global' Fahrzeug. The logic involves a series of normally open and normally closed contacts leading to a coil for 'BetriebsartAutomatik'. Below this, another network shows the logic for 'BetriebsartAutomatik' with inputs like '#TempStartimpuls', '#BetriebsartAutomatik', and '#Start', leading to a coil for 'BetriebsartAutomatik'.

Pretested modules, preconfigured TIA “AGV project”

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Carrier
Control


Navi-
gation

Master
Control



SIMOVE-

Support of all kinds of navigation, Siemens' navigation based on ANS

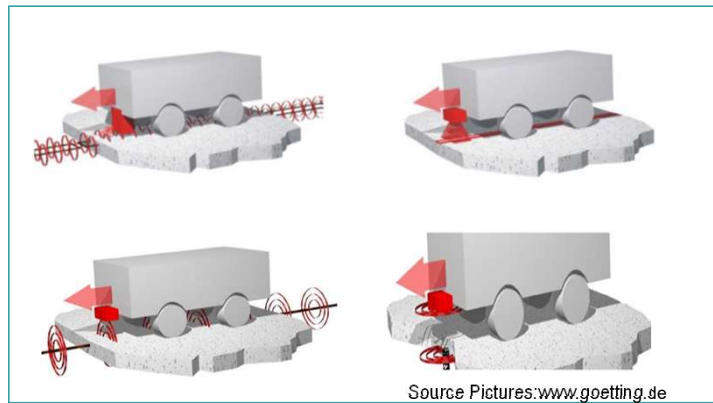


Carrier functions:


- Localization
- Route following
- Obstacle avoidance

Engineering:

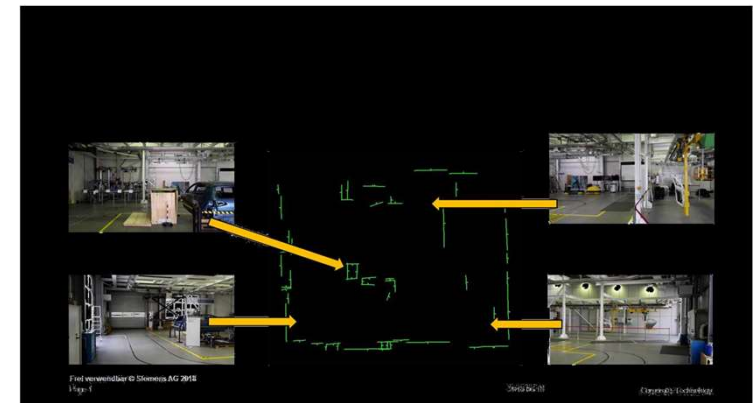
- Map Management
- Route Management




Track guided Navigation



- Proven technology
- Integrated in SIMOVE
- Already used in projects



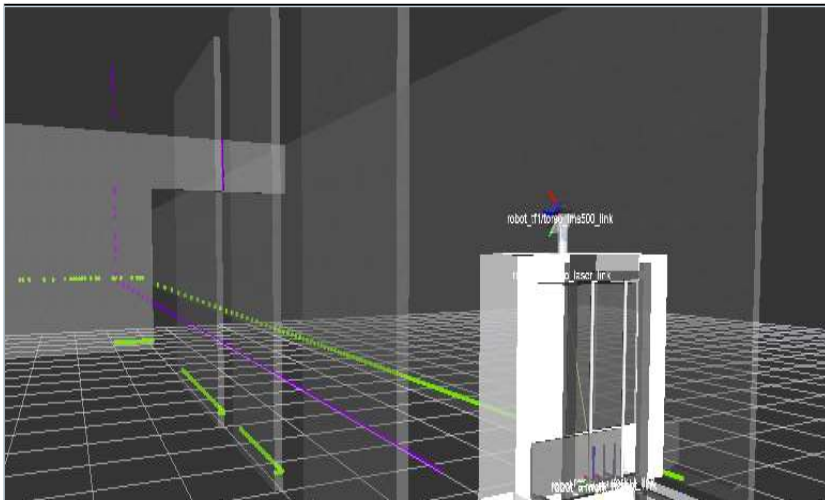
Free Navigation



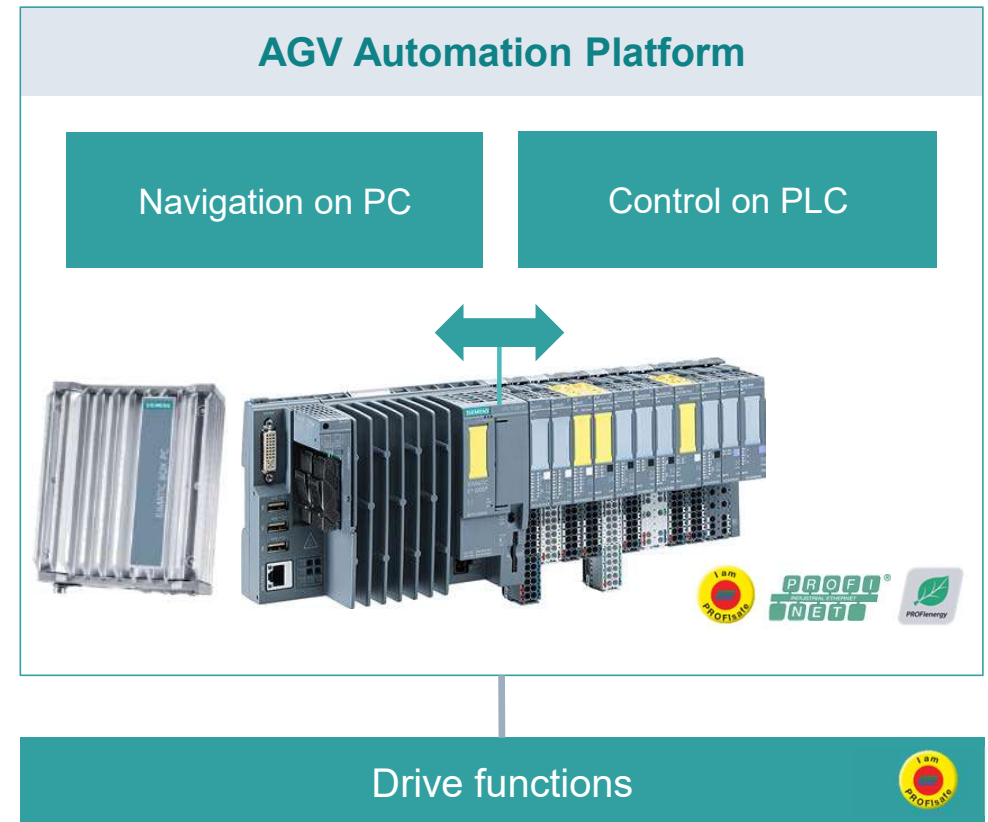
- Siemens ANS+ Navigation
- Integrated in common HW platform (PLC+PC with Linux)
- Supports 3rd party integration via open interface

Automation and Navigation – Integration of different AGV disciplines on one common system

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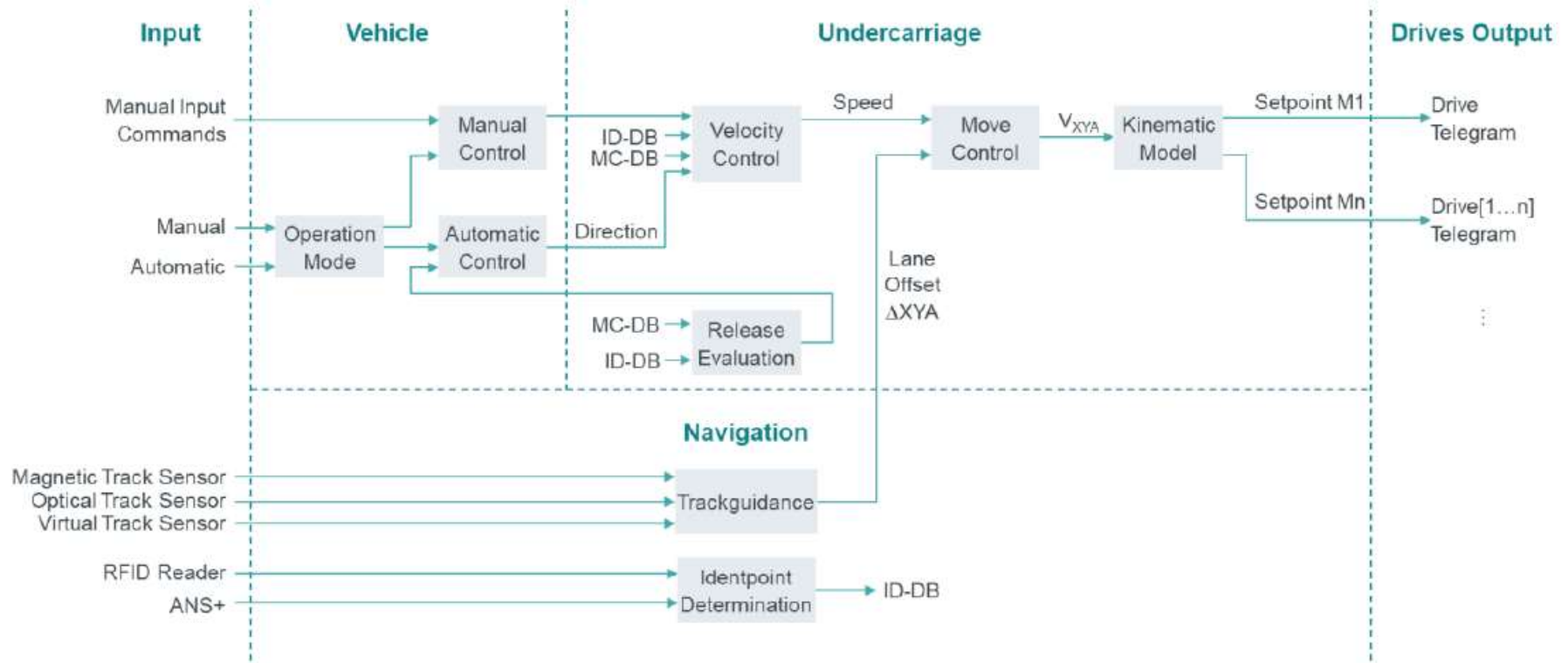
- Combine automation and navigation on one common HW platform
- Using appropriate operating systems
Navigation: Linux - Automation: PLC
- Integrated Safety supporting PROFIsafe



PLC program overview - Carrier Control Live Demo



Movement Control – Overview



Project tree

- Devices
 - SIMOVE_CarrierControl_Sample_V02.01.02
 - Add new device
 - Devices & networks
 - AGV_DEMO [CPU 1512SP-F-1 PN]
 - Device configuration
 - Online & diagnostics
 - Safety Administration
 - Software units
 - Program blocks
 - Add new block
 - Main [OB1]
 - Parameter [DB3]
 - Simulation [DB6]
 - FOB_RTG1 [OB123]
 - 10_UserBlocks
 - 90_Safety-UserBlocks
 - SafetyAGV [FB90]
 - SafetyEmergencyStop [FB93]
 - SafetyMain [FB1000]
 - SafetyPosition [FB91]
 - InstSafetyMain [DB1000]
 - SafetyInterfaceMC [DB922]
 - SectorTransponderData [DB921]
 - 99_Common
 - Custom
 - LSimoveC
 - SAFETY = siemens
 - System blocks
 - Technology objects
 - Energy objects
 - External source files
 - PLC tags
 - PLC data types
 - Watch and force tables
 - Online backups
 - Traces
 - OPC UA communication
 - Device proxy data
 - Program info
 - PLC supervisions & alarms
 - PLC alarm text lists
 - Online card data
 - Local modules



Properties Info Diagnostics

General

No 'properties' available.

No 'properties' can be shown at the moment. There is either no object selected or the selected object does not have any displayable properties.

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Carrier
Control

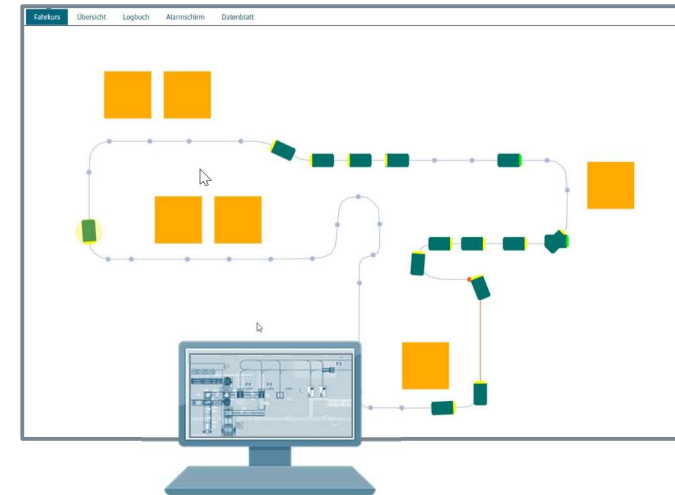
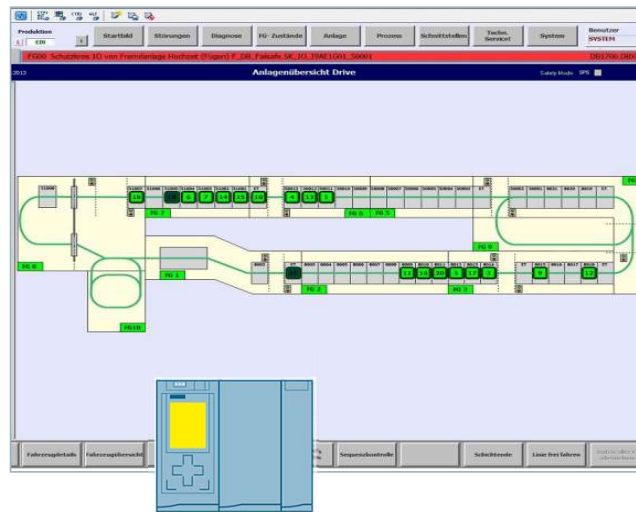
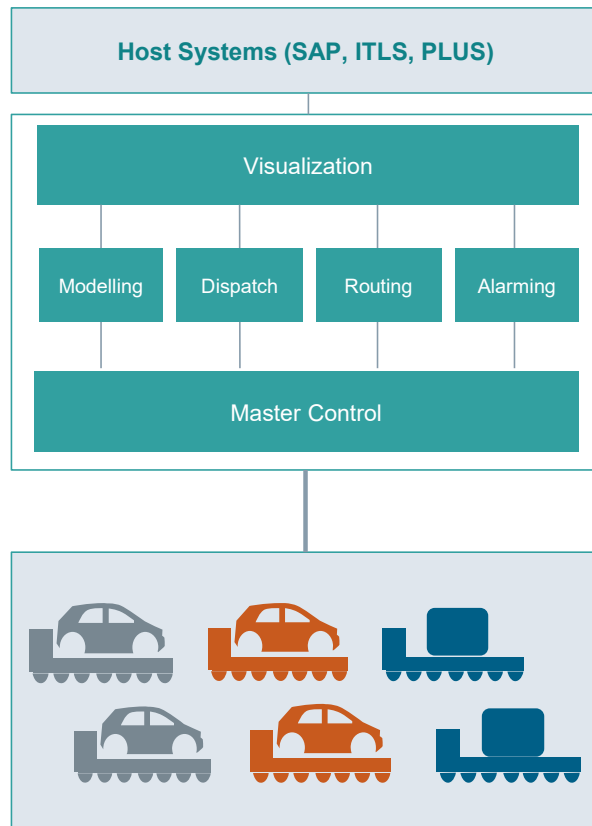
Navi-
gation

Master
Control



SIMOVE –

Integration of different AGVs in one common fleet management system

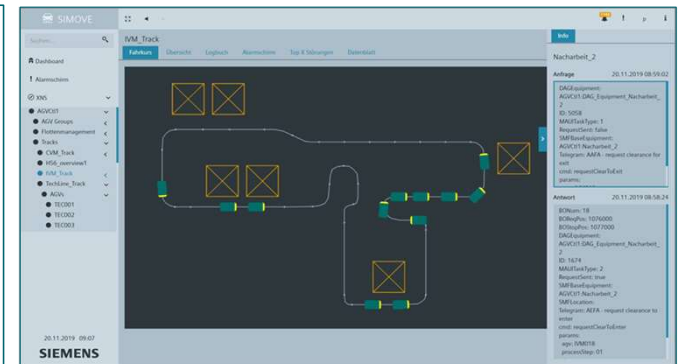
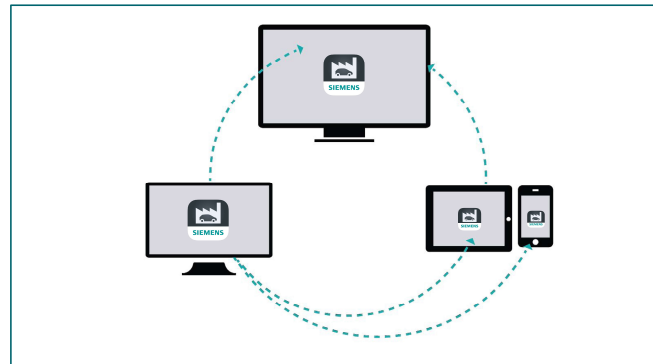


- Siemens offers both: PLC-controlled (PLC+WinCC) and PC-controlled (Windows+WinCC OA) fleet management
- Integrated safety functionality
- Scalable architecture enables system expandability
- Open interfaces to AGVs simplifies integration of different suppliers

Fleet Monitoring – Integrated SCADA and Line monitoring

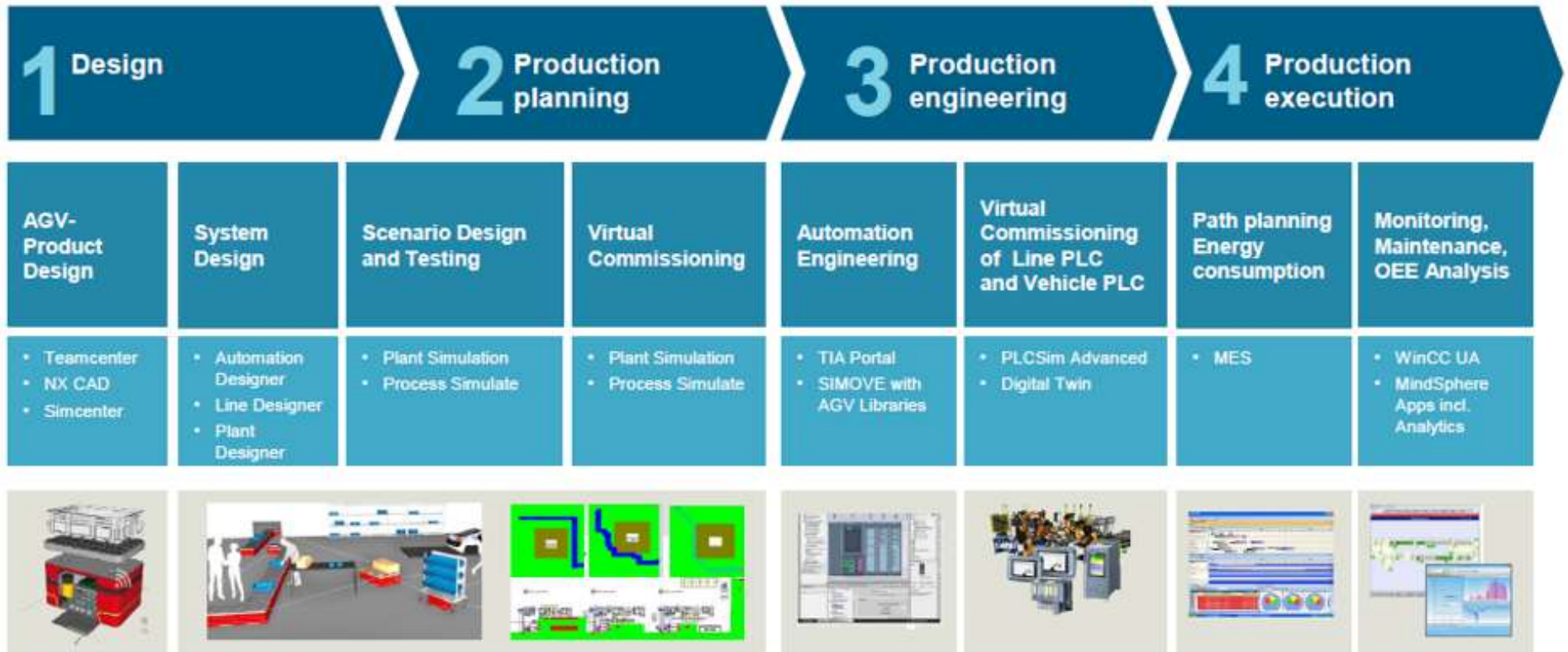


- Dashboard / Plant Overviews and Status Screen
- Alarm notification
- Top - X analyzes
- Logbook and work instruction
- System health check – connection monitoring
- OEE and KPI calculation
- Smart Scheduler incl. shift model editor
- Responsive HTML5 Client
- Full generic data driven UI
- Core SCADA functionality



Alert	Priority	System	Object	Text	Value	Direction	Time	Adt Time	Adt
A	50	System1	Building 1 Robot 1	TRLE	True	Dir	6/20/2019	11:05:46 AM	
I	10	System1	Robot 1	TRLE	True	Dir	6/18/2019	9:51:51 AM	
I	10	System1	Robot 1	TRLE	True	Dir	6/18/2019	9:51:51 AM	
I	10	System1	Building 1 Robot 1	TRLE	True	Dir	6/18/2019	9:51:49 AM	
I	10	System1	Building 1 Robot 1	TRLE	True	Dir	6/18/2019	9:51:49 AM	

Our AGV approach benefits from the digital tool chain and becomes a key element of the Digital Factory



Planning & Simulation of material and information flow with SIMOVE and the Siemens Digital Enterprise Suite

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Planning of flexible production systems with Plant Simulation

Simulation of material flow and information flow

Validate the AGV application (mechatronics) in the virtual world

Virtual Commissioning of SIMOVE applications via Process Simulate



SIMOVE-

Dedicated AGV Team and Demonstration Facility (Nuremburg)

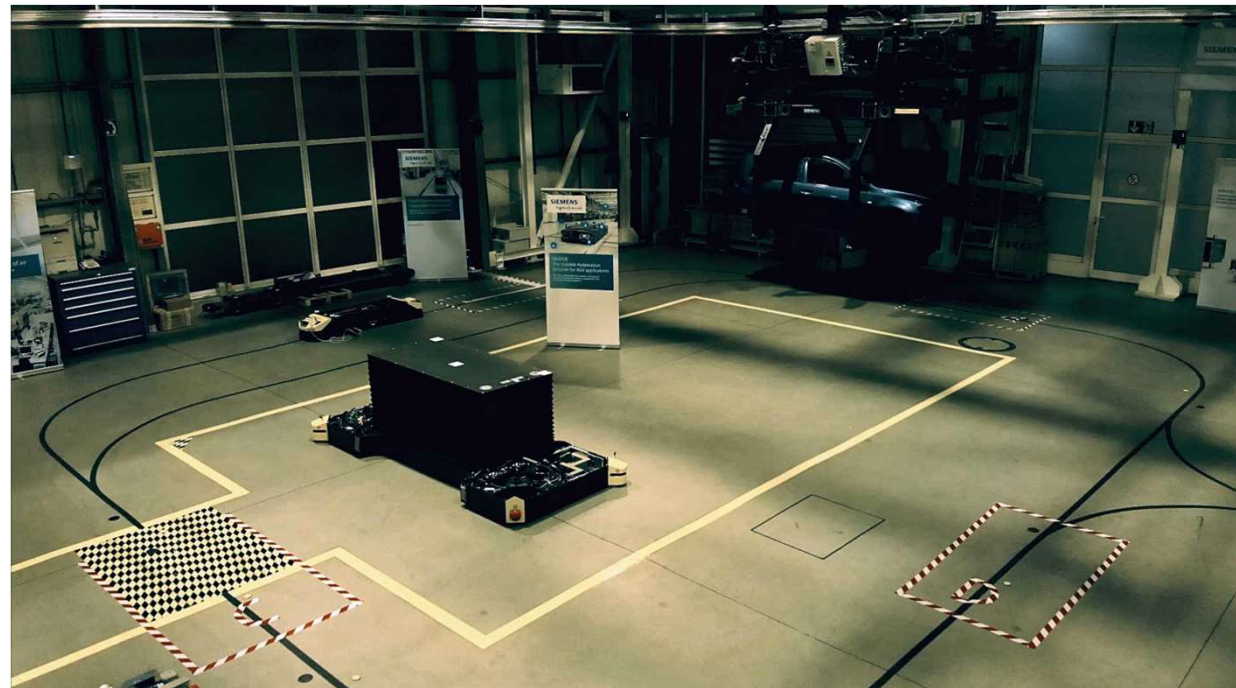


AGV Competency Centre

Showcasing AGV's, EMS and Ind.
WLAN, RTLS etc

SIMOVE Support Team

SUP FA for non Automotive



Documentation

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SIMOVE AGV System description

SIMOVE
<https://support.industry.siemens.com/cs/qa/view/1812514>

3 Engineering vehicle control

3.1 Path determination on the left (differential drive)

For direct calculation of the distance traveled.

On the left the absolute calculation of the traveled distance is measured. On the right, the calculation of the path with reference point (i.e. when selecting an identification point with selected homing, the current position value is set to the stored position value of the identification point).

Important: Even the homing of the absolute encoder position is absolutely necessary as otherwise the parameter may overflow. It is recommended to perform the homing at a specific identification point on the track.

Figure 3 - 10 Referencing the absolute path

Overriding the homing should be performed at an identification point which includes an exact stop (in order to increase the accuracy of the system).

Figure 3 - 61 Position detection left absolute and relative

SIMOVE System description
EmpoG 100/1600_V1.0_180219

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SIMOVE AGV Reference Manual

2 Cyclic interface

2.1 General

The cyclic interface consists of a defined size and can be used with different communication protocols:

- PROFINET (3 LAN-based)
- UDRP (Under development, not for safety control interface)

Besides the cyclically transmitted data acyclic information can be transmitted as well throughout the data structure. This acyclic part is used for the exchange of identification point data between Master Control and Carrier Control (download only).

2.2 Data types and encoding

All data types and encoding of variables in the chapter is according to SIEMENS SIMATIC 5T.

2.3 Non-safe interface between CC and MC

Figure 11 Data exchange between Master Control and Carrier Control

SIMOVE AGV Reference manual, software specification
EmpoG 100/1600_V1.1.2.0-180219

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SIMOVE AGV Reference Manual

2 Carrier Control

	1004453	SIEMENS laser scanner microSAS Pro - PROFIBET Type: MCR3-CRANOPROFI In distance: 0.1m
	1004453	For safety used the recognition MCR Vision Control and MCR20002 detecting object according to MCR category and product description
	1004453	SIEMENS safety relay Basic and Advanced series electronic safety relay - 16-channel I/O 4 x 16 V DC - 16-channel I/O 16 x 16 V DC

2.1.6.7 Drive system

	6ES7150-2BA10-0AA0	SIEMENS Microdrive FCC 100F
	6ES7150-2BA10-0AA0	SIEMENS Microdrive FCC 100F

SIMOVE AGV Reference manual, software specification
EmpoG 100/1600_V1.1.2.0-180219

Thank you for you attention.

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SIMATIC MICRO-DRIVE Wrap-up and Close

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[siemens.com/micro-drive](https://www.siemens.com/micro-drive)



SIMATIC MICRO-DRIVE

Launch Review – Product Overview



Product Highlights

Fast and Safe Communication via PROFINET ✓
PDC: IRT (<1ms)

Single Cable Connection to Motor Available ✓
Save time during commissioning

Ultra Low Voltage ✓
0.1 kW – 1 kW at 24-48V
With Energy Regen

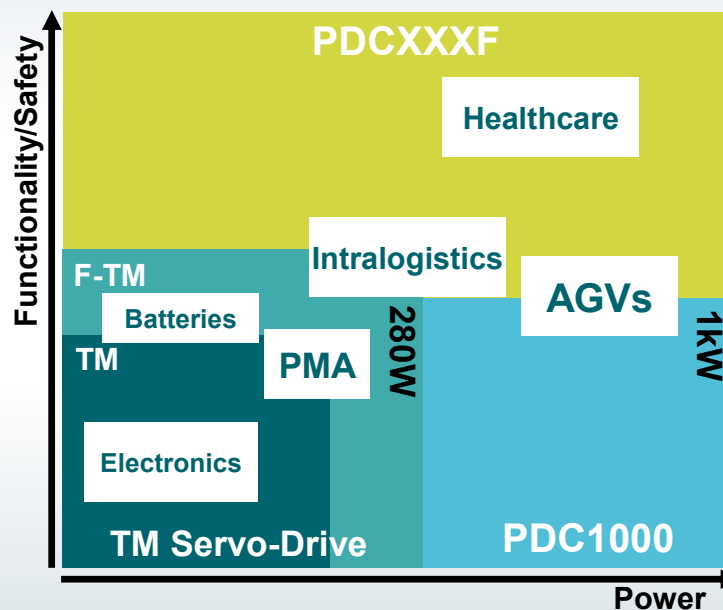
PDC: Safety integrated with new function: Safe Limit Torque ✓
Via PROFISAFE

Easy Commissioning via TIA Portal ✓
Single Button Tuning

F-TM Servo Drive: Power dense, integrated STO function ✓
(SIL2/hardwired)

Market Position

Ultra Low Voltage DC Drives Market <60V
Expected Market Size = £2⁴



System Overview



SIMATIC MICRO-DRIVE

Launch Review – Use Cases and Value



Example Use Cases and Value added

Autonomous Guided Vehicles (AGVs)

Application industries:

- Automotive
- Intralogistics
- food and bev, etc.

Key Features:

- Compact
- Battery powered
- High resolution position
- complex safety features



Value Added:

- Reduced costs – **no DC/AC Converter Required**
- reduced commissioning time with **single button tuning**
- **Sensorless safety functions** reduces development and parts costs
- **SIMOVE** and **SIMATIC tech support** provide confidence in AGV longevity

Positioning – Medical Imaging

Key Features:

- Compact
- Low Power: Single Phase Supply
- DC: Low EMC
- High Resolution Position
- Safety Functions
- Easily scalable Projects in TIA
- 4 levels of SLT



Value Added:

- **Sensorless safety features** reduces cost
- Safety features mean it can be used with people
- Reduced **commissioning time**
- Reduced **Engineering time**
- Standard **single phase** mains electricity can be used

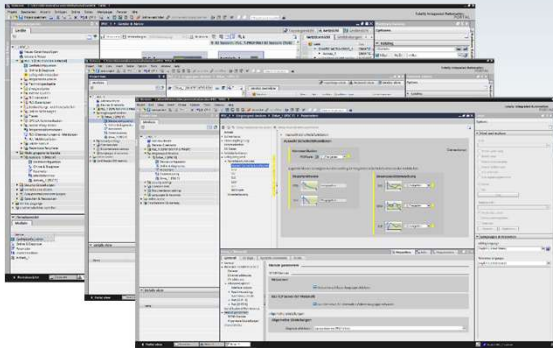
SIMATIC MICRO-DRIVE Launch Review – Software and Support Tools



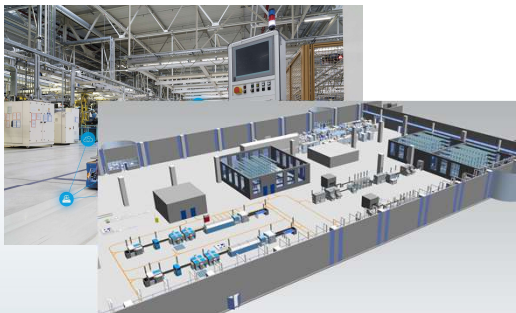
Engineering and Virtual Commissioning

Sales and Support Tools

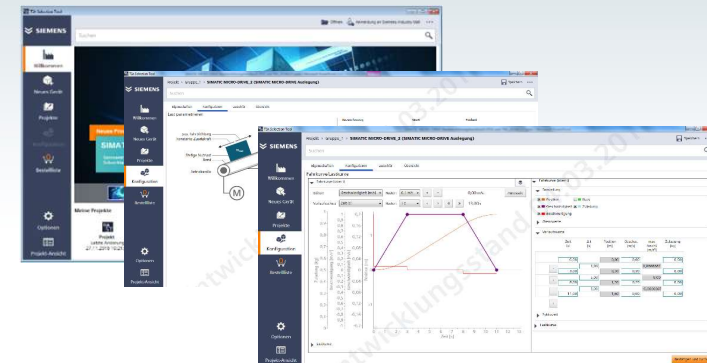
Engineering Using TIA Portal, HSP available from SIOS Site



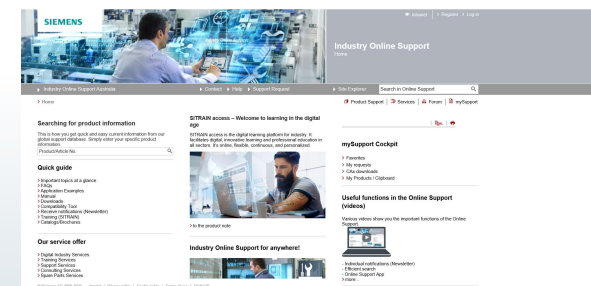
SIMOVE for AGVs and Plant Simulation



Simple Drive Sizing using the TIA Selection tool for Micro-Drive



SIMATIC Technical Support Accessed by SIOS Webpage



SIMATIC Micro Drive



SIMATIC Micro-Drive

Virtual Product Launch
Wednesday 10th June 2020

Agenda

Session 1 – 09:00 – 10:00

Micro-Drive Product Details, distribution, and product partners.

Session 2 – 10:15 – 11:15

Micro-Drive Product Support, Technical Details, and Demonstration.

Session 3 – 11:30 – 12:30

Sales Support Tools, SIMOVE, and Plant Simulator.