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SE-134C GROUND FAULT
GROUND CHECK MONITOR MANUAL

FPU-32 FEEDER PROTECTION
UNIT MANUAL

BENSHAW DATA SHEETS

FPU-32 DVD

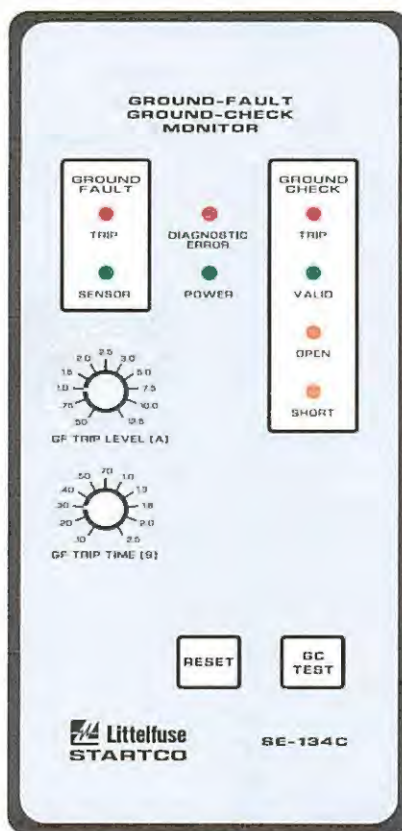
COMMUNICATION CABLE

SE-134C MANUAL

GROUND-FAULT GROUND-CHECK MONITOR

DECEMBER 16, 2009

REVISION 5



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DISCLAIMER

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1. GENERAL

The SE-134C is a microprocessor-based, combination ground-fault and ground-wire monitor for resistance-grounded systems. It has a switching power supply that accepts a wide range of ac and dc voltages, its specifications apply over an industrial temperature range at high humidity, and it meets the IEEE surge-withstand-capability tests (oscillatory and fast transient) for protective relays and relay systems. Isolated, normally open and normally closed contacts are provided for contactor control or for shunt or undervoltage operation in a breaker-trip circuit. All operating conditions are clearly annunciated and two Form C contacts are provided for remote indication. The SE-134C is housed in an anodized extruded-aluminum enclosure, and all connections are made with plug-in, wire-clamping terminal blocks. Provision is made for both panel and surface mounting.

The ground-fault circuit detects fundamental-frequency, zero-sequence current with a window-type current sensor and it verifies that the current sensor is connected and not shorted. A definite-time characteristic with 11 trip levels and 11 trip times allows coordination in virtually any resistance-grounded system. Although other current sensors may satisfy the verification circuit, only SE-CS10-series sensors have characteristics that meet system specifications. Current-sensor verification can be disabled for a ground-check-only application.

The ground-check circuit has an open-circuit voltage of 24 Vdc, which is not a hazard to personnel, and it has an output drive current above 100 mA for optimum performance in slip-ring, commutated-load, and high-induced-ac applications. Features include an externally accessible ground-check fuse, a resistance-insertion test, 3-kV isolation between the ground-check loop and the monitor electronics, and a PPI-600V accessory for parallel-ground-path rejection. A PPI-600V will also eliminate intermachine arcing and prevent stray ac and dc currents from flowing in the monitored ground wire. Unlike ground-check circuits using other termination devices, and especially those with phase-reversal switches, a ground-check circuit using a termination device with a Zener characteristic is capable of loop measurements that are independent of current in the phase conductors. The SE-134C ground-check circuit recognizes the SE-TA6A-series 5.6-volt Zener characteristic as a valid end-of-line completion. This is the only passive characteristic that will satisfy the ground-check circuit's multi-level drive, allow induced currents to circulate in the ground-check loop, survive a phase-to-ground-check fault, and clamp the ground-check voltage during the fault. Although a standard 5.6-volt Zener diode may engage the SE-134C's ground-check circuit, only an SE-TA6A-series termination assembly has the compensation required to meet system specifications. In

select applications, a combination of an SE-TA12A and SE-TA12B Termination Assemblies can be used to monitor the cables of a splitter box (junction box) using a single SE-134C Monitor. See Technical Note GC-11, available at www.startco.ca.

2. OPERATION

2.1 GROUND-FAULT CIRCUIT

2.1.1 GF TRIP TIME SETTING

The ground-fault circuit has a definite-time characteristic with 11 settings from 0.1 to 2.5 seconds. Time-coordinated ground-fault protection requires the trip time to be longer than the trip time of downstream ground-fault devices.

2.1.2 GF TRIP LEVEL SETTING

The trip level of the ground-fault circuit is switch selectable with 11 settings from 0.5 to 12.5 A. A minimum tripping ratio of 5 is recommended to achieve at least 80% winding protection, and this requires the trip level to be less than 20% of the grounding resistor let-through current. Suggested trip-level ranges for 5-, 15-, and 25-A neutral-grounding resistors are indicated on the faceplate. A ground-fault trip is latched, requiring a reset. A current-sensor failure will also cause a ground-fault trip. See Section 3.1.

If the SE-134C is operated in a ground-check-only application and an SE-CS10 is not connected, connect terminals 17 and 18 to disable sensor verification. See Fig. 1.

2.2 GROUND-CHECK CIRCUIT

The ground-check loop consists of the outgoing ground-check conductor, quick-coupler connections, the SE-TA6A-series termination assembly, the SE-TA6A connection to equipment frame or ground bus, the ground-return path, and the SE-134C cable-ground-terminal connection to substation ground.

The SE-134C detects a valid ground-check loop when an SE-TA6A-series termination assembly is detected in the loop and loop resistance is less than 28 ohms. The loop is not valid if open (or high resistance), or if the ground-check conductor is shorted to ground.

When the ground-check loop is valid, the SE-134C ground-check circuit can be tested by pressing the GC TEST switch or by shorting GC TEST terminals 11 and 12. This test invalidates the loop by inserting 47 Ω in the ground-check loop and a trip should occur in less than 250 ms.

The ground-check circuit is usually operated in the non-latching mode; however, it can be operated in the latching mode by connecting terminals 14 and 15.

The ground-check circuit is protected by a 1.5-A time-delay fuse (F1).

If the SE-134C is used in a ground-fault-only application, an SE-TA6A must be connected to the ground-check and cable-ground terminals to validate the ground-check circuit. See Fig. 1.

2.3 RESET

All ground-fault trips are latching and ground-check trips can be latching or non-latching. To reset ground-fault trips or latching ground-check trips, press the RESET switch or short the RESET terminals 9 and 10. See Fig. 1.

Cycling the supply voltage will also reset ground-fault trips; however, if the ground-check circuit is configured for latching fail-safe operation, the ground-check circuit will trip when supply voltage is applied.

The single-shot reset circuit responds only to a momentary closure; a jammed or shorted switch will not maintain a reset signal.

2.4 TRIP RELAY

Isolated, normally open (Trip A, terminals 24 and 25) and normally closed (Trip B, terminals 22 and 23) contacts are provided for use in a contactor- or breaker-control circuit. With no connection between terminals 12 and 13, the SE-134C trip relay operates in the fail-safe mode. This mode is used with undervoltage devices where the trip relay energizes and its normally open contact closes if the ground-fault and ground-check circuits are not tripped. This mode is recommended because:

- Undervoltage devices release if supply voltage fails.
- Undervoltage ground-check circuits do not allow the power circuit and open cable couplers to be energized until the ground-check loop is verified.

The fail-safe mode of operation of the SE-134C trip relay can be used for shunt-trip circuits with a stored-energy trip source. In this case, the normally closed trip contact is used—the contact opens when the SE-134C is energized and the ground-fault and ground-check circuits are not tripped. Care must be taken to ensure safe and correct operation during power up and power down.

Connect terminals 12 and 13 for non-fail-safe trip relay operation with shunt-trip devices. In this mode, the normally open trip contact is used—the trip contact is closed when a ground-fault or ground-check trip occurs.

Shunt-trip circuits are not fail-safe and are not recommended because:

- Shunt-trip devices do not operate if supply voltage fails.
- Shunt-trip ground-check circuits allow the power circuit and open cable couplers to be energized for a short interval after supply voltage is applied.

CAUTION: The SE-134C is not a lock-out device. Follow lock-out procedures for maintenance.

3. INDICATION

3.1 GROUND FAULT

A red LED indicates a ground-fault trip and the remote-indication relay GF is energized when the ground-fault circuit is not tripped (fail-safe indication-contact operation). A green LED indicates a current sensor is correctly connected. If the SE-CS10-series current sensor is disconnected or shorted, the green LED will go out and the ground-fault circuit will trip. If the sensor fault is intermittent, the ground-fault circuit will trip and the green LED will flash to indicate that the trip was initiated by a sensor fault.

3.2 GROUND CHECK

A red LED indicates a ground-check trip. A green LED indicates a valid ground-check loop and the remote-indication relay GC is energized when the ground-check loop is valid (fail-safe indication-contact operation). Two yellow LED's indicate the status of an invalid ground-check loop. OPEN indicates the loop resistance exceeds the trip resistance and SHORT indicates the ground-check conductor is shorted to the ground conductor. A flashing yellow LED indicates the corrected cause of a latched ground-check trip.

3.3 POWER

The green POWER LED indicates that the internal power supply is on.

3.4 DIAGNOSTIC ERROR

The red DIAGNOSTIC ERROR LED indicates that an internal error caused the SE-134C to trip. Return the SE-134C to the factory if a reset does not clear the trip.

Induced ac current in the ground-check loop can cause the LED to flicker. This is a normal condition and does not indicate a diagnostic error; the ground-check monitoring circuit is not affected.

4. INSTALLATION

4.1 GENERAL

This ground-fault ground-check monitoring system consists of an SE-134C Monitor, an SE-CS10-series Current Sensor, and an SE-TA6A-series Termination Assembly connected as shown in Fig. 1. Select applications can use a combination of SE-TA12A and SE-TA12B Termination Assemblies. See Technical Note GC-11. If required, remote indication and reset can be with standard pilot devices, or with an RK-132 Remote-Indication-and-Reset Kit.

4.2 MONITOR

Each SE-134C is packaged with both panel- and surface-mounting hardware.

Outline and panel-cutout dimensions for the SE-134C are shown in Fig. 2. To panel mount the SE-134C, insert it through the panel cutout and secure it with the four supplied 8-32 locknuts and flat washers.

All connections to the SE-134C are made through plug-in, wire-clamping terminal blocks for 24 to 12 AWG (0.2 to 2.5 mm²) conductors. Each plug-in terminal block can be secured to the monitor by two captive screws for reliable connections in high-vibration applications.

Outline dimensions and mounting details for surface mounting an SE-134C are shown in Fig. 3. Fasten the surface-mount adapter to the mounting surface and make connections to the adapter terminal blocks. Follow the instructions on Fig. 3 to mount or remove the SE-134C.

The option -00 power supply operates from 60 to 265 Vac and 80 to 370 Vdc. The option -10 power supply operates from 24 to 48 Vdc. Use terminal 2 (L2/N) as the neutral terminal on ac systems or the negative terminal on dc systems.

NOTE: On revision 5 and newer units, terminal 3 (SPG) is internally connected to terminal 4. For these units an external terminal-3-to-terminal-4 connection is not required, nor is it necessary to remove the terminal-3 connection for dielectric-strength testing.

4.3 CURRENT SENSORS

Outline dimensions and mounting details for the SE-CS10-series current sensors are shown in Fig. 4. Pass only phase conductors through the sensor window as shown in Fig. 1. If a shield, ground, or ground-check conductor enters the sensor window, it must be returned through the window before it is terminated. Connect the current sensor to terminals 16 and 17. Ground terminal 17. Current-sensor primary and secondary connections are not polarity sensitive.

4.4 TERMINATION ASSEMBLY

Outline dimensions and mounting details for the SE-TA6A, SE-TA6A-WL, and SE-TA6ASF-WL are shown in Figs. 5 and 6. Install the SE-TA6A at the load to complete the ground-check loop as shown in Fig. 1. Connect terminal G of the SE-TA6A to the equipment frame so that the ground-conductor-to-equipment-frame connection will be included in the monitored loop.

4.5 REMOTE OPERATION

Remote indication contacts and a reset input are provided for remote indication and remote reset as shown in Fig. 1.

The optional 22-mm-component RK-132 Remote Kit is shown in Fig. 7. Connect terminals of the green ground-check indicator to SE-134C terminals 26 and 27 and the red ground-fault indicator to terminals 19 and 21. For remote reset, connect the normally open push-button switch across terminals 9 and 10.

4.6 PARALLEL-PATH ISOLATION

A PPI-600V can be used for parallel-path rejection. A PPI-600V will also eliminate inter-machine arcing and prevent stray ac and dc currents from flowing in the monitored ground wire. See Figs. 8 and 9. See Technical Note GC-10 "Parallel Path Isolator" at www.startco.ca, or contact Littelfuse Startco for application details.

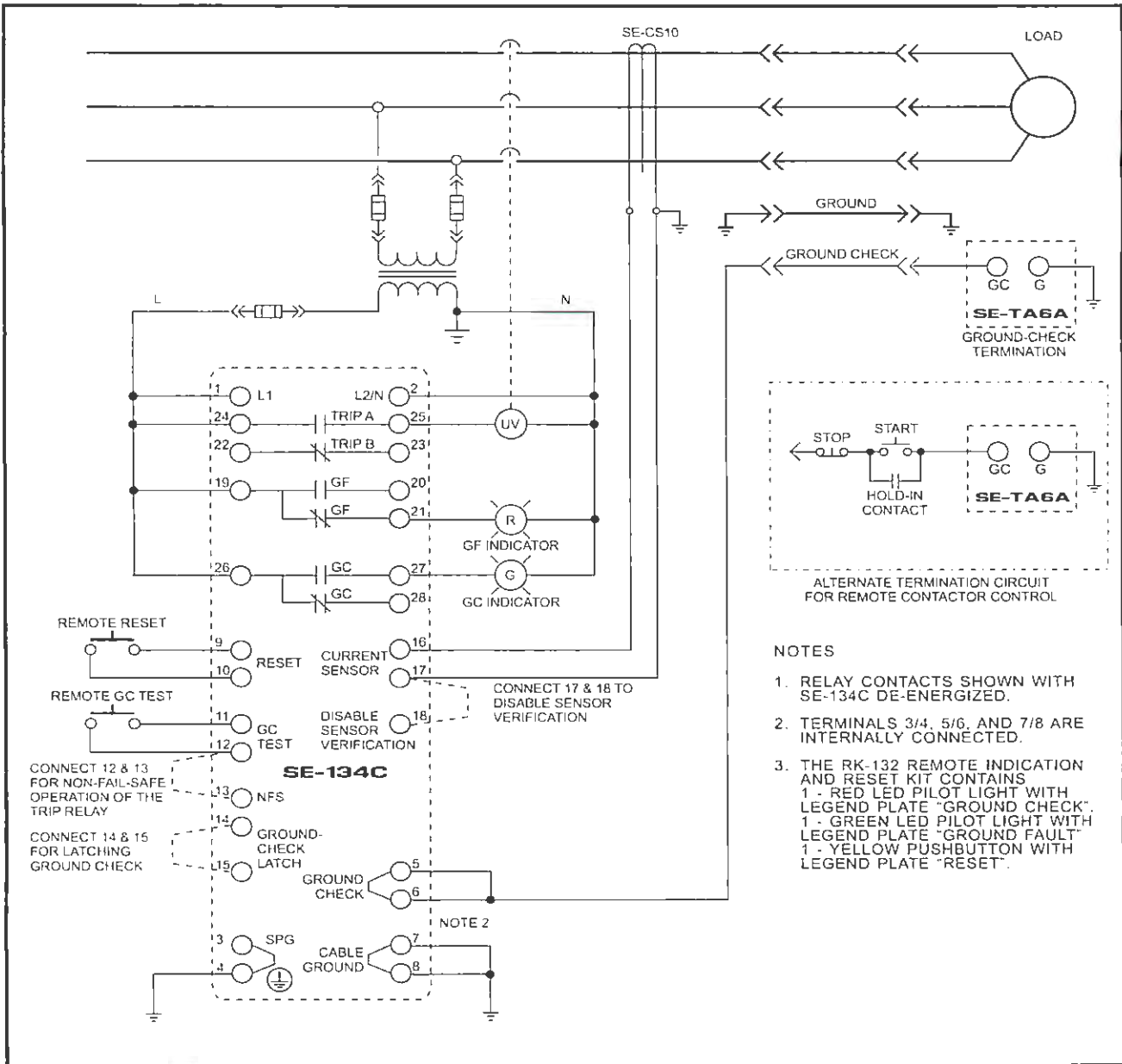


FIGURE 1. SE-134C Typical Application.

NOTES

1. RELAY CONTACTS SHOWN WITH SE-134C DE-ENERGIZED.
2. TERMINALS 3/4, 5/6, AND 7/8 ARE INTERNALLY CONNECTED.
3. THE RK-132 REMOTE INDICATION AND RESET KIT CONTAINS
 1 - RED LED PILOT LIGHT WITH LEGEND PLATE "GROUND CHECK"
 1 - GREEN LED PILOT LIGHT WITH LEGEND PLATE "GROUND FAULT"
 1 - YELLOW PUSHBUTTON WITH LEGEND PLATE "RESET".

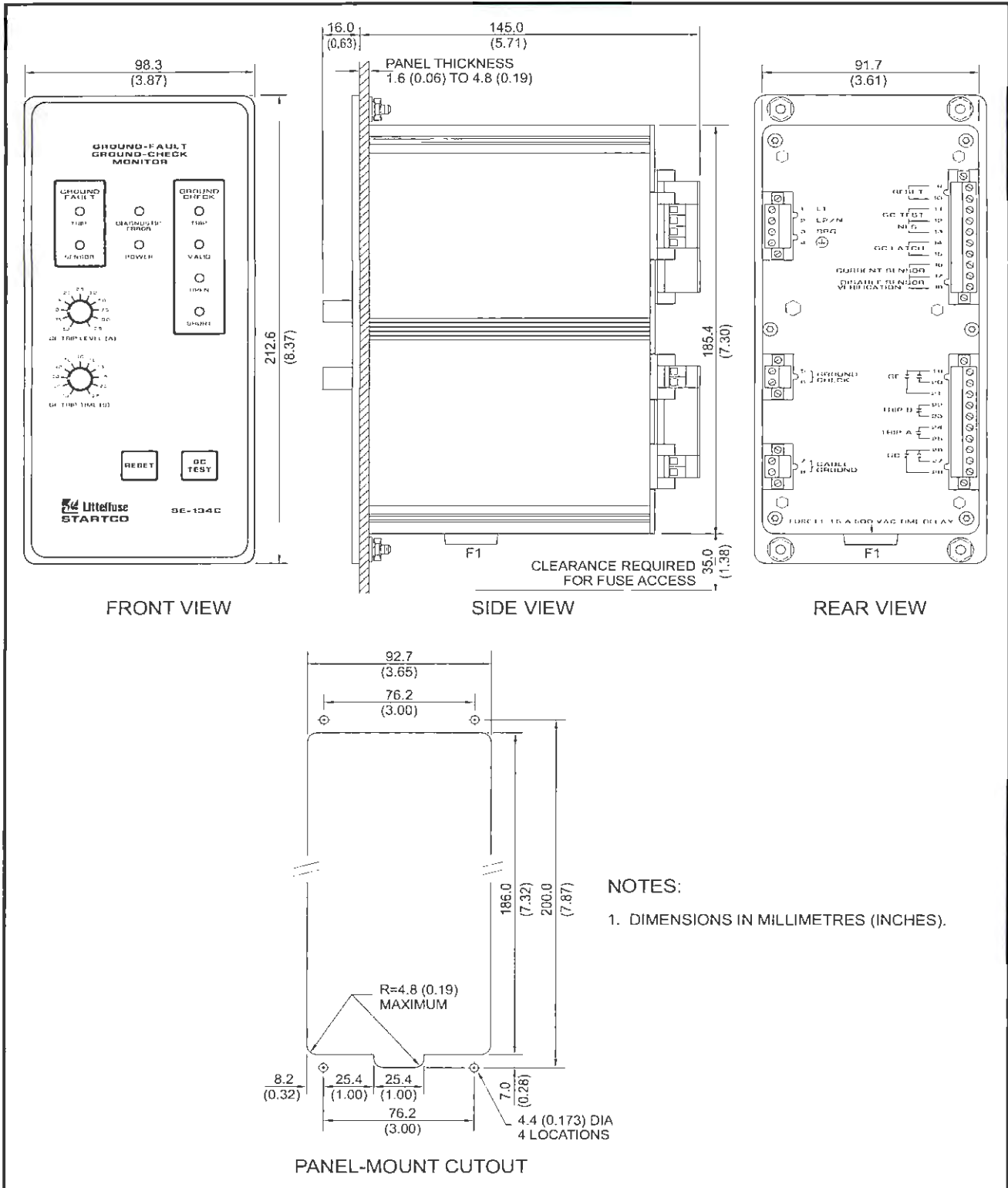


FIGURE 2. SE-134C Outline and Panel-Mounting Details.

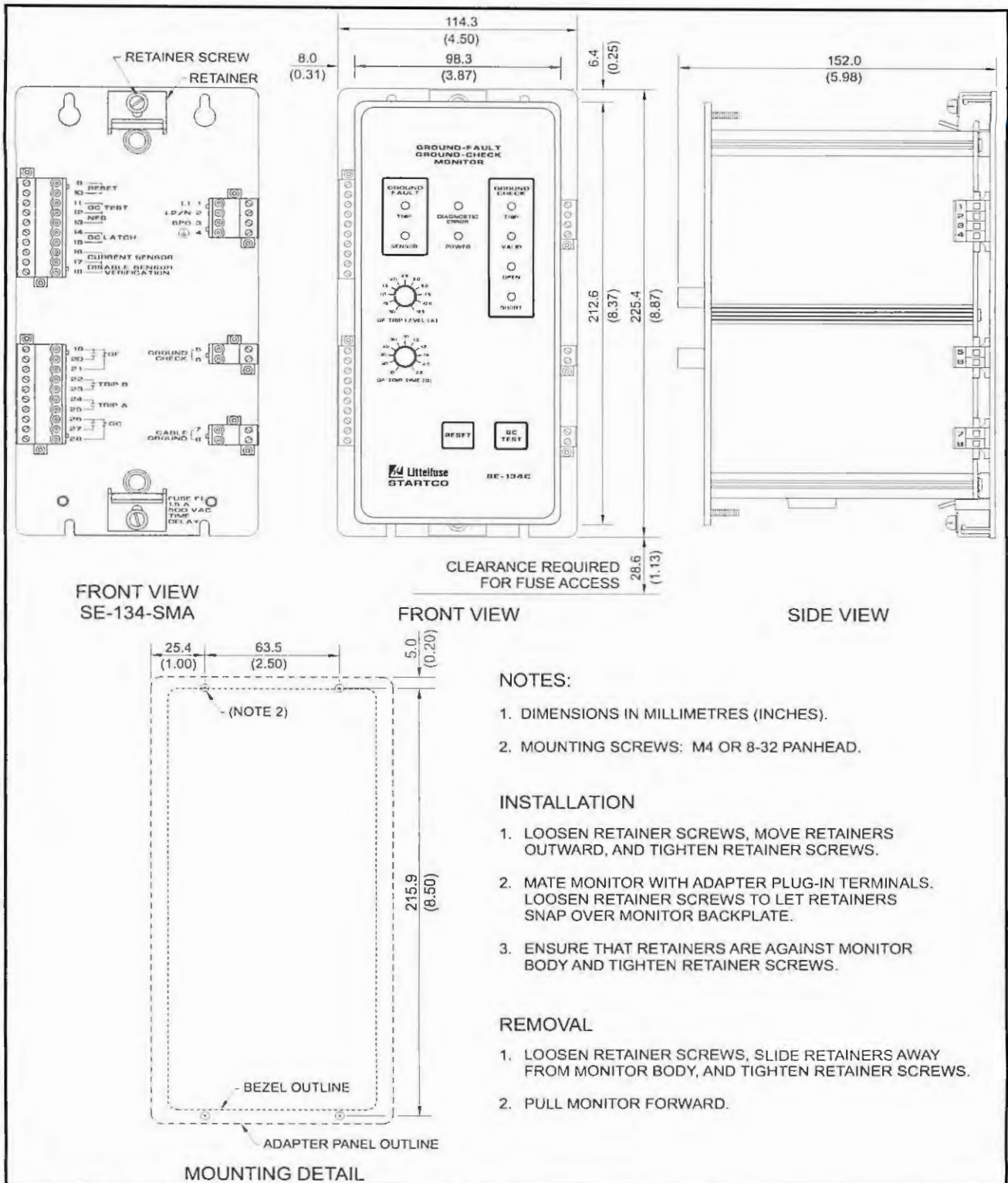


FIGURE 3. SE-134C Outline and Surface-Mounting Details.

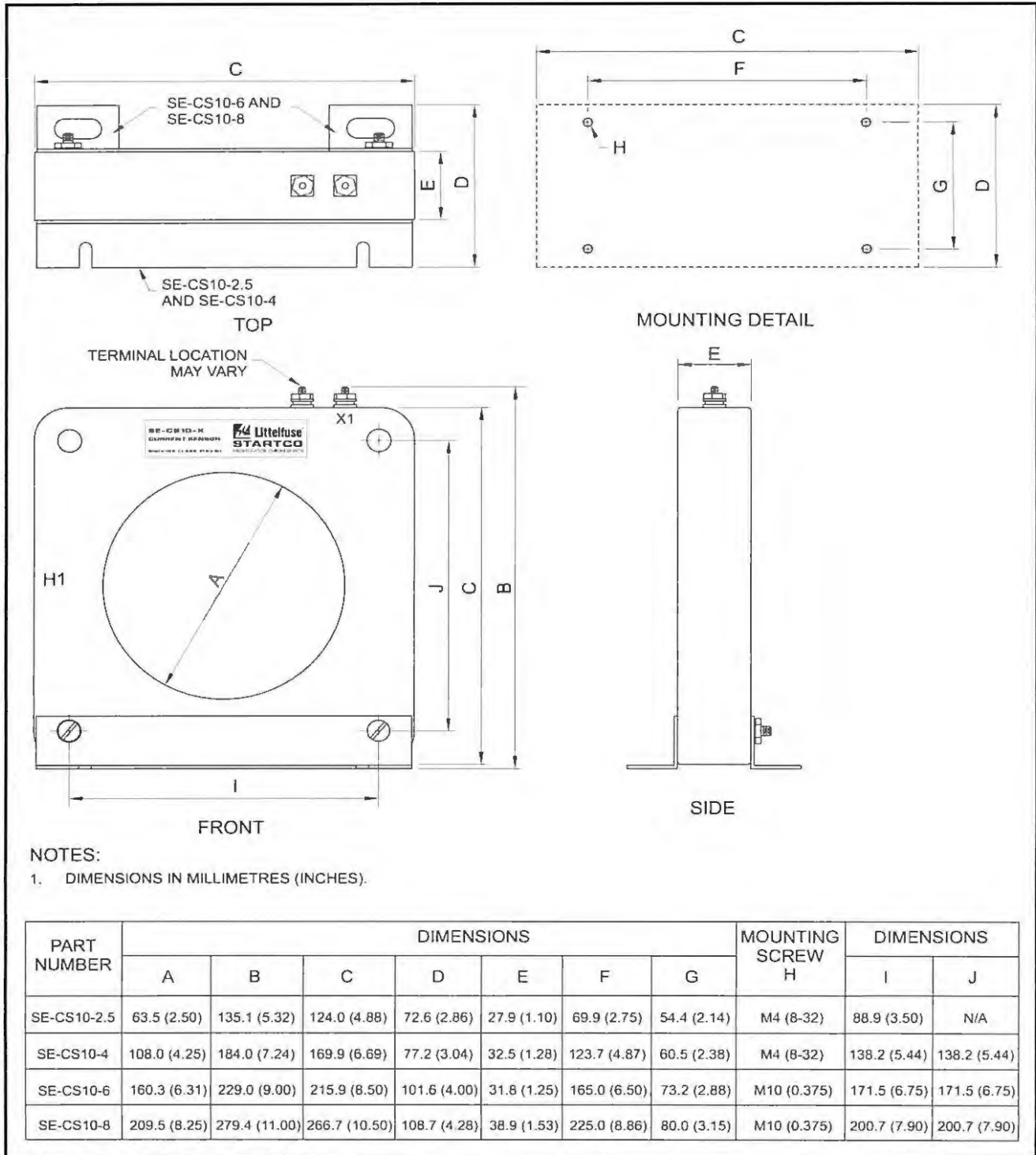


FIGURE 4. SE-CS10 Current Sensors.

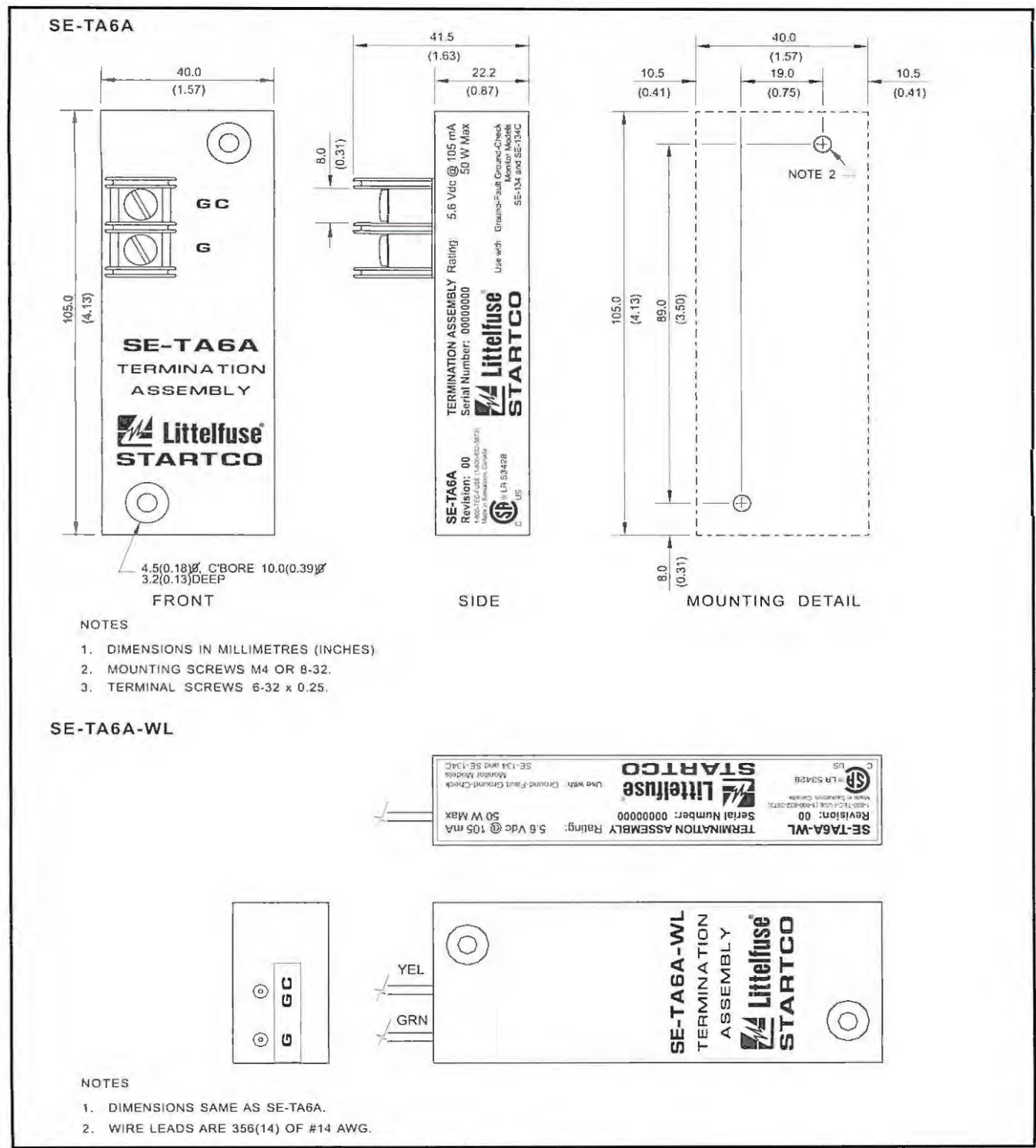


FIGURE 5. SE-TA6A and SE-TA6A-WL Termination Assemblies.

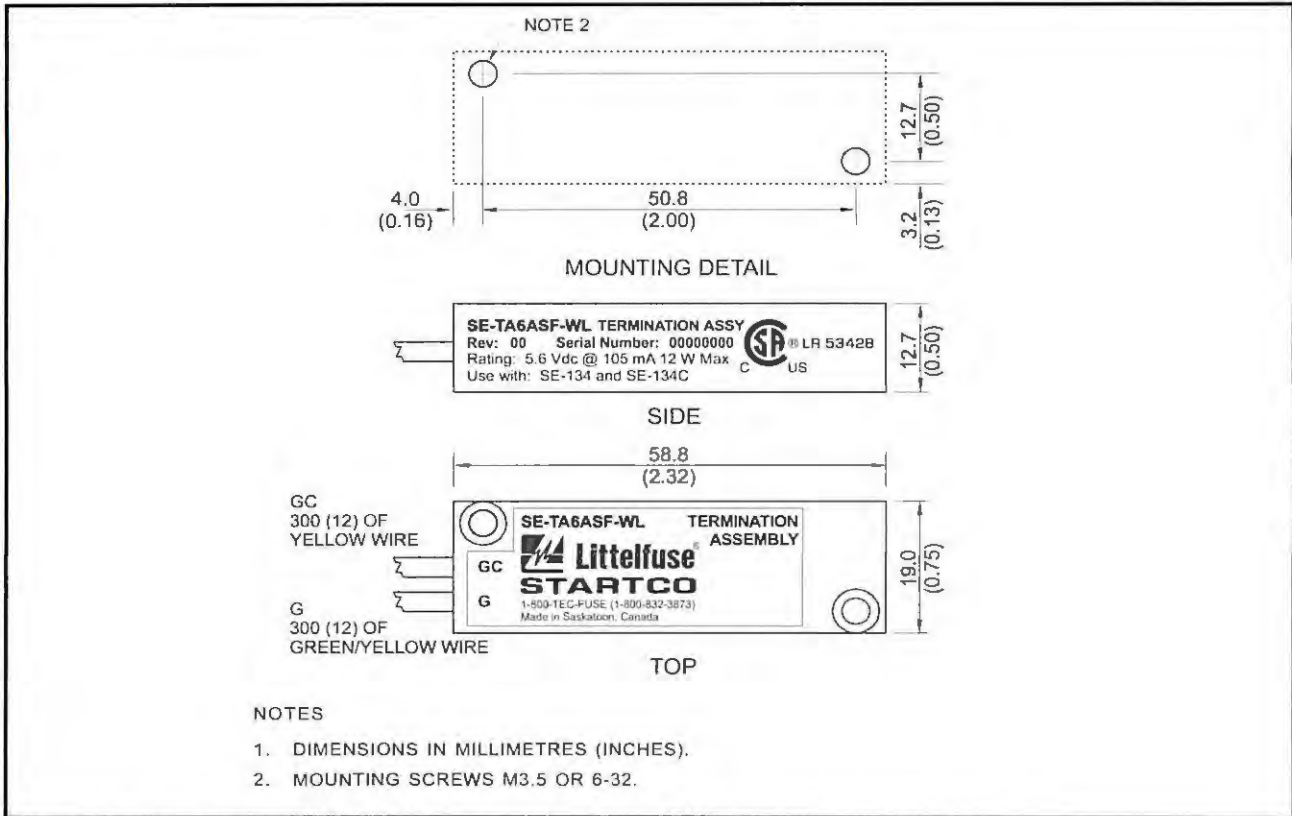


FIGURE 6. SE-TA6ASF-WL Small-Format Termination Assembly.

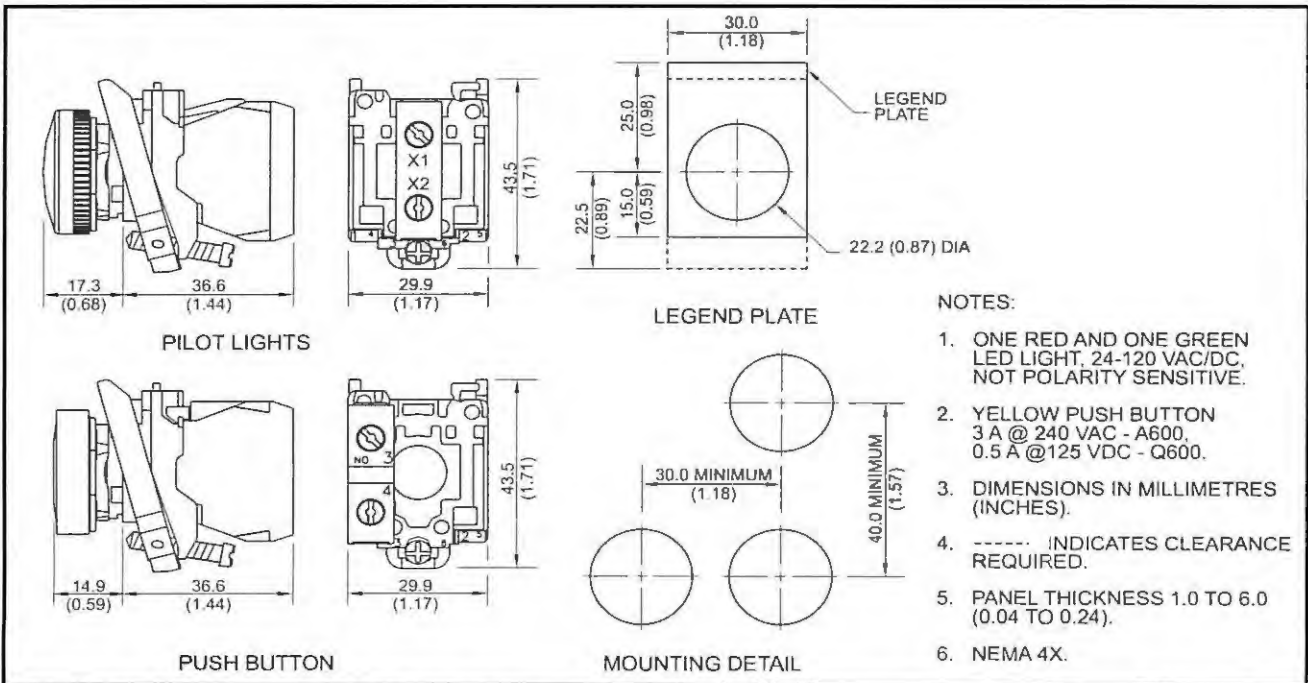


FIGURE 7. RK-132 Remote Indication and Reset.

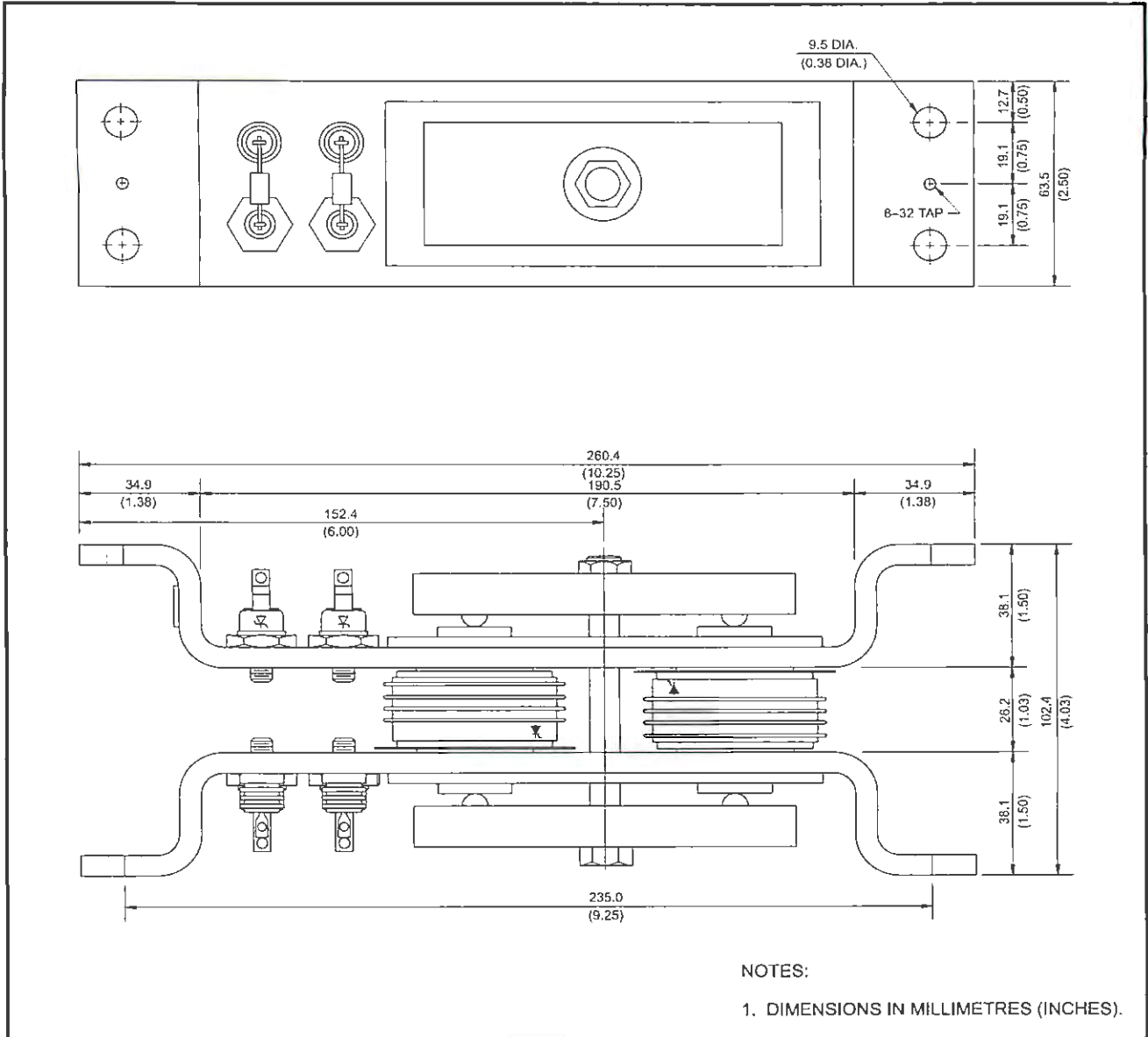


FIGURE 8. PPI-600V Parallel-Path Isolator.

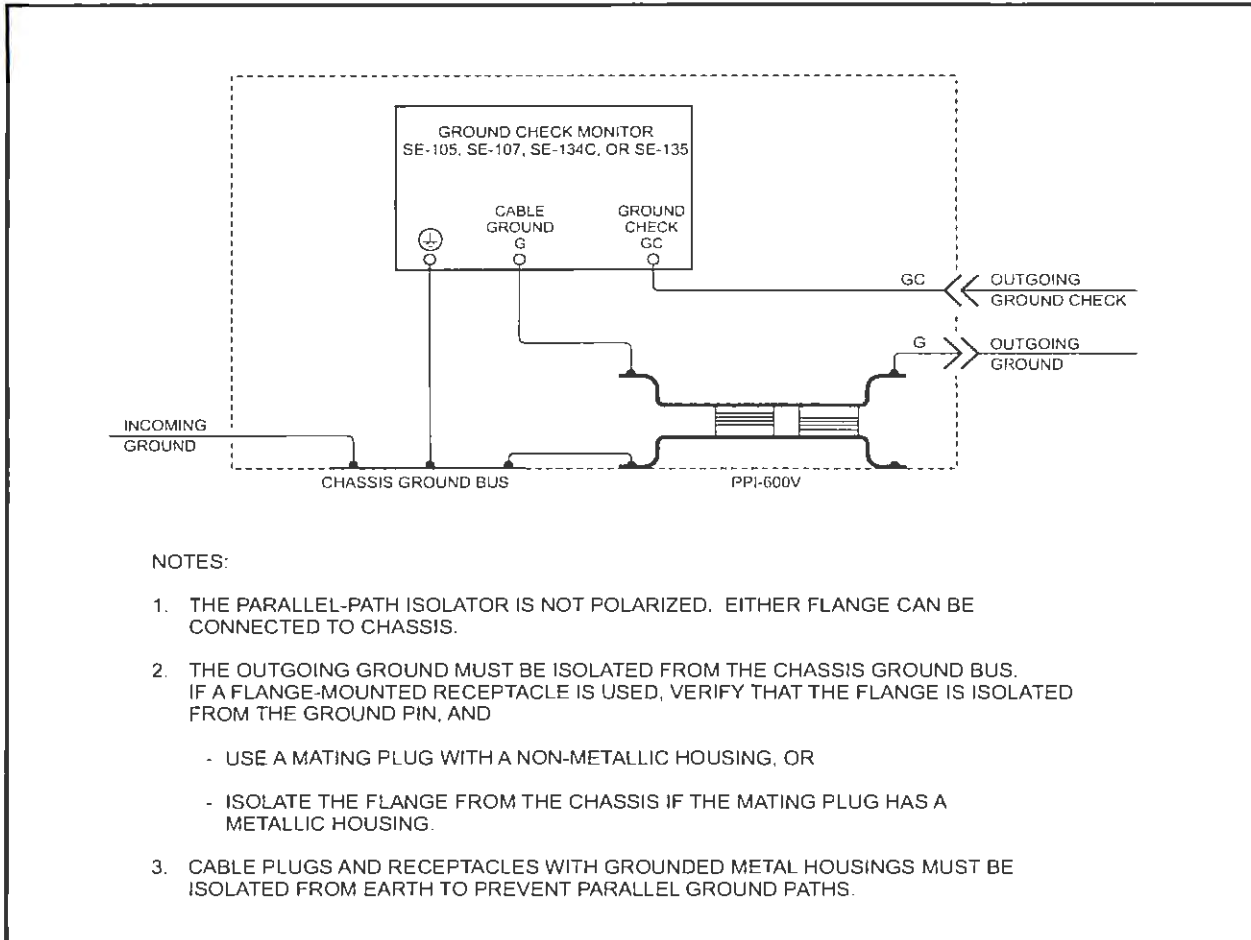


FIGURE 9. PPI-600V Typical Installation.

5. TECHNICAL SPECIFICATIONS

5.1 SE-134C

Supply:

Option 00.....	25 VA, 120-240 Vac (+10, -45%), 50-400 Hz, 15 W, 110-250 Vdc (+10, -25%)
Option 10	15 W, 24-48 Vdc (+50, -25%) 20 VA, 24-48 Vac (+10, -55%), 50-100 Hz

Ground-Fault Circuit:

Digital Filter.....	50 to 60 Hz, Bandpass
3 dB Frequency Response..	30 to 90 Hz
Trip-Level Settings	0.5, 0.75, 1.0, 1.5, 2.0, 2.5, 3.0, 5.0, 7.5, 10.0, and 12.5 A
Trip-Time Settings	0.1, 0.2, 0.3, 0.4, 0.5, 0.7, 1.0, 1.3, 1.6, 2.0, and 2.5 s
Thermal Withstand.....	150 A Continuous 1,000 A for 2.5 s (Ground-Fault Current)
Sensor Lead Resistance.....	2 Ω maximum
Trip-Level Accuracy	± 5% or 0.1 A
Trip-Time Accuracy.....	+50, -15 ms
Sensor Verification	Enabled or Disabled
Operating Mode	Latching

Ground-Check Circuit:

Open-Circuit Voltage.....	24 Vdc
Output Impedance	136 Ω
Loop Current.....	105 mA
Induced ac Withstand.....	60 Vac Continuous, 120 Vac for 10 s, 250 Vac for 0.25 s
Pull-in Time	≤ 750 ms
Trip Resistance.....	28 Ω ± 10%
Trip Time @ 50 Ω.....	220 ± 30 ms
Isolation.....	3 kV, 60 Hz, 1 s
Test	Front-Panel Switch and Remote, N.O. Contact
Fuse Rating (F1).....	1.5 A, 500 Vac, Time Delay
Fuse Part Number.....	FNQ 1½ Buss Fusetron
Operating Mode	Latching or Non-Latching

Trip Relay:

CSA/UL Contact Rating	8 A Resistive 250 Vac 5 A 30 Vdc, ¼ HP, B300 Pilot Duty
Supplemental Contact Ratings:	
Make/Carry (0.2 s).....	30 A
Break dc	75 W Resistive, 35 W Inductive (L/R < 0.04)

Break ac.....	2,000 VA Resistive, 1,500 VA Inductive (PF > 0.4)
---------------	---

Subject to maximums of 8 A and 250 V (ac or dc)	
Contact Configuration.....	Isolated N.O. and N.C. Contacts
Operating Mode	Fail-Safe or Non-Fail-Safe

Remote-Indication Relays:

CSA/UL Contact Rating	8 A Resistive 250 Vac 8 A 30 Vdc
----------------------------	-------------------------------------

Supplemental Contact Ratings:

Make/Carry (0.2 s).....	20 A
Break dc.....	50 W Resistive, 25 W Inductive (L/R < 0.04)
Break ac	2,000 VA Resistive, 1,500 VA Inductive (PF > 0.4)

Subject to maximums of 8 A and 250 V (ac or dc)	
Contact Configuration.....	N.O and N.C. (Form C)
Operating Mode	Fail-Safe

Terminal Block Rating.....	10 A, 300 Vac, 12 AWG (2.5 mm ²)
----------------------------	---

PWB Conformal Coating.....	MIL-1-46058 qualified, UL QMJU2 recognized
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Mounting Configuration	Panel Mount and Surface Mount
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Shipping Weight	2.3 kg (5.1 lb)
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Environment:

Operating Temperature	-40°C to 60°C
Storage Temperature.....	-55°C to 80°C
Humidity	85% Non-Condensing

Surge Withstand.....	ANSI/IEEE 37.90.1-1989 (Oscillatory and Fast Transient)
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Certification	CSA Canada and USA
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To:

CSA C22.2 No. 14 Industrial Control Equipment
UL 508 Industrial Control Equipment
UL 1053 Ground Fault Sensing and Relaying
Equipment

Australia



7. WARRANTY

The SE-134C Ground-Fault Ground-Check Monitor is warranted to be free from defects in material and workmanship for a period of five years from the date of purchase.

Littelfuse Startco will (at Littelfuse Startco's option) repair, replace, or refund the original purchase price of an SE-134C that is determined by Littelfuse Startco to be defective if it is returned to the factory, freight prepaid, within the warranty period. This warranty does not apply to repairs required as a result of misuse, negligence, an accident, improper installation, tampering, or insufficient care. Littelfuse Startco does not warrant products repaired or modified by non-Littelfuse Startco personnel.

Littelfuse Startco is not liable for contingent or consequential damages; for expenses sustained as a result of incorrect application, incorrect adjustment, or a malfunction; or for expenses resulting from the use of, or inability to use, the product.

8. TEST PROCEDURES

8.1 GROUND-CHECK TRIP TESTS

8.1.1 LATCHING GROUND-CHECK TRIP TEST

- Connect the monitor, current sensor and termination assembly as shown in Fig 10. Connect terminals 14 and 15 for latching operation. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.
- Open the ground-check loop by removing either the GC or G connection between the monitor and the termination assembly. Pressing the faceplate GC TEST button will also perform an open-ground-check test. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the OPEN LED's will be on.
- Reconnect the ground-check loop. The VALID and TRIP LED's will be on and the OPEN LED will be flashing. The TRIP contacts (terminals 22-23 and 24-25) will remain latched and ground-check indication contacts (terminals 26-27 and 26-28) will change state.
- Reset the monitor.
- Short the ground-check loop by connecting G to GC. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the SHORT LED's will be on.
- Remove the short from G to GC. The VALID and TRIP LED's will be on and the SHORT LED will be flashing. The TRIP contacts (terminals 22-23 and 24-25) will remain latched and ground-check indication contacts (terminals 26-27 and 26-28) will change state.
- Reset the monitor.

8.1.2 NON-LATCHING GROUND-CHECK TRIP TEST

- Connect the monitor, current sensor and termination device as shown in Fig. 10. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.
- Open the ground-check loop by removing either the GC or G connection between the monitor and the termination assembly. Pressing the faceplate GC Test button will also perform an open circuit test. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the OPEN LED's will be on.
- Reconnect the ground-check loop. The monitor will reset.
- Short the ground-check loop by connecting G to GC. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the SHORT LED's will be on.
- Remove the short from G to GC. The monitor will reset.

8.2. TRIP RELAY FAIL-SAFE MODE TEST

- Connect the monitor, current sensor and termination device as shown in Fig. 10. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on. The output contacts between terminals 22 and 23 will be open and between 24 and 25 will be closed.
- Remove the supply voltage. The output contacts between terminals 22 and 23 will close and the output contacts between terminals 24 and 25 will open.

8.3 CURRENT-SENSOR-VERIFICATION TEST

- Connect the monitor, current sensor and termination device as shown in Fig. 10. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.
- Open the current-sensor circuit by disconnecting one of the sensor leads. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-fault indication contacts (terminals 19-20 and 19-21) will change state. The GROUND FAULT TRIP LED will be on and the SENSOR LED will be off.
- Reconnect the current sensor. The GROUND FAULT TRIP LED will stay on and the SENSOR LED will flash. The output contacts will remain latched.
- Reset the monitor.
- Short the current sensor by connecting terminals 16 and 17. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-fault indication contacts (terminals 19-20 and 19-21) will change state. The GROUND FAULT TRIP LED will be on and the SENSOR LED will be off.

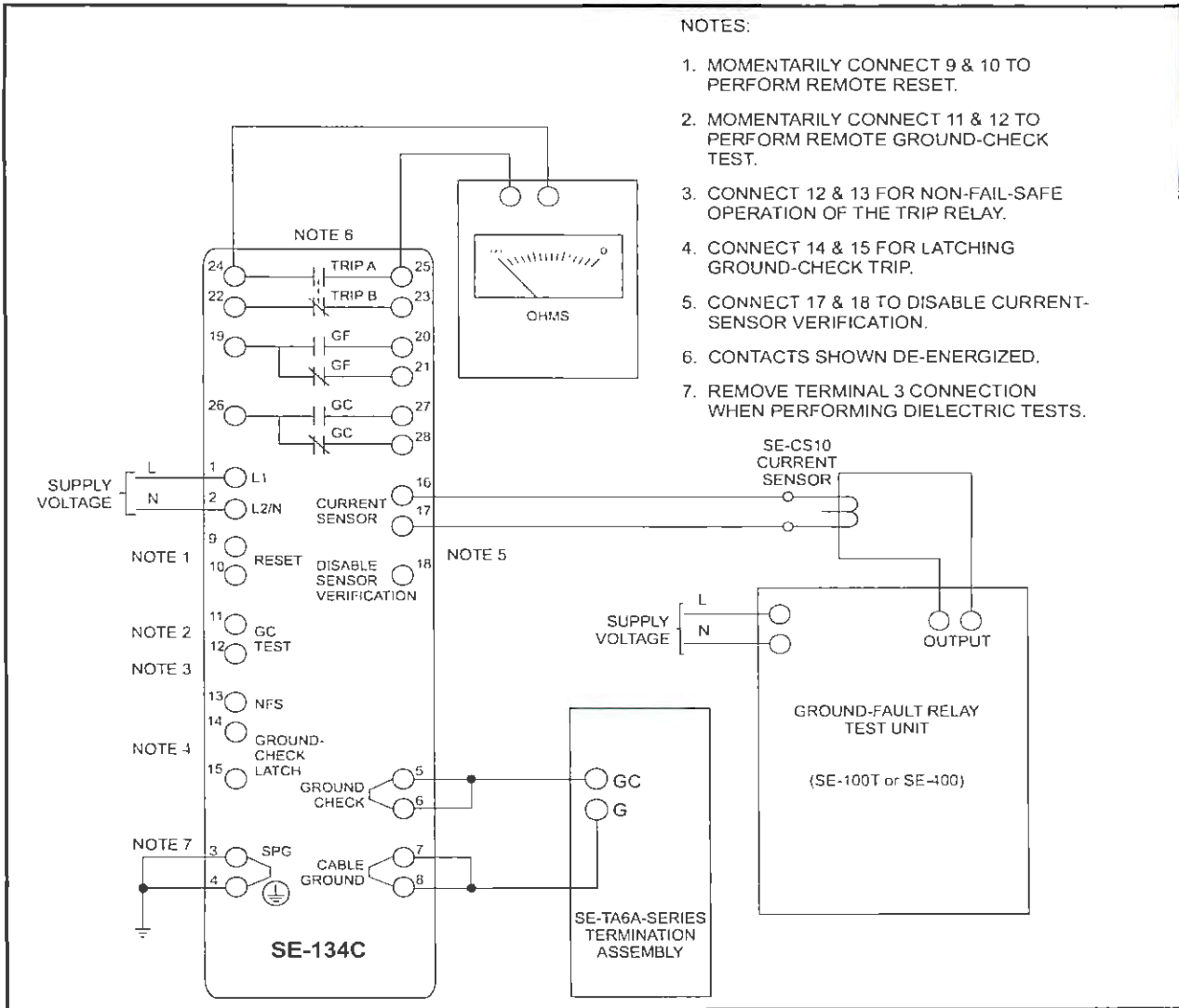


FIGURE 10. Ground-Fault-Test Circuit.

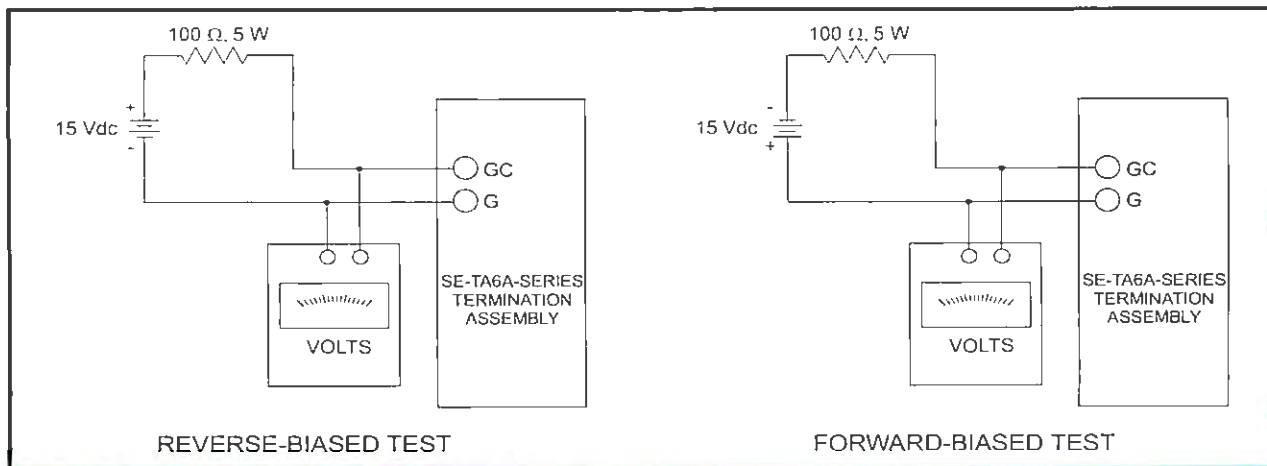
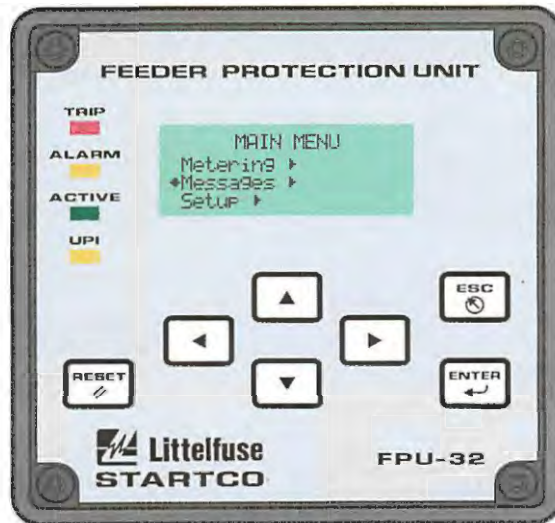


FIGURE 11. Termination-Assembly-Test Circuits.

FPU-32 MANUAL
FEEDER PROTECTION UNIT

May 13, 2010

Revision 1



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Factory default password is 1111

New Password

See Section 4.5

Feeder Identification

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DISCLAIMER

Specifications are subject to change without notice. Littelfuse Startco is not liable for contingent or consequential damages, or for expenses sustained as a result of incorrect application, incorrect adjustment, or a malfunction.

This product has a variety of applications. Those responsible for its application must take the necessary steps to assure that each installation meets all performance and safety requirements including any applicable laws, regulations, codes, and standards.

Information provided by Littelfuse Startco is for purposes of example only. Littelfuse Startco does not assume responsibility for liability for use based upon the examples shown.

1. INTRODUCTION

1.1 GENERAL

The FPU-32 is a feeder protection relay that provides integrated protection, metering, and data-logging functions. The FPU-32 can be programmed using the front-panel operator interface, the TIA-232 port, or an optional communications network.

1.2 FPU-32 FEATURES

1.2.1 PROTECTION

- Overload (49, 51)
- Definite-time overcurrent (50, 51)
- Inverse-time overcurrent (50, 51, IEC and IEEE)
- Definite-time earth fault (50G/N, 51G/N)
- Inverse-time earth fault (50G/N, 51G/N, IEC and IEEE)
- Unbalance (46)
- Phase loss (46)
- Phase reverse (46)
- PTC overtemperature (26, 49)
- RTD temperature (26, 49)
- Two set-point groups

1.2.2 METERING

- Line currents
- Current unbalance
- Positive-sequence current (I_1)
- Negative-sequence current (I_2)
- Zero-sequence current ($3I_0$, calculated)
- Earth-leakage current (CT input)
- Used thermal capacity
- Thermal trend
- RTD temperature

1.2.3 DATA LOGGING

- One-hundred records
 - Date and time of event
 - Event type
 - Cause of trip
 - Line currents
 - Current unbalance
 - Earth-leakage current
 - Used thermal capacity
 - RTD temperature
- Trip counters
- Running hours

1.2.4 INPUTS AND OUTPUTS

- Phase current inputs
- Earth-leakage-current input
- Programmable digital input (24 Vdc)
- 24-Vdc source for digital input
- 4–20-mA analog output, programmable
- Temperature-sensor input, Pt100 RTD or PTC
- I/O module interface
- Three output relays, programmable
- TIA-232 communications
- Network communications

1.2.5 OPERATOR INTERFACE

- 4 x 20 backlit LCD display
- Display-control and programming keys
- LED status indication

1.2.6 COMMUNICATIONS

The standard communications interface is a TIA-232 port using the Modbus[®] RTU protocol. In addition to the standard interface, network communications options include TIA-485 with both Modbus[®] RTU and A-B[®] DFI protocols, DeviceNet[™], and an IEEE 802.3 port with Modbus[®] TCP Ethernet protocol.

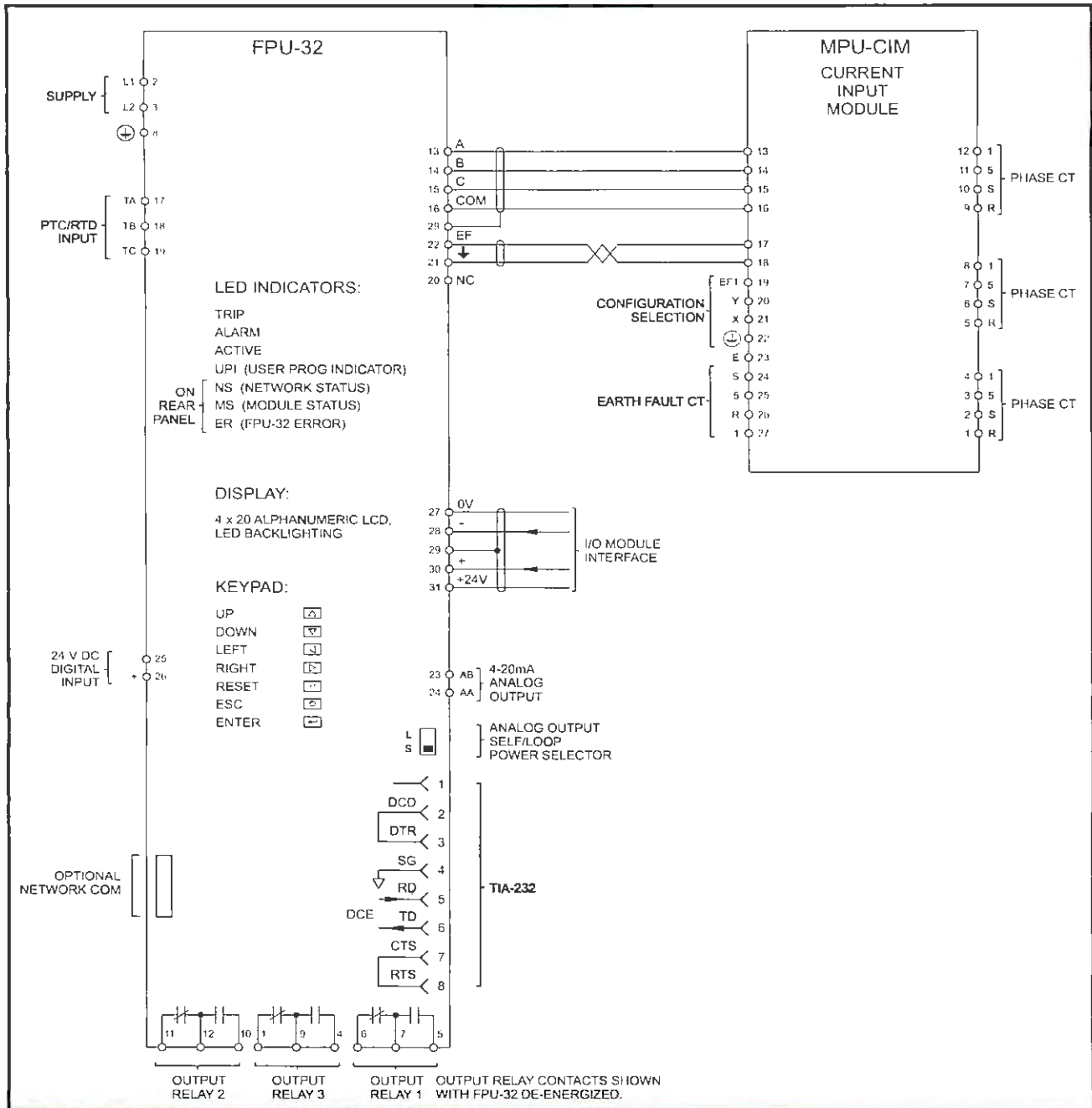


FIGURE 1.1 Feeder Protection Unit Block Diagram.

1.3 ORDERING INFORMATION

See Fig. 1.2 for FPU-32 and MPU-CIM model numbers.

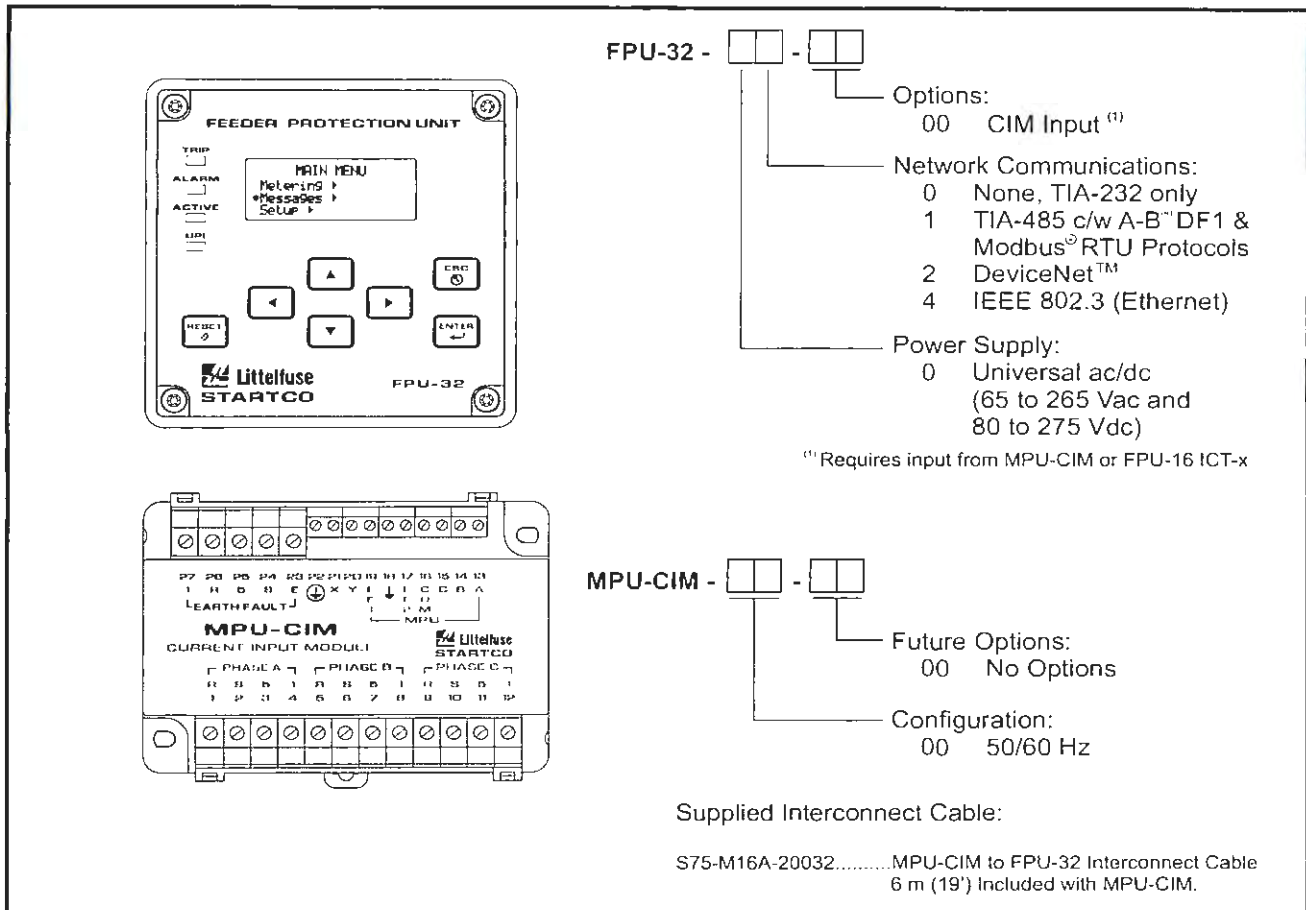


FIGURE 1.2 FPU-32 Ordering Information.

Current Transformers:

- EFCT-1 Sensitive Earth-Fault CT, 5-A-primary rating, 82-mm (3.2") window
- EFCT-1FC Flux Conditioner for EFCT-1, 70-mm (2.7") window
- EFCT-2 Sensitive Earth-Fault CT with Flux Conditioner, 5-A-primary rating, 139-mm (5.5") window
- EFCT-26 Sensitive Earth-Fault CT, 5-A-primary rating, 26-mm (1") window
- Other Earth-Fault CT's... Contact factory
- Phase CT's..... Contact factory

Accessories:

- MPU-32-SMK Surface-mounting hardware kit
- MPU-16A-Y92A-96N .. Watertight faceplate cover
- CA-945 DB9 to RJ-45 Adaptor with 1.5 m (5') cable
- SE-ICUSB232..... USB to TIA-232 serial converter

Software:

- SE-Comm-RIS..... PC Interface ⁽¹⁾
- SE-Flash..... Firmware Upgrade ⁽¹⁾

⁽¹⁾ Available at www.startco.ca.

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2. INSTALLATION

2.1 GENERAL

A basic system consists of an FPU-32, an MPU-CIM, and three 1-A- or 5-A-secondary line-current transformers. Earth-fault protection can be provided from a core-balance CT or from phase CT's. A core-balance CT (1-A, 5-A, or EFCT series) is recommended. A single PTC/RTD input is provided on the FPU-32.

The FPU-32 switch-mode power supply is rated 65 to 265 Vac and 80 to 275 Vdc.

All modules can be mounted in any orientation.

2.2 FPU-32 FEEDER PROTECTION UNIT

Outline and details for FPU-32 panel-mounting are shown in Fig. 2.1. The FPU-32 mounts in a 92-mm (3.62"), ¼ DIN, square cutout and is secured by a panel-mount clamp. Insert the FPU-32 through the panel cutout and slip the panel-mount clamp over the FPU-32 body. Slide the clamp forward until the latch tabs snap into the mating holes. Lock the unit in place by tightening the four clamp screws against the panel.

CAUTION:

Do not over tighten the clamp screws as this may deform the clamp and release the latch tabs.

Outline and details for FPU-32 surface-mounting are shown in Fig. 2.2. Ensure that the L/S switch is set before installing surface-mounting brackets. See Section 3.2.1.4 for switch positions. A detailed installation instruction sheet is included with the MPU-32-SMK Surface-Mounting Hardware Kit.

2.3 MPU-CIM CURRENT INPUT MODULE

The MPU-CIM can be surface or DIN-rail mounted. Outline and mounting details are shown in Fig. 2.3. To minimize CT-lead burden, an MPU-CIM can be located close to the CT's. The MPU-CIM terminates phase- and earth-fault-CT secondaries—shorting blocks are not required for MPU-CIM outputs.

2.4 SENSITIVE EARTH-FAULT CT'S

Outline and mounting details for the EFCT-1, EFCT-2, and EFCT-26 are shown in Figs. 2.4, 2.5 and 2.6.

2.5 FPU-32/FPU-16 COMPATIBILITY

The FPU-32 is hardware compatible with existing FPU-16 installations, except that it has a temperature sensor input and does not include an operations counter. An FPU-32 can replace an FPU-16 with minimal wiring changes. I/O connections to FPU-16 terminals 13 to 16 and 21 to 24 are identical to those on the FPU-32 and should be transferred to the plug-in terminal blocks supplied with the FPU-32. If a switch was connected to the FPU-16 program-enable terminal 21 and a hard-wired program enable is required, it can be implemented using digital-input terminals 25 and 26 as outlined in Section 4.2.6. A hard-wired program enable is often not required since the FPU-32 set points are password protected. If the FPU-16 analog output was used, ensure that the FPU-32 analog output switch is set to the 'S' (Self Powered) position.

Although FPU-32 terminals 1 to 12 have been rearranged to provide a third relay output (terminals 1, 4, and 9), the FPU-16 lower terminal block can be safely plugged into the equivalent FPU-32 terminal locations.

CAUTION:

The keying plug installed in position 9 of the FPU-16 lower terminal block must be removed before the terminal block can be plugged into an FPU-32. Use a dental pick, awl, or similar pointed tool to remove the keying plug. If the keying plug is difficult to remove, use the terminal blocks supplied with the FPU-32.

A TERMINAL BLOCK WITH A KEYING PLUG WILL DAMAGE THE FPU-32.

If the FPU-32 does not power up, ensure that L1 is connected to terminal 2 (not terminal 1) and L2/N is connected to terminal 3 (not terminal 4). If the duplicate L1 and L2 terminals on the FPU-16 are used to power another device, disconnect the outgoing L1 and L2 leads and power the next device directly from the power source. This change is in compliance with current codes that do not permit daisy chaining power connections at plug-in terminals. FPU-32 default relay assignment is the same as the FPU-16 trip- and alarm-relay configuration.

For additional information see www.startco.ca and refer to Technical Note FP-02 Replacing an FPU-16 with an FPU-32.

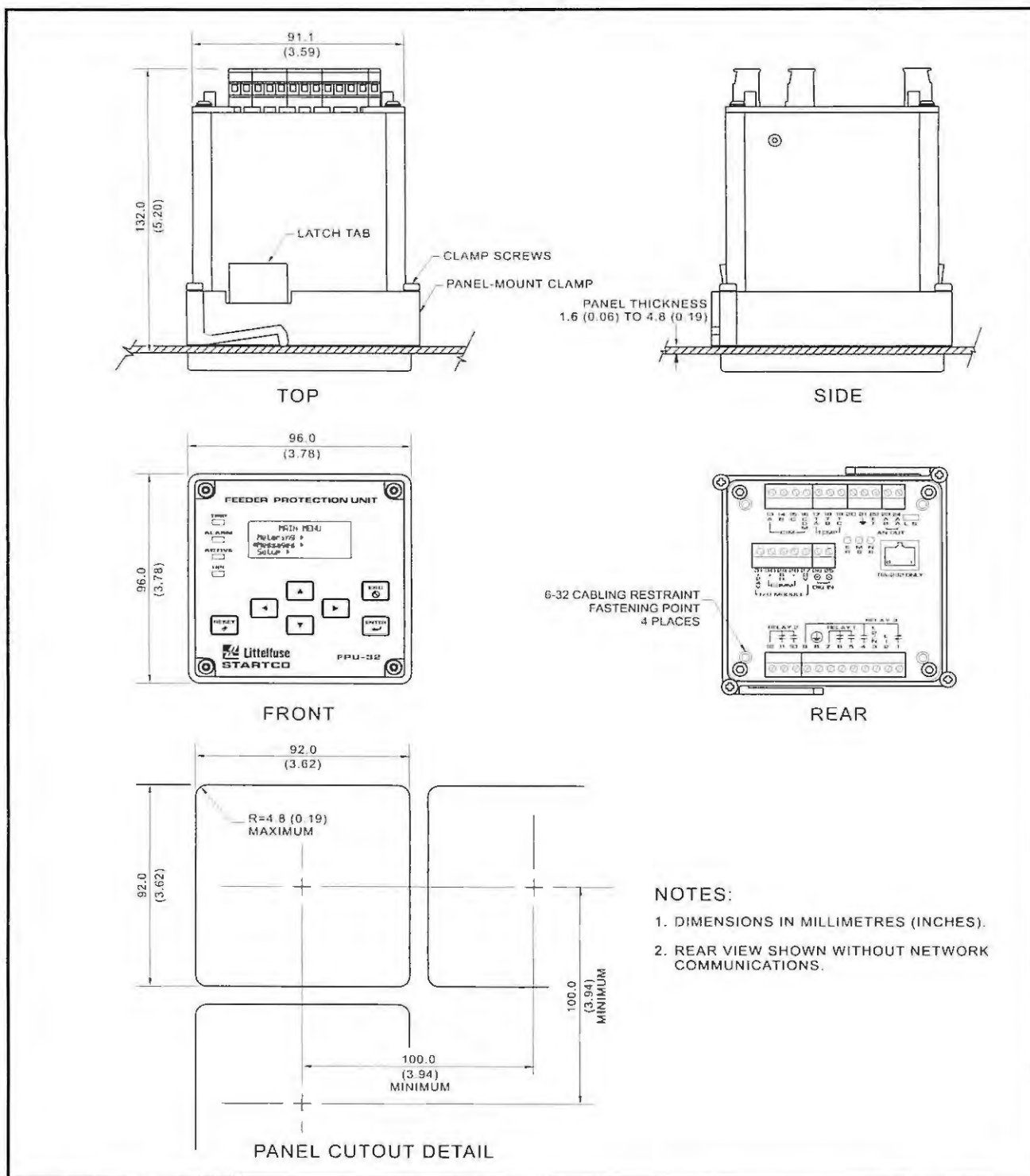


FIGURE 2.1 FPU-32 Outline and Panel-Mounting Details.

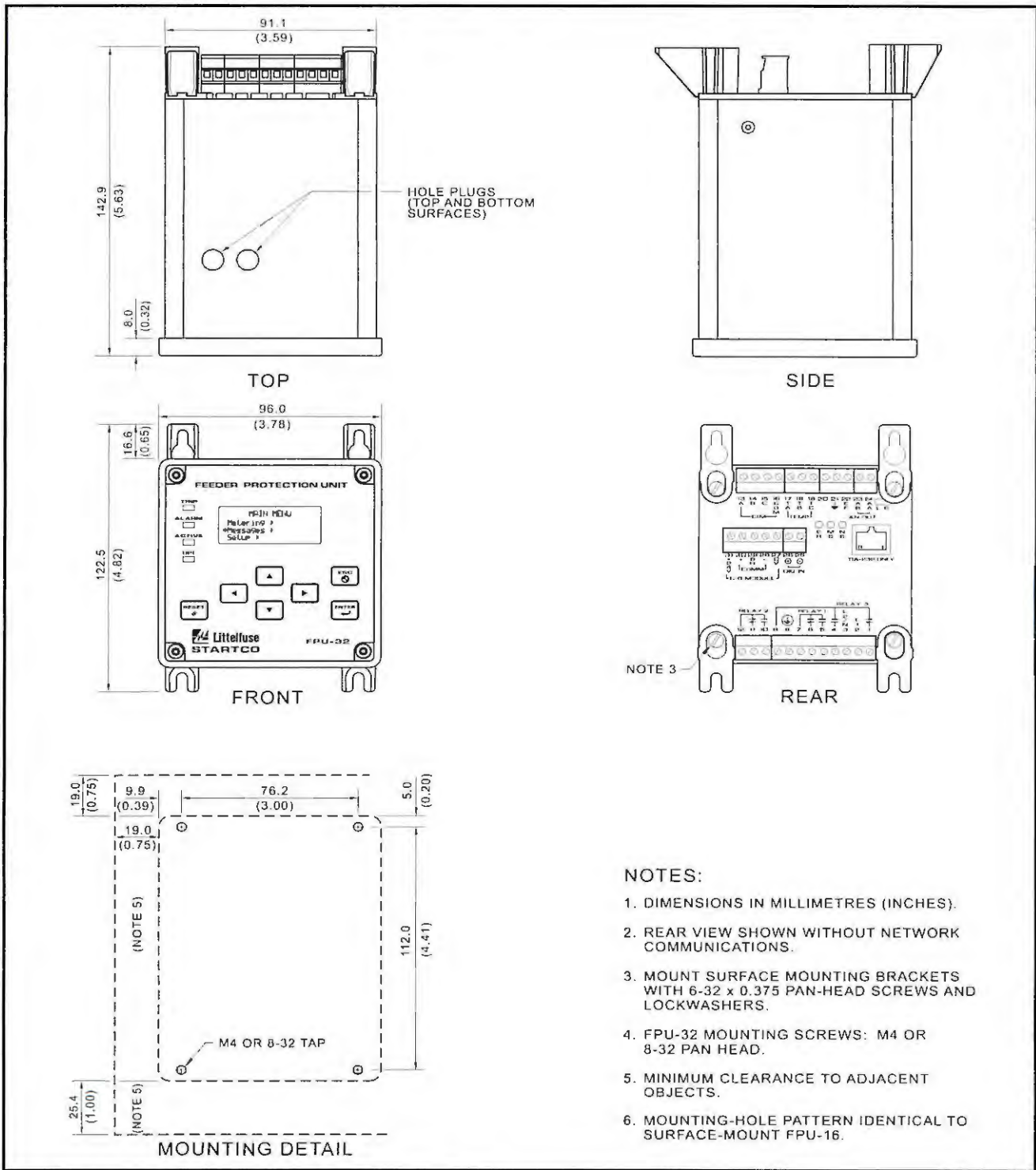


FIGURE 2.2 FPU-32 Outline and Surface-Mounting Details.

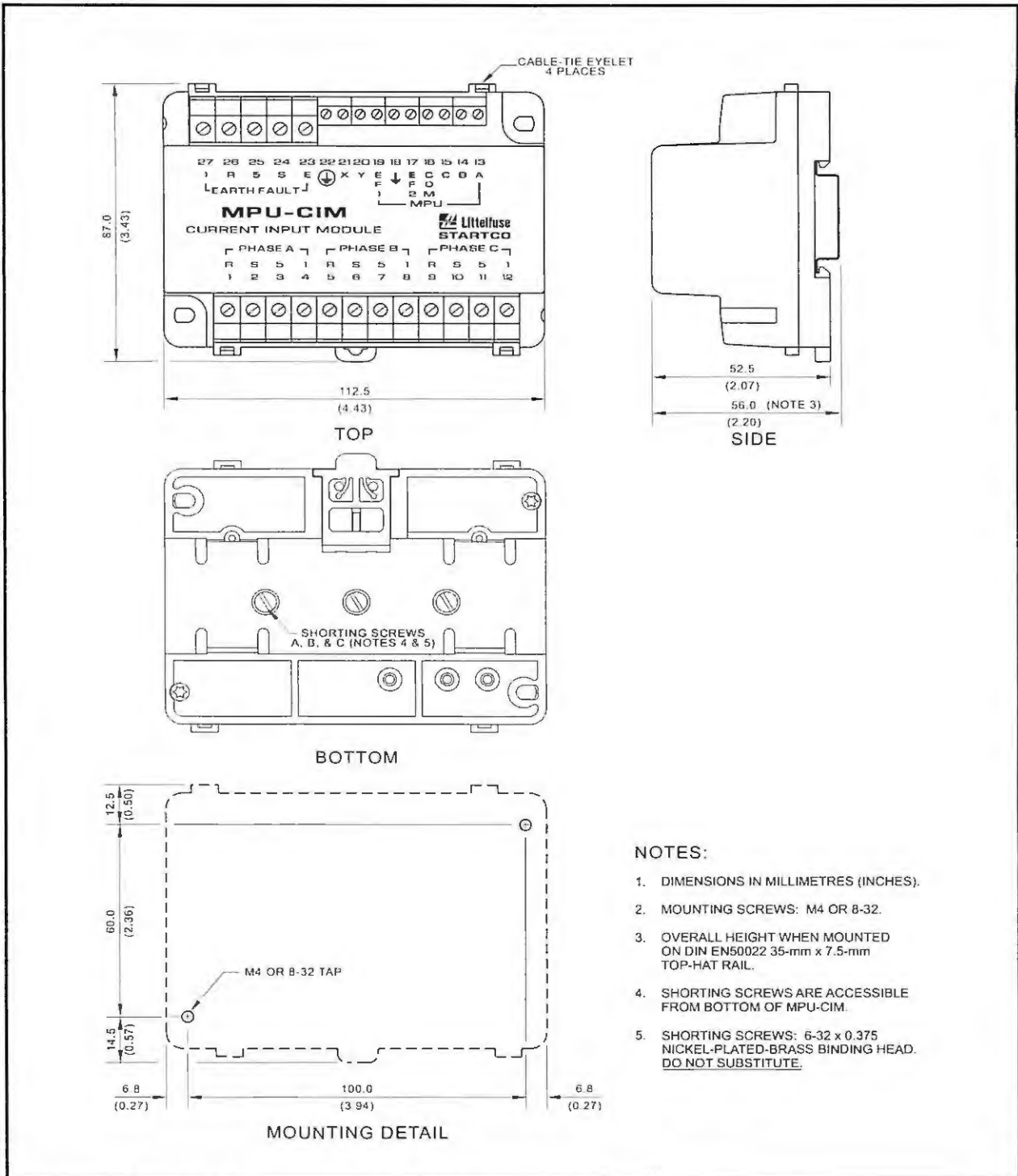


FIGURE 2.3 MPU-CIM Outline and Mounting Details.

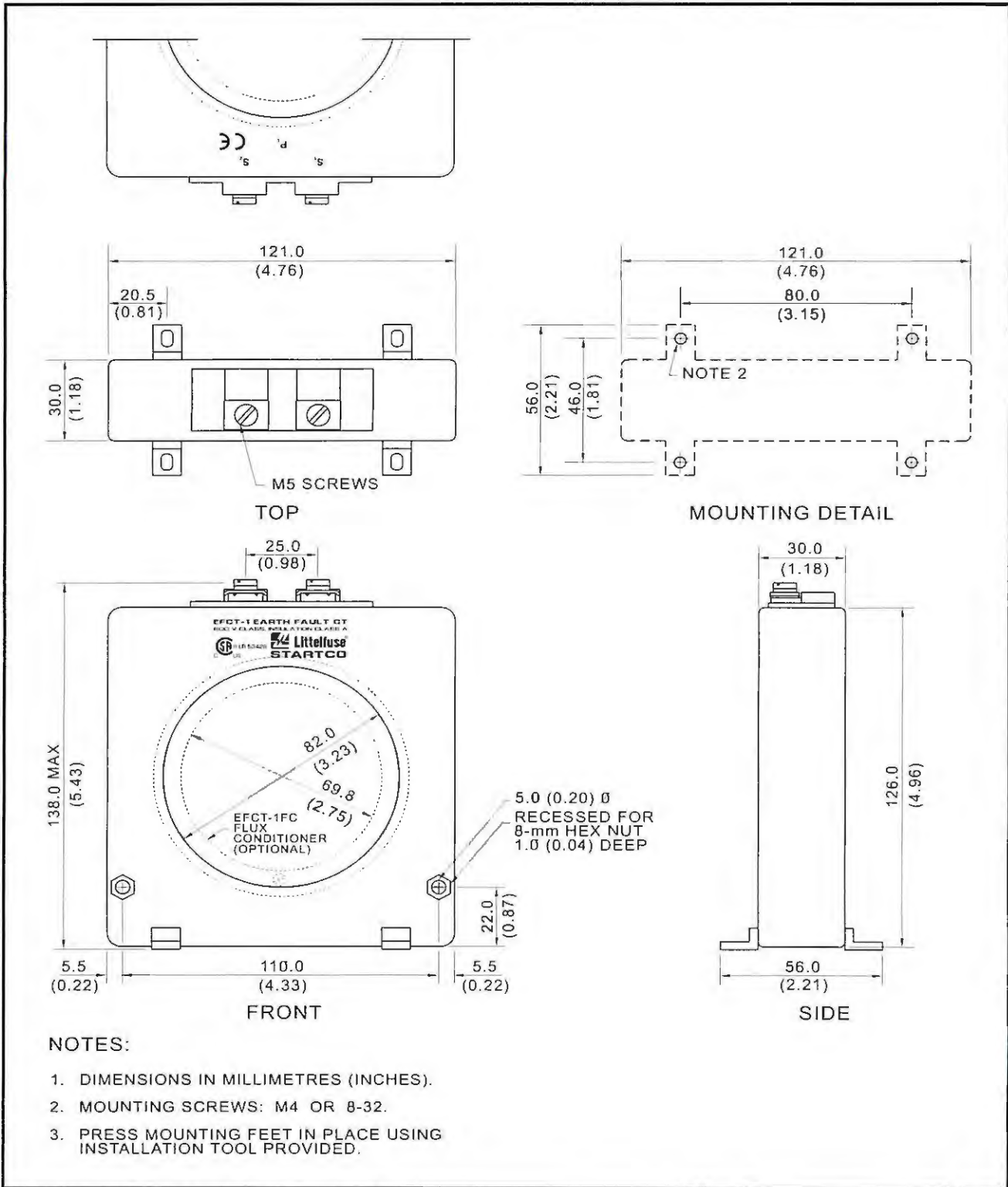


FIGURE 2.4 EFCT-1 Outline and Mounting Details.

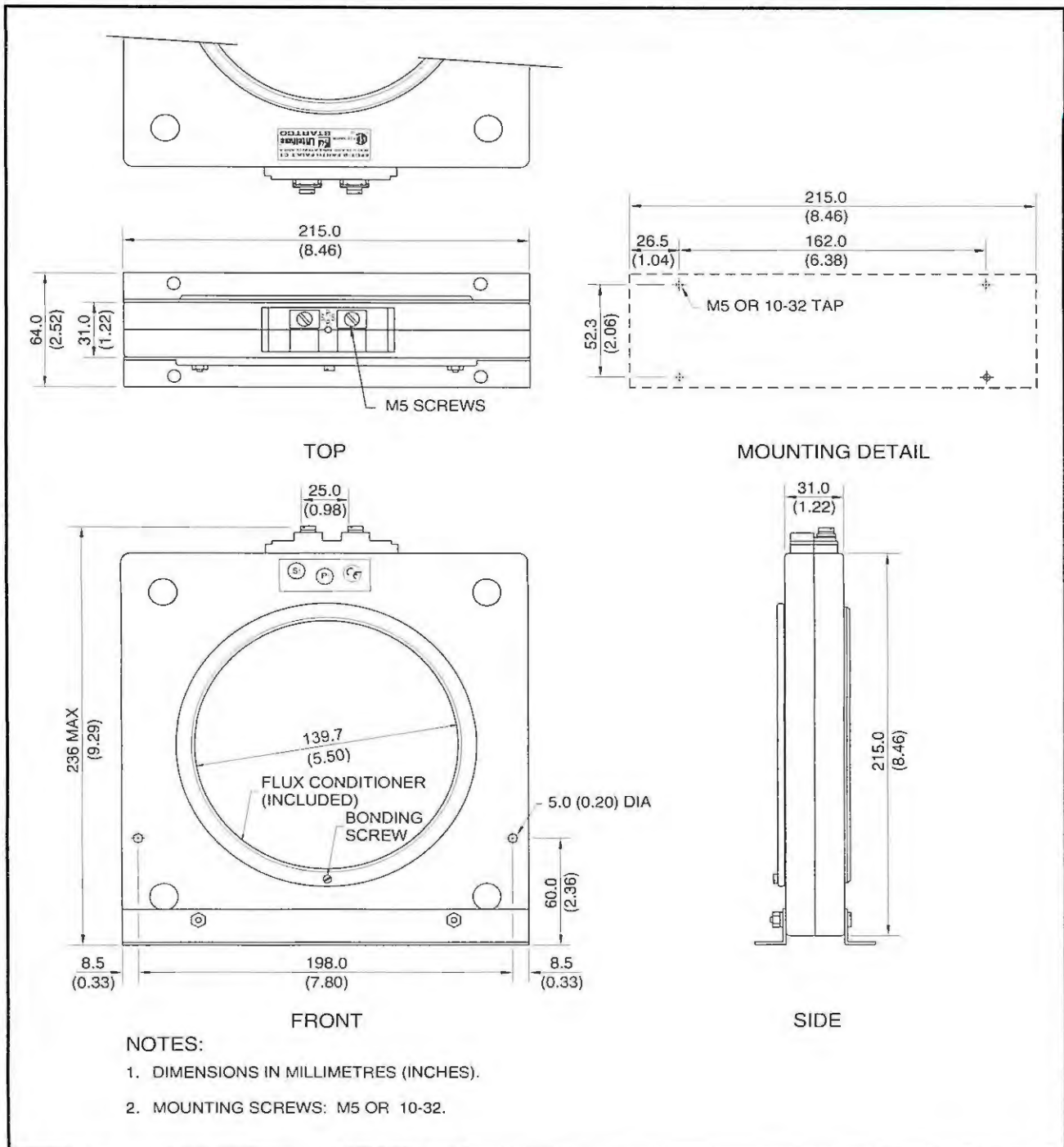


FIGURE 2.5 EFCT-2 Outline and Mounting Details.

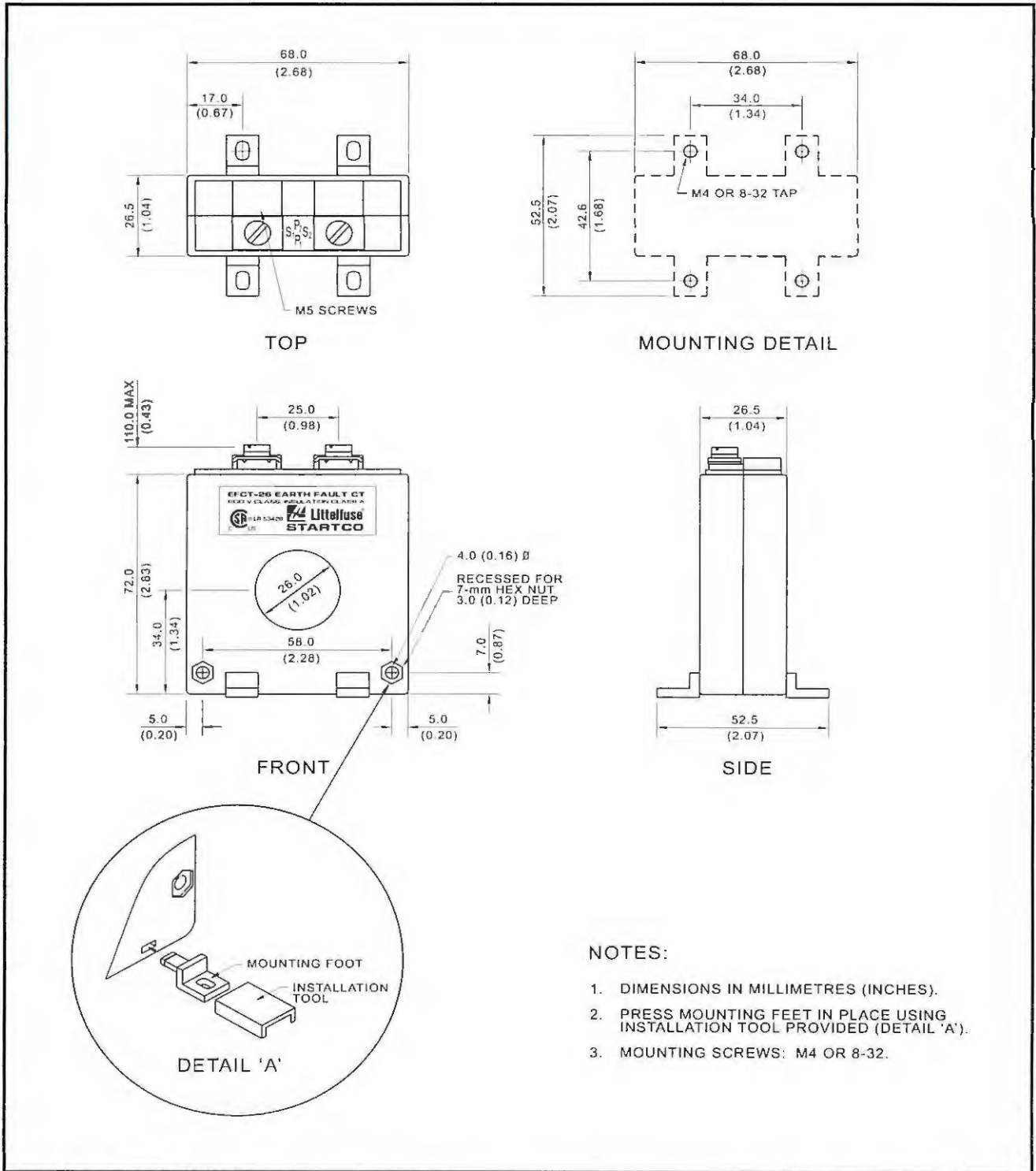


FIGURE 2.6 EFCT-26 Outline and Mounting Details.

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3. SYSTEM WIRING

3.1 GENERAL

A typical connection diagram for the FPU-32 with the MPU-CIM is shown in Fig. 3.1.

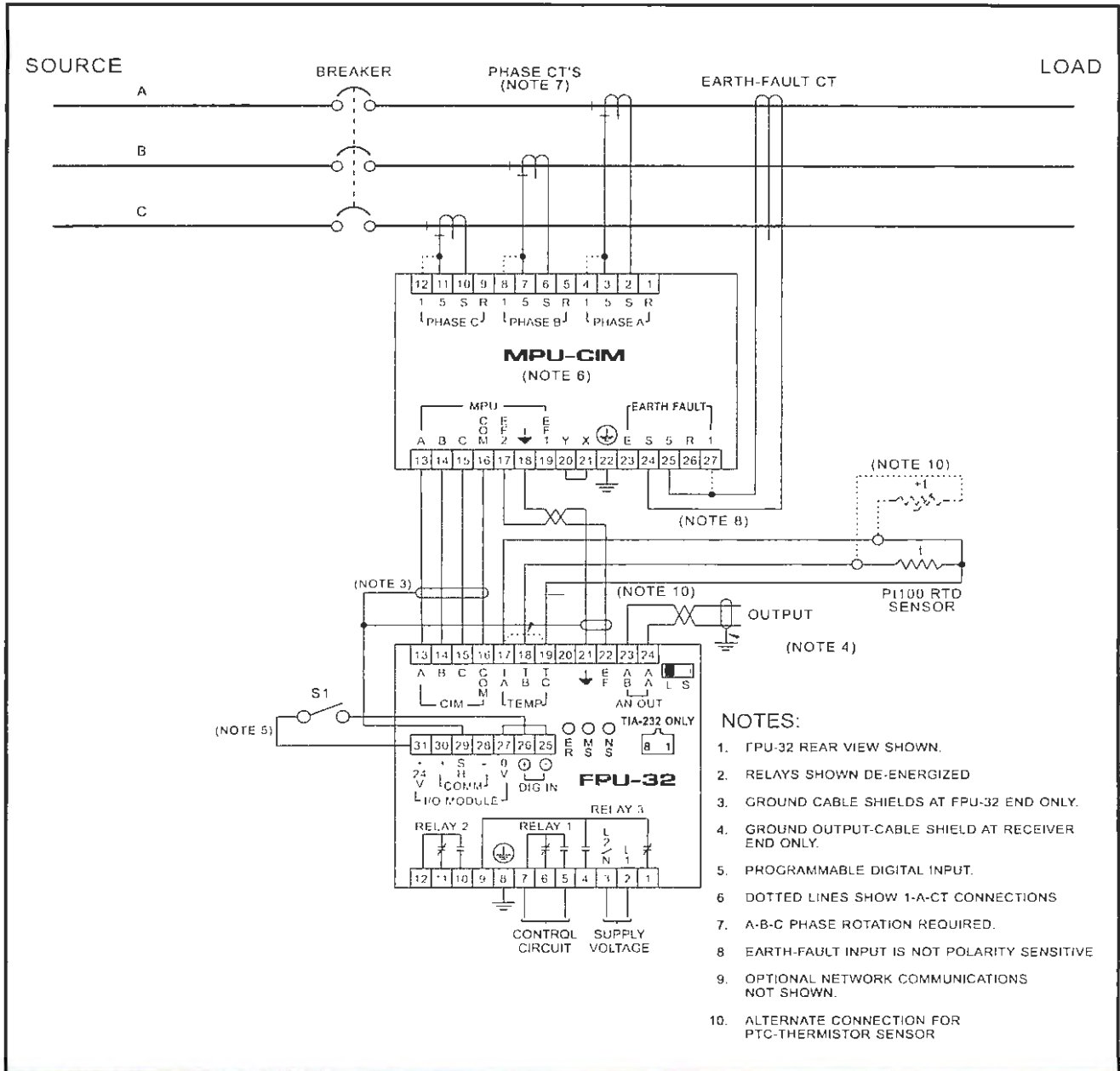


FIGURE 3.1 Typical FPU-32 Connection Diagram.

3.2 WIRING CONNECTIONS

3.2.1 FPU-32 CONNECTIONS

The FPU-32 wire-clamping terminal blocks accept 24 to 12 AWG (0.2 to 2.5 mm²) conductors. These terminal blocks unplug to allow the FPU-32 to be easily replaced.

3.2.1.1 SUPPLY VOLTAGE

Derive supply voltage from the line side of the breaker or from an independent source. Connect supply voltage to terminals 2 and 3 (L1 and L2/N) as shown in Fig. 3.1. In 120-Vac systems, L2/N is designated as the neutral conductor. For direct-current power supplies, use L1 for the positive terminal and L2/N as the negative terminal. Ground terminal 8 (⊕).

3.2.1.2 CIM INPUT

Connect the FPU-32 to the MPU-CIM as shown in Figs. 3.6 and 3.7 using the cable provided with the MPU-CIM.

3.2.1.3 DIGITAL INPUT

A 24-Vdc digital input is provided on terminals 25 and 26. This input is polarity sensitive. For a logical 1, terminal 26 must be positive with respect to terminal 25. See Section 4.2.6.

The current-limited 24-Vdc source (terminals 27 & 31) can be used for the digital input.

3.2.1.4 ANALOG OUTPUT

The analog output is switch selectable as self powered or loop powered.

For the self-powered connection, set the L/S switch to the S position. The self-powered connection is shown in Fig. 3.2 (a). The analog output is referenced to the I/O module supply, terminal 27.

For the loop-powered connection, set the L/S switch to the L position. The loop-powered connection is shown in Fig. 3.2 (b). In loop-powered operation, the analog output is isolated from all other FPU-32 terminals.

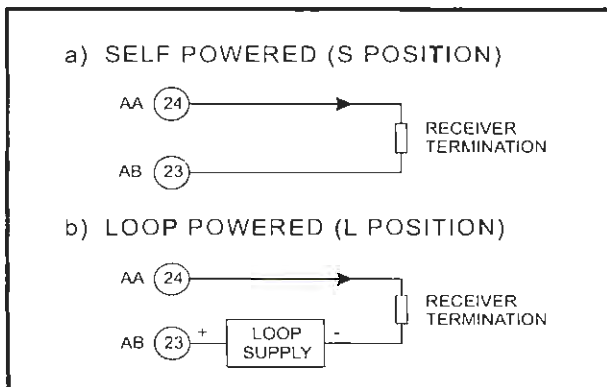


FIGURE 3.2 Analog-Output Connections.

3.2.1.5 PTC or RTD INPUT

The temperature-sensor input on the FPU-32 can be configured for either PTC or Pt100 RTD operation as shown in Fig. 3.3.

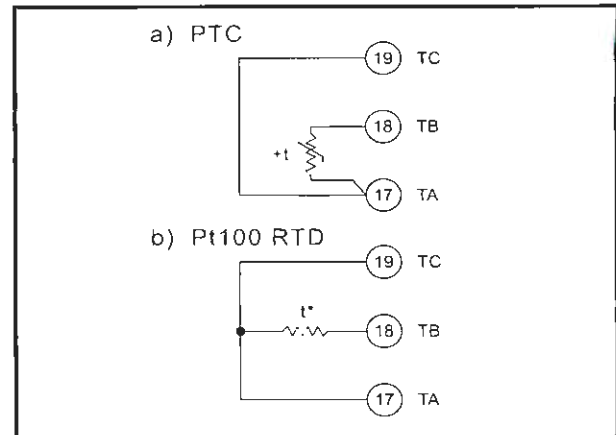


FIGURE 3.3 Temperature-Sensor Connections.

3.2.1.6 I/O MODULE COMMUNICATIONS

The I/O module communications interface is used to support optional modules.

At the publication date, no optional FPU-32 modules were available. The 24-Vdc supply can be used to power the digital input as outlined in Section 4.2.6.

I/O module communication is based on the two-wire multi-drop TIA-485 standard but uses a proprietary protocol. Overall line length must not exceed 1.2 km (4,000'). For line lengths exceeding 10 m (33'), 150-Ω terminations are required at the cable ends. See Fig. 3.4.

NOTE: I/O communication is shared with the display. Incorrect wiring can cause the display and keypad to freeze.

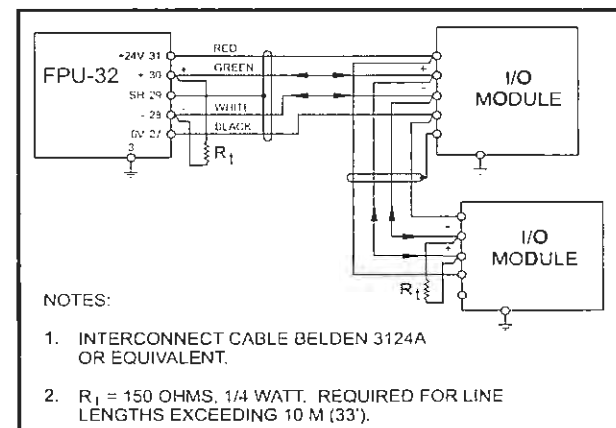


FIGURE 3.4 I/O Module Connection Diagram.

3.2.1.7 RS/EIA/TIA-232 COMMUNICATIONS

An RJ-45 TIA-232 connector is provided on the rear panel of the FPU-32. This port uses the Modbus[®] RTU protocol to communicate with SE-Comm-RIS PC-interface software. For Modbus[®] RTU protocol, see Appendix C. The slave ID and communication baud rate are set in the *Setup | Hardware | Local Comms* menu.

Table 3.1 shows the pinout for the optional CA-945 adapter for operation with SE-Comm-RIS. See Fig. 3.1 for RJ-45 pinout. For a USB connection, use a SE-ICUSB232 adapter.

TABLE 3.1 CA-945 ADAPTER

NAME	RJ-45	DB9
RI/DSR	1	9
CD	2	1
DTR	3	4
SG	4 ⁽¹⁾	5
RD	5 ⁽¹⁾	2
TD	6 ⁽¹⁾	3
CTS	7	8
RTS	8	7

⁽¹⁾ Minimum requirement for communications.

3.2.2 MPU-CIM CONNECTIONS

The MPU-CIM CT-input terminal blocks accept 22 to 10 AWG (0.3 to 4.0 mm²) conductors. The remaining MPU-CIM clamping blocks accept 24 to 12 AWG (0.2 to 2.5mm²) conductors.

The MPU-CIM contains four signal-conditioning interface transformers which are interconnected as shown in Fig. 3.5. These transformers isolate the FPU-32 from the phase and earth-fault CT's. The MPU-CIM eliminates the need for CT shorting contacts when the FPU-32 is disconnected. Phase-CT and earth-fault-CT secondaries can be simultaneously grounded through terminal 22 and a jumper to terminal 20. For applications where the CT secondaries must be grounded at another location, the CT secondaries can be isolated by removing shorting screws A, B, and C through holes in the bottom of the MPU-CIM. See Figs. 2.3 and 3.5.

NOTE: A-B-C phase sequence and polarity must be observed when connecting phase CT's. See Section 4.2.1.

Connect the MPU-CIM to the FPU-32 as shown in Figs. 3.6 and 3.7 using the cable provided with the MPU-CIM.

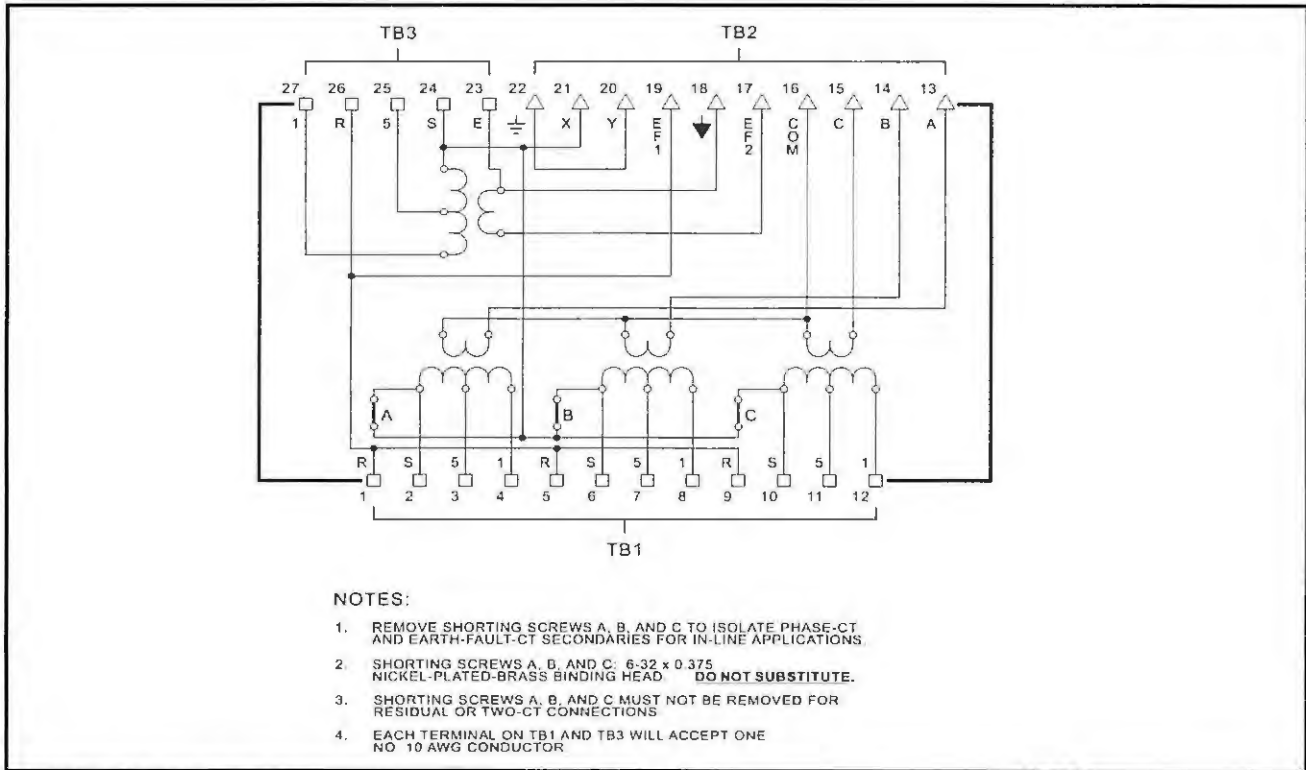


FIGURE 3.5 MPU-CIM Schematic.

3.2.2.1 STANDARD

Standard connections with earth-fault CT's are shown in Fig. 3.6. Dotted lines indicate 1-A-CT connections. Use shielded cable for EFCT-1 or EFCT-2 connections. Ensure only current-carrying phase conductors pass through the earth-fault-CT window and that ground conductors do not.

3.2.2.2 RESIDUAL EARTH-FAULT

The residual earth-fault connection is shown in Fig. 3.7 (a). Dotted lines indicate 1-A-CT connections. Use three identical CT's for this connection.

This connection is a legacy from FPU-16 applications. The FPU-32 calculates residual current. See Section 4.2.2.

3.2.2.3 Two-CT

The two-CT connection is shown in Figs. 3.7 (b) and 3.7 (c). Dotted lines indicate 1-A-CT connections. Since this connection derives the current in the unmonitored phase, this connection should be used only in retrofit applications where it is not possible to install a third CT.

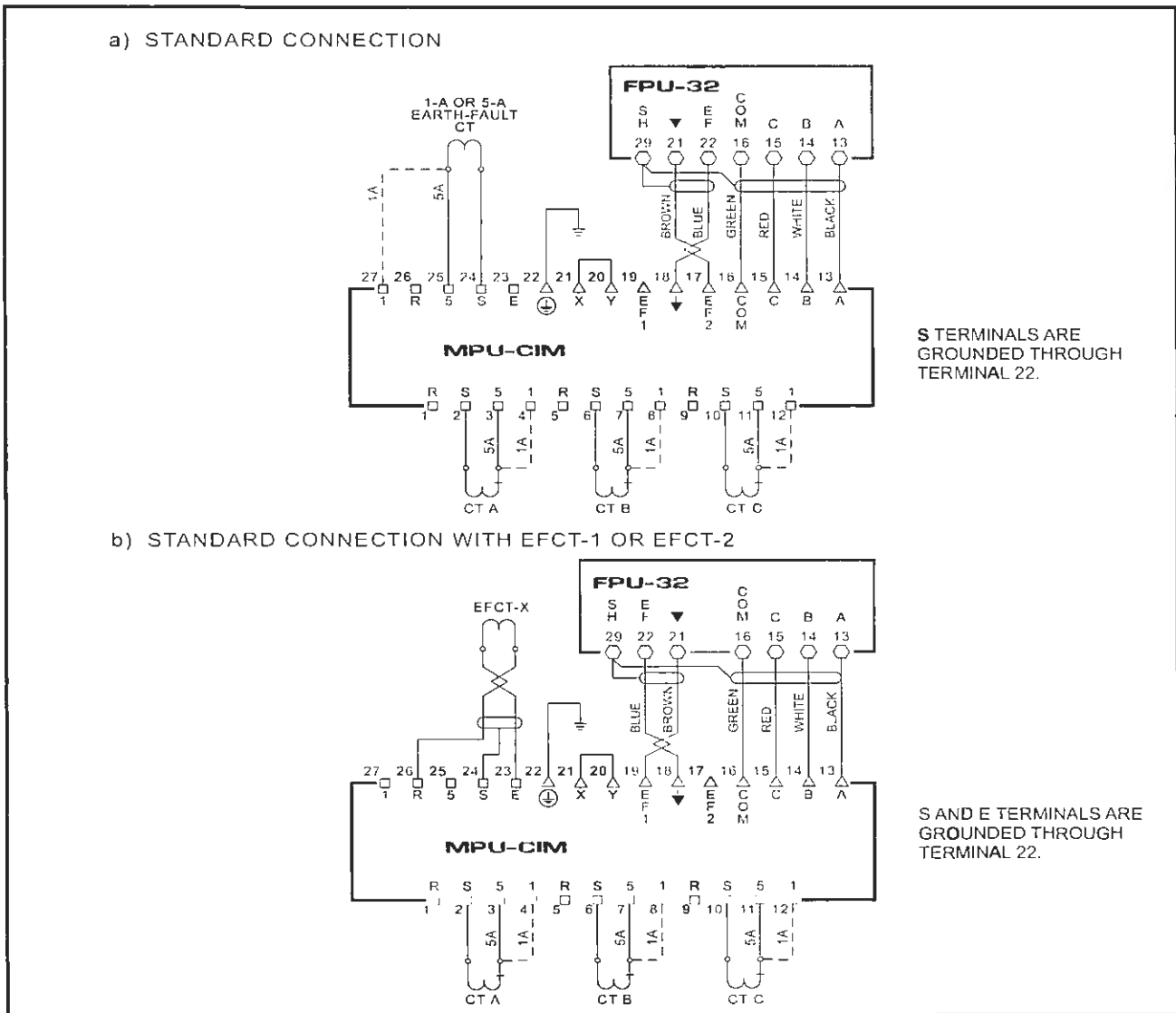


FIGURE 3.6 MPU-CIM Standard Connections.

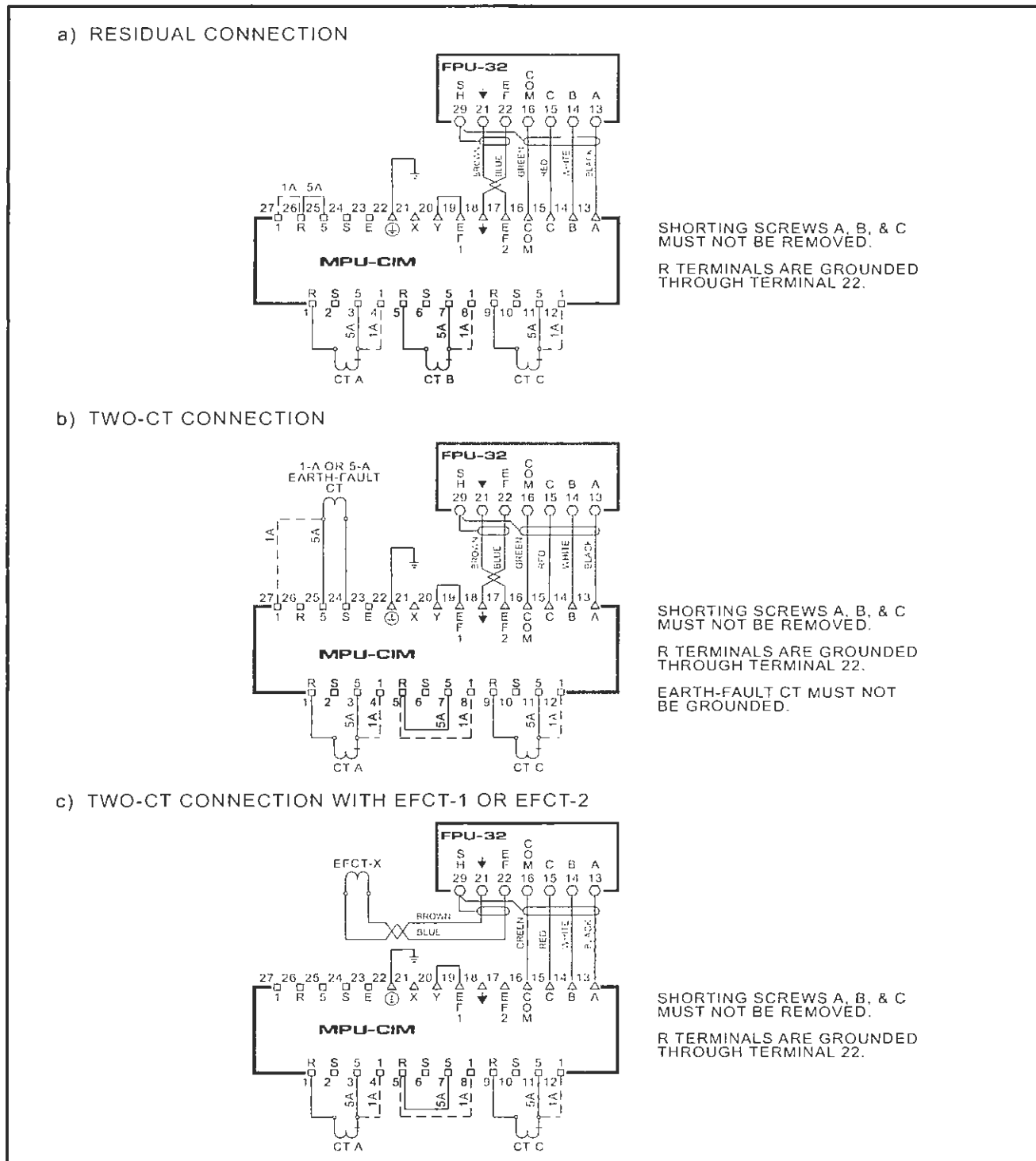


FIGURE 3.7 Other MPU-CIM Connections.

3.2.3 CABLE RESTRAINT

All conductors should be restrained within 100 mm (4") of the terminal blocks. Four cabling-restraint points are provided on the FPU-32 rear panel. Secure cables to the MPU-CIM using the cable-tie eyelets and the cable ties provided. See Figs. 2.1 and 2.3.

3.2.4 DIELECTRIC-STRENGTH TESTING

Dielectric-strength testing can be performed only on CT inputs, supply voltage input, and output relays. Unplug all other I/O and remove the MPU-CIM Ⓢ connection (terminal 22) during dielectric-strength testing.

4. OPERATION AND SETUP

4.1 DISPLAY AND INDICATION

All FPU-32 information displays and settings can be accessed using the FPU-32 menu system, the TIA-232 interface, or a network-communications interface.

In the following sections, menu items and setup parameters are listed in italics and are shown in the format displayed on the alphanumeric LCD. The LCD cannot display subscripts and superscripts.

Menu selection is in the following format:

Menu 1 | Sub Menu 1 | Sub Menu 2 | Sub Menu 3 | ...

Example: For the menu item shown in Fig. 4.1, the notation is *Setup | System Ratings | CT Primary*

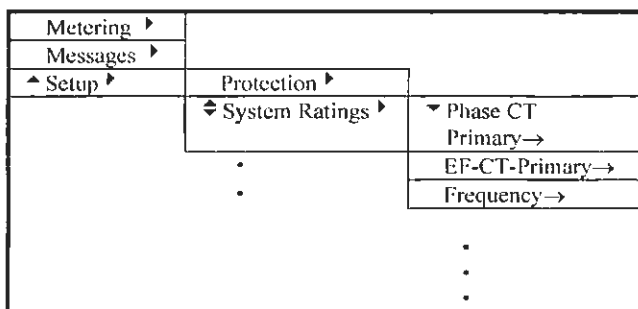


FIGURE 4.1 Menu Example.

Fig. 4.2 shows the symbols that assist in navigating the menu system and how these symbols relate to the arrow keys on the FPU-32. See the FPU-32 menu map in Appendix A.

4.1.1 FRONT-PANEL LED INDICATION

Menu: *Setup | System Config | UPI LED*

The red TRIP and yellow ALARM LED's indicate a trip or alarm condition. The green ACTIVE LED is OFF when current is not detected and is ON when current is detected. The yellow UPI LED is a user-programmable indicator and its function is defined by one of the menu selections shown in Table 4.1.

TABLE 4.1 UPI LED FUNCTIONS

SELECTION	LED ON CONDITION
None	LED remains off.
Trip1	Trip 1 condition exists.
Trip2	Trip 2 condition exists.
Trip3	Trip 3 condition exists.
Alarm1	Alarm 1 condition exists.
Alarm2	Alarm 2 condition exists.
Alarm3	Alarm 3 condition exists.
Relay1	Relay 1 is energized.
Relay2	Relay 2 is energized.
Relay3	Relay 3 is energized.
Digital Input	Digital input is valid.
Current Detected	Current is above 2% CT-primary rating.
3I _n Pickup	3I _n current exceeds inverse curve pickup value.
Phase Pickup	Phase current exceeds inverse curve pickup value.
ETR	FPU-32 is in Emergency Thermal Reset state.
Network Run I	Run 1 is issued by a network command.
Net Activity	Activity is detected on the communications interface.

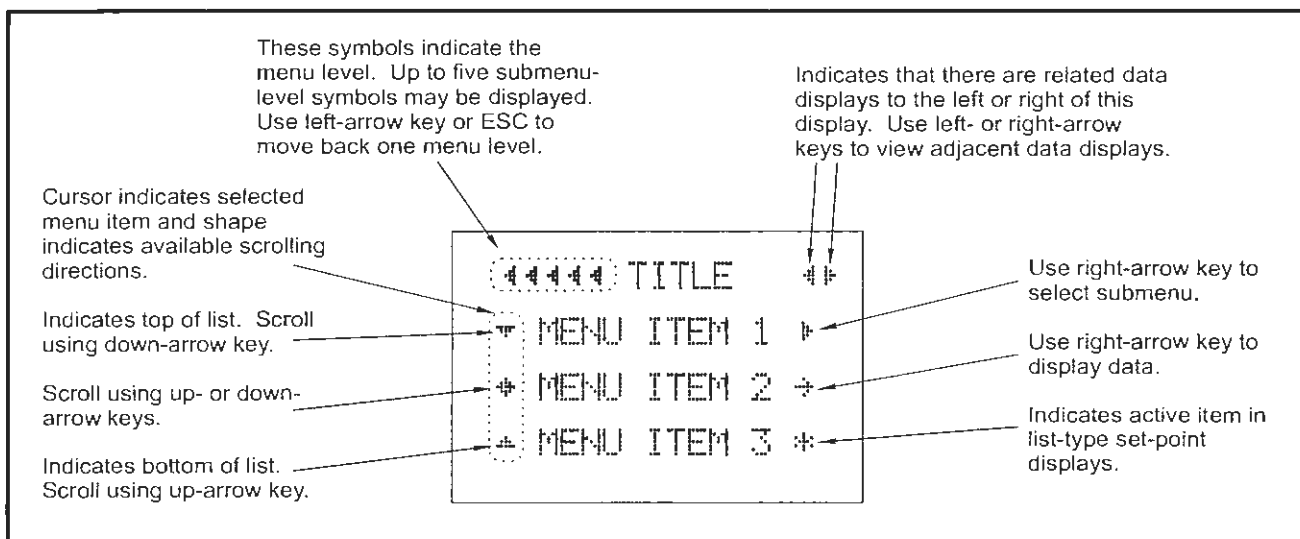


FIGURE 4.2 Menu Symbols.

4.1.2 REAR-PANEL LED INDICATION

The three LED's on the rear panel are labeled ER, MS, and NS. The red ER (Error) LED is OFF during normal operation and is ON when there is a processor error or during firmware-update operation. Output relays are de-energized when this LED is ON. The MS (Module Status) and NS (Network Status) LED's are used for network-communications and firmware-update annunciation. The specific colour and function of these LED's is defined by the network-communications option installed in the FPU-32. For detailed information, see the applicable communications manual.

4.1.3 DISPLAY CONTRAST

Contrast control and operator-interface test features are available when the display is in Local mode. To prevent a *Display Comm Trip*, select *Disabled* in the *Setup | Hardware | OPI Display | Trip Action* menu. To enter Local mode, press the up-arrow, right-arrow, and ENTER keys simultaneously.

In Local mode, all face-plate LED's are ON and the display indicates three menu items; *Contrast*, *Address*, and *Enter Test Mode*. Use the up- and down-arrow keys to select the menu item.

Contrast: Use the right- and left-arrow keys to increase or decrease contrast.

Address: The display address indicates 1 and cannot be changed.

Enter Test Mode: Press the right-arrow key to enter test mode. In test mode, the LED test, Display test, and Display-Heater test are automatically performed. The Interactive-Key test is then entered and the following symbols are displayed when a key is pressed.

Left Key:	←
Right Key:	→
Up Key:	↑
Down Key:	↓
ESC:	^
ENTER:	↵
RESET:	Press RESET to exit this menu.

Press the ESC key to exit Local mode and return to the FPU-32 menu. Re-enable *OPI Display Trip Action*.

4.2 SETUP

Certain FPU-32 settings cannot be changed when current is detected. See Appendix B.

4.2.1 PHASE-CT INPUTS

Menu: *Setup | System Ratings | CT Primary*

The CT-primary setting range is 1 to 5,000 A. To maintain specified accuracy, phase CT's should be selected with a primary rating between 100 and 300% of rated current.

For A-B-C sequence, the +Seq I_1 display value is larger than the -Seq I_2 display value and positive current unbalance is indicated. Negative current unbalance will be indicated if the phase sequence is B-A-C. If negative unbalance is indicated, correct the phase-CT

connections. Severe current unbalance may be indicated when phase-CT polarity is incorrect.

4.2.2 EARTH-FAULT-CT INPUT

Menu: *Setup | System Ratings | EF-CT Primary*

The earth-fault-CT-primary setting range is 1 to 5,000 A. The EF-CT-primary rating is 5 A for sensitive CT's--EFCT-1 and EFCT-2. *EF-CT Primary* should be set equal to *CT Primary* for residual CT connections. The protection setting range for the EF-CT connection is equal to the EF-CT-primary rating.

The FPU-32 also supports earth-fault protection based on the calculated zero-sequence component ($3I_0$). The protection setting range for the $3I_0$ connection is fifteen times the phase-CT-primary rating.

NOTE: Calculated $3I_0$ does not detect CT saturation. Enable overcurrent protection when earth-fault current can exceed 15 times the phase-CT-primary rating.

4.2.3 FREQUENCY

Menu: *Setup | System Ratings | Frequency*

Set *Frequency* at 50 or 60 Hz.

4.2.4 SET-POINT GROUP

Menu: *Setup | System Ratings | Set-Point Group*

The FPU-32 supports two set-point groups. The *Setup | System Ratings | Set-Point Group* menu specifies the active set-point group as Group1 or Group2. If the digital input is used to select the set-point group, it has priority over the menu setting.

4.2.5 OUTPUT RELAY ASSIGNMENT

Menu: *Setup | Relay Outputs | Relay x*

Menu: *Setup | Relay Outputs | RY Pulse Time*

Each of the three output relays can be assigned to one of the functions listed in Table 4.2. More than one relay can be assigned the same function. Trip and alarm assignments operate in the selected fail-safe or non-fail-safe mode.

The default assignment for Relay 1 is Trip1, for Relay 2 is Alarm1, and for Relay 3 is None. This assignment is compatible with the FPU-16 Feeder Protection Unit. The default mode setting for all three relays is Fail-Safe.

TABLE 4.2 OUTPUT-RELAY FUNCTIONS

FUNCTION	ASSIGNMENT OR ACTION
Trip1	Relay operates when a trip occurs in a protective function assigned Trip1, Trip1&2, Trip1&3, or Trip1,2&3 trip action. Fail-safe or non-fail-safe mode selection is active.
Trip2	Relay operates when a trip occurs in a protective function assigned Trip2, Trip1&2, Trip2&3, or Trip1,2&3 trip action. Fail-safe or non-fail-safe mode selection is active.
Trip3	Relay operates when a trip occurs in a protective function assigned Trip3, Trip1&3, Trip2&3, or Trip1,2&3 trip action. Fail-safe or non-fail-safe mode selection is active.
Alarm1	Relay operates when an alarm occurs in a protective function assigned Alarm1, Alarm1&2, Alarm1&3, or Alarm1,2&3 alarm action. Fail-safe or non-fail-safe mode selection is active.
Alarm2	Relay operates when an alarm occurs in a protective function assigned Alarm2, Alarm1&2, Alarm2&3, or Alarm1,2&3 alarm action. Fail-safe or non-fail-safe mode selection is active.
Alarm3	Relay operates when an alarm occurs in a protective function assigned Alarm3, Alarm1&3, Alarm2&3, or Alarm1,2&3 alarm action. Fail-safe or non-fail-safe mode selection is active.
Current	Relay is energized when current is greater than 2% of CT-primary rating.
Trip1 Pulse ⁽¹⁾	Trip1 energizes relay for the time duration specified by the <i>RY Pulse Time</i> set point.
Network Run1	Relay is energized by a network "Run1 Set" command and de-energized by a "Run1 Clear" command.
Watchdog	Relay is energized when the FPU-32 is operating properly.
None	No assignment.

⁽¹⁾ Assign this function to only one relay. Non-fail-safe operation only.

4.2.6 DIGITAL INPUT

Menu: *Setup | Digital Input | DIN1 Function*

Menu: *Setup | Digital Input | DIN1 Trip Delay*

The digital input can be assigned to one of the functions listed in Table 4.3.

When assigned to the *Trip1* function, the *DIN1 Trip Delay* set point is enabled. A trip occurs if the digital-input voltage is removed for the time specified by the *DIN1 Trip Delay*.

When assigned to *Reset*, trips can be reset using an external reset switch. The *Reset* input is a "one-shot" reset and requires a transition from open to closed. Maintaining a reset switch closure does not inhibit trips.

When assigned to *Program Enable*, the password protection function is disabled and program access is a function of the digital-input state.

When assigned to *Set-Point Group*, one of two groups is selected. The digital-input selection has priority over the *Setup | System Ratings | Set-Point Group* setting.

TABLE 4.3 DIGITAL-INPUT FUNCTIONS

FUNCTION	STATE ⁽¹⁾
Trip1	1 = No Trip1 0 = Trip1 (Delay selectable, reset required)
Reset	1 = Reset Trips
Program Enable ⁽²⁾	1 = Program changes allowed 0 = No program changes allowed
Set-Point Group	1 = Group2 Set Points 0 = Group1 Set Points
None	No assignment (Default)

⁽¹⁾ 1 = 24-Vdc applied, 0 = 24-Vdc not applied.

⁽²⁾ Password is disabled.

4.2.7 ANALOG OUTPUT

Menu: *Setup | Analog Output*

The 20-mA analog output can be programmed for one of the parameters shown in Table 4.4.

The analog output is factory calibrated for zero equals 4.0 mA and full scale equals 20.0 mA.

If adjustment is required use the *Analog Output* menus.

Zero Calibration:

- Select *Zero* in the *Output Parameter* menu.
- Measure the output current and adjust the *Zero Calibrate* setting for the desired output. The calibration number for 4 mA will be in the range of 100 to 110.

Full-Scale Calibration:

- Select *Full Scale* in the *Output Parameter* menu.
- Measure the output current and adjust the *FS Calibrate* setting for the desired output. The calibration number for 20 mA will be in the range of 540 to 550.

Calibration numbers are not changed when factory defaults are loaded or during a firmware update.

TABLE 4.4 ANALOG-OUTPUT PARAMETERS

PARAMETER	DESCRIPTION	FULL SCALE
Phase Current	Maximum of the three phase currents.	Phase-CT-primary rating
EF (I_{ct} Measured)	Measured earth-leakage current from EF-CT.	Earth-fault-CT-primary rating
EF ($3I_0$ Calculated)	Calculated earth-leakage current from phase CT's.	Phase-CT-primary rating
Used I^2t	Used thermal capacity.	100% I^2t
RTD Temp	RTD temperature ⁽¹⁾ .	260°C
Unbalance	Current unbalance (I_2/I_1).	1 per unit or 100%
Zero	Zero calibration.	Not applicable
Full Scale	Full-scale calibration.	Not applicable

⁽¹⁾ The output defaults to the calibrated zero output for an open or shorted RTD sensor.

4.2.8 MISCELLANEOUS CONFIGURATION

Menu: *Setup | System Config*

- System Name* Appears on many of the display screens and can be set by the user (18-character alphanumeric field).
- Password* Used to change the 4-character alphanumeric password.
- Clock Setting* Used to set the date and 24-hour clock.
- Password Timeout* Used to set the password time-out delay. Delay is measured from last key press.
- UPI LED* Used to assign the internal parameter to the UPI LED.
- Maintenance* Used to clear event records, trip counters, and run hours.
Used to load defaults.
Used to view firmware version, unit serial number, and MAC address.
Used for firmware updates.

4.2.9 COMMUNICATIONS

Menu: *Setup | Hardware | TIA-232 Comms*

Menu: *Setup | Hardware | Network Comms*

The TIA-232 interface uses the Modbus[®] RTU protocol. Set the *TIA-232 ID* and *TIA-232 Baud* to match the requirements of the communications device. Default settings are the same as SE-Comm-RIS PC-interface software defaults.

If equipped with an optional network-communications interface, refer to the appropriate communications-interface manual.

NOTE: RS-232, EIA-232 and TIA-232 signal specifications are compatible with the FPU-32.

4.3 METERING

Menu: *Metering*

When *Metering* is selected in the main menu, press the right-arrow key to access a list of metering displays. Use the up- and down-arrow keys to scroll through the display list. Pressing the right-arrow key displays the selected metering information.

RESET is a "hot key" that is active in all meter displays. Pressing RESET causes a jump to the *Trip and Alarm* display to allow trips to be viewed and reset. Pressing ESC or the left-arrow key causes a return to the *Metering* display.

Many displays include per unit (pu) values where 1.0 pu is equal to 100%. I_a , I_b , I_c , I_1 , I_2 , and $3I_0$ are in per unit of phase-CT-primary rating. I_{ct} is in per unit of earth-fault-CT-primary rating.

The unbalance display indicates minus (-) if current inputs are not sequenced A-B-C (negative-sequence current is greater than positive-sequence current).

TABLE 4.5 METERING DISPLAY

METERING MENU	INFORMATION DISPLAY ⁽¹⁾
Current	I_a , I_b , I_c in A and per unit of I_p
Unbalance	I_1 , I_2 in per unit of I_p . I_2/I_1 in per unit
Earth Leakage	I_{ct} in A and per unit of I_c . $3I_0$ in A and per unit of I_p Displays $3I_0 > Pickup$ when current exceeds setting and $3I_0$ protection is selected.
Thermal Status	Used I^2t in percent Trend I^2t in percent Displays "Reset I^2t Trip" when reset is allowed. Displays reset time when tripped on I^2t . Displays time to trip in minutes if in overload.
Inverse Status	Phase and earth currents are less than or greater than inverse-overcurrent pickup.
Local Sensor	Sensor Type: RTD or PTC Displays temperature in °C when type is RTD. Open or Short RTD failure Displays sensor status (Normal, Open, Short) when type is PTC.
I/O Status	Digital input On or Off and relay outputs in binary
System Status	Date and time Settings Group ETR mode
Network Status	Online or timed out Modbus state DeviceNet errors and status

⁽¹⁾ All metering displays show System Name.

4.4 MESSAGES

Menu: *Messages*

Selecting *Messages* allows trip, alarm, and inhibit messages, event records, and statistical data to be viewed and resets to be performed.

4.4.1 TRIP RESET

Menu: *Messages | Trip and Alarm*

Up to fifteen trip and alarm messages can be displayed in a scrollable-list format. Trips must be individually selected and reset using the RESET key. All trips are simultaneously reset by a digital-input reset or with a communications-network command. Alarms are non-latching and are displayed only for the time that the alarm condition exists.

RESET is a "hot key" to the *Trip and Alarm* display, except during set-point entry. In the *Trip and Alarm* display, pressing ESC or the left arrow key causes a return to the display shown when RESET was pressed.

4.4.2 DATA LOGGING

Menu: *Messages | Event Records*

Trip-record data and Emergency Thermal Resets (ETR) are logged. Trip-record data includes the time of trip, cause of trip, and pre-trip data. ETR records contain a snapshot of the data prior to an ETR.

Trip- or ETR-records data includes:

- Time Stamp YY/MM/DD HH:MM:SS.
- I_a , I_b , I_c , I_{ct} and $3I_0$ at time of trip or ETR.
- Unbalance (I_2/I_1) at time of trip or ETR.
- I^2t at time of trip or ETR, and
- PTC/RTD temperature data if applicable.

Each record includes a record number in the first line of the record-data display. The record number is incremented when a new record is generated and has a range from 0 to 65535. When the *Event Records* menu is entered, the first record displayed is the latest record. The right-arrow key scrolls through previous records. Record scrolling stops when the 100th record has been reached or an empty record is displayed.

Event records can be cleared in the *Setup | System Config | Maintenance* menu.

Record Type Trip/ETR
Number of Records 100 (First In First Out)

4.4.3 STATISTICAL DATA

Menu: *Messages | Statistics*

The FPU records the following statistical data:

- Running hours and
- Counters for each trip type.

Statistical data can be cleared in the *Setup | System Config | Maintenance* menu.

4.4.4 EMERGENCY THERMAL RESET

Menu: *Messages | Emerg I2t Reset*

The *Emerg I²t Reset* menu is used to set *Used I²t* to zero. See Section 5.2.2.

4.5 PASSWORD ENTRY AND PROGRAMMING

Menu: *Setup | System Config | Password*

Menu: *Setup | System Config | Password Timeout*

NOTE: The default password is 1111. When the digital input is programmed for Program Enable, set-point access via the menu system is controlled by the digital input state and not by the password. Set Points can always be changed using communications and the password.

When password access is active, all set points are locked from changes until the four-character password is entered. If set-point access is locked, the user is prompted to enter the password. Once entered, set-point access is allowed and remains enabled until a key has not been pressed for the time defined by the *Password Timeout* set point.

Set points are selected either by entering alphanumeric characters or by choosing from a list.

EXAMPLE:

Prior to password entry:

```
I2T PICKUP
= 1.00 x IF
Locked! Press ↵ To
Enter Password.
```

Press ENTER. The *Password Entry* display is shown:

```
PASSWORD ENTRY
Enter Password
And Press ↵
[****]
```

Use the left- and right-arrow keys to select the position of the flashing cursor. Use the up- and down-arrow keys to select password characters. Press ENTER.

When the correct password is entered, a flashing cursor is displayed, the set-point range and units are shown, and the set point can be changed.

```
I2T PICKUP
= 1.00 x IF
(0.10 ÷ 1.25) x IF
[00001.00]
```

Use the up- and down-arrow keys to change a set-point update-field character, and use the left- and right-arrow

keys to move between characters. Press ENTER to update the set point, or press ESC to exit the display without changing the set point. A set point is set to the minimum or maximum value of its range if an out-of-range value is entered. Press ESC to exit the set-point-update screen.

The sequence for set-point characters depends upon the set-point type. The character sequence for numeric set points is:

... 0 1 2 3 4 5 6 7 8 9 . 0 1 2 3

The character sequence for string set points is:

... [0...9] [A...Z] [a...z] SP - . / [0...9] [A...Z]

Characters forming a series are shown in brackets and "SP" represents the space character.

For set points requiring selection from a list, the up- and down-arrow keys are used to scroll through the items. In the same manner as menu items, selections are displayed using one of the three cursor symbols (▼ ▲ ◆) preceding the item. Press ENTER to select the item. The selected item is indicated by the "*" symbol to its right.

EXAMPLE:

```
TRIP ACTION
Disabled          *
◆Trip 1
Trip
```

5. PROTECTIVE FUNCTIONS

5.1 GENERAL

The FPU-32 measures true RMS, peak, and the fundamental-frequency values of current. Fundamental-frequency values (magnitude and phase angle) are obtained by using Discrete-Fourier Transform (DFT) filtering that rejects dc and harmonics. The type of measurement used for a protective function is indicated in each section.

Each protective function can be assigned a trip action that defines the output contact(s) used. Except for overload protection which has auto-reset available, FPU-32 trips are latched. Trip actions are logged.

Trip-action selections are:

- Disable
- Trip1
- Trip2
- Trip3
- Trip1 and Trip2
- Trip1 and Trip3
- Trip1 and Trip2 and Trip3
- Trip2 and Trip3

Most protection functions can be assigned an alarm action. Alarm actions are auto-reset and do not generate event records.

Alarm-action selections are:

- Disable
- Alarm1
- Alarm2
- Alarm3
- Alarm1 and Alarm2
- Alarm1 and Alarm3
- Alarm1 and Alarm2 and Alarm3
- Alarm2 and Alarm3

To operate output contacts, trip and alarm actions must be assigned to output relays using the *Setup | Relay Outputs* menu. See Section 4.2.5.

For phase-overcurrent protection, three protection elements are available—overload, inverse time, and definite time. Each can be enabled or disabled as required and are individually annunciated.

IEC and IEEE inverse-time curves are supported. An IEC time multiplier setting range of 0.05 to 1.0 is provided. For consistency, the same multiplier is used for IEEE curves and requires the IEEE characteristic equation to be multiplied by 3. For equations and curves see Fig. 5.1 to Fig. 5.9 in Section 5.3.

For earth-fault protection, inverse time and definite time elements are available for the calculated zero-sequence component ($3I_0$). For the earth-fault CT inputs, only definite-time protection is provided. Calculated ($3I_0$)

and CT-input protection elements can be enabled simultaneously to provide low- and high-level earth-fault protection in solidly grounded systems.

Phase-overcurrent and ground-fault protection functions have two setting groups; Group 1 and Group 2. Set points are entered for each group and the active group is selected using the menu system, communications, or the digital input. See Section 4.2.6. Group selection allows setting two levels of protection. This is useful in feeder applications where the connected load changes as in tie-breaker systems, or in applications where the feeder is in maintenance mode and operation with reduced trip levels is required.

SE-Comm-RIS PC-interface software can be used to plot FPU-32 protection curves. See Section 7.1.2.

NOTE: See Appendix B for default set-point values. Per-unit notation (pu) is used. 1 pu = 100%.

5.2 OVERLOAD

5.2.1 I²t PROTECTION

Menu: *Setup | Protection | Overload*

Unlike IEC and IEEE inverse-time overcurrent protection, the I²t protection tracks thermal capacity for currents below the pickup setting.

The I²t protection algorithm uses the square of the maximum phase current as an input.

The cold-curve time-to-trip (*t*) in seconds for currents above the *F²t Pickup* setting is defined by:

$$t = 60 \times \tau \times \ln \left(\frac{I_M^2}{I_M^2 - I} \right)$$

Where :

τ = Time Constant setting in minutes

$$I_M = \frac{I_{MAX-RMS}}{I_{Pickup}}$$

The time constant for overload protection is set in the *Setup | Protection | Overload | Groups | Time Constant* menu. This value is specified in minutes.

From a given curve, the time constant can be determined by knowing the trip time at six times the pickup value (t_6). For this case, the time constant simplifies to:

$$\tau = 0.591 \times t_6$$

Where :

t_6 = Time in seconds at 6 × pickup level

τ = Time Constant setting in minutes

The FPU-32 provides indication of thermal trend and used thermal capacity. Thermal trend is the value that used thermal capacity is tending toward and it is a function of the square of load current. For currents greater than or equal to the pickup current, time-to-trip is

displayed in *Metering | Thermal Capacity*. The thermal trend value (*Trend I²t*) in percent is:

$$\text{Trend } I^2t = I_M^2 \times 100\%$$

For currents less than *I²t Pickup* current, *Trend I²t* in percent is a function of the *Hot Factor* setting given by:

$$\text{Trend } I^2t = I_M^2 \times HF \times 100\%$$

Where :

HF = *Hot Factor* setting

Selected *I²t* overload cold curves are shown in Fig. 5.1. FPU-32 *I²t* overload protection is dynamic. Time to trip at any overload current depends on the value of *Used I²t*—as *Used I²t* increases, time to trip decreases. FPU-32 *I²t* overload cold and warm protection curves can be plotted using SF-Comm-RIS PC-interface software.

An overload trip occurs when *Used I²t* reaches 100%. When an overload trip occurs, reset is not allowed until *Used I²t* falls below the *I²t Reset Level* set point. The time-to-reset in minutes is:

$$t = -\tau \times \text{Cooling Factor} \times \ln(I^2t \text{ Reset Level})$$

Time-to-reset is displayed in *Metering | Thermal Capacity*.

The thermal model has three different reset modes; Normal, Auto, and Rapid. The *I²t*-overload reset mode is set using the *Setup | Protection | Overload | I²t Reset Type* menu, and applies to both set-point groups.

A thermal-overload trip reset is not allowed until *Used I²t* falls below the *I²t Reset Level* setting. In *Normal* mode a reset input is required to reset a trip. *Normal* is the default reset mode.

In *Auto* mode, an *I²t*-overload trip is automatically reset when *Used I²t* falls below the *I²t Reset Level* setting.

In *Rapid* mode, *Used I²t* decreases exponentially with a fixed two-second time constant when current is not detected. A reset input is required to reset a trip.

Cooling Factor.....	0.10 to 10.00 x Thermal Time Constant
Time Constant	1.00 to 60.00 minutes
<i>I²t</i> Pickup.....	0.10 to 1.25 pu of CT-Primary Rating (<i>I_p</i>)
Hot Factor.....	0.10 to 1.00
<i>I²t</i> Alarm.....	0.50 to 1.00 pu
<i>I²t</i> Trip.....	1.00 pu
Protection	Enable/Disable Trip1, 2, 3 Enable/Disable Alarm1, 2, 3
Measurement Method.....	RMS
Set-Point Groups	Group 1 and Group 2
<i>I²t</i> Reset Level.....	0.10 to 0.90 pu (Applies to both groups)

5.2.2 EMERGENCY THERMAL RESET

Menu: *Messages | Emerg I2t Reset | Reset I2t Memory*

Emergency Thermal Reset (ETR) sets *Used I²t* to 0% and disables PTC and RTD temperature trips. Program access is required. Disabled-temperature protection is indicated by *t° Disabled by ETR* in the *System State* display. If PTC or RTD temperature protection is not enabled, *t° Disabled by ETR* will not be displayed. RTD or PTC trips are reset when ETR is performed regardless of measured temperatures. Temperature protection must be re-enabled in the *Messages | Emerg I²t Reset | Reenable Temp* menu, or by cycling supply voltage. Disabled-temperature protection can be assigned to the user-programmable indication LED. See Section 4.1.1

Temperature alarms and sensor verification remain enabled during ETR.

CAUTION: Temperature protection is not automatically re-enabled after an Emergency Thermal Reset.

5.3 INVERSE-TIME OVERCURRENT

Menu: *Setup | Protection | Phase Inverse*

The FPU-32 supports the inverse-time curves listed in Table 5.1.

TABLE 5.1 CURVE TYPES

CURVE TYPE	FIGURE
IEC Normal Inverse, Curve Type A	5.2
IEC Very Inverse, Curve Type B	5.3
IEC Extreme Inverse, Curve Type C	5.4
IEC Short Inverse, Curve Type A	5.5
IEC Long Inverse, Curve Type B	5.6
IEEE Moderate Inverse Curves	5.7
IEEE Very Inverse Curves	5.8
IEEE Extreme Inverse Curves	5.9

NOTE: The IEEE standard equations were derived by taking the average response of a number of IAC and CO relays set to a "time-dial" setting of 5. The FPU-32 time-multiplier setting of 1.0 corresponds to the IAC/CO "time-dial" setting of 15.

The *Curve* menu is used to select one of the curve shapes listed in Table 5.1. *Pickup* is in per unit of phase-CT rating and specifies the location of the curve's vertical asymptote ($I_M = I_{DFT}/I_{pickup} = 1$). *Time Multiplier* selects the specific curve within the curve type.

The FPU-32 uses the same time-multiplier range of 0.05 to 1.0 for both IEC and IEEE curves.

The *Metering | Inverse Status* menu indicates whether current is above or below *Pickup* and the UPI face-plate LED can be programmed to indicate that current is above *Pickup*. See Section 4.1.1.

Curve See Table 5.1
 Pickup 0.10 to 10.00 x CT-Primary Rating (I_p)
 Pickup Curve Threshold 1.1 x Pickup setting
 Reset Curve Threshold 0.9 x Pickup setting
 Time Multiplier 0.05 to 1.00

Protection Enable/Disable Trip1, 2, 3
 Measurement Method DFT c/w CT-saturation compensation
 Set-Point Groups Group 1 and Group 2

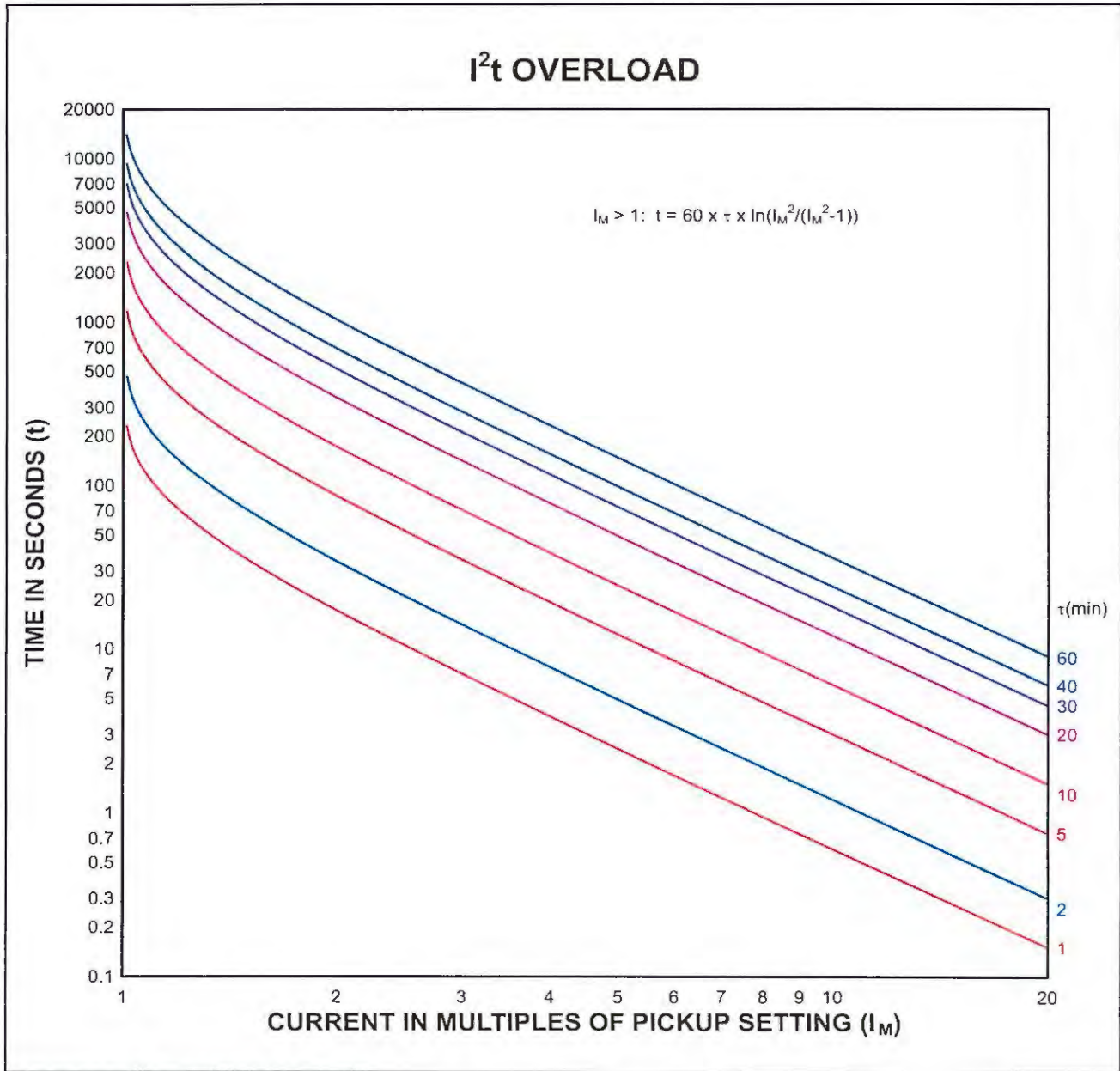


FIGURE 5.1 I²t Overload Cold Curves.

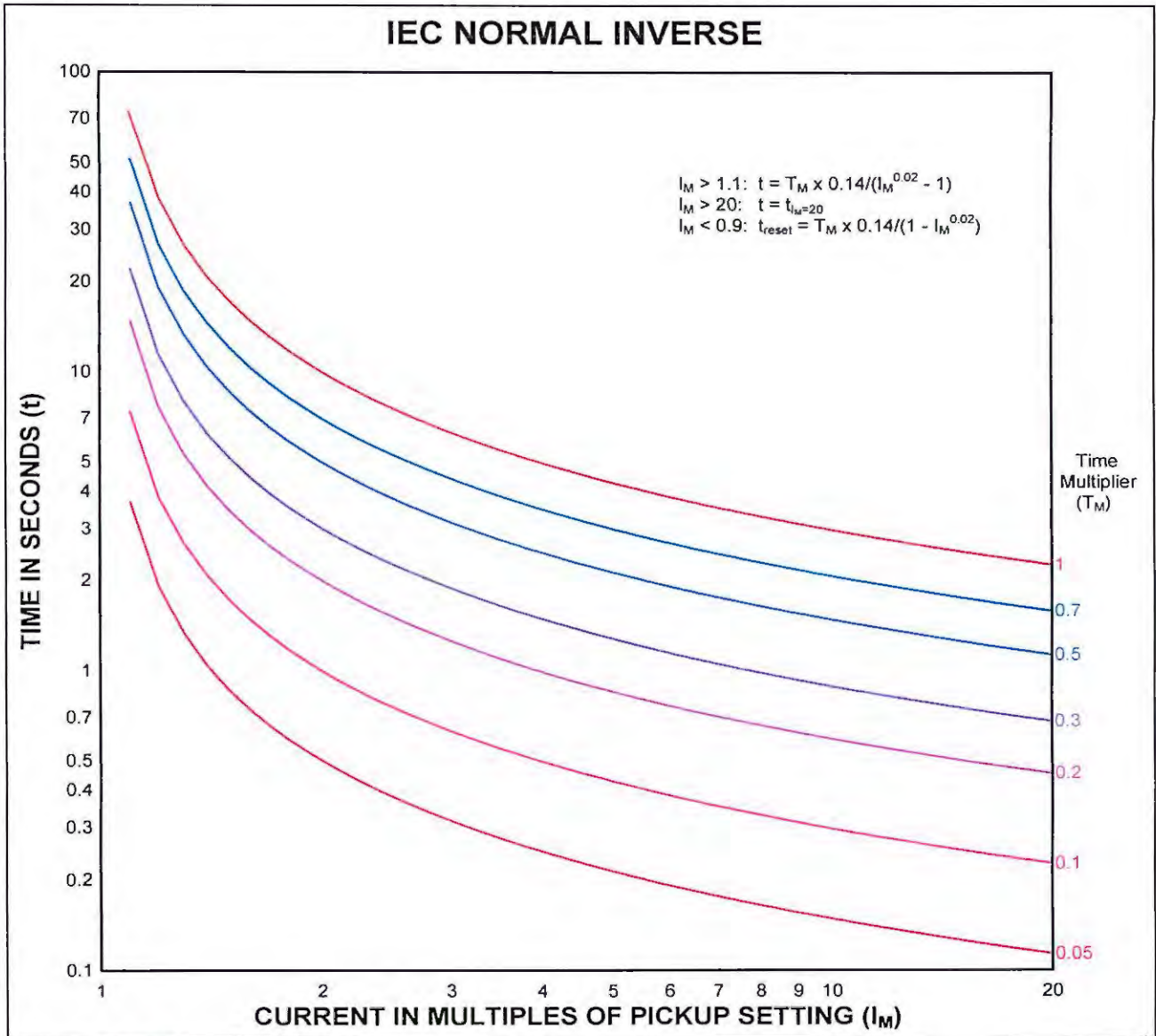


FIGURE 5.2 IEC Normal Inverse, Curve Type A.

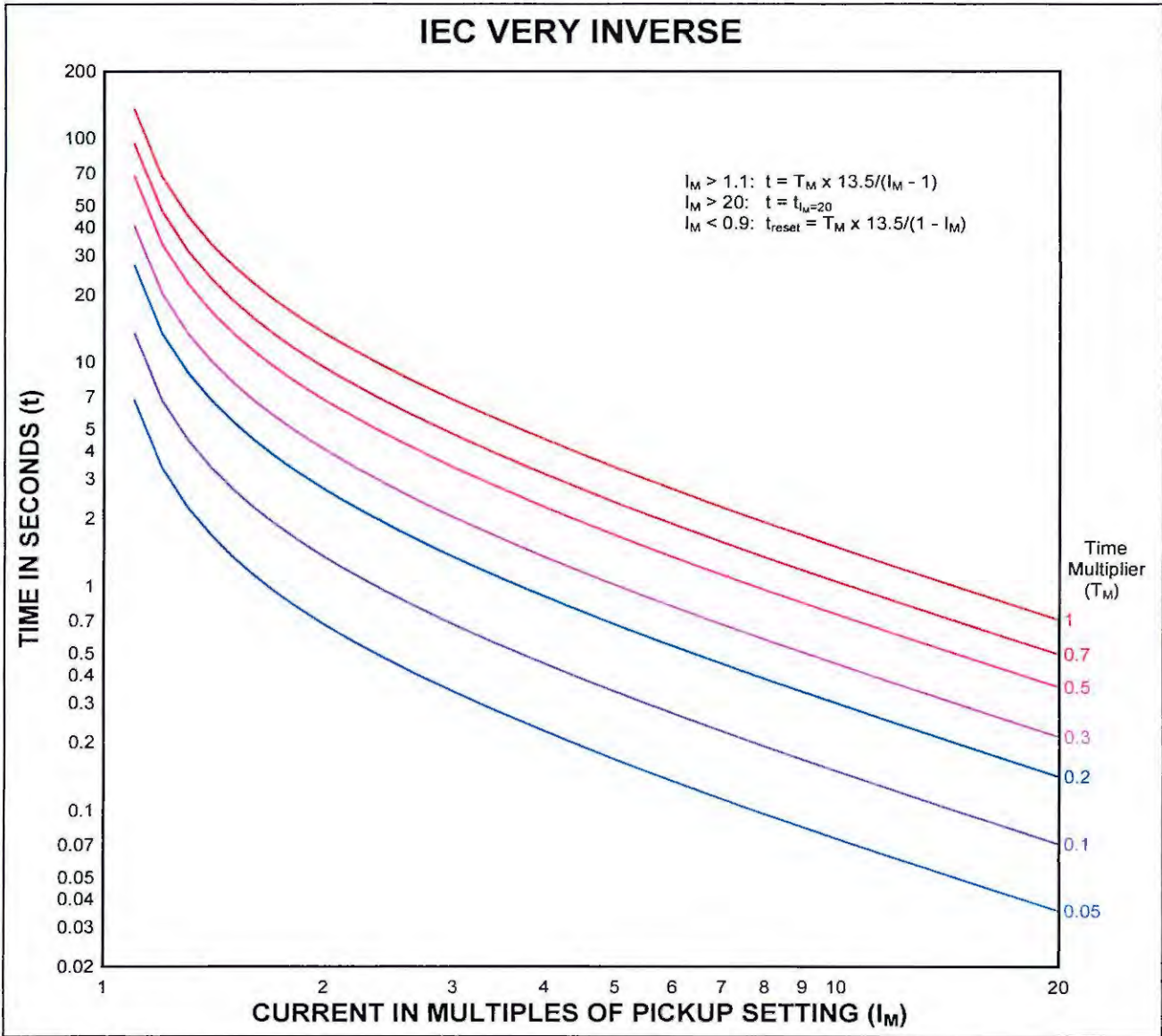


FIGURE 5.3 IEC Very Inverse, Curve Type B.

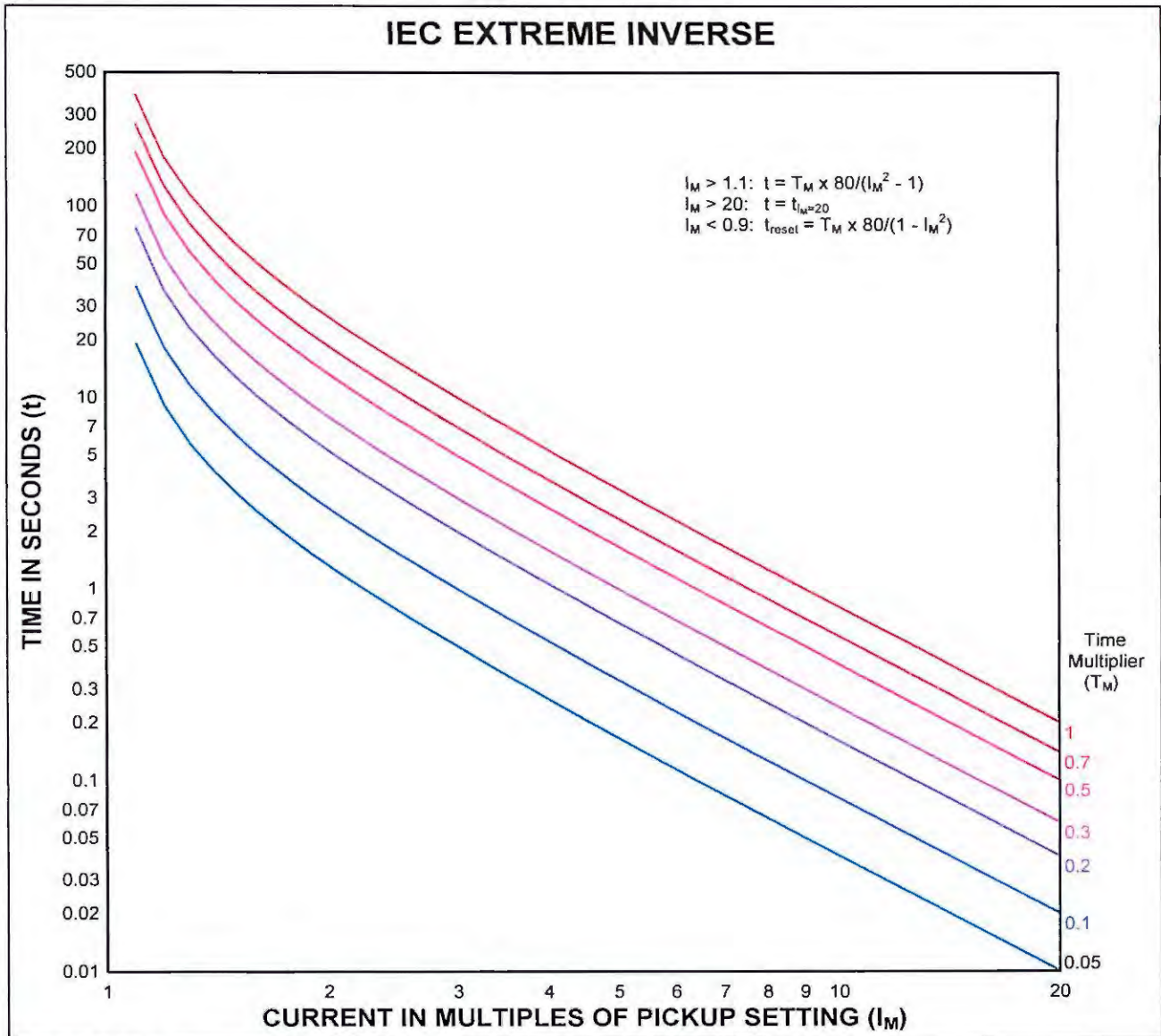


FIGURE 5.4 IEC Extreme Inverse, Curve Type C.

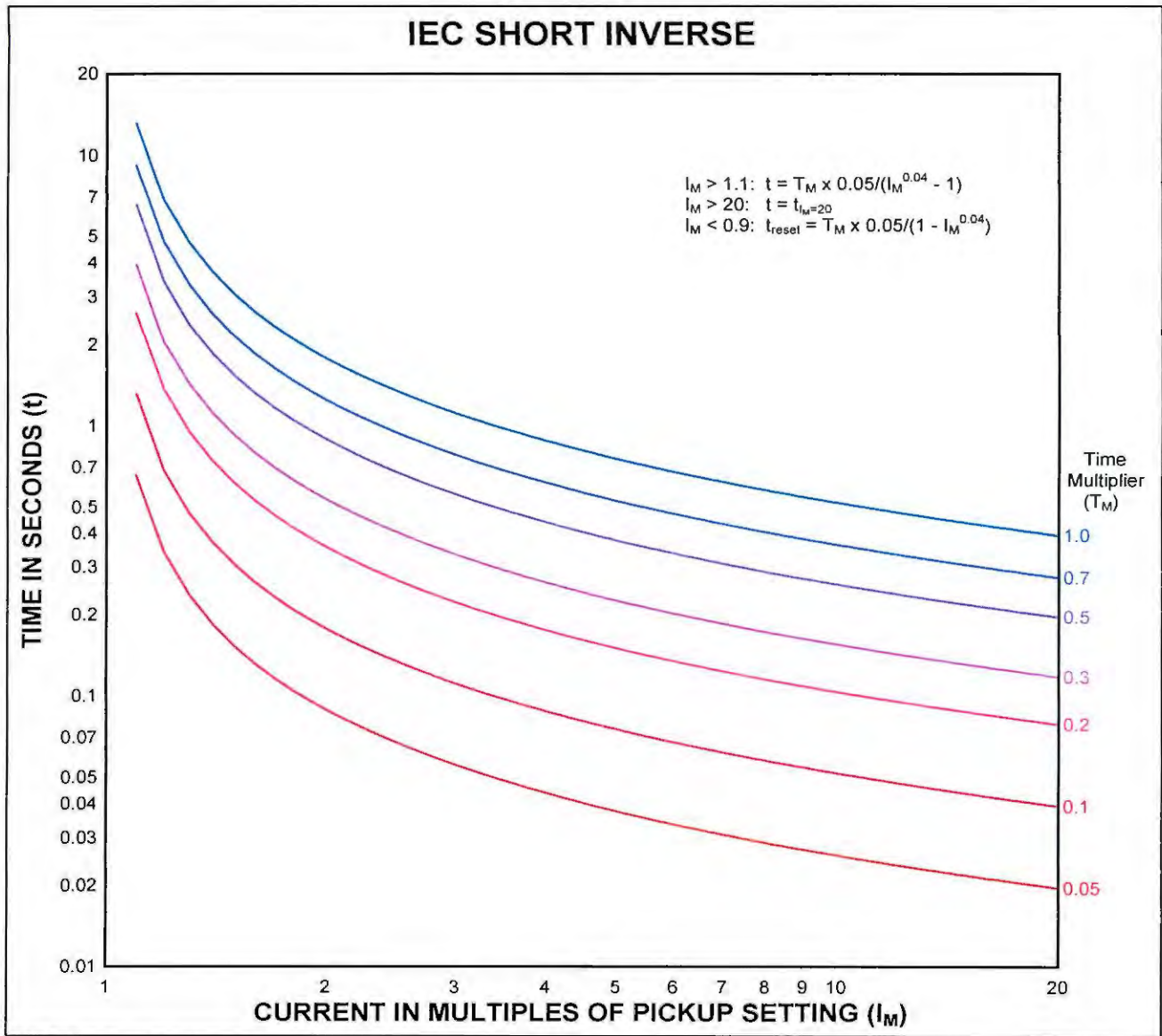


FIGURE 5.5 IEC Short Inverse, Curve Type A.

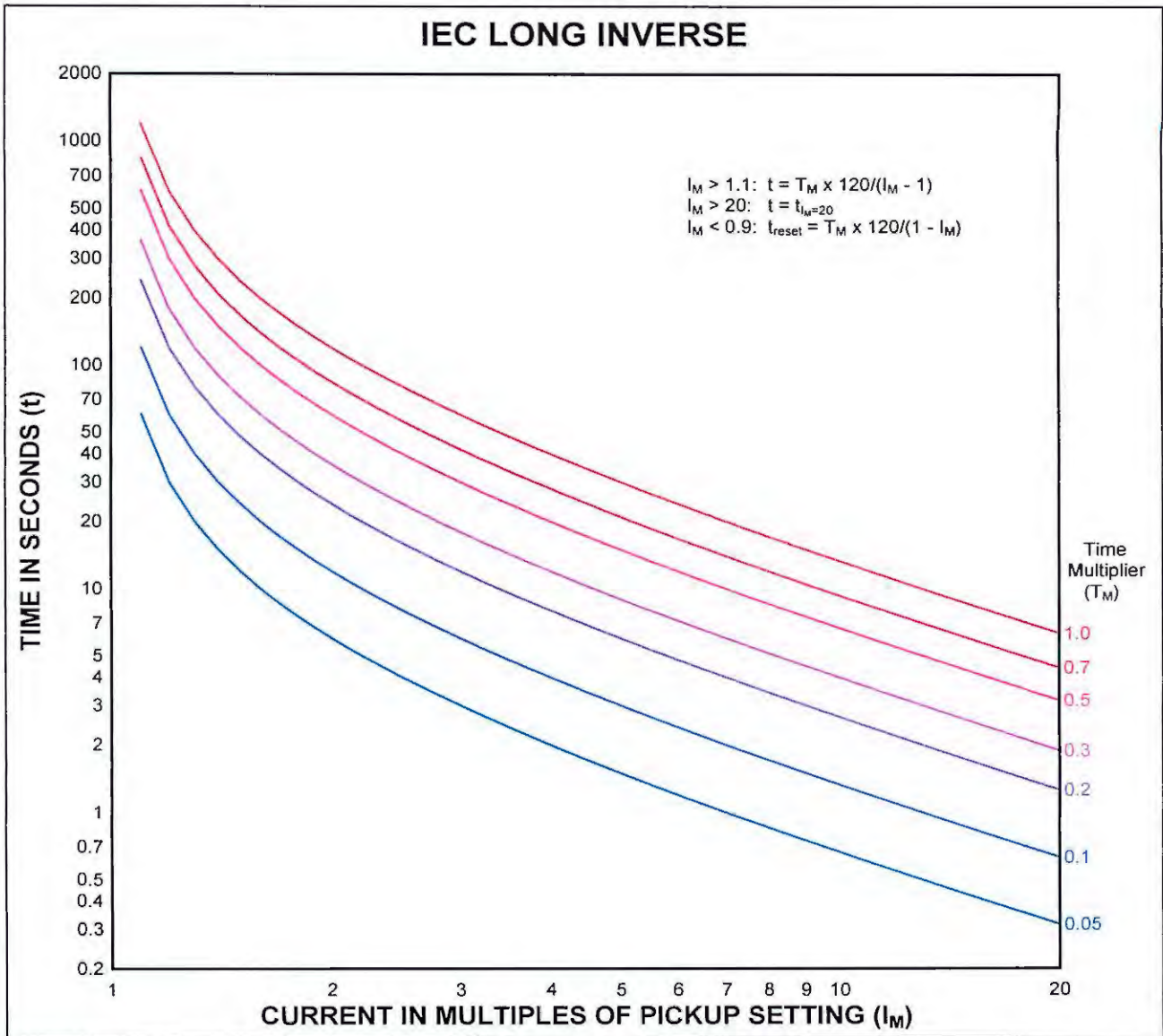


FIGURE 5.6 IEC Long Inverse, Curve Type B.

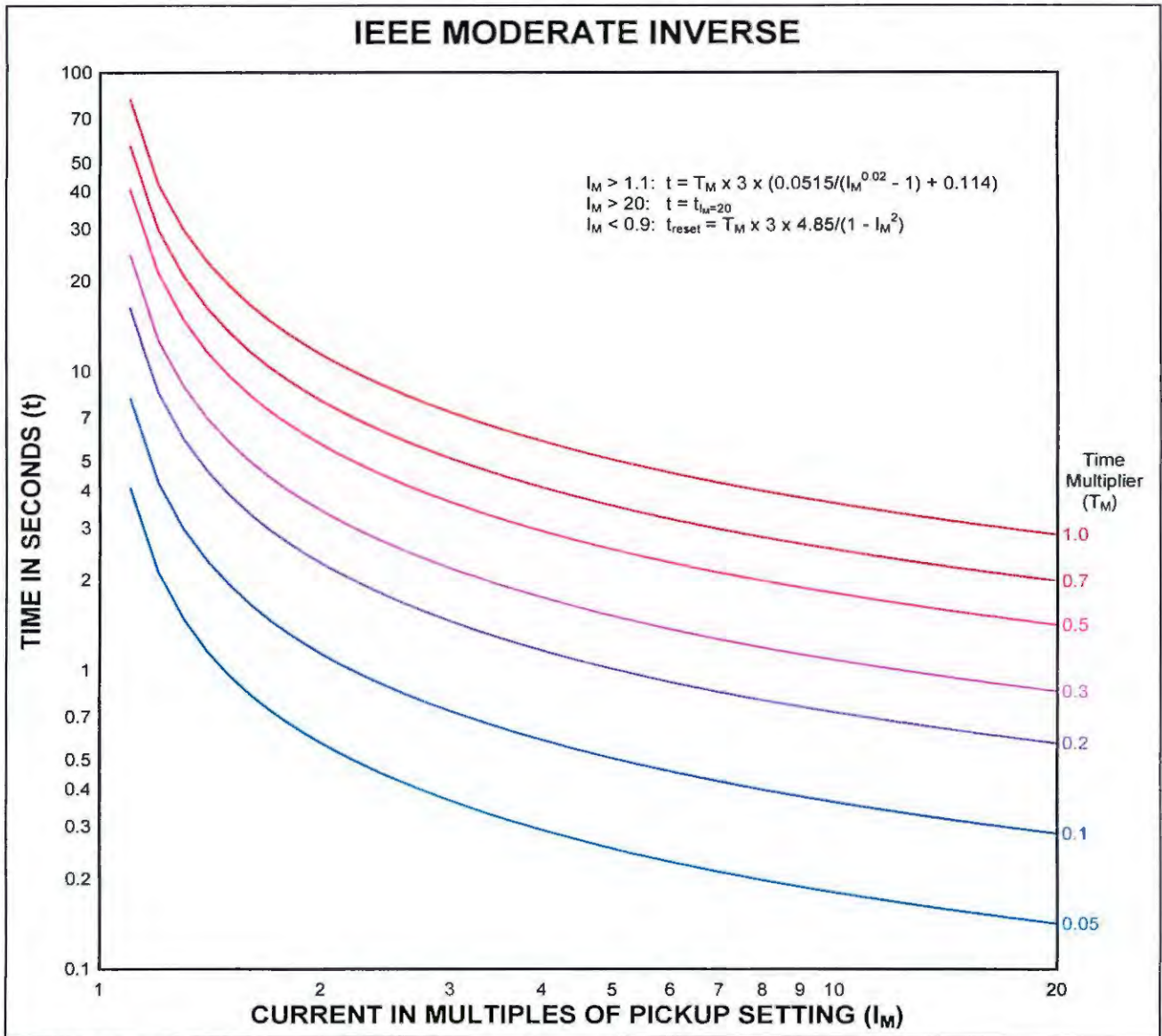


FIGURE 5.7 IEEE Moderate Inverse Curves.

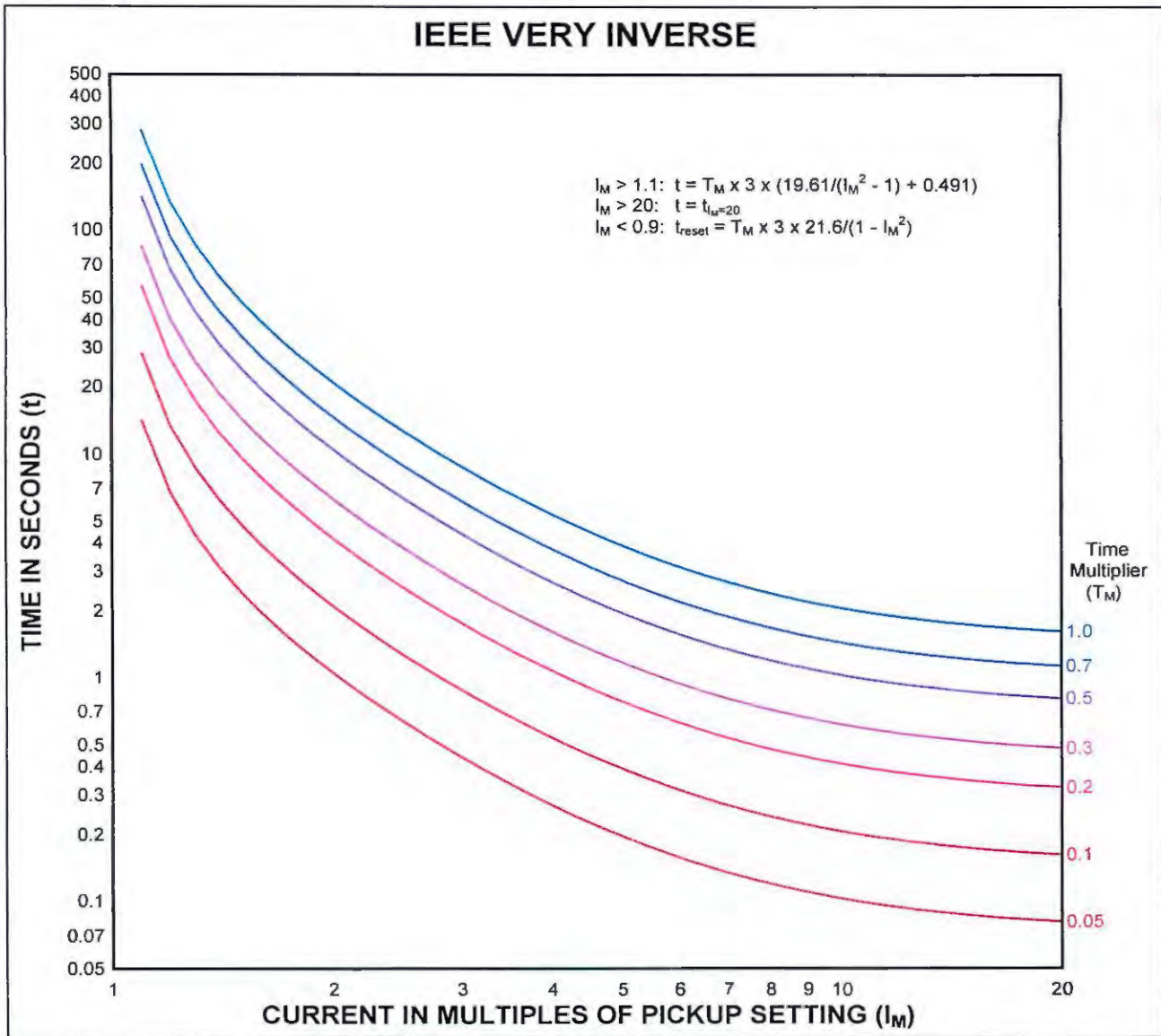


FIGURE 5.8 IEEE Very Inverse Curves.

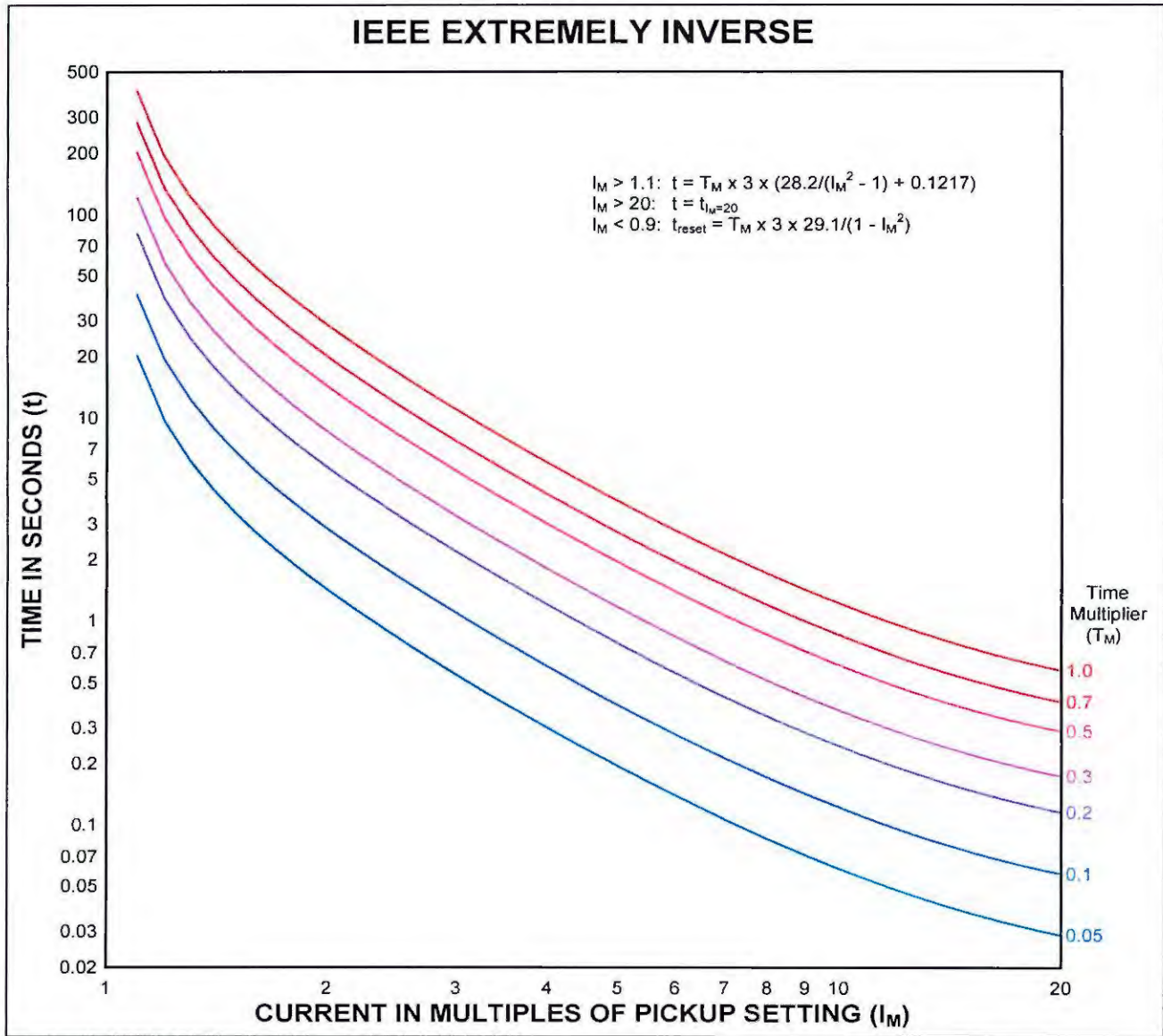


FIGURE 5.9 IEEE Extreme Inverse Curves.

5.4 DEFINITE-TIME OVERCURRENT

Menu: *Setup | Protection | Ph Def Time*

The definite-time overcurrent function has both trip and alarm settings. With the DFT measurement method it may be possible to set the overcurrent protection closer to the desired value as compared to the RMS measurement method.

The asymmetrical-current multipliers for RMS and DFT measuring methods are shown in Fig. 5.10. Typical X/R values are 6.6 for a low-voltage system, 15 for a medium-voltage system, and can be as high as 25 for a high-voltage system. The DFT filters the dc component so that the overcurrent setting can be set closer to the symmetrical fault value.

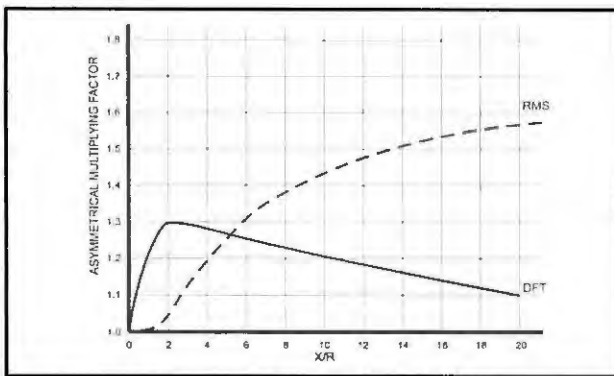


FIGURE 5.10 Asymmetrical-Current Multipliers

- Trip Level.....0.10 to 15.00 x CT-Primary Rating (I_p)
- Trip Delay (D).....0.00 to 10.00 s (see Table 5.2)
- Alarm Level0.10 to 15.00 x I_p
- Alarm Delay (D).....0.00 to 10.00 s (see Table 5.2)
- ProtectionEnable/Disable Trip1, 2, 3 Enable/Disable Alarm1, 2, 3
- Measurement Method.....DFT c/w CT-saturation compensation
- Set-Point GroupsGroup 1 and Group 2

TABLE 5.2 FAULT DURATION REQUIRED FOR TRIP⁽¹⁾⁽²⁾

FAULT LEVEL (multiples of trip-level setting)	FAULT DURATION (FD) (ms)	
	D ≤ 30 ms ⁽³⁾	D > 30 ms ⁽³⁾
2	FD = 10 ms	FD = (D - 20) ms
5	FD = 5 ms	FD = (D - 25) ms
10	FD = 2 ms	FD = (D - 28) ms

⁽¹⁾ For overcurrent less than 15 x CT-Primary Rating. For earth faults less than 1 x EF-CT-Primary Rating. Fixed frequency, 60 Hz.

⁽²⁾ Minimum relay operating time: 25 to 45 ms.

⁽³⁾ D is the trip-time setting.

5.5 INVERSE-TIME 3I₀ EARTH FAULT

Menu: *Setup | Protection | 3I₀ Inverse*

This protection function is based on the zero-sequence current calculated from the three phase currents.

The *Curve* menu is used to select one of the curve shapes listed in Table 5.1. *Pickup* is in per unit of phase CT rating and specifies the location of the curve's vertical asymptote ($I_M = I_{DFT}/I_{pickup} = 1$). *Time Multiplier* selects the specific curve within the curve type.

The FPU-32 uses the same time multiplier range of 0.05 to 1.0 for both IEC and IEEE curves.

The *Metering | Inverse Status* menu indicates whether current is above or below *Pickup* and the UPI face-plate LED can be programmed to indicate that current is above *Pickup*. See Section 4.1.1.

- Curve.....Table 5.1
- Pickup0.10 to 10.00 x CT-Primary Rating (I_p)
- Pickup Curve Threshold.....1.1 x Pickup setting
- Reset Curve Threshold.....0.9 x Pickup setting
- Time Multiplier0.05 to 1.00
- ProtectionEnable/Disable Trip1, 2, 3
- Measurement MethodDFT - derived 3I₀
- Set-Point GroupsGroup 1 and Group 2

NOTE: For IEEE curves, a multiplier of 1 corresponds to a IAC/CO "time-dial" setting of 15.

NOTE: CT saturation is not detected. Enable overcurrent protection when fault levels can exceed 15 times the phase-CT-primary rating.

5.6 DEFINITE-TIME 3I₀ EARTH FAULT

Menu: *Setup | Protection | 3I₀ Def Time*

This protection is based on the zero-sequence current calculated from the phase currents.

- Trip Level.....0.10 to 15.00 x CT-Primary Rating (I_p)
- Trip Delay (D).....0.00 to 10.00 s (see Table 5.2)
- Alarm Level0.10 to 15.00 x I_p
- Alarm Delay (D)0.00 to 10.00 s (see Table 5.2)
- ProtectionEnable/Disable Trip1, 2, 3 Enable/Disable Alarm1, 2, 3
- Measurement MethodDFT—derived 3I₀
- Set-Point GroupsGroup 1 and Group 2

NOTE: For IEEE curves, a multiplier of 1 corresponds to a IAC/CO "time-dial" setting of 15.

NOTE: CT saturation is not detected. Enable overcurrent protection when fault levels can exceed 15 times the phase-CT-primary rating.

5.7 DEFINITE-TIME EARTH FAULT

Menu: *Setup | Protection | Ict Def Time*

This protection function uses the earth-fault-CT input. The protection setting range is equal to the earth-fault-CT-primary rating (I_c).

- Trip Level.....0.01 to 1.00 x Earth-Fault
CT primary rating (I_c)
- Trip Delay (D).....0.00 to 100.00 s
(see Table 5.2)
- Alarm Level0.01 to 1.00 x I_c
- Alarm Delay (D).....0.00 to 100.00 s
(see Table 5.2)
- ProtectionEnable/Disable Trip1, 2, 3
Enable/Disable Alarm1, 2, 3
- Measurement Method.....DFT c/w saturation
compensation
- Set-Point GroupsGroup 1 and Group 2

5.8 CURRENT UNBALANCE

Menu: *Setup | Protection | Unbalance*

Menu: *Setup | System Config | I₂/I₁ Threshold*

Positive-sequence current (I_1) and negative-sequence current (I_2) are used to determine current unbalance (I_2/I_1). The unbalance display range is 0.00 to 1.00 where 1.00 is 100% unbalance—a single-phase condition. Single-phase loads generate unbalance that may cause false trips when feeder currents are low. The *I₂/I₁ Threshold* sets the current level where unbalance protection becomes active. The threshold is based on the maximum of the three-phase currents. Set this value above the single-phase load value to avoid false trips. Negative unbalance is indicated when current inputs are connected B-A-C (negative-sequence current is greater than positive-sequence current). Severe unbalance may also be indicated if phase-CT polarity is incorrect.

- Trip Level.....0.05 to 1.00
- Trip Delay1.00 to 100.00 s
- Alarm Level0.05 to 1.00
- Alarm Delay1.00 to 100.00 s
- ProtectionEnable/Disable Trip1, 2, 3
Enable/Disable Alarm1, 2, 3
- Threshold.....0.10 to 0.50 x I_p
- Measurement Method.....DFT

5.9 PHASE LOSS

Menu: *Setup | Protection | Phase Loss*

Phase loss is a severe form of unbalance and can be used to detect open-circuit faults. When phase loss occurs on a 3-phase load, negative-sequence current (I_2) is equal to positive-sequence current (I_1). The phase-loss algorithm considers I_2/I_1 from 0.90 to 1.00 to be a phase loss. Set the phase-loss trip delay shorter than the unbalance trip delay to avoid an unbalance trip in the event of a phase loss.

The phase-loss threshold is fixed at 10% of the CT-primary rating (I_p).

- Trip Delay 1.00 to 100.00 s
- Alarm Delay..... 1.00 to 100.00 s
- Protection Enable/Disable Trip1, 2, 3
Enable/Disable Alarm1, 2, 3
- Measurement Method DFT

5.10 PHASE REVERSE

Menu: *Setup | Protection | Phase Rev*

If the current phase sequence is B-A-C, the magnitude of negative-sequence current will be larger than the magnitude of positive-sequence current. To maintain magnitude consistency for set points, the I_2/I_1 ratio is inverted for the protection algorithm when phase sequence is B-A-C. A negative unbalance is indicated in the meter display for B-A-C sequence.

The phase-reverse threshold is fixed at 10% of the CT-primary rating (I_p).

- Trip Delay 1.00 to 100.00 s
- Alarm Delay..... 1.00 to 100.00 s
- Protection Enable/Disable Trip1, 2, 3
Enable/Disable Alarm 1, 2, 3
- Measurement Method DFT

5.11 PTC TEMPERATURE

Menu: *Setup | Hardware | Temp Sensor Type*

Menu: *Setup | Protection | PTC Local Temp*

The local-temperature-sensor input is configured for a positive-temperature-coefficient (PTC) thermistor sensor using the *Setup | Hardware | Temp Sensor Type* menu.

The total resistance of series-connected PTC thermistors must be less than 1,500 Ω at 20°C. A trip or alarm will occur when series resistance exceeds 2,800 Ω .

During Emergency Thermal Reset, a PTC trip is reset and PTC-temperature protection is disabled. See Section 5.2.2.

- ProtectionEnable/Disable Trip1, 2, 3
Enable/Disable Alarm1, 2, 3

5.12 RTD TEMPERATURE

Menu: *Setup | Hardware | Temp Sensor Type*

Menu: *Setup | Protection | RTD Temperature*

The local-temperature-sensor input is configured for a Pt100 RTD sensor using the *Setup | Hardware | Temp Sensor Type* menu.

Sensor verification is enabled using the *Sensor Trip Act* and *Sensor Alarm Act* Action menus. When a sensor failure is detected, the corresponding protection is disabled.

During Emergency Thermal Reset, an RTD trip is reset and RTD-temperature protection is disabled. See Section 5.2.2.

Trip Range.....	40.00 to 230.00°C
Alarm Range	40.00 to 230.00°C
Display Range	-40 to 260°C
Sensor Verification.....	Enable/Disable Trip 1, 2, 3
	Enable/Disable Alarm 1, 2, 3
Protection	Enable/Disable Trip 1, 2, 3
	Enable/Disable Alarm 1, 2, 3

6. THEORY OF OPERATION

6.1 SIGNAL-PROCESSING ALGORITHMS

The FPU-32 obtains thirty-two samples per cycle of each current signal — the sampling frequency is 1.6 kHz in 50-Hz applications and 1.92 kHz in 60-Hz applications.

A Discrete-Fourier-Transform (DFT) algorithm is used to obtain the magnitudes and phase angles of the fundamental-frequency components of the current waveforms. These values provide true positive-, negative-, and zero-sequence components. True RMS values of phase currents include up to the 16th harmonic. Fundamental-frequency values are displayed.

Peak-to-peak currents are measured and compared to DFT values to compensate for CT saturation.

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7. COMMUNICATIONS

7.1 PERSONAL-COMPUTER INTERFACE

7.1.1 FIRMWARE UPGRADE

The FPU-32 control program is stored in flash memory. Field updates can be made through the TIA-232 communication interface located on the rear panel. The following are required:

- A Windows[®] PC, a TIA-232 interface, and the SE-Flash program.
- a file containing the FPU-32 control program (.s19 file), and
- an RJ-45 to DB9 adapter (CA-945).

SE-Flash is available at www.startco.ca and a CA-945 adapter is available from Littelfuse Startco.

7.1.2 SE-COMM-RIS

SE-Comm-RIS Relay Interface Software is a Windows[®]-based program used to access FPU-32 functions with a personal computer (PC) via the TIA-232 or optional TIA-485 and Ethernet interfaces. Use SE-Comm-RIS to program an FPU-32 either by changing individual set points or by downloading set-point files. Existing FPU-32 set points can be transferred to the PC. Metered values can be viewed and the FPU-32 can be controlled with the computer. SE-Comm-RIS extends the event-record storage capability of the FPU-32 by allowing the user to transfer data to PC memory at a programmable interval. Protection curve plotting capability is included. SE-Comm-RIS is available at www.startco.ca.

7.2 NETWORK INTERFACE

For detailed information see Appendices to this manual and applicable communications manuals.

7.2.1 TIA-485 OPTION

The TIA-485 communications option supports Modbus[®] RTU and Allen-Bradley[®] DFI half-duplex protocols. All set points and meter values are accessible. Commands are provided to perform trips, resets, and remote relay control.

Modbus[®] RTU function codes supported:

- Read Holding Registers (Code 3)
- Read Input Registers (Code 4)
- Write Single Register (Code 6)
- Write Multiple Registers (Code 16)
- Command Instruction (Code 5)

DFI commands supported:

- Unprotected Read (CMD = 01)
- Unprotected Write (CMD = 08)
- Typed Read (CMD = 0F, FNC = 68)
- Typed Write (CMD = 0F, FNC = 67)
- Typed Logical Read (CMD = 0F, FNC = A2)
- Typed Logical Write (CMD = 0F, FNC = AA)

NOTE: The FPU-32 and FPU-16 can be connected to the same network; however, the FPU-32 register map is not compatible with the FPU-16.

7.2.2 DEVICENET OPTION

The DeviceNet[™] communications option supports Explicit Messaging and Polled I/O. All set points and meter values are accessible using Explicit Messaging. The Polled I/O connection supports the following ODVA input assemblies:

- Basic Overload (50)
- Extended Overload (51)
- Basic Motor Starter (52)
- Extended Motor Starter (53)

In addition to the ODVA assemblies, a user-configurable fixed block of 64 bytes is available.

The Polled I/O connection supports the following ODVA output assemblies:

- Basic Overload (2)
- Basic Motor Starter (3)

An Electronic Data Sheet (EDS) file is provided for use with DeviceNet configuration tools such as RSNetWorx and DeltaV.

7.2.3 ETHERNET OPTION

The Ethernet option supports the Modbus[®] TCP protocol. Modbus[®] TCP uses TCP/IP to encapsulate the Modbus[®] RTU protocol. Up to five simultaneous connections are supported. In addition to the Modbus[®] RTU function codes listed in Section 7.2.1, the Read Device Identification Code (43) is supported.

The FPU-32 Modbus[®] TCP interface is compatible with SE-Comm-RIS Version 1.6 and above. See Section 7.1.2.

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8. TECHNICAL SPECIFICATIONS

8.1 FPU-32

Supply 30 VA, 65 to 265 Vac,
40 to 400 Hz.
25 W, 80 to 275 Vdc.

Power-Up Time 800 ms at 120 Vac

Ride-Through Time 100 ms minimum

24-Vdc Source ⁽¹⁾ 400 mA maximum

AC Measurements:

Methods True RMS, DFT, Peak,
and positive- and
negative-sequence
components of the
fundamental.

Sample Rate 32 samples/cycle.

Frequency: 50 or 60 Hz

Phase-Current Measurement: ⁽²⁾

Metering Range 15 x CT-Primary Rating (I_p)

Protection Range 80 x I_p

Metering Accuracy: ^(3,4)

$I < I_p$ 2% I_p

$I > I_p$ 2% Reading

Unbalance Accuracy 0.02 pu

Earth-Leakage Measurement:

Range 1.5 x Earth-Fault-CT-
Primary Rating (I_e)

Accuracy ^(3,4) 2% I_e

PTC-Thermistor Input: ⁽⁷⁾

Cold Resistance 1,500 Ω maximum at 20°C

Trip Level 2,800 $\Omega \pm 200 \Omega$

Reset Level 1,500 $\Omega \pm 200 \Omega$

Sensor Current 1 mA maximum

RTD Input: ⁽⁷⁾

RTD Type 3 wire Pt100

Range -40 to 260°C with open
and short detection

Sensor Current 1 mA

Lead Compensation 25 Ω maximum

Accuracy 2°C (-40 to 200°C)

5°C (200 to 260°C)

4–20-mA Analog Output:

Type Self powered and loop
powered

Range 4 to 22 mA

Update Time 250 ms

Loop Voltage 8 to 26 Vdc

Load 500 Ω (maximum with
24 Vdc supply)

Isolation ⁽¹⁾ 120 Vac with L/S switch in
L position

Timing Accuracies: ⁽⁵⁾

I^2t Overload 2%, 100 ms resolution

IEC/IEEE Curves 5%, 10 ms resolution

Definite Time 2%, 10 ms resolution

Phase Unbalance,

Loss, Reverse 2%, 100 ms resolution

Relay Contacts:

Configuration N.O. and N.C. (Form C)

CSA/UL Contact Rating 8 A resistive 250 Vac,
8 A resistive 30 Vdc

Supplemental Contact Ratings:

Make/Carry 0.2 s 20 A

Break:

dc 50 W resistive,

25 W inductive (L/R = 0.04)

ac 2,000 VA resistive,

1,500 VA inductive

(PF = 0.4)

Subject to maximums of 8 A and 250 V (ac or dc).

Digital Input: ⁽¹⁾

Range 12 to 36 Vdc, 5 mA at
24 Vdc

Guaranteed On 12 Vdc at 2 mA

Guaranteed Off 3 Vdc at 0.5 mA

Isolation 120 Vac

I/O Module Interface:

Module Supply ⁽¹⁾ 24 Vdc, 400 mA maximum

Configuration TIA-485, 2 wire multi-drop

Bus Length 1.2 km (4,000') maximum

Cable Belden 3124A or
equivalent

TIA-232 Communications:

Baud Rate 9.6, 19.2, 38.4 khits

Protocol Modbus RTU

Address 1 to 255

Real-Time Clock:

Power-Off Operation 6 Months at 20°C

Battery Rechargeable lithium
(no service required)

Non-Volatile RAM:
Power-Off Retention..... 10 Years

Shipping Weight.....2.0 kg (4.4 lb)

PWB Conformal Coating MIL-I-46058 qualified
UL QMJU2 recognized

Environment:
Operating Temperature..... -40 to 60°C ⁽⁶⁾
Storage Temperature..... -55 to 80°C
Humidity 85% Non-Condensing

Surge Withstand ANSI/IEEE C37.90.1-1989
(Oscillatory and Fast Transient)

Inverse Time Curves IEEE Std C37.112-1996
CEI/IEC 255-3:1989

Certification..... CSA, Canada and USA



To:
CSA C22.2 No. 14 Industrial Control Equipment
UL 508 Industrial Control Equipment
UL 1053 Ground Fault Sensing and Relaying
Equipment



NOTES:

- ⁽¹⁾ The I/O module supply and analog output are referenced to the same supply when the L/S switch is in the "S" position. In the "L" position, the analog output's isolation is 120 Vac.
- ⁽²⁾ Current threshold is 2% of phase-CT rating. To maintain specified accuracy, phase CT's should be selected with a primary rating between 100 and 300% of rated current.
- ⁽³⁾ Transformer accuracy not included.
- ⁽⁴⁾ Accuracy is a function of MPU-CIM to FPU-32 cable resistance: % Accuracy = 2 + 0.65 x cable resistance (Ω).
- ⁽⁵⁾ Minimum time is 25 to 45 ms. See Table 5.2 for fault duration required.
- ⁽⁶⁾ Display readability decreases at temperatures below -20°C.
- ⁽⁷⁾ PTC and RTD sensors are mutually exclusive.

8.2 CURRENT INPUT MODULE (MPU-CIM)

CT Inputs:
Thermal Withstand:
Continuous..... 5 x CT-Secondary Rating
1-Second 80 x CT-Secondary Rating

Burden:
1- and 5-A inputs..... < 0.01 Ω
EFCT-x input..... 10 Ω

Interconnection Cable:
Type Littelfuse Startco
S75-M16A-20030
Resistance 5.3 Ω/100 m (328')⁽⁴⁾
Supplied Length 6 m (19')

Terminal-Block Ratings:
CT Inputs..... 25 A, 500 Vac.
10 AWG (4.0 mm²)

Shipping Weight.....0.4 kg (0.9 lb)

PWB Conformal Coating.....MIL-I-46058 qualified
UL QMJU2 recognized

Environment:
Operating Temperature.....-40 to 60°C
Storage Temperature.....-55 to 80°C
Humidity85% Non-Condensing

Surge WithstandANSI/IEEE C37.90.1-1989
(Oscillatory and Fast Transient)

CertificationCSA, Canada and USA



To:
CSA C22.2 No. 14 Industrial Control Equipment
UL 508 Industrial Control Equipment
UL 1053 Ground Fault Sensing and Relaying
Equipment



9. WARRANTY

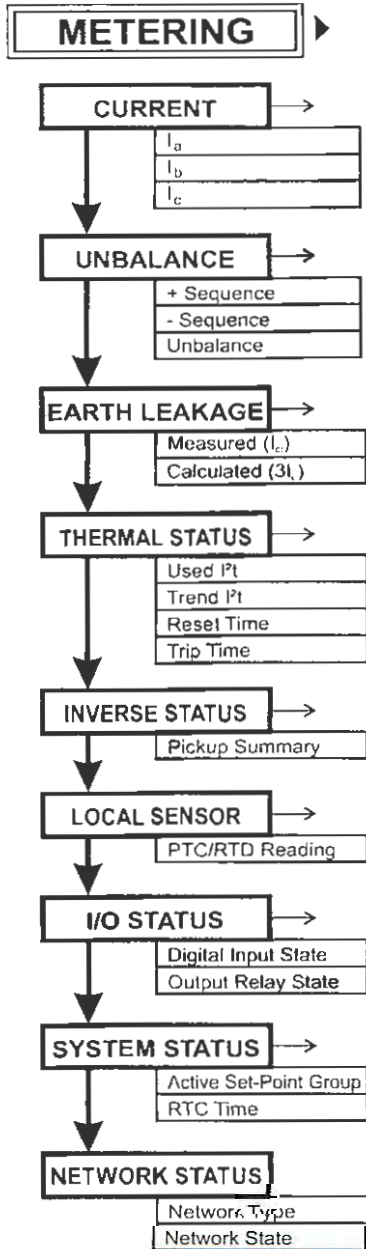
The FPU-32 Feeder Protection Unit is warranted to be free from defects in material and workmanship for a period of five years from the date of purchase.

Littelfuse Startco will (at Littelfuse Startco's option) repair, replace, or refund the original purchase price of an FPU-32 that is determined by Littelfuse Startco to be defective if it is returned to the factory, freight prepaid, within the warranty period. This warranty does not apply to repairs required as a result of misuse, negligence, an accident, improper installation, tampering, or insufficient care. Littelfuse Startco does not warrant products repaired or modified by non-Littelfuse Startco personnel.

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APPENDIX A
FPU-32 MENU MAP

MAIN MENU

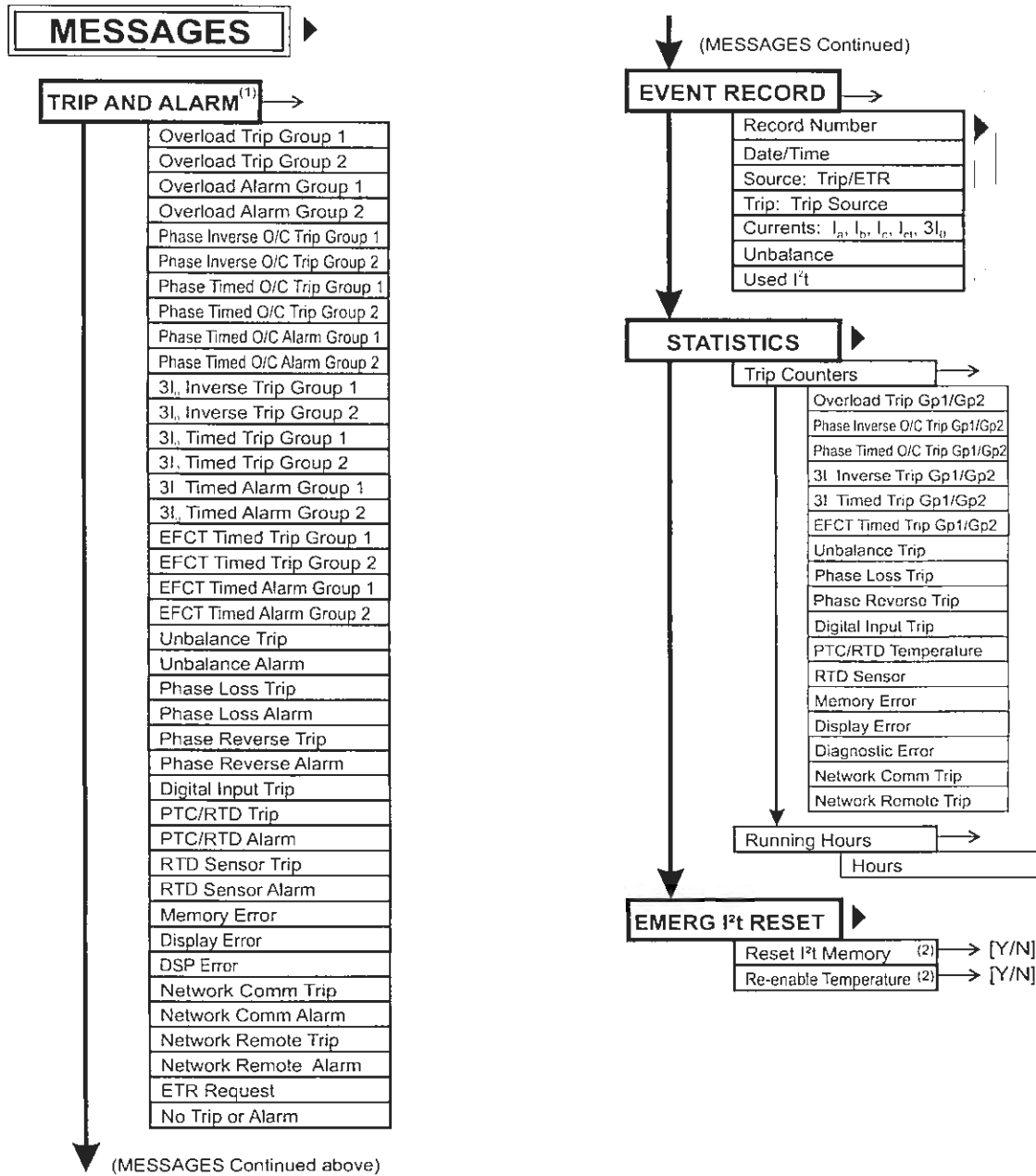


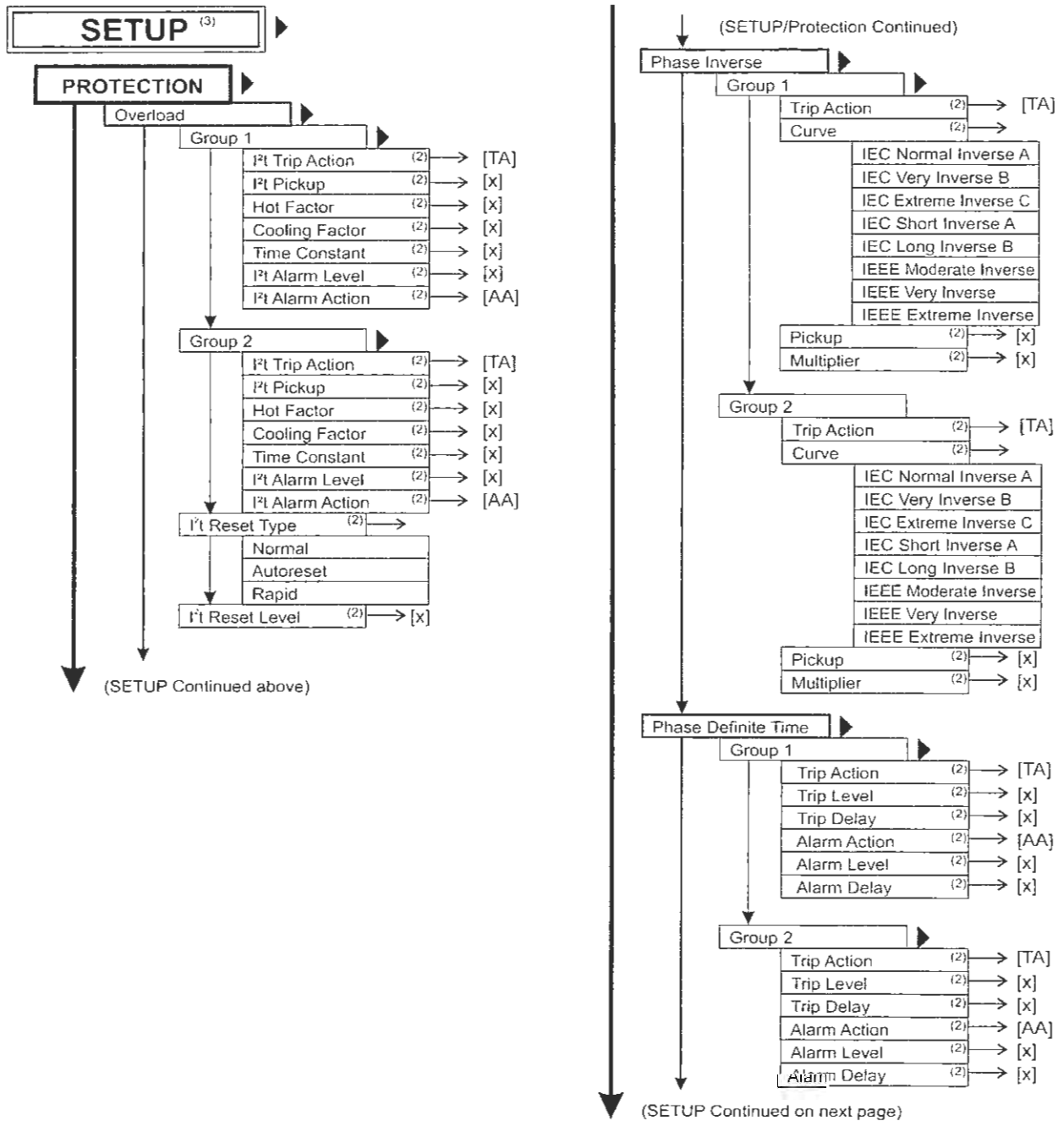
Notes:

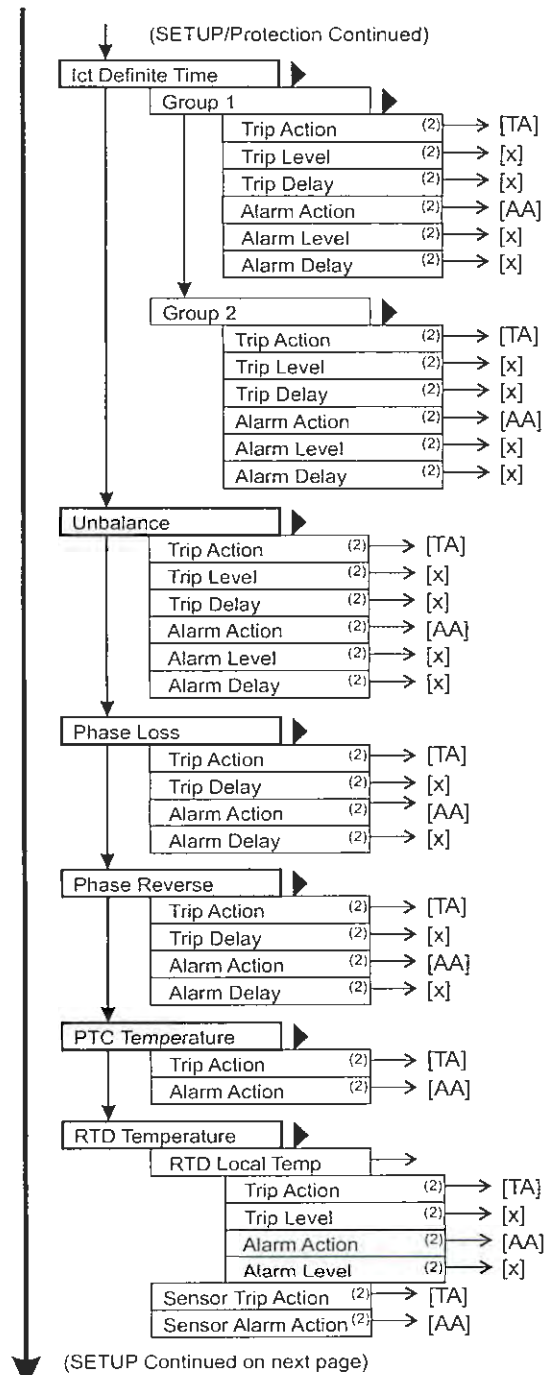
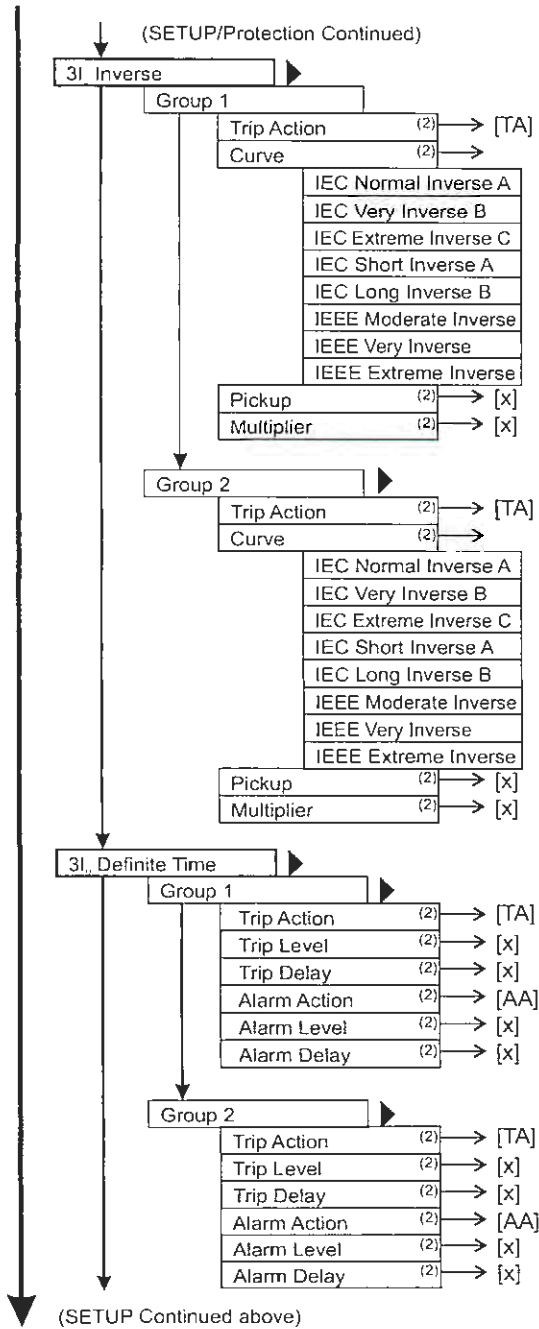
- (1) List indicates possible trips and alarms.
- (2) Password required.
- (3) Lists do not match FPU-32 menu order.
- (4) Locked when current detected.

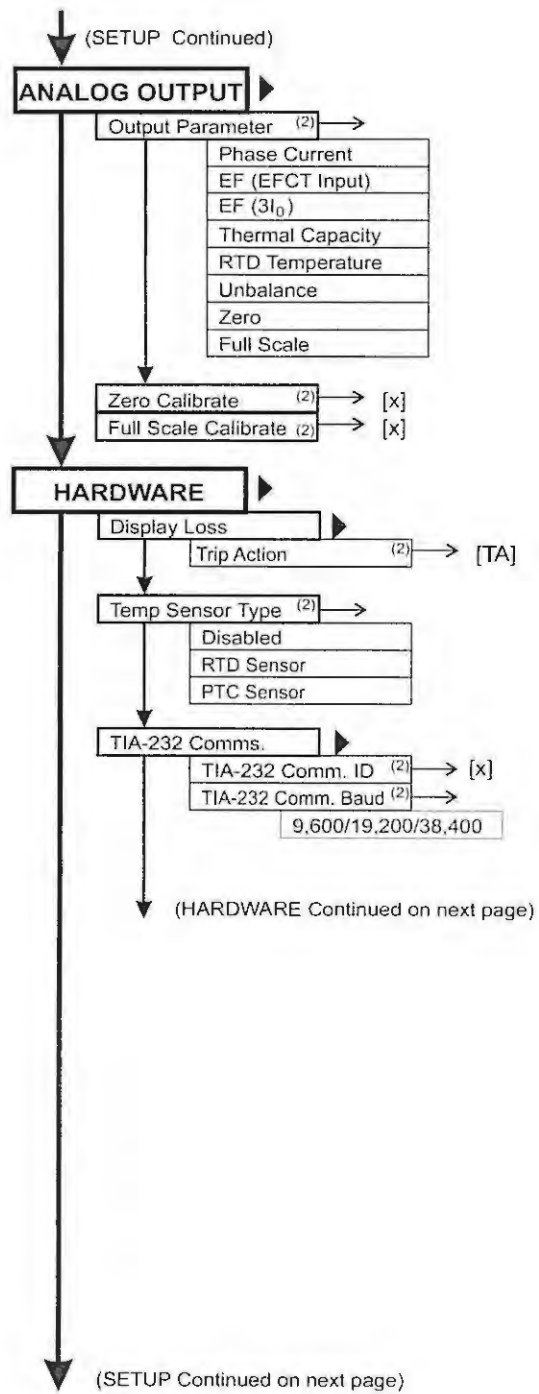
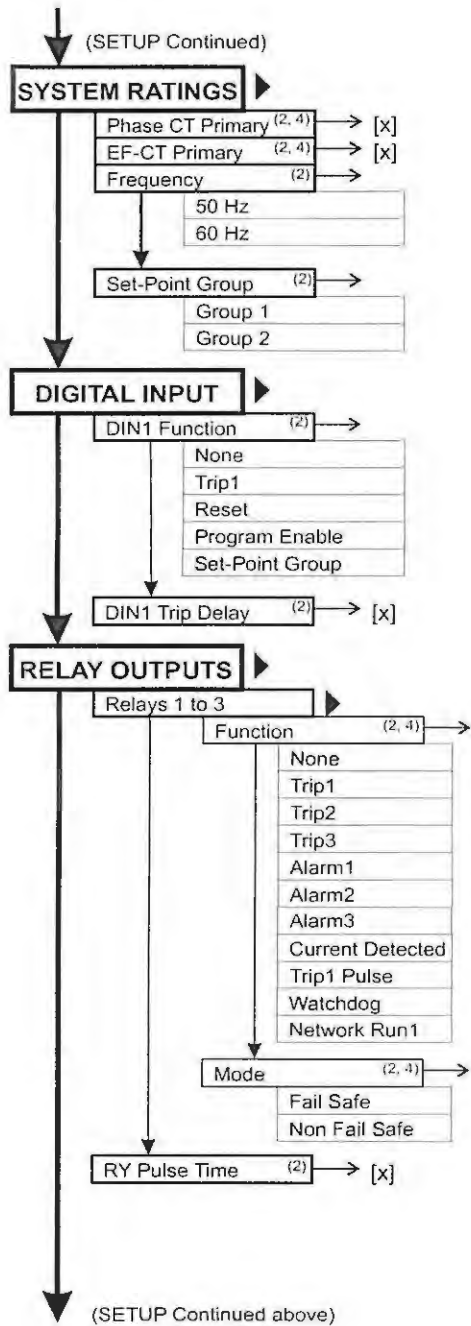
Legend:

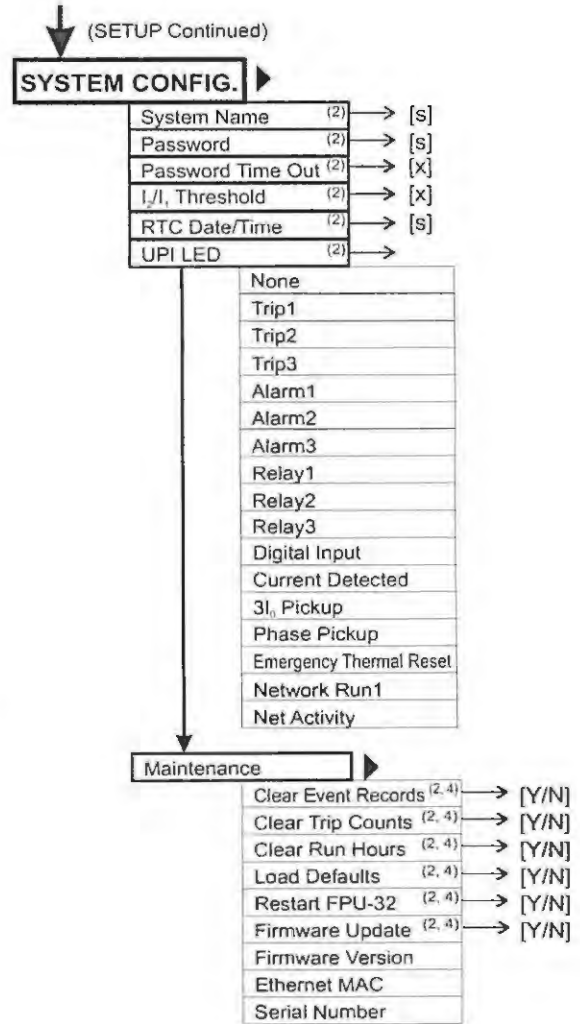
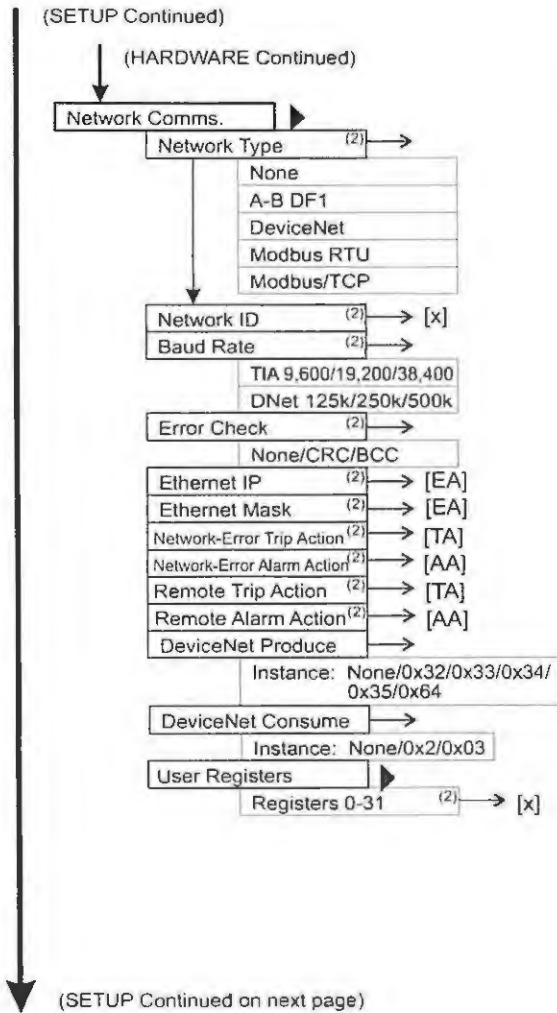
- [x] Enter numeric
- [s] Enter string
- [E/D] Enable/Disable
- [TA] Trip Action: Disable; Trip1; Trip2; Trip3
- [AA] Alarm Action: Disable; Alarm1; Alarm2; Alarm3
- [Y/N] Yes/No
- [EA] Ethernet address











**APPENDIX B
FPU-32 SET-UP RECORD**

Feeder: _____ FPU-32 S/N: _____ Date: _____

Firmware Revision: _____ Ethernet MAC ID: _____

PART I: SYSTEM PARAMETERS

PARAMETER AND SETTINGS	MIN	DEFAULT	MAX	UNIT	PROGRAM SELECTION
System Ratings					
CT Primary (I_p) ⁽¹⁾	1	100.00	5,000	A	
EF-CT Primary (I_e) ⁽¹⁾	1	5.00	5,000	A	
Set-Point Group		Group1			<input type="checkbox"/> Group1 <input type="checkbox"/> Group2
Frequency		60		Hz	<input type="checkbox"/> 50 <input type="checkbox"/> 60
Digital Input					
Function		None			<input type="checkbox"/> None <input type="checkbox"/> Program Enable <input type="checkbox"/> Trip1 <input type="checkbox"/> Set-Point Group <input type="checkbox"/> Reset
Trip Delay	0.01	0.10	100.00	s	
Relay Outputs See Table 4.2 Output-Relay Functions					
Relay 1: Function		Trip1			
Mode		Fail Safe			<input type="checkbox"/> Fail Safe <input type="checkbox"/> Non-Fail Safe
Relay 2: Function		Alarm1			
Mode		Fail Safe			<input type="checkbox"/> Fail Safe <input type="checkbox"/> Non-Fail Safe
Relay 3: Function		None			
Mode		Fail Safe			<input type="checkbox"/> Fail Safe <input type="checkbox"/> Non-Fail Safe
RY Pulse Time	0.05	0.25	10.00	s	
Analog Output See Table 4.4 Analog-Output Parameters					
Output Parameter		Phase Current			
Zero Calibrate		Factory Calibrated			
Full-Scale Calibrate		Factory Calibrated			
HARDWARE					
OPI Display					
OPI-Loss Trip		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
TIA-232 Communications					
TIA-232 Comm ID	0	254	255		
TIA-232 Comm Baud		9,600		bit/s	<input type="checkbox"/> 9,600 <input type="checkbox"/> 38,400 <input type="checkbox"/> 19,200
Temperature Sensor Type		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> PTC Sensor <input type="checkbox"/> RTD Sensor

PARAMETER AND SETTINGS	MIN	DEFAULT	MAX	UNIT	PROGRAM SELECTION
Network Communications					
Network Type		None			<input type="checkbox"/> None <input type="checkbox"/> Modbus TCP <input type="checkbox"/> A-B DF1 <input type="checkbox"/> DeviceNet <input type="checkbox"/> Modbus RTU
Network ID	0	254	255		
Baud Rate		TIA 9600			<input type="checkbox"/> TIA 9600 <input type="checkbox"/> DN125 <input type="checkbox"/> TIA 19k2 <input type="checkbox"/> DN250 <input type="checkbox"/> TIA 38k4 <input type="checkbox"/> DN500
Error Checking (A-B DF1 Only)		Not Selected			<input type="checkbox"/> Not Selected <input type="checkbox"/> BCC <input type="checkbox"/> CRC
Ethernet IP		192.168. 000.001			
Ethernet Mask		255.255. 255.000			
Network-Error Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Network-Error Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
Remote Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Remote Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
User Registers					
User Register 0	0	0	1399		
User Register 1	0	0	1399		
User Register 2	0	0	1399		
User Register 3	0	0	1399		
User Register 4	0	0	1399		
User Register 5	0	0	1399		
User Register 6	0	0	1399		
User Register 7	0	0	1399		
User Register 8	0	0	1399		
User Register 9	0	0	1399		
User Register 10	0	0	1399		
User Register 11	0	0	1399		
User Register 12	0	0	1399		
User Register 13	0	0	1399		
User Register 14	0	0	1399		
User Register 15	0	0	1399		
User Register 16	0	0	1399		
User Register 17	0	0	1399		
User Register 18	0	0	1399		
User Register 19	0	0	1399		
User Register 20	0	0	1399		
User Register 21	0	0	1399		
User Register 22	0	0	1399		
User Register 23	0	0	1399		
User Register 24	0	0	1399		

PARAMETER AND SETTINGS	MIN	DEFAULT	MAX	UNIT	PROGRAM SELECTION
User Register 25	0	0	1399		
User Register 26	0	0	1399		
User Register 27	0	0	1399		
User Register 28	0	0	1399		
User Register 29	0	0	1399		
User Register 30	0	0	1399		
User Register 31	0	0	1399		
SYSTEM CONFIG					
System Name	FPU-32				
Password	1111				
Password Timeout	1	10.00	60	min	
I ₂ /I ₁ Threshold	0.05	0.50	0.50		
UPI LED	None			See Table 4.1 UPI LED Functions	

PART II: PROTECTION SET POINTS

FUNCTION & SET POINT	MIN	DEFAULT	MAX	UNIT	PROGRAM SELECTION
Overload – Group1					
I ² t Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
I ² t Alarm Action		Alarm1			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
I ² t Pickup	0.10	1.00	1.25	x I _p	
Hot Factor	0.10	0.50	1.00		
Cooling Factor	0.10	1.00	10.00		
Time Constant	1.00	10.0	60.00	min	
I ² t Alarm level (Per unit based on 100% I ² t)	0.50	0.90	1.00	pu	
Overload – Group2					
I ² t Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
I ² t Alarm Action		Alarm1			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
I ² t Pickup	0.10	1.00	1.25	x I _p	
Hot Factor	0.10	0.50	1.00		
Cooling Factor	0.10	1.00	10.00		
Time Constant	1.00	10.0	60.00	min	
I ² t Alarm level (Per unit based on 100% I ² t)	0.50	0.90	1.00	pu	
Overload Reset Type		Normal			<input type="checkbox"/> Normal <input type="checkbox"/> Rapid <input type="checkbox"/> Auto
Overload Reset Level	0.10	0.30	0.90	pu	

FUNCTION & SET POINT	MIN	DEFAULT	MAX	UNIT	PROGRAM SELECTION
Phase Inverse – Group1					
Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Curve Type		IEC Normal			See Table 5.1
Curve Pickup	0.10	2.00	10.00	$\times I_p$	
Curve Multiplier	0.05	0.20	1.00		
Phase Inverse – Group2					
Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Curve Type		IEC Normal			See Table 5.1
Curve Pickup	0.10	2.00	10.0	$\times I_p$	
Curve Multiplier	0.05	0.20	1.00		
Phase Definite Time – Group1					
Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Trip Level	0.10	10.00	15.00	$\times I_p$	
Trip Delay	0.00	0.05	10.00	s	
Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
Alarm Level	0.10	10.00	15.00	$\times I_p$	
Alarm Delay	0.00	0.05	10.00	s	
Phase Definite Time – Group2					
Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Trip Level	0.10	10.00	15.00	$\times I_p$	
Trip Delay	0.00	0.05	10.00	s	
Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
Alarm Level	0.10	10.00	15.00	$\times I_p$	
Alarm Delay	0.00	0.05	10.00	s	
Earth-Fault 3I₀ Inverse – Group1					
Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Curve Type		IEC Normal			See Table 5.1
Curve Pickup	0.10	2.00	10.00	$\times I_p$	
Curve Multiplier	0.05	0.20	1.00		
Earth-Fault 3I₀ Inverse – Group2					
Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Curve Type		IEC Normal			See Table 5.1
Curve Pickup	0.10	2.00	10.00	$\times I_p$	
Curve Multiplier	0.05	0.20	1.00		

FUNCTION & SET POINT	MIN	DEFAULT	MAX	UNIT	PROGRAM SELECTION
Earth-Fault 3I₀ Definite Time – Group1					
Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Trip Level	0.10	10.00	15.00	x I _p	
Trip Delay	0.00	0.05	10.00	s	
Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
Alarm Level	0.10	10.00	15.00	x I _p	
Alarm Delay	0.00	0.05	10.00	s	
Earth-Fault 3I₀ Definite Time – Group2					
Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Trip Level	0.10	10.00	15.00	x I _p	
Trip Delay	0.00	0.05	10.00	s	
Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
Alarm Level	0.10	10.00	15.00	x I _p	
Alarm Delay	0.00	0.05	10.00	s	
Earth-Fault CT Input Definite Time – Group1					
Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Trip Level	0.01	0.40	1.00	x I _e	
Trip Delay	0.00	0.25	100.00	s	
Alarm Action		Alarm1			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
Alarm Level	0.01	0.20	1.00	x I _e	
Alarm Delay	0.00	1.00	100.00	s	
Earth-Fault CT Input Definite Time – Group2					
Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Trip Level	0.01	0.40	1.00	x I _e	
Trip Delay	0.00	0.25	100.00	s	
Alarm Action		Alarm1			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
Alarm Level	0.01	0.20	1.00	x I _e	
Alarm Delay	0.00	1.00	100.00	s	
Unbalance					
Trip Action		Trip1			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip1 <input type="checkbox"/> Trip2 <input type="checkbox"/> Trip3
Trip Level (Per unit based on I ₂ /I ₁)	0.05	0.25	1.00	pu	
Trip Delay	1.00	15.00	100.00	s	
Alarm Action		Alarm1			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm2 <input type="checkbox"/> Alarm3
Alarm Level (Per unit based on I ₂ /I ₁)	0.05	0.10	1.00	pu	
Alarm Delay	1.00	10.00	100.00	s	

FUNCTION & SET POINT	MIN	DEFAULT	MAX	UNIT	PROGRAM SELECTION	
Phase Loss						
Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip2	<input type="checkbox"/> Trip1 <input type="checkbox"/> Trip3
Trip Delay	1.00	5.00	100.00	s		
Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm2	<input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm3
Alarm Delay	1.00	2.00	100.00	s		
Phase Reverse						
Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip2	<input type="checkbox"/> Trip1 <input type="checkbox"/> Trip3
Trip Delay	1.00	5.00	100.00	s		
Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm2	<input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm3
Alarm Delay	1.00	2.00	100.00	s		
PTC Temperature						
Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip2	<input type="checkbox"/> Trip1 <input type="checkbox"/> Trip3
Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm2	<input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm3
RTD Temperature						
Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip2	<input type="checkbox"/> Trip1 <input type="checkbox"/> Trip3
Trip Level	40.00	200.00	230.00	°C		
Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm2	<input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm3
Alarm Level	40.00	130.00	230.00	°C		
RTD-Sensor-Error Trip Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Trip2	<input type="checkbox"/> Trip1 <input type="checkbox"/> Trip3
RTD-Sensor-Error Alarm Action		Disabled			<input type="checkbox"/> Disabled <input type="checkbox"/> Alarm2	<input type="checkbox"/> Alarm1 <input type="checkbox"/> Alarm3

⁽¹⁾ Locked when current is detected.

APPENDIX C FPU-32 TIA-232 MODBUS PROTOCOL

C.1 PROTOCOL

The FPU-32 implements the Modbus[®] RTU protocol as described in the Gould Modbus Reference Guide, Publication PI-MBUS-300 Rev. B.

Only the master can initiate a message transaction. Messages can be addressed to individual slaves or they can be broadcast messages. Broadcast messages are executed on the slaves but unlike individually addressed messages, the slaves do not generate a reply message.

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C.1.1 PROTOCOL SETUP

Setup options are available in the *Setup | Hardware | Local Comms* menu. Select *Local Comm ID* and *Local Comm Baud*.

C.2 MESSAGE SYNCHRONIZATION

Message synchronization is accomplished by detection of an idle communication line. The communication line is considered idle when no communication exists for an equivalent delay of 3.5 characters.

The first byte received after idle-line detection is interpreted as the address byte of the next message. Message bytes must be transmitted in a continuous stream until the complete message has been sent. If a delay of more than 3.5 characters exists within the message, the message is discarded.

Response messages from the FPU-32 are delayed by at least 3.5 character delays.

C.3 ERROR CHECKING

Modbus[®] RTU uses a 16-bit cyclic redundancy check (CRC). The error check includes all of the message bytes, starting with the first address byte.

When a CRC error is detected, the message is discarded and there will be no response.

If the CRC check is correct but the internal data in the message is not correct, the FPU-32 will respond with an exception response code.

C.4 FUNCTION CODES SUPPORTED

The FPU-32 Modbus Protocol supports the following function codes:

- Read Holding Registers (Function Code 3)

- Read Input Registers (Function Code 4)
- Write Single Register (Function Code 6)
- Write Multiple Registers (Function Code 16)
- Command Instruction (Function Code 5)

Function Codes 3 and 4 perform the same function in the FPU-32.

Registers in Modbus start at 40001 decimal and the register address generated for this register is 0.

C.4.1 APPLICATION LAYER

The hexadecimal system is used. Value representations use the "C" convention. For hexadecimal, 0x precedes the value.

C.4.2 READ INPUT/HOLDING REGISTERS (CODE 04/03)

The first byte of the read message is the slave address. The second byte is the function code. Bytes three and four indicate the starting register. The next two bytes specify the number of 16-bit registers to read. The last two bytes contain the CRC code for the message.

TABLE C.1 READ REGISTERS (CODE 04/03)

HEX BYTE	DESCRIPTION
Byte 1	Slave Address
Byte 2	Function Code
Byte 3	MSB Register Address
Byte 4	LSB Register Address
Byte 5	MSB Number of Registers
Byte 6	LSB Number of Registers
Byte 7	LSB CRC
Byte 8	MSB CRC

The two-byte values of starting register and number of registers to read are transmitted with the high-order byte followed by the low-order byte.

The CRC value is sent with the LSB followed by the MSB.

The following message will obtain the value of register 1 (Modbus 40002) from slave 1. Note that Modbus registers are numbered from zero (40001 = zero, 40002 = one, etc.):

0x01 | 0x03 | 0x00 | 0x01 | 0x00 | 0x01 | 0x15 | 0xCA

The addressed slave responds with its address and Function Code 3, followed by the information field. The information field contains an 8-bit byte count and the 16-bit data from the slave. The byte count specifies the number of bytes of data in the information field. The data in the information field consists of 16-bit data arranged so that the MSB is followed by the LSB.

NOTE: The maximum number of registers per read is 100 (200 bytes).

C.4.3 WRITE TO REGISTER

Function Code 6 or 16 is used to make set-point changes.

C.4.3.1 WRITE SINGLE REGISTER (CODE 6)

The function code format for writing a single register is shown in Table C.2.

The message consists of the slave address followed by the Function Code 6 and two 16-bit values. The first 16-bit value specifies the register to be modified and the second value is the 16-bit data.

Provided no errors occurred, the slave will re-send the original message to the master. The response message is returned only after the command has been executed by the slave.

The following message will set register 3 to 300 in slave 5:

0x05 | 0x06 | 0x00 | 0x03 | 0x01 | 0x2C | 0x78 | 0x03

TABLE C.2 WRITE SINGLE REGISTER (CODE 6)

HEX BYTE	DESCRIPTION
Byte 1	Slave Address
Byte 2	Function Code
Byte 3	MSB Register Address
Byte 4	LSB Register Address
Byte 5	MSB of Data
Byte 6	LSB of Data
Byte 7	LSB of CRC
Byte 8	MSB of CRC

C.4.3.2 WRITE MULTIPLE REGISTERS (CODE 16)

The function-code format in Table C.3 can be used for writing single or multiple registers.

TABLE C.3 WRITE MULTIPLE REGISTERS (CODE 16)

BYTE #	DESCRIPTION
Byte 1	Slave Address
Byte 2	Function Code
Byte 3	MSB Register Address
Byte 4	LSB Register Address
Byte 5	MSB of Quantity
Byte 6	LSB of Quantity
Byte 7	Byte Count
.	MSB of Data
.	LSB of Data
.	LSB of CRC
Byte n	MSB of CRC

The slave will reply with the slave address, function code, register address, and the quantity followed by the CRC code for a total of 8 bytes.

NOTE: The maximum number of registers per write is 100 (200 bytes).

C.4.4 COMMAND INSTRUCTION (CODE 5)

Modbus Function Code 5 (Force Single Coil) is used to issue commands to the FPU-32. The format for the message is listed in Table C.4 and the command code actions and corresponding coil number are listed in Table C.5.

TABLE C.4 COMMAND FORMAT (CODE 5)

HEX BYTE	DESCRIPTION
Byte 1	Slave Address
Byte 2	Function Code
Byte 3	MSB of Command Code
Byte 4	LSB of Command Code
Byte 5	Fixed at 0xFF
Byte 6	Fixed at 00
Byte 7	LSB of CRC
Byte 8	MSB of CRC

TABLE C.5 SUPPORTED COMMANDS

COMMAND CODE	COIL NUMBER	ACTION
0x0003	4	Reset Trips
0x0004	5	Set Real-Time Clock
0x0005	6	Clear Data-Logging Records
0x0006	7	Clear Trip Counters
0x0008	9	Clear Running Hours
0x0009	10	Emergency I ² t and Trip Reset
0x000D	14	Remote/Net Trip Set
0x000E	15	Remote/Net Trip Clear
0x000F	16	Remote/Net Alarm Set
0x0010	17	Remote/Net Alarm Clear
0x0011	18	Run 1 Set
0x0012	19	Run 1 Clear

Except for a broadcast address, the slave will return the original packet to the master.

C.4.5 COMMAND INSTRUCTIONS USING WRITE COMMANDS

For PLC's not supporting Function Code 5, commands can be issued using Write Single Register (Code 6) and Write Multiple Register (Code 16).

Commands are written to FPU-32 register 6 (Modbus register 40007). Supported commands are listed in the COMMAND CODE column in Table C.5.

When using the Write Multiple Registers function code, the write should be to the single FPU-32 Register 6. If multiple registers are written starting at FPU-32 Register 6, the first data element will be interpreted as the command code but no other registers will be written. If the command is successful, the FPU-32 will return a valid response message.

C.4.6 EXCEPTION RESPONSES

The FPU-32 supports the following exception responses:

- Boundry Error (1)—Applies to writes of 32-bit values. The high-order word must be written first followed by the write to the low-order word. If this sequence is not followed, a Boundry Error is returned and the value will not be stored. This does not apply on read requests.
- Address Error (2)—All accesses to communication registers must be within the specified address range or the Address Error code is returned.
- Command Error (3)—This error code is returned if the command code is not supported.
- Illegal Function Code (4)—The function code (Byte 2) is not supported.

The exception message consists of the slave address followed by a retransmission of the original function code. The function code will have the most-significant bit set to indicate an error. The 8-bit byte following the function code is the exception response code. The 16-bit CRC is at the end of the message.

C.5 FPU-32 DATABASE

Appendix D contains the Modbus Register in the Communications Database Table. The table starts at register 0 (Modbus 40001) and each register is 16-bits wide. Types "long" and "float" are 32-bit values. For both long and float types, the low-order word is transmitted first followed by the high-order word. Word values have the high byte followed by the low byte. Float types as per IEEE 754 Floating-Point Standard. All bytes of long and float types must be written using one message or an error will result. This does not apply for read commands.

C.5.1 DATA RECORDS

Only one event record can be read at a time. Record data is for the record indicated by the Record Selector. To select a record, write the record number to Record Selector and then read the values in the record. Record Head points to the next available record. The last event record captured is at Record Head minus one.

Both Record Selector and Record Head values are in the range of 0 to 99. Values outside this range will select record 0.

C.5.2 CUSTOM DATA ACCESS

Data access can be customized with the User-Defined Registers and the User-Data Registers.

User-Defined Registers are located in non-volatile memory and contain the register numbers from which data is required. To access the data, read the corresponding User-Data Registers.

The format of the User Data is a function of the corresponding register entered in the User-Defined-Register area.

C.6 SPECIFICATIONS

Interface.....	Non-Isolated RS/EIA/TIA-232, RJ-45
Protocol.....	Modbus [®] RTU
Baud Rate.....	9,600, 19,200, or 38,400 bit/s
Bit Format.....	8 bits, no parity, one stop bit

NOTE: A network communication interface has priority over the TIA-232 interface. To minimize TIA-232 errors when both network and TIA-232 communications are used, set the TIA-232 baud rate to 9,600 bit/s.

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**APPENDIX D
COMMUNICATIONS DATABASE TABLE**

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
Model Information							
0	40001	01-01-03	3:0	Model Code	Read Only	302	T3
1	40002	01-01-64	3:1	Software Version	Read Only		T3
2	40003	01-01-06	3:2	Serial Number	Read Only		T2 (low)
3	40004		3:3				T2 (high)
6	40007	29-01-64	3:6	Command Register	Write Only		T72
7	40008	29-01-77	3:7	Set-Point Group	R/W	0 – 1	T81
Overload Group 1							
8	40009	2C-01-64	3:8	I ² t Trip Action	R/W	0 – 7	T42
9	40010	2C-01-65	3:9	I ² t Alarm Action	R/W	0 – 7	T43
11	40012	2C-01-67	3:11	Pickup in per unit of CT rating	R/W	0.1 – 1.25 x I _p	T1 (low)
12	40013		3:12				T1 (high)
15	40016	2C-01-69	3:15	Hot Factor	R/W	0.1 – 1.0	T1 (low)
16	40017		3:16				T1 (high)
17	40018	2C-01-6A	3:17	Cooling Factor	R/W	0.1 – 10	T1 (low)
18	40019		3:18				T1 (high)
19	40020	2C-01-6B	3:19	Time Constant	R/W	1 – 60 min	T1 (low)
20	40021		3:20				T1 (high)
21	40022	2C-01-6C	3:21	I ² t Alarm Level	R/W	0.5 – 1.0	T1 (low)
22	40023		3:22				T1 (high)
Overload Group 2							
26	40027	2C-02-64	3:26	I ² t Trip Action	R/W	0 – 7	T42
27	40028	2C-02-65	3:27	I ² t Alarm Action	R/W	0 – 7	T43
28							
29	40030	2C-02-67	3:29	Pickup in per unit of CT rating	R/W	0.1 – 1.25 x I _p	T1 (low)
30	40031		3:30				T1 (high)
31							
32							
33	40034	2C-02-69	3:33	Hot Factor	R/W	0.1 – 1.0	T1 (low)
34	40035		3:34				T1 (high)
35	40036	2C-02-6A	3:35	Cooling Factor	R/W	0.1 – 10	T1 (low)
36	40037		3:36				T1 (high)
37	40038	2C-02-6B	3:37	Time Constant	R/W	1 – 60 min	T1 (low)
38	40039		3:38				T1 (high)
39	40040	2C-02-6C	3:39	I ² t Alarm Level	R/W	0.5 – 1.0	T1 (low)
40	40041		3:40				T1 (high)

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
Overload Reset							
44	40045	2C-00-64	3:44	Overload Reset Type	R/W	0 – 2	T38
45	40046	2C-00-65	3:45	Overload Reset Level	R/W	0.1 – 0.9	T1(low)
46	40047		3:46				T1(high)
Phase Inverse Group 1							
50	40051	69-01-01	3:50	Trip Action	R/W	0 – 7	T42
51	40052	69-01-02	3:51	Curve Type	R/W	0 – 7	T73
52	40053	69-01-03	3:52	Time Multiplier	R/W	0.05 – 1.0	T1(low)
53	40054		3:53				T1(high)
54	40055	69-01-04	3:54	Pickup in pu of CT Rating	R/W	0.1 – 10 x I _p	T1(low)
55	40056		3:55				T1(high)
Phase Inverse Group 2							
60	40061	69-02-01	3:60	Trip Action	R/W	0 – 7	T42
61	40062	69-02-02	3:61	Curve Type	R/W	0 – 7	T73
62	40063	69-02-03	3:62	Time Multiplier	R/W	0.05 – 1.0	T1(low)
63	40064		3:63				T1(high)
64	40065	69-02-04	3:64	Pickup in pu of CT Rating	R/W	0.1 – 10 x I _p	T1(low)
65	40066		3:65				T1(high)
Phase Definite Time Group 1							
70	40071	64-01-01	3:70	Trip Action	R/W	0 – 7	T42
71	40072	64-01-02	3:71	Alarm Action	R/W	0 – 7	T43
72	40073	64-01-03	3:72	Trip Level	R/W	0.1 – 15 x I _p	T1(low)
73	40074		3:73				T1(high)
74	40075	64-01-04	3:74	Trip Delay	R/W	0 – 10 s	T1(low)
75	40076		3:75				T1(high)
76	40077	64-01-05	3:76	Alarm Level	R/W	0.1 – 15 x I _p	T1(low)
77	40078		3:77				T1(high)
78	40079	64-01-06	3:78	Alarm Delay	R/W	0 – 10 s	T1(low)
79	40080		3:79				T1(high)
Phase Definite Time Group 2							
84	40085	64-02-01	3:84	Trip Action	R/W	0 – 7	T42
85	40086	64-02-02	3:85	Alarm Action	R/W	0 – 7	T43
86	40087	64-02-03	3:86	Trip Level	R/W	0.1 – 15 x I _p	T1(low)
87	40088		3:87				T1(high)
88	40089	64-02-04	3:88	Trip Delay	R/W	0 – 10 s	T1(low)
89	40090		3:89				T1(high)
90	40091	64-02-05	3:90	Alarm Level	R/W	0.1 – 15 x I _p	T1(low)
91	40092		3:91				T1(high)
92	40093	64-02-06	3:92	Alarm Delay	R/W	0 – 10 s	T1(low)
93	40094		3:93				T1(high)

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
Earth-Fault 3I₀ Inverse Group 1							
100	40101	69-03-01	3:100	Trip Action	R/W	0 – 7	T42
101	40102	69-03-02	3:101	Curve Type	R/W	0 – 7	T73
102	40103	69-03-03	3:102	Time Multiplier	R/W	0.05 – 1.0	T1(low)
103	40104		3:103				T1(high)
104	40105	69-03-04	3:104	Pickup in pu of CT Rating	R/W	0.1 – 10 x I _p	T1(low)
105	40106		3:105				T1(high)
Earth-Fault 3I₀ Inverse Group 2							
110	40111	69-04-01	3:110	Trip Action	R/W	0 – 7	T42
111	40112	69-04-02	3:111	Curve Type	R/W	0 – 7	T73
112	40113	69-04-03	3:112	Time Multiplier	R/W	0.05 – 1.0	T1(low)
113	40114		3:113				T1(high)
114	40115	69-04-04	3:114	Pickup in pu of CT Rating	R/W	0.1 – 10 x I _p	T1(low)
115	40116		3:115				T1(high)
Earth-Fault 3I₀ Definite Time Group 1							
120	40121	64-03-01	3:120	Trip Action	R/W	0 – 7	T42
121	40122	64-03-02	3:121	Alarm Action	R/W	0 – 7	T43
122	40123	64-03-03	3:122	Trip Level	R/W	0.1 – 15 x I _p	T1(low)
123	40124		3:123				T1(high)
124	40125	64-03-04	3:124	Trip Delay	R/W	0 – 10 s	T1(low)
125	40126		3:125				T1(high)
126	40127	64-03-05	3:126	Alarm Level	R/W	0.1 – 15 x I _p	T1(low)
127	40128		3:127				T1(high)
128	40129	64-03-06	3:128	Alarm Delay	R/W	0 – 10 s	T1(low)
129	40130		3:129				T1(high)
Earth-Fault 3I₀ Definite Time Group 2							
136	40137	64-04-01	3:136	Trip Action	R/W	0 – 7	T42
137	40138	64-04-02	3:137	Alarm Action	R/W	0 – 7	T43
138	40139	64-04-03	3:138	Trip Level	R/W	0.1 – 15 x I _p	T1(low)
139	40140		3:139				T1(high)
140	40141	64-04-04	3:140	Trip Delay	R/W	0 – 10 s	T1(low)
141	40142		3:141				T1(high)
142	40143	64-04-05	3:142	Alarm Level	R/W	0.1 – 15 x I _p	T1(low)
143	40144		3:143				T1(high)
144	40145	64-04-06	3:144	Alarm Delay	R/W	0 – 10 s	T1(low)
145	40146		3:145				T1(high)

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
Earth-Fault CT-Input Definite Time Group 1							
150	40151	64-05-01	3:150	Trip Action	R/W	0 – 7	T42
151	40152	64-05-02	3:151	Alarm Action	R/W	0 – 7	T43
152	40153	64-05-03	3:152	Trip Level	R/W	0.01 – 1.0 x I _c	T1(low)
153	40154		3:153				T1(high)
154	40155	64-05-04	3:154	Trip Delay	R/W	0 – 100 s	T1(low)
155	40156		3:155				T1(high)
156	40157	64-05-05	3:156	Alarm Level	R/W	0.01 – 1.0 x I _c	T1(low)
157	40158		3:157				T1(high)
158	40159	64-05-06	3:158	Alarm Delay	R/W	0 – 100 s	T1(low)
159	40160		3:159				T1(high)
Earth-Fault CT-Input Definite Time Group 2							
166	40167	64-06-01	3:166	Trip Action	R/W	0 – 7	T42
167	40168	64-06-02	3:167	Alarm Action	R/W	0 – 7	T43
168	40169	64-06-03	3:168	Trip Level	R/W	0.01 – 1.0 x I _c	T1(low)
169	40170		3:169				T1(high)
170	40171	64-06-04	3:170	Trip Delay	R/W	0 – 100 s	T1(low)
171	40172		3:171				T1(high)
172	40173	64-06-05	3:172	Alarm Level	R/W	0.01 – 1.0 x I _c	T1(low)
173	40174		3:173				T1(high)
174	40175	64-06-06	3:174	Alarm Delay	R/W	0 – 100 s	T1(low)
175	40176		3:175				T1(high)
Current Unbalance							
180	40181	64-07-01	3:180	Trip Action	R/W	0 – 7	T42
181	40182	64-07-02	3:181	Alarm Action	R/W	0 – 7	T43
182	40183	64-07-03	3:182	Trip Level	R/W	0.05 – 1.0	T1(low)
183	40184		3:183				T1(high)
184	40185	64-07-04	3:184	Trip Delay	R/W	1 – 100 s	T1(low)
185	40186		3:185				T1(high)
186	40187	64-07-05	3:186	Alarm Level	R/W	0.05 – 1.0	T1(low)
187	40188		3:187				T1(high)
188	40189	64-07-06	3:188	Alarm Delay	R/W	1 – 100 s	T1(low)
189	40190		3:189				T1(high)
Phase Reverse							
192	40193	64-08-01	3:192	Trip Action	R/W	0 – 7	T42
193	40194	64-08-02	3:193	Alarm Action	R/W	0 – 7	T43
194	40195	64-08-04	3:194	Trip Delay	R/W	1 – 100 s	T1(low)
195	40196		3:195				T1(high)
196	40197	64-08-06	3:196	Alarm Delay	R/W	1 – 100 s	T1(low)
197	40198		3:197				T1(high)

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
Phase Loss							
198	40199	64-09-01	3:198	Trip Action	R/W	0 – 7	T42
199	40200	64-09-02	3:199	Alarm Action	R/W	0 – 7	T43
200	40201	64-09-04	3:200	Trip Delay	R/W	1 – 100 s	T1(low)
201	40202		3:201				T1(high)
202	40203	64-09-06	3:202	Alarm Delay	R/W	1 – 100 s	T1(low)
203	40204		3:203				T1(high)
Remote/Network Trip							
230	40231	29-01-81	3:230	Trip Action	R/W	0 – 7	T42
231	40232	29-01-82	3:231	Alarm Action	R/W	0 – 7	T43
System Ratings							
250	40251	29-01-87	3:250	Frequency	R/W	0 – 1	T10
251	40252	29-01-85	3:251	Phase CT Primary	R/W	1 – 5,000 Λ	T1(low)
252	40253		3:252				T1(high)
253	40254	29-01-86	3:253	Earth-Fault CT Primary	R/W	1 – 5,000 Λ	T1(low)
254	40255		3:254				T1(high)
255	40256	29-01-95	3:255	Unbalance Current Threshold	R/W	0.1 – 0.5 $\times I_p$	T1(low)
256	40257		3:256				T1(high)
Operator Interface							
270	40271	29-01-7D	3:270	Display-Loss Trip Action	R/W	0 – 7	T42
271	40272	01-01-67	3:271	Password Timeout	R/W	1 – 60 min	T1(low)
272	40273		3:272				T1(high)
273	40274	29-01-84	3:273	UPI LED Assignment	R/W	0 – 17	T74
274	40275		3:274	Default Menu	R/W	0 - 9	T97
Digital Input							
280	40281	29-01-76	3:280	Function	R/W	0 – 4	T75
281	40282	29-01-79	3:281	Trip Delay	R/W	0.01 – 100 s	T1(low)
282	40283		3:282				T1(high)
Relay Output Function							
334	40335	29-01-6F	3:334	Relay 1 Output Function	R/W	0 – 12	T76
335	40336	29-01-70	3:335	Relay 1 Mode	R/W	0 – 1	T14
336	40337	29-01-71	3:336	Relay 2 Output Function	R/W	0 – 12	T76
337	40338	29-01-72	3:337	Relay 2 Mode	R/W	0 – 1	T14
338	40339	29-01-73	3:338	Relay 3 Output Function	R/W	0 – 12	T76
339	40340	29-01-74	3:339	Relay 3 Mode	R/W	0 – 1	T14
340	40341	29-01-75	3:340	Relay Pulse Time	R/W	0.05 – 10 s	T1(low)
341	40342		3:341				T1(high)
Analog Output							
372	40373	29-01-7B	3:372	Analog Output Parameter	R/W	0 – 11	T77

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
Network Communication							
374	40375	05-00-65	3:374	DeviceNet Producing Instance	R/W	0 – 5	T84
375	40376	05-00-64	3:375	DeviceNet Consuming Instance	R/W	0 – 2	T85
376	40377		3:376	Network Type	R/W	0 – 6	T65
377	40378		3:377	Network Baud	R/W	0 – 5	T69
378	40379		3:378	Network Error Check	R/W	0 – 2	T18
379	40380		3:379	Network ID (Slave ID)	R/W	0 – 255	T1(low)
380	40381		3:380				T1(high)
381	40382	03-01-64	3:381	Network Trip Action	R/W	0 – 7	T42
382	40383	03-01-65	3:382	Network Alarm Action	R/W	0 – 7	T43
Local TIA-232 Communication							
383	40384		3:383	TIA-232 Baud Rate	R/W	0 – 2	T66
384	40385		3:384	TIA-232 ID	R/W	0 – 255	T1(low)
385	40386		3:385				T1(high)
RTD Sensor							
388	40389	29-01-96	3:388	RTD-Sensor-Error Trip Action	R/W	0 – 7	T42
389	40390	29-01-97	3:389	RTD-Sensor-Error Alarm Action	R/W	0 – 7	T43
PTC Temperature							
560	40561	29-01-7F	4:170	Temperature Sensor Type	R/W	0 – 2	T68
561	40562	64-0A-01	4:171	Trip Action	R/W	0 – 7	T42
562	40563	64-0A-02	4:172	Alarm Action	R/W	0 – 7	T43
RTD Temperature							
563	40564	64-0B-01	4:173	Trip Action	R/W	0 – 7	T42
564	40565	64-0B-03	4:174	Trip Level	R/W	40 – 230 °C	T1(low)
565	40566		4:175				T1(high)
566	40567	64-0B-05	4:176	Alarm Level	R/W	40 – 230 °C	T1(low)
567	40568		4:177				T1(high)
568	40569	64-0B-02	4:178	Alarm Action	R/W	0 – 7	T43
Real Time Clock Reading							
574	40575	66-01-01	5:0	RTC Date	Read Only		T23(low)
575	40576		5:1				T23(high)
576	40577	66-01-02	5:2	RTC Time	Read Only		T24(low)
577	40578		5:3				T24(high)
Character Strings (10 words, 20 characters)							
580	40581	66-01-03	5:6	Clock Setting	R/W		T31
590	40591	01-01-66	5:16	Password Setting. (4 characters)	R/W		T22
600	40601	01-01-65	5:26	System Name	R/W		T22

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
Analog Output Calibration							
856	40857		5:282	Zero Calibration Value	R/W	0-1,000	T1(low)
857	40858		5:283				T1(high)
858	40859		5:284	Full-Scale Calibration Value	R/W	0-1,000	T1(low)
859	40860		5:285				T1(high)
Meter Values							
860	40861	29-01-88	6:0	I_a (A)	Read Only		T1(low)
861	40862		6:1				T1(high)
862	40863	29-01-89	6:2	I_b (A)	Read Only		T1(low)
863	40864		6:3				T1(high)
864	40865	29-01-8A	6:4	I_c (A)	Read Only		T1(low)
865	40866		6:5				T1(high)
866	40867	29-01-8B	6:6	Earth Leakage from CT (A)	Read Only		T1(low)
867	40868		6:7				T1(high)
868	40869	29-01-8C	6:8	Earth Leakage $3I_0$ (A)	Read Only		T1(low)
869	40870		6:9				T1(high)
870	40871	29-01-8D	6:10	Positive-Sequence Current (pu)	Read Only		T1(low)
871	40872		6:11				T1(high)
872	40873	29-01-8E	6:12	Negative-Sequence Current (pu)	Read Only		T1(low)
873	40874		6:13				T1(high)
874	40875	29-01-8F	6:14	Unbalance (pu)	Read Only		T1(low)
875	40876		6:15				T1(high)
876	40877	29-01-90	6:16	Used I^2t (pu)	Read Only		T1(low)
877	40878		6:17				T1(high)
878	40879	29-01-91	6:18	Trend I^2t (pu)	Read Only		T1(low)
879	40880		6:19				T1(high)
880	40881	29-01-92	6:20	RTD Reading (°C)	Read Only		T1(low)
881	40882		6:21				T1(high)
882	40883	29-01-93	6:22	Overload Trip/Reset Time (min)	Read Only		T1(low)
883	40884		6:23				T1(high)
884	40885	29-01-94	6:24	Running Time (seconds)	Read Only		T2(low)
885	40886		6:25				T2(high)
Event Records							
973	40974	68-01-01	7:0	Number of Records	Read Only	0 – 65535	T3
974	40975	68-01-02	7:1	Record Head (Next record)	Read Only	0 – 99	T3
975	40976	68-01-03	7:2	Record Selector	R/W	0 – 99	T3
976	40977	68-01-04	7:3	Record Date	Read Only		T23(low)
977	40978		7:4				T23(high)
978	40979	68-01-05	7:5	Record Time	Read Only		T24(low)
979	40980		7:6				T24(high)
980	40981	68-01-06	7:7	Record Type	Read Only		T26
981	40982	68-01-07	7:8	Record Trip/Alarm Code	Read Only		T79
982	40983	68-01-08	7:9	I_a Trip Value (A)	Read Only		T1(low)

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
983	40984		7:10				T1(high)
984	40985	68-01-09	7:11	I _b Trip Value (A)	Read Only		T1(low)
985	40986		7:12				T1(high)
986	40987	68-01-0A	7:13	I _c Trip Value (A)	Read Only		T1(low)
987	40988		7:14				T1(high)
988	40989	68-01-0B	7:15	Earth Leakage from CT (A)	Read Only		T1(low)
989	40990		7:16				T1(high)
990	40991	68-01-0C	7:17	Earth Leakage 3I ₀ (A)	Read Only		T1(low)
991	40992		7:18				T1(high)
992	40993	68-01-0D	7:19	Current Unbalance (pu)	Read Only		T1(low)
993	40994		7:20				T1(high)
994	40995	68-01-0E	7:21	Used I ² t (pu)	Read Only		T1(low)
995	40996		7:22				T1(high)
996	40997	68-01-0F		RTD Reading (°C)	Read Only		T1(low)
997	40998						T1(high)
Status							
1096	41097	29-01-65	8:0	Trip and Alarm Summary	Read Only		T67
1097	41098	29-01-66	8:1	FPU-32 Status	Read Only		T78
Trip-and-Alarm Bit Details							
1104	41105	29-01-67	8:8	Bits 0..15 (Bit 0 LSB, Bit 15 MSB) ⁽³⁾	Read Only		T45
1105	41106	29-01-68	8:9	Bits 16..31	Read Only		T46
1106	41107	29-01-69	8:10	Bits 32..47	Read Only		T47
1107	41108	29-01-6A	8:11	Bits 48..63	Read Only		T48
1108	41109	29-01-6B	8:12	Bits 64..79	Read Only		T49
1109	41110	29-01-6C	8:13	Bits 80..95	Read Only		T50
1110	41111	29-01-6D	8:14	Bits 96..111	Read Only		T51
1111	41112	29-01-6E	8:15	Bits 112..127	Read Only		T52
Trip Counters							
1130	41131	2C-01-6D	8:34	Overload Group 1	Read Only		T3
1131	41132	2C-02-6D	8:35	Overload Group 2	Read Only		T3
1132	41133	69-01-05	8:36	Phase Inverse Group 1	Read Only		T3
1133	41134	69-02-05	8:37	Phase Inverse Group 2	Read Only		T3
1134	41135	64-01-07	8:38	Phase Definite Time Group 1	Read Only		T3
1135	41136	64-02-07	8:39	Phase Definite Time Group 2	Read Only		T3
1136	41137	69-03-05	8:40	EF 3I ₀ Inverse Group 1	Read Only		T3
1137	41138	69-04-05	8:41	EF 3I ₀ Inverse Group 2	Read Only		T3
1138	41139	64-03-07	8:42	3I ₀ Definite Time Group 1	Read Only		T3
1139	41140	64-04-07	8:43	3I ₀ Definite Time Group 2	Read Only		T3
1140	41141	64-05-07	8:44	EF CT Definite Time Group 1	Read Only		T3
1141	41142	64-06-07	8:45	EF CT Definite Time Group 2	Read Only		T3
1142	41143	64-07-07	8:46	Current Unbalance	Read Only		T3

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
1143	41144	64-08-07	8:47	Phase Reverse	Read Only		T3
1144	41145	64-09-07	8:48	Phase Loss	Read Only		T3
1145	41146	29-01-7A	8:49	Digital Input	Read Only		T3
1146	41147	64-0B-07	8:50	RTD Temperature	Read Only		T3
1147	41148	64-0A-07	8:51	PTC	Read Only		T3
1148	41149	29-01-80	8:52	RTD Sensor	Read Only		T3
1184	41185		8:88	Non-Volatile Enum Error	Read Only		T3
1185	41186		8:89	Non-Volatile Number Error	Read Only		T3
1186	41187		8:90	Non-Volatile String Error	Read Only		T3
1187	41188		8:91	Non-Volatile Event Record Error	Read Only		T3
1188	41189		8:92	Non-Volatile Thermal Error	Read Only		T3
1189	41190	29-01-7E	8:93	Operator Interface Error	Read Only		T3
1190	41191		8:94	DSP Error	Read Only		T3
1191	41192	3-01-66	8:95	Communication Fault	Read Only		T3
1192	41193	29-01-83	8:96	Remote Trip	Read Only		T3
Ethernet							
1280	41281		9:70	IP Address	R/W		T22
1290	41291		9:80	Address Mask	R/W		T22
1300	41301		9:90	Gateway Address	R/W		T22
1310	41311		9:100	MAC Address	Read Only		T22
User-Defined Registers							
1400	41401	67-01-01	9:190	User Register 0	R/W		T3
1401	41402	67-01-02	9:191	User Register 1	R/W		T3
1402	41403	67-01-03	9:192	User Register 2	R/W		T3
1403	41404	67-01-04	9:193	User Register 3	R/W		T3
1404	41405	67-01-05	9:194	User Register 4	R/W		T3
1405	41406	67-01-06	9:195	User Register 5	R/W		T3
1406	41407	67-01-07	9:196	User Register 6	R/W		T3
1407	41408	67-01-08	9:197	User Register 7	R/W		T3
1408	41409	67-01-09	9:198	User Register 8	R/W		T3
1409	41410	67-01-0A	9:199	User Register 9	R/W		T3
1410	41411	67-01-0B	9:200	User Register 10	R/W		T3
1411	41412	67-01-0C	9:201	User Register 11	R/W		T3
1412	41413	67-01-0D	9:202	User Register 12	R/W		T3
1413	41414	67-01-0E	9:203	User Register 13	R/W		T3
1414	41415	67-01-0F	9:204	User Register 14	R/W		T3
1415	41416	67-01-10	9:205	User Register 15	R/W		T3
1416	41417	67-01-11	9:206	User Register 16	R/W		T3
1417	41418	67-01-12	9:207	User Register 17	R/W		T3
1418	41419	67-01-13	9:208	User Register 18	R/W		T3
1419	41420	67-01-14	9:209	User Register 19	R/W		T3

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
1420	41421	67-01-15	9:210	User Register 20	R/W		T3
1421	41422	67-01-16	9:211	User Register 21	R/W		T3
1422	41423	67-01-17	9:212	User Register 22	R/W		T3
1423	41424	67-01-18	9:213	User Register 23	R/W		T3
1424	41425	67-01-19	9:214	User Register 24	R/W		T3
1425	41426	67-01-1A	9:215	User Register 25	R/W		T3
1426	41427	67-01-1B	9:216	User Register 26	R/W		T3
1427	41428	67-01-1C	9:217	User Register 27	R/W		T3
1428	41429	67-01-1D	9:218	User Register 28	R/W		T3
1429	41430	67-01-1E	9:219	User Register 29	R/W		T3
1430	41431	67-01-1F	9:220	User Register 30	R/W		T3
1431	41432	67-01-20	9:221	User Register 31	R/W		T3
User Data							
1432	41433		9:222	User Register 0 Data	Read Only	<i>Range and Type defined by user register value</i>	
1433	41434		9:223	User Register 1 Data	Read Only		
1434	41435		9:224	User Register 2 Data	Read Only		
1435	41436		9:225	User Register 3 Data	Read Only		
1436	41437		9:226	User Register 4 Data	Read Only		
1437	41438		9:227	User Register 5 Data	Read Only		
1438	41439		9:228	User Register 6 Data	Read Only		
1439	41440		9:229	User Register 7 Data	Read Only		
1440	41441		9:230	User Register 8 Data	Read Only		
1441	41442		9:231	User Register 9 Data	Read Only		
1442	41443		9:232	User Register 10 Data	Read Only		
1443	41444		9:233	User Register 11 Data	Read Only		
1444	41445		9:234	User Register 12 Data	Read Only		
1445	41446		9:235	User Register 13 Data	Read Only		
1446	41447		9:236	User Register 14 Data	Read Only		
1447	41448		9:237	User Register 15 Data	Read Only		
1448	41449		9:238	User Register 16 Data	Read Only		
1449	41450		9:239	User Register 17 Data	Read Only		
1450	41451		9:240	User Register 18 Data	Read Only		
1451	41452		9:241	User Register 19 Data	Read Only		
1452	41453		9:242	User Register 20 Data	Read Only		
1453	41454		9:243	User Register 21 Data	Read Only		
1454	41455		9:244	User Register 22 Data	Read Only		
1455	41456		9:245	User Register 23 Data	Read Only		
1456	41457		9:246	User Register 24 Data	Read Only		
1457	41458		9:248	User Register 25 Data	Read Only		
1458	41459		9:248	User Register 26 Data	Read Only		

FPU-32 REGISTER (DECIMAL)	MODBUS REGISTER (DECIMAL)	DEVICENET (Hex) (NOTE 4)	A-B FILE (DECIMAL) (NOTE 2)	DESCRIPTION	ACCESS	RANGE	TYPE (NOTE 1)
1459	41460		9:249	User Register 27 Data	Read Only	<i>Range and Type defined by user register value</i>	
1460	41461		9:250	User Register 28 Data	Read Only		
1461	41462		9:251	User Register 29 Data	Read Only		
1462	41463		9:252	User Register 30 Data	Read Only		
1463	41464		9:253	User Register 31 Data	Read Only		

NOTES:

- (1) See Appendix E, Register Formats.
- (2) The A-B File is coded as FILE:ELEMENT. To read or write the element as floats, the PLC 5 or SLC 500 address would be <F><FILE>:<ELEMENT> (Example F9:222). To read or write the element as integers using PLC 5 Typed Read and Typed Write commands, add 20 to the file number and precede with N, <N><FILE+20>:<ELEMENT> (Example N29:222). File offset is not required for the SLC 500 Protected Typed Logical Read and Write commands. See MPU-32 and FPU-32 TIA-485 Network Manual.
- (3) The bit number corresponds to the T79 Message Code. The LSB corresponds to the lower message code in the 16-bit number.
- (4) Designation is Class – Instance –Attribute.

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**APPENDIX E
REGISTER FORMATS**

TYPE	C TYPE	DESCRIPTION ⁽¹⁾
T1	float	IEEE 32-Bit Floating-Point Number
		Bit 31: Sign
		Bits 30..23: Exponent
		Bits 22..0: Mantissa
		(high): Bits 31..16 (low): Bits 15..0
T2	long	32-Bit Integer
		(high) Bits 31..16
		(low) Bits 15..0
T3	short	16-Bit Integer
T6	short	Enable/Disable
		0: Enabled
		1: Disabled
T10	short	Frequency
		0: 50 Hz
		1: 60 Hz
T14	short	Relay Trip/Alarm Mode
		0: Fail Safe
		1: Non Fail Safe
T18	short	Error Checking (AB DF1 only)
		0: Not Selected
		1: CRC Check
		2: BCC Check
T22	char	20 ASCII Characters
		Register +0: char[0] and char[1]. Char[0] at MSByte
		Register +1: char[2] and char[3]. Char[2] at MSByte
		Register +2: char[4] and char[5]. Char[4] at MSByte
		Register +3: char[6] and char[7]. Char[6] at MSByte
		Register +4: char[8] and char[9]. Char[8] at MSByte
		Register +5: char[10] and char[11]. Char[10] at MSByte
		Register +6: char[12] and char[13]. Char[12] at MSByte
		Register +7: char[14] and char[15]. Char[14] at MSByte
		Register +8: char[16] and char[17]. Char[16] at MSByte
		Register +9: char[18] and char[19]. Char[18] at MSByte
		A character value of 0 (Null) will terminate the string and the following characters will be ignored
Ethernet address strings are of the form: "ddd.ddd.ddd.ddd". The MAC address is a hex string of the form: "hhhhhhhhhhhh"		

TYPE	C TYPE	DESCRIPTION ⁽¹⁾
T23	long	Date
		Bits 31..16: year in binary
		Bits 15..8: 1-12 months in binary
		Bits 7..0: 1-31 days in binary
T24	long	Time
		Bits 31..24: 0-23 hours in binary
		Bits 23..16: 0-60 minutes in binary
		Bits 15..8: 0-60 seconds in binary
T31	char	RTC ASCII-Character Setting String:
		YY/MM/DD HH:mm:SS
		YY: 2-digit Year (Year 2000 – 2099)
		MM: Month 1-12
		DD: Day 1-31
		HH: Hour 0-23
		mm: Minute 0-59
		SS: Seconds 0-59
RTC is updated when "Set RTC" command is issued		
T32	Short	Free Record Pointer. Subtract one to obtain last record. Range is 0 to 99.
T38	short	Overload Reset Type
		0: Normal
		1: Autoreset 2: Rapid
T42	short	Trip Action
		0: Disabled
		1: Trip1
		2: Trip2
		3: Trip3
		4: Trip1 & Trip2
		5: Trip1 & Trip3
		6: Trip1 & Trip2 & Trip3
7: Trip2 & Trip3		

TYPE	C TYPE	DESCRIPTION ⁽¹⁾
T43	short	Alarm Action
		0: Disabled
		1: Alarm1
		2: Alarm2
		3: Alarm3
		4: Alarm1 & Alarm2
		5: Alarm1 & Alarm3
		6: Alarm1 & Alarm2 & Alarm3
		7: Alarm2 & Alarm3
T45	short	Trip/Alarm Message Code Bits ⁽³⁾ 15..0
T46	short	Trip/Alarm Message Code Bits ⁽³⁾ 31..16
T47	short	Trip/Alarm Message Code Bits ⁽³⁾ 47..32
T48	short	Trip/Alarm Message Code Bits ⁽³⁾ 63..48
T49	short	Trip/Alarm Message Code Bits ⁽³⁾ 79..64
T50	short	Trip/Alarm Message Code Bits ⁽³⁾ 95..80
T51	short	Trip/Alarm Message Code Bits ⁽³⁾ 111..96
T52	short	Trip/Alarm Message Code Bits ⁽³⁾ 127..112
T65	short	Network Communication Type
		0: None
		1: A-B DF1
		2: DeviceNet
		3: Reserved
		4: Modbus RTU
		5: Modbus TCP
		6: Reserved
T66	short	Local Communication Baud Rates
		0: 9,600 bit/s
		1: 19,200 bit/s
		2: 38,400 bit/s
T67	short	Trip and Alarm Summary
		Bit0: 0
		Bit1: 0
		Bit2: 0
		Bit3: 0
		Bit4: Trip1
		Bit5: Trip2
		Bit6: Trip3
		Bit7: Alarm1
		Bit8: Alarm2
		Bit9: Alarm3

TYPE	C TYPE	DESCRIPTION ⁽¹⁾
T67		Bit10: 0
		Bit11: 0
		Bit12: 0
		Bit13: 0
		Bit14: 0
		Bit15: 0
T68	Short	Temperature Sensor Type
		0: Disabled
		1: RTD Sensor
		2: PTC Sensor
T69	short	Network Baud Rate
		0: TIA 9,600 bit/s
		1: TIA 19,200 bit/s
		2: TIA 38,400 bit/s
		3: DeviceNet 125 kbit/s
		4: DeviceNet 250 kbit/s
		5: DeviceNet 500 kbit/s
T72	short	Communications Command
		0: Reserved
		1: Reserved
		2: Reserved
		3: Reset Trips (All except Remote/Network Trips)
		4: Set RTC
		5: Clear Data-Logging Records
		6: Clear Trip Counters
		7: Reserved
		8: Clear Running Hours
		9: Emergency Thermal Reset
		10: Reserved
		11: Reserved
		12: Re-enable Temperature Protection
		13: Remote/Network Trip Set
		14: Remote/Network Trip Reset
		15: Remote/Network Alarm Set
		16: Remote/Network Alarm Reset
		17: Run1 Set
18: Run1 Clear		

TYPE	C TYPE	DESCRIPTION ⁽¹⁾
T73	Short	Inverse Time Curve
		0: IEC Normal Inverse A
		1: IEC Very Inverse B
		2: IEC Extreme Inverse C
		3: IEC Short Inverse A
		4: IEC Long Inverse B
		5: IEEE Moderate Inverse
		6: IEEE Very Inverse
		7: IEEE Extreme Inverse
T74	Short	User Programmable Indicator
		0: None (LED Off)
		1: Trip1
		2: Trip2
		3: Trip3
		4: Alarm1
		5: Alarm2
		6: Alarm3
		7: Relay 1
		8: Relay 2
		9: Relay 3
		10: Digital Input
		11: Current Detected
		12: 3I ₀ Pickup
		13: Phase Pickup
		14: ETR State
		15: Reserved
16: Network Run1		
17: Net Activity		
T75	Short	Digital Input Function
		0: None
		1: Trip1
		2: Reset
		3: Program Enable
		4: Set-Point Group 2 Select

TYPE	C TYPE	DESCRIPTION ⁽¹⁾
T76	short	Relay Output Function
		0: None (Relay De-energized)
		1: Trip1
		2: Trip2
		3: Trip3
		4: Alarm1
		5: Alarm2
		6: Alarm3
		7: Current Detected
		8: Reserved
		9: Reserved
		10: Trip1 Pulse
		11: Watchdog
12: Network Run 1		
T77	Short	Analog Output Function
		0: Phase Current
		1: EF (I_{ct} Measured)
		2: EF ($3I_0$ Calculated)
		3: Used I^2t
		4: Reserved
		5: Reserved
		6: Reserved
		7: Reserved
		8: Reserved
		9: Unbalance
		10: Zero (4 mA)
11: Full Scale (20 mA)		
T78	Short	FPU-32 Status
		Bit0: 1 = Current > Threshold
		Bit1: 1 = $3I_0$ Inverse Curve Picked Up
		Bit2: 1 = Ph Inverse Curve Picked Up
		Bit3: 0
		Bit4: 1 = ETR On
		Bit5: 1 = PTC Open
		Bit6: 0
		Bit7: 0
		Bit8: 1 = Digital Input Valid
		Bit9: 1 = Relay 1 Energized
		Bit10: 1 = Relay 2 Energized
Bit11: 1 = Relay 3 Energized		

TYPE	C TYPE	DESCRIPTION ⁽¹⁾
T79	Short	Trip Code
		0: Overload Trip Group 1
		1: Overload Trip Group 2
		2: Overload Alarm Group 1
		3: Overload Alarm Group 2
		4: Phase Inverse O/C Trip Group 1
		5: Phase Inverse O/C Trip Group 2
		6: Phase Timed O/C Trip Group 1
		7: Phase Timed O/C Trip Group 2
		8: Phase Timed O/C Alarm Group 1
		9: Phase Timed O/C Alarm Group 2
		10: 3I ₀ Inverse Trip Group 1
		11: 3I ₀ Inverse Trip Group 2
		12: 3I ₀ Timed Trip Group 1
		13: 3I ₀ Timed Trip Group 2
		14: 3I ₀ Timed Alarm Group 1
		15: 3I ₀ Timed Alarm Group 2
		16: EFCT Timed Trip Group 1
		17: EFCT Timed Trip Group 2
		18: EFCT Timed Alarm Group 1
		19: EFCT Timed Alarm Group 2
		20: Unbalance Trip
		21: Unbalance Alarm
		22: Phase Loss Trip
		23: Phase Loss Alarm
		24: Phase Reverse Trip
		25: Phase Reverse Alarm
		26 to 29: Reserved
		30: Digital Input Trip
		31: RTD Trip
		32: RTD Alarm
		33: RTD Sensor Trip
		34: RTD Sensor Alarm
		35: PTC Trip
		36: PTC Alarm
		37 to 93: Reserved
		94: Memory Error. All defaults loaded
		95: Memory Error. Enumeration
		96: Memory Error. Numeric
		97: Memory Error. String
		98: Memory Error. Records1
		99: Memory Error. Records2
		100: Display Error
		101: Reserved

TYPE	C TYPE	DESCRIPTION ⁽¹⁾
T79		102: DSP Error
		103: Network Comm Trip
		104: Network Comm Alarm
		105: Remote Trip Via Network
		106: Remote Alarm Via Network
		107 to 127: Reserved
		252: ETR Request ⁽²⁾
		255: No Trip or Alarm
T80	Short	Record Type
		0: Empty Record
		1: Trip Record
		3: ETR Record
T81	Short	Set-Point Group
		0: Group 1
		1: Group 2
T84	Short	DeviceNet Producing Instance
		0: None
		1: 0x32 Basic Overload
		2: 0x33 Extended Overload
		3: 0x34 Basic Motor Starter
		4: 0x35 Extended Motor Starter I
T85	Short	DeviceNet Consuming Instance
		0: None
		1: 0x02 Basic Overload
		2: 0x03 Basic Motor Starter
T97	Short	Default Menu
		0: Main
		1: Current
		2: Unbalance
		3: Earth Leakage
		4: Thermal Status
		5: Inverse Status
		6: Load Sensor
		7: I/O Status
		8: System Status
	9: Network Status	

NOTES:

⁽¹⁾ All values are integers unless indicated by "Bit x", where x represents bit location and 0 = LSB.

⁽²⁾ Not a trip code. Used by event records to indicate special type.

⁽³⁾ The bit number corresponds to the T79 Message Code. The LSB corresponds to the lower message code in the 16-bit number.

APPENDIX F GROUND-FAULT PERFORMANCE TEST

To meet the requirements of the National Electrical Code (NEC), as applicable, the overall ground-fault-protection system requires a performance test when first installed. A written record of the performance test is to be retained by those in charge of the electrical installation in order to make it available to the authority having jurisdiction. A test record form is provided for recording the date and the final results of the performance tests. The following ground-fault system tests are to be conducted by qualified personnel:

- a) Evaluate the interconnected system in accordance with the overall equipment manufacturer's detailed instructions.
- b) Verify proper location of the ground-fault current transformer. Ensure the cable or bus passes through the ground-fault current transformer window, and that the grounding conductors or shields are not encompassed by the ground-fault current transformer in such a way as to cause ground-fault current to be missed. These checks can be done visually with knowledge of the circuit involved.
- c) Verify that the system is correctly grounded and that alternate ground paths do not exist that bypass the current transformer. High-voltage testers and resistance bridges can be used to determine the existence of alternate ground paths.
- d) Verify proper reaction of the circuit-interrupting device in response to a simulated or controlled ground-fault current. To simulate ground-fault current, use CT-primary current injection. Fig. F.1(a) shows a test circuit using an SE-400 Ground-Fault-Relay Test Unit. The SE-400 has a programmable output of 0.5 to 9.9 A for a duration of 0.1 to 9.9 seconds. Set the test current to 15% greater than the FPU-32 trip setting. Fig. F.1(b) shows a test circuit using an SE-100T Ground-Fault-Relay Tester. The SE-100T provides a test current of 0.65 or 2.75 A for testing 0.5- and 2.0-A trip levels. Inject the test current through the current-transformer window for at least 2.5 seconds. Verify that the circuit under test has reacted properly. Correct any problems and re-test until the proper reaction is verified.
- e) Record the date and the results of the test on the attached test-record form.

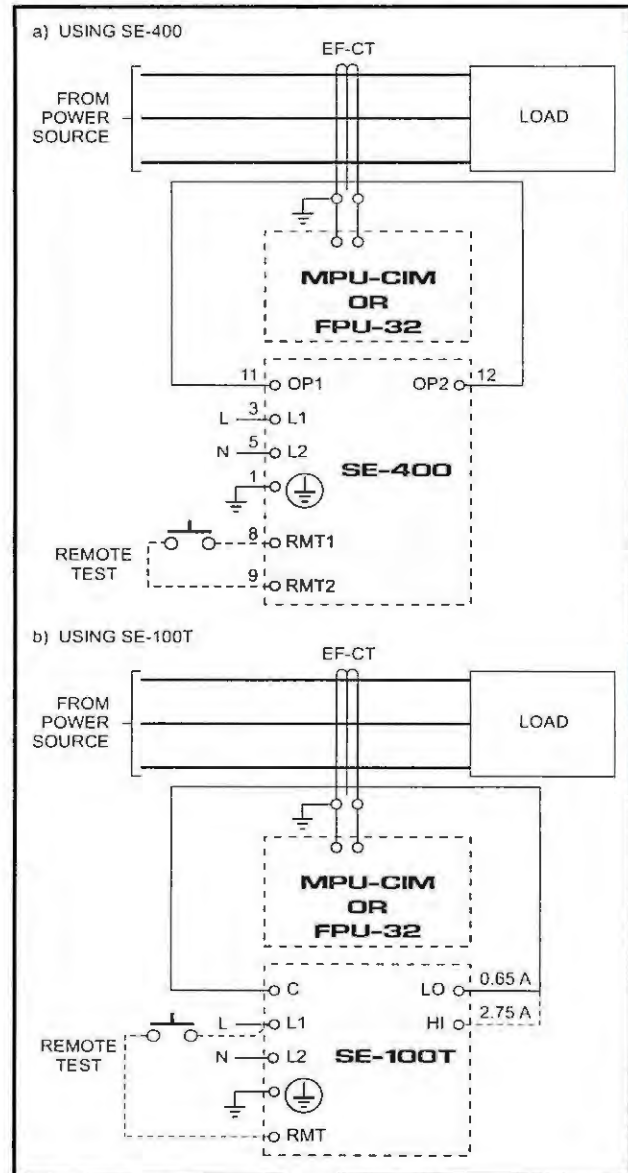


FIGURE F.1 Ground-Fault-Test Circuits

Filename: C:\Program Files\Startco Engineering\SECOMMRIS\FPU-32-SRS-CHILE.CDS
 Unit Type FPU-32
 Firmware Version Firmware Version: 1.30

Parameters	Value	Units	Comments (Not stored on Unit)
System Name	Startco FPU-32		
Overload Reset			
I2t Reset Type	Normal		
I2t Reset Level	0.50	pu	
Current Unbalance			
Trip Action	Trip1		
Trip Level	0.25		
Trip Delay	15.00	s	
Alarm Action	Disabled		
Alarm Level	0.50		
Alarm Delay	10.00	s	
Phase Loss			
Trip Action	Trip1		
Trip Delay	5.00	s	
Alarm Action	Alarm1		
Alarm Delay	2.00	s	
Phase Reverse			
Trip Action	Disabled		
Trip Delay	5.00	s	
Alarm Action	Disabled		
Alarm Delay	2.00	s	
PTC Local Temperature			
Trip Action	Disabled		
Alarm Action	Disabled		

Parameters	Value	Units	Comments (Not stored on Unit)
RTD Temperature			
Trip Action	Disabled		
Trip Level	200.00	°C	
Alarm Action	Disabled		
Alarm Level	130.00	°C	
RTD-Sensor-Error Trip Action	Disabled		
RTD-Sensor-Error Alarm Action	Disabled		
Overload G1			
I2t Trip Action	Trip1		
I2t Pickup	1.00	x Ip	
Hot Factor	0.50		
Cooling Factor	1.00		
Time Constant	10.00	min	
I2t Alarm Action	Alarm1		
I2t Alarm Level	1.00	pu	
Phase Inverse G1			
Trip Action	Trip1		
Curve Type	IEC Normal Inverse A		
Pickup	2.00	x Ip	
Time Multiplier	0.20		
Phase Definite Time G1			
Trip Action	Trip1		
Trip Level	10.00	x Ip	
Trip Delay	0.05	s	
Alarm Action	Alarm1		
Alarm Level	10.00	x Ip	
Alarm Delay	0.05	s	
EF 3Io Inverse G1			
Trip Action	Trip1		
Curve Type	IEC Normal Inverse A		
Pickup	2.00	x Ip	
Time Multiplier	0.20		

Parameters	Value	Units	Comments (Not stored on Unit)
EF 3Io Definite Time G1			
Trip Action	Trip1		
Trip Level	10.00	x Ip	
Trip Delay	0.05	s	
Alarm Action	Disabled		
Alarm Level	10.00	x Ip	
Alarm Delay	0.05	s	
EF CT-Input Definite Time G1			
Trip Action	Trip1		
Trip Level	0.40	x Ie	
Trip Delay	0.25	s	
Alarm Action	Alarm1		
Alarm Level	0.20	x Ie	
Alarm Delay	1.00	s	
Overload G2			
I2t Trip Action	Trip1		
I2t Pickup	1.00	x Ip	
Hot Factor	0.50		
Cooling Factor	1.00		
Time Constant	10.00	min	
I2t Alarm Action	Alarm1		
I2t Alarm Level	1.00	pu	
Phase Inverse G2			
Trip Action	Trip1		
Curve Type	IEC Normal Inverse A		
Pickup	2.00	x Ip	
Time Multiplier	0.20		
Phase Definite Time G2			
Trip Action	Disabled		
Trip Level	10.00	x Ip	
Trip Delay	0.05	s	
Alarm Action	Disabled		
Alarm Level	10.00	x Ip	

Parameters	Value	Units	Comments (Not stored on Unit)
Alarm Delay	0.05	s	
EF 3Io Inverse G2			
Trip Action	Disabled		
Curve Type	IEC Normal Inverse A		
Pickup	2.00	x Ip	
Time Multiplier	0.20		
EF 3Io Definite Time G2			
Trip Action	Disabled		
Trip Level	10.00	x Ip	
Trip Delay	0.05	s	
Alarm Action	Disabled		
Alarm Level	10.00	x Ip	
Alarm Delay	0.05	s	
EF CT-Input Definite Time G2			
Trip Action	Trip1		
Trip Level	0.40	x Ie	
Trip Delay	0.25	s	
Alarm Action	Alarm1		
Alarm Level	0.20	x Ie	
Alarm Delay	1.00	s	
System Ratings			
Phase-CT Primary (Ip)	150.00	A	
Earth-Fault CT Primary (Ie)	200.00	A	
Frequency	50 Hz		
Set-Point Group	Group 1		
Digital Input			
Function	None		
Trip Delay	0.10	s	
Relay Output Function			
Relay 1 Output Function	Trip1		
Relay 1 Mode	Fail Safe		

Parameters	Value	Units	Comments (Not stored on Unit)
Relay 2 Output Function	Alarm3		
Relay 2 Mode	Fail Safe		
Relay 3 Output Function	None		
Relay 3 Mode	Fail Safe		
Relay Pulse Time	0.25	s	
Analog Output			
Analog Output Parameter	Phase Current		
Hardware and System Config			
Display-Loss Trip Action	Trip1		
Temp Sensor Type	Disabled		
Password Timeout	10.00	min	
Unbalance Current Threshold	0.25	x Ip	
UPI LED Assignment	None		
Default Menu	Main		
Network Communication			
Network Type	None		
Network Baud	TIA 9600		
Net Error Check	Not Selected		
Network ID (Slave ID)	254.00		
Network Trip Action	Disabled		
Network Alarm Action	Disabled		
Remote Trip Action	Disabled		
Remote Alarm Action	Disabled		
DeviceNet Producing Instance	0x64 User Registers		
DeviceNet Consuming Instance	None		
Ethernet (If Applicable)			
IP Address	192.168.000.001		
Address Mask	255.255.255.000		
MAC Address	0015FC000000		Cannot be changed through SE-Comm-RIS
User Defined Registers			
User Register 0	0		
User Register 1	0		

Parameters	Value	Units	Comments (Not stored on Unit)
User Register 2	0		
User Register 3	0		
User Register 4	0		
User Register 5	0		
User Register 6	0		
User Register 7	0		
User Register 8	0		
User Register 9	0		
User Register 10	0		
User Register 11	0		
User Register 12	0		
User Register 13	0		
User Register 14	0		
User Register 15	0		
User Register 16	0		
User Register 17	0		
User Register 18	0		
User Register 19	0		
User Register 20	0		
User Register 21	0		
User Register 22	0		
User Register 23	0		
User Register 24	0		
User Register 25	0		
User Register 26	0		
User Register 27	0		
User Register 28	0		
User Register 29	0		
User Register 30	0		
User Register 31	0		

3-YEAR WARRANTY DATA SHEET



BENSHAW
ADVANCED CONTROLS & DRIVES

Benshaw Canada
550 Bright St. East
Listowel, Ontario
N4W 3W3
Tel: (519) 291-5112
Fax: (519) 291-2595

Benshaw's standard warranty is one (1) year from date of shipment. Benshaw will extend this warranty to three (3) years from date of shipment if the information requested on this extended warranty card and parameter sheets are completely and accurately filled out and returned to Benshaw within 5 days from the start-up of the equipment. See attached Warranty Statement and Terms and Conditions.

STARTER INFORMATION:

Date of Startup:	Date of purchase:
Benshaw Model #: CFMVRMX18-300-4160 3R	Benshaw Serial #: CA11000963B

USER INFORMATION (OWNER):

Company Name:	SRS Crisagfulli		
Address:	1610 Crisafulli DR Glendive MT 59330		
Contact:	Phone:	Fax:	
Purchased from (Distributor): Dykman Electric			

MOTOR INFORMATION:

Type of Motor:	<input checked="" type="checkbox"/> Std. Induction <input type="checkbox"/> Wound Rotor <input type="checkbox"/> Synchronous <input type="checkbox"/> Other		
Make:	Lincoln	Synchronous Motors	Wound rotor motors
HP:	300	SF: 1.15	Field Voltage:
VOLTS:	4160	LRA:	Secondary Volts:
FLA:	39	NEMA Design: B	Field Resistor:
RPM:	1485	Frame: 5011LS	Secondary Resistance:
FREQ:	50Hz	KVA Code: H	

LOAD INFORMATION:

Type of driven load:	Hyd pumps		
MFG. of driven equipment:	Eaton	Model #:	Serial #:

POWER SYSTEM INFORMATION:

<input checked="" type="checkbox"/> Utility Power	Transformer Rating	kVA	<input type="checkbox"/> Generator	Generator Rating	kW
Power cable run from source to starter: ft <input type="checkbox"/> Approximate or <input type="checkbox"/> Actual					
<input type="checkbox"/> Power Factor Caps/Surge Caps/Lightning Arrestors moved to line side of solid-state starter or removed.					
DANGER: Equipment may be damaged or personal injury may result if equipment is started with lightning arrestors, power factor capacitors or surge capacitors connected on the load side of the solid-state motor controls.					

STARTUP PROCEDURES (All procedures are found in your instruction manual):

<input checked="" type="checkbox"/> Pre-startup procedures followed	<input checked="" type="checkbox"/> Connection procedures followed	<input checked="" type="checkbox"/> Startup procedures followed
<input checked="" type="checkbox"/> Proper cable size	<input checked="" type="checkbox"/> All Connections tight (Power & Control)	
Name of person completing this report:	Signature:	

WARRANTY STATUS (For Benshaw Office Use Only):

Date Shipped:	Comments:
Effective Date:	
Expiration Date:	Approved by:

Please return to: Benshaw Canada, 550 Bright Street E. Listowel, Ontario, Canada N4W 3W3. Attn: Warranty Department. Fax: 519-291-2595

***** Complete the warranty registration on-line at <http://www.benshaw.com> *****

3-YEAR WARRANTY DATA SHEET

General Conditions

All warranties are provided in accordance with Benschaw, Inc. Terms and Conditions of Sale. Benschaw warrants its products including printed circuit boards, power electronic assemblies and integral bypass contactors per the periods and warranty types listed below. Other manufacturer's products which are included in the Benschaw equipment such as circuit breakers, fuses, transformers, relays, pilot devices and other power/control components are warranted per the terms and conditions of the manufacturer's original equipment warranty. All warranty periods for Benschaw manufactured products are based on the date of shipment unless otherwise specified.

Solid State Reduced Voltage Products		Warranty Period	Warranty Type	Warranty Registration
<i>RC2</i>	Non Reversing	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RC3</i>	Non Reversing	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RCM</i>	Non Reversing	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RB2</i>	Non Reversing with Bypass	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RB3</i>	Non Reversing with Bypass	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RBX</i>	Non Reversing with Bypass	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RBM</i>	Non Reversing with Bypass	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RSM10</i>	Reversing Starter	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RSM10B</i>	Reversing / Bypass	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RSM11</i>	Reversing / DC Brake	3 Years *	Factory Repair or Exchange	Data Sheet
<i>RSM11B</i>	Reversing / Brake / Bypass	3 Years *	Factory Repair or Exchange	Data Sheet
<i>MVRSM</i>	Medium Voltage-All Types	3 Years	Active On Site	Startup Service
<i>MVRMX</i>	Medium Voltage-All Types	3 Years	Active On Site	Startup Service
<i>WRSM6</i>	Wound Rotor Starter	3 Years *	Factory Repair or Exchange	Data Sheet
<i>SMRSM6B</i>	Synchronous Starter	3 Years *	Factory Repair or Exchange	Data Sheet

Brakes Products		Warranty Period	Warranty Type	Warranty Registration
<i>DCB3</i>	DC Injection Brake	3 Years	Factory Repair or Exchange	Data Sheet

Full Voltage Products		Warranty Period	Warranty Type	Warranty Registration
<i>FVNR</i>	Non Reversing	3 Years *	Factory Repair or Exchange	Data Sheet
<i>FVR</i>	Reversing	3 Years *	Factory Repair or Exchange	Data Sheet

* Motors larger than a T - Frame require a supervised start up for the 3-year warranty.

Factory Repair or Exchange:

Benschaw will repair or replace, at its option, all Benschaw manufactured components, which fail within the defined warranty period. Failures, which are caused by unauthorized repairs, mechanical, electrical or physical abuse and acts of God such as lightning, fires or floods, are excluded. The customer pays freight and any required labor costs.

Active On Site Time and Parts:

If Benschaw determines that on site repairs or exchange is necessary, Benschaw or an authorized service agent will perform the necessary work on site. Benschaw will provide the actual service time and required parts to repair the unit. The customer will pay for travel time and living costs to the site and any waiting time to perform the repairs. Failures, which are caused by unauthorized repairs, mechanical, electrical or physical abuse and acts of God such as lightning, fires or floods, are excluded. A purchase order must be issued for the non-warranty travel and living costs prior to the work being performed.

Warranty Registration – Installation Data Sheet:

For low voltage products, the Benschaw warranty registration form must be completed and returned to Benschaw within five (5) days of startup to activate the 3-year warranty. If the data sheet is not completed and returned, the warranty will be 12 months from date of shipment. All recommended maintenance procedures must be followed throughout the warranty period. Motors larger than a T-Frame require a Benschaw authorized representative to start the equipment to activate the 3-year warranty.

Warranty Registration – Benschaw Startup Service:

For Medium Voltage products, Benschaw or an authorized service agent must startup the equipment and complete the installation data sheet to activate the 3-year warranty from date of shipment. If the data sheet is not completed and returned, the warranty will be 12 months from date of shipment. The cost of this service is not included in the price of the Benschaw equipment and will be quoted separately to the customer. All recommended maintenance procedures must be followed throughout the warranty period.

12/18 Month Warranty

These warranties are 12 months from date of startup or 18 months from date of shipment, whichever is sooner.



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Medium Voltage Parameter List for MVRMX

Starter Parameters;

LCD	LED	Display	Parameter	Setting Range	Units	Default	User Setting
QST 00		Jump Code	Jump to Parameter	1 to 9		1	Jumper Code
QST 01	P1	Motor FLA	Motor FLA	1 - 6400	RMS Amps	10	39
QST 02	P2	Motor SF	Motor Service Factor	1.00 - 1.99		1.15	1.15
QST 03	P3	Running OL	Motor Running Overload Class	Off, 1 - 40		10	20
QST 04	P4	Local Src	Local Source	Keypad / Terminal / Serial		Terminal	Terminal
QST 05	P5	Remote Src	Remote Source			Terminal	Terminal
QST 06	P6	Init Cur 1	Initial Motor Current 1	50 - 600	%FLA	100	400
QST 07	P7	Max Cur 1	Maximum Motor Current 1	100 - 800	%FLA	600	500
QST 08	P8	Ramp Time 1	Ramp Time 1	0 - 300	Seconds	15	10
QST 09	P9	UTS Time	UTS Time / Transition Time	1 - 900	Seconds	20	12

LCD	LED	Display	Parameter	Setting Range	Units	Default	User Setting
CFN 00		Jump Code	Jump to Parameter	1 to 27		1	Jump Code 1
CFN 01	P10	Start Mode	Start Mode	Voltage Ramp Current Ramp TT Ramp Power Ramp Tach Ramp		Current Ramp	Current
CFN 02	P8	Ramp Time 1	Ramp Time 1	0 to 300	Seconds	15	10
CFN 03	P6	Init Cur 1	Initial Motor Current 1	50 to 600	%FLA	100	400
CFN 04	P7	Max Cur 1	Maximum Motor Current 1	100 to 800	%FLA	600	500
CFN 05	P24	Ramp Time 2	Ramp Time 2	0 to 300	Seconds	15	10
CFN 06	P22	Init Cur 2	Initial Motor Current 2	50 to 600	%FLA	100	400
CFN 07	P23	Max Cur 2	Maximum Motor Current 2	100 to 800	%FLA	600	500
CFN 08	P11	Init V/T/P	Initial Voltage/Torque/Power	1 to 100	%	25	50%
CFN 09	P12	Max T/P	Maximum Torque/Power	10 to 325	%	105	10.5
CFN 10		Accel Prof	Acceleration Ramp Profile	Linear/Squared/S-Curve		Linear	Linear
CFN 11	P13	Kick Lvl 1	Kick Level 1	Off, 100 to 800	%FLA	Off	off
CFN 12	P14	Kick Time 1	Kick Time 1	0.1 to 10.0	Seconds	1.0	1.0
CFN 13	P25	Kick Lvl 2	Kick Level 2	Off, 100 to 800	%FLA	Off	off
CFN 14	P26	Kick Time 2	Kick Time 2	0.1 to 10.0	Seconds	1.0	1.0
CFN 15	P15	Stop Mode	Stop Mode	Coast / Volt Decel / TT Decel / DC Brake		Coast	Coast
CFN 16	P16	Decel Begin	Decel Begin Level	100 to 1	%	40	40%
CFN 17	P17	Decel End	Decel End Level	99 to 1	%	20	20
CFN 18	P18	Decel Time	Decel Time	1 to 180	Seconds	15	15
CFN 19		Decel Prof	Decel Ramp Profile	Linear/Squared/S Curve		Linear	Linear
CFN 20	P19	Brake Level	DC Brake Level	0 to 100	%	25	25
CFN 21	P20	Brake Time	DC Brake Time	1 to 180	Seconds	5	5
CFN 22	P21	Brake Delay	DC Brake Delay	0.1 to 3.0	Seconds	0.2	1.0
CFN 23	P27	SSpd Speed	Slow Speed	Off, 1 - 40	%	Off	off
CFN 24	P28	SSpd Curr	Slow Speed Current Level	10 to 400	% FLA	100	100
CFN 25	P29	SSpd Timer	Slow Speed Timer	Off, 1 to 900	Seconds	10	10
CFN 26	P30	SSpd Kick Curr	Slow Speed Kick Level	Off, 100 to 800	% FLA	Off	10
CFN 27	P31	SSpd Kick T	Slow Speed Kick Time	0.1 to 10.0	Seconds	1.0	1.0



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Medium Voltage Parameter List for MVRMX

LCD	LED	Display	Parameter	Setting Range	Units	Default	User Setting
PFN 00		Jump Code	Jump to Parameter	1 - 35		1	Jump Code 1
PFN 01	P32	Over Cur Lvl	Over Current Trip Level	Off, 50 - 800	%FLA	Off	125%
PFN 02	P33	Over Cur Time	Over Current Trip Delay Time	Off, 0.1 - 90.0	Seconds	0.1	1.0
PFN 03	P34	Undr Cur Lvl	Under Current Trip Level	Off, 5 - 100	%FLA	Off	Off
PFN 04	P35	Undr Cur Time	Under Current Trip Delay Time	Off, 0.1 - 90.0	Seconds	0.1	.1
PFN 05	P36	Cur Imbl Lvl	Current Imbalance Trip Level	Off, 5 - 40	%	15	15
PFN 06		Cur Imbl Time	Current Imbalance Trip Time	0.1 - 90	Seconds	10	10
PFN 07	P37	Resid GF Lvl	Residual Ground Fault Trip Level	Off, 5 - 100	%FLA	Off	15%
PFN 08		ZS GF Lvl	Zero Sequence Ground Fault Trip Level	Off, 1.0 - 25	Amps	Off	10
PFN 09		Gnd Flt Time	Ground Fault Trip Time	0.1 - 90.0	Seconds	3.0	3.0
PFN 10	P38	Over Vlt Lvl	Over Voltage Trip Level	Off, 1 - 40	%	Off	15%
PFN 11	P39	Undr Vlt Lvl	Under Voltage Trip Level	Off, 1 - 40	%	Off	35%
PFN 12	P40	Vlt Trip Time	Over/Under Voltage Trip Delay Time	0.1 - 90.0	Seconds	0.1	3.0
PFN 13		Ph Loss Time	Phase Loss Trip Time	0.1 - 5.0	Seconds	0.2	1.0
PFN 14		Over Frq Lvl	Over Frequency Trip	24 - 72	Hz	72	70
PFN 15		Undr Frq Lvl	Under Frequency Trip	23 - 71	Hz	23	23
PFN 16		Frq Trip Time	Frequency Trip Time	0.1 - 90.0	Seconds	0.1	3.0
PFN 17		PF Lead Lvl	PF Lead Trip Level	Off, -0.80 lag to +0.01 lead		Off	Off
PFN 18		PF Lag Lvl	PF Lag Trip Level	Off, -0.01 lag to +0.80 lead		Off	Off
PFN 19		PF Trip Time	PF Trip Time	0.1 - 90.0	Seconds	10.0	10.0
PFN 20		Backspin Time	Backspin Timer	Off, 1 - 180	Minutes	Off	Off
PFN 21		Time Btw St	Time Between Starts	Off, 1 - 180	Minutes	Off	Off
PFN 22		Starts/Hour	Starts per Hour	Off, 1 - 6		Off	4
PFN 23	P41	Auto Reset	Auto Fault Reset Time	Off, 1 - 900	Seconds	Off	Off
PFN 24	P42	Auto Rst Lim	Auto Fault Reset Count Limit	Off, 1 - 10		Off	Off
PFN 25	P43	Ctrl Flt En	Controlled Fault Stop	Off, On		On	On
PFN 26		Speed Sw Time	Speed Switch Trip Time	Off, 1 - 250	Seconds	Off	Off
PFN 27		M PTC Time	Motor PTC Trip Time	Off, 1 - 5	Seconds	Off	Off
PFN 28	P44	Indep S/R OL	Independent Starting / Running Overload	Off, On		Off	Off
PFN 29	P45	Starting OL	Motor Overload Class Starting	Off, 1 - 40		10	20
PFN 30		Running OL	Motor Overload Class Running	Off, 1 - 40		10	20
PFN 31	P46	OL H/C Ratio	Motor Overload Hot/Cold Ratio	0 - 99	%	60	60%
PFN 32	P47	OL Cool Time	Motor Overload Cooling Time	1.0 - 999.9	Minutes	30.0	25
PFN 33		OL Alarm Lvl	Motor OL Alarm Level	1 - 100	%	90	90
PFN 34		OL Lock Lvl	Motor OL Lockout Level	1 - 99	%	15	15
PFN 35		OL Lock Calc	Motor OL Auto Lockout Level	Off, Auto		Off	Off



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Medium Voltage Parameter List for MVRMX

LCD	LED	Display	Parameter	Setting Range	Units	Default	User Setting
I/O 00		Jump Code	Jump to Parameter	1 to 27		1	Jump Code
I/O 01	P48	DI 1 Config	Digital Input #1 Configuration	Off Stop	Local/Remote Heat Disable	Stop	Stop
I/O 02	P49	DI 2 Config	Digital Input #2 Configuration	Fault High Fault Low	Heat Enable Ramp Select	Off	Off
I/O 03	P50	DI 3 Config	Digital Input #3 Configuration	Fault Reset Disconnect	Slow Spd Fwd Slow Spd Rev	Off	Off
I/O 04		DI 4 Config	Digital Input #4 Configuration	Inline Cnfrm Bypass Cnfrm	Brake Disabl Brake Enable	Off	Off
I/O 05		DI 5 Config	Digital Input #5 Configuration	E. OL Reset	Speed Sw NO	Off	Off
I/O 06		DI 6 Config	Digital Input #6 Configuration			Off	Off
I/O 07		DI 7 Config	Digital Input #7 Configuration			Off	Inline Config
I/O 08		DI 8 Config	Digital Input #8 Configuration			Off	Disconnect
I/O 09	P51	Dig Trp Time	Digital Fault Input Trip Time	0.1 to 90.0	Seconds	0.1	2.0
I/O 10	P52	R1 Config	Relay Output #1 Configuration	Off Fault FS	Shunt NFS Ground Fault	Fault FS	Fault FS
I/O 11	P53	R2 Config	Relay Output #2 Configuration	Fault NFS Running	Energy Saver Heating	Off	Running
I/O 12	P54	R3 Config	Relay Output #3 Configuration	UTS Alarm	Slow Spd Slow Spd Fwd	Off	Off
I/O 13		R4 Config	Relay Output #4 Configuration	Ready Locked Out	Slow Spd Rev Braking	Off	Off
I/O 14		R5 Config	Relay Output #5 Configuration	Overcurrent Undercurrent	Cool Fan Ctl PORT	Off	Off
I/O 15		R6 Config	Relay Output #6 Configuration	OL Alarm Shunt FS	Tach Loss	Off	Off
I/O 16	P55	Ain Trp Type	Analog Input Trip Type	Off Low Level High Level		Off	Off
I/O 17	P56	Ain Trp Lvl	Analog Input Trip Level	0 to 100	%	50	50
I/O 18	P57	Ain Trp Tim	Analog Input Trip Delay Time	0.1 to 90.0	Seconds	0.1	0.1
I/O 19	P58	Ain Span	Analog Input Span	1 to 100	%	100	100
I/O 20	P59	Ain Offset	Analog Input Offset	0 to 99	%	0	0
I/O 21	P60	Aout Fctn	Analog Output Function	Off 0 - 200% Curr 0 - 300% Curr 0 - 150% Volt 0 - 150% OL 0 - 10 kW 0 - 100 kW 0 - 1 MW 0 - 10 MW 0 - 100% Ain 0 - 100% Firing Calibration		Off	Off
I/O 22	P61	Aout Span	Analog Output Span	1 to 125	%	100	100
I/O 23	P62	Aout Offset	Analog Output Offset	0 to 99	%	0	0
I/O 24	P63	Inline Conf	Inline Configuration	Off, 1.0 to 10.0	Seconds	3.0	3.0
I/O 25	P64	Bypas Fbk Tim	Bypass / 2M Confirm	0.1 to 5.0	Seconds	2.0	2.0
I/O 26	P65	Kpd Stop	Keypad Stop Disable	Enabled, Disabled		Enabled	Enabled
I/O 27	P66	Auto Start	Power On Start Selection	Disabled Power	Fault Power, Fault	Disabled	Disabled



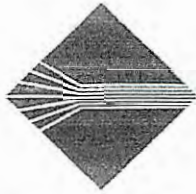
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Medium Voltage Parameter List for MVRMX

LCD	Display	Parameter	Setting Range	Units	Default	User Setting
RTD 00	Jump Code	Jump to Parameter	1 - 29		1	
RTD 01	RTD Mod1 Addr	RTD Module #1 Address	Off, 16 - 23		Off	↙
RTD 02	RTD Mod2 Addr	RTD Module #2 Address				OFF
RTD 03	RTD1 Group	RTD1 Group	Off		Off	
RTD 04	RTD2 Group	RTD2 Group	Stator			
RTD 05	RTD3 Group	RTD3 Group	Bearing			
RTD 06	RTD4 Group	RTD4 Group	Other			
RTD 07	RTD5 Group	RTD5 Group				
RTD 08	RTD6 Group	RTD6 Group				
RTD 09	RTD7 Group	RTD7 Group				
RTD 10	RTD8 Group	RTD8 Group				
RTD 11	RTD9 Group	RTD9 Group				
RTD 12	RTD10 Group	RTD10 Group				
RTD 13	RTD11 Group	RTD11 Group				
RTD 14	RTD12 Group	RTD12 Group				
RTD 15	RTD13 Group	RTD13 Group				
RTD 16	RTD14 Group	RTD14 Group				
RTD 17	RTD15 Group	RTD15 Group				
RTD 18	RTD16 Group	RTD16 Group				
RTD 19	Stator Alarm	Stator Alarm Level	1 - 200	"C	200	
RTD 20	Bearing Alarm	Bearing Alarm Level			200	
RTD 21	Other Alarm	Other Alarm Level			200	
RTD 22	Stator Trip	Stator Trip Level			200	
RTD 23	Bearing Trip	Bearing Trip Level			200	
RTD 24	Other Trip	Other Trip Level			200	
RTD 25	RTD Voting	RTD Voting	Disabled / Enabled		Disabled	
RTD 26	RTD Biasing	RTD Motor OL Biasing	Off, On		Off	
RTD 27	RTD Bias Min	RTD Bias Minimum Level	0 - 198	"C	40	
RTD 28	RTD Bias Mid	RTD Bias Mid Point Level	1 - 199	"C	130	
RTD 29	RTD Bias Max	RTD Bias Maximum Level	105 - 200	"C	155	

LCD	LED	Display	Parameter	Setting Range	Units	Default	User Setting
FUN 00		Jump Code	Jump to Parameter	1 to 26		1	
FUN 01	P71	Meter 1	Meter 1	Ave Current L1 Current L2 Current L3 Current Curr Imbal Ground Fault Ave Volts L1-L2 Volts L2-L3 Volts L3-L1 Volts Overload Power Factor Watts VA vars kW hours MW hours	Phase Order Line Freq Analog Input Analog Out Run Days Run Hours Starts TruTorque % Power % Pk Accel Cur Last Start T Zero Seq GF Stator Temp Bearing Temp Other Temp All Temp	Ave Current	AVE Current
FUN 02		Meter 2	Meter 2			Ave Volts	AVE Volts



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Medium Voltage Parameter List for MVRMX

LCD	LED	Display	Parameter	Setting Range	Units	Default	User Setting
FUN 03	P78	CT Ratio	CT Ratio	72:1, 96:1, 144:1, 288:1, 864:1, 1320:1, 2640:1, 2880:1, 3900:1, 5760:1, 8000:1, 14400:1, 28800:1, 50:5, 150:5, 250:5, 800:5, 2000:5, 5000:5		288:1	50:5
FUN 04	P77	Phase Order	Input Phase Sensitivity	Insensitive ABC	CBA Single Phase	Insensitive	Insensitive
FUN 05	P76	Rated Volts	Rated RMS Voltage	100, 110, 120, 200, 208, 220, 230, 240, 350, 380, 400, 415, 440, 460, 480, 500, 525, 575, 600, 660, 690, 800, 1000, 1140, 2200, 2300, 2400, 3300, 4160, 4600, 4800, 6000, 6600, 6900, 10000, 11000, 11500, 12000, 12470, 13200, 13800	RMS Voltage	480	4160
FUN 06	P75	Motor PF	Motor Rated Power Factor	-0.01 (Lag) to 1.00 (Unity)		-0.92	-0.92
FUN 07	P74	Starter Type	Starter Type	Normal Inside Delta Wye-Delta	Phase Ctl Curr Follow ATL	Normal	Normal
FUN 08	P73	Heater Level	Heater Level	Off, 1 to 40	%FLA	Off	Off
FUN 09	P72	Energy Saver	Energy Saver	Off, On	Seconds	Off	Off
FUN 10		PORT Flt Tim	P.O.R.T. Fault Time	Off, 0.1 - 90.0	Seconds	Off	Off
FUN 11		PORT Byp Tim	P.O.R.T. Bypass Hold Time	Off, 0.1 - 5.0	Seconds	Off	Off
FUN 12		PORT Recover	P.O.R.T. Recovery Method	Voltage Ramp Fast Recover Current Ramp	Curr Ramp 2 Ramp Select Tach Ramp	Fast Recover	Fast Recover
FUN 13		Tach FS Lvl	Tachometer Full Speed Voltage	1.00 - 10.00	Volts	5.00	5.00
FUN 14		Tach Los Tim	Tachometer Loss Time	0.1 - 90.0	Seconds	1.5	1.5
FUN 15		Tach Los Act	Tachometer Loss Action	Fault Current Ramp	TT Ramp Power Ramp	Fault	Fault
FUN 16	P70	Com Drop #	Communication Address	1 to 247		1	1
FUN 17	P69	Com Baud rate	Communication Baud Rate	1200 2400 4800	9600 19200	bps	19200
FUN 18	P68	Com Timeout	Communication Timeout	Off, 1 to 120	Seconds	Off	Off
FUN 19	P71	Com Parity	Communications Byte Framing	Even, 1 Stop Bit Odd, 1 Stop Bit None, 1 Stop Bit None, 2 Stop Bit		Even, 1 Stop	Even 1 Stop
FUN 20	P80	Software 1	Software Part Number 1	Display Only			
FUN 21		Software 2	Software Part Number 2	Display Only			
FUN 22	P67	Misc Command	Miscellaneous Commands	None Reset RT Reset kWh Reflash Mode Store Params	Load Params Factory Rst Std BIST Powered BIST	None	NONE



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Medium Voltage Parameter List for MVRMX

LCD	LED	Display	Parameter	Setting Range	Units	Default	User Setting
FUN 23		T/D Format	Time and Date Format	mm/dd/yy 12h mm/dd/yy 24h yy/mm/dd 12h yy/mm/dd 24h dd/mm/yy 12h dd/mm/yy 24h		mm/d/y 12h	
FUN 24		Time	Time			Present Time	
FUN 25		Date	Date			Present Date	
FUN 26		Passcode	Passcode			Off	