

**USERS MANUAL****GRASP: a data analysis package for gravitational wave detection**

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August 25, 1997

**Abstract**

GRASP (Gravitational Radiation Analysis & Simulation Package) is a public-domain software tool-kit designed for analysis and simulation of data from gravitational wave detectors. This users manual describes the use and features of this package. Note: an up-to-date version of this manual may be obtained at: [http://www.ligo.caltech.edu/LIGO\\_web/Collaboration/manual.pdf](http://www.ligo.caltech.edu/LIGO_web/Collaboration/manual.pdf), or at [http://www.ligo.caltech.edu/LIGO\\_web/Collaboration/lsc\\_interim.html](http://www.ligo.caltech.edu/LIGO_web/Collaboration/lsc_interim.html). The software package is available on request.

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**GRASP RELEASE 1.5**  
manual version 1.5.0

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# Contents

<b>1</b>	<b>Acknowledgements</b>	<b>6</b>
<b>2</b>	<b>Introduction</b>	<b>7</b>
2.1	The Purpose of GRASP . . . . .	7
2.2	Quick Start . . . . .	7
2.3	A few words about data formats . . . . .	8
2.4	GRASP Hardware & Software Requirements . . . . .	9
2.5	GRASP Installation . . . . .	9
2.5.1	GRASP File Structure . . . . .	10
2.5.2	Accessing <i>Numerical Recipes in C</i> libraries . . . . .	11
2.5.3	Accessing MPI and MPE libraries . . . . .	11
2.5.4	Accessing FRAME libraries . . . . .	12
2.5.5	Real-time 40-meter analysis . . . . .	12
2.5.6	Making the GRASP binaries and libraries . . . . .	12
2.6	Conventions used in this manual . . . . .	15
<b>3</b>	<b>GRASP Routines: Reading/using Caltech 40-meter prototype data</b>	<b>16</b>
3.1	The data format . . . . .	17
3.2	Function: read_block() . . . . .	21
3.3	Example: reader program . . . . .	23
3.4	Function: find_locked() . . . . .	24
3.5	Example: locklist program . . . . .	25
3.6	Function: get_data() . . . . .	26
3.7	Example: gwoutput program . . . . .	27
3.8	Example: animate program . . . . .	28
3.9	Function: read_sweptsine() . . . . .	32
3.10	Function: calibrate() . . . . .	35
3.11	Example: print_ss program . . . . .	36
3.12	Function: normalize_gw() . . . . .	37
3.13	Example: power_spectrum program . . . . .	39
3.14	Example: calibrate program . . . . .	42
3.15	Example: diag program . . . . .	45
<b>4</b>	<b>GRASP Routines: Reading/using FRAME format data</b>	<b>48</b>
4.1	Time-stamps in the November 1994 data-set . . . . .	50
4.2	Function: fget_ch() . . . . .	51
4.3	Function: framefiles() . . . . .	55
4.4	Example: locklistF program . . . . .	56
4.5	Example: gwoutputF program . . . . .	59
4.6	Example: animateF program . . . . .	61
4.7	Swept-sine calibration information . . . . .	66
4.8	Function: GRcalibrate() . . . . .	68
4.9	Example: print_ssF program . . . . .	69
4.10	Function: GRnormalize() . . . . .	71
4.11	Example: power_spectrumF program . . . . .	73
4.12	Example: calibrateF program . . . . .	77

4.13	Example: diagF program	81
<b>5</b>	<b>GRASP Routines: Gravitational Radiation from Binary Inspiral</b>	<b>84</b>
5.1	Chirp generation routines	85
5.2	Function: phase_frequency()	86
5.3	Example: phase_evoltm program	88
5.4	Detailed explanation of phase_frequency() routine	91
5.5	Function: chirp_filters()	94
5.6	Detailed explanation of chirp_filters() routine	96
5.7	Example: filters program	98
5.8	Practical Suggestion for Setting Up a Large Bank of Filters:	100
5.9	Spin Effects	101
5.10	Function: make_filters()	103
5.11	Stationary phase approximation to binary inspiral chirps	104
5.12	Function: sp_filters()	106
5.13	Example: compare_chirps program	107
5.14	Wiener (optimal) filtering	109
5.15	Function: correlate()	113
5.16	Function: avg_inv_spec()	115
5.17	Function: orthonormalize()	116
5.18	Dirty details of optimal filtering: wraparound and windowing	117
5.19	Function: find_chirp()	123
5.20	Function: freq_inject_chirp()	124
5.21	Function: time_inject_chirp()	125
5.22	Vetoing techniques	126
5.23	Function: splitup()	129
5.24	Function: splitup_freq()	130
5.25	Function: splitup_freq2()	131
5.26	Example: optimal program	132
5.27	Some output from the optimal program	138
5.28	Structure: struct Template	143
5.29	Structure: struct Scope	146
5.30	Function: tau_of_mass()	147
5.31	Function: m_and_eta()	148
5.32	Function: tauspace_area()	150
5.33	Example: area program	151
5.34	The match between two templates	152
5.35	Function: compute_match()	153
5.36	Function: match_parab()	154
5.37	Function: match_cubic()	156
5.38	Example: match_fit program	157
5.39	Function: template_grid()	159
5.40	Function: plot_template()	162
5.41	Example: template program	164
5.42	Example: multifilter program	165
5.43	Optimization and computation-speed considerations	178

<b>6</b>	<b>GRASP Routines: Black hole ringdown</b>	<b>180</b>
6.1	Quasinormal modes of black holes	181
6.2	Function: <code>qn_eigenvalues()</code>	183
6.3	Example: <code>eigenvalues</code> program	184
6.4	Function: <code>sw_spheroid()</code>	186
6.5	Example: <code>spherical</code> program	187
6.6	Example: <code>spheroid</code> program	190
6.7	Function: <code>qn_ring()</code>	192
6.8	Example: <code>ringdown</code> program	193
6.9	Function: <code>qn_qring()</code>	195
6.10	Function: <code>qn_filter()</code>	197
6.11	Function: <code>qn_normalize()</code>	198
6.12	Function: <code>findring()</code>	199
6.13	Function: <code>qn_inject()</code>	200
6.14	Vetoing techniques for ringdown waveforms	201
6.15	Example: <code>qn_optimal</code> program	202
6.16	Structure: <code>struct qnTemplate</code>	207
6.17	Structure: <code>struct qnScope</code>	208
6.18	Function: <code>qn_template_grid()</code>	209
<b>7</b>	<b>GRASP Routines: Stochastic background detection</b>	<b>211</b>
7.1	Data File: <code>detectors.dat</code>	211
7.2	Function: <code>detector_site()</code>	214
7.3	Function: <code>noise_power()</code>	216
7.4	Function: <code>whiten()</code>	218
7.5	Function: <code>overlap()</code>	220
7.6	Example: <code>overlap</code> program	221
7.7	Function: <code>get_IFO12()</code>	223
7.8	Function: <code>simulate_noise()</code>	224
7.9	Function: <code>simulate_sb()</code>	226
7.10	Function: <code>combine_data()</code>	229
7.11	Function: <code>monte_carlo()</code>	230
7.12	Example: <code>monte_carlo</code> program	232
7.13	Function: <code>test_data12()</code>	239
7.14	Function: <code>extract_noise()</code>	240
7.15	Function: <code>extract_signal()</code>	242
7.16	Function: <code>optimal_filter()</code>	244
7.17	Example: <code>optimal_filter</code> program	246
7.18	Discussion: Theoretical signal-to-noise ratio for the stochastic background	250
7.19	Function: <code>calculate_var()</code>	252
7.20	Example: <code>snr</code> program	254
7.21	Example: <code>omega_min</code> program	256
7.22	Function: <code>analyze()</code>	259
7.23	Function: <code>prelim_stats()</code>	261
7.24	Function: <code>statistics()</code>	263
7.25	Example: <code>simulation</code> program	264
7.26	Some output from the simulation program	267

<b>8 GRASP Routines: Supernovae and other transient sources</b>	<b>270</b>
<b>9 GRASP Routines: Periodic and quasi-periodic sources</b>	<b>271</b>
<b>10 GRASP Routines: General purpose utilities</b>	<b>272</b>
10.1 GRASP Error Handling	273
10.1.1 Reporting Errors In GRASP Code	273
10.1.2 How GRASP Error Reports Are Handled	273
10.1.3 Customizing The Default Handlers	274
10.1.4 Writing Custom Error Handlers	275
10.1.5 Functions: GR_start_error(), GR_report_error(), GR_end_error()	276
10.2 Function: grasp_open()	277
10.3 Function: avg_spec()	278
10.4 Function: binshort()	280
10.5 Function: is_gaussian()	281
10.6 Function: clear()	283
10.7 Function: product()	284
10.8 Function: productc()	285
10.9 Function: ratio()	286
10.10 Function: graph()	287
10.11 Function: graph_double()	288
10.12 Function: graph_short()	289
10.13 Function: sgraph()	290
10.14 Function: audio()	291
10.15 Function: sound()	292
10.16 Example: translate	293
10.17 Multi-taper methods for spectral analysis	300
10.18 Function: slepian_tapers()	301
10.19 Function: multitaper_spectrum()	303
10.20 Function: multitaper_cross_spectrum()	305
10.21 Structure: struct removed_lines	306
10.22 Function: fvalue_cmp()	307
10.23 Function: index_cmp()	308
10.24 Function: remove_spectral_lines()	309
10.25 Example: river	311
10.26 Example: ifo_clean	314
10.27 Example: tracker	318
10.28 Example: trackerF	320
<b>11 References</b>	<b>326</b>

## 1 Acknowledgements

This work has been partially supported by National Science Foundation grants to: the University of Wisconsin - Milwaukee PHY95-07740, the LIGO project PHY92-10038 and the LIGO visitors program PHY96-03177. It has also benefited from the contributions of several individuals. Alan Wiseman wrote the chirp generation routines with me in 1995, then entirely re-wrote them for GRASP. Joseph Romano took my (AVS versions of the) stochastic background code, helped to fix a number of the problems, and produced the stochastic background simulation routines contained in GRASP. Sathyaprakash generously provided me with a copy of his routine `grid4.f` which eventually evolved into `template_grid`. Jolien Creighton wrote and documented the section on black hole ringdown, and incorporated the FFTW optimized Fourier transform routines. Jim Mason was "instrumental" in helping me to understand and document the data format used in the 40-meter prototype experiment. Fred Raab, Bob Spero, Stan Whitcomb, Kent Blackburn and others have contributed many useful ideas and insights about how to understand the data stream from a real interferometer. Kip Thorne and his research group provided or called attention to many of these ideas.

## 2 Introduction

### 2.1 The Purpose of GRASP

The analysis and modeling of data from gravitational wave detectors requires specialized numerical techniques. GRASP was developed in collaboration with the Laser Interferometric Gravitational Observatory (LIGO) project in the United States, and contains a collection of software tools for this purpose.

In order that this package be of the most use to the physics community, this package (including all source code) is being released in the public domain. It may be freely used for any purpose with only one condition: GRASP and its author must be acknowledged or referenced in any work or publications to which GRASP made a contribution. This citation must specify the *version number* (for example, 1.0.0) of GRASP. In addition, if the code has been modified in any way, this must also be stated. While the GRASP package is available in the public domain, we do intend to regulate its distribution. You may request a copy of GRASP for your personal use, or for use at your own institution, but you must not distribute it outside that group. In addition, one person at each institution must be designated as the “responsible party” in charge of the GRASP package.

GRASP is intended for a broad audience, including those users whose main interest is in running simulations and analyzing data, and those users whose main interest is in testing new data analysis techniques or incorporating searches for new types of gravitational wave sources. The GRASP package includes a “cook-book” of documented and tested low-level routines which may be incorporated in user code, and simple example programs illustrating the use of these routines. GRASP also includes a number of high level user applications built from these routines.

We are always interested in extending the capabilities of GRASP. Suggestions for changes or additions, including reports of bugs or corrections, improvements, or extensions to the source code, should be communicated directly to the author.

### 2.2 Quick Start

If you hate to read manuals, and you just want to try something, here’s a suggestion. This assumes that the GRASP package has been installed by your local system administrator in a directory accessible to you, such as `/usr/local/GRASP` and that some 40-meter data (old-format) has also been installed, for example in `/usr/local/GRASP/data`.

If you want to try running a GRASP program, type

```
setenv GRASP_DATAPATH /usr/local/GRASP/data/19nov94.3
```

to set up a path to the data, then go to the GRASP directory:

```
cd /usr/local/GRASP/src/examples/examples_40meter
```

and try running one of the executables:

```
./locklist
```

will print out a list of the locked data segments from run 3 on 19 November 1994. A more interesting program to run (in the same directory) is

```
./animate | xmgr -pipe
```

which will produce an animated display of the IFO output. Note that in order for this to work, you will need to have the `xmgr` graphing program in your path. (Please see the comment about `xmgr` in Section 3.8).

If you only have data that has been distributed in the FRAME format, type

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/data/19nov94.3.frame
```

to set up a path to the data, then go to the GRASP directory:

```
cd /usr/local/GRASP/src/examples/examples_frame
```

and try running one of the executables:

```
./locklistF
```

will print out a list of the locked data segments from run 3 on 19 November 1994. A more interesting program to run (in the same directory) is

```
./animateF | xmgr -pipe
```

which will produce an animated display of the IFO output. Note that in order for this to work, you will need to have the `xmgr` graphing program in your path. (Please see the comment about `xmgr` in Section 3.8).

If you want to try writing some GRASP code, a simple way to start is to copy one of the example programs, and the Makefile, into your personal directory, and edit that:

```
mkdir ~/GRASP
```

```
cp /usr/local/GRASP/src/examples/examples_40meter/gwoutput.c ~/GRASP
```

```
cp /usr/local/GRASP/src/examples/examples_40meter/Makefile ~/GRASP
```

```
cd ~/GRASP
```

Now make editing changes to the file `gwoutput.c`, and when you are done, edit the `Makefile` that you have copied into your home directory. Find the line that reads:

```
all: ... gwoutput ...
```

and delete everything to the right of the colon except `gwoutput` from that line (but leave a space after the colon). Then type:

```
make gwoutput
```

to recompile this program. To run it, simply type:

```
gwoutput.
```

In general, if you want to modify GRASP programs, this is the simplest way to start.

### 2.3 A few words about data formats

The GRASP package was originally written for analysis of data in the "old" format, which was used in the Caltech 40-meter IFO laboratory prior to 1996. Starting in 1997, the LIGO project, and a number of other gravity-wave detector groups, have adopted the VIRGO FRAME data format. Almost every example in the GRASP package has equivalent programs to read and analyze data in either format. For example `animate` and `animateF` are two versions of the same program. The first reads data in the old format, the second reads data in the FRAME format. We have also included with GRASP a translation program that translates data from the old format to the new format (see `translate` in Section 10.16).

After careful thought, the LIGO management has decided to only distribute the November 1994 data in the FRAME format, except to a small number of groups (belonging to the *Data Translation Group*) who are responsible for ensuring that the translated data set contains the same information as the original! The initial distributions of GRASP will include both old-format and new-format code. However after a reasonable period of time, the old-format data and code will be removed from the package. So please be aware that the old-format material will be reaching the end of its useful lifetime fairly soon; we do not recommend investing much effort in these.

If you want to develop or work on data analysis algorithms, you will want to have access to this data archive. Because many people contributed to taking this data, and because the LIGO project wants to maintain control of its use and distribution, *this data set is NOT in the public domain*. However, you may request a copy for your use, or for use by your research group. Write to: Director of the LIGO Laboratory, Mail Stop 51-33, California Institute of Technology, Pasadena, CA 91125. The data set is available in `tar` format on two Exabyte 8500c format tapes.

In order to use the data in the FRAME format, you will need to have access to the FRAME libraries. These are available from the VIRGO project; they may be downloaded from the site <http://lapphp.in2p3.fr/>. Contact Benoit Mours [mours@lapp.in2p3.fr](mailto:mours@lapp.in2p3.fr) for further information.



## 2.4 GRASP Hardware & Software Requirements

GRASP was developed under the Unix (tm) operating system, on a Sun workstation network. The package is written in POSIX/ANSI C, so that GRASP can be compiled and used on any machine with an ANSI C compiler. All operating system calls are POSIX-compliant, which is intended to keep GRASP as portable to different platforms as possible. The main routines could also be linked to user code written in other languages such as Fortran or Pascal; the details of this linking, and the conventions by which Fortran and C (or Pascal and C) routines communicate are implementation dependent, and not discussed here.

Several of the high-level applications in GRASP can be run on parallel computer systems. These can be either dedicated parallel computers (such as the Intel Paragon or IBM SP2 machines) or a network of scientific workstations. The parallel programming in GRASP is implemented with version 1.1 of the Message Passing Interface (MPI) library specification [2]. All major computer system vendors currently support this standard, so GRASP can be easily compiled and used on virtually any parallel machine. In addition, there is a public-domain implementation of MPI called "mpich" [3] which will run MPI-based programs on networks of scientific workstations. This makes it easy to do "super-computing at night" by running GRASP on a network of workstations. Further information on MPI is available from the web site <http://www.mcs.anl.gov/mpi/>. The mpich implementation is available from <http://www.mcs.anl.gov/mpi/mpich/>. By the way, if you don't have access to parallel machines (or have no interest in parallel computing) don't worry! The only parallel code in GRASP is found in "top-level" applications; all of the functions in the GRASP library, and most of the examples, can be used without any modifications on a single processor, stand-alone computer.

GRASP makes use of a number of standard numerical techniques. In general, we use version 2.6 of the routines from "*Numerical Recipes in C: the art of scientific computing*" [1]. These routines are widely used in the scientific community. The full source code, examples, and complete documentation are provided in the book, and are also available (for about \$50) in computer readable form. Ordering information and further details are available from <http://cfata2.harvard.edu/numerical-recipes/>. These routines are extremely useful and beautifully-documented; if you don't already have them available for your use, you should!

In general, output from GRASP is in the form of ASCII text files. We assume that the user has graphing packages available to visualize and interpret this output. Our personal favorite is `xmgr`, available in the public domain from the site <http://plasma-gate.weizmann.ac.il/Xmgr/> which also lists mirror sites in Europe and USA. (Please see the comment about `xmgr` in Section 3.8). In some cases we do output "complete graphs" for `xmgr`. We do also output some data in the form of PostScript (tm) files. Previewers for postscript files are widely available in the public domain (we like GhostView).

## 2.5 GRASP Installation

As we have just explained, GRASP requires access to *Numerical Recipes in C* libraries and to MPI and MPE libraries. These packages must be installed, and then within GRASP a path to these libraries must be defined. This can be done by editing a single file, and then running a shell script. This section explains each of these steps in detail.

All of the site-specific information is contained in a single file `SiteSpecific` in the top-level directory of GRASP. This file contains a number of variables whose purpose is explained in this section. These variables must be correctly set before GRASP can be used; the definitions contained in `SiteSpecific` (as distributed) are probably *not* appropriate for your system, and will therefore require modification.

## 2.5.1 GRASP File Structure

The code for GRASP can be installed in a publicly-available directory, for example `/usr/local/GRASP`. (It can also be installed "privately" in a single user's home directory, if desired.) The name of this top-level directory must be set in the file `SiteSpecific` which is contained in the top-level GRASP directory. To do this, edit the file `SiteSpecific` and set the variable `GRASP_HOME` to the appropriate value, for example `GRASP_HOME=/usr/local/GRASP`. Please note that the installation scripts are not designed to "build" in one location and "install" in a separate location. You should go through the installation procedure in the same directory where you eventually want the GRASP package to reside.

Within this top level directory resides the entire GRASP package. The directories within this top level are:

`data/` Contains (both real and simulated) interferometer data, or symbolic links to this data. See the comments in Section 3 to find out how to obtain this data.

`parameters/` Contains parameters such as site location information, and estimated power spectra/whitening functions of future detectors.

`doc/` Documentation (in TeX, PostScript, DVI, and PDF formats) including this users guide.

`man/` This may be used in the future for UNIX on-line manual pages.

`testing/` This will eventually contain a suite of programs that test the GRASP installation.

`include/` Header files used to define structures and other common types in the code. This also include the ANSI C prototypes for all the GRASP functions.

`src/` Source code for analyzing various aspects of the data stream, distributed among the following directories:

`40-meter/` Reading data tapes produced on the Caltech 40 meter prototype prior to 1997.

`inspiral/` Binary inspiral analysis (including optimal filtering and vetoing).

`ringdown/` Black hole horizon ringdown (including optimal filtering). This can be used to filter for *any* exponentially-decaying sinusoid.

`stochastic/` Stochastic background detection (including optimal filtering and simulated signal production)

`transient/` Supernovae and other transient sources.

`periodic/` Searches for pulsars and other periodic and quasi-periodic sources.

`utility/` General purpose utility routines.

`examples/` The source code for all of the examples given in this manual (organized by section).

`optimization/` Additional library routines for optimizing GRASP operation of specific platforms (i.e., supercomputers).

`lib/` Object libraries.

`bin/` Executable applications and programs.

## 2.5.2 Accessing *Numerical Recipes in C* libraries

GRASP makes use of many of the functions and subroutines from *Numerical Recipes in C* [1]. These functions and subroutines are available in Fortran, Pascal, Basic, Kernighan and Ritchie (K&R) C, and ANSI-C versions; you will need the ANSI-C routines. The source code for these functions (both \*.c and \*.h files) must be installed in a directory (for example, /usr/local/recipes/src) and the compiled object modules (\*.o files) must be archived into a single library file (\*.a file). The instructions for this are included in the distribution of the source code for *Numerical Recipes*. In the end, a file called librecipes.c.a must be put into a directory where it is available to the linker for compilation. A good place to put this library is in /usr/local/recipes/lib/librecipes.c.a. When you run the command that installs GRASP, the linker needs to be able to find these libraries. The file SiteSpecific must then contain the line RECIPES\_LIB = /usr/local/recipes/lib near the top of the file.

It is frequently useful, for debugging purposes, to be able to link with both “debug” and “profile” versions of the libraries. For this reason, we recommend that users actually create *three separate libraries* of *Numerical Recipes* functions:

/usr/local/recipes/lib/librecipes.c.a: a library compiled for fast execution, with optimization options (for example, -O3 or -xO4) turned on during compilation.

/usr/local/recipes/lib/librecipes.cg.a: a library compiled for debugging, with the debug option (typically, -g) turned on during compilation. Note that in order to use a debugger with this library, and to be able to step “within” the *Numerical Recipes* functions, the debugger must be able to locate the source code for *Numerical Recipes*. Thus, after *Numerical Recipes* is compiled and installed, its \*.c and \*.h source files must be left in their original locations and not deleted or moved.

/usr/local/recipes/lib/librecipes.cp.a: a library compiled for profiling, with the profiling option (typically, -pg or -xpg for “gprof” or -p for “prof”) turned on during compilation.

One can then easily compile GRASP code with the appropriate library by setting LRECIPES in SiteSpecific. For example to run code as rapidly as possible one would set LRECIPES = recipes.c. However to compile code for debugging it would be preferable to set LRECIPES = recipes.cg. (Note that rather than recompiling the entire GRASP package in this way, one can simply modify the value of LRECIPES within the desired Makefiles and then recompile only the code of interest.)

We have encountered one minor problem with the *Numerical Recipes in C* routines. Unfortunately the authors of these routines choose to name one of their routines select(). This name conflicts with a POSIX name for one of the standard operating system calls. In linking with certain libraries (for example the MPI/MPE libraries) this can generate conflicts where the linker attaches the select() call to the entry point from the wrong library. We suggest that you fix this as follows. Before building the *Numerical Recipes* libraries, edit the source files recipes/rofunc.c, recipes/select.c, and recipes/select.c.orig changing each occurrence of select( to NRselect(. You will have to do this in (respectively) three places, one place and one place in these files. Then edit the file include/nr.h making the same change of select( to NRselect( in one place. This will eliminate the select() routine from the *Numerical Recipes* library, replacing it with a routine called NRselect(), and eliminating any possible naming conflict from the library.

## 2.5.3 Accessing MPI and MPE libraries

To enable use of the parallel processing code included with GRASP, one needs to link the code with an MPI function call library. (If you do not intend to use any of the multiprocessing code, we’ll tell you

what to do.) For performance monitoring purposes, we also make calls to the Message Passing Environment (MPE) library, which is included with `mpich` [3]. If these function libraries are not currently available on your system, you should obtain the public domain implementation `mpich` from the URL given above, and follow the instructions required to build the MPI/MPE libraries for your system. After the installation process is complete, the necessary libraries will be contained in a library archive, for example `/usr/local/mpi/lib/libmpi.a` and `/usr/local/mpe/lib/libmpe.a`. The path to these libraries is set in the file `SiteSpecific` by means of the variable `MPI_LIBS`. A typical line in `SiteSpecific` might then read:

```
MPI_LIBS=-L/usr/local/mpi/lib -lmpi -lmpe.
```

You must also set `BUILD_MPI= true` in `SiteSpecific`. Finally, in order to include appropriate header files in any MPI programs, you will need to include a path to these header files in the file `SiteSpecific`. You can do this by setting `MPI_INCLUDES` in the file `SiteSpecific`. A typical installation might have

```
MPI_INCLUDES = -I/usr/local/mpi/include.
```

NOTE: If you don't want to use *any* of the MPI code, just set:

```
BUILD_MPI= false
```

in `SiteSpecific`. All the other MPI-specific defines are then ignored.

#### 2.5.4 Accessing FRAME libraries

The LIGO and VIRGO detector projects have recently decided to standardize the format which their data will be recorded in (see Section 2.3). The standard is called the FRAME format, and is still under development. It appears quite possible that a number of other gravitational-wave detector groups will also adopt this same format. The GRASP package contains, for every example program, both FRAME format and old format versions. It also contains an translation program which converts data from the "old 1994" format into the new FRAME format.

Unless you are in one of the small number of groups with access to the old-format data, you will need to obtain the FRAME libraries. These are available from the VIRGO project; they may be downloaded from the site <http://lapphp.in2p3.fr/virgo/FrameL>. Contact Benoit Mours [mours@lapp.in2p3.fr](mailto:mours@lapp.in2p3.fr) for further information. In the `SiteSpecific` file, if you need the FRAME libraries, set a pointer to the directory containing them. NOTE: If you don't need the FRAME libraries, just set:

```
BUILD_FRAME = false
```

in `SiteSpecific`. All the other FRAME-specific defines are then ignored.

#### 2.5.5 Real-time 40-meter analysis

The analysis tools in the GRASP package can be used to analyze data in real-time, as it is recorded by the DAQ system. This facility is primarily for the use of experimenters working in the Caltech 40-meter lab. and will probably not be of use to anyone outside of that group.

In order to use the GRASP tools in real time, one needs to link to a set of EPICS (Experimental Physics and Industrial Control System) libraries, that are not otherwise needed. These permit the GRASP code to interrogate the EPICS system to find out the names and locations of the most-recently written FRAMES of data.

#### 2.5.6 Making the GRASP binaries and libraries

To make the GRASP libraries and executables described in this manual, please follow these directions. It should only take a few minutes to do this.

1. Within the main GRASP directory is a file called `SiteSpecific`. Make a copy of `SiteSpecific` called `SiteSpecific.save`. This way, if you mess up the installation, you can start over easily.
2. Now edit `SiteSpecific` so that `GRASP_HOME` has the correct path, for example  
`GRASP_HOME=/usr/local/GRASP`.  
 This must be the name of the directory on your system in which GRASP resides. If you are not the superuser and are installing GRASP only for your own use, you can set this path to point somewhere in your own home directory, and install GRASP there.
3. Find out where *Numerical Recipes in C* is installed on your system. Within `SiteSpecific` set `RECIPES_LIB` to point to the directory containing these libraries. For example  
`RECIPES_LIB=/usr/local/numerical_recipes/lib`.  
 If *Numerical Recipes in C* is not installed on your system, you will have to obtain a copy, and install it, following the directions to create the library file `librecipes.c.a`. Note that as described above, you might also want to create debugging libraries `librecipes.cg.a` and profiling libraries `librecipes.cp.a`.
4. Within `SiteSpecific` set `LRECIPES` to the name of the *Numerical Recipes in C* library you wish to use, for example  
`LRECIPES=recipes.c`.
5. If you intend to use the MPI code, set `BUILD_MPI= true`, otherwise set it to `false`. In this latter case, any MPI-specific defines are ignored, and no code that makes use of MPI/MPE function calls is compiled. (This is a shame – these are some of the nicest programs in the GRASP package. We urge you to reconsider building the `mpich` package on your system!)
6. Within `SiteSpecific` set `MPI_LIBS` to point to the directory containing the MPI/MPE libraries, and to specify the names of the link archives, for example  
`MPI_LIB=-L/usr/local/mpi/lib -lmpi -lmpe`.  
 Note that if you use the version of `mpicc` which is distributed with `mpich` you may not need to have any of the MPI libraries referenced here; the compiler may find them automatically.
7. Within `SiteSpecific` set `MPI_INCLUDES` to point to the directory which contains the MPI and MPE header (`*.h`) files, for example  
`MPI_INCLUDES = -I/usr/local/mpi/include`.
8. Within `SiteSpecific` set `MPICC` to the name of your local MPI C compiler, for example:  
`MPICC = /usr/local/bin/mpicc`.  
 You can include any compilation flags (say, `-g`) on this line also.
9. If you intend to use the FRAME code, set `BUILD_FRAME = true`, otherwise set it to `false`. In this latter case, any FRAME-specific defines are ignored, and no code that makes use of FRAME function calls is compiled.
10. Within `SiteSpecific` set `FRAME_DIR` to point to the directory which contains the LIGO/VIRGO format FRAME software, for example  
`FRAME_DIR=/usr/local/frame`.  
 This directory should contain `lib/libFrame.a` and `include/FrameL.h`. If you don't need the FRAME libraries, just leave this entry blank.

11. Within `SiteSpecific`, if you want to use GRASP for real-time analysis in the Caltech 40-meter lab, set `EPICS_INCLUDES` to point to the directory containing the EPICS \*.h include files, and set `EPICS_LIBS` to point to the directory containing the EPICS libraries. Finally, you need to uncomment the `BUILD_REALTIME` define statement. If you do not intend to use your GRASP installation for real-time analysis in the 40-meter lab, simply leave these three definitions commented out with a hash sign (#).
12. At the bottom of `SiteSpecific` are several define statements, which are currently commented out. These are primarily intended for production code; by undefining these lines you replace a cube root function and some trig functions in the code with faster (but less accurate) in-line approximations. We suggest that you leave these commented out. (You might want to consider uncommenting them if you are burning thousands of node hours on a large parallel machine - but you do so at your own risk!)
13. There are also lines that are currently commented out, which allow you to overload functions defined in the libraries and reference libraries of optimized functions. Once again, leave these commented out unless you want to replace standard *Numerical Recipes* functions with optimized versions. Currently, we support three sets of optimized libraries:
  - The CLASSPACK optimized FFT's for the Intel Paragon.
  - The Sun Performance Library's optimized FFT for the Sun SPARC architecture.
  - The Cray/SGI optimized FFT for the RS10000 and other MIPS architectures.
  - The FFTW (Fastest Fourier Transform in the West), which will run on any computer. This is a public domain optimized FFT package, available from the web site:  
<http://theory.lcs.mit.edu/~fftw>  
If you don't have an optimized FFT routine for your computer, we highly recommend this - it is a factor of three (or more) faster than *Numerical Recipes*.

Further details may be found in the `src/optimization` subdirectory of GRASP. If you want to use these optimized library routines, first go into the appropriate subdirectory of `src/optimization` and build the optimized library routine using the makefiles's that you find there; then uncomment the appropriate lines in `SiteSpecific` and follow the instructions given here.

14. Now, in the top level GRASP directory, execute the shell script `InstallGRASP`, by typing the commands:

```
chmod +x InstallGRASP
./InstallGRASP
```

From here on, the remainder of the installation should proceed automatically. The `InstallGRASP` script takes information contained in the `SiteSpecific` file, uses it to create Makefile's in each `src` subdirectory, and runs `make` in each of those directories.

The Makefile in each directory is constructed by concatenating the file `SiteSpecific` with a file called `Makefile.tail` in each individual directory. If you want to try changing the compilation procedure, you can modify the Makefile in a given directory. However this will be created each time that you run `InstallGRASP`; for changes to become permanent they should either be made in `SiteSpecific` or in the `Makefile.tail`'s.

Note that this installation procedure and code has been tested on the following types of machines: Sun 4 (Solaris), DEC AXP (OSF), IBM SP2 (AIX), HP 700 (HPUX), Intel (Linux), Intel Paragon. If you run into problems with our installation scripts, please let us know so that we can fix them.

If you want to experiment with GRASP or to write code of your own, a good way to start is to copy the `Makefile` and the example (`*.c`) programs from the `src/examples` directory into a directory of your own. You can then edit one of the example programs, and type “make” within your directory to compile a modified version of the program.

If you wish to modify the code and libraries distributed with GRASP (in other words, modify the functions described in this manual!) the best idea is to use `cp -r` to recursively copy the entire GRASP directory structure (and all associated files) into a private directory which you own. You can then install your personal copy of GRASP, by following the directions above. This will permit you to modify source code within any of the `src` subdirectories; typing `make` within that directory will automatically re-build the GRASP libraries that you are using. By the way, if you are modifying these functions to fix bugs or repair problems, or if you have a “better way” of doing something, please let us know so that we can consider incorporating those changes in the general GRASP distribution.

## 2.6 Conventions used in this manual

The conventions used in this manual are not strict ones. However we do observe a few general rules:

1. Words or lines that you might type on a computer (commands, filenames, names of C-language functions, and so are) are generally indicated in teletype font.
2. When a function is described, the arguments which are *inputs* and those which are *outputs* (or those which are both) are indicated. Thus, for example the function `add(int a, int b, int* c)` which sets `*c = a+b` is described by:

a: Input. One of the two integers that are added together.

b: Input. The second of these integers.

c: Output. Set to the sum of a and b.

Note that technically this is incorrect, because of course in C even the “output arguments” are really just inputs; they are pointers to an address in memory that the routine is supposed to modify. And technically, the statement that “c is set to...” is not correct, since in fact it is the integer pointed to by c (denoted `*c`) that is set. However we find that this convention makes it much easier to read the function descriptions!

3. Most of the time, the example programs using GRASP functions are given explicitly in the manual, so you can see the GRASP functions “in use”. Because these examples are illustrative, they are generally “pared down” as much as possible (for example, default values of adjustable parameters are hard-wired in, rather than prompted for).
4. Routines and example programs in GRASP generally begin with the line:  
`#include "grasp.h"`  
which includes the prototypes for all GRASP functions as well as the library header files `stdio.h`, `stdlib.h`, `math.h`, `values.h`, and `time.h`. The GRASP include file “`grasp.h`” can be found in the `include` subdirectory of GRASP.

### 3 GRASP Routines: Reading/using Caltech 40-meter prototype data

There is a good archive of data from the Caltech 40-meter prototype interferometer. Although the interferometer is only sensitive enough to detect events like binary inspiral within  $\approx 10$ kpc (the distance to the galactic center) its output is nevertheless very useful in studying data analysis algorithms on real-world interferometer noise. This data was taken during the period from 1993 to 1996; for our purposes here we will concentrate on data taken during a one-week long observation run from November 14-21, 1994. The original data is contained on 11 exabyte tapes with about 46 total hours of data; the instrument was in lock about 88% of the time. The details of this run, the status of the instrument, and the properties of this data are well-described in theses by Gillespe [19] and Lyons [20].

The GRASP package includes routines for reading this data. The data is not read directly from the tapes themselves; the data instead must be read off the tapes and put onto disk (or into pipes) using a program called `extract`. The GRASP routines can then be used to read the resulting files. While the GRASP routines can be used without any further understanding of the data format, it is very helpful to understand this in more detail. Note that these data formats and the associated structures were defined years before GRASP was written; we did not choose this data format and should not be held accountable for its shortcomings. We have included a preliminary translator that translates the data from this old 1994 format into the new LIGO/VIRGO frame format. The program `translate` may be found in the GRASP `src/examples/examples_utility` directory, and is documented in the Section on GRASP general purpose utilities.

If you want to develop or work on data analysis algorithms, you will want to have access to this data archive. Because many people contributed to taking this data, and because the LIGO project wants to maintain control of its use and distribution, *this data set is NOT in the public domain*. However, you may request a copy for your use, or for use by your research group. Write to: Director of the LIGO Laboratory, Mail Stop 51-33, California Institute of Technology, Pasadena, CA 91125. The data set is available in `tar` format on two Exabyte 8500c format tapes. Each directory (for a different run on a different day) occupies the following amount of space (in mbytes):

14nov94.1	647
14nov94.2	913
18nov94.1	1041
18nov94.2	1121
19nov94.1	1554
19nov94.2	1074
19nov94.3	1250
19nov94.4	1206
20nov94.1	1146
20nov94.2	1173
20nov94.3	1543

Each of these directories contains the `channel.*` files and the `swept-sine.ascii` swept-sine calibration files. In this manual, we assume that these directories (or links to them) have been placed where you can access them. The GRASP programs that use this data determine its location by means of the environment variable `GRASP_DATAPATH`. You can set this by typing (for example)

```
setenv GRASP_DATAPATH /usr/local/data/19nov94.3
```

to access the data from run 3 on November 19th. System administrators: after installing these directories in a convenient place on your machine, we recommend that you install a set of links to them in the directory `data` within the GRASP home directory. This way your users can find them without asking you for the location!



WARNING: this data was written on a “big-endian” machine (the sun-4 workstation is an example of such a machine). The floats are in IEEE 754 floating-point format. Attempts to read the data in its distributed form on a “little-endian” machine (such as Intel 80\*86 computers) will yield garbage unless the bytes are properly swapped. The routines used to read data (in particular, the function `read_block()`) test the byte order of the machine being used, and swaps the byte order if the machine is “little-endian”. This introduces some inefficiency if you are running on a “little-endian” machine, but is preferable to having two copies of the data, one for each architecture. If you are doing all of your work on a “little-endian” machine and you want to avoid this inefficiency, write a program which properly swaps the byte orders of the header blocks (which are in 4-byte units) and then also properly swaps the byte order of the data blocks (which are 2-byte units) and reformat the raw data files. Then modify the `read_block()` data so that it no longer swaps the bytes on your machine.

### 3.1 The data format

Data is written onto the exabyte tapes in blocks about 1/2 megabyte in size. The format of the data on the tapes is as shown in Table 1. The tape begins with a main header (denoted “mh” in the table). This is

mh	0's	0's	mh	0's	0's	mh	gh	0's	data	mh	gh	0's	data	...
1024	1024	1024	1024	1024	1024	1024	1024	1024	$1024 \times n$	1024	1024	1024	$1024 \times n$	...

Table 1: Format of Exabyte data tapes (first row: content, second row: length in bytes).

followed by a set of zeros, padding the length of the header block to 1024 bytes. There is then an empty block of 1024 bytes containing zeros. This pattern is repeated until the first block containing actual data. This is signaled by the appearance of a main header, followed by a gravity header (denoted “gh” in the figure above). These two headers are padded with zeros to a length of 1024 bytes. This is then followed by a set of data (the length of this set is a multiple of 1024 bytes). Information about the length of the data sets is contained in the headers. The data sets themselves consist of data from a total of 16 channels, each of which comes from a 12-bit A to D converter. Four of the 16 channels are fast (sample rates a bit slower than 10kHz) and the remaining 12 channels are slow (sample rates a bit slower than 1kHz). The ratio of sample rates is exactly 10 : 1. Within the blocks labeled “data”, these samples are interleaved. The information content of the different channels is detailed on page 136 of Lyon’s thesis [20], and is summarized in Table 3.

The program `extract` reads data off the tapes and writes them into files. One file is produced for each channel; typically these files are named `channel.0` → `channel.15`. The complete set of these files for the November 1994 run fits onto two Exabyte tapes (in the 8500c compressed format). The information in these files begins only at the moment when the useful data (starting with the gravity header blocks) begins to arrive. The format of the data in these `channel.*` files is shown in Table 2. Here the main headers are

block 0				block 1				block 2				block 3				...
mh	bh	0's	data	mh	bh	0's	data	mh	bh	0's	data	mh	bh	0's	data	...
1024		cs		1024		cs		1024		cs		1024		cs		...

Table 2: Format of a `channel.0` → `15` file (first row: block number, second row: content, third row: length in bytes).

the same as before, however the headers that follow them are called binary headers (denoted by “bh” in the table). The length of the data stream (in bytes) is called the “chunksize” and is denoted by “cs” in Table 2. We frequently reference the data in these files by “block number” and “offset”. The block number is an integer  $\geq 0$  and is shown in Table 2. The offset is an integer which, within a given block, defines the offset

of a data element from the first data element in the block. In a block containing 5000 samples, these offsets would be numbered from 0 to 4999.

The structure of the binary headers is

```
struct ld_binheader {
```

float elapsed\_time: This is the total elapsed time in seconds, typically starting from the first valid block of data, from the beginning of the run.

float datarate: This is the sample rate of the channel, in Hz.

```
};
```

The structure of the main headers is

```
struct ld_mainheader {
```

int chunksize: The size of the data segment that follows, in bytes.

int filetype: Undocumented; often 1 or 2.

int epoch\_time\_sec: The number of seconds after January 1, 1970, Coordinated Universal Time (UTC) for the first sample. This is the quantity returned by the function time() in the standard C library.

int epoch\_time\_msec: The number of milliseconds which should be added to the previous quantity.

int tod\_second: Seconds after minute, 0-61 for leap second.

int tod\_minute: Minutes after hour 0-59.

int tod\_hour: Hour since midnight 0-23.

int date\_day: Day of the month, 1-31.

int date\_month: Month of the year, 0-11 is January-December.

int date\_year: Years since 1900.

int date\_dow: Days since Sunday, 0-6.

int sub\_hdr\_flag: Undocumented.

```
};
```

Note: in the original headers, these int were declared as long. They are in fact 4-byte objects, and on some modern machines, if they are declared as long they will be incorrectly interpreted as 8-byte objects. For this reason, we have changed the header definitions to what is show above.

For several years, the extract program contained several bugs. One of these caused the channel . \* to have no valid header information apart from the elapsed time and datarate entries in the binary header, and the chunksize entry in the main header. All the remaining entries in the main header were either incorrect or nonsensical. This bug was corrected by Allen on 14 November 1996; data files produced from the tapes after that time should have valid header information.

There was also a more serious bug in the original versions of extract. The typical chunksize of most slow channels is 10,000 bytes (5,000 samples) and the chunksize of most fast channels is 100,000 bytes (50,000 samples) but until it was corrected by Allen on 14 November 1996, the extract program would in apparently unpredictable (though actually quite deterministic) fashion "skip" the last data point from the slow channels or the last ten data points from the fast channels, giving rise to sequences of 4,999 samples

from the slow channels, and correspondingly 49,990 samples from the fast channels. Not surprisingly, these missing data points gave rise to strange "gremlins" in the early data analysis work; these are described in Lyon's thesis [20] on pages 150-151. These missing points were simply cut out of the data stream as shown in Figure 1; rather like cutting out 1 millisecond of a symphony orchestra every 5.1 seconds; this gives rise to "clicks" which excited the optimal filters. This problem is shown below; data taken off the tapes after 14 November 1996 should be free of these problems.

There are a couple of caveats regarding use of these "raw data" files. First, in the `channel.*` files, there can be, with no warning, large segments of missing data. In other words, a block of data with time stamp 13,000 sec, lasting 5 sec, can be followed by another data block with a time stamp of 14,000 sec (i.e., 995 sec of missing data). Also, the time stamps are stored in single precision floats, so that after about 10,000 sec they no longer have a resolution better than a single sample interval. When we read the data, we typically use the time-stamp on the first data segment to establish the time at which the first sample was taken. Starting from that time, we then determine the time of a data segment by using `elapsed_time`, since the millisecond time resolution of `epoch_time_msec` is not good enough. (See the comments in Section `ss:timestamp`).

For our purposes, the most useful channels are `channel.0` and `channel.10`. Channel 0 contains the actual voltage output of the IFO. This is typically in the range of  $\pm 100$ . Later, we will discuss how to calibrate this signal. Channel 10 contains a TTL locked level signal, indicating if the interferometer was in lock. This is typically in the range from 1 to 10 when locked, and exceeds several hundred when the interferometer is out of lock. Note: after coming into lock you will notice that the IFO output is often zero (with a bit of DC offset) for periods ranging from a few seconds to a minute. This is because the instrument output amplifiers are typically overloaded (saturated) when the instrument is out-of-lock. Because they are AC coupled, this leads to zero output. After the instrument comes into lock, the charge on these amplifiers gradually bleeds off (or one of the operators remembers to hit the reset button) and then the output "comes alive". So don't be puzzled if the instrument drops into lock and the output is zero for 40 seconds afterwards!

The contents of the `channel.*` files was not the same for all of the runs. Lyon's thesis [20] gives a chart on page 136 with some "typical" channel assignments. The channel assignments during these November 1994 data runs are listed in a log book; they were initially chosen on November 14, then changed on November 15th and again on November 18th; these assignments are shown in Table 3. (Note that the chart on page 136 of Lyon's thesis describes the channel assignments on 15 November 94, a day when no data was taken.)

Channel Number	Description $\leq$ 14 November 94	Description $\geq$ 18 November 94
0	IFO output	IFO output
1	unused	magnetometer
2	unused	microphone
3	microphone	unused
4	dc strain	dc strain
5	mode cleaner pzt	mode cleaner pzt
6	seismometer	seismometer
7	unused	slow pzt
8	unused	power stabilizer
9	unused	unused
10	TTL locked	TTL locked
11	arm 1 visibility	arm 1 visibility
12	arm 2 visibility	arm 2 visibility
13	mode cleaner visibility	mode cleaner visibility
14	slow pzt	unused
15	arm 1 coil driver	arm 1 coil driver

Table 3: Channel assignments for the November 1994 data runs. Channels 0-3 are the “fast” channels, sampled at about 10 kHz; the remaining twelve are the “slow” channels, sampled at about 1KHz.

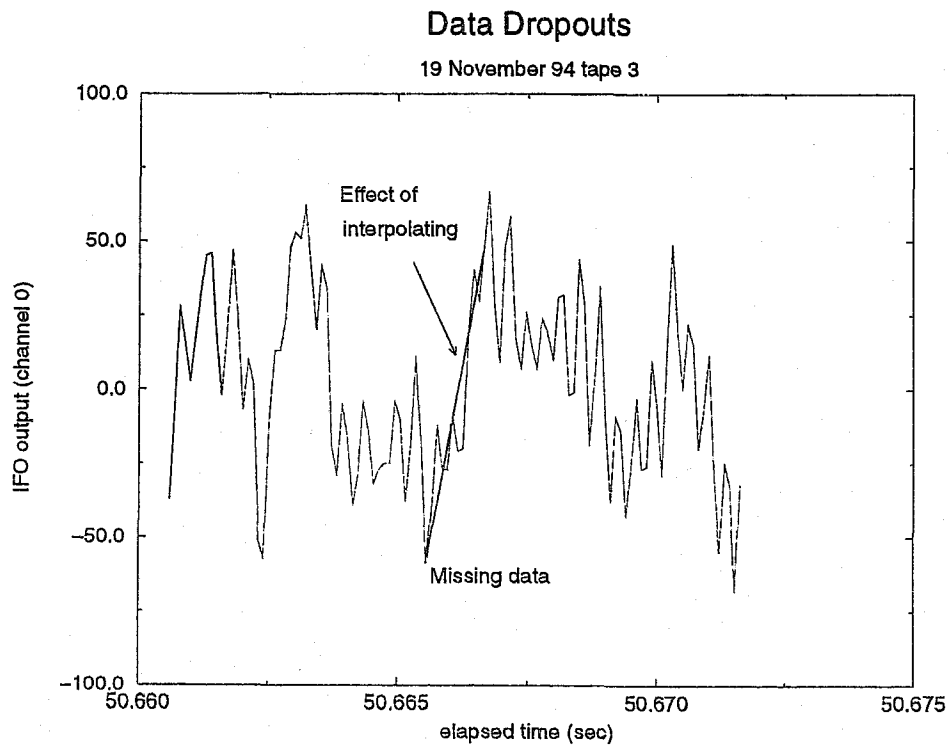


Figure 1: This shows the appearance of channel . 0 before and after the extract program was repaired (on 14 November 1996) to correctly extract data from the Exabyte data tapes. The old version of extract dropped the ten data points directly above the words “missing data”; in effect these were interpolated by the diagonal line (but with ten times the slope shown since everything in between was missing).

### 3.2 Function: read\_block()

```
int read_block(FILE *fp, short **here, int *n, float *tstart, float *srate, int
allocate, int *nalloc, int seek, struct ld_binheader* bh, struct ld_mainheader*
mh)
```

This function efficiently reads one block of data from one of the channel . \* data files, operating in sequential (not random) access. On first entry, it detects the byte-ordering of the machine that it is running on, and swaps the byte order if the machine is "little-endian" (the data was originally written in "big-endian" format, and is distributed that way). It will also print a comment (on first entry) if the machine is not big-endian.

The arguments are:

**fp:** Input. A pointer to the channel . \* file being read.

**here:** Input/Output. A pointer to an array of shorts, which is where the data will be found when read\_block() returns. If allocate=0, then this pointer is input. If allocate is non-zero, then this pointer is output.

**n:** Output. A pointer to an integer, which is the number of data items read from the block, and written to \*here. These data items are typically short integers, so the number of bytes output is twice \*n.

**tstart:** Output. The time stamp (elapsed time since beginning of the run) at the start of the data block. Taken from the binary header.

**srate:** Output. The sample rate, in Hz, taken from the binary header.

**allocate:** Input. The read\_block() function will place the data that it has read in a user defined array if allocate is zero. If allocate is set, it will use malloc() to allocate a block of memory, and set \*here to point to that block of memory. Further calls to read\_block() will then use calls to realloc() if necessary to re-allocate the size of the block of memory, to accommodate additional data points. Note that in either case, read\_block() puts into the array only the data from the next block; it over-writes any existing data in memory.

**nalloc:** Input/Output. If allocate is zero, then this is used to tell read\_block() the size (in shorts) of the array \*here. An error message will be generated by read\_block() if this array is too small to accommodate the data. If allocate is nonzero, then this integer is set (and reset, if needed) to the number of array entries allocated by malloc()/realloc(). In this case, be sure that \*nalloc is zero before the first call to read\_block(), or the function will think that it has already allocated memory!

**seek:** Input. If seek is set to zero, then the function reads data. If seek is set nonzero, then read\_block() does not copy any data into \*here. Instead it simply skips over the actual data.

**bh:** Output. A pointer to the binary header structure defined above.

**mh:** Output. A pointer to the main header structure defined above.

This is a low-level function, which reads a block of data. It is designed to either write the data into a user-defined array or block of memory, if allocate is off, or to allocate the memory itself. In the latter mode, the function uses nalloc to track the amount of memory allocated, and reallocates if necessary. It is often useful to be able to quickly skip over sections of data (for example, just after the interferometer locks, a few minutes is needed for the violin modes to damp down). Or if the IFO is out of lock, one needs to

quickly read ahead to the next locked section. If `seek` is set, then this routine behaves exactly as it would in normal (read) mode but does not copy any data.

The function `read_block()` returns the number of data items that will be returned on the *next* call to `read_block()`. It returns -1 if it has just read the final block of data (implying that the next call will return 0). It returns 0 if it can not read any further data, because none remains.

Note that if the user has set `allocate`, then the `read_block()` will allocate memory using `malloc()/realloc()`. It is the users responsibility to free this block of memory when it is no longer needed, using `free()`.

Author: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: This function was designed for variable-length blocks. It might be possible to simplify it for fixed-length block sizes.

### 3.3 Example: reader program

This example uses the function `read_block()` described in the previous section to read the first 20 blocks out of the file `channel.0`. It prints the header information for each block of data, and the 100th data item from each block, along with the time associated with that data item.

The data is located with the utility function `grasp_open()`, which is documented in Section 10.2. In order for this example program to work, you *must* set the environment variable `GRASP_DATAPATH` to point to a directory containing 40-meter data. You can do this with a command such as

```
setenv GRASP_DATAPATH /usr/local/data/19nov94.3
```

to access the data from run 3 on November 19th.

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

int main(){
    FILE *fp;
    short *data;
    float tblock,time,srate;
    int code,num,size=0,count=0,which=100;
    struct ld_binheader bheader;
    struct ld_mainheader mheader;

    /* open the IFO channel for reading */
    fp=grasp_open("GRASP_DATAPATH","channel.0");

    /* read the first 20 blocks of lock data */
    while (count <20) {
        /* read a block of data */
        code= read_block(fp,&data,&num,&tblock,&srate,1,&size,0,&bheader,&mheader);

        /* if there is no data left, then break */
        if (code==0) break;

        /* print some information about the data */
        printf("Data block %d from file channel.0 starts at t = %f sec.\n",count,tblock);
        printf("This block sampled at %f Hz and contains %d shorts.\n",srate,num);

        /* print out some information about a single data point from block */
        time=tblock+(which-1.0)/srate;
        printf("Data item %d at time %f is %d.\n",which,time,data[which-1]);
        printf("The next block of data contains %d shorts.\n\n",code);

        /* increment count of # of blocks read */
        count++;
    }

    /* print information about the largest memory block allocated */
    printf("The largest memory block allocated by read_block() was %d shorts long\n",size);

    /* free the array allocated by read_block() */
    free(data);
    return 0;
}
```

### 3.4 Function: `find_locked()`

```
int find_locked(FILE *fp, int *s_offset, int *s_block, int *e_offset, int *e_block,  
*tstart, float *tend, float *srate)
```

This mid-level function looks in a TTL-locked signal channel (typically, `channel.10`) and finds the regions of time when the interferometer is locked. The first time it is called, it returns information identifying the start and end times of the first locked region. The second time it is called it returns the start and end times of the second locked region, and so on.

The arguments are:

`fp`: Input. A pointer to the file containing the TTL lock signal. A typical file name might be "`channel.10`".

`s_offset`: Output. The offset (number of shorts) into the block where the IFO locks. This ranges from 0 to  $n-1$  where the number of data items in block `s_block` is  $n$ . This offset points to the first locked point.

`s_block`: Output. The number of the data block where the IFO locks. This ranges from 0 to  $n-1$  where the total number of data blocks in the file is  $n$ .

`e_offset`: Output. The offset (number of shorts) into the block where the IFO loses locks. This ranges from 0 to  $n-1$  where the number of data items in the block `e_block`. This offset points to the last locked point (not to the first unlocked point).

`e_block`: Output. The number of the data block where the IFO loses lock. This ranges from `s_block` to  $n-1$  where the total number of data blocks in the file is  $n$ .

`tstart`: Output. The elapsed time in seconds, since the beginning of the run, of the data block in which the first locked point was found. Note: This is not the time of lock acquisition!

`tend`: Output. The elapsed time in seconds, since the beginning of the run, of the data block in which the last locked point was found. Note: this is not the time at which lock was lost!

`srate`: Output. The sample rate of the TTL-locked channel, in Hz.

This routine uses `read_block()` to examine successive sections of the `channel.10` data file. It looks for continuous sequences of data points where the value lies between limits (inclusive) `LOCKL=1` and `LOCKH=10`. It returns the start and end points of each successive such sequence. The upper and lower limits can be changed in the code, if desired, however these values appear to be reliable ones.

The integer returned by `find_locked()` is the actual number of data points in the *fast* channels, during the locked period. It returns 0 if there are no remaining locked segments.

If there is a gap in the data stream, arising not because the instrument went out of lock, but rather because the tape-writing program was interrupted and then later restarted, `find_locked()` will print out a warning message, but will otherwise treat this simply as a loss of lock during the period of the missing data.

Author: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: This function was designed for variable-length blocks. It might be possible to simplify it for fixed-length block sizes.



### 3.5 Example: locklist program

This example uses the function `find_locked` described in the previous section to print out location information and times for all the locked sections in the file `channel.10`. Note that this example only prints out information for locked sections longer than 30 sec.

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

int main() {
    float tstart,tend,srate,totaltime,begin,end;
    int start_offset,start_block,end_offset,end_block,points;
    FILE *fplock;

    /* Open the file for reading */
    fplock=grasp_open("GRASP_DATAPATH","channel.10");

    while (1) {

        /* find the next locked section of the data */
        points=find_locked(fplock,&start_offset,
                        &start_block,&end_offset,&end_block,&tstart,&tend,&srate);

        /* if no data remains, then exit */
        if (points==0)
            break;

        /* calculate start and end of lock times */
        begin=tstart+start_offset/srate;
        end=tend+end_offset/srate;
        totaltime=end-begin;

        /* print out info for lock intervals > 30 seconds */
        if (totaltime>30.0) {
            printf("Locked from t = %f to %f for %f sec\n",begin,end,totaltime);
            printf("Number of data points is %d\n",points);
            printf("Start block: %d End block: %d\n",start_block,end_block);
            printf("Start offset: %d End offset %d\n\n",start_offset,end_offset);
        }
    }
    return 0;
}
```

### 3.6 Function: `get_data()`

```
int get_data(FILE *fp, FILE *fplock, float *tstart, int npoint, short *location, int *rem, float *srate, int seek)
```

This high-level function is an easy way to get the IFO output (gravity wave signal) during periods when the IFO is locked. When called, it returns the next locked data section of a user-specified length. It also specifies if the section of data is part of a continuous locked stream, or the beginning of a new locked section.

The arguments are:

`fp`: Input. Pointer to a file (typically `channel.0`) containing the channel 0 data.

`fplock`: Input. Pointer to a file (typically `"channel.10"`) containing the TTL lock signal.

`tstart`: Output. The time of the zeroth point in the returned data.

`npoint`: Input. The number of data points requested by the user.

`location`: Input. Pointer to the location where the data should be put.

`rem`: Output. The number of points of data remaining in this locked segment of data.

`srate`: Output. The sample rate of the fast data channel, in Hz.

`seek`: Input. If this is zero, then the data is returned in the array `location[ ]`. However if this input is non-zero, then `get_data` performs exactly as described, except that it does not actually read any data from the file or write to `location[ ]`. This is useful to quickly skip over un-interesting regions of the data, for example the first several minutes after the interferometer acquires lock.

This function returns 0 if there is no remaining locked data stream of the requested length. It returns 1 if it is just starting on a new locked section of the data stream, and it returns 2 if the data is part of an on-going locked sequence.

Author: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: This function was designed for variable-length blocks. It is possible to simplify it for fixed-length block sizes. It should also be modified to return a complete set of different channels, by adding additional arguments to specify which channels are desired and where the data should be placed. This could also be used to eliminate the `seek` argument.

### 3.7 Example: gwoutput program

This example uses the function `get_data()` described in the previous section to print out a two-column file containing the IFO output for the first locked section containing 100 sample points. In the output, the left column is time values, and the right column is the actual IFO output (note that because this comes from a 12 bit A-D converter, the output is an integer value from -2047 to 2048). The program works by acquiring data 100 points at a time, then printing out the values, then acquiring 100 more points, and so on. Whenever a new locked section begins, the program prints a banner message to alert the user. Note that typical locked sections contain  $\approx 10^7$  points of data, so this program should not be used for real work – it's just a demonstration!

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

main() {
    float tstart, time, srate;
    int remain, i, npoint, code;
    FILE *fp, *fplock;
    short *data;

    /* open the IFO output file and lock file */
    fp=grasp_open("GRASP_DATAPATH", "channel.0");
    fplock=grasp_open("GRASP_DATAPATH", "channel.10");

    /* specify the number of points of output & allocate array */
    npoint=100;
    data=(short *)malloc(sizeof(short)*npoint);

    while (1) {
        /* fill the array with npoint points of data */
        code=get_data(fp, fplock, &tstart, npoint, data, &remain, &srate, 0);
        /* if no data remains, exit loop */
        if (code==0) break;
        /* if starting a new locked segment, print banner */
        if (code==1) {
            printf("_____ NEW LOCKED SEGMENT _____\n\n");
            printf("  Time (sec)\t  IFO output\n");
        }
        /* now output the data */
        for (i=0; i<npoint; i++) {
            time=tstart+i/srate;
            printf("%f\t%d\n", time, data[i]);
        }
    }
    /* close the data files, and return */
    fclose(fp);
    fclose(fplock);
    return 0;
}
```

### 3.8 Example: animate program

This example uses the function `get_data()` described in the previous section to produce an animated display showing the time series output of the IFO in a lower window, and a simultaneously calculated FFT power spectrum in the upper window. This output from this program must be piped into a public domain graphing program called `xmgr`. This may be obtained from <http://plasma-gate.weizmann.ac.il/Xmgr/>. (This lists mirror sites in the USA and Europe also). Some sample output of `animate` is shown in Figure 2.

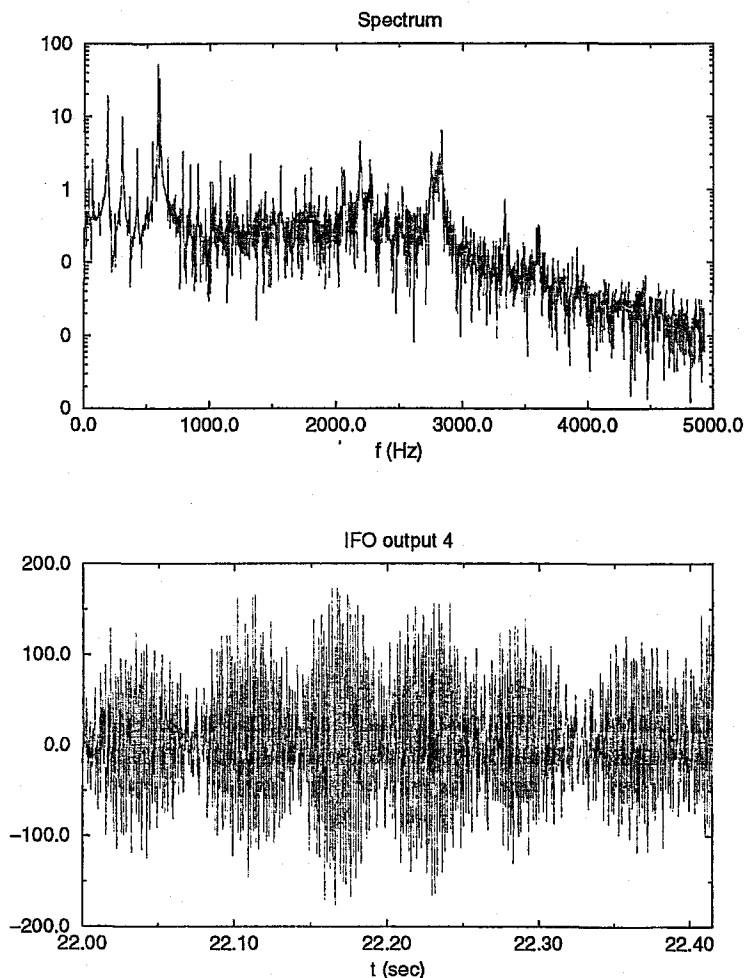


Figure 2: Snapshot of output from `animate`. This shows the (whitened) CIT 40-meter IFO a few seconds after acquiring lock, before the violin modes have damped down

After compilation, to run the program type:

```
animate | xmgr -pipe &
```

to get an animated display showing the data flowing by and the power spectrum changing, starting from the first locked data. You can also use this program with command-line arguments, for example

```
animate 100 4 500 7 900 1.5 | xmgr -pipe &
```

will show the data from time  $t = 100$  to time  $t = 104$  seconds, then from  $t = 500$  to  $t = 507$ , then from  $t = 900$  to  $t = 901.5$ . Notice that the sequence of start times must be increasing.

Note: The `xmgr` program as commonly distributed has a simple bug that needs to be repaired, in order for the frequency scale of the Fourier transform to be correct. The corrected version of `xmgr` is shown in

---

```

        case 0:
==>      delt=(x[ilen-1]-x[0])/(ilen-1.0);
==>      T=(x[ilen-1]-x[0]);
          setlength(cg, specset, ilen/2);
          xx=getx(cg, specset);
        ...

        case 1:
==>      delt=(x[ilen-1]-x[0])/(ilen-1.0);
==>      T=(x[ilen-1]-x[0]);

```

Figure 3: The corrections to a bug in the `xmgr` program are indicated by the arrows above. This bug is in the routine `do_fourier()` in the file `computils.c`.

---

Figure 3.

```

/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

int main(int argc, char **argv) {
    void graphout(float, float, int);
    float tstart=1.e35, srate=1.e-30, tmin, tmax, dt;
    double time;
    int remain, i, seq=0, code, npoint=4096, seek;
    FILE *fp, *fplock;
    short *data;

    /* open the IFO output file and lock file */
    fp=grasp_open("GRASP_DATAPATH", "channel.0");
    fplock=grasp_open("GRASP_DATAPATH", "channel.10");

    /* allocate storage space for data */
    data=(short *)malloc(sizeof(short)*npoint);
    /* handle case where user has supplied t or dt arguments */
    if (argc==1) {
        tmin=-1.e30;
        dt=2.e30;
        argc--;
    }
    /* now loop ... */
    seq=argc;
    while (argc!=1) {
        /* get the next start time and dt */
        if (argc!=-1) {
            sscanf(argv[seq-argc+1], "%f", &tmin);
            sscanf(argv[seq-argc+2], "%f", &dt);
            argc-=2;
        }
        /* calculate the end of the observation interval, and get data */
        tmax=tmin+dt;
        while (1) {
            if (tstart<tmin-(npoint+20.)/srate) seek=1; else seek=0;

```

```

code=get_data(fp,fplock,&tstart,npoint,data,&remain,&srate,seek);
/* if no data left, return */
if (code==0) return 0;
/* we need to be outputting now... */
if (tmin<=tstart){
    for (i=0;i<npoint;i++) {
        time=tstart+i/srate;
        printf("%f\t%d\n",time,data[i]);
    }
    /* put out information for the graphing program */
    graphout(tstart,tstart+npoint/srate,(argc==1 && time>=tmax));
}
/* if we are done with this interval, try next one */
if (time>=tmax) break;
}
}
/* close files and return */
fclose(fp);
return 0;
}
/* This routine is pipes output into the xmgr graphing program */
void graphout(float x1,float x2,int last) {
    static int count=0;
    printf("&\n"); /* end of set marker */
    /* first time we draw the plot */
    if (count==0) {
        printf("@doublebuffer true\n"); /* keeps display from flashing */
        printf("@s0 color 3\n"); /* IFO graph is green */
        printf("@view 0.1, 0.1, 0.9, 0.45\n"); /* set the viewport for IFO */
        printf("@with g1\n"); /* reset the current graph to FFT */
        printf("@view 0.1, 0.6, 0.9, 0.95\n"); /* set the viewport FFT */
        printf("@with g0\n"); /* reset the current graph to IFO */
        printf("@world xmin %f\n",x1); /* set min x */
        printf("@world xmax %f\n",x2); /* set max x */
        printf("@autoscale\n"); /* autoscale first time through */
        printf("@focus off\n"); /* turn off the focus markers */
        printf("@xaxis label \"t (sec)\"\n"); /* IFO axis label */
        printf("@fft(s0, 1)\n"); /* compute the spectrum */
        printf("@s1 color 2\n"); /* FFT is red */
        printf("@move g0.s1 to g1.s0\n"); /* move FFT to graph 1 */
        printf("@with g1\n"); /* set the focus on FFT */
        printf("@g1 type logy\n"); /* set FFT to log freq axis */
        printf("@autoscale\n"); /* autoscale FFT */
        printf("@subtitle \"Spectrum\"\n"); /* set the subtitle */
        printf("@xaxis label \"f (Hz)\"\n"); /* FFT axis label */
        printf("@with g0\n"); /* reset the current graph IFO */
        printf("@subtitle \"IFO output %d\"\n",count++); /* set IFO subtitle */
        if (!last) printf("@kill s0\n"); /* kill IFO; ready to read again */
    }
    else {
        /* other times we redraw the plot */
        printf("@s0 color 3\n"); /* set IFO green */
        printf("@fft(s0, 1)\n"); /* FFT it */
        printf("@s1 color 2\n"); /* set FFT red */
        printf("@move g0.s1 to g1.s0\n"); /* move FFT to graph 1 */
        printf("@subtitle \"IFO output %d\"\n",count++); /* set IFO subtitle */
        printf("@world xmin %f\n",x1); /* set min x */
        printf("@world xmax %f\n",x2); /* set max x */
        printf("@autoscale yaxes\n"); /* autoscale IFO */
    }
}

```

```

printf("@clear stack\n");
if (!last) printf("@kill s0\n");
printf("@with g1\n");
printf("@g1 type logy\n");
printf("@clear stack\n");
if (!last) printf("@kill s0\n");
printf("@with g0\n");
}
return;
}

```

```

/* clear the stack */
/* kill IFO data */
/* switch to FFT */
/* set FFT to log freq axis */
/* clear stack */
/* kill FFT */
/* ready to read IFO again */

```

### 3.9 Function: read\_sweptsine()

void read\_sweptsine(FILE \*fpss, int \*n, float \*\*freq, float \*\*real, float \*\*imag)

This is a low-level routine which reads in a 3-column ASCII file of swept sine calibration data used to calibrate the IFO.

The arguments are:

**fpss:** Input. Pointer to a file in which the swept sine data can be found. The format of this data is described below.

**n:** Output. One greater than the number of entries (lines) in the swept sine calibration file. This is because the read\_sweptsine returns, in addition to this data, one additional entry at frequency  $f = 0$ .

**freq:** Output. The array \*freq[1..\*n-1] contains the frequency values from the swept sine calibration file. The routine adds an additional entry at DC, \*freq[0]=0. Note: the routine allocates memory for the array.

**real:** Output. The array \*real[1..\*n-1] contains the real part of the response function of the IFO. The routine adds \*real[0]=0. Note: the routine allocates memory for the array.

**imag:** Output. The array \*imag[1..\*n-1] contains the imaginary part of the response function of the IFO. The routine adds \*imag[0]=0. Note: the routine allocates memory for the array.

The swept sine calibration files are 3-column ASCII files, of the form:

$f_1$	$r_1$	$i_1$
$f_2$	$r_2$	$i_2$
	...	
$f_m$	$r_m$	$i_m$

where the  $f_j$  are frequencies, in Hz, and  $r_j$  and  $i_j$  are dimensionless ratios of voltages. There are typically  $m = 801$  lines in these files. Each line gives the ratio of the IFO output voltage to a calibration coil driving voltage, at a different frequency. The  $r_j$  are the "real part" of the response, i.e. the ratio of the IFO output in phase with the coil driving voltage, to the coil driving voltage. The  $i_j$  are the "imaginary part" of the response, 90 degrees out of phase with the coil driving voltage. The sign of the phase (or equivalently, the sign of the imaginary part of the response) is determined by the following convention. Suppose that the driving voltage (in volts) is

$$V_{\text{coil}} = 10 \cos(\omega t) = 10 \Re e^{i\omega t} \quad (3.9.1)$$

where  $\omega = 2\pi \times 60$  radians/sec is the angular frequency of a 60 Hz signal. Suppose the response of the interferometer output to this is (again, in volts)

$$\begin{aligned} V_{\text{IFO}} &= 6.93 \cos(\omega t) + 4 \sin(\omega t) \\ &= 6.93 \cos(\omega t) - 4 \cos(\omega t + \pi/2) \\ &= 8 \Re e^{i(\omega t - \pi/6)} \end{aligned} \quad (3.9.2)$$

This is shown in Figure 4. An electrical engineer would describe this situation by saying that the phase of the response  $V_{\text{IFO}}$  is lagging the phase of the driving signal  $V_{\text{coil}}$  by  $30^\circ$ . The corresponding line in the swept sine calibration file would read:

...		
60.000	0.6930	-0.40000
	...	



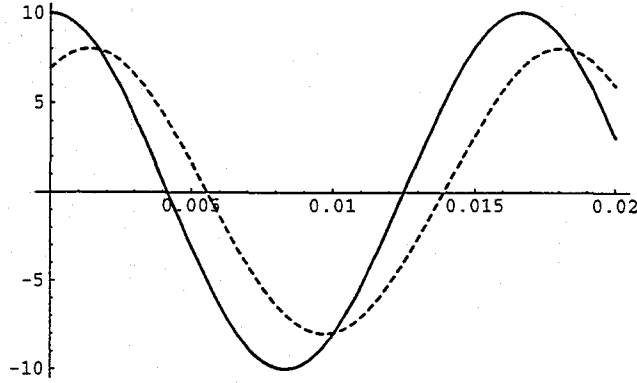


Figure 4: This shows a driving voltage  $V_{\text{coil}}$  (solid curve) and the response voltage  $V_{\text{IFO}}$  (dotted curve) as functions of time (in sec). Both are 60 Hz sinusoids; the relative amplitude and phase of the in-phase and out-of-phase components of  $V_{\text{IFO}}$  are contained in the swept-sine calibration files.

Hence, in this example, the real part is positive and the imaginary part is negative. We will denote this entry in the swept sine calibration file by  $S(60) = 0.8 e^{-i\pi/6} = 0.693 - 0.400i$ . Because the interferometer output is real, there is also a value implied at negative frequencies which is the complex conjugate of the positive frequency value:  $S(-60) = S^*(60) = 0.8 e^{i\pi/6} = 0.693 + 0.400i$ .

Because the interferometer has no DC response, it is convenient for us to add one additional point at frequency  $f = 0$  into the output data arrays, with both the real and imaginary parts of the response set to zero. Hence the output arrays contain one element more than the number of lines in the input files. Note that both of these arrays are arranged in order of increasing frequency; after adding our one additional point they typically contain 802 points at frequencies from 0 Hz to 5001 Hz.

For the data runs of interest in this section (from November 1994) typically a swept sine calibration curve was taken immediately before each data tape was generated.

We will shortly address the following question. How does one use the dimensionless data in the channel .0 files to reconstruct the differential motion  $\Delta l(t)$  (in meters) of the interferometer arms? Here we address the closely related question: given  $V_{\text{IFO}}$ , how do we reconstruct  $V_{\text{coil}}$ ? We choose the sign convention for the Fourier transform which agrees with that of *Numerical Recipes*: equation (12.1.6) of [1]. The Fourier transform of a function of time  $V(t)$  is

$$\tilde{V}(f) = \int e^{2\pi i f t} V(t) dt. \quad (3.9.3)$$

The inverse Fourier transform is

$$V(t) = \int e^{-2\pi i f t} \tilde{V}(f) df. \quad (3.9.4)$$

With these conventions, the signals (3.9.1) and (3.9.2) shown in in Figure 4 have Fourier components:

$$\tilde{V}_{\text{coil}}(60) = 5 \quad \text{and} \quad \tilde{V}_{\text{coil}}(-60) = 5, \quad (3.9.5)$$

$$\tilde{V}_{\text{IFO}}(60) = 4e^{i\pi/6} \quad \text{and} \quad \tilde{V}_{\text{IFO}}(-60) = 4e^{-i\pi/6}. \quad (3.9.6)$$

At frequency  $f_0 = 60$  Hz the swept sine file contains

$$S(60) = 0.8 e^{-i\pi/6} \Rightarrow S(-60) = S^*(60) = 0.8 e^{i\pi/6}. \quad (3.9.7)$$

since  $S(-f) = S^*(f)$ .

With these choices for our conventions, one can see immediately from our example (and generalize to all frequencies) that

$$\tilde{V}_{\text{coil}}(f) = \frac{\tilde{V}_{\text{IFO}}}{S^*(f)}. \quad (3.9.8)$$

In other words, with the *Numerical Recipes* [1] conventions for forward and reverse Fourier Transforms, the (FFT of the) calibration-coil voltage is the (FFT of the) IFO-output voltage divided by the complex conjugate of the swept sine response.

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Comments: The swept-sine calibration curves are usually quite smooth but sometimes they contain a “glitch” in the vicinity of 1 kHz; this may be due to drift of the unity-gain servo point.

### 3.10 Function: `calibrate()`

```
void calibrate(FILE *fpss, int num, float *complex, float srate, int method, int order)
```

This is an intermediate-level routine which reads in a 3-column ASCII file of swept sine calibration data used to calibrate the IFO, and outputs an array of interpolated points suitable for calibration of FFT's of the interferometer output.

The arguments are:

`fpss`: Input. Pointer to the file in which the swept sine data can be found. The format of this data is described below.

`srate`: Input. The sample rate  $F_{\text{sample}}$  (in Hz) of the data that we are going to be calibrating.

`num`: Input. The number of points  $N$  in the FFT that we will be calibrating. This is typically  $N = 2^k$  where  $k$  is an integer. In this case, the number of distinct frequency values at which a calibration is needed is  $2^{k-1} + 1 = N/2 + 1$ , corresponding to the number of distinct frequency values from 0 (DC) to the Nyquist frequency  $f_{\text{Nyquist}}$ . See for example equation (12.1.5) of reference [1]. The frequencies are  $f_i = \frac{i}{N} F_{\text{sample}}$  for  $i = 0, \dots, N/2$ .

`complex`: Input. Pointer to an array `complex[0..s]` where  $s = 2^k + 1$ . The routine `calibrate()` fills in this array with interpolated values of the swept sine calibration data, described in the previous section. The real part of the DC response is in `complex[0]`, and the imaginary part is in `complex[1]`. The real/imaginary parts of the response at frequency  $f_1$  are in `complex[2]` and `complex[3]` and so on. The last two elements of `complex[ ]` contain the real/imaginary parts of the response at the Nyquist frequency  $F_{\text{sample}}/2$ .

`method`: Input. This integer sets the type of interpolation used to determine the real and imaginary part of the response, at frequencies that lie in between those given in the swept sine calibration files. Rational function interpolation is used if `method=0`. Polynomial interpolation is used if `method=1`. Spline interpolation with natural boundary conditions (vanishing second derivatives at DC and the Nyquist frequency) is used if `method=2`.

`order`: Input. Ignored if spline interpolation is used. If polynomial interpolation is used, then `order` is the order of the interpolating polynomial. If rational function interpolation is used, then the numerator and denominator are both polynomials of order `order/2` if `order` is even; otherwise the degree of the denominator is  $(\text{order}+1)/2$  and that of the numerator is  $(\text{order}-1)/2$ .

The basic problem solved by this routine is that the swept sine calibration files typically contain data at a few hundred distinct frequency values. However to properly calibrate the IFO output, one usually needs this calibration information at a large number of frequencies corresponding to the distinct frequencies associated with the FFT of a data set. This routine allows you to choose different possible interpolation methods. If in doubt, we recommend spline interpolation as the first choice. The interpolation methods are described in detail in Chapter 3 of reference [1].

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Comments: It might be better to interpolate values of  $f^2$  times the swept-sine response function, as this is the quantity needed to compute the IFO response function.

### 3.11 Example: print\_ss program

This example uses the function `calibrate()` to read in a swept sine calibration file, and then prints out a list of frequencies, real, and imaginary parts interpolated from this data. The frequencies are appropriate for the FFT of a 4096 point data set with sample rate `srate`. The technique used is spline interpolation.

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
#define NPOINT 4096

int main() {
    float cplx[NPOINT+2], srate, freq;
    int npoint, i;
    FILE *fp;

    /* open the swept-sine calibration file */
    fp=grasp_open("GRASP_DATAPATH", "swept-sine.ascii");

    /* number of points of (imagined) FFT */
    npoint=NPOINT;

    /* a sample rate often used for fast channels */
    srate=9868.4208984375;

    /* swept sine calibration filename is first argument */
    calibrate(fp, npoint, cplx, srate, 2, 0);

    /* print out frequency, real, imaginary interpolated values */
    printf("# Freq (Hz)\tReal\t\tImag\n");
    for (i=0; i<=NPOINT/2; i++) {
        freq=i*srate/NPOINT;
        printf("%e\t%e\t%e\n", freq, cplx[2*i], cplx[2*i+1]);
    }
    return 0;
}
```

### 3.12 Function: `normalize_gw()`

```
void normalize_gw(FILE *fpss, int npoint, float srate, float *response)
```

This routine generates an array of complex numbers  $R(f)$  from the information in the swept sine file and an overall calibration constant. Multiplying this array of complex numbers by (the FFT of) `channel.0` yields the (FFT of the) differential displacement of the interferometer arms  $\Delta l$ , in meters:  $\widetilde{\Delta l}(f) = R(f)\widetilde{C}_0(f)$ . The units of  $R(f)$  are meters/ADC-count.

The arguments are:

`fpss`: Input. Pointer to the file in which the swept sine normalization data can be found.

`npoint`: Input. The number of points  $N$  of `channel.0` which will be used to calculate an FFT for normalization. Must be an integer power of 2.

`srate`: Input. The sample rate in Hz of `channel.0`.

`response`: Output. Pointer to an array `response[0..s]` with  $s = N + 1$  in which  $R(f)$  will be returned. By convention,  $R(0) = 0$  so that `response[0]=response[1]=0`. Array elements `response[2i]` and `response[2i+1]` contain the real and imaginary parts of  $R(f)$  at frequency  $f = israte/N$ . The response at the Nyquist frequency `response[N]=0` and `response[N+1]=0` by convention.

The absolute normalization of the interferometer can be obtained from the information in the swept sine file, and one other normalization constant which we denote by  $Q$ . It is easy to understand how this works. In the calibration process, one of the interferometer end mirrors of mass  $m$  is driven by a magnetic coil. The equation of motion of the driven end mass is

$$m \frac{d^2}{dt^2} \Delta l = F(t) \quad (3.12.1)$$

where  $F(t)$  is the driving force and  $\Delta l$  is the differential length of the two interferometer arms, in meters. Since the driving force  $F(t)$  is proportional to the coil current and thus to the coil voltage, in frequency space this equation becomes

$$(-2\pi i f)^2 \widetilde{\Delta l} = \text{constant} \times \widetilde{V}_{\text{coil}} = \text{constant} \times \frac{\widetilde{V}_{\text{IFO}}}{S^*(f)}. \quad (3.12.2)$$

We have substituted in equation (3.9.8) which relates  $\widetilde{V}_{\text{IFO}}$  and  $\widetilde{V}_{\text{coil}}$ . The IFO voltage is directly proportional to the quantity recorded in `channel.0`:  $V_{\text{IFO}} = \text{ADC} \times C_0$ , with the constant ADC being the ratio of the analog-to-digital converter's input voltage to output count.

Putting together these factors, the properly normalized value of  $\Delta l$ , in meters, may be obtained from the information in `channel.0`, the swept sine file, and the quantities given in Table 4 by

$$\widetilde{\Delta l} = R(f) \times \widetilde{C}_0 \quad \text{with} \quad R(f) = \frac{Q \times \text{ADC}}{-4\pi^2 f^2 S^*(f)}, \quad (3.12.3)$$

where the  $\widetilde{\phantom{x}}$  denotes Fourier transform, and  $f$  denotes frequency in Hz. (Note that, apart from the complex conjugate on  $S$ , the conventions used in the Fourier transform drop out of this equation, provided that identical conventions (3.9.3,3.9.4) are applied to both  $\Delta l$  and to  $C_0$ ). The constant quantity  $Q$  indicated in the above equations has been calculated and documented in a series of calibration experiments carried out by Robert Spero. In these calibration experiments, the interferometer's servo was left open-loop, and the end mass was driven at a single frequency, hard enough to move the end mass one-half wavelength and shift

Table 4: Quantities entering into normalization of the IFO output.

Description	Name	Value	Units
Gravity-wave signal (channel 1.0)	$C_0$	varies	ADC counts
A→D converter sensitivity	ADC	10/2048	$V_{\text{IFO}} (\text{ADC counts})^{-1}$
Swept sine calibration	S(f)	from file	$V_{\text{IFO}} (V_{\text{coil}})^{-1}$
Calibration constant	$Q$	$1.428 \times 10^{-4}$	meter $\text{Hz}^2 (V_{\text{coil}})^{-1}$

the interference fringe's pattern over by one fringe. In this way, the coil voltage required to bring about a given length motion at a particular frequency was established, and from this information, the value of  $Q$  may be inferred. During the November 1994 runs the value of  $Q$  was given by

$$Q = \frac{\sqrt{9.35 \text{ Hz}}}{k} = 1.428 \times 10^{-4} \frac{\text{meter Hz}^2}{V_{\text{coil}}} \quad \text{where } k = 21399 \frac{V_{\text{coil}}}{\text{meter Hz}^{3/2}}. \quad (3.12.4)$$

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Comments: See comment for calibrate().

### 3.13 Example: power\_spectrum program

This example uses the function `normalize_gw()` to produce a normalized, properly calibrated power spectrum of the interferometer noise, using the gravity-wave signal from `channel . 0`, the TTL-lock signal from `channel . 10` and a swept-sine calibration curve.

The output of this program is a 2-column file; the first column is frequency and the second column is the noise in units of meters/ $\sqrt{\text{Hz}}$ .

A couple of comments are in order here:

1. Even though we only need the modulus, for pedagogic reasons, we explicitly calculate both the real and imaginary parts of  $\widetilde{\Delta l}(f) = R(f)\widetilde{C}_0(f)$ .
2. The fast Fourier transform of  $\Delta l$ , which we denote  $\text{FFT}[\Delta l]$ , has the same units (meters!) as  $\Delta l$ . As can be immediately seen from *Numerical Recipes* equation (12.1.6) the Fourier transform  $\widetilde{\Delta l}$  has units of meters-sec and is given by  $\widetilde{\Delta l} = \Delta t \text{FFT}[\Delta l]$ , where  $\Delta t$  is the sample interval. The (one-sided) power spectrum of  $\Delta l$  in meters/ $\sqrt{\text{Hz}}$  is  $P = \sqrt{\frac{2}{T}}|\widetilde{\Delta l}|$  where  $T = N\Delta t$  is the total length of the observation interval, in seconds. Hence one has

$$P = \sqrt{\frac{2}{N\Delta t}} \Delta t |\text{FFT}[\Delta l]| = \sqrt{\frac{2\Delta t}{N}} |\text{FFT}[\Delta l]|. \quad (3.13.1)$$

This is the reason for the factor which appears in this example.

3. To get a spectrum with decent frequency resolution, the time-domain data must be windowed (see the example program `calibrate` and the function `avg_spec()` to see how this works).

A sample of the output from this program is shown in Figure 5.

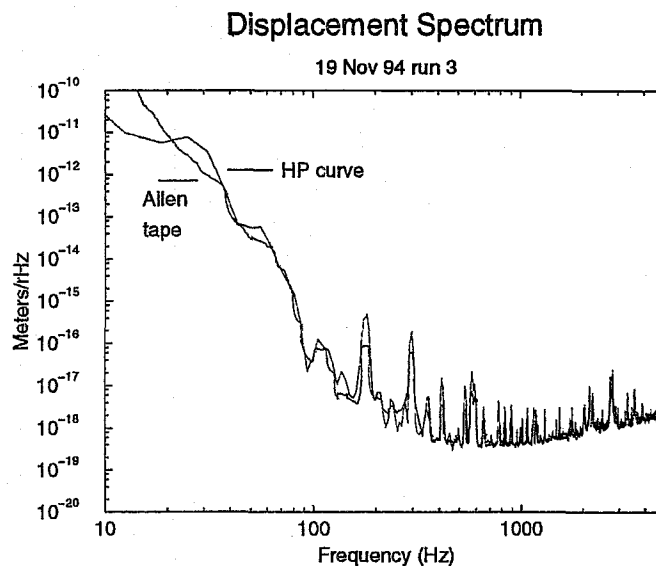


Figure 5: An example of a power spectrum curve produced with `power_spectrum`. The spectrum produced off a data tape (with 100 point smoothing) is compared to that produced by the HP spectrum analyzer in the lab.

```

/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
#define NPOINT 65536

int main() {
    void realft(float*, unsigned long, int);
    float response[NPOINT+2], data[NPOINT], tstart, freq;
    float res_real, res_imag, dl_real, dl_imag, c0_real, c0_imag, spectrum, srate, factor;
    FILE *fpifo, *fplock, *fpss;
    int i, npoint, remain;
    short datas[NPOINT];

    /* open the IFO output file, lock file, and swept-sine file */
    fpifo=grasp_open("GRASP_DATAPATH", "channel.0");
    fplock=grasp_open("GRASP_DATAPATH", "channel.10");
    fpss=grasp_open("GRASP_DATAPATH", "swept-sine.ascii");

    /* number of points to sample and fft (power of 2) */
    npoint=NPOINT;
    /* skip 200 seconds into locked region (seek=1) */
    while (tstart<200.0)
        get_data(fpifo, fplock, &tstart, npoint, datas, &remain, &srate, 1);
    /* and get next stretch of data from TTL locked file (seek=0) */
    get_data(fpifo, fplock, &tstart, npoint, datas, &remain, &srate, 0);
    /* convert gw signal (ADC counts) from shorts to floats */
    for (i=0; i<NPOINT; i++) data[i]=datas[i];
    /* FFT the data */
    realft(data-1, npoint, 1);
    /* get normalization R(f) using swept sine file */
    normalize_gw(fpss, npoint, srate, response);
    /* one-sided power-spectrum normalization, to get meters/rHz */
    factor=sqrt(2.0/(srate*npoint));
    /* compute dl. Leave off DC (i=0) or Nyquist (i=npoint/2) freq */
    for (i=1; i<npoint/2; i++) {
        /* frequency */
        freq=i*srate/npoint;
        /* real and imaginary parts of tilde c0 */
        c0_real=data[2*i];
        c0_imag=data[2*i+1];
        /* real and imaginary parts of R */
        res_real=response[2*i];
        res_imag=response[2*i+1];
        /* real and imaginary parts of tilde dl */
        dl_real=c0_real*res_real-c0_imag*res_imag;
        dl_imag=c0_real*res_imag+c0_imag*res_real;
        /* |tilde dl| */
        spectrum=factor*sqrt(dl_real*dl_real+dl_imag*dl_imag);
        /* output freq in Hz, noise power in meters/rHz */
        printf("%e\t%e\n", freq, spectrum);
    }
    return 0;
}

```

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Comments: The IFO output typically consists of a number of strong line sources (harmonics of the 60 Hz line and the 180 Hz laser power supply, violin modes of the suspension, etc) superposed on a continuum background (electronics noise, laser shot noise, etc) In such situations, there are better ways of finding the noise power spectrum (for example, see the multi-taper methods of David J. Thomson [24], or the textbook by Percival and Walden [25]). Using methods such as the F-test to remove line features from the time-domain data stream might reduce the sidelobe contamination (bias) from nearby frequency bins, and thus permit an effective reduction of instrument noise near these spectral line features. Further details of these methods, and some routines that implement them, may be found in Section 10.17.

### 3.14 Example: calibrate program

This example uses the function `normalize_gw()` and `avg_spec()` to produce an animated display, showing the properly normalized power spectrum of the interferometer, with a 30-second characteristic time moving average. After compilation, to run the program type:

```
calibrate | xmgr -pipe &
```

to get an animated display showing the calibrated power spectrum changing. An example of the output from `calibrate` is shown in Figure 6. Note that most of the execution time here is spent passing data down the pipe to `xmgr` and displaying it. The display can be speeded up by a factor of ten by binning the output values to reduce their number to a few hundred lines (the example program `calibrate_binned.c` implements this technique; it can be run by typing `calibrate_binned | xmgr -pipe`).

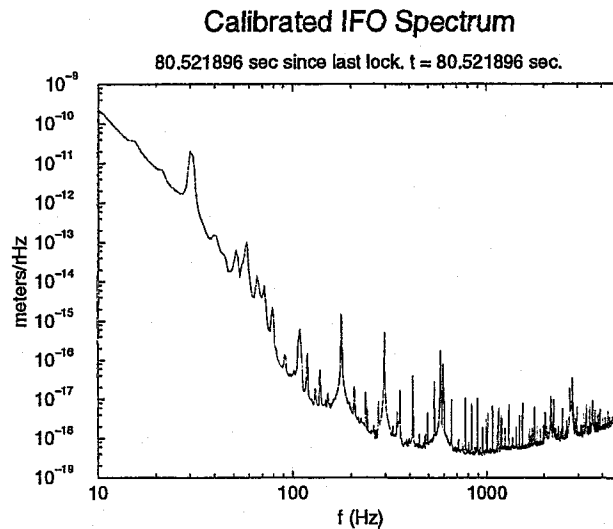


Figure 6: This shows a snapshot of the output from the program `calibrate` which displays an animated average power spectrum (Welch windowed, 30-second decay time).

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
#define NPOINT 4096

int main(int argc, char **argv) {
    void graphout(int, float, float);
    void realft(float*, unsigned long, int);
    float data[NPOINT], average[NPOINT], response[2*NPOINT+4];
    float spec, decaytime;
    float srate, tstart=0, freq, tlock;
    FILE *fpifo, *fpss, *fplock;
    int i, j, code, npoint, remain, ir, ii, reset=0, pass=0;
    short datas[NPOINT];
    double mod;

    /* open the IFO output file, lock file, and swept-sine file */
    fpifo=grasp_open("GRASP_DATAPATH", "channel.0");
    fplock=grasp_open("GRASP_DATAPATH", "channel.10");
    fpss=grasp_open("GRASP_DATAPATH", "swept-sine.ascii");
```

```

/* number of points to sample and fft (power of 2) */
npoint=NPOINT;

/* set the decay time (sec) */
decaytime=30.0;
/* get data */
while ((code=get_data(fpifo,fplock,&tstart,npoint,datas,&remain,&srate,0)) {
    /* put data into floats */
    for (i=0;i<npoint;i++) data[i]=datas[i];
    /* get the normalization */
    if (!pass++)
        normalize_gw(fpss,2*npoint,rate,response);
    /* Reset if just locked */
    if (code==1) {
        reset=0;
        tlock=tstart;
        avg_spec(data,average,npoint,&reset,rate,decaytime,2);
    } else {
        /* track average power spectrum, with Welch windowing. */
        avg_spec(data,average,npoint,&reset,rate,decaytime,2);
        /* loop over all frequencies except DC (j=0) & Nyquist (j=npoint/2) */
        for (j=1;j<npoint;j++) {
            /* subscripts of real, imaginary parts */
            ii=(ir=j+j)+1;
            /* frequency of the point */
            freq=0.5*rate*j/npoint;
            /* determine power spectrum in (meters/rHz) & print it */
            mod=response[ir]*response[ir]+response[ii]*response[ii];
            spec=sqrt(average[j]*mod);
            printf("%e\t%e\n",freq,spec);
        }
        /* print out useful things for xmgr program... */
        graphout(0,tstart,tlock);
    }
}
return 0;
}

```

```

void graphout(int last,float time,float tlock) {
    static int count=0;
    printf("&\n"); /* end of set marker */
    /* first time we draw the plot */
    if (count++==0) {
        printf("@doublebuffer true\n"); /* keeps display from flashing */
        printf("@focus off\n"); /* turn off the focus markers */
        printf("@s0 color 2\n"); /* FFT is red */
        printf("@g0 type logxy\n"); /* set graph type to log-log */
        printf("@autoscale \n"); /* autoscale FFT */
        printf("@world xmin %e\n",10.0); /* set min x */
        printf("@world xmax %e\n",5000.0); /* set max x */
        printf("@world ymin %e\n",1.e-19); /* set min y */
        printf("@world ymax %e\n",1.e-9); /* set max y */
        printf("@yaxis tick minor on\n"); /* turn on tick marks */
        printf("@yaxis tick major on\n"); /* turn on tick marks */
        printf("@yaxis tick minor 2\n"); /* turn on tick marks */
        printf("@yaxis tick major 1\n"); /* turn on tick marks */
        printf("@redraw \n"); /* redraw graph */
    }
}

```

```

printf("@xaxis label \"f (Hz)\\n"); /* FFT horizontal axis label */
printf("@yaxis label \"meters/rHz\\n"); /* FFT vertical axis label */
printf("@title \"Calibrated IFO Spectrum\\n"); /* set title */
/* set subtitle */
printf("@subtitle \"%2f sec since last lock. t = %2f sec.\\n",time-tlock,time);
if (!last) printf("@kill s0\\n"); /* kill graph; ready to read again */
}
else {
/* other times we redraw the plot */
/* set subtitle */
printf("@subtitle \"%2f sec since last lock. t = %2f sec.\\n",time-tlock,time);
printf("@s0 color 2\\n"); /* FFT is red */
printf("@g0 type logxy\\n"); /* set graph type to log-log */
printf("@world xmin %e\\n",10.0); /* set min x */
printf("@world xmax %e\\n",5000.0); /* set max x */
printf("@world ymin %e\\n",1.e-19); /* set min y */
printf("@world ymax %e\\n",1.e-9); /* set max y */
printf("@yaxis tick minor on\\n"); /* turn on tick marks */
printf("@yaxis tick major on\\n"); /* turn on tick marks */
printf("@yaxis tick minor 2\\n"); /* turn on tick marks */
printf("@yaxis tick major 1\\n"); /* turn on tick marks */
printf("@redraw\\n"); /* redraw the graph */
if (!last) printf("@kill s0\\n"); /* kill graph; ready to read again */
}
return;
}

```

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Comments: See comments for power\_spectrum example program.

### 3.15 Example: diag program

This program is a frequency-domain “novelty detector” and provides a simple example of a time-frequency diagnostic method. The actual code is not printed here, but may be found in the GRASP directory `src/examples/exan` in the file `diag.c`.

The method used by `diag` is as follows:

1. A buffer is loaded with a short stretch of data samples (2048 in this example, about 1/5 of a second).
2. A (Welch-windowed) power spectrum is calculated from the data in the buffer. In each frequency bin, this provides a value  $S(f)$ .
3. Using the same auto-regressive averaging technique described in `avg_spec()` the mean value of  $S(f)$  is maintained in a time-averaged spectrum  $\langle S(f) \rangle$ . The exponential-decay time constant for this average is `AVG_TIME` (10 seconds, in this example).
4. The absolute difference between the current spectrum and the average  $\Delta S(f) \equiv |S(f) - \langle S(f) \rangle|$  is determined. Note that the absolute value used here provides a more robust first-order statistic than would be provided by a standard variance  $(\Delta S(f))^2$ .
5. Using the same auto-regressive averaging technique described in `avg_spec()` the value of  $\Delta S(f)$  is maintained in a time-averaged absolute difference  $\langle \Delta S(f) \rangle$ . The exponential-decay time constant for this average is also set by `AVG_TIME`.
6. In each frequency bin,  $\Delta S(f)$  is compared to  $\langle \Delta S(f) \rangle$ . If  $\Delta S(f) > \text{THRESHOLD} \times \langle \Delta S(f) \rangle$  then a point is plotted for that frequency bin; otherwise no point is plotted for that frequency bin. In this example, `THRESHOLD` is set to 6.
7. In each frequency bin,  $\Delta S(f)$  is compared to  $\langle \Delta S(f) \rangle$ . If  $\Delta S(f) < \text{INCLUDE} \times \langle \Delta S(f) \rangle$  then the values of  $S(f)$  and  $\Delta S(f)$  are used to “refine” or “revise” the auto-regressive means described previously. In this example, `INCLUDE` is set to 10.
8. Another set of points (1024 in this example) is loaded into the end of the buffer, pushing out the oldest 1024 points from the start of the buffer, and the whole loop is restarted at step 2 above.

The `diag` program can be used to analyze any of the different channels of fast-sampled data, by setting `CHANNEL` appropriately. It creates one output file for each locked segment of data. For example if `CHANNEL` is set to 0 (the IFO channel) and there are four locked sections of data, one obtains a set of files: `ch0diag.000`, `ch0diag.001`, `ch0diag.002`, and `ch0diag.003`.

In similar fashion, if `CHANNEL` is set to 1 (the magnetometer) one obtains files: `ch1diag.000`, `ch1diag.001`, `ch1diag.002`, and `ch1diag.003`.

These files may be used as input to the `xmgr` graphing program, by typing:

```
xmgr ch0diag.000 ch1diag.000
```

(one may specify as many channels as desired on the input line). A typical pair of outputs is shown in Figures 7 and 8. By specifying several different channels on the command line for starting `xmgr`, you can overlay the different channels output with one another. This provides a visual tool for identifying correlations between the channels (the graphs shown below may be overlaid in different colors).

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Comments: This type of time-frequency event detector appears quite useful as a diagnostic tool. It might be possible to improve its high-frequency time resolution by being clever about using intermediate

19 November 1994 run 1

Time/Frequency statistics for channel 0

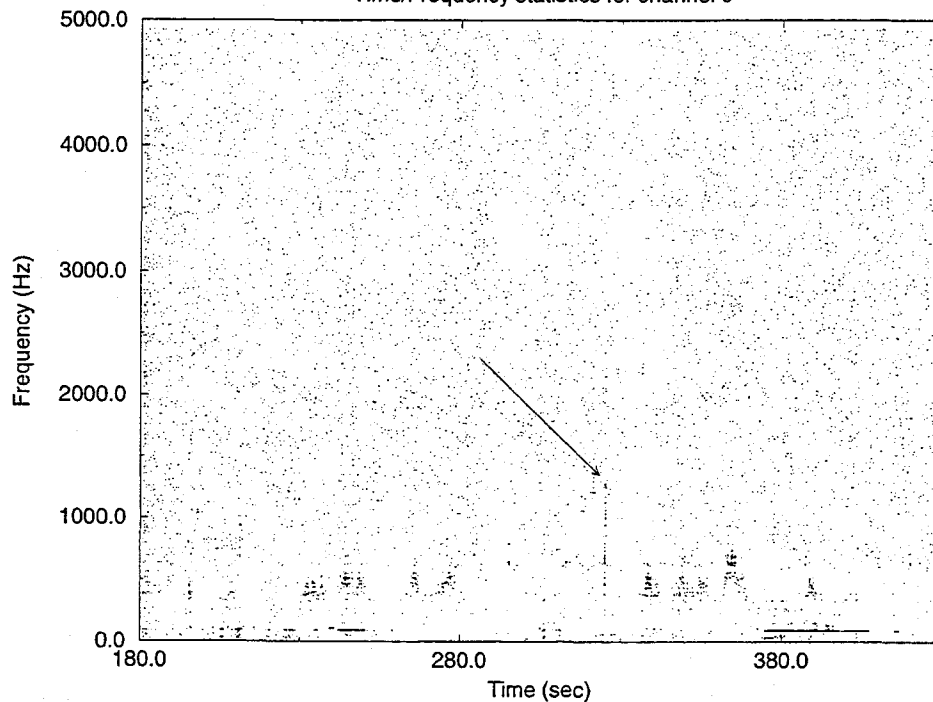


Figure 7: A time-frequency diagnostic graph produced by `diag`. The vertical line pointed to by the arrow is a non-stationary noise event in the IFO output, 325 seconds into the locked section. It sounds like a “drip” and might be due to off-axis modes in the interferometer optical cavities.

information during the recursive calculation of the FFT. One should probably also experiment with using other statistical measures to assess the behavior of the different frequency bins. It would be nice to modify this program to also examine the slow sampled channels (see comment for `get_data()`).

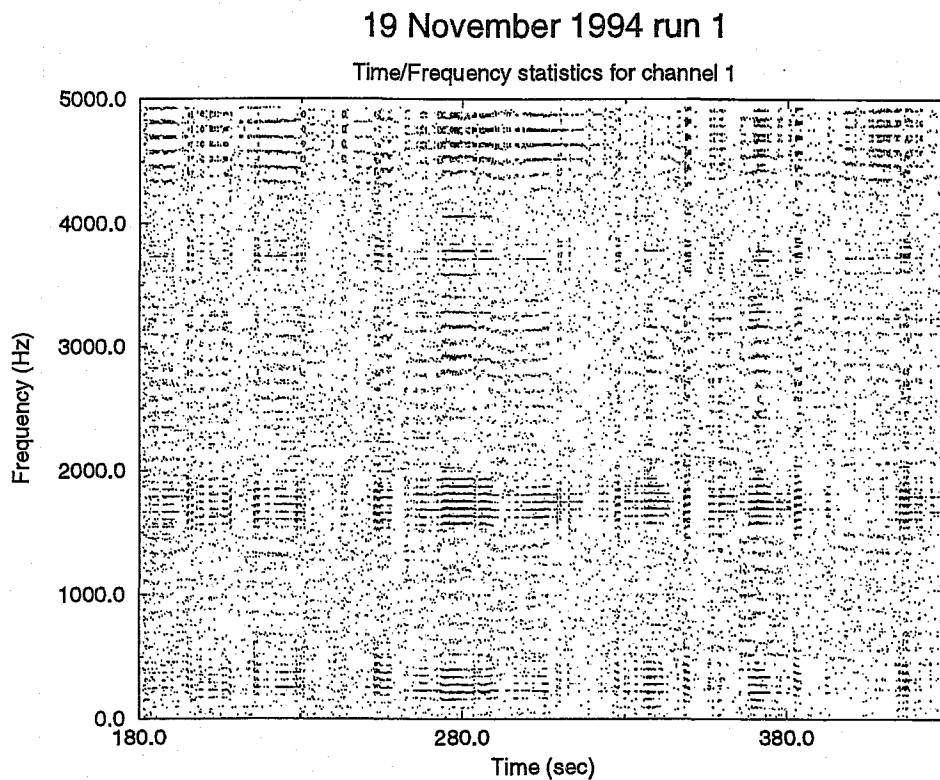


Figure 8: A time-frequency diagnostic graph produced by `diag`. This shows the identical period as the previous graph, but for the magnetometer output. Notice that the spurious event was not caused by magnetic field fluctuations.

## 4 GRASP Routines: Reading/using FRAME format data

The LIGO and VIRGO projects have recently adopted a data format standard called the FRAME format for time-domain data. The 40-meter laboratory at Caltech implemented this data format in Spring 1997; data taken after that time is in the FRAME format. The FRAME libraries are publicly available from the VIRGO project; they may be downloaded from the site <http://lapphp.in2p3.fr/virgo/FrameL>. Contact Benoit Mours [mours@lapp.in2p3.fr](mailto:mours@lapp.in2p3.fr) for further information.

The GRASP package includes routines for reading and using data in the FRAME format. Also included in the GRASP package is a translator (see Section 10.16) which translates data from the old data format used in 1994 to the new FRAME format. Data distributed for use with GRASP will primarily be distributed in this new FRAME format, and over a period of time we will remove from the GRASP package all of the code and routines which make use of the old format. In order to help make the transition from old format to FRAME format as smooth as possible, the GRASP package currently contains both old format and FRAME format versions of all of the example programs. For example `animate` and `animateF` are two versions of the same program. The first reads data in the old format, the second reads data in the FRAME format. If you are new to GRASP, we don't recommend that you waste your time with the old data format; start using the FRAME format immediately.

Data distributed in the FRAME format may not be compatible with future releases of the FRAME library, so if the FRAME libraries are updated you may need to obtain a new copy of the standard 40-meter test data set from November 1994. The data that has been distributed and is currently being distributed makes use of either version 2.20 or 2.30 of the FRAME library. Only two files in the GRASP package (`src/utility/frameinterface.c` and `src/examples/examplesutility/translate.c`) depend upon the version of the FRAME library. We distribute GRASP with versions of these files appropriate for different releases (currently 2.20, 2.30, and 2.33) of the FRAME library. The version 2.30 FRAME library data format is compatible with versions 2.30 and 2.33 of the FRAME library.

In order to give the 1994 40-meter data a form as similar as possible to the data being taken in 1997 and beyond, the channel names used have been given equivalent "FRAME" forms. These are shown in Table 5.

Note that new data created in the frame format will attempt to address at least a couple of the problems in the "old format" data. In particular, new frame format data (i.e., post 1996) has sample rate in Hz always being powers of 2, for example, 4,096 Hz or 16 Hz or 16,384 Hz. In addition, each frame always contains a power-of-two number of seconds of data. These conventions will make it easy to "match up" sample of channels taken at different rates, and to do FFT's of the channels. However the 1994 data does not conform to either of these conventions: each frame of 1994 data contains 5000 samples of the slow channels, and 50,000 samples of the fast channels, during a 5.06666... second interval.



Channel #	≤ 14 Nov 94	FRAME name	≥ 18 Nov 94	FRAME name
0	IFO output	IFO_DMRO	IFO output	IFO_DMRO
1	unused		magnetometer	IFO_Mag_x
2	unused		microphone	IFO_Mike
3	microphone	IFO_Mike	unused	
4	dc strain	IFO_DCDM	dc strain	IFO_DCDM
5	mode cleaner pzt	PSL_MC_V	mode cleaner pzt	PSL_MC_V
6	seismometer	IFO_Seis_1	seismometer	IFO_Seis_1
7	unused		slow pzt	PSL_SPZT_V
8	unused		power stabilizer <sup>1</sup>	PSL_PSS <sup>1</sup>
9	unused		unused	
10	TTL locked	IFO_Lock	TTL locked	IFO_Lock
11	arm 1 visibility	IFO_EAT	arm 1 visibility	IFO_EAT
12	arm 2 visibility	IFO_SAT	arm 2 visibility	IFO_SAT
13	mode cleaner visibility	IFO_MCR	mode cleaner visibility	IFO_MCR
14	slow pzt	IFO_SPZT	unused	IFO_SPZT
15	arm 1 coil driver	SUS_EE_Coil_V	arm 1 coil driver	SUS_EE_Coil_V

1.

On 18 November 1994 run 1 this was accidentally disconnected until approximately 20:00 local time.

Table 5: Channel assignments for the November 1994 data runs. Channels 0-3 are the “fast” channels, sampled at about 10 kHz; the remaining twelve are the “slow” channels, sampled at about 1KHz. The equivalent “FRAME” format names are also given.

#### 4.1 Time-stamps in the November 1994 data-set

There is a serious problem in the original data format used in November 1994. To understand the nature of this problem, remember that the individual data samples (fast channels) are taken at about 10kHz, so that the time between samples is about 100  $\mu$ sec. Ideally, the time-stamps of the individual blocks should be recorded with a precision which is substantially greater than this, i.e. a few  $\mu$ sec at the most. However the November 1994 time stamps are recorded in two ways: as an integer number of seconds and msec (with 1000  $\mu$ sec resolution) and as a floating point elapsed time. This latter quantity has a resolution of less than one  $\mu$ sec at early times, but a resolution of about 2000  $\mu$ sec at late times (say 15,000 sec into a run).

Thus, in translating the November 1994 data into frames (which have 1 nanosec resolution time-stamps), a reasonable effort was made to "correct" these time-stamps as much as possible, and to specify the time at which each data block begins as precisely as possible. After some research, we believe that the each block of old-format data is precisely  $76/15 = 5.0666666 \dots$  seconds long. So we have corrected the time stamps accordingly. One can show that in general, our time stamps agree with those in the original data, when they are expressed as floats, i.e. with the precision recorded in the original data set. There are some blocks where there is an error in the least-significant bit of the cast-into-float quantity; we do not understand this as well as we would like.

Please, *be warned that the absolute time indicated by these stamps is not correct!* These time stamps were not taken with a modern GPS clock system, or even with an old-fashioned WWV system. Our understanding is that the real-time computer system on which these data were originally taken had its clock set by wristwatch, with an accuracy of perhaps  $\pm 5$  minutes.. Indeed the computer system crashed on November 15, 1994 and the clock was subsequently reset again, so even the time difference can not be trusted between November 14 and November 18 data. It appears that the computer clock was not reset after November 15th, so the relative times in the remaining data may be trustworthy with somewhat better than  $\pm 1$  msec accuracy.

In any data analysis work (such as pulsar searching) where it is important to have precise time-stamps, these shortcomings must be taken into account. If you really want to determine the times more precisely than a millisecond, our only suggestion is to examine the seismometer data channel and correlate it with similar data taken by a system with good time-stamps. We don't know where to find such data, but it might exist, somewhere, in the public domain. If you do go to this trouble, please write to us and tell us the conclusions of your study. We would be delighted to correct the absolute offset error in these November 1994 time-stamps, if someone could show us how to do it!

## 4.2 Function: `fget_ch()`

```
int fget_ch(struct fgetoutput *fgetoutput, struct fgetinput *fgetinput)
```

This is a general function for sequentially reading one or more channels of FRAME format data. It can be used to obtain either locked sections only, or both locked and unlocked sections, and to retrieve calibration information from the FRAME data. It concatenates multiple frames and multiple files containing frames as necessary, to return continuous-in-time sequences.

The inputs to the routine `fget_ch()` are contained in a structure:

```
struct fgetinput {
    int nchan;
    char **chnames;
    int npoint;
    short **locations;
    char *(*files)();
    int (*filedes)();
    int inlock;
    int seek;
    int calibrate;
};
```

The different elements of the structure are:

`nchan`: Input. The number of channels that you want to retrieve ( $\geq 1$ ).

`chnames`: Input. The list of channel names. Each element of `chnames[0..nchan-1]` is a pointer to a null-terminated string. Note that the number of channels requested, and their names, must not be changed after the first call to `fget_ch`. It is assumed that the first channel in the list has the fastest sample rate of any of the requested channels.

`npoint`: Input. The number of points requested from the first channel. (May change with each call.)

`locations`: Input. The locations in memory where the arrays corresponding to each channel should be placed are `locations[0..nchan-1]`. (May change with each call.)

`files()`: Input. A pointer to a function, which takes no arguments, and returns a pointer to a null-terminated character string. This string is the name of the file to look in for FRAME format data. If no further frames remain in the file, then the function `files()` is called again. When this function returns a null pointer, it is assumed that no further data remains. A useful utility function called `framefiles()` has been provided with GRASP, and may be used as this argument. (May change with each call.)

`filedes()`: Input. This argument is used if and only if the previous argument, `fgetinput.files` is NULL. If `fgetinput.files` is not NULL then this argument is not used. This argument is a pointer to a function, which takes no arguments, and returns an integer *file descriptor*. The integer returned is a file descriptor for a file containing FRAME format data. If no further frames remain in the file, then the function `filedes()` is called again. When this function returns a negative file descriptor, it is assumed that no further data remains. (May change with each call.)

`inlock`: Input. Set to zero, return all data; set to non-zero, return only the locked sections of data. If set nonzero, then on output `fgetoutput.locklow` and `fgetoutput.lockhi` will be set.

**seek:** Input. Set to zero, return data. Set to non-zero, seek past the data, performing all normal operations, but do not actually write any data into the arrays pointed to by `locations[0..nchan-1]`. (May change with each call.) This is useful for skipping rapidly past uninteresting regions of data, for example, the first few minutes after coming into lock.

**calibrate:** Input. If set non-zero, return calibration information. If set to zero, do not return calibration information. (May change with each call.)

Except as noted above, it is assumed that none of these input arguments are changed after the first call to `fget_ch()`. It is also assumed that within any given frame, the numbers of points contained in different channels are exact integer multiples or fractions of the numbers of points contained in the other channels.

The outputs from the routine `fget_ch()` are contained in a structure:

```
struct fgetoutput {
    double tstart;
    double srate;
    int *npoint;
    int *ratios;
    int discarded;
    double tfirst;
    double dt;
    double lostlock;
    double lastlock;
    int returnval;
    int frinum;
    float *fri;
    int tcalibrate;
    int locklow;
    int lockhi;
};
```

The different elements of the structure are:

**tstart:** Output. Time stamp of the first point output in channel `chnames[0]`. Note: please see the comments in Section 4.1.

**srate:** Output. Sample rate (in Hz) of channel `chnames[0]`.

**npoint:** Output. The number of points returned in channel `chnames[i]` is `npoint[i]`. Note that `npoint[0]` is precisely the number of points requested in the input structure `fgetinput.npoint`.

**ratios:** Output. The sample rate of channel `chnames[0]` divided by the sample rate of channel `chnames[i]` is given in `ratios[i]`. Thus `ratios[0]=1`.

**discarded:** The number of points discarded from channel `chnames[0]`. These points are discarded because there is a missing period of time between two consecutive frames, or because the instrument was not in lock for long enough to return the requested number of points (or for both reasons).

**tfirst:** Output. The time stamp of the first point returned in the first call to `fget_ch()`.

**dt:** Output. By definition, `tstart-tfirst`, which is the elapsed time since the first time stamp.

lostlock: Output. The time at which we last lost lock (if searching only for locked segments).

lastlock: Output. The time at which we last regained lock (if searching only for locked segments).

returnval: Output. The return value of `fget_ch()`: 0 if it is unable to satisfy the request, 1 if the request has been satisfied by beginning a new locked or continuous-in-time section, and 2 if the data returned is part of an ongoing locked or continuous-in-time sequence.

frinum: Output. Three times the number of frequency values for which we are returning static calibration information. If this number is not divisible by three, something is wrong!

fri: Output. A pointer to the array of calibration data. This data is arranged with a frequency, then the real part, then the imaginary part of the response, followed by another frequency, then real part, then imaginary part, etc. So `fri[0]=f0`, `fri[1]=r0`, `fri[2]=i0`, `fri[3]=f1`, `fri[4]=r1`, `fri[5]=i1`,... and the total length of the array is `fri[0..frinum-1]`.

tcalibrate: Output. The time at which the current calibration information became valid.

locklow. Output. The minimum value (inclusive) for "in-lock" in the lock channel. Set if and only if `fgetinput.inlock` is nonzero.

lockhi. Output. The maximum value (inclusive) for "in-lock" in the lock channel. Set if and only if `fgetinput.inlock` is nonzero.

This routine is a useful interface to the FRAME library. It reads frames from files. To get the name of the first file to open, this routine calls the function `files()` specified in the input structure. Then, whenever there are no remaining frames in this file, it calls `files()` again. This function must return the name of the desired file, or NULL if no files remain. For example:

```
static char *filelist[]={
"C1-94_11_19_23_50_46", "C1-94_11_19_23_53_28",
"C1-94_11_19_23_56_10", "C1-94_11_19_23_58_52",
"C1-94_11_20_00_01_34", "C1-94_11_20_00_04_16" };

char *files() {
    static int entry=0;
    if (entry>=6)
        return NULL;
    else
        return filelist[entry++];
}
```

The function `fget_ch()` returns 0 if it is unable to satisfy the request for `fgetinput.npoint` points. It returns 1 if the request has been satisfied, and it is beginning a new locked section (or if the frames were not contiguous in time, and it is beginning with a new frame). It returns 2 if the data returned is part of an ongoing locked or continuous sequence.

When several channels are requested, and they have different sample rates, the first channel requested must always have the fastest sample rate. Other requested channels may have this same sample rate, but none may have a faster sample rate. Points are returned from the slower channels if and only if they satisfy the following condition. Suppose that  $r$  is the ratio of the channel 0 sample rate to the channel K sample rate, and label the points in channel 0 by  $i = 0, \dots, nr - 1$ , and the points in channel K by  $j = 0, \dots, n - 1$ . Then point  $j$  in channel K is returned if and only if point  $i = rj$  is returned from channel 0.

Authors: Bruce Allen, ballen@dirac.phys.uwm.edu

Comments: We intend to store the ranges corresponding to “in lock” in the frames, so these will not need to be entered by the user.

### 4.3 Function: `framefiles()`

`char *framefiles()`

This is a "utility function" for frame access. It takes no arguments, and returns a pointer to a static character string. It is intended primarily as an argument to be passed to the function `fget_ch()` via the structure member `fgetinput.files`.

The operation of the `framefiles()` is determined by two environment variables: `GRASP_FRAMEPATH`, and `GRASP_REALTIME`. If `GRASP_REALTIME` is set, then the `framefiles()` interrogates the EPICS control system and returns a pointer to a character string containing the name of the frame file most recently written to disk. This option is only intended for use in the 40-meter lab control room, for real-time analysis of data. For most users of GRASP, this option will never be used. Note: to set/unset the environment variable, use the commands:

```
setenv GRASP_REALTIME
unsetenv GRASP_REALTIME
```

respectively.

If the `GRASP_REALTIME` environment variable is NOT set, then the behavior of `framefiles()` is determined by the value of the `GRASP_FRAMEPATH` environment variable. This variable should point to a directory, and may be set with a command like:

```
setenv GRASP_DATAPATH /usr/local/GRASP/data/18nov94.1frame
```

The first time that `framefiles()` is called, it looks for all files named `C1-*` in the directory pointed to by `GRASP_FRAMEPATH`. The file names are stored internally, `framefiles()` returns a pointer to a character string containing the name of the first of these files. The second call to `framefiles()` returns the name of the second file found in the directory, and so on. When no more files remain, `framefiles()` returns a NULL pointer.

A simple way to analyze a subset of data is to create a directory containing symbolic links to the FRAME files containing data that you want to analyze, and to set the environment variable `GRASP_FRAMEPATH` to point to that directory.

Authors: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: None.

#### 4.4 Example: locklistF program

This example uses the function `fget_ch` described in the previous section to print out location information and times for all the locked sections in the directory pointed to by the environment variable `GRASP_FRAMEPATH`. To run this program, type

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/18nov94.1frame
locklistF
```

and a list of locked time intervals will be printed out. Here is some typical output:

```
locklistF
FrameL Version:April 10, 1997; v2.23(Apr 10 1997 18:32:52 ../src/FrameL.c)
GRASP: framefiles(): using 83 files from directory /ballen2/18nov94.1frame
Id: frameinterface.c,v 1.4 1997/04/30 07:00:39 ballen Exp
Name: RELEASE_1_3
In lock from t = 0.000000 into run to 526.450008 into run for 526.450008 sec
Out of lock from t = 526.450008 into run to 555.384692 into run for 28.934683 s
In lock from t = 555.384692 into run to 667.775527 into run for 112.390835 sec
Out of lock from t = 667.775527 into run to 708.000798 into run for 40.225272 s
In lock from t = 708.000798 into run to 2268.670924 into run for 1560.670125 s
Out of lock from t = 2268.670924 into run to 2283.429062 into run for 14.75813 s
In lock from t = 2283.429062 into run to 3954.517061 into run for 1671.088000 s
Out of lock from t = 3954.517061 into run to 3966.367962 into run for 11.85090 s
GRASP: fget_ch(): FRAMES NOT SEQUENTIAL
run 3 frame 842 ended at time: 785221840.948503 sec
run 3 frame 843 started at time: 785223012.765137 sec
Time gap is 1171.816634 sec
Gap starts 4266.133503 seconds into run; ends 5437.950137 seconds into run.
Discarding 294210 points remaining in the previous frame(s).
Id: frameinterface.c,v 1.4 1997/04/30 07:00:39 ballen Exp
Name: RELEASE_1_3
In lock from t = 3966.367962 into run to 4266.133503 into run for 299.765540 s
Out of lock from t = 4266.133503 into run to 5437.950137 into run for 1171.816 s
GRASP: fget_ch(): FRAMES NOT SEQUENTIAL
run 3 frame 1040 ended at time: 785224015.965104 sec
run 3 frame 1041 started at time: 785224175.714844 sec
Time gap is 159.749740 sec
Gap starts 6441.150104 seconds into run; ends 6600.899844 seconds into run.
Discarding 132000 points remaining in the previous frame(s).
Id: frameinterface.c,v 1.4 1997/04/30 07:00:39 ballen Exp
Name: RELEASE_1_3
In lock from t = 5437.950137 into run to 6441.150104 into run for 1003.199968 s
Out of lock from t = 6441.150104 into run to 6600.899844 into run for 159.7497 s
In lock from t = 6600.899844 into run to 7375.472558 into run for 774.572714 s
Out of lock from t = 7375.472558 into run to 7391.474039 into run for 16.00148 s
In lock from t = 7391.474039 into run to 7685.337699 into run for 293.863659 s
Out of lock from t = 7685.337699 into run to 7719.763049 into run for 34.42535 s
In lock from t = 7719.763049 into run to 7973.647310 into run for 253.884261 s
Out of lock from t = 7973.647310 into run to 8083.507974 into run for 109.8606 s
In lock from t = 8083.507974 into run to 9160.715956 into run for 1077.207982 s
```



```

Out of lock from t = 9160.715956 into run to 9220.780081 into run for 60.064125 s
In lock from t = 9220.780081 into run to 10552.863624 into run for 1332.083544 s
Out of lock from t = 10552.863624 into run to 10585.141461 into run for 32.277837 s
In lock from t = 10585.141461 into run to 11466.650847 into run for 881.509386 s
Out of lock from t = 11466.650847 into run to 11483.939559 into run for 17.288712 s
In lock from t = 11483.939559 into run to 13268.796352 into run for 1784.856793 s
Out of lock from t = 13268.796352 into run to 13297.379120 into run for 28.582768 s
GRASP: fget_ch(): could not open NULL file name
had 0 points; still need 296000 points...
Discarding 0 points remaining in the previous frame(s).
Id: frameinterface.c,v 1.4 1997/04/30 07:00:39 ballen Exp
Name: RELEASE_1_3

```

Note that this example only prints out information for locked sections longer than 30 sec. Also notice that because there are time gaps in between some of the successive frames, error messages are printed out. Notice the form of the GRASP error and warning messages. These typically begin with a line like:

```

GRASP: fget_ch(): this is the warning or error message
which specifies which GRASP function the error messages come from. They end with a pair of lines like
Id: frameinterface.c,v 1.4 1997/04/30 07:00:39 ballen Exp
Name: Name: RELEASE_1_3

```

which are information about the file from which the warning or error message came, including its version/release numbers. Here is the code for the locklistF example program:

```

/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

int main() {
    double begin,end,savebegin,saveend;
    struct fgetoutput fgetoutput;
    struct fgetinput fgetinput;

    /* this number of samples is about 30 seconds of data */
    fgetinput.npoint=296000;

    /* number of channels needed is one */
    fgetinput.nchan=1;

    /* storage for channel names, data locations, points returned, ratios */
    fgetinput.chnames=(char **)malloc(fgetinput.nchan*sizeof(char *));
    fgetinput.locations=(short **)malloc(fgetinput.nchan*sizeof(short *));
    fgetoutput.npoint=(int *)malloc(fgetinput.nchan*sizeof(int));
    fgetoutput.ratios=(int *)malloc(fgetinput.nchan*sizeof(int));

    /* since we operate in SEEK mode, no space needed for data storage */
    fgetinput.locations[0]=NULL;

    /* use utility function framefiles() to retrieve file names */
    fgetinput.files=framefiles;

    /* get only the locked sections */
    fgetinput.inlock=1;

    /* seek over data (we don't care what the values are!) */
    fgetinput.seek=1;

```

```

/* don't need calibration information */
fgetinput.calibrate=0;

/* set channel name */
fgetinput.chnames[0]="IFO_DMRO";

/* start the main loop */
while (1) {

    /* find the next locked section of the data */
    fget_ch(&fgetoutput,&fgetinput);

    /* see if we fell out of lock, and print if we did */
    if (fgetoutput.returnval==1) {

        /* time at which lock lost (relative to start of run) */
        begin=fgetoutput.lostlock-fgetoutput.tfirist;

        /* time at which lock aquired (relative to start of run) */
        end=fgetoutput.lastlock-fgetoutput.tfirist;
        if (begin>0.0 || fgetoutput.returnval==0) {
            printf("In lock from t = %f into run to %f into run for %f sec\n",
                saveend,begin,begin-saveend);
            printf("Out of lock from t = %f into run to %f into run for %f sec\n",
                begin,end,end-begin);
        }
        saveend=end;
    }

    /* if no data remains, then exit */
    if (fgetoutput.returnval==0) {
        printf("End of data at time %f\n",fgetoutput.tstart-fgetoutput.tfirist);
        break;
    }
}
return 0;
}

```

## 4.5 Example: gwoutputF program

This example uses the function `fget_ch()` described in the previous section to print out a two-column file containing the IFO output for the first locked section containing 100 sample points. To run this program, type

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/18nov94.1frame
gwoutputF
```

In the output, the left column is time values, and the right column is the actual IFO output (note that because this comes from a 12 bit A-D converter, the output is an integer value from -2047 to 2048). The program works by acquiring data 100 points at a time, then printing out the values, then acquiring 100 more points, and so on. Whenever a new locked section begins, the program prints a banner message to alert the user. Note that typical locked sections contain  $\approx 10^7$  points of data, so this program should not be used for real work – it's just a demonstration!

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

main() {
    float tstart,time,srate;
    int i,npoint,code;
    short *data;
    struct fgetinput fgetinput;
    struct fgetoutput fgetoutput;

    /* specify the number of points of output & allocate array */
    npoint=100;
    data=(short *)malloc(sizeof(short)*npoint);
    fgetinput.npoint=npoint;

    /* we only want one channel of data */
    fgetinput.nchan=1;

    /* use the framefiles() function to find it */
    fgetinput.files=framefiles;

    /* allocate space to store channel names */
    fgetinput.chnames=(char **)malloc(fgetinput.nchan*sizeof(char *));

    /* allocate space for data storage location addresses */
    fgetinput.locations=(short **)malloc(fgetinput.nchan*sizeof(short *));

    /* allocate space for numbers of points returned in each channel */
    fgetoutput.npoint=(int *)malloc(fgetinput.nchan*sizeof(int));

    /* allocate space for ratios of channel sample rates */
    fgetoutput.ratios=(int *)malloc(fgetinput.nchan*sizeof(int));

    /* channel name */
    fgetinput.chnames[0]="IFO_DMRO";

    /* set up different cases */
    if (NULL!=getenv("GRASP_REALTIME")) {
        /* don't care if locked */
        fgetinput.inlock=0;
    }
    else {
```

```

    /* only locked */
    fgetinput.inlock=1;
}

fgetinput.seek=0;
fgetinput.calibrate=0;
fgetinput.locations[0]=data;

while (1) {
    /* get npoint points of data */
    code=fget_ch(&fgetoutput,&fgetinput);
    tstart=fgetoutput.dt;
    srate=fgetoutput.srate;

    /* if no data remains, exit loop */
    if (code==0) break;
    /* if starting a new locked segment, print banner */
    if (code==1) {
        printf("_____ NEW LOCKED SEGMENT _____\n\n");
        printf("  Time (sec)\t  IFO output\n");
    }
    /* now output the data */
    for (i=0;i<npoint;i++) {
        time=tstart+i/srate;
        printf("%f\t%d\n",time,(int)data[i]);
    }
}
/* close the data files, and return */
return 0;
}

```

## 4.6 Example: animateF program

This example uses the function `fget_ch()` described in the previous section to produce an animated display showing the time series output of the IFO in a lower window, and a simultaneously calculated FFT power spectrum in the upper window. To run this program, type

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/18nov94.1frame
animateF | xmgr -pipe
```

This output from this program must be piped into a public domain graphing program called `xmgr`. This may be obtained from <http://plasma-gate.weizmann.ac.il/Xmgr/>. (This lists mirror sites in the USA and Europe also). Some sample output of `animateF` is shown in Figure 9.

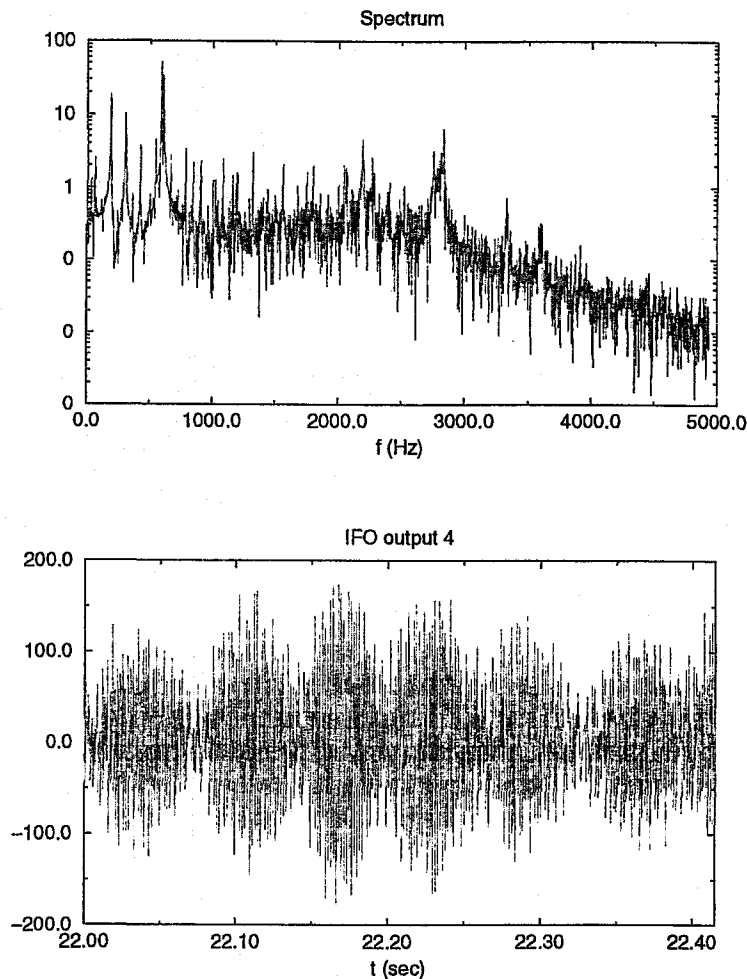


Figure 9: Snapshot of output from `animateF`. This shows the (whitened) CIT 40-meter IFO a few seconds after acquiring lock, before the violin modes have damped down

After compilation, to run the program type:

```
animateF | xmgr -pipe &
```

to get an animated display showing the data flowing by and the power spectrum changing, starting from the first locked data. You can also use this program with command-line arguments, for example

```
animateF 100 4 500 7 900 1.5 | xmgr -pipe &
```

will show the data from time  $t = 100$  to time  $t = 104$  seconds, then from  $t = 500$  to  $t = 507$ , then from  $t = 900$  to  $t = 901.5$ . Notice that the sequence of start times must be increasing. Note: the start times are

---

```

        case 0:
==>         delt=(x[ilen-1]-x[0])/(ilen-1.0);
==>         T=(x[ilen-1]-x[0]);
            setlength(cg,specset,ilen/2);
            xx=getx(cg,specset);
        ...

        case 1:
==>         delt=(x[ilen-1]-x[0])/(ilen-1.0);
==>         T=(x[ilen-1]-x[0]);

```

Figure 10: The corrections to a bug in the xmgr program are indicated by the arrows above. This bug is in the routine do\_fourier() in the file computils.c.

---

measured relative to the first data point in the first frame of data.

Note: The xmgr program as commonly distributed has a simple bug that needs to be repaired, in order for the frequency scale of the Fourier transform to be correct. The corrected version of xmgr is shown in Figure 10.

```

/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

int main(int argc,char **argv) {
    void graphout(float,float,int);
    float tstart=1.e35,srate=1.e-30,tmin,tmax,dt;
    double time;
    int i,seq=0,code,npoint=4096;
    short *data;
    struct fgetinput fgetinput;
    struct fgetoutput fgetoutput;

    /* number of channels */
    fgetinput.nchan=1;

    /* source of files */
    fgetinput.files=framefiles;

    /* storage for channel names, data locations, points returned, ratios */
    fgetinput.chnames=(char **)malloc(fgetinput.nchan*sizeof(char *));
    fgetinput.locations=(short **)malloc(fgetinput.nchan*sizeof(short *));
    fgetoutput.npoint=(int *)malloc(fgetinput.nchan*sizeof(int));
    fgetoutput.ratios=(int *)malloc(fgetinput.nchan*sizeof(int));

    /* set up channel names, etc. for different cases */
    fgetinput.chnames[0]="IFO_DMRO";

    /* set up for different cases */
    if (NULL!=getenv("GRASP_REALTIME")) {
        /* 40 meter lab */
        fgetinput.chnames[0]=getenv("GRASP_REALTIME");
        fgetinput.inlock=0;
    }
}

```

```

}
else {
    /* Nov 1994 data set */
    fgetinput.inlock=1;
}

/* number of points to get */
fgetinput.npoint=npoint;

/* don't seek, we need the sample values! */
fgetinput.seek=0;

/* but we don't need calibration information */
fgetinput.calibrate=0;

/* allocate storage space for data */
data=(short *)malloc(sizeof(short)*npoint);
fgetinput.locations[0]=data;

/* handle case where user has supplied t or dt arguments */
if (argc==1) {
    tmin=-1.e30;
    dt=2.e30;
    argc=-1;
}

/* now loop ... */
seq=argc;
while (argc!=1) {
    /* get the next start time and dt */
    if (argc!=-1) {
        sscanf(argv[seq-argc+1], "%f", &tmin);
        sscanf(argv[seq-argc+2], "%f", &dt);
        argc-=2;
    }
    /* calculate the end of the observation interval, and get data */
    tmax=tmin+dt;
    while (1) {
        /* decide whether to skip (seek) or get sample values */
        if (tstart<tmin-(npoint+20.)/srate)
            fgetinput.seek=1;
        else
            fgetinput.seek=0;

        /* seek, or get the sample values */
        code=fget_ch(&fgetoutput, &fgetinput);

        /* elapsed time, sample rate */
        tstart=fgetoutput.dt;
        srate=fgetoutput.srate;

        /* if no data left, return */
        if (code==0) return 0;

        /* we need to be outputting now... */
        if (tmin<=tstart){
            for (i=0; i<npoint; i++) {
                time=tstart+i/srate;
                printf("%f\t%d\n", time, data[i]);
            }
        }
    }
}

```

```

    }

    /* put out information for the graphing program */
    graphout(tstart, tstart+npoint/srate, (argc==1 && time>=tmax));
}
/* if we are done with this interval, try next one */
if (time>=tmax) break;
}
}
return 0;
}

```

```

/* This routine is pipes output into the xmgr graphing program */
void graphout(float x1, float x2, int last) {
    static int count=0;
    printf("&n"); /* end of set marker */
    /* first time we draw the plot */
    if (count==0) {
        printf("@doublebuffer true&n"); /* keeps display from flashing */
        printf("@s0 color 3&n"); /* IFO graph is green */
        printf("@view 0.1, 0.1, 0.9, 0.45&n"); /* set the viewport for IFO */
        printf("@with g1&n"); /* reset the current graph to FFT */
        printf("@view 0.1, 0.6, 0.9, 0.95&n"); /* set the viewport FFT */
        printf("@with g0&n"); /* reset the current graph to IFO */
        printf("@world xmin %f&n", x1); /* set min x */
        printf("@world xmax %f&n", x2); /* set max x */
        printf("@autoscale&n"); /* autoscale first time through */
        printf("@focus off&n"); /* turn off the focus markers */
        printf("@xaxis label \"t (sec)\"&n"); /* IFO axis label */
        printf("@fft(s0, 1)&n"); /* compute the spectrum */
        printf("@s1 color 2&n"); /* FFT is red */
        printf("@move g0.s1 to g1.s0&n"); /* move FFT to graph 1 */
        printf("@with g1&n"); /* set the focus on FFT */
        printf("@g1 type logy&n"); /* set FFT to log freq axis */
        printf("@autoscale&n"); /* autoscale FFT */
        printf("@subtitle \"Spectrum\"&n"); /* set the subtitle */
        printf("@xaxis label \"f (Hz)\"&n"); /* FFT axis label */
        printf("@with g0&n"); /* reset the current graph IFO */
        printf("@subtitle \"IFO output %d\"&n", count++); /* set IFO subtitle */
        if (!last) printf("@kill s0&n"); /* kill IFO; ready to read again */
    }
    else {
        /* other times we redraw the plot */
        printf("@s0 color 3&n"); /* set IFO green */
        printf("@fft(s0, 1)&n"); /* FFT it */
        printf("@s1 color 2&n"); /* set FFT red */
        printf("@move g0.s1 to g1.s0&n"); /* move FFT to graph 1 */
        printf("@subtitle \"IFO output %d\"&n", count++); /* set IFO subtitle */
        printf("@world xmin %f&n", x1); /* set min x */
        printf("@world xmax %f&n", x2); /* set max x */
        printf("@autoscale yaxes&n"); /* autoscale IFO */
        printf("@clear stack&n"); /* clear the stack */
        if (!last) printf("@kill s0&n"); /* kill IFO data */
        printf("@with g1&n"); /* switch to FFT */
        printf("@g1 type logy&n"); /* set FFT to log freq axis */
        printf("@clear stack&n"); /* clear stack */
        if (!last) printf("@kill s0&n"); /* kill FFT */
        printf("@with g0&n"); /* ready to read IFO again */
    }
}

```



```
return;
```

```
}
```

#### 4.7 Swept-sine calibration information

The swept sine calibration files are 3-column ASCII files, of the form:

$$\begin{array}{ccc} f_0 & r_0 & i_0 \\ f_1 & r_1 & i_1 \\ f_2 & r_2 & i_2 \\ & \dots & \\ f_m & r_m & i_m \end{array}$$

where the  $f_j$  are frequencies, in Hz, and  $r_j$  and  $i_j$  are dimensionless ratios of voltages. There are typically  $m = 801$  lines in these files. The data from these files (as well as one additional line of the form 0.0 0.0 0.0

showing vanishing response at DC) have been included in the frames. Each line gives the ratio of the IFO output voltage to a calibration coil driving voltage, at a different frequency. The  $r_j$  are the "real part" of the response, i.e. the ratio of the IFO output in phase with the coil driving voltage, to the coil driving voltage. The  $i_j$  are the "imaginary part" of the response, 90 degrees out of phase with the coil driving voltage. The sign of the phase (or equivalently, the sign of the imaginary part of the response) is determined by the following convention. Suppose that the driving voltage (in volts) is

$$V_{\text{coil}} = 10 \cos(\omega t) = 10 \Re e^{i\omega t} \quad (4.7.1)$$

where  $\omega = 2\pi \times 60$  radians/sec is the angular frequency of a 60 Hz signal. Suppose the response of the interferometer output to this is (again, in volts)

$$\begin{aligned} V_{\text{IFO}} &= 6.93 \cos(\omega t) + 4 \sin(\omega t) \\ &= 6.93 \cos(\omega t) - 4 \cos(\omega t + \pi/2) \\ &= 8 \Re e^{i(\omega t - \pi/6)} \end{aligned} \quad (4.7.2)$$

This is shown in Figure 11. An electrical engineer would describe this situation by saying that the phase of the response  $V_{\text{IFO}}$  is lagging the phase of the driving signal  $V_{\text{coil}}$  by  $30^\circ$ . The corresponding line in the swept sine calibration file would read:

$$\begin{array}{ccc} & \dots & \\ 60.000 & 0.6930 & -0.40000 \\ & \dots & \end{array}$$

Hence, in this example, the real part is positive and the imaginary part is negative. We will denote this entry in the swept sine calibration file by  $S(60) = 0.8 e^{-i\pi/6} = 0.693 - 0.400i$ . Because the interferometer output is real, there is also a value implied at negative frequencies which is the complex conjugate of the positive frequency value:  $S(-60) = S^*(60) = 0.8 e^{i\pi/6} = 0.693 + 0.400i$ .

Because the interferometer has no DC response, it is convenient for us to add one additional point at frequency  $f = 0$  into the output data arrays, with both the real and imaginary parts of the response set to zero. Hence the output arrays contain one element more than the number of lines in the input files. Note that both of these arrays are arranged in order of increasing frequency; after adding our one additional point they typically contain 802 points at frequencies from 0 Hz to 5001 Hz.

For the data runs of interest in this section (from November 1994) typically a swept sine calibration curve was taken immediately before each data tape was generated.

We will shortly address the following question. How does one use the dimensionless data in the swept-sine calibration curve to reconstruct the differential motion  $\Delta l(t)$  (in meters) of the interferometer arms? Here we address the closely related question: given  $V_{\text{IFO}}$ , how do we reconstruct  $V_{\text{coil}}$ ? We choose the sign

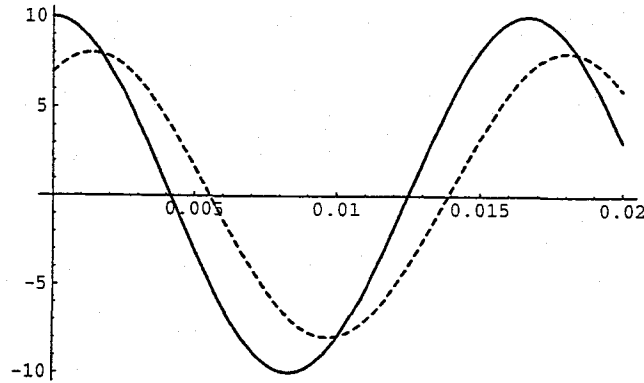


Figure 11: This shows a driving voltage  $V_{\text{coil}}$  (solid curve) and the response voltage  $V_{\text{IFO}}$  (dotted curve) as functions of time (in sec). Both are 60 Hz sinusoids; the relative amplitude and phase of the in-phase and out-of-phase components of  $V_{\text{IFO}}$  are contained in the swept-sine calibration files.

convention for the Fourier transform which agrees with that of *Numerical Recipes*: equation (12.1.6) of [1]. The Fourier transform of a function of time  $V(t)$  is

$$\tilde{V}(f) = \int e^{2\pi i f t} V(t) dt. \quad (4.7.3)$$

The inverse Fourier transform is

$$V(t) = \int e^{-2\pi i f t} \tilde{V}(f) df. \quad (4.7.4)$$

With these conventions, the signals (4.7.1) and (4.7.2) shown in in Figure 11 have Fourier components:

$$\tilde{V}_{\text{coil}}(60) = 5 \quad \text{and} \quad \tilde{V}_{\text{coil}}(-60) = 5, \quad (4.7.5)$$

$$\tilde{V}_{\text{IFO}}(60) = 4e^{i\pi/6} \quad \text{and} \quad \tilde{V}_{\text{IFO}}(-60) = 4e^{-i\pi/6}. \quad (4.7.6)$$

At frequency  $f_0 = 60$  Hz the swept sine file contains

$$S(60) = 0.8 e^{-i\pi/6} \Rightarrow S(-60) = S^*(60) = 0.8 e^{i\pi/6}. \quad (4.7.7)$$

since  $S(-f) = S^*(f)$ .

With these choices for our conventions, one can see immediately from our example (and generalize to all frequencies) that

$$\tilde{V}_{\text{coil}}(f) = \frac{\tilde{V}_{\text{IFO}}}{S^*(f)}. \quad (4.7.8)$$

In other words, with the *Numerical Recipes* [1] conventions for forward and reverse Fourier Transforms, the (FFT of the) calibration-coil voltage is the (FFT of the) IFO-output voltage divided by the complex conjugate of the swept sine response.

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Comments: The swept-sine calibration curves are usually quite smooth but sometimes they contain a “glitch” in the vicinity of 1 kHz; this may be due to drift of the unity-gain servo point.

#### 4.8 Function: GRcalibrate()

void GRcalibrate(float \*fri, int frinum, int num, float \*complex, float srate, int method, int order)

This is an intermediate-level routine which takes as input a pointer to an array containing the swept sine data, and outputs an array of interpolated points suitable for calibration of FFT's of the interferometer output.

The arguments are:

**fri:** Input. Pointer to an array containing swept sine data. The format of this data is  $fri[0]=f_0$ ,  $fri[1]=r_0$ ,  $fri[2]=i_0$ ,  $fri[3]=f_1$ ,  $fri[4]=r_1$ ,  $fri[5]=i_1, \dots$  and the total length of the array is  $fri[0..frinum-1]$ .

**frinum:** Input. The number of entries in the array  $fri[0..frinum-1]$ . If this number is not divisible by three, something is wrong!

**num:** Input. The number of points  $N$  in the FFT that we will be calibrating. This is typically  $N = 2^k$  where  $k$  is an integer. In this case, the number of distinct frequency values at which a calibration is needed is  $2^{k-1} + 1 = N/2 + 1$ , corresponding to the number of distinct frequency values from 0 (DC) to the Nyquist frequency  $f_{Nyquist}$ . See for example equation (12.1.5) of reference [1]. The frequencies are  $f_i = \frac{i}{N} F_{sample}$  for  $i = 0, \dots, N/2$ .

**srate:** Input. The sample rate  $F_{sample}$  (in Hz) of the data that we are going to be calibrating.

**complex:** Input. Pointer to an array  $complex[0..s]$  where  $s = 2^k + 1$ . The routine `calibrate()` fills in this array with interpolated values of the swept sine calibration data, described in the previous section. The real part of the DC response is in  $complex[0]$ , and the imaginary part is in  $complex[1]$ . The real/imaginary parts of the response at frequency  $f_1$  are in  $complex[2]$  and  $complex[3]$  and so on. The last two elements of  $complex[ ]$  contain the real/imaginary parts of the response at the Nyquist frequency  $F_{sample}/2$ .

**method:** Input. This integer sets the type of interpolation used to determine the real and imaginary part of the response, at frequencies that lie in between those given in the swept sine calibration files. Rational function interpolation is used if `method=0`. Polynomial interpolation is used if `method=1`. Spline interpolation with natural boundary conditions (vanishing second derivatives at DC and the Nyquist frequency) is used if `method=2`.

**order:** Input. Ignored if spline interpolation is used. If polynomial interpolation is used, then `order` is the order of the interpolating polynomial. If rational function interpolation is used, then the numerator and denominator are both polynomials of order `order/2` if `order` is even; otherwise the degree of the denominator is  $(order+1)/2$  and that of the numerator is  $(order-1)/2$ .

The basic problem solved by this routine is that the swept sine calibration data in a frame typically contain data at a few hundred distinct frequency values. However to properly calibrate the IFO output, one usually needs this calibration information at a large number of frequencies corresponding to the distinct frequencies associated with the FFT of a data set. This routine allows you to choose different possible interpolation methods. If in doubt, we recommend spline interpolation as the first choice. The interpolation methods are described in detail in Chapter 3 of reference [1].

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Comments: It might be better to interpolate values of  $f^2$  times the swept-sine response function, as this is the quantity needed to compute the IFO response function.

## 4.9 Example: print\_ssF program

This example uses the function `GRcalibrate()` to read the swept sine calibration information from a frame, and then prints out a list of frequencies, real, and imaginary parts interpolated from this data. The frequencies are appropriate for the FFT of a 4096 point data set with sample rate `srate`. The technique used is spline interpolation. To run this program, and display a graph, type

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/18nov94.1frame
print_ssF > outputfile
xmgr -nxy outputfile
```

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
#define NPOINT 4096

int main() {
    float cplx[NPOINT+2], srate, freq;
    int npoint, i;
    struct fgetoutput fgetoutput;
    struct fgetinput fgetinput;

    /* we need to ask for some sample values, even though all we want is calibration */
    fgetinput.npoint=256;

    /* number of channels */
    fgetinput.nchan=1;

    /* storage for channel names, data locations, points returned, ratios */
    fgetinput.chnames=(char **)malloc(fgetinput.nchan*sizeof(char *));
    fgetoutput.npoint=(int *)malloc(fgetinput.nchan*sizeof(int));
    fgetoutput.ratios=(int *)malloc(fgetinput.nchan*sizeof(int));

    /* use utility function framefiles() to retrieve file names */
    fgetinput.files=framefiles;

    /* don't care if IFO is in lock */
    fgetinput.inlock=0;

    /* don't need data anyway, so might as well seek */
    fgetinput.seek=1;

    /* but we DO need the calibration information */
    fgetinput.calibrate=1;

    /* set the channel name */
    fgetinput.chnames[0]="IFO_DMRO";

    /* number of points of (imagined) FFT */
    npoint=NPOINT;

    /* now get the data (none) and calibration (what we want) */
    fget_ch(&fgetoutput, &fgetinput);

    /* the fast-channel sample rate */
    srate=fgetoutput.srate;

    /* swept sine calibration array is first argument */
```

```

GRcalibrate(fgetoutput.fri, fgetoutput.frinum, npoint, cplx, srate, 2, 0);

/* print out frequency, real, imaginary interpolated values */
printf("# Freq (Hz)\tReal\t\tImag\n");
for (i=0; i<=NPOINT/2; i++) {
    freq=i*srate/NPOINT;
    printf("%e\t%e\t%e\n", freq, cplx[2*i], cplx[2*i+1]);
}
return 0;
}
}

```

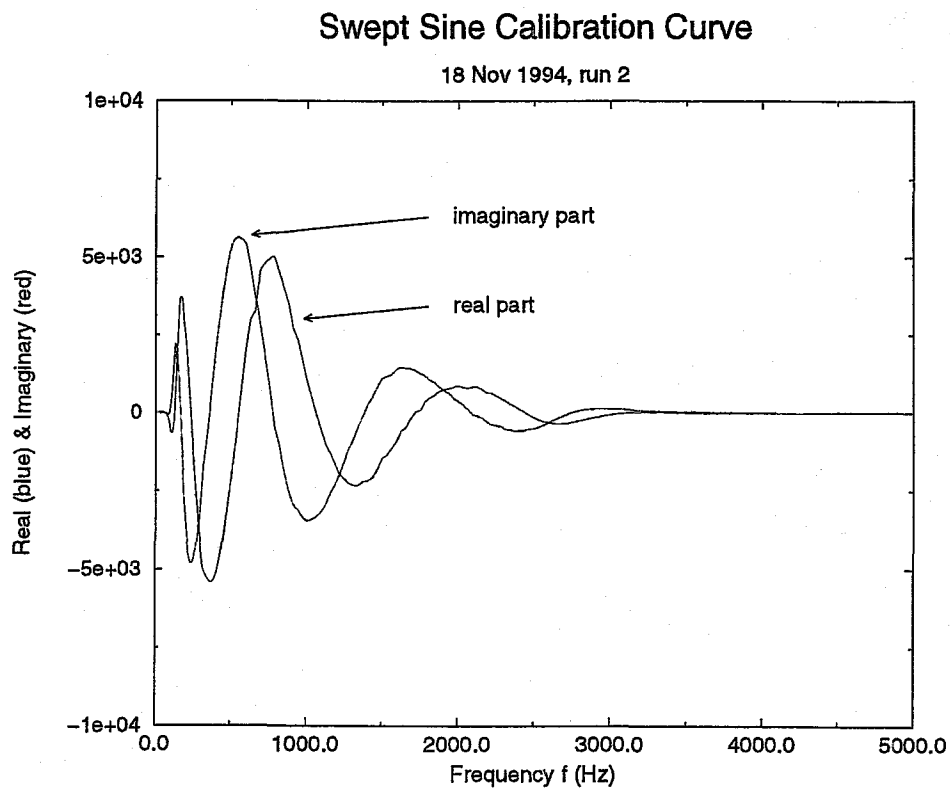


Figure 12: A swept sine calibration curve, showing the real and imaginary parts, produced by the example program `print_ssF`.

#### 4.10 Function: GRnormalize()

```
void GRnormalize(float *fri, int frinum, int npoint, float srate, float *response)
```

This routine generates an array of complex numbers  $R(f)$  from the swept sine information in a frame, and an overall calibration constant. Multiplying this array of complex numbers by (the FFT of) the raw IFO data yields the (FFT of the) differential displacement of the interferometer arms  $\Delta l$ , in meters:  $\widetilde{\Delta l}(f) = R(f)\widetilde{C}_{\text{IFO}}(f)$ . The units of  $R(f)$  are meters/ADC-count.

The arguments are:

- fri:** Input. Pointer to an array containing swept sine data. The format of this data is  $\text{fri}[0]=f_0$ ,  $\text{fri}[1]=r_0$ ,  $\text{fri}[2]=i_0$ ,  $\text{fri}[3]=f_1$ ,  $\text{fri}[4]=r_1$ ,  $\text{fri}[5]=i_1, \dots$  and the total length of the array is  $\text{fri}[0..\text{frinum}-1]$ .
- frinum:** Input. The number of entries in the array  $\text{fri}[0..\text{frinum}-1]$ . If this number is not divisible by three, something is wrong!
- npoint:** Input. The number of points  $N$  of IFO output which will be used to calculate an FFT for normalization. Must be an integer power of 2.
- srate:** Input. The sample rate in Hz of the IFO output.
- response:** Output. Pointer to an array  $\text{response}[0..s]$  with  $s = N + 1$  in which  $R(f)$  will be returned. By convention,  $R(0) = 0$  so that  $\text{response}[0]=\text{response}[1]=0$ . Array elements  $\text{response}[2i]$  and  $\text{response}[2i+1]$  contain the real and imaginary parts of  $R(f)$  at frequency  $f = \text{israte}/N$ . The response at the Nyquist frequency  $\text{response}[N]=0$  and  $\text{response}[N+1]=0$  by convention.

The absolute normalization of the interferometer can be obtained from the information in the swept sine file, and one other normalization constant which we denote by  $Q$ . It is easy to understand how this works. In the calibration process, one of the interferometer end mirrors of mass  $m$  is driven by a magnetic coil. The equation of motion of the driven end mass is

$$m \frac{d^2}{dt^2} \Delta l = F(t) \quad (4.10.1)$$

where  $F(t)$  is the driving force and  $\Delta l$  is the differential length of the two interferometer arms, in meters. Since the driving force  $d(t)$  is proportional to the coil current and thus to the coil voltage, in frequency space this equation becomes

$$(-2\pi i f)^2 \widetilde{\Delta l} = \text{constant} \times \widetilde{V}_{\text{coil}} = \text{constant} \times \frac{\widetilde{V}_{\text{IFO}}}{S^*(f)}. \quad (4.10.2)$$

We have substituted in equation (4.7.8) which relates  $\widetilde{V}_{\text{IFO}}$  and  $\widetilde{V}_{\text{coil}}$ . The IFO voltage is directly proportional to the quantity recorded in the IFO output channel:  $V_{\text{IFO}} = \text{ADC} \times C_{\text{IFO}}$ , with the constant ADC being the ratio of the analog-to-digital converters input voltage to output count.

Putting together these factors, the properly normalized value of  $\Delta l$ , in meters, may be obtained from the information in the IFO output channel, the swept sine calibration information, and the quantities given in Table 6 by

$$\widetilde{\Delta l} = R(f) \times \widetilde{C}_{\text{IFO}} \quad \text{with} \quad R(f) = \frac{Q \times \text{ADC}}{-4\pi^2 f^2 S^*(f)}, \quad (4.10.3)$$

where the  $\sim$  denotes Fourier transform, and  $f$  denotes frequency in Hz. (Note that, apart from the complex conjugate on  $S$ , the conventions used in the Fourier transform drop out of this equation, provided that

Table 6: Quantities entering into normalization of the IFO output.

Description	Name	Value	Units
Gravity-wave signal (IFO output)	$C_{\text{IFO}}$	varies	ADC counts
A→D converter sensitivity	ADC	10/2048	$V_{\text{IFO}} (\text{ADC counts})^{-1}$
Swept sine calibration	S(f)	from file	$V_{\text{IFO}} (V_{\text{coil}})^{-1}$
Calibration constant	$Q$	$1.428 \times 10^{-4}$	meter $\text{Hz}^2 (V_{\text{coil}})^{-1}$

identical conventions (4.7.3,4.7.4) are applied to both  $\Delta l$  and to  $C_{\text{IFO}}$ . The constant quantity  $Q$  indicated in the above equations has been calculated and documented in a series of calibration experiments carried out by Robert Spero. In these calibration experiments, the interferometer's servo was left open-loop, and the end mass was driven at a single frequency, hard enough to move the end mass one-half wavelength and shift the interferences fringes pattern over by one fringe. In this way, the coil voltage required to bring about a given length motion at a particular frequency was established, and from this information, the value of  $Q$  may be inferred. During the November 1994 runs the value of  $Q$  was given by

$$Q = \frac{\sqrt{9.35 \text{ Hz}}}{k} = 1.428 \times 10^{-4} \frac{\text{meter Hz}^2}{V_{\text{coil}}} \quad \text{where } k = 21399 \frac{V_{\text{coil}}}{\text{meter Hz}^{3/2}}. \quad (4.10.4)$$

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Comments: See comment for `calibrate()`.



#### 4.11 Example: power\_spectrumF program

This example uses the function `GRnormalize()` to produce a normalized, properly calibrated power spectrum of the interferometer noise, using the gravity-wave signal and the swept-sine calibration information from the frames.

The output of this program is a 2-column file; the first column is frequency and the second column is the noise in units of meters/ $\sqrt{\text{Hz}}$ . To run this program, and display a graph, type

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/18nov94.1frame
power_spectrumF > outputfile
xmgr -nxy outputfile
```

A couple of comments are in order here:

1. Even though we only need the modulus, for pedagogic reasons, we explicitly calculate both the real and imaginary parts of  $\widetilde{\Delta l}(f) = R(f)\widetilde{C}_{\text{IFO}}(f)$ .
2. The fast Fourier transform of  $\Delta l$ , which we denote  $\text{FFT}[\Delta l]$ , has the same units (meters!) as  $\Delta l$ . As can be immediately seen from *Numerical Recipes* equation (12.1.6) the Fourier transform  $\widetilde{\Delta l}$  has units of meters-sec and is given by  $\widetilde{\Delta l} = \Delta t \text{FFT}[\Delta l]$ , where  $\Delta t$  is the sample interval. The (one-sided) power spectrum of  $\Delta l$  in meters/ $\sqrt{\text{Hz}}$  is  $P = \sqrt{\frac{2}{T}}|\widetilde{\Delta l}|$  where  $T = N\Delta t$  is the total length of the observation interval, in seconds. Hence one has

$$P = \sqrt{\frac{2}{N\Delta t}} \Delta t |\text{FFT}[\Delta l]| = \sqrt{\frac{2\Delta t}{N}} |\text{FFT}[\Delta l]|. \quad (4.11.1)$$

This is the reason for the factor which appears in this example.

3. To get a spectrum with decent frequency resolution, the time-domain data must be windowed (see the example program `calibrate` and the function `avg_spec()` to see how this works).

A sample of the output from this program is shown in Figure 13.

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
#define NPOINT 65536

int main() {
    void realft(float*, unsigned long, int);
    float response[NPOINT+2], data[NPOINT], freq;
    float res_real, res_imag, dl_real, dl_imag, c0_real, c0_imag, spectrum, srate, factor;
    int i, npoint;
    short datas[NPOINT];
    struct fgetinput fgetinput;
    struct fgetoutput fgetoutput;

    /* We need only the IFO output */
    fgetinput.nchan=1;

    /* use utility function framefiles() to retrieve file names */
    fgetinput.files=framefiles;

    /* storage for channel names, data locations, points returned, ratios */
    fgetinput.chnames=(char **)malloc(fgetinput.nchan*sizeof(char *));
    fgetinput.locations=(short **)malloc(fgetinput.nchan*sizeof(short *));
```

```

fgetoutput.npoint=(int *)malloc(fgetinput.nchan*sizeof(int));
fgetoutput.ratios=(int *)malloc(fgetinput.nchan*sizeof(int));

/* set channel name */
fgetinput.chnames[0]="IFO_DMRO";

/* are we in the 40-meter lab? */
if (NULL!=getenv("GRASP_REALTIME")) {
    /* for Caltech 40-meter lab */
    fgetinput.inlock=0;
}
else {
    /* for Nov 1994 data set */
    fgetinput.inlock=1;
}
/* number of points to sample and fft (power of 2) */
fgetinput.npoint=npoint=NPOINT;
fgetinput.calibrate=1;

/* the array where we want the data to be put */
fgetinput.locations[0]=datas;

/* skip 200 seconds into locked region (just seek, no need for data) */
fgetinput.seek=1;
fgetoutput.tstart=fgetoutput.lastlock=0.0;
while (fgetoutput.tstart-fgetoutput.lastlock<200.0)
    fget_ch(&fgetoutput,&fgetinput);

/* and get next stretch of data (don't seek, we need data) */
fgetinput.seek=0;
fget_ch(&fgetoutput,&fgetinput);

/* the sample rate */
srate=fgetoutput.srate;

/* convert gw signal (ADC counts) from shorts to floats */
for (i=0;i<NPOINT;i++) data[i]=datas[i];

/* FFT the data */
realft(data-1,npoint,1);

/* get normalization R(f) using swept sine calibration information from frame */
GRnormalize(fgetoutput.fri,fgetoutput.frinum,npoint,srate,response);

/* one-sided power-spectrum normalization, to get meters/rHz */
factor=sqrt(2.0/(srate*npoint));
/* compute dl. Leave off DC (i=0) or Nyquist (i=npoint/2) freq */
for (i=1;i<npoint/2;i++) {
    /* frequency */
    freq=i*srate/npoint;
    /* real and imaginary parts of tilde c0 */
    c0_real=data[2*i];
    c0_imag=data[2*i+1];
    /* real and imaginary parts of R */
    res_real=response[2*i];
    res_imag=response[2*i+1];
    /* real and imaginary parts of tilde dl */
    dl_real=c0_real*res_real-c0_imag*res_imag;
}

```

```

dl_imag=c0_real*res_imag+c0_imag*res_real;
/* |tilde dl| */
spectrum=factor*sqrt(dl_real*dl_real+dl_imag*dl_imag);
/* output freq in Hz, noise power in meters/rHz */
printf("%e\t%e\n", freq, spectrum);
}
return 0;
}

```

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Comments: The IFO output typically consists of a number of strong line sources (harmonics of the 60 Hz line and the 180 Hz laser power supply, violin modes of the suspension, etc) superposed on a continuum background (electronics noise, laser shot noise, etc) In such situations, there are better ways of finding the noise power spectrum (for example, see the multi-taper methods of David J. Thomson [24], or the textbook by Percival and Walden [25]). Using methods such as the F-test to remove line features from the time-domain data stream might reduce the sidelobe contamination (bias) from nearby frequency bins, and thus permit an effective reduction of instrument noise near these spectral line features. Further details of these methods, and some routines that implemen them, may be found in Section 10.17.

# Displacement Spectrum

19 Nov 94 run 3

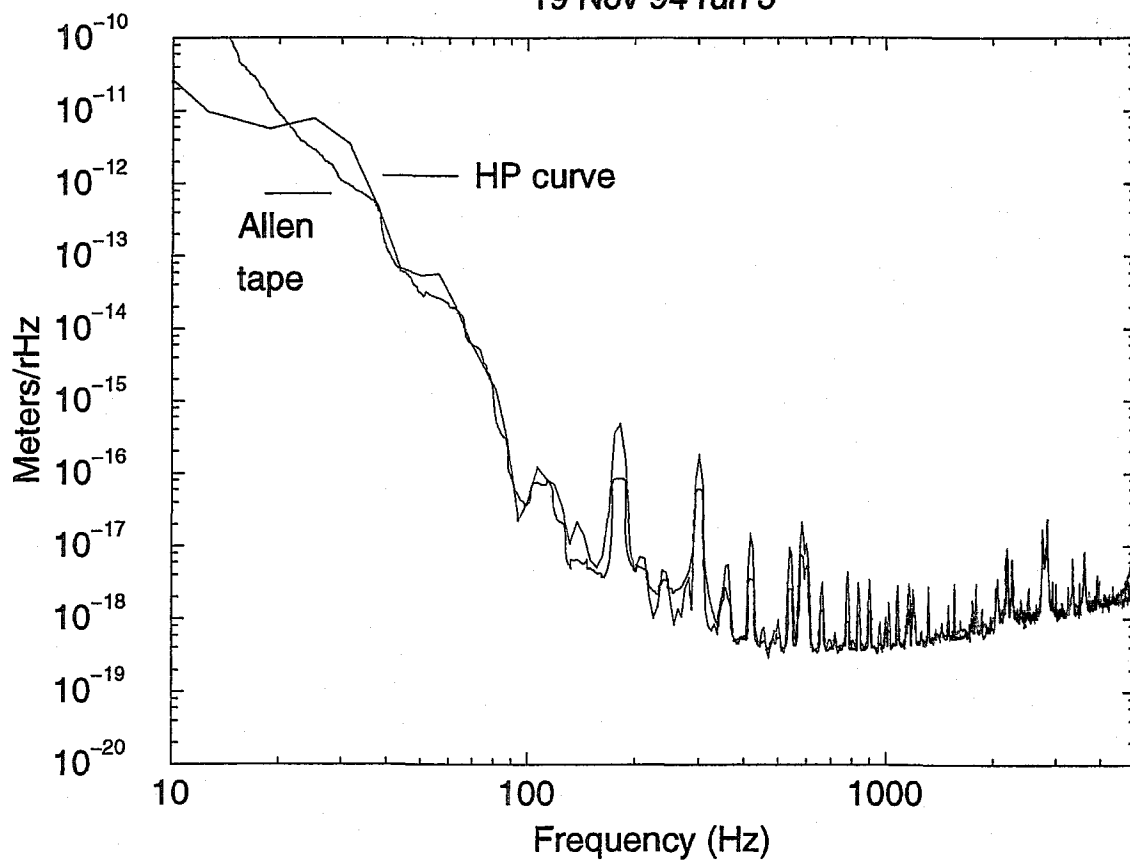


Figure 13: An example of a power spectrum curve produced with `power_spectrumF`. The spectrum produced off a data tape (with 100 point smoothing) is compared to that produced by the HP spectrum analyzer in the lab.

#### 4.12 Example: calibrateF program

This example uses the function `GRnormalize()` and `avg_spec()` to produce an animated display, showing the properly normalized power spectrum of the interferometer, with a 30-second characteristic time moving average. After compilation, to run the program type:

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/18nov94.1frame
calibrateF | xmgr -pipe &
```

to get an animated display showing the calibrated power spectrum changing. An example of the output from `calibrateF` is shown in Figure 14. Note that most of the execution time here is spent passing data down the pipe to `xmgr` and displaying it. The display can be speeded up by a factor of ten by binning the output values to reduce their number to a few hundred lines (the example program `calibrate_binnedF.c` implements this technique; it can be run by typing `calibrate_binnedF | xmgr -pipe`).

### Calibrated IFO Spectrum

80.521896 sec since last lock. t = 80.521896 sec.

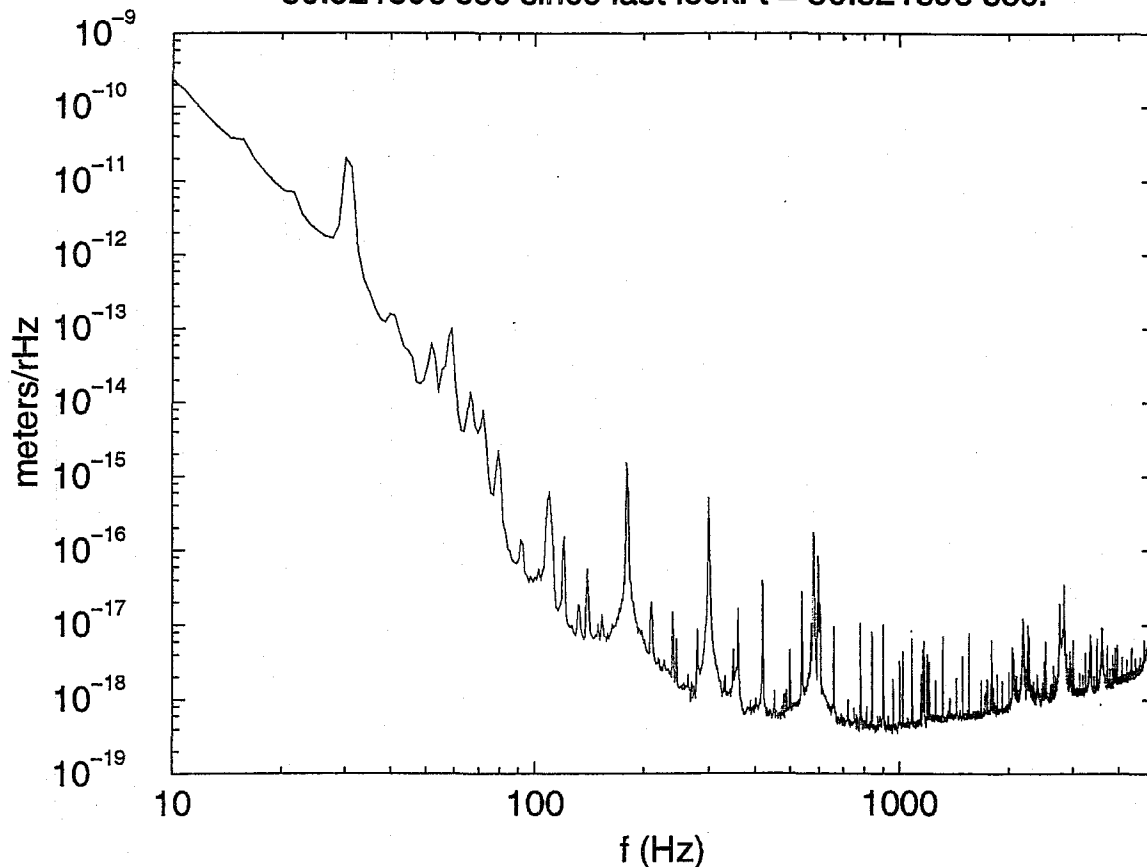


Figure 14: This shows a snapshot of the output from the program `calibrateF` which displays an animated average power spectrum (Welch windowed, 30-second decay time).

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
```

```

#define NPOINT 4096

int main() {
    void graphout(int, float, float);
    float data[NPOINT], average[NPOINT], response[2*NPOINT+4];
    float spec, decaytime;
    float srate, tstart=0, freq, tlock;
    int i, j, code, npoint, ir, ii, reset=0, pass=0;
    short datas[NPOINT];
    double mod;
    struct fgetinput fgetinput;
    struct fgetoutput fgetoutput;

    /* number of channels needed is one */
    fgetinput.nchan=1;

    /* use utility function framefiles() to retrieve file names */
    fgetinput.files=framefiles;

    /* storage for channel names, data locations, points returned, ratios */
    fgetinput.chnames=(char **)malloc(fgetinput.nchan*sizeof(char *));
    fgetinput.locations=(short **)malloc(fgetinput.nchan*sizeof(short *));
    fgetoutput.npoint=(int *)malloc(fgetinput.nchan*sizeof(int));
    fgetoutput.ratios=(int *)malloc(fgetinput.nchan*sizeof(int));

    /* set up channel name */
    fgetinput.chnames[0]="IFO_DMRO";

    /* set up channel names for different cases */
    if (NULL!=getenv("GRASP_REALTIME")) {
        /* for Caltech 40-meter lab */
        fgetinput.inlock=0;
    }
    else {
        /* for Nov 1994 data set */
        fgetinput.inlock=1;
    }

    /* number of points to sample and fft (power of 2) */
    fgetinput.npoint=npoint=NPOINT;

    /* we do need the data, so don't seek */
    fgetinput.seek=0;

    /* do need calibration information */
    fgetinput.calibrate=1;

    /* where to put the data points */
    fgetinput.locations[0]=datas;

    /* set the decay time (sec) */
    decaytime=30.0;

    /* get data */
    while (code=fget_ch(&fgetoutput, &fgetinput)) {
        tstart=fgetoutput.dt;
        srate=fgetoutput.srate;

        /* put data into floats */

```

```

for (i=0;i<npoint;i++) data[i]=datas[i];

/* use the swept-sine calibration (properly interpolated) to get R(f) */
if (!pass++) GRnormalize(fgetoutput.fri, fgetoutput.frinum, 2*npoint, srate, response);

/* Reset if just locked */
if (code==1) {
    reset=0;
    tlock=tstart;
    avg_spec(data, average, npoint, &reset, srate, decaytime, 2);
} else {

    /* track average power spectrum, with Welch windowing. */
    avg_spec(data, average, npoint, &reset, srate, decaytime, 2);

    /* loop over all frequencies except DC (j=0) & Nyquist (j=npoint/2) */
    for (j=1;j<npoint;j++) {
        /* subscripts of real, imaginary parts */
        ii=(ir=j+j)+1;
        /* frequency of the point */
        freq=0.5*srates*j/npoint;
        /* determine power spectrum in (meters/rHz) & print it */
        mod=response[ir]*response[ir]+response[ii]*response[ii];
        spec=sqrt(average[j]*mod);
        printf("%e\t%e\n", freq, spec);
    }
    /* print out useful things for xmgr program ... */
    graphout(0, tstart, tlock);
}
}
return 0;
}

void graphout(int last, float time, float tlock) {
    static int count=0;
    printf("&\n"); /* end of set marker */
    /* first time we draw the plot */
    if (count++==0) {
        printf("@doublebuffer true\n"); /* keeps display from flashing */
        printf("@focus off\n"); /* turn off the focus markers */
        printf("@s0 color 2\n"); /* FFT is red */
        printf("@g0 type logxy\n"); /* set graph type to log-log */
        printf("@autoscale \n"); /* autoscale FFT */
        printf("@world xmin %e\n", 10.0); /* set min x */
        printf("@world xmax %e\n", 5000.0); /* set max x */
        printf("@world ymin %e\n", 1.e-19); /* set min y */
        printf("@world ymax %e\n", 1.e-9); /* set max y */
        printf("@yaxis tick minor on\n"); /* turn on tick marks */
        printf("@yaxis tick major on\n"); /* turn on tick marks */
        printf("@yaxis tick minor 2\n"); /* turn on tick marks */
        printf("@yaxis tick major 1\n"); /* turn on tick marks */
        printf("@redraw \n"); /* redraw graph */
        printf("@xaxis label \"f (Hz)\"\n"); /* FFT horizontal axis label */
        printf("@yaxis label \"meters/rHz\"\n"); /* FFT vertical axis label */
        printf("@title \"Calibrated IFO Spectrum\"\n"); /* set title */
        /* set subtitle */
        printf("@subtitle \"%0.2f sec since last lock. t = %0.2f sec.\n", time-tlock, time);
        if (!last) printf("@kill s0\n"); /* kill graph; ready to read again */
    }
}

```

```

}
else {
    /* other times we redraw the plot */
    /* set subtitle */
    printf("@subtitle \".2f sec since last lock. t = %.2f sec.\\n\",time-tlock,time);
    printf("@s0 color 2\\n");          /* FFT is red */
    printf("@g0 type logxy\\n");      /* set graph type to log-log */
    printf("@world xmin %e\\n\",10.0); /* set min x */
    printf("@world xmax %e\\n\",5000.0); /* set max x */
    printf("@world ymin %e\\n\",1.e-19); /* set min y */
    printf("@world ymax %e\\n\",1.e-9); /* set max y */
    printf("@yaxis tick minor on\\n"); /* turn on tick marks */
    printf("@yaxis tick major on\\n"); /* turn on tick marks */
    printf("@yaxis tick minor 2\\n"); /* turn on tick marks */
    printf("@yaxis tick major 1\\n"); /* turn on tick marks */
    printf("@redraw\\n");             /* redraw the graph */
    if (!last) printf("@kill s0\\n"); /* kill graph, ready to read again */
}
return;
}

```

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Comments: See comments for power\_spectrumF example program.



### 4.13 Example: diagF program

This program is a frequency-domain “novelty detector” and provides a simple example of a time-frequency diagnostic method. The actual code is not printed here, but may be found in the GRASP directory `src/examples/exan` in the file `diagF.c`. To run the program type:

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/18nov94.1frame
diagF &
```

which will start the `diagF` program in the background.

The method used by `diagF` is as follows:

1. A buffer is loaded with a short stretch of data samples (2048 in this example, about 1/5 of a second).
2. A (Welch-windowed) power spectrum is calculated from the data in the buffer. In each frequency bin, this provides a value  $S(f)$ .
3. Using the same auto-regressive averaging technique described in `avg_spec()` the mean value of  $S(f)$  is maintained in a time-averaged spectrum  $\langle S(f) \rangle$ . The exponential-decay time constant for this average is `AVG_TIME` (10 seconds, in this example).
4. The absolute difference between the current spectrum and the average  $\Delta S(f) \equiv |S(f) - \langle S(f) \rangle|$  is determined. Note that the absolute value used here provides a more robust first-order statistic than would be provided by a standard variance  $(\Delta S(f))^2$ .
5. Using the same auto-regressive averaging technique described in `avg_spec()` the value of  $\Delta S(f)$  is maintained in a time-averaged absolute difference  $\langle \Delta S(f) \rangle$ . The exponential-decay time constant for this average is also set by `AVG_TIME`.
6. In each frequency bin,  $\Delta S(f)$  is compared to  $\langle \Delta S(f) \rangle$ . If  $\Delta S(f) > \text{THRESHOLD} \times \langle \Delta S(f) \rangle$  then a point is plotted for that frequency bin; otherwise no point is plotted for that frequency bin. In this example, `THRESHOLD` is set to 6.
7. In each frequency bin,  $\Delta S(f)$  is compared to  $\langle \Delta S(f) \rangle$ . If  $\Delta S(f) < \text{INCLUDE} \times \langle \Delta S(f) \rangle$  then the values of  $S(f)$  and  $\Delta S(f)$  are used to “refine” or “revise” the auto-regressive means described previously. In this example, `INCLUDE` is set to 10.
8. Another set of points (1024 in this example) is loaded into the end of the buffer, pushing out the oldest 1024 points from the start of the buffer, and the whole loop is restarted at step 2 above.

The `diagF` program can be used to analyze any of the different channels of fast-sampled data, by setting `CHANNEL` appropriately. It creates one output file for each locked segment of data. For example if `CHANNEL` is set to 0 (the IFO channel) and there are four locked sections of data, one obtains a set of files: `ch0diag.000`, `ch0diag.001`, `ch0diag.002`, and `ch0diag.003`.

In similar fashion, if `CHANNEL` is set to 1 (the magnetometer) one obtains files:

`ch1diag.000`, `ch1diag.001`, `ch1diag.002`, and `ch1diag.003`.

These files may be used as input to the `xmgr` graphing program, by typing:

```
xmgr ch0diag.000 ch1diag.000
```

(one may specify as many channels as desired on the input line). A typical pair of outputs is shown in Figures 15 and 16. By specifying several different channels on the command line for starting `xmgr`, you can overlay the different channels output with one another. This provides a visual tool for identifying correlations between the channels (the graphs shown below may be overlaid in different colors).

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19 November 1994 run 1

Time/Frequency statistics for channel 0

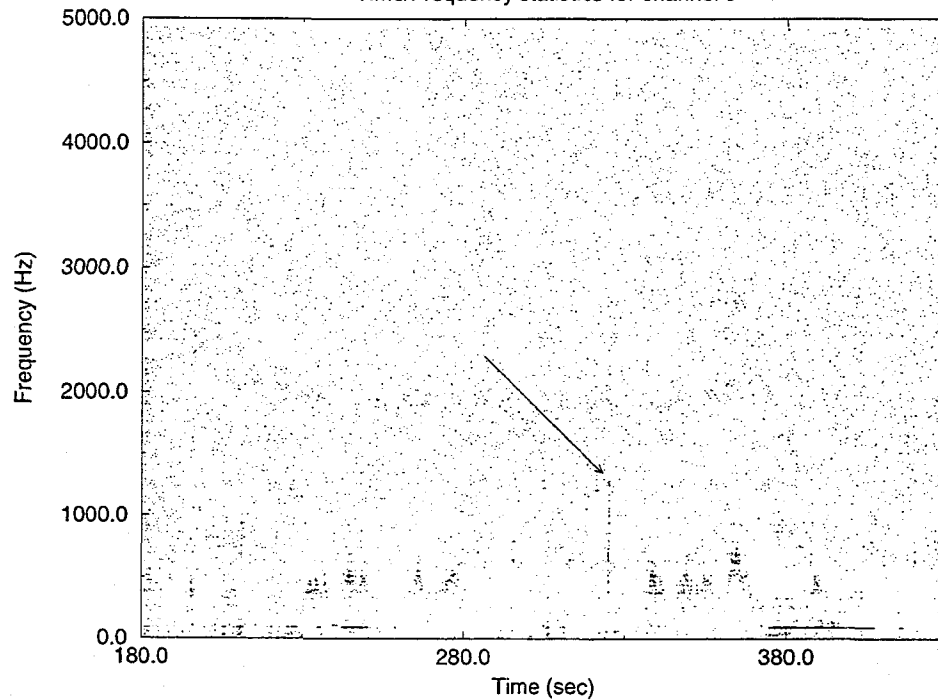


Figure 15: A time-frequency diagnostic graph produced by `diag`. The vertical line pointed to by the arrow is a non-stationary noise event in the IFO output, 325 seconds into the locked section. It sounds like a “drip” and might be due to off-axis modes in the interferometer optical cavities.

Comments: This type of time-frequency event detector appears quite useful as a diagnostic tool. It might be possible to improve its high-frequency time resolution by being clever about using intermediate information during the recursive calculation of the FFT. One should probably also experiment with using other statistical measures to assess the behavior of the different frequency bins. It would be nice to modify this program to also examine the slow sampled channels (see comment for `get_data()`).

19 November 1994 run 1

Time/Frequency statistics for channel 1

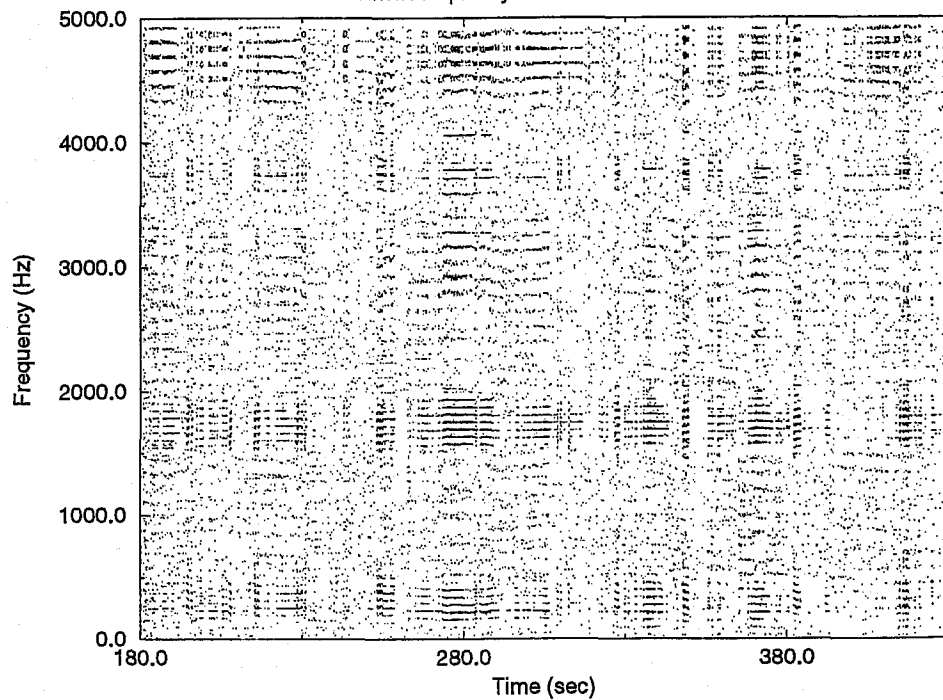


Figure 16: A time-frequency diagnostic graph produced by diag. This shows the identical period as the previous graph, but for the magnetometer output. Notice that the spurious event was not caused by magnetic field fluctuations.

## 5 GRASP Routines: Gravitational Radiation from Binary Inspiral

One of the principal sources of gravitational radiation which should be detectable with the first or second generation of interferometric detectors is *binary inspiral*. This radiation is produced by a pair of massive and compact orbiting objects, such as neutron stars or black holes.

The simplest case is when the two objects are describing a circular orbit about their common center-of-mass, and neither object is spinning about its own axis. With these assumptions the system is then described, at any time, by the masses  $m_1$  and  $m_2$  of the objects, and their orbital frequency  $\Omega$ . (It is also necessary to describe the orientation of the orbital plane and the positions of the masses at a given time; these are details we will sort out later).

For convenience in dealing with dimensional quantities, we introduce the *Solar Mass*  $M_\odot$  and the *Solar Time*  $T_\odot$  defined by

$$M_\odot = 1.989 \times 10^{33} \text{ grams} \quad (5.0.1)$$

$$T_\odot = \left(\frac{G}{c^3}\right) M_\odot = 4.925491 \times 10^{-6} \text{ sec.} \quad (5.0.2)$$

GRASP functions typically measure masses in units of  $M_\odot$  and times in units of seconds.

## 5.1 Chirp generation routines

The next several subsections document a number of routines for generating “chirps” from coalescing binaries. This package of routines is intended to be versatile, flexible and robust; and yet still fairly simple to use. The implementation we have included in this package is based on the second post-Newtonian treatment of binary inspiral presented in [6] and augmented by the spin-orbit and spin-spin corrections presented in [7]. The notation we use – even in the source code – closely reflects the notation used in those papers. In keeping with that notation, these routines calculate the **orbital phase** and **orbital frequency**. The gravitational-wave phase of the dominant quadrupolar radiation can be obtained by multiplying the orbital phase by two. The routines can be used to compute a few chirp waveforms (say to make transparencies for a seminar), or for wholesale computations of a bank of matched filters.

The routines are flexible in the sense that they have a number of *run-time* options available for choosing the post-Newtonian order of the phase calculations, or choosing whether or not to include spin effects. We have also isolated those parts of the code where the messy post-Newtonian coefficients appear; thus the routines may be easily modified to include yet higher-order post-Newtonian terms as they become available.

The post-Newtonian equations for the orbital phase evolution are notoriously ill-behaved [8, 9] as the binary system nears coalescence. In this regime the expansion parameters [namely the relative velocity  $v/c$  of the bodies and/or the field strength  $GM_{\text{tot}}/(c^2 r_{\text{orbit}})$ ] used in the derivation are comparable to unity. In post<sup>2</sup>-Newtonian calculations higher orders such as post<sup>3</sup>-Newtonian terms have been discarded. Because of this truncation, quantities that are positive definite in an exact calculation (say the energy-loss rate, or the time derivative of the orbital frequency) often become negative in their post-Newtonian expansion when the orbital separation becomes small. When this happens you are using a post-Newtonian expression in a regime where its validity is questionable. This is cause for concern, and it may be cause for terminating a chirp calculation; but, it need not crash your code. A full-scale gravitational-wave search will need to compute chirps over a broad range of parameters, virtually assuring that any post-Newtonian chirp generator will be pushed into a region of parameter space where it doesn't belong. These routines are designed to traverse these dangerous regions of parameter space as well as possible and gently warn the user of the dangers encountered. The calling routines may wish to act on the warnings coming from the chirp generator. For example a severe warning may prompt the calling routine to discard a given filter from a data search, because the second post-Newtonian calculation of the chirp is so dubious that it can't give meaningful results.

In the next several sections we detail the use of three routines used to compute the “chirp” of a coalescing binary system. The first routine we describe is `phase_frequency()`. This is the underlying routine for the other chirp routines. Given a set of parameters (*e.g.* the two masses, and the upper and lower cut-off frequency for the chirp) it returns the orbital phase and orbital frequency evolution as a function of time. Next we describe `chirp_filter()` which returns two (unnormalized) chirp signals. This routine can be used for wholesale production of a bank of templates for a coalescing binary search. The routine `strain()` returns the full second post-Newtonian gravitational wave strain. This can be used for plotting and examining the expected waveform of a given coalescing binary, or to add a “realistic” signal into detector noise. The strain output contains all the (sub)harmonic structure and its amplitude reflects the true astrophysical distance to the source.

## 5.2 Function: phase\_frequency()

```
int phase_frequency(float m1, float m2, float spin1, float spin2, int n_phaseterms,
float *phaseterms, float InitialFreq, float MaxFreqRqst, float *MaxFreqActual,
float SampleTime, float **phase, float **frequency, int *steps_alloc, int
*steps_filld, int err_cd_sprs)
```

This function computes the **orbital phase** and **orbital frequency** evolution of an inspiralling binary. It returns an integer termination code indicating how and why the chirp calculation terminated. This routine is the engine that powers the other chirp generation routines. The arguments are:

`m1`: Input. The mass of body-1 in solar masses.

`m2`: Input. The mass of body-2 in solar masses.

`spin1`: Input. The dimensionless spin parameter of body-1. See section on spin effects.

`spin2`: Input. The dimensionless spin parameter of body-2. See section on spin effects.

`n_phaseterms`: Input. Integer describing the number of post-Newtonian (pN) approximation terms implemented in the phase and frequency calculations. In the present implementation this should be set to 5.

`phaseterms`: Input. The array `phase_terms[0..n_phaseterms-1]` specifies which pN approximation terms will be included in the phase frequency calculations. Setting `phase_terms[i]=0.0` nullifies the term. Setting `phase_terms[i]=1.0` includes the term. This allows for easy run-time nullification of any term in the phase and frequency evolution, *e.g.* setting `phase_terms[4]=0.0` eliminates the *second* post-Newtonian terms from the calculation.

`Initial_Freq`: Input. The starting orbital frequency of the chirp in Hz.

`Max_Freq_Rqst`: Input. The requested orbital frequency where the chirp will stop. However, the actual calculation may not proceed all the way to this orbital frequency. This is discussed at length below.

`Max_Freq_Actual`: Output. The floating number `*Max_Freq_Actual` is the orbital frequency in Hz where the chirp actually terminated.

`Sample_Time`: Input. The time interval between successive samples, in seconds.

`phase`: Input/Output. The phase ephemeris  $\Omega$  in radians is stored in the array `*phase[0..steps_filld-1]`. Input in the sense that much of the internal logic of `phase_frequency()` depends on how the pointers `*phase` (and `*frequency` below) are set. If either is set to NULL memory allocation will be performed inside `phase_frequency()`. If both are not NULL then it is assumed the calling routine has allocated the memory before calling `phase_frequency()`.

`frequency`: Input/Output. Similar to phase above. The frequency ephemeris  $f = d\Omega/dt$  is stored in the array `*frequency[0..steps_filld-1]`.

`steps_alloc`: Input/Output. The integer `*steps_alloc` is the number of floating point entries allocated for storing the phase and frequency evolution, *i.e.* the length of `**phase` and `**frequency`. This integer should be set in the calling routine if memory is allocated there, or it will be set inside `phase_frequency()` if memory is to be allocated there. If both of the pointers `*phase` and `*frequency` are not NULL then `phase_frequency()` understands that the calling routine is taking responsibility for allocating the memory for the chirp, and the calling routine must set

`*steps_alloc` accordingly. In this case `phase_frequency()` will fill up the arrays `**phase` and `**frequency` until the memory is full (*i.e.* fill them with `*steps_alloc` of floats) or until the chirp terminates, whichever is less.

`steps_filld`: Output. The integer `*steps_filld` is the integer number of time steps actually computed for this evolution. It is less than or equal to `*steps_alloc`.

`clscnc_time`: Output. The float `*clscnc_time` is the time to coalescence in seconds, measured from the instant when the orbital frequency is `Initial_Freq` given by  $t_c$  in Eqs.(5.4.1) and (5.4.2).

`err_cd_sprs`: Input. Error code suppression. This integer determines at what level of disaster encountered in the computation of the chirp the user will be explicitly warned about with a printed message. Set to 0: prints all the termination messages. Set to 4000: suppresses all but a few messages which are harbingers of complete disaster. The termination messages are numbered from 0 to 3999 loosely in accordance with their severity (the larger numbers corresponding to more severe warnings). Any message with a number less than `err_cd_sprs` will not be printed. A termination code of 0 means the chirp calculation was executed as requested. A termination code in the 1000's means the chirp was terminated early because the post-Newtonian approximation was deemed no longer valid. A termination code in the 2000's generally indicates some problem with memory allocation. A termination code in the 3000's generally indicates a serious logic fault. Many of these "3000" errors result in the termination of the routine. If you get an error message number it is easy to find the portion of source code where the fault occurred; just do a character string search on the four digit number.

This phase and frequency generator has a number of very specialized features which will be discussed later. However, before we proceed further, we show a simple example of how `phase_frequency()` can be used.

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Comments: This function will need to be extended when results of order 2.5 and 3 post-Newtonian calculations have been reported and published.

### 5.3 Example: phase\_evoltn program

This example uses `phase_frequency()` to compute the phase and frequency evolution for an inspiraling binary and prints the results on the screen (`stdout`). The other output messages go to `stderr`.

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
int main() {
    float m1,m2,spin1,spin2,phaseterms[5],clscnc_time,*ptrphase,*ptrfrequency;
    float time,Initial_Freq,Max_Freq_Rqst,Max_Freq_Actual,Sample_Time,time_in_band;
    int steps_alloc,steps_filld,i,n_phaseterms,err_cd_sprs,chirp_ok;

    /* Set masses and spins of the orbital system: */
    m1=m2=1.4;
    spin1=spin2=0.;

    /* Set ORBITAL frequency range of the chirp and sample time: */
    Initial_Freq=60.; /* in cycles/second */
    Max_Freq_Rqst=2000.; /* in cycles/second */
    Sample_Time=1./9868.4208984375; /* in seconds */

    /* Use this block to compare with Will & Wiseman, PRD 54, 4813 (1996) Figure 10, page 4846.
    spin1=0.1; spin2=0.5;
    m1=1.4; m2=12.0;
    Initial_Freq=75.0; Max_Freq_Rqst=180.0; */

    /* post-Newtonian [O(1/c^n)] terms you wish to include (or supress)
    in the phase and frequency evolution: */
    n_phaseterms=5; /* the number of entries in phaseterms */
    phaseterms[0] =1.; /* The Newtonian piece */
    phaseterms[1] =0.; /* There is no O(1/c) correction */
    phaseterms[2] =1.; /* The post-Newtonian correction */
    phaseterms[3] =1.; /* The 3/2 PN correction */
    phaseterms[4] =1.; /* The 2PN correction */

    /* Set memory-allocation and error-code supression logic: */
    ptrphase=ptrfrequency=NULL;
    err_cd_sprs=0;

    /* Use phase_frequency() to compute phase and frequency evolution: */
    chirp_ok=phase_frequency(m1,m2,spin1,spin2,n_phaseterms,phaseterms,
        Initial_Freq,Max_Freq_Rqst,&Max_Freq_Actual,Sample_Time,&ptrphase,
        &ptrfrequency,&steps_alloc,&steps_filld,&clscnc_time,err_cd_sprs);

    /* ... and print out the results: */
    time_in_band=(float)(steps_filld-1)*Sample_Time;
    fprintf(stderr,"\nm1=%f m2=%f Initial_Freq=%f\n",m1,m2,Initial_Freq);
    fprintf(stderr,"steps_filld=%i steps_alloc=%i Max_Freq_Actual=%f\n",
        steps_filld,steps_alloc,Max_Freq_Actual);
    fprintf(stderr,"time_in_band=%f clscnc_time=%f\n",time_in_band,clscnc_time);
    fprintf(stderr,"Termination code: %i\n\n",chirp_ok);

    for (i=0;i<steps_filld;i++){
        time=i*Sample_Time;
        printf("%i\t%f\t%f\t%f\n",i,time,ptrphase[i],ptrfrequency[i]);
    }
    return 0;
}
```



Here is the output from the phase\_evoltn example:

```
GRASP: Message from function phase_frequency() at line number 439 of file "pN_chi
Frequency evolution no longer monotonic.
Phase evolution terminated at frequency and step: 911.681702      13357
Terminating chirp. Termination code set to:      1201
Returning to calling routine.
$Id: man_inspirial.tex,v 1.17 1997/08/07 22:31:57 ballen Exp $
$Name: RELEASE_1_5_2 $
```

```
m1=1.400000 m2=1.400000 Initial_Freq=60.000000
steps_filld=13357 steps_alloc=16384 Max_Freq_Actual=911.681702
time_in_band=1.353408 clscnc_time=1.353573
Termination code: 1201
```

0	0.000000	0.000000	60.000000
1	0.000101	0.038204	60.001675
2	0.000203	0.076369	60.003353
3	0.000304	0.114627	60.005020
4	0.000405	0.152820	60.006695
5	0.000507	0.191071	60.008366
6	0.000608	0.229173	60.010052
...	...	...	...
13349	1.352699	797.669800	720.294189
13350	1.352800	798.134949	741.157715
13351	1.352901	798.614136	764.565796
13352	1.353003	799.109192	791.015686
13353	1.353104	799.622192	821.015320
13354	1.353205	800.155457	854.720337
13355	1.353307	800.710999	890.133667
13356	1.353408	801.286499	911.681702

The first seven lines of output come directly from `phase_frequency()`, and are printed to `stderr`. These give a warning message telling why the chirp calculation was terminated; it no longer had monotonically increasing frequency. It also tells where the chirp was terminated; after computing 13357 points it has reached a frequency of 907Hz. The termination code (1201) is also printed. Knowing the termination code makes it easy to find the segment of source code that produced the termination; just do a search for the character string "1201" and you will find the line of code where the termination code was set. Setting `err_cd_sprgs` greater than 1201 would suppress the printing of this warning message and all messages with a termination code less than 1201. However, even without the printed message the calling routine can determine the value of the termination code; it is returned by `phase_frequency()`.

The rest of the output comes from the `phase_evoltn` program. The quantity `time_in_band=(steps_filld-1)*Sample.Time` is the length (in seconds) of the computed chirp. The quantity `clscnc_time` is the value of  $t_c$  that enters Eqs.(5.4.1) below. The four column output from left to right is the integer index of the data points, time stamp of each point in seconds (starting arbitrarily from zero), the

orbital phase in radians (starting arbitrarily from zero), and the orbital frequency (starting from the initial frequency of 60Hz).

To summarize: It takes about 1.35 seconds for two  $1.4M_{\odot}$  objects to spiral in from an orbital frequency of 60Hz to an orbital frequency of 911Hz. The chirp calculation was terminated at 911Hz – instead of the requested 2000Hz – because the post-Newtonian expression used to compute the chirp is clearly out of its region of validity: the frequency is no longer increasing. Examining the last few data points shows that the frequency was rising quickly – as expected – until the last two data points. During this inspiral the orbital system went through  $811.09/(2\pi) \approx 127.53$  revolutions. The two integer numbers `steps_filld` and `steps_alloc` are the number of actual data points computed and the number of floating point memory slots allocated, respectively. (Memory is allocated in blocks of 4096 floats at a time. Thus `steps_alloc` will generally exceed `steps_filld`.) The values of the phase and frequency at every  $1/\text{Sample\_Time} = 1.10333 \times 10^{-4}$  seconds starting from when the binary had an orbital frequency of 60Hz until it neared “coalescence” at 911Hz have been calculated.

#### 5.4 Detailed explanation of phase\_frequency() routine

The phase\_frequency() routine starts with inputs describing the physical properties of the system (the masses) and an initial frequency from which to start the evolution. We then compute the orbital frequency evolution [in cycles/second] directly from the formula given in [6]

$$f(t) = \frac{M_{\odot}}{16\pi T_{\odot} m_{\text{tot}}} \left\{ \Theta^{-3/8} + \left( \frac{743}{2688} + \frac{11}{32}\eta \right) \Theta^{-5/8} - \frac{3\pi}{10} \Theta^{-3/4} + \left( \frac{1855099}{14450688} + \frac{56975}{258048}\eta + \frac{371}{2048}\eta^2 \right) \Theta^{-7/8} \right\}, \quad (5.4.1)$$

where  $m_{\text{tot}}$  is the total mass of the binary. The time integral of this equation gives the orbital evolution in cycles. Multiplying by  $2\pi$  yields the orbital phase in radians

$$\phi(t) = \phi_c - \frac{1}{\eta} \left\{ \Theta^{5/8} + \left( \frac{3715}{8064} + \frac{55}{96}\eta \right) \Theta^{3/8} - \frac{3\pi}{4} \Theta^{1/4} + \left( \frac{9275495}{14450688} + \frac{284875}{258048}\eta + \frac{1855}{2048}\eta^2 \right) \Theta^{1/8} \right\}. \quad (5.4.2)$$

Here  $\Theta$  is a dimensionless time variable

$$\Theta = \frac{\eta M_{\odot}}{5T_{\odot} m_{\text{tot}}} (t_c - t), \quad (5.4.3)$$

$\eta = \mu/m_{\text{tot}}$ , and  $t_c$  is the time of coalescence of the two point masses. Similarly the constant  $\phi_c$  is the phase at coalescence, which is arbitrarily set in phase\_frequency() so that  $\phi = 0$  at the initial time. [See the detailed discussion of the phase conventions below.] Also notice that the mass quantities only appear as ratios with the solar Mass  $M_{\odot}$ , and the time only appears as a ratio with the quantity  $T_{\odot} = 4.925491 \times 10^{-6}$  sec in Eq.(5.0.2).

These formulations of the post-Newtonian equations for the phase and frequency are simple to implement: each pass through the loop increments the time by the sample time (Sample\_Time in the example) and computes the phase and frequency using Eqs. (5.4.1) and (5.4.2). However, there is an alternative formulation. In deriving these equations the ‘‘natural’’ equation that arises is of the form  $\dot{f} = F(f)$ . [See e.g. [10] Eq.(3).] This in turn can be integrated to give an equation of the form  $t_c - t = T(f)$ . In our formulation this equation has been inverted – throwing away higher-order post-Newtonian terms as you go – to give Eq.(5.4.1). However the equation in the form  $t_c - t = T(f)$  can also be implemented directly. In this type of formulation one would again increment the time, but then use a root-finding routine to find the frequency at each time step. Our chosen method has the advantage of avoiding a time-consuming root-finder at each time step; however the alternative formulation has undergone fewer damaging post-Newtonian transformations, and may therefore be more accurate.

In our formulation we only need to call a root-finding routine at the start of the chirp to find the value of  $t_c - t$  when the system is at the initial frequency. In order to insure that we find the correct root for the starting time we begin a search at a time when the leading order prediction of the frequency is well below the desired starting frequency. We step forward in time until we bracket the root; we then call the *Numerical Recipes* root-finder `rtbis()` to compute the root precisely. This is depicted in the lower right corner of figure 17 where we show the value of the ‘‘time’’ coordinate  $X$  that corresponds to an initial frequency of 60Hz. This method is virtually assured of finding the *correct* root in that it will find the first solution as we proceed from right to left in figure 17. The primary problem in finding this root is that there may actually be no meaningful start-time for the specified chirp. For example, if you were to specify a chirp with two  $1.4M_{\odot}$  objects with an initial frequency of 1000Hz, you can see from the figure that there is no value of  $X$  (i.e.  $t_c - t$ ) that corresponds to this frequency. In this case phase\_frequency() will search from right

to left for the start time. It will notice that it is passing over the peak in the graph and out of the regime of post-Newtonian viability. It will then terminate the search and notify the caller that there is no solution for the requested chirp.

The behavior of the frequency equation is shown in figure 17. As time increases the frequency rises to a maximum and then begins to decrease dramatically. Notice that the maximum occurs when the dimensionless time parameter  $\Theta = \frac{\eta(t_c - t)}{5T_\odot m_{tot}} = X^8$  is approximately unity; this feature is only weakly dependent on the mass ratio. The fact that  $\Theta \approx 1$  means the post-Newtonian corrections in Eq.(5.4.1) are comparable to the leading order term. Therefore, this peak is a natural place to terminate the post-Newtonian chirp approximation. In the example the code terminated the chirp for precisely this reason. [See the warning message.]

Although it is not shown in the figure the behavior of  $f$  as  $X$  nears zero is very abrupt; the function goes sharply negative and then turns around and diverges to  $+\infty$  as  $X \rightarrow 0$  (i.e.  $t \rightarrow t_c$ ). This abrupt behavior will happen on a time scale of order  $T_\odot$  (a few microseconds). Typical sample times are likely to be on the order of a tenth of a millisecond, and therefore the iterative loop may step right over this maximum-minimum-divergence behavior of the frequency function altogether. Don't worry. The routine `phase_frequency()` handles this case gracefully. The routine will stop the chirp calculation and warn the caller if the time stepper goes beyond the coalescence time. It will also stop the chirp calculation if it senses that the time has stepped over the dip in frequency and is on the strongly divergent part of the frequency curve near the  $X = 0$  axis.

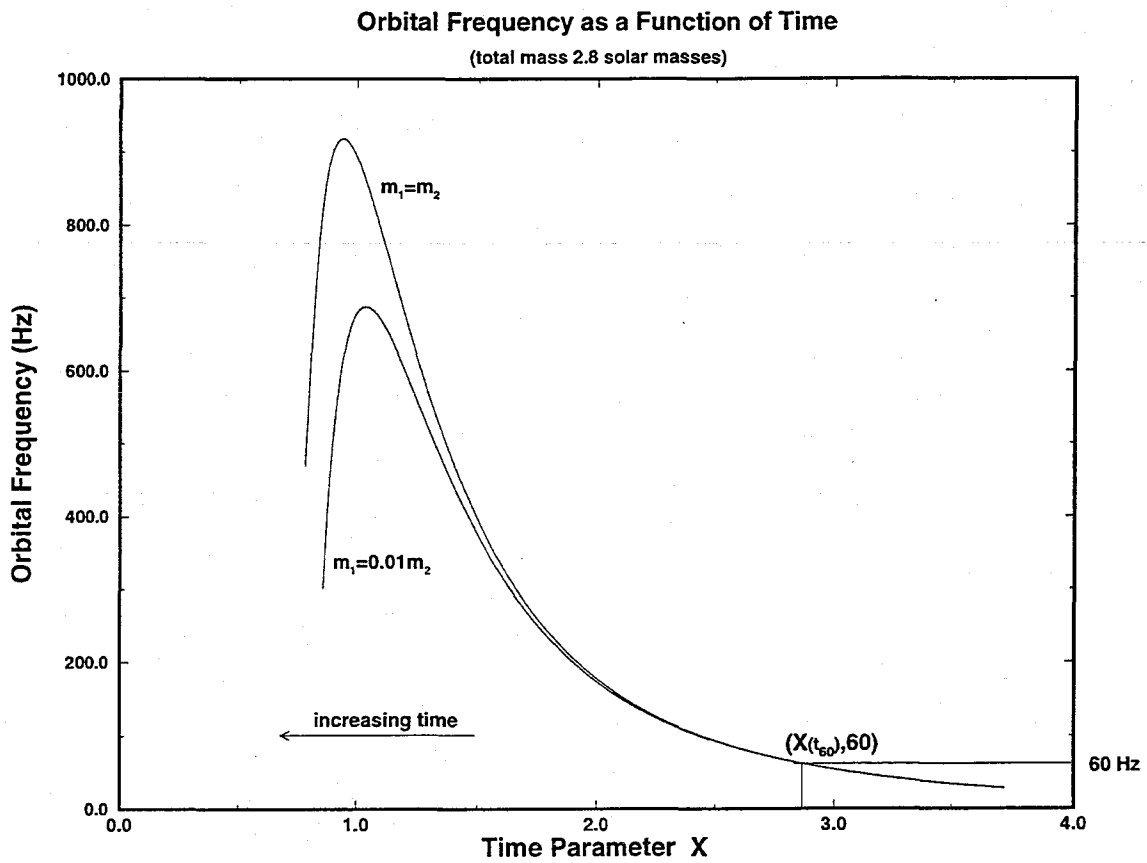


Figure 17: Orbital frequency as a function of the "time" coordinate  $X = \left( \frac{\eta(t_c - t)M_\odot}{5T_\odot m_{\text{tot}}} \right)^{1/8}$ .

## 5.5 Function: `chirp_filters()`

```
int chirp_filters(float m1, float m2, float spin1, float spin2, int n_phaseterms,
float *phaseterms, float Initial_Freq, float Max_Freq_Rqst, float *Max_Freq_Actual,
float Sample_Time, float **ptrptrCos, float **ptrptrSin, int *steps_alloc,
int *steps_filld, int err_cd_sprs)
```

This function is a basic stripped-down chirp generator. It computes two – nearly orthogonal – chirp waveforms for an inspiralling binary. The two chirps differ in phase by  $\pi/2$  radians. The chirp values are given by Eqs.(5.6.1) and (5.6.2). Just as the phase and frequency calculator `phase_frequency()` returns an integer number which describes how the chirp calculation was terminated, this routine does also.

The arguments are:

`m1`: Input. The mass of body-1 in solar masses.

`m2`: Input. The mass of body-2 in solar masses.

`spin1`: Input. The dimensionless spin parameter of body-1. See section on spin effects.

`spin2`: Input. The dimensionless spin parameter of body-2. See section on spin effects.

`n_phaseterms`: Input. Integer describing the number of terms implemented in the phase and frequency calculations. In the present implementation this should be set to 5.

`phaseterms`: Input. The array `phase_terms[0..n_phaseterms-1]` describes which terms will be included in the phase frequency calculations. Setting `phase_terms[i]=0` nullifys the term. Setting `phase_terms[i]=1` includes the term. This allows for easy run-time nullification of any term in the phase and frequency evolution, e.g. setting `phase_terms[4]=0` eliminates the second post-Newtonian terms from the calculation.

`Initial_Freq`: Input. The starting orbital frequency of the chirp in Hz.

`Max_Freq_Rqst`: Input. The requested orbital frequency where the chirp will stop. However, the actual calculation may not proceed all the way to this orbital frequency.

`Max_Freq_Actual`: Output. The floating number `*Max_Freq_Actual` is the orbital frequency in Hz where the chirp actually terminated.

`Sample_Time`: Input. The time interval between points in seconds.

`ptrptrCos`: Input/Output. The chirp corresponding to Eq.(5.6.1) is stored in `*ptrptrCos[0..steps_filld-1]`. Input in the sense that much of the internal logic of `chirp_filters()` depends on how the pointers `*ptrptrCos` (and `*ptrptrSin` below) are set. If either is set to NULL memory allocation will be performed inside `chirp_filters()`. If both are not NULL then it is assumed the calling routine has allocated the memory before calling `chirp_filters()`.

`ptrptrSin`: Input/Output. Similar to `ptrptrCos` above. The chirp corresponding to Eq.(5.6.2) is stored in `*ptrptrSin[0..steps_filld-1]`.

`steps_alloc`: Input/Output. The integer `*steps_alloc` is the number of floating point entries allocated for storing the two chirps, i.e. the number of valid subscripts in the arrays `**ptrptrCos` and `**ptrptrSin`. This integer should be set in the calling routine if memory is allocated there, or it will be set inside `chirp_filters()` if memory is to be allocated there. If both of the pointers `*ptrptrCos` and `*ptrptrSin` are not NULL then `chirp_filters()` understands that the

calling routine is taking responsibility for allocating the memory for the chirp, and the calling routine must set `*steps_alloc` accordingly. In this case `chirp_filters()` will fill up the arrays `**ptrptrCos` and `**ptrptrSin` until the memory is full (*i.e* fill them with `*steps_alloc` of floats) or until the chirp terminates, whichever is less.

`steps_filld`: Output. The integer `*steps_filld` is the number of time steps (sample values) actually computed for this evolution. It is less than or equal to `*steps_alloc`.

`clscnc_time`: Output. The float `*clscnc_time` is the time to coalescence in seconds, measured from the instant when the orbital frequency is `Initial_Freq` given by  $t_c$  in Eqs.(5.4.1) and (5.4.2).

`err_cd_sprs`: Input. Error code suppression. This integer specifies the level of disaster encountered in the computation of the chirp for which the user will be explicitly warned with a printed message. Set to 0: prints all the termination messages. Set to 4000: suppresses all but a few messages which are harbingers of true disaster. The termination messages are numbered from 0 to 3999 loosely in accordance with their severity (the larger numbers corresponding to more severe warnings). Any message with a number less than `err_cd_sprs` will not be printed. A termination code of 0 means the chirp calculation was executed as requested. A termination code in the 1000's means the chirp was terminated early because the post-Newtonian approximation was deemed no longer valid. A termination code in the 2000's generally indicates some problem with memory allocation. A termination code in the 3000's generally indicates a serious logic fault. Many of these "3000" errors result in the termination of the program. If you get an error message number it is easy to find the portion of source code where the fault occurred; just do a character string search on the four digit number.

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Comments: None.

## 5.6 Detailed explanation of `chirp_filters()` routine

The routine `chirp_filters()` calls `phase_frequency()` to find out how the orbital phase and frequency evolve in accordance with the input parameters. It then makes a single pass through that phase and frequency ephemeris, computing the chirps as it goes, and storing the information in the space already allocated for the phase and frequency. Most of the fault checking and computations are done in the `phase_frequency()` routine, and all the error messages and warnings come from there.

The routine `chirp_filters()` computes

$$h_c(t) = 2 \left( \frac{\mu}{M_\odot} \right) \left[ \frac{2\pi T_\odot m_{\text{tot}} f(t)}{M_\odot} \right]^{2/3} \cos 2\phi(t) \quad (5.6.1)$$

and the other orbital-phase chirp which is  $\pi/2$  out of phase with  $h_c(t)$

$$h_s(t) = 2 \left( \frac{\mu}{M_\odot} \right) \left[ \frac{2\pi T_\odot m_{\text{tot}} f(t)}{M_\odot} \right]^{2/3} \sin 2\phi(t), \quad (5.6.2)$$

with all the leading numerical factors we display.

If the so called “restricted” post<sup>2</sup>-Newtonian polarizations [leading order in the amplitude, but post<sup>2</sup>-Newtonian phase corrections] are desired, they can be easily assembled from  $h_c$  and  $h_s$ . The “+” (plus) polarization is given by

$$h_+(t) = -\frac{T_\odot c}{D} (1 + \cos^2 i) h_c(t), \quad (5.6.3)$$

and the “×” (cross) polarization is given by

$$h_\times(t) = -2 \frac{T_\odot c}{D} (\cos i) h_s(t). \quad (5.6.4)$$

Here  $D$  is the (luminosity) distance to the source in centimeters,  $c$  is the speed of light in centimeters/second, and  $i$  is the inclination angle (radians) of the angular momentum axis of the source relative to the line-of-sight. See Will and Wiseman [7] figure 7 for the precise definition of the inclination angle.

The restricted post<sup>2</sup>-Newtonian strain amplitude impinging on the detector can also be calculated from the output of `chirp_filters()` by

$$h(t) = F_+ h_+(t) + F_\times h_\times(t), \quad (5.6.5)$$

where  $F_+$  and  $F_\times$  are the detector beam-pattern functions.

In the remainder of this section we will clarify some technical issues involving the orbital phase. First, in computing  $\phi(t)$  in `phase_frequency()` we have arbitrarily set the constant  $\phi_c$  in Eq.(5.4.2) such that  $\phi = 0$  at the beginning of the chirp. The astrophysical convention for defining the orbital phase angle  $\phi$  given in [7] measures  $\phi$  in the plane of the orbit from the ascending node. [The ascending node of the orbit is where body-1 passes through the plane of the sky going away from the observer.] Choosing  $\phi_c$  in this way we have assumed that body-1 is passing through the ascending node of the orbit at the instant we start our chirp. Detailed information about the overall phase is not needed for many purposes (*i.e.* matched filters), therefore our choice is of little consequence. If this information needs to be included for some application, `chirp_filters()` can be modified to do so; thus one can leave the computational engine `phase_frequency()` untouched.

The second issue involving the phase is a bit more delicate. We have used the true orbital phase  $\phi(t)$  to compute oscillatory part of the chirp in Eqs.(5.6.1) and (5.6.2). But should we use the logarithmically modulated phase variable

$$\psi(t) = \phi - \frac{4Gm_{\text{tot}}\pi f(t)}{c^3} \ln[f(t)/f_0] \quad (5.6.6)$$



in our computation of the chirp? After all, the true phase of the gravitational-wave signal impinging on the detector is  $2\psi$ . Let us examine the effect on our signal replacing  $\sin 2\phi$  in Eq.(5.6.2) with the logarithmically corrected  $\sin 2\psi$

$$\begin{aligned}\sin 2\psi &= \sin\left(2\phi - \frac{8\pi m_{\text{tot}} f G}{c^3} \ln(f(t)/f_o)\right) \\ &= \sin 2\phi \cos\left(\frac{8\pi m_{\text{tot}} f G}{c^3} \ln(f(t)/f_o)\right) - \cos 2\phi \sin\left(\frac{8\pi m_{\text{tot}} f G}{c^3} \ln(f(t)/f_o)\right) \\ &\approx \left(1 + O(1/c^6)\right) \sin 2\phi - \left(\frac{8\pi m_{\text{tot}} f G}{c^3} \ln(f(t)/f_o)\right) \cos 2\phi.\end{aligned}\quad (5.6.7)$$

The  $O[1/c^6]$  is a post<sup>3</sup>-Newtonian term and can be neglected in the present post<sup>2</sup>-Newtonian analysis. However the coefficient of the  $\cos 2\phi$  is a post<sup>3/2</sup>-Newtonian order correction to the waveform, and must be included in any full post<sup>2</sup>-Newtonian analysis. This logarithmic term is included in the waveform calculation in the `strain()` routine. However, the last line of Eq.(5.6.7) also shows that the logarithmic phase correction can be considered a post<sup>3/2</sup>-Newtonian correction to the amplitude. In our present restricted post-Newtonian chirp calculation we neglect these higher order amplitude corrections, so we are justified in neglecting the logarithmic correction to the phase.

The advantage of neglecting the logarithm is that it speeds up the calculation of the chirps: we don't have to compute a logarithm at each time step. However, this may be at expense of accurately tracking the signal phase of a strongly relativistic source. After all much research has gone into computing the gravitational wave phase from these sources and we shouldn't willy-nilly discard these phase corrections. Is it difficult to modify our code to include this term? Not at all. In fact, the inclusion of the logarithmic correction to the gravitational wave phase would not affect `phase_frequency()`, at all. The fact that this logarithmic propagation effect only enters the `chirp_filters()` routine and not the `phase_frequency()` routine may seem like a computational quirk, but this actually has a physical origin: The routine `phase_frequency()` computes the local orbital phase of the binary; whereas, the physical origin of the logarithmic term is a *propagation* effect and has nothing to do with the orbital phase,

This is not say that no log terms will ever be needed in `phase_frequency()`. Note that at post<sup>4</sup>-Newtonian order there are log terms which do affect the local instantaneous orbital motion of the binary, so if `phase_frequency()` is ever modified to incorporate that order, then log terms will appear there also.

Another issue involving the log term in the phase is the presence of the "arbitrary" scale factor  $f_o$  entering the definition of  $\psi(t)$  in Eq.(5.6.6). The net effect of adjusting this constant is to change the value of another arbitrary constant in our phase and frequency equations; it shifts the value of  $t_c$  in Eq.(5.4.3). In order to to facilitate swift computation, we choose  $f_o$  to be the minimum frequency of the requested chirp. This insures that the ratio in the logarithm is of order unity during the chirp computation.

## 5.7 Example: filters program

This example uses `chirp_filters()` to generate two chirps  $\pi/2$  out of phase with each other. It also demonstrates a different memory allocation option than the `phase_evoln` example program.

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
int main() {
    float m1,m2,spin1,spin2,phaseterms[5],clscnc_time,*ptrCos,*ptrSin;
    float time,Initial_Freq,Max_Freq_Rqst,Max_Freq_Actual,Sample_Time,time_in_band;
    int steps_alloc,steps_filld,i,n_phaseterms,err_cd_sprs,chirp_ok;

    /* Set physical parameters of the orbital system: */
    m1=m2=1.4;
    spin1=spin2=0.;

    /* Set ORBITAL frequency range of the chirp and sample time: */
    Initial_Freq=60.; /* in cycles/second */
    Max_Freq_Rqst=2000.; /* in cycles/second */
    Sample_Time=1./9868.4208984375; /* in seconds */

    /* post-Newtonian [O(1/c^n)] terms you wish to include (or supress)
       in the phase and frequency evolution: */
    n_phaseterms=5;
    phaseterms[0] =1.; /* The Newtonian piece */
    phaseterms[1] =0.; /* There is no O(1/c) correction */
    phaseterms[2] =1.; /* The post-Newtonian correction */
    phaseterms[3] =1.; /* The 3/2 PN correction */
    phaseterms[4] =1.; /* The 2PN correction */

    /* Set memory-allocation and error-code supression logic: */
    steps_alloc=10000;
    ptrCos=(float *)malloc(sizeof(float)*steps_alloc);
    ptrSin=(float *)malloc(sizeof(float)*steps_alloc);
    err_cd_sprs=0; /* 0 means print all warnings */

    /* Use chirp_filters() to compute the two filters: */
    chirp_ok=chirp_filters(m1,m2,spin1,spin2,n_phaseterms,phaseterms,
        Initial_Freq,Max_Freq_Rqst,&Max_Freq_Actual,Sample_Time,
        &ptrCos,&ptrSin,&steps_alloc,&steps_filld,&clscnc_time,err_cd_sprs);

    /* ... and print out the results: */
    time_in_band=(float)(steps_filld-1)*Sample_Time;
    fprintf(stderr,"\nm1=%f m2=%f Initial_Freq=%f\n",m1,m2,Initial_Freq);
    fprintf(stderr,"steps_filld=%i steps_alloc=%i Max_Freq_Actual=%f\n",
        steps_filld,steps_alloc,Max_Freq_Actual);
    fprintf(stderr,"time_in_band=%f clscnc_time=%f\n",time_in_band,clscnc_time);
    fprintf(stderr,"Termination code: %i\n",chirp_ok);
    for (i=0;i<steps_filld;i++){
        time=i*Sample_Time;
        printf("%i\t%f\t%f\t%f\n",i,time,ptrCos[i],ptrSin[i]);
    }
    return 0;
}
```

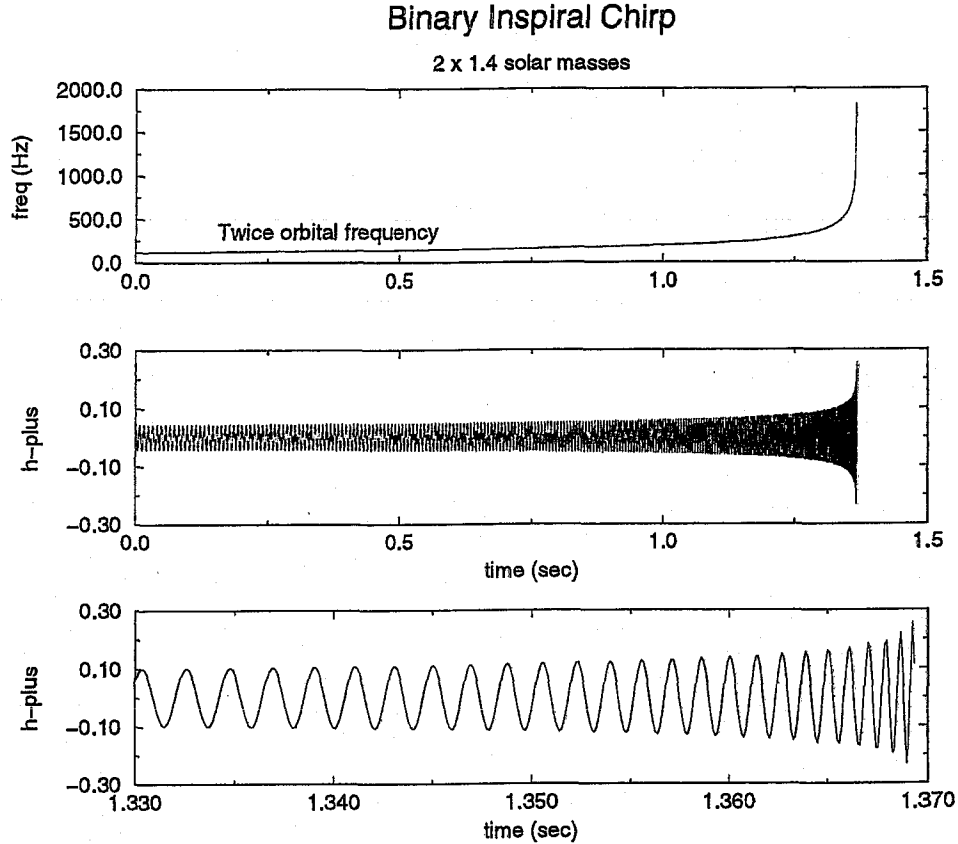


Figure 18: The zero-phase chirp waveform from a  $2 \times 1.4M_{\odot}$  binary system, starting at an orbital frequency of 60 Hz. The top graph shows the frequency of the dominant quadrupole radiation as a function of time, and the middle graph shows the waveform. The bottom graph shows a 40-msec stretch near the final inspiral/plunge.

Notice that we only allocated enough memory for 10000 points, and we know from the output from the previous example that this chirp takes 13515 points. Therefore running this example results in following error message printed to stderr:

```
GRASP:phase_frequency():Allocated memory is filled up before
reaching the maximum frequency requested for this chirp.
Orbital Frequency Reached(Hz): 98.867607, Number of points: 10000
Terminating chirp. Termination code set to:      2001
Returning to calling routine.
```

However, even though the routine ran out of memory it still computed the first 10000 points of the chirp and returned them in the arrays `*ptrptrCos[0..steps.alloc-1]` and `*ptrptrSin[0..steps.alloc-1]`.

## 5.8 Practical Suggestion for Setting Up a Large Bank of Filters:

We have carefully explained (how to avoid) a number of the pitfalls in computing post-Newtonian chirps. Before using the chirp generators to spit out hundreds or thousands of chirps needed for a bank of filters and farming out the computations out to dozens of parallel processors in a massive coalescing binary search, we strongly suggest that you edit the examples already given and check the routine against the **three** extreme cases you will encounter in your search.

1. Try the example with both masses set to the minimum mass in your proposed search, *i.e.* compute the phase and frequency evolution and the chirps for the template in the upper right hand corner in figure 33. This is the template of longest duration. If you are going to have a memory allocation problem you will have it with this template. Also, knowing the duration of the longest template in your search will help you decide the length of the segments of data which you filter. In general, you want the length of these data segments to be at least several times longer than the longest chirp. See Section 5.18 for further details.
2. Try the chirp generator with both masses set to the maximum mass in your search, *i.e.* compute the phase and frequency evolution of the template in the lower left corner of figure 33. This is the shortest duration template and the one least likely to make it to the upper cut off frequency before going out of the region of post-Newtonian viability. This case will be the most demanding test of the "chirp-termination" logic in `phase_frequency()`. It is also possible in the case of extremely large masses that there really is no chirp at all in the frequency regime requested. For example a binary composed of two  $100M_{\odot}$  object will coalesce long before it reaches the initial chirp frequency of the 60Hz we are using as our a lower cutoff frequency in our example. Don't worry. The routine `phase_frequency()` will warn you that the root finder was unable to find a viable solution for the initial time. You may have to adjust the search range accordingly.
3. Try the chirp generator with one mass at the minimum allowed value and the other mass at the maximum allowed value, *i.e.* compute the phase and frequency evolution for the template in the upper left corner of figure 33. This is the template which is most dominated by post-Newtonian terms in the evolution.

If the routine gives satisfactory results for these three cases, it should work for all the cases shown in figure 33; you are now ready for wholesale production.

## 5.9 Spin Effects

In the simple case where the spin vectors of the bodies are aligned (or antialigned) with the orbital angular momentum axis, the GRASP chirp-generating functions have the built-in capability of computing the leading order **spin-orbit** and **spin-spin** corrections to the inspiral chirp. To use this feature no modification of the chirp-generating routines [`phase_frequency()` or `chirp_filters()`] is necessary; simply pass nonzero values of the spin parameters to the functions. This can easily be done by editing the example programs `phase_evoltn.c` and/or `filters.c` to pass nonzero values of the variables `spin1` and `spin2`. [See below for definitions and allowed ranges of `spin1` and `spin2`.]

When spinning bodies are involved, the full gravitational waveform can be quite complicated; the orbital plane and the spin vectors of the individual bodies can precess. The precession causes a modulation of the signal. However, the GRASP routines only implement the special case when the spins are assumed to be aligned (or antialigned) with the orbital angular momentum axis. In this case there is no precession and, therefore, no modulation of the amplitude of the signal. Also in this case, the spin-corrections to the orbital frequency and phase are given by simple modifications to the nonspin phase and frequency Eqs. (5.4.1) and (5.4.2). The necessary terms can be found in Eq.(F22) in Appendix F of [7], and are given by

$$f(t) = \frac{M_{\odot}}{16\pi T_{\odot} m_{\text{tot}}} \left\{ \Theta^{-3/8} + \left( \frac{113}{160} [\chi_s + (\delta m/m)\chi_a] - \frac{19}{40} \eta \chi_s \right) \Theta^{-3/4} - \left( \frac{237}{512} \eta [(\chi_s)^2 - (\chi_a)^2] \right) \Theta^{-7/8} + \dots \right\}, \quad (5.9.1)$$

and

$$\phi(t) = \phi_c - \frac{1}{\eta} \left\{ \Theta^{5/8} + \left( \frac{113}{64} [\chi_s + (\delta m/m)\chi_a] - \frac{19}{16} \eta \chi_s \right) \Theta^{1/4} - \left( \frac{1185}{512} \eta [(\chi_s)^2 - (\chi_a)^2] \right) \Theta^{1/8} + \dots \right\}. \quad (5.9.2)$$

Here  $\Theta$  is the dimensionless time variable given by Eq. (5.4.3). The ellipses represent the nonspin (post)<sup>n</sup>-Newtonian terms already given in Eqs. (5.4.1) and (5.4.2). The quantities  $\chi_s$  and  $\chi_a$  are related to the angular momentum of the bodies by

$$\chi_s = \frac{1}{2} \left( \frac{S_1}{m_1^2} + \frac{S_2}{m_2^2} \right), \quad (5.9.3)$$

$$\chi_a = \frac{1}{2} \left( \frac{S_1}{m_1^2} - \frac{S_2}{m_2^2} \right), \quad (5.9.4)$$

where  $S_{1(2)}$  is the signed magnitude of the angular momentum vector of each body. The sign being positive (negative) for spins aligned (antialigned) with the the angular momentum axis. By comparing the nonspin phase and frequency evolution [Eqs. (5.4.1) and (5.4.2)] with the spin corrections in Eqs. (5.9.1) and (5.9.2), we see that the spin-orbit corrections (terms linear in  $\chi_s$  and  $\chi_a$ ) simply modify the (post)<sup>3/2</sup>-Newtonian contributions and the spin-spin corrections (term quadratic in  $\chi_s$  and  $\chi_a$ ) modify the (post)<sup>2</sup>-Newtonian contributions.

Specifically, the spin quantities passed to the chirp generation routines are the signed, dimensionless (Kerr-like) parameters of each body

$$\text{spin1} = \pm \frac{|S_1|}{m_1^2}, \quad (5.9.5)$$

$$\text{spin2} = \pm \frac{|S_2|}{m_2^2}, \quad (5.9.6)$$

where the  $+(-)$  sign is chosen if the spin is aligned (antialigned) with the orbital angular momentum axis. Some calculations (*e.g.* those requiring a precise definition of the orbital phase) are sensitive to the index assigned to the bodies. The GRASP convention is that  $m_1$  is the smaller of the two masses; therefore `spin1` should be the spin assigned to the smaller of the two masses.

What is the allowable range for the spin parameters `spin1` and `spin2`? For Kerr black holes, we know  $|\text{spin1}(2)| = (|\mathbf{S}_{1(2)}|/m_{1(2)}^2) \leq 1$ . For spinning neutron stars, stability studies (based on relativistic numerical hydrodynamic simulations) show that the spin parameter must satisfy  $|\text{spin1}(2)| = (|\mathbf{S}_{1(2)}|/m_{1(2)}^2) \lesssim 0.6$ . These limits can serve as a hard upper bound for a choice of spin parameters. However, observed pulsars in binaries have spin parameters substantially smaller than this limit, *e.g.* for the Hulse-Taylor pulsar we have `spin1`  $\lesssim 6.5 \times 10^{-3}$ . (See [10] for discussion and references.) Like all post-Newtonian equations, Eqs. (5.9.1) and (5.9.2) are slow-motion approximations to the fully relativistic equations of motion; therefore they are most accurate – and well behaved – for smaller values of the spin parameters. The GRASP routines have been tested for a modest range of masses ( $0.1M_\odot, 10M_\odot$ ) and spins ( $-0.2, +0.2$ ) in the frequency band  $60\text{Hz} \leq f_{orb} \leq 2000\text{Hz}$ ; they seem to give reasonable results in this regime. Finally, the admonitions and suggestions given in Sec. (5.8) about setting up banks of filters hold here also: test the chirp-generating functions with the extreme values of masses and spins you intend to use in your search. If the functions give satisfactory results at the “corners” of the parameter space, they should work on the interior of the parameter space.

## 5.10 Function: `make_filters()`

`void make_filters(float m1, float m2, float *ch1, float *ch2, float fstart, int n, float srate, int *filled, float *t_coal, int err_cd_sprs, int order)`

This function is an even more stripped down chirp generator, which fills a pair of arrays with waveforms for an inspiralling binary. The two chirps differ in phase by  $\pi/2$  radians and are given by Eqs.(5.6.1) and (5.6.2). This routine assumes spinless masses, and computes a chirp with phase corrections up to a specified post-Newtonian order.

The arguments are:

`m1`: Input. The mass of body-1 in solar masses.

`m2`: Input. The mass of body-2 in solar masses.

`ch1`: Output. Upon return, `ch1[0..filled-1]` contains the 0-phase chirp. The remaining array elements `ch1[filled..n-1]` are set to zero.

`ch2`: Output. Upon return, `ch2[0..filled-1]` contains the  $\pi/2$ -phase chirp. The remaining array elements `ch2[filled..n-1]` are set to zero.

`fstart`: Input. The starting gravity-wave frequency of the chirp in Hz. Note: this is twice the orbital frequency!

`n`: Input. The length of the arrays `ch1[]` and `ch2[]`.

`srate`: Input. The sample rate, in Hz. This is  $1/\Delta t$  where  $\Delta t$  is the time interval between successive entries in the `ch1[]` and `ch2[]` arrays.

`filled`: Output. The number of of time steps actually computed, before the chirp calculation was terminated, or until the arrays were filled (hence `filled`  $\leq$  `n`). Thus, on return, only the array elements `ch1[0..filled-1]` and `ch2[0..filled-1]` are contain the chirp; the remaining array elements are zero-padded.

`t_coal`: Output. The time to coalesce measured from the first point output, in `ch*[0]`.

`err_cd_sprs`: Input. Error code supression. This integer specifies the level of disaster encountered in the computation of the chirp for which the user will be explicitly warned with a printed message. Set to 0: prints all the termination messages. Set to 4000: suppresses all but a few messages which are harbingers of true disaster. (See identical argument in `chirp_filters()`).

`order`: Input. The order of the post-Newtonian approximation. This ranges from 0 (quadrupole approximation) up to 4 (second post-Newtonian order). Technicially, `order` is the power in  $(v/c)$  past the quadrupole approximation to which the post-Newtonian expansion is taken.

This routine assumes that you have already allocated storage arrays for the chirps. Note that the coalescence time may be much later than the last non-zero entry written into the `ch1[]` and `ch2[]` arrays.

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Comments: None.

## 5.11 Stationary phase approximation to binary inspiral chirps

Much of the literature on binary inspiral data analysis approximates chirps in the frequency domain by the method of stationary phase. The main reason for this approximation is the need to generate analytical expressions in the frequency domain, where almost all of the optimal filtering algorithm takes place. A side benefit is that the post-Newtonian expansion seems better behaved in the frequency domain—that is, there is no nonmonotonic frequency evolution as depicted in figure 17.

Therefore, GRASP includes `sp_filters()`, a stationary phase chirp generator similar to `make_filters()`. The advantage of this function is a considerable savings in CPU time by avoiding FFTs of time-domain chirps in the generation of matched filters. The disadvantage is that stationary phase is only an approximation, albeit a very good one in many situations of interest.

The stationary phase approximation can be found in any textbook on mathematical methods in physics. An excellent discussion in the context of binary inspiral can be found in section II C of [11].

The stationary phase approximations to the Fourier transforms of  $h_c(t)$  and  $h_s(t)$  [Eqs. (5.6.1,5.6.2)] are given in the restricted post-Newtonian approximation by

$$\tilde{h}_c(f) = \left(\frac{5\mu}{96M_\odot}\right)^{1/2} \left(\frac{M}{\pi^2 M_\odot}\right)^{1/3} f^{-7/6} T_\odot^{-1/6} \exp[i\Psi(f)], \quad (5.11.1)$$

$$\tilde{h}_s(f) = i\tilde{h}_c(f), \quad (5.11.2)$$

where  $f$  is the gravitational wave frequency in Hz,  $M$  is the total mass of the binary, and  $\mu$  is the reduced mass. Note that  $\tilde{h}_{c,s}(f)$  have dimensions of 1/Hz. The instrument strain per Hz,  $\tilde{h}(f)$ , is obtained from a linear superposition of  $\tilde{h}_{c,s}(f)$  in exactly the same way as  $h(t)$  is obtained from  $h_{c,s}(t)$ . See the discussion following Eqs. (5.6.1,5.6.2).

The restricted post-Newtonian approximation assumes that the evolution of the waveform amplitude is given by the 0'th-order post-Newtonian expression, but that the phase evolution is accurate to higher order. This phase is given by

$$\begin{aligned} \Psi(f) = & 2\pi f t_c - 2\phi_c - \pi/4 \\ & + \frac{3}{128\eta} \left[ x^{-5} + \left( \frac{3715}{756} + \frac{55}{9}\eta \right) x^{-3} - 16\pi x^{-2} \right. \\ & + \left( \frac{15\,293\,365}{508\,032} + \frac{27\,145}{504}\eta + \frac{3085}{72}\eta^2 \right) x^{-1} \\ & \left. + \left( \frac{38\,645}{756} + \frac{5}{3}\eta \right) \pi \ln x \right], \end{aligned} \quad (5.11.3)$$

where  $x = (\pi M f T_\odot / M_\odot)^{1/3}$ , the coalescence phase  $\phi_c$  is determined by the binary ephemeris, and the coalescence time  $t_c$  is the time at which the bodies collide. The chirps  $\tilde{h}_c$  and  $\tilde{h}_s$  are given  $\phi_c = 0$  and  $\phi_c = -\pi/4$ , respectively. All but the last term of (5.11.3) can be found in [12]; for the last term see the warning at the end of section 5.12.

The chirps are set to zero for frequencies below the requested starting frequency and above an upper cutoff  $f_c$ . Physically,  $f_c$  should correspond to the epoch when orbital inspiral turns to headlong plunge. The formula for  $f_c$  currently is not known for an arbitrary pair of objects, but in the limit of extreme mass ratio (and no spins) it should be equivalent to the well-known innermost stable circular orbit (ISCO) of Schwarzschild geometry. The frequency of the Schwarzschild ISCO can be computed exactly and is given in Hz by

$$f_c = \frac{M_\odot}{6^{3/2} \pi M T_\odot}. \quad (5.11.4)$$



In the absence of anything better, `sp_filters()` uses the Schwarzschild  $f_c$  for all binaries, a kludge which seems to work surprisingly well (see the `compare_chirps` program).

There is as yet no definitive, published investigation of how good the stationary phase approximation is for chirps. A future version of this document would be a good place for one!

## 5.12 Function: `sp_filters()`

```
void sp_filters(float m1, float m2, float *ch1, float *ch2, float fstart,
int n, float srate, float *f_c, float t_c, int order)
```

This function generates stationary phase approximations to binary inspiral chirp waveforms. Its input and output are similar to `make_filters()`. The difference is that the chirps are generated in the frequency domain using the stationary phase approximation.

The arguments are:

`m1`: Input. The mass of body-1 in solar masses.

`m2`: Input. The mass of body-2 in solar masses.

`ch1`: Output. Upon return, `ch1[0..n-1]` contains the stationary phase approximation to  $\tilde{h}_c(f)$  [Eq. (5.11.1)] in the same format as would be returned by a `realft()` of a time-domain function sampled at rate `srate`. That is, except for DC and Nyquist frequencies, `ch1[2*i]` and `ch1[2*i+1]` contain respectively the real and imaginary parts of  $\tilde{h}_c(f)$  for  $f = i * \text{srate}/n$ . This function sets `ch1[0]` (DC) and `ch1[1]` (Nyquist) to zero. The chirp is also set to zero for  $f < \text{fstart}$  and for  $f > \text{f}_c$  (see section 5.11 for  $f_c$ ). The output `ch1[0..n-1]` has dimensions of 1/Hz.

`ch2`: Output. Upon return, `ch2[]` contains  $\tilde{h}_s(f)$  in the same way that `ch1[]` contains  $\tilde{h}_c(f)$ .

`fstart`: Input. The starting gravitational-wave frequency of the chirp in Hz. Note: this is twice the orbital frequency!

`n`: Input. The length of the arrays `ch1[0..n-1]` and `ch2[0..n-1]`.

`srate`: Input. The sample rate, in Hz.

`f_c`: Output. The coalescence frequency  $f_c$ , as described in section 5.11. This is the high-frequency cutoff of the chirps.

`t_c`: Input. The coalescence time, in seconds. Note this is the time of the *end* of the chirp (see section 5.13).

`order`: Input. Order of generated chirps in  $(\pi M f T_\odot / M_\odot)^{1/3}$  (twice the post-Newtonian order).

This function assumes that you have already allocated storage for the chirps.

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Comments: The `sp_filters()` function doesn't include spins yet. Also, the approximation to  $f_c$  needs to be improved. It will be simple to add higher-order post-Newtonian phase terms as they appear in the literature.

Warning: I have included the 2.5-post-Newtonian term in this version of `sp_filters()`, but it should be treated with caution. To the best of my knowledge I am the only one in the world who has calculated  $\Psi(f)$  at this order, in a manuscript yet to be submitted. Somebody should check up on this term. Any volunteers?

### 5.13 Example: compare\_chirps program

This example compares a chirp generated by `sp_filters()` to a chirp with identical parameters generated by `make_filters()`; the output is shown in Figure 19. The chirp generated by `sp_filters()` is transformed to the time domain, and the two chirps are superimposed on one graph.

```
/* GRASP: Copyright 1997, Bruce Allen */
/* compare_chirps.c: by Benjamin Owen, 1997 */

#include "grasp.h"

#define FSTART 40.      /* GW starting frequency, in Hz */
#define SRATE 10000.   /* Sample rate, in Hz */
#define LENGTH 32768   /* Twice no of freq bins = samples in time domain */
#define MASS1 10.0     /* mass of first body, in solar masses */
#define MASS2 10.0     /* mass of second body, in solar masses */

int main() {
    FILE *fp;
    float t_c, f, *sp, *td, *dummy;
    int i;
    void realft(float*, unsigned long, int);

    /* Allocate memory for chirps */
    sp = (float *)malloc(sizeof(float)*LENGTH);
    td = (float *)malloc(sizeof(float)*LENGTH);
    dummy = (float *)malloc(sizeof(float)*LENGTH);

    /* Generate time-domain chirp for comparison purposes */
    make_filters(MASS1, MASS2, td, dummy, FSTART, LENGTH, SRATE, &i, &t_c, 2000, 4);

    /* Generate stationary phase chirp in frequency domain */
    sp_filters(MASS1, MASS2, sp, dummy, FSTART, LENGTH, SRATE, &f, t_c, 4);

    /* Transform stationary phase chirp to the time domain */
    realft(sp-1, LENGTH, -1);

    /* Graph both chirps in the time domain. First output file. */
    fp = fopen("compare_chirps.output", "w");
    for (i=0; i<LENGTH; i++)
        fprintf(fp, "%f %f %f\n", i/SRATE, td[i], sp[i]*2*SRATE/LENGTH);
    fclose(fp);

    /* Now graph the contents of the file using xmgr */
    system("xmgr -nxy compare_chirps.output &");

    return 0;
}
```

Note that to get the graph to show both chirps as simultaneous functions of time, `sp_filters()` needed to know the coalescence time found by `make_filters()`, so the latter function is called first. If the coalescence time input to `sp_filters()` had been zero, its chirp would have finished at the beginning—or equivalently, the end—of the time-domain data.

Also note that the inverse `realft()` of the stationary phase chirp had to be multiplied by a factor to be comparable to the time-domain chirp. The  $2/\text{LENGTH}$  factor is left out of the inverse `realft()`, and the

## Stationary Phase Approximation

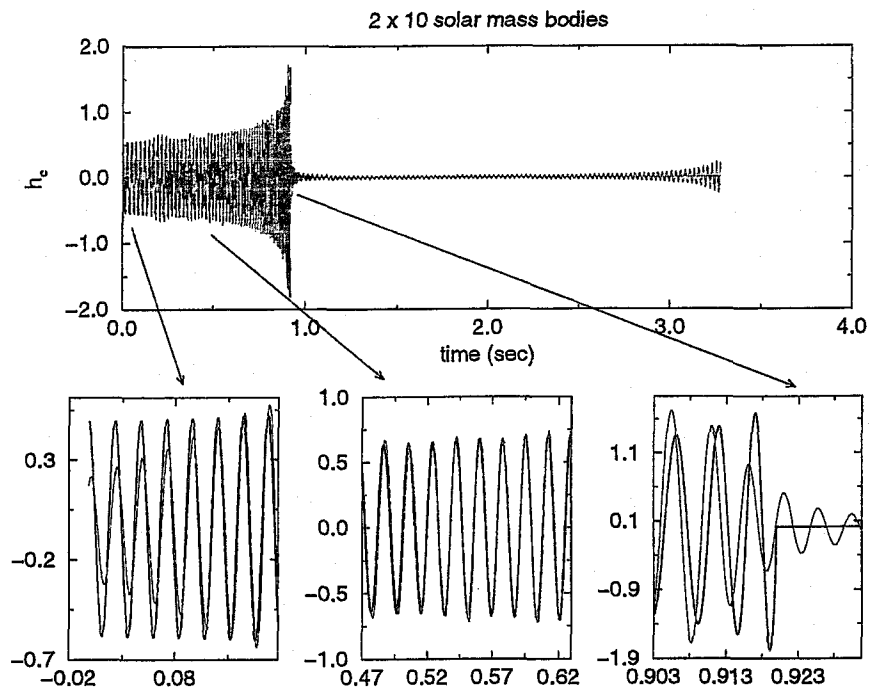


Figure 19: The output of `compare_chirps`, comparing the stationary-phase approximate waveform FFT'd into the time domain (red curve) with a 2nd-order post-Newtonian chirp calculated in the time domain, using `make_filters()` (black curve). The lower part of the graph shows three interesting regions of the upper (complete) graph. The bottom left detail shows the Gibbs startup-transient, the bottom middle detail shows a typical region of good agreement, and the bottom right detail shows the Gibbs turn-off transient. The Gibbs startup transient is also visible at the far right of the upper figure, which is periodically identified with the far left.

SRATE factor is needed to keep the dimensions right. (Also, the forward `realft()` of the time-domain chirp would need to be multiplied by  $1/\text{SRATE}$  to compare to the stationary phase chirp.)

## 5.14 Wiener (optimal) filtering

The technique of *optimal filtering* is a well-studied and well-understood technique which can be used to search for characteristic signals (in our case, chirps) buried in detector noise. In order to establish notation, we begin this section with a brief review of the optimal filtering technique.

Suppose that the detector output is a dimensionless strain  $h(t)$ . (In Section 3 we show how to construct this quantity for the CIT 40-meter prototype interferometer, using the recorded digital data stream). We denote by  $C(t)$  the waveform of the signal (i.e., the chirp) which we hope to find, hidden in detector noise, in the signal stream  $h(t)$ . Since we would like to know about chirps which start at different possible times  $t_0$ , we'll take  $C(t) = T(t - t_0)$  where  $T(t)$  is the waveform of a chirp which enters the sensitivity band of the interferometer at time  $t = 0$  (for the moment, forget about the fact that the chirps come in two different phase "flavors").

We will construct a signal  $S$  which is a number, defined by

$$S = \int_{-\infty}^{\infty} dt h(t)Q(t), \quad (5.14.1)$$

where  $Q(t)$  is an optimal filter function in time domain, which we will shortly determine in a way that maximizes the signal-to-noise ratio  $S/N$  or SNR. We will assume that  $Q$  is a real function of time.

We use the Fourier transform conventions of (3.9.3) and (3.9.4), in terms of which we can write the signal  $S$  as

$$\begin{aligned} S &= \int_{-\infty}^{\infty} dt \int_{-\infty}^{\infty} df \int_{-\infty}^{\infty} df' e^{-2\pi i f t + 2\pi i f' t} \bar{h}(f) \bar{Q}^*(f') \\ &= \int_{-\infty}^{\infty} df \int_{-\infty}^{\infty} df' \delta(f - f') \bar{h}(f) \bar{Q}^*(f') \\ &= \int_{-\infty}^{\infty} df \bar{h}(f) \bar{Q}^*(f). \end{aligned} \quad (5.14.2)$$

This final expression gives the signal value  $S$  written in the frequency domain, rather than in the time domain.

Now we can ask about the expected value of  $S$ , which we denote  $\langle S \rangle$ . This is the average of  $S$  over an ensemble of detector output streams, each one of which contains an identical chirp signal  $C(t)$  but different realizations of the noise:

$$h(t) = C(t) + n(t). \quad (5.14.3)$$

So for each different realization,  $C(t)$  is exactly the same function, but  $n(t)$  varies from each realization to the next. We will assume that the noise has zero mean value, and that the phases are randomly distributed, so that  $\langle \bar{n}(f) \rangle = 0$ . We can then take the expectation value of the signal in the frequency domain, obtaining

$$\langle S \rangle = \int_{-\infty}^{\infty} df \langle \bar{h}(f) \rangle \bar{Q}^*(f) = \int_{-\infty}^{\infty} df \bar{C}(f) \bar{Q}^*(f). \quad (5.14.4)$$

We now define the *noise*  $N$  to be the difference between the signal value and its mean for any given element of the ensemble:

$$N \equiv S - \langle S \rangle = \int_{-\infty}^{\infty} df \bar{n}(f) \bar{Q}^*(f). \quad (5.14.5)$$

The expectation value of  $N$  clearly vanishes by definition, so  $\langle N \rangle = 0$ . The expected value of  $N^2$  is non-zero, however. It may be calculated from the (one-sided) strain noise power spectrum of the detector  $S_h(f)$ , which is defined by

$$\langle \bar{n}(f) \bar{n}^*(f') \rangle = \frac{1}{2} S_h(|f|) \delta(f - f'), \quad (5.14.6)$$

and has the property that

$$\langle n^2(t) \rangle = \int_0^\infty S_h(f) df. \quad (5.14.7)$$

We can now find the expected value of  $N^2$ , by squaring equation (5.14.5), taking the expectation value, and using (5.14.6), obtaining

$$\begin{aligned} \langle N^2 \rangle &= \int_{-\infty}^{\infty} df \int_{-\infty}^{\infty} df' \tilde{Q}^*(f) \langle \tilde{n}(f) \tilde{n}^*(f') \rangle \tilde{Q}(f') \\ &= \frac{1}{2} \int_{-\infty}^{\infty} df S_h(|f|) |\tilde{Q}(f)|^2 \\ &= \int_0^\infty df S_h(f) |\tilde{Q}(f)|^2. \end{aligned} \quad (5.14.8)$$

There is a nice way to write the formulae for the expected signal and the expected noise-squared. We introduce an “inner product” defined for any pair of (complex) functions  $A(f)$  and  $B(f)$ . The inner product is a complex number denoted by  $(A, B)$  and is defined by

$$(A, B) = \int_{-\infty}^{\infty} df A(f) B^*(f) S_h(|f|). \quad (5.14.9)$$

Because  $S_h$  is positive, this inner product has the property that  $(A, A) \geq 0$  for all functions  $A(f)$ , vanishing if and only if  $A = 0$ . This inner product is what a mathematician would call a “positive definite norm”; it has all the properties of an ordinary dot product of vectors in three-dimensional Cartesian space.

In terms of this inner product, we can now write the expected signal, and the expected noise-squared, as

$$\langle S \rangle = \left( \frac{\tilde{C}}{S_h}, \tilde{Q} \right) \quad \text{and} \quad \langle N^2 \rangle = \frac{1}{2} (\tilde{Q}, \tilde{Q}). \quad (5.14.10)$$

(Note that whenever  $S_h$  appears inside the inner product, it refers to the function  $S_h(|f|)$  rather than  $S_h(f)$ .) Now the question is, how do we choose the optimal filter function  $Q$  so that the expected signal is as large as possible, and the expected noise-squared is as small as possible? The answer is easy: to maximize the signal-to-noise ratio

$$\left( \frac{S}{N} \right)^2 = \frac{\langle S \rangle^2}{\langle N^2 \rangle} = 2 \frac{(\frac{\tilde{C}}{S_h}, \tilde{Q})^2}{(\tilde{Q}, \tilde{Q})} \quad (5.14.11)$$

we choose

$$\tilde{Q}(f) = \frac{\tilde{C}(f)}{S_h(|f|)} = \frac{\tilde{T}(f)}{S_h(|f|)} e^{2\pi i f t_0}. \quad (5.14.12)$$

Going back to the definition of our signal  $S$ , you will notice that the signal  $S$  for “arrival time offset”  $t_0$  is given by

$$\begin{aligned} S &= \int_{-\infty}^{\infty} df \tilde{h}(f) \tilde{Q}^*(f) \\ &= \int_{-\infty}^{\infty} df \frac{\tilde{h}(f) \tilde{C}^*(f)}{S_h(|f|)} \\ &= \int_{-\infty}^{\infty} df \frac{\tilde{h}(f) \tilde{T}^*(f)}{S_h(|f|)} e^{-2\pi i f t_0}. \end{aligned} \quad (5.14.13)$$

Given a template  $\tilde{T}$  and the signal  $\tilde{h}$ , the signal values can be easily evaluated for any choice of arrival times  $t_0$  by means of a Fourier transform (or FFT, in numerical work). Thus, it is not really necessary to construct

a different filter for each possible arrival time; one can filter data for all possible choices of arrival time with a single FFT.

The signal-to-noise ratio for this optimally-chosen filter can be determined by substituting the optimal filter (5.14.12) into equation (5.14.11), obtaining

$$\left(\frac{S}{N}\right)^2 = 2(\bar{Q}, \bar{Q}) = 2 \int_{-\infty}^{\infty} df \frac{|\bar{C}(f)|^2}{S_h(|f|)} = 4 \int_0^{\infty} df \frac{|\bar{C}(f)|^2}{S_h(f)}. \quad (5.14.14)$$

You will notice that the signal-to-noise ratio  $S/N$  in (5.14.11) is independent of the overall normalization of the optimal filter  $Q$ : if we make  $Q$  bigger by a factor of ten, both the expected signal and the expected noise increase by exactly the same amount. For this reason, we will frequently specify the normalization of the filter so that the expected noise-squared from a specified source is unity:  $\langle N^2 \rangle = 1$ . This adjustment or change of the filter normalization can be obtained by moving the (fictitious) astrophysical system emitting the chirp template either closer or farther away from us. Because the metric strain  $h$  falls off as  $1/\text{distance}$ , the measured signal strength  $S$  is then a direct measure of the inverse distance.

For example, consider a system composed of two  $1.4 M_{\odot}$  masses in circular orbit. Suppose that normalizing the optimal filter for this system so that  $\langle N^2 \rangle = 1$  corresponds to putting the system at a distance of 15 megaparsecs (i.e., choosing  $C(t)$  to be the strain produced by an optimally-oriented  $2 \times 1.4 M_{\odot}$  system at a distance of 15 megaparsecs). If we then detect a signal with a signal-to-noise ratio  $S/N = 30$ , this corresponds to detecting an optimally-oriented source at a distance of half a megaparsec.

The functions `correlate()` and `productc()` are designed to perform this type of optimal filtering. We document these routines in the following section and in Section `s:utility`, then provide a simple example of an optimal filtering program.

There is an additional complication, arising from the fact that the gravitational radiation from a binary inspiral event is a linear combination of two possible orbital phases, as may be seen by reference to equations (5.6.1) and (5.6.2). Thus, the strain produced in a detector is a linear combination of two waveforms, corresponding to each of the two possible ( $0^\circ$  and  $90^\circ$ ) orbital phases:

$$h(t) = \alpha T_0(t) + \beta T_{90}(t) + n(t). \quad (5.14.15)$$

Here the subscripts 0 and 90 label the two possible orbital phases; the constants  $\alpha$  and  $\beta$  depend upon the distance to the source (or the normalization of the templates) and the orientation of the source relative to the detector. Thus  $T_0(t)$  denotes the (suitably normalized) function  $h_c(t)$  given by equation (5.6.1) and  $T_{90}(t)$  denotes the (suitably normalized) function  $h_s(t)$  given by equation (5.6.2).

In the optimal filtering, we are now searching for a pair of amplitudes  $\alpha$  and  $\beta$  rather than just a single amplitude. One can easily do this by choosing a filter function

$$\bar{Q}(f) = \frac{\bar{T}_0(f) - i\bar{T}_{90}(f)}{S_h(|f|)} e^{2\pi i f t_0}. \quad (5.14.16)$$

We will assume that the individual filters for each polarization are normalized by the convention just described, and that they are orthogonal:

$$\left(\frac{\bar{T}_0}{S_h}, \frac{\bar{T}_0}{S_h}\right) = 2, \text{ and } \left(\frac{\bar{T}_{90}}{S_h}, \frac{\bar{T}_{90}}{S_h}\right) = 2, \text{ and } \left(\frac{\bar{T}_0}{S_h}, \frac{\bar{T}_{90}}{S_h}\right) = 0. \quad (5.14.17)$$

Note that  $T_0$  and  $T_{90}$  are only exactly orthogonal in the adiabatic limit where they each have many cycles in any frequency interval  $df$  in which the noise power spectrum  $S_h(f)$  changes significantly. Also note that the filter function  $\bar{Q}(f)$  does not correspond to a real filter  $Q(t)$  in the time domain, since  $\bar{Q}(-f) \neq \bar{Q}^*(f)$ , so that the signal

$$S(t_0) = \left(\frac{\bar{h}}{S_h}, \bar{Q}\right) \quad (5.14.18)$$

is a complex-valued functions of the lag  $t_0$ . We define the noise as before, by  $N = S - \langle S \rangle$ . Its mean-squared modulus is

$$\begin{aligned} \langle |N|^2 \rangle &= \frac{1}{2} (\bar{Q}, \bar{Q}) \\ &= \frac{1}{2} \left( \frac{\bar{T}_0 - i\bar{T}_{90}}{S_h}, \frac{\bar{T}_0 - i\bar{T}_{90}}{S_h} \right) \\ &= \frac{1}{2} \left[ \left( \frac{\bar{T}_0}{S_h}, \frac{\bar{T}_0}{S_h} \right) + \left( \frac{\bar{T}_{90}}{S_h}, \frac{\bar{T}_{90}}{S_h} \right) \right] = 2, \end{aligned} \quad (5.14.19)$$

where we have made use of the orthonormality relation (5.14.17). Now the expected signal at zero lag  $t_0 = 0$  is

$$\langle S \rangle = \left( \frac{\langle \bar{h} \rangle}{S_h}, \bar{Q} \right) = \left( \frac{\alpha \bar{T}_0 + \beta \bar{T}_{90}}{S_h}, \frac{\bar{T}_0 - i\bar{T}_{90}}{S_h} \right) = 2\alpha + 2i\beta. \quad (5.14.20)$$

Hence the signal-to-noise ratio is

$$\frac{\langle S \rangle}{\sqrt{\langle |N|^2 \rangle}} = \alpha + i\beta. \quad (5.14.21)$$

In the absence of a signal  $\langle S \rangle = 0$  and the variance of this quantity (from the definition of  $N$ ) is unity:

$$\frac{\langle |S|^2 \rangle}{\langle |N|^2 \rangle} = 1. \quad (5.14.22)$$

In the presence of a signal, the signal-to-noise ratio is

$$\frac{|\langle S \rangle|^2}{\langle |N|^2 \rangle} = \alpha^2 + \beta^2 = \frac{1}{2} \sqrt{\left( \frac{\bar{h}}{S_h}, \frac{\bar{T}_0}{S_h} \right)^2 + \left( \frac{\bar{h}}{S_h}, \frac{\bar{T}_{90}}{S_h} \right)^2}. \quad (5.14.23)$$

The attentive reader will notice that we have lost a factor of  $\sqrt{2}$  in the signal-to-noise ratio compared to the case where we were searching for only a single phase of waveform. This is because of the additional uncertainty associated with our lack of information about the relative contributions of the two orbital phases. In other words, if we know in advance that a waveform is composed entirely of the zero-degree orbital phase, then the expectation value of the signal-to-noise, determined by equation (5.14.11) would be given by  $\langle S \rangle / N = \sqrt{2}\alpha$ . However if we need to search for the correct linear combination of the two possible phase waveforms, then the expectation value of the signal-to-noise is reduced to  $\langle S \rangle / N = \alpha$ .



### 5.15 Function: correlate()

```
void correlate(float *s, float *h, float *c, float *r, int n)
```

This function evaluates the correlation (as a function of lag time  $t$ ) defined by the discrete equivalent of equation (5.14.13):

$$s(t) = \frac{1}{2} \int_{-\infty}^{\infty} df \bar{h}(f) \bar{c}^*(f) \bar{r}(f) e^{-2\pi i f t}. \quad (5.15.1)$$

It is assumed that  $\bar{h}(f)$  and  $\bar{c}(f)$  are Fourier transforms of real functions, and that  $\bar{r}(f)$  is real. The factor of 1/2 appears in (5.15.1) for efficiency reasons; in order to calculate the integral (5.14.13) one should set  $\bar{r}(f) = 2/S_h(f)$ . The routine assumes that  $\bar{r}$  vanishes at both DC and the Nyquist frequency.

The arguments are:

s: Output. Upon return, the array  $s[0..n-1]$  contains the correlation  $s(t)$  at times

$$t = 0, \Delta t, 2\Delta t, \dots, (n-1)\Delta t. \quad (5.15.2)$$

h: Input. The array  $h[0..n-1]$  contains the positive frequency ( $f \geq 0$ ) part of the complex function  $\bar{h}(f)$ . The packing of  $\bar{h}$  into this array follows the scheme used by the *Numerical Recipes* routine `realft()`, which is described between equations (12.3.5) and (12.3.6) of [1]. The DC component  $\bar{h}(0)$  is real, and located in  $h[0]$ . The Nyquist-frequency component  $\bar{h}(f_{\text{Nyquist}})$  is also real, and is located in  $h[1]$ . The array elements  $h[2]$  and  $h[3]$  contain the real and imaginary parts, respectively, of  $\bar{h}(\Delta f)$  where  $\Delta f = 2f_{\text{Nyquist}}/n = (n\Delta t)^{-1}$ . Array elements  $h[2j]$  and  $h[2j+1]$  contain the real and imaginary parts of  $\bar{h}(j \Delta f)$  for  $j = 1, \dots, n/2 - 1$ . It is assumed that  $\bar{h}(f)$  is the Fourier transform of a real function, so that `correlate()` can infer the negative frequency components from the equation  $\bar{h}(-f) = \bar{h}^*(f)$ .

c: Input. The array  $c[0..n-1]$  contains the complex function  $\bar{c}$ , packed in the same format as  $\bar{h}(f)$ , with the same assumption that  $\bar{c}(-f) = \bar{c}^*(f)$ . Note that while you provide the function  $\bar{c}(f)$  to the routine, it is the *complex-conjugate* of the function contained in the array  $c[ ]$  which is used in calculating the correlation. Thus if  $\bar{r}$  is positive, `correlate(s, c, c, r, n)` will always return  $s[0] \geq 0$ .

r: Input. The array  $r[0..n/2]$  contains the values of the real function  $\bar{r}$  used as a weight in the integral. This is often chosen to be (twice!) the inverse of the receiver noise, as in equation (5.14.13), so that  $\bar{r}(f) = 2/\bar{S}_h(|f|)$ . The array elements are arranged in order of increasing frequency, from the DC value at subscript 0, to the Nyquist frequency at subscript  $n/2$ . Thus, the  $j$ 'th array element  $r[j]$  contains the real value  $\bar{r}(j \Delta f)$ , for  $j = 0, 1, \dots, n/2$ . Again it is assumed that  $\bar{r}(-f) = \bar{r}^*(f) = \bar{r}(f)$ .

n: Input. The total length of the complex arrays  $h$  and  $c$ , and the number of points in the output array  $s$ . Note that the array  $r$  contains  $n/2 + 1$  points.  $n$  must be even.

The correlation function calculated by this routine is  $\frac{1}{2} FFT^{-1}[\bar{h}\bar{c}^*\bar{r}]$  and has the same dimensions as the product  $\bar{h} \times \bar{c} \times \bar{r}$ . The definition is

$$s_k = \frac{1}{2} \sum_{j=0}^{n-1} h_j c_j^* r_j e^{-2\pi i j k/n} \quad (5.15.3)$$

where it is understood that  $\bar{h}_{n-j} = \bar{h}_j^*$  and that  $\bar{c}_{n-j} = \bar{c}_j^*$ , and that  $\bar{r}_{n-j} = \bar{r}_j$ .

Note that the input arrays  $h[ ]$  and  $c[ ]$  can be the same array. For example `correlate(s, c, c, r, n)` calculates the discrete equivalent of

$$s(t) = \frac{1}{2} \int_{-\infty}^{\infty} df |\bar{c}(f)|^2 \bar{r}(f) e^{-2\pi i f t}. \quad (5.15.4)$$

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Comments: For the sake of efficiency, this function does not include the contribution from either DC or Nyquist frequency bins to the correlation (these are negligible in any sensible data).

### 5.16 Function: avg\_inv\_spec()

```
void avg_inv_spec(float flo, float srate, int n, double decay, double *norm, float *htilde, float* mean_pow_spec, float* twice_inv_noise)
```

This function maintains an auto-regressive moving average (see avg\_spec()) of the power spectrum  $S_h(f)$ , and an array containing  $2/S_h(f)$ , which can be used for optimal filtering. This latter array is set to zero below a specified cut-off frequency  $f_{low}$ .

The arguments are:

**flo**: Input. The low frequency cut-off  $f_{low}$ , in Hz.

**srate**: Input. The sample rate, in Hz.

**n**: Input. The number of points in the arrays.

**decay**: Input. The quantity  $\exp(-\alpha)$  as defined in avg\_spec(). Sets the characteristic decay time for the auto-regressive average.

**norm**: Input/Output. Used for internal storage. Set to 0 when you want to begin a new auto-regressive average. Must not be altered otherwise.

**htilde**: Input. The array `htilde[0..n-1]` contains the positive frequency FFT of the metric perturbation.

**mean\_pow\_spec**: Output. The array `mean_pow_spec[0..n/2]` contains the mean power spectrum. Should be zeroed when resetting to begin a new average. The array element `mean_pow_spec[0]` contains the power spectrum at DC, and the array element `mean_pow_spec[n/2]` contains the power spectrum at the Nyquist frequency  $srate/2$ .

**twice\_inv\_noise**: Output. The array `twice_inv_noise[0..n/2]` contains  $2/S_h(f)$ . It is set to zero for  $f < f_{low}$ . The array element `twice_inv_noise[0]` contains the DC value, and the array element `twice_inv_noise[n/2]` contains the value at the Nyquist frequency  $srate/2$ .

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Comments: We assume here that the "correct" thing to do is the average the spectrum, then invert it. There may be a better way to construct the weight function for an optimal filter, however.

### 5.17 Function: orthonormalize()

```
void orthonormalize(float* ch0tilde, float* ch90tilde, float* twice_inv_noise,  
int n, float* n0, float* n90)
```

This function takes as input the (positive frequency parts of the) FFT of a pair of chirp signals. Upon return, the 90° phase chirp has been made orthogonal to the 0° phase chirp, with respect to the inner product defined by  $2/S_h$ . The normalizations of the chirps are also returned.

The arguments are:

`ch0tilde`: Input. The FFT of the zero-phase chirp  $T_0$ .

`ch90tilde`: Input/Output. The FFT of the 90°-phase chirp  $T_{90}$ .

`twice_inv_noise`: Input. Array containing  $2/S_h$ . The array element `twice_inv_noise[0]` contains the DC value, and the array element `twice_inv_noise[n/2]` contains the value at the Nyquist frequency.

`n`: Input. Defines the length of the arrays: `ch0tilde[0..n-1]`, `ch90tilde[0..n-1]`, and `twice_inv_noise`.

`n0`: Output. The normalization of the 0-phase chirp.

`n90`: Output. The normalization of the 90°-phase chirp.

Using the notation of (5.14.9) one may define an inner product of the chirps. The normalizations are defined as follows:

$$\frac{1}{n_0^2} \equiv \frac{1}{2}(Q_0, Q_0), \quad (5.17.1)$$

where  $Q_0$  is the optimal filter defined for the zero-phase chirp  $T_0$ . The chirps are orthogonalized internally using the Gram-Schmidt procedure. We first calculate  $(Q_0, Q_0)$  and  $(Q_{90}, Q_0)$  then define  $\epsilon = (Q_{90}, Q_0)/(Q_0, Q_0)$ . We then modify the 90°-phase chirp setting  $\tilde{T}_{90} \rightarrow T_{90} - \epsilon T_0$ . This ensures that the inner product  $(Q_{90}, Q_0)$  vanishes. The normalization for this newly-defined chirp is then defined by

$$\frac{1}{n_1^2} \equiv \frac{1}{2}(Q_{90}, Q_{90}). \quad (5.17.2)$$

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Comments: Notice that the filters  $Q_0$  and  $Q_{90}$  are not in general orthogonal except in the adiabatic limit as  $S_h(f)$  varies very slowly with changing  $f$ . Our approach to this is to construct a slightly-modified ninety-degree phase signal. Note however that this may introduce small errors in the determination of the orbital phase. This should be quantified.

## 5.18 Dirty details of optimal filtering: wraparound and windowing

To carry out optimal filtering, we need to break the data set (which might be hour, days, or weeks in length) into shorter stretches of  $N$  points (which might be seconds or minutes in length). We can understand the effects of “chopping up” the data most easily in the case for which (1) the instrument noise is *white*, so that  $S_h(f) = 1$ ; (2) the source is so close that its signal overwhelms the noise in the IFO, and (3) we are looking for a signal with a given phase (not a linear combination of the two orbital phases).

We want to calculate a signal  $S$  as a function of lag  $t_0$  using an FFT.

$$S(t_0) = \int h(t)T(t - t_0)dt \approx S(i_0) = \sum_j h_j T_{j-i_0}, \quad (5.18.1)$$

where we have written both the continuous-time and discrete-time version of the same equation. Using the definition of the discrete Fourier transform, and writing

$$h_j = \sum_{k=0}^{N-1} e^{-2\pi i j k / N} \bar{h}_k \quad \text{and} \quad T_{j-i_0} = \sum_{k'=0}^{N-1} e^{-2\pi i (j-i_0) k' / N} \bar{T}_{k'} \quad (5.18.2)$$

one can easily compute that the signal as a function of lag  $i_0$  is

$$S(i_0) = \sum_{j=0}^{N-1} \sum_{k=0}^{N-1} \sum_{k'=0}^{N-1} e^{-2\pi i j k / N} \bar{h}_k e^{-2\pi i (j-i_0) k' / N} \bar{T}_{k'} \quad (5.18.3)$$

$$= \sum_{k=0}^{N-1} \sum_{k'=0}^{N-1} N \delta_{k, -k'} e^{2\pi i i_0 k' / N} \bar{h}_k \bar{T}_{k'} \quad (5.18.4)$$

$$= \sum_{k=0}^{N-1} N e^{-2\pi i i_0 k / N} \bar{h}_k \bar{T}_k^* \quad (5.18.5)$$

Thus, if the data is treated as periodic, and the template is treated as periodic, one can compute the correlation as a function of time using only an FFT. In particular, the use of rectangular windowing does create sidelobes of the template’s frequency components. However it also creates identical sidelobes of the signal’s frequency components - so in effect the correlation in the time domain can be calculated exactly, without any windowing of the signal being necessary.

The only complication arises from the fact that the FFT treats the data as being periodic. Let’s consider some simple examples to illustrate the effects of this. In all of our examples, the number of data points is  $N = 65,536 = 2^{16}$  and the (schematic) chirp filter has length  $m = 13,500$  and is zero-padded after that time. Please remember, in all the figures that follow, to identify the far right hand side of the graph ( $i = 65535$ ) with the far left hand side ( $i = 0$ ). Figure 20 shows  $S(i_0)$  for a schematic chirp which begins at the first data point in the rectangular window. You will notice that the filter output peaks at  $i = 0$ . If the incoming chirp arrives somewhat later (it starts at  $i = 15,000$ ) as shown in Figure 21 then the filter output peaks at the start time, as shown. A chirp in the signal which starts at the  $i = 65,535 - 13,500$  as shown in Figure 22 causes the filter output to peak at  $i = 52,035$ . Thus, in order to find chirps, we need to find the maxima of the filter output over the interval  $i = 0 \dots, N - m$ .

Chirp filters can be “stimulated” or “triggered” by events that are not chirps. We will shortly discuss some techniques that can be used to distinguish triggering events that are chirps from those that are simply noise spikes or other transient (but non-chirp) varieties of non-stationary interferometer noise. Suppose that a chirp filter is triggered by some kind of transient event in the IFO output. At what time did this transient event occur? The answer to this question can be seen by examining the impulse response of the “periodic filter” scheme, as shown in the following figures. Thus, by searching for maxima in the filter output over

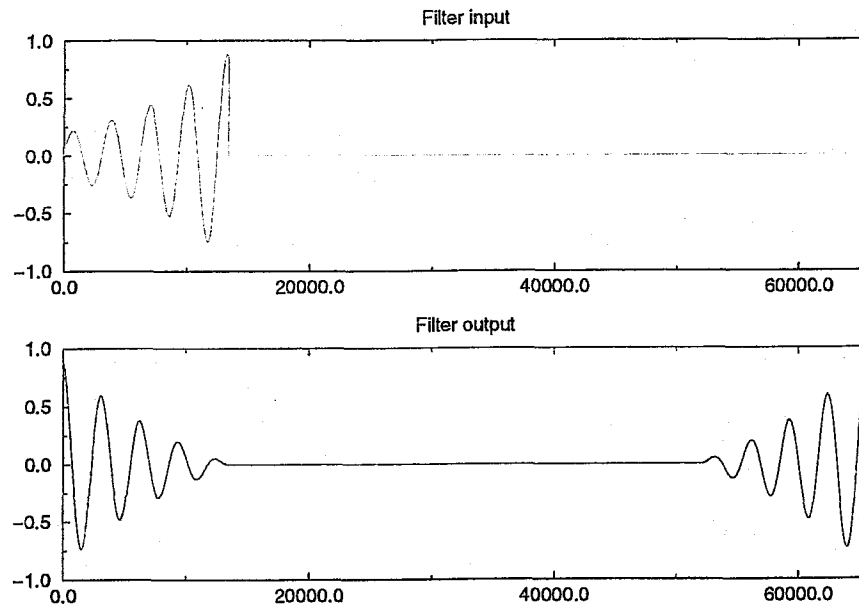


Figure 20: A chirp starting at initial time  $i = 0$  and ending at time  $i = 13500$  is processed through a chirp filter, whose output peaks at time  $i = 0$ . Notice that because of wraparound, the (non-causal) filter output begins “earlier” than  $i = 0$ .

the range  $i = 0, \dots, N - m - 1$  we can detect either true chirps in the data stream, starting in the time interval  $i = 0, \dots, N - m - 1$  and coalescing (roughly speaking) in the time interval  $i = m, \dots, N - 1$ , or we can detect transient impulse-like events in the data stream, which take place in the time interval  $i = m, \dots, N - 1$ . In the GRASP optimal filtering code, after examining the stretch of  $N$  data points, we then shift the data points  $i = N - m, \dots, N - 1$  into the range  $i = 0, \dots, m - 1$  and acquire a new additional set of  $N - m$  data points covering remaining (new) time interval.

Note that in practice, because the chirp signal has to be convolved with the response function  $R(f)$  of the detector, the impulse response of the filter is typically a few points longer than the actual chirp signal. For this reason it is smart to assume that the impulse response of your optimal filter is slightly longer (say a hundred points longer) than the actual time-domain length of the corresponding chirp. This safety margin is set with the `#define SAFETY` statement in the optimal filtering example. You lose a tiny bit of efficiency but reduce the likelihood that boundary effects from the data discontinuity at the start/end of the rectangular window will significantly stimulate the optimal filter output for  $i = 0, \dots, N - m - 1$ . (See Figs. 23 and 26 to see an illustration of how this windowing discontinuity will corrupt the filter’s output.)

We have demonstrated explicitly that with no windowing (or rather, rectangular windowing) of the data, one can find the appropriate correlation between the signal and a filter exactly: the rectangular window has the same effect on the signal as it does on the template (shifting energy into sidelobes in identical fashion). The only complication was that because of the periodic nature of the FFT one has to be careful about wrap-around errors in relating the output of a filter to the time of occurrence of a signal or impulse.

There is one remaining ugly question. The optimal filter  $\tilde{Q}$  depends upon the noise power spectrum of the detector. In real-world filtering, should this noise power spectrum be calculated with windowed, or non-windowed data? We can determine the correlation between signal and template exactly, with only rectangular windowing, because energy in either of these functions is shifted into sidelobes in identical fashion. However a “quiet” part of the IFO spectrum can be corrupted by sidelobes of a nearby noisy region.

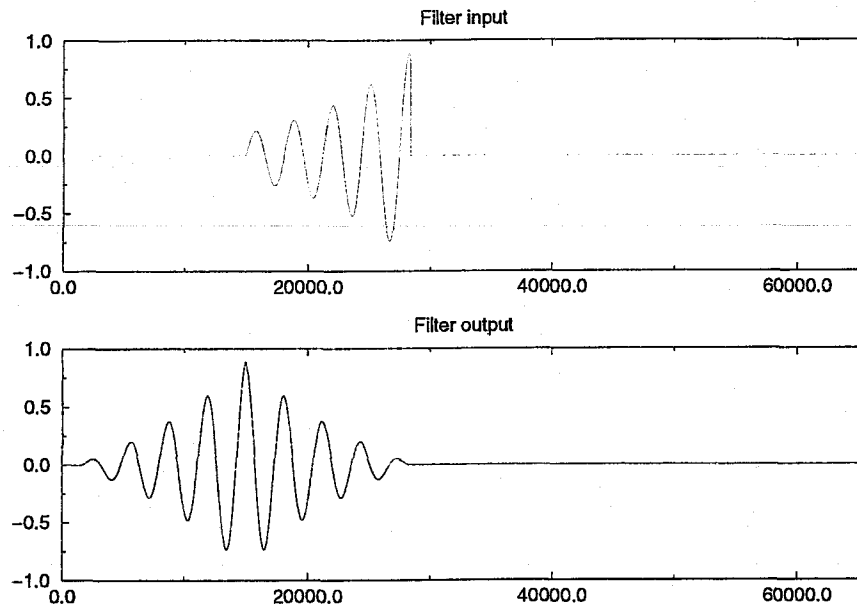


Figure 21: A chirp starting at initial time  $i = 15,000$  and ending at time  $i = 28,500$  is processed through a chirp filter, whose output peaks at time  $i = 15,000$ .

The effect of this is that the signal get rather less weight from this region of frequency space than it ought, in theory, to receive. This would argue for using only properly-windowed data to find the noise power spectrum to use in determining an optimal filter.

In fact, in our experience, it does not make any difference, at least not when you are searching for binary inspiral chirps. The reason is that the SNR obtained in an optimal filter is only sensitive at second order to errors in the optimal filter function. Thus, the errors due to noise sidelobes which appear if you fail to window the data to calculate an optimal filter are typically not large.

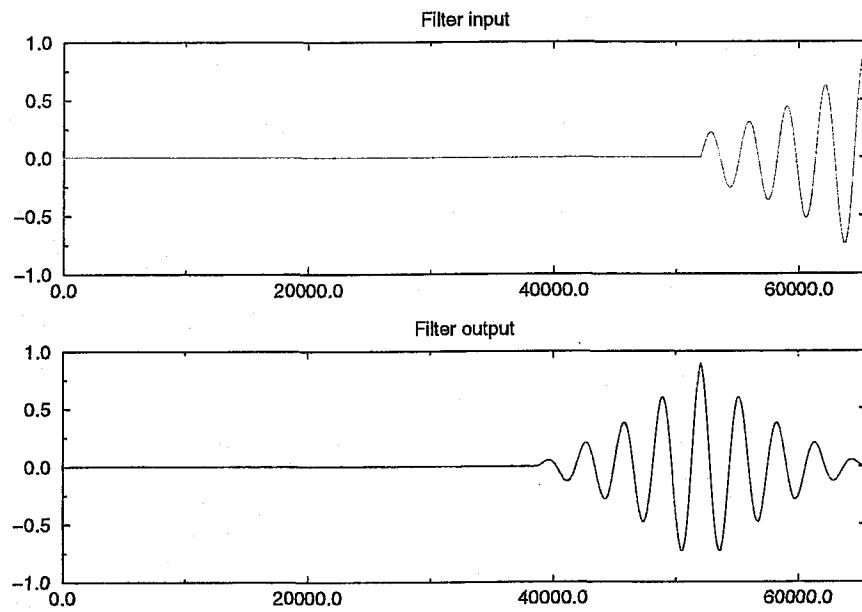


Figure 22: A chirp starting at initial time  $i = 52,035$ .

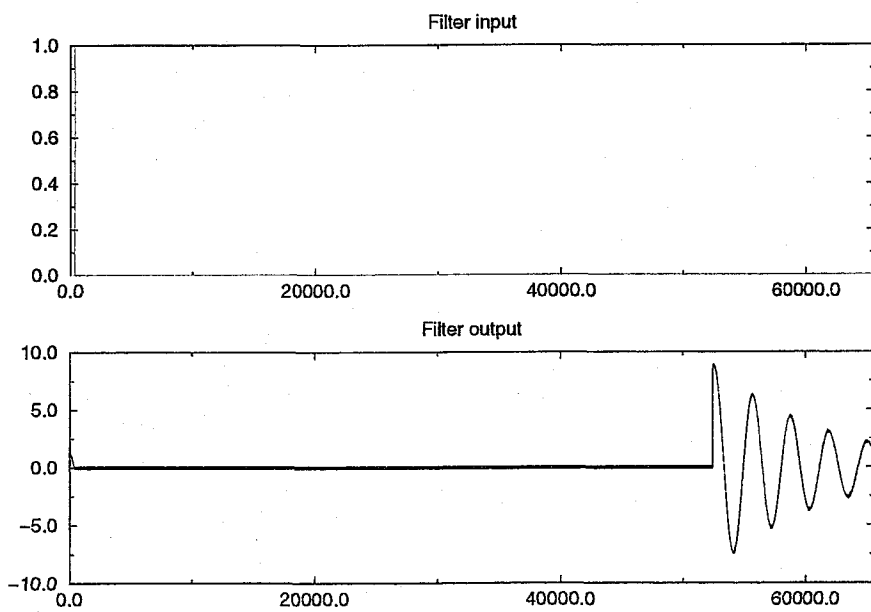


Figure 23: An impulse shortly after  $i = 0$ .



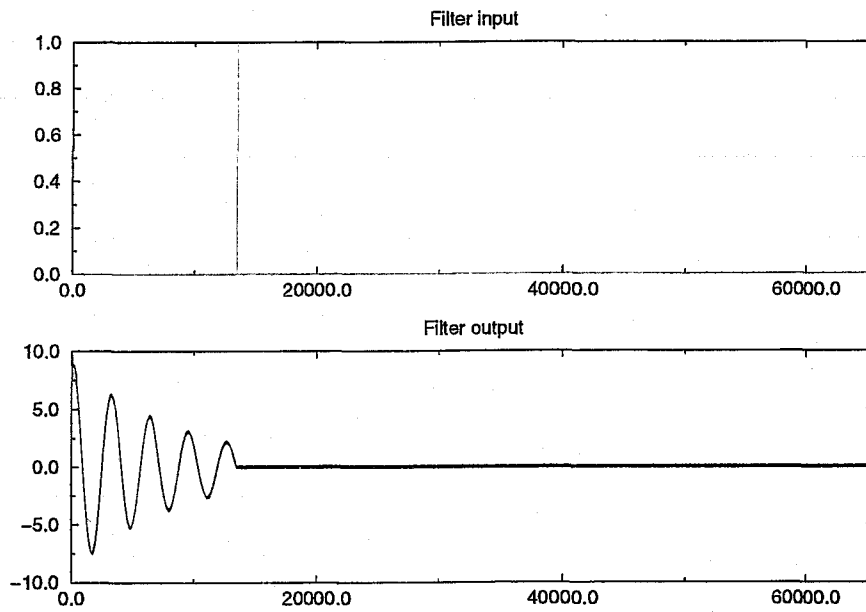


Figure 24: An impulse at  $i = 15,000$ .

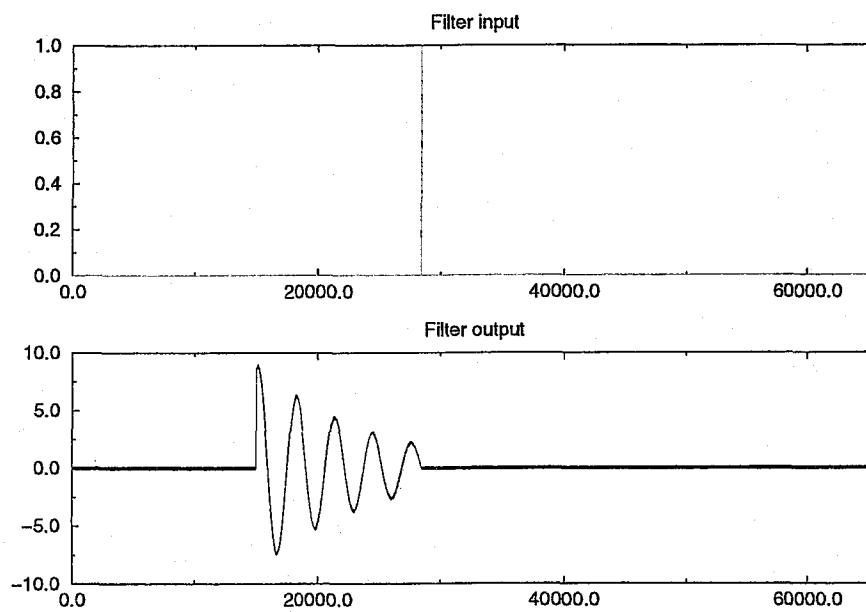


Figure 25: An impulse at  $i = 28,500$ .

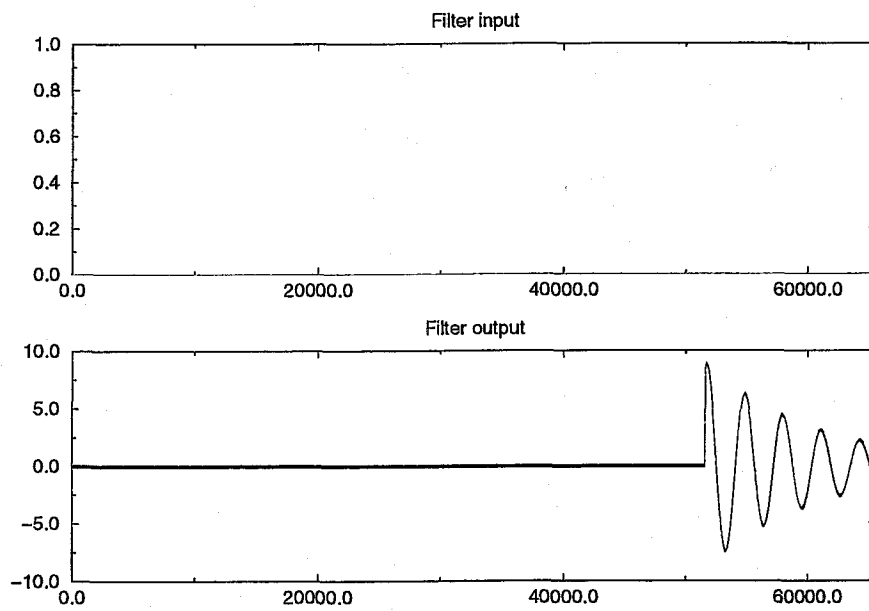


Figure 26: An impulse shortly before  $i = 65535$

### 5.19 Function: find\_chirp()

```
void find_chirp(float* htilde, float* ch0tilde, float* ch90tilde, float*
twice_inv_noise, float n0, float n90, float* output0, float* output90, int
n, int chirplen, int* offset, float* snr_max, float* c0, float* c90, float
*var)
```

This routine filters the gravity-wave strain through a pair of optimal filters corresponding to the two phases of a binary chirp, then finds the time at which the SNR peaks.

The arguments are:

`htilde`: Input. The FFT of the gravity-wave strain.

`ch0tilde`: Input. The FFT of the 0-degree chirp.

`ch90tilde`: Input. The FFT of the 90-degree chirp (assumed orthogonal to the 0-degree chirp).

`twice_inv_noise`: Input. Twice the inverse noise power spectrum, used for optimal filtering. The array element `twice_inv_noise[0]` contains the DC value, and the array element `twice_inv_noise[n/2]` contains the value at the Nyquist frequency.

`n0`: Input. Normalization of the 0-degree chirp.

`n90`: Input. Normalization of the 90-degree chirp.

`output0`: Output. A storage array. Upon return, contains the filter output of the 0-degree phase optimal filter.

`output90`: Output. A storage array. Upon return, contains the filter output of the 90-degree phase optimal filter.

`n`: Input. Defines the lengths of the various arrays: `ch0tilde[0..n-1]`, `ch90tilde[0..n-1]`, `output0[0..n-1]`, `output90[0..n-1]`, and `twice_inv_noise[0..n/2]`.

`chirplen`: Input. The number of bins in the time domain occupied by the chirp that you are searching for. This is necessary in order to untangle the wrap-around ambiguity explained earlier.

`offset`: Output. The offset, from 0 to `n-chirplen-1`, at which the signal output (for an arbitrary linear combination of the two filters) peaks.

`snr_max`: Output. The maximum signal-to-noise ratio (SNR) found.

`c0`: Output. The coefficient of the 0-phase template which achieved the highest SNR.

`c90`: Output. The coefficient of the 90°-phase template which achieved the highest SNR. Note that  $c_0^2 + c_{90}^2$  should be 1.

`var`: Output. The variance of the filter output. Would be 1 if the input to the filter were colored Gaussian noise with a spectrum defined by  $S_h$ .

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Comments: None.

## 5.20 Function: `freq_inject_chirp()`

```
void freq_inject_chirp(float c0, float c90, int offset, float invMpc, float*
ch0tilde, float* ch90tilde, float* htilde, int n)
```

The bottom-line test of any optimal filtering code or searching routines is: can you inject “fake” signals into the data stream, and properly detecting them, while properly rejecting all other signatures of instrumental effects, etc. This routine injects artificial signals into the frequency-domain strain  $\tilde{h}(f)$ . The plane of the binary system is assumed to be normal to the line to the detector.

The arguments are:

`c0`: Input. The coefficient of the 0-phase template to inject.

`c90`: Input. The coefficient of the 90°-phase to inject. Note that  $c_0^2 + c_{90}^2$  should be 1.

`offset`: Input. The offset number of samples at which the injected chirp starts, in the time domain.

`invMpc`: Input. The inverse of the distance to the system (measured in Mpc).

`ch0tilde`: Input. The FFT of the phase-0 chirp (strain units) at a distance of 1 Mpc.

`ch90tilde`: Input. The FFT of the phase-90 chirp (strain units) at a distance of 1 Mpc.

`htilde`: Output. The FFT of the gravity-wave strain. Note that this routine *adds into* and increments this array, so that if it contains another “signal” like IFO noise, the chirp is simply super-posed onto it.

`n`: Input. Defines the lengths of the various arrays `ch0tilde[0..n-1]`, `ch90tilde[0..n-1]`, and `htilde[0..n-1]`.

Note that in making use of this injection routine, you must determine the level of the quantization noise of the ADC, and be careful to inject a properly dithered version of this signal when its amplitude is small compared to the ADC quantization step size.

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Comments: See the comments for `time_inject_chirp`, particularly with respect to the digital quantization noise.

## 5.21 Function: `time_inject_chirp()`

```
void time_inject_chirp(float c0, float c90, int offset, float invMpc, float*
chirp0, float* chirp90, float* data, float *response, float *work, int n)
```

This is a time-domain version of the previous function `freq_inject_chirp()` which injects chirps in the time-domain (after deconvolving them with the detector's response function). This routine injects artificial signals into the time-domain strain  $h(t)$ . The plane of the binary system is assumed to be normal to the line to the detector.

The arguments are:

`c0`: Input. The coefficient of the 0-phase template to inject.

`c90`: Input. The coefficient of the 90°-phase to inject. Note that  $c_0^2 + c_{90}^2$  should be 1.

`offset`: Input. The offset number of samples at which the injected chirp starts, in the time domain.

`invMpc`: Input. The inverse of the distance to the system (measured in Mpc).

`chirp0`: Input. The time-domain phase-0 chirp (strain units) at a distance of 1 Mpc.

`chirp90`: Input. The time-domain phase-90 chirp (strain units) at a distance of 1 Mpc.

`data`: Output. The detector response in time that would be produced by the specified binary inspiral.

Note that this routine *adds into* and increments this array, so that if it contains another "signal" like IFO noise, the chirp is simply super-posed onto it.

`response`: Input. The function  $R(f)$  that specifies the response function of the IFO. This is produced by the routine `normalize_gw()`.

`work`: Output. A working array.

`n`: Input. Defines the lengths of the various arrays `chirp0[0..n-1]`, `chirp90[0..n-1]`, `data[0..n-1]`, `work[0..n-1]`, and `response[0..n+1]` (note that this "+" sign is *not* a typo!).

Note that in making use of this injection routine, you must determine the level of the quantization noise of the ADC, and be careful to inject a properly dithered version of this signal when its amplitude is small compared to the ADC quantization step size.

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Comments: A short look at the time-domain signal which is injected shows that it has a low-amplitude spike at the very start. This may be an un-avoidable Gibbs phenomenon associated with the turn-on of the waveform. A second interesting point is that for many interesting signals, the amplitude of the injected signal in the time domain is *below* the level of the quantization noise. Thus, a sensible injection scheme would be to add it into an appropriately dithered (float) version of the integer signal stream, then cast that back into an integer. This should be tried.

## 5.22 Vetoing techniques

In an ideal world, the output of an interferometer would be a stationary signal described by Gaussian statistics (with very rare superposed binary inspiral chirps and other gravitational-wave signals). This is unfortunately not the case, as can be quickly determined by simply listening to the raw (whitened) interferometer output. Typically the output is a stationary-sounding hiss, interrupted every few minutes by an obvious irregularity in the data stream. These are typically “pops”, “bumps”, “clicks”, “howlers”, “scrapers” and other recognizable categories of noises. In at least some cases, there are “suspects” for these events. For example the pops and bumps might be problems in any of the hundreds of BNC cable connectors used in the instrument.

It is an unfortunate fact that the output of an optimal filter strongly reflects these events. As you have seen in the previous section, a delta-function-like impulse signal in the IFO output can cause a large signal in the optimal filter. And in practice, this happens all of the time - the outputs of optimal chirp filters are frequently triggered by identifiable events in the IFO data stream that are clearly not binary inspiral chirps. Distinguishing these events from real inspiral chirps is called *vetoing*. We have found that two vetoing techniques work particularly well.

The first technique operates in the time domain, and is documented in the routine `is_gaussian()`. The idea is straightforward: if a chirp detector (optimal filter) is triggered, then we look in the data stream for an impulse event that might be responsible. Such events can be found by looking at the statistical distribution of the points in the time domain. If this distribution is significantly non-Gaussian then it indicates that some large transient event caused the filter to trigger, and the event is rejected.

The second technique is described here, and operates in the frequency domain. It is a very stringent test, which determines if the hypothetical chirp which has been found in the data stream is consistent with a true binary inspiral chirp summed with Gaussian interferometer noise. If this is true, it should be possible to subtract the (best fit) chirp from the signal, and be left with a signal stream that is consistent with Gaussian IFO noise. One of the nice features of this technique is that it can be statistically characterized in a rigorous way.

Suppose that one of our optimal chirp filters  $\bar{Q}$  is triggered with a large SNR at time  $t_0$ . We will denote the signal value at this time by  $S$ :

$$S = \int_{-f_{Ny}}^{f_{Ny}} df \frac{\bar{h}(f)\bar{T}^*(f)}{S_h(|f|)} e^{-2\pi i f t_0}. \quad (5.22.1)$$

(Here,  $f_{Ny}$  denotes the Nyquist frequency, one-half of the sampling rate.) The chirp template  $T$  is normalized so that the expected value  $\langle N^2 \rangle = 1$ :

$$\int_0^{f_{Ny}} df \frac{|\bar{T}(f)|^2}{S_h(|f|)} = 1. \quad (5.22.2)$$

We are going to investigate if this signal is “really” due to a chirp by investigating the way in which  $S$  gets its contribution from different ranges of frequencies. To do this, break up the integration region in this integral into a set of  $p$  disjoint subintervals  $\Delta f_1, \dots, \Delta f_p$  whose union is the entire range of frequencies from DC to Nyquist. Here  $p$  is a small integer (for example,  $p = 8$ ). This splitup can be performed using the GRASP function `splitup()`. The frequency intervals:

$$\begin{aligned} \Delta f_1 &= \{f \mid 0 < f < f_1\} \\ \Delta f_2 &= \{f \mid f_1 < f < f_2\} \\ &\dots \\ \Delta f_p &= \{f \mid f_{p-1} < f < f_{Ny}\}, \end{aligned} \quad (5.22.3)$$

are defined by the condition that the *expected signal contributions in each frequency band from a chirp are equal*:

$$\int_{\Delta f_i} df \frac{|\bar{T}(f)|^2}{S_h(|f|)} = \frac{1}{p} \int_0^{f_{Ny}} df \frac{|\bar{T}(f)|^2}{S_h(|f|)} \quad (5.22.4)$$

Because the filter is optimal, this also means that the expected noise contributions in each band from the chirp is the same. The frequency subintervals  $\Delta f_i$  are fairly narrow in regions of frequency space where the interferometer is quiet, and they are fairly wide in regions where the IFO is noisy.

Now, define a set of  $p$  signal values, one for each frequency interval:

$$S_i = \int_{-\Delta f_i \cup \Delta f_i} df \frac{\bar{h}(f)\bar{T}^*(f)}{S_h(|f|)} e^{-2\pi i f t_0} \quad \text{for } i = 1, \dots, p. \quad (5.22.5)$$

We have included both the positive and negative frequency subintervals to ensure that the  $S_i$  are real. If the detector output is Gaussian noise plus a true chirp, then the expected value of each of these signal values is  $\langle S_i \rangle = S/p$ . In this case the values of  $\Delta S_i \equiv S_i - S/p$  are independent normal random variables with a mean value of zero and a variance  $\sigma$  determined by the expected value of the noise-squared. Because of our choice of template normalization this is:

$$\sigma = \langle \Delta S_i^2 \rangle = \langle N^2 \rangle / p = 1/p. \quad (5.22.6)$$

Hence, in the presence of a true chirp and interferometer noise, the probability distribution of the  $\Delta S_i$  is given by

$$P(\Delta S_1, \dots, \Delta S_p) = \prod_{i=1}^p (2\pi\sigma)^{-1/2} e^{-\Delta S_i^2/2\sigma} = (2\pi\sigma)^{-p/2} e^{-(\Delta S_1^2 + \dots + \Delta S_p^2)/2\sigma}. \quad (5.22.7)$$

Thus, if our optimal chirp filter is triggered by an event, we can check the contributions to the signal in each of  $p$  frequency subintervals, to determine if the distribution of frequency and the arrival times in the  $p$  distinct subintervals is consistent with "chirp + Gaussian noise".

Because the  $\Delta S_i$  are independent random variables with zero mean and variance  $1/p$ , the sum of their squares is described by a  $\chi^2$  probability distribution. Define the statistic

$$r^2 = \sum_{i=1}^p (\Delta S_i)^2. \quad (5.22.8)$$

Then one can easily compute the probability distribution of  $r$ . The probability that  $r > R$  in the presence of a true chirp signal is

$$P(r > R) = (2\pi\sigma)^{-p/2} \Omega_{p-1} \int_R^\infty r^{N-1} e^{-r^2/2\sigma} dr \quad (5.22.9)$$

$$= \frac{1}{\Gamma(p/2)} \int_{R^2/2\sigma}^\infty x^{p/2-1} e^{-x} dx \quad (5.22.10)$$

$$= Q(p/2, R^2/2\sigma), \quad (5.22.11)$$

where  $\Omega_p$  is the  $p$ -volume of a unit-radius  $p$ -sphere  $S^p$ . The incomplete gamma function  $Q$  is the same function that describes the likelihood function in the traditional  $\chi^2$  test.

In practice (based on CIT 40-meter data) breaking up the frequency range into  $p = 8$  intervals provides a very reliable veto for rejecting events that trigger an optimal filter, but which are not themselves chirps. The value of  $Q(4, 10.0) = 0.0103 \dots$  so if  $r^2 > 2.5$  then one can conclude that the likelihood that a given

trigger is actually due to a chirp is less than 1%; rejecting or vetoing such events will only reduce the "true event" rate by 1%. However in practice it eliminates almost all other events that trigger an optimal filter; a noisy event that stimulates a binary chirp filter typically has  $r^2 \approx 100$  or larger!

Note that this technique is probably a computationally-efficient and simple version of the maximum-likelihood statistical test. This test is probably obtained in the limit where the number of frequency bins equals  $p$ .



### 5.23 Function: splitup()

```
void splitup(float *working, float template, float *r, int n, float total,
int p, int *indices)
```

This routine takes as inputs a template and a noise-power spectrum, and splits up the frequency spectrum into a set of sub-intervals to use with the vetoing technique just described.

The arguments are:

**working:** Input. An array `working[0..n-1]` used for working space.

**template:** Input. The array `template[0..n-1]` contains the positive frequency ( $f \geq 0$ ) part of the complex function  $\tilde{T}(f)$ . The packing of  $\tilde{T}$  into this array follows the scheme used by the *Numerical Recipes* routine `realft()`, which is described between equations (12.3.5) and (12.3.6) of [1]. The DC component  $\tilde{T}(0)$  is real, and located in `template[0]`. The Nyquist-frequency component  $\tilde{T}(f_{\text{Nyquist}})$  is also real, and is located in `template[1]`. The array elements `template[2]` and `template[3]` contain the real and imaginary parts, respectively, of  $\tilde{T}(\Delta f)$  where  $\Delta f = 2f_{\text{Nyquist}}/n = (n\Delta t)^{-1}$ . Array elements `template[2j]` and `template[2j+1]` contain the real and imaginary parts of  $\tilde{T}(j \Delta f)$  for  $j = 1, \dots, n/2 - 1$ .

**r:** Input. The array `r[0..n/2]` contains the values of the real function  $\tilde{r}$  which is twice the inverse of the receiver noise, as in equation (5.14.13), so that  $\tilde{r}(f) = 2/\tilde{S}_h(|f|)$ . The array elements are arranged in order of increasing frequency, from the DC value at subscript 0, to the Nyquist frequency at subscript  $n/2$ . Thus, the  $j$ 'th array element `r[j]` contains the real value  $\tilde{r}(j \Delta f)$ , for  $j = 0, 1, \dots, n/2$ . Again it is assumed that  $\tilde{r}(-f) = \tilde{r}^*(f) = \tilde{r}(f)$ .

**n:** Input. The total length of the complex arrays `template` and `working`, and the number of points in the output array `s`. Note that the array `r` contains  $n/2 + 1$  points.  $n$  must be even.

**total:** Input. This is the total value of the integrated template squared over  $S_h$ ; the frequency subintervals are chosen so that each of the  $p$  subintervals contains  $1/p$  of this total.

**p:** Input. The number of frequency bands into which you want to divide the range from DC to  $f_{\text{Nyquist}}$ .

**indices:** Output. The frequency bins of the first frequency band are  $i=0..indices[0]$ . The next frequency band is  $i=indices[0]+1..indices[1]$ . The  $p$ 'th frequency band is  $i=indices[p-2]+1..i$ . Note that `indices[p-1]=n-1`.

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Comments: None.

## 5.24 Function: splitup\_freq()

float splitup\_freq(float c0, float c90, float \*chirp0, float \*chirp90, float norm, float\* twice\_inv\_noise, int n, int offset, int p, int\* indices, float\* stats, float\* working, float\* htilde)

This routine returns the value of the statistic  $r^2 = \sum_{i=1}^p (\Delta S_i)^2$ . This is a less-efficient version, which internally constructs filters for each of the different frequency subintervals, and then filters the metric perturbation through those filters. It is useful to understand how the different frequency components behave in the time domain, after filtering.

The arguments are:

c0: Input. The coefficient of the 0-phase template.

c90: Input. The coefficient of the 90°-phase template. Note that  $c_0^2 + c_{90}^2$  should be 1.

chirp0: Input. An array chirp0[0..n-1] containing the FFT of the 0-phase chirp.

chirp90: Input. An array chirp90[0..n-1] containing the FFT of the 90°-phase chirp.

norm: Input. The normalization of the 0-phase chirp.

twice\_inv\_noise: Input. The array twice\_inv\_noise[0..n/2] contains  $2/S_h(f)$ , as described previously. The array element twice\_inv\_noise[0] contains the DC value, and the array element twice\_inv\_noise[n/2] contains the value at the Nyquist frequency.

n: Input. Defines the lengths of the previous arrays.

offset: Input. The offset of the moment of maximum signal in the filter output.

p: Input. The number of frequency bands  $p$  for the vetoing test.

indices: Output. An array indices[0..p-1] used for internal storage of the frequency subintervals (see splitup()).

stats: Output. An array stats[0..p-1] containing the values of the  $S_i$  for  $i = 1, \dots, p$ .

working: Output. An array working[0..n-1] used for internal storage.

htilde: Input. An array htilde[0..n-1] containing the positive frequency part of  $\tilde{h}(f)$ .

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Comments: None.

### 5.25 Function: splitup\_freq2()

float splitup\_freq2(float c0, float c90, float \*chirp0, float \*chirp90, float norm, float\* twice\_inv\_noise, int n, int offset, int p, int\* indices, float\* stats, float\* working, float\* htilde)

This routine returns the value of the statistic  $r^2 = \sum_{i=1}^p (\Delta S_i)^2$ . This is a more computationally-efficient version, which does not filter  $\tilde{h}$  through each of the  $p$  independent time domain filters. The arguments are identical to those of splitup\_freq().

The arguments are:

c0: Input. The coefficient of the 0-phase template.

c90: Input. The coefficient of the 90°-phase template. Note that  $c_0^2 + c_{90}^2$  should be 1.

chirp0: Input. An array chirp0[0..n-1] containing the FFT of the 0-phase chirp.

chirp90: Input. An array chirp90[0..n-1] containing the FFT of the 90°-phase chirp.

norm: Input. The normalization of the 0-phase chirp.

twice\_inv\_noise: Input. The array twice\_inv\_noise[0..n/2] contains  $2/S_h(f)$ , as described previously. The array element twice\_inv\_noise[0] contains the DC value, and the array element twice\_inv\_noise[n/2] contains the value at the Nyquist frequency.

n: Input. Defines the lengths of the previous arrays.

offset: Input. The offset of the moment of maximum signal in the filter output.

p: Input. The number of frequency bands  $p$  for the vetoing test.

indices: Output. An array indices[0..p-1] used for internal storage of the frequency subintervals (see splitup()).

stats: Output. An array stats[0..p-1] containing the values of the  $S_i$  for  $i = 1, \dots, p$ .

working: Output. An array working[0..n-1] used for internal storage.

htilde: Input. An array htilde[0..n-1] containing the positive frequency part of  $\tilde{h}(f)$ .

Author: Bruce Allen, ballen@dirac.phys.uwm.edu

Comments: None.

## 5.26 Example: optimal program

This program reads the 40-meter data stream, and then filters it through a chirp template corresponding to a pair of inspiraling  $1.4M_{\odot}$  neutron stars.

The correspondence between different arrays in this program, and the quantities discussed previously in this section, is given below. In these equations,  $\Delta t = 1/\text{srate}$  is the sample time in seconds, and  $\Delta f = (n\Delta t)^{-1} = \text{srate}/\text{npoint}$  is the size of a frequency bin, in Hz. Here  $n = \text{npoint}$  is the number of points in the data stream which are being optimally filtered in one pass.

Chirp templates (in frequency space) for the two polarizations are related to the arrays `chirp0[ ]` and `chirp1[ ]` by

$$\tilde{T}_0(f) = \frac{\Delta t}{\text{HSCALE}} \text{chirp0}[ ] \quad (5.26.1)$$

$$\tilde{T}_{90}(f) = \frac{\Delta t}{\text{HSCALE}} \text{chirp1}[ ] \quad (5.26.2)$$

where the elements `chirp0[2j]` and `chirp0[2j+1]` are the real and imaginary parts at frequency  $f = j\Delta f$  (with the exception of the Nyquist frequency, stored in `chirp0[1]`). Note that to ensure that quantities within the code remain within the dynamic range of floating point numbers, we have scaled up the template strain by a constant factor `HSCALE`; we also scale up the interferometer output by the same factor, so that all program output (such as signal-to-noise ratios) is independent of the value of `HSCALE`. If you're not comfortable with this, go ahead and change `HSCALE` to 1. It won't change anything, provided that you don't overflow the dynamic range of the floating point variables! The scaled interferometer response function is

$$\text{response}[ ] = \text{HSCALE}/\text{ARLENGTH} \times R(f), \quad (5.26.3)$$

where the function  $R(f)$  is defined by equation (3.12.3). The Fourier transform  $\tilde{h}$  of the dimensionless strain is obtained by multiplying  $\Delta t$  and the FFT of `channel.0` by `response[ ]`, yielding

$$\tilde{h}(f) = \frac{\Delta t}{\text{HSCALE}} \text{htilde}[ ]. \quad (5.26.4)$$

The one-sided noise power spectrum  $S_h(f)$  is the average of

$$S_h(f) = \frac{2}{n\Delta t} |\tilde{h}(f)|^2 = \frac{2}{n\Delta t} \frac{(\Delta t)^2}{\text{HSCALE}^2} |\text{htilde}[ ]|^2 = \frac{2\Delta t}{n \text{HSCALE}^2} |\text{htilde}[ ]|^2. \quad (5.26.5)$$

The power spectrum  $S_h(f)$  is averaged using the same exponential averaging technique described for the routine `avg_spec()`. This average is stored as

$$S_h(f) = \frac{2\Delta t}{n \text{HSCALE}^2} \langle |\text{htilde}[ ]|^2 \rangle = \frac{\Delta t}{n \text{HSCALE}^2} \text{mean\_pow\_spec}[ ] \quad (5.26.6)$$

Twice the inverse of this average is stored in the array `twice_inv_noise[ ]`, so that

$$\frac{2}{S_h(f)} = \frac{n \text{HSCALE}^2}{\Delta t} \text{twice\_inv\_noise}[ ]. \quad (5.26.7)$$

The expected noise-squared for the plus polarization is given by equation (5.14.8):

$$\begin{aligned} \langle N^2 \rangle &= \frac{1}{2} \langle Q, Q \rangle = \frac{1}{2} \int_{-\infty}^{\infty} df \frac{|\tilde{T}_0(f)|^2}{S_h(f)} \\ &= \frac{1}{2} \frac{1}{n\Delta t} \text{FFT}_0^{-1} \left[ \frac{(\Delta t)^2}{\text{HSCALE}^2} |\text{chirp0}[ ]|^2 \frac{n\text{HSCALE}^2}{\Delta t} \frac{1}{2} \text{twice\_inv\_noise}[ ] \right] \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2} FFT_0^{-1} \left[ |\text{chirp0}[]|^2 \frac{1}{2} \text{twice\_inv\_noise}[] \right] \\
&\rightarrow \frac{1}{2} \text{correlate}(\dots, \text{chirp0}[], \text{chirp0}[], \text{twice\_inv\_noise}[], \text{npoint}). \quad (5.26.8)
\end{aligned}$$

where the subscript on the inverse FFT means “at zero lag”, and “ $\rightarrow f$ ” means “returned by the call to the function  $f$ ”. We have chosen a distance for the system producing the “chirp”  $\tilde{T}(f)$  so that the expected value of  $\langle N^2 \rangle = 1$ .

In similar fashion, the signal  $S$  at lag  $t_0$  is given by

$$\begin{aligned}
S &= \left( \frac{\tilde{h}}{S_h}, \tilde{Q} \right) \\
&= \int_{-\infty}^{\infty} df \frac{\tilde{h}(f) \tilde{T}_0^*(f)}{S_h(f)} e^{-2\pi i f t_0} \\
&= \frac{1}{n \Delta t} FFT_i^{-1} \left[ \frac{\Delta t}{\text{HSCALE}} \text{htilde}[] \frac{\Delta t}{\text{HSCALE}} (\text{chirp0}[])^* \frac{n \text{HSCALE}^2}{\Delta t} \frac{1}{2} \text{twice\_inv\_noise}[] \right] \\
&= FFT_i^{-1} \left[ \text{htilde}[] \text{chirp0}[] \frac{1}{2} \text{twice\_inv\_noise}[] \right] \\
&\rightarrow \text{correlate}(\dots, \text{htilde}[], \text{chirp0}[], \text{twice\_inv\_noise}[], \text{npoint}), \quad (5.26.9)
\end{aligned}$$

where now the subscript on the FFT means “at lag  $t = i \Delta t$ ”.

You might wonder why we have been so careful – after all, both the signal and the noise, as we’ve defined them, are dimensionless, so it’s not surprising that all of the factors of  $\Delta t$  drop out of the final formulae for the signal and the expected noise-squared. The main reason we’ve been so long winded is to show exactly how the units cancel out, and to demonstrate that there aren’t any missing dimensionless constants, like `npoint`, left out of the program. Some sample output from this program is shown in the next section.

```

/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"
#define NPOINT 131072      /* The size of our segments of data (13.1 secs) */
#define FLO 120.0         /* The low frequency cutoff for filtering */
#define ARMLENGTH 40.0    /* Armlength of the IFO, in meters */
#define HSCALE 1.e21      /* A convenient scaling factor; results independent of it */
#define MIN_INT0_LOCK 3.0 /* Number of minutes to skip into each locked section */
#define SAFETY 1000       /* Padding safety factor to avoid wraparound errors */

int main() {
    void realft(float*, unsigned long, int);
    int i, code, npoint, remain=0, maxi, chirplen, needed, diff, impulseoff, chirppoints, indices[8];
    float distance, snr_max, srate=9868.4208984375, tstart, *mean_pow_spec, timeoff, timestart;
    float *data, *htilde, *output90, *output0, *chirp0, *chirp90, *ch0tilde, *ch90tilde;
    float n0, n90, inverse_distance_scale, decaytime, *twice_inv_noise, datastart, tc;
    float lin0, lin90, invMpc_inject, varsplit, stats[8], gammq(float, float), var, *response;
    double decay, norm, prob;
    short *datas;
    FILE *fpifo, *fpss, *fplock;

    /* open the IFO output file, lock file, and swept-sine file */
    fpifo=grasp_open("GRASP_DATAPATH", "channel.0");
    fplock=grasp_open("GRASP_DATAPATH", "channel.10");
    fpss=grasp_open("GRASP_DATAPATH", "swept-sine.ascii");

    /* number of points to sample and fft (power of 2) */
    needed=npoint=NPOINT;

    /* stores ADC data as short integers */
    datas=(short*)malloc(sizeof(short)*npoint);

    /* stores ADC data in time & freq domain, as floats */
    data=(float *)malloc(sizeof(float)*npoint);

    /* The phase 0 and phase pi/2 chirps, in time domain */
    chirp0=(float *)malloc(sizeof(float)*npoint);
    chirp90=(float *)malloc(sizeof(float)*npoint);

    /* Orthogonalized phase 0 and phase pi/2 chirps, in frequency domain */
    ch0tilde=(float *)malloc(sizeof(float)*npoint);
    ch90tilde=(float *)malloc(sizeof(float)*npoint);

    /* The response function (transfer function) of the interferometer */
    response=(float *)malloc(sizeof(float)*(npoint+2));

    /* The gravity wave signal, in the frequency domain */
    htilde=(float *)malloc(sizeof(float)*npoint);

    /* The autoregressive-mean averaged noise power spectrum */
    mean_pow_spec=(float *)malloc(sizeof(float)*(npoint/2+1));

    /* Twice the inverse of the mean noise power spectrum */
    twice_inv_noise=(float *)malloc(sizeof(float)*(npoint/2+1));

    /* Ouput of matched filters for phase0 and phase pi/2, in time domain, and temp storage */
    output0=(float *)malloc(sizeof(float)*npoint);
    output90=(float *)malloc(sizeof(float)*npoint);

    /* get the response function, and put in scaling factor */

```

```

normalize_gw(fpss,npoint,srate,response);
for (i=0;i<npoint+2;i++)
    response[i]*=HSCALE/ARMLENGTH;

/* manufacture two chirps (dimensionless strain at 1 Mpc distance) */
make_filters(1.4,1.4,chirp0,chirp90,FLO,npoint,srate,&chirppoints,&etc,0,4);
/* normalization of next line comes from GRASP (5.6.3) and (5.6.4) */
inverse_distance_scale=2.0*HSCALE*(TSOLAR*C_LIGHT/MPC);
for (i=0;i<chirppoints;i++){
    ch0tilde[i]=chirp0[i]*inverse_distance_scale;
    ch90tilde[i]=chirp90[i]*inverse_distance_scale;
}

/* zero out the unused elements of the tilde arrays */
for (i=chirppoints;i<npoint;i++)
    ch0tilde[i]=ch90tilde[i]=0.0;

/* and FFT the chirps */
realft(ch0tilde-1,npoint,1);
realft(ch90tilde-1,npoint,1);

/* set length of template including a safety margin */
chirplen=chirppoints+SAFETY;
if (chirplen>npoint) abort();

/* This is the main program loop, which acquires data, then filters it */
while (1) {

    /* Seek MIN_INT0_LOCK minutes into a locked stretch of data */
    while (remain<needed) {
        code=get_data(fpifo,fplock,&tstart,MIN_INT0_LOCK*60*srate,
                    datas,&remain,&srate,1);
        if (code==0) return 0;
    }

    /* if just entering a new locked stretch, reset averaging over power spectrum */
    if (code==1) {
        norm=0.0;
        clear(mean_pow_spec,npoint/2+1,1);

        /* decay time for spectrum, in sec. Set to 15x length of npoint sample */
        decaytime=15.0*npoint/srate;
        decay=exp(-1.0*npoint/(srate*decaytime));
    }

    /* Get the next needed samples of data */
    diff=npoint-needed;
    code=get_data(fpifo,fplock,&tstart,needed,datas+diff,&remain,&srate,0);
    datastart=tstart-diff/srate;

    /* copy integer data into floats */
    for (i=0;i<npoint;i++) data[i]=datas[i];

    /* inject signal in time domain (note output0[] used as temp storage only) */
    invMpc_inject=0.0; /* To inject a signal at 10 kpc, set this to 100.0 */
    time_inject_chirp(1.0,0.0,12345,invMpc_inject,chirp0,chirp90,data,
                    response,output0,npoint);

    /* find the FFT of data*/

```

```

realft(data-1,npoint,1);

/* normalized delta-L/L tilde */
product(htilde,data,response,npoint/2);

/* update the inverse of the auto-regressive-mean power-spectrum */
avg_inv_spec(FLO,srate,npoint,decay,&norm,htilde,mean_pow_spec,twice_inv_noise);

/* inject a signal in frequency domain, if desired */
invMpc_inject=0.0; /* To inject a signal at 10 kpc, set this to 100.0 */
freq_inject_chirp(-0.406,0.9135,23456,invMpc_inject,ch0tilde,ch90tilde,htilde,
                 npoint);

/* orthogonalize the chirps: we never modify ch0tilde, only ch90tilde */
orthonormalize(ch0tilde,ch90tilde,twice_inv_noise,npoint,&n0,&n90);

/* distance scale Mpc for SNR=1 */
distance=sqrt(1.0/(n0*n0)+1.0/(n90*n90));

/* find the moment at which SNR is a maximum */
find_chirp(htilde,ch0tilde,ch90tilde,twice_inv_noise,n0,n90,output0,output90,
           npoint,chirplen,&maxi,&snr_max,&lin0,&lin90,&var);

/* identify when an impulse would have caused observed filter output */
impulsoff=(maxi+chirppoints)%npoint;
timeoff=datastart+impulsoff/srate;
timestart=datastart+maxi/srate;

/* if SNR greater than 5, then print details, else just short message */
if (snr_max<5.0)
    printf("max snr: %.2f offset: %d data start: %.2f sec. variance: %.5f\n",
           snr_max,maxi,datastart,var);
else {
    /* See if the nominal chirp can pass a frequency-space veto test */
    varsplit=splitup_freq2(lin0*n0/sqrt(2.0),lin90*n90/sqrt(2.0),ch0tilde,
                           ch90tilde,2.0/(n0*n0),twice_inv_noise,npoint,maxi,8,
                           indices,stats,output0,htilde);
    prob=gammq(4.0,4.0*varsplit);
    printf("\nMax SNR: %.2f (offset %d) variance %f\n",snr_max,maxi,var);
    printf("  If impulsive event, offset %d or time %.2f\n",impulsoff,timeoff);
    printf("  If inspiral, template start offset %d (time %.2f) ",maxi,timestart);
    printf("coalescence time %.2f\n",timestart+tc);
    printf("  Normalization: S/N=1 at %.2f kpc\n",1000.0*distance);
    printf("  Lin combination of max SNR: %.4f x phase_0 + %.4f x phase_pi/2\n",
           lin0,lin90);
    if (prob<0.01)
        printf("  Less than 1%% probability that this is a chirp (p=%f).\n",prob);
    else
        printf("  POSSIBLE CHIRP! with > 1%% probability (p=%f).\n",prob);

    /* See if the time-domain statistics are unusual or appears Gaussian */
    if (is_gaussian(datas,npoint,-2048,2047,1))
        printf("  Distribution does not appear to have outliers...\n\n");
    else
        printf("  Distribution has outliers! Reject\n\n");
}

/* shift ends of buffer to the start */
needed=npoint-chirplen+1;

```



```
for (i=0;i<chirplen-1;i++)
    datas[i]=datas[i+needed];

/* reset if not enough points remain to fill the buffer */
if (remain<needed)
    needed=npoint;
}
```

## 5.27 Some output from the optimal program

Some output from the optimal program follows:

```
...
max snr: 3.11 offset: 23623 data start: 180.00 sec. variance: 0.94044
max snr: 2.91 offset: 3311 data start: 185.17 sec. variance: 0.84484
...
max snr: 2.53 offset: 19041 data start: 309.26 sec. variance: 0.70333
max snr: 2.98 offset: 35711 data start: 314.43 sec. variance: 0.67523

Max SNR: 8.71 (offset 42109) variance 0.805030
  If impulsive event, offset 55624 or time 325.23
  If inspiral, template start offset 42109 (time 323.86) coalescence time 325.23
  Normalization: S/N=1 at 116.75 kpc
  Linear combination of max SNR: 0.9315 x phase_0 + 0.3638 x phase_pi/2
  Less than 1% probability that this is a chirp (p=0.000000).
  Distribution: s= 23, N>3s= 12 (expect 176), N>5s= 0 (expect 0)
  Distribution does not appear to have outliers...

max snr: 2.51 offset: 31183 data start: 324.77 sec. variance: 0.63028
max snr: 2.56 offset: 49909 data start: 329.94 sec. variance: 0.66853
...
max snr: 2.82 offset: 35080 data start: 3002.03 sec. variance: 0.77306
max snr: 2.61 offset: 33141 data start: 3007.20 sec. variance: 0.74268

Max SNR: 89.75 (offset 16678) variance 82.547005
  If impulsive event, offset 30193 or time 3015.43
  If inspiral, template start offset 16678 (time 3014.06) coalescence time 3015.43
  Normalization: S/N=1 at 128.49 kpc
  Linear combination of max SNR: -0.3955 x phase_0 + 0.9185 x phase_pi/2
  Less than 1% probability that this is a chirp (p=0.000000).
  Distribution: s= 29, N>3s= 157 (expect 176), N>5s= 30 (expect 0)
  Distribution has outliers! Reject

max snr: 3.24 offset: 22412 data start: 3017.54 sec. variance: 0.99474
max snr: 2.73 offset: 37777 data start: 3022.71 sec. variance: 0.75325
...
max snr: 2.80 offset: 5893 data start: 4140.89 sec. variance: 0.73240
max snr: 2.75 offset: 46932 data start: 4146.06 sec. variance: 0.69654

Max SNR: 6.08 (offset 30002) variance 0.883380
  If impulsive event, offset 43517 or time 4155.64
  If inspiral, template start offset 30002 (time 4154.27) coalescence time 4155.64
  Normalization: S/N=1 at 113.04 kpc
  Linear combination of max SNR: -0.4773 x phase_0 + 0.8787 x phase_pi/2
  POSSIBLE CHIRP! with > 1% probability (p=0.024142).
  Distribution: s= 31, N>3s= 399 (expect 176), N>5s= 53 (expect 0)
  Distribution has outliers! Reject
```

```
max snr: 2.77 offset: 15985 data start: 4156.40 sec. variance: 0.72095
max snr: 2.69 offset: 47338 data start: 4161.57 sec. variance: 0.69708
...
```

This output shows three events that triggered an optimal filtering routine. The first and second of these events were rejected for different reasons. The first was rejected because it failed the frequency-distribution test. The second was rejected because it had 30 outlier points. The third failed for the same reason: it had 53 outlier points.

Next, we show some output when a fake chirp signal is injected into the data stream. This can be done for example by modifying optimal to read:

```
invMpc_inject=100.0; /* To inject a signal at 10 kpc, set this to 100.0 */
time_inject_chirp(1.0,0.0,12345,invMpc_inject,chirp0,chirp90,data,response,output)
```

This produces the following output:

```
...
Max SNR: 9.96 (offset 12345) variance 0.872624
  If impulsive event, offset 25860 or time 187.79
  If inspiral, template start offset 12345 (time 186.42) coalescence time 187.7
  Normalization: S/N=1 at 152.17 kpc
  Linear combination of max SNR: 0.9995 x phase_0 + -0.0304 x phase_pi/2
  POSSIBLE CHIRP! with > 1% probability (p=0.421294).
  Distribution: s= 23, N>3s= 12 (expect 176), N>5s= 0 (expect 0)
  Distribution does not appear to have outliers...

Max SNR: 12.84 (offset 12345) variance 0.834527
  If impulsive event, offset 25860 or time 192.96
  If inspiral, template start offset 12345 (time 191.59) coalescence time 192.9
  Normalization: S/N=1 at 132.47 kpc
  Linear combination of max SNR: 0.9953 x phase_0 + 0.0973 x phase_pi/2
  POSSIBLE CHIRP! with > 1% probability (p=0.949737).
  Distribution: s= 22, N>3s= 28 (expect 176), N>5s= 0 (expect 0)
  Distribution does not appear to have outliers...

Max SNR: 14.86 (offset 12345) variance 0.801640
  If impulsive event, offset 25860 or time 198.13
  If inspiral, template start offset 12345 (time 196.76) coalescence time 198.1
  Normalization: S/N=1 at 127.90 kpc
  Linear combination of max SNR: 0.9993 x phase_0 + -0.0372 x phase_pi/2
  POSSIBLE CHIRP! with > 1% probability (p=0.999236).
  Distribution: s= 22, N>3s= 35 (expect 176), N>5s= 0 (expect 0)
  Distribution does not appear to have outliers...
...
```

The code is correctly finding the chirps, getting the distance and phase and time location of the chirps about as accurately as one would expect given the level of the IFO noise.

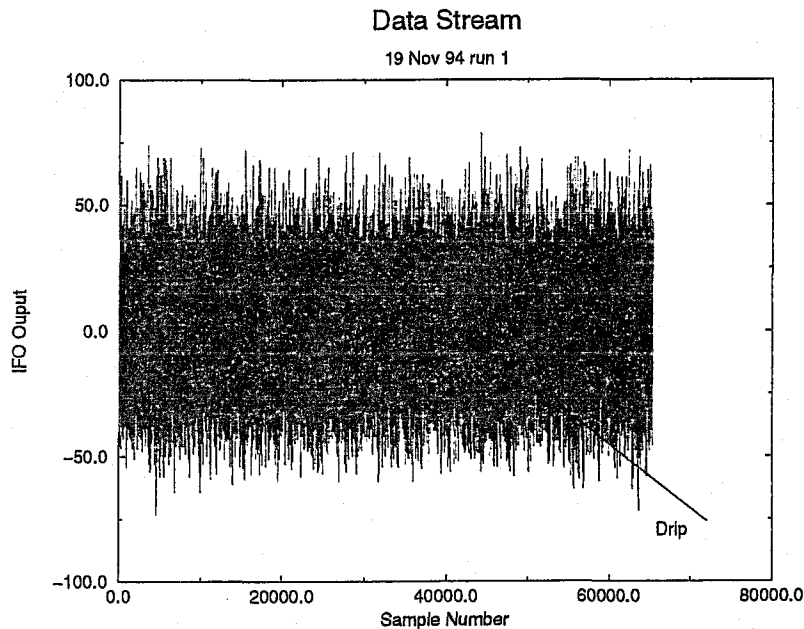


Figure 27: This shows the event that triggered the  $2 \times 1.4$  solar mass binary inspiral filter with a SNR of 8.71 (see the first set of sample output from the optimal filtering code above, at time 325.23). This same “event” can also be seen in Figure 7. The horizontal axis is sample number, with samples  $\approx 10^{-4}$  seconds apart; the vertical axis is the raw (whitened) IFO output. The event labeled “drip” can be heard in the data (it sounds like a faucet drip) and is picked up by the optimal filtering technique, but it is NOT visible to the naked eye. This event is vetoed by the splitup technique described earlier - it has extremely low probability of being a chirp plus stationary noise.

There are several interesting lessons that one can learn from this optimal filtering experience. The first is that (roughly speaking) the events that trigger an optimal filter (driving the output to a value much larger than would be expected for a colored-noise Gaussian input) can be broken into two classes: those which can be seen in the raw data stream, and those which can not. Here, by “seen in the raw data stream”, we mean “visible to the naked eye upon examination of a graph”. Shown in the following two figures are examples of each type of spurious event.

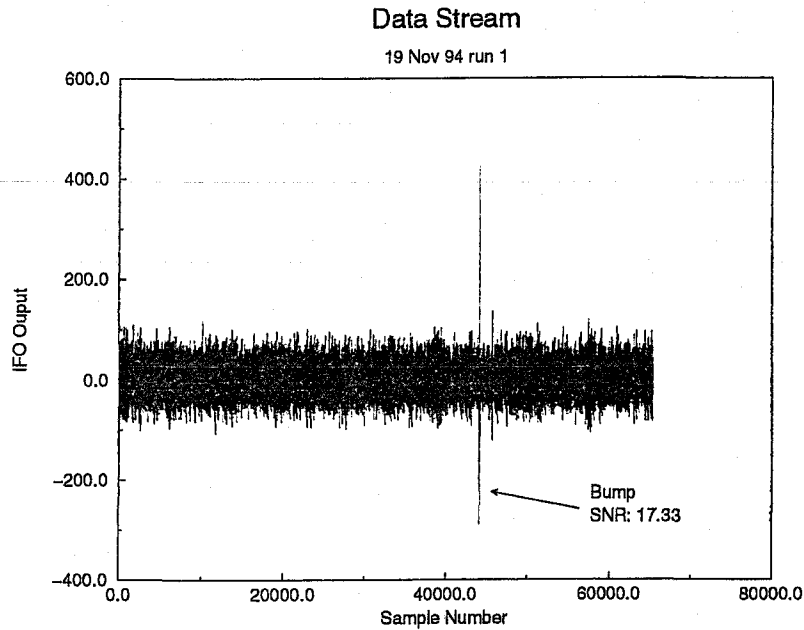


Figure 28: This another event that triggered the  $2 \times 1.4$  solar mass binary inspiral filter with a SNR of 17.33. This event sounds like a “bump”; it is probably due to a bad cable connection. It can be easily seen (and vetoed) in the time domain. A close-up of this is shown in the next figure.

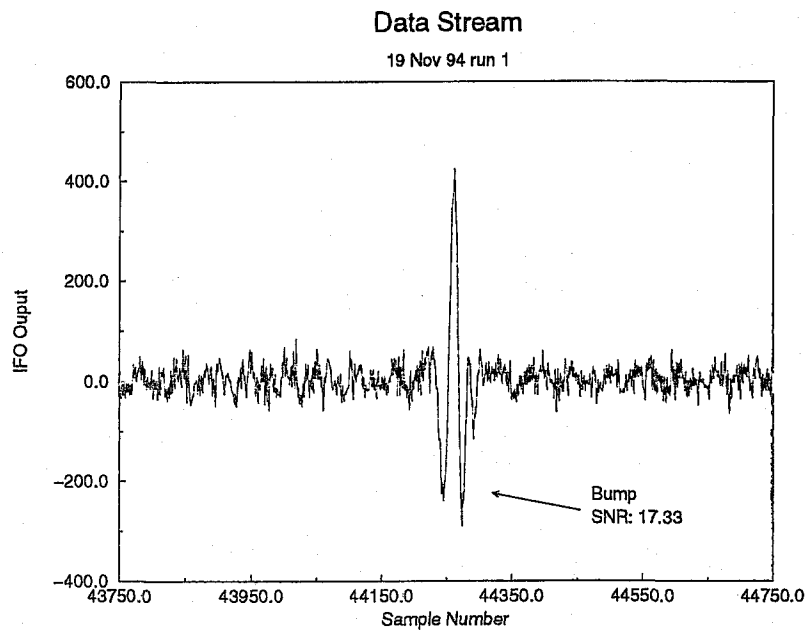


Figure 29: A close-up of the previous graph, showing the structure of the “bump”.

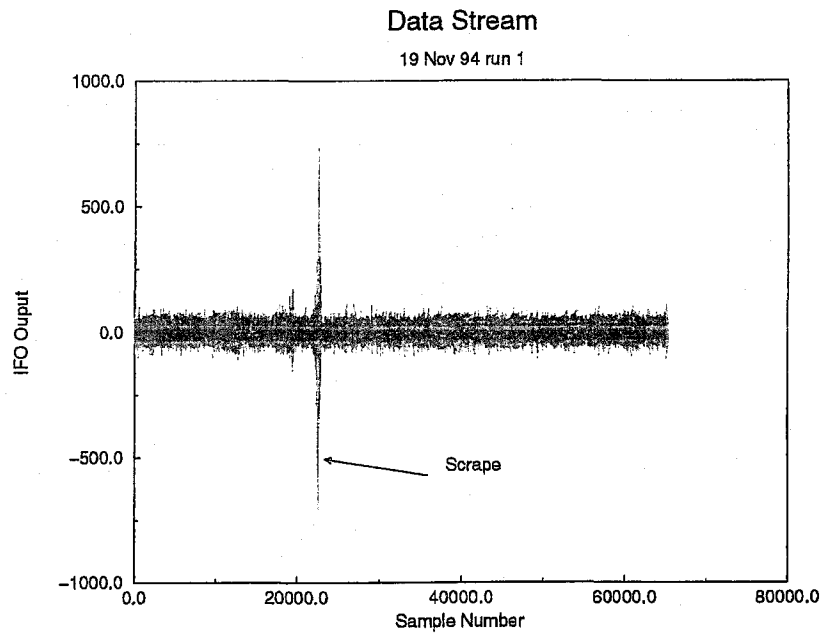


Figure 30: This another event that triggered the  $2 \times 1.4$  solar mass binary inspiral filter with a SNR of 32.77. This event sounds like a shovel scraping on the ground; its origin is unknown. It can be easily seen (and vetoed) in the time domain.

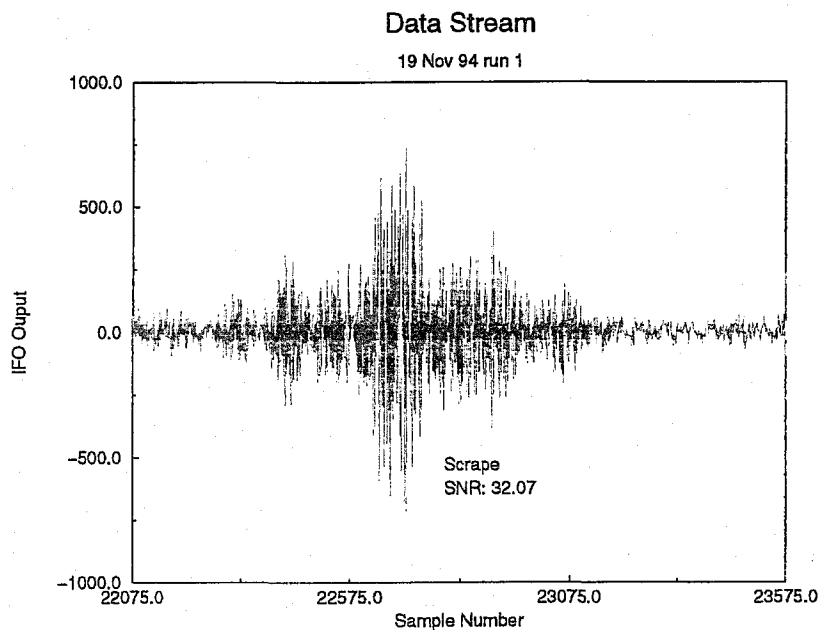


Figure 31: A close-up of the previous graph, showing the structure of the “scrape”.

## 5.28 Structure: struct Template

The structure used to describe the “chirp” signals from coalescing binary systems is: struct Template {

int num: In order to deal with templates “wholesale” it is useful to number them. The numbering system is up to you; we typically give each template a number, starting from 0 and going up to the number of templates minus one!

float f\_lo: This is the starting (low) frequency  $f_0$  of template, in units of  $\text{sec}^{-1}$ .

float f\_hi: This is the ending (high) frequency of the template, in units of  $\text{sec}^{-1}$

float tau0: The Newtonian time  $\tau_0$  to coalescence, in seconds, starting from the moment when the frequency of the waveform is f\_lo.

float tau1: First post-Newtonian correction  $\tau_1$  to  $\tau_0$ .

float tau15: 3/2 PN correction

float tau20: second order PN correction

float pha0: Newtonian phase to coalescence, radians

float pha1: First post-Newtonian correction to pha0

float pha15: 3/2 PN correction

float pha20: second order PN correction

float mtotal: total mass  $m_1 + m_2$ , in solar masses

float mchirp: chirp mass  $\mu\eta^{-2/5}$ , in solar masses

float mred: the reduced mass  $\mu = m_1 m_2 / (m_1 + m_2)$ , in solar masses

float eta: reduced mass/total mass  $\eta = m_1 m_2 / (m_1 + m_2)^2$ , dimensionless

float m1: the smaller of the two masses, in solar masses.

float m2: the larger of the two masses, in solar masses.

};

One may use the technique of *matched filtering* to search for chirps. The (noisy) signal is compared with templates, each formed from a chirp with a particular values of  $m_1$ ,  $m_2$ , and a “start frequency”  $f_0$  of the waveform at the time that it enters the bandpass of the gravitational wave detector. Several theoretical studies [4, 5] have shown how the template filtering technique performs when the detector is not ideal, but is contaminated by instrument noise.

In the presence of detector noise, one can never be entirely certain that a given chirp (determined by  $m_1, m_2$ ) will be detected by a particular template, even one with the exact same mass parameters. However one can make statistical statements about a template, such as “if the masses  $m_1$  and  $m_2$  of the chirp lie in region  $R$  of parameter space, then with 97% probability, they will be detected if their amplitude exceeds value  $h$ ”. Thus, associated with each chirp, and a specified level of uncertainty, is a region of parameter space.

It turns out that if we use the correct choice of coordinates on the parameter space  $(m_1, m_2)$  then these regions  $R$  are quite simple. If we demand that the uncertainty associated with each template be fairly small, then these regions are ellipses. Moreover, to a good approximation, the shape of the ellipses is determined only by the noise power spectrum of the detector, and does not change significantly as we move about in the parameter space. These “nice” coordinates  $(\tau_0, \tau_1)$  have units of time, and are defined by

$$\begin{aligned}\tau_0 &= \frac{5}{256} \left( \frac{GM}{c^3} \right)^{-5/3} \eta^{-1} (\pi f_0)^{-8/3} \\ &= \frac{5}{256} \left( \frac{M}{M_\odot} \right)^{-5/3} \eta^{-1} (\pi f_0)^{-8/3} T_\odot^{-5/3}\end{aligned}\quad (5.28.1)$$

and

$$\begin{aligned}\tau_1 &= \frac{5}{192} \left( \frac{c^3}{G\eta M} \right) \left( \frac{743}{336} + \frac{11}{4}\eta \right) (\pi f_0)^{-2} \\ &= \frac{5}{192} \left( \frac{M_\odot}{M} \right) \left( \frac{743}{336}\eta^{-1} + \frac{11}{4} \right) (\pi f_0)^{-2} T_\odot^{-1}.\end{aligned}\quad (5.28.2)$$

The symbol

$$M \equiv m_1 + m_2 \quad (5.28.3)$$

denotes the total mass of the binary system, and

$$\eta \equiv \frac{m_1 m_2}{(m_1 + m_2)^2} \quad (5.28.4)$$

is the ratio of the reduced mass to  $M$ . Notice that  $\eta$  is always (by definition) less than or equal to  $1/4$ .

We are generally interested in a region of parameter space corresponding to binary systems, each of whose masses lie in some given range, say from  $1/2$  to  $3$  solar masses. The region of parameter space is determined by a minimum and maximum mass; we show an example of this in Figure 32. Since we may

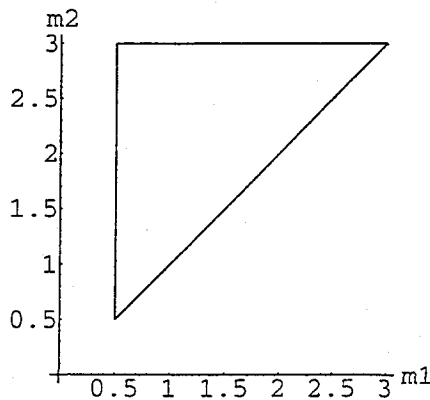


Figure 32: The set of binary stars with masses lying between set minimum and maximum values defines the interior of a triangle in parameter space

take  $m_2 \leq m_1$  without loss of generality, the region of interest is triangular rather than rectangular. The three lines on this diagram are:



(1) The equal mass line. Along this line  $\eta = 1/4$ .

(2) The minimum mass line. Along this line, one of the masses has its smallest value.

(3) The maximum mass line. Along this line, one of the masses has its largest value.

This triangular region is mapped into the  $(\tau_0, \tau_1)$  plane as shown in Figure 33. In this diagram, the lower curve  $\tau_1 \propto \tau_0^{3/5}$  is the equal mass line (1). The upper curve, to the right of the "kink" is the minimum mass line (2). The upper curve, to the left of the "kink" is the maximum mass line (3).

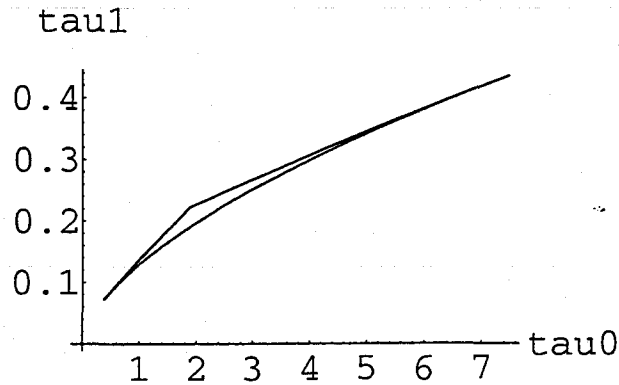


Figure 33: The triangular region of the previous figure is mapped into a distorted triangle in the  $(\tau_0, \tau_1)$  plane. Here  $f_0$  is 120 Hz.

## 5.29 Structure: struct Scope

The set of templates is described by a structure `struct Scope`. This structure specifies a set of templates covering the mass range in parameter space described above and shown in Figure 33. The fields of this structure are:

```
struct Scope {  
  
    int n_tmplt: This integer is the total number of templates needed to cover the region in parameter  
                space. This is typically computed or set by template_grid().  
  
    float m_mn: The minimum mass of an object in the binary system, as described above, in solar masses.  
  
    float m_mx: The maximum mass of an object in the binary system, as described above, in solar masses.  
                Together with the m_mn, this describes the region in parameter space covered by the set of templates.  
  
    float theta: The angle to the axis of the constant ambiguity ellipse whose axis has diameter dp. The  
                angle is measured in radians counterclockwise from the  $\tau_0$  axis. The range is  $\theta \in (-\pi/2, \pi/2)$ .  
  
    float dp: The diameter along the ellipse (in sec). This is twice the radius  $r_1$  given in Table 7. The  
              angle  $\theta$  is measured to this axis.  
  
    float dq: The diameter along the ellipse (in sec). This is twice the radius  $r_2$  given in Table 7.  
  
    float f_start: The frequency  $f_0$  used in the definitions of  $\tau_0$  and  $\tau_1$  (5.28.1, 5.28.2); this is typically  
                  the frequency at which a binary chirp first enters the usable bandpass of the detector.  
  
    struct Template* templates: Pointer to the array of templates. This pointer is typically set by  
                                template_grid(), when it allocates the memory necessary to store the templates, and creates the  
                                necessary templates.  
  
};
```

Note that a given constant ambiguity ellipse can be specified in either of two equivalent ways. For example the ellipse defined by

$$\theta = \pi/4, dp = 1 \text{ msec}, dq = 5 \text{ msec} \quad (5.29.1)$$

is completely equivalent to the ellipse

$$\theta = 5\pi/4, dp = 5 \text{ msec}, dq = 1 \text{ msec}. \quad (5.29.2)$$

Either of these is acceptable. The literature frequently uses the second convention (angle measured to the major axis).

### 5.30 Function: tau\_of\_mass()

```
void tau_of_mass(double m1, double m2, double pf, double *tau0, double *tau1)
```

This function calculates the coordinates  $(\tau_0, \tau_1)$  associated with particular values of the masses of the objects in the binary system, and a particular value of frequency  $f_0$ .

The arguments are:

m1: Input. The first mass (in solar masses).

m2: Input. The second mass (in solar masses).

pf: Input. The value  $\pi f_0$ . Here  $f_0$  is the frequency used in defining the  $\tau$  coordinates (see below). It is often chosen to be at (or below) the frequency at which the chirp first enters the bandpass of the gravitational wave detector.

tau0: Output. Pointer to  $\tau_0$  (in seconds).

tau1: Output. Pointer to  $\tau_1$  (in seconds).

Although one can think of  $\tau_0$  and  $\tau_1$  as coordinates in the parameter space defined by (5.28.1) and (5.28.2) they have simple physical meanings.  $\tau_0$  is the time to coalescence of the binary system, measured from the time that the waveform passes through frequency  $f_0$ , in the zeroth post-Newtonian approximation.  $\tau_1$  is the first-order post-Newtonian correction to this quantity, so that to this order the time to coalescence is  $\tau_0 + \tau_1$ .

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Comments: None.

### 5.31 Function: `m_and_eta()`

`int m_and_eta(double tau0, double tau1, double *M, double *eta, double Mmin, double Mmax, double pf)`

This function takes as inputs the coordinates  $(\tau_0, \tau_1)$ . If these correspond to individual masses  $m_1$  and  $m_2$  each lying in the range from  $M_{\min}$  to  $M_{\max}$  then the function sets the total mass  $M = m_1 + m_2$  and sets  $\eta = m_1 m_2 / (m_1 + m_2)^2$  and returns the value 1. Otherwise, the function returns 0 and does not change the values of mass  $M$  or  $\eta$ .

The arguments are:

`tau0` Input. The value of  $\tau_0$  (positive, sec).

`tau1` Input. The value of  $\tau_1$  (positive, sec).

`M` Output. The total mass  $M$  (solar masses). Unaltered if no physical mass values are found in the desired range.

`eta` Output. The value of  $\eta$  (dimensionless). Unaltered if no physical mass values are found in the desired range.

`Mmin` Input. Minimum mass of one object in the binary pair, in solar masses (positive).

`Mmax` Input. Maximum mass of one object in the binary pair, in solar masses (positive).

`pf`: Input. The value  $\pi f_0$ . Here  $f_0$  is the frequency at which the chirp first enters the bandpass of the gravitational wave detector.

The algorithm followed by `m_and_eta()` is as follows. Eliminate  $\eta$  from the equations defining  $\tau_0$  (5.28.1) and  $\tau_1$  (5.28.2) to obtain the following relation:

$$c_1 + c_2 \left( \frac{M}{M_\odot} \right)^{5/3} - c_3 \left( \frac{M}{M_\odot} \right) = 0, \quad (5.31.1)$$

with the constants given by:

$$\begin{aligned} c_1 &= 1155 T_\odot \\ c_2 &= 47552 (\pi f_0 T_\odot)^{8/3} \tau_0 \\ c_3 &= 16128 (\pi f_0 T_\odot)^2 \tau_1. \end{aligned} \quad (5.31.2)$$

Given  $(\tau_0, \tau_1)$  our goal is to find the roots of equation (5.31.1). It is easy to see that the function on the lhs of (5.31.1) has at most two roots. The function is positive at  $M = 0$  but decreasing for small positive  $M$ . However it is positive and increasing again as  $M \rightarrow \infty$ . Hence the function on the lhs of (5.31.1) has at most a single minimum for  $M > 0$ . Setting the derivative equal to zero and solving, this minimum lies at a value of the total mass  $M_{\text{crit}}$  which satisfies

$$\frac{M_{\text{crit}}}{M_\odot} = \left( \frac{3}{5} \frac{c_3}{c_2} \right)^{3/2} \quad (5.31.3)$$

Hence the lhs of (5.31.1) has no roots if its value is positive at  $M = M_{\text{crit}}$  or it has two roots if that value is negative. (The "set of measure zero" possibility is a single root at  $M_{\text{crit}}$ .)

If  $2M_{\min} < M_{\text{crit}} < 2M_{\max}$  then `m_and_eta()` searches for roots  $2M_{\min} < M < M_{\text{crit}}$  and  $M_{\text{crit}} < M < 2M_{\max}$  separately, else it looks for a root  $M$  in the range  $2M_{\min} < M < 2M_{\max}$ . If the lhs of (5.31.1)

changes sign at the upper and lower boundaries of the interval, then a double-precision routine, similar to the *Numerical Recipes* routine `rtsafe()`, is used to obtain the root with a combination of “safe” bisection and “rapid” Newton-Raphson.

If a root  $M$  is found in the desired range, then  $\eta$  is determined by (5.28.1) to be

$$\eta = \frac{5}{256} \left( \frac{M}{M_{\odot}} \right)^{-5/3} (\pi f_0 T_{\odot})^{-8/3} \frac{T_{\odot}}{\tau_0} \quad (5.31.4)$$

If  $\eta \leq 1/4$  then the smaller and larger masses are calculated from

$$m_1 = \frac{M}{2} (1 - \sqrt{1 - 4\eta}) \quad m_2 = \frac{M}{2} (1 + \sqrt{1 - 4\eta}). \quad (5.31.5)$$

(If both roots for  $M$  correspond to  $\eta \leq 1/4$  then an error message is generated and the routine aborts.) If both  $m_1$  and  $m_2$  are in the desired range  $M_{\min} < m_1, m_2 < M_{\max}$  then `m_and_eta()` returns 1 and sets  $M$  and  $\eta$  appropriately, else it returns 0, leaving  $M$  and  $\eta$  unaffected.

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Comments: Although the arguments to this function are double precision floats, the values of  $m_1$  and  $m_2$  that may be inferred from them can generally only be determined to single precision, particularly in the neighborhood of  $m_1 = m_2$ . The reason is that in the vicinity of  $\eta \sim 1/4$ , a fractional error  $\epsilon$  in the value of  $\eta$  produces a fractional error  $\sqrt{\eta}$  in the masses.

### 5.32 Function: `tauspace_area()`

`float tauspace_area(struct Scope *Grid)`

This function computes the area of the enclosed region of parameter space shown in Figure 33.

The arguments are:

**Grid:** Input. This function uses only the minimum mass, maximum mass and the cut-off frequency  $f_0$  fields of `Grid`.

The function returns the numerical value of the area in units of  $\text{sec}^2$ . See the example in the following subsection.

The function uses an analytic expression for the area obtained by integration of formulae (5.28.1, 5.28.2) for  $\tau_0$  and  $\tau_1$  given earlier. For example, to obtain the area of the trapezoidal region bounded above by the maximum-mass curve and below by the  $\tau_0$  axis, we integrate

$$\begin{aligned}
 A_1 &= \int_{m_{\max}}^{m_{\min}} \tau_1(m_{\min}, m) \frac{d\tau_0(m_{\min}, m)}{dm} dm \\
 &= A_0 \left[ \frac{m_{\min}}{M_{\odot}} \right]^{8/3} \left\{ \frac{-[3 + 2(4 + 2a)u + (5 + 9a)u^2]}{2u^2(1 + u)^{2/3}} \right. \\
 &\quad + \frac{9a - 1}{\sqrt{3}} \arctan \left[ \frac{1 + 2(1 + u)^{1/3}}{\sqrt{3}} \right] \\
 &\quad \left. + \frac{9a - 1}{6} \log \left[ \frac{1 + (1 + u)^{1/3} + (1 + u)^{2/3}}{1 - 2(1 + u)^{1/3} + (1 + u)^{2/3}} \right] \right\}_{u=m_{\min}/m_{\max}}^{u=1}
 \end{aligned}$$

Here  $a = 924/743$  and  $A_0$  is a quantity with dimensions  $\text{sec}^2$  given by

$$A_0 = \frac{18575}{49545216} \frac{M_{\odot}^2}{(\pi M_{\odot} f_0)^{14/3}} \left( \frac{c^3}{G} \right)^{8/3}$$

The area  $A_2$  under the minimum-mass curve can be obtained from the formula above by interchanging  $m_{\min}$  and  $m_{\max}$ . (If you wish to use geometrized units in which the solar mass is  $4.92 \times 10^{-6}$  sec simply set  $G = c = 1$ .) The area under the equal-mass curve  $A_3$  can be obtained by performing a similar integration along the equal-mass curve

$$\begin{aligned}
 A_3 &= \int_{m_{\max}}^{m_{\min}} \tau_1(m, m) \frac{d\tau_0(m, m)}{dm} dm \\
 &= \frac{60875}{2064384} \frac{M_{\odot}^2}{(\pi f_0 M_{\odot})^{14/3}} \left[ \left( \frac{M_{\odot}}{m_{\min}} \right)^{8/3} - \left( \frac{M_{\odot}}{m_{\max}} \right)^{8/3} \right] \left( \frac{c^3}{G} \right)^{8/3}
 \end{aligned}$$

These three results can be combined to give the total area enclosed

$$A_{\text{total}} = A_1 + A_2 - A_3 . \tag{5.32.1}$$

Equation (5.32.1) is the basis of `tauspace_area()`; the next example shows an application of this function.

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Comments: None.

### 5.33 Example: area program

This example uses the function `tauspace_area()` described in the previous section to compute the area of the specified parameter space. The parameters specifying the region are set: the minimum and maximum mass in solar masses and the cut off frequency in seconds<sup>-1</sup>. The numerical value of the area is returned and printed.

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

int main() {
    struct Scope Grid;
    float area;
    float template_area(struct Scope *);

    /* Specify the parameter space */
    Grid.m_mn=0.8;
    Grid.m_mx=50.0;
    Grid.f_start=140.0;

    /* find area of parameter space */
    area=template_area(&Grid);

    /* and print it */
    printf("The area in parameter space is %f seconds^2.\n",area);
    return 0;
}
```

### 5.34 The match between two templates

When one performs a search for a gravitational wave signal in noisy instrumental data, one lays a grid of templates out in parameter space. For instance, if one uses  $\tau_0$  and  $\tau_1$  [see Eqs. (5.28.1) and (5.28.2)] as parameter space coordinates, then one's templates can be described as a set of points  $(\tau_0^i, \tau_1^i)$  (with  $i$  ranging from 1 to the total number of templates). One requires these points to be spaced such that no more than some *a priori* fraction of SNR is lost due to the discreteness of the template family.

Suppose one has decided that a set templates can lose no more than 3% SNR in a search. This means that if some arbitrary signal  $b(t)$  is dropped onto the template grid, there must exist a template,  $a(t)$ , such that

$$\max_{t_0} \int_{-\infty}^{\infty} df \frac{\bar{b}(f)\bar{a}^*(f)}{S_h(f)} e^{-2\pi i f t_0} \geq .97 \left[ \int_{-\infty}^{\infty} df \frac{|\bar{b}(f)|^2}{S_h(f)} \right]^{1/2} \left[ \int_{-\infty}^{\infty} df \frac{|\bar{a}(f)|^2}{S_h(f)} \right]^{1/2} \quad (5.34.1)$$

("max  $t_0$ " indicates the integral on the left hand side is to be maximized over all possible values of  $t_0$ .) The integral on the left is the SNR obtained when the signal  $b(t)$  is measured using the Wiener optimal filter corresponding to the template  $a(t)$ . The first integral on the right is the SNR obtained when  $b(t)$  is measured with the Wiener optimal filter corresponding to a template  $b(t)$ ; the second when the signal and template are both  $a(t)$ . (The integrals on the right hand side, in other words, describe the situation in which the template exactly matches the signal). For a detailed discussion of Wiener filtering, see Section 5.14.

To simplify this discussion, let us introduce the following inner product:

$$\langle a, b \rangle_{t_0} \equiv \int_{-\infty}^{\infty} df \frac{\bar{a}(f)\bar{b}(f)}{S_h(f)} e^{-2\pi i f t_0}. \quad (5.34.2)$$

[Note: this inner product is not to be confused with the inner product  $(a, b)$  defined in Eq. (5.14.9).] We will use the convention that not including the  $t_0$  subscript on the angle bracket is equivalent to  $t_0 = 0$ . Eq. (5.34.1) can now be rewritten

$$\max_{t_0} \langle a, b \rangle_{t_0} \geq .97 \sqrt{\langle a, a \rangle \langle b, b \rangle}. \quad (5.34.3)$$

This motivates the definition of the *match* between  $a(t)$  and  $b(t)$ :

$$\mu \equiv \max_{t_0} \frac{\langle a, b \rangle_{t_0}}{\sqrt{\langle a, a \rangle \langle b, b \rangle}}. \quad (5.34.4)$$

The match can be thought of as a distance measure between  $a(t)$  and  $b(t)$  (it is in fact one of the starting points for the metric that Owen defines in [5]). One uses the match function as a means of determining how one must space templates on the parameter space. If one requires that no more than 3% of possible SNR be lost due to template discreteness, then one must require adjacent templates to have a match  $\mu = .97$ .

The next few functions described in this manual are tools that can be used for calculating the match function and understanding how it varies over one's parameter space.



### 5.35 Function: `compute_match()`

```
float compute_match(float m1, float m2, float ch0tilde[], float ch90tilde[],
float inverse_distance_scale, float twice_inv_noise[], float flo, float s_n0,
float s_n90, int npoint, float srate, int err_cd_sprs, int order)
```

This function computes and returns the match function between a binary inspiral template that is stored in the arrays `ch0tilde[]` and `ch90tilde` and the binary inspiral template that corresponds to the binary system whose bodies have masses `m1` and `m2`.

The two phases of the “reference chirp”, `ch0tilde[]` and `ch90tilde[]`, are assumed to have been precomputed and run through the function `orthonormalize()`. (The parameters `s_n0` and `s_n90` are assumed to have been found when the reference chirp was orthonormalized.) This allows efficient computation of the match of many different templates with the reference chirp.

The arguments to the function are:

`m1`: Input. Mass of body 1 in the template that is cross-correlated with the reference chirp, solar masses.

`m2`: Input. Mass of Body 2 in the template, solar masses.

`ch0tilde`: Input. The FFT of the 0°-phase reference chirp.

`ch90tilde`: Input. The FFT of the 90°-phase reference chirp.

`inverse_distance_scale`: Input. The inverse distance to the binary system, in 1/Mpc. Because the match is a normalized correlation, this parameter isn't physically relevant: moving the binary twice as far from the earth has no effect on the match. However, it may be computationally convenient to scale the inner products that go into the match definition by some amount to prevent numerical error.

`twice_inv_noise`: Input. Twice the inverse noise power spectrum, used for optimal filtering. For a more detailed description, see the routine `find_chirp()` (which is used within `compute_match()`).

`flo`: Input. The low-frequency cutoff to impose, in Hz. Within the code, this is used as the starting frequency of the templates; see `make_filters()`.

`s_n0`: Input. The normalization of `ch0tilde[]`, found using `orthonormalize()`.

`s_n90`: Input. The normalization of `ch90tilde[]`, found using `orthonormalize()`. Note that only the ratio `s_n0/s_n90` is physically relevant, because the match is normalized; if both `s_n0` and `s_n90` are multiplied by some constant, the match is unaffected.

`npoint`: Input. Defines the lengths of the various arrays: `ch0tilde[0..npoint-1]`, `ch90tilde[0..npoint-1]`, `twice_inverse_noise[0..npoint/2]`.

`srate`: Input. The sampling rate, in Hz. Used to convert between integer array time-domain subscripts and frequency subscripts. For example this is the sample rate of the 0°- and 90°-phase reference chirps, before they are FFT'd.

`err_cd_sprs`: Input. The error suppression code to be passed to the chirp generator; see `chirp_filters()`.

`order`: Input. Twice the post-Newtonian order; *i.e.*, the power of  $(v/c)$  used in the expansion. See `chirp_filters()`.

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### 5.36 Function: match\_parab()

```
int match_parab(float m1ref, float m2ref, float matchcont, int order, float
srate, float flo, float ftau, char *noisefile, float *semimajor, float *semimino,
float *theta, float mcoef[])
```

This function attempts to find a parabolic fit to the match function near a reference template with masses (m1ref, m2ref). It works in  $(\tau_0, \tau_1)$  coordinates, and can use any noise curve listed in detectors.dat for its inner products when computing the match.

Let the coordinates of the reference chirp be  $(\tau_0^r, \tau_1^r)$ , and define  $x \equiv \tau_0 - \tau_0^r, y \equiv \tau_1 - \tau_1^r$ . Then, the fit to the match is of the form

$$\begin{aligned}\mu &= 1 + ax^2 + 2bxy + cy^2 \\ &= 1 + (x \ y) \cdot \begin{pmatrix} a & b \\ b & c \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}.\end{aligned}\quad (5.36.1)$$

Written in the form on the second line, it is easy to show that, if the match is in fact parabolic, it has surfaces of constant value that are ellipses. The (unnormalized) eigenvectors of this matrix are given by

$$\begin{aligned}\vec{v}_0 &= \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} (a-c)/2b + \sqrt{[(a-c)/2b]^2 + 1} \\ 1 \end{pmatrix} \\ \vec{v}_1 &= \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} (a-c)/2b - \sqrt{[(a-c)/2b]^2 + 1} \\ 1 \end{pmatrix},\end{aligned}\quad (5.36.2)$$

and the eigenvalues are

$$\begin{aligned}\lambda_0 &= \frac{1}{2}(a+c) + \sqrt{\frac{1}{4}(a-c)^2 + b^2} \\ \lambda_1 &= \frac{1}{2}(a+c) - \sqrt{\frac{1}{4}(a-c)^2 + b^2}.\end{aligned}\quad (5.36.3)$$

(Note: because the match is maximal at  $x = y = 0$  and falls off as  $x$  and  $y$  increase, the matrix is negative definite. The eigenvalues are therefore negative, and so  $|\lambda_1| > |\lambda_0|$ .) From these values, it is simple to construct the equimatch ellipse. If the value of the match on the contour is  $\mu_{\text{cont}}$ , then the semimajor axis of the ellipse has length

$$r_{\text{major}} = \sqrt{\frac{\mu_{\text{cont}} - 1}{\lambda_0}},\quad (5.36.4)$$

and the semiminor axis has length

$$r_{\text{minor}} = \sqrt{\frac{\mu_{\text{cont}} - 1}{\lambda_1}}.\quad (5.36.5)$$

The counterclockwise angle between the semimajor axis and the  $\tau_0$  axis is easily found from  $\vec{v}_0$ :

$$\theta = \text{atan2}(v_{0y}, v_{0x}) = \arctan\left(1 / \left[(a-c)/2b + \sqrt{[(a-c)/2b]^2 + 1}\right]\right).\quad (5.36.6)$$

(Here,  $\text{atan2}()$  is the C math library function; using  $\text{atan2}()$  insures that the computer points  $\theta$  to the correct quadrant of the  $\tau_0, \tau_1$  plane.) If we now define normalized eigenvectors  $\vec{e}_0 = \vec{v}_0/|\vec{v}_0|, \vec{e}_1 = \vec{v}_1/|\vec{v}_1|$ , the ellipses are then easily constructed using the parametric curve

$$\begin{pmatrix} x \\ y \end{pmatrix} = r_{\text{major}} \cos \phi \vec{e}_0 + r_{\text{minor}} \sin \phi \vec{e}_1,\quad (5.36.7)$$

with  $\phi$  varying from 0 to  $2\pi$ .

The arguments to the function are:

`m1ref`: Input. Mass of body 1 for the reference chirp (solar masses).

`m2ref`: Input. Mass of body 2 for the reference chirp (solar masses).

`matchcont`: Input. The value of the match contour.

`order`: Input. Twice the post-Newtonian order to be used in computing the templates; *i.e.*, the power of  $(v/c)$  used in the post-Newtonian expansion.

`srate`: Input. The sample rate, in Hz. Used to convert between integer array time-domain subscripts and frequency subscripts. For example this is the sample rate of the  $0^\circ$ - and  $90^\circ$ -phase reference chirps, before they are FFT'd.

`flo`: Input. The low-frequency cutoff to impose, in Hz. Within the code, this is used as the starting frequency of the templates; see `make_filters()`.

`ftau`: Input. The frequency used to find  $\tau_0$  and  $\tau_1$ ; see Eqs. (5.28.1) and (5.28.2). Different authors use different conventions for this frequency—for example, Sathyaprakash uses the seismic wall frequency, whereas Owen uses the frequency at which the noise power is minimum. `ftau` is arbitrary, but should be used consistently: pick a value and stick with it.

`noisefile`: Input. A character string that specifies the name of a data file containing information about the noise power spectrum  $P(f)$  of a detector. See `noise_power()` for extended discussion.

`semimajor`: Output. The semimajor axis of the ellipse along which the match has the value `matchcont`.

`semiminor`: Output. The semiminor axis of the ellipse.

`theta`: Output. The counterclockwise angle, in radians, between `semimajor` and the  $\tau_0$  axis.

`mcoef`: Output. The array `mcoef[0..2]` contains the coefficients of the parabolic fit to the match:  
$$\mu_{\text{fit}} = 1 + \text{mcoef}[0]x^2 + \text{mcoef}[1]xy + \text{mcoef}[2]y^2.$$

The function works by sampling many templates in  $(\tau_0, \tau_1)$  coordinates that are close to the template with masses  $(m1ref, m2ref)$ . Periodically, it computes the best parabolic fit to the data it has gathered so far and constructs the elliptical contour corresponding to that fit. It then takes  $N_{\text{ell}}$  steps around this ellipse and compares the value of the match predicted by the fit with the actual match value at each point. It then computes the following “ $\chi^2$ -like” statistic:

$$\varepsilon = \frac{1}{N_{\text{ell}}} \sum_{i=1}^{N_{\text{ell}}} \left( \frac{\mu_{\text{actual}}^i - \mu_{\text{fit}}^i}{10^{-3}} \right)^2. \quad (5.36.8)$$

If  $\varepsilon = 1$ , then each fit point differs from the match by  $10^{-3}$ . A “good” fit will have  $\varepsilon$  of order 1.

This function returns 0 if a good fit is not found ( $\varepsilon$  is greater than 5 yet more than 250 templates have been used to generate fit data), and 1 otherwise. If a good fit is not found, then the match is not parabolic in the vicinity of the template  $(m1ref, m2ref)$  down to  $\mu = \text{matchcont}$ . This is typically the case if the masses are large (so that there are few cycles measured, and relativistic effects are very important), and if the value of `matchcont` is too far from 1. For instance, with the LIGO 40-meter prototype, `match_parab()` cannot find a parabolic fit to the .97 match contour for a binary with  $m_1 = 1.2M_\odot$ ,  $m_2 = 1.6M_\odot$ ; but it *does* find a parabolic fit for this binary at the .99 match contour.

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### 5.37 Function: `match_cubic()`

```
int match_cubic(float m1ref, float m2ref, float matchcont, int order, float
srate, float flo, float ftau, char *noisefile, float *semimajor, float *semiminor,
float *theta, float mcoef[])
```

This function is almost identical to `match_parab()`, except that it attempts to fit the match to a cubic form:

$$m = 1 + ax^2 + 2bxy + cy^2 + dx^3 + ey^3 + fx^2y + gxy^2 \quad (5.37.1)$$

The arguments to the function are:

`m1ref`: Input. Mass of body 1 for the reference chirp (solar masses).

`m2ref`: Input. Mass of body 2 for the reference chirp (solar masses).

`matchcont`: Input. The value of the match contour.

`order`: Input. Twice the post-Newtonian order to be used in computing the templates; *i.e.*, the power of  $(v/c)$  used in the post-Newtonian expansion.

`srate`: Input. The sample rate, in Hz. Used to determine the spacing of frequency bins for the templates.

`flo`: Input. The low-frequency cutoff to impose, in Hz. Within the code, this is used as the starting frequency of the templates; see `make_filters()`.

`ftau`: Input. The frequency used to find  $\tau_0$  and  $\tau_1$ ; see Eqs. (5.28.1) and (5.28.2). Different authors use different conventions for this frequency—for example, Sathyaprakash uses the seismic wall frequency, whereas Owen uses the frequency at which the noise power is minimum. `ftau` is arbitrary, but should be used consistently: pick a value and stick with it.

`noisefile`: Input. A character string that specifies the name of a data file containing information about the noise power spectrum  $P(f)$  of a detector. See `noise_power()` for extended discussion.

`semimajor`: Output. The semimajor axis of the ellipse along which the match has the value `matchcont`.

`semiminor`: Output. The semiminor axis of the ellipse.

`theta`: Output. The counterclockwise angle, in radians, between `semimajor` and the  $\tau_0$  axis.

`mcoef`: Output. The array `mcoef[0..6]` contains the coefficients of the parabolic fit to the match:  
$$\mu_{\text{fit}} = 1 + \text{mcoef}[0]x^2 + \text{mcoef}[1]xy + \text{mcoef}[2]y^2 + \text{mcoef}[3]x^3 + \text{mcoef}[4]y^3 + \text{mcoef}[5]x^2y + \text{mcoef}[6]xy^2.$$

The function works in almost exactly the same manner as `match_parab()`. In particular, it constructs an ellipse using the parabolic piece of the cubic fit, and checks the goodness of the fit along that ellipse. Because the ellipse is not made from the full functional form of the fit, the fit does not have constant value along the ellipse. Thus, `match_cubic()` does not really find contours with constant match value `matchcont`. The ellipses it finds, however, generally have match values fairly close to `matchcont`; and, more importantly, the match values along the ellipse are never less than `matchcont`.

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### 5.38 Example: match\_fit program

This program will try to find the fit to the match function about some template. It is called with four arguments: the mass of body 1 (in solar masses), the mass of body 2 (in solar masses), the value of the match for which it tries to fit, and (twice) the order of the post-Newtonian expansion used to compute the templates. For example, `match_fit 1.2 1.8 .98 4` will try to find a fit to the .98 match contour near the template for the  $1.2 M_{\odot} - 1.8 M_{\odot}$  using post-2-Newtonian templates.

The program first attempts to find a parabolic fit; if it is unable to do so, it then tries a cubic. If the cubic fails, you are in a region of parameter space where the match is badly behaved. This is typically the case if you ask for masses that are too large—for example, no fit can be found near a  $5 M_{\odot} - 5 M_{\odot}$  solar mass binary with the LIGO 40-meter prototype noise curve. When the masses are large, the system radiates very few gravitational-wave cycles in the instrument's frequency band; and, those cycles typically correspond to a strongly relativistic regime of inspiral. If you find yourself in this circumstance, either give up on the large mass binaries, or try to find a fit at a match level closer to 1.

```
#include "grasp.h"

#define DETECTOR_NUM 15      /* Smooth fit to Caltech 40m prototype */
#define FLO 120.            /* Hz - low frequency cut off for filtering */
#define FTAU 140.          /* Hz - frequency used in definitions of
                           tau0, tau1. */

/**define DETECTOR_NUM 8 /* Caltech 40m prototype */
/**define DETECTOR_NUM 1 /* LIGO initial interferometer */
/**define DETECTOR_NUM 12 /* LIGO Advanced interferometer */

int main(int argc, char **argv)
{
    float *pfit, *cfit, semimajor, semiminor, theta;
    float m1, m2, matchcont;
    float srate=50000;
    float site_parameters[9];
    char noise_file[128], whiten_file[128], site_name[128];
    int order, tstp, tstc;

    /* Check that the program is called with the correct number of
       arguments; print out argument information if it's not. */
    if(argc != 5) {
        fprintf(stderr, "4 Arguments: 1. Mass of body 1 (solar masses)\n");
        fprintf(stderr, "                2. Mass of body 2 (solar masses)\n");
        fprintf(stderr, "                3. Match contour match value;\n");
        fprintf(stderr, "                4. Waveform order [power of (v/c)]\n");
        fprintf(stderr, "\nExample: match_fit 1.2 1.6 .97 4\n");
        exit(0);
    }
    /* Assign arguments to variables */
    m1=atof(argv[1]);
    m2=atof(argv[2]);
    matchcont=atof(argv[3]);
    order=atoi(argv[4]);

    /* Get the file names for the desired noise curve */
    detector_site("detectors.dat", DETECTOR_NUM, site_parameters,
                 site_name, noise_file, whiten_file);

    printf("\nEvaluating templates for detector: %s using data from file: \"%s\"\n\n",
           site_name, noise_file);
}
```

```

/* Allocate memory for the coefficients used in the parabolic fits */
pfit=(float *)malloc(sizeof(float)*3);
cfit=(float *)malloc(sizeof(float)*7);

/* Try to find a parabolic fit */
tstp=match_parab(m1,m2,matchcont,order,srate,FLO,FTAU,noise_file,
                &semimajor,&semiminor,&theta,pfit);
if(tstp) {
    printf("Found a parabolic fit to the match around template with\n");
    printf("m1=%f, m2=%f.\n\n",m1,m2);
    printf("Semimajor axis of best fit ellipse:    %e ms\n",
           semimajor*1.e3);
    printf("Semiminor axis of best fit ellipse:    %e ms\n",
           semiminor*1.e3);
    printf("Angle between semimajor and tau0 axis: %f rad\n",theta);
    printf("Fit: m = 1 + %e x^2 + %e xy + %e y^2\n",
           pfit[0],pfit[1],pfit[2]);
    printf("[where x=dtau0, y=dtau1]\n");
} else
    printf("Unable to find parabolic fit.  Attempting cubic fit.\n");

/* If the parabola failed, try to find a cubic fit */
if(!tstp) {
    tstc=match_cubic(m1,m2,matchcont,order,srate,FLO,FTAU,noise_file,
                   &semimajor,&semiminor,&theta,cfit);

    if(tstc) {
        printf("Found a cubic fit to the match around template with\n");
        printf("m1=%f, m2=%f.\n\n",m1,m2);
        printf("Using ellipse constructed from parabolic part of cubic.\n");
        printf("Semimajor axis of best fit ellipse:    %e ms\n",
               semimajor*1.e3);
        printf("Semiminor axis of best fit ellipse:    %e ms\n",
               semiminor*1.e3);
        printf("Angle between semimajor and tau0 axis: %f rad\n",theta);
        printf("Fit: m = 1 + %e x^2 + %e xy + %e y^2\n",
               cfit[0],cfit[1],cfit[2]);
        printf("      + %e x^3 + %e y^3 + %e x^2 y + %e xy^2\n",
               cfit[3],cfit[4],cfit[5],cfit[6]);
        printf("[where x=dtau0, y=dtau1]\n");
    } else {
        printf("Unable to find a cubic fit.  Try looking for a match\n");
        printf("contour at smaller match value; or, give up on this\n");
        printf("mass regime.\n");
    }
}

return 0;
}

```

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### 5.39 Function: `template_grid()`

```
void template_grid(struct Scope *Grid)
```

This function evolved from `grid4.f`, a FORTRAN routine written by Sathyaprakash. This function lays down a grid of templates that cover a particular mass range (the region inside the distorted triangle shown in Figure 33).

The arguments are:

**Grid:** Input/Output. This function uses as input all of the fields of `Grid` except for `Grid.n_tmplt` and `Grid.templates`. On return from `template_grid` these latter two fields are set. The function uses `malloc()` to allocate storage space and creates in this space an array containing `Grid.n_tmplt` objects of type `Template`. If you wish to free the memory, call `free(Grid.templates)`.

It is easy to cover the parameter space shown in Figure 33 with ellipses. However each ellipse represents a filter, and filtering takes computer time and memory, so the real problem is to cover the parameter space completely, using the *smallest possible number* of templates. This is a non-trivial *packing problem*; while our solution is certainly not optimal, it is quite close.

The algorithm used to place the templates works in coordinates  $(x_0, x_1)$  which are rotated versions of  $(\tau_0, \tau_1)$ , aligned along the minor and major (or major and minor) axes of the template ellipses. The input angle `Grid.theta`, in the range  $(-\pi, \pi)$ , is the counterclockwise angle through which the  $(x_0, x_1)$  axes need to be rotated to bring them into alignment with the principal axis of the template ellipses.

Although each template is an ellipse, the problem of packing templates onto the parameter space can be more easily described in terms of a more familiar packing problem: packing pennies on the plane. One can always transform an ellipse into a circle by merely scaling one coordinate uniformly while leaving the other coordinate unchanged. So we introduce coordinates  $x_1$  along the major diameter and  $x_0$  along the minor diameter of the ellipse, and then “shrinking” the  $x_1$  coordinate by the ratio of major to minor diameters. In this way the ellipses are transformed into circles.

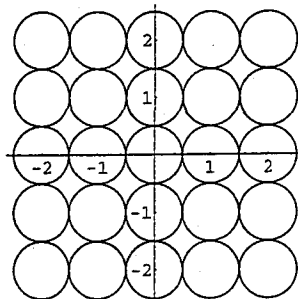


Figure 34: Covering a plane with a square lattice of pennies (or templates) leaves 21% of the area exposed

First, a template is laid down at the point where the equal mass line intersects the maximum mass line. Then additional templates are placed along the equal mass line, at increasing values of  $x_0$ . These templates are staggered up and down in the  $x_1$  direction. After laying down this set of templates, the remaining part of parameter space is covered with additional templates, in columns starting at each of the previously determined template locations. These columns have the same value of  $x_0$  as the previously determined templates but increasing values of  $x_1$ . The columns are continued until the “leading edge” of the final template lies outside the parameter space.

We can describe the packing (and the “efficiency”) of the packing in terms of the penny-packing problem. Suppose we start by setting pennies of radius  $1/2$  on all points in the plane with integer coordinates,

as shown in Figure 34. It is easy to show that the fraction of the plane (i.e., parameter space!) which is not covered by any pennies is  $\epsilon = 1 - \pi/4 = 0.214 \dots$  or about 21%.

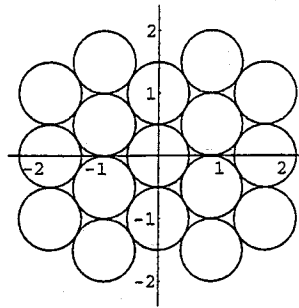


Figure 35: Staggering the pennies (or templates) decreases the uncovered fraction of the plane to 9.3%

Now suppose that we “stagger” the pennies as shown in Figure 35. In this case, the fraction of area not covered is  $\epsilon = 1 - \frac{\pi}{2\sqrt{3}} = 0.093 \dots$  or about 9.3%. If we wish to completely cover the missing bits of the plane, then we can do so by increasing the radius of each penny by  $\sqrt{5/4}$  (or, equivalently, by moving the points at which the pennies lie closer together by that same factor). The resulting diagram is shown in Figure 36. By increasing the number-density of pennies on the plane by 25% we have successfully covered up the remaining 9.3% of the area.

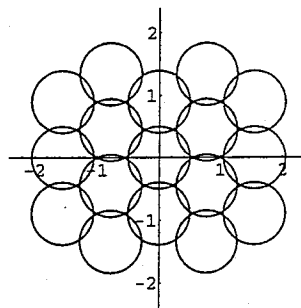


Figure 36: Decreasing the spacings of the pennies (or templates) by a factor of  $(5/4)^{1/2} = 1.118 \dots$  then covers the entire plane.

Now it is not possible to implement this algorithm exactly, because we are not attempting to cover the entire plane, but rather only a finite region of it. You might think that we could just start laying down templates in the same way as for Figure 36 and stick in a few extra ones for any parts of the parameter space which were not covered, but unfortunately this would then lead us to place templates centered at points in  $(\tau_0, \tau_1)$  space that do not correspond to  $\eta \leq 1/4$ , and for which the very meaning of a “chirp” is ill-defined.

The code in `template_grid()` thus uses a heuristic method to place templates, trying whenever possible to stagger them in the same way as Figure 36 but then shifting the center locations when necessary to ensure that the template corresponds to physical values of the mass parameters  $m_1$  and  $m_2$ . This is often referred to as “hexagonal packing”. In practice, to see if this placement has been successful or not, the function `plot_template()` can be used to visually examine the template map.

Table 7 gives information about the appropriate template sizes, spacings and orientations as found in



Author	Detector	$f_0/\text{Hz}$	$\theta/\text{rad}$	radius $r_1$ (msec)	radius $r_2$ (msec)
Sathyaprakash	Caltech 40m (Nov 94)	140	0.307	8.0	0.6
Owen	Initial LIGO	200	0.5066	2.109	0.162
Owen	Advanced LIGO	70	0.4524	3.970	0.352

Table 7: Orientation and dimensions of 0.97 ambiguity templates.

the recent literature, and using the `match_fit` example program. The angle  $\theta$  is the angle to the axis of the ellipse whose radius is  $r_1$ , measured counterclockwise from the  $\tau_0$  axis. The other radius (semi-axis) of the ellipse has length  $r_2$ . Equation (3.16-18) of reference [5] do not appear to agree with Table 7, but that is because the  $r_i = dx_i$  of [5] are defined by  $(dx_i)_{\text{Owen}} = dl_i/\sqrt{E_i}$ . The  $dl_i$  are the edge lengths of a hypercube in dimension  $N$ , chosen so that if templates are centered on its vertices, then the templates touch in the center of the cube, so that  $(dx_i)_{\text{Owen}} = dl_i/\sqrt{E_i}$ . In our  $N = 2$  dimensional case, this gives  $r_i = dx_i = (dx_i)_{\text{Owen}}/\sqrt{2}$ . Note also that in this table, Owen and Sathyaprakash use different definitions of  $f_0$ , so that their results may not be directly compared. In Owen's case,  $f_0$  refers to the frequency of maximum sensitivity of the detector, whereas in Sathyaprakash's case it refers to the frequency at which the chirp first enters the bandpass of the detector. In the case of the November 1994 data set, we quote two different sizes and orientations for the ellipses, depending upon the choice of  $f_0$ .

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Comments: This routine evolved from `grid4.f`, which was written by Sathyaprakash. The method used to stagger templates is heuristic, and could perhaps be improved. Very small regions of the parameter space along the equal-mass line ( $\eta = 1/4$ ) may not be covered by any templates.

#### 5.40 Function: `plot_template()`

`void plot_template(char *filename, struct Scope Grid, int npages, int number)`

This function generates a PostScript (tm) file that draws a set of templates on top of the region of parameter space which they cover.

The arguments are:

**filename:** Input. Pointer to a character string. This is used as the name of the output file, into which postscript output is written. We suggest that you use “.ps” as the final three characters of the filename. These files are best viewed using GhostView.

**Grid:** Input. The mass range specified by Grid is used to draw an outline of the region in  $(\tau_0, \tau_1)$  parameter space covered by the mass range, and an ellipse for each template included in Grid is then drawn on top of this outline.

**npages:** Input. If there are more than a few templates (and there can be thousands, or more) it is impossible to view this graphical output unless it is spread across many pages. `npages` specifies the number of pages to spread the output across. We suggest at least one page per hundred templates.

**number:** Input. Each template specified in Grid is numbered by the field `Grid.n_tmplt`. If `number` is set to 1, then when each ellipse is drawn in parameter space, the number of the template is placed inside the ellipse so that the particular template associated with each ellipse may be easily identified. If `number` is set to 0, then the templates are not identified in this way; each template is simply drawn as an empty ellipse.

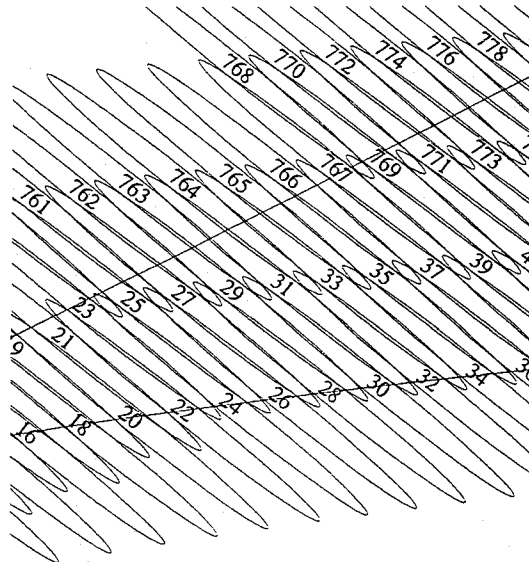


Figure 37: Part of some sample output from `plot_template()`.

Note that the output postscript file is designed to be edited if needed to enable clear viewing of details. Each file is broken into pages. At the beginning of each page are commands that set the magnification scale of each page, and determine if the page will be clipped at the boundaries of the paper or not. You can edit these

lines in the postscript file to enable you to “zoom in” on part of the parameter space, if desired. By turning off the clipping, you can easily move off the boundaries of a given page, if desired. Some sample output from `plot_template()` is shown in Figure 37. (In fact, this is part of the output file produced by the example program, showing a small number of the total of 1001 templates required).

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Comments: Another option should be added, to print out at the center of each template, the mass parameters  $m_1$  and  $m_2$  associated with the template.

### 5.41 Example: template program

This example lays down an optimal grid of templates covering parameter space. It also outputs a postscript file (best viewed with GhostView) which shows the elliptical region of parameter space covered by each template.

```
/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

int main() {
    struct Scope Grid;

    /* Set parameters for the inspiral search in CIT 40 meter */
    Grid.m_mn=0.9;
    Grid.m_mx=3.0;
    Grid.theta=0.307;
    Grid.dp=2*0.008;
    Grid.dq=2*0.0006;
    Grid.f_start=140.0;

    /* construct template set covering parameter space */
    template_grid(&Grid);

    /* create a postscript file showing locations of templates */
    plot_template("templates_40meter.ps",Grid,15,1);
    return 0;
}
```

Part of a typical picture contained in the output file `temp_list.ps` is shown in Figure 37 (though for different parameters than those shown above).

#### 5.42 Example: multifilter program

This example implements optimal filtering by a bank of properly-spaced templates. One could do this with trivial modifications of the example optimal program given earlier. Here we have shown something slightly more ambitious. The multifilter program is an MPI-based parallel-processing code, designed to run on either a network of workstations or on a dedicated parallel machine. It is intended to illustrate a particularly simple division of labor among computing nodes. Each segment of data (of length NPOINT) is broadcast to the next available node. That node is responsible for filtering the data through a bank of templates, chosen to cover the mass range from MMIN to MMAX. The output of each one of these filters is a set of 11 signals, which measure the following quantities:

1. The largest signal-to-noise ratio (SNR) at the output of the filter, for the given segment of data,
2. The distance for an optimally-oriented source, in Mpc, at which the SNR would be unity.
3. The amplitude  $\alpha$  of the zero-degree phase chirp matching the observed signal.
4. The amplitude  $\beta$  of the ninety-degree phase chirp matching the observed signal.
5. The offset of the best-fit chirp into the given segment of data
6. The offset of the impulse into the given segment of data, which would produce the observed output.
7. The time of that impulse, measured in seconds from the start of the data segment,
8. The time (in seconds, measured from the start of the data segment) at which an inspiral, best fitting the observed filter output, would have passed through the start frequency FLO.
9. The time (in seconds, measured from the start of the data segment) at which an inspiral, best fitting the observed filter output, would have passed through coalescence.
10. The observed average value of the output SNR (should be approximately unity).
11. The probability, using the splitup technique described earlier, that the observed filter output is consistent with a chirp plus stationary detector noise.

For completeness, we give this code in its entirety here. We also show some typical graphs produced by the MPE utility `nupshot` which illustrates the pattern of communication and computation for an analysis run. For these graphs, the analysis run lasted only about four minutes, and analyzed about three minutes of IFO data. We have performed an identical, but longer run, which analyzed about five hours of IFO output in just over three hours, running on a network of eight SUN workstations. The data is analyzed in 6.5 second segments, each of which is processed through a set of 66 filter templates completely covering the mass range from 1.2 to 1.6 solar masses. For the run that we have profiled here, `STORE_TEMPLATES` is set to 1. This means that each slave allocates memory internally for storing the Fourier-transformed chirp signals; the slaves only compute these once. However this does place demands on the internal storage space required - in the run illustrated here each individual process allocated about 34 Mbytes of internal memory. Another version of the code has also been tested; in this version the slave nodes compute the filters and Fourier transform them each time they are needed, for each new segment of data. This code has `STORE_TEMPLATES` set to 0. This is less efficient computationally, but requires only a small amount of internal storage. For a given hardware configuration, the optimal balance between these extremes, and between the amount of redundant broadcasting of data, depends upon the relative costs of communication and computation, and the amount of internal storage space available.

Based on these figures, it is possible to provide a rough table of computation times. These are given in tabular form in Table 8.

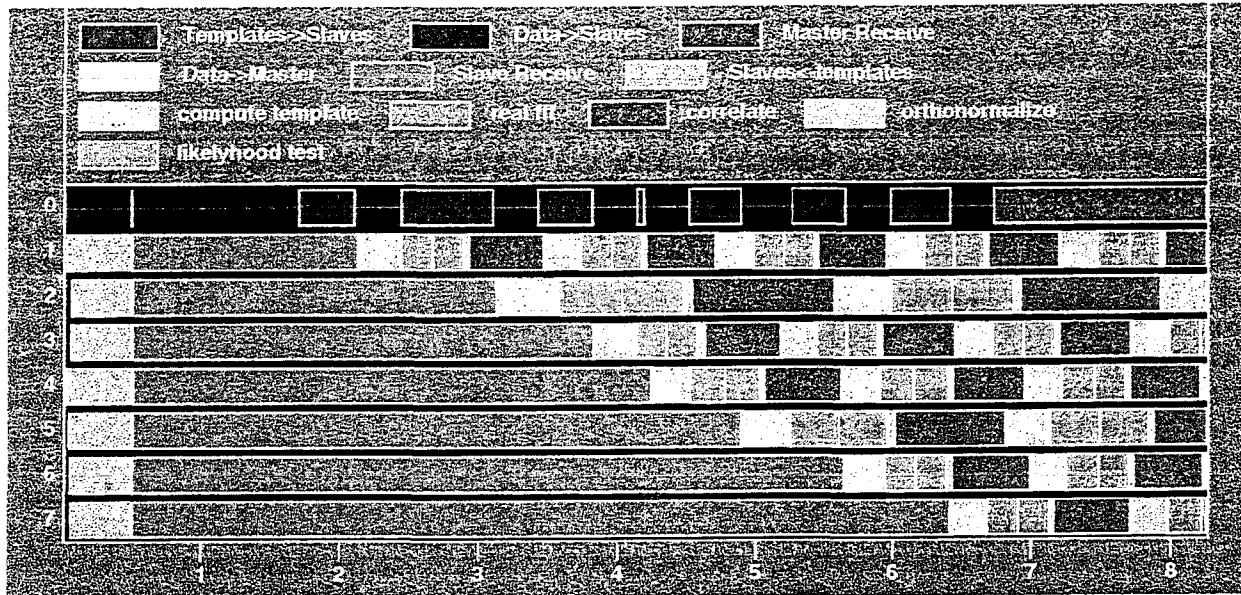


Figure 38: Output of the nupshot profiling tool, showing the behavior of the multifilter program running on a workstation network of 8 machines (the fastest of these are Sparc-20 class processors). This shows the first 8 seconds of operation (time on the horizontal axis). The gray segments show the slave processes receiving the template list. During the orange segments, the slave processes are waiting for data; the blue segments show the master transmitting data to each slave. During the light gray segments, the slaves are computing the templates, during the green segments they are computing the FFT's of those templates, and during the purple segments they are correlating the data against the templates. During the brown segment, the master is waiting to receive data back from the slaves.

Task	Color	Approximate time	Processing done
data → slaves	dark blue	350 msec	transfer 384 kbytes
data → master	yellow	1 msec	transfer 3 kbytes
correlate	purple	500 msec	2 ffts of 64k floats, and search
splitup (likelihood)	light blue	330 msec	several runs through 64k floats
real FFT (one phase)	green	150 msec	1 fft of 64k floats
compute template	gray	350 msec	compute 2 arrays of ≈ 18k floats
orthonormalize templates	wheat	25 msec	several runs through 64k floats

Table 8: Approximate computation times for different elements of the optimal-filtering process.

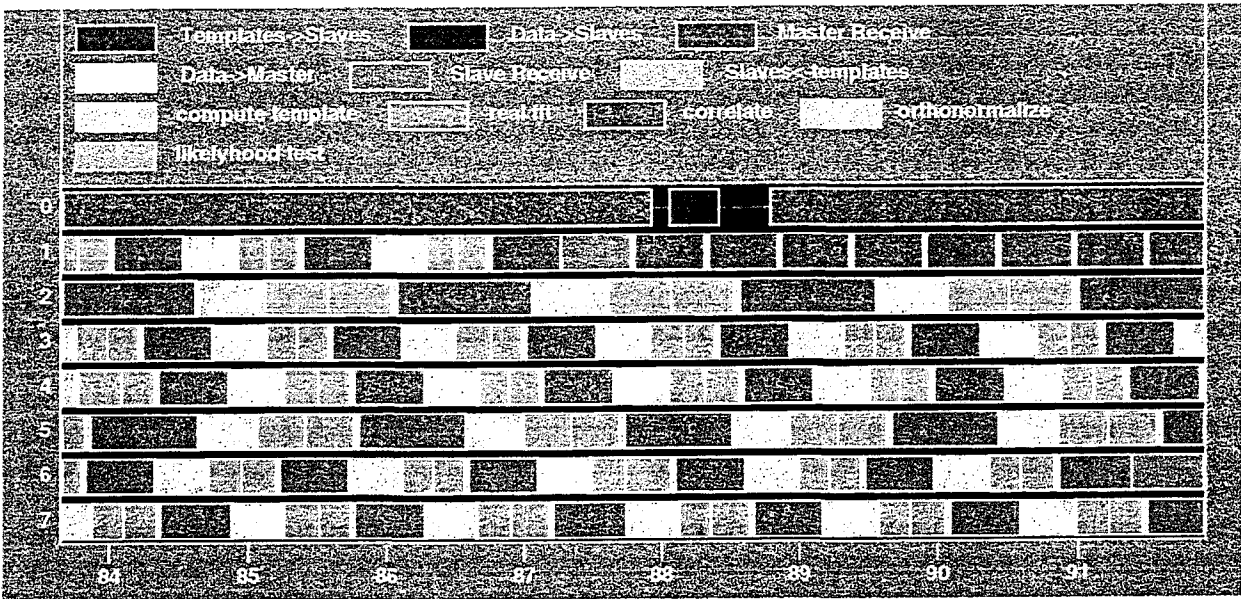


Figure 39: This is a continuation of the previous figure. Slave number 1 has completed its computation of the templates, and during the orange segment, waits to make a connection with the master. This is followed by a (very small) yellow segment, during which the slave transmits data back to the master, and a blue segment during which the master transmits new data to slave number 1. Immediately after this, slave number 1 begins a new (purple) sequence of correlation calculations on the newly received block of data. Notice that because slave 1 has already computed the templates, the light gray and green operations are no longer needed.

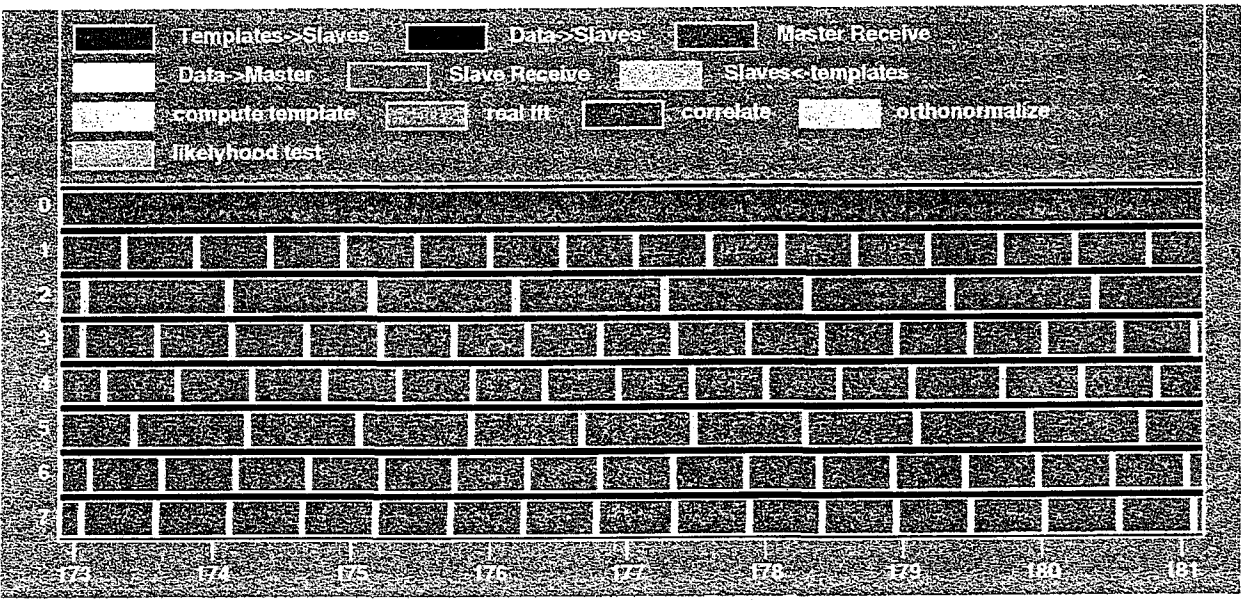


Figure 40: This is a continuation of the previous figure, and represents the “long-term” or “steady-state” behavior of the multiprocessing system. In this state, the different processors are spending all of their time doing correlation measurements of the data, as indicated by the purple segments, and the master is waiting for the results of the analysis (brown segments).

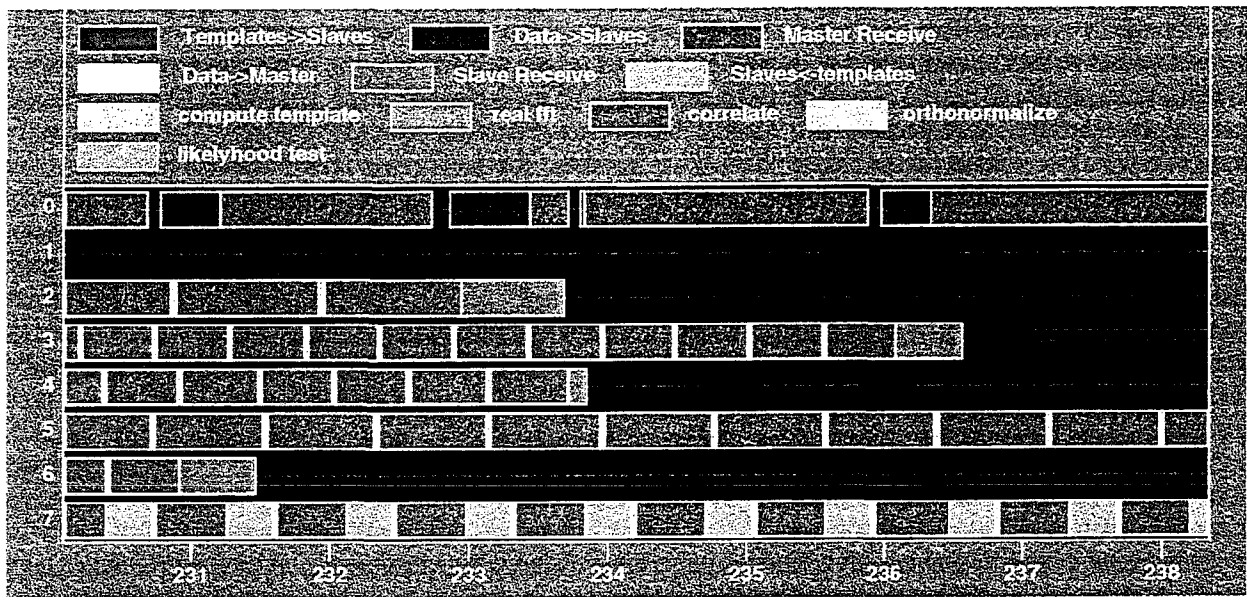


Figure 41: This is a continuation of the previous figure, and shows the termination of some of the slave processes (all the data has been analyzed, and there is no new data remaining). The blue segments (data being sent to slaves) are actually termination messages being sent to the different processes 2,3,4 and 6. Processes 5 and 7 are still computing. In the case of process 7, the data being analyzed contains a non-stationary "spurion" which triggered most of the filters beyond a pre-set threshold level. As a result, process 7 is performing some additional computations (the split-up likelihood test, shown as light blue segments) on the data.



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Comments: There are many other ways in which this optimal filtering code could be parallelized. This program illustrates one of the possibilities. Other possibilities include: maintaining different templates on different processes, and broadcasting identical IFO data to these different processes, or parallelizing across both data and templates.

```
/* GRASP: Copyright 1997, Bruce Allen */
/* multifilter.c
```

This code is intended for machines where computation is cheap, and communication is expensive. The processing is organized as master/slaves (or manager/workers!). The master process sends out data chunks to individual slave processes. These slave processes analyze the data against all templates, then return the largest signal values obtained for each template, along with other parameters like the time of coalescence and the phase of coalescence. They then get a new data chunk. If STORE\_TEMPLATES is set to 1, then the filters are computed once, then stored internally by each slave. This is the correct choice if each slave has lots of fast memory available to it. If STORE\_TEMPLATES is set to 0, then the slaves recompute the templates each time they use them. This is the correct choice if each slave has only small amounts of fast memory available.

```
*/
```

```
#include "mpi.h"
#include "mpe.h"
#include "grasp.h"
```

```
#define NPOINT 65536 /* The size of our segments of data (6.5 secs) */
#define FLO 120.0 /* The low frequency cutoff for filtering */
#define ARMLENGTH 40.0 /* Armlength of the IFO, in meters */
#define HSCALE 1.e21 /* A convenient scaling factor; results independent of it */
#define MIN_INTOLock 3.0 /* Number of minutes to skip into each locked section */
#define SAFETY 200 /* Padding safety factor to avoid wraparound errors */
#define CHIRPLEN 18000 /* length of longest allowed chirp */
#define MMIN 1.2 /* min mass object, solar masses */
#define MMAX 1.6 /* max mass object, solar masses */
#define DATA_SEGMENTS 25 /* largest number of data segments to process */
#define NSIGNALS 11 /* number of signal values computed for each template */
#define STORE_TEMPLATES 1 /* 0: slaves recompute templates. 1: slaves save templates. */
```

```
void shiftdata();
void realft(float*, unsigned long, int);
```

```
struct Saved {
    float tstart;
    int gauss;
};
```

```
short *datas;
int npoint, remain=0, needed, diff, gauss_test, num_sent=0, fill_buffer();
float *twice_inv_noise, *htilde, *data, *mean_pow_spec, tstart;
float srate=9868.4208984375, decaytime, datastart, *response;
double norm, decay;
FILE *fpifo, *fpss, *fplock;
```

```
int main(int argc, char *argv[])
{
```

```
int *lchirppoints, num_stored;
float *ltc, *lch0tilde, *lch90tilde;
int myid, numprocs, i, j, maxi, impulseoff, *chirppoints, indices[8], num_templates;
int slave, more_data, temp_no, num_recv=0, namelen, completed=0, longest_template=0;
float *tc, m1, m2, *template_list, *sig_buffer, distance, snr_max, var, timeoff, timestart;
float n0, n90, inverse_distance_scale, *output90, *output0, *ch0tilde, *ch90tilde;
float lin0, lin90, varsplit, stats[8], gammq(float, float);
```

```

double prob;
FILE *fpout;
MPI_Status status;
char processor_name[MPI_MAX_PROCESSOR_NAME], logfile_name[64], name[64];
struct Scope Grid;
struct Saved *saveme;

/* start MPI, find number of processes, find process number */
MPI_Init(&argc, &argv);
MPI_Comm_size(MPI_COMM_WORLD, &numprocs);
MPI_Comm_rank(MPI_COMM_WORLD, &myid);
MPI_Get_processor_name(processor_name, &namelen);
MPE_Init_log();

/* number of points to sample and fft (power of 2) */
needed=npoint=NPOINT;

/* Gravity wave signal (frequency domain) & twice inverse noise power */
htilde=(float *)malloc(sizeof(float)*npoint+sizeof(float)*(npoint/2+1));
twice_inv_noise=htilde+npoint;

/* Structure for saving information about data sent to slaves */
saveme=(struct Saved *)malloc(sizeof(struct Saved)*numprocs);

/* MASTER */
if (myid==0) {
    MPE_Describe_state(1,2, "Templates->Slaves", "red:vlines3");
    MPE_Describe_state(3,4, "Data->Slaves", "blue:gray3");
    MPE_Describe_state(5,6, "Master Receive", "brown:light_gray");
    MPE_Describe_state(7,8, "Data->Master", "yellow:dark_gray");
    MPE_Describe_state(9,10, "Slave Receive", "orange:white");
    MPE_Describe_state(13,14, "Slaves<-templates", "gray:black");
    MPE_Describe_state(15,16, "compute template", "lavender:black");
    MPE_Describe_state(17,18, "real fft", "lawn green:black");
    MPE_Describe_state(19,20, "correlate", "purple:black");
    MPE_Describe_state(21,22, "orthonormalize", "wheat:black");
    MPE_Describe_state(23,24, "likelihood test", "light sky blue:black");

    /* Set parameters for the inspiral search */
    Grid.m_mn=MMIN;
    Grid.m_mx=MMAX;
    Grid.theta=0.964;
    Grid.dp=2*0.00213;
    Grid.dq=2*0.0320;
    Grid.f_start=140.0;

    /* construct template set covering parameter space, m1 m2 storage */
    template_grid(&Grid);
    num_templates=Grid.n_tmplt;
    printf("The number of templates being used is %d\n", num_templates);
    template_list=(float *)malloc(sizeof(float)*2*num_templates);

    /* put mass values into an array */
    for (i=0; i<Grid.n_tmplt; i++) {
        template_list[2*i]=Grid.templates[i].m1;
        template_list[2*i+1]=Grid.templates[i].m2;
        printf("Mass values are m1 = %f m2 = %f\n", Grid.templates[i].m1, Grid.templates[i].m2);
    }
    fflush(stdout);
}

```

```

/* storage for returned signals (NSIGNALS per template) */
sig_buffer=(float *)malloc(sizeof(float)*num_templates*NSIGNALS);

/* broadcast templates */
MPE_Log_event(1,myid,"send");
MPI_Bcast(&num_templates,1,MPI_INT,0,MPI_COMM_WORLD);
MPI_Bcast(template_list,2*num_templates,MPI_FLOAT,0,MPI_COMM_WORLD);
MPE_Log_event(2,myid,"sent");

/* number of points to sample and fft (power of 2) */
needed=npoint=NPOINT;

/* stores ADC data as short integers */
datas=(short*)malloc(sizeof(short)*npoint);

/* stores ADC data in time & freq domain, as floats */
data=(float *)malloc(sizeof(float)*npoint);

/* The response function (transfer function) of the interferometer */
response=(float *)malloc(sizeof(float)*(npoint+2));

/* The autoregressive-mean averaged noise power spectrum */
mean_pow_spec=(float *)malloc(sizeof(float)*(npoint/2+1));

/* Set up noise power spectrum and decay time */
norm=0.0;
clear(mean_pow_spec,npoint/2+1,1);
decaytime=10.0*npoint/srate;
decay=exp(-1.0*npoint/(srate*decaytime));

/* open the IFO output file, lock file, and swept-sine file */
fpifo=grasp_open("GRASP_DATAPATH","channel.0");
fplock=grasp_open("GRASP_DATAPATH","channel.10");
fpss=grasp_open("GRASP_DATAPATH","swept-sine.ascii");

/* get the response function, and put in scaling factor */
normalize_gw(fpss,npoint,srate,response);
for (i=0;i<npoint+2;i++)
    response[i]*=HSCALE/ARMLENGTH;

/* while not finished, loop over slaves */
for (slave=1;slave<numprocs;slave++) {
    if (get_calibrated_data()) {
        /* if new data exists, then send it (nonblocking?) */
        fprintf(stderr,"Master broadcasting data segment %d\n",num_sent+1);
        MPE_Log_event(3,myid,"send");
        MPI_Send(htilde,NPOINT+NPOINT/2+1,MPI_FLOAT,slave,++num_sent,MPI_COMM_WORLD);
        MPE_Log_event(4,myid,"sent");
        saveme[slave-1].gauss=gauss_test;
        saveme[slave-1].tstart=datastart;
        shiftdata();
    }
    else {
        /* tell remaining processes to exit */
        MPE_Log_event(3,myid,"send");
        MPI_Send(htilde,NPOINT+NPOINT/2+1,MPI_FLOAT,slave,0,MPI_COMM_WORLD);
        MPE_Log_event(4,myid,"sent");
    }
}

```

```

}

/* now loop, gathering answers, sending out more data */
while (num_sent!=num_recv) {
    more_data=get_calibrated_data();

    /* listen for answer */
    MPE_Log_event(5,myid,"receiving...");
    MPI_Recv(sig_buffer,NSIGNALS*num_templates,MPI_FLOAT,MPI_ANY_SOURCE,
             MPI_ANY_TAG,MPI_COMM_WORLD,&status);
    MPE_Log_event(6,myid,"received");
    num_recv++;

    /* store the answers... */
    sprintf(name,"signals.%05d",status.MPI_TAG-1);
    fpout=fopen(name,"w");
    if (fpout==NULL) {
        fprintf(stderr,"Multifilter: can't open output file %s\n",name);
        MPI_Finalize();
        return 1;
    }
    fprintf(fpout,"# Gaussian %d\n",saveme[status.MPI_SOURCE-1].gauss);
    fprintf(fpout,"# tstart %f\n",saveme[status.MPI_SOURCE-1].tstart);
    fprintf(fpout,"# snr distance phase0 phase90 maxi\
    impulseoff impulsetime startinspiral coalesce variance prob\n");
    for (i=0;i<num_templates;i++) {
        for (j=0;j<NSIGNALS-1;j++)
            fprintf(fpout,"%g\t",sig_buffer[i*NSIGNALS+j]);
        fprintf(fpout,"%f\n",sig_buffer[i*NSIGNALS+j]);

        /* if data stream has no obvious outliers, and chirp prob is high, print */
        if (sig_buffer[i*NSIGNALS+10]>0.03 && saveme[status.MPI_SOURCE-1].gauss) {
            printf("POSSIBLE CHIRP: signal file %d, template %d, SNR = %f, prob = %f\n",
                  status.MPI_TAG-1,i,sig_buffer[i*NSIGNALS],sig_buffer[i*NSIGNALS+10]);
            fflush(stdout);
        }
    }
}
fclose(fpout);

/* if there is more data, send it off */
if (more_data) {
    fprintf(stderr,"Master broadcasting data segment %d\n",num_sent+1);
    MPE_Log_event(3,myid,"send");
    MPI_Send(htilde,NPOINT+NPOINT/2+1,MPI_FLOAT,status.MPI_SOURCE,++num_sent,MPI_COMM_WORLD);
    MPE_Log_event(4,myid,"sent");
    saveme[status.MPI_SOURCE-1].gauss=gauss_test;
    saveme[status.MPI_SOURCE-1].tstart=datastart;
    shiftdata();
}
/* or else tell the process that it can pack up and go home */
else {
    printf("Shutting down slave process %d\n",status.MPI_SOURCE);
    MPE_Log_event(3,myid,"send");
    MPI_Send(htilde,NPOINT+NPOINT/2+1,MPI_FLOAT,status.MPI_SOURCE,0,MPI_COMM_WORLD);
    MPE_Log_event(4,myid,"sent");
}
}
}

```

```

    /* when all the answers are in, print results */
    printf("This is the master - all answers are in!\n");
}

/* SLAVES */
else {
    printf("Slave %d (%s) just got started...\n",myid,processor_name);
    fflush(stdout);

    /* allocate storage space */
    /* Output of matched filters for phase0 and phase pi/2, in time domain, and temp storage */
    output0=(float *)malloc(sizeof(float)*npoint);
    output90=(float *)malloc(sizeof(float)*npoint);

    /* get the list of templates to use */
    MPE_Log_event(13,myid,"receiving...");
    MPI_Bcast(&num_templates,1,MPI_INT,0,MPI_COMM_WORLD);
    sig_buffer=(float *)malloc(sizeof(float)*num_templates*NSIGNALS);
    template_list=(float *)malloc(sizeof(float)*2*num_templates);
    MPI_Bcast(template_list,2*num_templates,MPI_FLOAT,0,MPI_COMM_WORLD);
    MPE_Log_event(14,myid,"received");
    printf("Slave %d (%s) just got template list...\n",myid,processor_name);
    fflush(stdout);

    /* Orthogonalized phase 0 and phase pi/2 chirps, in frequency domain */
    num_stored=STORE_TEMPLATES*(num_templates-1)+1;
    lch0tilde=(float *)malloc(sizeof(float)*npoint*num_stored);
    lch90tilde=(float *)malloc(sizeof(float)*npoint*num_stored);
    lchirppoints=(int *)malloc(sizeof(float)*num_stored);
    ltc=(float *)malloc(sizeof(float)*num_stored);

    if (lch0tilde==NULL || lch90tilde==NULL || lchirppoints==NULL || ltc==NULL) {
        fprintf(stderr,"Node %d on machine %s: could not malloc() memory!\n",
            myid,processor_name);
        abort();
    }

    /* now enter an infinite loop, waiting for new inputs */
    while (1) {
        /* listen for data, parameters from master */
        MPE_Log_event(9,myid,"receiving...");
        MPI_Recv(htilde,NPOINT+NPOINT/2+1,MPI_FLOAT,0,MPI_ANY_TAG,MPI_COMM_WORLD,&status);
        MPE_Log_event(10,myid,"received");
        printf("Slave %d (%s) got htilde (and noise spectrum) for segment %d \n",
            myid,processor_name,status.MPI_TAG);
        fflush(stdout);

        /* if this is a termination message, we are done! */
        if (status.MPI_TAG==0) break;

        /* compute signals */
        for (temp_no=0;temp_no<num_templates;temp_no++) {

            ch0tilde=lch0tilde+npoint*temp_no*STORE_TEMPLATES;
            ch90tilde=lch90tilde+npoint*temp_no*STORE_TEMPLATES;
            chirppoints=lchirppoints+temp_no*STORE_TEMPLATES;
            tc=ltc+temp_no*STORE_TEMPLATES;

            /* Compute the template, and store it internally, if desired */

```

```

if (completed!=num_templates) {
    /* manufacture two chirps (dimensionless strain at 1 Mpc distance) */
    m1=template_list[2*temp_no];
    m2=template_list[2*temp_no+1];

    MPE_Log_event(15,myid,"computing");
    make_filters(m1,m2,ch0tilde,ch90tilde,FLO,npoint,srate,chirppoints,tc,4000,4);
    MPE_Log_event(16,myid,"computed");

    if (*chirppoints>longest_template) longest_template=*chirppoints;

    if (*chirppoints>CHIRPLEN) {
        fprintf(stderr,"Chirp m1=%f m2=%f length %d too long!\n",m1,m2,
            *chirppoints);
        fprintf(stderr,"Maximum allowed length is %d\n",CHIRPLEN);
        fprintf(stderr,"Please recompile with larger CHIRPLEN value\n");
        fflush(stderr);
        abort();
    }

    /* normalize the chirp template */
    /* normalization of next line comes from GRASP (5.6.3) and (5.6.4) */
    inverse_distance_scale=2.0*HSCALE*(TSOLAR*C_LIGHT/MPC);
    for (i=0;i<*chirppoints;i++){
        ch0tilde[i]*=inverse_distance_scale;
        ch90tilde[i]*=inverse_distance_scale;
    }

    /* and FFT the chirps */
    MPE_Log_event(17,myid,"starting fft");
    realft(ch0tilde-1,npoint,1);
    MPE_Log_event(18,myid,"ending fft");
    MPE_Log_event(17,myid,"starting fft");
    realft(ch90tilde-1,npoint,1);
    MPE_Log_event(18,myid,"ending fft");

    if (STORE_TEMPLATES) completed++;

    /* print out the length of the longest template */
    if (completed==num_templates)
        printf("Slave %d: templates completed. Longest is %d points\n",
            myid,longest_template);
    fflush(stdout);
} /* done computing the template */

/* orthogonalize the chirps: we never modify ch0tilde, only ch90tilde */
MPE_Log_event(21,myid,"starting");
orthonormalize(ch0tilde,ch90tilde,twice_inv_noise,npoint,&n0,&n90);
MPE_Log_event(22,myid,"done");

/* distance scale Mpc for SNR=1 */
distance=sqrt(1.0/(n0*n0)+1.0/(n90*n90));

/* find the moment at which SNR is a maximum */
MPE_Log_event(19,myid,"searching");
find_chirp(htilde,ch0tilde,ch90tilde,twice_inv_noise,n0,n90,output0,output90,
    npoint,CHIRPLEN,&maxi,&snr_max,&lin0,&lin90,&var);
MPE_Log_event(20,myid,"done");

```

```

/* identify when an impulse would have caused observed filter output */
impulsoff=(maxi+*chirppoints)%npoint;
timeoff=impulsoff/srate;
timestart=maxi/srate;

/* collect interesting signals to return */
sig_buffer[temp_no*NSIGNALS]=snr_max;
sig_buffer[temp_no*NSIGNALS+1]=distance;
sig_buffer[temp_no*NSIGNALS+2]=lin0;
sig_buffer[temp_no*NSIGNALS+3]=lin90;
sig_buffer[temp_no*NSIGNALS+4]=maxi;
sig_buffer[temp_no*NSIGNALS+5]=impulsoff;
sig_buffer[temp_no*NSIGNALS+6]=timeoff;
sig_buffer[temp_no*NSIGNALS+7]=timestart;
sig_buffer[temp_no*NSIGNALS+8]=timestart+*tc;
sig_buffer[temp_no*NSIGNALS+9]=var;

prob=0.0;
if (snr_max>5.0) {
    MPE_Log_event(23,myid,"testing");
    varsplit=splitup_freq2(lin0*n0/sqrt(2.0),lin90*n90/sqrt(2.0),ch0tilde,
                           ch90tilde,2.0/(n0*n0),twice_inv_noise,npoint,maxi,8,
                           indices,stats,output0,htilde);
    prob=gammq(4.0,4.0*varsplit);
    MPE_Log_event(24,myid,"done");
}
sig_buffer[temp_no*NSIGNALS+10]=prob;
} /* end of loop over the templates */

/* return signals to master */
MPE_Log_event(7,myid,"send");
MPI_Send(sig_buffer,NSIGNALS*num_templates,MPI_FLOAT,0,status.MPI_TAG,MPI_COMM_WORLD);
MPE_Log_event(8,myid,"sent");

} /* end of loop over the data */
}

/* both slaves and master exit here */
printf("%s preparing to shut down (process %d)\n",processor_name,myid);
sprintf(logfile_name,"multifilter.%d.%d.log",numprocs,DATA_SEGMENTS);
MPE_Finish_log(logfile_name);
MPI_Finalize();
printf("%s shutting down (process %d)\n",processor_name,myid);
return 0;
}

/* This routine gets the data set, overlapping the data buffer as needed */
int get_calibrated_data() {
    int i,code;

    if (num_sent>=DATA_SEGMENTS)
        return 0;

    while (remain<needed) {
        code=get_data(fpifo,fplock,&tstart,MIN_INT0_LOCK*60*srate,
                     datas,&remain,&srate,1);
        if (code==0) return 0;
    }
}

```



```

/* Get the next needed samples of data */
diff=npoint-needed;
code=get_data(fpifo,fplock,&tstart,needed,datas+diff,&remain,&srate,0);
datastart=tstart-diff/srate;

/* copy integer data into floats */
for (i=0;i<npoint;i++) data[i]=datas[i];

/* find the FFT of data*/
realft(data-1,npoint,1);

/* normalized delta-L/L tilde */
product(htilde,data,response,npoint/2);

/* update the inverse of the auto-regressive-mean power-spectrum */
avg_inv_spec(FLO,srate,npoint,decay,&norm,htilde,mean_pow_spec,twice_inv_noise);

/* see if the data has any obvious outliers */
gauss_test=is_gaussian(datas,npoint,-2048,2047,0);

return 1;
}

/* this function shifts data by CHIRPLEN points in buffer */
void shiftdata() {
    int i;

    /* shift ends of buffer to the start */
    needed=npoint-CHIRPLEN+1;
    for (i=0;i<CHIRPLEN-1;i++) datas[i]=datas[i+needed];

    /* reset if not enough points remain to fill the buffer */
    if (remain<needed) needed=npoint;

    return;
}

```

### 5.43 Optimization and computation-speed considerations

The previous subsection describes the `multifilter` program, which filters data through a bank of templates. We have experimented with the optimization of this code on several platforms, and here recount some of that experience.

The first comment is that the *Numerical Recipes* routine `realft()` is not as efficient as possible. In order to produce a production version of the GRASP code, we suggest replacing this function with a more-optimal version. For example, on the Intel Paragon, the CLASSPACK library provides optimized real-FFT functions. To replace the `realft()` routine, we provide a replacement routine by the same name, which calls the CLASSPACK library. This routine may be found in the `src/optimization/paragon` directory of GRASP. By including the object file for this routine in the linking path, before the *Numerical Recipes* library, it replaces the `realft()` routine. (Note: GRASP currently contains optimized replacement routines for the FFT on SGI/Cray, Sun, Paragon and Intel Linux machines; see the `src/optimization/*` directories of GRASP).

The second comment is related to inspiral-chirp template generation. The binary inspiral chirps may be saved in the `multifilter` program, but one is then limited by the available memory space, as well as incurring the overhead of frequent disk accesses if that memory space is swapped onto and off the disk. To avoid this, it is attractive to generate templates “on the fly”, then dispose of them after each segment of data is analyzed. This corresponds to setting `STORE_TEMPLATES` to 0 in `multifilter`. In this instance, the computational cost of computing binary chirp templates may become quite high, relative to the cost of the remaining computation (FFT’s, orthogonalization, searching for the maximum SNR).

To cite a specific example, on the Intel Paragon, we found that the template generation was almost a factor of ten more time-consuming than the rest of the searching procedure. Some profiling revealed that the two culprits were the cube-root operation and the calculations of sines and cosines. Because the floating point hardware on the Paragon only does add, subtract and multiply, these operations required expensive library calls. In both cases, a small amount of work serves to eliminate most of this computation time. In the case of the cube root function, we have provided (through an `ifdef` `INLINE_CUBEROOT` in the code) an inline computation of cuberoot in 15 FLOPS, which only uses add, subtract and multiply. This routine shifts  $x$  into the range from  $1 \rightarrow 2$ , then uses a fifth-order Chebyshev approximation of  $x^{-2/3}$  then make one pass of Newton-Raphson to clean up to float precision, and returns  $x^{1/3} = x^{-2/3}x$ . In the case of the trig functions we have provided (through an `ifdef` `INLINE_TRIGS` in the code) inline routines to calculate the sine and cosine as well. After reducing the range of the argument to  $x \in [-\pi, \pi]$ , these use a 6th order Chebyshev polynomial to approximate the sine and cosine. These techniques speed up the template generation to the point where it is approximately as expensive as the remaining computations. While there is some small loss of computational accuracy, we have not found it to be significant. Shown in Figure 42 is a timing diagram illustrating the relative computational costs of these operations.

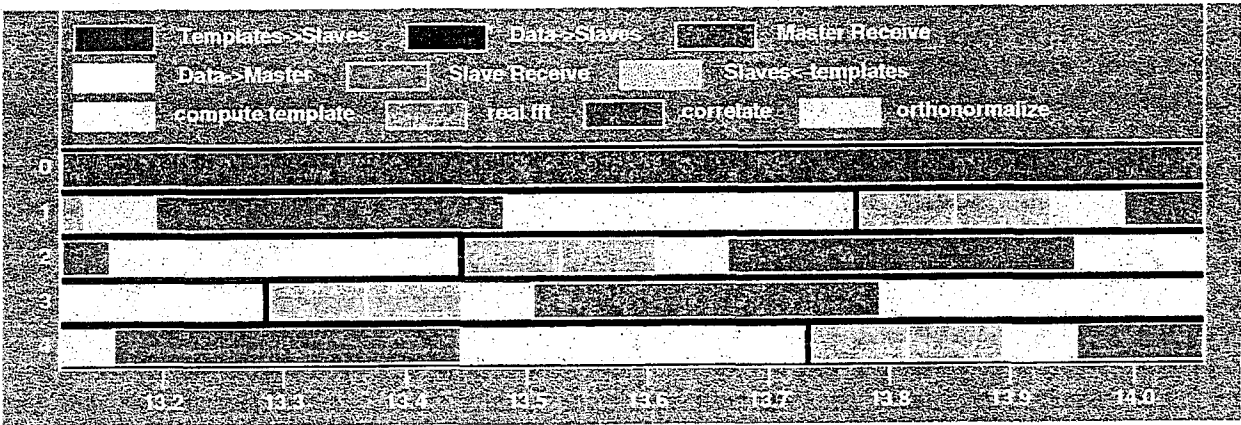
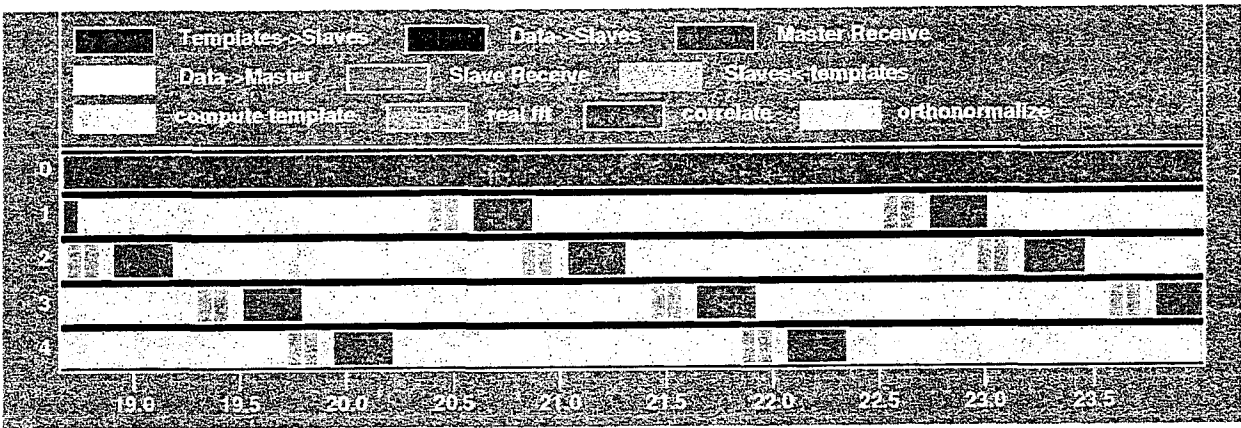
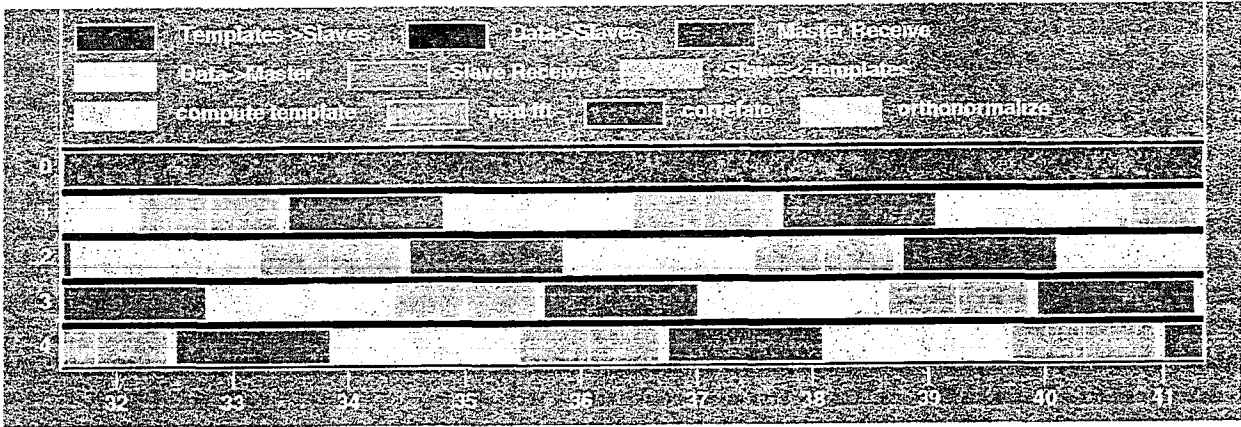


Figure 42: This shows the performance of an "on the fly" template search on the Intel Paragon, with different levels of optimization. The top diagram uses the *Numerical Recipes* FFT routine `realft()`, and takes about 4.2 seconds to process 6 seconds of data. The middle diagram shows identical code using the *CLASSPACK* optimized FFT routine, and takes about 2.1 seconds. Note that the template generation process is now becoming expensive. The bottom diagram shows identical code which includes inline functions for cube-root and sine/cosine functions to speed up the template generation process. The template generation takes about 325 msec, and the entire search procedure (including template generation) takes 780 msec per template per processor per 6-second stretch of data. Relative to the top diagram, this represents a speed-up factor of more than 5. Running on 256 nodes, it is possible to filter 5 hours of data through 66 templates (representing the mass range from 1.2 to 1.6 solar masses) in  $5 \times 3600 \times 66 \times (0.780) / (256 \times 6)$  seconds = 10.1 minutes.

## 6 GRASP Routines: Black hole ringdown

Stellar-sized black hole binaries are an important source of gravitational radiation for ground-based interferometric detectors. The radiation arises from three phases: the inspiral of the two black hole companions, the merger of these two companions to form a single black hole, and the ringdown of this initially distorted black hole to become a stationary Kerr black hole. The gravitational radiation of the black hole inspiral has been discussed in section 5; calculations of the late stages of inspiral, the merger, and the early stages of the ringdown have not yet been completed; the radiation produced in the late stages of black hole ringdown is the topic of this section.

At late times, the distorted black hole will be sufficiently “similar to” a stationary Kerr black hole that the distortion can be expanded in terms of “resonant modes” of the Kerr black hole. By “resonant modes” we refer to the eigenfunctions of the Teukolsky equation—which describes linear perturbations of the Kerr spacetime—with boundary conditions corresponding to purely ingoing radiation at the event horizon and purely outgoing radiation at large distances. These resonant modes are also called the quasinormal modes; they are described in the next subsection.

## 6.1 Quasinormal modes of black holes

Gravitational perturbations of the curvature of Kerr black holes can be described by two components of the Weyl tensor:  $\Psi_0$  and  $\Psi_4$ . Because these are components of the curvature tensor, they have dimensions of  $[L^{-2}]$ . Of particular interest is the quantity  $\Psi_4$  since it is this term that is suitable for the study of outgoing waves in the radiative zone. The formalism for the study of perturbations of rotating black holes was developed originally by Teukolsky [18] who was able to separate the differential equation to obtain solutions of the form

$$(r - i\mu a)^4 \Psi_4 = e^{-i\omega t} {}_{-2}R_{\ell m}(r) {}_{-2}S_{\ell m}(\mu) e^{im\beta} \quad (6.1.1)$$

where  ${}_{-2}R_{\ell m}(r)$  is a solution to a radial differential equation, and  ${}_{-2}S_{\ell m}(\mu)$  is a spin-weighted spheroidal wave function (see [18], equations (4.9) and (4.10)). The black hole has mass  $M$  and *specific angular momentum*  $a = cJ/M$  (which has dimensions of length) where  $J$  is the angular momentum of the spinning black hole. We shall often refer to the *dimensionless angular momentum parameter*,  $\hat{a} = c^2 a/GM = c^3 J/GM^2$ . For a Kerr black hole,  $\hat{a}$  must be between zero (Schwarzschild limit) and one (extreme Kerr limit). The observer of the perturbation is located at radius  $r$ , inclination  $\mu = \cos \iota$ , and azimuth  $\beta$  (see figure 43). The perturbation itself has the spheroidal eigenvalues  $\ell$  and  $m$ , and has a (complex) frequency  $\omega$ . The constants  $G$  and  $c$  are Newton's gravitational constant and the speed of light.

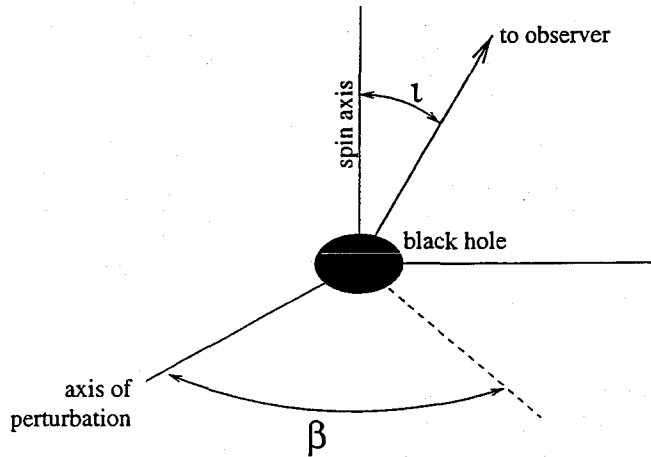


Figure 43: The polar angle,  $\iota$ , and the azimuthal angle,  $\beta$ , of the observer relative to the spin axis of a black hole and the (somewhat arbitrary) axis of perturbation.

The important physical quantities for the study of the gravitational waves arising from black hole perturbations can be recovered from the field  $\Psi_4$ . In particular, the “+” and “×” polarizations of the strain induced by the gravity waves are found by [18]

$$h_+ - ih_\times = -\frac{2c^2}{|\omega|^2} \Psi_4. \quad (6.1.2)$$

The quantity  $h_+ = h_{\hat{t}\hat{t}}$  is the metric perturbation that represents the linear polarization state along  $e_{\hat{t}}$  and  $e_{\hat{\beta}}$ , while the quantity  $h_\times = h_{\hat{t}\hat{\beta}}$  represents the linear polarization state along  $e_{\hat{t}} \pm e_{\hat{\beta}}$ . The power radiated towards the observer (per unit solid angle) is

$$\frac{d^2 E}{dt d\Omega} = \lim_{r \rightarrow \infty} \frac{c^7 r^2}{4\pi G |\omega|^2} |\Psi_4|^2. \quad (6.1.3)$$

Thus, in order to compute the relevant information about gravitational waves emitted as perturbations to rotating black hole spacetimes, one needs to calculate the value of  $\Psi_4$  at large radii from the black hole.

The quasinormal modes are resonant modes of the Teukolsky equation that describe purely outgoing radiation in the wave-zone and purely ingoing radiation at the event horizon. The quasi-normal modes are described by a spectrum of complex eigenvalues (which include the spectrum of eigenfrequencies  $\omega_n$ ), and eigenfunctions  ${}_2R_{\ell m}(r)$  and  ${}_2S_{\ell m}(\mu)$  for each value spheroidal mode  $\ell$  and  $m$ . These eigenvalues and functions also depend on the mass and angular momentum of the black hole. We shall only consider the fundamental ( $n = 0$ ) mode since the harmonics of this mode have shorter lifetimes. For the same reason, we are most interested in the quadrupole ( $\ell = 2$  and  $m = 2$ ) mode. The observer is assumed to be at a large distance; in this case, one can approximate the perturbation as follows:

$$\Psi_4 \approx \frac{A}{r} e^{-i\omega t_{\text{ret}}} {}_2S_{\ell m}(\mu) e^{im\beta}. \quad (6.1.4)$$

Here  $t_{\text{ret}} = t - r^*/c$  represents the retarded time, where  $r^*$  is a ‘‘tortoise’’ radial parameter. For large radii, the tortoise radius behaves as  $r - r_+ \log(r/r_+)$  where  $r_+$  is the ‘‘radius’’ of the black hole event horizon. Thus, we see that the tortoise radius is nearly equal to the distance of the objects surrounding the black hole, and we shall view it as the ‘‘distance to the black hole.’’ The parameter  $A$  represents the amplitude of the perturbation, which has the dimensions of  $[L^{-1}]$ .

Given the asymptotic form of the perturbation in equation 6.1.4, we can integrate equation 6.1.3 over the entire sphere and the interval  $t_{\text{ret}} \in [0, \infty)$  to obtain an expression for the total energy radiated in terms of the amplitude  $A$  of the perturbation. Thus, we can characterize the amplitude by the total amount of energy emitted:  $A^2 = 4Gc^{-7} E|\omega|^2 (-\text{Im } \omega)$ . The gravitational waveform is found to be

$$h_+ - ih_x \approx -\frac{4c}{r} \left( \frac{-\text{Im } \omega}{|\omega|^2} \right)^{1/2} \left( \frac{GE}{c^5} \right)^{1/2} e^{-i\omega t_{\text{ret}}} {}_2S_{\ell m}(\mu) e^{im\beta}. \quad (6.1.5)$$

In order to simulate the quasinormal ringing of a black hole, it is necessary to determine the complex eigenvalues of the desired mode, and then to compute the spheroidal wave function  $S_{\ell m}(\mu)$ . The routines to perform these computations are discussed in the following sections.

Rather than computing the actual gravitational strain waveforms at the detector, the routines will calculate the quantity  $H_+ - iH_x = (c^2 r / GM_\odot)(h_+ - ih_x)$ ; the normalization of these waveforms to the correct source distance is left to the calling routine. The distance normalization can be computed as follows:

$$\frac{c^2 r}{GM_\odot} = \frac{r}{T_\odot c} = \left( \frac{r}{1.4766 \text{ km}} \right) = 2.090 \times 10^{19} \left( \frac{r}{\text{Mpc}} \right). \quad (6.1.6)$$

where  $T_\odot = 4.925491 \mu\text{s}$  is the mass of the sun expressed in seconds (see equation 5.0.2). It will be convenient to write the time dependence of the strain as the complex function  $\mathcal{H}(\lfloor_{\text{ret}})$  so that  $H_+ - iH_x = \mathcal{H}(\lfloor_{\text{ret}}) {}_2S_{\ell m}(\mu) e^{im\beta}$ . The dimensionless eigenfrequency,  $\hat{\omega} = GM\omega/c^3$ , depends only on the mode and the dimensionless angular momentum of the black hole. In terms of this quantity, the function  $\mathcal{H}(\lfloor_{\text{ret}})$  is

$$\mathcal{H}(\lfloor_{\text{ret}}) \approx -\Delta \epsilon^{\infty/\epsilon} \frac{(-\text{Im } \hat{\omega})^{1/2}}{|\hat{\omega}|} \left( \frac{\mathcal{M}}{\mathcal{M}_\odot} \right) \exp \left[ -\hat{\omega} \left( \frac{\lfloor_{\text{ret}}}{T_\odot} \right) \left( \frac{\mathcal{M}}{\mathcal{M}_\odot} \right)^{-\infty} \right] \quad (6.1.7)$$

where  $\epsilon$  is the fractional mass loss due to the radiation in the excited quasinormal mode.

## 6.2 Function: `qn_eigenvalues()`

```
void qn_eigenvalues(float eigenvalues[], float a, int s, int l, int m)
```

This routine computes the eigenvalues associated with the spheroidal and radial wave functions for a specified quasinormal mode. The arguments are:

`eigenvalues`: Output. An array, `eigenvalues[0..3]`, which contains, on output, the real and imaginary parts of the eigenvalues  $\hat{\omega}$  and  $A$  (see below) as follows: `eigenvalues[0] = Re $\hat{\omega}$` , `eigenvalues[1] = Im $\hat{\omega}$` , `eigenvalues[2] = Re $A$` , and `eigenvalues[3] = Im $A$` .

`a`: Input. The dimensionless angular momentum parameter of the Kerr black hole,  $|\hat{a}| \leq 1$ , which is negative if the black hole is spinning clockwise about the  $\iota = 0$  axis (see figure 43).

`s`: Input. The integer-valued spin-weight  $s$ , which should be set to 0 for a scalar perturbation (e.g., a scalar field perturbation),  $\pm 1$  for a vector perturbation (e.g., an electromagnetic field perturbation), or  $\pm 2$  for a spin two perturbation (e.g., a gravitational perturbation).

`l`: Input. The mode integer  $l \geq |s|$ .

`m`: Input. The mode integer  $|m| \leq l$ .

For a Kerr black hole of a given dimensionless angular momentum parameter,  $\hat{a}$ , with a perturbation of spin-weight  $s$  and mode  $\ell$  and  $m$ , there is a spectrum of quasinormal modes which are specified by the eigenvalues  $\hat{\omega}_n$  and  $A_n$ . As discussed in the previous subsection, the eigenvalue  $\hat{\omega}_n$  is associated with the separation of the time dependence of the perturbation, and it specifies the frequency and damping time of the radiation from the perturbation. The additional complex eigenvalue  $A_n$  results from the separation of the radial and azimuthal dependence into the spheroidal and radial wave functions. Both of these eigenvalues will be necessary for the computation of the spheroidal wave function (below).

The routine `qn_eigenvalues()` can be used to compute the eigenvalues of the fundamental ( $n = 0$ ) mode. To convert the dimensionless eigenvalue  $\hat{\omega}$  to the (complex) frequency of the ringdown of a Kerr black hole of mass  $M$ , one simply computes  $\omega = c^3 \hat{\omega} / GM$ . The eigenfrequency is computed using the method of Leaver [15]. Note that Leaver adopts units in which  $2M = 1$ , so one finds that  $\hat{\omega} = \frac{1}{2} \omega_{\text{Leaver}}$  and  $\hat{a} = 2a_{\text{Leaver}}$  in our notation. The eigenvalues satisfy the following symmetry: if  $\rho_m = -i\hat{\omega}_m$  and  $A_m$  are the eigenvalues for an azimuthal index  $m$ , then  $\rho_{-m} = \rho_m^*$  and  $A_{-m} = A_m^*$  are the eigenvalues for the azimuthal index  $-m$ .

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Comment: For simplicity, we require that the spin-weight number,  $s$ , be an integer. Thus, the spinor perturbations  $\chi_0$  and  $\chi_1$ , associated with  $s = \pm \frac{1}{2}$  respectively [18], are not allowed.

### 6.3 Example: eigenvalues program

This example uses the function `qn_eigenvalues()` to compute the eigenvalues  ${}_s\hat{\omega}_{\ell m}$  and  ${}_sA_{\ell m}$  for the  $s$  spin-weighted quasinormal mode specified by  $\ell$  and  $m$ , and for a range of values of the dimensionless angular momentum parameter,  $\hat{a}$ . To invoke the program, type:

```
eigenvalues s l m
```

for the desired (integer) values of  $s$ ,  $\ell$ , and  $m$ . Make sure that  $\ell \geq |s|$  and  $0 \leq m \leq \ell$  (the eigenvalues for negative values of  $m$  can be inferred from the symmetries discussed in subsection 6.2). The output of the program is five columns of data: the first column is the value of  $\hat{a}$  running from just greater than  $-1$  to just less than  $1$  (or between  $0$  and  $1$  if  $m = 0$ ), the second and third columns are the real and imaginary parts of the eigenfrequency  $\hat{\omega}$ , and the fourth and fifth columns are the real and imaginary parts of the angular separation eigenvalue  $A$ . For the values of  $\hat{a} < 0$ , the eigenvalues correspond to the mode with azimuthal index  $-m$  so that the real part of the eigenfrequency is positive. A plot of the eigenfrequency output of the program `eigenvalues` for several runs with  $s = -2$  is shown in figure 44. The blue curves in figure 44 can be compared to figure 5 of reference [16] keeping in mind the conversion factors between Leaver's convention (which is also used in [16]) and the convention used here (see subsection 6.2).

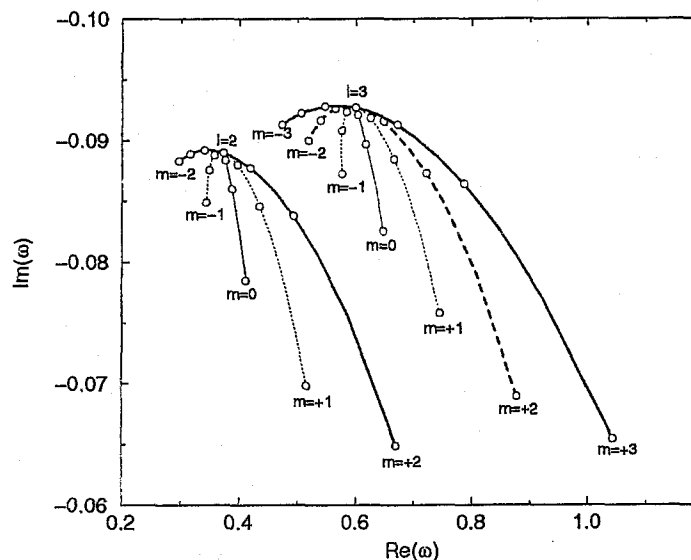


Figure 44: The real and imaginary parts of the eigenfrequencies,  $\hat{\omega}$ , as computed by the program `eigenvalues` with  $s = -2$ . Each curve corresponds to a range of values of  $\hat{a}$  from  $-0.9$  (left) to  $+0.9$  (right) for a single mode  $\ell$  and  $|m|$ . The open circles are placed at the values  $\hat{a} = -0.9, -0.6, -0.3, 0, +0.3, +0.6, \text{ and } +0.9$  except when  $m = 0$  in which case there are no negative values of  $\hat{a}$  plotted. The blue curves correspond to the  $\ell = 2$  modes and the red curves correspond to the  $\ell = 3$  modes.



```

/* GRASP: Copyright 1997, Bruce Allen */
#include "grasp.h"

main(int argc, const char *argv[])
{
    float a, da=0.1, eigen[4];
    int s, l, m;

    /* process the command line arguments */
    if (argc==4) { /* correct number of arguments */
        s = atoi(argv[1]);
        l = atoi(argv[2]);
        m = atoi(argv[3]);
    } else { /* incorrect number of arguments */
        fprintf(stderr, "usage: qn_eigen_values s l m\n");
        return 1;
    }

    /* scan through the range of a */
    for (a=1-da; a>-1; a-=da) {
        /* compute the eigenvalues */
        if (a<0) {
            if (m==0) break;
            qn_eigenvalues(eigen, a, s, l, -m);
        } else {
            qn_eigenvalues(eigen, a, s, l, m);
        }
        /* print the eigenvalues */
        printf("%f\t%f\t%f\t%f\n", a, eigen[0], eigen[1], eigen[2], eigen[3]);
    }

    return 0;
}

```

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## 6.4 Function: `sw_spheroid()`

```
void sw_spheroid(float *re, float *im, float mu, int reset,
                float a, int s, int l, int m, float eigenvalues[])
```

This routine computes the spin-weighted spheroidal wave function  ${}_sS_{\ell m}(\mu)$ . The arguments are:

`re`: Output. The real part of the spin-weighted spheroidal wave function.

`im`: Output. The imaginary part of the spin-weighted spheroidal wave function.

`mu`: Input. The independent variable,  $\mu = \cos \iota$  with  $\iota$  being a polar angle, of the spin-weighted spheroidal wave function;  $-1 < \mu < 1$ .

`reset`: Input. A flag that indicates that the function should reset (`reset = 1`) the internally stored normalization of the spin-weighted spheroidal wave function. The reset flag should be set if any of the following five arguments are changed between calls; otherwise, set `reset = 0` so that the routine does not recompute the normalization.

`a`: Input. The dimensionless angular momentum parameter,  $-1 < a < 1$ , of the Kerr black hole for which the spin-weighted spheroidal wave function is associated.

`s`: Input. The integer-valued spin-weight  $s$ , which should be set to 0 for a scalar perturbation (e.g., a scalar field perturbation),  $\pm 1$  for a vector perturbation (e.g., an electromagnetic field perturbation), or  $\pm 2$  for a spin two perturbation (e.g., a gravitational perturbation).

`l`: Input. The mode integer  $l \geq |s|$ .

`m`: Input. The mode integer  $|m| \leq l$ .

`eigenvalues`: Input. An array, `eigenvalues[0..3]`, which contains the real and imaginary parts of the eigenvalues  $\hat{\omega}$  and  $A$  (see below) as follows: `eigenvalues[0] = Re  $\hat{\omega}$` , `eigenvalues[1] = Im  $\hat{\omega}$` , `eigenvalues[2] = Re  $A$` , and `eigenvalues[3] = Im  $A$` . These may be calculated for a quasinormal mode using the routine `qn_eigenvalues()`.

The spin-weighted spheroidal wave function is also computed using the method of Leaver [15]. We have adopted the following normalization criteria for the spin-weighted spheroidal wave functions  ${}_sS_{\ell m}(\mu)$ . First, the angle-averaged value of the squared modulus of  ${}_sS_{\ell m}(\mu)$  is unity:  $\int_{-1}^1 |{}_sS_{\ell m}(\mu)|^2 d\mu = 1$ . Second, the complex phase is partially fixed by the requirement that  ${}_sS_{\ell m}(0)$  is real. Finally, the sign is set to be  $(-)^{\ell - \max(m, s)}$  for the real part in the limit that  $\mu \rightarrow -1$  in order to agree with the sign of the spin-weighted spherical harmonics  ${}_sY_{\ell m}(\mu, 0)$  (see [14]).

It is sufficient to compute the spin-weighted spheroidal wave functions with  $s < 0$  and  $a\omega = \hat{a}\hat{\omega} \geq 0$  because of the following symmetries [17]:

$$-{}_sS_{\ell m}(\mu, a\omega) = {}_sS_{\ell m}(-\mu, a\omega) \quad \text{with} \quad -{}_sE_{\ell m}(a\omega) = {}_sE_{\ell m}(a\omega) \quad (6.4.1)$$

and

$${}_sS_{\ell m}(\mu, -a\omega) = {}_sS_{\ell, -m}(-\mu, a\omega) \quad \text{with} \quad {}_sE_{\ell m}(-a\omega) = {}_sE_{\ell, -m}(a\omega) \quad (6.4.2)$$

where  ${}_sE_{\ell m} = {}_sA_{\ell m} + s(s+1)$ .

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## 6.5 Example: spherical program

The program `spherical` is an example implementation of the routine `sw_spheroid()` to compute the standard spin-weighted spherical harmonics [14]. The program also computes these functions using equation (3.1) of [14] for comparison. According to the normalization convention stated in subsection 6.4, the relationship between the spin-weighted spheroidal harmonics and the spin-weighted spherical harmonics is:

$${}_sY_{\ell m}(\theta, \phi) = (2\pi)^{-1/2} {}_sS_{\ell m}(\cos \theta) e^{im\phi} \quad (6.5.1)$$

with  $a\omega = 0$  and  $A = (\ell - s)(\ell + s + 1)$ .

To invoke the program, type:

```
spherical s l m
```

for the desired (integer) values of  $s$ ,  $\ell$ , and  $m$  ( $\ell \geq |s|$  and  $|m| \leq \ell$ ). The output is three columns of data: the first column is the independent variable  $\mu$  between  $-1$  and  $+1$ , the second column is the value of  $(2\pi)^{-1/2} {}_sS_{\ell m}(\mu)$ , and the third column is the value of  ${}_sY_{\ell m}(\mu, 0)$  as computed from equation (3.1) of [14]. A comparison of the results produced by the program `spherical` for  $\ell = m = -s = 2$  with the exact values of  ${}_2Y_{22}(\mu, 0) = (5/64\pi)^{1/2}(1 + \mu)^2$  is shown in table 9.

$\mu$	Goldberg	<code>sw_spheroid()</code>	exact
-0.99	$1.576955 \times 10^{-5}$	$1.576955 \times 10^{-5}$	$1.576958 \times 10^{-5}$
-0.95	$3.942387 \times 10^{-4}$	$3.942387 \times 10^{-4}$	$3.942395 \times 10^{-4}$
-0.75	$9.855968 \times 10^{-3}$	$9.855967 \times 10^{-3}$	$9.855986 \times 10^{-3}$
-0.55	$3.193334 \times 10^{-2}$	$3.193333 \times 10^{-2}$	$3.193340 \times 10^{-2}$
-0.35	$6.662639 \times 10^{-2}$	$6.662639 \times 10^{-2}$	$6.663647 \times 10^{-2}$
-0.15	$1.139351 \times 10^{-1}$	$1.139351 \times 10^{-1}$	$1.139352 \times 10^{-1}$
+0.15	$2.085525 \times 10^{-1}$	$2.085525 \times 10^{-1}$	$2.085527 \times 10^{-1}$
+0.35	$2.874004 \times 10^{-1}$	$2.874005 \times 10^{-1}$	$2.874006 \times 10^{-1}$
+0.55	$3.788640 \times 10^{-1}$	$3.788639 \times 10^{-1}$	$3.788641 \times 10^{-1}$
+0.75	$4.829430 \times 10^{-1}$	$4.829430 \times 10^{-1}$	$4.829433 \times 10^{-1}$
+0.95	$5.996378 \times 10^{-1}$	$5.996379 \times 10^{-1}$	$5.996382 \times 10^{-1}$
+0.99	$6.244906 \times 10^{-1}$	$6.244906 \times 10^{-1}$	$6.244911 \times 10^{-1}$

Table 9: A comparison of the values of the spin-weighted spherical harmonic  ${}_2Y_{22}(\mu, 0)$  calculated by equation (3.1) of Goldberg [14], the values of  $(2\pi)^{-1/2} {}_2S_{22}(\mu)$  using routine `sw_spheroid()`, and the values of the exact result  $(5/64\pi)^{1/2}(1 + \mu)^2$ . The three methods give excellent agreement.

```

/* GRASP: Copyright 1997, Bruce Allen */

#include "grasp.h"

#define TWOPI 6.28318530718
#define FOURPI 12.5663706144
static int imaxarg1,imaxarg2;
#define IMAX(a,b) (imaxarg1=(a),imaxarg2=(b),(imaxarg1) > (imaxarg2) ?\
    (imaxarg1) : (imaxarg2))
static int iminarg1,iminarg2;
#define IMIN(a,b) (iminarg1=(a),iminarg2=(b),(iminarg1) < (iminarg2) ?\
    (iminarg1) : (iminarg2))

float sw_spherical(float mu, int s, int l, int m)
/* Computes the spin-weighted spherical harmonic (with phi=0) using
   equation (3.1) of Goldberg et al (1967). */
{
    float factrl(int);
    float bico(int, int);
    float sum,coef,x;
    int sign,r,rmin,rmax;

    if (mu==--1.0) {
        fprintf(stderr,"error in sw_spherical(): division by zero");
        return 0;
    } else {
        x = (1 + mu)/(1 - mu);
    }
    coef = factrl(1+m)*factrl(1-m)*(2*l+1)/((factrl(1-s)*factrl(1+s)*FOURPI);
    rmin = IMAX(0,m-s);
    rmax = IMIN(1-s,l+m);
    sum = 0;
    for (r=rmin;r<=rmax;r++) {
        (((1-r+s)%2)==0) ? (sign = 1) : (sign = -1);
        sum += sign*bico(1-s,r)*bico(1+s,r+s-m)*pow(x,0.5*(2*r+s-m));
    }
    sum *= sqrt(coef)*pow(0.5*(1-mu),l);

    return sum;
}

main(int argc, char *argv[])
{
    float Sre,Sim,Y,norm=1.0/sqrt(TWOPI),mu=0,dmu=0.02;
    float eigenvalues[4];
    int s,l,m;

    /* process arguments */
    if (argc==4) { /* correct number of arguments */
        s = atoi(argv[1]);
        l = atoi(argv[2]);
        m = atoi(argv[3]);
    } else { /* incorrect number of arguments */
        fprintf(stderr,"usage: spherical s l m\n");
        return 1;
    }

    /* set the eigenvalues to produce spin-weighted spherical harmonics */

```

```

eigenvalues[0] = eigenvalues[1] = eigenvalues[3] = 0;
eigenvalues[2] = (1 - s)*(1 + s + 1);

/* reset the normalization */
sw_spheroid(&Sre, &Sim, mu, 1, 0.0, s, 1, m, eigenvalues);

for (mu=-1+0.5*dmu; mu<1; mu+=dmu) {
    /* compute the spin-weighted spheroidal harmonic */
    sw_spheroid(&Sre, &Sim, mu, 0, 0.0, s, 1, m, eigenvalues);
    /* compute the spin-weighted spherical harmonic */
    Y = sw_spherical(mu, s, 1, m);
    /* print results with correct normalization for the spheroidal harmonic */
    printf("%e\t%e\t%e\n", mu, norm*Sre, Y);
}

return 0;
}

```

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## 6.6 Example: spheroid program

This is a second implementation of the function `sw_spheroid()` which is used to compute the spin-weighted spheroidal wave function associated with a quasinormal ringdown mode of a Kerr black hole with a certain (specified in the code) dimensionless angular momentum parameter. To invoke the program, type:

```
spheroid s l m
```

for the desired (integer) values of  $s$ ,  $l$ , and  $m$  ( $l \geq |s|$  and  $|m| \leq l$ ) of the desired mode. The output is three columns of data: the first column is the independent variable  $\mu$  between  $-1$  and  $+1$ , the second column is the value of the real part of  ${}_sS_{\ell m}(\mu)$ , and the third column is the value of the imaginary part of  ${}_sS_{\ell m}(\mu)$ . Figure 45 depicts the output for the spin-weighted spheroidal wave function  ${}_{-2}S_{22}(\mu)$ .

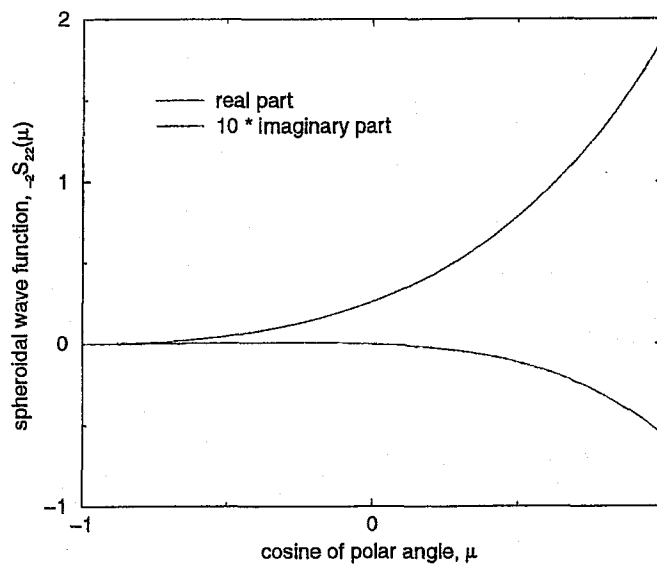


Figure 45: A plot of the real and imaginary parts of the  $l = m = -s = 2$  spin-weighted spheroidal wave function,  ${}_{-2}S_{22}(\mu)$ , associated with a black hole with dimensionless angular momentum parameter  $\hat{a} = 0.98$ . The imaginary part is scaled by a factor of ten.

```

/* GRASP: Copyright 1997, Bruce Allen */

#include "grasp.h"

#define SPIN 0.98 /* the dimensionless angular momentum parameter */

main(int argc, char *argv[])
{
    float re, im, mu=0, dmu=0.02, a=SPIN;
    float eigenvalues[4];
    int s, l, m;

    /* process arguments */
    if (argc==4) { /* correct number of arguments */
        s = atoi(argv[1]);
        l = atoi(argv[2]);
        m = atoi(argv[3]);
    } else { /* incorrect number of arguments */
        fprintf(stderr, "usage: spheroid s l m\n");
        return 1;
    }

    /* get the eigenvalues for the appropriate quasinormal mode */
    qn_eigenvalues(eigenvalues, a, s, l, m);

    /* reset the normalization */
    sw_spheroid(&re, &im, mu, 1, a, s, l, m, eigenvalues);

    for (mu=-1+0.5*dmu; mu<1; mu+=dmu) {
        /* compute the spin-weighted spheroidal harmonic */
        sw_spheroid(&re, &im, mu, 0, 0.0, s, l, m, eigenvalues);
        /* print results */
        printf("%e\t%e\t%e\n", mu, re, im);
    }

    return 0;
}

```

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## 6.7 Function: `qn_ring()`

```
int qn_ring(float iota, float beta,  
           float eps, float M, float a, int l, int m,  
           float dt, float atten, int max,  
           float **plusPtr, float **crossPtr)
```

This routine is used to compute the “+” and “x” polarizations of the gravitational waveform,  $H(t_{\text{ret}})$ , produced by a black hole ringdown at a distance  $GM_{\odot}/c^2 = T_{\odot}c \simeq 1.4766$  km. To obtain the waveforms at a distance  $r$ , multiply the result by  $GM_{\odot}/c^2 r = T_{\odot}c/r$ . The arguments are:

`iota`: Input. The polar angle (inclination),  $\iota$  (in radians), of the sky position of the observer with respect to the (positive) spin axis of the black hole,  $0 \leq \text{iota} \leq \pi$ .

`beta`: Input. The azimuth,  $\beta$  (in radians), of the sky position of the observer with respect to the axis of the perturbation at the start time. ( $0 \leq \text{beta} \leq 2\pi$ .)

`eps`: Input. The fraction of the total mass lost in gravitational radiation from the particular mode. ( $0 < \text{eps} \ll 1$ .)

`M`: Input. The mass of the black hole in solar masses.

`a`: Input. The dimensionless angular momentum parameter of the Kerr black hole,  $|\hat{a}| \leq 1$ , which is negative if the black hole is spinning clockwise about the  $\iota = 0$  axis (see figure 43).

`l`: Input. The mode integer  $\ell$ . ( $l \geq 2$ )

`m`: Input. The mode integer  $m$ . ( $|m| \leq l$ )

`dt`: Input. The time interval, in seconds, between successive data points in the returned waveforms.

`atten`: Input. The attenuation level, in dB, at which the routine will terminate calculation of the waveforms. I.e., the routine will terminate when the amplitude,  $A = A_0 \exp(-\text{Im} \omega t_{\text{ret}})$ , falls below the level  $A_{\text{cutoff}} = A_0 \text{alog}_{10}(-0.1 \times \text{atten})$ .

`max`: Input. The maximum number of data points to be returned in the waveforms.

`plusPtr`: Input/Output. A pointer to an array which, on return, contains the waveform  $H_+$  sampled at intervals `dt`. If the array has the value `NULL` on input, the routine allocates an amount of memory to `*plusPtr` to hold `max` elements.

`crossPtr`: Input/Output. A pointer to an array which, on return, contains the waveform  $H_x$  sampled at intervals `dt`. If the array has the value `NULL` on input, the routine allocates an amount of memory to `*crossPtr` to hold `max` elements.

The routine `qn_ring()` returns the number of data points that were written to the arrays `(*plusPtr) []` and `(*crossPtr) []`; this is either the number specified by the input parameter `max` or the number of points computed when the waveform was attenuated by the threshold `atten`. The eigenvalues are obtained from the function `qn_eigenvalues()`. The waveform is then computed using  $H_+ - iH_x = \mathcal{H}(\mathbb{L}_{\text{ret}})_{-\epsilon} \mathcal{S}_{\ell\uparrow}(\mu) \uparrow^{\beta}$  with  $\mathcal{H}(\mathbb{L}_{\text{ret}})$  given by equation (6.1.7). The spheroidal wave function is obtained from the function `sw_spheroid()`.

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## 6.8 Example: ringdown program

This example uses the function `qm_ring()` to compute the black hole quasinormal ringdown waveform for a preset mode and inclination. The waveform as a function of time is written to standard output in three columns: the time, the plus polarization, and the cross polarization. A Plot of the quasinormal ringdown waveform data is shown in figure 46.

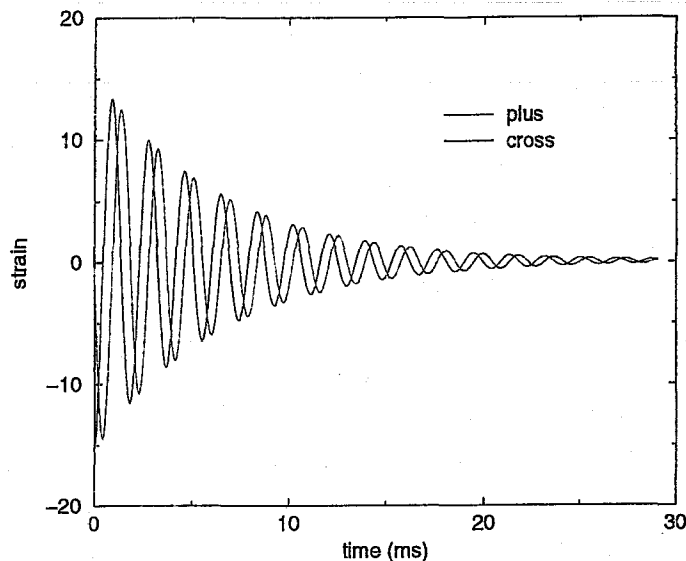


Figure 46: A plot of the plus and cross polarizations of the gravitational wave strain, at a (unphysical!) distance  $GM_{\odot}/c^2 = T_{\odot}c \simeq 1.4766$  km, for the fundamental  $\ell = m = 2$  mode of a black hole with mass  $M = 50M_{\odot}$ , dimensionless angular momentum parameter 0.98, and fractional mass loss  $\epsilon = 0.03$ , with inclination and azimuth  $\iota = 0$  and  $\beta = 0$ . The data was produced by the program `ringdown`.

```
/* GRASP: Copyright 1997, Bruce Allen */
```

```
#include "grasp.h"
```

```
#define IOTA 0.0      /* inclination (radians) */  
#define BETA 0.0     /* azimuth (radians) */  
#define EPS 0.03    /* fractional mass loss */  
#define MASS 50.0   /* mass (solar masses) */  
#define SPIN 0.98   /* specific angular momentum */  
#define MODE_L 2    /* mode integer l */  
#define MODE_M 2    /* mode integer m */  
#define SRATE 16000.0 /* sampling rate (Hz) */  
#define ATTEN 20.0  /* attenuation level (dB) */  
#define MAX 1024   /* max number of points in waveform */
```

```
main()
```

```
{  
    float *plus,*cross,t,dt=1/SRATE;  
    int i,n;  
  
    /* set arrays to NULL so that memory is allocated in called routines */  
    plus = cross = NULL;  
  
    /* generate the waveform function data */  
    n = qn_ring(IOTA,BETA,EPS,MASS,SPIN,MODE_L,MODE_M,dt,ATTEN,MAX,&plus,&cross);  
  
    /* output the data */  
    for (i=0,t=0;i<n;i++,t+=dt) printf("%e\t%e\t%e\n",t,plus[i],cross[i]);  
  
    return 0;  
}
```

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## 6.9 Function: `qn_qring()`

```
int qn_qring(float psi0, float eps, float M, float a,
            float dt, float atten, int max, float **strainPtr)
```

The routine `qn_qring()` is a quick ringdown generator which constructs a damped sinusoid with a frequency and quality approximately equal to that of the  $\ell = m = 2$  quasinormal mode of a Kerr black hole and an amplitude approximately equal to angle-averaged strain expected for black hole radiation at a distance  $GM_{\odot}/c^2 = T_{\odot}c \simeq 1.4766$  km. To obtain the waveforms at a distance  $r$ , multiply the result by  $GM_{\odot}/c^2 r = T_{\odot}c/r$ . The arguments to the routine are:

`psi0`: Input. The initial phase (in radians) of the waveform (see below).

`eps`: Input. The fractional mass loss in quadrupolar ( $\ell = m = 2$ ) radiation. ( $0 < \text{eps} \ll 1$ .)

`M`: Input. The mass of the black hole in solar masses.

`a`: Input. The dimensionless angular momentum parameter of the Kerr black hole,  $|\hat{a}| \leq 1$ , which is negative if the black hole is spinning clockwise about the  $\iota = 0$  axis (see figure 43).

`dt`: Input. The time interval, in seconds, between successive data points in the returned waveform.

`atten`: Input. The attenuation level, in dB, at which the routine will terminate calculation of the waveforms.

`max`: Input. The maximum number of data points to be returned in the waveforms.

`strainPtr`: Input/Output. A pointer to an array which, on return, contains the angle-averaged waveform sampled at intervals `dt`. If the array has the value NULL on input, the routine allocates an amount of memory to `*strainPtr` to hold `max` elements.

The routine `qn_qring()` returns the number of data points that were written to the array (`*strainPtr`)[`0`]; this is either the number specified by the input parameter `max` or the number of points computed when the waveform was attenuated by the threshold `atten`. The array contains the *angle averaged waveform*

$$H_{\text{ave}}(t_{\text{ret}}) = \frac{1}{\sqrt{5}} \text{Re} [\mathcal{H}(\lfloor_{\text{ret}})]^{i\psi_0}, \quad (6.9.1)$$

where  $\mathcal{H}(\lfloor_{\text{ret}})$  is given by equation (6.1.7), sampled at time intervals  $dt$ . The constant  $\psi_0$  defines the initial phase of the waveform. The amplitude factor is set by the following argument: The gravitational strain (at a distance  $GM_{\odot}/c^2 = T_{\odot}c \simeq 1.4766$  km) that would be observed by an interferometer is given by  $H(t_{\text{ret}}) = F_+(\theta, \phi, \psi)H_+(t_{\text{ret}}, \iota, \beta) + F_{\times}(\theta, \phi, \psi)H_{\times}(t_{\text{ret}}, \iota, \beta)$  where  $F_+$  and  $F_{\times}$  represent the antenna patterns of the interferometer. When averaged over  $\theta$ ,  $\phi$ , and  $\psi$ , one finds  $\langle F_+^2 \rangle = \langle F_{\times}^2 \rangle = \frac{1}{5}$  and  $\langle F_+ F_{\times} \rangle = 0$ . Thus,

$$\begin{aligned} \overline{\langle H^2(t_{\text{ret}}) \rangle}_{\theta, \phi, \psi, \iota, \beta} &= \frac{1}{5} \langle H_+^2(t_{\text{ret}}, \iota, \beta) + H_{\times}^2(t_{\text{ret}}, \iota, \beta) \rangle_{\iota, \beta} \\ &= \frac{1}{5} \langle |(H_+ - iH_{\times})(t_{\text{ret}}, \iota, \beta)|^2 \rangle_{\iota, \beta} \\ &= \frac{1}{10} |\overline{\mathcal{H}(\lfloor_{\text{ret}})}|^2 \\ &\approx \overline{H_{\text{ave}}^2} \end{aligned} \quad (6.9.2)$$

where the overbar indicates a time average over a single cycle; approximate equality becomes exact in the limit of a high quality ringdown. It is in this sense that the quantity  $H_{\text{ave}}(t_{\text{ret}})$  can be viewed as an angle-averaged waveform.

Rather than compute the eigenfrequency using the routine `qn_eigenvalues()`, this routine uses the analytic fits to the eigenfrequency found by Echeverria [13]. These expressions are:

$$\hat{\omega} \simeq f(\hat{a})(1 - \frac{1}{4}ig(\hat{a})) \quad (6.9.3)$$

with

$$f(\hat{a}) = 1 - 0.63(1 - \hat{a})^{3/10} \quad (6.9.4)$$

$$g(\hat{a}) = (1 - \hat{a})^{9/20}. \quad (6.9.5)$$

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Comments: Since this routine does not need to compute the spheroidal wave function and uses an analytic approximation to the eigenfrequency, it is much simpler than the routine `qn_ring()`. The approximate eigenfrequencies are typically accurate to within  $\sim 5\%$ , so this routine is to be preferred when computing quadrupolar ( $\ell = m = 2$ ) quasinormal waveforms unless accuracy is critical.

## 6.10 Function: `qn_filter()`

```
int qn_filter(float freq, float qual,  
             float dt, float atten, int max, float **filterPtr)
```

Quasinormal ringdown waveforms are characterized by two parameters: the central frequency of the waveform, and the *quality* of the waveform. The parameter space is most easily described in terms of these variables (rather than the mass and the angular momentum of the corresponding black hole), so it is useful to construct filters for quasinormal ringdown waveform searches in terms of the frequency and quality of the waveform. This routine constructs such a filter, with a specified frequency and quality. The routine returns the number of filter elements computed before a specified attenuation level was reached. The arguments are:

`freq`: Input. The central frequency, in Hertz, of the ringdown filter.

`qual`: Input. The quality of the ringdown filter.

`dt`: Input. The time interval, in seconds, between successive data points in the returned waveform.

`atten`: Input. The attenuation level, in dB, at which the routine will terminate calculation of the waveforms.

`max`: Input. The maximum number of data points to be returned in the waveforms.

`filterPtr`: Input/Output. A pointer to an array which, on return, contains the filter sampled at intervals `dt`. If the array has the value `NULL` on input, the routine allocates an amount of memory to `*filterPtr` to hold `max` elements.

The constructed filter,  $q(t)$ , is the function

$$q(t) = e^{-\pi ft/Q} \cos(2\pi ft) \quad (6.10.1)$$

where  $f$  is the central frequency and  $Q$  is the quality. The routine `qn_filter()` performs no normalization, nor does it account for different possible starting phases. The latter is not important for detection template construction. Normalization is achieved using the function `qn_normalize()`, which is described later.

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### 6.11 Function: `qn_normalize()`

```
void qn_normalize(float *u, float *q, float *r, int n, float *norm)
```

Given a filter,  $\bar{q}(f)$ , and twice the inverse power spectrum,  $r(f)$ , this routine generates a normalized template  $\tilde{u}(f)$  for which  $1 = \langle N^2 \rangle \rightarrow \frac{1}{2} \text{correlate}(\dots, u, u, r, n)$ . The arguments are:

**u:** Output. The array `u[0..n-1]` contains the positive frequency part of the complex template function  $\tilde{u}(f)$ , packed as described in the Numerical Recipes routine `realft()`.

**q:** Input. The array `q[0..n-1]` contains the positive frequency part of the complex filter function  $\bar{q}(f)$ , also packed as described in the Numerical Recipes routine `realft()`.

**r:** Input. The array `r[0..n/2]` contains the values of the real function  $r(f) = 2/S_h(|f|)$  used as a weight in the normalization. The array elements are arranged in order of increasing frequency from the DC component at subscript 0 to the Nyquist frequency at subscript `n/2`.

**n:** Input. The total length of the arrays `u` and `q`. Must be even.

**norm:** Output. The normalization constant,  $\alpha$ , defined below.

Given a filter,  $q(t)$ , this routine computes a template,  $u(t) = \alpha q(t)$ , which is normalized so that  $(u, u) = 2$ , where  $(\cdot, \cdot)$  is the inner product defined by equation (5.14.9). Thus, the normalization constant is given by

$$\frac{1}{\alpha^2} = \frac{1}{2}(q, q). \quad (6.11.1)$$

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## 6.12 Function: `find_ring()`

```
void find_ring(float *h, float *u, float *r, float *o,  
              int n, int len, int safe, int *off,  
              float *snr, float *mean, float *var)
```

This optimally filters the strain data using an input template and then finds the time at which the SNR peaks. The arguments are:

`h`: Input. The FFT of the strain data  $\bar{h}(f)$ .

`u`: Input. The normalized template  $\bar{u}(f)$ .

`r`: Input. Twice the inverse power spectrum  $2/S_h(|f|)$ .

`o`: Output. Upon return, contains the filter output.

`n`: Input. Defines the lengths of the arrays `h[0..n-1]`, `u[0..n-1]`, `o[0..n-1]`, and `r[0..n/2]`.

`len`: Input. The number of time domain bins for which the filter  $u(t)$  is non-zero. Needed in order to eliminate the wrap-around ambiguity described in subsection 5.18.

`safe`: Input. The additional number of time domain bins to use as a safety margin. This number of points are ignored at the beginning of the filter output and, along with the number of points `len`, at the ending of the filter output. Needed in order to eliminate the wrap-around ambiguity described in subsection 5.18.

`off`: Output. The offset, in the range `safe` to `n-len-safe-1`, for which the filter output is a maximum.

`snr`: Output. The maximum SNR in the domain specified above.

`mean`: Output. The mean value of the filter output over the domain specified above.

`var`: Output. The variance of the filter output over the domain specified above. Would be unity if the input to the filter were Gaussian noise with a spectrum defined by  $S_h$ .

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### 6.13 Function: `qn_inject()`

```
void qn_inject(float *strain, float *signal, float *response, float *work,  
              float invMpc, int off, int n, int len)
```

This routine injects a signal  $s(t)$ , normalized to a specified distance, into the strain data  $h(t)$ , with some specified time offset. The arguments to the routine are:

`strain`: Input/Output. The array `strain[0..n-1]` containing the strain data on input, and the strain data plus the input signal on output.

`signal`: Input. The array `signal[0..len-1]` containing the signal, in strain units at 1 Mpc distance, to be input into the strain data stream.

`response`: Input. The array `response[0..n+1]` containing the response function  $R(f)$  of the IFO.

`work`: Output. A working array `work[0..n-1]`.

`invMpc`: Input. The inverse distance of the system, measured in 1/Mpc, to be used in normalizing the signal.

`off`: Input. The offset number of samples (in the time domain) at which the injected signal starts.

`n`: Input. Defines the length of the arrays `strain[0..n-1]`, `work[0..n-1]`, and `response[0..n+1]`.

`len`: Input. Defines the length of the array `signal[0..len-1]`.

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Comments: See the description of the routine `time_inject()`.



## 6.14 Vetoing techniques for ringdown waveforms

Vetoing techniques for binary inspirals have already been described in subsection 5.22; these techniques are equally applicable to searches for ringdown waveforms. However, since ringdown waveforms are short lived and have a narrow frequency band, it is much more difficult to distinguish between a ringdown waveform and a purely impulsive event. Furthermore, since the ringdown waveform will be preceded by some unknown waveform corresponding to a black hole merger, one should not be too selective as to which events should be vetoed.

Nevertheless, the Caltech 40 meter interferometer data has many spurious events that will trigger a ringdown filter, and we would expect that other instruments will have similar properties. These spurious events will (hopefully) not be too common, and most will be able to be rejected if they are not reported by other detectors. At present, however, we have only the Caltech 40 meter data to analyze, so we must consider every event that is detected by the optimal filter. The single vetoing technique that we will use at present is to look for non-Gaussian events in the detector output using the routine `is_gaussian()`. Since the expected ringdown waveforms will be only barely discernible in the raw data, such a test has no chance of accidentally vetoing an actual ringdown, but it will veto the obvious irregularities in the data.

## 6.15 Example: `qn_optimal` program

This program is a reworking of the program `optimal` to be run on simulated 40-meter data. Instead of searching for binary inspiral, `qn_optimal` searches for an injected quasinormal ringdown waveform. Refer to the sections on optimal filtering and the `optimal` program for a detailed discussion.

The program is setup to inject a quasinormal ringdown, produced by the routine `qn_qring()`, due to a black hole of mass  $M = 50M_{\odot}$ , dimensionless angular momentum parameter  $\hat{a} = 0.98$ , and fractional mass loss of  $\epsilon = 0.03$ . The injection occurs at a time of 500 s and the source distance is set to 100 kpc. The filter is constructed from the same waveform.

The following is some sample output from `qn_optimal`:

```
max snr: 3.74 (offset 30469) data start: 466.77 variance: 0.72159
max snr: 4.03 (offset 50156) data start: 479.80 variance: 0.78550

Max SNR: 9.26 (offset 70785) variance 0.796263
  If ringdown, estimated distance: 0.114364 Mpc, start time: 499.999968
  Distribution: s= 40, N>3s= 0 (expect 353), N>5s= 0 (expect 0)
  POSSIBLE RINGDOWN: Distribution does not appear to have outliers

max snr: 3.58 (offset 70974) data start: 505.86 variance: 0.77432
...
max snr: 3.62 (offset 123006) data start: 1339.81 variance: 0.70885

Max SNR: 67.01 (offset 126129) variance 4.637304
  If ringdown, estimated distance: 0.009777 Mpc, start time: 1365.618108
  Distribution: s= 40, N>3s= 320 (expect 353), N>5s= 780 (expect 0)
  Distribution has outliers! Reject

Max SNR: 93.03 (offset 1295) variance 4.444335
  If ringdown, estimated distance: 0.005934 Mpc, start time: 1365.998780
  Distribution: s= 40, N>3s= 109 (expect 353), N>5s= 280 (expect 0)
  Distribution has outliers! Reject

max snr: 2.71 (offset 127389) data start: 1378.90 variance: 0.29810
...
max snr: 4.85 (offset 118137) data start: 2152.18 variance: 0.91870

Max SNR: 12.74 (offset 69426) variance 1.332324
  If ringdown, estimated distance: 0.081144 Mpc, start time: 2172.249524
  Distribution: s= 39, N>3s= 0 (expect 353), N>5s= 0 (expect 0)
  POSSIBLE RINGDOWN: Distribution does not appear to have outliers

max snr: 3.65 (offset 35976) data start: 2178.24 variance: 0.77820
max snr: 3.76 (offset 122854) data start: 2191.28 variance: 0.67849
```

As can be seen, `qn_optimal` is able to find the ringdown and correctly estimates its distance and time of arrival.

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```

/* GRASP: Copyright 1997, Bruce Allen */

#include "grasp.h"

#define NPOINT 131072      /* number of data points */
#define HSCALE 1.0e21     /* convenient scaling factor */
#define ARMLENGTH 40.0    /* armlength (meters) */
#define FLO 120.0         /* low frequency cutoff for filtering */
#define MIN_INT0_LOCK 3.0 /* time (minutes) to skip into each locked section */
#define THRESHOLD 6.0     /* detection threshold SNR */
#define ATTEN 30.0        /* attenuation cutoff for ringdown waveforms */
#define SAFETY 1000       /* padding safety to avoid wraparound errors */
#define DATA_SEGMENTS 3000 /* maximum number of data segments to filter */

double datastart;
float *response, srate=9868.4208984375;
short *datas;
int needed=NPOINT;

main()
{
    void realft(float *, unsigned long, int);

    double norm;
    float *data, *htilde, *output;
    float *mean_pow_spec, *twice_inv_noise;
    float *ring, *ringtilde, *template;
    float decaytime, decay, scale, snr, mean, var, tml_norm, dist;
    float mass=50.0, spin=0.98, eps=0.03, psi0=0.0, invMpc=10.0, ringstart=500.0;
    int i, code, len, safe=SAFETY, diff, off, n=NPOINT;

    /* allocate memory for arrays */
    response=(float *)malloc(sizeof(float)*(NPOINT+2));
    datas=(short *)malloc(sizeof(short)*NPOINT);
    data=(float *)malloc(sizeof(float)*NPOINT);
    htilde=(float *)malloc(sizeof(float)*NPOINT);
    output=(float *)malloc(sizeof(float)*NPOINT);
    ringtilde=(float *)malloc(sizeof(float)*NPOINT);
    template=(float *)malloc(sizeof(float)*NPOINT);
    mean_pow_spec=(float *)malloc(sizeof(float)*(NPOINT/2+1));
    twice_inv_noise=(float *)malloc(sizeof(float)*(NPOINT/2+1));

    /* manufacture quasinormal ring data; obtain length of signal */
    ring = NULL;
    len = qn_qring(psi0, eps, mass, spin, 1.0/srate, ATTEN, n, &ring);

    /* normalize quasinormal ring to one megaparsec */
    scale = HSCALE*M_SOLAR/MPC;
    for (i=0; i<len; i++) ringtilde[i] = ring[i] *= scale;
    for (i=len; i<n; i++) ringtilde[i] = ring[i] = 0;

    /* FFT the quasinormal ring waveform */
    realft(ringtilde-1, n, 1);
    if (n<len+2*safe) abort();

    while (1) {
        /* fill buffer with number of points needed */
        code = fill_buffer();
    }
}

```

```

/* if no points left, we are done! */
if (code==0) break;

/* if just entering a new locked stretch, reset averaging over power spectrum */
if (code==1) {
    norm = 0;
    clear(mean_pow_spec, n/2+1, 1);

    /* decay time in seconds: set to 15 x length of NPOINT sample */
    decaytime = 15.0*n/srate;
    decay = exp(-1.0*n/(srate*decaytime));
}

/* copy data into floats */
for (i=0; i<NPOINT; i++) data[i] = datas[i];

/* inject a time-domain signal before FFT (note output is used as temp storage only) */
qn_inject(data, ring, response, output, invMpc, (int)(srate*(ringstart-datastart)), n, len);

/* compute the FFT of data */
realft(data-1, n, 1);

/* normalized dL/L tilde */
product(htilde, data, response, n/2);

/* update auto-regressive mean power spectrum */
avg_inv_spec(FLO, srate, n, decay, &norm, htilde, mean_pow_spec, twice_inv_noise);

/* normalize the ring to produce a template */
qn_normalize(template, ringtilde, twice_inv_noise, n, &tmpl_norm);

/* calculate the filter output and find its maximum */
find_ring(htilde, template, twice_inv_noise, output, n, len, safe, &off, &snr, &mean, &var);

/* perform diagnostics on filter output */
if (snr<THRESHOLD) { /* threshold not exceeded: print a short message */
    printf("max snr: %.2f (offset %6d) ", snr, off);
    printf("data start: %.2f variance: %.5f\n", datastart, var);
} else { /* threshold exceeded */
    /* estimate distance to signal (template distance [Mpc] = 1 / tmpl_norm) */
    dist = 2/(tmpl_norm*snr);
    printf("\nMax SNR: %.2f (offset %d) variance %f\n", snr, off, var);
    printf("    If ringdown, estimated distance: %f Mpc, ", dist);
    printf("start time: %f\n", datastart+off/srate);
    /* See if time domain statistics are non-Gaussian */
    if (is_gaussian(datas, n, -2048, 2047, 1))
        printf("    POSSIBLE RINGDOWN: Distribution does not appear to have outliers\n\n");
    else
        printf("    Distribution has outliers! Reject\n\n");
}

/* shift ends of buffer to the start */
diff = len + 2*safe; /* safety is applied at beginning and end of buffer */
needed = NPOINT - diff;
for (i=0; i<diff; i++) datas[i] = datas[i+needed];
}

return 0;

```

```

}

/* this routine gets the data, overlapping the data buffer as needed */
int fill_buffer()
{
    static FILE *fpifo,*fplock;
    static int first=1,remain=0,num_sent=0;
    float tstart;
    int i,temp,code=2,diff=NPOINT-needed;

    if (first) { /* on first call only */
        FILE *fpss;
        first = 0;
        diff = 0;
        /* open the IFO output file, lock file, and swept-sine file */
        fpifo = grasp_open("GRASP_DATAPATH","channel.0");
        fplock = grasp_open("GRASP_DATAPATH","channel.10");
        fpss = grasp_open("GRASP_DATAPATH","swept-sine.ascii");
        /* get the response function and put in scaling factor */
        normalize_gw(fpss,NPOINT,srate,response);
        for (i=0;i<NPOINT;i++) response[i] *= HSCALE/ARMLENGTH;
        fclose(fpss);
    }

    if (num_sent==DATA_SEGMENTS) return 0;

    /* if new locked section, skip forward */
    while (remain<needed) {
        fprintf(stderr,"\nEnter new locked set of data\n");
        temp = get_data(fpifo,fplock,&tstart,MIN_INT0_LOCK*60*srate,datas,&remain,&srate,1);
        if (temp==0) return 0;

        /* number of points needed will be full length */
        needed = NPOINT;
        diff = 0;
        code = 1;
    }

    /* get the needed data and compute the start time of the buffer */
    temp = get_data(fpifo,fplock,&tstart,needed,datas+diff,&remain,&srate,0);
    if (temp==0) return 0;
    datastart = tstart - diff/srate;

    num_sent++;
    return code;
}

```

## 6.16 Structure: `struct qnTemplate`

The structure that will hold the filters for quasinormal ringdown waveforms is: `struct qnTemplate{`

`int num:` The number of the particular filter.

`float freq:` The central frequency of the filter template.

`float qual:` The quality of the filter template.

`};`

The actual filter data that corresponds to the parameters set by the fields `freq` and `qual` is generated by the routine `qn_filter()` above.

## 6.17 Structure: `struct qnScope`

The structure `struct qnScope` specifies a domain of parameter space and contains a set of templates that cover this domain. The fields of this structure are: `struct qnScope{`

`int n_tmplt:` The total number of templates required to cover the region in parameter space. This is typically set by `qn_template_grid()`.

`float freq_min:` The minimum frequency of the region of parameter space.

`float freq_max:` The maximum frequency of the region of parameter space.

`float qual_min:` The minimum quality of the region of parameter space.

`float qual_max:` The maximum quality of the region of parameter space.

`struct qnTemplate *templates:` Pointer to the array of templates. This pointer is usually set by `qn_template_grid()` when it allocates the memory necessary to store the templates and creates the necessary templates.

`};`

Although we are interested in the physical parameters, such as the mass and angular momentum, of the black hole sources of gravitational radiation, it will be more convenient to work with the frequency and quality parameters of damped sinusoids when creating detection templates. For the fundamental quadrupole quasinormal mode, there is a one-to-one correspondence between the mass and angular momentum parameters and the frequency and quality parameters which is approximately given by Echeverria [13].



## 6.18 Function: `qn_template_grid()`

```
void qn_template_grid(float dl, struct qnScope *grid)
```

This function is responsible for allocating the memory for a grid of templates on the parameter space and for choosing the location of the templates. The arguments are:

`dl`: Input. The length of the 'sides' of the square templates. This quantity should be set to  $dl = \sqrt{(2ds_{\text{threshold}}^2)}$  (see the discussion below).

`grid`: Input/Output. The grid of templates of type `struct qnScope`. On input, the fields that relate to parameter ranges should be set. On output, the field `n_tmplt` is set to the number of templates generated, and these templates are put into the array field `templates[0..n_tmplt-1]` (which is allocated by the function).

The function `qn_template_grid()` attempts to create a set of templates,  $\{u_i(t)\}$ , which "cover" parameter space finely enough that the distance between an arbitrary point on the parameter space and one of the templates is small. A precise statement of this goal, and how it is achieved, can be found in the paper by Owen [5]. We highlight the relevant parts of reference [5] here.

The templates  $\{u_i(t)\}$  are damped sinusoids with a set of frequency and quality parameters  $\{(f, Q)_i\}$ . They are normalized so that  $(u_i|u_i) = 1$  where  $(\cdot|\cdot)$  is the inner product defined by Cutler and Flanagan [11]. Since we are most interested in the high quality region of parameter space, it is a good approximation that the value of the one-sided noise power spectrum is approximately constant,  $S_h(f) \approx S_h(f_i)$ , over the frequency band of the template. This approximation simplifies the form of the inner product as the noise power spectrum appears in the inner product as a weighting function.

In order to estimate how close together the templates must be, we define the distance function  $ds_{ij}^2 = 1 - (u_i|u_j)$  corresponding to the mismatch between the two templates  $u_i$  and  $u_j$ . This interval can be expressed in terms of a metric as  $ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta$  where  $x^\alpha = (f, Q)^\alpha$  are coordinates on the two dimensional parameter space. Such an expression is only valid for sufficiently close points on parameter space. In the limit of a continuum of templates over parameter space, the metric can be evaluated by  $g_{\alpha\beta} = -\frac{1}{2}(u|\partial_\alpha\partial_\beta u)$  where  $\partial_\alpha$  is a partial derivative with respect to the coordinate  $x^\alpha$ . We find that the mismatch between templates that differ in frequency by  $df$  and in quality by  $dQ$  is given by

$$ds^2 = \frac{1}{8} \left\{ \frac{3 + 16Q^4}{Q^2(1 + 4Q^2)^2} dQ^2 - 2 \frac{3 + 4Q^2}{fQ(1 + 4Q^2)} dQ df + \frac{3 + 8Q^2}{f^2} df^2 \right\} \quad (6.18.1)$$

$$\approx \frac{1}{8} \frac{dQ^2}{Q^2} - \frac{1}{4} \frac{dQ}{Q} \frac{df}{f} + Q^2 \frac{df^2}{f^2}. \quad (6.18.2)$$

In the approximate metric of equation (6.18.2), we have kept only the dominant term in the limit of high quality. The minimum number of templates,  $\mathcal{N}$ , required to span the parameter space such that there is no point on parameter space that is a distance larger than  $ds_{\text{threshold}}^2$  from the nearest template can be found by integrating the volume element  $\sqrt{\det g_{\alpha\beta}}$  over the parameter space. Using the approximate metric and the parameter ranges  $Q \leq Q_{\text{max}}$  and  $f \in [f_{\text{min}}, f_{\text{max}}]$ , we find that the number of templates required is

$$\begin{aligned} \mathcal{N} &\approx \frac{1}{4\sqrt{2}} (ds_{\text{threshold}}^2)^{-1} Q_{\text{max}} \log(f_{\text{max}}/f_{\text{min}}) \\ &\approx 2700 \left( \frac{ds_{\text{threshold}}^2}{0.03} \right)^{-1} \left( \frac{Q_{\text{max}}}{100} \right) \left\{ 1 + \frac{1}{\log 100} \left[ \log \left( \frac{f_{\text{max}}}{10 \text{ kHz}} \right) - \log \left( \frac{f_{\text{min}}}{100 \text{ Hz}} \right) \right] \right\}. \end{aligned} \quad (6.18.3)$$

The issue of template placement is more difficult than computing the number of templates required. Fortunately, for the problem of quasinormal ringdown template placement, the metric is reasonably simple.

By using the coordinate  $\phi = \log f$  rather than  $f$ , we see that the metric components depend on  $Q$  alone. We can exploit this property for the task of template placement as follows: First, choose a "surface" of constant  $Q = Q_{\min}$ , and on this surface place templates at intervals in  $\phi$  of  $d\phi = dl/g_{\phi\phi}$  for the entire range of  $\phi$ . Here,  $dl = \sqrt{(2ds_{\text{threshold}}^2)}$ . Then choose the next surface of constant  $Q$  with  $dQ = dl/g_{QQ}$  and repeat the placement of templates on this surface. This can be iterated until the entire range of  $Q$  has been covered; the collection of templates should now cover the entire parameter region with no point in the region being farther than  $ds_{\text{threshold}}^2$  from the nearest template.

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## 7 GRASP Routines: Stochastic background detection

### 7.1 Data File: detectors.dat

This file contains site location and orientation information, a convenient name for the detector, and filenames for the detector noise power spectrum and whitening filter, for 11 different detector sites. These site are:

- (1) Hanford, Washington LIGO site,
- (2) Livingston, Louisiana LIGO site,
- (3) VIRGO site,
- (4) GEO-600 site,
- (5) Garching site,
- (6) Glasgow site,
- (7) MIT 5 meter interferometer,
- (8) Caltech 40 meter interferometer,
- (9) TAMA-300 site,
- (10) TAMA-20 site,
- (11) ISAS-100 site.

As explained below, information for additional detector sites can be added to `detectors.dat` as needed.

The data contained within this file is formatted as follows: Any line beginning with a # is regarded as a comment. All other lines are assumed to begin with an integer (which is the site identification number) followed by five floating point numbers and three character strings, each separated by *white* space (i.e., one or more spaces, which may include tabs). The first two floating point numbers specify the location of the central station (the central vertex of the two detector arms) on the earth's surface: The first number is the latitude measured in degrees North of the equator; the second number is the longitude measured in degrees West of Greenwich, England. The third floating point number specifies the orientation of the first arm of the detector, measured in degrees counter-clockwise from true North. The fourth floating point number specifies the orientation of the second arm of the detector, also measured in degrees counter-clockwise from true North. The fifth floating point number is the arm length, in cm. The three character strings specify: (i) a convenient name (e.g., VIRGO or GEO-600) for the detector site, (ii) the name of a data file that contains information about the noise power spectrum of the detector, and (iii) the name of a data file that contains information about the spectrum of the whitening filter of the detector. (We will say more about the content and format of these two data files in Secs. 7.3 and 7.4.) The information currently contained in `detectors.dat` is shown below:

```
#
# Hanford, Washington LIGO Site (initial detector)
# Fred Raab fjr@ligo.caltech.edu
1 46.45236 119.40753 36.8 126.8 4.e5 LIGO-WA_init noise_ligo_init.dat whiten_ligo_init.dat
#
# Livingston, Louisiana LIGO Site (initial detector)
# Fred Raab fjr@ligo.caltech.edu
2 30.56277 90.77425 108.0 198.0 4.e5 LIGO-LA_init noise_ligo_init.dat whiten_ligo_init.dat
#
# VIRGO Site
# Biplab Bhawal biplab@iucaa.iucaa.ernet.in
# 3 43.3 -10.1 71.5 341.5
# Raffaele Flaminio flaminio@lapphp0.in2p3.fr
# Carlo Bradaschia BRADASCHIA@VAXPIA.PI.INFN.IT
# Rosa Poggiani POGGIANI@pisa.infn.it
3 43.6333 -10.5 71.5 341.5 3.e5 VIRGO noise_virgo.dat whiten_virgo.dat
```

```

#
# GEO-600 as of April 1995
# Albrecht Ruediger atr@mpg.mpg.de
4 52.2467 -9.82167 25.94 291.61 6.e4 GEO-600 noise_geo.dat whiten_geo.dat
#
# Garching 30 Meter Interferometer
# Albrecht Ruediger atr@mpg.mpg.de
5 48.244 -11.675 329.0 239.0 3.e3 Garching-30 XXXXX XXXXX
#
# Glasgow 10 Meter Interferometer
# Albrecht Ruediger atr@mpg.mpg.de
# 6 55.86 4.23 77.0 167.0
# Jim Hough hough@physics.gla.ac.uk
6 55.8667 4.28333 62.0 152.0 1.e3 Glasgow-10 XXXXX XXXXX
#
# MIT 5 Meter Interferometer
# Gabriela Gonzalez gg@tristan.mit.edu
7 42.3667 71.1 34.5 304.5 5.e2 MIT-5 XXXXX XXXXX
#
# Caltech 40 Meter Interferometer NEEDS CORRECTION
# Fred Raab fjr@ligo.caltech.edu
8 34.1667 118.133 180.0 270.0 4.e3 Caltech-40 noise_40.dat whiten_40.dat
#
# TAMA 300 Meter
# Masa-Katsu Fujimoto fujimoto@gravity.mtk.nao.ac.jp
9 35.6766 -139.536 90.0 180.0 3.0e4 TAMA-300 noise_tama.dat whiten_tama.dat
#
# TAMA 20 Meter
# Masa-Katsu Fujimoto fujimoto@gravity.mtk.nao.ac.jp
10 35.6751 -139.536 45.0 315.0 2.0e3 TAMA-20 XXXXX XXXXX
#
# ISAS 100 Meter delay line
# Hide Mizuno hide@pleiades.sci.isas.ac.jp
11 35.5678 -139.467 42.0 135.0 1.0e4 ISAS-100 XXXXX XXXXX
#

```

Site information for new (or hypothetical) detectors can be added to detectors.dat by simply adhering to the above data format. For example, as the noise in the LIGO detectors improves, one can accommodate these changes in detectors.dat by adding additional lines that have the same site location and orientation information as the "old" detectors, but refer to different noise power spectra and whitening filter data files. The only other requirement is that the site identification numbers for these "new and improved" detectors be different from the old site identification numbers, so as to avoid any ambiguity. Explicitly, one could add the following lines to detectors.dat to include information about the advanced LIGO detectors:

```

#
# Hanford, Washington LIGO Site (advanced detector)
# Fred Raab fjr@ligo.caltech.edu
12 46.45236 119.40753 36.8 126.8 4.e5 LIGO-WA_adv noise_ligo_adv.dat whiten_ligo_adv.dat
#
# Livingston, Louisiana LIGO Site (advanced detector)
# Fred Raab fjr@ligo.caltech.edu
13 30.56277 90.77425 108.0 198.0 4.e5 LIGO-LA_adv noise_ligo_adv.dat whiten_ligo_adv.dat
#

```

The file `detectors.dat` currently resides in the `parameters` subdirectory of GRASP. In order for the stochastic background routines and example programs that are defined in the following sections to be able to access the information contained in this file, the user must set the environment variable `GRASP_PARAMETERS` to point to this directory. For example, a command like:

```
setenv GRASP_PARAMETERS /usr/local/GRASP/parameters
```

should do the trick. If, however, you want to modify this file (e.g., to add another detector or to add another noise curve), then just copy the `detectors.dat` file to your own home directory, modify it, and set the `GRASP_PARAMETERS` environment variable to point to this directory.

Comment: If you happen to find an error in the `detectors.dat` file, *please* communicate it to the caretakers of GRASP.

## 7.2 Function: `detector_site()`

```
void detector_site(char *detectors_file, int site_choice, float site_parameters[9],
char *site_name, char *noise_file, char *whiten_file)
```

This function calculates the components of the position vector of the central station, and the components of the two vectors that point along the directions of the detector arms (from the central station to each end station), for a given choice of detector site, using information contained in an input data file. This function also outputs three character strings that specify the site name, the name of a data file containing the detector noise power information, and the name of a data file containing information about the detector whitening filter, respectively.

The arguments of `detector_site()` are:

`detectors_file`: Input. A character string that specifies the name of a data file containing detector site information. This file is most likely the `detectors.dat` data file described in Sec. 7.1. If the file is different from `detectors.dat`, it must have the same data format as `detectors.dat`, and it must reside in the directory pointed to by the `GRASP_PARAMETERS` environment variable (which you may set as you wish). If you want to use the `detectors.dat` file distributed with GRASP, use a command like:

```
setenv GRASP_PARAMETERS /usr/local/GRASP/parameters
```

to point to the directory containing this file. If you want to modify this file (e.g., to add another detector or to add another noise curve), then just copy the `detectors.dat` file to your own home directory, modify it, and set the `GRASP_PARAMETERS` environment variable to point to this directory.

`site_choice`: Input. An integer value used as an index into the input data file. The value of `site_choice` should be chosen to match the site identification number for one of the detectors contained in this file.

`site_parameters`: Output. `site_parameters[0..8]` is an array of nine floating point variables that define the position of the central station of the detector site and the orientation of its two arms. The three-vector `site_parameters[0..2]` are the  $(x, y, z)$  components (in cm) of the position vector of the central station, as measured in a reference frame with the origin at the center of the earth, the  $z$ -axis exiting the North pole, and the  $x$ -axis passing out the line of  $0^\circ$  longitude. The three-vector `site_parameters[3..5]` are the  $(x, y, z)$  components (in cm) of a vector pointing along the direction of the first arm (from the central station to the end station). The three-vector `site_parameters[6..8]` are the  $(x, y, z)$  components (in cm) of a vector pointing along the direction of the second arm (from the central station to the end station).

`site_name`: Output. A character string that specifies a convenient name (e.g., VIRGO or GEO-600) for the chosen detector site.

`noise_file`: Output. A character string that specifies the name of a data file containing information about the noise power spectrum of the detector. (See Sec. 7.3 for more details regarding the content and format of this data file.)

`whiten_file`: Output. A character string that specifies the name of a data file containing information about the spectrum of the whitening filter of the detector. (See Sec. 7.4 for more details regarding the content and format of this data file.)

`detector_site()` reads input data from the file specified by `detectors_file`. This file is searched (linearly from top to bottom) until the value of `site_choice` matches the site identification number for one of the detectors contained in this file. The site location and orientation information for the chosen detector site are then read into variables local to `detector_site()`. The values contained in

the array `site_parameters[]` are calculated from these input variables using standard equations from spherical analytic geometry. (A correction is made, however, for the oblateness of the earth, using information contained in Ref. [22].) The `site_name`, `noise_file`, and `whiten_file` character strings are simply copied from input data file. If `site_choice` does not match any of the site identification numbers, `detector_site()` prints out an error message and aborts execution.

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Comments: None.

### 7.3 Function: noise\_power()

void noise\_power(char \*noise\_file, int n, float delta\_f, double \*power)

This function calculates the noise power spectrum  $P(f)$  of a detector at a given set of discrete frequency values, using information contained in a data file.

The arguments of noise\_power() are:

**noise\_file:** Input. A character string that specifies the name of a data file containing information about the noise power spectrum  $P(f)$  of a detector. Like the detectors.dat file described in Sec. 7.1, the noise power data file should reside in the directory pointed to by the GRASP\_PARAMETERS environment variable (which you may set as you wish). If you want to use the noise power spectrum data files distributed with GRASP, use a command like:

```
setenv GRASP_PARAMETERS /usr/local/GRASP/parameters
```

to point to the directory containing these files. If you want to use your own noise power spectrum data files, then simply set the GRASP\_PARAMETERS environment variable to point to the directory containing these files. Note, however, that if a program needs to access *both* detector site information and noise power spectrum data, then all of the files containing this information should reside in the *same* directory. (A similar remark applies for the whitening filter data files described in Sec. 7.4.)

**n:** Input. The number  $N$  of discrete frequency values at which the noise power spectrum  $P(f)$  is to be evaluated.

**delta\_f:** Input. The spacing  $\Delta f$  (in Hz) between two adjacent discrete frequency values:  $\Delta f := f_{i+1} - f_i$ .

**power:** Output. power[0..n-1] is an array of double precision variables containing the values of the noise power spectrum  $P(f)$ . These variables have units of strain<sup>2</sup>/Hz (or seconds). power[i] contains the value of  $P(f)$  evaluated at the discrete frequency  $f_i = i\Delta f$ , where  $i = 0, 1, \dots, N - 1$ .

The input data file specified by noise\_file contains information about the noise power spectrum  $P(f)$  of a detector. The data contained in this file is formatted as follows: Any line beginning with a # is regarded as a comment. All other lines are assumed to consist of two floating point numbers separated by white space. The first floating point number is a frequency  $f$  (in Hz); the second floating point number is the square root of the *one-sided* noise power spectrum  $P(f)$ , evaluated at  $f$ .  $P(f)$  is defined by equation (3.18) of Ref. [21]:

$$\langle \tilde{n}^*(f)\tilde{n}(f') \rangle =: \frac{1}{2}\delta(f - f') P(f). \quad (7.3.1)$$

Here  $\langle \rangle$  denotes ensemble average, and  $\tilde{n}(f)$  is the frequency spectrum (i.e., Fourier transform) of the strain  $n(t)$  produced by the noise intrinsic to the detector.  $P(f)$  is a non-negative real function, having units of strain<sup>2</sup>/Hz (or seconds). It is defined with a factor of 1/2 to agree with the standard definition used by instrument builders. The total noise power is the integral of  $P(f)$  over all frequencies from 0 to  $\infty$  (not from  $-\infty$  to  $\infty$ ). Hence the name *one-sided*.

Since the frequency values contained in the input data file need not agree with the desired frequencies  $f_i = i\Delta f$ , noise\_power() must determine the desired values of the noise power spectrum by doing an interpolation/extrapolation on the input data. noise\_power() performs a cubic spline interpolation, using the *Numerical Recipes in C* routines spline() and splint(). noise\_power() assumes that the length of the input data is  $\leq 65536$ , and it uses boundary conditions for a natural spline (i.e., with zero second derivative on the two boundaries). noise\_power() also squares the output of the splint() routine, since the desired values are  $P(f)$ —and not their square roots (which are contained in the input data file).



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Comments: In order for the cubic spline interpolation routines to yield approximations to  $P(f)$  that are not contaminated by spurious DC or low frequency (e.g., approximately 1 Hz) components, it is important that the input data file specified by `noise_file` contain noise power information down to, and including, zero Hz. This information can be added in "by hand," for example, if the experimental data for the noise power spectrum only goes down to 1 Hz. In this case, setting the values of  $\sqrt{P(f)}$  at 0.0, 0.1, 0.2, ..., 0.9 Hz equal to its 1 Hz value seems to be sufficient. (See Sec. 7.4 for a similar comment regarding `whiten()`.)

## 7.4 Function: `whiten()`

`void whiten(char *whiten_file, int n, float delta_f, double *whiten_out)`

This function calculates the real and imaginary parts of the spectrum  $\tilde{W}(f)$  of the whitening filter of a detector at a given set of discrete frequency values, using information contained in a data file.

The arguments of `whiten()` are:

`whiten_file`: Input. A character string that specifies the name of a data file containing information about the spectrum  $\tilde{W}(f)$  of the whitening filter of a detector. Like the `detectors.dat` and noise power spectrum data files described in Secs. 7.1 and 7.3, the whitening filter data file should reside in the directory pointed to by the `GRASP_PARAMETERS` environment variable (which you may set as you wish). If you want to use the whitening filter data files distributed with GRASP, use a command like:

```
setenv GRASP_PARAMETERS /usr/local/GRASP/parameters
```

to point to the directory containing these files. If you want to use your own whitening filter data files, then simply set the `GRASP_PARAMETERS` environment variable to point to the directory containing these files. Note, however, that if a program also needs to access either detector site information or noise power spectrum data, then all of the files containing this information should reside in the *same* directory.

`n`: Input. The number  $N$  of discrete frequency values at which the real and imaginary parts of the spectrum  $\tilde{W}(f)$  of the whitening filter are to be evaluated.

`delta_f`: Input. The spacing  $\Delta f$  (in Hz) between two adjacent discrete frequency values:  $\Delta f := f_{i+1} - f_i$ .

`whiten_out`: Output. `whiten_out[0..2*n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\tilde{W}(f)$  of the whitening filter. These variables have units rHz/strain (or  $\text{sec}^{-1/2}$ ), which are inverse to the units of the square root of the noise power spectrum  $P(f)$ . `whiten_out[2*i]` and `whiten_out[2*i+1]` contain, respectively, the values of the real and imaginary parts of  $\tilde{W}(f)$  evaluated at the discrete frequency  $f_i = i\Delta f$ , where  $i = 0, 1, \dots, N - 1$ .

The input data file specified by `whiten_file` contains information about the spectrum  $\tilde{W}(f)$  of the whitening filter of a detector. The data contained in this file is formatted as follows: Any line beginning with a # is regarded as a comment. All other lines are assumed to consist of three floating point numbers, each separated by white space. The first floating point number is a frequency  $f$  (in Hz). The second and third floating point numbers are, respectively, the real and imaginary parts of the spectrum  $\tilde{W}(f)$ , evaluated at  $f$ . These last two numbers have units of rHz/strain (or  $\text{sec}^{-1/2}$ ). This is because the whitening filter is, effectively, the inverse of the amplitude  $\sqrt{P(f)}$  of the noise power spectrum.

Since the frequency values contained in the input data file need not agree with the desired frequencies  $f_i = i\Delta f$ , `whiten()` must determine the desired values of the real and imaginary parts of the spectrum of the whitening filter by doing an interpolation/extrapolation on the input data. Similar to `noise_power()` (see Sec. 7.3), `whiten()` performs a cubic spline interpolation, using the `spline()` and `splint()` routines from *Numerical Recipes in C*. Like `noise_power()`, `whiten()` assumes that the length of the input data is  $\leq 65536$ , and it uses boundary conditions for a natural spline. Unlike `noise_power()`, `whiten()` does not have to square the output of the `splint()` routine, since the data contained in the input file and the desired output data both have the same form (i.e., both involve just the real and imaginary parts of  $\tilde{W}(f)$ ).

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Comments: In order for the cubic spline interpolation routines to yield approximations to  $\bar{W}(f)$  that are not contaminated by spurious DC or low frequency (e.g., approximately 1 Hz) components, it is important that the input data file specified by `whiten_file` contain information about the whitening filter down to, and including, zero Hz. This information can be added in "by hand," for example, if the experimental data for the spectrum of the whitening filter only goes down to 1 Hz. In this case, setting the values of  $\bar{W}(f)$  at 0.0, 0.1, 0.2, ..., 0.9 Hz equal to their 1 Hz values seems to be sufficient. (See Sec. 7.3 for a similar comment regarding `noise_power()`.)

Also, for the initial and advanced LIGO detector noise models, the spectra  $\bar{W}(f)$  of the whitening filters contained in the input data files were constructed by simply inverting the square roots of the corresponding noise power spectra  $P(f)$ . The spectra of the whitening filters thus constructed are *real*. Although this method of obtaining information about the spectra of the whitening filters is fine for simulation purposes, the data contained in the actual whitening filter input data files will be obtained *independently* from that contained in the noise power spectra data files, and the spectra  $\bar{W}(f)$  will in general be complex. The function `whiten()` described above—and all other stochastic background routines—allow for this more general form of whitening filter data.

## 7.5 Function: overlap()

```
void overlap(float *site1_parameters, float *site2_parameters, int n, float
delta_f, double *gamma12)
```

This function calculates the values of the overlap reduction function  $\gamma(f)$ , which is the averaged product of the response of a pair of detectors to an isotropic and unpolarized stochastic background of gravitational radiation.

The arguments of `overlap()` are:

`site1_parameters`: Input. `site1_parameters[0..8]` is an array of nine floating point variables that define the position of the central station of the first detector site and the orientation of its two arms. The three-vector `site1_parameters[0..2]` are the  $(x, y, z)$  components (in cm) of the position vector of the central station of the first site, as measured in a reference frame with the origin at the center of the earth, the  $z$ -axis exiting the North pole, and the  $x$ -axis passing out the line of  $0^\circ$  longitude. The three-vector `site1_parameters[3..5]` are the  $(x, y, z)$  components (in cm) of a vector pointing along the direction of the first arm of the first detector (from the central station to the end station). The three-vector `site1_parameters[6..8]` are the  $(x, y, z)$  components (in cm) of a vector pointing along the direction of the second arm of the first detector (from the central station to the end station).

`site2_parameters`: Input. `site2_parameters[0..8]` is an array of nine floating point variables that define the position of the central station of the second detector site and the orientation of its two arms, in exactly the same format as the previous argument.

`n`: Input. The number  $N$  of discrete frequency values at which the overlap reduction function  $\gamma(f)$  is to be evaluated.

`delta_f`: Input. The spacing  $\Delta f$  (in Hz) between two adjacent discrete frequency values:  $\Delta f := f_{i+1} - f_i$ .

`gamma12`: Output. `gamma12[0..n-1]` is an array of double precision variables containing the values of the overlap reduction  $\gamma(f)$  for the two detector sites. These variables are dimensionless. `gamma12[i]` contains the value of  $\gamma(f)$  evaluated at the discrete frequency  $f_i = i\Delta f$ , where  $i = 0, 1, \dots, N - 1$ .

The values of  $\gamma(f)$  calculated by `overlap()` are defined by equation (3.9) of Ref. [21]:

$$\gamma(f) := \frac{5}{8\pi} \int_{S^2} d\hat{\Omega} e^{2\pi i f \hat{\Omega} \cdot \Delta \vec{x} / c} \left( F_1^+ F_2^+ + F_1^\times F_2^\times \right). \quad (7.5.1)$$

Here  $\hat{\Omega}$  is a unit-length vector on the two-sphere,  $\Delta \vec{x}$  is the separation vector between the two detector sites, and  $F_i^{+, \times}$  is the response of detector  $i$  to the  $+$  or  $\times$  polarization. For the first detector ( $i = 1$ ) one has

$$F_1^{+, \times} = \frac{1}{2} \left( \hat{X}_1^a \hat{X}_1^b - \hat{Y}_1^a \hat{Y}_1^b \right) e_{ab}^{+, \times}(\hat{\Omega}), \quad (7.5.2)$$

where the directions of the first detector's arms are defined by  $\hat{X}_1^a$  and  $\hat{Y}_1^a$ , and  $e_{ab}^{+, \times}(\hat{\Omega})$  are the spin-two polarization tensors for the "plus" and "cross" polarizations, respectively. (A similar expression can be written down for the second detector.) The normalization of  $\gamma(f)$  is determined by the following statement: For coincident and coaligned detectors (i.e., for two detectors located at the same place, with both pairs of arms pointing in the same directions),  $\gamma(f) = 1$  for all frequencies.

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Comments: None.

## 7.6 Example: overlap program

The following example program shows one way of combining the functions `detector_site()` and `overlap()` to calculate the overlap reduction function  $\gamma(f)$  for a given pair of detectors. In particular, we calculate  $\gamma(f)$  for the Hanford, WA and Livingston, LA LIGO detector sites. The resulting overlap reduction function data is stored as two columns of double precision numbers ( $f_i$  and  $\gamma(f_i)$ ) in the file `LIGO_overlap.dat`. Here  $f_i = i\Delta f$  with  $i = 0, 1, \dots, N - 1$ . The values of  $N$  and  $\Delta f$  are input parameters to the program, which the user can change if he/she desires. (See the `#define` statements listed at the beginning of the program.) Also, by changing the site location identification numbers and the output file name, the user can calculate and save the overlap reduction function for *any* pair of detectors—e.g., the Hanford, WA LIGO detector and the GEO-600 detector; the GEO-600 and VIRGO detector; the Garching and Glasgow detectors; etc. The overlap reduction function data that is stored in the file can then be displayed with `xmgr`, for example. (See Fig. 47.)

```
/* main program to illustrate the function overlap() */

#include "grasp.h"

#define DETECTORS_FILE "detectors.dat" /* file containing detector info */
#define SITE1_CHOICE 1 /* 1=LIGO-Hanford site */
#define SITE2_CHOICE 2 /* 2=LIGO-Livingston site */
#define N 10000 /* number of frequency points */
#define DELTA_F 1.0 /* frequency spacing (in Hz) */
#define OUT_FILE "LIGO_overlap.dat" /* output filename */

int main(int argc, char **argv)
{
    int i;
    double f;

    float sitel_parameters[9], site2_parameters[9];
    char sitel_name[100], noise1_file[100], whiten1_file[100];
    char site2_name[100], noise2_file[100], whiten2_file[100];

    double *gamma12;

    FILE *fp;
    fp=fopen(OUT_FILE, "w");

    /* ALLOCATE MEMORY */
    gamma12=(double *)malloc(N*sizeof(double));

    /* CALL DETECTOR_SITE() TO GET SITE PARAMETER INFORMATION */
    detector_site(DETECTORS_FILE, SITE1_CHOICE, sitel_parameters, sitel_name,
                 noise1_file, whiten1_file);
    detector_site(DETECTORS_FILE, SITE2_CHOICE, site2_parameters, site2_name,
                 noise2_file, whiten2_file);

    /* CALL OVERLAP() AND WRITE DATA TO THE FILE */
    overlap(sitel_parameters, site2_parameters, N, DELTA_F, gamma12);

    for (i=0; i<N; i++) {
        f=i*DELTA_F;
        fprintf(fp, "%e %e\n", f, gamma12[i]);
    }
}
```

```
fclose(fp);  
return 0;  
}
```

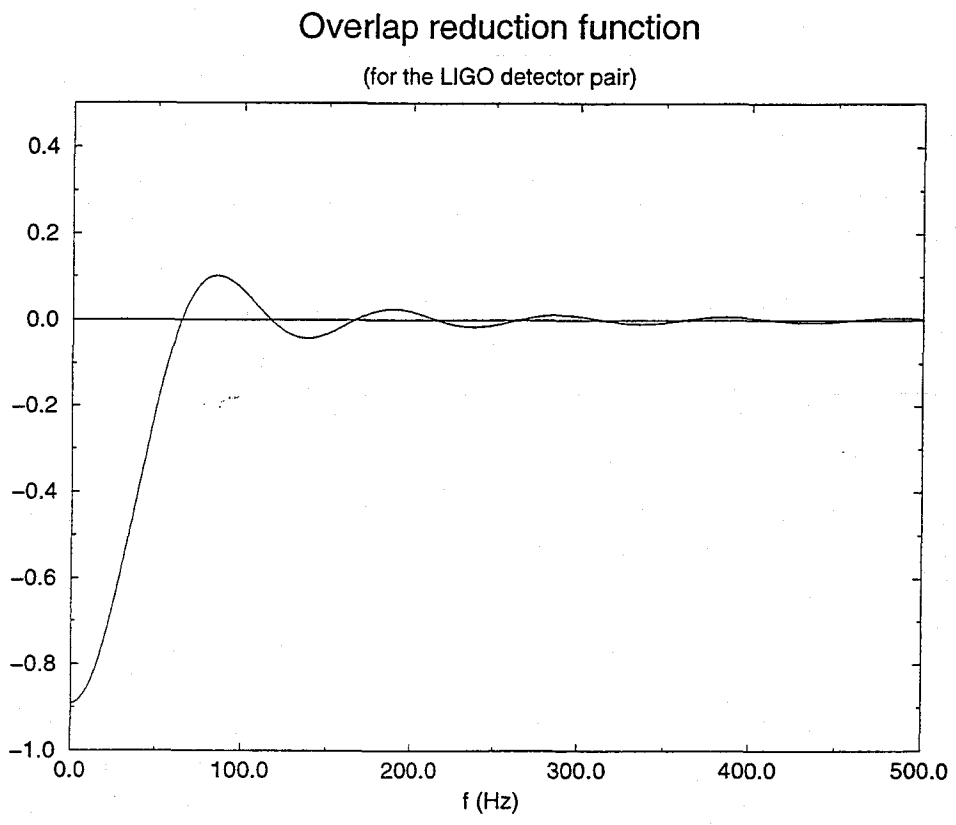


Figure 47: The overlap reduction function  $\gamma(f)$  for the Hanford, WA and Livingston, LA LIGO detector pair.

## 7.7 Function: `get_IFO12()`

`get_IFO12(FILE *fp1, FILE *fp2, FILE *fp1lock, FILE *fp2lock, int n, float *out1, float *out2, float *srate1, float *srate2)`

This function gets real interferometer output (IFO) data from two detector sites.

The arguments of `get_IFO12()` are:

`fp1`: Input. A pointer to a file that contains the interferometer output (IFO) data produced by the first detector.

`fp2`: Input. A pointer to a file that contains the interferometer output (IFO) data produced by the second detector.

`fp1lock`: Input. A pointer to a file that contains the TTL lock signal for the interferometer output produced by the first detector.

`fp2lock`: Input. A pointer to a file that contains the TTL lock signal for the interferometer output produced by the second detector.

`n`: Input. The number  $N$  of data points to be retrieved.

`out1`: Output. `out1[0..n-1]` is an array of floating point variables containing the values of the interferometer output produced by the first detector. These variables have units of ADC counts. `out1[i]` contains the value of the whitened data stream  $o_1(t)$  evaluated at the discrete time  $t_i = i\Delta t_1$ , where  $i = 0, 1, \dots, N - 1$  and  $\Delta t_1$  is the sampling period of the first detector, defined below.

`out2`: Output. `out2[0..n-1]` is an array of floating point variables containing the values of the interferometer output produced by the second detector, in exactly the same format as the previous argument.

`srate1`: Output. The sample rate  $\Delta f_1$  (in Hz) of the first detector.  $\Delta t_1 := 1/\Delta f_1$  (in sec) is the corresponding sampling period of the first detector.

`srate2`: Output. The sample rate  $\Delta f_2$  (in Hz) of the second detector.  $\Delta t_2 := 1/\Delta f_2$  (in sec) is the corresponding sampling period of the second detector.

`get_IFO12()` consists effectively of two calls to `get_data()`, which is described in detail in Sec. 3.6. It prints out a warning message if no data remains for one or both detectors. For that case, both `out1[]` and `out2[]` are set to zero.

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Comments: Currently, `get_IFO12()` calls `get_data()` and `get_data2()`, where `get_data2()` is simply a copy of the `get_data()` routine. `get_data()` should eventually be modified so that it can handle simultaneous requests for data from more than one detector. After this change is made, the function `get_data2()` should be removed.

## 7.8 Function: `simulate_noise()`

```
void simulate_noise(int n, float delta_t, double *power, double *whiten_out,
float *out, int *pseed)
```

This function simulates the generation of noise intrinsic to a detector. The output is a (not necessarily continuous-in-time) whitened data stream  $o(t)$  representing the detector output when only detector noise is present.

The arguments of `simulate_noise()` are:

`n`: Input. The number  $N$  of data points corresponding to an observation time  $T := N \Delta t$ , where  $\Delta t$  is the sampling period of the detector, defined below.  $N$  should equal an integer power of 2.

`delta_t`: Input. The sampling period  $\Delta t$  (in sec) of the detector.

`power`: Input. `power[0..n/2-1]` is an array of double precision variables containing the values of the noise power spectrum  $P(f)$  of the detector. These variables have units of  $\text{strain}^2/\text{Hz}$  (or seconds). `power[i]` contains the value of  $P(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

`whiten_out`: Input. `whiten_out[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\bar{W}(f)$  of the whitening filter of the detector. These variables have units  $\text{rHz}/\text{strain}$  (or  $\text{sec}^{-1/2}$ ), which are inverse to the units of the square root of the noise power spectrum  $P(f)$ . `whiten_out[2*i]` and `whiten_out[2*i+1]` contain, respectively, the values of the real and imaginary parts of  $\bar{W}(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

`out`: Output. `out[0..n-1]` is an array of floating point variables containing the values of the whitened data stream  $o(t)$  representing the output of the detector when only detector noise is present.  $o(t)$  is the convolution of detector whitening filter  $W(t)$  with the noise  $n(t)$  intrinsic to the detector. The variables `out[]` have units of  $\text{rHz}$  (or  $\text{sec}^{-1/2}$ ), which follows from the definition of  $n(t)$  as a strain and  $\bar{W}(f)$  as the “inverse” of the square root of the noise power spectrum  $P(f)$ . `out[i]` contains the value of  $o(t)$  evaluated at the discrete time  $t_i = i\Delta t$ , where  $i = 0, 1, \dots, N - 1$ .

`pseed`: Input. A pointer to a seed value, which is used by the random number generator routine.

`simulate_noise()` simulates the generation of noise intrinsic to a detector in the following series of steps:

- (i) It first constructs random variables  $\bar{n}(f_i)$  in the frequency domain that have zero mean and satisfy:

$$\langle \bar{n}^*(f_i) \bar{n}(f_j) \rangle = \frac{1}{2} T \delta_{ij} P(f_i), \quad (7.8.1)$$

where  $\langle \rangle$  denotes ensemble average. The above equation is just the discrete frequency version of Eq. (7.3.1). This equation can be realized by setting

$$\bar{n}(f_i) = \frac{1}{2} \sqrt{T} P^{1/2}(f_i) (u_i + iv_i), \quad (7.8.2)$$

where  $u_i$  and  $v_i$  are statistically independent (real) Gaussian random variables, each having zero mean and unit variance. These Gaussian random variables are produced by calls to the *Numerical Recipes in C* random number generator routine `gasdev()`.



- (ii) `simulate_noise()` then whitens the data in the frequency domain by multiplying  $\tilde{n}(f_i)$  by the frequency components  $\bar{W}(f_i)$  of the whitening filter of the detector:

$$\bar{o}(f_i) := \tilde{n}(f_i) \bar{W}(f_i). \quad (7.8.3)$$

This (complex) multiplication in the frequency domain corresponds to the convolution of  $n(t)$  and  $W(t)$  in the time domain. By convention, the DC (i.e., zero frequency) and Nyquist critical frequency components of  $\bar{o}(f_i)$  are set to zero.

- (iii) The final step consists of Fourier transforming the frequency components  $\bar{o}(f_i)$  into the time domain to obtain the whitened data stream  $o(t_i)$ . Here  $t_i = i\Delta t$  with  $i = 0, 1, \dots, N - 1$ .

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Comments: In the context of stochastic background simulations, it would be more efficient to simulate the noise at *two* detectors simultaneously. Since the time-series data are real, the two Fourier transforms that would need to be performed in step (iii) could be done simultaneously. However, for modularity of design, and to simulate noise for “single-detector” gravity-wave searches, we decided to write the above routine instead.

## 7.9 Function: simulate\_sb()

```
void simulate_sb(int n, float delta_t, float omega_0, float f_low, float f_high,
double *gamma12, double *whiten1, double *whiten2, float *out1, float *out2,
int *pseed)
```

This function simulates the generation of an isotropic and unpolarized stochastic background of gravitational radiation having a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $f_{\text{low}} \leq f \leq f_{\text{high}}$ . The outputs are (not necessarily continuous-in-time) whitened data stream  $o_1(t)$  and  $o_2(t)$  representing the detector outputs when only a stochastic background signal is present.

The arguments of `simulate_sb()` are:

`n`: Input. The number  $N$  of data points corresponding to an observation time  $T := N \Delta t$ , where  $\Delta t$  is the sampling period of the detectors, defined below.  $N$  should equal an integer power of 2.

`delta_t`: Input. The sampling period  $\Delta t$  (in sec) of the detectors.

`omega_0`: Input. The constant value  $\Omega_0$  (dimensionless) of the frequency spectrum  $\Omega_{\text{gw}}(f)$  for the stochastic background:

$$\Omega_{\text{gw}}(f) = \begin{cases} \Omega_0 & f_{\text{low}} \leq f \leq f_{\text{high}} \\ 0 & \text{otherwise.} \end{cases}$$

$\Omega_0$  should be greater than or equal to zero.

`f_low`: Input. The frequency  $f_{\text{low}}$  (in Hz) below which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background is zero.  $f_{\text{low}}$  should lie in the range  $0 \leq f_{\text{low}} \leq f_{\text{Nyquist}}$ , where  $f_{\text{Nyquist}}$  is the Nyquist critical frequency. (The Nyquist critical frequency is defined by  $f_{\text{Nyquist}} := 1/(2\Delta t)$ , where  $\Delta t$  is the sampling period of the detectors.)  $f_{\text{low}}$  should also be less than or equal to  $f_{\text{high}}$ .

`f_high`: Input. The frequency  $f_{\text{high}}$  (in Hz) above which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background is zero.  $f_{\text{high}}$  should lie in the range  $0 \leq f_{\text{high}} \leq f_{\text{Nyquist}}$ . It should also be greater than or equal to  $f_{\text{low}}$ .

`gamma12`: Input. `gamma12[0..n/2-1]` is an array of double precision variables containing the values of the overlap reduction function  $\gamma(f)$  for the two detector sites. These variables are dimensionless. `gamma12[i]` contains the value of  $\gamma(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

`whiten1`: Input. `whiten1[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\bar{W}_1(f)$  of the whitening filter of the first detector. These variables have units rHz/strain (or  $\text{sec}^{-1/2}$ ), which are inverse to the units of the square root of the noise power spectrum  $P_1(f)$ . `whiten1[2*i]` and `whiten1[2*i+1]` contain, respectively, the values of the real and imaginary parts of  $\bar{W}_1(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

`whiten2`: Input. `whiten2[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\bar{W}_2(f)$  of the whitening filter of the second detector, in exactly the same format as the previous argument.

`out1`: Output. `out1[0..n-1]` is an array of floating point variables containing the values of the whitened data stream  $o_1(t)$  representing the output of the first detector when only a stochastic background signal is present.  $o_1(t)$  is the convolution of detector whitening filter  $W_1(t)$  with the gravitational strain  $h_1(t)$ . The variables `out1[]` have units of rHz (or  $\text{sec}^{-1/2}$ ), which follows from the

definition of  $h_1(t)$  as a strain and  $\tilde{W}_1(f)$  as the “inverse” of the square root of the noise power spectrum  $P_1(f)$ . `out1[i]` contains the value of  $o_1(t)$  evaluated at the discrete time  $t_i = i\Delta t$ , where  $i = 0, 1, \dots, N - 1$ .

`out2`: Output. `out2[0..n-1]` is an array of floating point variables containing the values of the whitened data stream  $o_2(t)$  representing the output of the second detector when only a stochastic background signal is present, in exactly the same format as the previous argument.

`pseed`: Input. A pointer to a seed value, which is used by the random number generator routine.

`simulate_sb()` simulates the generation of an isotropic and unpolarized stochastic background of gravitational radiation having a constant frequency spectrum  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $f_{\text{low}} \leq f \leq f_{\text{high}}$  in the following series of steps:

- (i) It first constructs random variables  $\tilde{h}_1(f_i)$  and  $\tilde{h}_2(f_i)$  in the frequency domain that have zero mean and satisfy:

$$\langle \tilde{h}_1^*(f_i) \tilde{h}_1(f_j) \rangle = \frac{1}{2} T \delta_{ij} \frac{3H_0^2}{10\pi^2} f_i^{-3} \Omega_0 \quad (7.9.1)$$

$$\langle \tilde{h}_2^*(f_i) \tilde{h}_2(f_j) \rangle = \frac{1}{2} T \delta_{ij} \frac{3H_0^2}{10\pi^2} f_i^{-3} \Omega_0 \quad (7.9.2)$$

$$\langle \tilde{h}_1^*(f_i) \tilde{h}_2(f_j) \rangle = \frac{1}{2} T \delta_{ij} \frac{3H_0^2}{10\pi^2} f_i^{-3} \Omega_0 \gamma(f_i), \quad (7.9.3)$$

where  $\langle \rangle$  denotes ensemble average. Here  $\tilde{h}_1(f_i)$  and  $\tilde{h}_2(f_i)$  are the Fourier components of the gravitational strains  $h_1(t)$  and  $h_2(t)$  at the two detectors. The above equations are the discrete frequency versions of equation (3.17) of Ref. [21], with  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $f_{\text{low}} \leq f \leq f_{\text{high}}$ . They can be realized by setting

$$\tilde{h}_1(f_i) = \frac{1}{2} \sqrt{T} \left( \frac{3H_0^2}{10\pi^2} \right)^{1/2} f_i^{-3/2} \Omega_0^{1/2} (x_{1i} + iy_{1i}) \quad (7.9.4)$$

$$\tilde{h}_2(f_i) = \tilde{h}_1(f_i) \gamma(f_i) + \quad (7.9.5)$$

$$\frac{1}{2} \sqrt{T} \left( \frac{3H_0^2}{10\pi^2} \right)^{1/2} f_i^{-3/2} \Omega_0^{1/2} \sqrt{1 - \gamma^2(f_i)} (x_{2i} + iy_{2i}), \quad (7.9.6)$$

where  $x_{1i}$ ,  $y_{1i}$ ,  $x_{2i}$ , and  $y_{2i}$  are statistically independent (real) Gaussian random variables, each having zero mean and unit variance. (Note: The  $x_{1i}$ ,  $y_{1i}$ ,  $x_{2i}$ , and  $y_{2i}$  random variables are statistically independent of the  $u_i$  and  $v_i$  random variables defined in Sec. 7.8.) These Gaussian random variables are produced by calls to the *Numerical Recipes in C* random number generator routine `gasdev()`. Note also that the second term of  $\tilde{h}_2(f_i)$  (which is proportional to  $\sqrt{1 - \gamma^2(f_i)}$ ) is needed to obtain equation (7.9.2). Without this term,  $\langle \tilde{h}_2^*(f_i) \tilde{h}_2(f_j) \rangle$  would include an additional (unwanted) factor of  $\gamma^2(f_i)$ .

- (iii) `simulate_sb()` then whitens the data in the frequency domain by multiplying  $\tilde{h}_1(f_i)$  and  $\tilde{h}_2(f_i)$  by the frequency components  $\tilde{W}_1(f_i)$  and  $\tilde{W}_2(f_i)$  of the whitening filters of the two detectors:

$$\tilde{o}_1(f_i) := \tilde{h}_1(f_i) \tilde{W}_1(f_i) \quad (7.9.7)$$

$$\tilde{o}_2(f_i) := \tilde{h}_2(f_i) \tilde{W}_2(f_i). \quad (7.9.8)$$

This (complex) multiplication in the frequency domain corresponds to the convolution of  $h_1(t)$  and  $W_1(t)$ , and  $h_2(t)$  and  $W_2(t)$  in the time domain. By convention, the DC (i.e., zero frequency) and Nyquist critical frequency components of  $\tilde{o}_1(f_i)$  and  $\tilde{o}_2(f_i)$  are set to zero.

(iii) The final step consists of Fourier transforming the frequency components  $\bar{o}_1(f_i)$  and  $\bar{o}_2(f_i)$  into the time domain to obtain the whitened data streams  $o_1(t_i)$  and  $o_2(t_i)$ . Here  $t_i = i\Delta t$  with  $i = 0, 1, \dots, N - 1$ . Since  $\bar{o}_1^*(f_i)$  and  $\bar{o}_2^*(f_i)$  are the Fourier transforms of real data sets, the two Fourier transforms can be performed simultaneously.

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Comments: Although it is possible and more efficient to write a single function to simulate the generation of a stochastic background and intrinsic detector noise simultaneously, we have chosen—for the sake of modularity—to write separate functions to perform these two tasks separately. (See also the comment at the end of Sec. 7.8.)

## 7.10 Function: `combine_data()`

`void combine_data(int which, int n, float *in1, float *in2, float *out)`  
This low-level function takes two arrays as input, shifts them by half their length, and combines them with one another and with data stored in an internally-defined static buffer to produce output data that is continuous from one call of `combine_data()` to the next.

The arguments of `combine_data()` are:

**which:** Input. An integer variable specifying which internally-defined static buffer should be used when combining the input arrays with data saved from a previous call. The allowed values are  $1 \leq \text{which} \leq 16$ .

**n:** Input. The number  $N$  of data points contained in the input and output arrays.  $N$  is assumed to be even.

**in1:** Input. `in1[0..n-1]` is an array of floating point variables containing the values of the first input array.

**in2:** Input. `in2[0..n-1]` is an array of floating point variables containing the values of the second input array.

**out:** Output. `out[0..n-1]` is an array of floating point variables containing the output data, which is continuous from one call of `combine_data()` to the next.

`combine_data()` produces continuous output data by modifying the appropriately chosen static buffer `buf[0..3*n/2-1]` as follows:

$$\begin{aligned} \text{buf}[i] &+ = \sin[i * M\_PI/n] * \text{in1}[i] & \text{for } 0 \leq i \leq n/2 - 1 \\ \text{buf}[i] &+ = \sin[i * M\_PI/n] * \text{in1}[i] + \sin[(i - n/2) * M\_PI/n] * \text{in2}[i - n/2] & \text{for } n/2 \leq i \leq n - 1 \\ \text{buf}[i] &+ = \sin[(i - n/2) * M\_PI/n] * \text{in2}[i - n/2] & \text{for } n \leq i \leq 3 * n/2 - 1. \end{aligned}$$

The values of the output array `out[0..n-1]` are taken from the first two-thirds of the buffer, while the last one-third of the buffer is copied to the first third of the buffer in preparation for the next call. When this is complete, the last two-thirds of the buffer is cleared.

One nice feature of combining the data with a sine function (rather than with a triangle function, for example) is that if the input data represent statistically independent, stationary random processes having zero mean and the same variance, then the output data will also have zero mean and the same variance. This is a consequence of the trigonometric identity

$$\sin^2[i * M\_PI/n] + \sin^2[(i - n/2) * M\_PI/n] = 1. \quad (7.10.1)$$

Thus, `combine_data()` preserves the first and second-order statistical properties of the input data when constructing the output.

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Comments: In the context of stochastic background simulations, the two input arrays would represent two whitened data streams produced by a single detector, which are then time-shifted and combined to simulate *continuous-in-time* detector output. Since the contents of the internally-defined static buffer are equal to zero when `combine_data()` is first called, the amplitude of the output array initially builds up from zero to its nominal value over the course of the first  $N/2$  data points. This corresponds to an effective "turn-on" transient, with turn-on time equal to  $N \Delta t/2$  ( $\Delta t$  being the time between successive data samples).

## 7.11 Function: monte\_carlo()

```
void monte_carlo(int fake_sb, int fake_noise1, int fake_noise2, int n, float
delta_t, float omega_0, float f_low, float f_high, double *gamma12, double
*power1, double *power2, double *whiten1, double *whiten2, float *out1, float
*out2, int *pseed)
```

This high-level function simulates (if desired) the generation of noise intrinsic to a pair of detectors, and an isotropic and unpolarized stochastic background of gravitational radiation having a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $f_{\text{low}} \leq f \leq f_{\text{high}}$ . The outputs are two continuous-in-time whitened data streams  $o_1(t)$  and  $o_2(t)$  representing the detector outputs in the presence of a stochastic background signal plus noise.

The arguments of `monte_carlo()` are:

`fake_sb`: Input. An integer variable that should be set equal to 1 if a simulated stochastic background is desired.

`fake_noise1`: Input. An integer variable that should be set equal to 1 if simulated detector noise for the first detector is desired.

`fake_noise2`: Input. An integer variable that should be set equal to 1 if simulated detector noise for the second detector is desired.

`n`: Input. The number  $N$  of data points corresponding to an observation time  $T := N \Delta t$ , where  $\Delta t$  is the sampling period of the detector, defined below.  $N$  should equal an integer power of 2.

`delta_t`: Input. The sampling period  $\Delta t$  (in sec) of the detector.

`omega_0`: Input. The constant value  $\Omega_0$  (dimensionless) of the frequency spectrum  $\Omega_{\text{gw}}(f)$  for the stochastic background:

$$\Omega_{\text{gw}}(f) = \begin{cases} \Omega_0 & f_{\text{low}} \leq f \leq f_{\text{high}} \\ 0 & \text{otherwise.} \end{cases}$$

$\Omega_0$  should be greater than or equal to zero.

`f_low`: Input. The frequency  $f_{\text{low}}$  (in Hz) below which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background is zero.  $f_{\text{low}}$  should lie in the range  $0 \leq f_{\text{low}} \leq f_{\text{Nyquist}}$ , where  $f_{\text{Nyquist}}$  is the Nyquist critical frequency. (The Nyquist critical frequency is defined by  $f_{\text{Nyquist}} := 1/(2\Delta t)$ , where  $\Delta t$  is the sampling period of the detector.)  $f_{\text{low}}$  should also be less than or equal to  $f_{\text{high}}$ .

`f_high`: Input. The frequency  $f_{\text{high}}$  (in Hz) above which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background is zero.  $f_{\text{high}}$  should lie in the range  $0 \leq f_{\text{high}} \leq f_{\text{Nyquist}}$ . It should also be greater than or equal to  $f_{\text{low}}$ .

`gamma12`: Input. `gamma12[0..n/2-1]` is an array of double precision variables containing the values of the overlap reduction function  $\gamma(f)$  for the two detector sites. These variables are dimensionless. `gamma12[i]` contains the value of  $\gamma(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

`power1`: Input. `power1[0..n/2-1]` is an array of double precision variables containing the values of the noise power spectrum  $P_1(f)$  of the first detector. These variables have units of  $\text{strain}^2/\text{Hz}$  (or seconds). `power1[i]` contains the value of  $P_1(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

**power2**: Input. `power2[0..n/2-1]` is an array of double precision variables containing the values of the noise power spectrum  $P_2(f)$  of the second detector, in exactly the same format as the previous argument.

**whiten1**: Input. `whiten1[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\tilde{W}_1(f)$  of the whitening filter of the first detector. These variables have units rHz/strain (or  $\text{sec}^{-1/2}$ ), which are inverse to the units of the square root of the noise power spectrum  $P_1(f)$ . `whiten1[2*i]` and `whiten1[2*i+1]` contain, respectively, the values of the real and imaginary parts of  $\tilde{W}_1(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

**whiten2**: Input. `whiten2[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\tilde{W}_2(f)$  of the whitening filter of the second detector, in exactly the same format as the previous argument.

**out1**: Output. `out1[0..n-1]` is an array of floating point variables containing the values of the continuous-in-time whitened data stream  $o_1(t)$  representing the output of the first detector.  $o_1(t)$  is the convolution of detector whitening filter  $\tilde{W}_1(t)$  with the data stream  $s_1(t) := h_1(t) + n_1(t)$ , where  $h_1(t)$  is the gravitational strain and  $n_1(t)$  is the noise intrinsic to the detector. These variables have units of rHz (or  $\text{sec}^{-1/2}$ ), which follows from the definition of  $s_1(t)$  as a strain and  $\tilde{W}_1(f)$  as the "inverse" of the square root of the noise power spectrum  $P_1(f)$ . `out1[i]` contains the value of  $o_1(t)$  evaluated at the discrete time  $t_i = i\Delta t$ , where  $i = 0, 1, \dots, N - 1$ .

**out2**: Output. `out2[0..n-1]` is an array of floating point variables containing the values of the continuous-in-time whitened data stream  $o_2(t)$  representing the output of the second detector, in exactly the same format as the previous argument.

**pseed**: Input. A pointer to a seed value, which is used by the random number generator routine.

`monte_carlo()` is a very simple function, consisting of calls to `simulate_sb()`, `simulate_noise()`, and `combine_data()`. If `fake_sb=1`, `monte_carlo()` calls `simulate_sb()` twice, producing two sets of data that are time-shifted and combined by `combine_data()` to simulate continuous-in-time detector output. Similar statements apply when either `fake_noise1` or `fake_noise2` equals 1.

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Comments: None.

## 7.12 Example: monte\_carlo program

The following example program is a simple demonstration of the function `monte_carlo()`, which was defined in the previous section. It produces animated output representing time-series data for simulated detector noise and for a simulated stochastic background having a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $f_{\text{low}} \leq f \leq f_{\text{high}}$ . The output from this program must be piped into `xmgr`. The parameters that were chosen for the example program shown below produce whitened time-series data for a stochastic background having  $\Omega_{\text{gw}}(f) = 1.0 \times 10^{-3}$  for  $5 \text{ Hz} \leq f \leq 5000 \text{ Hz}$ . For this particular example, the noise intrinsic to the detectors was set to zero. A sample “snapshot” of the animation is shown in Fig. 48.

By modifying the parameters listed at the top of the example program, one can also simulate an unwhitened stochastic background signal (Fig. 49), and whitened and unwhitened data streams corresponding to the noise intrinsic to an initial LIGO detector (Figs. 50 and 51). Other combinations of signal, noise, whitening, and unwhitening are of course also possible. To produce the animated output, simply enter the command:

```
monte_carlo | xmgr -pipe &
```

after compilation.

Note: The amplitude of the animated output initially builds up from zero to its nominal value over (approximately) the first 1.5 seconds. This “turn-on” transient is a consequence of the overlapping technique used by `combine_data()` to produce continuous-in-time detector output. (See the comment at the end of Section 7.10.)

```
/* main program to illustrate monte_carlo() */

#include "grasp.h"
void graphout(float, float, int);

#define DETECTORS_FILE "detectors.dat" /* file containing detector info */
#define SITE1_CHOICE 1 /* identification number for site 1 */
#define SITE2_CHOICE 2 /* identification number for site 2 */
#define FAKE_SB 1 /* 1: simulate stochastic background */
/* 0: no stochastic background */
#define FAKE_NOISE1 0 /* 1: simulate detector noise at site 1 */
/* 0: no detector noise at site 1 */
#define FAKE_NOISE2 0 /* 1: simulate detector noise at site 2 */
/* 0: no detector noise at site 2 */
#define WHITEN_OUT1 1 /* 1: whiten output at site 1 */
/* 0: don't whiten output at site 1 */
#define WHITEN_OUT2 1 /* 1: whiten output at site 2 */
/* 0: don't whiten output at site 2 */

#define N 65536 /* number of data points */
#define DELTA_T (5.0e-5) /* sampling period (in sec) */
#define OMEGA_0 (1.0e-3) /* omega_0 */
#define F_LOW (5.0) /* minimum frequency (in Hz) */
#define F_HIGH (5.0e3) /* maximum frequency (in Hz) */
#define NUM_RUNS 5 /* number of runs */

int main(int argc, char **argv)
{
    int i, j, last=0, seed= -17;
    float delta_f, tstart=0.0, time_now;

    float site1_parameters[9], site2_parameters[9];
    char site1_name[100], noise1_file[100], whiten1_file[100];
```



```

char site2_name[100],noise2_file[100],whiten2_file[100];

double *power1,*power2,*whiten1,*whiten2,*gamma12;
float *out1,*out2;

/* ALLOCATE MEMORY */
power1=(double *)malloc((N/2)*sizeof(double));
power2=(double *)malloc((N/2)*sizeof(double));
whiten1=(double *)malloc(N*sizeof(double));
whiten2=(double *)malloc(N*sizeof(double));
gamma12=(double *)malloc((N/2)*sizeof(double));
out1=(float *)malloc(N*sizeof(float));
out2=(float *)malloc(N*sizeof(float));

/* IDENTITY WHITENING FILTERS (IF WHITEN_OUT1=WHITEN_OUT2=0) */
for (i=0;i<N/2;i++) {
    whiten1[2*i]=whiten2[2*i]=1.0;
    whiten1[2*i+1]=whiten2[2*i+1]=0.0;
}

/* CALL DETECTOR_SITE() TO GET SITE PARAMETER INFORMATION */
detector_site(DETECTORS_FILE,SITE1_CHOICE,site1_parameters,site1_name,
    noise1_file,whiten1_file);
detector_site(DETECTORS_FILE,SITE2_CHOICE,site2_parameters,site2_name,
    noise2_file,whiten2_file);

/* CONSTRUCT NOISE POWER SPECTRA, OVERLAP REDUCTION FUNCTION, AND */
/* (NON-TRIVIAL) WHITENING FILTERS, IF DESIRED */
delta_f=(float)(1.0/(N*DELTA_T));
noise_power(noise1_file,N/2,delta_f,power1);
noise_power(noise2_file,N/2,delta_f,power2);
overlap(site1_parameters,site2_parameters,N/2,delta_f,gamma12);
if (WHITEN_OUT1==1) whiten(whiten1_file,N/2,delta_f,whiten1);
if (WHITEN_OUT2==1) whiten(whiten2_file,N/2,delta_f,whiten2);

/* SIMULATE STOCHASTIC BACKGROUND AND/OR DETECTOR NOISE */
for (j=0;j<NUM_RUNS;j++) {
    monte_carlo(FAKE_SB,FAKE_NOISE1,FAKE_NOISE2,N,DELTA_T,OMEGA_0,F_LOW,F_HIGH,
        gamma12,power1,power2,whiten1,whiten2,out1,out2,&seed);

    /* DISPLAY OUTPUT USING XMGR */
    for (i=0;i<N;i++) {
        time_now=tstart+i*DELTA_T;
        printf("%e\t%e\n",time_now,out1[i]);
    }
    if (j==NUM_RUNS-1) last=1;
    graphout(tstart,tstart+N*DELTA_T,last);

    /* UPDATE TSTART */
    tstart+=N*DELTA_T;
} /* end for (j=0;j<NUM_RUNS;j++) */

return 0;
}

void graphout(float xmin,float xmax,int last)
{

```

```

static int first=1;
printf("&\n");

if (first) {

    /* first time we draw plot */
    printf("@doublebuffer true\n"); /* keep display from flashing */
    printf("@focus off\n");
    printf("@world xmin %e\n",xmin);
    printf("@world xmax %e\n",xmax);
    printf("@autoscale yaxes\n");
    printf("@xaxis label \"t (sec)\"\n");
    printf("@title \"Simulated Detector Ouput\"\n");
    printf("@subtitle \"(stochastic background--whitened)\"\n");
    printf("@redraw \n");
    if (!last) printf("@kill s0\n"); /* kill set; ready to read again */

    first=0;
}
else {

    /* other timeOAs we draw plot */
    printf("@world xmin %e\n",xmin);
    printf("@world xmax %e\n",xmax);
    printf("@autoscale yaxes\n");
    if (!last) printf("@kill s0\n"); /* kill set; ready to read again */

}

return;
}

```

### Simulated Detector Output

(stochastic background—whitened)

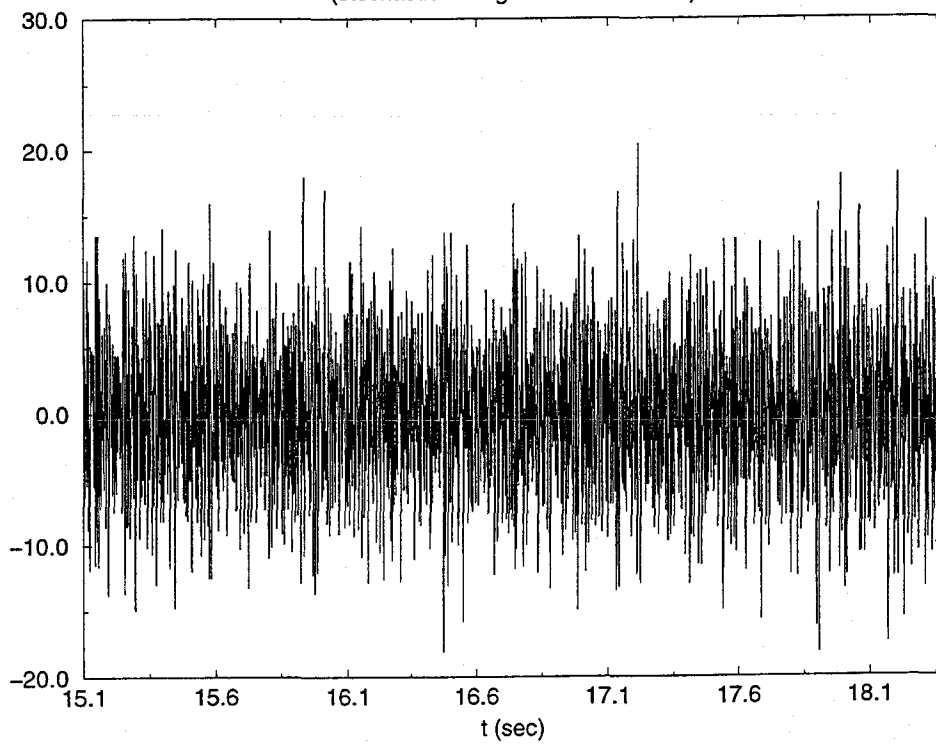


Figure 48: Time-series data (whitened) for a stochastic background having a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = 1.0 \times 10^{-3}$  for  $5 \text{ Hz} \leq f \leq 5000 \text{ Hz}$ .

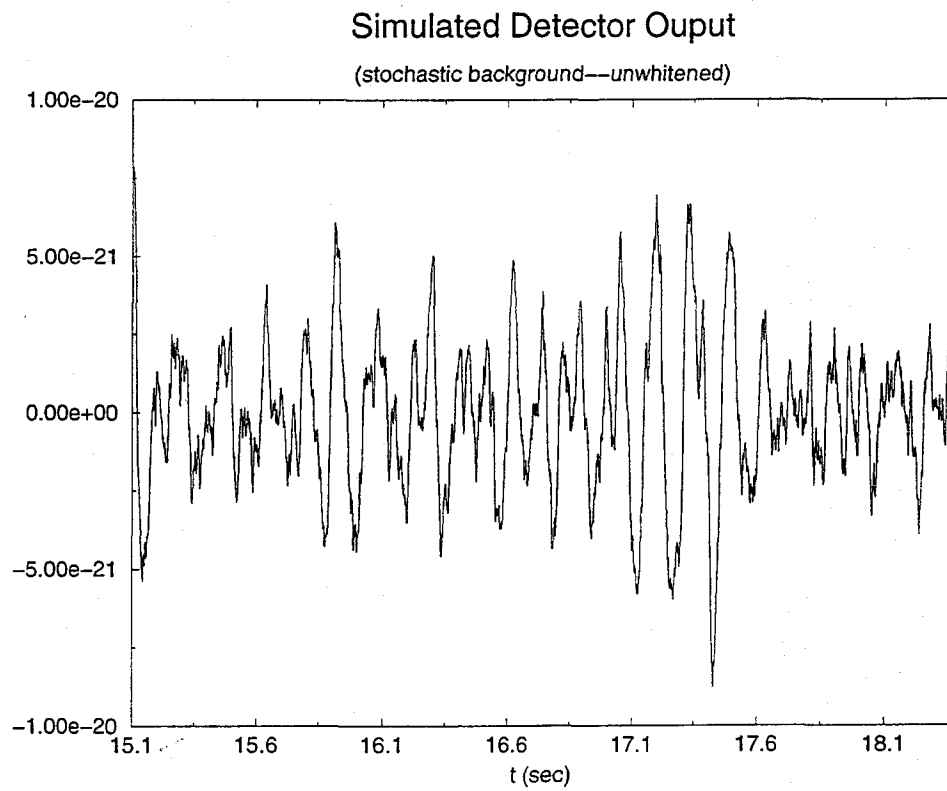


Figure 49: Time-series data (unwhitened) for a stochastic background having a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = 1.0 \times 10^{-3}$  for  $5 \text{ Hz} \leq f \leq 5000 \text{ Hz}$ .

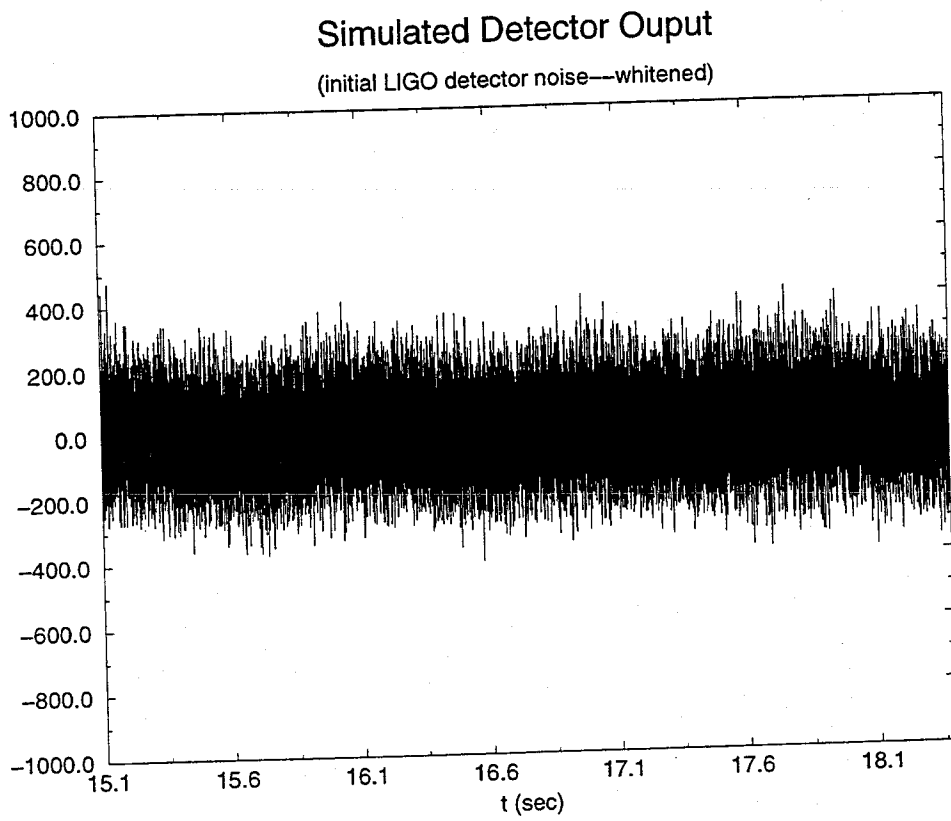


Figure 50: Time-series data (whitened) for the noise intrinsic to an initial LIGO detector.

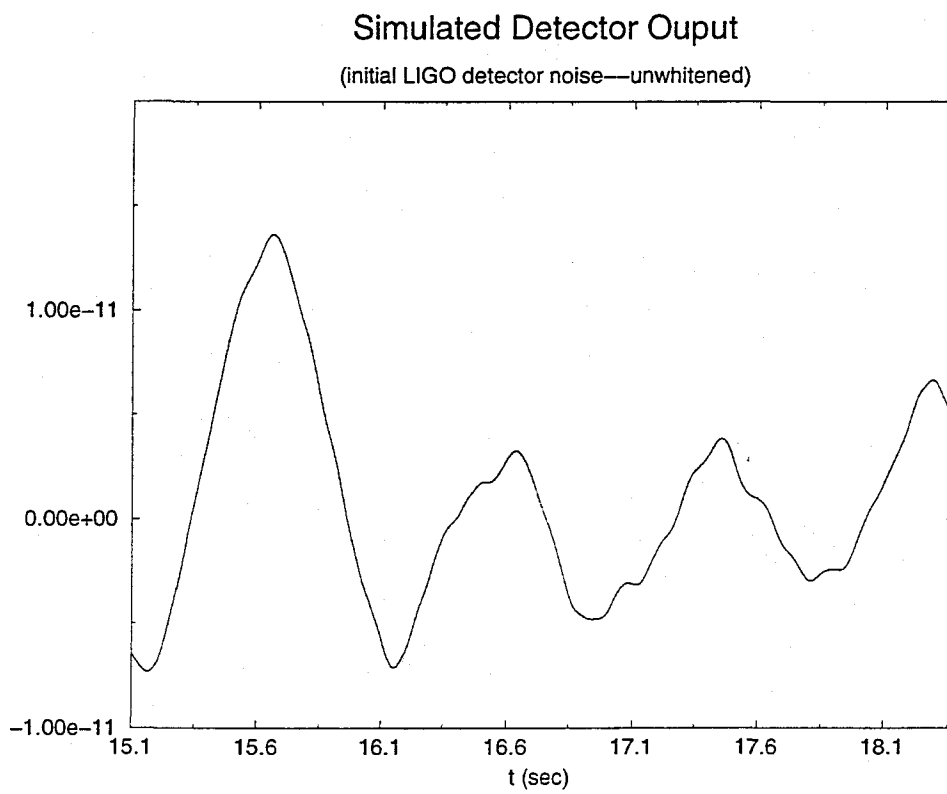


Figure 51: Time-series data (unwhitened) for the noise intrinsic to an initial LIGO detector.

### 7.13 Function: test\_data12()

```
int test_data12(int n, float *data1, float *data2)
```

This function tests two data sets to see if they have probability distributions consistent with a Gaussian normal distribution.

The arguments of test\_data12() are:

**n:** Input. The number  $N$  of data points contained in each of the input arrays.

**data1:** Input. data1[0..n-1] is an array of floating point variables containing the values of the first array to be tested.

**data2:** Input. data2[0..n-1] is an array of floating point variables containing the values of the second array to be tested.

test\_data12() is a simple function that makes use of the is\_gaussian() utility routine. (See Sec. 10.5 for more details.) test\_data12() prints a warning message if either of the data sets contain a value too large to be stored in 16 bits. (The actual maximum value was chosen to be 32765.) It returns 1 if both data sets pass the is\_gaussian() test. It returns 0 if either data set fails, and prints a message indicating the bad set.

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Comments: In the context of stochastic background simulations, data1[] and data2[] contain the values of the whitened data streams  $o_1(t)$  and  $o_2(t)$  that are output by the two detectors.

## 7.14 Function: `extract_noise()`

`void extract_noise(int average, int which, float *in, int n, float delta_t, double *whiten_out, double *power)`

This function calculates the real-time noise power spectrum  $P(f)$  of a detector, using a Hann window and averaging the spectrum for two overlapped data sets, if desired.

The arguments of `extract_noise()` are:

**average:** Input. An integer variable that should be set equal to 1 if the values of the real-time noise power spectra corresponding to two overlapped data sets are to be averaged.

**which:** Input. An integer variable specifying which internally-defined static buffer should be used when overlapping the new input data set with data saved from a previous call. The allowed values are  $1 \leq \text{which} \leq 16$ .

**in:** Input. `in[0..n-1]` is an array of floating point variables containing the values of the assumed continuous-in-time whitened data stream  $o(t)$  produced by the detector.  $o(t)$  is the convolution of detector whitening filter  $W(t)$  with the data stream  $s(t) := h(t) + n(t)$ , where  $h(t)$  is the gravitational strain and  $n(t)$  is the noise intrinsic to the detector. The variables `in[]` have units of rHz (or  $\text{sec}^{-1/2}$ ), which follows from the definition of  $s(t)$  as a strain and  $\bar{W}(f)$  as the “inverse” of the square root of the noise power spectrum  $P(f)$ . `in[i]` contains the value of  $o(t)$  evaluated at the discrete time  $t_i = i\Delta t$ , where  $i = 0, 1, \dots, N - 1$ .

**n:** Input. The number  $N$  of data points corresponding to an observation time  $T := N \Delta t$ , where  $\Delta t$  is the sampling period of the detector, defined below.  $N$  should equal an integer power of 2.

**delta\_t:** Input. The sampling period  $\Delta t$  (in sec) of the detector.

**whiten\_out:** Input. `whiten_out[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\bar{W}(f)$  of the whitening filter of the detector. These variables have units rHz/strain (or  $\text{sec}^{-1/2}$ ), which are inverse to the units of the square root of the noise power spectrum  $P(f)$ . `whiten_out[2*i]` and `whiten_out[2*i+1]` contain, respectively, the values of the real and imaginary parts of  $\bar{W}(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

**power:** Output. `power[0..n/2-1]` is an array of double precision variables containing the values of the real-time noise power spectrum  $P(f)$  of the detector. Explicitly,

$$P(f) := \frac{2}{T} \bar{s}^*(f) \bar{s}(f), \quad (7.14.1)$$

where  $\bar{s}(f)$  is the Fourier transform of the unwhitened data stream  $s(t)$  produced by the detector. These variables have units of  $\text{strain}^2/\text{Hz}$  (or seconds). `power[i]` contains the value of  $P(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

`extract_noise()` calculates the real-time noise power spectrum  $P(f)$  as follows:

- (i) It first stores the input data stream  $o(t)$  in the last two-thirds of an appropriately chosen static buffer `buf[0..3*n/2-1]`. The first one-third of this buffer contains the input data left over from the previous call.



(ii) It then multiplies the first two-thirds of this buffer by the Hann window function:

$$w(t) := \sqrt{\frac{8}{3}} \cdot \frac{1}{2} \left[ 1 - \cos\left(\frac{2\pi t}{T}\right) \right]. \quad (7.14.2)$$

The factor  $\sqrt{8/3}$  is the “window squared-and-summed” factor described in *Numerical Recipes in C*, p.553. It is needed to offset the reduction in power that is introduced by the windowing.

(iii) The windowed data is then Fourier transformed into the frequency domain, where it is unwhitened by dividing by the (complex) spectrum  $\bar{W}(f)$  of the whitening filter of the detector. The resulting unwhitened frequency components are denoted by  ${}^{(1)}\bar{s}(f)$ ; the superscript (1) indicates that we are analyzing the first of two overlapped data sets.

(iv) The real-time noise power spectrum is then calculated according to:

$${}^{(1)}P(f) := \frac{2}{T} {}^{(1)}\bar{s}^*(f) {}^{(1)}\bar{s}(f). \quad (7.14.3)$$

(v) The data contained in the last two-thirds of the buffer is then copied to the first two-thirds of the buffer, and steps (ii)-(iv) are repeated, yielding a second real-time noise power spectrum  ${}^{(2)}P(f)$ .

(vi) If `average=1`,  $P(f)$  is given by:

$$P(f) := \frac{1}{2} \left[ {}^{(1)}P(f) + {}^{(2)}P(f) \right]. \quad (7.14.4)$$

Otherwise,  $P(f) = {}^{(2)}P(f)$ .

(vii) Finally, the data contained in the last two-thirds of the buffer is again copied to the first two-thirds, in preparation for the next call to `extract_noise()`. The data saved in the first one-third of this buffer will match onto the next input data stream if the input data from one call of `extract_noise()` to the next is continuous.

Note: One should call `extract_noise()` with `average ≠ 1`, when one suspects that the current input data is *not* continuous with the data that was saved from the previous call. This is because a discontinuity between the “old” and “new” data sets has a tendency to introduce spurious large frequency components into the real-time noise power spectrum, which should not be present. Since a single input data stream by itself is continuous, the noise power spectrum  ${}^{(2)}P(f)$  (which is calculated on the second pass through the data) will be free of these spurious large frequency components. This is why we set  $P(f)$  equal to  ${}^{(2)}P(f)$ —and not equal to  ${}^{(1)}P(f)$ —when `average ≠ 1`.

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Comments: In the context of stochastic background simulations, it would be more efficient to extract the real-time noise power spectra at *two* detectors simultaneously. However, for modularity of design, and to allow this function to be used possibly for “single-detector” gravity-wave searches, we decided to write the above routine instead.

### 7.15 Function: `extract_signal()`

```
void extract_signal(int average, float *in1, float *in2, int n, float delta_t,  
double *whiten1, double *whiten2, double *signal12)
```

This function calculates the real-time cross-correlation spectrum  $\bar{s}_{12}(f)$  of the unwhitened data streams  $s_1(t)$  and  $s_2(t)$ , using a Hann window and averaging the spectrum for two overlapped data sets, if desired.

The arguments of `extract_signal()` are:

**average:** Input. An integer variable that should be set equal to 1 if the values of the real-time cross-correlation spectra corresponding to two overlapped data sets are to be averaged.

**in1:** Input. `in1[0..n-1]` is an array of floating point variables containing the values of the assumed continuous-in-time whitened data stream  $o_1(t)$  produced by the first detector.  $o_1(t)$  is the convolution of detector whitening filter  $\tilde{W}_1(t)$  with the data stream  $s_1(t) := h_1(t) + n_1(t)$ , where  $h_1(t)$  is the gravitational strain and  $n_1(t)$  is the noise intrinsic to the detector. The variables `in1[i]` have units of rHz (or  $\text{sec}^{-1/2}$ ), which follows from the definition of  $s_1(t)$  as a strain and  $\tilde{W}_1(f)$  as the “inverse” of the square root of the noise power spectrum  $P_1(f)$ . `in1[i]` contains the value of  $o_1(t)$  evaluated at the discrete time  $t_i = i\Delta t$ , where  $i = 0, 1, \dots, N-1$ .

**in2:** Input. `in2[0..n-1]` is an array of floating point variables containing the values of the assumed continuous-in-time whitened data stream  $o_2(t)$  produced by the second detector, in exactly the same format as the previous argument.

**n:** Input. The number  $N$  of data points corresponding to an observation time  $T := N\Delta t$ , where  $\Delta t$  is the sampling period of the detectors, defined below.  $N$  should equal an integer power of 2.

**delta\_t:** Input. The sampling period  $\Delta t$  (in sec) of the detectors.

**whiten1:** Input. `whiten1[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\tilde{W}_1(f)$  of the whitening filter of the first detector. These variables have units rHz/strain (or  $\text{sec}^{-1/2}$ ), which are inverse to the units of the square root of the noise power spectrum  $P_1(f)$ . `whiten1[2*i]` and `whiten1[2*i+1]` contain, respectively, the values of the real and imaginary parts of  $\tilde{W}_1(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2-1$ .

**whiten2:** Input. `whiten2[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\tilde{W}_2(f)$  of the whitening filter of the second detector, in exactly the same format as the previous argument.

**signal12:** Output. `signal12[0..n/2-1]` is an array of double precision variables containing the values of the real-time cross-correlation spectrum

$$\bar{s}_{12}(f) := (\bar{s}_1^*(f) \bar{s}_2(f) + \text{c.c.}), \quad (7.15.1)$$

where  $\bar{s}_1(f)$  and  $\bar{s}_2(f)$  are the Fourier transforms of the unwhitened data streams  $s_1(t)$  and  $s_2(t)$  produced by the two detectors. These variables have units of  $\text{strain}^2 \cdot \text{sec}^2$  (or simply  $\text{sec}^2$ ). `signal12[i]` contains the value of  $\bar{s}_{12}(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2-1$ .

`extract_signal()` calculates the real-time cross-correlation spectrum  $\bar{s}_{12}(f)$  as follows:

- (i) It first stores the input data streams  $o_1(t)$  and  $o_2(t)$  in the last two-thirds of internally-defined static buffers `buf1 [0..3*n/2-1]` and `buf2 [0..3*n/2-1]`. The first one-third of these buffers contains the input data left over from the previous call.
- (ii) It then multiplies the first two-thirds of these buffers by the Hann window function:

$$w(t) := \sqrt{\frac{8}{3}} \cdot \frac{1}{2} \left[ 1 - \cos\left(\frac{2\pi t}{T}\right) \right]. \quad (7.15.2)$$

The factor  $\sqrt{8/3}$  is the “window squared-and-summed” factor described in *Numerical Recipes in C*, p.553. It is needed to offset the reduction in power that is introduced by the windowing.

- (iii) The windowed data is then Fourier transformed into the frequency domain, where it is unwhitened by dividing by the (complex) spectra  $\tilde{W}_1(f)$  and  $\tilde{W}_2(f)$ , which represent the whitening filters of the two detectors. The resulting unwhitened frequency components are denoted by  $^{(1)}\tilde{s}(f)$  and  $^{(1)}\tilde{s}(f)$ ; the superscript (1) indicates that we are analyzing the first of two overlapped data sets.
- (iv) The real-time cross-correlation spectrum is then calculated according to:

$$^{(1)}\tilde{s}_{12}(f) := \left[ ^{(1)}\tilde{s}_1^*(f) ^{(1)}\tilde{s}_2(f) + \text{c.c.} \right]. \quad (7.15.3)$$

- (v) The data contained in the last two-thirds of the buffers is then copied to the first two-thirds of the buffers, and steps (ii)-(iv) are repeated, yielding a second real-time cross-correlation spectrum  $^{(2)}\tilde{s}_{12}(f)$ .
- (vi) If `average=1`,  $\tilde{s}_{12}(f)$  is given by:

$$\tilde{s}_{12}(f) := \frac{1}{2} \left[ ^{(1)}\tilde{s}_{12}(f) + ^{(2)}\tilde{s}_{12}(f) \right]. \quad (7.15.4)$$

Otherwise,  $\tilde{s}_{12}(f) = ^{(2)}\tilde{s}_{12}(f)$ .

- (vii) Finally, the data contained in the last two-thirds of the buffers is again copied to the first two-thirds, in preparation for the next call to `extract_sb()`. The data saved in the first one-third of these buffers will match onto the next input data streams if the input data from one call of `extract_sb()` to the next is continuous.

Note: One should call `extract_sb()` with `average ≠ 1`, when one suspects that the current input data is *not* continuous with the data that was saved from the previous call. This is because a discontinuity between the “old” and “new” data sets has a tendency to introduce spurious large frequency components into the real-time cross-correlation spectrum, which should not be present. Since a single input data stream by itself is continuous, the cross-correlation spectrum  $^{(2)}\tilde{s}_{12}(f)$  (which is calculated on the second pass through the data) will be free of these spurious large frequency components. This is why we set  $\tilde{s}_{12}(f)$  equal to  $^{(2)}\tilde{s}_{12}(f)$ —and not equal to  $^{(1)}\tilde{s}_{12}(f)$ —when `average ≠ 1`.

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Comments: Although it is possible and more efficient to write a single function to extract the real-time detector noise power and cross-correlation signal spectra simultaneously, we have chosen—for the sake of modularity—to write separate functions to perform these two tasks separately. (See also the comment at the end of Sec. 7.14.)

## 7.16 Function: optimal\_filter()

void optimal\_filter(int n, float delta\_f, float f\_low, float f\_high, double \*gamma12, double \*power1, double \*power2, double \*filter12)

This function calculates the values of the spectrum  $\tilde{Q}(f)$  of the optimal filter function, which maximizes the cross-correlation signal-to-noise ratio for an isotropic and unpolarized stochastic background of gravitational radiation having a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $f_{\text{low}} \leq f \leq f_{\text{high}}$ .

The arguments of optimal\_filter() are:

n: Input. The number  $N$  of discrete frequency values at which the spectrum  $\tilde{Q}(f)$  of the optimal filter is to be evaluated.

delta\_f: Input. The spacing  $\Delta f$  (in Hz) between two adjacent discrete frequency values:  $\Delta f := f_{i+1} - f_i$ .

f\_low: Input. The frequency  $f_{\text{low}}$  (in Hz) below which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background—and hence the optimal filter  $\tilde{Q}(f)$ —is zero.  $f_{\text{low}}$  should lie in the range  $0 \leq f_{\text{low}} \leq f_{\text{Nyquist}}$ , where  $f_{\text{Nyquist}}$  is the Nyquist critical frequency. (The Nyquist critical frequency is defined by  $f_{\text{Nyquist}} := 1/(2\Delta t)$ , where  $\Delta t$  is the sampling period of the detectors.)  $f_{\text{low}}$  should also be less than or equal to  $f_{\text{high}}$ .

f\_high: Input. The frequency  $f_{\text{high}}$  (in Hz) above which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background—and hence the optimal filter  $\tilde{Q}(f)$ —is zero.  $f_{\text{high}}$  should lie in the range  $0 \leq f_{\text{high}} \leq f_{\text{Nyquist}}$ . It should also be greater than or equal to  $f_{\text{low}}$ .

gamma12: Input. gamma12[0..n-1] is an array of double precision variables containing the values of the overlap reduction function  $\gamma(f)$  for the two detector sites. These variables are dimensionless. gamma12[i] contains the value of  $\gamma(f)$  evaluated at the discrete frequency  $f_i = i\Delta f$ , where  $i = 0, 1, \dots, N-1$ .

power1: Input. power1[0..n-1] is an array of double precision variables containing the values of the noise power spectrum  $P_1(f)$  of the first detector. These variables have units of strain<sup>2</sup>/Hz (or seconds). power1[i] contains the value of  $P_1(f)$  evaluated at the discrete frequency  $f_i = i\Delta f$ , where  $i = 0, 1, \dots, N-1$ .

power2: Input. power2[0..n-1] is an array of double precision variables containing the values of the noise power spectrum  $P_2(f)$  of the second detector, in exactly the same format as the previous argument.

filter12: Output. filter12[0..n-1] is an array of double precision variables containing the values of the spectrum  $\tilde{Q}(f)$  of the optimal filter function for the two detectors. These variables are dimensionless for our choice of normalization  $\langle S \rangle = \Omega_0 T$ . (See the discussion below.) filter12[i] contains the value of  $\tilde{Q}(f)$  evaluated at the discrete frequency  $f_i = i\Delta f$ , where  $i = 0, 1, \dots, N-1$ .

The values of  $\tilde{Q}(f)$  calculated by optimal\_filter() are defined by equation (3.32) of Ref. [21]:

$$\tilde{Q}(f) := \lambda \frac{\gamma(f)\Omega_{\text{gw}}(f)}{f^3 P_1(f) P_2(f)}. \quad (7.16.1)$$

Such a filter maximizes the cross-correlation signal-to-noise ratio  $\text{SNR} := \mu/\sigma$ , where

$$\mu := \langle S \rangle = T \frac{3H_0^2}{20\pi^2} \int_{-\infty}^{\infty} df \gamma(|f|) |f|^{-3} \Omega_{\text{gw}}(|f|) \tilde{Q}(f) \quad (7.16.2)$$

$$\sigma^2 := \langle S^2 \rangle - \langle S \rangle^2 \approx \frac{T}{4} \int_{-\infty}^{\infty} df P_1(|f|) P_2(|f|) |\tilde{Q}(f)|^2. \quad (7.16.3)$$

( $T$  corresponds to the observation time of the measurement.) We are working here under the assumption that the magnitude of the noise intrinsic to the detectors is much larger than the magnitude of the signal due to the stochastic background. If this assumption does not hold, Eq. 7.16.3 for  $\sigma^2$  needs to be modified, as discussed in Sec. 7.18.

Note that we have explicitly included a normalization constant  $\lambda$  in the definition of  $\tilde{Q}(f)$ . The choice of  $\lambda$  does not affect the value of the signal-to-noise ratio, since  $\mu$  and  $\sigma$  are both multiplied by the same factor of  $\lambda$ . For a stochastic background having a constant frequency spectrum

$$\Omega_{\text{gw}}(f) = \begin{cases} \Omega_0 & f_{\text{low}} \leq f \leq f_{\text{high}} \\ 0 & \text{otherwise,} \end{cases}$$

it is convenient to choose  $\lambda$  so that

$$\mu = \Omega_0 T. \quad (7.16.4)$$

From equations (7.16.1) and (7.16.2), it follows that

$$\lambda = \left[ \frac{3H_0^2}{10\pi^2} \Omega_0 \int_{f_{\text{low}}}^{f_{\text{high}}} df \frac{\gamma^2(f)}{f^6 P_1(f) P_2(f)} \right]^{-1} \quad (7.16.5)$$

will do the job. With this choice of  $\lambda$ ,  $\tilde{Q}(f)$  is dimensionless and independent of the value of  $\Omega_0$ . This is why  $\Omega_0$  does not have to be passed as a parameter to `optimal_filter()`.

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Comments: None.

## 7.17 Example: optimal\_filter program

The following example program shows one way of combining the functions `detector_site()`, `noise_power()`, `overlap()`, and `optimal_filter()` to calculate the spectrum  $\tilde{Q}(f)$  of the optimal filter function for a given pair of detectors. Below we explicitly calculate  $\tilde{Q}(f)$  for the initial Hanford, WA and Livingston, LA LIGO detectors. (We also choose to normalize the magnitude of the spectrum  $\tilde{Q}(f)$  to 1, for later convenience when making plots of the output data.) Noise power information for these two detectors is read from the input data file `noise_init.dat`. This file is specified by the information contained in `detectors.dat`. (See Sec. 7.1 for more details.) The resulting optimal filter function data is stored as two columns of double precision numbers ( $f_i$  and  $\tilde{Q}(f_i)$ ) in the file `LIGO_filter.dat`, where  $f_i = i\Delta f$  and  $i = 0, 1, \dots, N - 1$ . A plot of this data is shown in Fig. 52.

As usual, the user can modify the parameters in the `#define` statements listed at the beginning of the program to change the number of frequency points, the frequency spacing, etc. used when calculating  $\tilde{Q}(f)$ . Also, by changing the site location identification numbers and the output file name, the user can calculate and save the spectrum of the optimal filter function for *any* pair of detectors. For example, Fig. 53 is a plot of the optimal filter function for the advanced LIGO detectors.

```
/* main program to illustrate the function optimal_filter() */

#include "grasp.h"

#define DETECTORS_FILE "detectors.dat" /* file containing detector info */
#define SITE1_CHOICE 1 /* 1=LIGO-Hanford site */
#define SITE2_CHOICE 2 /* 2=LIGO-Livingston site */
#define N 500 /* number of frequency points */
#define DELTA_F 1.0 /* frequency spacing (in Hz) */
#define F_LOW 0.0 /* minimum frequency (in Hz) */
#define F_HIGH (1.0e+4) /* maximum frequency (in Hz) */
#define OUT_FILE "LIGO_filter.dat" /* output filename */

int main(int argc, char **argv)
{
    int i;
    double f;
    double abs_value, max;

    float site1_parameters[9], site2_parameters[9];
    char site1_name[100], noise1_file[100], whiten1_file[100];
    char site2_name[100], noise2_file[100], whiten2_file[100];

    double *power1, *power2;
    double *gamma12;
    double *filter12;

    FILE *fp;
    fp=fopen(OUT_FILE, "w");

    /* ALLOCATE MEMORY */
    power1=(double *)malloc(N*sizeof(double));
    power2=(double *)malloc(N*sizeof(double));
    gamma12=(double *)malloc(N*sizeof(double));
    filter12=(double *)malloc(N*sizeof(double));

    /* CALL DETECTOR_SITE() TO GET SITE PARAMETER INFORMATION */
    detector_site(DETECTORS_FILE, SITE1_CHOICE, site1_parameters, site1_name,
```

```

        noise1_file,whiten1_file);
detector_site(DETECTORS_FILE,SITE2_CHOICE,site2_parameters,site2_name,
        noise2_file,whiten2_file);

/* CALL NOISE_POWER() AND OVERLAP() */
noise_power(noise1_file,N,DELTA_F,power1);
noise_power(noise2_file,N,DELTA_F,power2);
overlap(site1_parameters,site2_parameters,N,DELTA_F,gamma12);

/* CALL OPTIMAL_FILTER() AND DETERMINE MAXIMUM ABSOLUTE VALUE */
optimal_filter(N,DELTA_F,F_LOW,F_HIGH,gamma12,power1,power2,filter12);

max=0.0;
for (i=0;i<N;i++) {
    abs_value=fabs(filter12[i]);
    if (abs_value>max) max=abs_value;
}

/* WRITE FILTER FUNCTION (NORMALIZED TO 1) TO FILE */
for (i=0;i<N;i++) {
    f=i*DELTA_F;
    fprintf(fp,"%e %e\n",f,filter12[i]/max);
}

fclose(fp);

return 0;
}

```

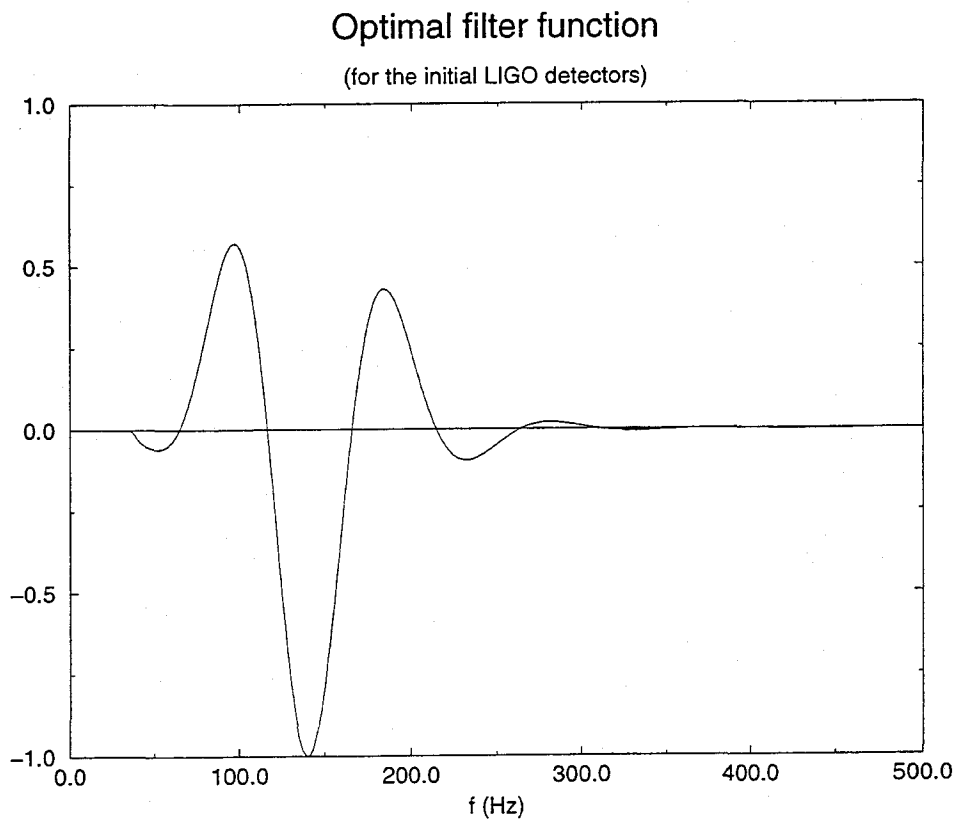


Figure 52: Optimal filter function  $\tilde{Q}(f)$  (normalized to 1) for the initial LIGO detectors.



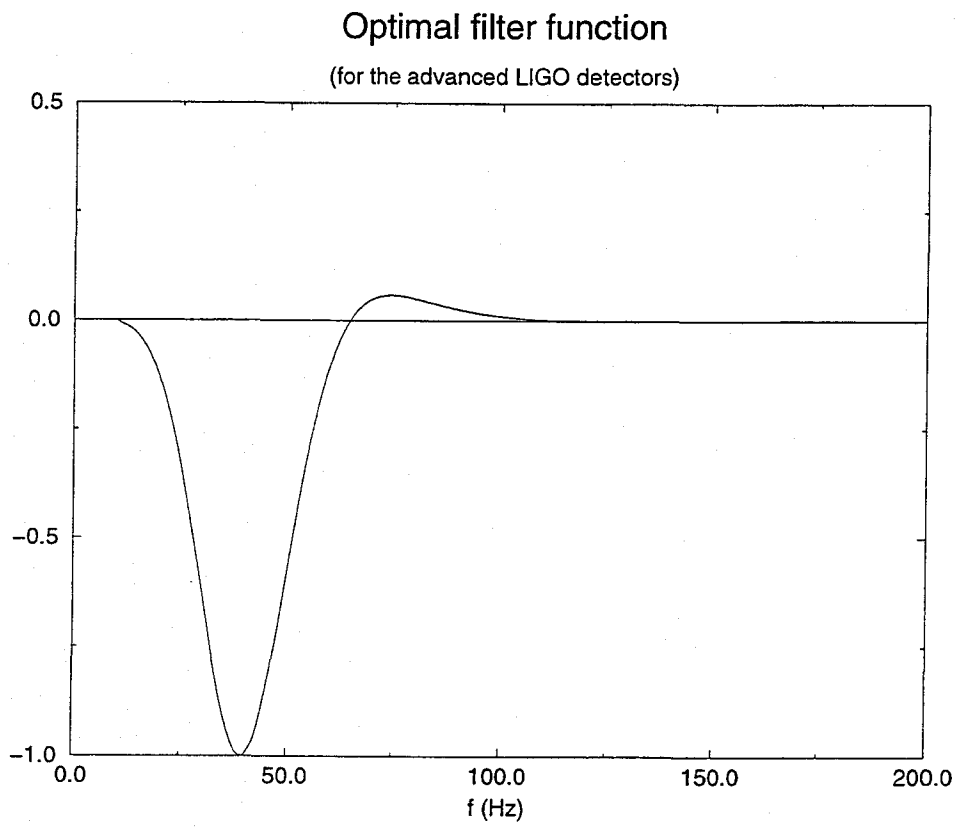


Figure 53: Optimal filter function  $\tilde{Q}(f)$  (normalized to 1) for the advanced LIGO detectors.

## 7.18 Discussion: Theoretical signal-to-noise ratio for the stochastic background

In order to reliably detect a stochastic background of gravitational radiation, we will need to be able to say (with a certain level of confidence) that an observed positive mean value for the cross-correlation signal measurements is not the result of detector noise alone, but rather is the result of an incident stochastic background. This leads us naturally to consider the signal-to-noise ratio, since the larger its value, the more confident we will be in saying that the observed mean value of our measurements is a valid estimate of the true mean value of the stochastic background signal. Thus, an interesting question to ask in regard to stochastic background searches is: "What is the theoretically predicted signal-to-noise ratio after a total observation time  $T$ , for a given pair of detectors, and for a given strength of the stochastic background?" In this section, we derive the mathematical equations that we need to answer this question. Numerical results will be calculated by example programs in Secs. 7.20 and 7.21.

To answer the above question, we will need to evaluate both the mean value

$$\mu := \langle S \rangle \quad (7.18.1)$$

and the variance

$$\sigma^2 := \langle S^2 \rangle - \langle S \rangle^2 \quad (7.18.2)$$

of the stochastic background cross-correlation signal  $S$ . The signal-to-noise ratio SNR is then given by,

$$\text{SNR} := \frac{\mu}{\sigma}. \quad (7.18.3)$$

As described in Sec. 7.16, if the magnitude of the noise intrinsic to the detectors is much larger than the magnitude of the signal due to the stochastic background, then

$$\mu = T \frac{3H_0^2}{20\pi^2} \int_{-\infty}^{\infty} df \gamma(|f|) |f|^{-3} \Omega_{\text{gw}}(|f|) \bar{Q}(f) \quad (7.18.4)$$

$$\sigma^2 \approx \frac{T}{4} \int_{-\infty}^{\infty} df P_1(|f|) P_2(|f|) |\bar{Q}(f)|^2, \quad (7.18.5)$$

where  $\bar{Q}(f)$  is an arbitrary filter function. The choice

$$\bar{Q}(f) := \lambda \frac{\gamma(f) \Omega_{\text{gw}}(f)}{f^3 P_1(f) P_2(f)} \quad (7.18.6)$$

maximizes the signal-to-noise ratio (7.18.3). It is the *optimal* filter for stochastic background searches. As also described in Sec. 7.16, if the stochastic background has a constant frequency spectrum

$$\Omega_{\text{gw}}(f) = \begin{cases} \Omega_0 & f_{\text{low}} \leq f \leq f_{\text{high}} \\ 0 & \text{otherwise,} \end{cases}$$

it is convenient to choose the normalization constant  $\lambda$  so that

$$\mu = \Omega_0 T. \quad (7.18.7)$$

For such a  $\lambda$ ,

$$\sigma^2 \approx \frac{T}{2} \left( \frac{10\pi^2}{3H_0^2} \right)^2 \left[ \int_{f_{\text{low}}}^{f_{\text{high}}} df \frac{\gamma^2(f)}{f^6 P_1(f) P_2(f)} \right]^{-1}, \quad (7.18.8)$$

which leads to the *squared* signal-to-noise ratio

$$(\text{SNR})^2 = T \Omega_0^2 \frac{9H_0^4}{50\pi^4} \int_{f_{\text{low}}}^{f_{\text{high}}} df \frac{\gamma^2(f)}{f^6 P_1(f) P_2(f)}. \quad (7.18.9)$$

This is equation (3.33) in Ref. [21].

But suppose that we do *not* assume that the noise intrinsic to the detectors is much larger in magnitude than that of the stochastic background. Then Eq. (7.18.5) for  $\sigma^2$  needs to be modified to take into account the non-negligible contributions to the variance brought in by the stochastic background signal. (Equation (7.18.4) for  $\mu$  is unaffected.) This change in  $\sigma^2$  implies that Eq. (7.18.6) for  $\tilde{Q}(f)$  is no longer optimal. But to simplify matters, we will leave  $\tilde{Q}(f)$  as is. Although such a  $\tilde{Q}(f)$  no longer maximizes the signal-to-noise ratio, it at least has the nice property that, for a stochastic background having a constant frequency spectrum, the normalization constant  $\lambda$  can be chosen so that  $\tilde{Q}(f)$  is independent of  $\Omega_0$ . The expression for the actual optimal filter function, on the other hand, would depend on  $\Omega_0$ .

So keeping Eq. (7.18.6) for  $\tilde{Q}(f)$ , let us consider a stochastic background having a constant frequency spectrum as described above. Then we can still choose  $\lambda$  so that

$$\mu = \Omega_0 T, \quad (7.18.10)$$

(the same  $\lambda$  as before works), but now

$$\begin{aligned} \sigma^2 = & \frac{T}{2} \left[ \int_{f_{\text{low}}}^{f_{\text{high}}} df \frac{\gamma^2(f)}{f^6 P_1(f) P_2(f)} \right]^{-2} \left\{ \left( \frac{10\pi^2}{3H_0^2} \right)^2 \int_{f_{\text{low}}}^{f_{\text{high}}} df \frac{\gamma^2(f)}{f^6 P_1(f) P_2(f)} \right. \\ & + \Omega_0 \left( \frac{10\pi^2}{3H_0^2} \right) \int_{f_{\text{low}}}^{f_{\text{high}}} df \frac{\gamma^2(f)}{f^9 P_1^2(f) P_2(f)} + \Omega_0 \left( \frac{10\pi^2}{3H_0^2} \right) \int_{f_{\text{low}}}^{f_{\text{high}}} df \frac{\gamma^2(f)}{f^9 P_1(f) P_2^2(f)} \\ & \left. + \Omega_0^2 \int_{f_{\text{low}}}^{f_{\text{high}}} df \frac{\gamma^2(f)}{f^{12} P_1^2(f) P_2^2(f)} (1 + \gamma^2(f)) \right\}. \quad (7.18.11) \end{aligned}$$

The new squared signal-to-noise ratio is  $\Omega_0^2 T^2$  divided by the above expression for  $\sigma^2$ .

Note the three additional terms that contribute to the variance  $\sigma^2$ . Roughly speaking, they can be thought of as two “signal+noise” cross-terms and one “pure signal” variance term. These are the terms proportional to  $\Omega_0$  and  $\Omega_0^2$ , respectively. When  $\Omega_0$  is small, the above expression for  $\sigma^2$  reduces to the pure noise variance term (7.18.8). This is what we expect to be the case in practice. But for the question that we posed at the beginning of the section, where no assumption is made about the relative strength of the stochastic background and detector noise signals, the more complicated expression (7.18.11) for  $\sigma^2$  should be used. The function `calculate_var()`, which is defined in the following section, calculates the variance using this equation.

### 7.19 Function: calculate\_var()

double calculate\_var(int n, float delta\_f, float omega\_0, float f\_low, float f\_high, float t, double \*gamma12, double \*power1, double \*power2)

This function calculates the theoretical variance  $\sigma^2$  of the stochastic background cross-correlation signal  $S$ .

The arguments of calculate\_var() are:

n: Input. The number  $N$  of discrete frequency values at which the spectra are to be evaluated.

delta\_f: Input. The spacing  $\Delta f$  (in Hz) between two adjacent discrete frequency values:  $\Delta f := f_{i+1} - f_i$ .

omega\_0: Input. The constant value  $\Omega_0$  (dimensionless) of the frequency spectrum  $\Omega_{\text{gw}}(f)$  for the stochastic background:

$$\Omega_{\text{gw}}(f) = \begin{cases} \Omega_0 & f_{\text{low}} \leq f \leq f_{\text{high}} \\ 0 & \text{otherwise.} \end{cases}$$

$\Omega_0$  should be greater than or equal to zero.

f\_low: Input. The frequency  $f_{\text{low}}$  (in Hz) below which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background is zero.  $f_{\text{low}}$  should lie in the range  $0 \leq f_{\text{low}} \leq f_{\text{Nyquist}}$ , where  $f_{\text{Nyquist}}$  is the Nyquist critical frequency. (The Nyquist critical frequency is defined by  $f_{\text{Nyquist}} := 1/(2\Delta t)$ , where  $\Delta t$  is the sampling period of the detector.)  $f_{\text{low}}$  should also be less than or equal to  $f_{\text{high}}$ .

f\_high: Input. The frequency  $f_{\text{high}}$  (in Hz) above which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background is zero.  $f_{\text{high}}$  should lie in the range  $0 \leq f_{\text{high}} \leq f_{\text{Nyquist}}$ . It should also be greater than or equal to  $f_{\text{low}}$ .

t: Input. The observation time  $T$  (in sec) of the measurement.

gamma12: Input. gamma12[0..n-1] is an array of double precision variables containing the values of the overlap reduction function  $\gamma(f)$  for the two detector sites. These variables are dimensionless. gamma12[i] contains the value of  $\gamma(f)$  evaluated at the discrete frequency  $f_i = i\Delta f$ , where  $i = 0, 1, \dots, N-1$ .

power1: Input. power1[0..n-1] is an array of double precision variables containing the values of the noise power spectrum  $P_1(f)$  of the first detector. These variables have units of  $\text{strain}^2/\text{Hz}$  (or seconds). power1[i] contains the value of  $P_1(f)$  evaluated at the discrete frequency  $f_i = i\Delta f$ , where  $i = 0, 1, \dots, N-1$ .

power2: Input. power2[0..n-1] is an array of double precision variables containing the values of the noise power spectrum  $P_2(f)$  of the second detector, in exactly the same format as the previous argument.

The double precision value returned by calculate\_var() is the theoretical variance  $\sigma^2$  given by Eq. (7.18.11) of Sec. 7.18. As discussed in that section, Eq. (7.18.11) for  $\sigma^2$  makes no assumption about the relative strengths of the stochastic background and detector noise signal, but it does use Eq. (7.18.6) for the filter function  $\tilde{Q}(f)$ , which is optimal only for the large detector noise case. For stochastic background simulations,  $\Omega_0$  is usually chosen to equal some known non-zero value. This is the value that should be passed as a parameter to calculate\_var(). For stochastic background searches (where  $\Omega_0$  is not known a priori) the value of the parameter  $\Omega_0$  should be set to zero. The variance for this case is given by Eq. (7.18.8).

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Comments: None.

## 7.20 Example: snr program

As mentioned in Sec. 7.18, an interesting question to ask in regard to stochastic background searches is: "What is the theoretically predicted signal-to-noise ratio after a total observation time  $T$ , for a given pair of detectors, and for a given strength of the stochastic background?" The following example program shows how one can combine the functions `detector_site()`, `noise_power()`, `overlap()`, and `calculate_var()` to answer this question for the case of a stochastic background having a constant frequency spectrum:  $\Omega_{gw}(f) = \Omega_0$  for  $f_{low} \leq f \leq f_{high}$ . Specifically, we calculate and display the theoretical SNR after approximately 4 months of observation time ( $T = 1.0 \times 10^7$  seconds), for the initial Hanford, WA and Livingston, LA LIGO detectors, and for  $\Omega_0 = 3.0 \times 10^{-6}$  for  $5 \text{ Hz} \leq f \leq 5000 \text{ Hz}$ . (The answer is  $\text{SNR} = 1.73$ , which means that we could say, with greater than 95% confidence, that a stochastic background has been detected.) By changing the parameters in the `#define` statements listed at the beginning of the program, one can calculate and display the signal-to-noise ratios for different observation times  $T$ , for different detector pairs, and for different strengths  $\Omega_0$  of the stochastic background.

Note: Values of  $N$  and  $\Delta f$  should be chosen so that the whole frequency range (from DC to the Nyquist critical frequency) is included, and that there are a reasonably large number of discrete frequency values for approximating integrals by sums. The final answer, however, is independent of the choice of  $N$  and  $\Delta f$ , for  $N$  sufficiently large and  $\Delta f$  sufficiently small.

```
/* main program to calculate the theoretical snr */

#include "grasp.h"

#define DETECTORS_FILE "detectors.dat" /* file containing detector info */
#define SITE1_CHOICE 1 /* 1=LIGO-Hanford site */
#define SITE2_CHOICE 2 /* 2=LIGO-Livingston site */
#define OMEGA_0 (3.0e-6) /* Omega_0 (for initial detectors) */
#define F_LOW 0.0 /* minimum frequency (in Hz) */
#define F_HIGH (1.0e+4) /* maximum frequency (in Hz) */
#define T (1.0e+7) /* total observation time (in sec) */
#define N 40000 /* number of frequency points */
#define DELTA_F 0.25 /* frequency spacing (in Hz) */

int main(int argc, char **argv)
{
    double mean, variance, stddev, snr;

    float site1_parameters[9], site2_parameters[9];
    char site1_name[100], noise1_file[100], whiten1_file[100];
    char site2_name[100], noise2_file[100], whiten2_file[100];

    double *power1, *power2;
    double *gamma12;

    /* ALLOCATE MEMORY */
    power1 = (double *)malloc(N*sizeof(double));
    power2 = (double *)malloc(N*sizeof(double));
    gamma12 = (double *)malloc(N*sizeof(double));

    /* CALL DETECTOR_SITE() TO GET SITE PARAMETER INFORMATION */
    detector_site(DETECTORS_FILE, SITE1_CHOICE, site1_parameters, site1_name,
                 noise1_file, whiten1_file);
    detector_site(DETECTORS_FILE, SITE2_CHOICE, site2_parameters, site2_name,
                 noise2_file, whiten2_file);
```

```

/* CALL NOISE_POWER() AND OVERLAP() */
noise_power(noise1_file,N,DELTA_F,power1);
noise_power(noise2_file,N,DELTA_F,power2);
overlap(site1_parameters,site2_parameters,N,DELTA_F,gamma12);

/* CALCULATE MEAN, VARIANCE, STDDEV, AND SNR */
mean=OMEGA_0*T;
variance=calculate_var(N,DELTA_F,OMEGA_0,F_LOW,F_HIGH,T,gamma12,
power1,power2);
stddev=sqrt(variance);
snr=mean/stddev;

/* DISPLAY RESULTS */
printf("\n");
printf("Detector site 1 = %s\n",site1_name);
printf("Detector site 2 = %s\n",site2_name);
printf("Omega_0 = %e\n",OMEGA_0);
printf("f_low = %e Hz\n",F_LOW);
printf("f_high = %e Hz\n",F_HIGH);
printf("Observation time T = %e sec\n",T);
printf("Theoretical S/N = %e\n",snr);
printf("\n");

return 0;
}

```

## 7.21 Example: omega\_min program

The example program described in the previous section calculates the theoretical signal-to-noise ratio after a total observation time  $T$ , for a given pair of detectors, and for a given strength  $\Omega_0$  of the stochastic background. A related—and equally important—question is the *inverse*: “What is the minimum value of  $\Omega_0$  required to produce a given SNR after a given observation time  $T$ ?” For example, if  $\text{SNR} = 1.65$ , then the answer to the above question is the minimum value of  $\Omega_0$  for a stochastic background that is detectable with 95% confidence after an observation time  $T$ . The following example program calculates and displays this 95% confidence value of  $\Omega_0$  for the initial Hanford, WA and Livingston, LA LIGO detectors, for approximately 4 months ( $T = 1.0 \times 10^7$  seconds) of observation time. (The answer is  $\Omega_0 = 2.87 \times 10^{-6}$ .) Again, we are assuming in this example program that the stochastic background has a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $5 \text{ Hz} \leq f \leq 5000 \text{ Hz}$ . By modifying the parameters in the #define statements listed at the beginning of the program, one can calculate and display the minimum required  $\Omega_0$ 's for different detector pairs, for different signal-to-noise ratios, and for different observation times  $T$ .

Note: As shown in Sec. 7.18, the squared signal-to-noise ratio can be written in the following form:

$$(\text{SNR})^2 = \frac{T \Omega_0^2}{A + B \Omega_0 + C \Omega_0^2}, \quad (7.21.1)$$

where  $A$ ,  $B$ , and  $C$  are complicated expressions involving integrals of the the overlap reduction function and the noise power spectra of the detectors, but are independent of  $T$  and  $\Omega_0$ . Thus, given SNR and  $T$ , Eq. (7.21.1) becomes a quadratic for  $\Omega_0$ :

$$a \Omega_0^2 + b \Omega_0 + c = 0, \quad (7.21.2)$$

which we can easily solve. It is this procedure that we implement in the following program.

```

/* main program to calculate the minimum detectable omega_0 */

#include "grasp.h"

#define DETECTORS_FILE "detectors.dat" /* file containing detector info */
#define SITE1_CHOICE 1 /* 1=LIGO-Hanford site */
#define SITE2_CHOICE 2 /* 2=LIGO-Livingston site */
#define SNR 1.65 /* 1.65=SNR for 95% confidence */
#define F_LOW 0.0 /* minimum frequency (in Hz) */
#define F_HIGH (1.0e+4) /* maximum frequency (in Hz) */
#define T (1.0e+7) /* total observation time (in sec) */
#define N 40000 /* number of frequency points */
#define DELTA_F 0.25 /* frequency spacing (in Hz) */

int main(int argc, char **argv)
{
    int i;
    float f;

    double factor, f3, f6, f9, f12, p1, p2, g2;
    double int1, int2, int3, int4;
    double a, b, c, omega_0;

    float site1_parameters[9], site2_parameters[9];
    char site1_name[100], noise1_file[100], whiten1_file[100];
    char site2_name[100], noise2_file[100], whiten2_file[100];

```



```

double *power1,*power2;
double *gamma12;

/* ALLOCATE MEMORY */
power1=(double *)malloc(N*sizeof(double));
power2=(double *)malloc(N*sizeof(double));
gamma12=(double *)malloc(N*sizeof(double));

/* CALL DETECTOR_SITE() TO GET SITE PARAMETER INFORMATION */
detector_site(DETECTORS_FILE,SITE1_CHOICE,site1_parameters,site1_name,
              noise1_file,whiten1_file);
detector_site(DETECTORS_FILE,SITE2_CHOICE,site2_parameters,site2_name,
              noise2_file,whiten2_file);

/* CALL NOISE_POWER() AND OVERLAP() */
noise_power(noise1_file,N,DELTA_F,power1);
noise_power(noise2_file,N,DELTA_F,power2);
overlap(site1_parameters,site2_parameters,N,DELTA_F,gamma12);

/* CALCULATE INTEGRALS FOR VARIANCE */
int1=int2=int3=int4=0.0;

for (i=1;i<N;i++) { /* start sum at i=1 to avoid possible division */
                    /* by 0 (e.g., if f_low=0) */
    f=i*DELTA_F;
    if (F_LOW<=f && f<=F_HIGH) {
        f3=f*f*f;
        f6=f3*f3;
        f9=f6*f3;
        f12=f9*f3;
        g2=gamma12[i]*gamma12[i];
        p1=power1[i];
        p2=power2[i];

        int1+=DELTA_F*g2/(f6*p1*p2);
        int2+=DELTA_F*g2/(f9*p1*p1*p2);
        int3+=DELTA_F*g2/(f9*p1*p2*p2);
        int4+=DELTA_F*g2*(1.0+g2)/(f12*p1*p1*p2*p2);
    }
}

/* CALCULATE COEFFICIENTS OF QUADRATIC EQUATION */
factor=10.0*M_PI*M_PI/(3.0*HUBBLE*HUBBLE);

a=(int4/int1-2.0*T*int1/(SNR*SNR))/(factor*factor);
b=(int2+int3)/(int1*factor);
c=1.0;

/* SOLVE THE QUADRATIC */
omega_0=0.5*(-b-sqrt(b*b-4*a*c))/a;

/* DISPLAY RESULTS */
printf("\n");
printf("Detector site 1 = %s\n",site1_name);
printf("Detector site 2 = %s\n",site2_name);
printf("S/N ratio = %e\n",SNR);
printf("f_low = %e Hz\n",F_LOW);
printf("f_high = %e Hz\n",F_HIGH);
printf("Observation time T = %e sec\n",T);

```

```
printf("Minumum Omega_0 = %e\n", omega_0);  
printf("\n");  
  
return 0;  
}
```

## 7.22 Function: analyze()

```
void analyze(int average, float *in1, float *in2, int n, float delta_t, float
f_low, float f_high, double *gamma12, double *whiten1, double *whiten2, int
realtime_noise1, int realtime_noise2, double *power1, double *power2, double
*signal, double *variance)
```

This high-level function performs the optimal data processing for the detection of an isotropic and unpolarized stochastic background of gravitational radiation having a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $f_{\text{low}} \leq f \leq f_{\text{high}}$ . It calculates the cross-correlation signal value  $S$  and theoretical variance  $\sigma^2$ , taking as input the continuous-in-time whitened data streams  $o_1(t)$  and  $o_2(t)$  produced by two detectors.

The arguments of analyze() are:

**average:** Input. An integer variable that should be set equal to 1 if the values of the real-time cross-correlation and/or noise power spectra corresponding to two overlapped data sets are to be averaged.

**in1:** Input. `in1[0..n-1]` is an array of floating point variables containing the values of the continuous-in-time whitened data stream  $o_1(t)$  produced by the first detector.  $o_1(t)$  is the convolution of detector whitening filter  $W_1(t)$  with the data stream  $s_1(t) := h_1(t) + n_1(t)$ , where  $h_1(t)$  is the gravitational strain and  $n_1(t)$  is the noise intrinsic to the detector. These variables have units of rHz (or  $\text{sec}^{-1/2}$ ), which follows from the definition of  $s_1(t)$  as a strain and  $\tilde{W}_1(f)$  as the “inverse” of the square root of the noise power spectrum  $P_1(f)$ . `in1[i]` contains the value of  $o_1(t)$  evaluated at the discrete time  $t_i = i\Delta t$ , where  $i = 0, 1, \dots, N - 1$ .

**in2:** Input. `in2[0..n-1]` is an array of floating point variables containing the values of the continuous-in-time whitened data stream  $o_2(t)$  produced by the second detector, in exactly the same format as the previous argument.

**n:** Input. The number  $N$  of data points corresponding to an observation time  $T := N \Delta t$ , where  $\Delta t$  is the sampling period of the detectors, defined below.  $N$  should equal an integer power of 2.

**delta\_t:** Input. The sampling period  $\Delta t$  (in sec) of the detectors.

**f\_low:** Input. The frequency  $f_{\text{low}}$  (in Hz) below which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background is assumed to be zero.  $f_{\text{low}}$  should lie in the range  $0 \leq f_{\text{low}} \leq f_{\text{Nyquist}}$ , where  $f_{\text{Nyquist}}$  is the Nyquist critical frequency. (The Nyquist critical frequency is defined by  $f_{\text{Nyquist}} := 1/(2\Delta t)$ , where  $\Delta t$  is the sampling period of the detectors.)  $f_{\text{low}}$  should also be less than or equal to  $f_{\text{high}}$ .

**f\_high:** Input. The frequency  $f_{\text{high}}$  (in Hz) above which the spectrum  $\Omega_{\text{gw}}(f)$  of the stochastic background is assumed to be zero.  $f_{\text{high}}$  should lie in the range  $0 \leq f_{\text{high}} \leq f_{\text{Nyquist}}$ . It should also be greater than or equal to  $f_{\text{low}}$ .

**gamma12:** Input. `gamma12[0..n/2-1]` is an array of double precision variables containing the values of the overlap reduction function  $\gamma(f)$  for the two detector sites. These variables are dimensionless. `gamma12[i]` contains the value of  $\gamma(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

**whiten1:** Input. `whiten1[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\tilde{W}_1(f)$  of the whitening filter of the first detector. These variables have units rHz/strain (or  $\text{sec}^{-1/2}$ ), which are inverse to the units of the square root of the noise power spectrum  $P_1(f)$ . `whiten1[2*i]` and `whiten1[2*i+1]` contain, respectively, the values of the real and imaginary parts of  $\tilde{W}_1(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ .

`whiten2`: Input. `whiten2[0..n-1]` is an array of double precision variables containing the values of the real and imaginary parts of the spectrum  $\tilde{W}_2(f)$  of the whitening filter of the second detector, in exactly the same format as the previous argument.

`real_time_noise1`: Input. An integer variable that should be set equal to 1 if the real-time noise power spectrum  $P_1(f)$  of the first detector should be calculated and used when performing the data analysis.

`real_time_noise2`: Input. An integer variable that should be set equal to 1 if the real-time noise power spectrum  $P_2(f)$  for the second detector should be calculated and used when performing the data analysis.

`power1`: Input/Output. `power1[0..n/2-1]` is an array of double precision variables containing the values of the noise power spectrum  $P_1(f)$  of the first detector. These variables have units of  $\text{strain}^2/\text{Hz}$  (or seconds). `power1[i]` contains the value of  $P_1(f)$  evaluated at the discrete frequency  $f_i = i/(N\Delta t)$ , where  $i = 0, 1, \dots, N/2 - 1$ . If `real_time_noise1 = 1`, the values of `power1[0..n/2-1]` are changed to

$$P_1(f) := \frac{2}{T} \tilde{s}_1^*(f) \tilde{s}_1(f), \quad (7.22.1)$$

where  $\tilde{s}_1(f)$  is the Fourier transform of the unwhitened data stream  $s_1(t)$  at the first detector site. If `real_time_noise1  $\neq$  1`, the values of `power1[0..n/2-1]` are unchanged.

`power2`: Input/Output. `power2[0..n/2-1]` is an array of double precision variables containing the values of the noise power spectrum  $P_2(f)$  of the second detector, in exactly the same format as the previous argument.

`signal`: Output. A pointer to a double precision variable containing the value of the cross-correlation signal

$$S := \int_{f_{\text{low}}}^{f_{\text{high}}} df \tilde{s}_{12}(f) \tilde{Q}(f), \quad (7.22.2)$$

where  $\tilde{s}_{12}(f)$  is the real-time cross-correlation spectrum and  $\tilde{Q}(f)$  is the spectrum of the optimal filter function.  $S$  has units of seconds.

`variance`: Output. A pointer to a double precision variable containing the value of the theoretical variance  $\sigma^2$  of the cross-correlation signal  $S$ .  $\sigma^2$  has units of  $\text{sec}^2$ .

`analyze()` is very simple function, consisting primarily of calls to other more basic functions. If `real_time_noise1` or `real_time_noise2 = 1`, `analyze()` calls `extract_noise()` to obtain the desired real-time noise power spectra. It then calls `extract_signal()` and `optimal_filter()` to obtain the values of  $\tilde{s}_{12}(f)$  and  $\tilde{Q}(f)$ , which are needed to calculate the cross-correlation signal  $S$ , according to Eq. (7.22.2). Finally, `analyze()` calls `calculate_var()` to obtain the theoretical variance  $\sigma^2$  associated with  $S$ .

Note: One should call `analyze()` with `average  $\neq$  1`, when one suspects that the current input data `in1[]` and `in2[]` are *not* continuous with the data from the previous call to `analyze()`. This is because a discontinuity between the “old” and “new” data sets has a tendency to introduce spurious large frequency components into the real-time cross-correlation and/or noise power spectra, which should not be present. (See the discussion at the end of Secs. 7.14 and 7.15 for more details.)

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Comments: None.

### 7.23 Function: `prelim_stats()`

`prelim_stats(float omega_0, float t, double signal, double variance)`

This function calculates and displays the theoretical and experimental mean value, standard deviation, and signal-to-noise ratio for a set of stochastic background cross-correlation signal measurements, weighting each measurement by the inverse of the theoretical variance associated with that measurement.

The arguments of `prelim_stats()` are:

`omega_0`: Input. The constant value  $\Omega_0$  (dimensionless) of the frequency spectrum  $\Omega_{gw}(f)$  for the stochastic background:

$$\Omega_{gw}(f) = \begin{cases} \Omega_0 & f_{low} \leq f \leq f_{high} \\ 0 & \text{otherwise.} \end{cases}$$

$\Omega_0$  should be greater than or equal to zero.

`float t`: Input. The observation time  $T$  (in sec) of an individual measurement.

`double signal`: Input. The value  $S$  of the current cross-correlation signal measurement. This variable has units of seconds.

`double variance`: Input. The value  $\sigma^2$  of the theoretical variance associated with the current cross-correlation signal measurement. This variable has units of  $\text{sec}^2$ .

`prelim_stats()` calculates the theoretical and experimental mean value, standard deviation, and signal-to-noise ratio, weighting each measurement  $S_i$  by the inverse of the theoretical variance  $\sigma_i^2$  associated with that measurement. This choice of weighting maximizes the theoretical signal-to-noise, allowing for possible drifts in the detector noise power spectra over the course of time. More precisely, if we let  $S_i$  ( $i = 1, 2, \dots, n$ ) denote a set of  $n$  statistically independent random variables, each having the same mean value

$$\mu := \langle S_i \rangle, \quad (7.23.1)$$

but different variances

$$\sigma_i^2 := \langle S_i^2 \rangle - \langle S_i \rangle^2, \quad (7.23.2)$$

then one can show that the weighted-average

$$\bar{S} := \frac{\sum_{i=1}^n \lambda_i S_i}{\sum_{j=1}^n \lambda_j} \quad (7.23.3)$$

has maximum signal-to-noise ratio when  $\lambda_i = \sigma_i^{-2}$ . Roughly speaking, the above averaging scheme assigns more weight to signal values that are measured when the detectors are “quiet,” than to signal values that are measured when the detectors are “noisy.”

The values calculated and displayed by `prelim_stats()` are determined as follows:

- (i) The total observation time is

$$T_{tot} := n T, \quad (7.23.4)$$

where  $n$  is the total number of measurements, and  $T$  is the observation time of an individual measurement.

- (ii) The theoretical mean is given by the product

$$\mu_{theory} = \Omega_0 T. \quad (7.23.5)$$

This follows from our choice of normalization constant for the optimal filter function. (See Sec. 7.16 for more details.)

(iii) The theoretical variance is given by

$$\sigma_{\text{theory}}^2 = \frac{n}{\sum_{i=1}^n \sigma_i^{-2}}. \quad (7.23.6)$$

Note that when the detector noise power spectra are constant,  $\sigma_i^2 =: \sigma^2$  for  $i = 1, 2, \dots, n$  and  $\sigma_{\text{theory}}^2 = \sigma^2$ . This case arises, for example, if we do *not* calculate real-time noise power spectra, but use noise power information contained in data files instead.

(iv) The theoretical signal-to-noise ratio (for  $n$  measurements) is given by

$$\text{SNR}_{\text{theory}} = \sqrt{n} \frac{\mu_{\text{theory}}}{\sigma_{\text{theory}}}. \quad (7.23.7)$$

The factor of  $\sqrt{n}$  comes from our assumption that the  $n$  individual measurements are statistically independent.

(v) The experimental mean is the weighted-average

$$\mu_{\text{expt}} := \frac{\sum_{i=1}^n \sigma_i^{-2} S_i}{\sum_{j=1}^n \sigma_j^{-2}}. \quad (7.23.8)$$

(vi) The experimental variance is given by

$$\sigma_{\text{expt}}^2 := \frac{\sum_{i=1}^n \sigma_i^{-2} S_i^2}{\sum_{j=1}^n \sigma_j^{-2}} - \mu_{\text{expt}}^2. \quad (7.23.9)$$

When the weights  $\sigma_i^{-2}$  are constant, the above formula reduces to the usual expression

$$\sigma_{\text{expt}}^2 = \frac{1}{n} \sum_{i=1}^n S_i^2 - \left( \frac{1}{n} \sum_{i=1}^n S_i \right)^2 \quad (7.23.10)$$

for the variance of  $n$  measurements  $S_i$ .

(vii) The experimental signal-to-noise ratio is given by

$$\text{SNR}_{\text{expt}} = \sqrt{n} \frac{\mu_{\text{expt}}}{\sigma_{\text{expt}}}. \quad (7.23.11)$$

(viii) The relative error in the signal-to-noise ratios is

$$\text{relative error} := \left| \frac{\text{SNR}_{\text{theory}} - \text{SNR}_{\text{expt}}}{\text{SNR}_{\text{theory}}} \right| \cdot 100\%. \quad (7.23.12)$$

The value of this quantity should be on the order of  $(1/\text{SNR}_{\text{theory}}) \cdot 100\%$ .

Note: `prelim_stats()` has internally-defined static variables which keep track of the number of times that it has been called, the sum of the weights, the sum of weights times the signal values, and the sum of the weights times the signal values squared.

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Comments: None.

## 7.24 Function: `statistics()`

```
void statistics(float *input, int n, int num_bins)
```

This function calculates and displays the mean value, standard deviation, signal-to-noise ratio, and confidence intervals for an input array of (assumed) statistically independent measurements  $x_i$  of a random variable  $x$ . This function also writes output data to two files: `histogram.dat` and `gaussian.dat`. The first file contains a histogram of the input data  $x_i$ ; the second file contains the Gaussian probability distribution that best matches this histogram. (See Sec. 7.22 for more details.)

The arguments of `statistics()` are:

`input`: Input. `input[0..n-1]` is an array of floating point variables containing the values of a set of (assumed) statistically independent measurements  $x_i$  of a random variable  $x$ .

`n`: Input. The length  $N$  of the input data array. If  $N < 2$ , `statistics()` prints out an error message and aborts execution.

`num_bins`: Input. The number of bins to be used when constructing a histogram of the input data  $x_i$ .

`statistics()` calculates and displays the mean value and standard deviation of the input data  $x_i$ . It also calculates and displays the signal-to-noise ratio and 68%, 90%, and 95% confidence intervals for the input data, assuming that the  $x_i$  are statistically independent measurements of a random variable  $x$ . `statistics()` also writes output data to two files:

- (i) `histogram.dat` is a two-column file of floating point numbers containing a histogram of the input data  $x_i$ . The length of each column of data is equal to `num_bins`, and the histogram is normalized so that it has unit area.
- (ii) `gaussian.dat` is a two-column file of floating point numbers containing the Gaussian probability distribution function that best matches the histogram of the input data  $x_i$ . Each column of `gaussian.dat` has a length equal to 8192. There are also three *markers* included in the Gaussian probability distribution data: One marker for the mean, and two for the  $\pm$  one standard deviation values of  $x$ .

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Comments: In the context of the stochastic background routines, `statistics()` is used to perform a statistical analysis of the cross-correlation signal values  $S_i$  calculated by the function `analyze()`.

## 7.25 Example: simulation program

By combining all of the functions defined in the previous sections, one can write a program to simulate the generation and detection of a stochastic background of gravitational radiation having a constant frequency spectrum:  $\Omega_{\text{gw}}(f) = \Omega_0$  for  $f_{\text{low}} \leq f \leq f_{\text{high}}$ . The following example program is a simulation for the initial Hanford, WA and Livingston, LA LIGO detectors. The parameters chosen for this particular simulation are contained in the #define statements listed at the beginning of the program. By changing these parameters, one can simulate the generation and detection of a stochastic background for different stochastic backgrounds (i.e., for different values of  $\Omega_0$ ,  $f_{\text{low}}$ , and  $f_{\text{high}}$ ) and for different detector pairs. The number of data points, the sampling period of the detectors, and the total observation time for the simulation, etc. can also be modified. Preliminary statistics are displayed during the simulation. In addition, a histogram and the best-fit Gaussian probability distribution for the output data are stored in two files: histogram.dat and gaussian.dat. Sample output produced by the simulation and a plot of the histogram and best-fit Gaussian data are given in Sec. 7.26.

```
/* main program for stochastic background simulation */

#include "grasp.h"

#define DETECTORS_FILE "detectors.dat" /* file containing detector info */
#define SITE1_CHOICE 1 /* identification number for site 1 */
#define SITE2_CHOICE 2 /* identification number for site 2 */
#define FAKE_SB 1 /* 1: simulate stochastic background */
/* 0: stochastic background from real data */
#define FAKE_NOISE1 1 /* 1: simulate detector noise at site 1 */
/* 0: detector noise from real data at site 1 */
#define FAKE_NOISE2 1 /* 1: simulate detector noise at site 2 */
/* 0: detector noise from real data at site 2 */

#define N 65536 /* number of data points */
#define DELTA_T (5.0e-5) /* sampling period (in sec) */
#define OMEGA_0 (1.0e-3) /* omega_0 */
#define F_LOW (0.0) /* minimum frequency (in Hz) */
#define F_HIGH (1.0e4) /* maximum frequency (in Hz) */
#define REAL_TIME_NOISE1 0 /* 1: use real-time noise at site 1 */
/* 0: use noise information from data file */
#define REAL_TIME_NOISE2 0 /* 1: use real-time noise at site 2 */
/* 0: use noise information from data file */

#define NUM_RUNS 2500 /* number of runs (for simulation) */
#define NUM_BINS 200 /* number of bins (for statistics) */

int main(int argc, char **argv)
{
    int i, pass_test=0, previous_test, runs_completed=0, seed= -17;
    float delta_f;
    double signal, variance;

    float site1_parameters[9], site2_parameters[9];
    char site1_name[100], noise1_file[100], whiten1_file[100];
    char site2_name[100], noise2_file[100], whiten2_file[100];

    double *generation_power1, *generation_power2;
    double *analysis_power1, *analysis_power2;
    double *whiten1, *whiten2;
    double *gamma12;
    float *out1, *out2;
    float *stats;
```



```

/* ALLOCATE MEMORY */
generation_power1=(double *)malloc((N/2)*sizeof(double));
generation_power2=(double *)malloc((N/2)*sizeof(double));
analysis_power1=(double *)malloc((N/2)*sizeof(double));
analysis_power2=(double *)malloc((N/2)*sizeof(double));
whiten1=(double *)malloc(N*sizeof(double));
whiten2=(double *)malloc(N*sizeof(double));
gamma12=(double *)malloc((N/2)*sizeof(double));
out1=(float *)malloc(N*sizeof(float));
out2=(float *)malloc(N*sizeof(float));
stats=(float *)malloc(NUM_RUNS*sizeof(float));

/* INITIALIZE OUTPUT ARRAYS TO ZERO */
for (i=0;i<N;i++) out1[i]=out2[i]=0.0;

/* CALL DETECTOR_SITE() TO GET SITE PARAMETER INFORMATION */
detector_site(DETECTORS_FILE, SITE1_CHOICE, site1_parameters, site1_name,
              noise1_file, whiten1_file);
detector_site(DETECTORS_FILE, SITE2_CHOICE, site2_parameters, site2_name,
              noise2_file, whiten2_file);

/* DISPLAY STOCHASTIC BACKGROUND SIMULATION PARAMETERS */
printf("\n");
printf("STOCHASTIC GRAVITATIONAL WAVE BACKGROUND SIMULATION\n");
printf("\n");
printf("PARAMETERS:\n");
printf("Simulated stochastic background (0=no,1=yes): %d\n",FAKE_SB);
printf("Simulated detector noise at site 1 (0=no,1=yes): %d\n",FAKE_NOISE1);
printf("Simulated detector noise at site 2 (0=no,1=yes): %d\n",FAKE_NOISE2);
printf("Real-time noise at site 1 (0=no,1=yes): %d\n", REAL_TIME_NOISE1);
printf("Real-time noise at site 2 (0=no,1=yes): %d\n", REAL_TIME_NOISE2);
printf("Detector site 1 = %s\n",site1_name);
printf("Detector site 2 = %s\n",site2_name);
printf("Sampling period = %e seconds\n",DELTA_T);
printf("Number of data points = %d\n",N);
printf("Omega_0 = %e\n",OMEGA_0);
printf("f_low = %e Hz\n",F_LOW);
printf("f_high = %e Hz\n",F_HIGH);
printf("Number of runs (for simulation) = %d\n",NUM_RUNS);
printf("Number of bins (for statistics) = %d\n",NUM_BINS);
printf("\n");

/* CONSTRUCT NOISE POWER (FOR SIGNAL GENERATION), WHITENING FILTER */
/* AND THE OVERLAP REDUCTION FUNCTION */
delta_f=(float)(1.0/(N*DELTA_T));
noise_power(noise1_file,N/2,delta_f,generation_power1);
noise_power(noise2_file,N/2,delta_f,generation_power2);
whiten(whiten1_file,N/2,delta_f,whiten1);
whiten(whiten2_file,N/2,delta_f,whiten2);
overlap(site1_parameters,site2_parameters,N/2,delta_f,gamma12);

/* CONSTRUCT NOISE_POWER (FOR SIGNAL ANALYSIS) IF REAL-TIME NOISE */
/* IS NOT DESIRED */
if (REAL_TIME_NOISE1!=1) {
    for (i=0;i<N/2;i++) analysis_power1[i]=generation_power1[i];
}
if (REAL_TIME_NOISE2!=1) {
    for (i=0;i<N/2;i++) analysis_power2[i]=generation_power2[i];
}

```

```

}

/* PERFORM THE SIMULATION */
for (i=1;i<=NUM_RUNS;i++) {

    /* SIMULATE STOCHASTIC BACKGROUND AND/OR DETECTOR NOISE, IF DESIRED */
    if (FAKE_SB==1 || FAKE_NOISE1==1 || FAKE_NOISE2==1) {
        monte_carlo(FAKE_SB,FAKE_NOISE1,FAKE_NOISE2,N,DELTA_T,OMEGA_0,
                    F_LOW,F_HIGH,gamma12,
                    generation_power1,generation_power2,
                    whiten1,whiten2,out1,out2,&seed);
    }

    /* TEST DATA TO SEE IF GAUSSIAN */
    previous_test=pass_test;
    pass_test=test_data12(N,out1,out2);

    if (pass_test==1) {

        /* ANALYZE DATA */
        analyze(previous_test,out1,out2,N,DELTA_T,OMEGA_0,F_LOW,F_HIGH,
                gamma12,whiten1,whiten2,
                REAL_TIME_NOISE1,REAL_TIME_NOISE2,
                analysis_power1,analysis_power2,&signal,&variance);

        /* DISPLAY PRELIMINARY STATISTICS */
        prelim_stats(OMEGA_0,N*DELTA_T,signal,variance);

        /* UPDATE RUNS COMPLETED AND STATS ARRAY FOR FINAL STATISTICS */
        runs_completed++;
        stats[runs_completed-1]=signal;
    }

} /* end for (i=1;i<+NUM_RUNS;i++) */

/* FINAL STATISTICS */
printf("\n");
statistics(stats,runs_completed,NUM_BINS);

return 0;
}

```

## 7.26 Some output from the simulation program

Below is a sample of the output that is produced during the execution of the stochastic background simulation program described in Sec. 7.25. Also shown, in Fig. 54, is a plot of the histogram and best-fit Gaussian probability distribution that were stored in data files by the function `statistics()`. For this particular simulation, the total number of runs was equal to 1271 and the number of bins for the histogram was equal to 200.

```
total number of runs completed=815
total observation time =2.670592e+03 seconds
signal value=2.659629e-03
experimental mean=3.360998e-03
experimental stddev=1.214569e-02
experimental SNR=7.899961e+00
theoretical mean=3.276800e-03
theoretical stddev=1.112916e-02
theoretical SNR=8.405551e+00
relative error in SNR=6 percent
experimental omega_0=1.025695e-03
theoretical omega_0=1.000000e-03
theoretical omega_0 for detection with 95 percent confidence=1.962989e-04
```

```
total number of runs completed=816
total observation time =2.673869e+03 seconds
signal value=-3.592409e-03
experimental mean=3.352476e-03
experimental stddev=1.214068e-02
experimental SNR=7.888017e+00
theoretical mean=3.276800e-03
theoretical stddev=1.112916e-02
theoretical SNR=8.410706e+00
relative error in SNR=6 percent
experimental omega_0=1.023095e-03
theoretical omega_0=1.000000e-03
theoretical omega_0 for detection with 95 percent confidence=1.961785e-04
```

```
total number of runs completed=817
total observation time =2.677146e+03 seconds
signal value=-7.967954e-03
experimental mean=3.338620e-03
experimental stddev=1.213970e-02
experimental SNR=7.860860e+00
theoretical mean=3.276800e-03
theoretical stddev=1.112916e-02
theoretical SNR=8.415858e+00
relative error in SNR=6 percent
experimental omega_0=1.018866e-03
theoretical omega_0=1.000000e-03
theoretical omega_0 for detection with 95 percent confidence=1.960585e-04
```

Data segment 1 failed Gaussian test!

```
total number of runs completed=818
total observation time =2.680422e+03 seconds
signal value=1.447747e-02
experimental mean=3.352238e-03
experimental stddev=1.213852e-02
```

experimental SNR=7.898519e+00  
theoretical mean=3.276800e-03  
theoretical stddev=1.112916e-02  
theoretical SNR=8.421007e+00  
relative error in SNR=6 percent  
experimental omega\_0=1.023022e-03  
theoretical omega\_0=1.000000e-03  
theoretical omega\_0 for detection with 95 percent confidence=1.959386e-04

total number of runs completed=819  
total observation time =2.683699e+03 seconds  
signal value=3.647211e-03  
experimental mean=3.352598e-03  
experimental stddev=1.213111e-02  
experimental SNR=7.909022e+00  
theoretical mean=3.276800e-03  
theoretical stddev=1.112916e-02  
theoretical SNR=8.426153e+00  
relative error in SNR=6 percent  
experimental omega\_0=1.023132e-03  
theoretical omega\_0=1.000000e-03  
theoretical omega\_0 for detection with 95 percent confidence=1.958189e-04

total number of runs completed=820  
total observation time =2.686976e+03 seconds  
signal value=-5.958459e-03  
experimental mean=3.341243e-03  
experimental stddev=1.212807e-02  
experimental SNR=7.889026e+00  
theoretical mean=3.276800e-03  
theoretical stddev=1.112916e-02  
theoretical SNR=8.431295e+00  
relative error in SNR=6 percent  
experimental omega\_0=1.019666e-03  
theoretical omega\_0=1.000000e-03  
theoretical omega\_0 for detection with 95 percent confidence=1.956995e-04

total number of runs completed=821  
total observation time =2.690253e+03 seconds  
signal value=1.057661e-02  
experimental mean=3.350056e-03  
experimental stddev=1.212331e-02  
experimental SNR=7.917764e+00  
theoretical mean=3.276800e-03  
theoretical stddev=1.112916e-02  
theoretical SNR=8.436435e+00  
relative error in SNR=6 percent  
experimental omega\_0=1.022356e-03  
theoretical omega\_0=1.000000e-03  
theoretical omega\_0 for detection with 95 percent confidence=1.955803e-04

Data segment 2 failed Gaussian test!

total number of runs completed=822  
total observation time =2.693530e+03 seconds  
signal value=6.683305e-03  
experimental mean=3.354111e-03  
experimental stddev=1.211649e-02  
experimental SNR=7.936639e+00

theoretical mean=3.276800e-03  
theoretical stddev=1.112916e-02  
theoretical SNR=8.441571e+00  
relative error in SNR=5 percent  
experimental omega\_0=1.023593e-03  
theoretical omega\_0=1.000000e-03  
theoretical omega\_0 for detection with 95 percent confidence=1.954613e-04

### Histogram and Gaussian Probability Distribution

(for the initial LIGO detectors simulation)

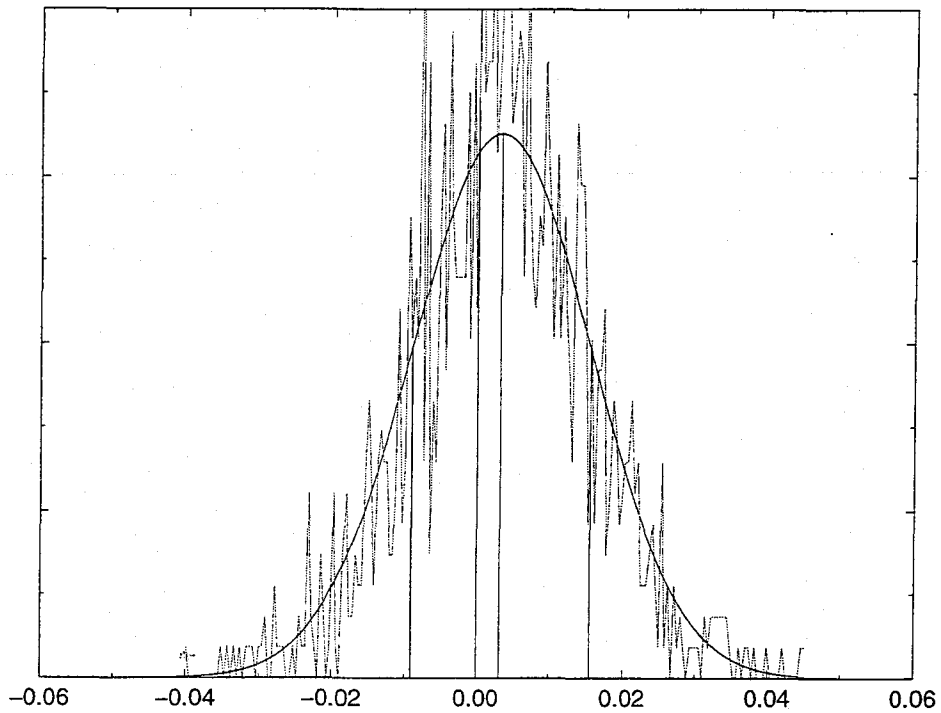


Figure 54: Histogram of the measured cross-correlation signal values, and the corresponding best-fit Gaussian probability distribution for the stochastic background simulation.

## 8 GRASP Routines: Supernovae and other transient sources

## 9 GRASP Routines: Periodic and quasi-periodic sources

## **10 GRASP Routines: General purpose utilities**

This section includes general purpose utility functions for a variety of purposes. For example, these include functions for error handling, to calculate time-averaged power spectra, and functions to graph data, listen to data, etc.



## 10.1 GRASP Error Handling

GR\_error is the GRASP error reporting module. It has two abstract interfaces which insulate the GRASP library and the programs which use it from the details of how GRASP will report errors and how the program will handle them. The internal interface provides GRASP itself with a standard method to report errors. The external interface allows programs which use GRASP to specify exactly how error reports are to be handled. In addition, a default set of handling routines is provided for printing error messages in a standard format to stderr or a log file.

### 10.1.1 Reporting Errors In GRASP Code

Reporting errors from within GRASP code is simple: every legal GRASP error report consists of exactly one call to `GR_start_error()`, zero or more calls to `GR_report_error()`, and exactly one call to `GR_end_error()`. Failing to call the functions in exactly this order will cause an assert to fail and the program to abort; this allows the code in the handler routines to safely assume that they will be called in the correct order.

`GR_start_error()` takes four arguments specifying the name of the function in which the error occurred, the RCS ID of the GRASP file which contains the function's source, the name of that file, and the line number on which the error report began. In practice providing this data is easy. Every GRASP file should declare a static string 'rcsid' containing the ID, and ANSI C defines the macros `_FILE_` and `_LINE_` which expand to the file name and line number, respectively. Within a given file only the function name parameter will change from call to call.

The arguments to `GR_report_error()` are exactly the same as those to `printf()`: a familiar printf-style format string followed by a variable number of arguments. There is no file pointer as in `fprintf()` because the errors may not be printed to a file or the screen but handled in some completely different way determined by the calling program. Repeated calls are a convenient way to build up the complete message just as with printing to the screen with `printf()`. Finally, a call to `GR_end_error()` ends the report. It requires no arguments.

The GRASP source code provides many examples of the use of these functions, and they are documented by example in Section 10.1. Because of the stereotyped calling sequence and arguments involved, an efficient technique for GRASP library programmers is to paste in the calls from another location in the source file or from a handy template kept in a scratch file so that only the function name and actual message needs editing for each case.

### 10.1.2 How GRASP Error Reports Are Handled

Programs vary widely in how they notify the user of errors. A simple command-line program will probably print the messages to the screen or a file, while a program with a graphical interface will likely send them to an error log window or to a dialog window. GRASP allows arbitrary error handlers to be specified, but the default provided will probably suffice for most GRASP application programmers.

Calling `GR_set_errors_enabled()` with an argument of false (zero) will suppress all GRASP error messages regardless of the actual handlers used, while a true argument will enable them again. `GR_errors_enabled()` returns true if errors are currently enabled and false otherwise. Errors always start out enabled unless the environment variable 'GRASP\_NODEBUG' exists (its value is irrelevant), in which case they are disabled by default. Errors may be disabled within a handler, but the change will not take place until the next `GR_start_error()` call.

By default, the default error handlers print errors to stderr. The function, file, and line number are reported in a standard header format, followed by the message itself printed as though each call to `GR_report_error(format,`

args) was a call to `fprintf(stderr, format, args)`, and ending with the RCS ID of the file containing the function source. If the environment variable 'GRASP\_ERRORFILE' exists and its value is the pathname of a file which can be opened for appending that filename is used instead of `stderr`. Finally, if in addition 'GRASP\_ERRORFILE\_OVERWRITE' exists (its value is irrelevant) the file is overwritten rather than appended to.

### 10.1.3 Customizing The Default Handlers

GRASP error reports may be customized by modifying the behavior of the default handler functions or by replacing them entirely. By default, when `GR_start_error()` is called it checks to see if there is a default file name set; if so, that file is opened for appending. If not (that is, if the filename has been set to `NULL`), or if the file cannot be opened, it then checks to see if an error `FILE*` has been set. If so, that file is used. If not, then the handler fails since it has no way to report the error. The default `GR_report_error()` prints to whatever file `GR_start_error()` chose to use, and `GR_end_error()` prints the RCS ID. If the file was opened by name in `GR_start_error()` then `GR_end_error()` also closes it.

The default `FILE*` can be set and examined with `GR_set_error_file()` and `GR_get_error_file()`, and the default filename can be set and examined with `GR_set_error_file_name()` and `GR_get_error_file_name()`. The default behavior can be restored with `GR_set_error_file(stderr)` and/or `GR_set_error_file_name(NULL)`. These functions may be called at any time except during an error report (between the calls to `GR_start_error()` and `GR_end_error()`), when an assert would fail. (This is a non-issue in practice because the file/filename could only be changed during a report if the file or filename is set in GRASP code itself, if the error reporting functions are called in user code as well as in GRASP, or if a custom handler changes the file/filename and then calls the default handler. The first possibility is strictly forbidden, and the others are discouraged because they can lead to confusion and subtle bugs.)

The reason for this somewhat complex system is safety. If a specified file name cannot be opened errors can still be reported to the `FILE*`, probably `stderr`. If an error file name has been set, the file is opened and closed for each report so that if the program crashes as much of the error log as possible is preserved on disk.

When using `GR_set_error_file()`, the calling program is responsible for opening the file for writing before the call and closing it (if necessary); GRASP will simply assume that the file is always available for output. A `NULL` file pointer is allowed, in which case calls to the default error handler will cause an assert to fail unless an error file name has been set.

When a file name is set with `GR_set_error_file_name()`, GRASP immediately attempts to open the file. If the `erasefile` parameter is `TRUE` (nonzero) the file will be opened for writing, if it is `false` (zero) it will be opened for appending. If the open succeeds, the name is copied and stored for future use (this means that the function can be safely called with locally allocated storage), an identifying start-up message and the time is written to the log file (even if error reporting is disabled), the file is closed, and the function returns `true`. When appending to a non-empty file it also writes a separator line so that reports from different runs are more easily distinguished. If the open fails, the filename is left unchanged (if a previous one existed), an error is reported in the usual way (unless error messages are suppressed), and the function returns `false`. Setting a `NULL` filename means that the `FILE*` should be used instead; the `erasefile` parameter is ignored in this case and the call always succeeds. As with `GR_set_error_file()`, the filename may not be changed during a report.

It is easy to see how the default behavior is obtained using these handlers. The default `FILE*` is `stderr`; conceptually a call to `GR_set_error_file(stderr)` occurs before the program begins. Similarly, a conceptual call to `GR_set_error_file_name(filename, erase)` occurs before program execution, with `filename` having the value of the environment variable `GRASP_ERRORFILE` if it exists and `NULL` otherwise, and `erase true` if the environment variable `GRASP_ERRORFILE_OVERWRITE` exists and `false` otherwise.

#### 10.1.4 Writing Custom Error Handlers

Internally, `GR_error` keeps three pointers of type `GR_start_error_type`, `GR_report_error_type`, and `GR_end_error_type` (defined in `grasp.h`) which point to the current `start_error`, `report_error`, and `end_error` handlers, respectively. When the three error handlers `GR_start_error()`, `GR_report_error()`, and `GR_end_error()` are called, they in turn check to see that they are called in the proper order and then call the function pointed to by the corresponding function pointer if (and only if) the function pointer is non-NULL (so that for convenience if a particular handler is not necessary a dummy routine is not required) and if errors are currently enabled (so disabling errors works regardless of the handler). By default the handler pointers simply reference `GR_default_start_error()`, `GR_default_report_error()`, and `GR_default_end_error()`, which actually implement the default behavior described above. For convenience they may be restored with `GR_restore_default_handlers()` as well as `GR_set_error_handlers()`.

The functions `GR_set_error_handlers()` and `GR_get_error_handlers()` set and examine the handler's current values, so that by writing the proper functions GRASP's error reports can be customized in any way desired. The `GR_..._error_type` typedef's in `grasp.h` illustrate the proper function prototypes. Note that `GR_report_error_type` functions take a `va_list` as their second argument rather than `'...'`; for convenience `GR_report_error()` creates the list and calls `va_start()` beforehand and calls `va_end()` afterwards so the handler need only deal with the list itself. In the common case where the message will simply be printed to a file, the `va_list` may be passed directly to one of the `v...printf` functions. The only restriction is that the handlers may not be changed between calls to `GR_start_error()` and `GR_end_error()`, but just as when changing the default error files this should not be a problem in practice.

The default handlers in `src/utility/GR_error.c` and their supporting routines are good examples of how GRASP error handlers are written. They are special only in that they are initialized and set automatically; otherwise, they use only features available to any handler. Most of their code provides the ability to switch files easily and safely; writing a custom handler that does not need this generality is quite straightforward. `GR_is_reporting()` returns true if a report is in progress and is sometimes useful when writing custom handlers.

### 10.1.5 Functions: GR\_start\_error(), GR\_report\_error(), GR\_end\_error()

These three functions are the GRASP error handlers. Their use is best illustrated by example. A typical usage is shown below – a fragment taken from a fictitious routine called “trouble()”.

```
...
GR_start_error("trouble()", rcsid, __FILE__, __LINE__);
GR_report_error("The GR_report_error() function is like printf().\n");
GR_report_error("It can have no arguments.\n");
GR_report_error("It can have a float argument %f\n", x1);
GR_report_error("Or any mixture of valid types %d %d %s\n", i1, i2, stringptr);
GR_end_error();
...
```

The use of these three routines as shown will print out, for example:

```
GRASP: Message from function trouble() at line number 123 of file "source.c".
The GR_report_error() function is like printf().
It can have no arguments.
It can have a float argument 5.43210
Or any mixture of valid types -2 17 the string pointed to by the pointer
$Id: man_utility.tex,v 1.20 1997/08/25 19:16:06 ballen Exp $
$Name: RELEASE_1_5_2 $
```

In particular, the line number, release number, and file name are all filled in automatically. The environment variables that govern the behavior of the default error handler are shown in Table 10 below.

Environment variable.	How to set, and effect obtained.
GRASP_NODEBUG	setenv GRASP_NODEBUG turns off error messages.
GRASP_ERRORFILE	setenv GRASP_ERRORFILE thisfile sends errors to file “thisfile”.
GRASP_ERRORFILE_OVERWRITE	setenv GRASP_ERRORFILE_OVERWRITE errors don’t accumulate in file.

Table 10: The behavior of the error handler is determined by three environment variables, which can be set and un-set using the shell commands `setenv` and `unsetenv`. These permit the error messages to be turned off, saved in a file, and control the file name and its over-write properties.

## 10.2 Function: `grasp_open()`

`FILE* grasp_open(const char *environment_variable, char *shortpath)`

This routine provides a simple mechanism for obtaining the pointer to a data or parameter file. It is called with two character strings. One of these is the name of an environment variable, for example `GRASP_DATAPATH` or `GRASP_PARAMETERS`. The second argument is the "tail end" of a path name. The routine then constructs a path name whose leading component is determined by the environment variable and whose tail end is determined by the short path name. `grasp_open()` opens the file (printing useful error messages if this is problematic) and returns a pointer to the file.

The arguments are:

`environment_variable`: Input. Pointer to a character string containing the name of the environment variable.

`shortpath`: Input. Pointer to a character string containing the remainder of the path to the file.

As a simple example, if the environment variable `GRASP_PARAMETERS` is set to `/usr/local/data/14nov94.2` and one calls `grasp_open("GRASP_PARAMETERS", "channel.0")`, then the routine opens the file `/usr/local/data/14nov94.2/channel.0` and returns a pointer to it.

### 10.3 Function: avg\_spec()

```
void avg_spec(float *data, float *average, int npoint, int *reset, float srate, float decaytime, int windowtype)
```

This routine calculates the power spectrum of the (time-domain) input stream `data[]`, averaged over time with a user-set exponential decay, and several possible choices of windowing.

The arguments are:

`data`: Input. The time domain input samples are contained in `data[0..N-1]`, with the data sample at time  $t = n\Delta t$  contained in `data[n]`.

`average`: Output. The one sided power spectrum is returned in `average[0..N-1]`. Note that *only after the second call* to `avg_spec()` will `average[]` be non-zero. The value of `average[m]` is the average power spectrum at frequency

$$f = \frac{m \times \text{srate}}{2 \times N}. \quad (10.3.1)$$

This is twice the number of distinct frequency values which appear in the FFT of  $N$  samples; this is because of the overlapping technique described below. We do not output the value of the average at the Nyquist frequency, which would be the (non-existent) array element `average[N]`. The units of `average[]` are  $\text{data}^2/\text{Hz}$ . Note: the elements of `average[]` must not be changed in between successive calls to `avg_spec()`.

`npoint`: Input. The number of points  $\text{npoint} = N$  input. This must be an integer power of two.

`reset`: Input. If set to zero, then any past contribution to the average power spectrum is initialized to zero, and a new average is begun with the current input data.

`srate`: Input. The sample rate  $1/\Delta t$  of the input data, in Hz.

`decaytime`: Input. The characteristic (positive) decay time  $\tau$  in seconds, to use for the moving (exponentially-decaying) average described below. If no averaging over time is wanted, simply set `decaytime` to be small compared to  $N\Delta t$ .

`windowtype`: Input. Sets the type of window used in power spectrum estimation. Rectangular windowing (i.e., no windowing) is `windowtype=0`, Hann windowing is `windowtype=1`, Welch windowing is `windowtype=2` and Bartlett windowing is `windowtype=3`. See [1] for a discussion of windowing and the definitions of these window types.

The methods used in this routine are quite similar to those used in the `overlap=1` version of the *Numerical Recipes* [1] routine `spctrm()`, and the reader interested in the details of this routine should first read the corresponding section of [1]. A continuous sample of the input data of twice the length of the array `data[]` is maintained by `avg_spec()`. Thus, each element of the array `data[]` is utilized twice; once with the first point `data[0]` right in the middle of the time-domain window function, and once more with that same point right at the beginning of the window function. Note that to reproduce (exactly) the procedure described in *Numerical Recipes* [1] one must have `npoint=M` where  $M$  is the variable used in the procedure `spctrm()`, and the decay time must be very large (so that the two successive spectra are equally weighted). For example, if you are doing analysis with 2048 samples, using that as the number of samples which you FFT and correlate, then you should make two calls to `avg_spec()`, in each of which `npoint=1024`; this will give you one spectral bin per FFT bin.

One frequently wants to do a moving-time average of power spectra, for example to see how the noise spectral properties of an interferometer are changing with time. This is accomplished in `avg_spec()` by averaging the spectrum with an exponentially-decaying average. Let  $A_t(f)$  denote the average power spectrum as a function of frequency  $f$ , at time  $t$ . Then the exponentially-decaying average  $\langle A(f) \rangle_t$  at time  $t$  is defined by

$$\langle A(f) \rangle_t = \frac{\int_{-\infty}^t dt' A_{t'}(f) e^{-(t-t')/\tau}}{\int_{-\infty}^t dt' e^{-(t-t')/\tau}}, \quad (10.3.2)$$

where  $\tau$  is the characteristic decay time over which an impulse in the power spectrum would decay. In our case, we wish to average the power spectra obtained in the  $n$ th pass through the averaging routine. The discrete analog of the previous equation (10.3.2) is

$$\langle A(f) \rangle_N = \frac{\sum_{n=0}^N A_n(f) e^{-\alpha(N-n)}}{\sum_{n=0}^N e^{-\alpha(N-n)}}. \quad (10.3.3)$$

Here,

$$\alpha = \frac{\text{npoint}}{\text{srate} \times \text{decaytime}} \quad (10.3.4)$$

is determined by the averaging time desired. The average defined by (10.3.3) can be easily determined by a recursion relation. We denote the the normalization factor by

$$\mathcal{N}_N = \sum_{n=0}^N e^{-\alpha(N-n)}. \quad (10.3.5)$$

It obeys the (stable) recursion relation  $\mathcal{N}_N = 1 + e^{-\alpha} \mathcal{N}_{N-1}$  together with the initial condition  $\mathcal{N}_{-1} = 0$ . The exponentially-decaying average then satisfies the (stable) recursion relation

$$\langle A(f) \rangle_N = e^{-\alpha} \frac{\mathcal{N}_{N-1}}{\mathcal{N}_N} \langle A(f) \rangle_{N-1} + \frac{A_N(f)}{\mathcal{N}_N} \quad \text{for } N = 0, 1, 2, \dots \quad (10.3.6)$$

(no initial condition is needed). The routine `avg_spec()` computes the exponentially decaying average by implementing these recursion relations for  $\langle A(f) \rangle_N$  and  $\mathcal{N}_N$ .

The units of the output array `average[ ]` are the square of the units of the input array `data[ ]` per Hz, i.e.

$$\text{units}(\text{average}[ ]) = (\text{units}(\text{data}[ ]))^2 / \text{Hz}. \quad (10.3.7)$$

The example program `calibrate` described earlier makes use of the routine `avg_spec()`.

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Comments: See comments for `calibrate`. *Warning:* Because `avg_spec()` uses an internal buffer to store a set of points twice as long as the input array `data[0..N-1]`, if you pass it sets of points that are not continuous, you will introduce discontinuous jumps between the data sets, and add lots of peculiar high-frequency garbage to the spectrum. You must feed this routine from a continuous data stream, and reset it in between breaks or gaps.

## 10.4 Function: binshort()

```
void binshort(short *input, int ninput, double *bins, int offset)
```

This function performs the “binning” which is needed to study the statistics of an array of short integers, such as the output of a 12 or 16 bit analog-to-digital converter. Its output is a histogram showing the number of times that a particular value occurred in an input array. Note that this routine *increments* the output histogram, so that you can use it for accumulating statistics of a particular variable.

The arguments are:

**input**: Input. This routine makes a histogram of the values `input[0..ninput-1]`.

**ninput**: Input. The number of elements in the previous array.

**bins**: Output. Upon return from the function, this array contains a histogram showing the probability distribution of the values `input[0..ninput-1]`. The array element `bins[offset]` is incremented by the number of elements  $x$  of `input[]` that had value  $x = 0$ . The array element `bins[offset+i]` is incremented by the number of elements  $x$  of `input[]` that had value  $x = i$ . If the output of your 16 bit ADC ranges from  $-32,768$  to  $+32,767$  and `nbins` has value  $2^{16} = 65,536$  then you would want `offset = 32,768`. For a 12-bit ADC you would probably want `nbins = 2^{12} = 4096`, and depending upon the sign conventions either `offset = 2047` or `offset = 2048`.

**offset**: Input. The offset defined above.

Note that in the interests of speed and efficiency this routine does *not* check that your values lie within range. So if you try to bin a value that lies outside of the range  $-\text{offset}, -\text{offset} + 1, \dots, \text{offset} - 1$  you may end up over-writing another array! You'll then spend unhappy hours trying to locate the source of bizzare unpredictable behavior in your code, when you could be doing better things, like seeing if your ADC has dynamic range problem (reaches the end-point values too often) or has a mean value of zero (even with AC-coupled inputs the ADC may have substantial DC offset).

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Comments: None.



## 10.5 Function: `is_gaussian()`

```
int is_gaussian(short *array, int n, int min, int max, int print)
```

This is a quick and robust test to see if a collection of values has a probability distribution that is consistent with a Gaussian normal distribution (“normal IFO operation”), or if the collection of values contains “outlier” points, indicating that the set of values contains “pulses”, “blips” and other “obvious” exceptional events that “stick out above the noise” (caused by bad cabling, alignment problems, or other short-lived transient events).

The arguments are:

`array`: Input. The values whose probability distribution is examined are `array[0..n-1]`.

`n`: Input. The length of the previous array.

`min`: Input. The minimum value that the input values *might* assume. For example, if `array[]` contains the output of a 12-bit analog-to-digital converter, one might set `min=-2048`. Of course the minimum value in the input array might be considerably larger than this (i.e., closer to zero!) as it should be if the ADC is being operated well within its dynamic range limits. If you’re not sure of the smallest value produced in `array[]`, set `min` smaller (i.e., more negative) than needed; the only cost is storage, not computing time.

`max`: Input. The maximum value that the input values *might* assume. For example, if `array[]` contains the output of a 12-bit analog-to-digital converter, one might set `max=2047`. The previous comments apply here as well: set `max` larger than needed, if you are not sure about the largest value contained in `array[]`.

`print`: Input. If this is non-zero, then the routine will print some statistical information about the distribution of the points.

The value returned by `is_gaussian()` is 1 if the distribution of points is consistent with a Gaussian normal distribution with no outliers, and 0 if the distribution contains outliers.

The way this is determined is as follows (we use  $x_i$  to denote the array element `array[i]`):

- First, the mean value  $\bar{x}$  of the distribution is determined using the standard estimator:

$$\bar{x} = \frac{1}{n} \sum_{i=0}^{n-1} x_i. \quad (10.5.1)$$

- Next, the points are binned into a histogram  $N[v]$ . Here  $N[v]$  is the number of points in the array that have value  $v$ . The sum over the entire histogram is the total number of points:  $\sum_i N[i] = n$ .
- Then the standard deviation  $s$  is estimated in the following robust way. It is the smallest integer  $s$  for which

$$\sum_{i=-s}^s N[i + \bar{x}] > n \operatorname{erf}(1/\sqrt{2}) = n \frac{1}{\sqrt{2\pi}} \int_{-1}^1 e^{-x^2/2} dx. \quad (10.5.2)$$

This value of  $s$  is a robust estimator of the standard deviation; the range of  $\pm s$  about the mean includes 68% of the samples. (Note that since the values of  $x_i$  are integers, we replace  $\bar{x}$  by the closest integer to it, in the previous equation).

- Next, the number of values in the range from one standard deviation to three standard deviations is found, and the number of values in the range from three to five standard deviations is found. This is compared to the expected number:

$$n(\operatorname{erfc}(3/\sqrt{2}) - \operatorname{erfc}(5/\sqrt{2})). \quad (10.5.3)$$

- If there are points more than five standard deviations away from the mean, or significantly more points in the 3 to 5 standard deviation range than would be expected for a Gaussian normal distribution, then `is_gaussian()` returns 0. If the numbers of points in each range is consistent with a Gaussian normal distribution, then `is_gaussian()` returns 1.

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Comments: This function should be generalized in the obvious way, to look at one sigma wide bins in a more systematic way. It can eventually be replaced by a more rigorously characterized test to see if the distribution of sample values is consistent with the normal IFO operation.

## 10.6 Function: clear()

```
void clear(float *array, int n, int spacing)
```

This routine clears (sets to zero) entries in an array.

The arguments are:

`array`: Output. This routine clears elements `array[0]`, `array[spacing]`, ..., `array[(n-1)*spacing]`.

`n`: Input. The number of array elements that are set to zero.

`spacing`: Input. The spacing in the array between successive elements that are set to zero.

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Comments: None.

## 10.7 Function: `product()`

`void product(float *c, float *a, float *b, int ncomplex)` This routine takes as input a pair of arrays  $a$  and  $b$  containing complex numbers. It multiplies  $a$  with  $b$ , placing the result in  $c$ , so that  $c = a \times b$ . The arguments are:

- a: Input. An array of  $N$  complex numbers  $a[0..2N-1]$  with  $a[2j]$  and  $a[2j+1]$  respectively containing the real and imaginary parts.
- b: Input. An array of  $N$  complex numbers  $b[0..2N-1]$  with  $b[2j]$  and  $b[2j+1]$  respectively containing the real and imaginary parts.
- c: Output. The array of  $N$  complex numbers  $c[0..2N-1]$  with  $c[2j]$  and  $c[2j+1]$  respectively containing the real and imaginary parts of  $a \times b$ .

`ncomplex`: Input. The number  $N$  of complex numbers in the arrays.

Note that the two input arrays  $a[ ]$  and  $b[ ]$  can be the same array; or the output array  $c[ ]$  can be the same as either or both of the inputs. For example, the following are all valid:

- `product(c, a, a, n)`, which performs the operation  $a^2 \rightarrow c$ .
- `product(a, a, b, n)`, which performs the operation  $a \times b \rightarrow a$ .
- `product(a, b, a, n)`, which performs the operation  $a \times b \rightarrow a$ .
- `product(a, a, a, n)`, which performs the operation  $a^2 \rightarrow a$ .

Note also that this routine does not allocate any memory itself - your input and output arrays must be allocated before calling `product()`.

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Comments: None.

## 10.8 Function: `productc()`

`void productc(float *c, float *a, float *b, int ncomplex)` This routine takes as input a pair of arrays  $a$  and  $b$  containing complex numbers. It multiplies  $a$  with the complex-conjugate of  $b$ , placing the result in  $c$ , so that  $c = a \times b^*$ . The arguments are:

a: Input. An array of  $N$  complex numbers  $a[0..2N-1]$  with  $a[2j]$  and  $a[2j+1]$  respectively containing the real and imaginary parts.

b: Input. An array of  $N$  complex numbers  $b[0..2N-1]$  with  $b[2j]$  and  $b[2j+1]$  respectively containing the real and imaginary parts.

c: Output. The array of  $N$  complex numbers  $c[0..2N-1]$  with  $c[2j]$  and  $c[2j+1]$  respectively containing the real and imaginary parts of  $a \times b^*$ .

`ncomplex`: Input. The number  $N$  of complex numbers in the arrays.

Note that the two input arrays  $a[ ]$  and  $b[ ]$  can be the same array; or the output array  $c[ ]$  can be the same as either or both of the inputs. For example, the following are all valid:

`productc(c, a, a, n)`, which performs the operation  $|a|^2 \rightarrow c$ .

`productc(a, a, b, n)`, which performs the operation  $a \times b^* \rightarrow a$ .

`productc(a, b, a, n)`, which performs the operation  $a^* \times b \rightarrow a$ .

`productc(a, a, a, n)`, which performs the operation  $|a|^2 \rightarrow a$ .

Note also that this routine does not allocate any memory itself - your input and output arrays must be allocated before calling `productc()`.

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Comments: None.

## 10.9 Function: ratio()

`void ratio(float *c, float *a, float *b, int ncomplex)` This routine takes as input a pair of arrays  $a$  and  $b$  containing complex numbers. It divides  $a$  by  $b$ , placing the result in  $c$ , so that  $c = a/b$ . The arguments are:

- a: Input. An array of  $N$  complex numbers  $a[0..2N-1]$  with  $a[2j]$  and  $a[2j+1]$  respectively containing the real and imaginary parts.
  - b: Input. An array of  $N$  complex numbers  $b[0..2N-1]$  with  $b[2j]$  and  $b[2j+1]$  respectively containing the real and imaginary parts.
  - c: Output. The array of  $N$  complex numbers  $c[0..2N-1]$  with  $c[2j]$  and  $c[2j+1]$  respectively containing the real and imaginary parts of  $a/b$ .
- `ncomplex`: Input. The number  $N$  of complex numbers in the arrays.

Note that the two input arrays  $a[ ]$  and  $b[ ]$  can be the same array; or the output array  $c[ ]$  can be the same as either or both of the inputs. For example, the following are all valid:

- `ratio(c, a, a, n)`, which (very inefficiently) sets every element of  $c$  to  $1 + 0i$ .
- `ratio(a, a, b, n)`, which performs the operation  $a/b \rightarrow a$ .
- `ratio(a, b, a, n)`, which performs the operation  $b/a \rightarrow a$ .
- `ratio(a, a, a, n)`, which (very inefficiently) sets every element of  $a$  to  $1 + 0i$ .

This routine is particularly useful when you want to reconstruct the raw interferometer output  $\widetilde{C}_0(f)$  that would have produced a particular interferometer displacement  $\widetilde{\Delta}l(f)$  (see for example `normalize_gw()` in Section 3.12). This occurs for example if you are “injecting” chirps into the raw interferometer output; they first need to be deconvolved with the response function of the instrument. One can invert this equation using `ratio()` since  $\widetilde{\Delta}l(f) = R(f)\widetilde{C}_0(f) \Rightarrow \widetilde{C}_0(f) = \widetilde{\Delta}l(f)/R(f)$ .

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Comments: None.

## 10.10 Function: graph()

```
void graph(float *array,int n,int spacing)
```

This is a useful function for debugging. It pops up a graph on the computer screen (using the graphing program `xmgr`) showing a graph of some array which you happen to want to look at.

The arguments are:

`array`: Input. The array that you want a graph of.

`n`: Input. The number of array elements that you want to graph.

`spacing`: Input. The spacing of the array elements that you want to graph. The elements graphed are `array[0]`, `array[spacing]`, `array[2*spacing]`, ..., `array[(n-1)*spacing]`.

This function is a handy way to get a quick look at the contents of some array. It writes the output to a temporary file and then starts up `xmgr`, reading the input from the file. The  $x$  values are evenly spaced integers from 0 to  $n-1$ . The  $y$  values are the (subset of) points in `array[ ]`. If your array contains real data, you might want to use `spacing=1`. If your array contains complex data (with real and imaginary parts interleaved) you will use `spacing=2`, and make separate calls to see the real and imaginary parts. For example if `complex[0..2047]` contains 1024 complex numbers, then:

```
graph(complex,1024,2) (view 1024 real values)
```

```
graph(complex+1,1024,2) (view 1024 imaginary values)
```

Note that in order not to produce too much garbage on the screen, any output or error messages from `xmgr` are tossed into `/dev/null!`

Authors: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: None.

## 10.11 Function: graph\_double()

```
void graph_double(double *array, int n, int spacing)
```

This is a useful function for debugging, and exactly like the function `graph()`, except that it's intended for double precision floating point numbers. It pops up a graph on the computer screen (using the graphing program `xmgr`) showing a graph of some array which you happen to want to look at.

The arguments are:

`array`: Input. The array that you want a graph of.

`n`: Input. The number of array elements that you want to graph.

`spacing`: Input. The spacing of the array elements that you want to graph. The elements graphed are `array[0]`, `array[spacing]`, `array[2*spacing]`, ..., `array[(n-1)*spacing]`.

This function is a handy way to get a quick look at the contents of some array. It writes the output to a temporary file and then starts up `xmgr`, reading the input from the file. The  $x$  values are evenly spaced integers from 0 to  $n-1$ . The  $y$  values are the (subset of) points in `array[ ]`. If your array contains real data, you might want to use `spacing=1`. If your array contains complex data (with real and imaginary parts interleaved) you will use `spacing=2`, and make separate calls to see the real and imaginary parts. For example if `complex[0..2047]` contains 1024 complex numbers, then:

```
graph(complex, 1024, 2) (view 1024 real values)
```

```
graph(complex+1, 1024, 2) (view 1024 imaginary values)
```

Note that in order not to produce too much garbage on the screen, any output or error messages from `xmgr` are tossed into `/dev/null!`

Authors: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: None.



## 10.12 Function: graph\_short()

```
void graph_short(short *array, int n)
```

This is a useful function for debugging, and exactly like the function `graph()`, except that it's intended for short integer values. It pops up a graph on the computer screen (using the graphing program `xmgr`) showing a graph of some array which you happen to want to look at.

The arguments are:

`array`: Input. The array that you want a graph of.

`n`: Input. The number of array elements that you want to graph. The elements graphed are `array[0..n-1]`.

This function is a handy way to get a quick look at the contents of some array. It writes the output to a temporary file and then starts up `xmgr`, reading the input from the file. The  $x$  values are evenly spaced integers from 0 to  $n-1$ . The  $y$  values are the points in `array[ ]`.

Note that in order not to produce too much garbage on the screen, any output or error messages from `xmgr` are tossed into `/dev/null!`

Authors: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: None.

### 10.13 Function: `sgraph()`

`sgraph(short *array, int n, char *name, int filenumber)`

This routine writes the elements of a short array into a file so that they may be viewed later with a graphing program like `xmgr`.

The arguments are:

`array`: Input. The array that you want to graph.

`n`: Input. The number of array elements that you want to graph. The elements used are `array[0..n-1]`.

`name`: Input. Used to construct the output file name.

`filenumber`: Input. The value of  $y$  used to construct the output file name.

This function produces an output file with two columns, containing:

0     `array[0]`

1     `array[1]`

...

`n-1`     `array[n-1]`

The name of this file is: `name.y` where  $y$  is the integer specified by `filenumber`. Note that if  $y < 1000$  then  $y$  is "expanded" or "padded" to three digits. For example, calling

`sgraph(array, 1024, "curious", 9)`

will produce the file

`curious.009`

containing 1024 lines.

Authors: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: None.

### 10.14 Function: `audio()`

```
void audio(short *array, int n)
```

Makes a Sun workstation play music!

The arguments are:

`array`: Input. The array that you want to hear.

`n`: Input. The number of array elements that you want to hear. The elements used are `array[0...n-1]`.

It doesn't take much experience before you find out that an interferometer can do funny things that you can't see in the data stream, if you just graph the numbers. However in many cases you can *hear* the peculiar events. This function works only on Sun workstations with a CD-sound quality chipset, that can handle 16 bit linear PCM audio. It creates a temporary file, then pipes it through the Sun utility `audioplay`. The sample rate is assumed to be 9600 Hz.

Note that `audio()` *adjusts the volume* so that the loudest event (largest absolute value) in the data stream has a (previously fixed, by us!) maximum amplitude. So the "background level" of the sound will depend upon the amplitude of the most obnoxious pings, blips, bumps, scrapes or howlers in the data set.

On a machine not equipped with the correct sound chip (for example a SparcStation 2) you can listen to the file, if you first convert it to a format that the chipset can handle. This can be done by taking the output of `audio()`, which is a file called `temp.au` and converting it to "voice" format. To do this, use the command:

```
audioconvert -f voice -o temp2.au temp.au
```

You can then listen to the sound using the command:

```
audioplay temp2.au
```

*Warning:* If you share your office with others, they will find the first few events that you listen to highly entertaining. After the first day however they will stop asking what you're listening to. After a few more days, their suggestions that you buy headphones will become more pointed. Respect this request.

Authors: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: This routine could be modified to permit a bit more freedom in setting the volume and/or the sample rate.

### 10.15 Function: `sound()`

`sound(short *array, int n, char *name, int filenumber)`

This is just like the function `audio()` except that it writes the sound data into a file of the form `*.au`.

The arguments are:

`array`: Input. The array that you want to hear.

`n`: Input. The number of array elements that you want to hear. The elements used are `array[0..n-1]`.

`name`: Input. Used to construct the output file name.

`filenumber`: Input. The value of `y` used to construct the output file name.

This function produces an output file with 16-bit PCM linear coding, containing sound data. The name of the file is: `name.y.au` where `y` is the integer specified by `filenumber`. Note that if `y < 1000` then `y` is "expanded" or "padded" to three digits. For example, calling

```
sound(array, 4800, "growl", 9)
```

will produce the file

```
growl.009.au
```

containing 1/2 second of sound.

Note: see the *Warning* that goes with `audio()`.

Authors: Bruce Allen, [ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)

Comments: This routine could be modified to permit a bit more freedom in setting the volume and/or the sample rate.

## 10.16 Example: translate

This example may be found in the `src/examples/examples_utility` directory of GRASP, and contains an example program which translates data from the "old 1994" Caltech 40-meter format described earlier, to the new LIGO/VIRGO frame format. Because this code provides an example of how the data is encoded in this new format, we have included the text of the translation code here. The frames produced by this translation contain about 5 seconds of data each, and are about half a megabyte in length. The number of frames in each data file is set by the

```
# define FRAMES_PER_FILE
```

at the top of the code. To run the utility, use the command

```
translate directory-name
```

where `directory-name` is the name of the directory in which the files `channel.0` to `channel.15` may be found. The FRAME format files produced by `translate` are labelled uniquely by the time at which the first data point in the first frame was taken (in Coordinated Universal Time). An example of such a file (produced by `translate`) is:

```
C1-94.10.15.06.18.02
```

where C1 denotes the Caltech 40-meter prototype. Suggested names for the other sites are H2 and H4 for the two Hanford LIGO detectors, L1 for the Livingston LIGO detector V1 for the Virgo detector, G1 for the GEO detector, T1 for the Tama detector, S1 for the Glasgow detector, M1 for the Max-Plank detector, and A1 for the AIGO detector. In the file name, 94 denotes the year (we will use 01 for 2001, etc.) and 10 denotes the month (labelled from 1 to 12). The hour ranges from 0 to 23 and in this examples is 06. The minutes (18) ranges from 0 to 59 and the seconds (02) ranges from 0 to 61 to include leap seconds but is normally in the range from 0 to 59. This naming convention will be used for any data files containing one second or more of data.

```
#include <math.h>
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "FrameL.h"
#include "grasp.h"
#define OLDNAMES 0 /* set to zero to use new channel names, 1 for old names */
#define LOCKLO 1
#define LOCKHI 10
#define CORRECTTIMESTAMPS 1 /* set to 1 to correct loss of timestamp resolution */

/* Each block of old-format data contains 5.07 secs of data. This
parameter determines how many of these old-format blocks (now a frame)
end up in each FRAME file. */
#define FRAMES_PER_FILE 32
/* earth's equatorial radius, in meters */
#define EQUATORIAL (6.37814e+06)
/* earth's ellipticity or flattening due to rotation */
#define FLAT (3.35281e-3)

/* the conversion from ADC counts to volts is: */
static char units[]="Units are 10 volts per 2048 counts. Range -2048 to +2047";

#if (OLDNAMES)
/* channel assignments before Nov 15, 1994 */
static char *prenov15[]={
    "IFO output", "", "", "microphone", "dc strain", "mode cleaner pzt",
    "seismometer", "", "", "", "TTL locked", "arm 1 visibility", "arm 2 visibility",
```

```

        "mode cleaner visibility", "slow pzt", "arm 1 coil driver"};

/* channel assignments after Nov 15, 1994 */
static char *postnov15[]={
    "IFO output", "magnetometer", "microphone", "", "dc strain", "mode cleaner pzt",
    "seismometer", "slow pzt", "power stabilizer", "",
    "TTL locked", "arm 1 visibility", "arm 2 visibility", "mode cleaner visibility",
    "", "arm 1 coil driver"};
#else
/* channel assignments before Nov 15, 1994 */
static char *prenov15[]={
    "IFO_DMRO", "", "", "IFO_Mike", "IFO_DCDM", "PSL_MC_V",
    "IFO_Seis_1", "", "", "", "IFO_Lock", "IFO_EAT", "IFO_SAT",
    "IFO_MCR", "IFO_SPZT", "SUS_EE_Coil_V"};

/* channel assignments after Nov 15, 1994 */
static char *postnov15[]={
    "IFO_DMRO", "IFO_Mag_x", "IFO_Mike", "", "IFO_DCDM", "PSL_MC_V",
    "IFO_Seis_1", "IFO_SPZT", "PSL_PSS", "",
    "IFO_Lock", "IFO_EAT", "IFO_SAT", "IFO_MCR",
    "", "SUS_EE_Coil_V"};
#endif

/* Program's only argument is the name of the directory containing old-format data */
int main(int argc, char* argv[]) {
    char filename[256], name[256], hist[1024], *histnew, *buff, **chan_name;
    int i, code=1, num, large=50000, small=5000, n, first=1, firsttime, nlines;
    long buffSize;
    float fastrate=9868.4208984375, tblock, slowrate=986.84208984375, *real, *imag, *freq, theta;
    double firstmsec, first_estimate, second_estimate, diff, dt, dtslow;
    float starttime=-100.0, guesstime;
    double currenttime=-200;
    int blockcount=0, channelsopen=0, expected;
    struct FrFile *outputfile;
    struct FrameH *frame;
    struct FrAdcData *adc[16];
    struct FrDetector *frdetect;
    struct FrVect *framevec;
    struct FrVect *framevecS;
    struct FrStatData *staticdata;
    struct FrStatData *staticdataS;
    struct ld_binheader bin_header;
    struct ld_mainheader main_header;
    struct tm timetm, *gtime, gts;
    time_t caltime, translate_time;
    FILE *fp[16], *fpsweptsine;
    void unhappyexit(int i);
    int get_run_number(int firsttime);

    /* initialize the frame system */
    FrLibIni(NULL, NULL, 2);
    buffSize=1000000;
    buff=malloc(buffSize);

    /* create a frame */
    frame=FrameHNew("C1");

    /* assign detector structure: site location and orientation information */
    frame->detectRec=FrDetectorNew("real");

```

```

frdetect=frame->detectRec;
frdetect->latitude=34.1667;
frdetect->longitude=118.133;
frdetect->arm1Angle=180.0;
frdetect->arm2Angle=270.0;
frdetect->arm1Length=38.5;
frdetect->arm2Length=38.1;

/* Correct for oblateness of earth, use reference spheroid with
flattening FLAT; EQUATORIAL is earth equatorial radius in meters.
Reference: eqns (4.13-14) in "Spacecraft attitude determination and
control", Ed. James R. Wertz, D. Reidel Publishing Co., Boston, 1985.
Note: this SHOULD be corrected to add in the height of Caltech above
sea level. */
/* angle measured down from the North pole */
theta=(M_PI/180.0)*(90.0-frdetect->latitude);
frdetect->altitude=EQUATORIAL*(1.0-FLAT*cos(theta)*cos(theta));

/* now open files containing 40 meter data */
if (!argv[1] || argc!=2) unhappyexit(1);

/* step through all possible channels, seeing which channels have data */
for (i=0;i<16;i++) {
    sprintf(name,"%s/channel.%d",argv[1],i);
    fp[i]=fopen(name,"r");
    if (fp[i]==NULL)
        fprintf(stderr,"File %s unavailable. Skipping it...\n",name);
    else
        channelsopen++;
}

/* if there are no open files, then please exit with a warning message */
if (channelsopen==0) unhappyexit(1);

/* the sample times for the fast/slow channels */
dt=1.0/fastrate;
dtslow=1.0/slowrate;

/* Define 4 fast, 12 slow ADC channels (long strings of blanks needed - see below) */
for (i=0;i<16;i++)
    if (fp[i]!=NULL)
        if (i<4)
            /* sample rates differ from fastrate, slowrate - see GRASP manual for details */
            adc[i]=FrAdcDataNew(frame,"",50000.0*15.0/76.0,large,16);
        else
            adc[i]=FrAdcDataNew(frame,"",5000.0*15.0/76.0,small,16);

/* now loop over the input data, creating blocks of output data */
while (code>0) {
    /* read a block of data */
    for (i=0;i<16;i++) {
        /* set size of data block */
        n=(i<4)?large:small;
        /* read data into frame short array */
        if (i<4 && fp[i]!=NULL)
            code=read_block(fp[i],&(adc[i]->data->dataS),&num,&tblock,&fastrate,0,&n,0,
                &bin_header,&main_header);
        else if (fp[i]!=NULL)
            code=read_block(fp[i],&(adc[i]->data->dataS),&num,&tblock,&slowrate,0,&n,0,

```

```

                                &bin_header, &main_header);
}

/* if no data remains, we have found an error */
if (code==0) {
    fprintf(stderr, "Error in translation: unexpected end of data!\n");
    abort();
}

/* check the various sample times */
if (dt!=1.0/fastrate) fprintf(stderr, "Fast sample rates don't match!\n");
if (dtslow!=1.0/slowrate) fprintf(stderr, "Slow sample rates don't match!\n");

/* set time stamps for this block of data */
/* create structure to store localtime of tape */
timetm.tm_sec=main_header.tod_second;
timetm.tm_min=main_header.tod_minute;
timetm.tm_hour=main_header.tod_hour;
timetm.tm_mday=main_header.date_day;
timetm.tm_mon=main_header.date_month;
timetm.tm_year=main_header.date_year;
timetm.tm_wday=main_header.date_dow;
timetm.tm_yday=-1; /* info not available, but filled in by mktime */
timetm.tm_isdst=-1; /* info not available, but filled in by mktime */
caltime=mktime(&timetm);
gtime=gmtime(&caltime);
gts=*gtime;

if (caltime!=main_header.epoch_time_sec) {
    fprintf(stderr, "I am confused about the correct time: %d or %d\n",
            (int)caltime, main_header.epoch_time_sec);
    fprintf(stderr, "If not running on a PST time-zone machine, ignore error!\n");
}

/* set the time stamp for the first data sample (more precise than header time) */
if (first) {
    firsttime=main_header.epoch_time_sec;
    firstmsec=0.001*main_header.epoch_time_msec;
    printf("Local start time: %s\n", ctime(&caltime));
    printf("UTC start time:  %s", asctime(&gts));

    /* assign the run number from 1,..,11 to the frame. */
    frame->run=get_run_number(firsttime);
    if (frame->run<1 || frame->run>11) unhappyexit(2);

    /* assign proper name to adc channel (to overwrite long blank space above) */
    if (frame->run<=2) {
        chan_name=prenov15;
        expected=11;
    }
    else {
        chan_name=postnov15;
        expected=13;
    }

    if (channelsopen!=expected) {
        fprintf(stderr, "Only found %d channels. Expected %d\n", channelsopen, expected);
        exit(1);
    }
}

```



```

for (i=0;i<16;i++)
  if (fp[i]!=NULL) {
    /* verify that name is correct */
    if (strcmp(chan_name[i],"")==0) {
      fprintf(stderr,"Channel %d is not recognized and has no name!\n",i);
      exit(1);
    }

    /* point to the correct channel name for this particular date, channel */
    strcpy(adc[i]->name,chan_name[i]);

    /* put in the physical volts/counts conversion */
    adc[i]->data->unit[0]=(char *)malloc((strlen(units)+1)*sizeof(char));
    strcpy(adc[i]->data->unit[0],units);

    /* which ADC "crate" was this */
    adc[i]->crate=i;
  }
}

if (CORRECTTIMESTAMPS) {
  guesstime=currenttime+76.0/15.0;
  if (fabs(guesstime-tblock)>1.0) {
    starttime=tblock;
    blockcount=0;
  }
  currenttime=(blockcount++)*((double)76.0/15.0)+starttime;

  /* put the time stamp into the frame structure */
  currenttime+=firstmsec;
  frame->UTimeS=firsttime+(int)currenttime;
  frame->UTimeN=(int)(1.e9*(currenttime-(int)currenttime));
  frame->dt=76.0/15.0;
}
else {
  /* put the time stamp into the frame structure */
  tblock+=firstmsec;
  frame->UTimeS=firsttime+(int)tblock;
  frame->UTimeN=(int)(1.e9*(tblock-(int)tblock));
  frame->dt=num/slowrate;
}

/* Localtime - UTC time in seconds */
frame->localTime=-9*3600;

/* frame->type[0]=0; */

/* put in the history information (only once per translation) */
if (first) {
  first=0;
  histnew=hist;
  time(&translate_time);
  histnew+=sprintf(histnew, "\nTranslation carried out by:\n");
  histnew+=sprintf(histnew, "    login: %s\n",getenv("LOGNAME"));
  histnew+=sprintf(histnew, "    user: %s\n",getenv("USER"));
  histnew+=sprintf(histnew, "    directory: %s\n",getenv("PWD"));
  histnew+=sprintf(histnew, "    datapath: %s\n",argv[1]);
  histnew+=sprintf(histnew, "    translation program name: %s\n",argv[0]);
}

```

```

histnew+=sprintf(histnew, "      source code name: %s\n", "translate.c");
histnew+=sprintf(histnew, "      translation date: %s\n", ctime(&translate_time));
FrHistoryAdd(frame, hist);

/* read the swept sine calibration files (only once per run) */
sprintf(name, "%s/swept-sine.ascii", argv[1]);
fpsweptsine=fopen(name, "r");
read_sweptsine(fpsweptsine, &nlines, &freq, &real, &imag);

/* copy swept sine calibration data into vector; see below for packing style */
framevec=FrVectNew(FR_VECT_F, 1, 3*nlines, 1.0, "Vifo/Vcoil");
for (i=0; i<nlines; i++) {
    framevec->dataF[i]=freq[i];
    framevec->dataF[i+nlines]=real[i];
    framevec->dataF[i+2*nlines]=imag[i];
}

/* then link the calibration data into the history structure */
staticdata=FrStatDataNew("sweptsine",
    "swept sine calibration:\npacking: freq[i], real[i], imaginary[i]",
    frame->UTimeS, MAXINT, 1, framevec);
FrStatDataAdd(&frame->detectRec->sData, staticdata);

/* put in lock range (INCLUSIVE low->high) Rolf: if 0=unlock and 1=lock
then you need LOCKLO=LOCKHI=1
*/
framevecS=FrVectNew(FR_VECT_S, 1, 2, 1.0, "adcCounts");
framevecS->dataS[0]=LOCKLO; /* smallest value at which we are still in lock */
framevecS->dataS[1]=LOCKHI; /* largest value at which we are still in lock */

/* then link the lockrange data into the history structure */
staticdataS=FrStatDataNew("locklo/lockhi",
    "lock range:\npacking: array[0]=locklo array[1]=lockhi",
    frame->UTimeS, MAXINT, 1, framevecS);
FrStatDataAdd(&frame->detectRec->sData, staticdataS);
}

/* is the time stamp for this data block consistent with start time+offset? */
first_estimate=frame->UTimeS+1.e-9*frame->UTimeN;
second_estimate=main_header.epoch_time_sec+1.e-3*main_header.epoch_time_msec;
diff=first_estimate-second_estimate;
if (fabs(diff)>0.002)
    fprintf(stderr, "Time stamps have drifted by %f msec!\n", diff);

/* Increment frame counter (set to 1 for first frame of each run) */
frame->frame++;

/* Open Frame file (one file per FRAMES_PER_FILE frames) */
if ((frame->frame%FRAMES_PER_FILE)==1) {
    /* set file name. Note that month=1 to 12 not 0 to 11! */
    sprintf(filename, "C1-%02d_%02d_%02d_%02d_%02d_%02d", gts.tm_year, gts.tm_mon+1,
        gts.tm_mday, gts.tm_hour, gts.tm_min, gts.tm_sec);
    printf("Filename: %s\n", filename);
    outputfile=FrFileONew(filename, NO, buff, buffSize);
}

/* un-comment to print a short snippet of each Frame onto the screen */
/* FrameDump(frame, stdout, 2); */

```

```

    /* Write frame to file, */
    FrameWrite(frame, outputfile);

    /* Close file if finished with FRAMES_PER_FILE or no remaining data */
    if ((frame->frame%FRAMES_PER_FILE)==0 || code==-1)
        FrFileOEnd(outputfile);
}

/* Free frame memory and return */
FrameFree(frame);
return(0);
}

/* this routine is called if something is wrong */
void unhappyexit(int i) {
switch (i) {
case 1:
    fprintf(stderr,
        "Syntax: \ntranslate directory\nwhere channel.* files may be found in directory\n");
    exit(1);
case 2:
    fprintf(stderr,
        "The UTC does not appear to lie in the range of any data set!\n");
    exit(1);
default:
    abort();
}
return;
}

/* number of secs after Jan 1 1970 UTC at which Nov 1994 runs began */
static int stimes[]={784880277,784894763,785217574,785233119,785250938,785271063,
                    785288073,785315747,785333880,785351969,785368428,785388248};

/* This routine looks at the epoch time (sec) and returns the run number (1-11) */
int get_run_number(int firsttime) {
    int i;

    for (i=0;i<12;i++)
        if (firsttime<stimes[i]) break;

    return i;
}

```

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Comments: The technique used to time-stamp this data is an attempt to correct the poor resolution of the original data – please see the remarks in 4.1 for additional detail. Also notice that because the sample rates of the slow/fast channels differ by a ratio of 10, we can not easily reformat the frames with sample sizes of length  $2^n$ . We expect that the FRAME format will continue to evolve, so that this translator (and the FRAME format data) may require periodic updates. Should the year have four digits (eg, 1994) for easier sorting?

## 10.17 Multi-taper methods for spectral analysis

Since the early 1980's there has been a revolution in the spectral analysis, due largely to a seminal paper by Thomson [24]. There is now a standard textbook on the subject, by Percival and Walden [25], to which we will frequently refer.

Among the most useful of these techniques are the so-called "multitaper" methods. These make use of a special set of windowing functions, called Slepian tapers. For discretely-sampled data sets, these are discrete prolate spheroidal sequences, and are related to prolate spheroidal functions. The GRASP package contains (a modified version of) a public domain package by Lees and Park, which is described in [26]. Further details of this package may be found at <http://love.geology.yale.edu/mtm/>. Note however that we have already included this package in GRASP; there is no need to hunt it down yourself.

For those who are unfamiliar with these techniques, we suggest reading Chapter 7 of [25]. The sets of tapered windows are defined by three parameters. These are, in the notation of Percival and Walden:

*N*: The length of the discretely-sampled data-set, typically denoted by the integer `npoints` in the GRASP routines.

*NWΔt*: The product of total observation time  $N\Delta t$  and the resolution bandwidth  $W$ . This dimensionless (non-integer) quantity is denoted `nwdt` in the GRASP routines. Note that for a conventional FFT, the frequency resolution would be  $W = \Delta f = 1/N\Delta t$ . This corresponds to having  $NW\Delta t = 1$ . The multitaper techniques are typically used with values of  $W$  which are several times larger, for example  $W = 3\Delta f$ , which corresponds to  $NW\Delta t = 3$ .

*K*: The number of Slepian tapers (or window functions) used, typically denoted `nwin` in the GRASP routines. Note that it is highly recommended (see page 334 of [25] and the final two figures on page 339) that the number of tapers  $K < 2NW\Delta t$ .

In addition to providing better spectral estimation tools, the multi-taper methods also provide nice techniques for spectral line parameter estimation and removal. When the sets of harmonic coefficients are generated for different choices of windows, one can perform a regression test to determine if the signal contains a sinusoid of fixed amplitude and phase, consistent across the complete set of tapers. The GRASP package uses this technique (the F-test described on page 499, and the worked-out example starting on page 504 of [25]) to estimate and remove spectral lines from a data-set. This can be used both for diagnostic purposes (i.e., track contamination of the data set by the 5th line harmonic at 300Hz) or to "clean up" the data (i.e., remove the pendulum resonance at 590 Hz).

As an aid in understanding these techniques, we have included with GRASP a section of the data-set from the Willamette River appearing on pg 505 of Percival and Walden [25], and an example program which repeats and reproduces the results in Section 10.13 of that textbook. This demonstrates the use of multi-taper methods in removing "spectral lines" from a data set.

## 10.18 Function: slepian\_tapers()

```
int slepian_tapers(int num_points, int nwin, double *lam, float nwdt, double
*tapers, double *tapsum)
```

This function computes and returns properly-normalized Slepian tapers. These tapers are normalized so that

$$\sum_{t=1}^N h_t^2 = N, \quad (10.18.1)$$

which is the *Numerical Recipes* convention for tapers (rather than the Percival and Walden convention for which the rhs is 1). It uses the method described in Percival and Walden [25] pages 386-387, finding the eigenvectors and eigenvalues of a tri-diagonal matrix. The arguments are:

`num_points`: Input. The number of points  $N$  in the taper.

`nwin`: Input. The number of tapers computed.

`lam`: Output. Upon return, `lam[0..nwin-1]` contains the eigenvalues  $\lambda$  of the tapers. Note that  $0 < \lambda < 1$ .

`nwdt`: Input. The (total sample time)  $\times$  (frequency resolution bandwidth) product.

`tapers`: Output. Upon return: `tapers[0..num_points-1]` contains the first taper, `tapers[num_points..2*num_points-1]` contains the second taper, and so on.

`tapsum`: Output. On return `tapsum[0]` contains the sum of the `num_points` values of the first taper, `tapsum[1]` contains the sum of the values of the second taper, and so on. Note that because the odd-index Slepian taper functions are odd, `tapsum[1, 3, 5, ...]` would vanish if it were not for round-off and other numerical error.

This function will print a warning message if the condition  $K < 2NW\Delta t$  is not satisfied (see Section 10.17).  
Author: Adapted from the original code (Lees and Park) by Bruce Allen (ballen@dirac.phys.uwm.edu) and Adrian Ottewill (ottewill@relativity.ucd.ie).

Comments: There are a number of techniques for calculating the Slepian tapers. We have not extensively tested these routines, but they appear to work well. They make use of the standard EISPACK routines, translated from FORTRAN into C using f2c.

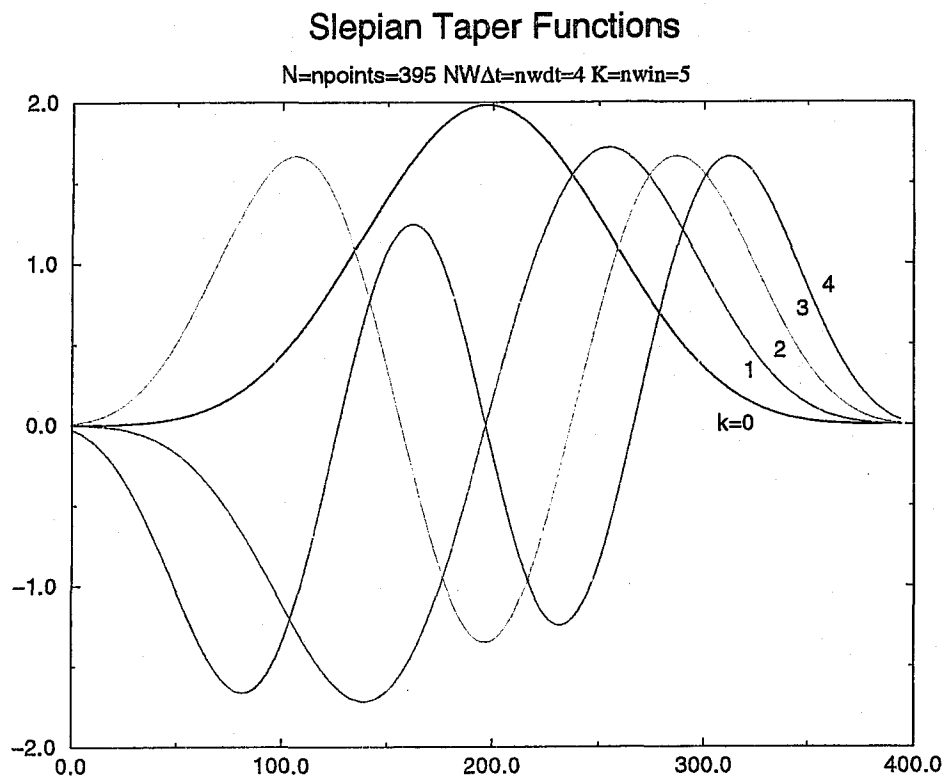


Figure 55: Here are five Slepian tapers computed with `slepian_tapers()`. The parameters are `npoints=395`, `nwdt=4.0` and `nwin=5`.

### 10.19 Function: multitaper\_spectrum()

multitaper\_spectrum(float \*data, int npoints, int kind, int nwin, float nwdt, int inorm, float dt, float \*ospec, float \*dof, float \*fvalues, int klen, float \*cest, int dospec)

This function computes the multi-taper spectrum, as defined for example by Percival and Walden [25] equation (333). For the sake of efficiency, it computes then stores internally the Slepian taper functions, so that if it is called a second time (and needs the same tapers) they do not need to be re-computed. If called with different parameters it recomputes the Slepian tapers for the new parameters.

The arguments are:

**data:** Input. Pointer to the time-domain data array, data[0..npoints-1].

**npoints:** Input. Number of data points in the data array.

**kind:** Input. If set to 1, compute the normal multi-taper spectrum. If set to 2, compute the "adaptive" spectrum defined by Percival and Walden equation (370a).

**nwin:** Input. The number of tapers to use.

**nwdt:** Input. The (total sample time)  $\times$  (frequency resolution bandwidth) product.

**inorm:** Input. Determines choice of normalization. Possible values are

- 1: Divide spectrum by  $N^2$ .
- 2: Divide spectrum by  $\Delta t^2$ .
- 3: Divide spectrum by  $N$ .
- 4: Divide spectrum by 1.

**dt:** Input. Sample interval (only used for normalization).

**ospec:** Output. The output spectrum, including both DC and Nyquist frequency bins. The array range is ospec[0..klen/2]. Warning -this is an *odd* number of entries. The user must provide a pointer to sufficient storage space.

**dof:** Output. The effective number of degrees of freedom of the spectral estimator at a given frequency, defined by Percival and Walden eqn (370b). The number of degrees of freedom is the constant nwin-1 for kind=1 above, and only useful in the adaptive case where kind=2. The array range is dof[0..klen/2]. Warning - this is an *odd* number of entries. The user must provide a pointer to sufficient storage space.

**fvalues:** Output. The value of the F-statistic in each frequency bin spectrum, including both DC and Nyquist. This is defined by Percival and Walden equation (499c), and roughly speaking is the ratio of the energy explained by the hypothesis that one has a fixed-amplitude spectral line at that frequency to the energy not explained by this hypothesis. The array range is fvalues[0..klen/2]. Warning -this is an *odd* number of entries. The user must provide a pointer to sufficient storage space.

**klen:** Input. An integer power of 2, greater than (or equal to) npoints. The (tapered) data is zero-padded out to this length. You generally want klen to be around four to eight times larger than the length of your data set, to get decent frequency resolution. The number of frequency bins (including DC and Nyquist) in the output spectrum is  $N_f = 1 + \text{klen}/2$ .

`cest`: Output. The estimated Fourier coefficients of any spectral lines in the data. The real and imaginary parts at DC are contained in `cest[0]`, `cest[1]`. The next higher frequency bin has its real/imaginary parts contained in `cest[2]`, `cest[3]`, and so on. This pattern continues up to and including the Nyquist frequency. The length of the array is `cest[0..klen+1]`. The normalization/sign conventions are identical to Percival and Walden eqns (499a) and the example on line 20 of page 513, except that the sign of the imaginary part is reversed, because the Percival and Walden FFT conventions eqn (65ab) are opposite to Numerical Recipes. The user must provide a pointer to sufficient storage space.

`dospec`: Input. If set non-zero, then the power spectrum (pointed to by `ospec`) is calculated. If set to zero, then to save time in situations where all that is needed is `cest`, the power spectrum `ospec` is *not* calculated.

Author: Adapted from the original code (Lees and Park) by Bruce Allen ([ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)) and Adrian Ottewill ([ottewill@relativity.ucd.ie](mailto:ottewill@relativity.ucd.ie)).

Comments: None.



## 10.20 Function: multitaper\_cross\_spectrum()

```
void multitaper_cross_spectrum(float *o1, float *o2, int npoints, int npadded,
float delta_t, int nwin, float nwdt, double *ReImSpec12)
```

This function calculates the high resolution multitaper spectral estimate of the (complex-valued) cross-correlation spectrum  $\bar{o}_1^*(f)\bar{o}_2(f)$  of the two input time-series  $o_1(t)$  and  $o_2(t)$ .

The arguments are:

**o1:** Input. `o1[0..npoints-1]` is an array of floating point variables containing the values of the input time-series  $o_1(t)$ . `o1[i]` contains the value of  $o_1(t)$  evaluated at the discrete time  $t_i := i\Delta t$ , where  $i = 0, 1, \dots, N - 1$ .

**o2:** Input. `o2[0..npoints-1]` is an array of floating point variables containing the values of the input time-series  $o_2(t)$ , in exactly the same format as the previous argument.

**npoints:** Input. The total number  $N$  of data points contained in the two input time-series.

**npadded:** Input. The padded length  $N_p$  is an integer power of 2, greater than (or equal to) the total number of data points. The tapered data sets are zero-padded out to this length. The total number of frequency bins (including DC and Nyquist) in the output cross-correlation spectrum is  $N_f = 1 + N_p/2$ .

**delta\_t:** Input. The sampling period  $\Delta t$  (in sec).

**nwin:** Input. The total number  $K$  of data tapers used when forming the multitaper spectral estimate.

**nwdt:** Input. The (total sample time)  $\times$  (frequency resolution bandwidth) product  $N\Delta t \cdot W$ .

**ReImSpec12:** Output. `ReImSpec12[0..npadded+1]` is an array of double precision variables containing the values of the high resolution multitaper spectral estimate of the (complex-valued) cross-correlation spectrum  $\bar{o}_1^*(f)\bar{o}_2(f)$ . `ReImSpec12[2*i]` and `ReImSpec12[2*i+1]` contain, respectively, the values of the real and imaginary parts of

$$\frac{1}{K} \sum_{k=0}^{K-1} \frac{1}{\lambda_k} \left( \Delta t \sum_{m=0}^{N-1} o_1(t_m) w_{k,m} e^{-i2\pi m j / N_p} \right) \left( \Delta t \sum_{n=0}^{N-1} o_2(t_n) w_{k,n} e^{+i2\pi n j / N_p} \right) \quad (10.20.1)$$

where  $w_{k,n}$  is the  $n$ th element of the  $k$ th order  $NW\Delta t$  discrete prolate spheroidal sequence data taper, and  $\lambda_k$  is its associated eigenvalue. (Here  $i = 0, 1, \dots, N_f - 1 = N_p/2$ .) The data tapers are normalized so that  $\sum_{n=0}^{N-1} w_{k,n}^2 = N$ . This differs from the normalization convention of Percival and Walden [25], where  $\sum_{n=0}^{N-1} w_{k,n}^2 = 1$ . Also, Equation (333) in [25] does not include the factors of  $1/\lambda_k$ . But for  $K < 2NW\Delta t$ , it follows that  $1/\lambda_k \approx 1$ .

If you want to obtain the same normalization as that used in the `avg_spec()` routine described by equation (10.3.7) for the case where  $o_1(t) = o_2(t)$  then the output array `ReImSpec12` must be multiplied by a factor of  $\frac{2}{N\Delta t}$ .

Author:

Adapted from the original code (Lees and Park) by Bruce Allen (ballen@dirac.phys.uwm.edu), Adrian Ottewill (ottewill@relativity.ucd.ie), and Joseph Romano (romano@csd.uwm.edu).

Comments: None.

## 10.21 Structure: struct removed\_lines

This is a structure used to keep track of spectral lines as they are removed. Its primary use is in the function `remove_spectral_lines()`. The structure contains the following:

```
struct removed_lines{
    int index;
    float fvalue;
    float re;
    float im;
};
```

The different quantities are:

**index:** The subscript (frequency bin) occupied by the spectral line in an array of length  $N_f$  (defined in the previous section). Note that in typical use index runs over a range of  $2^n + 1$  possible values, including DC and Nyquist.

**fvalue** The value of the F-statistic, defined by Percival and Walden eqn. (499c).

**re:** The real part of the line's complex amplitude. The normalization/sign conventions are identical to Percival and Walden eqns (499a) and the example on line 20 of page 513.

**im:** The imaginary part of the line's complex amplitude. The normalization conventions are identical to Percival and Walden eqns (499a) and the example on line 20 of page 513, but the sign is reversed, because the Percival and Walden FFT conventions eqn (65ab) are opposite to Numerical Recipes.

## 10.22 Function: `fvalue_cmp()`

```
int fvalue_cmp(const void *f1, const void *f2)
```

This is a function which may be used to compare the `fvalue`s of two different objects of type `struct removed_lines`. It is used for example as an argument to the standard-C library routine `qsort` for sorting lists of removed lines into decreasing order of `fvalue`.

This function is supplied with pointers to two structures. It returns -1 if the first structure has the larger `fvalue`, +1 if the first structure has the smaller `fvalue`, and 0 if the `fvalues` are equal.

The arguments are:

`f1`: Input. Pointer to the first structure of type `struct removed_lines` (cast to `void *` so that your compiler does not complain).

`f2`: Input. Pointer to the second structure of type `struct removed_lines` (cast to `void *` so that your compiler does not complain).

As an example, if `line_list[0..n-1]` is an array of `struct removed_lines`, then the function call:

```
qsort(line_list, n, sizeof(struct significant_values), fvalue_cmp)
```

will sort that array into decreasing `fvalue` order. (Note: you may have to cast the arguments to prevent your compiler from complaining.)

Author: Bruce Allen ([ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)) and Adrian Ottewill ([ottewill@relativity.ucd.ie](mailto:ottewill@relativity.ucd.ie)).

Comments: None.

### 10.23 Function: `index_cmp()`

```
int index_cmp(const void *f1, const void *f2)
```

This is a function which may be used to compare the indexes of two different objects of type `struct removed_lines`. It is used for example as an argument to the standard-C library routine `qsort` for sorting lists of removed lines into increasing order in frequency.

This function is supplied with pointers to two structures. It returns -1 if the first structure has the smaller index, +1 if the first structure has the larger index, and 0 if the indexes are equal.

The arguments are:

`f1`: Input. Pointer to the first structure of type `struct removed_lines` (cast to `void *` so that your compiler does not complain).

`f2`: Input. Pointer to the second structure of type `struct removed_lines` (cast to `void *` so that your compiler does not complain).

As an example, if `line_list[0..n-1]` is an array of `struct removed_lines`, then the function call:

```
qsort(line_list, n, sizeof(struct significant_values), index_cmp)
```

will sort that array into increasing index (frequency!) order. (Note: you may have to cast the arguments to prevent your compiler from complaining.)

Author: Bruce Allen ([ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)) and Adrian Ottewill ([ottewill@relativity.ucd.ie](mailto:ottewill@relativity.ucd.ie)).

Comments: None.

## 10.24 Function: `remove_spectral_lines()`

```
void remove_spectral_lines(float *data, int npoints, int padded_length, float
nwdt, int nwin, int max_lines, int maxpass, int *num_removed, struct removed_lines
*line_list,
float *mtap_spec_init, float *mtap_spec_final, int dospecs, int fimin, int
fimax)
```

This routine automatically identifies and removes “spectral lines” from a time series. The procedure followed is described in Percival and Walden Chapter 10. A worked example may be found in Section 10.13 of that book, and the next subsection of the GRASP manual includes two example programs which use `remove_spectral_lines()`. Upon return, `remove_spectral_lines()` provides both an “initial” multi-taper spectrum, of the original data, and a “final” multi-taper spectrum, after line removal. Upon return, the data set has the spectral lines subtracted. This routine also returns a list of the lines removed. For each line it provides the frequency bin (for the padded data set) in which the line falls, the value of the F-test for that line, and the complex coefficient  $\hat{C}_i$  defined by Percival and Walden eqn (499a) which defines the line.

The arguments are:

`data`: Input. A pointer to the time-series array `data[0..npoints-1]`.

`npoints`: Input. The number of points in the previous array.

`padded_length`: Input. The number of points of zero-padded data that will be analyzed. Note that this must be an integer power of two greater than or equal to `npoints`. We recommend that you use at least a factor of four greater, to obtain sufficient frequency resolution to accurately identify/remove spectral lines.

`nwdt`: Input. The (total sample time)  $\times$  (frequency resolution bandwidth) product.

`nwin`: Input. Number of Slepian tapers. See previous sections.

`max_lines`: Input. The maximum number of spectral lines that you want removed. The array `line_list[0..max_]` must have at least this length.

`maxpass`: Input. The maximum number of iterations or passes through the line-removal loop described below. Set to a large number to make as many passes as needed to remove all the spectral lines.

`num_removed`: Output. The actual number of spectral lines subtracted from the data.

`line_list`: Output. A list of structures `line_list[0..num_removed-1]` containing the frequency bin, real and imaginary parts of the removed line, and the F-test significance value associated with the *first* removal of the line. Upon return from this function, the elements of `line_list[]` are sorted into increasing frequency-bin order.

`mtap_spec_init`: Output. The multi-taper power spectrum of the *initial* `data[]` array, including both DC and Nyquist frequency bins. The array range is `mtap_spec_init[0..padded_length/2]`.  
Warning -this is an *odd* number of entries. The user must provide a pointer to sufficient storage space.

`mtap_spec_final`: Output. The multi-taper power spectrum of the *final* `data[]` array, with the spectral lines subtracted, including both DC and Nyquist frequency bins. The array range is `mtap_spec_final[0..p`.  
Warning -this is an *odd* number of entries. The user must provide a pointer to sufficient storage space.

`dospecs`: Input. If set non-zero, then the initial/final power spectra (pointed to by `mtap_spec_init` and `mtap_spec_final` are calculated. If set to zero, then to save time in situations where all that is needed a list of spectral lines and their amplitudes and phases, then neither of these power spectra are calculated.

`fimin`: Input. In situations where all that is needed is a list of spectral lines and their amplitudes, and it is desired to limit the search to a restricted range of frequencies, then `fimin` defines the lower bound of the range of (padded) frequency bins which are searched for spectral lines. The range of `fimin` is  $0..klen/2$ . Also, `fimin` < `fimax`.

`fimax`: Input. In situations where all that is needed is a list of spectral lines and their amplitudes, and it is desired to limit the search to a restricted range of frequencies, then `fimax` defines the upper bound of the range of (padded) frequency bins which are searched for spectral lines. The range of `fimin` is  $0..klen/2$ . Also, `fimin` < `fimax`.

The algorithm used by `remove_spectral_lines()` is an automated version of the procedure illustrated in Percival and Walden Section 10.13. The steps followed are:

1. The mean value is subtracted from the data-set, and it is zero padded to the specified length.
2. The set of Fourier coefficients for the tapered data sets are determined.
3. From these coefficients the F-statistic is determined for each frequency bin (Percival and Walden eqn (499c)). If the confidence level (that the frequency bin contains a spectral line) exceeds  $1 - 1/npoints$  (Percival and Walden pg 513), an estimator of the spectral line coefficients is constructed, and the line is placed onto a working list. If no frequency bins exceed this level of confidence, we are finished.
4. The working list is now sorted into order of decreasing F-values.
5. To ensure that we do not remove the same line twice, the spectral line associated with each spectral line on the working list is subtracted from the data-set, provided that it does not lie within a frequency width of  $\pm W$  of a stronger (larger F-value) line.
6. We return to step 1 above, iterating this procedure, provided that the number of times that we have passed by step 1 is less than or equal to `maxpass`.

Author: Bruce Allen ([ballen@dirac.phys.uwm.edu](mailto:ballen@dirac.phys.uwm.edu)) and Adrian Ottewill ([ottewill@relativity.ucd.ie](mailto:ottewill@relativity.ucd.ie)).

Comments: If `max_lines` is not large enough, then the `line_list[]` array may not contain all of the possible spectral lines, which exceed the confidence level above. This may even be the case if `num_removed` is less than `max_lines`. We suggest that you make `max_lines` somewhat larger than `num_removed`. One ought to be able to improve on this routine, by using the array of F-values generated internally and interpolating to find the frequency of the lines more precisely. One might also be able to fit to a model of two closely separated lines to better remove certain "split" features, or to fit to an exponentially-decaying model to remove other broadened features.

## 10.25 Example: river

This is an example program which uses the function `remove_spectral_lines()` to repeat the analysis of data from the Willamette River given by Percival and Walden in section 10.13 of their textbook.

It displays graphs of the river flow data (which is distributed with GRASP) and spectrum before and after automatic removal of the two significant spectral lines (whose frequencies are 1/year and 2/year). These graphs are also shown here. Before running this program, be sure to set the environment variable giving the path to the river data, for example:

```
setenv GRASP_PARAMETERS /usr/local/GRASP/parameters
```

The text output of the program is as follows:

```
Total number of lines removed: 2
Removed line of amplitude -0.291175 + i 0.312209 at freq 1.005848 cycles/year
(F-test value 48.455242)
Removed line of amplitude 0.023220 + i 0.098357 at freq 2.000000 cycles/year
(F-test value 15.224311)
```

```
#include "grasp.h"
#include <unistd.h> /* need the header for the sleep() function */

int main() {
    int i, num_points, num_win, num_freq, padded_length, max_lines, num_removed;
    float nwdt, *data, *mtap_spec_init, *mtap_spec_final, freq, fnyquist;
    struct removed_lines *line_list;
    FILE *fpriver;

    /* data length, padded length, num frequencies including DC, Nyquist */
    num_points=395;
    padded_length=1024;
    num_freq=1+padded_length/2;

    /* number of taper windows to use, and time-freq bandwidth */
    num_win=5;
    nwdt=4.0;

    /* maximum number of lines to remove */
    max_lines=8;

    /* allocate arrays */
    data= (float *)malloc(sizeof(float)*num_points);
    mtap_spec_init=(float *)malloc(sizeof(float)*num_freq);
    mtap_spec_final=(float *)malloc(sizeof(float)*num_freq);
    line_list=(struct removed_lines *)malloc(sizeof(struct removed_lines)*max_lines);

    /* Read Willamette River data from Percival & Walden example, pg 505 */
    fpriver=grasp_open("GRASP_PARAMETERS", "willamette_river.dat");
    for (i=0; i<395; i++) fscanf(fpriver, "%f", data+i);
    fclose(fpriver);

    /* Since the data is sampled once per month, fnyquist = 6 cyles/year */
    fnyquist=0.5*12;

    /* pop up a graph of the original data */
    graph(data, num_points, 1); sleep(5);
```

```

/* now remove the spectral lines from the data set */
remove_spectral_lines(data,num_points,padded_length,nwdt,num_win,
    max_lines,500,&num_removed,line_list,mtap_spec_init,mtap_spec_final,1,0,num_freq);

/* pop up a graph of the original multitapered spectrum */
graph(mtap_spec_init,num_freq,1); sleep(5);

/* pop up a graph of the line-removed data and multitapered spectrum */
graph(data,num_points,1); sleep(5);
graph(mtap_spec_final,num_freq,1); sleep(5);

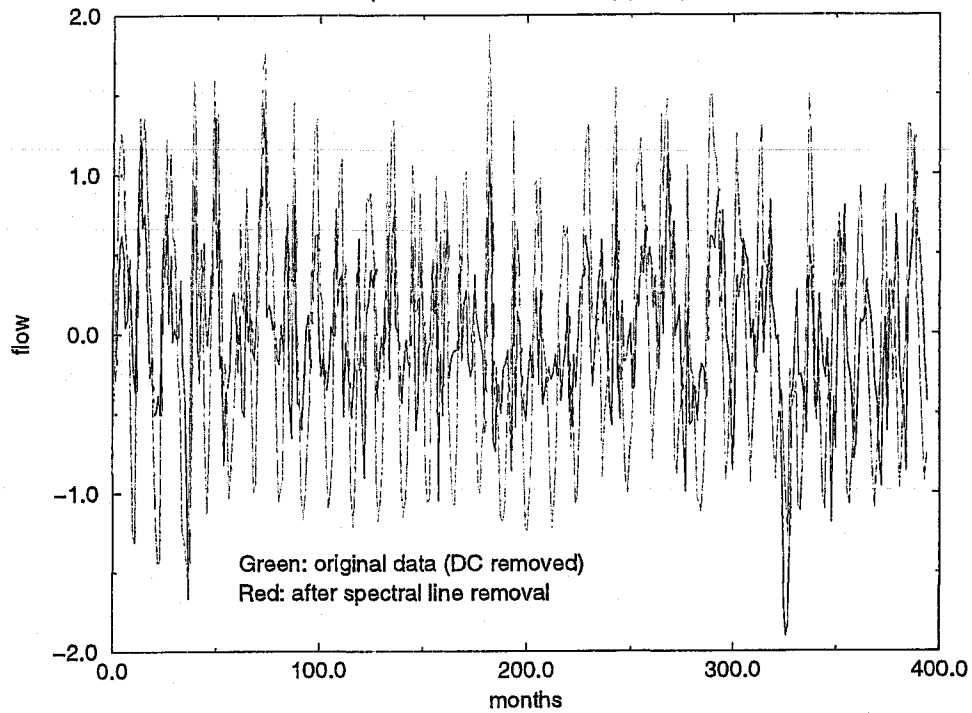
/* print out a list of lines removed */
printf("Total number of lines removed: %d\n",num_removed);
for (i=0;i<num_removed;i++) {
    freq=line_list[i].index*fnyquist/num_freq;
    printf("Removed line of amplitude %f + i %f at freq %f cycles/year\t",
        line_list[i].re,line_list[i].im,freq);
    printf("(F-test value %f)\n",line_list[i].fvalue);
}
return 0;
}

```



### Willamette River Flow

(from Percival & Walden pg 505)



### Willamette River

multi-taper power spectrum

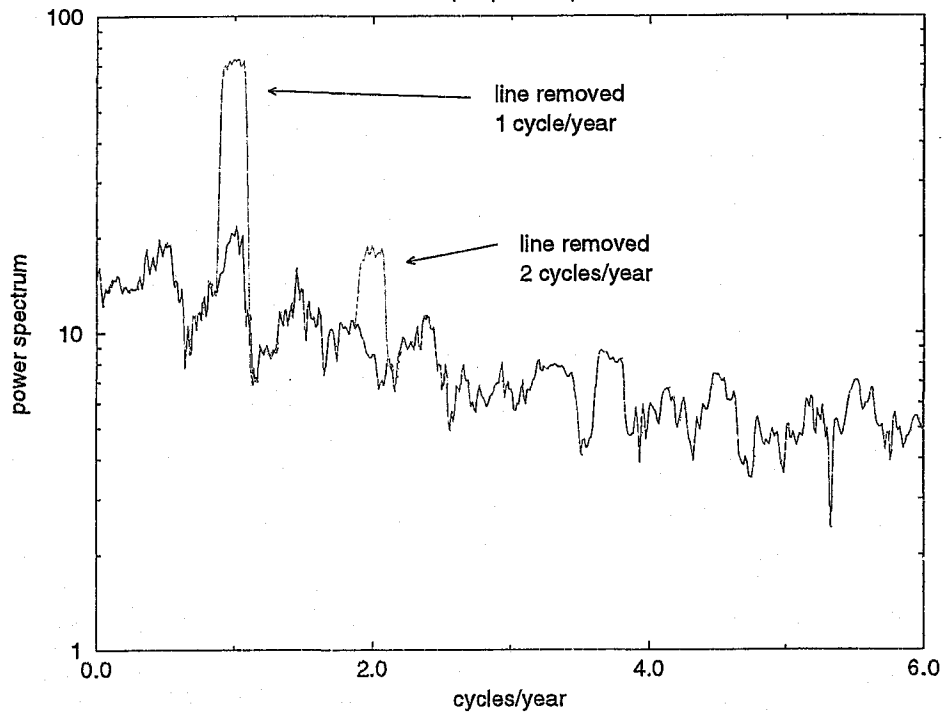


Figure 56: Output of the example program river, making use of `remove_spectral_lines()` to automatically find and remove two “spectral line” features from a data set. This is the same example treated by Percival and Walden in Section 10.13 of their textbook.

## 10.26 Example: ifo\_clean

This example program uses `remove_spectral_lines()` to automatically identify and remove "spectral lines" from the output of the 40-meter IFO. To run this program, be sure to set the data path environment variable, for example:

```
setenv GRASP_DATAPATH /usr/local/GRASP/data/19nov94.3
```

The program outputs graphs in a two files called `ifo_clean_data.out` and `ifo_clean_spec.out`, containing the before/after time series and spectra. These may be viewed with `xmgr` by typing:

```
xmgr -nxy ifo_clean_data.out
```

and

```
xmgr -nxy ifo_clean_spec.out
```

to start up the `xmgr` graphing program.

The output of this program is a list of lines removed:

Total number of lines removed: 39

```
Removed line frequency 30.717 Hz amplitude 0.78 phase 15.54 (F-test 68.6)
Removed line frequency 79.203 Hz amplitude 0.55 phase -157.41 (F-test 52.5)
Removed line frequency 80.257 Hz amplitude 0.12 phase -101.84 (F-test 39.3)
Removed line frequency 109.318 Hz amplitude 4.52 phase 10.21 (F-test 75.5)
Removed line frequency 120.009 Hz amplitude 0.46 phase 5.01 (F-test 537.9)
Removed line frequency 139.584 Hz amplitude 0.29 phase -163.57 (F-test 304.5)
Removed line frequency 179.938 Hz amplitude 21.91 phase -43.22 (F-test 3635.0)
Removed line frequency 239.867 Hz amplitude 0.45 phase 130.25 (F-test 42.2)
Removed line frequency 245.438 Hz amplitude 0.21 phase -116.94 (F-test 51.9)
Removed line frequency 279.167 Hz amplitude 0.31 phase 0.52 (F-test 47.2)
Removed line frequency 299.947 Hz amplitude 15.37 phase -135.82 (F-test 9712.5)
Removed line frequency 359.876 Hz amplitude 1.17 phase 61.64 (F-test 134.8)
Removed line frequency 419.955 Hz amplitude 4.48 phase -39.58 (F-test 356.1)
Removed line frequency 488.768 Hz amplitude 0.19 phase 165.56 (F-test 50.5)
Removed line frequency 500.212 Hz amplitude 0.64 phase 129.38 (F-test 34.5)
Removed line frequency 539.964 Hz amplitude 5.09 phase 119.38 (F-test 425.2)
Removed line frequency 571.585 Hz amplitude 4.01 phase 120.03 (F-test 50.6)
Removed line frequency 578.662 Hz amplitude 34.97 phase -149.12 (F-test 429.8)
Removed line frequency 582.426 Hz amplitude 107.36 phase 15.64 (F-test 1129.7)
Removed line frequency 597.936 Hz amplitude 58.72 phase 63.27 (F-test 558.6)
Removed line frequency 605.314 Hz amplitude 17.21 phase -140.57 (F-test 489.7)
Removed line frequency 659.822 Hz amplitude 2.20 phase -152.53 (F-test 121.0)
Removed line frequency 779.831 Hz amplitude 3.95 phase -39.18 (F-test 502.4)
Removed line frequency 839.760 Hz amplitude 2.75 phase -172.15 (F-test 468.2)
Removed line frequency 899.840 Hz amplitude 3.40 phase 113.05 (F-test 529.6)
Removed line frequency 959.919 Hz amplitude 0.80 phase 178.70 (F-test 43.2)
Removed line frequency 999.822 Hz amplitude 1.01 phase 67.74 (F-test 114.8)
Removed line frequency 1019.698 Hz amplitude 1.46 phase -156.72 (F-test 146.6)
Removed line frequency 1079.777 Hz amplitude 3.00 phase 51.82 (F-test 128.9)
Removed line frequency 1157.023 Hz amplitude 2.99 phase -76.14 (F-test 129.4)
Removed line frequency 1210.778 Hz amplitude 2.12 phase 128.39 (F-test 69.5)
Removed line frequency 1319.644 Hz amplitude 3.02 phase -105.29 (F-test 146.2)
Removed line frequency 1499.582 Hz amplitude 1.31 phase 141.94 (F-test 50.5)
```

Removed line frequency 1559.662 Hz amplitude 2.79 phase 107.12 (F-test 60.0)  
 Removed line frequency 1746.978 Hz amplitude 1.81 phase 50.38 (F-test 112.0)  
 Removed line frequency 2039.697 Hz amplitude 1.65 phase 165.82 (F-test 62.3)  
 Removed line frequency 2279.413 Hz amplitude 2.12 phase -25.06 (F-test 163.0)  
 Removed line frequency 3509.465 Hz amplitude 0.11 phase 43.89 (F-test 60.1)  
 Removed line frequency 4609.720 Hz amplitude 0.03 phase 24.61 (F-test 39.4)

Virtually all of these lines can be identified as either 60 Hz line harmonics, or as specific suspension and pendulum modes. The removal of these lines makes a dramatic difference to the appearance (and sound of) the signal, as shown in Figure 57. Note that the amplitudes of the lines above are properly normalized (in ADC units). For example the 180 Hz line harmonic is well described by  $A(t) = 21.91 \sin(360\pi t/\text{sec})$ . By far the largest amplitude lines are the three violin modes at 578.662, 582.426, and 597.936 Hz, and the 180 and 300 Hz line harmonics. Most of the structure visible in Figure 57 is the result of these five harmonics.

```
#include "grasp.h"

int main() {
    short *datas;
    int i,num_points,num_win,num_freq,padded_length,max_lines,num_removed,remain;
    float nwdt,*data,*mtap_spec_init,*mtap_spec_final,freq,tstart,srate,*initial_data,amp,phi;
    struct removed_lines *line_list;
    FILE *fpifo,*fplock,*fpout1,*fpout2;

    /* open the IFO output file and lock file */
    fpifo =grasp_open("GRASP_DATAPATH","channel.0");
    fplock=grasp_open("GRASP_DATAPATH","channel.10");

    /* data length, padded length, num frequencies including DC, Nyquist */
    num_points=8192;
    padded_length=65536;
    num_freq=1+padded_length/2;

    /* number of taper windows to use, and time-freq bandwidth */
    num_win=5;
    nwdt=3.0;

    /* maximum number of lines to remove */
    max_lines=100;

    /* allocate arrays */
    datas=(short *)malloc(sizeof(short)*num_points);
    data=(float *)malloc(sizeof(float)*num_points);
    mtap_spec_init=(float *)malloc(sizeof(float)*num_freq);
    mtap_spec_final=(float *)malloc(sizeof(float)*num_freq);
    line_list=(struct removed_lines *)malloc(sizeof(struct removed_lines)*max_lines);
    initial_data=(float *)malloc(sizeof(float)*num_points);

    /* get a section of data... */
    get_data(fpifo,fplock,&tstart,num_points,datas,&remain,&srate,0);

    /* copy short data to float data,and save initial data set */
    for (i=0;i<num_points;i++) initial_data[i]=data[i]=datas[i];

    /* remove the spectral lines from the data set */
    remove_spectral_lines(data,num_points,padded_length,nwdt,num_win,
        max_lines,500,&num_removed,line_list,mtap_spec_init,mtap_spec_final,1,0,num_freq);
}
```

```

/* print out a list of lines removed */
printf("Total number of lines removed: %d\n", num_removed);
for (i=0; i<num_removed; i++) {
    freq=0.5*line_list[i].index *srate/num_freq;
    amp=2.0*sqrt(line_list[i].re*line_list[i].re+line_list[i].im*line_list[i].im);
    phi=180*atan2(line_list[i].im,line_list[i].re)/M_PI;
    printf("Removed line frequency %.3f Hz amplitude %.2f phase %.2f (F-test %.1f)\n",
        freq, amp, phi, line_list[i].fvalue);
}

/* now output a file containing the initial and final data... */
fpout1=fopen("ifo_clean_data.out", "w");
fprintf(fpout1, "# Three columns are:\n# Time (sec) Initial data Final Data\n");
for (i=0; i<num_points; i++)
    fprintf(fpout1, "%f\t%f\t%f\n", i/srate, initial_data[i], data[i]);
fclose(fpout1);

/* ... and the initial and final spectra, for graphing by xmgr */
fpout2=fopen("ifo_clean_spec.out", "w");
fprintf(fpout2, "# Three columns are:\n# Freq (Hz) Initial spectrum Final spectrum\n");
for (i=0; i<num_freq; i++)
    fprintf(fpout2, "%f\t%f\t%f\n", 0.5*i*srate/num_freq, mtap_spec_init[i], mtap_spec_final[i]);
fclose(fpout2);

return 0;
}

```

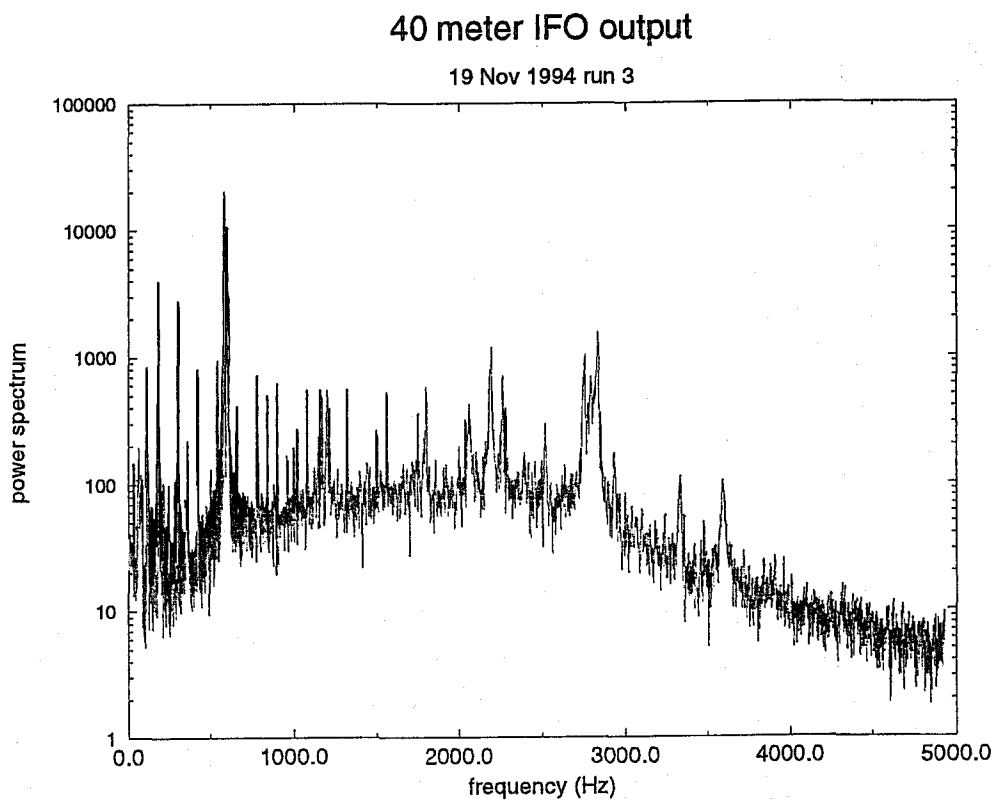
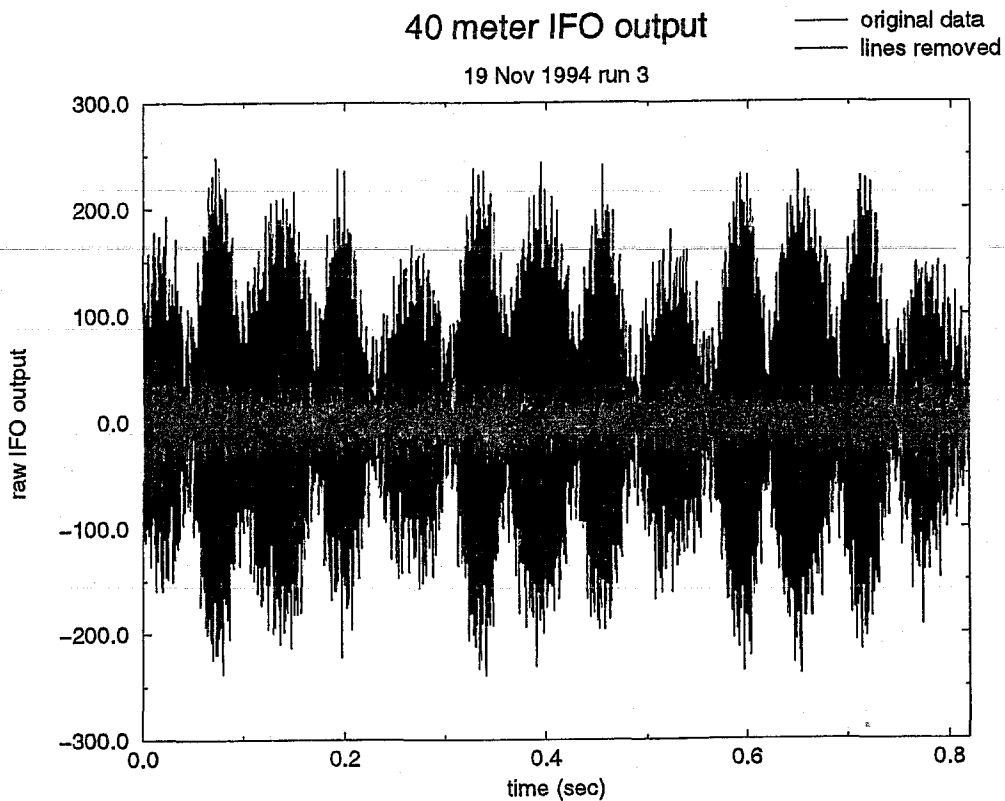


Figure 57: Output of the example program `ifo_clean`, making use of `remove_spectral_lines()` to automatically identify and remove “spectral line” features from the (whitened) output of the Caltech 40-meter interferometer. The black curve and the red curve show the before/after time series and spectra. We have deliberately chosen a stretch of data immediately after the IFO locks, so that the suspension and pendulum modes are excited.

## 10.27 Example: tracker

This program produces an animated display which tracks the amplitude and phase of selected line features in the spectrum. It has a number of user-settable options which determine how the line is tracked. To run this program, type

```
tracker | xmgr -pipe
```

and an animated display will start up. In normal use, the parameters should be set as follows:

`num_points`: a power of two. A single phase/amplitude point is printed for each set of `num_points` samples.

`padding_factor`: a power of two. This determines the amount of padding done on the data set, and thus the ultimate frequency resolution of the line discrimination.

`fpreset`: your best guess for the frequency that you want to track. If the actual frequency of the spectral line differs from this value, then the phase will slowly drift as a linear function of time. (The `tracker` program does a robust best linear fit to this slope, and uses it to report a best frequency estimate.)

`estimate`: if set to zero, then the phase of the line found is always compared with the frequency preset above. If set non-zero, then `tracker` will make a "best estimate" of the true frequency, and compare the phase of the line found with the phase appropriate to that sinusoid.

`nbins`: the number of (padded) frequency bins adjacent to the one of interest in which the line will be searched for. The frequency range covered is thus given by

$$\Delta f = \pm \frac{\text{nbins}}{\Delta t(\text{num\_points} \times \text{padding\_factor} + 2)} \quad (10.27.1)$$

`num_display`: the number of points displayed by `tracker`. The total amount of time covered by the output is `num_display`  $\times$  `num_points`  $\times$   $\Delta t$  where  $\Delta t$  is the sample interval.

`num_win`, `nwdt`: these parameters are described in the section on multi-taper methods.

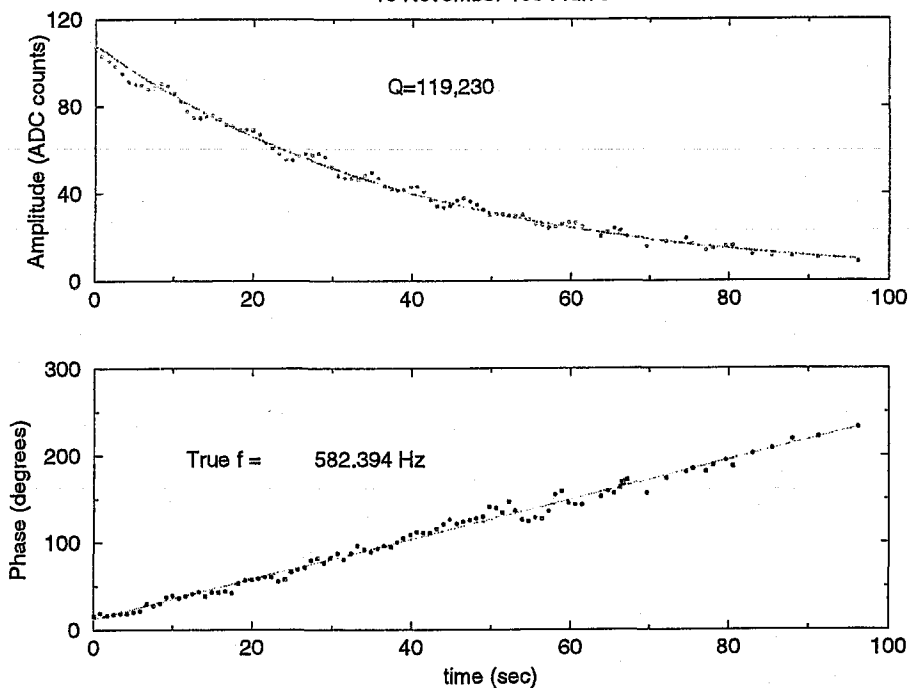
`maxpass`: the number of passes to make within `remove_spectral_lines()`. This number should be set as small as possible, provided that you still "catch" the line of interest.

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Comments: None.

### 582.4 Hz violin mode

19 November 1994 run 3



### Line Tracker

best estimate f=179.973053 Hz

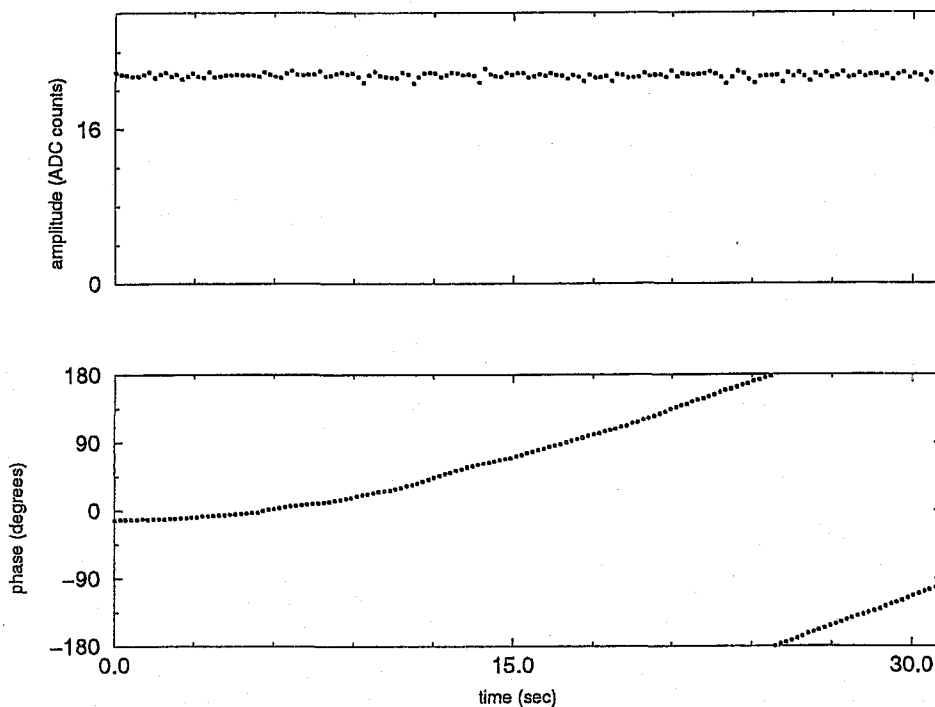


Figure 58: Output of the example program `tracker`, making use of `remove_spectral_lines()` to track the amplitude and phase of a selected "spectral line" features from the (whitened) output of the Caltech 40-meter interferometer. The upper two graphs show the approximately exponential decay of the 582.396 Hz violin mode; the lower two graphs show the amplitude and phase of the third harmonic of the 60Hz line noise (note the remarkable amplitude stability).

## 10.28 Example: trackerF

This example program is identical to the tracker program just described, which tracks spectral lines, but with one crucial difference: it reads its data from FRAME files rather than from the old format data stream.

To run this program, type

```
setenv GRASP_FRAMEPATH /usr/local/GRASP/18nov94.1frame
```

```
trackerF | xmgr -pipe
```

and an animated display will start up.

To run this example in real-time on data coming out at the 40-meter lab, type `setenv GRASP_REALTIME`

```
trackerF | xmgr -pipe
```

and an animated display will start up.

```
#include "grasp.h"

/* macros to define the standard mathematical forms of mod */
#define MOD(X) ((X)>=0?(X)%num_display):(num_display-1+((X+1)%num_display))
#define FMOD2PI(X) ((X)>=0.0?(fmod((X),2.0*M_PI):(2.0*M_PI+fmod((X),2.0*M_PI)))

/* numerical recipes routine for robust linear fit */
void medfit(float x[],float y[],int npoints,float *a ,float *b,float *dev);
void graphout(float,float,float,float);

main() {
    short *datas;
    int npass=1,num_points,num_win,num_freq,padded_length,max_lines,num_removed,remain,code,firstp
    int i,top,estimate,nbins,padding_factor,num_display,nprint,index,new=0,maxpass=1,minbin,maxbi
    float nwdt,*data,*mtap_spec_init,*mtap_spec_final,srate,creal,cimag;
    float *phase,phase1=0.0,ampl,phase2,*times,*linfitx,*linfity,offset,binpreset;
    float displaytime,t1,*amp,dbin,ffit,intercept,slope,deviation,maxamp,displayamp=1.0;
    double time,fpreset,sdoub,tsdoub,tinitial,tstart,initime=0.0;
    struct removed_lines *line_list;
    struct fgetinput fgetinput;
    struct fgetoutput fgetoutput;

    /* ----- USER DEFINABLE ----- */
    /* data length, padded length (powers of 2!) */
    num_points=2048;
    padding_factor=8;

    /* your best guess for the line frequency you want to track */
    fpreset=582.395;

    /* set non-zero if you want us to estimate the best-fit frequency */
    estimate=0;

    /* number of (padded) frequency bins (either side) to search near fpreset */
    nbins=5;

    /* the number of phase/amplitudes to display */
    num_display=150;

    /* number of taper windows to use, and time-freq bandwidth */
    num_win=5;
    nwdt=3.0;

    /* the number of passes to make within the line removal algorithm */
```



```

maxpass=1;

/* num_points=2048; padding_factor=8;fpreset=582.395; */
num_points=4096; padding_factor=4;fpreset=582.395;
num_points=4096; padding_factor=4;fpreset=180.0;
/* ----- END OF USER DEFINABLE ----- */

/* number of channels */
fgetinput.nchan=1;
fgetinput.inlock=0;
fgetinput.npoint=num_points;

/* source of files */
fgetinput.files=framefiles;

fgetinput.chnames=(char **)malloc(fgetinput.nchan*sizeof(char *));
fgetinput.locations=(short **)malloc(fgetinput.nchan*sizeof(short *));
fgetoutput.npoint=(int *)malloc(fgetinput.nchan*sizeof(int));

/* channel name */
fgetinput.chnames[0]="IFO_DMRO";

/* number of points to get */
fgetinput.seek=0;
fgetinput.calibrate=0;

padded_length=padding_factor*num_points;

/* num frequencies including DC, Nyquist */
num_freq=1+padded_length/2;

/* max number of lines to report on */
max_lines=64;

/* allocate storage */
datas=(short *)malloc(sizeof(short)*num_points);
data=(float *)malloc(sizeof(float)*num_points);
mtap_spec_init=(float *)malloc(sizeof(float)*num_freq);
mtap_spec_final=(float *)malloc(sizeof(float)*num_freq);
line_list=(struct removed_lines *)malloc(sizeof(struct removed_lines)*max_lines);
amp=(float *)malloc(sizeof(float)*num_display);
phase=(float *)malloc(sizeof(float)*num_display);
times=(float *)malloc(sizeof(float)*num_display);
linfitx=(float *)malloc(sizeof(float)*num_display);
linfity=(float *)malloc(sizeof(float)*num_display);

fgetinput.locations[0]=datas;

while (npass>0) {
    /* get a section of data... */
    code=fget_ch(&fgetoutput,&fgetinput);
    time=fgetoutput.dt;

    if (code==0) return 0;
    new+=code;

    srate=fgetoutput.srate;
    if (new==1) {
        fprintf(stderr, "\aTracker: New Locked Segment at time %f\n",time);
    }
}

```

```

    ffit=fpreset;
    npass=1;
    top=0;
    time=0.0;
}

binpreset=fpreset*2.0*num_freq/srate;
minbin=binpreset-nbins;
if (minbin<0) minbin=0;
maxbin=binpreset+nbins;
if (maxbin>num_freq) maxbin=num_freq;

/* copy short data to float data */
for (i=0;i<num_points;i++) data[i]=datas[i];

/* remove the spectral lines from the data set */
remove_spectral_lines(data,num_points,padded_length,nwdt,num_win,max_lines,
    maxpass,&num_removed,line_list,mtap_spec_init,mtap_spec_final,0,minbin,maxbin);

/* if we fail to remove a line, amplitude set to zero, phase RETAINS PRIOR VALUE */
amp1=0.0;
/* look in the list of removed lines for the right one */
for (i=0;i<num_removed;i++) {
    /* the closest bin to our estimated frequency */
    dbin=binpreset-line_list[i].index;
    if (fabs(dbin)<=nbins) {
        creal=line_list[i].re+dbin*line_list[i].dcdbr+
            0.5*dbin*dbin*line_list[i].d2cdb2r;
        cimag=line_list[i].im+dbin*line_list[i].dcdbi+
            0.5*dbin*dbin*line_list[i].d2cdb2i;
        ampl=2.0*sqrt(creal*creal+cimag*cimag);
        phase1=atan2(cimag,creal)+2.0*M_PI*fmod(fpreset*time,1.0);
        break;
    }
}

/* save data in a circular buffers *[0..num_display-1] */
amp[top]=ampl;
phase[top]=FMOD2PI(phase1);
times[top]=time;

/* how many values are we going to output to the graph? */
nprint=(npass<num_display)?npass:num_display;

/* cut out a piece for the linear fit */
if (npass>=2) {
    /* adjust the phases to avoid boundary jumps */
    offset=0.0;
    index=MOD(top-nprint+1);
    linfitx[0]=times[index];
    linfity[0]=phase[index];
    for (i=1;i<nprint;i++) {
        index=MOD(top+i-nprint+1);
        linfitx[i]=times[index];
        if (phase[index]-phase[MOD(index-1)]>M_PI)
            offset-=2.0*M_PI;
        else if (phase[index]-phase[MOD(index-1)]<=-M_PI)
            offset+=2.0*M_PI;
    }
}

```

```

    linfity[i]=phase[index]+offset;
}

/* do a robust linear fit */
medfit(linfitx-1,linfity-1,nprint,&intercept,&slope,&deviation);

/* now see what frequency the best fit corresponds to */
ffit=fpreset-slope/(2.0*M_PI);

/* if we are assuming a fixed frequency (not adapting) */
if (!estimate) {
    slope=intercept=0.0;
}

/* print out amplitude if non-zero */
maxamp=0.0;
for (i=0;i<nprint;i++) {
    index=MOD(top+i-nprint+1);
    if (amp[index]>0.0)
        printf("%e\t%e\n",linfitx[i],amp[index]);
    else
        /* won't appear on the graph - out of bounds */
        printf("%e\t%f\n",linfitx[i],-1.0);

    if (amp[index]>maxamp) maxamp=amp[index];
}
/* separate data sets */
printf("&\n");
/* print out phase if non-zero amplitude */
for (i=0;i<nprint;i++) {
    phase2=linfity[i];
    phase2=FMOD2PI((phase2-slope*linfitx[i]-intercept));
    if (phase2>M_PI)
        phase2-=2.0*M_PI;
    phase2=(180.0/M_PI)*phase2;
    index=MOD(top+i-nprint+1);
    if (amp[index]>0.0)
        printf("%.8e\t%.8f\n",linfitx[i],phase2);
    else
        /* won't appear on the graph - out of bounds */
        printf("%.8e\t%f\n",linfitx[i],-500.0);
}
/* set up scale of the x-axis */
t1=linfitx[0];
displaytime=num_display*(num_points/srate);
/* set up scale of the amplitude graph y-axis */
if (maxamp>0.9*displayamp) {
    displayamp=1.3*maxamp;
    fprintf(stderr,"\aTracker: Line at %f Hz, amplitude just increased\n",fpreset);
}
else if (maxamp<0.4*displayamp && maxamp>0.0)
    displayamp=1.3*maxamp;

graphout(t1,t1+displaytime,ffit,displayamp);
fflush(stdout);
}

/* now display set, then kill set */
npass++;

```

```

    top=MOD(top+1);
}

return 0;
}

void graphout(float t1,float t2,float freq,float displayamp) {
    static int count=0;
    int xmaj,xmin;
    float ymaj,ymin=1.0;
    int amprec;

    xmin=(t2-t1)/10.0;
    xmaj=5*xmin;

    if (ymin<=displayamp/10.0)
        while (ymin<=displayamp/10.0) {
            ymin*=2.0;
            ymaj=4.0*ymin;
        }
    else
        while (ymin>displayamp/10.0) {
            ymin/=10.0;
            ymaj=5.0*ymin;
        }
    amprec=(int)log10(ymaj);
    if (amprec>1)
        amprec=0;
    else
        amprec=1-amprec;

    /* end of set marker */
    printf("&\n");

    if (count==0) {
        /* first time we draw the plot */
        printf("@doublebuffer true\n");
        printf("@focus off\n");
    }
    printf("@with g0\n");
    printf("@move g0.s1 to g1.s0\n");
    printf("@title \\\"\\-Line Tracker\\\"\n");
    printf("@subtitle \"best estimate f=%f Hz\"\n",freq);
    printf("@s0 linestyle 0\n");
    printf("@s0 symbol color 4\n");
    printf("@s0 symbol 2\n");
    printf("@s0 symbol size 0.28\n");
    printf("@s0 symbol fill 1\n");
    printf("@view 0.15, 0.53, 0.95, 0.90\n");
    /* set up x-axis for amplitude */
    printf("@world xmin %e\n",t1);
    printf("@world xmax %e\n",t2);
    printf("@xaxis tick major %d\n",xmaj);
    printf("@xaxis tick minor %d\n",xmin);
    printf("@xaxis ticklabel prec 1\n");
    printf("@xaxis ticklabel off\n");
    printf("@yaxis label \\\"\\-amplitude (ADC counts)\\\"\n");
    printf("@world ymin %e\n",0.0);
    printf("@world ymax %e\n",displayamp);

```

```

printf("@yaxis tick major %e\n",ymaj);
printf("@yaxis tick minor %e\n",ymin);
if (amprec<4)
    printf("@yaxis ticklabel prec %d\n",amprec);
else {
    printf("@yaxis ticklabel format general\n");
    printf("@yaxis ticklabel prec %d\n",1);
}
/* now do phase plot */
printf("@with g1\n");
printf("@s0 linestyle 0\n");
printf("@s0 linewidth 0\n");
printf("@s0 symbol color 2\n");
printf("@s0 symbol 2\n");
printf("@s0 symbol size 0.28\n");
printf("@s0 symbol fill 1\n");
printf("@view 0.15, 0.1, 0.95, 0.47\n");
/* set up x-axis for phase */
printf("@world xmin %e\n",t1);
printf("@world xmax %e\n",t2);
printf("@xaxis tick major %d\n",xmaj);
printf("@xaxis tick minor %d\n",xmin);
printf("@xaxis ticklabel prec 1\n");
printf("@xaxis label "\\-time (sec)\n");
/* set up y-axis for phase */
printf("@world ymin %e\n",-180.0);
printf("@world ymax %e\n",180.0);
printf("@yaxis tick major 90\n");
printf("@yaxis tick minor 45\n");
printf("@yaxis ticklabel prec 0\n");
printf("@yaxis label "\\-phase (degrees)\n");
printf("@xaxis label "\\-time (sec)\n");
/* draw plot */
printf("@redraw\n");
printf("@kill s0\n");
printf("@with g0\n");
printf("@kill s0\n");
    count++;
return;
}

```

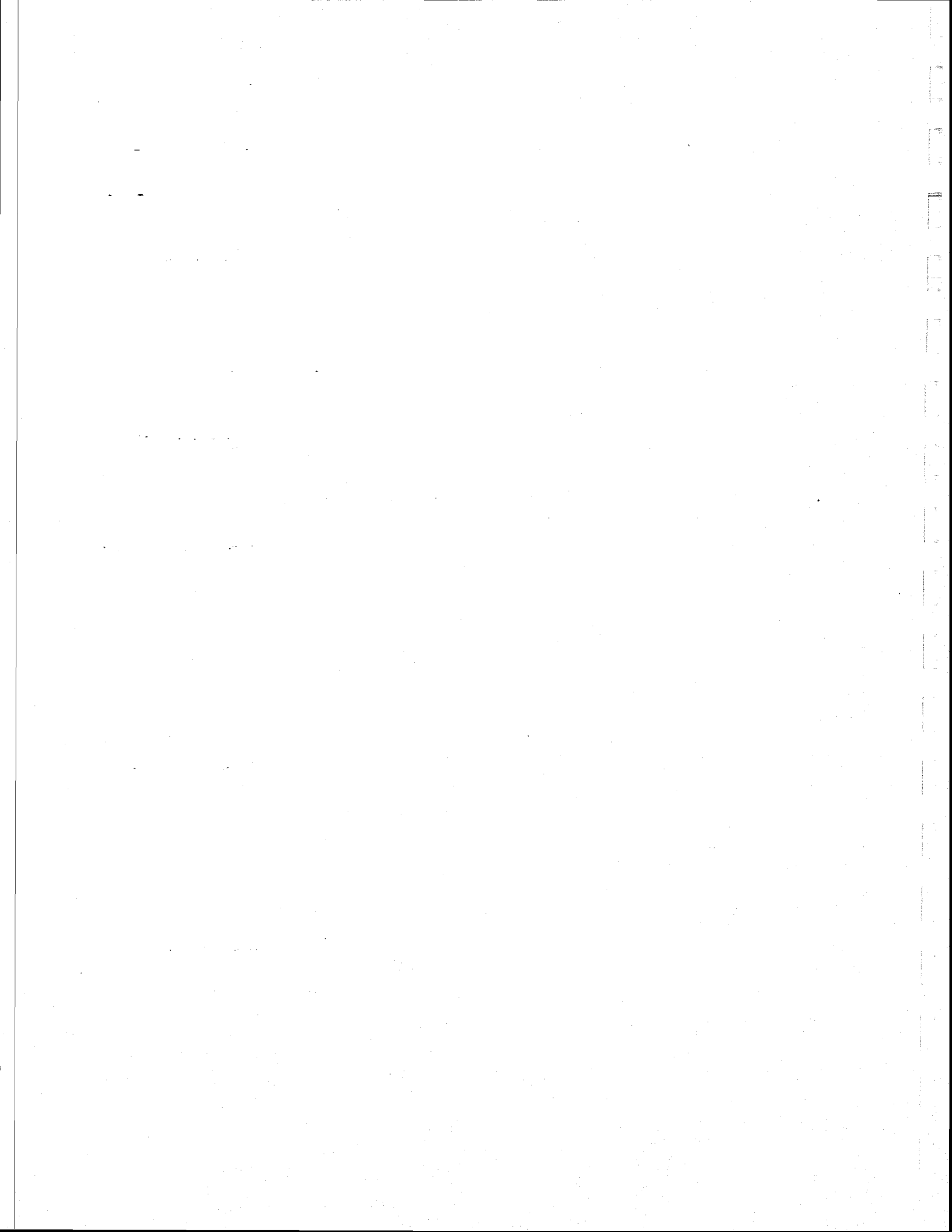
Authors: Bruce Allen (ballen@dirac.phys.uwm.edu) and Adrian Ottewill (ottewill@relativity.ucd.ie).

Comments: None.

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# **BATCH START**

---

**STAPLE  
OR  
DIVIDER**

**Sam, thank you very much for going to the trouble of writing this up for me. I thought that the easiest way to reply would be to type my remarks directly on your document, but in boldface, so that you can print it out and read my remarks immediately after your own.**

Bruce:

I believe that the algorithms used in GRASP to produce "calibrated" detector output are conceptually incorrect. As documented (see GRASP manual vers. 1.5.2 §4.7-§4.10) and coded, these routines do not correctly produce calibrated detector output. The affected routines include GRcalibrate, GRnormalize, and all GRASP routines that depend on them.

**As you will see below, I don't agree with this.**

Summarizing the documentation, the procedure used to calibrate the detector output is to

1. interpolate the swept sine calibration data, which is stored in the frequency domain, to some convenient resolution;
2. form, from the interpolated data, what is believed to be the detector transfer function in the frequency domain;
3. multiply, in the frequency domain, the interpolated transfer function with a transformed segment of detector output;
4. invert the transform to yield the "calibrated" detector output.

**A couple of comments here. First, the swept sine calibration data is not only stored in the frequency domain, it is actually obtained in the frequency domain. The output of the HP swept sine analyzer is actually a 3 column file of data, containing freq, real, imag parts. The HP works by driving the IFO coil voltage with a sinusoid of fixed frequency, waiting till the IFO output settles down to a sine wave of the same frequency, then outputting the ratio of output to input voltage, and the relative phase of input and output. It then steps up to the next frequency.**

There are two fundamental errors in this procedure:

1. the frequency domain interpolation of the swept sine data does not correctly produce the transfer function; and

**I don't agree with this. Please look at Figure 12, on page 70 of the GRASP 1.5 manual. This is the actual data from the HP, measured at 801 frequencies. As you can see, it varies quite smoothly over the frequency range of interest, having only a few smooth cycles from DC to 5kHz. For this reason, interpolating in these two sampled data sets (real and imaginary parts) will give an excellent fit to the transfer function, provided that we interpolate at more than a few hundred frequency values.**

2. the convolution of the (incorrect) transfer function with the raw data, which is carried out here in the frequency domain, fails to accommodate itself to either the periodic nature of the discrete Fourier transform (DFT) or the importance of transient effects in the initial and final values of the filter output.

**I don't agree with this either. The only convolution carried out in GRASP is in the find\_chirp() routine. The only times that we use this, we are always convolving a function which is non-zero for most of its samples (a zero-padded chirp) with a section of the data set. This is discussed in section 5.18 of the GRASP manual, beginning**

on page 117. We have been quite careful to **ONLY** take values of the output which are not affected by the periodic nature of the DFT. In fact if you read the relevant lines of code from the optimal program on page 134 of the GRASP manual, you will see how this works. The chirp length is 13,000. A variable called chirplen is set to this value plus a safety factor of SAFETY=1000 (more about this below). Then the routine find\_chirp() searches the output of the convolution only from 0 to npoint - chirplen. This is precisely the procedure described in *Numerical Recipes*.

In the following two subsections I will outline how I believe calibration should be carried out, noting where I think the GRASP routines are flawed.

**I am not sure by what is meant by "how the calibration should be carried out", do you agree that the measured data from the HP is sufficient to calibrate the instrument, or do you think it is not? If so, do you mean "how you should be using the calibration information" If not, what do you think is needed for calibrating the instrument?**

After you have looked these notes over we should talk.

**That would be nice.**

I will be relatively inaccessible this week and out of town from Saturday through Tuesday. I will be back Wednesday 29 October, though I may be difficult to get a hold of owing to the NSF review (I'll probably want to sit-in on some of the sessions in order to learn more about what's going on).

**I should be available virtually anytime. My phone number at work is 414-229-6439.**

## 1. THE TRANSFER FUNCTION

The measured transfer function is a linear filter determined by applying a known force (in this case, a swept sine wave) to the detector and measuring its response. Let the applied force be the sequence  $b[k]$  and the sampled response be  $a[k]$ , where  $k$  is the sample index. Define the  $z$ -transform of length  $N$  sequence  $c[k]$  by

$$C(z) = \sum_{k=0}^N -1c[k]z^{-k} \quad (1)$$

**I assume that this is a typo, and also that  $z = \exp(i\omega\Delta t)$  where  $\omega$  is frequency and  $\Delta t$  is the sample interval.**

The  $z$ -transform  $H(z)$  of the transfer function  $h[k]$  which takes the measured response to the applied force is given by

$$A(z)H(z) = B(z). \quad (2)$$

In this way, from the applied  $a[k]$  and the measured  $b[k]$  we can determine the transfer function as an ARMA (Auto-Regressive Moving-Average) filter:

$$H(z) = \frac{\sum_k b[k]z^{-k}}{\sum_k a[k]z^{-k}}. \quad (3)$$

The length of the sequences  $a$  and  $b$  determine the accuracy with which the detectors transfer function has been determined by the measurement process.

**This is in fact not how the transfer function of the instrument is measured. You might want to talk with Stan Whitcomb, Fred Raab, or**

Jennie Logan, or even go to the lab and ask someone there to demonstrate the procedure. A good way to do this is on a simple R-C circuit for which you can easily compute the answer.

In order to obtain, from a measured response  $y$  the applied force  $x[k]$ , we can apply the filter  $H(z)$ . We can do this in  $z$ -space; or, we can do it in the time domain:

$$y[n] = \sum_{k=0} b[k]x[n-k] - \sum_{k=0} a[k]y[n-1-k]. \quad (4)$$

The filter output depends on past states; it is for this reason that we call it autoregressive. (Note also that the filter has an infinite impulse response.)

**Both of these remarks are relevant. Although the filter output depends upon past states, the way that the calibration is typically measured is using the steady-state response to a sinusoidal driving force as described above. The HP is a fairly intelligent machine and actually waits until the output of the IFO has settled down to a steady sinusoid of fixed frequency and phase before it makes a measurement and steps to the next frequency. This is measured by something called the "coherence" which must be large for the instrument to make a measurement and step on to the next frequency.**

Since the filter response depends on past states, it is not sufficient to know the applied force to determine the detector output. The filter output will have an initial transient behavior associated with unknown past states. The response of real systems eventually damps, however, and as long as we measure the system response  $a[k]$  for a time longer than the sum of the duration of the applied force and the damping time, the derived filter will accurately relate the force to the detector output.

**The impulse response of the instrument (response of the IFO\_DMRO output to a delta-function gravitational strain) has a duration of about 3 msec. I show it in an attached graph, Figure 5.**

We can also represent the filter in the frequency domain, which is what is done in GRASP. We can assume that we know the applied force for as long as we have measured the system response; so, the DFT of each has the same resolution in the frequency domain.

The problem arises when you interpolate in the frequency domain. Interpolation in the discrete frequency domain is equivalent to *extrapolating* the applied force and measured response in the time domain: in this case, extrapolating a response unmeasured and unknown. The particular extrapolation carried out by the DFT is *periodic extrapolation*: i.e., the detector response is assumed to be *periodic*. The "transfer function" calculated by the GRASP routines thus bears no relationship to the actual response function.

**I think that the only effect of interpolating is the one that I described above. Provided that the transfer function varies smoothly so that you are not interpolating values of a wildly-oscillating function, there is no problem. As you can see from the GRASP figure that I reference, there is no problem here.**

For example, see figures 1 and 1. The first figure shows the product of a Gaussian and a sinusoid, which may be thought of as the time domain representation of a transfer function. The second figure shows what happens to this transfer function

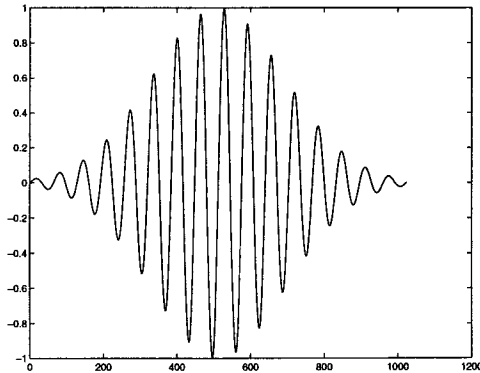


FIGURE 1. An example transfer function in the time domain.

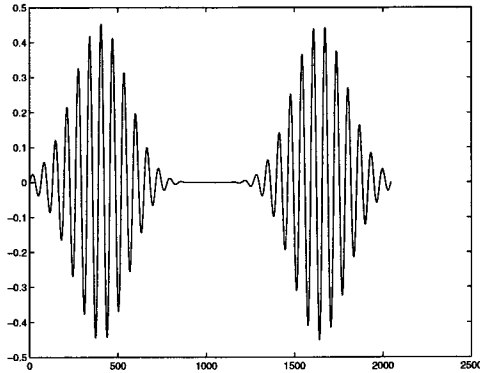
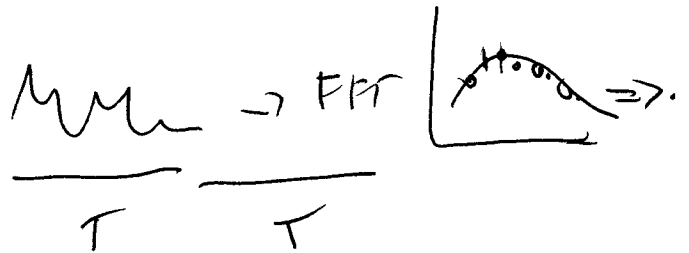


FIGURE 2. The transfer function of 1 after its DFT has been interpolated to twice the resolution in the frequency domain and transformed back to the time domain. Note that the filter has been replicated in the extended points.

if we transform it to the frequency domain, double the resolution there by linearly interpolating to the intermediate frequencies, and transform back via an inverse DFT. The resulting “transfer function” now has twice the duration in the time domain and, consistent with the periodic extrapolation of the DFT, the original filter has been replicated in the extended points.



Sam: to show that the problem that you describe here does not occur in GRASP, I have written you a one-page demonstration program. It has been used to produce the three graphs that follow. All the source code and the ready-to-run executable can be found in `ligo.caltech.edu:~ballen/FINN`. The code itself is very easy to read, and is included in Section 2 of this document. The program is called `sam.c`; the executable is called `sam`. To run the code, copy `sam` and `swept-sine.ascii` to your home directory (you must have write permission in the directory that you run in) then do the following commands:

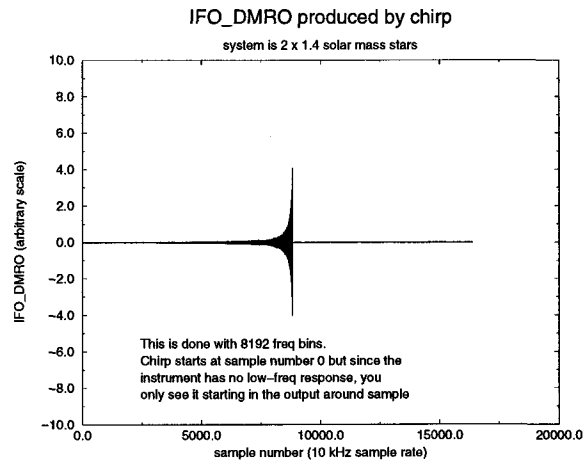
```
cd ~
setenv GRASP_DATAPATH `pwd`
sam
```

You will then be prompted for the number of frequency intervals. Enter a number (for example 8192) and a graph will pop up. If you want to play with the code, and you need help, please ask Kent or one of Kips postdocs for help. The program calculates the IFO\_DMRO output signal that would be produced by a  $2 \times 1.4$  solar mass chirp. When you run it, it prompts you for the number of frequency bins, then outputs a file containing the IFO\_DMRO signal as a two-column ascii file and also displays a graph of that file.

I have included here output for 8192 frequency bins (Figure 3) and 32768 frequency bins (Figure 4). I show the output in two attached figures. As you can see, the IFO\_DMRO calculated in each case looks precisely like what one would expect. The instrument has poor low-frequency response due to the whitening filters used to overcome seismic noise, so the low frequency part of the IFO\_DMRO has rather lower amplitude than the corresponding gravitational strain  $h(t)$ . The "doubling problem" that you claim is present in GRASP does not occur.

Because you are interested in the impulse response of the instrument, I have also included a line in this code (commented out) which calculates the impulse response. It is about 3 msec long, which is the reason for the SAFETY=1000 padding factor mentioned earlier. In fact since the sample rate is about 10kHz SAFETY=50 would probably be more than enough. In fact you can see an effect of this in the calibrated IFO\_DMRO outputs shown in the Figs 3 and 4. If you look very closely at the first 2 msec or so you will see a small transient. This is because the chirp is turned on abruptly so you see a little transient "wiggle" at the start. This is commented on, on page 125 of the GRASP manual, in the `time_inject_chirp()` routine. It turns out to be of no consequence.

This leads me to ask the question, were the graphs that you produced made with GRASP or with code of your own? If they were produced with GRASP I would be interested to see your code. I believe that there are no errors of the type that you describe in any of the GRASP example programs.



**FIGURE 3.** This shows the GRASP-computed IFO\_DMRO that would be produced by 2 x 1.4 solar mass stars. The chirp enters the band at 140 Hz at sample zero, on the far left of the graph. However because of the poor low-freq response of the instrument it does not appear in the DMRO until about half a second later. This calibrated output was computed using 8192 frequency bins.

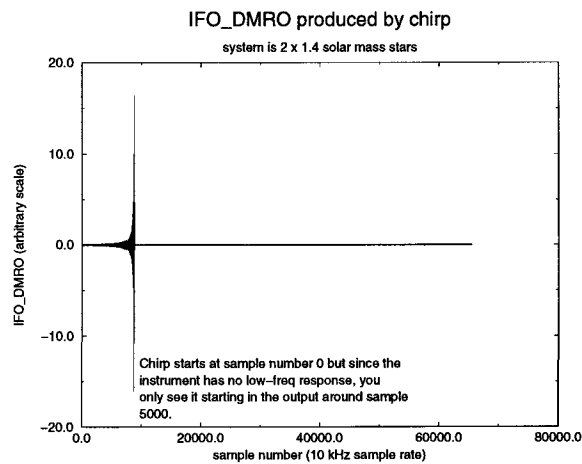


FIGURE 4. This shows the GRASP-computed IFO\_DMRO that would be produced by 2 x 1.4 solar mass stars. The chirp enters the band at 140 Hz at sample zero, on the far left of the graph. However because of the poor low-freq response of the instrument it does not appear in the DMRO until about half a second later. This calibrated output was computed using 32768 frequency bins. It does not demonstrate or indicate any of the “doubling” problems claimed by Finn.

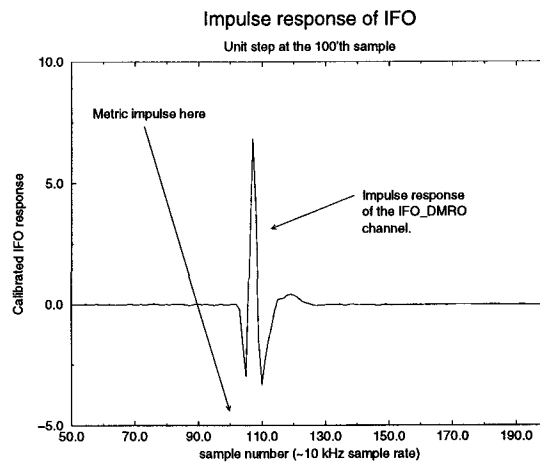


FIGURE 5. This shows the GRASP-computed IFO\_DMRO's impulse response. It is the response of the IFO to a delta-function unit impulse at the 100'th time sample. It falls off after about 3 msec = 30 samples.



## 2. GRASP CODE USED TO PRODUCE ALLEN'S FIGURES

```

#include <stdio.h>
#include <memory.h>
#include "grasp.h"
#define HSCALE 1.e20

main() {
float fstart,srate,tcoal,*c0,*c90,*response;
int filled,i,nmax=1,nbins;
void realft(float*,unsigned long, int);
FILE *fp;

printf("Please enter the number of desired freq bins\n");
scanf("%d",&nbins);
for (i=0;i<30;i++) if (nbins==(nmax+nmax)) break;
if (i<12 || i>=30) {
printf("This must be a power of two >=8192.\n");
exit(1);
}
nbins*=2;

/* allocate memory */
c0=(float*)malloc(sizeof(float)*nbins);
c90=(float*)malloc(sizeof(float)*nbins);
response=(float*)malloc(sizeof(float)*(nbins+1));

/* set start frequency, sample rate, make chirp */
make_filters(1.4,1.4,c0,c90,fstart=140.0,nbins,srate=9868.0,&filled,&tcoal,4000,4);
printf("Chirp length is %d.\n",filled);

/* Uncomment this line to see the impulse response of the instrument */
/* for (i=0;i<nbins;i++) c0[i]=0.0; c0[100]=1.0; */

/* put chirps into frequency domain */
realft(c0-1,nbins,1);

/* open file containing calibration data, get response, and scale */
fp=grasp_open("GRASP_DATAPATH","swept-sine.ascii");
normalize_gw(fp,nbins,srate,response);
for (i=0;i<nbins;i++) response[i]*=HSCALE;

/* avoid floating point errors in inversion */
nmax=0.05*fstart*nbins/srate;
for (i=0;i<nmax;i++) response[i]=1.e10;

/* determine IFO channel0 input which would have produced waveform */
ratio(c0,c0,response,nbins/2);

/* invert FFT */
realft(c0-1,nbins,-1);

/* make a graph showing IFO_DMRO */
printf("File temp.graph contains IFO_DMRO produced by 2 x 1.4 solar masses.\n");
graph(c0,nbins,1);
}

```

## 3. CONVOLUTIONS

Consider a finite impulse response (FIR) or moving average (MA) filter  $b$  of length  $N$  and indexed from 0:

$$y[n] = \sum_{k=0}^{N-1} b[k]x[n-k]. \quad (5)$$

The sequence  $y$  is the convolution of the two sequences  $b$  and  $x$ . This convolution can be carried out in the discrete frequency domain *if one is careful of the periodicity imposed by the DFT*.

The summation above has been written assuming that  $x$  and  $y$  have infinite length. Suppose we have a finite length stretch of data  $x$ , indexed from 0 to  $M$ , and that we wish to filter it with  $b$  to produce  $y$ . As written,  $y[0]$  depends on  $x[0]$  and on previous values of  $x$  that are unknown. In fact, we don't actually know all the values of  $x$  needed to produce  $y$  until we are  $N$  samples into the response.

It is conventional to assume that  $x$  and  $b$  are zero at indices outside their defined range. Suppose that  $b$  and  $x$  are extended to length  $N+M$ , with  $x$  defined to be zero at its *final*  $N$  points and  $b$  defined to be zero at its final  $M$  points. Finally, define both these new sequences to be *periodic*, so that references to sequence elements  $k$  outside the range  $0 \dots N+M-1$  evaluate to sequence elements  $k \bmod (N+M-1)$ . With these definitions, one can verify that the summation

$$y[n] = \sum_{k=0}^{N+M-1} b[k]x[n-k] \quad (6)$$

correctly produces the output  $y[n]$  for  $n = 0 \dots M-1$ , in addition to non-physical output at later times. Also note that  $y$  is defined for all  $n$  and is periodic with period  $N+M$ , corresponding to the periodicity of  $b$  and  $x$ .

If we transform the periodic sequence  $y$  to the discrete frequency domain we will find that  $\tilde{y}[k]$  is equal to  $\tilde{b}[k]\tilde{x}^*[k]$ . Crucial for our ability to do this, and attain this result, was our extension of  $x$  and  $b$  and the imposition of periodic boundary conditions so that the sequence  $y$  was properly periodic. Were we not to extend by zero-padding the sequences  $x$  and  $b$ , but try to evaluate the convolution in the frequency domain, the DFT will enforce its own periodicity and, without the zero-padding, cause the initial  $N-1$  elements of the sequence  $y$  to involve filter coefficients times the *last* coefficients of the input sequence  $x$ .

**As I stressed above, the only GRASP routine that does convolution and deconvolution is the `find_chirp()` routine. The only times that we use this routine, we do exactly what you describe: zero pad the filters then only examine the part of the output which has not been "polluted" by wraparound.**

The GRASP routines for producing the "calibrated" time domain output sequence of the interferometer makes exactly this mistake: they fail to extend and zero-pad the input sequence and the filter before evaluating the convolution in the frequency domain. The result is that sequence elements in the early part of the "calibrated" output are contaminated by contributions from the late time detector output, and sequence elements at late times are contaminated by early time elements.

**Please stop making this claim! There are NO GRASP ROUTINES THAT PRODUCE THE "CALIBRATED" TIME DOMAIN OUTPUT**

**SEQUENCE OF THE INTERFEROMETER.** In fact it does not make sense to do this, although you can try. If you attempt to do this, you will find that the  $h(t)$  can not be represented by a floating-point variable; the IFO noise has such a large dynamic range that the region from 0.1 to 100 Hz will occupy the entire floating-point dynamic range. If you use a double-precision variable you might be able to represent  $h(t)$ , however you will find that it is very un-interesting, dominated entirely by the low frequency component. It will look like a noisy sinusoid at very low frequency. Since the instrument has essentially zero low frequency response, when you attempt to “invert” the IFO\_DMRO to obtain  $h(t)$  you are dominated by low frequency components of the noise.

If you study GRASP you will notice that we NEVER attempt to calculate or pass  $h(t)$ , for exactly this reason. I did notice that your new postdoc Soma (hopefully this is the correct spelling) apparently tried to do this, which she reported in Kip’s group meeting yesterday. As I said this is not a smart or useful thing to do. I can suggest several experiments that Soma can do if you’d like me to, as a way of understanding this is a deep and profound way.

In fact, since the GRASP routines use a filter whose length is equal to the length of the sequence being filtered, no element of the convolution between the filter and the raw detector output is correctly evaluated (which, it could be commented, is no great loss because, as we have already shown, the transfer function has been incorrectly evaluated).

**Again, in our filtering process, the filters are always zero padded and we ignore the part of the convolution contaminated by wraparound.**

A more extended discussion of how zero-padding is used and convolutions of a reasonable length filter with indefinitely long times series can be accomplished using the DFT can be found in most texts on digital signal processing, or in Numerical Recipes [1].

**It can also be found in GRASP section 5.18, and as I said already, the code does this correctly.**

Note that evaluation of filtering via a convolution is possible only with an FIR filter: it is not possible with any kind of infinite impulse response (IIR) or auto-regressive (AR) filter. If we form the transfer function as the ratio of the  $z$ -transforms of the detector output and the calibrated input, the transfer function will be an ARMA filter, which cannot be written as a straight convolution in this way.

**As I comment, the actual impulse response of the IFO is about 3 msec long. Provided that we deal with data trains much longer than this, we can treat it as a finite impulse response system.**

#### 4. CONCLUSIONS

As presently constructed, GRASP does not correctly produce  $h[k]$ , the interferometer displacement measurement.

**As I said earlier, there is NOTHING in GRASP that produces  $h[k]$ . And it does not make much sense to try and do this.**

It does not correctly form the transfer function that takes detector output to strain, nor does it correctly implement a convolution in the frequency domain.

**I think that these are both done correctly. If you do not agree, then I challenge you to the following: produce a graph showing the response of the instrument IFO\_DMRO channel to a 2 x 1.4 solar mass chirp, and compare it with the GRASP-produced graphs that I have included here.**

All results that depend on GRASP calibrated detector output are, consequently, suspect.

**I do not agree with this conclusion.**

Since the errors are conceptual in nature it is likely that they also appear elsewhere in GRASP wherever filtering or convolution operations are performed; however, this has not been checked.

**I have checked these operations rather carefully. I am quite willing to believe that I may have errors in GRASP, however I do not believe that this document describes any errors in GRASP.**

**Sam, on another topic, I would like to thank you for the help that you've given Joe and me in finding and correcting several conceptual errors in our stochastic background paper. In particular, I had not realized that we could not use  $\sqrt{N}$  as a termination criteria.**

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