

# NEO<sup>®</sup> S-Series Tape Libraries

## *Service Guide*



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# Preface

## Topics in Preface

- [Audience and Purpose](#)
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## Audience and Purpose

This guide is intended for system and network administrators charged with servicing or upgrading a NEO S-Series Tape Library. The instructions are intended for the trained Administrators and technicians who need physical and functional knowledge of the S-Series tape library. Administrators should be familiar with the basic concepts and tasks of network administration.

The main components are:

- Base Module
- Expansion Modules

## General Product Warnings and Cautions

### High Voltage



**WARNING:** To reduce the risk of electric shock or damage to equipment, always remove any power cords while working with the unit. If the device has more than one power cord, disconnect ALL power cords before servicing.

**WARNUNG:** Um das Risiko eines elektrischen Schlags oder Schäden am Gerät zu vermeiden, ziehen Sie stets den Netzstecker, bevor Sie an der Einheit arbeiten. Wenn das Gerät über mehr als einen Netzstecker verfügt, dann ziehen Sie ALLE Netzstecker, bevor Sie das Gerät in Betrieb nehmen.

**AVERTISSEMENT:** Pour réduire le risque de choc électrique ou endommagement de l'équipement, retirez toujours les cordons électriques en travaillant avec l'appareil. Si l'appareil a plus d'un cordon d'alimentation, débranchez tous les cordons d'alimentation avant l'entretien.

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## Heavy Units in Boxes



**WARNING:** Due to the weight of the appliance, it is recommended that at least two people be used to lift the unit out of the box to prevent injury.

**WARNUNG:** Um Verletzungen zu vermeiden, empfehlen wir aufgrund des Gewichts des Geräts, dass mindestens zwei Personen das Gerät aus der Verpackung heben.

**AVERTISSEMENT:** En raison du poids de l'appareil, il est recommandé d'utiliser deux personnes au moins pour soulever l'appareil hors de la boîte pour éviter les blessures.

## Heavy Unit Installation/Removal



**WARNING:** It is recommended that a mechanical lifter (or at least two people) be used during rack installation or removal to prevent injury.

**WARNUNG:** Um Verletzungen zu vermeiden, empfehlen wir zur Rack-Installation oder -Deinstallation die Nutzung einer mechanischen Hebehilfe (oder mindestens zwei Personen).

**AVERTISSEMENT:** Pour éviter toute blessure il est recommandé qu'un monte-charge (ou deux personnes au moins) soit utilisé lors de l'installation ou de l'enlèvement du support.

## Rack Tipping



**WARNING:** Use care during rack installation or removal to prevent accidental tipping of the rack, causing damage or personal injury.

**WARNUNG:** Seien Sie vorsichtig bei der Rack-Installation oder -Entnahme, um ein versehentliches Kippen des Racks zu vermeiden und das Rack nicht zu beschädigen bzw. sich selbst zu verletzen.

**AVERTISSEMENT:** Soyez prudent lors de l'installation ou de l'enlèvement du support afin d'empêcher le renversement accidentel de la crémaillère, pour éviter dommages et blessures.

## General Guidelines



**CAUTION:** Follow the following guidelines when installing the unit:

- Ventilation – Place the product in a location that does not interfere with proper ventilation.
- Power sources – Connect the product to a power source only of the type directed in the operating instructions or as marked on the product.
- Power cord protection – Place the AC line cord so that it is not possible to be walked on or pinched by items placed upon or against it.
- Object and liquid entry – Insure that objects do not fall onto and that liquids are not spilled into the product's enclosure.

Ventilation – Place the product in a location that does not interfere with proper ventilation.

## Electrostatic Discharge

To prevent damaging the system, be aware of the precautions you need to follow when setting up the system or handling parts. A discharge of static electricity from a finger or other conductor may damage system boards or other static-sensitive devices. This type of damage may reduce the life expectancy of the device.

**Preventing Electrostatic Damage.** To prevent electrostatic damage, observe the following precautions:

- Avoid hand contact by transporting and storing products in static-safe containers.
- Keep electrostatic-sensitive parts in their containers until they arrive at static-free workstations.
- Place parts on a grounded surface before removing them from their containers.
- Avoid touching pins, leads, or circuitry.
- Always be properly grounded when touching a static-sensitive component or assembly. See the next section.

**Grounding Methods.** There are several methods for grounding. Use one or more of the following methods when handling or installing electrostatic-sensitive parts:

- Use a wrist strap connected by a ground cord to a grounded workstation or computer chassis. Wrist straps are flexible straps with a minimum of 1 megohm ( $\pm 10$  percent) resistance in the ground cords. To provide proper ground, wear the strap snug against the skin.
- Use heel straps, toe straps, or boot straps at standing workstations. Wear the straps on both feet when standing on conductive floors or dissipating floor mats.
- Use conductive field service tools.
- Use a portable field service kit with a folding static-dissipating work mat.

If you do not have any of the suggested equipment for proper grounding, have an authorized reseller install the part. For more information on static electricity, or assistance with product installation, contact your authorized reseller.

## Product Warranty

The customer should only perform the service and repair actions on the tape library components listed in this document. Any other actions needed should only be performed by an authorized service center.

The warranty for the tape library shall not apply to failures of any unit when:

- The tape library is repaired or modified by anyone other than the manufacturer's personnel or approved agent.
- The tape library is physically abused or used in a manner that is inconsistent with the operating instructions or product specification defined by the manufacturer.
- The tape library fails because of accident, misuse, abuse, neglect, mishandling, misapplication, alteration, faulty installation, modification, or service by anyone other than the factory service center or its approved agent.
- The tape library is repaired by anyone, including an approved agent, in a manner that is contrary to the maintenance or installation instructions supplied by the manufacturer.
- The manufacturer's serial number tag is removed.
- The tape library is damaged because of improper packaging on return.






**CAUTION:** Warranty becomes immediately void in the event of unauthorized repairs or modifications of any kind.

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## Conventions

This document exercises several alerts and typographical conventions.

### Alerts

| Convention   | Description & Usage  |
|--|--|
| <b>NOTE:</b> Text  | A <b>Note</b> indicates neutral or positive information that emphasizes or supplements important points of the main text. A note supplies information that may apply only in special cases, for example, memory limitations or details that apply to specific program versions.  |
|  <b>IMPORTANT</b>                 | An <b>Important</b> note is a type of note that provides information essential to the completion of a task or that can impact the product and its function.  |
|  <b>CAUTION</b>                   | A <b>Caution</b> contains information that the user needs to know to avoid damaging or permanently deleting data or causing physical damage to the hardware or system.   |
|  <b>WARNING</b><br><b>WARNUNG</b> | A <b>Warning</b> contains information concerning personal safety. Failure to follow directions in the warning could result in bodily harm or death.<br>Eine <i>Warnung</i> enthält Informationen zur persönlichen Sicherheit. Das Nichtbeachten der Anweisungen in der Warnung kann zu Verletzungen oder zum Tod führen. |
| <b>AVERTISSEMENT</b>   | Un Canadien avertissement comme celui-ci contient des informations relatives à la sécurité personnelle. Ignorer les instructions dans l'avertissement peut entraîner des lésions corporelles ou la mort.   |

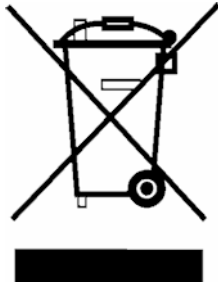
### Typographical Conventions

| Convention              | Description & Usage  |
|-------------------------|--|
| <b>Button_name</b>      | Words in this special boldface font indicate command buttons found in the <b>Remote Management Interface</b> (RMI) or <b>Operator Control Panel</b> (OCP).   |
| Ctrl-Alt-R              | Denotes the keys that you press simultaneously. In this example, hold down the <b>Ctrl</b> and <b>Alt</b> keys and press the <b>R</b> key.   |
| Menu Flow Indicator (>) | Words with a greater than sign between them indicate the flow of actions to accomplish a task. For example, <b>Setup &gt; Passwords &gt; User</b> indicates that you should press the <b>Setup</b> button, then the <b>Password</b> button, and finally the <b>User</b> button to accomplish a task. |
| <i>Courier Italic</i>   | Used to exemplify a variable for which you must substitute a value.  |
| <b>Courier Bold</b>     | Represents commands or text in a command-line interface (CLI).   |

Information contained in this guide has been reviewed for accuracy, but not for product warranty because of the various environments, operating systems, or settings involved. Information and specifications may change without notice.

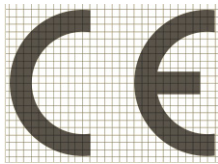
## Regulatory Information

### Disposal of Waste Equipment by Users in Private Households in the European Union and Norway



This symbol on the product or on its packaging indicates that this product must not be disposed of with your other household waste. Instead, it is your responsibility to dispose of your equipment by handling it over to a designated collection point for the recycling of waste electrical and electronic equipment. The separate collection and recycling of your waste equipment at this time of disposal will help to conserve natural resources and ensure that it is recycled in a manner that protects human health and the environment. For more information about where you can drop off your waste equipment for recycling, please contact your local city office, your household waste disposal service, or the shop where you purchased the product.

### CE Mark



The CE mark is a mandatory conformity mark on many products placed on the single market in the European Economic Area (EEA). The CE marking certifies that a product has met EU consumer safety, health or environmental requirements.

### CCL Mark



CSA C22-2 No. 60950-1 – Electrical safety – UL 60950-1  
68475

### FCC (United States)



The computer equipment described in this manual generates and uses radio frequency (RF) energy. If the equipment is not installed and operated in strict accordance with the manufacturer's instructions, interference to radio and television reception might result.

This equipment complies with Part 15 of the FCC Rules. Operation is subject to the following conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Part 15, Class A, of the FCC Rules, is designed to provide reasonable protection against radio and television interference in a residential installation. Although the equipment has been tested and found to comply with the allowed RF emission limits, as specified in the above-cited Rules, there is no guarantee that interference will not occur in a particular installation. Interference can be determined by turning the equipment off and on while monitoring radio or television reception. The user may be able to eliminate any interference by implementing one or more of the following measures:

- Reorient the affected device and/or its receiving antenna.
- Increase the distance between the affected device and the computer equipment.
- Plug the computer and its peripherals into a different branch circuit from that used by the affected device.
- If necessary, consult an experienced radio/television technician for additional suggestions.

## Canadian Verification

This Class A digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations (ICES-003, Class A).

## Product Documentation

NEO product documentation and additional literature are available online at the Overland-Tandberg Knowledge Base:

<https://www.overlandtandberg.com/knowledgebase/>

Use the these options to access the information you need:

- Product Type = Library and Tape
- Product Family = NEO S-Series
- Model = (select your model)
- Document Type = (select your document)

## Firmware Updates

The latest release of the NEO S-Series firmware can be obtained from the *Downloads and Resources* page at the Overland Storage website:

<http://support.overlandstorage.com/support/neo-series.htm>

Follow the appropriate instructions to download the **latest** software file.

For additional assistance, search at:

<https://support.overlandstorage.com/touchpoint/logIn/default.aspx>

## Technical Support

You can get additional technical support information on the [Contact Us](#) web page at:

<https://www.overlandstorage.com/company/contact-us/index.aspx>

For a complete list of support types, levels, and times, visit our website at:

[http://support.overlandstorage.com/support/overland\\_care.html](http://support.overlandstorage.com/support/overland_care.html)





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## Possible Tools Needed

- #2 Phillips screwdriver – securing or removing the round-hole rack adapter bracket, securing retention inserts in square-hole racks.
- Small Flat Head screwdriver or Torx tool – retracting the locking screen when moving a library cover, using the magazine manual release.
- T10 Torx tool – removing drive bay covers.
- Small Flat Head screwdriver – removing a magazine access door.
- Clip Nut installation tool – inserting or removing clip nuts in square-hole racks while installing or removing rack rails.

## Electrostatic Discharge

To prevent damaging the system, be aware of the precautions you need to follow when setting up the system or handling parts. A discharge of static electricity from a finger or other conductor may damage system boards or other static-sensitive devices. This type of damage may reduce the life expectancy of the device.

To prevent electrostatic damage, observe the following precautions:

- Avoid hand contact by transporting and storing products in static-safe containers.
- Keep electrostatic-sensitive parts in their containers until they arrive at static-free workstations.
- Place parts on a grounded surface before removing them from their containers.
- Avoid touching pins, leads, or circuitry.
- Always be properly grounded when touching a static-sensitive component or assembly. See the next section.

## Grounding Methods

There are several methods for grounding. Use one or more of the following methods when handling or installing electrostatic-sensitive parts:

- Use a wrist strap connected by a ground cord to a grounded workstation or computer chassis. Wrist straps are flexible straps with a minimum of 1 megohm ( $\pm 10$  percent) resistance in the ground cords. To provide proper ground, wear the strap snug against the skin.
- Use heel straps, toe straps, or boot straps at standing workstations. Wear the straps on both feet when standing on conductive floors or dissipating floor mats.
- Use conductive field service tools.

- Use a portable field service kit with a folding static-dissipating work mat.

If you do not have any of the suggested equipment for proper grounding, have an authorized reseller install the part.

**NOTE:** For more information on static electricity, or assistance with product installation, contact your authorized reseller.

## Identify a Failed Component


Using the Operator Control Panel (OCP) or Remote Management Interface (RMI):

1. Activate the UID (Unit Identification) LEDs from the **Maintenance > UID LED Control** screen or page. This illuminates the blue LED on the front and rear of the Base Module to identify the library containing the failed component.
2. Identify the module within the library that contains the failed component:
  - a. In the upper left corner of the **Home** screen, locate the module that indicates an error.
  - b. Click or tap the module status area for information on the failed component.

**NOTE:** If dealing with a failed drive power board, there are two drive power boards in each module. The screen indicates whether the left or right drive power board (as seen from the rear of the library) has failed. On the failed board itself, the amber LED may be illuminated and visible through the grating.

## Library Troubleshooting

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 **CAUTION:** The library is designed to operate when installed in a rack using the rack rail kit. Operating the library without installing it in the rails, such as on a table or rack shelf, could result in library errors. Placing any weight on top of the library might also cause errors.

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This chapter provides information for verifying correct installation and troubleshooting the library.

### Topics in Library Troubleshooting:

- [Troubleshooting Table](#)
- [Fibre Channel Troubleshooting](#)
- [SAS Troubleshooting](#)
- [Remove Stuck Tape Cartridges](#)
- [Emergency Magazine Release](#)
- [Upgrade the Library Firmware](#)
- [General Diagnostic Tests](#)

## Troubleshooting Table

| Problem  | Solution  |
|--|---|
| <b>Power</b>   |   |
| Library does not power up.                                       | <ul style="list-style-type: none"> <li>• Check all power cord connections.</li> <li>• Make sure the power switch on the front panel is in the &lt;ON&gt; position.</li> <li>• Make sure there is power to the outlet. Try another working outlet.</li> <li>• Replace the power cord.</li> <li>• Contact your service representative.</li> </ul> |
| No display messages appear.                                      | <ul style="list-style-type: none"> <li>• Make sure the power cord is connected.</li> <li>• Make sure the power switch is on.</li> <li>• Power cycle the library.</li> <li>• Download the library firmware.</li> <li>• Contact your service representative.</li> </ul>   |
| <b>Errors Displayed on Operator Control Panel</b>                |   |
| Exclamation mark (!) in library operator panel inventory display | Export the tape cartridge marked with the exclamation mark (!). The tape cartridge is either damaged, incompatible with the tape drive, or the wrong type for the attempted operation.  |

| Problem  | Solution  |
|--|---|
| There is an error code on the LCD              | Look up the error code, try to resolve the failure, and power cycle.<br>See <a href="#">Chapter 4, "Event Codes and Acronyms."</a>  |
| <b>Performance</b>                             |   |
| Poor throughput performance                    | <ul style="list-style-type: none"> <li>• Try a new tape. A marginal tape can cause performance problems due to bad spots on the tape requiring retries.</li> <li>• Backing up data that compresses poorly or is already compressed will lower performance.</li> <li>• Check the size of the files. Small file size can impact performance.</li> <li>• Confirm that the backup application is utilizing block sizes of at least 32KB, preferably 64KB. Refer to the backup application documentation for details.</li> <li>• Check the network bandwidth from the host computer. If you are backing up data over a network, consider comparing to a local-only backup.</li> <li>• Make sure the backup server has enough memory to handle the bandwidth of the backup or restore.</li> <li>• Clean the tape drive with OCP or RMI.</li> </ul>  |
| <b>Cleaning</b>                                |   |
| Cannot load the cleaning cartridge             | <ul style="list-style-type: none"> <li>• Make sure you are using an Ultrium universal cleaning cartridge.</li> <li>• Contact your service representative.</li> </ul>  |
| <b>Media</b>                                   |   |
| Cleaning or data tape incompatible with drive. | Cleaning or data tape incompatible with drive.  |
| Cannot write to or read from tape.             | <ul style="list-style-type: none"> <li>• Make sure that the tape is write enabled (move the write-protect switch to the enabled position).</li> <li>• Make sure you have the appropriate data tape for your library model.</li> <li>• Make sure you are using an Ultrium tape that has not been degaussed. Do not degauss Ultrium tapes.</li> <li>• Make sure that the tape has not been exposed to harsh environmental or electrical conditions and is not physically damaged in any way.</li> <li>• Many backup applications do not read or write to tapes that were created using a different backup application. In this case, perform an erase, format, or label operation on the tape.</li> <li>• Make sure you understand any data protection or overwrite protection schemes that your backup application may be using, which could prevent you from writing to a given tape.</li> <li>• Retry the operation with a different, known good tape.</li> <li>• Clean the tape drive with OCP or RMI.</li> </ul> |
| <b>&lt;Media Attention&gt; LED issues</b>      |   |
| Contamination by loose debris.                 | Avoid contamination by ensuring that the library is installed in a clean, contamination-free environment. Tapes should be stored vertically in their plastic cases. Continue cleaning the tape drive as needed.   |
| Non-acclimated media.                          | A tape should be acclimated for at least 24 hours before being used, particularly if it has been stored at a substantially different temperature or level of humidity than the library.   |
| Tape cartridge is incompatible.                | Use only tapes that are compatible with the tape drive type.  |
| Expired cleaning cartridge.                    | Make sure you are using an Ultrium universal cleaning tape. (max. 50 cleans)  |

| Problem                             | Solution   |
|-------------------------------------|--|
| Bad/defective/contaminated media.   | <p>If the &lt;Media Attention&gt; LED is cleared and –although the tape drive has been cleaned – immediately re-displays each time a particular tape is reloaded that tape should be suspected as being defective.</p> <ul style="list-style-type: none"> <li>• Export the tape and load a known good tape. In some cases, a tape can be worn out, have a defective tape memory, or have been formatted as a Firmware Upgrade Cartridge.</li> <li>• Any tape that is suspected of being defective or contaminated should NOT be reused in any drive.</li> </ul>  |
| <b>Tape cartridge movement</b>      |  |
| Tape cartridge stuck in tape drive. | <ul style="list-style-type: none"> <li>• Power cycle the library, allow it to complete initialization, which in rare cases can take as long as 10 minutes, and then retry unloading the tape using the library operator control panel.</li> <li>• Allow the tape drive to complete all operations. This may take as long as ten minutes if you reset or cycle power up the library while the cartridge is positioned at the physical end of the media.</li> <li>• Make sure that the backup software is not reserving the slot or preventing the tape drive from ejecting the tape. The backup software needs to cancel the reservation and any hold it has on the tape drive. Temporarily disconnecting the library from the host server and power cycling eliminates the host and its software as a problem source.</li> <li>• Contact your service representative.</li> </ul> |
| Tape stuck in storage slot.         | See <a href="#">Remove Stuck Tape Cartridges</a> .   |

## Fibre Channel Troubleshooting

Use the **Status > Drive Status** screen to check the link connection for your tape drive.

If the screen shows **Logged Out**:

- Verify that the correct Fibre speed is selected or is set to **Automatic**. If you are unsure of the speed of the HBA or switch that the drive is connected to, try **Automatic**.
- Check that the correct port type is selected. **Loop** requires additional configuration. If you are unsure of the correct port type, try **Automatic**.

If the screen shows **No Link**, the **Speed Status** is “–”, and the Link LED on the back of the drive is OFF:

- The speed is probably set incorrectly. Try setting the speed to **Automatic**.
- If there are still issues, change the port type to **Auto Detect**.

If the screen shows **No Light**:

- The cable is not plugged in correctly. Check that it is connected correctly to Port A of the tape drive.
- The cable is damaged. FC cables are delicate. If the cable has been bent or twisted sharply, it might be broken and must be replaced.

If the screen shows **ALPA Conflict**:

- There might be a conflict with the ALPA address on Loop ports. Select **Soft** for the Loop mode to allow the system to select an available address each time the tape drive connects to the FC fabric.

- If your server configuration does not support changing addresses, try using the **Hard Auto-Select** option for the Loop mode. This option allows the system to select an available address when it first connects, and then retain that address for future connections.

## SAS Troubleshooting

Frequent causes of SAS detection issues:

- Improper SAS cable connections.
- Application software configuration errors.
- An incorrectly configured operating system.

If the application software or operating system does not communicate with the library after installation, determine the extent of the detection problem:

- Does the application software detect the tape drive?
- Does the application software detect the library?
- Does the operating system detect the tape drive?
- Does the operating system detect the library?
- Does the operating system detect the library, but list it as a generic device?

Based on the extent of the detection problem, check the following:

- If neither the application software or operating system detects the tape drive, or they do not detect both the tape drive and the library:
  - Verify that all SAS cables are securely connected on both ends.  
If the mini-SAS connectors that connect to the tape drive and some HBAs will not plug in, check the key. The mini-SAS connector on the tape drive is keyed for location four, which is the standard location for end devices. If the connector on the cable is keyed in a different location, not only will the connector not plug in, but the cable probably will not work.
  - Check the length and integrity of your SAS cabling.  
For reliable operation, do not use a SAS cable longer than six meters. Do not use a cable adapter or converters between the HBA and the library.
  - Check the SAS connectors for damage or debris.
  - Verify that your HBA is supported by the host computer and qualified with the library.
  - Verify that your HBA has the latest firmware.
- If the application software or operating system detects the tape drive, but not the library:
  - Verify that multiple LUN support is enabled on the HBA.  
The library uses two Logical Unit Numbers (LUNs) to control the tape drive (LUN 0) and robotics (LUN 1). The library requires an HBA with multiple LUN support, and multiple LUN support must be enabled on the host computer. When multiple LUN support is not enabled, the host computer can see the tape drive, but not the library.

**NOTE:** Many RAID or array controllers do not provide multiple LUN support.

- If the application software or operating system does not detect any devices on the HBA:



- Verify that the SAS host adapter is installed correctly.  
For installation and troubleshooting instructions, see the manual that came with your host adapter. Pay particular attention to any steps describing configuration settings. Ensure that the host adapter is properly seated in the motherboard slot and that the operating system correctly detects the host adapter.
- Verify that the proper device driver is installed for the SAS host adapter.
- If the library is detected by the operating system, but not by the application software, verify that the backup application is installed correctly.  
For instructions verifying proper installation, see the backup application documentation. Some backup software packages require an additional module to communicate with the robotics.
- If the library is detected by the operating system, but is listed as an unknown or generic device, make sure that the proper device driver, if applicable, is installed for the device. Check your application provider website for the latest drivers and patches.

**NOTE:** Many backup applications use their own drivers. Before installing a driver, make sure that it is not in conflict with the application software.

## Remove Stuck Tape Cartridges



**CAUTION:** When the library is moved, any tape cartridge can become dislodged from the magazines and damage the tape cartridges left in the library and library robotic. To avoid damaging the libraries, remove the tape cartridges before moving the libraries.

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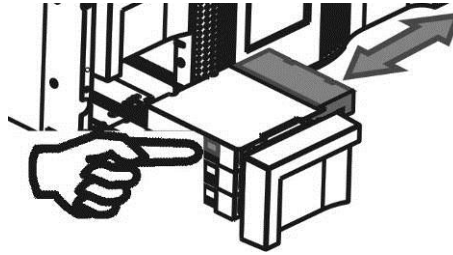
Indications for a stuck tape cartridge are:

- Cartridge cannot be removed via OCP or RMI.
- Robotic movement blocked when pulling a cartridge (see [Chapter 4, “Event Codes and Acronyms”](#)).
- Strange noises of the robotic; no read/write operation possible in the drive.

To remove a stuck tape cartridge:

1. Unlock the **magazine** (with or without mailslot):
  - If the OCP or RMI is working, unlock the magazine as described in [Unlock a Magazine with OCP or RMI on page 28](#).
  - If the procedure fails or if the magazine needs to be opened while the power is off, follow the procedure in [Remove the Magazine Manually on page 29](#).
2. If applicable, pull just the **mail slot** out to access the tape cartridge. Otherwise, supporting the magazine’s bottom, remove the entire magazine.

3. To remove the tape cartridge from the mail slot area:  
In the following figure, a triple mailslot is shown as an example.



- a. Use the **finger holes** to push the tape out of the mail slot.
  - b. If required, insert a **new tape** cartridge.
  - c. Repeat this process until **all stuck tapes** are removed.
4. Push the **mail slot** or insert the **magazine** back into the library.

## Emergency Magazine Release



**CAUTION:** Whenever possible, use the OCP or RMI to release the magazines. Use the manual release only in the case of emergency.

If you cannot remove the complete magazines via the OCP or RMI, see [Remove the Magazine Manually on page 29](#).

## Upgrade the Library Firmware

The firmware version for the libraries must be compatible with all implemented devices. Verify that the library has the latest released version of firmware loaded.

**NOTE:** After upgrading the library firmware, the library system restarts automatically.

To upgrade the library firmware, see [Update the System Firmware on page 25](#).

## General Diagnostic Tests

Available tests to determine the health of the library:

### System Test

The System Test is a general test to verify the usability and reliability of the library. The duration is depending on the test cycles defined.

To run the system test, navigate with RMI or OCP:

- RMI screen: **Service > General Diagnostic > System Test**
- OCP screen: **Main Menu > Service > Service Library > Run Tests > System Test**

## Slot-to-Slot Test

The Slot-to-Slot test shuffles the tapes between the slots to exercise the robotic. At the end of the test the tapes are not returned to their original slots.

To run the Slot-to-Slot test, navigate with RMI or OCP:

- RMI screen: **Service > General Diagnostic > Slot to Slot**
- OCP screen: **Main Menu > Service > Service Library > Run Tests > Slot to Slot Test**

## Library Verify Test

**NOTE:** The library will remove any tape from the tape drives and go offline when running the test. Verify that any applications using the library have completed before starting the test.

The Library verify test is a diagnostic routine called Library Health Check (LHC).

This routine allows:

- to functionally test all library and drive hardware with the exception of external interfaces (SCSI).
- to verify a newly installed machine.
- to verify repair actions.

To run Library verify test, navigate with OCP:

OCP screen: **Main Menu > Service > Service Library > Library Verify**

## Operations During the Library Health Check (LHC)

1. The user starts the test from the master library OCP. The administrator password is required. The test requires user interaction and can only be run from the OCP.
2. The master library performs a self-test, verifies that it can communicate with the tape drives and the library extender, and then the lower library performs a self-test.
3. The library returns any tapes from the tape drives to their home slots. If the home slot for a tape is unknown, the library will move the tape to the mail slot and prompt the user to remove it.
4. The library prompts the user to enter the number of cycles to run the test. The library runs up to 10 cycles.
5. The library opens the mail slot in the extended library, which will generally be in the lower library, and prompts the user to insert a scratch tape.
6. The user inserts a scratch tape into the lowest-numbered mail slot. If no mail slots are enabled or the user closes the mail slot without inserting a tape into the lowest-numbered mail slot, the library will perform a shortened version of the test, skipping [Step 7](#).
7. The library loads the scratch tape into the first tape drive, unloads the scratch tape from the tape drive, and returns the scratch tape to the mail slot. If the user selected to test all of the tape drives, the library will load the scratch tape into each tape drive before returning it to the mail slot.
8. The library moves the tape from the four top-row corner slots of both libraries to the tape drive load point and then returns the tape to its slot. If none of the top-row corner slot positions of either library contains a tape, the test stops and the library displays an error message.

9. If additional cycles remain to be run, the test will return to [Step 7](#) if there is a tape in the mail slot or [Step 8](#) if there is not a tape in the mail slot.
10. At the conclusion of the test, the library pops open the mail slot and waits for the user to remove the scratch tape.
11. The library displays the test completion status, including any recoveries or errors that may have occurred.

# 3

## Replacing Parts

This chapter provides instructions for servicing the NEO S-Series Tape Library. Any removed parts should be returned to Overland-Tandberg for service.

### Topics in Replacing Parts:

- [Add or Replace a Tape Drive](#)
- [Replace the Library Controller](#)
- [Add or Replace a Power Supply](#)
- [Replace the Base Chassis](#)

## Add or Replace a Tape Drive

Only individuals who are informed about the procedures and risks should replace or upgrade this tape drive assembly. Read all troubleshooting documentation and procedures before proceeding with repair or upgrade procedures.



**WARNING:** To reduce the risk of electric shock or damage to equipment, always remove any power cords while working with the library.

**WARNUNG:** Um das Risiko eines elektrischen Schlags oder Schäden am Gerät zu vermeiden, ziehen Sie stets den Netzstecker, bevor Sie an der Einheit arbeiten.

**AVERTISSEMENT:** Pour réduire le risque de choc électrique ou endommagement de l'équipement, retirez toujours les cordons électriques en travaillant avec l'appareil.

---



**CAUTION:** While working with the library, observe standard Electrostatic Discharge (ESD) precautions to prevent damage to micro-circuitry or static-sensitive devices.

---



**WARNING:** Hazardous moving parts exist inside this product. Do not insert tools or any portion of your body into the drive bay openings.

**WARNUNG:** Im Inneren dieses Produktes befinden sich gefährliche bewegliche Teile. Führen Sie keine Werkzeuge oder Körperteile in die Öffnungen der Laufwerksschächte ein.

**AVERTISSEMENT:** Ce produit comporte des pièces mobiles dangereuses à l'intérieur. Veuillez ne pas insérer d'outils ou une partie du corps dans les ouvertures de chargeur de lecteur.

---

To replace a tape drive:

- Make sure the tape cartridge has been removed from the tape drive. Use the operator control panel (OCP) or the remote management interface (RMI) to move the cartridge to a storage slot or mailslot.
- If you are replacing the tape drive in a single drive library or the master drive in a multi-drive library, verify that backups are not occurring on the drive you are replacing.

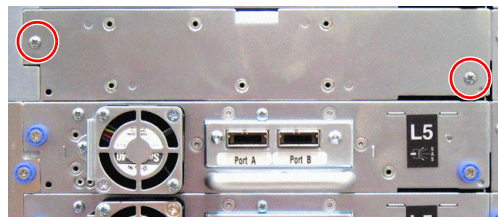
- If you determine that backups are occurring on the master drive, verify that the autoloader or library can not be accessed through this drive while the drive is being replaced.

The tape drives are hot-swappable.

## Add a New Tape Drive

**NOTE:** If you are replacing an existing tape drive, proceed with [Replace an Existing Tape Drive on page 23](#).

1. Verify the **location** for the tape drive.
  - If this is the first tape drive, install it in the **bottom drive bay**.
  - Otherwise, install the new drive in the **next higher** empty drive bay.
2. Using a Phillips screwdriver, **remove** the two screws securing the **drive bay cover**.



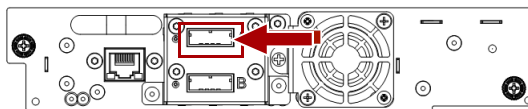
3. While supporting the bottom of the **new tape drive assembly**, slowly insert the drive into the drive bay until it is flush with the back panel of the device.



**CAUTION:** Support the bottom of the tape drive when removing it to avoid damaging any of the internal connections.

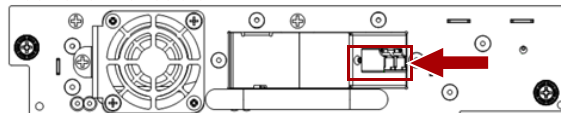
4. Finger-tighten the captive **thumbscrews** until the tape drive is secure.
5. Attach the **SAS** or **FC cables** to the connectors on the tape drive.
  - If you are installing an **SAS fanout cable**, attach one **mini-SAS connector** into the connector on the tape drive and use the **other ends** to connect tape drives (or coil and secure them to the rack to minimize stress on the connectors).

**SAS Cable**



- If you are installing an **FC cable**, connect the **FC cable connector** to the connector on the tape drive and then configure the **FC interface**.

**Fiber Channel Cable**



**NOTE:** Overland recommends the default settings of **Port Speed: Automatic** and **Port Type: Auto Detect** so the tape drive will use the appropriate configuration.

6. Use the OCP or RMI to **power on** the new tape drive.

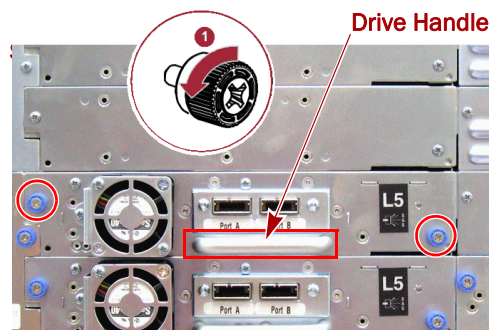
## Replace an Existing Tape Drive

To replace an existing tape drive:

1. Use the OCP or RMI to **power off** the tape drive.




2. Verify that the **LED** of the tape drive assembly being replaced is OFF, then label and remove the FC or SAS cables from the tape drive.
3. Loosen the blue captive **thumbscrews** on the tape drive being replaced.



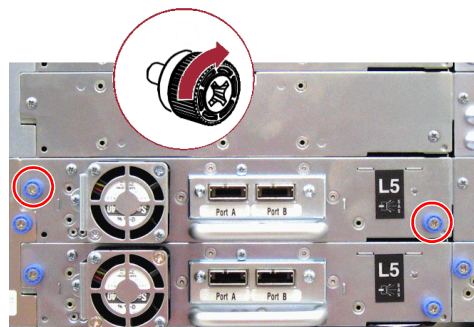
4. While supporting the drive bottom, use the tape drive handle and pull straight back to remove the **old tape drive** from the library.

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 **CAUTION:** Support the bottom of the tape drive when removing it to avoid damaging any of the internal connections.

---

5. While supporting the drive bottom, slowly insert the **new tape drive** into the drive bay until it is flush with the back panel of the device.
6. Finger-tighten the blue captive **thumbscrews** to secure the tape drive.



7. Reconnect the **FC or SAS cables** to the tape drive.
8. Use the OCP or RMI to **power on** the tape drive.

## Replace the Library Controller



**WARNING:** To reduce the risk of electric shock or damage to equipment, always remove any power cords while working with the library.

**WARNUNG:** Um das Risiko eines elektrischen Schlags oder Schäden am Gerät zu vermeiden, ziehen Sie stets den Netzstecker, bevor Sie an der Einheit arbeiten.

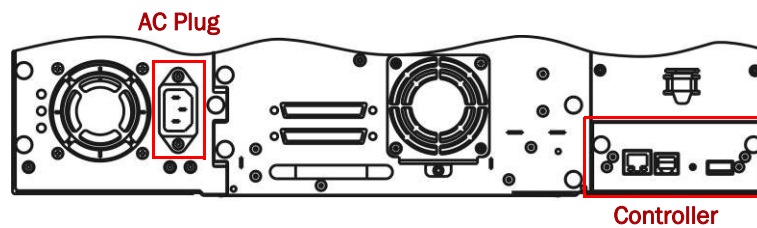
**AVERTISSEMENT:** Pour réduire le risque de choc électrique ou endommagement de l'équipement, retirez toujours les cordons électriques en travaillant avec l'appareil.



**CAUTION:** While working with the library, observe standard Electrostatic Discharge (ESD) precautions to prevent damage to micro-circuitry or static-sensitive devices.

### Prepare the Unit

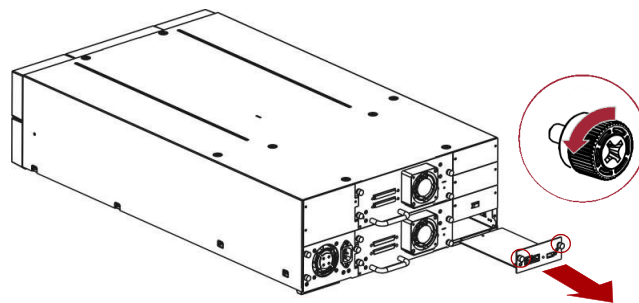
1. Verify that all host processes are **idle**.
2. Power off the library by depressing the **power button** on the front panel.
3. From the module containing the failed controller, unplug the **AC power cables**.



4. Remove the **Ethernet cables** and any **USB device** from the library controller being replaced.

### Remove the Library Controller

1. Loosen the **two blue captive thumbscrews** on the controller.
2. Using the thumbscrews, slowly remove the **controller** from the library.



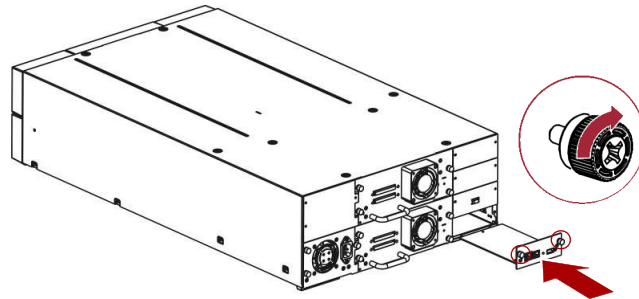
3. Set aside the old **controller** for return to Overland.

### Install the Library Controller

1. Position the new controller on the **alignment rails**.



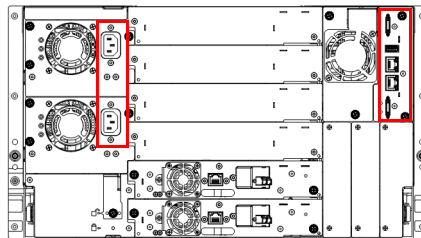
- Slide the **controller** slowly into the library until it is flush with the back panel of the library.



- Finger-tighten** the blue captive thumbscrews to secure it to the library.

### Reassemble the Unit

- Reconnect the **Ethernet cables** and any **USB device**.
- Plug in the **AC power cables**.



- Press the Base Module **power button** for one to two seconds to power on the library. The **green LED** is shown when the library completes its Power-on Self-test (POST).
- Confirm that the **library** recognizes the **new controller** by selecting **Status > Library Status**.  
Check the event log to make sure any library controller events have cleared.



**IMPORTANT:** If you are asked whether or not to retain the serial number, always select **Yes**.

- Use the RMI or OCP to verify that the library controller has the current **firmware**.  
If the firmware needs to be updated, continue with [Update the System Firmware](#).

### Update the System Firmware

- Download the latest firmware from:  
[ftp://ftp.overlandstorage.com/Firmware/Neo\\_Series/NeoS/](ftp://ftp.overlandstorage.com/Firmware/Neo_Series/NeoS/)
- Select the **folder** for the model chassis being replaced.
- If necessary, select the **drive type folder**.
- Load the firmware file (FBI) on a **USB stick**.
- Attach the **USB stick** to the port on the back panel of the new chassis.

6. Use the OCP or RMI to upload the firmware upgrade.
  - From OCP, select **Main Menu > Service > Service Library > FW Upgrade by USB**.
  - From RMI, select **Service > Firmware > Upgrade Library Firmware > Upgrade**.
7. Click **Browse** to select the firmware file.
8. Click **Upload**.
9. Once the update is complete, **verify** the firmware version.

## Add or Replace a Power Supply



**WARNING:** To reduce the risk of electric shock or damage to equipment, always remove any power cords while working with the library.

**WARNUNG:** Um das Risiko eines elektrischen Schlags oder Schäden am Gerät zu vermeiden, ziehen Sie stets den Netzstecker, bevor Sie an der Einheit arbeiten.

**AVERTISSEMENT:** Pour réduire le risque de choc électrique ou endommagement de l'équipement, retirez toujours les cordons électriques en travaillant avec l'appareil.



**CAUTION:** While working with the library, observe standard Electrostatic Discharge (ESD) precautions to prevent damage to micro-circuitry or static-sensitive devices.

The power supply unit (PSU) bays are located at the rear of the library.

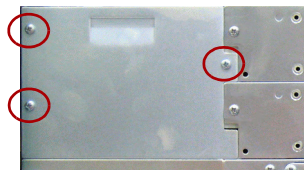
- 2U library – There is only one power supply bay.
- 4U library – There are two power supply bays. Always install the first power supply in the lower bay.

The unit can run with one power supply. If redundant a power supply is desired for fault tolerance, install a second power supply in the bay directly above the existing power supply.

### Add a Redundant Power Supply

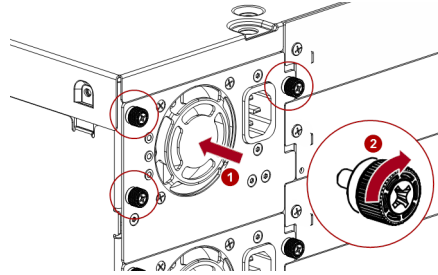
**NOTE:** If you are replacing an existing power Supply, proceed with [Replace a Power Supply on page 27](#).

1. Verify that all host processes are **idle** and power off the library by depressing the **power button** on the front panel.
2. Using a Phillips screwdriver, remove the **three screws** securing the cover plate on the upper power supply bay.



Set the **cover plate and screws** aside, saving them for possible future use.

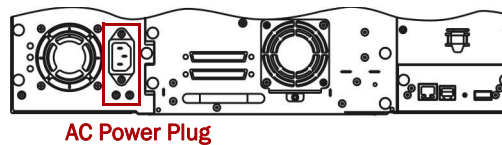
3. Position the **new power supply** onto the alignment rails in the bay.
4. Slide the **power supply** into the library until it is flush with the back panel of the library.



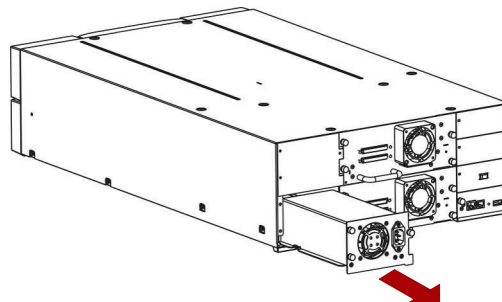
5. Finger-tighten the **blue captive thumbscrews** to secure the power supply.
6. Attach the supplied **AC power cord** to the new power supply.
7. Plug the power cord into a **different AC circuit** than the other PSU to operate in failover mode.
8. Press the **power button** to power the library back on.

### Replace a Power Supply

1. Use the PSU LEDs to locate the **failed power supply** on the rear of the library.
2. Verify that all host processes are **idle** and power off the library by depressing the **power button** on the front panel.
3. Unplug the **AC power cord** from the PSU being replaced.

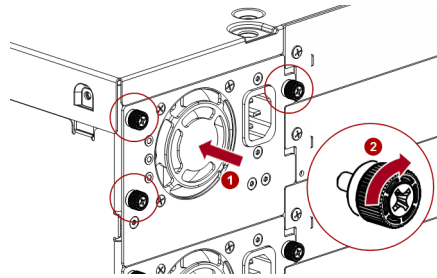


4. Remove the **old PSU**:
  - a. Finger-loosen the **three blue captive thumbscrews** on the power supply.
  - b. Using the thumbscrews, slowly pull the **power supply** approximately 4 inches (10 cm) out of the library.
  - c. While using one hand to support the bottom of the power supply, completely **remove** the **power supply** from the module and set aside.



5. Install the **replacement PSU**:
  - a. Position the **new power supply** onto the alignment rails in the bay.

- b. Slide the **power supply** into the library (1) until it is flush with the back panel of the library.



- c. Finger-tighten the **blue captive thumbscrews** (2) to secure the power supply.
- d. Attach the supplied **AC power cord** to the new power supply and plug it into the same AC circuit previously used.
6. Press the Base Module **power button** for one to two seconds to power on the library.

## Replace a Magazine



**WARNING:** To reduce the risk of electric shock or damage to equipment, always remove any power cords while working with the library.

**WARNUNG:** Um das Risiko eines elektrischen Schlags oder Schäden am Gerät zu vermeiden, ziehen Sie stets den Netzstecker, bevor Sie an der Einheit arbeiten.

**AVERTISSEMENT:** Pour réduire le risque de choc électrique ou endommagement de l'équipement, retirez toujours les cordons électriques en travaillant avec l'appareil.



**CAUTION:** While working with the library, observe standard Electrostatic Discharge (ESD) precautions to prevent damage to micro-circuitry or static-sensitive devices.

## Unlock a Magazine with OCP or RMI

**NOTE:** As a best practice, perform this procedure while applications are idle. While the magazine is extended, the library robotic assembly cannot move media.

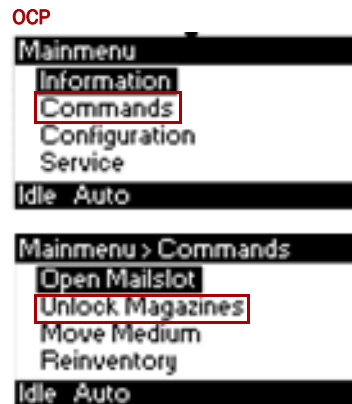
Unlock the magazine using the OCP or RMI. Only one magazine or mailslot can be open at a time.

**NOTE:** If these methods fail, or if a magazine needs to be removed when the power to the device is off, you can release the magazine manually. See [Remove the Magazine Manually on page 29](#).

1. Open the **magazine access door**.
2. Log in as an administrator in **OCP** or **RMI**.
3. Unlock the magazine.

**NOTE:** If not removed, the magazine and mailslot will relock after 30 seconds.

- In OCP, from the **Main Menu** screen, select **Commands > Unlock Magazines**.



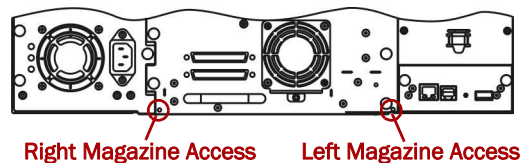
- In RMI, select **Operations > Magazines**, then select the magazine from the drop-down menu.



## Remove the Magazine Manually

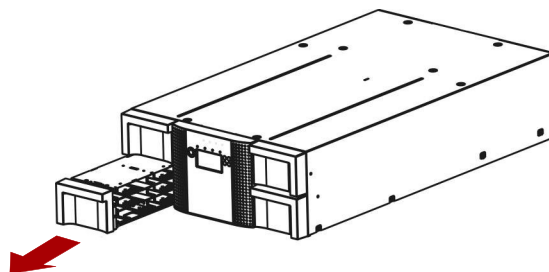
**NOTE:** This procedure requires two people.

1. Press the **power button** on the front bezel to power down the library.
2. Push a **small metal pin** or a **straightened paper clip** into the magazine access hole.



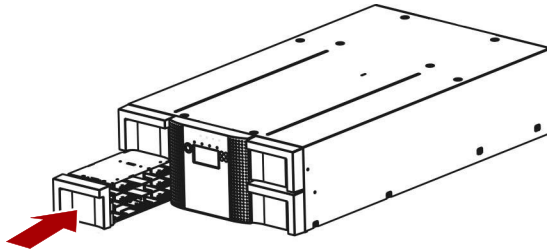
**NOTE:** For the 4U, all magazines on one side are released via the access hole and should be removed at the same time.

3. While one person presses and holds the **pin** or **paper clip** in the hole, the second person, supporting the **magazine** underneath, gently pulls it out of the unit.
4. Remove the **tape cartridges**, noting their locations within the magazine.



## Install New Magazine

1. Load the **tape cartridges** into the new magazine in the same locations that they were in the old magazine.
2. Supporting the magazine underneath, position the **new magazine rails** onto the alignment rails.



3. Using the handle, push the **magazine** slowly into the library until the magazine release latch snaps into place.  
The magazine automatically locks into place when it is correctly installed.

## Replace the Base Chassis



**WARNING:** To reduce the risk of electric shock or damage to equipment, always remove any power cords while working with the library.

**WARNUNG:** Um das Risiko eines elektrischen Schlags oder Schäden am Gerät zu vermeiden, ziehen Sie stets den Netzstecker, bevor Sie an der Einheit arbeiten.

**AVERTISSEMENT:** Pour réduire le risque de choc électrique ou endommagement de l'équipement, retirez toujours les cordons électriques en travaillant avec l'appareil.



**CAUTION:** While working with the library, observe standard Electrostatic Discharge (ESD) precautions to prevent damage to micro-circuitry or static-sensitive devices.

## Prepare the Unit



**CAUTION:** In the NEOs library, do not replace both the library controller and the chassis at the same time as the serial numbers for both cannot be updated when both are replaced simultaneously. If you receive a new library controller and chassis for the same unit, first install the new library controller in the old chassis as directed in the *Spare Library Controller Replacement Instructions*, then follow these provided instructions to replace the chassis.

The following items are included in the new chassis and should not be removed from the old chassis:

- Center bezel with the OCP
- Magazine access doors
- Robotic assembly
- Spooling mechanism

## Remove Components

1. Remove all tape magazines to reduce the unit's weight.
  - If the OCP or RMI is working, remove the magazine as described in [Unlock a Magazine with OCP or RMI on page 28](#).
  - If the procedure fails or if the magazine needs to be opened while the power is off, follow the procedure in [Remove the Magazine Manually on page 29](#).
2. If needed, power down the library by pressing the **power button** on the front panel.
3. Label and remove the **cables** on the rear of the library.

## Remove Old Base Chassis from Rack



**WARNING:** It is recommended that a mechanical lifter (or at least two people) be used during rack installation or removal to prevent injury.

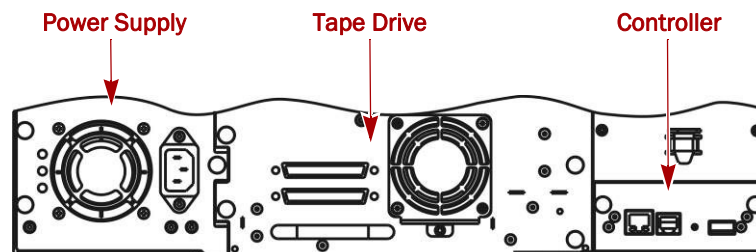
**WARNUNG:** Um Verletzungen zu vermeiden, empfehlen wir zur Rack-Installation oder -Deinstallation die Nutzung einer mechanischen Hebehilfe (oder mindestens zwei Personen).

**AVERTISSEMENT:** Pour éviter toute blessure il est recommandé qu'un monte-charge (ou deux personnes au moins) soit utilisé lors de l'installation ou de l'enlèvement du support.

1. Release the **screws** on both side flanges that secure the Base Chassis to the rack.
2. With a mechanical lifter positioned in front of the library, release the **rail locks** and slide the **Base Chassis** out onto the lifter.
3. Place the old chassis on an **ESD-safe** surface.
4. Unpack the **new chassis** and place next to the old chassis.

## Move Components to New Base Chassis

1. Move the **power supplies** from the old chassis to the new chassis (see [Add or Replace a Power Supply on page 26](#)).



2. Move the **tape drives** from the old chassis to the new chassis (see [Add or Replace a Tape Drive on page 21](#)).
3. Move the **library controller** from the old chassis to the new chassis (see [Replace the Library Controller on page 24](#)).

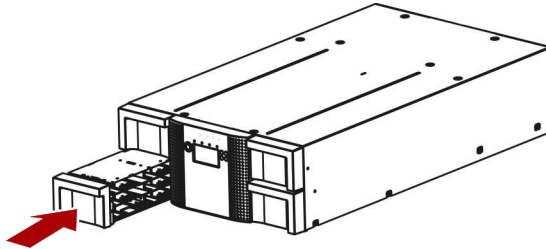
## Install New Base Chassis in Rack

1. Slide out the **middle** rack rails on both sides.
2. Using the mechanical lifter, position the **new chassis** in front of the rack.
3. Insert the chassis **inner rails** into the middle rack rails and slide the chassis into the rack until it is flush with the front.

4. Secure the chassis to the rack with the **captive screws** on both side flanges.
5. After the appliance is secured in the rack, verify that all **drives** are secure in their bays and have not become unseated.

## Reinstall the Tape Magazines

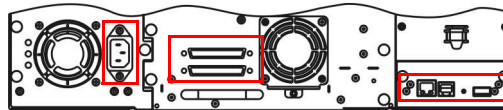
1. Supporting the magazine underneath, position the **magazine rails** onto the alignment rails in the appropriate bay.



2. Using the handle, push the **magazine** slowly into the library until the magazine release latch snaps into place.  
The magazine automatically locks into place when it is correctly installed.
3. Repeat [Steps 1–2](#) for the **remaining magazines**.

## Reconnect Cables and Verify Firmware Version

1. Reconnect all the **cables** to the same ports from which they were removed.



2. Reattach the **power cords**.
3. Press the Base Module **power button** for one to two seconds to power on the library.  
The **green LED** is shown when the library completes its Power-on Self-test (POST).

## Package Chassis for Shipment



**WARNING:** It is recommended that a mechanical lifter (or at least two people) be used during rack installation or removal to prevent injury.

**WARNUNG:** Um Verletzungen zu vermeiden, empfehlen wir zur Rack-Installation oder -Deinstallation die Nutzung einer mechanischen Hebehilfe (oder mindestens zwei Personen).

**AVERTISSEMENT:** Pour éviter toute blessure il est recommandé qu'un monte-charge (ou deux personnes au moins) soit utilisé lors de l'installation ou de l'enlèvement du support.

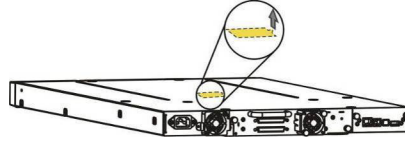


**CAUTION:** Before transport the library, it is recommended that the shipping lock and the yellow label is replaced from the rear panel on the top cover of the library.

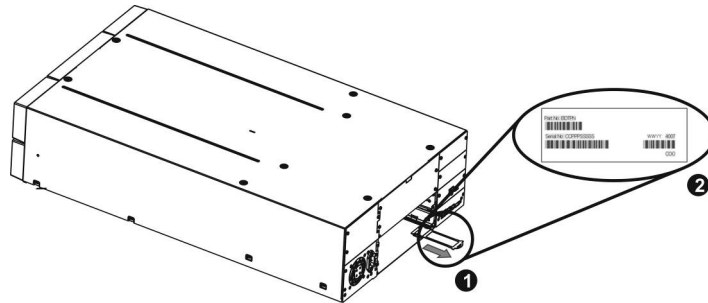


Before sending back the old library:

1. Place **shipping lock** in the unit:
  - a. Remove the **yellow label** that is covering the securing slot for the shipping lock on the top of the library.

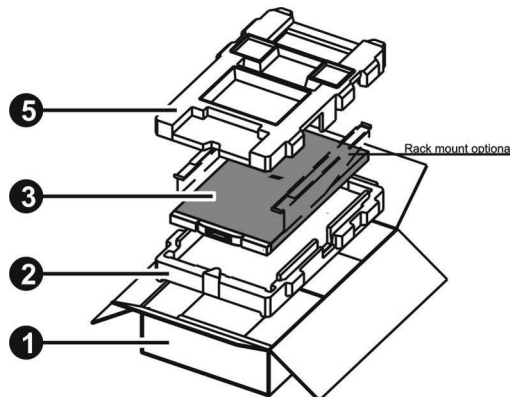


- b. Remove the **shipping lock** from the holder on the back of the unit and place it in the slot on top of the unit to secure the robotics.
  - c. Replace the **yellow label** (or use any other tape) over the shipping lock to secure it.
2. At the rear, extend the **pull-out tab** with the product ID label and note the **part number and serial number** of the unit.

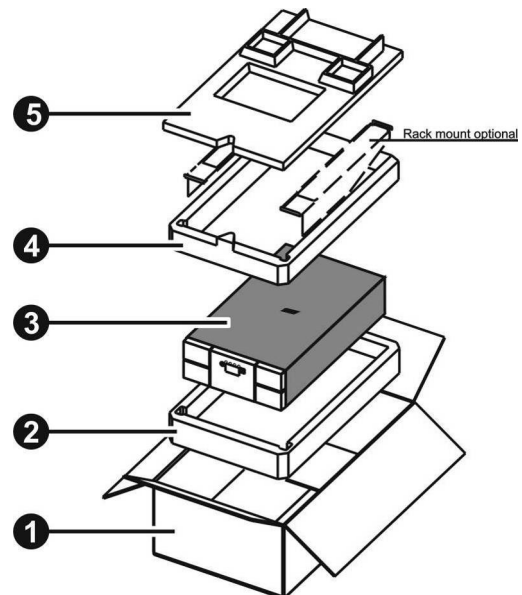


3. Use the appropriate figure for **packaging** your library for shipment.

#### Packaging the 1U or 2U Library



#### Packaging the 4U Library



| Step # | Description            |
|--------|------------------------|
| 1      | Packaging box          |
| 2      | Bottom shell           |
| 3      | Library                |
| 4      | Middle shell (4U only) |
| 5      | Top shell              |

# 4

## Event Codes and Acronyms

This appendix details the event codes and key acronyms for the NEO tape libraries.

### Topics in Event Codes and Acronyms:

- [Error Overview](#)
- [Main Error Codes](#)
- [Sub-error Codes Related to the Robotic](#)
- [Sub-error Codes Related to the Library](#)
- [Acronyms and Abbreviations](#)

## Error Overview

### Error Messaging

The internal error messaging between the different modules and tasks contain the following information:

- Error code
- Sub-error code
- Affected source element
- Affected target element
- Affected library in stacked mode (Master/Slave)
- Additional information depending on context and error code

### Error Structure

The error messaging is a fixed 4-byte structure with the following content:

- Error type
- Error code
- Sub-error code
- Internal code (active command code)

### Error Reporting

In case of an error or a warning, a popup message appears on the OCP or the RMI.

## Main Error Codes

| Error Code | Description   | User Action   | Critical Component Status  |
|------------|---|---|--|
| 80         | Bar Code Reader Error, cannot initialize BCR                          | Retry operation; after several occurrences contact technical support                    | Robotic probably defect <ul style="list-style-type: none"> <li>• Flexi cable to BCR not properly connected.</li> <li>• Flexi cable to BCR damaged.</li> <li>• Bar code engine defect.</li> </ul>   |
| 81         | Bar Code Reader Error, no response from BCR                           | Retry operation; after several occurrences contact technical support                    | Robotic probably defect <ul style="list-style-type: none"> <li>• Flexi cable to BCR not properly connected.</li> <li>• Flexi cable to BCR damaged.</li> <li>• Bar code engine defect.</li> </ul>   |
| 82         | EEPROM Error, no response from EEPROM (located on robotic controller) | Retry operation; after several occurrences contact technical support                    | Robotic probably defect<br>Robotic controller not working (hardware problem, EEPROM defect).   |
| 83         | Robotic controller generic problem                                    | Reset the unit and retry operation. After several occurrences contact technical support | Robotic probably defect<br>Robotic hardware not working (cables, distribution boards, robotics controller).  |
| 84         | Setting of gripper motor parameters failed                            | Reset the unit and retry operation. After several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> </ul>  |
| 85         | Setting of slider motor parameters failed                             | Reset the unit and retry operation. After several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> </ul>  |
| 86         | Setting of elevator motor parameters failed                           | Reset the unit and retry operation. After several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> </ul>  |
| 87         | Setting of rotation motor parameters failed                           | Reset the unit and retry operation. After several occurrences contact technical support | Robotic probably defect<br>Robotics controller defect.   |
| 88         | Setting of sled motor parameters failed                               | Reset the unit and retry operation. After several occurrences contact technical support | Robotic probably defect<br>Robotics controller defect.   |
| 89         | Gripper blocked   | Run 'Library Verify Test', after several occurrences contact technical support          | Robotic probably defect <ul style="list-style-type: none"> <li>• Gripper motor not connected or defect.</li> <li>• Gripper motor voltage too low.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check gripper mechanism according stiffness in movement.</li> </ul> |

| <b>Error Code</b> | <b>Description</b>                                   | <b>User Action</b>   | <b>Critical Component Status</b>  |
|-------------------|--|--|---|
| 8A                | Slider blocked                                       | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Slider Motor not connected or defect.</li> <li>• Slider motor voltage to low.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check slider mechanism according stiffness in movement.</li> </ul>  |
| 8B                | Elevator blocked                                     | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator motor not connected or defect.</li> <li>• Elevator motor voltage to low.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check elevator mechanism according stiffness in movement</li> </ul>   |
| 8C                | Rotation blocked                                     | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Rotation motor not connected or defect.</li> <li>• Rotation motor voltage to low.</li> <li>• Rotation home sensor defect.</li> <li>• Rotation sensor connecting cable damaged.</li> <li>• Robotics controller or distribution boards defect.</li> </ul>  |
| 8D                | Sled blocked   | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Sled motor not connected or defect.</li> <li>• Sled motor voltage to low.</li> <li>• Sled home sensor defect.</li> <li>• Sled sensor connecting cable damaged.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check sled mechanism (guide rail, duck tail) according stiffness in movement.</li> </ul> |
| 8E                | Cannot find gripper block within the expected range  | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> <li>• Check gripper gears.</li> </ul>   |
| 8F                | Cannot find slider block within the expected range   | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> <li>• Check slider gears.</li> </ul>  |
| 90                | Cannot find elevator block within the expected range | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> <li>• Check elevator gears.</li> </ul>  |
| 91                | Cannot find rotation block within the expected range | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Cabling incorrect.</li> <li>• Check rotation gears.</li> </ul>   |

| <b>Error Code</b> | <b>Description</b>  | <b>User Action</b>   | <b>Critical Component Status</b>   |
|-------------------|---|--|--|
| 92                | Cannot find sled block within the expected range                                  | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Cabling incorrect.</li> <li>• Check sled gears.</li> </ul>  |
| 93                | Gripper outside range, Gripper has reached a position beyond the expected range   | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> <li>• Check gripper gears.</li> </ul>                              |
| 94                | Slider outside range, Slider has reached a position beyond the expected range     | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> <li>• Check slider gears.</li> </ul>                               |
| 95                | Elevator outside range, Elevator has reached a position beyond the expected range | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Elevator distribution board defect.</li> <li>• Cabling incorrect.</li> <li>• Check elevator gears.</li> </ul>                             |
| 96                | Rotation outside range, Rotation has reached a position beyond the expected range | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Cabling incorrect.</li> <li>• Check rotation gears.</li> </ul>  |
| 97                | Sled outside range, Sled has reached a position beyond the expected range         | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Cabling incorrect.</li> <li>• Check sled gears.</li> </ul>  |
| 98                | Cartridge present sensor not found  | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Robotics controller defect.</li> <li>• Cartridge present sensor defect (mechanics, electronics).</li> <li>• Cabling incorrect.</li> </ul> |
| 99                | Sled home sensor not found  | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Robotics controller defect.</li> <li>• Slider home sensor defect (mechanics, electronics).</li> <li>• Cabling incorrect.</li> </ul>       |
| 9A                | Rotation home sensor not found  | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Robotics controller defect.</li> <li>• Rotation home sensor defect (mechanics, electronics).</li> <li>• Cabling incorrect.</li> </ul>     |
| 9B                | Sled position sensor (prism sensor) not found,                                    | Run 'Library Verify Test', after several occurrences contact technical support | Robotic probably defect <ul style="list-style-type: none"> <li>• Robotics controller defect.</li> <li>• Sled home sensor defect (mechanics, electronics).</li> <li>• Cabling incorrect.</li> </ul>         |

| <b>Error Code</b> | <b>Description</b>  | <b>User Action</b>  | <b>Critical Component Status</b>  |
|-------------------|---|---|---|
| 9C                | Gripper range out of specification  | Run 'Library Verify Test', after several occurrences contact technical support          | <p>Robotic probably defect</p> <ul style="list-style-type: none"> <li>• Gripper motor not connected or defect.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check gripper mechanism according stiffness in movement</li> </ul>  |
| 9D                | Slider range out of specification   | Run 'Library Verify Test', after several occurrences contact technical support          | <p>Robotic probably defect</p> <ul style="list-style-type: none"> <li>• Slider motor not connected or defect.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check slider mechanism according stiffness in movement.</li> </ul>   |
| 9E                | Elevator range out of specification   | Run 'Library Verify Test', after several occurrences contact technical support          | <p>Robotic probably defect</p> <ul style="list-style-type: none"> <li>• Elevator motor not connected or defect.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check elevator mechanism according stiffness in movement.</li> </ul>                                     |
| 9F                | Rotation range out of specification   | Run 'Library Verify Test', after several occurrences contact technical support          | <p>Robotic probably defect</p> <ul style="list-style-type: none"> <li>• Rotation motor not connected or defect.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check rotation mechanism according stiffness in movement.</li> </ul>                                     |
| A0                | Sled range out of specification   | Run 'Library Verify Test', after several occurrences contact technical support          | <p>Robotic probably defect</p> <ul style="list-style-type: none"> <li>• Sled motor not connected or defect.</li> <li>• Robotics controller or distribution boards defect.</li> <li>• Check sled mechanism according stiffness in movement.</li> </ul>   |
| A1                | Open Mail Slot (Import/Export Element) failed   | Retry operation, after several occurrences contact technical support                    | Mail Slot release mechanism defect  |
| B0                | Robotic controller response timeout. A command did not complete in the required amount of time. | Reset the unit and retry operation. After several occurrences contact technical support | <p>Robotic probably defect</p> <ul style="list-style-type: none"> <li>• No communication from library controller to robotic controller.</li> <li>• Robotic hardware not working (cables, distribution boards, robotics controller).</li> <li>• Download robotic firmware fails.</li> </ul>        |
| B1                | NACK received from robotic controller   | Reset the unit and retry operation. After several occurrences contact technical support | <p>Robotic probably defect</p> <ul style="list-style-type: none"> <li>• Communication from library controller to robotic controller disturbed.</li> <li>• Robotic hardware not working (cables, distribution boards, robotics controller).</li> <li>• Download robotic firmware fails.</li> </ul> |

| <b>Error Code</b> | <b>Description</b>   | <b>User Action</b>   | <b>Critical Component Status</b>  |
|-------------------|--|--|---|
| B2                | Robotic controller communication failed  | Reset the unit and retry operation. After several occurrences contact technical support                            | Robotic probably defect <ul style="list-style-type: none"> <li>• No communication from library controller to robotic controller.</li> <li>• Robotic hardware not working (cables, distribution boards, robotics controller).</li> <li>• Download robotic firmware fails.</li> </ul> |
| B3                | Robotic controller urgent stop due to a released magazine  | Check if magazine are completely inserted and retry operation. After several occurrences contact technical support | Magazines released<br>Magazine present sensor defect.   |
| B4                | Cartridge did not transport completely<br>Gripper could not pick cartridge and CP sensor not present<br>After pushing the cart CP sensor still present |  | <ul style="list-style-type: none"> <li>• CP sensor defect</li> <li>• Cartridge sticks in slot/drive</li> </ul>  |
| B5                | Robotic controller doesn't respond on command  | Reset the unit and retry operation. After several occurrences contact technical support                            | Robotic probably defect <ul style="list-style-type: none"> <li>• No communication from library controller to robotic controller.</li> <li>• Robotic hardware not working (cables, distribution boards, robotics controller).</li> <li>• Download robotic firmware fails.</li> </ul> |
| C0                | Network initialization failed  | Check network cable and network configuration. If the error recurs, contact technical support                      | Library controller probably defect probably a hardware problem, check library controller  |
| C1                | Telnet Interface initialization failed   | Check network cable and network configuration. If the error recurs, contact technical support                      | Library controller probably defect, probably a hardware problem, check library controller   |
| C2                | Web server initialization failed   | Check network cable and network configuration. If the error recurs, contact technical support                      | Library controller probably defect, probably a hardware problem, check library controller   |
| C6                | Ping command did not reached target  | Check network cable and network configuration. If the error recurs, contact technical support                      | Library controller probably defect, probably a hardware problem, check library controller   |
| C7                | Cannot Upgrade from USB  | Retry of Firmware upgrade, if not successful contact technical support   | Library controller probably defect, probably a hardware problem, check library controller   |
| C8                | Cannot Upgrade from FTP  | Retry of Firmware upgrade, if not successful contact technical support   | Library controller probably defect, probably a hardware problem, check library controller   |
| C9                | Cannot Upgrade Robotic from Flash  | Retry of Firmware upgrade, if not successful contact technical support   | Library controller probably defect, probably a hardware problem, check library controller   |
| D0                | ROM error.<br>ROM checksum incorrect   | Retry of Firmware upgrade, if not successful contact technical support   | Library controller probably defect, probably a hardware problem, check library controller   |



| Error Code | Description  | User Action   | Critical Component Status   |
|------------|--|---|---|
| D1         | RAM error.<br>Power on Self Test (POST) has failed,  | Retry operation; after several occurrences contact technical support  | Library controller probably defect, RAM defect, check library controller  |
| D2         | NVRAM error.<br>R/W operation to NVRAM has failed  | Retry operation; after several occurrences contact technical support  | Library controller probably defect, probably a hardware problem, check library controller   |
| D3         | CTC Error.<br>Timer unit has failed during POST.   | Retry operation; after several occurrences contact technical support  | Library controller probably defect, probably a hardware problem, check library controller   |
| D4         | UART Error.<br>Frame overrun or Parity Error on serial Interface.  | Retry operation; after several occurrences contact technical support  | Check library and robotics controller   |
| D5         | Display Error<br>Communication to display failed   | Retry operation; after several occurrences contact technical support  | Check library controller and OCP  |
| D6         | Memory Error, Stack and heap overflow.   | Retry operation; after several occurrences contact technical support  | Library controller probably defect  |
| D7         | Fatal system error   | Retry operation; after several occurrences contact technical support  | Library controller probably defect probably hardware problem, check library controller  |
| D8         | Data base error  | Retry operation; after several occurrences contact technical support  | Library controller probably defect, probably hardware problem, check library controller   |
| D9         | No SCSI IC detected  | Retry operation; after several occurrences contact technical support  | SCSI controller probably defect, check SCSI controller and library controller   |
| DA         | In Library Verify Test the bar code reader has read different bar code data for the same cartridge label | Check bar code label on scratch cartridge and run Library Verify Test again. If the error recurs, contact technical support |   |
| DB         | Warning event!<br>See section below  |   |   |
| DC         | I <sup>2</sup> C Bus Failure   | Retry operation; after several occurrences contact technical support  | Failure in I <sup>2</sup> C bus communication. <ul style="list-style-type: none"> <li>• Check library controller and connections to OCP and backplane.</li> <li>• Check OCP.</li> <li>• Check backplane.</li> <li>• Check drive sleds.</li> </ul> |
| DD         | Warning event!<br>See section below  |   |   |
| DE         | Warning event!<br>See section below  |   |   |
| DF         | Warning event!<br>See section below  |   |   |
| E0         | Incompatible magazine detected   | Check type of lowest left magazine  | Magazine type not supported   |

| Error Code | Description  | User Action   | Critical Component Status   |
|------------|--|---|---|
| E2         | Unsupported hardware detected – Library firmware upgrade required  | Library Extender was installed without upgrading the library firmware. Upgrade library code to revision which supports this feature |   |
| EB         | Power supply health check failed due to a power supply failure. Please contact service.  | Contact technical support   | Power supply probably defect  |
| F0         | Drive Over temperature Condition<br>The sub code indicates which drive is affected<br>Example:<br>Sub code 01: drive #1  | Check ambient temperature conditions and check all fans, after several occurrences contact technical support                        | Drive probably defect   |
| F1         | Drive Communication Error, Library controller has lost communication to drive<br>The sub code indicates which drive is affected<br>Example:<br>Sub code 01: drive #1 | Retry operation; if not successful contact technical support  | Communication cable between drive and drive sled controller defect. <ul style="list-style-type: none"> <li>• Drive sled controller defect</li> <li>• Check cabling drive sled controller-backplane</li> <li>• Check cabling backplane library controller</li> <li>• Drive defect / check drive</li> </ul> |
| F2         | Drive sled not present<br>The sub code indicates which drive sled is affected<br>Example:<br>Sub code 01: drive sled #1  | Retry operation; if not successful contact technical support  | Drive probably defect <ul style="list-style-type: none"> <li>• Check if drive sled is completely inserted</li> <li>• Drive sled controller defect.</li> <li>• Drive defect.</li> </ul>  |
| F3         | Drive Hardware Error<br>The sub code indicates which drive is affected<br>Example:<br>Sub code 01: drive #1  | Cycle Power, after several occurrences contact technical support  | Drive probably defect   |
| F4         | Drive Load Timeout<br>Drive has run in a timeout while loading a tape<br>The sub code indicates which drive is affected  | Retry operation; if not successful contact technical support  | Drive probably defect <ul style="list-style-type: none"> <li>• Drive leader bent.</li> <li>• Drive initialize repeatedly.</li> <li>• Drive defect (no function).</li> </ul>   |
| F5         | Drive Unload Timeout<br>Drive has run in a timeout while unloading a tape<br>The sub code indicates which drive is affected  | Retry operation; if not successful contact technical support  | Drive probably defect <ul style="list-style-type: none"> <li>• Drive leader bent.</li> <li>• Drive initialize repeatedly.</li> <li>• Drive defect (no function).</li> </ul>   |
| F8         | Invalid drive command  | Retry operation; if not successful contact technical support  | Drive probably defect   |
| F9         | Invalid drive parameter  | Retry operation; if not successful contact technical support  | Drive probably defect   |
| FA         | SDCI microcode error   | Retry operation; if not successful contact technical support  | Drive probably defect   |

| Error Code | Description                                       | User Action  | Critical Component Status |
|------------|---|--|---------------------------|
| FB         | Drive logged out                                  | Retry operation; if not successful contact technical support | Drive probably defect     |
| FC         | Internal SCSI command failed with check condition | Retry operation; if not successful contact technical support | Drive probably defect     |
| FD         | Internal SCSI command timeout                     | Retry operation; if not successful contact technical support | Drive probably defect     |

## Sub-error Codes Related to the Robotic

|    |  |
|----|--|
| 01 | Mechanical initialization failure                      |
| 02 | Connection to slave robotic failed                     |
| 03 | Error motor initialization                             |
| 04 | Error during gripper close                             |
| 05 | Error slider home positioning                          |
| 06 | Error elevator home movement                           |
| 07 | Error during sled movement to rotation position        |
| 08 | Error during rotation initialization, get range failed |
| 09 | Error elevator init                                    |
| 0A | Error during rotation to far position                  |
| 0B | Error first sled init, move to sensor failed           |
| 0C | Error during sled movement to rotation position        |
| 0D | Error during rotation to drive position                |
| 0E | Error slider init, get range failed                    |
| 0F | Error during slider forward movement                   |
| 10 | Error gripper init, get range failed                   |
| 11 | Error during slider home movement                      |
| 12 | Error during rotation to FAR position                  |
| 13 | Error sled init, move to sensor failed                 |
| 14 | Error during sled move – check shipping lock           |
| 20 | Error Inventory scan                                   |
| 21 | Error during gripper close                             |
| 22 | Error slider home movement                             |
| 23 | Error during move gripper to scan POS                  |
| 24 | Error reading bar code label                           |
| 25 | Error during move sled to scan position                |
| 26 | Error during move elevator to scan position            |
| 27 | Error during sled preposition movement                 |
| 29 | Error during closing gripper                           |

|    |   |
|----|---|
| 2A | Error slider preposition movement                                   |
| 2B | Error during opening gripper  |
| 2C | Error during sled movement up to sensor                             |
| 2D | Error slider preposition backwards movement                         |
| 30 | Error slot preposition  |
| 31 | Error during sled movement in <FLMoveRotation> function             |
| 32 | Command sending to robotic failed                                   |
| 33 | Error during elevator movement in <FLMoveRotation> function         |
| 34 | Error during rotation in <FLMoveRotation> function                  |
| 35 | Error during elevator movement in <FLMoveSled> function             |
| 36 | Error during sled movement in <FLMoveSled> function                 |
| 37 | Error during sled positioning to sensor in <FLMoveSled> function    |
| 38 | Error during sled positioning to mail slot in <FLMoveSled> function |
| 39 | Error during sled positioning without sensor                        |
| 3A | Error during elevator movement without sensor                       |
| 3B | Error slot position sensor not found                                |
| 40 | Movement to/from slot failed  |
| 41 | Error during first slider movement                                  |
| 42 | Error during first gripper movement                                 |
| 43 | Error during second slider movement                                 |
| 44 | Error during second gripper movement, get range failed              |
| 45 | Error during third slider movement, move home failed                |
| 46 | Error during set hold current to avoid torsion                      |
| 50 | Preposition to drive failed   |
| 51 | Elevator movement to home sensor failed                             |
| 52 | Sled movement to home sensor failed                                 |
| 53 | Error during sled movement to drive position                        |
| 54 | Error during rotation to drive position                             |
| 55 | Error during elevator movement in drive position                    |
| 56 | Error during sled movement to rotation position                     |
| 57 | Error during rotation to end position                               |
| 60 | Move from/to drive failed   |
| 61 | Error during first slider movement                                  |
| 62 | Error during first gripper movement                                 |
| 63 | Error during second slider movement                                 |
| 64 | Error during second gripper movement, get range failed              |
| 65 | Error during third slider movement, move home failed                |
| 70 | Release magazine failed   |
| 71 | Error during sled movement to rotation position                     |
| 72 | Error during rotation to unlock position                            |

|    |   |
|----|---|
| 73 | Error during move sled to block   |
| 80 | Opening mail slot failed  |
| 81 | Error during movement to mail slot open position  |
| 82 | Error during moving back - sensor was found   |
| 90 | Movement to home position failed  |
| 91 | Elevator movement to home position failed   |
| 92 | Error during sled movement to rotation position   |
| 93 | Error during rotation to home or far position   |
| 94 | Sled movement to home sensor position failed  |
| 95 | Sled movement to transport position failed  |
| 99 | Error during rotation movement to rotation min position   |
| A0 | Movement to mail slot failed  |
| A1 | Sled movement to sensor failed  |
| A2 | Sled movement to rotation position failed   |
| A3 | Elevator movement to home position failed   |
| A4 | Error during rotation to far position   |
| A5 | Sled movement to mail slot position failed  |
| A6 | Error during elevator movement to position  |
| A7 | Error during mail slot detection  |
| B0 | EEPROM on robotics controller not accessible or error during r/w operation  |
| B1 | Save/restore configuration settings: not enough internal memory available for creating the file and restoring the file respectively |
| B2 | Save/restore configuration settings: restore buffer corrupted, checksum calculation failed  |
| B3 | Save/restore configuration settings: data base field corrupted  |
| B4 | Save/restore configuration settings: invalid personality  |
| B5 | Save/restore configuration settings: invalid file   |

## Sub-error Codes Related to the Library

| All libraries |  |
|---------------|--|
| 81            | Tape drive wake up failed                    |
| 88            | Error accessing slot status                  |
| 90            | Robotic load not reached tape present sensor |
| 91            | No activity after <Load> command             |
| 92            | Timeout while loading tape                   |
| 93            | No activity after <Load> command             |
| 94            | Timeout drive unload                         |
| 95            | Tape drive terminated unsuccessfully         |
| 96            | Tape not ejected at robot unload             |

|                        |                                      |
|------------------------|--------------------------------------|
| 97                     | Slot not free at robot unload        |
| 98                     | Tape not seated in <Load> phase 1    |
| <b>1U library only</b> |                                      |
| C0                     | Check magazine failed                |
| C1                     | Error during rotation movement       |
| C2                     | Error during elevator movement       |
| C3                     | Error during sled movement           |
| C4                     | Error during sled movement to sensor |

## Acronyms and Abbreviations

| Acronym | Meaning                            |
|---------|------------------------------------|
| FC      | Fibre Channel                      |
| FH      | Full Height                        |
| GUI     | Graphical User Interface           |
| HBA     | Host Bus Adapter                   |
| HH      | Half Height                        |
| LUN     | Logical Unit Number                |
| OCP     | Operator Control Panel             |
| RMI     | Remote Management Interface        |
| SAN     | Storage Area Network               |
| SAS     | Serial Attached SCSI               |
| SNMP    | Simple Network Management Protocol |
| SSH     | Secure Shell                       |
| SSL     | Secure Socket Layer                |
| UID     | Unit Identification                |
| USB     | Universal Serial Bus               |
| WORM    | Write Once, Read Many              |
| WWPN    | World-Wide Port Name               |

# 5

## Technical Specifications

**NOTE:** These specifications are accurate at the time of publication. Refer to the Overland-Tandberg website for the latest figures.

### Hardware Specifications

| Form factor                        | 1U (StorageLoader)                                  | 2U (T24)  | 4U (T48)  |
|------------------------------------|---|---|---|
| Product Dimensions (H x W x D)     | 1.73 x 18.98 x 31.85 in.<br>(4.4 x 48.2 x 80.9 cm)  | 3.44 x 17.60 x 29.13 in.<br>(8.8 x 44.7 x 74.0 cm)                                    | 1.73 x 17.60 x 29.13 in.<br>(17.5 x 44.7 x 74.0 cm)   |
| Packaged Dimensions (H x W x D)    | 9.25 x 23.19 x 38.94 in.<br>(23.5 x 58.9 x 98.9 cm) | 9.76 x 23.54 x 39.09 in.<br>(24.8 x 59.8 x 99.3 cm)                                   | 12.99 x 23.03 x 38.98 in.<br>(33.0 x 58.5 x 99.0 cm)  |
| Shipping Weight (without Rail Kit) | 25.4 lbs.<br>(11.52 kg)                             | 33.0 lbs.<br>(14.97 kg)   | 47 lbs.<br>(21.31 kg)   |
| Product Weight (without media)     | 1 HH drive unit:<br>25.13 lbs. (11.4 kg)            | 1 FH drive unit:<br>32.41 lbs. (14.7 kg)<br>2 HH drive units:<br>34.39 lbs. (15.6 kg) | 1 FH drive unit:<br>46.96 lbs. (21.3 kg)<br>2 FH drive units:<br>53.57 lbs. (24.3 kg)<br>2 HH drive unit:<br>48.94 lbs. (22.2 kg)<br>4 HH drive units:<br>57.54 lbs. (26.1 kg)  |
| Product Weight (with media)        | 1 HH drive unit:<br>28.88 lbs. (13.1 kg)            | 1 FH drive unit:<br>44.53 lbs. (20.2 kg)<br>2 HH drive units:<br>46.52 lbs. (21.1 kg) | 1 FH drive unit:<br>67.46 lbs. (30.6 kg)<br>2 FH drive units:<br>74.08 lbs. (33.6 kg)<br>2 HH drive units:<br>69.23 lbs. (31.4 kg)<br>4 FH drive units:<br>77.82 lbs. (35.3 kg) |

## Operating Environment

| Environment                              | Characteristics       | Specification                            |
|--|-----------------------|--|
| Operating                                | Temperature           | 10 °C to 35 °C                           |
|  | Max. temperature rise | 10 °C / hour                             |
|  | Humidity              | 20% to 80% R.H. (non condensing)         |
|  | Maximum wet bulb      | 26 °C                                    |
|  | Max. humidity rise    | 10% / hour                               |
|  | Altitude operating    | 0 to 10.000 ft (3000 m) at 25 °C ambient |
| Non Operating<br>Storage and<br>Shipping | Temperature           | -30 °C to +60 °C                         |
|  | Max. temperature rise | 20 °C / hour                             |
|  | Humidity              | 10% to 90% RH (non condensing)           |
|  | Altitude              | -22 to 33000 feet (-7 to 10000 m)        |

## Maximum Storage Capacity and Data Transfer Rates

Numbers for the 1U, 2U, and 4U models. Host interface is 6 Gb/s (SAS) and 8 Gb/s (FC).

| Characteristics                                       | Specification  |
|---|--|
| <b>NEO S-Series tape library with LTO-5 drives</b>    |  |
| Maximum storage capacity<br>(8/24/48 data cartridges) | Native 12/36/72 TB<br>Compressed: 24/72/144 TB<br>(assuming 2:1 compression)                   |
| Maximum data transfer rate<br>(single LTO-5 drive)    | Native: 140 MB/s (504 GB/h)<br>Compressed: 280 MB/s (1 TB/h)<br>(assuming 2:1 compression)     |
| <b>NEO S-Series tape library with LTO-6 drives</b>    |  |
| Maximum storage capacity<br>(8/24/48 data cartridges) | Native 20/60/120 TB<br>Compressed: 50/150/300 TB<br>(assuming 2.5:1 compression)               |
| Maximum data transfer rate<br>(single LTO-6 drive)    | Native: 160 MB/s (576 GB/h)<br>Compressed: 389 MB/s (1.4 TB/h)<br>(assuming 2.5:1 compression) |



| Characteristics                                       | Specification  |
|---|--|
| <b>NEO S-Series tape library with LTO-7 drives</b>    |  |
| Maximum storage capacity<br>(8/24/48 data cartridges) | Native 48/144/260 TB<br>Compressed: 120/360/720 TB<br>(assuming 2.5:1 compression)             |
| Maximum data transfer rate<br>(single LTO-7 drive)    | Native: 278 MB/s (1.0 TB/h)<br>Compressed: 750 MB/s (2.7 TB/h)<br>(assuming 2.5:1 compression) |
| <b>NEO S-Series tape library with LTO-8 drives</b>    |  |
| Maximum storage capacity<br>(8/24/48 data cartridges) | Native 96/288/576 TB<br>Compressed: 240/720/1400 TB<br>(assuming 2.5:1 compression)            |
| Maximum data transfer rate<br>(single LTO-8 drive)    | Native: 278 MB/s (1.0 TB/h)<br>Compressed: 750 MB/s (2.7 TB/h)<br>(assuming 2.5:1 compression) |

## Logins and Default Passwords

To login, select the access type and enter the correct password. There are three levels of access:

- **Guest** – Standard user level, default password “**std001**”.
- **Admin** – Administrator user level, default password “**adm001**”.
- **Service** – Access by service personnel only.

Each level affects which areas you have access to and what actions you can initiate from those areas.

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