The John A. Blume Earthquake Engineering Center Department of Civil Engineering<br>Stanford University

## A STUDY OF SEISMIC RISK FOR NICARAGUA

## Part I



by<br>Haresh C. Shah Christian P. Mortgat Anne Kiremidjian<br>Theodore C. Zsutty

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#### Abstract

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Any opinions, findings, conclusions or recommendations expressed in this publication are those of the author(s) and do not necessarily reflect the views of the National Science Foundation.

## SYMBOLS AND DEFINITIONS

| a | $=$ Fixed Acceleration |
| :---: | :---: |
| $A_{g}, \mathrm{~A}$ | $=$ Effective Ground Acceleration |
| AZG | = Accelexation Zone Charts |
| C | $=$ Subscript for Condemnation Threshold |
| CAP | = Subscript for Structure Capacity |
| CON | = Subscript for Condemnation Capacity |
| CTSD | = Condemnation Threshold Spectrum for Structure Deformation Determination |
| D | $=$ Subscript for Damage Threshold |
| $\mathrm{D}_{\mathrm{g}}$ | = Effective Ground Displacenent |
| DAF | $=$ Dynamic Amplification Factor for Spectral Shape |
| DAM | = Subscript for Damage Capacity |
| DEM | = Subscript for Earthquake Demand |
| DES | = Subscript for Member Design Level |
| DTSS | $=$ Damage Threshold Spectrum for Member Strength Determination |
| E | $=$ Expected Value |
| $K_{G}$ | = Confidence Limit Contribution due to Use Group |
| K | Confidence Limit Contribution due to structural system type |
| $\left(K_{G}+K_{T}\right) \sigma$ | $=$ Confidence Limit above the mean DAF |
| L | = Structure Life in years |
| m | = Fixed Richter Magnitude |
| M | = Richter Magnitude |
| $M_{b}$ | = Body Wave Magnitude |


| $M_{S}$ | = Surface Wave Magnitude |
| :---: | :---: |
| MMI | $=$ Modified Mercalli Intensity |
| n | $=$ Number of events |
| $N(M)$ | $=$ Number of earthquakes above Richter Magnitude M |
| $N^{\prime}(\mathrm{M})$ | $=$ Normalized $\mathrm{N}(\mathrm{M})$ |
| p | $=$ Probability of success (Bernouilli Trials) |
| p | $=$ Probability |
| R | $=$ Reliability $=1-p$ |
| RP | $=$ Return Period |
| $S_{a}(\beta, T)$ | = A basic acceleration response spectrum ordinate for a system with damping $\beta$, and period $T$ |
| SRSS | = Square Root of Sum of Squared Modal Responses |
| t | $=$ Fixed Period of Time |
| V | = Lateral Load due to Earthquake Ground Motion |
| $\mathrm{V}_{\mathrm{g}}$ | $=$ Effective Ground Velocity |
| $\alpha \beta$ | $=$ Regression Coefficient |
| $\alpha^{\prime}$ | $=$ Normalized $\alpha$ |
| $\beta$ | $=$ Damping Ratio |
| $\beta^{\prime}$ | $=$ Modified Damping Ratio |
| $\beta_{F}$ | $=$ Damping due to structure-foundation interaction |
| $\beta_{S}$ | = Damping due to structural system type |
| $\triangle$ | $=$ Deformation |
| $\delta$ | $=$ Mean Rate of Occurrence (Poisson Law) |
| $\mu$ | $=$ Ductility Ratio |
| $\mu^{\prime}$ | $=$ Modified Ductility Ratio |
| $\sigma$ | $=$ Standard Deviation of the DAF |

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## CHAPTER I

## INTRODUCTION

On December 23, 1972, three strong earthquake tremors struck the city of Managua. Even though of "modoratc" magnitude, this cvent caused thousands of deaths, many more injuries, an untold amount of economic hardship and disxuption of a way of life. It is very hard if not impossible to translate all these losses into quantitative economic terms. However, such a catastrophe does remind us of the devastation and far-reaching consequences of major earthquake events.

The rebuilding efforts which follow such events bring up many questions. Axe existing design requirements adequate? What level of future risk is acceptable? How should the acceptable risk level be translated into acceptable design parameters? Should similar land uses be permitted in the future for areas which suffered major damage? Thesc and numerous other questions become especially relevant after a significant damaging event. The decision process which leads to answers for these questions is a complex mixture of political cxpcdiency, engineering knowhow, socioeconomic optimization and proper understanding of the overall parameters involved in the decision making process. In times when no significant earthquake events have taken place, the decision making process goes on at a notably slow rate, while decisions immediately after significant events are often based on expediency and, at times, on irrational analysis. This leads to decisions which might
well be considered inadequate in the light of rational decisions made on the basis of long-term perspective.

This report is the result of a seismic risk study conducted at Stanford and supported by Banco Central de Nicaragua and the National Science Foundation grant GI 39122. The total seismic risk analysis of Nicaragua is done in two parts. This report is Part I of the study. In general, Part I is associated with the future probably seismic loading determination of Nicaragua and how that loading can be used to determine future damage potential and "insurance risk." Suggestions regarding seismic zoning of the country are also presented in this part. Similarly, the relationships between seismic loading information and design provisions is discussed. Part II is a continuation of Part I, and in general is associated with probabilistic response spectra analysis, probabilistic seismic exposure of different classes of structures and the seismic structural response. A decision analysis of associated risks of loss of life, injury and economic loss will be performed in Part II. A simplified equivalent design procedure will be developed, based on the general concepts and findings of the more detailed response spectrum method. This simplified approach is intended to be applicable for a majority of ordinary regular structures.

It should be emphasized that the work presented in this report is to provide a base for planning and decision making in Nicaragua. The project results provide professionals in Nicaragua with tools and procedures to make seismic risk analysis. A single recommendation today does not appear practical to fit all future circumstances. Hence, major effort is focused on presenting methodology and procedures
that can be used by participating organizations in decision making processes.

Finally, it should be kept in mind that the work and results presented here depend on the available data base and information. The reliability of results are at best as good as the reliability of the data on which the results are based. It is very easy to attack and criticize any work from the point of view of data reliability. However, it is very difficult to obtain long-range reliable data. We have used the best available information through various organizations and researchers. The forecasts and predictions are based on those data. However, if in the future more reliable data are available, the model can easily accommodate the inclusion of new information and update the resuits. Further discussion on this topic will be presented in Chapter 3. At this time, the authors of this report feel that the results presented here represent the "best available" estimates of the future forecasts.

The report is organized in eight chapters and six appendices. Chapter 2 deals with the geologic setting of Nicaragua in general and Managua in particular. In this chapter, the geologic hazards and their implications are pointed out. Chapter 3 gives the discussion on available data. This chapter should be carefully read because it points out, in detail, the shortcomings of the available seismic data and how those shortcomings are treated in the present work. Chapter 4 develop: the future forecasting models based on past data, and presents isoacceleration maps for the country in general and selected citics in particular. In Chapter 5 , the concept of seismic zoning is presented.

Charts relating risk level, economic life of structures, return period and the corresponding loading levels are presented in that chapter. Chapter 6 deals with future damage potential prediction and presents some thoughts on insurance risk. Chapter 7 gives the relationship between seismic zoning, group and use of structures and the needed design provisions. Chapter 7 should be viewed as an introduction to part II of the current study in which further design provision development will be presented. Chapter 8 gives summary and conclusion for part I of the research project and introduces to the reader part II of the study.

In reading this report, a casual reader can start with Chapter 4 and see the forecasting on future seismic loading. A planner can start with Chapter 5 to see the seismic zoning of the country. A structural engineer should read Chapters $4,5,6$, and 7 . In conclusion, it should be emphasized that this is a report on seismic risk analysis. As the name implies, there are many uncertainties and there is always a chance that nature will have the last say.

## CHAPTER II

REGIONAL GEOLOGIC SETTING

## Relation to Plate Tectonics

Nicaragua lies on the Circumpacific "Ring of Fire" which dominates the tectonics of the Pacific Ocean region. The city of Managua lies on the western edge of the Caribbean Plate. In the parlance of the new global plate tectonics, the Caribbean Plate is apparently being underridden by both the Cocos Plate, to the west, and the Atlantic Plate, to the east. Volcanic arcs and grabens, or long, linear depressions in the earth's crust, are characteristic of the intersection of many plates. Managua lies within such a graben, the Nicaragua Depression, and also within a volcanic arc.

Another characteristic of plate intersections are ocean trenches. In this case, such a trench is the Middle America Trench, which marks the depression of the Cocos Plate below the Caribbean Plate. The trench is 4-5 km deep, extends west of the Central American Coast from Mexico to Costa Rica, and runs sub-parallel to the arc-shaped chain of andesitic stratovolcanoes.

Marking the descent of the Cocos Plate is a zone of friction, generally termed the Benioff Zone. This zone is marked by mumerous earthquakes, extending several hundred kilometers into the Earth's interior. The 1972 earthquakes, however, did not occur along this zone, as they were much shallower. They were probably related to
relatively shallow adjustment to accumulating crustal strain within the southwest part of the Caribbean Plate.

## Geology of the Nicaragua Depression

The outstanding feature of the Pacific Coastal Region of Nicaragua is the Nicaragua Depression (also called the Nicaragua Graben, or Central Valley). Bounded on the northeast by a long, straight, en echelon fault, or the Boundary Fault, the Depression extends from the Gulf of Fonseca, to the north, to near Limon, Costa Rica, in the south (figures 2-1, 2-2, and 2-3). The western boundary is placed by some workers beneath the Pacific Ocean, by others along the Mateare Fault, a semi-continuous fault zone. Downfaulting, which began at the beginning of the Quaternary, about $1,000,000$ years ago, has continued to the present.

The Boundary Fault, although at depth probably a normal (block above the fault moves relatively downward) fault, locally suggests right-lateral, or strike slip (opposite block moves laterally to the right) movement. It is locally buried by volcanic rocks. This fault is more regular than the Mateare; it is traceable along the entire length of the Depression. The graben floor is tilted away from the fault, suggesting that either normal movement is minor, or that it is less recent than on the Mateare Fault. In addition, much of the vertical movement could have been taken on several, sub-parallel, en echelon faults.

The Mateare Fault is less clearly expressed in all places. Where prominent, it is a normal fault, displaying a scarp with a

Figure 2-1.Sketch of part of Nicaragua showing the most conspicuous tectonic features. The Cordillera de Marrabios is a line of volcanoes, offset in the vicinity of Managua. The valley containing Lake Managua and Lake Nicaragua is called the Nicaragua Graben. The boundary fault of the graben bounds the Atlantic side of the tectonically active area.

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## 



after McBirney, $A$, and Willians, $H, 196$

Figure 2-3-Local Faulting in the Managua Area. The boundary fault of the graben is some 40 miles to the northeast. The Falla Mateare is a normal fault with some lateral movement of undetermined sense. The Fractura de Nejapa is a line of explosion pits, craters, collapse structures and aberrant stream channels arranged along an extensional zone. Between Lago Nicaragua and the line of faults between the airport and Rio Tipitapa, extensive alluviation from the Masaya Complex may hide the surface expression of some faults. Data is not available to me at this time to delineate faults on the northside of Lago Managua in the same detail as on the south side. Note that the fracture pattern strongly suggests a rudely circular area of subsidence across the valley. From Saint-Amand, 1973
maximum height of 1000 meters along the Sierras de Carazo. The uplift is recent, as evidenced by the slight erosion of the upland surface, despite easily eroded volcanic rocks and high rainfall. Matumoto and Latham calculate the total vertical movement along the western edge of the graben as 2.4 km by adding the thickness of accumulated sediments in the graben ( 1.4 km ) to the vertical drop (scarp) ( 1 km ). (See reference 11.)

The Depression contains a thick accumulation of alluvium, lake sediments, deeply weathered volcanic ash, and some volcanic flow deposits, aggregating, as stated, to a total thickness in excess of 1400 m . The basement rocks are unknown, being neither penetrated by wells nor ejected from volcanoes. The isolated hills of Tertiary volcanics are largely buried, although more exposed to the northeast. This suggests a thicker sedimentary accumulation to the southwest, giving further evidence of greater subsidence in this part of the graben.

## Geology of Managua Region

The city of Managua sits atop a succession of volcanic rocks and sediments aggregating at least 1000 meters in thickness. The section is probably typical of the entire Nicaragua Depression, a1though specific units lense out and are replaced by other units elsewhere in the graben.

To a depth of at least 200 m , the section is a relatively homogeneous and predominantly volcanic sequence of lapilli-sized, angular scoria, or cinder deposits, with interbedded, thin ash deposits. These are derived either from Masaya Crater, 22 km distant,
or the line of volcanoes to the west. Firm and relatively welllithified (consolidated) volcanic mudflow deposits are also common. These are thick and firm enough to be used as building stones. The scoria is extremely porous, permeable, and features a low bulk density. It demonstrates good stability under static loads, and stands in nearvertical slopes if undisturbed, but is not stable under dynamic loading (see reference 14 ).

Some authors emphasize sedimentary rocks, especially lake sediments, in the sequence. A more exact determination of the nature of the rocks would aid in predictions of seismic wave propagation, especially the attenuation of the waves, in general, and the effect of the rocks on accelerations, in particular.

West of Managua, relatively dense lava flows and vent debris are associated with pyroclastics similar to those underlying the city. Less damage occurred here during the 1972 earthquake, but this is probably because of the greater distance from the earthquake epicenter (see reference 14).

## Volcanism

The entire Nicaragua Depression is either an active or potentially active area. Managua lies atop volcanics and volcanically derived sediments that have been deposited in the recent geologic past. Masaya Crater, centered 22 km distant from Managua, has been active in historic times (see reference 12), and some of the volcanic deposits underlying the city have been traced to this same volcanoe. Managua lies within an apparent right-lateral offset of a line of volcanoes, the

Cordillera de 105 Marrabios. The reason for this offset is unclear.

Soils
The soils of Managua are, on the whole, relatively similar throughout the city (Figures $2-4,2-5$ ). They "consist mainly of volcanic deposits of cohesionless silts, sand and gravels ranging from loose to well-consolidated and having various degrees of cementation" (sec reference 17). The soils occur in well-defincd layers of from a few to several hundred centimeters thickness. However, thicknesses, as well as degree of compaction, are somewhat variable even at individual sites. The first "rock-like" material occurs at variable depths. It is called "cantera," or "volcanic sandstone," but in reality is a volcanic tuff agglomerate (see reference 17).

## Water Levels

The water table is generally $10-30 \mathrm{~m}$ below the ground, and 19 m in the city center. Near Lago de Managua (lake Managua) it reaches to within 3 m of the surface. For most of the city, it is too deep to be of significance in the design or location of foundations (see references 17,14 ).

## Faulting

The faults which pass through Managua are members of a system of faults which scar much of the Nicaragua Depression. The faults show some normal, or vertical movement. In general, faults in the western part of the city show movement down to the east, whereas faults to the east demonstrate the opposite. Thus, a shallow composite graben

Fig.2-4 Contour lines of depth of loose surface deposits ( $N<10$ )

is being formed. Movement in the 1972 earthquake is in general agrecment with older fault displacements.

One of the purposes of the geologic study was to describe and interpret the pattern of faulting within the city, as an aid to seismic zoning. The task is extremely difficult, however, because there is no agrecment on the location of the faults in Managua. As many as 10 faults have been mapped (Figures 2-6, 2-7); at least 4 suffered offset in the 1972 earthquake (Figure 2-8). One othcr, the poorly defined Stadium Fault, was offset in the 1931 earthquake. Although we will address ourselves to some general remarks in relation to these faults, final discussions must wait until thorough trenching and mapping, currently underway, is completed and made available.

In conclusion, the Nicaragua Depression is a currently active downfaulted block, bounded on one side by an active fault, and on the other by a potentially active fault. The pile of sediments and volcanics underlying the Depression total more than 1000 m in thickness. Active volcanics cover part of its surface.

A few important points relating to seismic zoning follow:
(1) Each of the 10 "faults" is a zone, rather than a line of movement. Whether the "fault" has moved in the recent past is not of significance in Managua, as each zonc of fracturing could suffer either more fracturing or actual offset in a future earthquake. Thus, fracture zones from the 1972 earthquake should be considered in the same light as faults where displacement actually occurred.
(2) The distance a structure should be placed from a known
$\left\lvert\, \begin{aligned} & \text { Reproduced from } \\ & \text { best available copy. }\end{aligned}\right.$

Figure 2-6 Map of Managua showing faults as located by the group of Mexican geologists

## From Caldera, 1973

Lake Managua


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fault is open to considerable debate. It has been observed that faults tend to rupture repeatedly along nearly the same line, although many recent scarps are located within much wider fault zones, and in alluvium, the fault rupture could easily occur outward from the previously "recognized" breakage. It is our opinion that vital structures, such as hospitals, police and fire stations, etc., should be located at least 100 feet from any fault zone or individual rupture. In a major fault zone, such as the San Andreas Fault in California, movement can be expected to occur along the same trace as the previous movement, but in a region such as Managua, it is our opinion that this would not necessarily be the case.
(3) The type of material on which the structure rests, and the degree of saturation of the material, are extremely important. However, in the case of Managua, these parameters are relatively insignificant, because of the nearness of seismic activity. The only exceptions would be saturated fill and lake sediments. Structures built on those materials faired especially poorly in the 1972 earthquake.
(4) The definition of an "active" fault is not agreed upon. Many geologists use 40,000 years since the last movement as the criterion of "active." This, of course, is often difficult to determine. In addition, the valid argument that even 10,000 years, or less, is economically impractical when considering structures with an anticipated lifetime of less than 100 years. It is our opinion that strategically important and large, public structures should not be located over defined faults in the city of Managua, unless the most conservative
(40,000 years) definition of "active" is used. This would apply to the 10 faults and fracture zones discussed earlier, as well as possibly some buried faults. As a practical manner for the city of Managua, any faults that have not displaced the "White pumice" unit are probably no longer active.
(5) It is unlikely that a better location for the city could easily be found within the Nicaragua Depression, as the graben is cut by numerous faults. On a random movement from the city, the chances for an earthquake would be equal or greater, and the chances for actual surface rupture would be less, the same, or greater. 'lo find a lesser chance for rupture would require an exhaustive and time-consuming study, which would have to locate an almost fault-free site.

Each of the identificd surface or near-surface "faults" within the city should be considered potentially active. As apparently only one fault ruptured in the 1931 earthquake, and at least 4 other faults moved in the 1972 earthquake, it is likely that still other faults could rupture in a future earthquake. From a geologic hazard point of view, where fault rupture and fault displacement are of main concern, critical facilities should not be built within 100 feet of the fault zone or individual rupture. Wallace (see reference 20) suggested one zoning scheme (fig. 2-8) based on strictly geologic hazard. For resistance to seismic vibrational loading, the following chapters will develop criteria for design and zoning requirements. It should be kept in mind that the location of rupture and fault zones within Managua is under study and the future zoning for such geologic hazards should incorporate results of that study.


Figure 2-9-Seismic Map of Part of Nicaragua. The epicenters shown are from 1964 to 1970 as calculated by the U.S. Coast and Geodetic Survey. It is important to note that only one appears north of the boundary fault in Nicaragua and that one is deeper than 70 kms . The most active area lies offshore. It must be realized that although an area may appear to be earthquake free for a long time that large earthquakes may occur in areas thought to be devoid of them because of a total lack of activity in the area. Nonetheless, by picking the areas shown to be free of earthquakes for a protracted period, one is indeed reducing the overall hazard.

## CHAPTER III

## SEISMIC DATA BASE

## Introduction

In Chapter 2, we discussed general geology of Nicaragua. We also discussed the geologic hazards that planners and builders should consider. One major informational parameter needed in any future planning of a facility in a seismic region is the amount of shaking or vibration that this facility will have to undergo during its economic life. In other words, one has to consider the future seismic dynamic loads for which the structures should be designed. Such information helps in seismic zoning of a region. There are various parameters used in the literature to represent the seismic loading. They are:
(1) Richter Magnitude (M);
(2) Modified Mercalli Intensity (MMI);
(3) Peak ground acceleration (PGA);
(4) Spectral Intensity;
(5) Root Mean Square (RMS) acceleration, velocity, or displacement.

However, the most commonly used loading parameters are the Richter Magnitude, the Modified Mercalli Intensity, and the peak ground acceleration. As for the Richter Magnitude, the loading information is in the form of overall energy release of a seismic event. It does not
explicitly represent a loading at a given site some distance away from the source of energy release.

The Modified Mercalli Intensity scale represents the effect of an earthquakc at a given site. It is a subjective scale of damage at a site. Thus, for a given seismic event in a region, various sites experience different intensities. In general, intensity decreases with distance. Appendix 2 gives the $M M$ Intensity scale. Future forecasting of $M M$ intensities for a given region help in determining the future damage potential and hence insurance risk. However, for structural engineering and design purposes, this parameter is not as useful as the peak ground acceleration. The most commonly and conveniently used parameter is the peak ground acceleration. In this work, peak ground acceleration ( $\mathrm{PG} \Lambda$ ) will be used to represent the seismic load level. For frequency content, normalized design spectra will be developed for different parts of the country. (See Chapter 7.)

To estimate probabilistically these peak ground acceleration levels throughout the country in some time frame, we need to get information regarding past seismic events. In particular, we need to get the following information:
(1) Epicentral locations of past seismic events;
(2) Time of occurrence;
(3) Magnitude associated with each occurrence;
(4) Depth of hypocenter;
(5) Acceleration records associated with the above occurrences at different sites;
(6) If possible, information on how energy (or peak ground
acceleration) attenuates from source of energy release to any site away from the source.

As for items 5 and 6 above, not much data is available for Central America in general and Nicaragua in particular. We will discuss these two items in detail in the next two chapters. As for the information on epicentral locations, time of occurrence, magnitude of occurrence and depth of hypocenter, the basic data were obtained from the National Earthquake Information Center, U.S. Department of Commercc, National Oceanic \& Atmospheric Agency, National Earthquake Information Center, Boulder. The information obtained from this source contained all events from 1900 to 1973. Another source that was consulted for earthquakes before 1900 was the "Catalog of Nicaraguan Earthquakes 1520-1973' by David J. Leeds of Dames $\frac{G}{4}$ Moore, Los Angeles. The list of references at the end of this report gives other sources used to develop the total data base (see references 21,22 , 23 , and 24).

Before we go into the discussion on the use and analysis of available data, certain observations should be made regarding the type, amount and reliability of the data base used for the current research.

All the data sources have one common shortcoming. That is, the frequency of recorded earthquakes increases with time. It is very realistic to assume that the seismic phenomenon in Nicaragua has not drastically changed in the past few hundred years and that it will remain the same for a few hundred years more. However, the number of seismic events recorded in general increases with each year. Also, only major events were recorded in the 16 th, 17 th, and 18 th centuries.

This gives a bias to the data because in recent years, all events, big and small, are recorded, whereas old records only show large events. This nonhomogeneity in data reliability is a "fact of life" and we can not get away from it. Another problem is in the events which were not recorded as to time, place and magnitude, but only conveyed through church records or through word-of-mouth. How can one incorporate such information quantitatively?

Fortunately, for well-codified methods and structures, the structural performance and consequences in general follow the pattern shown in figure $3-1$. The horizontal axis represents structural performance such as, say, deformation, whereas the vertical axis represents the consequences of those performances. The performance can be tied in with the seismic demand (or loading). Thus, a 10 percent variation about the mean demand value $D$ can be represented by $D_{1}$ and $D_{2}$. Corresponding to this variation, the performance variations could be $10 \%$ about the mean performance $P$, represented by $P_{1}$ and $P_{2}$. However, this 10 percent variation in loading estimate may result in only a slight variation on the consequence side. This ability of a well designed structure based on a well designed code helps in overcoming the uncertainty in the loading parametcr such as peak ground acceleration. Further discussion on this aspect will be presented in Chapter 7 of this report. Also, inclusion or exclusion of some unrecorded historical events in the past does not change the estimated values of the loading parameters substantially, because the estimates are based on a large collection of data to begin with.

Due to above mentioned considerations, the authors of this


FIGURE 3-1
report feel that the seismic loading estimates, based on probabilistic analysis, are realistic and representative of the future seismic loadings.

Data Analysis
As mentioned previously, two main sources of information were considered. The NEIC-NOAA data file covering the period from January 1900 to August 1973 constituted the primary source of information and is referred to hereafter as Source 1. The Catalogue of Nicaraguan Earthquakes, 1520-1973, by David J. Leeds, is referred to as Source 2. It was used to obtain:

- data about earthquakes associated with volcanic activity along the Cordillera de los Marrabios (1850-1973);
- data about earthquakes not reported in the NEIC-NOAA file (1900-1973);
- additional information about events incompletely documented in the NEIC-NOAA file (1900-1973).

The time period of data gathering is thus 73 years for the whole country and 123 years for earthquakes associated with volcanic activity along the Cordi1lera de los Marrabios.

In spite of the complementarity of the two sources, a large number of events remained insufficiently documented to be used as such in the analysis. Rather than disregarding these events, the missing information was generated using a Monte Carlo Process supplemented by judgment. It is felt that the total analysis benefits more than suffers from such an additional input.

The following remarks are valid for both sources:
. No critical study was made regarding the validity of the information and the reliability of the data.
. Whenever information as basic as epicentral location or magnitude were missing, the event was disregarded.
. Events with Richter Magnitude smallex than 3.0 were not considered.

Source 1

When complete, the information contained in this source includes for a given event: time of occurrence, epicentral location (degree), depth of hypocenter (km), and magnitude. The magnitude is in terms of one of the following:
(1) CGS $M_{b}$ average (body wave magnitude)
(2) CGS $M_{S}$ average (surface wave magnitudc)
(3) Richter Magnitude M.

The acceleration attenuation relationships used in Chapter 4 are based on the Richter Magnitude. Hence, when missing, this information was generated from $M_{b}$ or $M_{s}$. It is known that for a given part of the world, the Richter Magnitude and CGS $M_{b}$ are linearly related such that

$$
M=a+b M_{b}
$$

In order to determine the coefficients $a$ and $b$, a regression analysis was run for all the earthquakes of which $M$ and $M_{b}$ were known using the total data of Central America. The Richter Magnitude was then obtained by substituting the value of $\mathrm{M}_{\mathrm{b}}$ in equation 3-1.

Whenever data on depth of hypocenter were not available, a depth was assigned, as will be explained later in the chapter.

From Source 1, 419 events contained complete information; they are plotted in Chart 1 and shown as a function of depth in Table 3-1.

Source 2
When complete, the information contained in this source includes for a given event: time of occurrence, epicenter location (degree), depth, Richter Magnitude and sometimes a short description of the seismic event. The depth is either expressed in km or by a letter symbol N $(0-60 \mathrm{~km})$ or I $(70-200 \mathrm{~km})$. In the same way, the Richter Magnitude is either expressed by its numerical value or by a letter symbol, as follows:

$$
\begin{array}{ll}
B- & 7 \leq M \leq 7.7 \\
C- & 6 \leq M \leq 6.9 \\
D- & 5.3 \leq M \leq 5.9 \\
E- & M<5.3
\end{array}
$$

Through a simulation process, all the events taken from Source 2 were assigned a numerical Richter Magnitude from letter magnitude.

Hence, an additional 196 events were obtained (including events from Source 1 with partial information), distributed as follows:

43 events associated with volcanic activity and with shallow hypocenters $N(0-60 \mathrm{~km})$.
events with shallow hypocenters $\mathrm{N}(0-60 \mathrm{~km})$.
3 events with deep hypocenters I (70-200 km).
63 events with no data on depth.
47 events with numerical data on depth $(\mathrm{km})$.

## Table 3-1

Data from Source 1, Sorted According to Depth of Hypocenter (Total Events 421)

| Number of Earthquakes | Depth Range (kms.) |
| :---: | :---: |
| 8 | 0- 9 |
| 9 | 10-19 |
| 12 | 20-29 |
| 159 | 30-39 |
| 35 | 40-49 |
| 32 | 50-59 |
| 34 | 60-69 |
| 32 | 70-79 |
| 18 | 80-89 |
| 14 | 90-99 |
| 13 | 100-109 |
| 9 | 110-119 |
| 3 | 120-129 |
| 7 | 130-139 |
| 3 | 140-149 |
| 7 | 150-159 |
| 3 | 160-169 |
| 6 | 170-179 |
| 3 | 180-189 |
| 5 | 190-199 |
| 9 | 200-215 |

The 466 earthquakes with complete data (419 from Source 1 and 47 from Source 2), were plotted as a function of depth. Using those plots together with epicenter location, magnitude value, partial information on depth and judgment, the 156 remaining events were assigned appropriate depths. This led to a total data of 615 events ranging from 5 to 215 km in depth and from 3.0 to 7.7 in magnitude. Appendix 3 gives the listing of those earthquakes; in Chart $2-7$ they are plotted as a function of depth.

From these charts, the general seismic pattern of Nicaragua can be divided into the following regions:
(1) The Benioff Zone dipping North East toward the Nicaraguan coast. This zone is marked by numerous earthquakes covering the whole range of magnitude (larger as depth increases) and extending several hundred kilometers into the earth's interior. The shallow earthquakes ( $\pm 30 \mathrm{~km})$ due to this source are from 30 to 100 km away from the coast. As the epicenters get closer to the coast, the hypocenters get deeper. Hence, under Managua the hypocenters of earthquakes situated on the Benioff Zone are very deep (100-200 km).
(2) In contrast, for the local seismic sources, such as the ones identified under Managua (Figures 2-3 and 2-6, Chapter 2), the hypocenters are shallow ( $5-30 \mathrm{~km}$ ). In magnitude scale, these sources do not generate major earthquakes such as those on the Benioff Zone. However, due to their shallowness and nearness to populated areas, they have caused extensive damage and loss of life in past history. The

December 23, 1972 event was due to the local source under Managua. Appendix I gives details regarding this source of seismic activity.
(3) The line of volcanoes from Northwest to Southeast (Cordillera de los Marrabios) represents sources of future seismic activities. Volcanic eruptions are seldom by themselves sources of seismic activity, and in the past various earthquakes have been recorded preceding volcanic eruptions. For this reason earthquakes "associated" with volcanic activity were treated in the model (Chapter 4) as shallow tectonic earthquakes.
(4) Two shallow ( $\pm 30 \mathrm{~km}$ ) seismic regions, one more or less coinciding with the Pacific seashore between Lake Managua and the Costa Rica border, the other one in the Gulf of Fonseca.
(5) The Atlantic coast of low seismicity.

Source Location and Scismicity
Based on the above observations, the total number of events was divided into 13 seismic sources: Ten of these are line sources and three are area sources. Table 3-2 shows these 13 sources, the number of events and the depth range of each source.

Appendix 3 gives a listing of the earthquakes included in each source. Line sources were located by fitting a line through the data using regression analysis. For area sources, the centroid was obtained from the data and the radius taken as the distance from the centroid to the most distant epicenter in the source.

The depth of each source was computed as an average hypocentral

Table 3-2
Seismic Sources for Nicaragua

| Source | Number of Events | Name of Source | Depth (kms.) |
| :---: | :---: | :---: | :---: |
| 1 Line | 159 | Benioff | $5-39$ |
| 2 Line | 186 | Benioff \& Costa Rica | 40-79 |
| 3 Line | 72 | Benioff | 80-109 |
| 4 Line | 31 | Benioff | 110-159 |
| 5 Line | 41 | Benioff | 160-215 |
| 6 Line | 23 | "Costa Rica" | $5-39$ |
| 7 Line | 11 | Atlantic | A11 Depths |
| 8 Line | 12 | Pacific Coast Line | 33 |
| 9 Line | 57 | Line of Volcanoes | 33 |
| 10 Line | 57 | Line of Volcanoes | 33 |
| 11 Area | 5 | Managua Area | 5 |
| 12 Area | 8 | Gulf of Fonseca | 33 |
| 13 Area | 10 | Costa Rica Area | $80-109$ |

depth of all the earthquakes included in the source. Earthquakes with no or limited depth information were not included in this averaging process. Howover, they were considered in dotermining the location and the seismicity of the source. Charts 2 through 7 show the source locations and depths. The recurrence relationship for each individual source was obtained by fitting a regression line of the following form:

$$
\ln _{e} N(M)=\alpha+\beta M
$$

$N(M)=$ Number of events above magnitude $M$
M $=$ Richter Magnitude
$\alpha$ and $\beta$ are regression constants.
$\alpha$ is a measure of the number of events above magnitude 0 for a given source and $\beta$ is a measure of the seismic scverity for a given source. The larger the negative value of $\beta$, the smaller the seismic severity. For many sources, a single regression line gave erroneous results because the interpolation of the line beyond the range of data indicated unreasonably high magnitude occurrences. For such cases, two regression lines were fitted to the data, and a geologically consistent upper magnitude value was used for cutoff. (See Figures 3-2 through 3-13.) Table $3-3$ gives a summary of $\alpha^{\prime}$ and $\beta$ values for each source and the magnitude cutoff point corresponding to $\ln N(M)=0.1$.

$$
\text { Let } \begin{align*}
N^{\prime}(M) & =\frac{N(M)}{A T} \text { for area source } \\
& =\frac{N(M)}{L C} \text { for line source }
\end{align*}
$$

where $L=$ length of the line source



CUMULATIVE NUMBER OF OCCURENCES








$$
\begin{aligned}
A= & \text { Area of the area source } \\
T= & \text { time for which data was obtained } \\
N^{\prime}(M)= & \text { Normalized mean number of events above magnitude } M \\
& \text { for unit-time }(1 \text { year }) \text { and umit-area or unit length. }
\end{aligned}
$$

Then

$$
\ln N^{\prime}(M)=\alpha^{\prime}+\beta M
$$

where

$$
\begin{aligned}
\alpha^{\prime} & =\alpha-\ln (\mathrm{AT}) \text { for area source } \\
& =\alpha-\ln (L T) \text { for line source. }
\end{aligned}
$$

Table $3-3$ shows values of $\alpha^{\prime}, \beta$ and the upper cutoff magnitude as described previously. The table gives values of $\alpha^{\prime}$ and. $\beta$ in terms of degrees of latitude and longitude. These relationships will be used to develop the forecasting model in Chapter 4.

## Limitations

In conclusion, it can be said that there are limitations to the use of available data for the Nicaragua region. These limitations are given below.

1. $24 \%$ of the data contain incomplete information regarding the depth. This information was added from either judgment or by correlating the event with other data where the depth information was available.
2. $32 \%$ of the data have magnitude defined by a symbol.

Numerical value of magnitude for these cases was obtained through simulation.

Table 3-3

| Source | $\alpha_{1}{ }^{\prime}$ | $\beta_{1}$ | $\alpha_{2}{ }^{\prime}$ | $\beta_{2}$ | Cutoff |
| :---: | ---: | ---: | ---: | ---: | :--- |
| 1. | 2.58 | -1.09 | 24.00 | -4.55 | 6.8 |
| 2. | 1.49 | -0.74 | 62.80 | -9.21 | 7.8 |
| 3. | -0.38 | -0.42 | 3.60 | -5.75 | 7.7 |
| 4. | -0.39 | -0.65 | 26.50 | -4.55 | 7.5 |
| 5. | 0.33 | -0.72 | 36.20 | -5.27 | 8.5 |
| 6 | 0.42 | -0.77 | 46.50 | -7.82 | 6.9 |
| 7. | -2.13 | -0.33 | 18.60 | -3.53 | 7.5 |
| 8. | -0.89 | -0.37 | 43.10 | -7.57 | 6.8 |
| 9. | -4.71 | -0.24 | 34.20 | -5.43 | 7.8 |
| 10. | -4.71 | -0.24 | 34.20 | -5.43 | 7.8 |
| 11. | 3.17 | -0.74 | 79.15 | -12.4 | 6.7 |
| 12. | 0.14 | -0.07 | 79.90 | -13.04 | 6.5 |
| 13. | -0.66 | -0.59 | 34.60 | -5.54 | 7.5 |

3. The reliability of the total data base was not evaluated.
(1) Some information was from church and historica1 records.
(ii) Distribution of information over the country is biased. Populated arcas have better records than sparsely populated areas. (No population $\rightarrow$ no records.)
(iii) Epicentral location could be in error due to lack of a good grid of recording system. It is hoped that the recording network presently installed by the Nicaraguan authorities, the U.S.G.S. and private organizations in Nicaragua will help in increasing the understanding of attenuation relationships and the accuracy of epicentral locations in the future. Such calibration may help in relocating the past events. (See reference 4 by Dewey.)

It is felt that the work done by Dewey (see reference 4) and others in calibrating the epicentral locations through the ESSO refinery record does not have sufficient experimental evidence as yet. Hence, no hypocenters are moved based on Dewey's work. (One exception is the 1931 earthquake-stadium fault.) It should be emphasized that as additional data become available to give more reliable information on epicentral locations, the methodology presented in this research project will be able to modify the results accordingly.

## CHAPTER IV

## PROBABILISTIC SEISMIC LOADING -- ISO-ACCELERATION MAPPING

OF NICARAGUA

## Introduction

In Chapter 3, we discussed the data base, the limitations of the available information and the approximations made in using the seismic data of Nicaragua. We also presented the recurrence relationship associated with all the seismic sources for the region. These recurrence relationships give us the mean number of events of magnitude greater than $M$ due to a given source and time period. If the mean number of events above a specified magnitude $M$ is normalized with respect to time and length of the source for line source or area of the source for area source, we get the normalized recurrence relationship. This normalized relationship gives the quantitative statistical seismic recurrence formula for each source. This, however, represents the past seismic history of the region. In developing understanding on the seismic risk for Nicaragua, we need the future forecasting of events. Based on the past data, the future forecasting can be done by means of two widely used statistical models. These models are:
(1) Poisson Model.
(2) Markov Model.

The Poisson Model assumes that major seismic events are
spatially and temporally independent. This has been observed to be true for the southern California region. (See reference 25.) The Markov Model assumes memory in two successive seismic events. Thus, occurrence or non-occurrence of an earthquake this year effects the occurrence or non-occurrence of an event next year. Even though this model conforms with the so-called elastic rebound theory, it has been observed that for events with interarrival times of more than 10 years, the Markov Model gives similar results to the Poisson Model. References 26 and 27 are two good examples of using Poisson and Markov Chain Models. In this study, the Poisson Model is used because of its simplicity, its widespread use in literature, and because the results it gives are very similar to results arising from more complex models such as the Markov Chain Model.

## Poisson Model of Seismic Occurrences

As mentioned in the previous paragraph, earthquake occurrences can be modeled using the Poisson probability law. For earthquake events to follow the Poisson Model, the following assumptions must be valid:
(1) Earthquakes are spatially independent;
(2) Earthquakes are temporally independent;
(3) Probability that two seismic events will take place at the same place and at the same instant of time approaches zero.

These assumptions are necessary for the formulation of the Poisson
Mode1. The first assumption implies that occurrence or nonoccurrence
of a seismic event at one site does not affect the occurrence or nonoccurrence of another seismic event at some other site. The second assumption implies that the seismic events do not have memory in time. A Markovian assumption of one-step memory in time may be a better assumption, but as mentioned previously, this assumption for large events does not introduce major errors (see reference 25). The third assumption implies that for a small time interval, $\Delta t$, more than one seismic event cannot occur. This is a very realistic and good assumption which fits the physical phenomenon.

In its most general form, the Poisson law can be written as

$$
p_{n}(t)=\frac{e^{-\lambda t}(\lambda t)^{n}}{n!}
$$

where $P_{n}(t)=$ Probability of having $n$ events in time period $t$. $n=$ Number of events.
$\lambda=$ Mean rate of occurrence per unit of time.

In Chapter 3, we have seen how, using recurrence relationships, we can obtain the mean number of occurrences above Magnitude $M$ for a given source. This relationship in its general form can be written as

$$
N(M)=\phi(M, A, T)
$$

```
where N(M) = Number of occurrences above Richter Magnitude M.
    M = Richter Magnitude.
    A = Source characteristic (area for area source, length
        for line source).
    T = Time period of data base.
```

As mentioned in Chapter 3, a $\log$-linear recurrence relationship is assumed for all sources. Also, for each source, the relationship is bi-linear (two lines described by $\alpha_{1}, \beta_{1}$ and $\alpha_{2}, \beta_{2}$ ). (See Table 3-3 of Chapter 3.) Thus, for a given source, the two lines describing the recurrence relationship are given by:

$$
\begin{array}{ll}
\ln N^{\prime}(M)=\alpha_{1}^{\prime}+\beta_{1} M & 0 \leq M \leq M_{1} \\
\ln N^{\prime}(M)=\alpha_{2}^{\prime}+\beta_{2} M & M_{1} \leq M \leq M_{2}
\end{array}
$$

where $M_{1}$ is the magnitude at which the two recurrence lines intersect (see, for example, fig. 3-2)
$M_{2}$ is the upper cutoff magnitude for a given source (see Table 3-3, Chapter 3).

Thus, depending on the source and the value of $M$, the mean number of events above Magnitude $M$ for a unit area for area source, a unitlength for line source, and a unit-time is given by:

$$
N^{\prime}(M)=\exp \left[\alpha_{i}^{\prime}+\beta_{i} M\right]
$$

Thus, from equation 4-1

$$
P_{n}(t)=\frac{\exp \left[-\exp \left(\alpha_{i}^{\prime}+\beta_{i} M\right) t\right]\left[\exp \left(\alpha_{i}^{\prime}+\beta_{i} M\right) t\right]^{n}}{n!}
$$

Note that in equation 4.5 above, $\lambda$ is replaced by $N^{\prime}(M)$. Equation 4-5 gives the probability of observing $n$ events above magnitude $M$ in time period $t$, based on the seismic history of a given source.

Three different types of sources can be used to represent the scismicity of any location. They are point, line, and area sources. All three source mechanisms will be discussed for generality and completeness, although only the line and area sources wexe considered for the Nicaragua region.
a. Point Source

For this type of source, all occurrences (past and future) take place at one point. The recurrence relationship can be normalized with respect to time T as follows:

$$
N^{\prime}(M)=\frac{N(M)}{T}
$$

and $\ln N^{\prime}(M)=\alpha^{\prime}+\beta M--4-3$ repeated.

Substituting the value of $\mathrm{N}^{\prime}(\mathrm{M})$ in the Poisson law of equation 4-1, we get:

$$
P_{n}(M>m, t)=\frac{\left.\exp \left[-N^{\prime}(m) t\right]^{\left[N^{\prime}(m) t\right.}\right]^{n}}{n!} \quad 4-7
$$

where the notation
$P_{n}(M>m, t)$ gives the probability that there will be $n$ events of Richter magnitude greater than $m$ in time period $t$.

For engineering purposes, we are usually interested in determining the probability of at least one event greater than m in time period t. This probability is given by

$$
\begin{aligned}
& \text { P (at least one event of Richter Magnitude } M>m \text { in time } \\
& \text { period } t \text { ) } \\
& \quad=1-P \text { (no earthquake of magnitude } M>m \text { in time } t \text { ). }
\end{aligned}
$$

Hence, from equation 4-7,
$P$ (at least one event of Magnitude $M>m$ in time $t)$
$=1-\exp \left[-N^{\prime}(m) t\right]$.

## b. Line Source

For a line source, it is assumed that epicenters lie along a linear fault. For a line source of length $L$ (fault length L) and the data base for a time period $T$, the recurrence relationship of Chapter 3 and equation 3-2 can be normalized to:

$$
N^{\prime}(M)=\frac{N(M)}{L T} \quad \cdots \text { Equation } 3-3 \text { repeated }
$$

and

$$
\ln N^{\prime}(M)=\alpha^{\prime}+\beta M-- \text { Equation } 3-4 \text { repeated. }
$$

Thus, the Poisson law of equation 4-1 can be written as

$$
P_{n}(M>m, t)=\frac{\exp \left[-N^{\prime}(m) t\right]\left[N^{\prime}(m) t\right]^{n}}{n!}
$$

where $N^{\prime}(\mathrm{m})$ for line source is normalized with respect to length of the fault and time period T. Again, for determining the probability of at least one event of magnitude greater than $m$ for a future time period $t$ is given by,
$P($ at least one earthquake of $M>m$ in time $t)$

$$
=1-P_{0}(M>m, t)
$$

$$
=1-\exp \left[-N^{\prime}(m) t\right]
$$

which is a similar expression to equation 4-8 except that the interpretation of $N^{\prime}(m)$ is different.

## c. Area Source

When the past earthquake epicenters do not lie on a line (i.e. 2.long a given fault line) but are scattered over a region, the seismic source should be considered as an area source. The area source could be a full circle or any section of a circle where epicenters are scattered. Un this case, the recurrence relationship is normalized with respect to area $A$ and the time of data base $T$.

$$
N^{\prime}(M)=\frac{N(M)}{A T} \quad \cdots-E q \cdot 3-3 \text { repeated }
$$

and $\ln N^{\prime}(M)=\alpha^{\prime}+\beta M \ldots E q .3-4$ repeated.

Thus, the probability of at least one event due to this area source above magnitude $m$ in time period $t$ is given by:
$\mathrm{P}($ at least one $\mathrm{M}>\mathrm{m}$ in time t$)=1-\exp \left[-\mathrm{N}^{\prime}(\mathrm{m}) \mathrm{t}\right]$. Again, this expression is similar to equation 48 for a point source, and also for a line source. However, in each case the normalized $N^{\prime}(M)$ has a different interpretation.

Peak Ground Acceleration at a Site

As we mentioned in Chapter 3 , the most commonly used parameter to describe the seismic loading at a given site is the peak ground acceleration (PGA, usually denoted by A). In the previous section, we obtained the probability of exceeding a magnitude level in time $t$ by
using a Poisson odel. (The probability distribution represented by Eq. 48 gives information only on Richter magnitude.) For design purposes, we wish to know the loading at a site, away from the epicenter. Modified Mercalli Intensity (MMI, see Appendix 2) peak ground acceleration, spectral acceleration, and several other parameters have been used to represent the loading at a given site. To obtain probabilistic information about peak ground acceleration at a site, we have to know the following parameters:

1. Probabilistic information on Richter Magnitude for a source as a function of future time $t$.
2. Distance of the site from the source.
3. Attemuation of peak ground acceleration from source to site.

We have already determined the first parameter in the previous section. Various attenuation formulae are available which give relationship between the Richter Magnitude $M$, the epicentral distance or the hypocentral distance, and the peak ground acceleration. The most commonly used relationship is of the form given by

$$
A=\frac{b_{1} \exp \left(b_{2}{ }^{M}\right)}{\left(R_{h}+b_{4}\right)^{b_{3}}}
$$

where $A=$ Peak Ground Acceleration (PGA) in $\mathrm{cm} / \mathrm{sec}^{2}$.
$R_{h}=$ Hypocentral distance from source to site (in kms.).
$M=$ Richter Magnitude.
$b_{1}, b_{2}, b_{3}$, and $b_{4}$ are constants depending on the region.

Since there is not a close grid of seismographs in Nicaragua, not much information is available on attenuation of accelerations in that part of the world. However, various values of $b_{1}, b_{2}, b_{3}$ and $b_{4}$ are available for other parts of the world. One such relationship that has been adopted for this work is the onc developed by Esteva. The attenuation constants are given by

$$
\begin{array}{ll}
\mathrm{b}_{1}=5,000 ; & \mathrm{b}_{3}=2.0 ; \\
\mathrm{b}_{2}=0.8 ; & \mathrm{b}_{4}=40
\end{array}
$$

Thus, the attenuation relationship becomes

$$
A=\frac{5,000 \exp (0.8 \mathrm{M})}{\left(R_{h}+40\right)^{2}}
$$

Figure 4-1 shows the behavior of Eq. 4-10 for different Richter magnitudes and hypocentral distances. This equation was correlated with the ESSO Refinery data for the 1972 December earthquake and also with the aftershocks. The correlation of the curve of Eq. 4-10 with the data is quite reasonable; consequently, the attenuation relationship given by Eq. 4-10 is used in this study. It should be pointed out that the installation of many new instruments will help in calibrating the attenuation relationship for Nicaragua in the future. When that is done, the results presented in this study can be readily modified.

We have seen that three types of seismic sources are possible. Due to each of these seismic sources, the peak ground acceleration at a site in a probabilistic sense can be determined.

a. Point Source

For a point source shown in Figure 4-2, we can derive the following expressions:

$$
\begin{aligned}
\mathrm{p}(M>m, t)= & \text { Probability of at least one event greater than } \\
& m \text { in time } t . \\
= & 1-\exp \left[-N^{\prime}(m) t\right] \\
\text { but } N^{\prime}(M)= & \exp \left[\alpha^{\prime}+\beta M\right]
\end{aligned}
$$

Thus,

$$
P(M>m, t)=1-\exp \left[-\exp \left(\alpha^{\prime}+\beta m\right) t\right]
$$

To determine the probability distribution on peak ground acceleration $A$, we have

$$
\begin{align*}
\mathrm{P}[\mathrm{~A}>\mathrm{a}] & =\mathrm{P}\left[\frac{\mathrm{~b}_{1} \exp \left(\mathrm{~b}_{2} \mathrm{M}\right)}{\left(\mathrm{R}_{\mathrm{h}}+\mathrm{b}_{4}\right) \mathrm{b}_{3}}>a\right] \\
& =\mathrm{P}\left[M>\ln \left\{\frac{a}{b_{1}}\left(R_{h}+b_{4}\right)^{b_{3}}\right\} \frac{1}{b_{2}}\right]
\end{align*}
$$

Using equation 4-11 in 4-12, we get

$$
P[A>a]=1-\exp \left\{-e^{\alpha \prime}\left(\frac{a}{b_{1}}\right)^{\beta / b_{2}}\left(R_{h}+b_{4}\right)^{\frac{\beta / b_{3}}{b_{2}}} t\right\}
$$

Denoting

$$
\begin{aligned}
\gamma & =e^{\alpha^{\prime}} \\
\delta & =\beta / b_{2} \\
\text { and } \rho & =\frac{\beta b_{3}}{b_{2}}=\delta b_{3}
\end{aligned}
$$


we get

$$
P[A>a]=1-\exp \left\{-\gamma\left(\frac{a}{b_{1}}\right)^{\delta}\left(R_{h}+b_{4}\right)^{\rho} t\right\} \quad 4-14
$$

b. Line Source

Most of the earthquake epicenters around the world are gencrally located around the major fault systems. Thus, the usual case of epicenters falling along a line gives rise to the so-called line source. The line source can be divided into $k$ small segments of length dl. Each one of these segments can be treated as a point source. Summing the effects of all such segments, as $\mathrm{dl} \rightarrow$ o, gives the probability of a peak ground acceleration $A$ exceeding a value a due to a fault line source of length L.

For a point source, we have seen that

$$
\begin{aligned}
P[A>a] & =1-\exp \left\{-\gamma\left(\frac{a}{b_{1}}\right)^{\delta}\left(R_{h}+b_{4}\right)^{\rho} t\right\} \\
\text { then } \quad P[A<a] & =\exp \left\{-\gamma\left(\frac{a}{b_{1}}\right)^{\delta}\left(R_{h}+b_{4}\right)^{\rho} t\right\} .
\end{aligned}
$$

Thus, for an element i of the line source, we have

$$
\mathrm{P}_{\mathrm{i}}[\mathrm{~A}<\mathrm{a}]=\exp \left\{-\gamma\left(\frac{\mathrm{a}}{\mathrm{~b}_{1}}\right)^{\delta} \underset{\mathrm{i}}{\left.\left(\mathrm{R}_{\mathrm{h}}+\mathrm{b}_{4}\right)^{\rho} \mathrm{d} \ell_{i} t\right\}}\right.
$$

From Fig. 4-3,

$$
R_{h}=\left(d^{2}+l^{2}+h^{2}\right)^{1 / 2}
$$

where $\ell$ is the distance of element under consideration from the
perpendicular on the line source.
Thus,
$P_{i}[A<a]=\exp \left\{-\gamma\left(\frac{a}{b_{1}}\right)\left[\left(d^{2}+\ell_{j}{ }^{2}+h^{2}\right)^{1 / 2}+b_{4}\right]^{\rho} d l_{i} t\right\}$

From the basic assumption of spatial independence of occurrences, we get

$$
\begin{aligned}
& P[A<a]=\lim \prod_{i=1}^{K} P_{i}[A<a] . \\
& d \ell{ }_{i} \rightarrow 0 \\
& k \rightarrow \infty \\
& =1 \mathrm{im} \\
& \lim _{i} \rightarrow 0 \quad \exp \left\{-\gamma\left(\frac{a}{b_{1}}\right)^{\delta} \sum_{i=1}^{K}\left[\left(d^{2}+\ell_{i}{ }^{2}+h^{2}\right)^{1 / 2}+b_{4}\right]^{\rho} d \ell_{i} t\right\} \\
& \kappa \rightarrow \infty \\
& P[A<a]=\exp \left\{\left(-\gamma\left(\frac{a}{b_{1}}\right)^{\delta} t \int_{\ell_{1}}^{\ell_{2}}\left[\left(d^{2}+\ell^{2}+h^{2}\right)^{1 / 2}+b_{4}\right]^{\rho} d l\right\} \quad 4-15\right.
\end{aligned}
$$

Alternatively,

$$
P[A>a]=1-\exp \left\{-\gamma\left(\frac{a}{b_{1}}\right)^{\delta} t \int_{\ell}^{\ell_{2}}\left[\left(d^{2}+l^{2}+h^{2}\right)^{1 / 2}+b_{4}\right]^{\rho} d \ell\right\} \quad 4-16
$$

Expressions 4-15 and 4-16 provide the probabilities of peak ground acceleration $A$ due to a line source located some distance away and whose seismicity is available in terms of $\alpha^{\prime}$ and $\beta$ and also for which the attenuation relationship of the form of Eq. 4-9 is available.

## c. Area Source

Peak ground acceleration due to an area source at a site can be obtained in a manner similar to that for line source. In many parts of the world, including Nicaragua, there are regions where the epicenters are not only located along a line but are scattered all over the region. This may be due to the existence of numerous faults crisscrossing the region or due to errors in estimating epicentral locations. In any case, there are places where point or line sources may not fit the scatter of epicentral locations. For such cases, area source should be used to determine probabilistic loadings at a site. Figure 4-4 shows schematically the area source geometry.

$$
\text { Consider an elemental area } d A_{i}=R_{i} \mathrm{dR}_{\mathrm{i}} \mathrm{~d} \theta_{\mathrm{i}} \text {. With this elemental }
$$ area as a source, the probability that the Richter Magnitude M will be less than $m$ in time $t$ is given by

$$
\begin{aligned}
P_{i}[M<m, t] & =\exp \left[-N^{\prime}(m) d A_{i} t\right] \\
& =\exp \left[-\exp \left(\alpha^{\prime}+\beta m\right) t R_{i} d R_{i} d \theta_{i}\right]
\end{aligned}
$$

or

$$
p_{i}[A<a, t]=\exp \left[-e^{\alpha^{\prime}}\left(\frac{a}{b_{1}}\right)^{\beta / b_{2}}\left(\sqrt{R_{i}^{2}+h^{2}}+b_{4}\right)^{\beta b_{3}} b_{2} t R_{i} d R_{i} d \theta_{i}\right]
$$

Summing the effect of all clemental areas, we get

$$
\begin{aligned}
P[A<a, t]= & \lim _{\substack{ \\
\\
\\
\\
\\
\\
\\
\\
d \theta_{i} \rightarrow 0}} \quad P_{i}(A<a, t)
\end{aligned}
$$

Hence,


FIGURE 4-4

$$
\begin{aligned}
& p[A<a, t]=\exp \left\{-e^{+\alpha^{\prime}}\left(\frac{a}{b_{1}}\right)^{\beta / b_{2}} t \int_{0}^{\Theta_{0}} d \theta \int_{R_{1}}^{R_{2}}\left(\sqrt{R^{2}+h^{2}}+b_{4}\right)^{\overline{b_{2}}} R d R\right\} \\
& =\exp \left\{-e^{\alpha^{\prime}}\left(\frac{a}{b_{1}}\right)^{\beta / b_{2}} t \theta \int_{R_{1}}^{R_{2}}\left(\sqrt{R^{2+h^{2}}}+b_{4}\right)^{\frac{\beta b_{3}}{b_{2}}} R d R\right\} \\
& \text { Let } \gamma=e^{\alpha \prime} \\
& \delta=\beta / b_{2} \\
& \rho=\frac{\beta b_{3}}{b_{2}} \quad \text { as before }
\end{aligned}
$$

and

$$
\mathrm{R}_{\mathrm{h}}=\sqrt{\mathrm{R}^{2}+\mathrm{h}^{2}}
$$

Then

$$
P[A<a, t]=\exp \left\{-\gamma\left(\frac{a}{b_{1}}\right)^{\delta} t \theta \int_{R}^{R_{2}}\left(R_{h}+b_{4}\right)^{\dot{\rho}} R d R\right\}
$$

and

$$
P[A>a, t]=1-\exp \left\{-\gamma\left({\frac{a}{b_{1}}}^{\delta} t \theta \int_{R_{1}}^{R_{2}}\left(R_{h}+b_{4}\right)^{\rho} R d R\right\} 4.18\right.
$$

Equations 4-17 and 4-18 provide the probability distribution of peak ground acceleration A at a site due to a generalized area source shown in Figure 4-4.

In general, a site is usually surrounded by any or all of the
above three sources discussed in this section. The probabilistic loading due to such a case can be obtained by the following expression.

Let there be NP point sources
NL line sources
NA area sources
The probability distribution of peak ground acceleration at a site is then given by

$$
\begin{aligned}
& P[A>a, t]=1-\exp \left\{-\sum_{i=1}^{N P} \gamma_{i}\left(\frac{a}{b}\right)^{\delta} t\left(R_{h_{i}}+b_{4}\right)^{\rho_{i}}\right. \\
& -\sum_{j=1}^{N L} \quad \gamma_{j}\left(\frac{a}{b_{1}}\right)^{\delta} \int_{l_{1 j}}^{\ell_{2 j}}\left[\left(d_{j}^{2}+\ell^{2}+h_{j}^{2}\right)^{1 / 2}+b_{4}\right]^{\rho}{ }_{j} d \ell \\
& \text { R } \\
& -\sum_{k=1}^{N A} \gamma_{k}\left(\frac{a}{b_{1}}\right)^{\delta_{k}} \quad t \theta_{k} \int_{\left(R_{h}+b_{4}\right)}^{\rho_{k}}{ }_{R d R\}}^{4-19}
\end{aligned}
$$

In equation 4-19, summation over $i$ is for all point sources, that over $j$ is for all line sources, and over $k$ is for all area sources.

As we have seen in Chapter 3, there are ten line sources and three area sources that we have formulated for the Nicaragua region, based on past data. Any part of the country is affected by these sources, depending upon the proximity of the site to the source location.

## Iso-Acceleration Maps for Nicaragua

Equation 4-19 can be used to determine the probability distribution function of poak ground acceleration as a function of time and space. For example, at a given site, the probability of $A>a$ increases with time. In other words, the longer the "exposure time," the greater the probability that the peak ground acceleration will exceed some level a. If we take the country as a whole and determine accelerations at different locations for a specific time period $t$ (exposure time) and specific probability of $A<a$, we can obtain lines of equal accelerations. These lines of equal accelerationsfor a specific probability of non-exceed ence and exposure time are called "Iso-Acceleration" lines. The maps representing iso-acceleration lines are called the iso-acceleration maps. Thesc iso-accelcration maps are a form of seismic zoning maps. From these maps, for a given reliability or risk, one can determine the loading parameter (peak ground acceleration) for the seismic design of a structure. Detailed methodology describing the use of these maps for structural design will be presented in Chapter 7 of this report and also in the Part II report of the total study.

Charts 8 through 13 show the iso-acceleration maps for Nicaragua for a time period of 50 years and 20 years. For each time period the iso-acceleration maps are drawn for three risk levels. The risk level is defined as the probability that the peak ground acceleration will be exceeded during the exposure time (or economic lifetime) of the facility under consideration.

In addition to the iso-acceleration maps for the whole country,
the following cities are studied in detail.

1. Managua
2. Leon
3. Granada
4. Masaya
5. Chinandega
6. Matagalpa
7. Este1i
8. San Carlos
9. Rivas
10. Juigalpa
11. Bluefields.

Figures 4-5 through 4-26 show the cumulative distribution function of the peak ground acceleration for each of the cities. Again, results are presented for the exposure time of 20 years and 50 years. Thus, as an example, for Leon, there is approximately $53 \%$ chance that the peak ground acceleration in 20 years of exposure time will not exceed 0.20 g (see Figure 4-8). The corresponding value for a 50 year exposure time for the same city is $21 \%$. Thus, the probability of exceeding 0.20 g in 20 years is $47 \%$, whereas it goes up to $79 \%$ in 50 years. The implications of these probability values and the corresponding acceleration values will be discussed in Chapters 5, 6, and 7. When we compare the cumulative distribution plots for different cities, we can see the relative seismicity in terms of peak ground acceleration for each city. In conclusion, it can be said that one method of representing seismic risk is by means of the iso-acceleration









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maps and the other method of representing seismic risk is by means of cumulative distribution function plots of Figures 4-5 through 4-26.

The engineering interpretation of these results will be presented in the next three chapters. It should also be pointed out that the iso-acceleration maps and any zoning based on such maps only ropresent macro characteristics. The macrozoning of the country should be modified with site-specific micro characteristics to microzone a given region. In that case, the local geotechnical and geological features (such as those discussed in Chapter 2) should be incorporated together with the macro characteristics presented in this chapter.
$\qquad$

## CHAPTER V

## SEISMIC RISK ZONING

## Concept of Return Period and Acceleration

 Zone Graphs (AZG)In deriving the probabilistic loading at a given site as a function of time, we have assumed that the forecasting process is Poisson. This process implies that the events are independent in time and space. Using this assumption and an appropriate attenuation relationship, we developed the iso-acceleration maps for the country. For a given city, we also developed the cumulative distribution function of the peak ground acceleration $A$, as mentioned in Chapter 4. Consider the cumulative distribution of peak ground acceleration in Managua for an exposure time of 20 years. (See Figure 4-5.) Then

$$
\mathrm{P}_{20}(\mathrm{~A}>0.20 \mathrm{~g})=0.73
$$

Equation 5-1 can be interpreted in the following way:
"For Managua, there is a $73 \%$ chance that during the next 20 years, the peak ground acceleration of 0.20 g will be exceeded at least once."

Thus, there is a $27 \%$ chance that for Managua, 0.20 g peak ground acceleration will not be exceeded a single time.

Hence,
$P$ (Zero exceedence of 0.20 g in 20 years) $=0.27$.
From the Binomial Probability Law, we know that for independent trials with probability of success $p$ at each trial, the probability of $r$
successes in $n$ trials is given by

$$
p_{n}(r)=\binom{n}{r} p^{r}(1-p)^{n-r} \quad 5-2
$$

where

$$
\mathrm{r}=0,1, . . . \mathrm{n} ; \mathrm{n}=\mathrm{r}, \mathrm{r}+1, \mathrm{r}+2, . .
$$

and

$$
\binom{n}{r}=\frac{n!}{r!(n-r)!}
$$

Let each trial be a one-year duration for which we are observing the level of peak ground acceleration. Let us define success as that event when the peak ground acceleration for a given trial (year) exceeds 0.2 g . Thus, the probability of zero exceedence of level 0.2 g in 20 years is the same as the probability of 0 successes in 20 trials. Hence, from Eq. 5-2:

$$
\begin{aligned}
& \mathrm{p}_{20}(0)=\binom{20}{0} \mathrm{p}^{0}(1-\mathrm{p})^{20} \\
& \mathrm{p}_{20}(0)=(1-\mathrm{p})^{20}
\end{aligned}
$$

However,
or

$$
\begin{aligned}
& \mathrm{p}_{20}(0)=0.27 \\
& (1-p)^{20}=0.27
\end{aligned}
$$

$$
\mathrm{p}=0.063 .
$$

Thus, for Managua, there is a $6.3 \%$ chance that in any given year, a peak ground acceleration of 0.20 g will be exceeded.

However, the return period is defined as

$$
\text { Return Period }=\mathrm{RP}=\frac{1}{\mathrm{p}}
$$

Thus, the return period RP in Managua for a peak ground acceleration of 0.20 g is $\frac{1}{0.063} \approx 16$ years .

It should be pointed out that this return period of 16 years corresponding to 0.2 g , obtained by using the cumulative distribution function (CDF) of PGA A at Managua for a 20 year exposure time does not change if we use the CDF corresponding to 50 year exposure time. For example, for a 50 year exposure time, (see Figure 4-27),

$$
\mathrm{P}_{50}(\mathrm{~A}>0.20 \mathrm{~g})=0.963
$$

Hence,

$$
P_{50}(A<0.20 g)=0.037
$$

Or

$$
P_{50}(0)=(1-p)^{50}=.037
$$

which gives
$p=0.063$ 5-5
and Return period $R P \approx 16$ years.

Thus, using the CDFs for all the cities in Nicaragua considered in Chapter 4, we can develop a table of peak ground acceleration and return period. Tablc $5-1$ is a general table giving this relationship for the cities considered. The following statements should be understood in using the concept of return period:
(1) A return period is the mean (or average waiting time for an event of interest. Thus, the average (waiting) time between 2 events producing 0.20 g in Managua is approximately 16 years.
Table 5-1

| PGA A in $g$ units | Managua | Leon | Granada | Masaya | Chinandega | Matagalpa | Esteli | San Carlos | Rivas | Juigalpa | Bluefields |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| . 05 | 1.5 | 2.0 | 3.0 | 2.0 | 3.0 | 6.0 | 7.0 | 8.0 | 3.0 | 6.0 | 60.0 |
| .10 | 5.0 | 7.0 | 7.0 | 6.0 | 7.0 | 642.0 | 162.0 | 262.0 | 10.0 | 74.0 | 1127.0 |
| .15 | 9.0 | 13.0 | 12.0 | 10.0 | 12.0 | 9990.0 | 2522.0 | 11755.0 | 23.0 | 1153.0 |  |
| .20 | 16.0 | $32 \cdot 0$ | 35.0 | 20.0 | 106.0 |  | . |  | 81.0 |  |  |
| . 25 | 35.0 | 146.0 | 157.0 | 72.0 | 482.0 |  |  |  | 371.0 |  |  |
| . 30 | 56.0 | 502.0 | 540.0 | 194.0 | 1657.0 |  |  |  | 1280.0 |  |  |
| . 35 | 110.0 | 1430.0 | 1526.0 | 794.0 |  |  |  |  |  |  |  |
| . 40 | 247.0 | 3562.0 |  | 2370.0 |  |  |  |  |  |  |  |
| .45 | 687.0 |  |  |  |  |  |  |  |  |  |  |
| . 50 | 2975.0 |  |  |  |  |  |  |  |  |  |  |

(2) The probability that an event corresponding to a return period RP will occur in any given year is given by $p=\frac{1}{R P}$. Thus, probability of exceeding 0.20 g in Managua in any given year is $\frac{1}{16} \approx 0.063$ (same as Eq. 5-5).
(3) The probability that not a single event of the RP type will occur in RP years is given by $\frac{1}{e}$ where $e=2.718$, the Naperian base. Thus, probability that in 16 years, there will not be a single event producing a pcak ground acceleration of 0.20 g in Managua is given by $\frac{1}{\mathrm{e}} \approx 0.36$.

Thus, there is $64 \%$ chance that in RP years there will be at least one event of RP type. For Managua, there is a $64 \%$ chance that in 16 years, 0.20 g peak ground acceleration will be exceeded. Consider again Table 5-1. For seismic zoning purposes, the following statements can be made:

The return period corresponding to a peak ground acceleration of 0.20 g in Managua is 16 years, in Leon is 32 years, in Granada is 35 years, in Masaya is 20 years, in Chinandega is 106 years and in Rivas is 81 years. Thus, for each city, a graph relating the peak ground acceleration and return period can be plotted. Figures 5-1 through 5-12 show these graphs. We will refer to these graphs as Acceleration Zones. Figure 5-1 shows return period vs. peak ground acceleration for all the cities. It can be seen that for a given return period event (say, 100 years), Bluefields has the lowest value of peak ground acceleration ( $\approx .05 \mathrm{~g}$ ) and Managua has the highest value of peak ground acceleration (. 34 g ) . The values for other cities lie between these two limits. Qualitatively, it can be said that for a
1000
9 ${ }^{\prime}$










facility requiring a design loading corresponding to a 200 year return period, Bluefields has the lowest seismic zoning requirement; San Carlos, Matagalpa, Esteli and Juigalpa have similar zoning requirements but above the Bluefields level; Rivas, Granada, Chinandega, Masaya and Leon, having similar zoning requirements, come next; and finally, the highest level is for Managua. This type of graph can help in macrozoning a country for a given class and use of a structure or facility. (See Chapter 7.)

## Seismic Risk Zoning

In the previous section, we have seen the relationship between the peak ground acceleration and the corresponding return period for different major cities of Nicaragua. However, these relationships by themselves do not help in selecting a return period for a given acceptable level of risk. The next step, in any seismic zoning procedure, is to obtain a relationship between the economic (or exposure) life of a structure, the level of risk one is willing to take, and the return period consistent with the risk and economic life. Consider again the Binomial distribution. The probability of $r$ successes in $n$ independent Bernoulli trials, with probability $p$ of success at each trial, is given by

$$
p_{n}(r)=\binom{n}{r} \quad p^{r}(1-p)^{n-r} \quad \text { Eq. } 5-2 \text { repeated }
$$

Thus

$$
\begin{aligned}
& p_{10}(0)=\binom{10}{0}(\mathrm{p})^{0}(1-\mathrm{p})^{10} \\
&=(1-\mathrm{p})^{10}=\underset{\text { probability of zero success in }}{ } \\
& \quad \begin{aligned}
\text { ten trials (years). }
\end{aligned}
\end{aligned}
$$

Let $p(0)=(1-p)^{10}$ be equal to 0.90 . Then the probability of no occurrence (or success) of a certain level of loading in ten years is given by 0.90 .
or

$$
(1-p)^{10}=0.90
$$

Hence

$$
p=.01048
$$

or return period $R P=95$ years .
Thus, for a structure whose economic life is ten years, if the acceptable risk level is $90 \%$ of not exceeding the specified loading level (i.e., $10 \%$ of exceeding), then the structure should be designed for a return period of 95 years. Table 5-2 gives the relationship between acceptable risk level, economic life and return period. If, for examplc, the acceptable risk level is $80 \%$ for a structure whose economic life is 50 years, then the loading level should correspond to a return period of 225 years. If this structure is in Managua, the corresponding peak ground acceleration level is approximately 0.39 g . If the same facility for the same risk level is to be built in Matagalpa, the corresponding peak ground acceleration level should be approximately 0.12 g . Thus, for a given class and use of structure, having the same economic life (50 years) and same acceptable risk ( $80 \%$ ), the two consistent values of peak ground accelerations in Managua and Matagalpa are 0.39 g and 0.12 g . This is the concept of consistent risk design from one seismic region to another region of different seismicity. Figure $5-13$ shows the graph relating the risk level, economic life and the return period. This particular graph is independent of any region and gives return periods only as functions

Table 5-2
Return Period as a Function of Economic Life and Probability of Non-exceedence

of risk and economic life. Such graphs can easily be codified. Once the acceptable risk level for a given economic life is selected for a given class and use of a structure, the corresponding return period is immediately obtained from Figure 5-13. Then, based on the graph of return period vs. peak ground acceleration (similar to Figures 5-1 to 5-12), the loading at a site can be determined. Let us describe this concept of risk, economic $1 i f e$, return period and Acceleration Zone Graphs (AZG).

As an example, consider a design of a hospital facility. Assume that the exposure time or economic life of the system is 50 years. We are to detcrmine the peak ground acceleration level for which this facility should be designed for each of three different cities. The cities are Managua, Leon, and Esteli. Assume that for the hospital, which is a critical facility that must remain functional after a seismic event, the acceptable level of risk corresponding to damage is $20 \%$ (see Chapter 7 for details). Thus, whether the planned facility is in Esteli, Managua, or Leon, we will accept a $20 \%$ chance of damage during the 50 years economic life of the structure. Then, from Figure 5-13, the return period corresponding to the 50 year economic life and $20 \%$ risk is 225 years.

Now let us refer to the AZG corresponding to Managua (see Figure 5-2). The peak ground acceleration for a 225 year return period in Managua is 0.39 g . Similarly, referring to the AZG for Esteli and Leon, the peak ground acceleration values corresponding to the 225 year recurn period are 0.11 g and 0.27 g . Thus, these three values of peak ground acceleration in the three different cities are consistent
with the given acceptable risk.
As an alternatc situation, consider two separate classes of structures to be built in Managua. Let a school building with an economic 1 ife of 30 years have an accoptable risk level of $20 \%$, and a warehouse with a ten year economic life have a $40 \%$ acceptable risk level. Referring to Figure 5-13, the return period for which the school should be designed is 135 years, and the return period for which the warehouse should be designed is 20 years. Again from the Managua AZG (Figure 5-2), the corresponding peak ground acceleration values are 0.36 g and 0.21 g for the school and warehouse, respectively. If the same two facilities were to be located in Juigalpa, the corresponding peak ground acceleration values would be 0.11 g and 0.07 g . The major advantage of this method of zoning is that one can keep a consistent risk level from one region to another. Variations in the economic life and acceptable risk levels can be accounted for in arriving at a loading level through the return period transformation. Further application of the AZG to structural design will be prosented in Chapter 7 of this report and in Part II of the total study.


## PROBABILISTIC INTENSITY FORECASTING -- DAMAGE ESTIMATION

## MMI Forecasting

Seismic zoning or seismic risk can be presented, as shown in the previous section, in the form of iso-acceleration maps or cumulative distribution functions (CDF) of peak ground accelerations for differcnt citics or by acceleration zone graphs (AZG). Another very informative and useful parameter for representing future seismic risk is in the form of Modified Mercalli Intensity Scale MMI (see Appendix 2 for definition). This intensity scale describes the behavior of different types and classes of masonary and frame structures at a site due a seismic event. Recently, there has been a considerable amount of work in correlating the damage observed due to a seismic event. (See references 35,36 , and 37. ) This damage correlation is usually with the MMI level for a given region. In previous chapters, we have already obtained the probabilistic loading level in the form of peak ground acceleration. Various empirical relationships are available to convert peak ground acceleration to the MMI Scale. The MMI Scale is discrete, whereas the acceleration scale is continuous. To obtain this discrete probability mass function of the MM intensity at different parts of the country for 20 years and $5 \dot{0}$ years, a Monte Carlo simulation process was used. The procedure can be described as follows:
(1) Obtain the CDF for peak ground acceleration $A$ for the region under study. (See Figures $4-5$ to $4-26$. )
(2) Select an empirical equation to convert peak ground acceleration to MMI. The relationship used in this report (see reference 38) is

$$
\begin{equation*}
\log _{10}(a)=\frac{I}{3}-0.5 \tag{61}
\end{equation*}
$$

where $a$ is the acceleration in $\mathrm{cm} / \mathrm{sec}^{2}$
$I$ is the MM intensity.
Thus, for example, the peak ground acceleration at a site is 0.10 g , then

$$
\begin{aligned}
a=0.10 \mathrm{~g} & =\frac{10}{100} \times 981.46 \\
& =98.146 \\
\log _{10} 98.146 & =\frac{I}{3}-0.5
\end{aligned}
$$

or

$$
I=7.5
$$

Since I has to be VII or VIII, we pick $I=$ VIII.
(3) Through random number generation, pick a value of the peak ground acceleration by using CDF for the PGA. Substitute this generated value of PGA in equation $6-1$ and obtain $I$.
(4) Repeat step (3) n times and draw a histogram of frequency chart for I. As $n \rightarrow \infty$, the frequency of I will approach the probability mass function of $I$.

This process was repeated for all eleven cities mentioned in

Chapter 5. A time period of 20 years and 50 years was selected for convenience. Figures 6-1 through 6-11 show the probability mass functions for all the cities. The interpretation of these graphs can be explained by means of an example.

For Managua, during the next 20 yoars, probability that the maximum Modified Mercalli Intensity I will be VIII is given by 0.39 (see Figure 6-1).

Thus,
P [Maximum MMI in 20 years will be VIII] $=0.39$.

Similar statements can be made for other parts of the country. Iso-seismal maps based on such forecasting can be generated for the whole country. It should be pointed out that intensity of shaking is very much a function of local geologic and soil conditions. For proper evaluation of these parameters, a detailed site-specific study and micro-characterization of the site are needed. The values presented here are based on macro study.

## "Insurance Risk" or Damage Potential

We have not correlated the damage data for Nicaragua with the observed past intensities. This study will be presented in part II of the current study. Such correlation can be made by observing the percentage damage in a given class of structures due to an observed past seismic event. From the 1972 earthquake in Managua, the information on such Intensity-Damage correlation can be obtained. However, we will present a methodology of using such information to estimate the "insurance risk" for a given region.














A study of $M M$ intensity and dollar damage was conducted after the Long Beach, the Kern County, and the San Fernando earthquakes. Figure 6-12 shows a graph of Median Loss in percent as a function of MMI for different types of structures. Even though we realize that these values are not applicable to Nicaragua, behavior of structures in Nicaragua built similar to those in the Southern California region will exhibit relationships similar to Figure 6-12. The purpose of presenting numerical examples with damage data from California and intensity forecast for Nicaragua is to show the methodology. No conclusions regarding insurance risk or damage potential should be made by using these numerical values. The purpose, to repeat once again, is strictly to demonstrate methodology. However, appropriate and applicable numorical values will be used in Part II of this study. If, on the other hand, residential houses or light industrial buildings are constructed similar to those in Southern California, such as wood frame dwellings and tilt-up structures, then the numerical values presented here can be used with some caution.

The three classes of structures considered in the example are:
(1) A11 one- and two-story wooden frame residential houses;
(2) Pre-1940 residential homes; and
(3) Light industrial buildings.

Using Figure 6-12, Table 6-1 can be constructed. The losses corresponding to any $M M$, intensity level are in percentages. Thus, for example, due to MMI of $V$, damage to a wood frame dwelling would be $0.1 \%$. The corresponding loss to pre-1940 design dwellings would be


Table 6-1

Median Losses Due to Different MMI Levels

| Intensity | Al1 <br> Dwellings | Pre-1940 <br> Construction | Light Industrial <br> Buildings |
| :---: | :---: | :---: | :---: |
| VI | 0.1 | 0.2 | 0.75 |
| VII | 0.2 | 0.4 | 1.5 |
| VIII | 1.4 | 0.9 | 2.1 |
| IX | 7.3 | 18.0 | 3.0 |
| X | 29.0 | 16.0 |  |

$0.2 \%$, and to light industrial buildings, it would be $0.75 \%$. To determine the expected loss to any class of structure, the probability of any MMI level must be multiplied by the corresponding loss due to that level. The summation over all intensities will give the expected loss in percentage for that class of structure.

Consider, for example, the probability mass function of MMI for a twenty year period at Masaya (see Figure 6-4):

| Intensity | VII | VIII | IX | X |
| :--- | :---: | :---: | :---: | :---: |
| Probability | .01 | .47 | .51 | .01 |
| Damage \% |  |  |  |  |
| All Dwellings | 0.6 | 1.4 | 3.3 | 7.7 |

The expected median damage in 20 years for "all dwellings" is given by

$$
\begin{aligned}
\mathrm{E}[\text { Damage }] & =(.01)(.6)+(.47)(1.4)+(.51)(3.3)+(.01)(7.7) \\
& =2.424 \%
\end{aligned}
$$

Thus, for a $\$ 1,000$ valuation, the expected damage in 20 years is given by

$$
\begin{aligned}
\text { Expected Damage } & =\frac{2.424}{100} \times 1,000 \\
& =\$ 24.24 \text { per } \$ 1,000 \text { valuation in } 20 \text { years. }
\end{aligned}
$$

Similar calculations can be carried out for all eleven cities considered for 20 and 50 years. Table 6-2 shows these loss calculation results. Table 6-3 shows similar expected loss calculations for a $20 \%$ chance of exceedance. Thus, in Managua, there is a $20 \%$ chance that in twenty years a light industrial building will have an expected loss of
Table 6-3


|  | 20 Yrs. |  |  | $50 \mathrm{Yrs}$. |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | A11 <br> Dwell. | $P-1940$ <br> Dwel1. | L. I. Struct. | A11 Dwell. | $\text { P- } 1940$ <br> Dwel1. | L. I. Struct. |
| Managua | 65.5 | 99.2 | 321.0 | 84.8 | 129.0 | 411.0 |
| Leon | $50 \cdot 0$ | 75.0 | 250.0 | 65.5 | 99.2 | 321.2 |
| Granada | 50.0 | 75.8 | 250.0 | 66.5 | 100.8 | 325.8 |
| Masaya | 60.5 | 91.8 | 298.5 | 74.0 | 112.2 | 361.0 |
| Chinandega | 41.2 | 62.0 | 208.5 | 49.8 | 75.0 | 248.2 |
| Matagalpa | 15.0 | 22.5 | 83.0 | 16.5 | 25.0 | 90.2 |
| Esteli | 16.5 | 24.8 | 89.2 | 20.25 | 30.2 | 107.8 |
| San Carlos | 15.8 | 23.8 | 86.0 | 18.5 | 27.5 | 99.0 |
| Rivas | 40.2 | 60.5 | 203.5 | 52.5 | 79.0 | 260.0 |
| Juigalpa | 19.0 | 28.8 | 102.3 | 24.5 | 37.0 | 129.2 |
| Bluefields | 7.3 | 12.0 | 43.8 | 11.2 | 17.8 | 64.5 |

\$321.00. However, the median (expected) loss for the same time period in Managua for the same class of structure will be $\$ 128.40$. Figure 6-13 shows the behavior of expected losses as a function of time and the class of structure. It can be seen that the expected loss or economic (or insurance) risk for the Managua region in one year is $\$ 5.84$ per thousand-dollar valuation. However, over a 20 year life of the structure, the expected median loss is $\$ 26.20$ per $\$ 1,000$ valuation. It can be seen from this example that expected loss averaged over a twenty year time period gives less mean rate of loss $\$ 26.2 / 20 \times \$ 1.31$ per $\$ 1,000$ valuation per year compared to $\$ 5.84$ per $\$ 1,000$ valuation when only one year was considered. This is the concept of risk averaging over time. Thus, if it were possible to insure a given facility for a 20 year economic life (say, a light industrial building), then it would be cheaper to buy that insurance for all twenty years at the same time as opposed to buying it year-by-year. In the long range, buying of insurance, for our numerical problem, the cost would be $\$ 128.4$ per $\$ 1,000$ valuation for a twenty year economic life. For a year-to-year buying, it would cost $\$ 31.84$ per $\$ 1,000$ valuation per year, or $\$ 638.8$ per $\$ 1,000$ valuation over a twenty-year span. Of course, in these simple calculations the value of money and the interest rate are not taken into account. From Tables $6-2$ and $6-3$ it can be seen that the "insurance risk" in decreasing order of magnitude in different cities is:

1. Managua
2. Masaya
3. Granada

4. Leon
5. Chinandega
6. Rivas
7. Juigalpa
8. Esteli
9. San Carlos
10. Matagalpa
11. Bluefields.

Granada and Leon have almost equal expected economic or insurance risks. Similarly, Juigalpa, Esteli, San Carlos and Matagalpa have very similar insurance risks. The seismic insurance risk at Bluefields is very small. It should be pointed out that even though the damage data used in the numerical problem were from Southern California earthquakes, the order of these cities in their seismic and economic risks is valid. If proper data from Nicaragua are considered with appropriate economic conditions in Nicaragua, the ordering of the citics in their risks will not change substantially.

In conclusion, it can be said that the methodology presented here for determining the probable intensity levels and their use in determining expected damages needs a closer look and further investigation. Part II of the current study will go decper into that question.
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## CHAPTER VII

## THE RELATIONSHIP OF ISO-ACCELERATION AND ACCELERATION ZONE GRAPHS (AZG) TO SEISMIC DESIGN PROVISIONS

## Introduction

From the information as developed in the preceding chapter, ground acceleration values $A_{g}$ may be established for a given structure location. These values have selected probabilities $P$ of not being exceeded during a given economic structure life L. The purpose of this chapter is to show how these accelcration values are to be incorporated into load criteria for seismic design provisions. Basically, acceleration values must be converted to seismic load information, such that structures, as designed for these load levels, will have a desircd reliability $R_{D}$ of damage protection and a much higher reliability $R_{C}$ against total building condemnation or incipient collapse during the economic structure life.

While at first thought a building owner may desire full protection against both the hazards of damage and condemnation, a consideration of the complete set of his objectives will show the necessity for acceptance of some level of risk. For a given site location, structure 1ife, and Use Group or Function, these objectives of the building owner are:
. Low construction cost
. Low operating cost
. Functional configuration
. Attractive configuration
. Damage protection
. Condemnation protection.

Perfect and certain fulfillment of all of these objectives is not possible due to the uncertainties in earthquake demands and in structural capacities and behavior. Practical fulfillment of the first four objectives requires the acceptance of a moderate probability of damage $P_{D}$ (equal to $1-R_{D}$ ) and a small probability of structural condemnation $P_{C}$ during the building's economic life, L. Owners, therefore, must agree to a definite set of values for $P_{D}, P_{C}$, $L$ for the given value, and Use Group of the building. Graphs presented in Chapter 6 can help the owner decide on the level of risk and hence can result in the determination of the appropriate probability values.

For these given values of $P_{D}, P_{C}$, and $L$, the Acceleration Zone Graphs (AZG) provide the Peak Ground Acceleration values $A_{D}$ and $A_{C}$ which have the moderate $P_{D}$ and small $P_{C}$ probabilities of exceedence during the structure life $L$ at a given site location.

For example, the use or function of structures may be organized into the following groups which depend on the desired reliabilities of operation and damage protection in the event of a large earthquake.

Group A: Critical facilities necessary for life care and safety; hospitals; penal and mental institutions; gas, water, electric, and waste
water treatment facilities; communcations facilities; police and fire departments; and disaster control centers.

Group B: Multi-family residences; hotels; recreational and entertainment structures; churches and schools; commercial and industrial structures necessary for normal commerce.

Group C: Facilities which are relatively non-essential for normal commerce and where damage will not create a life safety hazard. An example of such facilities would be warehouses.

Example values of the peak ground accelerations $A_{D}$ and $A_{C}$, at sites in Managua and Leon, are given in the following Tables: 7-1, $7-2,7-3$, and 7-4. These are based on structure lives of 20 and 50 years, and on reasonable values for $P_{D}$ and $P_{C}$ corresponding to the structure Use Group. The values given in these tables are strictly for demonstrating the concepts, and are not meant to be used by engineers at this time. As can be seen from these four tables, the same facility and risk in Leon and Managua requires different $A_{D}$ and $A_{C}$ values. Obviously, Leon has a lower seismic demand than Managua.

With thesc known values of $A_{D}$ and $A_{C}$ at the structure site, the primary objectives of the structural designer are to:
. Provide a structure with sufficient rigidity such that no significant non-structural damage will occur due to earthquake ground motions of a level represented by $A_{D}$.

- Provide a structure with sufficient strength capacity such that no significant structural damage will occur due to deformation demands caused by earthquake ground motions of a level represented by $A_{D}$.

Table 7-1
20 Year Economic Life, Managua Region

| Group | $P_{D}$ | $R_{D}$ | $A_{D}$ | $P_{C}$ | $R_{C}$ | ${ }_{C} A_{C}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| B | $20 \%$ | 90 | .33 g | $10 \%$ | 190 | .38 g |
| C | $50 \%$ | 30 | .24 g | $20 \%$ | 90 | .33 g |
|  | $70 \%$ | 17 | .20 g | $50 \%$ | 30 | .24 g |

Table 7-2
20 Year Economic Life, Leon Region

| Group | $P_{D}$ | $R_{D}$ | $A_{D}$ | $P_{C}$ | $R_{C} P_{C}$ | $A_{C}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| B | $20 \%$ | 90 | 0.24 g | $10 \%$ | 190 | 0.26 g |
| $C$ | $50 \%$ | 30 | 0.20 g | $20 \%$ | 90 | 0.24 g |

Table 7-3
50 Year Economic Life, Managua Region

| Group | $P_{D}$ | ${ }^{R P} P_{D}$ | $A_{D}$ | ${ }^{P}{ }_{C}$ | ${ }^{R P}{ }_{C}$ | ${ }^{A_{C}}$ |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
| A | $20 \%$ | 225 | 0.40 g | $10 \%$ | 475 | 0.44 g |
| B | $50 \%$ | 72 | 0.32 g | $20 \%$ | 225 | 0.40 g |
| C | $70 \%$ | 42 | 0.27 g | $50 \%$ | 72 | 0.32 g |

Table 7-4
50 Year Economic Life, Leon Region

| Group | $P_{D}$ | $R_{D}$ | $A_{D}$ | ${ }^{P_{C}}$ | ${ }^{R P_{C}}$ | ${ }^{A_{C}}$ |
| :--- | ---: | ---: | ---: | ---: | ---: | :--- |
| A | $20 \%$ | 225 | 0.26 g | $10 \%$ | 475 | 0.30 g |
| B | $50 \%$ | 72 | 0.23 g | $20 \%$ | 225 | 0.26 g |
| C | $70 \%$ | 42 | 0.21 g | $50 \%$ | 72 | 0.23 g |

. Provide a structure with sufficient strength, stability, and deformation capacity such that condemnation of the structure will not result from the effects of earthquake ground motions of a level represented by $A_{C}$.
. While the possibility of significant damage is admissible with the moderate probability $P_{D}$, and the possibility of building condemnation is admissible with the small probability $P_{C}$, every prudent effort is to be made to prevent serious injury or death of the building occupants. This life safety objective requires that the details of both the structural and non-structural elements, and the complete structural system are such that neither injurious system failures, injurious falling debris, nor structural collapse will result from ground motions of a level represented by $A_{C}$.

The practical consequence of this last objective is that only those types of structural systems which are capable of retaining their integrity and stability at deformations at and beyond the $A_{C}$ level are to be used.

Within these systems, the details of the connections between structural elements must tie the structure together, and the elements themselves must not have brittle or sudden buckling modes of failure. Multiple systems of frames, or back-up systems in the form of shear wall or vertical bracing must provide a series of lateral force resisting systems such that vertical load capacity is maintained for earthquake deformation demands at and reasonably beyond the $A_{C}$ level.

The complete set of structural design objectives is shown in Figure 7-1. Since the demands of earthquake ground motions create nonlinear structural behavior, this figure indicates the critical design thresholds of damage $\Delta_{D}$ and condemnation $\Delta_{C}$ in terms of structure deformation $\Delta$ rather than forces. The solid line coordinate system represents the probability density function $f(\Delta)$ of Earthquake Deformation Demands $\Delta_{\text {DEM }}$ which may occur on a given structure during a life L. The dotted line system indicates the load $V$ versus deformation capacity $\Delta_{\text {CAP }}$ curve of a given structure which satisfies the stated design objectives. Specifically, the structure has been designed such that its deformation capacities are equal to or greater than the earthquake demands at the damage and condemnation threshold levels. The earthquake of level $A_{D}$ with probability of exceedence $P_{D}$ does not exceed the damage capacity level $\Delta_{\text {DAM }}$, and the earthquake having the condemnation level $A_{C}$ with probability $P_{C}$, does not exceed the condemnation capacity level $\Delta_{\text {CON }}$. Further, the structure loaddeformation curve maintains a reasonably constant level for even those highly improbable deformations which might reasonably exceed the condemnation level. This latter characteristic insures the stability of the structure against collapse.

The purpose of this chapter is two-fold. First, the response spectrum method of analysis will be described as the means of relating the AZG values $A_{D}$ and $A_{C}$ to their corresponding earthquake demands ${ }_{D}$. and $\Delta_{C}$ on a given structure. Second, the complete design procedure will be developed such that the resulting structure will have the necessary design requirements of $\Delta_{D A M} \geq \Delta_{D}$ and $\Delta_{C O N} \geq \Delta_{C}$. In addition,


FIGURE 7.1
the types of structural systems and details necessary for the Iife safety requirement of collapse prevention will be defined. The analysis and design procedures will follow the general concepts as set forth in reference 28. The order of the subjects to be treated are as follows:

- Basic Response Spectra:

Definition of an earthquake response spectrum for an ideal elastic single-degree-of-freedom system; Effective ground acceleration as a working measure of spectral size or level; Spectral shape in terms of the dynamic amplification factor (DAF), its mean and standard deviation ( $\sigma$ ) value; the effect of the damping ratio ( $\beta$ ); the effect of inelastic behavior as represented by the ductility ratio ( $\mu$ ) ; site or soilcolumn response effects on the average ground motion values.

- Response Spectrum Analysis:

Response of multi-degree of freedom systems as the square root of the sum of the squared response of each mode to a given spectrum (SRSS response); use of the SRSS response to an inelastic response spectrum as an approximation of inelastic system response.

- Types and Characteristics of Lateral

Force-Resisting Systems in Buildings:

Ductile frames; shear walls; walls and ductile frames; walls and ordinary frames; the effect of the choice of system type on the accomplishment of the design objectives.

- Design Spectra:

Definition and purpose of design spectra for the damage and collapse threshold earthquakes; spectral level established by the effective ground acceleration A for a given structure use group and life L; spectral confidence limits $k \sigma$ for structural system types;
> structure-foundation interaction effects; subjective assignment of $\mu, \beta$, and $\kappa \sigma$ for given structural system types; formulation of a set of example design spectra.

- Proposed Design Method:

Earthquake loading as provided by the SRSS response to the Design Spectra; structure modeling for dynamic modal analysis; Dead, Live, and earthquake Load combination; design on an ultimate strength basis; calculation of inelastic deformation-demands and comparison with allowable ductility limits, and stability limits.

It is important to emphasize that the response spectrum analysis and corresponding design procedures are to be presented in a general descriptive form in this report. The current practice of seismic design is such that these methods are still in a state of development within the design profession. They represent, however, the most effective practical means of achieving the design objectives and are to be developed in detail in the proposed Part II of this study.

## Basic Response Spectra

The earthquake response spectrum is to provide the analytical model by which the $A Z G$ values of $A_{D}$ and $A_{C}$ are to be related to structural load values. These load values, in turn, are to be employed within an appropriate design procedure to provide the necessary sizes and proportions of structural elements required to satisfy the design objectives. Before going into the method of formulating what may be termed as structural design spectra, it is necessary to describe the basic spectral characteristics and parameters. These include: size or level, shape, confidence limit, damping, and ductility. (A typical basic response spectrum is shown in Figure 7-2.)


Definition of an Earthquake Response Spectrum:
For a given accelerogram or time history of earthquake ground motion, the ordinate $S_{a}(\beta, T)$ of the acceleration response spectrum (shown in Figure 7-2) is the maximum effective acceleration response felt by an elastic single-degree-of-freedom system, having a damping ratio $\beta$ and natural period of vibration $T$.

Basic Response Spectra:
Figures $7-3$ and $7-4$ show response spectra plotted on special three-way logrithmic paper. They represent the type of basic spectral shape as proposed by Newmark in reference 29 , and as extracted in Appendix 5 of this report. The Newmark method of spectrum construction is representative of current practice and is employed for the purpose of this report. Basically, it consists of the following steps:

- Three straight lines representing constant acceleration, velocity, and displacement are used for the ground motion base line. The acceleration leg $A_{g}$ is the peak effective ground acceleration from the AZG, either $A_{D}$ or $A_{C}$. These $A_{g}$ values set the level of the spectrum; and the ground velocity $V_{g}$ and displacement $D_{g}$ are proportional to this given $A_{g}$ value.
. The basic response spectrum for a given damping value $\beta$ is formed by multiplying the $A_{g}, V_{g}, D_{g}$ curve values by DAF values. In the Newmark method these DAF values are at about two standard deviations (2 $\sigma$ ) from the mean DAF shape.


FIGURE 7.3


FIGURE 7.4

Inelastic Response Spectra:
When the inelastic deformation response of ideal elastoplastic system is known in terms of the ductility factor $\mu$, then the inelastic force and inelastic deformation spectra may bc obtained by the rules given in the method and these are represented in Figure $7-5$. If the ideal system (with period $T$ ) were to have its yield strength level cqual to the Force at the Inelastic-Acceleration line, then the total inelastic deformation of the system is given by the Non-Elastic Displacement line.

Some improvements and modifications to this Newmark method which are to be introduced in this part I report, and subsequently developed in the Part II report, are as follows:

- The ground motion base line values and the resulting shape may need to be modified to represent the envelope of possible effects from the three principal sources of major earthquakes: Local Fault Systems, Volcanic Activity, and the Benioff Zone.
. The DAF in terms of its statistical mean value and standard deviation o must be evaluated for a macro-region which is representative of Nicaragua; see, for example, reference 30 for this type of study. A similar study as reference 30 will be prescribed for the Nicaragua region in part II of this report.
. The rules for forming the inelastic acceleration and


THE NEWMARK-HALL METHOD

FIGURE 7.5
inelastic displacement spectra must be modified to represent the actual inelastic behavior of structures rather than the given ideal elastic-plastic system behavior. In particular, the low period region of the inelastic displacemont spectrum might be better represented by a curve equal to or close to the elastic response spectrum; this is because a real structure must be designed for the inelastic acceleration forces, but in this low period region these forces are equal to the elastic acceleration forces and hence the structure remains clastic with the corresponding elastic (rather than the $\mu$ magnified inelastic) displacement value.

- Depending on the local site conditions, the response of the underlying soil column may be significantly different from average base line ground motion values. Therefore, soilcolumn adjustment factors must be evaluated to modify the basic $A_{g}, V_{g}, D_{g}$ lines of the spectrum. These factors would be applied for either shallow-stiff sites or for deep-soft sites.

Response Spectrum Analysis
Referring back to Figure 7-1, it is necessary for the designer to have some analytical method of computing the earthquake demands of $\Delta_{D}$ and $\Delta_{C}$. The method to be employed is modal analysis as described in reference 31. Briefly, this consists of the following steps:
. A linear elastic dynamic model of the structure is formulated, and the characteristic mode shapes and frequencies
are evaluated.
. For any given Response Spectrum, the force and displacement response of the linear model are assumed to be given by the square root of the sum of the squared response of each mode. This is termed as SRSS response.

- Design spectra are to be formulated (in a following section) such that: the SRSS response to the Damage Threshold Spectrum provides the demand $\Delta_{D}$, and the SRSS response to the condemnation Threshold Spectrum provides the demand $\Delta_{C}$. Since both $\Delta_{D}$ and $\Delta_{C}$ may be inelastic deformations, it is necessary to employ the assumption that inelastic structure deformations may be predicted by the elastic dynamic model response to the specially formulated inelastic design spectra. A detailed study of the validity of this assumption will be presented in part II of this report.

Types of Structures in Terms of Their Lateral Force-Resisting Systems

Before proceeding to formulate the Design Spectra, it is necessary to define and consider the inelastic behavior of the following structural systems:
. Ductile Moment Resisting Frames: (the $K=0.67$ system of the Uniform Building Code).

1.00MX
1.00MP

Same as 0.80 P , but with ordinary frames.

Same as 1.00 M , but with vertical bracing in place of walls.

Same as 1.00P, but with vertical bracing.

All systems are to have the necessary details required to insure the ductility and integrity of the system; these include: steel and reinforced concrete details for ductile and semi-ductile frames; chord, grid, and collector reinforcing for shear walls; details for vertical bracing systems; horizontal diaphram chords, drag, and shear connection to walls or bracing; and load transfer through construction joints. These details are best exemplified in references 32 and 33 .

For a given constant strength level the general inelastic behavior of the various general classes of systems is shown in Figure 7-6, and for a given stiffness or rigidity the behavior is as in Figure 7-7.

Clearly, from Figures $7-6$ and $7-7$ the $K=0.67$ systems have the advantage of large ductility, but for some cases they may not have the required rigidity for damage control; and, alternatively, the $K=1.33$ systems have the desired rigidity, but suffer from a lack of ductility. In addition to these properties; each system has its particular structural damping ratio $\beta_{S}$, and subjective reputation of dependable performance. All of these characteristics-rigidity, ductility, damping,


FIGURE 7.6


FIGURE 7.7
and dependability--must enter into the formulation of design spectra as given in the next section. However, before going into this formulation, it is well to treat a very important aspect of seismic design. This is the adoption of the appropriate structural system for the given structure configuration and earthquake demand conditions. Consider the following cases:

## Insufficient Rigidity of a $\mathrm{K}=0.67 \mathrm{M}$ Frame with $\Delta_{\mathrm{DAM}}<\Delta_{\mathrm{D}}$ (see Figure 7-8).

The adoption of the $K=0.80 \mathrm{M}$ system is preferable to the increase of section sizes in the original frame.

Insufficient Ductility of a $K=1.33$ Box System with $\Delta_{C O N}<\Delta_{C}$ (see Figure 7-9).

The formation of a $K_{1}=1.00 \mathrm{M}$ system is preferable to the general increase of section sizes in the original design. Even more dramatic in this case would be the consideration of a type of brittle pre-cast system (1.33 PC) of wall structure, where a strong back-up frame would be most essential for collapse safety.

## Design Spectra

In the section on Basic Response Spectra, two groups of spectral characteristics were discussed: those dealing mainly with ground motion such as the $A_{g}, V_{g}, D_{g}$ base lines and the site soilcolumn response factor; and those dealing with the elastic system such as the mean and standard deviation of the DAF, damping, and ductility. The $U_{\text {se }}$ Group of a structure has already been related to $A_{g}$, and the purpose of this section is to relate the actual structural character-



FIGURE 7.9
istics to spectral characteristics which deal with the ideal elastic system. Specifically,
. The confidence level or number of standard deviations $\mathrm{K} \sigma$ above the mean DAF is to be related to the structure Use Group and the reputation or dependability of the type of structural system.

- Damping is to be related to structural damping and struc-ture-foundation interaction.
. Ductility is to be related to the member ductility, connection details, and number of back-up frames or indetermineacies contained in the type of structural system.

Confidence Limit for the DAF:
The choice of spectral DAF levels based on the reputation or performance record of a structural system may be best explained in terms of the reliability levels or confidence limits of the amplified response spectrum (or DAF). It should be realized that the DAF values are random variables which can be described in terms of their average value and standard deviation ( $\sigma$ ) as shown in Figure 7-10. In the Newmark-Hall paper (Appendix 5), it is stated that the DAF values in Table 2 are such that there is only a 10 percent chance of being exceeded. This level would coincide roughly with the upper (two- $\sigma$ ) confidence level. It is proposed here, that the appropriate DAF confidence level may be different for different types of structural systems. If a system has proven to be reliable from past experience,


FIGURE 7.10
and can tolerate a fairly wide range of displacements before showing significant damage, and has back-up systems to prevent collapse--then it should merit a low confidence level (say the (one- $\sigma$ ) level) for its design spectrum. This is because the system can be depended upon to resist chance exceedences of the design level without failure.

On the other hand, if a system is new and untried, if it is brittle or not well connected, or has no reliable back-up system, then there is a need for that protection against chance excess demands as would be provided by the $2 \sigma$ exceedence level.

Therefore, for each type of structural system, an appropriate component $K_{T}$ of the confidence level will be assigned according to the system performance record.

Also, for the purpose of providing a desired level of protection for critical facilities, an additional component $K_{G}$ of the confidence level will be assigned according to the structure Use Group. The total confidence level for a given group and type is $\left(K_{G}+K_{T}\right) \sigma$ above the mean DAF. It should be recalled that in addition to this confidence limit, the ground acceleration base line $A_{g}$ for the spectrum has also been assigned from the AZG according to the accepted probability of exceedance as governed by the building use group.

Damping:
Damping due to the type of structural system is termed as $\beta_{S}$, and will be assigned according to the general material behavior. A new and additional component of damping occurs due to the effects of structure foundation interaction. This will be termed as $\beta_{F}$ and
will be evaluated in accordance with the methods in reference 34. Total damping for a design spectrum is therefore $\beta^{\prime}=\beta_{S}+\beta_{F}$.

Ductility:
Ductility varies with the type of structural system according to the material, member and connection details, and the number of statistical indeterminacies or back-up systems within the structure. Each structural type will be assigned a ductility value $\mu^{\prime}$ according to its particular description.

## Properties

The complete set of spectral properties for the different types of structural systems may be organized as shown in Table 7-5. The values are given for some example systems with a Use Group B. In general, the values are assigned by professional judgment to provide agreement with past experience, reported behavior, and a reasonable level for the final design load values.

Definition and Formulation of Design Spectra in Terms of Modified Inelastic Spectra

While it is generally recognized that the condemnation or collapse threshold level of earthquake motions must be resisted by structural behavior in the inelastic range, this report advances the concept that some inelastic behavior may be tolerated while resisting motions representative of the damage threshold earthquake. This concept is based on the fact that the structural damage threshold occurs at story deformations somewhat greater than the deformation at the attainment of first yield or design strength at the member section

Table 7-5
Given Use Group B, $K_{G}=1.0$

| Type | Damage Threshold |  | Collapse Threshold |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathrm{K}_{\mathrm{T}}$ | $\beta_{\mathrm{S}}$ | $\mu^{\prime}$ | $\mathrm{K}_{\mathrm{T}}$ | $\beta_{\mathrm{S}}$ | $\mu^{\prime}$ |
| 0.67 M | 1.00 | 0.05 | 1.5 | 1.00 | 0.05 | 4.00 |
| 1.00 M | 1.20 | 0.05 | 1.5 | 1.10 | 0.07 | 3.00 |
| 1.33 C | 1.50 | 0.05 | 1.5 | 1.20 | 0.07 | 2.00 |

having the highest stress ratio. Figure $7-11$ shows the states of strength design, damage threshold, and condemnation threshold.

The following discussion presents the definitions, methods, and reasoning employed for the formation of modified inelastic design spectra:

- the Damage Threshold Spectrum for strength determination (DTSS), for setting the design strength of members, and
. the Damage Threshold Spectrum for Deformation determination (DTSD), for the evaluation of P-Delta effects on design strength.
. the Condemnation Threshold Spectrum for Deformation determination (CTSD), for the evaluation of member ductility demand, and detection of instability problems due to P-Delta effects.

The modified, inelastic response, design spectra are formed by the use of what may be termed as spectral modification factors $\mu^{\prime}$ and $\beta^{\prime}$. These factors are used as ductility and damping factor values to obtain the inelastic spectra. They are selected by judgment, consistent with the respective ductility and damping capabilities of the particular type of lateral force-resisting system of a given structure; where these capabilities are as evidenced by test results and past performance of similar systems having undergone strong earthquake ground motions. Referring to Figure 7-12, the objectives are:

1) For the Damage Threshold Earthquake (DTEQ) the factors


WALLS


FRAMES

| DESIGN LEVEL $X$ | DAMAGE O | CONDEMNATION |
| :--- | :--- | :--- |
| AT ULTIMATE | TRESHOLD | TRESHOLD |
| STRENGTH BASIS |  |  |

FIGURE 7-11
$\mu_{D}^{\prime}, \beta_{D}^{\prime}$ are to produce an inelastic acceleration spectrum (see Figure 7-13) (DTSS) such that when members are designed on the ultimate strength basis for forces due to: (this is in accordance with the design procedure given in the next section)

- dead load
- code specified (non-load factored) live load
. DTSS Acceleration
- Extra story shear due to P-Delta effect at DTSD deformation
then it is assumed that the structural damage threshold deformation capacity will be equal or larger, with an acceptable level of reliability, than the deformation demands $\Delta_{D}$ of the damage threshold earthquake (DTEQ). If it is further assumed that the damage threshold demand is provided by the DTSD deformation, then it is important that the magnitude or size measure, the shape, and the $\mu_{D}^{\prime}$ and $\beta_{D}^{\prime}$ values be selected to provide DTSD values having the acceptable level of reliability (corresponding to an upper confidence limit). This damage threshold deformation demand assumption would allow study and formulation of drift limitations for control of non-structural damage.

2) For the Condemnation Threshold Earthquake (CTEQ) the factors $\mu_{C}^{\prime}, \beta_{C}^{\prime}$ are to produce an inelastic deformation spectrum (see Figure 7-14) (CTSD) that will provide deformation values reliably greater or equal to the deformation demand $\Delta_{C}$ of the CTEQ. Local member ductility demands and story stability


Modified Damage Threshold Spectra with $\mu_{D}^{\prime}$ and $\beta_{D}^{\prime}$ (Group B, Managua)
figure .7.13


Modified Collapse Threshold Spectra with $\mu_{C}^{\prime}$ and $\beta_{C}^{*}$ (Group, B Managua).
checks (involving $P$-Delta effects) evaluated for CTSD deformations will therefore be upper confidence limits for the CTEQ demands.

For this report, the purpose of the $H_{C}^{\prime}$ value is to produce a reasonable, but reliably large estimate of CTEQ deformations. For the formation of an inelastic deformation spectrum, a large value of $\mu_{C}^{\prime}$ provides conservative (large) values of deformation demand. If it were desired to employ an inelastic acceleration spectrum (CTSS) for the strength design of members, then a large $\mu_{C}^{\prime}$ value would of course provide nonconservative (low) force demand values. A proposed change to the Newmark method for construction of the CTSD is indicated in Figure 7-14. This may provide a more realistic estimate of actual structure deformation.

It is assumed in this report that the DTSS is larger than the CTSS and therefore controls the strength design of members. Examples of the design spectra DTSS and CTSD will be constructed later in this chapter, after the presentation of the complete proposed Design Procedure in the next section.

## Proposed Design Procedure

The DTSS and CTSD design spectra are to be employed in the following design procedure:

- Given Use Group, Life, and Site: Obtain $A_{D}, A_{C}, K_{G}$, and site soil-column response factor. The mean DAF and $\sigma$ values are known. (These will be available from Part II of this study.)


## - Given Structure Type and Foundation:

Obtain $\beta_{S}, \beta_{F}, \mu, K_{T}$ at both Damage $D$ and condermation $C$ levels.

## - Construct Design Spectra:

DTSS for Member Section Design, with $\mu_{D}^{\prime}, \beta_{D}^{\prime}=\beta_{S}+\beta_{F}$, $\left(K_{G}+K_{T}\right) \sigma$.

CTSD for Ductibility Evaluation and Stability Analysis, with $\mu_{C}^{\prime}, \beta_{\mathrm{C}}^{\prime}=\beta_{\mathrm{S}}+\beta_{\mathrm{F}},\left(K_{G}+K_{\mathrm{T}}\right) \sigma$.

- Formulate a Linear Elastic Model of the Structure and Find SRSS Value of:

1) Member Force Response to the DTSS;
2) Member Deformation Response to the CTSD.

- Design Members for Load Combinations on an Ultimate Strength Basis for:

1) Load Factored Vertical Dead and Live Load;
2) DTSS Force plus Vertical Dead and Live Load, and Seismic P-Delta Effects;
3) DTSS Force plus two-thirds Dead Load (for vertical acceleration effects). (See Appendix 6 for vertical acceleration effects.)

- Perform Deformation Analysis due to CTSD Response:

1) Evaluate local member ductility demands and compare with established allowablc values (to be determined in Part II of this report).
2) Investigate the stability of structural system.

Construction of Example Design Spectra
Given the structure use group, life $L$, and structural system type, such that the spectral values ( $A, K \sigma, \beta^{\prime}$, and $\mu^{\prime}$ ) can be determined for both the Damage and Condemnation Level Earthquakes. The basic elastic spectra may be constructed with these known $A, K \sigma$, and B' values. (Examples are shown in Figures 7-3 and 7-4.) Then, with the given $\mu_{D}$ and $\mu_{C}$ ductility values, the inelastic design spectra DTSS and CTSD are constructed according to the Newmark method in Appendix 5. The complete procedure is given in the following example for a structure in the Managua region.
. Structure Use Group: B.
. Region: Managua.
. Type of Structural System: 0.67 M .
. Economic Life L = 20 years.
. Site soil-column conditions are average such that the site factor $S=1.00$.
. Structure-Foundation Interaction Damping $\beta_{F}=0.05$.
. The ground acceleration base lines are found from Table 7-1.

$$
A_{D}=0.24 \mathrm{~g}, \quad A_{C}=0.33 \mathrm{~g}
$$

. The structural system properties are found from Table 7-5.

$$
\mathrm{K}_{\mathrm{G}}=1.0,
$$

For DTSS

$$
\mathrm{K}_{\mathrm{T}}=1.00, \beta_{\mathrm{S}}=0.05, \mu_{\mathrm{D}}=1.5
$$

For CTSD

$$
K_{T}=1.00, B_{S}=0.05, \mu_{C}=4.00
$$

- The Spectral Properties are:

For DTSS

$$
\begin{aligned}
& \beta_{D}^{\prime}=\beta_{F}+\beta_{S}=0.10, \mu_{D}^{\prime}=1.5 \\
& K=K_{G}+K_{T}=2.0, K \sigma=2 \sigma
\end{aligned}
$$

## For CTSD

$$
\beta_{C}^{\prime}=\beta_{F}+\beta_{S}=0.10, \mu_{C}^{\prime}=4.00
$$

. The Basic Elastic Response Spectra for these properties are constructed and are as shown in Figures 7-3 and 7-4.

- The modified inelastic Design Spectra DTSS and CTSD are constructed and shown in Figure 7-15.

It is interesting to see how design load values from this spectrum compare with loads from the Uniform Building Code. Let us consider a 10 story, Type 0.67 M steel frame building with first mode period of 1 second. From Figure $7-15$, the acceleration $S_{a}=0.14 \mathrm{~g}$, and the resulting base shear value would be about

$$
V_{1}=(0.14)(0.8) W=\underline{0.112} \mathrm{~W}
$$

where the 0.8 factor allows for the multi-mode response participation factors (or equivalent weights), and $W$ is the structure weight. Member forces from $V_{1}$ would be combined with Dead and un-factored Live Load forces for ultimate strength design. The corresponding UBC base shear is

$$
\begin{aligned}
\mathrm{V}_{2}=\mathrm{UKCW} & =1.4(0.67)\left(\frac{0.05}{3-\sqrt{1}}\right) \mathrm{W} \\
\mathrm{~V}_{2} & =\underline{0.047 \mathrm{~W}}
\end{aligned}
$$



Member forces from $V_{2}$ would be combincd with a load-factored value of 1.4 times the Dead and Live Load forces, for ultimate strength design. Therefore, although the $V_{1}$ is 2.4 times the $V_{2}$ value, the resulting $V_{1}$ member designs will not differ from the $V_{1}$ dosigns by as much as this amount because of the different method of factoring the Dead and Live Load effects.

It should be realized that these resulting spectra are for example only. The assigned spectral property values are very approximate. These values are to be refined in Part II of this study in order to provide consistent Design Spectra for all Use Groups and Structural Types.

## CHAPTER VIII

SUMMARY, CONCLUSIONS AND FURTHER RESEARCH

Summary
In Part I of the seismic risk study for Nicaragua, the following topics are presented:

1. Geological setting for the country in general and the Managua area in particular.
2. Data base for past seismic events was extensively studied. Limitations of the data and approximations were discussed. Seismic recurrence for ten line sources and three area sources was developed.
3. Based on the assumption of the Poisson occurrence of seismic events, probabilities of exceeding different magnitude levels as functions of time for different regions was derived. Using Esteva's attenuation relationship, isoacceleration maps for the country were constructed. Eleven cities in Nicaragua were considered in this mapping process. Cumulative distribution functions of peak ground accelerations for 20 and 50 years were established. This was shown to be one way of presenting seismic risk for Nicaragua.
4. Based on iso-acceleration maps, the Acceleration Zone

Graphs (AZG) were developed for the eleven cities. A method of determining load levels for consistent risk for the whole country was discussed and suggested. It was proposed that charts such as AZG be used for seismic zoning of Nicaragua.
5. Another parameter, the MMI scale, in understanding seismic risk was presented in probabilistic sense. Based on the damage data in the U.S.A., a method of determining insurance risk was presented.
6. Ground acceleration values from AZG were employed to set the level of the design spectra for structural damage prevention and condemnation control. A design methodology was proposed based on ultimate strength and loads resulting from the above inelastic design spectra.

## Conclusions

It can be concluded that there are sufficient data and analytical methods to provide adequate seismic zoning information on an acceptable risk criterion. The methods presented here are simple, easy to use and transferable to structural design procedures. The zoning of the country can be interpreted from iso-acceleration maps or from cumulative distribution plots of peak ground accelerations or from AZG. The method of zoning presented here is general and is completely amenable to availability of additional future data. From the current study, it can be clearly seen that the seismicity of Nicaragua varies significantly from region to region. The Managua region and
the region surrounding the line of volcanoes is much more seismic than the central or the eastern region. For example, Bluefields has the lowest probable loading level and the Managua region has the highest probable loading level. Looking at the iso-acceleration maps and AZGs, this information becomes obvious.

It is also obvious that methodologies as presented in this report can be used to convert the loading information based on acceptable risk and economic life of the facility to the structural design process. Further insight can be obtained regarding insurance and economic risk in different parts of the country based on the method presented in this report. Again, it can be seen that for a given region, it is cheaper to buy long-range seismic insurance than to purchase short-term coverage. Based on this insurance risk concept, various parts of the country can be compared for future probable economic impact due to a seismic event.

## Further Research

In order to implement and use the procedures presented in their general form in this report, the following tasks are to be accomplished in Part II:
. Refined seismic zoning of the country based on acceptable risk levels for different classes and uses of structures. A detailed look at the acceptable probability levels and their effect on cost and general economy.

- The concept of microzoning a given region in the country.
. Mapping information in the form of effective ground velocity values $V_{g}$ as predicted in terms of historical data and geological characteristics.
. Inclusion of the site (or soil-column) response factor in the evaluation of $A_{g}, V_{g}, D_{g}$ at a given structure location.
. Representation of foundation-structure interaction in the form of an additive component of structural damping $\beta_{F}$ and change in the structure period of vibration.
. Evaluation of the standard deviation values $\sigma$ and the mean values of the spectral DAF for a given region, with recognition of either the averaging or the predominance of the possible earthquake sources (Benioff Zone, Volcanic, and Local Faulting) as they affect the $A_{g}, V_{g}, D_{g}$ values.
- Formulation of a more precise listing of the Structure Use Groups ranging from critical to non-essential facilities; and establishment of the corresponding acceptable exceedance probability values $P$ for typical structure life times L.
- Assignment of the use Group contribution $K_{G}$ to the spectrum DAF confidence level.
. Elastic structure modeling techniques to allow reliable prediction by response spectrum analysis of structural element forces and inelastic deformations.
. Improvements in the method of forming the inelastic force and displacement response spectra.
- Categorization of the types of structural lateral force-
resisting systems and the assignment of the corresponding ductility $\mu$, damping $\beta_{S}$, and structure type contribution $K_{T}$ to the spectrum DAF confidence level, for both the damage and condemnation threshold spectra.
. Formulation of appropriate ultimate strength member design equations for all acceptable materials; specification of essential details necessary for the ductility and stability against collapse; and establishment of allowable ductility demand limits for all acceptable materials and systems.
- Simplification of the design spectrum, the dynamic analysis, and the deformation and stability analysis, to a procedure similar to that employed by the Uniform Building Code. This simplified design procedure would be applicable to the majority of structures. The detailed response spectrum analysis would be required only for those structures which are extremely critical, costly, and/or unique in their configuration and structural systems.
. With damage and economic data from Nicaragua, an insurance and economic risk analysis is to be accomplished. Risk to life and limb will be treated in Part II of this study.


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## APPFNDIX 1

THE DECEMBER 23, 1972 EARTHQUAKE

THE DECEMBER 23, 1972 EARTHQUAKE

## Introduction

The Managua Earthquake actually consisted of three tremors. The major shock, which registered a surface wave magnitude (Ms, NOAA) of 6.2 and a body wave magnitude ( Mb , NOAA) of 5.6 , was followed by two major aftershocks within one hour, with $\mathrm{Mb}=5.0$ and 5.2 , respectively. The quakes were relatively moderate in size, compared to other major earthquakes (e.g. San Francisco, 1906, $M=8.3$ ), but caused extensive damage because (1) the epicenters were shallow, (2) surface rupture occurred, and (3) many buildings were constructed with an adobe or taquezal type of construction.

## Intensity

The maximum intensity of shaking (Figures A1-1, A1-2), employing the Modified Mercalli Scale, was $X$ along the lakeshore, with VIT-IX common throughout most of the city center. (An intensity IX is defined as follows: "Damage considerable in specially designed structures; well-designed frame structures thrown out of plumb. . . . Buildings shifted off foundations. Ground cracked conspicuously. Underground pipes broken." (Reference 7, p. 59.)

The intensity decreased radially outward from the city center (reference 15, p. 18). Near the epicenter, however, intensity contours


Figure A1-1 Isoseismal Map of Nicaragua
After Hansen and Chavez, 1973
parallel the active faults, whereas southwest of the city they cross the faults. This suggests release of energy near the city center, rather than to the southwest (reference 4, p. 70).

## Shaking

"Duration of the earthquake in its destructive phase was about 7 seconds" (reference 3, p. 143). The shaking was described as "a series of vertical shakes, followed by horizontal motion, then a vertical 'drop.'" (Reference 15, p. 18.) Peak ground acceleration, recorded 7 km west of the city center, was 0.39 g (reference $15, \mathrm{p} .18$ ).

Damage
Damage occurred as ". . . two broad lanes of heavily damaged buildings of high density, separated by a stretch wherein heavy damage was expressed in a loose, random pattern." (Reference 2, p. 267.) The western lane was bordered by the 1931 fault trace; the eastern was situated between the Tiscapa Fault and the "secondary trace 400 m to the east" (Chico Pelon Fault) (reference 2, p. 267).

## Hypocenter Location

The original hypocenter calculation, based on P-wave arrivals, was by NOAA. The location, 27 km northeast of the city center, was erroneous for two reasons: (1) a poor seismic net exists for Central America, and (2) the standard P-wave trend-time tables are incorrect for this area. The "correct" determination, based on an accelerogram recorded at a nearby refinery, placed the hypocenter beneath the center of the city, at a depth no greater than 8 km . This placement
has led to a better location of the Benioff Zone in Central America by relocating previous earthquake hypocenters, based on the erroneous velocity data, to the south (reference 4, pp. 66, 70, 75). Aftershock data substantiate the accelerogram hypocentral location, although the depth indicated is $8-10 \mathrm{~km}$, and show three zones of activity. The zones are shown in Figures A1-3 to A1-5.

P-wave first motions, recorded at telescismic distances, are consistent with fault plane movement parallel to the mapped surface fault traces within the city. It is probable that the major seismic zone, striking $\mathrm{N} 30-40^{\circ} \mathrm{E}$ and dipping from $74^{\circ} \mathrm{W}$ to $82^{\circ} \mathrm{E}$, with a 1 km width, bifurcates near the surface into 2 fault traces, the Tiscapa and Chico Pelon Faults. This is supported by the observations that the two faults are at the most only a few hundred meters apart, they trend towards an intersection, and they display roughly equal amounts of displacement from the 1972 tremors. . The zone passes through Laguna Tiscapa and the Customs House, and is within 1500 m of nearly all of the severely damaged part of Managua. Aftershock data also suggest left-lateral movement, the same as that observed on the ground. The fault zone responsible for the major portion of the seismic energy was about 15 km long (reference 4, pp. 66, 71; reference 11, p. 97; reference 18, p. 95; reference 14, pp. 115, 127).

Nature and Amount of Fault Movement
Movement was predominantly sinistral, or left-lateral, al-
though local dextral (right-lateral) and normal, or vertical slip, did occur. The faults are manifested in unconsolidated sediments and


FigureAl-3Locations of 171 aftershocks. The polygons represent the error in location assuming a possible error in reading arrival times at each station of 0.1 second. Station locations are designated by stars. The wide solid line in Managua represents faults $B$ and $C$ mapped at the surface (Plate 1, Brown and others, 1973).


Fig. Al-4 Intensity map for the main shock and epicenters of 300 aftershocks $10-$ cated by data from a 5 -station seismic array. At least two linear trends in the aftershock activity are suggested, as indicated by the dashed lines.

After Matumoto and Latham, 1973

 (1971)(light dashed line).
After Dewey, et al, 1973
volcanics by en echelon, rather than continuous fractures. The strike of these fractures is generally more northerly than that of the fault zones themselves. The faults die out within $1.6-5.9 \mathrm{~km}$ of Lago de Managua.

The maximum horizontal displacement, determined by triangulation, was 40 cm . Maximum vertical movement measured was 10.2 cm .

According to Plafker and Brown, a geometric reconstruction of Tiscapa Crater and the lakefront suggest 10 m sinistral and 30 m vertical displacement. Noting that 1972 movement was predominantly sinistral, they suggest that there has been a late Holocene (past 1,000-2,000 years) change in the tectonic deformation style (reference 14, p. 134). Their geometric reconstruction is open to interpretation, however. In addition, it is possible for an individual seismic trend to be in apparent conflict with the overall, long-term trend.

## Cause of the Earthquake

A number of hypotheses have been advanced to explain the earthquake mechanism. They relate to various interpretations of the tectonic setting of Nicaragua.

The 1972 earthquake hypocenter was much too shallow to be related to the underlying Benioff Zone. It was probably caused by tectonic forces associated with the Nicaragua Depression and/or with the chain of volcanoes. This earthquake was typical of numerous Central American tremors, which, although responsible for only a small fraction of the total seismic energy released in the region, and which are of small or moderate magnitude, nevertheless produce intense ground
shaking in small, often densely populated areas (reference 4, p. 67).
One explanation of the earthquake relates the tremblors to isostatic and gravity conditions. There is a correlation of earthquakes in the Managua area with years of drought, which is reflected in surface levels of Lago de Managua falling as much as 3.77 m . It is suggested that the low lake level leads to a decrease in weight from the lake onto the earth's crust below. Resisting forces, in years of low lake levels, are thus in excess of equilibrium, strains build up, and earthquakes result. In addition, there is a correlation of earth tide maximums with the 1931,1968 , and 1972 quakes (reference 16 , pp. 56-60). One problem with this theory is that it postulates upward movement of the block, whereas slight subsidence, in addition to horizontal movements, in fact occurred. However, earthquakes have been recorded during the loading and unloading of reservoirs, and the decreases in water levels could have been the triggering force needed to initiate rupture along faults already at maximum stress.

A second theory "explains" both the left-lateral offset within Managua and the right-lateral offset of the Cordillera de Marrabios. It suggests that the chain of volcanoes is a secondary spreading center, analogous to the East Pacific Rise or Mid Atlantic Ridge. The rift is thus a zone of crustal extension, a fact suggested by the general structure of the Nicaragua Depression. The entire rift is being pulled apart in the fashion shown in Figure Al-6, but with irregular breaks, known as transform faults. Movement on such a transform fault would show left-lateral displacement within Managua, located within the zone of extension between offsets of the ridge, or

volcanics, yet beyond the immediate area of the city both sides of the fault would show movement in the same direction (reference $4, \mathrm{pp}, 82-$ 84). This theory is attractive because it suggests an explanation for several geologic phenomena. It is especially useful because it predicts earthquakes for two other parts of the Nicaragua Depression, where the Cordillera de Marrabios is offset.

A third theory ascribes the concentration of seismic activity near the Nicaragua volcanics to an unusually thin, rigid lithosphere, resulting in the crust being subjected to unusually high tectonic stresses. Although both north-south compression or east-west tension could produce the observed pattern, geologic evidence favors the latter (reference 4, pp. 84-85). This explanation fits with the apparent tensional nature of the Nicaragua Depression, as well as regional plate movements, and also the observed left-lateral movement of the faults in Managua, but does not explain the line of volcanoe offset. Such a stress system could be caused by movement of the Caribbean Plate (Eastern Nicaragua) eastward, while the Cocos Plate (Pacific Ocean) travels north and plunges under Central America (reference 11, p. 102).

The final theory is that right-lateral offset is occurring along the Cordillera de Marrabios (Figure A1-7). Extension occurs at a kink, and left-lateral oblique faults, members of the conjugate shear set, form (reference $15, \mathrm{p} .12$ ). This explanation is similar to the preceding one, but fails to explain the cause of the kinking, extension, or the origin of the volcanics. Although volcanoes do occur along fault zones, we are not aware of any cases where the line of


FigureAl-Mechanism for Diastrophism in the Managua Area. (A) Right lateral displacement of the Pacific coastal block tends to produce a gap if a fracture, kinked to the right is slipped in a right handed sense. After Brouwer.
(B) In the Managua area, a series of normal left-lateral oblique faults are members of the conjugate shear set produced by extension and by a shear resulting from a northwesterly aligned dextral couple.

After Saint-Amand, 1973
volcanics is so straight or so long.
It is not possible to conclude the cause of the tectonic pattern around Managua. The transform fault explanation seems to be the most reasonable, because it explains all of the observed phenomena. However, it presupposes an interpretation of Plate Tectonics which has not, for this region, at least, been proven. Further detailed work is needed. The explanation will aid in interpretations of the entire Nicaragua Depression.

APPENDIX 2

MODIFIED MERCALLI INTENSITY SCALE

# THE MODIFIED MERCAILI INTENSITY SCALE 

Mercalli's (1902) improved intensity scale served as a basis for the scale advanced by Wood and Neumann (1931), known as the modified Mercalli scale and commonly abbreviated MM. The modified version is described below with some improvements by Richter (1958). The following remarks are taken almost verbatim from Elementary Seismology, Charles F. Richter (W. H. Freeman and Company, San Francisco, copyright (C) 1958).
To eliminate many verbal repetitions in the original scale, the following convention has been adopted. Each effect is named at that level of intensity at which it first appears frequently and characteristically. Each effect may be found less strongly, or in fewer instances, at the next lower grade of intensity; more strongly or more often at the next higher grade. A few effects are named at two successive levels to indicate a more gradual increase.

Masonry $A, B, C, D$. To avoid ambiguity of language, the quality of masonry, brick or otherwise, is specified by the following lettering (which has no connection with the conventional Class $A, B, C$ construction).

Masonry A. Good workmanship, mortar, and design; reinforced, especially laterally, and bound together by using steel, concrete, etc.; designed to resist lateral forces.

Masonry B. Good workmanship and mortar; reinforced, but not designed in detail to resist lateral forces.

Masonry C. Ordinary workmanship and mortar; no extreme weaknesses like failing to tie in at corners, but neither reinforced nor designed against horizontal forces.

Masonry D. Weak materials, such as adobe; poor mortar; low standards of workmanship; weak horizontally.

Modifed Mercalli Intensity Scale of 1931 (Abridged and Rewritten by C.F.
Richter.)

1. Not felt. Marginal and long-period of large earthquakes.

Taken From "Fundamentals Of Earthquake Engineering"
N.M.Newnark and E.Rosenblueth. Prentice Hall.
2. Felt by persons at rest, on upper floors, or favorably placed.
3. Felt indoors. Hanging objects swing, Vibration like passing of light trucks. Duration estimated. May not be recognized as an earthquake.
4. Hanging objects swing. Vibration like passing of heavy trucks; or sensation of a jolt like a heavy ball striking the walls. Standing motor cars rock. Windows, dishes, doors rattle. Glasses clink. Crockery clashes. In the upper range of 4, wooden walls and frames crack.
5. Felt outdoors; direction estimated. Sleepers wakened. Liquids disturbed, some spilled. Small unstable objects displaced or upset. Doors swing, close, open. Shutters, pictures move. Pendulum clocks stop, start, change rate.
6. Felt by all. Many frightened and run outdoors. Persons walk unsteadily. Windows, dishes, glassware broken. Knickknacks, books, and so on, off shelves. Pictures off walls. Furniture moved or overturned. Wcak plaster and masonry D cracked. Small bells ring (church, school). Trees, bushes shaken visibly, or heard to rustle.
7. Difficult to stand. Noticed by drivers of motor cars. Hanging objects quiver. Furniture broken. Damage to masonry $D$ including cracks. Weak chimneys broken at roof line. Fall of plaster, loose bricks, stones, tiles, cornices, unbraced parapets, and architectural ornaments. Some cracks in masonry $C$. Waves on ponds; water turbid with mud. Small slides and caving in along sand or gravel banks. Large bells ring. Concrete irrigation ditches damaged.
8. Steering of motor cars affected. Damage to masonry $C$; partial collapse. Some damage to masonry $B$; none to masonry $A$. Fall of stucco and some masonry walls. Twisting, fall of chimneys, factory stacks, monuments, towers, elevated tanks. Frame houses moved on foundations if not bolted down; loose panel walls thrown out. Decayed piling broken off. Branches broken from trees. Changes in flow or temperature of springs and walls. Cracks in wet ground and on steep slopes.
9. General panic. Masonry $D$ destroyed; masonry $C$ heavily damaged, sometimes with complete collapse; masonry $B$ seriously damaged. General damage to foundations. Frame structures, if not bolted, shifted off foundations. Frames racked. Conspicuous cracks in ground. In alluviated areas sand and mud ejected, earthquake fountains, sand craters.
10. Most masonry and frame structures destroyed with their foundations. Some well-built wooden structures and bridges destroyed. Serious damage to dams, dikes, embankments. Large landslid s. Water thrown on banks of canals, rivers, lakes, etc. Sand and mud shifted horizontally on beaches and flat land. Rails bent slightly.
11. Rails bent greatly. Underground pipelines completely out of service.
12. Damage nearly total. Large rock masses displaced. Lines of sight and level distorted. Objects tirown into the air.

Other commonly used intensity scales include those of Rossi-Forel (Rossi, 1883; Forel 1884), Cancani (1904), Sieberg, (1923), and Medvedev (1953). The latter is known as the Soviet scale and roughly coincides with the MM intensity scale. Also roughly equivalent is the MSK scale (Medvedev and Sponheuer, 1969). The other scales are falling slowly into disuse. The same is true of the Japanese, Chilean, and other systems of intensity grading that have enjoyed some degree of popularity at national or regional levels.

A now classical piece of work on earthquake intensity and its relation with magnitude is found in a paper by Gutenberg and Richter (1942 and 1956).

APPENDIX 3

LISTING OF EARTHQUAKES

EARTHQUAKES SORTED GY SOURCES
**************か**************

| S | D | $M \quad Y$ | H | M | S |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A 0 | A | 0 E | 0 | 1 | E |  |  |
| U | $\gamma$ | N | $U$ | N | C |  |  |
| R |  | $T \mathrm{R}$ | R | U | 0 |  |  |
| C |  | $T$ |  | 1 | N |  |  |
| E |  |  |  | E | 0 | Tu0 |  |
| * BENICFF |  | 5 TO 39 KM |  |  | (159) |  |  |
| NOS 45 | 18 | 0671 | 133 | 360 | 01 | 14.678 N |  |
| CGS-B | 30 | 0167 | 093 | 302 | 27 | 12.196 N |  |
| CGS 54 | 15 | 0869 | 014 | 431 | 11 | 09.473 N | 83.863 H |
| CGSPDE | 14 | 0768 | 035 | 552 | 24 | 15.23 N | 88. 843 H |
| CGS 15 | 25 | 0269 | 020 | 014 | 44 | 15.274 N | 87.54.4W |
| CGS 15 | 25 | 0269 | 073 | 390 | 00 | 15.231 N | 87.466W |
| CGS 71 | 16 | 1068 | 060 | 084 | 45 | 13.893 N | 88. 250 W |
| CGS-8 | 15 | 0664 | 111 | 134 | 47 | 12.600 N | 88.000W |
| CGSPDE | 23 | 0667 | 133 | 304 | 46 | 12.900 N | 87. 800 H |
| CGSPDE | 13 | 1167 | 160 | 054 | 46 | 10.400 N | 85.700 H |
| CG SPDE | 14 | 0368 | 100 | 091 | 19 | 12.00 ON | 86.800 W |
| CGS 23 | 19 | 0369 | 194 | 492 | 22 | 11.786 N | 88.087 W |
| ERL 65 | 02 | 1172 | 182 | 244 | 45 | 11.711 N | 87.939W |
| CG 5-B | 20 | 0864 | 082 | 265 | 52 | 11.70 ON | 87. 200 W |
| ERL 71 | 11 | 1272 | 125 | 510 | 04 | 11.403 N | \& 7.151W |
| CGS-8 | 23 | 0665 | 073 | 374 | 46 | 11.430 N | 87.800W |
| CG S-B | 31 | 0565 | 204 | 465 | 54 | 11.100 N | 86.000 W |
| CGSPDE | 11 | 0867 | 122 | 261 | 18 | 11.800 N | 85.900 |
| CGSPDE | 03 | 1067 | 181 | 1603 | 03 | 10.900 N | 85.900W |
| CGS-B | 19 | 1166 | 160 | 014 | 46 | 09.200N | 85.800 W |
| ERL 74 | 25 | 1272 | 002 | 26 | 28 | 15.215 N | 88.943W |
| CGSPDE | 04 | 1067 | 001 | 121 | 12 | 15.700 N | 88.600w |
| CGS-8 | 13 | 0366 | 214 | 462 | 23 | 14.200 N | 88.400w |
| CGS-8 | 09 | 0164 | 183 | 381 | 10 | 14.90 ON | 87.900 W |
| $\operatorname{CGS~} 16$ | 08 | 0269 | 045 | 565 | 59 | 13.624 N | 88. 27 lW |
| CGS-8 | 29 | 1064 | 122 | 215 | 52 | 13.200N | 88.500 W |
| CGS-8 | 24 | 0466 | 154 | 410 | 03 | 13.700 N | 88.300 W |
| CGSPCE | 06 | 1187 | 184 | 492 | 26 | 13.500 N | 98.000W |
| CGS-B | 27 | 1164 | 105 | 551 | 11 | 13.400 N | 88.700 W |
| CGSPDE | 03 | 0468 | 000 | 060 | 00 | 12.20 NN | 88.300W |
| CGS-8 | <3 | 0866 | 060 | 073 | 36 | 12.400 N | 88.200w |
| CGEm | 15 | 0864 | 144 | 4303 | 03 | 12.000 N | 88.000W |
| CGS-8 | 16 | 0466 | 132 | 214 | 40 | 12.300 N | 88.400 W |
| CGS 65 | $C 1$ | 1069 | 084 | 413 | 31 | 12.084 N | 88.358 ${ }^{\text {d }}$ |
| CGS-B | 12 | 0165 | 031 | 191 | 10 | 12.300 N | 88.900 W |
| CGS-B | 29 | 0464 | 080 | 08 | 41 | 12.10 NN | 88.400 W |
| CGS-8 | 08 | 0567 | 144 | 40 | 08 | 12.974 N | 88.073 W |
| CGSPDE | 19 | 0968 | 003 | 371 | 17 | 12.143 N | 88.714W |
| ERL 47 | 04 | 0873 | 115 | 54 | 16 | 12.140 N | 88. 983 W |
| CGS-B | 30 | 0765 | 063 | 333 | 30 | 12.030N | 88.500w |
| CGSm | 07 | 1164 | 013 | 365 | 56 | 12.000 N | 88.000 |
| CGS-B | 16 | 1263 | 062 | 232 | 20 | 12.200 N | 88.400 N |
| CGS-8 | 21 | 1165 | 021 | 191 | 12 | 12.100 N | 88.900 W |
| CGS 41 | 23 | 0669 | 204 | 464 | 40 | 12.410 N | 88.052 W |
| 6GS-B | 12 | 0466 | 173 | 30 | 49 | 12.600 N | 88.000W |
| CGS-8 | 12 | 0467 | 045 | 562 | 25 | 12.2174 | 88.102W |
| $6 \mathrm{GS-8}$ | 03 | 1264 | 145 | 511 | 10 | 12.300 N | 88.500 W |
| G S-B | 23 | 0365 | 025 | 58 | 39 | 12.30 | 88.20 |


|  |  |  |  |  |  |  |  |  |  |  |  | A3-3 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| cgspoe | Cl | 04 | 68 | 07 | 28 | 28 | 12.4000 | 88.500w | 33 | 440 Mz | 076 | 0 |  | 0 | 013 | 379 |
| CGS-B | 06 | 11 | 63 | 21 | 49 | 57 | 12.200N | 88.000w | 37 | 410MB | 076 | 0 |  | 0 | 010 | 329 |
| C6, S-B | 24 | 07 | 66 | 18 | 50 | 54 | 12.200 N | 88.700 W | 33 | 410 ME | 076 | 0 |  | 0 | 010 | 329 |
| CGS-B | 15 | 04 | 67 | 22 | 10 | 08 | 12.743 N | 88.163 W | 33 | 430M8 | 076 | 0 |  | 0 | NOO ${ }^{\text {\% }}$ | 362 |
| CGS-B | 16 | 08 | 64 | 12 | 34 | 34 | 12.000N | 88.60 CW | 33 | 430 mB | 076 | 0 |  | 0 | 011 | 362 |
| Cos-B | 27 | 09 | 65 | 1.7 | 37 | 53 | 12.900 N | 88.400 W | 33 | 420 MB | 076 | 0 |  | 0 | 007 | 345 |
| CGS-B | 10 | 12 | 65 | 17 | 59 | 11 | 12.400 N | 87.300 H | 33 | 420 Me | 074 | 0 |  | 0 | 011 | 345 |
| CGS-B | C8 | 09 | 63 | 05 | 28 | 37 | 12.330 N | 87.900 W | 31 | 410 NB | 074 | 0 |  | 0 | 008 | 329 |
| FRL 30 | 07 | 05 | 73 | 11 | 54 | 36 | 12.344V | 87.949W | 33 | 430 NB | 074 | 40 MS |  | 0 | NO13 | 400 |
| ERL 5E | 28 | 09 | 72 | 03 | 20 | 16 | 12.231 N | 87.412H | 37 | 460 ME | 074 | 38 MS |  | 0 | 016* | 380 |
| cos 38 | 13 | 05 | 89 | 16 | 39 | 27 | 12.447 N | 87.83 OW | 33 | 420 MB | 074 | 0 |  | 0 | N007* | 345 |
| $665-8$ | 27 | 06 | 65 | 13 | 08 | 28 | 12.600 N | 87.900 W | 33 | 410 MB | 074 | 0 |  | 0 | 007 | 329 |
| C.GS-8 | 02 | 04 | 64 | 03 | 48 | 59 | 12.50 ON | 87.800W | 32 | 420 MB | 074 | 0 |  | 0 | 009 | 345 |
| ISS | 20 | 11 | 52 | 15 | 37 | 17 | 12.100 N | 87.500 W | 33 | 0 | 074 | 0 |  | $625 P A S$ |  | 625 |
| C3S-8 | 17 | 06 | 64 | 09 | 11 | 42 | 12.000 N | 87.200W | 33 | 410 MB | 074 | 0 |  | 0 | 008 | 329 |
| CGS-8 | 23 | 12 | 66 | 22 | 10 | 25 | 12,630N | 87.700 W | 32 | 450 ME | 074 | 0 |  | 0 | 019 | 395 |
| $\cos 48$ | 05 | c7 | 70 | 05 | 42 | 05 | 12.561 N | 87.448N | 33 | 450 MB | 074 | 0 |  | 0 | NO31 | 395 |
| GS 51 | 27 | 07 | 73 | 08 | 51 | 11 | 12.415 N | 87.407W | 33 | 450 MB | 074 | 0 |  | 0 | ND1 7* | 395 |
| -GS-8 | 24 | 04 | 65 | 13 | 25 | 41 | 12.70 ON | 82.000w | 33 | 440 MB | 094 | 0 |  | 0 | 009 | 379 |
| C.6S-B | 16 | 07 | 65 | 10 | 34 | 12 | 11.600 N | 88.000w | 30 | 490阴 8 | 076 | 0 |  | 0 | 022 | 462 |
| CGS-8 | 23 | 03 | 65 | 17 | 18 | 29 | 11.830 N | 88. 200 W | 33 | 42 DMB | 076 | 0 |  | 0 | 006 | 345 |
| cos-b | 18 | 04 | 67 | 08 | 24 | 17 | 11.41 gN | 88.415 W | 33 | 400 MB | 076 | 0 |  | 0 | N007* | 312 |
| vas 45 | 16 | 06 | 71 | 04 | 18 | 56 | 11.722 N | 88.222 W | 33 | 450 MB | 076 | 0 |  | 0 | NO1.2* | 395 |
| CGS-B | 18 | 06 | 65 | 09 | 28 | 21 | 11.500 N | 88. 200 W | 33 | 430 MB | 076 | 0 |  | 0 | 007 | 362 |
| EFL 66 | 27 | 08 | 71 | 09 | 21 | 57 | 11.839 N | 88.884W | 33 | 500 MB | 076 | 38 MS |  | 0 | NO41 | 380 |
| CGSPDE | 28 | 04 | 68 | 10 | 03 | 31 | 11.830 N | 88.800 W | 39 | 490 MB | 076 | 0 |  | 0 | 039 | 462 |
| CGS-B | 29 | 01 | 67 | 20 | 11 | 22 | 11.953 N | 88.923W | 33 | 450 mB | 076 | 0 |  | 0 | N01 8 | 395 |
| 二css | 28 | 05 | 66 | 14 | 34 | 39 | 11.900 N | 88.100W | 33 | 430 MB | 076 | 0 |  | 0 | 013 | 362 |
| C GS- 8 | 18 | 07 | 64 | 20 | 37 | 35 | 11.000 M | 87.000 W | 33 | 460 MB | 074 | 0 |  | 0 | 010 | 412 |
| CGS-B | 29 | 0.4 | 64 | 21 | 53 | 15 | 11.800 N | 87. 800 W | 33 | 450 MB | 074 | 0 |  | 0 | 007 | 395 |
| C.G S-B | $0 \times$ | 04 | 65 | 15 | 09 | 15 | 11.400 N | 87.400w | 33 | 420 MB | 074 | 0 |  | 0 | 009 | 345 |
| CGS-B | 1.4 | 04 | 66 | 06 | 57 | 45 | 11.830 N | 87. 500 W | 33 | 41 OM. | 074 | 0 |  | 0 | 007 | 329 |
| CG SPDE | 04 | 07 | 67 | 13 | 29 | 04 | 11.630 N | 87. 200 W | 33 | 420 MB | 074 | 0 |  | 0 | 010 | 345 |
| CGS-B | 22 | 03 | 85 | 00 | 17 | 27 | 11.900 N | 87.900 W | 33 | 430 MB | 074 | 0 |  | 0 | 007 | 362 |
| CGS-B | 16 | C7 | 65 | 11 | 21 | 10 | 11.630 N | 87.800w | 33 | 480 MB | 074 | 0 |  | 0 | 016 | 445 |
| CGS- ${ }^{\text {C }}$ | 04 | 10 | 64 | 06 | 30 | 14 | 11.300 N | 87.400 W | 33 | 420 MB | 074 | 0 |  | 0 | 007 | 345 |
| CGSPOE | 04 | 07 | 67 | 07 | 39 | 20 | 11.800N | 87.300w | 38 | 400 mb | 074 | 0 |  | 0 | 016 | 312 |
| NOS 8 C | 25 | 11 | 70 | 05 | 38 | 12 | 11.745 N | 87.920W | 36 | 480 Mg | 074 | 0 |  | 0 | $014 *$ | 445 |
| vos s | 11 | 01 | 71 | 17 | 13 | 48 | 11.714 N | 87. 79 44 | 33 | 480 MB | 074 | 0 | F | 0 | NO14* | 445 |
| 6GS 3 | 06 | 01 | 69 | 09 | 44 | 41 | 11.410 N | 87. 232 W | 33 | 430 MB | 074 | 0 |  | 0 | 011 | 362 |
| EGS 3 | C6 | 01 | 69 | 09 | 24 | 23 | 11.44 ON | 87.245 | 33 | 480 MB | 074 | 43 MS |  | 0 | N0 26 | 430 |
| CGS-8 | 06 | 04 | 85 | 08 | 34 | 17 | 11.1JON | 87.200w | 33 | 460 MB | 074 | 0 |  | 0 | 005 | 412 |
| CGS-B | 30 | 07 | 63 | 12 | 25 | 39 | 11.400 N | 87.300 W | 33 | 420 MB | 074 | 0 |  | 0 | 005 | 345 |
| CGS-8 | 29 | 08 | 64 | 20 | 51 | 54 | 11.40 ON | $87.200 \%$ | 33 | 420 MB | 074 | 0 |  | 0 | 005 | 345 |
| CGS-8 | 20 | 08 | 64 | 09 | 12 | 53 | 11.000 V | 87.50 cw | 33 | 420 MB | 074 | 0 |  | 0 | 008 | 345 |
| CGS-8 | 13 | 0.4 | 63 | 18 | 53 | 18 | 11.70 NN | 87.800w | 33 | 430 MB | 074 | 0 |  | 0 | 016 | 362 |
| C GS-B | 20 | 05 | 67 | 23 | 42 | 19 | 11.653 N | 86. 714 k | 33 | 420 mC | 074 | 0 |  | 0 | NO2* | 345 |
| CGS-B | 08 | 06 | 65 | 01 | 25 | 59 | 11.030 N | 86.800W | 33 | 470 MB | 074 | 0 |  | 0 | 007 | 428 |
| CGS 92 | 16 | 11 | 68 | 15 | 14 | 37 | 1.1 .082 N | 86.91 lW | 33 | 460 MB | 074 | 39MS |  | 0 | NO18 | 390 |
| CGS \& | 15 | 01 | 70 | 16 | 57 | 47 | 11.614 N | 86.929W | 33 | 480MB | 074 | 0 |  | 0 | NO08* | 445 |
| CGSPDE | 02 | 10 | 67 | 15 | 59 | 43 | 11.700 N | 86.800 W | 39 | 470 MB | 074 | 0 |  | 0 | 025 | 428 |
| $C G S-B$ | 12 | 09 | 64 | 19 | 05 | 47 | 11.200 N | 86.900W | 33 | 470 MB | 074 | 0 |  | 0 | 014 | 428 |
| $\operatorname{ccs} 89$ | 21 | 1.1 | 68 | 07 | 19 | 34 | 11.203N | 86.891 W | 33 | 450 MB | 074 | 0 |  | 0 | N016 | 395 |
| cgs-8 | 23 | 03 | 65 | 21 | 21 | 52 | 11.000 V | 86. 600 H | 33 | 480 MB | 074 | 0 |  | 0 | 014 | 445 |
| CCS-8 | 30 | 04 | 64 | 15 | 05 | 57 | 11.200 N | 86.700W | 33 | 430 MB | 074 | 0 |  | 0 | 005 | 362 |
| CGS 94 | 19 | 11 | 68 | 00 | 09 | 27 | 11.336 N | 86.714 | 33 | 460 Na | 074 | 41 MS |  | 0 | NO 22 | 410 |
| CGS 26 | 20 | 03 | 70 | 21 | 00 | 08 | 10.428 N | 87.364 N | 36 | 440 MB | 077 | 43 MS |  | 0 | 013* | 430 |
| CGS 54 | 20 | 07 | 70 | 04 | 58 | 05 | 10.366 N | 87.400 W | 33 | $460 \mathrm{N8}$ | 077 | 0 |  | 0 | N01 5* | 412 |
| CGS 55 | 12 | 08 | 70 | 11 | 07 | 59 | 10.867 N | 87.229W | 33 | 450 MB | 077 | 0 |  | 0 | NOO9** | 395 |
| CGS 37 | 25 | 05 | 70 | 23 | 05 | 18 | 10.738 N | *6.939H | 33 | 4 BONB | 077 | 0 |  | 0 | NO14 | 445 |



| ERL 85 | 26 | 117 | 71 | 04 | 06 | 38 | 12.148 N | 87.626W |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CGS-B | 30 | 016 | 62 | 08 | 34 | 23 | 12.730 V | 87.50 cm |
| $C \mathrm{Cos}-8$ | 04 | 04 | 64 | 06 | 43 | 20 | 12.50 ON | 87.700 W |
| CGS-8 | 06 | 12 | 65 | 13 | 19 | 13 | 12.400 N | c7.400w |
| CGS 12 | 12 | 02 | 70 | 17 | 22 | 11 | 12.139N | 86. 616 W |
| FRL 16 | 05 | 037 | 72 | 21 | 47 | 26 | 11.971 N | 87.914W |
| CGS-B | 31 | 086 | 63 | 13 | 08 | 46 | 11.930 N | E7.000w |
| CGS-8 | 08 | 12 | 64 | 04 | 11 | 53 | 11.530 N | 87.000W |
| GS 52 | 14 | 07 | 73 | 07 | 55 | C8 | 11.637 V | 87. 291 W |
| ERL 35 | 28 | 057 | 73 | 06 | 19 | 00 | 11.474 N | 87.266W |
| ERL $4 \%$ | 05 | 07 | 73 | 08 | 08 | 07 | 11.949 N | c7.541W |
| CGS 7 | 20 | 01 | 70 | 08 | 27 | 48 | 11.482 N | 86. 353 W |
| CGS 3 | 12 | 10 | 66 | 20 | 20 | 06 | 11.200 N | 86.200 W |
| EPL 9 | 30 | 017 | 72 | 22 | 25 | 03 | 11.082 N | 86.750 W |
| CGSPDE | 30 | 06 | 67 | 11 | 42 | 33 | 11.000 N | 86.600W |
| CGS-B | 30 | 076 | 64 | 05 | 16 | 03 | 11.100 N | 86.200W |
| ERL 7 | 30 | 01 | 72 | 19 | 10 | 07 | 11.261 N | 86.773 W |
| CGS 36 | 13 | 05 | 69 | 17 | 38 | 28 | 11.784 N | 86. 179 W |
| ERL 61 | 01 | 10 | 72 | 06 | 00 | 51. | 11.015 N | 86.330 W |
| SYKES | 27 | 10 | 57 | 18 | 29 | 10 | 15.970 N | 88.11 OW |
| CGS 55 | 03 | 08 | 69 | 21 | 17 | 16 | 13.342 N | 88. 342 W |
| CGS 59 | 04 | 096 | 69 | 06 | 25 | 28 | 13.216 N | 88.429W |
| ERL 51 | 31 | 08 | 72 | 02 | 24 | 09 | 13. 272 N | 88.513W |
| CGSPDE | 06 | 05 | 68 | 21 | 23 | 11 | 13.021 N | 87.734W |
| CGS-B | 25 | 02 | 63 | 08 | 58 | 43 | 12.300 N | 88.200 W |
| CGS-8 | C5 | 036 | 64 | 14 | 30 | 18 | 12.130 N | 88.100 W |
| CGS-B | 15 | 06 | 64 | 09 | 41 | 24 | 12.600 N | 88.300W |
| CGS-B | 19 | 06 | 64 | 17 | 31 | 56 | 12.400 N | 88.100 W |
| CGSPDE | 18 | 04 | 68 | 04 | 40 | 38 | 12.50 0N | 88.600 W |
| CGS-B | 30 | 08 | 64 | 15 | 20 | 50 | 12.600N | 88. 500 W |
| CGS-B | 04 | 076 | 63 | 01 | 43 | 20 | 12.800N | 88.700W |
| CGS-B | 13 | 076 | 66 | 08 | 20 | 58 | 12.60 ON | 87.800w |
| CGS-B | 09 | 05 | 63 | 15 | 03 | 43 | 12.400N | 87.000w |
| CGS-B | 17 | 07 | 65 | 13 | 59 | 46 | 12.200N | 87.900W |
| $\mathrm{CGS-8}$ | 27 | 036 | 67 | 14 | 40 | 13 | 12.221 N | 87.712W |
| CGS-B | 06 | 126 | 65 | 04 | 39 | 10 | 12.500 N | 87.300w |
| cos 54 | 07 | 08 | 70 | 13 | 03 | 14 | 12.325 N | 87.79 IW |
| NCS 21 | 25 | 02 | 71 | 04 | 15 | 41 | 12.159 N | B7.489 W |
| CGS- ${ }^{\text {c }}$ | 10 | 06 | 64 | 16 | 25 | 09 | 12.000 N | 87.900W |
| ERL 41 | 07 | 07 | 73 | 07 | 07 | 55 | 11.842 N | 87.76 1W |
| c.GS 32 | 24 | 04 | 69 | 22 | 29 | 46 | 11.539 N | 87.022W |
| ERL 40 | 06 | 07 | 73 | 05 | 21 | 49 | 11.962 N | E 7.588 H |
| CGS-B | 07 | 10 | 63 | 03 | 59 | 54 | 11.600 N | 86.900 W |
| ERL 9 | 04 | 02 | 72 | 01 | 07 | 43 | 11.213 N | 86.891 W |
| CGS 23 | 18 | 03 | 70 | 23 | 17 | 57 | 10.984 N | 86.015 W |
| $\mathrm{CGS}-\mathrm{B}$ | 01 | 03 | 65 | 15 | 17 | 45 | 10.800 N | 86.700W |
| CGS-B | 18 | 04 | 67 | 07 | 05 | 08 | 10.749 N | 36.777 |
| CGS-8 | 03 | 02 | 64 | 01 | 46 | 27 | 13.030 N | 88.000 W |
| CGS | 27 | 06 | 58 | 05 | 44 | 28 | 13.000 N | 88.500W |
| C.GS 80 | 22 | 10 | 68 | 06 | 42 | 01 | 13.208 N | 88.247W |
| $\mathrm{COS}-\mathrm{CB}^{\text {c }}$ | 20 | 12 | 63 | 22 | 28 | 31 | 13.200 N | 88.000w |
| CGS-B | 21 | 07 | 64 | 07 | 01 | 59 | 13.130 N | 88. 400 W |
| $\mathrm{CGS}-\mathrm{B}$ | 16 | 08 | 64 | 07 | 30 | 12 | 13.300 N | 87.600 W |
| CGS-B | 02 | 03 | 64 | 16 | 09 | 46 | 12.500 N | 88.00 cW |
| CG S- ${ }^{-8}$ | 19 | 05 | 61 | 09 | 25 | 41 | 12.850 N | 88.200 W |
| ERL 49 | 19 | 08 | 73 | 22 | 17 | 49 | 12.651 N | 88.507 W |
| ERL 14 | C4 | 03 | 72 | 22 | 04 | 23 | 12.933 N | 88.743W |
| ERL 15 | 07 | 03 | 73 | 13 | 00 | 45 | 12.705 N | 88.027 W |
| CGS-B | 24 | 07 | 66 | 06 | 11 | 55 | 12.200 N | 88.300 W |
| ERL 81 | C8 | 11 | 71 | 04 | 26 | 16 | 12.472 N | 88.165W |


|  | A3-5 |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 47 | 440 MB |  | 074 | 0 | 0 | 013 | 379 |
| 49 | 0 |  | 074 | 0 | F 488 PAL | 049 | 488 |
| 41 | 430 MB |  | 074 | 0 | 0 | 012 | 362 |
| 44 | 390 MB |  | 074 | 0 | 0 | 007 | 300 |
| 44 | 440 MB |  | 075 | 0 | 0 | 013 | 379 |
| 46 | 460 MB | 3 | 074 | 0 | F 0 | 020* | 412 |
| 48 | 490ME |  | 074 | 0 | 0 | 018 | 462 |
| 48 | 500 mB |  | 074 | 0 | 0 | 029 | 478 |
| 46 | 490 M8 |  | 074 | 44MS | 0 | 024* | 440 |
| 42 | 460 ME |  | 074 | 40MS | 0 | 014* | 400 |
| 48 | 430 MB |  | 074 | 0 | 0 | 015 | 362 |
| 46 | 540 MB |  | 074 | 0 | 0 | 063 | 545 |
| 45 | 510 MB |  | 074 | 0 | 0 | 054 | 495 |
| 43 | 450 Mg |  | 074 | 38 MS | 0 | 017 | 380 |
| 44 | 450 MB |  | 074 | 0 | 0 | 022 | 395 |
| 42 | 570 MB |  | 074 | 0 | 0 | 022 | 594 |
| 48 | 460 MB |  | 074 | 44 MS | 0 | 027 | 440 |
| 46 | 490 MB |  | 074 | 52MS | $4008 R \mathrm{~K}$ | 042 | 520 |
| 49 | 42 CMB |  | 074 | 0 | 0 | 006 | 345 |
| 56 | 0 |  | 093 | 0 | 400 PAL | DOB | 400 |
| 52 | 430 MB |  | 073 | 0 | 0 | $010 *$ | 362 |
| 53 | 460 MB | 4 | 073 | 0 | $F \quad 0$ | 020 | 412 |
| 50 | 540 ME |  | 073 | 48 MS | 0 | 088 | 480 |
| 56 | 460 MB |  | 072 | 0 | 0 | 0024* | 412 |
| 58 | 410 MB |  | 076 | 0 | 0 | 029 | 329 |
| 53 | 430 ME |  | 076 | 0 | 0 | 009 | 362 |
| 56. | 410\% |  | 076 | 0 | 0 | 007 | 329 |
| 53 | 400 MB |  | 076 | 0 | 0 | 011 | 312 |
| 54 | 490 MB |  | 076 | 0 | 0 | 019 | 462 |
| 54 | 460 MB |  | 076 | 0 | 0 | 015 | 412 |
| 55 | 410 MB |  | 076 | 0 | 0 | 007 | 329 |
| 56 | 530 MB |  | 074 | 0 | 0 | 073 | 528 |
| 50 | 550 MB |  | 074 | 0 | 0 | 047 | 561 |
| 56 | 440MB |  | 074 | 0 | 0 | 013 | 379 |
| 54 | 420 MB |  | 074 | 0 | 0 | 019 | 345 |
| 50 | 450 M 4 |  | 074 | 0 | 0 | 024 | 395 |
| 59 | 450 MB |  | 074 | 0 | 0 | 016 | 395 |
| 52 | 530 MB |  | 074 | 0 | 0 | 075 | 528 |
| 55 | 420 MB |  | 074 | 0 | 0 | 006 | 345 |
| 55 | 430 Mg |  | 074 | 0 | 0 | 015 | 362 |
| 50 | 440 MB |  | 074 | 0 | 0 | 022 | 379 |
| 51 | 480 MB |  | 074 | 0 | 0 | 023 | 445 |
| 50 | 450 MB |  | 074 | 0 | 0 | 015 | 395 |
| 52 | 480 MB |  | 074 | 0 | 0 | 019 | 445 |
| 56 | 490 ME |  | 074 | 0 | 0 | 037 | 462 |
| 55 | 490 MB |  | 077 | 0 | 0 | 009 | 462 |
| 53 | 480 MB |  | 077 | 0 | 0 | 041 | 445 |
| 61 | 410 MB |  | 073 | 0 | 0 | 006 | 329 |
| 60 | 0 |  | 073 | 0 | DFGOOPAS |  | 600 |
| 64 | 470 MB | 5 | 073 | 0 | 0 | 017 | 428 |
| 64 | 430 MB |  | 073 | 0 | 0 | 005 | 362 |
| 68 | 470 MB |  | 073 | 0 | 0 | 030 | 428 |
| 60 | 390MB |  | 072 | 0 | 0 | 005 | 300 |
| 63 | 440MB |  | 076 | 0 | 0 | 018 | 379 |
| 68 | 0 | 5 | 076 | 0 | F $463 P A L$ |  | 463 |
| 68 | 510 MB | 4 | 076 | 0 | F 0 | D033 | 495 |
| 64 | 470 MB | 4 | 076 | 0 | F 0 | 024 | 428 |
| 64 | 460 mg |  | 076 | 0 | 0 | $013 *$ | 412 |
| 61 | 410 MB |  | 076 | 0 | 0 | 013 | 329 |
| 68 | 490 HB |  | 076 | 0 | 0 | 031 | 462 |


|  |  |  |  |  |  |  |  |  | A3－6 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CGSPOE | 26 | 01 | 68 | 10 |  | 56 | 12.730 N | 82．800 | 80 | 390848 |  | 076 | 0 |  | 0 | 007 | 300 |
| CGS－B | 31 | 07 | 66 | 19 | 10 | 4 | 12.400 V | 88．100w | 63 | 420888 |  | 076 | 0 |  | 0 | 032 | 345 |
| CGS－B | 04 | 05 | 68 | 18 | 13 | 55 | 12.500 N | 87．700 | 68 | 510 M 8 |  | 074 | 0 |  | 0 | 038 | 495 |
| CGS－8 | 08 | 08 | 64 | 15 | 45 | 10 | 12．500N | ¢7．800 ${ }^{\text {d }}$ | 63 | 580 mB |  | 074 | 0 |  | 0 | 032 | 611 |
| CGS 20 | 10 | 03 | 69 | 08 | 15 | 08 | 12.369 N | B7．455w | 62 | 53048 |  | 074 | 0 |  | 6008RK | 059 | 600 |
| C．6 5－8 | 21 | 02 | 64 | 07 | 24 | 08 | 12.800 N | 87，900H | 82 | 39016 |  | 074 | a |  | 0 | 007 | 300 |
| ERL 85 | 25 | 11 | 71 | 22 | 06 | 26 | 12．759N | 87.4580 N | 62 | 49010 |  | 074 | 0 |  | 0 | 024 | 462 |
| CGS－${ }^{\text {C }}$ | 18 | 048 | 67 | 08 | 29 | 12 | 110738N | 87．3074 | 85 | 460 MB |  | 074 | 0 |  | 0 | 028 | 412 |
| ERL 8 | 16 | 01 | 72 | 23 | 55 | 10 | 11.505 N | 87． 582 㑲 | 52 | 460 HB |  | 074 | 0 |  | 0 | 014 | 482 |
| GUTE | 06 | 0 Cl | 41 | 09 | 48 | 34 | 11．750N | 86．5004 | 80 | 0 |  | 034 | 0 |  | 600PAS |  | 600 |
| CG S－B | 20 | 03 | al | 06 | 16 | 21 | 11．300V | 86．500\％ | 60 | 0 |  | 074 | 0 | F | 613PAS |  | 613 |
| CGS 38 | 14 | 0.5 | 69 | 13 | 49 | 03 | 11.518 N | 06． 154 相 | 62 | ¢80．m8 |  | 076 | 0 |  | 0 | 046 | 445 |
| VOS 44 | 10 | 06 | 71 | 11 | 20 | 31 | 11.101 N | 86．766 6 | 60 | 490阵 8 |  | 074 | 0 |  | 0 | 015＊ | 462 |
| VOS 30 | 26 | 04 | 71 | 18 | 32 | 20 | $11.422 N$ | 86．7604 | 69 | ¢70MB |  | 074 | 0 |  | 0 | 040 | 428 |
| CGS－8 | 02 | 11 | 65 | 22 | 44 | 41 | 10.50 ON | 86． 3004 | 69 | 450 mb |  | 077 | 0 |  | 0 | 010 | 395 |
| CGS－B | C8 | 03 | 67 | 23 | 07 | 02 | 15．10 NN | 88．782N | 76 | 420明 8 |  | 072 | 0 |  | 0 | 006\％ | 345 |
| CGS－8 | 08 | 03 | 67 | 15 | 52 | 15 | 13.049 N | 88． 227 \％ | 75 | 390MB |  | 073 | 0 |  | 0 | 005＊ | 300 |
| CGS 19 | 09 | 03 | 69 | 07 | 12 | 39 | 13.101 N | 88．528W | 75 | 480 Mm |  | 073 | 0 |  | 0 | 021 | 379 |
| gUte | 26 | 12 | 39 | 11 | 55 | 11 | 13.250 N | 88.25 cm | 35 | 0 |  | 073 | 0 |  | 600PAS | AAA | 600 |
| CGS－B | 09 | 01 | 87 | 22 | 31 | 22 | $13.138 N$ | 88．9814 | 78 | 410 HB |  | 073 | 0 |  | 0 | 008 | 329 |
| CGS－B | 04 | 016 | 67 | 00 | 28 | 07 | 13.100 N | 88.625 W | 72 | $410 \mathrm{~m} \mathrm{~B}^{4}$ |  | 073 | 0 |  | 0 | 010 | 329 |
| CGS－B | 27 | 12 | 66 | 21 | 22 | 16 | 13.300 N | 88．800 | 78 | 580 MB |  | 073 | 0 |  | 0 | 090 | 545 |
| ERL 66 | 19 | 21 | 72 | 04 | 35 | $2{ }^{4}$ | 12.973 N | 88．52 4 d | 83 | 560MB |  | 073 | 0 |  | 0 | 065 | 578 |
| CGS－B | 10 | 08 | 64 | 14 | 00 | 51 | 12.400 N | 89．300N | 71 | 400．98 |  | 076 | 0 |  | 0 | 006 | 312 |
| CGS 33 | 03 | 05 | 69 | 03 | 19 | 06 | 12.987 N | 88． 5 的 5 chd | 77 | 450月18 | 5 | 073 | 0 | F | 0 | 032 | 395 |
| CGS 25 | 01 | 04 | 69 | 21 | 19 | 53 | 12.6774 | 88． 233 d | 71 | 490 Mg | 4 | 076 | 0 | $F$ | 0 | 038 | 462 |
| CGS 26 | 08 | 04 | 69 | 19 | 41 | 58 | 12．670N | 88.34041 | 76 | 480 AB |  | 076 | 0 |  | 0 | 023 | 445 |
| ERL 32 | 30 | 04 | 72 | 10 | 55 | 19 | 12．8964 | 98．6684 | 77 | 440 MB | 3 | 076 | 0 | $F$ | 0 | 019 | 379 |
| CGS 62 | 06 | 09 | 70 | 20 | 44 | 49 | 12.783 N | 88．595w | 15 | 450m |  | 076 | 0 | F | 0 | 017 | 395 |
| CGS 34 | 21 | 04 | 70 | 05 | 37 | 98 | 12.9887 N | －87．880넨 | 79 | 52048 |  | 074 | 0 |  | 0 | 045 | 511 |
| ERL 47 | 28 | 03 | 73 | 20 | 48 | 24 | 12.333 N | 87\％ 08.4 | 79 | 540M 93 |  | 074 | 0 | $F$ | 0 | 0087 | 545 |
| CGS－B | 82 | 03 | 67 | 09 | 15 | 29 | 12.653 V | 870823W | 70 | 440 m 8 |  | 074 | 0 |  | 0 | 025 | 379 |
| CGS 71 | 23 | 09 | 70 | 23 | 57 | 45 | 12.021 N | 87．4ヶ6园 | 70 | 450 ME |  | 074 | 0 |  | 0 | 029 | 395 |
| CG 5－8 | 20 | 10 | 65 | 23 | 54 | 30 | 12.500 N | 87.3006 | 72 | 540 mb |  | 074 | 0 |  | 0 | 063 | 545 |
| CGS－B | 25 | 03 | 67 | 07 | 26 | 37 | $12.406 N$ | 87．876 | 76 | 400 mb |  | 074 | 0 |  | 0 | 005＊ | 312 |
| $C G S B$ | 25 | 08 | 64 | 05 | 03 | 18 | 12.100 N | 87．700w | 72 | 400 MB |  | 074 | 0 |  | 0 | 005 | 312 |
| cGSPOE | 28 | 01 | 68 | 08 | 47 | 20 | 12.6904 | 87.9000 N | 75 | 440 MS |  | 074 | 0 |  | 0 | 022 | 379 |
| cos－B | 31 | 12 | 63 | 1．4 | 22 | 07 | 12.400 N | 87．900 W | 77 | 430 MB |  | 074 | 0 |  | 0 | 007 | 362 |
| CGSPDE | 24 | 03 | 68 | 17 | 13 | 20 | 12．500N | 86，500N | 79 | 510 mb |  | 075 | 0 |  | 0 | 043 | 495 |
| cos 38 | 13 | 05 | 69 | 14 | 15 | 52 | 11.428 N | 80．3694 | 71 | 480 ME |  | 074 | 0 |  | 0 | 037 | 445 |
| CGS 38 | 13 | 05 | 69 | 14 | 15 | 52 | 12.459 N | 66． 355 d | 79 | 560 MB |  | 074 | 0 | F | $5708 R K$ | 104 | 570 |
| cos 3日 | 13 | 05 | 69 | 18 | 11 | 39 | 11.523 N | 86．509W | 72 | 460ME |  | 074 | 0 |  | 0 | 037 | 412 |
| CGS 4 | 15 | 01 | 69 | 06 | 57 | 22 | 11．308v | 86．813 $\mathrm{SH}^{\text {d }}$ | 72 | 450 mB |  | 074 | 0 |  | 0 | 010 | 395 |
| cgs 8 | 15 | 01 | 70 | 16 | 52. | 42 | 11.512 N | 80．733 W | 70 | 510 MB | 3 | 074 | 0 | $F$ | 575BRK | 046 | 575 |
| CGS | 19 | 02 | 54 | 21 | 34 | 41 | 12.500 N | 27．500b | N | 0 |  | 074 | 0 | F | 663 PAS | ＊ | 663 |
| gute | 28 | 03 | 21 | 07 | 49 | 22 | 12.500 N | 870500w | N | 0 |  | 074 | 0 |  | 730945 | ＊ | 730 |
| CGS | 25 | 10 | 56 | 05 | 21 | 40 | 12.000 N | 87，000w | N | 0 |  | 074 | 0 |  | $637 P A S$ | ＊ | 637 |
| LSS | 24 | 10 | 56 | 14 | 42 | 12 | 13．790N | 88．460\％ | N | 0 |  | 074 | 0 |  | F730PAS | ＊ | 730 |
| ISS | 24 | 04 | 59 | 09 | 31 | 33 | 11.480 N | 86．4006 | N | 0 |  | 074 | 0 |  | 638PAS | ＊ | 638 |
| DEA 113 | 1 | 5 | 16 |  |  |  | 11.00 | 85． 50 | N | D |  |  |  |  |  | 4＊＊ | 54.7 |
| ）EN114 | 23 | 9 | 16 |  |  |  | 11.00 | 85.50 | N | D |  |  |  |  |  | \＃\＃ | 580 |
| DEM 255 | 12 | 7 | 59 |  |  |  | 11.50 | 86.00 | N | 0 |  |  |  |  |  |  | 547 |
| DEth 313 | 26 | 2 | 63 |  |  |  | 12.40 | 87.80 | N | $E$ |  |  |  |  |  | ＊去如 | 505 |
| DEN 326 | 13 | 10 | 63 |  |  |  | 12.50 | 87.10 | N | D |  |  |  |  |  | ＊＊＊ | 535 |
| DEM 327 | 23 | 11 | 63 |  |  |  | 12.00 | 4 7.20 | N | $C$ |  |  |  |  |  | ＊＊＊ | 605 |
| Dem 331 | 11 | 3 | 64 |  |  |  | 12.50 | 87.10 | N | D |  |  |  |  |  | ＊＊${ }^{\text {\％}}$ | 540 |
| DE 332 | 29 | 4 | 64 |  |  |  | 12． 30 | E7080 | N | $E$ |  |  |  |  |  | \＃＊${ }^{\text {\％}}$ | 515 |
| DEM 45. | 13 | 4 | 73 |  |  |  | 10.52 | 85.50 | N | 6.7 |  |  |  |  |  | 中家 | 6.7 |
| DEM 111 | 27 | 02 | 18 |  |  |  | 11．00 | 85.50 | N | $\&$ |  |  |  |  |  | ＊ | 650 |
| D6\％ 196 | $30^{\prime}$ | 45 | 55 |  |  |  | 12.00 | 87．00 | N | 60 |  |  |  |  |  | \％ | 6.0 |






|  |  |  |  |  |  |  |  |  | A3-11 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CGS-8 | 23 | 05 | 67 | 17 | 14 |  | 10.197N | 84.022W | 119 | 430 MB |  | 078 | 0 |  | 0 | 008* | 362 |
| CGSPDE | 04 | 07 | 68 | 15 | 15 | 59 | 10.464 N | 84.056 W | 113 | 440 MB |  | 078 | 0 |  | 0 | 012 | 379 |
| CGS-B | 23 | 07 | 64 | 04 | 57 | 54 | 10.500N | 83.90 CH | 114 | 420Me |  | 078 | 0 |  | 0 | 010 | 345 |
| CGS-B | 12 | 08 | 63 | 1.7 | 19 | 05 | 09.830N | 84. 200 W | 114 | 42 MmB |  | 078 | 0 |  | 0 | 007 | 345 |
| OEM 160 | 18 | 8 | 51 |  |  |  | 11.00 | 84. 00 | 96 | $E$ |  |  |  |  |  | * | 449 |
| * PaCIF | 1 C | COA | STLL | INE |  | 33 | KM (12) |  |  |  |  |  |  |  |  |  |  |
| $\cos 55$ | 12 | 08 | 70 | 09 | 24 | 11 | 12.015 N | $86.54{ }^{\text {2 }}$ | 33 | 590 MB |  | 075 | 63ms | $F$ | 600PA S | N077 | 630 |
| CGS-B | 11 | 0.5 | 66 | 05 | 57 | 02 | 12.300 N | 86.800 W | 33 | 400 MB |  | 075 | 0 |  | 0 | 007 | 312 |
| CGS 55 | 12 | C8 | 70 | 10 | 24 | 23 | 12.051 N | 86.539W | 33 | 560 M ${ }^{\text {B }}$ |  | 075 | 55MS |  | 530 PAS | N05 7 | 550 |
| ERL 12 | 15 | 02 | 73 | 00 | 15 | 53 | 11.534 N | 86.473W | 33 | 510m8 |  | 074 | 50 MS |  | 0 | D053 | 500 |
| cGspoe | 08 | 10 | 67 | 14 | 28 | 07 | 11.300 N | 86.000w | 33 | 420 MB |  | 074 | 0 |  | 0 | 009 | 345 |
| CGS-B | 21 | 03 | 65 | 09 | 42 | 41 | 11.700 N | 66.400w | 36 | 520M8 |  | 074 | 0 |  | 0 | 036 | 511 |
| CGS 8 | 15 | 01 | 70 | 19 | 08 | 59 | 11.157N | 86. 015 W | 33 | 460 MB |  | 074 | 0 |  | 0 | Not 2* | 412 |
| ERL 13 | 29 | 08 | 71 | 08 | 26 | 52 | 11.547 N | 86.180W | 33 | 490 MB |  | 074 | 0 |  | 0 | NO 34 | 462 |
| ERL 77 | 24 | 08 | 71 | 08 | 09 | 07 | 11.509 N | 86.323W | 33 | 510 Me |  | 074 | 42 MS |  | 0 | N049 | 420 |
| OEM 172 | 3 | 3 | 52 |  |  |  | 11.50 | 86.30 | 33 | $E$ |  |  |  |  |  | * | 500 |
| DEM 174 | 5 | 12 | 52 |  |  |  | 11.50 | 86.30 | 33 | E |  |  |  |  |  | * | 486 |
| DEM 253 | 5 | 6 | 59 |  |  |  | 12.06 | 66. 52 | 27 | $E$ |  |  |  |  |  | * | 491 |
| * atlantic all depth (11) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| CGS-B | 25 | 06 | 62 | 18 | 58 | 35 | 14.50 ON | 82.400 h | 25 | 0 |  | 094 | 0 |  | $463 P \mathrm{~A}$ L | 015 | 463 |
| -GS- ${ }^{\text {c }}$ | 20 | 05 | 66 | 03 | 58 | 01 | 12.60 0N | 82.600 W | 33 | 390 ME |  | 079 | 0 |  | 0 | 009 | 300 |
| CGS-B | 11 | 08 | 65 | 18 | 15 | 39 | 10.80 ON | 83.200 W | 33 | 390 MB |  | 078 | 0 |  | 0 | 007 | 300 |
| CGS-8 | 08 | 10 | 66 | 20 | 38 | 07 | 10.700 N | 82.4004 | 33 | 410 mB |  | 079 | 0 |  | 0 | 008 | 329 |
| gute | 17 | 03 | 26 | 11 | 53 | 36 | 12.500 N | 82.500W | 50 | 0 |  | 094 | 0 |  | 690PAS |  | 690 |
| GUTE | 06 | 12 | 37 | 21 | 43 | 09 | 14.030 N | 82.000 W | 60 | 0 |  | 094 | 0 |  | 600 PA S |  | 600 |
| CGSPDE | 17 | 07 | 68 | 06 | 23 | 11 | 10.394 V | 83.389 W | 19 | 510 MB |  | 078 | 0 |  | 0 | 0052 | 495 |
| cgspae | 03 | 03 | 68 | 08 | 43 | 24 | 10.00 0 N | 83.100 W | 13 | 410 me |  | 078 | 0 |  | 0 | 010 | 329 |
| gute | 20 | 03 | 36 | 18 | 46 | 28 | 11.0DON | 84.000 W | N | 0 |  | 075 | 0 |  | $560 P A S$ | * | 560 |
| GUTE | 25 | 07 | 13 | 12 | 38 | 06 | 13.000 N | 83.000 W | 0 | 0 |  | 075 | 0 |  | $630 P A S$ | * | 630 |
| S YKES | 07 | 12 | 57 | 22 | 18 | 51 | 13.550 N | 82.410 W | 0 | 0 |  | 094 | 0 |  | 510 PAL | 023 | 510 |
| * managua volcano line n (57) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| LGS-B | 09 | 05 | 63 | 15 | 06 | 24 | 12.700N | 86.600 W | 33 | 410 Me |  | 075 | 0 |  | 0 | 008 | 329 |
| ERL 2 | 05 | 01 | 72 | 11 | 52 | 26 | 12.296 N | 86. 236 W | 33 | 42 OMB |  | 075 | 0 |  | 0 | NO1 9* | 345 |
| ERL 1 | 03 | 01 | 72 | 04 | 31 | 04 | 12.311 N | 86.300W | 33 | 410 MB |  | 075 | 0 |  | 0 | N019* | 329 |
| DEM 131 | 11 | 7 | 33 |  |  |  | 12. 23 | 8t. 30 | N | 0 |  |  |  |  |  | *** | 583 |
| DEM 132 | 24 | 8 | 33 |  |  |  | 12.23 | 86. 30 | N | 0 |  |  |  |  |  | *** | 531 |
| DEM 156 | 5 | 1 | 51 |  |  |  | 12.20 | 86. 30 | N | 0 |  |  |  |  |  | *** | 565 |
| DEN 272 | 16 | 2 | 61 |  |  |  | 12.70 | 86.50 | 40 | $E$ |  |  |  |  |  | * | 393 |
| DEN 309 | 15 | 1 | 63 |  |  |  | 13.00 | 86.70 | 33 | $E$ |  |  |  |  |  | * | 444 |
| DEN 161 | 8 | 7 | 51 |  |  |  | 12.03 | 88.00 |  | $E$ |  | DEEP M | AY BE |  |  | * | 489 |
| DEM 175 |  | 1 | 53 |  |  |  | 13.50 | 86. 50 |  | D |  | DEEP M | AY BE |  |  | * | 576 |
| O\&N 20C | 30 | 4 | 55 |  |  |  | 12.50 | 86.50 |  | 0 |  | DEEP M | AY BE |  |  | * | 559 |
| DEM 236 | 5 | $t$ | 58 |  |  |  | 12.50 | 86.50 |  | E |  | DEEP M | ar be |  |  | * | 461 |
| DEM 256 | 12 | 8 | 59 |  |  |  | 12.00 | 86.00 |  | E |  | DEEP M | AY be |  |  | * | 470 |
| DEN 41 |  |  | 50 |  |  |  | 12.60 | 86.36 | N | D | $v$ |  |  |  |  | *** | 598 |
| OEM 42 | 11 | 4 | 50 |  |  |  | 12.48 | 86.68 | $N$ | C | $v$ |  |  |  |  | * ${ }_{\text {\% }}$ ( ${ }^{\text {d }}$ | 674 |
| DEM 43 | 27 | 4 | 50 |  |  |  | 12.48 | 86.67 | V | 0 | $v$ |  |  |  |  | *** | 551 |
| )EM 44 |  |  | 52 |  |  |  | 12.42 | 86.55 | N | 0 | $v$ |  |  |  |  | *** | 561 |
| 1)EM 45 | 8 | 5 | 52 |  |  |  | 12.16 | 86. 30 | N | C | $v$ |  |  |  |  | *** | 692 |
| JEM 46 | 29 | 6 | 52 |  |  |  | 11.95 | 86. 15 | $N$ | D | $v$ |  |  |  |  | *** | 566 |
| JEM 47 |  | 7 | 52 |  |  |  | 11.95 | 86.15 | N | D | $v$ |  |  |  |  | *** | 575 |
| DEM 49 | 8 | 4 | 53 |  |  |  | 11.95 | 86. 15 | N | D | $v$ |  |  |  |  | *** | 547 |
| DEM 50 | 29 | 6 | 53 |  |  |  | 11.95 | 86. 15 | $N$ | D | $v$ |  |  |  |  | *** | 595 |
| DEM 51 |  | G | 53 |  |  |  | 11.95 | 86.15 | N | D | $v$ |  |  |  |  | *** | 595 |
| DGM 53 | 2 | 1 | 55 |  |  |  | 11.95 | 86.15 | N | D | $v$ |  |  |  |  | *** | 540 |
| DEM | 2 |  | 55 |  |  |  | 11.95 | 86.15 | N | 0 | $v$ |  |  |  |  | *** | 595 |
| DEM 54 |  | 12 | 56 |  |  |  | 11.95 | E6. 15 | $N$ | C | $v$ |  |  |  |  | *** | 682 |
| DEM 55 |  |  | 56 |  |  |  | 11.95 | 86.15 | $N$ | C | V |  |  |  |  | *** | 653 |




| gute | 17 | 03 | 26 | 11 | 53 | 36 | 12.500 N | 82.500 H | 50 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| gute | 05 | 11 | 26 | 07 | 55 | 38 | 12.300 N | 85.800 W | 135 | 0 |
| DEM 121 | 25 | 10 | 28 |  |  |  | 12.30 | 85.80 |  | c |
| gute | C7 | 02 | 31 | 03 | 30 | 35 | 13.000 N | 87.000W | 100 | 0 |
| gute | 07 | 03 | 31 | 00 | 41 | 56 | 11.500 V | 85.500 W | 80 | 0 |
| GUTE | 31 | 03 | 31 | 16 | 162 | 21 | 12.250 N | 86.200 W | 0 | 0 |
| gute | 21 | 05 | 32 | 10 | 10 | 07 | 12.000 N | E7.500W | 90 | 0 |
| DEM 130 | 21 | 5 | 33 |  |  |  | 12.00 | 87.50 | 90 |  |
| DEM 131 | 11 | 7 | 33 |  |  |  | 12.20 | 86.30 | N | D |
| DEM 132 | 24 | 8 | 33 |  |  |  | 12.20 | 86.30 | N | 0 |
| gute | 12 | 01 | 33 | 01 | 17 | 42 | 11.000 N | 87.000 W | N | 0 |
| GUTE | 24 | 02 | 34 | 05 | 53 | 30 | 12.750 N | 86.750W | 200 | 0 |
| gute | C7 | 03 | 34 | 22 | 41 | 47 | 13.250 N | 87.750 W | 0 | 0 |
| gute | 22 | 12 | 34 | 14 | 42 | 31 | 11.500 N | 87.000 W | N | 0 |
| DEM 135 | 1 | 9 | 35 |  |  |  | 12.58 | 87.16 |  | E |
| GUTE | 20 | 03 | 36 | 18 | 46 | 28 | 11.000 N | 84.000 W | N | 0 |
| DEM 137 | 12 | 1 | 37 |  |  |  | 12.58 | 87.16 |  | D |
| DEM 138 | 25 |  | 37 |  |  |  | 11.00 | 85. 00 |  | E |
| gute | 09 | 03 | 37 | 15 | 40 | 20 | 09.000 N | 83.500 W | 30 | 0 |
| gute | 06 | 12 | 37 | 21 | 143 | 09 | 14.030 N | 82.000 W | 60 | 0 |
| DEM 139 | 25 |  | 38 |  |  |  | 12.20 | 86.90 |  | c |
| DEP 141 | 9 |  | 39 |  |  |  | 11.10 | 66.20 |  | E |
| gute | 18 | $0 ¢$ | 39 | 16 | 1646 | 05 | 10.000 N | 83.000W | 70 | 0 |
| gute | 08 | 07 | 39 | 21 | 131 | 44 | 12.500 N | 88.000 W | 90 | 0 |
| gute | 21 | 12 | 39 | 20 | 54 | 48 | 10.00 ON | 85.0004 | 0 | 0 |
| gute | 22 | 12 | 39 | 04 | 444 | co | 10.000 N | 84.500W | 0 | 0 |
| GUTE | 26 | 12 | 39 | 11 | 155 | 11 | 13.250 N | 88.25 0W | 15 | 0 |
| DEM 143 | 29 | 12 | 39 |  |  |  | 13.00 | 86.00 |  | E |
| DEM 144 | 20 | 2 | 40 |  |  |  | 12.50 | 87.50 |  | ¢ |
| gute | 05 | 10 | 40 | 14 | 438 | 43 | 09.500N | 84.250 W | 0 | 0 |
| gute | 27 | 10 | 40 | 05 | 35 | 37 | 09.750 N | 84.50 ch | 0 | 0 |
| GUTE | 06 | 01 | 41 | 09 | 948 | 34 | 11.750 N | 86.500 W | 0 | 0 |
| gute | C8 | 10 | 41 | 04 | 22 | 13 | 10.50 ON | 86.250W | 0 | 0 |
| gute | 16 | 11 | 41 | 09 | 39 | 46 | 13.250 N | 88.500 W | 80 | 0 |
| gUTE | 06 | 12 | 41 | 01 | 125 | cl | 10.500 N | 85.250 W | 0 | 0 |
| DEF 147 | 5 |  | 44 |  |  |  | 12.50 | 87.50 |  | E |
| gute | 07 | 04 | 44 | 13 | 332 | 58 | 12.000 N | 85.500 W | 200 | 0 |
| OCM 148 | 5 | 10 | 45 |  |  |  | 13.00 | 87.00 | 100 | E |
| DEN 149 | 11 | 2 | 46 |  |  |  | 11.60 | 85.60 |  | c |
| OEM 151 | 15 |  | 47 |  |  |  | 12.50 | 86.80 | N | c |
| gute | 26 | 01 | 47 | 10 | 06 | 46 | 12.500 N | 86. 250 W | 170 | 0 |
| gute | 19 | 11 | 48 | 01 | 104 | 24 | 10.000 N | 83.500 W | 80 | 0 |
| DEM 152 | 25 | 1 | 49 |  |  |  | 11.03 | 86.00 |  | E |
| DEM 153 | 11 | 6 | 49 |  |  |  | 12.50 | 87.00 | 100 | E |
| JEN 154 | 13 | 11 | 49 |  |  |  | 11.00 | 85.50 | 60 | E |
| gute | 05 | 10 | 50 | 16 | 609 | 31 | 11.000 N | $85.000 \%$ | N | 0 |
| 155 | 11 | 11 | 50 | 13 | 351 | 10 | 10.400 N | 85.700w | 0 | O |
| DEN 156 | 5 | 1 | 51 |  |  |  | 12.20 | 86.30 | N | D |
| OEM 157 | 2 |  | 51 |  |  |  | 12.00 | \& 7.00 |  | E |
| DEM 158 | 6 | 5 | 51 |  |  |  | 11.00 | 85.50 |  | E |
| DEN 159 | 11 |  | 51 |  |  |  | 13.00 | 87.50 | 100 | E |
| UEM 160 | 18 | 6 | 51 |  |  |  | 11.00 | 84.00 | 96 | E |
| DEM 161 | 8 | 7 | 51 |  |  |  | 12.00 | 86.00 |  | E |
| DEM 162 | - | 7 | 51 |  |  |  | 11.00 | 85.00 |  | E |
| DEM 166 | 6 | 8 | 51 |  |  |  | 13.05 | 87.50 | 33 | 5.5 |
| DEM 168 | 28 | 9 | 51 |  |  |  | 11.50 | 86.30 | 160 | E |
| ISS | 06 | C5 | 51 | 23 | 308 | 01 | 13.000 N | 87.800 W | 0 | 0 |
| 1SS | 06 | 05 | 51 | 23 | 303 | 32 | 13.000 N | 87.800 W | 86 | 0 |
| ISS | 07 | 05 | 51 | 20 | 22 | 21 | 13.000 N | 87.800 W | 0 | 0 |
| ISS | 02 | 08 | 51 | 20 | 030 | 17 | 13.000 N | 87.800 W | 33 | 0 |



|  |  |  |  |  |  |  |  |  |  |  |  | A3-15 |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Iss | C3 | 08 | 51 | 0525 |  | 13.030 N | 87.800w | 33 | 0 |  | 072 | 0 | 550PAS |  | 550 |
| 155 | 03 | 08 | 51 | 0023 | 58 | 13.000 V | 87.800W | 33 | 0 |  | 072 | 0 | dF600pas |  | 600 |
| ISS | 28 | 09 | 51 | 1207 | 07 | 11.50 ON | 86.300 H | 20 | 0 | 0 | 07 | 40 | 575 PaS | * | 575 |
| DEM 169 | 17 | 12 | 51 |  |  | 11.50 | 86.30 | 98 | E |  |  |  |  | * | 375 |
| DEM 171 | 2 | 3 | 52 |  |  | 11.53 | 86. 30 | 100 | D |  |  |  |  | * | 572 |
| -EM 172 | 3 | 3 | 52 |  |  | 11.50 | 86.30 | 33 | E |  |  |  |  | * | 500 |
| OEN 173 | 12 | 3 | 52 |  |  | 11.00 | 86.00 |  | E |  |  |  |  | * | 389 |
| ISS | 26 | 02 | 52 | 1539 | 28 | 11.530 N | 86.300 W | 96 | 0 |  | 074 | 0 | F 60CPA 5 |  | 800 |
| ISS | 13 | 05 | 52 | 1931 | 45 | 10.300 N | 85.300 h | 64 | 0 |  | 078 | 0 | 690PAS |  | 690 |
| 155 | c9 | 09 | 52 | 1254 | 42 | 09.200N | 84.200 H | 0 | 0 |  | 078 | 0 | F 688pas | * | 688 |
| 155 | 20 | 11 | 52 | 1537 | 17 | 12.100N | 87.900W | 33 | 0 |  | 074 | 0 | 625PAS |  | 625 |
| OEM 174 | 5 | 12 | 52 |  |  | 11.50 | 86. 30 | 33 | E |  |  |  |  | * | 486 |
| OEM 175 |  | 1 | 53 |  |  | 13.50 | $\varepsilon 6.50$ |  | 0 |  | OEEP M | AY be |  | * | 576 |
| DEM 180 | 21 | 2 | 54 |  |  | 12.53 | 87.00 | 60 | E |  |  |  |  | * | 420 |
| DEM 179 | 21 | 2 | 54 |  |  | 11.90 | 87.00 |  | E |  |  |  |  | * | 480 |
| TAC | 13 | 01 | 54 | 0026 | 30 | 14.030N | 86.41614 | 1 CO | 0 |  | 072 | 0 | 575 TAC |  | 575 |
| CGS | 19 | 02 | 54 | 2134 | 41 | 12.500 N | 87.500 W | N | - |  | 074 | 0 | $F 663 P A S$ | * | 663 |
| cos | 19 | 02 | 54 | 0040 | 25 | 11.500 N | 87.500 W | N | 0 |  | 074 | 0 | F 663PAS | * | 663 |
| C.GS | 20 | 02 | 54 | 0200 | 43 | 11.550 N | 67.500w | $N$ | 0 |  | 074 | 0 | $F$ 587PAS | * | 587 |
| CGS | 03 | 05 | 54 | 1713 | 32 | 12.000 N | 86.000W | 150 | 0 |  | 075 | 0 | 600PAS |  | 600 |
| OEM 182 | 27 | 11 | 54 |  |  | 12.00 | 87.00 |  | E |  |  |  |  | * | 373 |
| D\&M 183 | 2 | 12 | 54 |  |  | 12.00 | 86.50 | 100 | E |  |  |  |  | * | 497 |
| DEM 184 | 28 | 12 | 54 |  |  | 11.50 | 87. 50 |  | E |  |  |  |  | * | 515 |
| DEM 186 | 11 | 1 | 55 |  |  | 11.00 | 86.50 |  | E |  |  |  |  | * | 498 |
| DEM 189 | 7 | 3 | 55 |  |  | 13.05 | 87.00 |  | E |  |  |  |  | * | 394 |
| DEM 190 | 10 | 3 | 55 |  |  | 12.53 | 87.00 |  | E |  |  |  |  | * | 486 |
| DEM 194 | 11 | 4 | 55 |  |  | 13.50 | 87.00 |  | E |  |  |  |  | * | 506 |
| DEN 200 | 30 | 4 | 55 |  |  | 12.50 | 86.50 |  | 0 |  | DEEP M | AY BE |  | * | 559 |
| DEM 195 | 20 | 4 | 55 |  |  | 12.50 | E 7.00 |  | D |  |  |  |  | * | 597 |
| DEM 196 | 30 | 4 | 55 |  |  | 12.00 | 87.00 | N | 6.0 |  |  |  |  | * | 6.0 |
| DEM 2 Cl | 7 | 7 | 55 |  |  | 12.50 | 88.00 | $N$ | E |  |  |  |  | * | 515 |
| OEM 203 | 16 | 8 | 55 |  |  | 11.03 | 87.00 |  | E |  |  |  |  | * | 464 |
| DEM 204 | 29 | 8 | 55 |  |  | 12.00 | 87.00 |  | E |  |  |  |  | * | 458 |
| cGs | 04 | 04 | 55 | 1924 | 04 | 13.000 N | 87.000 W | N | 0 |  | 072 | 0 | 625 PAS | * | 625 |
| DEM 206 | 13 | 10 | 55 |  |  | 12.00 | 87.00 |  | E |  |  |  |  | * | 358 |
| DEM $2 C 7$ | 24 | 1 | 56 |  |  | 12.20 | 86.70 | I | 7.3 |  |  |  |  | * | 7.3 |
| DEN 208 | 21 | 4 | 56 |  |  | 12.00 | 87.33 |  | D |  |  |  |  | * | 581 |
| OEM 209 | 9 | - | 56 |  |  | 12.80 | 86.00 | $N$ | D |  |  |  |  | *** | 571 |
| cGs | 19 | 07 | 56 | 2326 | 25 | 09.500 N | 84.500 W | 0 | 0 |  | 078 | 0 | F 600日RK | * | 600 |
| ISS | 24 | 10 | 56 | 1442 | 12 | 11.790 oN | 86.460 W | N | 0 |  | 074 | 0 | OF730PAS | * | 730 |
| CGS | 25 | 10 | 56 | 0521 | 40 | 12.000N | 87.000 W | N | 0 |  | 074 | 0 | F 637PAS | * | 637 |
| IS 5 | 27 | 1.0 | 56 | 1533 | 02 | 12.880 N | 86.460 W | 90 | 0 |  | 074 | 0 | 587PAS |  | 587 |
| CGS | 10 | 11 | 56 | 0008 | 27 | 10.500 N | 86.000 W | 100 | 0 |  | 077. | 0 | 600PAS |  | 600 |
| QEM 216 | 28 | 1 | 57 |  |  | 12.00 | 86.50 |  | E |  |  |  |  | * | 486 |
| DEN 218 | 19 | 5 | 57 |  |  | 12.14 | 87.24 | 24 | E |  |  |  |  | * | 413 |
| SYKES | 27 | 10 | 57 | 1829 | 10 | 15.970 N | 88.110 W | 56 | 0 |  | 093 | 0 | 400 PaL | 008 | 400 |
| DEM 226 | 26 | 11 | 57 |  |  | 11.50 | 86. 50 | 100 | E |  |  |  |  | * | 512 |
| SYKES | C7 | 12 | 57 | 2218 | 51 | 13.550 N | 82.410w | 0 | 0 |  | 054 | 0 | 510 PAL | 023 | 510 |
| OfM 231 | 23 | 12 | 57 |  |  | 12.50 | 86.50 | 150 | E |  |  |  |  | * | 368 |
| DEM 235 | 4 | 6 | 58 |  |  | 12.00 | 86.50 |  | E |  |  |  |  | * | 352 |
| DEN 236 | 5 | 6 | 58 |  |  | 12.50 | 86.50 |  | E |  | DEEP M | AY BE |  | * | 461 |
| DEM 238 | 13 | 8 | 58 |  |  | 11.70 | 87.20 | N | 0 |  |  |  |  | *** | 538 |
| DEM 239 | 3 | , | 58 |  |  | 11.70 | 87.20 | N | E |  |  |  |  | *** | 351 |
| CGS | 27 | 06 | 58 | 0544 | 28 | 13.000 N | 88.500W | 60 | 0 |  | 073 | 0 | DF6009AS |  | 600 |
| UEM 241 | 14 | 11 | 58 |  |  | 12.36 | 86.37 | 72 | c |  |  |  |  | * | 670 |
| DEM 242 | 4 | 12 | 58 |  |  | 11.50 | 86.50 | 100 | 6.0 |  |  |  |  | * | 6.0 |
| DEN 243 | 27 | 12 | 58 |  |  | 12.85 | 87.30 |  | D |  |  |  |  | * | 593 |
| DEM 445 | 21 | 2 | 59 |  |  | 11.70 | 87.20 |  | 0 |  |  |  |  | * | 582 |
| DEM 246 | 15 | 3 | 59 |  |  | 12.00 | 85.00 |  | E |  |  |  |  | * | 386 |
| DEM 247 | 31 | 3 | 59 |  |  | 13.00 | 87.00 |  | E |  |  |  |  | * | 482 |



|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CGS-8 | 05 | 0763 | 14 | 40 | 54 | 12.800N | 28.900w | 85 | 410 MB | 076 | 0 | 0 | 011 | 329 |
| c.6 S-8 | 30 | 0763 | 12 | 25 | 39 | 11.400 N | 87.300W | 33 | 420 MS | 074 | 0 | 0 | 005 | 345 |
| CGS-8 | 31 | 0763 | 18 | 33 | 28 | 09.200N | 82.400 W | 33 | 410 MB | 080 | 0 | 0 | 036 | 329 |
| CGS-B | 12 | 0863 | 17 | 19 | 05 | 09.800N | 84.200 W | 114 | 420 MB | 078 | 0 | 0 | 007 | 345 |
| GGS-B | 28 | 0863 | 05 | 55 | 51 | 12.600 N | 87.200 W | 115 | 420 MB | 074 | 0 | 0 | 006 | 345 |
| CGS-3 | 31 | 0863 | 13 | 08 | 46 | 11.9JON | 87.000 W | 48 | 490 ME | 074 | 0 | 0 | 018 | 462 |
| $665-8$ | 01 | 0963 | 22 | 5 ? | 34 | 11.300 N | 85.500W | 120 | 440 MB | 075 | 0 | 0 | 010 | 379 |
| CG 5-8 | 08 | 0963 | 05 | 28 | 37 | 12.300 N | 87.900W | 31 | 410 MB | 074 | 0 | 0 | 038 | 329 |
| CGS-8 | 17 | C9 63 | 03 | 48 | 09 | 12.60 oN | 87.100 W | 144 | 390Mr8 | 074 | 0 | 0 | 007 | 300 |
| CG5-8 | ¢8 | 0963 | 05 | 25 | 03 | 10.20 OV | 86.000 W | 33 | 410 MB | 077 | 0 | 0 | 008 | 329 |
| CG s-B | 01 | 1063 | 10 | 30 | 31 | 10.200 N | 84.500w | 46 | 460 MB | 078 | 0 | 0 | 022 | 412 |
| CGS-B | 07 | 1063 | 03 | 59 | 54 | 11.600 N | 86.900 ${ }^{\text {d }}$ | 50 | 450 MB | 074 | 0 | 0 | 015 | 395 |
| DEM 326 | 13 | 1 C 63 |  |  |  | 12.53 | 87.10 | N | D |  |  |  | *** | 535 |
| CGS-8 | 13 | 1063 | 05 | 10 | 12 | 09.800 N | 84. 100 W | 63 | 440 MB | 078 | 0 | 0 | 012 | 379 |
| CGS-8 | 06 | 1163 | 21 | 49 | 57 | 12.230 N | 88.000W | 37 | 410 MB | 076 | 0 | 0 | 010 | 329 |
| CG S-8 | 10 | 1163 | 07 | 18 | 07 | 12.900 N | 88.500 ${ }^{\text {d }}$ | 45 | 420MB | 076 | 0 | 0 | 007 | 345 |
| DEM 327 | 23 | 1163 |  |  |  | 12.00 | 87. 20 | N | C |  |  |  | *** | 605 |
| CGS-8 | 16 | 1263 | 06 | 23 | 20 | 12.200 N | 88.400w | 34 | 430 MBB | 076 | 0 | 0 | 010 | 362 |
| CG S-8 | 40 | 1263 | 22 | 28 | 31 | 13.200 N | 88.000W | 64 | 430 NB | 073 | 0 | 0 | 005 | 362 |
| DEM 328 | 21 | 1263 |  |  |  | 13.40 | 87.20 | N | D |  |  |  | *** | 570 |
| CGS-8 | 31 | 1263 | 14 | 22 | 07 | 12.40 ON | 8 7. 900 W | 77 | 430 MB | 074 | 0 | 0 | 007 | 362 |
| DEM 329 | 18 | 264 |  |  |  | 13.03 | 87. 50 | N | D |  |  |  | *** | 546 |
| DEM 331 | 11 | 364 |  |  |  | 12.50 | 87. 10 | N | 0 |  |  |  | ** ${ }^{\text {\% }}$ | 540 |
| DEN 332 | 29 | 464 |  |  |  | 12.30 | 87.40 | N | $E$ |  |  |  | *** | 515 |
| CGS-B | 09 | 0164 | 18 | 38 | 10 | 14.900 N | 87.900 W | 33 | 470 MB | 072 | 0 | 0 | 005 | 428 |
| CGS-8 | 030 | 0264 | 01 | 46 | 27 | 13.000 N | 88.000 W | 61 | 410 MB | 073 | 0 | 0 | 006 | 329 |
| ccs- 8 | 20 | 0264 | 09 | 54 | 12 | 09.50 ON | 84.600 W | 33 | 430 MB | 078 | 0 | 0 | 009 | 362 |
| $\cos -8$ | 210 | 0264 | 07 | 24 | 08 | 12.800 N | 87.900 W | 62 | 390 NB | 074 | 0 | 0 | 007 | 300 |
| CGS S-A | 24 | 0264 | 02 | 29 | 12 | 13.000 N | 87.200w | 83 | 390M8 | 072 | 0 | 0 | 006 | 300 |
| CGS- 3 | 02 | 0364 | 16 | 09 | 46 | 12.50 ON | 88.000W | 63 | 440 MA | 076 | 0 | 0 | 018 | 379 |
| CG S-8 | 05 | 0364 | 14 | 30 | 18 | 12.130 N | 88. 100 W | 53 | 43 OMB | 076 | 0 | 0 | 009 | 362 |
| CGS-B | 06 | 0364 | 02 | 55 | 11 | 12.400 N | 87.600 W | 100 | 39048 | 074 | 0 | 0 | 008 | 300 |
| CGS-B | 16 | 0364 | 06 | 06 | 51 | 13.500 N | 88.300 W | 92 | 390MB | 073 | 0 | 0 | 008 | 300 |
| CGS-8 | 27 | 0364 | 17 | 27 | 35 | 09.400N | 83.900 W | 33 | 420 MB | 078 | 0 | 0 | 015 | 345 |
| CGS-B | 27 | 0364 | 17 | 12 | 36 | 09.200N | 84.000 W | 33 | 420 MB | 078 | 0 | 0 | 011 | 345 |
| CGS-B | 02 | 0464 | 15 | 25 | 41 | 09.500N | 82.700W | 33 | 390ME | 080 | 0 | 0 | 007 | 300 |
| CGS-B | 020 | 0464 | 03 | 48 | 59 | 12.500N | 87.800 W | 32 | 420 M8 | 074 | 0 | 0 | 009 | 345 |
| cG S-8 | 04 | 0464 | 06 | 43 | 20 | 12.50 ON | 67.700W | 41 | 430 M 8 | 074 | 0 | 0 | 012 | 362 |
| CGS-B | 24 | 0464 | 14 | 40 | 28 | 13.30 ON | 88.800 W | 158 | 510 MB | 073 | 0 | 0 | 044 | 495 |
| C GS-B | 29 | 0464 | 08 | 08 | 41 | 12.150N | 88.400w | 33 | 390 MB | 076 | 0 | 0 | 007 | 300 |
| cos | 29 | 0464 | 21 | 53 | 15 | 11.800 N | 87.600 W | 33 | 450 MB | 074 | 0 | 0 | 007 | 395 |
| CGS-B | 30 | 0464 | 15 | 05 | 57 | 11.200 N | 86. 700 H | 33 | 430 MB | 074 | 0 | 0 | 005 | 362 |
| CGS-B | 02 | 0564 | 19 | 53 | 10 | 09.530N | 84.500 W | 44 | 43 OM8 | 078 | 0 | 0 | 007 | 362 |
| CGS-B | 150 | 0564 | 05 | 46 | 32 | 09.80 ON | 85.500 W | 33 | 420 NB | 077 | 0 | 0 | 010 | 345 |
| CGS-B | 15 | 0564 | 12 | 10 | 25 | 10.50 ON | 85.700W | 33 | 450 MP | 078 | 0 | 0 | 024 | 395 |
| $\mathrm{CGS}-\mathrm{B}$ | 23 | 0564 | 06 | 45 | 21 | 11.750 N | 86.600 W | 93 | 460 MB | 074 | 0 | 0 | 007 | 412 |
| C6S-8 | 10 | 0664 | 16 | 25 | 09 | 12.000 N | 87.900 W | 55 | 420 MB | 074 | 0 | 0 | 006 | 345 |
| CGS-8 | 15 | 0664 | 09 | 41 | 24 | 12.60 ON | 88.300 W | 55 | 410 MB | 076 | 0 | 0 | 007 | 329 |
| CGS-8 | 150 | 0664 | 11 | 13 | 47 | 12.630 N | 88.000\% | 14 | 410 NB | 076 | 0 | 0 | 005 | 329 |
| cos-B | 17 | 0664 | 09 | 11 | 42 | 12.000N | 87. 200w | 33 | 410M9 | 074 | 0 | 0 | 008 | 329 |
| CGS-B | 19 | 0664 | 17 | 31 | 56 | 12.400 N | 88.100 W | 53 | 400 MB | 076 | 0 | 0 | 011 | 312 |
| $\cos -8$ | 20 | 0664 | 05 | 02 | 37 | 09.2J0N | 84.40 OW | 45 | 430 MLB | 078 | 0 | 0 | 007 | 362 |
| 66S-8 | 01 | 0764 | 00 | 42 | 55 | 12.000 N | 86.700 W | 108 | 430 MB | 075 | 0 | 0 | 008 | 362 |
| c.cs-8 | C4 | 0764 | 02 | 36 | 54 | 11.300N | 86.500w | 90 | 410 MB | 074 | 0 | 0 | 007 | 329 |
| COS-8 | 07 | 0764 | 09 | 59 | 19 | 10.830 N | 86.600 W | 33 | 490 MB | 077 | 0 | 0 | 010 | 462 |
| CGS-8 | 18 | 0764 | 20 | 37 | 35 | 11.00 ON | 87.000 W | 33 | 460 MB | 074 | 0 | 0 | 010 | 412 |
| CGS-8 | 21. | 0764 | 07 | 01 | 59 | 13.100 N | 88.400 W | 68 | 470 MA | 073 | 0 | 0 | 030 | 428 |
| CGS-8 | 23 | 0764 | 04 | 57 | 54 | 10.500 V | 83.900 W | 114 | 420 MB | 078 | 0 | 0 | 010 | 345 |
| CGS-B | 26 | 0764 | 13 | 53 | 25 | 11.800 N | 88. 200 W | 9 | 440 MB | 076 | 0 | 0 | 010 | 379 |
| CGS-8 | 280 | 0764 | 02 | 53 | 26 | 11.50 ON | 86.400 W | 111 | 420 mb | 074 | 0 | 0 | 006 | 345 |


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| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CGS-B | 28 | 0764 | 01 | 54 | 18 | 10.800 ON | 86.2004 | 33 | 420 Ha | 077 | 0 | 0 | 006 | 345 |
| CSS-B | 30 | 0764 | 15 | 13 | 39 | 10.600 N | 86.500W | 33 | 470 NB | 077 | 0 | 0 | 007 | 428 |
| CGS-B | 30 | 0764 | 05 | 16 | 03 | 11.100 N | 86.200 w | 42 | 570 MB | 074 | 0 | 0 | 022 | 594 |
| CGS-B | 01 | C8 64 | 08 | 55 | 42 | 11.800 N | 87.000W | 88 | 430 Mg | 074 | 0 | 0 | 008 | 362 |
| CGS-8 | 02 | 0864 | 04 | 00 | 45 | 10.900 N | 86.300w | 32 | 470 FB | 077 | 0 | 0 | 022 | 428 |
| COS-8 | 07 | 0864 | 08 | 21 | 0's | 11.800 N | 86.900 4 | 130 | 470 MB | 074 | 0 | 0 | 010 | 428 |
| CGS-8 | 08 | 0864 | 15 | 45 | 10 | 12.500 N | \&7.800W | 63 | 580 MB | 074 | 0 | 0 | 032 | 611 |
| CGS-8 | 10 | C8 64 | 14 | 00 | 51 | 12.430 N | 88.300列 | 71 | 400 MB | 076 | 0 | 0 | 006 | 312 |
| CGS-B | 12 | 0864 | 12 | 47 | 46 | 11.400 N | 86. 100 H | 135 | 410 mB | 074 | 0 | 0 | 007 | 329 |
| c.cs-3 | 15 | 0864 | 14 | 43 | 03 | 12.030 N | 88.000w | 39 | A0OME | 076 | 0 | 0 | 036 | 312 |
| cGS-8 | 16 | 0864 | 12 | 34 | 34 | 12:000N | 88.600w | 33 | 430 MB | 076 | 0 | 0 | 011 | 362 |
| CGS-8 | 16 | 0864 | 07 | 30 | 12 | 13.300 N | 87.600 | 60 | 390 MB | 072 | 0 | 0 | 035 | 300 |
| CGS-8 | 17 | c8 84 | 19 | 05 | 44 | 12.400 N | 86.800 H | 116 | 450 mg | 075 | 0 | 0 | 008 | 395 |
| CGS-8 | 20 | 0864 | 08 | 26 | 52 | 11.700 V | 87. 200 W | 25 | 430 MB | 074 | 0 | 0 | 008 | 362 |
| CGS-8 | 20 | 0864 | 09 | 12 | 53 | 11.000 N | 87.500w | 33 | 420 Ms | 074 | 0 | 0 | 008 | 345 |
| CGS-B | 25 | 0864 | 05 | 03 | 18 | :2.100N | E7.700W | 72 | 400 me | 074 | 0 | 0 | 035 | 312 |
| CGS-8 | 29 | 0864 | 20 | 51 | 54 | 11.450 N | 87. 200 w | 33 | 420 MB | 074 | 0 | 0 | 005 | 345 |
| CGS-B | 30 | 0864 | 15 | 20 | 50 | 12.600 N | 98.500W | 54 | 460 NB | 076 | 0 | 0 | 015 | 412 |
| CGS-8 | 31 | 0864 | 17 | 07 | 39 | 09.60 ON | 85.400w | 33 | 420 mB | 077 | 0 | 0 | 036 | 345 |
| CGS-8 | 03 | 0964 | O1 | 55 | 32 | 12.200 N | 67,000W | 108 | 400 MB | 074 | 0 | 0 | 005 | 312 |
| ccs-8 | 12 | 0964 | 19 | 05 | 47 | 11.200 N | 86.900 W | 33 | 470 MB | 074 | 0 | 0 | 014 | 428 |
| CGS-B | 04 | 1064 | 06 | 30 | 14 | 11.300 ON | 67.400W | 33 | 420 MB | 074 | 0 | 0 | 007 | 345 |
| CGS-8 | 15 | 10.64 | 21 | 09 | 02 | 99.600 | 840000 d | 51 | 420 MB | 078 | 0 | 0 | 007 | 345 |
| CGS-8 | 15 | 1064 | 21 | 04 | 11 | 09.100 N | 84.000 W | 36 | 430 MB | 078 | 0 | 0 | 011 | 362 |
| cGS-8 | 15 | 1064 | 22 | 52 | 35 | 09.600N | 83. 1004 | 37 | 420 ME | 078 | 0 | 0 | 011 | 345 |
| CGS-B | 29 | 1064 | 12 | 21 | 52 | 13.230 N | 88. 500 W | 33 | 400 M 8 | 073 | 0 | 0 | 008 | 312 |
| CGS-B | 02 | 1164 | 07 | 07 | 57 | 11.800 N | 86.900 W | 117 | 460 MB | 074 | 0 | 0 | 009 | 412 |
| CGS-8 | 07 | 11184 | 01 | 36 | 56 | 12.000 N | 88.000W | 33 | 440 MP | 076 | 0 | 0 | 012 | 379 |
| CGS-B | 13 | 1164 | 08 | 02 | 38 | 13.000 N | 88.600 W | 86 | 490 MB | 073 | 0 | 0 | 024 | 462 |
| CGS-B | 27 | 1164 | 10 | 55 | 11 | 13.400 N | 88.700 W | 33 | 410 MB | 073 | 0 | 0 | 056 | 329 |
| $\operatorname{ccs}-8$ | 03 | 1264 | 14 | 51 | 10 | 12.300 N | 88.500 N | 33 | 410 MB | 076 | 0 | 0 | 010 | 329 |
| cGS-8 | 08 | 1264 | 04 | 12 | 53 | 12.500 V | 87.000 W | 48 | 500 NB | 074 | 0 | 0 | 029 | 478 |
| $\operatorname{ccss}-8$ | 09 | 1264 | 14 | 22 | 03 | 13.20 cN | 87.200 W | 200 | 390 MB | 072 | 0 | 0 | 008 | 300 |
| C.GS-8 | 12 | Of 65 | 03 | 19 | 10 | 12.300 N | 88.900W | 39 | 430 Mt | 076 | 0 | 0 | 007 | 362 |
| CGS-8 | 13 | 0165 | 02 | 19 | 49 | 10.100v | 8 6. 300 W | 33 | 480 NB | 077 | 0 | 0 | 009 | 445 |
| $\operatorname{cosc} 8$ | 21 | 0165 | 20 | 43 | 55 | 12.300 N | 86.700 W | 138 | 450 MB | 075 | 0 | 0 | 016 | 379 |
| CCS- 8 | 15 | 0265 | 02 | 29 | 48 | 09.900 N | 86.50014 | 33 | 550ME | 077 | 0 | 0 | 011 | 561 |
| CGS-B | 01 | 0365 | 15 | 17 | 45 | 10.830 N | 85.700w | 55 | 490 MB | 077 | 0 | 0 | 009 | 462 |
| Cos-B | 21 | 0365 | 09 | 42 | 41 | 1i. 700 N | 86.400 W | 36 | 520 Mm | 074 | 0 | 0 | 036 | 511 |
| CGS-8 | 22 | 0365 | 00 | 17 | 27 | 11.900N | 87.900 W | 33 | 430 ${ }^{\text {m }} \mathrm{B}$ | 074 | 0 | 0 | 037 | 362 |
| CSS-9 | 23 | 0365 | 21 | 21 | 52 | 11.000 N | 36.600 W | 33 | 480 MB | 0.74 | 0 | 0 | 014 | 445 |
| CGS-8 | 23 | 0365 | 02 | 58 | 39 | 12.300 N | 88.200W | 33 | 410 MB | 076 | 0 | 0 | 038 | 329 |
| CGS-B | 23 | 6365 | 17 | 18 | 29 | 12.80 ON | 88.200 W | 33 | 420 MB | 076 | 0 | 0 | 006 | 345 |
| CGS-8 | 09 | 0465 | 15 | 09 | 15 | 11.400 N | 87.400 W | 33 | 420 NB | 074 | 0 | 0 | 009 | 345 |
| CGS-B | 13 | 0465 | 04 | 46 | 43 | 09.740N | $9 a_{8} .400$ b | 33 | 400 MB | 078 | 0 | 0 | 006 | 312 |
| CGS-B | 24 | 0465 | 13 | 25 | 41 | 12.70 ON | 82.000 W | 33 | 440 Am | 094 | 0 | 0 | 009 | 379 |
| CGS-8 | 31 | 0565 | 20 | 46 | 54 | 12. 290 N | 86.000W | 28 | 470 MB | 074 | 0 | 0 | 030 | 428 |
| CGS-B | 06 | 0665 | 08 | 34 | 17 | 12.100N | 87.200W | 33 | 460 MB | 074 | 0 | 0 | 005 | 412 |
| CGS-3 | C7 | 0.565 | 07 | 41 | 47 | 10.40 ON | 88.0006 | 33 | 470 ME | 077 | 0 | 0 | 007 | 428 |
| CGS-8 | 08 | 0665 | 01 | 25 | 59 | 11.000 N | 86.800 W | 33 | 470 MB | 074 | 0 | 0 | 007 | 428 |
| CGS~B | 18 | 0665 | 09 | 28 | 21 | 11.0600 N | 88.200 4 | 33 | 430 MB | 076 | 0 | 0 | 007 | 362 |
| CGS-B | 23 | 0665 | 07 | 37 | 46 | 11.400 N | 87.800 W | 24 | 450 NB | 074 | 0 | 0 | 028 | 395 |
| CGS-B | 27 | 0665 | 13 | 08 | 28 | 12.600 N | 87.900w | 33 | 410 MB | 074 | 0 | 0 | 007 | 329 |
| CGS-B | 01 | 0765 | 16 | 57 | 30 | 12.100 N | 87.500 | 176 | 430 MB | 074 | 0 | 0 | 007 | 362 |
| ccs-8 | 16 | 0765 | 10 | 34 | 12 | 11.060 N | 88.000 W | 30 | 490 MB | 076 | 0 | 0 | 022 | 462 |
| CGS-B | 16 | 0765 | 11 | 21 | 10 | 11.600 N | 87,800 ${ }^{\text {d }}$ | 33 | 480 MB | 074 | 0 | 0 | 026 | 445 |
| C.65-3 | 17 | 0765 | 04 | 05 | 16 | 10.100N | 86.500 w | 33 | 430 NB | 077 | 0 | 0 | 006 | 362 |
| CGS-8 | 17 | 0765 | 13 | 59 | 46 | 12.200 N | 87.900N | 56 | 440 MB | 074 | 0 | 0 | 013 | 379 |
| CGS-B | 19 | 0765 | 22 | 14 | 21 | 10.600N | 85. 300 d | 80 | 460 ME | 078 | 0 | 0 | 019 | 412 |
| CGS-B | 30 | 0765 | 06 | 33 | 30 | 18.03.0N | 88. 200 H | 33 | 420 mb | 076 | 0 | 0 | 009 | 345 |


|  |  |  |  |  |  |  |  |  |  |  | A3- |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ccs-b | 11 | 086 | 6518 | 15 | 39 | 10.800N | 83.200w | 33 | $390 \mathrm{\mu g}$ | 078 | 0 | 0 | 007 | 300 |
| 665-8 | 09 | 096 | 6512 | 43 | 37 | 09.600 N | 85.300 W | 33 | 450 MB | 077 | 0 | 0 | 008 | 395 |
| C. $65-8$ | 27 | 096 | $65 \quad 17$ | 37 | 53 | 12.930 N | 88.400 W | 33 | 420 MB | 076 | 0 | 0 | 007 | 345 |
| C6S-B | 16 | 106 | 6514 | 22 | 55 | 09.020N | 83.500 W | 48 | 510 MB | 078 | 0 | 0 | 053 | 495 |
| CG5-B | 20 | 10 | 6523 | 54 | 51 | 12.700N | 87.000w | 91 | 560 mB | 074 | 0 | 0 | 032 | 578 |
| cos- 8 | 20 | 106 | 6523 | 54 | 30 | 12.500 N | 97.300w | 72 | 540 MB | 074 | 0 | 0 | 063 | 545 |
| CGS-B | 02 | 116 | 6522 | 44 | 4 | 10.530 N | 86. 3006 | 69 | 450 MB | 077 | 0 | 0 | 010 | 395 |
| cGs-8 | 12 | 116 | 6508 | 59 | 54 | 10.600 N | 84.400w | 37 | $500 \mathrm{M8}$ | 078 | 0 | 0 | 037 | 478 |
| cGS-8 | 21 | 116 | 6502 | 19 | 12 | 12.120 N | 88.900W | 33 | 430 MB | 076 | 0 | 0 | 008 | 362 |
| cos-8 | C6 | 126 | $65 \quad 13$ | 19 | 13 | 12.400 N | 87.400w | 44 | 390M ${ }^{\text {P }}$ | 074 | 0 | 0 | 007 | 300 |
| cos-b | 06 | 126 | $65 \quad 04$ | 39 | 10 | 12.5004 | 87.300 W | 50 | 450 MB | 0.74 | 0 | 0 | 024 | 395 |
| c, 5-8 | 10 | 126 | 6517 | 59 | 11 | 12.400 N | 87.300 W | 33 | 420ms | 074 | 0 | 0 | 011 | 345 |
| cos-8 | 16 | 126 | 6505 | 23 | 06 | 12.600 N | 88.800w | 152 | 440 MB | 076 | 0 | 0 | 019 | 379 |
| CGS-B | 17 | 126 | $65 \quad 04$ | 03 | 28 | 09.300 N | 84.200 W | 35 | 420 MB | 078 | 0 | 0 | 007 | 345 |
| CGS-8 | 24 | 016 | $66 \quad 03$ | 46 | 57 | 12.300N | 88.400W | 46 | 450 MB | 076 | 0 | 0 | 018 | 395 |
| cGS-8 | 09 | 026 | 6608 | 22 | 44 | 12.700N | 87.800w | 98 | 440 MB | 074 | 0 | 0 | 021 | 379 |
| CGS-8 | 23 | 026 | 6601 | 02 | 01 | 09.730N | 85.800w | 35 | 400 MB | 077 | 0 | 0 | 008 | 312 |
| C65-8 | 13 | 036 | 6621 | 46 | 23 | 14.200 N | 88.400 W | 36 | 420 MB | 072 | 0 | 0 | 017 | 345 |
| cGs-B | 27 | 036 | 6623 | 12 | 49 | 09.80 ON | 83.300 W | 61 | 420 MB | 078 | 0 | 0 | 018 | 345 |
| cos-B | 28 | 036 | 6600 | 33 | 30 | 09.500N | 83.100 W | 46 | 400 MB | 078 | 0 | 0 | 008 | 312 |
| CGS-B | 09 | 046 | 6602 | 34 | 23 | 09.400N | 84.200 W | 47 | 530 MB | 078 | 0 | 0 | 071 | 528 |
| CGS- 9 | 09 | 046 | $66 \quad 02$ | 42 | 11 | 109.500 N | 84.100W | 49 | 570 MB | 078 | 0 | 0 | 079 | 594 |
| CGS-8 | 12 | 046 | $66 \quad 03$ | 34 | 22 | 12.600 N | 87.600w | $1 \mathrm{CH}_{4}$ | 390 MB | 074 | 0 | 0 | 009 | 300 |
| $6 \mathrm{C} 5-8$ | 12 | 046 | $66 \quad 17$ | 30 | 49 | 12.600 N | 88.000 W | 33 | 440 MB | 076 | 0 | 0 | 019 | 379 |
| CGS-3 | 14 | 046 | 6606 | 57 | 45 | 11.800 N | 87.500w | 33 | 410 m 8 | 074 | 0 | 0 | 007 | 329 |
| CGS-B | 16 | 046 | 6613 | 21 | 40 | 12.330 N | 88.4004 | 33 | 440 MB | 076 | 0 | 0 | 017 | 379 |
| cos-8 | 24 | 046 | $66 \quad 15$ | 41 | 03 | 13.700 N | 88.300 W | 33 | 390NB | 073 | 0 | 0 | 009 | 300 |
| 66s-8 | 01 | 056 | $66 \quad 22$ | 29 | 45 | 09.600 N | 83.900 W | 71 | 430 MB | 078 | 0 | 0 | 018 | 362 |
| CGS-B | 04 | 056 | $66 \quad 18$ | 13 | 55 | 12.500N | 87.700w | 68 | 510 MB | 074 | 0 | 0 | 036 | 495 |
| $\operatorname{cos-8}$ | 11 | 056 | 6605 | 57 | 02 | 12.300N | 86.800w | 33 | 400 MB | 075 | 0 | 0 | 007 | 312 |
| C.6.5-8 | 20 | 056 | 6603 | 58 | 01 | 11.60 ON | 82.600 w | 33 | 390 MB | 079 | 0 | 0 | 009 | 300 |
| CGS-8 | 28 | 056 | 6614 | 34 | 39 | 11.900 N | 88. 100 W | 33 | 430 MP | 076 | 0 | 0 | 013 | 362 |
| CGS-E | 30 | 06 | 6610 | 39 | 00 | 11.900 N | 85.900w | 187 | 400 MB | 075 | 0 | 0 | 021 | 312 |
| CGS- 8 | 01. | 076 | $66 \quad 20$ | 17 | 49 | 13.700N | 88.400 W | 201 | 460 MB | 073 | 0 | 0 | 049 | 412 |
| CGS-8 | 08 | 076 | $66 \quad 13$ | 22 | 13 | 12.400 N | 88.900 W | 43 | 430 MB | 076 | 0 | 0 | 013 | 362 |
| cos- ${ }^{\text {cos }}$ | 10 | 076 | 6619 | 18 | 57 | 09.700 ${ }^{\text {d }}$ | 83.900W | 33 | 410 mb | 078 | 0 | 0 | 008 | 329 |
| cGs-B | 13 | 076 | 6608 | 20 | 58 | 12.60 ON | 87.800W | 56 | 530 MB | 074 | 0 | 0 | 073 | 528 |
| CGS-8 | 17 | 076 | 6600 | 14 | 03 | 09.200N | 82.300 W | 44 | 400 MB | 080 | 0 | 0 | 013 | 312 |
| CG S-8 | 21 | 076 | 6613 | 53 | 23 | 09.100N | 83.900 W | 33 | 400 MB | 078 | 0 | 0 | 011 | 312 |
| CGS- $B$ | 24 | 076 | 6606 | 11 | 55 | 12.200 N | 88.300w | 61 | 410 MB | 076 | 0 | 0 | 013 | 329 |
| CGS-B | 24 | 076 | 6618 | 50 | 54 | 12. 200 N | 88.700w | 33 | 410 MB | 076 | 0 | 0 | 010 | 329 |
| cg S-E | 25 | 076 | $66 \quad 00$ | 42 | 58 | 13.200 N | 87.800W | 210 | 400 MB | 072 | 0 | 0 | 006 | 312 |
| CGS-B | 31 | 076 | $66 \quad 19$ | 10 | 46 | 12.40 0N | 88. 100 W | 63 | 420 MB | 076 | 0 | 0 | 032 | 345 |
| CGS-8 | c 7 | 086 | $66 \quad 04$ | 11 | 30 | 11.000 N | 86.200W | 125 | 410 mB | 074 | 0 | 0 | 009 | 329 |
| CGS-B | 09 | 08 | 6611 | 12 | 39 | 09.300 N | 83.800W | 35 | 470 MB | 078 | 0 | 0 | 032 | 428 |
| CGS -8 | 11 | 086 | 6609 | 50 | 41 | 10.500 N | 84.00 0W | 96 | 430 M 8 | 078 | 0 | 0 | 014 | 362 |
| CGS-8 | 23 | 086 | 6606 | 07 | 36 | 12.400 | 88.200 W | 39 | 400 MB | 076 | 0 | 0 | 011 | 312 |
| CGS-B | 20 | 056 | 6603 | 53 | 34 | 13.120N | 88. 200 W | 81 | 400 MB | 073 | 0 | 0 | 008 | 312 |
| ctse | 08 | 106 | 6620 | 38 | C7 | 10.700 N | 82.400 W | 33 | 410 MB | 079 | 0 | 0 | 008 | 329 |
| c, GS-B | 12 | 10 | 6620 | 20 | 06 | 11.2JON | 86.200W | 45 | 510 MB | 074 | 0 | 0 | 054 | 495 |
| $\cos$ S-B | 19 | 11 | 6616 | 01 | 46 | 09.200 N | 85.800 W | 25 | 430 MB | 077 | 0 | 0 | 012 | 362 |
| CGS-8 | 10 | 126 | 66 Ol | 09 | 39 | 10.300 N | 85. 100 W | 87 | 430 MB | 078 | 0 | 0 | 011 | 362 |
| CG5-B | 11 | 126 | 6617 | 21 | 56 | 10.200 N | 840 $0^{10006}$ | 82 | 430 MB | 078 | 0 | 0 | 018 | 362 |
| CGS-B | 14 | 12 | 6601 | 33 | 13 | 10.600 N | 86800 W | 33 | 430 NB | 077 | 0 | 0 | 008 | 362 |
| 6 CSO | 23 | 126 | 6622 | 10 | 25 | 12.60 aN | 87.700w | 32 | 450 MB | 074 | 0 | 0 | 019 | 395 |
| 6G5-8 | 23 | 126 | 6602 | 02 | 19 | 12.90 ON | 88.600W | 88 | 450 MB | 076 | 0 | 0 | 023 | 395 |
| CGS-B | 27 | 126 | 6621 | 22 | 15 | 13.350 N | 88.800W | 78 | 54 CMB | 073 | 0 | 0 | 090 | 545 |
| 6GS-8 | 30 | 126 | 6618 | 35 | 15 | 10.100 N | 84.700W | 43 | 440 MB | 078 | 0 | 0 | 015 | 379 |
| $\mathrm{CGS}-\mathrm{B}$ | C4 | 016 | 6700 | 28 | 07 | 13.120N | 88.625 w | 72 | 410 me | 073 | 0 | 0 | 010 | 329 |
| c.65-8 | 09 | 016 | 6722 | 31 | 22 | 13.138 N | 88.98 lW | 78 | 410 MB | 073 | 0 | 0 | 008 | 329 |


|  |  |  |  |  |  |  | A3－2 |  |  |  |  |  |  |  |
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| CG S－B | 16 | 0167 | 1530 | 3048 | 4710.6 .68 | 85．920w | 33 | 470 MB | 078 | 0 |  | 0 | NO19＊ | 428 |
| CGS－B | 19 | 0167 | 0219 | 1923 | 2312.561 N | 86.813 W | 200 | 450\％8 | 075 | 0 |  | 0 | G024 | 395 |
| CGS－6 | 29 | 0167 | 201 | 1122 | 2211.953 N | 80.9284 | 33 | 450 me | 078 | 0 |  | 0 | NO 18 | 395 |
| CGS－8 | 30 | 0167 | 0930 | 3027 | 27 12．196的 | 878．5964 | 8 | 410 mb | 074 | 0 |  | 0 | 010＊ | 329 |
| CGS－B | 06 | 0367 | 2331 | 3125 | 2512.389 N | 87． 127 H | 159 | 410 MB | 074 | 0 |  | 0 | 008＊ | 329 |
| CG S－B | 08 | 0367 | 155 | 5215 | 1513.049 N | 88．1274 | 75 | 39048 | 073 | 0 |  | 0 | 005 | 300 |
| CGS－B | C8 | 0367 | 2307 | 0702 | 0215.101 N | 88.8826 | 76 | 420 me | 072 | 0 |  | 0 | 036＊ | 345 |
| Cssse | 22 | 0367 | 0915 | 1529 | 2912.653 N | 87．823 d | 70 | $440 \mathrm{M8}$ | 074 | 0 |  | 0 | 025 | 379 |
| cgs－b | 25 | 0367 | 0726 | $26 \quad 37$ | 37.2 .2060 N | 67．876 | 76 | 400 ME | 074 | 0 |  | 0 | 035＊ | 312 |
| CGS－B | 27 | C3 67 | 1440 | 4013 | 1312.22 Nm | 87．712 | 54 | 420 MB | 07／3 | 0 |  | 0 | 019 | 345 |
| CGS－B | 12 | 0467 | 0\％ 56 | 5625 | 2512.2174 | 88．1024 | 33 | 480 ¢8 | 076 | 0 |  | 0 | N025 | 445 |
| cGS－8 | 15 | 0467 | 2210 | 1008 | 08 a 20.443 N | 88．163 4 | 33 | 430 MB | 076 | 0 |  |  | NO06＊＊ | 362 |
| c．gs－8 | 18 | 0467 | 0824 | 2417 | 17 11．649N | 88．415 | 33 | 400 HB | 076 | 0 |  | 0 | NOOT＊ | 312 |
| CGS－B | 18 | 04.67 | 082 | 2912 | $12 \mathrm{1L}$. | 67． 307 H | 65 | 460 MB | 074 | 0 |  | 0 | 028 | 412 |
| C6S－8 | 18 | 0467 | 0705 | 9508 | 0810.789 N | 86．7774 | 53 | 480 MB | 077 | 0 |  | 0 | 041 | 445 |
| CGS－8 | 18 | 0467 | 1305 | 051.5 | 1512.865 N | 07．943W | 84 | 390Mg | 074 | 0 |  | 0 | 007＊ | 300 |
| CS s－ | 23 | 0467 | 14 ¢ | $44_{3} 10$ | 1012.525 N | 86．480 4 | 82 | 440 Mg | 074 | 0 |  | 0 | 014 | 379 |
| CGS－8 | 30 | 0467 | 0310 | 1049 | 4932.632 N | 86．852W | 115 |  | 075 | 0 |  | 0 | 009 | 345 |
| CGS－B | 08 | 0567 | 1480 | 80 08 | 0812.984 N | 88．07 | 33 | 460 MB | 073 | 0 | F | 0 | NO30 | 412 |
| 6GS－8 | 13 | 0567 | $12 \% 8$ | \＆ 800 | 0009.247 N | 82．3954 | 68 | 400 Hg | 080 | 0 |  | 0 | 008＊ | 312 |
| cGs－B | 20 | 0567 | 234 | 4219 | 19.11 .653 N | 86．714 4 | 33 | 420 ME | 074 | 0 |  | 0 | N012＊ | 345 |
| cGs－8 | 23 | 0567 | 173 | 3450 | 5010.197 N | 84， 022 L | 119 | 430 M 8 | 078 | 0 |  | 0 | $008 *$ | 362 |
| cgspet | 23 | 0657 | 1330 | 30 \％ | \％6 12．930 ${ }^{\text {d }}$ | 67．800H | 11 | 420 MB | 074 | 0 |  | 0 | 012 | 34.5 |
| cGspde | 25 | 0667 | 2252 | 5212 | 1210.700 N | 86.000 W | 33 | 400 MB | 077 | 0 |  | 0 | 007 | 312 |
| CGSPDE | 30 | 0667 | 1142 | ¢2 33 | 33 11．000N | 86.600 d | 48 | 450 ME | 074 | 0 |  | 0 | 022 | 395 |
| caspde | 04 | 0767 | 0612 | 1257 | 5710.800 N | 86．4006 | 33 | 410 AB | 077 | 0 |  | 0 | 016 | 329 |
| CGSPDE | 04 | 0767 | 1329 | 29 O | $0 \leqslant 11.60004$ | 87．200的 | 33 | 420 MB | 074 | － |  | 0 | 010 | 345 |
| cgspoe | 04 | 0767 | 0739 | 3920 | 20 1．1．300N | 37．3004 | 38 | 400 MiB | 074 | ， |  | 0 | 016 | 312 |
| cgspde | 14 | 0767 | 1802 | 02 Ce | CE E3．500 | 88．800W | 147 | 460 NB | 073 | 0 |  | 0 | 014 | 412 |
| CGSPDE | 18 | 0867 | 1225 | 2618 | 1811.800 N | 35．9004 | 21 | 470 MB | 075 | 0 |  | 0 | 017 | 428 |
| CGSPDE | 27 | 0867 | 1308 | 0855 | 5312.300 N | 8a． 200 F | 183 | 520M8 | 075 | 0 |  | 0 | 060 | 511 |
| CGSPDE | 02 | 1067 | 1559 | 5943 | 4311.730 N | 86． 800 H | 39 | 47048 | 074 | 0 |  | 0 | 025 | 428 |
| GG SPDE | 03 | 1067 | 192 | 2239 | 3910.500 N | 86． 200 W | 33 | 450 MB | 077 | 0 |  | 0 | 019 | 395 |
| CGSPDE | 63 | 1067 | 1816 | 1603 | 0310.900 H | 85．9004 | 21 | 580MB | 078 | 0 |  | 0 | 104 | 611 |
| COSPDE | 04 | 1067 | 00 | 1212 | 1215.700 m | 88.600 H | 33 | 440 MB | 072 | 0 |  | 0 | 010 | 379 |
| cgspue | 04 | 1067 | 0602 | 02 is | Is 10.700 N | 86．000 ${ }^{\text {d }}$ | 33 | $530 \mathrm{M8}$ | 077 | － |  | 0 | 086 | 528 |
| cgspoe | 08 | 1067 | 1428 | 2807 | $07 \mathrm{Li.330N}$ | 86．0006 | 33 | $420 \mathrm{M8}$ | 074 | 0 |  | 0 | 009 | 345 |
| CGSPDE | 15 | 1067 | 0800 | 0050 | 5011.900 V | 86．000 | 262 | 620 \％ | 074 | 0 |  | 0 | 083 | 677 |
| cGspoe | 00 | 1167 | 1245 | －9 26 | 26.13 .500 N | 88．0006 | 33 | 430148 | 073 | c |  | 0 | 010 | 362 |
| cgspoe | 13 | 1167 | 1505 | 0546 | 4610.400 N | 85， 700 CH | 18 | 460 mb | 078 | 0 |  | 0 | 019 | 412 |
| CGSPDE | 06 | 1267 | 0253 | 5303 | OS 12．530N | 87．2004 | 87 | 530 M 8 | 074 | － |  | 0 | 057 | 528 |
| DEM 389 | $2^{4}$ | 568 |  |  | 12.30 | 86． 50 | 79 | 5.1 |  |  |  |  | ＊＊＊＊ | 5.1 |
| cospue | 04 | 0168 | 100 | 355 | 5512.100 N | 86.300 w | 5 | 4601 m B | 075 | 0 |  | 0 | 028 | 412 |
| CGSPDE | 25 | 0168 | 103 | 3756 | 5612.730 N | 86．8004 | 60 | 390m8 | 078 | 0 |  | 0 | 007 | 300 |
| ccspoz | 28 | 0168 | 084 | 4720 | 2012.600 N | 37．900 H | 75 | 440 MB | 074 | 0 |  | 0 | 022 | 379 |
| cgspde | 28 | 0168 | 1820 | 2049 | 69120100 N | 86．900w | 152 | 440 MB | 075 | 0 |  | 0 | 015 | 379 |
| CGSPDE | 01 | 0368 | 1534 | 3444 | 44.3107004 | 35.500 d | 190 | 480 MB | 075 | 0 |  | 0 | 033 | 445 |
| CGSPDE | 03 | 0368 | 084 | 4324 | 2410.000 N | 83．100 W | 16 | 41048 | 078 | 0 |  | 0 | 010 | 329 |
| CGSPDE | 14 | 0368 | 1009 | 0919 | $19: 2.000 \mathrm{~N}$ | 86． 800 H | 25 | \％50 5 ¢ 8 | 075 | － |  | 0 | 013 | 395 |
| CGSPDE | 24 | 0368 | 1713 | 1320 | 2012.530 N | 86． 500 H | 79 | 510 MB | 075 | 0 |  | 0 | 043 | 495 |
| cespde | 01 | 0468 | 0728 | 2828 | 2812.6000 | 98．500w | 33 | 440 FB | 076 | 0 |  | 0 | 013 | 379 |
| cgspot | 63 | 0468 | 0006 | 0600 | 0012.20 ON | 88.300 W | 33 | 430 mB | 076 | 0 |  | 0 | 011 | 362 |
| CCSPOE | 18 | 04 68 | 04.0 | 4038 | 3812.500 N | 88.6004 | 54 | 490mb | 076 | 0 |  | － | 019 | 462 |
| CGSPDE | 28 | 0.468 | 1003 | 0331 | $3111.800 N$ | 88.800 W | 39 | \％90MB | 076 | 0 |  | 0 | 039 | 462 |
| CGSPDE | 06 | 0568 | 2123 | 2311 | 1113.021 N | 87．734 4 | 56 | 460 M | 072 | 0 |  | 0 | 0024＊＊ | 412 |
| c．cspde | 11 | 0668 | 0552 | 5233 | 3313.942 N | 88．7614 | 199 | 530ヶ48 | 073 | 0 |  | 0 | 0066 | 528 |
| CGSPDE | 02 | 0768 | 1615 | 1548 | 4809.045 | B2． 934 d | 33 | 420 MB | 080 | 0 |  | 0 | NOOT＊ | 345 |
| CGSPDE | $0 \cdot 6$ | 0768 | 1515 | 1559 | 5910.464 N | 84．056 | 113 | 440 MB | 078 | 0 |  | 0 | 012 | 379 |
| CGSPDE | 67 | 0768 | 1949 | 4936 | 3610.678 N | 88.9394 | 134 | 450 mb | 072 | 0 |  | 0 | $017 *$ | 395 |
| CGSPDE | 14 | 0768 | $03 \leq 5$ | 8524 | 24.25 .237 N | 88.8434 |  | 450 N⿴囗 | 072 | 0 | F | 0 | 033 | 395 |



|  |  |  |  |  |  |  |  |  | A3－22 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CGS 54 | 20 | 07 | 70 | 04 | 58 | 05 | 10.366 N | 87．400w | 33 | 460 MB |  | 077 | 0 |  | 0 | NO 15 | 412 |
| CGS 53 | C5 | 08 | 70 | 13 | 22 | 05 | 09.841 N | 8403176 | 56 | 460 ME |  | 078 | 0 |  | 0 | 023 | 412 |
| CGS 54 | 07 | 08 | 70 | 13 | 03 | 14 | 12.325 N | 87．7914 | 59 | 450 mb |  | 074 | 0 |  | 0 | 016 | 395 |
| CGS 55 | 12 | 08 | 70 | 11 | 07 | 59 | 10.8674 | 87．229 | 33 | 450 ms |  | 077 | 0 |  | 0 | NOOS＊＊ | 395 |
| CGS 55 | 12 | 08 | 70 | 10 | 24． | 23 | 12.051 N | 86．539w | 33 | 560 MB |  | 075 | 55MS |  | 530PAS | N057 | 550 |
| CGS 55 | 12 | 08 | 70 | 09 | 24 | 11 | 12．085V | 66.5424 | 33 | 590 mb |  | 075 | 63 MS | $F$ | 600PAS | N077 | 630 |
| CGS 62 | 02 | 09 | 70 | 17 | 51 | 35 | 10.432 N | 86．015id | 33 | 430MB |  | 077 | 0 |  | 0 | NOO9＊＊ | 362 |
| EGS 62 | 06 | 09 | 70 | 20 | 4 | 49 | 12．783N | E8．595 ${ }^{\text {d }}$ | 75 | 450 MB |  | 076 | 0 | F | 0 | 017 | 395 |
| CGS 71 | 23 | 69 | 70 | 23 | 57 | 45 | 82．02 1 \＃ | 87．446W | 70 | 450 mm |  | 074 | 0 |  | 0 | 029 | 395 |
| CGS 67 | 29 | 09 | 70 | 04 | 42 | 46 | 11.453 N | 85．479 ${ }^{\text {d }}$ | 192 | 540 MB |  | 075 | 0 |  | 540 BRK | D132 | 540 |
| CGS 68 | 06 | 10 | 70 | 15 | 18 | 54 | 13.56 N | 98．312w | 192 | 4.60 H 8 |  | 073 | 0 |  | 0 | 0484 | 412 |
| vOS 75 | 03 | 12 | 70 | 08 | 39 | 12 | 11．0644N | 85．1124 | 100 | 460 mB |  | 074 | 0 |  | 0 | 0023 | 412 |
| NOS 80 | 25 | 12 | 70 | 05 | 38 | 12 | 12．785N | 87.920 w | 36 | 480 MB |  | 074 | 0 |  | 0 | 014＊ | 445 |
| DEH428 | 3 | 2 | 71 |  |  |  | 12.50 | 86.70 | N | D $v$ |  |  |  |  |  | ＊＊＊＊ | 581 |
| DEM 431 | 3 | 5 | 78 |  |  |  | 12.70 | 87．00 | N | D V |  |  |  |  |  | 婦为 | 58 L |
| NOS 9 | 21 | 01 | 71 | 17 | 13 | 48 | 1．1．714N | 87．794N | 33 | 480 ms |  | 074 | 0 | $F$ | 0 | NO1 4\％ | 445 |
| NOS 16 | 19 | 02 | \％ | 1.5 | 59 | 40 | 13.582 N | 82．795N | 176 | 520 ms | 3 | 073 | 0 | $F$ | 0 | D042 | 511 |
| NOS 21 | 25 | 02 | 71 | 04 | 15 | 41 | 12.159 N | 27． 48896 | 52 | 530m8 |  | 074 | 0 |  | 0 | 075 | 528 |
| NOS 3 C | 26 | 04 | 71 | 10 | 32 | 20 | 11.4222 N | 86．760N | 69 | 470 MB |  | 074 | 0 |  | 0 | 040 | 428 |
| NOS 31 | C1 | 05 | 71 | 84 | 32 | 12 | 13.25 N | 80．699W | 93 | 540ME | 5 | 073 | 0 | F | 0 | 053 | 545 |
| YOS 41 | 05 | 06 | 71 | 14 | 20 | 42 | 09．339N | 84．232 ${ }^{\text {d }}$ | 26 | 540 MB | 3 | 1078 | 51MS | $F$ | 0 | 082 | 510 |
| MOS 4\％ | 20 | 06 | 81 | 11 | 20 | 32 | 11． $102 N$ | 36．765 | 60 | 490 MB |  | 074 | 0 |  | 0 | 015＊ | 462 |
| NOS 41 | 11 | 06 | 71 | 11 | 51. | 40 | 12.648 N | 96．967 | 148 | 450 mg |  | 074 | 0 |  | 0 | 02緒 | 395 |
| NOS 45 | 1.6 | 06 | 78 | 06 | 18 | 56 | $11_{0} 72 \mathrm{NV}$ | 88.222 W | 33 | 450 MB |  | 076 | 0 |  | 0 | NO12＊ | 395 |
| VIS 45 | 18 | 06 | 71 | 13 | 36 | 01 | 14.678 N | \＆7．567W | 7 | 500 MB |  | 072 | 0 |  | 0 | 022 | 478 |
| ERL 60 | 05 | 08 | 72 | 22 | 58 | 08 | 09．6614 | 94．069W | 33 | 490 MB |  | 078 | 0 |  | 0 | NOL 9 | 462 |
| ERL 60 | 12 | 08 | 710 | 05 | 59 | 00 | 12.877 N | 87． 368 | 211 | 470 MB |  | 074 | 0 |  | 0 | 026 | 428 |
| ER L 77 | 24 | 08 | 71 | 08 | 09 | 07 | 11．599N | 860323\％ | 33 | 510ME |  | 074 | 42 mS |  | 0 | NO\＆9 | 420 |
| ERL 66 | 27 | 08 | 71 | 09 | 21 | 57 | 11.839 N | 28． 88 4 4， | 33 | 500MB |  | 076 | 38MS |  | 0 | NO4 1 | 380 |
| ERL 33 | 29 | 08 | 71 | 08 | 26 | 52 | 11.547 N | 36． 280 m | 33 | 490 Mg |  | 074 | 0 |  | 0 | NO 34 | 462 |
| ERL 71 | 13 | 09 | 71 | 15 | 33 | 27 | 09.973 N | 87.361 .18 | 33 | 440 MB |  | 077 | 0 |  | 0 | NOO7 | 379 |
| ERL 77 | 28 | 09 | 71 | 05 | 47 | 16 | 09．82IV | 86．267W | 33 | 500 MB |  | 077 | 0 |  | 0 | N036＊ | 478 |
| ERL 81 | 14 | 10 | 71 | 06 | 59 | 10 | 10.824 N | 86.268 W | 33 | 470 mB |  | 077 | 40 MS |  | 0 | NO2 ${ }^{*}$ | 400 |
| ERL 81 | 08 | P1 | $7 \pm$ | 04 | 26 | 10 | 120432N | Ea， 2654 | 68 | 490 mb |  | 076 | 0 |  | 0 | 031 | 462 |
| ERL 85 | 25 | 11 | 71 | 22 | 06 | 26 | 22．759N | 87．458w | 62 | 490 MB |  | 074 | 0 |  | 0 | 024 | 462 |
| ［RL 85 | 26 | 12 | 710 | 04 | 06 | 38 | 12．1．48N | 87，626 | 47 | 440 MB |  | 074 | 0 |  | 0 | 013 | 379 |
| DEM 438 | 1 | 12 | 31 |  |  |  | 12．63 | 96． 90 | N | 0 V |  |  |  |  |  | \＃＊＊ | 585 |
| ERL 1 | 03 | 01 | 72 | $0 \sim$ | 31 | 04 | 12．31 IN | 86．300 m | 33 | 41088 |  | 075 | 0 |  | 0 | NOP 9＊ | 329 |
| ERL 2 | 05 | 01 | 72 | 11 | 52 | 26 | 12.286 N | 86.236 m | 33 | 420 MB |  | 075 | 0 |  | 0 | NO 19＊ | 345 |
| ERL 8 | 16 | $0 \pm$ | 72 | 23 | 55 | 10 | 21．53 5N | 67．582t | 62 | 460 M ${ }^{\text {\％}}$ |  | 074 | 0 |  | 0 | 014 | 412 |
| ERL 9 | 30 | 01 | 72 | 22 | 25 | 03 | 11．002V | 86．750 W | 43 | 450 NB |  | 074 | 38MS |  | 0 | 017 | 380 |
| ER： 7 | 30 | 02 | 72 | 29 | 10 | 07 | 11.251 N | 86．773 | 48 | 460 mB |  | 074 | 44 MS |  | 0 | 027 | 440 |
| ERL S | c 4 | 02 | 72 | 01 | 07 | 43 | 11.213 Nd | ع6．891 ${ }^{\text {d }}$ | 52 | $480 \mathrm{M} \cdot \mathrm{B}$ |  | 074 | a |  | 0 | 019 | 445 |
| EKRL 10 | 05 | C 2 | 72 | 10 | 05 | 31 | 10.592 N | 86． 400 ly | 36 | 44048 |  | 077 | 0 |  | 0 | 008＊ | 379 |
| ERL 21 | 17 | 02 | 72 | 09 | 19 | C6 | 13.269 N | 88．691 ${ }^{\text {b }}$ | 80 | 470 MB | 5 | 073 | 0 | $F$ | 0 | 031 | 428 |
| ERL LS | 19 | 02 | 72 | 19 | 45 | 33 | $50.3884 \times$ | 86．085 d | 53 | 470 ME |  | 077 | 0 |  | 0 | NOS4＊ | 428 |
| ERL 11 | 25 | 02 | 72 | 03 | 43 | 47 | 10.137 N | 83.414 W | 88 | 480 MB |  | 078 | 0 |  | 0 | 019＊ | ${ }_{8} 12$ |
| ERL 14 | 04 | 03 | 72 | 22 | 04 | 23 | 12.933 N | 88．7436 | 64 | 470 MB | 4 | 076 | 0 | $F$ | 0 | 024 | 428 |
| ERL 16 | 05 | 03 | 72 | 21 | 47 | 26 | 11.971 N | c7．914 ${ }^{\text {d }}$ | 46 | 480 MB | 3 | 074 | 0 | $F$ | 0 | 020＊ | 412 |
| ER．L | 30 | 04 | 72 | 10 | 55 | 19 | 12．8964 | 88．468W | 77 | 440 MB | 3 | 076 | 0 | $F$ | 0 | 019 | 379 |
| ERL 4 C | 27 | 06 | 72 | 1 t | 45 | 32 | 1．2．182N | 86．588W | 104 | 460 AmP |  | 075 | 0 |  | 0 | 01 4＊ | 412 |
| ERL 45 | 28 | 07 | 72 | 13 | 53 | 40 | 83.651 N | c7．753w | 209 | 440 me |  | 072 | 0 |  | 0 | 016 | 379 |
| ERL 51 | 31 | 02 | 12 | 02 | 24 | 09 | 13.272 N | 88． 52.36 | 50 | 540 MB |  | 073 | 48 MS |  | 0 | 068 | 480 |
| ERL 58 | 26 | 09 | 72 | 03 | 20 | 16 | 12.211 N | 87．4R2W | 37 | 460 ma |  | 074 | 38 MS |  | 0 | 018 | 380 |
| ERL 61 | Cl | 10 | 32 | 06 | 00 | 51 | 11.015 N | 88．330W | 49 | 420 MB |  | 074 | 0 |  | 0 | 036\％ | 345 |
| ERL 65 | 02 | 11 | 72 | 18 | 24 | 45 | 21．71 1 ${ }^{\text {d }}$ | 87.9394 | 24 | 460 MB |  | 074 | 0 |  | 0 | 020＊ | 422 |
| ERI 66 | 19 | 11 | 72 | 04 | 35 | 24 | $12.973 N$ | 88．524W | 73 | 560 MB |  | 073 | 0 |  | 0 | 085 | 578 |
| ERL 71 | 12 | 12 | 72 | 12 | 51 | 04 | 11.403 N | 87．1516 | 27 | 440 MB |  | 074 | 0 |  | 0 | DO17年 | 375 |
| ERL 73 | 14. | 12 | 72 | 03 | 55 | 41. | 11．8588 | 86．574 ${ }^{\text {d }}$ | 1 cs | 460 MB |  | 074 | 0 |  | 0 | D019\％ | 412 |
| ERL 77 | 23 | 12 | 72 | 07 | 17 | 36 | 12.030 N | 96． 378 W | 5 | 500 MA |  | 075 | 0 |  | 0 | 602\％ | 478 |


|  |  | 12 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Ef 37 | 23 | 12 | 72 | 07 | 19 | 49 | 12.00 |  |  |  |
| ERL 7.4 | 25 | 12 | 72 | 00 | 26 | 28 | 15 |  | 34 | 460 ME |
| 457 | 13 | 4 | 73 |  |  |  |  |  |  | 6.7 |
| 12 | 15 | 02 | 73 |  |  |  | 11.534 | E6.473 | 33 | 510 |
| 13 | 23 | 02 | 73 | 19 | 36 | 48 | 09.84 5 | 83.49 | 33 | 470 m |
| 13 | 26 | 02 | 73 | 00 | 43 | 39 | 09 | 84.22 | 33 |  |
| 15 | 07 | 03 | 73 | 13 | 00 | 45 | 12.705 | . | 64 |  |
| 22 | 09 | 04 | 73 | 03 | 17 | 48 | 12.25 | 86.55 | 67 |  |
| 36 | 14 | 04 | 73 | 08 | 34 | Co | 10.679 | 84 | 33 |  |
| 36 | 14 | 04 | 73 | 08 | 54 | 29 | 10 |  | 33 |  |
| RL 36 | 14 | 04 | 73 | 09 | 19 | 09 | 10.260 | 5.015 | 33 |  |
| RL 30 | 07 | 05 | 73 | 11 | 54 | 36 | 12. | 87.949 | 33 |  |
| ERL 35 | 28 | 05 | 73 | 06 | 19 | 00 | 1. |  | 42 |  |
| ERL 42 | 05 | 07 | 73 | 08 | 08 | 07 | 11. | B7. 54 lW | 48 |  |
| RL 40 | 06 | 07 | 73 | 05 | 21 |  | 11.962 |  | 51 |  |
| L 4.1 | 07 | 07 | 73 | 07 | 07 |  | 41.842N |  |  |  |
| GS 52 | 14 | 07 | 73 | 07 | 55 | 08 | 11.637 N |  | 46 |  |
| 5 | 27 | 07 | 73 | 08 | 51 | 11 | 12.4 | 7 | 33 |  |
| 145 | 27 | 07 | 73 | 19 | 42 | 47 | 12.813 M | 86.67 | 199 |  |
| L 47 | 28 | 07 | 73 | 20 | 48 | 24 | 12.333 N | 87.084 | 79 |  |
| 47 | 04 | 08 | 73 | 00 | 44 | 42 | 09.838 N | 84 | 33 |  |
| 147 | C4 | 08 | 73 | 11 | 54 | 16 | 12.140 N |  | 33 |  |
| RL 49 |  |  |  |  |  |  |  |  |  |  |


|  | A3-23 |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 075 | 62mS | CO6 20PAS | 6099 | 620 |
|  | 075 | 0 | 0 | 6049 | 511 |
|  | 072 | 0 | 0 | 020 | 412 |
|  |  |  |  | *** | 6.7 |
|  | 074 | 50 MS | 0 | 0053 | 500 |
|  | 078 | 42 MS | 0 | N038 | 420 |
|  | 078 | 40 MS | F 0 | NO31 | 400 |
|  | 076 | 0 | 0 | 013* | 412 |
|  | 075 | 0 | 0 | 035 | 428 |
|  | 078 | 65MS | CDS 50PAS | NL1 $7 *$ | 650 |
|  | 078 | 0 | $\bigcirc$ | NO 34* | 445 |
|  | 078 | 0 | 0 | NOO6* | 362 |
|  | 074 | 40 MS | 0 | NO13 | 400 |
|  | 074 | 40 MS | 0 | $014{ }^{\text {1 }}$ | 400 |
|  | 074 | 0 | 0 | 015 | 362 |
|  | 074 | 0 | 0 | 023 | 445 |
|  | 074 | 0 | 0 | 015 | 362 |
|  | 074 | 44 MS | 0 | 024** | 440 |
|  | 074 | 0 | 0 | NO1 7* | 395 |
| 3 | 075 | 0 | F 0 | D111 | 528 |
|  | 074 | 0 | F 0 | 0087 | 545 |
|  | 073 | 54MS | F 52089 K | NO83 | 540 |
|  | 076 | 0 | 0 | NaO8* | 379 |
| 4 | 076 | 0 | F 0 | D033 | 495 |

## APPENDIX 4

COMPU'IER PROGRAM LISTING
$\qquad$


|  |  |
| :---: | :---: |
| c | prcgrab gener.mag Stanford university |
|  |  |
| c | this frogran replages the letters ear fhquake richter magnitudes |
| c | A,B,C,D,E (FROPG THE DAMES \& MCORE NICARAEUA EARTHQUAKE CATALOGI by a richter magnituoe obtalned through randem number generatlon. <br>  |
| c |  |
| ¢ |  |
| c | infut format <br>  |
| c |  |
|  |  |
| ¢ | col variable name variable descripticn |
|  | 1.- earthquake record card 1 caro per recerr (10a4) |
| 6 | 1-36 XMAG(1-9) COL $1 / 36$ READ IN A FORMAT |
| $c$ | 37-40 Xmag(10) Lepter ear phquake nagitiude |
| c | cliput |
|  |  |
| c | tata cutput is saved on disk, it contains the same information as |
| c |  |
|  | the input. but the letter hagnitude has been replaced by the |
| c | richter magnitude. |
| ${ }_{c}^{\text {c }}$ |  |
|  |  |
|  |  |
| c |  |

C 200 CINTINUE
RFTIPN
EMD
\$OATA





AT THE SAME DEPTH.
$* * * * * * * * * * * *$
INPUT FRQMAT
$* * * * * * * * * *$
cot variablename variable pescriotion


Y COOROINATE OF THE SAME POINT
SL.OPE OF THE LINE


$\begin{array}{lll}11-20 \\ 21-30 & \text { AL2 } 2 & \text { SLOPE OF THE LINE }\end{array}$
DUTPITT
******
THE OUPUT OISPLAYS THE IDENTIFICATION CF THE LINES ANO
THEIR THE COORDINATES DF THEIR INTERSECTIOM POIMT.



| C | ****************************************************************** |
| :---: | :---: |
| $\checkmark$ | PROGRAM LINE.LENGTH STANFORD UNIVERSITY |
| c | ***************************************************************** |
| c | IhIS Program computes the length of a segment of line between |
| C | TWO HORIZONTAL COORD INAYES. |
| c | ***************************************************************** |
| c | INPUT FORMAT |
| c | ************ |
| c |  |
| c | CGL Variable vame variable description |
| c |  |
| c | 1.- IDENTIFICATIDN 1 CARD (20A4) |
| c | 1-80 HEDI LINE IDENTIFICATION |
| C |  |
| c | 2.- LINE PARAMETERS 1 CARD (5FIC.C) |
| C | 1-10 XI X Coordinate of a point of the line |
| $\sigma$ | 11-20 YI Y COORDINATE OF THE SAME PCINT |
| c | 21-30 ALPH SLOPE OF THE LINE |
| c | 31-40 XS $\quad \times$ COORD OF ORIGIN CF SEGMENT |
| c | 41-50 YX X COORD OF END OF SEGMENT |
| C |  |
| c | OUTPUT |
| c | ****** |
| c | the output displays the live identification and paramenters as |
| c | as hell as the length of the segment. |
| c |  |
| $c$ | ***************************************************************** |
|  | DIMENSION HEDI(20) |
| $c$ | ***************************************************************** |
| $c$ |  |
| 100 | READ (5,1001, END=99) $\mathrm{HED1}$ |
| 1001 | FORMAT( 20A4) |
|  | READ 5,1000 ) $1, Y 1, A L P H, X S, X E$ |
| 1000 | FORMAT (8F10.0) |
|  |  |
|  | $Y E=A L P H *(X E-X 1)+\mathrm{Y} 1$ |
|  |  |
|  | WRITEI 6, 2000) MEDI |
| 2000 | FCRMAT ('00, 20 A4) |
|  | PRINT, 'DATA ', X1, Y1, ALPH |
|  | PRINT, 'ORIGIN ENO LENTEH ',XS,YS,XE,YE,XLEN |
|  | GL TO 100 |
| 99 | RETURN |
|  | END |
| \$0ATA |  |



 COEFFICIENTS ALPHA AND BE
TO TIME AND AREA OR LENGTH.

 111 QEAO (5, 1000, END $=99$ )RMMN, RMIC, RMPK, A, T, SKIPCD, SKIPDZ, HED
1000 FORMAT 5 F10.0,215,5A4)
 IFISKIPCO.EO.0) GO TT 200 NBIC=1

C 100 READ (5,1001, END $=104$ ) $\times$ (NBIC), YY(NBIC)
$\stackrel{\text { ロ }}{\stackrel{-}{4}}$
104 NBIC=NBIC-1
1001 FORMAT(2F10.
2002 FRITEIG;20021NBIC
*DOINDEPENDENT DEPENDENT.
150 HRI $150(6,2011) \times(I X), Y Y(I X)$
2011 FORMAT(: $2 F 11.21$
200 continue
COMPUTE HISTOGRAM
CAUTION FORMAT SET TO READ DATA FROM TAPE U599
NBRC $=0$
RML $W=10$.

## $12 \mathrm{NBRC}=\mathrm{NBRC+1}$

 THIS PROGRAM IS TO RE USEC FOR REGRESSIIN ANAIYSIS BETWEEN
ONE DEPENDENT VARIARLE AND ONE TNDEPENOENT VARIARLE. ONE DEPENDENT VARIARLE AND ONE INDEPENOENT VARIABLE.
THE IINFAR SCALE IS USED FDR THE IMDEPFNDEAT VAPIARLE IXI AND THE LN SCALE FOD THE DEPFNDENT VARIABLE IYI
BOTH VARIARLES ARE INPUT CN THF LINEAR SCAL

IF THE DEPENDENT VAPIARLE IS NOT DETERNINED, THE PPDGRAM WILL
COMPUTF IT AS II-CDFI USING A INCREMENT RMIC OF THE DEPENDENT VARIABLE IT RAN EITHED FIT ONE OR TWOLINES ON THE DATA WITH A BREAKING
POINT INPUT AS RMBK

IAPIYT FORMAT
****A********
1.-10ENTIFICATION CARD 1 CARD (5F10.0.215.5A4)

1-10 RMMN 21-30 DMAK

AREA
TIME
A AND T ARE USED TO NORMALIZE ALPHA
$=I$ BNTH X AND Y ARE INPUT
MINIMUM RM VALUE
RM INCREMENT TO BE USED TO COMPUTE COF
BREAK DFF MAGNITUNE
BREAK OFF MAGN ITUDE
IF IPMRK. EQ. O.I ONLY ONE LINE WILL BE FIT
$\begin{array}{ll}=1 & \text { BNTH X AND Y ARE INPUT } \\ & \text { RMMN, RMIS ARE INPUT AS ZEROS } \\ =0 \text { ONLY XIS INDUT IAS RMI, Y IS }\end{array}$
RMMN, RMIS ARE INPUY AS ZEROS $\quad$ ONLY XS INDUT IAS RMI, Y IS COMPUTED FROM COF
RMMN, RMIC ARE TO BE INPITT
$=0$ INTERVALS WITH NO EVENT WILL NOT BE
and
TITLE


> INDEPENDENT VARIARLE OEPENDENT VARIABLE

NDENT VARI ABLE
NBRC CAROS 150

INDEPENDENT VARTABLE 4.-END OF FILE CARD (ONLY IF RM IS INPUT) ONE CARO (50X, F3. 11
5I-53 RM VALUE GREATER THAN 9.
NOTE
IF RM IS INPUT, SEVERAL FILES CAN BE RUN AT ONE TIME BY QEPEATING
THE INPUT SEOUENCE DESCRIBED ABOVE. 4.-END OF FILE CARD (ONLY IF RM IS INPUT) ONE CARO (50X, F3. 11
5I-53 RM VALUE GREATER THAN 9.
NOTE
IF RM IS INPUT, SEVERAL FILES CAN BE RUN AT ONE TIME BY QEPEATING
THE INPUT SEOUENCE DESCRIBED ABOVE. 4.-end of file card (only if rm is indut) one card (50x, f3.11
51-53 rm value greater than 9.
note
If rm is input, Several files can be run at one time by oepeating
the indut Seouence oescriben above. outpat



READ ANO WRITE ATTENUATTCN CONSTANTS



SEISMIC SOURCES*************************************************** INPUT FORMAT
1.- IDENTIFICATION CARD 1 CARD 2044

1-80 HEDI TITLE
2. - ATTENUATION CONSTANTS

TTENUATION FORMULA OF THF TYOE



C RCAD(5,1040)HEDI


READC5,1001INL, NA, NT, NY
READ(5,1000) (T(T),I=1,NT)
WRITE( 6,2220 )(TR(I).I=1,NT) NY=N!Y+!
$\operatorname{READ}(5,1000)(Y G(I), I=2, N Y)$ WVITE 6,2230$)$
WRITE 6,2220$)(Y G T I), I=2, N Y)$

FORMATI' 'LOFIO.EIOD'
FORMAT("OTIME DERIOOS
FDRMAT('OACCELEPATIONS')



-1
8
-1
$\mathrm{O} O$
$N \sim N$
$N \sim N$
$\begin{array}{ll}00 \\ N & N \\ N & N \\ N & N \\ N\end{array}$
TFANL LE.O1 60 TO 610

[^1]
## Y11(1)=Y12(IL)



C ITERATION ON TME PERIODS
650 DO 370 IT=1; NT
WRITE $(6,225)$
WRITE $(6,3000)$ TIIT)
WRITE $(10,5020)$ T (IT)

ITERATION TN GRID
ITERATION IN THE Y
ITERATION ON GRID
ITERATINN IN THE YIRECTION
Y=YBEGIN
DO 385 IY $=1$, NYMAX
ITERATION IN THE $X$ DIRECTION
$X=X B E G I N$
$X=X B E G I$
DO 380 I $X=1, N X M A X$
WRITE $6,22221 X, Y$
ITERATION ON PGA
ITERATION ON
DO 360 II $=2, N Y$
YGII=YGIII)
$\begin{array}{ll}C & \text { ITERATION ON LINE SOURCES } \\ C\end{array}$


$$
\begin{aligned}
& \text { SUMxSUM +FF } \\
& \text { SUMIISUMI+FFI } \\
& \text { CONTINUE }
\end{aligned}
$$

51 C

 $R H=(01 S T+B 1) * * R H 22$
$E X C K=R H * G A M 22 *(Y G 11 B 1 * * D E(22) *(8.2831 D 0 * R I A * R I A) * T(I T)$ EXCK
IFIEXCK.LE.1.O-5) GO TO 850
$S U M D=0 . D 0$

SUMP $=0.00$
SUMP1 $=0.00$

$$
\begin{aligned}
& N R=R I A / D E L T \\
& D R=R A / N R \\
& D R 1=D P * \cdot 500
\end{aligned}
$$

ITEPATION ON THE NB OF SEGMENTS IN THE CIRCLE
202IR=1, NR $002021 R=1$, NR
$0 L 1=0 A B S 101 S T-D P .11$

OL2=DIST*DR1
 SUMP $=$ SUMP $+F F * 2 . D 0$

 $\operatorname{SUMP}=\operatorname{SUMP}+F F F 2 . n 0$

DR1 $1=0 P_{1+D Q}$
CONTINUE
Sump=sumpadp
$\operatorname{SUMP}=\operatorname{SUMD*DP}$
$\operatorname{SUMP1}=\operatorname{SUMP1*DR}$
$\operatorname{SUM} \operatorname{SUM}^{2}+\operatorname{SUMP}$
$\operatorname{SUM} 1=\operatorname{SUM} 1+\operatorname{SIMP1}$
IFIXBAF.LT.XLI) ALI=-ALI

IF（XRAR．LE．XLZ R ETURN
DUM $=A L 1$
$A L 1=-A L 2$
$A L 2=D U M$

## 

 $\mathrm{Str}=\times 11$
$\times 11=\times 12$
$\times 12=\mathrm{S} r \mathrm{P}$

THE EPICENTRAL DISTANCE IS NOT SMALLER THAN DLIL，DOINTS OF TERMI $=A I L * I B I L-Y)-X$
$T E R M 2=X * X+8 I L * B T L+Y *(Y-2 . D O * S I L)-R E C K * R E C K$ TERM3 $=$ AIL＊AIL＋1＊DO
TERM2 $=$ DSORT（TEPM1＊TERMI－TERM2＊TERM3）

COOROINATES OF THE POINTS OF INTERSECTION XI $1=(-$ TERM1 $1+$ TERM2 $) /$ TERM3
$\times 12=(-$ TERM1－TERM2 I／TERM3
$Y I 1=A 1 L * X 11+B I L$ $\mathrm{YIL=AIL*X11+BIL}$
YI2 $=A I L * X I 2+B I L$

oETERMINE LINE PARAMATERS

OELII＝RETA1（IL）／B2
RH711 $=0 E L .11 * B 3$
$N B S G=1$
$\times \times(1)=X L 1$
$Y Y(1)=Y L 1$ TFRECK．LE．DLILI GO TC 830

THE EPICENTRAL RISTANCE IS NOT SMALIER THAN DLIL，DOINTS OF
INTERSECTION WITH THE LINE ARE COMPUTED







A MONTF－CARL O PROCESS IS USED．CDF P（A．GT．AOI IS INPUT．
INPUT FORMAT
1．－GENERAL 1 card（315） 1 （N）＊2


AN ACC EQUAL OR LARGE THAN XINB＋2）．
MAXIMUM POSSIBLE ACC TO BE USED IN CASE inPUT CDF DDES NOT GO UP TD 100\％

THF PEMAINING DATA IS READ FROM DISK（20A4）

4．－CDF pla．gt．adi 8 values per card image
P（A．GT．X（NB＋2I）
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THE MOOIFIED MERCALLI INTESITY IN THE SIMULATION AND THE
CORQESDCNDING PERCENTAGE．

READI5，1000INB，IY，NBPT
$\mathrm{NB2}=\mathrm{NB}+4$
$\mathrm{NB} 1=\mathrm{NB}+1$
$\mathrm{X1}$
FORMAT1315）（x1（1），I $=4, N B 2,2)$
FORMAT BFID．0


| $\circ$ | $\circ$ |
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|  |  |
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THIS PROGRAM PLOTS THE EARTHOUAKF EPICENTSRS DN A GRID (MAP)
GIVEN THE LATITUDE AND LONGITUDE. DIFFERENT SYMBOLS ARE USED FOR THE DIFFERENT MAGNITUDES.
THE PLOT WILL RF ROTATED 9O DEGREES COURITERCLACWISE IF IT IS TOD MESSAGE WILL BE GENERATED AND THE PLDT ABORTED. INPUT FORMAT
************


THE BOTYOU LEFT COQNER: THE END AS THE NORTH FJR THE DATA TO BE READ IN CONS ISTENTLY.



 LDGICAL*1 HED(70)
 INTERCHANGE $X$ AND Y SCALES
110 WRITE $(6,21011$
2101 FORMAT OTHE PLOT WILL BE ROTATED BY 90 OEGREES ')
111 CALL MODESG(AMODES, MORTGAT,BIN $502^{\circ}, 151$
DO $500 \quad 1 P=1, N B P L$
$A M \cap D E S(45)=1$.
$\triangle M \cap D E S(45)=1$
$X M A X=X M A X 1$
GO TO 111
YMIN
$X$
YMIN
STOR = DELTAX
DELTAX=DELTAY
DELTAY=STOR
STOR $=X R A S$
$X R A S=Y R A S+3.5 * I N R A S$

DO $500 \quad 1 \mathrm{P}=1, \mathrm{NBPL}$
$\stackrel{N}{\sim}$

$Y M A X=Y M A X I$
$X M I N=X M I N 1$
$Y M I V=Y M I N I$
READ 10,1030 )NBRC, HED
1030 FDPMAT $155,70 A 11$

on To 130
100 CONTINUF
ON 140 I $X=1$, NERC
On 140 I
PEAD
On
CHECK SIGNS
IF $\quad$ XMAXXI-GT. XMTM1) GO TO 150
XMAX $=-X M A X 1$
XUIN $=-X M I N 1$
DO 160 I

C 150 XFMAX $=X$ MAX + DEI TAX $* 4.25 / .75$

YMA $=-Y M A X_{1}$
YMIN
Of $180 \quad X=1$, NBRC
$Y(1 \times 1=-Y(1 x)$
$Y F M A X=Y M A(1)$
$180 \quad Y$ YFMAX = YMAX + DELTAY


IFIAMODES(12).NE.AMODES(13)IWRTTE(E,2102)AMDDES(12), AMJDES(13)
2102 FOPMAT(IOTHE SCALES ARE NOT THF SAME:,2FIO.6)

DELTA2×1./(8.*(NDGX)
XMUL=4.
DETAI $=4 . *$ DELTA2
DFLTA $=3 . * D E L T A Z$

ล๊
XT=XFMAX-3./INDGGX
CALL VESSGIAMODES,XT,YT,16,". MAGNITUDE $4+\%$

Call vecsgiamodes, xt.yt.16.' + magnitude 5+1)
XTFXT +DELTAL
AMODES(45) 35
CALL VECSGIAMCOES,XT,YT,16, $X$ MAGNITUDE $6+1)$
AMCDE S $(45)=1.0$
CALL VESSGAMDDES, $X T, Y T, 16$, . MAGNITUDE $7+*)$


sdata
$\quad$ IFIIRM.LT.1) GO TO 300
GO TO $1230,240,250,260,270,2801, I R M$
$230 \quad 13=13+1$ $13=13+1$
$X X 3(I 3)=X(I X)$
$Y Y 3(I 3)=Y(I X)$
$X X 3(I 3)=X(I X)$
$Y Y 3(I 3)=Y(I X)$
$G 0 T 0300$
$I 4=I 4+1$
$\begin{array}{lllll}0 & O & 0 & O & 0 \\ N & \text { N } & \text { N } & \text { N } & \text { N }\end{array}$

 IFISKIP4.EQ.O.AND.14.GG.OICALI PONTG

## 

 AMCDES $(45)=.35$AMODES 184$)=40$.
 AMODES
$A M O D 1=2.0$
 AMCDES $(45)=.65$
AMODE $S(84)=40$. $A M C O E S(45)=65$
$A M O D E S(B 4)=40$.
 $X T=X M A X-.5 / I N O G X$

$\triangle M C H E M M N+n E L T A 1$
$Y T=Y M I N(45)=.5$
$A M D E S$



[^2]






CHECK SIGNS
F(XMAXGT.XMIN) GO TO 150
XAX=XMAX
MIM N -XMIN GO Tn 150
$145 I=1+N F$
$x F 1(T)=-x F 1(1)$
$145 \times F 2(1)=-X F 2(1)$
C 150 XFMAX $=X M A X+$ OELTAX*4.25/.75
MIN=XMIN-DELTAX TO 170


$Y F_{1}(1)=-Y F_{1}(1)$
$Y F_{2}(1)=-Y F_{2}(1)$

c $173 \begin{aligned} & \text { YFMAX } \\ & \text { YFMIN } \\ & \text { YMAX }\end{aligned}$
PRINT, DELTAX, DELTAY, XFMAX,YFMAX, DELTAX, DELTAY, XFMAX, YFMAX
XFMINI=-DELTAX XFMINI=-DELTAX
YFMINI $=-$ DELTAY

|  | ```PRINT, DELTAX,DELTAY, XFMAX,YFMAXT, DELTAX, DELTAY, XFMAX,YFMAX XFMINI=-DELTAX YFMIN1=-DELTAY``` |
| :---: | :---: |
| C |  |
|  | PRINT, 'RASOR, XRAS,YRAS',RASOR, XRAS, YRAS |
|  | CALL SURJEG(AMODES, XFMIN1, YFMIN1, XFMAXI, YFMAXI) |
|  | PRINT. SCALE', AMODESI 12), AMEDES(13) |
| C |  |
| c | CREATE COLINTOURS AND PLOT THEM |
|  | CALL CONTPG(AMODES, $A, N R, N C, D X, D Y, C M I N, D C, C M A X)$ |
| c |  |
|  | CALL PICTRCIAMOUES) |
| 600 | CONTINUF |
| $c$ |  |
|  | CALL EXITGYAMODES) |
|  | RETURN |
|  | ENO |
|  | SUBROUTINE READI $A A, H E D 2, N R O H, N C O L, N R O T)$ |
| $c$ |  |
| $c$ |  |
|  | DIMENSITN AAINROW, NCOLI |
|  | LOGICAL*1 MED2 (80) |
| C |  |
| C |  |
| C | THIS SUBROUTINE REAOS THE DATA TO RE INTERPOLATED |
|  | READ 10,1002 IHED2 |
| 1002 |  |
| C |  |
| - | IFINROT.EQ. 11 GO PO 110 |
| 0 |  |
| C | THE DATA IS STORED IN A TWO DIMENSIDNAL ARRAY, A IL, I) BEING AT |
| C | THE ORIGIN OF THE PLOT IBOTTOM LEFT CORNER: |
| C |  |
|  | 00100 IR = 1 , NRCW |
| 100 | REAO(10,1000) (AA(IR,IC),IC=1,NCOS) |
|  | GO TO 99 |
| $C$ THE PLOT HAS BEEN ROTATED BY OO DEGREES COUNTERCLOCKWISE |  |
| C | THE PLOT HAS BEEN ROTATED BY 90 DEGREES COUNTERCLOCKWISE, |
| C | THE ROWS AND COLUMNS ARE INVERTED IN THE CALL STATEMENT |
| 110 | CONTINUE |
|  | DO $200 \mathrm{I}=1$, NCOL |
|  | $1 \mathrm{C}=\mathrm{NCOL}+1-\mathrm{I}$ |
| 200 | READ ( 10,1000 ( $A$ A (IR,IC), IR $=1, N \mathrm{NCW}$ ) |
| 99 | CONTINUF |
| C 0000 |  |
|  | 00300 IR $=1$, NR.OW |
| 300 | WRITE (6, 1001) (AA (IR, TC), IC=1, MCCL) |
| 1001 | FORMAT ( ', 13F10.3) |
| 1000 | FORMAT (8F10.5) |
| C |  |
|  | RETIRN |
|  | END |
|  | SUBROUTINE LIMITS (A,NBVL, SKIPAC,CMIN, DC, CMAXI |
| C |  |
| C |  |
|  | DIMENSION A(1) |
|  | INTEGER SKIPAC |
| $c$ |  |
| C |  |
| C | SEARCH FOR LOW BOUND |



IFISKIPAC.NE. 11 GO TO 110
FINO INTENSITIES USING RICHTER GUTENBERG RELATIONSHID
D $9 Q$ IV $=1$ NAVL AIIV)=3.*(ALOGIO(AIIV)*1000.1+.51
CONTINUE LIMIT THE FAULTS TO THE SREA UNDEP CONS IDEQATION RETURN
Ead
SugRn!
 SURRUUTINF FRAMF (NE, XMIN, YMIN, XMAX,YMAX,XFI,YFI, XEZ,YF?)
 LIMIT THE FAULTS TO THE SREA UNDE CONS TOEAAT
DO 500 IF $=1$, NF
CHECK THE $x$ COOFDINATES OF THE FAMLT SIGA=
CHECK=XMIN
CHFCX FOR IOHER AND UPPER BORN
OD $100 X=1,2$
$X F=X P I I F I K I G N$
CHECK FOR INGER ANO UPDER JORN
OD $100 \quad X=1,2$
$X F=X F B I I F I G S I G N$
CHECK EOS CNIGIN ANO END MF SEGMENT
OO $200 \quad 1=1 . ?$
 BET=YFIIIFI-ASL*XFII!F)
IF(1.50.? GO TO 300

CHANGE COMPDINARES
XFIIFI=SIGNACHECK
YFI(IFI=ASI*XFIIIFIARET
$c$
$c$
$c$
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$c$

$$
\begin{aligned}
& \text { DFFSET }=\text { DC } / 1000 . \\
& \text { OVE FOR EACH CONTOUR } \\
& \text { DO } 18 \text { IEVEI }=1 .
\end{aligned}
$$

$$
\begin{gathered}
7021 \\
9021 \\
7021
\end{gathered}
$$

CMIN IS THE LEAST CIONTOUP VAIUF.
חr. IS THE CONTOUR InTEQVAl.
 ICOL $\quad$ (CHP $(+N R+1)$

## $\triangle(C H D I) \quad A(C H P I+N R)$

USED


$$
\begin{gathered}
\text { OO } 18 \text { IEVEL }=1 \text {. NCNTR }
\end{gathered}
$$

$$
\begin{aligned}
& 095 \text { S }=1 \text {, NTRNG } \\
& 5 \text { STATUS } 11=\text { EMOTY } \\
& \text { IPEN }=0
\end{aligned}
$$

$$
\begin{aligned}
& C \\
& C
\end{aligned} \text { OVCE FOR EACH COLUMN OF ENCLOSED GRIDS }
$$

uo uu

$P B=A(C H P I+N R+1)$
$O C=A(C H D I+N R+1)$
$P D=A(C H P T+N R)$


[^3] IF (AMODES(15) AT, AMODES(22)
PRINT, 'VECTOF AS IT IS PLOTTED,
WQITE(6,1000)(A(1),i=1,NVL)
1000 FRPMAT(:, $12 F 10.31$
MANY CONTOURS
NCNTQ $=(C M A X-C M I N) / D C+1$.

ScE TF THE ERROR RCNOIYION IS TON HIGH
IF (AMODES(15). GT. AMODES(22) QETURN

## APPENDIX 5

NEWMARK AND HALL PAPER
(Taken from reference 52)
by
N. M. Newmark and W. J. Hall

Urbana, Illinois

## I. Introduction

When a building or other structure is subjected to earthquake motion, its base or support moves with the ground. Since this motion is relatively rapid, it causes stresses and deformations throughout the structure. If we neglect temporarily the interaction between the base of the structure and its foundation, when the structure is quite rigid, its motion is nearly the same as that of the ground and the dynamic forces acting on it are very nearly equal to those associated with the ground accelerations applied to the structure as a rigid body. If the structure is quite flexible, large relative motions or strains can be induced in the structure because of the differential movements between the supports and the masses of the structure. In order to survive the earthquake motions the structure must be either strong enough or ductile enough to resist the forces generated by these deformations; the combination of the required strength and ductility is a function of the stiffness or flexibility of the structure.

Seismic effects on a structure, component or element, depend not only on the earthquake motion but also on the properties of the structure, component or element itself. Among these properties, the most important are the energy absorption within it or at interfaces between the item under consideration and its support, either due to damping or inetastic behavior, its period of vibration, and its strength or resistance.

It is the purpose of this paper to describe the general nature of the principles upon which earthquake resistant design is based, and to consider the development of design procedures for the design of structures, facilities or components.

Examples of structures that did not have sufficient strength and ductility to resist the earthquakes to which they were subjected are well known. Failures occurred in the columns and frames of buildings in caracas. for example, when inadequate strength and energy absorbing capacity were available for the earthquake of 1967. Other failures in earthquakes are clearly due to lack of adequate support details, or lack of adequate continuity between individual elements.

Emphasis is placed herein on design as contrasted with analysis, and essentially on preliminary design or the selection of the general outine, type of framing, and first estimate of requirements. This choice of emphasis is made because methods suitable for such purposes generally can assure adequate performance and serve as a check on designs made by more sophisticated methods.

The general concepts presented in this paper have been adapted from those given in References [1], [2], [3], and [4].

The design of a structure, as either a complete system in itself, or as part of the system of which the structure is only a component, can be a highly complex matter involving a number of input data of various types and a host of special requirements. Once the structure has been dimensioned, that is g laid out in plan and the size and strength of its various elements. selected, then the analysis of the structure for given conditions of loading
and foundation motion can be made by relatively well understood methods, even though the analysis can be a tedious and lengthy one for a complex system. However, unless the designer uses a so-called "direct design"procedure, he is faced with a problem of the preliminary selection of the structural layout, framing, element strength, and the like, before he has a structure which he can analyze. Even with direct design procedures, for important structures he will want to have some handy approximation that can be used for his preliminary studies.

The steps which the designer must take are generally as follows:
(1) Select the earthquake hazard.
(2) Select the safety factor, or the allowable limits of deformation, or the allowable probability of damage or failure. This may depend on step (3).
(3) Select the type or layout of the structure, and estimate its dynamic (and static) parameters. These include a) dynamic resistance, b) natural frequency or period of vibration. c) damping or energy absorption, d) ductility that can be counted on before failure. These may be assigned in a direct-design procedure, or are subject to successive revision in more traditional procedures.
(4) Verify the adequacy of the structure selected, and make any necessary changes in strength or other parameters, or in the complete layout or plan.
(5) Repeat steps (3) and (4) until a satisfactory design is achieved.
(6) Hake a more accurate analysis of the final design, and make further changes that may be necessary. If these are not minor, steps (3) to (6) may need repeating. In some cases revisions in steps (1) and (2) may be desirable. In other cases an upper bound direct procedure may be used involving essentially only steps (1), (2), and (3). Most so-called "static design codes" are intended to be of this type.

## II. Earthquake Hazard

Earthquakes are relatively rare occurrences, but in many regions of the worid one can count on a high probability of at least a small earthquake occurring once in the lifetime of a building. However, the stronger or more intense the earthquake the smaller is the probability of its occurrence. An earthquake that has a relatively high probability of occurrence is appropriately considered as a loading for which the design must provide in such a way that the cost of the minor repairs required is not excessive. Major strengthening of a structure to resist intense forces is expensive, and the cost of such design provisions must be weighed against the possible cost of repairs in order to design whether the additional design strength or ductility is economically justified.

It is generally agreed that structural collapse of such a nature that it might endanger a great many lives should be prevented by the design, even for the maximum credible earthquake. But it would be unreasonable and uneconomical to provide for resistance to an extreme earthquake with the same factor of safety or margin of safety that one normally uses. The selection of the factor of safety for the maximum credible earthquake is in part dependent on the nature and importance of the structure, and on the consequences should the structure fail.

Unfortunately the earthquake hazard for which designs should be made is
subject to a high degree of uncertainty. In only a few areas of the country are there relatively long periods of observation of strong earthquake motions. By correlating the available strong motion records with the more common records available from the sensitive recording instruments used by seismologists, and by use of qualitative reports of the effects of earthquakes where motion records are not available, some measure can be obtained of the maximum intensities which have occurred in various geological regions, and predictions can be made of those which might occur in the future. In other regions of the country, where records are scarcer, estimates of a similar nature can be inferred but are much more uncertain.

However, the maximum historical earthquake determined by such a procedure is not a proper measure of the possible intensity of an earthquake which might occur in the future nor of the earthquake for which the design should provide. At some sites, maximum or extreme earthquakes might never have occurred in the past; it is almost certain that they did not occur within the period of recorded history.

In order to specify adequately the earthquake intensity for either the historical or the extreme earthquake, one must do more than determine the possible or probable acceleration of the ground. The character of the earthquake motions must also be described in a way that is representative of the geologic conditions, taking into account the local soil conditions including overburden depths and characteristics, presence of water, depth to basement rock, and the like. A better measure of the free-field earthquake motions is a description which includes not only the maximum ground acceleration, but also the maximum ground velocity and the maximum ground displacement, with some measure of the number of pulses or the duration of the strong motions that should be considered. All of these quantities are dependent on the geologic and soil characteristics, and are in part dependent on the soil-structure interaction of the structure supported on the soil or rock.

Earthquakes in different parts of the world on different types of foundations and rock or soil strata have greatly different characteristics. The Niigata Earthquake of 1964 was characterized by the phenomenon of liquefaction of the soil and foundation failures causing tilt and overturning of a number of buildings that otherwise would not have been badly damaged. The earthquakes in Mexico city are affected by the natural frequency of the huge bowl of soft jellylike soil which underlies most of the central part of the city, and which emphasizes and amplifies motions ir the range of periods of vibration of 2 to 2.5 sec. and diminishes those of very low period, of less than 0.5 sec.

The low buildings, the old churches and the cathedral in Mexico, many of which have been in existence several hundred years during which time Mexico has been subjected to serious shaking from earthquakes, generally have not been severely damaged by earthquakes, but modern tall buildings were seriously damaged, especially in the earthquake of 1957. Nevertheless, one building, construction of which was completed during the early $1950^{\prime}$ s, the Latiro Americana Tower, survived this earthquake and, subsequently, the several slightly less intense earthquakes of the past decade with no damage, not even cracking of window panes. This is due to the fact that the expected nature of the earthquake motions was taken into account in its design. The building is of interest because it was the first building which was designed in accordance with modern analytical methods that was actually subjected to an earthquake approaching the intensity of the earthquake for which it was designed.

With the increased knowledge of the characteristics of earthquakes from the records obtained of strong motions in earthquakes in various parts of the world, we now have the basis for a much more detailed description of the type and intensity of earthquake motions that should be considered for design of structures of various types in various regions, taking into account the

## III. General Design Concepts

## General Principles

The designer's freedom of choice in selecting methods of resisting earthquake motions is restricted by the necessity that he comply with the architectural form selected for the building. If the form follows the function, the constraints are generally minimal. However, it is not necessarily true that an efficient earthquake resisting capability can be put into any arbitrary form of envelope for the structure. The designer must, therefore, have latitude in his selection of the resisting elements of the structure. He may choose a flexural framework; or a structure having resistance primarily in the outer walls as a monocoque assembly; or a structure strengthened by shear walls or by bracing; or a structure with a resisting core from which the lower parts of the building are hung; or various modifications and combinations of these. The methods of achieving strength and ductility in these various forms are necessarily different and the design criteria have to take this into account.

The permissibie level of response of a structure, element or component, must be associated with a loading criteria. The response criteria should properly be dependent on the type of structure, the relative cost of repairs for minor damage, and the hazard in terms of possible loss of life should the item fail or reach extreme deformation limits. The seismic resistance of an element is a function primarily of its yield strength, its natural frequency of vibration, its damping and energy absorption in the elastic range, and its ductility and energy absorption capacity in the range before unacceptable damage occurs.

## Dynamic Resistance

Detailed descriptions of the response of simple elastic systems, or more complex structure and elements, subjected to dynamic loading and especially to seismic loading, are given in References [2], [3], and [4]. In general, it can be shown that the response of a simple damped oscillator to a dynamic motion of its base can be represented graphically in a simple fashion by a logarithmic plot as shown in Figure 1. In this figure, there are shown on the one plot, using four logarithmic scales, the following three quantities:

```
D = Maximum relative displacement between the mass of the oscillator
        and its base
V = Maximum pseudo relative velocity = \omegaD
A = Maximum pseudo acceleration of the mass of the oscillator = = '}\omega
```

In these relations, $w$ is the circular natural frequency of the oscillator.
The effective maximum ground motions for the earthquake disturbance for which Fig. 1 is drawn are maximum ground displacement $d_{m}=10$ in., maximum ground velocity $v_{m}=15 \mathrm{in}$. per sec., maximum ground acceleration $a_{m}=0.3 \mathrm{~g}$, where $g$ is the acceleration of gravity. The curve shown is a smooth curve rather than the actual jagged curve that one obtains from a precise calculation. The symbols 1,2 and 3 on the curve represent oscillators, item 7 having a frequency of 20 cps , item 2 of 2.5 cps , and item 3 of 0.25 cps . It can be seen that for item 1 the maximum relative displacement is extremely small, but for item 3 it is quite large. On the other hand, the pseudo acceleration for item 3 is relatively small compared with that for item 2 . The pseudo relative velocities for items 2 and 3 are substantially larger


FIG. I RESPONSE SPECTRUM FOR TYPICAL EARTHQUAKE
than that for item 1.
The advantage of using the tripartite logarithmic plot, with frequency plotted also logarithmically, is that one curve can be drawn to represent the three quantities $D, V$ and $A$. The pseudo relative velocity is nearly the same as the maximum relative velocity for higher frequencies, but differs substantially for very low frequencies. It is, however, a measure of the energy absorbed in the spring. The maximum energy in the spring, neglecting that involved in the damper of the oscillator, is $H V^{2} / 2$, where $M$ is the mass of the oscillator.

The pseudo acceleration is practically the same as the maximum acceleration, and the quantity $M A$ is precisely the maximum force in the spring. Therefore, the pseudo acceleration is exactly the same as the maximum acceleration when there is no damping.

In the discussion and figures which follow, the terms "velocity" will be cused for $V$ and "acceleration" for $A$ without the explanatory words maximum, pseudo, relative or absolute.

There are many strong motion earthquake records available. One that has been used for a number of years is that for the el centro earthquake of May 18, 1940. The response spectra computed for the earthquake for several different amounts of damping are shown in figure 2. The oscillatory nature of the response spectra, especially for low amounts of damping, is typical of the nature of response spectra for earthquake motions in general. A replot of fig. 2 is given in fig. 3 in a dimensionless form where the scales are given in terms of the maximum ground motion components. In this figure, the ground displacement is given by the symbol $y$, and the subscript m designates a maximum value. Dots over the $y$ indicate differentiation with respect to time.

It can be seen from Fig. 3 that for relatively low frequencies, below something of the order of about 0.05 cps , the maximum displacement response D is practically equal to the maximum ground displacement. For intermediate frequencies, however, greater than about 0.1 cps, up to about 0.3 cps , there is an amplified displacement response, with amplification factors running up to about three or more for low values of the damping factor $B$.

For high frequencies, over about 20 to 30 cps or so, the maximum acceleration is practically equal to the maximum ground acceleration. However, for frequencies below about 6 cps, ranging down to about 2 cps, there is nearly a constant amplification of acceleration, with the higher amplification corresponding to the lower values of damping. In the intermediate range between about 0.3 to 2 cps , there is nearly a constant velocity response, with an amplification over the maximum ground velocity. The amplifications also are greater for the smaller values of the damping factor.

The results shown in Fig. 3 are typical for other inputs, either for other earthquake motions or for simple types of dynamic motion in general. The data from which Fig. 3 was drawn, as well as other similar figures, are taken from Reference [2].

## Natural Frequency

The dynamic response of a structure is a function, among other things, of its natural frequencies of vibration in its various modes. Natural frequencies can be computed from the mass and stiffness distributions of the structure but such calculations involve an idealization of the structure for the purpose of the analysis. The influence of nonstructural components on natural frequencies can be of particularimportance. Also the natural frequencies may be affected to a large degree by the foundation-structure


FIG. 2 RESPONSE SPECTRA, EL CENTRO EARTHQUAKE, MAY 18, 1940, NORTH-SOUTH DIRECTION

interaction.
Design specifications which involve natural frequencies have the disadvantage that the structure must be designed, at least in a preliminary way, before the frequencies can be determined, or else the frequencies must be estimated from factors involving judgment and overall dimensions. Hence, such methods may involve relatively large errors in the response or else the method of design must be one of continuing approximations and revisions.

## Damping

Energy absorption in a structure arises in various ways including damping or energy absorption of various types within the structure itself, friction or viscous damping, or other types of damping in the structure as well as in the parts of the structure interfering with each other or moving against one another. These can all be generally approximated by use of a damping coefficient. The damping is a function of the intensity of motion and of the stress levels induced within the structural components, and it is highly dependent on the makeup of the structure and the energy absorption mechanisms within it and at its interfaces with the foundation or with other structures. The importance of damping is indicated by the fact that the dynamic response of a structure in an earthquake may be affected to as great a degree by damping as by almost any other parameter. This is especially true in those instances when long sustained nearly harmonic motions are involved. It is because of this reason that the greatest difficulties are found with design specifications other than of the performance type in which the design forces do not properly reflect the differences in damping associated with different materials, different types of framing, and different levels of allowable deformation and stress.

## Inelastic Behavior and Ductility

Let us now consider the situation in which the simple oscillator has a spring which can deform inelastically during the response. The simple resistance-displacement relationship for the spring is shown by the light line in Fig. 4, where the yield point is indicated, with a curved relationship showing a rise to a maximum resistance and then a decay to a point of maximum useful limit or fallure at a displacement um. An equivalent elasto-plastic resistance curve is shown by the heavy line in the figure, rising on a straight line to a point where the yield displacement is $u_{y}$ and the resistance $r_{y}$, and then extending without appreciable increase in resistance to the maximum displacement $u_{m}$. The effective resistance curve is drawn so as to have the same area between the origin and uy as the actual curve, and again the same area to the maximum displacement point. The ductility factor $\mu$ is defined as the ratio between the maximum permissible or useful displacement to the yield displacement, for the effective curve.

It is convenient to use an elasto-plastic resistance-displacement relation because one can draw response spectra for such a relation in generally the same way as the spectra were drawn for elastic conditions in Fig. 2 and 3 . In Fig. 5 there are shown acceleration spectra for elastoplastic systems having 2 of critical damping for the El Centro 1940 earthquake. Here, the symbol $D_{y}$ represents the elastic component of the response displacement, but is not the total displacement. Hence, the curves also give the elastic component of maximum displacement as well as the maximumacceleration, A, but they do not give the proper value of maximum velocity. This is designated by the use of the symbol $V^{\prime}$ for the pseudo velocity drawn in the figure. The figure is drawn for ductility factors ranging from to 10 . It is typical of other acceleration spectra for elasto-plastic systems, as indicated by the acceleration spectra shown in Fig. 6 far the step displacement pulse sketched in the figure.


FIG. 4 RESISTANCE - DISPLACEMENT RELATIONSHIP


Figure 6 is drawn for a step displacement pulse corresponding to the two triangular pulses of acceleration shown, where the total length of time required to reach the maximum ground or base displacement is 1 second. The frequency scale shown in Fig. 6 will be changed for any other length of time, t, to reach the maximum displacement by dividing the frequencies $f$ by $t$. In other words, for a step displacement pulse that takes 0.2 sec., the abscissa for a frequency of 1 cps would be changed to 5 cps , and that for 3 cps in the figure would be changed to 15 cps , etc. The general nature of the similarity between Figs. 5 and 6 is important.

One can also draw a response spectrum for total displacement, as shown in Fig. 7. This is drawn for the same conditions as Fig. 5, and is obtained from Fig. 5 by multiplying each curve's ordinates by the value of ductility factor $\mu$ shown on that curve. It can be seen that the maximum total displacement is virtually the same for all ductility factors, actually perhaps decreasing even slightly for the larger ductility factors in the low frequency region, for frequencies below about 2 cps . Moreover, it appears from Fig. 5 that the maximum acceleration is very nearly the same for frequencies greater than about 20 to 30 cps for all ductility factors. In between, there is a transition. These remarks are applicable to the spectra for other earthquakes also. One can generalize about them in the following way for general nonlinear relations between resistance and displacement, for single degree of freedom structures.

For low frequencies, corresponding to something of the order of about 0.3 cps as an upper limit, displacements are preserved. As a matter of fact, the inelastic systems have perhaps even a smaller displacement than elastic systems. For frequencies between about 0.3 to about 2 cps , the displacements are very nearly the same for all ductility factors. For frequencies between about 2 up to about 6 cps , the best relationship appears to be to equate the energy in the various curves, or to say that energy is preserved, with a corresponding relationship between defiections and accelerations or forces. There is a transition region between 6 and 20 to 30 cps , depending on the damping ratio. Above 20 to 30 cps , the force or acceleration is nearly the same for all ductility ratios.

## Structure-Foundation Interaction

Earthquake motions are transmitted through the ground to the foundation of a structure and then to the structure itself. The interaction between the foundation components of the structure and the earth upon which it rests are of particular importance in defining the nature of the forces and motions transmitted to the structure. Energy absorption can take place at the interfaces between the structure and the foundation, and between the foundation and the supporting medium. Under certain conditions amplifications of motion may even occur. The interaction between the foundation medium and the foundation structure can be particularly complicated when the building is set into the soil or rock rather than resting upon it.

Design specifications either of the cookbook type, the intermediate type, or the type solely concerned with environmental and performance criteria fall short of their requirements if they do not consider the interaction between the structure and its supports, and especially the type of supports, whether it is pile or caisson foundations, isolated footings, or a mat, or some combination of these.

## Nonstructural Components

In buildings, particularly, it is necessary to make a distinction between those components which are essential parts of the structure in its resistance to loads and deformations, and nonstructural components which are those parts needed to perform the proper function of the structure but which

Undomped Nafural Frequency, $f$, cps
FIG. 7 TOTAL OISPLACEMENT SPECTRA, ELASTOPLASTIC SYSTEMS, TWO PERCENT CRITICAL DAMPING,
EL CENTRO 1940 EARTHQUAKE
are not added primarily for resistance to lateral forces. Partitions in a building may be structural or nonstructural depending upon whether they are designed to act as part of the load-carrying framing. However, whatever the designer's intent may be; all the elements of the structure, whether functional or otherwise, have an effect on the behavior of the building under dynamic excitation, and must be considered in terms of dynamic response, strength, and the damage which may be caused by exceeding allowable stress or deformation limits. Even nonfunctional ornamentation on a building that can be dislodged because of lateral motion can cause hazard to life as well as property.

## IV. Design Procedures

## General Approach

- The designer has considerable freedom of choice, in general, as to the type of resisting structure he will use in the design. He may choose a flexible, energy-absorbing structure which can comply with the ground motion readily, or he can use a rigid structure to limit the relative deformation within the structure itself. In one case the strains in the structure are determined primarily by the maximum transient ground displacement or velocity, and in the other they are determined primarily by the maximum transient ground acceleration.

If the structure is in an intermediate range of stiffness, then its energy absorbing capacity is of the greatest importance, which involves both its strength and ductility in some balanced manner. Under these conditions, one may reduce the strength and increase the ductility, or increase the strength and reduce the ductility, in both cases arriving at a satisfactory design. Although the designer must be careful in the determination of these balances, and must look into the strength and ductility of elements or components as well as those of the completed assemblage, he can make up for deficiency in one by an overdesign in the other, in many instances. Constraining the designer to use always highly ductile elements may be unreasonably restrictive since it appears possible to design a structure with as much margin to resist failure by making it less ductile but stronger, in an appropriate fashion. It appears unwise to establish design criteria solely on preconceived notions as to either strength or ductility without considering the combination of both of these that is required for adequate performance.

Theoretically and to a considerable extent practically, it is possible to use any material in almost any fashion one chooses to use it, by providing the proper combination of strength and ductility associated with the particular structural configuration and dimensions, thereby to insure that the completed structure will be able to perform adequately under the appropriate loading or motion environmental conditions.

It has already been noted that in many structures it is desirable, and in fact quite proper and reasonable, for the structure to go well into the inelastic range of behavior, especially for the maximum or extreme environmental seismic conditions. Different types of framing and different materials pose a variety of problems for an adequate specification of performance involving deformations and stresses beyond yield. This has been taken into account in existing codes in various ways, usually by specifying the relative intensity of loading to be considered for different types of framing. Each material must be studied from the point of view of its particular characteristics of strength and ductility, when fabricated into structural members or elements, or when connected together to form a structure. The performance criteria must be prepared in such a way as to avoid unusual handicaps to any one type of framing or material, or to give unusual advantages to any other type.

## Selection of Paramerers

In the light of the preceding discussion, we can now develop a basis for design of structures, elements or components, where these are subjected directly to the ground or base motion for which we have maximum values of displacement, velocity and acceleration. We first proceed with selection of values of damping. Table $l$ is reproduced with some changes from References [5] and [6], and gives the percentage of critical damping for various types and conditions of structures or elements, as a function of stress level. It represents the best information available at the present time, but certainly involves a great deal of judgment and interpretation.

The damping in structural elements and components and in supports and foundations of the equipment is a function of the intensity of motion and of the stress levels introduced within the structural component or structure, as well as being highly dependent on the makeup of the structure and the energy absorption mechanisms within it. For example, a structure with riveted or bolted joints that can undergo relative motion during deformation will absorb a great deal of energy in friction in these joints. A reinforced concrete beam that is cracked, where the elements on the two sides of the crack can move relative to one another with the absorption of energy at the faying surface, will also absorb considerable energy. On the other hand, a homogeneous solid structure or a welded steel structure has relatively 5 mall amounts of lost energy because of play in the joints, and a concrete beam before cracking has a relatively small amount of energy losses except those within the material itself. Hence, the degrea of damping depends on the framing and makeup of the structure or elements, and on the material used and the stress level within the material for the degree of excitation which it experiences in the shaking motion. For low stress levels and for homogeneous structures, steel or reinforced concrete below cracking levels, the damping may be no greater than in the range of one-half to one percent. For stresses at the level of working stresses or at about half the level of yield point values, the damping may range from about 2 percent for welded steel structures, for well reinforced concrete structures with only small amounts of cracking or for prestressed concrete structures, to 3 percent to 5 percent for ordinary reinforced concrete structures with considerable cracking, and possibly above 5 percent for riveted or bolted connections, or for wood structures with nailed joints and the like. At or near yield point values of stress, the damping may be in the range of about 5 percent for steel structures and prestressed concrete structures that have not completely lost their prestress, ranging to 7 to 10 percent for ordinary reinforced concrete, and as high as 10 to 15 percent for structures with play in the joints, or for masonry structures.

The fundamental frequency of vibration, or its reciprocal, the fundamental period, is best estimated by a simple calculation by use of standard methods of analysis such as are described in Reference [3]. For buildings simple rules, also given in [3], are often used to approximate the fundamental frequency, but are generally not reliable for unusual types of framing or for extremely heavy or extremely light construction.

The ductility factors for various types of construction are more difficult to characterize. They depend on the use of the building, the hazard involved in its fallure, the material used, and the framing or layout of the structure, and above all on the method of construction and the details of fabrication of joints and connections. A discussion of these topics is given in Reference [3] also.

## Design Spectrum - Elastic

In either analysis or design for earthquake resistance it is convenient to use the concept of the response spectrum. A response spectrum developed to give design coefficients is called a "Design spectrum".

```
Type and Condition of
        Structure
a. Vital piping
    0.5 to 1.0
Working stress, no
more than about 1/2
yield point
At or just below yield
pointa. Vital piping2
```

b. Welded steel, prestressed concrete (without complete loss in prestress) ..... 5
c. Prestressed concrete with no prestress left ..... 7
d. Reinforced concrete ..... 7 to 10
e. Bolted and/or riveted steel, wood structures, with bolted joints ..... 10 to 15
f. Wood structures with nailed joints ..... 15 to 20

In general, for any given area or site, estimates might be made of the maximum ground acceleration, maximum ground velocity, and maximum ground displacement. The lines representing these values can be drawn on the tripartite logarithmic chart of which Fig. 8 is an example. The lines showing the ground motion maxima in fig. 8 are drawn for a maximum ground acceleration of 1.0 g , velocity of $48 \mathrm{in} / \mathrm{sec}$, and displacement of 36 in . These data represent motions more intense than those generally considered for any postulated design earthquake hazard. They are, however, approximately in correct proportion for a number of areas of the world, where earthquakes occur either on firm ground, soft rock, or competent sediments of various kinds. For relatively soft sediments, the velocities and displacements might require increases above the values corresponding to the given acceleration as scaled from Fig. 8. However, it is not likely that maximum ground velocities in excess of 4 to 5 ft per second are obtainable under any circumstances.

Amplification factors for the various ranges in the response spectrum were considered in References [5] and [6]. The values determined therein for a number of earthquakes, with some smoothing and reduction of peaks to present a reasonably consistent probability of failure (of the order of about 10 percent or less), are given in Table 2. The amplification factors given in that table are used in connection with fig. 8, as explained below.

For each of the amounts of damping shown in Fig. 8 or tabulated in Table 2, the amplified displacements are shown on the left, the amplified velocities at the top, and the amplified accelerations in that part of the right-hand side of the figure for which the lines are parallel to the maximum ground acceleration line, but lie above it. We shall identify these portions of the line as the amplified displacement region, the amplified velocity region, and the amplified acceleration region, respectively.

At a frequency of about 6 cps , the amplified acceleration region line intersects a line sloping down toward the maximum ground acceleration value, and intersecting that line at various frequencies, depending on the damping. The intersection is at a frequency of about 30 cps for $2 \%$ damping, and the other lines are parallel to the line for $2 \%$ damping. These lines are designated as the acceleration transition region of the spectra. Finally, beyond the intersection with the maximum ground acceleration line, the response spectrum continues with the maximum ground acceleration value for higher frequencies.

The spectra so determined can be used as design spectra for elastic responses. The spectra are completely described when the maximum ground motion values are given for the three components of ground motion, and the damping is known. When only the maximum ground acceleration is given, the values used for maximum ground velocity and displacement are taken as proportional to those in the figure, or as scaled by the same scale factor relative to the maximum ground acceleration compared with 1 g .

The amplification factors given in Table 2 and shown in Fig. 8 are still under study, but it is not expected that major revisions in them will be required.

## Design Spectrum - Inelastic

To use the design spectrum to approximate inelastic behavior, the following suggestions are made. In the amplified displacement region of the spectra, the left-hand side, and in the amplifjed velocity region, at the top, the spectrum remains unchanged for total displacement, and is divided by the ductility factor to obtain yield displacement or acceleration. The upper right-hand portion sloping down at $45^{\circ}$, or the amplified acceleration region of the spectrum, is relocated for an elasto-plastic resistance curve, or for any other resistance curve for actual structural materials, by choosing


## Table 2

## RELATIVE VALUES OF SPECTRUM AMPLIFICATION FACTORS

| Percent of Critical Damping | Amplification Factor For |  |  |
| :---: | :---: | :---: | :---: |
|  | Displacement | Velocity | Acceleration |
| 0 | 2.5 | 4.0 | 6.4 |
| 0.5 | 2.2 | 3.6 | 5.8 |
| 1 | 2.0 | 3.2 | 5.2 |
| 2 | 1. 8 | 2.8 | 4.3 |
| 5 | 1.4 | 1.9 | 2.6 |
| 7 | 1.2 | 1.5 | 1.9 |
| 10 | 1.1 | 1.3 | 1.5 |
| 20 | 1.0 | 1.1 | 1.2 |

it at a level which corresponds to the same energy absorption for the elastoplastic curve as for an elastic curve shown for the same period of vibration. The extreme right-hanc portion of the spectrum, where the response is governed by the maximum ground acceleration, remains at the same acceleration level as for the elastic case, and therefore at a corresponding increased total displacement level. The frequencies at the corners are kept at the same values as in the elastic spectrum. The acceleration transition region of the response spectrum is now drawn also as a straight fine transition from the newly located amplified acceleration line and the ground acceleration line, using the same frequency points of intersection as in the elastic response spectrum.

In all cases the "inelastic maximum acceleration" spectrum and the "inelastic maximum displacement" spectrum differ by the factor $\mu$ at the same frequencies. The design spectrum so obtained is shown in Fig. 9.

An earlier procedure for the definition of inelastic response spectra for design was presented in Reference [2]. In that presentation, the displacement bound, the velocity bound, and the acceleration bound were determined, respectively, by keeping the displacement constant, the energy constant, and the force in the spring constant, and drawing the corresponding maximum response displacement limits.

The revised procedure presented in this report is shown in Fig. 9 for $2 \%$ damping, for an elasto-plastic system with a ductility factor of 5 . Both the maximum displacement and maximum acceleration bounds are shown, for comparison with the elastic response spectrum.

The solid line DVAA shows the elastic response spectrum. The heavy circles at the intersections of the various branches show the frequencies which remain constant in the construction of the inelastic design spectrum.

The dashed line $D^{\prime} V^{\prime} A^{\prime} A_{0}$ shows the inelastic acceleration, and the lines DVA"A"o shows the inelastic displacement. These two differ by a constant factor $\mu=5$ for the construction shown, but $A$ and $A^{\prime}$ differ by the factor $\sqrt{2 \mu-1}=3$, since this is the factor that corresponds to constant energy, as indicated in Reference [2].

Of course, the elasto-plastic or other inelastic response spectra can be used only as an approximation for multi-degree-of-freedom systems.

In the deyelopment of a design spectrum one may choose to use an "effective" value of maximum ground acceleration rather than an actual value, particularly in cases where the higher spikes of acceleration are associated with very short durations and correspond to velocity changes much smaller than the maximum ground velocity, or where the duration of the earthquake motion is extremely short and the influence on failure or inelastic behavior is thereby lessened.

## Vertical and Horizontal Excitation

Since the ground moves in all three directions in an earthquake, and even tilts and rotates, consideration of the combined effects of all these motions must be included in the design of important structures. When the responses in the various directions may be considered to be uncoupled, then consideration can be given separately to the various components of base motion, and individual response spectra can be determined for each component or direction of transient base displacement. Calculations have been made for the elastic response spectra in all directions for a number of earthquakes. The complete results for the three components of motion for these are not yet available, but the trends are sumarized below.


There are several interesting features of the response spectra. For example, the frequencies at which spikes and valleys occur are generally not the sane for the different directions of any earthquake nor for the same directions at the same site for different earthquakes. The responses for the two horizontal directions show cross-overs and significant differences in some ranges of frequency. The vertical response is often equal to or greater than the maximum horizontal response in the high frequency region, but is somewhat to a great deal less in the intermediate and low frequency regions.

It is suggested that until further information becomes available the following design criteria be used:
(a) The design spectrum for vertical response be considered equal to that for horizontal response for frequencies in the amplified acceleration range or higher frequencies. In other words, the acceleration bounds are the same for both horizontal and vertical response.
(b) The design spectrum for vertical response be considered equal to two-thirds that for horizontal response for frequencies in the amplified velocity or displacement ranges.

## Combined Effects of Earthquake Motions

Since the responses for motions in the various directions (horizontal and vertical) may not occur at the same time, it is considered reasonable to combine the effects of the several components of motion in a probabilistic manner, by taking the maximum stress, deflection, or other specific response as the square root of the sums of the squares of the corresponding responses to the individual components of motion.
"The effects of transient tipping, tilting, and rotation of the ground during an earthquake have not been studied extensively. An elementary treatment of some aspects of these movements has been given in Section 7.7 of Reference [3], and the effects of rotation of the ground about a vertical axis on the accidental torsion in symmetrical buildings, for example, is given in Section 15.6 of the same reference.

When the responses of the structure or component are coupled, the analys is becomes much more complex and a three-dimensional (or at least twodimensional) response analysis must be considered. However, data regarding the simultaneous input motions must be used in such an analysis, and little guidance is available on this topic.

The motions due to an earthquake occur in both horizontal and vertical directions in a complex manner. It is necessary to consider the interactions between the responses in the various directions, and especially important to consider the interaction between the vertical and the maximum horizontal response. Vertical loads, and eccentricities of the vertical loads caused by horizontal displacements, must often be taken into account with especially heayy structures that carry large masses at or near the poincs which may deflect a great deal. Some of the resisting capacity for horizontal motions may be used up by the secondary effects of the eccentricities of the gravity loads.

Quite often, the vertical motions may produce vertical stresses in the structure or element that exceed by a large amount those stresses due to the inertial forces corresponding to the vertical acceleration multiplied by the mass of the element. This is true when the frequencies of vibration in the vertical direction of the element or component are in the range where major amplification of response can occur.

A number of points are often overlooked in the design of structures or components to resist dynamic motions. A summary of some of the more important factors, but by no means a complete listing of all of them, is contained herein.

One of the factors that is commonly overlooked is the matter of relative motions between the parts or elements of a system having supports at different points, because the support motions may not occur simultaneously. Hence, there may be transient relative motions which produce strains in the structure, in addition to the strains produced by the dynamic affects of the overall motion. This is especially important in piping, electric wiring, or other elements connecting parts of a facility.

Finaliy, there are a group of items which do not lend themselves readily to analytical consideration. These concern the details and material properties of the element or component, and the inspection and control of quality in the construction procedure. The details of connections of the structure to its support or foundations, as well as the various elements or items within the structure or component, are of major importance. Failures often occur at the connections and joints because of inadequacy of these to carry the forces to which they are subjected under dynamic conditions. Inadequacy in properties of the materials can often be encountered, leading to brittle fracture where sufficient energy cannot be absorbed even though such energy absorption may have been counted on in the design.

In order to insure that the intent of the designer is achieved, control of construction procedures and appropriate inspection practices are necessary. It is important that the practical aspects of seismic design be emphasized and that both designers and constructors be fully aware of their importance.

## V. Desirable Features of Design Codes

## Relation Between Analysis and Design

When the configuration of a structure is fixed by architectural or other requirements, the designer has a restricted choice in the development of the strength and ductility required to insure adequate seismic behavior. It is not always possible to say that some design layouts are better than others for dynamic resistance, although it is fairly clear that different choices of framing can lead to vastly different requirements of strength and ductility. For example, a framed structure is generally less stiff and usually lower in frequency than a shear wall structure with nearly solid walls providing lateral resistance. Hence the design forces may be smaller for the framed structure than for the shear wall structure, although the required ductility may be larger. Methods of design for the dynamic loadings arising from earthquakes are in general simpler and better understood for structures for which there is a great deal of experience. However, unless methods are developed and specifications are devised to take account of new structural types or of new imaginative architectural designs, such designs will be placed at a disadvantage relative to more standard designs because of the necessity for providing greater margins of safety for those designs for which experience is unavailable.

The methods of analysis, and also the details of the design specifications, have implications on the cost and the performance capability of the design. If the specifications are unduly conservative the design will not only be unduly conservative, but may also be forced into a type chat is stronger and less ductile than is desirable. It is difficult to avoid differences in the degree of conservatism among different types of structures, and in some cases it is undesirable to do so. Some materials by their nature,
including their variability or lack of adequate control of properties, may require a greater factor of safety than other materials the properties of which are more accurately determinable and controllable. The margin between incipient failure and complete collapse may differ for different materials and may therefore involve a difference in the factor of safety required in the design.

## Basic Function of Design Codes

The designer, as well as anyone else who has a responsibility for the final structure, has to have some general method of knowing that gross errors have been avoided, and must have some basis of comparison to insure that the design is adequate in an overall sense. It is the purpose of building codes and specifications to perform these functions. However, it is not yet established that building codes can do this kind of job without introducing constraints and controls that may be a severe handicap on the development of new design concepts and procedures. Where building codes are used to insure, by rule-of-thumb methods, that a design is adequate, they embody the result of experience and judgment and must therefore deal implicitly, if not explicitly, with particular structural types and configurations.

The most desirable type of design code or specification is one which puts the least restrictions on the initiative, imagination and innovation of the designer. Such a code might involve only criteria for: (1) the loading or environment; and (2) the level of response, the stresses and deformation, or the performance of the structure under the specified loading or environmental conditions. Such an approach need not, and preferably should not, indicate how the designer is to reach his objective, provided he can show that he has achieved a structural capability to resist the specified environmental conditions. This approach is generally the one that is now used for the design of nuclear reactor power stations. Experience over the past several years in approaching seismic design criteria in this way has indicated a number of problems, but has also been reasonably successful in avoiding constraints due solely to the specifications themselves, although there have been constraints based on the environmental conditions and the stress and deformation levels allowed.

## Seismic Response Criteria

The permissible level of response of a structure must, of course, be associated with the loading criteria. One cannot be specified independently of the other. This implies, for example, that different response criteria are to be associated with the probable earthquake or the historical earthquake from those used for the maximum credible or extreme earthquake. Moreover, for either of these, the response criteria should properly be a function of the type of structure, the relative cost of repairs for minor damage, and the hazard in terms of possible loss of life should the structure or any of its elements fail. Hence, the response criteria could be greatly different for individual homes than for multistory buildings housing hundreds or even thousands of people, and certainly different even from these for high dams above large centers of population or for nuclear reactor power stations.

It appears reasonable to establish such criteria in terms of the consequences of failure, and in relative terms associated with yield points or buckling loads of similar dynamic limit loads for the paricular material or structural elements used. The aim of the criteria should be consistent with the basic seismic design philosophy stated earlier. Appropriate performance criteria may well be stated most rationally in terms of probabilities of failure or collapse associated with various levels of the probability of the hazard considered.

It is essential that the response levels or maximum stresses and deformations be limited, for structures, components, and details such as joints and connections, in order to insure adequate strength and ductility of a structure as well as of its various component parts. However, it is desirable, in the development of the basis for a performance criterion, that the designer's approach not be too greatly constrained. For example, it may be unwise to prescribe limits for both strength and ductility in such a way that the balance between the two cannot be adjusted to take account of new material properties or new structural types as they are developed. A tradeoff between ductility and strength should be available in the methods that are permitted, so as to achieve economy without the sacrifice of safety. But whether one is interested in achieving strength or ductility, or both, the materials have to be used in an appropriate fashion, and adequate methods of inspection and control of construction are needed to insure that their use is proper.

## Methods of Analysis

A variety of methods of analysis are now available, ranging from simple upper-bound static coefficient methods to modal response combinations, including time history analyses either in the elastic or inelastic range, and extending to probabilistic methods or methods involving consideration of random vibrations. It should be possible to use any of these that are sufficiently justified by either general acceptance or by demonstrated mathematical and physical validity, with requiring that any one particular method be used. Of course, it is desirable always to allow the use of simple methods that are adequately conservative. Properly stated criteria, used with appropriate methods of approximate analysis and design, may make it unnecessary in many cases to perform detailed and costly analyses, particularly in those instances where the simpler approximate methods insure adequate margins of safety.

To push these concepts to the limit involves generally the idea of approximate methods that give reasonably accurate results or, at least, results that are consistent with those obtained from more precise analyses. Depending on the degree and extent of the approximation, it may be necessary, from the point of view of achieving a reasonable degree of precision, to have special modifications of a general procedure for various unusual structural classifications. Methods may be used that do not require knowledge of the period of vibration of the structure, for example, or the methods may involve an approximate determination of the natural period. Approximate damping factor determinations may be involved as well.

For the complete development of this type of approach it may be desirable to explore the possibility of a hierarchy of methods ranging from the crudest approximation, for very simple structures and structural elements, to more accurate approximate methods, for structures of intermediate complexity, and to relatively precise and accurate calculations, for extremely complex structures.

## Special Structures

Although many of the problems assoriated with the design of special structures such as nuclear reactors, high dams, schools and hospitals, are similar to those involved in other more ordinary types of structures, there are some implications of failure of these special structures that require special consideration in selecting margins of safety and the development of design procedures and criteria governing them.

Many siructures or parts of structures and many items of equipment can
be severely damaged without any implication of loss of life or even of major property damage in an earthquake. For such items and structures it is unnecessary and certainly uneconomical to provide great margins of safety for unlikely earthquakes. The margin of safety of the provision made for an earthquake of a reasonable degree of probability of occurrence within the lifetime of a structure need only be great enough to offset the cost of repairs or reconstruction.

However, structures whose loss of function might cause hazard to life, or structures which are important to prevent damage to major services, have to be designed on an entirely different basis. For such structures, an earthquake even of relatively low probability of occurrence, but one that possibly could occur, should not cause collapse or damage of such a nature that endangers the health or life of large numbers of the population.

Hence, for such structures, much greater accuracy in procedures and assumptions is required, and the type of design specification must be more carefully framed and more clearly stated to give an assuredly adequate margin of safety against failure even for unusual types of structure and framing.

The type of design specification used for major nuclear reactor power plants has emphasized loading or environmental criteria, and performance criteria in terms of stress and deformation levels of response. The experience that has been gained with criteria of these types indicates that benefits are possible for other types of special structures with similar kinds of design specifications. The advantages are in the encouragement of the designer to explore various types of structures, to consider the use of a variety of materials, and to look for economical ways of achieving the desired levels of safety and performance.

Detailed prescriptions of methods and procedures were necessary when the majority of practicing engineers had neither the sophistication nor the computational aids to take account of the more accurate methods of analysis and design that are now available. However, this situation has changed and is continuing to change at a rapid rate. With the increase in numbers of more highly trained engineers, and with a greater store of knowledge available, together with more efficient ways of using that knowledge which have become possible with the general availability of and accessibility to high speed digital computers, it appears that it is now possible to make a major change in our methods of specifying or codifying seismic design.

## General Comments and Conclusions

The field of earthquake engineering is relatively new, not much more than three decades old, and advances in knowledge are progressing at a rapid rate, not only because of a greater emphasis on analytical and experimental work in the laboratory, but also because of the availability of more definitive information on earthquake motions, the accumulation of strong-motion records, and recent accelerated expenditures on research. It is important that the discoveries from observations, and studies from the research laboratory and the analyst, find their way into practice as soon as possible. But this is difficult because engineers are traditionally unwilling to take chances on things that they have not proved out. Too little attention has been given to methods of demonstrating adequate performance capability for major structures and structural elements. Although this is not necessarily a part of our consideration in design specifications, it might well be desirable to look for ways of determining the capability of completed structures or for ways of proving the performance capability in the design stage by appropriate methods, so as to encourage the development of more economical designs and methods.

In order the insure that the intent of the designer is achieved, control
of construction procedures and appropriate inspection practices are necessary. This point cannot be overemphasized. lt is difficult to synthesize and distill the collective experience and judgment of the engineering profession into a set of rules, especially when they cannot be put into a mathematical formulation. This is a difficulty, however, not only with performance and environmental criteria but also with more standard types of design specifications of the current and past eras. Nevertheless, it is important that the practical aspects of seismic design be emphasized and that engineers and constructors be fully aware of their importance.

It is the intent of this discussion to focus attention on the aims and objectives of seismic design in such a way as to encourage the development of methods and practices suitable for structural design of the future; methods that will permit more treedom and latitude to the architectural and engineering innovator.

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## APPENDIX 6

## VERTICAL GROUND MOTION IN EARTHQUAKES-- <br> ITS NATURE AND ITS EFFECTS ON THE <br> RESPONSE OF BUILDINGS

## APPENDIX 6

VERTICAL GROUND MOTION IN EARTHQUAKES--ITS NATURE
AND ITS EFFECTS ON THE RESPONSE OF BUILDINGS
by
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Introduction
Vertical ground motions currently are given surprisingly little consideration in the earthquake resistant design of structures. This disregard is mainly based on the assumption that structures are almost "rigid" in the vertical direction, and hence the effects of vertical ground motions can be neglected. However, the few investigations carricd out on this subject show that the vertical periods of many standard structures and important structural components are in the range of amplifications of response spectra developed from vertical acceleration components. The amplification of the vertical acceleration at the top of multistory steel structures may be in the order of four times the ground acceleration (references 45, 47). Such accelerations could contribute to the compression failure of columns, increase the ductility requirements in beams, reduce the factor of safety against overturning, or cause a critical condition in a prestressed bean by reducing the effective dead load on the beam (references 42, 46). More research on this subject is therefore urgently needed.

The following summary of information available on vertical
ground motions and its effects on the response of structures and structural components is based on the investigations reported in References 42 to 51 . The summary is by no means complete, since it only includes work carried out in the United States and disregards research done in Japan and other countries.

## Nature of Vertical Ground Motion

A large number of records are available on vertical accelerations in past earthquakes from accelerographs recording horizontal and vertical components. All accelerogram records were digitized by and are available through the Earthquake Engineering Research Laboratory of the California Institute of Technology. Response spectra for single degree of freedom damped oscillators derived from these records are presented in references 46 and 48 , and are also available through U.S. Coast and Geodetic Survey. A typical accelerogram for vertical accelerations is shown in Figure A6-1, and a comparison of horizontal vs. vertical spectral responses of SDF oscillators (reference 48) is presented in Figures A6-2 and A6-3.

The following general observations can be made from the data presented in the available references:

1. The peak vertical accelerations may not occur at exactly the same time as the peak horizontal accelerations; however, major vertical accelerations do occur within the same general time as the major horizontal ones. Thus the vertical and horizontal accelerations could be conservatively assumed to act simultaneously. (See Reference 46). Iyengar
and Shinozuka (reference 44) point out that there is no reason to believe that the horizontal and vertical components are uncorrelated, and they propose to represent the two components by a bivariate stationary Gaussian process with a cross spectrum between horizontal and vertical acccleration.
2. An examination of the available response spectra indicates that for most cases the response spectra for vertical ground motion are flatter (broader) than those for horizontal motions (reference 48). The spectra for vertical motion show significant amplification in the high frequency range (4 to 20 cps ), and most of them also indicate an attenuation of the low period components (reference 46). It can also be seen that the response spectra for vertical motion approach the ground acceleration at higher frequencies than is the case for horizontal motion (reference 48). This phenomenon is due mainly to the presence of higher frequencies in vertical components of ground motion (rcference 47). This will be reflected in the construction of design spectra, where the vertical ground acceleration is amplified over a larger frequency domain than the horizontal acceleration.
3. Vertical accelerations increase rapidly as the distance from the fault decreases, more so than horizontal accelerations. This is confirmed with experience from underground nuclear explosions, where vertical accelerations
close to the point of detonation in some cases exceed the horizontal accelerations (see reference 46).
ad/v $\mathrm{v}^{2}$ Ratio
The nondimensional quantity $\mathrm{ad} / \mathrm{v}^{2}$ can be taken as a basic index for monitoring the shape, and especially the breadth of the response spectra. The discussion of this parameter and others necossary to characterize the vertical ground motion is extracted from reference 48. A summary of the maximum values of the ground motion data studied in reference 48 is presented in Table A6-1.

Recognizing that the maximum ground displacements have to be obtained from the recorded accelerations through double integration and that these values are very sensitive to the base line adjustment procedure, it can be stated that the accelerations, the vclocities, and the ad/v ratio are the most important parameters characterizing a ground motion. It also is established that the $\mathrm{ad} / \mathrm{v}^{2}$ ratio is a function of the focal distance of the earthquake and the attenuation of motion in the ground. This ratio is therefore of foremost importance for the construction of design spectra and needs to be carefully studied.

The values of $\mathrm{ad} / \mathrm{v}^{2}$ range from 1.84 to 30.58 , but disregarding the $E 1$ Centro earthquake of $5-18-40$, most values fall in the range from about 5 to 15 . In general it will be noted that the $\mathrm{ad} / \mathrm{v}^{2}$ values are higher for vertical motion, as would be expected in part because the high frequency components in the vertical direction are more pronounced than in the horizontal direction.

The average values of $\mathrm{ad} / \mathrm{v}^{2}$ for different site conditions are
summarized in Table A6-2. The average value for horizontal motions was about 5.6 , and differs little from rock sites to alluvial sites. For vertical motions, the average value for alluvial sites was equal to 10.0 and that for rock sites was 13.0 . Since only three sets of data were available for rock sites, more confidence can be placed in the values obtained for alluvial sites. Based on the available data, it was concluded that $a d / v^{2}$ ratios of 6 and 10 may be representative for horizontal and vertical ground motions, respectively.

Peak Horizontal vs. Vertical Accelerations
Newmark and Hall state in Reference 49 that the vertical compononts of motion may be somewhat less, or in some circumstances equal to or slightly greater than the horizontal motions, depending upon whether the associated fault motions in the earthquake are primarily horizontal (strike-slip motions) or primarily vertical (thrust fault or dip-slip motions). This general statement was confirmed by the study of particular earthquakes that show a range of ratios of vertical to horizontal peak acceleration from 0.27 for the Ferndale earthquake (12-21-54) to 1.29 for the Holiday Inn record of the San Fernando carthquake. It is clear that this ratio is a function of the fault motion, the distance from the fault, the ground motion intensity and the geological site conditions. Average values of these ratios for different site characteristics are presented in Table A6-3. The values range from 0.40 to 0.72 , depending on the acceleration level included and the geological conditions. On the basis of these data, and ralizing that only a few samples existed for the rock site, it
was decided in reference 48 to take the ground acceleration for a given site for the vertical spectrum to be equal to two-thirds of that for the horizontal motion.

Response Amplifications
Studies of the response amplification in various ranges of frequencies were carried out in reference 7. The input ground motion was normalized to the following values:

Maximum ground displacement $\quad 1.0$ inch
Maximum ground velocity $\quad 10.0 \mathrm{in} / \mathrm{sec}$
Maximum ground acceleration 1.0 g
The results for mean response amplification for 5 percent critical damping is shown in Figure A6-4 for the horizontal and the vertical ground motion.

The following observations wore made regarding the vertical response amplification:

1. The amplification factors for accelerations are virtually constant for the range of frequencies from about 3 to 10 hertz, and then decrease fairly uniformly to intersect the ground motion accelerations at frequencies of about 50 hertz for all values of damping.
2. For the intermediate range of frequencies (0.3 to 3.0 hertz), a slight drop in the velocity amplification factor is evident as the frequency increases. However, the drop is only of the order of about 10 percent over the frequency range for which vclocity amplification is valid, and it therefore appears reasonable to use a constant
amplification for the velocity range as well as for the acceleration and displacement range.
3. In the low frequency range of the spectrum the displacements are amplified by a constant factor for all values above the 0.05 hertz level.

The statistical values of response amplifications for horizontal and vertical motion obtained from a normal distribution curve for $0.5,2,5$, and 10 percent of critical damping are presented in Table A6-4. It is recommended that these amplification factors for vertical ground motion be applied to the following frequency ranges:

| Displacement amplification | 0.1 to 0.3 hertz |
| :--- | :--- |
| Velocity amplification | 0.3 to 3.0 hertz |
| Acceleration amplification | 3.0 to 10.0 hertz |

Design Spectra for Vertical Motion
It has to be emphasized that it is difficult to generalize as to the shape of the vertical spectra versus the shape of the horizontal spectra. This shape will be a function of the distance to the fault, the site characteristics, the ground motion intensity, etc. In part such a generalization has been attempted in reference 48 , where some of the parameters required in constructing the vertical design spectra are expressed as fractions of the parameters used for horizontal design spectra. The procedure utilized in reference 48 for the construction of design spectra for vertical ground motion can be briefly summarized as follows:

1. The peak vertical ground acceleration is taken to be twothirds of the peak horizontal acceleration, regardless of site.
2. The ratio of $v / a$ for the vertical motion to that of the horizontal motion is 0.90 , regardless of site.
3. The $\mathrm{ad} / \mathrm{v}^{2}$ for vertical motion is taken to be 10.0 , regardless of site.
4. These three parameters define the ground motion bounds. Tho design spectra are obtained by multiplying these ground motion values by the amplification factors given in Table A6-4. The frequency ranges applicable for the amplification of acceleration, velocity, and displacement are listed previously. The faring frequency in the high frequency region was taken to be 50 hertz for all values of damping.

It should be noted that the above parameters wore computed from a statistical study including only strong motion data, i.e., disregarding all traces that had accolerations less than 0.1 g in the case of horizontal motion and 0.05 g in the case of vertical motion.

The values of ground motion bounds of acceleration, velocity and displaccmont for horizontal and vertical ground motions are presented in Table A6-5. The values are normalized with respect to a horizontal ground acceleration of 1.0 g . The displacement values were calculated on the basis of the $a, v$, and $a d / v^{2}$ values, and were then rounded off to a representative number. The actual response spectra bounds, obtained through multiplication with the appropriate amplification factors, are tabulated in Table A6-6 for horizontal and vertical motion. A typical vertical response spectrum is shown in Figure A6-5.

Effects of Vertical Ground Motion on the Response of Buildings

The types of structures and structural components that may experience significant effects from vertical ground motions are high rise buildings, cantilevered structures such as grandstand roofs, aircraft hangars and marquees, cable suspended structures, slabs, and long span elements, particularly of prestressed concrete (see references $46,47)$.

Various opinions are expressed in the literature regarding the importance of the effects of vertical accelerations. Larson (reference 47) states that studies of the behavior of structures in the Anchorage, Caracas, and Santa Rose earthquakes disclosed many effects which could be ascribed to vertical components of seismic excitation. Jennings (reference 45), to the contrary, concluded from a damage study of the San Fernando carthquake: "There were no instances where it appeared to the writers that vertical accelerations had been major contributors to the damage sustained by building structures, and it is not recommended at this time that vertical accelerations be included in normal seismic design procedures for typical buildings. There are special structures, however, which could be more sensitive to vertical accelerations and vertical motions should be considered in such cases." Rosenblueth (reference 50) reports the appearance of vertical tensions during nearby earthquakes. These, as well as large compressions, also caused by vertical accelerations, can combine with the effects of overturning moments. He also states that we may have to expect appreciably permanent deformations in floor systems after several nearby strong
earchquakes.
Regardless of the wide range of opinions expressed in the literature, it is well established that vertical accelexations are greatly amplified from the ground floor to the top of multistory buildings. This can be seen from the records of the San Fernando earthquake presented in Table A6-7 (see reference 45), which show an amplification of vertical acceleration ranging from 1.4 to 4.5. This is also evident from analytical investigations that show that the vertical period of many typical structures lies in the range of acceleration amplification.

Dynamic Properties of Structures in the Vertical Direction

Building structures can be modeled through a lumped massspring system, with each point mass representing the total weight at the floor level, and each spring representing the axial deformation of the columns between floors (see reference 46). The effects of intcrconnecting girdcrs on the columns could be included, but is not considered to be significant. The vertical period of buildings depends on the height of the structure and on the level of stresses in the column. For multistory steel structures the vertical period can be estimated from Figure A6-6, taken from reference 46.

Results of Analytical Investigations
A series of steel structures, ranging from 5 to 51 stories, was studied in reference 46 . The response spectra for the Taft and Golden Gate Park earthquakes were used as input in the analysis.

Elastic behavior was assumed in the analysis. This is a reasonable approximation for studies of structures in the vertical direction because of the current design philosophy to avoid plastic hinges in the columns. The findings of this study are briefly summarized below.

1. The vertical periods of steel structures lie in the range of acceleration amplification of the spectra developed for vertical motion.
2. The amplification of the vertical acceleration at the top of steel structures may be in the order of four times the ground acceleration. Similar results should be expocted for buildings of other materials. This amplification could increase or decrease column dead loads by 20 percent or more.
3. Vertical accelerations may contribute to the overstress or compression failure of columns and may reduce the factor of safety against overturning.

A study of a ten story unbraced steel frame subjected to gravity loads and a combination of horizontal and vertical ground motion components is reported in reference 42. An inelastic dynamic analysis of this structure was carried out, using the Pacoima Dam and the Taft earthquake records as an input. Both records were normalized to a maximum vertical ground acceleration of 0.31 g . For comparison, a second analysis was carried out with the structure subjected only to gravity loads and horizontal accelerations. The maximum vertical accelerations of the selected nodal points in the structure are shown in Figure A6-7, for the Pacoima Dam record. The following conclusions
were drawn from a study of the response of the structure that was designed for seismic loads specified in the Uniform Building Code and following the allowable stress design procedure.

1. The inclusjon of vertical components of ground motion increases the ductility requirements in both the columns and girders of the upper stories. Vertical motion is particularly significant in causing inelastic action at the midspan of the girders. Inelastic action in the columns is increased by the amplification of the vertical motion in these members and by the amplified vertical response of the girders.
2. The relative importance of the vertical motions is dependent on the main characteristics of the complete time histories of both the horizontal and vertical components of the earthquake. The duration and frequency content as well as the maximum acceleration of the ground motion need to be considcred in determining the offccts of earthquakes on structures.
3. Ductility requirements at the critical regions of individual members cannot be evaluated with accuracy from just analyzing maximum lateral displacements and maximum relative story drifts.

Iyengar and Shinozuka (reference 44) used statistical models for the horizontal and vertical components of ground motion to study the cffect of self-woight and vertical acceleration on the tip deflection, base bending moment, and base shear force of cantilever type
structures. As expected, the effects were of more significance in taller structures than in shorter ones, but in either case the differences caused by including self-weight and vertical acceleration seem to be considerable.

In conclusion, it has to be stated that no evaluation of the effects of vertical ground motion for structures older than steel structures and for important structural components could be found in the literature. Further research in this area seems to be urgently needed.

| Record description | - Maximum ground acc. a, g | Maximum ground vel $v$, in/sec | Maximu ground d, in | $=\frac{a d}{v^{2}}$ | ```Site``` | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| F |  |  |  |  | 40.80 ft of alluvium over 100 ft of sandstone over siltstone | Instrument on the ground floor of a |
| N 46 W | 0.120 | 2.86 | 0.95 | 5.39 |  | 2 story frame |
| S 44 W | 0.123 | 1.73 | 1.07 | 16.99 |  | structure |
| Vertical | 0.032 | 1.02 | 1.24 | 14.74 |  |  |
| Ferndale, 12-21-54, 1156 PST (Record IA 9) |  |  |  |  | $40-80 \mathrm{ft}$ of alluvium over 100 ft of sandstone over siltstone | Instrument on the ground floor of a 2 story frame structure <br> Ref. (8) |
| N 46 W | 0.209 | 9.79 | 4.92 | 4.15 |  |  |
| N 44 E | 0.166 | 14.10 | 8.09 | 2.61 |  |  |
| Vertical | 0.045 | 3.13 | 2.49 | 4.42 |  |  |
| Eureka, 12-21-54, 1156 PST (Record IA 8) |  |  |  |  | $100^{\prime}$ sandstone (poorly consolidated) over 360 ft of siltstone over sandstone | Instrument in the basement of a brick and stone building |
| N 11 W | 0.189 | 5.92 | 8.45 | 17.61 |  |  |
| N 79 E | 0.271 | 9.23 | 3.14 | 3.86 |  |  |
| Vertical | 0.110 | 2.64 | 2.22 | 13.54 |  | Ref. (8) |
| Hollister, 4-8-61, 2323 PST (Record IA 18) |  |  |  |  | 500 ft of alluvium over cenozolc rock water table at 50 ft | Instrument on the first floor of the public library, a 2 story structure |
| s 01 W | 0.076 | 3.10 | 3.03 | 9.26 |  |  |
| N 89 W | 0.189 | 6.45 | 1.97 | 3.46 |  |  |
| Vertical | 0.056 | 1.73 | 1.03. | 7.45 |  |  |

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| Record description | - Maximum ground acc. a, $g$ | Maximum ground vel. $v, \mathrm{in} / \mathrm{sec}$ | Maximu ground d d, in | $\frac{a d}{h^{2}}$ | $\begin{gathered} \text { Site } \\ \text { description } \end{gathered}$ | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pacoima Dam, 2-9-71, 0600 PST (Record 1C 041) |  |  |  |  | Highly jointed diorite gneiss 4 km from surface faulting | Small bullding houses the Instrument |
| S 74 W | 1.250 | 22.49 | 5.11 | 4.88 |  |  |
| S 16 E | 1.241 | 43.70 | 23.18 | 5.82 |  |  |
| vert: ! | 0.718 | 23.06 | 13.75 | 7.17 |  |  |
| Castaic, 2-9-71, 0600 PST (Record ID 056) |  |  |  |  | Sandstone | Small building houses the instrument |
| N21 E | 0.333 | 6.73 | 2.05 | 5.82 |  |  |
| N 69 W | 0.281 | 10.55 | 3.22 | 3.14 |  |  |
| Vertical | 0.181 | 2.75 | 1.42 | 13.13 |  |  |
| Holiday Inn (First floor), 2-9-71, 0600 PST (Record IC 048) |  |  |  |  | Alluvium - 8 km from surface faulting | Instrument on the first floor of a 7 story RC building structure |
| NS | 0.258 | 12.13 | 8.70 | 5.90 |  |  |
| EW | 0.137 | 9.68 | 6.37 | $3.60{ }^{\circ}$ |  |  |
| Vertical | 0.177 | 12.81 | 6.37 | 2.65 |  |  |
| 15250 Ventura Boulevard (Basement), 2-9-71, 0600 |  |  | 00 PST ( | IH 115) | Alluvium. <br> water table at 55' | Instrument in the basement of a 12 story RC building structure |
| $N \\| \mathrm{E}$ | 0.234 | 10.96 | 7.07 | 5.32 |  |  |
| N 79 W | 0.154 | 7.88 | 4.48 | 4.29 |  |  |
| Vertical | 0.108 | 4.77 | 3.09 | 5.67 |  |  |
| E1 Centro, 5-18-40, 2037 PST (Record IA 1) |  |  |  |  | Alluvium to about 5000 ft | Instrument on the first floor of a 2 story massive concrete, heavily reinforced structure |
| NS | 0.352 | 13.88 | 4.74 | 3.35 |  |  |
| EW | 0.223 | 11.72 | 6.58 | 4.13 |  |  |
| Vertical | 0.280 | 3.95 | 4.41 | 30.58 |  |  |


| Site | Direction | No. of Records | $a d / v^{2}$ |
| :---: | :---: | :---: | :---: |
| alluvium E rock | horizontal | 28 | 5.6 |
| alluvium | horizontal | 22 | 5.7 |
| rock | horizontal | 6 | 5.4 |
| alluvium \& rock, ${ }^{\text {a }}$ a 0.1 g | horizontal | 20 | 5.7 |
| alluvium, $2>0.1 \mathrm{~g}$ | horizontal | 14 | 5.9 |
| rock, ${ }^{\text {a }}$ >0.1g (same as above) | horizontal. | 6 | 5.4 |
| alluvium, $\ll 0.1 \mathrm{~g}$ | horizontal | 8 | 5.3 |
| alluvium $\varepsilon$ rock | vertical | 14 | 10.7 |
| alluvium \& rock* | vertical | 13 | 9.1 |
| al huvam | vertical | 11 | 10.0 |
| alluvium* | vertical | 10 | 7.9 |
| rock | vertical | 3 | 13.0 |
| alluvium \& rock, $a>0.05 \mathrm{~g}$ | vertical | 8 | . 12.4 |
| alluvium, $2>0.05 \mathrm{~g}$ | vertical | 5 | 12.0 |
| alluvium, ${ }^{\text {a }}$ ¢ $0.05 \mathrm{~g}^{*}$ | vertical | 4 | 7.3 |
| rock, $2>0.05 \mathrm{~g}$ (same as above) | vertical | 3 | 13.0 |
| alluvium, $\alpha^{<0.05 g}$ | vertical | 6 | 8.4 |
|  | i | $\cdots$ |  |

* Discarding the extreme value, El Centro, $5-18-40,2037$ PST, ad $/ \mathrm{v}^{2}=30.58$

Summary of Average ad/v ${ }^{2}$ Values
Table A6-2. (reference 48)

| Site | No. of records | Average $\frac{a-v e r t i c a l}{a-h o r i z o n t a l}$ |
| :---: | :---: | :---: |
| alluvium \& rock | 28 | 0.53 |
| alluvium | 22 | 0.53 |
| rock | 6 | 0.54 |
| alluviume rock, $a_{h}>0.1 \mathrm{~g}, \mathrm{a}_{\mathrm{p}}>0.05 \mathrm{~g}$ | 15 | 0.65 |
| alluvium, $a_{h}>0.1 \mathrm{~g}, a_{v}>0.05 \mathrm{~g}$ | 9 | 0.72 |
| alluvium $\varepsilon$ rock, $a_{h}<0.19, a_{v}<0.05 \mathrm{~g}$ | 13 | 0.40 |
| alluvium, $a_{h}<0.1 \mathrm{~g}, a_{v}<0.05 \mathrm{~g}$ <br> (same as above) | 13 | 0.40 |

[^4]| Percentile | Damping | All Records (28) |  |  | Records with a $>0.19$ (20) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | D | $V$ | A | D | $v$ | A |
| 50 | 0.5 | 1.98 | 2.86 | 4.00 | 1.97 | 2.58 | 3.67 |
|  | 2.0 | 1.69 | 2.23 | 2.91 | 1.68 | 2.06 | 2.76 |
|  | 5.0 | 1.39 | 1.74 | 2.20 | 1.40 | 1.65 | 2.11 |
|  | 10.0 | 1.13 | 1.38 | - 1.72 | 1.15 | 1.34 | 1.65 |
| 75 | 0.5 | 2.66 | 3.81 | 5.02 | 2.66 | 3.41 | 4.65 |
|  | 2.0 | 2.23 | 2.89 | 3.52 | 2.24 | 2.68 | 3.36 |
|  | 5.0 | 1.80 | 2.19 | 2.59 | 1.83 | 2.10 | 2.48 |
|  | 10.0 | 1.43 | 1.69 | 1.97 | 1.47 | 1.66 | 1.89 |
| 90 | 0.5 | 3.27 | 4.67 | 5.95 | 3.28 | 4.16 | 5.53 |
|  | 2.0 | 2.72 | 3.48 | 4.06 | 2.74 | 3.23 | 3.90 |
|  | 5.0 | 2.17 | 2.60 | 2.93 | 2.21 | 2.51 | 2.82 |
|  | 10.0 | 1.71 | 1.98 | 2.20 | 1.75 | 1.94 | 2.11 |
| 95 | 0.5 | 3.64 | 5.19 | 6.50 | 3.65 | 4.60 | 6.05 |
|  | 2.0 | 3.02 | 3.84 | 4.39 | 3.04 | 3.57 | 4.22 |
|  | 5.0 | 2.39 | 2.84 | 3.14 | 2.44 | 2.75 | 3.03 |
|  | $i 0.0$ | 1.87 | 2.15 | 2.33 | 1.98 | 2.11 | 2.24 |

Statistical Value of Response Amplifications (Normal Distribution - Horizontal Components)

Table A6-4. (reference 48)

| Percentile | Damping | All Records (14) |  |  | Records with a $>0.05 \mathrm{~g}$ (8) |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | D | V | $A^{\prime}$ | D | V | A |
| 50 | 0.5 | 1.77 | 2.74 | 4.22 | 1.86 | 2.52 | 4.02 |
|  | 2.0 | 1.57 | 2.10 | 2.86 | 1.65 | 1.97 | 2.80 |
|  | 5.0 | 1.33 | 1.56 | 2.08 | 1.40 | 1.51 | 2.05 |
|  | 10.0 | 1.09 | 1.22 | 1.62 | 1.16 | 1.17 | 1.59 |
| 75 | 0.5 | 2.33 | 3.67 | 5.47 | 2.48 | 3.39 | 5.46 |
|  | 2.0 | 2.04 | 2.77 | 3.60 | 2.17 | 2.61 | 3.70 |
|  | 5.0 | 1.70 | 2.06 | 2.52 | 1.81 | 1.97 | 2.57 |
|  | 10.0 | 1.38 | 1.55 | 1.91 | 1.47 | 1.49 | 1.92 |
| 90 | 0.5 | 2.83 | 4.51 | 6.59 | 3.04 | 4.17 | 6.76 |
|  | 2.0 | 2.46 | 3.37 | 4.27 | 2.63 | 3.18 | 4.51 |
|  | 5.0 | 2.04 | 2.47 | 2.92 | 2.18 | 2.37 | 3.04 |
|  | 10.0 | 1.63 | 1.84 | 2.17 | 1.75 | 1.78 | 2.22 |
| 98 | 0.5 | 3.13 | 5.02 | 7.26 | 3.37 | 4.64 | 7.53 |
|  | 2.0 | 2.71 | 3.73 | 4.67 | 2.91 | 3.52 | 4.99 |
|  | 5.0 | 2.24 | 2.73 | 3.16 | 2.40 | 2.62 | 3.32 |
|  | 10.0 | 1.79 | 2.01 | 2.32 | 1.92 | 1.95 | 2.40 |
| Statistical Values of Response Amplifications (Normal Distribution - Vertical Components) |  |  |  |  |  |  |  |


| Site | Direction | $\begin{gathered} \text { Acceleration } \\ a, g \end{gathered}$ | Velocity <br> $v$, in/sec | Displacement d, in | $a d / v^{2}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| alluvium | horizontal | 1.0 | 48 | 36 | 6.04 |
| rock | horizontal | 1.0 | 28 | 12 | 5.92 |
| alluvium | vertical | 2/3 | 29 | 33 | 10.10 |
| rock | vertical | 2/3 | 17 | 11 | 9.80 |

[^5]
 $\underset{\text { Table A6－7 }}{\text {（reference }}$ 45） TYPICAL PEAK ACCELERATIONS IN MULTI－STORY BUILDINGS
Accelerations in Fractions of g
Date $\quad$ No．Ground，Basement or lst Floor Intermediate Level $\quad$ Roof or Top Floor


| O～ | 0 |
| :---: | :---: |
| かo | ¢た |
| のののお | のの |



| ueudrup 0not | 81 |
| :---: | :---: |
| әxt¢sirm 0029 | 21 |
| อxب̧silM 00¢z | 91 |
| exmuan oszsi | ¢ I |
| upooult 6e．98 | もI |
| จxฺ¢sITM 0Lも | $\varepsilon I$ |
| ＊əxŢ̣STTM 0ILE | 21 |
| POOMKイITH 080 L | 11 |
| hinqxoy 027 | 01 |
| uosfiraqoy 02I | 6 |
|  | 8 |
| 「euoz It02 | $L$ |
| 7．suns L897 | 9 |
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Mean Response Amplification, 5\% Crit. Damping _ _ - Vertical Components

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|  |  | FREQUENCY, CPS Design Spectra, Vertical Direction. Rock. 50 Percentile $0.5,2,5, \& 10$ percent critical damping (reference 48)





Fig. A6-7. Maximum Vertical Accelerations for Pacoima Dam Record (ref. 42)



(1)








$A 7-13=$




[^0]:    From Saint-Amand,
    1973

[^1]:    read and hrite line source properties 1024 FRITE (G:1024)
    
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    READ 5,10401
    READ 5,1000
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    $\times 0=X L 1(1 L)$
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    $x(1)(1 L)=X L 2$

    ## XLI(IL)=XLZ(IL)

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[^2]:    

[^3]:    
    

[^4]:    Summary of Vertical to Horizontal Acceleration Ratios Table A6-3. (reference 48)

[^5]:    Horizontal and Vertical Design Ground Motions Table A6-5. (reference 48)

