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## The John A. Blume Earthquake Engineering Center

Department of Civil Engineering Stanford University

## A STUDY OF SEISMIC RISK FOR NICARAGUA Part I



by

Haresh C. Shah Christian P. Mortgat Anne Kiremidjian Theodore C. Zsutty

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Part I

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#### SYMBOLS AND DEFINITIONS

а	= Fixed Acceleration
A <sub>g</sub> , A	= Effective Ground Acceleration
AZG	= Acceleration Zone Charts
С	= Subscript for Condemnation Threshold
CAP	= Subscript for Structure Capacity
CON	= Subscript for Condemnation Capacity
CTSD	= Condemnation Threshold Spectrum for Structure Deformation Determination
D	= Subscript for Damage Threshold
Dg	= Effective Ground Displacement
DAF	= Dynamic Amplification Factor for Spectral Shape
DAM	= Subscript for Damage Capacity
DEM	= Subscript for Earthquake Demand
DES	= Subscript for Member Design Level
DTSS	= Damage Threshold Spectrum for Member Strength Determination
E	= Expected Value
К <sub>G</sub>	= Confidence Limit Contribution due to Use Group
К <sub>Т</sub>	= Confidence Limit Contribution due to structural system type
(K <sub>G</sub> +K <sub>T</sub> )♂	= Confidence Limit above the mean DAF
L	= Structure Life in years
m	= Fixed Richter Magnitude
М	= Richter Magnitude
м <sub>b</sub>	= Body Wave Magnitude

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м <sub>S</sub>	= Surface Wave Magnitude
MMI	= Modified Mercalli Intensity
n	= Number of events
N (M)	= Number of earthquakes above Richter Magnitude M
N'(M)	= Normalized N(M)
р	= Probability of success (Bernouilli Trials)
р	= Probability
R .	= Reliability = 1-P
RP	= Return Period
$S_{a}^{(\beta,T)}$	= A basic acceleration response spectrum ordinate for a system with damping $\beta,$ and period T
SRSS	= Square Root of Sum of Squared Modal Responses
t	= Fixed Period of Time
V	= Lateral Load due to Earthquake Ground Motion
Vg	= Effective Ground Velocity
αβ	= Regression Coefficient
αı	= Normalized $\alpha$
β	= Damping Ratio
β'	= Modified Damping Ratio
$\beta_{\rm F}$	= Damping due to structure-foundation interaction
β <sub>S</sub>	= Damping due to structural system type
Δ	= Deformation
δ	= Mean Rate of Occurrence (Poisson Law)
μ	= Ductility Ratio
μ'	= Modified Ductility Ratio
σ	= Standard Deviation of the DAF

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#### CHAPTER I

#### INTRODUCTION

On December 23, 1972, three strong earthquake tremors struck the city of Managua. Even though of "moderate" magnitude, this event caused thousands of deaths, many more injuries, an untold amount of economic hardship and disruption of a way of life. It is very hard if not impossible to translate all these losses into quantitative economic terms. However, such a catastrophe does remind us of the devastation and far-reaching consequences of major earthquake events.

The rebuilding efforts which follow such events bring up many questions. Are existing design requirements adequate? What level of future risk is acceptable? How should the acceptable risk level be translated into acceptable design parameters? Should similar land uses be permitted in the future for areas which suffered major damage? These and numerous other questions become especially relevant after a significant damaging event. The decision process which leads to answers for these questions is a complex mixture of political expediency, engineering knowhow, socioeconomic optimization and proper understanding of the overall parameters involved in the decision making process. In times when no significant earthquake events have taken place, the decision making process goes on at a notably slow rate, while decisions immediately after significant events are often based on expediency and, at times, on irrational analysis. This leads to decisions which might

well be considered inadequate in the light of rational decisions made on the basis of long-term perspective.

This report is the result of a seismic risk study conducted at Stanford and supported by Banco Central de Nicaragua and the National Science Foundation grant GI 39122. The total seismic risk analysis of Nicaragua is done in two parts. This report is Part I of the study. In general, Part I is associated with the future probably seismic loading determination of Nicaragua and how that loading can be used to determine future damage potential and "insurance risk." Suggestions regarding seismic zoning of the country are also presented in this Similarly, the relationships between seismic loading information part. and design provisions is discussed. Part II is a continuation of Part I, and in general is associated with probabilistic response spectra analysis, probabilistic seismic exposure of different classes of structures and the seismic structural response. A decision analysis of associated risks of loss of life, injury and economic loss will be performed in Part II. A simplified equivalent design procedure will be developed, based on the general concepts and findings of the more detailed response spectrum method. This simplified approach is intended to be applicable for a majority of ordinary regular structures.

It should be emphasized that the work presented in this report is to provide a base for planning and decision making in Nicaragua. The project results provide professionals in Nicaragua with tools and procedures to make seismic risk analysis. A single recommendation today does not appear practical to fit all future circumstances. Hence, major effort is focused on presenting methodology and procedures

that can be used by participating organizations in decision making processes.

Finally, it should be kept in mind that the work and results presented here depend on the available data base and information. The reliability of results are at best as good as the reliability of the data on which the results are based. It is very easy to attack and criticize any work from the point of view of data reliability. However, it is very difficult to obtain long-range reliable data. We have used the best available information through various organizations and researchers. The forecasts and predictions are based on those data. However, if in the future more reliable data are available, the model can easily accommodate the inclusion of new information and update the results. Further discussion on this topic will be presented in Chapter 3. At this time, the authors of this report feel that the results presented here represent the "best available" estimates of the future forecasts.

The report is organized in eight chapters and six appendices. Chapter 2 deals with the geologic setting of Nicaragua in general and Managua in particular. In this chapter, the geologic hazards and their implications are pointed out. Chapter 3 gives the discussion on available data. This chapter should be carefully read because it points out, in detail, the shortcomings of the available seismic data and how those shortcomings are treated in the present work. Chapter 4 develop: the future forecasting models based on past data, and presents isoacceleration maps for the country in general and selected cities in particular. In Chapter 5, the concept of seismic zoning is presented.

Charts relating risk level, economic life of structures, return period and the corresponding loading levels are presented in that chapter. Chapter 6 deals with future damage potential prediction and presents some thoughts on insurance risk. Chapter 7 gives the relationship between seismic zoning, group and use of structures and the needed design provisions. Chapter 7 should be viewed as an introduction to part II of the current study in which further design provision development will be presented. Chapter 8 gives summary and conclusion for part I of the research project and introduces to the reader part II of the study.

In reading this report, a casual reader can start with Chapter 4 and see the forecasting on future seismic loading. A planner can start with Chapter 5 to see the seismic zoning of the country. A structural engineer should read Chapters 4, 5, 6, and 7. In conclusion, it should be emphasized that this is a report on seismic risk analysis. As the name implies, there are many uncertainties and there is always a chance that nature will have the last say.

#### CHAPTER II

#### REGIONAL GEOLOGIC SETTING

#### Relation to Plate Tectonics

Nicaragua lies on the Circumpacific "Ring of Fire" which dominates the tectonics of the Pacific Ocean region. The city of Managua lies on the western edge of the Caribbean Plate. In the parlance of the new global plate tectonics, the Caribbean Plate is apparently being underridden by both the Cocos Plate, to the west, and the Atlantic Plate, to the east. Volcanic arcs and grabens, or long, linear depressions in the earth's crust, are characteristic of the intersection of many plates. Managua lies within such a graben, the Nicaragua Depression, and also within a volcanic arc.

Another characteristic of plate intersections are ocean trenches. In this case, such a trench is the Middle America Trench, which marks the depression of the Cocos Plate below the Caribbean Plate. The trench is 4-5 km deep, extends west of the Central American Coast from Mexico to Costa Rica, and runs sub-parallel to the arc-shaped chain of andesitic stratovolcanoes.

Marking the descent of the Cocos Plate is a zone of friction, generally termed the Benioff Zone. This zone is marked by numerous earthquakes, extending several hundred kilometers into the Earth's interior. The 1972 earthquakes, however, did not occur along this zone, as they were much shallower. They were probably related to

relatively shallow adjustment to accumulating crustal strain within the southwest part of the Caribbean Plate.

#### Geology of the Nicaragua Depression

The outstanding feature of the Pacific Coastal Region of Nicaragua is the Nicaragua Depression (also called the Nicaragua Graben, or Central Valley). Bounded on the northeast by a long, straight, en echelon fault, or the Boundary Fault, the Depression extends from the Gulf of Fonseca, to the north, to near Limon, Costa Rica, in the south (figures 2-1, 2-2, and 2-3). The western boundary is placed by some workers beneath the Pacific Ocean, by others along the Mateare Fault, a semi-continuous fault zone. Downfaulting, which began at the beginning of the Quaternary, about 1,000,000 years ago, has continued to the present.

The Boundary Fault, although at depth probably a normal (block above the fault moves relatively downward) fault, locally suggests right-lateral, or strike slip (opposite block moves laterally to the right) movement. It is locally buried by volcanic rocks. This fault is more regular than the Mateare; it is traceable along the entire length of the Depression. The graben floor is tilted away from the fault, suggesting that either normal movement is minor, or that it is less recent than on the Mateare Fault. In addition, much of the vertical movement could have been taken on several, sub-parallel, en echelon faults.

The Mateare Fault is less clearly expressed in all places. Where prominent, it is a normal fault, displaying a scarp with a



Marrabios is a line of volcanoes, offset in the vicinity of Managua. The valley containing Lake Managua and Lake Nicaragua is called the Nicaragua Graben. The boundary fault of the graben bounds the Atlantic Figure 2-1.Sketch of part of Nicaragua showing the most conspicuous tectonic features. The Cordillera de side of the tectonically active area.

From Saint-Amand, 1973







Between Lago Nicaragua and the line of faults between the air-Figure 2-3-Local Faulting in the Managua Area. The boundary fault of the graben is some 40 miles to the port and Rio Tipitapa, extensive alluviation from the Masaya Complex may hide the surface expression of The Fractura de Nejapa is a line of explosion pits, craters, collapse structures and aberrant stream chan-Note that the fracture pattern strongly suggests a some faults. Data is not available to me at this time to delineate faults on the northside of Lago northeast. The Falla Mateare is a normal fault with some lateral movement of undetermined sense. rudely circular area of subsidence across the valley. Managua in the same detail as on the south side. nels arranged along an extensional zone. From Saint-Amand, 1973

maximum height of 1000 meters along the Sierras de Carazo. The uplift is recent, as evidenced by the slight erosion of the upland surface, despite easily eroded volcanic rocks and high rainfall. Matumoto and Latham calculate the total vertical movement along the western edge of the graben as 2.4 km by adding the thickness of accumulated sediments in the graben (1.4 km) to the vertical drop (scarp) (1 km). (See reference 11.)

The Depression contains a thick accumulation of alluvium, lake sediments, deeply weathered volcanic ash, and some volcanic flow deposits, aggregating, as stated, to a total thickness in excess of 1400 m. The basement rocks are unknown, being neither penetrated by wells nor ejected from volcanoes. The isolated hills of Tertiary volcanics are largely buried, although more exposed to the northeast. This suggests a thicker sedimentary accumulation to the southwest, giving further evidence of greater subsidence in this part of the graben.

#### Geology of Managua Region

The city of Managua sits atop a succession of volcanic rocks and sediments aggregating at least 1000 meters in thickness. The section is probably typical of the entire Nicaragua Depression, although specific units lense out and are replaced by other units elsewhere in the graben.

To a depth of at least 200 m, the section is a relatively homogeneous and predominantly volcanic sequence of lapilli-sized, angular scoria, or cinder deposits, with interbedded, thin ash deposits. These are derived either from Masaya Crater, 22 km distant,

or the line of volcanoes to the west. Firm and relatively welllithified (consolidated) volcanic mudflow deposits are also common. These are thick and firm enough to be used as building stones. The scoria is extremely porous, permeable, and features a low bulk density. It demonstrates good stability under static loads, and stands in nearvertical slopes if undisturbed, but is <u>not</u> stable under dynamic loading (see reference 14).

Some authors emphasize sedimentary rocks, especially lake sediments, in the sequence. A more exact determination of the nature of the rocks would aid in predictions of seismic wave propagation, especially the attenuation of the waves, in general, and the effect of the rocks on accelerations, in particular.

West of Managua, relatively dense lava flows and vent debris are associated with pyroclastics similar to those underlying the city. Less damage occurred here during the 1972 earthquake, but this is probably because of the greater distance from the earthquake epicenter (see reference 14).

#### Volcanism

The entire Nicaragua Depression is either an active or potentially active area. Managua lies atop volcanics and volcanically derived sediments that have been deposited in the recent geologic past. Masaya Crater, centered 22 km distant from Managua, has been active in historic times (see reference 12), and some of the volcanic deposits underlying the city have been traced to this same volcanoe. Managua lies within an apparent right-lateral offset of a line of volcanoes, the

Cordillera de los Marrabios. The reason for this offset is unclear.

#### Soils

The soils of Managua are, on the whole, relatively similar throughout the city (Figures 2-4, 2-5). They "consist mainly of volcanic deposits of cohesionless silts, sand and gravels ranging from loose to well-consolidated and having various degrees of cementation" (see reference 17). The soils occur in well-defined layers of from a few to several hundred centimeters thickness. However, thicknesses, as well as degree of compaction, are somewhat variable even at individual sites. The first "rock-like" material occurs at variable depths. It is called "cantera," or "volcanic sandstone," but in reality is a volcanic tuff agglomerate (see reference 17).

#### Water Levels

The water table is generally 10-30 m below the ground, and 19 m in the city center. Near Lago de Managua (Lake Managua) it reaches to within 3 m of the surface. For most of the city, it is too deep to be of significance in the design or location of foundations (see references 17, 14).

#### Faulting

The faults which pass through Managua are members of a system of faults which scar much of the Nicaragua Depression. The faults show some normal, or vertical movement. In general, faults in the western part of the city show movement down to the east, whereas faults to the east demonstrate the opposite. Thus, a shallow composite graben





Fig.2-4 Contour lines of depth of loose surface deposits (N < 10)



is being formed. Movement in the 1972 earthquake is in general agreement with older fault displacements.

One of the purposes of the geologic study was to describe and interpret the pattern of faulting within the city, as an aid to seismic zoning. The task is extremely difficult, however, because there is no agreement on the location of the faults in Managua. As many as 10 faults have been mapped (Figures 2-6, 2-7); at least 4 suffered offset in the 1972 earthquake (Figure 2-8). One other, the poorly defined Stadium Fault, was offset in the 1931 earthquake. Although we will address ourselves to some general remarks in relation to these faults, final discussions must wait until thorough trenching and mapping, currently underway, is completed and made available.

In conclusion, the Nicaragua Depression is a currently active downfaulted block, bounded on one side by an active fault, and on the other by a potentially active fault. The pile of sediments and volcanics underlying the Depression total more than 1000 m in thickness. Active volcanics cover part of its surface.

A few important points relating to seismic zoning follow:

(1) Each of the 10 "faults" is a zone, rather than a line of movement. Whether the "fault" has moved in the recent past is not of significance in Managua, as each zone of fracturing could suffer either more fracturing or actual offset in a future earthquake. Thus, fracture zones from the 1972 earthquake should be considered in the same light as faults where displacement actually occurred.

(2) The distance a structure should be placed from a known



From Calders, 1973 of Mexican geologists Figure 2-6 Map of Managua showing faults as located by the group



fault is open to considerable debate. It has been observed that faults tend to rupture repeatedly along nearly the same line, although many recent scarps are located within much wider fault zones, and in alluvium, the fault rupture could easily occur outward from the previously "recognized" breakage. It is our opinion that vital structures, such as hospitals, police and fire stations, etc., should be located at least 100 feet from any fault zone or individual rupture. In a major fault zone, such as the San Andreas Fault in California, movement can be expected to occur along the same trace as the previous movement, but in a region such as Managua, it is our opinion that this would not necessarily be the case.

(3) The type of material on which the structure rests, and the degree of saturation of the material, are extremely important. However, in the case of Managua, these parameters are relatively insignificant, because of the nearness of seismic activity. The only exceptions would be saturated fill and lake sediments. Structures built on these materials faired especially poorly in the 1972 earthquake.

(4) The definition of an "active" fault is not agreed upon. Many geologists use 40,000 years since the last movement as the criterion of "active." This, of course, is often difficult to determine. In addition, the valid argument that even 10,000 years, or less, is economically impractical when considering structures with an anticipated lifetime of less than 100 years. It is our opinion that strategically important and large, public structures should not be located over defined faults in the city of Managua, unless the most conservative

(40,000 years) definition of "active" is used. This would apply to the 10 faults and fracture zones discussed earlier, as well as possibly some buried faults. As a practical manner for the city of Managua, any faults that have <u>not</u> displaced the "White Pumice" unit are probably no longer active.

(5) It is unlikely that a better location for the city could easily be found within the Nicaragua Depression, as the graben is cut by numerous faults. On a random movement from the city, the chances for an earthquake would be equal or greater, and the chances for actual surface rupture would be less, the same, or greater. To find a lesser chance for rupture would require an exhaustive and time-consuming study, which would have to locate an almost fault-free site.

Each of the identified surface or near-surface "faults" within the city should be considered potentially active. As apparently only one fault ruptured in the 1931 earthquake, and at least 4 <u>other</u> faults moved in the 1972 earthquake, it is likely that still other faults could rupture in a future earthquake. From a geologic hazard point of view, where fault rupture and fault displacement are of main concern, critical facilities should not be built within 100 feet of the fault zone or individual rupture. Wallace (see reference 20) suggested one zoning scheme (fig. 2-8) based on strictly geologic hazard. For resistance to seismic vibrational loading, the following chapters will develop criteria for design and zoning requirements. It should be kept in mind that the location of rupture and fault zones within Managua is under study and the future zoning for such geologic hazards should incorporate results of that study.





earthquakes may occur in areas thought to be devoid of them because of a total lack of activity in the It must be realized that although an area may appear to be earthquake free for a long time that large Nonetheless, by picking the areas shown to be free of earthquakes for a protracted period, one The epicenters shown are from 1964 to 1970 as calculated boundary fault in Nicaragua and that one is deeper than 70 kms. The most active area lies offshore. by the U.S. Coast and Geodetic Survey. It is important to note that only one appears north of the Figure 2-9-Seismic Map of Part of Nicaragua. is indeed reducing the overall hazard. From Saint-Amand, 1973 area.

#### CHAPTER III

#### SEISMIC DATA BASE

#### Introduction

In Chapter 2, we discussed general geology of Nicaragua. We also discussed the geologic hazards that planners and builders should consider. One major informational parameter needed in any future planning of a facility in a seismic region is the amount of shaking or vibration that this facility will have to undergo during its economic life. In other words, one has to consider the future seismic dynamic loads for which the structures should be designed. Such information helps in seismic zoning of a region. There are various parameters used in the literature to represent the seismic loading. They are:

- (1) Richter Magnitude (M);
- (2) Modified Mercalli Intensity (MMI);
- (3) Peak ground acceleration (PGA);
- (4) Spectral Intensity;
- (5) Root Mean Square (RMS) acceleration, velocity, or displacement.

However, the most commonly used loading parameters are the Richter Magnitude, the Modified Mercalli Intensity, and the peak ground acceleration. As for the Richter Magnitude, the loading information is in the form of overall energy release of a seismic event. It does not

explicitly represent a loading at a given site some distance away from the source of energy release.

The Modified Mercalli Intensity scale represents the effect of an earthquake at a given site. It is a subjective scale of damage at a site. Thus, for a given seismic event in a region, various sites experience different intensities. In general, intensity decreases with distance. Appendix 2 gives the MM Intensity scale. Future forecasting of MM intensities for a given region help in determining the future damage potential and hence insurance risk. However, for structural engineering and design purposes, this parameter is not as useful as the peak ground acceleration. The most commonly and conveniently used parameter is the peak ground acceleration. In this work, peak ground acceleration (PGA) will be used to represent the seismic load level. For frequency content, normalized design spectra will be developed for different parts of the country. (See Chapter 7.)

To estimate probabilistically these peak ground acceleration levels throughout the country in some time frame, we need to get information regarding past seismic events. In particular, we need to get the following information:

- (1) Epicentral locations of past seismic events;
- (2) Time of occurrence;
- (3) Magnitude associated with each occurrence;
- (4) Depth of hypocenter;
- (5) Acceleration records associated with the above occurrences at different sites;
- (6) If possible, information on how energy (or peak ground
acceleration) attenuates from source of energy release to any site away from the source.

As for items 5 and 6 above, not much data is available for Central America in general and Nicaragua in particular. We will discuss these two items in detail in the next two chapters. As for the information on epicentral locations, time of occurrence, magnitude of occurrence and depth of hypocenter, the basic data were obtained from the National Earthquake Information Center, U.S. Department of Commerce, National Oceanic & Atmospheric Agency, National Earthquake Information Center, Boulder. The information obtained from this source contained all events from 1900 to 1973. Another source that was consulted for earthquakes before 1900 was the "Catalog of Nicaraguan Earthquakes 1520-1973" by David J. Leeds of Dame<sup>S</sup> & Moore, Los Angeles. The list of references at the end of this report gives other sources used to develop the total data base (see references 21, 22, 23, and 24).

Before we go into the discussion on the use and analysis of available data, certain observations should be made regarding the type, amount and reliability of the data base used for the current research.

All the data sources have one common shortcoming. That is, the frequency of recorded earthquakes increases with time. It is very realistic to assume that the seismic phenomenon in Nicaragua has not drastically changed in the past few hundred years and that it will remain the same for a few hundred years more. However, the number of seismic events recorded in general increases with each year. Also, only major events were recorded in the 16th, 17th, and 18th centuries.

This gives a bias to the data because in recent years, all events, big and small, are recorded, whereas old records only show large events. This nonhomogeneity in data reliability is a "fact of life" and we can not get away from it. Another problem is in the events which were not recorded as to time, place and magnitude, but only conveyed through church records or through word-of-mouth. How can one incorporate such information quantitatively?

Fortunately, for well-codified methods and structures, the structural performance and consequences in general follow the pattern shown in figure 3-1. The horizontal axis represents structural performance such as, say, deformation, whereas the vertical axis represents the consequences of those performances. The performance can be tied in with the seismic demand (or loading). Thus, a 10 percent variation about the mean demand value D can be represented by  $D_1$  and  $\mathrm{D}_2.$  Corresponding to this variation, the performance variations could be 10% about the mean performance P, represented by  $P_1$  and  $P_2$ . However, this 10 percent variation in loading estimate may result in only a slight variation on the consequence side. This ability of a well designed structure based on a well designed code helps in overcoming the uncertainty in the loading parameter such as peak ground acceleration. Further discussion on this aspect will be presented in Chapter 7 of this report. Also, inclusion or exclusion of some unrecorded historical events in the past does not change the estimated values of the loading parameters substantially, because the estimates are based on a large collection of data to begin with.

Due to above mentioned considerations, the authors of this



report feel that the seismic loading estimates, based on probabilistic analysis, are realistic and representative of the future seismic loadings.

#### Data Analysis

As mentioned previously, two main sources of information were considered. The NEIC-NOAA data file covering the period from January 1900 to August 1973 constituted the primary source of information and is referred to hereafter as Source 1. The Catalogue of Nicaraguan Earthquakes, 1520-1973, by David J. Leeds, is referred to as Source 2. It was used to obtain:

. data about earthquakes associated with volcanic activity along the Cordillera de los Marrabios (1850-1973);

. data about earthquakes not reported in the NEIC-NOAA file (1900-1973);

. additional information about events incompletely documented in the NEIC-NOAA file (1900-1973).

The time period of data gathering is thus 73 years for the whole country and 123 years for earthquakes associated with volcanic activity along the Cordillera de los Marrabios.

In spite of the complementarity of the two sources, a large number of events remained insufficiently documented to be used as such in the analysis. Rather than disregarding these events, the missing information was generated using a Monte Carlo Process supplemented by judgment. It is felt that the total analysis benefits more than suffers from such an additional input.

The following remarks are valid for both sources:

- . No critical study was made regarding the validity of the information and the reliability of the data.
- . Whenever information as basic as epicentral location or magnitude were missing, the event was disregarded.
- . Events with Richter Magnitude smaller than 3.0 were not considered.

#### Source 1

When complete, the information contained in this source includes for a given event: time of occurrence, epicentral location (degree), depth of hypocenter (km), and magnitude. The magnitude is in terms of one of the following:

- (1) CGS  $M_{\rm b}$  average (body wave magnitude)
- (2) CGS  $M_{c}$  average (surface wave magnitude)
- (3) Richter Magnitude M.

The acceleration attenuation relationships used in Chapter 4 are based on the Richter Magnitude. Hence, when missing, this information was generated from  $M_b$  or  $M_s$ . It is known that for a given part of the world, the Richter Magnitude and CGS  $M_b$  are linearly related such that

$$M = a + b M_{b}$$
 3-1

In order to determine the coefficients a and b, a regression analysis was run for all the earthquakes of which M and  $M_b$  were known using the total data of Central America. The Richter Magnitude was then obtained by substituting the value of  $M_b$  in equation 3-1.

Whenever data on depth of hypocenter were not available, a depth was assigned, as will be explained later in the chapter.

From Source 1, 419 events contained complete information; they are plotted in Chart 1 and shown as a function of depth in Table 3-1.

Source 2

When complete, the information contained in this source includes for a given event: time of occurrence, epicenter location (degree), depth, Richter Magnitude and sometimes a short description of the seismic event. The depth is either expressed in km or by a letter symbol N (0 - 60 km) or I (70 - 200 km). In the same way, the Richter Magnitude is either expressed by its numerical value or by a letter symbol, as follows:

 $B - 7 \le M \le 7.7$   $C - 6 \le M \le 6.9$   $D - 5.3 \le M \le 5.9$   $E - M \le 5.3$ 

Through a simulation process, all the events taken from Source 2 were assigned a numerical Richter Magnitude from letter magnitude.

Hence, an additional 196 events were obtained (including events from Source 1 with partial information), distributed as follows:

- 43 events associated with volcanic activity and with shallow hypocenters N (0 60 km).
- 40 events with shallow hypocenters N (0 60 km).
- 3 events with deep hypocenters I (70 200 km).
- 63 events with no data on depth.
- 47 events with numerical data on depth (km).

# Table 3-1

# Data from Source 1, Sorted According to Depth of Hypocenter

Number of Earthquakes	Depth Range (kms.)
8	0- 9
9	10- 19
12	20- 29
159	30- 39
35	40- 49
32	50- 59
34	60- 69
32	70- 79
18	80- 89
14	90- 99
13	100-109
9	110-119
3	120-129
7	130-139
3	140-149
7	150-159
3	160-169
6	170-179
3	180-189
5	190-199
9	200-215

# (Total Events 421)

The 466 earthquakes with complete data (419 from Source 1 and 47 from Source 2), were plotted as a function of depth. Using those plots together with epicenter location, magnitude value, partial information on depth and judgment, the 156 remaining events were assigned appropriate depths. This led to a total data of 615 events ranging from 5 to 215 km in depth and from 3.0 to 7.7 in magnitude. Appendix 3 gives the listing of those earthquakes; in Chart 2-7 they are plotted as a function of depth.

From these charts, the general seismic pattern of Nicaragua can be divided into the following regions:

- (1) The Benioff Zone dipping North East toward the Nicaraguan coast. This zone is marked by numerous earthquakes covering the whole range of magnitude (larger as depth increases) and extending several hundred kilometers into the earth's interior. The shallow earthquakes (± 30 km) due to this source are from 30 to 100 km away from the coast. As the epicenters get closer to the coast, the hypocenters get deeper. Hence, under Managua the hypocenters of earthquakes situated on the Benioff Zone are very deep (100 200 km).
- (2) In contrast, for the local seismic sources, such as the ones identified under Managua (Figures 2-3 and 2-6, Chapter 2), the hypocenters are shallow (5 - 30 km). In magnitude scale, these sources do not generate major earthquakes such as those on the Benioff Zone. However, due to their shallowness and nearness to populated areas, they have caused extensive damage and loss of life in past history. The

December 23, 1972 event was due to the local source under Managua. Appendix I gives details regarding this source of seismic activity.

- (3) The line of volcanoes from Northwest to Southeast (Cordillera de los Marrabios) represents sources of future seismic activities. Volcanic eruptions are seldom by themselves sources of seismic activity, and in the past various earthquakes have been recorded preceding volcanic eruptions. For this reason earthquakes "associated" with volcanic activity were treated in the model (Chapter 4) as shallow tectonic earthquakes.
- (4) Two shallow (± 30 km) seismic regions, one more or less co-inciding with the Pacific seashore between Lake Managua and the Costa Rica border, the other one in the Gulf of Fonseca.
  (5) The Atlantic coast of low seismicity.

## Source Location and Seismicity

Based on the above observations, the total number of events was divided into 13 seismic sources: Ten of these are line sources and three are area sources. Table 3-2 shows these 13 sources, the number of events and the depth range of each source.

Appendix 3 gives a listing of the earthquakes included in each source. Line sources were located by fitting a line through the data using regression analysis. For area sources, the centroid was obtained from the data and the radius taken as the distance from the centroid to the most distant epicenter in the source.

The depth of each source was computed as an average hypocentral

# Table 3-2

N Source		Number of Events	Name of Source	Depth (kms.)	
1	Line	159	Benioff	5 - 39	
2	Line	186	Benioff & Costa Rica	40 - 79	
3	Line	72	Benioff	80 - 109	
4	Line	31	Benioff	110 - 159	
5	Line	41	Benioff	160 - 215	
6	Line	23	"Costa Rica"	5 - 39	
7	Line	11	Atlantic	All Depths	
8	Line	12	Pacific Coast Line	33	
9	Line	57	Line of Volcanoes	33	
10	Line	57	Line of Volcanoes	33	
11	Area	5	Managua Area	5	
12	Area	8	Gulf of Fonseca	33	
13	Area	10	Costa Rica Area	80 - 109	

Seismic Sources for Nicaragua

depth of all the earthquakes included in the source. Earthquakes with no or limited depth information were not included in this averaging process. However, they were considered in determining the location and the seismicity of the source. Charts 2 through 7 show the source locations and depths. The recurrence relationship for each individual source was obtained by fitting a regression line of the following form:

$$\ln_{e} N(M) = \alpha + \beta M \qquad 3-2$$

N(M) = Number of events above magnitude M

M = Richter Magnitude

 $\alpha$  and  $\beta$  are regression constants.

 $\alpha$  is a measure of the number of events above magnitude 0 for a given source and  $\beta$  is a measure of the seismic severity for a given source. The larger the negative value of  $\beta$ , the smaller the seismic severity. For many sources, a single regression line gave erroneous results because the interpolation of the line beyond the range of data indicated unreasonably high magnitude occurrences. For such cases, two regression lines were fitted to the data, and a geologically consistent upper magnitude value was used for cutoff. (See Figures 3-2 through 3-13.) Table 3-3 gives a summary of  $\alpha'$  and  $\beta$  values for each source and the magnitude cutoff point corresponding to  $\ln N(M) = 0.1$ .

Let N'(M) = 
$$\frac{N(M)}{AT}$$
 for area source  
=  $\frac{N(M)}{LT}$  for line source

where

L = length of the line source







ЧO NUMBER CUMULATIVE





CUMULATIVE NUMBER OF OCCURENCES



.

-



Ъ CUMULATIVE NUMBER











A = Area of the area source

N'(M) = Normalized mean number of events above magnitude M for unit-time (1 year) and unit-area or unit length.

Then

$$\ln N'(M) = \alpha' + \beta M \qquad 3-4$$

where  $\alpha' = \alpha - \ln(AT)$  for area source =  $\alpha - \ln(LT)$  for line source.

Table 3-3 shows values of  $\alpha'$ ,  $\beta$  and the upper cutoff magnitude as described previously. The table gives values of  $\alpha'$  and  $\beta$  in terms of degrees of latitude and longitude. These relationships will be used to develop the forecasting model in Chapter 4.

#### Limitations

In conclusion, it can be said that there are limitations to the use of available data for the Nicaragua region. These limitations are given below.

- 24% of the data contain incomplete information regarding the depth. This information was added from either judgment or by correlating the event with other data where the depth information was available.
- 32% of the data have magnitude defined by a symbol.
   Numerical value of magnitude for these cases was obtained through simulation.

Source	α1'	β <sub>1</sub>	α <sub>2</sub> '	β2	Cutoff
1.	2.58	-1.09	24.00	-4.55	6.8
2.	1.49	-0.74	62,80	-9.21	7.8
3.	-0.38	-0.42	3.60	-5.75	7.7
4.	-0.39	-0.65	26.50	-4.55	7.5
5.	0.33	-0.72	36.20	-5.27	8.5
6	0.42	-0.77	46.50	-7.82	6.9
7.	-2.13	-0.33	18.60	-3.53	7.5
8.	-0.89	-0.37	43.10	-7.57	6.8
9.	-4.71	-0.24	34.20	-5.43	7.8
10.	-4.71	-0.24	34.20	-5.43	7.8
11.	3.17	-0.74	79.15	-12.4	6.7
12.	0.14	-0.07	79.90	-13.04	6.5
13.	-0.66	-0.59	34.60	- 5.54	7.5

Table 3-3

- 3. The reliability of the total data base was not evaluated.
  - Some information was from church and historical records.
  - (ii) Distribution of information over the country is biased. Populated areas have better records than sparsely populated areas. (No population → no records.)
  - (iii) Epicentral location could be in error due to lack of a good grid of recording system. It is hoped that the recording network presently installed by the Nicaraguan authorities, the U.S.G.S. and private organizations in Nicaragua will help in increasing the understanding of attenuation relationships and the accuracy of epicentral locations in the future. Such calibration may help in relocating the past events. (See reference 4 by Dewey.)

It is felt that the work done by Dewey (see reference 4) and others in calibrating the epicentral locations through the ESSO refinery record does not have sufficient experimental evidence as yet. Hence, no hypocenters are moved based on Dewey's work. (One exception is the 1931 earthquake-stadium fault.) It should be emphasized that as additional data become available to give more reliable information on epicentral locations, the methodology presented in this research project will be able to modify the results accordingly.

## CHAPTER IV

# PROBABILISTIC SEISMIC LOADING -- ISO-ACCELERATION MAPPING OF NICARAGUA

# Introduction

In Chapter 3, we discussed the data base, the limitations of the available information and the approximations made in using the seismic data of Nicaragua. We also presented the recurrence relationship associated with all the seismic sources for the region. These recurrence relationships give us the mean number of events of magnitude greater than M due to a given source and time period. If the mean number of events above a specified magnitude M is normalized with respect to time and length of the source for line source or area of the source for area source, we get the normalized recurrence relationship. This normalized relationship gives the quantitative statistical seismic recurrence formula for each source. This, however, represents the past seismic history of the region. In developing understanding on the seismic risk for Nicaragua, we need the future forecasting of events. Based on the past data, the future forecasting can be done by means of two widely used statistical models. These models are:

(1) Poisson Model.

(2) Markov Model.

The Poisson Model assumes that major seismic events are

spatially and temporally independent. This has been observed to be true for the southern California region. (See reference 25.) The Markov Model assumes memory in two successive seismic events. Thus, occurrence or non-occurrence of an earthquake this year effects the occurrence or non-occurrence of an event next year. Even though this model conforms with the so-called elastic rebound theory, it has been observed that for events with interarrival times of more than 10 years, the Markov Model gives similar results to the Poisson Model. References 26 and 27 are two good examples of using Poisson and Markov Chain Models. In this study, the Poisson Model is used because of its simplicity, its widespread use in literature, and because the results it gives are very similar to results arising from more complex models such as the Markov Chain Model.

#### Poisson Model of Seismic Occurrences

As mentioned in the previous paragraph, earthquake occurrences can be modeled using the Poisson probability law. For earthquake events to follow the Poisson Model, the following assumptions must be valid:

- (1) Earthquakes are spatially independent;
- (2) Earthquakes are temporally independent;
- (3) Probability that two seismic events will take place at the same place and at the same instant of time approaches zero.

These assumptions are necessary for the formulation of the Poisson Model. The first assumption implies that occurrence or nonoccurrence

of a seismic event at one site does not affect the occurrence or nonoccurrence of another seismic event at some other site. The second assumption implies that the seismic events do not have memory in time. A Markovian assumption of one-step memory in time may be a better assumption, but as mentioned previously, this assumption for large events does not introduce major errors (see reference 25). The third assumption implies that for a small time interval,  $\Delta t$ , more than one seismic event cannot occur. This is a very realistic and good assumption which fits the physical phenomenon.

In its most general form, the Poisson law can be written as

$$P_{n}(t) = \frac{e^{-\lambda t} (\lambda t)^{n}}{n!} \qquad 4-1$$

where  $P_n(t)$  = Probability of having n events in time period t.

n = Number of events.

 $\lambda$  = Mean rate of occurrence per unit of time.

In Chapter 3, we have seen how, using recurrence relationships, we can obtain the mean number of occurrences above Magnitude M for a given source. This relationship in its general form can be written as

$$N(M) = \phi(M, A, T)$$
 4-2

where N(M) = Number of occurrences above Richter Magnitude M.

M = Richter Magnitude.

- A = Source characteristic (area for area source, length
   for line source).
- T = Time period of data base.

As mentioned in Chapter 3, a log-linear recurrence relationship is assumed for all sources. Also, for each source, the relationship is bi-linear (two lines described by  $\alpha_1$ ,  $\beta_1$  and  $\alpha_2$ ,  $\beta_2$ ). (See Table 3-3 of Chapter 3.) Thus, for a given source, the two lines describing the recurrence relationship are given by:

$$\ln N'(M) = \alpha_1' + \beta_1 M \qquad 0 \le M \le M_1$$

$$\ln N'(M) = \alpha_2' + \beta_2 M \qquad M_1 \le M \le M_2$$

$$4-3$$

Table 3-3, Chapter 3).

Thus, depending on the source and the value of M, the mean number of events above Magnitude M for a unit area for area source, a unitlength for line source, and a unit-time is given by:

$$N'(M) = \exp \left[\alpha_{i}' + \beta_{i} M\right] \qquad 4-4$$

Thus, from equation 4-1

$$P_{n}(t) = \frac{\exp \left[-\exp \left(\alpha_{i}' + \beta_{i} M\right)t\right] \left[\exp \left(\alpha_{i}' + \beta_{i} M\right)t\right]^{n}}{n!} \qquad 4-5$$

Note that in equation 4.5 above,  $\lambda$  is replaced by N'(M). Equation 4-5 gives the probability of observing n events above magnitude M in time period t, based on the seismic history of a given source.

### Source Mechanisms

Three different types of sources can be used to represent the scismicity of any location. They are point, line, and area sources. All three source mechanisms will be discussed for generality and completeness, although only the line and area sources were considered for the Nicaragua region.

## a. Point Source

For this type of source, all occurrences (past and future) take place at one point. The recurrence relationship can be normalized with respect to time T as follows:

$$N'(M) = \frac{N(M)}{T} \qquad 4-6$$

and  $\ln N'(M) = \alpha' + \beta M - - 4^{-3}$  repeated.

Substituting the value of N'(M) in the Poisson law of equation 4-1, we get:

$$P_{n} (M > m, t) = \frac{\exp [-N'(m) t] [N'(m) t]^{11}}{n!}$$
 4-7

where the notation

 $P_n$  (M > m, t) gives the probability that there will be n events of Richter magnitude greater than m in time period t.

For engineering purposes, we are usually interested in determining the probability of at least one event greater than m in time period t. This probability is given by

P (at least one event of Richter Magnitude M > m in time
period t)

= 1 - P (no earthquake of magnitude M > m in time t). Hence, from equation 4-7,

P (at least one event of Magnitude M > m in time t)

$$= 1 - \exp[-N'(m)t].$$
 4-8

b. Line Source

For a line source, it is assumed that epicenters lie along a linear fault. For a line source of length L (fault length L) and the data base for a time period T, the recurrence relationship of Chapter 3 and equation 3-2 can be normalized to:

N'(M) = 
$$\frac{N(M)}{LT}$$
 --- Equation 3-3 repeated

and

$$\ln N'(M) = \alpha' + \beta M - -- Equation 3-4$$
 repeated

Thus, the Poisson law of equation 4-1 can be written as

 $P_n(M \ge m, t) = \frac{\exp[-N'(m)t][N'(m)t]^n}{n!}$ 

where N'(m) for line source is normalized with respect to length of the fault and time period T. Again, for determining the probability of at least one event of magnitude greater than m for a future time period t is given by,

> P (at least one earthquake of M > m in time t) =  $1 - P_0 (M > m, t)$

$$= 1 - \exp [-N'(m)t]$$

which is a similar expression to equation 4-8 except that the interpretation of N'(m) is different.

#### c. Area Source

When the past earthquake epicenters do not lie on a line (i.e. along a given fault line) but are scattered over a region, the seismic source should be considered as an area source. The area source could be a full circle or any section of a circle where epicenters are scattered. In this case, the recurrence relationship is normalized with respect to area A and the time of data base T.

N'(M) = 
$$\frac{N(M)}{AT}$$
 --- Eq. 3-3 repeated

and  $\ln N'(M) = \alpha' + \beta M - - - Eq. 3-4$  repeated,

Thus, the probability of at least one event due to this area source above magnitude m in time period t is given by:

P (at least one M > m in time t) = 1 - exp [-N'(m)t]. Again, this expression is similar to equation 4 8 for a point source, and also for a line source. However, in each case the normalized N'(M) has a different interpretation.

## Peak Ground Acceleration at a Site

As we mentioned in Chapter 3, the most commonly used parameter to describe the seismic loading at a given site is the peak ground acceleration (PGA, usually denoted by A). In the previous section, we obtained the probability of exceeding a magnitude level in time t by using a Poisson odel. (The probability distribution represented by Eq. 4 8 gives information only on Richter magnitude.) For design purposes, we wish to know the loading at a site, away from the epicenter. Modified Mercalli Intensity (MMI, see Appendix 2) peak ground acceleration, spectral acceleration, and several other parameters have been used to represent the loading at a given site. To obtain probabilistic information about peak ground acceleration at a site, we have to know the following parameters:

- Probabilistic information on Richter Magnitude for a source as a function of future time t.
- 2. Distance of the site from the source.
- Attenuation of peak ground acceleration from source to site.

We have already determined the first parameter in the previous section. Various attenuation formulae are available which give relationship between the Richter Magnitude M, the epicentral distance or the hypocentral distance, and the peak ground acceleration. The most commonly used relationship is of the form given by

$$A = \frac{b_1 \exp(b_2 M)}{(R_p + b_4)^{b_3}} 4_{\tau} S$$

where

A = Peak Ground Acceleration (PGA) in  $cm/sec^2$ .

R<sub>h</sub> = Hypocentral distance from source to site (in kms.). M = Richter Magnitude.

 $b_1$ ,  $b_2$ ,  $b_3$ , and  $b_4$  are constants depending on the region.

Since there is not a close grid of seismographs in Nicaragua, not much information is available on attenuation of accelerations in that part of the world. However, various values of  $b_1$ ,  $b_2$ ,  $b_3$  and  $b_4$ are available for other parts of the world. One such relationship that has been adopted for this work is the one developed by Esteva. The attenuation constants are given by

$$b_1 = 5,000;$$
  $b_3 = 2.0;$   
 $b_2 = 0.8;$   $b_4 = 40$ 

Thus, the attenuation relationship becomes

$$A = \frac{5,000 \exp (0.8 M)}{(R_{h} + 40)^{2}}$$
 4-10

Figure 4-1 shows the behavior of Eq. 4-10 for different Richter magnitudes and hypocentral distances. This equation was correlated with the ESSO Refinery data for the 1972 December earthquake and also with the aftershocks. The correlation of the curve of Eq. 4-10 with the data is quite reasonable; consequently, the attenuation relationship given by Eq. 4-10 is used in this study. It should be pointed out that the installation of many new instruments will help in calibrating the attenuation relationship for Nicaragua in the future. When that is done, the results presented in this study can be readily modified.

We have seen that three types of seismic sources are possible. Due to each of these seismic sources, the peak ground acceleration at a site in a probabilistic sense can be determined.


## a. Point Source

For a point source shown in Figure 4-2, we can derive the following expressions:

> P (M > m, t) = Probability of at least one event greater thanm in time t.= 1 - exp [-N'(m)t]. $but N'(M) = exp [<math>\alpha' + \beta M$ ].

Thus,

$$P(M > m, t) = 1 - \exp [-\exp (\alpha' + \beta m)t]$$
 4-11

To determine the probability distribution on peak ground acceleration A, we have

$$P [A > a] = P \left[ \frac{b_1 \exp(b_2 M)}{(R_h + b_4)^{b_3}} > a \right]$$
  
= P [M > 1n { $\left\{ \frac{a}{b_1} (R_h + b_4)^{b_3} \right\}^{\frac{1}{b_2}}$  4-12

Using equation 4-11 in 4-12, we get

$$P [A > a] = 1 - \exp \{-e^{\alpha'}(\frac{a}{b_1}), (R_h + b_4), t\}$$
 4-13

Denoting 
$$\gamma = e^{\alpha'}$$
  
 $\delta = \beta/b_2$   
and  $\rho = \frac{\beta}{\frac{b_3}{b_2}} = \delta b_3$ 



we get

$$P[A > a] = 1 - \exp \{-\gamma (\frac{a}{b_1})^{\delta} (R_h + b_4)^{\rho} t\}$$
 4-14

### b. Line Source

Most of the earthquake epicenters around the world are generally located around the major fault systems. Thus, the usual case of epicenters falling along a line gives rise to the so-called line source. The line source can be divided into  $\kappa$  small segments of length dl. Each one of these segments can be treated as a point source. Summing the effects of all such segments, as dl  $\rightarrow$  o, gives the probability of a peak ground acceleration A exceeding a value a due to a fault line source of length L.

For a point source, we have seen that

$$P [A > a] = 1 - \exp \{-\gamma \left(\frac{a}{b_{1}}^{\delta} (R_{h} + b_{4})^{\rho} t\}$$
  
then  $P [A < a] = \exp \{-\gamma \left(\frac{a}{b_{1}}^{\delta} (R_{h} + b_{4})^{\rho} t\}$ .

Thus, for an element i of the line source, we have

$$P_{i} [A < a] = \exp \left\{-\gamma \left(\frac{a}{b_{1}}\right)^{\delta} \left(R_{h} + b_{4}^{\rho}\right)^{\delta} d\ell_{i} t\right\}$$

From Fig. 4-3,

$$R_{h} = (d^{2} + \ell^{2} + h^{2})^{1/2}$$

where  $\ell$  is the distance of element under consideration from the

perpendicular on the line source.

Thus,  

$$P_{i} [A < a] = \exp \{-\gamma(\frac{a}{b_{1}}) [(d^{2} + \ell_{j}^{2} + h^{2})^{1/2} + b_{4}]^{\rho} d\ell_{i} t \}$$

From the basic assumption of spatial independence of occurrences, we get

$$P [A < a] = \lim_{\substack{i=1 \\ i < a}} \prod_{i=1}^{\kappa} P_i [A < a].$$

$$d_{\substack{i \neq 0 \\ i \\ \kappa \neq \infty}}$$

$$= \lim_{\substack{d\ell_{i} \to 0 \\ \kappa \to \infty}} \exp \{-\gamma (\frac{a}{b_{1}}) \sum_{i=1}^{\delta} [(d^{2} + \ell_{i}^{2} + h^{2})^{1/2} + b_{4}]^{\rho} d\ell_{i}t\}$$

$$\leq a_{1} = \exp \{(-\gamma (\frac{a}{b_{1}}) t - \ell_{i}^{2} + h^{2})^{1/2} + b_{i}^{2} + b_{i}^{2} + h^{2})^{1/2} + b_{i}^{2} +$$

$$P[A < a] = \exp \{(-\gamma(\frac{a}{b_1})^{\circ} t \int_{l_1}^{2} [(d^2 + l^2 + h^2)^{1/2} + b_4]^{\rho} dl\}$$
 4-15

Alternatively,

$$P[A > a] = 1 - \exp\{-\gamma(\frac{a}{b_1})^{\delta} t \int_{\ell_1}^{\ell_2} [(d^2 + \ell^2 + h^2)^{1/2} + b_4]^{\rho} d\ell\} - 4 - 16$$

Expressions 4-15 and 4-16 provide the probabilities of peak ground acceleration A due to a line source located some distance away and whose seismicity is available in terms of  $\alpha'$  and  $\beta$  and also for which the attenuation relationship of the form of Eq. 4-9 is available.

# c. Area Source

Peak ground acceleration due to an area source at a site can be obtained in a manner similar to that for line source. In many parts of the world, including Nicaragua, there are regions where the epicenters are not only located along a line but are scattered all over the region. This may be due to the existence of numerous faults crisscrossing the region or due to errors in estimating epicentral locations. In any case, there are places where point or line sources may not fit the scatter of epicentral locations. For such cases, area source should be used to determine probabilistic loadings at a site. Figure 4-4 shows schematically the area source geometry.

Consider an elemental area  $dA_i = R_i dR_i d\Theta_i$ . With this elemental area as a source, the probability that the Richter Magnitude M will be less than m in time t is given by

$$P_{i} [M \le m, t] = \exp [-N'(m) dA_{i}t]$$
$$= \exp [-\exp (\alpha' + \beta m) tR_{i}dR_{i}d\Theta_{i}]$$

or

$$P_{i}[A < a,t] = \exp \left[-e^{\alpha'} \left(\frac{a}{b_{1}}\right)^{\beta/b_{2}} \left(\sqrt{R_{i}^{2} + h^{2}} + b_{4}\right)^{\beta/b_{3}} tR_{i}dR_{i}d\Theta_{i}\right]$$

Summing the effect of all elemental areas, we get

$$P [A < a, t] = \lim_{i \to 0} P_i (A < a, t)$$
$$\frac{dR_i \rightarrow 0}{d\Theta_i \rightarrow 0}$$

Hence,



$$P [A < a, t] = \exp \{-e^{+\alpha'} (\frac{a}{b_1})^{\beta/b_2} t \int_{0}^{\Theta} d\Theta \int_{R_1}^{R_2} (\sqrt{R^2 + h^2} + b_4)^{\frac{\beta b_3}{b_2}} RdR\}$$

$$= \exp \{-e^{\alpha'} (\frac{a}{b_1}) \stackrel{\beta/b_2}{=} t \bigoplus_{R_1}^{R_2} (\sqrt{R^2 + h^2} + b_4) \stackrel{\beta/b_3}{=} RdR\}$$

Let 
$$\gamma = e^{\dot{\alpha}'}$$
  
 $\delta = \beta/b_2$   
 $\rho = \frac{\beta b_3}{b_2}$  as before

and

$$R_h = \sqrt{R^2 + h^2}$$

Then  

$$P [A < a, t] = \exp \{-\gamma(\frac{a}{b_1})^{\delta} t\Theta \int_{R_1}^{R_2} (R_h + b_4)^{\rho} RdR \} 4.17$$

and

P [A > a, t] = 1 - exp { - 
$$\gamma \left(\frac{a}{b_1}\right)^{\delta} + t \Theta \int_{R_1}^{R_2} (R_h + b_4)^{\rho} RdR } 4.18$$

Equations 4-17 and 4-18 provide the probability distribution of peak ground acceleration A at a site due to a generalized area source shown in Figure 4-4.

In general, a site is usually surrounded by any or all of the

above three sources discussed in this section. The probabilistic loading due to such a case can be obtained by the following expression.

Let there be NP point sources

NL line sources

NA area sources

The probability distribution of peak ground acceleration at a site is then given by



In equation 4-19, summation over i is for all point sources, that over j is for all line sources, and over k is for all area sources.

As we have seen in Chapter 3, there are ten line sources and three area sources that we have formulated for the Nicaragua region, based on past data. Any part of the country is affected by these sources, depending upon the proximity of the site to the source location.

## Iso-Acceleration Maps for Nicaragua

Equation 4-19 can be used to determine the probability distribution function of peak ground acceleration as a function of time and space. For example, at a given site, the probability of A > a increases with time. In other words, the longer the "exposure time," the greater the probability that the peak ground acceleration will exceed some level a. If we take the country as a whole and determine accelerations at different locations for a specific time period t (exposure time) and specific probability of A < a, we can obtain lines of equal accelerations. These lines of equal accelerations for a specific probability of non-exceedence and exposure time are called "Iso-Acceleration" lines. The maps representing iso-acceleration lines are called the iso-acceleration maps. These iso-acceleration maps are a form of seismic zoning maps. From these maps, for a given reliability or risk, one can determine the loading parameter (peak ground acceleration) for the seismic design of a structure. Detailed methodology describing the use of these maps for structural design will be presented in Chapter 7 of this report and also in the Part II report of the total study.

Charts 8 through 13 show the iso-acceleration maps for Nicaragua for a time period of 50 years and 20 years. For each time period the iso-acceleration maps are drawn for three risk levels. The risk level is defined as the probability that the peak ground acceleration will be exceeded during the exposure time (or economic lifetime) of the facility under consideration.

In addition to the iso-acceleration maps for the whole country,

the following cities are studied in detail.

1. Managua

2. Leon

- 3. Granada
- 4. Masaya
- 5. Chinandega
- 6. Matagalpa
- 7. Esteli
- 8. San Carlos
- 9. Rivas
- 10. Juigalpa
- 11. Bluefields.

Figures 4-5 through 4-26 show the cumulative distribution function of the peak ground acceleration for each of the cities. Again, results are presented for the exposure time of 20 years and 50 years. Thus, as an example, for Leon, there is approximately 53% chance that the peak ground acceleration in 20 years of exposure time will not exceed 0.20 g (see Figure 4-8). The corresponding value for a 50 year exposure time for the same city is 21%. Thus, the probability of exceeding 0.20 g in 20 years is 47%, whereas it goes up to 79% in 50 years. The implications of these probability values and the corresponding acceleration values will be discussed in Chapters 5, 6, and 7.

When we compare the cumulative distribution plots for different cities, we can see the relative seismicity in terms of peak ground acceleration for each city. In conclusion, it can be said that one method of representing seismic risk is by means of the iso-acceleration















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maps and the other method of representing seismic risk is by means of cumulative distribution function plots of Figures 4-5 through 4-26.

The engineering interpretation of these results will be presented in the next three chapters. It should also be pointed out that the iso-acceleration maps and any zoning based on such maps only represent macro characteristics. The macrozoning of the country should be modified with site-specific micro characteristics to microzone a given region. In that case, the local geotechnical and geological features (such as those discussed in Chapter 2) should be incorporated together with the macro characteristics presented in this chapter.

#### CHAPTER V

#### SEISMIC RISK ZONING

# Concept of Return Period and Acceleration Zone Graphs (AZG)

In deriving the probabilistic loading at a given site as a function of time, we have assumed that the forecasting process is Poisson. This process implies that the events are independent in time and space. Using this assumption and an appropriate attenuation relationship, we developed the iso-acceleration maps for the country. For a given city, we also developed the cumulative distribution function of the peak ground acceleration A, as mentioned in Chapter 4. Consider the cumulative distribution of peak ground acceleration in Managua for an exposure time of 20 years. (See Figure 4-5.)

Then

 $P_{20}$  (A > 0.20g) = 0.73

5-1

Equation 5-1 can be interpreted in the following way: "For Managua, there is a 73% chance that during the next 20 years, the peak ground acceleration of 0.20g will be exceeded at least once."

Thus, there is a 27% chance that for Managua, 0.20g peak ground acceleration will not be exceeded a single time. Hence,

P (Zero exceedence of 0.20g in 20 years) = 0.27. From the Binomial  $^{P}$ robability Law, we know that for independent trials with probability of success p at each trial, the probability of r

successes in n trials is given by

$$p_n(r) = {n \choose r} p^r (1-p)^{n-r}$$
 5-2

where

$$r = 0, 1, ..., n; n = r, r+1, r+2, ...$$

and

$$\binom{n}{r} = \frac{n!}{r! (n-r)!}$$

Let each trial be a one-year duration for which we are observing the level of peak ground acceleration. Let us define success as that event when the peak ground acceleration for a given trial (year) exceeds 0.2g. Thus, the probability of zero exceedence of level 0.2g in 20 years is the same as the probability of 0 successes in 20 trials. Hence, from Eq. 5-2:

$$p_{20}(0) = {\binom{20}{0}} p^0 (1-p)^{20}$$
  
 $p_{20}(0) = (1-p)^{20}$ 

However,

$$p_{20}(0) = 0.27$$
  
 $(1-p)^{20} = 0.27$   
 $p = 0.063.$ 

 $\mathbf{or}$ 

Thus, for Managua, there is a 6.3% chance that in any given year, a peak ground acceleration of 0.20g will be exceeded.

However, the return period is defined as
Return Period = 
$$RP = \frac{1}{p}$$
 5-3

Thus, the return period RP in Managua for a peak ground acceleration of 0.20g is  $\frac{1}{0.063} \approx 16$  years.

It should be pointed out that this return period of 16 years corresponding to 0.2g, obtained by using the cumulative distribution function (CDF) of PGA A at Managua for a 20 year exposure time does not change if we use the CDF corresponding to 50 year exposure time. For example, for a 50 year exposure time, (see Figure 4-27),

$$P_{50}$$
 (A > 0.20g) = 0.963 5-4

Hence,

$$_{50}$$
 (A < 0.20g) = 0.037

Р

0r

$$P_{50}(0) = (1-p)^{50} = .037$$

which gives  $p \approx 0.063$  5-5 and Return period RP  $\approx$  16 years.

Thus, using the CDFs for all the cities in Nicaragua considered in Chapter 4, we can develop a table of peak ground acceleration and return period. Table 5-1 is a general table giving this relationship for the cities considered. The following statements should be understood in using the concept of return period:

> A return period is the mean (or average waiting time for an event of interest. Thus, the average (waiting) time between 2 events producing 0.20g in Managua is approximately 16 years.

Table 5-1

Return Period in Years

DCA A in											
g units	Managua	Leon	Granada	Masaya	Chinandega	Matagalpa	Esteli	San Carlos	Rivas	Juigalpa	Bluefields
.05	1.5	2.0	3.0	2.0	3.0	6.0	7.0	8.0	3.0	6.0	60.0
.10	5.0	7.0	7.0	6.0	7.0	642.0	162.0	262.0	10.0	74.0	1127.0
.15	0.0	13.0	12.0	10.0	12.0	0.0666	2522.0	11755.0	23.0	1153.0	
.20	16.0	32.0	35.0	20.0	106.0				81.0		
.25	35.0	146.0	157.0	72.0	482.0			- <u></u>  	371.0		
.30	56.0	502.0	540.0	194.0	1657.0				1280.0		
.35	110.0	1430.0	1526.0	794.0					<u></u>		
.40	247.0	3562.0		2370.0							
.45	687.0										
.50	2975.0										

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- (2) The probability that an event corresponding to a return period RP will occur in any given year is given by  $p = \frac{1}{RP}$ . Thus, probability of exceeding 0.20g in Managua in any given year is  $\frac{1}{16} \approx 0.063$  (same as Eq. 5-5).
- (3) The probability that not a single event of the RP type will occur in RP years is given by  $\frac{1}{e}$  where e = 2.718, the Naperian base. Thus, probability that in 16 years, there will not be a single event producing a peak ground acceleration of 0.20g in Managua is given by  $\frac{1}{e} \approx 0.36$ .

Thus, there is 64% chance that in RP years there will be at least one event of RP type. For Managua, there is a 64% chance that in 16 years, 0.20g peak ground acceleration will be exceeded. Consider again Table 5-1. For seismic zoning purposes, the following statements can be made:

The return period corresponding to a peak ground acceleration of 0.20g in Managua is 16 years, in Leon is 32 years, in Granada is 35 years, in Masaya is 20 years, in Chinandega is 106 years and in Rivas is 81 years. Thus, for each city, a graph relating the peak ground acceleration and return period can be plotted. Figures 5-1 through 5-12 show these graphs. We will refer to these graphs as Acceleration Zones. Figure 5-1 shows return period vs. peak ground acceleration for all the cities. It can be seen that for a given return period event (say, 100 years), Bluefields has the lowest value of peak ground acceleration ( $\approx$ .05g) and Managua has the highest value of peak ground acceleration (.34g). The values for other cities lie between these two limits. Qualitatively, it can be said that for a



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PEAK GROUND ACCELERATION - GRAVITY UNITS











facility requiring a design loading corresponding to a 200 year return period, Bluefields has the lowest seismic zoning requirement; San Carlos, Matagalpa, Esteli and Juigalpa have similar zoning requirements but above the Bluefields level; Rivas, Granada, Chinandega, Masaya and Leon, having similar zoning requirements, come next; and finally, the highest level is for Managua. This type of graph can help in macrozoning a country for a given class and use of a structure or facility. (See Chapter 7.)

## Seismic Risk Zoning

In the previous section, we have seen the relationship between the peak ground acceleration and the corresponding return period for different major cities of Nicaragua. However, these relationships by themselves do not help in selecting a return period for a given acceptable level of risk. The next step, in any seismic zoning procedure, is to obtain a relationship between the economic (or exposure) life of a structure, the level of risk one is willing to take, and the return period consistent with the risk and economic life. Consider again the Binomial distribution. The probability of r successes in n independent Bernoulli trials, with probability p of success at each trial, is given by

$$p_n(r) = {n \choose r} p^r (1-p)^{n-r}$$
 Eq. 5-2 repeated

Thus

$$p_{10} (0) = {\binom{10}{0}} (p)^0 (1-p)^{10}$$
$$= (1-p)^{10} = \text{probability of zero success in ten trials (years).}$$

Let  $p(0) = (1-p)^{10}$  be equal to 0.90. Then the probability of no occurrence (or success) of a certain level of loading in ten years is given by 0.90.

or 
$$(1-p)^{10} = 0.90$$

Hence

p = .01048

or return period RP = 95 years.

Thus, for a structure whose economic life is ten years, if the acceptable risk level is 90% of not exceeding the specified loading level (i.e., 10% of exceeding), then the structure should be designed for a return period of 95 years. Table 5-2 gives the relationship between acceptable risk level, economic life and return period. If, for example, the acceptable risk level is 80% for a structure whose economic life is 50 years, then the loading level should correspond to a return period of 225 years. If this structure is in Managua, the corresponding peak ground acceleration level is approximately 0.39g. If the same facility for the same risk level is to be built in Matagalpa, the corresponding peak ground acceleration level should be approximately 0.12g. Thus, for a given class and use of structure, having the same economic life (50 years) and same acceptable risk (80%), the two consistent values of peak ground accelerations in Managua and Matagalpa are 0.39g and 0.12g. This is the concept of consistent risk design from one seismic region to another region of different seismicity. Figure 5-13 shows the graph relating the risk level, economic life and the return period. This particular graph is independent of any region and gives return periods only as functions

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N. C. Stranger

# Table 5-2

# Return Period as a Function of Economic Life and Probability of Non-exceedence

Economic Life Years Probability of not exceeding	10	20	30	40	50	100
90	95	190	285	390	475	950
80	45	90	135	180	225	449
70	29	57	84	113	140	281
60	20	40	59	79	98	196
50	15	29	44	58	72	145
40	11	22	33	44	55	110
30	9	17	25	34	42	84
20	7	13	19	25	31	63
10	5	9	14	18	22	44
5	4	7	11	14	18	34
1	3	5	7	9	11	22
0.5	2	4	6	8	10	19

of risk and economic life. Such graphs can easily be codified. Once the acceptable risk level for a given economic life is selected for a given class and use of a structure, the corresponding return period is immediately obtained from Figure 5-13. Then, based on the graph of return period vs. peak ground acceleration (similar to Figures 5-1 to 5-12), the loading at a site can be determined. Let us describe this concept of risk, economic life, return period and Acceleration Zone Graphs (AZG).

As an example, consider a design of a hospital facility. Assume that the exposure time or economic life of the system is 50 years. We are to determine the peak ground acceleration level for which this facility should be designed for each of three different cities. The cities are Managua, Leon, and Esteli. Assume that for the hospital, which is a critical facility that must remain functional after a seismic event, the acceptable level of risk corresponding to damage is 20% (see Chapter 7 for details). Thus, whether the planned facility is in Esteli, Managua, or Leon, we will accept a 20% chance of damage during the 50 years economic life of the structure. Then, from Figure 5-13, the return period corresponding to the 50 year economic life and 20% risk is 225 years.

Now let us refer to the AZG corresponding to Managua (see Figure 5-2). The peak ground acceleration for a 225 year return period in Managua is 0.39g. Similarly, referring to the AZG for Esteli and Leon, the peak ground acceleration values corresponding to the 225 year return period are 0.11g and 0.27g. Thus, these three values of peak ground acceleration in the three different cities are consistent

with the given acceptable risk.

As an alternate situation, consider two separate classes of structures to be built in Managua. Let a school building with an economic life of 30 years have an acceptable risk level of 20%, and a warehouse with a ten year economic life have a 40% acceptable risk level. Referring to Figure 5-13, the return period for which the school should be designed is 135 years, and the return period for which the warehouse should be designed is 20 years. Again from the Managua AZG (Figure 5-2), the corresponding peak ground acceleration values are 0.36g and 0.21g for the school and warehouse, respectively. If the same two facilities were to be located in Juigalpa, the corresponding peak ground acceleration values would be 0.11g and 0.07g. The major advantage of this method of zoning is that one can keep a consistent risk level from one region to another. Variations in the economic life and acceptable risk levels can be accounted for in arriving at a loading level through the return period transformation. Further application of the AZG to structural design will be presented in Chapter 7 of this report and in Part II of the total study.

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### CHAPTER VI

#### PROBABILISTIC INTENSITY FORECASTING -- DAMAGE ESTIMATION

### MMI Forecasting

Seismic zoning or seismic risk can be presented, as shown in the previous section, in the form of iso-acceleration maps or cumulative distribution functions (CDF) of peak ground accelerations for different cities or by acceleration zone graphs (AZG). Another very informative and useful parameter for representing future seismic risk is in the form of Modified Mercalli Intensity Scale MMI (see Appendix 2 for definition). This intensity scale describes the behavior of different types and classes of masonary and frame structures at a site due a seismic event. Recently, there has been a considerable amount of work in correlating the damage observed due to a seismic event. (See references 35, 36, and 37.) This damage correlation is usually with the MMI level for a given region. In previous chapters, we have already obtained the probabilistic loading level in the form of peak ground acceleration. Various empirical relationships are available to convert peak ground acceleration to the MMI Scale. The MMI Scale is discrete, whereas the acceleration scale is continuous. To obtain this discrete probability mass function of the MM intensity at different parts of the country for 20 years and 50 years, a Monte Carlo simulation process was used. The procedure can be described as follows:

- Obtain the CDF for peak ground acceleration A for the region under study. (See Figures 4-5 to 4-26.)
- (2) Select an empirical equation to convert peak ground acceleration to MMI. The relationship used in this report (see reference 38) is

$$\log_{10}(a) = \frac{1}{3} - 0.5$$
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where a is the acceleration in  $cm/sec^2$ 

I is the MM intensity.

Thus, for example, the peak ground acceleration at a site is 0.10g, then

 $a = 0.10g = \frac{10}{100} \times 981.46$ = 98.146. $\log_{10} 98.146 = \frac{1}{3} - 0.5$ 

 $\mathbf{or}$ 

I = 7.5.

Since I has to be VII or VIII, we pick I = VIII.

- (3) Through random number generation, pick a value of the peak ground acceleration by using CDF for the PGA. Substitute this generated value of PGA in equation 6-1 and obtain I.
- (4) Repeat step (3) n times and draw a histogram of frequency chart for I. As n→∞, the frequency of I will approach the probability mass function of I.

This process was repeated for all eleven cities mentioned in

Chapter 5. A time period of 20 years and 50 years was selected for convenience. Figures 6-1 through 6-11 show the probability mass functions for all the cities. The interpretation of these graphs can be explained by means of an example.

For Managua, during the next 20 years, probability that the <u>maximum</u> Modified Mercalli Intensity I will be VIII is given by 0.39 (see Figure 6-1).

Thus,

P [Maximum MMI in 20 years will be VIII] = 0.39.

Similar statements can be made for other parts of the country. Iso-seismal maps based on such forecasting can be generated for the whole country. It should be pointed out that intensity of shaking is very much a function of local geologic and soil conditions. For proper evaluation of these parameters, a detailed site-specific study and micro-characterization of the site are needed. The values presented here are based on macro study.

### "Insurance Risk" or Damage Potential

We have not correlated the damage data for Nicaragua with the observed past intensities. This study will be presented in part II of the current study. Such correlation can be made by observing the percentage damage in a given class of structures due to an observed past seismic event. From the 1972 earthquake in Managua, the information on such Intensity-Damage correlation can be obtained. However, we will present a methodology of using such information to estimate the "insurance risk" for a given region.



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A study of MM intensity and dollar damage was conducted after the Long Beach, the Kern County, and the San Fernando earthquakes. Figure 6-12 shows a graph of Median Loss in percent as a function of MMI for different types of structures. Even though we realize that these values are not applicable to Nicaragua, behavior of structures in Nicaragua built similar to those in the Southern California region will exhibit relationships similar to Figure 6-12. The purpose of presenting numerical examples with damage data from California and intensity forecast for Nicaragua is to show the methodology. No conclusions regarding insurance risk or damage potential should be made by using these numerical values. The purpose, to repeat once again, is strictly to demonstrate methodology. However, appropriate and applicable numerical values will be used in Part II of this study. If, on the other hand, residential houses or light industrial buildings are constructed similar to those in Southern California, such as wood frame dwellings and tilt-up structures, then the numerical values presented here can be used with some caution.

The three classes of structures considered in the example . are:

- (1) All one- and two-story wooden frame residential houses;
- (2) Pre-1940 residential homes; and

(3) Light industrial buildings.

Using Figure 6-12, Table 6-1 can be constructed. The losses corresponding to any MM intensity level are in percentages. Thus, for example, due to MMI of V, damage to a wood frame dwelling would be 0.1%. The corresponding loss to pre-1940 design dwellings would be



## Table 6-1

Intensity	All Dwellings	Pre-1940 Construction	Light Industrial Buildings
V	0.1	0.2	0.75
VI	0.2	0.4	1.5
VII	0.6	0.9	3.3
VIII	1.4	2.1	7.2
IX	3.3	5.0	16.0
Х	7.7	12.0	36.0
XI	. 18.0	29.0	80.0

Median Losses Due to Different MMI Levels

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0.2%, and to light industrial buildings, it would be 0.75%. To determine the expected loss to any class of structure, the probability of any MMI level must be multiplied by the corresponding loss due to that level. The summation over all intensities will give the expected loss in percentage for that class of structure.

Consider, for example, the probability mass function of MMI for a twenty year period at Masaya (see Figure 6-4):

Intensity	VII	VIII	IX	Х
Probability	.01	.47	.51	.01
Damage % All Dwellings	0.6	1.4	3,3	7.7

The expected median damage in 20 years for "all dwellings" is given by

$$E [Damage] = (.01) (.6) + (.47) (1.4) + (.51) (3.3) + (.01) (7.7)$$
$$= 2.424\%$$

Thus, for a \$1,000 valuation, the expected damage in 20 years is given by

Expected Damage =  $\frac{2.424}{100}$  x 1,000

= \$24.24 per \$1,000 valuation in 20 years.

Similar calculations can be carried out for all eleven cities considered for 20 and 50 years. Table 6-2 shows these loss calculation results. Table 6-3 shows similar expected loss calculations for a 20% chance of exceedance. Thus, in Managua, there is a 20% chance that in twenty years a light industrial building will have an expected loss of Table 6-2

Expected Median Losses

		20 Yrs.			50 Yrs.	
	A11 Dwell.	P-1940 Dwell.	L. I. Struct.	AII Dwell.	P-1940 Dwell.	L. I. Struct.
Managua	26.2	39.7	128.4	33.9	51.6	164.4
Leon	20.0	30.0	100.0	26.2	39.7	128.6
Granada	20.0	30.3	100.0	26.6	40.3	130.3
Masaya	24.2	36.7	119.4	29.6	44.9	144.4
Chinandega	16.5	24.8	83.4	19.9	30.0	99.3
Matagalpa	6.0	0.6	33.2	6.6	10.0	36.10
Esteli	6.6	6.9	35.7	8.1	12.1	43.1
San Carlos	6.3	9.5	34.4	7.4	11.0	39.6
Rivas	16.1	24.2	81.4	21.0	31.6	104.2
Juigalpa	7.6	11.5	40.9	9.8	14.8	51.7
Bluefields	2.9	4.8	17.5	4.5	7.1	25.8

Table 6-3

Expected Losses with 20% Chance of Exceedence

All Dwell. Dwell. Managua 65.5 Leon 50.0 Granada 50.0 Masaya 60.5				1 IT 3'	
Managua 65.5 Leon 50.0 Granada 50.0 Masaya 60.5	P-1940 Dwe11.	L. I. Struct.	A11 Dwell.	P-1940 Dwell.	L. I. Struct.
Leon 50.0 Granada 50.0 Masaya 60.5	99.2	321.0	84.8	129.0	411.0
Granada 50.0 Masaya 60.5	75.0	250.0	65.5	99.2	321.2
Masaya 60.5	75.8	250.0	66.5	100.8	325.8
Chinandeda	91.8	298.5	74.0	112.2	361.0
	62.0	208.5	49.8	75.0	248.2
Matagalpa 15.0	22.5	83.0	16.5	25.0	90.2
Esteli 16.5	24.8	89.2	20.25	30.2	107.8
San Carlos 15.8	23.8	86.0	18.5	27.5	0.66
Rivas 40.2	60.5	203.5	52.5	0.07	260.0
Juigalpa 19.0	28.8	102.3	24.5	37.0	129.2
Bluefields 7.3	12.0	43.8	11.2	17.8	64.5

\$321.00. However, the median (expected) loss for the same time period in Managua for the same class of structure will be \$128,40. Figure 6-13 shows the behavior of expected losses as a function of time and the class of structure. It can be seen that the expected loss or economic (or insurance) risk for the Managua region in one year is \$5.84 per thousand-dollar valuation. However, over a 20 year life of the structure, the expected median loss is \$26.20 per \$1,000 valuation. It can be seen from this example that expected loss averaged over a twenty year time period gives less mean rate of loss \$26.2/20 = \$1.31per \$1,000 valuation per year compared to \$5.84 per \$1,000 valuation when only one year was considered. This is the concept of risk averaging over time. Thus, if it were possible to insure a given facility for a 20 year economic life (say, a light industrial building), then it would be cheaper to buy that insurance for all twenty years at the same time as opposed to buying it year-by-year. In the long range, buying of insurance, for our numerical problem, the cost would be \$128.4 per \$1,000 valuation for a twenty year economic life. For a year-to-year buying, it would cost \$31.84 per \$1,000 valuation per year, or \$638.8 per \$1,000 valuation over a twenty-year span. Of course, in these simple calculations the value of money and the interest rate are not taken into account. From Tables 6-2 and 6-3 it can be seen that the "insurance risk" in decreasing order of magnitude in different cities is:

- 1. Managua
- 2. Masaya
- 3. Granada



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- 4. Leon
- 5. Chinandega
- 6. Rivas
- 7. Juigalpa
- 8. Esteli
- 9. San Carlos
- 10. Matagalpa
- 11. Bluefields.

Granada and Leon have almost equal expected economic or insurance risks. Similarly, Juigalpa, Esteli, San Carlos and Matagalpa have very similar insurance risks. The seismic insurance risk at Bluefields is very small. It should be pointed out that even though the damage data used in the numerical problem were from Southern California earthquakes, the order of these cities in their seismic and economic risks is valid. If proper data from Nicaragua are considered with appropriate economic conditions in Nicaragua, the ordering of the cities in their risks will not change substantially.

In conclusion, it can be said that the methodology presented here for determining the probable intensity levels and their use in determining expected damages needs a closer look and further investigation. Part II of the current study will go deeper into that question.

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#### CHAPTER VII

# THE RELATIONSHIP OF ISO-ACCELERATION AND ACCELERATION ZONE GRAPHS (AZG) TO SEISMIC DESIGN PROVISIONS

#### Introduction

From the information as developed in the preceding chapter, ground acceleration values  $A_g$  may be established for a given structure location. These values have selected probabilities P of not being exceeded during a given economic structure life L. The purpose of this chapter is to show how these acceleration values are to be incorporated into load criteria for seismic design provisions. Basically, acceleration values must be converted to seismic load information, such that structures, as designed for these load levels, will have a desired reliability  $R_D$  of damage protection and a much higher reliability  $R_C$ against total building condemnation or incipient collapse during the economic structure life.

While at first thought a building owner may desire full protection against both the hazards of damage and condemnation, a consideration of the complete set of his objectives will show the necessity for acceptance of some level of risk. For a given site location, structure life, and Use Group or Function, these objectives of the building owner are:

- . Low construction cost
- . Low operating cost
- . Functional configuration
- . Attractive configuration
- . Damage protection
- . Condemnation protection.

Perfect and certain fulfillment of all of these objectives is not possible due to the uncertainties in earthquake demands and in structural capacities and behavior. Practical fulfillment of the first four objectives requires the acceptance of a moderate probability of damage  $P_D$  (equal to 1- $R_D$ ) and a small probability of structural condemnation  $P_C$  during the building's economic life, L. Owners, therefore, must agree to a definite set of values for  $P_D$ ,  $P_C$ , L for the given value, and Use Group of the building. Graphs presented in Chapter 6 can help the owner decide on the level of risk and hence can result in the determination of the appropriate probability values.

For these given values of  $P_D$ ,  $P_C$ , and L, the Acceleration Zone Graphs (AZG) provide the Peak Ground Acceleration values  $A_D$  and  $A_C$  which have the moderate  $P_D$  and small  $P_C$  probabilities of exceedence during the structure life L at a given site location.

For example, the use or function of structures may be organized into the following groups which depend on the desired reliabilities of operation and damage protection in the event of a large earthquake.

<u>Group A</u>: Critical facilities necessary for life care and safety; hospitals; penal and mental institutions; gas, water, electric, and waste

water treatment facilities; communications facilities; police and fire departments; and disaster control centers.

<u>Group B</u>: Multi-family residences; hotels; recreational and entertainment structures; churches and schools; commercial and industrial structures necessary for normal commerce.

<u>Group C</u>: Facilities which are relatively non-essential for normal commerce and where damage will not create a life safety hazard. An example of such facilities would be warehouses.

Example values of the peak ground accelerations  $A_{\rm D}$  and  $A_{\rm C}$ , at sites in Managua and Leon, are given in the following Tables: 7-1, 7-2, 7-3, and 7-4. These are based on structure lives of 20 and 50 years, and on reasonable values for  $P_{\rm D}$  and  $P_{\rm C}$  corresponding to the structure Use Group. The values given in these tables are strictly for demonstrating the concepts, and are not meant to be used by engineers at this time. As can be seen from these four tables, the same facility and risk in Leon and Managua requires different  $A_{\rm D}$  and  $A_{\rm C}$  values. Obviously, Leon has a lower seismic demand than Managua.

With these known values of  $A_D$  and  $A_C$  at the structure site, the primary objectives of the structural designer are to:

- . Provide a structure with sufficient rigidity such that no significant non-structural damage will occur due to earthquake ground motions of a level represented by A<sub>D</sub>.
- . Provide a structure with sufficient strength capacity such that no significant structural damage will occur due to deformation demands caused by earthquake ground motions of a level represented by A<sub>p</sub>.

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Group	PD	RPD	A <sub>D</sub>	Р <sub>С</sub>	<sup>RP</sup> C	A <sub>C</sub>
A	20%	90	.33g	10%	190	.38g
В	50%	30	.24g	20%	90	.33g
С	70%	17	, 20g	50%	30	.24g

20 Year Economic Life, Managua Region

Table 7-2

20 Year Economic Life, Leon Region

Group	P <sub>D</sub>	<sup>RP</sup> D	A <sub>D</sub>	<sup>р</sup> с	<sup>RP</sup> C	A <sub>C</sub>
A	20%	90	0.24g	10%	190	0.26g
В	50%	30	0.20g	20%	90	0.24g
C	70%	17	0.17g	50%	30	0.17g

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Group	PD	RP <sub>D</sub>	А <sub>D</sub>	Р <sub>С</sub>	RP <sub>C</sub>	A <sub>C</sub>
A	20%	225	0.40g	10%	475	0.44g
В	50%	72	0.32g	20%	225	0.40g
С	70%	42	0.27g	50%	72	0.32g

Table 7-3

50 Year Economic Life, Managua Region

Table 7-4

50 Year Economic Life, Leon Region

Group	PD	₽₽ <sub>D</sub>	A <sub>D</sub>	Р <sub>С</sub>	<sup>RP</sup> C	А <sub>С</sub>
A	20%	225	0.26g	10%	475	0.30g
В	50%	72	0.23g	20%	225	0.26g
С	70%	42	0.21g	50%	72	0.23g

- . Provide a structure with sufficient strength, stability, and deformation capacity such that condemnation of the structure will not result from the effects of earthquake ground motions of a level represented by  $A_{\rm C}$ .
- While the possibility of significant damage is admissible with the moderate probability  $P_D$ , and the possibility of building condemnation is admissible with the small probability  $P_C$ , every prudent effort is to be made to prevent serious injury or death of the building occupants. This life safety objective requires that the details of both the structural and non-structural elements, and the complete structural system are such that neither injurious system failures, injurious falling debris, nor structural collapse will result from ground motions of a level represented by  $A_C$ .

The practical consequence of this last objective is that only those types of structural systems which are capable of retaining their integrity and stability at deformations at and beyond the  $A_{C}$  level are to be used.

Within these systems, the details of the connections between structural elements must tie the structure together, and the elements themselves must not have brittle or sudden buckling modes of failure. Multiple systems of frames, or back-up systems in the form of shear wall or vertical bracing must provide a series of lateral force resisting systems such that vertical load capacity is maintained for earthquake deformation demands at and reasonably beyond the  $A_C$  level.

The complete set of structural design objectives is shown in Figure 7-1. Since the demands of earthquake ground motions create nonlinear structural behavior, this figure indicates the critical design thresholds of damage  $\boldsymbol{\Delta}_{\!\!\!\!\!D}$  and condemnation  $\boldsymbol{\Delta}_{\!\!\!\!\!\!\!C}$  in terms of structure deformation  $\triangle$  rather than forces. The solid line coordinate system represents the probability density function f ( $\Delta$ ) of Earthquake Deformation Demands  $\boldsymbol{\Delta}_{\text{DFM}}$  which may occur on a given structure during a life L. The dotted line system indicates the load V versus deformation capacity  $\Delta_{\text{CAP}}$  curve of a given structure which satisfies the stated design objectives. Specifically, the structure has been designed such that its deformation capacities are equal to or greater than the earthquake demands at the damage and condemnation threshold levels. The earthquake of level  $A_{D}$  with probability of exceedence  $P_{D}$ does not exceed the damage capacity level  $\boldsymbol{\Delta}_{\text{DAM}}\text{,}$  and the earthquake having the condemnation level  ${\rm A}_{\rm C}$  with probability  ${\rm P}_{\rm C}$  , does not exceed the condemnation capacity level  $\Delta_{\rm CON}.$  Further, the structure loaddeformation curve maintains a reasonably constant level for even those highly improbable deformations which might reasonably exceed the condemnation level. This latter characteristic insures the stability of the structure against collapse.

The purpose of this chapter is two-fold. First, the response spectrum method of analysis will be described as the means of relating the AZG values  $A_D$  and  $A_C$  to their corresponding earthquake demands  $\Delta_D$  and  $\Delta_C$  on a given structure. Second, the complete design procedure will be developed such that the resulting structure will have the necessary design requirements of  $\Delta_{DAM} \geq \Delta_D$  and  $\Delta_{CON} \geq \Delta_C$ . In addition,



the types of structural systems and details necessary for the life safety requirement of collapse prevention will be defined. The analysis and design procedures will follow the general concepts as set forth in reference 28. The order of the subjects to be treated are as follows:

. Basic Response Spectra:

Definition of an earthquake response spectrum for an ideal elastic single-degree-of-freedom system; Effective ground acceleration as a working measure of spectral size or level; Spectral shape in terms of the dynamic amplification factor (DAF), its mean and standard deviation ( $\sigma$ ) value; the effect of the damping ratio ( $\beta$ ); the effect of inelastic behavior as represented by the ductility ratio ( $\mu$ ); site or soilcolumn response effects on the average ground motion values.

. Response Spectrum Analysis:

Response of multi-degree of freedom systems as the square root of the sum of the squared response of each mode to a given spectrum (SRSS response); use of the SRSS response to an inelastic response spectrum as an approximation of inelastic system response.

. Types and Characteristics of Lateral Force-Resisting Systems in Buildings:

Ductile frames; shear walls; walls and ductile frames; walls and ordinary frames; the effect of the choice of system type on the accomplishment of the design objectives.

. Design Spectra:

Definition and purpose of design spectra for the damage and collapse threshold earthquakes; spectral level established by the effective ground acceleration A for a given structure use group and life L; spectral confidence limits  $\kappa\sigma$  for structural system types;

structure-foundation interaction effects; subjective assignment of  $\mu$ ,  $\beta$ , and  $\kappa\sigma$  for given structural system types; formulation of a set of example design spectra.

. Proposed Design Method:

Earthquake loading as provided by the SRSS response to the Design Spectra; structure modeling for dynamic modal analysis; Dead, Live, and earthquake Load combination; design on an ultimate strength basis; calculation of inelastic deformation-demands and comparison with allowable ductility limits, and stability limits.

It is important to emphasize that the response spectrum analysis and corresponding design procedures are to be presented in a general descriptive form in this report. The current practice of seismic design is such that these methods are still in a state of development within the design profession. They represent, however, the most effective practical means of achieving the design objectives and are to be developed in detail in the proposed Part II of this study.

#### Basic Response Spectra

The earthquake response spectrum is to provide the analytical model by which the AZG values of  $A_D$  and  $A_C$  are to be related to structural load values. These load values, in turn, are to be employed within an appropriate design procedure to provide the necessary sizes and proportions of structural elements required to satisfy the design objectives. Before going into the method of formulating what may be termed as structural design spectra, it is necessary to describe the basic spectral characteristics and parameters. These include: size or level, shape, confidence limit, damping, and ductility. (A typical basic response spectrum is shown in Figure 7-2.)



Definition of an Earthquake Response Spectrum:

For a given accelerogram or time history of earthquake ground motion, the ordinate  $S_a(\beta, T)$  of the acceleration response spectrum (shown in Figure 7-2) is the maximum effective acceleration response felt by an elastic single-degree-of-freedom system, having a damping ratio  $\beta$  and natural period of vibration T.

Basic Response Spectra:

Figures 7-3 and 7-4 show response spectra plotted on special three-way logrithmic paper. They represent the type of basic spectral shape as proposed by Newmark in reference 29, and as extracted in Appendix 5 of this report. The Newmark method of spectrum construction is representative of current practice and is employed for the purpose of this report. Basically, it consists of the following steps:

> . Three straight lines representing constant acceleration, velocity, and displacement are used for the ground motion base line. The acceleration leg  $A_g$  is the peak effective ground acceleration from the AZG, either  $A_D$  or  $A_C$ . These  $A_g$ values set the level of the spectrum; and the ground velocity  $V_g$  and displacement  $D_g$  are proportional to this given  $A_g$ value.

. The basic response spectrum for a given damping value  $\beta$  is formed by multiplying the A<sub>g</sub>, V<sub>g</sub>, D<sub>g</sub> curve values by DAF values. In the Newmark method these DAF values are at about two standard deviations (2  $\sigma$ ) from the mean DAF shape.





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Inelastic Response Spectra:

When the inelastic deformation response of ideal elastoplastic system is known in terms of the ductility factor  $\mu$ , then the inelastic force and inelastic deformation spectra may be obtained by the rules given in the method and these are represented in Figure 7-5. If the ideal system (with period T) were to have its yield strength level equal to the Force at the Inelastic-Acceleration line, then the total inelastic deformation of the system is given by the Non-Elastic Displacement line.

Some improvements and modifications to this Newmark method which are to be introduced in this Part I report, and subsequently developed in the Part II report, are as follows:

- . The ground motion base line values and the resulting shape may need to be modified to represent the envelope of possible effects from the three principal sources of major earthquakes: Local Fault Systems, Volcanic Activity, and the Benioff Zone.
- . The DAF in terms of its statistical mean value and standard deviation  $\sigma$  must be evaluated for a macro-region which is representative of Nicaragua; see, for example, reference 30 for this type of study. A similar study as reference 30 will be prescribed for the Nicaragua region in part II of this report.
- . The rules for forming the inelastic acceleration and



inelastic displacement spectra must be modified to represent the actual inelastic behavior of structures rather than the given ideal elastic-plastic system behavior. In particular, the low period region of the inelastic displacement spectrum might be better represented by a curve equal to or close to the elastic response spectrum; this is because a real structure must be designed for the inelastic acceleration forces, but in this low period region these forces are equal to the elastic acceleration forces and hence the structure remains elastic with the corresponding elastic (rather than the  $\mu$ magnified inelastic) displacement value.

. Depending on the local site conditions, the response of the underlying soil column may be significantly different from average base line ground motion values. Therefore, soil-column adjustment factors must be evaluated to modify the basic  $A_g$ ,  $V_g$ ,  $D_g$  lines of the spectrum. These factors would be applied for either shallow-stiff sites or for deep-soft sites.

### Response Spectrum Analysis

Referring back to Figure 7-1, it is necessary for the designer to have some analytical method of computing the earthquake demands of  $\Delta_{\rm D}$  and  $\Delta_{\rm C}$ . The method to be employed is modal analysis as described in reference 31. Briefly, this consists of the following steps:

> . A linear elastic dynamic model of the structure is formulated, and the characteristic mode shapes and frequencies

are evaluated.

. For any given Response Spectrum, the force and displacement response of the linear model are assumed to be given by the square root of the sum of the squared response of each mode. This is termed as SRSS response.

. Design spectra are to be formulated (in a following section) such that: the SRSS response to the Damage Threshold Spectrum provides the demand  $\Delta_D$ , and the SRSS response to the condemnation Threshold Spectrum provides the demand  $\Delta_C$ . Since both  $\Delta_D$  and  $\Delta_C$  may be inelastic deformations, it is necessary to employ the assumption that inelastic structure deformations may be predicted by the elastic dynamic model response to the specially formulated inelastic design spectra. A detailed study of the validity of this assumption will be presented in part II of this report.

## Types of Structures in Terms of Their Lateral Force-Resisting Systems

Before proceeding to formulate the Design Spectra, it is necessary to define and consider the inelastic behavior of the following structural systems:

. Ductile Moment Resisting Frames: (the K=0.67 system of the Uniform Building Code).

Symbol	Description
0.67M	Complete Ductile Frames for each Bay Width of the building plan.
0.67P	Ductile Frames around the plan perimeter, with non-ductile columns in the plan interior areas.
. Shear and Bearing Wall	s: (the K=1.33 System of the UBC).
1.33B	A box system of walls with few openings.
1.33P	A box system of walls with many open- ings that form an equivalent frame system of piers and spandrels.
1.33C	Cantilever walls or towers with few openings.
1.335	Cantilever walls or towers with vertical alignment of openings which form sets of coupling spandrels.
. Ductile Frames and She	ar Walls: (the K=0.80 System of the UBC).
.080M	Same as 0.67M, but with several shear walls.
.080P	Same as 0.67P, but with few shear walls or towers.
. Ordinary Frames with S	emi-Ductile Details and Shear Walls:
(the K=1.00 System of	the UBC).
1.00M	Same as 0.80M, but with ordinary frames.

- 1.00P Same as 0.80P, but with ordinary frames.
- 1.00MX Same as 1.00M, but with vertical bracing in place of walls.

1.00MP Same as 1.00P, but with vertical bracing.

All systems are to have the necessary details required to insure the ductility and integrity of the system; these include: steel and reinforced concrete details for ductile and semi-ductile frames; chord, grid, and collector reinforcing for shear walls; details for vertical bracing systems; horizontal diaphram chords, drag, and shear connection to walls or bracing; and load transfer through construction joints. These details are best exemplified in references 32 and 33.

For a given constant strength level the general inelastic behavior of the various general classes of systems is shown in Figure 7-6, and for a given stiffness or rigidity the behavior is as in Figure 7-7.

Clearly, from Figures 7-6 and 7-7 the K=0.67 systems have the advantage of large ductility, but for some cases they may not have the required rigidity for damage control; and, alternatively, the K=1.33 systems have the desired rigidity, but suffer from a lack of ductility. In addition to these properties, each system has its particular structural damping ratio  $\beta_S$ , and subjective reputation of dependable performance. All of these characteristics--rigidity, ductility, damping,



and dependability--must enter into the formulation of design spectra as given in the next section. However, before going into this formulation, it is well to treat a very important aspect of seismic design. This is the adoption of the appropriate structural system for the given structure configuration and earthquake demand conditions. Consider the following cases:

Insufficient Rigidity of a K=0.67M Frame with  $\Delta_{DAM} < \Delta_{D}$  (see Figure 7-8).

The adoption of the K=0.80M system is preferable to the increase of section sizes in the original frame.

 $\label{eq:linear} Insufficient Ductility of a K=1.33 \mbox{ Box System with } \Delta_{\rm CON} < \Delta_{\rm C} \mbox{(see Figure 7-9).}$ 

The formation of a  $K_1$ =1.00M system is preferable to the general increase of section sizes in the original design. Even more dramatic in this case would be the consideration of a type of brittle pre-cast system (1.33 PC) of wall structure, where a strong back-up frame would be most essential for collapse safety.

#### Design Spectra

In the section on Basic Response Spectra, two groups of spectral characteristics were discussed: those dealing mainly with ground motion such as the  $A_g$ ,  $V_g$ ,  $D_g$  base lines and the site soil-column response factor; and those dealing with the elastic system such as the mean and standard deviation of the DAF, damping, and ductility. The Use Group of a structure has already been related to  $A_g$ , and the purpose of this section is to relate the actual structural character-


istics to spectral characteristics which deal with the ideal elastic system. Specifically,

- . The confidence level or number of standard deviations Ko above the mean DAF is to be related to the structure Use Group and the reputation or dependability of the type of structural system.
- . Damping is to be related to structural damping and structure-foundation interaction.
- . Ductility is to be related to the member ductility, connection details, and number of back-up frames or indetermineacies contained in the type of structural system.

Confidence Limit for the DAF:

The choice of spectral DAF levels based on the reputation or performance record of a structural system may be best explained in terms of the reliability levels or confidence limits of the amplified response spectrum (or DAF). It should be realized that the DAF values are random variables which can be described in terms of their average value and standard deviation ( $\sigma$ ) as shown in Figure 7-10. In the Newmark-Hall paper (Appendix 5), it is stated that the DAF values in Table 2 are such that there is only a 10 percent chance of being exceeded. This level would coincide roughly with the upper (two- $\sigma$ ) confidence level. It is proposed here, that the appropriate DAF confidence level may be different for different types of structural systems. If a system has proven to be reliable from past experience.



and can tolerate a fairly wide range of displacements before showing significant damage, and has back-up systems to prevent collapse--then it should merit a low confidence level (say the (one- $\sigma$ ) level) for its design spectrum. This is because the system can be depended upon to resist chance exceedences of the design level without failure.

On the other hand, if a system is new and untried, if it is brittle or not well connected, or has no reliable back-up system, then there is a need for that protection against chance excess demands as would be provided by the  $2\sigma$  exceedence level.

Therefore, for each type of structural system, an appropriate component  $K_{T}$  of the confidence level will be assigned according to the system performance record.

Also, for the purpose of providing a desired level of protection for critical facilities, an additional component  $K_{\rm G}$  of the confidence level will be assigned according to the structure Use Group. The total confidence level for a given group and type is  $(K_{\rm G}+K_{\rm T})\sigma$ above the mean DAF. It should be recalled that in addition to this confidence limit, the ground acceleration base line  $A_{\rm g}$  for the spectrum has also been assigned from the AZG according to the accepted probability of exceedance as governed by the building use group.

## Damping:

Damping due to the type of structural system is termed as  $\beta_S$ , and will be assigned according to the general material behavior. A new and additional component of damping occurs due to the effects of structure foundation interaction. This will be termed as  $\beta_F$  and will be evaluated in accordance with the methods in reference 34. Total damping for a design spectrum is therefore  $\beta' = \beta_S + \beta_F$ .

#### Ductility:

Ductility varies with the type of structural system according to the material, member and connection details, and the number of statistical indeterminacies or back-up systems within the structure. Each structural type will be assigned a ductility value  $\mu$ 'according to its particular description.

## Properties

The complete set of spectral properties for the different types of structural systems may be organized as shown in Table 7-5. The values are given for some example systems with a Use Group B. In general, the values are assigned by professional judgment to provide agreement with past experience, reported behavior, and a reasonable level for the final design load values.

## Definition and Formulation of Design Spectra in Terms of Modified Inelastic Spectra

While it is generally recognized that the condemnation or collapse threshold level of earthquake motions must be resisted by structural behavior in the inelastic range, this report advances the concept that some inelastic behavior may be tolerated while resisting motions representative of the damage threshold earthquake. This concept is based on the fact that the structural damage threshold occurs at story deformations somewhat greater than the deformation at the attainment of first yield or design strength at the member section

Table	7-5
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Given	Use	Group	Β,	ĸ <sub>G</sub>	=	1.0
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Туре	Damage Threshold			Collapse Threshold		
	К <sub>Т</sub>	β <sub>S</sub>	μ'	к <sub>т</sub>	β <sub>S</sub>	μ' .
0.67M	1.00	0.05	1.5	1.00	0.05	4.00
1.00M	1.20	0.05	1.5	1.10	0.07	3.00
1.33C	1.50	0.05	1.5	1.20	0.07	2.00

having the highest stress ratio. Figure 7-11 shows the states of strength design, damage threshold, and condemnation threshold.

The following discussion presents the definitions, methods, and reasoning employed for the formation of modified inelastic design spectra:

- . the Damage Threshold Spectrum for strength determination (DTSS), for setting the design strength of members, and
- . the Damage Threshold Spectrum for Deformation determination (DTSD), for the evaluation of P-Delta effects on design strength.
- . the Condemnation Threshold Spectrum for Deformation determination (CTSD), for the evaluation of member ductility demand, and detection of instability problems due to P-Delta effects.

The modified, inelastic response, design spectra are formed by the use of what may be termed as spectral modification factors  $\mu$ ' and  $\beta$ '. These factors are used as ductility and damping factor values to obtain the inelastic spectra. They are selected by judgment, consistent with the respective ductility and damping capabilities of the particular type of lateral force-resisting system of a given structure; where these capabilities are as evidenced by test results and past performance of similar systems having undergone strong earthquake ground motions. Referring to Figure 7-12, the objectives are:

1) For the Damage Threshold Earthquake (DTEQ) the factors





 $\mu_D'$ ,  $\beta_D'$  are to produce an inelastic acceleration spectrum (see Figure 7-13) (DTSS) such that when members are designed on the ultimate strength basis for forces due to: (this is in accordance with the design procedure given in the next section)

- . dead load
- , code specified (non-load factored) live load
- . DTSS Acceleration
- . Extra story shear due to P-Delta effect at DTSD deformation

then it is assumed that the structural damage threshold deformation capacity will be equal or larger, with an acceptable level of reliability, than the deformation demands  $\Delta_D$ of the damage threshold earthquake (DTEQ). If it is further assumed that the damage threshold demand is provided by the DTSD deformation, then it is important that the magnitude or size measure, the shape, and the  $\mu_D'$  and  $\beta_D'$  values be selected to provide DTSD values having the acceptable level of reliability (corresponding to an upper confidence limit). This damage threshold deformation demand assumption would allow study and formulation of drift limitations for control of non-structural damage.

2) For the Condemnation Threshold Earthquake (CTEQ) the factors  $\mu_{C}^{\prime}$ ,  $\beta_{C}^{\prime}$  are to produce an inelastic deformation spectrum (see Figure 7-14) (CTSD) that will provide deformation values reliably greater or equal to the deformation demand  $\Delta_{C}$  of the CTEQ. Local member ductility demands and story stability



checks (involving P-Delta effects) evaluated for CTSD deformations will therefore be upper confidence limits for the CTEQ demands.

For this report, the purpose of the  $\mu'_C$  value is to produce a reasonable, but reliably large estimate of CTEQ deformations. For the formation of an inelastic deformation spectrum, a large value of  $\mu'_C$  provides conservative (large) values of deformation demand. If it were desired to employ an inelastic acceleration spectrum (CTSS) for the strength design of members, then a large  $\mu'_C$  value would of course provide nonconservative (low) force demand values. A proposed change to the Newmark method for construction of the CTSD is indicated in Figure 7-14. This may provide a more realistic estimate of actual structure deformation.

It is assumed in this report that the DTSS is larger than the CTSS and therefore controls the strength design of members. Examples of the design spectra DTSS and CTSD will be constructed later in this chapter, after the presentation of the complete proposed Design Procedure in the next section.

## Proposed Design Procedure

The DTSS and CTSD design spectra are to be employed in the following design procedure:

. Given Use Group, Life, and Site:

Obtain  $A_D$ ,  $A_C$ ,  $K_G$ , and site soil-column response factor. The mean DAF and  $\sigma$  values are known. (These will be available from Part II of this study.)

. Given Structure Type and Foundation:

Obtain  $\beta_S,\ \beta_F,\ \mu,\ K_T$  at both Damage D and condemnation C levels.

. Construct Design Spectra:

DTSS for Member Section Design, with  $\mu_D'$ ,  $\beta_D' = \beta_S + \beta_F$ , (K<sub>G</sub> + K<sub>T</sub>) $\sigma$ .

CTSD for Ductibility Evaluation and Stability Analysis,

with  $\mu_C'$ ,  $\beta_C' = \beta_S + \beta_F$ ,  $(K_G + K_T)\sigma$ .

Formulate a Linear Elastic Model of the Structure and Find SRSS Value of:

- 1) Member Force Response to the DTSS;
- 2) Member Deformation Response to the CTSD.

Design Members for Load Combinations on an Ultimate Strength Basis for:

- 1) Load Factored Vertical Dead and Live Load;
- DTSS Force plus Vertical Dead and Live Load, and Seismic P-Delta Effects;
- 3) DTSS Force plus two-thirds Dead Load (for vertical acceleration effects). (See Appendix 6 for vertical acceleration effects.)
- . Perform Deformation Analysis due to CTSD Response:
  - Evaluate local member ductility demands and compare with established allowable values (to be determined in <sup>P</sup>art II of this report).

2) Investigate the stability of structural system.

## Construction of Example Design Spectra

Given the structure use group, life L, and structural system type, such that the spectral values (A, K $\sigma$ ,  $\beta$ ', and  $\mu$ ') can be determined for both the Damage and Condemnation Level Earthquakes. The basic elastic spectra may be constructed with these known A, K $\sigma$ , and  $\beta$ ' values. (Examples are shown in Figures 7-3 and 7-4.) Then, with the given  $\mu_D$  and  $\mu_C$  ductility values, the inelastic design spectra DTSS and CTSD are constructed according to the Newmark method in Appendix 5. The complete procedure is given in the following example for a structure in the Managua region.

. Structure Use Group: B.

- . Region: Managua.
- . Type of Structural System: 0.67M.
- . Economic Life L = 20 years.
- . Site soil-column conditions are average such that the site factor S = 1.00.
- . Structure-Foundation Interaction Damping  $\beta_{\rm F}$  = 0.05.
- . The ground acceleration base lines are found from Table 7-1.

$$A_{\rm D} = 0.24 g$$
,  $A_{\rm C} = 0.33 g$ 

. The structural system properties are found from Table 7-5.

$$K_{\rm G} = 1.0,$$
  
For DTSS  
 $K_{\rm T} = 1.00, \ \beta_{\rm S} = 0.05, \ \mu_{\rm D} = 1.5$   
For CTSD  
 $K_{\rm T} = 1.00, \ \beta_{\rm S} = 0.05, \ \mu_{\rm C} = 4.00$ 

. The Spectral Properties are:

	For DTSS		
$\beta_{\rm D}^{\prime} = \beta_{\rm F} + \beta_{\rm S} = 0$	.10, $\mu_D^* = 1.5$		
$K = K_{G} + K_{T} = 2.$	0, Ko = 20		

## For CTSD

 $\beta_{\rm C}^{\,\prime} = \beta_{\rm F} + \beta_{\rm S} = 0.10, \ \mu_{\rm C}^{\,\prime} = 4.00$ 

The Basic Elastic Response Spectra for these properties are constructed and are as shown in Figures 7-3 and 7-4.
The modified inelastic Design Spectra DTSS and CTSD are constructed and shown in Figure 7-15.

It is interesting to see how design load values from this spectrum compare with loads from the Uniform Building Code. Let us consider a 10 story, Type 0.67M steel frame building with first mode period of 1 second. From Figure 7-15, the acceleration  $S_a = 0.14g$ , and the resulting base shear value would be about

 $V_1 = (0.14) (0.8) W = 0.112 W$ 

where the 0.8 factor allows for the multi-mode response participation factors (or equivalent weights), and W is the structure weight. Member forces from  $V_1$  would be combined with Dead and un-factored Live Load forces for ultimate strength design. The corresponding UBC base shear is

$$V_2 = UKCW = 1.4 (0.67) (\frac{0.05}{3\sqrt{1}}) W$$
  
 $V_2 = 0.047 W$ 



Member forces from  $V_2$  would be combined with a load-factored value of 1.4 times the Dead and Live Load forces, for ultimate strength design. Therefore, although the  $V_1$  is 2.4 times the  $V_2$  value, the resulting  $V_1$  member designs will not differ from the  $V_1$  designs by as much as this amount because of the different method of factoring the Dead and Live Load effects.

It should be realized that these resulting spectra are for example only. The assigned spectral property values are very approximate. These values are to be refined in Part II of this study in order to provide consistent Design Spectra for all Use Groups and Structural Types. i a construction of the second se ł. ł 

#### CHAPTER VIII

## SUMMARY, CONCLUSIONS AND FURTHER RESEARCH

## Summary

In Part I of the seismic risk study for Nicaragua, the following topics are presented:

- Geological setting for the country in general and the Managua area in particular.
- Data base for past seismic events was extensively studied. Limitations of the data and approximations were discussed. Seismic recurrence for ten line sources and three area sources was developed.
- 3. Based on the assumption of the Poisson occurrence of seismic events, probabilities of exceeding different magnitude levels as functions of time for different regions was derived. Using Esteva's attenuation relationship, isoacceleration maps for the country were constructed. Eleven cities in Nicaragua were considered in this mapping process. Cumulative distribution functions of peak ground accelerations for 20 and 50 years were established. This was shown to be one way of presenting seismic risk for Nicaragua.
- 4. Based on iso-acceleration maps, the Acceleration Zone

Graphs (AZG) were developed for the eleven cities. A method of determining load levels for consistent risk for the whole country was discussed and suggested. It was proposed that charts such as AZG be used for seismic zoning of Nicaragua.

- 5. Another parameter, the MMI scale, in understanding seismic risk was presented in probabilistic sense. Based on the damage data in the U.S.A., a method of determining insurance risk was presented.
- 6. Ground acceleration values from AZG were employed to set the level of the design spectra for structural damage prevention and condemnation control. A design methodology was proposed based on ultimate strength and loads resulting from the above inelastic design spectra.

## Conclusions.

It can be concluded that there are sufficient data and analytical methods to provide adequate seismic zoning information on an acceptable risk criterion. The methods presented here are simple, easy to use and transferable to structural design procedures. The zoning of the country can be interpreted from iso-acceleration maps or from cumulative distribution plots of peak ground accelerations or from AZG. The method of zoning presented here is general and is completely amenable to availability of additional future data. From the current study, it can be clearly seen that the seismicity of Nicaragua varies significantly from region to region. The Managua region and

the region surrounding the line of volcanoes is much more seismic than the central or the eastern region. For example, Bluefields has the lowest probable loading level and the Managua region has the highest probable loading level. Looking at the iso-acceleration maps and AZGs, this information becomes obvious.

It is also obvious that methodologies as presented in this report can be used to convert the loading information based on acceptable risk and economic life of the facility to the structural design process. Further insight can be obtained regarding insurance and economic risk in different parts of the country based on the method presented in this report. Again, it can be seen that for a given region, it is cheaper to buy long-range seismic insurance than to purchase short-term coverage. Based on this insurance risk concept, various parts of the country can be compared for future probable economic impact due to a seismic event.

## Further Research

In order to implement and use the procedures presented in their general form in this report, the following tasks are to be accomplished in Part II:

> Refined seismic zoning of the country based on acceptable risk levels for different classes and uses of structures.
>  A detailed look at the acceptable probability levels and their effect on cost and general economy.

> . The concept of microzoning a given region in the country.

- . Mapping information in the form of effective ground velocity values V as predicted in terms of historical data and geological characteristics.
- . Inclusion of the site (or soil-column) response factor in the evaluation of  $A_g$ ,  $V_g$ ,  $D_g$  at a given structure location. Representation of foundation-structure interaction in the form of an additive component of structural damping  $\beta_F$  and change in the structure period of vibration.
- . Evaluation of the standard deviation values  $\sigma$  and the mean values of the spectral DAF for a given region, with recognition of either the averaging or the predominance of the possible earthquake sources (Benioff Zone, Volcanic, and Local Faulting) as they affect the  $A_{\sigma}$ ,  $V_{\sigma}$ ,  $D_{\sigma}$  values.
- . Formulation of a more precise listing of the Structure Use Groups ranging from critical to non-essential facilities; and establishment of the corresponding acceptable exceedance probability values P for typical structure life times L.
- . Assignment of the use Group contribution  ${\rm K}_{\rm G}$  to the spectrum DAF confidence level.
- . Elastic structure modeling techniques to allow reliable prediction by response spectrum analysis of structural element forces and inelastic deformations.
- . Improvements in the method of forming the inelastic force and displacement response spectra.
- . Categorization of the types of structural lateral force-

resisting systems and the assignment of the corresponding ductility  $\mu$ , damping  $\beta_S$ , and structure type contribution  $K_T$  to the spectrum DAF confidence level, for both the damage and condemnation threshold spectra.

- Formulation of appropriate ultimate strength member design equations for all acceptable materials; specification of essential details necessary for the ductility and stability against collapse; and establishment of allowable ductility demand limits for all acceptable materials and systems.
  Simplification of the design spectrum, the dynamic analysis, and the deformation and stability analysis, to a procedure similar to that employed by the Uniform Building Code. This simplified design procedure would be applicable to the majority of structures. The detailed response spectrum analysis would be required only for those structures which are extremely critical, costly, and/or unique in their configuration and structural systems.
- . With damage and economic data from Nicaragua, an insurance and economic risk analysis is to be accomplished. Risk to life and limb will be treated in Part II of this study.

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# APPENDIX 1

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THE DECEMBER 23, 1972 EARTHQUAKE

## APPENDIX 1

## THE DECEMBER 23, 1972 EARTHQUAKE

#### Introduction

The Managua Earthquake actually consisted of three tremors. The major shock, which registered a surface wave magnitude (Ms, NOAA) of 6.2 and a body wave magnitude (Mb, NOAA) of 5.6, was followed by two major aftershocks within one hour, with Mb=5.0 and 5.2, respectively. The quakes were relatively moderate in size, compared to other major earthquakes (e.g. San Francisco, 1906, M=8.3), but caused extensive damage because (1) the epicenters were shallow, (2) surface rupture occurred, and (3) many buildings were constructed with an adobe or taquezal type of construction.

## Intensity

The maximum intensity of shaking (Figures A1-1, A1-2), employing the Modified Mercalli Scale, was X along the lakeshore, with VII-IX common throughout most of the city center. (An intensity IX is defined as follows: "Damage considerable in specially designed structures; well-designed frame structures thrown out of plumb. . . . Buildings shifted off foundations. Ground cracked conspicuously. Underground pipes broken." (Reference 7, p. 59.)

The intensity decreased radially outward from the city center (reference 15, p. 18). Near the epicenter, however, intensity contours



Figure A1-1 Isoseismal Map of Nicaragua After Hansen and Chavez, 1973



Dashed lines Figure  $^{\rm AI-2}$  Isoseismal map, Managua earthquakes of 23 December 1972. are fault traces from Brown and others (1973).

After Dewey, it al, 1973

parallel the active faults, whereas southwest of the city they cross the faults. This suggests release of energy near the city center, rather than to the southwest (reference 4, p. 70).

#### Shaking

"Duration of the earthquake in its destructive phase was about 7 seconds" (reference 3, p. 143). The shaking was described as "a series of vertical shakes, followed by horizontal motion, then a vertical 'drop.'" (Reference 15, p. 18.) Peak ground acceleration, recorded 7 km west of the city center, was 0.39 g (reference 15, p. 18).

#### Damage

Damage occurred as ". . . two broad lanes of heavily damaged buildings of high density, separated by a stretch wherein heavy damage was expressed in a loose, random pattern." (Reference 2, p. 267.) The western lane was bordered by the 1931 fault trace; the eastern was situated between the Tiscapa Fault and the "secondary trace 400 m to the east" (Chico Pelon Fault) (reference 2, p. 267).

# Hypocenter Location

The original hypocenter calculation, based on P-wave arrivals, was by NOAA. The location, 27 km northeast of the city center, was erroneous for two reasons: (1) a poor seismic net exists for Central America, and (2) the standard P-wave trend-time tables are incorrect for this area. The "correct" determination, based on an accelerogram recorded at a nearby refinery, placed the hypocenter beneath the center of the city, at a depth no greater than 8 km. This placement

has led to a better location of the Benioff Zone in Central America by relocating previous earthquake hypocenters, based on the erroneous velocity data, to the south (reference 4, pp. 66, 70, 75). Aftershock data substantiate the accelerogram hypocentral location, although the depth indicated is 8-10 km, and show three zones of activity. The zones are shown in Figures A1-3 to A1-5.

P-wave first motions, recorded at telescismic distances, are consistent with fault plane movement parallel to the mapped surface fault traces within the city. It is probable that the major seismic zone, striking N 30-40° E and dipping from 74° W to 82° E, with a 1 km width, bifurcates near the surface into 2 fault traces, the Tiscapa and Chico Pelon Faults. This is supported by the observations that the two faults are at the most only a few hundred meters apart, they trend towards an intersection, and they display roughly equal amounts of displacement from the 1972 tremors. The zone passes through Laguna Tiscapa and the Customs House, and is within 1500 m of nearly all of the severely damaged part of Managua. Aftershock data also suggest left-lateral movement, the same as that observed on the ground. The fault zone responsible for the major portion of the seismic energy was about 15 km long (reference 4, pp. 66, 71; reference 11, p. 97; reference 18, p. 95; reference 14, pp. 115, 127).

## Nature and Amount of Fault Movement

Movement was predominantly sinistral, or left-lateral, although local dextral (right-lateral) and normal, or vertical slip, did occur. The faults are manifested in unconsolidated sediments and



FigureA1-3Locations of 171 aftershocks. The polygons represent the error in location assuming a possible error in reading arrival times at each station of 0.1 second. Station locations are designated by stars. The wide solid line in Managua represents faults B and C mapped at the surface (Plate 1, Brown and others, 1973).

After Ward, et al, 1973


Fig.Al-4 Intensity map for the main shock and epicenters of 300 aftershocks located by data from a 5-station seismic array. At least two linear trends in the aftershock activity are suggested, as indicated by the dashed lines.

After Matumoto and Latham, 1973





volcanics by en echelon, rather than continuous fractures. The strike of these fractures is generally more northerly than that of the fault zones themselves. The faults die out within 1.6 - 5.9 km of Lago de Managua.

The maximum horizontal displacement, determined by triangulation, was 40 cm. Maximum vertical movement measured was 10.2 cm.

According to Plafker and Brown, a geometric reconstruction of Tiscapa Crater and the lakefront suggest 10 m sinistral and 30 m vertical displacement. Noting that 1972 movement was predominantly sinistral, they suggest that there has been a late Holocene (past 1,000-2,000 years) change in the tectonic deformation style (reference 14, p. 134). Their geometric reconstruction is open to interpretation, however. In addition, it is possible for an individual seismic trend to be in apparent conflict with the overall, long-term trend.

#### Cause of the Earthquake

A number of hypotheses have been advanced to explain the earthquake mechanism. They relate to various interpretations of the tectonic setting of Nicaragua.

The 1972 earthquake hypocenter was much too shallow to be related to the underlying Benioff Zone. It was probably caused by tectonic forces associated with the Nicaragua Depression and/or with the chain of volcanoes. This earthquake was typical of numerous Central American tremors, which, although responsible for only a small fraction of the total seismic energy released in the region, and which are of small or moderate magnitude, nevertheless produce intense ground

shaking in small, often densely populated areas (reference 4, p. 67).

One explanation of the earthquake relates the tremblors to isostatic and gravity conditions. There is a correlation of earthquakes in the Managua area with years of drought, which is reflected in surface levels of Lago de Managua falling as much as 3.77 m. It is suggested that the low lake level leads to a decrease in weight from the lake onto the earth's crust below. Resisting forces, in years of low lake levels, are thus in excess of equilibrium, strains build up, and earthquakes result. In addition, there is a correlation of earth tide maximums with the 1931, 1968, and 1972 quakes (reference 16, pp. 56-60). One problem with this theory is that it postulates <u>upward</u> movement of the block, whereas slight subsidence, in addition to horizontal movements, in fact occurred. However, earthquakes have been recorded during the loading and unloading of reservoirs, and the decreases in water levels could have been the triggering force needed to initiate rupture along faults already at maximum stress.

A second theory "explains" both the left-lateral offset within Managua and the right-lateral offset of the Cordillera de Marrabios. It suggests that the chain of volcanoes is a secondary spreading center, analogous to the East Pacific Rise or Mid Atlantic Ridge. The rift is thus a zone of crustal extension, a fact suggested by the general structure of the Nicaragua Depression. The entire rift is being pulled apart in the fashion shown in Figure Al-6, but with irregular breaks, known as transform faults. Movement on such a transform fault would show left-lateral displacement within Managua, located within the zone of extension between offsets of the ridge, or



After Dewey, et al, 1973

volcanics, yet beyond the immediate area of the city both sides of the fault would show movement in the same direction (reference 4, pp. 82-84). This theory is attractive because it suggests an explanation for several geologic phenomena. It is especially useful because it predicts earthquakes for two other parts of the Nicaragua Depression, where the Cordillera de Marrabios is offset.

A third theory ascribes the concentration of seismic activity near the Nicaragua volcanics to an unusually thin, rigid lithosphere, resulting in the crust being subjected to unusually high tectonic stresses. Although both north-south compression or east-west tension could produce the observed pattern, geologic evidence favors the latter (reference 4, pp. 84-85). This explanation fits with the apparent tensional nature of the Nicaragua Depression, as well as regional plate movements, and also the observed left-lateral movement of the faults in Managua, but does not explain the line of volcanoe offset. Such a stress system could be caused by movement of the Caribbean Plate (Eastern Nicaragua) eastward, while the Cocos Plate (Pacific Ocean) travels north and plunges under Central America (reference 11, p. 102).

The final theory is that right-lateral offset is occurring along the Cordillera de Marrabios (Figure A1-7). Extension occurs at a kink, and left-lateral oblique faults, members of the conjugate shear set, form (reference 15, p. 12). This explanation is similar to the preceding one, but fails to explain the cause of the kinking, extension, or the origin of the volcanics. Although volcanoes do occur along fault zones, we are not aware of any cases where the line of



Figure Al-Mechanism for Diastrophism in the Managua Area. (A) Right lateral displacement of the Pacific coastal block tends to produce a gap if a fracture, kinked to the right is slipped in a right handed sense. After Brouwer. (B) In the Managua area, a series of normal left-lateral oblique faults are members of the conjugate shear set produced by extension and by a shear resulting from a northwesterly aligned dextral couple.

After Saint-Amand, 1973

volcanics is so straight or so long.

It is not possible to conclude the cause of the tectonic pattern around Managua. The transform fault explanation seems to be the most reasonable, because it explains all of the observed phenomena. However, it presupposes an interpretation of Plate Tectonics which has not, for this region, at least, been proven. Further detailed work is needed. The explanation will aid in interpretations of the entire Nicaragua Depression.

#### APPENDIX 2

#### MODIFIED MERCALLI INTENSITY SCALE

# THE MODIFIED MERCALLI INTENSITY SCALE

Mercalli's (1902) improved intensity scale served as a basis for the scale advanced by Wood and Neumann (1931), known as the modified Mercalli scale and commonly abbreviated MM. The modified version is described below with some improvements by Richter (1958). The following remarks are taken almost verbatim from *Elementary Seismology*, Charles F. Richter (W. H. Freeman and Company, San Francisco, copyright © 1958).

To eliminate many verbal repetitions in the original scale, the following convention has been adopted. Each effect is named at that level of intensity at which it first appears frequently and characteristically. Each effect may be found less strongly, or in fewer instances, at the next lower grade of intensity; more strongly or more often at the next higher grade. A few effects are named at two successive levels to indicate a more gradual increase.

Masonry A, B, C, D. To avoid ambiguity of language, the quality of masonry, brick or otherwise, is specified by the following lettering (which has no connection with the conventional Class A, B, C construction).

Masonry A. Good workmanship, mortar, and design; reinforced, especially laterally, and bound together by using steel, concrete, etc.; designed to resist lateral forces.

Masonry B. Good workmanship and mortar; reinforced, but not designed in detail to resist lateral forces.

Masonry C. Ordinary workmanship and mortar; no extreme weaknesses like failing to tie in at corners, but neither reinforced nor designed against horizontal forces.

Masonry D. Weak materials, such as adobe; poor mortar; low standards of workmanship; weak horizontally.

Modified Mercalli Intensity Scale of 1931 (Abridged and Rewritten by C. F. Richter.)

1. Not felt. Marginal and long-period of large earthquakes.

Taken From "Fundamentals Of Earthquake Engineering" N.M.Newmark and E.Rosenblueth. Prentice Hall.

- 2. Felt by persons at rest, on upper floors, or favorably placed.
- 3. Felt indoors. Hanging objects swing. Vibration like passing of light trucks. Duration estimated. May not be recognized as an earthquake.
- 4. Hanging objects swing. Vibration like passing of heavy trucks; or sensation of a jolt like a heavy ball striking the walls. Standing motor cars rock. Windows, dishes, doors rattle. Glasses clink. Crockery clashes. In the upper range of 4, wooden walls and frames crack.
- 5. Felt outdoors; direction estimated. Sleepers wakened. Liquids disturbed, some spilled. Small unstable objects displaced or upset. Doors swing, close, open. Shutters, pictures move. Pendulum clocks stop, start, change rate.
- 6. Felt by all. Many frightened and run outdoors. Persons walk unsteadily. Windows, dishes, glassware broken. Knickknacks, books, and so on, off shelves. Pictures off walls. Furniture moved or overturned. Weak plaster and masonry D cracked. Small bells ring (church, school). Trees, bushes shaken visibly, or heard to rustle.
- 7. Difficult to stand. Noticed by drivers of motor cars. Hanging objects quiver. Furniture broken. Damage to masonry D including cracks. Weak chimneys broken at roof line. Fall of plaster, loose bricks, stones, tiles, cornices, unbraced parapets, and architectural ornaments. Some cracks in masonry C. Waves on ponds; water turbid with mud. Small slides and caving in along sand or gravel banks. Large bells ring. Concrete irrigation ditches damaged.
- 8. Steering of motor cars affected. Damage to masonry C; partial collapse. Some damage to masonry B; none to masonry A. Fall of stucco and some masonry walls. Twisting, fall of chimneys, factory stacks, monuments, towers, elevated tanks. Frame houses moved on foundations if not bolted down; loose panel walls thrown out. Decayed piling broken off. Branches broken from trees. Changes in flow or temperature of springs and walls. Cracks in wet ground and on steep slopes.
- 9. General panic. Masonry D destroyed; masonry C heavily damaged, sometimes with complete collapse; masonry B seriously damaged. General damage to foundations. Frame structures, if not bolted, shifted off foundations. Frames racked. Conspicuous cracks in ground. In alluviated areas sand and mud ejected, earthquake fountains, sand craters.
- 10. Most masonry and frame structures destroyed with their foundations. Some well-built wooden structures and bridges destroyed. Serious damage to dams, dikes, embankments. Large landslides. Water thrown on banks of canals, rivers, lakes, etc. Sand and mud shifted horizontally on beaches and flat land. Rails bent slightly.
- 11. Rails bent greatly. Underground pipelines completely out of service.

12. Damage nearly total. Large rock masses displaced. Lines of sight and level distorted. Objects thrown into the air.

Other commonly used intensity scales include those of Rossi-Forel (Rossi, 1883; Forel 1884), Cancani (1904), Sieberg, (1923), and Medvedev (1953). The latter is known as the Soviet scale and roughly coincides with the MM intensity scale. Also roughly equivalent is the MSK scale (Medvedev and Sponheuer, 1969). The other scales are falling slowly into disuse. The same is true of the Japanese, Chilean, and other systems of intensity grading that have enjoyed some degree of popularity at national or regional levels.

A now classical piece of work on earthquake intensity and its relation with magnitude is found in a paper by Gutenberg and Richter (1942 and 1956).

#### APPENDIX 3

### LISTING OF EARTHQUAKES

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E	•		ε	Ð	TUDE	TUDE		MAG			MAG		MAG	•	MAG
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NOS 45	18 0.6 71	13	36	01	14.678N	87.567W	7	500 MB		072	0		0	022	478
CG S-8	30 01 67	09	30	27	12.196N	87.596 N	8	410 MB		074	0		0	010*	329
CGS 54	15 08 69	01	43	11	09.473N	83.863W	9	440MB		078	0		0	022	379
CGSPDE	14 07 68	3 03	55	24	15.237N	68. 843W	14	450MB		072	0	F	0	033	395
66515	25 02 69	02	01	44	15.274N	87.544W	13	480 M8		072	0	-	0	6036	445
665 15	25 02 65	101	39	00	15.231N	27.466W	15	540118	,	0 72	50M5	F	0	G0 / 2	500
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CGSPDE	14 03 6	10	00	19	12.000N	86.800W	25	450MB		075	ő		õ	013	395
CGS 23	19 03 69	1 19	49	22	11.786N	88.087W	23	470 M8		076	ñ		õ	021	428
ERL 65	02 11 72	18	24	45	11.71 IN	87.939W	24	46018		074	õ		õ	02.0*	412
CG S-B	20 08 64	08	26	52	11.70 ON	87.200W	25	430MB		074	Ō		Ő	008	362
ER L 71	11 12 72	2 12	51	04	11.40 3N	87.151W	27	440M8		0 74	Ó		Ö	DO 17#	379
CG S 8	23 06 65	5 07	37	46	11.400N	87.800W	24	450M8		074	0		0	028	395
C G S8	31 05 6	5 20	46	54	11.100N	86.000W	28	470 MB		074	0		0	0 30	42 8
CGSPDE	11 08 67	12	26	18	11.80 ON	85.900W	21	470MB		075	0		0	017	428
CG SP D E	03 10 6	7 18	16	03	10,900N	85 <b>.9</b> 00W	21	580 MB		078	0		0	104	611
CG <b>S-</b> B	19 11 60	5 16	01	46	109.200N	85.800W	25	430 MB		077	0		0	012	362
ER L 74	25 12 72	2 00	26	28	15.215N	88.943W	34	460M8		0 72	0		0	020	412
CGSPDE	04 10 6	7 00	12	12	15.70 ON	88.60 OW	33	44018		072	0		0	010	379
CG S-8	13 03 66	21	46	23	14.20 ON	88.400W	36	420MB		072	0		0	017	345
CGS-8	09 01 64	+ 18	38	10	14.90 ON	81.900W	- 55	470M8		072	0	~	0	005	428
CC 5-2	08 02 01		20	59	13.024N	88. 27 LW	22	43 UMB	4	073	0	F	0	NUUS	362
CCS-8	29 10 64	4 12	41	22	13 700N	88. 200W	22	400 M0		C10 270	0		0	008	312
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CG S~B	27 11 64	4 10	55	11	13-40 ON	88.700 H	33	410MB		073	ŏ		õ	006	329
CGSPDE	03 04 68	1 00	06	00	12.20 ON	88.300W	33	430 MB		0.76	õ		õ	011	362
C GS-B	23 08 6	5 06	07	36	12.400N	88.200W	39	400/18		076	õ		õ	011	312
CG 5-B	15 08 64	4 14	43	03	12.00 ON	88.000W	39	400 MB		076	0		0	006	312
CGS-B	16 04 66	5 13	21	40	12.300N	88.400W	33	440MB		076	0		0	017	379
CGS 65	CL 10 69	9 08	41	31	12.084N	88.358W	33	440MB	3	076	0	F	0	N011	379
CG S-8	12 01 6	5 03	19	10	12.300N	88.900W	39	4 30 MB		076	0		0 .	007	362
CGS-B	29 04 64	F 08	08	41	12.10 ON	88.400W	33	390M 8		076	0		0	007	300
CGS-B	08 05 6	714	40	08	12.974N	86.073W	33	460M8		073	0	F	0	N030	412
C G SP D E	19 09 68	3 00	37	17	12.143N	88.714W	33	440 MB		076	0		0	NO14*	379
EPL 47	04 08 73	3 11	54	16	12.14 ON	88. 983W	33	440MB		0 76	0		0	N008*	379
C65-B	30 07 6	06	- 33	30	12.030N	88.5004	- 33	42 UM		076	U		Ű	009	343
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CGSPOE	C1	64	68	07	28	28	12.400N	88.500W	33	440M8		076	0		0	013	379
C G S-B	06	11	63	21	49	57	12.20 ON	88°000	37	410MB		076	0		0	010	329
CGS-B	24	07	66	18	50	54	12-200N	88.700W	33	410 MB		076	0		0	01 0	329
C G SB	15	04	67	22	10	08	12.743N	88.163W	33	430M8		0 76	a		0	N00 6*	362
C C S B	27	08	64	12	34 27	34	12-000N	88° COCM	35	430110		076	0		0	011	36 2
C 6 5 - 8	10	12	65	17	50	33	12-400N	87.3004	22	420110		074	0 n		0	007	343
CGS-B	63	09	63	05	28	37	12.32 DN	87.900W	31	41 04/8		0 74	0		0	008	329
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CGS 38	13	05	69	16	39	27	12.447N	8 7. 83 OM	33	42 0 MB		074	0		0	N007#	345
CGS-B	27	06	65	13	08	28	12.600N	87.900W	33	410MB		074	0		0	007	329
CG 5-8	02	04	64	03	48	59	12.50 ON	87.800W	32	420MB		074	0		0	009	345
	20	11	52	15	37	17	12.10 ON	87. 90 CW	33	0		074	0		625PAS		625
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CGS 48	25	67	70	05	47	05	12.56 IN	87. 44 AN	22	45048		074	ñ		0	N031	205
GS 51	27	07	73	0.8	51	ñ	12.415N	87.407	33	450 NB		074	ñ		ő	ND1 7*	3 95
CGS-8	24	04	65	13	25	41	12.70 ON	82.000W	33	440MB		094	õ		õ	009	379
CGS-B	16	07	65	10	34	12	11.60 ON	88.000W	30	490MB		076	0		Ó	022	462
CG S-B	23	03	65	17	18	29	11.830N	88. 200W	33	42 OMB		076	0		0	006	345
CGS-B	18	04	67	08	24	17	11.41 9N	88.415₩	33	400MB		076	0		0	N007*	312
NOS 45	16	06	71	04	18	56	11.722N	88.222₩	33	450MB		076	0		0	NO12*	395
CGS-B	18	0.6	65	09	28	21	11.630N	86, 200W	33	430M8		076	0		0	007	362
	21	80	11	109	21	57	11.839N	88.884W	- 33	500M8		016	3885		0	N041	380
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0.65-8	18	07	64	20	37	35	11.00 ON	87.000W	33	460MB		074	õ		õ	010	417
CG S-B	29	0.4	64	21	53	15	11.800N	87. 500W	33	450MB		074	õ		õ	007	395
CGS-B	01	04	65	15	09	15	11.40 ON	87.400W	33	420 MB		074	0		Ó	009	345
C GS-B	14	04	66	06	57	45	11.830N	87. 500W	33	41 OM B		074	0		0	007	329
CG SP DE	04	07	67	13	29	04	11.600N	87.200W	33	420 MB		074	0		0	010	345
CGS-B	22	03	65	00	17	27	11.900N	87.900W	33	430MB		074	D		0	007	362
CCS-8	10	10	62	11	21	10	11.000N	87.800W	 	480 MB		0 14	0		0	016	440
CGSPDE	04	07	67	07	30	20	11.80 ON	87.300	32	420 00		074	0		0	016	212
NCS 8C	25	i i	70	05	38	12	11.745N	87. 92 OW	36	480M8		074	ă		õ	014	445
NOS S	11	01	71	17	13	48	11.714N	87.794	33	480MB		074	ŏ	F	õ	N014*	445
CGS 3	06	01	69	09	44	41	11.41 ON	87.232W	33	4 30 MB		074	0		0	011	362
CGS 3	C6	01	69	09	24	23	11.44 ON	87.245W	33	480M B		074	43MS		0	NO 26	430
CG S-B	06	06	65	08	34	17	11-130N	87.200W	33	460M8		074	0		0	005	412
CGS~B	30	07	63	12	25	39	11.400N	87.300W	33	420 MB		074	0		0	005	345
0.05-8	29	08	64 56	20	21	54	11.0009	67.200% 87.500W	22	420MG		0 14	0		0	005	347
CG 5-8	13	0.0	63	18	14	18	11.700N	87. 900W	33	42000		074	ñ		0	016	367
C GS-B	20	05	67	23	42	19	11.65 BN	E6. 714W	33	420MR		0 74	õ		ñ	NO 1 24	345
CGS-B	80	06	65	01	25	59	11.020N	86.800W	33	470MB		074	ō		õ	007	428
CG5 92	16	11	68	15	14	37	11.082N	86.911W	33	460 MB		074	39MS		0	N018	390
CGS 8	15	01	70	16	57	47	11.614N	86 <b>. 9</b> 2 9W	33	480M8		074	0		0	N008*	445
CGSPDE	02	10	67	15	59	43	11.790N	86.800W	39	470 MB		074	0		a	025	428
LGS-B	12	09	64	19	05	47	11.200N	86.900W	33	4TOMB		074	0		0	014	428
CCS-89	22	11	00 45	71	14	.14 52	LL COON	00°0718	22	400 MB		014	0		Û	NUL6	395
CC 5-R	30	04	64	15	05	57	11-2004	86. 700W	22	430MB		074	ő		õ	005	ササン
CGS 94	19	11	68	00	09	27	11.33 6N	86.714W	33	460MB		074	41MS		õ	NO 22	410
CGS 26	20	03	70	21	00	08	10.428N	87.364W	34	440M8		077	43MS		õ	013*	430
CGS 54	20	07	70	04	58	05	10.366N	87.400W	33	460 M8		077	0		0	N015*	412
CG S 55	12	80	70	11	07	59	10.867N	87.2298	33	450MB		077	0		0	N009*	395
CGS 37	25	05	70	23	05	18	10.738N	86. 93 9W	33	480MB		077	0		0	N014	445

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CGS 62	12	03	10	17	21	32	10.432N	80.010W	22	950MB		077	0		U	NU097	362
E9110	13	09	72	14	20	21	10 5021	94 400H	32	40000		077	0		0	0004	372
C C S D D E	25	02	67	22	57	17	10 70 04	84 000W	22	440FIC		077	ň		ő	007	217
CC 5005	72	0.2	67	66	12	57	10.000	04 400W	33	400 MB		077	0		0	001	320
CC 3FD C	28	07	66	00	54	18	10.8000	86 700W	33	420 MB		077	ñ		0	016	345
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CG 5-B	17	07	65	04	05	16	10,100M	84 500W	33	43048		077	ŏ		õ	010	367
CGSPDE	24	10	67	06	02	16	10.70 ON	86.000	33	53048		077	õ		ŏ	066	528
FRL 81	14	ĩũ	71	06	59	10	10.824N	86-268W	33	47048		077	4 045		ň	N020*	600
CGS-B	13	ōī	65	02	19	49	10.100N	86. 300W	33	480 M8		077	0		õ	009	645
CGS-8	30	07	64	15	13	39	10.60 GN	86.5000	33	470ME		077	õ		õ	007	428
C GS-B	28	0.9	63	05	25	03	10.20 ON	86.000W	33	410MB		077	ö		â	008	329
CGSPDE	03	10	67	19	22	39	10.400N	86. 200 W	33	450MB		077	ō		õ	019	395
CGS-B	14	12	66	01	33	13	10.60 ON	86. 800W	33	430MB		077	à		ō	008	362
C GS-B	02	08	64	04	00	45	10.93 ON	86.300W	32	470M8		077	Ő		õ	012	428
ERL 19	19	02	72	19	41	33	10.574N	86.085₩	33	470 MB		077	0		0	N014#	428
CG5-8	67	06	65	07	41	47	10.400N	86.000W	33	470M8		077	0		Ö	007	428
CGS 45	11	C7	69	07	5 ì	04	10.34 2N	85.369W	33	500M8		078	0	F	450BRK	N049	450
CGS-B	16	01	67	15	30	47	10.641N	85.920W	33	470 ×8		078	0		0	N 01 9 *	428
CGS 46	11	07	69	05	57	12	10.189N	85.484W	30	470MB		078	0	F	0	025	428
ERL 36	14	04	73	09	19	09	10.260N	85.015W	33	430MB		078	0		0	N006*	362
CG S-B	15	05	64	12	10	25	10.500N	85.700W	33	450 M8		078	0		0	024	3 95
ERL 71	13	09	71	15	33	27	09.973N	87.3618	33	440MB		077	0		0	N00 7	379
ERL 77	28	09	71	05	47	16	09.821N	8 E. 26 W	33	500M8		077	0		Ö	N036*	478
CG S-B	15	02	65	02	29	48	09.900N	86.500W	33	550M8		077	0		0	011	561
C GS-8	31	08	64	17	07	39	09.60 ON	85.400W	33	420M@		077	0		0	006	345
CGS-B	23	02	66	01	02	01	09.700N	85.800H	35	4 0 0 M B		077	0		0	800	312
CGS-B	15	05	64	05	46	32	09.80 ON	85,500W	33	420 18		077	0		0	010	345
CGS-8	69	09	65	12	43	37	09.60 M	85.300W	33	450 88		077	0	_	0	008	395
CGS	20	02	54	02	00	43	1 1. 50 ON	87.5004	N	0		074	0	F	587PAS	*	587
CGS	19	02	54	00	40	25	11.530N	87.500W	N	0		0 74	0	F	663 PA S	*	663
GUIE	22	12	34	14	29	31	11.500N	87.00UW	N	0		014	0		6 SOPAS	*	650
GUIE	12	01	33	01	17	42	11-00 ON	87.0000	N	0		0 /4	0		SOUPAS	5 	560
DEM 238	13	8	28				11.70	87.20	N	U						***	338
DEM 239	20	<u> </u>	28				11.70	87.20		E						~~~~	371
DEM 335	20	77	43				11 80	67 40	NI NI	E E						***	471 619
CLITE	10	10	41	0.4	22	12	10 50 0M	6 10 TO	- N	E		077	0		575046	***	575
755	11	11	50	13	51	10	10.40 M	85.7000	ň	ň		078	ň		575045	*	575
DEM 246	21		50	10	21	10	11.71	87.20	v	0		0.0	v		2121 43	*	582
DEM 248	2	4	50				11.70	87.20		ň						*	571
DEN 184	28	12	54				11.50	87.50		F						*	515
DEM 186	11	1	55				11.00	86.50		Ē						卒	498
D &M 203	16	8	55				11.00	87.00		Ē						\$	464
D&# 219</td><td>ii</td><td>9</td><td>59</td><td></td><td></td><td></td><td>12.00</td><td>87.50</td><td></td><td>Ē</td><td></td><td></td><td></td><td></td><td></td><td>ŧ</td><td>513</td></tr><tr><td>DEM 307</td><td>15</td><td>1</td><td>63</td><td></td><td></td><td></td><td>12.00</td><td>8.7.50</td><td>20</td><td>D</td><td></td><td></td><td></td><td></td><td></td><td>***</td><td>582</td></tr><tr><td>DEM 317</td><td>30</td><td>6</td><td>63</td><td></td><td></td><td></td><td>11-40</td><td>87.30</td><td>33</td><td>4.2</td><td></td><td></td><td></td><td></td><td></td><td>***</td><td>4.2</td></tr><tr><td>DEM 218</td><td>19</td><td>5</td><td>57</td><td></td><td></td><td></td><td>12.14</td><td>87.24</td><td>24</td><td>E</td><td></td><td></td><td></td><td></td><td></td><td>\$</td><td>413</td></tr><tr><td>06 M 306</td><td>15</td><td>1</td><td>63</td><td></td><td></td><td></td><td>12.03</td><td>87.50</td><td>33</td><td>D</td><td></td><td></td><td></td><td></td><td></td><td>*</td><td>589</td></tr><tr><td>D&M 298</td><td>17</td><td>7</td><td>62</td><td></td><td></td><td></td><td>11.60</td><td>87.10</td><td>25</td><td>E</td><td></td><td></td><td></td><td></td><td></td><td>*</td><td>470</td></tr><tr><td>* BENIOR</td><td>F /</td><td>NO</td><td><b>C</b>03</td><td>S T A</td><td>R 10</td><td><b>A</b></td><td>40 60 7</td><td>9 KM (1</td><td>861</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></tr><tr><td>CGS 11</td><td>31</td><td>01</td><td>70</td><td>22</td><td>23</td><td>37</td><td>15.72 7N</td><td>88. 75 OW</td><td>46</td><td>500MB</td><td></td><td>072</td><td>45 M S</td><td></td><td>0</td><td>060</td><td>450</td></tr><tr><td>CG S-B</td><td>10</td><td>11</td><td>63</td><td>07</td><td>18</td><td>07</td><td>12.93 ON</td><td>88.500W</td><td>45</td><td>42 OM B</td><td></td><td>076</td><td>0</td><td></td><td>0</td><td>007</td><td>345</td></tr><tr><td>C G S-8</td><td>24</td><td>05</td><td>63</td><td>06</td><td>10</td><td>09</td><td>12.100N</td><td>88<b>.50</b>0W</td><td>42</td><td>440 MB</td><td></td><td>076</td><td>0</td><td></td><td>0</td><td>012</td><td>379</td></tr><tr><td>C G S-8</td><td>08</td><td>07</td><td>66</td><td>13</td><td>22</td><td>13</td><td>12.40 ON</td><td>58.900W</td><td>43</td><td>430M8</td><td></td><td>076</td><td>0</td><td></td><td>0</td><td>013</td><td>. 362</td></tr><tr><td>CGS-B</td><td>24</td><td>01</td><td>66</td><td>03</td><td>46</td><td>57</td><td>12.30 ON</td><td>88.400H</td><td>46</td><td>450MB</td><td></td><td>076</td><td>0</td><td>-</td><td>Û</td><td>018</td><td>395</td></tr><tr><td></td><td>06</td><td>06</td><td>69</td><td>16</td><td>16</td><td>CI.</td><td>12.45 TN</td><td>88.000W</td><td>48</td><td>50048</td><td>3</td><td>075</td><td>45MS</td><td>F</td><td>U</td><td>051</td><td>450</td></tr><tr><td>C82 AC</td><td>28</td><td>11</td><td>68</td><td>13</td><td>44</td><td>33</td><td>12.45IN</td><td>88.006W</td><td>49</td><td>490MB</td><td></td><td>076</td><td>0</td><td></td><td>Q</td><td>021</td><td>46Z</td></tr><tr><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></tr></tbody></table>																	

												A3	5			
FRL 85	26 11	71	04	06	38	12.14 8N	87.626¥	47	440MB		0 74	O	a	013	379	
CGS-B	30 01	62	08	34	23	12.730N	87.500W	49	0		074	õ	F 488PAL	049	488	
CG \$-8	04 04	64	06	43	20	12.50 ON	87. 700 W	41	430 MB		074	0	O	012	362	
CG <del>S-</del> '8	06 12	65	13	19	13	12.40 ON	87.400W	44	390 MB		074	0	0	007	300	
CGS 12	12 02	70	17	22	11	12-139N	8 6 <b>-</b> 61 6W	44	440M8		075	0	0	013	379	
EPL 16	05 03	72	21	47	26	11.971N	87.914W	46	460MB	3	074	0	F.0	020*	412	
CGS-B	31 08	63	13	08	46	11.930N	67.000W	48	490M8		074	0	0	018	462	
CGS-8	08 12	64	04	11	53	11.530N	87.000W	48	500MB		0 74	0	0	029	478	
65 52	14 07	73	07	55	60	11.63/N	87.291W	46	490 10		074	44MS	0	024#	440	
EKL 33	20 02	13	00	19	00	11.0409	67+200W	42	40UND		074	40713	0	015	400	
CG 5 7	20 01	70	na Na	27	48	11.49794	67.341W	46	540 MR		076	ñ	0	063	545	
665-8	12 10	66	20	20	06	11.200N	86-200W	45	510MB		074	ñ	ů l	054	495	
EPL 9	30 01	72	22	25	οā	11.08 2N	86.750W	43	450M9		074	38 MS	õ	617	380	
CG SP DE	30 06	67	11	42	33	11.000N	86.600W	44	450 MB		074	0	ō	022	3 95	
CGS-8	30 07	64	05	16	03	11-100N	86.200W	42	STONB		074	ō	0	022	594	
ERL 7	30 01	72	19	10	07	11.261N	86.773W	48	460 MB		0 74	44MS	0	027	440	
CGS 36	13 0 9	69	17	38	28	11.784N	86.179W	46	490 MB		074	52MS	400BR K	042	520	
ERL 61	01 10	72	06	00	51,	41 -01 5N	86.330W	49	420 MB		074	0	0	00.6*	345	
SYKES	27 10	57	18	29	10	15.970N	88.11 CW	56	0		093	0	400PAL	008	400	
CGS 55	03 08	69	21	17	16	13.342N	88. 342W	52	43 OMB		073	0	0	01 0*	362	
CGS 59	04 09	69	06	25	28	13.21 6N	88.429W	53	460M8	4	073	0	FO	0.20	412	
	21 08	1 12	21	24	11	13.27 ZN	00.713H	50	34088		073	48 115		0000	400	
CG SPDE	25 0 2	400	61	29 58	11	12 200N	88 2000	50	410110		074	0	0	079	320	
CGS-8	65 03	64	14	30	18	12-100N	88-1004	53	430MA		0.76	ñ	õ	009	362	
CGS-8	15 0 6	64	09	41	24	12.600N	88.300W	56	410 18		076	õ	ō	007	329	
CG S-8	19 06	64	17	31	56	12.40 ON	88.100W	53	400MB		076	0	0	011	312	
CGSPDE	18 04	68	04	40	38	12.50 ON	W000.88	54	490MB		076	0	0	019	462	
CG S-B	30 08	64	15	20	50	12.600N	88.500W	54	460M8		076	0	0	015	412	
CGS-B	04 07	63	01	43	20	12.80 ON	88.700W	55	410M8		076	0	0	007	329	
C G S - B	13 07	66	08	20	58	12.630N	87.800W	56	530MB		074	0	0	073	528	
CGS-B	17 05	63	15	03	43	12.400N	E / . 000W	50	550MB		074	0	0	047	501	
CG 5-8	27 03	63	14	2.2	40	12.200N	87.712W	50	4 20 M/R		074	0	0	010	319	
C G S = B	06 12	67 5	04	30	10	12.500N	87.300	50	450M6		074	ň	0	024	395	
CG S 54	07 08	70	13	03	14	12.325N	87.79 LW	59	450MB		074	ŏ	ŏ	016	395	
NCS 21	25 0	2 71	04	15	41	12.159N	87.489W	52	530MB		074	ō	Ó	075	528	
CGS-B	10 06	64	16	25	09	12.00 ON	87.900W	55	420MB		074	0	0	006	345	
ERL 41	07 07	73	07	07	55	11.842N	87.76 1W	55	430 MB		074	0	0	015	362	
CG S 32	24 04	69	22	29	46	11 .53 9N	87.D22W	50	440 MB		074	0	0	022	379	
ERL 40	06 07	73	05	21	49	11.962N	E7+588H	51	480M8		074	0	0	023	445	
CG S-B	07 10	63	03	59	54	11.600N	86. 900W	50	450MB		074	0	0	015	395	
EKL 9	104 02	12	01	10	43	11.21.3N	80° 8AI M	52	480MB		074	0	0	019	445	
C 63 2 5	01 02	46	15	17	45	10.8000	86.700W	50	490116		074	ő	Ň	0097	402	
CGS~8	18 04	67	07	0.5	08	10.749N	86.7778	53	48048		077	ñ	ă	041	445	
CGS-B	03 02	64	õi	46	27	13.000N	88.00 OM	61	410 MB		073	õ	õ	006	329	
CGS	27 06	58	05	44	28	13.000N	88.500W	60	0		073	ō	DE600PAS		600	
CGS 80	22 10	68	06	42	01	13.20 BN	88.247W	64	470 M&	5	073	0	0	017	42 8	
ር G S- ፀ	20 12	63	22	28	31	13.20 ON	88.000W	64	430M8		0 73	0	0	005	362	
CG S-B	21 01	64	07	01	59	13.130N	88. 40 OW	€8	470MB		073	0	0	03 0	428	
CG S-B	16 08	64	07	30	12	13.300N	87.600W	60	390MB		072	0	0	005	300	
LGS-B	02 03	64	16	09	46	12.50 ON	88.000W	63	440M8	-	076	0	0	018	5/9	
LG 3-8	10 00	01	09	20	41	12.83UN	00 4 20 0W	63 20	U 5 10 MP	2	076	0	F 403PAL	0022	405 405	
ERL 147	17 08	72	22	04	ידידי 22	12+071N	88.7434	00 44	210710 470 MAR	4	010	0	r V F A	024	777 428	
ERL 15	07 03	73	13	00	45	12.70.5	88.0279	64	460 MB	7	0.76	õ		017*	412	
CGS-B	24 07	66	06	11	55	12.20 ON	88.300W	61	410M8		076	õ	ŏ	013	32.9	
ERL 81	C8 11	71	04	26	16	12.472N	88.165W	68	490N8		076	Ö	Ō	031	462	

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CGSPDE	26	01	68	10	37	56	12.730N	88.800W	60	390 MB		076	0		0	007	300
C G S B	31	07	66	19	10	46	12-4001	88.100W	63	420 MB		076	0		0	032	345
CG S-B	04	05	66	18	13	55	12.500N	87.700H	68	5 10 M 8		074	0		0	036	495
CGS-8	08	08	64	15	45	10	12.50 ON	£7.800W	63	580MB		074	0		0	032	611
CG \$ 20	10	03	69	80	15	08	12.349N	87. 455W	62	530M8		074	0		600BRK	059	600
C G S-8	21	02	64	07	24	08	12.80 ON	87, 900H	62	390 M B		074	a		0	007	300
ERL 85	25	11	71	22	06	<b>2</b> 6	12°723N	8 7. 45 8W	62	490m8		074	0		0	024	462
CG S-8	18	04	67	80	29	12	11.751N	87.30 TW	65	460MB		074	0		0	02 8	412
ERL 8	16	01	72	23	55	10	11.505N	97.582W	62	460 MB		074	0		0	014	412
GUTE	90	01	41	09	48	34	11.75 ON	86.500H	60	0		074	0		600PAS		600
CG S-B	20	03	61	06	16	21	11.300N	86.500 W	60	0		074	0	F	613PAS		613
CG 5 38	14	0.5	69	13	49	03	11.51 8N	86. 154 W	62	480 MB		074	0		0	046	445
NOS 44	10	06	71	11	20	31	11.101N	EG. 766W	60	490M8		074	0		0	015*	462
NO 5 30	- 26	04	71	18	32	20	11.422N	86. 760W	69	470MB		074	0		0	040	428
CGS-B	02	11	65	22	44	41	10.50 ON	86.300¥	69	450MB		077	0		0	010	395
C GS-B	30	03	67	23	07	02	15.10 LN	88.782W	76	420MB		072	a		0	006*	345
CG S- 8	08	03	67	15	52	15	13.049N	86.127W	75	390 MB		073	0		0	005*	300
CGS 19	09	03	69	07	12	39	13.101N	88,528W	75	440M8		073	0		0	021	379
GUTE	26	12	39	11	55	11	13.250N	88.25 OM	75	0		0 73	0		6.00PAS	AAA	600
CGS-B	09	01	67	22	31	22	13.138N	88.981W	78	410 MB		073	0		0	008	329
CGS−B	04	01	67	00	28	07	13-10 ON	88.625W	72	4 LO M 8		073	0		0	010	329
C GS-B	27	12	66	21	22	16	13.30 ON	88.800W	78	540M8		073	0		0	090	545
ERL 66	19	11	72	04	35	2%	12.973N	88. 52 4	73	560MB		073	0		0	065	578
CGS-B	10	08	64	14	00	51	12.40 ON	88.300W	71	400M8		076	0		0	006	312
CGS 33	03	05	69	03	19	06	12.987N	88.44 90	77	450M 8	5	0 73	0	F	0	032	395
CGS 25	01	04	69	21	19	53	12.677N	88. 23 3W	71	490M8	4	076	0	F	0	038	462
CGS 26	08	04	69	19	41	58	12.670N	88.34 OH	76	480M8		076	, 0		0	023	445
ERL 32	30	04	72	10	55	19	12.8964	88.6680	77	440MB	3	076	0	F	0	01.9	379
CG S 62	06	09	70	20	44	49	12.783N	88.595W	75	450M8		076	0	۴	0	017	3 95
CGS 34	21	04	70	05	37	08	12.94 7N	-87. 880W	79	5 20 M B		074	0		0	045	511
ERL 41	28	07	73	20	48	24	12.333N	87. 08 4W	79	540M8		074	0	F	0	D087	545
CGS-B	22	03	67	09	15	29	12.6531	87.823W	70	440 18		074	0		0	025	319
CGS 71	23	09	70	23	57	45	12.021N	87.4461	70	450M8		074	0		0	029	395
CG S-8	20	10	65	23	54	30	12.500N	61.JO0H	12	340M8		074	, 0		U	6.60	242
CG 5-8	25	- U 3	61	01	26	31	12.406N	01.016W	10	400MB		0/4	. 0		U	005*	582
LU3-10	25	08	04	05	03	18	12 JUN	a 1. (UUW	12	SUOMB		0 /4			ů,	00.5	31Z
CGSPDE	28	01	68	08	61	20	12.6304	9 1º 40 0M	13	44UM8		0/4	· U		u C	022	319
- CG 5-8	31	12	63	14	22	07	12.540UN	81. 900W	11	450MB		074	U Q		0	007	302 605
06280F	24	05	60	11	15	20	12.000N	NDO DUUK	19	0 10 M 01 C		015	0		0	043	473 445
103 38 105 100	13	00	40	人名	12	22	LLOYZON	000 2078	11	SKONO		0.14	, Å	F	57089 4	104	***> 570
003 38	13	, V.D	67 40	24	10	22	VIC OPO 1 1	56 500 W	17 77	200 PD		0.14	, n	. <b>r</b>	D FUBKK	104	01C 412
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1000 M			70	14	<i>ו ב</i> הי	6.C 63	13 51 200	86 722L	70	510 MP	2	0176	. ^	K۳.	57580 M	044	575
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003 0175	20	1 U Z	21	61 07	2 V 6 O	74 20	12.5004	87, 500W	ių Ni	0		0/14 7/2 A		6.	720044	с. 44	720
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155	24	, na	50	00	31	37	11 .6R ON	86. 4004	AL	ň		074		0	ASADAS	*	638
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- D G M I I	4 23	្តែ	16				11.00	85,50	N	Ď						***	560
DEM 25	5 12	, 7	59				11.50	86.00	A	กี้						<b>本</b> 承応	547
D 6M 31	3 74		63				12.40	87.40	N	£						森森山	505
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DEM 32	1 1	· • •	64				12.50	87.10	N	ñ						冷容者	540
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CM 201	7 7 55				12.50	88.00	N	F		A3-7			*	515
M 206	13 10 55				12.02	87.00	••	Ē					*	358
M 258	15 8 59				12.20	87.30	N	Ō					*	557
M 144	20 2 40				12.50	87.50	••	ē					*	681
M 139	25 4 38				12.20	86-90		- Č					*	676
M 141	9 2 39				11.10	86.20		Ē					*	446
M 147	5 8 4 4				12.50	87.50		Ē					*	425
M 157	2 4 51				12.00	87.00		Ē					*	419
₩ 158	6 5 51				11.00	85.50		Ē					*	353
M 173	12 3 52				11.00	86.00		Ē					*	389
4 179	21 2 54				11.90	87.00		ε					*	480
M 182	27 11 54				12.00	87.00		E					*	373
M 2C4	29 8 55				12.00	87.00		E					*	458
4 2 08	21 4 56				12.03	87.33		D					*	581
M 247	31 3 59				13.00	87.00		E					*	482
M 249	22 4 59				11.50	86.50		D					*	591
M 252	30 5 59				11.00	66.00		E					*	448
M 262	21 1 60				12.00	87.25		8					*	420
M 264	15 2 60				12.00	87.00		E					*	390
M 322	9 8 6 3				12.90	87.40	80	ε					***	383
M 369	24 5 68				12.50	86.50	79	5.1					***	5.1
M 154	13 11 49				11.00	85, 50	60	E					*	384
M 260	19 11 59				12.00	87.00	60	E					*	397
M 263	26 1 60				13.00	87.50	60	D					*	580
4 267	10 7 60				12.50	86,00	150	6.0					*	6.0
M 289	22 12 61				11.90	85.50	49	E					*	393
₩ 311	11 2 63				11.60	87.50	. 41	E					*	496
M 314	25 4 63				12.23	87.30	75	E						415
M 180	21 2 54				12.50	87.00	60	E					# `*	420
M 248	14 11 58	• •		••	12,36	80.31	12		0.10			•	*	670
2-8	01 10 63	10	30	31	10.200N	84. 50 UW	40	460 MB	078	0		0	02.2	412
5~8	30 12 66	10	30	15	10-100N	84. 700W	45	440 118	078	U Q		0	015	319
5-0 5-0	02 03 04	1.2	22	10	09.5000	354.70 UM	44	43UMC	078	0		0	007	302
5-D 5-D	20 04 00	02	42	27	09.5JUN	84. 100W	49.9	210MD	075	0		0	019	344
3-D	20 00 04	02	24	24	094200N	WUUH #FO	42	53040	010	0		0	071	502
3-0 5-4	16 10 65	14	22	55	09 0100	8 3 50 0H	11	51049	070	ň		ŏ	052	220
S-8	28 03 66	00	22	20	09.50 ON	93. 100W	46	40088	078	0		ő	000	212
5-8 5-8	17 07 66	00	14	03	09.200N	82.300	44	40000	080	ă		ă	013	312
5 31	16 04 70	05	04	41	09-632N	84. 2404	50	430 MR	078	ň		ň	G016#	362
5 53	05 08 70	13	22	05	09-841N	84.317	56	460 MB	078	õ		õ	0.23	412
S-8	15 10 64	21	09	02	09.60 ON	84, 00 OW	51	420MB	078	ŏ		ő	007	345
S	13 05 52	19	31	45	10.3001	85.300W	64	0	078	Ő		690PA S		690
S−B	13 10 63	05	١Ō	12	09-800N	84-100W	63	440 MB	078	Ö		0	012	379
S-8	27 03 66	23	12	49	09.800N	83.300W	61	420MB	078	0		0	018	345
S- 8	02 07 63	18	05	33	09,00.0N	83.000W	64	42 0 MB	078	0		0	011	345
S-B	13 05 67	12	48	00	09.24 7N	82. 395W	68	400MB	080	٥		0	008*	312
S-B	21 06 63	03	32	41	10, 700N	85.800W	73	500M8	078	0		0	022	478
TĘ	18 06 39	16	46	05	10.030N	83.000W	70	0	078	0		6 50 PA S	BCB	650
S~8	01 05 66	22	28	45	09.600N	83.900W	71	430 M8	078	0		0	018	362
LE	26 04 16	02	21	30	10.030N	85.000W	0	0	078	0		730PA S	* 1	730
TE	21 12 39	20	54	48	10.000N	65.000W	0	0	078	0		730PAS	*	730
TE	06 12 41	01	25	01	10.50 ON	85.25 OW	0	0	078	0		600PAS	*	600
TE	22 12 39	04	44	00	10.00 ON	84.50 CW	0	0	078	0		675PAS	*.	675
S	09 09 52	12	54	42	09.200N	84. 200W	0	0	078	0	F	688PAS	*	688
TE	05 10 40	14	38	43	09.50 ON	84.25 OW	0	0	078	0		6 25P AS	· +	625
TE	27 10 40	05	35	37	09.750N	84-50 CM	0	0	078	0		675 PAS	*	675
5	19 07 56	23	26	25	09.500N	84.500W	Ö	0	078	0	F	600BR K	*	600
16	U4 03 24	10	07	42	09.750N	84.000W	0	- 0	078	0		700PA5	•	700

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≁ 10EN LU ≏LITE	rr 14	80	10	10.	3 KP 20	1 1	12 25 01	88 500W	90			072	0		5.75DAS	A A A	575
0012	20	11	41	03	52	26	13 1000	60.300W	81	4 0 0 M B		015	ň		DI DE AS	000	212
CCS-0	20	V7	60	0.0	22	29	13-1004	00+200W	01	400MB		073	0		0	000	316
	12	11	77	00	02	30	12 2/00	00- CON	<b>c</b> O	4 90 50	F	013	0	r	U A	0.21	402
EKL IL	11	UZ	12	0.9	14	100	13-2030	80.07 IW	80	970RD	2	075	0	r	0	0.01	420
	24	UZ QZ	04	02	24	12	13-030N	87.200	65	390MC		072	0		<u> </u>	000	200
66 5-6	05	07	60	14	40	24	12.8JUN	88.900W	87	410 MD		076	U C		0	011	329
CC2-8	25	12	66	02	02	19	12.9004	88.500W	88	450148		076	0		0	023	39 2
CGSPDE	06	12	67	02	53	06	12.530N	87.2008	87	530M8		0 74	0		0	057	528
CGS 48	- 26	07	69	07	21	00	12.62 5N	87.798W	84	480 MB		074	0		٥	039	445
CG S-B	18	04	67	13	05	15	12.765N	87。943 H	84	390 MB		074	0		0	00 7*	3 0 0
CGS-B	01	08	64	80	55	49	11.80 ON	87.000W	88	430MB		074	0		0	008	362
CG S-B	23	04	67	14	44	10	11.525N	86. 480 W	82	44 O MB		074	0		0	014	379
GUTE	07	03	31	00	41	56	11.500N	85.500W	80	0		075	0		600P AS	ACB	600
C GS-B	10	12	66	01	09	39	10.30 ON	85.10 CW	87	430M8		078	0		0	011	362
CGS-B	19	07	65	22	14	21	10.600N	85.30 OW	80	460 MB		078	0		0	019	412
NOS 31	01	05	71	14	32	12	13.25 9N	88.499W	93	540 MB	5	073	0	F	0	053	545
CGS-8	16	<b>Q</b> 3	64	06	06	51	13.500N	88.30 OW	92	390MB		073	0		0.	800	300
155	06	05	51	23	03	32	13.00 ON	87.800W	96	0		072	0		625TAC		625
GUTE	08	07	39	21	31	44	12.500N	88.000W	90	0		076	0		550PAS	CCC	550
CGS-B	09	02	66	06	22	44	12.70 ON	67.800W	98	440M8		074	ō		0	021	379
CG S-B	20	10	65	23	54	51	12.730N	87.000W	51	560MB		074	õ		ŏ	032	578
GUTE	21	05	32	10	10	07	12.000N	87.500W	90	0		076	ñ		690PA6	٨٨٨	690
C GS=B	22	05	66	<b>06</b>	45	21	11.700N	86 6004	63	46048		074	ň		0	0.07	417
1 5 5	26	02	52	15	20	28	11 50 ON	84 3004	40	0		076	à	F	FUDENS	0.01	600
100	20	10	56	16	22	02	11 0000	86. 440W		0		074	5	r	597045		500
133	21	07	44	22	22	54	11 2004	04 E0 0W		A 1 0HB		074	~		<b>J</b> 01FA3	007	220
103-0 TAC	1049	21	64 57	02	20	2%	14 00.00	00.00W	100	4 LOND		070	~		. U E7674#	001	527
1AC 33	- 13	01	34	00	20	50	14.0004	00.4108	100	12040		012	v,		JAICIC	000+	242
CUTC	04	04	09	08	40	08	13.3340	98* 49 TM	105	43080		013	u o		575040	008+	- 30 Z
GUIE	07	UZ	51	0.5	50	- 22	13.000N	W100.13	100	0		072	0		DIDEAS		515
CG 5-8	05	03	64	02	>>	11	12.4001	87.600%	100	390MB		074	0		0	008	300
CG 5-16	12	04	66	03	34	22	12+60 UN	87.500W	104	390MB		074	0		U	009	300
CGS-B	C3	09	64	01	55	32	12.20 ON	87.00CW	1 08	40048		074	0	_	0	005	312
CGS	0.3	05	59	04	41	24	12.500N	87.500W	100	0	5	074	0	F	5601AC		560
ERL 4C	27	06	72	14	45	32	12.182N	86.588W	104	460MB		075	0		0	014#	412
CG S-B	C1	C7	64	00	42	55	12.030N	86.700W	1 08	43 OM B		0 75	0		0	008	362
NOS 75	03	11	70	08	39	12	11.644	86.112W	100	460 MB		074	0		0	D 02 3	412
ERL 73	14	12	72	03	55	41	11 . 85 8N	86.574W	104	460 MB		074	0		0	DO 19#	412
CGS 42	24	06	69	00	35	05	11.661N	85 <b>. 71</b> 7¥	1 00	530MB		075	0		500PAL	G085	500
CGS	10	11	56	00	08	27	10.500N	86.000W	100	0		077	0		600PAS		600
CGS	04	04	55	19	24	04	13.00 ON	87.000W	N	0		072	0		6 25 P A 5	*	62 5
DEM 310	16	L	63				13.00	86.70	N	E						***	367
D&M 328	21	12	63				13.40	87.20	N	D						***	570
DEM 207	24	1	56				12.20	86.70	I	7.3						*	7.3
D& # 137	12	1	37				12.58	87.16		D						*	590
DEM 243	27	12	58				12.80	87.30		D						<b>卒</b>	593
DEN 135	1	9	35				12.58	87.16		E						\$	465
DEM 138	25	9	37				11.00	85.00		E						*	444
D.EM 152	25	1	49				11.00	86-00		Ē						*	429
DEN 190	10	3	55				12.50	87-00		F						*	486
DEM TOP	20	4	55				12.50	87.00		n						*	597
DEM 236	20	1	57				12.00	86.50		Ē						¢	486
DUM 210	20		51				12000	06.50		<u> </u>						*	261
DGP 233		-0	20				12 02	80.00	1 00	<u>د</u>						÷	324
DGM 148	2.2	10	42				13.00	87.00	100	E F						*	202
DAM 133	11	0	44				12.50	87.00	100	2						, î	37:
DEM 159	11	5	51				13.00	87.50	100	E						<b>#</b>	401
DEM 169	17	12	51				11.53	86.30	96	E						來	315
DEM 171	. 2	3	52				11.50	86.30	100	D						*	572
DEN 183	2	12	54				12.00	86.50	1 00	E						卒	497
DEM 226	26	11	57				11.50	186₀50	1 00	Ē						傘	512
D 6M 171 D 6M 183 D 6M 226	2 26	3 12 11	52 54 57				11.50 12.00 11.50	86.30 86.50 86.50	100 100 100	D E E							* *

												A3 <b>-9</b>			
DEM 242 4	4 1 2	58			11.50	86.50	100	6.0						*	5.0
062 M3C	3 1	62			12.20	85.40	103	E						*	380
08 M 2 92 1	71	62			11.90	86.30	97	E						*	389
DEM 303 27	7 10	62			11.60	86-40	1 (6	Ē						*	360
155 16	5 02	59	17 5	54 15	13.11 ON	87-3404	- õ	õ			072	0	540T A		540
15.5 06	5 05	51	23 0	<b>DR 01</b>	13.00 ON	E7.800W	ā	ň			0.72	ň	CDASOTAL		650
50 22	7 05	51		22 21	13.0000	87 8004	ň	ő			072	ň	600TA		400
101E 01	7 02	34	22 2	LL LI LI 67	13 25 ON	87 7504	ň	Ň			072	Ň	4 35045		425
101E 01		10 1	56 7 22 1	TL 70	12 5000	PA FOOL	- 60	Ň			076	0	476040	,	475
JEM 130 23	, 00 , 5	73 6			12 00	87 60		4 Ö	001		015	v	UTJPA.	9 000 1	4 0
CM 336 11	1 5	47			11 40	07 60	100	04.7	000						047 883
		60			11 444	67.71	1 00	E 2 7	051	•					572
000 413 Z-	<b>7</b> 7	07			11.00	U fa / L	100		Urt		÷.,			***	202
BENICEF	11	O TO	159	KM	(31)	07 0000			•			•	-		
-0-3-18 ZC	5 U 8	1 60	ככו	10 21	12.0000	81.200W	112	4207	5		074	U .	U	000	393
.6.3 <del>-</del> 13 [/	1 08	04	19 0	J5 44	12.400N	86.800W	1 10	450 M	5		075	0	0	00.8	399
.65-B 30	0.04	67 (	13 1	10 49	12.632N	86.852W	115	#ZOM	U		075	0	0	009	345
-65-B 02	z 11	64	07 (	U7 57	11.8004	86. 900W	117	460M	8		074	0	0	009	412
GS-8 28	8 07	64 (	2 5	53 26	11.50 ON	86.400W	111	420 M	в		074	0	0	006	345
GGS-8 12	2 04	61 3	22 2	20 33	13.20 ON	88.900W	122	0	6	•	0 73	0	D 588PA	S	588
GS-8 01	7 08	66	04 L	1 30	11.030N	86.200W	125	410M	8		074	0	0	009	329
GS-B 0	1 09	63 ;	22 5	5734	11.30 ON	85.500W	120	440 M	B		075	0	0	01 0	379
GSPDE 01	7 07	68	19 4	49 36	14.678N	88.939W	134	450M	6		0 72	0	0	017*	395
CGS-B 23	3 0 5	61	16 4	44 59	12.700N	87.300W	138	0	. 6		074	0	DF 650PA	5	650
CG S-8 21	1 01	65	20 4	43 55	12.300N	86.700W	1 38	440M	<b>B</b> :		075	0	0	016	379
GUTE CS	5 10	25 (	04 0	07 07	12.250N	85.25 DV	1 35	0			0 75	0	675 PA3	5 88A	675
SUTE OS	5 11	26	07 5	55 38	12.300N	85.800W	135	0			075	0	700PA5	68 A	700
CGS-8 07	7 08	64 (	08 2	21 03	11.800N	86.900W	130	470 M	ß		074	0	. 0	010	42 8
CGS-8 12	2 08	64	1.2 4	47 46	11.400N	86.100W	135	410M	6		074	0	0	007	329
GSPDE 14	4 07	67	18 (	02 08	13.50 ON	88.800W	147	460M	8		073	0	0	014	412
CGS-8 17	7 09	63 /	03 4	48 09	12.600N	87.100W	144	390 M	B		074	0	ø	007	300
NOS 41 11	1 06	71	11 5	51 40	12.647N	86.9671	148	450M	6		074	õ	ō	024*	395
CGS-B 24	4 0 4	64	14 4	40 28	13.30 ON	88. 80 OW	158	51 0 M	8		073	0	Ó	044	495
G SPDE 20	0 08	68 (	00 3	34 04	13.105N	67.833W	157	430 M	B		072	0	Ō	014	362
CGS-8 16	6 12	65 /	05 2	23 06	12.60 ON	88. 800W	1 52	440N	8		076	0	0	019	379
CG S-8 04	6 03	67 2	23 3	31 25	12.389N	87.127W	159	41 OM	8		074	0	0	008*	329
CGS 03	3 05	54	17 1	13 32	12.00 ON	86.000W	150	0			075	0	600PAS		600
CG SPOE 28	8 01	68	18 2	20 49	12-10 ON	86. 900W	152	440M	ß		075	ō	0	015	379
GUTE 22	2 07	19	22 0	01 35	12.000N	85.00 CW	150	0	-		075	Ō	650PA	5.00	650
DEM 209	9 8	56			12.82	86.00	Ň	Ď			•••	-		***	571
31 00 E M3 C	6 8	62			12.60	85.60	N	Ď						***	562
10 M 246 1	- J 5 7.	59			12.00	85,00	14	Ĕ						*	386
10 EPE M3C	8 1 2	68			12.10	86.90	i 52	4.4						***	4.4
6M 231 2	3 12	57			12.50	86-50	150	F						*	368
AN 265 3	3 5	61			12.20	86.90	124	Ē						*	381
* BENIGEE	16	o m	215	5 K M	(41)										
GS 74 1	5 0 9	68	04	32 04	13.45 AN	87.2434	1 64	390M	8		072	0	a	009+	300
RL 22 09	9 04	73 (	<u>1</u> 31	17 48	12.267N	86.553	167	470M	B		075	õ	õ	035	478
G SPDE 1	5 10	67	08 0	0 50	11.90 ON	86.000	162	620M	8		0 74	ō	ő	083	677
GS-8 02	2 07	67	$\frac{1}{22}$	0 48	13.700	88.900	1 72	4104	Ř		073	ñ	ő		320
105 16 19	9 02	71	16 9	59 40	13.5624	88.795	176	520M	ă 3		073	ñ	FŇ	0042	513
65 51 17	7 07	60	13 3	76 22	17.5004	57.004U	175	A LON	0 J R		074	õ		6012	370
	ינט י ילית ו	65	16 5	57 20	12 1304		1 72	MUTTE 420M	0		074	ň	U A	0012	263
	1 U / 6 / 1 I	67	10 2	1 3U 04 44	12. LJUN	0 /+ 30 UW	1 10	-+ 3 VP	Ð		014	Ň.	7 20 0 4 7	007	704
001E 20	0 UL 6 กา	- <b>11</b> - 20	10 V	67 14 67 14	12 01 4	00-27UW	170	5404	•		017	0	E EROPAS	N 00 A	120
- 1 C C C C C C C C C C C C C C C C C C	7 03	70	יי סע ר פו	77 LO	12 4211	CO+ / 7 7 W	1 07	50UM	ย • 0	,	V 17	õ		021	20V 40F
	+ U3 7 AP	A7	12 7	77 IQ 78 Ec	12 2004	00.02JW	1 02	210M	0		072	0	0	021	477
CC 200 - 27		91	13 (	0 0 00	12.500%	00.200W	107	2201	0		075	0	. v	000	212
CG SPDE 27	0.04	66	10 2	40 87											-
G SPDE 27 G S-8 30 G S 6 8 04	006	66 70	10 3	39 UQ 19 K4	12.541M	88 212U	101	4000	0		072	ă.	Å	0104	212

													42 10			
C C C DD H		<b>64</b>	<i>.</i> 0	0E	63	3.9	13 0414	00 74111	1.00	C 2041	,	4 7 2	A2-I0			5.20
	27	00	72	10	52	33	13.9418	00. IOLW	100	530M		075	0	5 0	0020	528
CAC 44	01	01	43	16	72	44	11 70 ON	85 500W	190	490 10		075	ů		022	220
CCS 67	20	00	70	04	42	46	11.473N	85.4794	192	54044	2	075	ň	54080K	022	540
CGS-8	01	07.	66	20	17	40	13.700N	88.400W	20	460.86	5 L	073	õ	340044	0192	412
CGS-B	09	12	64	14	22	03	13-20 ON	87.200W	200	390 44	í	072	ă	õ	00.8	300
FRI 45	28	<b>07</b>	72	13	53	40	13-151N	87.753W	2 09	440M	á	072	ñ	ň	000	370
CG 5-8	25	67	66	õõ	42	58	13.20 ON	87.800W	210	400MF	í	072	ñ	ő	006	312
ERI 60	12	ñ.	71	05	59	00	12.877N	87.3414	211	470M	, a	074	õ	ñ	0.26	42.8
CGS-B	19	01	67	02	19	23	12.561N	86.613W	2 00	450M	8	0.75	õ	ŏ	6024	395
GUTE	24	02	34	05	33	30	12.75 ON	86.750W	200	0	-	075	õ	6 COPA'S	A38	600
GUTE	07	04	44	13	32	58	12.000N	85.500W	200	Ō		075	ō	600PAS	800	600
CGS 11	29	C1	70	23	06	38	11.492N	86.086W	215	480M	3	0 74	0	0	G018*	445
GUTE	24	04	16	08	02	12	11-000N	8 5.000W	N	0		075	0	730 PA S	*	730
GUTE	05	10	50	16	09	31	11.00 ON	85.000W	N	0		075	0	CD770PAS	*	770
10 E M 3 GL	10	9	62				12.30	86.70	N	E					¥	370
D&M 121	25	10	28				12.30	85.80		С					*	622
D&M 162	9	7	51				11.00	85.00		E					*	466
DEM 189	7	3	55				13.00	£7. CO		ε					*	394
DEM 194	11	4	55				13.50	87.00		E					*	506
DEM 265	24	3	60				13.50	87.00		E					*	368
D&M 266	26	4	60				11.00	84.50		£					*	493
155	28	09	51	12	07	07	11.530N	86 - 300¥	20	0 0		07	40	575PA:	S #	575
D.&M 168	28	9	51				11.50	86.30	160	ε					*	466
DEM 274	22	3	61				11.80	86.80	172	E					*	449
D&M 118	10	2	22				13-00	8 5. 40	I	C	OFL				*	671
D6M 143	29	12	39				13.00	86. 00		E	OFL				ŧ	521
DEM 299	- 24	7	62				11.20	67.70	173	E	0 FL				*	390
+ 00034			e -				(									
~ CUSIA CGS-B	26	A 7	5 :	13	י י <i>יכ</i> הא	25	11.8308	88. 20 OM	9	44 M	1	0.76	0	0	01.0	279
NIIS 41	05	66	71	14	20	42	09.33 ON	84.2326	26	540M	, 	1078	5145	FÕ	082	510
FRI 47	04	08	73	00	44	42	09-838N	84. 586W	33	5 30 M	P 7	078	54MS	E 52088K	NOR3	540
ERL 60	05	0.8	71	22	5.8	08	09.64 IN	84.069	33	490M	4	078	0	0	NO19	462
CG S-B	27	03	64	17	12	36	09-200N	84.000W	33	420 ₩	3	078	ō	ō	011	345
CGS-B	13	04	65	04	46	43	09.70 ON	84.40CW	33	400M	8	0 78	õ	õ	006	312
CGS-B	15	10	64	21	04	11	09.130N	84.000W	36	430M	3	0 78	õ	0	011	362
CG S-B	20	02	64	09	54	12	09.500N	84.600%	33	430 M	3	078	ō	õ	009	362
ER L 13	26	02	73	00	43	39	09-606N	84.22 9W	33	470 M	3	078	4 OMS	F 0	NO 31	400
CGS-B	17	12	65	04	03	28	09.300N	84,20CW	35	420M	8	078	0	0	007	345
GUTE	09	03	37	15	40	20	09.000N	83.500W	30	0		078	0	6 40 PA S		640
CGS-8	09	08	66	11	12	39	09.300N	83.800W	35	470M	9	078	0	0	032	428
CGS-B	27	63	64	17	27	35	09.43.0N	83.900W	33	420 M	Β.	078	0	0	015	345
ERL 13	23	02	73	19	36	48	09.845N	<b>83.49</b> 3₩	33	470 M	3	078	42MS	0	N038	420
CG\$-B	21	07	66	13	53	23	09.100N	83 <b>. 900</b> W	33	400 M	3	078	0	0	011	312
CGS-B	10	07	66	19	18	57	09.70 ON	83.900W	33	410M	3	078	. 0	0	008	329
CG S-B	15	10	64	22	52	35	09.600N	83.700W	- 37	42 OM	3	078	0	0	011	345
C G S-8	31	07	63	18	33	28	09.200N	82.400W	33	410 M	B	080	0	0	006	329
C GS-B	C2.	04	64	15	25	41	09.500N	82.70 OW	33	3 90M	В	080	0	0	007	300
CG SP DE	02	07	68	16	15	48	09-045N	82.934W	33	420M	3	080	0	0	N007*	345
CGS-B	12	11	65	08	59	54	10.600N	84.400W	37	500M	В	078	0	0	037	478
ERL 36	14	04	73	08	54	29	10.711N	84.763W	33	480M	B	078	0	0	N034*	445
ERL 36	14	04	73	08	34	00	1 0.67 9N	84.759₩	33	570 M	3	078	65MS	CD650PAS	N117*	650
			RE		80 1	rn -	119 KM	(10)								
* COSTA	810	4 "					a ar (1851) - 1	W0								
* COSTA	RIC	12	66	17	21	56	10.210	84, 100W	82		4	078	0	0	01.8	362
* COSTA CGS-B FRL 11	R IC 11 25	A A 12 02	66 72	17 03	21 43	56 47	10.23 ON	84. 100W	88 88	43 0M	5 R	078 078	0	0	018 019#	362 412
* COSTA CGS-B ERL 11 GUTE	R IC 11 25 19	A A 12 02 11	66 72 48	17 03 01	21 43 04	56 47 24	10.230N 10.187N 10.030N	84.100W 83.414W 83.500W	88 88 80	43 0M 460M 0	3 B	078 078 078	0 0 0	0 0 700 PAS	01.8 0.19* BBC	362 412 700
* COSTA CGS-B ERL 11 GUTE CGS-B	RIC 11 25 19 11	A A 12 02 11 08	66 72 48 65	17 03 01 09	21 43 04 50	56 47 24 41	10.230N 10.187N 10.030N 10.500N	84.100W 83.414W 83.50CW 84.00CW	88 88 90 96	43 0M 460M 0 430M	5 8 8	078 078 078 078	0 0 0	0 0 700 PAS 0	01.8 019¢ 88C 014	362 412 700 362
* COSTA CGS-B ERL 11 GUTE CGS-B CGS-B	RIC 11 25 19 11 23	12 02 11 08 05	66 72 48 65 61	17 03 01 09 03	21 43 04 50 40	56 47 24 41 24	10.230N 10.187N 10.030N 10.500N 09.830N	84. 100W 83. 414W 83. 50 CW 84. 00 CW 84. 00 CW	88 88 90 96 93	43 0M 460M 0 430M	8 8 8	078 078 078 078 078 078	0 0 0 0	0 0 700PAS 0 538PAL	018 019* 88C 014	362 412 700 362 538

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												A3-11			
CGS-8	23	05	67 1	17 1	4 50	10. 197N	84.022W	119	430K8		078	0	0	008*	362
C G SPD E	04	07 (	68 )	15 L	5 59	10.464N	84. 056W	113	440 M 8	i	078	0	0	012	379
C G S-8	23	07	64 (	04 5	7 54	10.500N	83.90 GW	114	420M€	3	078	0	0	0 10	345
CG S∸ B	12	80	63 ]	17 1	9 05	09.830N	8 4. 20 OW	114	42 OM8	l .	078	0	0	007	345
061 M30	18	6	51			11.00	84.00	96	E					*	449
* PACIF	10	COA	STL 1	[NE	33	(M (12)									
CGS 55	12	9.0	70 (	09 24	4 11	12.015N	86.5428	33	590MB		075	63MS F	6 0 0 PA S	N077	630
CGS-B	11	0.5	66 (	05 5	7 02	12.300N	86.800W	33	400 MB		075	0	0	007	312
CGS 55	12	68	70 1	10 2	4 23	12.051N	€6.53 9W	33	560M8		075	55 MS	530PAS	N057	550
ERL 12	15	02	73 (	00 1	5 53	11.534V	86+473W	33	510 MB	i	074	50 MS	0	D053	500
CGSPDE	80	10	67	14 2	8 07	11.30 ON	86.000W	33	420M8		074	0	0	009	345
CGS-8	21	03	55 (	)9 <b>6</b>	2 41	11.700N	86.400W	35	520#8		074	0	0	036	511
	12	01	10	1 A D	8 59	11.1578	80.010	33	460/18		074	U Q	0	NULZ#	412
ERL 73	29	08	$\frac{n}{n}$	38 Z	6 72	11.54/N	86. 180W	33	490M0	1	074	42.86	0	NU 34	402
EKL II	24	08	/1 L 52	18 0	9 07	11.50 9N	8C.J2 JW		DIUME		0 74	42 23	0	NU49	420
DOM 172	2	12	22			11.50	00.30	35	12 17						500
D G P 1 1 4	2	32	26			12.06	06.50	33	С ·					-	401
Dam 233	2	c	22			12000	0 Ge 92	21	E					<b>.</b>	471
* ATLAN	n no	A ( 1	ne (	отн	(11)										
CG S-B	25	06	62	18 5	8 35	14.50 ON	8 2. 400 k	25	0		094	0	46 3P 4 1	015	463
~ G <b>S</b> 8	20	05	66 (	03 S	8 01	11.60 ON	82.600W	23	390.48	L	079	ő	0	009	300
C GS+B	ĩ	08	65	18 1	5 39	10.80 ON	83.200W	33	390ME	3	078	õ	ő	007	300
CG S-8	08	10	66 3	20 3	8 07	10-700N	82.4004	33	410 //8		079	õ	ŏ	008	329
GUTE	17	03	26	11 5	3 36	12.50 ON	82. 500W	50	0		094	0	690PAS		690
GUTE	06	12	37	21 4	3 09	14.030N	82.00 OW	60	õ		0.94	ō	600PA S		600
CGSPDE	17	07	68 (	06 2	3 11	10.3941	83.389W	19	510 MB	-	078	Ō	0	0052	495
CGSPDE	03	03	68 (	08 4	3 24	10.00 ON	83.100W	16	410ME	1	078	Ū.	ŏ	010	329
GUTE	20	03	36	18 4	6 28	11.00 ON	84. 00 OH	N	0		075	0	560PAS	*	560
GUTE	25	07	13	12 3	8 06	13.000N	83.000W	0	Ō		075	0	6 30PAS	*	630
SYKE S	07	12	57	22 1	8 51	13.55 ON	82.41 OW	ō	ō		0 94	Ō	5 10P AL	023	510
* MANAGI	UA 1	VOLC	AND	LIN	E	N (57)									_
C GS-B	09	05	63	15 0	6 24	12.70 ON	86.600W	33	410M6	}	075	0	0	008	329
ERL 2	05	01	72	11 5	2 26	12.236N	86, 236W	33	42 OND		075	0	0	NO1 9*	345
ERLI	03	01	72 (	04 3	1 04	12.311N	86.300W	33	410 MB	ļ	075	0	0	ND19*	329
DEM 131	11	7	33			12.23	8 <b>€.</b> 30	N	D					平半卓	583
DEM 132	24	8	33			12.23	86.30	N	U					東京市	531
064 196		1	21			12.20	86.30	N	D		- /			***	262
DEM 212	10	2	01			12.70	86.50	40	E						393
D&M 309	15	1	05			13.00	86.70	- 33	E F		D.C.D. 44			-	444
DGP 1C1	c		21			12.00	80.00		5		DEEP M	AT DE		1	487
06M 113	20	4	22 55			13.30	00,00		0			AT DE		*	510
DEM 224	50	<b>*</b>	55			12 50	86 50		U F		DEEP M	AT DE		÷	337
DGH 250	12	с 9	50			12.00	84 00		с с		DECP M	AT DE			470
DEN 41	14	Q	50			12 60	86.26	M	с n	v	DEEP H	HI OC		***	508
0 G F 41	11	4	50			12.60	00.00	14	ř	¥ M				***	674
DEM 43	27	4	50			12 48	A6 67	NI NI	С Л	v				***	551
DEM 44	τ,		52			12.42	86.55	N.	5	v				***	561
DEM 45	8	5	52			12.15	86.30	N' IA	r	v				***	692
16M 46	29	6	52			11.95	86.15	NI M	ñ	v				***	566
DEM 47	. /	ž	52			11,95	86.15	N	กั	v				***	575
DEM 49	8	4	53			11.95	86.15	N	ñ	v				***	547
DEM 50	29	6	53			11.95	86.15	N	Ď	v				***	595
DEM 1		ŝ	53			11.95	86-15	N	Ď	v				***	595
D6M 57	2	1	55			11.95	86.15	N	ň	Ň				***	540
DEM	ž	î	55			11.95	86.15	Ň	Ď	v				***	5 95
D&M 54		12	56			11.95	86.15	N	č	v				***	682
D&M 55			56			11.95	86, 15	N	č	v				***	653
			-					•	~	-					

															A3-12			1
D & M	56			57				11.95	86-15	N	C		٧				本本本	632
M 3 G	57	11	- 4	58				11.95	86.15	N	C	;	V				***	661
M30	58	25	- 4	58				11.95	86.15	N	C		V				***	656
DEM	59			58				12.42	86. 55	N	C	)	v				***	552
M3G	60	10	11	58				11.95	86.15	N	Ċ	2	v				***	644
D& M	61	27	1	59				11.95	86.15	N	C		v				***	680
DEM	62	27	3	59				11.95	86.15	N	C	)	v				***	581
M 3G	64			60				11.95	86.15	N	(	2	v				***	585
D & M	67		8	63				12.70	87.02	N	Ð	)	v				***	568
D &M	69	14	11	67				12.48	86.68	N	8	3	V				***	729
M 3 C	70	24	7	68				12.42	86.55	N	(	5	v				***	670
D&M	71	16	6	70				11.95	86.15	N	C		v				***	689
D & M	72	18	6	70				12.42	86.55	N	Ċ		V.				***	674
D&M	82		4	83				11.53	85.65	N	t	5	v.				***	574
M.3C	83		5	83				11.53	85.65	Ň	C	5	v				***	546
M3G	84	2	5	83				11.53	85.65	N	(	)	v				***	557
M 3 C	85	4	5	83				11.53	85.65	N	C	)	v				***	5 3 9
DEM	86	6	5	83				11.53	85.65	N	C	)	v				***	530
DEM	87	6	5	83				11.53	85.65	N	0	)	v				***	564
M3C	88	15	5	83				11.53	85.65	N	ſ	)	v				***	542
D&M	101	22	5	86				12.42	86.55	N	Ċ	;	v				***	628
D&M	1 09	1	5	11				11.50	85.70	N	6	2	٧				***	592
D&M	110	17	10	13				11.95	£6.15	N	1	D	v				***	557
M.30	149	11	2	46				11.60	85.60		C	2	V				***	696
D&M	151	15	7	47				12.50	86.80	N	0	5	v				***	643
M 3G	358	24	10	68				12.52	86.73	N	0	2	۷				***	611
D&M	428	3	2	71				12.50	86.70	N	Ľ	)	٧				***	581
D & M	431	3	5	71				12.70	87.00	N	1	D	v				***	581
<b>₩</b> 30	438	1	12	71				12.63	86.90	N	C	)	V				***	585
≭ M∆	NAGI	14	ARF	Δ 4	5 KI	<b>.</b>	(5)											
ERL	77	23	12	72	07	19	49	12.000N	86.189W	5	520	) M	8	075	0	0	6049	511
C G SP	DE	04	01	68	10	03	56	12.100N	86.300W	5	460	M	В	075	Ō	0	028	412
ERL	76	23	12	72	06	29	42	12.357N	86.11 9W	5	560	) M	8	075	62 MS	CD620PAS	G099	620
ERL	77	23	12	72	07	17	36	12.050N	86.378	5	500	O M	8	075	0	0	G 02 9	478
GUTE		31	03	31	16	02	21	12.25 ON	86.200W	õ	C	)		075	Ō	560PAS	*	560
* EU	λi S Ε4	r .			22	¥ M	10											
- 10 - 11 - 10 - 11 - 10	11 JE1 729	18	ארג ב. 2	~ 66	د ر	, <b>5</b> 7	10	13.00	87.50	м	1	n					***	546
Mag	304	24	11	62				13.00	87.50	25	Ċ						***	615
DEM	284	29	8	61				13.00	87.50	33	Ĩ	D					*	562
DEM	2 94	16	6	62				13.30	87.30	33	1	E					\$	369
Mag	166	6	8	51				13.02	87.50	33	5.5	5					*	550
ISS		03	08	51	00	23	58	13.00 ON	87.800W	33	(	)		072	0	DF600PAS		600
155		C3	08	51	05	25	44	13.000N	87.800W	33	Ċ	)		072	0	550PAS		550
ISS		02	08	51	20	30	17	13.000N	87.800W	33	Ċ	0		072	0	575PA 6		575

,

## EARTHQUAKES IN CHRONOLCGICAL ORDER

#### 0 \$ Ð M Y H C E D M I S E (THE FIRST DIGIT OF MAGNITUDES MB,MS A O OR RICHTER CORRESPOND TO UNIT ) Α N T A R τu Ų C Y Ν A R C Ř U Ō LATI-TUDE LONG I-RICHTER T T Ν MB MS RICHTER E D TUDE MAG MAG ε MAG MAG D&M 41 50 12.60 86.36 Ŋ D ۷ \*\*\* 598 DEM 42 11 4 50 N Ý 12.48 86.68 С \*\*\* 674 12.48 DEM 43 27 4 50 86.67 N Ð ۷ \*\*\* 551 DEM 44 52 86.55 N N N D C v \*\*\* 561 5 52 6 52 7 52 12.16 D&M 45 8 v \*\*\* 86.30 692 Ý D&M 46 29 \*\*\* 86.15 D 566 D&M 47 11.95 86.15 Ν 0 ۷ \*\*\* 575 DEM 47 752 DEM 49 8 4 53 547 595 11.95 86.15 Ν D ۷ \*\*\* DEM 50 29 6 53 Ŷ 11.95 86.15 Ν 0 \*\*\*

												-						
D &M	51		9	53				11.95	86.15	N	D	v				***	595	
<b>₩</b> 30	53	2	1	55				11.95	86.15	Ν	D	٧				***	540	
Μ3C		2	1	55				11.95	86.15	N	D	٧				<b>**</b> *	595	
Mad	54		12	56				11.95	86.15	N	С	V				***	682	
M 3 G	55			56				11.95	86.15	N	C	v				***	653	
M 3G	56			57				11.95	86.15	N	C	v				***	632	
D&M	57	11	- 4	58				ł1.95	86.15	N	C	¥				***	661	
D&₽	58	25	4	58				11.95	86.15	N	С	۷				***	656	
M 3 G	59			58				12.42	86.55	N	D	V				***	552	
M.3 O	60	10	11	58				11.95	86.15	N	C	V				***	644	
M 3 G	61	27	1	59				11.95	86.15	N	С	۷				***	680	
M30	62	27	3	59				11.95	86.15	N	Ð	¥				***	581	
M.3 C	64			60				11.95	86.15	N	D	v				***	585	
DEM	67		8	63				12,70	E7.C2	N	Ð	V				***	568	
M 30	69	14	11	67				12.48	86.68	N	8	۷.				***	729	
M 3 G	70	24	7	68				12.42	86.55	N	С	v				** *	670	
DEM	n	16	6	70				11.95	86.15	N	С	۷				***	689	
MBG	72	18	б	70				12.42	86.55	N	С	۷				***	674	
M3 (	85		- 4	83				11.53	85.65	N	D	v				***	574	
M 30	83		5	83				11.53	85-65	N	D	V				***	546	
MBG	84	2	- 5	63				11.53	85.65	N	D	v				***	557	
DEM	85	4	5	83				11.53	85.65	N	D	V				*** :	539	
МЗG	86	6	5	83				11.53	85.65	N	Ð	V				***	530	
DEM	87	6	5	83				11.53	85.65	N	D	۷				***	564	
M 3 C	88	15	5	83				11.53	85.65	N	D	۷				***	542	
DEM	101	22	5	86				12.42	8 č <b>.</b> 55	N	С	¥				***	628	
DEM	1 09	1	- 5	11				11.50	85.70	N	D	V				***	592	
<b>GUTE</b>		25	07	13	12	38	06	13.00 ON	83.000W	0	0		075	0	630PAS	*	630	
M 30	110	17	10	13				11.95	86-15	N	D	V				***	557	
D&M	1 1 3	1	5	16				11.00	85.50	N	D					***	547	
M 3 C	114	23	9	16				11.00	85.50	N	D					***	560	
DEM	111	27	02	16				11.00	8 5 50	N	C					*	650	
g u te		24	04	16	08	02	12	11.00 ON	85.000W	N	0		075	Q	7 30P A S	*	730	
GUTE		26	04	16	02	21	30	10.00 ON	85.000W	0	0		078	O	7 30P A S		730	
GUTE		29	06	19	23	14	23	1.3.50 ON	86.500W	90	0		075	0	675PAS	BÇC	675	
SUTE		22	07	19	22	01	35	12.000N	85.000W	1 50	0		075	0	6 50PA S	202	65 Q	
GUTE		28	03	21	07	49	22	12.50 ON	87.500W	N	0		074	0	730PAS	*	730	
M 3G	118	10	2	22				13.00	85.40	I	С	OFL				*	671	
GUTE		04	03	24	10	07	42	09.75 ON	84.000W	0	0		078	0	700PA S	*	700	
GUTE		05	10	25	04	09	07	12.25 ON	85.25 OW	1 35	0		075	Ö	675P AS	88A	675	
													•					

A3-13

													A3-1	14		
GUTE	17	03	26	11	53	36	12.50 ON	82.500W	50	0		094	0	690PAS		69
GUTE	05	11	26	07	55	38	12.300N	85.80 OW	135	D		0 75	0	7 00 PA S	8 B A	70
D&M 121	25	10	28				12.30	85.80		C			-		*	62
GUTE	<b>C</b> 7	02	31	03	30	35	13.00 ON	87.000W	100	0		072	0	575P AS	ccc	57
GUTE	07	03	31	00	41	56	11.500N	85.500₩	80	0		075	0	6 0 0 PA S	AC 8	60
GUTE	31	03	31	16	02	21	12.25 ON	86.200W	0	0		075	0	560PAS	*	56
GUTE	21	05	32	10	10	07	12.000N	E7.500W	90	0		074	0	690PAS	AAA	69
DEM 130	21	5	33				12.00	E 7. 50	90	6.9	OFL				***	6.
DEM 131	11	- 7	33				12.20	86.30	N	D					***	58
DEM 132	24	8	13	•••			12+20	86.30	. N	U			-		***	5:
GUIE	12	01	33	OL	11	42	11.000N	87.000W	N	0		074	0	560PAS	*	56
GUIE	24	02	34	05	33	30	12.75 ON	86.750W	200	0		075	0	600PAS	ABB	6(
GUTE	07	03	34	22	41	47	13.250N	87.75 OW	0	0		072	0	625PAS	*	64
GUIE	22	12	34	14	29	31	11.500N	87.000W	N	0		074	0	650PA S	*	65
DEM 135	1	. 9	35	• •			12.58	87-16	•	E					*	-40
GUTE	20	03	36	18	46	28	11_00 ON	84.000H	N	0		075	0	560PAS	*	-56
UEM 137	12	1	37				12.58	81.16		D					*	59
U&M 138	25	.9	37	1-		~~	11.00	85.00		E			~		*	- 44
GUTE	09	03	31	15	40	20	09.000N	83.500W	- 30	0		0 78	0	640PAS		64
GUIE	0.6	15	31	21	43	09	14-03 UN	82.000W	60	0		094	0	600PAS		60
DEM 139	Z5	4	38				12.20	86.90		C					*	6
DEN 141	. 9	2	39	• •		~	11.10	66.20	-	£			•		*	44
GUIE	18	30	39	15	46	05	10.000N	83.000	10	0		078	0	650PAS	8.8	- 63
GUTE	80	01	39	21	31	44	12.500N	88.000W	90	0		076	0	550PAS	CCC	5
GUTE	21	12	39	20	54	48	10.00 ON	85.000W	0	0		0 18	0	730PAS	<b>本</b> 1	C
GUIE	22	12	39	04	44	00	10.00 ON	84-500W	-0	0		078	0	675PAS	¥	6
GUIE	26	12	39	11	>>	11	13.25UN	88.25 UW	15	0	~~.	013	U	6 UOP AS	AAA	6
DEM 143	29	12	39				13.00	86.00		E	QFL				*	57
DEM 144	20	2	40	• •			12.50	87.50	~	C C		***			*	61
GUIE	05	10	40	14	38	43	09.500N	84.25 OW	0	0		078	0	6 25P AS	*	6
GUTE	21	10	40	05	35	31	09.750N	84.50 W	0	0		078	0	6 /5 PAS	*	6
GUIE	06	<b>UI</b>	41	09	48	34	11.75 ON	86.500W	- 50	U		074	0	600PAS		6
GUIE	60	10	41	04	22	13	10.500N	80.2504	0	U		077	0	SISPAS	*	2
GUTE	10	11	-91	09	39	40	13.250N	88.500W	80	0		0 13	0	575PA 5	AAA	2
GUIE	00	12	41	01	25	CI.	10.500N	85.25UW	0	0		078	0	600PAS	*	, p
067 147	2		44		22		12.50	81.50	2.00	E		0.75	~		, ₽¢¢	4
GUTE	01	04	44	13	32	58	12.000N	85.500W	200	0		075	0	6 CUPAS	BLL	- 61
U &M 148	2	10	47				13.00	87.00	100	t c					بېت ملىكىند	30
DEP 149	11	2	90				11.60	85-60			v				***	ĉ
DOW IDI	12		41	10	~ <	1.6	12.50	0 Ca BU	1 70	L L	v	0.76	~	7 20.0 4 5		
CUTE	20	11	41	10	00	70	10 000N	00+ 200W	110	0		010	~	120843	03A 007	7
OCHE IFS	72	1	40	<b>V</b> 1	04	24	10.00 UN	86-00	60	С С		010	u.	100PA5	*	
DAP 1.2	11	4	49				12 50	87.00	100	5					*	30
DEN 154	17	11	49				11.00	85.50	60	Ę					<b>4</b>	3
GUTE	0.5	10	50	16	09	31	11.000	85,0004	N	5		0.75	n	C 0 7 7 0 PA S	*	7
155	11	11	50	13	51	10	10.400N	85.700W		ă		078	ň	575245	*	5
DE ¥ 156	ŝ	- î	51		~	* •	12.20	86.30	Ň	ň		0.0	•	515140	***	5
DEM 157	5	4	51				12.00	87.00		Ē					*	- 4
DEM 158	6	5	51				11.00	85.50		F					*	3
DEN 159	εĭ	5	51				13.00	87.50	1 00	F					*	4
061 M30	18	6	51				11.00	84.00	56	F					*	4
DEM 161	8	7	51			,	12,00	86.00		F		DEEP M	AY	BE	*	4
DEN 162	ä	7	51				11 -00	85.00		Ē		"	• • •		*	4
DEM 166	6	8	51				13.00	87.50	33	5.5					*	5
DEM 168	28	9	51				11.50	86.30	140	F					*	4
200	06	05	51	23	0 A	01	13.00 ON	87.800	0	ñ		0.72	Ő	CD650TAC	*	6
122			51	22	03	32	13-00 ON	87.800	- sé	ŏ		072	õ	625740	•	6
155	06	_ () m								~		~	-			
155 155 155	06	05	51	20	22	21	13.00 0	87. 800W	0	0		072	ō	600TAC	*	6

															۵٦.	.15	
ISS		C3	6.8	51	05	25	44	13.030N	87.800W	33	0			0 72	0	550P4 S	
155		0.3	0.8	51	00	23	58	13.00 ON	87.800W	33	Õ			072	õ	DEGODPAS	
ISS		28	09	51	12	07	07	11.50 ON	86.300W	20	0	0		07	4 (	0 575P A	S #
DEM	169	17	12	51				11.50	86.30	96	Έ						*
M 3C	171	2	3	52				11.50	86. 30	100	D						*
D & M	172	3	3	52				11.50	86.30	33	E						*
M 3 G	173	12	3	52				11.00	86.00		E						*
155		26	02	52	15	39	28	11.500N	86.300W	96	0			074	0	F 600PAS	
155		13	05	52	19	31	45	L C.300N	85.300h	64	0			078	0	690PAS	
155		69	09	52	12	54	42	09.200N	84.200₩	0	0			078	0	🗧 투 688PAS	*
155		20	11	52	15	37	17	12.100N	8 7. 90 OW	- 33	0			074	0	625PAS	
D &M	174	5	12	52				11.50	86.30	33	E						*
DEM	175		1	53				13.50	£6.50		D		OEI	EP M	AY	BE	*
M.3C	180	21	2	54				12.53	87.00	60	E						*
D&M	179	21	2	54				11.90	87.00		E				_		*
TAC		13	01	54	00	26	30	14.030N	86.416	1 00	0			0.72	0	5 75 TAC	
CGS		19	02	54	21	34	41	12.500N	87.500W	N	.0			074	0	F 663PAS	*
005		19	02	54	00	40	25	11.500N	87.500W	N	0			014	- 0	F 663PAS	*
665		20	02	54	- 02	00	43	11.5JON	E7.500H	N	0			0 14	0	F 587PAS	*
665		03	05	24	r.	13	32	12.000N	86.000W	1 50	0			075	Û	SUUPAS	
02.0	182	21	11	24				12.00	87.00	1.00	5 E						
0.64	103	- 20	12	24				12.00	20.30	1.00	E r						*
0.65	104	20	14	24				11.00	39 / 4 20		E						. ቸ
0 G M	190	- 11	2	55				12 00	87 00		С С						
	100	10	<i>ב</i> ג	55				12 53	87.00		с с						*
D 2 M	104	11		55				12 50	87 00		C E						*
ារ	200	30	4	55				12.50	86-50		ຄ		D EI	ED M	AV	BE	*
001 000	195	20		-55				12.50	67.00		กั			LF D	~ '		*
0.6M	196	30	4	55				12.00	87.00	N	6.0						*
DEM	2 01	7	7	55				12.50	88,00	N	F						*
08.M	203	16	8	55				11.03	87.00		F						*
DEM	2 04	29	8	55				12.00	87.00		Ē						*
ÇGS		04	04	55	19	24	04	13.000N	87.000W	N	ō			0 72	0	625 PAS	*
D&M	206	13	10	55				12.00	87.00		Ē						*
M 3 C	2 07	24	1	56				12.20	86,70	I	7.3						*
M 3C	208	21	- 4	56				12.00	87.33		D						*
Mac	209	- 9	8	56				12.80	86.00	N	D						***
CGS		19	07	56	23	26	25	09.50 ON	84.500W	0	0			078	0	F 600 BRK	<b>#</b> -
1 S S		24	10	56	14	42	12	11.79 ON	86.46 OW	N	0			074	0	DF730PAS	*
CGS		25	10	56	05	21	40	12.00 ON	87.000W	N	0			0.74	0	F 637PAS	*
155		27	1.0	56	15	33	02	11.880N	86.460W	90	0			074	0	587PAS	
CGS		10	11	56	00	08	27	10.50 ON	86.000W	1 00	0			077	0	600PAS	
DEM	2 16	28	1	57				12.00	86.50		E						*
M 3 C	218	19	5	57	• •			12.14	87.24	24	E				-		*
SYK	ES	27	10	51	18	29	10	15.970N	88.110W	56	0			093	0	400PA L	.008
DEM	226	26	11	57				11.50	86.50	100	E				~		**
SYN	5	07	12	21	22	18	51	13.55 UN	82.410	10	0			0.54	U	STOPAL	023
04.0	221	23	12	51				12.50	86.50	150	E E						*
0.64	2 37	4	5	20				12.00	80.50		E		0.54			D.C.	*
0.0 M	220	2	0	20				12+50	80.50	A1	5 5		UE	şΡ M	AT	BE	ب مد
0.60	2 20	10	0	50				11+10	07 20	N N	U E						***
0.6M	239	נ דר		20	06		20	12 00 01	81+20 69 E00H	×0	E 0			0.72	•	DE4 000 45	***
003	241	21	11	20	02		20	12 34	86 27	00	0			013	U	DECOUPAS	+
DEM	241	14	1 1 1	20				12+30	90.31	100	ند د د						-
	263	77	12	50				12 670	97 20	ton	-94U - n						
ם בש	2 7 3 3 4 5	21		50				11.70	87.20		0						*
ח פיט	244	15	2	50				12.00	85.00		L L						
0.013	247	31	2	50				13.00	87.00		с 2						Ĩ
UGP	471	32	د	.,				1.3400	01+00		E						-

													A3-	-16	
D& ₩ 248	2	4	59				11.70	87.20		D					*
DEM 249	22	.4	59				11.50	86.50		Ð					1
DEM 252	30	5	59				11.00	86.00		E					4
DEM 255	12	7	27				12+05	86 00	21	10 E					و مغربته
DEM 256	12	ิล์	59				12.00	86.00	14	D E		DEED M	A V	RE	
DEM 256	15	8	59				12.20	£7.30	N	ñ		DECF	~ •	DC	,
D&M 259	11	9	59				12.00	87.50		Ĕ					1
155	16	02	59	17	54	15	13.110N	87.340W	0	0		072	0	540TAC	
155	24	04	59	09	31	33	11.48 ON	86.400W	N	0		074	0	638PAS	;
CGS	03	05	59	04	41	24	12.500N	87.500W	100	0	5	074	0	F 560TAC	
DEM 260	19	11	59				12.00	87.00	60	E					1
DGF 202	21	1	- 6U - 40				12.00	87.25	60	t o					1
DEN 265	15	2	60				12.00	87.00	90	5					
DEM 265	24	3	60				13,50	£7.00		Ē					
DEM 266	26	4	60				11.00	84.50		Ē					,
D&M 261	10	7	60				12.50	86.00	150	5.0					,
D&M 272	16	2	61				12.70	86.50	40	E					3
D&M 274	22	3	61				11.80	86.80	172	£					1
DEM 284	29	8	61				13.00	87.50	33	D					,
DEM 281	E 1	9	61	~			12.23	86.90	124	E					
CG 3~B CG S-B	12	03	61	22	20	21	13.200N	88.000W	100	0	4	074	0	► 6 13PAS	
CG S- B	19	05	61	09	25	41	12.80 ON	88.200W	122	0	5	075	0	E 463041	
CG S-B	23	05	61	16	44	59	12.700N	87.300W	138	0 0	6	076	0	0F6 50PAS	
CGS-B	23	05	61	03	40	24	09.80 ON	84.000W	93	õ	•	078	õ	538PAL	
D&M 289	22	12	61			-	11.90	85.50	49	E			-		
D&M 290	8	1	62				12.20	85.40	103	5					
DEM 292	17	1	62				11.90	£6.30	97	E					
DEM 294	16	6	62				13.30	87.30	33	E					
DEM 298	11		62				11.60	87.10	25	E	05				1
DOF 231	16	1	62				12.61	85.40	L 13	с р	UFL				**
D 6M 3 CI	10	ğ	62				12.30	86.70	N	F					**
DE M 302	28	9	62				11.60	87.20	N	Ē					**
CGS-8	30	01	62	08	34	23	12.700N	87.500W	49	Ō		074	0	F 488PAL	0
CG SB	25	06	62	18	58	35	14.50 ON	82.400₩	25	0		0 \$4	0	4 6 3P AL	0
D&M 303	27	10	62				11.60	£6.40	106	E					
DEM 304	24	11	62				13.00	87.50	25	ç					<b>本</b> 本:
06M 204	15	1	63				13.00	80.10	- 55	5 0	ĩ				
DEM 307	15	1	63				12.00	87.50	20	n					**
D &M 310	16	i	63				13.00	86.70	20	E					**
D&M 311	11	ž	63				11.60	87.50	41	Ē					:
D&M 313	26	2	63				12.40	87.40	N	Ε					**
D&M 314	25	4	63				12-20	87.30	75	E					1
DEM 334	11	5	63				11.40	87.50	100	D	OFL				**
DEM 311	30	6	63				11.40	87.30	33	4.2					**
DEN 335	14	8	42				12.90	87.40	80	t					**
048 333 035-8	25	02	63	กร	58	43	12.3001	88-200H	59 69	61 ANR		0.76	0	0	** ^
CGS-B	13	04	63	18	53	18	11.700N	87.800	33	410HD	,	074	ő	ő	ň
CGS-B	09	05	63	15	03	43	12.400N	87.000W	50	550MP	, t	074	ă	ő	- ŏ
CGS-B	09	05	63	15	06	24	12.700N	86.600W	33	410 MB		075	ŏ	ŏ	ŏ
CG S-8	24	05	63	06	10	09	12.10 ON	88.500W	42	440 M B	1	076	0	0	0
C GS-B	21	06	63	03	32	41	10.70 ON	85.800W	73	500MB	<b>i</b>	078	0	0	0
CG S-B	02	07	63	18	05	33	09+000N	83.000W	64	42.0M8	i i	078	0	0	0
CGS-B	02	07	63	22	00	48	13.70 ON	88. 900W	173	410 MB	1	073	0	0	_
C 62-8	04	07	63	01	43	20	12.80 ON	88.70 OW	55	410M8	3	076	0	0	0

												A3-17	• ·		
CGS-B	05	07	63	14	40	54	12.80 ON	88.90CW	85	410MB	076	0	0	011	329
26 <b>S-</b> B	30	07	63	12	25	39	11.40 ON	87.300W	33	420 48	074	0	0	005	345
CGS−B	31	07	63	18	33	28	09.200N	82.400W	33	410MB	080	0	0	036	329
CG S <del>-</del> B	12	0.6	63	17	19	05	09.800N	84. 200W	114	42 OMB	078	0	0	007	345
GS−B	28	08	63	05	55	51	12.600N	87.200 H	115	420M8	074	0	0	006	345
GS-B	31	68	63	13	08	46	11.93 ON	87.000W	48	490M8	074	0	. 0	018	462
16 S- 8	01	09	63	22	57	34	11.300N	85.500W	120	440 MB	.075	. 0	C	01 0	379
JG 5-8	08	09	63	05	28	31	12.30 0	87.900W	31	4 10 M8	074	0.	0	038	329
.63-8	11	09	63	03	48	09	12.60 ON	87.100W	144	390 MB	074	0	0	007	300
-63-8 -0 5-8	20	10	63	10	20	21	10.2001	8C. 000W	33	41000	077	Ů	0	008	329
CS+8	07	10	63	01	50	71 64	10.200N	N000 40	50	400 MG	070	ň	Ň	015	412
DEM 326	13	ÎC	63	0,1	,,		12.53	87.10	JU N				0	***	525
16 S~8	13	10	63	05	10	12	09-800N	84. 100W	63	440 MR	078	0	n	012	279
GS~B	06	11	63	21	49	57	12.23 ON	88.000W	37	410MB	076	ŏ	ŏ	010	329
CG S~ B	10	11	63	07	18	07	12.90 ON	88.500W	45	420 MB	076	0	Ċ	007	345
8M 327	23	11	63				12.00	87.20	N	C				***	605
CGS-8	16	12	63	06	23	20	12.20 ON	88.400W	34	430MB	0 76	0	0	010	362
CG S-B	20	12	63	22	28	31	13.200N	88.000W	64	430MB	073	0	0	005	362
826 M3	21	12	63				13.40	87.20	N	D		-		***	570
GS-B	31	12	63	14	22	07	12.40 ON	67.900W	77	430MB	074	, a	0	007	362
16M 329	18	2	64				13.00	87.50	N	D				***	546
164 331 267 831	11	3	04				12.50	87.10	N N	U E				***	540
16 M 332	60	1	64	19	3.8	10	14.9004	87 0004	11	с 470 МВ	072	0	0	005	212
65-B	กัจ	02	64	01	46	27	13.000N	88.000W	61	410/60	073	. 0	ŏ	00.5	329
G S	20	02	64	09	54	12	09.50 ON	84-600W	33	430 MB	078	ŏ	õ	000	362
CGS-B	21	02	64	07	24	08	12.80 ON	87. 900W	62	390 MB	074	õ	ŏ	007	300
G S-B	24	02	64	02	29	12	13.00 ON	87.200W	83	390 MB	072	0	Ó	006	300
C G S B	02	03	64	16	09	46	12.50 ON	88.000W	63	440M8	076	0	0	018	379
CG S-8	05	03	64	14	30	18	12.13 ON	88, 100W	53	43 OMB	076	0	0	009	362
CG SB	66	03	64	02	55	11	L2.400N	87.600W	100	390M8	074	0	0	800	300
GS-B	16	03	64	06	06	51	13.50 ON	88.300W	92	390M B	073	0	0	008	300
CG S B	27	03	64	17	27	35	09.400N	83-900W	33	420 MB	078	0	0	015	345
.63-8 .cs_8	21	20	64	11	12	30	09.200N	84.000W	ور در	4 ZU MB	078	0	0	011	345
,03-0 10,5-8	02	04	64	12	23	41 50	12 5004	92 . TUUW	33	570M0 420M0	0.00	0	0	007	300
65-8	04	04	64	60	43	20	12.50 ON	87 700W	- 2C - 63	42010	074	n	ŏ	007	362
CGS-B	24	04	64	14	40	28	13.30 ON	88.800W	1 58	SLOMB	073	ŏ	õ	044	495
CGS-B	29	04	64	08	08	41	12.10 ON	88.400W	33	390M8	075	ō	ŏ	007	300
CG S <del>-</del> 8	29	04	64	21	53	15	11.80 ON	87.600W	33	450M8	074	0	0	007	3 95
C G S B	30	04	64	15	05	57	11.200N	86. 700W	33	4 30 M 8	074	0	0	00 5	362
CG S – B	02	05	64	19	53	10	09.530N	84. 50 OH	44	43 OM8	078	0	0	007	362
CG S-B	15	05	64	05	46	32	09.80 ON	85,500W	33	420 M8	077	0	0	010	345
GS-B	15	05	64	12	10	25	10.50 ON	85.700W	33	450M 8	078	0	0	024	395
26 S-B	23	05	64	- 06	45	21	11.700N	86.600W	93	450MB	074	0	0	007	412
.63-8 .65-8	10	00	04	10	25	- 0.9	12.00 UN	81.90UW	55	420 MB	074	0	Ű	006	345 220
.us−p ^6\$ <b>-</b> R	16	00	04 64	11	12	47	12.600 UN	88.000	20 14	410MB	010	õ	v n	001	327
16 S- B	17	0.6	64	09	11	42	12.00 0N	87.200	33	41048	076	õ	n	005	329
GS-B	19	06	64	17	31	56	12.40 ON	88,100	53	400MA	0.74	õ	ň	011	312
CGS-B	20	06	64	05	02	37	09.230N	84. 400W	45	43 OMB	078	ō	õ	007	362
G S-8	01	07	64	00	42	55	12.000N	86.700W	108	430 MB	075	0	ō	008	362
CGS-8	Ç4	07	64	02	36	54	11.300N	86.500W	90	410MB	074	0	0	007	329
CG S- B	07	07	64	09	59	19	10.830N	86.600W	33	490 MB	077	0	0	010	462
G S+B	18	07	64	20	37	35	11.00 ON	87.000W	33	460 MB	074	0	0	01.0	412
CG S-8	21	07	64	07	01	59	13.10 ON	88.400W	68	470M8	0 73	0	0	030	428
:G S-B	23	01	64	04	57	54	10.5001	83.900W	114	42 O MB	078	0	0	01 0	345
G S-B	26	07	64	13	53	25	11-800N	88.200W	. 9	440 MB	076	0	0	010	379
.65-8	28	07	64	02	53	26	11.50 ON	86.400W	111	420MB	0 74	0	0	006	345

													10 10			
C 6 5 - B	29	07	66	<b>01</b>	54	10	10 00 08	44 20 MU	12	6 204.9		77	81-EA	0	007	3/5
C5.5+B	30	07	64	15	13	30	10.500M	86.2004	22	42088	0	77	0	0	005	247
0 000	30	07	64	n5	16	02	11.1000	86.200W	42	570 MB	0	74	0	ů	007	920 607
CGS-8	01	6.0	64	08	55	49	11_80 ON	87.0004	92	430 Mg	0	76	0	0	022	362
CGS-A	0.2	08	64	Ω4.	00	45	10.9004	86 2004	22	430110	0	77	ă	0	000	420
CG 5-8	07	0.8	44	0.8	23	03	11.80 ON	86. 9004	130	47088	0	74	ñ	0	010	420
CGS-8	08	08	66	15	45	10	12.500N	57.800W	£3	58088	0	74	õ	0	010	420
CG S-8	10	6.8	64	14	00	51	12.43 ON	88. 3008	71	400MB	0	76	0	0	006	212
CGS-B	12	0.8	64	12	47	46	11.400N	86. 100W	135	410MB	0	74	õ	0	007	329
C GS-B	15	08	64	14	43	03	12.03 ON	88.000W	39	400M8	ň	76	ň	õ	0.06	312
CG S-B	16	08	64	12	34	34	12.00 ON	88. 600W	33	430 MB	ő	76	õ	ñ	011	362
CGS-B	16	08	64	07	30	12	13.300N	87.600W	60	390 MB	ő	12	õ	õ	0.05	300
CGS-B	17	68	64	19	05	44	12.40 ON	86.800W	116	450 MB	õ	75	Ď	õ	008	395
CG S-B	20	08	64	08	26	52	11.700N	87.200W	25	430MB	ŏ	74	õ	ō	008	362
CGS-B	20	08	64	09	12	53	11.000N	87.500W	33	420M8	0	74	ō	ō	008	345
CGS-B	25	80	64	05	03	18	12.100N	£7.700W	72	400M8	Ō	74	Ũ	ō	035	312
CGS-8	29	80	64	20	51	54	11.430N	87. 200W	33	42 OMB	0	74	0	ō	005	345
CG S-8	30	08	64	15	20	50	12.600N	86.500W	54	460 MB	0	76	0	0	015	412
CGS-B	31	08	64	17	07	39	09 .60 ON	85.400W	33	420MB	0	77	0	0	006	345
CG 5-8	03	09	64	01	55	32	12.23 ON	87.000W	108	400MB	0	74	0	0	005	312
CG S-8	12	09	64	19	05	47	11.200N	86.900W	- 33	470 MB	0	74	0	0	014	428
C G S <del>~</del> B	04	10	64	06	30	14	11.30 ON	87.400W	33	420MB	0	74	0	0	007	345
CGS-B	15	10	64	21	09	02	09.60 ON	84.000W	51	420MB	0	78	0	0	007	345
C G S-8	15	10	64	21	04	11	09.100N	84.000W	36	430 MB	0	78	0	0	011	362
C G S-8	15	10	64	22	52	35	09.60 ON	83.700¥	37	420M8	0	78	0	0	011	345
CG S-B	29	10	64	12	21	52	13.230N	88. 50 OW	33	4 0 0 M 8	0	73	0	0	008	312
CGS-B	02	11	64	07	07	57	11.800N	86.900W	117	460MB	0	74	0	0	009	412
C GS-8	07	11	64	01	36	56	12.00 ON	88.000W	33	440M8	0	76	0	D	012	379
LLS-B	13	11	64	08	02	38	13.000N	88.600W	86	490 MB	0	73	0	a	02.4	462
CG S-B	21	11	64	10	55	11	13.400N	88.700W	33	4 10 MB	0	13	0	0	036	329
CCS-0	00	12	64	14	27	10	12.3000	800000	22	410MB	0	10	0	0	010	324
C G SB	00	12	64	14	22	22	12 2000	87 700W	200	20049		14	0	0	02.9	4/8
0-203	12	16	66	74	10	10	12 30 0N	88 900W	200	330M8	0	76	Å	U 0	000	343
C GS-8	13	01	65	02	19	4.9	10-100V	86. 300W	33	48068	0	77	ò	ŏ	000	445
CG 5~8	21	01	65	20	43	55	12.300N	86. 700H	138	440M8	0	75	ă	ň	016	379
CGS-B	15	02	65	02	29	48	09.90 ON	86.5004	33	55048	ő	77	ñ	ŏ	011	561
CGS-B	õi	03	65	15	17	45	10-830N	86. 70 OW	55	490MB	Ő	77	õ	õ	009	462
C6 S-8	21	03	65	09	42	41	11.700N	86.400W	36	520MB	ō	74	ō	ñ	036	511
CGS-B	22	03	65	00	17	27	11.90 ON	87.90 OW	33	430MB	Ō	74	õ	ō	007	36 2
CG S- 8	23	03	65	21	21	52	11.000N	86.600W	33	4 80 MB	0	74	0	Q	014	445
CG S-8	23	03	65	02	58	39	12.300N	88.200W	33	410 MB	0	76	0	0	008	329
CGS-B	23	C3	65	17	18	29	11.80 ON	88.200W	33	420MB	0	76	a	0	006	345
CGS-8	09	04	65	15	09	15	11.400N	87.400W	33	42 O MB	0	74	0	0	009	345
C G S-B	13	04	65	04	46	43	09.700N	84 <b>.40</b> 0H	33	400MB	0	78	0	0	006	312
CGS-B	24	04	65	13	25	41	12.70 ON	82.000W	33	440M8	0	94	0	0	009	379
CGS-8	31	05	65	20	46	54	11.130N	86.000W	28	470MB	0	74	0	0	03 0	428
CGS-B	06	06	65	08	34	17	11.100N	87.200W	33	460M B	0	74	0	0	005	412
065-3	07	àŪ	65	07	41	47	10.40 ON	86.000W	33	470M8	0	17	0	0	007	428
LG 5-8	08	06	55	01	23	59	IL.UUUN	86-800W	33	470 M8	0	14	0	0	007	428
665~8	18	00	65	09	28	21	11.500N	88.200W	33	4 30 MB	0	16	0	0	007	362
CG 3-D	23	06	45	12	21	40	12 4000	07.000W	24	450 68	0	14	0	0	028	395
CC S P	21	00	07 45	73	57	20	12 1000	010 70 00	35 174	4 10MB	Ű	74	ů	Ų	100	329
C G S-R	16	07	65	10	34	12	11 AAAM	88.000	710	43070	0	74	0	U A	001	202
C G S-B	16	07	65	11	21	10	11.60.0M	87.8004	22	4.80 M/B	0	74	õ	0	016	402
CGS-8	17	07	65	04	05	16	10. 10 ON	86,5004	22	430 MR	0 n	77	õ	0 A	004	- 772 - 762
CGS-B	17	07	65	ĩ3	59	46	12.20 DN	87. 900N	56	440MB	ő	74	õ	õ	013	379
CGS-B	19	07	65	22	14	21	10.600N	85.300	80	460MB	ő	78	0	õ	0 19	412
CG S B	30	07	65	06	33	30	12.03.0N	88. 50 ON	33	42 OMB	ō	76	ō	õ	009	345
											-	-		-		

												A3 <b>-19</b>				
CGS-B	11 (	80	65	18	15	39	10.80 ON	83,200W	33	3 90 48	078	0	0	007	300	
CG S-B	09 (	09	65	12	43	37	09.60 ON	85.300W	33	450MB	077	0	0	8 00	395	
CGS→B	27	09	65	17	37	53	12.930N	88.400W	33	420M8	076	0	0	007	345	
CG \$- 8	16	10	65	14	22	55	09.030N	83.500W	48	51 OMB	078	0	0	053	495	
C G 5-B	20	10	65	23	54	51	12.700N	87.00 <b>0</b> W	91	560MB	074	Q	0	032	578	
C GS-8	20	10	65	23	54	30	12.50 ON	87.300W	72	540M8	0 74	0	0	063	545	
CG S-B	02	11	65	22	44	41	10.530N	86.300W	69	450MB	077	0	0	010	395	
CGS-B	12	11	65	08	59	54	10.600N	84.400W	37	500MB	078	0	0	037	478	
CGS-8	21	11	65	02	19	12	12.130N	98.300%	25	930M8	076	0	0	008	362	
002-8	00	12	62	13	19	13	12.4004	87.400W	99 50	390MB	074	0	0	007	205	
CCS-0	10	12	62	17	57	11	12.400	87 3004	33	420M0	0.74	a	ň	011	345	
CGS-8	16	12	65	05	23	06	12.600N	88-800W	152	440MB	0.76	ñ	õ	019	379	
C GS~8	17	12	65	04	ñ3	28	09.30 ON	84.20DW	35	420MR	078	ă	Ô	007	345	
CG S-B	24 1	01	66	ŏ3	46	57	12.300N	88.400W	46	450MB	076	ŏ	õ	01.8	395	
CGS-8	09	02	66	06	22	44	12.700N	87.800W	98	4 40MB	074	ō	Ō	021	379	
CGS-8	23	02	66	01	02	01	09.730N	85.800W	35	4 00MB	077	0	0	008	312	
CGS-B	13 (	ΕO	66	21	46	23	14.200N	88.400W	36	4 20 MB	072	0	0	017	345	
CGS-B	27	03	66	23	12	49	09.80 ON	83.300W	61	4 20 M B	078	0	0	018	345	
CGS-B	28	03	66	00	33	30	09.500N	83.100W	46	400M8	078	0	0	008	312	
CG S-B	09 (	0.4	66	02	34	23	09.40 ON	84.200₩	47	5 30 MB	078	0	0	071	528	
CGS-8	09 (	04	66	02	42	11	09.50 ON	84.100W	49	570MB	078	0	0	079	594	
CGS-B	12 (	04	66	03	34	22	12.600N	87.60 OW	1 64	390M8	074	0	0	009	300	
CG 5-8	12 (	04	66	17	30	49	12.600N	88.000W	33	440M8	076	0.	0	019	379	
CGS~3	14	04	66	06	51	45	11.800N	87.500W	33	4 10M8	074	0	0	007	329	
CG2~B	16	04	60	13	21	40	12.33UN	88.400%	33	440MB	010	0	0	017	200	
CC 5-8	24	04 05	00	12	41	(5	1.5.1000	88° 3004	3.2 71	270 PD	015	0	ő	019	362	
C G S=B	04	05	60	10	12	4) 55	12.50 DN	87.700W	, L A R	510MR	076	ň	ñ	036	495	
CG S-B	11	05	66	05	57	02	12.300N	86. 800W	33	4 0 0 MB	075	å	ŏ	007	312	
C G S~B	20	05	66	03	58	οĩ.	11.60 ON	82.600W	33	390MB	079	ā	ō	009	300	
CGS-8	28	05	66	14	34	39	11.93 ON	88.100W	33	430M P	076	Ō	Ö	013	362	
CG S-B	20	0.6	66	10	39	00	11.900N	85.900W	187	400 MB	075	0	0	021	312	
CGS-B	01	07	66	20	17	49	13.700N	88.400W	201	460MB	073	0	0	049	412	
CGS-8	80	07	66	13	22	13	12.40 ON	88.900W	43	43 OMB	0 76	0	0	013	362	
CGS-8	10	07	66	19	18	57	09.700N	83.900W	33	410 MB	078	0	0	008	329	
CGS-B	13	07	66	80	20	58	12.60 ON	87.800W	56	530MB	0 74	0	0	073	528	
CGS-B	17	07	66	00	14	0.3	09.200N	82.300W	44	400/18	080	0	0	013	312	
CG S~B	21	07	66	13	53	23	09.100N	83.900W		400MB	078	0	0	011	312	
CG 5-8	24	01	66	06	11	55	12.20 DN	88.300W	61	410MB	076	0	0	013	329	
	24	01	60	10	20	24	12.200	88. 100W	210	41000	070	0	ů n	010	313	
CG 5-8	21	07	66	10	10	- <u>1</u> 0	12.40 01	88-1004	63	4 20MB	076	õ	ň	032	345	
CG3 D CG5-8	07	08	66	04	11	70	11.00:0N	86-200W	125	410MB	074	ŏ	õ	009	329	
CGS-8	09	08	66	11	12	39	09.300N	83.800W	35	470 MB	078	ō	ō	032	428	
CGS-B	11	08	66	09	50	41	10.50 ON	84.000W	96	430M8	078	0	C	014	362	
CGS-8	23	80	66	06	07	36	12.40 ON	88-200W	39	400MB	076	0	0	011	312	
CG S B	20	80	66	03	53	34	13.130N	68.200W	81	400MB	073	0	0	800	312	
C G S-8	08	10	66	20	38	C7	10.700N	82.400W	33	410MB	079	0	0	8 00	329	
C 65 – 8	12	10	66	20	20	06	11.23 ON	86.200W	45	5 10MB	074	0	0	054	495	
CG S- B	19	11	66	16	01	46	09.200N	85.800W	25	430MB	077	0	0	012	362	
CGS-B	10	12	66	01	09	39	10.300N	85.100W	87	430 MB	078	0	0	011	362	
CGS-B	11	12	66	17	21	56	10.20 ON	84-100W	82	430M8	078	0	0	018	362	
CGS-B	14	12	66	01	33	13	10.6001	86.800W	33	430 MB	077	<b>U</b>	0	008	302	
663 <del>-8</del>	23	12	00	24	TO	20	12 00 0N	01.100W	52	450M0	074	0	0	013	377	
663-8 66 6-9	22	12	00 64	21	22	14	13 3301	188 800UW	00 70	54 0MD	010 21	n	ň	000	545	
CG S-8	21	12	66	19	25	15	10.1000	84.7000	10	440MR	075 078	ő.	õ	015	170	
C 65-8	64	01	67	00	28	07	13.100N	88. 625	72	410MB	073	õ	ō.	010	329	
CG S-B	09	01	67	22	31	22	13.13 8N	88.98 IW	78	410 MB	073	ō	ō	008	329	
	<b>-</b> ·											-				

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CG S-B	16	01	67	15	30	47	10-64 IN	85.9204	33	470MB	078	0		n		428
CGS-B	19	01	67	02	19	23	12.561N	86.513W	200	450MB	075	õ		ñ	6026	395
CGS-B	29	01	67	20	11	22	11.95 3N	88.92 84	33	450M B	076	õ		õ	NO 18	395
CGS-B	30	01	67	09	30	27	12.19 6N	87.596W	8	410MB	074	Ō		ō	010*	329
CG S-B	06	03	67	23	31	25	12.389N	87.127H	159	41 OMB	074	0		0	008#	329
CGŞ-B	08	03	67	15	52	15	13.049N	88.127W	75	390MB	073	0		0	00 5*	300
C GS-B	68	03	67	23	07	02	15.19 IN	88. 782W	76	420M8	072	0		0	036*	345
CG 5-8	22	03	67	09	15	29	12.653N	87.823W	70	440 M8	074	0		0	025	379
CGS-B	25	03	67	07	26	37	12 .40 6N	87.876W	76	400 M B	074	0		0	005*	312
CGS-B	27	СЗ	67	14	40	13	12.22 IN	87.71 2H	54	42 OM 8	074	0		0	019	345
CGS-B	12	04	67	04	56	25	12.2171	88. 102W	33	480 MB	076	0		0	N 02 5	445
CGS-B	15	04	67	22	10	80	12.743N	88-163H	33	430MB	0 76	a		0	N036 🕈	362
C 65-8	18	04	67	80	24	17	11.419N	88.415	33	400M8	076	0		0	N007*	312
CC 5-8	10	04	67	08	29	12	11.7>1N	B7. 30 FW	65	460MB	074	0		0	02.8	412
003-0	10	04	01	07	05	08	10.749N	86.777W	53	480MB	077	0		0	041	445
COS-B	22	0.5	67	13	60	10	1201030	8 6 545W	84	39008	074	0		0	007*	300
CGS=8	20	04	47	15	10	10	12 6252N	00000000000000000000000000000000000000	115	640 MB	074	0		0	014	319
CG3-0	06	05	67	14	40	02	32 0002 N	80°07%M	112	72UM C 440M9	C10 c10	0	~	0	009	343
CGS-8	13	05	67	17	48	00	12071 WIN	82 2054	22	400m0 600 M2	015	0	г	0	NU3U	412
CGS-8	20	05	67	22	42	10	11.65 3M	86.7164	22	470 FO	080	0		0	NO12*	345
CGS-B	23	05	67	17	14	50	10.1970	94.022W	119	43048	078	ñ		ň	00127	242
CG SP D E	23	06	67	12	30	46	12.9304	87.8006	11	42 MMB	076	õ		ŏ	012	365
CGSPDE	25	06	67	22	52	12	10.700N	86.000W	33	400M8	077	õ		ŏ	00.7	312
CGSPDE	30	06	67	11	42	33	11.000N	86.60 CW	44	450MB	074	õ		õ	022	395
CGSPDE	04	07	67	06	12	57	10.800N	86.400W	33	410MB	077	õ		ā	016	329
CGSPDE	04	07	67	13	29	04	11.600N	87.200H	33	4 20 MB	074	õ		õ	010	345
CGSPDE	04	07	67	07	39	20	11.80 ON	87.300W	38	400MB	0 74	0		ō	016	312
CG SP D E	14	07	67	18	02	80	13.500N	88.800W	147	460 MB	073	0		0	014	412
CG SPD E	11	08	67	12	26	18	11.80 ON	85.9001	21	470M8	075	0		0	017	428
CGSPDE	27	8.0	67	13	80	55	12.300N	86.200W	1 83	520M8	075	0		0	060	511
CG SP D E	02	10	67	15	59	43	11.730N	86. 8 <b>0</b> 0₩	39	470MB	074	0		0	025	428
CG SPDE	63	10	67	19	22	39	10.40 ON	86.200W	33	450MB	077	0		0	019	395
CGSPDE	63	10	67	18	16	03	10.930N	85.90 CW	21	580MB	078	0		0	104	611
CGSPDE	04	10	67	00	12	12	15.70CN	88.600W	33	440 MB	072	0		0	010	379
COSPDE	04	1.0	61	06	02	10	10.700N	86-000	33	5 30 MB	077	0		0	066	528
COSPDE	90	10	01	14	28	07	L1 JJ ON	86°000M	د در	420148	0 14	Û		0	009	345
CESPDE	12	10	67	100	70 70	20	11.9000	60.000W	102	620 88	074	0		0	083	5//
COSPOE	12	23	67	86	22	20	10 400N	96 700W	23	430110	013	ů,		0	010	202
CGSPDE	06	12	67	02	53	05	12.5300	87.2004	10	52048	· 076	ñ		à	019	912 529
DEM 369	24	**	68	0/-	11	05	12.50	84.50	79	51	014	U		U	نرن مدينية	5 1
CGSPDE	04	01	68	10	0.3	55	12-100N	86.300	5	460MB	075	0		0	0.28	412
CGSPDE	26	01	68	10	37	56	12.700N	88.800%	60	390 MB	076	õ		ñ	007	300
CC SPDE	28	01	68	08	47	20	12.600N	87.900 W	75	440 MB	074	õ		õ	022	379
CGSPDE	28	01	68	18	20	49	12.100N	86.900W	152	440M8	0 75	Ō		ō	015	379
CGSPDE	01	03	68	16	34	44	11.70 ON	85.50 OW	190	480M8	075	0		ō	033	445
CG SPDE	03	03	68	80	43	24	1 0. 00 CN	83.100W	16	410M8	078	D		0	010	329
CGSPDE	14	03	68	10	09	19	12.00 ON	86.800W	25	450M8	075	0		0	013	395
CGSPDE	24	03	68	17	13	20	12.530N	86. 50 OM	79	51 OM/B	075	0		0	043	495
C G SPD E	01	04	68	07	28	28	12.40 ON	88.500W	33	440 MB	076	0		0	013	379
CGSPDE	<b>C</b> 3	04	68	00	06	00	12.20 ON	88.300W	33	430M8	076	a		0	011	362
CCSPDE	18	04	68	<b>C</b> /~	40	38	12.50 ON	88.600W	54	490MB	076	0		0	019	462
CG SPDE	28	0.4	68	10	03	31	11.800N	88. 800W	39	490 MB	076	0		0	039	462
CCCDDC	06	05	68	21	23	11	13.021N	87.734W	56	460MB	0 72	0		0	0024*	41Z
COSPUE	11	0.0	68	05	22	33	13.941N	88.7614	1 23	53048	073	0		ů ů	0056	528
COSPOR	02	07	08 40	10	15	48 60	09.045N	62. 934W	33	420MB	080	U		0	NOU /*	545 270
003705	09	07	60 40	10	47	27	100909N	0.0000	115	440 BB	078	0		U A	012	205
CREADE	16	07	60	4 7 02	77 25	20	10010011 10 7270	0003378 000070	1.34	450 MP	0.82	0	c	0	02.2	305
GOUTOE	7.5	V 1	50	<b>V</b> 3		<b>6</b> %	690291N	0000938	74	-900 PC9-	072	U	г	ų	0.9.5	232

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CG SPDE	17	07	68	06	23	11	10-394N	83. 389W	19	510 MR		078	0		0	0052	4 94
CGSPDE	20	0B	68	00	34	04	13.105N	87.833W	157	430M8		072	õ		ŏ	014	362
CGS 74	15	09	68	04	32	04	13-45 6N	87.243W	164	3 90M8		0 72	Ó		Ō	009*	300
CGSPDE	19	09	68	00	37	17	12.143N	88.714W	33	440 MB		076	0		0	N014#	379
CGS 77	16	10	68	06	80	45	13.893N	88.25 OW	16	430 M B	4	073	0	F	0	009	362
CGS 80	22	10	68	06	42	01	13. 20 8N	86.247W	64	470 MB	5	073	0		. 0	017	428
D &M 398	24	10	68				12.52	86.73	N	Cγ						***	611
GG \$ 92	16	11	68	15	14	37	11.082N	86.911W	- 33	460MB		0 74	3 9MS		0	N018	390
CGS 94	19	11	68	00	09	27	11.336N	86.7144	33	460MB		074	41 MS		0	N022	410
CG 5 89	21	11	68	07	19	34	11.203N	86.89 IW	33	4 50 MB		074	0		0	NO16	3 9 9
CGS 90	28	11	68	13	44	33	12.451N	88.006W	49	490 M毛		076	0		0	021	462
D& M 393	28	12	68				12.13	86.90	1 52	4.4						***	4.4
DEM 413	24	9	69				11.66	87.71	100	5.3 CFL					_	***	5.3
CGS 3	06	01	69	09	24	23	L1 .44 ON	87.245W	33	480M8		074	43MS		0	N026	430
-GS 3	06	01	69	09	44	41	11.410N	₹7.232W	33	430 MB		074	U		U C	011	362
CGS 4	15	61	69	06	57	22	11.338N	86.813W	12	4 2 UMB		074	U A	-	Ű	010	395
005 16	08	02	69	04	56	59	L5.624N	88.27 LW	33	4 JU M8	4	073	U E AME	F	U O	NUU 6	362
-03 15	20	02	69	01	39	00	15 274H	C/-+00%	12	うゆい 川道		012	C PRU C	٣	v o	0012	200
003 13	22	02	<b>۲</b> 0 ۵۵	02	101	74	12 1014	010244%	13	400/10		012	0		0	0000	443
003 14	10	0.2	60	01	16	27	13 34GM	97 466U	42 62	530M8		013	0		400B04	050	215
CGS 21	14	0.2	60	08	47	16	12.014	97273JN 87,7664	179	56000	4	075	ñ	F	SADAK	0 99 D1 /10	5000
16623	10	03	60	19	40	22	11_786N	88,087	23	470MR	Ŧ	074	õ	•	0	021	47 9
00325	01	0.5	69	21	10	53	12.677N	RR. 233W	71	4 90 10	4	076	ň	F	ŏ	0.38	462
16 200	04	64	69	DR.	43	06	13.534N	88.9814	105	430MB	4	073	õ	•	ŏ	00.8*	36.2
065 26	08	04	69	19	41	58	12.67 ON	68. 340W	76	480 18		076	ŏ		ŏ	023	445
565 32	24	04	69	22	29	46	11.53 9N	87.0224	50	440M#		074	õ		õ	022	379
CGS 33	03	05	69	03	19	06	12-987N	88.4494	77	450MB	5	073	õ	F	õ	032	395
CGS 38	13	0.5	69	18	11	39	11.52 3N	86.509W	72	4.60 MB	-	074	õ		ō	037	412
CGS 38	13	05	69	14	16	52	11.469N	86.355W	79	560M8		0 74	ō	F	5708RK	104	570
C GS 38	13	05	69	14	15	52	11.4081	86.369W	71	480 MB		074	0	-	0	037	445
CG S 38	13	05	69	16	39	27	12.447N	87.830W	33	420MB		074	0		0	NO0 7#	345
CGS 35	13	05	69	14	36	16	10.817N	86.338W	33	450 MB		017	0		0	N008*	39 5
CGS 36	13	05	69	17	38	28	11.784N	86.179W	46	490MB		0 74	52 MS		4008RK	042	520
CGS 38	14	0.5	69	13	49	03	11.518N	86.154W	62	480 MB		074	0		0	046	445
CG5 4 <b>C</b>	06	06	69	16	16	01	12.467N	88.000W	48	500M8	3	076	45 M S	F	0	051	45(
CGS 41	23	06	69	20	46	40	12.41 ON	88.052W	33	470MB		076	0		0	N033	428
CGS 42	24	06	69	00	35	05	11.661N	85.717W	100	530M8		0.75	0		500PA L	G085	500
CGS 46	11	07	69	05	57	12	10.189N	85.484W	30	470M8		078	0	F	0	025	428
CGS 45	11	07	69	07	51	04	10. 34 2N	85.369W	33	500M@		078	0	F	450BRK	N049	450
CG S 51	17	07	69	13	24	22	12.590N	87.006W	175	440 MB		074	0		0	G012	379
CGS 48	26	07	69	07	21	00	12.625N	87.798W	84	480M8		074	0		0	039	445
CGS 55	03	C 8	69	21	17	16	13.342N	88.342W	52	430MB		0 73	0		0	010*	362
CGS 54	15	80	69	01	43	11	09.4731	83.863W	9	440 18		078	0		0	022	379
CGS 59	04	09	69	06	25	28	13.216N	88.429W	53	460M8	4	073	0	F	U A	0.20	412
CGS 65	01	10	69	08	41	<u>1</u>	12.084N	28.358W	33	440MB	3	076	U A	F	Ű	NULL	379
	15	01	70	16	57	41	11.614N	80.929W	33	48088	-	074	ů v	-	U	*800M	445
065 8	15	01	10	16	52	42	11.512N	86. /33W	70	SIUMB	3	074	U	F	2128RK	046	>75
1.65 E	15	UL	10	19	08	59	L1. 15 /N	86.015W	33	45UM8		074	U C		0	NU12*	912
	20	UL	10	80	21	48	11-482N	86.3538	46	54UMB		074	ů		U	053	545
00511	29	01	10	23	05	58	11-492N	00.U86W	215	480 148		014	0			GUL 8#	445
	11	01	70	22	23	57	1 20 12 IN	60° 12 M	45	300MB		072	42 M3		0	050	400
005 12	12	02	70	11	22	11	12+1394	SC. DION	44	440718		075	U C		U A	013	519
00323	10	03	10	23	11	21	10 AD4N	00. U10 W	20	4707113 44049		074	6246		0	0.1 11	462
	20	0.0	70	10	20	10	10 42 0N	C1. 304W	39 1 6 7	510M/0		071	4075		u o	01.3*	450
	12	0.0	70	10	37	10 11	12.0031N	00.02.0W	102	21040		C10 070	0		ň	100	473
1000 J1	21	04	70	0.0	77	41	12.047N	87.88 AU	70	5 20 80		010	ñ		ñ	045	511
005 37	25	05	70	22	05	18	10.738N	WUDGALE	33	ASOMS		077	ñ		ŏ	NO14	446
003 31	05	07	70	05	42	05	12-561M	87.4464	33	450 MB		074	ň		ñ	N031	305
~~ · · · · ·			.0	ر پ	76	ر ب	75 430 10	~ · • • • • • •		47010		0.44			Υ.	1003	290

														A3-22				
CGS	54	20	07	70	04	58	05	10.366N	87.400W	33	460MB		077	0		0	NO 1 54	412
CGS	53	C5	08	70	13	22	05	09.841N	84.31 74	56	460MB		078	ō		0	023	412
CGS	54	07	08	70	13	03	14	12.325N	87.79 IW	59	450MB		074	0		0	016	395
6 G S	55	12	08	70	11	07	59	10.867N	87.229W	33	450 MB		077	0		0	N009*	3 95
CGS	55	12	68	70	10	24	23	12.051N	86.53 9W	33	560MB		075	55 MS		530PAS	N057	550
ÇGS	55	12	08	70	09	24	11	12.015V	86.542W	33	590 MB		075	63MS	F	600PAS	N077	630
CG S	62	02	09	70	17	51	35	10.432N	86.015W	33	430MB		077	Q		0	ND 0 9*	362
CGS	62	06	09	70	20	44	49	12.783N	88.595₩	75	450M8		076	0	F	0	017	395
CGS	71	23	69	70	23	57	45	12.02 IN	87.446W	70	450MB		074	0		0	029	395
CGS	67	29	09	70	04	42	46	11.473N	85 <b>.</b> 4791	192	540 MB		075	0		540 BR K	D132	540
CGS	68	60	10	70	15	18	54	13.561N	88.312W	192	460M8		073	0		0	018*	412
NDS	75	03	11	70	08	39	12	11.644N	86-1124	100	460MB		074	0		0	D023	412
NOS	80	25	11	70	05	38	12	11.745N	87.9201	36	480 MB		074	0		0	014*	445
D£¥	428	3	2	71				12.50	86.70	M	DV						***	581
DEM	431	3	5	71				12.70	87.00	N	D V						**	581
NO S	9	21	01	71	17	13	48	11.714N	87.794W	33	480 MB		074	0	F	0	NO1 4*	445
NOS	16	19	02	71	15	59	40	13.562N	82. 795W	1 76	5 20M8	3	073	0	F	0	D0 4 2	511
NDS	21	25	02	71	04	15	41	12.159N	87.489W	52	53 OM 8		074	0		0	075	528
NOS	30	26	04	71	10	32	20	11.422N	86.760W	69	470 MB	-	074	0	_	0	040	428
NOS	31	C1	05	71	14	32	12	13.25 9N	88.499W	93	540M8	5	073	0	F	0	053	545
NOS	41	05	06	71	14	20	42	09.339N	84.2324	26	540MB	3	1078	51MS	F	0	082	510
NOS	44	20	0.6	81	11	20	31	11.101N	36. 166W	60	490 MB		074	0		0	015*	462
NUS	41	LL	06	11	11	≫ I.	40	12.6% M	86.9674	148	450M8		0.74	0		0	024#	395
NOS	45	16	06	71	04	18	56	11.722N	88# 222W	33	450M8		076	0		0	NO12*	395
NO S	45	18	06	71	13	36	01	14.678N	87.56 TW	ſ	500MB		072	0		0	022	478
ERL	60	05	08	11	22	58	80	09-64 IN	84.069W	33	490MB		078	0		0	N01 9	462
ERL	50	12	08	11	05	59	00	12.81/N	87.39 IW	211	470MB		074	0		U U	026	428
ERL	11	24	80	11	80	09	01	11-5J9N	86.36.38	25	STOMB		0 /4	42 115		U	NU 4 9	420
ERL	00	2 ₫	80	11	0.4	21	51	11.889N	28.584	دد ده	500MB		076	3883		u Q	NU4 I	380
CDI	53	27	08	11	30	20	22	11.079/N	00 + 100 W	33 77	490M9		074	0		0	NO 34	%0∠ 370
ERL	74	10	69	1	10	33	21	00 0014		33	440 MO		077	0		0	NOUT	616
	( / 0 1	20	103	71	0.4	% ₹ ⊆ Ω	10	10 0740243	00° 201 W	22	200 FO		011	4 0416		0	N030*	400
CNL	01	1.9	2.04	1 A 7 1	00	27	10 14	20.02.00	000200W	22	410M0		074	4083		0	0.23	400
COL	01	08 75	1 1 1	12	22	20	10 26	1204121V	07 AEOU	40	49070		070	0		0	0.91	402
ENL EDJ	25	22	3 ±	73	04	00	20	12 14 04	87 430N	62	4 70MD		019	0		0	0.13	402 270
DOM	6.20	20	11	6 I 7 1	<u> </u>	υu	50	12 21 201	01203	-07 NI			017	v		U	***	577
EDI	~ <u>,</u> ,	03	54	5 L 72	202	31	~	12000 12 21 1 M	960 JU	22	410HQ		0.75	0		0	N/010±	220
EPI	2	0.5	01	72	11	57	26	12 32 LLN	86 236	33	41090		075	ő		ő	NO 10 #	345
EPI	e e	14	01	72	22	55	10	31 57 SN	87 6924	62	460MA		074	õ		õ	014	412
FRE	9	20	0.1	72	22	25	02	11.0820	86.75AW	43	450 ¥8		074	28.95		õ	017	380
ERI	7	30	01	72	10	10	07	11.261N	86.773W	48	460#8		074	44 MS		ñ	027	44.0
FRI	ċ	64	02	72	01	0.7	43	11. 21 aN	56. 891W	52	6 8 0 M B		0.74	0		õ	0.19	445
ERL	ιά	06	62	72	ĩô	05	31	10.59 2N	86. 4004	36	44 OM/8		077	õ		õ	008*	379
FRI	11	17	0.2	72	<u>ถ</u> ิจ	19	60	13,26 9N	88.6914	80	470 MB	5	073	0	F	õ	031	42.8
ERL	ĩŝ	19	02	72	19	41	33	10.674N	86.085W	53	470M@	-	077	õ	•	õ	N014*	428
FRI	ĩi	25	02	72	0÷	47	4.7	10.137N	83.414	88	460MB		0.78	õ		õ	019*	412
ERI	14	04	03	72	22	04	23	12.933N	88.74.31	64	470 MB	4	076	õ	F	õ	02.4	428
ERL	16	05	03	72	21	47	26	11.971N	67.914H	46	460 MB	3	0 74	ō	F	ō	020*	412
EK.L	32	30	04	72	10	55	19	12.8961	88.468W	77	440M8	3	076	ō	F	Ō	01 9	379
ERL	40	27	60	72	14	45	32	12.182N	86.588W	104	460 MB	-	075	Ó		Ō	014*	412
ERL	45	28	07	72	13	53	40	13.151N	87.753W	2 09	440#8		072	ò		Ó	016*	379
ERL	51	31	0.8	72	02	24	09	13,272N	88. 51.34	50	54 OM B		073	48 MS		0	06.8	480
ERL	58	26	09	72	03	20	16	12.231N	87.412W	37	460M8		074	38MS		Ó	016#	380
ERL	61	C1	10	72	06	00	51	11.015M	86.33 OW	49	420MB		074	0		Ó	036*	345
ERL	65	02	11	72	18	24	45	11.711N	87.9394	24	460 MB		074	ō		Ō	020*	412
ERL	66	19	11	72	04	35	24	12.973N	88.5246	73	560 MB		073	0		ō	065	578
ERL	71	11	12	72	12	52	04	11.403N	87.151W	27	440M8		0 74	D		0	D017*	379
ERL	73	14	12	72	03	55	41	11.858N	86. 574W	1 (4	460¥8		074	0		0	D 01 9*	412
ERL	77	23	12	72	07	17	36	12.05 ON	86.378W	5	500 MB		075	0		0	G02 9	478

														A3-23			
ERL	76	23	12	72	06	29	42	12.357N	86.1198	5	560 MB		075	62MS	CD6 20PAS	6099	620
EP L	77	23	12	72	07	19	49	12.00 ON	86.189W	5	520MB		0 75	Ó	0	GO 49	511
ER L	7.4	25	12	72	00	26	28	15.215N	88.943W	34	460MB		072	0	0	02.0	412
DEM	457	13	4	73				10.50	85.50	Ν	6.7					***	6.7
ERL	12	15	02	73	00	15	53	11.534N	86.473W	33	5 10M O		074	50MS	0	0053	500
ERL	13	23	02	73	19	36	48	09.84 5N	8 3. 49 3N	33	470M8		078	42MS	0	N038	420
ERL	13	26	02	73	00	43	39	09.606N	84.229W	33	470 MB		078	40MS	FO	NO 31	400
ERL	15	07	03	73	13	00	45	12.705N	88.027H	64	460Me		076	0	0	013*	412
ERL	22	09	04	73	03	17	48	12.257N	86.553W	167	470MB		075	0	0	035	428
ERL	36	14	04	73	80	34	CO	10.679N	84.759W	33	570 MB		078	65MS	CD6 50PAS	N117*	650
ERL	36	14	04	73	08	54	29	10.711N	84.763W	33	480MB		078	0	Q	NO 34#	445
ERL	36	14	04	73	09	19	09	10.26 ON	85.015W	- 33	430M8		078	0	0	N006*	362
ERL	30	07	05	73	11	54	36	12.344N	87.949 W	33	430MB		074	40MS	0	NO13	400
ER L	35	28	05	73	06	19	00	11.47 4N	87.266W	42	460M B		074	40MS	0	014*	400
ERL	42	05	07	73	08	08	07	11.949N	87.541W	48	43 OM/B		0.74	0	0	015	362
ERL	40	06	07	73	05	21	49	11.962N	87.588W	51	480 MB		074	0	0	023	445
ERL	41	07	07	73	07	07	55	11.842N	87.761W	55	430M8		074	0	0	015	362
GS	52	14	07	73	07	55	08	11.637N	£7.291W	46	490MB		074	44 MS	0	024*	440
GS	51	27	07	73	80	51	11	12.415N	87. 407W	33	45 OMB		074	0	0	NO1 7*	3 95
ERL	49	27	07	73	19	42	47	12.81 3N	86.674W	199	530MB	3	075	0	F 0	D111	528
EPL	47	28	07	73	20	48	24	12.333N	87.084W	79	540M B		074	0	F 0	0087	545
ERL	47	04	08	73	00	44	42	09.838N	84.586W	33	530 №8		078	54MS	F 5 2088 K	NO 8 3	540
ERL	47	C4	80	73	11	54	16	12.140N	88.983W	33	440Me		076	0	0	N008*	379
ERL	49	19	68	73	22	17	49	12.65 IN	88 <b>.5</b> 07¥	68	510M®	4	076	0	F 0	D033	495
# APPENDIX 4

# COMPUTER PROGRAM LISTING

	************************************
ათ	COL VARIABLE NAME VARIABLE DESCRIPTICN
ب ن ن ن د	1.5 – EARTHQUAKE RECORD CARD 1 CARD PER RECCRC (1044) 1-36 XMAG(1-9) COL 1/36 READ IN A FORMAT 37-40 XMAG(10) LETTER EARTHQUAKE PAGNITUDE
ىرىرىرى	CUTPUT 404444 104401 IS SAVED ON DISK, IT CONTAINS THE SAME INFORMATION AS THE INPUT, BUT THE LETTER MAGNITUDE HAS BEEN REPLACED BY THE RICHTER MAGNITUDE.
പംപം	o თე თავი არ არარი ის თავი ის თავი არი თავი არი არ არ არე არე არე არე არე არე არე არე ა
0000 1 0001	IY=1 Call Randk(IY,YFL,0) C0 100 1=1,1000 Format(1004) Format(1004) Call Randk(IY,VFL,0)
، د	IF (XM A6(9).EQ.E) EQ TO 110 IF (XM A6(9).EQ.D) GO TO 120 IF (XM A6(9).EQ.C) GO TO 120 IF (XM A6(9).EQ.B) GO TO 130 IF (XM A6(9).EQ.B) GO TO 140
د ء دەد	MRITE(10,2000)XMAG,XMAG(9) Fermatiloa4,31X,A4) Ge to 100
ر <b>۲۱ د</b>	MAG=[3_5+YFL*1。8]*100. 6C TO 109
<b>120</b>	MAG=(5.3+YFL*.7)*100. GC TC 109
ر 130	MAG=(6.0+YFL)*100. GC TC 1CS
2020 2020 2020 2020 299	MAG=(7.0+YFL*.7)*100. WRITE(10,2020)XMAG,MAG FCRMAT(104.31X,14) GCOTINLE Return ENC Subroutine Randk (1Y,YFL,iNDEX)

THIS SUBROUTINE GENERATES RANDOM NUMBERS

ບບບ

- IY=IY\*3141592694453806245
   IF(IY\*6Ee.0) GO TO 6
   S IY\*1Y\*2147483647\*1
   6 CCNTINUE
   IF(INCEx.GT.0) GO TO 8
   FFLEFLOAT(IY)\*.4656613E-9
   RETURN
   sDATA
   sDATA

THIS PROGPAM SORTS EARTHQUAKES BY DEPTH. THE BAND THICKNESS IS SET THE DATA IS READ FROM DISK. THE CARD PER EVENT. (844.13.1144) THE PUTPUT IS SAVED DN DISK AND CONTAINS THE DATA SDRTED BY Bandmith of 10 km starting at depth o COL 1/32 READ IN A FORMAT Dedth of hypocenter Col 36/79 read in a format NED=IND(N) IF(NED.FO.0) GD TO 210 IF(NED.FO.0) GD TO 210 WAITE(11,2010) NED, NDP PRIVI.NED, EQ AT DEPTH '15, PLUS' PRIVI.NED, EQ AT DEPTH '15, PLUS' DO 220 13, NDED DO 220 13, NDED I (XINF3(N,1,J), J=1,11) I (XINF3(N,1,J), J=1,11) DO FORAT(' '8A4,13,11A4) VARIABLE DESCRIPTION ? s GD TD 200 210 PRINT, ND EQ AT DEPTH\*, NDP.\* PLUS\* READ(5,1000,END=99)XIN1,NDP,XIN3 F0RMAT(844,13,1144) D3 400 J=1,8 XTNFI(N,NFD,J)=XINI(J) D0 500 J=1,11 XINF3(N,MED,J)=XIN3(J) G3 TP 100 VARIABLE NAME IF(N,GT,ZI)N=21 IND(N)=IND(N)+1 NED=IND(N) NDEP(N.NED)=NDP X I N1 N0P ENIX DC 200 N=1,21 NDP=(N-1)\*10 DC 130 F=1.21 130 TND(T)=0 THPUT FORMAT I+(01/d0N)=N **张士兴 安安士夫大夫夫女女** CONTINUE PRINT. 99 CONTINUE PRINT, ΩUTPUT \*\*\*\* 1-32 33-35 36-79 ยี่ 1000 220 400 500 2010 ى ç  $\cup \cup$ 

C 200 CONTINUE RETIAN EMD \$DATA

THIS PROGRAM FITS A LINE THROUGH A SET OF POINTS IN A PLANE USING REGRESSION ANALYSIS. IT IS USED TO LOCATE A SEISMIC LINE SOURCE GIVEN A NUMBER OF EPICENTERS. THE DUTPUT DISPLAYS THE SOURCE IDENTIFICATION, THE NUMBER DF Records for in the source, the congoinates of the centroid of the data as well as the slope and the depth of the line. 1 CARD (15,1844) NB OF RECCORDS IN THE SOURCE IDENTIFICATION OF THE SOURCE 1 CARD (15) NB DF SOURCES TO BE LOCATED LDS (4F10.01) LATITUDE OF THE EPICENTER LONGITUDE OF THE EPICENTER DEPTH OF THE HYPOCENTER REPEAT CARDS 2/3 NAST TIMES FOR THE NBST SOURCES VARIABLE DESCRIPTION IMPLICIT REAL\*8 (A-H, C-Z) DIMENSION HED1(18),X(200),Y(200),D(200),XM(200) RICHTER MAGNITUDE WFITE(6,2000)NBRC,HED1 FORMAT(\*0NUMBER DF RECORDS\*,I6,3X,1844) NBRC CARDS 2. SOURCE IDENTIFICATION
1 = 5 NBRC
6-77 HED1 XY=0.00 XT=0.00 YT=0.00 XT=0.00 XT=0.00 XT=0.00 RFAD(5,1000)NBRC,HED1 VARIABLE NAME 1.\*\* NUMBER OF SOURCES
1 - 5 NBST RECORD CARDS READ( 5, 1000 ) NBST DO 100 IS=1,NBST FOPMAT(15,1844) ( ) MX 0( INPUT FORMAT \*\*\*\*\*\* × REAL\*4 HED1 XB=0.00 YB=0.00 DB=0.00 YZ=0.00 XZ=0.00 OUTPUT 1-10 11-20 21-30 31-40 \*\*\*\* Б ۹°, 1000 2000 υU

DN 110 IR=1/NRPC READ(5,1010)((1P),X(1R),D(TR),XM(1R) FOPWAT(19X,F5.3,3X,F5.3,14X,F3.0,25X,F3.2) X(1R)=-X(1R)

1010

NB2 E= 0

\$ DATA

ALPH= (XY-XNBRC\*X8\*YB) / (X2-XNBRC\*XR\*XB) ALPH1= (XY-XNBRC\*X8\*YB) / (Y2-XNBRC\*X8\*YB) TF(D(TR),EQ.0.0)NBZE=NBZE+1 Y2=Y2+Y(IR)+Y(IR) X2=X2+X(IR)+X(IR) XY=XY+X(IR)+Y(IR) XYT=XYT+X(IR)#Y(IR) XT=XT+X(IR) \*X(IR) YT=YT+Y(IR) \*Y(IR) XNBRC 1=NBRC-NBZE PRINT, ALPH, ALPHI CONTINUE RETURN X(IR)=X(IP)-XB Y(IR)=Y(IR)-YB X8=X8+X(T9) Y8=Y8+Y(T9) D8=D8+D(T9) ALPH1=XYT/YT YB=YB/XNBRC DB=DB/XNBRC1 XB=XB/XNBRC AL PH= XYT / XT XNBRC=NBRC CONTINUE CONTINUE END 110 100 130

ARD (3FI0.0) X CODROINATE OF A POINT OF THE LINE X CODROINATE OF THE SAME POINT Y COORDINATE OF THE SAME POINT SLOPE OF THE LINE 1 CARD (3F10.0) X CORPINATE OF A POINT OF THE LINE Y CODROINATE OF THE SAME POINT SLOPE OF THE LINE SLOPE OF THE LINE CARD (2044) IDENTIFICATION OF THE SECOND LINE / (2044)
// CENTIFICATION OF THE FIRST LINE THE DUTPUT DISPLAYS THE IDENTIFICATION OF THE LINES AND THEIR THE COORDINATES OF THEIR INTERSECTION POINT. VARIABLE DESCRIPTION X=(AL1\*X1-AL2\*X2-Y1+Y2)/(AL1-AL2) IF{Y2.6C0.0.) X=X2 Y±AL1\*(X-X1)+Y1 1 CARD 1.- IDENTIFICATION 1 CAPD 1-80 HEDI 1 WRITE(6,2000)HED1,HED2 5 FORWAT(\* 2044) PRINT\*(LINE1\*,X1,Y1,AL1 PRINT,\*(LNE2\*,X2,Y2,AL2 PRINT,\*INTERSECTION\*,X,Y ----READ(5,1000,END=99)HED1 READ(5,1001)X1,V1,AL1 D0 200 1=1,2 READ(5,1000)HED2 READ(5,1001)X2,V2,AL2 PEARMAT(2044) VARIABLE NAME Z-- LINE PARAMTETERS 1-10 X1 2.- LINE PARAMETERS 1-10 X2 11-20 Y2 21-30 AL2 3.- IDENTIFICATION 1-30 HED2 FORMAT(8F10.0) AL 1 200 CONTINUE GO TO 100 99 RETURN 5 OUTPUT 11-20 21-30 \*\*\*\*\* τüς 0N3 1001 001 2000 J c J υL 

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I CARD (5FIC.C) X COORDINATE OF A POINT OF THE LINE Y COORDINATE OF THE SAME PCINT SLOPE OF THE LINE X COORD OF ORIGIN OF SEGMENT X COORD OF END OF SEGMENT THE DUTPUT DISPLAYS THE LIVE IDENTIFICATION AND PARAMENTERS AS AS WELL AS THE LENGTH OF THE SEGMENT. YS=ALPH\*(XS-X1)+YI YS=ALPH\*(XS-X1)+YI YE=ALPH\*(XS-X1)+YI XLEN=SCRT((XS-XE)+(YS-YE)+(YS-YE)) XLEN=SCRT((XS-XE)+(XS-XE)+(YS-YE)) 2000 FCRMT(\*0\*,2001HED1 PRINT\*(DATA\*,X1,Y1,ALPH VARIABLE DESCRIPTION L INE IDENTIFICATION 1.4 - I DENTIFICAT ION 1 CARD 1-80 HEDI I READ(5,1000)X1,Y1,ALPH,XS,XE FORMAT(8F10.0) 100 READ( 5,1001,END=99)HED1 VARIABLE VAME 2.- LINE PARAMETERS 1-10 XI 11-20 YI 21-30 ALPH 31-40 YX 41-50 YX 1001 FORMAT( 2044) DUTPUT ปีว \*\*\*\* QN B \$ DATA ں ں 

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A4-7

201 DF 202 IX=1.NBIC 202 V(IX)=ALDG(YV(IX)) C CHECK WHETHER THERE WILL RE DNF DR TWP REGRESSION LINES C IR=1 NBPT=NBIC IF(RMBK.EQ.O.) GD TO 300 C C	NRPT=0. DO 320 [X=1,NBIC IF(X [X],GGTMBK) GOTO 340 320 NPPT=NRPT+1	340 NBPTI=NBIC-NBPT+1 WRIFE(6,2110)RMBK,NBPT,NBPT1 2110 FORMAT(10TM0 STRAIGHT LINES WILL BE USED TO FIT THE DATA'/ 1 BREAK POINT MANTIUDE'F88.2,'' ',15,' POINTS IN THE FIRST LINE' 2 /' ',15,' POINTS IN THE SECND, LINE' 1 60 TO 300	330 NBPT1=NBFT-1 NBPT=NBFC-NBPT1 RMBK-0. IR=IP+1 D7 350 IX=1,NBPT X(IX)=Y(IX+NBPT1) 350 Y(IX)=Y(IX+NBPT1)	C 300 WRITE(6,2130)IR 2130 FORMAT(*0INTERCEPT AND SLOPE OF LINE*,15)	C COMPUTE ALPHA INTERSEPT C COMPUTE BETA SLOPE	C COMPUTE MEAN Smxx=0. Smxt=0. Smxt=0.	PRINT, NBPT, NBPT PRINT, NBPT, NBPT WRITE(6,3333)(Y(I),T=1,NBPT) WRIE(6,3333)(X(I),1=1,NBPT) 3333 FDRMAT(' '13F10,5)	DO 140 IX=1,NRPT Swx==Swxx+X(TX)*X(IX) Swz=Swx+X(IX) Swz=Swx+Y(IX)*Y(IX) 140 Swy=Y(IX)	XNRPT = NRPT YM= SYV/XNRPT XM= SNX/XNPT RFIA([R) = (SNXY-XNBDT★YM≢XM)/(SMXX-XNBDT★XM*XM)	ALPHA([F]=YW-BETA([R]*XM Write(6,2007)ALPHA([R],BETA(!?) 2007 Farmat("OALPHA",Fl0.6/*OBETA ",Fl0.6) C	IF(A.FG.OCR.T.EG.O.) G7 T7 360 Alphaba AlphakirlaLnG(A*T) Vrite(s.2008)Alphan 2008 Firmat(*ON7Rmalized Alpha*,Flo.6 //)
WRITF(6,2112)RMMN,RMTC 2112 FORMAT("OMINIMUM MAGNITUDE",12X,F10.2 / *00AGNITUDE INCREMENT FOR CDF ",F10.2) po 120 1=1,50 RmcK.remcK1+RMTC IFCMLW-LT-(RMCK051) GD TO 121 RMCK1=RMCK 120 WRITE(6,2220) RMMN,RMCK	2223 FORMAT(' THERE IS NO RECORD BETWEEN MAGNITUDE',F8.2,' AND',F8.2) 121 Continue Write(6,2004) 2006 Formationed	WPITE(6,2003)[RWIIX),IX=1,NBRC] 2003 FORAT(0 *13F10.2) RWIC2ERMIC#*5 NBIC=0 NBIC=0 S(1)=RMCK1+PMIC2 NBIC=0 S(1)=12=1.49	<pre>102 THIS(I)=0 THIS(I)=0 THIS(I)=0 TO 103 IX=1,NBRC NBRCC=(FMMIL)/RMIC)+.999 THIS(NBRC)=FHIS(NBRC)+1 IF(NBRC.6T_NBIC) NBIC=NBRC</pre>	IO3 CUNTINUE IF(Skipd2.e0.1.0R.Skipc0.f01) G0 T0 133		134 IF(1.6E.NBIC) GO TO 133 134 IF(1.6E.NBIC) GO TO 133 NBICL=NBIC-1 N9 132 K=I.NBIC1 V/V//////////////////////////////////	132 [HISK)=[HISK+1) NBIC=NBIC-1 GO TJ 134	133 CONTINUE iffumic.t.2) GD TO 111 compute CDF vymmic.f.Hiss(NBIC) NRTC1=HNST(NBIC)	00 130 1×=;^NBIC K×=MBIC1-1X 130 YY1X1=YYKX+1)+FLDAT(1HIS(KX)) WPITF(6,2005)	<pre>2005 FORMAT(:0*,7X,"RM',10X,"INTERVAL',10X,"CUMULATIVE FPEQUENCY' / *</pre>	RMZ=X([X]+RWIC201 163 WPTTE(6,2006)RM1,RM2,IHIS([X],YY([X],RM1 2006 FORMAT(1 'F7.2,' - ',F4.2,I8,12X,F10.0,8X,F6.2)

A4-8

360 CONTINUE J

IF(RMBK.NE.0.) GO TO 330 IF(IR.E0.1) GO TO 111

C COMPUTE INTERSECTION POINT IF THERE ARE TWD LINES
XM=ABS(ALPHA(1)-ALPHA(2))/(BETA(1)-BETA(2)))
XL=ALPHA(1)+BETA(1)\*XM
WRITE(6,21201XM,XLN
2123 FORMAT(0INTERSECTION POINT\*/\* MAGNITUDE\*,F8.2,/\* LN OF N \*,F8.2)
C C

...01 60 TO 111 99 RETURN 50ATA 50ATA

A4-9

CARD 1 1+80 HEDZ IDENTIFICATION OF THE LINE SOURCE	CARD 2 7F10.0 Properties on the left of breaking point 1-10 AIDHAIT A MOMMITED INTEDERT	11-20 RETAIL SLOPE 21-30 XLI() X COORD FOR ORIGIN	31-40 XL2() X COURD DF END 41-50 YL1() Y COORD DF DF GIN 51-60 YL2() Y COURD DF END	61-70 HL() DEPTH OF LINE	CARD 3 3F10.0 PROPERTIES ON THE RIGHT DF BREAKING PJINT	INPUT THE SAME VALUES FOR ALPHA AND BETA AND DUMMY BREAKING POINT IF THERE IS NO REEAKING POINT	1-10 ALPHA2() NORMALIZED INTERCEPT 11-20 BFTA2() SLOPE 21-30 RML() BREAKING PDINT MAGNITUDE	5 AREA SOURCES PROPERTIES 3 CARDS PEP SOURCE	CAPD I 2044 1-80 HED APEA SOURCE IDENTIFICATION	CARD 2 6F10.0	PROPERTIES ON THE LEFT OF BREAKING POINT 1-10 ALPHAI( ) NORMALIZED INTERCEDI	11-20 BETAIL SLOPE	ZI-30 XLL() X COURD UP CIPILE CENTER 31-40 YLL() Y COOPD OF CIRCLE CENTER	41-50 ALZ( ) RADIUS OF CIRFLE 51-60 HL( ) DEPTH OF APEA SOURCE	CARD 3 3F10.0 poncertee on the offert of operative offert	INDUCINIES ON THE FIGHT OF BEAKING FOIR INDUCT SAME VALUES FOR ALPHA AND BETA AND RUMUK SAME VALUES FOR ALPHA AND RETAIND	1-10 ALPHAZ( ) NORMALIZED INTERCEPT	11-20 BETAZI / SLUPF 21-30 RML( ) BREAKING POINT MAGNITUDE		DEPENDING UPON THE INPUT, THE OUTPUT WILL DISPLAY FROM ONE PROBABILITY OF EXCEENANCE AT ONE DOINT TO A WHOLE ONE ONE A	WHOLE GETD OF POINTS	\$P\$\$P\$\$P\$\$P\$\$P\$\$P\$\$P\$\$P\$\$P\$\$P\$\$P\$\$P\$\$P\$	IMPLICII KEAL*8 (A-H,U-Z) DIMENSION HEDI(20),HED2(20)	COMMON/SOUPCE/ALPHA1(20),ALPHA2(20),BETA1(20),RETA2(20),PML(20), 1 HL (20)	COMMON/ATTEN/B1,82,83,84,DELTAL,DELTAC DIMENSION XIII201,VII200,XI21201,VII2201,VII2201,VII2201,PDF1301.	I FY1 (30), FY2 (30) ************************************	READ AND WRITE ATTENUATION COMSTANTS
。 1 1	PROGRAM ACC.LINE.AREA STAVFJRD UNIVERSITY C ************************************	GRUGNI) ALCELERATIONS AT SPECIFIEU SITES UNE TI LIME UN ANEA SELSMIC SQURCES. Карактертерататата сорона и со		1 IDENTIFICATION CARD 1 CARD 2044 C	1-80 HEDI TITLE C	2 ATTENUATION CONSTANTS 1 CARD 3F10.0	1-10 B1 11-20 B2 21-30 B3	31-40 B4 21-50 DELTAL STEP SIZE FOR LINE INTEGRATION	51-60 DELTAC STEP SIZE FUX CINCLE INTEGRATION UNITS DF LENGTH USED IN THE PROGRAM ATTENUATION FORMULA OF THE TYPE OF	ACC=B1*EXP(82*MAG)/(8+B4)**B3 C	3 PROBLEM DESCRIPTION 4. CARDS	CARD 1 415	I+ 5 NL NUMBER DF LINE SOURCES 6−10 NA NUMBER DF AREA SOURCES	II-I5 NT NUMBER OF TIME PERIODS 16-20 NY NUMBER OF ACC	CARD 2 TIME PERIDDS, NT VALUES, 8 VALUES PER CARD 8F10.0	1-10 T(1) PERIOD 1 11-20 T(2) PERIOD 2	T(NT) PERIJDS NT	CARD 3 PEAK GROUND ACC., NY VALUFS, 8 VÁLUES PER CARD 8F10.0	1-10 Y(1) PGA 1 11-20 Y(2) PGA 2	Y(NY) PGA NY	CARD 4 SEARCHING GRID DESCRIPTION BF10.0	1-10 XBEGIN DRIGIN DE GRID X CODRD 11-20 YREGIN DRIGIN DE GRID Y CADRD	21–30 XEND END OF GRID X COORD 31–40 YEND END OF GRID Y COORD	CRICIN AND END SHOULD COINCIDE IF DNLY	41-50 DX UNE LUCATION IS REDUIRED	DI-DU UV TINUKETINI DX AND DY MUST RE DIFFERENT FROM ZERD	4 LINE SOURCES PPOPERTIES 3 CARDS PEP SPUGGE

YLI(IL)=YL2(IL) XL2(IL)=XD YL2(IL)=YD YL2(IL)=YD 700 CCNTINUE 610 IF(NA.LE.0) GD TO 551 C READ AND WRITE AREA SOU T I=NL+1 NN=NL+1 NN=NL+1 NN=NL+1 2124 FORMAT(**//*AREA SOURCES*/	C 90 615 T=T1,NN READ(5,1040)HED2 READ(5,1000) ALPHAI(T),BETAJ READ(5,1000) ALPHAI(T),BETAJ READ(5,1000) ALPHAZ(I),BETAZ WRITE(6,1023) ALPHAI(I),BETA WRITE(6,1023) ALPHAI(I),BETA WRITE(6,1023) ALPHAZ(I),BETA WRITE(6,1023) ALPHAZ(I),BETA	C 2120 FORMAT(* ', 2X, 'ALPHAL', 10X,' 5.12X, *YO', 12X, *K, 13X, *HA') 2123 FORMAT(' SECOND REGRESSION C 6'BETA2', 10X, MR') 551 CONTINUE C ITERATION ON TIME PERIODS 6 01 370 1T=1, MT MRITE(6, 3000) T(IT) C MRITE(6, 3000) T(IT) C MRITE(10, 5020) T(IT) C C MRITE(10, 5020) T(IT)	3000 FORMAT(*0*,* TIME PERIDD=*,F C ITERATION ON GRID C ITERATION IN THE Y DIRECTION Y=YBEGIN DD 385 IY=1,NYMAX DD 385 IY=1,NYMAX C ITERATION IN THE X DIRECTION X=XBEGIN DD 380 IX=1,NYMAX	WHITE(0,2222) X,Y PDF(1)=0.0D0 C ITERATION ON PGA DD 360 II=2.NY YGIIB1=YGII1) YGIIB1=YGII/B1 SUM = 0.0D0 SUM1=0.0D0	C ITERATION ON LINE SOURCES IF(NL.EO.O) GO TO 441 DO 351 IL=1,NL C CALL CONSTL(X,Y,XLL(IL),YL1(
C 8cAD(5,1040)HED1 1045 F5R4AT(2044) WRITE(6,1041)HED1 1041 FDRMAT(00,2044) READ(5,1000)B1,82,83,84,DELTAL,DELTAC MRITE(6,1020)B1,82,83,84,DELTAL,DELTAC 1025 FORMAT(100,*ATFNUATION CONSTANTS*//,* B1=*,E15,7,3X,*B2=*,E15.7, 83X,*B3=*,E15.7,2X,*B4=*,E15.7 /* DELTAL =*,E15.7,3X,*DELTAC =* 1000 FORMAT(810.0)	<pre>READ AND WRITE GEOWETRIC CONSTANTS READ(5,1001)NL,NA,NT,NY LOOI FORMAT(1015) READ(5,1000)(T(1),1=1,NT) WRITE(6,2220)(T(1),1=1,NT) WRITE(6,2220)(T(1),1=1,NT) WRITE(6,2220)(T(1),1=2,NY) WRITE(6,2220)(YG(1),1=2,NY) WRITE(6,2220)(YG(1),1=2,NY)</pre>	<pre>2220 FORMAT( *10*10:2) 2210 FORMAT( *10*10:2) 2210 FORMAT(*0THME PERIDDS*) 76(1)=0.000 2222 FORMAT(*00* SITE LOCATION*//, *,*X= *,FI0.3,5X,*Y= *,F10.3) 350 READ(5,1000) XREGIN*KEND,VX*ND,VX*DY NXMAX=DABS((XREGIN-KEND)/DX)+1.9D0 NYMAX=DABS((YREGIN-KEND)/DY)+1.9D0 NYMAX=DABS((YREGIN-KEND)/DY)+1.9D0 NPTE(6,1021)NU,NA,NXMAX,NYMAX,N 1021 FORMAT(*0*,'GEOWETRIC CONSTMATS*//, *NL=*,I5,5X*'NNA = *,I5,5X* 1021 FORMAT(*0*,'GEOWETRIC CONSTMATS*//, *NL=*,I5,5X*'NNA = *,I5,5X*' 1021 FORMAT(*0*,'GEOWETRIC CONSTMATS*//, *NL=*,I5,5X*'NNA = *,I5,5X*'NNA = *,I5,5X*'NNA = *,I5,5X*'NT=*,I5,5X*'NT=*,I5,5X*'NNA = *,I5,5X*'NNA = *,I5,5X*'NNA = *,I5,5X*'NT=*,I5,5X*'NT=*,I5,5X*'NNA = *,I5,5X*'NNA = *,I5</pre>	READ AND WRITE LIME SOURCE PROPERTIES           WRITE(6,1024)           J024 FORWAT(:0LINE SOURCES'/* ***********************************	WRITE(6,1023)ALPHAI(1),BETAI(1),XL1(1),XL2(1),YL1(1),YL2(1),HL(1) 1022 FORMAT(*',2X,*ALPHA1*,10X,*BETA1*,11 5.X,XL1*,11X,*XL2*,11X,*YL1*,11X,*YL2*,12X,*HL*} 1023 FORMAT(*,*E13.5,6E14.5) WRITE(6,1023) ALPHA2(1),BETA2(1),RML(1) 1031 FORMAT(* SECOND REGRESSTON CONSTAMTS*,/**,2X,*ALPHAL2*,9X, 616, CONTAMIE	00 700 1L=1.NL FF(XLITL).LT.XL2(TL)) GO TO 700 XD=XL1(TL) XD=YL1(TL) XL1(TL)=XL2(TL) XL1(TL)=XL2(TL)

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	L AL1, AL2, DLIL, AIL, BIL)	850 CUNTINUE
	HLILEHL(IL)	442 CONTINUE
	DEL 22=8 ET A211L)/82	FV1(1)=DEXP(-SUM*T(1))
	RH022=DEL 22*B3	FY2(II)×1+000-FY1(II) DDEfri)≤-SUM1±T/II)±EV1/II)
	FFY=(DLIL*DLIL)+(HLIL*HLIL) Du-fnc0DTfErv1*B&)**Du72	360 CONTINUE
	EXCK=RH+GAM22+(YGIIBI++DEL22)+(AL2+AL1)+f(IT)	C
	IF(EXCK-LE.1.D-5) GD TD 351	C WRITE(10,5000)(FY2(J),J=2,NY)
	CALL INTGLN(IL, XL1(IL), YL1(IL), XL2(IL), YL2(IL), AL1, AL2, DLIL,	
	L HL(IL/AIL/BIL/FTGII/A)FFFF65AMZZ4UELZ26MUZ29FFFFL/ SUM±SUM + FF	
	SUM1 + SUM1 + FF1	DQ 375 JJ=1,NYY
351	CONTINUE	IF(JJ&EU&MYY) NYITNY WRITF(4,204)[VC1]], I#K.NV]]
υu	APEA SUURCE COMPUTATION	WRITE(6,227)(FY2(J),J=K,NY1)
ຸບ		WRITE(6,228)(FY1(J),J=K,NY1)
<b>4</b> 41	IFINA.E0.0) GO TO 442	C WRITE(6+229)(PDF(J)+J=K+NYI) NV1=NV1+10
	II≡NL+I TENN≞NI+NÅ	
	D0 850 IA=II.IEND	375 CONTINUE
ں <i>د</i>	CHECK WHETHER THE CIRCLE CONTRIBUTES ANY IN THE PROB	5000 FORMAT(10F8.5)
)		226 FORMAT(*0',*PGA = ',10F10.4)
		ZZF FUKMAIT* ***********************************
	GAM22=DEXP(ALPHAZ(IA))	229 FDRMAT(* *, *PDF(Y) *, 10F10.4)
		Ľ,
	DIST=DSORT((X-XL1(IA))*(X-XL1(IA))+(Y-YL1(IA))*(Y-YL1(IA)))	C MOVE TO THE NEXT POINT ALONG THE GRID
	R H= (0)	385 Y=V+DY
	EKUK#KH#GAMGZ#(1011bL##DELZZ1#10。283LUU#KIA#KIA!#1111 IF1FXCK_LF_1_D_51_G1_T0_850	370 CONTINUE
	SUMP=0.DO	365 CONTINUE
	SUMP1=0.D0	222 FUKBAI("1"""""""""""""""""""""""""""""""""""
	NAT & 1 A V C L 1 A L + 0 + V U	
	UK=K.IA/WR DR1=DP★+5500	STOP
с i	LIVER STATES OF STOLENESS STATES	ENU SURPOUTINE CONSTICX.Y.XII.YII.XI7.YI2.
J	IIFRAILUN UN IME NG UF SEGMENIS IN IME UIKULE Di 303 18≞1.MR	1 AL1, AL2, DLIL, AM, B)
		U
	DL2=D15T+0R1	● ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★ ★
	AL=DSCRT(RIA+PIA-DR1+DR1) EEV-D11+D11+D11+D11	· [MPLICII KEAL#8 (A-H9 U-Z) · ####################################
	FILTENLISHIFTHLISHIER	, <b>c</b>
	I YGT 1,0.00,0.00, FFY, GAM2 2, DEL 22, RHC22, FF, FF1)	C AW = SLOPE OF LINE DEFINED FY (X1, Y1), (X2,
	SUMP#SUMP+FFF2_D0	C B = Y-INTERSEPT
	20MPI=5UMPI+FFI*6+EU * FFY=DI 2*DI 2+HFI1/	AM=(YL2-YL1)/(XL2-XL1)
	CALL INTGLN(IA,0.00,0L2,AL,0L2,0.00,AL,0L2,HL1L,0.00,0L2,	B=YL1-AM*XL1
	1 YGII.0.D0,0.D0,FFY,GAM22,DEL22,RH022,FF,FF]) SUMD-SUMBJEE*2 00	XBAP={X+AM*Y-B*AM}/{A**AM+1.0U01 YBAR={AM*X+Y*AM*AM+B}/{AM*AM+1.0D0}
	SUMP1=SUMP1+FF1*2.00	DL 1 L=DSQRT((X-XBAR)*(X-XBAR)+(Y-YBAP)*(
202	DRI=DPI+DR CONTINUE	C CHECK POSITION OF (XBAR, YBAR) ALONF LIME W.
<b>.</b> ,	SUMP=SUMP+DP	C OF POINTS OF LINE SOURCE ALI=DSQRT((XL1-XBAR)*(XL1-XBAR)+(YL1-YF ALI=DSQRT((Y) 2-YAAR)*(XY 2-YRAAP)+(YV 2-YP
	SUM=I SUM+SUM P	
	SUM1=SUM1+SUM1+SUM1	IF(XBAR.LT.XL1) ALI=-ALI

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·谢米拉谢谢谢的林家林家长的小小小小小小小小小 (米 新香菇 林立 林文 林文 法 教 秋 新 秋 林 林 林 林 林 林 林 林 林 林 林 林 ITY DISTRIBUT ELERATION \*\*\*\*\*\*\* 14R) \* ( YL I-YBAR) ) 14P ) \* ( YL 2-YAAR) ) R.T. END Y-YBAP)] Y2)

STUREVII VII=VI2 VI2=STOR ISO CONTINUE	C CHECK WHETHER THE POINTS OF INTERSECTION ARE ON THE SEGMENT C CONSTDEMED AND DETERMINE THE USE OF ALPHA AND BETA FF(KL1.LT.XII) GD TO 800 IF(KL1.GT.XI2) GD TO 820 IF(XL2.GT.XI2) GD TO 820 C TO 850 C TO 850	C 800 IF(XL2.LT.XII) GD TO 830 IF(XL2.LT.XIZ) GD TO 840 C CASF=5 NBSG=3 XX(2)=XI1 YY(2)=XI1 YY(2)=YI1 YY(2)=YI2	C AST 4) = XL2 XX(4) = XL2 XY(4) = YL2 GG TJ 870 C 830 CASE=3 850 XX(2) = XL2 VY(2) = YL2 GD TD 870 GD TD 870	C 820 CASE=2 X11=X12 Y11=Y12 60 T0 860 61 T0 860 640 CASE=4 860 NBSG=2 XX(2)=XT1 XX(2)=XT1 XX(2)=XT1 XX(2)=XT1 XX(2)=XT1	C 870 CONTINUE 1=1 1=1 1=1 C C C C C C C C C C C C C
IF(XRAP.LE.XL2) RFTURN DUM = Ali Ali = -Al2 Al2 = DUM	RETURN END SUBROUTINE INTGLNIL, XL1, YL1, XL2, YL2, AL1, AL2, DLIL, HLIL, AIL, BIL, I YGII, X, Y, FFY, GAM22, DEL22, RHN22, FF, FFI) I YGII, X, Y, FFY, GAM22, DEL22, RHN22, FF, FFI) THIS SUBROUTINE COMPUTES THE INTEGXAL ALONG A LIVE IT IS CALLED FOR LINE SOURCES AS WELL AS FOR CIRCLES SOURCES THE PARAMETERS ALPHA AND BETA TO BE USED IRE FIRST CHECKED #XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	<pre>IMPLICIT REAL*8 (A-H, D-Z) INFLICIT REAL*8 (A-H, D-Z) INTEGFR CASE DIMENSION XX(4), YY(4), DEL(2), GAM(2), RHD(2) COMMON/SOURCE/ALPHA1(20), ALPHA2(20), BETA2(20), RML(20), L COMMON/ATTEN/R1, B2, B3, B4, DELTAL, DEL TAC COMMON/ATTEN/R1, B2, B3, B4, DELTAL, DEL TAC, B4, B4, B4, B4, B4, B4, B4, B4, B4, B4</pre>	DELUTERFAI(TL)/B2 BHOLLEDELLIE83 N95G=1 XX(1)=XL1 YY(1)=YL1 YY(1)=YL1 COMPUTE EPICENTPAL DISTANCE RECK AT WHICH AN EARTHOUAKE OF BREAKPOINT MAGNITUDE RAWL(IL) WILL GENERATE AN ACCELERATION	YG(II) IF RECK IS IMAGINARY OR SMALLER THAN DLIL, ALPHAZ AND BETAZ ARE USED., OTHERWISE POINNS WHERE ALPHA AND BETA CHANGE VALUE ARE DETEPMINED ON THE LINE TERM=(0.1*DEXP(0.2*RML(IL))YGII)**(1.00/B3) TERM=0.4*(LEMLIL)GOTO B30 TERM=64.(LEMLIL)GOTO B30 TERM=67ERM=64.)-(HLIL*HLIL) THE EPICENTRAL DISTANCE IS NOT IMAGINARY RECK=0GART(TERM) IF(RECK=LE*DLIL)GOTO B30	THE EPICENTRAL DISTANCE IS NOT SMALLER THAN DLIL, POINTS DF INTERSECTION WITH THE LINE ARE COMPUTED TERM1=AIL+(BIL-Y)-X TERM2=AX+BILBABL+Y+(Y-2, DO#BIL)-RECK+RECK TERM2=AX+BILBABL+Y+(Y-2, DO#BIL)-RECK+RECK TERM2=AX+BILBABL+Y+(Y-2, DO#BIL)-RECK+RECK TERM2=BSIC+T+100 TERM2=BSIC+T+100 TERM2=BSIC+TFRM1+TERM1-TERM2+TERM3} COORDINATES OF THE POINTS OF INTERSECTION XII=(TERM1+TERM2)/TERM3 XII=(TERM1+TERM2)/TERM3 XII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=(L+XI1+BIL YII=XI2+BIL

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C DD 900 IXSG=1,NBSG TERN=0.D0 IFEIX.E0.3) IX=1 C TERN=0.D0 IFEIX.E0.3) IX=1 C COMPUTF LENGTH OF SEGMENT CONSIDERED AND DETERWINE C COMPUTF LENGTH OF SEGMENT CONSIDERED AND DETERWINE C COMPUTF LENGTH OF SEGMENT CONSIDERED AND DETERWINE NUMBER OF INCREMENTS XLENDSOFI(IXX(IXSG)-XX(IXSG)-YY(IXSG)-

IVEN THE OF ON ACCELERATION PLA.GT.A01 FOR EACH WODE CF A GAID MASABILITUR STRACT. RECELERATION (A0) CORRESPONDING THA GIVEN DATA FOR THE AND A STUTES AND A STUDE THATTUR STRACT TON THATTUR STRACT STRACT TON THATTUR STRACT STRACT STRACT TON THATTUR STRACT STRACT STRACT STRAST STRACT THATTUR STRACT STRACT STRACT STRACT THATTUR STRACT STRACT STRACT STRAST STRATTON THATTER STRACT STRACT STRACT STRAST SPONDING THAT STRACT STRACT STRACT STRAST SPONDING THAT STRACT STRACT STRACT STRAST SPONDING THAT STRACT STRACT STRAST STRATTON THAT STRA	жажасасқақталған сағасқа жана саға жана саға жана жана жана жана жана жана жана ж	14444444444444444444444444444444444444
WUT FRAMAT WUT FRAMAT COL VARIABLE NAME VARIABLE DESCRIPTION - GENERAL INFORMATICN 1 CARD (415) - GENERAL INFORMATICN 1 CARD (415) - GENERAL INFORMATICN 1 CARD (415) - 0 NBAC NB OF RUNS FROUTERD - 10 NBAC NB OF RUNS - COLUMNS - COF PARAMETERS 1 CARD (7510.0) - 10 NBAC NB OF RUNS - COLUMNS - COF PARAMETERS 1 CARD (7510.0) - 10 NBAC NB OF RUNS - COLUMNS - 10 FRILITY AD - 10 FRILITY AD - 10 FRILI N 1 CAPD (2044) - 10 FRILI N 1 CAPD (2045) - 10 FRILI N 1 CAPD (2	IVEN THE CDF ON ACCELERATION P(A.GT.AO) FOR EACH N HIS PROGRAM FINDS THE ACCELERATION (AO) CURRESPOND Robability Using Linear interpriation. The GPT I Tapting From Bottom Left Node, itfrations Ape VAD He Hopizontal Direction	NODE CF A GRID NDING TD A GIVEN IS COVERED IDE FIRST IN
COL VARIABLE NAME VARIABLE DESCRIPTION GENERAL INFORMATION 1 CARD (415) 1-5 WAPD NAME NA FEOUREF MB OF ACC GIVEN FOR EACH NODE ALLOS NAME NA OF ACC GIVEN FOR EACH NODE ALLOS NAYY NA OF ACC GIVEN FOR EACH NODE ALLOS NAYY NA OF ACC IN CF ALLES ACC IN CF ACC INTRAMANTIN	######################################	·法法按法律法法律法法律法律
<ul> <li>GENERAL INFORMATION 1 GARD (415)</li> <li>GENERAL INFORMATION 1 GARD (415)</li> <li>SUBDO NOR FOUR FOR FOR FOR FOR FOR FOR FOR B-10 NBAC NO F RUNS RECUTER FOR NBAC NEW NO F ROUS</li> <li>L-10 AGST SARLEST AGC IN COF ACC INTEREMENT IN COF ACC INTEREMENT IN COF PROFILET AGO ACC INTEREMENT IN COF PROFILET AGO ACC INTEREMENT IN COF PROFILETION 1 CAPD (2044)</li> <li>L-10 AGST ACCLERATION ACC INTEREMENT IN COF PROFILE PROFILEST ACCLERATION</li> <li>L-10 AGST (NBXX*NBY) CARDS OR SET OF CAPOS (10F8.0)</li> <li>L-10 PRUTIFICATION 1 CAPD (2044)</li> <li>PRUTIFICATION 1 CAPD (2044</li></ul>	COL VARTABLE NAME VARIABLE DESCRIPTION	
<pre> CDF PARAMETERS 1 CARD (3F10.0) 1-10 ACST SMALLEST ACC IN CDF 1-30 PRCK PARENT IN CDF 1-30 PRCK PREATION 1 CAPD (2044)  IDENTIFICATION 1 CAPD (2044) 1-90 HED1 RUN IDENTIFICATION  CDF CARDS (NBXX*NRYY) CARDS 07 SET OF CAPDS (10F8.0) PR(1) PR(1) THE SMALLEST ACCELERATION PR(1) PR(1) THE SMALLEST ACCELERATION PR(1) PR(1) THE LARGEST ACCELERATION PR(1) PR(1) THE LARGEST ACCELERATION PR(1) PR(1) THE LARGEST ACCELERATION PR(1) PR(1) THE LARGEST ACCELERATION PR(1) THE LARGEST ACCELERATION PR(1) PR(1) THE LARGEST ACCELERATION PR(1) THE DUTTUT IS SAVED ON DISK AND CONTAINS THE PUN IDENTIFICATION WO THE ACCELERATION AT EACH NODE CORRESPONDING TO THE GIVEN PREASIN ACC301.PR(301.ACP8(40).HED1(20).HED2(20) ************************************</pre>	<ul> <li>GENERAL INFORMATION I CARD (415)</li> <li>5 NBPD NB OF RUNS REQUIRED</li> <li>6-10 NBAC NB OF ACC GIVEN FOR EACH</li> <li>1-15 NBXX NB OF COLUMNS</li> <li>6-20 NBYY NB OF ROWS</li> </ul>	H NODE
<ul> <li>TIDENTIFICATION 1 CAPD (204)</li> <li>HEDI RUN IDENTIFICATION</li> <li>CDF CARDS (NBXX*NBYY) CARDS OR SET OF CAPDS (10F8.0)</li> <li>PR(1) PR(1) TO THE SMALLEST ACCELERATION</li> <li>PR(1) TO THE SMALLEST ACCELERATION</li> <li>PR(1) PR(1) PROBABILITY OF EXCEEDANCE CORRESPONDING</li> <li>PR(1) PROBABILITY OF EXCEEDANCE CORRESPONDING</li> <li>PROBABILITY OF EXCEEDANCE CORRESPONDING TO THE GIVEN</li> <li>PROBABILITY OF EXCEEDANCE - FORMAT (8F10.6)</li> <li>PROBABILITY OF EXCEPTION</li> <li>PROVISIONADO OF EXCEPTION</li> <li>PROVISIONADO OF EXCEPTION</li> <li>PROVISIONADO OF EXCEPTION</li> <li>PROVISIONADO OF EXCEPTION</li></ul>	CDF PARAWETERS I CARD (3F10.0) 1-10 ACST SMALLEST ACC IN CDF 1-20 ACIC ACC INTREMENT IN CDF 1-30 PBCK PRIBABILITY AO	
<ul> <li>CDF CARDS (NBXX*NBYY) CARDS OR SET OF CAPDS (10F8.0)</li> <li>I-10 PA(1) TO THE SMALLEST ACCELERATION TO THE SMALLEST ACCELERATION</li> <li>PB(1) TO THE LARGEST ACCELERATION</li> <li>PB(1) PACHBALLITY OF EXCEEDANCE CORRESPONDING</li> <li>PB(1) PACHBALLITY OF EXCEEDANCE CORRESPONDING</li> <li>PB(1) PACHBALLITY OF EXCEEDANCE CORRESPONDING</li> <li>PB(1) PACHBAL TO THE LARGEST ACCELERATION</li> <li>PB(1) PACHBAL TO THE LARGEST ACCELERATION</li> <li>PB(1) PACHBAL TEAL NODE CORRESPONDING TO THE GIVEN</li> <li>PACHBALLITY OF EXCEEDANCE. FORMAT (8F10.6)</li> <li>PACHARANANANANANANANANANANANANANANANANANANA</li></ul>	IDENTIFICATION 1 CAPD (2044) 1-90 Hedi 1 RUN IDENTIFICATION	
PRIVID PRIVIDE CORRESPONDING PRIVIDE PRIVIDE PRIVIDE CORRESPONDING PRIVIDE CORRESPONDING PRIVIDE CORRESPONDING PRIVIDE PRIVIDE PRIVIDE CORRESPONDING PRIVIDE CORRESPONDING PRIVIDE PRIVE PRIVIDE PRIVIDE PRIVE PRIVIDE PRIV	CDF CARDS (NBXX*NBVY) CARDS OR SET DF CAPDS 1-10 Pa(1) TOF EXCEEDANC TO THE SMALLEST ACCELERA	(10F8.0) Jce cjrresponding (Ation
UTPUT ***** HE DUTPUT IS SAVED ON DISK AND CONTAINS THE PUN IDENTIFICATION ND THE ACCELERATION AT EACH NODE CORRESPONDING TO THE GIVEN ND THE ACCELERATION AT EACH NODE CORRESPONDING TO THE GIVEN RABARLITY OF EXCEEDANCE. FORMAT (8F10.6) ************************************	PB( ) PB(NBAC) PRABABILITY OF EXCEEDANC PB(NBAC) TO THE LAPGEST ACCELEPAN	LCE CORRESPONDING NTION
**************************************	UTPUT ***** He dutput is Saved on disk and contains the PUN IC Nd the acceleration at each node corresponding to Rabarliity of exceedance. Format (8F10.6)	DENTIFICATION The given
EAD(5,1010)NBPD,NBAC,NBXX,NBYY CRMAT(815) Ritel6,2010)NBPD,NBAC,NBXX,NBYY CRMAT(10NBPD',16,' NBAC,16,' NBXX',16,' NBYY',16) EAD(5,1040)ACST,ACTC,PBCK NAMAT(8F10.0) Rite(5,2030)ACST,ACTC,PBCK	жа чакта ща чака кака кака кака кака кака кака	1 + + + + + + + + + + + + + + + + + + +
EAD(5,1040)ACST,ACTC,PBCK nrmat(8F10.0) KTTE(6,2030)ACST,ACTC,PBCK nrmattinansti.fina.fi	EAD(5,1010)NBPD,NBAC,NBXX,NBYY (DRMAT1815) Rite16,2010)NBPD,NBAC,NBXX,NBYY (DRMAT1"ONSPD',16," NBAC',16," NBXX',16," NBYY',	,161
ADEDTIA: VOCL - ADEDTIA: STOR - ADEDTIA: SOCOL: CALLO	<pre>(EAD(5,1040)ACST,ACTC,PBC# inpmat(8F10.0) (Rite(6,2030)ACST,ACIC,PBCK ORMAT('0ACST',F10.2, ACIC',F10.2, PBCK',F10.2)</pre>	ā

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NBAC1=NRAC+1

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WRITE(6,2020)HED1 2020 FORMAT('0\*\*\* ATTENTION \*\*\*'/' EXCEDANCE IS LARGER THAN THE INPUT' 1 /' \*2044) ACPB(IX)=AC(NBAC1) GO TO 110 GO TO 110 163 aCPB(IX)=AC(kP-1)+((AC(kP)-AC(KP-1))\*(PB(KP-1)-PBCK))/
1 (PB(KP-1)-PB(KP))
110 CONTINUE WRITE(6,2040)(ACPB(1),I±1,NBXX) O FORMAT(\* \*,12F10.6) WRITE(10,3000)(ACPB(1),I=1,NBXX) O FORMAT(8F10.6) O CONTINUE ETURN END READ(5,1030)(PB(I),I=2,NBAC1) 1030 FORMAT(10F8.0) DD 150 KP=2,NBAC1 IF(PBCK.GE.PB(KP)) GO TO 160 150 CONTINUE D0 100 TP=1.NBD READ(5.1000)HFD1 1000 FDRMAT(2040) MRITE(6.2000)HFD1 2000 FDRMAT(1 '.2041) WRITE(10,1000)HFD1 D0 100 TY=1.NBYY D0 100 TY=1.NBYY D0 100 TY=1.NBYY C READ(5.1020)HFD1 C1020 FDRMAT(//2044) PB(1)=1.00 AC(1)=0.00 AC(2)=ACST AC(2)=ACST DD 120 1=2.NBAC DD 120 1=2.NBAC PRINT, AC. AC 2040 3000 120 \$DATA

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A4-15

READ(10,1020)HED1 1020 FURMAT(2044) READ(10,1200)(X1(1),1=3,NR1,2) 1200 FURMAT(10F8.0) D0 60 1=3,NR1,2 60 X1(1)=1X1(1) D0 220 1=1.NB1,2 220 X1(1)=X1(1)*100.	C WRITE(6,2010)HED1 2010 Forwat(* ',//' ',2044) 2015 Forwat(6,2050) 2050 Forwat(0,-7x,"CDF*,7x,"ACC")	C WRITE(6,2020)X1 2020 FORMAT(* ',2F10.3) DO 90 IT=1,12 90 INTEN(IT)=0	DC 100 IT=1,1000 CALL CDF(X1,NB2,1,ACC) INT=3.*(ALGGIO(ACC*1000.)+.5)+.5 IF(INT.LT.1) GC TO 100 C PRINT,*CC.FINT.*ACC.INT C INTEN(INT)=INTEN(INT)+1	100 CONTINUE C T01=00. D0 110 INT=1,12 C PRINT,FINTNB OF DCC',INT,INTEN(INT) C PRINT,FINAT(INTN)	C WRITE(6,2060) 2060 FDRMT(*0INTEVSITY PERCENTAGE*/* *******************/) DO 120 INT=112 SUB=FLOAT(INTEN(INT)/TOT 120 WRITE(6,2030)INT_SUB	400 CONTINUE 2030 FORMAI(* *,19,F13.3) RETURN END SUBROUTINE CDF(X1,KEND,ICK,ANS) C THIS SUBROUTINE EINDS THE VALUE FORDEEEDINDING TO THE DANDON	UNITABLE ON THE CDF, LINEAR FITTING IS APPLIED IF INDEX.FG.I UNITABLE ON THE CDF, LINEAR FITTING IS APPLIED IF INDEX.FG.I ( ************************************	C ************************************	00 100 I=1.кЕN ГF(VFL.LT.(XI(2*I-1)/100.)) GD TP 110 100 CDNTINUF WPITF(6,1000) 1000 FCPMAT(27H0** EPRD9 IN CDF INPUT ** //
######################################	INPUT FORMAT ********* Col variable name variable description 1 generai 1 card (315)	1 - 5 CHAR A CHAR AND	<ul> <li>X(1)</li> <li>LARGEST ACC IN CDF</li> <li>X(NB+2)</li> <li>LARGEST ACC IN CDF</li> <li>X(NB+4)</li> <li>AN ACC EQUAL DR LARGER THAN XINB+2).</li> <li>X(NB+4)</li> <li>AN ACC EQUAL DR LARGER THAN XINB+2).</li> <li>NAXIMUM POSSIBLE ACC TO BE USED IN CASE</li> <li>INPUT CDF DOES NOT GO UP TO 100%</li> </ul>	THE REMAINING DATA IS READ FROM DISK 3 NODE IDENTIFICATION 1 CARD IMAGE (2044) 1 80 HED1 IDENTIFICATION 4 CDF P(4.6T.40) 8 VALUES PER CARD IMAGE (8F10.01 1-10 X(3) PI3.6T.X41)	X(NB+L) P(A.GT.X(NB+2)) X(NB+L) P(A.GT.X(NB+2)) OUTPUT ****** THE DUTPUT DISPLAYS THE INPUT, THE NUMBER OF OCCURRENCES OF	THE WODIFIED MERCALLI INTESITY IN THE SIMULATION AND THE CORRESPONDING PERCENTAGE. Corresponding percentage. ************************************	READ(5,1000)NB,1Y,NBPT READ(5,1000)NB,1Y,NBPT NB1=NB+4 NB1=NB+1 X1(1)=0.	X1(2)=0. 1000 FORMAT[3[5] READ(5,1100)(X1(1),[=4,NB2,2) 1105 FORMAT[RF10.0] X1(NB+3)=100. CAI! BANNUT'V-VEL.01	YFL=01 YFL=01 REAR(10.1020)HED1 WRITF(6.2010) HED1 D^ 400 IP=1.NBPT

A4-16

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LfNEAR FITTING HALE DISTANCE BETWEEN INPUT PDINTS

TF(1.EC.KENGG TO 140

TF(1.LT.3) GG TO 130

XT=(X1(2*1)+X1(2*1-2))*.5

YT=X1(2*1-1)

YT=X1(2*1-4)

YT=(X1(2*1-4))

YT=(X1(2*1-4))

YT=(X1(2*1-4))

GG TO 150

GG TO 150
1 36H LAST PEPTENTAGE INPUT IS NOT 100.01 //)
1=1-1
112 TF(ICK-1) 200.300,120
200 &NS = X1(2*1)
200 APS = X1(2*1)
200 RETURN
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      THIS SUBROUTINE GENERATES RANDOM NUMBERS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       CHECK FOR VERTICAL INTERPOLATION
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            END
SUBPRUTINE PANDK (IY,YFL,INDEX)
                                                                                                                                                                                                                                                                                                                                                                                             LINEAP FIT TROUGH INPUT POINTS
XT=X1(2*1)
YT=X12*1)
Y=X112*1-2)
Y=X1(2*1-2)
Y=X1(2*1-3)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    IF((XT-X8).LT..00001) RETURN
                                                                                                                                                                                                                                                                                                                                      XR=[X1(2*[-4)+X1(2*I-2)]*.5
YB=X1(2*[-3)
Gn T0 150
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Y=IY*3141592694453806245
4 [F{IY.GE.0] GD TD 6
5 IY=IY+2147483647+1
6 CONTINUE
1F[INDEX.GT.0] GD TD 8
YEL=ELNAT(IY)*.4455613E-9
8 RFTURN
                                                                                                                                                                                                                               130 XT=(X1(2*1)+X1(2*1-2))*•5

YT=X1(2*1-1)

XB=X1(2*1-2)

YB=X1(2*1-2)

140 XT=X1(2*1)

140 XT=X1(2*1)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         A={YT-YR}/{XT-XB}
ANS={YFL*100.-{YT-A*XT}}/A
Return
                                                                                                                                                                                                                                                                                                                           YT=100.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      ANS=XT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         END
                                                                                                                12.0
                                                                                                                                                                                                                                                                                                                                       160
                                                                                                                                                                                                                                                                                                                                                                                                              300
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     150
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      $DATA
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C #************************************	READ(5,1001)HED 1001 FORMAT(80A1) READ(5,1002)N8PL,SKIP3,SKIP4,SK 1002 FORMAT(1015)	READ(3-1000)XWINI,YWANI,YWAXI,Y F(Divr.E0.0.) Divr=1. 1000 FORMAT(8F10.0) TNRAS=100. IF(CAL.E0.29.) INRAS=200.	XRAS=(ABS(YMAXI-YMINI)#INDGY+1. YRAS=(ABS(YMAXI-YMINI)#INDGY+1. XMINI=XMINI#DIVR XMAXI=PDVR YMINI=YMINI#DIVR YMAXI=YMAXI#DIVR INDGX=INDGX/DIVP INDGY=INDGY/DIVR C ORIENTAF FRAME	DELTAX="55/NDGX DELTAY="55/NDGY DELTAY="75/NDGY IFFYRAS.LE.(CAL*INPAS)) GO TO 1 IFFXRAS.LE.(CAL*INPAS)) GO TO 1 IFFXRAS.LE.(CAL*INPAS)) GO TO 1 XRITE(6,2100) 2100 FORMAT(*OTHE SCALE TS TOU LARGE 5EGREE") STOP	C INTERCHANGE X AND Y SCALES I UNRITE(6,2101) I PORMAT(00THE PLDT WILL BE ROTAT STOR=XMINI XMIN1=YMAX1	YMAXI=YMXI XMXI=YMFNI YMINI=STOR STOR=DELTAX DELTAX=DELTAY DELTAY=STOR STOR-YDAS	XRAS=YRAS+3.5*INRAS XRAS=YRAS+3.5*INRAS YRAS=STOR GO TO 111 C 112 XRAS+3.5*INRAS	<pre>111 CALL WODESG(AWODES, MCRTGAT,BIN C DD 500 iP=1,NBPL AMODES(45)=1. XAXT=XMAX1</pre>
**************************************	AND THE PLOT ABORTED. ####################################	VARIABLE DESCRIPTION 1 Card (80a1) RUN IDENTIFICATION	(715) NB DF PLOTS =0. WILL PLOT EO OF MAG 3 =1. WILL NOT PLOT EO OF MAG 3 EO OF MAG 4 EO OF MAG 5 EO OF MAG 7 EO OF MAG 8	ARD (8F10.0) THE DRIGIN OF THE GRID IS DEFINED AS THE BOTTOW LEFT CORNER: THE END AS THE TOP RIGHT. THE VERTICAL HAS TO PDINT NORTH FOR THE DATA TO BE READ IN CONSISTENTLY. X CODED OF DRIGIN	Y COORD OF DAIGIN X COORD OF END. Y COORD OF END. Length of Dee Degree in Inches For The PLOT (X Direction). Length of One Degreee in Inches For	THE PLOT (Y DIRECTION) PLOTTER TO BE USED (10, DR 29.) The Zern, Will Be Set to 10. The Frame Consoinates are rounded off to The Closest (negree/nivg) IF INPUT AS 0. WILL RE SET TO 1	I EPICENTER PER CARD IMAGE (3FI0.0) Information read from disk X condrinate (longitude) df Epicenter Y coopdinate (latitude) df Epicenter Magnitude	<ul> <li>IT HAS TO BE TRANSFERRED ON TAPE AND</li> <li>CALCOMP PLOTTER</li> </ul>
######################################	MESSAGE WILL BE GENERATEO ####################################	COL VARIABLENAME 1 IDENTIFICATION CARD 1-80 HED	2 PLOT FLAGS 1 CARD 1-5 NBPL 6-10 SKIP3 11-15 SKIP4 16-20 SKIP4 16-20 SKIP5 26-30 SKIP5 26-30 SKIP8 31-35 SKIP8	3 GRID PARAMETERS 1 C 1-10 XMIN1	11-20 YMIN1 31-40 YMAX1 31-50 TNDGX 51-60 INDGY	61–70 CAL 71–80 DTVR	3 EPICENTER COURDINATES X( ) X( ) RM( )	DUTPUT ****** A FILE IS CPEATED ON DISK A FILE IS CPEATED ON DISK PLOTTED GN A 10 DR 29 INCI

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I W I W X = N I W X = N I W X = N I W X = N I W X = N I W X = N I W X = N I W X = N I W X = N I W X = N W X W X = N W X W X W X W X W X W X W X W X W X W	READIIO,1030)NBRC,HED 30 FDRMAT(I5,70Al)	IF(YRAS_LE_(CAL*INPAS)) GO TO 100 DO 120 TX=1.NB9C 23 9EAD(10,1010)X(TX),Y(TX),RM(TX) 10 FOPMAT(19X,F5.3,3X,F5.3,42X,F3.2) 60 TO 130	JO CONTINUE DD 140 IX≈1,NBRC 40 FEAD(10,1010)Y(IX),X(IX),RM(IX)	CHECK SIGNS 30 IF(XMAX1.GT.XMIM1) GD TD 150 XMAXXMAX1 Xuine-Xmini DD 160 IX-1,NBRC 50 X(IX)=-X(IX)	50 XFMAX=XMAX+DELTAX+6.25/.75 XFW?N=YM-DELTAX ff(MAX1.6T-YM!N1) GJ TD 170 YMAX=-YMAX1 YM1N=-YWIN1	DC 180 TX=1,NBRC 30 Y(TX)=-Y(TX) 70 FFMAX=PDELTA 76 FFMAX=PDELTA 52 WPTF(6,551)f(t(TX),Y(TX),RM(1X),TX=1,NBRC) 51 FORMAT(**+12F10.3)	AMDES(97)=XRAS AwdfS(179)=YRAS Call SubjeG(Amddes,XFMIN,YFMIN,XFMAX,YFMAX) Call ObjeGG(Amddes,0.,30.,XRAS,YRAS)	<pre>IF(AMDDES(12).NE.AMDDES(13))WRTTE(6.2102)AMDDES(12),AMDDES(13) PPPMAT(*0THE SCALES ARE NOT THE SAME*,2F10.6) FND1(1)=IFIX(YWAX) FND2(1)=IFIX(YWAX) END2(2)=IFIX(YWAX) END2(2)=IFIX(YWAX) END2(2)=IFIX(YWAX)</pre>	DELTA2=1./(8.*TNDGX) XMUL=4. DELTA1=4.*DELTA2 DELTA3=3.*DELTA2 STGN=-1.	I≈1 VAP=EMD1(2) FIX=FND2(2) DD 400 K=1,2
	с 103	101		94 10 10	1 12	119 55 55 55	u i	510		0 0 0

CALL INUMBG(AMDDES, XC, YC, 3, INTG) WRITE(6,550)XC,YC,INTG T=1+3 If(vAR,EQ.END1(K)) GD TD 402 VAR=VAA+SIGN GD TP 401 CALL INUMBG(AMODES, XC, VC, 3, INTG) WRITE(6,550)XC, YC, INTG I = I + 3If VAR.EQ.END2(K)) GO TO 403 VAR=VAR-SIGN GO TO 404 T=I-3 Call LINESG(AMODES,I,XX,YY) 400 CONTINUE C 00 500 K=1,1 C 500 WRITE(6,550)XX(K),YY(K) 550 FORMAT(\* ',2F10.3,16) 402 STDR= VAR VAR=FIX VAR=FIX 404 XK(1)=FIX XX(1+1)=FIX XX(1+1)=FIX XX(1+1)=FIX XX(1+2)=FIX XX(1+2)=FIXXX(1+2)=FIX XX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FIXXX(1+2)=FI 401 XX(I)=FIX V(I)=VAR XX(1+1)=FIX+DELTA2 YY(1+1)=VAP YY(1+2)=VAR YY(1+2)=VAR INTG=ABS(VAR) XC=FIX-DELTA2\*XMUL YC=VAP I8=0 DJ 300 IX=1,NBRC IRM=RM(IX)-1,99 FIX=5T0R DELTA2=-DELTA2 XMUL=2. DELTA3=-DELTA3 SIGN=-SIGN STDR=VAR VAR=FIX 13±0 14=0 15=0 16=0 17=0 403 υ ى U υ ပ

AMODES(45)= .5 AMODES(84)=12. F#(5KIP3.E0.0.AND.13.6T.0) CALL POINTG(AMODES,13,XX3,YY3) FF(5KIP3.E0.0.AND.13.6T.0) PRINT.13 HAS BEEN CALLED' FF(5KIP4.E0.0.AND.14.6T.0)CALL POINTG(AMODES,14,XX4,YY4) FF(5KIP4.E0.0.AND.14.6T.0)PRINT,14 HAS BEEN CALLED' FF(5KIP4.E0.0.AND.14.6T.0)PRINT,14 HAS BEEN CALLED' IFISKIP5.E0.0.AND.15.GT.0)CALL PDIVIG(AMDDES,15.XX5.YY5)
IFISKIP5.E0.0.AND.15.GT.0)PRIVI.15 HAS BFEN CALLED\* AMODES(84)=40. IF(SkIP6.EQ.0.AVD.I6.GT.0)CALL POINTG(AMODES,I6.XX6.YY6) IF(SkIP6.EQ.0.AND.I6.GT.0) PRINT.16 HAS PFEN CALLED' AMODES(84)=12. IF(SkIP7.E0.0.AND.I7.67.01CALL POINTG(AMODES.17.XX7.YY7) IF(SkIP7.F0.0.AND.17.67.01 PRINT.'!7 HAS REEN CALLED' AWTDES(45]=.65 AMDDES(84)=40. If(SKIP8.F9.0.AND.IR.GT.0)CALL PDIVTG(AMTDES.f8,XX8.YY8) If(SKIP8.E9.0.AND.IR.GT.0) PRINT,'I8 HAS REEN CALLED' IF(SKIP8.E9.0.AND.IR.GT.0) PRINT,'I8 HAS REEN CALLED' IF(IRM\_LT\*1) GD TD 300 GD TD (230,240,250,260,270,280),IRM 13=13+1 AMUDES(40)=8.\*INRAS/100. Amudes(41)=14.\*INPAS/100. XT=XMAX-.5/INDGX AMODE S(84)=15. AMDDE S(45)=.35 AM0.0ES(45)=2.0 AMDDE S( 50)=90. AMDDE S( 461=90. VT=YMIN+OELTAI AMNDES(45)=.5 XX3(I3)=X(IX) YY3(I3) = Y(IX)XX4([4)=X([X) YY4([4)=Y([X) XX5(I5)=X(IX) YV5(I5)=Y(IX) (XI)X=(91)9XX (XI) = (I) = X(IX)XX8[]8]=X[]X) YY8(I8)=Y(IX) GO TO 300 G0 T0 300 TO 300 GD TO 300 TO 300 60 TO 30 15=15+1 CONTINUE 1++1=+1 16=16+1 1+21=71I 8= I 8+1 69 230 240 260 250 270 280 300 υ U ပ J υ υ

AMODES(45)=1.5 AMODES(45)=1.5 CALL VECSG(AMODES,XT,VT,48,HED) CALL PICTRG(AMODES) PPINT, MAGNITUDE 3 FF(13.NE.0)WRITE(6.555)(XX3(1),YY3(1),I=1,13) PRINT, WAGNITUDE 4 + FF(15.ME.0)WRITE(6.555)(XX4(1),YY4(1),I=1,15) PRINT, WAGNITUDE 5 + FF(15.ME.0)WRITE(6.555)(XX5(1),YY6(1),I=1,15) PRINT, WAGNITUDE 5 + FF(15.ME.0)WRITE(6.555)(XX6(1),YY6(1),I=1,15) PRINT, WAGNITUDE 7 + FF(16.ME.0)WRITE(6.555)(XX6(1),YY6(1),I=1,15) PRINT, WAGNITUDE 7 + 5+1) (++9 (.+1 (.+8 XT=XFMAX-3./INDGX Call vecs6(amodes,XT,YT,16,\* . magnITUDE 4+\*) AMDDES(45)=.55 Call VecSG(AMDDES,XT,YT,16,' X MAGNITUDE MAGNI TUDE MAG NI TUDE MAGNI TUDE XT=XT+DELTA1 CALL VECSG(AMDDES,XT,YT,16,' + AMDDES(45)=1.0 Call Vecs6(AMDDES,XT,YT,16,' . AMODES(45)\*.35 CALL VECSG(AM@DES,XT,YT,16,' X FJRMAT(' ',12F10.3) CALL EXITG(AMODES) RETURN XT=XT+DELTA1 XT=XT+DELTAL XT = XT + 0ELTA1XT=XT+DELTA1 CONTINUE END 500 \$DATA U ں ں υ ں

4 ACCELERATION AT THE NODES 8 VALUES PER CARD (BFI0.0) 1-10 ACC(1,1C) ACC AT PRIGIN (TC=1) ACC(18,1C) ACC AT TOP OF FIRST COLUMN (IC=1) ACC(NR,1C) REPEAT NC TIMES MUTPUT ALLET IS CREATED DN DISK, IT HAS TO BE TRANSFERRED ON TAPE AND PLOTTED ON A 10 OR 29 INCH CALCOMP PLOTTER	DIMENSION AMDDES(200), ENDI(2), ENDI(2), XX(1000), YY(1000), A(4900) L, AA(70, 70), XF1(20), XF2(20), YF2(20), YF2(20), HED1(20) INTEGERAA, NR,NC, RDTA, SKIPAC REAL IMEAS, NUG, NUGS, INDGY LOGICALT HED2(80, INDGX, INDGY EQUIVALENCE(A(1), AA(1,1))	READ(5,1001)HED1 FORMAT(2044) WR TE 66,2202)HED1 READ(5,1003)SKIPAC,NF,NBPL,NR,NC,DX,DV,DC READ(5,1003)SKIPAC,NF,NBPL,NR,NC,DX,DV,DC READ(5,1003)SKIPAC,NF,NMIN,XMAX,YMAX,IN9GX,INDGY,CAL,DIVR IF(DIV8,EC,0,0) DIV8=1. FRINT,XHIN,YMIN,YMAX,YMAX,INDGX,INDGY,CAL,DIVR PRINT,XHIN,NRINC,XZ,VYMAX,INDGX,INDGY,CAL,DIVR	FORMAT(BF10.0) FORMAT(SF10.0) INRAS=100. IF(CAL.EG.29.) INRAS=200. DIVR IS USED TO TO BE ABLE TO PLOT PARTS OF DEGREES, USALLY DEGREE XMINA:FEIX(YMIN#DIVR5) VMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX#DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5) YMAX=IFIX(YMAX+DIVR5)	MUIA=0 ORTENTATE FRAME DELTAX-15/INDGX DELTAY-15/INDGX IF(YRAS.LE.(CAL*INRAS)) GO TO 100 IF(YRAS.LE.(CAL*INRAS)) GO TO 100 IF(YRAS.LE.(CAL*INRAS)) GO TO 100 FORMAT('OTHE SCALE IS TOO LARGE FOR THE PLOTTEP, REDUCE INDG PER D FORMAT('OTHE SCALE IS TOO LARGE FOR THE PLOTTEP, REDUCE INDG PER D SECREE') STOP INTERCHANGE X AND Y SCALES
		1001 2202 2203		50 510 50 50 50 50
<pre>CGAAW PLDT.ISO CGAAW PLDT.ISO CGAAW PLDT.ISO CGAAW PLDT.ISO CGAAW PLDT.ISO CGAAW PLDT.ISO CGAAW PLDT.ISO CGAAW PLDT.ISO CGAAW PLDT.ISO CGAAW PLDT.ISO CAAW PLC CAAW PL</pre>	odade Will PE Generated and the PLOT aburted. 	IDENTIFICATION CARD 1 CA°D (80A1) 80 HEN RUN IDENTIFICATION PLOT FLAGS 1 CARD (515,6F10.0) 5 SKIPAC =0, WILL PLOT ISO ACCELERATION LINES 10 NF NB OF FALUTS TO BE PLOTTED 15 NBPL NB OF PLOTS 20 NR ND OF ROUS IN INPUT	<ul> <li>5 DX DISTANCE (DEGREE) BETWEEN TWO COLUMNS</li> <li>5 DY DISTANCE (DEGREE) BETWEEN TWO ROWS</li> <li>5 DC DISTANCE (DEGREE) BETWEEN TWO ROWS</li> <li>5 DC DISTANCE (DEGREE) BETWEEN TWO ROWS</li> <li>6 PID PARAMETES I CARD (18 DE THE NOTON LET CORNER: THE END AS THE POLICY LES TO POINT</li> <li>6 DATA TO BETALE</li> <li>6 DATA TO BE TAGE</li> <li>7 CORD OF TAGE</li> <li>8 DATA</li> <li>8 DATA</li> <li>8 DATA TO BE TAGE</li> <li>8 DATA</li> <li>8 DATA TO BE TAGE</li> <li>8 DATA TO BE TAGE</li> <li>8 DATA</li> <li>9 DATA</li></ul>	70 CAL THE PLOT (Y DIRECTION) 80 DIVR THE FRAME COORDINATES ARE ROUNDED OFF 17 ZERO, WILL BE SET TO 10. 81 DIVR THE FRAME COORDINATES ARE ROUNDED OFF 70 THE CLOSEST (DEGREE/DIVR) 17 INPUT AS 0, WILL BE SET TO 1 10 YEI() X COORD OF ORIGIN OF FAULT 1 30 YEI() X COORD OF ORIGIN OF FAULT 1 30 YEI() X COORD OF ORIGIN OF FAULT 1 40 XF2() X COORD OF END OF FAULT 1 40 XF2() X COORD OF END OF FAULT 1 40 XF2() X COORD OF END OF FAULT 2 872070 OF END OF FAULT 2 90 YE2() X COORD OF FAULT 2 9

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C FIND INTERSECTION BETWEEN FAULTS AND FRAME IF(NF.NE.OICALL FRAME(MF,XMIN,YMIN,XMAX,YMAX,XFI,VFI,XF2,YF2)	C CALL WDDESG(AMODES, MORTGAT, BIN 502, 15) AMODES(97)=XPAS AMODES(179)=YPAS Call ObjecG(AMODEs,0,0, XRAS, YRAS) Ff(DTA.EQ.0) G9 TD 610 NST7R=NC NST7R=NC	610 CUNTIAUF 610 CUNTIAUF C DO 600 [P=1,MBPL C	CALL READ(AA,HEDZ,NB,NC,RCTA) C FIND LOWEP AND UPPER CONTOUR VALUES NBVL=NR*NC CALL IIMITS(A,NBVL,SKIPAC,CMIN,DC,CMAX)	C AMDDES(50)=0. AMDDES(46)=0. Call SURJEG(AMDDES,XFMIN,YFMIN,XFMAX,YFMAX) C IF(AMDDES(12),NF.AMDDES(13))WRITF(6,2102)AMDDES(12),AMDDES(13)	ZIOZ FORMATI "DTHE SLALES ARE NUT THE SAME", ZEIO. 21 C PLOT GRID ENDL(1)=FFIX(YMIN) ENDL(1)=FFIX(YMAX) FNDL(2)=FFIX(YMAX) FNDL2(2)=FFIX(YMIN)	C DELTA2=1./(8.*INDGX) XWUL=4. **NELTA2 DELTA1=4.*DELTA2 DELTA3=3.*DELTA2 AFLTA3=3.*DELTA2 C I=1 VAR=END1(2) FIX=END2(2) C DD 400 K=1.2 C DD 400 K=1.2	401 XX(1)=FIX V(T)=VAR XX(1+1)=FIX YY(1+1)=YAR YY(1+2)=YAR INTG=BESVAR XC=FIX-DELTA2*XMUL VC=VAR C_ALL FNUMBG(AMTDES,XC,YC,4,1NTG) XC=FIX-DELTA2*XMUL VC=VAR TETA CALL FNUMBG(AMTDES,XC,YC,4,1NTG) TETA TETA TETA TETA
110 WRITE(6+2101) 2101 FORMAT(*0THE PLDT WILL BE ROTATED BY 90 DEGREES COUNTERCLOCKWISE*)	RTTA=1 STOR=DX DV=STOR DV=STOR STOR=DELTAV DELTAV=STOR STOR=XMIN	XMIN=VMX XMX=XMX NIV=XTOR YMIN=STOR STOR=XRAS	XPAS=YPAS+3.5*INRAS YRAS=STOR IF(NF.EQ.O) G0 T0 144 READ FAULTS	RED(5,1007)(YF1(1),XF1(1),YF2(1),XF2(1),1=1,NF) 1007 FOR*AT(4F10.0) 60 TO 130 100 XRAS=XRAS+3.5*INRAS	IF(NF.EO.O) GD TD 144 READ(5,1007)(XF1(I),YF1(I),XF2(I),YF2(I),I=1,NF) 130 DD 143 T=1,NF XF1(I)=XF1(I)*DIVR	YFI(I)=YFI(I)#DIVR 143 YF2(I)=XF2(I)#DIVP 144 CCNTINUE CHECK SIGNS FF(XMAX.GT.XMIN) GD TD 150 TF(XMAX.GT.XMIN) GD TD 150 XMAX.=XMAIN TF(NF.E0.0) GD TD 150 DD 145 I=1.NF XFI(I)=-XF1(I) 145 XF2(I)=-XF2(I)	<pre>150 XFMAX=XMAX+DELTAX*4.25/.75 XFMIN=YMIN-OELTAX 1F(YMAX.GT.YMIN) GO TO 170 YMAX=-YMAX YMAX=-YMAX YMIN=YMIN 1F(NF.FC.0) GO TO 170 OO 146 1=1.NF OO 146 1=1.NF OO 146 1=1.NF YFI(1)=-YF1(1) 145 YF2(1)=-YF2(1) 170 YFMAX=YMAX+DELTAY YFMIN=YMIN-OELTAY</pre>

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PRINT, 'DELTAX, DELTAY, XFMAX,YFMAX',DELTAX, DELTAY, XFMAX,YFMAX XFMIN1=-DELTAX YFMIN1=-DELTAY	PRINT,'RASDR,XRAS,YRAS',RASDP,XRAS,YRAS Call Surjeg(amodes,xfmini,yfmini,xfmaxi,yfmaxi) Print,'Scale',amodes(12),amodes(13)	C CREATE COUNTOURS AND PLOT THEM Call Comt96(Amodes,4,NR,NC,DX,DY,CMIN,DC,CMAX)	C CALL PICTRG(AMPDES) 600 CONTINUF	C CALL EXITGIAMODES) Return	END Subrutine readiaa, Hed2, Nrow, Ncol, Nrot)	C ####################################	C THIS SUBROUTINE READS THE DATA TO BE INTERPOLATED READ(10,1002)HED2 1002 FDRMAT(80A1)	C IF(NROT.EQ.I) GO TO 110 C	C THE DATA IS STORED IN A TWO DIMENSIONAL ARRAY, A(1,1) BEING AT C THE ORIGIN OF THE PLOT (BOTTOM LEFT CORNER)	DD 100 IR=1,NRDW 100 READ(10,1000)(AA(IR,IC),IC*1,NCCL) 60 TD 99	C THE PLOT HAS BEEN ROTATED BY 90 DEGREES COUNTERCLOCKWISE, C THE ROWS AND COLUMNS ARE INVERTED IN THE CALL STATEMENT	<pre>110 CONTINUE DO ZOO T=1,NCOL T CENCOL+1-T 200 READ(10,1000)(AA(IR,IC),IR*1,NRCW) 99 CONTINUE</pre>	C DD 300 IR=1,NRUW 300 WRITE(6,1001)(AA(IR,[C],IC=1,NCCL) 1001 FORMAT(R=1, 5) 1000 FORMAT(R=1, 5)	C RETURN END SUBROUTINE LIMITS(A,NBVL,SKIPAC,CMIN,DC,CMAX)	C ####################################
VAP=VAR+SICN 50 TC 401	402 S104=VAR VA≿≠TX FIX=ST∩R 404 XY(I)=VAR	YY(1)=FIX XX(1+1)=KAA YY(1+1)=FIX+DELTA2	XX(1+2)=VAR YY(1+2)=F1X TMTG=ABS(VAP)	XC=VAR VC=FIX-DELTAR	CALL INUMBGIAMDDES,XC,YC,4,INTG) HRITE(6,550)XC,YC,INTG	I=1+5 IF(VΔP=CQ.END2(K)) GD TD 403 VAR=VAR-SIGN GD TP 404	403 SIGN=-SIGN STCA=VAR VAR=FIX FIX=STCP °	DELTA Z=−DELTA Z XMUL Z Z DELTA Z =−DELTA 3	400 CONTINUE	500 WATTE(6,5501XXK1,YY(K) 550 FAPMAT(* ',2F10,3,16) 1=1-3	CALL LINESG(AMUDES,I,XX,YY) Plot title	XT=XFMAX - 3.*PELTAX IF(CAL.EQ.29*) AWDDES(45)=3. ANDDES(50)=90. AMODES(50)=90. YT=YMINDFLTAL	CALL VELSSIAMUUESSALTTIABATEOZI AMODES(45)=1. IF(NF 62,0) GO TO 142 BI AT EALLTE	PRINT,"FAULTS AS THEY ARE PLOTTED" PRINT,"FAULTS AS THEY ARE PLOTTED" Watte(6,2011)(1,xf1(1),Yf1(1),Xf2(1),Yf2(1),f=1,NF) 2011 FORMAT(",15,4F10,3) CAN: SEGWT(AMODFS.MFXF1,XF2,YF2)	142 CONTINUE CHAMGE SUBJECT SPACE TO PLOT CONTOURS, THE BOTTOM LEFT CORNER HAS TO HAVE (00.) COORDINATES XMAX1=ABS(XFMAX-YFMIN)-DELTAX YFMAX1=ABS(YFMAX-YFMIN)-DELTAX

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<pre>GO FO 200 300 XF2(IF)=SIGN*CHECK YF2(IF)=ASU*XF2(IF)+RET 200 XF2(IF)*SIGN SIGN=1. 100 CHECK=-XMAX C CHECK THE Y COCROINATES DF THE FAULT CHECK=YMIN CHECK=YMIN C CHECK FOR LOWER AND UPPER BORN C CHECK FOR LOWER AND UPPER BORN</pre>	UN 110 X=1.2 YEAYEI(TE)ASIGN C CMECK FOR ORIGIN AND END OF SEGMENT DO 210 T=1.2 TEYF.GF.CHECKJ GO 70 210 ASLETVEI(TE)-VF2TTE)/JKFLITE)-XF2(TF)) BETEVEI(TE)-VF2TTE)/JKFLITE)-XF2(TF)) TF(T.F0.2) CO TO 310	C CHANGE COORDINATES YFI(IF)=S(AWCHECK XFI(IF)=(YF(ITF)-RET)/ASL GO TO 210 310 YF2(IF)=S(GA*CHECK XF2(IF)=(YF2(IF)-BET)/ASL 210 YF2(IF)=S(GA*CHECK SIGN=1.	IIO CHECK=-YMAX C 500 CANTINUF Berurn End Subroutine Confreiamodes, A, Nr, NC, DX, DY, Chin, DC, CMAX ) Subroutine Confreiar Pinting subroutine C c contruir Pinting subroutine	C NAPCH 3, 1970 MAPCH 3, 1970 C USE: C USE: C WHERE: AMODES IS THE 200 ELEMENT MODE-SET-APRAY.	<ul> <li>A IS A RUE DIFFUSIONAL APRAV CONTAINING FUNCTION VALUE</li> <li>D A UNIFGA LY SPACED GRID. AA IS ONDEED AS AN EOULVARENT TAN BLASTIONAL ANAL ANAL WITH FIRST FOLOWN C BAT THE ADTION OF THE ROID (JSO) AND THE FIRST COLUMN AT THE LEFT SIDE (IY=0.) AND THE FIRST COLUMN AT THE LEFT SIDE (IY=0.), THE SUDJECT SPACE HAS TO WE SET AS FOLLOW (00., NC*DX, MR*DY)</li> </ul>	C REAL ANDER OF POINTS IN THE Y-DIMENSION. MC IS THE NUMARS OF POINTS IN THE X-DIMENSIOM. DX IS THE X-DISTANCE RETWEEN POINTS. (SURABET UNITS) C DY IS THE Y-DISTANCE RETWEEN POINTS. (SURABET UNITS) C DY IS THE Y-DISTANCE RETWEEN POINTS. (SURABET UNITS)
<pre>IF(SkIPAC.NE.1) GO F9 110 C FIND INTENSITIES USING RICHTER GUTENBERG RELATIOWSHIP 0 99 LUNE=1.NBVL 0 00 TINUE 110 CONTINUE 110 CONTINUE 110 CONTINUE 0 120 TV=2.NBVL 100 100 TV=7.NBVL 100 CONTINUE 100 CONTINUE</pre>	C SEARCH FMR UPPER BOUND C SEARCH EMR UPPER BOUND D 200 IV=2.MBVL IFLA(IV.GT.XHIGH) XHIGM=A(IV) 200 CONTINUE C FIND LOW AND MIGH CONTOUR LINES TO BE PLOTTED C MIN=-DT	300 CMTWHECT IFICWIN-LT-XLDWN GD TO 300 C CMAXECWIN-DC 400 CMAXECWIN-DC 1FICMAX-LT-XHIGH) GD TO 400 C MAXECWAX-DC C MAXECMAX-DC C MAXECMAX-DC C PRINT,*XLDW,XHIGH,CMIN,CMAX	С RFTURN END SUMRULTINE FRAMF(NF,XMTN,YMIN,XMAX,YMAX,XF1,YF1,XF2,YF2) C Фермаликинанскийнийнийн автанийн автанийн автанийн автаний C Фермаликин (10,10,10,10,10,10,10,10,10,10,10,10,10,1	C LIMIT THE FAULTS TO THE AREA UNDEP CONSIDERATION DD 500 IF=1.VF C CHECK THE X COMPDINATES OF THE FAULT SIGN=1. CHECK=XWIN	C CHECK FOR LOWER AND UPPER BORN DO 100 K=1,2 KF=XF11F)+51GN C CHECK FOP CRIGIN AND END OF SFGMENT C CHECK FOP CRIGIN AND END OF SFGMENT	IF(XF.SF.CHFK) GD TP 200 ASL=(YF](F)-YF2[(F))/(XF1(F)-XF2(F)) BFT=YF1(F)-ASL*XF1(F) IF(T.F0.2) GD TP 300 C CHANGF COPPINATES YF1(F)=ASL*XF1(F)+AFF YF1(F)=ASL*XF1(F)+AFF

A4-24



A4~25

# APPENDIX 5

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NEWMARK AND HALL PAPER

(Taken from reference 52)

#### PROCEDURES AND CRITERIA FOR EARTHQUAKE RESISTANT DESIGN

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#### N. M. Newmark and W. J. Hall

#### Urbana, Illinois

## I. Introduction

When a building or other structure is subjected to earthquake motion, its base or support moves with the ground. Since this motion is relatively rapid, it causes stresses and deformations throughout the structure. If we neglect temporarily the interaction between the base of the structure and its foundation, when the structure is quite rigid, its motion is nearly the same as that of the ground and the dynamic forces acting on it are very nearly equal to those associated with the ground accelerations applied to the structure as a rigid body. If the structure is quite flexible, large relative motions or strains can be induced in the structure because of the differential movements between the supports and the masses of the structure. In order to survive the earthquake motions the structure must be either strong enough or ductile enough to resist the forces generated by these deformations; the combination of the required strength and ductility is a function of the stiffness or flexibility of the structure.

Seismic effects on a structure, component or element, depend not only on the earthquake motion but also on the properties of the structure, component or element itself. Among these properties, the most important are the energy absorption within it or at interfaces between the item under consideration and its support, either due to damping or inelastic behavior, its period of vibration, and its strength or resistance.

It is the purpose of this paper to describe the general nature of the principles upon which earthquake resistant design is based, and to consider the development of design procedures for the design of structures, facilities or components.

Examples of structures that did not have sufficient strength and ductility to resist the earthquakes to which they were subjected are well known. Failures occurred in the columns and frames of buildings in Caracas, for example, when inadequate strength and energy absorbing capacity were available for the earthquake of 1967. Other failures in earthquakes are clearly due to lack of adequate support details, or lack of adequate continuity between individual elements.

Emphasis is placed herein on design as contrasted with analysis, and essentially on preliminary design or the selection of the general outline, type of framing, and first estimate of requirements. This choice of emphasis is made because methods suitable for such purposes generally can assure adequate performance and serve as a check on designs made by more sophisticated methods.

The general concepts presented in this paper have been adapted from those given in References [1], [2], [3], and [4].

The design of a structure, as either a complete system in itself, or as part of the system of which the structure is only a component, can be a highly complex matter involving a number of input data of various types and a host of special requirements. Once the structure has been dimensioned, that is, laid out in plan and the size and strength of its various elements selected, then the analysis of the structure for given conditions of loading and foundation motion can be made by relatively well understood methods, even though the analysis can be a tedious and lengthy one for a complex system. However, unless the designer uses a so-called "direct design" procedure, he is faced with a problem of the preliminary selection of the structural layout, framing, element strength, and the like, before he has a structure which he can analyze. Even with direct design procedures, for important structures he will want to have some handy approximation that can be used for his preliminary studies.

The steps which the designer must take are generally as follows:

- (1) Select the earthquake hazard.
- (2) Select the safety factor, or the allowable limits of deformation, or the allowable probability of damage or failure. This may depend on step (3).
- (3) Select the type or layout of the structure, and estimate its dynamic (and static) parameters. These include a) dynamic resistance, b) natural frequency or period of vibration, c) damping or energy absorption, d) ductility that can be counted on before failure. These may be assigned in a direct-design procedure, or are subject to successive revision in more traditional procedures.
- (4) Verify the adequacy of the structure selected, and make any necessary changes in strength or other parameters, or in the complete layout or plan.
- (5) Repeat steps (3) and (4) until a satisfactory design is achieved.
- (6) Make a more accurate analysis of the final design, and make further changes that may be necessary. If these are not minor, steps (3) to (6) may need repeating. In some cases revisions in steps (1) and (2) may be desirable. In other cases an upper bound direct procedure may be used involving essentially only steps (1), (2), and (3). Most so-called "static design codes" are intended to be of this type.

## II. Earthquake Hazard

Earthquakes are relatively rare occurrences, but in many regions of the world one can count on a high probability of at least a small earthquake occurring once in the lifetime of a building. However, the stronger or more intense the earthquake the smaller is the probability of its occurrence. An earthquake that has a relatively high probability of occurrence is appropriately considered as a loading for which the design must provide in such a way that the cost of the minor repairs required is not excessive. Major strengthening of a structure to resist intense forces is expensive, and the cost of such design provisions must be weighed against the possible cost of repairs in order to design whether the additional design strength or ductility is economically justified.

It is generally agreed that structural collapse of such a nature that it might endanger a great many lives should be prevented by the design, even for the maximum credible earthquake. But it would be unreasonable and uneconomical to provide for resistance to an extreme earthquake with the same factor of safety or margin of safety that one normally uses. The selection of the factor of safety for the maximum credible earthquake is in part dependent on the nature and importance of the structure, and on the consequences should the structure fail.

Unfortunately the earthquake hazard for which designs should be made is

subject to a high degree of uncertainty. In only a few areas of the country are there relatively long periods of observation of strong earthquake motions. By correlating the available strong motion records with the more common records available from the sensitive recording instruments used by seismologists, and by use of qualitative reports of the effects of earthquakes where motion records are not available, some measure can be obtained of the maximum intensities which have occurred in various geological regions, and predictions can be made of those which might occur in the future. In other regions of the country, where records are scarcer, estimates of a similar nature can be inferred but are much more uncertain.

However, the maximum historical earthquake determined by such a procedure is not a proper measure of the possible intensity of an earthquake which might occur in the future nor of the earthquake for which the design should provide. At some sites, maximum or extreme earthquakes might never have occurred in the past; it is almost certain that they did not occur within the period of recorded history.

In order to specify adequately the earthquake intensity for either the historical or the extreme earthquake, one must do more than determine the possible or probable acceleration of the ground. The character of the earthquake motions must also be described in a way that is representative of the geologic conditions, taking into account the local soil conditions including overburden depths and characteristics, presence of water, depth to basement rock, and the like. A better measure of the free-field earthquake motions is a description which includes not only the maximum ground acceleration, but also the maximum ground velocity and the maximum ground displacement, with some measure of the number of pulses or the duration of the strong motions that should be considered. All of these quantities are dependent on the geologic and soil characteristics, and are in part dependent on the soil-structure interaction of the structure supported on the soil or rock.

Earthquakes in different parts of the world on different types of foundations and rock or soil strata have greatly different characteristics. The Niigata Earthquake of 1964 was characterized by the phenomenon of liquefaction of the soil and foundation failures causing tilt and overturning of a number of buildings that otherwise would not have been badly damaged. The earthquakes in Mexico City are affected by the natural frequency of the huge bowl of soft jellylike soil which underlies most of the central part of the city, and which emphasizes and amplifies motions in the range of periods of vibration of 2 to 2.5 sec. and diminishes those of very low period, of less than 0.5 sec.

The low buildings, the old churches and the cathedral in Mexico, many of which have been in existence several hundred years during which time Mexico has been subjected to serious shaking from earthquakes, generally have not been severely damaged by earthquakes, but modern tall buildings were seriously damaged, especially in the earthquake of 1957. Nevertheless, one building, construction of which was completed during the early 1950's, the Latino Americana Tower, survived this earthquake and, subsequently, the several slightly less intense earthquakes of the past decade with no damage, not even cracking of window panes. This is due to the fact that the expected nature of the earthquake motions was taken into account in its design. The building is of interest because it was the first building which was designed in accordance with modern analytical methods that was actually subjected to an earthquake approaching the intensity of the earthquake for which it was designed.

With the increased knowledge of the characteristics of earthquakes from the records obtained of strong motions in earthquakes in various parts of the world, we now have the basis for a much more detailed description of the type and intensity of earthquake motions that should be considered for design of structures of various types in various regions, taking into account the

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geologic conditions as well as the foundation materials under the buildings.

## III. General Design Concepts

## General Principles

The designer's freedom of choice in selecting methods of resisting earthquake motions is restricted by the necessity that he comply with the architectural form selected for the building. If the form follows the function, the constraints are generally minimal. However, it is not necessarily true that an efficient earthquake resisting capability can be put into any arbitrary form of envelope for the structure. The designer must, therefore, have latitude in his selection of the resisting elements of the structure. He may choose a flexural framework; or a structure having resistance primarily in the outer walls as a monocoque assembly; or a structure strengthened by shear walls or by bracing; or a structure with a resisting core from which the lower parts of the building are hung; or various modifications and combinations of these. The methods of achieving strength and ductility in these various forms are necessarily different and the design criteria have to take this into account.

The permissible level of response of a structure, element or component, must be associated with a loading criteria. The response criteria should properly be dependent on the type of structure, the relative cost of repairs for minor damage, and the hazard in terms of possible loss of life should the item fail or reach extreme deformation limits. The seismic resistance of an element is a function primarily of its yield strength, its natural frequency of vibration, its damping and energy absorption in the elastic range, and its ductility and energy absorption capacity in the range before unacceptable damage occurs.

#### Dynamic Resistance

Detailed descriptions of the response of simple elastic systems, or more complex structure and elements, subjected to dynamic loading and especially to seismic loading, are given in References [2], [3], and [4]. In general, it can be shown that the response of a simple damped oscillator to a dynamic motion of its base can be represented graphically in a simple fashion by a logarithmic plot as shown in Figure 1. In this figure, there are shown on the one plot, using four logarithmic scales, the following three quantities:

- D = Maximum relative displacement between the mass of the oscillator and its base
- $V = Maximum pseudo relative velocity = \omega D$
- A = Maximum pseudo acceleration of the mass of the oscillator =  $^{2}\omega D$

In these relations,  $\omega$  is the circular natural frequency of the oscillator.

The effective maximum ground motions for the earthquake disturbance for which Fig. 1 is drawn are maximum ground displacement  $d_m = 10$  in., maximum ground velocity  $v_m = 15$  in. per sec., maximum ground acceleration  $a_m = 0.3g$ , where g is the acceleration of gravity. The curve shown is a smooth curve rather than the actual jagged curve that one obtains from a precise calculation. The symbols 1, 2 and 3 on the curve represent oscillators, item 1 having a frequency of 20 cps, item 2 of 2.5 cps, and item 3 of 0.25 cps. It can be seen that for item 1 the maximum relative displacement is extremely small, but for item 3 it is quite large. On the other hand, the pseudo acceleration for item 3 is relatively small compared with that for item 2. The pseudo relative velocities for items 2 and 3 are substantially larger



FIG. I RESPONSE SPECTRUM FOR TYPICAL EARTHQUAKE

than that for item 1.

The advantage of using the tripartite logarithmic plot, with frequency plotted also logarithmically, is that one curve can be drawn to represent the three quantities D, V and A. The pseudo relative velocity is nearly the same as the maximum relative velocity for higher frequencies, but differs substantially for very low frequencies. It is, however, a measure of the energy absorbed in the spring. The maximum energy in the spring, neglecting that involved in the damper of the oscillator, is  $MV^2/2$ , where M is the mass of the oscillator.

The pseudo acceleration is practically the same as the maximum acceleration, and the quantity MA is precisely the maximum force in the spring. Therefore, the pseudo acceleration is exactly the same as the maximum acceleration when there is no damping.

In the discussion and figures which follow, the terms "velocity" will be used for V and "acceleration" for A without the explanatory words maximum, pseudo, relative or absolute.

There are many strong motion earthquake records available. One that has been used for a number of years is that for the El Centro earthquake of May 18, 1940. The response spectra computed for the earthquake for several different amounts of damping are shown in Figure 2. The oscillatory nature of the response spectra, especially for low amounts of damping, is typical of the nature of response spectra for earthquake motions in general. A replot of Fig. 2 is given in Fig. 3 in a dimensionless form where the scales are given in terms of the maximum ground motion components. In this figure, the ground displacement is given by the symbol y, and the subscript m designates a maximum value. Dots over the y indicate differentiation with respect to time.

It can be seen from Fig. 3 that for relatively low frequencies, below something of the order of about 0.05 cps, the maximum displacement response D is practically equal to the maximum ground displacement. For intermediate frequencies, however, greater than about 0.1 cps, up to about 0.3 cps, there is an amplified displacement response, with amplification factors running up to about three or more for low values of the damping factor  $\beta$ .

For high frequencies, over about 20 to 30 cps or so, the maximum acceleration is practically equal to the maximum ground acceleration. However, for frequencies below about 6 cps, ranging down to about 2 cps, there is nearly a constant amplification of acceleration, with the higher amplification corresponding to the lower values of damping. In the intermediate range between about 0.3 to 2 cps, there is nearly a constant velocity response, with an amplification over the maximum ground velocity. The amplifications also are greater for the smaller values of the damping factor.

The results shown in Fig. 3 are typical for other inputs, either for other earthquake motions or for simple types of dynamic motion in general. The data from which Fig. 3 was drawn, as well as other similar figures, are taken from Reference [2].

#### Natural Frequency

The dynamic response of a structure is a function, among other things, of its natural frequencies of vibration in its various modes. Natural frequencies can be computed from the mass and stiffness distributions of the structure but such calculations involve an idealization of the structure for the purpose of the analysis. The influence of nonstructural components on natural frequencies can be of particular importance. Also the natural frequencies may be affected to a large degree by the foundation-structure



FIG. 2 RESPONSE SPECTRA, EL CENTRO EARTHQUAKE, MAY 18, 1940, NORTH-SOUTH DIRECTION





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#### interaction.

Design specifications which involve natural frequencies have the disadvantage that the structure must be designed, at least in a preliminary way, before the frequencies can be determined, or else the frequencies must be estimated from factors involving judgment and overall dimensions. Hence, such methods may involve relatively large errors in the response or else the method of design must be one of continuing approximations and revisions.

## Damping

Energy absorption in a structure arises in various ways including damping or energy absorption of various types within the structure itself, friction or viscous damping, or other types of damping in the structure as well as in the parts of the structure interfering with each other or moving against one another. These can all be generally approximated by use of a damping coefficient. The damping is a function of the intensity of motion and of the stress levels induced within the structural components, and it is highly dependent on the makeup of the structure and the energy absorption mechanisms within it and at its interfaces with the foundation or with other structures. The importance of damping is indicated by the fact that the dynamic response of a structure in an earthquake may be affected to as great a degree by damping as by almost any other parameter. This is especially true in those instances when long sustained nearly harmonic motions are involved. It is because of this reason that the greatest difficulties are found with design specifications other than of the performance type in which the design forces do not properly reflect the differences in damping associated with different materials, different types of framing, and different levels of allowable deformation and stress.

#### Inelastic Behavior and Ductility

Let us now consider the situation in which the simple oscillator has a spring which can deform inelastically during the response. The simple resistance-displacement relationship for the spring is shown by the light line in Fig. 4, where the yield point is indicated, with a curved relationship showing a rise to a maximum resistance and then a decay to a point of maximum useful limit or failure at a displacement  $u_m$ . An equivalent elasto-plastic resistance curve is shown by the heavy line in the figure, rising on a straight line to a point where the yield displacement is  $u_y$  and the resistance  $r_y$ , and then extending without appreciable increase in resistance to the maximum displacement  $u_m$ . The effective resistance curve is drawn so as to have the same area between the origin and  $u_y$  as the actual curve, and again the same area to the maximum displacement point. The ductility factor  $\mu$  is defined as the ratio between the maximum permissible or useful displacement to the yield displacement, for the effective curve.

It is convenient to use an elasto-plastic resistance-displacement relation because one can draw response spectra for such a relation in generally the same way as the spectra were drawn for elastic conditions in Fig. 2 and 3. In Fig. 5 there are shown acceleration spectra for elastoplastic systems having 2% of critical damping for the El Centro 1940 earthquake. Here, the symbol  $D_y$  represents the elastic component of the response displacement, but is not the total displacement. Hence, the curves also give the elastic component of maximum displacement as well as the maximum acceleration, A, but they do not give the proper value of maximum velocity. This is designated by the use of the symbol V' for the pseudo velocity drawn in the figure. The figure is drawn for ductility factors ranging from 1 to 10. It is typical of other acceleration spectra for elasto-plastic systems, as indicated by the acceleration spectra shown in Fig. 6 for the step displacement pulse sketched in the figure.



FIG. 4 RESISTANCE - DISPLACEMENT RELATIONSHIP









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Figure 6 is drawn for a step displacement pulse corresponding to the two triangular pulses of acceleration shown, where the total length of time required to reach the maximum ground or base displacement is 1 second. The frequency scale shown in Fig. 6 will be changed for any other length of time, t, to reach the maximum displacement by dividing the frequencies f by t. In other words, for a step displacement pulse that takes 0.2 sec., the abscissa for a frequency of 1 cps would be changed to 5 cps, and that for 3 cps in the figure would be changed to 15 cps, etc. The general nature of the similarity between Figs. 5 and 6 is important.

One can also draw a response spectrum for total displacement, as shown in Fig. 7. This is drawn for the same conditions as Fig. 5, and is obtained from Fig. 5 by multiplying each curve's ordinates by the value of ductility factor µ shown on that curve. It can be seen that the maximum total displacement is virtually the same for all ductility factors, actually perhaps decreasing even slightly for the larger ductility factors in the low frequency region, for frequencies below about 2 cps. Moreover, it appears from Fig. 5 that the maximum acceleration is very nearly the same for frequencies greater than about 20 to 30 cps for all ductility factors. In between, there is a transition. These remarks are applicable to the spectra for other earthquakes also. One can generalize about them in the following way for general nonlinear relations between resistance and displacement, for single degree of freedom structures.

For low frequencies, corresponding to something of the order of about 0.3 cps as an upper limit, displacements are preserved. As a matter of fact, the inelastic systems have perhaps even a smaller displacement than elastic systems. For frequencies between about 0.3 to about 2 cps, the displacements are very nearly the same for all ductility factors. For frequencies between about 2 up to about 6 cps, the best relationship appears to be to equate the energy in the various curves, or to say that energy is preserved, with a corresponding relationship between deflections and accelerations or forces. There is a transition region between 6 and 20 to 30 cps, depending on the damping ratio. Above 20 to 30 cps, the force or acceleration is nearly the same for all ductility ratios.

#### Structure-Foundation Interaction

Earthquake motions are transmitted through the ground to the foundation of a structure and then to the structure itself. The interaction between the foundation components of the structure and the earth upon which it rests are of particular importance in defining the nature of the forces and motions transmitted to the structure. Energy absorption can take place at the interfaces between the structure and the foundation, and between the foundation and the supporting medium. Under certain conditions amplifications of motion may even occur. The interaction between the foundation medium and the foundation structure can be particularly complicated when the building is set into the soil or rock rather than resting upon it.

Design specifications either of the cookbook type, the intermediate type, or the type solely concerned with environmental and performance criteria fall short of their requirements if they do not consider the interaction between the structure and its supports, and especially the type of supports, whether it is pile or caisson foundations, isolated footings, or a mat, or some combination of these.

#### Nonstructural Components

In buildings, particularly, it is necessary to make a distinction between those components which are essential parts of the structure in its resistance to loads and deformations, and nonstructural components which are those parts needed to perform the proper function of the structure but which



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are not added primarily for resistance to lateral forces. Partitions in a building may be structural or nonstructural depending upon whether they are designed to act as part of the load-carrying framing. However, whatever the designer's intent may be, all the elements of the structure, whether functional or otherwise, have an effect on the behavior of the building under dynamic excitation, and must be considered in terms of dynamic response, strength, and the damage which may be caused by exceeding allowable stress or deformation limits. Even nonfunctional ornamentation on a building that can be dislodged because of lateral motion can cause hazard to life as well as property.

## IV. Design Procedures

#### General Approach

The designer has considerable freedom of choice, in general, as to the type of resisting structure he will use in the design. He may choose a flexible, energy-absorbing structure which can comply with the ground motion readily, or he can use a rigid structure to limit the relative deformation within the structure itself. In one case the strains in the structure are determined primarily by the maximum transient ground displacement or velocity, and in the other they are determined primarily by the maximum transient ground acceleration.

If the structure is in an intermediate range of stiffness, then its energy absorbing capacity is of the greatest importance, which involves both its strength and ductility in some balanced manner. Under these conditions, one may reduce the strength and increase the ductility, or increase the strength and reduce the ductility, in both cases arriving at a satisfactory design. Although the designer must be careful in the determination of these balances, and must look into the strength and ductility of elements or components as well as those of the completed assemblage, he can make up for deficiency in one by an overdesign in the other, in many instances. Constraining the designer to use always highly ductile elements may be unreasonably restrictive since it appears possible to design a structure with as much margin to resist failure by making it less ductile but stronger, in an appropriate fashion. It appears unwise to establish design criteria solely on preconceived notions as to either strength or ductility without considering the combination of both of these that is required for adequate performance.

Theoretically and to a considerable extent practically, it is possible to use any material in almost any fashion one chooses to use it, by providing the proper combination of strength and ductility associated with the particular structural configuration and dimensions, thereby to insure that the completed structure will be able to perform adequately under the appropriate loading or motion environmental conditions.

It has already been noted that in many structures it is desirable, and in fact quite proper and reasonable, for the structure to go well into the inelastic range of behavior, especially for the maximum or extreme environmental seismic conditions. Different types of framing and different materials pose a variety of problems for an adequate specification of performance involving deformations and stresses beyond yield. This has been taken into account in existing codes in various ways, usually by specifying the relative intensity of loading to be considered for different types of framing. Each material must be studied from the point of view of its particular characteristics of strength and ductility, when fabricated into structural members or elements, or when connected together to form a structure. The performance criteria must be prepared in such a way as to avoid unusual handicaps to any one type of framing or material, or to give unusual advantages to any other type.

## Selection of Parameters

In the light of the preceding discussion, we can now develop a basis for design of structures, elements or components, where these are subjected directly to the ground or base motion for which we have maximum values of displacement, velocity and acceleration. We first proceed with selection of values of damping. Table 1 is reproduced with some changes from References [5] and [6], and gives the percentage of critical damping for various types and conditions of structures or elements, as a function of stress level. It represents the best information available at the present time, but certainly involves a great deal of judgment and interpretation.

The damping in structural elements and components and in supports and foundations of the equipment is a function of the intensity of motion and of the stress levels introduced within the structural component or structure, as well as being highly dependent on the makeup of the structure and the energy absorption mechanisms within it. For example, a structure with riveted or bolted joints that can undergo relative motion during deformation will absorb a great deal of energy in friction in these joints. A reinforced concrete beam that is cracked, where the elements on the two sides of the crack can move relative to one another with the absorption of energy at the faying surface, will also absorb considerable energy. On the other hand, a homogeneous solid structure or a welded steel structure has relatively small amounts of lost energy because of play in the joints, and a concrete beam before cracking has a relatively small amount of energy losses except those within the material itself. Hence, the degree of damping depends on the framing and makeup of the structure or elements, and on the material used and the stress level within the material for the degree of excitation which it experiences in the shaking motion. For low stress levels and for homogeneous structures, steel or reinforced concrete below cracking levels, the damping may be no greater than in the range of one-half to one percent. For stresses at the level of working stresses or at about half the level of yield point values, the damping may range from about 2 percent for welded steel structures, for well reinforced concrete structures with only small amounts of cracking or for prestressed concrete structures, to 3 percent to 5 percent for ordinary reinforced concrete structures with considerable cracking, and possibly above 5 percent for riveted or bolted connections, or for wood structures with nailed joints and the like. At or near yield point values of stress, the damping may be in the range of about 5 percent for steel structures and prestressed concrete structures that have not completely lost their prestress, ranging to 7 to 10 percent for ordinary reinforced concrete, and as high as 10 to 15 percent for structures with play in the joints, or for masonry structures.

The fundamental frequency of vibration, or its reciprocal, the fundamental period, is best estimated by a simple calculation by use of standard methods of analysis such as are described in Reference [3]. For buildings simple rules, also given in [3], are often used to approximate the fundamental frequency, but are generally not reliable for unusual types of framing or for extremely heavy or extremely light construction.

The ductility factors for various types of construction are more difficult to characterize. They depend on the use of the building, the hazard involved in its failure, the material used, and the framing or layout of the structure, and above all on the method of construction and the details of fabrication of joints and connections. A discussion of these topics is given in Reference [3] also.

#### Design Spectrum - Elastic

In either analysis or design for earthquake resistance it is convenient to use the concept of the response spectrum. A response spectrum developed to give design coefficients is called a "Design Spectrum".

# Table 1

# RECOMMENDED DAMPING VALUES

Type and Condition of Structure	Percentage of Critical Damping
a. Vital piping	0.5 to 1.0
b. Welded steel, prestressed concrete, well reinforced concrete (only slight cracking)	2
c. Reinforced concrete with considerable cracking	3 to 5
d. Bolted and/or riveted steel, wood structures with nailed or bolted joints	5 to 7
a. Vital piping	2
b. Welded steel, prestressed concrete (without complete loss in prestress)	5
c. Prestressed concrete with no prestress left	7
d. Reinforced concrete	7 to 10
e. Bolted and/or riveted steel, wood structures, with bolted joints	10 to 15
f. Wood structures with nailed joints	15 to 20
	<ul> <li>Type and Condition of Structure</li> <li>a. Vital piping</li> <li>b. Welded steel, prestressed concrete, well reinforced concrete (only slight cracking)</li> <li>c. Reinforced concrete with considerable cracking</li> <li>d. Bolted and/or riveted steel, wood structures with nailed or bolted joints</li> <li>a. Vital piping</li> <li>b. Welded steel, prestressed concrete (without complete loss in prestress)</li> <li>c. Prestressed concrete with no prestress left</li> <li>d. Reinforced concrete</li> <li>e. Bolted and/or riveted steel, wood structures, with bolted joints</li> <li>f. Wood structures with nailed joints</li> </ul>

In general, for any given area or site, estimates might be made of the maximum ground acceleration, maximum ground velocity, and maximum ground displacement. The lines representing these values can be drawn on the tripartite logarithmic chart of which Fig. 8 is an example. The lines showing the ground motion maxima in Fig. 8 are drawn for a maximum ground acceleration of 1.0g, velocity of 48 in/sec., and displacement of 36 in. These data represent motions more intense than those generally considered for any postulated design earthquake hazard. They are, however, approximately in correct proportion for a number of areas of the world, where earthquakes occur either on firm ground, soft rock, or competent sediments of various kinds. For relatively soft sediments, the velocities and displacements might require increases above the values corresponding to the given acceleration as scaled from Fig. 8. However, it is not likely that maximum ground velocities in excess of 4 to 5 ft per second are obtainable under any circumstances.

Amplification factors for the various ranges in the response spectrum were considered in References [5] and [6]. The values determined therein for a number of earthquakes, with some smoothing and reduction of peaks to present a reasonably consistent probability of failure (of the order of about 10 percent or less), are given in Table 2. The amplification factors given in that table are used in connection with Fig. 8, as explained below.

For each of the amounts of damping shown in Fig. 8 or tabulated in Table 2, the amplified displacements are shown on the left, the amplified velocities at the top, and the amplified accelerations in that part of the right-hand side of the figure for which the lines are parallel to the maximum ground acceleration line, but lie above it. We shall identify these portions of the line as the amplified displacement region, the amplified velocity region, and the amplified acceleration region, respectively.

At a frequency of about 6 cps, the amplified acceleration region line intersects a line sloping down toward the maximum ground acceleration value, and intersecting that line at various frequencies, depending on the damping. The intersection is at a frequency of about 30 cps for 2% damping, and the other lines are parallel to the line for 2% damping. These lines are designated as the acceleration transition region of the spectra. Finally, beyond the intersection with the maximum ground acceleration line, the response spectrum continues with the maximum ground acceleration value for higher frequencies.

The spectra so determined can be used as design spectra for elastic responses. The spectra are completely described when the maximum ground motion values are given for the three components of ground motion, and the damping is known. When only the maximum ground acceleration is given, the values used for maximum ground velocity and displacement are taken as proportional to those in the figure, or as scaled by the same scale factor relative to the maximum ground acceleration compared with 1 g.

The amplification factors given in Table 2 and shown in Fig. 8 are still under study, but it is not expected that major revisions in them will be required.

#### Design Spectrum - Inelastic

To use the design spectrum to approximate inelastic behavior, the following suggestions are made. In the amplified displacement region of the spectra, the left-hand side, and in the amplified velocity region, at the top, the spectrum remains unchanged for total displacement, and is divided by the ductility factor to obtain yield displacement or acceleration. The upper right-hand portion sloping down at 45°, or the amplified acceleration region of the spectrum, is relocated for an elasto-plastic resistance curve, or for any other resistance curve for actual structural materials, by choosing



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Remark of Cuitical	Amplification Factor For			
Damping	Displacement	Velocity	Acceleration	
0	2.5	4.0	6.4	
0.5	2.2	3.6	5.8	
1	2.0	3.2	5.2	
2	1.8	2.8	4.3	
5	<b>1.4</b>	1.9	2.6	
7	1.2	1.5	1.9	
10	1.1	1.3	1.5	
20	1.0	1.1	1.2	

# RELATIVE VALUES OF SPECTRUM AMPLIFICATION FACTORS

Table 2

it at a level which corresponds to the same energy absorption for the elastoplastic curve as for an elastic curve shown for the same period of vibration. The extreme right-hand portion of the spectrum, where the response is governed by the maximum ground acceleration, remains at the same acceleration level as for the elastic case, and therefore at a corresponding increased total displacement level. The frequencies at the corners are kept at the same values as in the elastic spectrum. The acceleration transition region of the response spectrum is now drawn also as a straight line transition from the newly located amplified acceleration line and the ground acceleration line, using the same frequency points of intersection as in the elastic response spectrum.

In all cases the "inelastic maximum acceleration" spectrum and the "inelastic maximum displacement" spectrum differ by the factor  $\mu$  at the same frequencies. The design spectrum so obtained is shown in Fig. 9.

An earlier procedure for the definition of inelastic response spectra for design was presented in Reference [2]. In that presentation, the displacement bound, the velocity bound, and the acceleration bound were determined, respectively, by keeping the displacement constant, the energy constant, and the force in the spring constant, and drawing the corresponding maximum response displacement limits.

The revised procedure presented in this report is shown in Fig. 9 for 2% damping, for an elasto-plastic system with a ductility factor of 5. Both the maximum displacement and maximum acceleration bounds are shown, for comparison with the elastic response spectrum.

The solid line DVAA shows the elastic response spectrum. The heavy circles at the intersections of the various branches show the frequencies which remain constant in the construction of the inelastic design spectrum.

The dashed line D'V'A'A<sub>0</sub> shows the inelastic acceleration, and the lines DVA"A"<sub>0</sub> shows the inelastic displacement. These two differ by a constant factor  $\mu = 5$  for the construction shown, but A and A' differ by the factor  $\sqrt{2\mu - 1} = 3$ , since this is the factor that corresponds to constant energy, as indicated in Reference [2].

Of course, the elasto-plastic or other inelastic response spectra can be used only as an approximation for multi-degree-of-freedom systems.

In the development of a design spectrum one may choose to use an "effective" value of maximum ground acceleration rather than an actual value, particularly in cases where the higher spikes of acceleration are associated with very short durations and correspond to velocity changes much smaller than the maximum ground velocity, or where the duration of the earthquake motion is extremely short and the influence on failure or inelastic behavior is thereby lessened.

#### Vertical and Horizontal Excitation

Since the ground moves in all three directions in an earthquake, and even tilts and rotates, consideration of the combined effects of all these motions must be included in the design of important structures. When the responses in the various directions may be considered to be uncoupled, then consideration can be given separately to the various components of base motion, and individual response spectra can be determined for each component or direction of transient base displacement. Calculations have been made for the elastic response spectra in all directions for a number of earthquakes. The complete results for the three components of motion for these are not yet available, but the trends are summarized below.



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There are several interesting features of the response spectra. For example, the frequencies at which spikes and valleys occur are generally not the same for the different directions of any earthquake nor for the same directions at the same site for different earthquakes. The responses for the two horizontal directions show cross-overs and significant differences in some ranges of frequency. The vertical response is often equal to or greater than the maximum horizontal response in the high frequency region, but is somewhat to a great deal less in the intermediate and low frequency regions.

It is suggested that until further information becomes available the following design criteria be used:

- (a) The design spectrum for vertical response be considered equal to that for horizontal response for frequencies in the amplified acceleration range or higher frequencies. In other words, the acceleration bounds are the same for both horizontal and vertical response.
- (b) The design spectrum for vertical response be considered equal to two-thirds that for horizontal response for frequencies in the amplified velocity or displacement ranges.

## Combined Effects of Earthquake Motions

Since the responses for motions in the various directions (horizontal and vertical) may not occur at the same time, it is considered reasonable to combine the effects of the several components of motion in a probabilistic manner, by taking the maximum stress, deflection, or other specific response as the square root of the sums of the squares of the corresponding responses to the individual components of motion.

<sup>°</sup>The effects of transient tipping, tilting, and rotation of the ground during an earthquake have not been studied extensively. An elementary treatment of some aspects of these movements has been given in Section 7.7 of Reference [3], and the effects of rotation of the ground about a vertical axis on the accidental torsion in symmetrical buildings, for example, is given in Section 15.6 of the same reference.

When the responses of the structure or component are coupled, the analysis becomes much more complex and a three-dimensional (or at least twodimensional) response analysis must be considered. However, data regarding the simultaneous input motions must be used in such an analysis, and little guidance is available on this topic.

The motions due to an earthquake occur in both horizontal and vertical directions in a complex manner. It is necessary to consider the interactions between the responses in the various directions, and especially important to consider the interaction between the vertical and the maximum horizontal response. Vertical loads, and eccentricities of the vertical loads caused by horizontal displacements, must often be taken into account with especially heavy structures that carry large masses at or near the points which may deflect a great deal. Some of the resisting capacity for horizontal motions may be used up by the secondary effects of the eccentricities of the gravity loads.

Quite often, the vertical motions may produce vertical stresses in the structure or element that exceed by a large amount those stresses due to the inertial forces corresponding to the vertical acceleration multiplied by the mass of the element. This is true when the frequencies of vibration in the vertical direction of the element or component are in the range where major amplification of response can occur.

#### Special Considerations and Quality Control

A number of points are often overlooked in the design of structures or components to resist dynamic motions. A summary of some of the more important factors, but by no means a complete listing of all of them, is contained herein.

One of the factors that is commonly overlooked is the matter of relative motions between the parts or elements of a system having supports at different points, because the support motions may not occur simultaneously. Hence, there may be transient relative motions which produce strains in the structure, in addition to the strains produced by the dynamic effects of the overall motion. This is especially important in piping, electric wiring, or other elements connecting parts of a facility.

Finally, there are a group of items which do not lend themselves readily to analytical consideration. These concern the details and material properties of the element or component, and the inspection and control of quality in the construction procedure. The details of connections of the structure to its support or foundations, as well as the various elements or items within the structure or component, are of major importance. Failures often occur at the connections and joints because of inadequacy of these to carry the forces to which they are subjected under dynamic conditions. Inadequacy in properties of the materials can often be encountered, leading to brittle fracture where sufficient energy cannot be absorbed even though such energy absorption may have been counted on in the design.

In order to insure that the intent of the designer is achieved, control of construction procedures and appropriate inspection practices are necessary. It is important that the practical aspects of seismic design be emphasized and that both designers and constructors be fully aware of their importance.

#### V. Desirable Features of Design Codes

### Relation Between Analysis and Design

When the configuration of a structure is fixed by architectural or other requirements, the designer has a restricted choice in the development of the strength and ductility required to insure adequate seismic behavior. It is not always possible to say that some design layouts are better than others for dynamic resistance, although it is fairly clear that different choices of framing can lead to vastly different requirements of strength and ductility. For example, a framed structure is generally less stiff and usually lower in frequency than a shear wall structure with nearly solid walls providing lateral resistance. Hence the design forces may be smaller for the framed structure than for the shear wall structure, although the required ductility may be larger. Methods of design for the dynamic loadings arising from earthquakes are in general simpler and better understood for structures for which there is a great deal of experience. However, unless methods are developed and specifications are devised to take account of new structural types or of new imaginative architectural designs, such designs will be placed at a disadvantage relative to more standard designs because of the necessity for providing greater margins of safety for those designs for which experience is unavailable.

The methods of analysis, and also the details of the design specifications, have implications on the cost and the performance capability of the design. If the specifications are unduly conservative the design will not only be unduly conservative, but may also be forced into a type that is stronger and less ductile than is desirable. It is difficult to avoid differences in the degree of conservatism among different types of structures, and in some cases it is undesirable to do so. Some materials by their nature, including their variability or lack of adequate control of properties, may require a greater factor of safety than other materials the properties of which are more accurately determinable and controllable. The margin between incipient failure and complete collapse may differ for different materials and may therefore involve a difference in the factor of safety required in the design.

#### Basic Function of Design Codes

The designer, as well as anyone else who has a responsibility for the final structure, has to have some general method of knowing that gross errors have been avoided, and must have some basis of comparison to insure that the design is adequate in an overall sense. It is the purpose of building codes and specifications to perform these functions. However, it is not yet established that building codes can do this kind of job without introducing constraints and controls that may be a severe handicap on the development of new design concepts and procedures. Where building codes are used to insure, by rule-of-thumb methods, that a design is adequate, they embody the result of experience and judgment and must therefore deal implicitly, if not explicitly, with particular structural types and configurations.

The most desirable type of design code or specification is one which puts the least restrictions on the initiative, imagination and innovation of the designer. Such a code might involve only criteria for: (1) the loading or environment; and (2) the level of response, the stresses and deformation, or the performance of the structure under the specified loading or environmental conditions. Such an approach need not, and preferably should not, indicate how the designer is to reach his objective, provided he can show that he has achieved a structural capability to resist the specified environmental conditions. This approach is generally the one that is now used for the design of nuclear reactor power stations. Experience over the past several years in approaching seismic design criteria in this way has indicated a number of problems, but has also been reasonably successful in avoiding constraints due solely to the specifications themselves, although there have been constraints based on the environmental conditions and the stress and deformation levels allowed.

#### Seismic Response Criteria

The permissible level of response of a structure must, of course, be associated with the loading criteria. One cannot be specified independently of the other. This implies, for example, that different response criteria are to be associated with the probable earthquake or the historical earthquake from those used for the maximum credible or extreme earthquake. Moreover, for either of these, the response criteria should properly be a function of the type of structure, the relative cost of repairs for minor damage, and the hazard in terms of possible loss of life should the structure or any of its elements fail. Hence, the response criteria could be greatly different for individual homes than for multistory buildings housing hundreds or even thousands of people, and certainly different even from these for high dams above large centers of population or for nuclear reactor power stations.

It appears reasonable to establish such criteria in terms of the consequences of failure, and in relative terms associated with yield points or buckling loads of similar dynamic limit loads for the particular material or structural elements used. The aim of the criteria should be consistent with the basic seismic design philosophy stated earlier. Appropriate performance criteria may well be stated most rationally in terms of probabilities of failure or collapse associated with various levels of the probability of the hazard considered.

## Performance Criteria

It is essential that the response levels or maximum stresses and deformations be limited, for structures, components, and details such as joints and connections, in order to insure adequate strength and ductility of a structure as well as of its various component parts. However, it is desirable, in the development of the basis for a performance criterion, that the designer's approach not be too greatly constrained. For example, it may be unwise to prescribe limits for both strength and ductility in such a way that the balance between the two cannot be adjusted to take account of new material properties or new structural types as they are developed. A tradeoff between ductility and strength should be available in the methods that are permitted, so as to achieve economy without the sacrifice of safety. But whether one is interested in achieving strength or ductility, or both, the materials have to be used in an appropriate fashion, and adequate methods of inspection and control of construction are needed to insure that their use is proper.

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#### Methods of Analysis

A variety of methods of analysis are now available, ranging from simple upper-bound static coefficient methods to modal response combinations, including time history analyses either in the elastic or inelastic range, and extending to probabilistic methods or methods involving consideration of random vibrations. It should be possible to use any of these that are sufficiently justified by either general acceptance or by demonstrated mathematical and physical validity, with requiring that any one particular method be used. Of course, it is desirable always to allow the use of simple methods that are adequately conservative. Properly stated criteria, used with appropriate methods of approximate analysis and design, may make it unnecessary in many cases to perform detailed and costly analyses, particularly in those instances where the simpler approximate methods insure adequate margins of safety.

To push these concepts to the limit involves generally the idea of approximate methods that give reasonably accurate results or, at least, results that are consistent with those obtained from more precise analyses. Depending on the degree and extent of the approximation, it may be necessary, from the point of view of achieving a reasonable degree of precision, to have special modifications of a general procedure for various unusual structural classifications. Methods may be used that do not require knowledge of the period of vibration of the structure, for example, or the methods may involve an approximate determination of the natural period. Approximate damping factor determinations may be involved as well.

For the complete development of this type of approach it may be desirable to explore the possibility of a hierarchy of methods ranging from the crudest approximation, for very simple structures and structural elements, to more accurate approximate methods, for structures of intermediate complexity, and to relatively precise and accurate calculations, for extremely complex structures.

## Special Structures

Although many of the problems associated with the design of special structures such as nuclear reactors, high dams, schools and hospitals, are similar to those involved in other more ordinary types of structures, there are some implications of failure of these special structures that require special consideration in selecting margins of safety and the development of design procedures and criteria governing them.

Many structures or parts of structures and many items of equipment can

be severely damaged without any implication of loss of life or even of major property damage in an earthquake. For such items and structures it is unnecessary and certainly uneconomical to provide great margins of safety for unlikely earthquakes. The margin of safety of the provision made for an earthquake of a reasonable degree of probability of occurrence within the lifetime of a structure need only be great enough to offset the cost of repairs or reconstruction.

However, structures whose loss of function might cause hazard to life, or structures which are important to prevent damage to major services, have to be designed on an entirely different basis. For such structures, an earthquake even of relatively low probability of occurrence, but one that possibly could occur, should not cause collapse or damage of such a nature that endangers the health or life of large numbers of the population.

Hence, for such structures, much greater accuracy in procedures and •assumptions is required, and the type of design specification must be more carefully framed and more clearly stated to give an assuredly adequate margin of safety against failure even for unusual types of structure and framing.

The type of design specification used for major nuclear reactor power plants has emphasized loading or environmental criteria, and performance criteria in terms of stress and deformation levels of response. The experience that has been gained with criteria of these types indicates that benefits are possible for other types of special structures with similar kinds of design specifications. The advantages are in the encouragement of the designer to explore various types of structures, to consider the use of a variety of materials, and to look for economical ways of achieving the desired levels of safety and performance.

Detailed prescriptions of methods and procedures were necessary when the majority of practicing engineers had neither the sophistication nor the computational aids to take account of the more accurate methods of analysis and design that are now available. However, this situation has changed and is continuing to change at a rapid rate. With the increase in numbers of more highly trained engineers, and with a greater store of knowledge available, together with more efficient ways of using that knowledge which have become possible with the general availability of and accessibility to high speed digital computers, it appears that it is now possible to make a major change in our methods of specifying or codifying seismic design.

#### General Comments and Conclusions

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The field of earthquake engineering is relatively new, not much more than three decades old, and advances in knowledge are progressing at a rapid rate, not only because of a greater emphasis on analytical and experimental work in the laboratory, but also because of the availability of more definitive information on earthquake motions, the accumulation of strong-motion records, and recent accelerated expenditures on research. It is important that the discoveries from observations, and studies from the research laboratory and the analyst, find their way into practice as soon as possible. But this is difficult because engineers are traditionally unwilling to take chances on things that they have not proved out. Too little attention has been given to methods of demonstrating adequate performance capability for major structures and structural elements. Although this is not necessarily a part of our consideration in design specifications, it might well be desirable to look for ways of determining the capability of completed structures or for ways of proving the performance capability in the design stage by appropriate methods, so as to encourage the development of more economical designs and methods.

In order towinsure that the intent of the designer is achieved, control

of construction procedures and appropriate inspection practices are necessary. This point cannot be overemphasized. It is difficult to synthesize and distill the collective experience and judgment of the engineering profession into a set of rules, especially when they cannot be put into a mathematical formulation. This is a difficulty, however, not only with performance and environmental criteria but also with more standard types of design specifications of the current and past eras. Nevertheless, it is important that the practical aspects of seismic design be emphasized and that engineers and constructors be fully aware of their importance.

It is the intent of this discussion to focus attention on the aims and objectives of seismic design in such a way as to encourage the development of methods and practices suitable for structural design of the future; methods that will permit more freedom and latitude to the architectural and engineering innovator.

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# APPENDIX 6

VERTICAL GROUND MOTION IN EARTHQUAKES--ITS NATURE AND ITS EFFECTS ON THE RESPONSE OF BUILDINGS

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## APPENDIX 6

# VERTICAL GROUND MOTION IN EARTHQUAKES--ITS NATURE

# AND ITS EFFECTS ON THE RESPONSE OF BUILDINGS

by

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## Introduction

Vertical ground motions currently are given surprisingly little consideration in the earthquake resistant design of structures. This disregard is mainly based on the assumption that structures are almost "rigid" in the vertical direction, and hence the effects of vertical ground motions can be neglected. However, the few investigations carried out on this subject show that the vertical periods of many standard structures and important structural components are in the range of amplifications of response spectra developed from vertical acceleration components. The amplification of the vertical acceleration at the top of multistory steel structures may be in the order of four times the ground acceleration (references 45, 47). Such accelerations could contribute to the compression failure of columns, increase the ductility requirements in beams, reduce the factor of safety against overturning, or cause a critical condition in a prestressed beam by reducing the effective dead load on the beam (references 42, 46). More research on this subject is therefore urgently needed.

The following summary of information available on vertical

ground motions and its effects on the response of structures and structural components is based on the investigations reported in References 42 to 51. The summary is by no means complete, since it only includes work carried out in the United States and disregards research done in Japan and other countries.

## Nature of Vertical Ground Motion

A large number of records are available on vertical accelerations in past carthquakes from accelerographs recording horizontal and vertical components. All accelerogram records were digitized by and are available through the Earthquake Engineering Research Laboratory of the California Institute of Technology. Response spectra for single degree of freedom damped oscillators derived from these records are presented in references 46 and 48, and are also available through U.S. Coast and Geodetic Survey. A typical accelerogram for vertical accelerations is shown in Figure A6-1, and a comparison of horizontal vs. vertical spectral responses of SDF oscillators (reference 48) is presented in Figures A6-2 and A6-3.

The following general observations can be made from the data presented in the available references:

1. The peak vertical accelerations may not occur at exactly the same time as the peak horizontal accelerations; however, major vertical accelerations do occur within the same general time as the major horizontal ones. Thus the vertical and horizontal accelerations could be conservatively assumed to act simultaneously. (See Reference 46). Iyengar

and Shinozuka (reference 44) point out that there is no reason to believe that the horizontal and vertical components are uncorrelated, and they propose to represent the two components by a bivariate stationary Gaussian process with a cross spectrum between horizontal and vertical acceleration.

- An examination of the available response spectra indicates 2. that for most cases the response spectra for vertical ground motion are flatter (broader) than those for horizontal motions (reference 48). The spectra for vertical motion show significant amplification in the high frequency range (4 to 20 cps), and most of them also indicate an attenuation of the low period components (reference 46). It can also be seen that the response spectra for vertical motion approach the ground acceleration at higher frequencies than is the case for horizontal motion (reference 48). This phenomenon is due mainly to the presence of higher frequencies in vertical components of ground motion (reference 47). This will be reflected in the construction of design spectra, where the vertical ground acceleration is amplified over a larger frequency domain than the horizontal acceleration.
- 3. Vertical accelerations increase rapidly as the distance from the fault decreases, more so than horizontal accelerations. This is confirmed with experience from underground nuclear explosions, where vertical accelerations

close to the point of detonation in some cases exceed the horizontal accelerations (see reference 46).

 $ad/v^2$  Ratio

The nondimensional quantity  $ad/v^2$  can be taken as a basic index for monitoring the shape, and especially the breadth of the response spectra. The discussion of this parameter and others necessary to characterize the vertical ground motion is extracted from reference 48. A summary of the maximum values of the ground motion data studied in reference 48 is presented in Table A6-1.

Recognizing that the maximum ground displacements have to be obtained from the recorded accelerations through double integration and that these values are very sensitive to the base line adjustment procedure, it can be stated that the accelerations, the velocities, and the  $ad/v^2$  ratio are the most important parameters characterizing a ground motion. It also is established that the  $ad/v^2$  ratio is a function of the focal distance of the earthquake and the attenuation of motion in the ground. This ratio is therefore of foremost importance for the construction of design spectra and needs to be carefully studied.

The values of  $ad/v^2$  range from 1.84 to 30.58, but disregarding the El Centro earthquake of 5-18-40, most values fall in the range from about 5 to 15. In general it will be noted that the  $ad/v^2$  values are higher for vertical motion, as would be expected in part because the high frequency components in the vertical direction are more pronounced than in the horizontal direction.

The average values of  $ad/v^2$  for different site conditions are

summarized in Table A6-2. The average value for horizontal motions was about 5.6, and differs little from rock sites to alluvial sites. For vertical motions, the average value for alluvial sites was equal to 10.0 and that for rock sites was 13.0. Since only three sets of data were available for rock sites, more confidence can be placed in the values obtained for alluvial sites. Based on the available data, it was concluded that  $ad/v^2$  ratios of 6 and 10 may be representative for horizontal and vertical ground motions, respectively.

# Peak Horizontal vs. Vertical Accelerations

Newmark and Hall state in Reference 49 that the vertical components of motion may be somewhat less, or in some circumstances equal to or slightly greater than the horizontal motions, depending upon whether the associated fault motions in the earthquake are primarily horizontal (strike-slip motions) or primarily vertical (thrust fault or dip-slip motions). This general statement was confirmed by the study of particular earthquakes that show a range of ratios of vertical to horizontal peak acceleration from 0.27 for the Ferndale earthquake (12-21-54) to 1.29 for the Holiday Inn record of the San Fernando carthquake. It is clear that this ratio is a function of the fault motion, the distance from the fault, the ground motion intensity and the geological site conditions. Average values of these ratios for different site characteristics are presented in Table A6-3. The values range from 0.40 to 0.72, depending on the acceleration level included and the geological conditions. On the basis of these data, and realizing that only a few samples existed for the rock site, it

was decided in reference 48 to take the ground acceleration for a given site for the vertical spectrum to be equal to two-thirds of that for the horizontal motion.

Response Amplifications

Studies of the response amplification in various ranges of frequencies were carried out in reference 7. The input ground motion was normalized to the following values:

Maximum	ground	displacement	1.0	inch
Maximum	ground	velocity	10.0	in/sec
Maximum	ground	acceleration	1.0	σ

The results for mean response amplification for 5 percent critical damping is shown in Figure A6-4 for the horizontal and the vertical ground motion.

The following observations were made regarding the vertical response amplification:

- The amplification factors for accelerations are virtually constant for the range of frequencies from about 3 to 10 hertz, and then decrease fairly uniformly to intersect the ground motion accelerations at frequencies of about 50 hertz for all values of damping.
- 2. For the intermediate range of frequencies (0.3 to 3.0 hertz), a slight drop in the velocity amplification factor is evident as the frequency increases. However, the drop is only of the order of about 10 percent over the frequency range for which velocity amplification is valid, and it therefore appears reasonable to use a constant

amplification for the velocity range as well as for the acceleration and displacement range.

3. In the low frequency range of the spectrum the displacements are amplified by a constant factor for all values above the 0.05 hertz level.

The statistical values of response amplifications for horizontal and vertical motion obtained from a normal distribution curve for 0.5, 2, 5, and 10 percent of critical damping are presented in Table A6-4. It is recommended that these amplification factors for vertical ground motion be applied to the following frequency ranges:

Displacement amplification	0.1	to	0.3 hertz
Velocity amplification	0.3	to	3.0 hertz
Acceleration amplification	3.0	to	10.0 hertz

## Design Spectra for Vertical Motion

It has to be emphasized that it is difficult to generalize as to the shape of the vertical spectra versus the shape of the horizontal spectra. This shape will be a function of the distance to the fault, the site characteristics, the ground motion intensity, etc. In part such a generalization has been attempted in reference 48, where some of the parameters required in constructing the vertical design spectra are expressed as fractions of the parameters used for horizontal design spectra. The procedure utilized in reference 48 for the construction of design spectra for vertical ground motion can be briefly summarized as follows:

> 1. The peak vertical ground acceleration is taken to be twothirds of the peak horizontal acceleration, regardless

of site.

- 2. The ratio of v/a for the vertical motion to that of the horizontal motion is 0.90, regardless of site.
- 3. The  $ad/v^2$  for vertical motion is taken to be 10.0, regardless of site.
- 4. These three parameters define the ground motion bounds. The design spectra are obtained by multiplying these ground motion values by the amplification factors given in Table A6-4. The frequency ranges applicable for the amplification of acceleration, velocity, and displacement are listed previously. The faring frequency in the high frequency region was taken to be 50 hertz for all values of damping.

It should be noted that the above parameters were computed from a statistical study including only strong motion data, i.e., disregarding all traces that had accelerations less than 0.1g in the case of horizontal motion and 0.05g in the case of vertical motion.

The values of ground motion bounds of acceleration, velocity and displacement for horizontal and vertical ground motions are presented in Table A6-5. The values are normalized with respect to a horizontal ground acceleration of 1.0g. The displacement values were calculated on the basis of the a, v, and  $ad/v^2$  values, and were then rounded off to a representative number. The actual response spectra bounds, obtained through multiplication with the appropriate amplification factors, are tabulated in Table A6-6 for horizontal and vertical motion. A typical vertical response spectrum is shown in Figure A6-5.

# Effects of Vertical Ground Motion on the Response of Buildings

The types of structures and structural components that may experience significant effects from vertical ground motions are high rise buildings, cantilevered structures such as grandstand roofs, aircraft hangars and marquees, cable suspended structures, slabs, and long span elements, particularly of prestressed concrete (see references 46, 47).

Various opinions are expressed in the literature regarding the importance of the effects of vertical accelerations. Larson (reference 47) states that studies of the behavior of structures in the Anchorage, Caracas, and Santa Rose earthquakes disclosed many effects which could be ascribed to vertical components of seismic excitation. Jennings (reference 45), to the contrary, concluded from a damage study of the San Fernando carthquake: "There were no instances where it appeared to the writers that vertical accelerations had been major contributors to the damage sustained by building structures, and it is not recommended at this time that vertical accelerations be included in normal seismic design procedures for typical buildings. There are special structures, however, which could be more sensitive to vertical accelerations and vertical motions should be considered in such cases." Rosenblueth (reference 50) reports the appearance of vertical tensions during nearby earthquakes. These, as well as large compressions, also caused by vertical accelerations, can combine with the effects of overturning moments. He also states that we may have to expect appreciably permanent deformations in floor systems after several nearby strong

earthquakes.

Regardless of the wide range of opinions expressed in the literature, it is well established that vertical accelerations are greatly amplified from the ground floor to the top of multistory buildings. This can be seen from the records of the San Fernando earthquake presented in Table A6-7 (see reference 45), which show an amplification of vertical acceleration ranging from 1.4 to 4.5. This is also evident from analytical investigations that show that the vertical period of many typical structures lies in the range of acceleration amplification.

# Dynamic Properties of Structures in the Vertical Direction

Building structures can be modeled through a lumped massspring system, with each point mass representing the total weight at the floor level, and each spring representing the axial deformation of the columns between floors (see reference 46). The effects of interconnecting girders on the columns could be included, but is not considered to be significant. The vertical period of buildings depends on the height of the structure and on the level of stresses in the column. For multistory steel structures the vertical period can be estimated from Figure A6-6, taken from reference 46.

# Results of Analytical Investigations

A series of steel structures, ranging from 5 to 51 stories, was studied in reference 46. The response spectra for the Taft and Golden Gate Park earthquakes were used as input in the analysis.

Elastic behavior was assumed in the analysis. This is a reasonable approximation for studies of structures in the vertical direction because of the current design philosophy to avoid plastic hinges in the columns. The findings of this study are briefly summarized below.

- The vertical periods of steel structures lie in the range of acceleration amplification of the spectra developed for vertical motion.
- 2. The amplification of the vertical acceleration at the top of steel structures may be in the order of four times the ground acceleration. Similar results should be expected for buildings of other materials. This amplification could increase or decrease column dead loads by 20 percent or more.
- 3. Vertical accelerations may contribute to the overstress or compression failure of columns and may reduce the factor of safety against overturning.

A study of a ten story unbraced steel frame subjected to gravity loads and a combination of horizontal and vertical ground motion components is reported in reference 42. An inelastic dynamic analysis of this structure was carried out, using the Pacoima Dam and the Taft earthquake records as an input. Both records were normalized to a maximum vertical ground acceleration of 0.31g. For comparison, a second analysis was carried out with the structure subjected only to gravity loads and horizontal accelerations. The maximum vertical accelerations of the selected nodal points in the structure are shown in Figure A6-7, for the Pacoima Dam record. The following conclusions

were drawn from a study of the response of the structure that was designed for seismic loads specified in the Uniform Building Code and following the allowable stress design procedure.

- 1. The inclusion of vertical components of ground motion increases the ductility requirements in both the columns and girders of the upper stories. Vertical motion is particularly significant in causing inelastic action at the midspan of the girders. Inelastic action in the columns is increased by the amplification of the vertical motion in these members and by the amplified vertical response of the girders.
- 2. The relative importance of the vertical motions is dependent on the main characteristics of the complete time histories of both the horizontal and vertical components of the earthquake. The duration and frequency content as well as the maximum acceleration of the ground motion need to be considered in determining the effects of earthquakes on structures.
- 3. Ductility requirements at the critical regions of individual members cannot be evaluated with accuracy from just analyzing maximum lateral displacements and maximum relative story drifts.

Iyengar and Shinozuka (reference 44) used statistical models for the horizontal and vertical components of ground motion to study the effect of self-weight and vertical acceleration on the tip deflection, base bending moment, and base shear force of cantilever type

structures. As expected, the effects were of more significance in taller structures than in shorter ones, but in either case the differences caused by including self-weight and vertical acceleration seem to be considerable.

In conclusion, it has to be stated that no evaluation of the effects of vertical ground motion for structures older than steel structures and for important structural components could be found in the literature. Further research in this area seems to be urgently needed.

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Remarks	Instrument on the ground floor of a 2 story frame structure Ref. (8)	Instrument on the ground floor of a 2 story frame structure Ref. (8)	Instrument in the basement of a brick and stone building Ref. (8)	Instrument on the first floor of the public library, a 2 story structure Ref. (8)
Site description	40-80 ft of alluvium over 100 ft of sandstone over siltstone	40-80 ft of alluvium over 100 ft of sandstone over siltstone	100' sandstone (poorly consolidated) over 360 ft of siltstone over sandstone	500 ft of alluvium over cenozoic rock water table at 50 ft
ג <mark>פ</mark> ל ע2	<b>5.39</b> 16.99 14.74	4.15 2.61 4.42	17.61 3.86 13.54	9.26 3.46 7.45
Max1mum ground d1sp1. d, în	0.95 1.07 1.24	4.92 8.09 2.49	8.45 3.14 2.22	3.03 1.97 1.03
Max1mum ground vel. v, in/sec	ord IA 2) 2.86 1.73 1.02	cord IA 9) 9.79 14.10 3.13	rrd IA 8) 5.92 9.23 2.64	ord IA 18) 3.10 6.45 1.73
Maxîmum ground acc. a, g	, 2011 PST (Rec 0.120 0.123 0.032	4, 1156 PST (Re 0.209 0.166 0.045	1156 PST (Reco 0.189 0.271 0.110	, 2323 PST (Rec 0.076 0.189 0.056
Record description	Ferndale, 10-7-51 N 46 W S 44 W Vertical	Ferndale, 12-21-5 <sup>1</sup> N 46 W N 44 E Vertical	Eureka, 12-21-54, N 11 W N 79 E Vertical 7	Hollister, 4-8-61, S 01 W N 89 W Vertical

Maximum Ground Motions and Site Description Table A6-1. (reference 48)

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Rema rk s	Instrument on the first floor of a 2 story massive concrete, heavily reinforced structure	Instrument on the first floor of a 2 story massive concrete, heavily reinforced structure	Instrument in the basement of a 14 story RC building		Instrument in a small shack used to house electrical equipment
Site description	Alluvium to about 5000 ft	Alluvium to about 5000 ft	700' <u>+</u> of alluvium	700' ± of alluvium	Siliceous sandstone 1-2 miles from San Andreas Fault
<pre>% Record Maximum Maximum Maximum ed description ground acc. ground vel. ground displ. 2 a, g v, in/sec d, in v</pre>	El Centro, 2-9-56, 0633 PST (Record IA 11) NS 0.036 1.52 1.27 7.65 EW 0.055 3.11 2.48 5.45 Vertical 0.016 0.75 0.55 6.05	El Centro, 4-8-68, 1830 PST (Record IA 19) NS 0.142 10.49 3.68 1.84 EV 0.058 4.72 4.68 4.71 Vertical 0.036 1.16 1.36 14.06	Hollywood Storage Basement, 7-21-52, 0453 PDT (Record IA 6) NS 0.059 2.58 1.41 4.83 EW 0.046 3.74 2.73 3.47 Vertical , 0.023 1.12 0.85 6.02	Hollywood Storage PE Lot, <b>7-21-5</b> 2, 0453 PDT (Record IA 7) NS 0.063 2.60 1.26 4.54 EW 0.043 4.11 2.89 2.84 Vertical 0.023 1.22 0.81 4.84	San Francisco Golden Gate Park, 3-22-57, 1144 PST (Record IA 15)         N 10 E       0.106       1.09       0.20       6.90         N 10 E       0.105       1.26       0.18       5.56         S 80 E       0.127       1.26       0.18       5.56         Vertical       0.051       0.41       0.16       18.76

Table A6-1. (continued)
	Remarks	Small building houses the instrument	Small building houses the instrument	Instrument on the first floor of a 7 story RC building structure	Instrument in the basement of a 12 story RC building structure	Instrument on the first floor of a 2 story massive concrete, heavily reinforced structure
i						
	Site description	Highly jointed diorite gneiss 4 km from surface faulting	Sandstone	Alluvium 8 km from surface faulting	Alluvium water table at 55'	Alluvium to about 5000 ft
	Maxfmum ground displ. <sub>i</sub> ad d, in <sup>,</sup> v <sup>2</sup>	5.11 4.88 23.18 5.82 13.75 7.17	2.05 5.82 3.22 3.14 1.42 13.13	(Record IC 048) 8.70 5.90 6.37 3.60 6.37 2.66	1600 PST (Record IH 115) 7.07 5.32 4.48 4.29 3.09 5.67	4.74 3.35 6.58 4.13 4.41 <b>3</b> 0.58
	Maximum ground vel. v, in/sec	T (Record IC 041) 22.49 43.70 23.06	ecord ID 056) 6.73 10.55 2.75	-9-71, 0600 PST ( 12.13 9.68 12.81	ement), 2-9-71, C 10.96 7.88 4.77	(Record IA 1) 13.88 11.72 3.95
	Maximum ground acc. a, g	-9-71, 0600 PS 1.250 1.241 0.718	1, 0600 PST (R 0.333 0.281 0.181	irst Floor), 2 0.258 0.137 ** 0.177	Boulevard (Bas 0.234 0.154 0.108	8-40, 2037 PST 0.352 0.223 0.280
	, Record description	Pacoima Dam, 2 S 74 W S 16 E Vertial	Castaic, 2-9-7 N 21 E N 69 W Vertical	Holiday Inn (F NS EW Vertical	15250 Ventura N 11 E N 79 W Vertical	El Centro, 5-1 NS EW Vertical

Table A6-1. (continued)

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Site	Direction	No. of Records	ad/v <sup>2</sup>
alluvium & rock	horizontal	28	5.6
alluvium	horizontal	22	5.7
rock	horizontal	6	5.4
alluvium & rock, a>0.1g	horizontal	20	5.7
alluvium, a>0.1g	horizontal	14	5.9
rock, a>0.1g (same as above)	horizontal	6	5.4
alluvium, a<0.1g	horizontal	8	5.3
	•		
alluvium & rock	vertical	14	10.7
alluvium & rock	vertical	13	9.1
alluvium	vertical		10.0
alluvium*	vertical	10	7.9
rock	vertical	3	13.0
			· · ·
alluvium & rock, a>0.05g	vertical	8	12.4
alluvium, a>0.05g	vertical	5	12.0
alluvium, a>0.05g*	vertical	4	7.3
rock, a>0.05g (same as above)	vertical	3	13.0
alluvium, a<0.05g	vertical	6	8.4
	, C	κ.,	· ·

\* Discarding the extreme value, El Centro, 5-18-40, 2037 PST,  $ad/v^2 = 30.58$ 

Summary of Average  $ad/v^2$  Values Table A6-2. (reference 48)

<u>a - vertical</u> - horizontal	Average <u>a -</u> a - h	No. of records	Site
0.53	0.53	28	alluvium & rock
0.53	0.53	. 22	alluvium
0.54	0.54	6	rock
0.65	0.65	15	alluvium & rock, a <sub>h</sub> >0.lg, a <sub>v</sub> >0.05g
0.72	0.72	9	alluvium, a <sub>h</sub> >0.1g, a <sub>v</sub> >0.05g
0.40	0.40	13	alluvium & rock, a <sub>h</sub> <0.1g, a <sub>v</sub> <0.05g
			alluvium, a <sub>b</sub> <0.1g, a <sub>y</sub> <0.05g
0.40	0.40	13	(same as above)
0	O	13	alluvium, a <0.1g, a <0.05g v (same as above)

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Summary of Vertical to Horizontal Acceleration Ratios Table A6-3. (reference 48)

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	D	A1	1 Records	(28)	Records w	ith a > (	D.1g (20)
rercentile	Vamping	Ď	V	Α	D	v	A
	0.5	1.98	2.86	4.00	1.97	2.58	3.67
PA	2.0	1.69	2.23	2.91	1.68	2.06	2.76
50	5.0	1.39	1.74	2.20	1.40	1.65	2.11
	10.0	1.13	1.38	1.72	1.15	1.34	1.65
ggaaga ay ah	0.5	2.66	3.81	5.02	2.66	3.41	4.65
	2.0	2.23	2.89	3.52	2.24	2.68	3.36
15	5.0	1.80	2.19	2.59	1.83	2.10	2.48
•	10.0	1.43	1.69	1.97	1.47	1.65	1.89
and a second	0.5	3.27	4.67	5.95	3.28	4.16	5.53
00	2.0	2.72	3.48	4.06	2.74	3.23	3.90
90	5.0	2.17	2.60	2.93	2.21	2.51	2.82
	10.0	1.71	1.98	2.20	1.75	1.94	2.11
Manafala (Arang) - gal da Din za ang na katang ng na kang n	0.5	3.64	5.19	6.50	3.65	4.60	6.05
٥C	2.0	3.02	3.84	4.39	3.04	3.57	4.22
77	5.0	2.39	2.84	3.14	2.44	2.75	3.03
	i0.0	1.87	2.15	2.33	1.91	2.11	2.24
•			· •				

Statistical Value of Response Amplifications (Normal Distribution - Horizontal Components)

Table A6-4. (reference 48)

D		A11	Records (	(14)	Records	s with a >	0.05g (8)
Percentile	Damping	D	• • V	A	D	ν	A
	0.5	1.77	2.74	4.22	1.86	2.52	4.02
	2.0	1.57	2.10	2.86	1.65	1.97	2.80
50	5.0	1.33	1.56	2.08	1.40	1.51	2.05
	10.0	1.09	1.22	1.62	1.16	1.17	1.59
· · · · · · · · · · · · · · · · · · ·	0.5	2.33	3.67	5.47	2.48	3.39	5.46
	2.0	2.04	2.77	3.60	2.17	2.61	3.70
/5 •*	5.0	1.70	2.06	2.52	1.81	1.97	2.57
4 <b>1</b>	10.0	1.38	1.55	1.91	1.47	1.49	1.92
<b></b>	0.5	2.83	4.51	6.59	3.04	4.17	6.76
	2.0	2.46	3.37	4.27	2.63	3.18	4.51
90	5.0	2.04	2.47	2.92	2.18	2.37	3.04
	10.0	1.63	1.84	2.17	1.75	1.78	2.22
	0.5	3.13	5.02	7.26	3-37	4.64	7.53
OC	2.0	2.71	3.73	4.67	2.91	3.52	4.99
カ	5.0	2.24	2.73	3.16	2.40	2.62	3.32
	10.0	1.79	2.01	2.32	1.92	1.95	2.40

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Statistical Values of Response Amplifications (Normal Distribution - Vertical Components)

Table A6-4. (continued) (Ref. 48)

\$ite .	Direction	Acceleration a, g	Velocity v, in/sec	Displacement d, in	ad/v2
alluvium	horizontal	1.0	48	36	6.04
rock	horizontal	1.0	28	12	5.92
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alluvium	vertical	2/3	29	. 33	10.10
rock	vertical	2/3	17	11	9.80

## Horizontal and Vertical Design Ground Motions Table A6-5. (reference 48)

	١								•		•	
Percentile	•	Damplng percent	D Amr	olificati V	on A	Faring: frequency her:z	Spectrum D in	bounds V in/sec	(alluvium) A g	Spect r D in	'um bound: V .1n/sec	s (rock) A g
		0.5	1.97	2.58	3.67	40	12	124	3.67.	24	72	3.67
	•	2.0	1.68	2.06	2.76	30	60	66	2.76	20	53	2.76
04		5.0	1.40	1.66	2.11	20	20	80	2.11	17	46	2.11
		10.0	1.15	1.34	1.65	20	41	64	1.65	14	38	1.65
\$ 		0.5	2.66	3.41	4.65	0†	96	164	4.65	32	95	4.65
1		2.0	2.24	2.68	3.36	30	81	129	3.36	27	75	3.36
Ŕ		5.0	1.83	2.10	2.48	20	66	101	2.48	22	59	2.48
•	ťť	10.0	1.47	1.66	1.89	20	53	80	1.89	8	46	1.89
		0.5	3.28	4.16	5.53	04	118	200	5.53	39	116	5.53
4		2.0	2.74	3.23	3.90	30	66	155	3.90	33	6	3.90
• 06		.5.0	2.21	2.51	2.82	20	80	120	2.82	27	. 70	2.82
	<b>.</b>	10.0	1.75	1.94	2.1	20	63	6	2.11	21	54	2.11
	•	Ground m alluvl	lotion um	а,	50 60	v, in/sec 48	d, in 36				· ·	
-		rock			0	28	, <mark>1</mark> 2					
				j.Li	Jorizontal Tahla	L Design Spect A6-6 (refor	ra Bounds					
					シーンサー	10-04 VICTOR	כווכע לכו					

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Percentile	Dampîng percent	DAmp	olificati V	on A	Faring frequency hertz	Spectrum D 1n	bounds V in/sec	(alluvlum) A g	Spectr D in	'um bound V in/sec	ls (rock) A g
	0.5	1.86	2.52	4.02	50	[9]	73	2.68	20	43	2.68
ć	2.0	1 .65	1.97	2 °80	50	54	57	1.87	18	33	1.87
5	5.0	1.40	1.51	2.05	20	46	717	1.37.	15	26	1.37
	10.0	1.16	1.17	1.59	20	38	34	1.06	5	20	1.06
not contract of the second	0.5	2.48	3.39	5.45	50	82	98	3.64	27	58	3.64
il. F	2.0	2.17	2.61	3.70	50	72	76	2.47	24	<b>1</b> 17	2.47
<b>€</b> ¢	5.0	1.81	1.97	2.57	20	é Ó	57	1.71	20	33	1.71
	10.0	1.47	1.49	1.92	20	6†	43	1.28	16	25	1.28
	0.5	3.04	4.17	6.76	50	100	121	4.51	33	71	4.51
Ş	2.0	2.63	3.18	4.51	20	87	32	3.01	29	54	3.01
25	5.0	2.18	2.37	3.04	50	72	69	2.03	24	07	2.03
	10.0	1.75	1.78	2.22	50	58	52	1.48	6	30	1.48
n Country of Management and Andreas and	Ground n	notion	a, <u>c</u>	6	v, in/sec	d, in				-	
	a l luvi rock	m	2/2	<b>~</b> ~~	29 17	33			•		
				. *			•	-			
				Vert	ical Design S <sub>l</sub>	pectra Bound	ß				
				Table	A6-6. (cont:	inued) (Ref.	. 48)				

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BUILDINGS	
YPICAL PEAK ACCELERATIONS IN MULTI-STORY	Accelerations in Fractions of o
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ν.ν	Building	Date	No.	Ground. Ba	sement or	lst Floor	Interm	ediate	Level	Roof o	r Top F	loor
	0		Stories	1	٢	2	Ч	ħ	^	Ч	F	>
Reinf	orced Concrete											
T	15107 Vanowen	1970	2	0.11	0.11	0.11	0.24	0.23	0.20	0.36	0.40	0.17
· ~	82.44 Orion	1967	2	0.25	0.15	0.19	0.21	0.25	0.24	0.40	0.34	0.26
1 00	1640 Marengo	1966	7	0.14	0,15	<b>0.</b> 09	0.15	0.27	0.13	0.25	0.44	0.15
4	4680 Wilshire	1967	7	0.14	0.10	0.09	0.23	0.19	0.12	0.24	0.30	0.15
	646 Olive*	1967	7	0.22	0.26	<b>0.</b> 09	0.25	0.25	0.13	0.39	0.48	0.26
9	4687 Sunset	1966	80	0.20	0.18	0,15.	0.31	0.24	0.15	0.45	0.47	0, 22
5	2011 Zonal	1966	6	0.08	0.08	0.07	0.20	0.17	0.10	0.23	0.21	0.11
· 00	433 Oakhurst	1970	10	0, 09	0, 06	0.03	0.14	0.14	0.04	0.27	0.27	0.10
6	120 Robertson	1966	10	0, 10	0.10	0.04	0.18	0.19	0.10	0,33	0.28	0.12
10	420 Roxbury	1969	10	0.21	0.17	0.05	0.21	0.24	0.11	0.30	0.22	0.14
	7080 Hollywood	1966	11	0.11	0.11.	0.08	0.21	0, 13	0.16	0.21	0.13	0.22
12	3710 Wilshire*	1966	11	0.17	0.16	0.09	0.29	0, 17	0.11	0.22	0.38	0°17
13	3470 Wilshire	1966	12	0.15	0.12	0.06	0.21	0.22	0.11	0.22	0.25	0, 15
14	8639 Lincoln	1969	12	0,04	0.03	0.03	0.09	0.08	0.09	0.13	0.13	0,06
1.5	15250 Ventura	1971	12	0.17	0.24	0.11	0.25	0.28	0.16	0.18	0.30	0.18
16	2500 Wilshire	1969	13	0.11	0.13	0.06	0.14	0, 16	0.07	0.20	0.20	0.15
17	6200 Wilshire	1970	16	0.12	0,13	0.03	0.29	0.17	0.05	0, 28	0.26	0.08
18	4000 Chapman	1970	19	0.02	0.02	0.02	0.05	0.04	0.03	0.06	0.06	0.04
Steel	Frame			-								
-	5260 Century*	1968	7	0.06	0.05	0.02	0.05	0.07	0,04	0.07	0.05	0.09
- 2	3407 Sixth	1966	80	0.17	0.20	0.06	0.22	0.22	0.10	0.28	0.22	0.27
ŝ	1150 Hill	1970	10	0,12	0.09	0.05	0.10	0.12	0.09	0.12	0, 12	0.15
4	900 Fremont	1971	12	0.14	0.14	0.07	0.14	0.15	0.12	0.18	0, 15	0.17.
Ś	L.A. Water				·					ţ		
	and Power	1969	15	0.15	0.20	0.08	0.19	0.14	0.09	0.17	0,10	0,10
9	250 First	1967	15	0,10	0.14	0, 06	0.21	0.17	0° 04	0.11	V. 10	0. 60
2	1800 Century				•		, , ,	u c	71 0	0 0 0	9 C U	23 0
	Park East	1970	16	0,08	0.11	0,08	0, 23	0, 20	0.10	0, 40	0.20	0°00
8	800 First	1969	33	0.09	0.14	0.00		0.17	0.16		1	1

Shear Wall

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Table A6-7. (reference 45)

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Fig. A6-7. Maximum Vertical Accelerations for Pacoima Dam Record (ref. 42)

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