N69-30352

EARTH RESOURCES PROGRAM GROUND TRUTH SESSION

Test and Operations Office Manned Spacecraft Center Houston, Texas

November 1967

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RATIONAL ARCHAUTICS AND SPACE ADMINISTRATION

EARTH RESOURCES PROGRAM

PROCEEDINGS OF GROUND TRUTH SUSSION NOVEMBER 1967

PREPARED BY TEST AND OPERATIONS OFFICE SCIENCE AND APPLICATIONS DIMENTRATE

MANNED SPACECRAFT CENTER

HOUSTON; TEXAS



EARTH RESOURCES FROGRAM

GROUND TRUTH

INTERIM REPORT

PROCEEDINGS OF GROUND TRUTH SESSION

NOVEMBER 1967

INTRODUCTION

The importance of ground truth to the success of the Earth Resources Aircraft Program (ERAP) is recognized by user agencies, instrument teams, and MASA. It is also recognized that documentation is needed of the role of ground truth in future orbital space missions, as well as present capabilities and future requirements in the ERAP.

The initial ground truth working session was held at the Manned Spacecraft Center (MSC) on November 27, 1967, to discuss and document these capabilities and requirements. The ground truth activities discussed in the session primarily included the following topics:

- 1. Existing ground truth capabilities.
- 2. Measurements required and measurements currently being made.
- 3. Equipment now being used and future requirements.
- 4. Ground sites now supported and type of support.
- 5. Recommendations relative to the ERAP concerning ground truth.

6. Extrapolations of the above topics for short terms (10-15 days) and long terms (1-2 years) orbital missions.

This report is a compilation of papers presented at the session by various participants in the ERAP. This document is not intended to represent total ground trutb capabilities and requirements, but should be used for information and as an aid in planning for development of ground truth capabilities in the future.

Table of Contents

<u>96 61 98</u>		Fane	
2.	Sorth Resources Ground Truth for Agriculture, by Ψ . I. Myers, USDA	2-62	
II.	Geologic Ground Truth for Earth Resources Survey Programs, by J. Lints, J. Quade, and P. Chapman, University of Nevada	43-80	
III:	Presentation by Jules Friedman, USOS (Test not available for printing in final document)		
₩.	Ground Truth Massurements to Support Eader Studies, by D. S. Simonett, University of Eanses	81-91	
₹.	Oceanographic Ground Truth Bequirements, Spacecraft Oceanography Project, U.S. Naval Oceanographic Office, presented by H. Yotko	92-120	
VI.	Ground Truth Working Session, by R.J.P. Lyon, Stanford University	121-142	
VII.	Ground Truth Requirements for Remote Sensing of Geesmographic Features, by Don Malsh, Zuzas A6M	143-168	
m.	Preliminary Report of Mission 60, Sea State at Argentia, Newfoundland, by W. J. Pierson, New York University	169-175	

A

EARTH RESOURCES GROUND TRUTH FOR ACRICULTURE

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Victor I. Myers, UEDA *

Introduction

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Agricultural ground truth can be defined as data concerning plants, soils, water, atmosphere, and energy balance, gathered for scientific interpretation of phenomena registered on a remote sensing datector or camera.

In celecting agricultural remote sensing sites or flight lines, the following criteria should be given consideration:

1. Sites should have representative soil and plant conditions.

2. Flight lines should be in streight lines insofar as possible to facilitate flying.

3. The same flight lines should be covered each time to provide repetitive sessonal and annual covarage of specific conditions.

4. In selecting sites, advantage should be taken of controlled experiments already being conducted for other purposes, whenever possible, such as statistically designed plot studies.

5. Calibration panels and instrumentation must be available slong the

flight lines.

The following report on ground truth for agriculture also includes brief material on techniques and instrumentation for forestry. Regular organized ground truth collection programs are underway by the U.S. Forest Service, the University of California, Furdue University, as well as U.S.D.A., Agricultural Research Service, Weslaco, Tazas.

Figure 1 shows flight lines for the Agricultural Earth Resources Site 32 in the Lower Rio Grande Valley of Texas. The flight lines, selected according to the above criteria, cover ground truth site conditions described in Exhibit A.

Minimum Secie Equipment Required for a Fundamental Apricultural Test Site

Field fundemental and applied studies

Thermal hand-held radiometers - 2 required (ground truth temperatures) Field spectrometer-short wave (0.3 to 2.5 microns) Field spectrometer-long wave (2.5 to 14.0 mierons)

* Material contributed by Robert Hellar, U.S.D.A. Forest Service, and Purdue University.

Earth Resources Ground Truth

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for Agriculture

By V. I. Myers, USDA

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Seven-track magnetic taps recordsr for each spectromater - 2 required Storage oscillosope for instantaneous recording and viswing of spectra from field spectrometers - 2 required

Mobile instrumentation pickup track with compar (for spectrometer instrumentation recording complex)

Infrared camera for detailed field thermal studies involving crop

Infrared reference for IR calibration

Automatic data recording system (punch tape) for mateorological data - 20 channels

Mobile instrumentation trailer for data recording system and suziliary equipment

Mateorological and micromateorological instrumentation Encorders - dual pen millivolt Camaras

Fundamental laboratory studies

Microscope Spectrophotometer

Photo Laboratory and densitoestry

Photographic film processing equipment for at least 70 mm Combination isodensitracer and microdensitometer Densichrons for optical density messurements

Communications

UHF Radio System (necessary for communications between aircraft and ground parties and bateaen ground parties during remote sensing overflights)

Miscellaneous laboratory and field equipment

Crop and Soil Identification

The USDA remote sensing program at Wealsoo is concerned primarily with recording, measuring, and identifying the energy in wavelengths between .3 and 14 microms reflected or emitted from the earth's surface, and the microwave frequencies. A working hypothesis is that each crop and soil condition reflects or emits energy typical of the specific condition. This problem is to determine which wavelengths are the most sensitive to changes in crop and soil conditions, to discover empose sensitive to changes lengths, and to develop methods of recording, measuring, and identifying the specific crop or soil condition represented by a specific reflected spectrum.

The attached Exhibit A describes the objectives and precodures for collecting ground truth and determining characteristic crop and well signatures at MASA Earth Resources Site 32.

Data Collection

84

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General.

As is evident from the work plan, extensive ground truth data are collected in connection with MASA overflights. Figure 2 shows one of a number of ground parties making crop and soil measurements at the time of an overflight. Redios are considered essential during these overflights for maintaining mobility and communications.

Figure 3 shows a sample data sheet of the type filled in by ground parties.

Soil Moisture Massurement on Represend Site

Available soil moisture in the root some affects the reflectance pattern from agricultural crops and rangeland vegetation. Also, surface soil moisture influences the intensity of momochromatic light reflected from soils. Careful massurement of soil moisture is essential as an element of ground truth.

Figure 4 shows a technician measuring soil moisture with a F-19 Buckets Chicago neutron probe and pertable scales in an area of rangeland vegetation. This equipment requires semi-perm.cont installation of an aluminum access tube at each ground truth site.

Automatic Recording of Field Data

Automatic recording of data is accomplianed with the Howell Data Logger shown in Figure 5. The instrumant, a 20-channel logger, records sequentially on command every 3 seconds, 6 seconds, or 8 seconds. Each channel reading is summed for 10 readings and the average is punched out on tape at the end of a 10 value recording cycle. The range of input signals the equipment is capable of hendling extends from -2 to 18 mv.

Interpretation of Photographic and Scenner Transportancies

Interpretation of photographic and sesumer transparencies is made with manual densitometers and with estimatic equipment, the most important of which is the isodensitracer. The isodensitracer, shown in Figure 6, is a high-speed, direct reading isophotometer designed for the rapid presentation of two-dimensional photometer information. The instrument quickly and estomatically scans and measures the optical density of all points is a film transparency and plots the values as a quastitative, two-dimensional density may of the scanse d area.

* Trade nemes and company names used in this paper are for information only and do not constitute endorsement by the U.S. Department of Agriculture. The isodensitracer eliminates the tedious manual correlation of data from successive tracings. It can also be used as a microdensitometer to plot absolute optical density in graphical form. This equipment has recently been fitted with encoders which permit placing values of eptical density and X-Y position of resolution elements on paper punched tape. Digitized data can then be processed in a computer. Figure 16 is an isodensitracing of thermal imagery shown in Figure 15, taken at 1900 hours.

Field Spectrometer Data Collection

Reflectance and transmittance measurements from a laboratory spectrophotometer (see Figure 7) are valuable for controlled studies of plants and soils and frequently indicate the portion of the spectrum where anomalies can be expected to occur in remote sensing measurements. The absolute energy value of spectrophotometer curves is difficult or impossible to detarmine, however, and the spectral distribution of the source differs from that of solar energy. Field spectra, which have a solar energy source, are influenced by such factors as reflectance from multiple leaf layers, soil background radiance, and atmospheric absorption and scattering of certain wavelengths.

An Instrumentation Specialties Company (ISCO) Spectroradiometar, shown in Figure 8, is used for gathering field spectra. Other field instruments also have been used for this purpose. In Figure 9 a Perkin-Elmer SG4 Spectrometer is elevated over field plots on a Truco Aerial Lift. The spectroradiometer has a wavelength range of 450 to 1550 mu with bandwidths of 15 and 30 mu, respectively, in the visible and infrared. Sensitivity is from 0.3 to 1000 uw cm⁻²mu⁻¹ in eight ranges with accuracy of 7 to 10 percent. Two sensing heads, each having 180° field of view, are provided with the spectroradiometer. One is a diffusing screen mounted directly on the instrument case for measuring incoring radiation, and the other is a six-foot fiber optics probe which is directed toward selected areas of plants and soils for measuring radiance. The fiber optics proba has been modified to decrease the field of view from 180° to 10° so that specific areas can be isolated for radiance measurements. A recorderscanner is used in conjunction with the spectroradiometer which records spectral intensity versus wavelength in a continuous spectral distribution curve. It incorporates a 24-hour program timer which may be set to initiate a scanning cycle at any predstermined time during the day at intervals of fifteen minutes of longer.

A punched tape format, shown in Figure 10, has been prepared for automatic handling of spectroradiomater data. Field data are placed on punched tape according to the format.

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Purdue University has developed a mobile laboratory for gathering field rediance data and for taking other suriliary data. The equipment is described in Exhibit B. Redience spectra ...quired in the field with a spectromater or spectroradiometer have a general similarity to reflectance spectra measured from individual Leaves on a spectrophotometer in a Laboratory. There are important differences, however, which are due to the following: (a) absorption and scattering by gas molecules and dust reduce incoming solar radiation in certain wavelength bands; (b) illumination from the sum varies in intensity with numerous conditions; (c) the energy source in a spectrophotometer is of constant intensity whereas the solar energy source varies in intensity with wavelength; (d) radiance from crops in the field is affected by erop geometry, background soil reflectance and other factors; and (a) radiance from soils in the field is difficult to duplicate in the laboratory with disturbed soils.

Spectra from a cotton field, measured with an ISCO spectroradiometer, and from a cotton leaf using a laboratory spectrophotometer are shown in Figure 11.

Thermal Infrared Calibration Procedures

The MASA plane is not equipped with internal reference signal generation for the thermal infrared scanners. Therefore, it is necessary for thermal imagery to be calibrated by making ground truth measurements. These measurements are made during, immediately before, and immediately after the scanner-bearing plane is over the target area.

A Barnes PHT-5 radiometer sensitive in the 8-14 micron wavelength range is used for the ground measurements. It is calibrated over a wide range in its reference body temperature against a Laslie cube blackbody source. The temperatures for soil, plant, and other surfaces, then are equivalent blackbody temperatures; i.e., the temperatures these objects would have if they had unit emissivity. This reporting form is used unless the necessary measurements for correction for reflected radiation from the surroundings (fuchs and Tenner, Agron. J. 58:597-601. 1966) are made. The care with which the radiometer is calibrated and the high emissivity of dry soil (about 0.92) and green leaves (0.97 to 0.98) minimize the demonstrue from true temperature.

Interpretation of the imagery is made by making microdensitomater tracings across the film imagery at sites where the ground truth temperature is datarmined. Optical density of the film at these particular sites is then plotted against the ground truth temperature to produce a curve encompassing the range of film densities in the imagery.

Since it is not possible to integrate the temperature of plants, and exposed soil in furrows, in a ground based measurement, as the airborne sensor does, large areas of uniform surface are used. A highway, a 6 acre-foot water reservoir, and smooth bare fallow soil are the principal calibration sites. Temperature measurements are also used of plywood pauels 25 feet by 50 feet recently painted with 3M optical white and optical grey (obtained by mixing optical white and optical black) paint.

Because the temperature of plant, soil, and other surfaces fluctuates readily with changes in insolation, the direct plus diffuse radiation indicated by an Eppley pyranometer is recorded at the same time the temperature measurements are made.

Figure 12 shows the relationship of film density (D) and equivalent blackbody temperature (T) established for a rangeland site. The relationship of T to D is lunear. The bare soils were considerably warmer than the semi-desert vegetation and the water surfaces were cooler. The individual brush species vary approximately 1.5 C in temperature.

48

Thermal Infrared Thermograms as Ground Truth

In addition to using a Barnes PRT-5 radiomater for obtaining plant, soil, and water temperatures for ground truth, a Barnes Model T-5 infrared camera produces a thermogram of the target in the form of a Polaroid picture. Temperatures from the thermograms can be used to establish the accuracy of those obtained from the NASA IR scanner.

Plant canopy temperature patterns obtained with an infrared camera during a study of diurnal temperature changes in small, differentially irrigated cotton plots are presented in Figure 13. The figure is a composite of 4 thermograms taken at the time of day (CST) indicated below each thermogram. The first thermogram use obtained at 0540, well in advance of daybreak. The light areas from bottom to top on this thermogram - ignoring the one at the very bottom of the thermogram are a man kneeling between the plot in the fore round and the center plot, an incandescent lamp in the far plot, and three aide-by-side instrument shelters just beyond the plots. The other thermograms depict the same target at later times during the day.

In all the thermograms presented, the lighter toned areas present warmer plant temperatures. Interpretation of the thermograms is made by matching the tone of a target within the field of view with one of the eight gray scale steps printed automatically at the top of each thermogram. From the electronic settings used to obtain the thermograms and a parameter corresponding to the gray scale step, the target radiance may be calculated and then converted to target temperature. It was necessary to vary the electronic settings as the crop surface warmed so that temperature differences could not be compared by visual inspection except relatively within individual thermograms.

The cotton plot in the foreground and the one in the background of each thermogram were at about the same moisture condition, and have the same tone. The middle plot was driar than the others. The calculated temperature difference between dry and wet plots was 0.1, 0.3, 2.0, and 0.2 C at the hours 0540, 0935, 1520, and 2210, respectively.

Thermal Infrared Detection of Soil Characteristics

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Soils are unique in that subsurface soil characteristics influence the energy received by thermal infrared remote sensors. Investigations of thermal infrared detection of soil characteristics are being made in an area of alluvial floodplain soils shown in Figure 14. The bare soils shown in fields k, 1, and m are those investigated in detail. A transect of 16 soil sampling sites was extended across the bare soils area, having a variation in surface and subsurface soil characteristics.

Diurnally-flown thermal imagery of the area is shown in Figure 15. Each of the transparencies was scanned with an isodensitracer to determine film densities. An isodensitracing of the 1900 hour thermogram is shown in Figure 16. Film densities (D) are directly related to equivalent blackbody temperatures. The temperature-film density relationship was established at a well instrumented site several miles away which was flown only a few minutes earlier, in each case, with the same scanner electronic gain settings. Data from the calibration site were used to plot a graph of ground truth temperature versus film density. The relation was linear in every case.

Temperatures at 30 selected sites were determined and are shown on the isodensitracing of Figure 16. The numerals beneath each point (23/26) mean point 23 which is at 26°C. The significance of these temperatures in relation to soil characteristics are discussed in the 1967 Weslaco, Texas, MASA report.

Data Processing

The amount of information being collected and the number of different forms of data being collected demands that there be a means of automatically summarising all the different forms of signals and to convert all summaries to a common base.

The Weslaco remote sensing program at present has information in the form of photographic and scanner imagery from the MASA plane, analog signals on magnetic tape from the four scanners in the Michigan plane, photographs in conventional color, black and white infrared, and infrared color taken from the local Weslaco plane as well as information from laboratory instruments on punched paper tape, x-y recorder charts, and stripchart recordings. All these forms of data are compared to manually recorded ground truth conditions and in pletures from ground level.

Crop signatures will be developed for testing by recording reflected spectra from various crop and soil conditions by ground based spectrometers. Spectrophotometer curves of transmitted and reflected emergy from individual leaves under controlled conditions are also used to suggest crop signatures. Statistical energyees and summiries of data in the form of digitized spectrophotometer curves, data logger output of mateorological sensors, and other laboratory measurements are being made by Texas A&M University.

Efficient bandling of data in many formats and originating in a number of different forms requires a data handling system specifically designed to take cars of the unique characteristics of the system. Figure 17 is a flow sheet which shows sources of ground truth data; ground based instrumentation for gathering ground truth, as well as aerial equipment; and how the output from the instrumentation and equipment must be processed and analyzed by computer and then, in some cases, reconstituted into imagery.

Retablishing Interpretation Keys

In phases of the agriculture and forestry programs which involve identification of crops and soils, forest and range species or plant communities, establishment of interpretation keys is found to be a valuable aid in establishing standards. Interpretation keys in current use consist of vertical photographs supplemented with obliques and ground photography. Interpretation keys serve three purposes; first, as a training aid for the new student; second, as indoctrination into new areas or items for trained personnel; and third, as a comprehensive library reference for the experienced interpretar.

Forestry Ground Truth

Investigations are underway by the U.S. Forest Service (R. C. Heiler and associates[®]) to determine the ground instrumentation, aerial sensing equipment, and techniques required to detect vigor loss and previsual signs of tree mortality caused by bark beetles in coniferous timber stands. Ground and aerial studies are involved. Figure 18 shows the 1966-1967 USFS-EASA Black Wills Beetle Test Site near Lead, South Dekots. The following are examples of ground truth obtained in this study. Many other forestry projects are underway for which ground truth data are collected.

Establishment of Attractant Sites

It has been found that by placing laboratory reared beetles in screen cages on host trees (Figure 19) during the period of active beetle emergency in the summer, wild beatle populations could be induced to attack the tree with the caged beetles and many surrounding trees as well. In August 1965, a total of 11 sites were established in this menner within the study area.

Mathod for Determining Vigor Loss

Meedle moisture tension is one additional parameter measured in 1967 that may help to determine early vigor loss. Briefly the method is as follows:

* Pacific Southwest Forest and Range Experiment Station, USDA, Borkeley, California.

The twig end of a freshly-cut foliage sample (about 4 inches long) is inserted through a rubber "o" ring which is fitted into the top side of a pressurised container (Figure 20). The proximal end of the twig is exposed to atmospheric pressure. The needle portion of the sample is then placed inside the bottom part of the container and the two parts are screwed together. Bitrogen gas is introduced slowly to the container until free water begins to bubble from the tracheid cells in the cut end of the twig. Hornel foliage required less pressure to force out the water than foliage from stressed trees. The absolute pressure values - but not comparative values - are affected by time-of-day, season, soil moisture availability, and sunlight conditions.

Preparation of Ground Resolution Target

A ground resolution target measuring 8x68 feet was constructed to determine spatial and thermal resolution capabilities of thermal infrared scamers. Twenty-seven fiberboardpanels, each 4x8 feet, were covered with 2 mil aluminum foil; the foil was pasted to the smooth side of the panels with wallpaper paste. Half of the panels in widths of 2, 4, and 8 feet were pointed with 3M black velvet point; the remaining panels were left aluminum. They were then laid out in alternating black and aluminum array (Figure 21).

This target array was designed to test whether the airborne scanners had a 1-, 2-, or 3-milliradian resolution capability.

Ground Truth Measurements - Short Term Orbital Mission

The following ground truth measurements (at time of overflights) would be required in relation to a 10-15 day orbital mission:

1. Simultaneous photography (aircraft and ground).

2. Plant and soil observations at all ground stations as recorded on standard form (Figure 3).

3. Short wave spectrometer spectra.

4. Meteorological measurements

- a. Barometric pressure
- b. Dew point
- c. Incoming total radiation
- d. Sky radiation
- e. Wind
- f. Ambient temperature

5. Specific fields with stressed plant conditions shall be established to determine if they can be detected from space.

6. A large bare field will be subdivided and prepared to include different soil conditions for detection from space.

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7. Large areas of various range type plant communities will be delineated for sensing from spece.

Ground Truth Measurements - One Year Orbital Mission

The same measurements made for a short orbital mission will be made for a one-year mission with the following additions:

1. Sequential measurements will be made to establish the validity of orbital sensing of plant and soil characteristics under a wide variety of conditions.

2. Yields of crops will be measured and correlated with orbital sensing data.

EXHIBIT A

Objectives:

- 1. To determine characteristic multiband signatures of various crops and soils in the Lower Rio Grands Valley of Texas.
- To identify grops and grop conditions by remote spectral seasing techniques.

Variables:

- 1. Under investigation
 - a. Crop varieties
 - (1) Cotton
 - (2) Grain Sorghum
 - (3) Citrus
 - (4) Corn
 - (5) Vegetables
 - (6) Pasture
 - (7) Oats
 - (8) Alfalfa
 - (9) Mative brushland
 - b. Stage of maturity
 - (1) Plant height .
 - (2) Leaf area index
 - (3) Percent ground cover
 - (4) Number of nodes
 - (5) Row spacing
 - (6) Phonological development

c. Plant vigor and condition

(1) Stand (Plants per unit length of row)

- (2) Weediness
- (3) Crop color
- (4) Nutrient deficiencies
- (5) Insect and disease infestation
- (6) Relative turgidity or absolute water content
- (7) Yield or potential yield
- d. Soil characteristics
 - (1) Soil series
 - (2) Moisture content
- 2. Not under investigation
 - a. Climatic variations
 - (1) But dates of irrigations, standard weather station data,

12

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and solar radiation information will be recorded or available.

b. Cultural practices

(1) Will be observed and recorded at test sites.

Procedure to be followed:

The ground truth will be that obtained in conjunction with overflights along 65 miles of ground test sites, and continuing periodic flights by MASA and locally chartered plane. On these flights multihand imagery is collected from sirborne remote sensors such as multihese commens, multichannel optical scanners, thermal pyrometers, microwave radiometers, radar scanners, and other appropriate instruments. Ground truth information describing completely the soil and crop conditions is collected simultaneously with the multihand signatures.

All imagery will be examined visually and electronically to detect obvious differences in the crop signatures. Characteristic signatures will be set in an electronic discriminator and into a digital computer to determine the uniqueness of the specified signatures. Confidence levels of individual signatures will be determined through statistical calculations in a computer.

Signatures from individual fields will be correlated with ground truth observations through a covariance matrix calculation in a computer. Factors that are significantly correlated will be examined more closely to determine the interrelations emong orop factors and signatures.

Data to be obtained:

Crop signatures, or portions of signatures, will be obtained as

- a. Voltage signals on magnetic tape
- b. Recorder trace on paper charts
- c. Photographic imagery
- d. Thermograms
- e. Photographs of oscilloscope display
- f. Isodensitracings of transparencies, and
- g. Densichron readings of transparencies

All signals will represent intensity of reflection or emission in one or more wavelength bands.

Interpretation and Application of Results:

Signatures will be used to survey areas to determine the entent of the crop species or condition specified by the signature. Surveys may be used to determine the potential yield, to locate the outbreak of certain plant diseases, to assess the spread of an insect invasion, to follow the progress of harvesting, or to estimate the acreage planted, and to determine the need for soil moisture or plant nutrients. LARS Information Note OBLA67 Pursue University

FRANKING A

IABORATORY FOR AGRICULTURAL REPORTS SERVICES Truck Instrumentation and Corphitules

The basic field data instrumentation is designed to be mounted as a complete unit in the field van such that all field date can be collected in the natural environment of the sample to be measured with a minimum of external equipment and a minimum of sot-up and take-down time. As a self-contained unit, the field van contains all the necessary measuring equipment and its com power source. Provisions are included for operating the data collecting instruments from either the field van moder or the charry-picker bucket (up to 50 feet from the ground surface). The general instrument schematic is shown in Fig. 1.

This instrumentation includes the causing instruments and the necessary recording equipment. The recording equipment consists of three basic types-the Aspex SP-300 seven-channel (1/2 inch) 2% or direct tops recorder, the Honeyvall 24-channel strip recorder, and the operator's data sheet. The Anyex SP-300 seven-channel type recorder is used to record the output signals (interforograms) and the digitizing signals (clock signals) from the Block interferometers. The output signals from the Block interferometers are recorded in the 18 mode in order to eliminate the reproduced signal amplitude variations inherent in a direct mode tape recording device, while the clock signals are recorded in the direct mode because of the frequency limited one of the FM mode. Provisions are included for a voice channel for recording identification numbers and other pertinent information if it is desired. The Honeyvall 24chonnel strip recorder is used to record in a sampled form on paper the alosly-varying signals from thermocouples measuring the ground and/or ambient temperatures at various levels, the output signal from the Sypley pyrinklicenter used for indicating the quantity of incident solar energy contained in four wide wavelength bands, the output of the Bannes PHP-b redicenter for measuring



the apparent temperature of the scene examined, and the output of the ISCO spectroredicaster for indicating the spectral distribution of the incident solar energy. This recorder is a universal jaw recorder for indicating sampled values of slowly varying conditions pertinent to the experiment. The operator data abset indicates the information necessary for tying together the data recorded on the other recorders. This includes information such as the run identification numbers, the tape position indicator values for the stop and start of each run, the time of day, various instrument settings, and photograph number if photos were taken.

Other accessory equipment is required for operation as a self-contained unit. This includes the 6.500 gasoline (or gasecus fuel) driven Kohler frequency stellized MG set for supplying instrument and lighting power, the 300 truck engine driven generator for supplying power to the air conditioner and tools which are apt to cause line transients that interfere with date collection, the tranceiver gear for communications between the operator of the sensing equipment and the recording equipment operator, and miscellaneous tools and instruction manuals for field maintenance.

At the present time most of the sensing and recording equipment and all of the accessory equipment has been installed and used on several data collecting missions. The remainder of the equipment is in the process of being installed and continued improvements are being made on the existing installation.

The installation of the accessory equipment is complete and in operational status. The frequency stabilized 6.569 generator attaches as a trailer with connecting cables to the field wan and has a frequency stabilization sufficient to maintain constant recorder speeds. The 369 generator connects to the truck angine when needed and the voltage level and frequency are controlled from the van. The communications gear is rack mounted and is used both for lits recording and for unloading the data from the truck to the analog-todigital converter. Tools and manuals are in permanently mounted cases and file catinets in the van. Because of the weight distribution in the van it has been found necessary to equip the truck with heavy duty springs which are now being obtained.

The Ampex SP-300 tape recorder and the Block 195T and 195E interferometer electronics are rack mounted in the van. Figure 2 shows the recorder in its mount in a preliminary set-up. Cabling has been made with interface panels for operating the interferomatic optical heads either on top of the van as shown in Figure 3 or in the cherry-picker as shown in Figure 4 and Figure 5. At the time of these photos, the truck interface panels were not installed. The cabling and interface panels allow for simultaneous operation of the Block 195E and 195T interferometers. Operation from the van roof is made by mounting the optical heads on a tripod set on the aluminums grid platform and connecting cables from the optical heads to the interface panel. Operation from the cherry-picker is made using an instrument platform mounted on the bucket. The optical heads are mounted on geared pan heads fixed to this platform. A fifty foot cable connects the optical heads to the truck interface panel. The long cables have not noticeably affected the quality of the output signals. The output of instrument electronics in the wan are connected via interface panels on the instrumentation rack and on the recorder rack to the respective recording channels. The input and recorded signals are monitored on an oscilloscope for instrument and recorder level adjustments.

The Honsywell 24-channel recorder is in the process of being mounted in ite rack in the van. Connections will be made from the recorder to the outside of the van. The sensing equipment for this recorder are, for the most part, portable and are set up outside the van either on the ground, on the truck roof, or in the cherry-picker as the experiment requires.

In a typical data-collecting mission using the cherry-picker and the

17

Elock 195E and 195T interferometers, three operators are required. About 15 minutes are required in order to set-up and adjust the recording levels, optical heads, and cabling. For the 195E interforometer, liquid mitrogen is transferred from the large dewar in the truck to the small vacuum bottle mounted w. h the optical head. A proper flow of liquid mitrogen must be obtained in order to assure cooling of the detector. The run procedure requires that one operator in the cherry-picker aims the optical heads at the desired scene of view while the other operator records the run number, description, etc., on the data sheet. A minimum of one minute of data and clock signals are recorded to separate the runs. The third operator installs micromet and insolation gear on location, and takes radiometer readings as required. When all the runs desired at one location are complete, the cable to the cherry-picker bucket plotform is disconnected at the platform and the van and cherry-picker move separately to the new location. Take-down time at the end of the day is also on the order of 15 minutes since only the external equipment and cabling must be packed.

The data is transferred to the LARS A/D converter by means of the fifty foot cable and interface panels at the truck and the building. This allows the data to be reproduced from the 3P-300 without removing the recorder from the van. The transceiver gear is used in this process for communication between the operator in the van and the operator of the A/D converter in the building.



19



Figure 3 Measuring crop radiance in the 2 to 15µ bend from the field van roof.

18

Figure 2 At the tape recorder inside the truck.





NASA-5-67-7727

FORM USED IN COLLECTING GROUND TRUTH INFORMATION

OCATION: TransectSite No	Legal Descr.	
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Color, Muneel	et Dry	Set . 1_
Color,	Cand D	epth to Water Ta
Texture	Pr 2nd Pt.	3rd Pt.
Noiscure, Surfaceier	Other	
Salialty	OCH S	
TEMPERATURE. (PRT) Plant	ioilInregrat	**************************************
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ROUND PHOTO: EAN NoColor	NoIR No	Ocher
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PECTROPHOTOMETER CURVE NO.	Book	
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NASA-5-67-7731



















NASA-S-67-7733

HIGH RANGER RECORDING INSTRUMENTS MOUNTED IN BUCKET



MASA-5-67-7726

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PUNCHED TAPE FORMAT SPECTRORADIOMETER DATA

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Nonserventions Hamilton 201-098
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NASA-5-67-7724

SPECTROPHOTOMETER AND PAPER TAPE PUNCH SYSTEM 關係亦是 SPECTRORADIOMETER NASA-S-67-7719 MOUNTED IN BUCKET OF HIGH RANGER

4. Soil enalysis

- 5. Emissivity analysis
- 6. Meteorologio enalysia
- 7. Density specific gravity
- 8. Photogregmetric constructions
- 9. Drafting and illustrations
- 10. Documentation and reports
- 11. Test site selection analysis

Field cershilities include:

- 1. Geologie mapping
- 2. Soils sapping
- 3. Rook and soil moisture data
- 4. Brissivity data
- 5. Meteorologic data, including around to senser profiles
- 6. Thermal data collection (8-14a)
- 7. Thermal diffusion
- 8. Vehicular and transportation
- 9. Communications
 - a. Introparty b. Ground-alreraft
 - o. Single side band
- 10. Beacons for sensors a. Microwave b. Radar
- 11. Flight line marking
- 12. Biosphere data collecting micro to moga aphere.

While it is well enough to know one's strengths and abilities, the wise will have full knowledge of their limitations as well. Thus, the following expabilities have not been activitated and may be worthy of future consideration:

a. Depth studies in rocks. The majority of our research has been at the surface. Recently, we began measuring atmospheric profiles between the surface and the sensors. We have still to commonse studies of rock data down to the pelstration limit of the MAMA suite of sensors, a depth of 10-12 feet. The microwave team has expressed an interest in our undertaking research in this area.

b. Ground based sensors in the microwave region. Because of the tightly constrained atronaft schedule and the general lack of microwave data, ground based microwave sensors (rediometer and/or scatteremeter) would yield meaningful data and shorten the time span required to evaluate ground truth parameters at these wavelengths.

c. Telemetering. The ability to talemeter data to any direction is totally lasking. Possible points of transmission include (1) up to an airwart or spacecraft, (2) laterally to a van, (3) direct to the Manned Spacecraft Center (MSC) data bank.

45

Ground Operations

in a very bread sense, the Ground Operations Flow Chart (Plate 3) escribes a systematic method in which ground and airborne conner ata are accumulated and shows how the resulting information, the orm of a final evaluation of remotely sensed data, is produced.

ince the ultimate objective of the program is to remote-sames specific argots from space and airborns sensors, it follows quite logically hat in the initial stages of the program a clear understanding of what entributes to the total signal of any sensor must be defined and sacured if we are over to make sense out of the data.

istrument teams must understand the limitations and capabilities f their can instruments before user groups can intelligently designate beir use for any specific target. The need for calibrating the istruments by building a backlog of data generated over carafully build targets has been a common objective of the instrument and ground ruth teams.

b have a description of the varied parameters that affect the total ignal of the microwave, infrared, sultispec, and radar. It now becomes is charge of the ground team to collect the data on the ground that on be used to describe quantitatively the percentage contribution of out of the varied parameters affecting the total signal on the aircraft istrumentation. The next logical step would be to superimpose on the istrument data accourcements taken on the ground from which scame underanding of instrument capability should evolve as well as now and better warting parameters for specific targets.

geologic target provides some of the most complex problems in remote insing, however, even though the targets vary, the same instruments are wolved and the parameters, if any, remain constant. It is the applied ichniques that change.

Parameters Affecting the Infrared Signal

Three types of consors in the infrared portion of the spectra are currently being flowm in the Earth Resources Program - an infrared redimeter, an infrared imager, and a spectrometer. For the sale of simplicity the parameters affecting the total signal of these three instruments are combined on plates 7 and 8. Each instrument's Each of operation controls the order of significance of the individual environmental variables.

The besting property of a material is controlled by two variables, the albedo and the thermal conductivity. For example, a dark substance such as baselt will heat more repidly under solar rediction than a lighter material such as granits. However, a soil may heat with even greater rapidity due to its slow downward conduction of energy. During the nightly cooling period of these waits, a complete inversior of the nightly cooling period of these waits, a complete inversior of surface temperature is likely to useur. The soil material will quickly surface temperature is likely to useur. The soil material will quickly drop below the air temperature. The granite which has a comparatively high thermal diffusion will now be heated by a subsurface temperature and because the warmest material.

The amount of energy radiated at the surface of a material is dependent on its emissivity (E_R). For example, a substance at 70°F with an emissivity of .80 will redict only 80% of that capray and appears to an infrared radiometer to have a temperature of 56°F. The other 20% of the energy is reflected from the sky and neighboring material. The total signal can be expressed by the equation $P_{\rm R} = T_{\rm R} (E_{\rm R}) + T_{\rm R} (1-E_{\rm R}),$ where $T_{\rm R}$ is the temperature of the environment (i.e. sky), (1-E_R) is the reflectance, $T_{\rm R}$ is the temperature of the material and $T_{\rm R}$ the temperature resolved at the redicemeter.

The energy attenuated by the atmosphere is entracely frequency-consitive. A alight change in oness or water waper content may absorb one wave length's energy and have little or no affect or mother wave length. For this reaces close attention chould be taken to the atmospheric column between the aliveraft and ground. Without proper correction for atmospheric content, data recorded at different altitudes should not be compared. Likewise, data taken at various times during a seasonal period should be compared with coution.

Data interprotation is complicated by vegetation on the geologic test cites. A multicensor package is very useful in removing this variable from the signal. Hear infrared examples detection film may sid in identifying the type and distribution of vegetation, and the vigor of individual types. Flast life is very balaful in spetting characol changes in soil context and dofining a climatic sens. The latter is significent when subter the use thering the set of the start of very solar to be added to extend the use thering the set of very solar to be types and the soils they are forming. Multure context and percolation, which affect vegetation distibution and vigor, is dependent on rock type, moved by, and sail corting. Proper interpretation of the environmental variables is necessary in defining and interpreting thermal anomalies. In predicting volcanic cruption, the type of material, the thermal diffusion, and entseivity will determine whether a large transfor in subsurface temperature will be reflected at the surface. In the case of sulfide oxidation, climatic features and the weathering characteristics of the sulfide bearing rock will determine the size and extent of this anomaly.

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Paremeters Affecting the Badar and Higromere System

In the microwave portion of the spectra wany of the persentere affecting the signal are similar to those in the infrared. The major difference between infrared and microwave is the depth of penetration of the redient energy. The penetration power is controlled by the disloctric properties of the material. In particulate matter, three variables must be considered - the disloctric constant of the solid matter, the contained water, and the porceity. In areas of high moleture cantest even the pH of the moleture can affect the conductivity - resistivity balance. In solid rock, disloctric constant measurements can be made directly on small complete.

The emissivity at microwave frequencies is lower than that of the infrared. This makes the reflectance of considerable importance in the signal received at the instrument. Slope, surface geometry, and the temperature of the sky, contribute a larger portion of the rediant energy received.

All subsurface features such as layered bedding, depth of water table, and subsurface temperature directly affect the emitted radiation. Flate 11 shows the diurnal beating and cooling curve of coll at depth. Note that lag in heating produced by poor thermal conduction. Subsurface temperature measurements are necessary in data interpretation in materials which examt be easily removed for laboratory emilysis of their disloctric properties.

Bautement List

A list of measurements and the equipment used by the University of Neveda are indicated on Flates 12 and 13. While not means to centain all the minor supporting gear, these Plates indicate some of the major equipment and the measurements made by these instruments.

There should be a standardisation in the sireraft overflight memitering gear, to make possible the comparison of data from different test sites.

Recommendations for the Puture

Airoraft Program

Recommendations for the aircraft program have arisen over a period of two and one-half years and represent a synthesis of discussion with many people who have varying degrees of familiarity with the program.

1. <u>Ground Resed Sensors</u> - For spectra longer than the visual region, much more surface work with sensors on the ground should be accouplished in IR, both imaging and spectral, in microwave, and in southercovery. In a multispectral approach these sensors might be tied together with a field van, although several independent wans would be superior in that they would offer greater flexibility and the wan would not be useless to the other sensors if one same wave incorrello. There is an intense meed for field work basis to the underwtanding of ground truth which can be best accomplished with this technique.

2. <u>Talematering</u> - MSC should be entering talematering procedures as rapidly as possible in the aircraft segment of the Earth Resources Survey Program. Experience prior to spacecraft flights is required. Data can be telematered unward to aircraft or spacecraft, downward to field wans, or directly to MSC data bank. HECONSENDED: A conference to decide how telematering is to be accomplished and when it can commence.

3. <u>Automated Data Promessing</u> - MSC needs to move toward any system likely to lead to automated data processing. Each passibility needs to be applored and evaluated with the idea of determining which is best suited for the Earth Resources Survey Program. The optimum would appear to be a single system which would handle data from all parts of the spectrum. Automation must start immediately with the Aircraft Program; to wait for the spacewardt is to invite diseator.

4. <u>Sevent Integration</u> - New sensors have special problems of their own; they require severe time frames and intensive usage until they become calibrated and useful for their framibility studies. RECONSENT Acquisition of a light aircraft for getting the bugs out of new prototype sensors. The larger multisensor aircraft should not be tied up with this type of activity, and should carry cally those sensors which have proven themselves in the air on an isolated basis.

5. Additional Sensors - Additional sensors should be sought for consideration. Most likely sorts of things to be desired: additional warelengths, especially longer wavelengths in infrared and microwave than ourrently being studied. This approach would also give bottor multispectral capability.

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Spacecraft Frogram 14-Day Mission at 125n.m. 50° Inclination

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Recommendations made in this section are the result of inquiries commenced by Frank Casey in October 1966 and represent an evolutionary continuum of thought since that time, rather than ideas generated in the past two weeks.

1. <u>Hell-known Test Sites</u> - For geology we believe that the test sites should have adequate conventional geology available, so that the field teams need only perform the specialized studies required for ground truth calibration work.

2. <u>Ground Truth Research Teams</u> - A two to three man ground truth research team will be needed on the ground for 90-100 days, any time in advance of the overflight. Their role will be to plan the operational aspects of the ground truth data collection and to obtain advanced field data for research purposes. This group would subsequently write and make available to the operational ground truth squad a manual of operations.

3. <u>Ground Truth Operational Sounds</u> - A squad of 15-20 men, suitably equipped, will be needed for each geologic test sits. Their time in the area should be approximately two weeks, during which time they establish theseslves, support an aircraft overflight in preparation for the spacecraft overflight and finally support the spacecraft overflight. Their work will be laid out in prepared manuals which will become available prior to their departure from NSC or other base.

4. <u>Simultaneous Aircraft Overflights</u> - In conjunction with the spacecraft flights there need to be aircraft operations to permit the bulld-up of remotely sensed data in three dimensions: on the ground, at aircraft altitudes, and at space altitudes. Simultaneous aircraft overflights are of prime importance in the early spacecraft missions to provide a standard of comparison of data, so that the quality of the space sensors can be more accurately gauged. Ideally, identical sensors would be on the aircraft and spacecraft.

5. <u>Bight to Tan Test Sites</u> - Eight to ten test sites should be sufficient to calibrate the sensors for a variety of geological features. The majority should be in the United States for reasons of ecomony and efficiency, but a few will need to be outside the country to meet conditions which are not found within the United States. The test sites recommended have have been under consideration for more than a year, and appear to offer a most meaningful experiment calibration system. They are numbers, order and no priority is intended by any of the numbers.

5.1 MoDonald Range, Alice Springs, Australia. This is the locale of a great sequence of sedimentary rock very simply arranged. Detailed geologic reports are svailable and the area is ideal for the minimal soil and vegetation encountered.

100

6. <u>Ground Truth Squads</u> - Full consideration should be given to the establishment of ground truth collection teams within MSC or via contractors. These teams would function to collect data on operational missions, collecting according to specific instructions for each site as established by the research teams. Thus, there would be research teams for geology, commonstraphy, agriculture, etc., operating at the scientific level, including planning of missions and continued research in improved techniques. Ground truth squads would be primarily technicians with the capability of collecting ground truth date for every discipline. This type of activity will become much more important in the future when the larger aircraft operate cutside the country and when spacecraft fly.

7. <u>Communications</u> - There needs to be a greater number of meetings of the warious components of the Earth Resources Survey Program for the full exchange of ideas and progress summy the various contractors and grantees. Prior to 1966, meetings of this type were relatively rare and the majority of workers in the program did not have a clear view of the overall program. The commencement of aircraft scheduling meetings in Houston in the fall of 1966 afforded the representatives of the instrument and discipline groups the opportunity to gather every three months for informal discussions and markedly aided communications. RECOMMENDED: This type of program be continued.

8. <u>Boresisht Camera for NR 62-64 Radiometers</u> - A boresight owners depicting the field of view for the NR 62-64 microwave radiometers is required for the interpretation of microwave data. These sensors are tisd to the tracking devices of the present photographic systems indirectly. Locating the field of view of the axisting microwave data is cumbersome at best, and impossible at worst. The microwave radiometers are hard mounted and the camera systems are flaxmounted. The cameras lock at the nadir, the radiometers lock a minimum of 10° from the nadir, and as high as 45.

9. <u>Fast Film for Mishi Missions</u> - We recommend experimentation with films of 3,000 and 6,000 ASA for night missions at 2,000' absolute to see if visual data can be gathered to permit interpretation of the non-imaging data such as microwave radiometers and scatterometry.

10. <u>AAP-1A Test Sites</u> - Test sites for instrument calibration for AAP-1A should be defined as early as possible and should be overflown with the aircraft in the near future for preliminary studies.

11. The time is approaching when ground truth determinations should be standardised as to equipment and technique. We are not at this point today, but it is on the horison. Ground truth squads (#6 above) will, of course, bring increased emphasis on this requirement.

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Also the weather is exceptionally favorable, with clouds a rarity.

5.2 Volcanos, Hawaii. The volcano complex on the island of Hawaii, especially the Mana Los-Kilausa complex is of especial interest. The United States Volcanologic Observatory has an extensive background of data, and could cooperate with the growth truth teams and equads. This represents an outstanding opportunity to see what can be accomplished by remote remove in the area of volcanologic study.

5.3 Southern California. This very large test site, estending across the southern margin of California includes a veriety of diverse geologic and other features. It is in an area of law clowed cover which makes it a high interest site for all sonceres. Included within this test site area (a) Metropolitan San Diago (geography), (b) intrustre igneous rock complexes (geology), (c) decert terrain (geology and scopraphy), (d) Salton San (hydrology), (e) Imperial Vallay (agriculture), (f) Entrusive and sedimentary rocks (geology), (g) the Colerado Eiver on the sectors boundary for sensor blackbody calibration. The Panific Geess off the coast is also of interest to cossangraphers and serves for blackbody calibration.

5.4 Sumatran-Javances Volences. On Gemini photography all of Java and most of Sumatra are obscured by clouds. These island chains have a vertebras of volences, many of which are classified as "dangarous" to the danse population. This would make an emcoedingly fine site for volence study by the cloud peeefrating sensors; microsuve and redar. Good ground support is available locally.

5.5 Followstone Maticual Park. The U.S. Geological Survey has had a program of research going in this locality for many years and has built up an impressive number of man-months of field and laboratory research effort. This body of data deserves to be sugmented by spacecraft data. Clouds and the biosphere are likely to be deleterious to a few of the sensors.

Se

5.6 Pinacati Hill, Mexico. This circular, well-known feature inactistely couch of the American border is af geologic interact as an extensive laws field. It is readily located by its proximity to the Gulf of California, and obseed up well on Genisi photography.

5.7 Sheep Kountain, Nyeming. A sequence of folded sediminitary rocks in simple pattern, this breached semealizes serves as an encellent structural target with a wide variety of sodimentary rocks which are wall appead. Much of the basic geologic work is already complete for this target providing an excellent base to apply remote semeat toolmignes.

5.6 Quadrilatoro Ferrifero, Erasil, Tais is en eres of important motolio cros end vould serve to provide an eres of obsity wiser vegetation is not dense and where rech exposures are prof. A hope background in conventional geology is evaluate for this test site, 5.9 Continental Margins. Continental margins should be corutialed always for possible water resources entering the cos, usually visible by tesperature contrasts and should appear on infrared and microwave radiosetry data.

33

In closing, a table of events is postellated for goologie ground truth, showing the sequence of events enticipated and the probable amount of time required for each event (Figure 19).

Spacesraft Program - One Year Mission at 270- 70n.m. 50° Tealingtion

A one year mission might very well be run in four two-week segments to take advantage of the seasonal changes for the non-geologic dissiplines. For the geologic test sites, we recommend that the basic two-week ground truth regimes of the previous section be followed.

We cannot help but wander what level of resolution HAGA anticipates receiving at this altitude with the present generation of sensors. We ask also if it might be possible to schedule a remote sensing operation during the decay phase of the mission when the spacecraft would be orbiting at 125-150 n.m.?





MICROWAVE BEACON



NASA 5-67-7747

LAUNCHING A RADIOSONDE BALLOON

NASA 5-67-7746

BARNES INFRARED RADIATION THERMOMETER

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DEFINITION OF GROUND TRUTH

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NASA-6-0-7703 REPORTS (CONT)

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INFRARED SYSTEMS

PARAMETERS EFFECTING JOIAL SIGNAL	ENVIRONMENTAL VARIABLES
THERMAL DIFFUSIVITY	MOISTURE CONTENT GRAIN SIZE AND SHAPE SUBSURFACE TEMPERATURE 'THERMAL COMDUCTIVITY' COMPOSITION BULK DENSITY
EMISSIVITY, EX	 SURFACE GEOMETRY MINERAL CONTENT*
SOLAR ALBEDO	COLOR AND SURFACE GEOMETRY OHURNAL HEATING CYCLE
METEOROLOGY	AIR TEMPERATURE SKY TEMPERATURE WIND AIR WATER CONTENT*
SIOSPHERE	 VEGETATION TYPE AND DISTRIBUTION VEGETATION VIGOR ORGANIC DECAY
ANOMALOUS FACTORS	 VOLCANIC & HYDROTHERMAL ACTIVITIES SULFIDE OXIDATION

*VERY IMPORYANT IN IMPRARED SPECTROMETRY

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RADAR AND MICROWAVE SYSTEMS

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SCATTERING AND POLAN- ZATION EFFECTS	SUBPACE ROUGHINESS SUBPACE ROUGHINESS SUBPACE ROUGHINESS
METEOBOLOGY	© AEL MOIST JRE © SEY TEMPERATURE* © UEND*
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SLOPE	SLOPE ANGLE AND
TEMPERATURE	SUBFACE AND SUBSURPACE

* IMPORTANT MOSTLY IN PASSINE SYSTEMS

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N284-9-98-961

DIURNAL HEATING-COOLING CURVE FOR BASALT CINDER



UNIVERSITY OF REMAIN

MEASUREMENTS MADE AND EQUIPMENT USED

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BUBBURFACE IBMP	O DUDITECS & THERMISTOR PROSES
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ENNESIVITY (0-1-441)	& EMISSIVITY CHAMBER
THEBRIAL DIFFUSIVET	O THERMAL OFFICER TEST SET
ATMOSPHERIC	COMPLETE WEATNER STATION IN CLUDING RADIOSONDE BOURP

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MOVERENTY OF MEVADA

NAEA-5-67-3712 RECOMMENDATIONS AIRCRAFT PROGRAM

- · GROUND BASED SENSORS (VAN)
- · TELEMETERING EQUIPMENT FOR DATA GATHERING
- · PRIGHTIZATION A/C OPERATIONAL FLUE
- · USS OF 3050, 4005 ASA PILM, NEGHT MUSSIONS
- DEVELOPMENT OPERATIONAL ORGUND TRUTH TEARS (AS DISTINCT FROM RESEARCL4)
- · AUTOMATED PROCESSING OF DATA
- · ADDITIONAL SENSORS ABDITIONAL WAVELENGTHS
- · PERIODIC INFETINGS INSTRUMENT, MER ? CAMS
- · BORESIGNT CAREER FOR AUCDOWAVE RADIOMETERS

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NABA-8-69-5798

- SUPPORTING EQUIPMENT @ P1010
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CALIBRATION SITE ACTIVITIES

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-5	LOGISTICS AND PLANNERS
-4	ON-SITE BESEADCH AND PLANNING
-8	
-2	OPERATIONS MANUAL TO MSC GIA-SITE RESEARCH CONTINUES
-1	
-1/2	OPERATIONS TAAM TO FEST SHIS
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+1	GATA AVAILAGLE FOE PROCESSING CANCE LOGE REPORT
+2	DATA REDUCTION AND AMALVERS
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Presentation by Jules Friedman, USOB

(Text not available for printing in final document)

Ground Truth Measurements to Support Redar Stuffes

Dr. D. S. Simonett University of Kassas

Introduction

The atmosphere is not a preseing problem in the collection of radar data as it is with other sensors. Air temperature is unimportant, so are ground temperatures except then dealing with frozen ground, enow and ice, for which object temperature measurements need to be obtained. Atmospheric particles (dust, water vapor, etc.) including clouds have virtually no effect, nor is the level of natural background radiation of significance.

However, with X-band radar (wavelengths of about 3 cm) light to moderate rainfall of the order of .2 cm per hour will produce attenuation in the range 1 to 3 db which is of the order of the inherent uncertainty even in fully calibrated systems. Finally, interference from ground and airborne recars and some UHF and VHF systems may occur. Thus, with the exception of chance occurrences of interference and for the relatively rare occusions when reinfall rates exceed approximately 3 db attenuation, ground truth observations regarding the weather may be confined to brief visual reports of conditions. Data on attenuation by rainfall may be obtained from Moore and Simonett (1967).

In evaluating multifrequency, polypolarised radar it is essential that both exarefully-controlled ground sites and extended sites be available. Detailed measurements have been made by Congriff, Feske and Taylor (1960) and Feske, Rieglar, and Schults (1966) using truck-mounted radar equipment. These and similar studies by Lundien (1965) and others at the U.S. Waterways Experiment Station, Vicksburg, Mississippi, are among the most carefully controlled studies concerning radar return from crops and others at the U.S. Waterways Experiment station, Wicksburg, Mississippi, are among the most carefully controlled studies concerning radar return from crops and other materials. However, these measurements are essentially microscale, the illuminated area being only about a foot square. Hence they are not necessarily representative of data obtained from aircraft or orbital radars of very different resolutions. Present studies at selected test sites attempt to scheve comparable results, but on a marro or aircraft scale, by considering the nature of the radar return is relatively large areas as obtained with aircraft radars. As an example, the ground truth data collected at Garden City, Eansas (MASA-esSC fest Site Ho. 76) may briefly be described through the factors which gost influence the radar returns:

1. Surface roughness to the order of 1/10 of the radar wavelength

2. Geometry of the surface of the objects illuminated

3. Dielectric properties, including conductivity, permitivity, and resistivity of the illuminated surface

4. Polarisation characteristics of the surface

5. Redar incidence angle on the surface being illuminated (for this factor, it is very important to acquire boresighted oblique and/or vertical

serial photograph concurrently with the radar data)

Surfaces with a roughness less than 1/10 of the redar wavelength generally appear smooth (dark areas on positive imagery) to that wavelength, However, such surfaces are relatively rare for most redar frequencies, being represented only by placid water or smooth highways. In an area of gentle slopes (as at the agricultural test site at Garden City), we may anticipate that the soil surface and plant geometry will contribute substantially to differences in redar return.

82

Cther factors affecting redar return, such as surface penetration and radar polarisation are not yet fully understood and are contributing factors not easily identified. Relatively little soil-surface penetration is achieved with high frequency radar such as K-band radar.

Variation in the electrical properties of imaged objects such as dialectric constant, conductivity, sto., will also affect the return signal strength. Although a smooth water surface tends to set us a specular reflector, returning little energy to the antenna, rougher land areas which are moist (such as soils which have been recently setted by irrigation) may provide a stronger return than adjacent dry soils if all other things are unchanged. This stronger return is theoretically stributable to differences in dielectric properties, arising from the smoothing of the surface which accompanies irrigation may actually lower the radar return. Consequently ground condition should also be monitored.

Radar signal incidence angle and look-direction are other variables influencing radar return. More experiments are needed to accurately describe their influence.

Ground Truth Measurements to Support Reder/Asriculture Studies - Measurements on a large scale of micro-roughness, crop geometry, and dislectric constant in agricultural crops are infessible in our present state of understanding. It is necessary, therefore, to select measures which are both related to or are partial surrogates for the actual parameters which influence the reder return and would be relatively simple to obtain in the field at the time of a radar overflight. For example:

1. Crop type, height, moisture content, and stage of growth.

2. Moisture content of the soil at several depths.

3. Method of land preparations, including cloddiness, row directions, etc.

4. Percent of ground covered by regetation, measured at the radar incidence angle.

The relative importance of each of the selected parameters may then be statistically determined through an analysis of co-variance.

To simplify the analysis of the effect of only these selected variables on radar return signal strength, it has been desirable to reduce certain unnecessarily complicating factors for the early studies. This has been accomplished by selection of a test site which minimized soil type differences and effects of slope, and maximizes the range of other variables. Such is the case of the agricultural test site at Garden City, Mansas. In this area there are over 400 fields for which data are collected at the time of radar overflights. The area was chosen because fields are generally large, alops are extramely gentle, soils are uniform, both dryland and irrigated cropping is practiced, and there is some diversity of erop types, agricultural testniques, and moleture conditions.

Other sites chosen by the university of Mansas to provide additional environmental data include (all data collected by CHES personnel):

1. Horsefly Mountain, Oregon (HASA-MSC Test Site No. 159) - This test site chosen in order to examine forestry and natural vegetation conditions. Landform (geomorphic) enalysis also important.

2. Learence, Mansas (MASA-MSC Test Site No. 85) - Chosen because of its proximity to the University of Mansas. This site includes examination of urban and rural settlement patterns, agricultural, and broadlaaf woodland conditions. A geology subsite is located near Learence. The geology subsite has been mapped in detail by the Mansas Geological Survey both for the geology and for various environmental factors (soils, vegetation, land-use, sto.)

3. Wichita, Kansas Soil Strip (MASA-MSC Test Site No. 35) - Chosen because it is an area of diverse soil types and is covered with a number of recent soil surveys.

Ground truth of these sites consists simply of documenting the cultural and natural land-use patterns. In some cases radar corner reflectors would be valuable as markers to establish key locations, and in uniquely flat areas or recently ploughed fields storeo ground photographs or microrelief profiles may be obtained (the latter with a simple profile sampler).

Ground truth currently collected at Garden City, Kensas (MASA-MSC Test Site No. 76) by CRES personnel:

1. Maps of field boundaries have been made from ASCS 1:20,000 scale sarial photos. These field maps have been checked in the field and modified to fit current conditions.

2. All field data is plotted on the field maps.

a. All field data is collected on either side of three H-S county roads located one sile apart. The length of each of the three test strips is 16 miles. An additional flight line is located diagonal

to the M-S roads. A short flight line located over the usin runnary of the Garden City, Kenses Municipal Airport provides calibration data for the scatterometer.

b. Grop type is recorded; its height measured and noted. The height recorded is an average of at least three independent measurements recorded at least to feet from the adjacent reachesy.

c. Percent ground covered by vegetation is estimated and noted. Visual estimation of percent ground coverage is based on previous studies which involved taking 35mm ground photography of crops in each field during several MASA sponsored side-looking radar (SLR) missions. During these missions, ground photographs were taken of the crop in each field with the camera elevated about twelve feet and aimed at the same angle as the mean incident radar beem. A grid was then placed over the resultant enlarged photography and percent of ground covered was calculated. After a large file of photographs representing small incremental steps in percent cover of various crops was obtained, the photographs were taken into the field during later missions and estimates accurate to a few percent could readily be made.

d. Average crop moisture percent is calculated for the crop in each field. The procedure for obtaining this information is as follows:

(1) Sorghum: Ten or more leaves randomly selected from several plants are taken, along with a sorghum head and portion of a stalk. All samples are placed in a single plastic bag and scaled, and the sample location noted.

(2) Corn: The sampling procedure is similar to that of sorghum - ears and tassels are sampled if the crop is at that stage of growth.

(3) Sugar Bests: This plant is essentially leaf and root. Samples of ten or more leaves in the early stages of growth, and five or six at maturity are randomly taken and included as one sample for that field. The samples are sealed in a plastic bag.

(4) Wheat, Sudengruss and Alfalfa: Approximately ten random cuttings of these are taken. If wheat and Sudangrass are headed, several heads are included with the stalks. All are sealed in a plastic bag.

(5) Pasture, stubble, or weeds: Representative samples of the vegetative cover was taken for each field and included as a single sample of that field.

e. All semples are collected at least 60 fest into the field to eliminate axtraneous effects on the field margins or near the road. If fields of crops are at least 33% weeky, representative samples of the weeds are collected and included in the crop sample. The percent of moisture in each sample is calculated at the Kansas State University Agricultural Experiment Station at Garden City by oven-drying the samples and using the following formula to obtain a percentage:

wet weight - dry weight x 100 = MS

f. Soil samples are taken of nearly all bare fields and in most fields under the crops. Stendard soil sampling cans are filled, not packed, with soil taken at the surface (0 to 3 1/2 inches). To date, only the higher frequency redar systems have successfully acquired data at Garden City and relatively little soil-surface penetration is achieved, hence, moisture data has been limited to the range C in. to about 3 1/2 inches. However, when longer wavelength systems successfully acquirs data at Gardan City, it is anticipated that soil moisture data will be acquired at three-inch increments up to 12 1/2 Anches.

Oven dry weight was determined by placing the soil samples in an oven at a temperature of 105°C until they lost no more water. A volumetric technique is used to establish a measure of soil moisture, since a value obtained from percent by weight varies as the bulk density of the soil varies. The volume of the cans used are 475 cc, and the formula for computing the volumetric measures of percent moisture is:

wet weight - dry weight x 100 = 1875 175 ec

g. Additional field data are noted such as:

Stage of crop growth (maturity)

Stage of crop growth (maturity)
 State of the crop (parched, diseased, weedy, well-

cultivated, etc.) (3) Irrigated or non-irrigated (with approximate irrigation

date of recently-irrigated fields)

 (4) Crop row direction
 (5) Other significant lineations
 (6) Cloidiness of the surface, estimated and photographed for establishing subsets of closdiness.

Ground Truth Measurements to Support Redar Geologic Studies

Innormaphic Characteristics - Gross Topography - Existing contour maps with a 10-foot contour interval are normally adequate for this purpose. & 20-fost contour interval is baraly acceptable.

Surface Roughness - In general, average roughness less than A/10 (1/10 wavelength) is not significant in affecting the radar roturn. Reughness greater than this affects the southaring of the transmitted pulse and hence the magnitude of the return signal, depending on the degree of organisation of this roughness.

The radar wavelengths which are being or will be used in our studies are given below.

Wright-Patterson		λ	2/10
(Avionics Aircraft)	35,000mc	8.6800	lnun)
	(8,910mc	3.4cm	3mm
Naval Research	4,450mc	6.7cm	1cm > Radar Imagers
Laboratory	1,225mc	24 cm	2011
	428mc	70 cm	7cm
NASA-MSC	16,500mc	.18cm	JIcm
NASA-MSC	400mc	75 cm	7.5cm - Radar Scatterometer

Extremely rough surfaces, presenting many faces to the transmitted pulse within the confines of a single range resolution patch, act in some degree (weak or strong) as Lambert Law scatterers. However, to our knowledge, only dense evergreen forests act as strong Lambert Law scatterers, though gravel bajadas and as lava at Pisgah Crater, California approach this. Most surfaces, it will be appreciated, are essentially rough surfaces for the short-wavelength systems. Even a pond lightly stirred by the breeze is rough. An absolutely still pond at dawn may be smooth enough to be a specular reflector to all frequencies normally in use.

<u>Requirements</u> - In areas which are totally or almost completely vegetation free, oblique and vertical ground storeo photographs should be obtained which indicate the nature of the micro-relief. Scales should be included on all photographs. In addition random microrelief profiles using a device comparable to that used by Dr. Timothy Whitten and associates or that by Dr. L. F. Dellwig of the University of Kansas should be used. The Dellwig device is designed so that microrelief at lem intervals may be obtained at a series of randomly designated sites on each lithology. The bases for randomization should follow standard statistical design, of the type employed by Dr. Timothy Whitten at Pisgah Crater.

The operation of the Profilometer is simple. It is loosened over the sample site. Thin metal rods drop and make contact with the ground. All are then clamped with butterfly nuts at both ends, laid flat on white paper and the ends lightly sprayed with spray paint to give a microrelief shadow. The shadow is then a permanent record of the microrelief at the given site.

Profilometers may be made also with 0.5cm centers as well as 1.0cm centers for the thin (1.5mm diameter) rode. Our present Profilometer is on 1cm centers. Our next one would be on 0.5cm centers and we recommend the closer spacing as giving a better control on microrelief.

The micro-roughness problem is exceedingly difficult to handle in the field. Our solution, of using stereo ground photographs (with scale), together with the Profilometer, falls far short of the requirements for proper theoretical treatment of the data. It is a counsel of desperation, not the ideal. However, we cannot ask geologists to obtain measurements of microreliaf accurate to lumm on X-X-Z coordinates over distances of matters in the field.

Ground vertical and ground oblique photographs should be taken where any vegetation occurs so that an estimate of the total percent of ground cover may be made. Oblique photographs should be taken at an angle of 45° if possible as in the photography below. Color slides or Polaroids are appropriate to accompany black and white (35mm). It is most important that a copy of the best available recent air photos accompany the geologic map whon sent to other investigators.

<u>Structural Characteristics</u> - A geologic map with structural symbols is essential background information as are geologic cross-sections. Sub-surface contour maps as a geologist ordinarily thinks of them are unnecessary, though materials very shallowly buried (a foot or so) may be sampled by shallow augering. If isopach maps are required by other investigators we would not ignore them, for we can make use of them. More desirable would be a measured section. Since much of our interpretation will hings on the quality of the geologic mapping and reporting.

<u>Meathered Layer (Overburden) Characteristics</u> - It is appropriate to delineate the thickness and extent of an overburden and to note the composition of soil types found in an area as part of the normal routine of geologic mapping. No special effort at accurate measurements of depths, etc., need to made.

If field study coincides with the time of a radar flight, the moisture content in the surface half-inch and the layer 3 to 3 1/2 inches from the surface should be determined on a percent by <u>VOLIME</u> (NOT by weight) has at least in random triplicate for each soil type. If no radar flight occurs this information may be ignored. Where information is available on the clay minerology this will be valuable but is not essential. The texture of the soil as given by percent sand, ailt and clay would be desirable but is not vital. A normal soil field texture determination (e.g. silty clay loam) is adequate. The direction and angle of slope at any point sampled should be noted together with notes on superficial coverings of alian material (i.e., sand etc.).

<u>Redrologic Characteristics</u> - If data is collected at the time of a radar flight the presence and depth of dry or wet snow should be noted. The temperture of the snow at the time of the study should be obtained. (Radar penetrates dry grow very well.)

<u>Veretation</u> - The type, size, life-form, height, and life-stage should be noted even when veretation is very sparse. Even our so-called lumar analogs on earth are by no means veretation free. With high resolution

some of the effects of vegetation can be filtered out, but inspection of ground photographs of Pisgah Crater, for example, shows small vegetation of sprawling habit which will be included willy-nilly with rocks with most sensors, including radar.

Lithologic Characteristics - <u>Physical uncertiss</u> - Notes on the density, porosity, permeability and texture, and preferred orientation of grains, jointing, shattering, are apyropriate. If the rocks are free of vegetation and the overburden is less than 6 inches thick, a full megascopic description should be made. It is assumed that a suite of rocks will be collected for later study, and that detailed laboratory study will be collected for later study, and that detailed laboratory study will be collected for later study.

Some of the radar systems we are studying have the property of recording polarized and cross-polarized return signals. Polarization and crosspolarization may be sensitive to anistropy in minerals, layering in rooks, alikensliding, etc., as well as being sensitive to the direction of a dielectric slab (such as trees versus a sprawling crop).

<u>Dielectric Properties</u> - Permittivity and conductivity both affect the radar return signal. Permittivity is dependent at least in part on transmitted wavelength and strongly influences the reflecting properties of a surface in the wavelengths we are using. Conductivity in these same frequencies affects mostly attenuation of the signal.

Permittivity and conductivity are closely related to the contained water content of rocks and their mineralogy. Published values of the dislectric for rocks indicate much overlap within the igneous and metemorphic groups and even some sedimentaries overlap the former in value.

However, as a general rule sedimentary rocks have higher conductivity than low-water igneous types, usually well outside the extreme range of the latter. It is worth noting also, that much of the variation is dielectric within a single igneous rock type probably relates substantially to slight variations in contained (including telluric) water.

In short, differences in dielectric properties are not likely to be a reasonable basis for specifically distinguishing between say, as or pabechoe laves with redar. Their variations may be significant at some wavelengths.

If data is being collected at the time of a radar flight it would be appropriate for field geologists to obtain in triplicate on each likelogy some conductivity measurements for the surface rock or soil, following a standard procedure. At other times judgement should be used. At Fisgah Crater, for example, to determine conductivity soon after a rain would be a waste of time.

Permittivity cannot reasonably be determined in the field and is emceedingly difficult on soils. Consequently only solid rock samples $6^{n} \ge 2^{n} \ge 2^{n}$ should be collected and packed in plastic bags in air-tight metal boxes for laboratory dielectric measurements.

Laboratory dielectric measurements are not made as a routine service (with appropriate fee) by any individual or agency as yet.

Refiguitive Characteristics - Albedo - We would like information on albedo in all wavelengths available as a function of angle of incidence. This information is not a significant parameter in evaluation of the radar per ss, but because we wish to build up data on the relations between albedo and redar return for experience in working with comparable lumar relations.

Ground Truth for Scatterometer/Sea State Experiments - Recently NASA-MSC Mission 60 was flown off southern Newfoundiand to gather 13.3 GHs scatterometer/sea-state data. Prior to the mission, a meeting was held at MSC to establish among other things what kind of ground truth measurements are required for this kind of experiment. At the meeting it was decided that the method of wave and wind speed and direction hindcasting employed by Dr. Willard Pierson of New York University is appropriate for ground truth at a wave study site. "Hindcasting" gives estimates of wave height of the desired accuracy and repeatibility for scatterometer/seastate experiments. However, adequate hindcasting depends on inputs from many vessels at sea.

Suggested alternatives for the inputs are:

1. Mave staff measurements such as those at Argus Island, Bermuda. The wave staff could be of the continual recording type or visual observations could be noted during the time of a mission.

2. Shipborne wave height recordings either of the continual recording variety or by a trained observer. Ship location would be preferably at end of flight line but if not feasible, somewhere along the wind fetch.

3. Airborne profiles such as that currently mounted in a Navy ASMEPS aircraft. Profiler equipped aircraft should fly side-by-side with the RASA-MSC remote sensor aircraft. Ideal situation would be to have a profiler mounted in the RASA-MSC P3 aircraft along with the 13.3 GHz and .4 GHz scatterometers. Frequency of the profiler must be different than that of the scatterometers. Frequency of the profiler must be different than that of the scatterometers as not to create RFI (interference). Profilers cannot be used at the low altitudes needed to obtain the wave spectrum for high winds and seas, because of safety considerations.

The acquisition of single camera starso photography for ground truth purposes appears to be infeasible for the following reasons:

1. Since the ocean is continually moving the maximum cycle times for stareo photography would need to be on the order of 4 seconds (i.e., it takes approximately 4 seconds for a wave to form and break so that two stereo photos taken more than 3 or 4 seconds apart would not indicate

the true geometries of the waves). For an ordinary metric mapping camera with a 6-inch lens and 60% overlap, cycle times on this order of magnitude would be most difficult to achieve unless the aircraft flew at very low altitudes (approximately 1000 feet). At this low altitude in high winds and seas the scatterometer data is degraded and severe turbulence would partially or fully exceed the stabilization limits of the camera system; hence, distortion problems. Such distortions are expansive to remove during photogrammetric processing, but the resulting processed photography is of questionable value without it. Then there would be the question of time and money involved with transforming and stereo plotting a large mass of stereo photo data, almost regardless of altitude.

Another factor should be considered in regard to stereo photo acquisition. Scatterometer/see-state data acquisition experiments are designed to fly at the highest altitudes practical for the aircraft involved in order to average over a large enough area to encompass the full spectrum of the waves. This means aircraft altitudes, according to present MSC aircraft car ilities, in the renge 12,000 - 35,000 feet. At these altitudes it is almost certain that undercast conditions would prohibit acquisition of stree-photography. And the cycle rates are prohibitive.

Bi-static or side-lap stereo photos in which two aircraft, each carrying a single mapping camera and flying side-by-side could provide the necessary stereo photos. The ramifications of mission planning in this regard are almost without end.

In summary, there is no single simple accurate solution to obtaining ground truth for the wave spectrum of the ocean. Any decision is a compromise and the location of the site in relation to available ASMEPS and NASA aircraft, shipping lanes and so on are factors to be considered.

Ground Truth for Sea or Lake Ice Studies - The following data is required to support either imaging or scatterometer studies:

- 1. Vertical pan minus blue air photography, 60% and lap
- 2. Ice and snow temperature measurements at several depths (surface, 1 foot, 2 fest, etc.)
- 3. Ice and snow contained moisture measurements at same depths
- 4. Borings to determine depth of ice and snew. For scatterometer studies at least three borings should be made in each ice type studied, preferably up to 10 borings in each ice type.

Ground Truth for Snew Depth Studies with Radar - The following data is required to support snow depth and moisture content studies with multi-frequency multipolarization radar scatterometer and imaging systems:

- 1. Vertical pan minus blue air photography, 60% end lap
- Snow moisture content temperature, and depth measurements at depths of 0", 6", 12", 18", 24", 36", 48", 60" etc.
- 3. Where feasible multi-frequency transponder systems may be employed in some cases at remote sites. However, such a system is warranted only for experimental evaluation of snow depth penetration.

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Oceanographic Ground Truth Bacuirments H. J. Yotho and J. B. Zeitseff Spacecraft Oceanography Project U.S. Mayal Oceanographic Office

92

This report discusses the status and requirements for oceanographic test sites involved in the Spacecraft Oceanographic Project, United States Oceanographic Office.

In consonance with the MASA Earth Resources Survey Program Plan, a series of experiments are being conducted exploying various remote sensors. The current effort of the Spacecraft Oceanography Project under the MASA Program is directed toward program and instrument definition and the use of aircraft for determining sensor feasibility and instrument development and also spacecraft experiments leading to eventual operational systems in earth orbit.

The Earth Resources Survey Program is utilizing a number of test sites as a means of calibrating sensors and providing "ground truth" for assessment of airborne or spacecraft bensors. Matters pertaining to test sites are governed by the Test Site and Aircraft Committee of the Natural Resources Program.

Several test sites have been selected for oceanographic purposes. The general locations of these sites are shown in Figure 1. The selection of sites has been based on oceanographic phenomenon desired to be measured and the availability of the critical requirements needed to provide adequate ground truth data. The oceanographic test sites are catagorised as: (1) calibration sites, (2) overflight sites, (3) special purpose sites.

(1) Calibration Sites - Sites with climatic/historical oceanographic data available. These sites are instrumented and manued to provide correlative environmental ground truth. They provide multi-purpose environmental sensor test facilities.

Three calibration test sites have been selected by the Haval Oceanographic Office (HAVOCEAND) for their diversity of oceanographic properties, which are considered suitable for evaluating the various airborne sensors under know surface conditions. These sites are: (a) Argus Island (Bersuda), (b) Foint Barrow (Alaska), and (c) Scripps Area (Southern California). It is intended that calibration site overflights will help evaluate the aircroft remote sensors under known anvironmental conditions and not just to gather large amount of oceanographic data.

(2) Overflight Sites - Sites containing one or more special oceanographic features. Surface data will be obtained on an opportunity basis. Some historical/climatic data of atlas type are available. A larger number of oceanographic overflight sites have been selected by MAYOCEANO to extend the sensor feasibility investigations to a greater variety of oceanographic conditions. Overflight sites selected to date are: (a) Goose Bay (Labrador), (b) Columbia River Month (Oregon), (c) Mississippi Delta Negion (Louisiana). (d) Florida Straits (Florida), (e) Navy Acre (310-32% and 710-72%), (f) Oulf Stream (off Hows Scotia), (g) Grand Banks (off Hewfoundland), and (h) Baffin Bay (west of Greenland). For the overflight sites, surface data could it is arranged with oceanographic ships-of-opportunity operating in the area and capable of bing correlated with the planned airwarkt or spacecareft overflight.

(3) Special Purpose Sites - Sites which contain one particular feature, usually in a remote area.

The availability of concurrent surface data is improbable over the Special Furpose Sites, and interpretative techniques are the primary means of evaluating the data. Little or no historical/climatic data is available. These sites are selected as required or determined as the opportunity arises to coordinate aircraft flights over particular dynamic oceanographic features such as various sea state conditions.

Because of the necessary requirement of relating surface parameters to remote sensor "signatures" calibration site functions will be the basic content of this report.

The surface equipment recommended for support of various areas of investigation is outlined in Table 1 for each of the Calibration Sites. Calibration Site descriptions, functions, and requirements are discussed below.

Site Descriptions

<u>Argus Island (Bernuda)</u> - Argus Island is a Texas tower-type structure. The tower is located approximately 22 miles southwest of Bernuda stop Plantagent Bark, which is a large sea mount to the southwest of the Bernuda Islands. This comemographic platform has been used by the U.S. Karal Oceanographic Office since late 1961 for data collection and instrumentation development purposes.

An area around the tower has been designated as one of the fundamental test sites for testing remote sensing instruments for the purpose of determining their applicability in measuring and investigating gross cosenographic parameters from overflying aircraft. The purpose which have been and can be investigated at Argus Island are those which are directly or indirectly related to the following areas of interest:

- 1. Sea state
- 2. Surface temperature
- 3. Volcanic activity
- 4. Air-ses interaction

Because of the water depths present, deep water wave calibrations can be performed at Argus Island with comparative case. Considerable wave anight/ tidal/power spectrum data has been collected at this site. The site, housever,

lacks for the most part, the wide variety of sea-state conditions desired for a more extensive sensor evaluation such as might be obtained over the rougher Borth Atlantic waters. The Argus Island site provides secstate conditions, primarily scalls, ranging from low to moderate. The site also offers suitable temperature variations for calibration as the waters pass scores the sheals. The desper colder waters, during such passage, are forced up and mix across the bank to present a cold area anomaly ideal for surface temperature calibrations. The utility of the site for investigation of volcanic activity by the remote sensor is questionable. The area has been quiescent for a long period of time and both temperature anomalies and out-gassing traces are not anticipated for future calibration overflights.

Argue Island Instrumentation

The types of equipment currently available and utilized at Argus Telend for purposes of the remote sensor caliburation programs are outlined bolow.

1091	**************************************	
1.	Wave staff	Veres
2.	Appareter	Wind speed and direction
3.	Thermistor	Sea and air temperature
4.	Tide gauge	Tides
5.	Current meter	Current speed
6.	Current direction sensor	Current direction
7.	Epploy Pyrheliometere	Solar rediation
8.	Thornthwaite net	
	radicator	Net total rediction
9.	Data acquisition system	-
10.	Hurricane recording	•
	system	-

In addition to the above principal instruments, the site can provide: (a) a gravity meter, (b) depth sounder, (c) busy markers, and (d) dys markers. A significant addition to the listed equipments is a flux meter which can make measurements to determine the exchange of energy between the air and sea due to windfields. Coordination between ground and aircraft personnel is provided by a ground-air radio communication system at the Tower.

The following are data presently svailable at Argos Island:

- 1. Mave beight measurements
- 2. Current measurements
- 3. Tidal repres
- 4. Wind speed and direction
- 5. See and air temperatures
- 6. Solar redistion
- 7. Magnetic intensity

Pt. Barrow. Alagha - This site offers an optimum location for the calibration study of mirborne instrumentation directed toward sensing and mapping sen-ice distributions and associated surface characteristics. In addition to the wide variety of ice/sater/snow land interfaces, that are present in this area, considerable scientific/technical/labor perconcel as well as facilities are provided by the Arctic Research Laboratory (AHL) under contract with the Office of Haval Research (CEH).

Two general areas of investigation are considered at this site. These are:

1. Les <u>Hamping and Thickness Measurements</u> - The geographical areas established for these investigations incluis (a) the off-ohore area about the Laboratory which is located at 71° 20' H Lat., and 156° 46' W. Long., (b) a marrow strip of 30-60 miles long from Pt. Harrow at a course of 045° true, (c) an equivalent strip at 315° true, and (d) the floating ice-ialand, T-3 (Fletcher's Island).

2. <u>Thornal Mapping and Land/Mater/Ics/Boow Interface Studies</u> -The geographical areas established for these investigations include (a) and (b) above.

<u>Basearch Facilities</u> - Scientific, technological, and labor support for Arctic research is provided by ARL. The Laboratory is located about four miles north of Barrow, Alaska, and about six miles south of Pt. Barrow,

The principal role of ARL is to provide all facilities and services for research in scientific fields related to the Arctic environment. This includes both support of laboratory studies per so and logistic services to field parties.

At sea, ARL operates one major drifting research station; Fistchar's Ice Island, or T-3. On the island are emplaced semi-permanent, well-equipped Isboratory and housing facilities, and an airstrip, upon which landings may be made year-around, weather permitting. The station is manned continuously.

Soripus Area - This Southern California site offers a large variety of occomographic conditions, facilities, and favorable weather conditions for evaluating the airborns (and spaceborns) remote consore.

The calibration site encoupasses an extended area which includes specific locations for site calibration efforts. The calibration areas that are included in this site area

a. The near-shore area extending northward some ten miles or so parallel to the coartiline from the Eaval Kleutronics Laboratory Tower off Mission Beach to the Scrippe Beach area north of Pt. LaJolla. This includes both shallow and fairly deep vaters. The following experimental areas are applicable to this area;

- 1. Surface Temperature Measurement
- 2. Location and Mapping of Longshore Currents
- 7. Shoreline and Beach Studies
- 4. Bottom Detection by Wave Refraction and Color Tones
- 5. Laser Altimetry Calibration

b. An area which is some 30-100 miles off-shore, lying east of San Clements Island and south of Santa Catalina Island. This area is suitable study in the following areas:

> 1. Surface Temperature Measurement Involving the Japan Current 2. Biological Studies

The off-shore waters and coastal beaches of this area have been the object of intensive research for fifty years. The Boripps Institution maintains continuous observations of many types, including tides, water temperatures, salinity, and weather, and has the capacity to undertake comprehensive inshore and beach surveys when desirable.

The site is optimumally situated to provide the maximum control (ground truth) in oceanographic and littoral processes. The large scale features, as coastal embayments and a baseliand such as Pt. LaJolla might provide readily identifiable landmarks at orbital altitudes.

The Scripps area site offers a large number of facilities for the acquisition of ground truth data, including the Oceanographic Data Archive (approximately 500,000 BT observations), a 1000' x 20' pier, a number of research vessels, and smaller boats.

Some of the significant data available at this site are the following:

Scripps Pier

Tidal variations Temperature surface bottom bathythermograph dual-wavelength IR radiometry (3.5 - 4.5 microns; 2.0 - 2.4 microns) Selinity surface bottom Air temperature Wet and dry bulb thermometer readings Maximum and minimum daily temperature readings Wind velocity and direction Multiple bathythermograph readings Continuous wave recording for short periods of time Inshore bathametry and beach surveys

Nevy Electronics Laboratory Oceanographic ; over

Wind direction and velocity Water temperature surface bottom hathythermograph Mater acoustical properties Tide measurements

For the deeper water areas off San Clemente, the research vessel facilities are exemplified by the Ellen B. Scripps. Some of the equipment onboard for ground truth measurements include:

> Hytech. STD 8-1? micro: radiometer on prow of boat Single element towed thermistor Anemometer Physchrometer Ship-air communications (4415.8 kc)

Site Recuircants

Argus Island Site

Sea State Measurement - The primary surface measurements required for sea state measurement are wave height and tidal range measurements, wind speed and direction, surface photography and surface current flow.

The wave height and tidal range measurements at the surface can be satisfactorily made by instruments available at the site with the possible exception of a small radar to perform scatterometry measurements, albeit at low gasing angles.

The Navy boat (MAC III), manned by technicians, is available to obtain data over any greater area or deeper waters near the site; it is noted that a ahipboard wave staff can be available which has an accuracy of about \pm 6 inches; the method of adequately recording data from this mobile installation mede further determination.

The anemometer installation at the Tower is sufficient for wind and direction measurement. In anticipation of future requests by investigators for a more extensive gathering of local wind data, several secondary sources of meteorological data can be made available. First, data from the weather station at Kinley AFB can be obtained despite the relatively long distance from Argus (approximately 40 miles). Second, a shipboard mount on the MAC III can be used to make measurements about the Taland; this requires procurement of a portable anemometer for shipboard use. Third, a sparse array of moored, talemestering buoys could perform such measurement at, say, three to five different locations about the site waters with recording completed at the Tower.

Some form of surface-based photography is possible to correlate with the airborne sensors. A 35mm motion or small, hand-held framing camera, while deemed to have a medium significance factor in this calibration, could provide imagery to supplement the visual observations expected to be recorded in the surface logbook which should be maintained throughout the calibration effort.

The measurement of surface current flow is included, primarily because of its availability at the site, but its value to the sea-state calibration remains to be clearly determined.

Surface Temperature Measurements - Argus Island offers some useful surface temperature distributions for calibration and evaluation for some of the remote sensors considered by the Project. Surface measurement requirements include reflectivity and emissivity, wind speed and direction measurements, surface temperature, current speed and direction, air temperature and relative humidity measurements.

The surface calibration measurements emphasize obtaining atmospheric conditions. Air temperature and humidity measurements at low level can be adequately handled by the equipment installed at the Tower; this can be supplemented by data taken by the weather station at Kinley AFB, some 40 miles away. In addition, a hygrometer is available onboard the MASA P3A which, by making level runs at various fixed altitudes supplies varical distribution data on air temperature, water vapor and liquid moisture content. The Manned Spacecraft Center at Houston (per L. Childs/H. Toy) may be able to offer the use of radiosondes dropped from the P3A. Two types are being investigated: (a) a small radiosonde which provides temperature profiles by telemetry to the aircraft and (b) a larger radiosonde which telemeters both temperature and pressure during descent and after surface contact releases a thermistor giving water temperature data that is telemetered.

A significant calibration measurement that is extremely complex is that of emissivity/reflectivity of the perturbed ocean surfaces, as it applies to both the remote sensing infrared and passive microwave equipments. The smooth surface case which can be more easily handled is not too informative. For this reason, a broad band IR radiometer with appropriate filters mounted on the Tower is suggested as a useful piece of surface equipment which may be utilized. An equivalent Tower mount of a passive microwave radiometer should be noted that at the short ranges involved, the errors introduced by slide-lobes may be extremely troublesome in data interpretation.

An interesting surface technique for helping evaluate passive microwave equipments would utilize some floating reflector sheets on relatively smooth water. The metal reflector with its microwave emissivity close to zero essentially masks any thermal contribution beneath it and the observed anomaly may serve as a cold landmark calibration reference during overflight. At 1000-foot altitudes, the airborne passive microwave equipments can resolve less than a 17-foot patch. This technique does not lend itself to source depth measurement because of the small penetration at the X and K bands involved.

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With the use of the N&C III (and a technician), surface temperature measuremants away from the Tower and especially over the shoal where the deeper colder waters come up and mix can be made; a simple resistance or expansion thermometer would be used. Additionally, the boat crew could use the buckst approach to obtain water samples which might show significant oil slick or other properties affecting emissivity/reflectivity interpretation.

<u>Air-Sea Interactions</u> - The study of air-sea interactions at Argus includes fog, clouds and water vapor distributions. Surface measurement requirements for this study are sea temperature profile measurements, air temperature and humidity profiles, wind speed and direction, current speed and direction, wave heights, solar influx measurements, IR surface temperatures, and surface volatiles.

Associated with surface measurements is the need for weather charts and other meteorological records to provide interfaces between the data collected and weather conditions over the larger entire area which preceded and followed each overflight period; hourly records of such data are indicated. It is noted that air-see interaction investigations, as in many of the others discussed in this report, require surface environmental information such as sea temperature profiles, near-surface air temperatures, current speeds, etc., which are amenable to common baoy mounts having distributions which allow a realistic description of the site areas. Since the Argue site is sufficiently small, the addition to this calibration site.

For the gathering of higher-level meteorological data it is recommended that the current MASA aircraft plans for implementing the P3A to drop radiosondes as previously mentioned be continued.

Point Barrow. Alaska

<u>Ice Mapping and Thickness Measurements</u> - In order to evaluate the airborne remote sensors for their capability in ice mapping and thickness measurement, a wedge-shaped area extending north of the Point and the ice-island T-3 is utilized for the variety of ice forms encountered there. This includes: (a) the shore-fast ice area in the vicinity of Pt. Barrow extending six to eight miles offshore, (b) an offshore polar-lice area on a course of 045 degrees true and 30-50 miles from the Point, and (c) an offshore, seasonalice area on a course of 315 degrees true and 30-60 miles from the Point, and (d) the thick floating, manned ice-island, T-3. Surface requirements measured for airborne remote sensor data evaluation are: physical and ohemical properties of snow and ice, ice and/or mow surface temperatures, ice and/or mow thicknesses, wind speed and direction, ice stress-strain measurements, ice ages, surface roughness, solar influx, air temperature, and relative humidity profile measurements.

Scripps Area

Surface Temperature Measurements - Surface temperature measurements for the Scripps area have been divided into two areas of operation. The most accessible area for surface measurements is a near-shore area extending some ten miles parallel to the coastline from the Naval Electronics Laboratory (NEL) Towar to the south at Mission Beach, up to and just north of Scripps Pier. Off-shore the strip will extend out to about 1-3 miles offering both a shallow and deep water facility including the sloping continental shalf, the Scripps Canyon and the San Diego Trough (approximately 6000 feet): the second area of interest lies southeast of San Clemente Island and includes those waters about 50-50 miles off-shore where Japan currents come in from the north creating eddy distributions that offer some realistic temperature patterns for adequate testing of spatial/temperature resolution of the airborne sensors. Research vessel facilities for obtaining ground truth data are available from the Scrippe Institution of Oceanography (SIO).

The near-shore area described previously can be adequately handled. The facilities at the NEL Tower and off of Scripps Pier will essentially satisfy requirements for ground truth acquisition. If measurements are to be expanded about these local points, a number of small motor craft (on the Pier) can be utilized using a hand-held or portable thermometer, psychrometer, anemometer or shipboard wave staff with a orew of two technicians. A dual-wavelength radiometer is also available at the Pier for making temperature gradient measurements at the surface. The latter requires a new detector system to improve its sensitivity.

The off-shore area southeast of San Clemente requires a ship operation. The SIO research vessel, such as the Ellen B. Scripps, can satisfactorily provide surface requirements.

Location and Maroing of Longehore Currents - This calibration effort can be suitably performed at the near shore strip between the NEL Tower and Scripps Beach area, extanding one to three miles off the shoreline. This area is easily accessible to instrumentation, especially for current measurement which is the most critical calibration involved in the surface effort.

Surface equipments, for surface requirements, i.e., current tracking, see temperature profiles, air temperature profiles, relative humidity, and wind speed and directions, are available through the Haval Electronics Laboratory and Scripps Institute of Oceanography. It is noted, however, that a careful review of available equipment is required concerning the accuracy of measuring alcely-moving longabors currents which are present at the site. Dye marking offers semi-quantitative data. J. Cairns (HEL) has suggested the floating crossed-wane drogue as an intermediary device subject to some improvement in accuracy; the crossed vanes present an almost uniform drag surface regardless of current direction. Motion with the current can be sensed at the aircraft by identifiable float markers above the water line, and observing the displacement with time, providing <u>yind</u> <u>effects</u> are minimised in the floation design. Selection of this or other

100

Since ice thicknesses vary considerably during the entire year, the "all weather" capability sensors can be effectively evaluated during all four seasons. On the other hand, because of the extensive fog conditions which are prevalent during the third quarter, airborne remote sensors as photographic, infrared, laser will be denied effective operation during this season.

Arctic operations pose a severe limitation on surface equipment requiremente because of logistics and extreme cold effects on components. For this reason, all surface equipments/techniques used for this calibration effort are primarily at Point Barrow. With some possible assistance from gathering higher-level meteorological data from the NASA P3A via hygrometer and the currently-planned radiosonde drops, a weather vane implant is also in area (b) above.

The off-shore areas, (b) and (c) above, offer a relatively simple means of performing mapping of ice movements. A large number of black. empty oil drums can be made available by the Arctic Research Laboratory (ARL-Under CHR Contract) for this purpose. These drums can be dropped from the ARL aircraft, on almost straight-line references along the 045 and 315 degree courses from 30 to 60 miles from the Point. These lines of drop will be approximately perpendicular to current flow for these floating-ice waters. Experience (per Max Brewer, Director of ARL) indicates that such markers have proven to be among the most effective for photographic or visual sensing at remote distances. Drops less than a mile spart will form an identifiable reference line whose distortion with time will relate to the ice movements in these areas. Emphasis is placed on the airborne panoramic camera(a) which should reveal ice movements (normal to the drop line) of 50-60 miles, under relatively clear atmospheric conditions. Stero photography also provides information on vertical displacement.

Thermal Mapping and Surface Interfaces - These investigations can be performed over two of the four areas used for ice-mapping/thickness measurements, using the immediate vicinity of Pt. Barrow, and the occupied ice island. T-3.

These two areas are able to provide adequate voice communications and homing beacons for control/navigation. In addition, NASA plans for dropping radiosondes might be modified to include telemetering temperature sensors that could be dropped onto ice floses or into open leads or polynas to provide extended temperature references for calibration, recorded onboard the aircraft. Both Barrow and T-3 facilities include the capability for such measurements which are very local in extent and recorded at these sites. The radiosonde technique can simultaneously provide air temperature profiles (and the very low humidities expected). The hyprometer onboard the F3A can also be used for this purpose by flying at a series of fixed altitudes; this instrument can also measure light water content.

available current-measuring techniques, i.e., Eulerian current meter, Roberts meter, hot-wire anemometer, etc., or a new development may have to be considered for this particular problem.

<u>Shoreline and Beach Studies</u> - The shoreline utilized for this investigation runs from the Mission Bay Split to the south up to the Torrey Pines-Del Mar Area. This provides a variety of coastline features of long, straight beaches, small pocket beaches, rocky coastlines and cliff structures.

Surface requirements for shoreline and beach studies include sample analysis (sand, rock, vegetation), water content of beach sands and rock units, sea state measurements, surface temperature mapping, offshore current measurements, and meteorological data. These requirements are adequately provided for by existing facilities at the Scripps Institute of Oceanography.

Bottom Detection by Wave Diffraction and Color Tones - This calibration affort can be suitably performed in the Scripps area over a longehore strip from the NEL Tower on the south to the Scripps Pier area on the north, extending off-shore some one to three miles. This beach area provides both shallow and deep waters in a relatively small area which is conveniently accessible to surface facilities and personnel.

Among the various surface measurement requirements for this investigation, the need for bottom contour data and optical-transparency of the sea water is paramount for this investigation. In view of the ongoing extensive efforts by such organizations as NEL, SIO, and the U.S. Coast and Geodetic Survey, the bottom contour problem is minimal. To supplement or verify the data which is already available, a portable meter-wheel fathometer, somer depth finder, or pressure gauge (Bourdon, Vibratron) can be manned from one of the boats available to make spot check measurements.

Underwater photometers and equipment necessary for the measurement of sea water transparency are available.

Equipment at the NEL Tower and Scripps Pier are adequate for collecting meteorological data during overflight periods. This can be supplemented for higher-altitude data by the PiA hygrometer and contemplated radiosonde drops from the NASA aircraft, or data procurable from North Island/Lindberg Airport Weather Stations.

<u>Biological Phenomena</u> - Calibration data related to remote sensing of biological phenomena in the Suripps area is best handled by a research vessel operation. The desired biological phenomena are not generally available close to the shore areas proposed for the other investigations at the Scripps site. Surface ship calibration afforts can be conducted in waters some 30-100 miles off-shore in the vicinity of the Santa Catalina-San Clemente Islands which offer considerable varieties of biological species, i.e., fish, plankton, etc.

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Biological surface measurement requirements include sits temperature measurements, transparency/luminescence observations, solar influx or sky record, bioluminescence measurements, atmospheric trace spectrometry determinations, chlorophyll concentrations, and population density measurements.

Most surface measurement requirements can be effected with the available instrumentation on the Scripps Institute of Oceanography vessel "Ellen B. Scripps" except for a photometer used for obtaining transparency/liminescence data, though can be obtained from SIO facilities under agreement with NAVOCENNO.

<u>Altimetry by Laser</u> - Estimated surface calibration requirements necessary to help evaluate laser altimetry for oceanographic purposes consist of altimetry calibration, penetration calibration, stability calibration, and accuracy calibration. The Scripps Beach area presents an adequate range of wave heights, period and direction approach, usually during October-February. Average breaker heights of about 5 feet are indicated in this period with occasional winter storms causing heights of 12 feet or more for short periods of time.

Critical areas in the calibration of the laser technique as applied to oceanography are (a) errors inherent in the technique due to penetration of the sea surface by the light beam with the resulting volume scatter at appreciable (order of feet) depth beneath the surface, and (b) errors in ranging that result from flight platform instabilities inammuch as beam widths of 10^{-4} to 10^{-5} radiens will be involved.

Absolute range calibration can be performed on the ground, using horizontal paths against target reflectors whose distances must be surveyed to an accuracy that is better than the projected for the laser (0.1 - 0.2 feet) against nonpenetrable surfaces. Having established the ranging accuracy by ground tests, one can now measure the degradation in accuracy using the aircraft platform at various altitudes, to examine the effects of known atmospheric paths and platform instabilities.

A wooden platform exposing 6 steps (5 x 20") to the laser beam can provide calibration data on the accuracy of contouring for an idealised non-penetrating surface. The actual step heights require accurate measurement to ± 0.25 ". The critical difficulty is in precise navigation over such a small target, approximately 30 by 20 feet, for the plot at a suggested altitude of 1000 feet. By orienting the conspicuous, white beaded-urethane painted steps so that the required ground track is parallel to the shoreline, a coarse visual navigation guide is conveniently provided. By adding a number of markers/lights along the desired track through the target, the desired precision can be obtained, especially after a few passes aided by communication from ground observers. If possible, provides. The overall bombeight would also be a significant aid in this problem. The overall technique has been favorably checked with several pilots.

A floating flat top barge (20 x 20") can provide a non-penetrable target whose small height (one foot) is accurately known above the penetrable water. Comparison of the altimetry data taken just before, during, and immediately following the target overpass should provide data on the errors introduced in altimetry over adjoining sea surfaces. Calm waters offer the least introduce tion of error in this measurement; the problem of foamy, aerated surfaces is questionable for the proposed technique.

For stability calibrations the use of the wooden steps previously mentioned can be utilized to make some determination of short-period instability (.12 second at 150 knot ground speed). By mounting a wide angle cammar (tilted down) above the step structure, a time exposure, should provide a track of the diffusely reflected beam as it moves arross the step structure. Appropriate filtering on the camera should allow the laser track emission to stand out against the background (moonlight reflection, beacon sources used for guidance, etc.). The proposed measurement is limited to a few samples of short-term beam deviations, but is easily implemented.

Summarized below are generalized measurements and equipments necessary for ground truth requirements at the oceanographic calibration and overflight sites.

MEASUREMENTS REQUIRED AND BEING MADE

The following lists those oceanographic variables which are measured at the surface to properly assess the feasibility of remote sensing for oceanography. Not all measurements are required for every experiment. Those measurements being made generally apply to the calibration site; the surface data for overflight sites depends on the type of surface or near-surface platform employed.

	OCEAN VARIABLES	MADE
1.	Sea Surface lemperature	Tes
2.	Surface Salinity	Tea
3.	Maya Height/Direction	Yes
i.	Current Sosed/Direction	Yea
5.	Water Depth (Shoal area)	Tes
6	Mater Clarity/Color	Yes
2	Water Samples (Sediments/Biological	
	content)	Yes
8	Air Towneystars	Yes
0	Wind mond/direction	Yes
10	Cloud cover	Tes
11	Moisture in Air Column	Scentimes
12	Persont Form/Suray	殿の
12.	Rollantiwity /helasivity	Bo
14	The manage of the granners time	No
1.00	Color modic bion	Yes
170	TR Measurement a	Tea
17.	Detection and Description Fish Schools	Yee

18.	Sam Ice Distribution	Yes
19.	Sea Ice Thickness	Sometimes
20.	Sea Ice Temperature	Sometimes
21.	Detail Sea Ice Topography Water	- Caller Caller
	Features	Sometimes

EQUIPMENT REQUIRED AND USED

DEOUTD-2D

As in the previous section, this listing is general and not specifically tied to any given experiment. Not all instruments are required for every experiment. Incofar as the use of ships and buoys is concerned, the requirement is for greater use specifically for remote sensor experiments. Except for a few cases, this has not been possible up to now because of the long lead-time required to program for ship time and the basic lack of funds to pay for this time and furnish the staff to obtain the required observations.

	REQUIRED	USICO
1.	Bucket thermometers/thermistors	Tes
2.	Water samplers	Yes
3.	Surface sailnograph	No
4.	Expendable BT	No
5.	IRT/ART	Yes/No
6.	Wave staff	Yes
7.	Current asters	Yes
8,	Met. Instruments (air temp, wind	
	speed/direction, humidity, etc.)	Yes
9.	Dropsondes or radiosondes	No
10.	Transmissometer	No
11.	Photo systems	No
12.	Buoys (moored, free floating, arctic)	Raraly
13.	Ships	Scmetines
14.	Small boats	Sometimen
15.	PDR	No
16.	Microwave (19 GHz, 6 GHz, etc.)	No
17.	Ice measuring equipmont	Partially
18.	Sonar	No
19.	Surface to air communications	Scentines

LETAILED RECOMMENDATIONS RELATIVE TO THE AIRCRAFT PROGRAM CONCERNING OCEAN TRUTH

<u>Comment</u> - Some of the concepts derived through the geological phase of the program do not lend wall to "ocean" truth. The "calibration site" concept, for example, does not apply. Fur, although permanently located and wall instrumented, the fact that the ocean is dynamic and variable weekons the reason for having a special static site where long term observations are obtained to "understand" the area. It is also difficult, if not impossible, to calect a permanent site and wait for all the ocean variables of interest to come by.

Recommendation - That specific sites not be designated, but that, within aircraft range constraints, test sites be selected where "the action is."

104

Recommendation - The program consider funding for aircraft time in cases where warranted.

<u>Comment</u> - Data for data's sake usually serves no purpose but to fill file drawers. Frequently, if not always, only very little data are required to advance feasibility studies, providing the data are of the type and quality required by the investigator. Often, massive amounts of data do more than fill massive numbers of file drawers; they may actually retard or detar effective analysis. These statements pertain to surface as well as aircraft and orbital data.

<u>Recommendation</u> - The specifications of the investigator should be understood and closely adhered to in acquiring aircraft, space and ocean truth data. On the other hand, Investigators must be required to define in better terms their environmental and sensor data requirements, and then maintain communications with the data collectors and even participate actively in the data collection process.

<u>Comment</u> - A wealth of ocean truth sites (platforms) are available through existing oceanographic programs. This generally entails going where the ships (platforms) are at the proper time, since it usually has not been possible to program ship time specifically for SPOC projects. Some of these platforms include the survey ships of BCF, ESSA, Coast Guard. Havy, Woods Hole Oceanographic Institute, etc. as well as the Coast Guard Light Towers, and the Ocean Station Vessels. Resources (money and people) are required to implement a successful ocean truth program.

Recommendation - Funding be provided for ship time personnel and special instrumentation for ships (microwave, IR, etc.).

<u>Preliminary Spacecy of Test Site Requirements</u> - Phases of sensor testing proceeding the spacecraft utilization phase which are devoted to program and instrument definition and use of aircraft for determining sensor feasibility include extensive testing of basically identical sensors aboard airborne platforms. This testing provides experience with results of airborne sensors to establish a comparative base for analysis of test results from spacecraft-borne equipment in the later time frame.

It will be useful to correlate results of simultaneous operations of both types of platforms to determine the comparative utility of spacecraft-borne instruments, especially during those experiments where the physical phenomena of the sea wary markedly with time. For this reason plans for simultaneous aircraft utilisation with spacecraft schedules should be established when spacecraft overflight information becomes available.

While much of the ground truth data will have to be gathered at the time of the spacecraft overflight, some of it can be taken in advance, by aircraft flights, to provide pancremis and topographic mapping of coastal features.

Documentation should cover an area large enough to be useful for calibration of the spacecraft data. Minimum size of useful calibration areas should be determined, since current experimental flights could be extended to provide the initial coverage of these areas.

106

For example, in order to get desired wave conditions, it appears necessary to select a period when the probability for the conditions is high, then fly sufficiently long legs over the area to increase the chances of obtaining the desired data.

<u>Commant</u> - Attempting to forecast the event of an ocean variable six months in advance is a very costly exercise. Waiting until the probability of the event usu be predicted more accurately can increase the chances of success.

Recommodation - That greater flexibility be allowed in scheduling the aircraft for ocean sensing, particularly waves. Some phases, such as river effluent studies, bathythemetric studies, sea ice, etc., may portione to be scheduled well in advance.

<u>Comment</u> - The range limitations of the Convair 240 minimize its usefulness as an oceanographic data collector.

Recommendation - Except for coastal experiments, the P-3 be scheduled for ocean work. The increased range and duration will permit greater opportunity for acquiring data on most ocean variables.

<u>Comment</u> - In most cases, engineering factors in remote sensing far exceed the oceanographers ability to use the instruments. Most ocean investigators are just beginning to define the problem and develop an experiment progress for a solution.

<u>Recommendation</u> - That hasts in requiring quick results and answers from the oceanographers may not be in order. More communications between investigators and those obtaining the data will lead to mutual understanding of requirements, problems, etc., enhancing chance for success.

<u>Comment</u> - A successful ocean truth program must make provision for those resources (people, ships, instruments) which will permit programming experiments specifically for SPOC.

Recommandation - Funding for this purpose be provided.

<u>Comment</u> - The staggering number of test sites and investigators in the Earth Resources Survey Program deters effective aircraft scheduling for ocean experiments.

Becommendation - Consideration be given to obtaining an aircraft especially for oceanography, and/or permit for contracting of specialised aircraft, and/or make available MASA Sensors for temporary or permanent installation on other aircraft such as ASMEPS.

<u>Comment</u> - Some sensor techniques being developed (WISP system for example) require testing on, and in fact may be more economical to test on, special aircraft.

107

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Farticular areas of the Gulf of Mexico are of special oceanographic interest. The Yucatan Current and Gulf Loop and areas of upwelling north of Yucatan Feninsula are significant oceanographic features. Large thermal gradients should be associated with these phenomena. Aircraft missions over areas such as this with concurrent ground truth acquisition will contribute to understanding oceanographic phenomena in the Gulf of Mexico which has been designated as an area of interest for the AAP-1A Mission. It is perhaps not premature to explore the feasibility or concept of designating the Gulf of Mexico as the "NASA Acre." This concept would utilize the Gulf of Mexico as the spacecraft test site and use the many resources for a surface observational network. The idea has merit and should be considered, although some ocean features (ice, high sea state) will still require observations outside the area.

The Spacecraft Oceanography Project bas selected five basic oceanographic experimental areas for the AAP-1A Mission contingent on the availability of the primary instrumentation identified in Tables 2-6. These are:

- a. Food from the Son
- b. Ocean Dynamics
- c. Coastal Features

- d. Environmental Prediction
- e. Selected Photography

The above areas are further delineated in specific experiments as shown in Tables 2-6.

The geographical experimental areas were selected based on oceanographic phenomena and the availability of surface or near surface platforms during the proposed period of the AAP-1A Mission. The platforms will include ships, aircraft, and/or towers as identified in Tables 2-6. These experimental areas are outlined in Figure 2. The larger areas will be narrowed in coverage when the exact times of spacecraft coverage are known to coincide with the planned positions of the ships operating in the area.

It is anticipated that missile tracking vessels possessing sums ground truth capabilities will be utilized as additional sources of data collection systems during orbital missions.

Photographic areas will not necessarily have ground truth but cover areas which possess features of oceanographic interest.

A surface observational program will be developed when details of the spacecraft instruments and orbit parameters are determined.

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* P = PRIMARY REQUIREMENT S = SECONDARY REQUIREMENT ** OPERATE PRIMARY AND SECONDARY SENSORS ± 3 MINUTES OVER TEST SITE

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Ground Truth Working Session Dr. R. J. P. Lyon

A conference on ground measurements for the instrument and geologic teams was held on the Rono campus of the University of Mevada March 14-15, 1966. This was an attempt to establish certain test requirements before the field summar season commenced at Sonora Pass.

This two-day mesting was designed to identify the basic needs of each instrument group and how these needs might be accomplished. The reader is referred to Technical Letter No. 3 of the University of Novada group in which these requirements are fully detailed. Requirements for the infrared (IR) spectroseter/redioneter experiment have been copied and included in this document as Table I.

Since that time attempts have been made by Stanford and by the University of Nevada to implement many of these measurements, particularly those dealing with the atmosphere. We have delegated the responsibility to the Nevada group to provide most of the ground truth measurements for the PJA IR spectrometer/radiometer experiment when this experiment has been used in the airborne mode. At test sites other than Sonora Pass and Mt. Lassen the ground truth measurements have been made by the Stanford group themselves.

In a recent study effort at Woods Hole considerable time was spent delineating the basic problems in remote sensing for geology, and methods by which these could best be solved in a research and development effort. Figure 1 is taken from this report and indicates that considerable affort should be devoted to the understanding of the geology of the outermost surface (or "optical depth", "akin depth", or "depth to opacity"). It is this surface skin layer which ultimately determines the response of the rocks to the remote sensors. Detailed study of Figure 1 indicates that the maximum effort should be devoted to the surficial geology, with only minor effort devoted to classical geological mapping. A similar minimum effort only should be devoted to the development of new remote sensing hardware. Over 80% of the total E&D effort is recommended be placed in understanding the ground truth dates.

In order to relate these concepts to the operational sepects of the F3A aircraft, Figure 2 has been drawn. In this flow diagram the relationships between Stanford, University of Hewada and the Manned Spacecraft Center (MSC) on the IF spectrometer/radiometer experiment are clearly indicated. The stippled areas in the center of the diagram are those in which much more research and many more measurements are required.

the top left-hand corner of Figure 2 in the hachured area is shown the ea of responsibility of MSC, for operational use of the combined ckage (the Rapid Scan spectrometer, the radiometer (or PRT-5), the resight camera, the aircraft hygrometer, and the aircraft data recording stem). The next block indicates that the data from such an aircraft eration flow through the MSC formatting computer to produce blocked gital tapes immediately compatible with the Stanford IBM 360 computer stem. The boresight and RCS camera data are sent to Stanford to tablish the precise ground position of the aircraft at any given time eeded to ± 10 feet at 2000 feet). These data are used in an interlation program in the Stanford computer to establish the aircraft sition on an arbitrary ground grid, which is drawn on a base map epared from high altitude photographs of the locality, taken (hopefully) e same day. From these two outputs it is possible to relate any given time s from the ASQ90 or from the various aircraft clock systems in use at e moment) to a portion of the map grid, and hence (through the relationip shown as a vertical line) with the mapping and ground truth parameters termined by the University of Nevada.

e identification of aircraft location on high altitude photographs and the map grid, as well as the production of the computer reduced aircraft ectra and all data analysis are the <u>responsibilities of Stanford University</u>. the Lower section in the laft-hand and bottom edge of Figure 2, the sponsibility areas of the University of Nevada are indicated.

the center of the diagram the attenuation of the smitted infrared diation by the atmospheric column is measured, by the use of weather ations and, when used together with the aircraft hygrometer, provide profile of the water wapor in the airpath between ground and aircraft for a computers at Stanford. The field data collection is well in hand but a aircraft systems need improvement. The second block (Surface Skin mpositions) is determined by measurements of soil moisture, vegetation unt and particle size. These <u>surfaces shin compositions</u> are then related hrough the aircraft time system) to <u>surface scolary (along the aircraft</u> ack) interrated over the field of view of the equivalent (0.3°) at any one stant of time. This is one-of the major ground truth measurements which at be made in greater detail then is in present practice.

e lower section of Figure 2 shows how determination of rock type and s pattern (or structure) and distribution of rock types ar. lated rough field geology mapping to a basic geological map. <u>A b.</u> <u>val</u> <u>closical map is a subsurface man</u> and generally does not show, for example, s position of snow banks, sand dunes, and other surficial cover. These l affect the "target", which is the surface integrated over a field of sw of the instruments. The vertical time-linkage between the University Wevada operations and the MSC operations of the aircraft is essential ad will be brought out in a later chart) as ground truth is only meetinl are the aircraft passed in its flight pattern.

more detailed analysis and flow chart of the operation is shown in gure 3. This rather complicated diagram starts in the center left-hand side with an <u>Experiment Definition</u>, a <u>Site Selection</u> and a specific <u>Tarxet Selection</u>, which were confirmed at the preflight Mission Briefing approximately 14 days before the flight. The F3A flight then occurs and starts the flow diagram into operation.

In the center of the diagram one sees the boresight camera being triggered by output from the spectrometer and their mutual relationship with the radiometer (presently the PRT-5). The serial cameras give the aircraft location. These locations are compared then with the target selections and the ground truth measurements made by the University of Neveda. The area of responsibility for the Neveda group is shown in the upper hachured segment. Laboratory work, following the aircraft flight, will enable the University of Neveda to prepare <u>Rock Type analyzes</u> using thin section and point counting and to provide Stanford with a modal (or mineralogical) analysis.

Ine x-ray fluorescence unit yields a chamical composition of the rocks from which one can determine a "normative" or theoretical mineral composition. Both of these analyses are fed into the block labeled "<u>Bata Analysis</u>". Again it is most important that the samples used in the determination of the rock type and chamical composition <u>be those which are encody</u> (or at least adequately represented) <u>along the flight lines actually flown</u>.

In the center panel we see the relationships between the <u>aircraft operation</u> at HSC and the <u>data handling design</u> responsibilities of Stanford (under Dr. Roger Viokzer). The center hashured and stippled area chows the detailed experimental design (which originated at Stanford) and its execution in an aircraft flight and subsequent data reduction performed at NSC. Digital recording is still not installed in the aircraft although we are already installing it for our ground operations. The digital radiometer and spectrometer outputs are sampled in the computer by the signal from the edge coding around the periphery of the filterwheel in the spectrometer. This julied signal is used to trigger the digital sampler in the computer. This in turn produces an IBM 960 taps formatted to the Stanford pattern. This tape is then sent to Stanford wherein spectra are produced from programs operating on the Stanford emputer.

These spectra are the sincle west important product of the entire flight. An on-line program called CORNCO (a correlation coefficient program, see SEE Technical Report 67-1) is used, and this produces a ranked, rock-type analysis as seen on the right-hand side. Other Stanford programs are used by Switzer in a <u>stan-wise discriminant function</u> (or adaptive learning) program which learns from standard spectra and identifies rock classes on a probability basis. The correct class is assigned to each incoming aircraft spectra. Another rock-type listing is produced and this, in turn, is compared with the (CORNC) reck-type reaking, in the <u>Bati Analysis</u> <u>block</u>. A further program is utilised by Switzer at Stanford in the minral smalysis program to produce a "modal" (or minoralogical) analysis as its and product. This also is compared through the Bate Analysis lock with that

derived by rock-type analysis by the University of Nevada.

This is the program design diagram. At present few of the cycles have been completed for Mission 56 as considerable portions of the data are not yet available. Model analyses of thin section material have not yet been prepared but a number of useful chanical compositions and normative analyses have been received. These baiever are percentages of theoretical minerals and not the actual minerals occurring in the rook. In addition, most of the samples which have been so far analyzed are not from this year's flight lines. This is not meant as a negative statement, but to indicate work yet to be done on <u>one</u> mission. We are all in a learning situation with "ground truth", and working responsibilities and tasks are continually becoming more clearly defined.

In the area represented by the center block called "Aircraft Location" we have also had many problems due to the mainmention of the beresight campra. We have had to revert to an aircraft location method which utilises the RCS cameras which trigger every five seconds. These cameras carry their own clocks and it is possible with a fair degree of precision" to interpolate spectral start times between individual RCS frames to locate the 300 spectra which occur between each RCS photograph. The RCS cameras were locked in position to the aircraft frame and were not corrected for drift in order to have them record as accurately as possible the madir beneath the line of sight of the spectrometer.

In summary some points to be made are shown in Table II as a listing of axiens for ground truth operations. These are:

- a. Ground truth data are only useful along the aircraft ground track.
- b. Heather data are only useful at flight time.
- o. Water content in the air and on the ground is the single most important parameter to be measured.

d. Ground truth data are only useful if they can be used in subsequent statistical analysis of the data.

In conclusion, it is still necessary at present to make a <u>goalderable</u> <u>number of ground truth measurements</u>. It is perhaps debatable has many about the arcoraft truth measurements. It is perhaps debatable has many about the arcoraft flight. In some cases the sensoral conditions presides making these measurements <u>after</u> alroraft flight, particularly when one considers the time required between the aircraft flight and receipt of the photographic date by which aircraft trucking must be determined. One must then add time for a considerable amount of work involved in transforring cases conter younts from the RDS easers and in locating these on the ground. It can be settighted that approximately 2-4 weeks offert would be required after an aircraft flight and prior to accurate grown location being obtained along the size arts theself.

* (\pm 25 feet) 150 Kts. = 300 feet/cee. FOV of spectrazeter is 0.5° or 5 B radians, or 10 feet at 2000' clearance. A/C crear is 50 feet in the 150 meet between spectra totalling 10 x 60 feet/spectras.

We must more fully understand the <u>total system</u>, how the <u>ground truth</u> <u>parameters</u> and the <u>subsurface sendary</u> (as shown on a typical geological map) interact in the surface sendary (as shown on a typical geological map) interact in the surface sendary (as shown on a typical geological map) interact in the surface sendary, we sumt not neglect the effects of the miroraft modifies these signals. He must not neglect the effects of the miroraft data system and how final output from the computers further changes the date. After all, "success" is the right relationship between the output from the computers and how final output from the ground truth measurements. Before this because possible we are going to have to face up to the collection of a considerable amount of possibly redundant data. In addition a strong plan must be made for a more solutions of union successes. It is already fairly clear that core measurement of union vapor content between an miroraft and the ground is an extremely difficult and quits sophisticated metoorological experiment, not yet performed by metorologists with a degree of local and temporal procision requested by this emperiment.

APPENDIX

Computer Analysis of Ground Truth Data

Analysis of Stanford 1965 meteorological data has been made by cross correlation methods. Several attempts have been made previously to search for meaningful patterns in our 1700 sets of ground truth data, which would relate directly to the results of the infrared spectral matching process. One such report appeared in our first semi-annuml report a year ago (May 10, 1966, p. 15) and another was summarised in the First Annual Report (November 1, 1966) on page 4 and in detail on pages 54-56 of that report. At the latter time we felt that we could see <u>no effect on the outcome of the spectral matching process</u> which would be directly related to meteorological conditions present at the time the spectra were taken.

Intuitively, this seems to be the wrong conclusion, and so we have made a further, more detailed analysis of these field data. One answer to which we attribute some oredence is that the spectra are themselves so noisy, due to the microphonic condition of the GuiGe detector (See SRSL Tech Report 67-3) that any further perturbations introduced by "noise" in the weather variables cannot be seen. In this manner one can truthfully say that...."the use of the...._weather/... variables did not lead to a significantly better classification into rock types." (1st Annual Report, p. 4)

The present study was to all intents and purposes a "shot-gun" approach. We collected all the available data and found we had 2 groups.

Group I Those with data for 17 variables (275 samples) Group II Those with data for 23 variables (252 samples)

A cross correlation program was run in the computer with these groups of data and a triangular coefficient matrix prepared for each group (pages A3 and A4). Suitable stippled patterns indicate the 0.25, 0.4, and 0.6 coefficient levels. No confidence level was run by this program so we are not sure which numbers are significant at the 95% level, for example. A quick glance will show that for 250 samples of 17 or 23 variables each, the stippled levels are conservative.

Of more significance is the analysis following in Tables X A & B, where we have tried to segregate relationships which have obvious character (even redundancy in some cases) from those which might have experimental significance. Many associations can be explained by the temporal pattern of daily or yearly activity (geographical locations or altitudes for example) as we moved from test site to test site.

Sequence of Test Sites - 1965 Field Period

Date	(Day)	Location (Cal	ifornia)	titude/S.L.	Rock Type Ta	pe No.
(1965)					Banco Bancolow
8/12	(1:.4)	Pacific Coast	(PGLHO1)	30	Granite	1
8/13	(2.4)	Pacific Coast	(FGLPC1)	30	Granite	2
8/18	(230)	Denner Pass	(DPGCO1	6825	Granite	2
9/2"	(268)	Mono Lake	(MCABO1)	7310	Granite	3
9/26	(269)	Mono Lake	(MCSCO1)	8680	Rhy. Pumice	3
9/24	(270)	Mono Lake	(MCSCO5)	8680	Rhy. Pumice	4
9/25	(271)	Mono Lake	(MCNLO1)	6800	.Rhy. flows	4
10/1	(274)	Mono Lake	(MCNCO1)	6800	Rhy. flows	4
10/2	(2:15)	Mono Lake	(MCCCOI)	7629	Bas. Cinder	5
10/3	(276)	Mono Lake	(MCSCO)) (MCSC10)	8680	Rhy. Pumice	6
10/4	(277)	Mono Lake	(MCSBO1)	6440	Pum. Beach	6
10/14	(287)	Tioga Pass	(TPOPO1) (TPLDO1)	8500	Granite	7
10/15	(288)	Mono Lake	(MCHPO1)	6520	Basalt Cone	8
10/23	(296)	Pisgah Crater	(PCWR01,02,0)	2515	Basalt Cone	8,9
10/24	(297)	Pisgal: Crater	(PCTPO1) (PCERO1,02)	2543	Basalt Cone	9,10
10/25	(298)	Pisgah Crater	(PCLL12,13,14)1888	Basalt flows	10
10/26	(29))	Pisgah Crater	(PCLL15)	1888	Basalt flows	10





The tables A-K which have been prepared from this analysis are

as follows. Experimentally significant tables are indicated by an asteriak(*).

- A. Logically explainable by parameter involved
- B. Explainable by relationships between meteorological and rock temperature.
- C.* Experimentally significant relationships not immediately explainable.
- D. Directly related to the yearly sequence of site chosen for field work.
- E. Related to daily work pattern at sites.
- F. Related to sequential breakdown of detector in SG-4.
- G.* Instrumental Relationship
- H. Modal Quartz percentage
- I. Emissivity average (K Bar)
- J. LMSC correlation coefficient (CORRCO)
- K. Correlations ranked by value (over 0.24).
- The following notes are important to the analysis of tables A-K:
- 1. Tape No. Serially from Tape 1 to Tape 10
- 2. Day day of the year, see sequence table above
- Temperatures all contract, using DIGITEC thermistor probes (Sand) in *C (Ba)
 - (Rock)
- 4. Air Temperature 6 inches off ground in shade, DIGITEC thermistor
- 5. <u>Relative Humidity</u> Percentage, Honeywell RH Indicator meter, type WollA used with 5 ranges of probes
- 6. Altitude taken from topographic maps
- 7. <u>S3-4 parameters</u> electronic settings off unit, period in <u>seconds</u> (Gain) (Period)
 - (Bandpasa)
- 8. Spectrum No. sequential spectral group along any one tape
- 9. <u>Lapse Time</u> time in <u>minutes</u> since last filling of liquid helium cryogenics (appeared to be directly related to noise increases in the fie'1)

- <u>Guartz</u> modal analysis, prepared by counting 1500 grains in a thin section under the microscope, can be considered to be an approximation of rock type
- 11. CORRCO See footnote table K, correct answer for that rock type target was used, not the highest value
- <u>VOIDS</u> modal analysis at for quartz. Both Pisgah basalts and Mono Crater pumice had high void values which may have acted to cut down "spectral contrast".
- 13. E RAR average emittance ratio values in LMSC program
- 14. E Var variance of emittance ratio in LMSC program
- 15. Wind velocity in miles per hour, hand held "venturi" gauge
- 16. Range in feet, if over 1000, taken from maps.

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R	3 .		
	с.	EXPERIMENTALLY SIGNIFICANT RELATIONSHIPS N	OT INMEDIATELY EXPLAINABLE
	a share a second		Correlation Coefficient
	1.	IMSC Correlation Coefficient vs. Tape No.	(34) (Wny?)
-	2.	SG-4 Cain vs. BB Temperature	(.35) (Why not negative?
	3.	Average Emissivity (E) vs. SC-4 Bandpass	(29)
	4.	Average Emissivity (E) vs. Void \$	(29)
	5.	Quartz 5 vs. RH	(.28)
	6.	Quartz 5 vs. Day of Year	(35)
	7.	Average Emissivity ($\tilde{\Sigma}$) vs. Lapse Time	(28)
	D.	NELATED TO THE YEARLY SEQUENCE OF SITES CH	OSEN FOR FIELD WORK
	1.	Day No. vs. Relative Humidity	(79)
	2.	Tabe No. vs. Relative Humidity	(63)
	3.	None No. vs. Air Tenr.	(.43)
		Tane No. vs. BB Terry.	(, 36.)
	5	Quartz content vs. Day of Year	(35)
	6	Tene No. vs. Altitule	(30)
		Tona in ve Sand Temp.	(.29)
		rape net tot cand temp.	(
	F.	RELATED TO THE DALLY WORK PATTERN AT SITES	
1	1.	SG-4 gain va. Sequential Spectrum No.	(.36) (not clear)
	2.	SG-% period vs. Day of Year	(34)
	F.	RELATED TO SECURITIAL BREAKDOWN OF DETECTO	B IN SG-4
		Shall main ve Day of Year	(63)
the second s	1.	(whereas BFT vs. day is (.19)	(
	2.	SG-1. gain vs. Tope No.	(.39)
	3.	SG-4 gain vs. Sequential Spectrum No.	(.36)
		Uncertain Why Relationship Exists	
	1.	SG-4 gain vs. Relative Humidity	(53)
		(Day vs. RH 1s79) (Day vs. SG-4 gain is .63)	
(m. 1)			
	1		

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Contraction of the second

TABLE X CORRELATION STUDIES ON 1965 FIELD DATA

Α.	LOGICALLY EXPLAINABLE BI PARAFEIER I	Correlation Coefficient
	Simply Explained of Year	(.90)
1.	Cand Demperature vs. BB Temp.	(.86)
2.	Cand Temperature vs. Rock Temp.	(.81)
3.	an mamperature vs. Rock Temp.	(.76)
4.	and Tomperature vs. Void %	(.34)
6.	Rock Temperature vs. Void %	(.31)
1.	Not so obviously related Sequential spectrum no. vs. lapse t	ime (.43) (should be higher but lapse Time returns often to rero)
в.	EXPLAINABLE BY RELATIONSHIPS BETWEE	EN METEOROLOGICAL & ROCK TEMPERATURES
1	Air Temperature vs. BB Temp.	(.86)
2	Air Temperature vs. Sand Temp.	(.84)
3	Air Temperature vs. Rock Temp.	(.73)
4	Air Temperature vs. Altitude Temp.	(62)
5	Average Emissivity (E) vs. Void \$	(.29)
6	Lapse time vs. BB, rock, sir, Temp	(17 to27)
	Not so obviously related	(67)
1	. BB Temperature vs. Altitude	(- 60)
5	. Sand Temperature vs. Altitude	()
3	. Rock Temperature vs. Altitude	(32)
24	. SG-4 Gain vs. Altitude	(27)
5	Air Temperature vs. Day	(32)
6	. SG-4 Bandpass vs. Altitude	

4

	Uncertain May Relation	ship Exists	Correlation Coefficient
2.	80-4 Period vs. Day of	Year	(-, 54)
3.	80-4 Period vs. Rel. M	(12.)	
	INSTRUMENTAL RELATIONS	HIPB	
	Clearly Related		
	90-4 Bandpess vs. 88 Tr	mp.	(.35) (not so clear)
	80-4 Period vs. 80-4 B	ndpass	(22)
•	90-4 Gain vs. 80-4 Band	lpase	(20)
	Clearly related and sho	ould be of other sig	<u>n</u>
	80-4 Gain vs. BB Temper	rature	(13) (why negative?
	Unclear but probably sh	nould be of other si	<u>en</u>
	80-4 Gain vs. 80-4 Bert	lođ	(22)
		·····	
	NODAL QUARTZ PERCENTAGE	1 .	
	Relationship Found	Correl. Coeff	Resson
•	Quarts vs. Day	(+.35)	Day vs. Tape (.90)
•	Quarts ve. Tape	(35)	
•	Quarts vs. RH	(.28)	Day vs. R.H. (79)
•	Quarts va. 3 Average	(25)	
•	DUBSIVITY AVERAGE (1)		
	vs. Volda	(.29)	
	rs. 60-4 Bandpass	(29)	
	ve. Time Lapse .	(28)	
	ve. Querte	(25)	
	re. IMSC CORRCO	·(24)	•
; '	vs. 2 variance	(.23)	
	vs. Range	(18)	

	CORPTATION CORFFICIENT (COR	RCO)
	Contrasta	Correl. Coeff.
	_ · · ·	(34)
ORRCO	vs. Tape Ho	(27)
OFRICO	vs. Day	(24)
ORRCO	vs. E	(.18)
CORRO	vs. Quarts	(17)
CORRCO	vs. Voids	(17)
CORRCO	vs. B variance	(.16)
CORRICO	vs. Spectral Sequence	(120)

•

	Group II	
	(23 variables	Group I
CORRELATIONS PAMED BY VALUES	includes LMSC output)	(17 variables)
Tape number vs. Day	.90	.89
Sand T vs. BB Temp	.86	. 84
Air T. vs. BB Temp	.86	.85
Air T. va. Sand Temp	. 34	.84
Sand T. vs. Rock Temp	.81	.81
RH VA. Day	79	78
BB Temp va. Rock Temp	.75	76
Ata Tamp Le Bock Tamp	73	73
BB Temp vs. Altitude	. 67	
Po-h Cain ve Dav	63	60
Mana No. Vo. P.H	63	.00
Hape No. Ve. Althude	03	00
Air lemp vs. Alticude	· .02	02
Sand Temp vs. Altitude	00	* • 79
BO-4 Gain vs. R.H.	53	- 49
Tape No. vs. Air Temp	.43	.44
Spectrum no. vs. Lapse Time	.43	. 38
Rock Temp vs. Altituda	41	42
Tape No. ve. SG-4 Gain	• 39	. 36
Tape No. vs. BB Temp	. 36	. 36
Spectrum No. vs. SO-4 Gain	. 35	.32
86-4 Bandpass vs. BB Temp	.35	• 35
Quartz ve. Day	35	35
Voids vs. Sand Temp	. 34	. 32
SG-4 Period vs. Day	34	34
Tape No. vs. CORRCO(*)	34	(rot used in Group I)
80. + Oain vs. Altitude	. 32	. 30
80-4 Bandpass vs. Altitude	32	32
Voids vn. Rock Temp	. 31	.29
80-4 Period vs. R.H.	. 31	.30
Tape vs. Altitude	30	32
Tape vs. Sand Temp	.29	-29
E vs. SO-4 Bandpase	29	
2 vs. Voids	.29	
Quartz vs. R.H.	. 28	.28
E vs. Lapse Time	- ,28	
Atr VA. Day	.27	-28
SG-4 Bandpess vs. Bock Temp	.27	.27
CORRCO(*) Vs. Day	- 27	
Sand Temp ve. Lanse	27	2.28
Tane No. va. Soak period	2.27	27
Stah Pariod va. Altitude		85
Stak Sandnass vs. Wind Val		2.24
Stall Bandmans ve. Atv Tamp.		.95
Volde va Aty Temp	.94	24
Spectral No. va. R.N.	- 25	- 24
B wa Chieveta	- 08	
to vor substan	- + 6.4	

"CORRCO - Correlation coefficient used was from the LMBC output. The value used was that which correctly matched the target rock type, for the same rock type in the library, and motnecessarily the maximum value of CORRCO. TABLE I

PRELIMINARY BASIC REQUIREMENTS AS DEFINED BY DR. R. J. P. LYON FOR THE INFRARED TEAM

March 14, 1966

A. Field Solid or Loose Material - Surface Only

1. Roughness using Form Tool-NS and EW profiles. Make profile and then record to \pm 0.5 mm, by:

- a. Spray paint (not pencil).
- b. Photo sensitive paper (visicorder rolls) on a sheet of rollsd chart paper for late reduction by curve follower mothods.
- c. Fabric or texture describe, draw, and also photograph.

2. Surface sample down to 1 on depth

- If rock, cut 3" x 3" slab and place in cotton in box (mail to Lyon).
- b. If loose, pour black plastic mold for vertical sectioning. Send half to Lyon for modal analysis of polished slab.
- Note color, weathering degree, glacial polish, desert varnish, etc., in field.
- 3. Photometric backscattering in field

Produce graph at least in N-S and B-W planes. If continuous trace is not available, then position lamp source at $+60^\circ$ and take readings with PE cell at 0, 30, 60, 90, 120, 150, and 180°. (May have to be done after dark if instrument is not adequate.)

- 4. Emissivity box measurements in field. Two at each grid point. (Need values to ± 0.05)
- 5. Color photos vertical. Two mach (with original set for Lyon) of:
 - a. Modachrome II or Ektachrome
 - b. Asro Infrared Ektachrome (CD)

If possible:

- o. From 2 feet and 10 feet
- d. Stereo-shifted 3" at 2 feet
- e. Stereo-shifted 12" at 10 feat
- Use "b" for Lichen and vagetative counts.

TABLE I (contd)

6. Moisture - if possible in field (especially on flight days)

a. Surface to 1 mm.
b. Other layer at 1-2 om depth.
(Accuracy needed ± 5% of amount present)

7. Atmospheric - and micro - meteorology (especially on flight days).

Wind velocity to 1 mph, RH to $\pm 0.5\%$. Air temperature (°C) at 1 1/2 meter/ground (to $\pm 0.2°$ C), Barometric pressure (to ± 0.5 inches), all taken at a single base-cump with respect to time of day in a 24-hour cycle. Repeated once a week, but specifically performed on flight days 12 hours before tr 12 hours after flight. (For solors, use OSA Standard Rock Color Chart.)

138

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B. Laboratory

Carry law is the property the standard

 Modal analysis, major minerals - 1500 point count. If fine grained, use thin section(s), if coarser, use a polished slab (+ z thin section to identify the ground mass). Bring piece back for slab polishing.

Identify:

- a. To ± 1% of amount present quarts, K-spar, plagicolase (with An% to ± 5%) pyroxene, amphibole, clivine, mica, glass and woids. Determine bulk rock S.G.
- b. To ± 5% of amount present opaques, color index. (Identify opaques if practical.)
- c. Fabric texture, note, preferred orientation of grain pattern in soil using:
 - (1) Bulk "parent" rock at some small depth below weathering rind and/or soll
 - (2) Actual surface chip (or layer of soil) to t 1 am depth.
- 2. Chemical analysis (X-ray, spot. or emission spec.). Record as oxides to $\pm 0.5\%$ of amount present. Si, Al, K, Ha, Ca, Mg, Fe(T), $(\frac{1}{2}Fo_2O_3 \text{ and FeO} \text{ if possible})$ Ti etc. to $\pm 5\%$ of amount present. Use I lb. specimen, pulverise and mix thoroughly. Send 10 grams in bottle to Lyon. Get powder S0 as well as bulk rock S0.

TABLE II

MASA-S-67-7768

AXIOMS FOR GROUND TRUTH

- D DATA ONLY USEFUL WHERE THE AIRCRAFT ACTUALLY WENT. THIS MAY CESSITATE POSTFLIGHT GEOLOGY AND SAMPLING. THIS IS PARTICULAR-SIGNIFICANT FOR NON-IMAGING LINE-TRACE EQUIPMENT LIKE IR SPEC-RADIOMETER AND MICROWAVE RADIOMETERS NECESSITATE IROMETER. **GROUND DATA** Z
- WEATHER DATA IS ONLY USEFUL AT FLIGHT TIME AND FOR 24 HOURS PRIOR TO FLIGHT IF GROUND IS WET 0
- **BE MEASURED** WATER CONTENT IS THE SINGLE MOST IMPORTANT PARAMETER TO BE MEA BECAUSE OF ITS HIGH ABSORPTION COEFFICIENT AND EFFECT IN THE DIELECTRIC CONSIANT
- MOISTURE ON GROUND
- MOISTURE DOWN TO SKIN DEPTH, f (A)
- WATER VAPOR IN TOTAL AIR PATH FOR IR, AND ITS DISTRIBUTION WITH TIME
 - FREQUENCY IN AIR PATH FOR MICROWAVE IID WATER DROPLET SIZE AND AND RADAR WAVELENGTHS LIQUID WATER

CROUND TRUTH DATA ARE ONLY USEFUL IF THEY CAN BE USED

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The second second second second second

RECOMMENDED FOR REMOTE SENSING 70 00 D EFFORT MIX IN GEOLOGY

	HARDWARE	INTERPRETATION					
	REMOTE SENSING TECHNOLOGY AND HARDWARE	INTER-RELATING REMOTE SENSING DATA TO SURFICIAL GEOLOGY	SURFICIAL GEOLOGY *	CLASSICAL GEOLOGY			
27	्री	15%	9	34	EFFORT IN		
40	99 98	<i>ل</i>	15m	28	EFFORT IN FIELD		
x	Th	12% 8	12%	22	DATA FROM AEROSPACE		
100	19	. A	33	0	RE		

A, B IMPLIES A TIME-STEP SEQUENCE

SURFICIAL GEOLOGY = "OPTICAL DEPTH", "DEPTH TO OPACITY", "SKIN DEPTH", GENERALLY $\frac{\lambda}{10}$, to 10 λ

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Research conducted through the

Texas A&N Research Foundation

A&M Project 206-13

Project 286 is sponsored by the Office of Hevel Research [Project NE 083-036, Contract Hour 2119(04)]. The Project 286-13 portion is oparated through funding provided by the Spacecraft Oceanography Project of the Hevel Oceanographic Office and is part of the National Asronautics and Space Administration's Earth Resources Survey Program.

> Report prepared 22 November 1967

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TABLE OF CONTENTS

									rage
BACKGROUND		•	•	•		•	•	•	146
PURPOSE AND SCOPE OF THIS PAPER			•	•	•	•	•	•	148
GENERAL REQUIREMENTS OF GROUND TRUTH PROGRAMS		•	•	•	•	•	•	•	149
EXISTING GROUND TRUTH CAPABILITIES		•	•	•	•	•	•	•	150
MEASUREMENTS REQUIRED	•	•	•	•			•	•	153
SUPPORT OF MISSISSIPPI DELTA TEST SITE	•	•	•	•	•	•	•		158
SPECIFIC RECOMMENDATIONS		•		•	•	•	•	э	159
Ship support		•	•	•		•	•	•	159
International cooperation		•	•	•	•	•	•		160
Suitcase instrumentation	•	•	•	•	•	•	•	•	160
Calibration standards	•	•	•	•	•		•	•	161
SURPHARY			•			•			162
GROUND TRUTH REQUIREMENTS FOR REMOTE SENSING

OF OCEANOGRAPHIC FEATURES

BACKGROUND

The Spacecraft Oceanography Project (SPOC) at Texas A&M University was initiated in early 1966 under the Department of Oceanography. Its goals are to determine the utility of using remote sensors in studying the features of the Gulf of Maxico and specifically the Mississippi Delta area from airborne and Earth orbital heights, to develop techniques whereby these studies might be conducted, to nominate a group of remote sensors that have optimum use for oceanography and to design experiments to be conducted using satellite based sensors. The Department of Oceanography at Texas Add University has been interested in the Gulf of Mexico and its features for some time. The region of the outflow of the Mississippi River (the second largest in the world) was selected as a test site for the Earth Resources Aircraft Survey Program due to many reasons. Firstly, it is an area where large spatial and temporal variations occur in the important parameters measurable by classical oceanographic techniques. Secondly, it is near Texas A&M University and MSC/MASA Houston where the aircreft are based. Lastly, it is an area in which a fair amount of classical oceanographic research had been conducted in the past.

To date seven flights by MASA sircraft have been made over the Mississippi Delta, Site #128. Only two of these flights have been supported by

ABSTRACT

145

GERTIN

For almost two years the Spacecraft Oceanography Project (SPOC) at Texms A&M University has been studying the use of remotely sensed data from aircraft to determine oceanographic features.in the Missianippi Delts region of the Gulf of Nexico. Past experience has shown that the present ground truth program is inadequate due to the nonevailability of research ships and other sophisticated instrument platforms. All the important physical parameters on the sea surface and in the atmeephers above should be measured. Recommendations: The Earth Resources Survey Program (ERSP) should lesse or purchase additional research ships. Steps should be taken to secure international cooperation in making surface surveys of test site areas. Fortable instrument packages should be made that may be placed on non-research ships. ERSP should standardize the calibration of the sensors being used on ship and aircraft.

PURPOSE AND SCOPE OF THIS PAPER

The purpose of this paper is to present a summary of our past experiences in gathering ground truth data from an operational point of view 'n support of the Earth Resources Aircraft Survey Program in oceanography. The meterial herein is intended to be supplementary in nature. Bearing in mind our limited viewpoint as regards the total Spacecraft Oceanography project's needs, the recommendations and comments contained in this paper apply only to our experiences in the Gulf of Mexico and specifically the Mississippi Delta region. It is not intended to be a comprehensive survey of the overall ground truth requirements of the Karth Resources Survey Program in oceanography.

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147

surface ships collecting data, and in only one of these flights was the data obtained anywhere near the amount and extent to satisfy the requirements of a ground truth program.

There are several areas of study under SPOC at Texas AAM University that are not concerned with the Mississippi Delta test site. One is a study simed at correlating cloud patterns with oceanic features in the Gulf of Maxico. NIMBUS and ESSA data are being used in these studies using ground truth data from the various cruises of <u>Alaminos</u> for ground truth. Other studies are concerned with the heat and water budgets at the air-ses interface and periphery of the Gulf of Maxico.

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GENERAL REQUIREMENTS OF GROUND TRUTH PROCRAM

The primary requirement for any ground truth program is that sufficiently accurate measurements be made of all the important parameters at the surface and in the subsurface under study and of all other parameters affecting the readings of the various sensors. In this way one any be able to show a correlation (positive or n=jative) between what is happening or present in the area of interest and what the remote sensors see from above.

Ideally, these determinations should be made synoptically--all at the same time. An exception of this principle could be taken if nono of the parameters had changed during the period between the collection of remote sensed data and ground truth data.

In the case of oceanic surveys by remote sensors, only the temporal and spatial distribution of surface peremeters such as temperature, salinity, roughness (see state), biological activity, oils, etc. need he determined. The task of correlating these surface persmeters to subsurface oceanographic phenomena is given to classical oceanographic survey.

It is possible that ground truth may be obtained by using measurements from remote sensor systems that are, or become reliable as the program develops. The IRT is an example of such a sensor. Another example is that it is possible to obtain ground truth on the roughness of the sea surface from the sun's glitter patterns as seen photographically. Low altitude flights may be able to provide ground truth for high altitude measurements.

EXISTING GROUND TRUTH CAPABILITIES

Under the present procedures, gr md truth is obtained by ships or fixed platforms in the Mississippi Delts. Since our SPOC project has no control over the scheduling of oceanographic research vessels except the <u>Aleminos</u> (Texas AGN University oceanographic research vessel) which is scheduled on a yearly basis in advance, it has been difficult to obtain simultaneor surveys of the test site by airplane and ship.

Due to the fluid nature of the oceans, ground truth messurements must be made synoptically or quasi-synoptically with the mircraft measurements or else their value is lost. This is the most significant difference between the requirements of a ground truth program supporting oceanographical studies and for one supporting land studies.

In the past, the problem of coordinating aircraft flights and ships cruises plue occasional incloment weather or equipment melfunction has resulted in a small percentage of successful ventures.

When the <u>Aleminos</u> is in the test site, the following types of data are collected:

 Temperature of the skin of the ocean's surface is measured continuously by a Barnes IXT at a he'g't of approximately five meters and recorded on a strip chart. A backup IRT is available in case of malfunction.

 Total cloud covar is recorded by a time-lapse hemispheric (fisheye) camera.

following summaries of missions in the past are included:

 July 1966 - Ground truth was collected in a very limited part of the test site area by a commercial charter boat, the <u>Playboy</u>, which had a graduate student on board to obtain some BT's and bucket-temperature measurements.

152

 <u>October 1966</u> - Personnel from MIT and the University of Hevada were on hand to make colorimetric and IR temperature measurements of the Mississippi Hiver outflow. Unfortunately the aircraft mission was rained out after only a brief flight.

 <u>December 1966</u> - A partially successful aircraft flight coupled with no ground truth made this mission of questionable value.

 February 1967 - A completely successful mission was flown by the mircraft; but, no ground survey of the area was possible due to the non-availability of ships.

5. April 1967 - Ground truth teams were prepared to survey the test site area, but the siccraft could not fly due to equipment malfunction.

June 1967 - This mission was similar to the February mission.
 August 1967 - For the first time quasi-simultaneously surveys
 ware made of the test site by both the MASA FIA and the <u>Alaminos</u>. To

point out the differences between aircraft survey and ship survey, it took the <u>Alamimos</u> two days to survey the three lines surveyed by the MASA P3A in a period of two hours.

 Air temperature and dev-point temperature are recorded continuously at a height of tem maters.

 Surface wind speed and direction is observed by personnel onboard and recorded in a log.

 Standard meteorological surface observations are recorded in a log.

 The temperature of the top layer (subsurface) of the water is monitored continuously by a resistance thermometer and recorded on a strip chart.

 Sea surface salinities are continuously measured by a salinity cell and recorded on a strip chart.

 Vertical distributions of salinity and temperature are measured by salinity, temperature and depth devices (STD's).

 Additional vertical distributions of temperature are obtained by bathythermographs (BT's) which are regged and reliable but not as accurate as the STD's.

Oceanographic research vessels can survey only a few lines in a few days so that synoptic coverage cannot be obtained by the one ship alone neither can one ship satisfacturily survey even an area as small as the Mississippi Delta region.

The other aircraft missions have been supported feebly by small boets and fixed oil platforms.

To illustrate the past problem of obtaining ground truth, the

154

With the above comments in wind, the following is a list of the measurements required (*indicates that these measurements are currently being made satisfactorily is our present ground truth program).

 Amount and spectral distribution of direct and indirect solar radiation impinging upon the ocean's surface.

2. Net terrestial radiation near the ocean's surface.

3. Downward radiation from the sky in the microwave bands used

by the passive microwave radiometers.

 Vertical distributions of temperature and water vapor in the atmosphere over the test e.cs from surface to 50,000 feet.

*5. Cloud coverage.

*6. Refizontal _istribution of water-surface temperature and salinity

in the test site area.

 Magnitude and direction of water wapor flux and censible heat flux at the air-sea interface.

8. Complete surface meteorological observations.

9. Accurate navigational equipment.

10. Colorimetric analysis of surface waters.

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11. Amount of suspended material (sediments) in the surface water.

12. Unified data management system on board the ship using a common time base to enable correlation of ground truth data. This system should include analog-to-digital conversion and digital storage on magnetic tapes. All the measurements should be stored in digital format to provide easy reduction and use.

153

MEASUREMENTS REQUIRED

One of the goals of SPOC at Texas AAN University is to develop techniques whareby meaningful oceanographic measurements can be made from satellite based sensors. To accomplish this, the effects of the atmosphere in attenuating and redistributing the redistions from the ocean's surface must be considered. Thus, detailed knowledge about the tempwrature structure and composition of the atmosphere over the test site area must be obtained by the ground truth program. This implies the use of various atmospheric sounding devices such as rediceondes, rawinsonde, tethered balloons, wire sondes and rockets.

The sheer size and number of required measurements and instrument systems dictates the use of large platforms on which these instruments are to be based. The most logical platform is the ship. These vessels cost from two to six thousand dollars per day to operate. Also, the number of research vessels in the United States is quite limited.

In some cases, fixed platforms such as oil platforms may be used to hold ground truth instruments; however, these would be inflexible and necessarily located close to shore lines.

Aircraft may be used to provide ground truth in a number of ways in addition to those already mentioned. Dropeondes (atmospheric profiles) and expendable BT's may be dropped from ground truth aircraft along with buoys to monitor automatically water temperature, salinity and meteorological conditions at the sir-ses interface.

as the actual measured value.

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Similar problems exist for photographic interpretation. Factors such as water contaminants, surface roughness and even atmospheric pollutants c_n directly affect the apparent color of the water. In this aspect then, it is imperative to know the factor which lead to the color dues observed on the ocean surface (items 10, 11).

Microwevo measurements are as sensitive, if not more so, to the same factors that must be considered for infrared measurements. In this aspect surface roughness is particularly important to signal return. Surface temperature and surface salinity effects microwave emission so that they also must be determined accurately before microwave data wequisition is realistic. An additional factor which must be considered, as in the case of the infrared messurements, is the sky radiation.

All the considerations stated above require adequate ground truth coverage.

The question might be raised as to why it is considered important to be able to determine the horizontal distribution of temperature, salinity and roughness on the ocean's surface. Studies at Texas A&M University have shown correlation between sea surface temperature patterns and currents. Most of the physical properties of sea water such as density, conductivity, dielectric constant, heat capacity and others can be obtained knowing its temperature and salinity. Roughness distribution can imply eveporation distribution. Finally, these parameters all enable estimates of the heat and water vapor flux into

155

 A system to allow real time comparison of ship and aircraft data at points of coincidence.

 Development of portable or suitcase instrumentation adaptable to many different types of vessels.

Although the above requirements have been given in brief outline form, their importance to a remote sensing program cannot be over emphasized. Remote sensing itself consists of measuring a large area of the ocean surface on a very short-time scale. Although this has the obvious advantage of surveying large areas we must also know how representative our "instantaneous" picture is.

In the infrared or temperature picture a representative view requires that we must know the time change of heat flux from or toward the ocean surface (items 1, 2, 4, 5, 6, 7) in addition to vertical mixing at the surface. Without such information on both a spatial and temporal basis the temperature structure we describe by a remote sensor survey will have little meaning in any representative or scientific sense.

In addition to change at the ocean surface affecting the remote sensing approach to sampling the ocean surface, there is always the problem of looking through a sea of air. It is imperative that we know how the vertical temperature and moisture structure affects remote sensing equipment. The atmospheric pollutants can also play an important role in the "observed" surface temperature structure through selection, absorbtion and transmission. It is elso possible that pollutants effect the representativeness of the surface temperature value on a time scale as well

158

the atmosphere to be measured. This in turn affects long period

weather forecasting.

SUPPORT OF MISSISSIPPI DELTA TEST SITE

Ground truth in the Mississippi Delta test site has been obtained in the past due to a combination of luck and persuasion. Research vessels are scheduled a year in advance; whereas, aircraft missions are scheduled quarterly. Since the principle investigators in Space Oceanography are not funded specifically for the maintenance of a fleet of vessels for use in the test site, vessels must be requested from the institutions under which they are controlled and many times the press of other research precludes their use at any given time and place. Apparently, the only solution is for funding to be made available for the leasing or purchasing of research ships specifically to be used to support the ground truth program of the Earth Resources Survey Program. Purchase of a fleet would involve a high initial capital investment; however, since the business of studying Earth from space is probably here to etay, the long-term economics of such a move fully justifies the initial investment. This needed fleet is not in existence today, and it is unreasonable to expect that the current fleet of oceanographic research vessels could do much to relieve the situation.

It appears that our ground truth problems lie not in the instance of the instruments but in the nonavailability of the vessels on which to carry these instruments.

157

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SPECIFIC RECOMMENDATIONS

159

Ship support

Since the major deficiency in ground truth support is simply lack of ship support it is recommended that NASA acquire the use of at least five support vessels to be used specifically for ground truth support during the next 5 to 10 years in this program. Furthermore it is recommended that these vessels be of the type used by the offshore oil platforms for logistic support. These ships are relatively inexpensive and available for either purchase or lease and lend themselves to the module concept of instrumentation. "Module" refers to the construction of instrumented vans which can be used in a wanner to provide great flexibility. This concept has been successfully used by the Westinghouse Corporation on board their ship which supports their deep submergence program. Discussions with personnel from this ship revealed that the van system is very seaworthy and flexible. We estimate that each vessel with a basic suite of instrumented modules will cost about two million dollars initially. Annual operating costs will be in the range of three quarters of a million dollars. If the ship is leased the initial costs will be much lower though on a prolonged operational basis it may be cheaper to purchase them outright.

The five ships should be stationed where they can give the exisum flexibility in support of oceanic requirements for ground truch. It is recommended that Woods Hole, Hismi, Texas AAM, Scripps, and Washington each have the management responsibility for one ship. In this way when the ships are not actually supporting a mission they could be out investigating oceanic features.

International cooperation

NASA cannot afford to meet all ground truth requirements throughout the world ocean. Nugotiations should begin now on a program of international cooperation in ground truth and space oceanographic data sharing. By using international oceanographic vessels with some specialized instrumentation furnished by NASA the ground truth requirements for extensive world wide oceanic areas could be met.

The current planning for this type of program for the governments of Mexico and Brazil by NASA indicates steps in the right direction. Due to the closeness of the first Earth Resources Survey space mission, a rapid acceleration of this effort is necessary to insure that several nations will be able to support this program.

Suitcase instrumentation

It is recommended that NASA let a contract to develop a portable ground truth instrumentation package. Such units will be very effective in meeting requirements where several data points are required or where remearch vessels are not available.

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Calibration standards

NASA should establish uniform calibration standards for all ground truth instrumentation developed under this program. This will insure that all instrumentation systems are compatible and checked against the same standard. Systems' specification and procurement should be under the supervision of a select group of environmental sensor experts. Total integration of all systems can be developed by applying the systems analysis approach to this effort.

161

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SUMMAR"

The lack of research wessels available for specific support of ground truth requirements of remote sensor studies of the ocean is the principal limiting factor in the Spacecraft Oceanography Program. The current fleet of research wessels cannot support the extra demands of this program nor are they readily available for the addition of the sophisticated instrumentation systems necessary to support this work. The only satisfactory answer is to add new ships to the U.S. research wessel fleet that are specifically earmarked for support of SPOC. In addition, provisions should be made for a simplified instrumentation package that could be placed on existing ships, ships of opportunity and other platforms when the regular ground truth vessels were not available or where more data points were required.

The soundest procedure is to consider the ship procurement and instrumentation installation as a ground truth support system. This should insure full compatability between instrumentation systems and the other ships in this class.

Even with these ships the requirements for ground truth support world-wide will exceed any reasonable NASA capabilities. Therefore it is important that NASA rapidly develop an international cooperative space oceanography program using our remote sensor platforms and the research vessels of foreign nations for ground truth support. The current Mexican-Brasilian program seems to be headed in this direction

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163

but it represents only a fraction of the effort required to enlist the aid of the world's oceanographic community.

There is no inexpensive way to obtain ground truth over and on the occan environment. If space occanography is to be part of the future space missions then there is no choice but to develop the ground truth support now. Each year that this decision is delayed will result in higher start up costs when it is finally implemented.

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A COMPARISON OF RADAR SCATTEROMETRY FOR 28 TO 30-ENOT WINDS OBTAINED OFF NEWFOUNDLAND WITH DATA FOR 16 TO 20-ENOT WINDS OBTAINED AT ARGUS ISLAND AND OVER THE GULF STREAM

169

(Preliminary Analysis) Dr. W. J. Pierson, New York University

Data

Thirty-two plots of radar scattering cross section versus incidence angle in degrees were obtained with the NASA-MSC 13.3 GHz (2 cm wavelength) scatterometer during two flights on the CV240 based at Argentia, Newfoundland, (Mission 60). The flights were on 31 October 1967. Flight I was from 1551Z to 1823Z with a target area at $45^{\circ}N$ 55°W, and Flight II was from 2059Z to 2320Z with a target area at $45^{\circ}30^{\circ}N$ and $50^{\circ}30^{\circ}W$. These data are compared with data obtained by the same radar with the same sircraft near Bermuda on 7 March 1966 over the Gulf Stream on 12 October 1966.

Comparison of the 32 plots with wind data and wave hindcasts for region overflown

The winds over the area of interest shifted from a southerly direction to a northeasterly direction after 182 30 October, and were northeasterly from OOZ 31 October to OOZ 1 November. Graphs of the estimated wind speed at the two target areas for the 24-bour period encompassing the two flights are shown in Figure 1. The wind speed over the two target areas was essentially the same at the time of the overflight (shown by the arrows) and was somewhere between 28 to 30 knots.

The weather and wind patterns during the flight were rather confused comparsi to the more fully developed patterns that can occur, and it would be difficult to state precisely the overall nature of the wind field over the complete tracks of the aircraft. An appendix by Mr. Lionel Moskowitz describes the weather pattern and operational decisions.

Plots numbered 1 to 18 correspond to Flight I Target I. The essential feature of these plots is that the crosswind plots, no matter where taken, are all essentially equal throughout the entire flight. These plots are numbered as follows: 1, 2, 5, and 14 to 17. Plot No. 18 is close to the coast and runs from 2 to 3 db lower than the others. The upwind-downwind plots are again almost all essentially equal and run about 4 db higher than the crosswind plots. These correspond to plots 3, 4, and 7 through 13. Plots 19 to 34 correspond to Flight II Target II. Plots 19, 20, 21, and 24 to 29 in the crosswind direction are all alike and essentially the same as 1, 2, 5, and 14 to 17. Plot 23 in the upwind-downwind direction is the same as plots 3, 4, and 7 through 13. Plot 19 is for nearly the same point as plot 18 and suggests that plot 18 may be anomalous.

Plots 30 to 34 all show a 2 to 3 db drop when compared to all other crosswind plots and suggest that the waves and winds may have decreased during the last part of the last flight; that is, around 2200 to 2300 on 31 October.

The wind data from the area suggest that the wind was essentially the same over each target area at the time of the respective overflights and that it was northeasterly at a speed of about 28 to 30 knots. The significant wave height was about 13 feet.

Figure 2 shows plot no. 4 for fore-aft scatter and plot no. 5 for crosswind acatter as being the closest to Target 1.

Comparison with Gulf Stream and Argus Island data

Mission 34 over the Gulf Stream and the flights near Argus Ialand (Mission 20) provided the same kind of plots for lower wind speeds and lower waves. The plots for both situations are essentially the same for incidence angles from 5 to 20 degrees, and the argues Ialand data extend to 55 degrees. The waves measured over the Gulf Stream were scewhere between 4.8 and 5.4 feet, which corresponds to a wind from 16.2 to 17.2 inots. The waves measured at Argus Island were 7.4 feet, which corresponds to a wind of 20.2 inots. However, the spectrum at Argus Island suggests some swell, and if this is removed to recover the wind see spectrum, the winds near Argus Island could have been as 10w as 19 knots. The data for both missions have been combined in one single plot in Figure 2.

We are tans able to compare the two sets of data, one for waves from 5 to 7 feet high, (more probably from 5 to 6 feet), and winds from 16 to 20 knots, (more probably 17 to 19 knots), and one for waves about 13 feet high and winds from 28 to 30 knots as shown in Figure 2.

For all incidence angles greater than 10° , the curves for higher winds and waves lie above the curves for lower winds and waves. The separation is 6 db at 15° and as much as 12 db at 55° . There is every indication that the trend could continue were these plots obtained for even higher winds and waves.

Comparisons of other available sea backscattered data

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To show the changes in the normalised backscattering cross section as a function of incidence angle $\sigma_0(\theta)$ for sea return, certain available and appropriate published data were plotted for comparison in Figure 3.

The data used for comparison with the Mission 60 data were taken by the Narsa Research Laboratory (NRL) with a vertically polarised L-band radar at 8.91 GHs. The NRL sea return data were taken roughly two years ago at Sea States 2, 3, and 4, where most of the $\sigma_{c}(\theta)$ information presented was in the range $30^{\circ} \lesssim \theta \lesssim 85^{\circ}$. This range, however, is of vital interest since it can be correlated to wave baight or sea roughness. It must be noted that the NRL radar is at a slightly lower frequency than the NAL 13.3 GHz scatterometer.

All of the Sea State 4 data were taken on Mission 60, 3! October 1967, with the 13.3 CHz scatterometer. The Sea State 5 $\sigma_{\rm c}$ plots annow upwind UW (or forward antenna beam), downwind DW (or aft antenna beam), and crosswind CM (forward and aft-beam) information in the angular range 5 to 60 degrees. The NRL $\sigma_{\rm c}$ data are shown for Sea State 2 for $0 \le 0 \le 30^\circ$ for Sea State 3 for $30^\circ \le 0 \le 70^\circ$; Sea State 4, CW, $30^\circ \le 0 \le 85^\circ$; and Seu State 4, UW and DW, $72^\circ \le 0 \le 55^\circ$. The Sea State 4 data were roughly interpolated in the region $30^\circ \le 0 \le 70^\circ$ for comparative purposes.

Mission 20, Bermuda, March 1966, sea return data taken by MASA with the 13.3 GHz scatterometer, (waves around 7 fest), are shown by the beavy black dots.

Of considerable analytical significance is the large difference in the value of σ_c (db) between Sea States 3 and 4. This difference is around 14 db at $\theta = 30^\circ$, and around 20 db at $\theta = 60^\circ$ when one considers only the upwind plots. This difference certainly is sufficient to allow good resolution of wave heights for the various sea states.

It is also important to note that both the NASA scatterometer and the NRL radar transmitted vertically polarized waves and received in the vertical mode VV. Additional information can be obtained in the horizontally polarized transmit-receive mode HH as well as the cross-polarized modes TH or HV.

As a final consideration, even though the late were taken from different sources and experiments, the plots and trands are clear and consistent particularly for angles greater than 30 degrees.

Conclusions and recommendations

The measurements for higher winds and waves follow the trend predicted by previous observations. Whether the plots are more nearly representative of wave height or local wind, speed cannot be decided on the basis of this one experiment. More observations for even higher winds and waves and for situations where strong winds hlow directly offshore instead of parallel to the cost are needed to resolve these difficulties.

PPENDIX

Forecast and hindcast data

At 12002 on 31 October, the southern coast of Newfoundland was under the influence of a pressure gradient yielding winds of 20 knots from 040 degrees. Offshors wind speeds were significantly greater. (approximately 30 knots). The USGGC CASCO (45.8N, 53.9N) reported 29-knot winds and 14-foot seas. On the basis of the synoptic situation and the CASCO's report as an impetus, a "go" condition was decided upon. The target point 45N, 55W was selected, this point being chosen because it would remain under the influence of the prevailing synoptic conditions and it would afford a leaver in the flight time should the wind system collapse repidly. A preliminary forecast of 28-knot winds from 060 degrees associated with 13-foot seas (significant wave height) was initially forecast. These forecasted values at the target Station Argentia.

After a "go" situation was determined and after flight plans had already been scheduled by the flight operations people, a phone call was received from L. Gratham of NAYOCEANO. From this call it was determined that the forecasters of ESSS concur on a "go" situation. The alreaft, airborne at 15522, proceeded with its mission and arrived over the target at about 17002 and returned at 13252.

Prior to the return of the aircraft, it was decided to run a second mission, although the synoptic pattern was rapidly breaking down and seas did not apear to be as high nor wind speeds as strong as during the first mission. The second target, approximately 25 miles SE of Cape Race, was at 45.5%, 50.5%. The sea state was forecasted to be 9-10 feet.

Winds were approximately 24 knots from 060 degrees. The second mission attempted to gather continuous scatterometer data from the coast to the target. The aircraft flew out and back at an altitude of 8000 feet. For the first mission, the aircraft flew out at 8000 feet and back at 15,000 feet. The aircraft was over the second target at about 22002. The cloud cover was overcast thin stratus with bases at 1500 feet and tops at about 3500 feet for both flights.

Hindoasts were prepared upon return to Washington, D.C., using more complete data. The results for Target I: $H_1/3 = 12-13$ feet from 060 degrees. The results for Target II: $H_1/3 = 12-13$ feet also from 060 degrees. Mater temperatures were approximately 50°F for both missions. Air and see point temperatures were, also, approximately 50°F. Water depth at Target I was over 400 fathoms and at Target II was approximately 50°F. Water depth at Target I was over 400 fathoms and at Target II was approximately 40 fathoms. It should be pointed out that the water depth at Target I is non-representative of the general area only a few miles away. The contours off the south, southeast, and east consts of Newfoundland are rather flat (approximately 40-50 fathoms) for at least 150 miles. The first target falls just outside the flat area.



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