

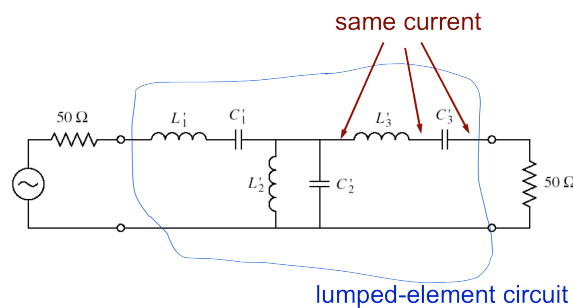
ECE 391

supplemental notes - #1

Lumped vs. Distributed Circuits

Lumped-Element Circuits:

- Physical dimensions of circuit are such that voltage across and current through conductors connecting elements does not vary.
- Current in two-terminal lumped circuit element does not vary (**phase change or transit time are neglected**)



Lumped vs. Distributed Circuits

Distributed Circuits:

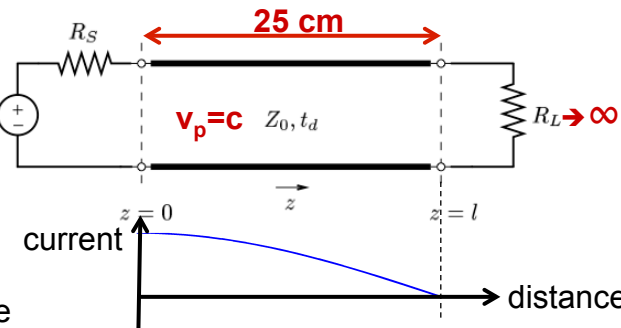
- Current varies along conductors and elements;
 - Voltage across points along conductor or within element varies
- phase change or transit time **cannot be neglected**

Example:

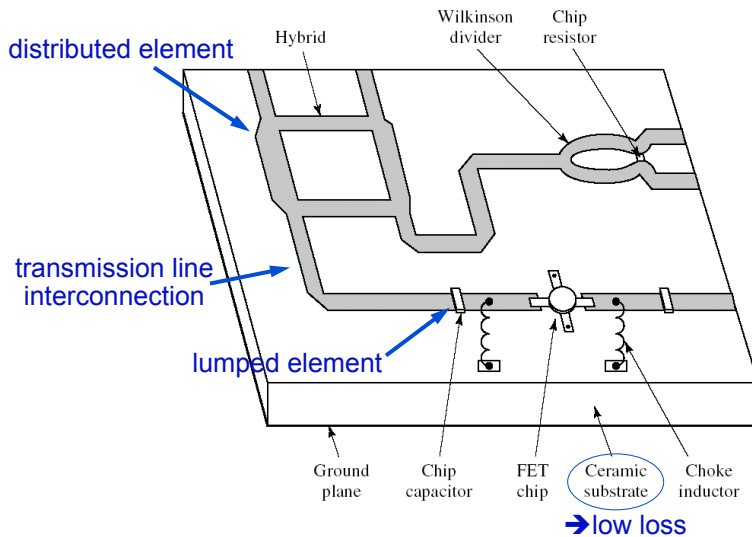
$f = 300\text{MHz}$ $v_S(t)$

$$\lambda = \frac{c}{f} = \frac{3 \times 10^8 \frac{\text{m}}{\text{s}}}{300 \times 10^6 \frac{1}{\text{s}}} = 1\text{m}$$

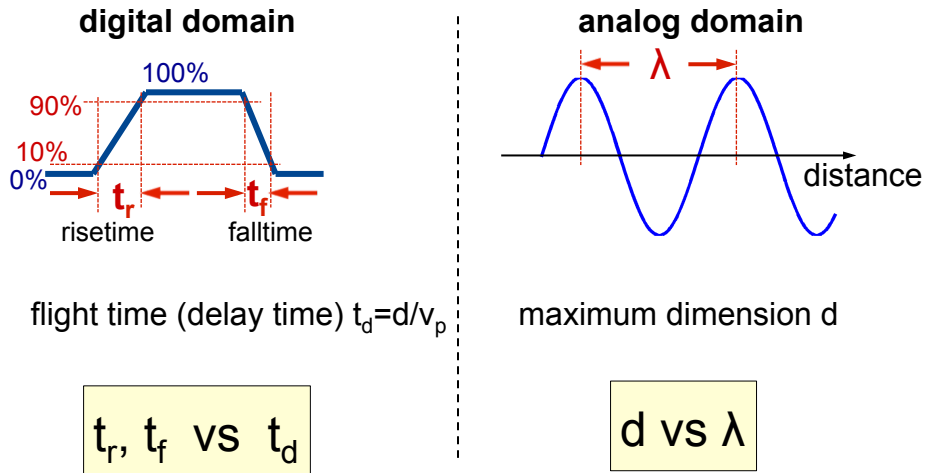
wavelength λ
= 1 period in space



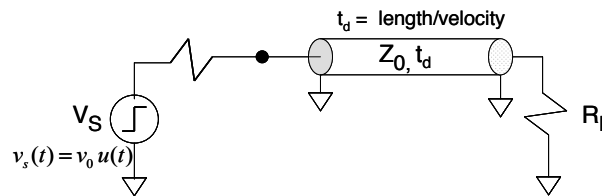
Example: Hybrid Microwave Integrated Circuit (MIC)



When Do We Need to Consider Transmission Lines Effects



Lumped vs. Distributed



- **Rule-of-thumb (heuristic)**
 Delay time $t_d = \text{length of line} / \text{velocity}$
 Rise time of signal t_r (fall time t_f)

Signal path can be treated as

lumped element
 if $t_r/t_d > 6$

distributed element
 if $t_r/t_d < 2.5$

Example

- CMOS Buffer with $t_r = t_f = 0.5$ ns
- FR-4 PCB (velocity ≈ 0.45 c)

• Note:

$$v_p \approx c / \sqrt{\epsilon_r}$$

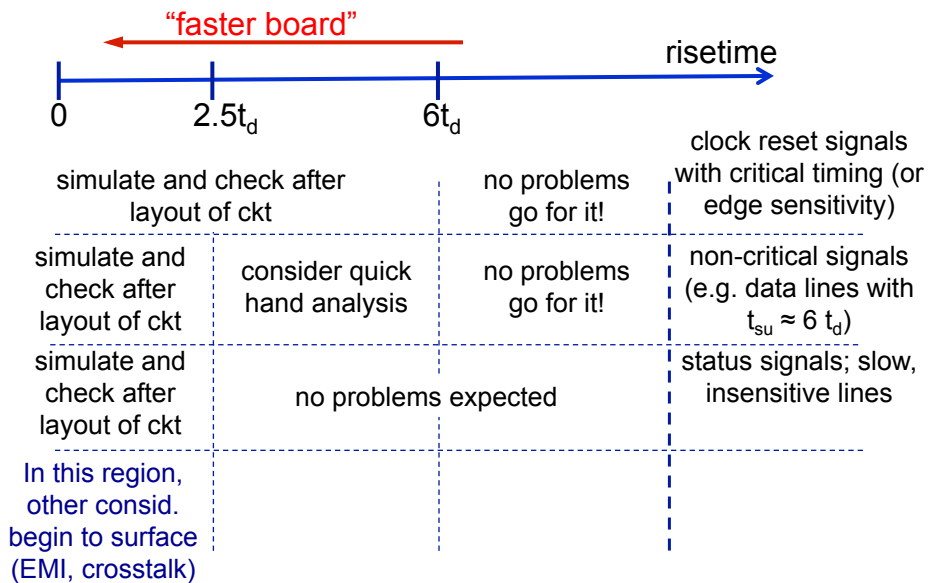


Determine maximum distance d so that $t_r/t_d > 6$

$$t_r/t_d = t_r/(d/v_p) > 6 \quad \rightarrow \quad d < t_r v_p/6$$

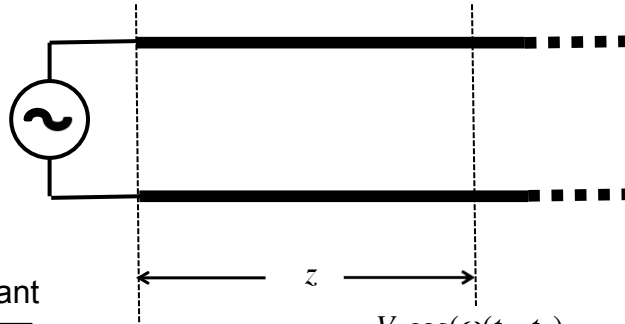
$$d < 0.5\text{ns} * (0.45*30\text{cm/ns})/6 = 1.125 \text{ cm} \approx \mathbf{11 \text{ mm}}$$

TL Problem Classification



Sinusoidal Signals

$$V_0 \cos(2\pi ft) \\ = V_0 \cos(\omega t)$$



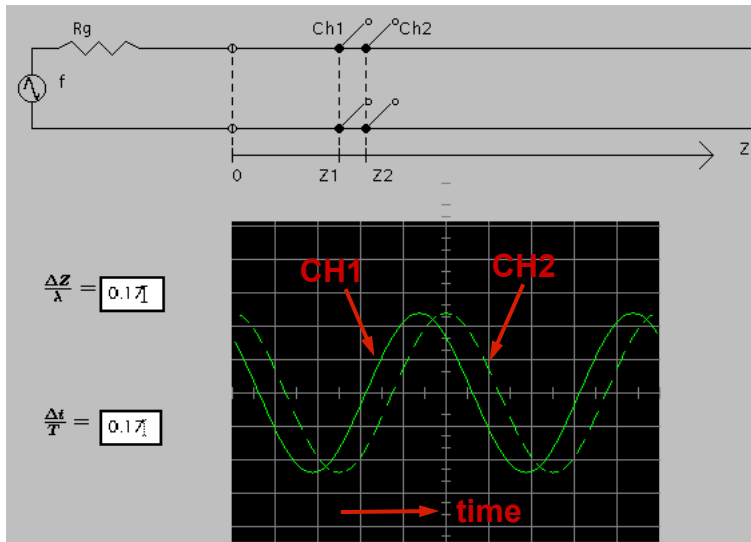
phase constant

$$\beta = \frac{\omega}{v_p} = \frac{2\pi}{\lambda}$$

$$V_0 \cos(\omega(t - t_d)) \\ = V_0 \cos(\omega t - \omega t_d) \\ = V_0 \cos(\omega t - \omega \frac{z}{v_p}) = V_0 \cos(\omega t - \beta z)$$

In practice: lumped if $t_d < 0.1 T$ ($d < 0.1 \lambda$)
safely lumped if $d < 0.01 \lambda$

Illustration



$$\frac{\Delta z}{\lambda} = 0.1 \lambda$$

$$\frac{\Delta t}{T} = 0.1 \lambda$$

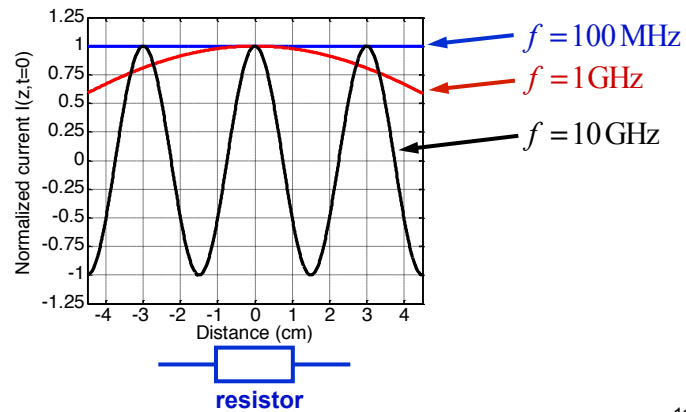
Example: Lumped vs. Distributed

For example, the spatial dependence z of the current

$$i(z,t) = I_0 \cos(\omega t - \beta z)$$

in a conductor can be neglected if $z/\lambda \ll 1$.

Example:



Concept: Electrical Length

- Electrical length (θ , E) is a measure of the physical length expressed in terms of wavelength λ

$$\theta = E = 2\pi \frac{z}{\lambda} \quad (\text{in radians})$$

$$\theta = E = 360^\circ \frac{z}{\lambda} \quad (\text{in degrees})$$

$$E = \frac{z}{\lambda} \quad (\text{as fraction of wavelength})$$

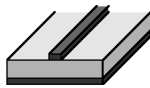
Transmission Line Examples



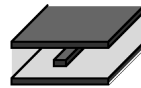
coaxial line



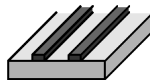
two-wire line (also twisted-pair)



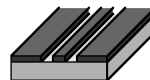
microstrip



stripline



coplanar strip (CPS)

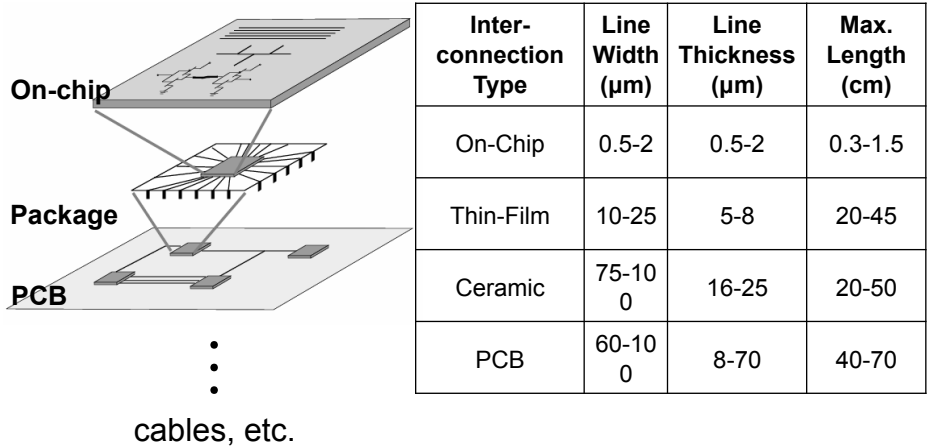


coplanar waveguide (CPW)

Transmission Lines/Interconnects

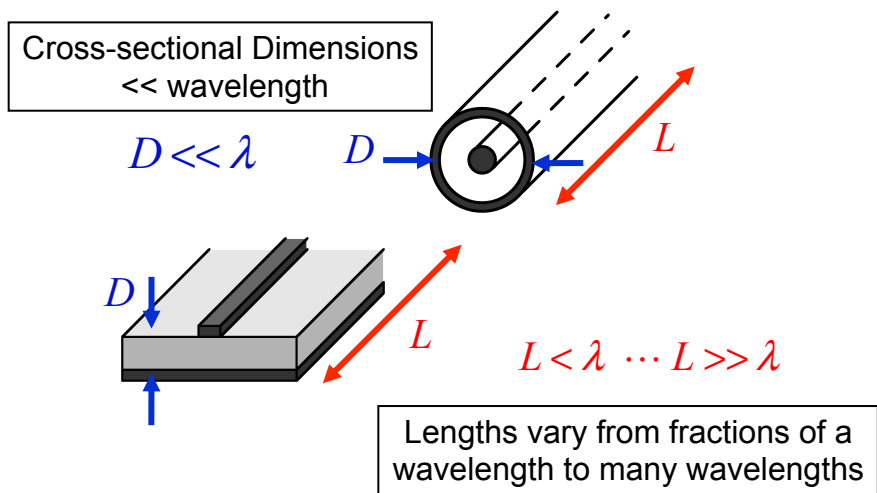
- What is a transmission line?
 - lumped vs. distributed circuit?
 - how many conductors?
- Types of transmission lines
 - on-chip (→ transmission line?)
 - off chip
 - PCB, packages
 - cables (coax, twisted pair, ...)
 - etc.
- Applications of transmission lines
 - interconnections
 - signal transmission
 - power transmission
 - circuit elements/functional components (at high frequencies)
 - filters (e.g. coupled lines, stubs, ...)
 - couplers
 - power dividers
 - matching networks
 - ...

Interconnect Technologies

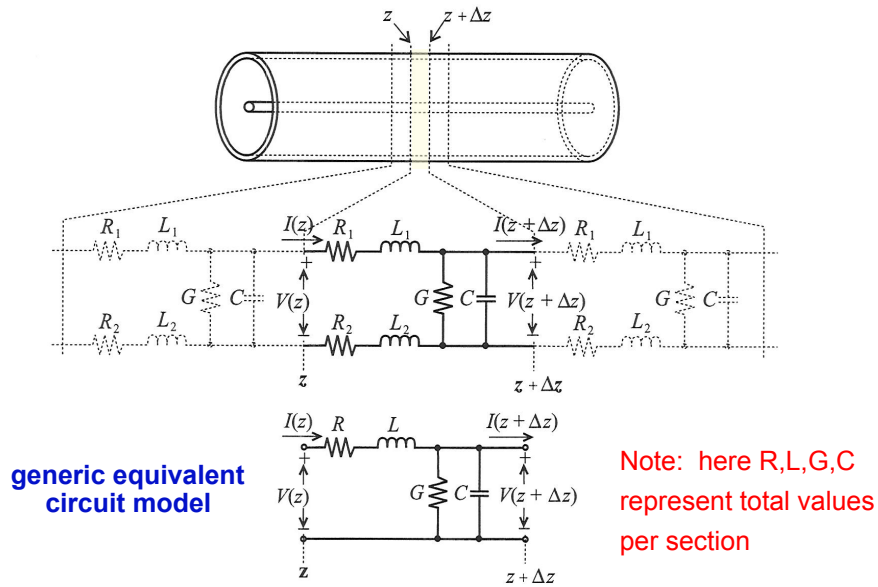


Source: IBM (plus changes)

Transmission Line – Characteristic Dimensions



Model for Transmission Line



Transmission Line Parameters

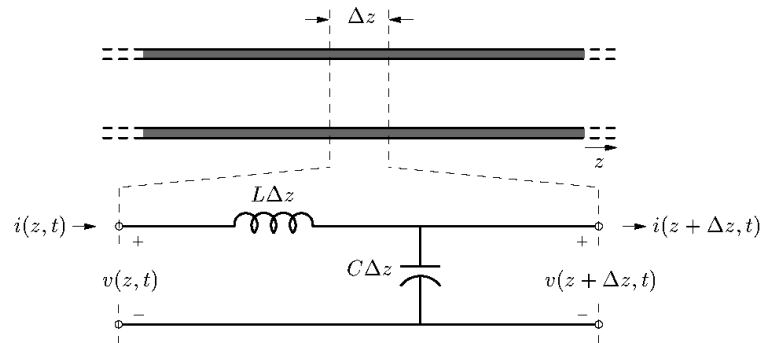
Cross-sectional view of typical **uniform** interconnects:



- Capacitance between conductors, C (F/m)
- Inductance of conductor loop, L (H/m)
- Resistance of conductors (conductor loss), R (Ω/m)
- Shunt conductance (dielectric loss), G (S/m)

➔ R, L, G, C are specified as **per-unit-length** parameters

Derivation of Transmission Line Equations



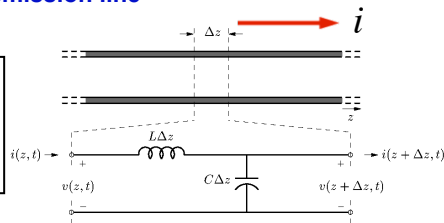
$$\begin{aligned}
 -[v(z + \Delta z, t) - v(z, t)] &= L\Delta z \frac{\partial i(z, t)}{\partial t} \\
 -[i(z + \Delta z, t) - i(z, t)] &= C\Delta z \frac{\partial v(z + \Delta z, t)}{\partial t}
 \end{aligned}$$

Note: here L, C are per-unit-length parameters

Transmission Line Equations

Lossless transmission line

$$\begin{aligned}
 -[v(z + \Delta z, t) - v(z, t)] &= L\Delta z \frac{\partial i(z, t)}{\partial t} \\
 -[i(z + \Delta z, t) - i(z, t)] &= C\Delta z \frac{\partial v(z + \Delta z, t)}{\partial t}
 \end{aligned}$$



after taking $\Delta z \rightarrow 0$

Telegrapher's Equations

$$\begin{aligned}
 -\frac{\partial v(z, t)}{\partial z} &= L \frac{\partial i(z, t)}{\partial t} & -\frac{\partial i(z, t)}{\partial z} &= C \frac{\partial v(z, t)}{\partial t}
 \end{aligned}$$

Wave Equations

$$-\frac{\partial v(z,t)}{\partial z} = L \frac{\partial i(z,t)}{\partial t} \quad -\frac{\partial i(z,t)}{\partial z} = C \frac{\partial v(z,t)}{\partial t}$$

Wave Equations

$$\frac{\partial^2 v(z,t)}{\partial z^2} = LC \frac{\partial^2 v(z,t)}{\partial t^2} = \frac{1}{v_p^2} \frac{\partial^2 v(z,t)}{\partial t^2}$$

$$\frac{\partial^2 i(z,t)}{\partial z^2} = LC \frac{\partial^2 i(z,t)}{\partial t^2} = \frac{1}{v_p^2} \frac{\partial^2 i(z,t)}{\partial t^2}$$

General Wave Solutions

$$\frac{\partial^2 v}{\partial z^2} = LC \frac{\partial^2 v}{\partial t^2} = \frac{1}{v_p^2} \frac{\partial^2 v}{\partial t^2}$$

General Solution for Voltage

$$v(z,t) = v^+(z - v_p t) + v^-(z + v_p t)$$

$$= v^+(t - z/v_p) + v^-(t + z/v_p)$$

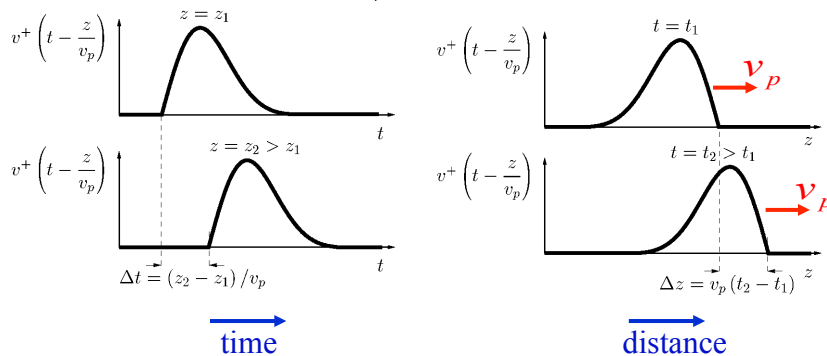
+z direction

-z direction

Velocity of Propagation $v_p = \frac{1}{\sqrt{LC}}$ (m/s)

Illustration of Space-Time Variation of Single Traveling Wave

$$v(z, t) = v^+(z - v_p t) + v^-(z + v_p t) \\ = v^+(t - z/v_p) + v^-(t + z/v_p)$$



Wave Solutions for Current

$$i(z, t) = i^+(t - z/v_p) + i^-(t + z/v_p)$$

$$-\frac{\partial v(z, t)}{\partial z} = L \frac{\partial i(z, t)}{\partial t} \quad -\frac{\partial i(z, t)}{\partial z} = C \frac{\partial v(z, t)}{\partial t}$$

$$\frac{1}{v_p} \{v^+(t - z/v_p) - v^-(t + z/v_p)\} = L \{i^+(t - z/v_p) + i^-(t + z/v_p)\}$$

$$\frac{1}{v_p} \{i^-(t - z/v_p) - i^+(t + z/v_p)\} = C \{v^+(t - z/v_p) + v^-(t + z/v_p)\}$$

$$i(z, t) = \frac{v^+(t - z/v_p)}{Z_0} - \frac{v^-(t + z/v_p)}{Z_0}$$

Characteristic Impedance $Z_0 = v_p L = \frac{1}{v_p C} = \sqrt{\frac{L}{C}} \text{ } (\Omega)$

Summary of Transmission Line Parameters

- Capacitance per-unit-length C (F/m)
- Inductance per-unit-length L (H/m)
- Characteristic impedance Z_0 (Ω)
- Velocity of propagation v_p (m/s)
- Per-unit-length delay time $t_p = 1/v_p$ (s/m)
- Delay time (TD) $t_d = l/v_p = lt_p$ (sec)

$$Z_0 = \sqrt{\frac{L}{C}} \quad v_p = \frac{1}{\sqrt{LC}} \quad t_p = \sqrt{LC} \quad t_d = l\sqrt{LC}$$

$$L = Z_0/v_p = Z_0 t_p \quad C = 1/(Z_0 v_p) = t_p/Z_0$$

Properties of Ideal Transmission Lines



- **C** from 2D electro-static solution
- **L** from 2D magneto-static solution
- **Velocity of propagation**

$$v_p = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{\mu_0 \mu_r \epsilon_0 \epsilon_r}} = \frac{c_0}{\sqrt{\epsilon_r}}$$

(neglecting magnetic materials)

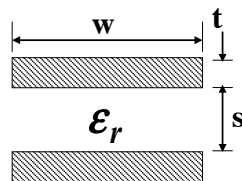
$c_0 \approx 30 \text{ cm/nsec}$

Propagation Speeds for Typical Dielectrics

Dielectric	Rel. Dielectric Constant ϵ_r	Propagation speed (cm/nsec)	Delay time per unit length (ps/cm)
Polyimide	2.5 – 3.5	16-19	53 - 62
Silicon dioxide	3.9	15	66
Epoxy glass (PCB)	5.0	13	75
Alumina (ceramic)	9.5	10	103

Example T-Line Structures

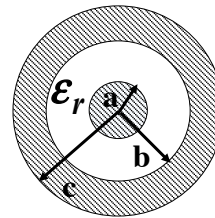
Parallel-Plate Line



$$C = \epsilon_0 \epsilon_r \frac{w}{s} \quad L = \mu_0 \frac{s}{w}$$

$$Z_0 = \sqrt{\frac{\mu}{\epsilon_0 \epsilon_r} \frac{s}{w}} \quad R_{DC} = \frac{2\rho}{wt}$$

Coaxial Line

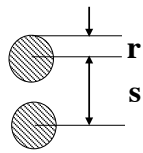


$$C = \frac{2\pi\epsilon_0\epsilon_r}{\ln(b/a)} \quad L = \frac{\mu_0}{2\pi} \ln\left(\frac{b}{a}\right)$$

$$Z_0 = \sqrt{\frac{\mu}{\epsilon_0\epsilon_r} \frac{\ln(b/a)}{2\pi}}$$

$$R_{DC} = \frac{\rho}{\pi a^2} + \frac{\rho}{\pi(c^2 - b^2)}$$

Examples (cont' d)

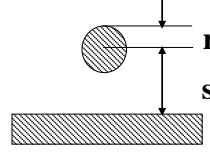


$$R_{DC} = \frac{2\rho}{\pi r^2}$$

$$C = \frac{\pi\epsilon}{\cosh^{-1}(s/2r)}$$

$$L = \frac{\mu_0}{\pi} \cosh^{-1}(s/2r)$$

$$Z_0 = \frac{1}{\pi} \sqrt{\frac{\mu_0}{\epsilon}} \cosh^{-1}(s/2r)$$



$$R_{DC} = \frac{\rho}{\pi r^2}$$

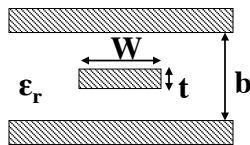
$$C = \frac{2\pi\epsilon}{\cosh^{-1}(s/r)}$$

$$L = \frac{\mu_0}{2\pi} \cosh^{-1}(s/r)$$

$$Z_0 = \frac{1}{2\pi} \sqrt{\frac{\mu_0}{\epsilon}} \cosh^{-1}(s/r)$$

Examples (cont' d)

stripline

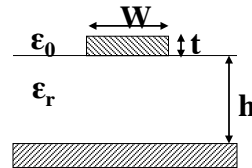


$$Z_0 = \frac{1}{4} \sqrt{\frac{\mu}{\epsilon}} \ln \left(\frac{1+w/b}{w/b+t/b} \right)$$

$$C = \sqrt{\epsilon_r} \frac{1}{c_0 Z_0}$$

$$L = \sqrt{\epsilon_r} \frac{Z_0}{c_0}$$

microstrip



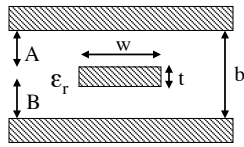
$$Z_0 = \frac{1}{2\pi} \sqrt{\frac{\mu}{\epsilon_0 \epsilon_{eff}}} \ln \left(\frac{4h}{d} \right)$$

$$d = 0.536w + 0.67t$$

$$\epsilon_{eff} \approx 0.475\epsilon_r + 0.67$$

(very approximate!)

Alternative Formulas

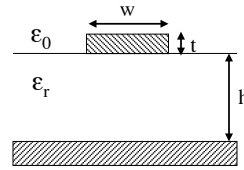


$$Z_{0, sym} = \frac{60\Omega}{\sqrt{\epsilon_r}} \ln\left(\frac{4b}{0.67\pi(t+0.8w)}\right)$$

for $w/b < 0.35$ and
 $t/b < 0.25$

$$Z_{0, offset} \cong 2 \frac{Z_{0, sym}(2A, w, t, \epsilon_r) * Z_{0, sym}(2B, w, t, \epsilon_r)}{Z_{0, sym}(2A, w, t, \epsilon_r) + Z_{0, sym}(2B, w, t, \epsilon_r)}$$

more accurate if $2A \neq 2A+t$ and $2B \neq 2B+t$



$$Z_0 = \frac{87\Omega}{\sqrt{\epsilon_r + 1.41}} \ln\left(\frac{5.98h}{0.8w+t}\right)$$

for $0.1 < w/h < 2$
and $1 < \epsilon_r < 15$