

FORMAL LANGUAGES, AUTOMATA AND COMPUTATION

TURING MACHINES

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TURING MACHINES-SYNOPSIS

- The most general model of computation
- Computations of a TM are described by a sequence of configurations.
 - Accepting Configuration
 - Rejecting Configuration
- Turing-recognizable languages
 - TM halts in an accepting configuration if w is in the language.
 - TM may halt in a rejecting configuration or go on indefinitely if w is not in the language.
- Turing-decidable languages
 - TM halts in an accepting configuration if w is in the language.
 - TM halts in a rejecting configuration if w is not in the language.

NONDETERMINISTIC TURING MACHINES

- We defined the state transition of the ordinary TM as

$$\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

- A **nondeterministic** TM would proceed computation with multiple next configurations. δ for a nondeterministic TM would be

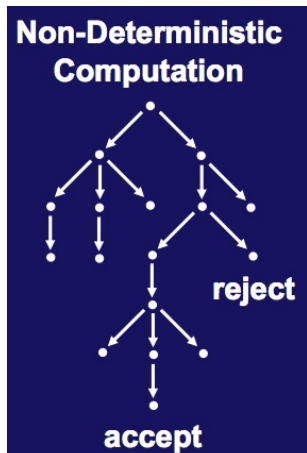
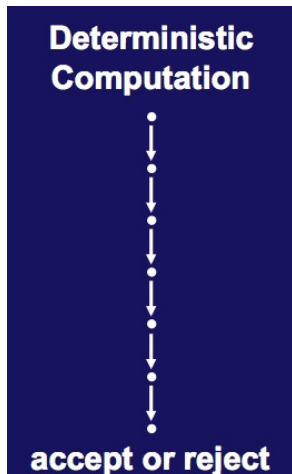
$$\delta : Q \times \Gamma \rightarrow \mathcal{P}(Q \times \Gamma \times \{L, R\})$$

($\mathcal{P}(S)$ is the power set of S .)

- This definition is analogous to NFAs and PDAs.

NONDETERMINISTIC TURING MACHINES

- A computation of a Nondeterministic TM is a tree, where each branch of the tree looks like a computation of an ordinary TM.



NONDETERMINISTIC TURING MACHINES

- If a single branch reaches the accepting state, the Nondeterministic TM accepts, even if other branches reach the rejecting state.
- What is the power of Nondeterministic TMs?
 - Is there a language that a Nondeterministic TM can accept but no deterministic TM can accept?

NONDETERMINISTIC TURING MACHINES

THEOREM

Every nondeterministic Turing machine has an equivalent deterministic Turing Machine.

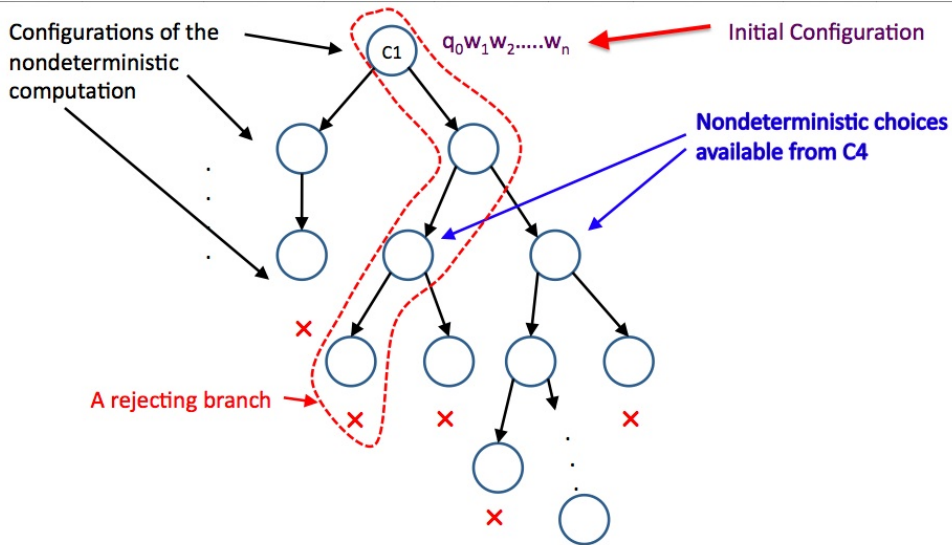
PROOF IDEA

- Timeshare a deterministic TM to different branches of the nondeterministic computation!
- Try out all branches of the nondeterministic computation until an accepting configuration is reached on one branch.
- Otherwise the TM goes on forever.

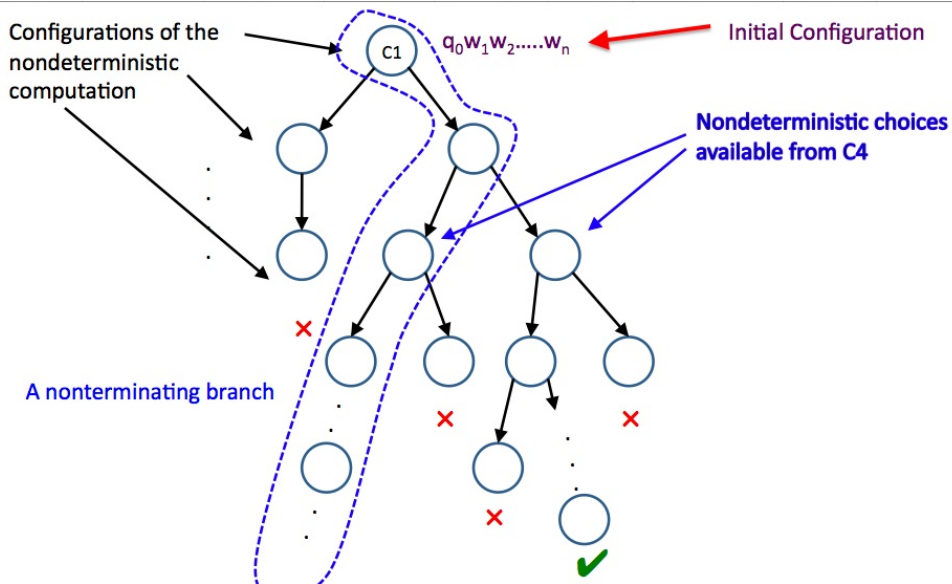
NONDETERMINISTIC TURING MACHINES

- Deterministic TM D simulates the Nondeterministic TM N .
- Some of branches of the N 's computations may be infinite, hence its computation tree has some infinite branches.
- If D starts its simulation by following an infinite branch, D may loop forever even though N 's computation may have a different branch on which it accepts.
- This is a very similar problem to processor scheduling in operating systems.
 - If you give the CPU to a (buggy) process in an infinite loop, other processes “starve”.
- In order to avoid this unwanted situation, we want D to execute all of N 's computations concurrently.

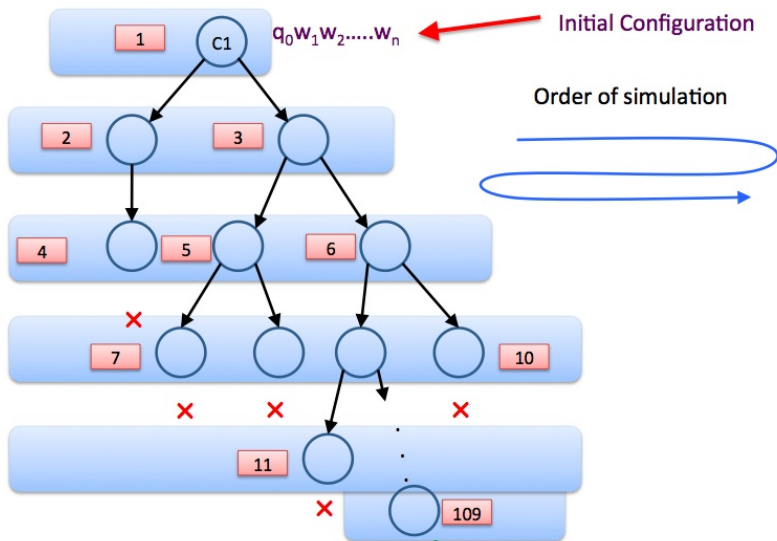
NONDETERMINISTIC COMPUTATION



NONDETERMINISTIC COMPUTATION

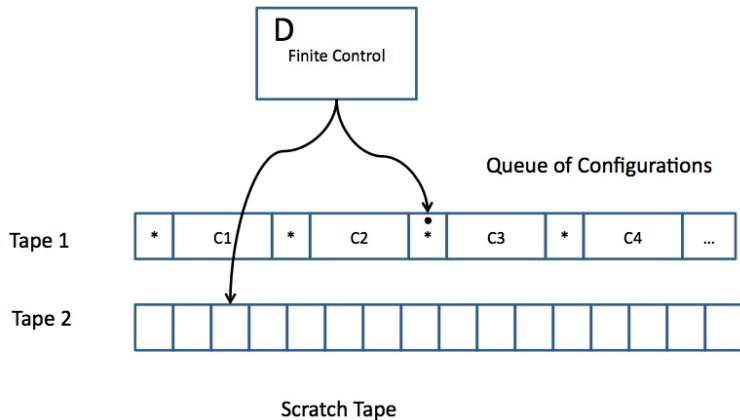


SIMULATING NONDETERMINISTIC COMPUTATION

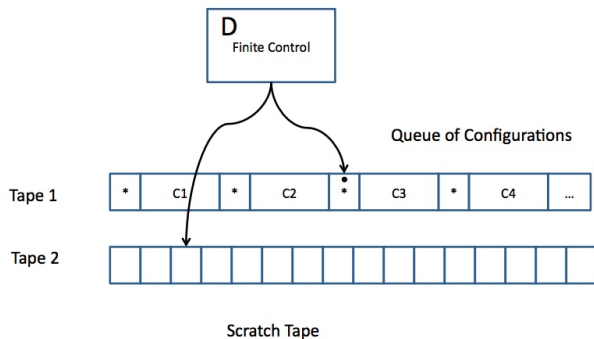


STRUCTURE OF THE SIMULATING DTM

- N is simulated with 2-tape DTM, D
 - Note that this is different from the construction in the book!

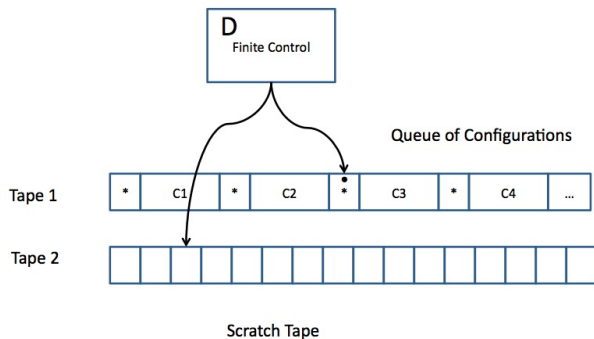


HOW D SIMULATES N



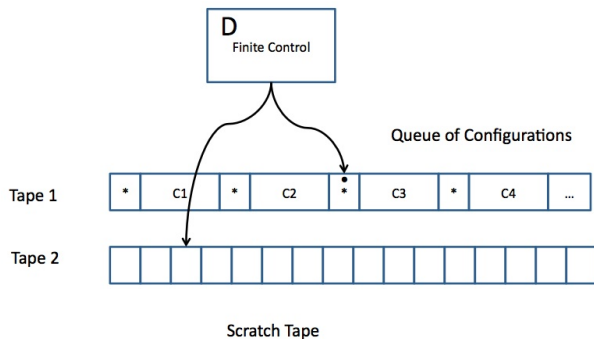
- Built into the finite control of D is the knowledge of what choices of moves N has for each state and input.

HOW D SIMULATES N



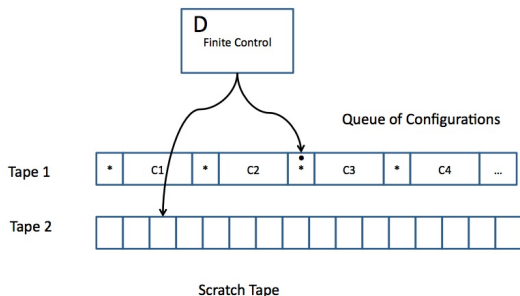
- 1 D examines the state and the input symbol of the current configuration (right after the dotted separator)
- 2 If the state of the current configuration is the accept state of N , then D accepts the input and stops simulating N .

HOW D SIMULATES N



- 1 D copies k copies of the current configuration to the scratch tape.
- 2 D then applies one nondeterministic move of N to each copy.

HOW D SIMULATES N



- D then copies the new configurations from the scratch tape, back to the **end** of tape 1 (so they go to the back of the queue), and then clears the scratch tape.
- D then returns to the marked current configuration, and “erases” the mark, and “marks” the next configuration.
- D returns to step 1), if there is a next configuration. Otherwise rejects.

HOW D SIMULATES N

- Let m be the maximum number of choices N has for any of its states.
- Then, after n steps, N can reach at most $1 + m + m^2 + \dots + m^n$ configurations (which is at most nm^n)
- Thus D has to process at most this many configurations to simulate n steps of N .
- Thus the simulation can take **exponentially** more time than the nondeterministic TM.
- It is not known whether or not this exponential slowdown is necessary.

IMPLICATIONS

COROLLARY

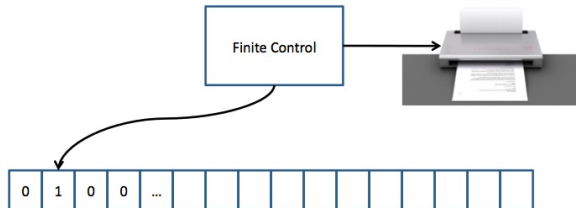
A language is Turing-recognizable if and only if some nondeterministic TM recognizes it.

COROLLARY

A language is decidable if and only if some nondeterministic TM decides it.

ENUMERATORS

- Remember we noted that some books used the term **recursively enumerable** for Turing-recognizable.
- This term arises from a variant of a TM called an **enumerator**.



- TM generates strings one by one.
- Everytime the TM wants to add a string to the list, it sends it to the printer.

ENUMERATORS

- The enumerator E starts with a blank input tape.
- If it does not halt, it may print an infinite list of strings.
- The strings can be enumerated in any order; repetitions are possible.
- The language of the enumerator is the collection of strings it eventually prints out.

ENUMERATORS

THEOREM

A language is Turing recognizable if and only if some enumerator enumerates it.

PROOF.

The If-part: If an enumerator E enumerates the language A then a TM M recognizes A .

$M =$ “On input w

- 1 Run E . Everytime E outputs a string, compare it with w .
- 2 If w ever appears in the output of E , *accept*.”

Clearly M accepts only those strings that appear on E 's list.



ENUMERATORS

THEOREM

A language is Turing recognizable if and only if some enumerator enumerates it.

PROOF.

The Only-If-part: If a TM M recognizes a language A , we can construct the following enumerator for A . Assume s_1, s_2, s_3, \dots is a list of possible strings in Σ^* .

$E =$ “Ignore the input

- 1 Repeat the following for $i = 1, 2, 3, \dots$
- 2 Run M for i steps on each input $s_1, s_2, s_3, \dots, s_i$.
- 3 If any computations accept, print out corresponding s_j .”

If M accepts a particular string, it will appear on the list generated by E (in fact infinitely many times)

THE DEFINITION OF ALGORITHM - HISTORY

- in 1900, Hilbert posed the following problem:

“Given a polynomial of several variables with integer coefficients, does it have an integer root – an assignment of integers to variables, that make the polynomial evaluate to 0”

- For example, $6x^3yz^2 + 3xy^2 - x^3 - 10$ has a root at $x = 5, y = 3, z = 0$.
- Hilbert explicitly asked that an algorithm/procedure to be “devised”. He assumed it existed; somebody needed to find it!
- 70 years later it was shown that no algorithm exists.
- The intuitive notion of an algorithm may be adequate for giving algorithms for certain tasks, but was useless for showing no algorithm exists for a particular task.

THE DEFINITION OF ALGORITHM - HISTORY

- In early 20th century, there was no formal definition of an algorithm.
- In 1936, Alonzo Church and Alan Turing came up with formalisms to define algorithms. These were shown to be equivalent, leading to the

CHURCH-TURING THESIS

Intuitive notion of algorithms \equiv Turing Machine Algorithms

THE DEFINITION OF AN ALGORITHM

- Let $D = \{p \mid p \text{ is a polynomial with integral roots}\}$
- Hilbert's 10th problem in TM terminology is “Is D decidable?” (No!)
- However D is Turing-recognizable!
- Consider a simpler version
$$D_1 = \{p \mid p \text{ is a polynomial over } x \text{ with integral roots}\}$$
- $M_1 =$ “The input is polynomial p over x .
 - 1 Evaluate p with x successively set to 0, 1, -1, 2, -2, 3, -3,
 - 2 If at any point, p evaluates to 0, *accept*.”
- D_1 is actually decidable since only a finite number of x values need to be tested (math!)
- D is also recognizable: just try systematically all integer combinations for all variables.

DESCRIBING TURING MACHINES AND THEIR INPUTS

- For the rest of the course we will have a rather standard way of describing TMs and their inputs.
- The input to TMs have to be strings.
- Every object O that enters a computation will be represented with an string $\langle O \rangle$, encoding the object.
- For example if G is a 4 node undirected graph with 4 edges $\langle O \rangle = (1, 2, 3, 4) ((1, 2), (2, 3), (3, 1), (1, 4))$
- Then we can define problems over graphs, e.g., as:

$$A = \{ \langle G \rangle \mid G \text{ is a connected undirected graph} \}$$

DESCRIBING TURING MACHINES AND THEIR INPUTS

- A TM for this problem can be given as:
- $M =$ “On input $\langle G \rangle$, the encoding of a graph G :
 - 1 Select the first node of G and mark it.
 - 2 Repeat 3) until no new nodes are marked
 - 3 For each node in G , mark it, if there is edge attaching it to an already marked node.
 - 4 Scan all the nodes in G . If all are marked, the *accept*, else *reject*”

OTHER OBJECT ENCODINGS

- DFAs: Represent as a graph with 4 components, q_0 , F , δ as a list of labeled edges.
- TMs: Represent as a string encoding δ with blocks of 5 components, e.g., q_i , a , q_j , b , L . Assume that q_0 is always the start state and q_1 is the final state.
 - Individual symbols can even be encoded using only two symbols e.g. just $\{0, 1\}$.