

Matrix 210N™

PRODUCT REFERENCE GUIDE



Image Based Reader

DATALOGIC

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Patents

See www.patents.datalogic.com for patent list.

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PREFACE

ABOUT THIS MANUAL

This Product Reference Guide (PRG) is provided for users seeking advanced technical information, including connection, programming, maintenance and specifications. The Quick Reference Guide (QRG) and other publications associated with this product can be downloaded free of charge from the website listed on the back cover of this manual.

Manual Conventions

The following conventions are used in this document:

The symbols listed below are used in this manual to notify the reader of key issues or procedures that must be observed when using the reader:



NOTE

Notes contain information necessary for properly diagnosing, repairing and operating the reader.



CAUTION

The CAUTION symbol advises you of actions that could damage equipment or property.




WARNING

The WARNING symbol advises you of actions that could result in harm or injury to the person performing the task.

TECHNICAL SUPPORT

Support Through the Website

Datalogic provides several services as well as technical support through its website. Log on to (www.datalogic.com).

For quick access, from the home page click on the search icon , and type in the name of the product you're looking for. This allows you access to download Data Sheets, Manuals, Software & Utilities, and Drawings.

Hover over the Support & Service menu for access to Services and Technical Support.

Reseller Technical Support

An excellent source for technical assistance and information is an authorized Datalogic reseller. A reseller is acquainted with specific types of businesses, application software, and computer systems and can provide individualized assistance.

COMPLIANCE

GENERAL

For installation, use and maintenance it is not necessary to open the reader.

Only connect Ethernet and dataport connections to a network which has routing only within the plant or building and no routing outside the plant or building.

POWER SUPPLY

ATTENTION: READ THIS INFORMATION BEFORE INSTALLING THE PRODUCT

This product is intended to be installed by **Qualified Personnel** only.

This product is intended to be connected to a UL Listed Computer (LPS or “Class 2”) which supplies power directly to the reader or a UL Listed Direct Plug-in Power Unit (rated 10 to 30 V, minimum 500 mA) marked LPS or “Class 2”.

EMC COMPLIANCE

In order to meet the EMC requirements:

- connect reader chassis to the plant earth ground by means of a flat copper braid shorter than 100 mm;
- connect pin “Earth” of the CBX connection box to a good Earth Ground

CE COMPLIANCE

CE marking states the compliance of the product with essential requirements listed in the applicable European directive. Since the directives and applicable standards are subject to continuous updates, and since Datalogic promptly adopts these updates, therefore the EU declaration of conformity is a living document. The EU declaration of conformity is available for competent authorities and customers through Datalogic commercial reference contacts. Since April 20th, 2016 the main European directives applicable to Datalogic products require inclusion of an adequate analysis and assessment of the risk(s). This evaluation was carried out in relation to the applicable points of the standards listed in the Declaration of Conformity. Datalogic products are mainly designed for integration purposes into more complex systems. For this reason it is under the responsibility of the system integrator to do a new risk assessment regarding the final installation.

Warning: This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

FCC COMPLIANCE

Modifications or changes to this equipment without the expressed written approval of Datalogic could void the authority to use the equipment.

This device complies with PART 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference which may cause undesired operation.

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his/her own expense.

EAC COMPLIANCE

Customs Union:

The CU Conformity certification has been achieved; this allows the Product to bear the Eurasian Mark of conformity.

LASER SAFETY

The Matrix 210N liquid lens models contain two aiming Laser LEDs used to position the reader.

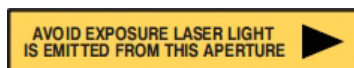
This product conforms to the applicable requirements of IEC 60825-1 and complies with 21 CFR 1040.10 except for deviations pursuant to Laser Notice N° 50, date June 24, 2007. This product is classified as a Class 2 laser product according to IEC 60825-1 regulations.



Use of controls or adjustments or performance of procedures other than those specified herein may result in exposure to hazardous visible laser light.

Disconnect the power supply when opening the device during maintenance or installation to avoid exposure to hazardous laser light. The laser beam can be switched on or off through a software command.

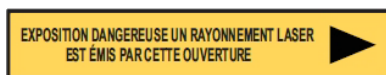
The following warning label content is applied to each of the laser equipped products indicated in the General View illustration (Figure 1).



Example Laser Warning Labels

Produit(s) conforme selon 21CFR 1040.10 sauf des dérogations relatives à la Laser Notice N° 50, data Juin 24, 2007.

Dans le paquet il y a l'étiquette(s) pour les pays où le texte d'avertissement en français est obligatoire. Le(s) mettre sur le produit à la place de la version anglaise.



Exemple d'étiquettes d'avertissement laser

LED SAFETY

LED emission according to EN 62471.

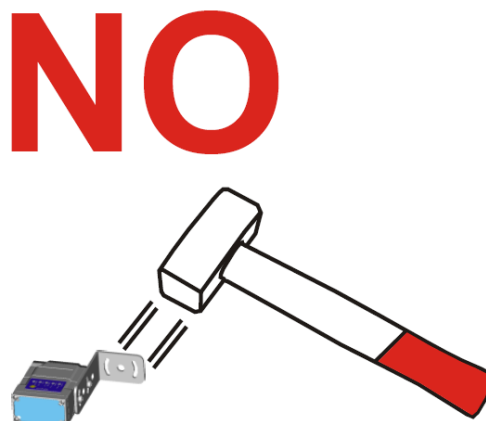
HANDLING

The Matrix 210N is designed to be used in an industrial environment and is built to withstand vibration and shock when correctly installed, however it is also a precision product and therefore before and during installation it must be handled correctly to avoid damage.

- avoid that the readers are dropped (exceeding shock limits)



- do not fine tune the positioning by striking the reader or bracket.



- do not weld the reader into position which can cause electrostatic, heat or reading window damage.



- do not spray paint near the reader which can cause reading window damage.



GENERAL VIEW

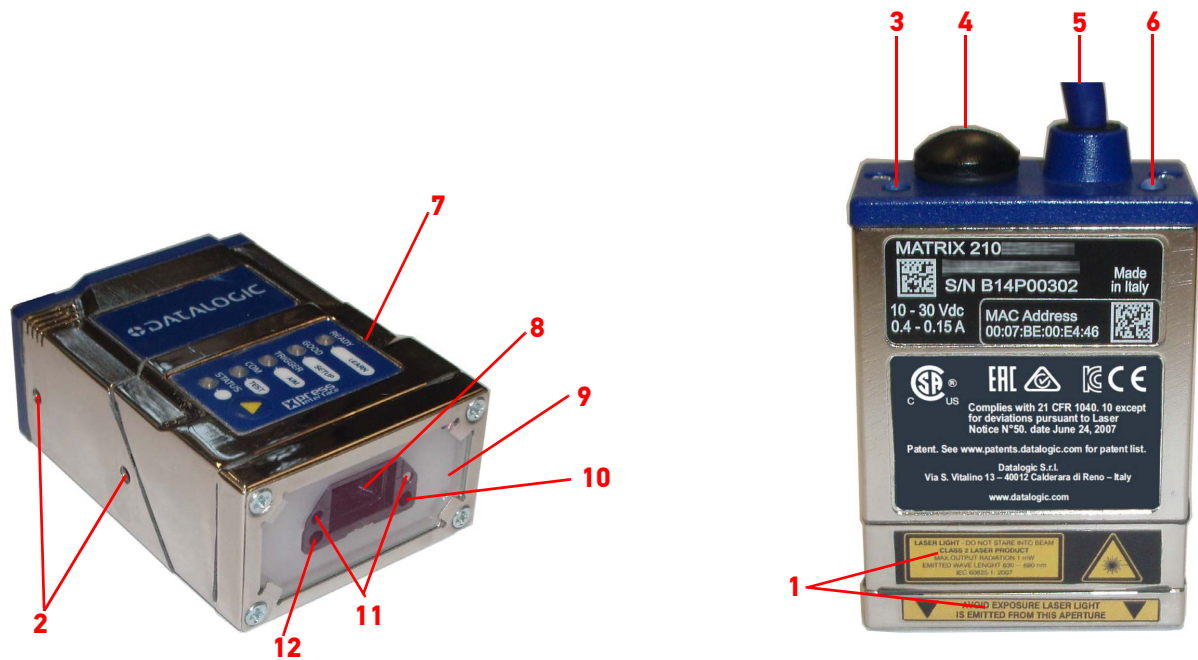


Figure 1 - Matrix 210N Software Adjustable Focus (Liquid Lens) Models

1. Device Class and Warning Labels	7. HMI X-PRESS Interface
2. Mounting Holes (4)	8. Lens
3. Ethernet Connection LED	9. Internal Illuminator
4. Ethernet Connector	10. Good Read LED Spot (green)
5. Power - Serial - I/O Cable Connector	11. Aiming System Laser Pointers
6. Power On LED	12. No Read LED Spot (red)



Figure 2 - Matrix 210N Fixed Focus Models

1. Device Labels	7. HMI X-PRESS Interface
2. Mounting Holes (4)	8. Aiming System (Blue Ring)
3. Ethernet Connection LED	9. Lens
4. Ethernet Connector	10. Internal Illuminator
5. Power - Serial - I/O Cable Connector	11. Good Read LED Spot (green)
6. Power On LED	

CHAPTER 1

RAPID CONFIGURATION

STEP 1 - CONNECT THE SYSTEM

Ethernet Connections

To connect the system in a Stand Alone configuration, you need the hardware indicated in Figure 1.

In this layout the data is transmitted to the Host from the Matrix 210N on-board Ethernet interface by using a CAB-ETH-M0x cable. There is not need to use a crossover adapter since Matrix 210N incorporates an autocross function.

Matrix 210N power and I/O device connections take place through the CBX connection box.

When One Shot or Phase Mode Operating mode is used, the reader is activated by an External Trigger (photoelectric sensor) when the object enters its reading zone.

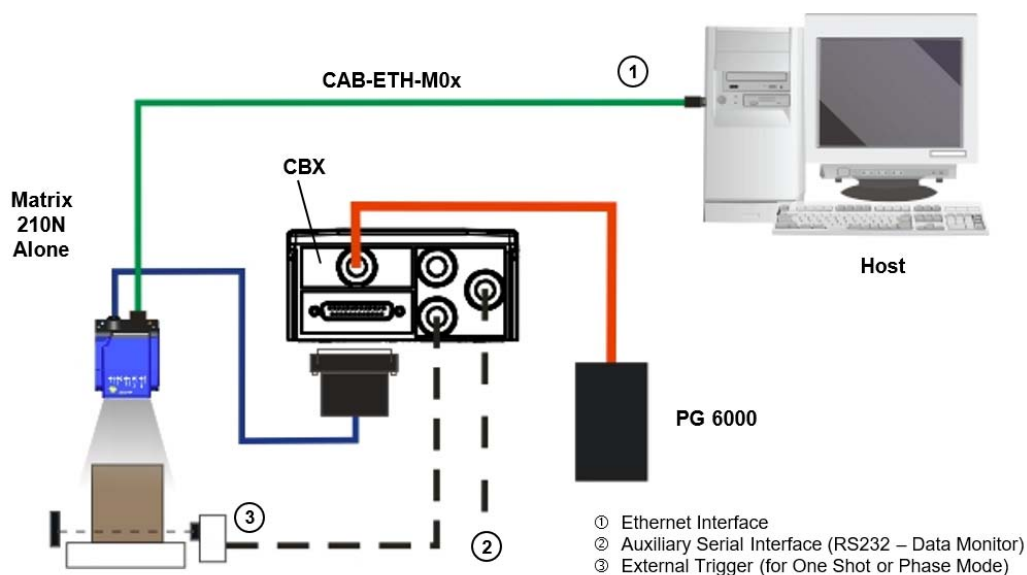


Figure 3 - Ethernet Point-to-Point Layout

USB Connections

Matrix 210N USB models can be connected in a Point-to-Point layout to a local host through their USB cable. No external power supply is necessary.

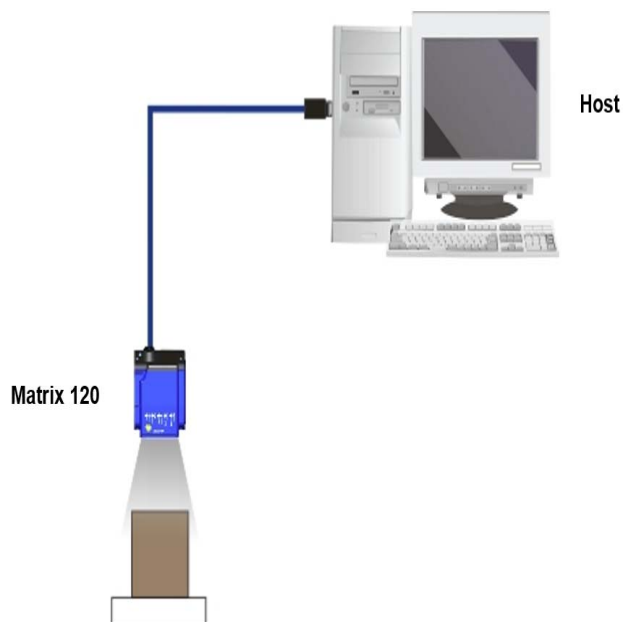


Figure 4 - Matrix 210N USB Point-to-Point Layout

Serial Connections

To connect the system in a Serial point-to-point configuration, you need the hardware indicated in Figure 5.

In this layout the data is transmitted to the Host from the Matrix 210N main serial interface.

Matrix 210N power and I/O device connections take place through the CBX connection box.

When One Shot or Phase Mode Operating mode is used, the reader is activated by an External Trigger (photoelectric sensor) when the object enters its reading zone.

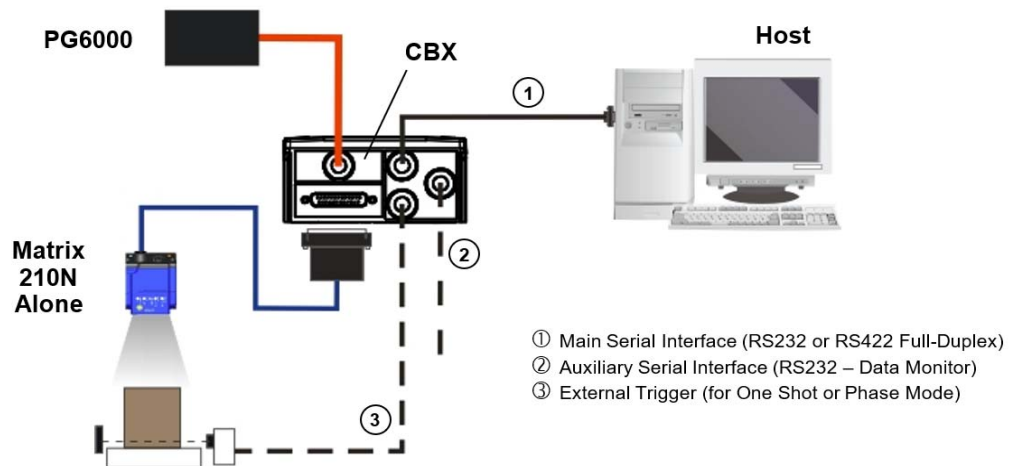


Figure 5 - Matrix 210N Serial Point-to-Point Layout



NOTE

For device configuration through DL.CODE, it is recommended to use the Ethernet interface (depending on your model).

All devices except dedicated USB models can be configured through their slower than the Ethernet interface and presents some limitations. It is recommended to use the Serial interface for configuration only if the Ethernet interface is not available.

CBX100/CBX500 Pinout for Matrix 210N

The table below gives the pinout of the CBX100/CBX500 terminal block connectors. Use this pinout when the Matrix 210N reader is connected by means of the CBX100/CBX500:

GROUP	LABEL	DESCRIPTION
Input Power	Vdc	Power Supply Input Voltage +
	GND	Power Supply Input Voltage -
	Earth	Protection Earth Ground
Inputs	+V	Power Source - External Trigger
	I1A	External Trigger A (polarity insensitive)
	I1B	External Trigger B (polarity insensitive)
	-V	Power Reference - External Trigger
	+V	Power Source - Inputs
	I2A	Input 2 A (polarity insensitive)
	I2B	Input 2 B (polarity insensitive)
	-V	Power Reference - Inputs
Outputs	+V	Power Source - Outputs
	-V	Power Reference - Outputs
	O1+	Output 1 +
	O1-	Output 1 -
	O2+	Output 2 +
	O2-	Output 2 -
Auxiliary Interface	TX	Auxiliary Interface TX
	RX	Auxiliary Interface RX
	SGND	Auxiliary Interface Reference
ID-NET™	REF	Network Reference
	ID+	ID-NET network data +
	ID-	ID-NET network data -
Shield	Shield	Network Cable Shield
Main Interface	RS232	RS422 Full Duplex
	TX	TX+
	-	TX-
	RX	*RX+
	-	*RX-
	SGND	SGND

* Do not leave floating, see [RS422 Full Duplex Interface](#)" on page 65 for connection details.



Do not connect GND, SGND and REF to different (external) ground references. GND, SGND and REF are internally connected through filtering circuitry which can be permanently damaged if subjected to voltage drops over 0.8 Vdc.

STEP 2 - MOUNT AND POSITION THE READER

1. To mount the Matrix 210N, use the mounting brackets to obtain the most suitable position for the reader. The most common mounting configuration is shown in the figure below. Other mounting solutions are provided in "Mounting And Positioning Matrix 210N" on page 59.

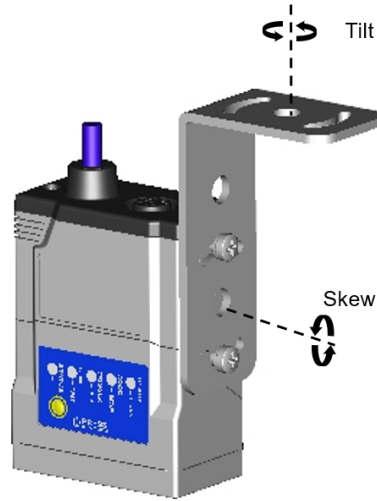


Figure 6 - Positioning with Mounting Bracket



NOTE

For applications where strong vibration or continuous bumps are present, it is recommended to use a double mounting bracket solution.

- When mounting the Matrix 210N take into consideration these three ideal label position angles: **Pitch or Skew 10° to 20° and Tilt 0°**, although the reader can read a code at any tilt angle provided the code fits into the Field Of View (FOV).

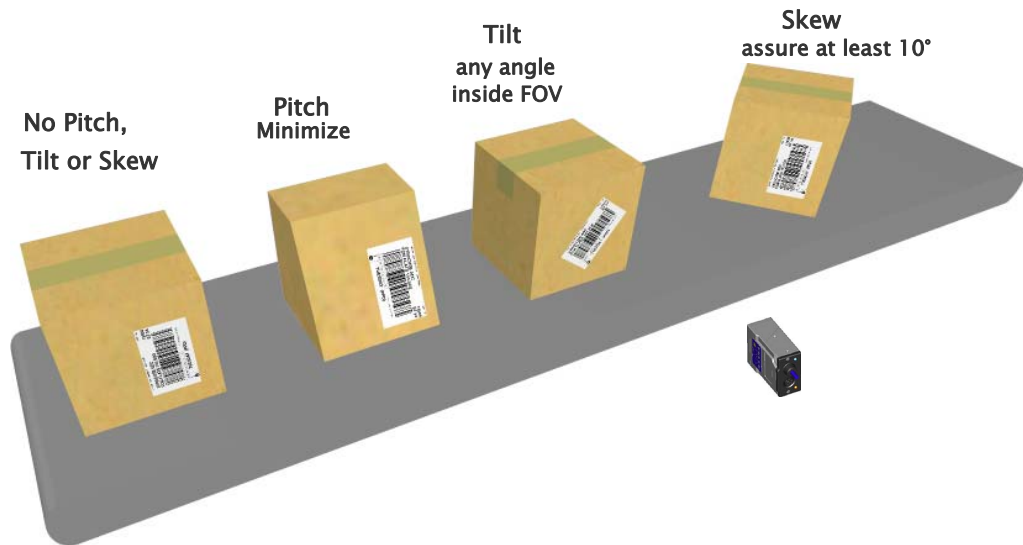


Figure 7 - Pitch, Skew and Tilt Angles

- Refer to the reading diagrams in to determine the distance your reader should be positioned at.



NOTE

Rapid Configuration of the Matrix 210N reader can be made either through the X-PRESS interface (steps 3-4) which requires no PC connection, or by using the DL.CODE Configuration Program (steps 5-6). Select the procedure according to your needs.

STEP 3 - FOCUS THE READER FOR SOFTWARE ADJUSTABLE FOCUS MODELS

Matrix 210N liquid lens models provide a built-in laser pointer aiming system to aid reader positioning. For these models the autofocus feature is also incorporated into this function. The aiming system is accessed through the X-PRESS Interface.

1. Power the reader on. During the reader startup (reset or restart phase), all the LEDs blink for one second. On the reverse side of the reader near the bracket, the "POWER ON" LED (blue) indicates the reader is correctly powered.
2. Place the **Grade A Barcode Test Chart** in front of the reader at the correct reading distance for your application. See the Global FOV Diagrams in [Chapter 6, Reading Features](#) for reference.
3. Enter the Aim/Autofocus function by pressing and holding the X-PRESS push button until the Aim LED is on.
4. Release the button to enter the Aim function. The laser pointers turn on, and the Autofocus procedure begins, see Figure 8. The Aim LED will blink until the procedure is completed.

Within 3 seconds (before the reader flashes), center one of the larger codes on the aiming system pointers (the code must not move during this procedure).

The Autofocus procedure ends when the Reading Distance and PPI values are successfully saved in the reader memory, the Aim LED will stop blinking and Matrix 210N emits 3 high pitched beeps.

If the Autofocus cannot be reached after a timeout of about 3 (three) minutes Matrix 210N will exit without saving the parameters to memory, the Aim LED will stop blinking and in this case Matrix 210N emits a long low-pitched beep.

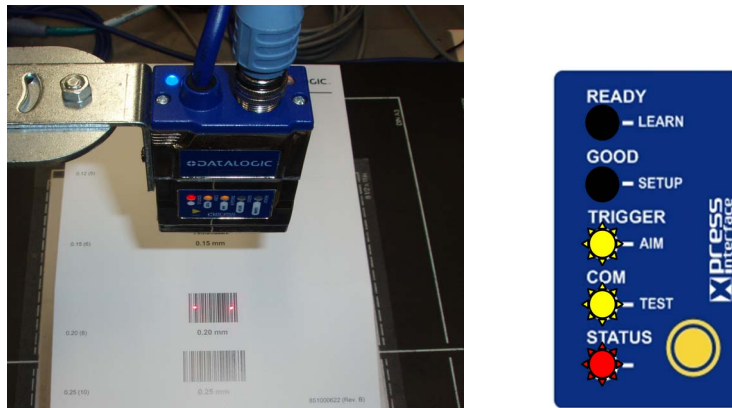


Figure 8 - X-PRESS Interface: Aim/Autofocus Function

- b. Tighten the Diaphragm Locking Knob.



NOTE

You can exit the Aim/Autofocus function at any time by pressing the X-PRESS push button once. After a short delay the autofocus procedure is canceled and the laser pointers turn off.

Once Matrix 210N is focused at the correct reading distance, you must configure it for optimal code reading relative to your application.

Aim



Figure 9 - X-PRESS Interface: Aim Function

5. Repeat the Aim function, but now position a **single code from your application** at the center of the FOV (equidistant from the laser pointers). The reader may start flashing and try to perform autofocus.
6. To avoid overwriting the distance and PPI values previously set, exit the Aim function by pressing the X-PRESS push button once. After a short delay the Aim function is canceled and the laser pointers turn off.

Setup



Figure 10 - X-PRESS Interface: Setup Function

7. Enter the Setup function by pressing and holding the X-PRESS push button until the Setup LED is on.
8. Release the button to enter the Setup function. The Setup LED will blink until the procedure is completed. The Setup procedure ends when the Image Acquisition parameters are successfully saved in the reader memory, the Setup LED will stop blinking and Matrix 210N emits 3 high pitched beeps. If the calibration cannot be reached after a timeout of about 5 (five) seconds Matrix 210N will exit without saving the parameters to memory, the Setup LED will stop blinking and in this case Matrix 210N emits a long low-pitched beep.

Learn

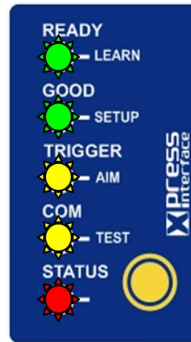
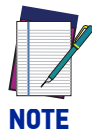


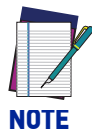
Figure 11 - X-PRESS Interface: Learn Function

9. Enter the Learn function by pressing and holding the X-PRESS push button until the Learn LED is on.
10. Release the button to enter the Learn function. The Learn LED will blink until the procedure is completed.
The Learn procedure ends when the Image Processing and Decoding parameters for **a single code** are successfully saved in the reader memory, the Green Spot is activated, the Learn LED will stop blinking and Matrix 210N emits 3 high pitched beeps¹.
If the autolearning cannot be reached after a timeout of about 3 (three) minutes Matrix 210N will exit without saving the parameters to memory, the Learn LED will stop blinking and in this case Matrix 210N emits a long low-pitched beep.



NOTE

When using X-PRESS or the BM150 menu to perform the Autolearn, only a single code can be configured (successive Learns will substitute the current code). To configure multiple code symbologies, use the DL.CODE Autolearn procedure.



NOTE

You can always exit form any X-PRESS function at any time by pressing the X-PRESS push button once. After a short delay the procedure is canceled.



NOTE

If you have used this procedure to configure Matrix 210N, go to "Step 6 - Device Configuration" on page 21.

1. The Learn procedure will not recognize the following symbologies: Postal Codes, Pharmacode, MSI, Standard 2 of 5, Matrix 2 of 5.

STEP 4 - X-PRESS CONFIGURATION FOR FIXED FOCUS MODELS

Matrix 210N fixed focus models provide a built-in aiming system to aid reader positioning. The aiming system is accessed through the X-PRESS Interface.

1. Power the reader on. During the reader startup (reset or restart phase), all the LEDs blink for one second. On the connector side of the reader near the cable, the "POWER ON" LED (blue) indicates the reader is correctly powered.
2. Enter the Aim/Locate function by pressing and holding the X-PRESS push button until the Aim LED is on.
3. Release the button to enter the Aim function. The aiming system turns on, see Figure 12.
4. Place the **application specific code** in front of the reader at the reading distance indicated for your model in the Reading Features Fixed Focus table in "[Maximum Line Speed Calculations](#)" on page 99, centering it in the aiming system indicator.

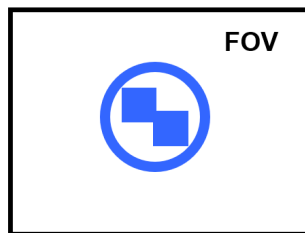


Figure 12 - Aiming Function
using the Blue Ring

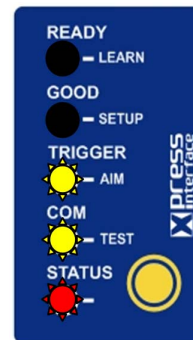


Figure 13 - X-PRESS Interface:
Aim Function

5. Exit the Aim function by pressing the X-PRESS push button once. The aiming system turns off.

Once Matrix 210N is focused at the correct reading distance, you must configure it for optimal code reading relative to your application.

Setup



Figure 14 - X-PRESS Interface: Setup Function

6. Enter the Setup function by pressing and holding the X-PRESS push button until the Setup LED is on.
7. Release the button to enter the Setup function. The Setup LED will blink until the procedure is completed.
The Setup procedure ends when the Image Acquisition parameters are successfully saved in the reader memory, the Setup LED will stop blinking and Matrix 210N emits 3 high pitched beeps.
If the calibration cannot be reached after a timeout of about 5 (five) seconds Matrix 210N will exit without saving the parameters to memory, the Setup LED will stop blinking and in this case Matrix 210N emits a long low-pitched beep.

Learn



Figure 15 - X-PRESS Interface: Learn Function

8. Enter the Learn function by pressing and holding the X-PRESS push button until the Learn LED is on.
9. Release the button to enter the Learn function. The Learn LED will blink until the procedure is completed.
The Learn procedure ends when the Image Processing and Decoding parameters for a **single code** are successfully saved in the reader memory, the Green Spot is activated, the Learn LED will stop blinking and Matrix 210N emits 3 high pitched beeps¹.

1. The Learn procedure will not recognize the following symbologies: Postal Codes, Pharmacode, MSI, Standard 2 of 5, Matrix 2 of 5.

If the autolearning cannot be reached after a timeout of about 3 (three) minutes Matrix 210N will exit without saving the parameters to memory, the Learn LED will stop blinking and in this case Matrix 210N emits a long low-pitched beep.

**NOTE**

When using X-PRESS or the BM150 menu to perform the Autolearn, only a single code can be configured (successive Learns will substitute the current code). To configure multiple code symbologies, use the DL.CODE Autolearn procedure.

**NOTE**

You can always exit from any X-PRESS function at any time by pressing the X-PRESS push button once. After a short delay the procedure is canceled.

**NOTE**

If you have used this procedure to configure Matrix 210N, go to "Step 6 - Device Configuration" on page 21.

Reset Reader to Factory Default Environment (Optional)

If it ever becomes necessary to reset the reader's Environment parameters to their factory default values, you can perform this procedure by holding the X-PRESS push button pressed while powering up the reader. **You must keep the X-PRESS push button pressed until all LEDs blink simultaneously for about 3 seconds. Release and re-press the button during this LED blinking sequence.**

All the device's Environment parameters are reset including the default IP Address. The Matrix 210N emits 3 high pitched beeps and after a few seconds enters run mode.

Any previously saved configurations on the device will remain in memory, but the Default configuration is set as the startup configuration.

**NOTE**

If you release the button while the LEDs are all on continuously (after the blinking phase), the reader will enter the Loader program sequence and the LEDs will begin to cycle through various patterns. Just cycle power to return to run mode.

STEP 5 - INSTALLING DL.CODE CONFIGURATION PROGRAM



DL.CODE does not currently support Windows Embedded (often used in industrial PCs and/or PLCs).

CAUTION

DL.CODE is a Datalogic reader configuration tool providing several important advantages:

- Intuitive Graphical User Interface for rapid configuration
- Defined configuration directly stored in the reader
- Discovery and IP address setting features to facilitate remote configuration
- Device Monitoring

To install DL.CODE

1. On the PC that will be used for configuration, (running Windows 7, 8.1, or 10), download the DL.CODE mini-DVD.zip file. Extract the files maintaining the folder structure and run the **start.hta** file to access the installation pop-up. Click on the **Install DL.CODE** link to run the installation program and follow the installation procedure.



NOTE

To configure Serial model devices, check the Matrix RS232 Serial Port Driver installation box in the Welcome window of the DL.CODE Installer. In this case it is recommended to reboot the PC after DL.CODE installation. The Matrix USB Driver selection is not for Matrix 210N devices, see "Step 5B - USB Device Discovery" on page 16.



NOTE

To perform a "silent" installation (without user input), see the DL.CODE User's Guide.

2. When the installation is complete the DL.CODE entry is created in the Start>Programs bar under "Datalogic" as well as a desktop icon. Double-click the desktop icon to run it.

Depending on your Matrix 210N model, you can connect to the DL.CODE configuration environment through one of the following interfaces:

MODEL	INTERFACE	INSTRUCTIONS
Matrix 210N xxx-x1x	Ethernet Configuration	"Step 5A - Ethernet Device Discovery" on page 14
Matrix 210N xxx-x2x	USB Configuration	"Step 5B - USB Device Discovery" on page 16
Matrix 210N xxx-x0x	Serial Configuration ^a	"Step 5C - Serial Device Discovery" on page 19

- a. All devices except dedicated USB models can be configured through their Main or Aux Serial port. However, through these interfaces, configuration is slower than the Ethernet interface and presents some limitations. It is recommended to use the Serial interface for configuration **only** if no other interface is available.

Step 5A - Ethernet Device Discovery

The following configuration procedure assumes a laptop computer, running DL.CODE, is connected to a factory default reader through the Ethernet port. See "Step 1 - Connect the System" on page 1.

The User Interface opens and displays a list of all the devices belonging to the Local Area Network. DL.CODE has a discovery feature to accomplish this task.

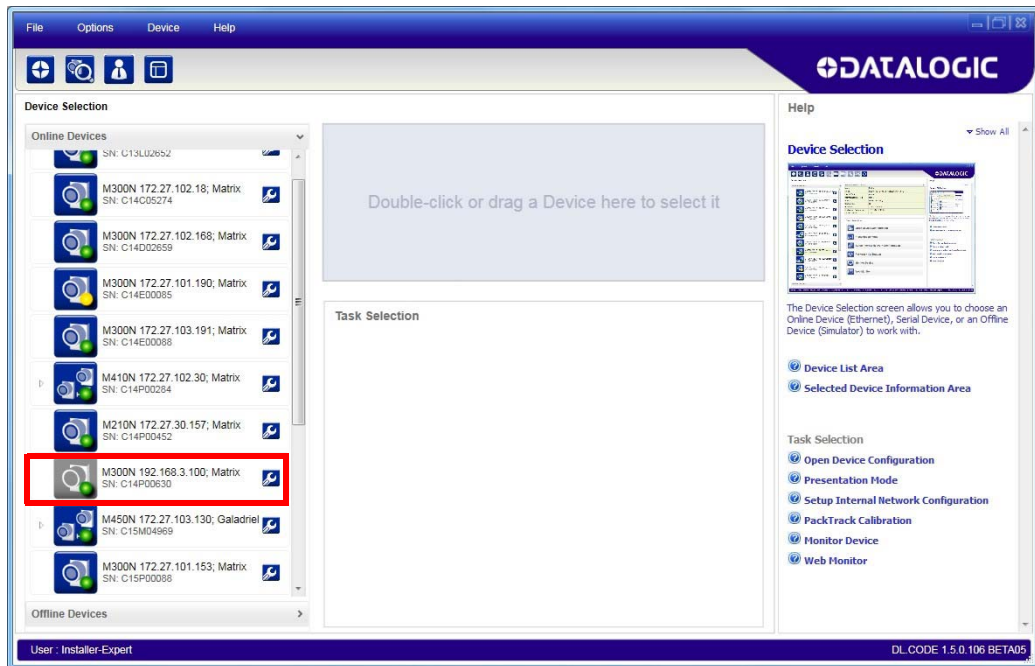


Figure 16 - Device Discovery

The discovery feature will also show devices not belonging to the LAN and display them in gray (see Figure 16).

3. First the device must be added to the LAN by aligning its IP Address to the network. The network administrator should provide valid LAN address(es).



4. Find your device in the list by matching its serial number (SN) then click on the device wrench icon to open the Device Environment Configuration window.
5. Change the Ethernet Settings (IP Address, Subnet Mask, Gateway Address etc.) according to the network requirements.

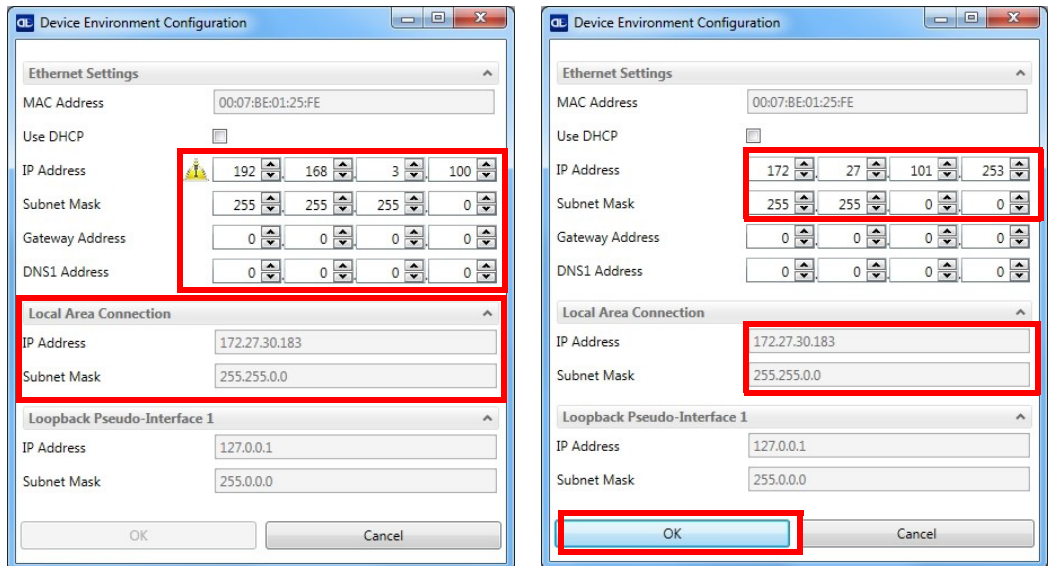
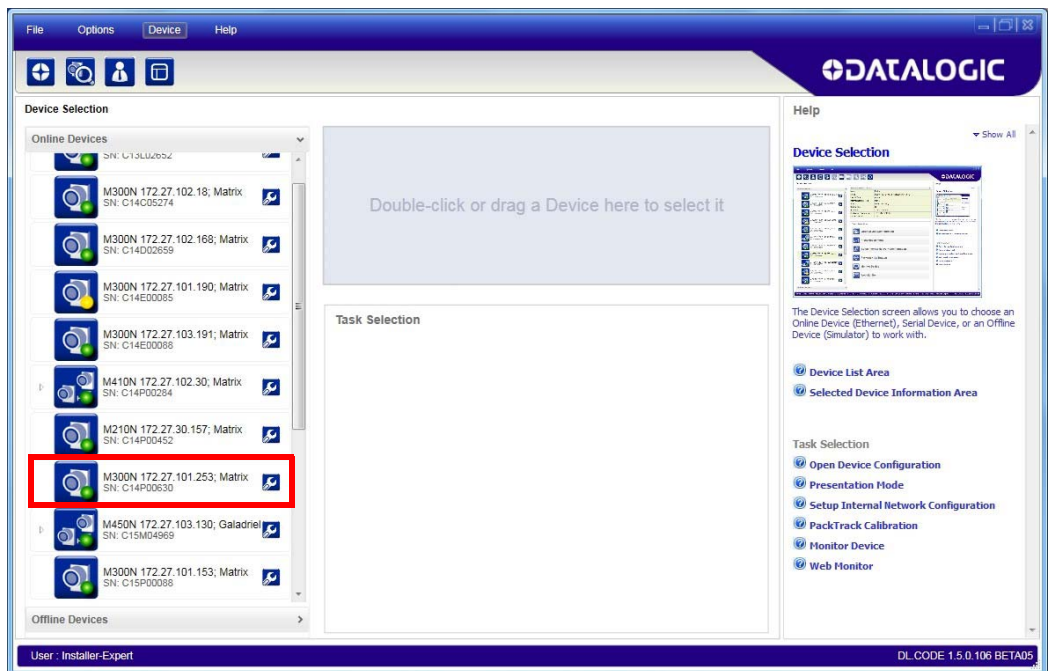


Figure 17 - Device Environment Configuration Window

- Click OK; the device will reappear in the list of Online Devices (in color) meaning it is now part of the LAN and can be configured. The new IP address will also be displayed.



7. Double-click on or drag the device icon into the Selected Device Information Area. Details about the device will be displayed in this area.

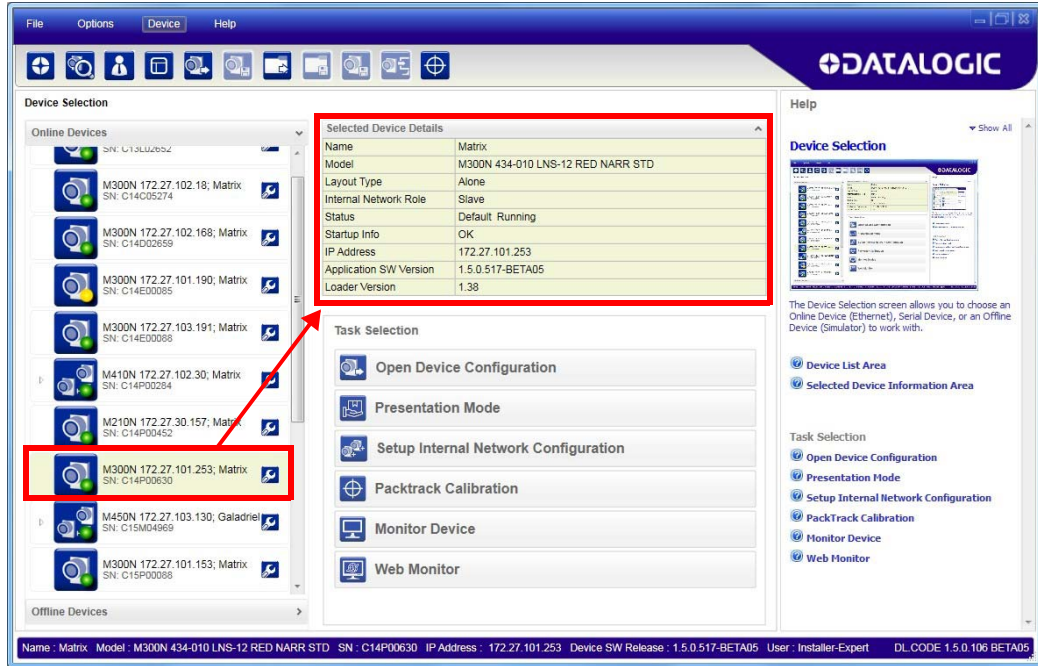
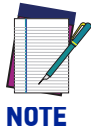


Figure 18 - DL.CODE Opening Window



After device discovery, configure your device through DL.CODE as described in "Step 6 - Device Configuration" on page 21.

NOTE

Step 5B - USB Device Discovery

The following configuration procedure assumes that a laptop computer running DL.CODE is connected to a Matrix 210N USB model factory default reader through the USB port.

Matrix 210N USB devices require their virtual COM port driver to be installed on the PC being used for configuration. This can be done in two ways:

- If the PC used for configuration is connected to Internet and has access to Windows Update, then the correct device driver will automatically be installed.
- If the PC used for configuration is not connected to Internet and does not have access to Windows Update, then the correct device driver can be installed from the DL.CODE mini-DVD (downloaded zip file or mini-DVD accessory). The installation file is located in the Software\ SW Utilities\USB Virtual COM Port Drivers directory. See the paragraph below for installation instructions.



The Matrix USB Driver selection box in the Welcome window of the DL.CODE Installer is not for Matrix 210N devices.

NOTE

The USB Virtual COM Port Driver allows sending serial data using the Matrix 210N USB port. A different virtual COM Port will be assigned to each connected reader.

Installing the USB Virtual COM port drivers

Double-click on one of the following files to launch the correct USB Virtual COM Port Driver Installer for your PC.

- Windows XP//7 (x32) = "DPIInst.exe"
- Windows 7, 8, 10 (x64) = "DPIInstx64.exe"

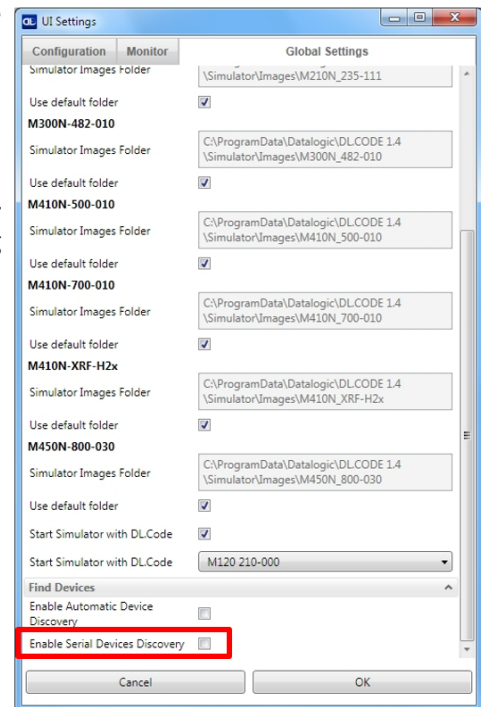
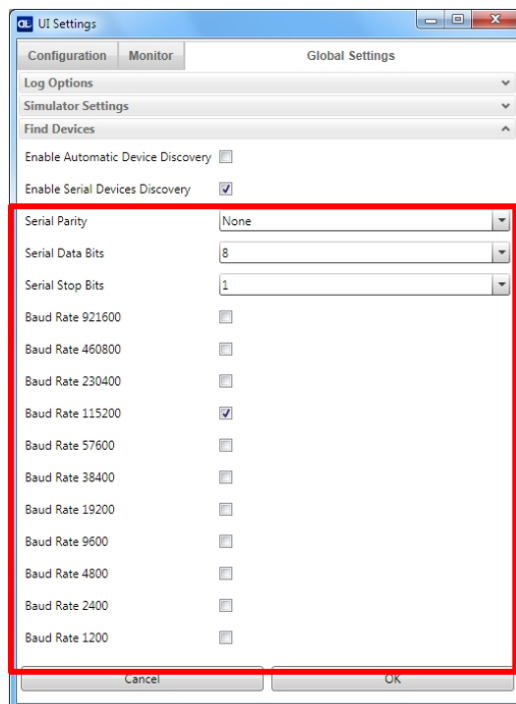
The driver will be installed.

For updated drivers or more details go to ftdichip.com/Drivers/VCP.htm.

Starting from DL.CODE 1.4.0, serial port communication is supported for device discovery and configuration. This allows dedicated Matrix 210N USB communication models to be configured through DL.CODE.

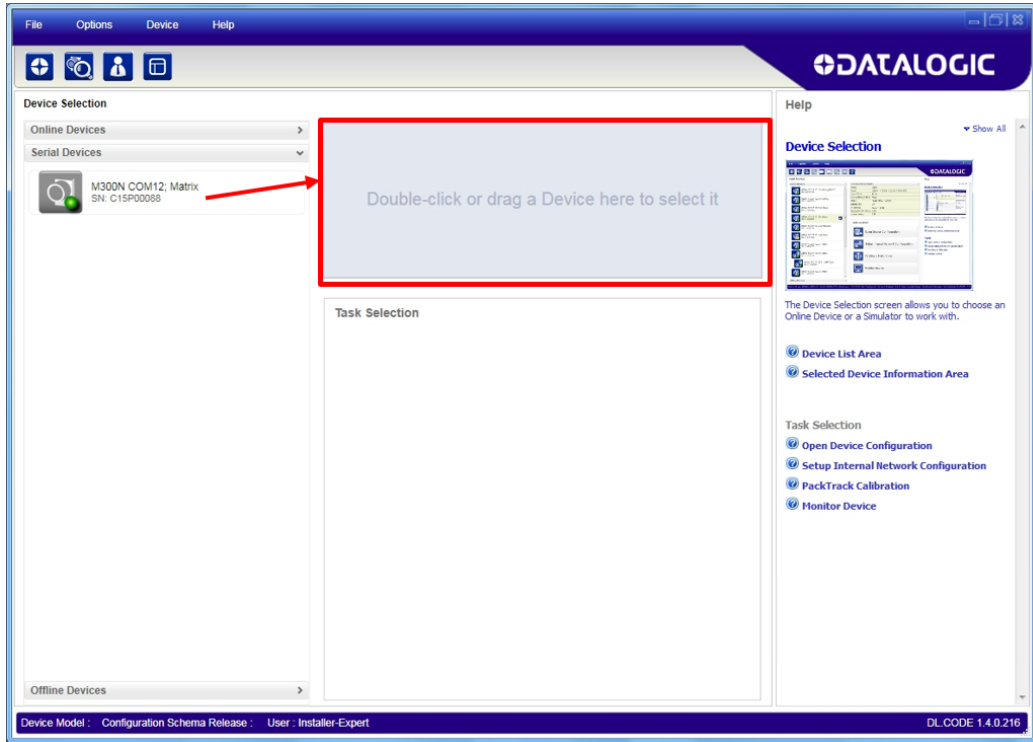
This feature is not enabled by default, so the first thing to do is to enable it through the UI Settings window.

1. From the main menu open the Options>UI Settings window.
2. Click on the Global Settings menu and scroll down to the Find Devices tab.
3. Check the **Enable Serial Device Discovery** box. Scroll down to see the following selections.
4. For Matrix 210N USB models the baud rate is fixed at 115200. Select **115200**.



5. Click OK to return to DL.CODE and click on the Getting Started icon.

- Open the Serial devices tab and double-click on or drag the device icon into the Selected Device Information Area.

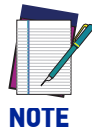


The device is now connected to the DL.CODE Configuration environment. Configure your device through DL.CODE as described in "Step 6 - Device Configuration" on page 21.



Step 5C - Serial Device Discovery

Starting from DL.CODE 1.4.0, serial port communication is supported for device discovery and configuration. This allows dedicated serial communication models to be configured through DL.CODE.

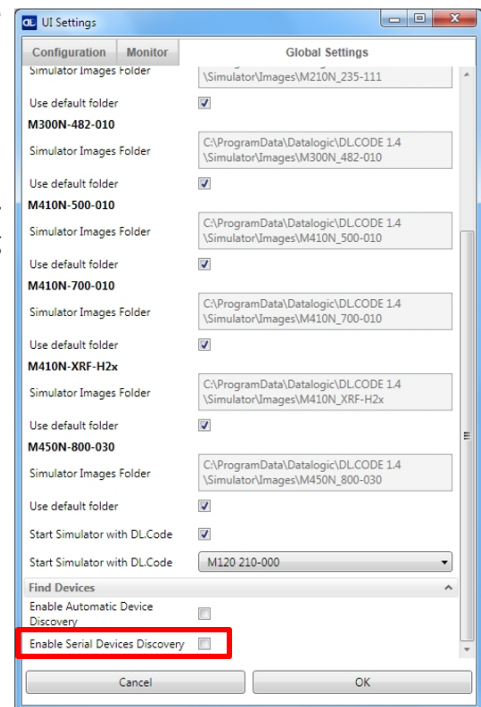
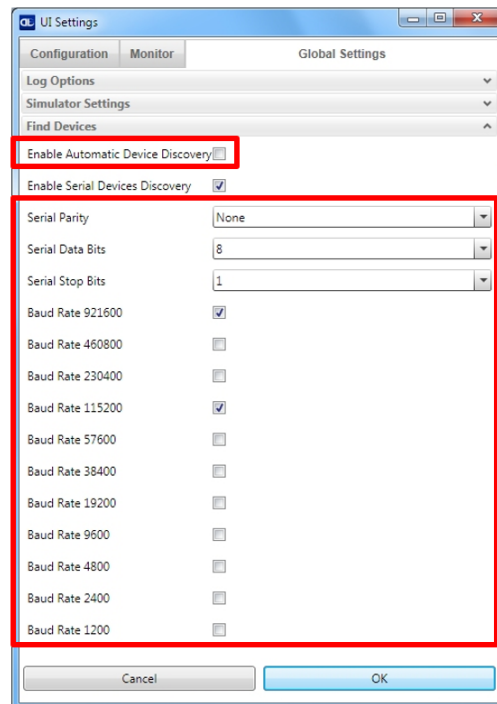


NOTE

Although this feature allows all devices to be configured through their Serial Interface, be aware that transmission speeds and some DL.CODE features are limited when using this interface. It is always advised to use the Ethernet interface whenever possible.

This feature is not enabled by default, so the first thing to do is to enable it through the UI Settings window.

1. From the main menu open the Options>UI Settings window.
2. Click on the Global Settings menu and scroll down to the Find Devices tab.
3. Check the **Enable Serial Device Discovery** box. Scroll down to see the following selections.
4. For Matrix 210N USB models the baud rate is fixed at 115200. Select **115200**.

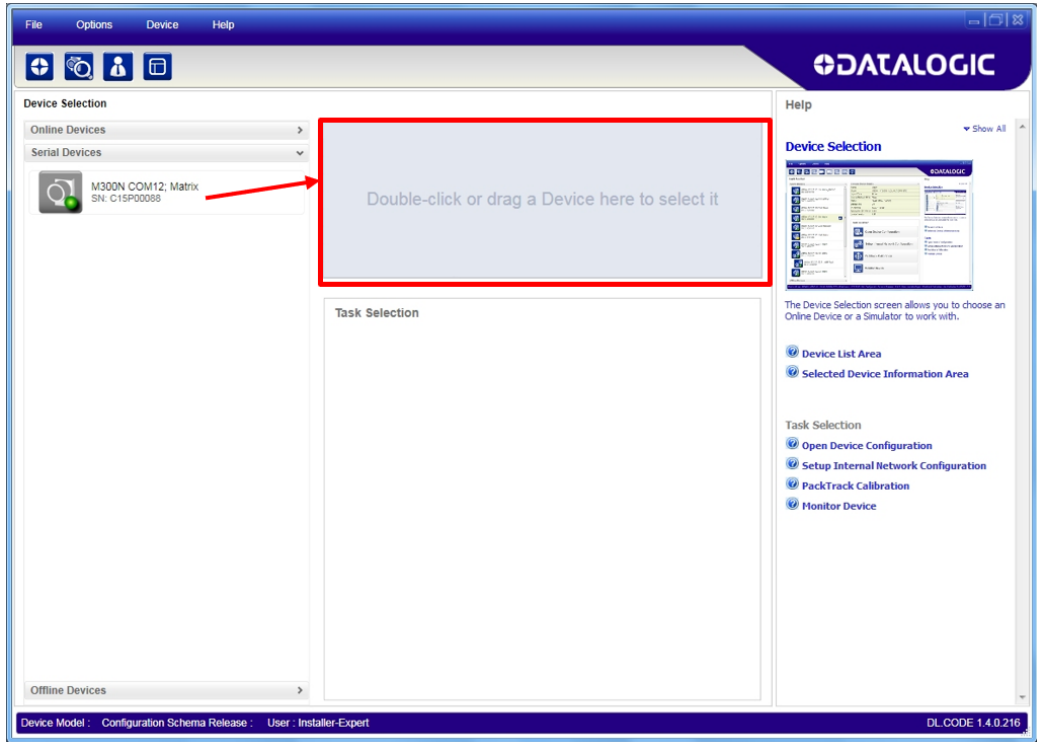


NOTE

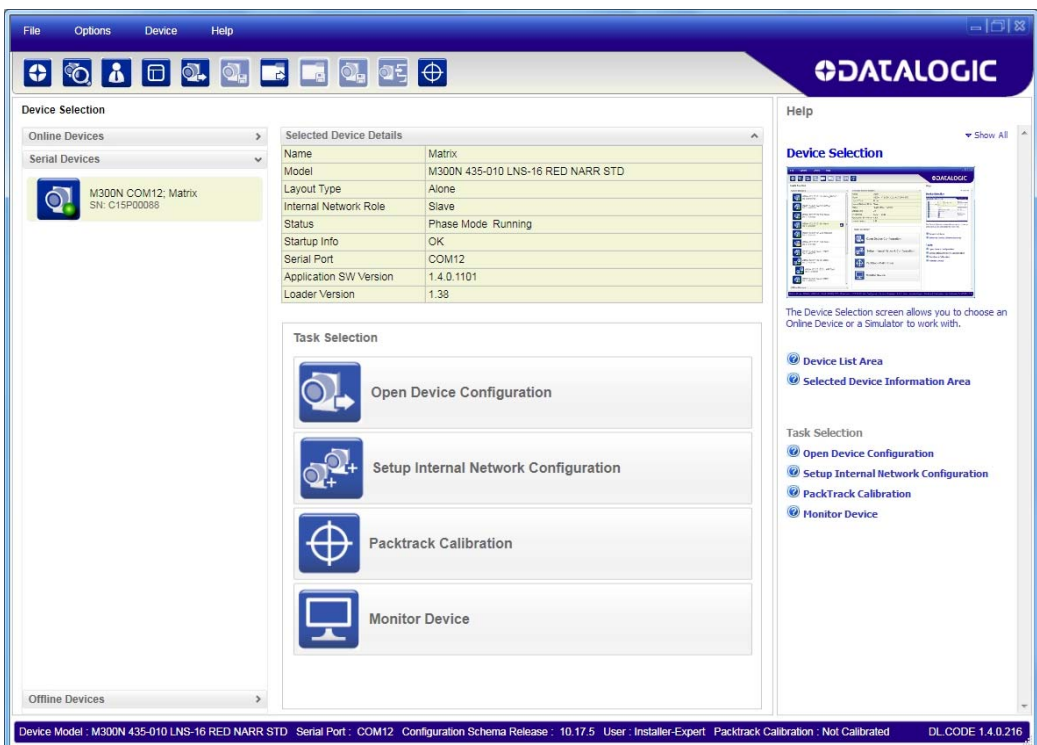
If you're not sure of the Serial baud rate you can also check the **Enable Automatic Device Discovery** box which for serial devices will try communication at all baud rates, but only at No parity, 8 data bits; 1 stop bit. Enabling this parameter can notably lengthen Discovery time, therefore it is generally better to disable it to increase Discovery efficiency.

5. Click OK to return to DL.CODE and click on the Getting Started icon.

- Open the Serial devices tab and double-click on or drag the device icon into the Selected Device Information Area.



The device is now connected to the DL.CODE Configuration environment. Configure your device through DL.CODE as described in "Step 6 - Device Configuration" on page 21.



STEP 6 - DEVICE CONFIGURATION

Automatic or Advanced Setup

Automatic Setup provides an automatic procedure for setting: optical/illumination, reading distance, and code definition parameters to obtain the most stable decoding conditions for a single code symbology based on the images presented to the reader. It can be set to include Image Filters if necessary. See the table below for codes and filters managed by Automatic Setup. Automatic Setup is especially useful for DPM applications.

ENABLED 1D CODES	ENABLED 2D CODES	ENABLED FILTERS
CODE 128 EAN 128 CODE 39 CODE 93 CODABAR PDF417 MICRO PDF417 GS1 DATABAR GS1 DATABAR STACKED GS1 DATABAR LIMITED GS1 DATABAR EXPANDED GS1 DATABAR EXPANDED STACKED UPCEAN FAMILY EAN13 UPCEAN FAMILY EAN8 UPCEAN FAMILY UPCA UPCEAN FAMILY UPCE	DATAMATRIX ECC 200 QR MICRO QR AZTEC MAXICODE DOTCODE	ERODE 3x3, 5x5 and 7x7 DILATE 3x3, 5x5 and 7x7 SMOOTHING

Advanced Setup provides access to the complete array of optical/illumination, focusing adjustment, and code definition parameters that can be fine-tuned semi-automatically and manually to obtain the best results for applications of any complexity.



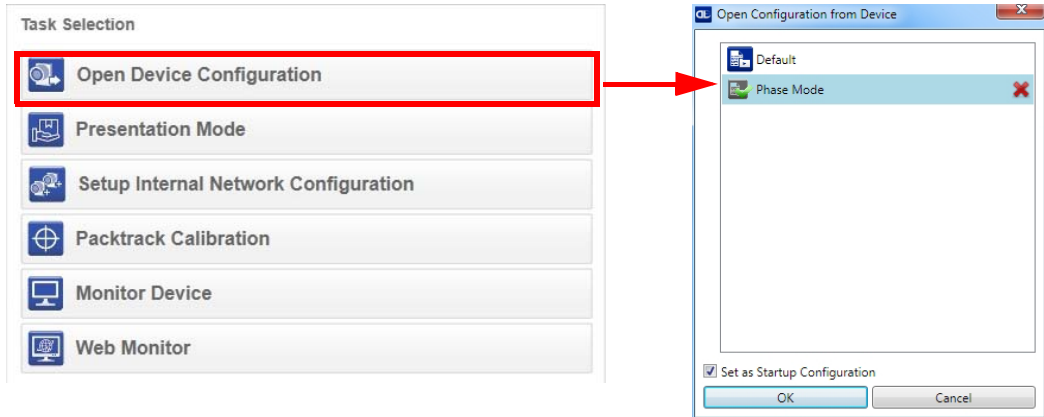
NOTE

If your application requires multiple code symbologies, multiple image settings, Code Grading or other parameter settings for decoding, then use the Advanced Setup, see page 24.

Automatic Setup

To begin configuration, the reader must be correctly mounted so that its Field of View covers the application reading area.

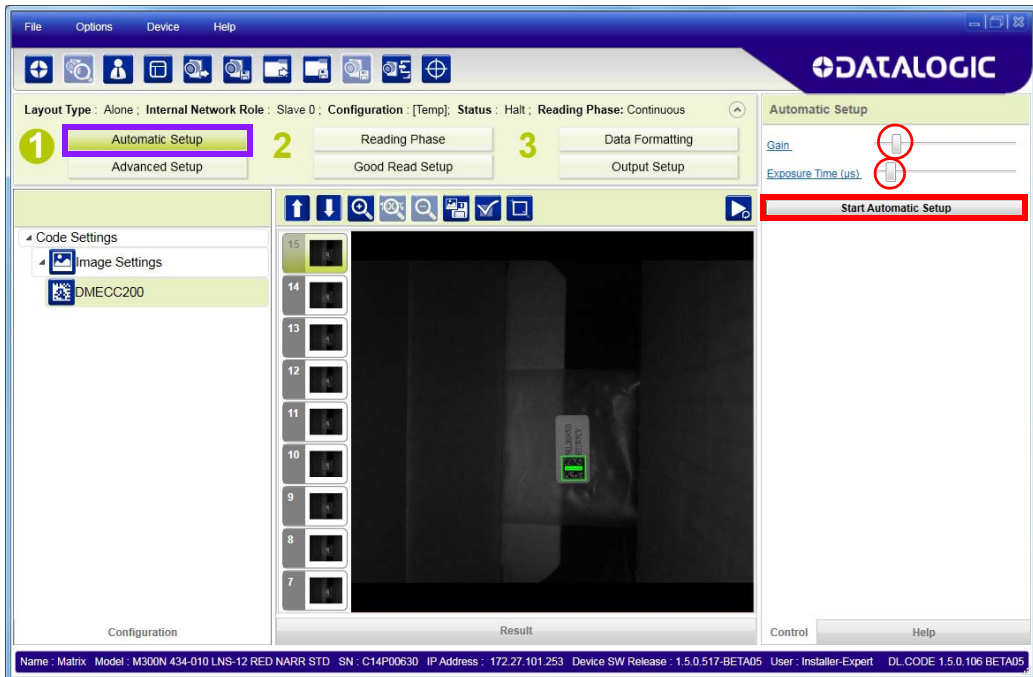
1. From the Task Area select Open Device Configuration.
2. The Open Device Configuration window opens showing the list of currently saved configurations (jobs) saved on the device. For new devices, the only saved job is the Default configuration. Click OK. The device enters run mode and begins acquiring images.



3. Place the application code in front of the reader at the correct application reading distance.



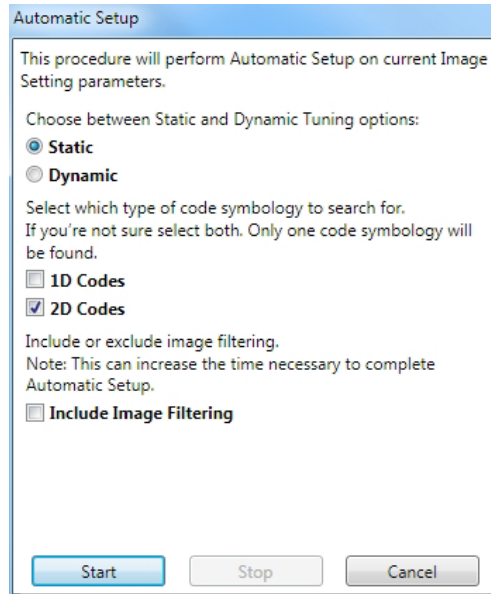
4. Click on the Pause button to stop image acquisition.



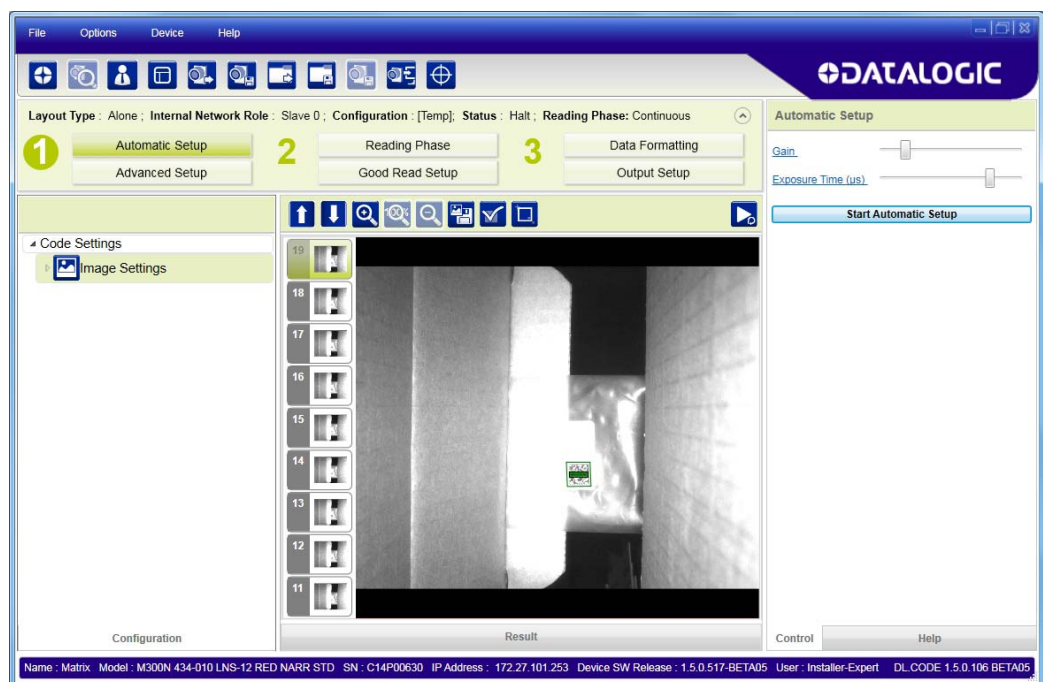
NOTE

If the image display area is too dark to see the images being captured, you can drag the Gain and Exposure Time sliders (circled in red in the figure above) to the right to increase visibility. This will not affect Automatic Setup.

- Click on the **Start Automatic Setup** button. The following window is displayed:



- Select the correct reading conditions: Static or Dynamic Tuning, 1D or 2D code, Include Image Filtering (to find the best decoding condition).
- Click Start to begin the procedure. The reader begins acquiring images. At the end of the procedure the **Status: Completed** message appears. You can Close the Automatic Setup window.



Your reader is now optimized for decoding. Continue with the Reading Phase configuration described on page 34.

Advanced Setup for Software Adjustable Focus Models (Liquid Lens)

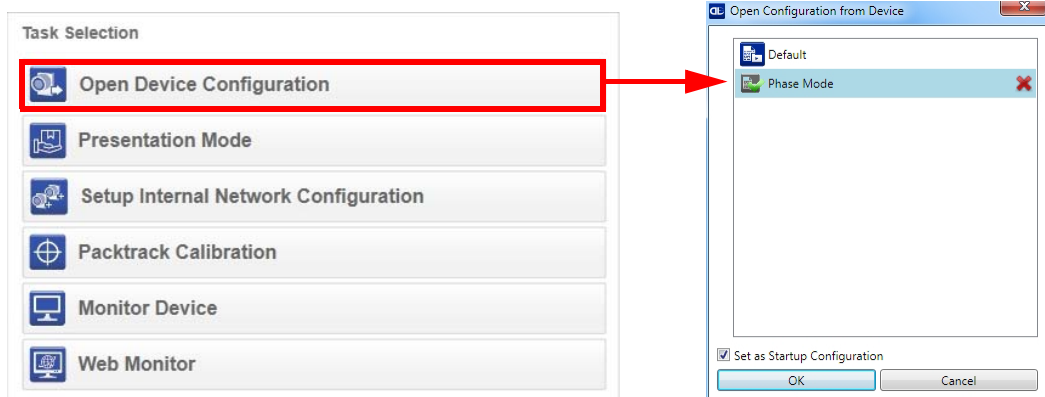


NOTE

For Fixed Focus models go to "Advanced Setup for Fixed Focus Models" on page 31 then continue with "Reading Phase" on page 34.

To begin configuration, the reader must be correctly mounted at the correct reading distance for your application so that its Field of View covers the application reading area.

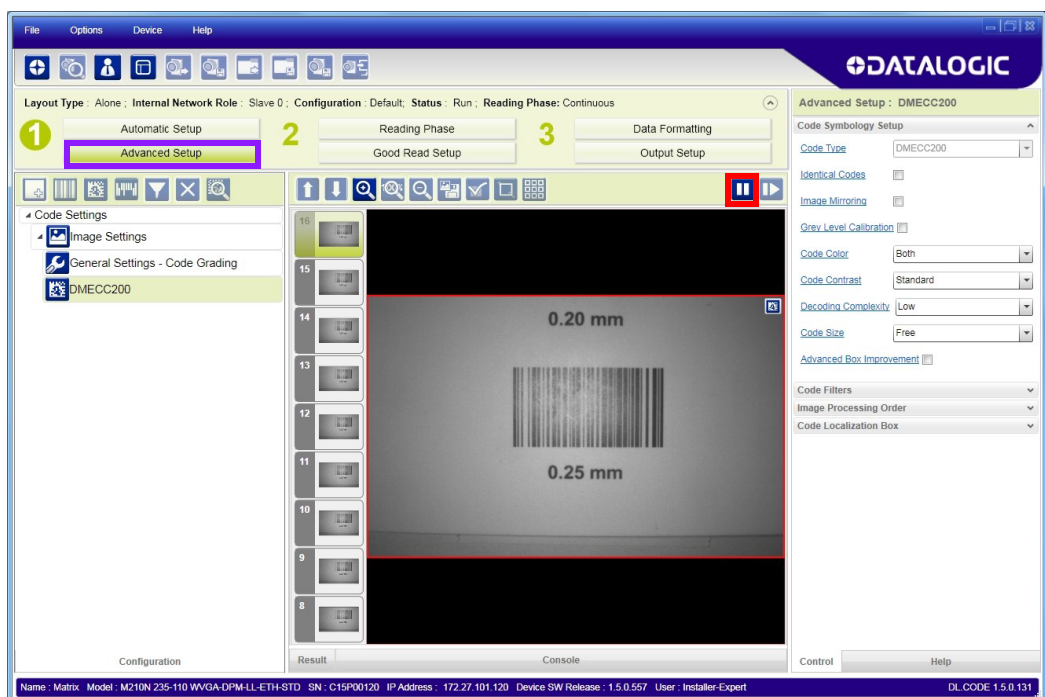
1. From the Task Area select Open Device Configuration.
2. The Open Device Configuration window opens showing the list of currently saved configurations (jobs) saved on the device. For new devices, the only saved job is the Default configuration. Click OK. The device enters run mode and begins acquiring images.



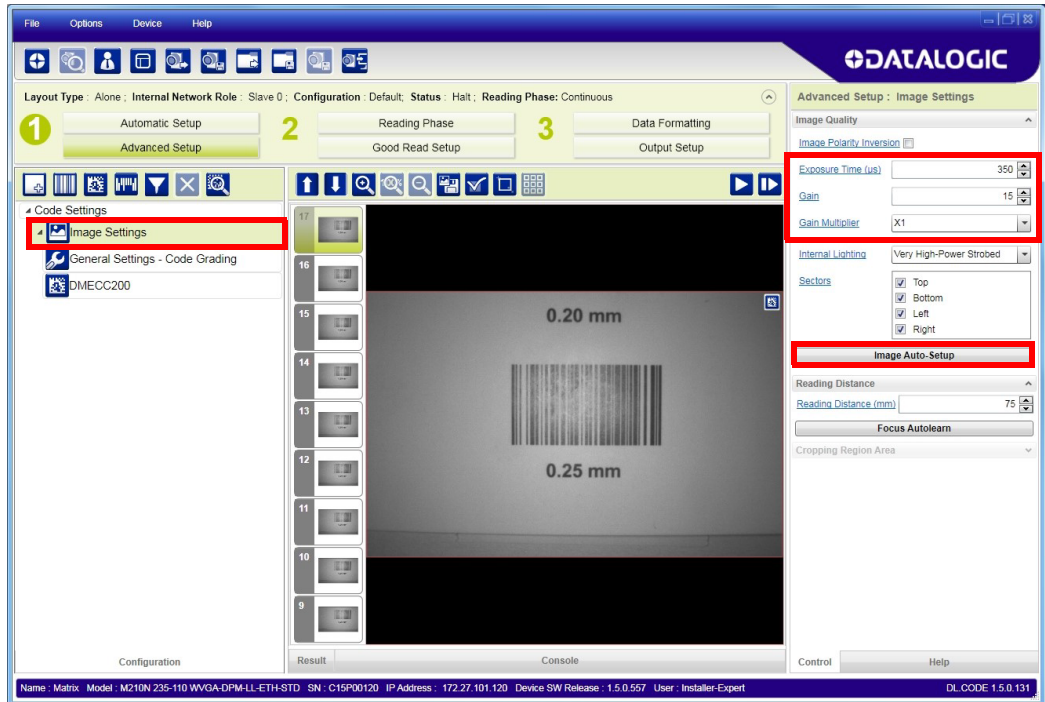
3. Click on the Advanced Setup button and press the Play icon.



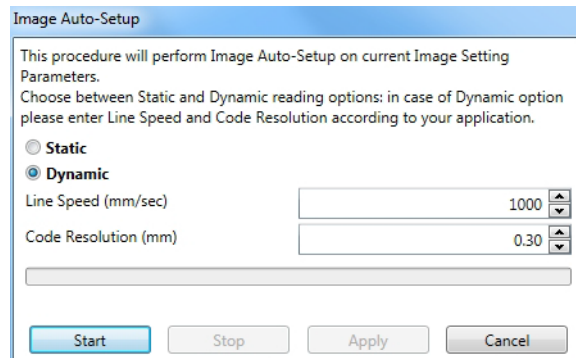
4. Place the **Grade A Barcode Test Chart** in the reading area. Once positioned, stop image acquisition by clicking on the Pause button.

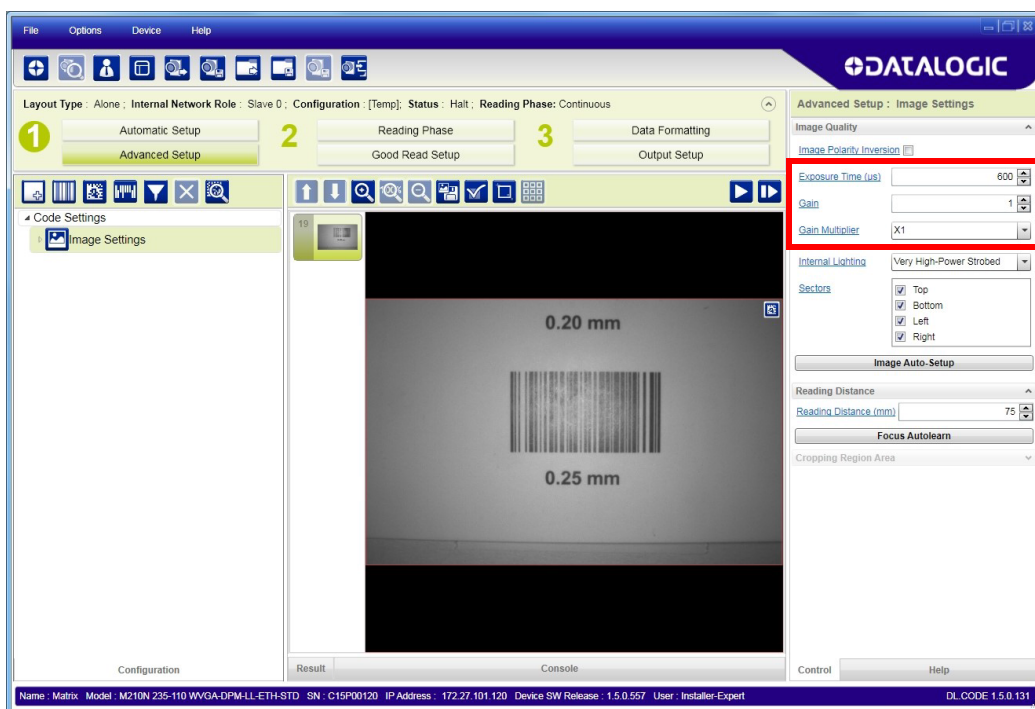


- Click the Image Settings branch and then click the Image Auto-Setup button to automatically acquire the best exposure time and gain values.



- Select the Static or Dynamic Self-Tuning option; Start the Image Auto Setup and Apply to the Image Settings.





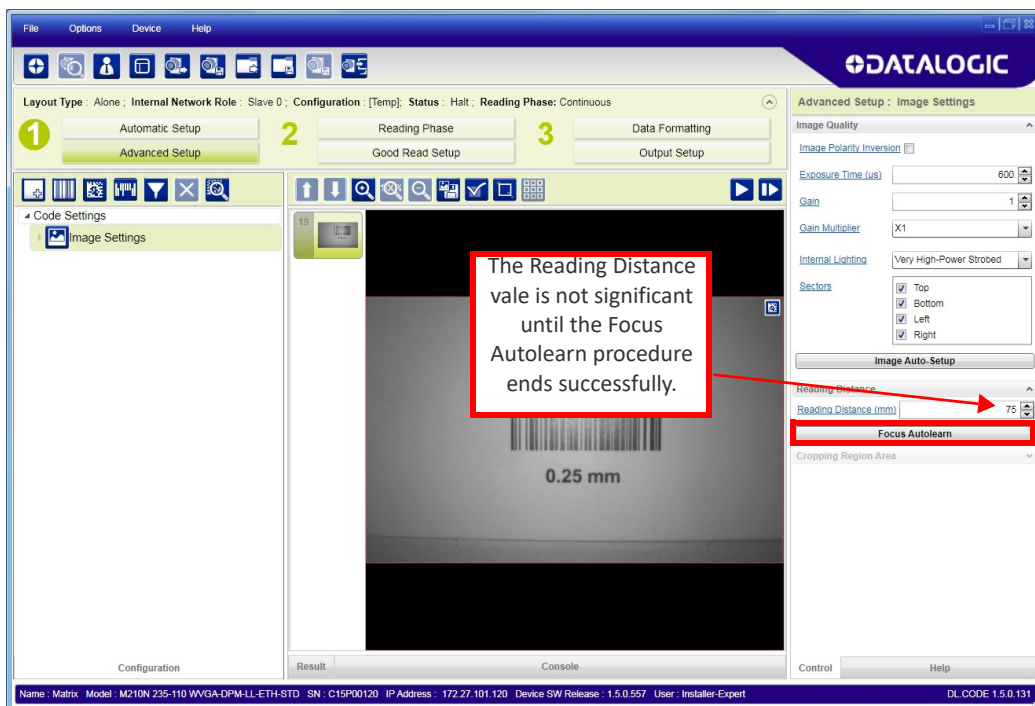
NOTE

For applications having multiple lighting or code reading conditions, up to 10 different Image Settings can be configured by adding them with the

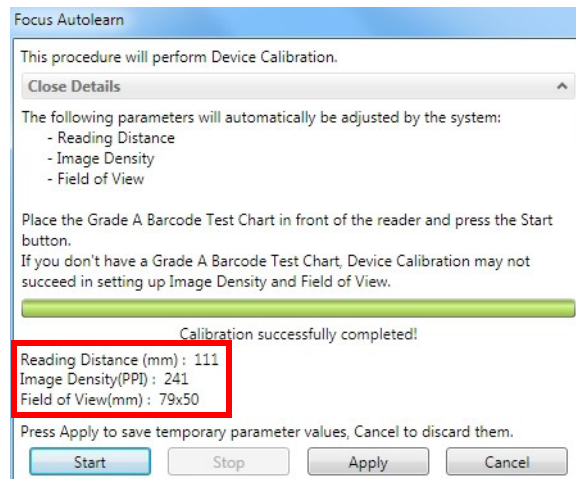
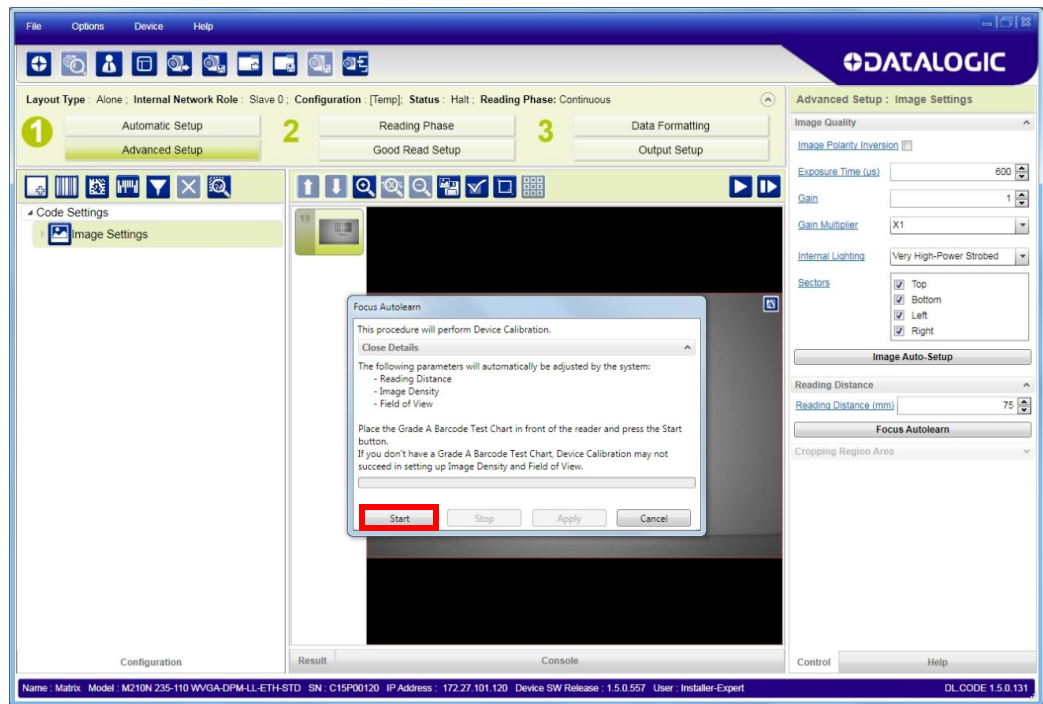


icon.

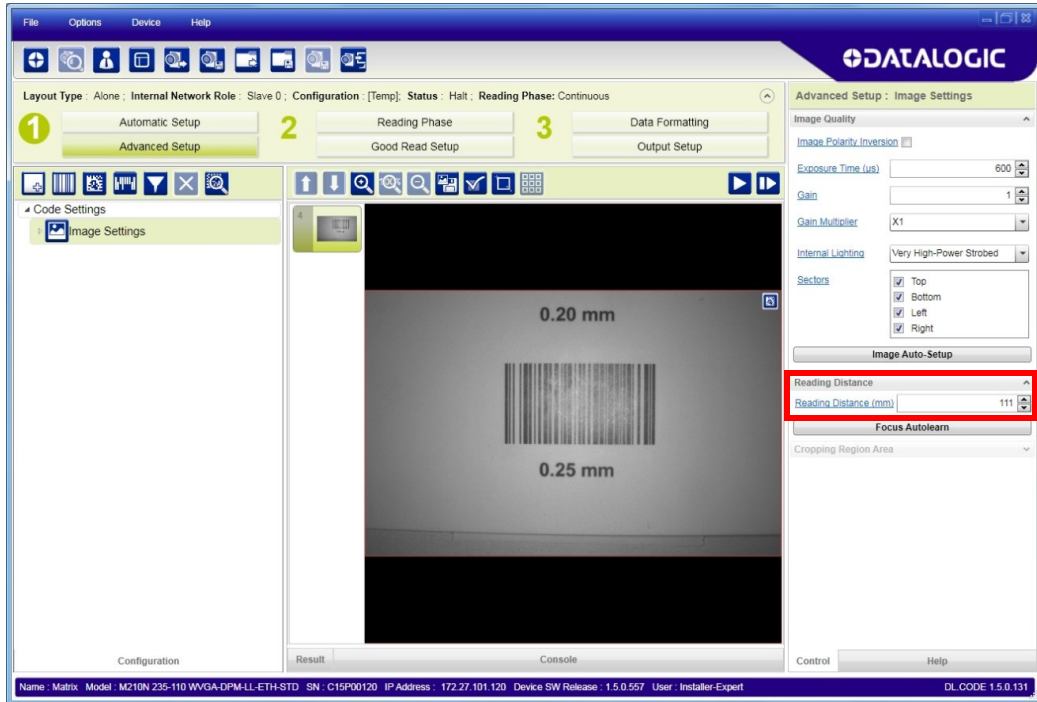
7. Now click on the Focus Autolearn button.



8. The Calibrate dialog box opens allowing you to start the procedure. Click Start.



At the end of the calibration you can see the new Reading Distance and Image Density (PPI) values as well as the FOV dimensions. Click Apply.



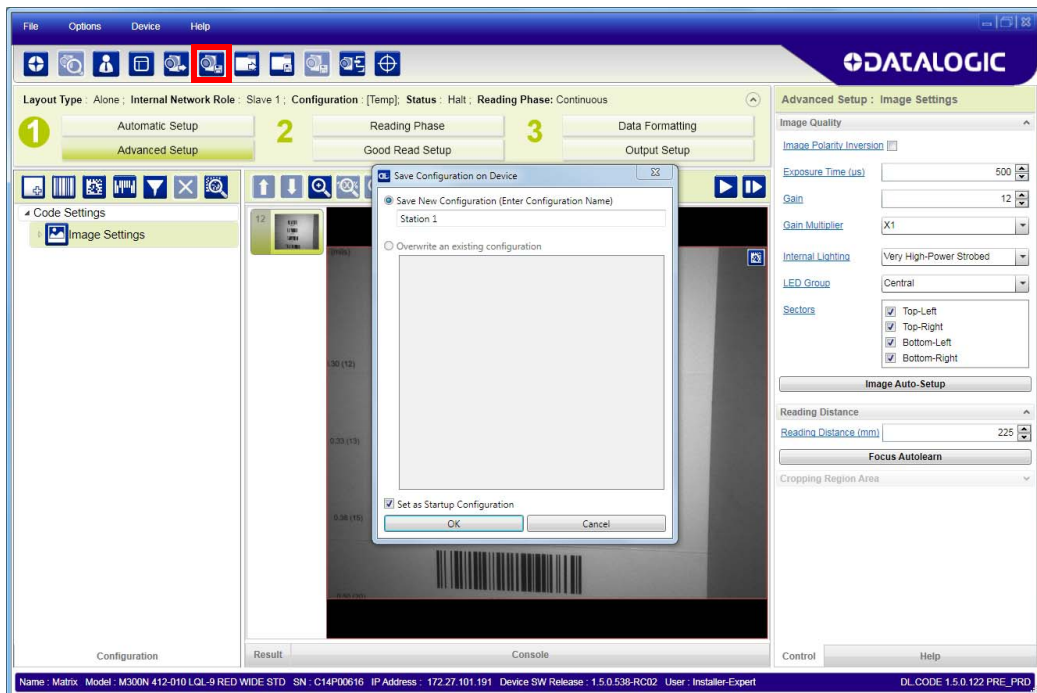
NOTE

To enlarge the visual image of the code view, you can click on the zoom image icon repositioning it on the code.

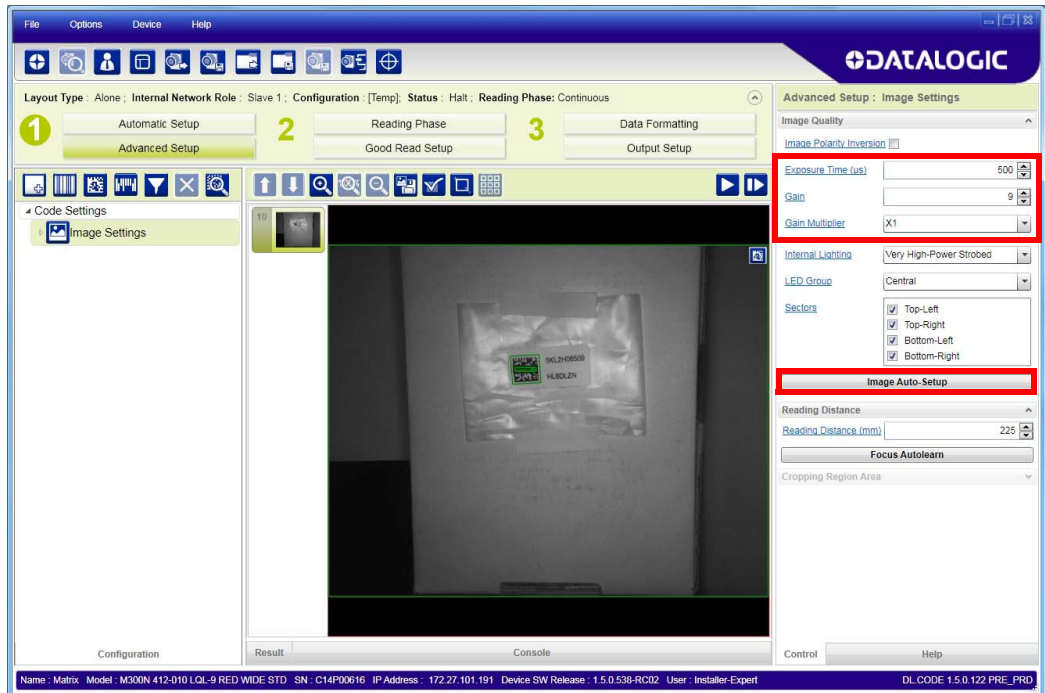


NOTE

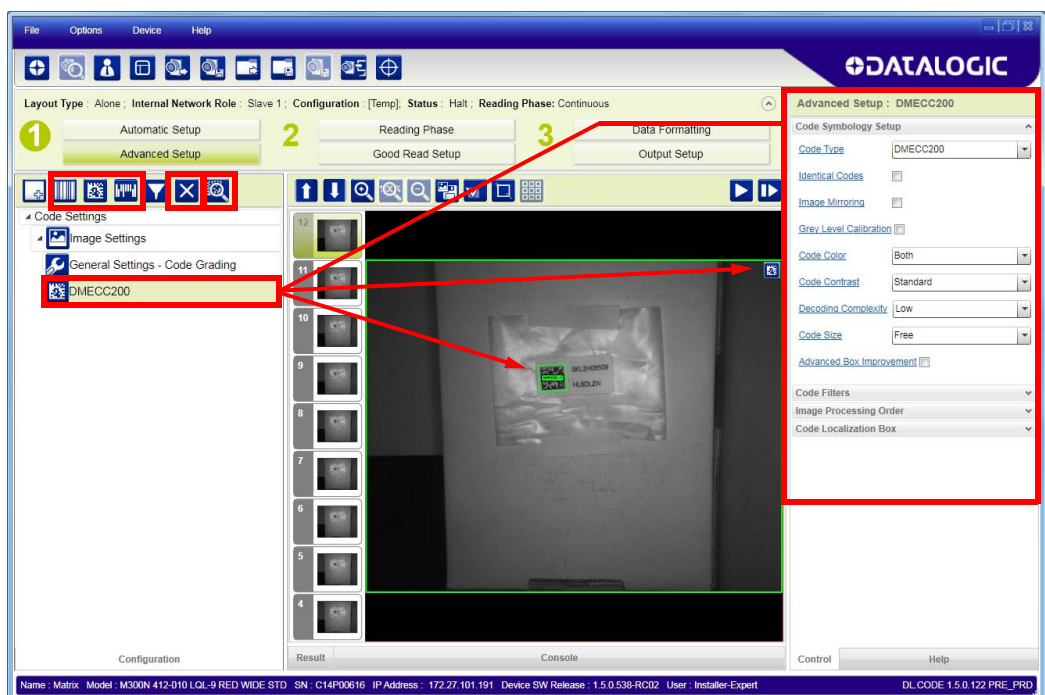
At this point it is probably a good idea to save the configuration from temporary memory to permanent memory giving it a specific name.



9. Now place an **application specific code** in front of the reader and repeat **only** the **Image Auto-Setup** to register any changes in lighting or code surface contrast.



10. Click on the Data Matrix ECC 200 symbology under the Image Settings branch (enabled by default). If this symbology is among those in your application it will be shown in the image display with its code symbology name and a small green box around it indicating it is decoded.



NOTE

The large green box for each symbol indicates the code localization area which by default is equal to the maximum FoV. It can be resized and moved by dragging its borders with the mouse. The code must be found within this area in order to be decoded.



11. Add your application specific codes to the Code Settings by selecting them from the icons over the Configuration Parameters tree area. If the Data Matrix symbology is not used, then delete it from the Code Settings with the Delete icon.



If you don't know the code type, you can use the Code Autolearn feature by clicking on the Code Autolearn icon.¹ See the DL.CODE User's Manual for details.

12. For each code symbology set the relative parameters according to your application.

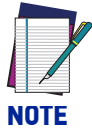


NOTE

Continue the configuration from "Reading Phase" on page 34.

1. *The Code Autolearn procedure will not recognize the following symbologies: Pharmacode, MSI, Standard 2 of 5, Matrix 2 of 5.*

Advanced Setup for Fixed Focus Models

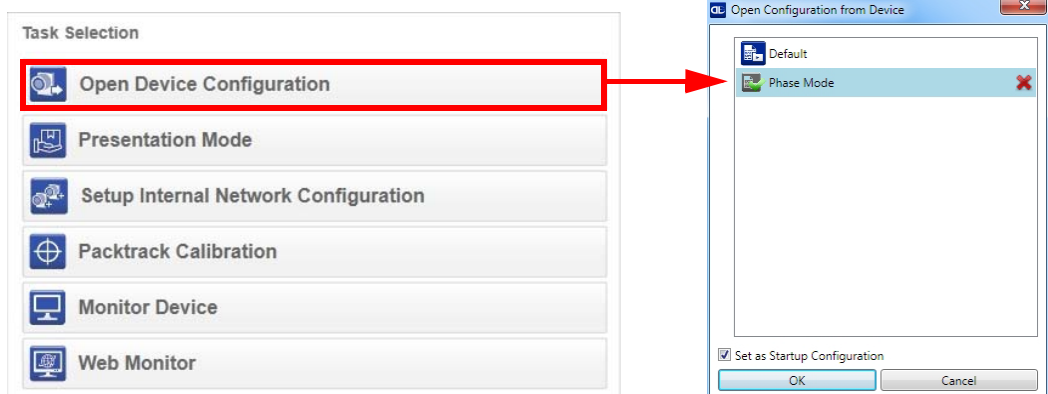


NOTE

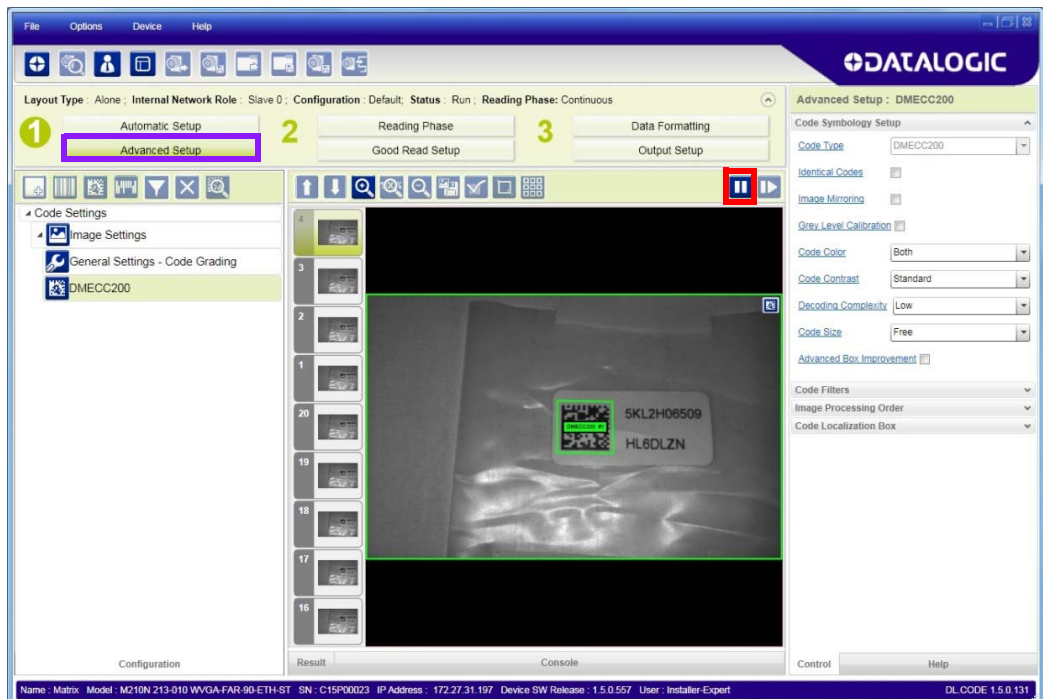
For Software Adjustable Focus models go to "Advanced Setup for Software Adjustable Focus Models (Liquid Lens)" on page 24 then continue with "Reading Phase" on page 34.

To begin configuration, the reader must be correctly mounted at the correct reading distance for your application so that its Field of View covers the application reading area.

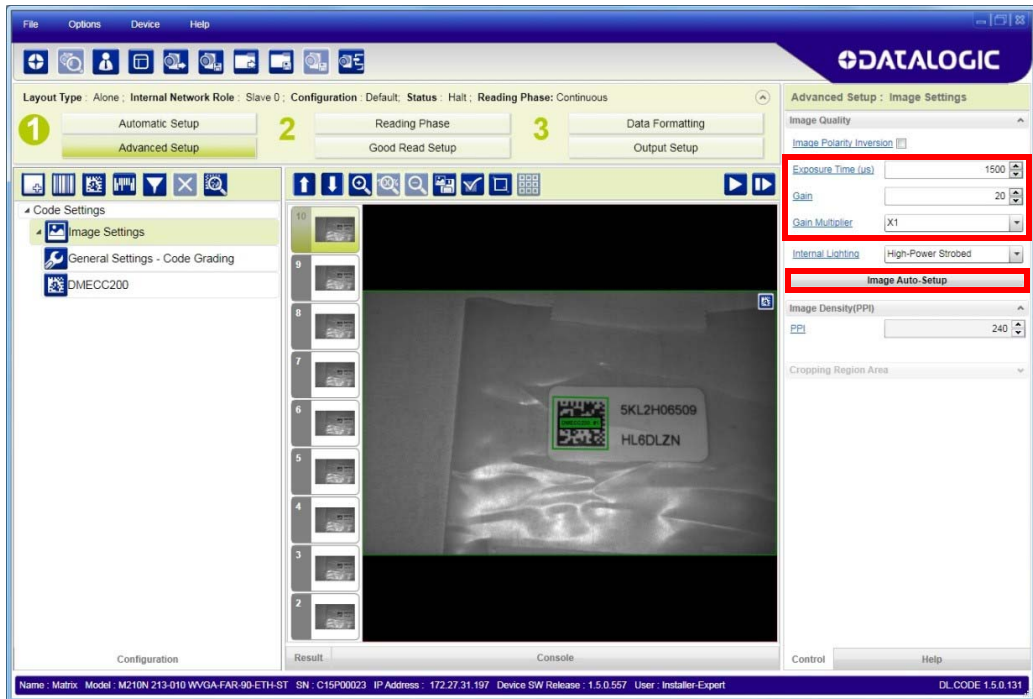
1. From the Task Area select Open Device Configuration.
2. The Open Device Configuration window opens showing the list of currently saved configurations (jobs) saved on the device. For new devices, the only saved job is the Default configuration. Click OK. The device enters run mode and begins acquiring images.



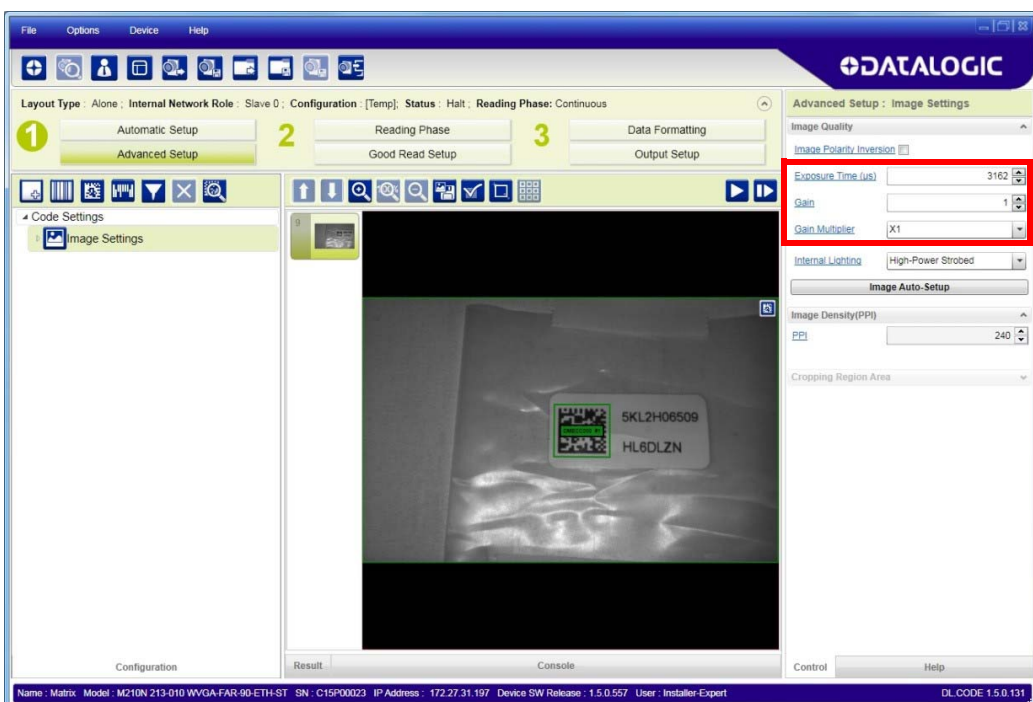
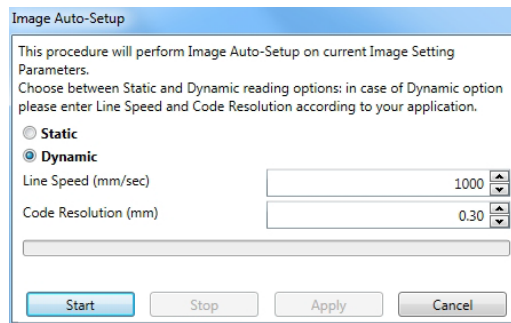
3. Click on the Advanced Setup button and press the Play icon.
4. Place an **application specific code** in the reading area. Once positioned, stop image acquisition by clicking on the Pause button. If a Data Matrix code is placed in front of the reader you may also see the green good decoding box imposed on the display image.

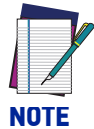


- Click the Image Settings branch and then click the Image Auto Setup button to automatically acquire the best exposure time and gain values.



- Select the Static or Dynamic Self-Tuning option; Start the Image Auto-Setup and Apply to the Image Settings.

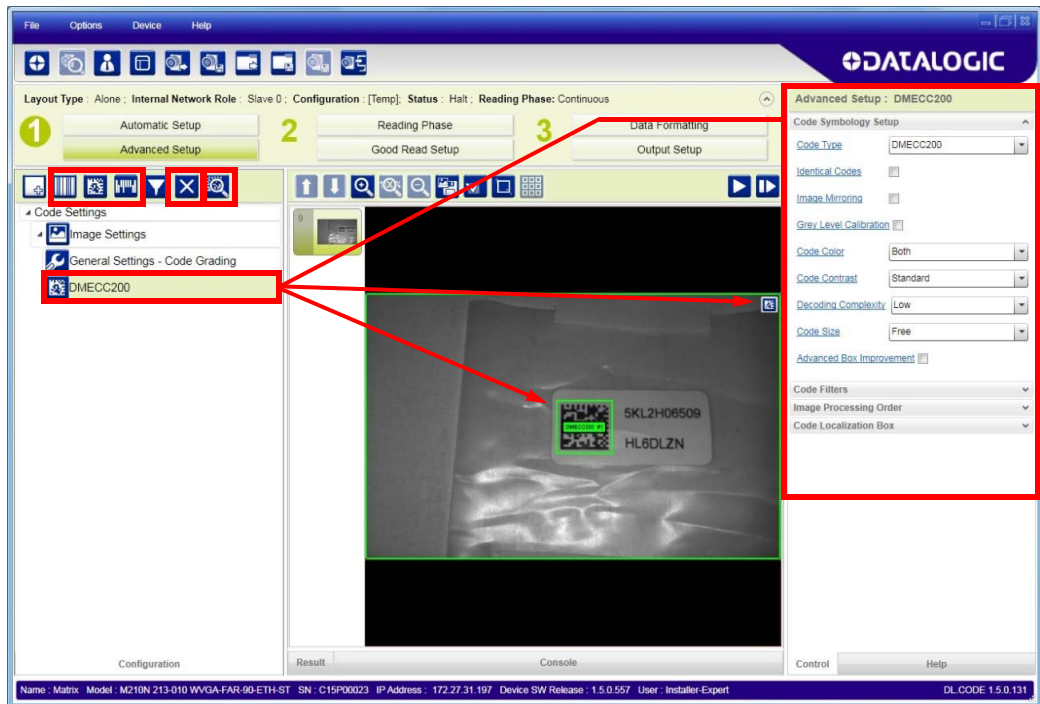




For applications having multiple lighting or code reading conditions, up to 10 different Image Settings can be configured by adding them with the



- Click on the Data Matrix ECC 200 symbology under the Image Settings branch (enabled by default). If this symbology is among those in your application it will be shown in the image display with its code symbology name and a small green box around it indicating it is decoded.



The large green box for each symbol indicates the code localization area which by default is equal to the maximum FoV. It can be resized and moved by dragging its borders with the mouse. The code must be found within this area in order to be decoded.



- Add your application specific codes to the Code Settings by selecting them from the icons over the Configuration Parameters tree area. If the Data Matrix symbology is not used, then delete it from the Code Settings with the Delete icon.



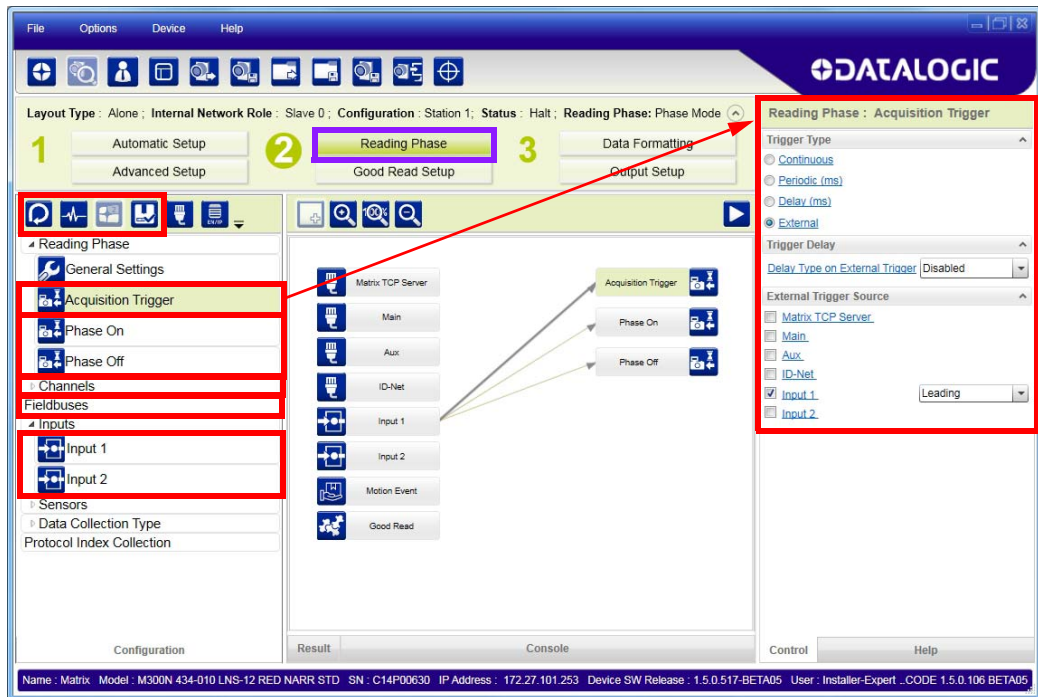
If you don't know the code type, you can use the Code Autolearn feature by clicking on the Code Autolearn icon.¹ See the DL.CODE User's Manual for details.

- For each code symbology set the relative parameters according to your application.

1. The Code Autolearn procedure will not recognize the following symbologies: Pharmacode, MSI, Standard 2 of 5, Matrix 2 of 5.

Reading Phase

1. Select your application specific Operating Mode from the icons over the Configuration Parameters tree area: Continuous, One Shot, Phase Mode or PackTrack.

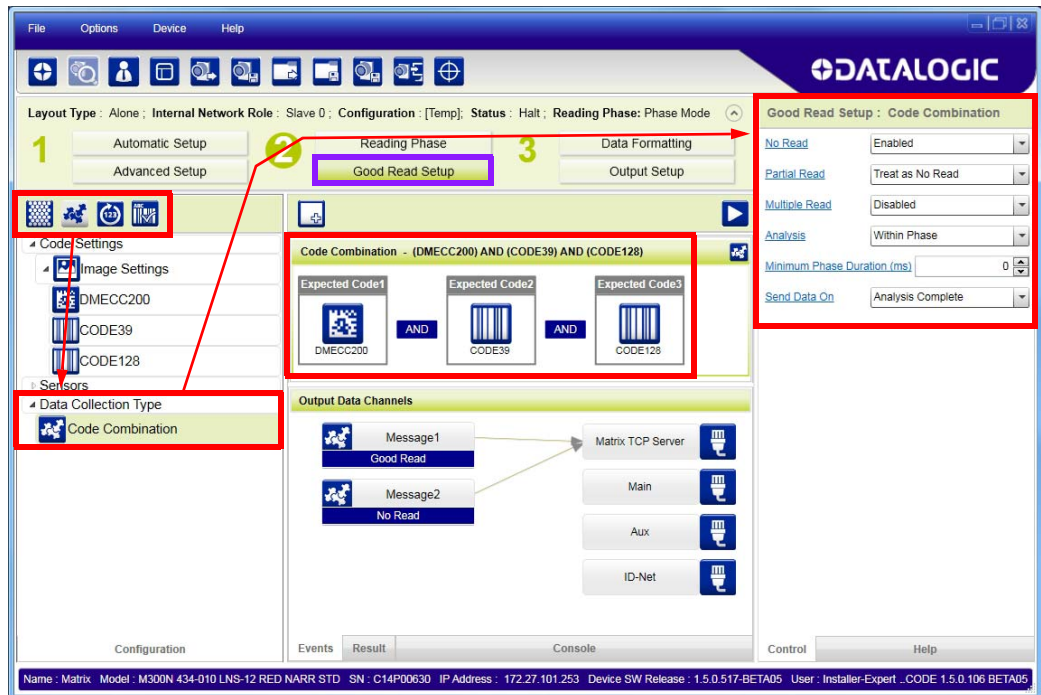


2. Configure the relative Operating Mode parameters from the Reading Phase parameters panel. Different groups will appear in the panel depending on the selected icons over the Configuration Parameters tree area.

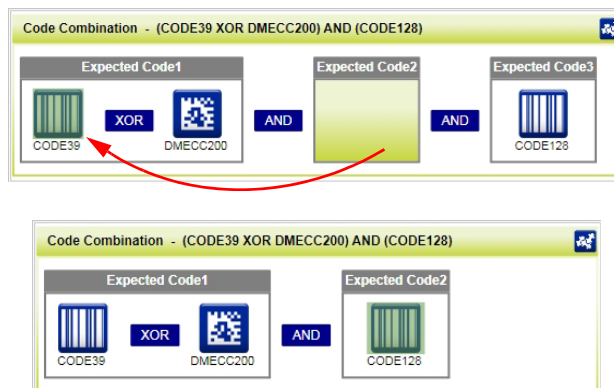
Good Read Setup

1. Select your specific data collection type from the icons over the Configuration Parameters tree area: Code Collection, Code Combination, Presentation or Match Code. Not all data collection types are available for all Operating Modes; for example PackTrack Operating Mode only supports Code Combination. Incompatible data collection types will be shown in gray and cannot be selected.

The following example shows Code Combination. By default, the Expected Codes (when more than one code type is selected), are in logical AND, which means that all codes are required to be decoded to produce a Good Read condition.

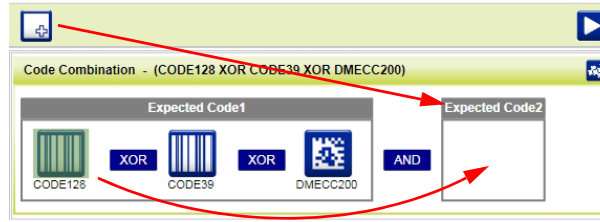


2. If a Good Read condition should be produced when any single code is decoded, independent from the others, then they need to be combined in logical XOR. To do this, drag the code icon(s) from their relative Expected Code box into the Expected Code box of the XOR combination you wish to create. Then delete the empty box by selecting it with the mouse (highlighted) and pressing the delete key on your keyboard.



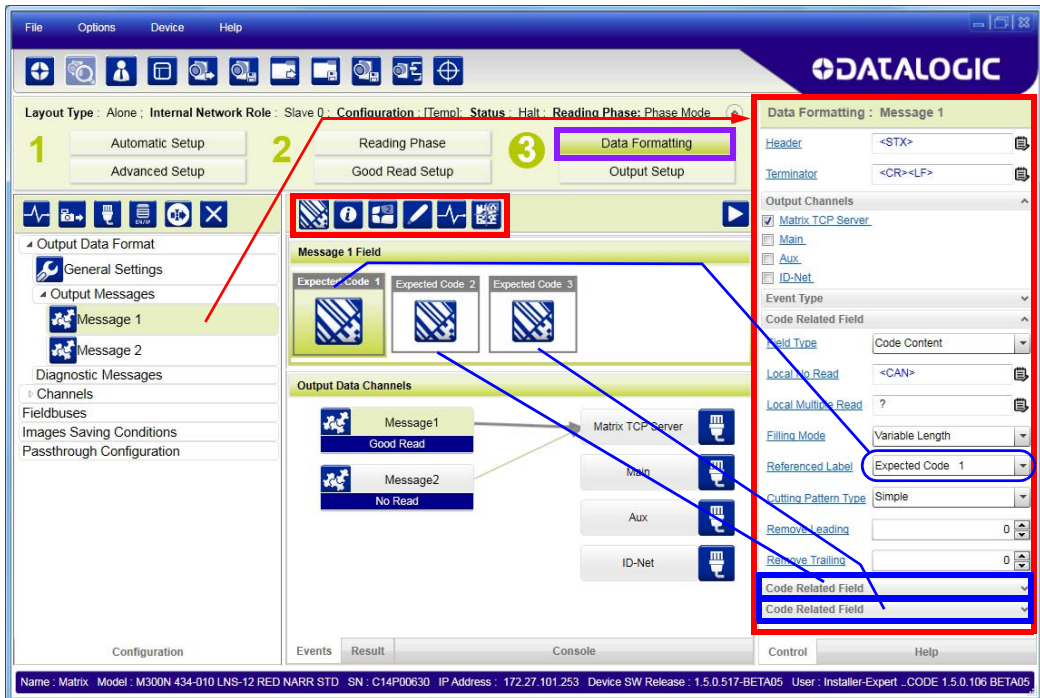


To create a logical AND condition from a logical XOR, create a new Expected Code box using the Add icon. Then drag the desired code icon from one box to the other.



Data Formatting

1. Configure your application specific Data Formatting Message(s) from the Configuration Parameters tree area: Message 1, Message 2, etc.

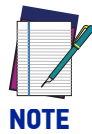
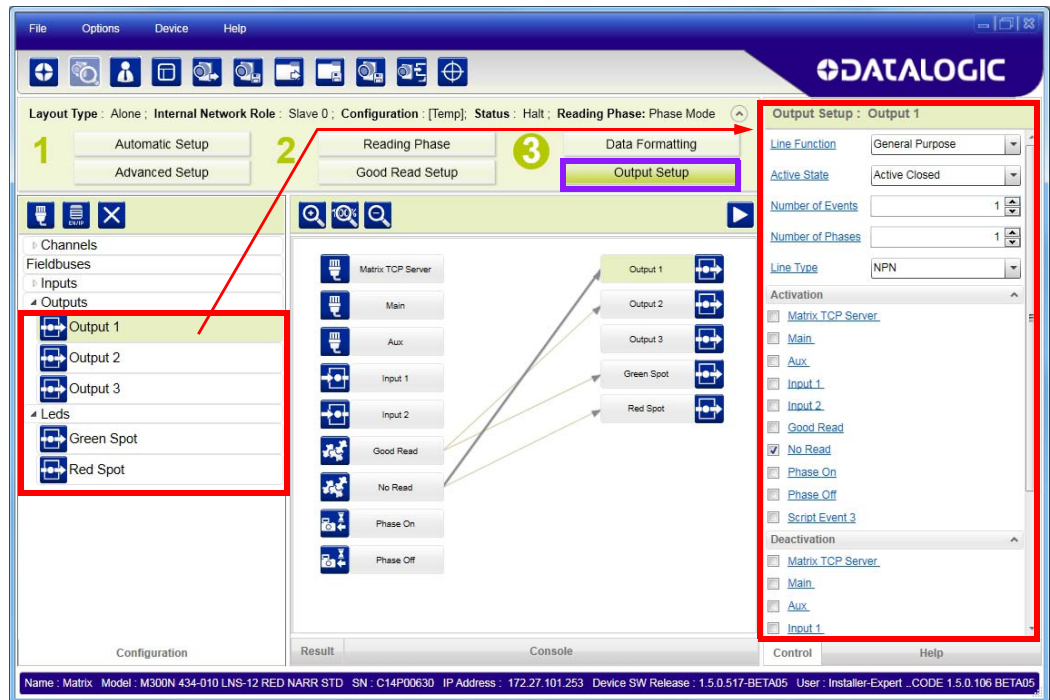


You can add fields to the output message by clicking on the icons above the Message Field area. They will be appended to the message. You can drag them to position them between other fields in the message so that the output message is ordered according to your application requirements.

Each field has its own relative configuration parameters in the parameters panel.

Output Setup

1. Configure your application specific Digital Output(s) and Green/Red Spots (if used) from the Configuration Parameters tree area: Output 1, Output 2, etc.



NOTE

Save the configuration from temporary memory to permanent memory, overwriting the previously saved configuration.

STEP 8 - TEST MODE

Use a code suitable to your application to test the reading performance of the system.

1. Enter the *Test* function by pressing and holding the X-PRESS push button until the Test LED is on.
2. Release the button to enter the *Test* function.
Once entered, the Bar Graph on the five LEDs is activated and if the reader starts reading codes the Bar-Graph shows the Good Read Rate.



Figure 19 - X-PRESS Interface: Test Function

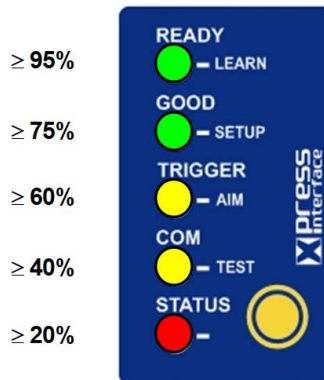
3. To exit the Test, press the X-PRESS push button once.



NOTE

By default, the Test exits automatically after three minutes.

The Bar Graph has the following meaning:



In case of No Read condition, only the STATUS LED (red) is on and blinks.

ADVANCED READER CONFIGURATION

For further details on advanced product configuration, refer to the DL.CODE User's Guide available in the DL.CODE Help menu.

Host Mode Programming

The reader can also be partially configured from a host computer using the Host Mode programming procedure.

CHAPTER 2

INTRODUCTION

PRODUCT DESCRIPTION

Matrix 210N is the new Datalogic 2D reader offering excellent reading performance, ultra compact size and extreme ease of use. Thanks to innovative optical features, advanced software functions and complete connectivity options, Matrix 210N is the cost effective solution for applications where the space is very limited.

Ultra Compact Size

Compact dimensions allow flexible mounting and positioning in narrow spaces.

Excellent Reading Performance

WVGA image sensor, up to 60 frames/s acquisition rate and dynamic reading capability, together with powerful decoding libraries provide excellent performance on a wide range of code symbologies as well as damaged and low quality codes. Matrix 210N allows reading 10 mils codes in moving applications at speeds up to 2 m/sec.

Innovative Optical Features

The Liquid Lens technology allows dynamic focusing to extend Depth of Field. The innovative optical and lighting systems ensure wide field of view at short reading distances, combined with excellent illumination pattern.

Ease Of Use

The intuitive X-PRESS Human Machine Interface makes installation and maintenance easier than ever thanks to a five LED bar graph and the multi-function key providing immediate access to relevant functions such as Aiming, Setup (for automatic imager calibration), Learn (for automatic code setting), Test Mode (for bar graph activation). A Green Spot provides immediate Good Read feedback.

Enhanced Connectivity

An embedded Ethernet interface allows for faster communication

An embedded high speed ID-NET communication interface allows efficient data collection and simplifies network wiring.

Industrial Features

Matrix 210N, with its rugged construction, IP65 protection class and 10 to 30 VDC power supply is the ideal product for industrial applications.

Matrix 210N has been developed for use in numerous industries like:

Electronics

- PCB Board Tracking
- Electronics Product Tracking

Pharmaceutical & Chemical

- Medical Devices Traceability
- Pharmaceutical and Medicine Manufacturing

OEM

- Chemical & Biomedical Analysis Machines
- Access Control Systems
- Self Service Systems (ATM, Kiosks)
- Print & Apply systems
- Document Handling

This technology intrinsically provides omni-directional reading.

Standard Application Program

A Standard Application Program is factory-loaded onto Matrix 210N. This program controls code reading, data formatting, Ethernet interfacing, serial port and USB interfacing, and many other operating and control parameters. It is completely user configurable from a Laptop or PC using the dedicated configuration software program DL.CODE, provided on the DL.CODE mini-DVD (downloaded .zip file or mini-DVD accessory).

There are different programmable operating modes to suit various code reading system requirements.

Quick, automatic positioning, calibration and code setting of the imager can be accomplished using the X-PRESS button and LEDs on top of the reader without the necessity of a PC.

The previous functions can also be performed through DL.CODE. This tool includes visual feedback from the reader.

DL.CODE allows verifying the exact positioning of the reader to maximize its reading performance.

Statistics on the reading performance can also be visualized through a dedicated window in DL.CODE.

Programmability

If your requirements are not met by the Standard Application Program, Custom Application Programs can be requested at your local Datalogic distributor.

Some of the main features of this reader are given below:

- Ultra Compact Dimensions
- Outstanding decoding capability 1D, 2D, Stacked, and Postal symbologies
- High performance on dynamic reading applications
- X-PRESS for easy and intuitive setup
- Optical Aiming System
- 10 to 30 Vdc Power Supply
- High Speed on-board Ethernet Connectivity
- ID-NET embedded high-speed network connectivity
- Image Cropping for higher frame rate

INDICATOR AND KEYPAD BUTTON

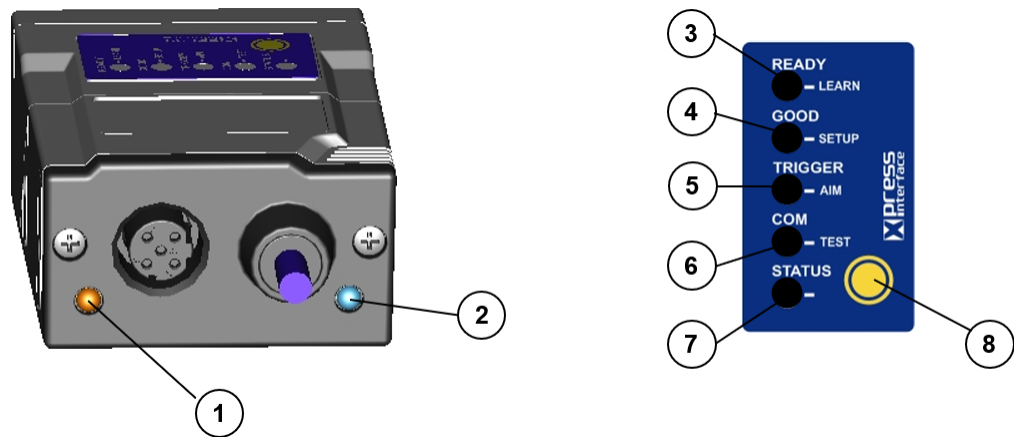


Figure 20 - Indicators

The following LED indicators are located on the reader:

NET	On the connector side of the reader near the Ethernet connector, the orange ETHERNET NETWORK PRESENCE LED indicates the on-board Ethernet network connection (Figure 20, 1)
PWR	On the connector side of the reader near the cable, the blue POWER ON LED indicates the reader is correctly powered (Figure 20, 2)

In normal operating mode the colors and meaning of the five LEDs are illustrated in the following table:

READY	green LED indicates that the reader is ready to operate (Figure 20, 3)
GOOD	green LED confirms successful reading (Figure 20, 4)
TRIGGER	yellow LED indicates the status of the reading phase (Figure 20, 5)
COM	yellow LED indicates active communication on the main serial port * (Figure 20, 6)
STATUS	red LED indicates a NO READ result (Figure 20, 7)

* When connected to a Fieldbus network through the CBX500, the COM LED is always active, even in the absence of data transmission, because of polling activity on the Fieldbus network.

During the reader startup (reset or restart phase), these five LEDs blink for one second.

In X-PRESS Configuration mode the colors and meaning of these five LEDs are described in X-PRESS Human Machine Interface.

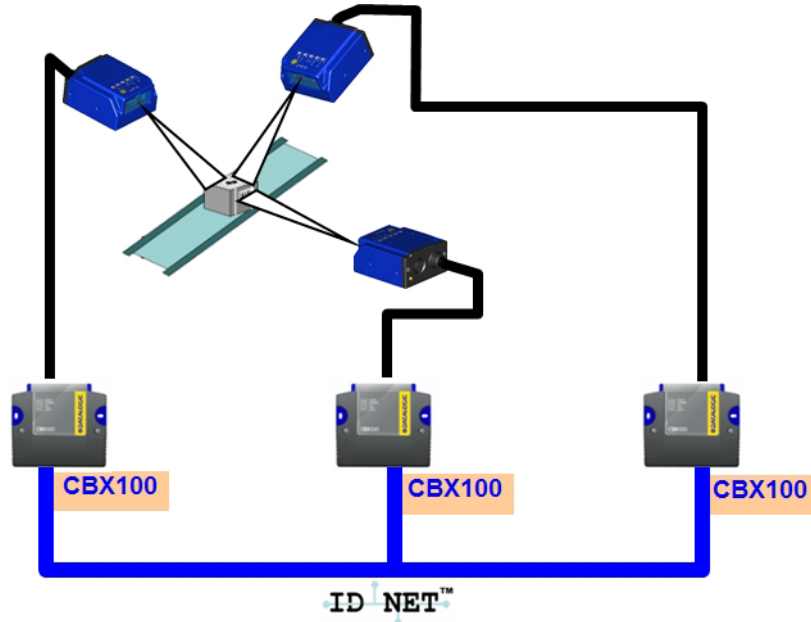
The keypad button (Figure 20, 8) is software programmable. By default it starts the X-PRESS interface for quick installation without using a PC (see [Chapter 1, Rapid Configuration](#)).

ID-NET

The ID-NET™ network is a built-in high-speed interface dedicated for high-speed reader interconnection. ID-NET is in addition to the Main and Auxiliary serial interfaces.

The following network configurations are available:

- **ID-NET Synchronized:** Single station – multiple readers

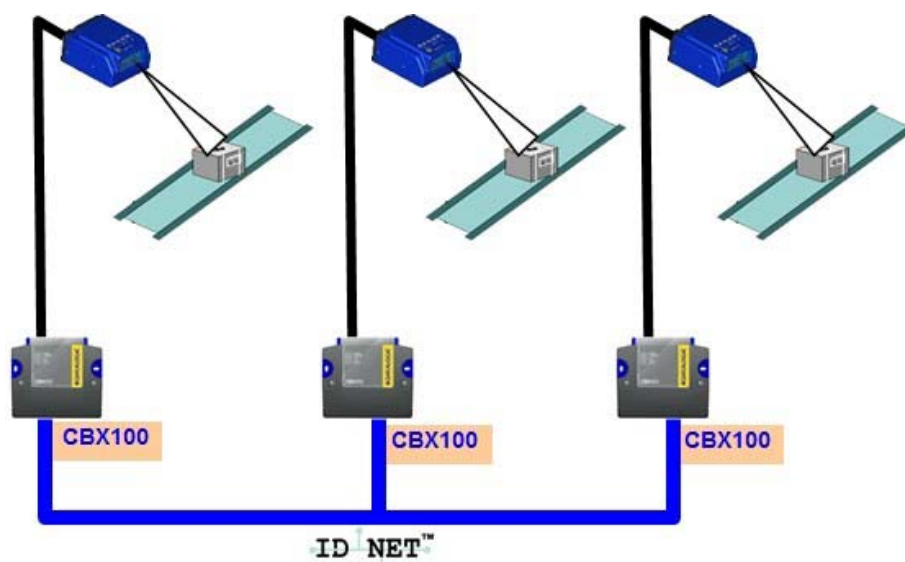


ID-NET interface allows local connection of multiple readers reading different sides of the same target. All readers share a single presence sensor and activate/deactivate simultaneously.

At the end of each reading phase a single data message is transmitted to the host. Thanks to ID-NET, data communication among readers is highly efficient so that an immediate result will be available.

See "[ID-NET Interface](#)" on page 66 for connection details and "[Internal Network Configurations](#)" on page 120 for configuration details.

- **ID-NET Multidata:** Multiple stations – single reader



ID-NET interface allows connection of readers reading objects placed on independent conveyors. All readers are typically located far away from each other and they can have different operating modes from each other.

At the end of each reading phase, each reader transmits its own data message to the host. Thanks to ID-NET, data collection among readers is accomplished at a high speed without the need of an external multiplexing device. This leads to an overall cost reduction and to simple system wiring.

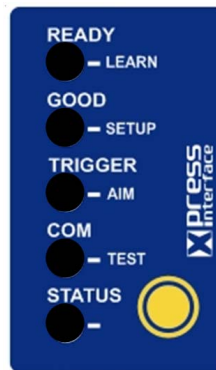
See "[ID-NET Interface](#)" on page 66 for connection details and "[Internal Network Configurations](#)" on page 120 for configuration details.

X-PRESS HUMAN MACHINE INTERFACE

X-PRESS is the intuitive Human Machine Interface designed to improve ease of installation and maintenance.

Status information is clearly presented by means of the five colored LEDs, whereas the single push button gives immediate access to the following relevant functions:

- Learn to self-detect and auto-configure for reading unknown codes.
- Setup to perform Exposure Time and Gain calibration.
- Aim/Locate to turn on the blue ring to aid positioning.
- Test with bar graph visualization to check static reading performance.

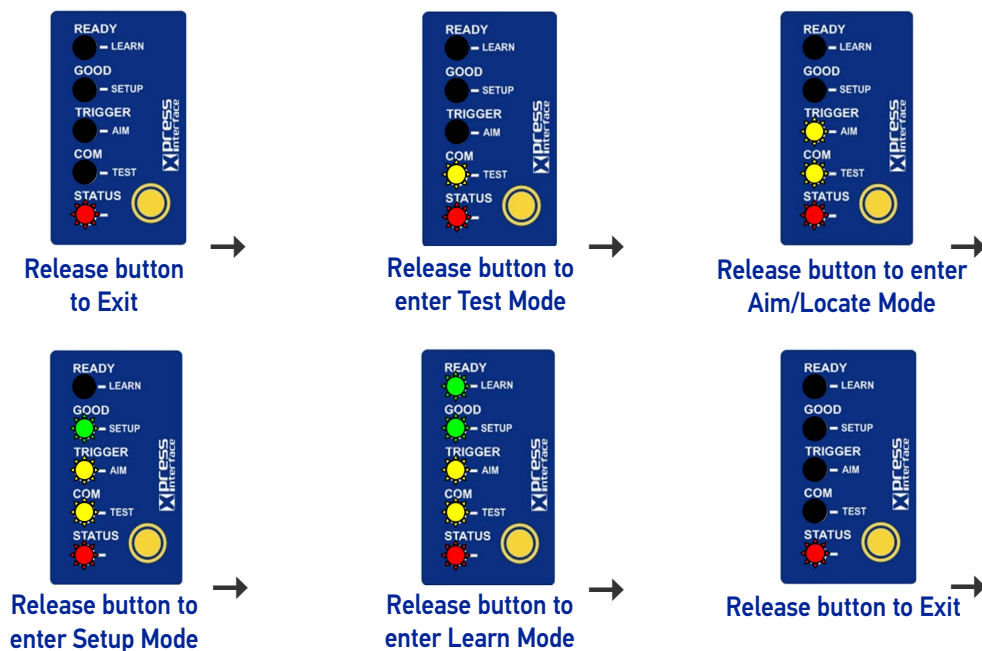


X-PRESS Functions

Quick access to the following functions is provided by an easy procedure using the push button:

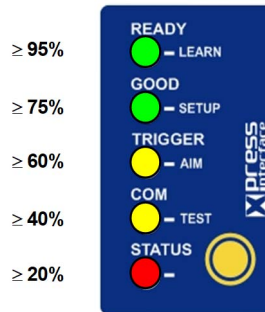
1. **Press** the button (the Status LED will give a visual feedback).
2. **Hold** the button until the specific function LED is on (Test, Focus, Setup or Learn).
3. **Release** the button to enter the specific function.

Once button is pressed, the cycle of LEDs activation is as follows:



Test Mode

Once entered, the Bar Graph on the five LEDs is activated and if the imager starts reading codes the Bar-Graph shows the Good Read Rate. The Bar Graph has the following meaning:



In case of a NO READ condition, only the Status LED is on and blinks.

To exit the Test Mode, press the X-PRESS push button once.



NOTE

By default, the Test exits automatically after three minutes.

Aim/Autofocus

This function causes the laser pointers to turn on. Since the laser pointers are centered on the FOV they can be used to position the imager on the code. The Aim LED blinks to indicate this state. After a short delay, this function also performs the Autofocus procedure for Liquid Lens models.

You can exit the Aim/Autofocus function at any time by pressing the X-PRESS push button once. After a short delay the autofocus procedure is canceled and the laser pointers turn off.

Setup

Once entered, the imager automatically performs Image Acquisition parameter calibration for the specific code presented to it.

The Setup LED will blink until the procedure is completed.

The Setup procedure ends when the Image Acquisition parameters are successfully saved in the reader memory, the Setup LED will stop blinking and Matrix 210N emits 3 high-pitched beeps.

If the calibration cannot be reached after a timeout of about 5 (five) seconds Matrix 210N will exit without saving the parameters to memory, the Setup LED will not remain on continuously but it will stop blinking. In this case Matrix 210N emits a long low-pitched beep.

Learn

Once entered, the imager starts a procedure to automatically detect and recognize a **single code** which is presented to it. Successive Learns will substitute the current code.


The Learn LED will blink until the procedure is completed.

The Learn procedure ends when the Image Processing and Decoding parameters are successfully saved in the reader memory, the Green Spot is activated, the Learn LED will remain on continuously and Matrix 210N emits 3 high-pitched beeps.

If the calibration cannot be reached after a timeout of about 3 (three) minutes, Matrix 210N will exit without saving the parameters to memory, the Learn LED will not remain on continuously but it will stop blinking. In this case Matrix 210N emits a long low-pitched beep.

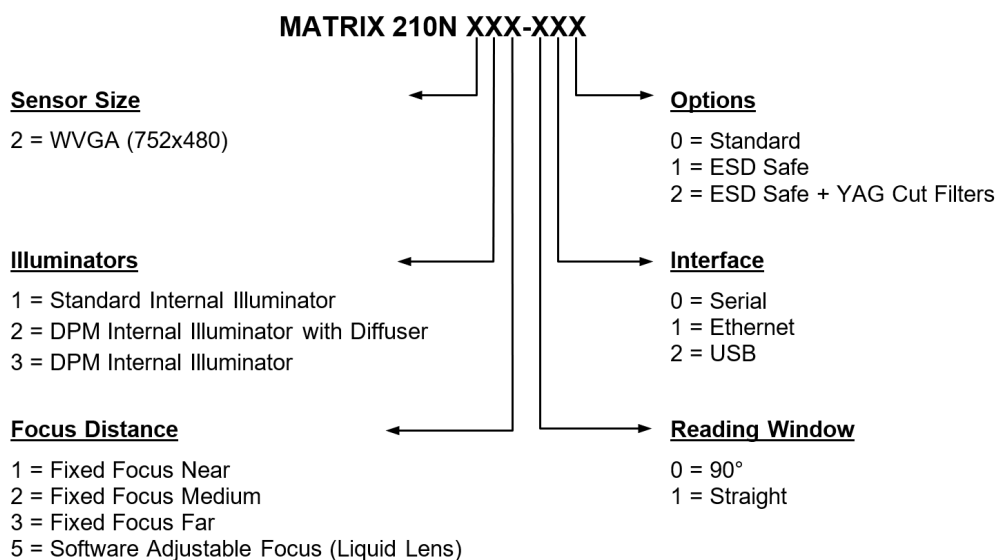
Diagnostic Indication

The "STATUS" (red) and "READY" LED (green) blink simultaneously to signal the presence of an error. Diagnostic message transmission on interfaces can be enabled to provide details about specific error conditions. See the Diagnostic Error Conditions chart in the Diagnostic page of the DL.CODE Monitor.

	LED	STATUS
	Ready	Blink
	Good	
	Trigger	
	COM	
	Status	Blink

MODEL DESCRIPTION

Matrix 210N readers are described by their model number which indicates the characteristics listed in the diagram below. Not all combinations are available. For a complete list of combinations see the Models tab on the Product page of the website.



AVAILABLE MODELS

PART NUMBER	DESCRIPTION
937501238	MATRIX 210N 211-100 WVGA-NEAR-25P-ST
937501239	MATRIX 210N 212-100 WVGA-MED-25P-ST
937501240	MATRIX 210N 213-100 WVGA-FAR-25P-ST
937501241	MATRIX 210N 211-110 WVGA-NEAR-ETH-ST
937501242	MATRIX 210N 212-110 WVGA-MED-ETH-ST
937501243	MATRIX 210N 213-110 WVGA-FAR-ETH-ST
937501244	MATRIX 210N 211-120 WVGA-NEAR-USB-ST
937501245	MATRIX 210N 212-120 WVGA-MED-USB-ST
937501246	MATRIX 210N 213-120 WVGA-FAR-USB-ST
937501247	MATRIX 210N 211-000 WVGA-NEAR-90-25P-ST
937501248	MATRIX 210N 212-000 WVGA-MED-90-25P-ST
937501249	MATRIX 210N 213-000 WVGA-FAR-90-25P-ST
937501250	MATRIX 210N 211-010 WVGA-NEAR-90-ETH-ST
937501251	MATRIX 210N 212-010 WVGA-MED-90-ETH-ST
937501252	MATRIX 210N 213-010 WVGA-FAR-90-ETH-ST
937501253	MATRIX 210N 211-020 WVGA-NEAR-90-USB-ST
937501254	MATRIX 210N 212-020 WVGA-MED-90-USB-ST
937501255	MATRIX 210N 213-020 WVGA-FAR-90-USB-ST
937501256	MATRIX 210N 211-101 WVGA-NEAR-25P-ES
937501257	MATRIX 210N 212-101 WVGA-MED-25P-ES
937501258	MATRIX 210N 213-101 WVGA-FAR-25P-ES
937501259	MATRIX 210N 211-111 WVGA-NEAR-ETH-ES
937501260	MATRIX 210N 212-111 WVGA-MED-ETH-ES
937501261	MATRIX 210N 213-111 WVGA-FAR-ETH-ES

PART NUMBER	DESCRIPTION
937501262	MATRIX 210N 211-121 WVGA-NEAR-USB-ES
937501263	MATRIX 210N 212-121 WVGA-MED-USB-ES
937501264	MATRIX 210N 213-121 WVGA-FAR-USB-ES
937501265	MATRIX 210N 211-001 WVGA-NEAR-90-25P-ES
937501266	MATRIX 210N 212-001 WVGA-MED-90-25P-ES
937501267	MATRIX 210N 213-001 WVGA-FAR-90-25P-ES
937501268	MATRIX 210N 211-011 WVGA-NEAR-90-ETH-ES
937501269	MATRIX 210N 212-011 WVGA-MED-90-ETH-ES
937501270	MATRIX 210N 213-011 WVGA-FAR-90-ETH-ES
937501271	MATRIX 210N 211-021 WVGA-NEAR-90-USB-ES
937501272	MATRIX 210N 212-021 WVGA-MED-90-USB-ES
937501273	MATRIX 210N 213-021 WVGA-FAR-90-USB-ES
937501274	MATRIX 210N 211-112 WVGA-NEAR-ETH-ESYF
937501275	MATRIX 210N 212-112 WVGA-MED-ETH-ESYF
937501276	MATRIX 210N 213-112 WVGA-FAR-ETH-ESYF
937501277	MATRIX 210N 211-012 WVGA-NEAR-90-ETH-ESY
937501278	MATRIX 210N 212-012 WVGA-MED-90-ETH-ESYF
937501279	MATRIX 210N 213-012 WVGA-FAR-90-ETH-ESYF
937501280	MATRIX 210N 225-111 WVGA-LL-DPM-D-ETH-ES
937501281	MATRIX 210N 225-112 WVGA-LL-DPM-D-ETH-EY
937501282	MATRIX 210N 235-110 WVGA-DPM-LL-ETH-STD
937501283	MATRIX 210N 235-111 WVGA-DPM-LL-ETH-ES
937501284	MATRIX 210N 235-112 WVGA-DPM-LL-ETH-ESYF

ACCESSORIES

The following accessories can be used with the Matrix 210N reader.

ACCESSORY	DESCRIPTION	ORDER NO.
External Illuminator		
LT-700	Linear Array Lighting System	93A401028
BK-21-000	LT-700 Fixing Bracket	93ACC0052
Cables		
CAB-ETH-M01	M12-IP67 Ethernet Cable (1M)	93A051346
CAB-ETH-M03	M12-IP67 Ethernet Cable (3M)	93A051347
CAB-ETH-M05	M12-IP67 Ethernet Cable (5M)	93A051348
CBL-1534.02	Adapter Cable Ethernet M12 to RJ45	93A050057
CBL-1480-01	Thin M12/5P Male/Female (1M)	93A050049
CBL-1480-02	Thin M12/5P Male/Female (2M)	93A050050
CBL-1490	Term. Resist. Thin M12/5P/Male	93A050046
CBL-1496	Term. Resist. Thin M12/5P/Female	93A050047
Connectivity		
CBX100	Compact Connection Box	93A301067
CBX500	Modular Connection Box	93A301068
BM100	Backup Module for CBX100/500	93ACC1808
BM150	Display Module for CBX500	93ACC1809
Various Fieldbus Host Interface Modules and All-In-One Connection Box Kits are available		
BA100	DIN Rail Adapters	93ACC1821
BA200	Bosch and 80/20 Profile Adapters	93ACC1822
Various M12 Panel Connectors for CBX Connection Boxes are available		
QL100	Quick Link Slave ID-NET T-Connector	93ACC1860
QL150	Quick Link Slave ID-NET + Service T-Connector	93ACC1868
QL300	Quick Link Master ID-NET - Serial Host Connector	93ACC1862
QLM500	Quick Link Metal Master ID-NET - EtherNet/IP Gateway	93ACC0037
QLM600	Quick Link Metal Master ID-NET - Profibus Gateway	93ACC0033
QLM700	Quick Link Metal Master ID-NET - Profinet IO Gateway	93ACC0038
Various M12 Service Cables and Field Mount Connectors are available for Quick Link Series Connectors		
Power Supplies		
PG6002	AC/DC Power Supply Unit (US)	93ACC1718
PG6001	AC/DC Power Supply Unit (UK)	93ACC1719
PG6000	AC/DC Power Supply Unit (EU)	93ACC1720
Sensors		
MEP-593	Photocell Kit PNP (PH-1)	93ACC1791
MEP-543	Photocell Kit-NPN	93ACC1728
Brackets		
BK-21-020	Fixing Bracket Kit for 0 Degree (straight) models	93ACC0199
BK-21-030	Fixing Bracket Kit for 90 Degree models	93ACC0200

APPLICATION EXAMPLES

Document Handling

Matrix 210N is profitably used in the omnidirectional reading of 2D, stacked, linear and postal codes for example in automated document handling and mail processing systems.



Figure 21 - Address Coded in Data Matrix Symbology for Automated Mail Processing

Deformed or Overprinted Code Reading

Matrix 210N assures the reading of deformed and/or overprinted codes, even though damaged or printed on high reflective surfaces.



Figure 22 - Unidose Flow-Pack with PDF417 Code



Figure 23 - Overprinted Barcode Readable by Matrix 210N also Through the Envelope Window Film



Figure 24 - Barcode Printed on Curved Surface Readable by Matrix 300N in spite of Image Optical Distortion

Direct Part Marking

Matrix 210N is also very powerful in reading low-contrast direct part marked codes.



Figure 25 - Dot Matrix Code Directly Marked on Metal Surface by Using Dot Peening Technology

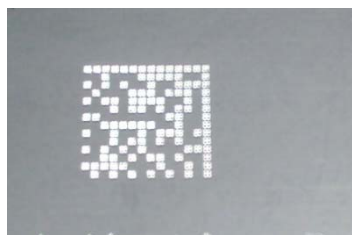


Figure 26 - Dot Peening Marking on Metal Surface with Multi-dot per Code Element



Figure 27 - Directly Marked Dot Matrix Code Characterized by Outstanding Separation Distance between Adjacent Code Elements

Ink-Jet Printing Technology

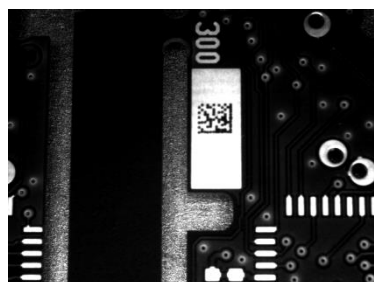


Figure 28 - Dot Matrix Code Directly Marked on PCB Copper Pad by Using Ink-Jet Technology

Laser Marking/Etching Technology



Figure 29 - Data Matrix Code Directly Marked on PCB Surface by Using Laser Etching Technology



If application codes must be read which are produced by Laser Marking in real time, use the correct diameter accessory IR Cut Filter with the Matrix 210N reader in order to avoid burning the CMOS sensor.

EXTERNAL LIGHTING SYSTEM

In some direct part marking applications best reading results are obtained by using an external lighting system. A series of accessory illuminators are available which cover a variety of applications.

The LT-700 Linear Array Lighting System provides a high intensity light source designed for the following applications:

- with uneven, noisy and scratched surfaces;
- where dot peening or laser etching codes are directly marked onto metal surfaces or PCBs and need to be highlighted. Here the use of more than one LT-700 at different positions can remove any shadowing effect;
- in the presence of highly reflective surfaces (metal, glass, etc.) causing direct reflections. Low light path to surface angles strongly reduce direct reflections.



Figure 30 - LT-700 Linear Array Lighting System

CHAPTER 3

INSTALLATION

PACKAGE CONTENTS

Verify that the Matrix 210N reader and all the parts supplied with the equipment are present and intact when opening the packaging; the list of parts includes:

- Matrix 210N reader
- Quick Reference Guide
- Test Chart
- Mounting Kit
 - Mounting Screws (2)
 - Washers (2)
 - Mounting Bracket

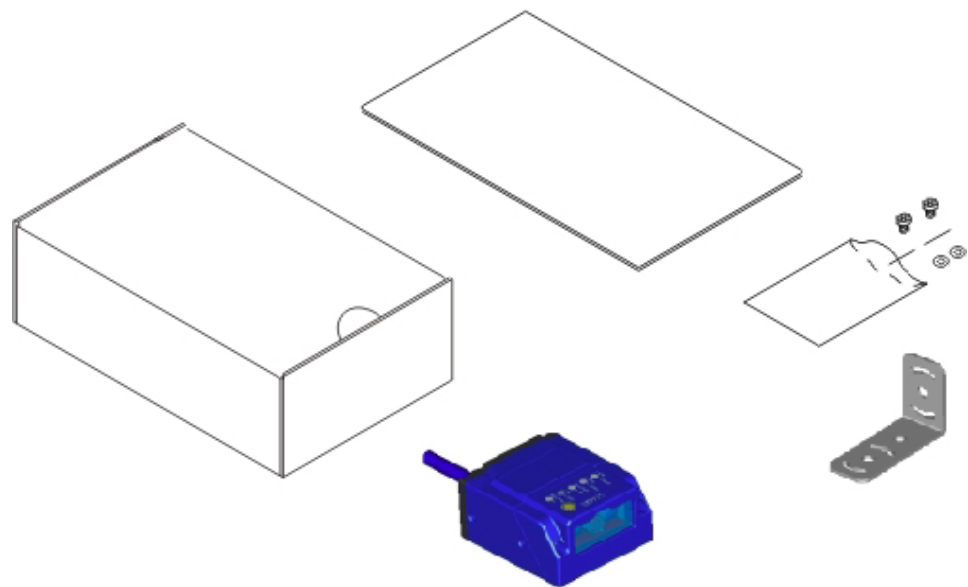


Figure 31 - Package Contents

MECHANICAL DIMENSIONS

Matrix 210N can be installed to operate in different positions. The four screw holes (M3 x 4) on the body of the reader are for mechanical fixture.

The diagram below gives the overall dimensions of the reader and may be used for its installation.

Refer to page 59 for various mounting solutions and correct positioning, and [Chapter 6, Reading Features](#) for Reading Distance considerations.

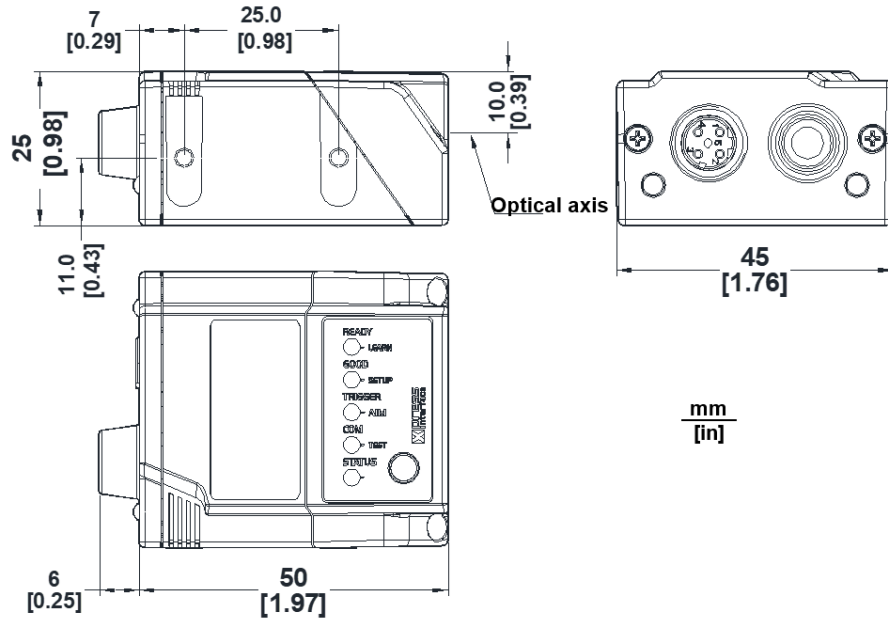


Figure 32 - Straight Model Overall Dimensions

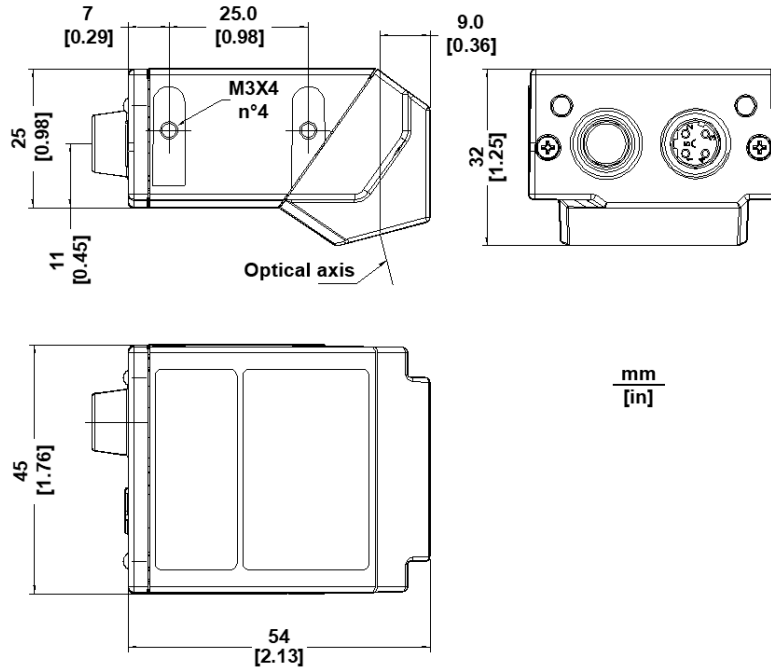


Figure 33 - 90° Model Overall Dimensions

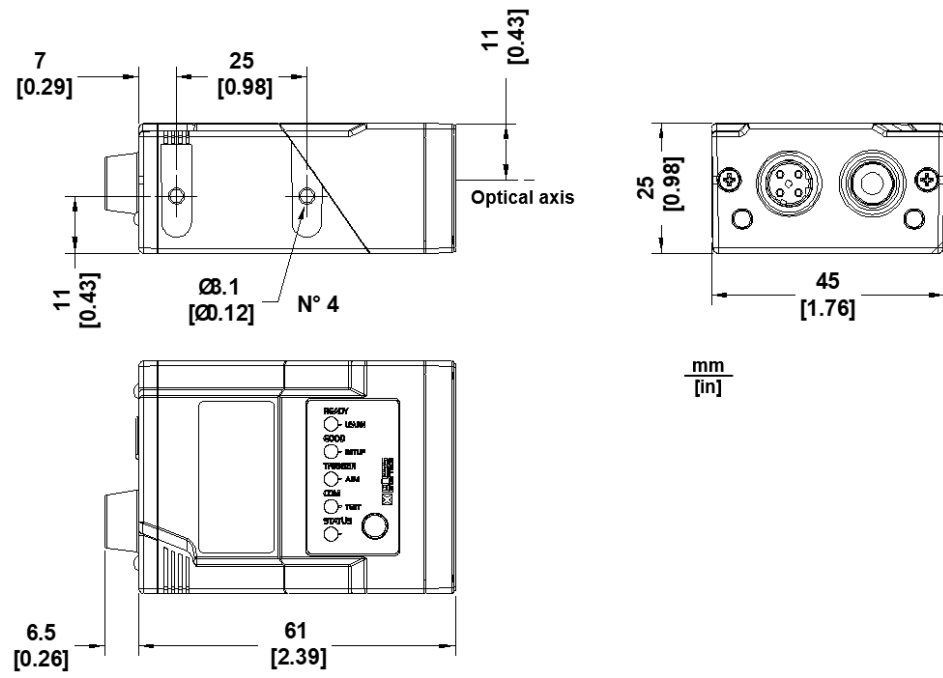


Figure 34 - Liquid Lens Model Overall Dimensions

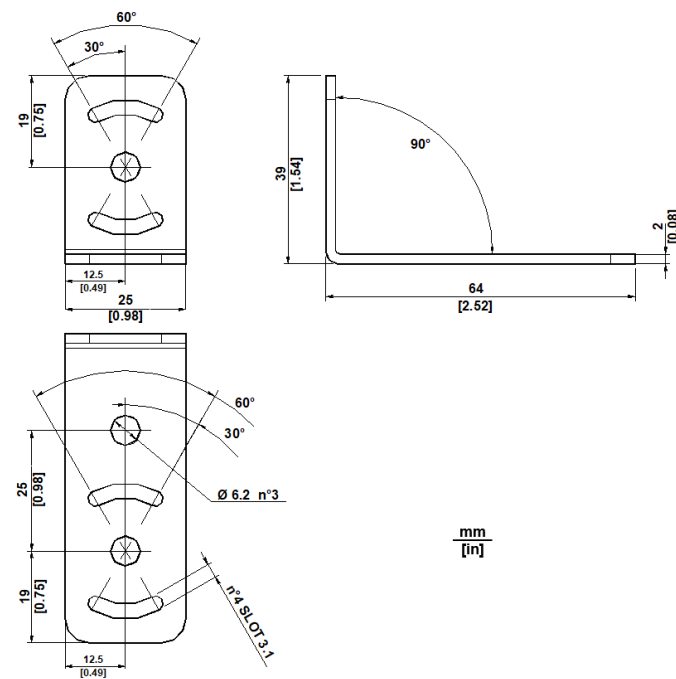


Figure 35 - ST-336 Mounting Bracket Overall Dimensions

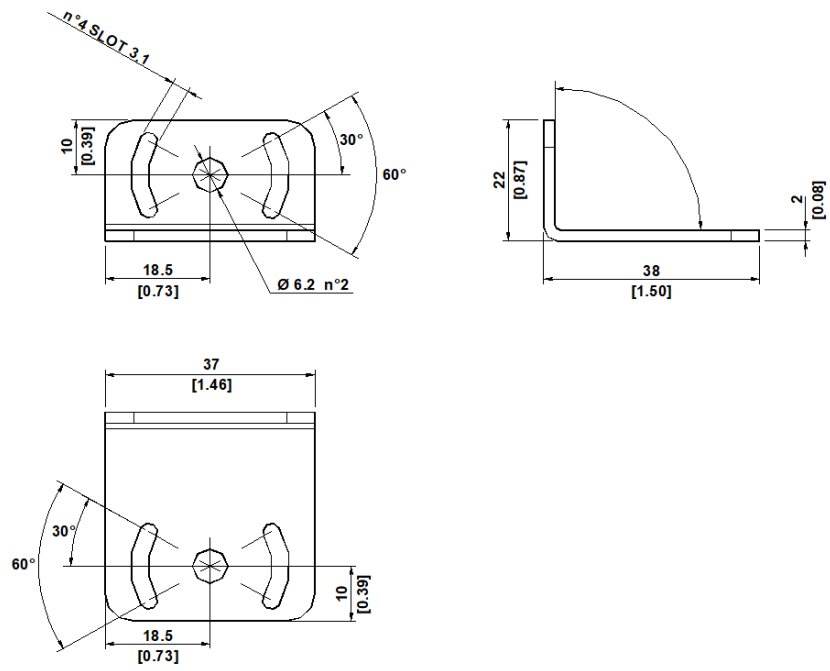


Figure 36 - ST-337 Mounting Bracket Overall Dimensions

MOUNTING AND POSITIONING MATRIX 210N

Using the Matrix 210N mounting brackets you can obtain rotation on the various axes of the reader as shown in the diagrams below:

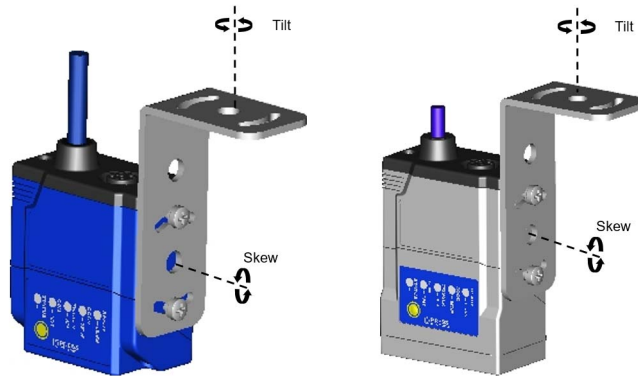


Figure 37 - Straight Model with ST-336 Mounting Bracket – External Positioning

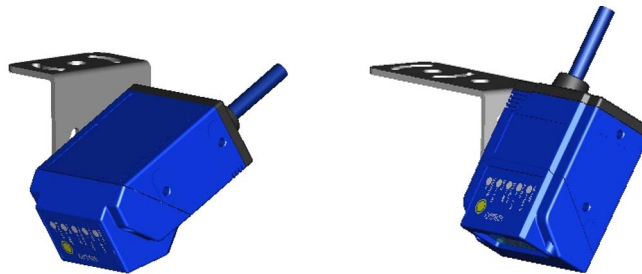


Figure 38 - Mounting Bracket External Positioning

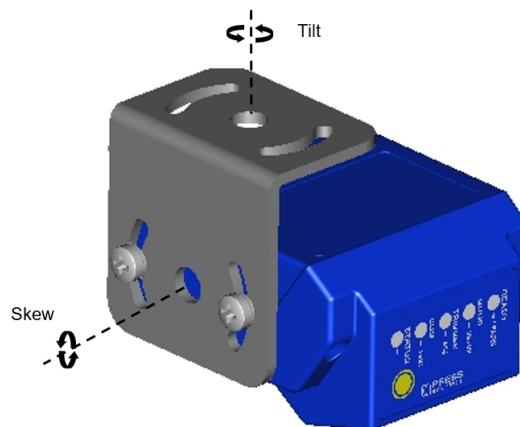


Figure 39 - Straight Model with ST-337 Mounting Bracket – Internal Positioning



NOTE

For applications where strong vibrations or continuous bumps are present, it is recommended to use a double mounting bracket solution.

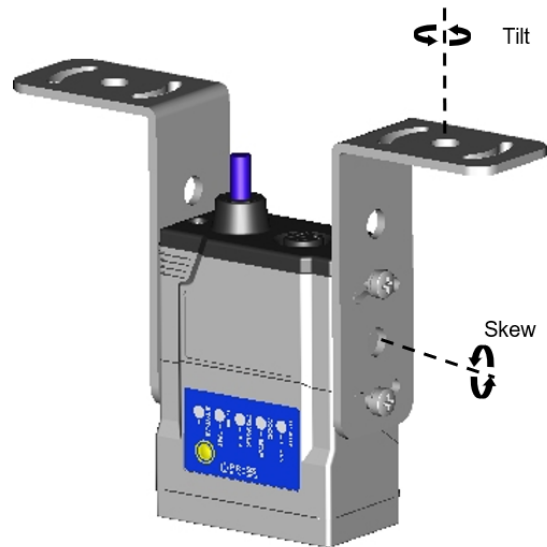
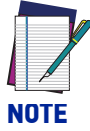


Figure 40 - Double Mounting Bracket Solution

Matrix 210N is able to decode code labels at a variety of angles; however significant angular distortion may degrade reading performance.

When mounting Matrix 210N, take into consideration these **ideal** label position angles: **Pitch or Skew 10° to 20° and Tilt 0°.**



NOTE

Since Matrix 210N is omni-directional on the code plane, the Pitch and Skew angles have the same significance with respect to the code plane. However, in some advanced code reading applications performance can be improved by modifying the Skew angle.

The **Pitch, Skew and Tilt** angles are represented in Figure 41. Follow the suggestions below for the best orientation:

Position the reader in order to avoid the direct reflection of the light emitted by the Matrix 210N reader; it is advised to **assure at least 10°** for the Skew angle.

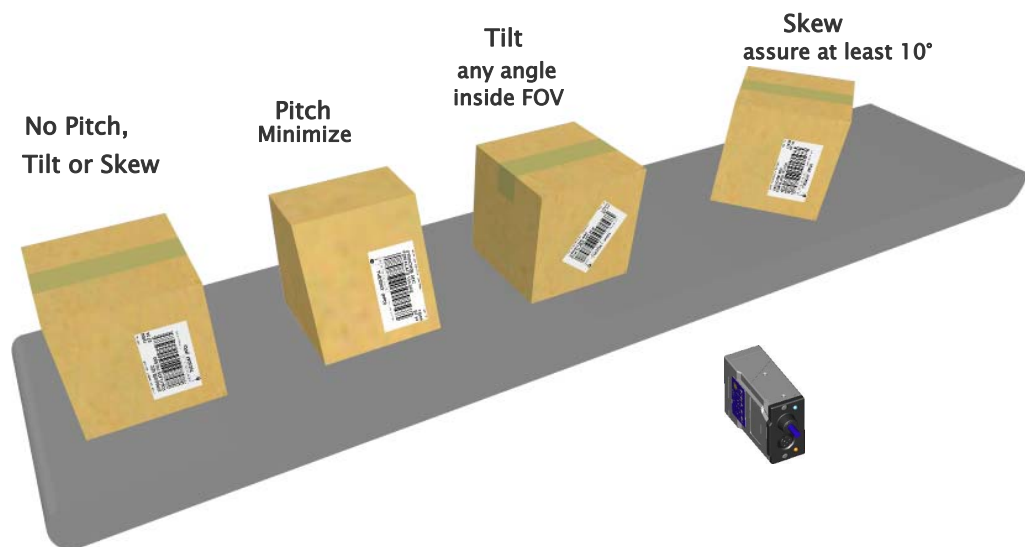


Figure 41 - Pitch, Tilt, and Skew Angles

In some cases, such as low contrast or low illumination, it can be useful to use a **Pitch or Skew** angle = 0°.

The **Tilt** angle is also represented in Figure 41. Matrix 210N can read labels with any tilt angle. Keep in mind however, that since linear barcodes are rectangular, the reader should be aligned to fit them into the horizontal FOV.

See [Chapter 6, Reading Features](#) for FOV vs. Reading Distance considerations.

CHAPTER 4

CBX ELECTRICAL CONNECTIONS

All Matrix 210N models can be connected to a CBX connection box.

We recommend making system connections through one of the CBX connection boxes since they offer the advantages of easy connection, easy device replacement, and filtered reference signals.



NOTE

If you require direct wiring to the reader the details of the connector pins and relative connections are indicated in Appendix B.



NOTE

To avoid electromagnetic interference when the reader is connected to a CBX connection box, verify the jumper positions in the CBX as indicated in its Installation Manual.

CBX CONNECTION BOX PINOUT

The table below gives the pinout of the CBX100/500 terminal block connectors. Use this pinout when the Matrix 210N reader is connected by means of the CBX100/500:

Group	Label	Description
Input Power	Vdc	Power Supply Input Voltage +
	GND	Power Supply Input Voltage -
	Earth	Protection Earth Ground
Inputs	+V	Power Source - External Trigger
	I1A	External Trigger A (polarity insensitive)
	I1B	External Trigger B (polarity insensitive)
	-V	Power Reference - External Trigger
	+V	Power Source - Inputs
	I2A	Input 2 A (polarity insensitive)
	I2B	Input 2 B (polarity insensitive)
	-V	Power Reference - Inputs
Outputs	+V	Power Source - Outputs
	-V	Power Reference - Outputs
	O1+	Output 1 + opto-isolated and polarity sensitive
	O1-	Output 1 - opto-isolated and polarity sensitive
	O2+	Output 2 + opto-isolated and polarity sensitive
	O2-	Output 2 - opto-isolated and polarity sensitive
Auxiliary Interface	TX	Transmit Data
	RX	Receive Data
	SGND	Auxiliary Interface Signal Ground
ID-NET	REF	Network Reference
	ID+	ID-NET network data +
	ID-	ID-NET network data -
	Shield	Network Cable Shield
Main Interface	RS232	RS422 Full Duplex
	TX	TX+
	RX	*RX+
	-	TX-
	-	*RX-
	SGND	SGND

* Do not leave floating, see ["RS422 Full Duplex Interface"](#) on page 65 for connection details.

POWER SUPPLY

Power can be supplied to the reader through the CBX100/500 spring clamp terminal pins as shown in Figure 42:

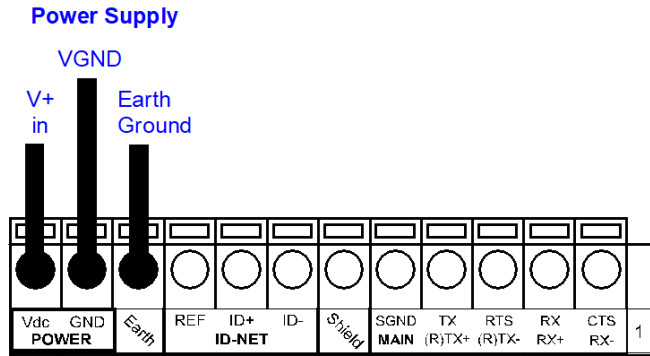


Figure 42 - Power Supply Connections

The power must be between 10 and 30 Vdc only.

It is recommended to connect the device CHASSIS to earth ground (Earth) by setting the appropriate jumper in the CBX connection box. See the CBX Installation Manual for details.

MAIN SERIAL INTERFACE



Do not connect to the Main Interface spring clamp terminals if using Host Interface Modules (Fieldbus) with the CBX500.

The signals relative to the following serial interface types are available on the CBX spring clamp terminal blocks.

The main serial interface type and its parameters (baud rate, data bits, etc.) can be defined by the user via DL.CODE software. For more details refer to the Help On Line page of the Reading Phase step (Channels) in DL.CODE.

Details regarding the connections and use of the interfaces are given in the next paragraphs.

RS232 Interface

The RS232 interface is generally used for Point-to-Point connections. When it is connected to the host computer it allows transmission of code data.

The following pins are used for RS232 interface connection:

CBX100/500	Description
TX	Transmit Data
RX	Receive Data
SGND	Signal Ground

It is always advisable to use shielded cables. The overall maximum cable length must be less than 15 m (49.2 ft).

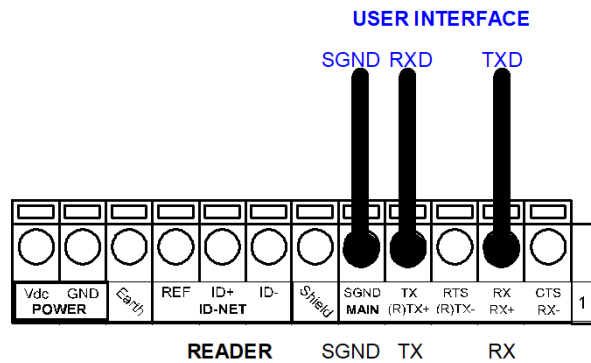


Figure 43 - RS232 Main Interface Connections

RS422 Full Duplex Interface

The RS422 full-duplex (5 wires + shield) interface is used for non-pollled communication protocols in point-to-point connections over longer distances (max 1200 m / 3940 ft) than those acceptable for RS232 communications or in electrically noisy environments.

The CBX pinout follows:

CBX100/500	Description
TX+	RS422 Transmit Data +
RX+	RS422 Receive Data +
TX-	RS422 Transmit Data -
RX-	RS422 Receive Data -
SGND	Signal Ground

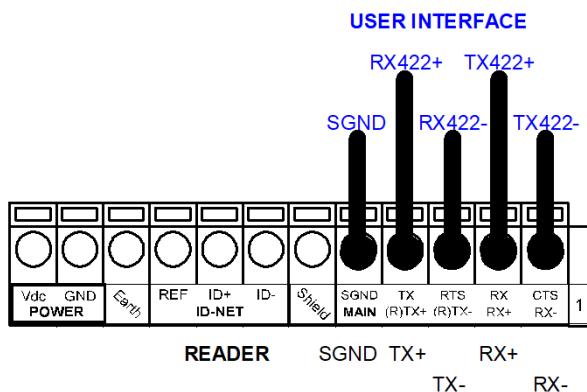


Figure 44 - RS422 Full Duplex Connections



NOTE

For applications that do not use RS422 transmission to the reader (terminal block RX+ and RX- signals), do not leave these lines floating but connect them to SGND as shown below.

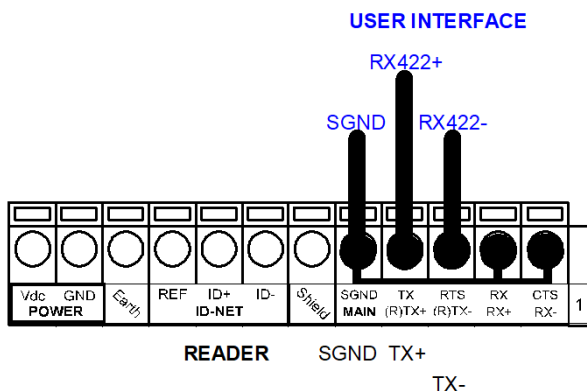


Figure 45 - RS422 Full Duplex Connections Using Only TX Signals to Host

ID-NET INTERFACE

CBX100/500	Description
Shield	Network Cable Shield
ID+	ID-NET Network Data +
ID-	ID-NET Network Data -
REF	Network Reference

ID-NET Cables

The following instructions are referred to Figure 47, Figure 48 and Figure 49.

- The general cable type specifications are: CAT5 twisted pair + additional CAT5 twisted pair, shielded cable AWG 24 (or AWG 22) stranded flexible.
We recommend using DeviceNet cables (drop or trunk type) to the following reference standards:
AN50325 – IEC 62026
UL STYLE 2502 80°C 30V
- Cable Shield **MUST** be connected to earth ground **ONLY** at the Master.
- NEVER use ID-NET cable shield as common reference.
- The ID-NET max cable length depends on the baudrate used (see the Baudrate Table below).
- For Common Power Connections use only 2 wires (ID+ and ID-).
 - DC Voltage Power cable (Vdc – GND) should be handled as a signal cable (i.e. do not put it together with AC cable):
 - Wire dimensioning must be checked in order to avoid voltage drops greater than 0.8 Volts.
 - Cable should lie down as near as possible to the ID-NET cable (avoiding wide loops between them).
- Reader's chassis may be connected to earth.
- Network inside the same building.

Baudrate Table				
Baudrate	125 kbps	250 kbps	500 kbps	1 Mbps
Cable Length	1200 m	900 m	700 m	*

* Application dependent, contact your Datalogic representative for details.



NOTE

The default ID-NET baudrate is 500 kbps. Lower ID-NET baudrates allow longer cable lengths.

ID-NET Response Time

The following figure shows the response time of the ID-NET network. This time is defined as the period between the Trigger activation and the beginning of data transmission to the Host.

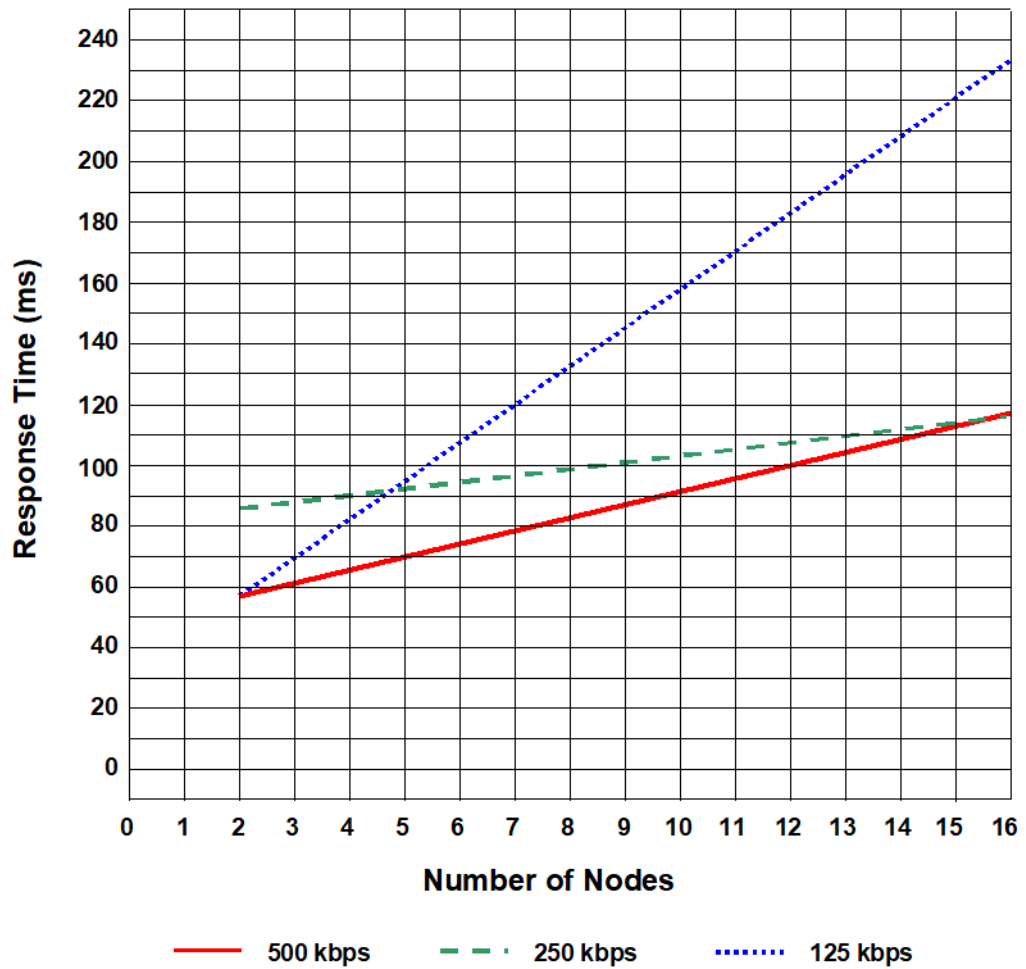


Figure 46 - ID-NET Response Time

Conditions

- ID-NET M/S Synchronized layout
- message length = 50 bytes per node

ID-NET Network Termination

The network must be properly terminated in the first and last reader of the network. This is done by setting the ID-NET Termination Resistance Switch in the CBX100/500 to ON.

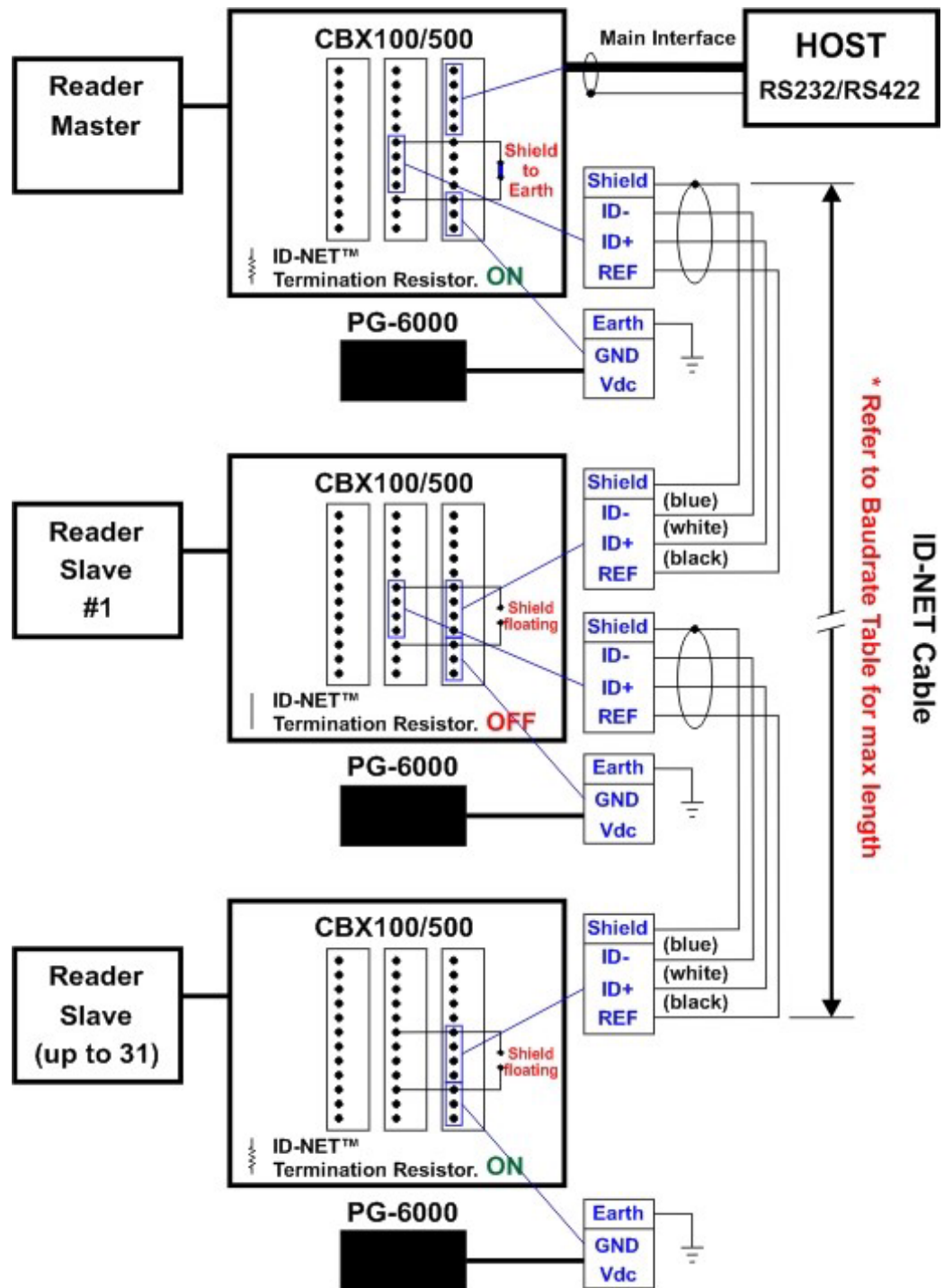


Figure 47 - ID-NET Network Connections with isolated power blocks

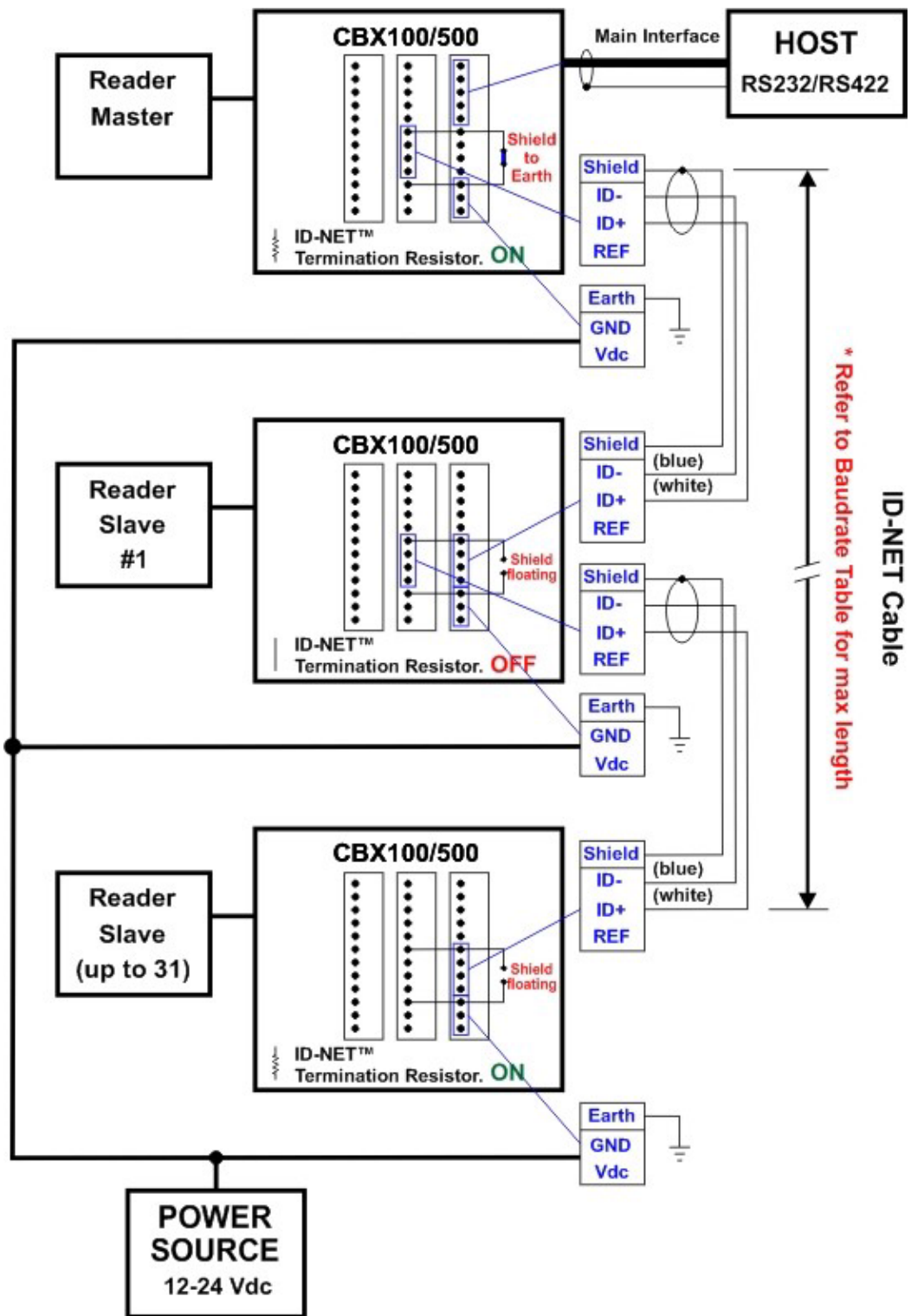


Figure 48 - ID-NET Network Connections with Common Power Branch Network

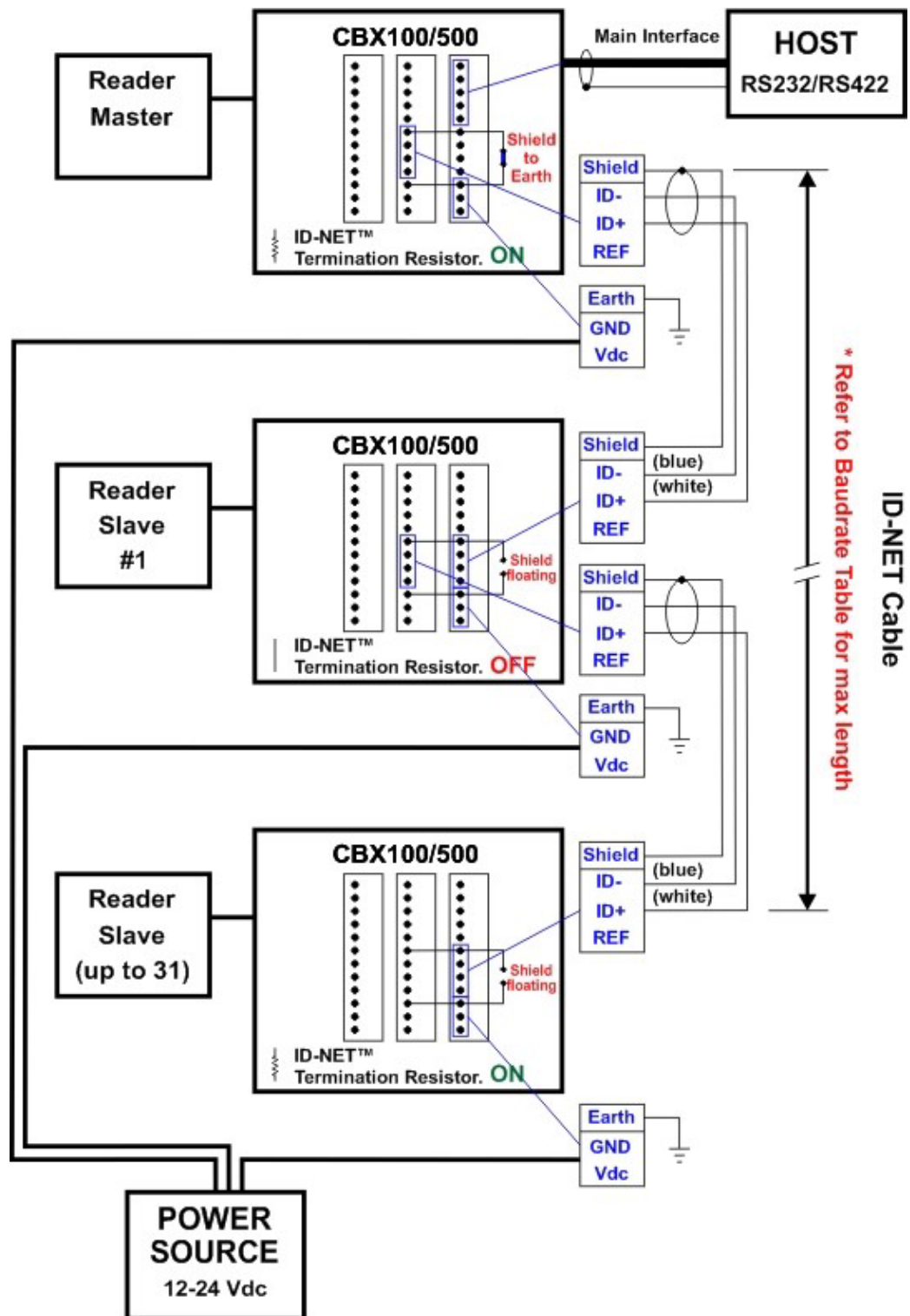


Figure 49 - ID-NET Network Connections with Common Power Star Network

AUXILIARY RS232 INTERFACE

The RS232 auxiliary interface is available for Point-to-Point connections. When it is connected to the host computer it allows transmission of code data.

The parameters relative to the aux interface (baud rate, data bits, etc.) can be defined through the Reading Phase step (Channels) in DL.CODE.

The 9-pin female Auxiliary Interface connector inside the CBX is the preferred connector for temporary communication monitoring.

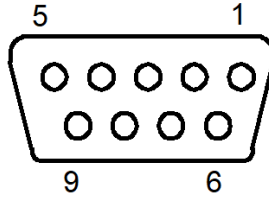


Figure 50 - 9-pin female connector

If permanent system wiring is required, the following pins are used to connect the RS232 auxiliary interface:

CBX100/500	Description
TX	Auxiliary Interface Transmit Data
RX	Auxiliary Interface Receive Data
SGND	Auxiliary Interface Reference

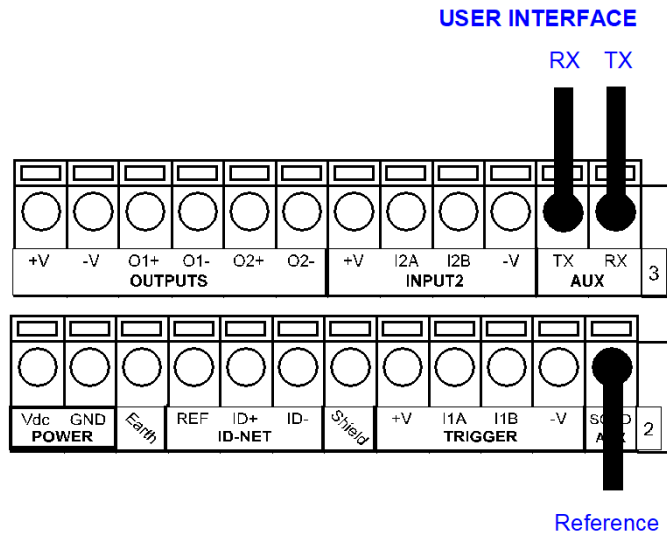


Figure 51 - RS232 Auxiliary Interface Connections



NOTE

Do not connect the Aux Interface to the CBX spring clamp connectors and the 9-pin connector simultaneously.

INPUTS

There are two optocoupled polarity insensitive inputs available on the reader: Input 1 (External Trigger) and Input 2, a generic input:

The External Trigger can be used in One Shot Mode or in Phase Mode. Its main functions are:

- acquisition trigger in One Shot Mode
- reading phase-ON/reading phase-OFF command in Phase Mode

The main functions of the general purpose Input 2 are:

- second external trigger in Phase Mode
- match code storage command when the Match Code option is enabled

The electrical features of both inputs are:

$$V_{AB} = 30 \text{ Vdc max.}$$

$$I_{IN} = 12 \text{ mA (reader) + 12 mA (CBX) max.}$$

The active state of these inputs are selected in software.

An anti-disturbance filter, by default, is implemented in software on both inputs. The value can be changed through the software parameter Debounce Filter. See the Help On Line page of the Reading Phase step (Inputs) in DL.CODE for further details on these parameters.

These inputs are optocoupled and can be driven by both NPN and PNP type commands.



NOTE

Polarity insensitive inputs assure full functionality even if pins A and B are exchanged.

The connections are indicated in the following diagrams:

CBX100/500	Description
+V	Power Source - External Trigger
I1A	External Trigger A (polarity insensitive)
I1B	External Trigger B (polarity insensitive)
-V	Power Reference - External Trigger

The yellow Trigger LED (Figure 20, 5) is on when the active state of the External Trigger corresponds to ON.

External Trigger Input Connections Using Matrix 210N Power



Power from the Vdc/GND spring clamps is available directly to the Input Device on the +V/-V spring clamps, and does not pass through the Power Switch (ON/OFF) inside the CBX. Disconnect the power supply when working inside the CBX.

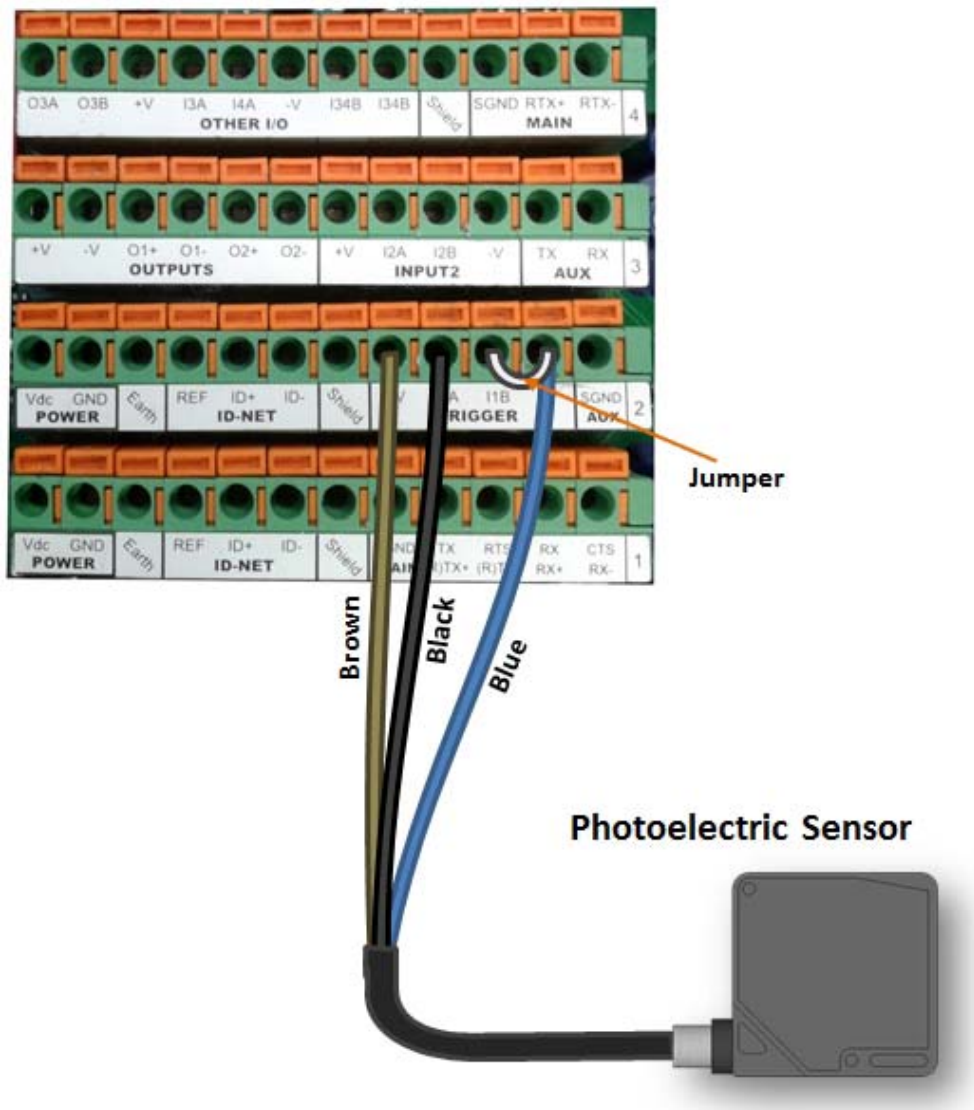


Figure 52 - PNP External Trigger Using Matrix 210N Power

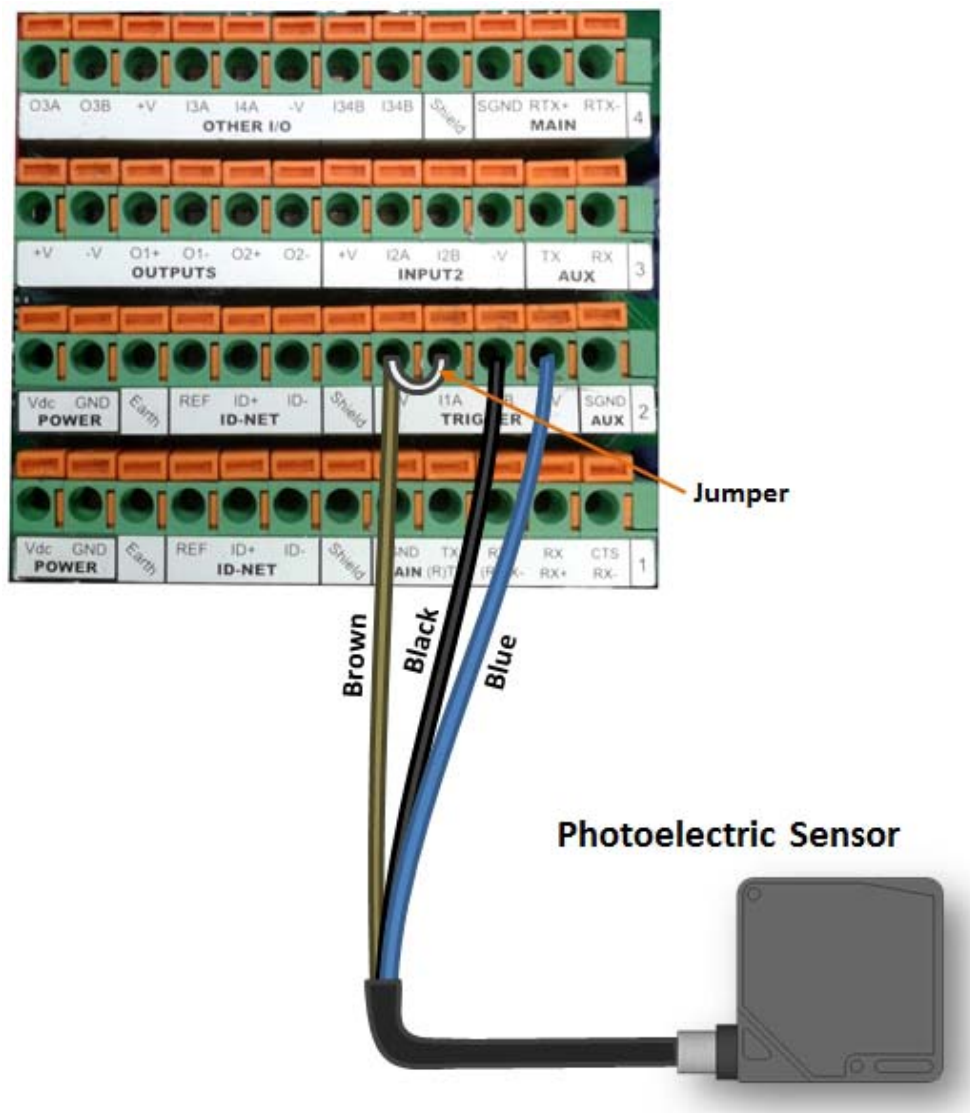


Figure 53 - NPN External Trigger Using Matrix 210N Power

External Trigger Input Connections Using External Power

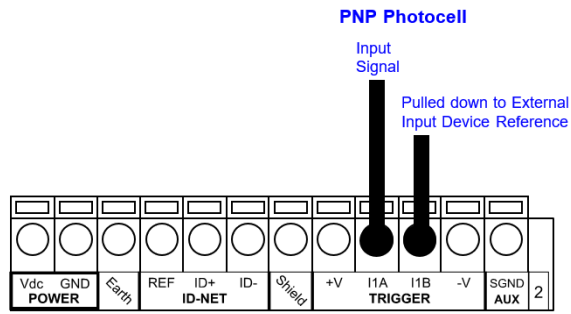


Figure 54 - PNP External Trigger Using External Power

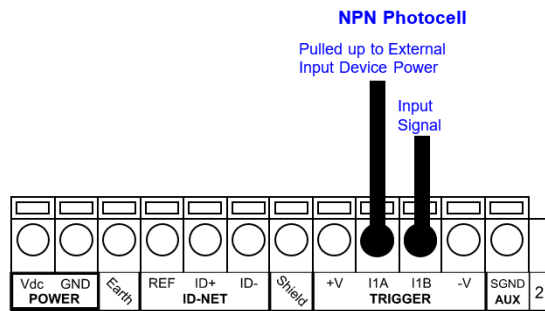


Figure 55 - NPN External Trigger Using External Power

CBX100/500	Description
+V	Power Source - External Trigger
I2A	Input 2 A (polarity insensitive)
I2B	Input 2 B (polarity insensitive)
-V	Power Reference - External Trigger

Input 2 Connections Using Matrix 210N Power



Power from the Vdc/GND spring clamps is available directly to the Input Device on the +V/-V spring clamps, and does not pass through the Power Switch (ON/OFF) inside the CBX. Disconnect the power supply when working inside the CBX.

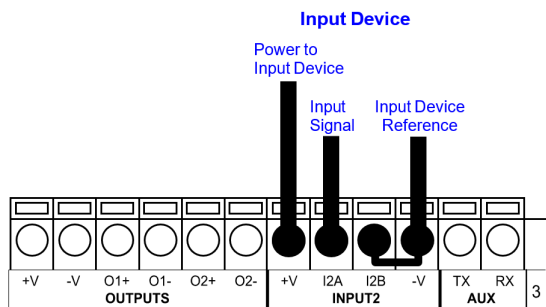


Figure 56 - PNP Input 2 Using Matrix 210N Power

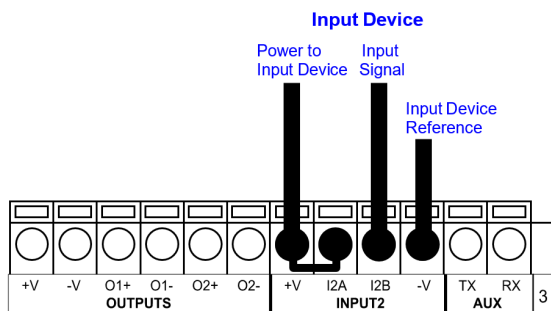


Figure 57 - NPN Input 2 Using Matrix 210N Power

Input 2 Connections Using External Power

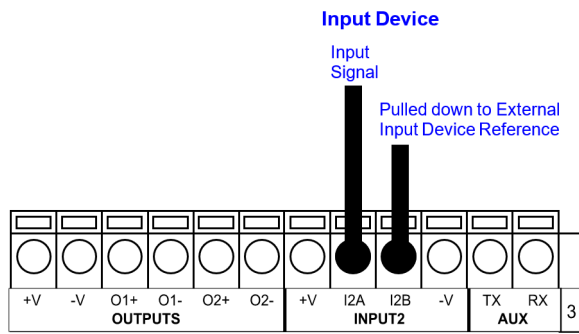


Figure 58 - PNP Input 2 Using External Power

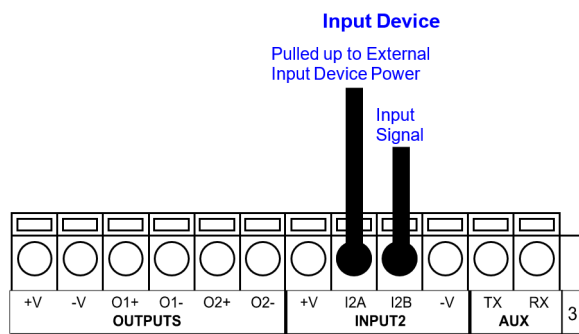


Figure 59 - NPN Input 2 Using External Power

OUTPUTS

Two optocoupled general purpose outputs are available and their meaning can be defined by the user. They are typically used either to signal the data collection result or to control an external lighting system.

CBX100/500	Description
+V	Power Source - Outputs
O1+	Output 1 +
O1-	Output 1 -
O2+	Output 2 +
O2-	Output 2 -
-V	Power Reference - Outputs

The electrical features of the outputs are the following:

$$V_{CE} = 30 \text{ Vdc max.}$$

$$I_{CE} = 40 \text{ mA continuous max.; 130 mA pulsed max.}$$

By default, Output 1 is associated with the No Read event, which activates when the code(s) signaled by the external trigger are not decoded, and Output 2 is associated with the Good Read event, which activates when all the selected codes are correctly decoded.

The output signals are fully programmable being determined by the configured Activation/Deactivation events, Deactivation Timeout or a combination of the two. Refer to the DL.CODE parameters Help On Line for further details.

Output Connections Using Matrix 210N Power



Power from the Vdc/GND spring clamps is available directly to the Output Device on the +V/-V spring clamps, and does not pass through the Power Switch (ON/OFF) inside the CBX. Disconnect the power supply when working inside the CBX.

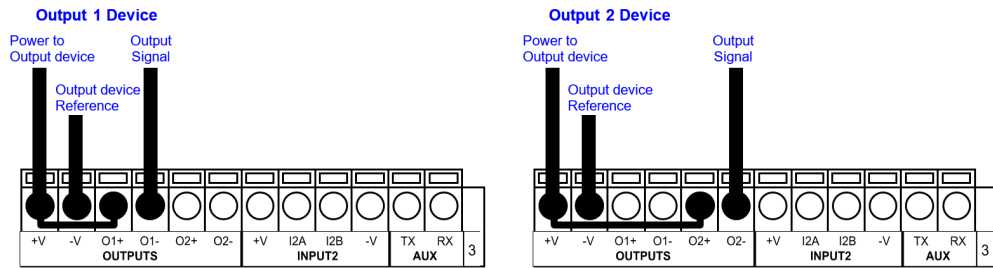


Figure 60 - Open Emitter Output Using Matrix 210N Power

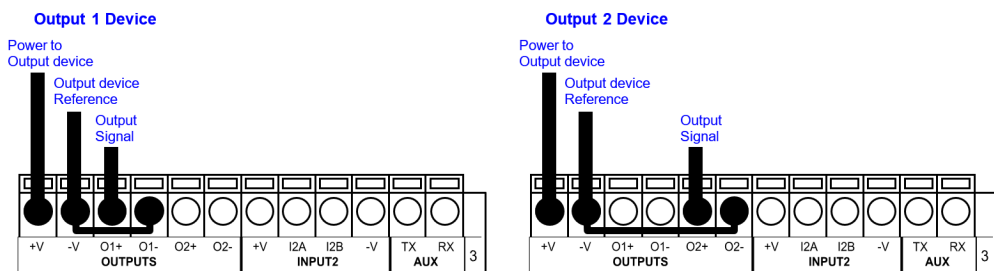


Figure 61 - Open Collector Output Using Matrix 210N Power

Output Connections Using External Power

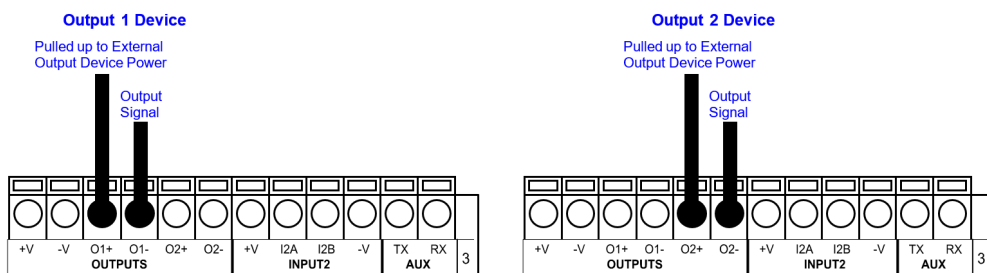


Figure 62 - Open Emitter Output Using External Power

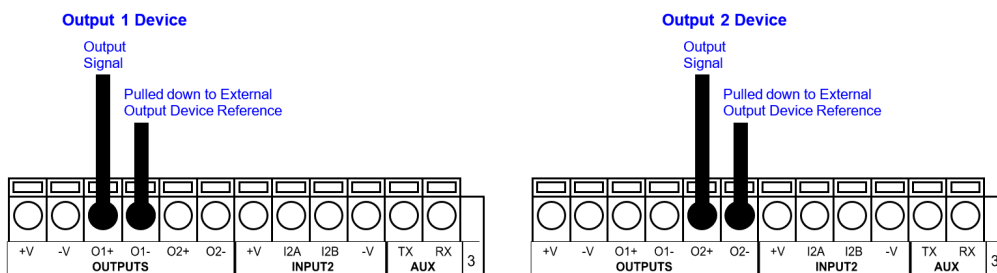


Figure 63 - Open Collector Output Using External Power

EXTERNAL LIGHTING SYSTEMS

If an External Illuminator is used, it can be powered from the CBX connection box. It must be connected to the **Vdc** and **GND** terminal clamps.



Power is available directly to the Illuminator, independently from the Power Supply Switch inside the CBX. Disconnect the power supply when working inside the CBX.

In the case of the LT-700 illuminators, one of the available digital outputs must be connected as the control signal. In DL.CODE, configure the Output Line Function parameter to one of the External Illuminator selections: Always On or Strobed.

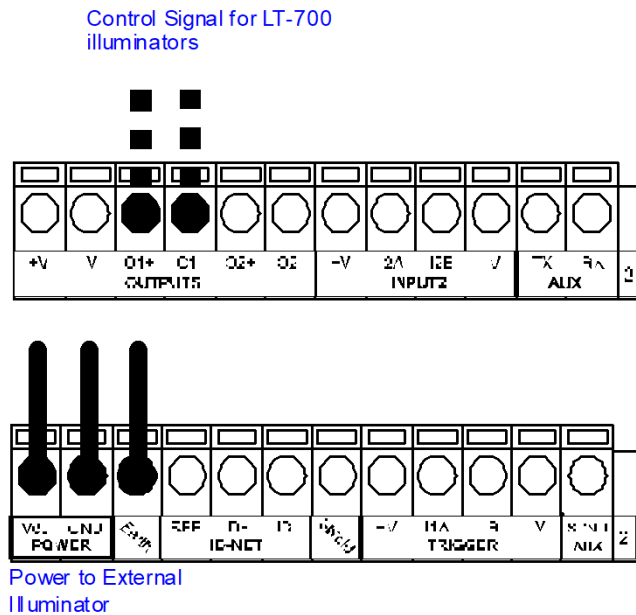


Figure 64 - External Lighting System Connections

Below is a table summarizing the various External Illuminator wiring and power requirements:

Illuminator	Wire Color	CBX/Matrix Signal	Meaning
LT-700	Red	Vdc	10 to 30 Vdc
	Black	GND	Ground
	White	Earth	Shield/Earth Ground
	Green	O1- or O2-	Control Signal -
	Yellow	O1+ or O2+	Control Signal +

ON-BOARD ETHERNET INTERFACE

The on-board Ethernet Interface can be used for TCP/IP communication with a remote or local host computer by connecting the reader to either a LAN or directly to a host PC. There is no need to use a crossover adapter since Matrix 210N incorporates an auto-cross function.

A **CAB-ETH-X-M0x** cable can be used to connect to a LAN.

On the Matrix 210N on-board Ethernet interface the following communication channels are available:

- TCP Client
- TCP Server
- UDP Channel
- FTP Client

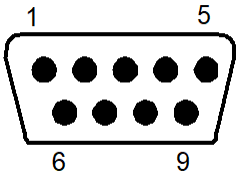
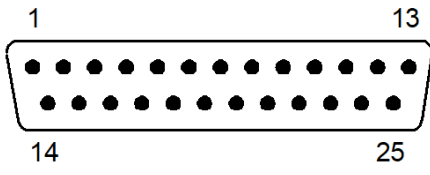
The following Fieldbus protocols are also available over the on-board Ethernet interface:

- EtherNet/IP
- PROFINET IO
- Modbus TCP Client

For further details refer to the Help On Line page of the Reading Phase step (Channels) and (Fieldbuses) in DL.CODE.

USER INTERFACE - SERIAL HOST

The following table contains the pinout for standard RS232 PC Host interface. For other user interface types please refer to their own manual.

RS232 PC-side Connections			
 <p>9-pin male connector</p>		 <p>25-pin male connector</p>	
Pin	Name	Pin	Name
2	RX	3	RX
3	TX	2	TX
5	GND	7	GND

CHAPTER 5

TYPICAL LAYOUTS

The following typical layouts refer to system hardware configurations. However, they also require the correct setup of the software configuration parameters. Dotted lines in the figures refer to optional hardware configurations within the particular layout.



NOTE

All software configurations are made through DL.CODE which connects to the reader through the on-board Ethernet interface.



NOTE

DL.CODE now supports several different multi device configuration types using the PASS-THROUGH configuration. In particular this feature allows MULTIDATA ID-NET network configurations to be made. Master/Slave SYNCHRONIZED ID-NET network configurations are also configurable as before.



NOTE

The Master/Slave Role is only significant for the Internal ID-NET Network. If your layout doesn't use the ID-NET network then the device's Role is not significant and can be ignored.

ETHERNET CONNECTION

The Ethernet connection is possible in two different layouts.

In a Point-to-Point layout the reader is connected to a local host by using a CAB-ETH-X-M0x cable. There is no need to use a crossover adapter since Matrix 210N incorporates an autocross function.

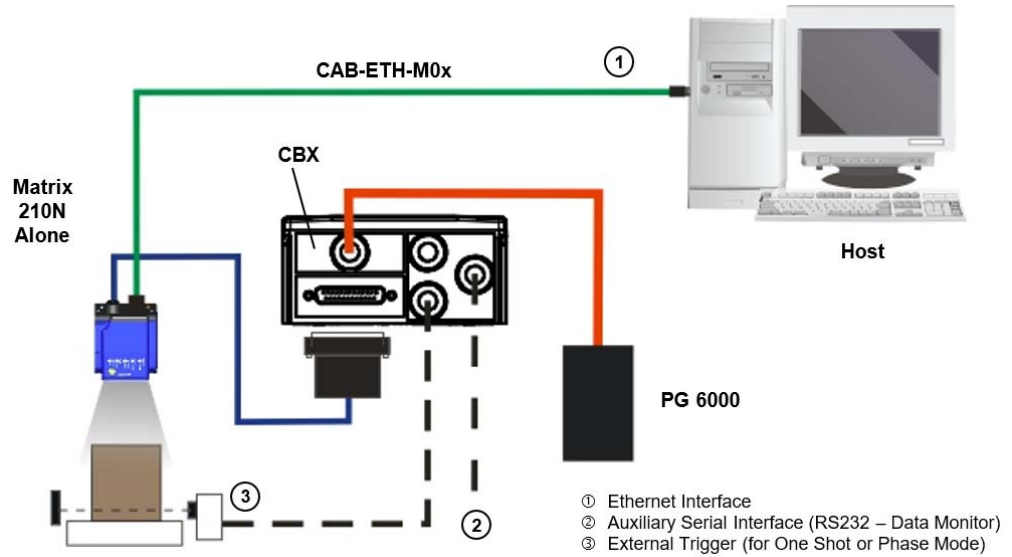


Figure 65 - Ethernet Point-to-Point Layout

All devices always support multiple output channels (i.e. for data monitoring).

When using a Local Area Network (LAN), one or more Matrix 210N readers can be connected to the network by using **CAB-ETH-X-M0x** cables:

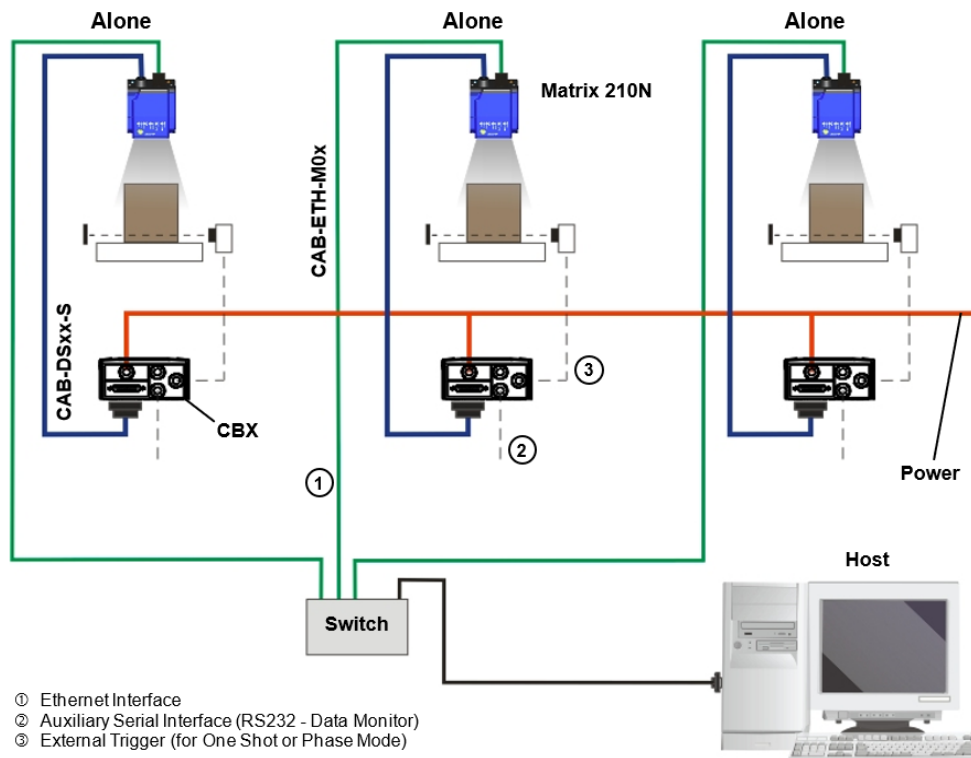


Figure 66 - Ethernet Network Layout

SERIAL CONNECTION

In this layout the data is transmitted to the Host on the main serial interface. The Ethernet interface can be used for reader configuration by connecting a laptop computer running DL.CODE.

Data can be transmitted on the RS232 auxiliary interface independently from the main interface selection to monitor data.

When One Shot or Phase Mode operating mode is used, the reader can be activated by an External Trigger (for example a pulse from a photoelectric sensor) when the object enters its reading zone.

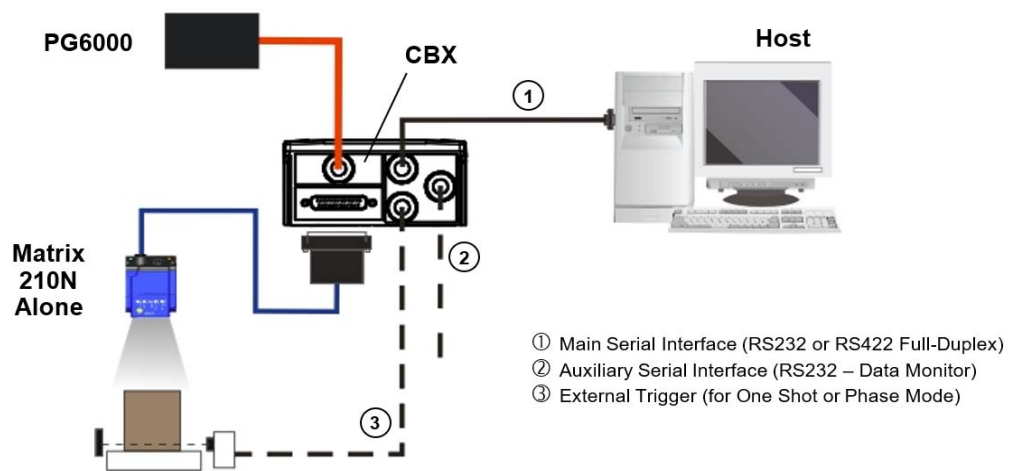


Figure 67 - Serial Interface Point-to-Point Layout

All devices always support multiple output channels (i.e. for data monitoring).

FIELDBUS CONNECTION

In this layout a single reader functions as a Slave node on a Fieldbus network. The data is transmitted to the Host through an accessory Fieldbus interface board installed inside the CBX500 connection box.

Reader configuration can be accomplished through the Ethernet interface using the DL.CODE configuration program.

Data can be transmitted on the RS232 auxiliary interface independently from the Fieldbus interface selection to monitor data.

When One Shot or Phase Mode operating mode is used, the reader can be activated by an External Trigger (photoelectric sensor) when the object enters its reading zone.

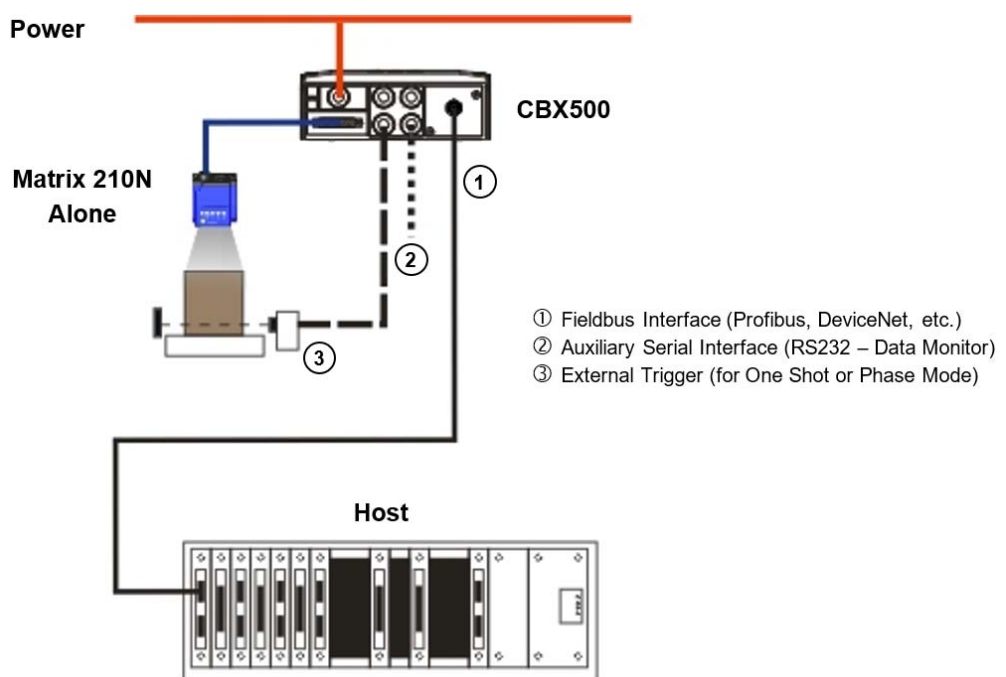


Figure 68 - Fieldbus Interface Point-to-Point Layout

All devices always support multiple output channels (i.e. for data monitoring).

PASS-THROUGH

The pass-through layout allows each device **working Alone**, to collect data from one or more pass-through input channels and send this data plus its own on one or more different output channels.

In this way independent devices can be connected together in combinations to create multi device networks. Many devices reading independently can send their messages through a common output channel which instead of being directed at a Host can be collected by another device on its pass-through input channel and sent to a Host on a different output channel.

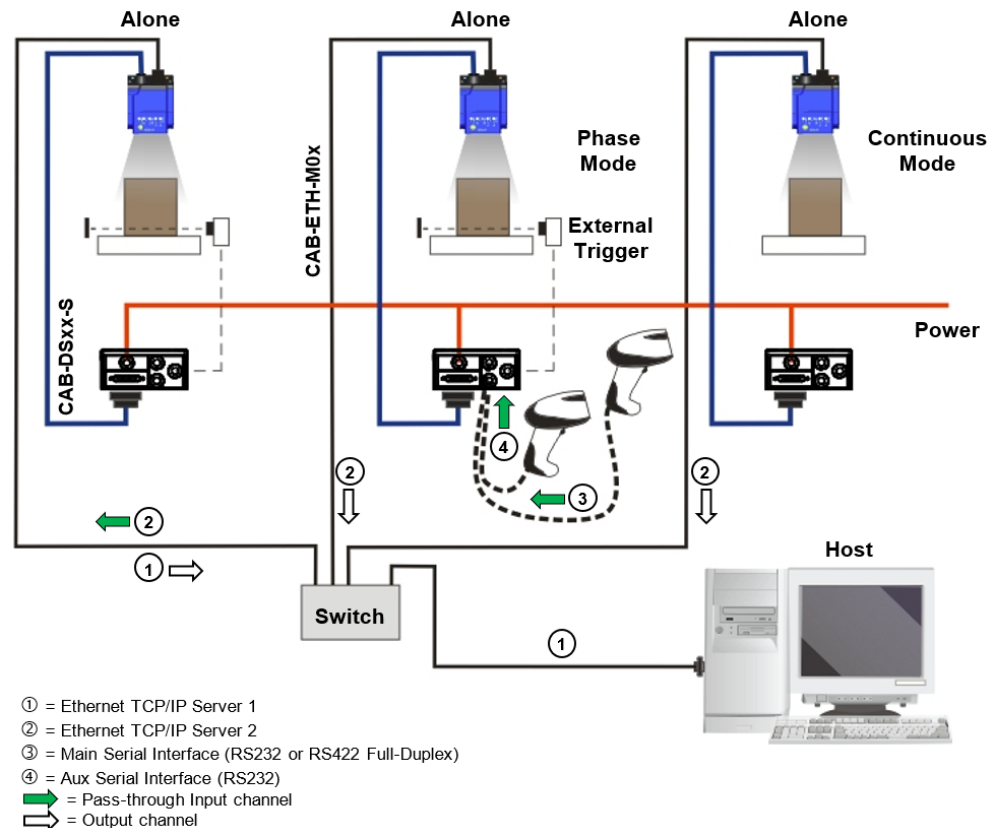


Figure 69 - Pass-Through Layout

In a Pass-through layout each device supports multiple pass-through configurations to accept input from different devices on different channels (i.e. middle reader above). However, readers are not required to have a pass-through configuration if they don't need to receive data from an input channel (i.e. right reader above). The overall data collection device always has at least one pass-through configuration to collect the input data from the other devices and send it to the Host (i.e. left reader above).

All devices always support multiple output channels (i.e. for data monitoring).

In a Pass-through layout each device can have a different operating mode: Continuous, One Shot, Phase Mode, etc.

ID-NET MULTIDATA NETWORK (PASS-THROUGH)

A special case of the pass-through layout allows each Slave device **working Alone**, to collect data from one or more pass-through input channels and send this data plus its own on the ID-NET output channel to the Master.

The Slave readers are connected together using the ID-NET interface. Every Slave reader must have an ID-NET address in the range 1-31.

The Master collects the data from its pass-through ID-NET input channel and sends it to the Host on a different output channel.

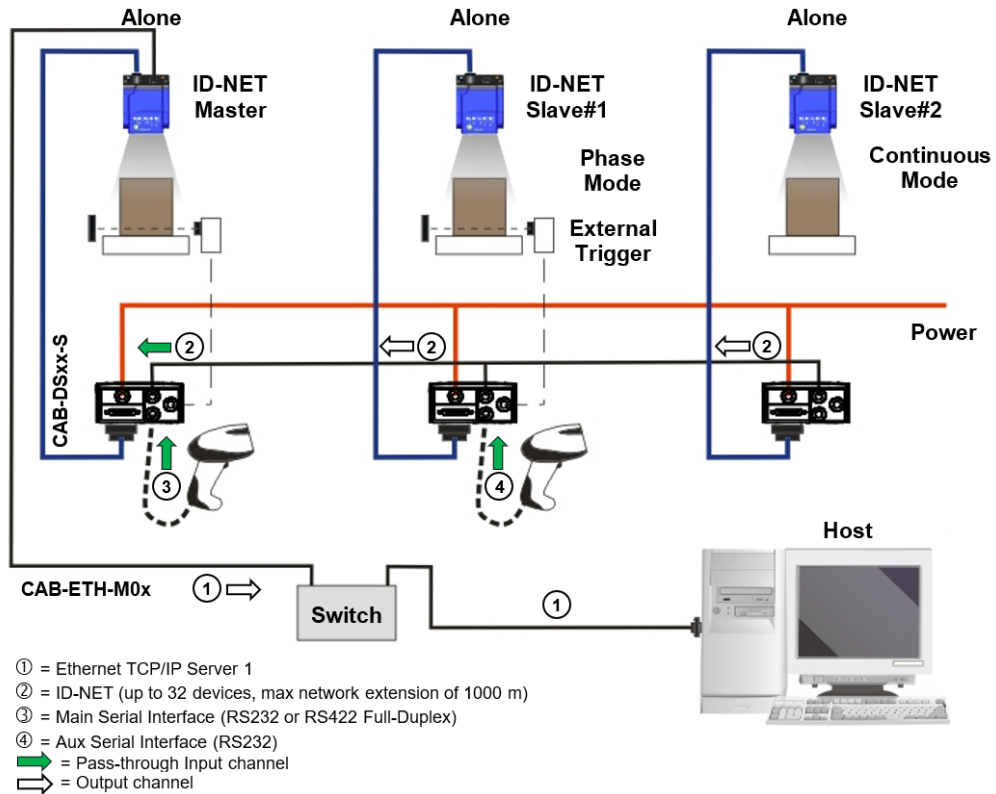


Figure 70 - ID-NET Multidata Layout (Pass-through)

In a Pass-through layout each device supports multiple pass-through configurations to accept input from different devices on different channels (i.e. Master reader above). However, ID-NET Slave readers are not required to have a pass-through configuration if they don't need to receive data from an input channel (i.e. right reader above). The ID-NET Master always has at least one pass-through configuration to collect the ID-NET Slaves data and send it to the Host.



Slave devices cannot receive data from a pass-through ID-NET input channel and Master devices cannot send data on an ID-NET output channel.

NOTE

All devices always support multiple output channels (i.e. for data monitoring).

In a Pass-through layout each device can have a different operating mode: Continuous, One Shot, Phase Mode, etc.

ID-NET SYNCHRONIZED NETWORK

When the device is **working Synchronized**, the ID-NET connection is used to collect data from several readers to build a multi-point or a multi-sided reading system; there can be one Master and up to 31 Slaves connected together.

The Slave readers are connected together using the ID-NET interface. Every slave reader must have an ID-NET address in the range 1-31.

The Master reader is also connected to the Host on one of its communication channels. In the following examples the RS232/RS422 main serial interface is used.

For a Master/Slave Synchronized layout the External Trigger signal is unique to the system; there is a single reading phase and a single message from the Master reader to the Host computer. **It is not necessary to bring the External Trigger signal to all the readers.**

In the Master/Slave Synchronized layout the Master operating mode can only be set to Phase Mode.

The Main and ID-NET interfaces are connected as shown in the following figures.

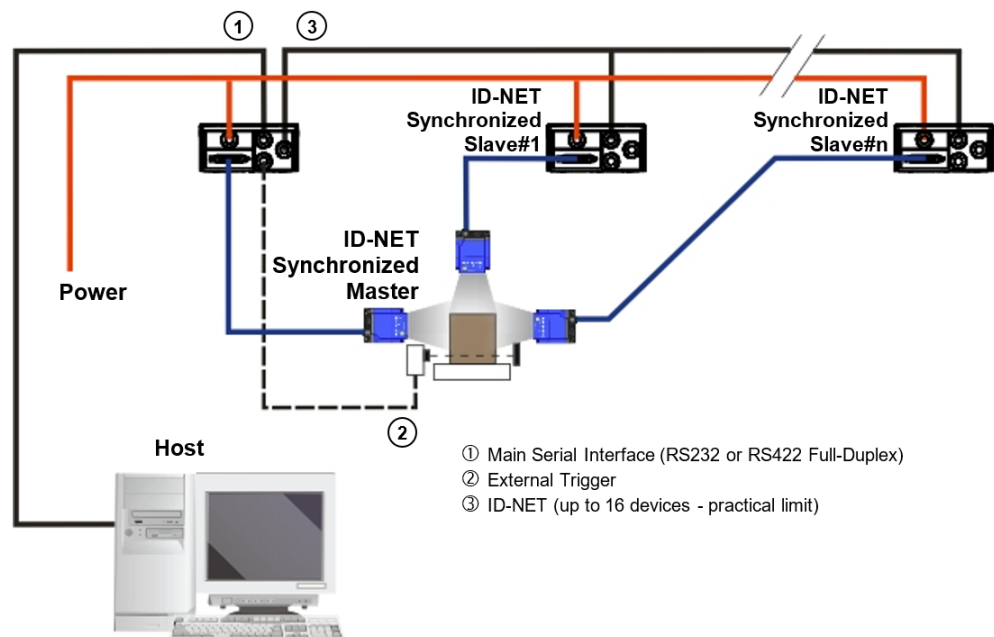


Figure 71 - ID-NET Synchronized Layout

The Master reader can be connected to the CBX series connection box with the advantage of the Backup and Restore configuration function (CBX + BM100 module).

All devices always support multiple output channels (i.e. for data monitoring).

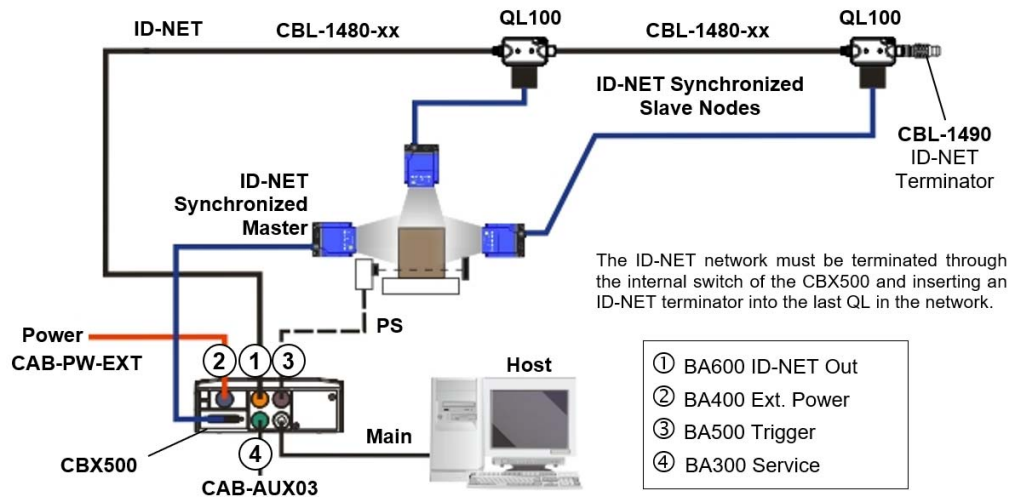


Figure 72 - ID-NET Synchronized Layout. Matrix 210N Master with CBX500 + Matrix 210N Slaves with QL100

If the Backup and Restore function is not required, then a QL300 can be used to connect the master reader.

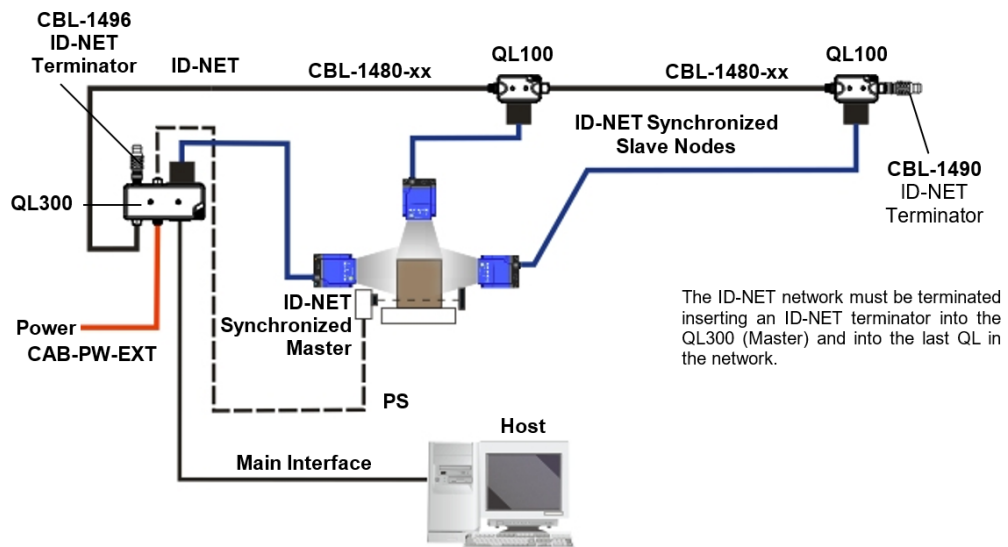


Figure 73 - ID-NET Synchronized Layout. Matrix 210N Master with QL300+ Matrix 210N Slaves with QL100

The same configuration can be made to a Host using the on-board Ethernet interface to the Master. The TCP/IP Ethernet and ID-NET interfaces are connected as shown in the figure below.

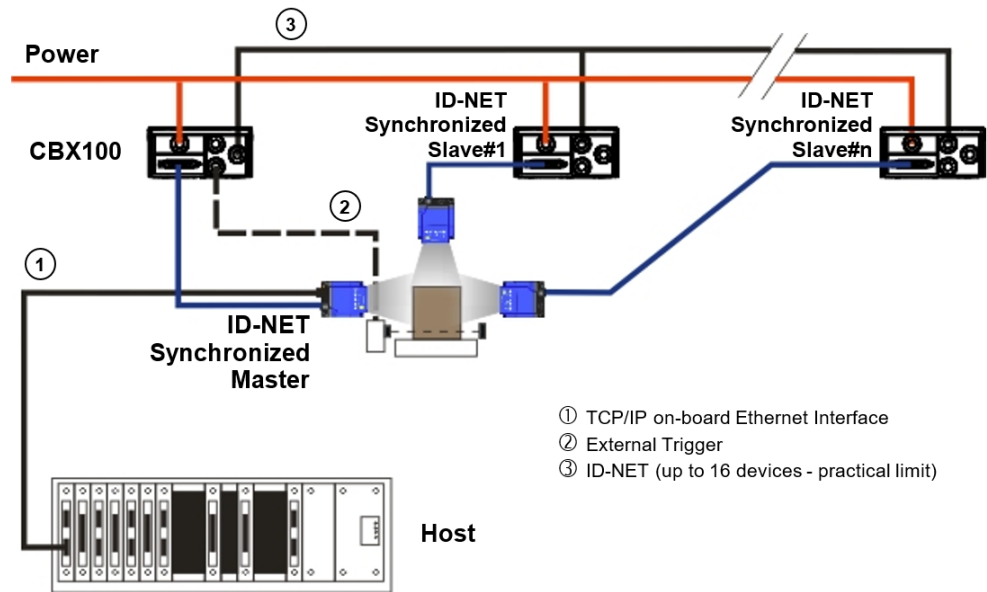


Figure 74 - ID-NET Synchronized Layout with Master on-board TCP/IP Ethernet Interface to Host

Alternatively, the Master reader can communicate to the Host as a Slave node on a Fieldbus network. This requires using an accessory Fieldbus interface board installed inside the CBX500 connection box. System configuration can be accomplished through the Ethernet interface of each individual reader using the DL.CODE configuration program.

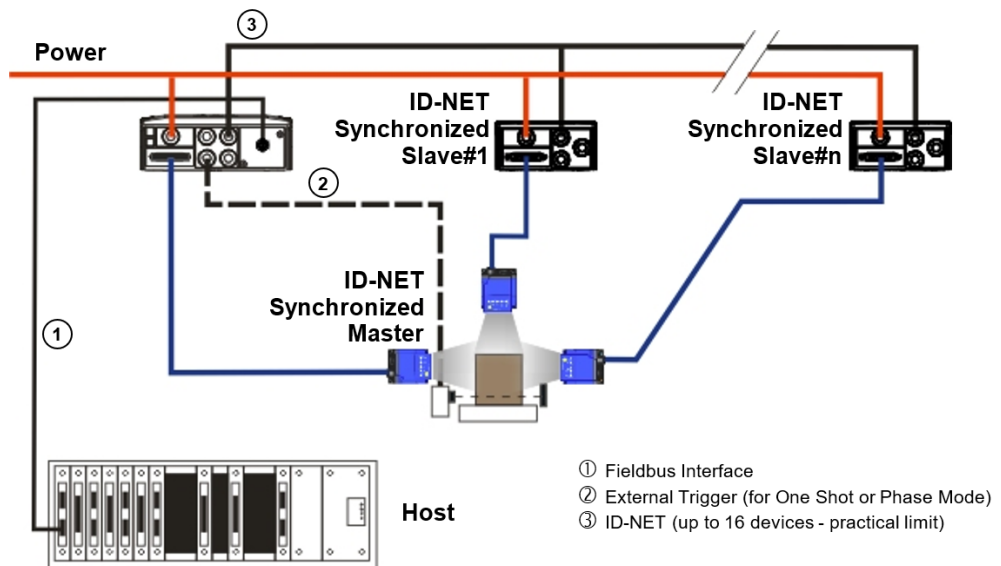


Figure 75 - ID-NET Synchronized Layout with Master CBX500 Fieldbus Interface to Host

USB CONNECTION

Matrix 210N USB models can be connected in a Point-to-Point layout to a local host through their USB cable. No external power supply is necessary.

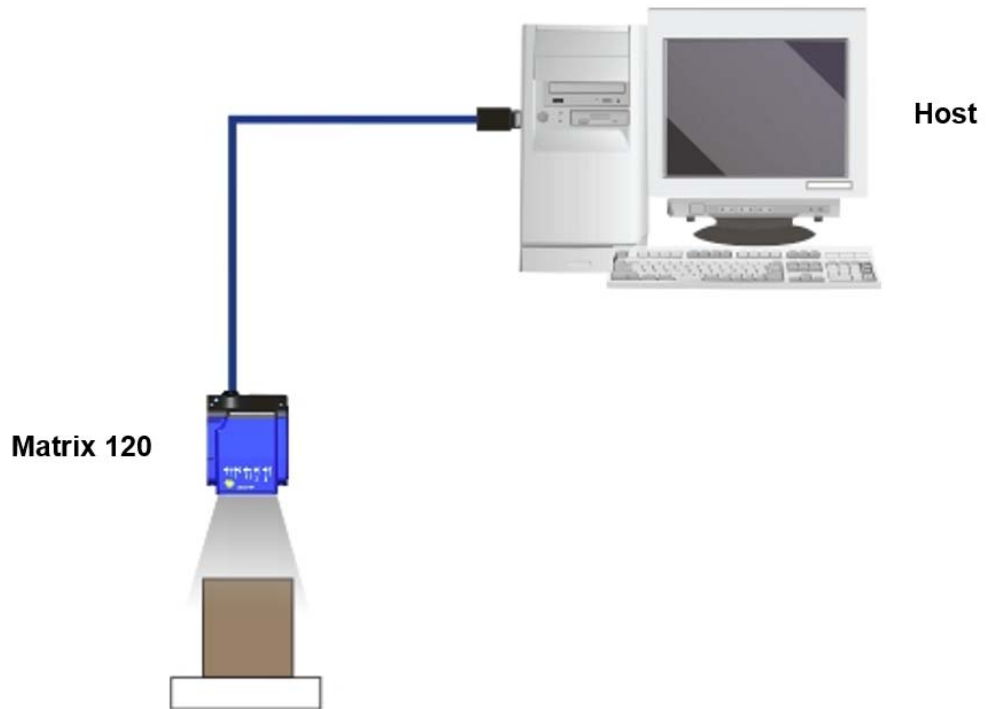


Figure 76 - Matrix 210N USB Point-to-Point Layout

One or more Matrix 210N USB models can be connected to a USB Hub. The HUB must be able to supply 500 mA to each port.

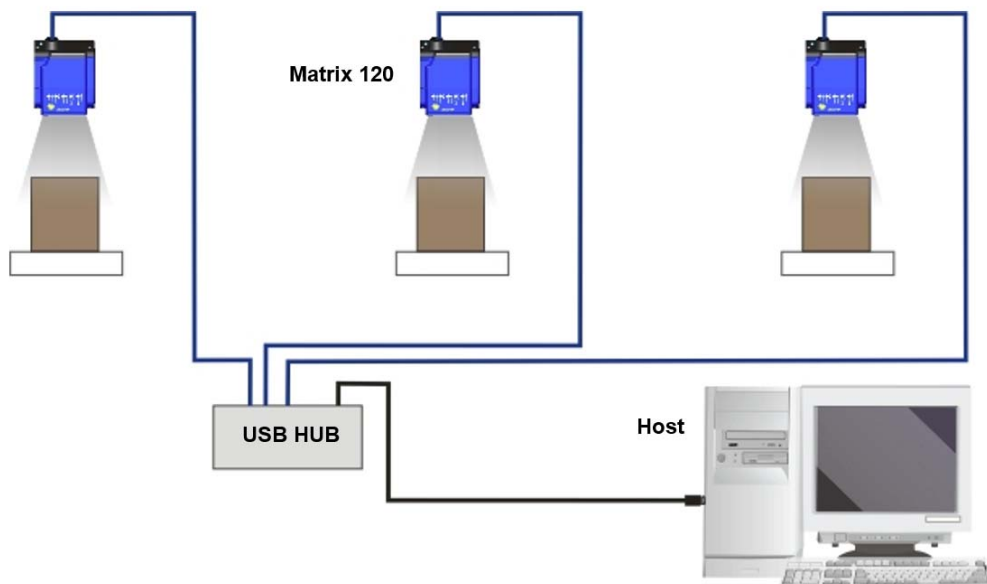


Figure 77 - Matrix 210N USB Layout to HUB

CHAPTER 6

READING FEATURES

MATRIX FIXED FOCUS MODELS

Models	Focus Distance mm (in)	Field of View ^a mm (in)	PPI ^b	Typ. Linear and Stacked Code Resolution mm (in)	2D Code Resolution mm (in)	Reading Distance ^c mm (in)	
						min.	max.
211-xxx NEAR	45 (1.77)	35 x 22 (1.38x0.87)	545	0.10 (4)	Max. 0.13 (5)	42 (1.65)	53 (2.08)
					Typ. 0.19 (7.5)	36 (1.42)	61 (2.40)
212-XXX MEDIUM	65 (2.56)	50 x 32 (1.97x1.26)	380	0.15 (6)	Max. 0.19 (7.5)	54 (2.13)	90 (3.54)
					Typ. 0.25 (10)	47 (1.85)	101 (3.97)
213-XXX FAR	105 (4.13)	80 x 50 (3.15x1.97)	238	0.20 (8)	Max. 0.25 (10)	85 (3.35)	135 (5.31)
					Typ. 0.38 (15)	70 (2.76)	192 (7.55)

a. @ Focus Distance

b. Pixels per inch @ Focus Distance

c. Measurement Conditions:

- Test Chart: provided with the reader
- Still code at the center of the FOV
- Code Symbology: Data Matrix ECC 200
- Tilt Angle: 45°
- Skew Angle: 15°
- Code Contrast = Low *
- Decoding Complexity = Very High *

*These parameter settings can increase the image processing time.

All distances are measured from the reading window to the code surface.

Depending on the code resolution, symbology and number of characters in the code, the Reading Area can be different from the FOV.

FOV CALCULATION

Use the data in the following table to calculate the FOV for your application, referring to Figure 78 and the formula below.

Model	Lens Focus Type	d_0	Viewing Angle Horizontal	Viewing Angle Vertical	Viewing Angle Diagonal	Min Reading Distance (mm)
Matrix 210N 2x5-xxx	7 mm software	14 mm	35°	23°	41°	40

The viewing angle has a tolerance of $\pm 1^\circ$ depending on the reading distance.

$$FOV_x = 2 [(d + d_0) * \tan (\alpha_x/2)]$$

where:

FOV_x = horizontal, vertical or diagonal FOV

α_x = horizontal, vertical or diagonal viewing angles.

d = reading distance (in mm) from window surface to code surface

d_0 = offset (in mm) from center of lens to external window surface

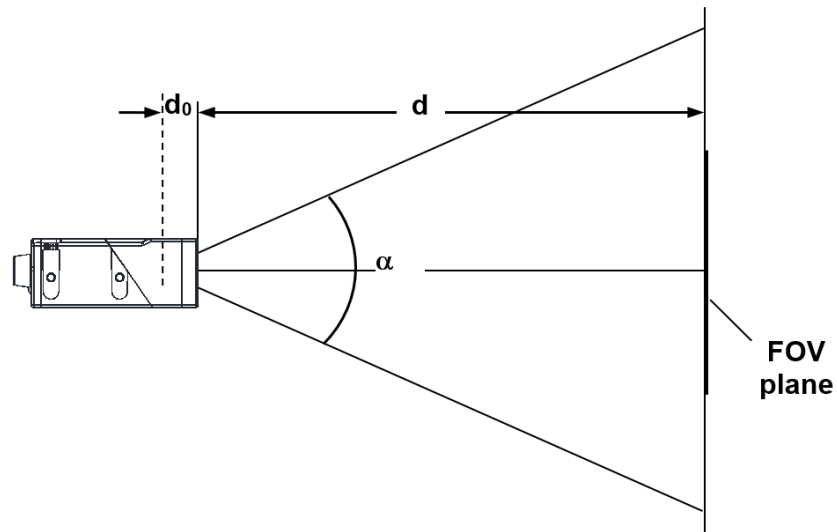


Figure 78 - Reading Distance References

Example:

The FOV for a **Matrix 210N 225-111** at a **reading distance of 120 mm** is:

$$FOV_H = 2 [(120 \text{ mm} + 14 \text{ mm}) * \tan (35^\circ/2)] \cong 85 \text{ mm}$$

$$FOV_V = 2 [(120 \text{ mm} + 14 \text{ mm}) * \tan (23^\circ/2)] \cong 55 \text{ mm}$$

GLOBAL FOV DIAGRAMS



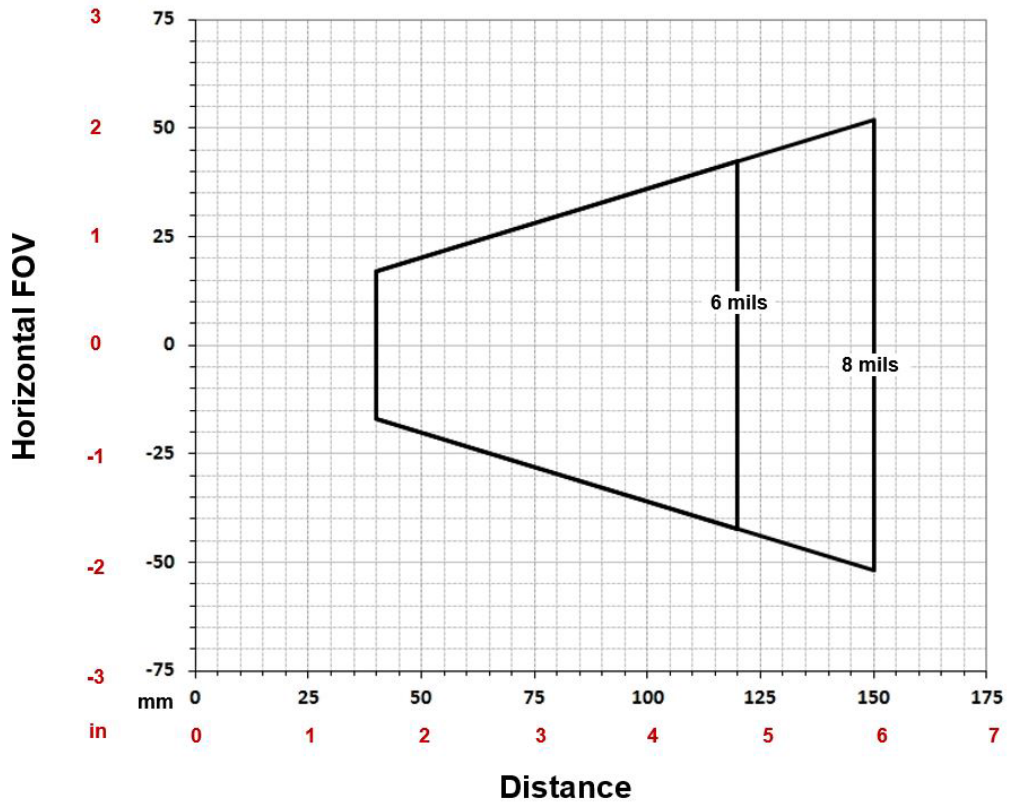
NOTE

The following diagrams are given for typical performance at 25°C using high quality grade A symbols according to ISO/IEC 15416 (1D code) and ISO/IEC 15415 (2D code) print quality test specifications. Testing should be performed with actual application codes in order to maximize the application performance.

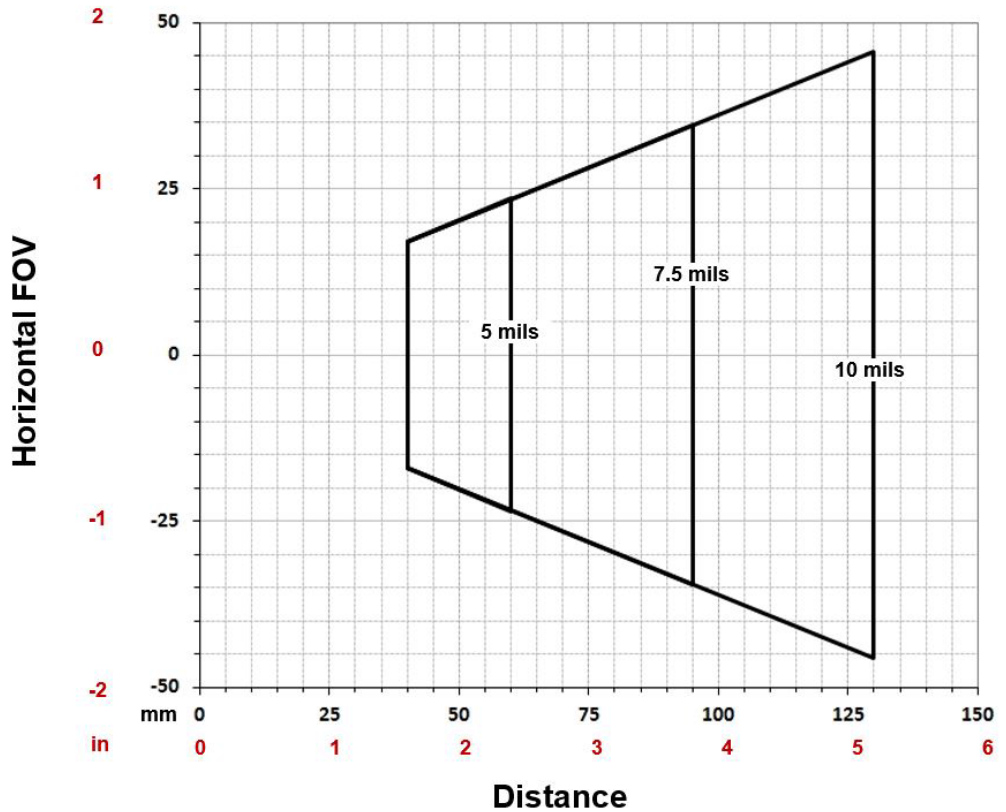
The following diagrams show the **maximum obtainable** Field of View for 1D and 2D codes using Processing Mode = Advanced. Depending on the code resolution, symbology, and number of characters in the code, the Reading Area can be different from the FOV.

Software Adjustable Focus Models

1D Codes



2D Codes



MAXIMUM LINE SPEED CALCULATIONS

The **Exposure Time** (or **Shutter**) parameter defines the time during which the image will be exposed to the reader sensor to be acquired. This parameter depends heavily on the environmental conditions (external lighting system, image contrast etc.).

In general, a longer time corresponds to a lighter image but is susceptible to blurring due to the code movement; a shorter exposure time corresponds to a darker image.



NOTE

The following considerations must be applied only when the internal lighting system and 2D codes are used. The Maximum line speed allowed for linear codes or postal code reading applications heavily depends on the direction of symbol movement. When the direction of movement is parallel to the elements of the code, the maximum speed is greater.

Assuming:

- **X**: Code Resolution (mm)
- **T_{exp}**: Exposure Time (s)
- **LS**: Line Speed (mm/s)

The essential condition to avoid blurring effects between two adjacent elements in a dynamic reading application is:

$$LS * T_{exp} \leq X$$

The maximum (theoretical) line speed **LS** can be calculated as follows:

$$X / T_{exp (min)} = LS (max)$$

T_{exp (min)} is the minimum **Exposure Time** value obtainable for the specific application. It can be evaluated in static reading conditions and may depend on code printing quality, reader position, etc.

Using the formulas previously explained it is possible to calculate the theoretical maximum line (target) speed expected for the application, based on the maximum code resolution and the minimum suitable **Exposure Time** value.

The minimum **Exposure Time** value depends on the reading distance and on external lighting.

The maximum target speed in the application is also affected by these conditions:

- **Code/Background Contrast**: maximum speed decreases when decreasing image contrast (poor quality codes, reflective transparent coverings, different supports and printing techniques).
- **Code Resolution**: maximum speed increases when decreasing code resolution, (i.e. **2X**). There is a decrement of overlapping effects between two adjacent elements.
- **Tilt Angle**: maximum speed decreases when increasing Tilt angle (from 0 to 45 degrees).

The **Internal Lighting** parameter allows setting the operating mode of the internal lighting system. The possible values are:

- *Disabled*: the built-in lighting system is turned off all the time. This option can be useful only if external lighting is sufficient;
- *Always ON*: the built-in lighting system is turned on all the time at the lowest power level. This option is useful if the lighting system blinking (Strobed operating mode) disturbs the operator.
- *-Power Strobed*: the built-in lighting system is on only during the image exposure time. Different Power Strobed lighting levels can be set.



NOTE

To avoid LED array overheating, for Power Strobed settings, the program automatically limits the range of allowed values for the Exposure Time parameter. Therefore, after changes to Internal Lighting, recheck Exposure Time.

CHAPTER 7

SOFTWARE CONFIGURATION

Software configuration of your Matrix 210N for static reading or simple code reading applications can be accomplished by the Rapid Configuration procedure using the X-PRESS HMI (which requires no external configuration program). This procedure is described in [Chapter 1, Rapid Configuration Steps 3-4](#).

For the majority of applications however you will use DL.CODE, connecting to the reader through the on-board Ethernet interface. See [Chapter 1, Rapid Configuration Steps 5-6](#).

DL.CODE SYSTEM REQUIREMENTS



DL.CODE does not currently support Windows Embedded (often used in industrial PCs and/or PLCs).

To install and run DL.CODE you should have a Laptop or PC that meets or exceeds the following:

- 2.00 GHz or faster microprocessor
- Windows: 7, 8.1, or 10
- 1 GB RAM
- 2 GB hard disk for 64-bit machines; 1 GB hard disk for 32-bit machines
- 100 Base-T Ethernet
- One 19" or larger monitor (optimized for 1280x1024 resolution)

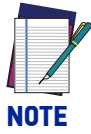
READER CONFIGURATION

For an example of Matrix device configuration see the example in [Chapter 1, Rapid Configuration Steps 5-6](#).



Especially for lengthy configurations, it is always good practice to periodically save the configuration to permanent memory (Save on Device) to avoid losing the configuration in Temporary Memory. You must give a name to the new configuration or overwrite an existing one (except for Default which cannot be modified).

When all the configuration parameters are set correctly and saved to the device, you can perform a Backup to File and/or to an External storage device (BM100, etc.). See "Backup and Restore Through DL.CODE" on page 135.

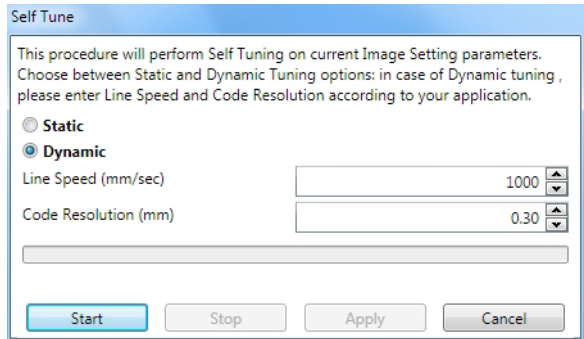


An improvement in the Matrix N Family readers allows them to contain several configurations or jobs in permanent memory.

This means that in addition to your application configuration(s), the Default configuration is always present on the reader and in fact it is not modifiable and cannot be deleted.

Auto-Calibration

DL.CODE provides the **Image Auto-Setup** tool to maximize the reading performance by tuning the acquisition parameters (photometry) automatically. By selecting the **Image Auto-Setup** tool from the Image Settings branch in the Advanced Setup step, the following window appears:



Select the Static or Dynamic Self-Tuning option; Start Image Auto-Setup and Apply to the Image Settings. The Advanced Setup window works interactively so that you can see the results of the parameter setting changes as well as the decoding results (Results panel).

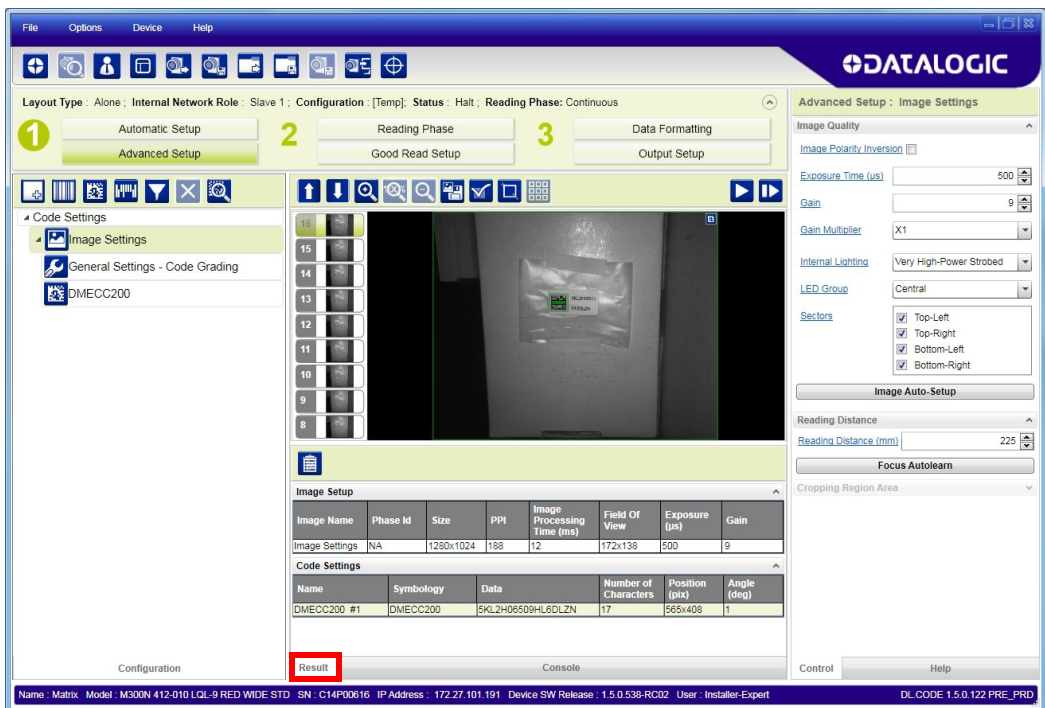


Figure 79 - Decoding Results OK

Manual Calibration

The following examples show some of the typical conditions occurring during the installation and how they can be tuned manually.

Under-exposure

To correct this result it is recommended to change the following parameters in their order of appearance:

1. increase the **Exposure Time**
2. increase the **Gain**



NOTE

In general, a longer exposure time corresponds to a lighter image but is susceptible to blurring due to code movement. Exposure time is also limited by the Internal Lighting mode parameter. Longer exposure times can be set if the power strobe level is lowered.

High gain settings may produce a grainy image that may affect the decoding process.

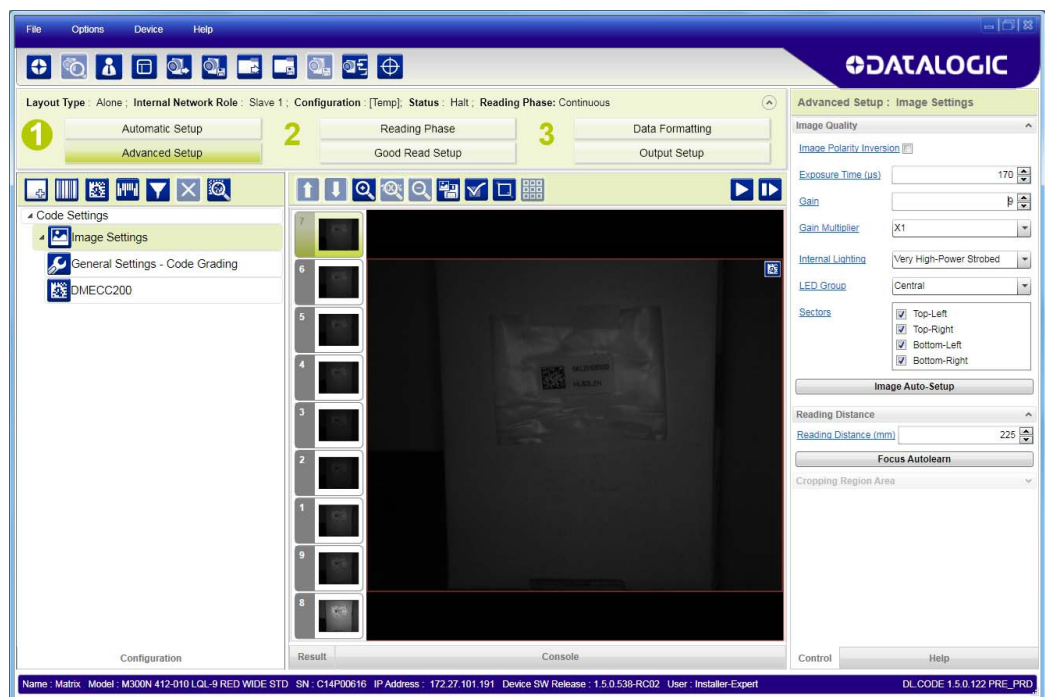


Figure 80 - Example Under Exposure: Too Dark

Over-exposure

To correct this result it is recommended to change the following parameters in their order of appearance:

1. decrease the **Gain**
2. decrease the **Exposure Time**

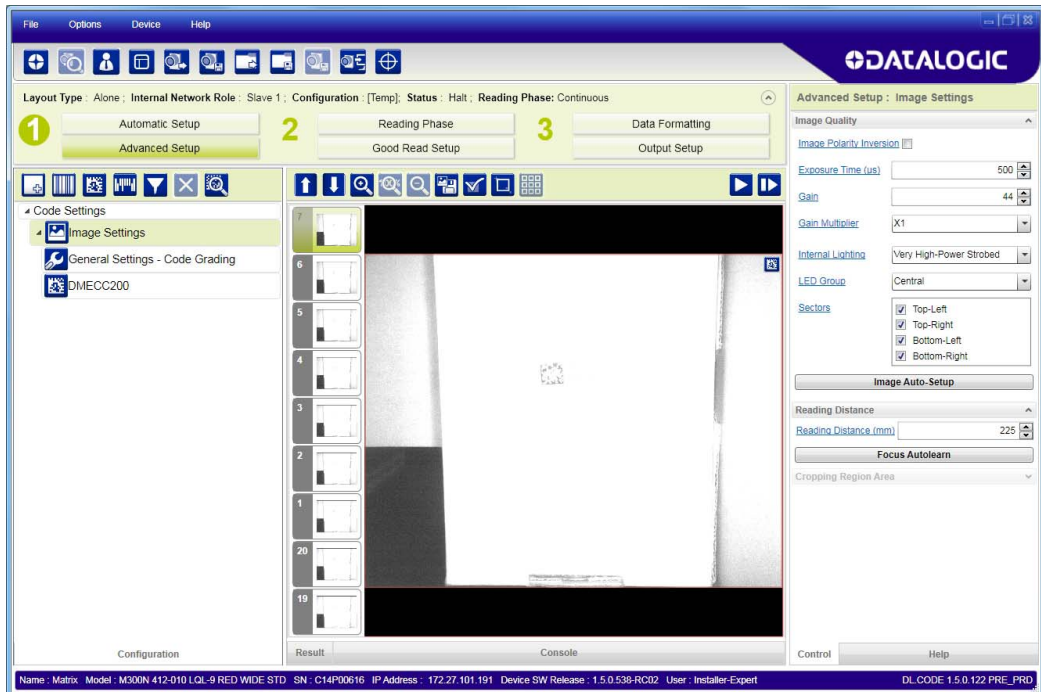


Figure 81 - Example Over Exposure: Too Light

Moving code out of the Field of View

To correct this result and have the code completely visible in FOV, it is possible to follow one or both the procedures listed below:

- reposition the reader
- use the **Delay on Trigger** and set the **Time** or **Space** values.

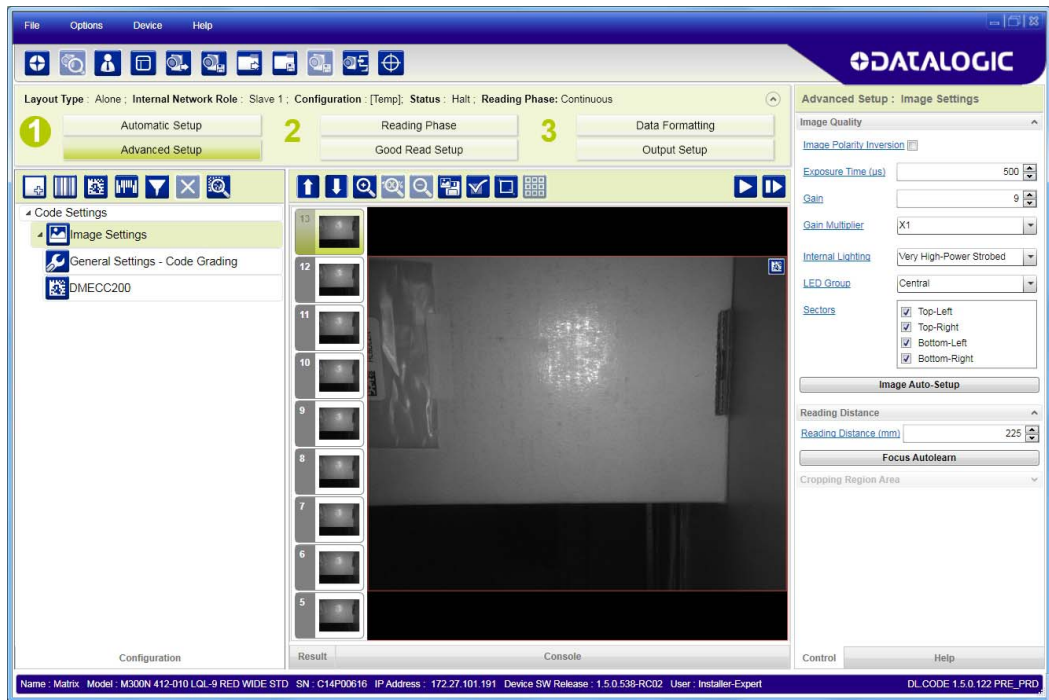


Figure 82 - Example Out of FOV

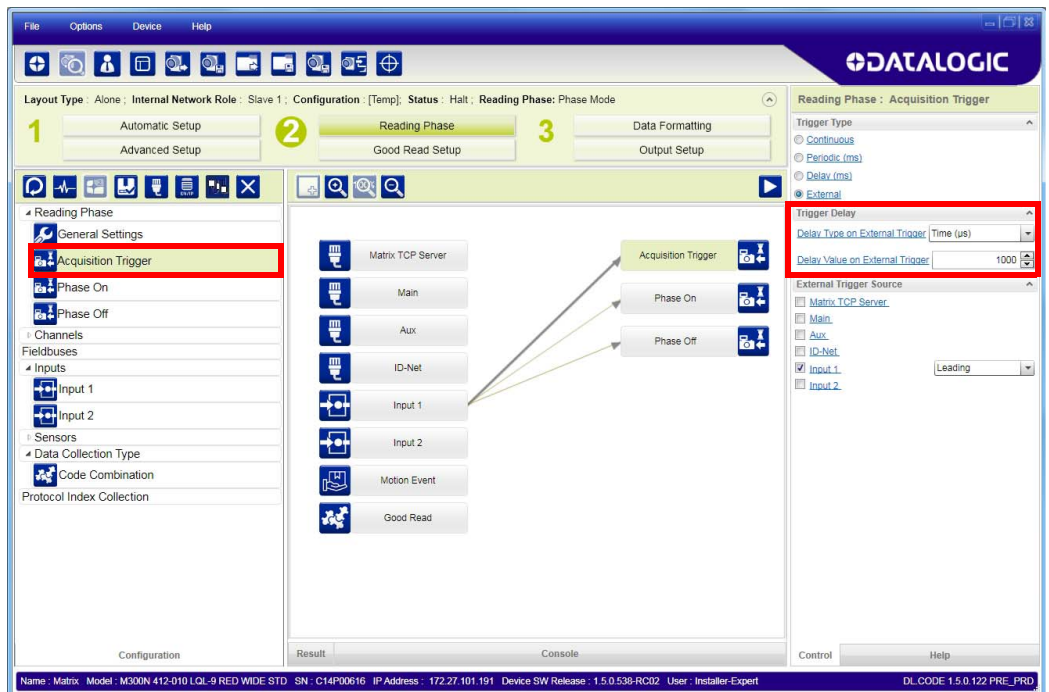


Figure 83 - Add Delay on Trigger to Correct Out of FOV

MULTI IMAGE ACQUISITION SETTINGS

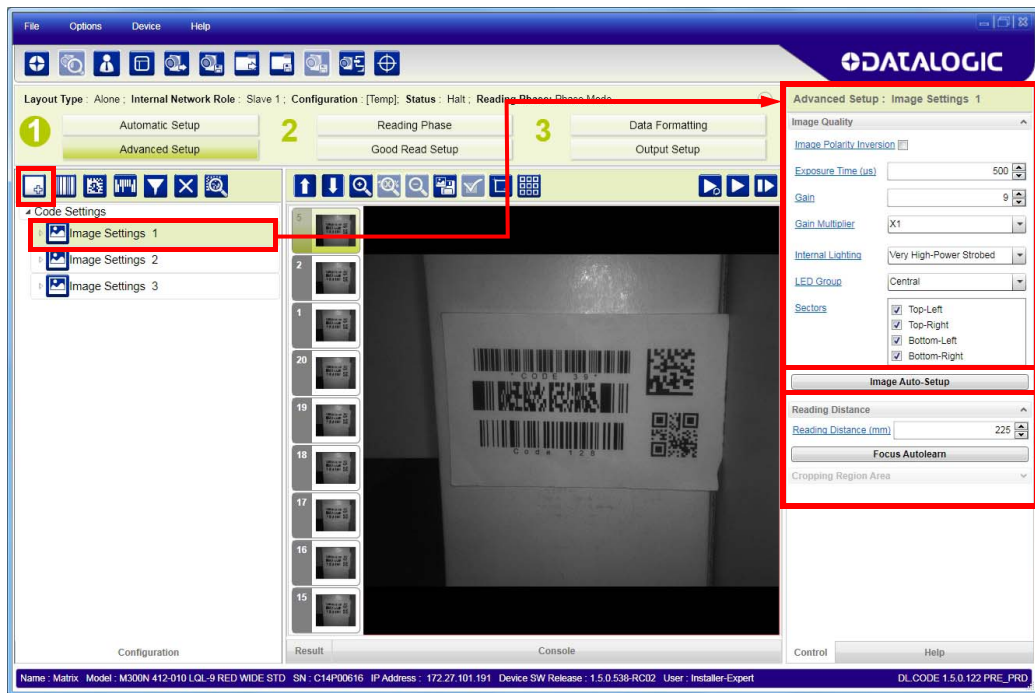
When controlled variable conditions occur in the application, Multiple **Image Acquisition Settings** can be defined to create a database of parameter groups that handle each specific application condition. This database of pre-defined settings improves system flexibility and readiness by being applied either automatically or selectively by an activation event.

For example, an application may have several stable but different lighting conditions which require different lighting options. One Image Acquisition Setting could enable and use an internal illuminator and another setting could enable and use an external lighting system.

This feature is available for all Operating Modes.



Image Settings are found in the DL.CODE **Advanced Setup** step. Up to 10 different Image Settings can be configured by adding them with the icon.

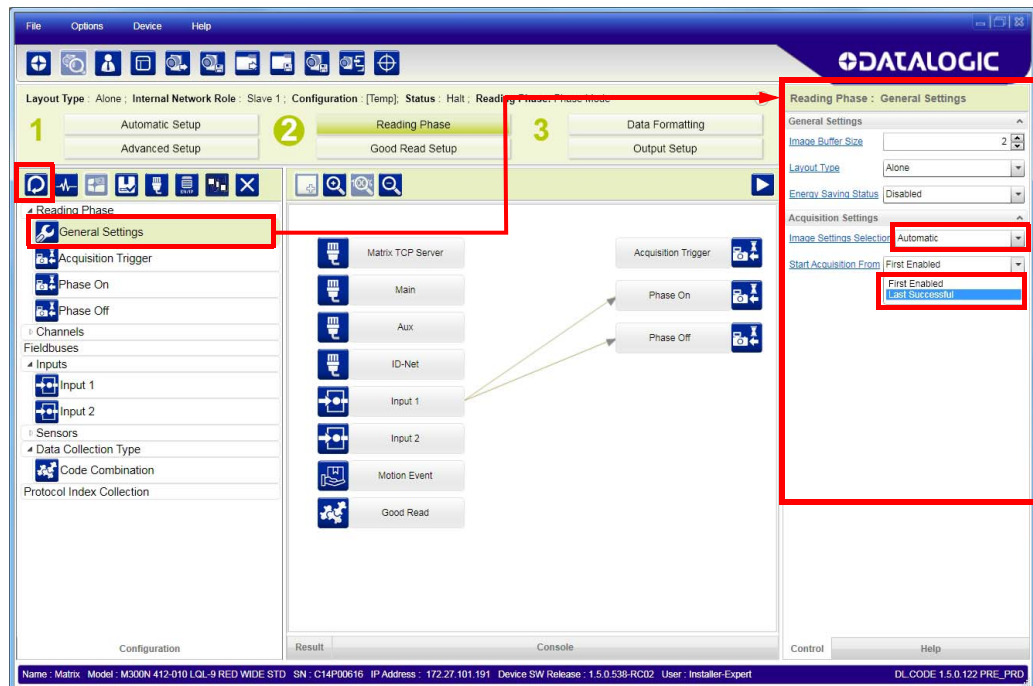


For each Image Setting condition start **Image Auto-Setup**, select the Static or Dynamic Self-Tuning option; and Apply it.

Automatic Image Settings Selection

If we don't know from one item to the next which reading condition will be presented, we will cycle through the pre-defined database of Image Settings (one per acquisition) in order to automatically capture the correctly lighted image over the course of several acquisitions. When the correct condition is matched, the result should be able to produce a Good Read.

When the Image **Settings Selection** is **Automatic** (default), then these Image Settings groups will be used cyclically.



NOTE

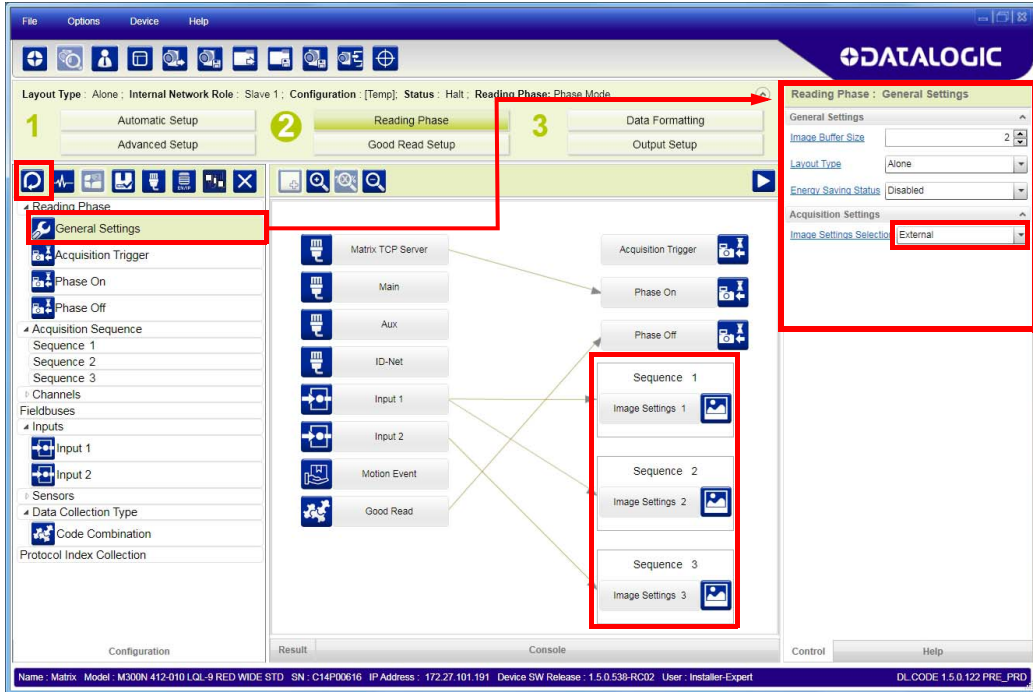
Applications typically require more than one acquisition to obtain sufficient Good Read percentages. This means that for N acquisitions we will surely have captured the correct lighting condition, but we will also have captured some acquisitions with the wrong lighting condition. A consequence then is that we cannot run these types of applications at the maximum speed because not all the acquisitions are useful to us. We must wait for a sufficient number of acquisitions that will guarantee a Good Read result.

If items to be read having the same lighting conditions are grouped together, then we can improve the read rate through the **Start Acquisition From** parameter. By choosing the **Last Successful** value, we will start with the Image Setting that last produced a Good Read. For this group of items the last Image Setting used will be correct for the next item and so we start each cycle with the acquisition that will potentially produce a Good Read.

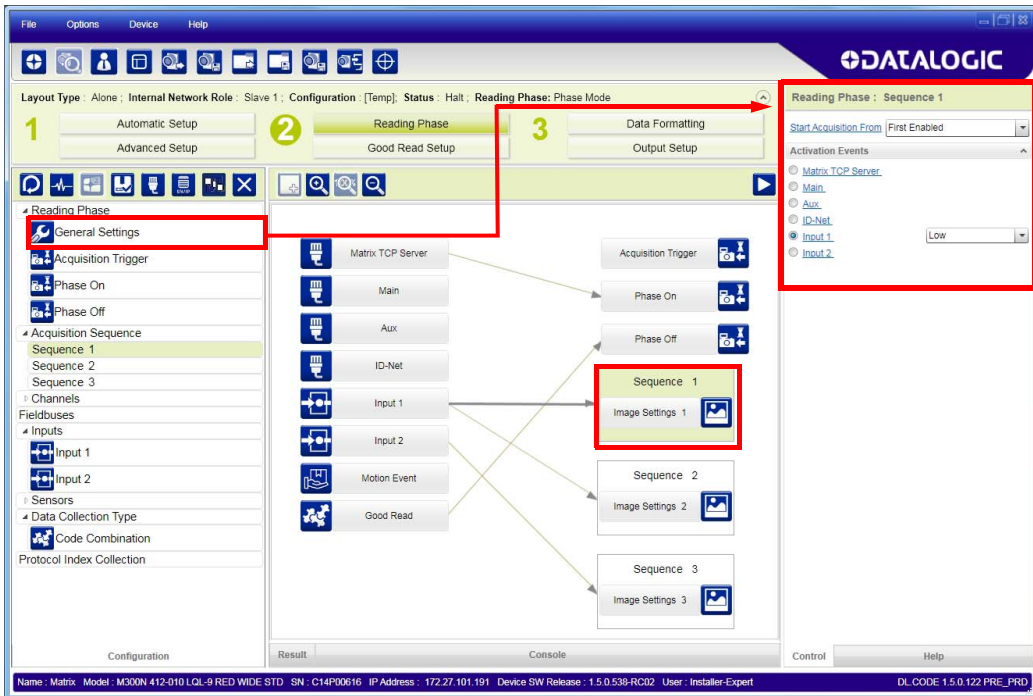
External Image Settings Selection

There are some applications where the lighting conditions are known before each item is read and therefore we can pre-select the correct Image Setting from an external source.

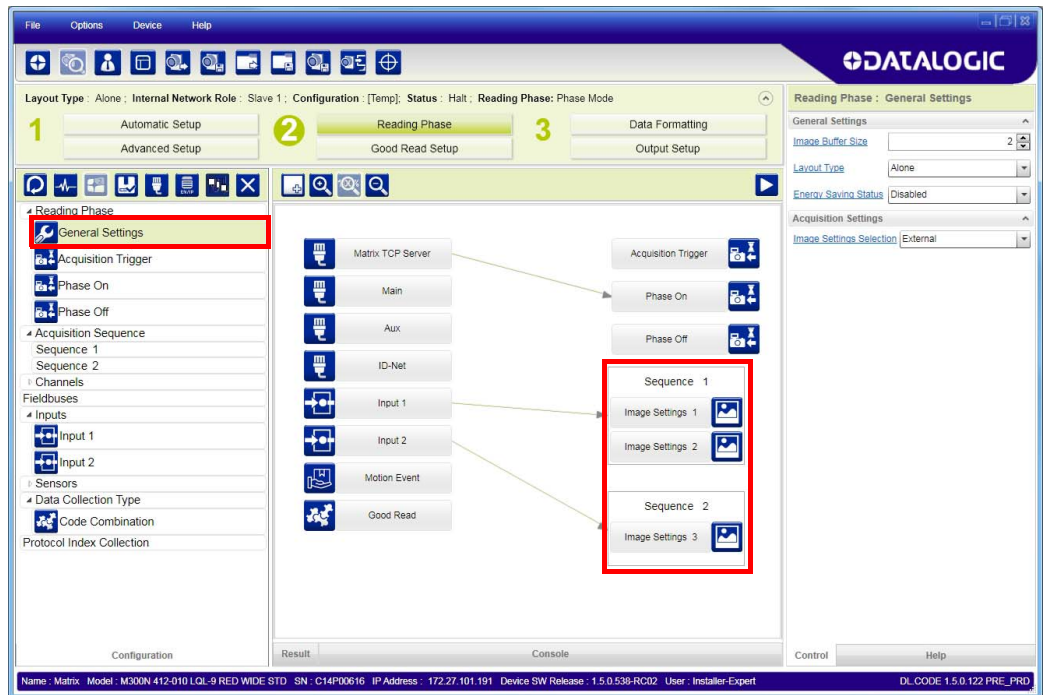
When the **Image Settings Selection** is **External**, Acquisition Sequences are created and by default each Image Setting has its own Acquisition Sequence.



Each **Acquisition Sequence** can be activated exclusively by a single event, either through a string from an available communication channel or by a digital input.



Alternatively, a hybrid configuration can be made where more than one **Image Setting** can be grouped into an Acquisition Sequence by dragging it into the desired Sequence box. Select the empty Sequence box and delete it with the delete key.



Each **Acquisition Sequence** can be activated exclusively by a single event, either through a string from an available communication channel or by a digital input.

In this case the **Start Acquisition From** parameter can improve the read rate for that Sequence. It has no meaning for a Sequence containing only one Image Setting.

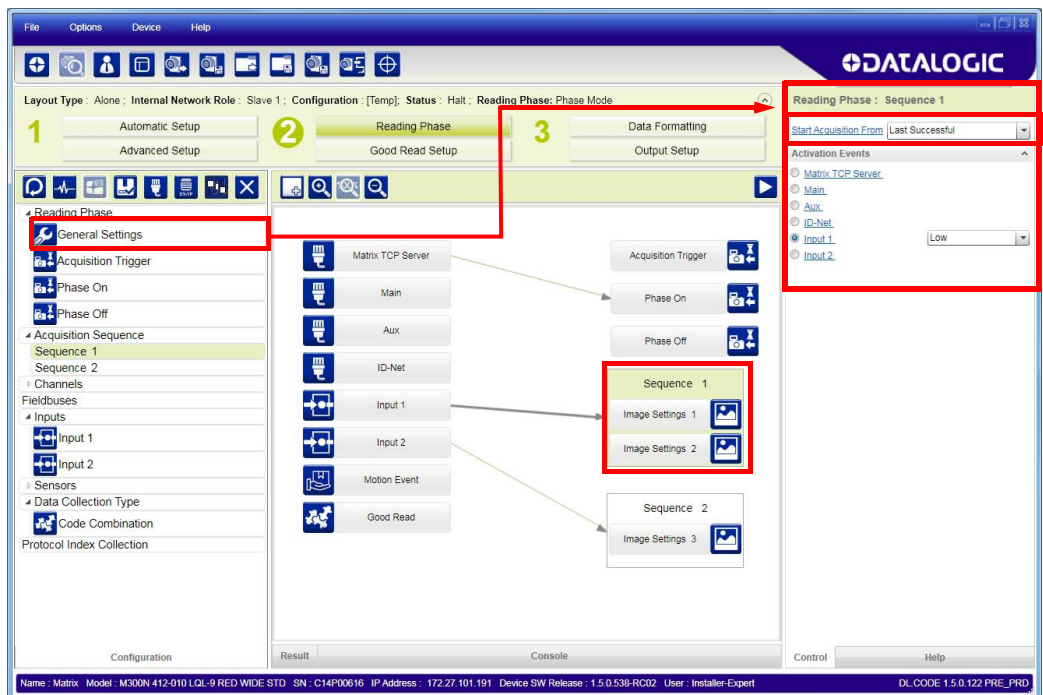


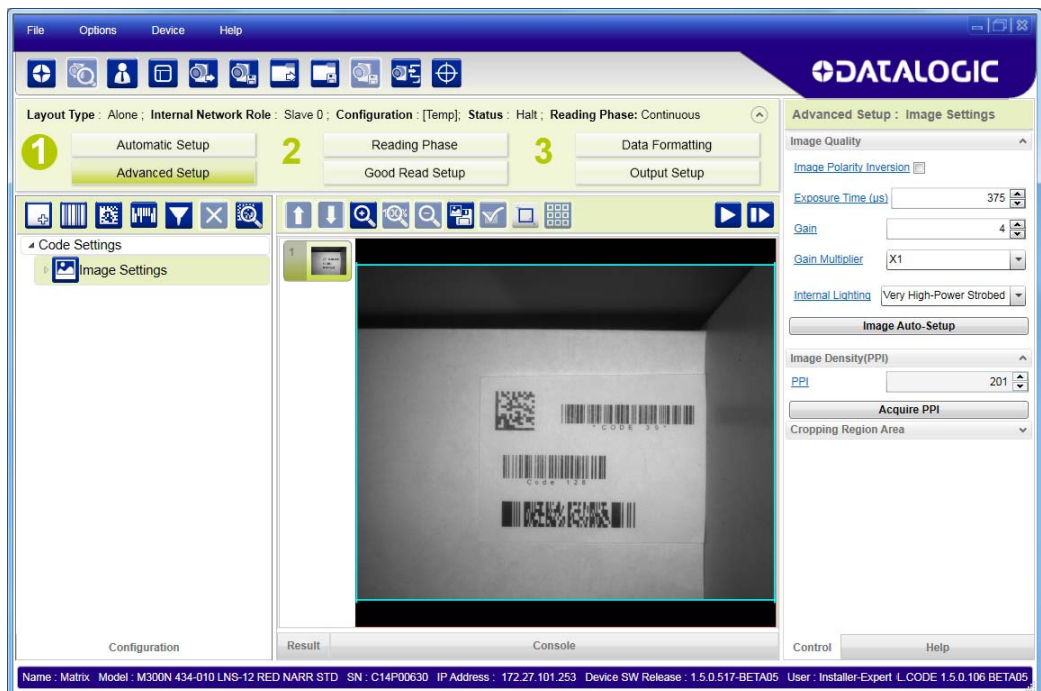
IMAGE CROPPING

In some applications, the Image Cropping feature in DL.CODE can help to increase decoding and result performance. Image cropping is performed from the Advanced Setup tab by clicking on the Add Cropping Region icon as shown below.

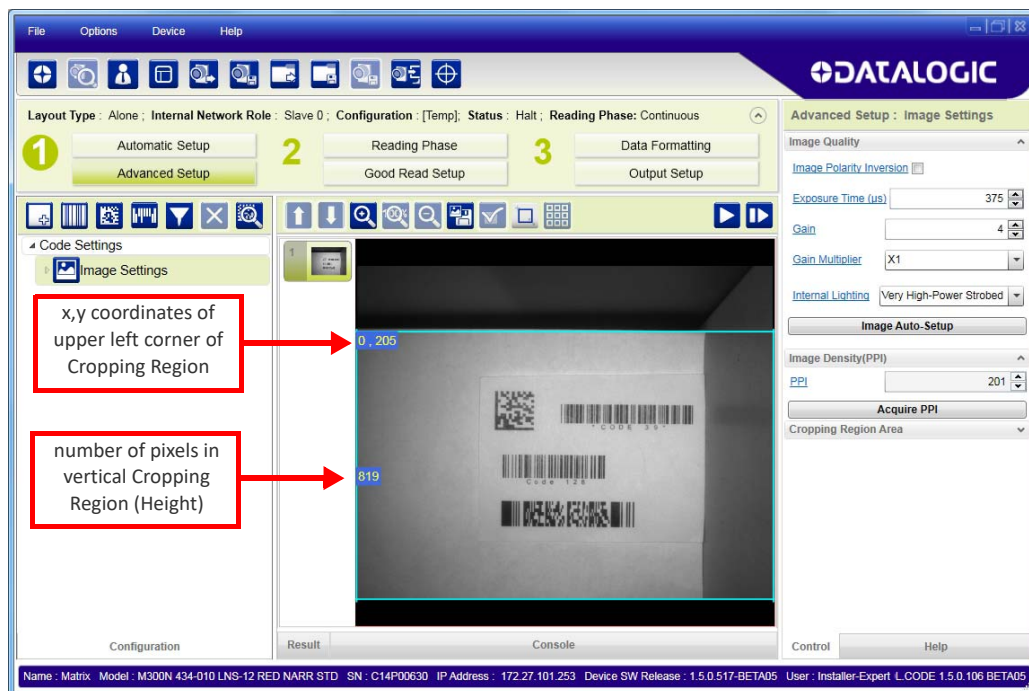
In Matrix 210N the frame rate is dependent on the number of rows and columns in the defined window. Image cropping allows reducing the Image processing area from the full FoV to a smaller area where codes are present. By excluding portions of the FoV, processing time is reduced.



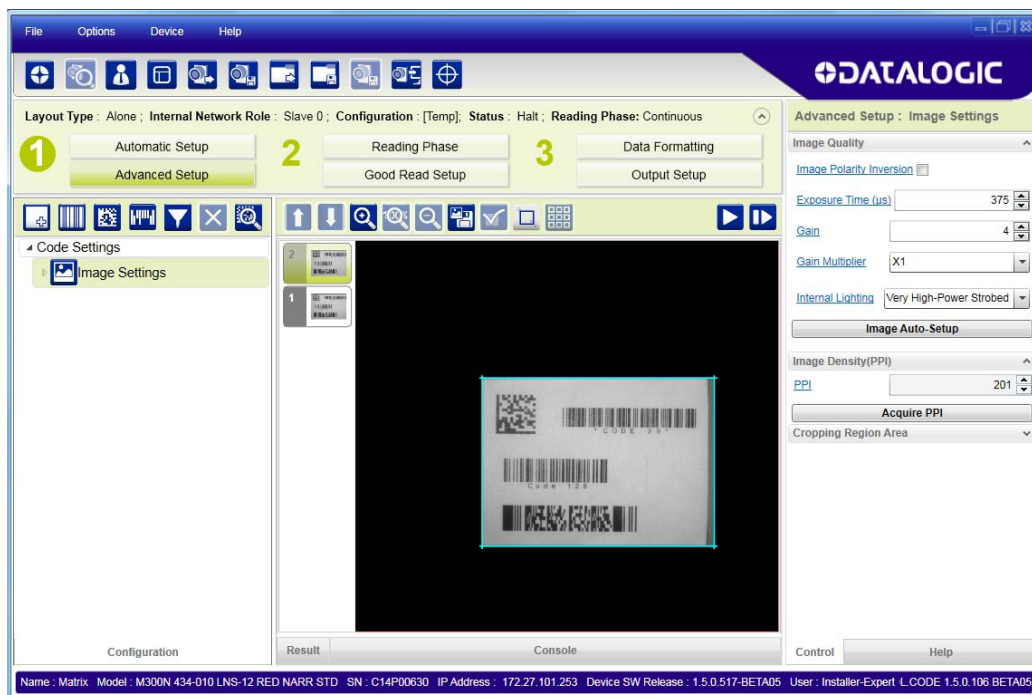
After clicking the Add Cropping Region icon, a blue border appears which by default is equal to the FoV.



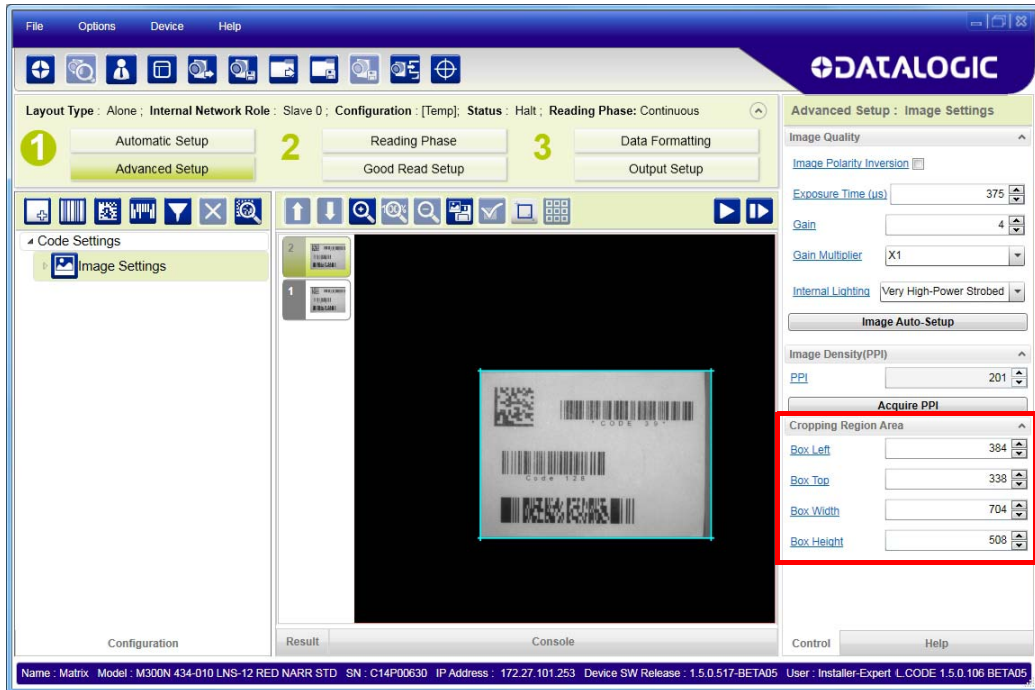
By dragging the edges with the mouse (resizing) you can crop the image to a specific location where codes are present. The numbers in the blue boxes refer to pixel references.



The cropped area can be moved by dragging the center.



You can also set the cropped image size and position through the Cropping Region Area group of parameters; size = **Width** and **Height**, position = **Left**, **Top** (x,y) coordinates.



DIRECT PART MARKING APPLICATIONS

For **Data Matrix** family codes the **Decoding Complexity** parameter is available when Processing Mode is set to Standard and selects the decoding algorithm according to the printing/marketing technique used to create the symbol and on the overall printing/marketing quality.

The possible selections progress from Low to Very High where Low can improve decoding time for good print/mark quality and/or relatively normal size codes. This is the default setting. Very High can improve the decode rate for low print/mark quality and/or small size codes. This algorithm is much more aggressive but in general it may have longer decoding times than the lower complexity algorithms. **To minimize decoding time it is better to select the lowest value that still guarantees good decoding.**



Figure 84 - Problematic Direct Part Marking Examples

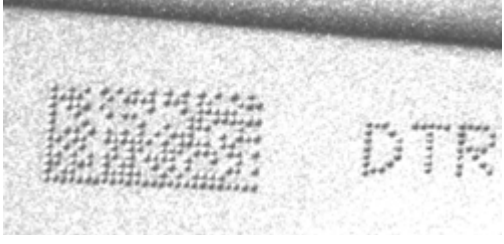
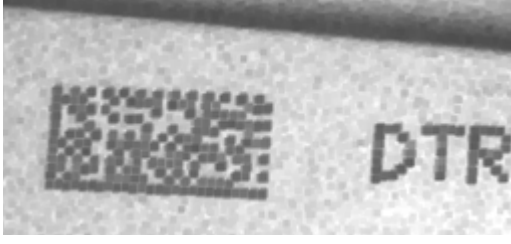
For **QR** code the **Decoding Method** parameter allows the Dot Peen Decoding algorithm to be selected which improves the decode rate for low quality Direct Part Mark codes and in general for Direct Part Mark codes with dot peening type module shapes.

Image Filter

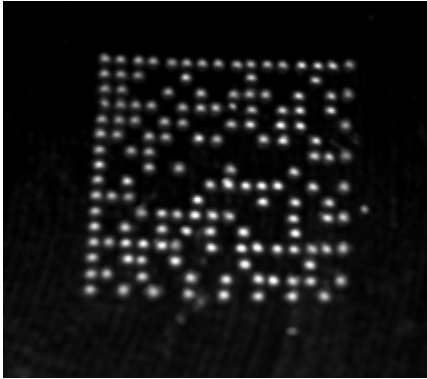

Sets the filter to be applied to the image before being processed. This parameter can be used to successfully decode particular ink-spread printed codes (e.g. direct part mark codes).

Different filters can be applied to a single code or group of codes in one or more **Image Settings**. See the DL.CODE User’s Manual for examples of Image Filter application.



The **Erode** Filter enlarges the image dark zones to increase readability.

	
Before - No Read	After - Readable

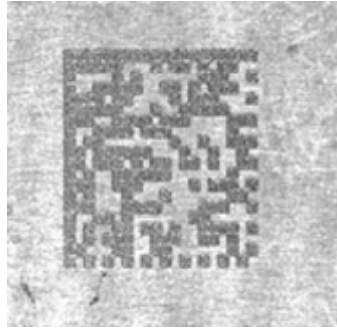
The **Dilate** Filter enlarges the image white zones to increase readability.

	
Before - No Read	After - Readable

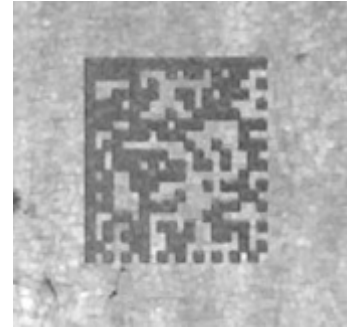
The **Close** filter eliminates dark areas (defects) in the white zones of the image.

	
Before - No Read	After - Readable

The **Open** filter eliminates white areas (defects) in the dark zones of the image.

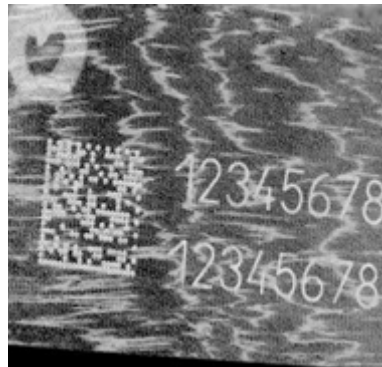


Before - No Read

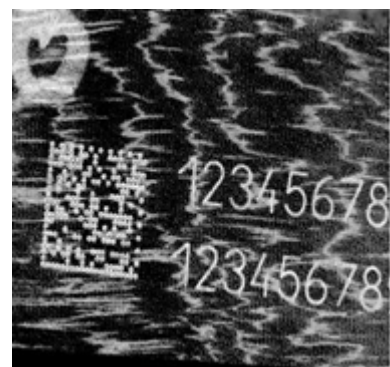


After - Readable

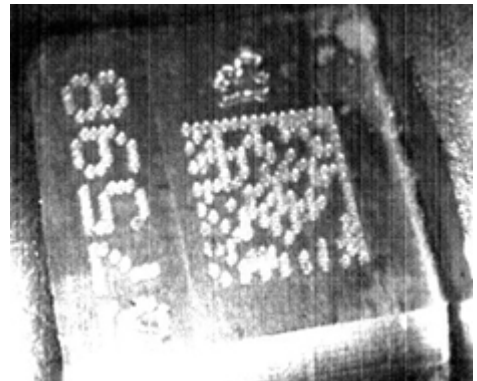
The **Contrast Stretching** filter maximizes image contrast.





Before - No Read



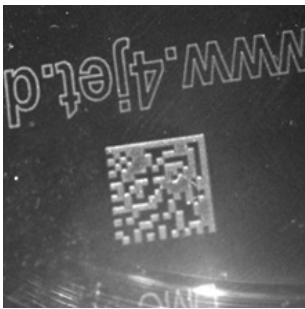
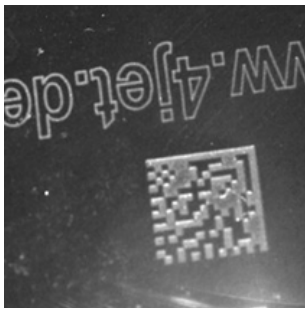
After - Readable



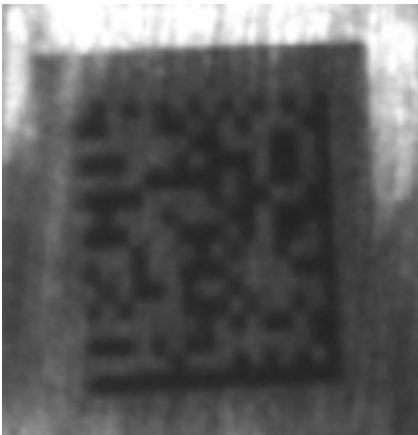
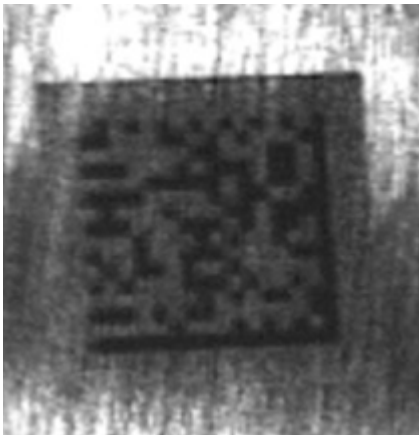
The **Histogram Equalization** filter makes the gray level distribution uniform.

	
<p>Before - No Read</p>	<p>After - Readable</p>

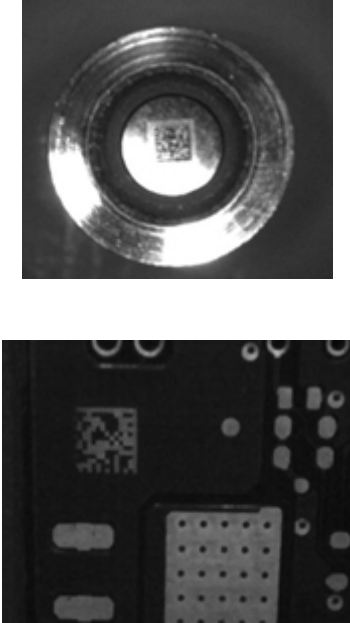
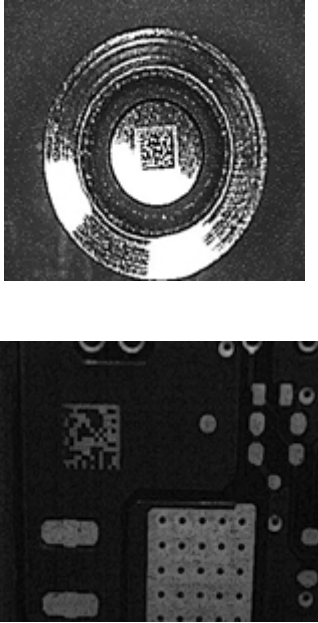
The **Smoothing** filter deletes small (insignificant) details in the center of the image.

	
<p>Before - No Read</p>	<p>After - Readable</p>



The **Sharpening** filter improves out of focus images.

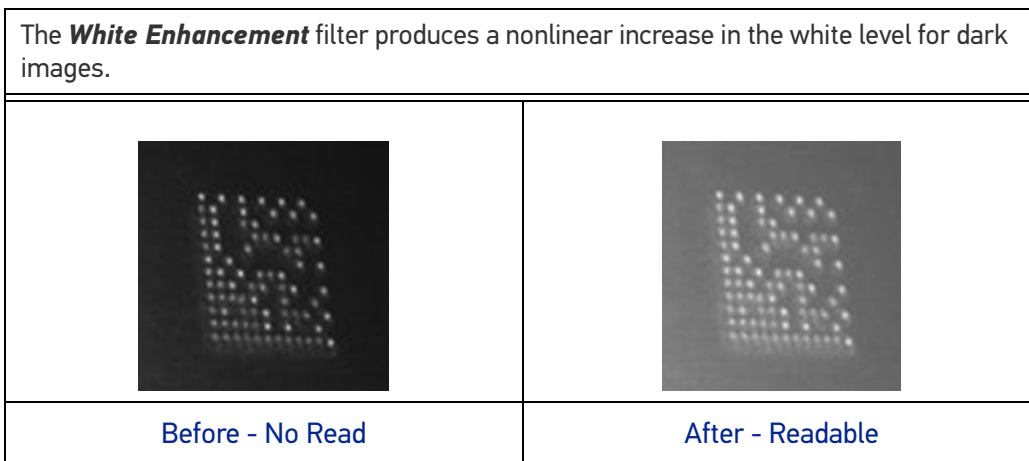
	
<p>Before - No Read</p>	<p>After - Readable</p>

The **Deblurring** filter improves blurred images.

	
<p>Before - No Read</p>	<p>After - Readable</p>

The **Black Enhancement** filter produces a nonlinear increase in the black level for light images.

	
<p>Before - No Read</p>	<p>After - Readable</p>

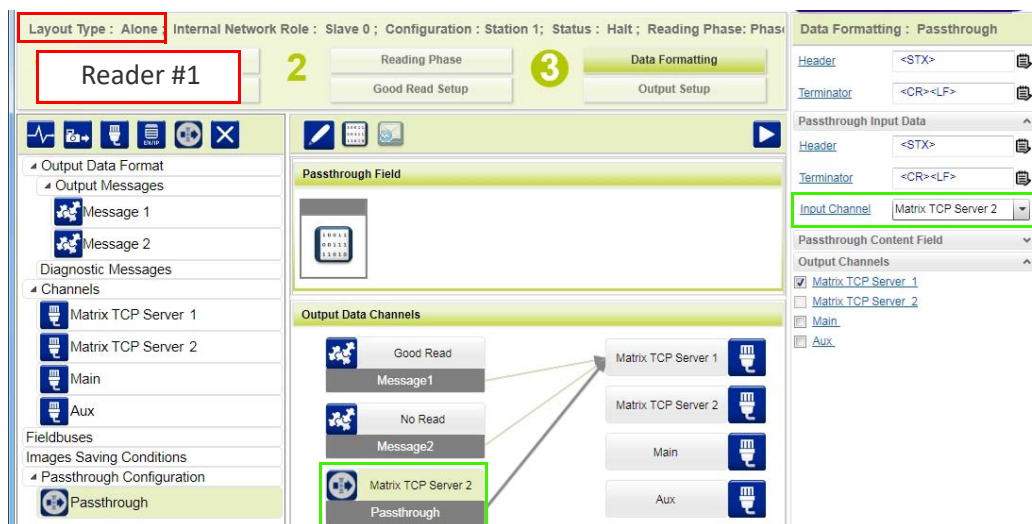


PASS-THROUGH CONFIGURATIONS

Starting from software version 1.3.0, DL.CODE and Matrix N family readers support pass-through multi device configurations.

The pass-through configuration allows individually working devices (Alone), to collect data from other devices (also working Alone) and pass this data to a third device through a different communication channel.

The following screenshots show the pass-through configuration settings for the three devices in the example in "Pass-Through" on page 89.



Layout Type : Alone Internal Network Role : Slave 0 ; Configuration : Station 2; Status : Halt ; Reading Phase: Phase 2

Reader #2 2 Reading Phase 3 Data Formatting

Good Read Setup Output Setup

Output Data Format

- Output Messages
 - Message 1
 - Message 2
- Diagnostic Messages
- Channels
 - Matrix TCP Server 1
 - Matrix TCP Server 2
 - Main
 - Aux
- Fieldbuses
- Images Saving Conditions
- Passthrough Configuration
 - Passthrough 1
 - Passthrough 2

Passthrough 2 Field

Output Data Channels

Good Read Message1 Matrix TCP Server 1

No Read Message2 Matrix TCP Server 2

Main Main

Aux Passthrough1 Aux

Passthrough2

Data Formatting : Passthrough 2

Header <STX>

Terminator <CR><LF>

Passthrough Input Data

Header <STX>

Terminator <CR><LF>

Input Channel Aux

Passthrough Content Field

Output Channels

- Matrix TCP Server 1
- Matrix TCP Server 2
- Main
- Aux

Layout Type : Alone Internal Network Role : Slave 0 ; Configuration : Station 3; Status : Halt ; Reading Phase: Cont

Reader #3 2 Reading Phase 3 Data Formatting

Good Read Setup Output Setup

Output Data Format

- Output Messages
 - Message 1
 - Message 2
- Diagnostic Messages
- Channels
- Fieldbuses
- Images Saving Conditions
- Passthrough Configuration

Message 1 Field

Expected Code 1

Output Data Channels

Good Read Message1 Matrix TCP Server 1

No Read Message2 Matrix TCP Server 2

Main Main

Aux

Data Formatting : Message 1

Header <STX>

Terminator <CR><LF>

Code Related Field

Output Channels

- Matrix TCP Server 1
- Matrix TCP Server 2
- Main
- Aux

Event Type

INTERNAL NETWORK CONFIGURATIONS

Internal Network configurations (also called Master/Slave configurations), are designed to collect data from several devices connected together in an ID-NET™ network and send data output to the Host system.

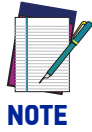
DL.CODE has a Net Autoset feature for the Internal ID-NET Network which automatically recognizes and assigns addresses to all connected Slave readers.

In order to automatically recognize the ID-NET Slaves, all devices must be physically installed and electrically connected (including ID-NET network wiring).

The general procedure (also detailed in the following paragraphs) is to:

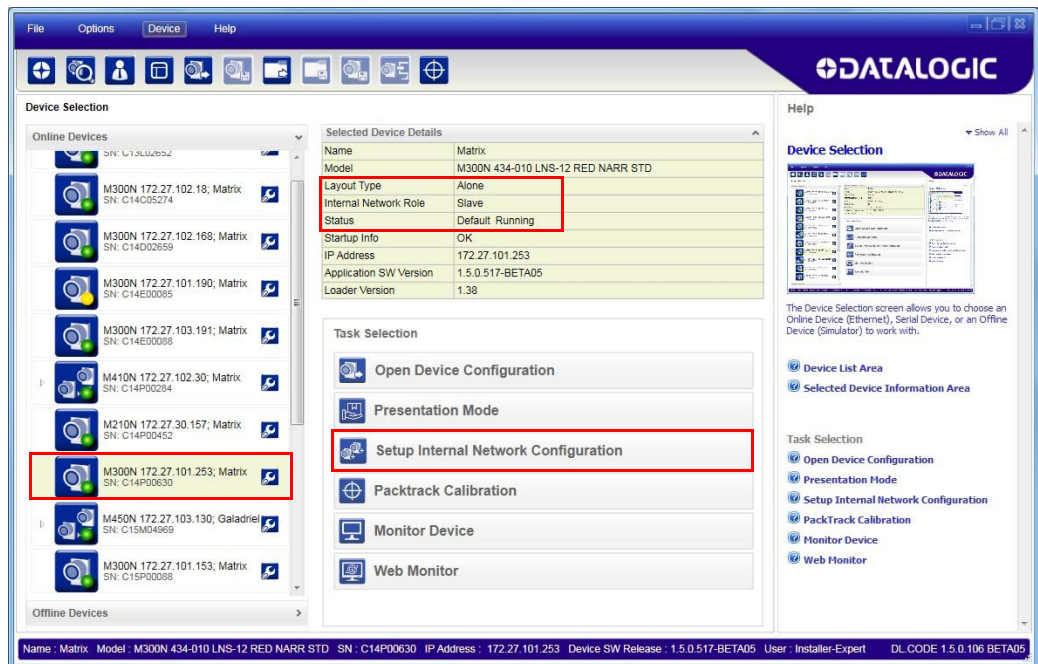
1. Mount all the readers mechanically (refer to "[Mechanical Dimensions](#)" on page 56 and "[Mounting And Positioning Matrix 210N](#)" on page 59) and electrically (refer to "[ID-NET Interface](#)" on page 66) with factory default settings (Layout Type = Alone, Internal Network Role = Slave).
2. Run DL.CODE and verify that all the devices are discovered and shown in the device list area.
3. Connect to the designated Master device in DL.CODE and open the **Setup Internal Network Configuration**. You will be prompted to change the device to Master. Click OK. The Slave units will automatically be recognized. See "[Master Configuration](#)" on page 121.
4. Depending on the application, select Multidata, Synchronized Phase Mode or Synchronized PackTrack Configuration.
5. Connect to each Slave reader via Ethernet and set the Slave specific parameters depending on the application type. Save each Slave specific configuration. See "[Multidata ID-NET Network Configurations](#)" on page 123 or "[Synchronized ID-NET Network Configurations](#)" on page 128.
6. For Synchronized networks Verify/Test network performance. See "[Verify Master/Slave Synchronized Configuration](#)" on page 132.
7. Perform the **Backup current Internal Network configurations** procedure. See "[Backup](#)" on page 136.

Master Configuration

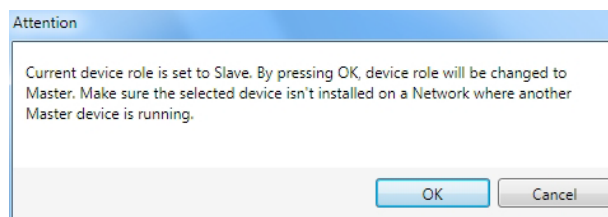


The following paragraphs demonstrate example network configurations using a Matrix 300N device. For Matrix 210N readers, the PackTrack operating mode is not available.

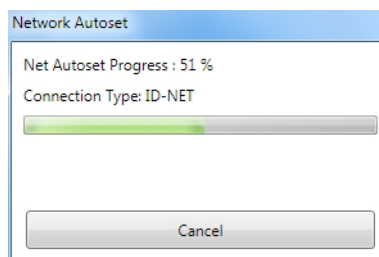
First start with the desired device to assign as ID-NET Master (current default setting is Slave). Click on Setup Internal Network Configuration from the Task area.



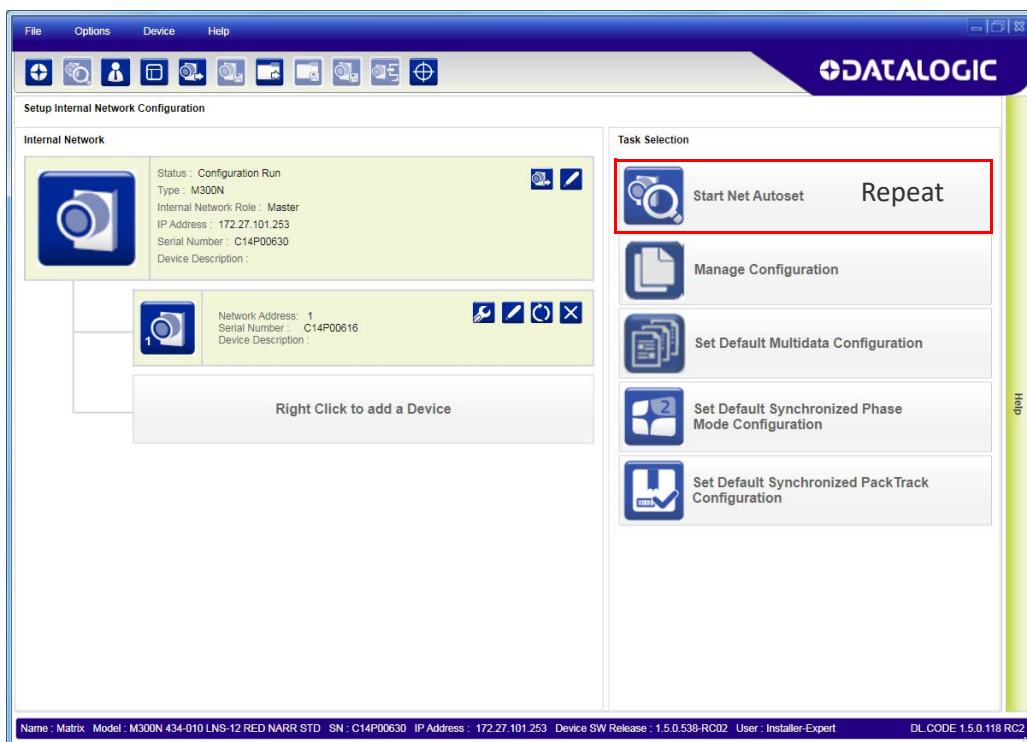
You will be advised that the device role will be changed to Master.



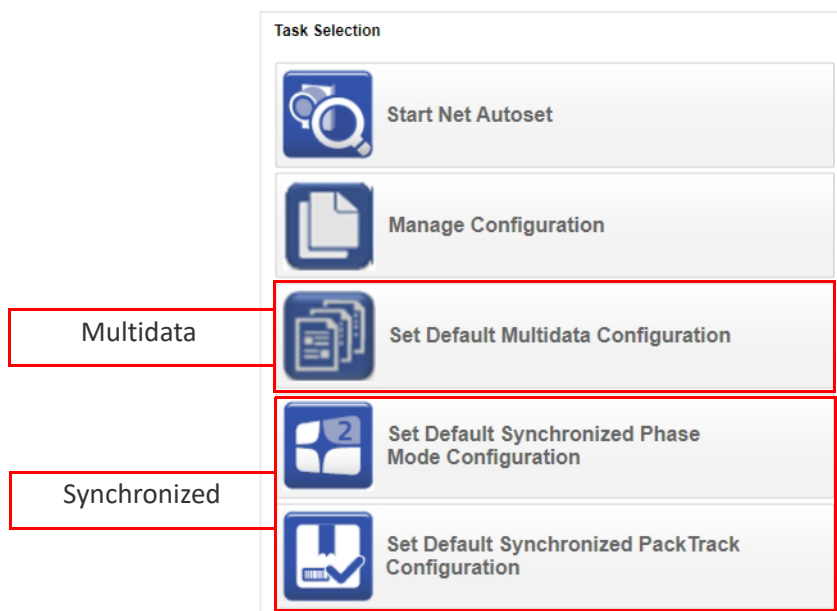
Click OK. The Net Autoset feature automatically starts to find Slave devices connected to the ID-NET network of the Master.



When finished, all the Slaves should have been correctly recognized. If not, verify all device connections and power and then repeat the operation by clicking on the Start Net Autoset button.



Depending on the application, select one of the Default Internal Network Configurations: **Multidata** or **Synchronized Phase Mode**.



This selection will open a pre-configured job for the Master reader according to the selection. Follow the specific application instructions in the following paragraphs.

Multidata ID-NET Network Configurations

The Multidata ID-NET network communications between Master and Slave are managed by the application job (configuration) using the pass-through feature. A pre-configured job is loaded with the correct pass-through settings for both the Master and Slaves when the Default Multidata Configuration is selected from the Internal Network Setting feature.

1. Complete the configuration of all the application parameters (including Image Settings) and save them to the Master with an application specific name. Optionally, checking the **Save on Slave Device** box can be helpful to save all the current individual Slave configurations with the new configuration *name*. This does not clone any parameters. If not checked, Slave configurations will remain as *Temp* configurations and you will be warned that changes to the Master have not been saved to the Cluster.

For Multidata configurations, the option to **Clone Master configuration on Slaves** **must not be checked**.

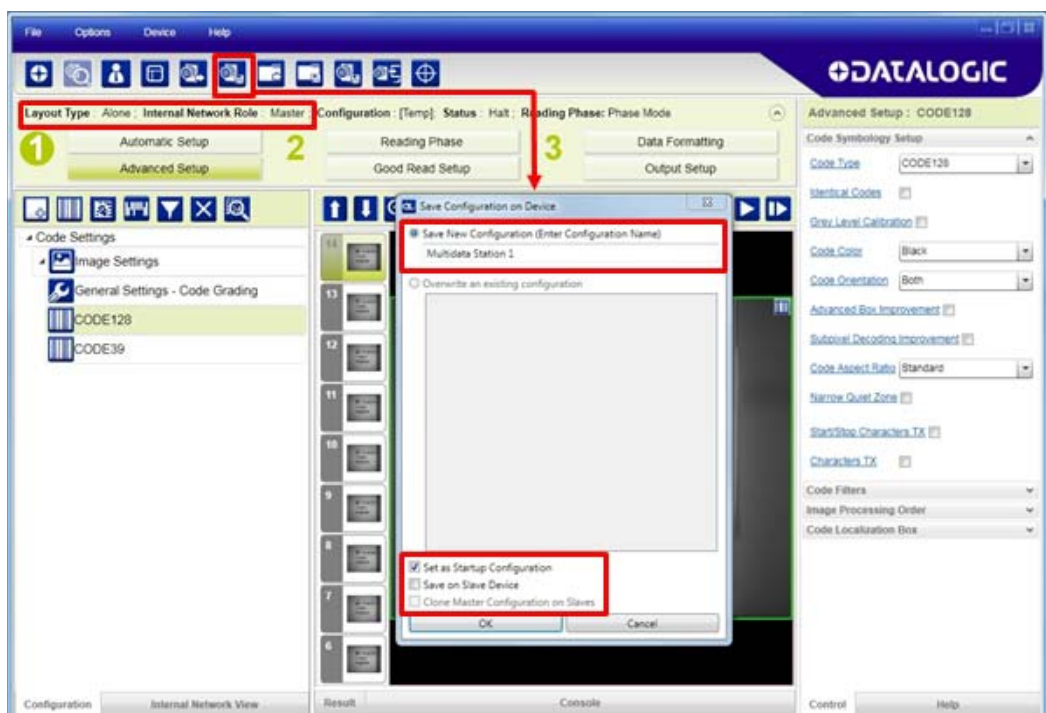


Figure 85 - Saving Multidata Configuration to Master

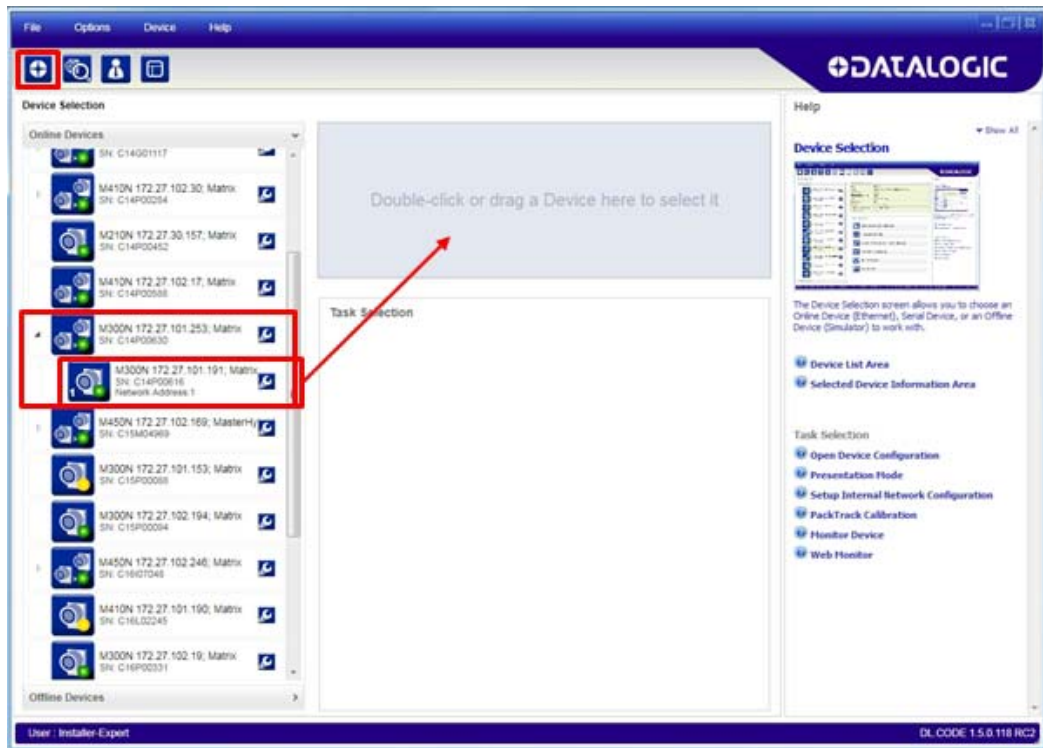
The jobs must not be cloned because the Master and Slaves have different input/output communication channels. The readers are also working independently from each other, often on separate stations with different code reading requirements, different operating modes, etc.

2. Connect to each Slave reader via Ethernet (see note below), and set all the configuration parameters of each Slave device.

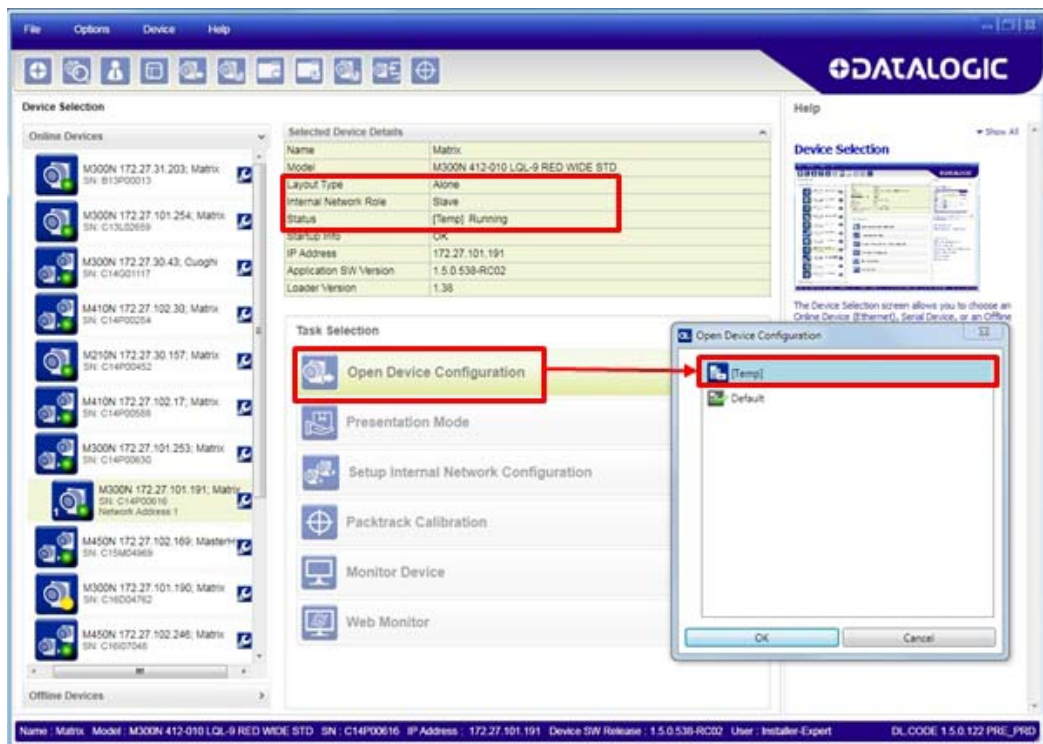


NOTE

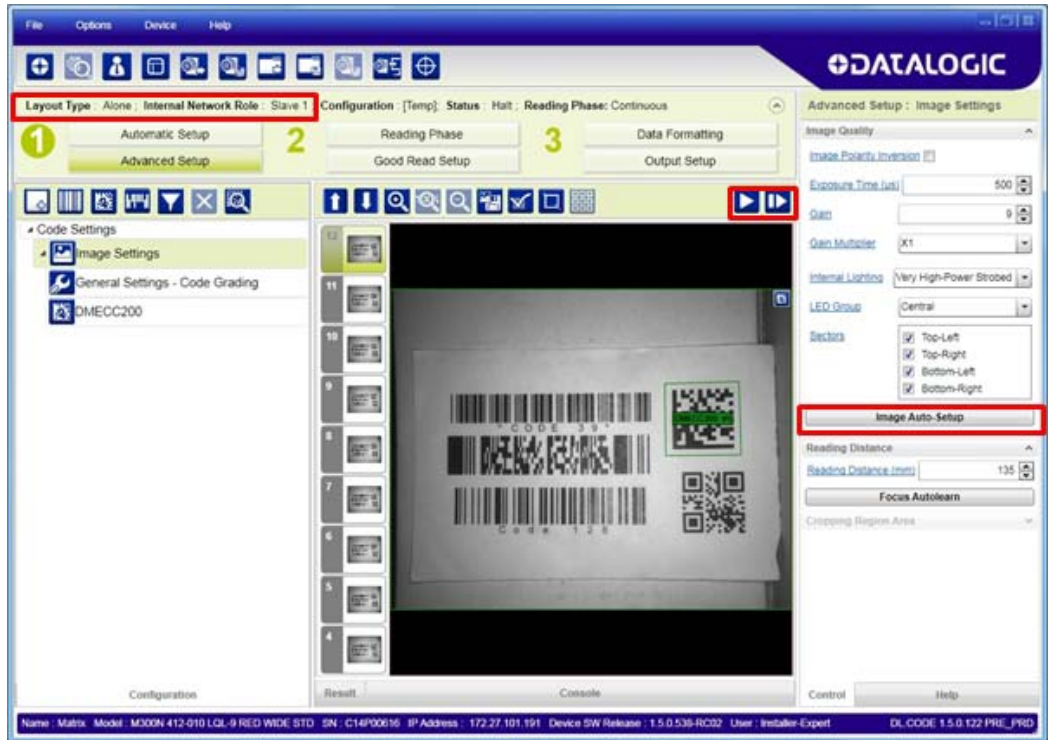
If necessary, Slave device photometric (Image Settings) parameters must be configured separately through DL.CODE. This is preferably done through each device's Ethernet TCP/IP channel. If Slave devices are not connected to Ethernet you must temporarily (manually) connect them one by one to perform Image Settings.



Open the **Slave specific application** job, (it will either have the new name saved from the Master or Temp depending on the **Save on Slave Device** selection).



When the configuration opens, pause run mode and set all the application specific configuration parameters (including Image Settings).



Verify the focus and decoding with the capture image button.

3. Now save them to a new Slave specific application job¹.

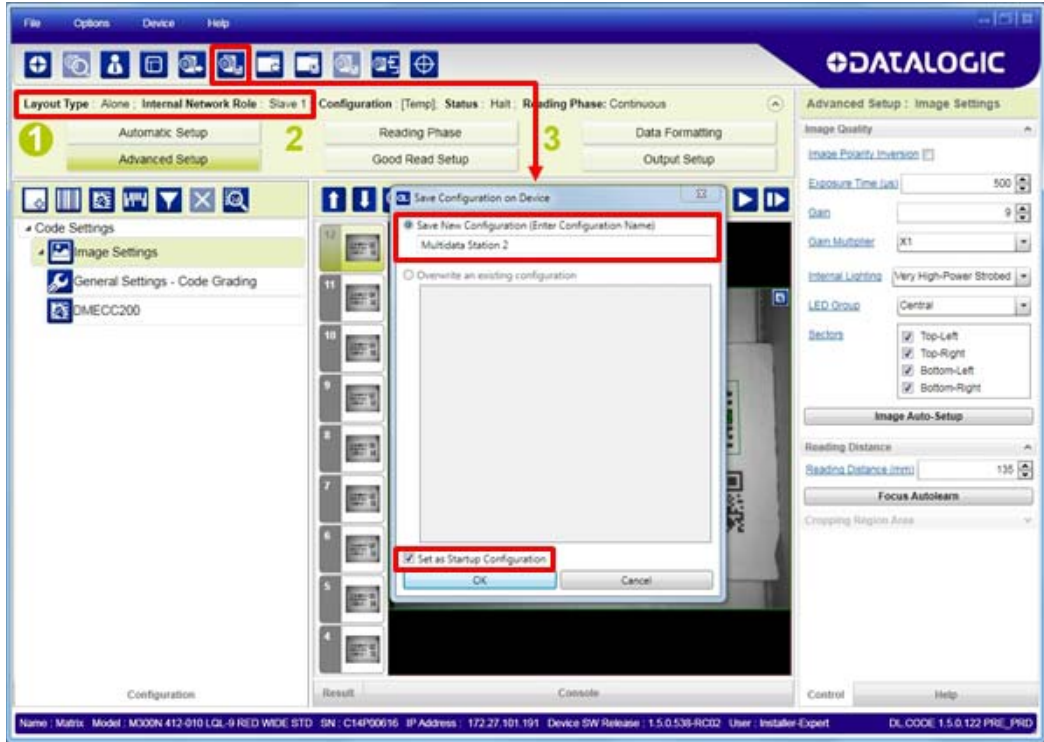
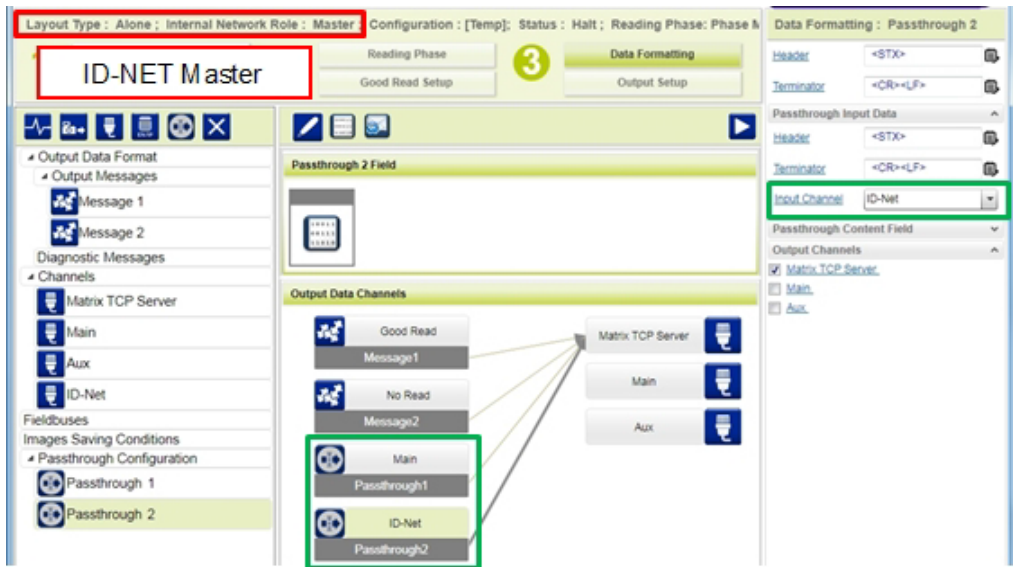


Figure 86 - Saving Multidata Configuration to Slave 1

Repeat this procedure for each Slave device until the entire network is configured.

The following screenshots show the pass-through configuration settings.



1. If **Save on Slave Device** was selected when saving the Master configuration, an application job with the same name (but with all Slave specific configuration parameters), has been saved to the Slaves. No parameters have been cloned from the Master. There are no common parameters managed by the Master for Multidata configurations.

Layout Type : Alone ; Internal Network Role : Slave 1 Configuration : [Temp]; Status : Halt ; Reading Phase: Phase 1

ID-NET Slave #1

Reading Phase: 3 Data Formatting: Passthrough

Good Read Setup Output Setup

Output Data Format

- Output Messages
 - Message 1
 - Message 2
- Diagnostic Messages
- Channels
 - Matrix TCP Server
 - Main
 - Aux
 - ID-Net
- Fieldbuses
- Images Saving Conditions
- Passthrough Configuration
 - Passthrough

Passthrough Field

Output Data Channels

- Good Read Message1
- No Read Message2
- Aux Passthrough

Matrix TCP Server

- Main
- Aux
- ID-Net

Data Formatting : Passthrough

Header: <STX>

Terminator: <CR><LF>

Passthrough Input Data

Header: <STX>

Terminator: <CR><LF>

Input Channel: Aux

Passthrough Content Field

Output Channels

- Matrix TCP Server
- Main
- Aux
- ID-Net

Layout Type : Alone ; Internal Network Role : Slave 2 Configuration : [Temp]; Status : Halt ; Reading Phase: Contin

ID-NET Slave #2

Reading Phase: 3 Data Formatting: Message 1

Good Read Setup Output Setup

Output Data Format

- Output Messages
 - Message 1
 - Message 2
- Diagnostic Messages
- Channels
- Fieldbuses
- Images Saving Conditions
- Passthrough Configuration

Message 1 Field

Expected Code 1

Output Data Channels

- Good Read Message1
- No Read Message2

Matrix TCP Server

- Main
- Aux
- ID-Net

Data Formatting : Message 1

Header: <STX>

Terminator: <CR><LF>

Code Related Field

Output Channels

- Matrix TCP Server
- Main
- Aux
- ID-Net

Event Type

Synchronized ID-NET Network Configurations

The Synchronized ID-NET network communications between Master and Slave are internally managed by the application software. A pre-configured job is loaded with the Synchronized Layout Type and the correct Operating Mode for both the Master and Slaves when either the Phase Mode or PackTrack Configuration is selected from the Internal Network Setting feature.

1. Complete the configuration of all the application parameters (including Image Settings) and save them to the Master with an application relative name and **with** the option to **Clone Master configuration on Slaves**.



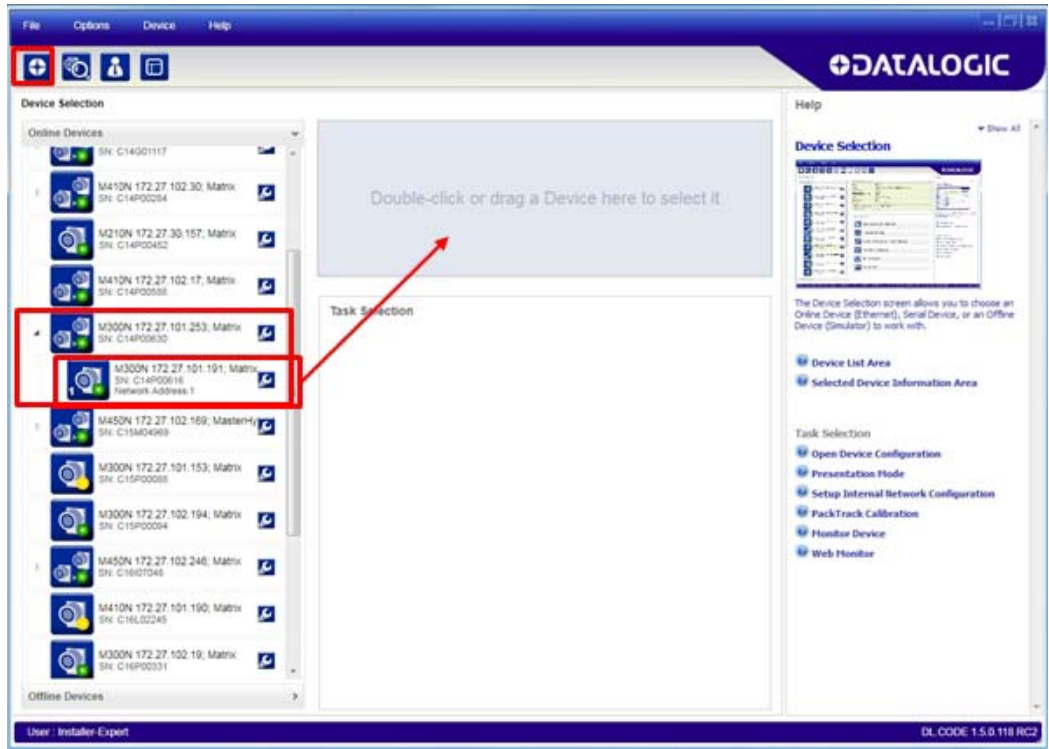
Figure 87 - Saving Synchronized Phase Mode Configuration to Master

2. Connect to each Slave reader via Ethernet (see note below) and set the Slave specific parameters.

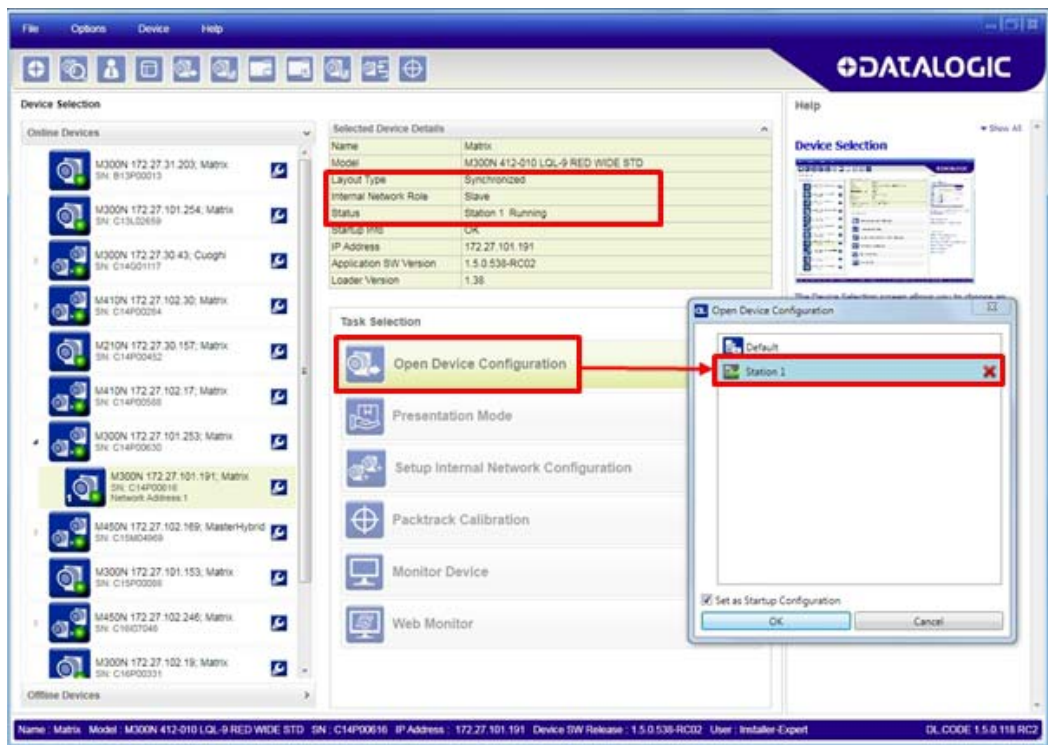


NOTE

If necessary, Slave device photometric (Image Settings) parameters must be configured separately through DL.CODE. This is preferably done through each device Ethernet TCP/IP channel. If Slave devices are not connected to Ethernet you must temporarily (manually) connect them one by one to perform Image Settings.

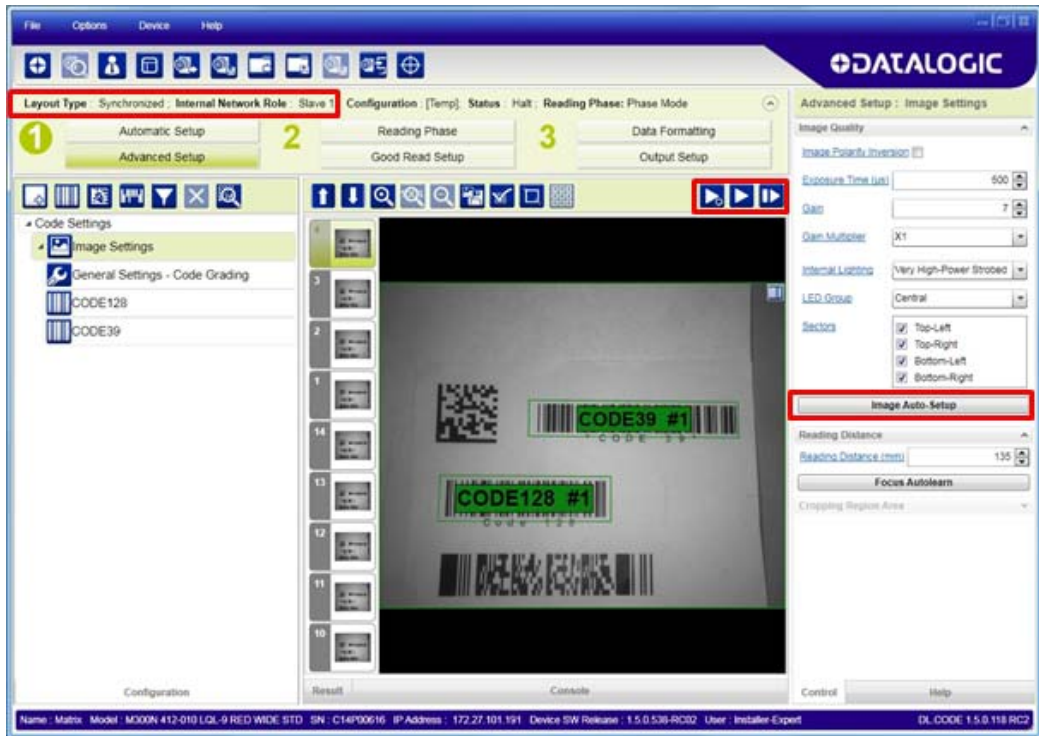


Open the cloned application job.



When the job opens, pause run mode and configure the Slave specific parameters. These depend on the application and include the following:

- photometric parameters (Image Auto-Setup feature in the Advanced Setup – Image Settings step)
- Acquisition Trigger Delays necessary to avoid lighting interference between adjacent or oppositely positioned readers (Reading Phase step)
- Images Saving if used (Data Formatting step)
- Encoder Sensor: if used, (for all Slaves, the Encoder Type must be set to **Internal**)



Verify the focus and decoding with the capture image button.

3. Now save them, overwriting the cloned application job¹.

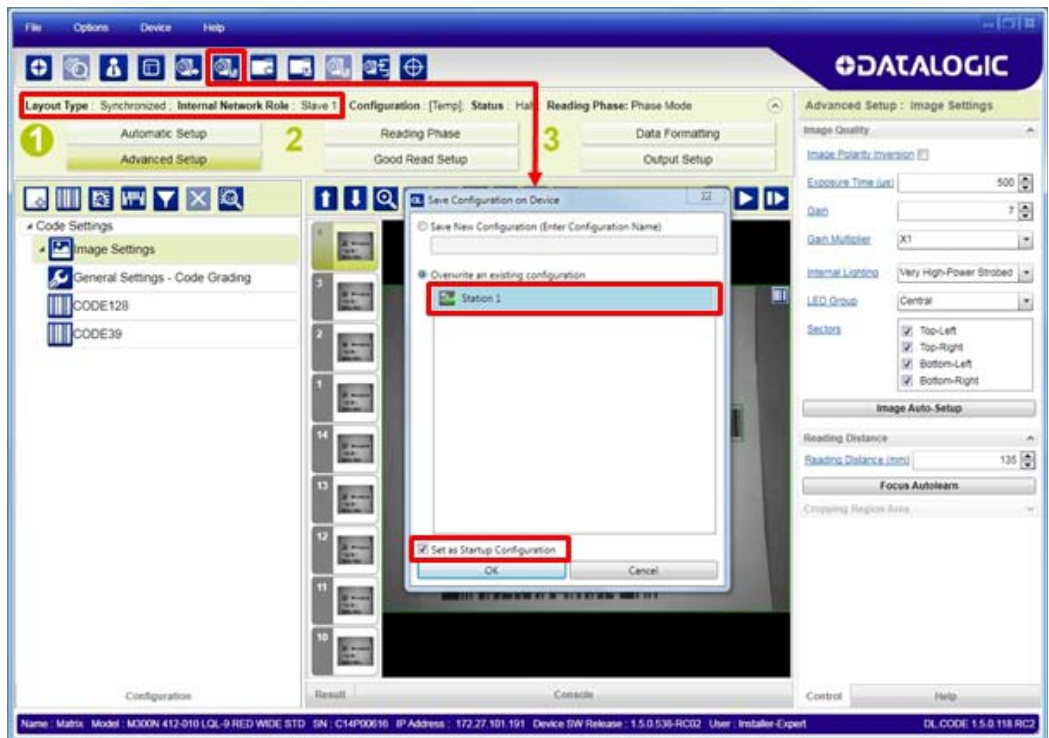


Figure 88 - Saving Synchronized Phase Mode Configuration to Slave

Repeat this procedure for each Slave device until the entire network is configured.

See "ID-NET Synchronized Network" on page 91 for an example.

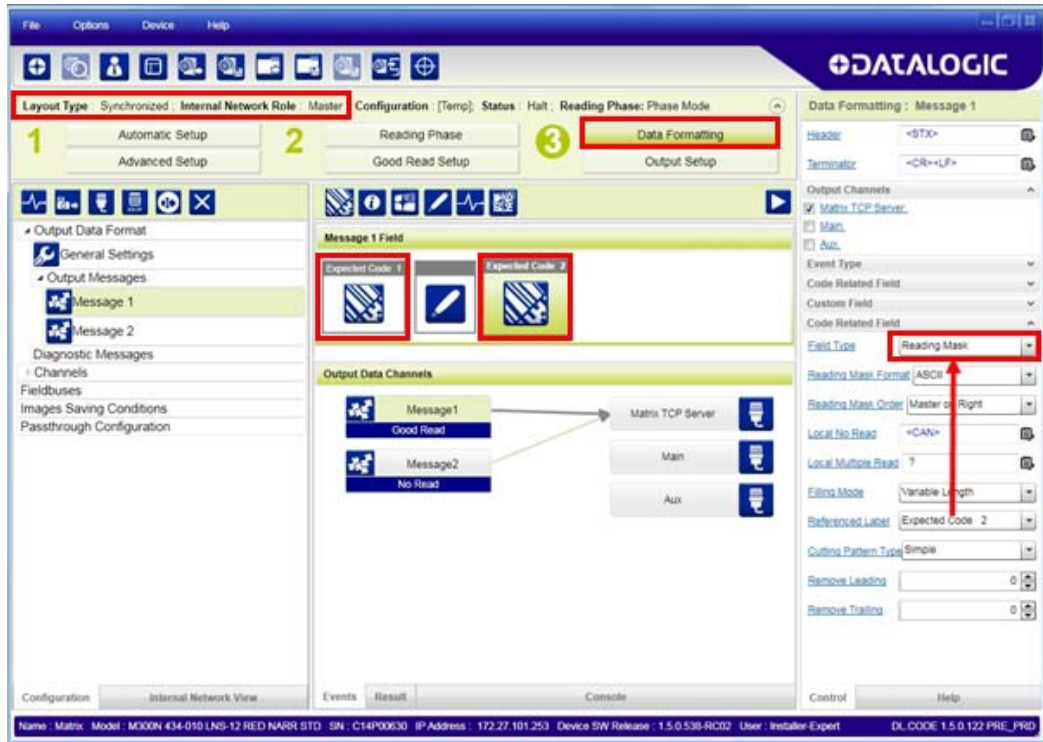
1. An application job with the same name as the Master's has been cloned to the Slaves. Each Slave can have its own Image Settings parameters saved in its own copy of the application job. Common parameters managed by the Master such as Operating Mode cannot be modified in the Slave jobs and are shown in dark gray.

Verify Master/Slave Synchronized Configuration

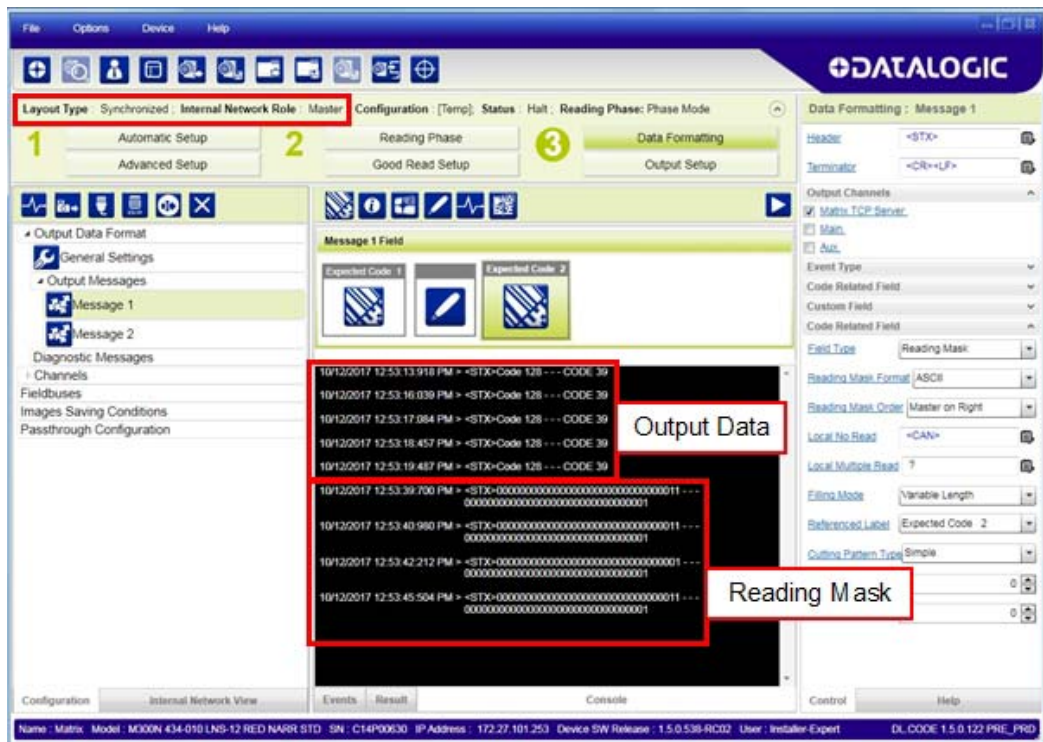
From the Master configuration, run the application and monitor the output data from the DL.CODE Console or a configured channel terminal.

If necessary, as a troubleshooting tip, you can temporarily apply the **Reading Mask** field in place of each Code Content field to verify if all devices are reading. To do this:

1. Connect to the Master device via Ethernet and from the Data Formatting step, change each Expected Code Field Type from Code Content to Reading Mask.



2. Run the application and monitor the output data from the DL.CODE Console or a configured channel terminal.



The Reading Mask shows which device reads which Expected Code. The mask is composed of a fixed 32-character string (0=No Read or 1=Read) representing the 32 possible readers in an ID-NET network. By default the Master is the last character in the string (**Master on Right**) but this can be changed. The Slaves are shown adjacent to the Master in order (1 to 31), by default from right to left.

Example: Master + Slave 1 = 0000000000000000000000000000000011

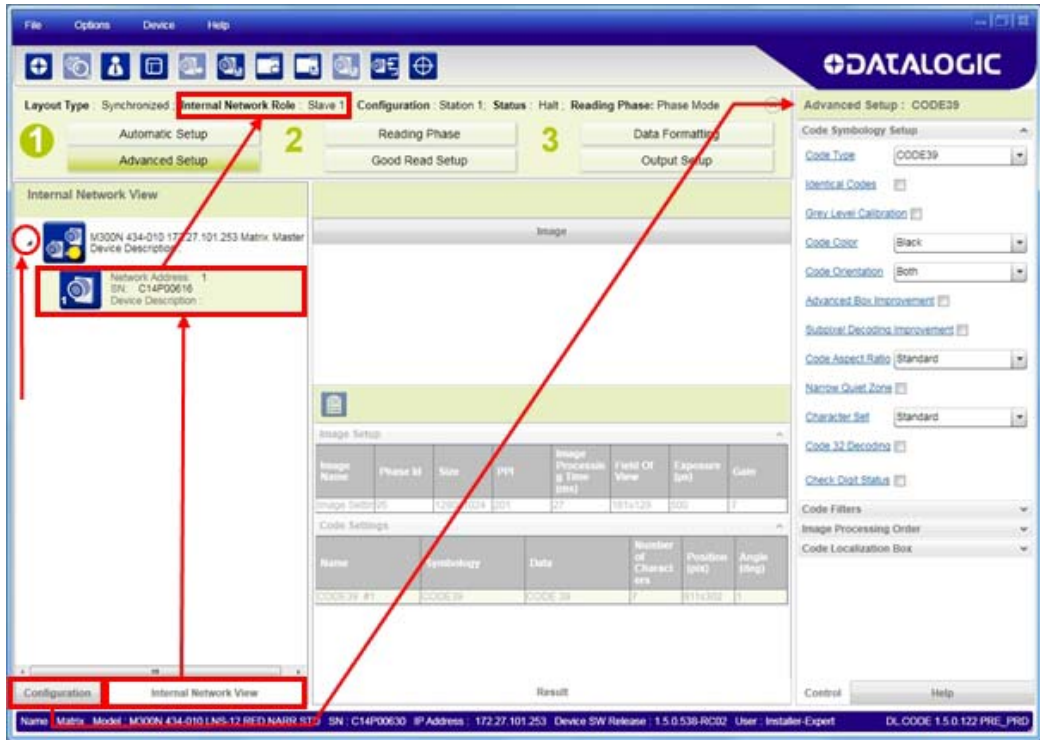
The figure above shows that both the Master and Slave 1 are reading Code 128 while only the Master is reading Code 39.

3. After verifying correct functioning of the reading devices, return the Expected Code fields from Reading Mask to Code Content.
4. If you haven't made any other changes you can exit without saving. Otherwise, save the Master device configuration overwriting its previous one, making sure to save **without Clone Master Configuration on Slaves**, otherwise the Slave configurations will be overwritten.

To view the connected Slave configurations:

1. Click on the Internal Network View tab at the bottom of the screen.
2. Open the Master branch by clicking on the arrow to the left of the Master icon.
3. Select any slave. Wait for the configuration to load.
4. Click The Configuration tab at the bottom of the screen.

By selecting the various configuration steps above you can visualize the slave configuration.



NOTE

You can modify some Slave Synchronized parameters from this view but you cannot save them here.

To save changed slave parameters here, you must click on the Master and Save the configuration overwriting it, making sure to select Save on Slave Device but **without** Clone Master Configuration on Slaves, otherwise all the Slave configuration parameters will be overwritten by the Master configuration.

BACKUP AND RESTORE THROUGH DL.CODE

DL.CODE allows Backup and Restore to be performed to/from the configuration PC via file or to an external storage device such as BM100/BM150.

DL.CODE provides complete backup and restore functions (Configuration and Environmental parameters) with the following difference:

For Single Readers or individual ID-NET Slaves:

- Backup and Restore functions provide parameter storage including all configuration jobs present on the reader.

For Master Readers in ID-NET Master/Slave networks:

- Backup and Restore functions provide parameter storage of only the Startup Configuration for the Master and all Slaves present in the network.



CAUTION

For Master/Slave networks any other configurations (jobs) stored in the device memory will not be backed up. Therefore, all jobs other than the startup configuration will be overwritten (erased) upon a restore. It is strongly recommended to save all configurations to backup files.

Slave devices must always be configured with the same network baudrate as the Master device for correct functioning including performing Backup and Restore procedures.

When performing Backup and Restore to/from file, device firmware can be included.

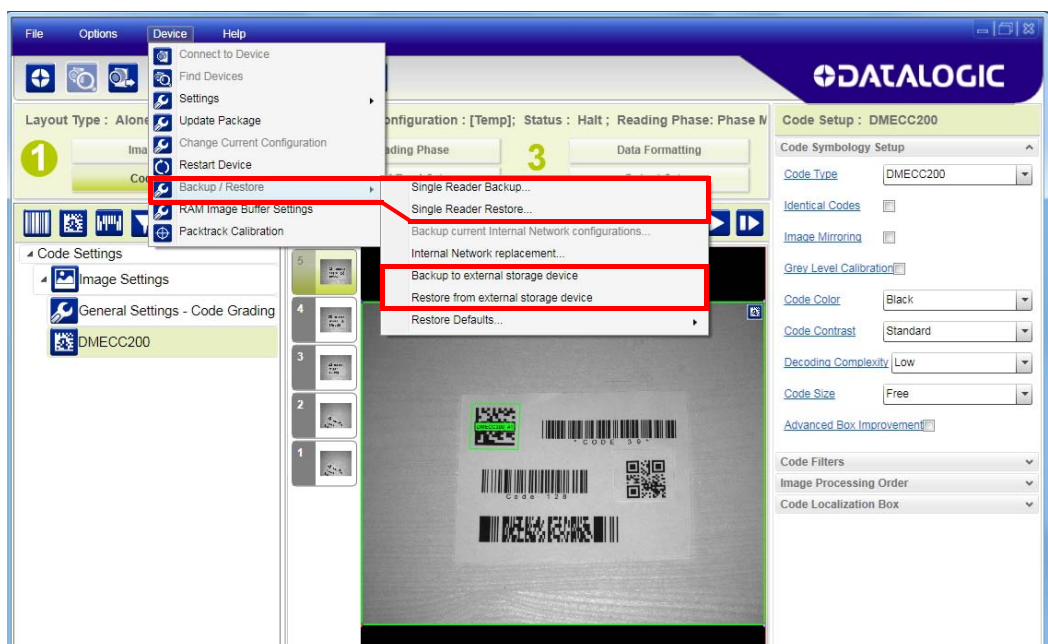
Regardless of the reader network configuration, Backup to and Restore from external device is supported by DL.CODE for all reading devices when connected to:

- CBX + BM100
- QLM-Series Gateways



NOTE

Before executing a Backup to a BM100 backup module make sure the Write Protection switch is set to Unlocked.



Backup

To perform a **Backup**:

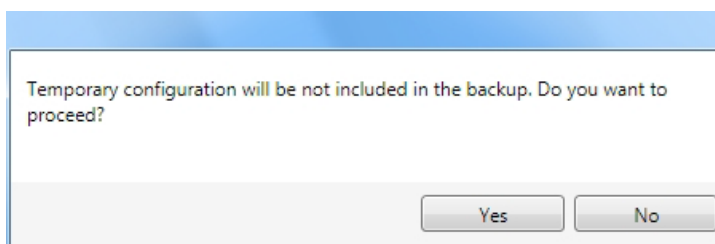
1. From the DL.CODE Device menu, select either **Single Reader Backup** (to file on PC); or **Backup to external storage device**.



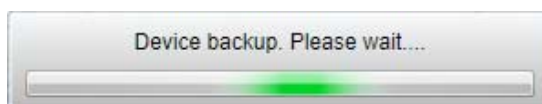
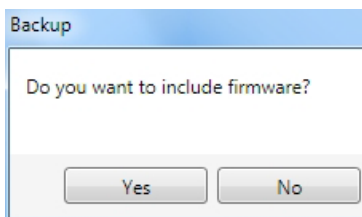
NOTE

For ID-NET network Backup, select the Backup current Internal Network configurations selection.

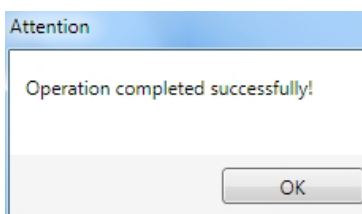
You will be reminded that configuration in temporary memory will not be saved so you should save the configuration to the reader before performing Backup.



If you are performing a backup to a file you will be asked whether to include the firmware or not.



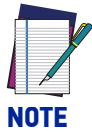
At the end of the backup, DL.CODE shows a message indicating successful completion.



Restore

To perform a **Restore**:

1. From the DL.CODE Device menu, select either **Single Reader Restore** (from file on PC); or **Restore from external storage device**.

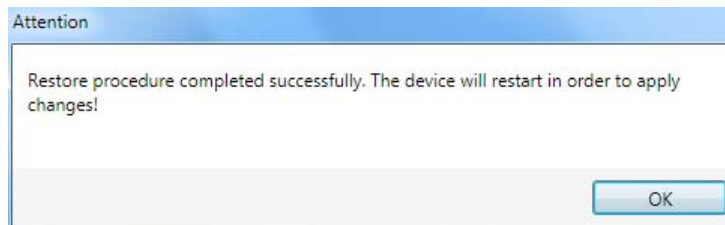


For ID-NET network Restore, select the Internal Network replacement selection.



If restoring an ID-NET network through the Master, this may take a few minutes.

At the end of the restore, DL.CODE shows a message indicating successful completion.



Replacement



The replacement device must be the exact same model as the device it is replacing.

The **Restore** function also provides easy and secure Single Device Replacement:

1. Remove the device to be replaced.
2. Connect the new device (make sure the new device has been previously set to factory default).
3. Run the Restore procedure by selecting either **Single Reader Restore** (from file on PC) or **Restore from external storage device** item (see: Restore procedure).



In case of Backup or Restore operation failures, error messages will be displayed in the Monitor Diagnostic page.

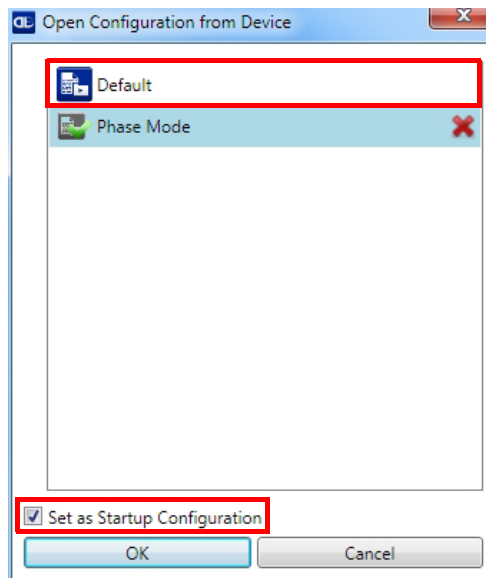
RESTORE DEFAULTS

The device parameters are divided into two main classes, Configuration and Environment which are affected differently by the Restore Defaults commands.

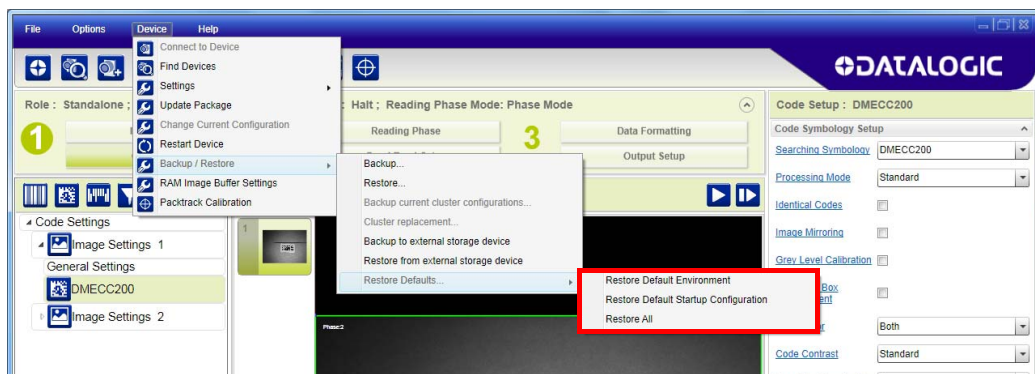
- The Configuration parameters are the ones set in the various steps of the configuration process and are specific to each application. When multiple configurations (jobs) are saved on a single device, these parameters can be different from one configuration to the next.
- Environment parameters regard the device Identity and Position in a Network (Ethernet, ID-NET, etc.) and are not influenced by the Default (or any other) Configuration present in memory.

Restore Default Startup Configuration

The Default configuration is always present on the reader and in fact it is not modifiable and cannot be deleted. It can always be restored by simply selecting it from the Open from Device configuration list.



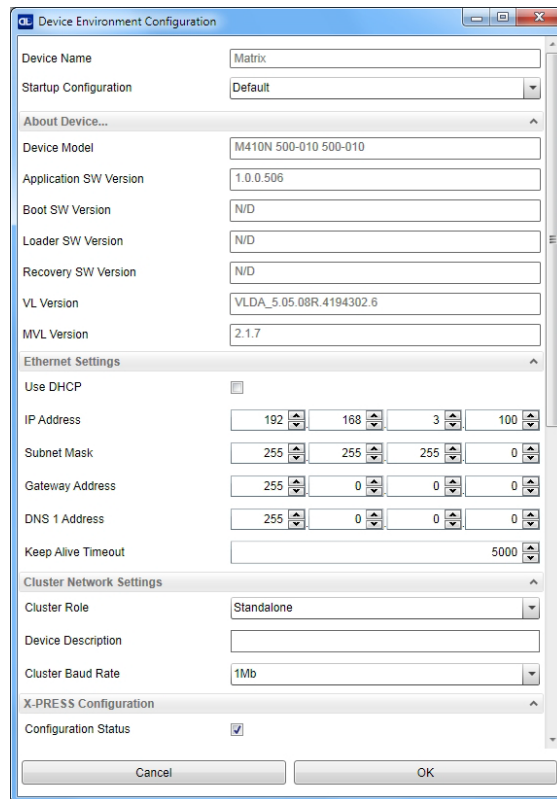
The same action can be performed from the Device menu >Backup/Restore > Restore Defaults > **Restore Default Startup Configuration**. The Default Configuration will be set to run at startup and the reader will be reset.



Any previously saved configurations on the device will remain in memory, but the Default configuration is set as the startup configuration.

Restore Default Environment

Restore Default Environment returns all Environment parameters to their factory default settings. The default IP address will be restored as well as all the parameters managed in the Device Environment Configuration window.



The Factory Default static IP address for all Matrix N Family readers is:

IP Address = 192.168.3.100

Any previously saved configurations on the device will remain in memory, but the Default configuration is set as the startup configuration.

Restore Factory Defaults

In order to return a device to its absolute Factory default parameters (for example device replacement) it is necessary to use the **Restore Factory Defaults** command. You will be prompted to confirm.

All Environment parameters will be restored to Factory default values **and any existing configurations stored on the device will be erased**. The device will be reset and therefore start in run mode with the factory default configuration.

DIAGNOSTIC ALARMS

By using the **DL.CODE Monitor** functions from the File menu (or Monitor icon), you can get information about the state of the ID-NET network.

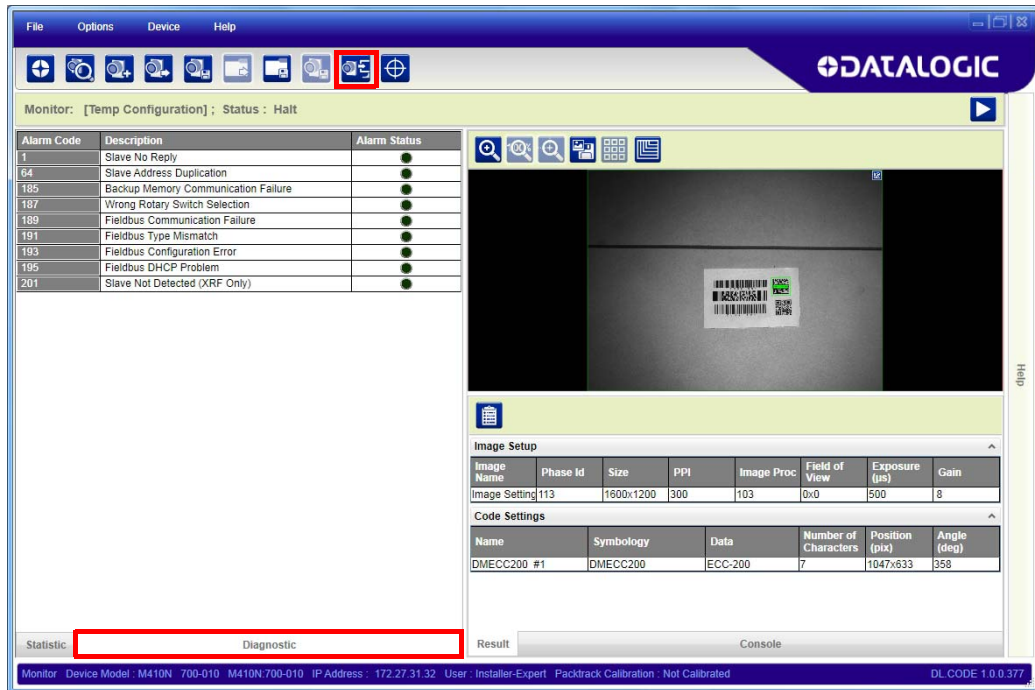


Figure 89 - Diagnostic Alarms

STATISTICS

Statistics on the reading performance can be viewed by enabling the Statistics panel from the **DL.CODE Monitor** item selected from the File menu (or Monitor icon).

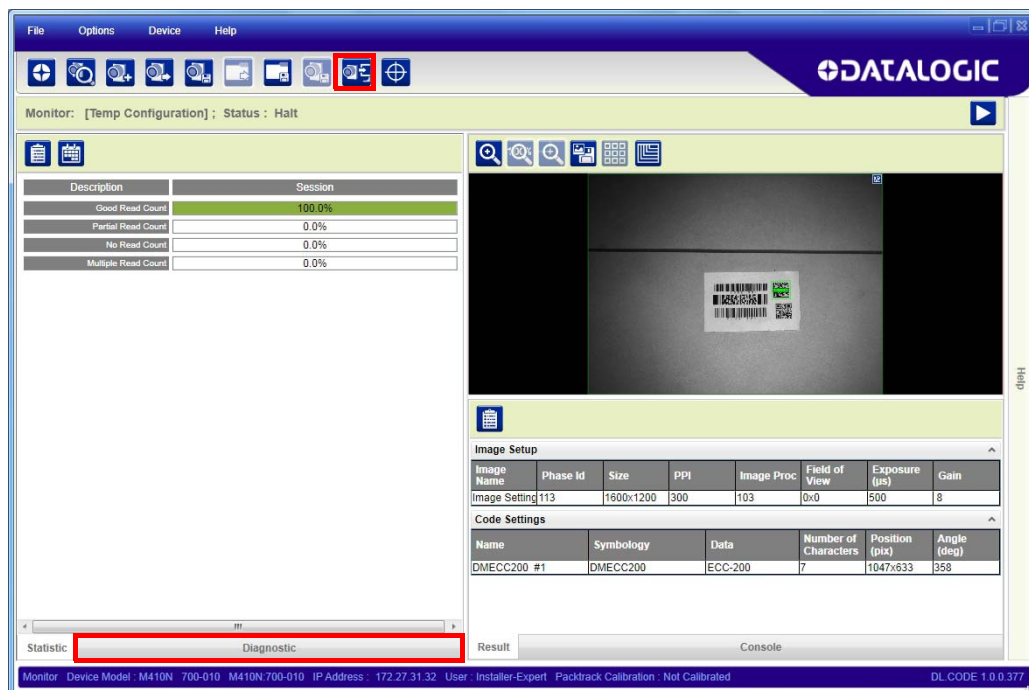
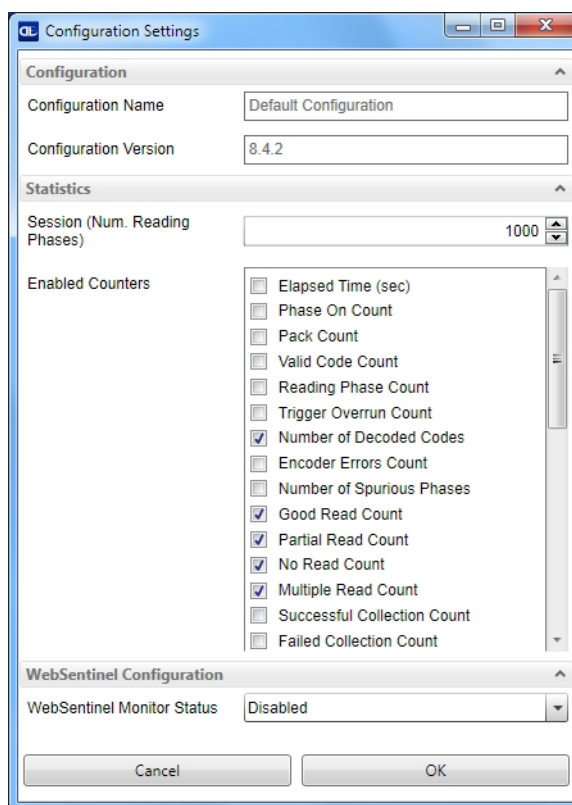


Figure 90 - Reading Statistics

The enabled Statistical Counters can be selected from the Device>Settings>Configuration Settings menu.



BM150 DISPLAY MODULE CONFIGURATION AND MESSAGES

The BM150 display module is an optional accessory for the CBX500 connection box. Although independent, it is an extension of the reader's HMI Interface, so through its keypad it provides execution of HMI features such as Test, Focus/Locate, Calibration and Code Setting. It also displays device status information, reading results, diagnostic and network messages. Since it connects through the BM100 backup memory module, it provides access to Backup and Restore features through its Extended menu.

Configuration Through DL.CODE

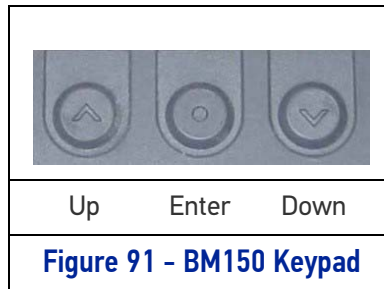
BM150 must be detected through the BM100 backup memory module at power-up/reset and this is done through a command setting in DL.CODE. By connecting the reader to DL.CODE the following parameters can be managed.

In the Device>Settings>Settings>Maintenance window:

- **Enable BM100 Detection**
Checked (Enabled): the BM100 backup memory module will be detected on power-up/reset; therefore the BM150 display module (if present), will also be enabled.
Unchecked (Disabled): the BM100 backup memory module will **not** be detected on power-up/reset; therefore the BM150 display module (if present), will also **not** be enabled.
- **BM150 Display Layout (Master Only)**
Reading Mask Only: the Reading Mask screen is sent to the BM150 display.
Reading Mask/Device State: the Reading Mask/Device State screen is sent to the BM150 display.

Accessing the HMI Interface Through Keypad and Display Menu

Through its keypad and display, the BM150 provides a remote extension of the reader's HMI Interface. The HMI default menu items can be accessed as well as the View menu for Master devices and the Extended menu for Backup and Restore functions.



To enter the Main Menu press the **Up** and **Down** buttons simultaneously.

The menu structure is shown below.

Main Menu

- **[Exit]** (exits HMI Interface menu)
- **Test Mode** (performs Test mode)
- **Focus/Locate** (performs Focus function: turns on LED pointers)
- **Calibration** (performs Setup function)
- **Code Setting** (performs Learn function)
- **Match Code Tra...** (Training: allows to read a code and store it as the Match code)

View Menu (Master Only)

- **[Exit]** (returns to Main menu)
- **Standard** (displays the Standard Reading Results screen during run mode)
- **Reading Mask** (displays the Reading Mask or Reading Mask/Device State screen during run mode) depends on the selection in DL.CODE see par. Configuration Through DL.CODE.
- **Network State** (displays the Network State screen during run mode)

Extended Menu

- **[Exit]** (returns to Main menu)
- **Backup** (performs Backup - uninterruptible)
- **Restore** (performs Restore - uninterruptible)
- **Erase** (erases the backup configuration in external memory - uninterruptible)

To move through the list press and release the **Up** or **Down** key.

To select an item or enter a submenu, press and release the **Enter** key. After executing an HMI function the display shows a result message and then automatically exits from the menu structure.

To exit a menu manually, press and release the **Enter** key at the [Exit] item or press the **Up** and **Down** buttons simultaneously.

To exit from a running HMI function, press the **Up** and **Down** buttons simultaneously. These functions will also exit upon their configured timeout.



NOTE

When the HMI Interface is entered from either the Local Device (reader) or Remote Device (BM150), the key(s) on the other device are disabled.



NOTE

When the reader is connected to DL.CODE, access to the BM150 HMI Interface is disabled.



NOTE

The "Reset Reader to Factory Default Environment" function of the HMI Interface is only available on the local device (reader), and not on the BM150.

Display Messages

The following examples of Remote Display messages are given to help interpret the information reported. The content of these messages depends on the connected reader.

Welcome Message

```
M M M M M M M M M M M M
K K K V V V V V V V V V R R R N N N
S N D D D D D D D D D
E T H A A A . A A A . A A A . A A A
```

M = scanner model

K = software – STD=Standard, SS =Special

V = software version

R = Device Network Type – MUL=Multidata, SYN=Synchronized, ALN=Alone

N = Device Network Setting – M00=ID-NET Network Master, Sxx= ID-NET Network Slave address, Null string= Alone (no network)

D = device serial number

A = Ethernet IP Address

Test Mode Results

```
A A A % Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z
Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z
Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z Z
```

A = reading percentage from 000 to 100%.

Z = code content.

Calibration (Setup) Results

```
E x p = X X X X
G a i n = G G
C a l i b r a t i o n
O K ( p e r m a n e n t )
```

X = exposure value (in μ s).

G = gain value

Code Setting (Learn) Results

```
X X X X X X X X X
C o d e S e t t i n g
O K ( p e r m a n e n t )
```

X = recognized code symbology.

Diagnostic Alarms

Diagnostic error messages are sent to the BM150 display as numeric Alarm Codes (even if Failure Messages are selected for data transmission the numeric Alarm Code is sent to the display).

```

Alert :
Failure # X X X
R R R N N N
    
```

X = numeric Alarm Code (see below for the list of Alarm Codes)
 R = Device Network Type – MUL=Multidata, SYN=Synchronized, ALN=Alone
 N = Device Network Setting – M00=ID-NET Network Master, Sxx= ID-NET Network Slave address, Null string= Alone (no network)

Alarm Code	Description
1	Slave No Reply
64	Slave Address Duplication
171	Protocol Index Failure
185	Backup Memory Communication Failure
187	Wrong Rotary Switch Selection
189	Fieldbus Communication Failure
191	Fieldbus Type Mismatch
193	Fieldbus Configuration Error
195	Fieldbus DHCP Problem
201	No XRF Slave(s) Detected

Slave Node Alarms (Master only)

```

Alert : I D - N E T
Node # X X M i s s i n g
R R R M 0 0
    
```

X = slave node number (1-31)
 R = Device Network Type – MUL=Multidata, SYN=Synchronized

Network State (Master only)

```

0 N e t w o r k 1 5
M S S S S S S S S S S S S S S
1 6 N e t w o r k 3 1
S S S S S S S S S S S S S S S
    
```

M = Master diagnostic condition; S = Slave diagnostic condition:
 * = scanner OK
 - =scanner not detected at startup
 ? =scanner detected at startup but not responding to diagnostic polling
 ! = scanner diagnostic error

Standard Reading Results

```

A A A A A A A A A A A A A
X X X X X X X X X X X X X X X X X X X X
X X X X X X X X X X X X X X X X X X X X
Y Y C o d e s
    
```

A = reading result – Good Read, Partial Read, Multiple Read

X = code content

Y = number of codes read

Reading Mask Only (Master Only)

```

X X X X X X X X X X X X X X X X X X . . .
G Y Y Y % N Y Y Y % M Y Y Y % P Y Y Y %
S S S S S S S S S S S S S S S S
T T T T T T T T T T T T T T T T
    
```

X = code content (or "No Read" or "Multiple Read")

Y = Good Read, No Read, Multiple Read and Partial Read counters on the last 100 codes read (%)

S = Reading Mask for Stand Alone or Master plus Slave readers 1 - 15
(0 = No Read, 1 = Good Read, M = Multiple Read)

T = Reading Mask for Slave readers 16 - 31
(0 = No Read, 1 = Good Read, M = Multiple Read)

Reading Mask/Device State (Master Only)

```

X X X X X X X X X X X X X X X X X X . . .
P = Y Y Y Y Y Y Y Y G R = Z Z Z . Z Z %
S S S S S S S S S S S S S S S S
U U U U U U U U U U U U U U U U
    
```

X = Recognized code label data (or "No Read" or "Multiple Read")

Y = Phase Counter (range: 0000000 to 9999999)

Z = Good Read or Multiple Read counters (%)

S = Reading Mask for Stand Alone or Master plus Slave readers 1 - 15
(0 = No Read, 1 = Good Read, M = Multiple Read)

U = Diagnostic condition for Stand Alone or Master plus Slave readers 1 - 15:
 * = reader OK
 - = reader not detected at startup
 ? = reader detected at startup but not responding to diagnostic polling
 ! = reader diagnostic error

BM150 Backup and Restore Procedure

The Backup and Restore functions are valid for any application layout type (point-to-point, network, etc.) using CBX500 connection boxes through the BM100 Backup module (required accessory for BM150 installation).

The Backup and Restore functions are managed through the BM150 display and keypad and therefore are disabled at the BM100 Backup/Restore button.

If it ever becomes necessary to replace the reading device, it can be quickly configured through the restore procedure.

BM150 provides complete backup and restore functions (Configuration and Environmental parameters) with the following difference:

For Single Readers or individual ID-NET Slaves:

- Backup and Restore functions provide parameter storage including all configuration jobs present on the reader.

For Master Readers in ID-NET Master/Slave networks:

- Backup and Restore functions provide parameter storage of only the Startup Configuration for the Master and all Slaves present in the network.



For Master/Slave networks any other configurations (jobs) stored in the device memory will not be backed up. Therefore upon a restore, all jobs other than the startup configuration will be overwritten (erased). It is strongly recommended to save all configurations to backup files.

The Slaves must always be configured with the same network baudrate as the Master for correct functioning including performing Backup and Restore procedures.

Backup and Restore functions cannot be interrupted once started.

To perform *Backup*

1. Make sure the Write Protection switch on the BM100 is unlocked.
2. Select the **Backup** item from the Extended menu and press the Enter key.
3. When the procedure is complete a message appears on the display showing the results (**Backup OK 1 File Saved** or an error message).
4. Set the Write Protection switch to locked.

To perform *Restore*

1. Select the **Restore** item from the Extended menu and press the Enter key.
2. When the procedure is complete a message appears on the display showing the results (**Restore OK 1 File Restored** or an error message).

CHAPTER 8

MAINTENANCE

CLEANING

Clean the lens cover periodically for continued correct operation of the reader. See "General View" on page xiii.

Dust, dirt, etc. on the lens cover may alter the reading performance.

Repeat the operation frequently in particularly dirty environments.

Use soft material and alcohol to clean the lens cover and avoid any abrasive substances.

CHAPTER 9

TROUBLESHOOTING

GENERAL GUIDELINES

- When wiring the device, pay careful attention to the signal name (acronym) on the CBX100/500 spring clamp connectors (Chapter 4, CBX Electrical Connections). If you are connecting directly to the Matrix 210N M12 17-pin connector, pay attention to the pin number of the signals (Appendix B,).
- If you need information about a certain reader parameter you can refer to the DL.CODE help on line. Connect the device and click on the link to the parameter you're interested in.
- If you're unable to fix the problem and you're going to contact your local Datalogic office or Datalogic Partner or ARC, we suggest providing (if possible): Application Program version, Parameter Configuration file, Serial Number and Order Number of your reader. You can get most of this information while DL.CODE is connected to the reader.

Troubleshooting Guide	
Problem	Suggestion
DL.CODE Installation: Autorun or Start.hta doesn't run	Check Windows settings to see if Autorun is disabled. Associate the file type .hta with the Microsoft HTML Application host mshsa.exe in Windows\System32.
Power ON: the "POWER" LED is not lit.	Is power connected? If using a power adapter (like PG6000), is it connected to wall outlet? If using rail power, does rail have power? If using CBX, does it have power (check switch and LED)? Check if you are referring to the 25-pin connector or to the CBX spring clamp connectors. Measure Voltage either at pin 13 and pin 25 (for 25-pin connector) or at spring clamp Vdc and GND (for CBX).

Troubleshooting Guide	
Problem	Suggestion
<p>One Shot or Phase Mode using the Input 1 (External Trigger) or Input 2: the "TRIGGER" LED is not blinking while the External Trigger is switching.</p>	<p>Check if you are referring to the 25-pin connector or to the CBX spring clamp connectors.</p> <p>Is the sensor connected to Input 1 or Input 2?</p> <p>Is power supplied to the photo sensor?</p> <p>For NPN configuration, is power supplied to one of the two I1 or I2 signals (A or B)?</p> <p>For PNP configuration, is one of the two I1 or I2 signals grounded (A or B)?</p> <p>Are the photo sensor LEDS (if any) working correctly?</p> <p>Is the sensor/reflector system aligned (if present)?</p> <p>On the Reading Phase step check the Input 1 or Input 2 <i>Debounce Filter</i> parameter setting.</p> <p>On the Reading Phase step check the settings for <i>Acquisition Trigger</i>, <i>Reading Phase-ON</i>, and <i>Reading Phase-OFF</i> parameters.</p>
<p>One Shot or Phase Mode using serial trigger source: the "TRIGGER" LED is not blinking.</p>	<p>On the Reading Phase step check the settings for <i>Acquisition Trigger</i>, <i>Reading Phase-ON</i>, and <i>Reading Phase-OFF</i> parameters.</p> <p>Are the COM port parameters (<i>Baud Rate</i>, <i>Parity</i>, <i>Data Bits</i>, <i>Stop Bits</i>) correctly assigned?</p> <p>On the Reading Phase step check the settings of <i>Acquisition Trigger String</i>, <i>Reading Phase-ON String</i>, and <i>Reading Phase-OFF String</i> parameters.</p> <p>Is the serial trigger source correctly connected?</p>
<p>Phase Mode: the "TRIGGER" LED is correctly blinking but no image is displayed in the DL.CODE window.</p>	<p>Is the Phase frequency lower than the maximum frame rate?</p>
<p>Continuous Mode: the "TRIGGER" LED is not blinking.</p>	<p>Verify the correct software configuration settings.</p>
<p>Any Operating Mode: the "TRIGGER" LED is correctly blinking but no result is transmitted by the reader at the end of the reading phase collection.</p>	<p>Check the Code Collection parameters on the Reading Phase step and the Data Formatting parameters on the Data Formatting step.</p>
<p>Image not clear:</p>	<p>verify the Focus procedure</p>
<p>Image focused but not decoded:</p>	<p>verify the Calibrate Image Density procedure.</p>

Troubleshooting Guide	
Problem	Suggestion
<p>Reading: the reader always transmits the <i>No Read Message</i></p>	<p>Run the Rapid Configuration procedure in Chapter 1, Rapid Configuration.</p> <p>Position the reader as described in "Mounting And Positioning Matrix 210N" on page 59 and through DL.CODE:</p> <p>Tune the Acquisition Delay on Trigger, if the moving code is out of the reader field of view;</p> <p>Set the Continuous Operating Mode if no external trigger source is available;</p> <p>Tune the Image Settings to improve the code image quality;</p> <p>Check the parameter settings in the Advanced Setup step: 2D Codes, 1D Codes, and Postal Codes;</p> <p>View the full resolution code image to check the printing or marking quality.</p>
<p>Communication: reader is not transmitting anything to the host.</p>	<p>Is the serial cable wiring correct?</p> <p>If using CBX, be sure the RS422 termination switch is OFF.</p> <p>Are the host serial port settings the same as the reader serial port settings?</p> <p>In DL.CODE Device menu > Settings > Settings > LED Configuration, the COM LED Function can be configured to indicate Main Serial Port TX or Main Serial Port RX.</p>
<p>Communication: data transferred to the host are incorrect, corrupted or incomplete.</p>	<p>Are the host serial port settings the same as the reader serial port settings?</p> <p>In the DL.CODE Data Formatting step check the settings of Header and Terminator String parameters.</p> <p>In the DL.CODE Data Formatting step, check the various Message Field parameter settings.</p>
<p>Configuration: cannot access environment parameters in DL.CODE (Device>Settings>Settings menu item is grey)</p>	<p>Are you using the Installer - Expert User level? If not change it in the Options>Change User menu.</p>
<p>How do I obtain my reader Serial Number?</p>	<p>The reader Serial Number consists of 9 characters: one letter, 2 numbers, another letter followed by 5 numbers.</p> <p>The reader Serial Number is printed on a label that is affixed to the case or connector block of the reader.</p> <p>The Serial Number is also visible from the DL.CODE Device List Area.</p>
<p>How do I obtain my reader Order Number?</p>	<p>The reader Order Number consists of 9 numbers.</p> <p>The reader Order Number can be obtained by comparing the Device Model (in DL.CODE Device Menu > Settings > Settings > About Device) with the product models page on the Datalogic website.</p>

APPENDIX A

TECHNICAL FEATURES

ELECTRICAL FEATURES			
	Matrix 210N Serial	Matrix 210N Ethernet	Matrix 210N USB
Power			
Supply Voltage	10 to 30 Vdc	10 to 30 Vdc	5 Vdc
Consumption	0.35 - 0.13 A, 3.9 W max.; 0.16 A @ 24 V	0.4 to 0.15 A, 4.5 W max.; 0.18 A @ 24 V	0.5A, 2.5 W max.
Communication Interfaces			
Main: RS232, RS422 Full-duplex	2400 to 115200 bit/s	2400 to 115200 bit/s	USB 2.0 up to 921600 bit/s
Auxiliary: RS232	2400 to 115200 bit/s	2400 to 115200 bit/s	
ID-NET	Up to 1 Mbaud	Up to 1 Mbaud	
Ethernet (Built-in) ^a		10/100 Mbit/s	
Inputs			
Input 1 (External Trigger) and Input 2	Opto-isolated and polarity insensitive	Opto-isolated and polarity insensitive	
Max. Voltage	30 Vdc	30 Vdc	
Max. Input Current	10 mA	10 mA	
Outputs^b			
Output 1 and Output 2	Opto-coupled	Opto-coupled	
V _{OUT} (I _{LOAD} = 0 mA) Max.	30 Vdc	30 Vdc	
V _{OUT} (I _{LOAD} = 100 mA) Max.	1.8 Vdc	1.8 Vdc	
I _{LOAD} Max.	170 mA	170 mA	

- a. For Ethernet models only. Supported application protocols: TCP/IP, Ethernet/IP, PROFINET-IO, Modbus TCP
- b. When connected to the CBX connection boxes the electrical features for Output 1 and 2 become the following:
 Opto-isolated; V_{CE} = 30 Vdc max.; I_{CE} = 40 mA continuous max.; 130 mA pulsed max.;
 V_{CE saturation} = 1 Vdc max. @ 10 mA; P_D = 90 mW Max. @ 50 °C ambient temp.

OPTICAL FEATURES	
Image Sensor	CMOS sensor with Global Shutter
Image Format	WVGA (752x480)
Frame Rate	up to 60 frames/s @ full window size
Pitch	± 35°
Tilt	0° - 360°
Lighting System	Internal LED Illuminator to EN 62471
Aiming System	Blue Ring; for liquid lens models only: Laser Pointers IEC 60825-1 2007
*See Chapter 6, Reading Features for other optical features	

ENVIRONMENTAL FEATURES	
Operating Temperature ^a	0 to 50 °C (32 to 122 °F) for liquid lens models only: 0 to 45 °C (32 to 113 °F)
Storage Temperature	-20 to 70 °C (-4 to 158 °F)
Max. Humidity	90% non condensing
Vibration Resistance EN 60068-2-6	14 mm @ 2 to 10 Hz; 1.5 mm @ 13 to 55 Hz; 2 g @ 70 to 500 Hz; 2 hours on each axis
Bump Resistance EN 60068-2-29	30g; 6 ms; 5000 shocks on each axis
Shock Resistance EN 60068-2-27	30g; 11 ms; 3 shocks on each axis
Protection Class ^b EN 60529	IP65

- a. High ambient temperature applications should use metal mounting bracket for heat dissipation.
- b. IP54 for ESD models.

PHYSICAL FEATURES			
Dimensions	50 x 25 x 45 mm (2 x 1 x 1.8 in)	54 x 32 x 45 mm (2.1 x 1.3 x 1.8 in)	61 x 25 x 45 mm (2.4 x 1 x 1.8 in)
Weight (with cable)	204 g (7.2 oz)	190 g (6.7 oz)	237 g (8.4 oz)
Material	ZAMA	Aluminum	ZAMA / Nickel finish
Output cable length	1000 ± 15 mm (39.4 ± 0.6 in)		

SOFTWARE FEATURES

Readable Code Symbolologies

1D and Stacked	2D	Postal
PDF417 Standard and Micro PDF417 Code 128 (GS1-128) Code 39 (Standard and Full ASCII) Code 32 MSI Standard 2 of 5 Matrix 2 of 5 Interleaved 2 of 5 Codabar Code 93 Pharmacode EAN-8/13 - UPC-A/E (including Addon 2 and Addon 5) GS1 DataBar Family Composite Symbolologies	Data Matrix ECC 200 (Standard, GS1 and Direct Marking) QR Code (Standard and Direct Marking) Micro QR Code MAXICODE Aztec Code	Australia Post Royal Mail 4 State Customer Kix Code Japan Post PLANET POSTNET POSTNET (+BB) Intelligent Mail Swedish Post
Operating Mode	Continuous, One Shot, Phase Mode	
Configuration Methods	<ul style="list-style-type: none"> • X-PRESS Human Machine Interface • Windows-based SW (DL.CODE) via Ethernet or Serial interface • Host Mode Programming sequences sent over Serial or Ethernet TCP interfaces 	
Parameter Storage	Permanent memory (Flash)	

CODE QUALITY METRICS

Standard	Supported Symbolologies
ISO/IEC 16022	Data Matrix ECC 200
ISO/IEC 18004	QR Code
AIM DPM	Data Matrix ECC 200, QR Code
ISO/IEC 15416	Code 128, Code 39, Interleaved 2 of 5, Codabar, Code 93, EAN-8/13, UPC-A/E

USER INTERFACE

LED Indicators	Power, Ready, Good, Trigger, Com, Status, (Ethernet Network), (Green Spot)
Keypad Button	Configurable via DL.CODE
Beeper	Configurable via DL.CODE

APPENDIX B

ALTERNATIVE CONNECTIONS

The connector pinouts and notes given in this appendix are for custom cabling applications.

POWER, COM AND I/O CONNECTOR

The Matrix 210N reader is equipped with an 25-pin male D-sub connector for connection to the power supply, serial interfaces, and input/output signals. The details of the connector pins are indicated in the following table:

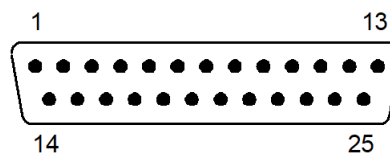


Figure 1 - 25-pin male D-sub Connector

POWER, COM AND I/O CONNECTOR PINOUT		
PIN	NAME	DESCRIPTION
13, 9	Vdc	Power supply input voltage +
25, 7	GND	Power supply input voltage -
1	CHASSIS	Cable shield connected to chassis
18	I1A	External Trigger A (polarity insensitive)
19	I1B	External Trigger B (polarity insensitive)
6	I2A	Input 2 A (polarity insensitive)
10	I2B	Input 2 B (polarity insensitive)
8	O1+	Output 1 +
22	O1-	Output 1 -
11	O2+	Output 2 +
12	O2-	Output 2 -
20	RX	Auxiliary RS232 RX
21	TX	Auxiliary RS232 TX
23	ID+	ID-NET network data +
24	ID-	ID-NET network data -
14, 15, 16,17	NC	Not Connected

POWER, COM AND I/O CONNECTOR PINOUT			
PIN	NAME	DESCRIPTION	
		RS232	RS422 Full-Duplex
2	Main Interface (SW Selectable)	TX	TX+
3		RX	*RX+
4		-	TX-
5		-	*RX-

* Do not leave floating, see "RS422 Full Duplex Interface" on page 65 for connection details.

In order to meet EMC requirements:

- connect the reader chassis to the plant earth ground by means of a flat copper braid shorter than 100 mm;
- for direct connections, connect the main interface cable shield to pin 1 of the 25-pin connector.

ON-BOARD ETHERNET CONNECTOR

A Standard M12 D-Coded female connector is provided for the on-board Ethernet connection. This interface is IEEE 802.3 10 BaseT and IEEE 802.3u 100 BaseTx compliant.

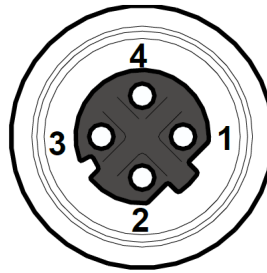


Figure 2 - M12 X-Coded Female Ethernet Network Connector

ON-BOARD ETHERNET NETWORK CONNECTOR PINOUT			
PIN	NAME	DESCRIPTION	
1	TX+	Transmit data +	
2	RX+	Received data +	
3	TX-	Transmit data -	
4	RX-	Received data -	

ID-NET NETWORK TERMINATION

The network must be properly terminated by a 120 Ohm resistor at the first and last reader of the network.

INPUTS

There are two opto-coupled polarity insensitive inputs available on the 25-pin connector of the reader: Input 1 (External Trigger) and Input 2, a generic input. See "Inputs" on page 73 for more details.

The electrical features of both inputs are:

$$V_{AB} = 30 \text{ Vdc max.}$$

$$I_{IN} = 10 \text{ mA max.}$$

The relative pins on the M12 17-pin connector are:

INPUT PINOUT		
PIN	NAME	DESCRIPTION
9	Vdc	Power Supply input voltage +
18	I1A	External Trigger A (polarity insensitive)
19	I1B	External Trigger B (polarity insensitive)
6	I2A	Input 2 A (polarity insensitive)
10	I2B	Input 2 B (polarity insensitive)
7	GND	Power Supply input voltage -

OUTPUTS

Two general purpose outputs are available on the 25-pin connector. See "Outputs" on page 79 for more details.

The pinout is the following:

OUTPUT PINOUT		
PIN	NAME	DESCRIPTION
9	Vdc	Power Supply input voltage +
8	O1+	Configurable digital output 1 - positive pin
22	O1-	Configurable digital output 1 - negative pin
11	O2+	Configurable digital output 2 - positive pin
12	O2-	Configurable digital output 2 - negative pin
7	GND	Power supply input voltage -

The electrical features of the two outputs are the following:

Reverse-Polarity and Short-Circuit Protected

$$V_{OUT} (I_{LOAD} = 0 \text{ mA}) \text{ max} = 30 \text{ Vdc}$$

$$V_{OUT} (I_{LOAD} = 10 \text{ mA}) \text{ max} = 1.8 \text{ Vdc}$$

$$I_{LOAD} \text{ max} = 40 \text{ mA continuous; } 130 \text{ mA pulsed}$$

$$P_D = V_{OUT} \text{ max} * I_{LOAD} = 170 \text{ mW}$$

The output signals are fully programmable being determined by the configured Activation/Deactivation events, Deactivation Timeout or a combination of the two. For further details refer to the Help On Line page for the Output Setup step in DL.CODE.

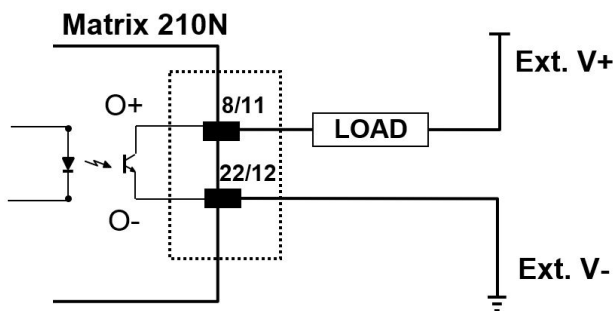


Figure 3 - Isolated Current Sinking Output Connection

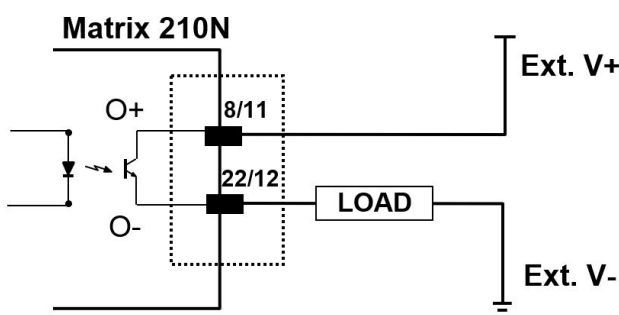


Figure 4 - Isolated Current Sourcing Output Connection

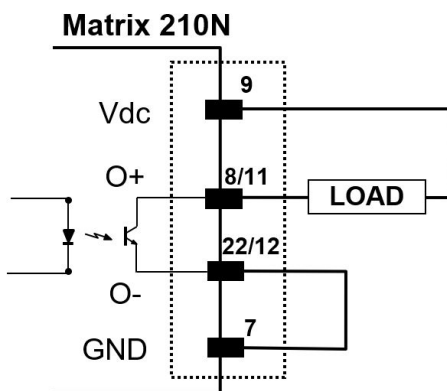


Figure 5 - Non-Isolated Current Sinking Output Connection

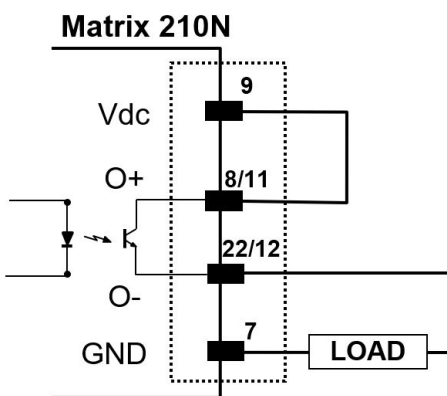
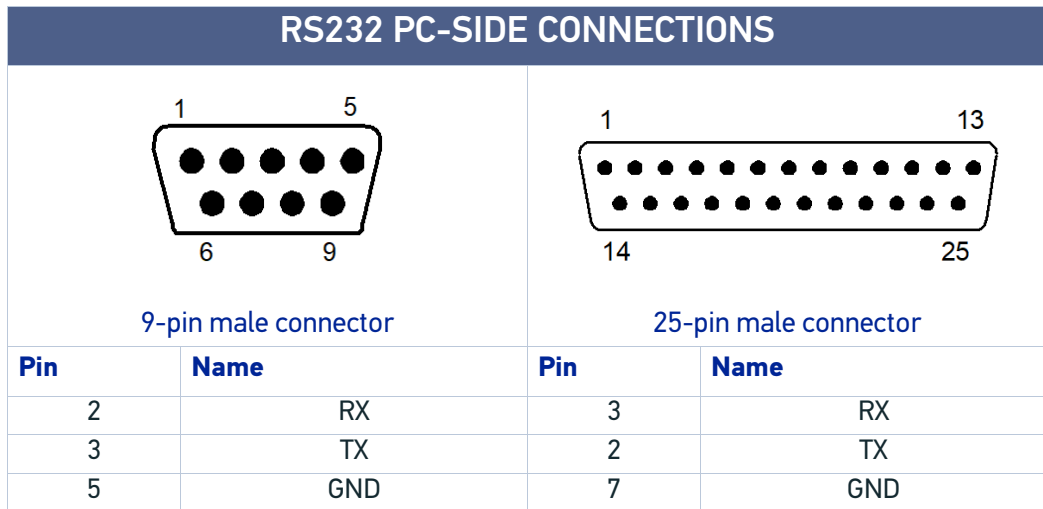


Figure 6 - Non-Isolated Current Sourcing Output Connection

USER INTERFACE - SERIAL HOST



How To Build A Simple Interface Test Cable

The following wiring diagram shows a simple test cable including power, external (push-button) trigger and PC RS232 COM port connections.

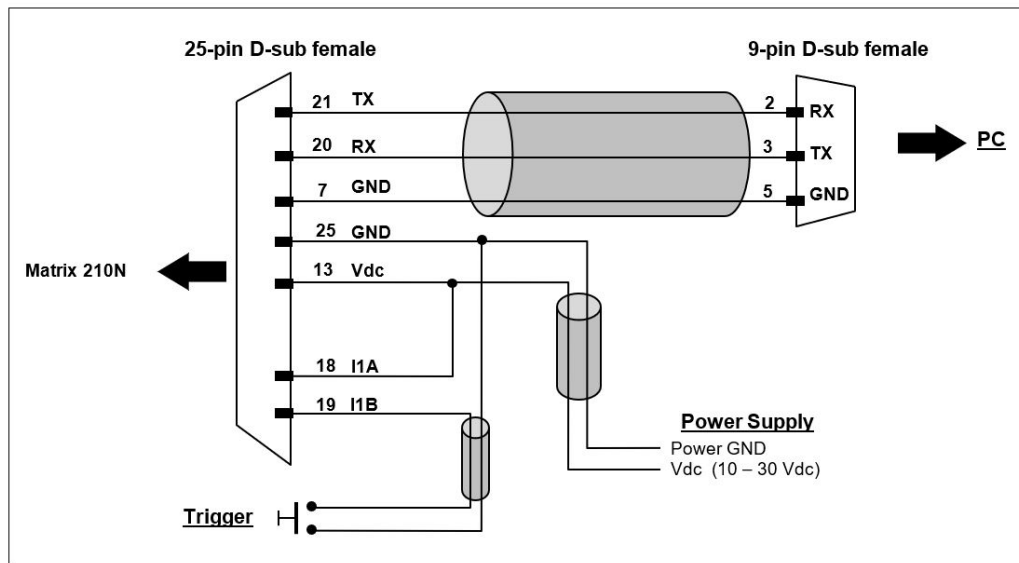


Figure 7 - Test Cable for Matrix 210N

GLOSSARY

AIM

(Association for Automatic Identification and Mobility): AIM Global is the international trade association representing automatic identification and mobility technology solution providers.

AIM DPM Quality Guideline

Standard applicable to the symbol quality assessment of direct part marking (DPM) performed in using two-dimensional bar code symbols. It defines modifications to the measurement and grading of several symbol quality parameters.

Barcodes (1D Codes)

A pattern of variable-width bars and spaces which represents numeric or alphanumeric data in machine-readable form. The general format of a barcode symbol consists of a leading margin, start character, data or message character, check character (if any), stop character, and trailing margin. Within this framework, each recognizable symbology uses its own unique format.

BIOS

Basic Input Output System. A collection of ROM-based code with a standard API used to interface with standard PC hardware.

Bit

Binary digit. One bit is the basic unit of binary information. Generally, eight consecutive bits compose one byte of data. The pattern of 0 and 1 values within the byte determines its meaning.

Bits per Second (bps)

Number of bits transmitted or received per second.

Byte

On an addressable boundary, eight adjacent binary digits (0 and 1) combined in a pattern to represent a specific character or numeric value. Bits are numbered from the right, 0 through 7, with bit 0 the low-order bit. One byte in memory can be used to store one ASCII character.

Composite Symbologies

Consist of a linear component, which encodes the item's primary data, and an adjacent 2D composite component, which encodes supplementary data to the linear component.

Dark Field Illumination

Lighting of surfaces at wide angles used to avoid direct reflection of the light into the reader's lens. Typically this type of lighting is used in DPM solutions to enhance reflectance of the uneven surface do to the symbol marking technique. It is also used with very reflective surfaces.

Decode

To recognize a barcode symbology (*e.g.*, Codabar, Code 128, Code 3 of 9, UPC/EAN, etc.) and analyze the content of the barcode scanned.

Depth of Field

The difference between the minimum and the maximum distance of the object in the field of view that appears to be in focus.

Diffused Illumination

Distributed soft lighting from a wide variety of angles used to eliminate shadows and direct reflection effects from highly reflective surfaces.

Direct Part Mark (DPM)

A symbol marked on an object using specific techniques like dot peening, laser etching, chemical etching, etc.

EEPROM

Electrically Erasable Programmable Read-Only Memory. An on-board non-volatile memory chip.

Element

The basic unit of data encoding in a 1D or 2D symbol. A single bar, space, cell, dot.

Exposure Time

For digital cameras based on image sensors equipped with an electronic shutter, it defines the time during which the image will be exposed to the sensor to be acquired.

Flash

Non-volatile memory for storing application and configuration files.

Host

A computer that serves other terminals in a network, providing services such as network control, database access, special programs, supervisory programs, or programming languages.

Image Processing

Any form of information processing for which the input is an image and the output is for instance a set of features of the image.

Image Resolution

The number of rows and columns of pixels in an image. The total number of pixels of an image sensor.

Image Sensor

Device converting a visual image to an electric signal. It is usually an array of CCD (Charge Coupled Devices) or CMOS (Complementary Metal Oxide Semiconductor) pixel sensors.

IEC

(International Electrotechnical Commission): Global organization that publishes international standards for electrical, electronic, and other technologies.

IP Address

The terminal's network address. Networks use IP addresses to determine where to send data that is being transmitted over a network. An IP address is a 32-bit number referred

to as a series of 8-bit numbers in decimal dot notation (e.g., 130.24.34.03). The highest 8-bit number you can use is 254.

ISO

(International Organization for Standardization): A network of the national standards institutes of several countries producing world-wide industrial and commercial standards.

LED (Light Emitting Diode)

A low power electronic light source commonly used as an indicator light. It uses less power than an incandescent light bulb but more than a Liquid Crystal Display (LCD).

LED Illuminator

LED technology used as an extended lighting source in which extra optics added to the chip allow it to emit a complex radiated light pattern.

Matrix Symbologies (2D Codes)

An arrangement of regular polygon shaped cells where the center-to-center distance of adjacent elements is uniform. Matrix symbols may include recognition patterns which do not follow the same rules as the other elements within the symbol.

Multi-row (or Stacked) Symbologies

Symbologies where a long symbol is broken into sections and stacked one upon another similar to sentences in a paragraph.

RAM

Random Access Memory. Data in RAM can be accessed in random order, and quickly written and read.

Symbol Verification

The act of processing a code to determine whether or not it meets specific requirements.

Transmission Control Protocol/Internet Protocol (TCP/IP)

A suite of standard network protocols that were originally used in UNIX environments but are now used in many others. The TCP governs sequenced data; the IP governs packet forwarding. TCP/IP is the primary protocol that defines the Internet.

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