

# Math155: Calculus for Biological Scientists Analysis of Discrete-Time Dynamical Systems

David Eklund

Colorado State University

August 26, 2012

# Cobwebbing: A graphical solution technique

Consider a discrete-time dynamical system with updating function  $f$ :

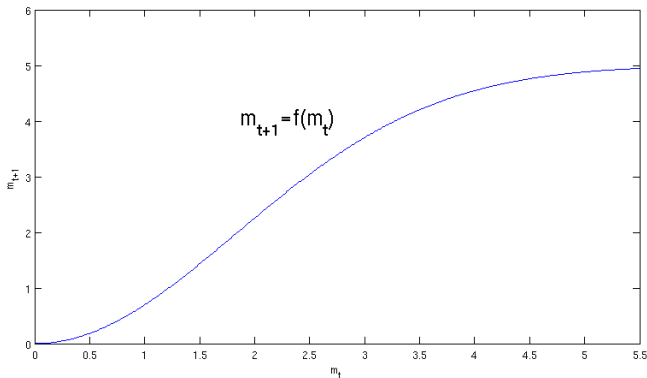
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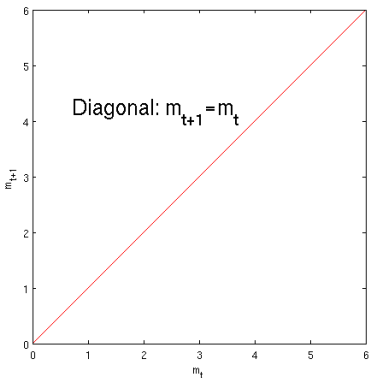
$$m_{t+1} = f(m_t).$$

For example, the graph of  $f$  might look like this:



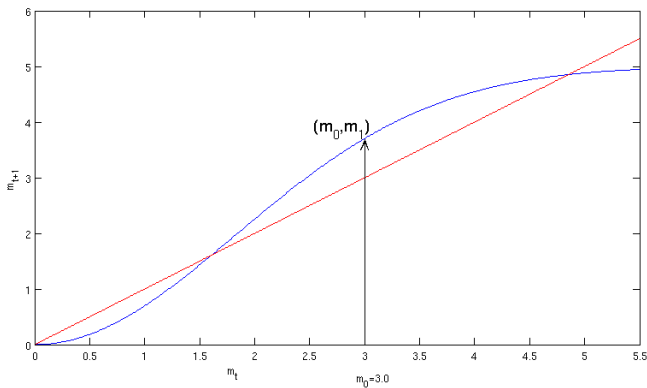
# Cobwebbing: A graphical solution technique

The diagonal is the line below defined by  $m_{t+1} = m_t$ :



# Cobwebbing: A graphical solution technique

Note that the point  $(m_0, m_1)$  lies on the graph of  $f$ ,  
 $m_1 = f(m_0)$ . For example, if  $m_0 = 3.0$ :



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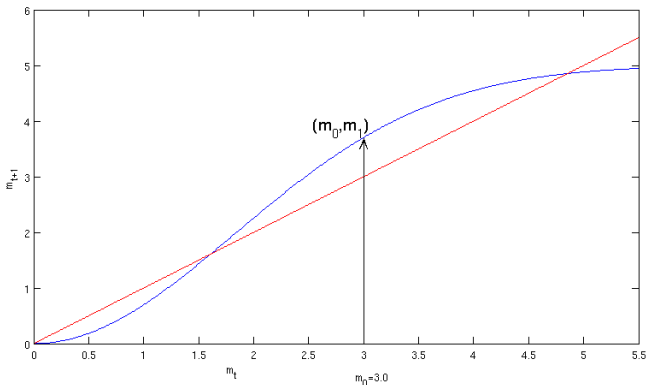
Cobwebbing step 1: find  $(m_0, m_1)$ .

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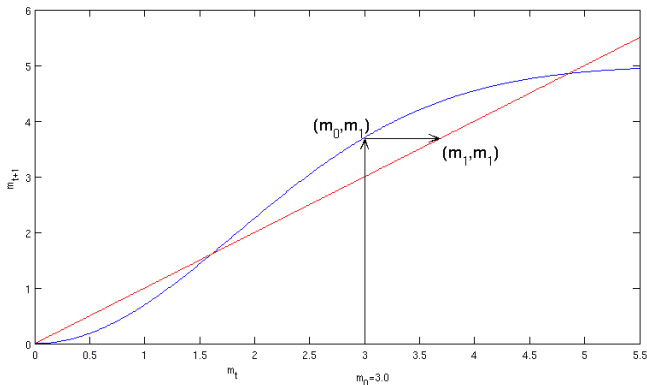
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Cobwebbing step 1: find  $(m_0, m_1)$ . For  $m_0 = 3.0$ :



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Step 2: move horizontally to the diagonal, ending at  $(m_1, m_1)$ .



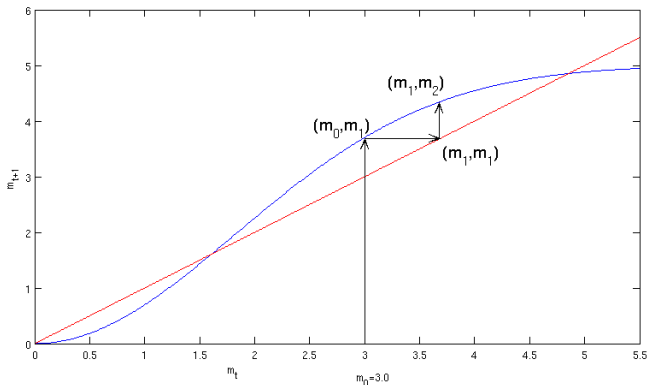


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Step 3: move vertically to  $(m_1, m_2)$  on the graph of  $f$ .

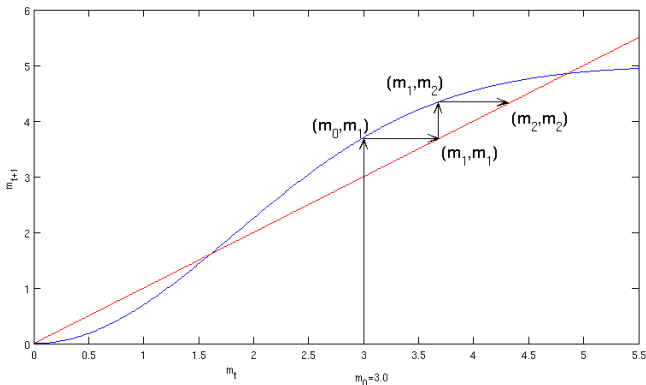


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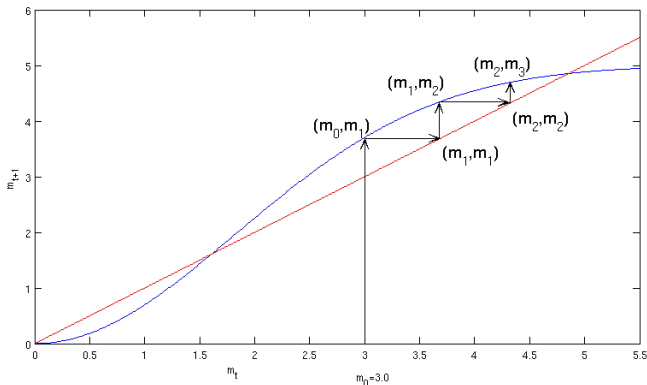
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Move horizontally to the diagonal again: move to  $(m_2, m_2)$ .



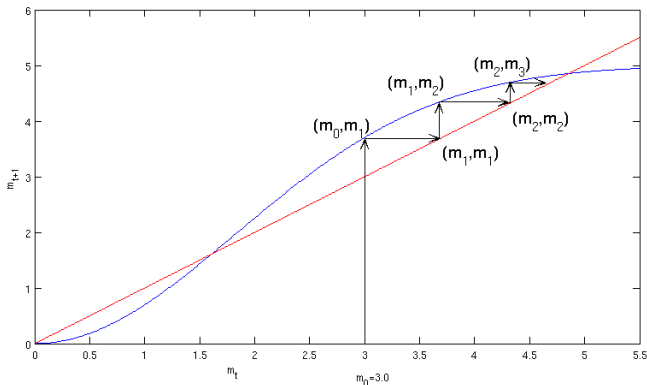
# Cobwebbing: A graphical solution technique

And so on...move vertically to  $(m_2, m_3)$ .



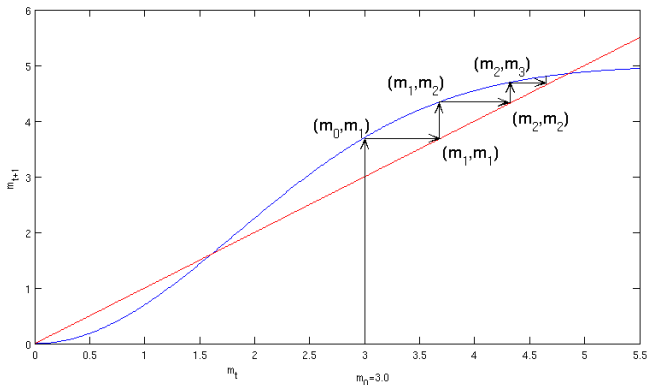
# Cobwebbing: A graphical solution technique

Move horizontally to  $(m_3, m_3)$ .



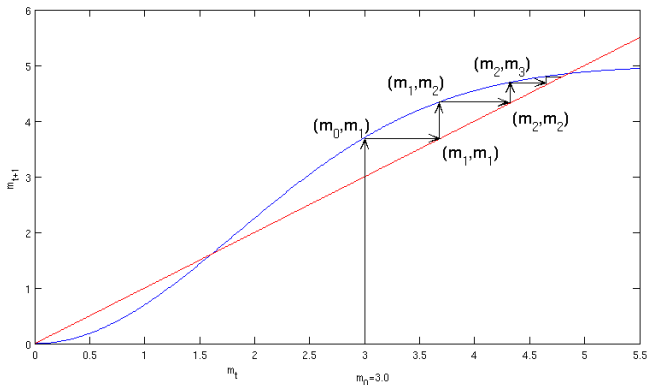
# Cobwebbing: A graphical solution technique

Move vertically to  $(m_3, m_4)$ .



# Cobwebbing: A graphical solution technique

Move horizontally to  $(m_4, m_4)$



# Cobwebbing: A graphical solution technique

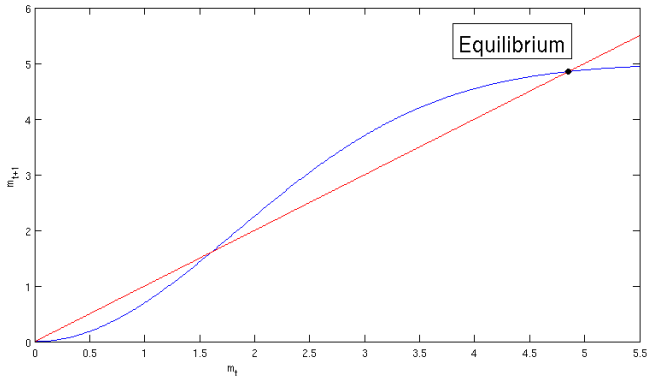
We approach a point where the graph of  $f$  intersects the diagonal, that is where  $f(m_t) = m_t$ . This is called an **equilibrium**.

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$$m_{t+1} = f(m_t) = m_t,$$

hence  $m_{t+1} = m_t$  and the measured quantity does not change!

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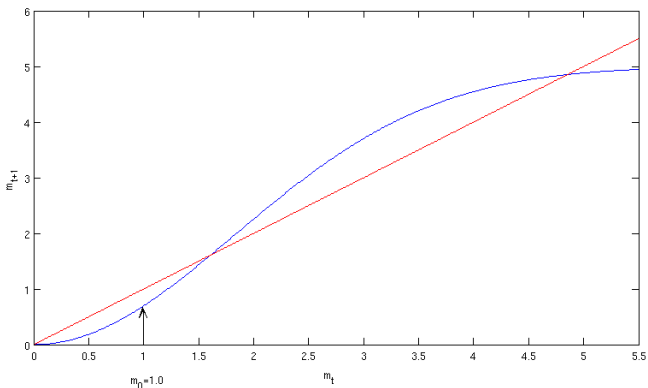
- Physical systems often tend toward some equilibrium over time.

# Cobwebbing: A graphical solution technique

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What happens if we start at  $m_0 = 1.0$ ?

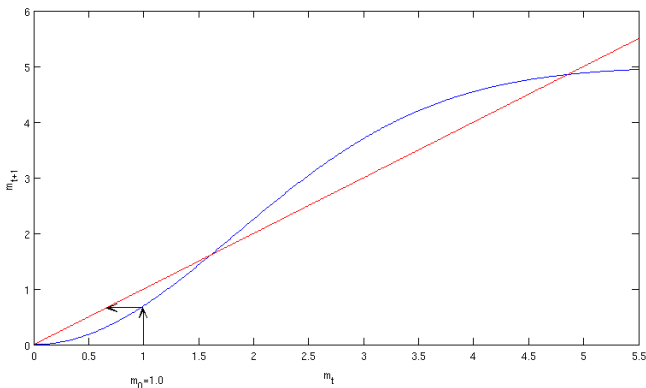


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Cobweb as before. First move horizontally to the diagonal.

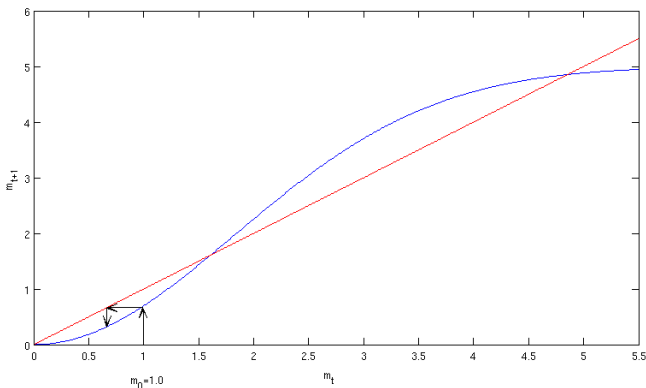


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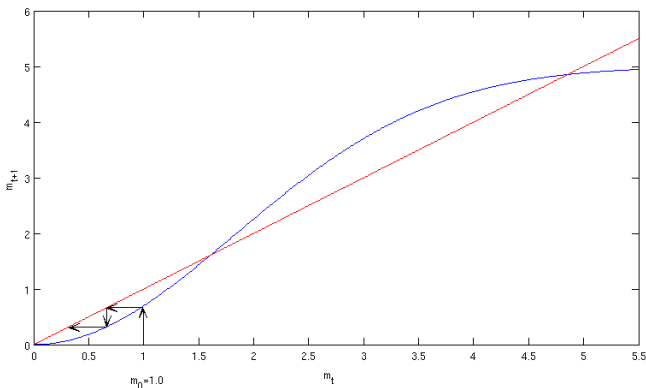


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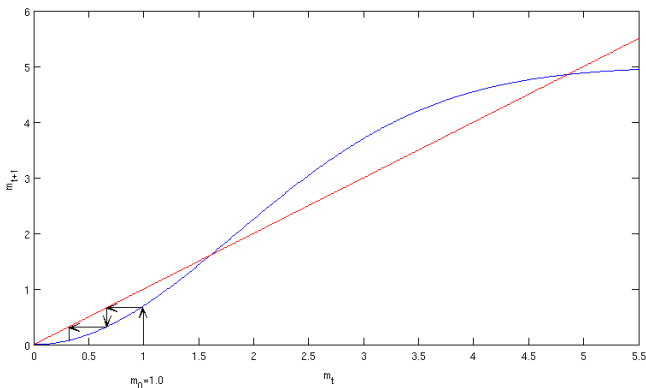


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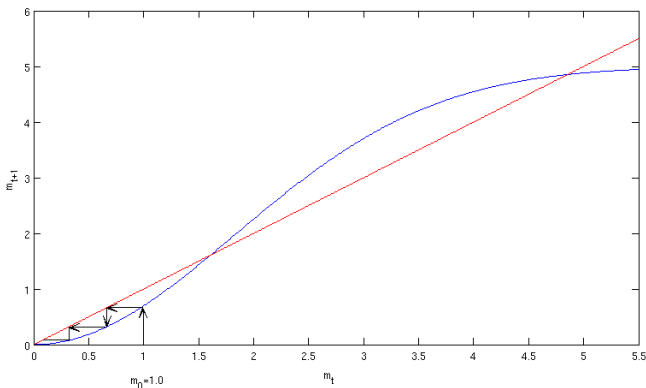


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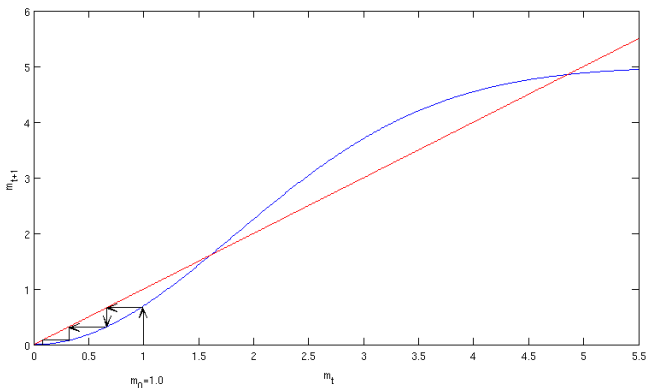


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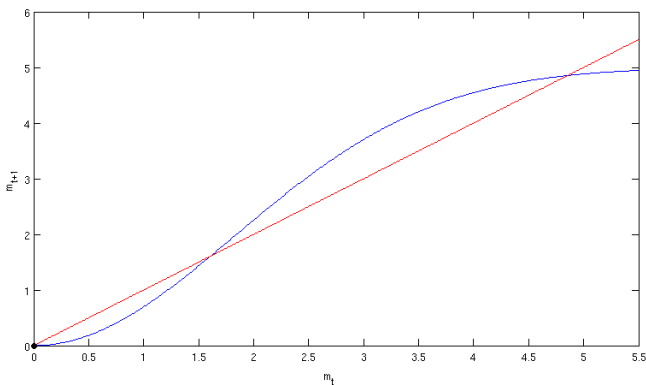
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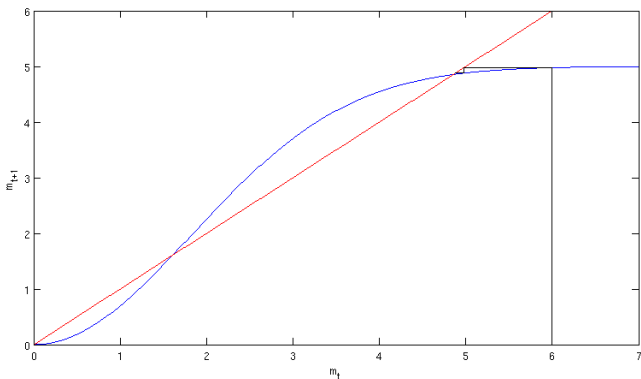
If we start at  $m_0 = 6.0$ , we approach the same equilibrium as before, when we started at  $m_0 = 3.0$ .

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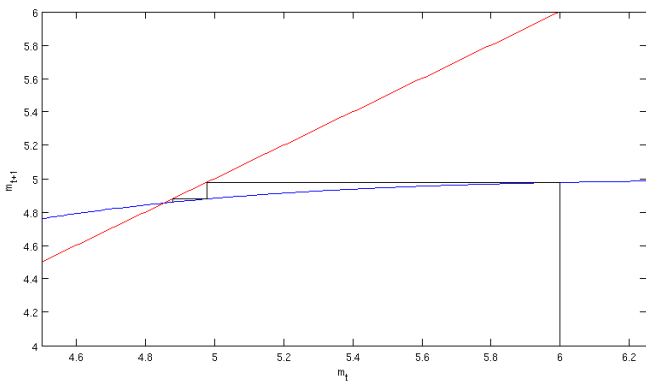


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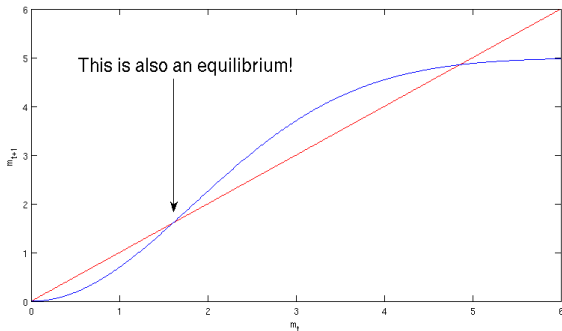
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If we start at  $m_0 = 6.0$ , we approach the same equilibrium as before. Zooming in:



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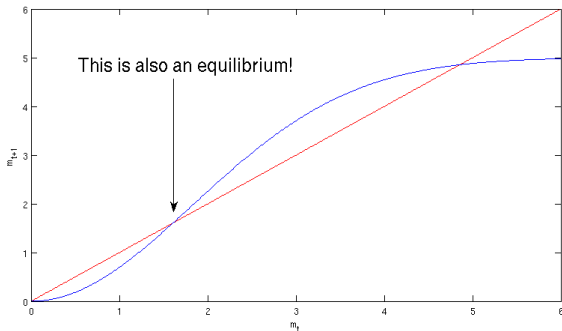
The equilibrium in the middle is special. If we start there we never leave, but if we merely start close to it then we move away from it!





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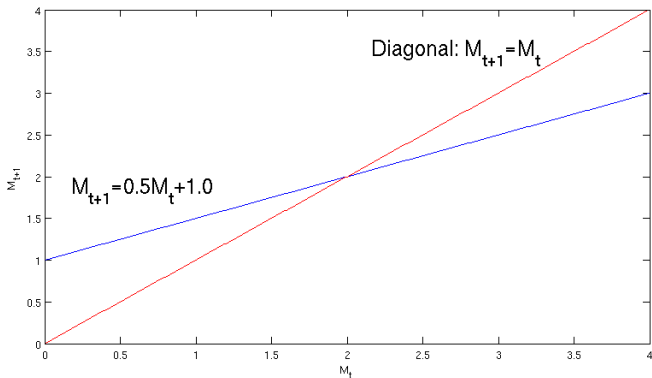
The middle equilibrium is called **unstable**, and the other two are called **stable**.

# Examples

Example 1: Consider the medication dynamics from a previous lecture. Let  $M_t$  denote the concentration (in mg/l) of medication in a persons bloodstream and suppose this concentration is measured every day and that the updating function is  $M_{t+1} = 0.5M_t + 1.0$ .

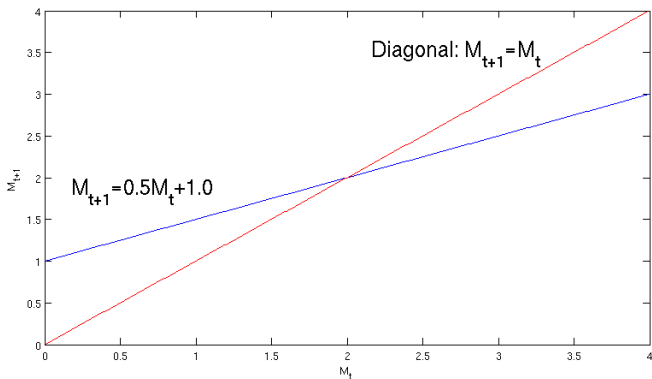
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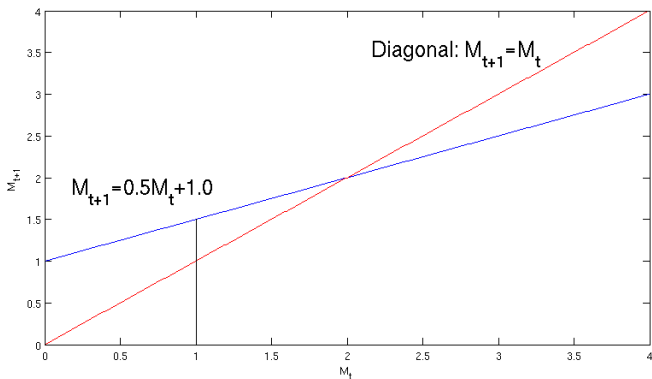
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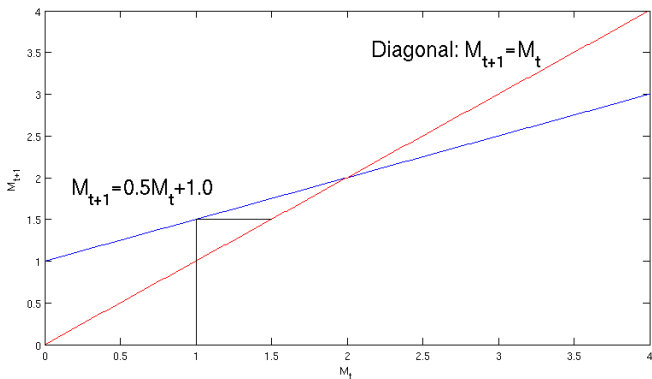
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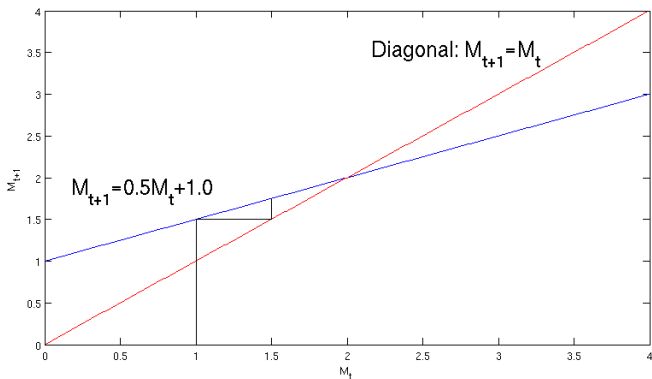
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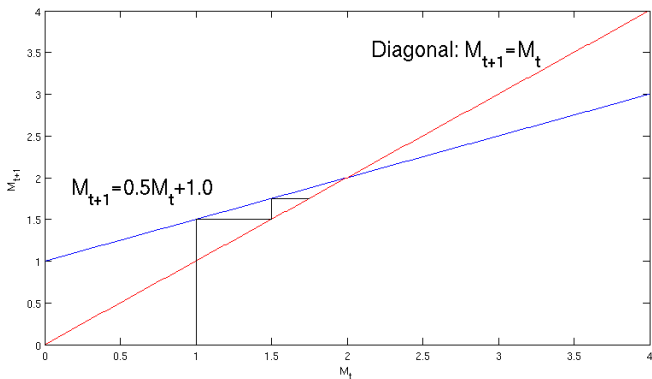
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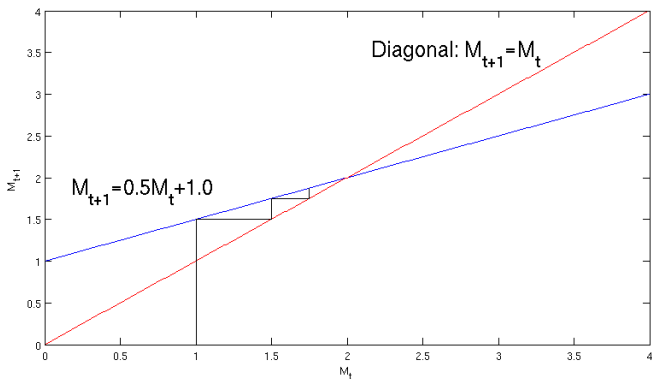
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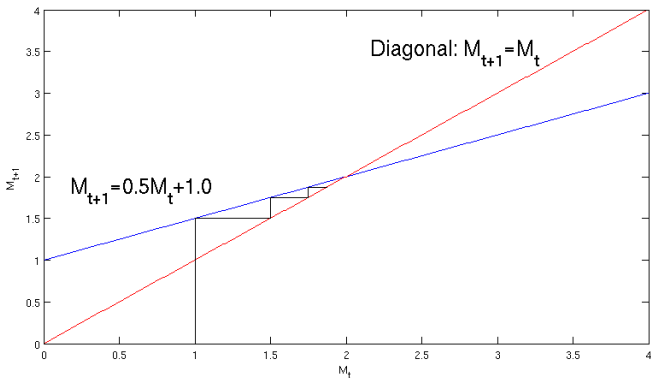
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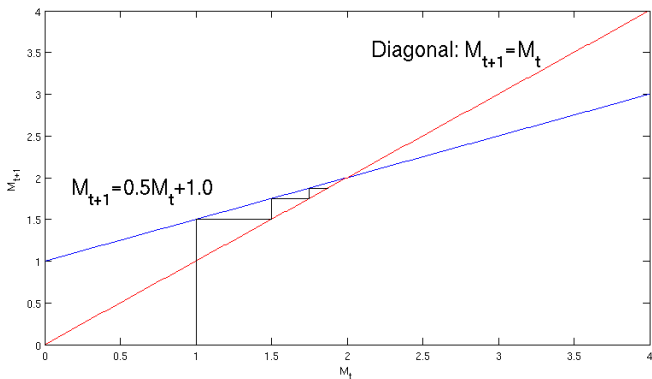
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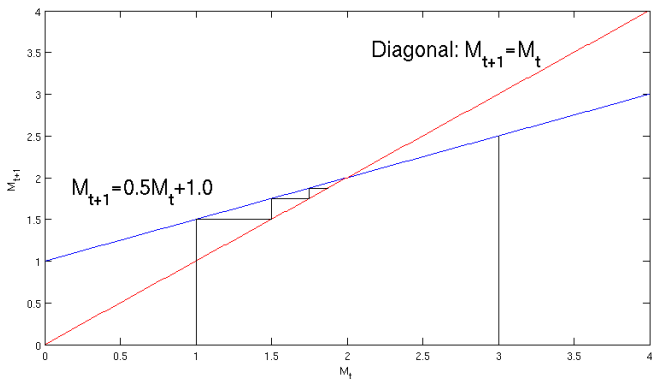
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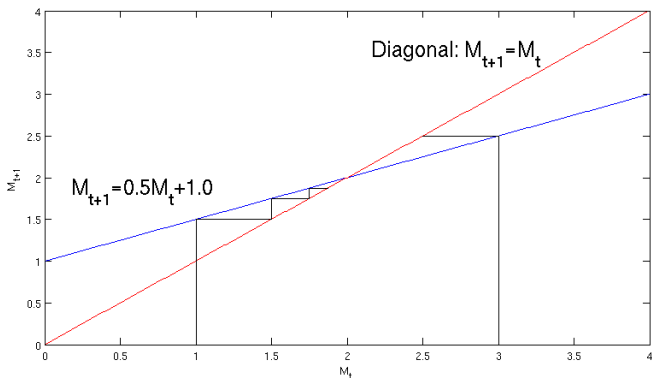
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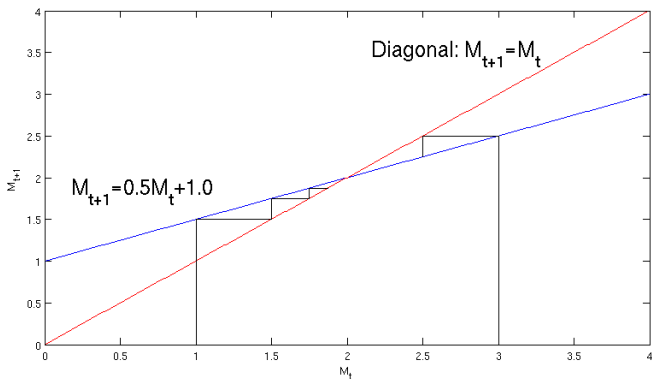
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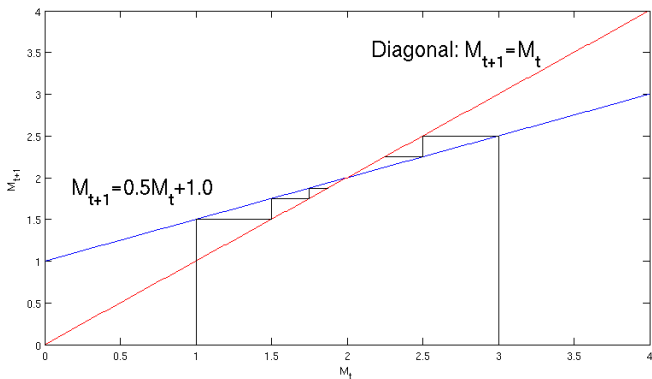
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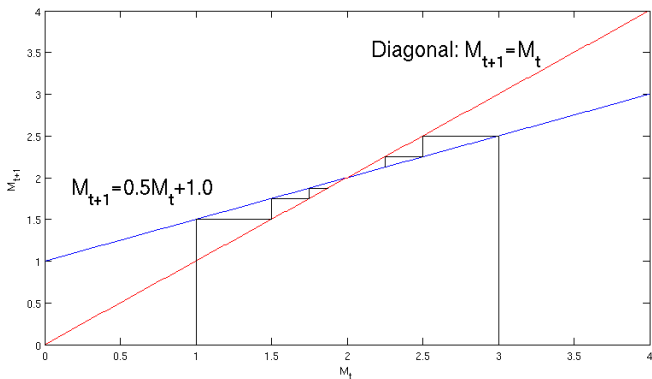
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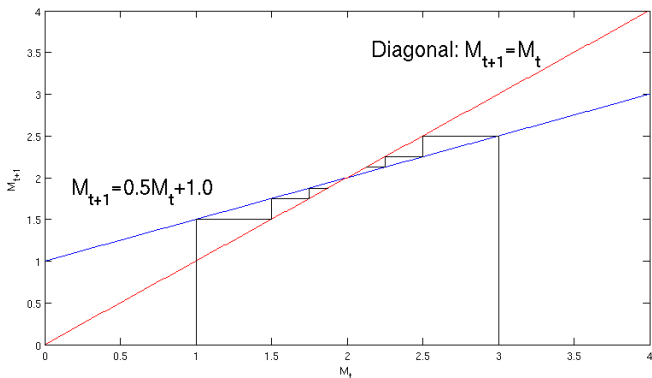
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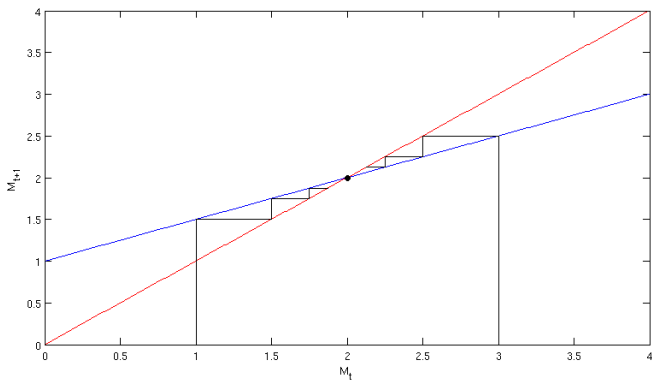


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In both cases we approach the equilibrium 2.0! Recall that we have seen this before.

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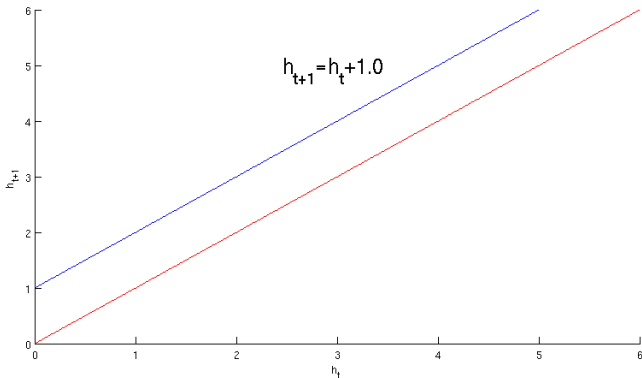


# Examples

Example 2: Now consider the a tree that grows 1.0 meter per year, let  $h_t$  denote the tree height (in meters), which is measured every year. The updating function is  $h_{t+1} = h_t + 1.0$ .

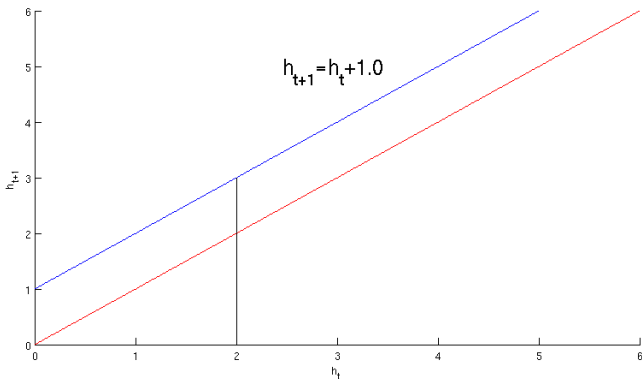
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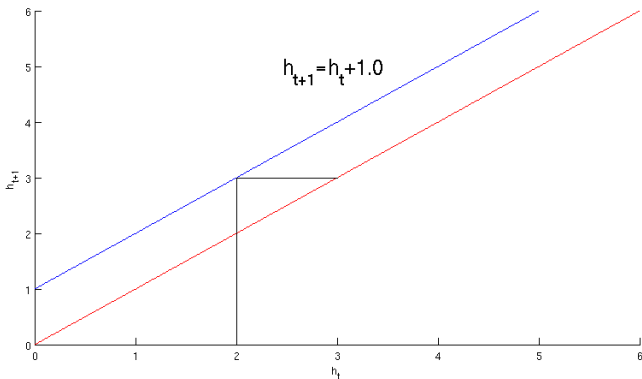
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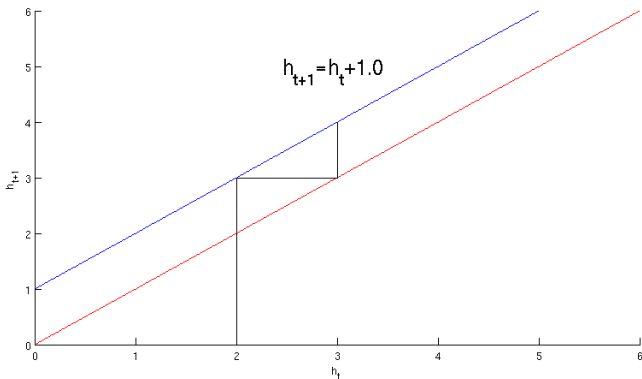
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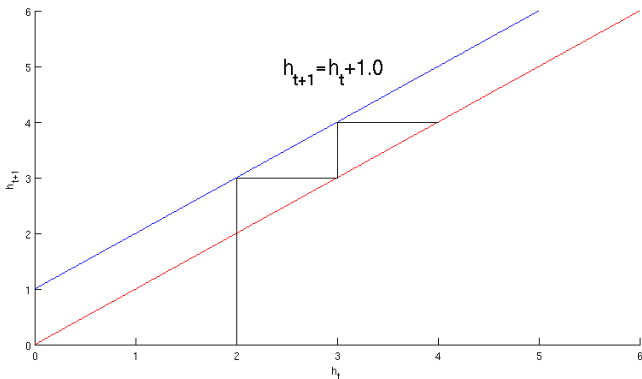
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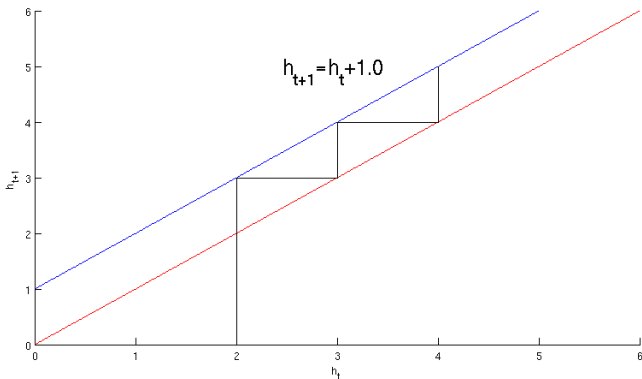
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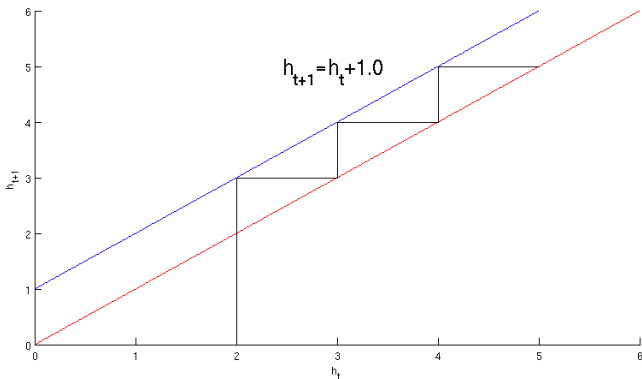
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We cobweb from  $M_0 = 2.0$ :



# Examples

The sequence keeps growing! No equilibrium is approached.



# Finding equilibria

Let  $f$  be the updating function of a dynamical system:  
 $m_{t+1} = f(m_t)$ . An equilibrium is a point  $m^*$  such that

$$f(m^*) = m^*.$$

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If  $M^*$  is an equilibrium, then  $0.5M^* + 1.0 = M^*$ .

This implies that  $1.0 = 0.5M^*$ , and hence  $M^* = 2.0$ .



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If  $h^*$  is an equilibrium, then  $h^* = h^* + 1.0$ . But this equation has no solutions and hence there is no equilibrium.

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We will find the equilibria of the dynamical system

$$x_{t+1} = \frac{cx_t}{x_{t+1}}, \text{ where } c \text{ is some number with } c \neq 0.$$

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This implies that  $x^*(x^* + 1) = cx^*$  and hence

$$x^*(x^* + 1 - c) = 0.$$

Therefore  $x^* = 0$  or  $x^* + 1 - c = 0$ , which gives  $x^* = 0$  or  $x^* = c - 1$ .

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If  $x^*$  is an equilibrium then  $x^* = \frac{cx^*}{x^*+1}$ .

This implies that  $x^*(x^* + 1) = cx^*$  and hence

$$x^*(x^* + 1 - c) = 0.$$

Therefore  $x^* = 0$  or  $x^* + 1 - c = 0$ , which gives  $x^* = 0$  or  $x^* = c - 1$ .

These points are really equilibria, as long as  $x^* + 1 \neq 0$ , which is true since  $c \neq 0$ .

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Conclusion: When  $c \neq 1$  there are two equilibria,  $x^* = 0$  and  $x^* = c - 1$ . When  $c = 1$  there is only one equilibrium,  $x^* = 0$ .