7.1 Diagonalization of Symmetric Matrices

Matrix transpose reminder:

The transpose of $A B$ is $(A B)^{T}=B^{T} A^{T}$

The transpose of $A^{-1}$ is $\left(A^{-1}\right)^{T}=\left(A^{T}\right)^{-1}$

## Definition:

A symmetric matrix is a matrix $A$ such that $A^{T}=A$.

A symmetric matrix is necessarily square.
A symmetric matrix may not have an inverse but if an inverse exists, it is also symmetric.
Here is an example of a symmetric matrix:

$$
\left[\begin{array}{rrr}
0 & -1 & 0 \\
-1 & 5 & 8 \\
0 & 8 & -7
\end{array}\right]
$$

Multiplying any matrix $A$ by $A^{T}$ gives a symmetric matrix.
Note, our previous $L U$ factorization misses symmetry but a factorization $L D L^{-1}$ captures it!

Suppose $A=A^{T}$ can be factored into $A=L D U$ without row interchanges. Then $U$ is the transpose of $L$.

The symmetric factorization becomes $A=L D L^{T}$

The transpose of $A=L D U$ gives $A^{T}=U^{T} D^{T} L^{T}$.
Since $A=A^{T}$, we have a factorization of $A$ into lower triangular times diagonal times upper triangular.
$L^{T}$ is upper triangular with ones on the diagonal just like $U$. Since this factorization is unique, $L^{T}$ must be identical to $U$.

Example:
$L^{T}=U$ and $A=L D L^{T}$.

$$
A=\left[\begin{array}{ll}
1 & 2 \\
2 & 8
\end{array}\right]=\left[\begin{array}{ll}
1 & 0 \\
2 & 1
\end{array}\right]\left[\begin{array}{ll}
1 & 0 \\
0 & 4
\end{array}\right]\left[\begin{array}{ll}
1 & 2 \\
0 & 1
\end{array}\right]=L D L^{T}
$$

Elimination and Symmetric Matrices.
$A=A^{T}$ is an advantage. The smaller matrices stay symmetric as elimination proceeds. So we only need to work with half the matrix! The lower right-hand corner remains symmetric.

$$
\left[\begin{array}{lll}
a & b & c \\
b & d & e \\
c & e & f
\end{array}\right] \rightarrow\left[\begin{array}{ccc}
a & b & c \\
0 & d-\frac{b^{2}}{a} & e-\frac{b c}{a} \\
0 & e-\frac{b c}{a} & f-\frac{c^{2}}{a}
\end{array}\right]
$$

The elimination effort is reduced from $\frac{n^{3}}{3}$ operations to $\frac{n^{3}}{6}$.

In addition, there is no need to store entries from both sides of the diagonal, or to store both $L$ and $U$.

EXAMPLE 2 If possible, diagonalize the matrix $A=\left[\begin{array}{rrr}6 & -2 & -1 \\ -2 & 6 & -1 \\ -1 & -1 & 5\end{array}\right]$.
SOLUTION The characteristic equation of $A$ is

$$
0=-\lambda^{3}+17 \lambda^{2}-90 \lambda+144=-(\lambda-8)(\lambda-6)(\lambda-3)
$$

Standard calculations produce a basis for each eigenspace:

$$
\lambda=8: \mathbf{v}_{1}=\left[\begin{array}{r}
-1 \\
1 \\
0
\end{array}\right] ; \quad \lambda=6: \mathbf{v}_{2}=\left[\begin{array}{r}
-1 \\
-1 \\
2
\end{array}\right] ; \quad \lambda=3: \mathbf{v}_{3}=\left[\begin{array}{l}
1 \\
1 \\
1
\end{array}\right]
$$

These three vectors form a basis for $\mathbb{R}^{3}$. In fact, it is easy to check that $\left\{\mathbf{v}_{1}, \mathbf{v}_{2}, \mathbf{v}_{3}\right\}$ is an orthogonal basis for $\mathbb{R}^{3}$. Experience from Chapter 6 suggests that an orthonormal basis might be useful for calculations, so here are the normalized (unit) eigenvectors.

$$
\mathbf{u}_{1}=\left[\begin{array}{c}
-1 / \sqrt{2} \\
1 / \sqrt{2} \\
0
\end{array}\right], \quad \mathbf{u}_{2}=\left[\begin{array}{c}
-1 / \sqrt{6} \\
-1 / \sqrt{6} \\
2 / \sqrt{6}
\end{array}\right], \quad \mathbf{u}_{3}=\left[\begin{array}{l}
1 / \sqrt{3} \\
1 / \sqrt{3} \\
1 / \sqrt{3}
\end{array}\right]
$$

Let

$$
P=\left[\begin{array}{crc}
-1 / \sqrt{2} & -1 / \sqrt{6} & 1 / \sqrt{3} \\
1 / \sqrt{2} & -1 / \sqrt{6} & 1 / \sqrt{3} \\
0 & 2 / \sqrt{6} & 1 / \sqrt{3}
\end{array}\right], \quad D=\left[\begin{array}{lll}
8 & 0 & 0 \\
0 & 6 & 0 \\
0 & 0 & 3
\end{array}\right]
$$

Then $A=P D P^{-1}$, as usual. But this time, since $P$ is square and has orthonormal columns, $P$ is an orthogonal matrix, and $P^{-1}$ is simply $P^{T}$. (See Section 6.2.)

Theorem
If $A$ is symmetric, then any two eigenvectors from different eigenspaces are orthogonal.

PROOF Let $\mathbf{v}_{1}$ and $\mathbf{v}_{2}$ be eigenvectors that correspond to distinct eigenvalues, say, $\lambda_{1}$ and $\lambda_{2}$. To show that $\mathbf{v}_{1} \cdot \mathbf{v}_{2}=0$, compute

$$
\begin{aligned}
\lambda_{1} \mathbf{v}_{1} \cdot \mathbf{v}_{2} & =\left(\lambda_{1} \mathbf{v}_{1}\right)^{T} \mathbf{v}_{2}=\left(A \mathbf{v}_{1}\right)^{T} \mathbf{v}_{2} & & \text { Since } \mathbf{v}_{1} \text { is an eigenvector } \\
& =\left(\mathbf{v}_{1}^{T} A^{T}\right) \mathbf{v}_{2}=\mathbf{v}_{1}^{T}\left(A \mathbf{v}_{2}\right) & & \text { since } A^{T}=A \\
& =\mathbf{v}_{1}^{T}\left(\lambda_{2} \mathbf{v}_{2}\right) & & \text { since } \mathbf{v}_{2} \text { is an eigenvector } \\
& =\lambda_{2} \mathbf{v}_{1}^{T} \mathbf{v}_{2}=\lambda_{2} \mathbf{v}_{1} \cdot \mathbf{v}_{2} & &
\end{aligned}
$$

Hence $\left(\lambda_{1}-\lambda_{2}\right) \mathbf{v}_{1} \cdot \mathbf{v}_{2}=0$. But $\lambda_{1}-\lambda_{2} \neq 0$, so $\mathbf{v}_{1} \cdot \mathbf{v}_{2}=0$.

## Definition

A matrix $A$ is orthogonally diagonalizable if there are an orthogonal matrix $P$, with $P^{-1}=P^{T}$, and a digonal matrix $D$ such that $A=P D P^{T}=P D P^{-1}$

If $A$ is orthogonally diagonalizable, then

$$
A^{T}=\left(P D P^{T}\right)^{T}=P^{T T} D^{T} P^{T}=A .
$$

So $A$ is symmetric.

An $n \times n$ matrix $A$ is orthogonally diagonalizable if and only if $A$ is a symmetric matrix.

EXAMPLE 3 Orthogonally diagonalize the matrix $A=\left[\begin{array}{rrr}3 & -2 & 4 \\ -2 & 6 & 2 \\ 4 & 2 & 3\end{array}\right]$, whose
characteristic equation is

$$
0=-\lambda^{3}+12 \lambda^{2}-21 \lambda-98=-(\lambda-7)^{2}(\lambda+2)
$$

SOLUTION The usual calculations produce bases for the eigenspaces:

$$
\lambda=7: \mathbf{v}_{1}=\left[\begin{array}{l}
1 \\
0 \\
1
\end{array}\right], \mathbf{v}_{2}=\left[\begin{array}{c}
-1 / 2 \\
1 \\
0
\end{array}\right] ; \quad \lambda=-2: \mathbf{v}_{3}=\left[\begin{array}{c}
-1 \\
-1 / 2 \\
1
\end{array}\right]
$$

Although $\mathbf{v}_{1}$ and $\mathbf{v}_{2}$ are linearly independent, they are not orthogonal. Recall from Section 6.2 that the projection of $\mathbf{v}_{2}$ onto $\mathbf{v}_{1}$ is $\frac{\mathbf{v}_{2} \cdot \mathbf{v}_{1}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}} \mathbf{v}_{1}$, and the component of $\mathbf{v}_{2}$ orthogonal to $\mathbf{v}_{1}$ is

$$
\mathbf{z}_{2}=\mathbf{v}_{2}-\frac{\mathbf{v}_{2} \cdot \mathbf{v}_{1}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}} \mathbf{v}_{1}=\left[\begin{array}{c}
-1 / 2 \\
1 \\
0
\end{array}\right]-\frac{-1 / 2}{2}\left[\begin{array}{l}
1 \\
0 \\
1
\end{array}\right]=\left[\begin{array}{c}
-1 / 4 \\
1 \\
1 / 4
\end{array}\right]
$$

Then $\left\{\mathbf{v}_{1}, \mathbf{z}_{2}\right\}$ is an orthogonal set in the eigenspace for $\lambda=7$. (Note that $\mathbf{z}_{2}$ is a linear combination of the eigenvectors $\mathbf{v}_{1}$ and $\mathbf{v}_{2}$, so $\mathbf{z}_{2}$ is in the eigenspace. This construction of $\mathbf{z}_{2}$ is just the Gram-Schmidt process of Section 6.4.) Since the eigenspace is twodimensional (with basis $\mathbf{v}_{1}, \mathbf{v}_{2}$ ), the orthogonal set $\left\{\mathbf{v}_{1}, \mathbf{z}_{2}\right\}$ is an orthogonal basis for the eigenspace, by the Basis Theorem. (See Section 2.9 or 4.5 .)

Normalize $\mathbf{v}_{1}$ and $\mathbf{z}_{2}$ to obtain the following orthonormal basis for the eigenspace for $\lambda=7$ :

$$
\mathbf{u}_{1}=\left[\begin{array}{c}
1 / \sqrt{2} \\
0 \\
1 / \sqrt{2}
\end{array}\right], \quad \mathbf{u}_{2}=\left[\begin{array}{c}
-1 / \sqrt{18} \\
4 / \sqrt{18} \\
1 / \sqrt{18}
\end{array}\right]
$$

An orthonormal basis for the eigenspace for $\lambda=-2$ is

$$
\mathbf{u}_{3}=\frac{1}{\left\|2 \mathbf{v}_{3}\right\|} 2 \mathbf{v}_{3}=\frac{1}{3}\left[\begin{array}{r}
-2 \\
-1 \\
2
\end{array}\right]=\left[\begin{array}{r}
-2 / 3 \\
-1 / 3 \\
2 / 3
\end{array}\right]
$$

By Theorem 1, $\mathbf{u}_{3}$ is orthogonal to the other eigenvectors $\mathbf{u}_{1}$ and $\mathbf{u}_{2}$. Hence $\left\{\mathbf{u}_{1}, \mathbf{u}_{2}, \mathbf{u}_{3}\right\}$ is an orthonormal set. Let

$$
P=\left[\begin{array}{lll}
\mathbf{u}_{1} & \mathbf{u}_{2} & \mathbf{u}_{3}
\end{array}\right]=\left[\begin{array}{crr}
1 / \sqrt{2} & -1 / \sqrt{18} & -2 / 3 \\
0 & 4 / \sqrt{18} & -1 / 3 \\
1 / \sqrt{2} & 1 / \sqrt{18} & 2 / 3
\end{array}\right], \quad D=\left[\begin{array}{rrr}
7 & 0 & 0 \\
0 & 7 & 0 \\
0 & 0 & -2
\end{array}\right]
$$

Then $P$ orthogonally diagonalizes $A$, and $A=P D P^{-1}$.

The Spectral Theorem for Symmetric Matrices:
An $n \times n$ matrix $A$ is orthogonally diagonalizable if and only if $A$ is a symmetric matrix.

The Spectral Theorem for symmetric matrices:
An $n \times n$ symmetric matrix $A$ has the following properties:
a. A has $n$ real eigenvalues, counting multiplicities.
b. The dimension of the eigenspace for each eigenvalue $\lambda$ equals the multiplicity of $\lambda$ as a root of the characteristic equation.
c. The eigenspaces are mutually orthogonal, in the sense that eigenvectors corresponding to different eigenvalues are orthogonal.
d. $A$ is orthogonally diagonalizable.

## Spectral Decomposition.

Suppose $A=P D P^{-1}$, where the columns of $P$ are orthonormal eigenvectors $\vec{u}_{1}, \ldots, \vec{u}_{n}$ of $A$ and the corresponding eigenvalues $\lambda_{1}, \ldots, \lambda_{n}$ are in the diagonal matrix $D$. Then, since $P^{-1}=P^{T}$,

$$
\begin{aligned}
A & =P D P^{T}=\left[\begin{array}{lll}
\vec{u}_{1} & \cdots & \vec{u}_{n}
\end{array}\right]\left[\begin{array}{lll}
\lambda_{1} & & 0 \\
0 & \ddots & \\
0 & & \lambda_{n}
\end{array}\right]\left[\begin{array}{c}
\vec{u}_{1}^{T} \\
\vdots \\
\vec{u}_{n}^{T}
\end{array}\right] \\
& =\left[\begin{array}{lll}
\lambda_{1} \vec{u}_{1} & \cdots & \lambda_{n} \vec{u}_{n}
\end{array}\right]\left[\begin{array}{c}
\vec{u}_{1}^{T} \\
\vdots \\
\vec{u}_{n}^{T}
\end{array}\right]
\end{aligned}
$$

So we have $\quad A=\lambda_{1} \vec{u}_{1} \vec{u}_{1}^{T}+\lambda_{2} \vec{u}_{2} \vec{u}_{2}^{T}+\cdots+\lambda_{n} \vec{u}_{n} \vec{u}_{n}^{T}$
This representation of $A$ is called a spectral decomposition of $A$ because it breaks up $A$ into pieces determined by the spectrum (the eigenvalues) of $A$.

Each term, $\vec{u}_{j} \vec{u}_{j}^{T}$, is an $n \times n$ matrix of rank 1.

For example, every column of $\lambda_{1} \vec{u}_{1} \vec{u}_{1}^{T}$ is a multiple of $\vec{u}_{1}$.
In addition, each matrix $\vec{u}_{j} \vec{u}_{j}^{T}$ is a projection matrix in the sense that for each $\vec{x}$ in $\mathbb{R}^{n}$, the vector $\left(\vec{u}_{j} \vec{u}_{j}^{T}\right) \vec{x}$ is the orthogonal projection of $\vec{x}$ onto the subspace spanned by $\vec{u}_{j}$.

## NUMERICAL NOTE

When $A$ is symmetric and not too large, modern high-performance computer algorithms calculate eigenvalues and eigenvectors with great precision. They apply a sequence of similarity transformations to $A$ involving orthogonal matrices. The diagonal entries of the transformed matrices converge rapidly to the eigenvalues of $A$. (See the Numerical Notes in Section 5.2.) Using orthogonal matrices generally prevents numerical errors from accumulating during the process. When $A$ is symmetric, the sequence of orthogonal matrices combines to form an orthogonal matrix whose columns are eigenvectors of $A$.

A nonsymmetric matrix cannot have a full set of orthogonal eigenvectors, but the algorithm still produces fairly accurate eigenvalues. After that, nonorthogonal techniques are needed to calculate eigenvectors.

Example: Let $A=\left[\begin{array}{lll}3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 3\end{array}\right]$ and $\vec{v}=\left[\begin{array}{l}1 \\ 1 \\ 1\end{array}\right]$.

Verify that 5 is an eigenvalue of $A$ and $\vec{v}$ is an eigenvector. Then orthogonally diagonalize $A$.

## Solution:

Let $A=\left[\begin{array}{lll}3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 3\end{array}\right]$. Since each row of $A$ sums to 5 ,
$A\left[\begin{array}{l}1 \\ 1 \\ 1\end{array}\right]=\left[\begin{array}{lll}3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 3\end{array}\right]\left[\begin{array}{l}1 \\ 1 \\ 1\end{array}\right]=\left[\begin{array}{l}5 \\ 5 \\ 5\end{array}\right]=5\left[\begin{array}{l}1 \\ 1 \\ 1\end{array}\right]$ and 5 is an eigenvalue of $A$.
The eigenvector $\left[\begin{array}{l}1 \\ 1 \\ 1\end{array}\right]$ may be normalized to get $\vec{u}_{1}=\left[\begin{array}{l}1 / \sqrt{3} \\ 1 / \sqrt{3} \\ 1 / \sqrt{3}\end{array}\right]$.

Also,
$A\left[\begin{array}{r}-1 \\ 1 \\ 0\end{array}\right]=\left[\begin{array}{lll}3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 3\end{array}\right]\left[\begin{array}{r}-1 \\ 1 \\ 0\end{array}\right]=\left[\begin{array}{r}-2 \\ 2 \\ 0\end{array}\right]=2\left[\begin{array}{r}-1 \\ 1 \\ 0\end{array}\right]$, so 2 is a repeated eigenvalue of $A$ associated with the eigenvector $\left[\begin{array}{r}-1 \\ 1 \\ 0\end{array}\right]$. For $\lambda=2$, a basis for the eigenspace is $\left\{\left[\begin{array}{r}-1 \\ 1 \\ 0\end{array}\right],\left[\begin{array}{r}-1 \\ -1 \\ 2\end{array}\right]\right\}$. This basis is an orthogonal basis for the eigenspace, and these vectors can be normalized ...

We get $\vec{u}_{2}=\left[\begin{array}{r}-1 / \sqrt{2} \\ 1 / \sqrt{2} \\ 0\end{array}\right]$ and $\vec{u}_{3}=\left[\begin{array}{c}-1 / \sqrt{6} \\ -1 / \sqrt{6} \\ 2 / \sqrt{6}\end{array}\right]$.
Let

$$
P=\left[\begin{array}{lll}
\vec{u}_{1} & \vec{u}_{2} & \vec{u}_{3}
\end{array}\right]=\left[\begin{array}{ccc}
1 / \sqrt{3} & -1 / \sqrt{2} & -1 / \sqrt{6} \\
1 / \sqrt{3} & 1 / \sqrt{2} & -1 / \sqrt{6} \\
1 / \sqrt{3} & 0 & 2 / \sqrt{6}
\end{array}\right] \text { and } D=\left[\begin{array}{lll}
5 & 0 & 0 \\
0 & 2 & 0 \\
0 & 0 & 2
\end{array}\right] \text {. }
$$

Then $P$ orthogonally diagonalizes $A$, and $A=P D P^{-1}$

Theorem:
If $A$ is symmetric, then any two eigenvectors from different eigenspaces are orthogonal.

Definition:
A matrix $A$ is said to be orthogonally diagonalizable if there are an orthogonal matrix $P$ and a diagonal matrix $D$ such that

$$
A=P D P^{T}=P D P^{-1}
$$

To orthogonally diagonalize an $n \times n$ matrix, we need to find $n$ linearly independent and orthonormal vectors.

If $A$ is orthogonally diagonalizable, then

$$
A^{T}=\left(P D P^{T}\right)^{T}=P^{T} P^{T} D^{T} P^{T}=P D P^{-1}=A
$$

Thus $A$ is symmetric. It turns out that every symmetric matrix is orthogonally diagonalizable.

Matrix Factorizations

1. $A=L U=\binom{$ lower triangular $L}{$ ones on the diagonal }$\binom{$ upper triangular $U}{$ pivots on the diagonal } Requirements: No row exchanges, as Gaussian Elimination reduces $A$ to $U$.
2. $A=S \Lambda S^{-1}$
$=($ eigenvectors in $S)($ eigenvalues in $\Lambda)\left(\right.$ left eigenvectors in $\left.S^{-1}\right)$
Requirements: $A$ must have $n$ linearly independent eigenvectors.

Matrix Factorizations continued
3. $A=Q \Lambda Q^{T}=($ orthogonal matrix $Q)($ real eigenvalues in $\Lambda)\left(Q^{T}\right.$ is $\left.Q^{-1}\right)$ Requirements: $A$ is symmetric. This is the spectral theorem.
4. $A=U \Sigma V^{T}=\binom{$ orthogonal }{$U$ is $m \times m}\binom{m \times n$ matrix $\Sigma}{\sigma_{1}, \ldots, \sigma_{r}$ on diagonal }$\binom{$ orthogonal }{$V$ is $n \times n}$ Requirements: None. The singular value decomposition (SVD) has the eigenvectors of $A A^{T}$ in $U$ and of $A^{T} A$ in $V$.

$$
\sigma_{i}=\sqrt{\lambda_{i}\left(A^{T} A\right)}=\sqrt{\lambda_{i}\left(A A^{T}\right)}
$$

Reminder: Diagonalization of a Matrix

The eigenvectors diagonalize a matrix. Suppose the $n \times n$ matrix $A$ has $n$ linearly independent eigenvectors. If these eigenvectors are the columns of a matrix $S$, then $S^{-1} A S$ is a diagonal matrix $\Lambda$.

The eigenvalues of $A$ are on the diagonal of $\Lambda$ :

$$
S^{-1} A S=\Lambda=\left[\begin{array}{lll}
\lambda_{1} & & \\
& \ddots & \\
& & \lambda_{n}
\end{array}\right]
$$

Proof: Put the eigenvectors $\vec{v}_{i}$ in the columns of $S$, and compute AS by columns:

$$
A S=A\left[\begin{array}{llll}
\vec{v}_{1} & \vec{v}_{2} & \cdots & \vec{v}_{n}
\end{array}\right]=\left[\begin{array}{llll}
\lambda_{1} \vec{v}_{1} & \lambda_{2} \vec{v}_{2} & \cdots & \lambda_{n} \vec{v}_{n}
\end{array}\right] .
$$

Then the last matrix can be written
$\left[\begin{array}{llll}\lambda_{1} \vec{v}_{1} & \lambda_{2} \vec{v}_{2} & \cdots & \lambda_{n} \vec{v}_{n}\end{array}\right]=\left[\begin{array}{llll}\vec{v}_{1} & \vec{v}_{2} & \cdots & \vec{v}_{n}\end{array}\right]\left[\begin{array}{lll}\lambda_{1} & & \\ & \ddots & \\ & & \lambda_{n}\end{array}\right]=S A$
The order of the matrices is important.
If $\Lambda$ came before $S$ then $\lambda_{1}$ would multiply the entries in the first row. We want $\lambda_{1}$ to appear in the first column. Therefore, $A S=S \Lambda$, or $S^{-1} A S=S \Lambda \Rightarrow A=S \Lambda S^{-1}$.

## End presentation

