Weilong Zhang

El Monte, CA • LinkedIn • http://weilong.tk

EDUCATION

Columbia University, Fu Foundation School of Engineering and Applied Science

December 2012

Master of Science in Mechanical Engineering (GPA: 3.83/4.0)

New York, NY

Coursework: Introduction to Database, Robotics, Control Theory, Mechatronics and Embedded Microcomputer Control, Advanced Machine Dynamics, Computational Geometry, Digital Control System

Zhejiang University, Department of Mechanical Engineering

July 2011

Bachelor of Science in Mechanical Engineering and Automation (GPA: 3.51/4.0)

Hangzhou, China

Honor: Excellent Student Leader, 2008

WORK EXPERIENCE

Software Engineer Intern

Since May 2013

Smartplane Inc.

Los Angeles, CA

- Developed program for decoding major ADS-B messages for use in modern personal aircrafts, translating from code to weather element and plain language
- Set up hardware architecture for necessary avionics, including aircraft cockpit computer, radio, navigation devices, etc.
- Implemented haptic autopilot algorithm that made piloting easier than never before

Mechanical Engineer Intern

May 2012-August 2012

Guangzhou Institutes of Advanced Technology, Chinese Academy of Sciences

Guangzhou, China

- Designed Artificial Compound Eyes Testing System in SolidWorks and AutoCAD based on imaging requirements, including capability to auto-focus and adjust sensor position in three directions
- Assembled all hardware including CMOS imaging sensor, focusing module (resolution up to 1μm) and other auxiliary equipment
- Developed a Windows application with Visual Studio in order to implement retrieving images and post-processes

PROJECTS

Mechanical Models of Human Respiratory System

September 2012-January 2013

Graduate Project, Professor Nicholas Chbat, Columbia University

New York, NY

- Implemented and evaluated CPR model and respiratory pump model in Matlab and Simulink based on literature
- Analyzed the responses to applied forces of our mathematical models and the ones from literature, examined limitations

Mechatronics and Embedded Microcomputer Control

September 2011-December 2011

Curricular Project, Columbia University

New York, NY

- Installed mechatronics development environment and performed major embedded system developing procedures
- Accomplished 6 case studies related to practical applications with use of microcontroller PIC16F74

Computational Aspects of Robotics

September 2011-December 2011

Curricular Project, Columbia University

New York, NY

- Configured hardware for a mobile robot and established communicating connection via Bluetooth/Wi-Fi and a network camera
- Developed programs in Matlab to drive the robot to achieve several missions, including route planning and object search

HBLS Pendant Station Control Program

February 2011-June 2011

Undergraduate Thesis, Zhejiang University

Hangzhou, China

- Installed the hardware and configured all control parameters of SyngNet networks, filters, digital I/O devices and a motor
- Developed a visualized program in C++ with MFC, using the libraries from devices manufacturers

TECHNICAL SKILLS

Applications	SolidWorks 2012, AutoCAD R14, Ansys, MATLAB R2011, Visual Studio 2010, Eclipse, MPLAB 8, MS Office
Research & Development	2-D/3-D CAD Drafting and Modeling, Finite Element Analysis, Computer Software Design, Programming
	Microcomputers, Arduino Development, Avionics, Aviation Communication (Entry-level)
Programming Languages	Java, C, C++, SQL, Assembly Language, Embedded C
Lab Equipment	Oscilloscope, Function Generator, Digital Multimeter, Programmer
OTHER	

Leadership Activities