

# Use and Design of Acceleration and Deceleration Lanes in Indiana

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The speed and lateral placement of vehicles on the various designs of the acceleration and deceleration lanes of the Indiana Toll Road and the Interstate System of the State of Indiana were studied to correlate the acceleration and deceleration lane design with traffic behavior and driver requirements and to determine which acceleration and deceleration lane designs provide the most efficient and safest operation. Data on speeds and lateral placement of traffic using the acceleration and deceleration lanes were obtained by use of a motion picture technique. Spot speeds of through lane traffic were measured using an electromatic radar speed meter.

The study revealed that a large number of the driving public do not know how to use acceleration and deceleration lanes properly. Acceleration or deceleration lane traffic was found to have little effect on the speed of the through lanes before diverging into the deceleration lanes. The long direct taper type of design was found superior for both acceleration and deceleration lanes.

• ON THE BASIS of various recent research studies, it is apparent that highway designers are becoming more and more concerned with the relationship between highway design and traffic behavior. An excellent example of current interest is the design of acceleration and deceleration lanes. To obtain maximum efficiency and safety in the operation of acceleration and deceleration lanes, and to maintain efficiency on the main facility, it is necessary to relate the design of such lanes to traffic behavior, as indicated by the requirements and desires of drivers.

Drivers leaving a highway at an intersection are usually required to reduce speed before turning. On the other hand, drivers entering a highway at an intersection have to accelerate to reach the desired speed of the traffic on the facility. Whenever this deceleration or acceleration by exiting or entering traffic takes place on the main traveled way of the highway, it disrupts the flow of through traffic and is hazardous (1). Thus, to minimize these undesirable aspects on high-speed facilities, maximum use should be made of acceleration and deceleration lanes.

For best operating conditions, acceleration and deceleration lanes should be used for the entire acceleration and deceleration phase by vehicles entering or leaving the through traffic lane. Each such acceleration and deceleration lane, therefore, should be of a design that will enable a driver to maneuver his vehicle onto it without a major change in speed and, once on it, to make the necessary change between the speed of operation on the main facility and the lower speed required for exit or entrance. The optimum condition of operation for an acceleration lane is to have acceleration lane traffic accelerate on the acceleration lane and merge into the through lane traffic at approximately the same direction of travel and at the same speed as the through lane traffic. That for a deceleration lane is to have deceleration lane traffic leave the

through lane at about the same direction of travel as through lane traffic and at the same speed, with all deceleration taking place in the deceleration lane.

Acceleration and deceleration lane design varies very significantly from State to State. Some States follow the standards set forth in the AASHO manual (1); others have developed their own standards using the AASHO manual as a guide.

The Indiana State Highway Commission has used several designs for acceleration and deceleration lanes. The parallel lane type of acceleration lane was initially adopted as a standard. This type, consisting of a full width lane 350 ft long with 400 ft of taper, has been constructed at several locations. Later, the length of the parallel acceleration lane was changed to 250 ft of full width with 250 ft of taper. Later yet, the direct taper type of acceleration lane design was adopted to correct a tendency for entering traffic to move into the through lane too quickly. This latter acceleration lane has a 750-ft taper. More recently, an acceleration lane having 50:1 taper was adopted. This design is similar to one described in "Traffic Behavior on Freeways," Highway Research Board Bulletin 235. This last design, however, had not been incorporated in any construction completed before 1962.

Adopted standards for the State of Indiana for deceleration lanes have also included the parallel lane type and the direct taper type. One design uses a taper lane width ranging from 0 to 12 ft in 250 ft, followed by 50 ft of tangent and then a curve. A second design uses a continuous curve. A third design has a taper followed by a curve, and a fourth design uses a straight short taper. During 1961, a design having about 900 ft of straight taper was adopted.

This paper reports the speed and lateral placement of vehicles on acceleration and deceleration lanes of these various designs as constructed in Indiana. It also correlates acceleration and deceleration lane design with traffic behavior and apparent driver requirements and makes some suggestions relative to acceleration lane and deceleration lane design.

## SCOPE

The study was limited to high-type facilities in Indiana. Locations were chosen on the Indiana Toll Road and those sections of the Interstate System that were completed and had been opened to traffic before 1962. The study locations were specifically selected to provide data on speeds and lateral placement for various designs of acceleration and deceleration lanes and for operation under different conditions. Not all the different designs of acceleration and deceleration lanes which have been adopted by the Indiana State Highway Commission could be studied, as some of these designs had not as yet been incorporated in any completed construction.

Locations were chosen, if possible, to include one of three conditions of road geometry: where the acceleration or deceleration lanes met or left the through lanes on (a) a tangent, (b) a right curve, or (c) a left curve. One location was also studied where an acceleration lane joined the through lane on the upgrade portion of a crest vertical curve, and another was included where the junction occurred on the downgrade portion of a sag vertical curve. All these conditions were studied to evaluate what effects each had on traffic behavior and to determine which condition provided for the most efficient and safe use of acceleration and deceleration lanes.

In four cases, more than one location having the same acceleration or deceleration lane design and similar conditions of road geometry were studied. These studies were made at different locations having different traffic, in order to evaluate the repetitive character of the results. It was suspected that other factors such as traffic volumes and types of drivers using the facility would have a significant bearing on the results.

The speeds of through vehicles were also analyzed at each interchange around the point where the acceleration or deceleration lanes joined the through lanes. This was done to compare speeds of acceleration or deceleration lane traffic with through lane traffic at each location. The speeds of through traffic were also obtained before or after the interchanges to evaluate the effect of interchange traffic on the speed of through traffic at the interchange.

The types of vehicles studied were passenger cars and light trucks, which were considered as passenger cars. Data from at least 108 passenger cars were analyzed for

each acceleration or deceleration lane studied. Heavy trucks were not included, as the number of such trucks using acceleration and deceleration lanes on existing Indiana freeways was small and a long and expensive period of data collection to obtain an adequate sample of trucks would have been required. Information on the use of acceleration and deceleration lanes by trucks is certainly desirable and should be obtained. During the course of the study the location where deceleration lane traffic begins to decelerate while on the through lanes and before the beginning of the deceleration lane was found of interest. This information, therefore, was obtained for a few of the study locations for deceleration lanes. Only information for free-moving vehicles was used for all parts of this study.

Vehicles that stopped on the acceleration or deceleration lanes were not included in the speed and lateral placement evaluations but were recorded for possible use as a measure of the efficiency of operation of the various designs. Data on accidents at each site were obtained but the number of accidents was so small because so little time had elapsed since construction that an analysis was not possible.

### PROCEDURE

Data on speeds and lateral placement of traffic using acceleration and deceleration lanes were obtained with a 16-mm motion picture camera. The motion picture type of study was selected, after consideration of various other methods, as being the best for detailed study and analysis.

The filming was done from a vantage point, usually an overpass over the main facility at the interchange. The camera used was a 16-mm Bell and Howell movie camera with a built-in turret head.

In the case of acceleration lanes, movies were taken of each free-flowing passenger car as it passed a designated point, usually the nose, beyond which it was able to maneuver and merge into the through lanes, and until the left rear wheel of the vehicle crossed from the acceleration lane onto the through lane. The left rear wheel of the car was chosen as the criterion because acceleration lane traffic traveled away from the camera and therefore was visible, and for all practical purposes the instant the left rear wheel crosses from the acceleration lane onto the through lane, conflict with the through traffic operation becomes serious.

As for the deceleration lane, movies were taken of each vehicle before its left front wheel crossed from the through lane onto the deceleration lane and until it passed a designated point on the deceleration lane, usually the nose, beyond which the car was unable to maneuver back onto the through lane. Here, the left front wheel of the car was chosen because, for deceleration lanes, traffic traveled towards the camera and by that point most of the car had left the through lane and was no longer a conflict on the through lanes.

The film was analyzed by projecting it through a time-motion study projector. A grid was superimposed on the screen where the film was projected to a scale which provided accurate ground measurements. The vehicle speeds at various locations on the acceleration and deceleration lanes were computed using the grid system by determining the distance traveled during a time period. Time was measured by the number of frames a vehicle traveled between two grid lines. The lateral placement of the vehicles on the acceleration or deceleration lanes was also traced by using the grid system. The stations at which the left rear wheel of acceleration lane traffic and the left front wheel of deceleration lane traffic crossed the line between the acceleration or deceleration lane and through lanes were noted.

Speed information was grouped by 100-ft sections according to the location on the acceleration or deceleration lane where each car merged or diverged. For example, the speed data for all vehicles on a study lane which merged between Station 0+00 and Station 1+00 were grouped for analysis. The average speed, 85th percentile speed, standard deviation, and percent of total vehicles leaving or entering between stations were computed for each group. The 85th percentile speed and percent leaving or entering between 100-ft stations are indicated on the sketches of each study site which are included in this report. A single value for the 85th percentile speed for all vehicles entering or leaving the deceleration or acceleration lane is shown on these sketches in parentheses.

A cumulative frequency graph of lateral placements was plotted for each study site. This graph was developed by plotting the cumulative percent of vehicles that merged into or diverged from the through lane against the distance from the nose at which the merger or divergence occurred. It was found that the cumulative curves thus prepared tended to break sharply at approximately 90 percent. Thus, the 90th percentile was taken as an important criterion for determining the length of an acceleration or deceleration lane which would be effectively used.

Spot speeds of through lane traffic were measured using a concealed radar meter. The spot speeds of through traffic were measured at two locations at each study site. The first of these was "within the area of conflict," the area where acceleration or deceleration lanes adjoined the through lane. The second spot speed location was "beyond the area of conflict," a point approximately 1 mi before or after the interchange. Posted speed limits were the same for traffic on all through lanes studied.

Spot speeds of deceleration lane traffic were measured at three deceleration lane sites in an attempt to determine where traffic destined for a deceleration lane begins to decelerate on the through lane. The radar meter was placed so that the cars approaching the deceleration lane intersected the beam at the specified location, but only cars that proceeded to use the deceleration lane were recorded.

## RESULTS

### Acceleration Lanes

Figure 1 is a map of Indiana showing the location of the acceleration and deceleration lanes studied. Pertinent data for each acceleration lane location are given in Table 1.

TABLE 1  
STUDY LOCATION DATA—ACCELERATION LANES

Accel. Lane Identification	Location	Direction of Accel. Lane Traffic	Geometric Condition		Acceleration Lane	
			Description	Type	Description	Type
A1a	Indiana Toll Road—Middlebury	Westbound	Tangent	1	Direct taper 1,200 ft	1
A1b	Gary West	Westbound	Tangent	1	Direct taper 1,200 ft	1
A1c	Michigan City	Westbound	Tangent and down-grade portion of sag vertical curve	4	Direct taper 1,200 ft	1
A1d	Chesterton—Valparaiso	Westbound	Right curve	2	Direct taper 1,200 ft	1
A1e	LaPorte	Westbound	Right curve and up-grade portion of crest vertical curve	5	Direct taper 1,200 ft	1
A1f	Gary East	Eastbound	Left curve	3	Direct taper 1,200 ft	1
A2a	Interstate 65—State Road 39	Northbound	Tangent	1	Parallel— 350-ft str and 400-ft taper	2
A2b	Tri-State—Kennedy Ave.	Eastbound	Tangent	1	Parallel— 350-ft str and 400-ft taper	2
A2c	Interstate 74—Post Road	Eastbound	Tangent	1	Parallel— 350-ft str and 400-ft taper	2
A2d	Interstate 65—State Road 60	Southbound	Right curve	2	Parallel— 350-ft str and 400-ft taper	2
A2e	State Road 39	Southbound	Left curve	3	Parallel— 350-ft str and 400-ft taper	2
A3a	State Road 56	Northbound	Tangent	1	Parallel— 250-ft str and 250-ft taper	3
A3b	State Road 334	Northbound	Left curve	3	Parallel— 250-ft str and 250-ft taper	3
A4a	Tri-State—Calumet Ave.	Eastbound	Tangent	1	Direct taper 300 ft	4
A4b	Calumet Ave.	Westbound	Right curve	2	Direct taper 300 ft	4

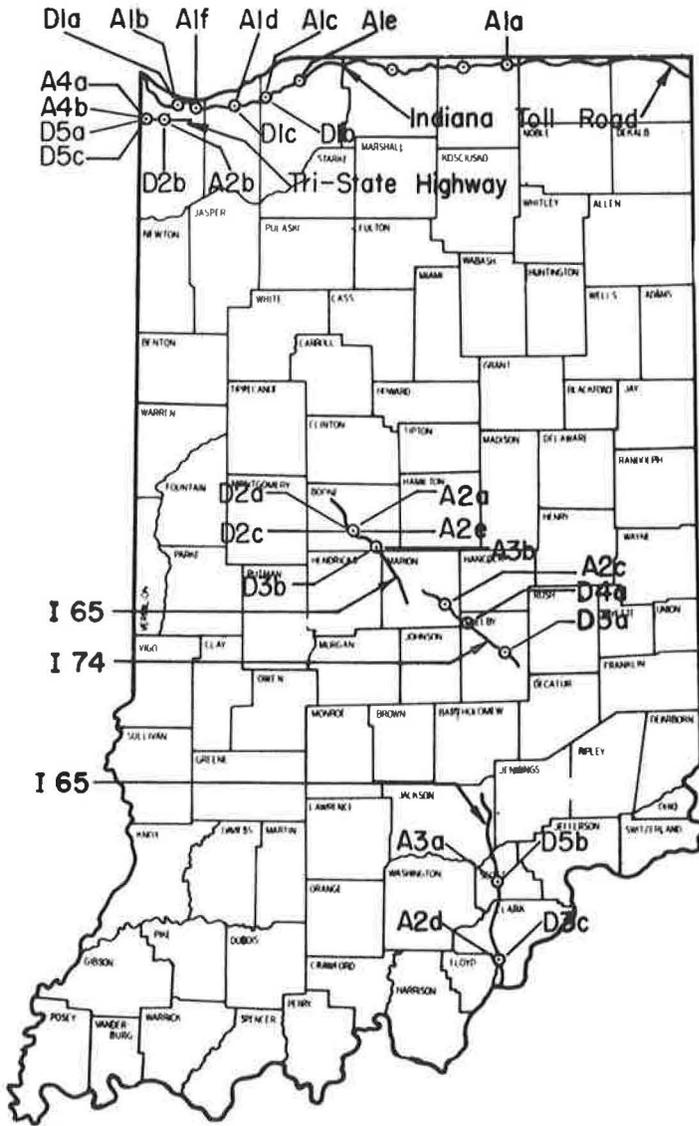


Figure 1. Study locations of acceleration and deceleration lanes.

These locations are coded as follows: A1a, A2b, etc., in which the A stands for acceleration lane; the number, for the type of lane design; and the lower-case letter (a, b, etc.), for the location.

Type 1.—One type of acceleration lane studied is on the Indiana Toll Road and is of the design shown in Figure 2. The length of the acceleration lane is 1,200 ft from the end of the ramp curve to the intersection with the right edge of the through lane. A shoulder, paved but of a different color, separates the acceleration lane from the through lane for a distance of 577.82 ft. For some of this distance, a curb also adjoins the acceleration lane. Beyond the point of separation, the acceleration lane is an extra lane with a 52:1 straight taper from a width of 12 to 0 ft in a distance of 622.03 ft.

Six locations of this type of acceleration lane were studied. At two of these locations, the acceleration lane meets the through lane on a tangent; at a third location, on

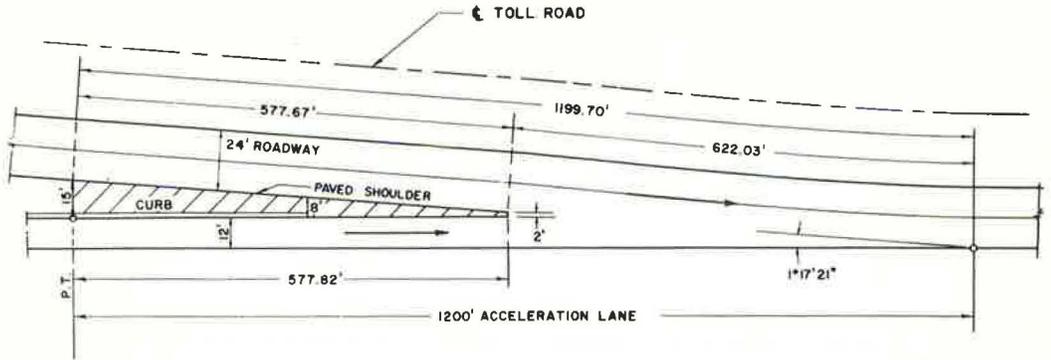


Figure 2. Acceleration lane, type 1.

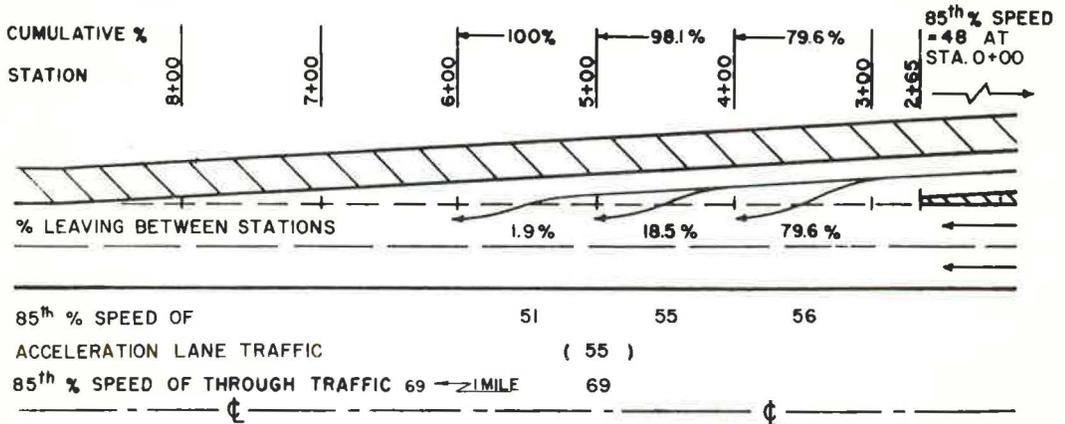


Figure 3. Speeds and lateral placement of passenger cars on type 1 acceleration lane, location A1a—Indiana Toll Road, Middlebury Interchange, westbound traffic.

a tangent and also on the downgrade portion of a sag vertical curve; at a fourth, on a right curve; at a fifth, on a right curve and also on the upgrade portion of a crest vertical curve; and at a sixth, on a left curve.

Station 0+00 was placed as the end of the ramp curb; beyond this point, acceleration lane traffic could merge into the through lanes.

Figures 3 through 8 show the results of the speed and lateral placement studies made at these locations. The results at location A1a are discussed in the following paragraphs as an example of how each of these figures and the data in Table 2 were analyzed. A summary of the important characteristics of use obtained at each location is given in Table 2.

In location A1a, the acceleration lane meets the through lane on a tangent at the interchange. The annual average daily traffic (1960) on the acceleration lane was 620 vehicles per day and on the westbound through lanes was 3,720 vehicles per day.

Figure 3 shows the results of the speed and lateral placement study made at this location. On this figure, as on similar figures for other locations of acceleration and deceleration lanes studied, 85th percentile speeds are shown for acceleration lane traffic and for through lane traffic. For acceleration lane traffic, the 85th percentile speed is given for Station 0+00 and for all vehicles which left the acceleration lane in each 100 ft thereafter at the time of merging. The percentage of the total non-stopping vehicles using the acceleration lanes which left the lane in each 100 ft and the cumulative percent-

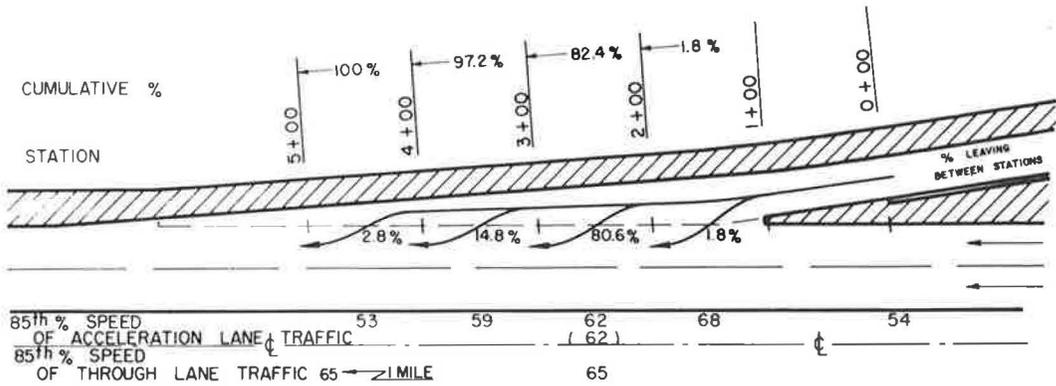


Figure 4. Speeds and lateral placement of passenger cars on type 1 acceleration lane, location Alb—Indiana Toll Road, Gary West Interchange, westbound traffic.

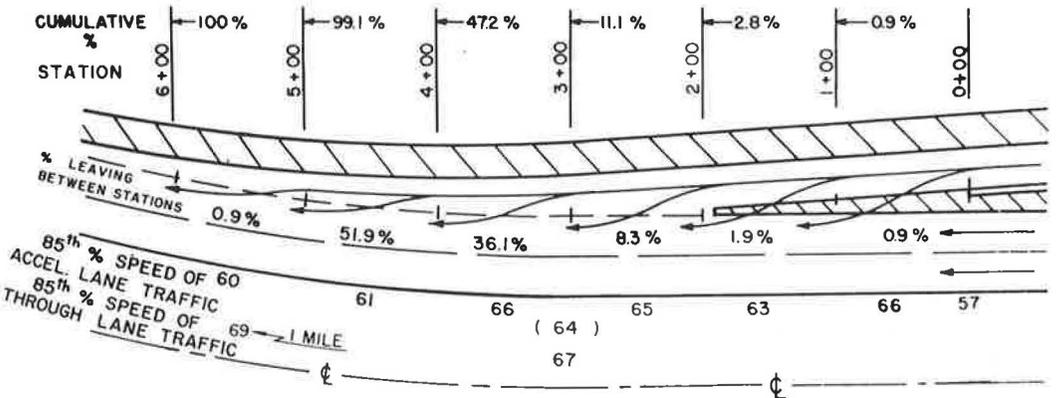
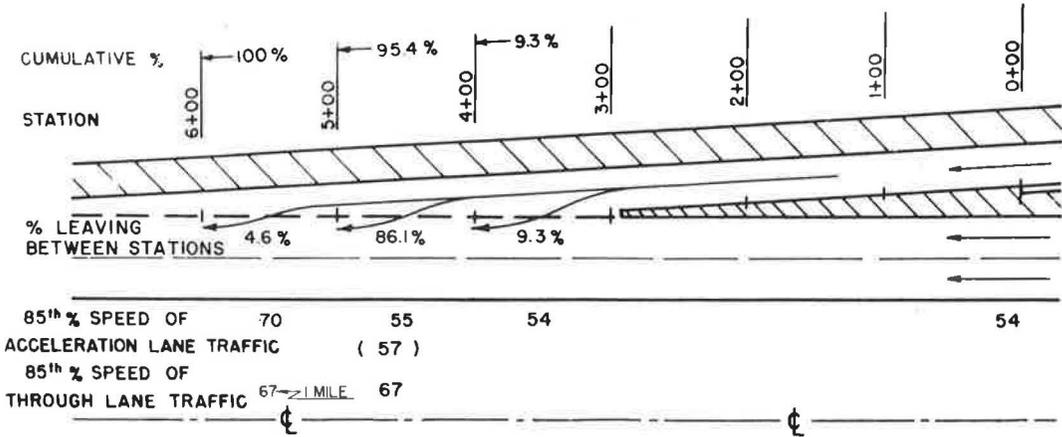


Figure 6. Speeds and lateral placement of passenger cars on type 1 acceleration lane, location Ald—Indiana Toll Road, Valparaiso Interchange, westbound traffic.

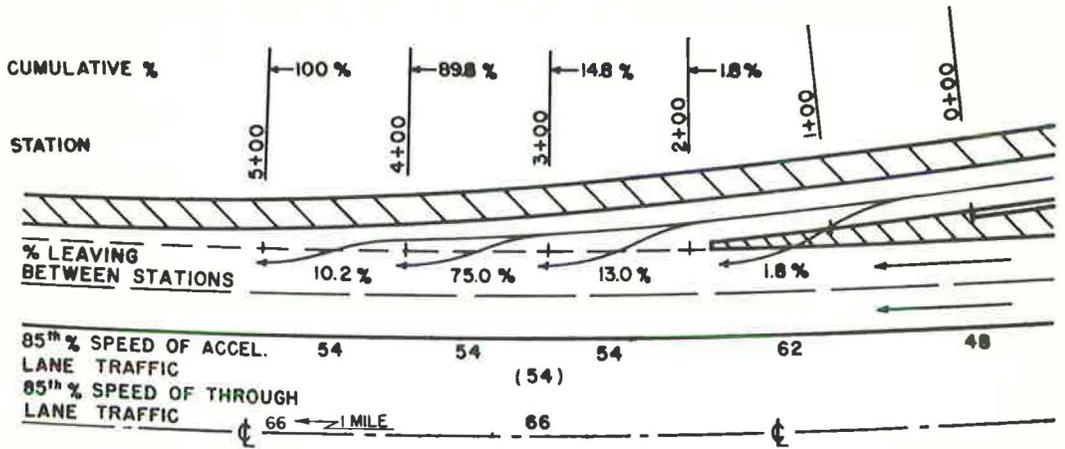


Figure 7. Speeds and lateral placement of passenger cars on type 1 acceleration lane, location Ale—Indiana Toll Road, LaPorte Interchange, westbound traffic.

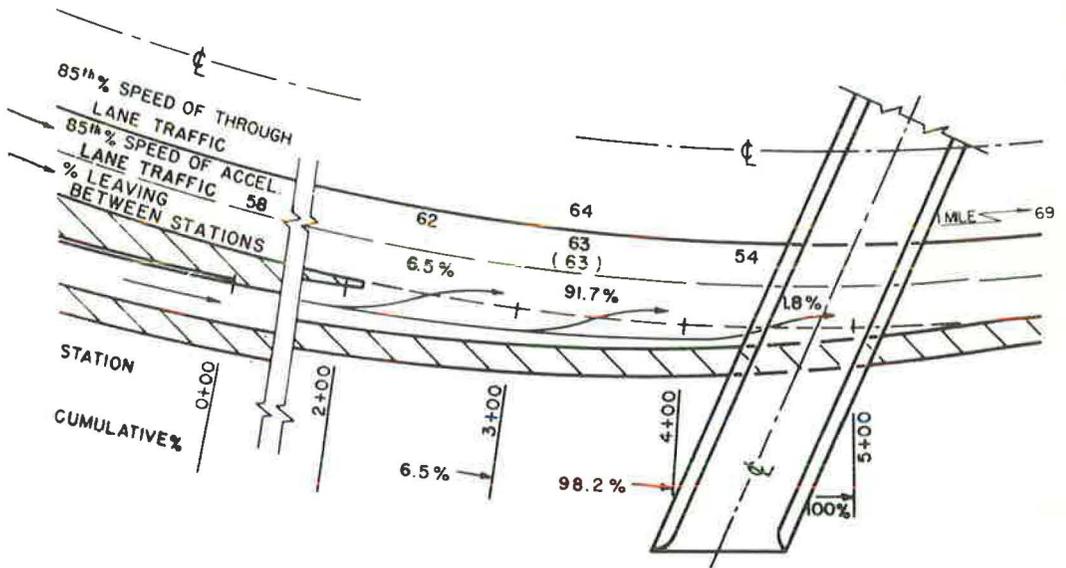


Figure 8. Speeds and lateral placement of passenger cars on type 1 acceleration lane, location Alf—Indiana Toll Road, Gary East Interchange, eastbound traffic.

age leaving at the end of each 100 ft are also given. The average 85th percentile speed of all vehicles using the acceleration lanes and at the time of their merging, except those that stopped, is shown by a number in parentheses; for example, (55). The 85th percentile speed for through lane traffic is given for a point within the area of merging and at a point approximately 1 mi from this area. All percentages of acceleration lane traffic used in this report are on the basis of the total number of passenger cars and light trucks using the lane which did not stop before entering the through lane.

The 85th percentile speed of acceleration lane traffic for location A1a at Station 0+00 was 48 mph (Fig. 3). The difference between the 85th percentile speed of through traffic within the area of conflict and the average 85th percentile speed of acceleration lane traffic as it merged into the through lane was 14 mph (69-55). This difference is

TABLE 2  
SUMMARY OF RESULTS—ACCELERATION LANES

Location	Fig. No.	Geometric Condition <sup>1</sup>	Type of Accel. Lane <sup>2</sup>	Annual Avg. Daily Traffic			85th Percentile Speed					Distance Beyond Point of Separation Within Which 90% of Accel. Lane Traffic Merged (ft)	Usable Length of Accel. Lane <sup>5</sup> (ft)	Length of Accel. Lane Unused by 90% of Through Lane Traffic (ft)	Accel. Lane Traffic That Stopped (%)	Was This Accel. Lane Used Satisfactorily as to	
				Accel. Lane	Through Lane	Station 0+00	Avg. Accel. Lane	Through Lane WAOC <sup>3</sup>	Speed Diff. <sup>4</sup>	Through Lane BAOC <sup>5</sup>	Speed Diff. <sup>4</sup>					Speed Placement	
A1a	3	1	1	620	3,720	48	55	69	14*	69	0	185	890	125	1.0	No	No
A1b	4	1	1	1,310	7,860	54	62	65	3	65	0	200	890	110	10.7	Yes	Yes
A1c	5	4	1	870	5,950	54	57	67	10*	67	0	200	890	110	1.8	No	Yes
A1d	6	2	1	650	6,420	57	64	67	3	69	2	260	890	60	3.6	Yes	Yes
A1e	7	5	1	1,230	5,030	48	54	66	12*	66	0	200	890	110	3.7	No	Yes
A1f	8	3	1	590	6,520	58	63	64	1	69	5*	190	890	120	0	Yes	Yes
A2a	10	1	2	260	4,550	42	47	66	19*	68	2	450	650	200	9.3	No	No
A2b	11	1	2	680	17,200	47	51	62	11*	62	0	500	650	150	16.0	No	No
A2c	12	1	2	1,130	3,030	55	55	61	6*	63	2	385	650	265	4.4	No	No
A2d	13	2	2	880	4,530	42	50	64	14*	58	-6*	600	650	50	14.3	No	No
A2e	14	3	2	1,380	4,170	44	46	66	20*	67	1	415	650	235	10.7	No	No
A3a	16	1	3	670	2,800	51	54	61	7*	65	4*	375	475	100	14.3	No	No
A3b	17	3	3	1,450	2,650	50	53	64	11*	63	1	365	475	110	3.6	No	No
A4a	19	1	4	1,960	23,730	44	48	60	12*	66	6*	135	250	115	34.6	No	No
A4b	20	2	4	3,880	21,620	41	45	60	15*	60	0	130	250	120	28.0	No	No

<sup>1</sup>Refers to condition given in Table 1.

<sup>2</sup>Refers to type given in Table 1.

<sup>3</sup>Within area of conflict.

<sup>4</sup>\* = significant.

<sup>5</sup>Beyond area of conflict.

<sup>6</sup>That length from end of ramp curve to where acceleration lane width is 6 ft wide.

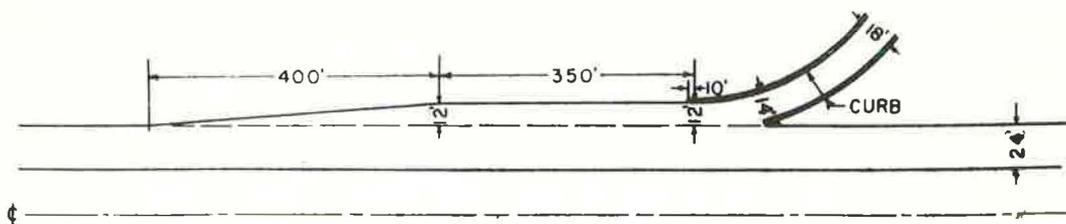


Figure 9. Acceleration lane, type 2.

statistically significant and indicates that much of the acceleration lane traffic did not accelerate to about the same speed as the through lane traffic before merging with it.

The difference between the 85th percentile speed of through lane traffic within the area of conflict and that beyond the area of conflict was zero (69-69).

Ninety percent of the traffic using the acceleration lane merged into the through lane before Station 4+50. This indicates that the majority of drivers merged within a distance of about 185 ft (4+50 - 2+65) beyond the point of separation of the acceleration lane from the through lane by means of the paved shoulder.

For this 52:1 taper design and at this location, the natural straight path of the left wheels of acceleration lane vehicles intersects the edge of the through lanes between Stations 4+00 and 5+00. Only 18.5 percent of acceleration lane traffic, however, merged in this area. The majority (79.6%) merged between Stations 3+00 and 4+00. It thus merged earlier than the natural straight path and at significantly lower speeds than through lane traffic.

A small percentage (1.9%) merged into the through lanes between Stations 5+00 and 6+00 at an 85th percentile speed of 51 mph. This small percentage of vehicles made use of a longer distance of the acceleration lane, and yet they merged at lower speeds than those at the previous indicated locations. The reason for this is either that these cars had to slow down due to conflicts with through traffic or that the drivers hesitated before merging due to inexperience in driving on high-type facilities or to not understanding the proper usage of acceleration lanes.

Of all vehicles using this acceleration lane, 1 percent stopped on the acceleration lane.

These results indicate that, at this location, this type of acceleration lane design was not being properly used by the majority of drivers.

**Type 2.**—The second type of acceleration lane studied is shown in Figure 9. The acceleration lane is of the parallel type having a full width lane for 350 ft plus 400 ft of taper. Five locations of this type of acceleration lane were studied. At three of the locations, the acceleration lane meets the through lane on a tangent; at the fourth location, on a right curve; and at the fifth location, on a left curve. Station 0+00 for this type of lane was taken to be at the nose. Beyond this point, acceleration lane traffic could merge into the through lane. The results of the speed and lateral placement studies of these five locations are shown in Figures 10 through 14.

**Type 3.**—The third type of acceleration lane studied is shown in Figure 15. The acceleration lane is of the parallel type having a full width lane of 250 ft plus 250 ft of taper.

Two locations of this type of acceleration lane were studied. At the first location, the acceleration lane meets the through lane on a tangent, and at the second, on a left curve. No suitable location could be found where the acceleration lane met the through lane on a right curve. Figures 16 and 17 show the results of the speed and lateral placement studies at these two locations.

**Type 4.**—The fourth type of acceleration lane studied is shown in Figure 18. This acceleration lane is of the taper design, but has only 300 ft of taper.

Two locations of this type were studied and both were at the same interchange. At the first location, the acceleration lane meets the through lane on a tangent, and at the second, on a right curve. No suitable location could be found where the acceleration

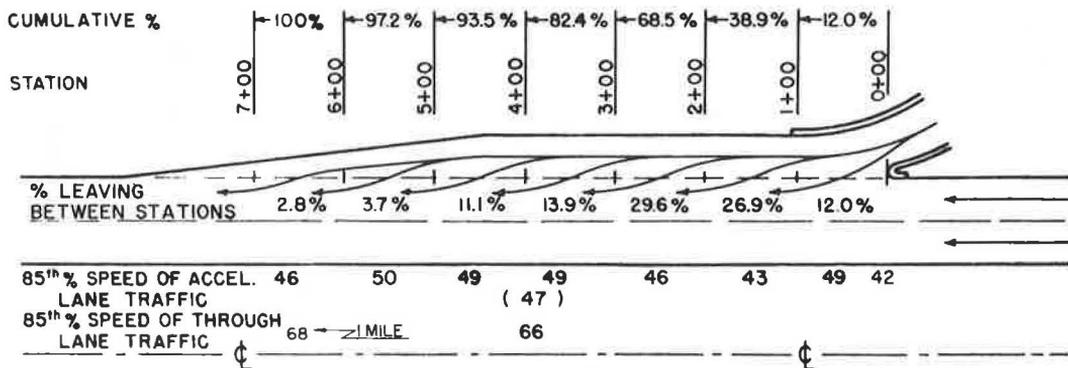


Figure 10. Speeds and lateral placement of passenger cars on type 2 acceleration lane, location A2a—Interstate 65, S. R. 39 Interchange, northbound traffic.

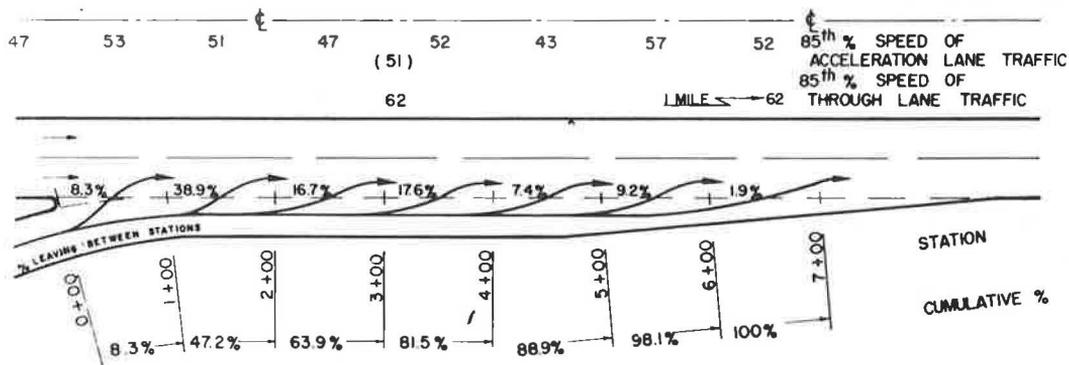


Figure 11. Speeds and lateral placement of passenger cars on type 2 acceleration lane, location A2b—Tri-State Highway, Kennedy Avenue Interchange, eastbound traffic.

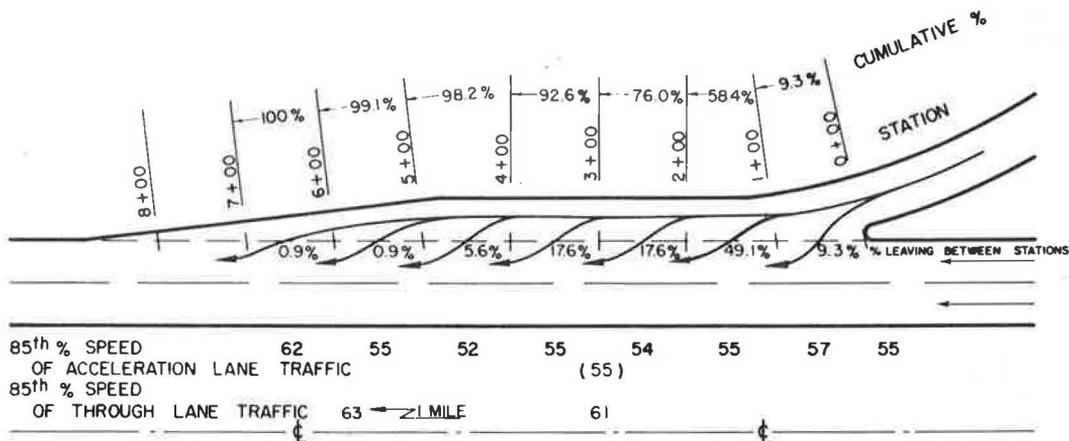


Figure 12. Speeds and lateral placement of passenger cars on type 2 acceleration lane, location A2c—Interstate 74, Post Road Interchange, eastbound traffic.

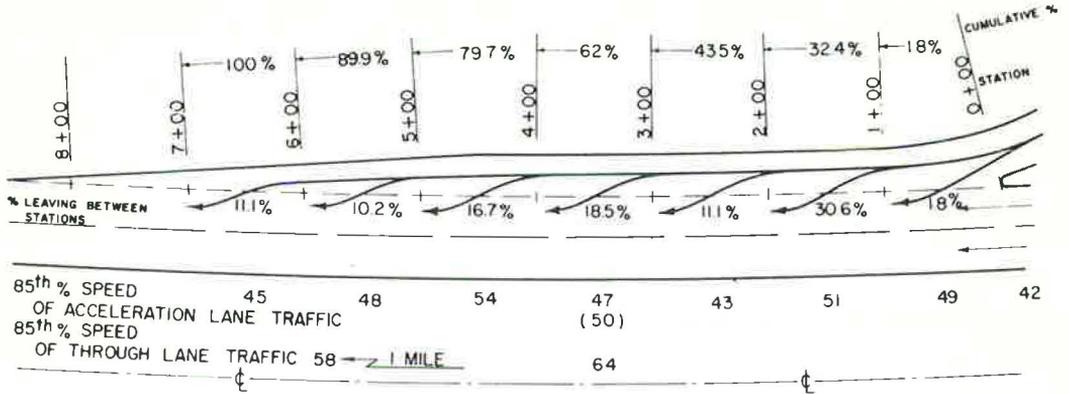


Figure 13. Speeds and lateral placement of passenger cars on type 2 acceleration lane, location A2d—Interstate 65, S. R. 60 Interchange, southbound traffic.

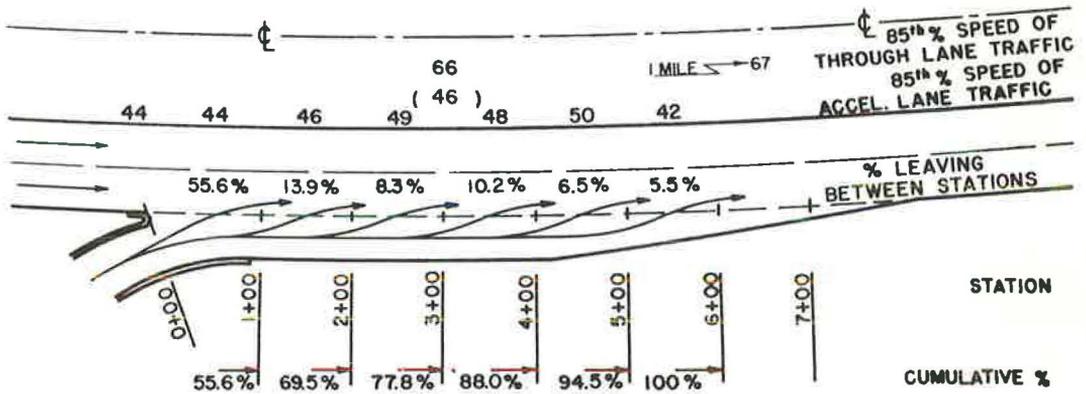


Figure 14. Speeds and lateral placement of passenger cars on type 2 acceleration lane, location A2e—Interstate 65, S. R. 39 Interchange, southbound traffic.

lane met the through lane on a left curve. Figures 19 and 20 show the results of the speed and lateral placement studies at these two locations.

Deceleration Lanes

The locations of the deceleration lanes studied are also shown in Figure 1, and pertinent data for each location are given in Table 3. These locations are referenced like those for acceleration lanes, except that the D stands for deceleration lanes.

Type 1.—The first type of deceleration lane studied was on the Indiana Toll Road (Fig. 21). The deceleration lane is 1,200 ft long from the right edge of the through lane to the beginning of the ramp curve. It consists of 845 ft of direct taper, having an angle of divergence of 1° 30 min with the through lanes. Along this distance, the deceleration lane is not separated from the through lane. It is then connected to a 356-ft direct taper, having an angle of divergence of 4° with the through lane. For this 356 ft, the deceleration lane is separated from the through lanes by a shoulder paved but of a different color than the traveled area. The exit nose is offset 6 ft from the edge of the through lane, and there are 173 ft of recovery.

Three locations were studied of this type of deceleration lane. At two of the locations,

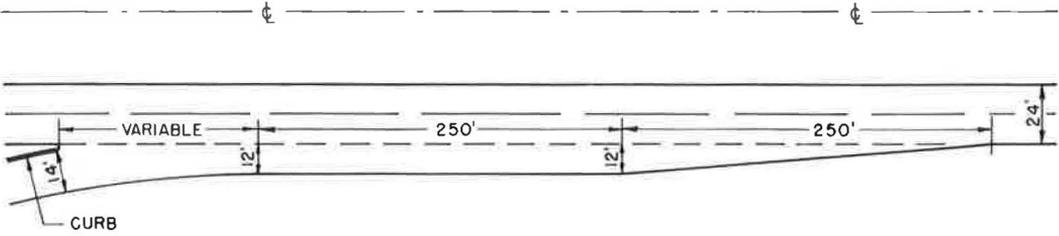


Figure 15. Acceleration lane, type 3.

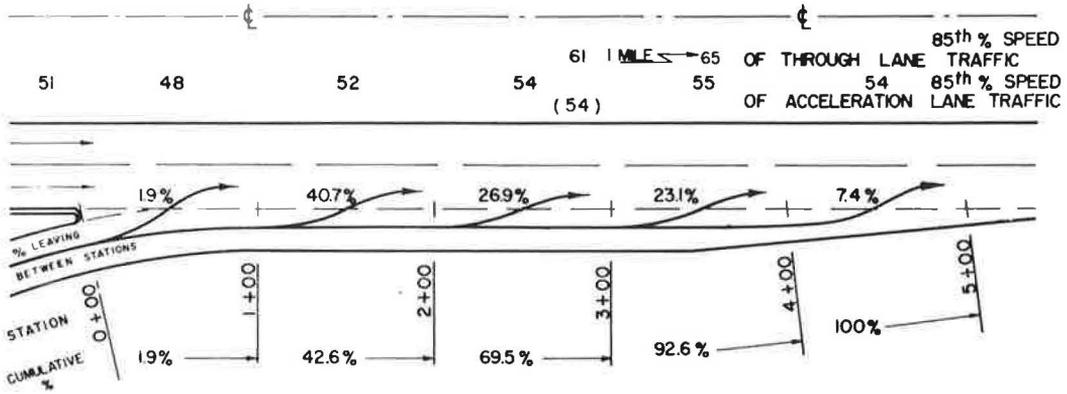


Figure 16. Speeds and lateral placement of passenger cars on type 3 acceleration lane, location A3a—Interstate 65, S. R. 56 Interchange, northbound traffic.

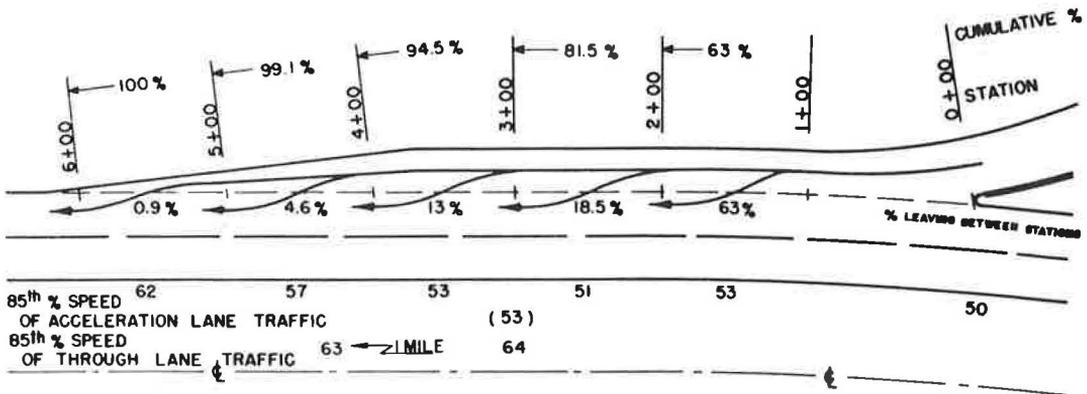


Figure 17. Speeds and lateral placement of passenger cars on type 3 acceleration lane, location A3b—Interstate 65, S. R. 334 Interchange, northbound traffic.

the deceleration lane leaves the through lanes on a tangent, and at the third, on a left curve. No suitable location could be found where the deceleration lane left the through lane on a right curve.

Station 0+00 was taken at the nose, which is the point where the paved shoulder that

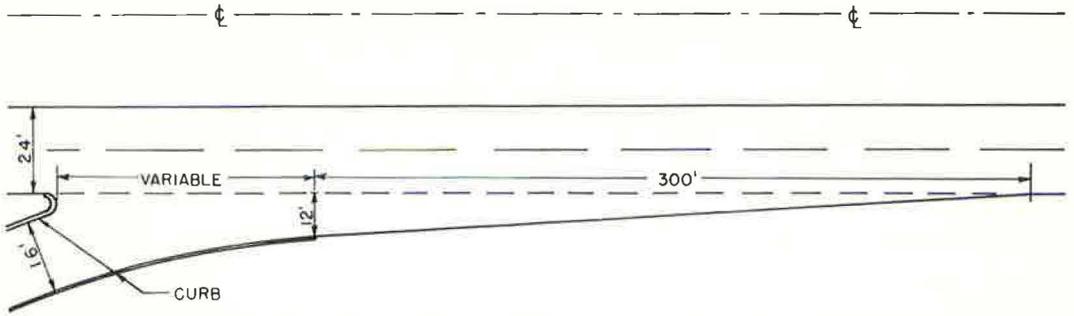


Figure 18. Acceleration lane, type 4.

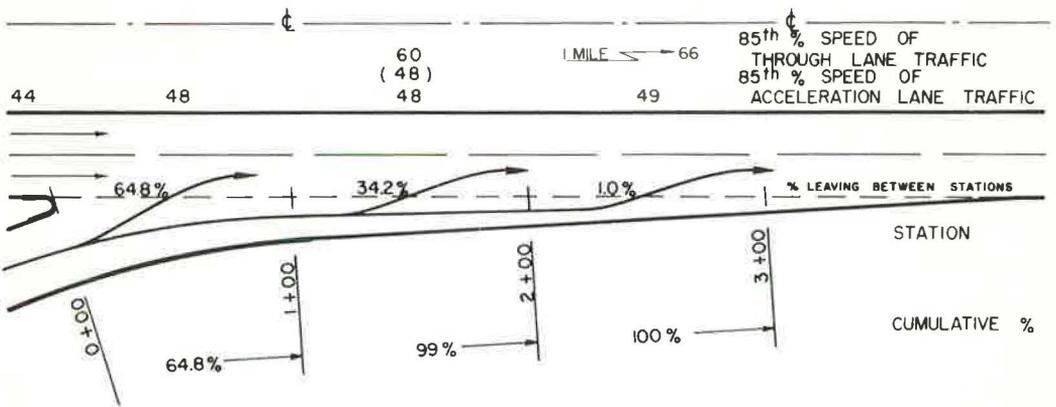


Figure 19. Speeds and lateral placement of passenger cars on type 4 acceleration lane, location A1a—Tri-State Highway, Calumet Ave. Interchange, eastbound traffic.

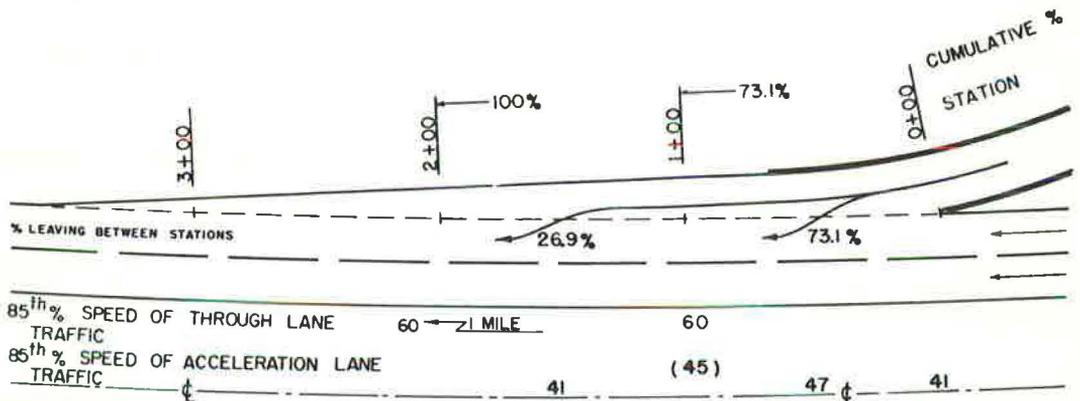


Figure 20. Speeds and lateral placement of passenger cars on type 4 acceleration lane, location A1b—Tri-State Highway, Calumet Ave. Interchange, westbound traffic.

separates the deceleration lane and the through lane begins. At the end of the deceleration lane and the beginning of the exit ramp there is an advisory speed sign, "Ramp Speed 25."

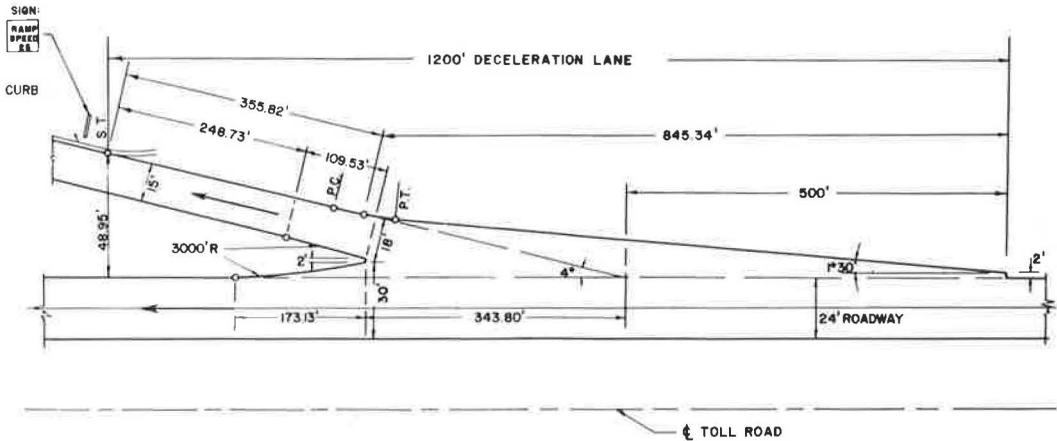


Figure 21. Deceleration lane, type 1.

TABLE 3  
STUDY LOCATION DATA—DECELERATION LANES

Reference	Location	Direction of Deceleration Lane Traffic	Geometric Condition		Deceleration Lane	
			Description	Type	Description	Type
D1a	Indiana Toll Road—Gary West	Eastbound	Tangent	1	Direct taper 1,200 ft	1
D1b	Michigan City	Westbound	Tangent	1	Direct taper 1,200 ft	1
D1c	Chesterton—Valparaiso	Eastbound	Left curve	3	Direct taper 1,200 ft	1
D2a	Interstate 65 and State Road 39	Southbound	Tangent	1	250-ft taper and 50-ft straight + curve	2
D2b	Tri-State and Kennedy Avenue	Westbound	Tangent	1	250-ft taper and 50-ft straight + curve	2
D2c	Interstate 65 and State Road 39	Northbound	Right curve	2	250-ft taper and 50-ft straight + curve	2
D3a	Interstate 74 and State Road 9	Eastbound	Tangent	1	Curve	3
D3b	Interstate 65 and State Road 334	Southbound	Right curve	2	Curve	3
D3c	Interstate 65 and State Road 60	Northbound	Left curve	3	Curve	3
D4a	Interstate 74 and Pleasant View	Eastbound	Tangent	1	Direct taper 400 ft	4
D5a	Tri-State and Calumet Avenue	Westbound	Tangent	1	Taper 200 ft + curves	5
D5b	Interstate 65 and State Road 56	Northbound	Tangent	1	Taper 250 ft + curves	5
D5c	Tri-State and Calumet Avenue	Eastbound	Left curve	3	Taper 200 ft + curves	5

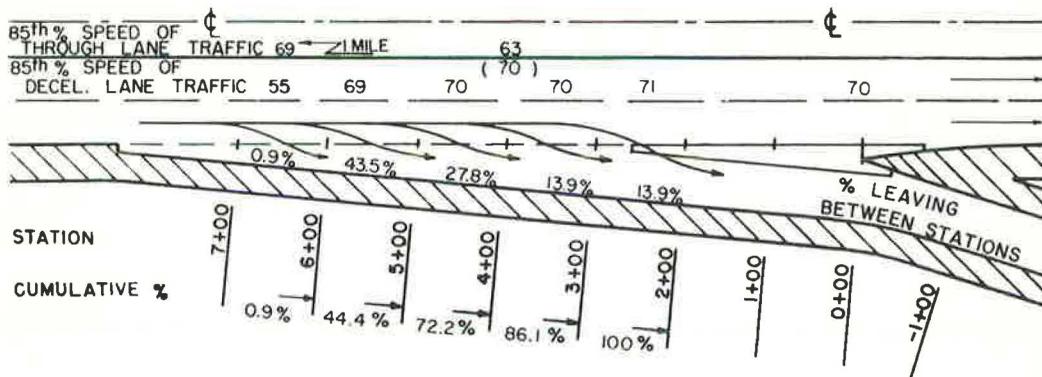


Figure 22. Speeds and lateral placement of passenger cars on type 1 deceleration lane, location D1a—Indiana Toll Road, Gary West Interchange, eastbound traffic.

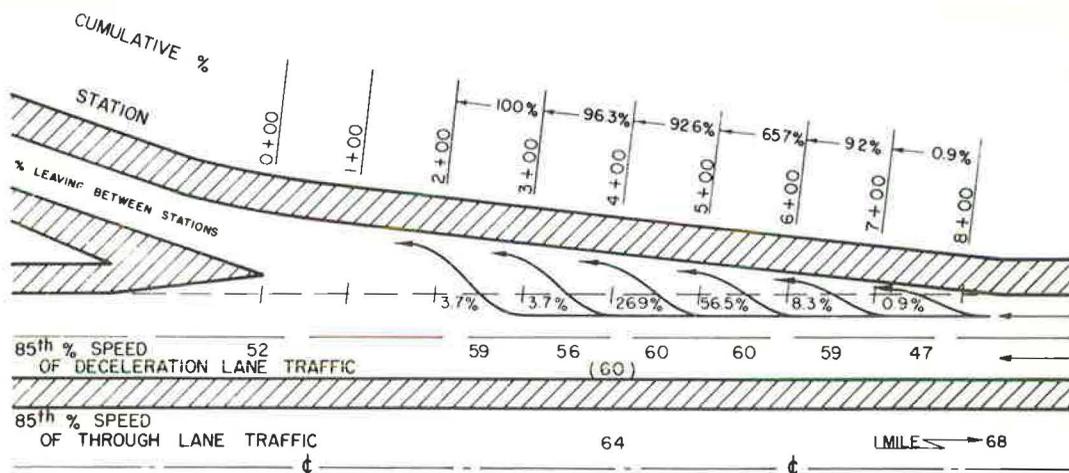


Figure 23. Speeds and lateral placement of passenger cars on type 1 deceleration lane, location D1b—Indiana Toll Road, Michigan City Interchange, westbound traffic.

Figures 22, 23, and 24 show the results of the speed and lateral placement studies at these three locations. The results at location D1c are described next as an example of how the information shown in the figures was analyzed. Also, summaries of the important deceleration lane characteristics and of the results obtained at each location studied are given in Table 4.

The deceleration lane leaves the through lane at location D1c on a left curve. The annual average daily traffic on the deceleration lane was 730 vehicles per day and on the through lanes eastbound was 6,630 vehicles per day.

The difference between the 85th percentile speed of through lane traffic within the area of conflict and the average 85th percentile speed of deceleration lane traffic as it diverged into the deceleration lane was 14 mph (69-55) (Fig. 24). This difference is significant, and indicates that most of this deceleration lane traffic started to decelerate on the through lane before diverging into the deceleration lane.

Because of the significant deceleration on the through lane at this location, a study was made as to where it occurred with respect to the beginning of the deceleration lane. Figure 25 shows for 200-ft intervals prior to the beginning of the deceleration lane the

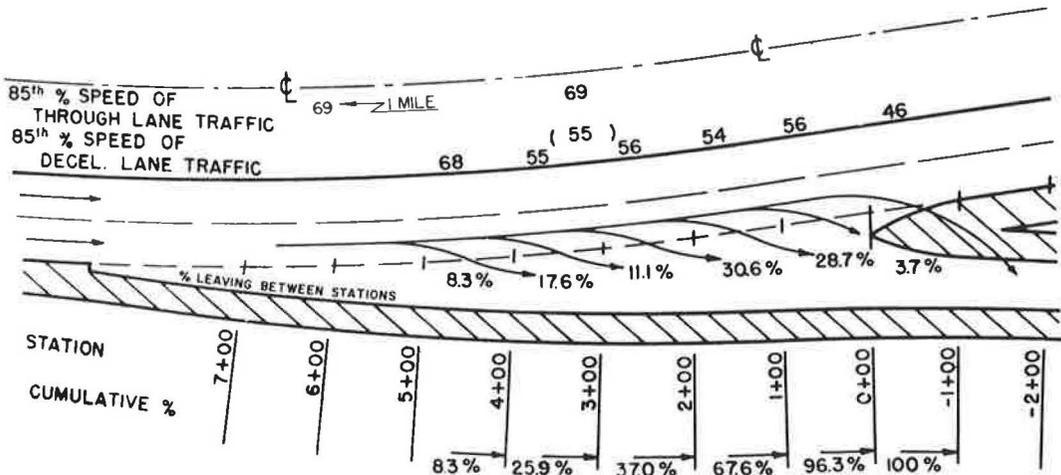


Figure 24. Speeds and lateral placement of passenger cars on type 1 deceleration lane, location Dlc—Indiana Toll Road, Chesterton-Valparaiso Interchange, eastbound traffic.

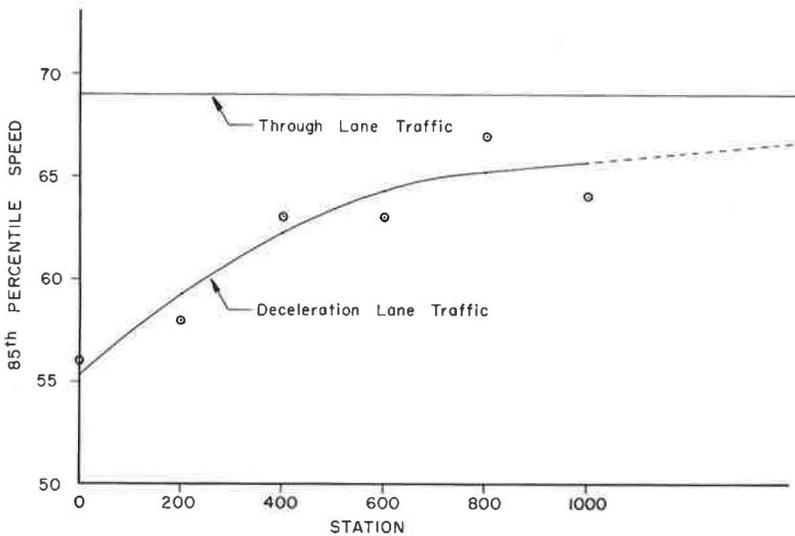


Figure 25. Determination of point where deceleration lane traffic begins to decelerate on through lane, location Dlc.

85th percentile speeds for the traffic that later entered the deceleration lane. Through traffic in this area was traveling at 69 mph. There is a clear indication that some of the traffic planning to use the deceleration lane at this location begins to decelerate well in advance (over 1,000 ft) of the deceleration lane.

The data in Figure 22, as well as that in similar figures for other deceleration lanes, are similar to that given for acceleration lanes, and explained earlier in this report.

Approximately 90 percent of the drivers using the deceleration lane diverged within a distance of approximately 400 ft.

The natural straight path of exit of the left wheels of the vehicles, which was taken as a line parallel to but offset by a distance of 3 ft from that path joining the point of beginning of the deceleration lane with the end point of the deceleration lane at the nose (Station 0+00), intersects the through lane between Station 4+00 and 5+00, where only

TABLE 4  
SUMMARY OF RESULTS—DECELERATION LANES

Location	Figure No.	Geometric Condition <sup>1</sup>	Type of Decel. Lane <sup>2</sup>	Annual Avg. Daily Traffic		85th Percentile Speed						Distance Within Which 90% of Decel. Lane Traffic Diverged in (ft)	Usable Length of Decel. Lane <sup>5</sup> (ft)	Length of Decel. Lane Not Used by 90% of Traffic (ft)	Was This Decel. Lane Used Satisfactorily as to	
				Decel. Lane	Through Lane	Station 0+00	Avg. Decel. Lane	Through Lane WAOC <sup>3</sup>	Speed Diff. <sup>4</sup>	Through Lane BAOC <sup>5</sup>	Speed Diff. <sup>4</sup>				Speed	Placement
D1a	22	1	1	1,460	7,680	70	70	63	-7*	69	6*	300	990	50	Yes	Yes
D1b	23	1	1	310	5,910	52	60	64	4*	68	4*	300	990	30	No	Yes
D1c	24	3	1	720	6,630	46	55	69	14*	69	0	400	990	230	No	No
D2a	27	1	2	240	4,170	49	49	67	18*	68	1	200	370	120	No	No
D2b	28	1	2	1,430	16,790	41	46	60	14*	63	3*	200	370	75	No	No
D2c	29	2	2	1,060	4,550	46	50	68	18*	70	2	200	370	90	No	No
D3a	31	1	3	—	—	46	51	62	11*	65	3*	100	150	0	No	Yes
D3b	32	2	3	1,010	3,230	50	54	65	11*	67	2	100	150	0	No	Yes
D3c	33	3	3	930	4,740	54	55	60	5*	60	0	200	300	25	No	Yes
D4a	37	1	4	250	3,780	50	57	63	6*	63	0	200	308	20	No	Yes
D5a	39	1	5	4,100	21,820	32	46	63	17*	62	1	100	240	40	No	Yes
D5b	40	1	5	770	2,800	51	56	64	8*	67	3	100	340	50	No	Yes
D5c	41	3	5	1,830	23,530	35	42	61	19*	60	1	100	240	50	No	Yes

<sup>1</sup>Refers to geometric condition given in Table 3.

<sup>2</sup>Refers to type given in Table 3.

<sup>3</sup>Within area of conflict.

<sup>4</sup>\* = significant.

<sup>5</sup>Beyond area of conflict.

<sup>6</sup>That length from beginning of ramp curve to where deceleration lane width is 6 ft wide.

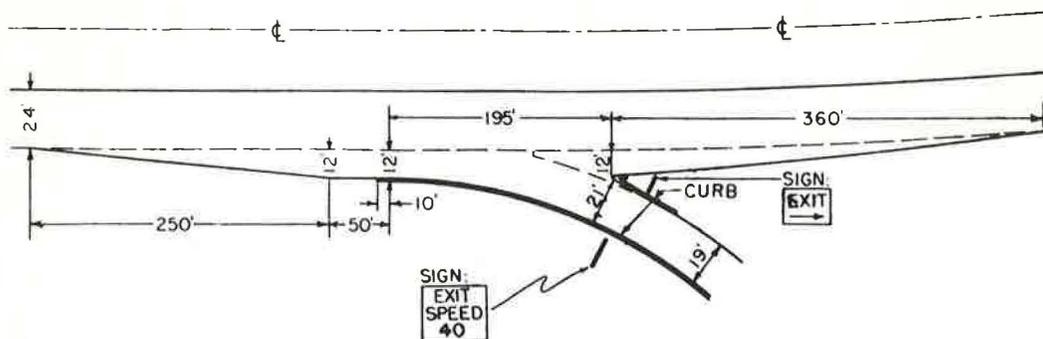


Figure 26. Deceleration lane, type 2.

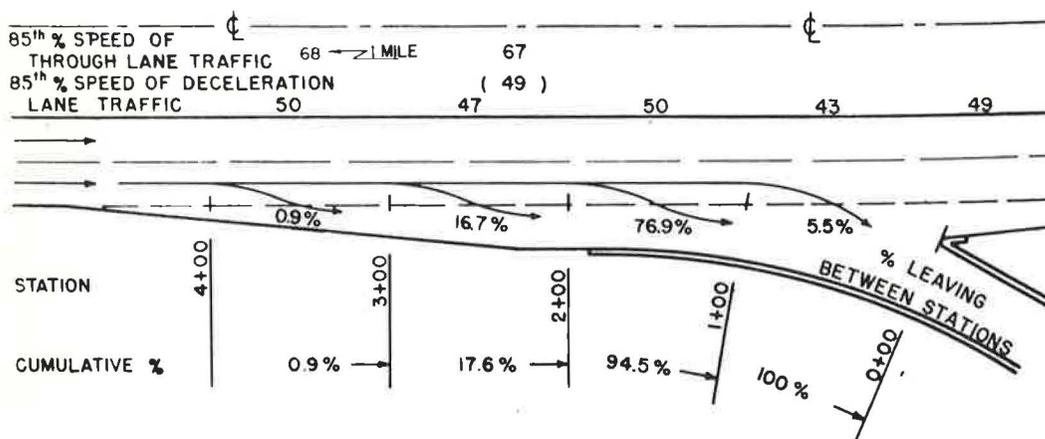


Figure 27. Speeds and lateral placement of passenger cars on type 2 deceleration lane, location D2a—Interstate 65, State Route 39 Interchange, southbound traffic.

a small percentage (8.3%) of deceleration lane traffic diverged at an 85th percentile speed of 68 mph. Most of the remaining drivers diverged later and at lower speeds, thus indicating deceleration on the through lane instead of on the deceleration lane. This could have been aggravated by the effect of the left curve.

A small percentage (3.7%) of deceleration lane traffic crossed the paved shoulder and diverged between Stations 0+00 and 1+00 at an 85th percentile speed of 46 mph. This speed is lower than that of other observed deceleration lane traffic, and this might have been caused by these drivers hesitating on the through lane and making the decision at the last minute to leave at this interchange.

These results indicate that drivers were not properly using the deceleration lane at this location for this roadway geometry and this type of deceleration lane design.

**Type 2.**—The second type of deceleration lane studied is shown in Figure 26. The deceleration lane has a taper from 0 to 12 ft in a distance of 250 ft, followed by 50 ft of tangent and 195 ft of curve. Near the exit nose there is a regulatory speed sign, "Exit Speed 40." Three locations of this type of deceleration lane were studied. At two of the locations, the deceleration lane leaves the through lane on a tangent, and at the third, on a right horizontal curve. No suitable location could be found where the deceleration lane left the through lane on a left curve. Station 0+00 was taken at the nose of the deceleration lane. The results of the speed and lateral placement studies at these locations are shown in Figures 27, 28, and 29.

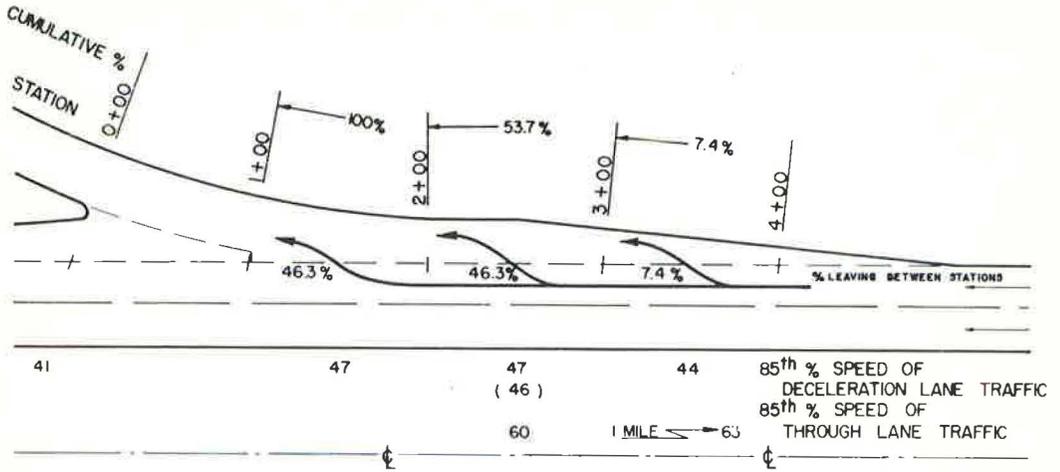


Figure 28. Speeds and lateral placement of passenger cars on type 2 deceleration lane, location D2b—Tri-State Highway and Kennedy Avenue Interchange, westbound traffic.

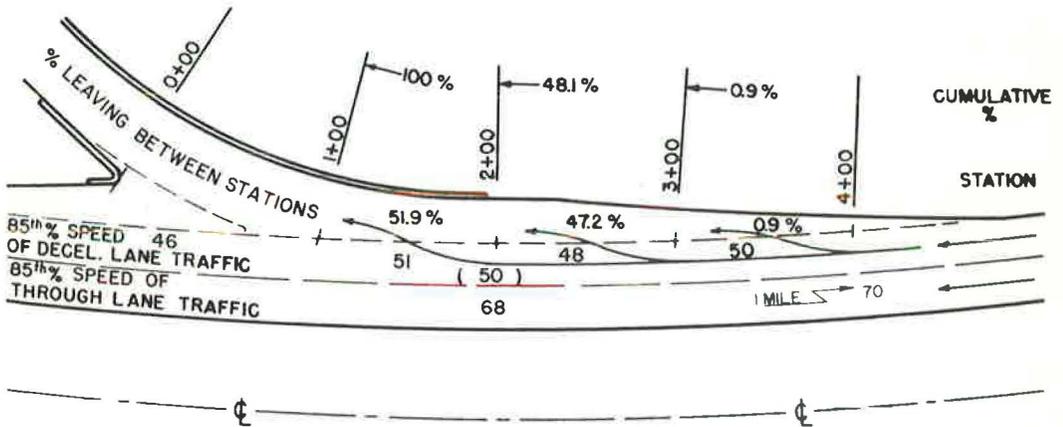


Figure 29. Speeds and lateral placement of passenger cars on type 2 deceleration lane, location D2c—Interstate 65, State Route 39 Interchange, northbound traffic.

Type 3.—The third type of deceleration lane studied is shown in Figure 30. The deceleration lane in this design is a curve of varying degrees of curvature. Near the nose there is a regulatory speed sign, "Exit Speed 40."

Three locations were studied of this type of deceleration lane. At the first location, the deceleration lane leaves the through lane on a tangent; at the second, on a right curve; and at the third, on a left curve. The results of the speed and lateral placement studies at these three locations are shown in Figures 31, 32, and 33. Figures 34 and 35 show the results of a study at two of these locations where the distance prior to the beginning of the deceleration lane and in which the deceleration occurred was determined.

Type 4.—The fourth type of deceleration lane studied is shown in Figure 36. The deceleration lane in this design is a direct taper 400 ft long. Near the exit nose, there is a regulatory speed sign, "Exit Speed 40."

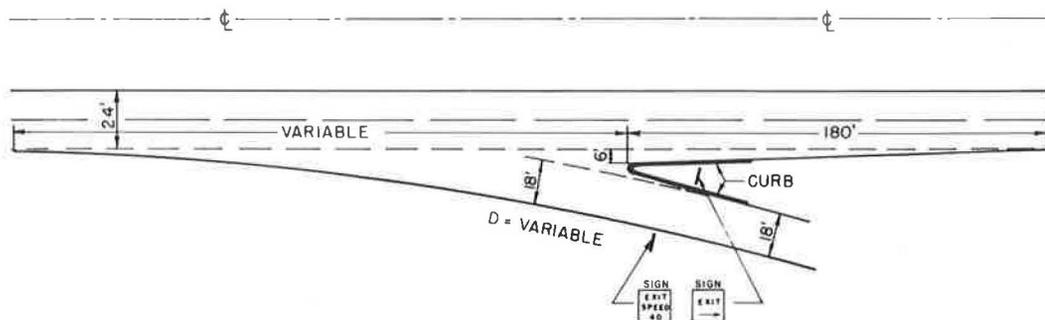


Figure 30. Deceleration lane, type 3.

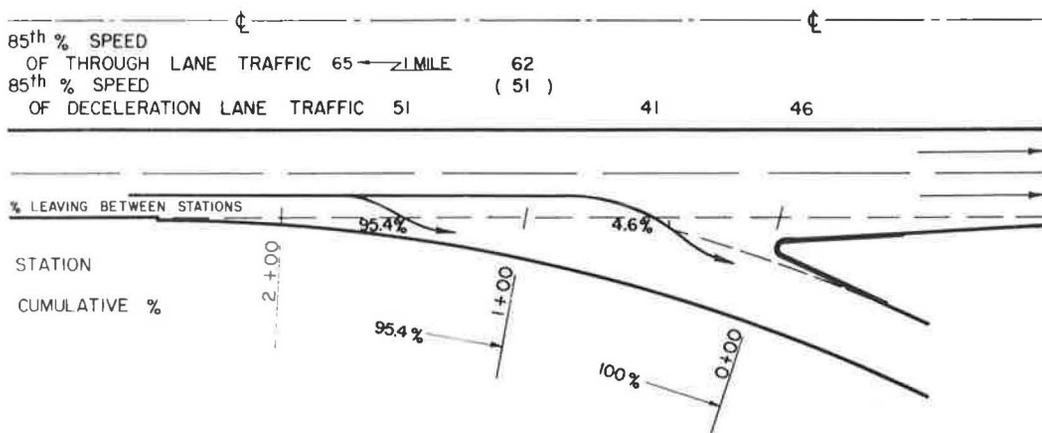


Figure 31. Speeds and lateral placement of passenger cars on type 3 deceleration lane, location D3a—Interstate 74, S. R. 9 Interchange, eastbound traffic.

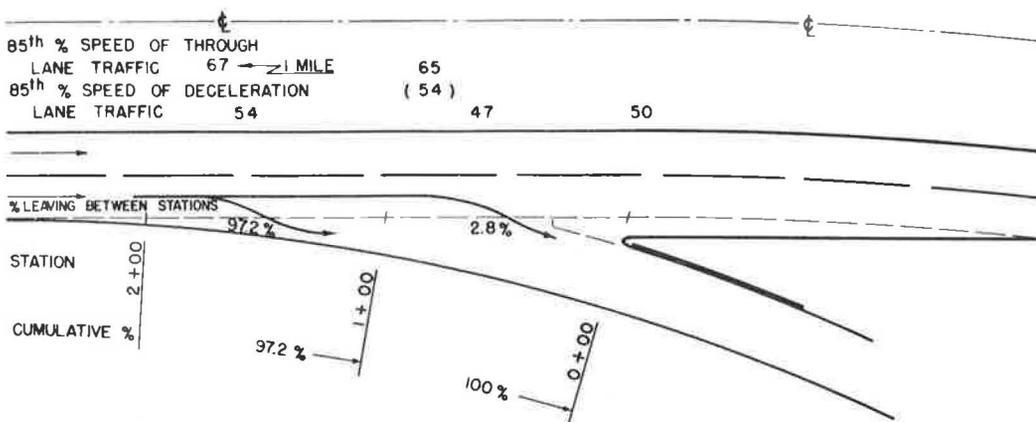


Figure 32. Speeds and lateral placement of passenger cars on type 3 deceleration lane, location D3b—Interstate 65 and S. R. 334 Interchange, southbound traffic.

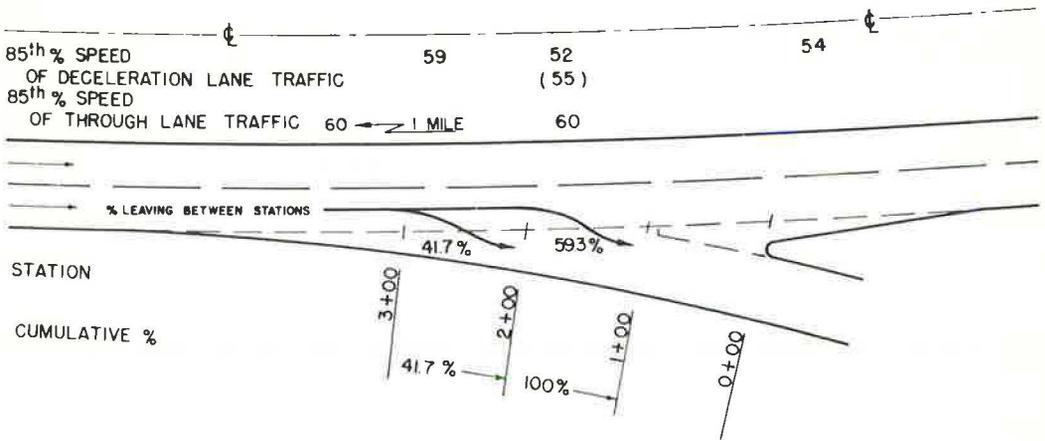


Figure 33. Speeds and lateral placement of passenger cars on type 3 deceleration lane, location D3c—Interstate 65 and S. R. 60 Interchange, northbound traffic.

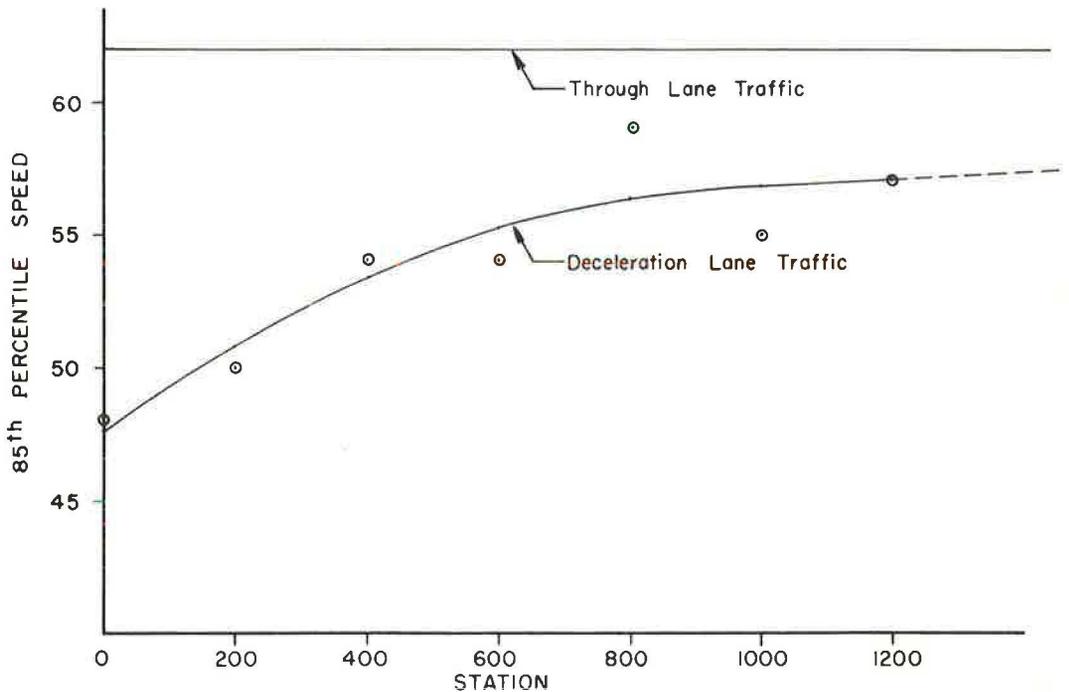


Figure 34. Determination of point where deceleration lane traffic begins to decelerate on through lane, location D3a.

Only one location was studied of this type of deceleration lane as it was the only one completed as of the date of this study. Figure 37 shows the results of the speed and lateral placement study at this location.

Type 5. — The fifth type of deceleration lane studied is shown in Figure 38. The deceleration lane in this design is a variable distance, direct taper followed by a curve. Near the exit nose, there is a regulatory speed sign, "Exit Speed 40."

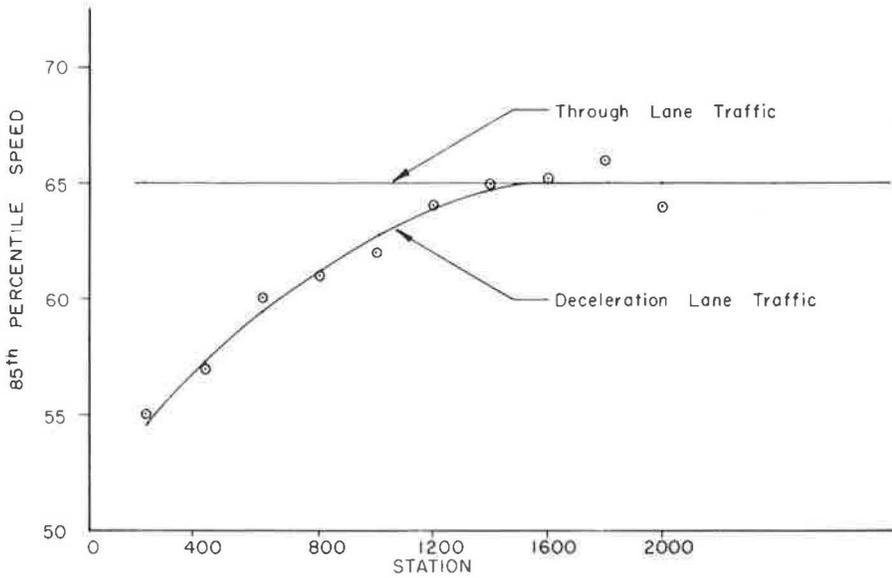


Figure 35. Determination of point where deceleration lane traffic begins to decelerate on through lane, location D3b.

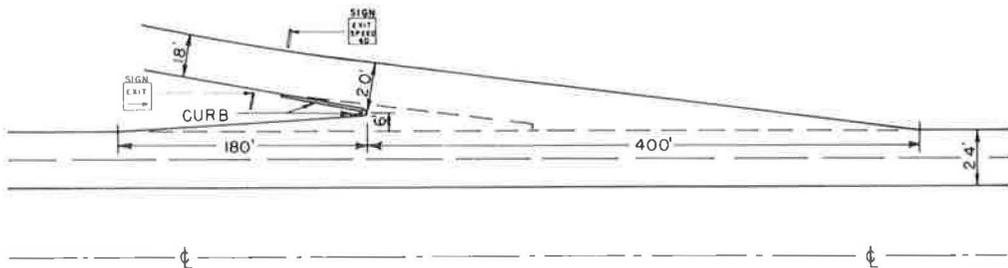


Figure 36. Deceleration lane, type 4.

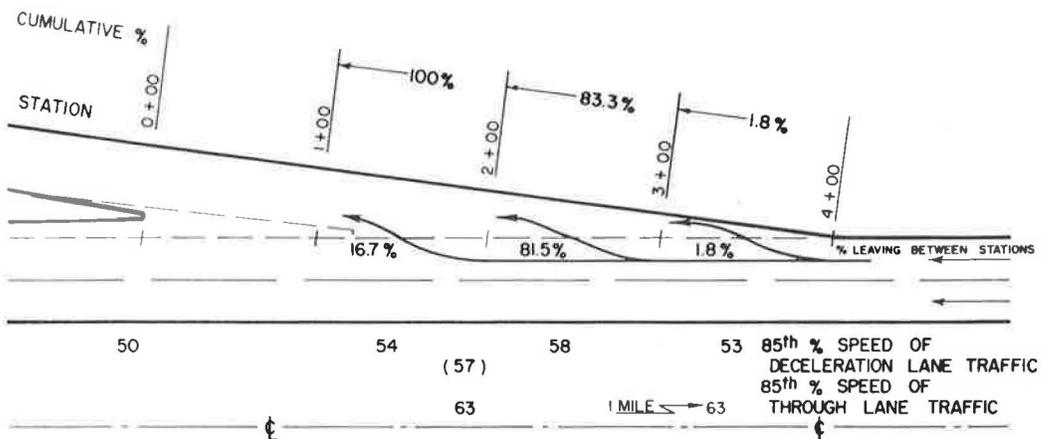


Figure 37. Speeds and lateral placement of passenger cars on type 4 deceleration lane, location D4a—Interstate 74, Pleasant View Interchange, eastbound traffic.

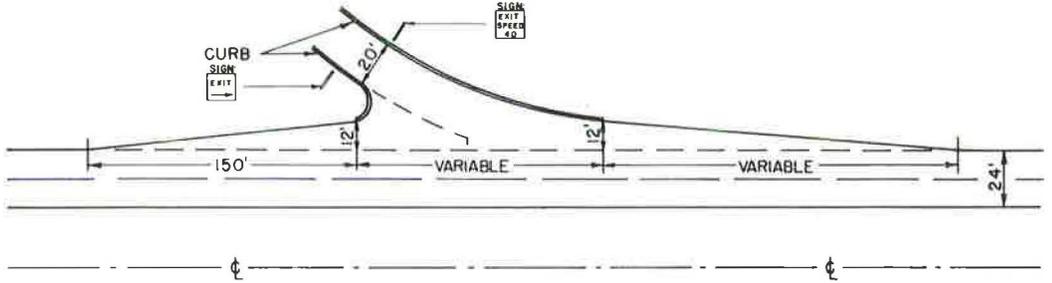


Figure 38. Deceleration lane, type 5.

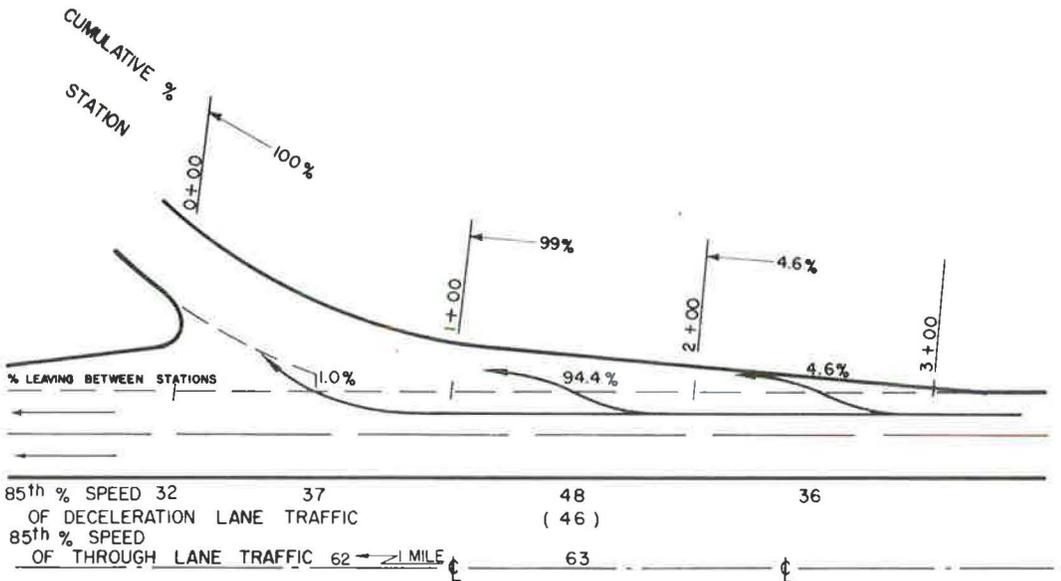


Figure 39. Speeds and lateral placement of passenger cars on type 5 deceleration lane, location D5a—Tri-State Highway and Calumet Avenue Interchange, westbound traffic.

Three locations were studied of this type of deceleration lane. At the first two locations, the deceleration lanes leave the through lanes on a tangent, and at the third, on a left curve. At the first and third locations, the length of the tangent section is 200 ft and the length of the curve portion to the nose is 139 ft, whereas at the second location, these lengths are 250 and 217 ft, respectively. Figures 39, 40, and 41 show the results of the speed and lateral placement studies at these three locations.

### SUMMARY AND FINDINGS

Summaries of the important acceleration lane characteristics and of the results obtained at each location studied are given in Table 2. A similar table for the deceleration lanes studied is Table 4. These two tables provide a comparison of the use characteristics found on the various designs and permit a rather rapid comparison of the various designs.

The behavior of vehicles on acceleration and deceleration lanes as found and reported in the figures and tables indicates the following:

General

1. There were large differences in speed between acceleration or deceleration lane traffic at the time of merging or diverging, respectively, and that of the through lanes on many of the highway sections studied. It is obvious that better use of these and similar facilities that will be constructed is desirable.

2. A large number of motorists apparently do not know how to use acceleration and deceleration lanes properly. Thus, for the most efficient and safest operation of traffic, it is imperative that the driving public be better informed on the proper use of acceleration and deceleration lanes. It is recommended that all the interested agencies of the city, State, and Federal governments recognize their responsibilities in this area and formulate at an early date a program of education directed toward the proper use of acceleration and deceleration lanes.

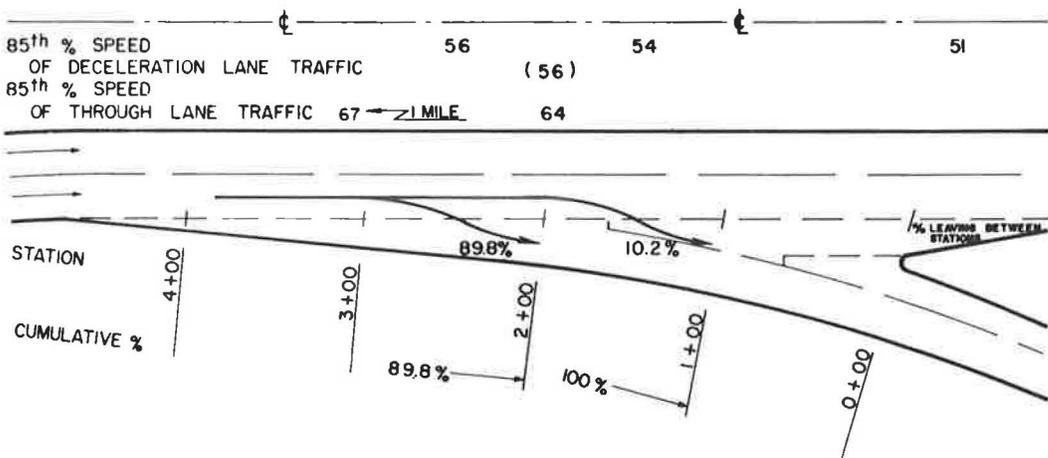


Figure 40. Speeds and lateral placement of passenger cars on type 5 deceleration lane, location D5b—Interstate 65 and S. R. 56 Interchange, northbound traffic.

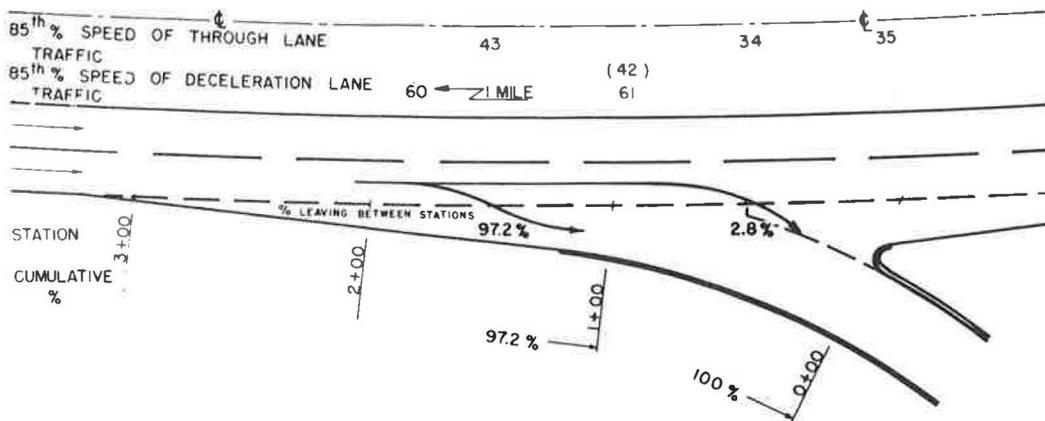


Figure 41. Speeds and lateral placement of passenger cars on type 5 deceleration lane, location D5c—Tri-State Highway and Calumet Avenue Interchange, eastbound traffic.

To facilitate this education of the driving public in the use of such lanes and to eliminate much of the confusion that motorists now exhibit, some standardization of design for acceleration and deceleration lanes should be adopted, at least within the same geographic region. The Indiana State Highway Commission has already constructed three different designs of acceleration lanes and four different designs of deceleration lanes on the Interstate sections that have been opened to traffic. On some of these sections, the design varies from one interchange to the next.

3. The use results were not similar at all locations for acceleration and deceleration lanes having the same design and operating under the same roadway geometry. This indicates that other factors, such as types of driver using the lanes and traffic volume, had a significant bearing on the results.

4. Acceleration or deceleration lane traffic had little effect on the speed of through traffic at interchanges where acceleration and deceleration lanes were studied in this research. At only 8 of the 28 acceleration and deceleration lane locations studied was the difference between the 85th percentile speed of the through lane traffic within the area of conflict and that beyond the area of conflict statistically significant. Drivers slowed at 7 of these locations and traveled faster at the eighth. The change in speed was never greater than 6 mph. At some of the locations where the speed effect was significant, other factors, such as a narrow median or a horizontal curve, probably contributed to the changes in speed.

5. For the best use for both acceleration and deceleration lanes at an interchange location, it is desirable to have the through lanes, at the location of the acceleration or deceleration lanes, on a tangent.

#### Acceleration Lanes

1. A higher percentage of drivers utilized more length of the acceleration lane when the acceleration lane met the through lane on a right curve, and less length of the acceleration lane when it met the through lane on a left curve, than under the condition where the acceleration lane met the through lane on a tangent.

2. On the four acceleration lane designs studied, the long direct taper type of design with separation from the through lanes for approximately 500 ft was found to be the only type where most drivers tended to approach the optimum condition of operation for acceleration lanes.

3. For the long direct taper design, a high percentage of drivers followed a natural straight path from the beginning of the acceleration lane at the end of the ramp curve until they merged into the through lanes. Some control, such as a curb, appeared to be desirable beyond the end of the ramp curve to align some motorists properly in a straight path, and thus prevent too early a merging at too low a speed into the through lane.

4. For the long direct taper type of design studied, most drivers merged (left rear wheel entered through lane) within a maximum distance of 260 ft beyond the nose.

5. Most drivers tended to merge soon after entering all parallel acceleration lanes studied and at too low a speed. A longer length of the parallel portion of the acceleration lane did not show better usage than a shorter length.

6. Most drivers tended to merge as soon as possible and at too low a speed on the short taper design acceleration lanes which had no separation from the through lanes.

#### Deceleration Lanes

1. A higher percentage of drivers utilized less length of the deceleration lane and diverged later at lower speeds, thereby decelerating more on the through lane, when the deceleration lane left the through lane on a left curve than when the deceleration lane left the through lane on a right curve or tangent.

2. Most drivers at most locations studied did not obey the regulatory speed signs (Exit Speed 40) placed near the nose of the deceleration lane on the Interstate sections. It is suggested that this regulatory speed sign be changed to an advisory ramp speed sign with the numerical value the safe design speed of the exit ramp and placed so as to permit comfortable deceleration to this safe speed.

3. At all but one of the locations studied, much of the deceleration lane traffic started to decelerate on the through lane before diverging into the deceleration lane. The results further show that many drivers began to decelerate well in advance (more than 1,000 ft) of the beginning of the deceleration lane.

4. Of the five types of design studied, the long direct taper type of deceleration lane with separation of the lane from the through lane for about 300 ft (as on the Indiana Toll Road) was found to be the best. On this design, most drivers tended to approach the optimum condition of operation for deceleration lanes.

5. Most drivers on the deceleration lanes studied desired to follow a natural straight path of exit with a minimum of maneuvering.

6. Ninety percent of the drivers diverging onto a deceleration lane did so within a maximum distance of 300 ft, except for one case where the lane was on a left horizontal curve.

7. The curve type design for deceleration lanes tended to provide good usage throughout the length of the lane, but most drivers decelerated considerably before entering lanes of this design.

8. Most drivers tended to decelerate appreciably on the through lane where a short direct taper design was used.

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