

Lecture # 8

Wind driven circulation

Elementarstromsystem
 Ekman transport
 Ekman pumping
 Sverdrup transport
 Sverdrup meets Ekman

Wind driven circulation

Elementarstromsystem

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- ▶ now include also pressure gradient $\nabla_h p$
- ▶ momentum equation in vector form for $Ro \ll 1$

$$f \mathbf{k} \times \mathbf{u} = -\frac{1}{\rho_0} \nabla_h p + \frac{1}{\rho_0} \frac{\partial \boldsymbol{\tau}}{\partial z} \quad \text{with} \quad \mathbf{k} \times \mathbf{u} = (-v, u, 0)$$

- ▶ $\boldsymbol{\tau} = (\tau^x, \tau^y)$ is a stress vector with $\boldsymbol{\tau}(z=0) = \boldsymbol{\tau}^a$ where $\boldsymbol{\tau}^a$ is the surface wind stress in N/m^2 acting on the ocean
- ▶ split the flow into geostrophic and frictional (Ekman) components, $\mathbf{u} = \mathbf{u}_G + \mathbf{u}_E$ (and $w = w_G + w_E$), governed by

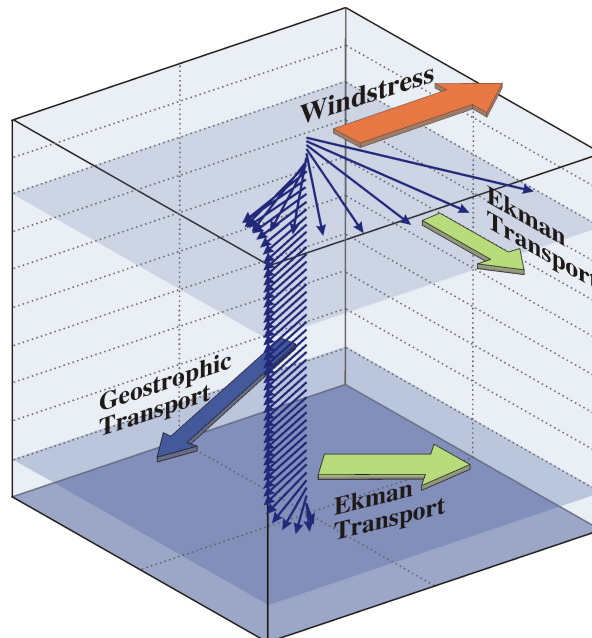
$$f \mathbf{k} \times \mathbf{u}_G = -\frac{1}{\rho_0} \nabla_h p \quad \text{and} \quad f \mathbf{k} \times \mathbf{u}_E = \frac{1}{\rho_0} \frac{\partial \boldsymbol{\tau}}{\partial z}$$

and the same for continuity equation

$$\nabla \cdot \mathbf{u}_G + \frac{\partial w_G}{\partial z} = 0 \quad \text{and} \quad \nabla \cdot \mathbf{u}_E + \frac{\partial w_E}{\partial z} = 0$$

- ▶ sum $\mathbf{u}_G + \mathbf{u}_E$ satisfies full momentum and continuity equation

- ▶ Elementarstromsystem (for $\rho = \text{const}$)
- ▶ $\mathbf{u} = \mathbf{u}_G + \mathbf{u}_E$ (and $w = w_G + w_E$)
surface and bottom Ekman layers superimposed on geostrophic flow



- ▶ vertically integrated velocity

$$\mathbf{U} = \int_{-h}^0 \mathbf{u} dz = \int_{-h}^0 (\mathbf{u}_G + \mathbf{u}_E) dz = \mathbf{U}_G + \mathbf{U}_E$$

- ▶ with the (total) transport vector \mathbf{U} , dimension m^2s^{-1}
- ▶ transport by the geostrophic velocity \rightarrow geostrophic transport \mathbf{U}_G
transport by the Ekman velocity \rightarrow Ekman transport \mathbf{U}_E

$$f\mathbf{k} \times \mathbf{u}_E = \frac{1}{\rho_0} \frac{\partial \tau}{\partial z}$$

$$f\mathbf{k} \times \int_{-h}^0 \mathbf{u}_E dz = \frac{1}{\rho_0} (\tau(z=0) - \tau(z=-h))$$

$$f\mathbf{k} \times \mathbf{U}_E = \frac{1}{\rho_0} (\tau^a - \tau_b)$$

with surface wind stress τ^a and bottom stress τ_b

- ▶ with $\mathbf{k} \times (\mathbf{k} \times \mathbf{U}) = \mathbf{k} \times (-V, U, 0) = (-U, -V, 0) = -\mathbf{U}$

$$\mathbf{U}_E = -\frac{1}{f\rho_0} \mathbf{k} \times (\tau^a - \tau_b)$$

- ▶ split \mathbf{U}_E into surface and bottom Ekman transport

- ▶ vertically integrated velocity $\mathbf{U} = \mathbf{U}_G + \mathbf{U}_E$ with geostrophic transport \mathbf{U}_G and Ekman transport \mathbf{U}_E given by

$$\mathbf{U}_E = -\frac{1}{f\rho_0} \mathbf{k} \times (\boldsymbol{\tau}^a - \boldsymbol{\tau}_b) \equiv \mathbf{U}_E^{top} + \mathbf{U}_E^{bot}$$

with surface wind stress $\boldsymbol{\tau}^a$ and bottom stress $\boldsymbol{\tau}_b$

- ▶ split into surface Ekman transport in surface Ekman layer

$$\mathbf{U}_E^{top} = -\frac{1}{f\rho_0} \mathbf{k} \times \boldsymbol{\tau}^a$$

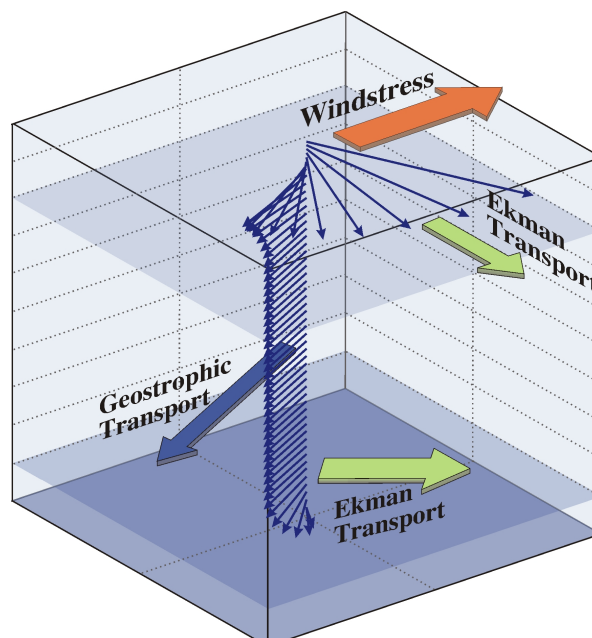
orthogonal to wind stress direction (to the right for $f > 0$)
does not depend on parameterisation of $\boldsymbol{\tau}$ in the interior

- ▶ and bottom Ekman transport in bottom Ekman layer

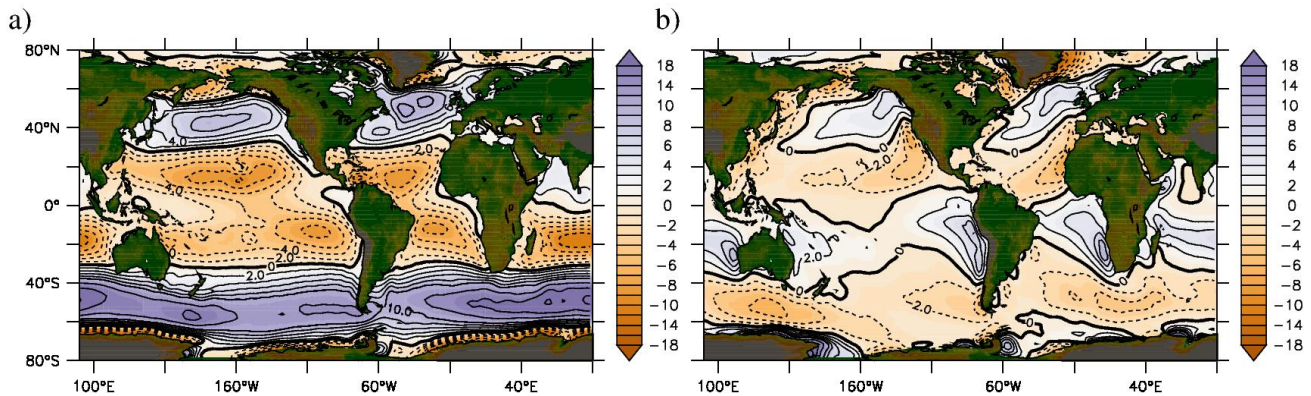
$$\mathbf{U}_E^{bot} = \frac{1}{f\rho_0} \mathbf{k} \times \boldsymbol{\tau}_b$$

depends on parameterisation of $\boldsymbol{\tau}$ in the interior

- ▶ Elementarstromsystem
- ▶ $\mathbf{u} = \mathbf{u}_G + \mathbf{u}_E$ (and $w = w_G + w_E$)
surface and bottom Ekman layers superimposed on geostrophic flow



- ▶ zonal (left) and meridional component (right) of τ^a in 10^{-2} N/m^2



- ▶ surface Ekman transport in surface Ekman layer

$$\mathbf{U}_E^{top} = -\frac{1}{f\rho_0} \mathbf{k} \times \boldsymbol{\tau}^a$$

orthogonal to wind stress direction (to the right for $f > 0$)

- ▶ equatorward in west wind region poleward in trade wind region
- ▶ convergence between west wind and trade wind region
- ▶ divergence at high latitude and at equator

- ▶ momentum equation in vector form for $Ro \ll 1$

$$f \mathbf{k} \times \mathbf{u} = -\frac{1}{\rho_0} \nabla_h p + \frac{1}{\rho_0} \frac{\partial \boldsymbol{\tau}}{\partial z} \quad \text{with} \quad \mathbf{k} \times \mathbf{u} = (-v, u, \emptyset)$$

- ▶ $\boldsymbol{\tau} = (\tau^x, \tau^y)$ is a stress vector with $\boldsymbol{\tau}(z=0) = \boldsymbol{\tau}^a$ where $\boldsymbol{\tau}^a$ is the surface wind stress in N/m^2 acting on the ocean
- ▶ split the flow into geostrophic and frictional (Ekman) components, $\mathbf{u} = \mathbf{u}_G + \mathbf{u}_E$ (and $w = w_G + w_E$), governed by

$$f \mathbf{k} \times \mathbf{u}_G = -\frac{1}{\rho_0} \nabla_h p \quad \text{and} \quad f \mathbf{k} \times \mathbf{u}_E = \frac{1}{\rho_0} \frac{\partial \boldsymbol{\tau}}{\partial z}$$

and the same for continuity equation

$$\nabla \cdot \mathbf{u}_G + \frac{\partial w_G}{\partial z} = 0 \quad \text{and} \quad \nabla \cdot \mathbf{u}_E + \frac{\partial w_E}{\partial z} = 0$$

- ▶ sum $\mathbf{u}_G + \mathbf{u}_E$ satisfies full momentum and continuity equation

- ▶ integrating the continuity equation for \mathbf{u}_E and w_E from z to $z = 0$

$$\nabla \cdot \mathbf{u}_E + \frac{\partial w_E}{\partial z} = 0$$

yields the vertical Ekman velocity

$$\int_z^0 \nabla \cdot \mathbf{u}_E dz + \cancel{w_E(z=0)} - w_E(z) = 0 \rightarrow w_E(z) = \nabla \cdot \int_z^0 \mathbf{u}_E dz$$

- ▶ Ekman velocity is given by

$$\mathbf{u}_E = D/(2A_v) e^{z/D} ((\boldsymbol{\tau}_a - \mathbf{k} \times \boldsymbol{\tau}_a) \cos(z/D) + (\boldsymbol{\tau}_a + \mathbf{k} \times \boldsymbol{\tau}_a) \sin(z/D))$$

- ▶ since $\mathbf{u}_E \approx 0$ below Ekman depth $D \approx 50$ m

$$w_E|_{z < -D} \approx \nabla \cdot \int_{z < -D}^0 \mathbf{u}_E dz = \nabla \cdot \mathbf{U}_E^{top} = -\nabla \cdot \frac{1}{f\rho_0} \mathbf{k} \times \boldsymbol{\tau}^a = \mathbf{k} \times \nabla \cdot \frac{\boldsymbol{\tau}^a}{\rho_0 f}$$

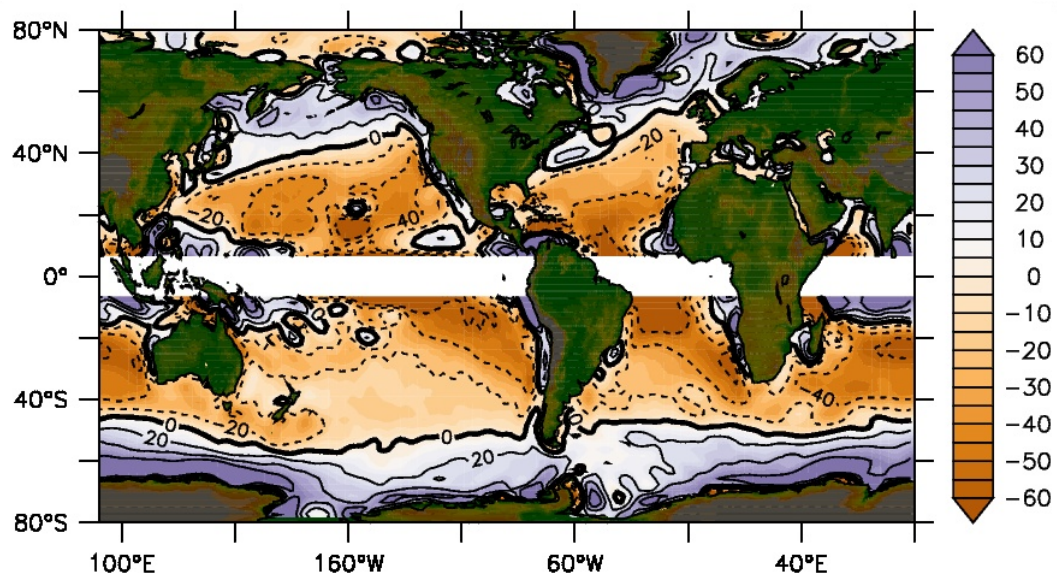
with Ekman pumping $w_E|_{z < -D}$ and

$$\begin{aligned} \mathbf{k} \times \nabla \cdot \boldsymbol{\tau} &= \begin{pmatrix} -\frac{\partial}{\partial y} \\ \frac{\partial}{\partial x} \end{pmatrix} \cdot \begin{pmatrix} \tau^{(x)} \\ \tau^{(y)} \end{pmatrix} = -\frac{\partial}{\partial y} \tau^{(x)} + \frac{\partial}{\partial x} \tau^{(y)} \\ &= \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix} \cdot \begin{pmatrix} \tau^{(y)} \\ -\tau^{(x)} \end{pmatrix} = \nabla \cdot (-\mathbf{k} \times \boldsymbol{\tau}) \end{aligned}$$

- ▶ Ekman pumping w_E in m per year

$$w_E|_{z < -D} \approx \nabla \cdot \mathbf{U}_E^{top} = \mathbf{k} \times \nabla \cdot \frac{\boldsymbol{\tau}^a}{\rho_0 f}$$

with Ekman depth $D \approx 50$ m (depends on A_v)



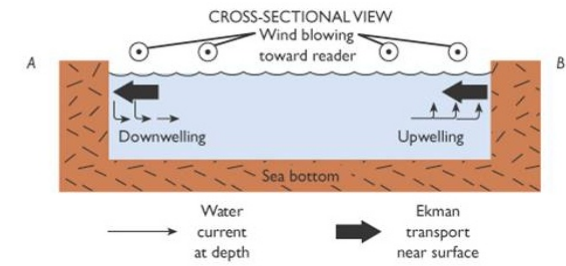
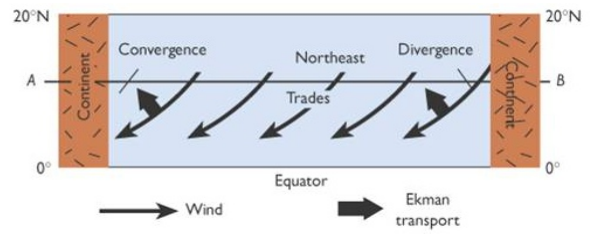
- ▶ Ekman transport \mathbf{U}_E^{top} and pumping w_E do not depend on A_v

- ▶ Ekman pumping w_E

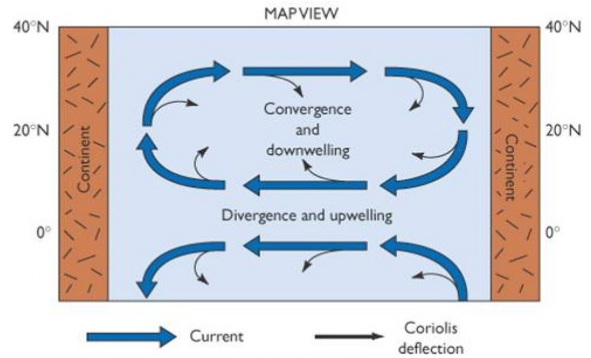
$$w_E|_{z < -D} \approx \nabla \cdot \mathbf{U}_E^{top}$$

i.e. w_E from divergence of Ekman transport

- ▶ $w_E > 0$: Upwelling
 - ▶ subpolar gyre
 - ▶ at eastern boundaries
 - ▶ at equator
- ▶ $w_E < 0$: Downwelling
 - ▶ subtropical gyres

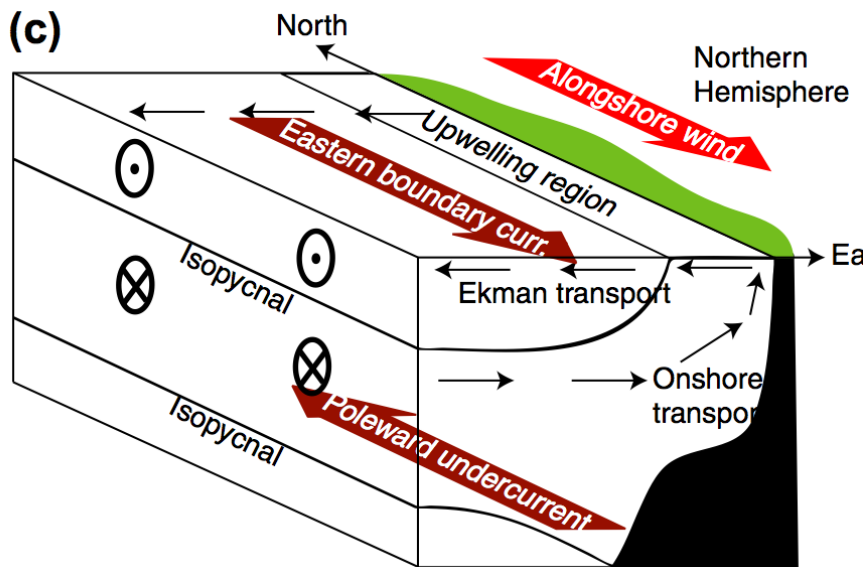


(a) COASTAL DIVERGENCE AND CONVERGENCE



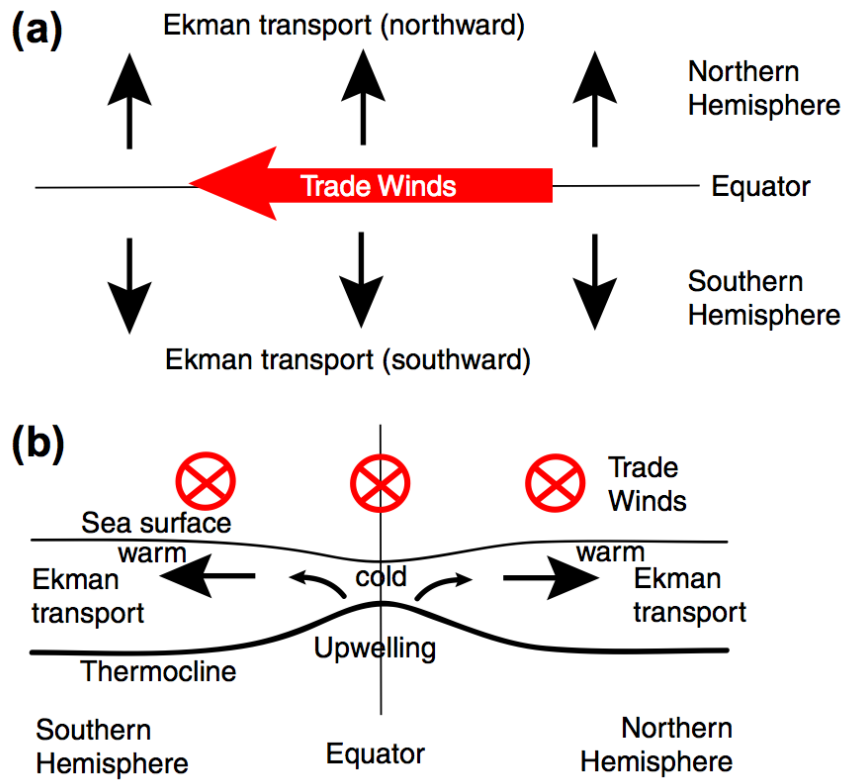
(b) OCEAN DIVERGENCE AND CONVERGENCE

- ▶ coastal upwelling

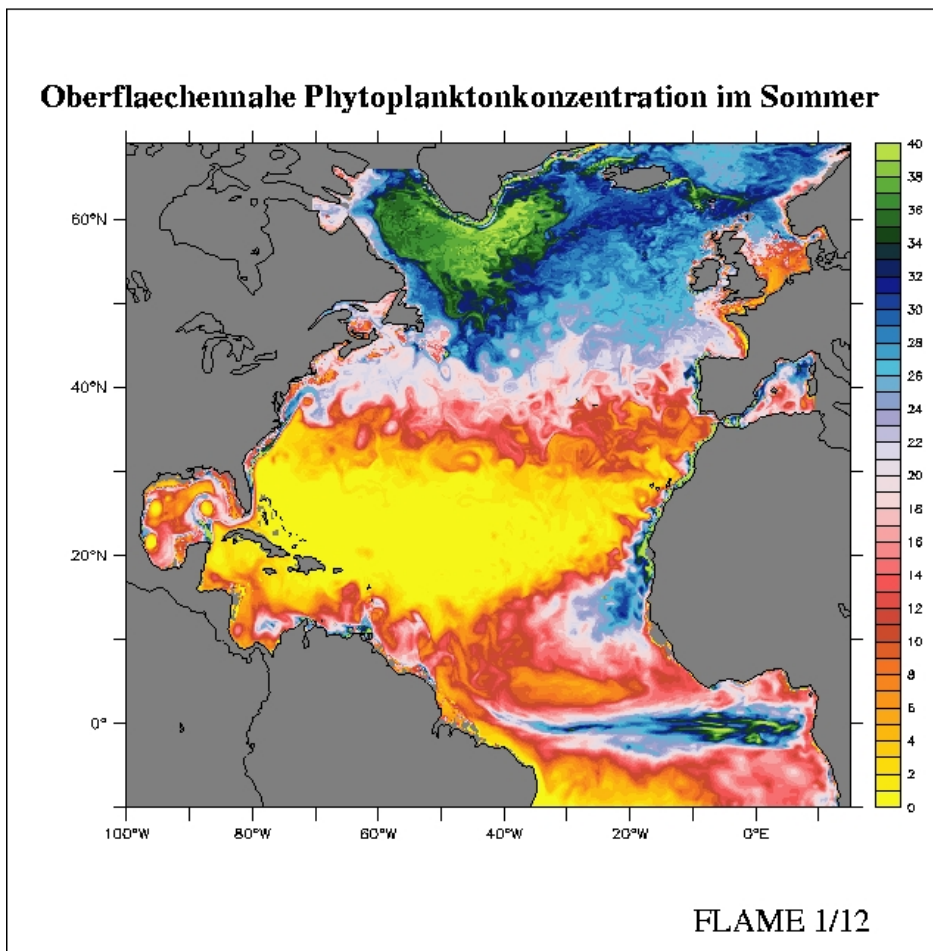


from Talley et al 2011

▶ equatorial upwelling



from Talley et al 2011



- ▶ momentum equation for $Ro \ll 1$

$$f \mathbf{k} \times \mathbf{u} = -\frac{1}{\rho_0} \nabla_h p + \frac{1}{\rho_0} \frac{\partial \tau}{\partial z} \quad \text{with } \mathbf{k} \times \mathbf{u} = (-v, u, 0)$$

- ▶ neglect sea surface height $z = \zeta \rightarrow$ assume rigid lid at $z = 0$
- ▶ assume flat bottom at $z = -h = \text{const}$
- ▶ vertically integrate momentum equation from bottom to surface

$$\rho_0 f \mathbf{k} \times \mathbf{U} = -\nabla_h \int_{-h}^0 p dz + \tau_a - \tau_b$$

with transport $\mathbf{U} = \int_{-h}^0 \mathbf{u} dz$, surface and bottom stress τ_a and τ_b

- ▶ take curl which yields (after a little calculation)

$$\rho_0 \beta V + \rho_0 f \nabla_h \cdot \mathbf{U} = \mathbf{k} \times \nabla \cdot (\tau_a - \tau_b)$$

with $\beta = df/dy$

- ▶ since $\nabla_h \cdot \mathbf{U} = 0$ from continuity equation $\nabla_h \cdot \mathbf{u} + \partial w / \partial z = 0$ it follows the famous Sverdrup relation

$$\rho_0 \beta V = \mathbf{k} \times \nabla \cdot (\tau_a - \tau_b)$$

- ▶ little calculation: curl of vertically integrated momentum equation

$$\rho_0 f \mathbf{k} \times \mathbf{U} = -\nabla_h \int_{-h}^0 p dz + \tau_a - \tau_b$$

- ▶ rewrite component wise

$$-\rho_0 f V = -\frac{\partial}{\partial x} \int_{-h}^0 p dz + \tau_a^x - \tau_b^x, \quad \rho_0 f U = -\frac{\partial}{\partial y} \int_{-h}^0 p dz + \tau_a^y - \tau_b^y$$

- ▶ $\partial/\partial y$ of 1. equation minus $\partial/\partial x$ of 2. equation

$$\begin{aligned} -\frac{\partial}{\partial y}(\rho_0 f V) &= -\frac{\partial^2}{\partial x \partial y} \int_{-h}^0 p dz + \frac{\partial}{\partial y}(\tau_a^x - \tau_b^x) \\ \rho_0 f \frac{\partial U}{\partial x} &= -\frac{\partial^2}{\partial x \partial y} \int_{-h}^0 p dz + \frac{\partial}{\partial x}(\tau_a^y - \tau_b^y) \\ -\rho_0 \frac{df}{dy} V - \rho_0 f \frac{\partial V}{\partial y} - \rho_0 f \frac{\partial U}{\partial x} &= \frac{\partial}{\partial y}(\tau_a^x - \tau_b^x) - \frac{\partial}{\partial x}(\tau_a^y - \tau_b^y) \\ -\rho_0 \beta V - \rho_0 f \nabla_h \cdot \mathbf{U} &= -\mathbf{k} \times \nabla \cdot (\tau_a - \tau_b) \end{aligned}$$

with $\beta = df/dy$ and $\mathbf{k} \times \nabla = (-\partial/\partial y, \partial/\partial x, 0)$

- ▶ since $\nabla_h \cdot \mathbf{U} = 0$ introduce volume transport streamfunction, with

$$U = -\frac{\partial\psi}{\partial y}, \quad V = \frac{\partial\psi}{\partial x} \quad \rightarrow \quad \mathbf{U} = \mathbf{k} \times \nabla\psi$$

transport \mathbf{U} is parallel to contour lines of ψ

- ▶ ψ determines transport perpendicular to or "across" section $A \rightarrow B$

$$\int_A^B \mathbf{U} \cdot d\mathbf{s} = \int_A^B \mathbf{k} \times \nabla\psi \cdot d\mathbf{s} = \int_A^B \nabla_h\psi \cdot d\boldsymbol{\ell} = \psi(B) - \psi(A)$$

where $d\mathbf{s}$ is a line element perpendicular to section $A \rightarrow B$

and $d\boldsymbol{\ell}$ is line element along section $A \rightarrow B$

- ▶ Sverdrup relation becomes (for $\tau_b = 0$)

$$\rho_0\beta V = \rho_0\beta \frac{\partial\psi}{\partial x} = \mathbf{k} \times \nabla \cdot \boldsymbol{\tau}_a$$

- ▶ integration from x to eastern boundary ($x = x_E$) where $\psi(x_E) = 0$

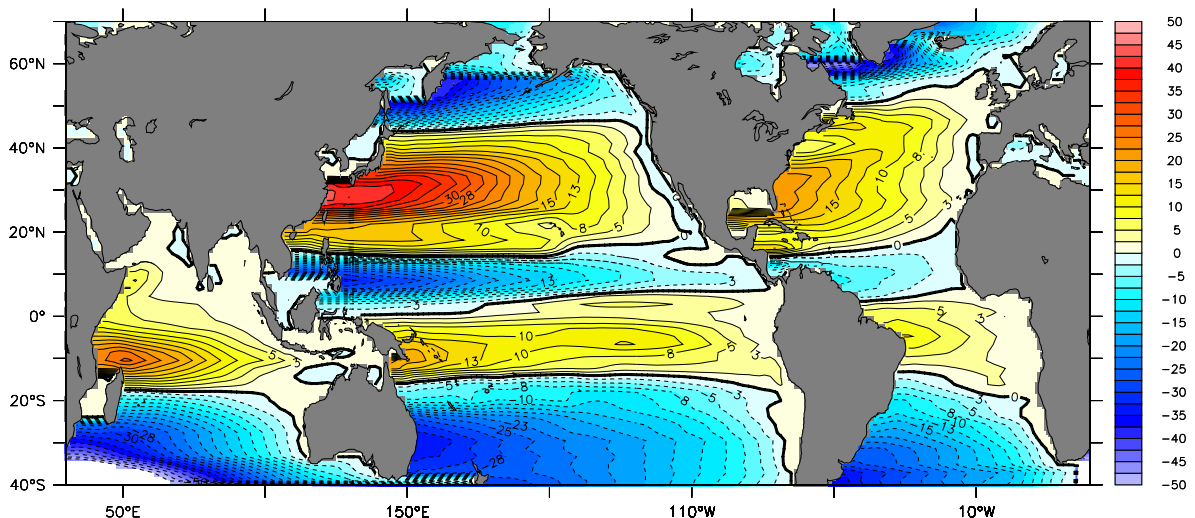
$$\psi(x, y) = -\frac{1}{\rho_0\beta} \int_x^{x_e} \mathbf{k} \times \nabla \cdot \boldsymbol{\tau}_a dx$$

→ Sverdrup streamfunction

- ▶ Sverdrup streamfunction

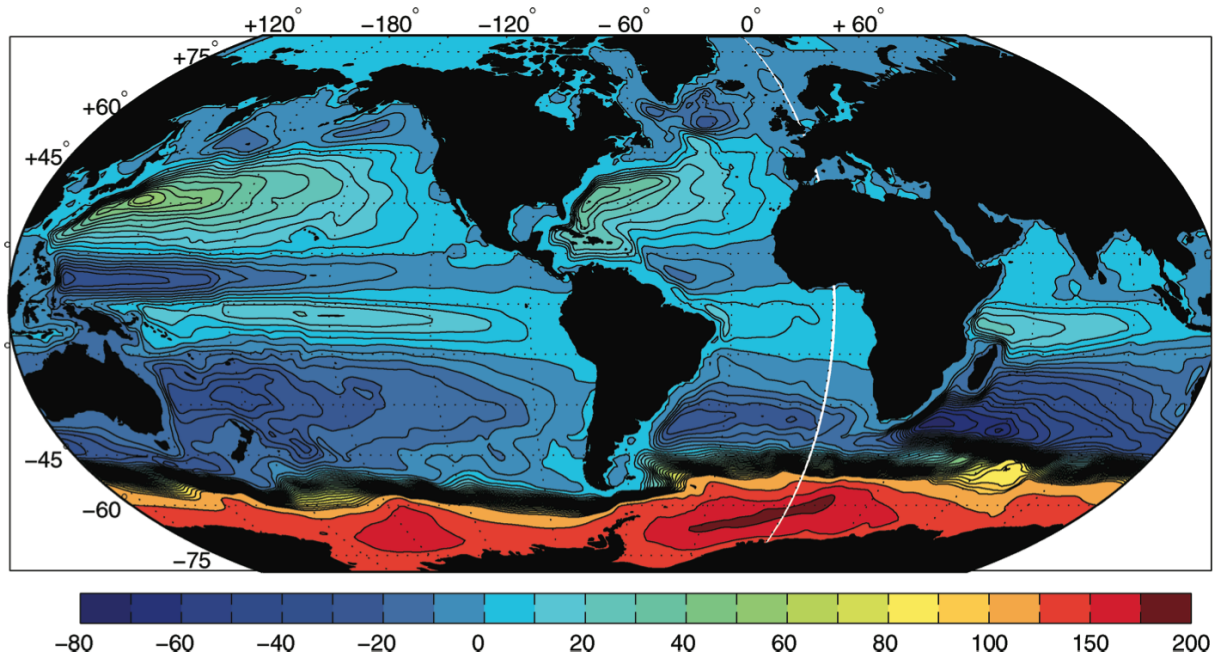
$$\psi = -\frac{1}{\rho_0\beta} \int_x^{x_e} \mathbf{k} \times \nabla \cdot \boldsymbol{\tau}^a dx$$

from realistic wind stress in $10^6 \text{ m}^3/\text{s} \equiv 1 \text{ Sv}$

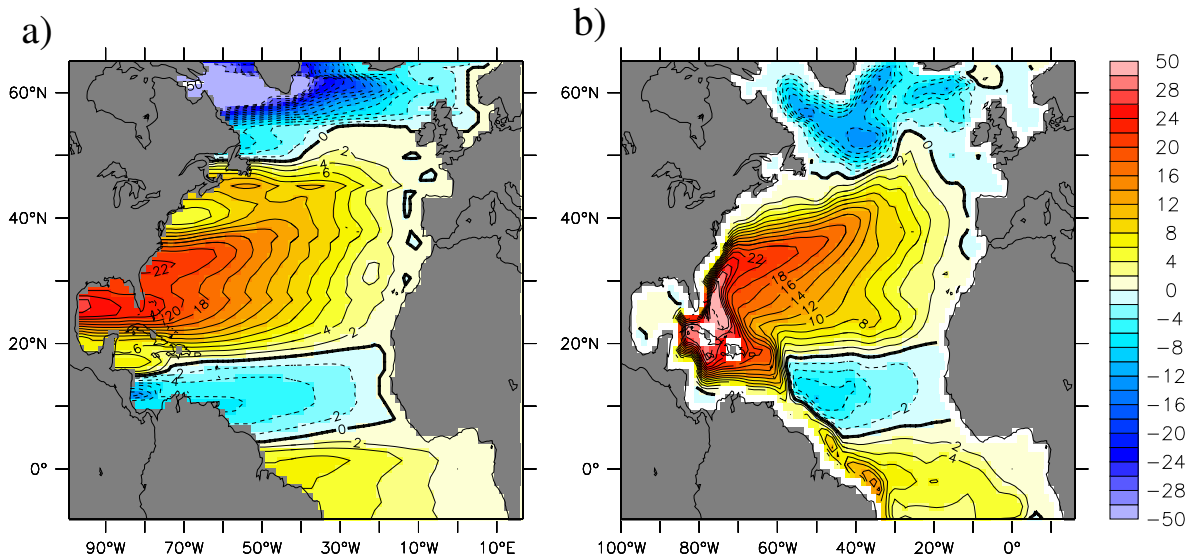


- ▶ $\psi(x_E) = 0$ along east eastern boundary but not at western boundary
→ western boundary current not included
- ▶ but in the interior ψ is rather realistic

- ▶ ψ in a global state estimate in $10^6 \text{ m}^3/\text{s} \equiv 1 \text{ Sv}$



- ▶ Streamfunction ψ in $\text{Sv} = 10^6 \text{ m}^3/\text{s}$ from simple Sverdrup relation
- ▶ Streamfunction ψ for a realistic model of the Atlantic Ocean



- ▶ simple Sverdrup relation works surprisingly well

- ▶ vertically integrated momentum equation

$$-\rho_0 f V = -\frac{\partial}{\partial x} \int_{-h}^0 p dz + \tau_a^x \equiv -\frac{\partial P}{\partial x} + \tau_a^x$$

$$\rho_0 f U = -\frac{\partial}{\partial y} \int_{-h}^0 p dz + \tau_a^y \equiv -\frac{\partial P}{\partial y} + \tau_a^y$$

- ▶ split in Ekman transport \mathbf{U}_E und geostrophic transport \mathbf{U}_G

$$-\rho_0 f V \equiv -\rho_0 f (V_G + V_E) = -\frac{\partial P}{\partial x} + \tau_a^x$$

$$\rho_0 f U \equiv \rho_0 f (U_G + U_E) = -\frac{\partial P}{\partial y} + \tau_a^y$$

- ▶ with Ekman transport

$$-\rho_0 f V_E = \tau_a^x, \quad \rho_0 f U_E = \tau_a^y \rightarrow \rho_0 f \mathbf{k} \times \mathbf{U}_E = \boldsymbol{\tau}_a \rightarrow \rho_0 f \mathbf{U}_E = -\mathbf{k} \times \boldsymbol{\tau}_a$$

- ▶ and with geostrophic transport

$$-\rho_0 f V_G = -\frac{\partial P}{\partial x}, \quad \rho_0 f U_G = -\frac{\partial P}{\partial y} \rightarrow \rho_0 f \mathbf{U}_G = \mathbf{k} \times \nabla_h P$$

- ▶ Ekman transport + geostr. transport = Sverdrup transport

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- ▶ with Ekman transport

$$-\rho_0 f V_E = \tau_a^x, \quad \rho_0 f U_E = \tau_a^y, \quad \rho_0 f \mathbf{U}_E = -\mathbf{k} \times \boldsymbol{\tau}_a$$

- ▶ and geostrophic transport

$$-\rho_0 f V_G = -\frac{\partial P}{\partial x}, \quad \rho_0 f U_G = -\frac{\partial P}{\partial y}, \quad \rho_0 f \mathbf{U}_G = \mathbf{k} \times \nabla_h P$$

- ▶ both transports are divergent

$$\nabla_h \cdot \mathbf{U}_E = -\nabla_h \cdot \mathbf{k} \times \frac{\boldsymbol{\tau}_a}{\rho_0 f} = \mathbf{k} \times \nabla_h \cdot \frac{\boldsymbol{\tau}_a}{\rho_0 f} = w_E$$

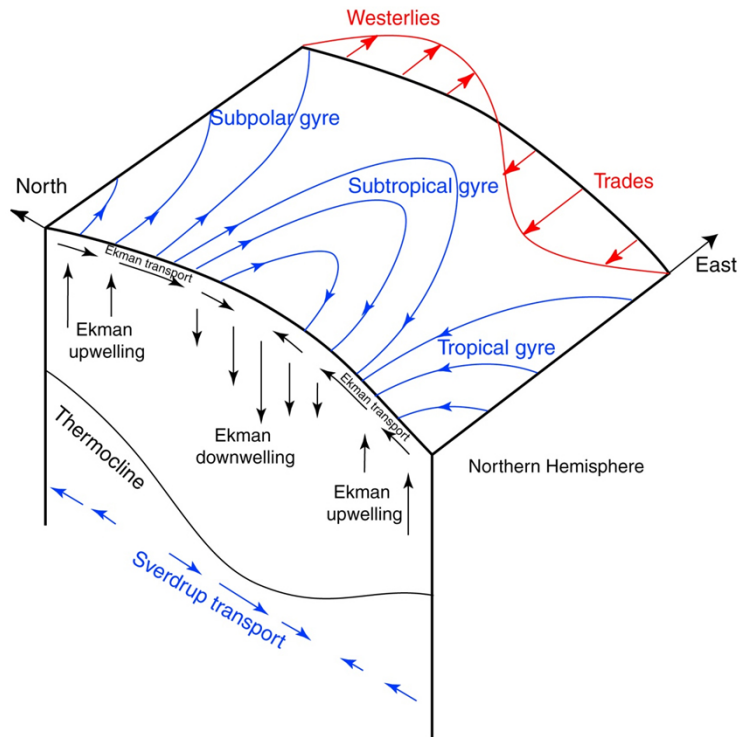
$$\begin{aligned} \nabla_h \cdot \mathbf{U}_G &= -\frac{\partial}{\partial x} \left(\frac{\partial P}{\partial y} \frac{1}{\rho_0 f} \right) + \frac{\partial}{\partial y} \left(\frac{\partial P}{\partial x} \frac{1}{\rho_0 f} \right) = \frac{\partial P}{\partial x} \frac{\partial}{\partial y} \left(\frac{1}{\rho_0 f} \right) \\ &= -\frac{1}{\rho_0 f^2} \frac{df}{dy} \frac{\partial P}{\partial x} = -\frac{\beta}{\rho_0 f^2} \frac{\partial P}{\partial x} = -\frac{\beta}{f} V_G \end{aligned}$$

- ▶ but the total transport $\mathbf{U} = \mathbf{U}_E + \mathbf{U}_G$ is non-divergent

$$\nabla_h \cdot \mathbf{U} = 0 \rightarrow w_E^{top} = \frac{\beta}{f} V_G$$

Ekman pumping generates southward geostr. transport (for $f > 0$)

- ▶ Ekman pumping generates southward geostr. transport (for $f > 0$)



from Talley et al 2011

- ▶ Sverdrup relation follows from potential vorticity conservation
- ▶ potential vorticity equation for a single layer

$$\frac{Dq}{Dt} = 0, \quad q = \frac{\zeta + f}{h} \quad \text{or} \quad q \approx \zeta - \frac{f_0}{H}h + f$$

q is conserved for fluid parcels in single layer

- ▶ w_E lead to vortex stretching and meridional motion

